

Revision History

Revision	Date	Description	
1.9	Oct 2009	Updated section 5.1, table 2.	
1.8	Aug 2009	Updated section 5.2, table 3.	
1.7	Oct 2005	Changed interrupt signals INTA# and INTB# symbol types from TS (tristate) to OD (open drain).	
1.6	June 2005	Added a more detailed AUX_PWR pin description.	
1.0	Julie 2003	Added tristate and XOR non-JTAG test modes description.	
		Added lead-free product and ordering information.	
	April 2005	Added major product features to cover page.	
1.5		Added text stating that the TTL inputs on the Ethernet controller are not 5V tolerant.	
		Updated thermal specifications.	
1.4	Sept 2004	Corrected the nominal impedance values for the I/O cells from 50 K Ω to a nominal impedance value of 120 K Ω , with a minimum of 90 K Ω and a maximum of 190 K Ω .	
1.3	Dec 2003	Added an I/O Characteristics table in Section 4.3, "DC Characteristics."	
1.2	Nov 2003	Corrected typing error of "q" to "0" in Section 6.3, "Thermal Specifications," on page 38.	
1.1	Sept 2003	Declassified document from confidential status.	
1.0	July 2003	Initial release.	

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Copies of documents which have an ordering number and are referenced in this document, or other Intel literature may be obtained by calling 1-800-548-4725 or by visiting Intel's website at http://www.intel.com.

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1.0 Introduction

The Intel® 82546GB Dual Port Gigabit Ethernet Controller is a single, compact component with two full integrated Gigabit Ethernet Media Access Control (MAC) and physical layer (PHY) functions. The Intel® 82546GB enables dual port Gigabit Ethernet implementations in a very small area and can be used for desktop and workstation PC network designs as well as backplane applications with critical space constraints.

The Intel® 82546GB integrates Intel's fourth generation gigabit MAC and PHY to provide a standard IEEE 802.3 Ethernet interface for 1000BASE-T, 100BASE-TX, and 10BASE-T applications (802.3, 802.3u, and 802.3ab). The controller is capable of transmitting and receiving two channels of data at rates of 1000 Mbps, 100 Mbps, or 10 Mbps. In addition, it provides a 64-bit wide direct Peripheral Component Interconnect (PCI) 2.3 and PCI-X 1.0a compliant interface capable of operating at frequencies up to 133 MHz. The 82546GB also delivers a dual port PCI-X solution without added bridge latency.

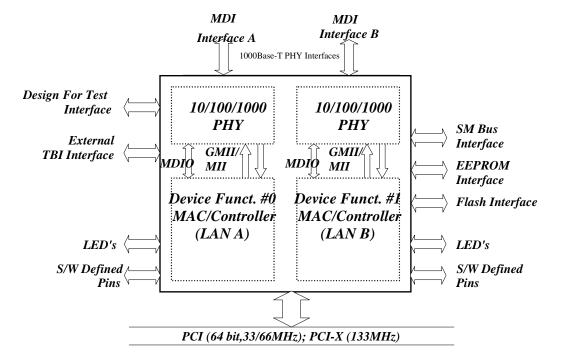
The Intel® 82546GB on-board System Management Bus (SMB) port enables network manageability implementations required by information technology personnel for remote control and alerting through the LAN. Using the SMB, management packets can be routed to or from a management processor. The SMB port enables industry standards, such as Intelligent Platform Management Interface (IPMI) and Alert Standard Format (ASF), to be implemented using the 82546GB. In addition, on chip ASF 1.0 circuitry provides alerting and remote control capabilities with standardized interfaces.

