Features

- Single-chip 10Base-T/100Base-TX physical layer solution
- Fully compliant to IEEE 802.3u Standard
- Low power CMOS design, power consumption of <180mW
- HP auto MDI/MDI-X for reliable detection and correction for straight-through and crossover cables with disable and enable option
- Robust operation over standard cables
- LinkMD[®] TDR-based cable diagnostics for identification of faulty copper cabling
- Fiber support: 100Base-FX (KSZ8041FTL only),
- Back-to-Back mode support for 100Mbps repeater or media converter
- MII interface support
- RMII interface support with external 50MHz system clock (KSZ8041TL/FTL only)
- SMII interface support with external 125MHz system clock and 12.5MHz sync clock from MAC (KSZ8041TL/FTL only)
- MIIM (MDC/MDIO) management bus to 12.5MHz for rapid PHY register configuration
- Interrupt pin option
- Programmable LED outputs for link, activity and speed
- · Power down and power saving modes
- Single power supply (3.3V)
- Built-in 1.8V regulator for core
- Available packages:
 - 48-pin LQFP (KSZ8041MLL) 48-pin TQFP (KSZ8041TL/FTL)

Ordering Information

Part Number (marking)	Ordering Number	Temp. Range	Package	Lead Finish	Description
KSZ8041MLL	KSZ8041MLL	0°C to 70°C	48-Pin LQFP	Pb-Free	MII, 10/100 Copper, C-Temp, 48-LQFP
KSZ8041TL	KSZ8041TL	0°C to 70°C	48-Pin TQFP	Pb-Free	MII / RMII, 10/100 Copper, C-Temp, 48-TQFP
KSZ8041TLI ⁽¹⁾	KSZ8041TLI	-40°C to 85°C	48-Pin TQFP	Pb-Free	MII / RMII, 10/100 Copper, I-Temp, 48-TQFP
KSZ8041FTL	KSZ8041FTL	0°C to 70°C	48-Pin TQFP	Pb-Free	MII / RMII, 100Base-FX Fiber, C-Temp, 48-TQFP
KSZ8041FTLI (1)	KSZ8041FTLI	-40°C to 85°C	48-Pin TQFP	Pb-Free	MII / RMII, 100Base-FX Fiber, I-Temp, 48-TQFP
KSZ8041TL (1)	KSZ8041TL-S	0°C to 70°C	48-Pin TQFP	Pb-Free	SMII, 10/100 Copper, C-Temp, 48-TQFP
KSZ8041TLI (1)	KSZ8041TLI-S	-40°C to 85°C	48-Pin TQFP	Pb-Free	SMII, 10/100 Copper, I-Temp, 48-TQFP
KSZ8041FTL ⁽¹⁾	KSZ8041FTL-S	0°C to 70°C	48-Pin TQFP	Pb-Free	SMII, 100Base-FX Fiber, C-Temp, 48-TQFP
KSZ8041FTLI (1)	KSZ8041FTLI-S	-40°C to 85°C	48-Pin TQFP	Pb-Free	SMII, 100Base-FX Fiber, I-Temp, 48-TQFP

Note:

1. Contact factory for lead time.

- Printer
- LOM
- Game Console
- IPTV
- IP Phone
 - IP Set-top Box
 - Media Converter

Revision History

Revision	Date	Summary of Changes
1.0	12/21/06	Data sheet created.
1.1	4/27/07	Added maximum MDC clock speed.
		Added 40K +/-30% to note 1 of Pin Description and Strapping Options tables for internal pull-ups/pull- downs.
		Changed Model Number in Register 3h – PHY Identifier 2.
		Changed polarity (swapped definition) of DUPLEX strapping pin.
		Removed DUPLEX strapping pin update to Register 4h – Auto-Negotiation Advertisement bits [8, 6].
		Added Back-to-Back mode for KSZ8041TL.
		Added Symbol Error to MII/RMII Receive Error description and Register 15h – RXER Counter.
		Added a 100pF capacitor on REXT (pin 16) in Pin Description table.
1.2	12/9/09	Updated Ordering Information.
		Changed MDIO hold time (min) from 10ns to 4ns.
		Added thermal resistance (θ_{JC}).
		Added chip maximum current consumption.
		Added LED drive current.
		Renamed Register 3h bits [3:0] to "manufacturer's revision number" and changed default value to "Indicates silicon revision."
		Updated RMII output delay for CRSDV and RXD[1:0] output pins.
		Added support for Asymmetric PAUSE in register 4h bit [11].
		Added control bits for 100Base-TX preamble restore (register 14h bit [7]) and 10Base-T preamble restore (register 14h bit [6]).
		Changed strapping pin definition for CONFIG[2:0] = 100 from "PCS Loopback" to "MII 100Mbps Preamble Restore."
		Corrected MII timing for t _{RLAT} , t _{CRS1} , t _{CRS2} .
		Added SMII timing.
		Added KSZ8041MLL device and updated entire data sheet accordingly.
		Added 48-Pin LQFP package information.

Contents

General Description	1
Functional Diagram	
Features	2
Applications	2
Ordering Information	2
Revision History	3
List of Figures	6
List of Tables	7
Pin Configuration – KSZ8041TL	8
Pin Configuration – KSZ8041FTL	
Pin Description- KSZ8041TL/FTL	
Strapping Options- KSZ8041TL/FTL	
Pin Configuration –KSZ8041MLL	
Pin Description- KSZ8041MLL	
Strapping Options – KSZ8041MLL	
Functional Description	
100Base-TX Transmit	
100Base-TX Receive	
PLL Clock Synthesizer	
Scrambler/De-scrambler (100Base-TX only)	
10Base-T Transmit	
10Base-T Receive	
SQE and Jabber Function (10Base-T only)	
Auto-Negotiation	
MII Management (MIIM) Interface	
Interrupt (INTRP)	
MII Data Interface	
MII Signal Definition	
Transmit Clock (TXC)	
Transmit Enable (TXEN)	
Transmit Data [3:0] (TXD[3:0]) Receive Clock (RXC)	
Receive Data Valid (RXDV) Receive Data [3:0] (RXD[3:0])	
Receive Error (RXER)	
Carrier Sense (CRS) Collision (COL)	
Reduced MII (RMII) Data Interface (KSZ8041TL/FTL only)	
RMII Signal Definition (KSZ8041TL/FTL only)	
Reference Clock (REF_CLK)	
Transmit Enable (TX_EN)	
Transmit Data [1:0] (TXD[1:0])	
Carrier Sense/Receive Data Valid (CRS_DV)	
Receive Data [1:0] (RXD[1:0])	
Receive Error (RX_ER)	
Collision Detection	
Serial MII (SMII) Data Interface (KSZ8041TL/FTL only)	
· · · · · · · · · · · · · · · · · · ·	

Downloaded from Arrow.com.

SMII Signal Definition (KSZ8041TL/FTL only)	
Clock Reference (CLOCK)	
Sync Pulse (SYNC)	
Transmit Data and Control (TX)	
Receive Data and Control (RX)	
Collision Detection	
HP Auto MDI/MDI-X	
Straight Cable	
Crossover Cable	
LinkMD [®] Cable Diagnostics	
Access	
Usage	
Power Management	
Power Saving Mode	
Power Down Mode	
Reference Clock Connection Options	
Reference Circuit for Power and Ground Connections	
100Base-FX Fiber Operation (KSZ8041FTL only)	
Fiber Signal Detect	
Far-End Fault	
Back-to-Back Media Converter	
MII Back-to-Back Mode	
RMII Back-to-Back Mode (KSZ8041TL/FTL only)	
Register Map	40
Register Description	
Absolute Maximum Ratings ⁽¹⁾	
Operating Ratings ⁽²⁾	
Electrical Characteristics ⁽³⁾	
Timing Diagrams	
MII SQE Timing (10Base-T)	
MII Transmit Timing (10Base-T)	
MII Receive Timing (10Base-T)	
MII Transmit Timing (100Base-TX)	
MII Receive Timing (100Base-TX)	
RMII Timing	
SMII Timing	
Auto-Negotiation Timing	
MDC/MDIO Timing	
Reset Timing	
Reset Circuit	
Selection of Isolation Transformer	
Selection of Reference Crystal	
Package Information	63
48-Pin LQFP 48-Pin TQFP	63

List of Figures

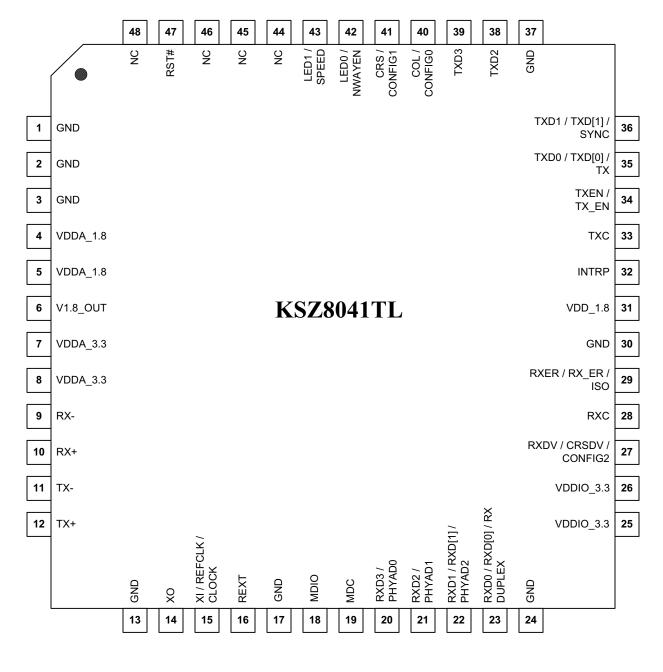
Figure 1. Auto-Negotiation Flow Chart	
Figure 2. SMII Transmit Data/Control Segment	
Figure 3. SMII Receive Data/Control Segment	
Figure 4. Typical Straight Cable Connection	
Figure 5. Typical Crossover Cable Connection	
Figure 6. 25MHz Crystal / Oscillator Reference Clock for MII Mode	
Figure 7. 50MHz Oscillator Reference Clock for RMII Mode	
Figure 8. 125MHz Oscillator Reference Clock for SMII Mode	
Figure 9. KSZ8041TL/FTL/MLL Power and Ground Connections	
Figure 10. KSZ8041TL/MLL and KSZ8041FTL Back-to-Back Media Converter	
Figure 11. MII SQE Timing (10Base-T)	
Figure 12. MII Transmit Timing (10Base-T)	51
Figure 13. MII Receive Timing (10Base-T)	
Figure 14. MII Transmit Timing (100Base-TX)	
Figure 15. MII Receive Timing (100Base-TX)	
Figure 16. RMII Timing – Data Received from RMII	
Figure 17. RMII Timing – Data Input to RMII	
Figure 18. SMII Timing – Data Received from SMII	
Figure 19. SMII Timing – Data Input to SMII	
Figure 20. Auto-Negotiation Fast Link Pulse (FLP) Timing	
Figure 21. MDC/MDIO Timing	
Figure 22. Reset Timing	
Figure 23. Recommended Reset Circuit	
Figure 24. Recommended Reset Circuit for Interfacing with CPU/FPGA Reset Output	
Figure 25. Reference Circuits for LED Strapping Pins	61

Downloaded from Arrow.com.

List of Tables

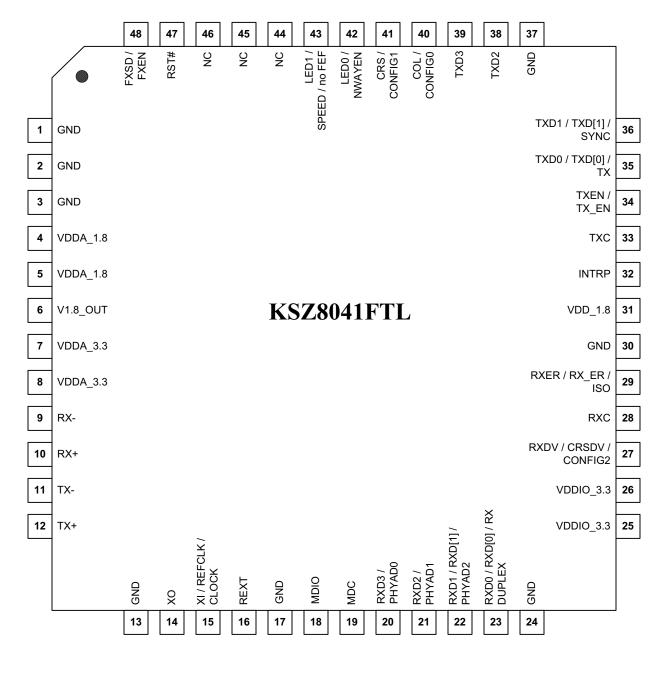
Table 1. MII Management Frame Format	25
Table 2. MII Signal Definition	
Table 3. RMII Signal Description	
Table 4. SMII Signal Description	29
Table 5. SMII TX Bit Description	
Table 6. SMII TXD[0:7] Encoding Table	
Table 7. SMII RX Bit Description	31
Table 8. SMII RXD[0:7] Encoding Table	31
Table 9. MDI/MDI-X Pin Definition	
Table 10. KSZ8041TL/FTL/MLL Power Pin Description	
Table 11. Copper and Fiber Mode Selection	37
Table 12. MII Signal Connection for MII Back-to-Back Mode	
Table 13. RMII Signal Connection for RMII Back-to-Back Mode	
Table 14. MII SQE Timing (10Base-T) Parameters	
Table 15. MII Transmit Timing (10Base-T) Parameters	51
Table 16. MII Receive Timing (10Base-T) Parameters	52
Table 17. MII Transmit Timing (100Base-TX) Parameters	
Table 18. MII Receive Timing (100Base-TX) Parameters	54
Table 19. RMII Timing Parameters	
Table 20. SMII Timing Parameters	56
Table 21. Auto-Negotiation Fast Link Pulse (FLP) Timing Parameters	57
Table 22. MDC/MDIO Timing Parameters	
Table 23. Reset Timing Parameters	
Table 24. Transformer Selection Criteria	
Table 25. Qualified Single Port Magnetics	
Table 26. Typical Reference Crystal Characteristics	62

Pin Configuration – KSZ8041TL



48-Pin TQFP

Pin Configuration – KSZ8041FTL



48-Pin TQFP

Pin Description- KSZ8041TL/FTL

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function	
1	GND	Gnd	Ground	
2	GND	Gnd	Ground	
3	GND	Gnd	Ground	
4	VDDA_1.8	Р	1.8V analog V _{DD}	
5	VDDA_1.8	Р	1.8V analog V _{DD}	
6	V1.8_OUT	Р	1.8V output volta	age from chip
7	VDDA_3.3	Р	3.3V analog V _{DD}	
8	VDDA_3.3	Р	3.3V analog V _{DD}	
9	RX-	I/O	Physical receive	or transmit signal (- differential)
10	RX+	I/O	Physical receive	or transmit signal (+ differential)
11	TX-	I/O	Physical transmi	t or receive signal (- differential)
12	TX+	I/O	Physical transmi	t or receive signal (+ differential)
13	GND	Gnd	Ground	
14	ХО	0	Crystal feedback	
			This pin is used	only in MII mode when a 25MHz crystal is used.
			This pin is a no o mode or SMII mo	connect if oscillator or external clock source is used, or if RMII ode is selected.
15	XI /	I	Crystal / Oscillate	or / External Clock Input
	REFCLK /		MII Mode:	25MHz +/-50ppm (crystal, oscillator, or external clock)
	CLOCK		RMII Mode:	50MHz +/-50ppm (oscillator, or external clock only)
			SMII Mode:	125MHz +/-100ppm (oscillator, or external clock only)
16	REXT	I/O	Set physical tran	smit output current
			Connect a $6.49K\Omega$ resistor in parallel with a 100pF capacitor to ground on this pin. See KSZ8041TL-FTL reference schematics.	
17	GND	Gnd	Ground	
18	MDIO	I/O	Management Int	erface (MII) Data I/O
			This pin requires	an external 4.7K Ω pull-up resistor.
19	MDC		Management Inte	erface (MII) Clock Input
			This pin is synch	ronous to the MDIO data interface.
20	RXD3 /	Ipu/O	MII Mode:	Receive Data Output[3] ⁽²⁾ /
	PHYAD0		Config. Mode:	The pull-up/pull-down value is latched as PHYADDR[0] during power-up / reset. See "Strapping Options" section for details.
21	RXD2 /	lpd/O	MII Mode:	Receive Data Output[2] ⁽²⁾ /
	PHYAD1		Config. Mode:	The pull-up/pull-down value is latched as PHYADDR[1] during power-up / reset. See "Strapping Options" section for details.
22	RXD1 /	Ipd/O	MII Mode:	Receive Data Output[1] ⁽²⁾ /
	RXD[1] /		RMII Mode:	Receive Data Output[1] ⁽³⁾ /
	PHYAD2		Config. Mode:	The pull-up/pull-down value is latched as PHYADDR[2] during power-up / reset. See "Strapping Options" section for details.

