

LTC2232/LTC2233

ABSOLUTE MAXIMUM RATINGS

$OV_{DD} = V_{DD}$ (Notes 1, 2)

Supply Voltage (V_{DD})	4V
Digital Output Ground Voltage (OGND)	–0.3V to 1V
Analog Input Voltage (Note 3)	–0.3V to ($V_{DD} + 0.3V$)
Digital Input Voltage	–0.3V to ($V_{DD} + 0.3V$)
Digital Output Voltage	–0.3V to ($OV_{DD} + 0.3V$)
Power Dissipation	1500mW
Operating Temperature Range	
LTC2232C, LTC2233C	0°C to 70°C
LTC2232I, LTC2233I	–40°C to 85°C
Storage Temperature Range	–65°C to 125°C

PACKAGE/ORDER INFORMATION

TOP VIEW UK PACKAGE 48-LEAD (7mm × 7mm) PLASTIC QFN EXPOSED PAD IS GND (PIN 49), MUST BE SOLDERED TO PCB $T_{JMAX} = 125^{\circ}C$, $\theta_{JA} = 29^{\circ}C/W$	
ORDER PART NUMBER	UK PART MARKING*
LTC2232CUK	LTC2232UK
LTC2232IUK	LTC2232UK
LTC2233CUK	LTC2233UK
LTC2233IUK	LTC2233UK
Order Options Tape and Reel: Add #TR Lead Free: Add #PBF Lead Free Tape and Reel: Add #TRPBF Lead Free Part Marking: http://www.linear.com/leadfree/	

*The temperature grade is identified by a label on the shipping container.
Consult LTC Marketing for parts specified with wider operating temperature ranges.

CONVERTER CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$. (Note 4)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
Resolution (No Missing Codes)		● 10			Bits
Integral Linearity Error (Note 5)	Differential Analog Input	● –0.8	±0.15	0.8	LSB
Differential Linearity Error	Differential Analog Input	● –0.6	±0.1	0.6	LSB
Integral Linearity Error (Note 5)	Single-Ended Analog Input		±0.5		LSB
Differential Linearity Error	Single-Ended Analog Input		±0.1		LSB
Offset Error (Note 6)		● –37	±5	37	mV
Gain Error	External Reference	● –2.5	±0.5	2.5	%FS
Offset Drift			±10		μV/C
Full-Scale Drift	Internal Reference External Reference		±30 ±15		ppm/C ppm/C
Transition Noise	SENSE = 1V		0.12		LSB _{RMS}

223231fa

ANALOG INPUT

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$. (Note 4)

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
V_{IN}	Analog Input Range ($A_{IN}^+ - A_{IN}^-$)	$3.1V < V_{DD} < 3.5V$	●	± 0.5 to ± 1			V
$V_{IN, CM}$	Analog Input Common Mode ($A_{IN}^+ + A_{IN}^-$)/2	Differential Input	●	1	1.6	1.9	V
		Single Ended Input (Note 7)	●	0.5	1.6	2.1	V
I_{IN}	Analog Input Leakage Current	$0 < A_{IN}^+, A_{IN}^- < V_{DD}$	●	-1		1	μA
I_{SENSE}	SENSE Input Leakage	$0V < SENSE < 1V$	●	-1		1	μA
I_{MODE}	MODE Pin Pull-Down Current to GND				10		μA
	Full Power Bandwidth	Figure 8 Test Circuit			775		MHz
t_{AP}	Sample and Hold Acquisition Delay Time				0		ns
t_{JITTER}	Sample and Hold Acquisition Delay Time Jitter				0.15		ps _{RMS}
CMRR	Analog Input Common Mode Rejection Ratio				80		dB

DYNAMIC ACCURACY

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$. $A_{IN} = -1\text{dBFS}$. (Note 4)

SYMBOL	PARAMETER	CONDITIONS		LTC2232			LTC2233			UNITS
				MIN	TYP	MAX	MIN	TYP	MAX	
SNR	Signal-to-Noise Ratio	30MHz Input (1V Range)			59.8			59.9		dB
		30MHz Input (2V Range)	●	60.4	61.3		60.4	61.3		dB
		70MHz Input (1V Range)			59.8			59.8		dB
		70MHz Input (2V Range)			61.2			61.3		dB
		140MHz Input (1V Range)			59.8			59.8		dB
		140MHz Input (2V Range)			61.2			61.2		dB
		250MHz Input (1V Range)			59.6			59.7		dB
		250MHz Input (2V Range)			61.1			61.2		dB
SFDR	Spurious Free Dynamic Range	30MHz Input (1V Range)			80			80		dB
		30MHz Input (2V Range)	●	69	78		69	78		dB
		70MHz Input (1V Range)			80			80		dB
		70MHz Input (2V Range)			78			78		dB
		140MHz Input (1V Range)			78			78		dB
		140MHz Input (2V Range)			78			78		dB
		250MHz Input (1V Range)			71			73		dB
		250MHz Input (2V Range)			70			72		dB
SFDR	Spurious Free Dynamic Range 4th Harmonic or Higher	30MHz Input (1V Range)			86			86		dB
		30MHz Input (2V Range)			86			86		dB
		70MHz Input (1V Range)			86			86		dB
		70MHz Input (2V Range)			86			86		dB
		140MHz Input (1V Range)			86			86		dB
		140MHz Input (2V Range)			86			86		dB
		250MHz Input (1V Range)			86			86		dB
		250MHz Input (2V Range)			86			86		dB
S/(N+D)	Signal-to-Noise Plus Distortion Ratio	30MHz Input (1V Range)			59.8			59.9		dB
		30MHz Input (2V Range)	●	60.2	61.3		60.2	61.3		dB
		70MHz Input (1V Range)			59.8			59.8		dB
		70MHz Input (2V Range)			61.2			61.2		dB
IMD	Intermodulation Distortion	$f_{IN1} = 138\text{MHz}$, $f_{IN2} = 140\text{MHz}$			81			81		dBc

INTERNAL REFERENCE CHARACTERISTICS (Note 4)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
V_{CM} Output Voltage	$I_{OUT} = 0$	1.570	1.600	1.630	V
V_{CM} Output Tempco			±25		ppm/°C
V_{CM} Line Regulation	$3.1V < V_{DD} < 3.5V$		3		mV/V
V_{CM} Output Resistance	$-1mA < I_{OUT} < 1mA$		4		Ω

DIGITAL INPUTS AND DIGITAL OUTPUTS The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$. (Note 4)

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
ENCODE INPUTS (ENC⁺, ENC⁻)						
V_{ID}	Differential Input Voltage		●	0.2		V
V_{ICM}	Common Mode Input Voltage	Internally Set Externally Set (Note 7)	●	1.1	1.6 1.6 2.5	V V
R_{IN}	Input Resistance			6		k Ω
C_{IN}	Input Capacitance	(Note 7)		3		pF
LOGIC INPUTS ($\overline{OE}$, SHDN)						
V_{IH}	High Level Input Voltage	$V_{DD} = 3.3V$	●	2		V
V_{IL}	Low Level Input Voltage	$V_{DD} = 3.3V$	●		0.8	V
I_{IN}	Input Current	$V_{IN} = 0V$ to V_{DD}	●	-10	10	μA
C_{IN}	Input Capacitance	(Note 7)		3		pF
LOGIC OUTPUTS						
$0V_{DD} = 3.3V$						
C_{OZ}	Hi-Z Output Capacitance	$\overline{OE} = \text{High}$ (Note 7)		3		pF
I_{SOURCE}	Output Source Current	$V_{OUT} = 0V$		50		mA
I_{SINK}	Output Sink Current	$V_{OUT} = 3.3V$		50		mA
V_{OH}	High Level Output Voltage	$I_O = -10\mu\text{A}$ $I_O = -200\mu\text{A}$	●	3.1	3.295 3.29	V V
V_{OL}	Low Level Output Voltage	$I_O = 10\mu\text{A}$ $I_O = 1.6mA$	●		0.005 0.09 0.4	V V
$0V_{DD} = 2.5V$						
V_{OH}	High Level Output Voltage	$I_O = -200\mu\text{A}$		2.49		V
V_{OL}	Low Level Output Voltage	$I_O = 1.6mA$		0.09		V
$0V_{DD} = 1.8V$						
V_{OH}	High Level Output Voltage	$I_O = -200\mu\text{A}$		1.79		V
V_{OL}	Low Level Output Voltage	$I_O = 1.6mA$		0.09		V

POWER REQUIREMENTS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$. (Note 9)

SYMBOL	PARAMETER	CONDITIONS		LTC2232			LTC2233			UNITS
				MIN	TYP	MAX	MIN	TYP	MAX	
V_{DD}	Analog Supply Voltage		●	3.1	3.3	3.5	3.1	3.3	3.5	V
OV_{DD}	Output Supply Voltage		●	0.5	3.3	3.6	0.5	3.3	3.6	V
I_{VDD}	Analog Supply Current		●		144	162		111	123	mA
P_{DISS}	Power Dissipation		●		475	535		366	406	mW
P_{SHDN}	Shutdown Power	SHDN = H, $\overline{OE}$ = H, No CLK			2			2		mW
P_{NAP}	Nap Mode Power	SHDN = H, $\overline{OE}$ = L, No CLK			35			35		mW

TIMING CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$. (Note 4)

SYMBOL	PARAMETER	CONDITIONS		LTC2232			LTC2233			UNITS
				MIN	TYP	MAX	MIN	TYP	MAX	
f_S	Sampling Frequency		●	1		105	1		80	MHz
t_L	ENC Low Time (Note 8)	Duty Cycle Stabilizer Off	●	4.5	4.76	500	5.9	6.25	500	ns
		Duty Cycle Stabilizer On	●	3	4.76	500	3	6.25	500	ns
t_H	ENC High Time (Note 8)	Duty Cycle Stabilizer Off	●	4.5	4.76	500	5.9	6.25	500	ns
		Duty Cycle Stabilizer On	●	3	4.76	500	3	6.25	500	ns
t_{AP}	Sample-and-Hold Aperture Delay				0			0		ns
t_D	ENC to DATA Delay	(Note 7)	●	1.3	2.1	4	1.3	2.1	4	ns
t_C	ENC to CLOCKOUT Delay	(Note 7)	●	1.3	2.1	4	1.3	2.1	4	ns
	DATA to CLOCKOUT Skew	$(t_C - t_D)$ (Note 7)	●	-0.6	0	0.6	-0.6	0	0.6	ns
t_{OE}	Output Enable Delay	(Note 7)	●		5	10		5	10	ns
Pipeline Latency					5			5		Cycles

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: All voltage values are with respect to ground with GND and OGNND wired together (unless otherwise noted).

Note 3: When these pin voltages are taken below GND or above V_{DD} , they will be clamped by internal diodes. This product can handle input currents of greater than 100mA below GND or above V_{DD} without latchup.

Note 4: $V_{DD} = 3.3\text{V}$, $f_{\text{SAMPLE}} = 105\text{MHz}$ (LTC2232) or 80MHz (LTC2233), differential ENC⁺/ENC⁻ = 2V_{P-P} sine wave, input range = 2V_{P-P} with differential drive, unless otherwise noted.

Note 5: Integral nonlinearity is defined as the deviation of a code from a straight line passing through the actual endpoints of the transfer curve. The deviation is measured from the center of the quantization band.

Note 6: Offset error is the offset voltage measured from -0.5 LSB when the output code flickers between 00 0000 0000 and 11 1111 1111 in 2's complement output mode.

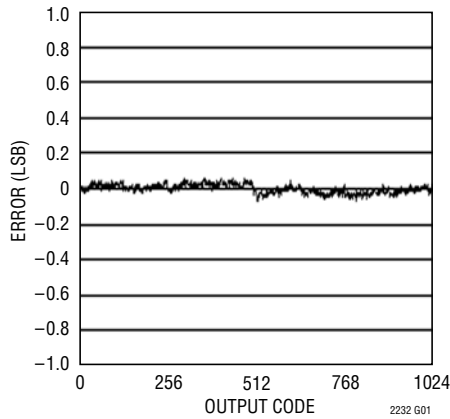
Note 7: Guaranteed by design, not subject to test.

Note 8: Recommended operating conditions.

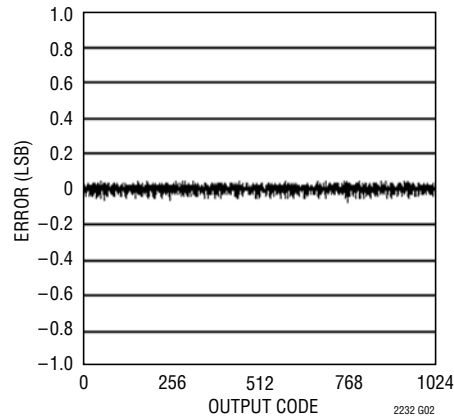
Note 9: $V_{DD} = 3.3\text{V}$, $f_{\text{SAMPLE}} = 105\text{MHz}$ (LTC2232) or 80MHz (LTC2233), differential ENC⁺/ENC⁻ = 2V_{P-P} sine wave, input range = 1V_{P-P} with differential drive.

