

# **ORDERING INFORMATION**

PART NUMBER	TEMPERATURE RANGE	PACKAGE	PINS	PACKING
ACT4065ASH-T	-40°C to 85°C	SOP-8	8	TAPE & REEL

### **PIN CONFIGURATION**



SOP-8

# **PIN DESCRIPTIONS**

PIN NUMBER	NAME	DESCRIPTION
1	BS	Bootstrap. This pin acts as the positive rail for the high-side switch's gate driver. Connect a 10nF between this pin and SW.
2	IN	Input Supply. Bypass this pin to G with a low ESR capacitor. See <i>Input Capacitor</i> in <i>Application Information</i> section.
3	SW	Switch Output. Connect this pin to the switching end of the inductor.
4	G	Ground.
5	FB	Feedback Input. The voltage at this pin is regulated to 0.808V. Connect to the resistor divider between output and ground to set output voltage.
6	COMP	Compensation Pin. See Compensation Techniques in Application Information section.
7	EN	Enable Input. When higher than 0.8V, this pin turns the IC on. When lower than 0.8V, this pin turn the IC off. Output voltage is discharged when the IC is off. This pin has a small internal pull-up current to a high level voltage when pin is not connected. Do not allow EN pin to exceed 6V.
8	N/C	Not Connected.

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# ACT4065A High Input 2A Step Down Converter

# **ABSOLUTE MAXIMUM RATINGS<sup>®</sup>**

PARAMETER	VALUE	UNIT
IN Supply Voltage	-0.3 to 30	V
SW Voltage	-1 to V <sub>IN</sub> + 1	V
BS Voltage	Vsw - 0.3 to Vsw + 7	V
EN, FB, COMP Voltage	-0.3 to 6	V
Continuous SW Current	Internally limited	А
Maximum Power Dissipation	0.76	W
Junction to Ambient Thermal Resistance $(\theta_{JA})$	105	°C/W
Operating Junction Temperature	-40 to 150	°C
Storage Temperature	-55 to 150	°C
Lead Temperature (Soldering, 10 sec)	300	°C

①: Do not exceed these limits to prevent damage to the device. Exposure to absolute maximum rating conditions for long periods may affect device reliability.

# **ELECTRICAL CHARACTERISTICS**

 $(V_{IN} = 12V, T_J = 25^{\circ}C, unless otherwise specified.)$ 

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
Input Voltage	VIN	Vout = 5V, Iload = 1A	6		30	V
Feedback Voltage	V <sub>FB</sub>	$V_{COMP} = 1.5V$	0.792	0.808	0.824	V
High-Side Switch On Resistance	Ronh			0.22		Ω
Low-Side Switch On Resistance	Ronl			8		Ω
SW Leakage		$V_{EN} = 0$		1	10	μA
High-Side Switch Current Limit	I <sub>LIM</sub>	Duty = 50%		3.5		Α
COMP to Current Limit Transconductance	GCOMP			3.4		A/V
Error Amplifier Transconductance	Gea	$\Delta I_{COMP} = \pm 10 \mu A$		650		μA/V
Error Amplifier DC Gain	AVEA			4000		V/V
Switching Frequency	fsw		190	210	240	kHz
Short Circuit Switching Frequency		V <sub>FB</sub> = 0		30		kHz
Maximum Duty Cycle	DMAX	$V_{FB} = 0.7V$		88		%
Minimum Duty Cycle		V <sub>FB</sub> = 1.0V			0	%
Enable Threshold Voltage		Hysteresis = 0.1V	0.75	0.8	0.85	V
Enable Pull-Up Current		Pin pulled up to 4.5V typically when left unconnected		4		μΑ
Supply Current in Shutdown		V <sub>EN</sub> = 0		75	100	μA
IC Supply Current in Operation		$V_{EN} = 3V, V_{FB} = 1.0V$		0.75		mA
Thermal Shutdown Temperature		Hysteresis = 10°C		155		°C

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# FUNCTIONAL BLOCK DIAGRAM



# FUNCTIONAL DESCRIPTION

As seen in, *Functional Block Diagram*, the ACT4065A is a current mode pulse width modulation (PWM) converter. The converter operates as follows:

A switching cycle starts when the rising edge of the Oscillator clock output causes the High-Side Power Switch to turn on and the Low-Side Power Switch to turn off. With the SW side of the inductor now connected to IN, the inductor current ramps up to store energy in its magnetic field. The inductor current level is measured by the Current Sense Amplifier and added to the Oscillator ramp signal. If the resulting summation is higher than the COMP volt- age, the output of the PWM Comparator goes high. When this happens or when Oscillator clock output goes low, the High-Side Power Switch turns off and the Low-Side Power Switch turns on. At this point, the SW side of the inductor swings to a diode voltage below ground, causing the inductor current to decrease and magnetic energy to be transferred to the output. This state continues until the cycle starts again.