The 82546GB Dual Port Gigabit Ethernet Controller architecture is designed to deliver high performance and PCI/PCI-X bus efficiency. Wide internal data paths eliminate performance bottlenecks by efficiently handling large address and data words. Combining a parallel and pipelined logic architecture optimized for Gigabit Ethernet and independent transmit and receive queues, the 82546GB controller efficiently handles packets with minimum latency. The 82546GB controller includes advanced interrupt handling features to limit PCI bus traffic and a PCI interface that maximizes the use of bursts for efficient bus usage. The 82546GB is able to cache up to 64 packet descriptors in a single burst for efficient PCI bandwidth use. A large 64 Kbyte on-chip packet buffer maintains superior performance as available PCI bandwidth changes. By using hardware acceleration, the controller is able to offload tasks, such as checksum calculations and TCP segmentation, from the host processor.



The 82546GBis packaged in a 21 mm x 21 mm 364-ball grid array and footprint compatible with the Intel® 82544GC Gigabit Ethernet Controller and 82546EB Dual Port Gigabit Ethernet Controller.

Figure 1. Gigabit Ethernet Controller Block Diagram



1.1 Document Scope

This document contains datasheet specifications for the 82546GB Dual Port Gigabit Ethernet Controller, which includes signal descriptions, DC and AC parameters, packaging data, and pinout information.

1.2 Reference Documents

It is assumed that the designer is acquainted with high-speed design and board layout techniques. Document that may provide additional information are:

- PCI Local Bus Specification, Revision 2.3, PCI Special Interest Group.
- PCI-X Specification, Revision 1.0a, PCI Special Interest Group.
- PCI Bus Power Management Interface Specification, Rev. 1.1, PCI Special Interest Group.
- IEEE Standard 802.3, 1996 Edition, Institute of Electrical and Electronics Engineers (IEEE).
- IEEE Standard 802.3u, 1995 Edition, Institute of Electrical and Electronics Engineers (IEEE).
- IEEE Standard 802.3x, 1997 Edition, Institute of Electrical and Electronics Engineers (IEEE).
- IEEE Standard 802.3z, 1998 Edition, Institute of Electrical and Electronics Engineers (IEEE).



- IEEE Standard 802.3ab, 1999 Edition, Institute of Electrical and Electronics Engineers (IEEE).
- Intel[®] Ethernet Controllers Timing Device Selection Guide, AP-419. Intel Corporation.

1.3 Product Codes

The product ordering code for the 82546GB is: FW82546GB.

The lead-free product ordering code for the 82546GB is: NH82546GB.

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2.0 Additional 82546GB Features

2.1 PCI

Feature	Benefits
Algorithms that optimally use advanced PCI, MWI, MRM, and MRL commands as well as PCI-X MRD, MRB, and MWB commands	Efficient bus operations

2.2 MAC

Features	Benefits	
Low-latency transmit and receive queues	Network packets handled without waiting or buffer overflow.	
Caches up to 64 packet descriptors in a single burst	Efficient use of PCI bandwidth	
Descriptor ring management hardware for transmit and receive	Simple software programming model	
Mechanism available for reducing interrupts generated by transmit and receive operations	Maximizes system performance and throughput	
Support for transmission and reception of packets up to 16 Kbytes	Enables jumbo frames	

2.3 PHY

Feature	Benefits
State-of-the-art DSP architecture implements digital adaptive equalization, echo cancellation, and crosstalk cancellation	Robust performance in noisy environments Tolerance of common electrical signal impairments



2.4 Host Offloading

Features	Benefits
Descriptor ring management hardware for transmit and receive	Optimized fetching and write-back mechanisms for efficient system memory and PCI bandwidth usage
16-Kbyte jumbo frame support	High throughput for large data transfers on networks supporting jumbo frames
Interrupt coalescing (multiple packets per interrupt)	Increased throughput by reducing interrupts generated by transmit and receive operations