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function	
23	RXD0 /	lpu/O	MII Mode:	Receive Data Output[0] ⁽²⁾ /
	RXD[0] /		RMII Mode:	Receive Data Output[0] ⁽³⁾ /
	RX		SMII Mode:	Receive Data and Control ⁽⁴⁾ /
	DUPLEX		Config. Mode:	Latched as DUPLEX (register 0h, bit 8) during power-up / reset. See "Strapping Options" section for details.
24	GND	Gnd	Ground	
25	VDDIO_3.3	Р	3.3V digital V_{DD}	
26	VDDIO_3.3	Р	3.3V digital V _{DD}	
27	RXDV /	lpd/O	MII Mode:	Receive Data Valid Output /
	CRSDV /		RMII Mode:	Carrier Sense/Receive Data Valid Output /
	CONFIG2		Config. Mode:	The pull-up/pull-down value is latched as CONFIG2 during power-up / reset. See "Strapping Options" section for details.
28	RXC	0	MII Mode:	Receive Clock Output.
29	RXER /	lpd/O	MII Mode:	Receive Error Output /
	RX_ER /		RMII Mode:	Receive Error Output /
	ISO		Config. Mode:	The pull-up/pull-down value is latched as ISOLATE during power-up / reset. See "Strapping Options" section for details.
30	GND	Gnd	Ground	
31	VDD_1.8	Р	1.8V digital V_{DD}	
32	INTRP	Opu	Interrupt Output: Programmable Interrupt Output	
			interrupt conditio	he Interrupt Control/Status Register for programming the ns and reading the interrupt status. Register 1Fh bit 9 sets the o active low (default) or active high.
33	TXC	I/O	MII Mode:	Transmit Clock Output
			MII Back-to Back	Mode: Transmit Clock Input
34	TXEN /	Ι	MII Mode:	Transmit Enable Input /
	TX_EN		RMII Mode:	Transmit Enable Input
35	TXD0 /	I	MII Mode:	Transmit Data Input[0] ⁽⁵⁾ /
	TXD[0] /		RMII Mode:	Transmit Data Input[0] ⁽⁶⁾ /
	ТХ		SMII Mode:	Transmit Data and Control ⁽⁷⁾
36	TXD1 /	I	MII Mode:	Transmit Data Input[1] ⁽⁵⁾ /
	TXD[1] /		RMII Mode:	Transmit Data Input[1] ⁽⁶⁾ /
	SYNC		SMII Mode:	SYNC Clock Input
37	GND	Gnd	Ground	
38	TXD2	I	MII Mode:	Transmit Data Input[2] ⁽⁵⁾ /
39	TXD3	I	MII Mode:	Transmit Data Input[3] ⁽⁵⁾ /
40	COL /	lpd/O	MII Mode:	Collision Detect Output /
-	CONFIG0	r · · -	Config. Mode:	The pull-up/pull-down value is latched as CONFIG0 during power-up / reset. See "Strapping Options" section for details.
41	CRS /	lpd/O	MII Mode:	Carrier Sense Output /
	CONFIG1	·	Config. Mode:	The pull-up/pull-down value is latched as CONFIG1 during power-up / reset. See "Strapping Options" section for details.

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function		
42	LED0 /	lpu/O	LED Output:	Programmable LE	ED0 Output /
(KSZ8041TL)	NWAYEN		Config. Mode:		Negotiation Enable (register 0h, bit 12) / reset. See "Strapping Options" section for
			The LED0 pin is follows.	programmable via	register 1Eh bits [15:14], and is defined as
			LED mode =	[00]	
			Link/Activity	Pin State	LED Definition
			No Link	Н	OFF
			Link	L	ON
			Activity	Toggle	Blinking
			LED mode =	[01]	
			Link	Pin State	LED Definition
			No Link	Н	OFF
			Link	L	ON
			LED mode = [1	<u>01</u>	
			Reserved		
			<u>LED mode = [1</u>	<u>1]</u>	
			Reserved		
42	LED0 /	lpu/O	LED Output:	Programmable LE	•
(KSZ8041FTL)	NWAYEN		Config. Mode:		FXEN=0), latched as Auto-Negotiation Dh, bit 12) during power-up / reset.
					EN=1), this pin configuration is always le Auto-Negotiation.
					Options" section for details.
			The LED0 pin is follows.	programmable via	register 1Eh bits [15:14], and is defined as
			LED mode =	[00]	
			Link/Activity		LED Definition
			No Link	н	OFF
			Link	L	ON
			Activity	Toggle	Blinking
			LED mode =	[01]	
			Link	Pin State	LED Definition
			No Link	н	OFF
			Link	L	ON
			LED mode = [10 Reserved	<u>0]</u>	
			LED mode = [1	1]	
			Reserved		

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function		
43	LED1 /	lpu/O	LED Output:	Programmable LE	ED1 Output /
(KSZ8041TL) SPEED	SPEED		Config. Mode:		D (register 0h, bit 13) during power-up / pping Options" section for details.
		The LED1 pin is programmable via register 1Eh bits [15:14], and is defined as follows.			
			LED mode =	[00]	
			Speed	Pin State	LED Definition
			10BT	н	OFF
			100BT	L	ON
			LED mode =		
			Activity	Pin State	LED Definition
			No Activity	Н	OFF
			Activity	Toggle	Blinking
			LED mode = [1	01	
			Reserved	-	
			<u>LED mode = [1</u>	<u>11</u>	
10	/ /		Reserved		
43	LED1/	lpu/O	LED Output:	Programmable LE	•
(KSZ8041FTL)	SPEED / no FEF		Config. Mode:	If copper mode (F 13) during power-	FXEN=0), latched as SPEED (register 0h, bit -up / reset.
	HOT EI				EN=1), latched as no FEF (no Far-End Fault)
				See "Strapping O	ptions" section for details.
			The LED1 pin is follows.	s programmable via	register 1Eh bits [15:14], and is defined as
			LED mode =	[00]	
			Speed	Pin State	LED Definition
			10BT	н	OFF
			100BT	L	ON
			LED mode =	[04]	
			LED mode = Activity	Pin State	LED Definition
			No Activity	H	OFF
			Activity	Toggle	Blinking
			Activity	loggie	Diriking
			<u>LED mode = [1</u>	<u>0]</u>	
			Reserved		
			LED mode = [1	1]	
			Reserved		
44	NC	-	No connect		
45	NC	-	No connect		
46	NC	-	No connect		

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function	
47	RST#	I	Chip Reset (active low)	
48	NC	-	No connect	
(KSZ8041TL)				
48	FXSD /	lpd	FXSD: Signal Detect for 100Base-FX fiber mode	
(KSZ8041FTL)	FXEN		FXEN: Fiber Enable for 100Base-FX fiber mode	
			If FXEN=0, fiber mode is disabled. PHY is in copper mode. The default is "0". See "100Base-FX Operation" section for details.	

Notes:

1. P = Power supply.

Gnd = Ground.

I = Input.

O = Output.

I/O = Bi-directional.

Ipd = Input with internal pull-down (40K +/-30%).

Ipu = Input with internal pull-up (40K +/-30%).

Opu = Output with internal pull-up (40K +/-30%).

Ipu/O = Input with internal pull-up (40K +/-30%) during power-up/reset; output pin otherwise.

Ipd/O = Input with internal pull-down (40K +/-30%) during power-up/reset; output pin otherwise.

- 2. MII Rx Mode: The RXD[3..0] bits are synchronous with RXCLK. When RXDV is asserted, RXD[3..0] presents valid data to MAC through the MII. RXD[3..0] is invalid when RXDV is de-asserted.
- 3. RMII Rx Mode: The RXD[1:0] bits are synchronous with REF_CLK. For each clock period in which CRS_DV is asserted, two bits of recovered data are sent from the PHY.
- 4. SMII Rx Mode: Receive data and control information are sent in 10 bit segments. In 100MBit mode, each segment represents a new byte of data. In 10MBit mode, each segment is repeated ten times; therefore, every ten segments represent a new byte of data. The MAC can sample any one of every 10 segments in 10MBit mode.
- 5. MII Tx Mode: The TXD[3..0] bits are synchronous with TXCLK. When TXEN is asserted, TXD[3..0] presents valid data from the MAC through the MII. TXD[3..0] has no effect when TXEN is de-asserted.
- 6. RMII Tx Mode: The TXD[1:0] bits are synchronous with REF_CLK. For each clock period in which TX_EN is asserted, two bits of data are received by the PHY from the MAC.
- 7. SMII Tx Mode: Transmit data and control information are received in 10 bit segments. In 100MBit mode, each segment represents a new byte of data. In 10MBit mode, each segment is repeated ten times; therefore, every ten segments represent a new byte of data. The PHY can sample any one of every 10 segments in 10MBit mode.

Strapping Options- KSZ8041TL/FTL

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function	
22	PHYAD2	lpd/O	The PHY Address is latched at power-up / reset and is configurable to any value from	
21	PHYAD1	lpd/O	1 to 7.	
20	PHYAD0	lpu/O	The default PHY Address is 00001.	
			PHY Address bits [4:3] are always set to '00'.	
27	CONFIG2	lpd/O	The CONFIG[2:0] strap-in pins are latched at power-up / reset and are defined as	
41	CONFIG1	Ipd/O	follows:	
40	CONFIG0	Ipd/O		
			CONFIG[2:0] Mode	
			000 MII (default)	
			001 RMII	
			010 SMII	
			011 Reserved – not used	
			100 MII 100Mbps Preamble Restore	
			101 RMII back-to-back	
			110 MII back-to-back	
			111 Reserved – not used	
29	ISO	lpd/O	ISOLATE mode	
		-	Pull-up = Enable	
			Pull-down (default) = Disable	
			During power-up / reset, this pin value is latched into register 0h bit 10.	
43	SPEED	lpu/O	SPEED mode	
(KSZ8041TL)			Pull-up (default) = 100Mbps	
,			Pull-down = 10Mbps	
			During power-up / reset, this pin value is latched into register 0h bit 13 as the Speed Select, and also is latched into register 4h (Auto-Negotiation Advertisement) as the Speed capability support.	
43	SPEED /	lpu/O	If copper mode (FXEN=0), pin strap-in is SPEED mode.	
(KSZ8041FTL)			Pull-up (default) = 100Mbps	
			Pull-down = 10Mbps	
			During power-up / reset, this pin value is latched into register 0h bit 13 as the Speed Select, and also is latched into register 4h (Auto-Negotiation Advertisement) as the Speed capability support.	
	no FEF		If fiber mode (FXEN=1), pin strap-in is no FEF.	
			Pull-up (default) = Enable Far-End Fault	
			Pull-down = Disable Far-End Fault	
			This pin value is latched during power-up / reset.	

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function
23	DUPLEX	lpu/O	DUPLEX mode
			Pull-up (default) = Half Duplex
			Pull-down = Full Duplex
			During power-up / reset, this pin value is latched into register 0h bit 8 as the Duplex Mode.
42	NWAYEN	lpu/O	Nway Auto-Negotiation Enable
(KSZ8041TL)			Pull-up (default) = Enable Auto-Negotiation
			Pull-down = Disable Auto-Negotiation
			During power-up / reset, this pin value is latched into register 0h bit 12.
42	NWAYEN	lpu/O	If copper mode (FXEN=0), pin strap-in is Nway Auto-Negotiation Enable.
(KSZ8041FTL)			Pull-up (default) = Enable Auto-Negotiation
			Pull-down = Disable Auto-Negotiation
			During power-up / reset, this pin value is latched into register 0h bit 12.
			If fiber mode (FXEN=1), this pin configuration is always strapped to disable Auto- Negotiation.

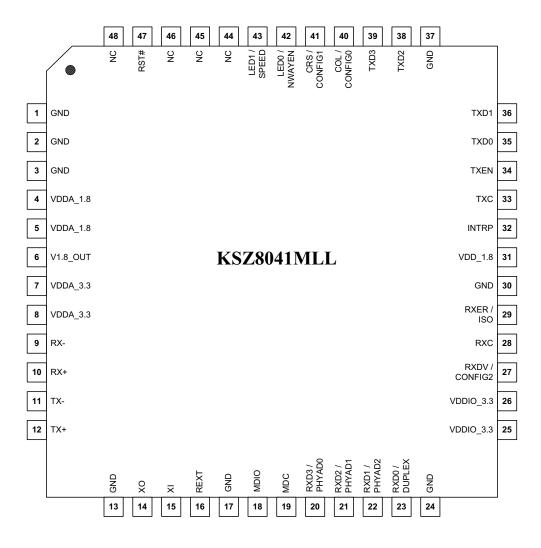
Note:

1. lpu/O = Input with internal pull-up (40K +/-30%) during power-up/reset; output pin otherwise.

Ipd/O = Input with internal pull-down (40K +/-30%) during power-up/reset; output pin otherwise.

Pin strap-ins are latched during power-up or reset. In some systems, the MAC receive input pins may drive high during power-up or reset, and consequently cause the PHY strap-in pins on the MII/RMII/SMII signals to be latched high. In this case, it is recommended to add 1K pull-downs on these PHY strap-in pins to ensure the PHY does not strap-in to ISOLATE mode, or is not configured with an incorrect PHY Address.

