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1 Overview

Features

- Integrated high current H-Bridge
- Path resistance of max. 295 mΩ @ 150 °C (typ. 150 mΩ @ 25 °C)
- Low quiescent current of typ. 5μA @ 25 °C
- PWM capability of up to 25kHz combined with active freewheeling
- Current limitation level of 12 A typ. (8 A min.)
- Driver circuit with logic inputs
- Status flag diagnosis with current sense capability
- Overtemperature shut down with latch behaviour
- Overvoltage lock out
- Undervoltage shut down
- Switch-mode current limitation for reduced power dissipation in overcurrent situation
- Integrated dead time generation
- Operation up to 28V
- Green Product (RoHS compliant)
- AEC Qualified



PG-DSO-36-29

Description

The BTM7752G is a fully integrated high current H-bridge for motor drive applications. It contains two p-channel highside MOSFETs and two n-channel lowside MOSFETs with an integrated driver IC in one package. Due to the p-channel highside switches the need for a charge pump is eliminated thus minimizing EMI. Interfacing to a microcontroller is made easy by the integrated driver IC which features logic level inputs, diagnosis with current sense, dead time generation and protection against overtemperature, overvoltage, undervoltage, overcurrent and short circuit.

The BTM7752G provides an optimized solution for protected high current PWM motor drives with very low board space consumption.

Type	Package	Marking
BTM7752G	PG-DSO-36-29	BTM7752G

2 Block Diagram

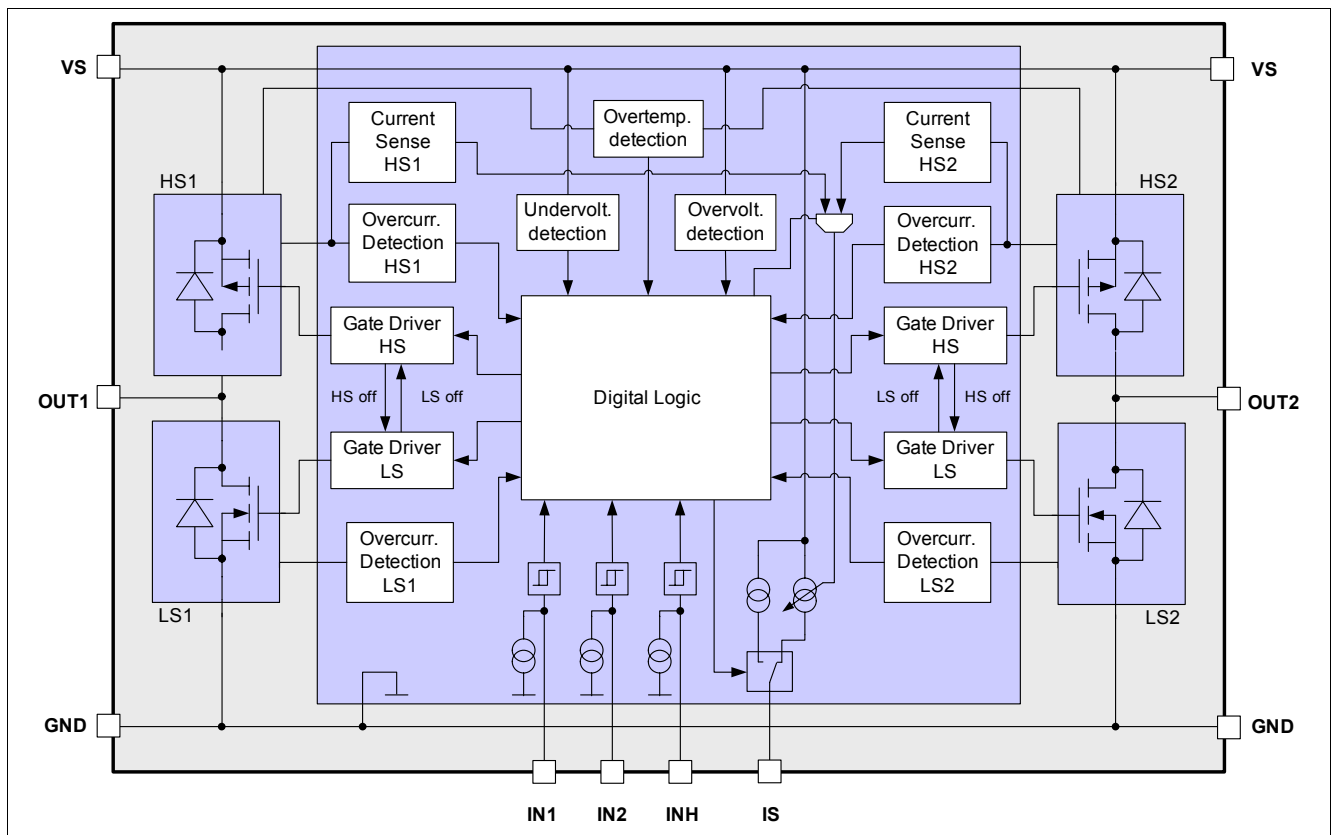


Figure 1 Block Diagram

3 Terms

following figure shows the terms used in this data sheet.