The High-Side Power Switch is driven by logic using the BS bootstrap pin as the positive rail. This pin is charged to  $V_{SW}$  + 5V when the Low-Side Power Switch turns on.

The COMP voltage is the integration of the error between the FB input and the internal 0.808V

reference. If FB is lower than the reference voltage, COMP tends to go higher to increase current to the output. Current limit happens when COMP reaches its maximum clamp value of 2.0V.

The Oscillator normally switches at 210kHz. However, if the FB voltage is less than 0.6V, then the switching frequency decreases until it reaches a minimum of 30kHz at  $V_{FB} = 0.15V$ .

#### **Shutdown Control**

The ACT4065A has an enable input EN for turning the IC on or off. When EN is less than 0.7V, the IC is in  $8\mu$ A low current shutdown mode. When EN is higher than 0.8V, the IC is in normal operation mode. EN is internally pulled up with a  $4\mu$ A current source and can be left unconnected for always-on operation. EN should never be directly connected to IN.

#### Thermal Shutdown

The ACT4065A automatically turns off when its junction temperature exceeds 155°C.

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### ACT4065A High Input 2A Step Down Converter

# **APPLICATIONS INFORMATION**

#### **Output Voltage Setting**

Figure 1: Output Voltage Setting



Figure 1 shows the connections for setting the output voltage. Select the proper ratio of the two feedback resistors  $R_{FB1}$  and  $R_{FB2}$  based on the output voltage. Typically, use  $R_{FB2}\approx 10 k\Omega$  and determine  $R_{FB1}$  from the output voltage:

$$R_{FB1} = R_{FB2} \left( \frac{V_{OUT}}{0.808 \, V} - 1 \right) \tag{1}$$

#### **Inductor Selection**

The inductor maintains a continuous current to the output load. This inductor current has a ripple that is dependent on the inductance value: higher inductance reduces the peak-to-peak ripple current. The trade off for high inductance value is the increase in inductor core size and series resistance, and the reduction in current handling capability. In general, select an inductance value L based on ripple current requirement:

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} f_{SW} I_{OUTMAX} K_{RIPPLE}}$$
(2)

where  $V_{IN}$  is the input voltage,  $V_{OUT}$  is the output voltage,  $f_{SW}$  is the switching frequency,  $I_{OUTMAX}$  is the maximum output current, and  $K_{RIPPLE}$  is the ripple factor. Typically, choose  $K_{RIPPLE} = 30\%$  to correspond to the peak-to-peak ripple current being 30% of the maximum output current.

With this inductor value (Table 1), the peak inductor current is  $I_{OUT} \times (1 + K_{RIPPLE} / 2)$ . Make sure that this peak inductor current is less that the 3A current limit. Finally, select the inductor core size so that it does not saturate at 3A.

#### Table 1. Typical Inductor Values

Vout	1.5V	1.8V	2.5V	3.3V	5V
L	10µH	10µH	15µH	22µH	33µH

#### **Input Capacitor**

The input capacitor needs to be carefully selected to maintain sufficiently low ripple at the supply input of the converter. A low ESR capacitor is highly recommended. Since a large current flows in and out of this capacitor during switching, its ESR also affects efficiency.

The input capacitance needs to be higher than  $10\mu$ F. The best choice is the ceramic type; however, low ESR tantalum or electrolytic types may also be used provided that the RMS ripple current rating is higher than 50% of the output current. The input capacitor should be placed close to the IN and G pins of the IC, with shortest possible traces. In the case of tantalum or electrolytic types, they can be further away if a small parallel  $0.1\mu$ F ceramic capacitor is placed right next to the IC.