Pin Configuration – KSZ8041MLL



48-Pin LQFP

Pin Description- KSZ8041MLL

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function			
1	GND	Gnd	Ground			
2	GND	Gnd	Ground			
3	GND	Gnd	Ground			
4	VDDA_1.8	Р	1.8V analog V _{DD}	1.8V analog V _{DD}		
5	VDDA_1.8	Р	1.8V analog V _{DD}			
6	V1.8_OUT	Р	1.8V output volta	ige from chip		
7	VDDA_3.3	Р	3.3V analog V_{DD}			
8	VDDA_3.3	Р	3.3V analog V_{DD}			
9	RX-	I/O	Physical receive	or transmit signal (- differential)		
10	RX+	I/O	Physical receive	or transmit signal (+ differential)		
11	TX-	I/O	Physical transmit	t or receive signal (- differential)		
12	TX+	I/O	Physical transmit	t or receive signal (+ differential)		
13	GND	Gnd	Ground			
14	ХО	0	Crystal feedback			
			This pin is used of	only when a 25 MHz crystal is used.		
			This pin is a no c	connect if oscillator or external clock source is used.		
15	XI	I	Crystal / Oscillato	or / External Clock Input		
			25MHz +/-50ppm			
16	REXT	I/O	Set physical trans	smit output current		
			Connect a $6.49K\Omega$ resistor in parallel with a 100pF capacitor to ground on this pin. See KSZ8041MLL reference schematic.			
17	GND	Gnd	Ground			
18	MDIO	I/O	Management Inte	erface (MII) Data I/O		
			This pin requires	an external 4.7KΩpull-up resistor.		
19	MDC	I	Management Inte	erface (MII) Clock Input		
			This pin is synch	ronous to the MDIO data interface.		
20	RXD3 /	lpu/O	MII Mode:	Receive Data Output[3] ⁽²⁾ /		
	PHYAD0		Config. Mode:	The pull-up/pull-down value is latched as PHYADDR[0] during power-up / reset. See "Strapping Options" section for details.		
21	RXD2 /	lpd/O	MII Mode:	Receive Data Output[2] ⁽²⁾ /		
	PHYAD1		Config. Mode:	The pull-up/pull-down value is latched as PHYADDR[1] during power-up / reset. See "Strapping Options" section for details.		
22	RXD1 /	Ipd/O	MII Mode:	Receive Data Output[1] ⁽²⁾ /		
	PHYAD2		Config. Mode: The pull-up/pull-down value is latched as PHYADDR[2] during power-up / reset. See "Strapping Options" section for details.			
23	RXD0 /	lpu/O	MII Mode: Receive Data Output[0] ⁽²⁾ /			
	DUPLEX		Config Mode:	Latched as DUPLEX (register 0h, bit 8) during power-up / reset. See "Strapping Options" section for details.		
24	GND	Gnd	Ground			
25	VDDIO_3.3	Р	3.3V digital V _{DD}			
26	VDDIO 3.3	Р	3.3V digital V _{DD}			

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function				
27	RXDV /	lpd/O	MII Mode:	Receive Data Vali	id Output /		
	CONFIG2		Config. Mode:		own value is latched as CONFIG2 during See "Strapping Options" section for details.		
28	RXC	0	MII Receive Clo	ck Output			
29	RXER /	lpd/O	MII Mode:	Receive Error Out	tput /		
	ISO		Config. Mode: The pull-up/pull-down value is latched as ISOLATE during power-up / reset. See "Strapping Options" section for deta				
30	GND	Gnd	Ground				
31	VDD_1.8	Р	1.8V digital V _{DD}				
32	INTRP	Opu	Interrupt Output:	Programmable Int	terrupt Output		
			interrupt condition		I/Status Register for programming the interrupt status. Register 1Fh bit 9 sets the t) or active high.		
33	TXC	I/O	MII Transmit Clo	ock Output			
34	TXEN	I	MII Transmit Ena	able Input			
35	TXD0	I	MII Transmit Dat	ta Input[0] ⁽³⁾			
36	TXD1	I	MII Transmit Dat	ta Input[1] ⁽³⁾			
37	GND	Gnd	Ground				
38	TXD2	I	MII Transmit Data Input[2] ⁽³⁾ /				
39	TXD3	I	MII Transmit Dat	ta Input[3] ⁽³⁾ /			
40	COL /	lpd/O	MII Mode:	Collision Detect C	Dutput /		
	CONFIG0		Config. Mode: The pull-up/pull-down value is latched as CONFIG0 during power-up / reset. See "Strapping Options" section for deta				
41	CRS /	lpd/O	MII Mode:	Carrier Sense Out	tput /		
	CONFIG1		Config. Mode:		own value is latched as CONFIG1 during See "Strapping Options" section for details.		
42	LED0 /	lpu/O	LED Output:	Programmable LE	ED0 Output /		
	NWAYEN		Config. Mode:		Negotiation Enable (register 0h, bit 12) / reset. See "Strapping Options" section for		
			The LED0 pin is follows.	programmable via ı	register 1Eh bits [15:14], and is defined as		
			LED mode = [[00]			
			Link/Activity	Pin State	LED Definition		
			No Link	Н	OFF		
			Link	L	ON		
			Activity	Toggle	Blinking		
			LED mode = [[01]			
			Link	Pin State	LED Definition		
			No Link	Н	OFF		
			Link	L	ON		
			<u>LED mode = [10</u>	0] Reserved			
			<u>LED mode = [11</u>	1] Reserved			

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function				
43	LED1 /	lpu/O	LED Output:	Programmable LE	ED1 Output /		
	SPEED		Config. Mode:	Config. Mode: Latched as SPEED (register 0h, bit 13) during power-up reset. See "Strapping Options" section for details.			
			The LED1 pin is follows.	programmable via	register 1Eh bits [15:14], and is defined as		
			LED mode = [00]			
			Speed	Pin State	LED Definition		
			10BT	Н	OFF		
			100BT	L	ON		
			LED mode = [01]			
			Activity	Pin State	LED Definition		
			No Activity	Н	OFF		
			Activity	Toggle	Blinking		
			<u>LED mode = [10</u>	l Reserved			
			<u>LED mode = [11</u>] Reserved			
44	NC	-	No connect				
45	NC	-	No connect				
46	NC	-	No connect				
47	RST#	I	Chip Reset (activ	re low)			
48	NC	-	No connect				

Notes:

1. P = Power supply.

Gnd = Ground.

I = Input.

O = Output.

I/O = Bi-directional.

lpd = Input with internal pull-down (40K +/-30%).

Ipu = Input with internal pull-up (40K +/-30%).

Opu = Output with internal pull-up (40K +/-30%).

Ipu/O = Input with internal pull-up (40K +/-30%) during power-up/reset; output pin otherwise.

lpd/O = Input with internal pull-down (40K +/-30%) during power-up/reset; output pin otherwise.

 MII Rx Mode: The RXD[3..0] bits are synchronous with RXCLK. When RXDV is asserted, RXD[3..0] presents valid data to MAC through the MII. RXD[3..0] is invalid when RXDV is de-asserted.

3. MII Tx Mode: The TXD[3..0] bits are synchronous with TXCLK. When TXEN is asserted, TXD[3..0] presents valid data from the MAC through the MII. TXD[3..0] has no effect when TXEN is de-asserted.

Strapping Options – KSZ8041MLL

Pin Number	Pin Name	Type ⁽¹⁾	Pin Function			
22	PHYAD2	lpd/O		is latched at power-up / reset and is configurable to any value from		
21	PHYAD1	Ipd/O	1 to 7.			
20	PHYAD0	lpu/O	The default PHY A			
			PHY Address bits	[4:3] are always set to '00'.		
27	CONFIG2	Ipd/O	The CONFIG[2:0]	strap-in pins are latched at power-up / reset and are defined as		
41	CONFIG1	lpd/O	follows:			
40	CONFIG0	lpd/O				
		P	CONFIG[2:0]	Mode		
			000	MII (default)		
			001	Reserved – not used		
			010	Reserved – not used		
			011	Reserved – not used		
			100	MII 100Mbps Preamble Restore		
			101	Reserved – not used		
			110	MII back-to-back		
			111	Reserved – not used		
29	ISO	lpd/O	ISOLATE mode			
			Pull-up =	Enable		
			Pull-dowr	n (default) = Disable		
			During power-up /	reset, this pin value is latched into register 0h bit 10.		
43	SPEED	lpu/O	SPEED mode			
			Pull-up (c	lefault) = 100Mbps		
			Pull-dowr	= 10Mbps		
				reset, this pin value is latched into register 0h bit 13 as the Speed latched into register 4h (Auto-Negotiation Advertisement) as the upport.		
23	DUPLEX	lpu/O	DUPLEX mode			
			Pull-up (d	lefault) = Half Duplex		
			Pull-dowr	n = Full Duplex		
			During power-up / Mode.	reset, this pin value is latched into register 0h bit 8 as the Duplex		
42	NWAYEN	lpu/O	Nway Auto-Negoti	ation Enable		
			Pull-up (c	lefault) = Enable Auto-Negotiation		
			Pull-dowr	n = Disable Auto-Negotiation		
			During power-up /	reset, this pin value is latched into register 0h bit 12.		

Note:

1. Ipu/O = Input with internal pull-up (40K +/-30%) during power-up/reset; output pin otherwise.

Ipd/O = Input with internal pull-down (40K +/-30%) during power-up/reset; output pin otherwise.

Pin strap-ins are latched during power-up or reset. In some systems, the MAC receive input pins may drive high during power-up or reset, and consequently cause the PHY strap-in pins on the MII signals to be latched high. In this case, it is recommended to add 1K pull-downs on these PHY strap-in pins to ensure the PHY does not strap-in to ISOLATE mode, or is not configured with an incorrect PHY Address.

Functional Description

The KSZ8041TL is a single 3.3V supply Fast Ethernet transceiver. It is fully compliant with the IEEE 802.3u specification.

On the media side, the KSZ8041TL supports 10Base-T and 100Base-TX with HP auto MDI/MDI-X for reliable detection of and correction for straight-through and crossover cables.

The KSZ8041TL offers a choice of MII, RMII, or SMII data interface connection to a MAC processor. The MII management bus option gives the MAC processor complete access to the KSZ8041TL control and status registers. Additionally, an interrupt pin eliminates the need for the processor to poll for PHY status change.

Physical signal transmission and reception are enhanced through the use of patented analog circuitries that make the design more efficient and allow for lower power consumption and smaller chip die size.

The KSZ8041FTL has all the identical rich features of the KSZ8041TL plus 100Base-FX fiber support.

The KSZ8041MLL is the basic 10Base-T/100Base-TX copper version with MII support.

100Base-TX Transmit

The 100Base-TX transmit function performs parallel-to-serial conversion, 4B/5B coding, scrambling, NRZ-to-NRZI conversion, and MLT3 encoding and transmission.

The circuitry starts with a parallel-to-serial conversion, which converts the MII data from the MAC into a 125MHz serial bit stream. The data and control stream is then converted into 4B/5B coding, followed by a scrambler. The serialized data is further converted from NRZ-to-NRZI format, and then transmitted in MLT3 current output.

The output current is set by an external 6.49 K Ω 1% resistor for the 1:1 transformer ratio. It has typical rise/fall times of 4 ns and complies with the ANSI TP-PMD standard regarding amplitude balance, overshoot and timing jitter. The wave-shaped 10Base-T output drivers are also incorporated into the 100Base-TX drivers.

100Base-TX Receive

The 100Base-TX receiver function performs adaptive equalization, DC restoration, MLT3-to-NRZI conversion, data and clock recovery, NRZI-to-NRZ conversion, de-scrambling, 4B/5B decoding, and serial-to-parallel conversion.

The receiving side starts with the equalization filter to compensate for inter-symbol interference (ISI) over the twisted pair cable. Since the amplitude loss and phase distortion is a function of the cable length, the equalizer must adjust its characteristics to optimize performance. In this design, the variable equalizer makes an initial estimation based upon comparisons of incoming signal strength against some known cable characteristics, and then tunes itself for optimization. This is an ongoing process and self-adjusts against environmental changes such as temperature variations.

Next, the equalized signal goes through a DC restoration and data conversion block. The DC restoration circuit is used to compensate for the effect of baseline wander and to improve the dynamic range. The differential data conversion circuit converts the MLT3 format back to NRZI. The slicing threshold is also adaptive.

The clock recovery circuit extracts the 125MHz clock from the edges of the NRZI signal. This recovered clock is then used to convert the NRZI signal into the NRZ format. This signal is sent through the de-scrambler followed by the 4B/5B decoder. Finally, the NRZ serial data is converted to the MII format and provided as the input data to the MAC.

PLL Clock Synthesizer

The KSZ8041TL/FTL/MLL generates 125MHz, 25MHz and 20MHz clocks for system timing. In MII mode, internal clocks are generated from an external 25MHz crystal or oscillator. For the KSZ8041TL/FTL, in RMII and SMII modes, these internal clocks are generated from external 50MHz and 125MHz oscillators or system clocks, respectively.

Scrambler/De-scrambler (100Base-TX only)

The purpose of the scrambler is to spread the power spectrum of the signal in order to reduce EMI and baseline wander.

10Base-T Transmit

The 10Base-T drivers are incorporated with the 100Base-TX drivers to allow for transmission using the same magnetic. The drivers also perform internal wave-shaping and pre-emphasize, and output 10Base-T signals with a typical amplitude of 2.5V peak. The 10Base-T signals have harmonic contents that are at least 27dB below the fundamental frequency when driven by an all-ones Manchester-encoded signal.

10Base-T Receive

On the receive side, input buffer and level detecting squelch circuits are employed. A differential input receiver circuit and a PLL performs the decoding function. The Manchester-encoded data stream is separated into clock signal and NRZ data. A squelch circuit rejects signals with levels less than 400mV or with short pulse widths to prevent noise at the RX+ and RX- inputs from falsely trigger the decoder. When the input exceeds the squelch limit, the PLL locks onto the incoming signal and the KSZ8041TL/FTL/MLL decodes a data frame. The receive clock is kept active during idle periods in between data reception.

SQE and Jabber Function (10Base-T only)

In 10Base-T operation, a short pulse is put out on the COL pin after each frame is transmitted. This SQE Test is required as a test of the 10Base-T transmit/receive path. If transmit enable (TXEN) is high for more than 20ms (jabbering), the 10Base-T transmitter is disabled and COL is asserted high. If TXEN is then driven low for more than 250ms, the 10Base-T transmitter is re-enabled and COL is de-asserted (returns to low).

Auto-Negotiation

The KSZ8041TL/FTL/MLL conforms to the auto-negotiation protocol, defined in Clause 28 of the IEEE 802.3u specification. Auto-negotiation is enabled by either hardware pin strapping (pin 42) or software (register 0h bit 12).

Auto-negotiation allows unshielded twisted pair (UTP) link partners to select the highest common mode of operation. Link partners advertise their capabilities to each other, and then compare their own capabilities with those they received from their link partners. The highest speed and duplex setting that is common to the two link partners is selected as the mode of operation.