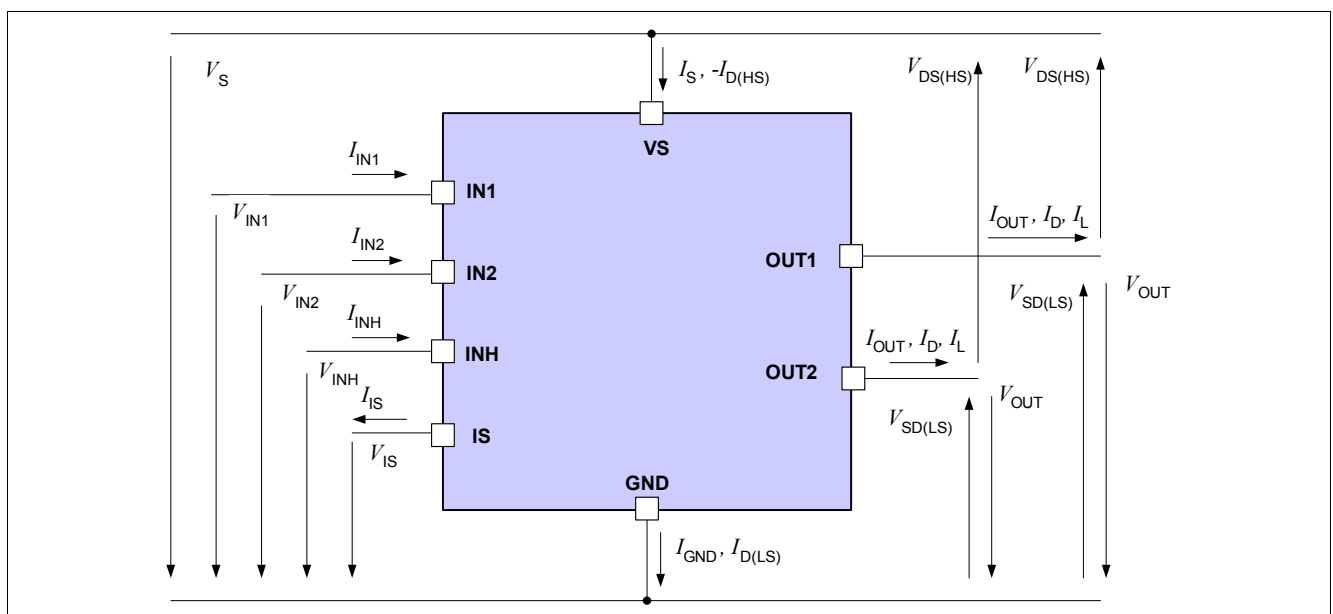


Figure 2 Terms

4 Pin Configuration

4.1 Pin Assignment

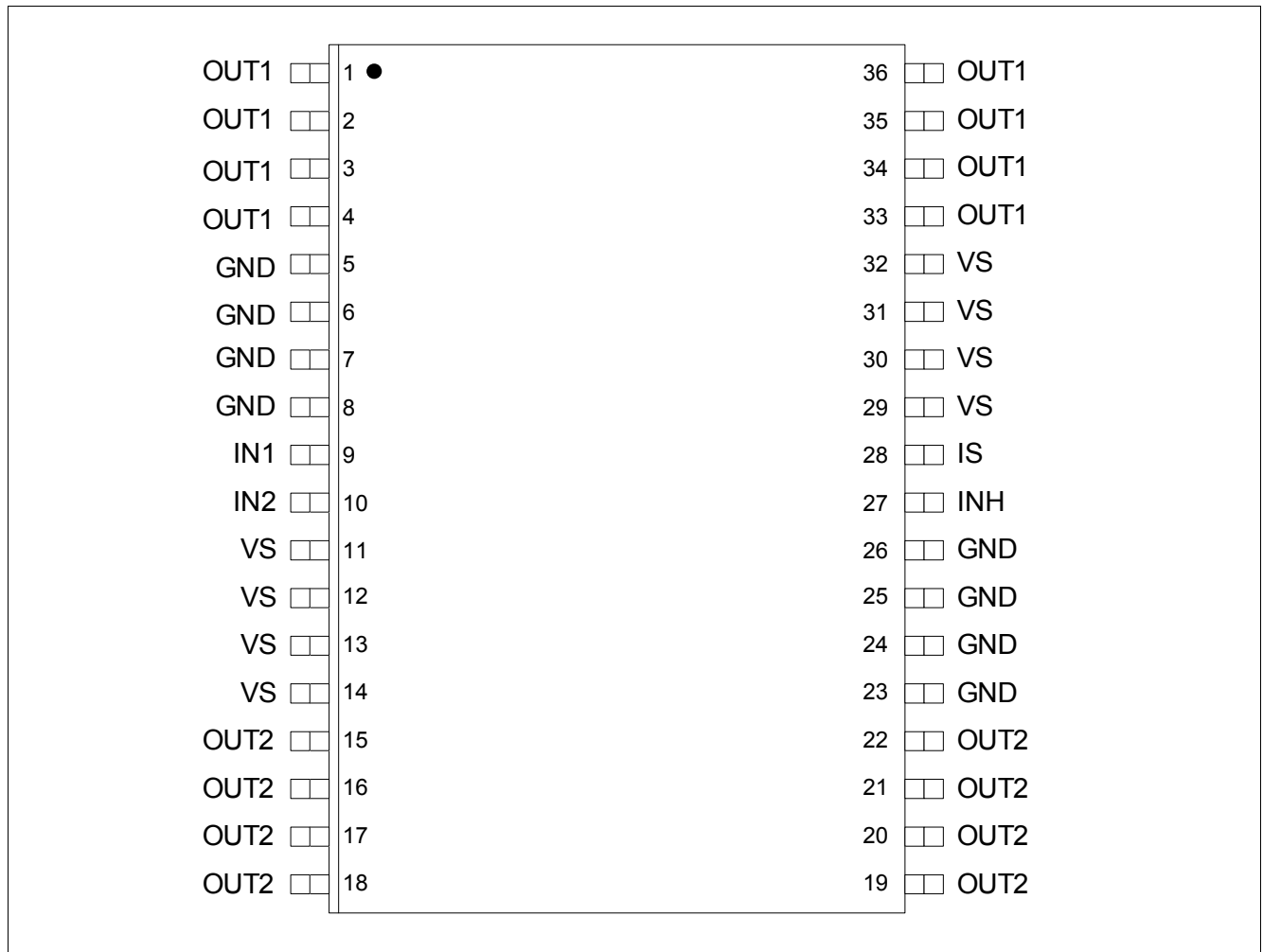


Figure 3 Pin Configuration BTM7752G

4.2 Pin Definitions and Functions

Pins written in bold type need power wiring.

Pin	Symbol	Function
1..4, 33..36	OUT1	Output of first half bridge
5..8, 23..26	GND	Ground
9	IN1	Input of first half bridge
10	IN2	Input of second half bridge
11..14, 29..32	VS	Supply, all pins to be connected and shorted externally
15..22	OUT2	Output of second half bridge
27	INH	Inhibit pin, to set device in sleep/stand-by mode
28	IS	Current sense and error signal

5 General Product Characteristics

5.1 Absolute Maximum Ratings

Absolute Maximum Ratings ¹⁾

$T_j = -40\text{ °C to }+150\text{ °C}$; all voltages with respect to ground (unless otherwise specified)

Pos.	Parameter	Symbol	Limit Values		Unit	Conditions
			Min.	Max.		
5.1.1	Supply voltage	V_S	-0.3	45	V	–
5.1.2	Logic Input Voltage	$V_{IN1}, V_{IN2}, V_{INH}$	-0.3	5.5	V	–
5.1.3	HS/LS continuous drain current	$I_{D(HS)}, I_{D(LS)}$	-4	4	A	$T_C < 85\text{ °C}$ switch active
5.1.4	Voltage between VS and IS pin	$V_S - V_{IS}$	-0.3	45	V	–

Thermal Maximum Ratings

5.1.5	Junction temperature	T_j	-40	150	°C	–
5.1.6	Storage temperature	T_{stg}	-55	150	°C	–

ESD Susceptibility

5.1.7	ESD susceptibility	V_{ESD}			kV	HBM ²⁾
	IN1, IN2, IS, INH		-2	2		
	OUT1, OUT2, GND, VS		-4	4		

1) Not subject to production test, specified by design.

2) HBM according to EIA/JESD 22-A 114B (1.5 kΩ, 100pF)

Note: Stresses above the ones listed here may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: Integrated protection functions are designed to prevent IC destruction under fault conditions described in the data sheet. Fault conditions are considered as "outside" normal operating range. Protection functions are not designed for continuous repetitive operation.

Maximum Single Pulse Current

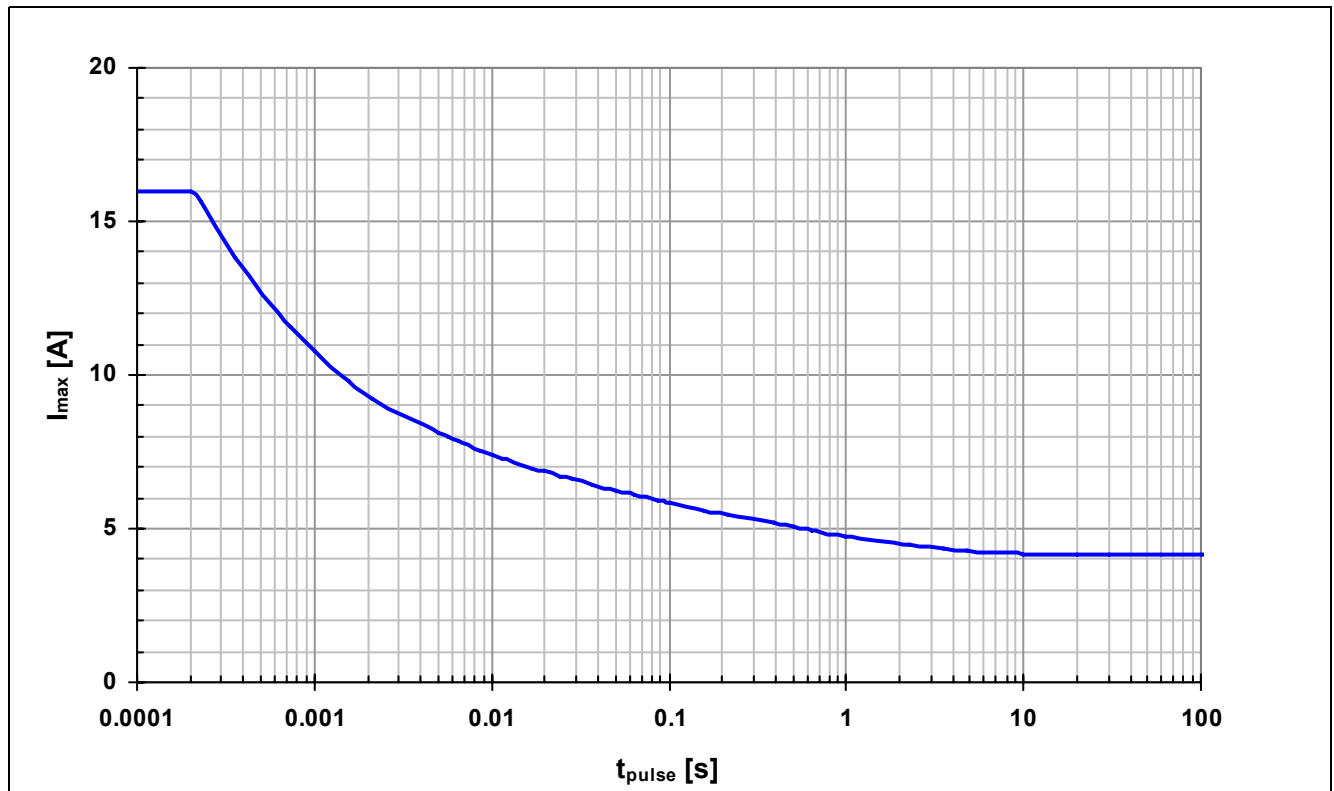


Figure 4 BTM7752G Maximum Single Pulse Current ($T_C = T_{j(0)} < 85^\circ\text{C}$)

This diagram shows the maximum single pulse current that can be driven for a given pulse time t_{pulse} . The maximum reachable current may be smaller depending on the current limitation level. Pulse time may be limited due to thermal protection of the device.

5.2 Functional Range

Pos.	Parameter	Symbol	Limit Values		Unit	Conditions
			Min.	Max.		
5.2.1	Supply Voltage Range for Normal Operation	$V_{S(\text{nor})}$	8	18	V	VS pins shorted
5.2.2	Extended Supply Voltage Range for Operation	$V_{S(\text{ext})}$	5.5	28	V	VS pins shorted; Parameter deviations possible; 1)
5.2.3	Junction Temperature	T_j	-40	150	$^\circ\text{C}$	–

1) Overtemperature protection available up to supply voltage $V_S = 18\text{V}$.

Note: Within the functional range the IC operates as described in the circuit description. The electrical characteristics are specified within the conditions given in the related electrical characteristics table.

5.3 Thermal Resistance

Note: This thermal data was generated in accordance with JEDEC JESD51 standards. For more information, go to www.jedec.org.

Pos.	Parameter	Symbol	Limit Values			Unit	Conditions
			Min.	Typ.	Max.		
5.3.1	Thermal Resistance Junction to Soldering Point, Low Side Switch $R_{thjSP(LS)} = \Delta T_{j(LS)} / P_{v(LS)}$	$R_{thjSP(LS)}$	—	—	29	K/W	1)
5.3.2	Thermal Resistance Junction to Soldering Point, High Side Switch $R_{thjSP(HS)} = \Delta T_{j(HS)} / P_{v(HS)}$	$R_{thjSP(HS)}$	—	—	29	K/W	1)
5.3.3	Thermal Resistance Junction to Soldering Point, both switches $R_{thjSP} = \max[\Delta T_{j(HS)}, \Delta T_{j(LS)}] / (P_{v(HS)} + P_{v(LS)})$	R_{thjSP}	—	—	29	K/W	1)
5.3.4	Thermal Resistance Junction-Ambient	R_{thja}	—	46	—	K/W	1), 2)

1) Not subject to production test, specified by design.