TYPICAL PERFORMANCE CHARACTERISTICS

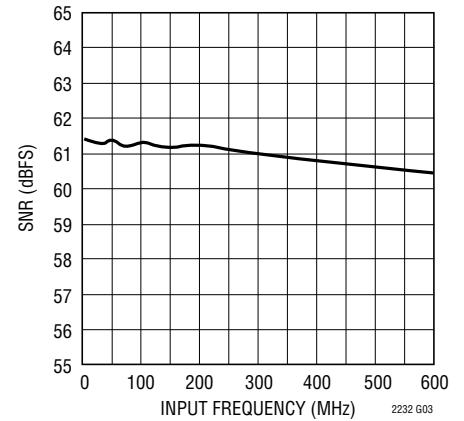
LTC2232: INL, 2V Range



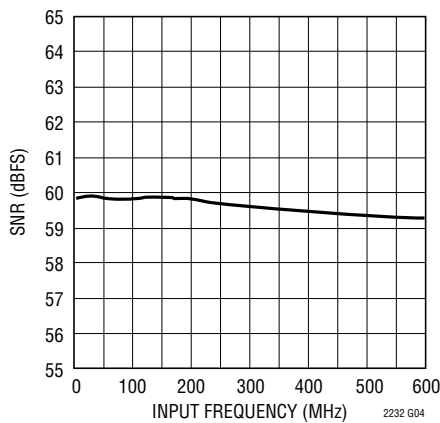
LTC2232: DNL, 2V Range



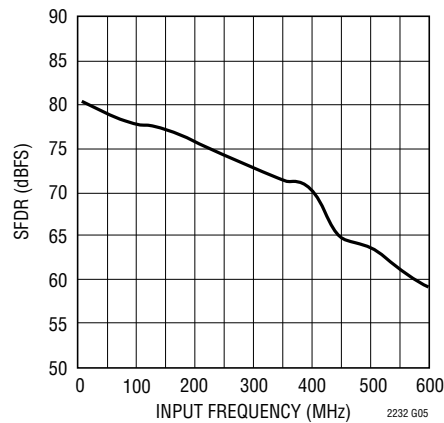
LTC2232: SNR vs Input Frequency, -1dB, 2V Range



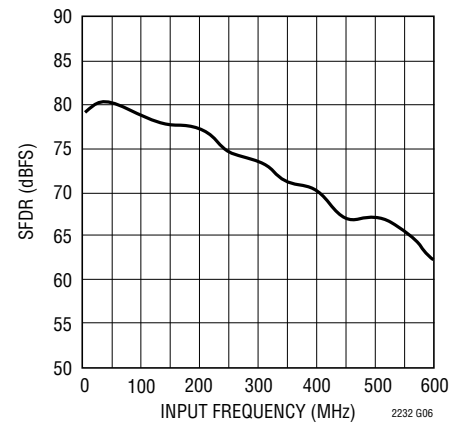
LTC2232: SNR vs Input Frequency, -1dB, 1V Range



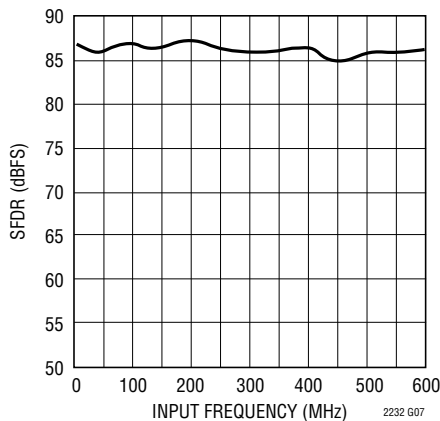
LTC2232: SFDR (HD2 and HD3) vs Input Frequency, -1dB, 2V Range



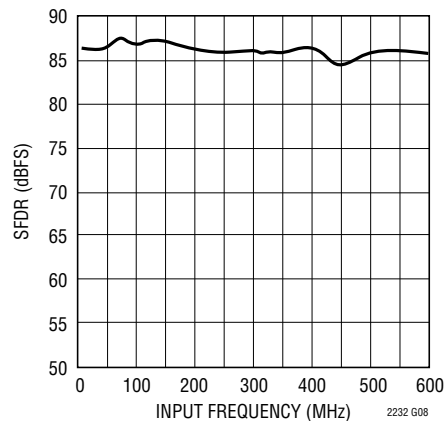
LTC2232: SFDR (HD2 and HD3) vs Input Frequency, -1dB, 1V Range



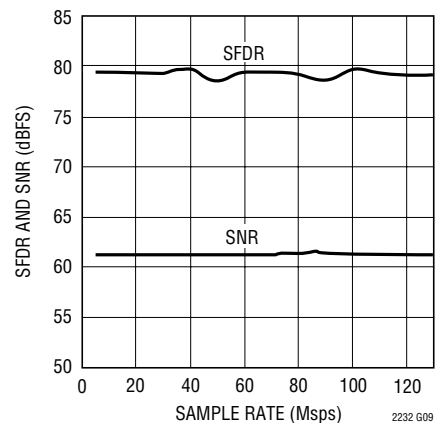
LTC2232: SFDR (HD4+) vs Input Frequency, -1dB, 2V Range



LTC2232: SFDR (HD4+) vs Input Frequency, -1dB, 1V Range

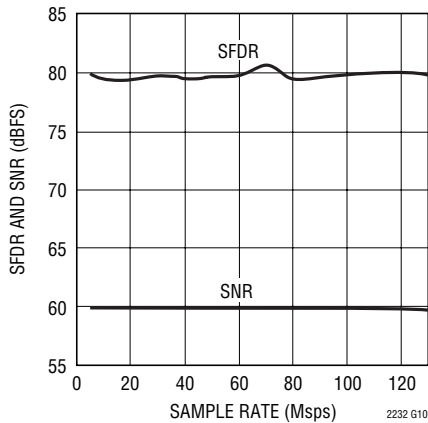


LTC2232: SFDR and SNR vs Sample Rate, 2V Range, $f_{IN} = 30\text{MHz}$, -1dB

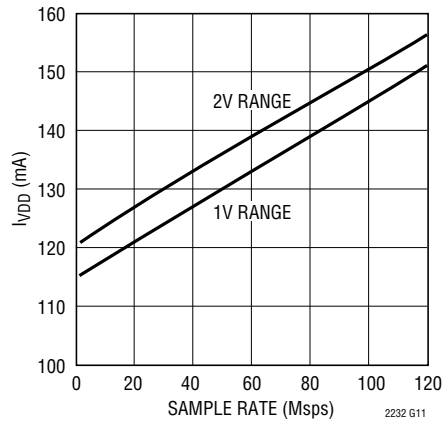


TYPICAL PERFORMANCE CHARACTERISTICS

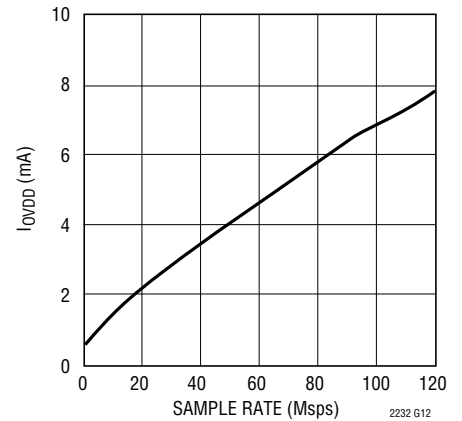
LTC2232: SFDR and SNR vs Sample Rate, 1V Range, $f_{IN} = 30\text{MHz}$, -1dB



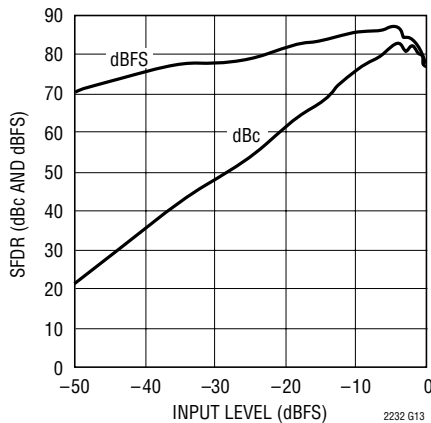
LTC2232: I_{VDD} vs Sample Rate, 5MHz Sine Wave Input, -1dB



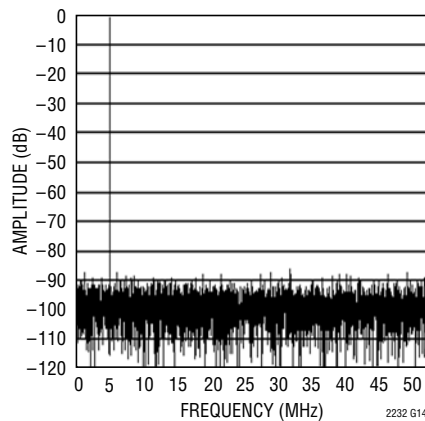
LTC2232: I_{OVD} vs Sample Rate, 5MHz Sine Wave Input, -1dB , $0V_{DD} = 1.8\text{V}$



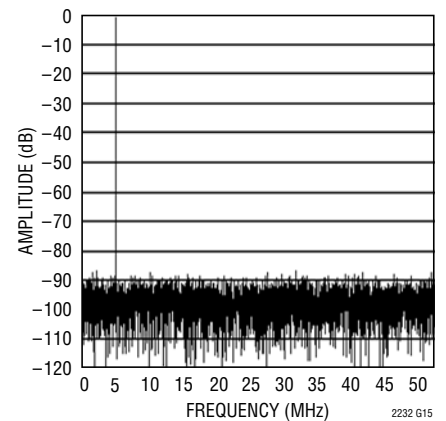
LTC2232: SFDR vs Input Level, $f_{IN} = 70\text{MHz}$, 2V Range



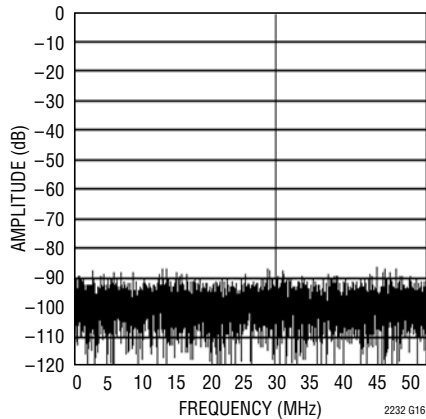
LTC2232: 8192 Point FFT, $f_{IN} = 5\text{MHz}$, -1dB , 2V Range



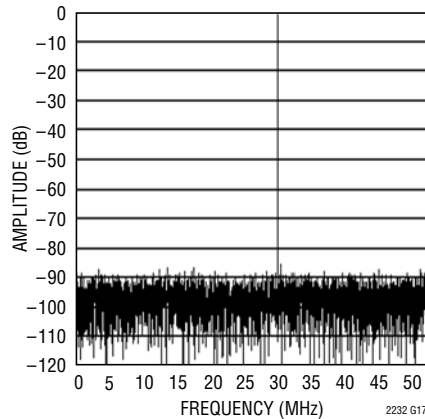
LTC2232: 8192 Point FFT, $f_{IN} = 5\text{MHz}$, -1dB , 1V Range



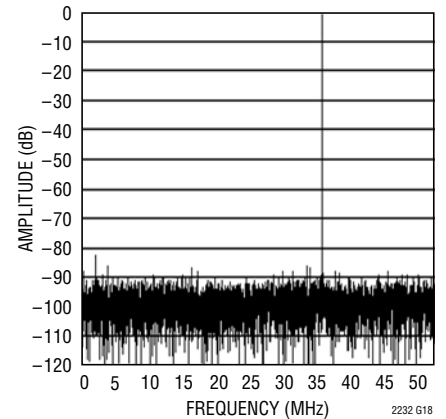
LTC2232: 8192 Point FFT, $f_{IN} = 30\text{MHz}$, -1dB , 2V Range