2.5 Manageability

Features	Benefits
On-board SMB port	Enables IPMI and ASF implementations Allows packets routing to and from either LAN port and a server management processor
Preboot eXecution Environment (PXE) Flash interface support (32-bit and 64-bit)	Local Flash interface for PXE image
Compliance with PCI Power Management 1.1 and ACPI 2.0 register set compliant including: D0 and D3 power states Network Device Class Power Management Specification 1.1 PCI Specification 2.3	PCI power management capability requirements for PC and embedded applications
SNMP and RMON statistic counters	Easy system monitoring with industry standard consoles
SDG 3.0, WfM 2.0, and PC2001 compliance	Remote network management capabilities through DMI 2.0 and SNMP software
Wake on LAN support	Packet recognition and wake-up for NIC and LOM applications without software configuration
IPMI MAC Address Read capability	Allows MAC address read to be read by remote users through IMPI
IPMI I ² C Addressing capability	Enables device addressing over the I ² C bus



2.6 Device

Features	Benefits
Internal PLL for clock generation (use either a 25 MHz crystal or a 25 MHz oscillator)	Lower component count and system cost
JTAG (IEEE 1149.1) Test Access Port built in silicon	Simplified testing using boundary scan
On-chip power control circuitry	Reduced number of on-board power supply regulators
	Simplified power supply design
Eight software definable pins	Additional flexibility for LEDs or other low speed I/O devices
Supports little endian byte ordering for both 32 and 64 bit systems and big endian byte ordering for 64 bit systems	Portable across application architectures
Provides loopback capabilities	Validates silicon integrity
Single-pin LAN disable function	Allows LAN port enabling and disabling through BIOS control (OS not required) for both ports
VLAN Management Filtering	Allows VLAN-based management packet filtering
Full 2/3 Wire Downshift capability	Allows silicon to downshift speed to two or three wire install and still achieve valid link
PICMIG 3.1 Compliant SERDES Interface	Enables interface connections with PICMIG 3.1 compliant devices

2.7 Technology

Features	Benefits
364-pin Ball Grid Array (BGA) package	21 mm x 21 mm component makes LOM designs easier
Footprint compatible with the 82544GC/EI and 82545GM/EM single port gigabit Ethernet controllers	Single port or dual port implementation on the same board with minor option changes.
Implemented in 0.15µ CMOS process	Offers lowest geometry to minimize power and size while maintaining Intel quality reliability standards
3.3 V PCI signaling with an average power dissipation of 3.5 W	Lower power requirements
Operating temperature: 0° C to 55° C (with or without thermal management, maximum); 0° C to 70° C (with increased thermal management, maximum)	Extended temperature attainable with thermal management device for more demanding systems requiring a wider temperature range.



3.0 Signal Descriptions

Note: The targeted signal names are subject to change without notice. Verify with your local Intel sales office that you have the latest information before finalizing a design.

3.1 Signal Type Definitions

The signals of the 82546GB controller are electrically defined as follows:

Name	Definition
I	Input. Standard input only digital signal.
0	Output. Standard output only digital signal.
TS	Tri-state. Bi-directional three-state digital input/output signal.
STS	Sustained Tri-state. Sustained digital three-state signal driven by one agent at a time. An agent driving the STS pin low must actively drive it high for at least one clock before letting it float. The next agent of the signal cannot drive the pin earlier than one clock after it has been released by the previous agent.
OD	Open Drain. Wired-OR with other agents. The signaling agent asserts the OD signal, but the signal is returned to the inactive state by a weak pull-up resistor. The pull-up resistor may require two or three clock periods to fully restore the signal to the de-asserted state.
Α	Analog. PHY analog data signal.
Р	Power. Power connection, voltage reference, or other reference connection.
R	Reserved.

Note: The TTL inputs on the Ethernet controller are not 5V tolerant. If these inputs are connected to 5V, then damage to the Ethernet controller is likely to occur. TTL inputs include the JTAG interface pins, the FLASH interface pins, the EEPROM interface pins, the LED pins, the software definable pins, and the LAN_PWR_GOOD pin.

3.2 PCI Bus Interface

When the Reset signal (RST#) is asserted, the 82546GB will not drive any PCI output or bidirectional pins except the Power Management Event signal (PME#).