2) Specified R_{thja} value is according to Jedec JESD51-2, -7 at natural convection on FR4 2s2p board; The product (chip+package) was simulated on a 76.2 x 114.3 x 1.5 mm board with 2 inner copper layers (2 x 70µm Cu, 2 x 35µm Cu).

Transient thermal impedance Z_{thja}

Figure 5 is showing the typical transient thermal impedance of high side or low side switch of BTM7752G mounted according to JEDEC JESD51-7 at natural convection on FR4 2s2p board. The device (chip+package) was simulated on a 76.2 x 114.3 x 1.5 mm board with 2 inner copper layers (2 x 70µm Cu, 2 x 35µm Cu). For the simulation each chip was separately powered with 1W at an ambient temperature T_a of 85°C.

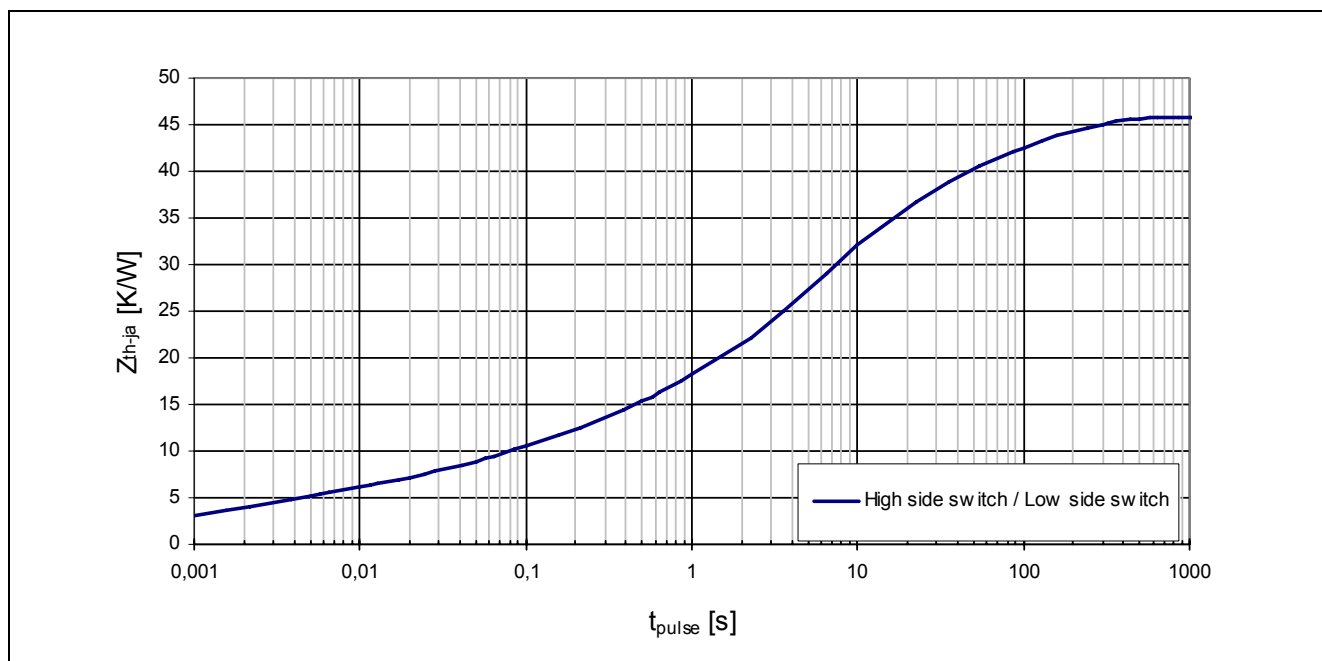


Figure 5 Typical transient thermal impedance of BTM7752G on JESD51-7 2s2p board (1W each chip (separately heated), $T_a = 85^\circ\text{C}$, single pulse)

6 Block Description and Characteristics

6.1 Supply Characteristics

$V_S = 8\text{ V to }18\text{ V}$, $T_j = -40\text{ °C to }+150\text{ °C}$, $I_L = 0\text{ A}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Pos.	Parameter	Symbol	Limit Values			Unit	Test Conditions
			Min.	Typ.	Max.		
General							
6.1.1	Supply Current	$I_{S(on)}$	–	5	9.5	mA	V_{INH} or V_{IN1} or V_{IN2} = 5 V DC-mode normal operation (no fault condition)
6.1.2	Quiescent Current	$I_{S(off)}$	–	5	15	μA	$V_{INH} = V_{IN1} = V_{IN2} = 0$ V $T_j < 85$ °C; ¹⁾
			–	–	30	μA	$V_{INH} = V_{IN1} = V_{IN2} = 0$ V

1) Not subject to production test, specified by design.

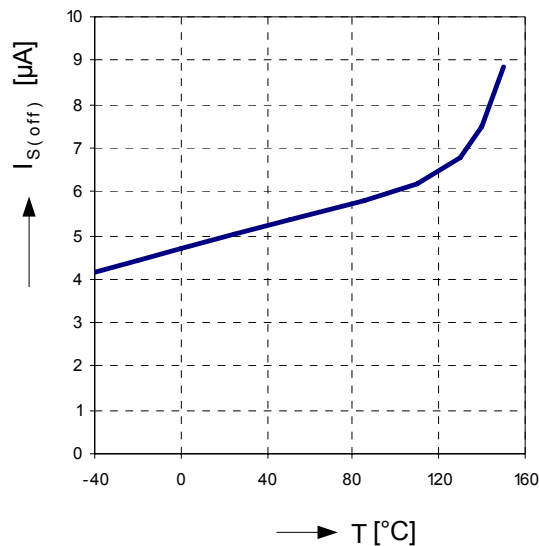


Figure 6 Typical Quiescent Current vs. Junction Temperature (typ. @ $V_S = 13.5\text{ V}$)

6.2 Power Stages

The power stages of the BTM7752G consist of p-channel vertical DMOS transistors for the high side switches and n-channel vertical DMOS transistors for the low side switches. All protection and diagnostic functions are located in a separate control chip. Both switches, high side and low side, allow active freewheeling and thus minimize power dissipation in the forward operation of the integrated diodes.

The on state resistance R_{ON} is dependent on the supply voltage V_S as well as on the junction temperature T_j . The typical on state resistance characteristics are shown in **Figure 7**.

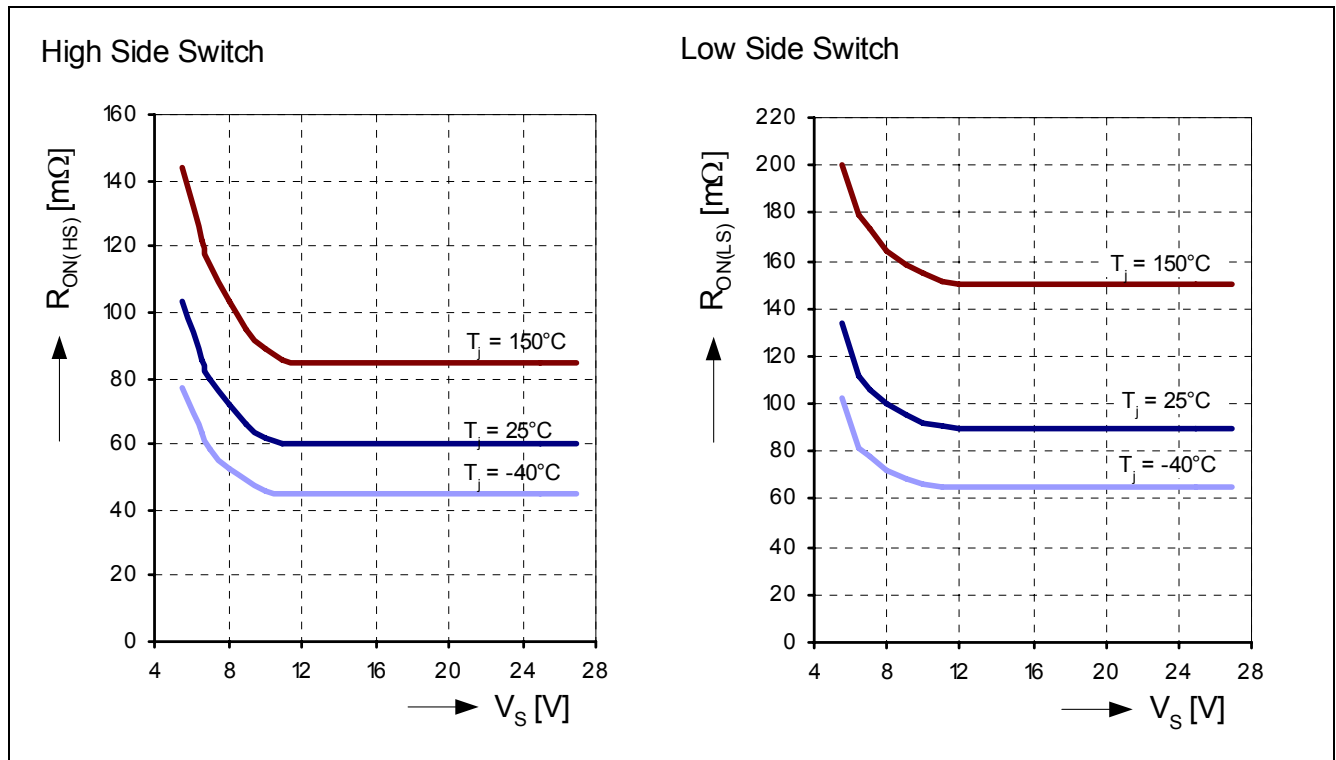


Figure 7 Typical On State Resistance vs. Supply Voltage

6.2.1 Power Stages - Static Characteristics

$V_S = 8\text{ V to }18\text{ V}$, $T_j = -40\text{ °C to }+150\text{ °C}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Pos.	Parameter	Symbol	Limit Values			Unit	Test Conditions
			Min.	Typ.	Max.		