The following list shows the speed and duplex operation mode from highest to lowest.

- Priority 1: 100Base-TX, full-duplex
- Priority 2: 100Base-TX, half-duplex
- Priority 3: 10Base-T, full-duplex
- Priority 4: 10Base-T, half-duplex

If auto-negotiation is not supported or the KSZ8041TL/FTL/MLL link partner is forced to bypass auto-negotiation, the KSZ8041TL/FTL/MLL sets its operating mode by observing the signal at its receiver. This is known as parallel detection, and allows the KSZ8041TL/FTL/MLL to establish link by listening for a fixed signal protocol in the absence of auto-negotiation advertisement protocol.

The auto-negotiation link up process is shown in the following flow chart.

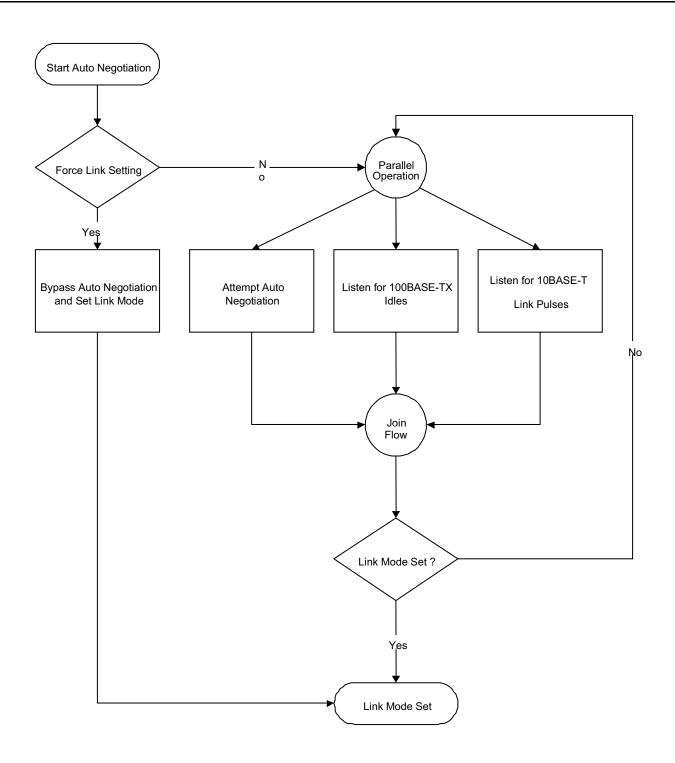


Figure 1. Auto-Negotiation Flow Chart

MII Management (MIIM) Interface

The KSZ8041TL/FTL/MLL supports the IEEE 802.3 MII Management Interface, also known as the Management Data Input / Output (MDIO) Interface. This interface allows upper-layer devices to monitor and control the state of the KSZ8041TL/FTL/MLL. An external device with MIIM capability is used to read the PHY status and/or configure the PHY settings. Further details on the MIIM interface can be found in Clause 22.2.4 of the IEEE 802.3 Specification.

The MIIM interface consists of the following:

- A physical connection that incorporates the clock line (MDC) and the data line (MDIO).
- A specific protocol that operates across the aforementioned physical connection that allows a external controller to communicate with one or more PHY devices. Each KSZ8041TL/FTL/MLL device is assigned a unique PHY address between 1 and 7 by its PHYAD[2:0] strapping pins. Also, every KSZ8041TL/FTL/MLL device supports the broadcast PHY address 0, as defined per the IEEE 802.3 Specification, which can be used to read/write to a single KSZ8041TL/FTL/MLL device, or write to multiple KSZ8041TL/FTL/MLL devices simultaneously.
- A set of 16-bit MDIO registers. Register [0:6] are required, and their functions are defined per the IEEE 802.3 Specification. The additional registers are provided for expanded functionality.

The following table shows the MII Management frame format for the KSZ8041TL/FTL/MLL.

	Preamble	Start of Frame	Read/Write OP Code	PHY Address Bits [4:0]	REG Address Bits [4:0]	ТА	Data Bits [15:0]	ldle
Read	32 1's	01	10	00AAA	RRRRR	Z0	DDDDDDDD_DDDDDDD	Z
Write	32 1's	01	01	00AAA	RRRRR	10	DDDDDDDD_DDDDDDD	Z

Table 1. Mll Management Frame Format

Interrupt (INTRP)

INTRP (pin 32) is an optional interrupt signal that is used to inform the external controller that there has been a status update to the KSZ8041TL/FTL/MLL PHY register. Bits[15:8] of register 1Bh are the interrupt control bits, and are used to enable and disable the conditions for asserting the INTRP signal. Bits[7:0] of register 1Bh are the interrupt status bits, and are used to indicate which interrupt conditions have occurred. The interrupt status bits are cleared after reading register 1Bh.

Bit 9 of register 1Fh sets the interrupt level to active high or active low.

MII Data Interface

The Media Independent Interface (MII) is specified in Clause 22 of the IEEE 802.3 Specification. It provides a common interface between physical layer and MAC layer devices, and has the following key characteristics:

- Supports 10Mbps and 100Mbps data rates.
- Uses a 25MHz reference clock, sourced by the PHY.
- Provides independent 4-bit wide (nibble) transmit and receive data paths.
- Contains two distinct groups of signals: one for transmission and the other for reception.

By default, the KSZ8041TL/FTL/MLL is configured to MII mode after it is power-up or reset with the following:

- A 25MHz crystal connected to XI, XO (pins 15, 14), or an external 25MHz clock source (oscillator) connected to XI.
- CONFIGURATION[2:0] (pins 27, 41, 40) set to '000' (default setting).

MII Signal Definition

The following table describes the MII signals. Refer to Clause 22 of the IEEE 802.3 Specification for detailed information.

MII Signal Name	Direction (with respect to PHY, KSZ8041TL/FTL/MLL signal)	Direction (with respect to MAC)	Description
TXC	Output	Input	Transmit Clock
			(2.5 MHz for 10Mbps; 25 MHz for 100Mbps)
TXEN	Input	Output	Transmit Enable
TXD[3:0]	Input	Output	Transmit Data [3:0]
RXC	Output	Input	Receive Clock
			(2.5 MHz for 10Mbps; 25 MHz for 100Mbps)
RXDV	Output	Input	Receive Data Valid
RXD[3:0]	Output	Input	Receive Data [3:0]
RXER	Output	Input, or (not required)	Receive Error
CRS	Output	Input	Carrier Sense
COL	Output	Input	Collision Detection

Table 2. MII Signal Definition

Transmit Clock (TXC)

TXC is sourced by the PHY. It is a continuous clock that provides the timing reference for TXEN and TXD[3:0]. TXC is 2.5MHz for 10Mbps operation and 25MHz for 100Mbps operation.

Transmit Enable (TXEN)

TXEN indicates the MAC is presenting nibbles on TXD[3:0] for transmission. It is asserted synchronously with the first nibble of the preamble and remains asserted while all nibbles to be transmitted are presented on the MII, and is negated prior to the first TXC following the final nibble of a frame.

TXEN transitions synchronously with respect to TXC.

Transmit Data [3:0] (TXD[3:0])

TXD[3:0] transitions synchronously with respect to TXC. When TXEN is asserted, TXD[3:0] are accepted for transmission by the PHY. TXD[3:0] is "00" to indicate idle when TXEN is de-asserted. Values other than "00" on TXD[3:0] while TXEN is de-asserted are ignored by the PHY.

Receive Clock (RXC)

RXC provides the timing reference for RXDV, RXD[3:0], and RXER.

- In 10Mbps mode, RXC is recovered from the line while carrier is active. RXC is derived from the PHY's reference clock when the line is idle, or link is down.
- In 100Mbps mode, RXC is continuously recovered from the line. If link is down, RXC is derived from the PHY's reference clock.

RXC is 2.5MHz for 10Mbps operation and 25MHz for 100Mbps operation.

Receive Data Valid (RXDV)

RXDV is driven by the PHY to indicate that the PHY is presenting recovered and decoded nibbles on RXD[3:0].

- In 10Mbps mode, RXDV is asserted with the first nibble of the SFD (Start of Frame Delimiter), "5D", and remains asserted until the end of the frame.
- In 100Mbps mode, RXDV is asserted from the first nibble of the preamble to the last nibble of the frame.

RXDV transitions synchronously with respect to RXC.

Receive Data [3:0] (RXD[3:0])

RXD[3:0] transitions synchronously with respect to RXC. For each clock period in which RXDV is asserted, RXD[3:0] transfers a nibble of recovered data from the PHY.

Receive Error (RXER)

RXER is asserted for one or more RXC periods to indicate that a Symbol Error (e.g. a coding error that a PHY is capable of detecting, and that may otherwise be undetectable by the MAC sub-layer) was detected somewhere in the frame presently being transferred from the PHY.

RXER transitions synchronously with respect to RXC. While RXDV is de-asserted, RXER has no effect on the MAC.

Carrier Sense (CRS)

CRS is asserted and de-asserted as follows:

- In 10Mbps mode, CRS assertion is based on the reception of valid preambles. CRS de-assertion is based on the reception of an end-of-frame (EOF) marker.
- In 100Mbps mode, CRS is asserted when a start-of-stream delimiter, or /J/K symbol pair is detected. CRS is deasserted when an end-of-stream delimiter, or /T/R symbol pair is detected. Additionally, the PMA layer de-asserts CRS if IDLE symbols are received without /T/R.

Collision (COL)

COL is asserted in half-duplex mode whenever the transmitter and receiver are simultaneously active on the line. This is used to inform the MAC that a collision has occurred during its transmission to the PHY.

COL transitions asynchronously with respect to TXC and RXC.

Reduced MII (RMII) Data Interface (KSZ8041TL/FTL only)

The Reduced Media Independent Interface (RMII) specifies a low pin count Media Independent Interface (MII). It provides a common interface between physical layer and MAC layer devices, and has the following key characteristics:

- Supports 10Mbps and 100Mbps data rates.
- Uses a single 50MHz reference clock provided by the MAC or the system board.
- Provides independent 2-bit wide (di-bit) transmit and receive data paths.
- Contains two distinct groups of signals: one for transmission and the other for reception.

The KSZ8041TL/FTL is configured in RMII mode after it is power-up or reset with the following:

- A 50 MHz reference clock connected to REFCLK (pin 15).
- CONFIG[2:0] (pins 27, 41, 40) set to '001'.

In RMII mode, unused MII signals, TXD[3:2] (pins 39, 38), are tied to ground.

RMII Signal Definition (KSZ8041TL/FTL only)

The following table describes the RMII signals. Refer to RMII Specification for detailed information.

RMII Signal Name	Direction (with respect to PHY, KSZ8041TL/FTL signal)	Direction (with respect to MAC)	Description		
REF_CLK	Input	Input, or Output	Synchronous 50 MHz clock reference for receive, transmit and control interface		
TX_EN	Input	Output	Transmit Enable		
TXD[1:0]	Input	Output	Transmit Data [1:0]		
CRS_DV	Output	Input	Carrier Sense/Receive Data Valid		
RXD[1:0]	Output	Input	Receive Data [1:0]		
RX_ER	Output	Input, or (not required)	Receive Error		

Table 3. RMII Signal Description

Reference Clock (REF_CLK)

REF_CLK is sourced by the MAC or system board. It is a continuous 50 MHz clock that provides the timing reference for TX_EN, TXD[1:0], CRS_DV, RXD[1:0], and RX_ER.

Transmit Enable (TX_EN)

TX_EN indicates that the MAC is presenting di-bits on TXD[1:0] for transmission. It is asserted synchronously with the first nibble of the preamble and remains asserted while all di-bits to be transmitted are presented on the RMII, and is negated prior to the first REF_CLK following the final di-bit of a frame.

TX_EN transitions synchronously with respect to REF_CLK.

Transmit Data [1:0] (TXD[1:0])

TXD[1:0] transitions synchronously with respect to REF_CLK. When TX_EN is asserted, TXD[1:0] are accepted for transmission by the PHY. TXD[1:0] is "00" to indicate idle when TX_EN is de-asserted. Values other than "00" on TXD[1:0] while TX_EN is de-asserted are ignored by the PHY.

Carrier Sense/Receive Data Valid (CRS_DV)

CRS_DV is asserted by the PHY when the receive medium is non-idle. It is asserted asynchronously on detection of carrier. This is when squelch is passed in 10Mbps mode, and when 2 non-contiguous zeroes in 10 bits are detected in 100Mbps mode. Loss of carrier results in the de-assertion of CRS_DV.

So long as carrier detection criteria are met, CRS_DV remains asserted continuously from the first recovered di-bit of the frame through the final recovered di-bit, and it is negated prior to the first REF_CLK that follows the final di-bit. The data on RXD[1:0] is considered valid once CRS_DV is asserted. However, since the assertion of CRS_DV is asynchronous relative to REF_CLK, the data on RXD[1:0] is "00" until proper receive signal decoding takes place.

Receive Data [1:0] (RXD[1:0])

RXD[1:0] transitions synchronously to REF_CLK. For each clock period in which CRS_DV is asserted, RXD[1:0] transfers two bits of recovered data from the PHY. RXD[1:0] is "00" to indicate idle when CRS_DV is de-asserted. Values other than "00" on RXD[1:0] while CRS_DV is de-asserted are ignored by the MAC.

Receive Error (RX_ER)

RX_ER is asserted for one or more REF_CLK periods to indicate that a Symbol Error (e.g. a coding error that a PHY is capable of detecting, and that may otherwise be undetectable by the MAC sub-layer) was detected somewhere in the frame presently being transferred from the PHY.

RX_ER transitions synchronously with respect to REF_CLK. While CRS_DV is de-asserted, RX_ER has no effect on the MAC.

Collision Detection

The MAC regenerates the COL signal of the MII from TX_EN and CRS_DV.

Serial MII (SMII) Data Interface (KSZ8041TL/FTL only)

The Serial Media Independent Interface (SMII) is the lowest pin count Media Independent Interface (MII). It provides a common interface between physical layer and MAC layer devices, and has the following key characteristics:

- Supports 10Mbps and 100Mbps data rates.
- Uses 125MHz reference clock provided by the MAC or the system board.
- Uses 12.5MHz sync pulse provided by the MAC.
- Provides independent single-bit wide transmit and receive data paths for data and control information.

The KSZ8041TL/FTL is configured in SMII mode after it is power-up or reset with the following:

- A 125MHz reference clock connected to CLOCK (pin 15).
- A 12.5MHz sync pulse connected to SYNC (pin 36).
- CONFIGURATION[2:0] (pins 27, 41, 40) set to '010'.

In SMII mode, unused MII signals, TXD[3:2] (pins 39, 38), are tied to ground.

SMII Signal Definition (KSZ8041TL/FTL only)

The following table describes the SMII signals. Refer to SMII Specification for detailed information.

