Dual supply translating transceiver; auto direction sensing; 3-state

# 3. Ordering information

#### Table 1. Ordering information

Type number	Topside	Package							
	marking	Name	Description	Version					
NTB0104BQ	B0104	DHVQFN14	plastic dual in-line compatible thermal enhanced very thin quad flat package; no leads; 14 terminals; body $2.5 \times 3 \times 0.85$ mm	SOT762-1					
NTB0104GU12	t4	XQFN12	plastic, extremely thin quad flat package; no leads; 12 terminals; body 1.70 $\times$ 2.0 $\times$ 0.50 mm	SOT1174-1					
NTB0104UK	t04	WLCSP12	wafer level chip-size package, 12 bumps; body 1.20 $\times$ 1.60 $\times$ 0.56 mm. (Backside Coating included)	NTB0104UK					

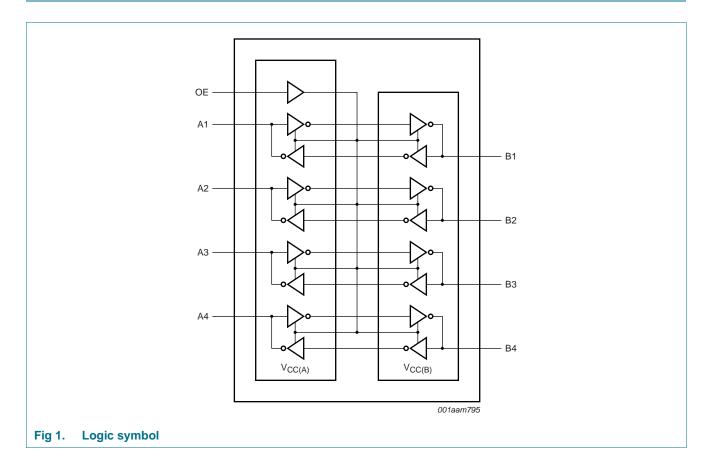
## 3.1 Ordering options

#### Table 2. Ordering options

Type number	Orderable part number	Package	Packing method	Minimum order quantity	Temperature
NTB0104BQ	NTB0104BQ,115	DHVQFN14	REEL 7" Q1/T1 *STANDARD MARK SMD	3000	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$
NTB0104GU12	NTB0104GU12,115	XQFN12	REEL 7" Q1/T1 *STANDARD MARK SMD	4000	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$
NTB0104UK	NTB0104UK,012	WLCSP12	REEL 7" Q1/T1 *SPECIAL MARK CHIPS DP	5000	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$

Dual supply translating transceiver; auto direction sensing; 3-state

# 4. Functional diagram

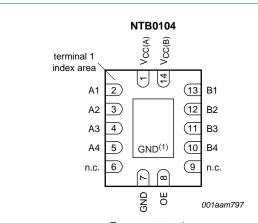


**Product data sheet** 

Dual supply translating transceiver; auto direction sensing; 3-state

## 5. Pinning information

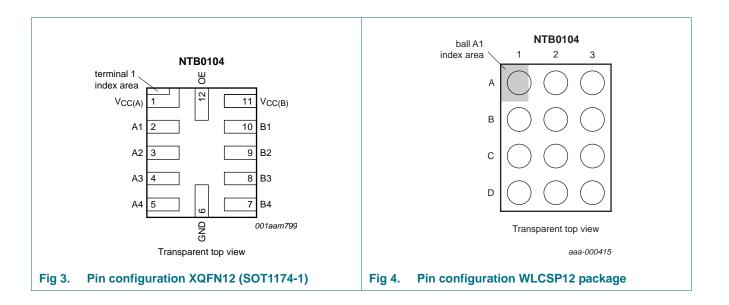
## 5.1 Pinning



Transparent top view

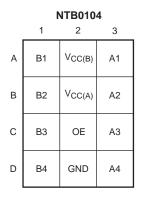
(1) This is not a supply pin, the substrate is attached to this pad using conductive die attach material. There is no electrical or mechanical requirement to solder this pad, however if it is soldered the solder land should remain floating or be connected to GND

#### Fig 2. Pin configuration DHVQFN14 (SOT762-1)



**Product data sheet** 

### Dual supply translating transceiver; auto direction sensing; 3-state



Transparent top view

aaa-000416

Fig 5. Ball mapping for WLCSP12

## 5.2 Pin description

Table 3. Pin description

Symbol	Pin		Ball	Description		
	SOT762-1	SOT1174-1	WLCSP12			
V <sub>CC(A)</sub>	1	1	B2	supply voltage A		
A1, A2, A3, A4	2, 3, 4, 5	2, 3, 4, 5	A3, B3, C3, D3	data input or output (referenced to V <sub>CC(A)</sub> )		
n.c.	6, 9	-	-	not connected		
GND	7	6	D2	ground (0 V)		
OE	8	12	C2	output enable input (active HIGH; referenced to $V_{\text{CC(A)}}$ )		
B4, B3, B2, B1	10, 11, 12, 13	7, 8, 9, 10	D1, C1, B1, A1	data input or output (referenced to V <sub>CC(B)</sub> )		
V <sub>CC(B)</sub>	14	11	A2	supply voltage B		

# 6. Functional description

Table 4. Function table [1]

Supply voltage		Input	Input/output			
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	OE	An	Bn		
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	L	Z	Z		
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	Н	input or output	output or input		
GND[2]	GND[2]	X	Z	Z		

<sup>[1]</sup> H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

<sup>[2]</sup> When either  $V_{\text{CC(A)}}$  or  $V_{\text{CC(B)}}$  is at GND level, the device goes into power-down mode.