High Side Switch - Static Characteristics

6.2.1	On state high side resistance	$R_{ON(HS)}$	— —	60 85	— 115	mΩ	$I_{OUT} = 1\text{ A}$ $V_S = 13.5\text{ V}$ $T_j = 25\text{ °C}; ^{1)}$ $T_j = 150\text{ °C}$
6.2.2	Leakage current high side	$I_{L(LKHS)}$	— —	— —	1 5	μA	$V_{INH} = V_{IN1} = V_{IN2} = 0\text{ V}$ $V_{OUT} = 0\text{ V}$ $T_j < 85\text{ °C}; ^{1)}$ $T_j = 150\text{ °C}$
6.2.3	Reverse diode forward-voltage high side ²⁾	$V_{DS(HS)}$	— — —	0.9 0.8 0.6	— — 0.8	V	$I_{OUT} = -1\text{ A}$ $T_j = -40\text{ °C}; ^{1)}$ $T_j = 25\text{ °C}; ^{1)}$ $T_j = 150\text{ °C}$

Low Side Switch - Static Characteristics

6.2.4	On state low side resistance	$R_{ON(LS)}$	— —	90 150	— 180	mΩ	$I_{OUT} = -1\text{ A}$ $V_S = 13.5\text{ V}$ $T_j = 25\text{ °C}; ^{1)}$ $T_j = 150\text{ °C}$
6.2.5	Leakage current low side	$-I_{L(LKLS)}$	— —	— —	1 3	μA	$V_{INH} = V_{IN1} = V_{IN2} = 0\text{ V}$ $V_{OUT} = V_S$ $T_j < 85\text{ °C}; ^{1)}$ $T_j = 150\text{ °C}$
6.2.6	Reverse diode forward-voltage low side ²⁾	$V_{SD(LS)}$	— — —	0.9 0.8 0.6	— — 0.8	V	$I_{OUT} = 1\text{ A}$ $T_j = -40\text{ °C}; ^{1)}$ $T_j = 25\text{ °C}; ^{1)}$ $T_j = 150\text{ °C}$

1) Not subject to production test, specified by design.

2) Due to active freewheeling diode is conducting only for a few μs.

6.2.2 Switching Times

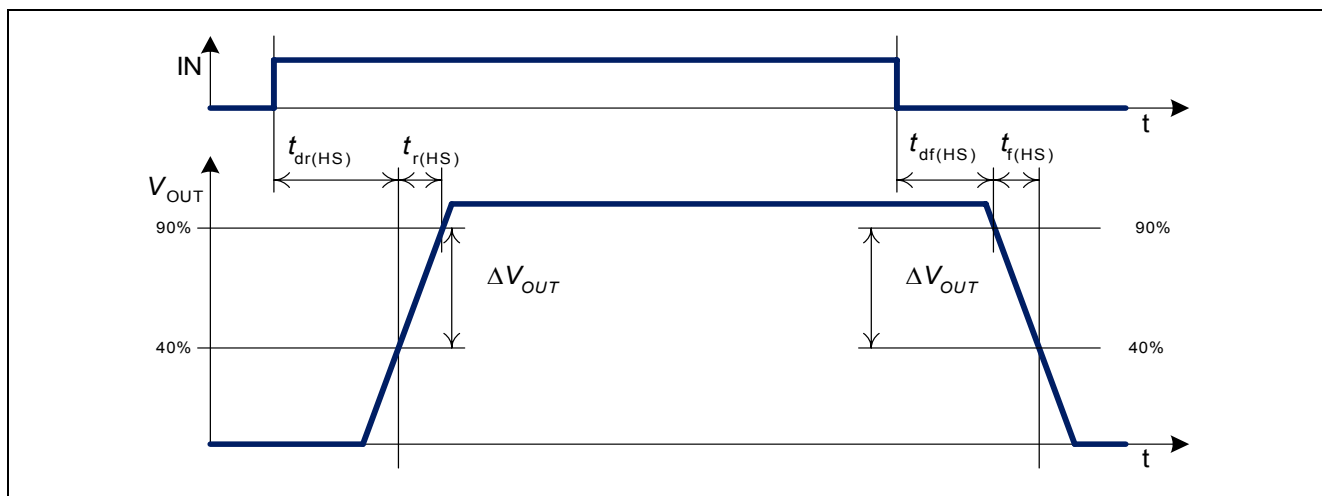


Figure 8 Definition of switching times high side (R_{load} to GND)

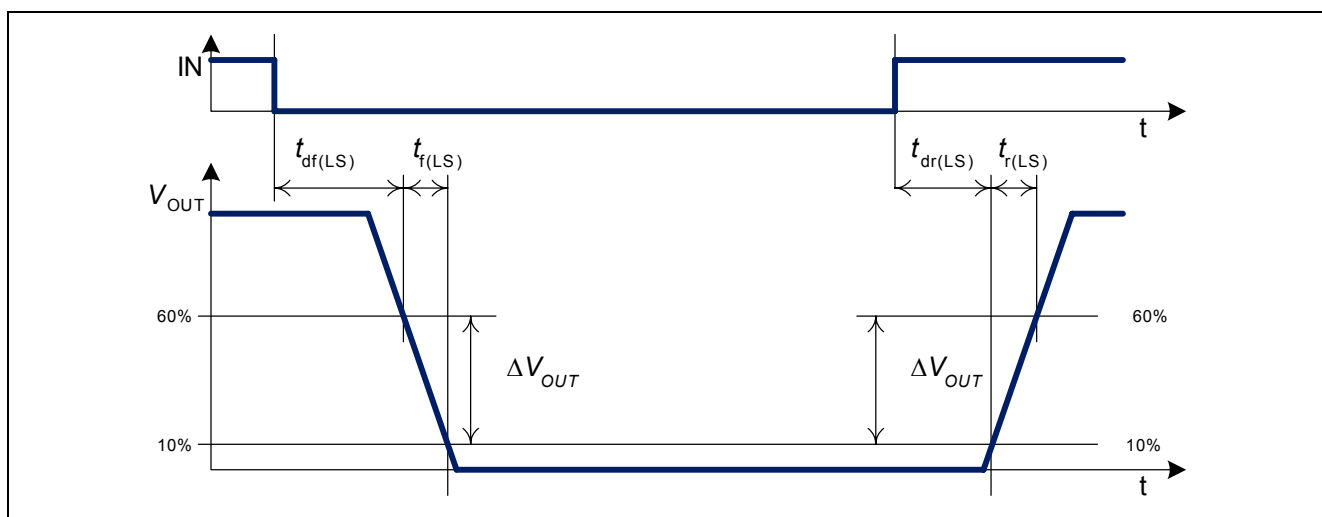


Figure 9 Definition of switching times low side (R_{load} to VS)

Due to the timing differences for the rising and the falling edge there will be a slight difference between the length of the input pulse and the length of the output pulse. It can be calculated using the following formulas:

- $\Delta t_{HS} = (t_{dr(HS)} + 0.2 t_{r(HS)}) - (t_{df(HS)} + 0.8 t_{f(HS)})$
- $\Delta t_{LS} = (t_{df(LS)} + 0.2 t_{f(LS)}) - (t_{dr(LS)} + 0.8 t_{r(LS)})$

6.2.3 Power Stages - Dynamic Characteristics

$V_S = 13.5V$, $T_j = -40\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$, $R_{Load} = 12\text{ }\Omega$, $V_{INH} = 5V$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Pos.	Parameter	Symbol	Limit Values			Unit	Test Conditions
			Min.	Typ.	Max.		
High Side Switch Dynamic Characteristics							
6.2.7	Rise-time of HS	$t_{r(HS)}$	0.35	0.7	1.05	μs	—
6.2.8	Slew rate HS on	$\Delta V_{OUT}/t_{r(HS)}$	—	9.6	—	$\text{V}/\mu\text{s}$	—
6.2.9	Switch on delay time HS	$t_{dr(HS)}$	3	5	8	μs	—
6.2.10	Fall-time of HS	$t_{f(HS)}$	0.35	0.7	1.05	μs	—
6.2.11	Slew rate HS off	$-\Delta V_{OUT}/t_{f(HS)}$	—	9.6	—	$\text{V}/\mu\text{s}$	—
6.2.12	Switch off delay time HS	$t_{df(HS)}$	1.5	3.5	5.5	μs	—
Low Side Switch Dynamic Characteristics							
6.2.13	Rise-time of LS	$t_{r(LS)}$	0.4	0.8	1.2	μs	—
6.2.14	Slew rate LS off	$\Delta V_{OUT}/t_{r(LS)}$	—	8.4	—	$\text{V}/\mu\text{s}$	—
6.2.15	Switch off delay time LS	$t_{dr(LS)}$	1.5	3.5	5.5	μs	—
6.2.16	Fall-time of LS	$t_{f(LS)}$	0.35	0.8	1.2	μs	—
6.2.17	Slew rate LS on	$-\Delta V_{OUT}/t_{f(LS)}$	—	8.4	—	$\text{V}/\mu\text{s}$	—
6.2.18	Switch on delay time LS	$t_{df(LS)}$	2.5	5	7.5	μs	—

6.3 Protection Functions

The device provides integrated protection functions. These are designed to prevent IC destruction under fault conditions described in the data sheet. Fault conditions are considered as “outside” normal operating range. Protection functions are not to be used for continuous or repetitive operation, with the exception of the current limitation ([Chapter 6.3.4](#)). Overvoltage, overtemperature and overcurrent are indicated by a fault current $I_{IS(LIM)}$ at the IS pin as described in the paragraph [“Status Flag Diagnosis with Current Sense Capability” on Page 17](#) and [Figure 13](#).