SMII Signal Name	Direction (with respect to PHY, KSZ8041TL/FTL signal)	Direction (with respect to MAC)	Description		
CLOCK	Input	Input, or Output	125 MHz clock reference for receive and transmit data and control		
SYNC	Input	Output	12.5 MHz sync pulse from MAC		
ТХ	Input	Output	Transmit Data and Control		
RX	Output	Input	Receive Data and Control		

Table 4. SMII Signal Description

Clock Reference (CLOCK)

CLOCK is sourced by the MAC or system board. It is a continuous 125 MHz clock that provides the timing reference for SYNC, TX, and RX.

Sync Pulse (SYNC)

SYNC is a 12.5MHz synchronized pulse derived from CLOCK by the MAC. It is used to indicate the segment boundary for each transmit data/control segment, or receive data/control segment. Each segment is comprised of ten bits. SYNC is generated continuously by the MAC at every ten cycles of CLOCK.

Transmit Data and Control (TX)

TX provides transmit data and control information from MAC-to-PHY in 10-bit segments.

- In 10Mbps mode, each segment is repeated ten times. Therefore, every ten segments represent a new byte of data. The PHY can sample any one of every ten segments.
- In 100Mbps mode, each segment represents a new byte of data.

The following figure and table shows the transmit data/control format for each segment:

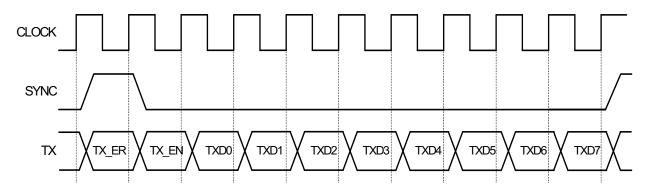


Figure 2. SMII Transmit Data/Control Segment

SMII TX Bit	Description
TX_ER	Transmit Error
TX_EN	Transmit Enable
TXD[0:7]	Encoded Data
	See SMII TXD[0:7] Encoding Table (below)

Table 5. SMII TX Bit Description

TX_ER	TX_EN	TXD0	TXD1	TXD2	TXD3	TXD4	TXD5	TXD6	TXD7
x	0	Use to force an error in a direct MAC-to- MAC connection	Speed 0=10M 1=100M	Duplex 0=Half 1=Full	Link 0=Down 1=Up	Jabber 0=No 1=Yes	1	1	1
Х	1	One Data By	One Data Byte						

Table 6. SMII TXD[0:7] Encoding Table

Receive Data and Control (RX)

RX provides receive data and control information from PHY-to-MAC in 10-bit segments.

- In 10Mbps mode, each segment is repeated ten times. Therefore, every ten segments represent a new byte of data. The MAC can sample any one of every ten segments.
- In 100Mbps mode, each segment represents a new byte of data.

The following figure and table shows the receive data/control format for each segment:

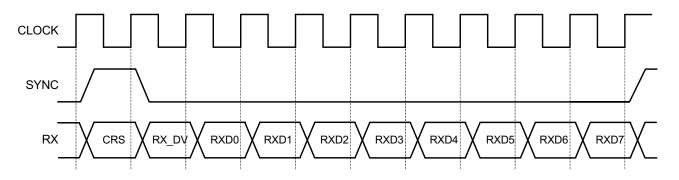


Figure 3. SMII Receive Data/Control Segment

SMII RX Bit	Description
CRS	Carrier Sense
RX_DV	Receive Data Valid
RXD[0:7]	Encoded Data
	See SMII RXD[0:7] Encoding Table (below)

Table 7. SMII RX Bit Description

CRS	RX_DV	RXD0	RXD1	RXD2	RXD3	RXD4	RXD5	RXD6	RXD7
X	0	RX_ER from pervious frame	Speed 0=10M 1=100M	Duplex 0=Half 1=Full	Link 0=Down 1=Up	Jabber 0=No 1=Yes	Upper Nibble 0=Invalid 1=Valid	False Carrier Detected	1
Х	1	One Data Byte							

Table 8. SMII RXD[0:7] Encoding Table

Collision Detection

Collisions occur when CRS and TX_EN are simultaneously asserted. The MAC regenerates the MII collision signal from CRS and TX_EN.

HP Auto MDI/MDI-X

HP Auto MDI/MDI-X configuration eliminates the confusion of whether to use a straight cable or a crossover cable between the KSZ8041TL/FTL/MLL and its link partner. This feature allows the KSZ8041TL/FTL/MLL to use either type of cable to connect with a link partner that is in either MDI or MDI-X mode. The auto-sense function detects transmit and receive pairs from the link partner, and then assigns transmit and receive pairs of the KSZ8041TL/FTL/MLL accordingly.

HP Auto MDI/MDI-X is enabled by default. It is disabled by writing a one to register 1F bit 13. MDI and MDI-X mode is selected by register 1F bit 14 if HP Auto MDI/MDI-X is disabled.

An isolation transformer with symmetrical transmit and receive data paths is recommended to support auto MDI/MDI-X. The IEEE 802.3 Standard defines MDI and MDI-X as follow:

М	DI	MDI-X		
RJ-45 Pin	Signal	RJ-45 Pin	Signal	
1	TD+	1	RD+	
2	TD-	2	RD-	
3	RD+	3	TD+	
6	RD-	6	TD-	

Table 9. MDI/MDI-X Pin Definition

Straight Cable

A straight cable connects a MDI device to a MDI-X device, or a MDI-X device to a MDI device. The following diagram depicts a typical straight cable connection between a NIC card (MDI) and a switch, or hub (MDI-X).

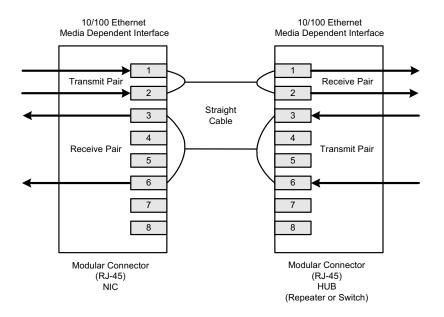


Figure 4. Typical Straight Cable Connection

Crossover Cable

A crossover cable connects a MDI device to another MDI device, or a MDI-X device to another MDI-X device. The following diagram depicts a typical crossover cable connection between two switches or hubs (two MDI-X devices).

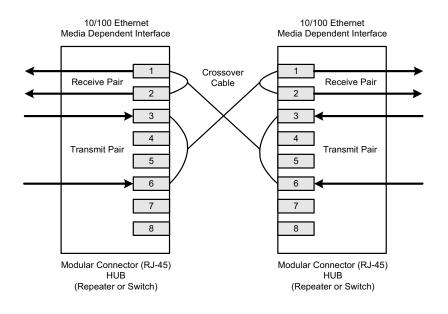


Figure 5. Typical Crossover Cable Connection

LinkMD[®] Cable Diagnostics

The LinkMD[®] feature utilizes time domain reflectometry (TDR) to analyze the cabling plant for common cabling problems, such as open circuits, short circuits and impedance mismatches.

LinkMD[®] works by sending a pulse of known amplitude and duration down the MDI and MDI-X pairs, and then analyzing the shape of the reflected signal. Timing the pulse duration gives an indication of the distance to the cabling fault with maximum distance of 200m and accuracy of +/-2m. Internal circuitry computes the TDR information and presents it in a user-readable digital format.

Note: Cable diagnostics are only valid for copper connections and do not support fiber optic operation.

Access

LinkMD[®] is initiated by accessing register 1Dh, the LinkMD[®] Control/Status Register, in conjunction with register 1Fh, the PHY Control 2 Register.

Usage

The following test procedure demonstrates how to use LinkMD[®] for cable diagnostic:

- 1. Disable auto MDI/MDI-X by writing a '1' to register 1Fh bit 13 to enable manual control over the differential pair used to transmit the LinkMD[®] pulse.
- 2. Select the differential pair to transmit the LinkMD[®] pulse with register 1Fh bit 14.
- 3. Start cable diagnostic test by writing a '1' to register 1Dh bit 15. This enable bit is self-clearing.
- 4. Wait (poll) for register 1Dh bit 15 to return a '0', indicating cable diagnostic test is completed.
- 5. Read cable diagnostic test results in register 1Dh bits [14:13]. The results are as follows:
 - 00 = normal condition (valid test)
 - 01 = open condition detected in cable (valid test)
 - 10 = short condition detected in cable (valid test)
 - 11 = cable diagnostic test failed (invalid test)

The '11' case, invalid test, occurs if the KSZ8041TL/FTL/MLL is unable to shut down the link partner. In this instance, the test is not run, since it would be impossible for the KSZ8041TL/FTL/MLL to determine if the detected signal is a reflection of the signal generated by the KSZ8041TL/FTL/MLL, or a signal from its link partner.

6. Get distance to fault by multiplying the decimal value in register 1Dh bits [8:0] by a constant of 0.4. The distance, D (expressed in meters), to the cable fault is determined by the following formula:

D (distance to cable fault) = 0.4 x {decimal value of register 1Dh bits [8:0]}

The 0.4 constant can be calibrated for different cable types and cabling conditions, such as cables with velocity of propagation that varies significantly from the norm.

Power Management

The KSZ8041TL/FTL/MLL offers the following power management modes:

Power Saving Mode

This mode is used to reduce power consumption when the cable is unplugged. It is in effect when auto-negotiation mode is enabled, cable is disconnected, and register 1Fh bit 10 is set to 1. Under power saving mode, the KSZ8041TL/FTL/MLL shuts down all transceiver blocks, except for transmitter, energy detect and PLL circuits. Additionally, in MII mode, the RXC clock output is disabled. RXC clock is enabled after the cable is connected and link is established.

Power saving mode is disabled by writing a zero to register 1Fh bit 10.

Power Down Mode

This mode is used to power down the entire KSZ8041TL/FTL/MLL device when it is not in use. Power down mode is enabled by writing a one to register 0h bit 11. In the power down state, the KSZ8041TL/FTL/MLL disables all internal functions, except for the MII management interface.

December 2009

Reference Clock Connection Options

A crystal or clock source, such as an oscillator, is used to provide the reference clock for the KSZ8041TL/FTL/MLL. The following figure illustrates how to connect the 25MHz crystal and oscillator reference clock for MII mode.

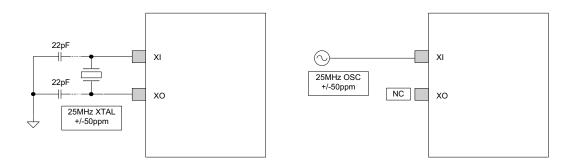


Figure 6. 25MHz Crystal / Oscillator Reference Clock for MII Mode

For the KSZ8041TL/FTL, the following figure illustrates how to connect the 50MHz oscillator reference clock for RMII mode.

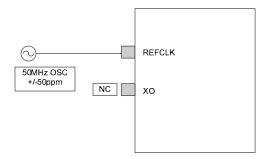


Figure 7. 50MHz Oscillator Reference Clock for RMII Mode

For the KSZ8041TL/FTL, the following figure illustrates how to connect the 125MHz oscillator reference clock for SMII mode.

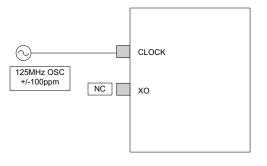


Figure 8. 125MHz Oscillator Reference Clock for SMII Mode

December 2009

Reference Circuit for Power and Ground Connections

The KSZ8041TL/FTL/MLL is a single 3.3V supply device with a built-in 1.8V low noise regulator. The power and ground connections are shown in the following figure and table.

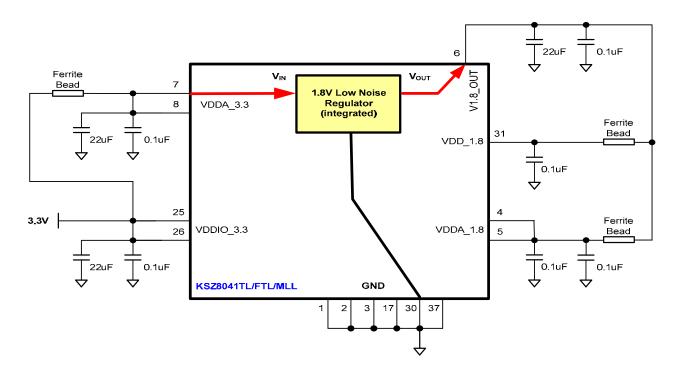


Figure 9. KSZ8041TL/FTL/MLL Power and Ground Connections

Power Pin	Pin Number	Pin Type	Description
V1.8_OUT	6	Output	1.8V supply output from KSZ8041TL/FTL/MLL
			Decouple with 22uF and 0.1uF capacitors to ground.
VDD_1.8	31	Input	Connect to V1.8_OUT (pin 6) thru ferrite bead.
			Decouple with 0.1uF capacitor to ground.
VDDA_1.8	4, 5	Input	Connect to V1.8_OUT (pin 6) thru ferrite bead.
			Decouple with 0.1uF capacitor on each pin to ground.
VDDIO_3.3	25, 26	Input	Connect to board's 3.3V supply.
			Decouple with 22uF and 0.1uF capacitors to ground.
VDDA_3.3	7, 8	Input	Connect to board's 3.3V supply thru ferrite bead.
			Decouple with 22uF and 0.1uF capacitors to ground.

Table 10. KSZ8041TL/FTL/MLL Power Pin Description

100Base-FX Fiber Operation (KSZ8041FTL only)

100Base-FX fiber operation is similar to 100Base-TX copper operation with the differences being that the scrambler/descrambler and MLT3 encoder/decoder are bypassed on transmission and reception. In addition, auto-negotiation is bypassed, auto MDI/MDI-X is disabled, and speed is set to 100Mbps. The duplex can be set to either half or full. Usually, it is set to full-duplex.

Fiber Signal Detect

In 100Base-FX operation, FXSD (fiber signal detect), input pin 48, is usually connected to the fiber transceiver SD (signal detect) output pin. 100Base-FX mode is activated when the FXSD input pin is greater than 1V. When FXSD is between 1V and 1.8V, no fiber signal is detected and a Far-End Fault is generated. When FXSD is over 2.2V, the fiber signal is detected.

100Base-FX mode and signal detection is summarized in the following table:

FXSD Input Voltage	Mode	
Less than 0.2V	Copper mode	
Greater than 1V, but less than 1.8V	Fiber mode	
	No signal detected	
	Far-End Fault generated (if enabled)	
Greater than 2.2V	Fiber mode	
	Signal detected	

Table 11. Copper and Fiber Mode Selection

To ensure proper operation, a resistive voltage divider is recommended to adjust the fiber transceiver SD (signal detect) output voltage swing to match the FXSD pin's input voltage threshold.

Alternatively, the Far-End Fault feature can be disabled. In this case, the FXSD input pin is tied high to 3.3V to force 100Base-FX mode.

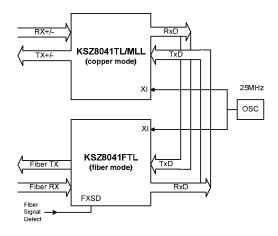
Far-End Fault

A Far-End Fault (FEF) occurs when the signal detection is logically false on the receive side of the fiber transceiver. The KSZ8041FTL detects a FEF when its FXSD input (pin 48) is between 1V and 1.8V. When a FEF is detected, the KSZ8041FTL signals its fiber link partner that a FEF has occurred by transmitting a repetitive pattern of 84-ones and 1-zero. This pattern is used to inform the fiber link partner that there is a faulty link on its transmit side.