#### Dual supply translating transceiver; auto direction sensing; 3-state

## 7. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A			-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B			-0.5	+6.5	V
VI	input voltage		[1]	-0.5	+6.5	V
Vo	output voltage	Active mode	[1][2][3]	-0.5	V <sub>CCO</sub> + 0.5	V
		Power-down or 3-state mode	[1]	-0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < 0 V		-50	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V		-50	-	mA
Io	output current	$V_O = 0 V \text{ to } V_{CCO}$	[2]	-	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>		-	100	mA
I <sub>GND</sub>	ground current			-100	-	mA
T <sub>stg</sub>	storage temperature			-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$	[4]	-	250	mW

<sup>[1]</sup> The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

## 8. Recommended operating conditions

Table 6. Recommended operating conditions [1][2]

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		1.2	3.6	V
V <sub>CC(B)</sub>	supply voltage B		1.65	5.5	V
VI	input voltage		0	5.5	V
Vo	output voltage	Power-down or 3-state mode; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V			
		A port	0	3.6	V
		B port	0	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	40	ns/V

<sup>[1]</sup> The A and B sides of an unused I/O pair must be held in the same state, both at  $V_{\text{CCI}}$  or both at GND.

<sup>[2]</sup>  $V_{CCO}$  is the supply voltage associated with the output.

<sup>[3]</sup>  $V_{CCO}$  + 0.5 V should not exceed 6.5 V.

<sup>[4]</sup> For DHVQFN14 packages: above 60 °C the value of P<sub>tot</sub> derates linearly with 4.5 mW/K. For XQFN12 packages: above 128 °C the value of P<sub>tot</sub> derates linearly with 11.5 mW/K.

<sup>[2]</sup>  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

#### Dual supply translating transceiver; auto direction sensing; 3-state

### 9. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
V <sub>OH</sub>	HIGH-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$ ; $I_O = -20 \mu\text{A}$		-	1.1	-	V
V <sub>OL</sub>	LOW-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$ ; $I_O = 20 \mu\text{A}$		-	0.09	-	V
l <sub>l</sub>	input leakage current	OE input; $V_1 = 0 \text{ V to } 3.6 \text{ V}; V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	-	±1	μА
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0$ V to $V_{CCO}$ ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	[1]	-	-	±1	μΑ
I <sub>OFF</sub>	power-off leakage current	A port; $V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V		-	-	±1	μΑ
		B port; $V_1$ or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V		-	-	±1	μΑ
I <sub>CC</sub>	supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	[2]				
		$I_{CC(A)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V		-	0.05	-	μΑ
		$I_{CC(B)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V		-	3.3	-	μΑ
		$I_{CC(A)} + I_{CC(B)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V		-	3.5	-	μΑ
Cı	input capacitance	OE input; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	2.8	-	pF
C <sub>I/O</sub>	input/output	A port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	4.0	-	pF
	capacitance	B port; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	7.5	-	pF

<sup>[1]</sup>  $V_{CCO}$  is the supply voltage associated with the output.

Table 8. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	V <sub>CC(B)</sub>									
	1.8 V	1.8 V		2.5 V		3.3 V					
	I <sub>CC(A)</sub>	I <sub>CC(B)</sub>									
1.2 V	10	10	10	10	10	20	10	1050	nA		
1.5 V	10	10	10	10	10	10	10	650	nA		
1.8 V	10	10	10	10	10	10	10	350	nA		
2.5 V	-	-	10	10	10	10	10	40	nA		
3.3 V	-	-	-	-	10	10	10	10	nA		

**Product data sheet** 

<sup>[2]</sup>  $V_{CCI}$  is the supply voltage associated with the input.

### Dual supply translating transceiver; auto direction sensing; 3-state

Table 9. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		–40 °C to	+85 °C	–40 °C to	Unit	
				Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
$V_{IL}$	LOW-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
V <sub>OH</sub>	HIGH-level	A or B port; $I_O = -20 \mu A$	[2]					
output voltag	output voltage	A port; V <sub>CC(A)</sub> = 1.4 V to 3.6 V		V <sub>CCO</sub> - 0.4	-	V <sub>CCO</sub> - 0.4	-	V
		B port; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		V <sub>CCO</sub> - 0.4	-	V <sub>CCO</sub> - 0.4	-	V
$V_{OL}$	LOW-level	A or B port; $I_O = 20 \mu A$	[2]					
	output voltage	A port; V <sub>CC(A)</sub> = 1.4 V to 3.6 V		-	0.4	-	0.4	V
		B port; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	0.4	-	0.4	V
l <sub>l</sub>	input leakage current	OE input; $V_I = 0 \text{ V to } 3.6 \text{ V};$ $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	±2	-	±5	μА
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$ ; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	[2]	-	±2	-	±10	μА
I <sub>OFF</sub>	power-off leakage	A port; $V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V		-	±2	-	±10	μΑ
	current	B port; $V_1$ or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V		-	±2	-	±10	μА