LTC2232: 8192 Point FFT, $f_{IN} = 30\text{MHz}$, -1dB , 1V Range

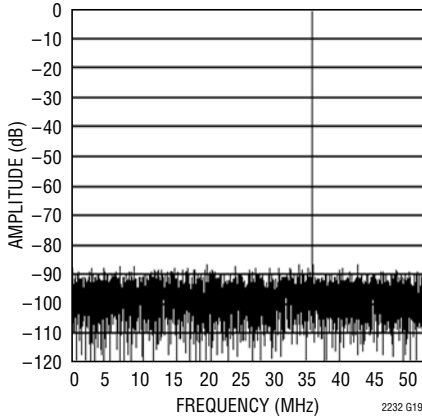


LTC2232: 8192 Point FFT, $f_{IN} = 70\text{MHz}$, -1dB , 2V Range

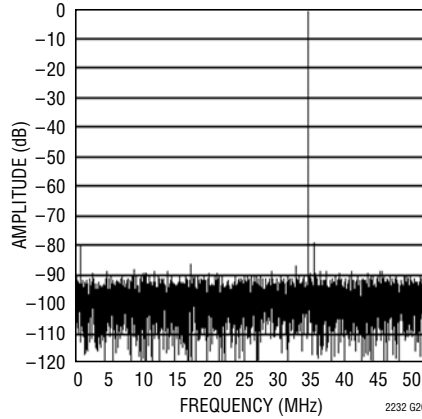


TYPICAL PERFORMANCE CHARACTERISTICS

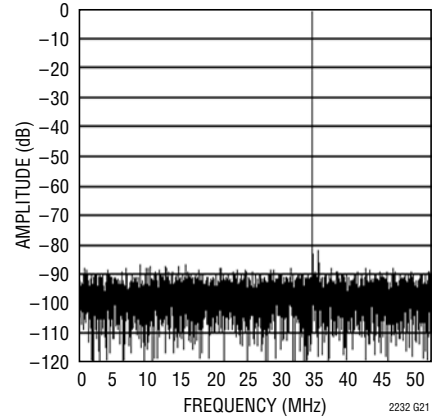
LTC2232: 8192 Point FFT,
 $f_{IN} = 70\text{MHz}$, -1dB, 1V Range



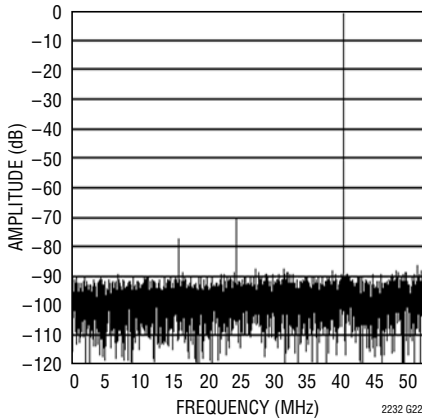
LTC2232: 8192 Point FFT,
 $f_{IN} = 140\text{MHz}$, -1dB, 2V Range



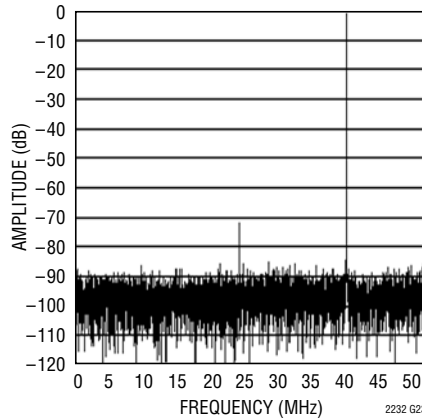
LTC2232: 8192 Point FFT,
 $f_{IN} = 140\text{MHz}$, -1dB, 1V Range



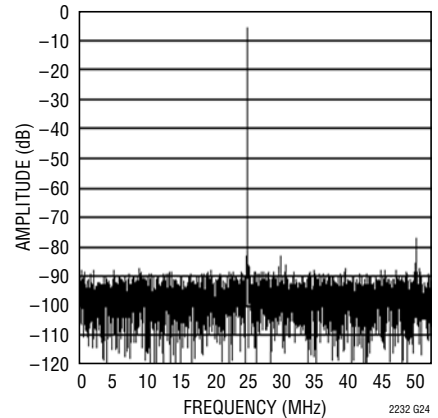
LTC2232: 8192 Point FFT,
 $f_{IN} = 250\text{MHz}$, -1dB, 2V Range



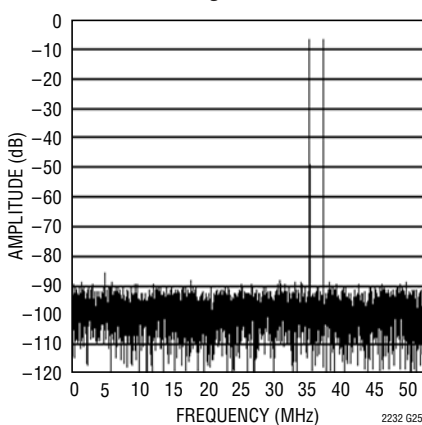
LTC2232: 8192 Point FFT,
 $f_{IN} = 250\text{MHz}$, -1dB, 1V Range



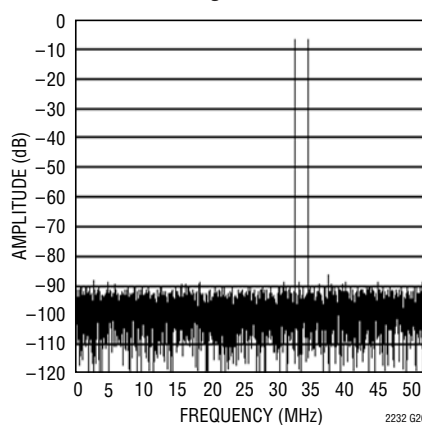
LTC2232: 8192 Point FFT,
 $f_{IN} = 500\text{MHz}$, -6dB, 1V Range



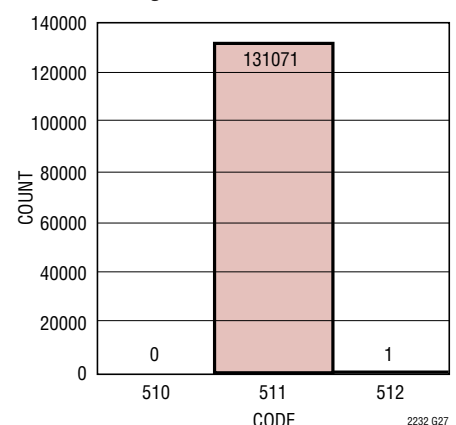
LTC2232: 8192 Point 2-Tone FFT,
 $f_{IN} = 68\text{MHz}$ and 70MHz , -7dB
Each, 2V Range



LTC2232: 8192 Point 2-Tone FFT,
 $f_{IN} = 138\text{MHz}$ and 140MHz , -7dB
Each, 1V Range

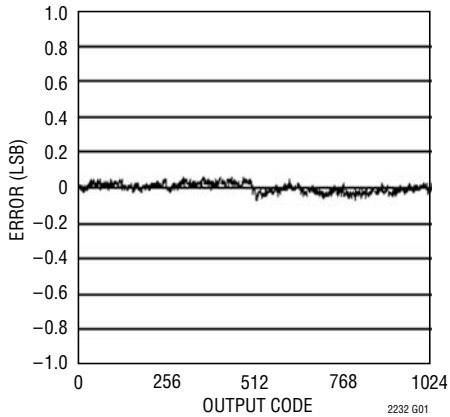


LTC2232: Shorted Input Noise
Histogram

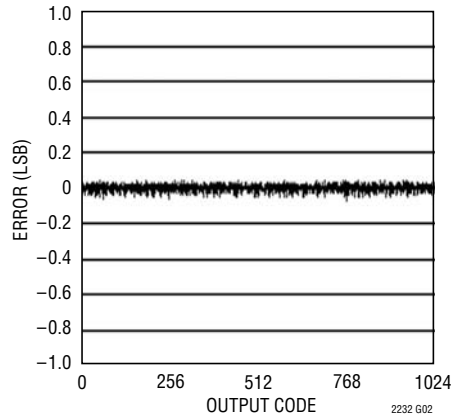


TYPICAL PERFORMANCE CHARACTERISTICS

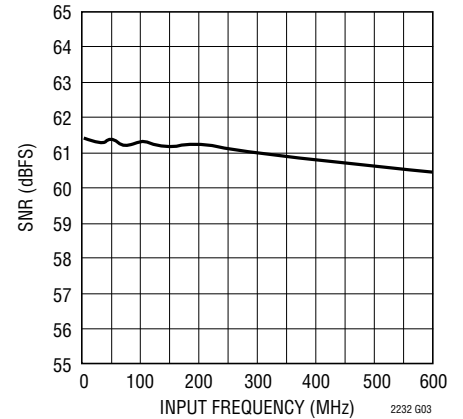
LTC2233: INL, 2V Range



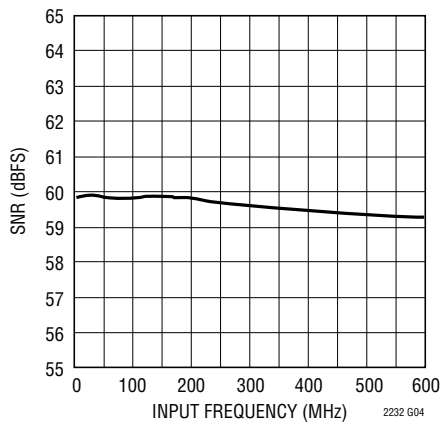
LTC2233: DNL, 2V Range



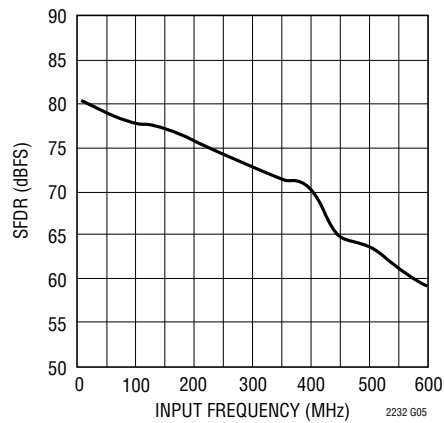
LTC2233: SNR vs Input Frequency, -1dB, 2V Range



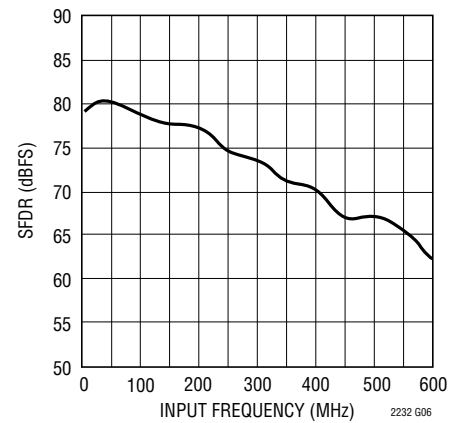
LTC2233: SNR vs Input Frequency, -1dB, 1V Range



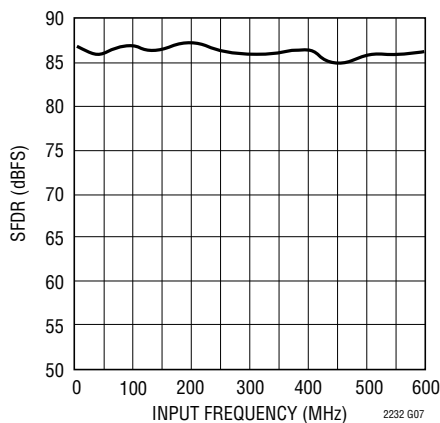
LTC2233: SFDR (HD2 and HD3) vs Input Frequency, -1dB, 2V Range



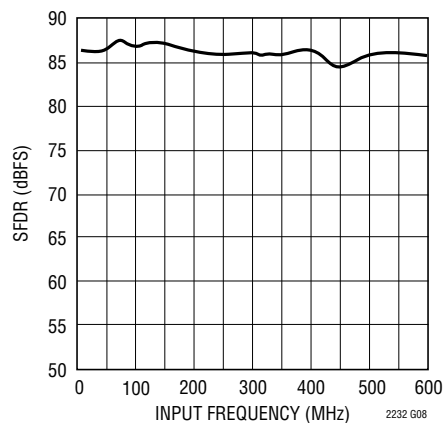
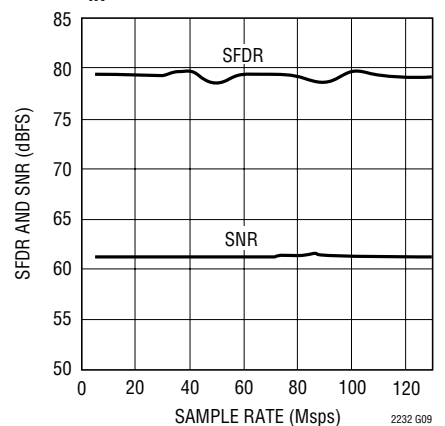
LTC2233: SFDR (HD2 and HD3) vs Input Frequency, -1dB, 1V Range