By default, FEF is enabled. FEF is disabled by strapping "no FEF" (pin 43) low. See "Strapping Options" section for detail.

Back-to-Back Media Converter

A KSZ8041TL/MLL and a KSZ8041FTL can be connected back-to-back to provide a low cost media converter solution. In back-to-back mode, media conversion is between 100Base-TX copper and 100Base-FX fiber. On the copper side, link up at 10Base-T is not allowed, and is blocked during auto-negotiation.





MII Back-to-Back Mode

In MII Back-to-Back mode, the KSZ8041TL/MLL interfaces with another KSZ8041TL/MLL, or a KSZ8041FTL to provide a complete 100Mbps repeater or media converter solution. The KSZ8041TL/FTL/MLL devices are configured to MII Back-to-Back mode after they are power-up or reset with the following:

- CONFIGURATION[2:0] (pins 27, 41, 40) set to '110'
- A common 25MHz reference clock connected to XI (pin 15)
- MII signals connected as shown in the following table.

	•	MLL (100Base-TX copper) 1TL (100Base-TX copper) KSZ8041MLL (100Base-TX copper) KSZ8041FTL (100Base-TX fiber			copper)
Pin Name	Pin Number	Pin Type	Pin Name	Pin Number	Pin Type
RXC	28	Output	TXC	33	Input
RXDV	27	Output	TXEN	34	Input
RXD3	20	Output	TXD3	39	Input
RXD2	21	Output	TXD2	38	Input
RXD1	22	Output	TXD1	36	Input
RXD0	23	Output	TXD0	35	Input
TXC	33	Input	RXC	28	Output
TXEN	34	Input	RXDV	27	Output
TXD3	39	Input	RXD3	20	Output
TXD2	38	Input	RXD2	21	Output
TXD1	36	Input	RXD1	22	Output
TXD0	35	Input	RXD0	23	Output

Table 12	. MII Signal Connection	for MII Back-to-Back Mode
----------	-------------------------	---------------------------

RMII Back-to-Back Mode (KSZ8041TL/FTL only)

In RMII Back-to-Back mode, the KSZ8041TL interfaces with another KSZ8041TL, or a KSZ8041FTL to provide a complete 100Mbps repeater or media converter solution. The KSZ8041TL/FTL devices are configured to RMII Back-to-Back mode after they are power-up or reset with the following:

- CONFIGURATION[2:0] (pins 27, 41, 40) set to '101'
- A common 50MHz reference clock connected to REFCLK (pin 15)
- RMII signals connected as shown in the following table.

KSZ8041TL (100Base-TX copper)				1TL (100Base-TX 41FTL (100Base-F	,
Pin Name	Pin Number	Pin Type	Pin Name	Pin Number	Pin Type
CRSDV	27	Output	TXEN	34	Input
RXD1	22	Output	TXD1	36	Input
RXD0	23	Output	TXD0	35	Input
TXEN	34	Input	CRSDV	27	Output
TXD1	36	Input	RXD1	22	Output
TXD0	35	Input	RXD0	23	Output

Table 13. RMII Signal Connection for RMII Back-to-Back Mode

RMII Back-to-Back mode provides an option to disable the fiber side when the copper side is down. This, effectively, produces a link fault propagation for media converter applications, such that a copper side link down will automatically disable the fiber side. This KSZ8041TL/FTL feature functions as follows:

- On the KSZ8041TL copper side, RXD2 (pin 21) indicates if there is energy detected at the receive inputs of the copper port. RXD2 outputs a low if there is no energy detected (cable disconnected), and outputs a high if there is energy detected (cable connected).
- The RXD2 output of the KSZ8041TL copper side drives the input of an inverter, and the output of the inverter drives the TXD2 (pin 38) input of the KSZ8041FTL fiber side. The fiber side transmitter is disabled if the TXD2 input is high.

The TXD3 and TXD2 pins should be pulled down with 1K resistors, and RXD3 and RXD2 pins should be left floating, if they are not used.

Register Map

Register Number (Hex)	Description
Oh	Basic Control
1h	Basic Status
2h	PHY Identifier 1
3h	PHY Identifier 2
4h	Auto-Negotiation Advertisement
5h	Auto-Negotiation Link Partner Ability
6h	Auto-Negotiation Expansion
7h	Auto-Negotiation Next Page
8h	Link Partner Next Page Ability
9h – 13h	Reserved
14h	MII Control
15h	RXER Counter
16h – 1Ah	Reserved
1Bh	Interrupt Control/Status
1Ch	Reserved
1Dh	LinkMD [®] Control/Status
1Eh	PHY Control 1
1Fh	PHY Control 2

Register Description

Address	Name	Description	Mode ⁽¹⁾	Default
Register 0h	n – Basic Control			
0.15	Reset	1 = Software reset	RW/SC	0
		0 = Normal operation		
		This bit is self-cleared after a '1' is written to it.		
0.14	Loop-back	1 = Loop-back mode	RW	0
		0 = Normal operation		
0.13	Speed Select	1 = 100Mbps	RW	Set by SPEED strapping pin.
	(LSB)	0 = 10Mbps		See "Strapping Options" section
		This bit is ignored if auto-negotiation is enabled (register $0.12 = 1$).		for details.
0.12	Auto-	1 = Enable auto-negotiation process	RW	Set by NWAYEN strapping pin.
	Negotiation Enable	0 = Disable auto-negotiation process		See "Strapping Options" section
		If enabled, auto-negotiation result overrides settings in register 0.13 and 0.8.		for details.
0.11	Power Down	1 = Power down mode	RW	0
		0 = Normal operation		
0.10	Isolate	1 = Electrical isolation of PHY from MII and	RW	Set by ISO strapping pin.
		TX+/TX-		See "Strapping Options" section
		0 = Normal operation		for details.
0.9	Restart Auto-	1 = Restart auto-negotiation process	RW/SC	0
	Negotiation	0 = Normal operation.		
		This bit is self-cleared after a '1' is written to it.		

Address	Name	Description	Mode ⁽¹⁾	Default
0.8	Duplex Mode	1 = Full-duplex	RW	Inverse of DUPLEX strapping pin
		0 = Half-duplex		value.
				See "Strapping Options" section for details.
0.7	Collision Test	1 = Enable COL test	RW	0
		0 = Disable COL test		
0.6:1	Reserved		RO	000_000
0.0	Disable	0 = Enable transmitter	RW	0
	Transmitter	1 = Disable transmitter		
Register 1h	– Basic Status			
1.15	100Base-T4	1 = T4 capable	RO	0
		0 = Not T4 capable		
1.14	100Base-TX	100Base-TX 1 = Capable of 100Mbps full-duplex RO	RO	1
	Full Duplex	0 = Not capable of 100Mbps full-duplex		
1.13	100Base-TX	1 = Capable of 100Mbps half-duplex	RO	1
	Half Duplex	0 = Not capable of 100Mbps half-duplex		
1.12	10Base-T Full	1 = Capable of 10Mbps full-duplex	RO	1
	Duplex	0 = Not capable of 10Mbps full-duplex		
1.11	10Base-T Half	1 = Capable of 10Mbps half-duplex	RO	1
	Duplex	0 = Not capable of 10Mbps half-duplex		
1.10:7	Reserved		RO	0000
1.6	No Preamble	1 = Preamble suppression	RO	1
		0 = Normal preamble		
1.5	Auto-	1 = Auto-negotiation process completed	RO	0
	Negotiation Complete	0 = Auto-negotiation process not completed		
1.4	Remote Fault	1 = Remote fault	RO/LH	0
		0 = No remote fault		
1.3	Auto-	1 = Capable to perform auto-negotiation	RO	1
	Negotiation	0 = Not capable to perform auto-negotiation		
1.0	Ability			
1.2	Link Status	1 = Link is up 0 = Link is down	RO/LL	0
1.1	labbar Dataat	1 = Jabber detected	RO/LH	0
1.1	Jabber Detect	0 = Jabber not detected (default is low)	KU/LH	0
1.0	Extended	1 = Supports extended capabilities registers	RO	1
1.0	Capability	i – Supports extended capabilities registers	KU	
Register 2h	– PHY Identifier 1			
2.15:0	PHY ID	Assigned to the 3rd through 18th bits of the	RO	0022h
	Number	Organizationally Unique Identifier (OUI). Kendin Communication's OUI is 0010A1 (hex)		

Address	Name	Description	Mode ⁽¹⁾	Default
Register 3h	– PHY Identifier 2			
3.15:10	PHY ID Number	Assigned to the 19th through 24 th bits of the Organizationally Unique Identifier (OUI). Kendin Communication's OUI is 0010A1 (hex)	RO	0001_01
3.9:4	Model Number	Six bit manufacturer's model number	RO	01_0001
3.3:0	Revision Number	Four bit manufacturer's revision number	RO	Indicate silicon revision
Register 4h	– Auto-Negotiatio	n Advertisement		
4.15	Next Page	1 = Next page capable	RW	0
		0 = No next page capability.		
4.14	Reserved		RO	0
4.13	Remote Fault	1 = Remote fault supported	RW	0
		0 = No remote fault		
4.12	Reserved		RO	0
4.11:10	Pause	[00] = No PAUSE	RW	00
		[10] = Asymmetric PAUSE		
		[01] = Symmetric PAUSE		
		[11] = Asymmetric & Symmetric PAUSE		
4.9	100Base-T4	1 = T4 capable	RO	0
		0 = No T4 capability		
4.8	100Base-TX	1 = 100Mbps full-duplex capable	RW	Set by SPEED strapping pin.
	Full-Duplex	0 = No 100Mbps full-duplex capability		See "Strapping Options" section for details.
4.7	100Base-TX	1 = 100Mbps half-duplex capable	RW	Set by SPEED strapping pin.
	Half-Duplex	0 = No 100Mbps half-duplex capability		See "Strapping Options" section for details.
4.6	10Base-T	1 = 10Mbps full-duplex capable	RW	1
	Full-Duplex	0 = No 10Mbps full-duplex capability		
4.5	10Base-T	1 = 10Mbps half-duplex capable	RW	1
	Half-Duplex	0 = No 10Mbps half-duplex capability		
4.4:0	Selector Field	[00001] = IEEE 802.3	RW	0_0001
Register 5h	– Auto-Negotiatio	n Link Partner Ability		
5.15	Next Page	1 = Next page capable	RO	0
		0 = No next page capability		
5.14	Acknowledge	1 = Link code word received from partner	RO	0
		0 = Link code word not yet received		
5.13	Remote Fault	1 = Remote fault detected	RO	0
		0 = No remote fault		
5.12	Reserved		RO	0
5.11:10	Pause	[00] = No PAUSE	RO	00
		[10] = Asymmetric PAUSE		
		[01] = Symmetric PAUSE		
		[11] = Asymmetric & Symmetric PAUSE		

Address	Name	Description	Mode ⁽¹⁾	Default
5.9	100Base-T4	1 = T4 capable	RO	0
		0 = No T4 capability		
5.8	100Base-TX	1 = 100Mbps full-duplex capable	RO	0
	Full-Duplex	0 = No 100Mbps full-duplex capability		
5.7	100Base-TX	1 = 100Mbps half-duplex capable	RO	0
	Half-Duplex	0 = No 100Mbps half-duplex capability		
5.6	10Base-T	1 = 10Mbps full-duplex capable	RO	0
	Full-Duplex	0 = No 10Mbps full-duplex capability		
5.5	10Base-T	1 = 10Mbps half-duplex capable	RO	0
	Half-Duplex	0 = No 10Mbps half-duplex capability		
5.4:0	Selector Field	[00001] = IEEE 802.3	RO	0_0001
Register 6h	– Auto-Negotiatio	n Expansion		
6.15:5	Reserved	•	RO	0000_0000_000
6.4	Parallel	1 = Fault detected by parallel detection	RO/LH	0
	Detection Fault	0 = No fault detected by parallel detection.		
6.3	Link Partner	1 = Link partner has next page capability	RO	0
	Next Page Able	0 = Link partner does not have next page capability		
6.2	Next Page	1 = Local device has next page capability	RO	1
	Able	0 = Local device does not have next page capability		
6.1	Page Received	1 = New page received	RO/LH	0
		0 = New page not received yet		
6.0	Link Partner	1 = Link partner has auto-negotiation capability	RO	0
	Auto- Negotiation Able	0 = Link partner does not have auto-negotiation capability		
Register 7h	- Auto-Negotiatio	n Next Page		
7.15	Next Page	1 = Additional next page(s) will follow	RW	0
		0 = Last page		
7.14	Reserved		RO	0
7.13	Message Page	1 = Message page	RW	1
		0 = Unformatted page		
7.12	Acknowledge2	1 = Will comply with message	RW	0
		0 = Cannot comply with message		
7.11	Toggle	1 = Previous value of the transmitted link code word equaled logic one	RO	0
		0 = Logic zero		
7.10:0	Message Field	11-bit wide field to encode 2048 messages	RW	000_0000_0001
Register 8h	– Link Partner Nex	t Page Ability		
8.15	Next Page	1 = Additional Next Page(s) will follow	RO	0
0.15				

Address	Name	Description	Mode ⁽¹⁾	Default
8.14	Acknowledge	1 = Successful receipt of link word	RO	0
		0 = No successful receipt of link word		
8.13	Message Page	1 = Message page	RO	0
		0 = Unformatted page		
8.12	Acknowledge2	1 = Able to act on the information	RO	0
		0 = Not able to act on the information		
8.11	Toggle	1 = Previous value of transmitted link code word equal to logic zero	RO	0
		0 = Previous value of transmitted link code word equal to logic one		
8.10:0	Message Field		RO	000_0000_0000
Register 14	h – MII Control			
14.15:8	Reserved		RO	0000_0000
14.7	100Base-TX Preamble Restore	 1 = Restore received preamble to MII output (random latency) 0 = Consume 1-byte preamble before sending frame to MII output for fixed latency 	RW	0 or 1 (if CONFIG[2:0] = 100) See "Strapping Options" section for details.
14.6	10Base-T Preamble Restore	 1 = Restore received preamble to MII output 0 = Remove all 7-bytes of preamble before sending frame (starting with SFD) to MII output 	RW	0
14.5:0	Reserved		RO	00_0001
Register 15	h – RXER Counter			
15.15:0	RXER Counter	Receive error counter for Symbol Error frames	RO/SC	0000h
Register 1B	Sh – Interrupt Contr			
1b.15	Jabber	1 = Enable Jabber Interrupt	RW	0
	Interrupt Enable	0 = Disable Jabber Interrupt		
1b.14	Receive Error	1 = Enable Receive Error Interrupt	RW	0
	Interrupt Enable	0 = Disable Receive Error Interrupt		
1b.13	Page Received Interrupt Enable	1 = Enable Page Received Interrupt 0 = Disable Page Received Interrupt	RW	0
1b.12	Parallel Detect Fault Interrupt Enable	1 = Enable Parallel Detect Fault Interrupt 0 = Disable Parallel Detect Fault Interrupt	RW	0
1b.11	Link Partner Acknowledge Interrupt Enable	 1 = Enable Link Partner Acknowledge Interrupt 0 = Disable Link Partner Acknowledge Interrupt 	RW	0
1b.10	Link Down Interrupt Enable	1 = Enable Link Down Interrupt 0 = Disable Link Down Interrupt	RW	0
1b.9	Remote Fault Interrupt Enable	1 = Enable Remote Fault Interrupt 0 = Disable Remote Fault Interrupt	RW	0