3.2.1 PCI Address, Data and Control Signals

Symbol	Туре	Name and Function		
	TS	Address and Data. Address and data signals are multiplexed on the same PCI pins. A bus transaction includes an address phase followed by one or more data phases.		
AD[63:0]		The address phase is the clock cycle when the Frame signal (FRAME#) is asserted low. During the address phase AD[63:0] contain a physical address (64 bits). For I/O, this is a byte address, and for configuration and memory, a DWORD address. The 82546GB device uses little endian byte ordering.		
		During data phases, AD[7:0] contain the least significant byte (LSB) and AD[63:56] contain the most significant byte (MSB).		
		The 82546GBcontroller may optionally be connected to a 32-bit PCI bus. On the 32-bit bus, AD[63:32] and other signals corresponding to the high order byte lanes do not participate in the bus cycle.		
CBE[7:0]#	TS	Bus Command and Byte Enables. Bus command and byte enable signals are multiplexed on the same PCI pins. During the address phase of a transaction, CBE[7:0]# define the bus command. In the data phase, CBE[7:0]# are used as byte enables. The byte enables are valid for the entire data phase and determine which byte lanes contain meaningful data.		
		CBE0# applies to byte 0 (LSB) and CBE7# applies to byte 7 (MSB).		
PAR	TS	Parity. The Parity signal is issued to implement even parity across AD[31:0] and CBE[3:0]#. PAR is stable and valid one clock after the address phase. During data phases, PAR is stable and valid one clock after either IRDY# is asserted on a write transaction or TRDY# is asserted after a read transaction. Once PAR is valid, it remains valid until one clock after the completion of the current data phase.		
		When the 82546GB controller is a bus master, it drives PAR for address and write data phases, and as a slave device, drives PAR for read data phases.		
PAR64	TS	Parity 64. The Parity 64 signal is issued to implement even parity across AD[63:32] and CBE[7:4]#. PAR64 is stable and valid one clock after the address phase. During data phases, PAR64 is stable and valid one clock after either IRDY# is asserted on a write transaction or TRDY# is asserted after a read transaction. Once PAR64 is valid, it remains valid until one clock after the completion of the current data phase.		
		When the 82546GB controller is a bus master, it drives PAR64 for address and write data phases, and as a slave device, drives PAR64 for read data phases.		
FRAME#	STS	Cycle Frame. The Frame signal is driven by the 82546GB device to indicate the beginning and length of an access and indicate the beginning of a bus transaction. While FRAME# is asserted, data transfers continue. FRAME# is de-asserted when the transaction is in the final data phase.		
IRDY#	STS	Initiator Ready. Initiator Ready indicates the ability of the 82546GB controller (as bus master device) to complete the current data phase of the transaction. IRDY# is used in conjunction with the Target Ready signal (TRDY#). The data phase is completed on any clock when both IRDY# and TRDY# are asserted.		
IRDY#	515	During the write cycle, IRDY# indicates that valid data is present on AD[63:0]. For a read cycle, it indicates the master is ready to accept data. Wait cycles are inserted until both IRDY# and TRDY# are asserted together. The 82546GB controller drives IRDY# when acting as a master and samples it when acting as a slave.		
TPDV#	STS	Target Ready. The Target Ready signal indicates the ability of the 82546GB controller (as a selected device) to complete the current data phase of the transaction. TRDY# is used in conjunction with the Initiator Ready signal (IRDY#). A data phase is completed on any clock when both TRDY# and IRDY# are sampled asserted.		
TRDY#		During a read cycle, TRDY# indicates that valid data is present on AD[63:0]. For a write cycle, it indicates the target is ready to accept data. Wait cycles are inserted until both IRDY# and TRDY# are asserted together. The 82546GB device drives TRDY# when acting as a slave and samples it when acting as a master.		