LTC2233: SFDR (HD4+) vs Input Frequency, -1dB, 2V Range

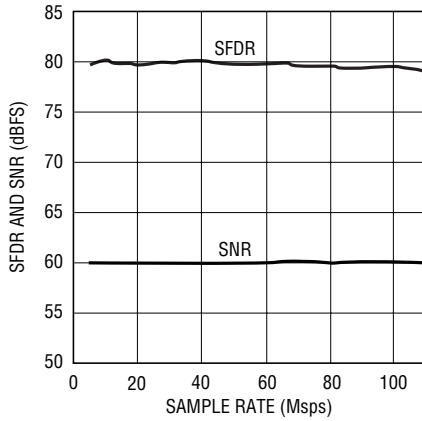


LTC2233: SFDR (HD4+) vs Input Frequency, -1dB, 1V Range

LTC2233: SFDR and SNR vs Sample Rate, 2V Range, $f_{IN} = 30\text{MHz}$, -1dB

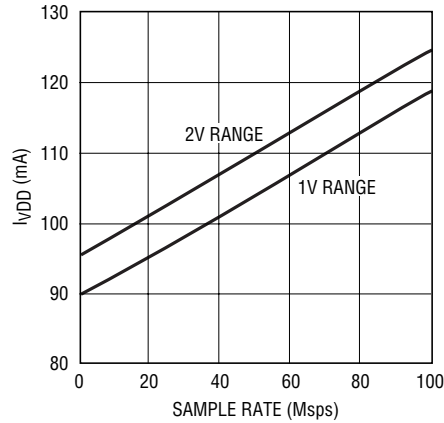
TYPICAL PERFORMANCE CHARACTERISTICS

LTC2233: SFDR and SNR vs Sample Rate, 1V Range, $f_{IN} = 30\text{MHz}$, -1dB



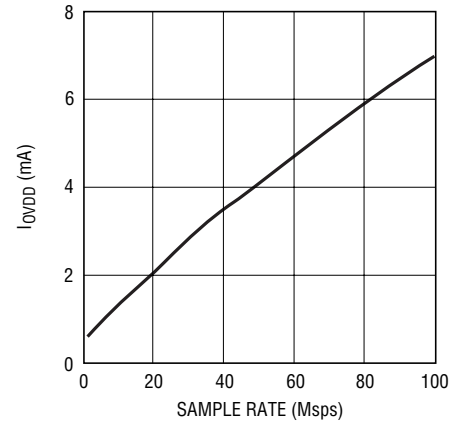
2233 G10

LTC2233: I_{VDD} vs Sample Rate, 5MHz Sine Wave Input, -1dB



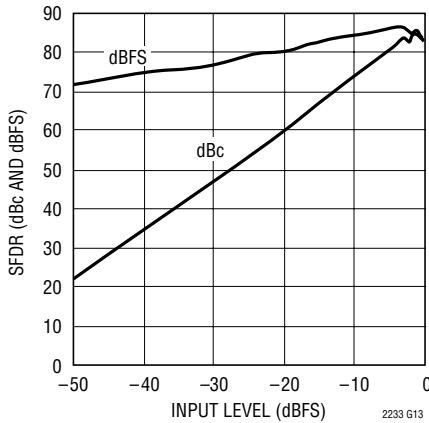
2233 G11

LTC2233: I_{OVPD} vs Sample Rate, 5MHz Sine Wave Input, -1dB , $0V_{DD} = 1.8V$



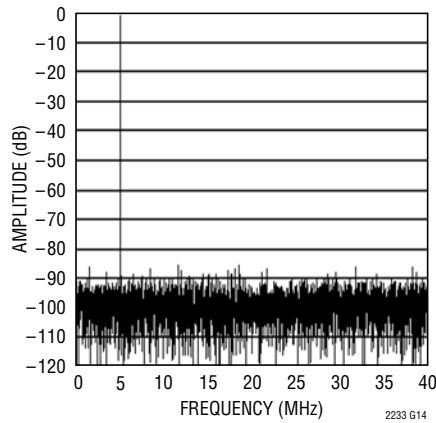
2233 G12

LTC2233: SFDR vs Input Level, $f_{IN} = 70\text{MHz}$, 2V Range



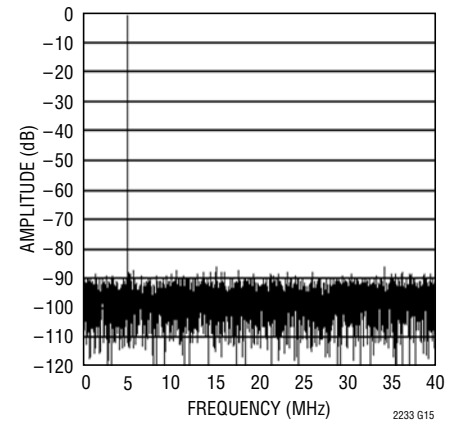
2233 G13

LTC2233: 8192 Point FFT, $f_{IN} = 5\text{MHz}$, -1dB , 2V Range



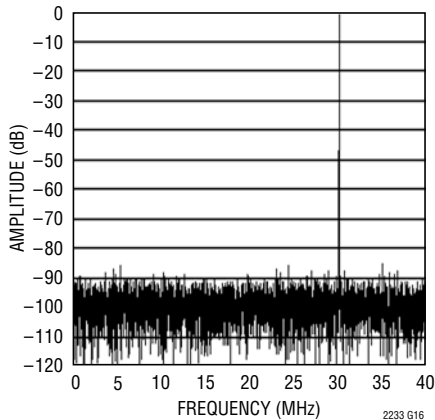
2233 G14

LTC2233: 8192 Point FFT, $f_{IN} = 5\text{MHz}$, -1dB , 1V Range



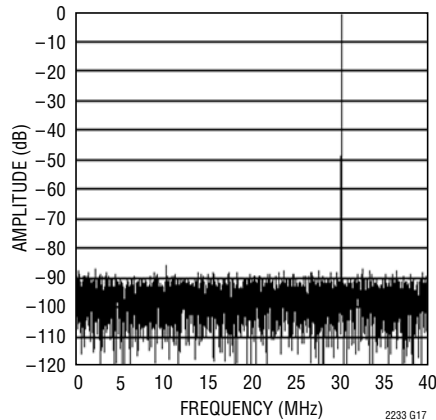
2233 G15

LTC2233: 8192 Point FFT, $f_{IN} = 30\text{MHz}$, -1dB , 2V Range



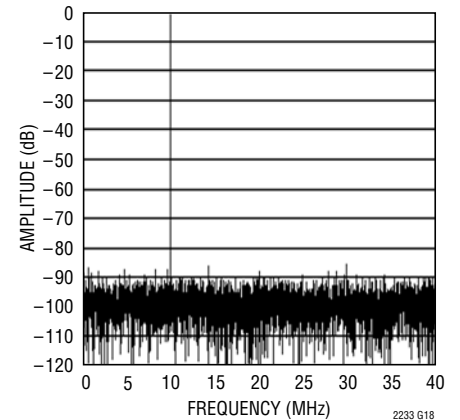
2233 G16

LTC2233: 8192 Point FFT, $f_{IN} = 30\text{MHz}$, -1dB , 1V Range



2233 G17

LTC2233: 8192 Point FFT, $f_{IN} = 70\text{MHz}$, -1dB , 2V Range

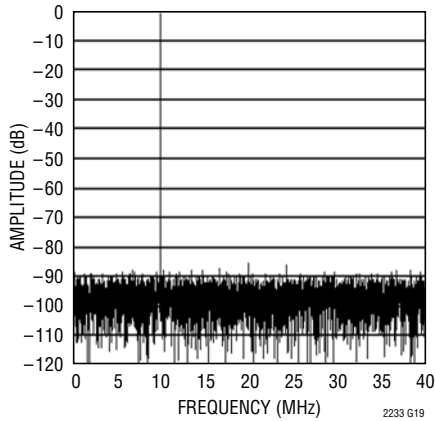


2233 G18

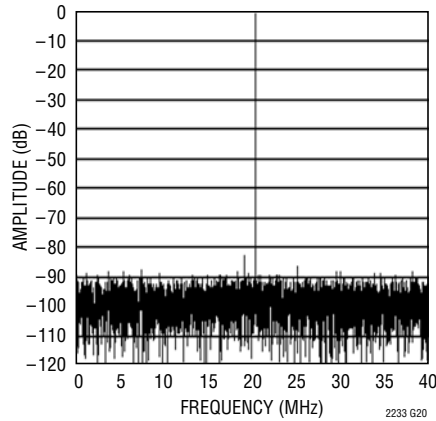
22323fa

TYPICAL PERFORMANCE CHARACTERISTICS

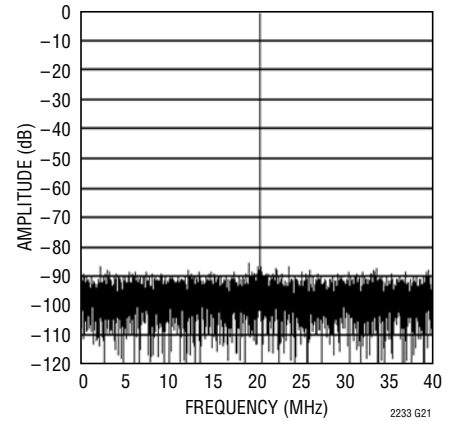
LTC2233: 8192 Point FFT,
 $f_{IN} = 70\text{MHz}$, -1dB, 1V Range



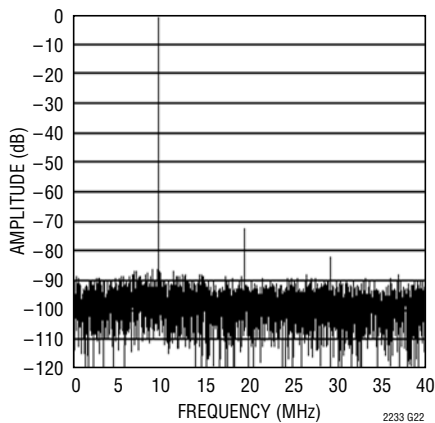
LTC2233: 8192 Point FFT,
 $f_{IN} = 140\text{MHz}$, -1dB, 2V Range



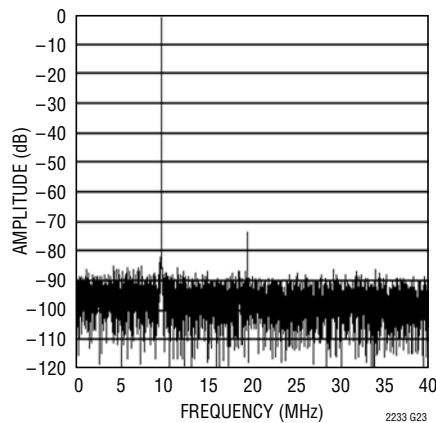
LTC2233: 8192 Point FFT,
 $f_{IN} = 140\text{MHz}$, -1dB, 1V Range



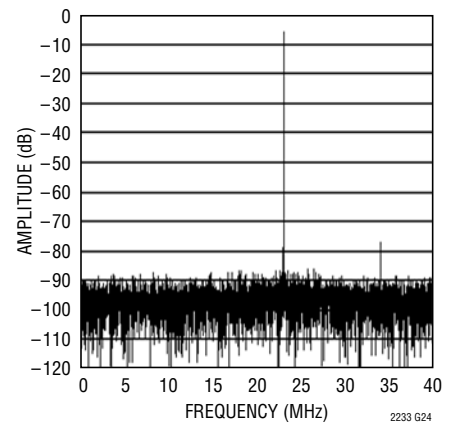
LTC2233: 8192 Point FFT,
 $f_{IN} = 250\text{MHz}$, -1dB, 2V Range



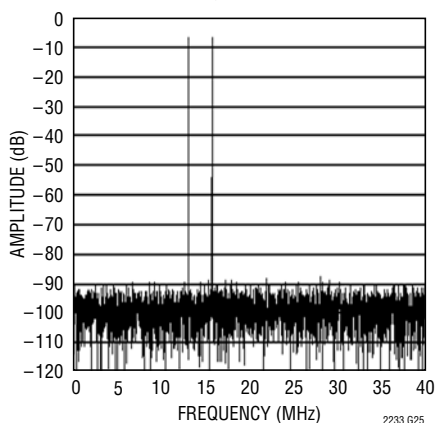
LTC2233: 8192 Point FFT,
 $f_{IN} = 250\text{MHz}$, -1dB, 1V Range



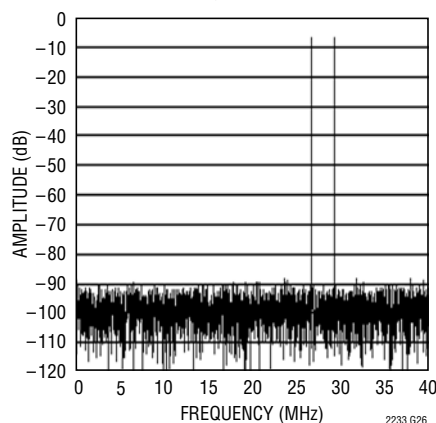
LTC2233: 8192 Point FFT,
 $f_{IN} = 500\text{MHz}$, -6dB, 1V Range



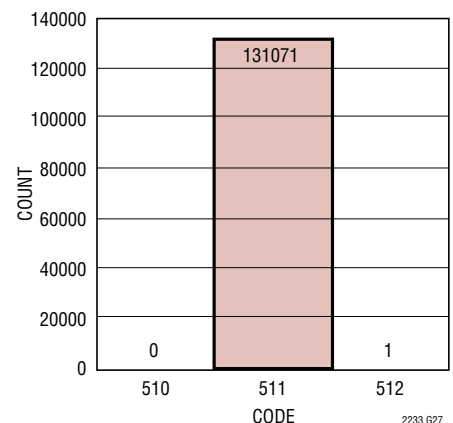
LTC2233: 8192 Point 2-Tone FFT,
 $f_{IN} = 68\text{MHz}$ and 70MHz , -7dB
 Each, 2V Range



LTC2233: 8192 Point 2-Tone FFT,
 $f_{IN} = 138\text{MHz}$ and 140MHz , -7dB
 Each, 1V Range



LTC2233: Shorted Input Noise
 Histogram



PIN FUNCTIONS

A_{IN+} (Pin 1): Positive Differential Analog Input.