In the following the protection functions are listed in order of their priority. Overvoltage lock out overrides all other error modes.

6.3.1 Overvoltage Lock Out

To assure a high immunity against overvoltages (e.g. load dump conditions) the device shuts both lowside MOSFETs off and turns both highside MOSFET on, if the supply voltage V_S is exceeding the over voltage protection level $V_{OV(OFF)}$. The IC operates in normal mode again with a hysteresis $V_{OV(HY)}$ if the supply voltage decreases below the switch-on voltage $V_{OV(ON)}$. This behavior of the BTM7752G will lead to freewheeling in highside during over voltage.

6.3.2 Undervoltage Shut Down

To avoid uncontrolled motion of the driven motor at low voltages the device shuts off (both outputs are tri-state), if the supply voltage V_S drops below the switch-off voltage $V_{UV(OFF)}$. In this case all latches will be reset. The IC becomes active again with a hysteresis $V_{UV(HY)}$ if the supply voltage rises above the switch-on voltage $V_{UV(ON)}$.

6.3.3 Overtemperature Protection

The BTM7752G is protected against overtemperature by integrated temperature sensors. Each half bridge, which consists of one high side and one low side switch, is protected by one temperature sensor located in the high side switch. Both temperature sensors function independently. A detection of overtemperature through temperature sensor leads to a shut down of both switches in the half bridge. This state is latched until the device is reset by a low signal with a minimum length of t_{reset} simultaneously at the INH pin and both IN pins, provided that its temperature has decreased at least the thermal hysteresis ΔT in the meantime.

Overtemperature protection is available up to supply voltage $V_S = 18V$.

For sufficient over temperature protection please consider also operation below the limitations outlined in **Figure 4** and **Figure 5**.

Repetitive use of the overtemperature protection might reduce lifetime.

6.3.4 Current Limitation

The current in the bridge is measured in all four switches. As soon as the current in forward direction in one switch is reaching the limit I_{CLX} , this switch is deactivated for t_{CLS} . In case of INH = 5V (high) the other switch of the same half bridge is activated for the same time (t_{CLS}). During that time all changes at the related IN pin are ignored. However, the INH pin can still be used to switch all MOSFETs off. After t_{CLS} the switches return to their initial setting. The error signal at the IS pin is reset after $1.5 * t_{CLS}$ if no overcurrent state is detected in the meantime. Unintentional triggering of the current limitation by short current spikes (e.g. inflicted by EMI coming from the motor) is suppressed by internal filter circuitry. Due to thresholds and reaction delay times of the filter circuitry the effective current limitation level I_{CLX} depends on the slew rate of the load current di/dt as shown in **Figure 11**.