Symbol	Туре	Name and Function	
STOP#	STS	Stop. The Stop signal indicates the current target is requesting the master to stop the current transaction. As a slave, the 82546GB controller drives STOP# to request the bus master to stop the transaction. As a master, the 82546GB controller receives STOP# from the slave to stop the current transaction.	
IDSEL#	I	nitialization Device Select. The Initialization Device Select signal is used by the 2546GB as a chip select signal during configuration read and write transactions.	
DEVSEL#	STS	Device Select. When the Device Select signal is actively driven by the 82546GB, it signals notifies the bus master that it has decoded its address as the target of the current access. As an input, DEVSEL# indicates whether any device on the bus has been selected.	
VIO	Р	VIO. The VIO signal is a voltage reference for the PCI interface (3.3 V or 5 V PCI signaling environment). It is used as the clamping voltage. Note: An external resistor is required between the voltage reference and the VIO pin. The target resistor value is $100 \text{ K}\Omega$	

3.2.2 Arbitration Signals

Symbol	Туре	Name and Function	
REQ64#	TS	Request Transfer. The Request Transfer signal is generated by the current initiator indicating its desire to perform a 64-bit transfer. REQ64# has the same timing as the Frame signal.	
ACK64#	TS	nowledge Transfer. The Acknowledge Transfer signal is generated by the ently addressed target in response to the REQ64# assertion by the initiator. (64# has the same timing as the Device Select signal.	
REQ#	TS	Request Bus. The Request Bus signal is used to request control of the bus from the ribiter. This signal is point-to-point.	
GNT#	I	Grant Bus. The Grant Bus signal notifies the 82546GB that bus access has been pranted. This is a point-to-point signal.	
LOCK#	I	Lock Bus. The Lock Bus signal is asserted by an initiator to require sole access to a target memory device during two or more separate transfers. The 82546GB device does not implement bus locking.	

3.2.3 Interrupt Signals

Symbol	Туре	Name and Function
INTA#	OD	Interrupt A. Interrupt A is used to request an interrupt by port 1 of the 82546GB. It is an active low, level-triggered interrupt signal.
INTB#	OD	Interrupt B. Interrupt B is used to request an interrupt by port 2 of the 82546GB. It is an active low, level-triggered interrupt signal.



3.2.4 System Signals

Symbol	Туре	Name and Function	
CLK	I	PCI Clock. The PCI Clock signal provides timing for all transactions on the PCI bus and is an input to the 82546GB device. All other PCI signals, except the Interrupt A (INTA#) and PCI Reset signal (RST#), are sampled on the rising edge of CLK. All other timing parameters are defined with respect to this edge.	
M66EN	I	6 MHz Enable. The 66 MHz Enable signal is used to indicate whether or not the ystem bus is capable of supporting an operating frequency of 66 MHz.	
RST#	I	PCI Reset. When the PCI Reset signal is asserted, all PCI output signals, except the Power Management Event signal (PME#), are floated and all input signals are ignored. The PME# context is preserved, depending on power management settings.	
		Most of the internal state of the 82546GB is reset on the de-assertion (rising edge) of RST#.	
LAN_ PWR_ GOOD	I	Power Good (Power-on Reset). The Power Good signal is used to indicate that stable power is available for the 82546GB. When the signal is low, the 82546GB holds itself in reset state and floats all PCI signals.	

3.2.5 Error Reporting Signals

Symbol	Туре	Name and Function	
SERR#	OD System Error. The System Error signal is used by the 82546GB controller to readdress parity errors. SERR# is open drain and is actively driven for a single PC when reporting the error.		
PERR#	STS	Parity Error. The Parity Error signal is used by the 82546GB controller to report data parity errors during all PCI transactions except by a Special Cycle. PERR# is sustained tri-state and must be driven active by the 82546GB controller two data clocks after a data parity error is detected. The minimum duration of PERR# is one clock for each data phase a data parity error is present.	