A_{IN-} (Pin 2): Negative Differential Analog Input.

REFHA (Pins 3, 4): ADC High Reference. Bypass to Pins 5, 6 with 0.1μF ceramic chip capacitor, to Pins 9, 10 with a 2.2μF ceramic capacitor and to ground with a 1μF ceramic capacitor.

REFLB (Pins 5, 6): ADC Low Reference. Bypass to Pins 5, 6 with 0.1μF ceramic chip capacitor. Do not connect to Pins 9, 10.

REFHB (Pins 7, 8): ADC High Reference. Bypass to Pins 9, 10 with 0.1μF ceramic chip capacitor. Do not connect to Pins 3, 4.

REFLA (Pins 9, 10): ADC Low Reference. Bypass to Pins 7, 8 with 0.1μF ceramic chip capacitor, to Pins 3, 4 with a 2.2μF ceramic capacitor and to ground with a 1μF ceramic capacitor.

V_{DD} (Pins 11, 12, 14, 46, 47): 3.3V Supply. Bypass to GND with 0.1μF ceramic chip capacitors. Adjacent pins can share a bypass capacitor.

GND (Pins 13, 15, 45, 48): ADC Power Ground.

ENC+ (Pin 16): Encode Input. The input is sampled on the positive edge.

ENC- (Pin 17): Encode Complement Input. The input is sampled on the negative edge. Bypass to ground with 0.1μF ceramic for single-ended ENCODE signal.

SHDN (Pin 18): Shutdown Mode Selection Pin. Connecting SHDN to GND and $\overline{OE}$ to GND results in normal operation with the outputs enabled. Connecting SHDN to GND and $\overline{OE}$ to V_{DD} results in normal operation with the outputs at high impedance. Connecting SHDN to V_{DD} and $\overline{OE}$ to GND results in nap mode with the outputs at high impedance. Connecting SHDN to V_{DD} and $\overline{OE}$ to V_{DD} results in sleep mode with the outputs at high impedance.

$\overline{OE}$ (Pin 19): Output Enable Pin. Refer to SHDN pin function.

CLOCKOUT (Pin 20): Data Valid Output. Latch data on the falling edge of CLKOUT.

NC (Pins 21, 24): Do not connect these pins.

D0 – D9 (Pins 25, 26, 29, 30, 31, 34, 35, 36, 39, 40): Digital Outputs. D9 is the MSB.

OGND (Pins 22, 27, 32, 38): Output Driver Ground.

OV_{DD} (Pins 23, 28, 33, 37): Positive Supply for the Output Drivers. Bypass to ground with 0.1μF ceramic chip capacitors.

OF (Pin 41): Over/Under Flow Output. High when an over or under flow has occurred.

MODE (Pin 42): Output Format and Clock Duty Cycle Stabilizer Selection Pin. Connecting MODE to 0V selects offset binary output format and turns the clock duty cycle stabilizer off. Connecting MODE to 1/3 V_{DD} selects offset binary output format and turns the clock duty cycle stabilizer on. Connecting MODE to 2/3 V_{DD} selects 2's complement output format and turns the clock duty cycle stabilizer on. Connecting MODE to V_{DD} selects 2's complement output format and turns the clock duty cycle stabilizer off.

SENSE (Pin 43): Reference Programming Pin. Connecting SENSE to V_{CM} selects the internal reference and a ±0.5V input range. V_{DD} selects the internal reference and a ±1V input range. An external reference greater than 0.5V and less than 1V applied to SENSE selects an input range of ±V_{SENSE}. ±1V is the largest valid input range.

V_{CM} (Pin 44): 1.6V Output and Input Common Mode Bias. Bypass to ground with 2.2μF ceramic chip capacitor.

Exposed Pad (Pin 49): ADC Power Ground. The exposed pad on the bottom of the package needs to be soldered to ground.

FUNCTIONAL BLOCK DIAGRAM

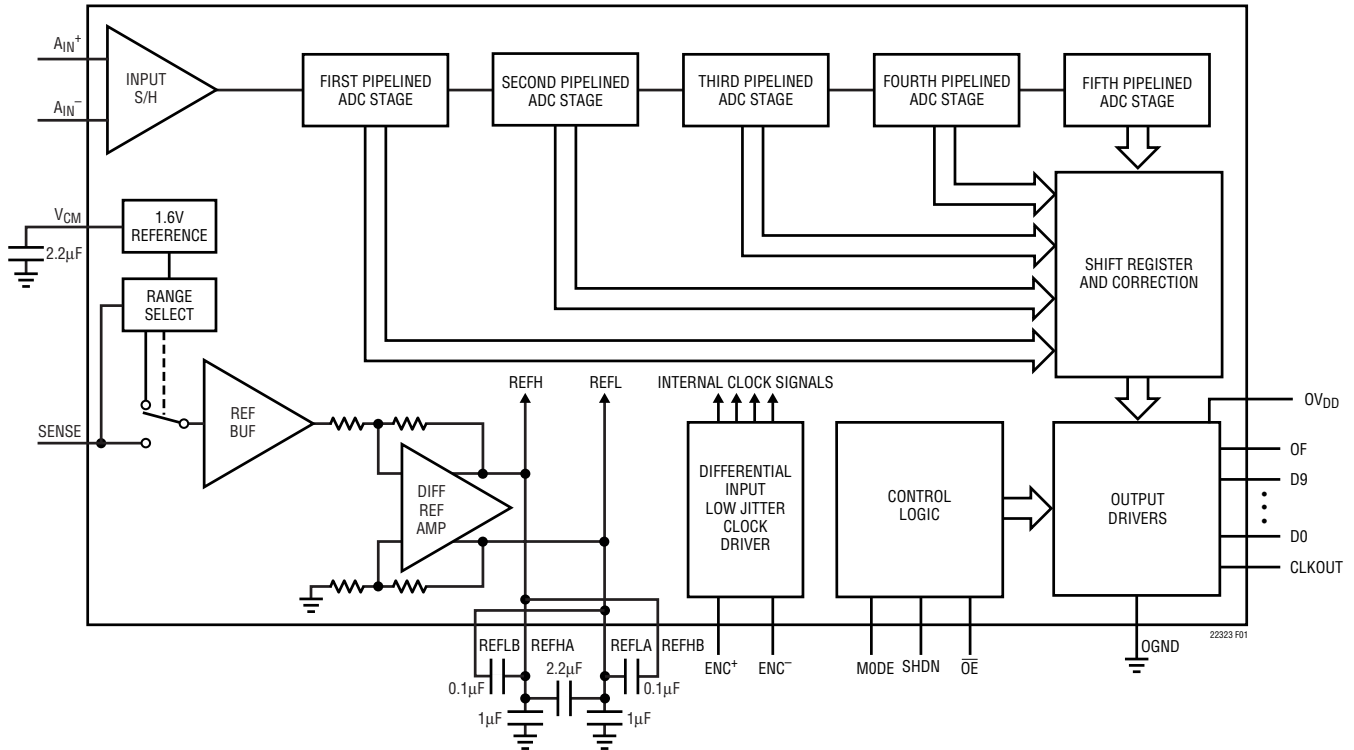
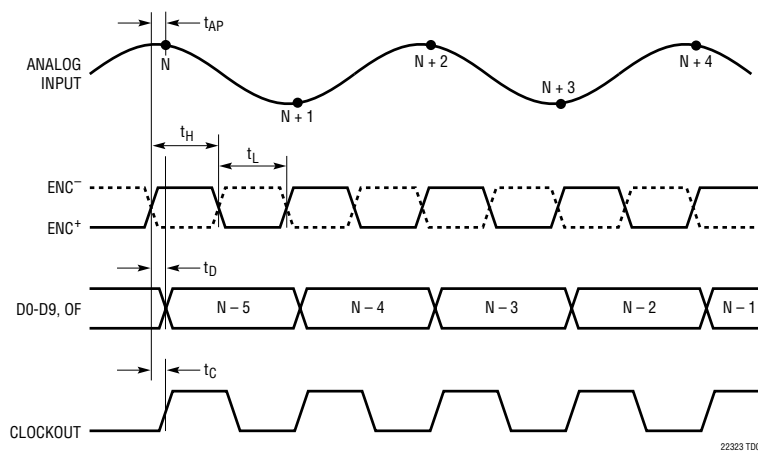


Figure 1. Functional Block Diagram

TIMING DIAGRAMS

Timing Diagram



APPLICATIONS INFORMATION

DYNAMIC PERFORMANCE

Signal-to-Noise Plus Distortion Ratio

The signal-to-noise plus distortion ratio $[S/(N + D)]$ is the ratio between the RMS amplitude of the fundamental input frequency and the RMS amplitude of all other frequency components at the ADC output. The output is band limited to frequencies above DC to below half the sampling frequency.

Signal-to-Noise Ratio

The signal-to-noise ratio (SNR) is the ratio between the RMS amplitude of the fundamental input frequency and the RMS amplitude of all other frequency components except the first five harmonics and DC.

Total Harmonic Distortion

Total harmonic distortion is the ratio of the RMS sum of all harmonics of the input signal to the fundamental itself. The out-of-band harmonics alias into the frequency band between DC and half the sampling frequency. THD is expressed as:

$$THD = 20\log \left(\frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + \dots + V_n^2}}{V_1} \right)$$

where V_1 is the RMS amplitude of the fundamental frequency and V_2 through V_n are the amplitudes of the second through n th harmonics. The THD calculated in this data sheet uses all the harmonics up to the fifth.

Intermodulation Distortion

If the ADC input signal consists of more than one spectral component, the ADC transfer function nonlinearity can produce intermodulation distortion (IMD) in addition to THD. IMD is the change in one sinusoidal input caused by the presence of another sinusoidal input at a different frequency.

If two pure sine waves of frequencies f_a and f_b are applied to the ADC input, nonlinearities in the ADC transfer function can create distortion products at the sum and difference frequencies of $m f_a \pm n f_b$, where m and $n = 0, 1, 2, 3$, etc. The 3rd order intermodulation products are $2f_a + f_b$, $2f_b + f_a$, $2f_a - f_b$ and $2f_b - f_a$. The intermodulation distortion is defined as the ratio of the RMS value of either input tone to the RMS value of the largest 3rd order intermodulation product.

Spurious Free Dynamic Range (SFDR)

Spurious free dynamic range is the peak harmonic or spurious noise that is the largest spectral component excluding the input signal and DC. This value is expressed in decibels relative to the RMS value of a full scale input signal.

Input Bandwidth

The input bandwidth is that input frequency at which the amplitude of the reconstructed fundamental is reduced by 3dB for a full scale input signal.

Aperture Delay Time

The time from when a rising ENC^+ equals the ENC^- voltage to the instant that the input signal is held by the sample and hold circuit.

Aperture Delay Jitter

The variation in the aperture delay time from conversion to conversion. This random variation will result in noise when sampling an AC input. The signal to noise ratio due to the jitter alone will be:

$$SNR_{JITTER} = -20\log (2\pi \cdot f_{IN} \cdot t_{JITTER})$$

APPLICATIONS INFORMATION

CONVERTER OPERATION

As shown in Figure 1, the LTC2232/LTC2233 is a CMOS pipelined multistep converter. The converter has five pipelined ADC stages; a sampled analog input will result in a digitized value five cycles later (see the Timing Diagram section). For optimal AC performance the analog inputs should be driven differentially. For cost sensitive applications, the analog inputs can be driven single-ended with slightly worse harmonic distortion. The encode input is differential for improved common mode noise immunity. The LTC2232/LTC2233 has two phases of operation, determined by the state of the differential ENC⁺/ENC⁻ input pins. For brevity, the text will refer to ENC⁺ greater than ENC⁻ as ENC high and ENC⁺ less than ENC⁻ as ENC low.

Each pipelined stage shown in Figure 1 contains an ADC, a reconstruction DAC and an interstage residue amplifier. In operation, the ADC quantizes the input to the stage and the quantized value is subtracted from the input by the DAC to produce a residue. The residue is amplified and output by the residue amplifier. Successive stages operate out of phase so that when the odd stages are outputting their residue, the even stages are acquiring that residue and vice versa.

When ENC is low, the analog input is sampled differentially directly onto the input sample-and-hold capacitors, inside the "Input S/H" shown in the block diagram. At the instant that ENC transitions from low to high, the sampled input is held. While ENC is high, the held input voltage is buffered by the S/H amplifier which drives the first pipelined ADC stage. The first stage acquires the output of the S/H during this high phase of ENC. When ENC goes back low, the first stage produces its residue which is acquired by the second stage. At the same time, the input S/H goes back to acquiring the analog input. When ENC goes back high, the second stage produces its residue which is acquired by the third stage. An identical process is repeated for the third and fourth stages, resulting in a fourth stage residue that is sent to the fifth stage ADC for final evaluation.