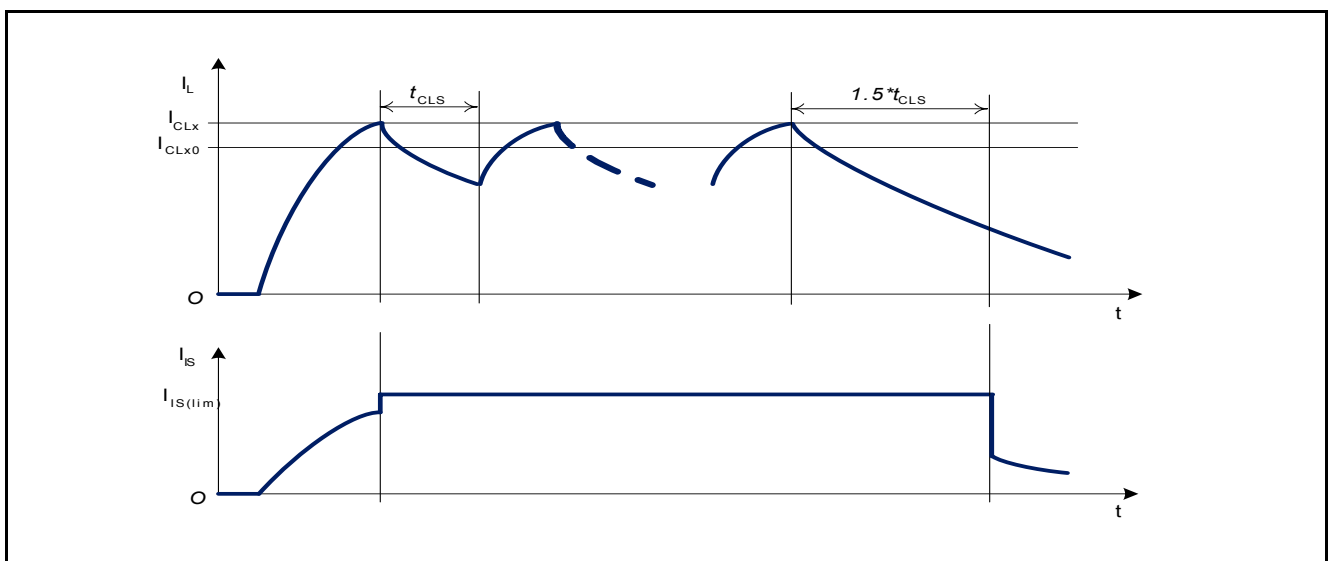


Figure 10 Timing Diagram Current Limitation and Current Sense

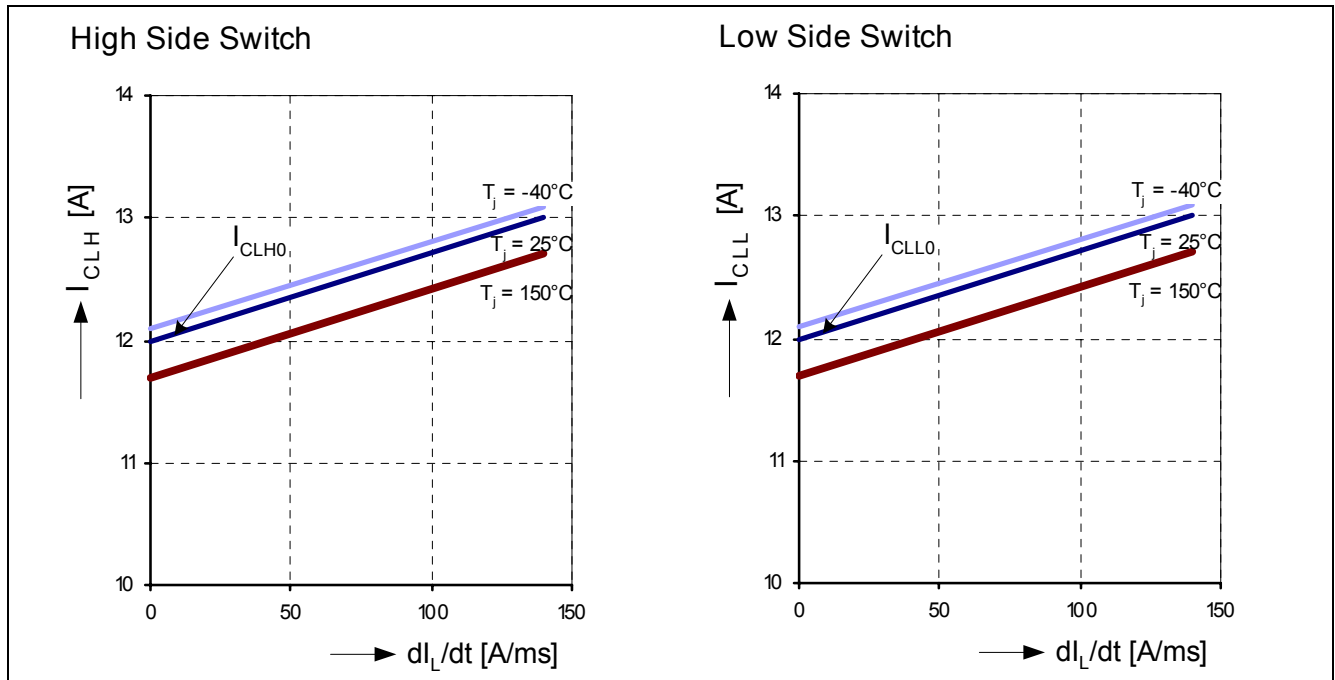


Figure 11 Current Limitation Level vs. Current Slew Rate dI_L/dt

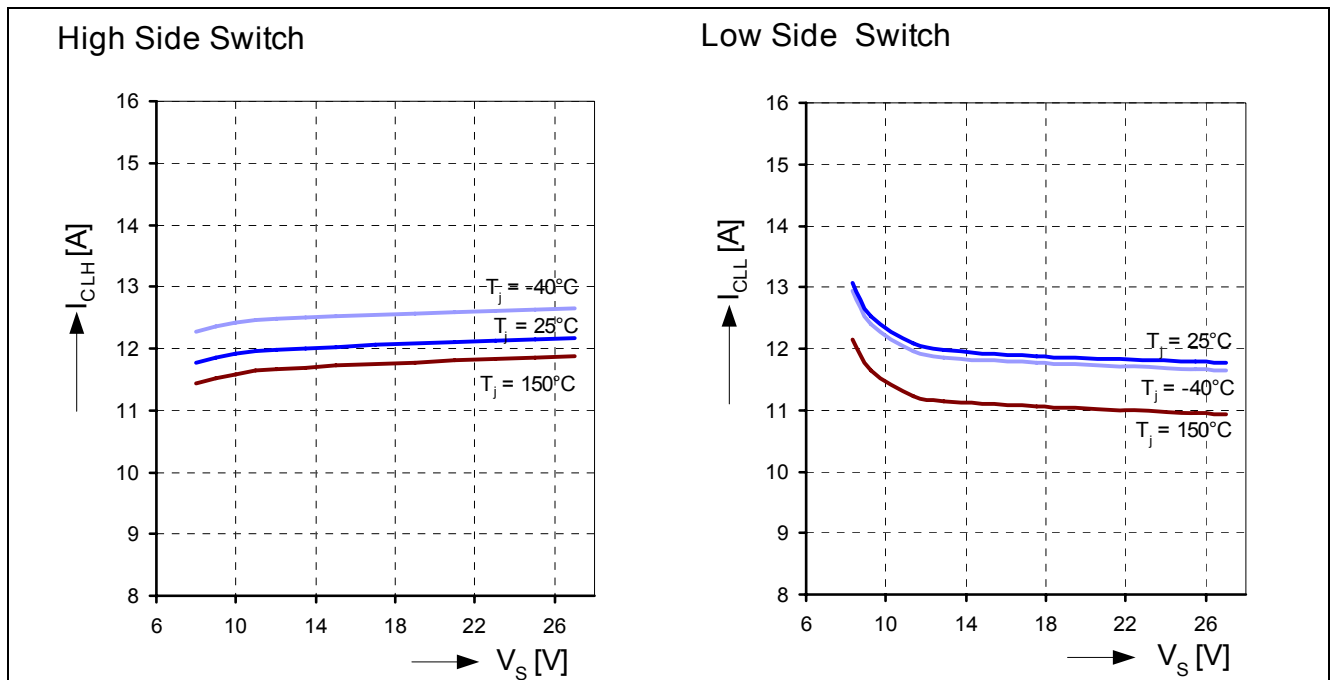


Figure 12 Typical Current Limitation Detection Levels vs. Supply Voltage

In combination with a typical inductive load, such as a motor, this results in a switched mode current limitation. This method of limiting the current has the advantage that the power dissipation in the BTM7752G is much smaller than by driving the MOSFETs in linear mode. Therefore it is possible to use the current limitation for a short time without exceeding the maximum allowed junction temperature (e.g. for limiting the inrush current during motor start up). However, the regular use of the current limitation is allowed as long as the specified maximum junction temperature is not exceeded. Exceeding this temperature can reduce the lifetime of the device.

6.3.5 Short Circuit Protection

The device provides embedded protection functions against

- output short circuit to ground
- output short circuit to supply voltage
- short circuit of load

The short circuit protection is realized by the previously described current limitation in combination with the over-temperature shut down (see [Chapter 6.3.3](#)) of the device.

6.3.6 Electrical Characteristics - Protection Functions

$V_S = 8\text{ V to }18\text{ V}$, $T_j = -40\text{ °C to }+150\text{ °C}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Pos.	Parameter	Symbol	Limit Values			Unit	Test Conditions
			Min.	Typ.	Max.		
Over Voltage Lock Out							
6.3.1	Switch-ON voltage	$V_{OV(ON)}$	27.8	–	–	V	V_s decreasing
6.3.2	Switch-OFF voltage	$V_{OV(OFF)}$	28	–	30	V	V_s increasing
6.3.3	ON/OFF hysteresis	$V_{OV(HY)}$	–	0.2	–	V	¹⁾
Under Voltage Shut Down							
6.3.4	Switch-ON voltage	$V_{UV(ON)}$	–	–	5.5	V	V_s increasing
6.3.5	Switch-OFF voltage	$V_{UV(OFF)}$	4.0	–	5.4	V	V_s decreasing
6.3.6	ON/OFF hysteresis	$V_{UV(HY)}$	–	0.2	–	V	¹⁾
Thermal Shut Down							
6.3.7	Thermal shut down junction temperature	T_{jSD}	155	175	200	°C	¹⁾ ; $V_s \leq 18\text{ V}$
6.3.8	Thermal switch on junction temperature	T_{jSO}	153	–	190	°C	¹⁾
6.3.9	Thermal hysteresis	ΔT	–	7	–	°C	¹⁾
6.3.10	Reset pulse at INH and IN pin (INH, IN1 and IN2 low)	t_{reset}	8	–	–	μs	¹⁾
Current Limitation							
6.3.11	Current limitation detection level high side	I_{CLH0}	8	12	16	A	$V_s = 13.5\text{ V}$
6.3.12	Current limitation detection level low side	I_{CLL0}	8	12	16	A	$V_s = 13.5\text{ V}$
6.3.13	Shut off time for HS and LS	t_{CLS}	50	100	200	μs	$V_s = 13.5\text{ V}$, $T_j = 25\text{ °C}$

¹⁾ Not subject to production test, specified by design.

6.4 Control and Diagnostics

6.4.1 Input Circuit

The control inputs INx and INH consist of TTL/CMOS compatible schmitt triggers with hysteresis which control the integrated gate drivers for the MOSFETs. To set the device in stand-by mode, INH and INx pins need to be all connected to GND. When the INH is high, in each half bridge one of the two power switches (HSx or LSx) is switched on, while the other power switch is switched off, depending on the status of the INx pin. When INH is low, a high INx signal will turn the corresponding highside switches on. This provides customer the possibility to switch on one high side switch while keeping the other switches off and therefore to do an open load detection together with external circuitry (see also [Chapter 7](#) - Application Information). A low on all INx and INH signal will turn off both power switches. To drive the logic inputs no external driver is needed, therefore the BTM7752G can be interfaced directly to a microcontroller.

6.4.2 Dead Time Generation

In bridge applications it has to be assured that the highside and lowside MOSFET are not conducting at the same time, connecting directly the battery voltage to GND. This is assured by a circuit in the driver IC, which senses the status of the MOSFETs to ensure that the high or low side switch can be switched on only if the corresponding low or high side switch is completely turned off.

6.4.3 Status Flag Diagnosis with Current Sense Capability

The status pin IS is used as a combined current sense and error flag output. In normal operation (current sense mode), a current source is connected to the status pin, which delivers a current proportional to the forward load current flowing through the active high side switch. If the high side switch is inactive or the current is flowing in the reverse direction no current will be driven except for a marginal leakage current $I_{IS(LK)}$. If both high side switches are in on state, the IS provides the sense current of the high side switch, which has been turned on first. To reset this assignment both inputs IN1 and IN2 has to be set to low and both high side switches has to be off.

The external resistor R_{IS} determines the voltage per output current. E.g. with the nominal value of **3.1k** for the current sense ratio $k_{ILIS} = I_L / I_{IS}$, a resistor value of $R_{IS} = 1k\Omega$ leads to $V_{IS} = (I_L / 3.1A)V$. In case of a fault condition the status output is connected to a current source which is independent of the load current and provides $I_{IS(lim)}$. The maximum voltage at the IS pin is determined by the choice of the external resistor and the supply voltage. In case of current limitation the $I_{IS(lim)}$ is activated for $1.5 \cdot t_{CLS}$.