#### **Output Capacitor**

The output capacitor also needs to have low ESR to keep low output voltage ripple. The output ripple voltage is:

$$V_{RIPPLE} = I_{OUTMAX} K_{RIPPLE} \left( R_{ESR} + \frac{1}{8 \times f_{SW} \times C_{OUT}} \right)$$
(3)

where  $I_{OUTMAX}$  is the maximum output current,  $K_{RIPPLE}$  is the ripple factor, RESR is the ESR resistance of the output capacitor,  $f_{SW}$  is the switching frequency, L is the inductor value,  $C_{OUT}$  is the output capacitance,  $R_{ESR}$ is very small and does not contribute to the ripple. Therefore, a lower capacitance value can be used for ceramic type. In the case of tantalum or electrolytic type, the ripple is dominated by  $R_{ESR}$  multiplied by the ripple current. In that case, the output capacitor is chosen to have sufficiently low ESR.

For ceramic output type, typically choose a capacitance of about  $22\mu$ F. For tantalum or electrolytic type, choose a capacitor with less than  $50m\Omega$  ESR.

#### **Rectifier Diode**

Use a Schotky diode as the rectifier to conduct current when the High-Side Power Switch is off. The Schottky diode must have current rating higher than the maximum output current and the reverse voltage rating higher than the maximum input voltage.

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#### **Stability Compensation**

Figure 2: Stability Compensation



10: C<sub>COMP2</sub> is needed only for high ESR output capacitors

The feedback system of the IC is stabilized by the components at COMP pin, as shown in Figure 2. The DC loop gain of the system is determined by the following equation:

$$A_{VDC} = \frac{0.808 V}{I_{OUT}} A_{VEA} G_{COMP}$$
<sup>(4)</sup>

The dominant pole P1 is due to CCOMP:

$$f_{P1} = \frac{G_{EA}}{2\pi A_{VEA} C_{COMP}} \tag{5}$$

The second pole P2 is the output pole:

$$f_{P2} = \frac{I_{OUT}}{2\pi \, V_{OUT} \, C_{OUT}} \tag{6}$$

The first zero Z1 is due to RCOMP and CCOMP:

$$f_{Z1} = \frac{1}{2\pi R_{COMP} C_{COMP}} \tag{7}$$

And finally, the third pole is due to  $R_{COMP}$  and  $C_{COMP2}$  (if  $C_{COMP2}$  is used):

$$f_{P3} = \frac{1}{2\pi R_{COMP} C_{COMP2}} \tag{8}$$

Follow the following steps to compensate the IC:

STEP 1. Set the cross over frequency at 1/5 of the switching frequency via RCOMP:

$$R_{COMP} = \frac{2\pi V_{OUT} C_{OUT} f_{SW}}{10 G_{EA} G_{COMP} \times 0.808 V}$$
(9)  
= 2.75 x 10<sup>8</sup> V<sub>OUT</sub> C<sub>OUT</sub> (Ω)

but limit  $R_{COMP}$  to  $15k\Omega$  maximum.

STEP 2. Set the zero  $f_{Z1}$  at 1/4 of the cross over frequency. If  $R_{COMP}$  is less than 15k $\Omega$ , the equation for  $C_{COMP}$  is:

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$$C_{COMP} = \frac{1.8 \times 10^{-5}}{R_{COMP}} \quad (F) \tag{10}$$

If  $R_{COMP}$  is limited to  $15k\Omega$ , then the actual cross over frequency is 6.1/ (VoutCout). Therefore:

$$C_{COMP} = 1.2 \times 10^{-5} \, V_{OUT} \, C_{OUT} \ (F) \tag{11}$$

STEP 3. If the output capacitors ESR is high enough to cause a zero at lower than 4 times the cross over frequency, an additional compensation capacitor  $C_{COMP2}$  is required. The condition for using  $C_{COMP2}$  is required. The condition for using  $C_{COMP2}$  is

$$R_{ESROUT} \ge Min\left(\frac{1.1 \times 10^{-6}}{C_{OUT}}, 0.012 V_{OUT}\right)$$
 (2) (12)

And the proper value for CCOMP2 is:

$$C_{COMP2} = \frac{C_{OUT} R_{ESROUT}}{R_{COMP}}$$
(13)

Though  $C_{COMP2}$  is unnecessary when the output capacitor has sufficiently low ESR, a small value  $C_{COMP2}$  such as 100pF may improve stability against PCB layout parasitic effects.