Each ADC stage following the first has additional range to accommodate flash and amplifier offset errors. Results from all of the ADC stages are digitally synchronized such that the results can be properly combined in the correction logic before being sent to the output buffer.

SAMPLE/HOLD OPERATION AND INPUT DRIVE

Sample/Hold Operation

Figure 2 shows an equivalent circuit for the LTC2232/LTC2233 CMOS differential sample-and-hold. The analog inputs are connected to the sampling capacitors (C_{SAMPLE}) through NMOS transistors. The capacitors shown attached to each input ($C_{\text{PARASITIC}}$) are the summation of all other capacitance associated with each input.

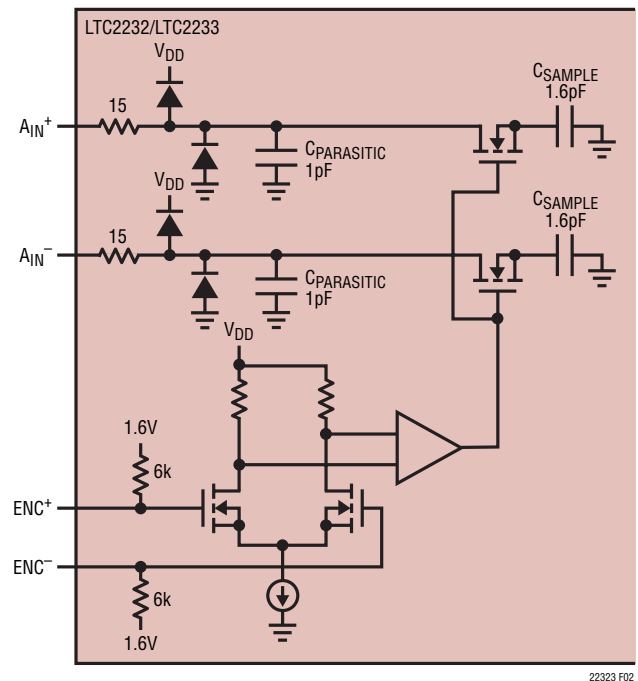


Figure 2. Equivalent Input Circuit

APPLICATIONS INFORMATION

During the sample phase when ENC is low, the transistors connect the analog inputs to the sampling capacitors and they charge to, and track the differential input voltage. When ENC transitions from low to high, the sampled input voltage is held on the sampling capacitors. During the hold phase when ENC is high, the sampling capacitors are disconnected from the input and the held voltage is passed to the ADC core for processing. As ENC transitions from high to low, the inputs are reconnected to the sampling capacitors to acquire a new sample. Since the sampling capacitors still hold the previous sample, a charging glitch proportional to the change in voltage between samples will be seen at this time. If the change between the last sample and the new sample is small, the charging glitch seen at the input will be small. If the input change is large, such as the change seen with input frequencies near Nyquist, then a larger charging glitch will be seen.

Single-Ended Input

For cost sensitive applications, the analog inputs can be driven single-ended. With a single-ended input the harmonic distortion and INL will degrade, but the SNR and DNL will remain unchanged. For a single-ended input, A_{IN}^+ should be driven with the input signal and A_{IN}^- should be connected to 1.6V or V_{CM} .

Common Mode Bias

For optimal performance the analog inputs should be driven differentially. Each input should swing $\pm 0.5V$ for the 2V range or $\pm 0.25V$ for the 1V range, around a common mode voltage of 1.6V. The V_{CM} output pin (Pin 44) may be used to provide the common mode bias level. V_{CM} can be tied directly to the center tap of a transformer to set the DC input level or as a reference level to an op amp differential driver circuit. The V_{CM} pin must be bypassed to ground close to the ADC with a 2.2 μF or greater capacitor.

Input Drive Impedance

As with all high performance, high speed ADCs, the dynamic performance of the LTC2232/LTC2233 can be influenced by the input drive circuitry, particularly the second and third harmonics. Source impedance and input reactance can influence SFDR. At the falling edge of ENC,

the sample-and-hold circuit will connect the 1.6pF sampling capacitor to the input pin and start the sampling period. The sampling period ends when ENC rises, holding the sampled input on the sampling capacitor. Ideally the input circuitry should be fast enough to fully charge the sampling capacitor during the sampling period $1/(2F_{ENCODE})$; however, this is not always possible and the incomplete settling may degrade the SFDR. The sampling glitch has been designed to be as linear as possible to minimize the effects of incomplete settling.

For the best performance, it is recommended to have a source impedance of 100 Ω or less for each input. The source impedance should be matched for the differential inputs. Poor matching will result in higher even order harmonics, especially the second.

Input Drive Circuits

Figure 3 shows the LTC2232/LTC2233 being driven by an RF transformer with a center tapped secondary. The secondary center tap is DC biased with V_{CM} , setting the ADC input signal at its optimum DC level. Terminating on the transformer secondary is desirable, as this provides a common mode path for charging glitches caused by the sample and hold. Figure 3 shows a 1:1 turns ratio transformer. Other turns ratios can be used if the source impedance seen by the ADC does not exceed 100 Ω for each ADC input. A disadvantage of using a transformer is the loss of low frequency response. Most small RF transformers have poor performance at frequencies below 1MHz.

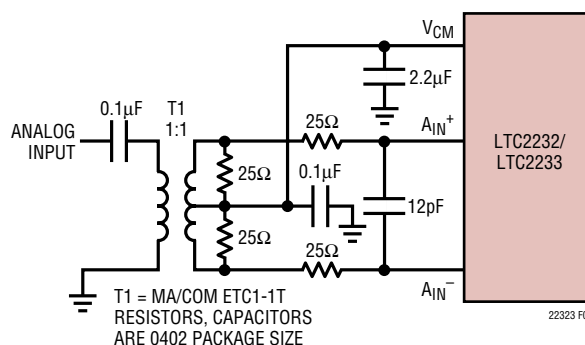


Figure 3. Single-Ended to Differential Conversion Using a Transformer

APPLICATIONS INFORMATION

Figure 4 demonstrates the use of a differential amplifier to convert a single ended input signal into a differential input signal. The advantage of this method is that it provides low frequency input response; however, the limited gain bandwidth of most op amps will limit the SFDR at high input frequencies.

Figure 5 shows a single-ended input circuit. The impedance seen by the analog inputs should be matched. This circuit is not recommended if low distortion is required.

The 25Ω resistors and 12pF capacitor on the analog inputs serve two purposes: isolating the drive circuitry from the sample-and-hold charging glitches and limiting the wideband noise at the converter input. For input frequencies higher than 100MHz, the capacitor may need to be decreased to prevent excessive signal loss.

For input frequencies above 100MHz the input circuits of Figure 6, 7 and 8 are recommended. The balun transformer gives better high frequency response than a flux coupled center tapped transformer. The coupling capacitors allow the analog inputs to be DC biased at 1.6V. In Figure 8 the series inductors are impedance matching elements that maximize the ADC bandwidth.

Reference Operation

Figure 9 shows the LTC2232/LTC2233 reference circuitry consisting of a 1.6V bandgap reference, a difference amplifier and switching and control circuit. The internal voltage reference can be configured for two pin selectable

input ranges of 2V ($\pm 1V$ differential) or 1V ($\pm 0.5V$ differential). Tying the SENSE pin to V_{DD} selects the 2V range; tying the SENSE pin to V_{CM} selects the 1V range.

The 1.6V bandgap reference serves two functions: its output provides a DC bias point for setting the common mode voltage of any external input circuitry; additionally, the reference is used with a difference amplifier to generate the differential reference levels needed by the internal ADC circuitry. An external bypass capacitor is required for the 1.6V reference output, V_{CM} . This provides a high frequency low impedance path to ground for internal and external circuitry.

The difference amplifier generates the high and low reference for the ADC. High speed switching circuits are connected to these outputs and they must be externally bypassed. Each output has four pins: two each of REFHA and REFHB for the high reference and two each of REFLA and REFLB for the low reference. The multiple output pins are needed to reduce package inductance. Bypass capacitors must be connected as shown in Figure 9.

Other voltage ranges in between the pin selectable ranges can be programmed with two external resistors as shown in Figure 10. An external reference can be used by applying its output directly or through a resistor divider to SENSE. It is not recommended to drive the SENSE pin with a logic device. The SENSE pin should be tied to the appropriate level as close to the converter as possible. If the SENSE pin is driven externally, it should be bypassed to ground as close to the device as possible with a 1μF ceramic capacitor.

APPLICATIONS INFORMATION

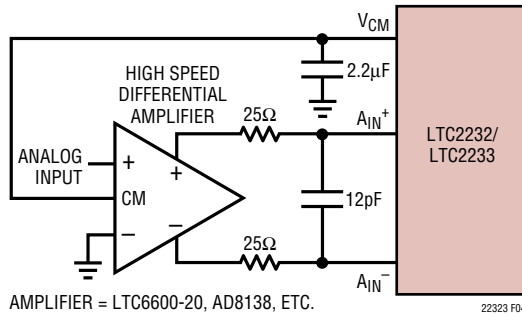


Figure 4. Differential Drive with an Amplifier

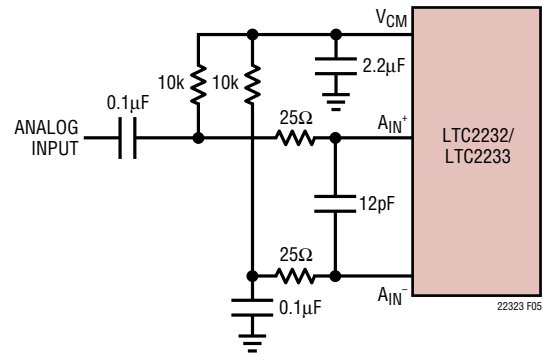


Figure 5. Single-Ended Drive

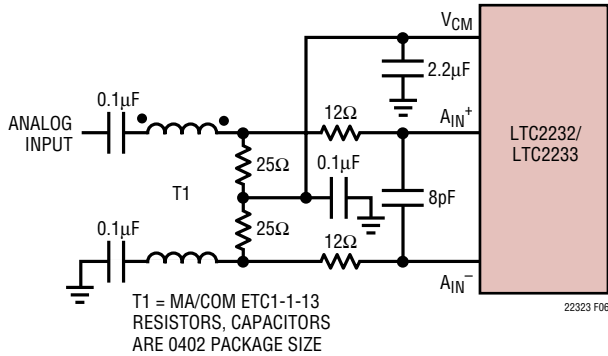


Figure 6. Recommended Front End Circuit for Input Frequencies Between 100MHz and 250MHz

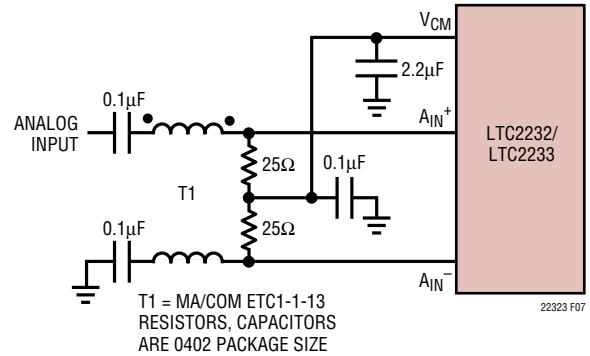


Figure 7. Recommended Front End Circuit for Input Frequencies Between 250MHz and 500MHz

APPLICATIONS INFORMATION

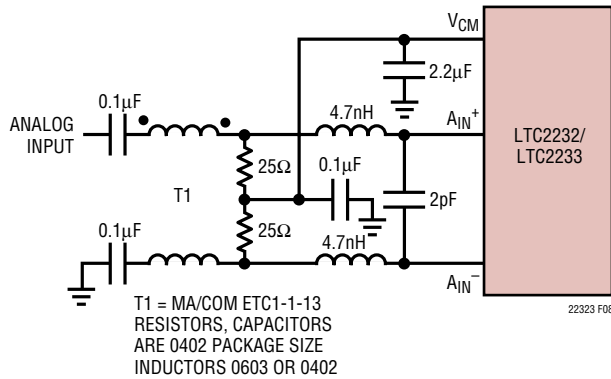


Figure 8. Recommended Front End Circuit for Input Frequencies Above 500MHz

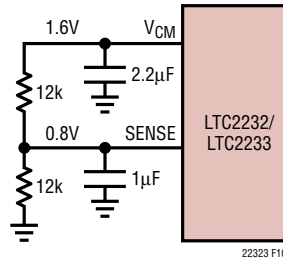


Figure 10. 1.6V Range ADC

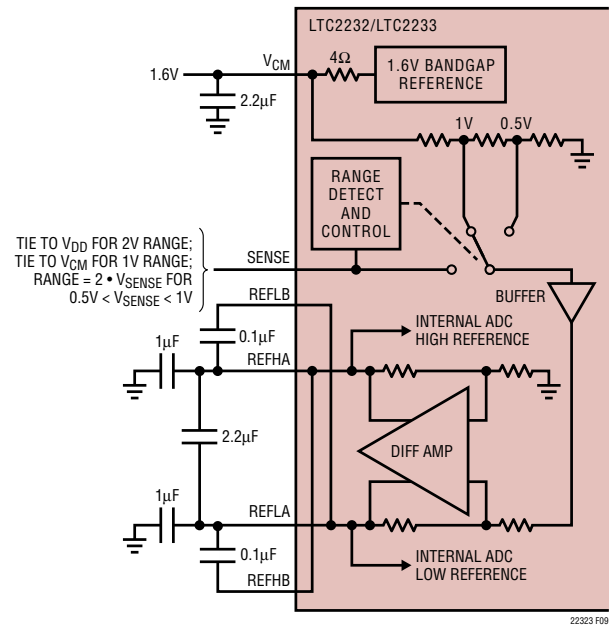


Figure 9. Equivalent Reference Circuit

APPLICATIONS INFORMATION

Input Range

The input range can be set based on the application. The 2V input range will provide the best signal-to-noise performance while maintaining excellent SFDR. The 1V input range will have better SFDR performance, but the SNR will degrade by 1.5dB. See the Typical Performance Characteristics section.