3.2.6 Power Management Signals

Symbol	Туре	Name and Function	
PME# OD		Power Management Event. The 82546GB device drives this signal low when it receives a wake-up event and either the PME Enable bit in the Power Management Control/Status Register or the Advanced Power Management Enable (APME) bit of the Wake-up Control Register (WUC) is 1b.	
AUX_PWR	I	Auxiliary Power. If the Auxiliary Power signal is high, then auxiliary power is available and the 82546GB device should support the D3cold power state. Note that AUX_PWR is not a supply input, but is an indication of whether AUX_PWR is available to the 82546GB and/or subsystem. Setting AUX_PWR to 1b enables advertising D3cold Wake Up support and changes the reset function of PME_En and PME_Status. AUX_PWR is level sensitive, and any changes are immediately reflected in the D3cold Wake Up advertisements and the PME_En and PME_Status behavior on PCI reset.	



3.2.7 Impedance Compensation Signals

Symbol	Туре	Name and Function		
ZN_COMP	I/O	N Device Impedance Compensation. This signal should be connected to an external precision resistor (to VDD) that is indicative of the PCI/PCI-X trace load. This cell is used to dynamically determine the drive strength required on the N-channel transistors in the PCI/PCI-X I/O cells.		
		The internal pull-up impedance is nominally 120 K Ω with a minimum of 90 K Ω and a maximum of 190 K Ω .		
ZP_COMP	I/O	P Device Impedance Compensation. This signal should be connected to an external precision resistor (to VSS) that is indicative of the PCI/PCI-X trace load. This cell is used to dynamically determine the drive strength required on the P-channel transistors in the PCI/PCI-X I/O cells.		
		The internal pull-up impedance is nominally 120 K Ω with a minimum of 90 K Ω and a maximum of 190 K Ω .		

3.2.8 SMB Signals

Note: A pull-up resistor with a recommended value of 4.7 K Ω should be placed along the SMB. A precise value may be calculated from the SMB specification.

Symbol	Туре	Name and Function
SMBCLK	I/O	SMB Clock. The SMB Clock signal is an open drain signal for serial SMB interface.
SMBDATA	I/O	SMB Data. The SMB Data signal is an open drain signal for serial SMB interface.
SMBALRT #	0	SMB Alert. The SMB Alert signal is open drain for serial SMB interface.

3.3 **EEPROM Interface Signals**

Symbol	Туре	Name and Function	
EE_DI	0	EEPROM Data Input. The EEPROM Data Input pin is used for output to the memory device.	
EE_DO	I	EEPROM Data Output. The EEPROM Data Output pin is used for input from the memory device. The EE_DO includes an internal pull-up resistor.	
EE_CS	0	EEPROM Chip Select. The EEPROM Chip Select signal is used to enable the device.	
EE_SK	0	EEPROM Serial Clock . The EEPROM Shift Clock provides the clock rate for the EEPROM interface, which is approximately 1 MHz.	



3.4 Flash Interface Signals

Symbol	Туре	Name and Function	
FL_ADDR [18:0]	0	Flash Address Output. The Flash Address Output signals are used for a Flash or Boot ROM device.	
FL_CS#	0	Flash Chip Select. The Flash Chip Select signal is used to enable the Flash or Boot ROM device.	
FL_OE#	0	Flash Output Enable. The Flash Output Enable signal is used to enable the Flash buffers.	
FL_WE#	0	Flash Write Enable Output. The Flash Write ENable Output signals are used for write cycles.	
FL_DATA [7:2]	TS	Flash Data I/O. The Flash Data I/O signals are bi-directional and used for Flash data These signals include internal pull-up devices.	
FL_DATA [1:0]/ LAN_DISA BLE#	TS	Flash Data I/O [1:0] / LAN Port Disable. These pins are inputs from the Flash memory. Alternatively, they can be used to disable the LAN A or LAN B port from a system Super I/O General (GP) port. (FL_DATA[1] corresponds to LAN B, and FL_DATA[0], to LAN A.) They have internal pull-up devices. If the 82546GB is not using Flash functionality, these pins should be connected to external pull-up resistors. If the pins are used as LAN_DISABLE#, the device transitions to a low power state, and the corresponding LAN port is disabled when its pin is sampled low on the rising edge of PCI reset.	