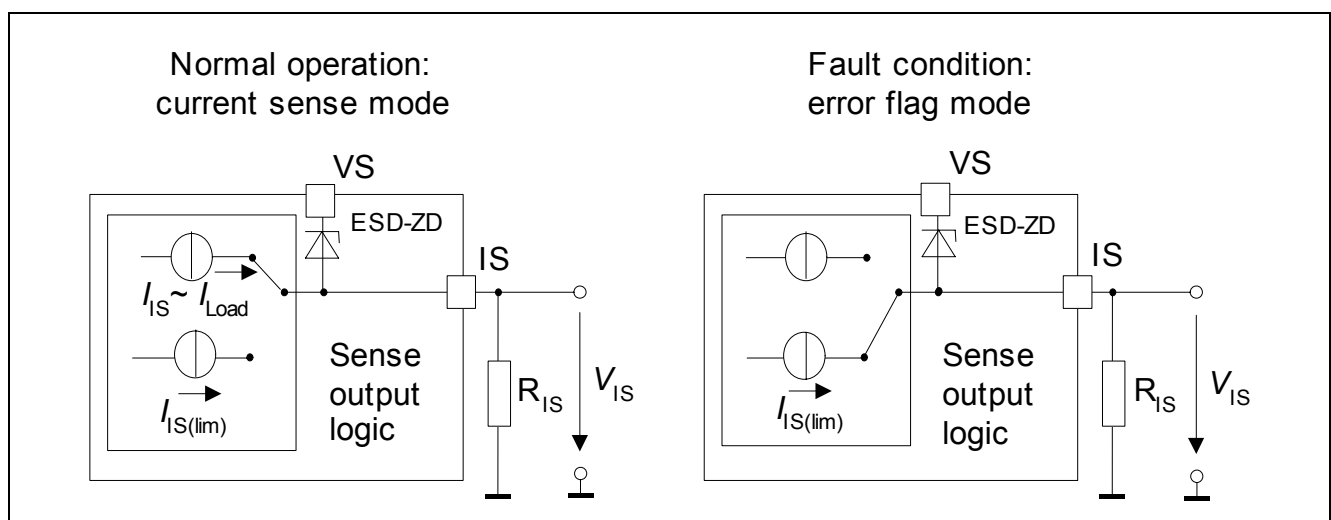


Figure 13 Sense current and fault current

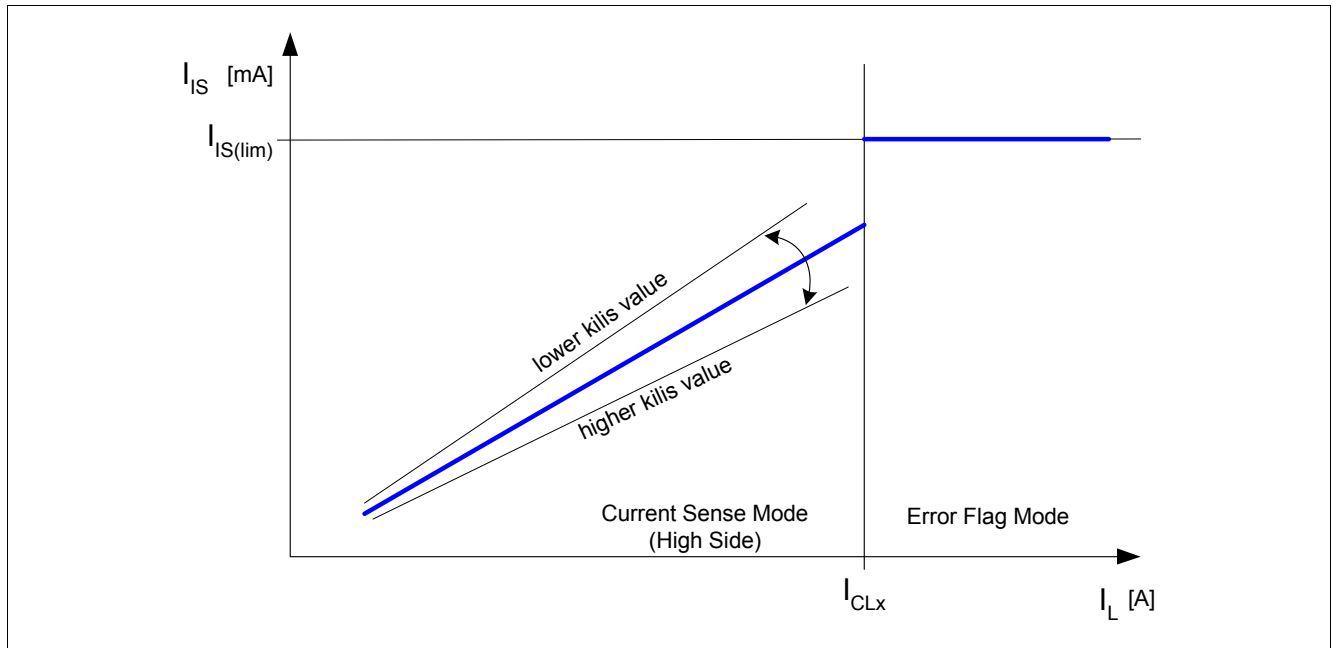


Figure 14 Sense Current vs. Load Current

6.4.4 Truth Table

Device State	Inputs			Outputs					Mode
	INH	IN1	IN2	HS1	LS1	HS2	LS2	IS	
Normal operation	0	0	0	OFF	OFF	OFF	OFF	0	Stand-by mode, reset
	1	0	0	OFF	ON	OFF	ON	0	–
	1	0	1	OFF	ON	ON	OFF	CS HS2 ¹⁾	–
	1	1	0	ON	OFF	OFF	ON	CS HS1 ¹⁾	–
	1	1	1	ON	OFF	ON	OFF	CS ²⁾	–
Open-Load detection mode	0	0	1	OFF	OFF	ON	OFF	CS HS2 ¹⁾	Enable Open-load detection
	0	1	0	ON	OFF	OFF	OFF	CS HS1 ¹⁾	Enable Open-load detection
	0	1	1	ON	OFF	ON	OFF	CS ²⁾	
Over-voltage (OV)	X	X	X	ON	OFF	ON	OFF	1	Shut-down of LSS, HSS activated, error detected
Under-voltage (UV)	X	X	X	OFF	OFF	OFF	OFF	0	UV lockout, reset
Overtemperature or short circuit of HSS or LSS ³⁾	0	0	0	OFF	OFF	OFF	OFF	0	Stand-by mode, reset of latch
	1	X	X	OFF	OFF	OFF	OFF	1	Shut-down with latch, error detected
	X	1	X						
	X	X	1						
Current limitation mode half bridge 1	1	0	X	ON	OFF	X	X	1	Short Circuit in LS1 detected, half bridge 2 operates in normal mode
	1	1	X	OFF	ON	X	X	1	Short Circuit in HS1 detected, half bridge 2 operates in normal mode
	0	1	X	OFF	OFF	X	X	1	Short Circuit in HS1 detected
Current limitation mode half bridge 2	1	X	0	X	X	ON	OFF	1	Short Circuit in LS2 detected, half bridge 1 operates in normal mode
	1	X	1	X	X	OFF	ON	1	Short Circuit in HS2 detected, half bridge 1 operates in normal mode
	0	X	1	X	X	OFF	OFF	1	Short Circuit in HS2 detected

- 1) Previous current sense assignment to be reset by IN1=IN2=low and both high side switches off (see [Chapter 6.4.3](#)).
- 2) When both high side switches are in on state, the CS provides the sense signal for the high side switch, which has been turned on first.
- 3) In short circuit of HSS or LSS, the junction temperature will arise and as soon as the over temperature shut down threshold is reached the device will shut down and latch the status. Short circuit of HSS and LSS itself won't be detected as failure.

Inputs:	Switches	Status Flag IS:
0 = Logic LOW	OFF = switched off	CS = Current sense mode
1 = Logic HIGH	ON = switched on	1 = Logic HIGH (error)
X = 0 or 1	X = switched on or off	

6.4.5 Electrical Characteristics - Control and Diagnostics

$V_S = 8\text{ V to }18\text{ V}$, $T_J = -40\text{ °C to }+150\text{ °C}$, VS pins shorted, all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

Pos.	Parameter	Symbol	Limit Values			Unit	Test Conditions
			Min.	Typ.	Max.		
Control Inputs (IN and INH)							
6.4.1	High level threshold voltage INH, IN1, IN2	$V_{\text{INH(H)}},$ $V_{\text{IN1(H)}}, V_{\text{IN2(H)}}$	—	1.6	2	V	—
6.4.2	Low level threshold voltage INH, IN1, IN2	$V_{\text{INH(L)}},$ $V_{\text{IN1(L)}}, V_{\text{IN2(L)}}$	1.1	1.4	—	V	—
6.4.3	Input voltage hysteresis	$V_{\text{INH(HY)}}, V_{\text{INHY}}$	—	200	—	mV	1)
6.4.4	Input current	$I_{\text{INH(H)}},$ $I_{\text{IN1(H)}}, I_{\text{IN2(H)}}$	—	30	200	μA	$V_{\text{IN1}}, V_{\text{IN2}}, V_{\text{INH}} = 5.5 \text{ V}$
6.4.5	Input current	$I_{\text{INH(L)}},$ $I_{\text{IN1(L)}}, I_{\text{IN2(L)}}$	—	25	125	μA	$V_{\text{IN1}}, V_{\text{IN2}}, V_{\text{INH}} = 0.4 \text{ V}$
Current Sense							
6.4.6	Current sense ratio in static on-condition $k_{\text{ILIS}} = I_{\text{L}} / I_{\text{IS}}$	k_{ILIS}	2 1.7 1.5	3.1 3.1 3.1	4.2 4.6 5	10^3	$R_{\text{IS}} = 1 \text{ k}\Omega$ $I_{\text{L}} = 6 \text{ A}$ $I_{\text{L}} = 2 \text{ A}$ $I_{\text{L}} = 1 \text{ A}$
6.4.7	Differential Current sense ratio in static on-condition $dk_{\text{ILIS}} = dI_{\text{L}} / dI_{\text{IS}}$	dk_{ILIS}	2	3.1	4.2	10^3	$R_{\text{IS}} = 1 \text{ k}\Omega$ $I_{\text{L}} > 0.5 \text{ A}$ 1)
6.4.8	Maximum analog sense current - Sense current in fault condition	$I_{\text{IS(lim)}}$	4.25	5	7	mA	$V_{\text{S}} = 13.5 \text{ V}$ $R_{\text{IS}} = 1 \text{ k}\Omega$
6.4.9	Isense leakage current	I_{ISL}	—	—	1	μA	$V_{\text{IN1}} = V_{\text{IN2}} = 0 \text{ V},$ no error detected
6.4.10	Isense leakage current, active high side switch	I_{ISH}	—	1	100	μA	V_{IN1} or $V_{\text{IN2}} = 5 \text{ V}$ $I_{\text{L}} = 0 \text{ A}$

¹⁾ Not subject to production test, specified by design.

7 Application Information

Note: The following information is given as a hint for the implementation of the device only and shall not be regarded as a description or warranty of a certain functionality, condition or quality of the device.