Driving the Encode Inputs

The noise performance of the LTC2232/LTC2233 can depend on the encode signal quality as much as on the analog input. The ENC⁺/ENC⁻ inputs are intended to be driven differentially, primarily for noise immunity from common mode noise sources. Each input is biased through a 6k resistor to a 1.6V bias. The bias resistors set the DC operating point for transformer coupled drive circuits and can set the logic threshold for single-ended drive circuits.

Any noise present on the encode signal will result in additional aperture jitter that will be RMS summed with the inherent ADC aperture jitter.

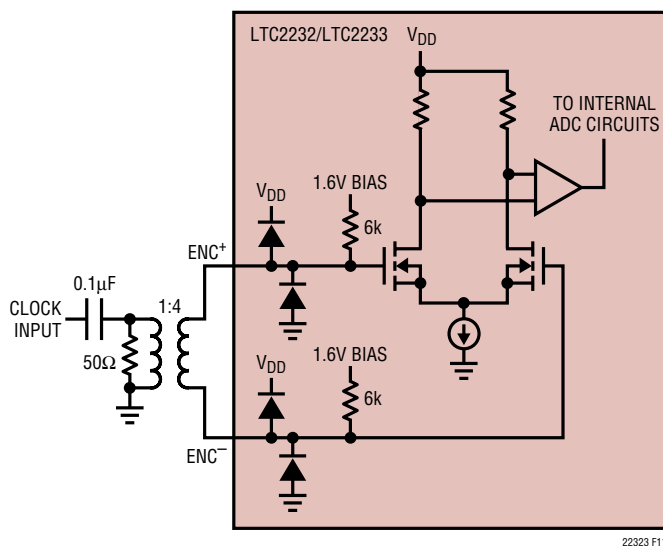


Figure 11. Transformer Driven ENC⁺/ENC⁻

In applications where jitter is critical (high input frequencies) take the following into consideration:

1. Differential drive should be used.
2. Use as large an amplitude as possible; if transformer coupled use a higher turns ratio to increase the amplitude.
3. If the ADC is clocked with a sinusoidal signal, filter the encode signal to reduce wideband noise.
4. Balance the capacitance and series resistance at both encode inputs so that any coupled noise will appear at both inputs as common mode noise. The encode inputs have a common mode range of 1.1V to 2.5V. Each input may be driven from ground to V_{DD} for single-ended drive.

Maximum and Minimum Encode Rates

The maximum encode rate for the LTC2232/LTC2233 is 105MSPS (LTC2232) and 80MSPS (LTC2233). For the ADC to operate properly, the encode signal should have a 50% ($\pm 5\%$) duty cycle. Each half cycle must have at least 4.5ns (LTC2232) or 5.9ns (LTC2233) for the ADC internal circuitry to have enough settling time for proper operation. Achieving a precise 50% duty cycle is easy with differential sinusoidal drive using a transformer or using symmetric differential logic such as PECL or LVDS.

An optional clock duty cycle stabilizer circuit can be used if the input clock has a non 50% duty cycle. This circuit uses the rising edge of the ENC⁺ pin to sample the analog input. The falling edge of ENC⁺ is ignored and the internal falling edge is generated by a phase-locked loop. The input clock duty cycle can vary from 20% to 80% and the clock duty cycle stabilizer will maintain a constant 50% internal duty cycle. If the clock is turned off for a long period of time, the duty cycle stabilizer circuit will require a hundred clock cycles for the PLL to lock onto the input clock. To use the clock duty cycle stabilizer, the MODE pin should be connected to $1/3V_{DD}$ or $2/3V_{DD}$ using external resistors.

APPLICATIONS INFORMATION

The lower limit of the LTC2232/LTC2233 sample rate is determined by droop of the sample-and-hold circuits. The pipelined architecture of this ADC relies on storing analog signals on small valued capacitors. Junction leakage will discharge the capacitors. The specified minimum operating frequency for the LTC2232/LTC2233 is 1Msps.

DIGITAL OUTPUTS

Table 1 shows the relationship between the analog input voltage, the digital data bits and the overflow bit.

Table 1. Output Codes vs Input Voltage

$A_{IN}^+ - A_{IN}^-$ (2V Range)	OF	D9 – D0 (Offset Binary)	D9 – D0 (2's Complement)
>+1.000000V	1	11 1111 1111	01 1111 1111
+0.998047V	0	11 1111 1111	01 1111 1111
+0.996094V	0	11 1111 1110	01 1111 1110
+0.001953V	0	10 0000 0001	00 0000 0001
0.000000V	0	10 0000 0000	00 0000 0000
-0.001953V	0	01 1111 1111	11 1111 1111
-0.003906V	0	01 1111 1110	11 1111 1110
-0.998047V	0	00 0000 0001	10 0000 0001
-1.000000V	0	00 0000 0000	10 0000 0000
<-1.000000V	1	00 0000 0000	10 0000 0000

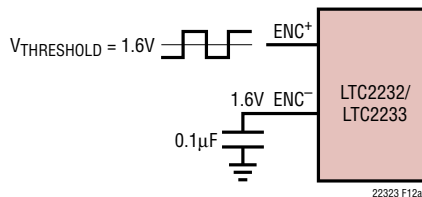


Figure 12a. Single-Ended ENC Drive, Not Recommended for Low Jitter

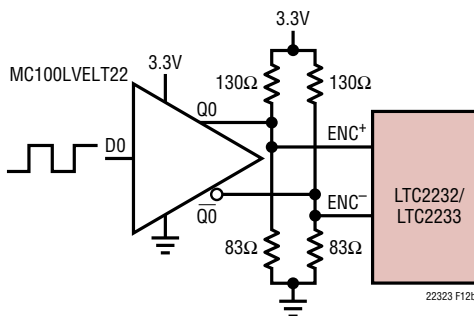


Figure 12b. ENC Drive Using a CMOS to PECL Translator

Digital Output Buffers

Figure 13 shows an equivalent circuit for a single output buffer. Each buffer is powered by OV_{DD} and OGND, isolated from the ADC power and ground. The additional N-channel transistor in the output driver allows operation down to low voltages. The internal resistor in series with the output makes the output appear as 50Ω to external circuitry and may eliminate the need for external damping resistors.

As with all high speed/high resolution converters, the digital output loading can affect the performance. The digital outputs of the LTC2232/LTC2233 should drive a minimal capacitive load to avoid possible interaction between the digital outputs and sensitive input circuitry. The output should be buffered with a device such as an ALVCH16373 CMOS latch. For full speed operation the capacitive load should be kept under 10pF.

Lower OV_{DD} voltages will also help reduce interference from the digital outputs.

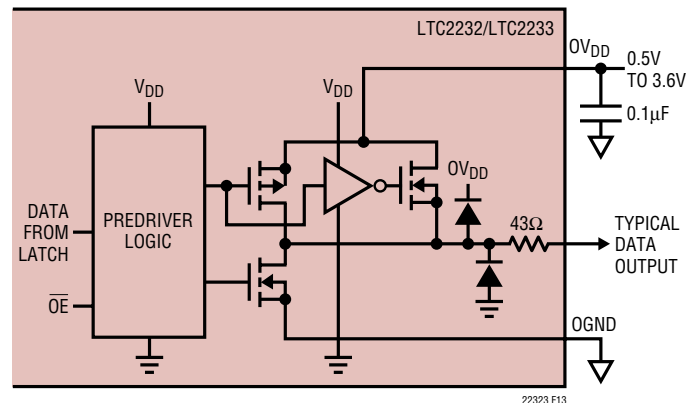


Figure 13. Digital Output Buffer

APPLICATIONS INFORMATION

Data Format

The LTC2232/LTC2233 parallel digital output can be selected for offset binary or 2's complement format. The format is selected with the MODE pin. Connecting MODE to GND or $1/3V_{DD}$ selects offset binary output format. Connecting MODE to $2/3V_{DD}$ or V_{DD} selects 2's complement output format. An external resistor divider can be used to set the $1/3V_{DD}$ or $2/3V_{DD}$ logic values. Table 2 shows the logic states for the MODE pin.

Table 2. MODE Pin Function

MODE Pin	Output Format	Clock Duty Cycle Stabilizer
0	Offset Binary	Off
$1/3V_{DD}$	Offset Binary	On
$2/3V_{DD}$	2's Complement	On
V_{DD}	2's Complement	Off

Overflow Bit

When OF outputs a logic high the converter is either overranged or underranged.

Output Clock

The ADC has a delayed version of the ENC⁺ input available as a digital output, CLKOUT. The CLKOUT pin can be used to synchronize the converter data to the digital system. This is necessary when using a sinusoidal encode. Data will be updated just after CLKOUT rises and can be latched on the falling edge of CLKOUT.

Output Driver Power

Separate output power and ground pins allow the output drivers to be isolated from the analog circuitry. The power supply for the digital output buffers, OV_{DD} , should be tied to the same power supply as for the logic being driven. For example if the converter is driving a DSP powered by a 1.8V supply then OV_{DD} should be tied to that same 1.8V supply.

OV_{DD} can be powered with any voltage up to 3.6V. OGND can be powered with any voltage from GND up to 1V and must be less than OV_{DD} . The logic outputs will swing between OGND and OV_{DD} .

Output Enable

The outputs may be disabled with the output enable pin, $\overline{OE}$. $\overline{OE}$ high disables all data outputs including OF and CLKOUT. The data access and bus relinquish times are too slow to allow the outputs to be enabled and disabled during full speed operation. The output Hi-Z state is intended for use during long periods of inactivity.

Sleep and Nap Modes

The converter may be placed in shutdown or nap modes to conserve power. Connecting SHDN to GND results in normal operation. Connecting SHDN to V_{DD} and $\overline{OE}$ to V_{DD} results in sleep mode, which powers down all circuitry including the reference and typically dissipates 1mW. When exiting sleep mode it will take milliseconds for the output data to become valid because the reference capacitors have

APPLICATIONS INFORMATION

to recharge and stabilize. Connecting SHDN to V_{DD} and $\overline{OE}$ to GND results in nap mode, which typically dissipates 30mW. In nap mode, the on-chip reference circuit is kept on, so that recovery from nap mode is faster than that from sleep mode, typically taking 100 clock cycles. In both sleep and nap mode all digital outputs are disabled and enter the Hi-Z state.

GROUNDING AND BYPASSING

The LTC2232/LTC2233 requires a printed circuit board with a clean unbroken ground plane. A multilayer board with an internal ground plane is recommended. Layout for the printed circuit board should ensure that digital and analog signal lines are separated as much as possible. In particular, care should be taken not to run any digital track alongside an analog signal track or underneath the ADC.

High quality ceramic bypass capacitors should be used at the V_{DD} , OV_{DD} , V_{CM} , REFHA, REFHB, REFLA and REFLB pins as shown in the block diagram on the front page of this data sheet. Bypass capacitors must be located as close to the pins as possible. Of particular importance are the capaci-

tors between REFHA and REFLB and between REFHB and REFLA. These capacitors should be as close to the device as possible (1.5mm or less). Size 0402 ceramic capacitors are recommended. The 2.2 μ F capacitor between REFHA and REFLA can be somewhat further away. The traces connecting the pins and bypass capacitors must be kept short and should be made as wide as possible.

The LTC2232/LTC2233 differential inputs should run parallel and close to each other. The input traces should be as short as possible to minimize capacitance and to minimize noise pickup.

HEAT TRANSFER

Most of the heat generated by the LTC2232/LTC2233 is transferred from the die through the bottom-side exposed pad and package leads onto the printed circuit board. For good electrical and thermal performance, the exposed pad should be soldered to a large grounded pad on the PC board. It is critical that all ground pins are connected to a ground plane of sufficient area.