Address	Name	Description	Mode ⁽¹⁾	Default
1b.8	Link Up Interrupt Enable	1 = Enable Link Up Interrupt 0 = Disable Link Up Interrupt	RW	0
1b.7	Jabber Interrupt	1 = Jabber occurred 0 = Jabber did not occurred	RO/SC	0
1b.6	Receive Error Interrupt	1 = Receive Error occurred 0 = Receive Error did not occurred	RO/SC	0
1b.5	Page Receive Interrupt	1 = Page Receive occurred 0 = Page Receive did not occurred	RO/SC	0
1b.4	Parallel Detect Fault Interrupt	1 = Parallel Detect Fault occurred 0 = Parallel Detect Fault did not occurred	RO/SC	0
1b.3	Link Partner Acknowledge Interrupt	1 = Link Partner Acknowledge occurred0 = Link Partner Acknowledge did not occurred	RO/SC	0
1b.2	Link Down Interrupt	1 = Link Down occurred 0 = Link Down did not occurred	RO/SC	0
1b.1	Remote Fault Interrupt	1 = Remote Fault occurred0 = Remote Fault did not occurred	RO/SC	0
1b.0	Link Up Interrupt	1 = Link Up occurred 0 = Link Up did not occurred	RO/SC	0
Register 1D	h – LinkMD [®] Conti	rol/Status		
1d.15	Cable Diagnostic Test Enable	 1 = Enable cable diagnostic test. After test has completed, this bit is self-cleared. 0 = Indicates cable diagnostic test (if enabled) has completed and the status information is valid for read. 	RW/SC	0
1d.14:13	Cable Diagnostic Test Result	 [00] = normal condition [01] = open condition has been detected in cable [10] = short condition has been detected in cable [11] = cable diagnostic test has failed 	RO	00
1d.12:9	Reserved			0000
1d.8:0	Cable Fault Counter	Distance to fault; it's approximately 0.4m*(Cable Fault Counter value in decimal)	RO	0_0000_0000
Register 1E	h – PHY Control 1	· · · · · · · · · · · · · · · · · · ·	1	
1e.15:14	LED mode	[00] = LED1 : Speed LED0 : Link/Activity [01] = LED1 : Activity LED0 : Link [10], [11] = Reserved	RW	00
1e.13	Polarity	0 = Polarity is not reversed 1 = Polarity is reversed	RO	

Address	Name	Description	Mode ⁽¹⁾	Default
1e.12	Far-End Fault	0 = Far-End Fault not detected	RO	0
	Detect	1 = Far-End Fault detected		
		This bit applies to KSZ8041FTL fiber only.		
1e.11	MDI/MDI-X	0 = MDI	RO	
	State	1 = MDI-X		
1e.10:8	Reserved			
1e.7	Remote	0 = Normal mode	RW	0
	loopback	1 = Remote (analog) loop back is enable		
1e.6:0	Reserved			
Register 1F	h – PHY Control 2		_ I	
1f.15	HP_MDIX	0 = Micrel Auto MDI/MDI-X mode	RW	1
	_	1 = HP Auto MDI/MDI-X mode		
1f.14	MDI/MDI-X	When Auto MDI/MDI-X is disabled,	RW	0
	Select	0 = MDI Mode		
		Transmit on TX+/- (pins 12,11) and Receive on RX+/- (pins 10,9)		
		1 = MDI-X Mode		
		Transmit on RX+/- (pins 10,9) and Receive on TX+/- (pins 12,11)		
1f.13	Pairswap	1 = Disable auto MDI/MDI-X	RW	0
	Disable	0 = Enable auto MDI/MDI-X		
1f.12	Energy Detect	1 = Presence of signal on RX+/- analog wire pair	RO	0
		0 = No signal detected on RX+/-		
1f.11	Force Link	1 = Force link pass	RW	0
		0 = Normal link operation		
		This bit bypasses the control logic and allow transmitter to send pattern even if there is no link.		
1f.10	Power Saving	1 = Enable power saving	RW	0
		0 = Disable power saving		
		If power saving mode is enabled and the cable is disconnected, the RXC clock output (in MII mode) is disabled. RXC clock is enabled after the cable is connected and link is established.		
1f.9	Interrupt Level	1 = Interrupt pin active high	RW	0
		0 = Interrupt pin active low		
1f.8	Enable Jabber	1 = Enable jabber counter	RW	1
		0 = Disable jabber counter		
1f.7	Auto-	1 = Auto-negotiation process completed	RO	0
	Negotiation Complete	0 = Auto-negotiation process not completed		
1f.6	Enable Pause	1 = Flow control capable	RO	0
	(Flow Control)	0 = No flow control capability		

Address	Name	Description	Mode ⁽¹⁾	Default
1f.5	PHY Isolate	1 = PHY in isolate mode	RO	0
		0 = PHY in normal operation		
1f.4:2	Operation	[000] = still in auto-negotiation	RO	000
	Mode Indication	[001] = 10Base-T half-duplex		
	Indication	[010] = 100Base-TX half-duplex		
		[011] = reserved		
		[101] = 10Base-T full-duplex		
		[110] = 100Base-TX full-duplex		
		[111] = reserved		
1f.1	1f.1 Enable SQE test	1 = Enable SQE test	RW	0
		0 = Disable SQE test		
1f.0	Disable Data	1 = Disable scrambler	RW	0
	Scrambling	0 = Enable scrambler		

Note:

1. RW = Read/Write.

RO = Read only.

SC = Self-cleared.

LH = Latch high.

LL = Latch low.

Absolute Maximum Ratings⁽¹⁾

Supply Voltage

0.5V to +2.4V
0.5V to +4.0V
0.5V to +4.0V
0.5V to +4.0V
260°C
55°C to +150°C

Operating Ratings⁽²⁾

Supply Voltage

(V _{DDIO_3.3} , V _{DDA_3.3})	+3.135V to +3.465V
Ambient Temperature (T _A , Comm	ercial) 0°C to +70°C
Ambient Temperature (T _A , Industr	ial)40°C to +85°C
Maximum Junction Temperature (T _J Max) 125°C
Thermal Resistance (θ_{JA})	
Thermal Resistance (θ_{JC})	15°C/W

Electrical Characteristics⁽³⁾

Symbol	Parameter	Condition	Min	Тур	Max	Units
Supply C	urrent ⁽⁴⁾					
I _{DD1}	100Base-TX	Chip only (no transformer);		53.0	58.3	mA
		Full-duplex traffic @ 100% utilization				
I _{DD2}	10Base-T	Chip only (no transformer);		38.0	41.8	mA
		Full-duplex traffic @ 100% utilization				
I _{DD3}	Power Saving Mode	Ethernet cable disconnected (reg. 1F.10 = 1)		32.0	35.2	mA
I _{DD4}	Power Down Mode	Software power down (reg. 0.11 = 1)		4.0	4.4	mA
TTL Input	s					
VIH	Input High Voltage		2.0			V
V _{IL}	Input Low Voltage				0.8	V
I _{IN}	Input Current	$V_{IN} = GND \sim V_{DDIO}$		-10	10	μA
TTL Outp	uts					
V _{OH}	Output High Voltage	$I_{OH} = -4mA$	2.4			V
V _{OL}	Output Low Voltage	I _{OL} = 4mA			0.4	V
I _{oz}	Output Tri-State Leakage				10	μA
LED Outp	uts		•			
I _{LED}	Output Drive Current	Each LED pin (LED0, LED1)		8		mA
100Base-	TX Transmit (measured differentia	ally after 1:1 transformer)				
Vo	Peak Differential Output Voltage	100Ω termination across differential output	0.95		1.05	V
VIMB	Output Voltage Imbalance	100Ωtermination across differential output			2	%
t _r , t _f	Rise/Fall Time		3		5	Ns
	Rise/Fall Time Imbalance		0		0.5	Ns
	Duty Cycle Distortion				± 0.25	Ns
	Overshoot				5	%
V _{SET}	Reference Voltage of ISET			0.65		V
	Output Jitter	Peak-to-peak		0.7	1.4	Ns
10Base-T	Transmit (measured differentially	/ after 1:1 transformer)	•			
VP	Peak Differential Output Voltage	100 Ω termination across differential output	2.2		2.8	V
	Jitter Added	Peak-to-peak			3.5	Ns
t _r , t _f	Rise/Fall Time			25		ns
10Base-T	Receive			•		
V _{SQ}	Squelch Threshold	5MHz square wave		400		mV

Notes:

- 1. Exceeding the absolute maximum rating may damage the device. Stresses greater than the absolute maximum rating may cause permanent damage to the device. Operation of the device at these or any other conditions above those specified in the operating sections of this specification is not implied. Maximum conditions for extended periods may affect reliability.
- 2. The device is not guaranteed to function outside its operating rating.
- 3. $T_A = 25^{\circ}C$. Specification for packaged product only.
- 4. Current consumption is for the single 3.3V supply KSZ8041TL/FTL/MLL device only, and includes the 1.8V supply voltage (V_{DD_1.8}, V_{DDA_1.8}, V_{1.8_OUT}) that is provided by the KSZ8041TL/FTL/MLL. The PHY port's transformer consumes an additional 45mA @ 3.3V for 100Base-TX and 70mA @ 3.3V for 100Base-T.

Timing Diagrams

MII SQE Timing (10Base-T)

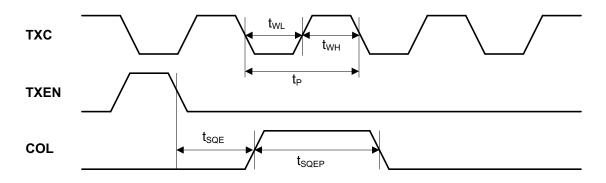
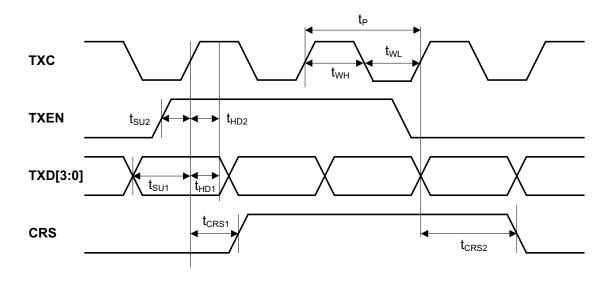


Figure 11. MII SQE Timing (10Base-T)

Timing Parameter	Description	Min	Тур	Max	Unit
t _P	TXC period		400		ns
t _{WL}	TXC pulse width low		200		ns
t _{wн}	TXC pulse width high		200		ns
t _{SQE}	COL (SQE) delay after TXEN de-asserted		2.5		μs
t _{SQEP}	COL (SQE) pulse duration		1.0		μs

Table 14. MII SQE Timing (10Base-T) Parameters

MII Transmit Timing (10Base-T)





Timing Parameter	Description	Min	Тур	Max	Unit
t _P	TXC period		400		ns
t _{WL}	TXC pulse width low		200		ns
t _{WH}	TXC pulse width high		200		ns
t _{SU1}	TXD[3:0] setup to rising edge of TXC	10			ns
t _{SU2}	TXEN setup to rising edge of TXC	10			ns
t _{HD1}	TXD[3:0] hold from rising edge of TXC	0			ns
t _{HD2}	TXEN hold from rising edge of TXC	0			ns
t _{CRS1}	TXEN high to CRS asserted latency		160		ns
t _{CRS2}	TXEN low to CRS de-asserted latency		510		ns

Table 15. MII Transmit Timing (10Base-T) Parameters

MII Receive Timing (10Base-T)

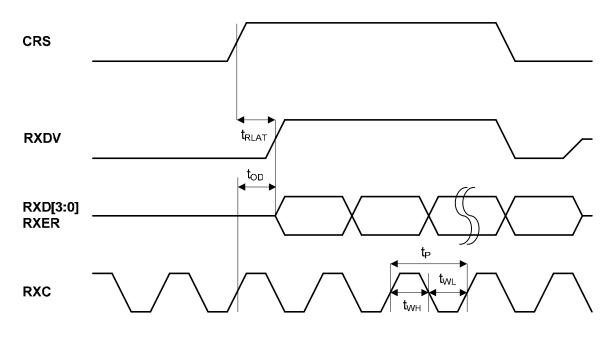


Figure 13. MII Receive Timing (10Base-T)

Timing Parameter	Description	Min	Тур	Max	Unit
t _P	RXC period		400		ns
t _{WL}	RXC pulse width low		200		ns
t _{WH}	RXC pulse width high		200		ns
t _{OD}	(RXD[3:0], RXER, RXDV) output delay from rising edge of RXC	182		225	ns
t _{RLAT}	CRS to (RXD[3:0], RXER, RXDV) latency		6.5		μ S

Table 16. MII Receive Timing (10Base-T) Parameters

MII Transmit Timing (100Base-TX)

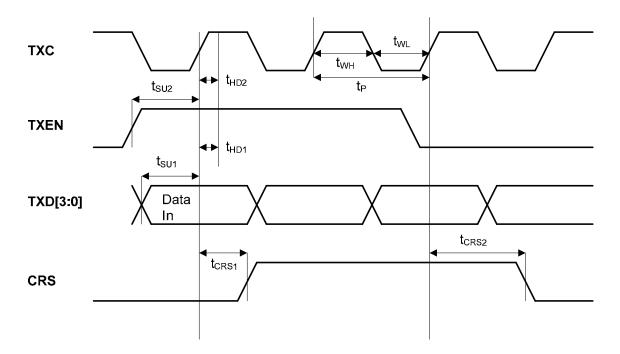
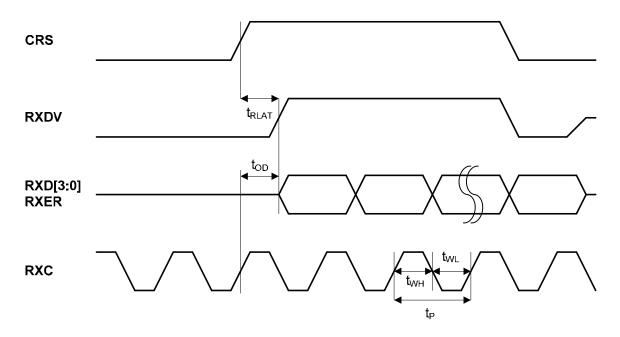


Figure 14. MII Transmit Timing (100Base-TX)