#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 9. Static characteristics ... continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		–40 °C t	o +85 °C	-40 °C to	o +125 °C	Unit
				Min	Max	Min	Max	
I <sub>CC</sub>	supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	<u>[1]</u>					
		I <sub>CC(A)</sub>						
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	5	-	15	μΑ
		OE = HIGH; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	5	-	20	μΑ
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	2	-	15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$		-	-2	-	-15	μΑ
		I <sub>CC(B)</sub>						
		OE = LOW; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	5	-	15	μΑ
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	5	-	20	μΑ
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	-2	-	-15	μΑ
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V		-	2	-	15	μΑ
		$I_{CC(A)} + I_{CC(B)}$						
		$V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	10	-	40	μΑ

<sup>[1]</sup>  $V_{\text{CCI}}$  is the supply voltage associated with the input.

# 10. Dynamic characteristics

Table 10. Typical dynamic characteristics for temperature 25 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for waveforms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions				Unit			
Symbol	Parameter	Conditions		V <sub>CC(B)</sub>					
				1.8 V	2.5 V	3.3 V	5.0 V		
V <sub>CC(A)</sub> = '	1.2 V; T <sub>amb</sub> = 25 °C								
t <sub>pd</sub> prop	propagation delay	A to B		5.9	4.8	4.4	4.2	ns	
		B to A		5.6	4.8	4.5	4.4	ns	
t <sub>en</sub>	enable time	OE to A, B		0.5	0.5	0.5	0.5	μS	
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	8.3	8.3	8.3	8.3	ns	
		OE to B; no external load	[2]	10.4	9.4	9.3	8.8	ns	
		OE to A		81	69	83	68	ns	
		OE to B		81	69	83	68	ns	
t <sub>t</sub>	transition time	A port		4.0	4.0	4.1	4.1	ns	
		B port		2.6	2.0	1.7	1.4	ns	

<sup>[2]</sup>  $V_{CCO}$  is the supply voltage associated with the output.

#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 10. Typical dynamic characteristics for temperature 25 °C[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for waveforms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions			Unit			
				1.8 V	2.5 V	3.3 V	5.0 V	
t <sub>sk(o)</sub>	output skew time	between channels	[3]	0.2	0.2	0.2	0.2	ns
t <sub>W</sub>	pulse width	data inputs		15	13	13	13	ns
f <sub>data</sub>	data rate			70	80	80	80	Mbps

[1] t<sub>pd</sub> is the same as t<sub>PLH</sub> and t<sub>PHL</sub>.

ten is the same as tPZL and tPZH.

 $t_{\mbox{\scriptsize dis}}$  is the same as  $t_{\mbox{\scriptsize PLZ}}$  and  $t_{\mbox{\scriptsize PHZ}}.$ 

 $t_{t}$  is the same as  $t_{THL}$  and  $t_{TLH}$ 

- [2] Delay between OE going LOW and when the outputs are actually disabled.
- [3] Skew between any two outputs of the same package switching in the same direction.

Table 11. Dynamic characteristics for temperature range -40 °C to +85 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions					Vcc	(B)				Unit
				1.8 V ±	0.15 V	2.5 V	± 0.2 V	3.3 V	± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.5 V ± 0.1 V											
t <sub>pd</sub>	propagation	A to B		1.4	12.9	1.2	10.1	1.1	10.0	0.8	9.9	ns
	delay	B to A		0.9	14.2	0.7	12.0	0.4	11.7	0.3	13.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.9	1.0	12.9	1.0	12.9	1.0	12.9	ns
		OE to B; no external load	[2]	1.0	18.7	1.0	15.8	1.0	15.1	1.0	14.4	ns
		OE to A		-	320	-	260	-	260	-	280	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t <sub>t</sub>	transition time	A port		0.9	5.1	0.9	5.1	0.9	5.1	0.9	5.1	ns
		B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbps
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V											
t <sub>pd</sub>	propagation	A to B		1.6	11.0	1.4	7.7	1.3	6.8	1.2	6.5	ns
	delay	B to A		1.5	12.0	1.3	8.4	1.0	7.6	0.9	7.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	11.7	1.0	11.7	1.0	11.7	1.0	11.7	ns
		OE to B; no external load	[2]	1.0	16.9	1.0	14.5	1.0	13.7	1.0	12.7	ns
		OE to A		-	260	-	230	-	230	-	230	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		0.8	4.1	0.8	4.1	0.8	4.1	0.8	4.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 11. Dynamic characteristics for temperature range -40 °C to +85 °C !1 ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions					Vcc	(B)				Unit
				1.8 V ±	0.15 V	2.5 V	± 0.2 V		± 0.3 V	5.0 V	± 0.5 V	-
				Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		20	-	17	-	17	-	17	-	ns
f <sub>data</sub>	data rate			-	49	-	60	-	60	-	60	Mbps
V <sub>CC(A)</sub> =	2.5 V ± 0.2 V								·		·	
t <sub>pd</sub>	propagation	A to B		-	-	1.1	6.3	1.0	5.2	0.9	4.7	ns
	delay	B to A		-	-	1.2	6.6	1.1	5.1	0.9	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	9.7	1.0	9.7	1.0	9.7	ns
		OE to B; no external load	[2]	-	-	1.0	12.9	1.0	12.0	1.0	11.0	ns
		OE to A		-	-	-	200	-	200	-	200	ns
		OE to B		-	-	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		-	-	0.7	3.0	0.7	3.0	0.7	3.0	ns
	time	B port		-	-	0.7	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	12	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	85	-	100	-	100	Mbps
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
t <sub>pd</sub>	propagation	A to B		-	-	-	-	0.9	4.7	0.8	4.0	ns
	delay	B to A		-	-	-	-	1.0	4.9	0.9	3.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.4	1.0	9.4	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	11.3	1.0	10.4	ns
		OE to A		-	-	-	-	-	260	-	260	ns
		OE to B		-	-	-	-	-	200	-	200	ns
t <sub>t</sub> transition	transition	A port		-	-	-	-	0.7	2.5	0.7	2.5	ns
	time	B port		-	-	-	-	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	putput skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	th data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate	·		-	-	-	-	-	100	-	100	Mbps