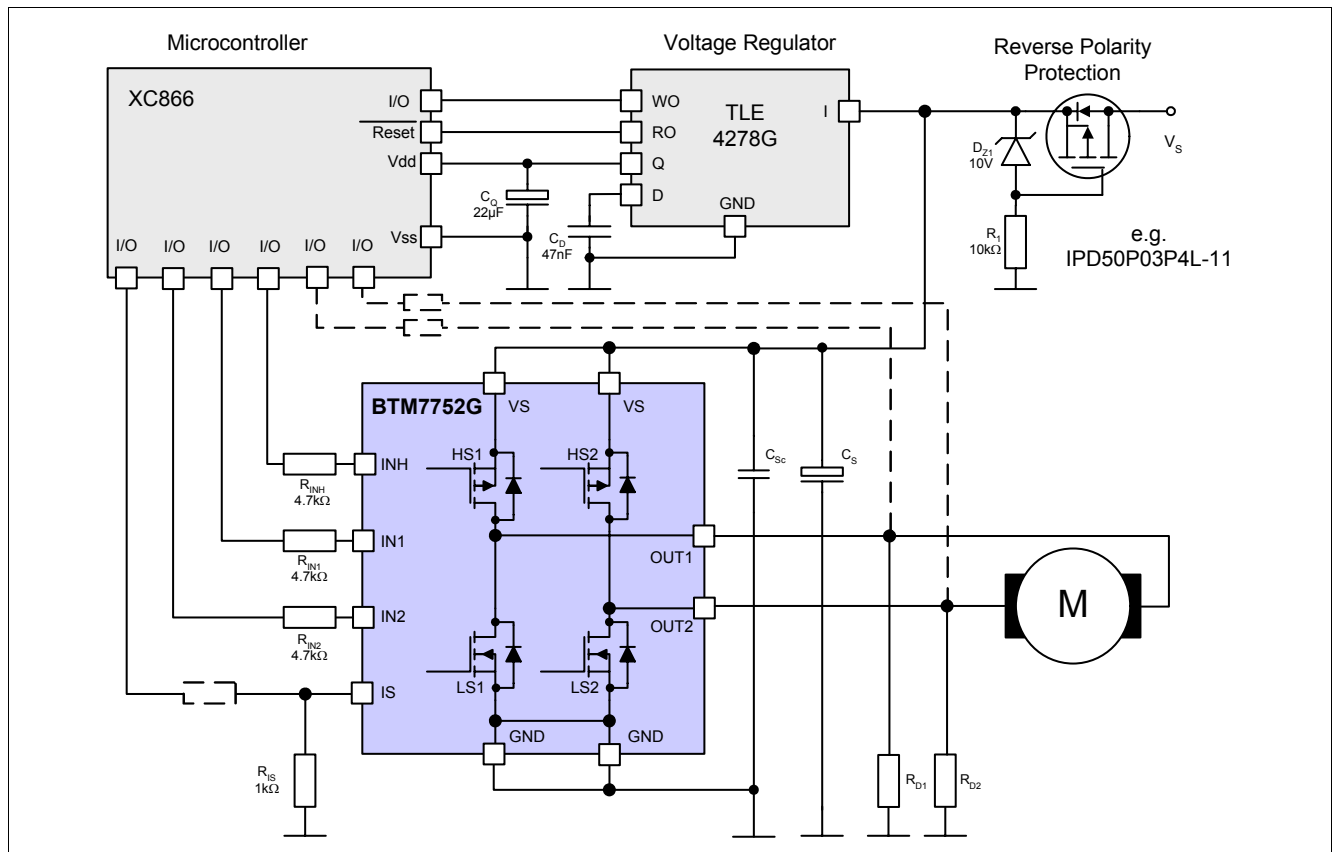


Figure 15 Application Diagram

Note: This is a very simplified example of an application circuit. The function must be verified in the real application.

7.1 Application and Layout Considerations

Due to the fast switching times for high currents, special care has to be taken during the PCB layout. Stray inductances have to be minimized in the power bridge design as it is necessary in all switched high power bridges. The BTM7752G has no separate pin for power ground and logic ground. **Therefore it is recommended to ensure that the offset between power ground and logic ground pins of the device is minimized. It is also necessary to ensure that all VS pins are at the same voltage level. Therefore the VS pins need to be shorted together.** Voltage differences between the VS pins may cause parameter deviations (such as reduced current limits and current sense ratio (kilis)) up to a latched shutdown of the device with error signal on the IS pin, similar to overtemperature shutdown.

Due to the fast switching behavior of the device in current limitation mode or overvoltage lock out a low ESR electrolytic capacitor C_S of at least 100 μF from VS to GND is recommended. This prevents destructive voltage peaks and drops on VS. This is recommended for both PWM and non PWM controlled applications. The value of the capacitor must be verified in the real application.

In addition a ceramic capacitor C_{SC} from VS to GND close to each device is recommended to provide current for the switching phase via a low inductance path and therefore reducing noise and ground bounce. A reasonable value for this capacitor would be about 470 nF.

It is recommended to do the freewheeling in the low side path to ensure a proper function and avoid unintended overtemperature detection and shutdown. For proper operation it is also recommended to put a pull-down resistor R_{Dx} on each output OUTx to GND with a value in the range of e.g. 1...10 k Ω . These resistors can also be used for open load detection.

Considerations for Open Load Detection Mode

As mentioned in [Chapter 6.4.1](#) both high side switches can be switched on independently while all other switches are off. This will be realized by setting the corresponding IN signal to high while INH and the other IN are low.

Device State	Inputs			Outputs					Mode
	INH	IN1	IN2	HS1	LS1	HS2	LS2	IS	
Open-Load detection mode	0	0	1	OFF	OFF	ON	OFF	CS HS2 ¹⁾	HS2 active
	0	1	0	ON	OFF	OFF	OFF	CS HS1 ¹⁾	HS1 active
	0	1	1	ON	OFF	ON	OFF	CS ²⁾	both HSx are active

1) Previous current sense assignment to be reset by IN1=IN2=low and both high side switches off (see [Chapter 6.4.3](#))

2) When both high side switches are in on state, the CS provides the sense signal for the high side switch, which has been turned on at first.

Together with the recommended pull-down resistors on the outputs OUTx to GND this provides the possibility to do an open load detection in H-bridge configuration.

In case of one high side is active while the other half bridge is off (HS off and LS off) a current of up to 2mA will be sourced out of the OUT of the high ohmic half bridge. This has to be considered while choosing the right value of the pull-down resistor.

8 Package Outlines

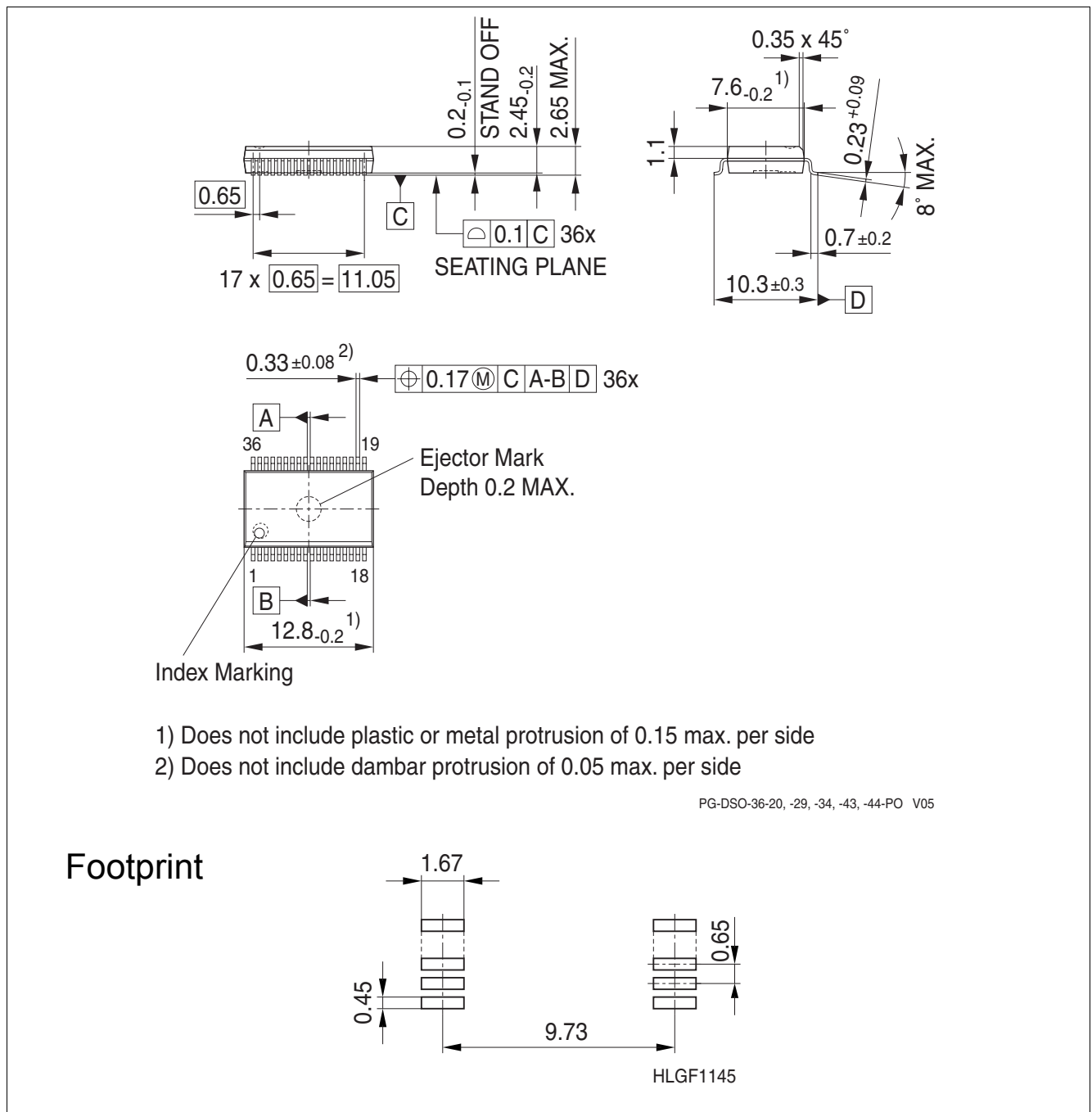


Figure 16 PG-DSO-36-29 (Plastic Green Dual Small Outline Package)

Green Product (RoHS compliant)

To meet the world-wide customer requirements for environmentally friendly products and to be compliant with government regulations the device is available as a green product. Green products are RoHS-Compliant (i.e Pb-free finish on leads and suitable for Pb-free soldering according to IPC/JEDEC J-STD-020).

For further information on alternative packages, please visit our website:

<http://www.infineon.com/packages>.

Dimensions in mm

9 Revision History

Revision	Date	Changes
2.0	2010-05-28	Initial version Data Sheet

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