Timing Parameter	Description	Min	Тур	Max	Unit
t _P	TXC period		40		ns
t _{WL}	TXC pulse width low		20		ns
t _{WH}	TXC pulse width high		20		ns
t _{su1}	TXD[3:0] setup to rising edge of TXC	10			ns
t _{SU2}	TXEN setup to rising edge of TXC	10			ns
t _{HD1}	TXD[3:0] hold from rising edge of TXC	0			ns
t _{HD2}	TXEN hold from rising edge of TXC	0			ns
t _{CRS1}	TXEN high to CRS asserted latency		34		ns
t _{CRS2}	TXEN low to CRS de-asserted latency		33		ns

Table 17.	MII Transmit Timing	(100Base-TX) Parameters
-----------	---------------------	-------------------------

MII Receive Timing (100Base-TX)





Timing Parameter	Description	Min	Тур	Max	Unit
t _P	RXC period		40		ns
t _{WL}	RXC pulse width low		20		ns
t _{WH}	RXC pulse width high		20		ns
top	(RXD[3:0], RXER, RXDV) output delay from rising edge of RXC	19		25	ns
t _{RLAT}	CRS to RXDV latency		140		ns
	CRS to RXD[3:0] latency		52		ns
	CRS to RXER latency		60		ns

Table 18. MII Receive Timing (100Base-TX) Parameters

RMII Timing

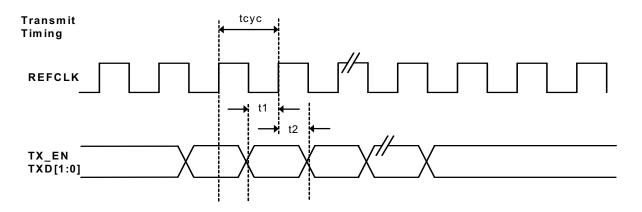


Figure 16. RMII Timing – Data Received from RMII

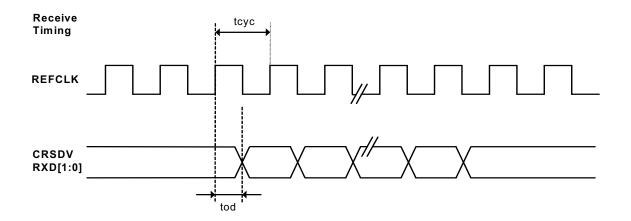


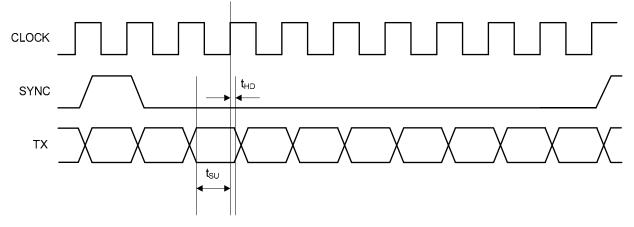
Figure 17. RMII Timing – Data Input to RMII

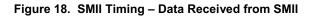
Timing Parameter	Description	Min	Тур	Max	Unit
t _{cyc}	Clock cycle		20		ns
t ₁	Setup time	4			ns
t ₂	Hold time	2			ns
t _{od}	Output delay	3		9	ns

Table 19. RMII Timing Parameters

SMII Timing







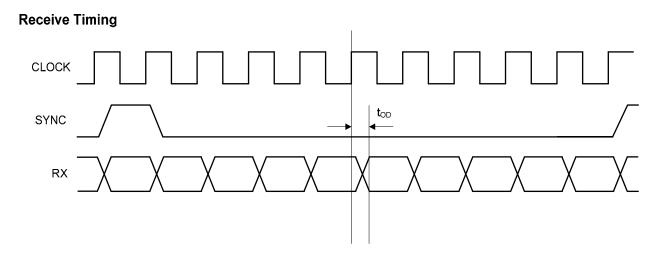


Figure 19. SMII Timing – Data Input to SMII

Timing Parameter	Description	Min	Тур	Max	Unit
t _{SU}	Setup time	1.5			ns
t _{HD}	Hold time	1.0			ns
t _{OD}	Output delay	4.0		5.0	ns

Table 20. SMII Timing Parameters

Auto-Negotiation Timing

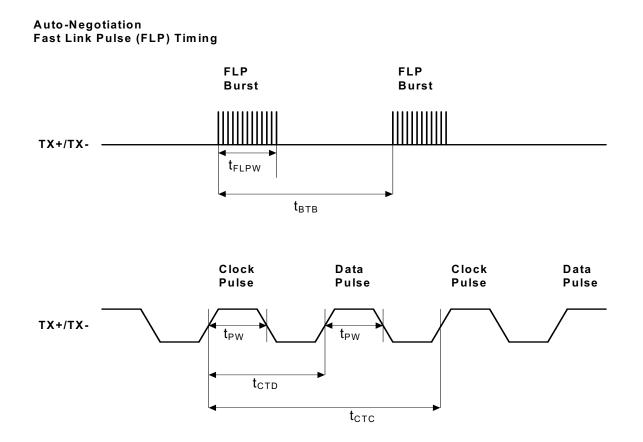
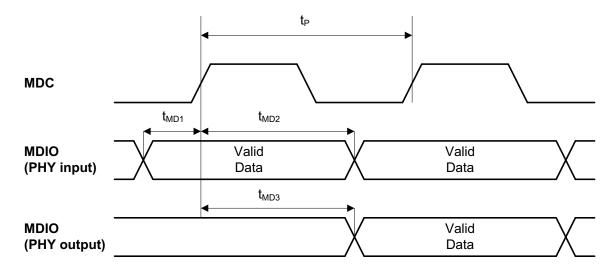


Figure 20. Auto-Negotiation Fast Link Pulse (FLP) Timing

Timing Parameter	Description	Min	Тур	Max	Units
t _{втв}	FLP Burst to FLP Burst	8	16	24	ms
t _{FLPW}	FLP Burst width		2		ms
t _{PW}	Clock/Data Pulse width		100		ns
t _{CTD}	Clock Pulse to Data Pulse	55.5	64	69.5	μ S
tстс	Clock Pulse to Clock Pulse	111	128	139	μ s
	Number of Clock/Data Pulse per FLP Burst	17		33	

Table 21. Auto-Negotiation Fast Link Pulse (FLP) Timing Parameters

MDC/MDIO Timing



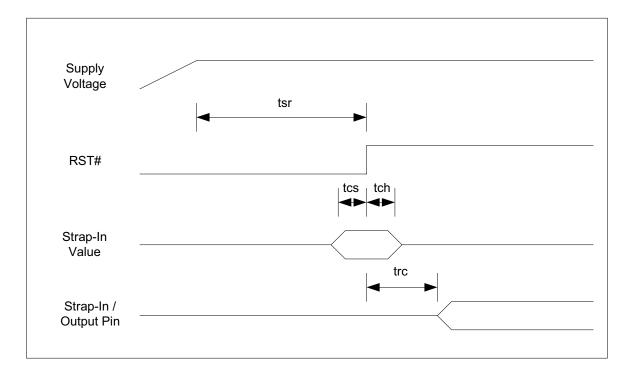


Timing Parameter	Description	Min	Тур	Max	Unit
t _P	MDC period		400		ns
t _{1MD1}	MDIO (PHY input) setup to rising edge of MDC	10			ns
t _{MD2}	MDIO (PHY input) hold from rising edge of MDC	4			ns
t _{MD3}	MDIO (PHY output) delay from rising edge of MDC		222		ns

Table 22.	MDC/MDIO	Timing	Parameters
-----------	----------	--------	------------

Reset Timing

The KSZ8041TL/FTL/MLL reset timing requirement is summarized in the following figure and table.





Parameter	Description	Min	Max	Units
t _{sr}	Stable supply voltage to reset high	10		ms
t _{cs}	Configuration setup time	5		ns
t _{ch}	Configuration hold time	5		ns
t _{rc}	Reset to strap-in pin output	6		ns

Table 23.	Reset Tim	ing Parameters
-----------	-----------	----------------

After the de-assertion of reset, it is recommended to wait a minimum of 100µs before starting programming on the MIIM (MDC/MDIO) Interface.

Reset Circuit

The following reset circuit is recommended for powering up the KSZ8041TL/FTL/MLL if reset is triggered by the power supply.

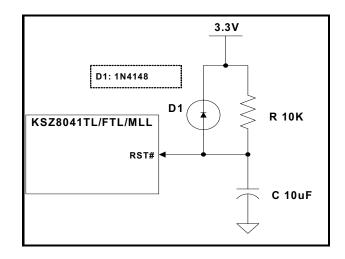
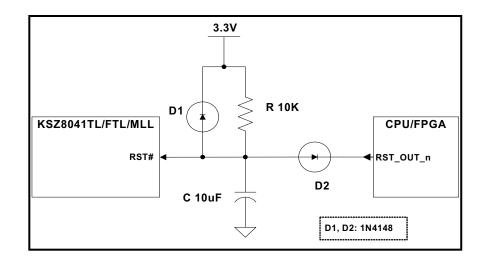


Figure 23. Recommended Reset Circuit

The following reset circuit is recommended for applications where reset is driven by another device (e.g., CPU or FPGA). At power-on-reset, R, C and D1 provide the necessary ramp rise time to reset the KSZ8041TL/FTL/MLL device. The RST_OUT_n from CPU/FPGA provides the warm reset after power up.





The following figure shows the reference circuits for pull-up, float and pull-down on the LED1 and LED0 strapping pins.

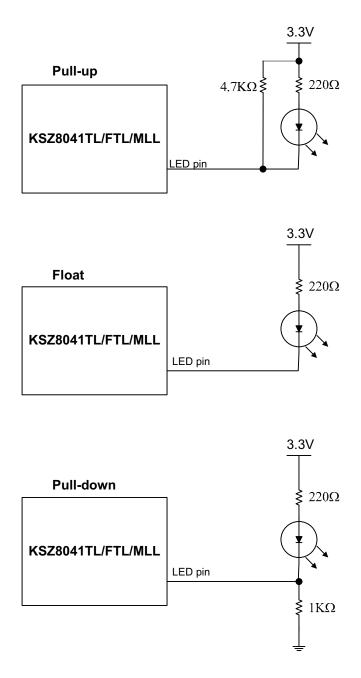


Figure 25. Reference Circuits for LED Strapping Pins

Selection of Isolation Transformer

A 1:1 isolation transformer is required at the line interface. An isolation transformer with integrated common-mode chokes is recommended for exceeding FCC requirements.

The following table gives recommended transformer characteristics.

Parameter	Value	Test Condition
Turns ratio	1 CT : 1 CT	
Open-circuit inductance (min.)	350µH	100mV, 100kHz, 8mA
Leakage inductance (max.)	0.4µH	1MHz (min.)
Inter-winding capacitance (typ.)	12pF	
D.C. resistance (typ.)	0.9Ω	
Insertion loss (max.)	-1.0dB	0MHz – 65MHz
HIPOT (min.)	1500Vrms	

Table 24. Transformer Selection Criteria

Magnetic Manufacturer	Part Number	Auto MDI-X	Number of Port
Bel Fuse	S558-5999-U7	Yes	1
Bel Fuse (Mag Jack)	SI-46001	Yes	1
Bel Fuse (Mag Jack)	SI-50170	Yes	1
Delta	LF8505	Yes	1
LanKom	LF-H41S	Yes	1
Pulse	H1102	Yes	1
Pulse (low cost)	H1260	Yes	1
Transpower	HB726	Yes	1
TDK (Mag Jack)	TLA-6T718	Yes	1

Table 25. Qualified Single Port Magnetics

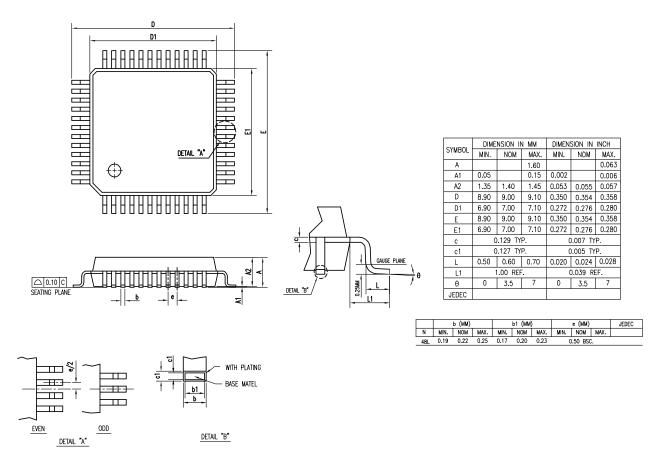
Selection of Reference Crystal

Characteristics	Value	Units
Frequency	25	MHz
Frequency tolerance (max)	±50	ppm
Load capacitance	20	pF
Series resistance	40	Ω

Table 26. Typical Reference Crystal Characteristics

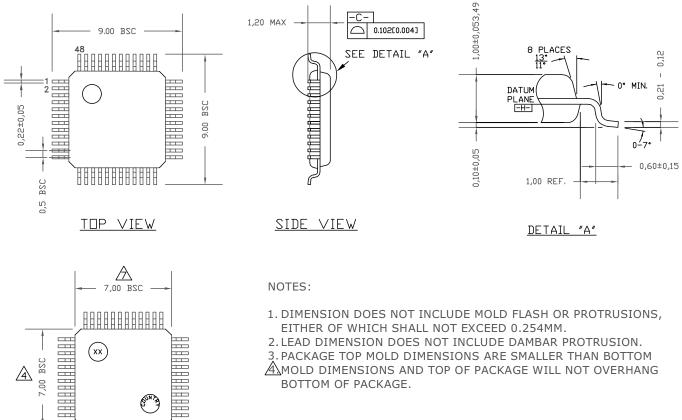
Package Information

48-Pin LQFP



48-Pin (7mm x 7mm) LQFP Package

48-Pin TQFP

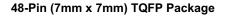


 $\underline{\mathbb{A}}$ MOLD DIMENSIONS AND TOP OF PACKAGE WILL NOT OVERHANG BOTTOM OF PACKAGE.

BOTTOM VIEW

88888888

888



Note: ALL DIMENSIONS ARE IN MILLIMETERS.

____

11 -

MICREL, INC. 2180 FORTUNE DRIVE SAN JOSE, CA 95131 USA TEL +1 (408) 944-0800 FAX +1 (408) 474-1000 WEB http://www.micrel.com

The information furnished by Micrel in this data sheet is believed to be accurate and reliable. However, no responsibility is assumed by Micrel for its use. Micrel reserves the right to change circuitry and specifications at any time without notification to the customer.

Micrel Products are not designed or authorized for use as components in life support appliances, devices or systems where malfunction of a product can reasonably be expected to result in personal injury. Life support devices or systems are devices or systems that (a) are intended for surgical implant into the body or (b) support or sustain life, and whose failure to perform can be reasonably expected to result in a significant injury to the user. A Purchaser's use or sale of Micrel Products for use in life support appliances, devices or systems is a Purchaser's own risk and Purchaser agrees to fully indemnify Micrel for any damages resulting from such use or sale.

© 2008 Micrel, Incorporated.

December 2009