<sup>[1]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{\text{en}}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}.$ 

 $t_{\mbox{\scriptsize dis}}$  is the same as  $t_{\mbox{\scriptsize PLZ}}$  and  $t_{\mbox{\scriptsize PHZ}}.$ 

 $t_t$  is the same as  $t_{\text{THL}}$  and  $t_{\text{TLH}}$ 

- [2] Delay between OE going LOW and when the outputs are actually disabled.
- [3] Skew between any two outputs of the same package switching in the same direction.

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### Dual supply translating transceiver; auto direction sensing; 3-state

Table 12. Dynamic characteristics for temperature range –40 °C to +125 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions		V <sub>CC(B)</sub>								Unit
				1.8 V ±	0.15 V	2.5 V ±	± 0.2 V	3.3 V	± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.5 V ± 0.1 V				•	'						
t <sub>pd</sub>	propagation	A to B		1.4	15.9	1.2	13.1	1.1	13.0	0.8	12.9	ns
	delay	B to A		0.9	17.2	0.7	15.0	0.4	14.7	0.3	16.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	13.5	1.0	13.5	1.0	13.5	1.0	13.5	ns
		OE to B; no external load	[2]	1.0	19.9	1.0	16.8	1.0	16.1	1.0	15.2	ns
		OE to A		-	340	-	280	-	280	-	300	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.9	7.1	0.9	7.1	0.9	7.1	0.9	7.1	ns
	time	B port		0.9	6.5	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	w between channels		-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbps
	1.8 V ± 0.15 V		-									
t <sub>pd</sub>	propagation	A to B		1.6	14.0	1.4	10.7	1.3	9.8	1.2	9.5	ns
	delay	B to A		1.5	15.0	1.3	11.4	1.0	10.6	0.9	10.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.3	1.0	12.3	1.0	12.3	1.0	12.3	ns
ais		OE to B; no external load	[2]	1.0	18.1	1.0	15.3	1.0	14.5	1.0	13.5	ns
		OE to A		-	280	-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.8	6.2	0.8	6.1	0.8	6.1	0.8	6.1	ns
	time	B port		0.9	5.8	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		22	-	19	-	19	-	19	-	ns
f <sub>data</sub>	data rate			-	45	-	55	-	55	-	55	Mbps
	2.5 V ± 0.2 V		-				1					-
t <sub>pd</sub>	propagation	A to B		-	-	1.1	9.3	1.0	8.2	0.9	7.7	ns
	delay	B to A		-	-	1.2	9.6	1.1	8.1	0.9	7.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	10.1	1.0	10.1	1.0	10.1	ns
		OE to B; no external load	[2]	-	-	1.0	13.5	1.0	12.7	1.0	11.7	ns
		OE to A		-	-	-	220	-	220	-	220	ns
		OE to B		-	-	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		-	-	0.7	5.0	0.7	5.0	0.7	5.0	ns
•	time	B port	+	_	_	0.7	4.6	0.5	4.8	0.4	4.7	ns

#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 12. Dynamic characteristics for temperature range -40 °C to +125 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ± 0.15 V		$\textbf{2.5 V} \pm \textbf{0.2 V}$		3.3 V $\pm$ 0.3 V		5.0 V $\pm$ 0.5 V		
				Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs;		-	-	14	-	13	-	10	-	ns
f <sub>data</sub>	data rate				-	-	75	-	80	-	100	Mbps
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V			1	1	1	1	1			1	
t <sub>pd</sub>	propagation delay	A to B		-	-	-	-	0.9	7.7	0.8	7.0	ns
		B to A		-	-	-	-	1.0	7.9	0.9	6.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.9	1.0	9.9	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	12.1	1.0	10.9	ns
		OE to A		-	-	-	-	-	280	-	280	ns
		OE to B		-	-	-	-	-	220	-	220	ns
t <sub>t</sub>	transition	A port		-	-	-	-	0.7	4.5	0.7	4.5	ns
	time	B port		-	-	-	-	0.5	4.1	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

<sup>[1]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

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 $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .

 $t_{\mbox{\scriptsize dis}}$  is the same as  $t_{\mbox{\scriptsize PLZ}}$  and  $t_{\mbox{\scriptsize PHZ}}.$ 

 $t_{t}$  is the same as  $t_{\text{THL}}$  and  $t_{\text{TLH}}$ 

<sup>[2]</sup> Delay between OE going LOW and when the outputs are actually disabled.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 13. Typical power dissipation capacitance

Voltages are referenced to GND (ground = 0 V).[1][2]

Symbol	Parameter	Conditions				V <sub>CC(A)</sub>				Unit
			1.2 V	1.2 V	1.5 V	1.8 V	2.5 V	2.5 V	3.3 V	
						V <sub>CC(B)</sub>				
			1.8 V	5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V	
$T_{amb} = 2$	5 °C									
C <sub>PD</sub>	power dissipation capacitance	outputs enabled; $OE = V_{CC(A)}$								
		A port: (direction A to B)	5	5	5	5	5	5	5	pF
		A port: (direction B to A)	8	8	8	8	8	8	8	pF
		B port: (direction A to B)	18	18	18	18	18	18	18	pF
		B port: (direction B to A)	13	16	12	12	12	12	13	pF
		outputs disabled; OE = GND								
		A port: (direction A to B)	0.12	0.12	0.04	0.05	0.08	0.08	0.07	pF
		A port: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction A to B)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction B to A)	0.07	0.09	0.07	0.07	0.05	0.09	0.09	pF

[1]  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu W$ ).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:

 $f_i$  = input frequency in MHz;

fo = output frequency in MHz;

C<sub>L</sub> = load capacitance in pF;

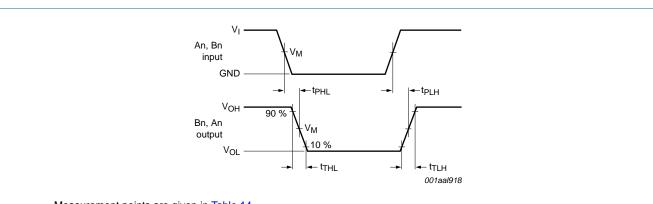
V<sub>CC</sub> = supply voltage in V;

N = number of inputs switching;

 $\Sigma (C_L \times V_{CC}{}^2 \times f_o)$  = sum of the outputs.

[2]  $f_i$  = 10 MHz;  $V_I$  = GND to  $V_{CC}$ ;  $t_r$  =  $t_f$  = 1 ns;  $C_L$  = 0 pF;  $R_L$  =  $\infty$   $\Omega$ .

### 11. Waveforms



Measurement points are given in Table 14.

 $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Fig 6. The data input (An, Bn) to data output (Bn, An) propagation delay times

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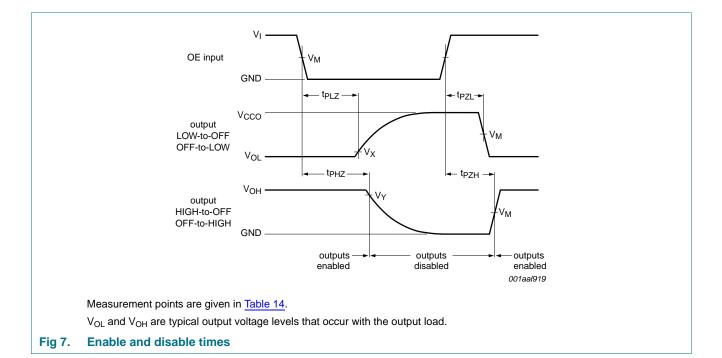
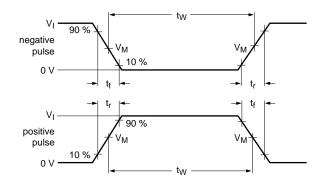


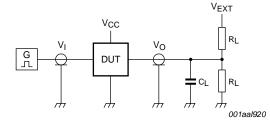
Table 14. Measurement points[1]

Supply voltage	Input	Output	Output					
V <sub>cco</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>				
1.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> – 0.1 V				
1.5 V $\pm$ 0.1 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	$V_{OH} - 0.1 V$				
1.8 V ± 0.15 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V				
2.5 V ± 0.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V				
3.3 V $\pm$ 0.3 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	$V_{OH} - 0.3 V$				
5.0 V ± 0.5 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> – 0.3 V				

<sup>[1]</sup>  $V_{CCI}$  is the supply voltage associated with the input and  $V_{CCO}$  is the supply voltage associated with the output.

#### Dual supply translating transceiver; auto direction sensing; 3-state





Test data is given in Table 15.