Table 2 shows some calculated results based on the compensation method above

#### Table 2:

# Typical Compensation for Different Output voltages and Output Capacitors

Vout	Соит	R <sub>COMP</sub>	Ссомр	CCOMP2 <sup>®</sup>
2.5V	22µF Ceramic	12kΩ	2.2nF	None
3.3V	22µF Ceramic	12kΩ	1.5 nF	None
5V	22µF Ceramic	15kΩ	2.2 nF	None
2.5V	47µF SP Cap	15kΩ	1.5 nF	None
3.3V	47µF SP Cap	15kΩ	1.8 nF	None
5V	47µF SP Cap	15kΩ	2.7 nF	None
2.5V	470µF/6.3V/30mΩ	15kΩ	1.5 nF	47pF
3.3V	$470\mu F/6.3V/30m\Omega$	15kΩ	2.2 nF	47pF
5V	470µF/10V/30mΩ	15kΩ	2.7 nF	47pF

 $\textcircled{O}: C_{\text{COMP2}} \text{ is needed only for high ESR output capacitors}$ 

Figure 3 shows a sample ACT4065A application circuit generating a 2.5V/2A output.

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#### Figure 3:

Typical Application Circuit for 5V/2A Car Charge



#### Table 3: BOM List for 5V/2A Car Charger

ITEM	REFERENCE	DESCRIPTION	MANUFACTURER	QTY
1	U1	IC, ACT4065ASH, SOP-8EP	Active-Semi	1
2	C1	Capacitor, Electrolytic, 47µF/35V, 6.3x7mm	Murata, TDK	1
3	C2	Capacitor, Ceramic, 10µF/35V, 1210, SMD	Murata, TDK	1
4	C3	Capacitor, Ceramic, 2.2nF/6.3V, 0603, SMD	Murata, TDK	1
5	C4	Capacitor, Ceramic, 10nF/50V, 0603, SMD	Murata, TDK	1
6	C5	Capacitor, Electrolytic, 100µF/10V, 6.3x7mm	Murata, TDK	1
7	C6	Capacitor, Ceramic, 1µF/10V, 0603, SMD	Murata, TDK	1
8	L1	Inductor,33µH, 3.0A	Sumida	1
9	D1	Diode, Schottky, 40V/2A, SB240	Diodes	1
10	R1	Chip Resistor, 52kΩ, 0603, 1%	Murata, TDK	1
11	R3	Chip Resistor, 8.2kΩ, 0603, 5%	Murata, TDK	1
12	R2	Chip Resistor, 10kΩ, 0603, 1%	Murata, TDK	1

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# ACT4065A High Input 2A Step Down Converter

# **TYPICAL PERFORMANCE CHARACTERISTICS**

(Circuit of Figure 3, unless otherwise specified.)







Start up with EN





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# PACKAGE OUTLINE AND DIMENSIONS



Side View



Side View

	Dimensional Ref.					
REF.	Min.	Nom.	Max.			
Α	1.450		1.750			
A1	0.100		0.250			
A2	1.350		1.550			
b	0.330		0.510			
С	0.170		0.250			
D E	4	.900BS	C			
	e	.000BS	C			
E1	3	1.900BS	C			
e	1	1.270 BSC				
L	0.400		1.270			
L1	1	.040REF				
R	0.070					
R1	0.070					
θ	0°		8°			
<del>0</del> 1	5°		15°			
Τc	Tol. of Form&Position					
ааа	0.10					
ЬРР	0.20					
ددد	0.10					
ddd	0.25					
eee	0.10					

Notes

1. ALL DIMENSIONS AND TOLERANCES CONFORM TO ASME Y14.5-2009.

2. All DIMENSIONS ARE IN MILLIMETERS.

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# **Product Compliance**

This part complies with RoHS directive 2011/65/EU as amended by (EU) 2015/863.

This part also has the following attributes:

- Lead Free
- Halogen Free (Chlorine, Bromine)

# **Contact Information**

For the latest specifications, additional product information, worldwide sales and distribution locations:

Web: www.qorvo.com

Email: customer.support@gorvo.com

For technical questions and application information:

Email: appsupport@gorvo.com

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Tel: 1-844-890-8163

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