APPLICATIONS INFORMATION

Clock Sources for Undersampling

Undersampling raises the bar on the clock source and the higher the input frequency, the greater the sensitivity to clock jitter or phase noise. A clock source that degrades SNR of a full-scale signal by 1dB at 70MHz will degrade SNR by 3dB at 140MHz, and 4.5dB at 190MHz.

In cases where absolute clock frequency accuracy is relatively unimportant and only a single ADC is required, a 3V canned oscillator from vendors such as Saronix or Vectron can be placed close to the ADC and simply connected directly to the ADC. If there is any distance to the ADC, some source termination to reduce ringing that may occur even over a fraction of an inch is advisable. You must not allow the clock to overshoot the supplies or performance will suffer. Do not filter the clock signal with a narrow band filter unless you have a sinusoidal clock source, as the rise and fall time artifacts present in typical digital clock signals will be translated into phase noise.

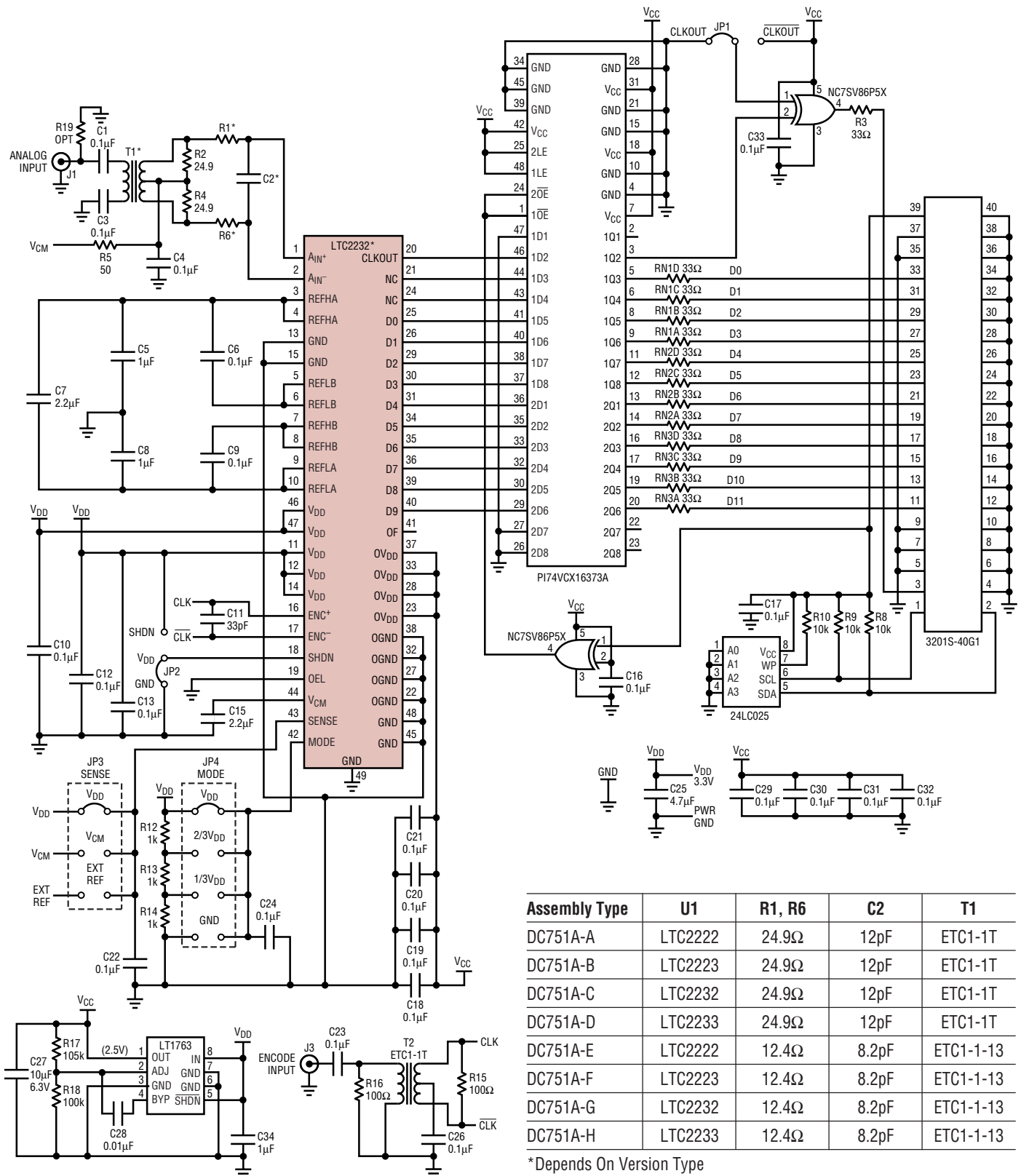
The lowest phase noise oscillators have single-ended sinusoidal outputs, and for these devices the use of a filter close to the ADC may be beneficial. This filter should be close to the ADC to both reduce roundtrip reflection times, as well as reduce the susceptibility of the traces between the filter and the ADC. If you are sensitive to close-in phase noise, the power supply for oscillators and any buffers

must be very stable, or propagation delay variation with supply will translate into phase noise. Even though these clock sources may be regarded as digital devices, do not operate them on a digital supply. If your clock is also used to drive digital devices such as an FPGA, you should locate the oscillator, and any clock fan-out devices close to the ADC, and give the routing to the ADC precedence. The clock signals to the FPGA should have series termination at the source to prevent high frequency noise from the FPGA disturbing the substrate of the clock fan-out device. If you use an FPGA as a programmable divider, you must re-time the signal using the original oscillator, and the re-timing flip-flop as well as the oscillator should be close to the ADC, and powered with a very quiet supply.

For cases where there are multiple ADCs, or where the clock source originates some distance away, differential clock distribution is advisable. This is advisable both from the perspective of EMI, but also to avoid receiving noise from digital sources both radiated, as well as propagated in the waveguides that exist between the layers of multi-layer PCBs. The differential pairs must be close together, and distanced from other signals. The differential pair should be guarded on both sides with copper distanced at least 3x the distance between the traces, and grounded with vias no more than 1/4 inch apart.

APPLICATIONS INFORMATION

Evaluation Circuit Schematic of the LTC2232



Assembly Type	U1	R1, R6	C2	T1
DC751A-A	LTC2222	24.9Ω	12pF	ETC1-1T
DC751A-B	LTC2223	24.9Ω	12pF	ETC1-1T
DC751A-C	LTC2232	24.9Ω	12pF	ETC1-1T
DC751A-D	LTC2233	24.9Ω	12pF	ETC1-1T
DC751A-E	LTC2222	12.4Ω	8.2pF	ETC1-1-13
DC751A-F	LTC2223	12.4Ω	8.2pF	ETC1-1-13
DC751A-G	LTC2232	12.4Ω	8.2pF	ETC1-1-13
DC751A-H	LTC2233	12.4Ω	8.2pF	ETC1-1-13

*Depends On Version Type

Pin 1 to 39 of the DC7515A schematic diagram. The diagram shows the internal circuitry of the device, including various logic blocks, registers, and control logic. Key components include:

- Pin 1:** CLK (Clock input)
- Pin 2:** EXT REF (External Reference input)
- Pin 3:** VDD +3.3V (Supply voltage)
- Pin 4:** J1 (Connector pin)
- Pin 5:** ANALOG INPUT (Analog input)
- Pin 6:** E4 (External input/output)
- Pin 7:** PWR GND (Power ground)
- Pin 8:** J3 (Connector pin)
- Pin 9:** ENCODE INPUT (Encode input)
- Pin 10:** GND (Ground)
- Pin 11:** E5 (External input/output)
- Pin 12:** J2 (Connector pin)
- Pin 13:** L5B (Least Significant Bit output)
- Pin 14:** J1 (Connector pin)
- Pin 15:** CLKOUT (Clock output)
- Pin 16:** CLKOUT (Clock output)
- Pin 17:** J1 (Connector pin)
- Pin 18:** J1 (Connector pin)
- Pin 19:** J1 (Connector pin)
- Pin 20:** J1 (Connector pin)
- Pin 21:** J1 (Connector pin)
- Pin 22:** J1 (Connector pin)
- Pin 23:** J1 (Connector pin)
- Pin 24:** J1 (Connector pin)
- Pin 25:** J1 (Connector pin)
- Pin 26:** J1 (Connector pin)
- Pin 27:** J1 (Connector pin)
- Pin 28:** J1 (Connector pin)
- Pin 29:** J1 (Connector pin)
- Pin 30:** J1 (Connector pin)
- Pin 31:** J1 (Connector pin)
- Pin 32:** J1 (Connector pin)
- Pin 33:** J1 (Connector pin)
- Pin 34:** J1 (Connector pin)
- Pin 35:** J1 (Connector pin)
- Pin 36:** J1 (Connector pin)
- Pin 37:** J1 (Connector pin)
- Pin 38:** J1 (Connector pin)
- Pin 39:** J1 (Connector pin)

A high-contrast, black and white image of a circuit board layout. The image shows a complex arrangement of white traces and components on a black background. On the left side, there are several circular features of varying sizes, some of which appear to be mounting holes or vias. A series of small, dark, rectangular components are arranged in a row. A prominent feature is a large, white, rectangular area in the center, which could be a microcontroller or a large component. To the right, there are more traces and components, including a small, white, rectangular component. The overall layout is dense and intricate, typical of a printed circuit board (PCB) design.

RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LTC1748	14-Bit, 80Msps, 5V ADC	76.3dB SNR, 90dB SFDR, 48-Pin TSSOP Package
LTC1750	14-Bit, 80Msps, 5V Wideband ADC	Up to 500MHz IF Undersampling, 90dB SFDR
LT1993-2	High Speed Differential Op Amp	800MHz BW, 70dBc Distortion at 70MHz, 6dB Gain
LT1994	Low Noise, Low Distortion Fully Differential Input/Output Amplifier/Driver	Low Distortion: -94dBc at 1MHz
LTC2202	16-Bit, 10Msps, 3.3V ADC, Lowest Noise	150mW, 81.6dB SNR, 100dB SFDR, 48-Pin QFN
LTC2208	16-Bit, 130Msps, 3.3V ADC, LVDS Outputs	1250mW, 78dB SNR, 100dB SFDR, 64-Pin QFN
LTC2220-1	12-Bit, 185Msps, 3.3V ADC, LVDS Outputs	910mW, 67.7dB SNR, 80dB SFDR, 64-Pin QFN
LTC2222	12-Bit, 105Msps, 3.3V ADC, High IF Sampling	475mW, 68.4dB SNR, 84dB SFDR, 48-Pin QFN
LTC2222-11	11-Bit, 105Msps, 3.3V ADC, High IF Sampling	475mW, 65.7dB SNR, 84dB SFDR, 48-Pin QFN
LTC2223	12-Bit, 80Msps, 3.3V ADC, High IF Sampling	366mW, 68.5dB SNR, 84dB SFDR, 48-Pin QFN
LTC2224	12-Bit, 135Msps, 3.3V ADC, High IF Sampling	630mW, 67.6dB SNR, 84dB SFDR, 48-Pin QFN
LTC2232	10-Bit, 105Msps, 3.3V ADC, High IF Sampling	475mW, 61.3dB SNR, 78dB SFDR, 48-Pin QFN
LTC2233	10-Bit, 80Msps, 3.3V ADC, High IF Sampling	366mW, 61.3dB SNR, 78dB SFDR, 48-Pin QFN
LTC2234	10-Bit, 135Msps, 3.3V ADC, High IF Sampling	630mW, 61.2dB SNR, 78dB SFDR, 48-Pin QFN
LTC2255	14-Bit, 125Msps, 3V ADC, Lowest Power	395mW, 72.5dB SNR, 88dB SFDR, 32-Pin QFN
LTC2284	14-Bit, Dual, 105Msps, 3V ADC, Low Crosstalk	540mW, 72.4dB SNR, 88dB SFDR, 64-Pin QFN
LT5512	DC-3GHz High Signal Level Downconverting Mixer	DC to 3GHz, 21dBm IIP3, Integrated LO Buffer
LT5514	Ultralow Distortion IF Amplifier/ADC Driver with Digitally Controlled Gain	450MHz to 1dB BW, 47dB OIP3, Digital Gain Control 10.5dB to 33dB in 1.5dB/Step
LT5515	1.5GHz to 2.5GHz Direct Conversion Quadrature Demodulator	High IIP3: 20dBm at 1.9GHz, Integrated LO Quadrature Generator
LT5516	800MHz to 1.5GHz Direct Conversion Quadrature Demodulator	High IIP3: 21.5dBm at 900MHz, Integrated LO Quadrature Generator
LT5517	40MHz to 900MHz Direct Conversion Quadrature Demodulator	High IIP3: 21dBm at 800MHz, Integrated LO Quadrature Generator
LT5522	600MHz to 2.7GHz High Linearity Downconverting Mixer	4.5V to 5.25V Supply, 25dBm IIP3 at 900MHz. NF = 12.5dB, 50Ω Single-Ended RF and LO Ports