All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  10 MHz;  $Z_0 = 50 \Omega$ ; dV/dt  $\geq$  1.0 V/ns.

R<sub>L</sub> = Load resistance.

C<sub>L</sub> = Load capacitance including jig and probe capacitance.

 $V_{EXT}$  = External voltage for measuring switching times.

#### Fig 8. Test circuit for measuring switching times

Table 15. Test data

Supply voltage		Input		Load		V <sub>EXT</sub>			
	V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	۷ <sub>ا</sub> [1]	Δt/ΔV	CL	R <sub>L</sub> [2]	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]
	1.2 V to 3.6 V	1.65 V to 5.5 V	$V_{CCI}$	≤ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>

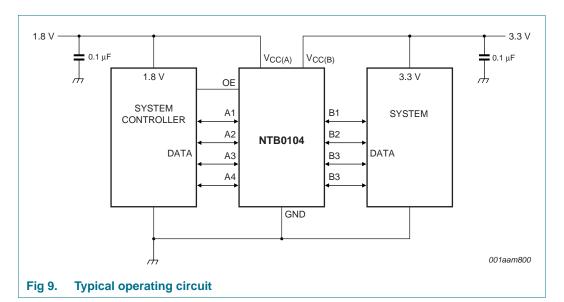
- [1] V<sub>CCI</sub> is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L = 1 \text{ M}\Omega$ ; for measuring enable and disable times,  $R_L = 50 \text{ k}\Omega$ .
- [3]  $V_{CCO}$  is the supply voltage associated with the output.

Dual supply translating transceiver; auto direction sensing; 3-state

## 12. Application information

## 12.1 Applications

Voltage level-translation applications. The NTB0104 can be used to interface between devices or systems operating at different supply voltages. See <u>Figure 9</u> for a typical operating circuit using the NTB0104.

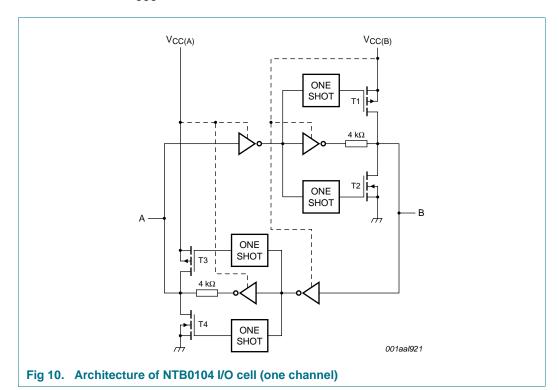


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#### Dual supply translating transceiver; auto direction sensing; 3-state

#### 12.2 Architecture

The architecture of the NTB0104 is shown in Figure 10. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NTB0104 can maintain a defined output level, but the output architecture is designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output one shots detect rising or falling edges on the A or B ports. During a rising edge, the one shots turn on the PMOS transistors (T1, T3) for a short duration, accelerating the low-to-high transition. Similarly, during a falling edge, the one shots turn on the NMOS transistors (T2, T4) for a short duration, accelerating the high-to-low transition. During output transitions the typical output impedance is 70  $\Omega$  at  $V_{\rm CCO}$  = 1.2 V to 1.8 V, 50  $\Omega$  at  $V_{\rm CCO}$  = 1.8 V to 3.3 V and 40  $\Omega$  at  $V_{\rm CCO}$  = 3.3 V to 5.0 V.

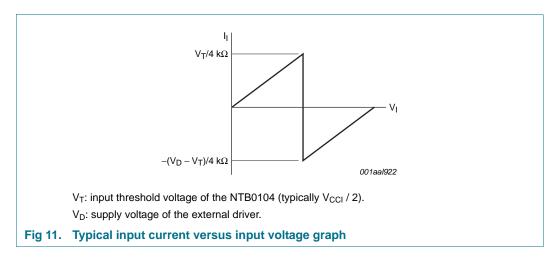


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### 12.3 Input driver requirements

For correct operation, the device driving the data I/Os of the NTB0104 must have a minimum drive capability of  $\pm 2$  mA See Figure 11 for a plot of typical input current versus input voltage.



### 12.4 Power up

During operation  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ , however during power-up  $V_{CC(A)} \ge V_{CC(B)}$  does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTB0104 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

#### 12.5 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{dis}$  with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ( $t_{en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

#### 12.6 Pull-up or pull-down resistors on I/O lines

As mentioned previously the NTB0104 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistors used must be kept higher than 50 k $\Omega$ . For this reason the NTB0104 is not recommended for use in open drain driver applications such as 1-Wire or I<sup>2</sup>C. For these applications, the NTS0104 level translator is recommended.

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## 13. Package outline

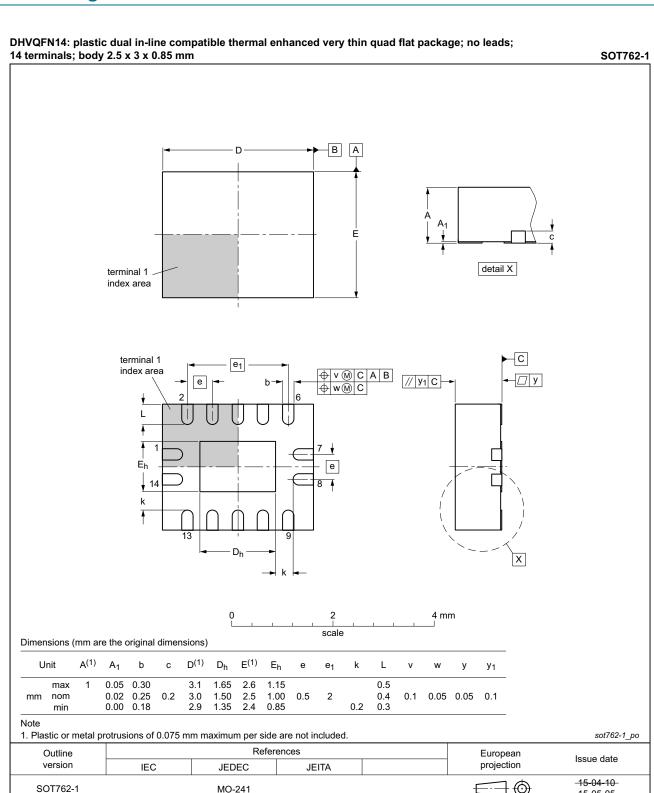


Fig 12. Package outline SOT762-1 (DHVQFN14)

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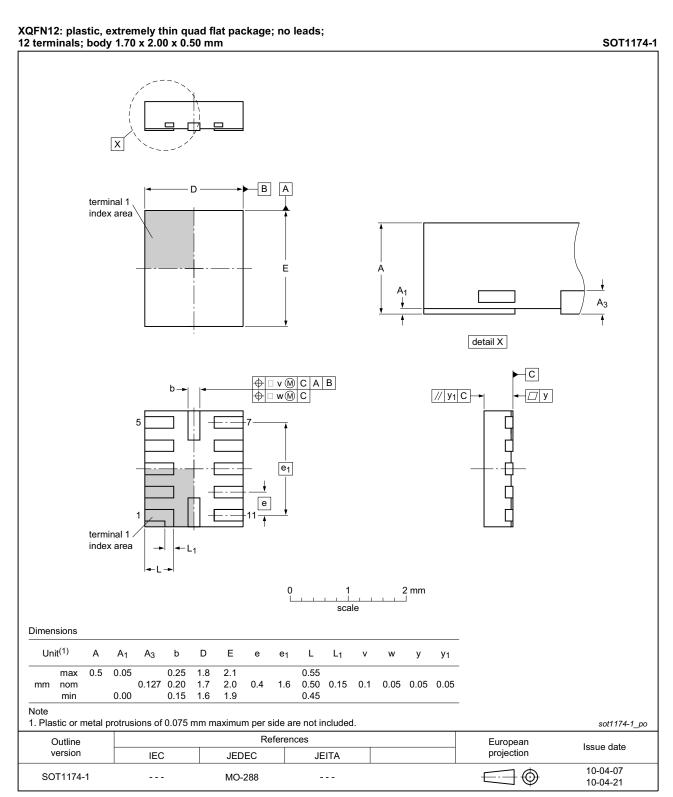


Fig 13. Package outline SOT1174-1 (XQFN12)

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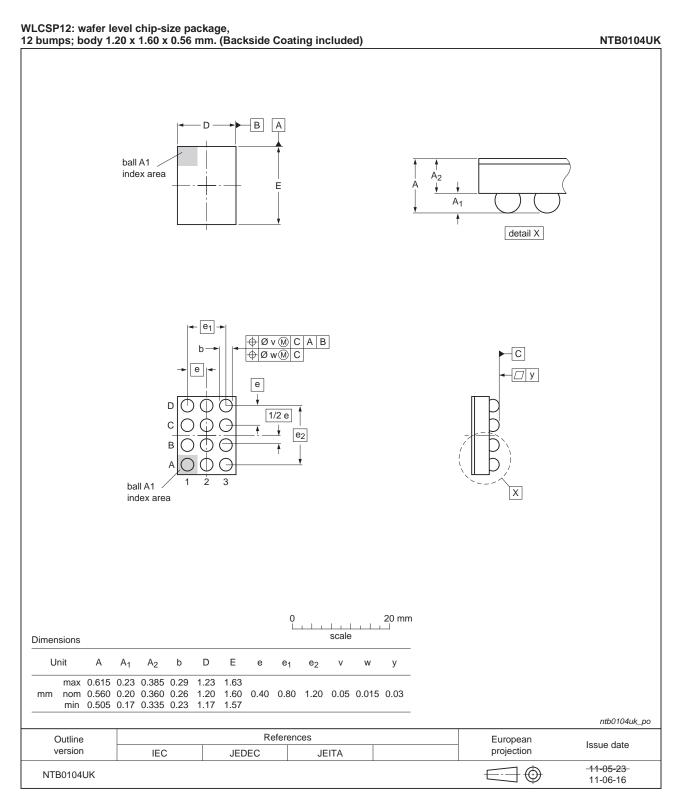
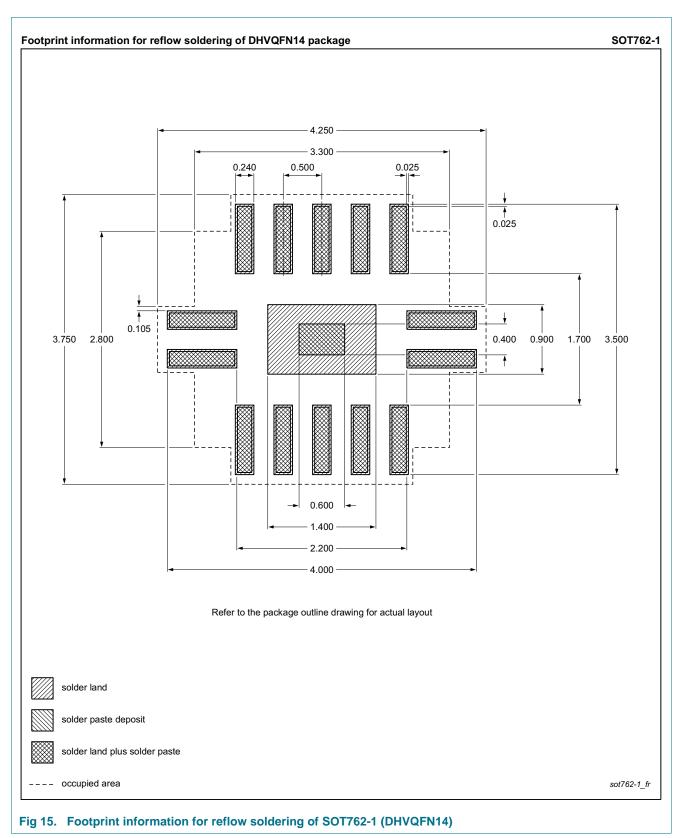


Fig 14. Package outline WLCSP12 package

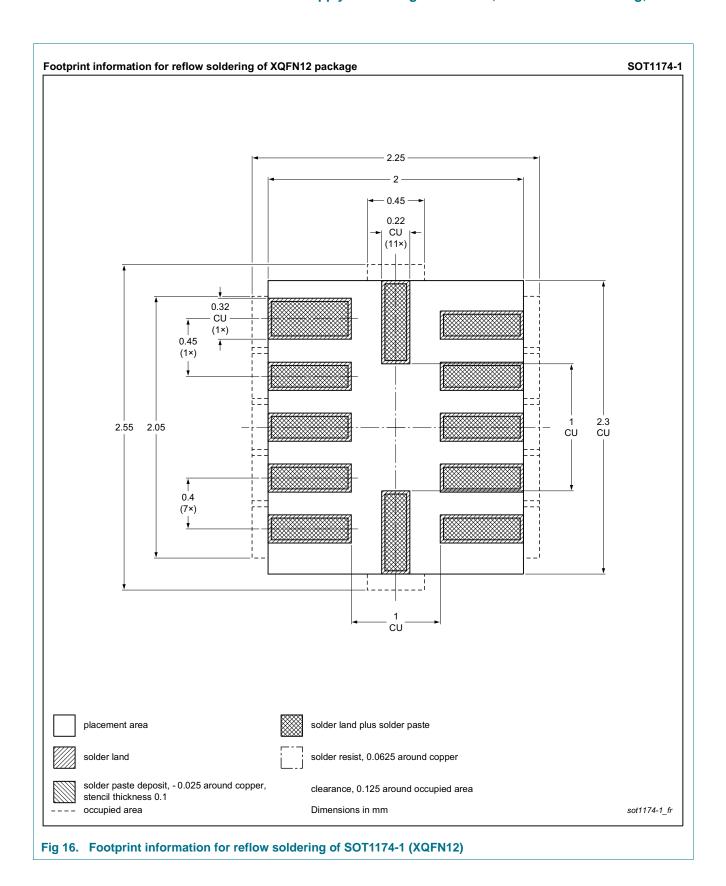
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## 14. Footprint information



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## 15. Abbreviations

#### Table 16. Abbreviations

Acronym	Description
CDM	Charged Device Model
CMOS	Complementary Metal Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

# 16. Revision history

#### Table 17. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
NTB0104 v.4	20180419	Product data sheet	-	NTB0104 v.3
Modifications:	gap dimer  Added Se  Removed		Section 14 "Footprint	d "k" heat pad to pin minimum information"
NTB0104 v.3	20111110	Product data sheet	-	NTB0104 v.2
Modifications:	Legal page	es updated.		
NTB0104 v.2	20111109	Product data sheet	-	NTB0104 v.1
NTB0104 v.1	20101026	Product data sheet	-	-

#### Dual supply translating transceiver; auto direction sensing; 3-state

## 17. Legal information

#### 17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <a href="http://www.nxp.com">http://www.nxp.com</a>.

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#### Dual supply translating transceiver; auto direction sensing; 3-state

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### Dual supply translating transceiver; auto direction sensing; 3-state

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