3.5 Miscellaneous Signals

3.5.1 LED Signals

Symbol	Туре	Name and Function
LED1/ACT#	0	Activity. Programmable LED indication. Defaults to flash to indicate transmit or receive activity.
LED0/LINK#	0	Link. Programmable LED indication. Defaults to indicate link connectivity.
LED2/LINK100#	0	Link100. Programmable LED indication. Defaults to indicate link at 100 Mbps.
LED3/LINK1000#	0	Link1000. Programmable LED indication. Defaults to indicate link at 1000 Mbps.

3.5.2 Software Definable Signals

Symbol	Туре	Name and Function		
SDP[7:6] SDP[1:0]	TS	Software Defined Pin. The Software Defined Pins are reserved and programmable with respect to input and output capability. These default to input signals upon power-up but may be configured differently by the EEPROM. The upper four bits may be mapped to the General Purpose Interrupt bits if they are configured as input signals. Note: SDP5 is not included in the group of Software Defined Pins.		



3.6 PHY Signals

3.6.1 Crystal Signals

Symbol	Туре	Name and Function		
XTAL1	I	Crystal One. The Crystal One pin is a 25 MHz +/- 30 ppm input signal. It can be connected to either an oscillator or crystal. If a crystal is used, Crystal Two (XTAL2) must also be connected.		
XTAL2	0	Crystal Two. Crystal Two is the output of an internal oscillator circuit used to drive a crystal into oscillation. If an external oscillator is used in the design, XTAL2 must be disconnected.		

3.6.2 PHY Analog Signals

Symbol	Туре	Name and Function			
REF_A	Р	Reference A. This Reference signal should be connected to VSS through an external 2.49 $K\Omega$ resistor.			
		Media Dependent Interface A [0].			
		1000BASE-T : In MDI configuration, MDIA[0]+/- corresponds to BI_DA+/-, and in MDI-X configuration, MDIA[0]+/- corresponds to BI_DB+/			
MDIA[0]+/-	Α	100BASE-TX : In MDI configuration, MDIA[0]+/- is used for the transmit pair, and in MDI-X configuration, MDIA[0]+/- is used for the receive pair.			
		10BASE-T : In MDI configuration, MDIA[0]+/- is used for the transmit pair, and in MDI-X configuration, MDIA[0]+/- is used for the receive pair.			
		Media Dependent Interface A [1].			
		1000BASE-T : In MDI configuration, MDIA[1]+/- corresponds to BI_DB+/-, and in MDI-X configuration, MDIA[1]+/- corresponds to BI_DA+/			
MDIA[1]+/-	Α	100BASE-TX : In MDI configuration, MDIA[1]+/- is used for the receive pair, and in MDI-X configuration, MDIA[1]+/- is used for the transit pair.			
		10BASE-T : In MDI configuration, MDIA[1]+/- is used for the receive pair, and in MDI-X configuration, MDIA[1]+/- is used for the transit pair.			
	А	Media Dependent Interface A [2].			
MDIA[2]+/-		1000BASE-T : In MDI configuration, MDIA[2]+/- corresponds to BI_DC+/-, and in MDI-X configuration, MDIA[2]+/- corresponds to BI_DD+/			
		100BASE-TX: Unused.			
		10BASE-T: Unused.			
		Media Dependent Interface A [3].			
MDIA[3]+/-	А	1000BASE-T : In MDI configuration, MDIA[3]+/- corresponds to BI_DD+/-, and in MDI-X configuration, MDIA[3]+/- corresponds to BI_DC+/			
		100BASE-TX: Unused.			
		10BASE-T: Unused.			
REF_B	Р	Reference B. This Reference signal should be connected to VSS through an external 2.49 $K\Omega$ resistor.			



Symbol	Туре	Name and Function		
		Media Dependent Interface B [0].		
		1000BASE-T : In MDI configuration, MDIB[0]+/- corresponds to BI_DA+/-, and in MDI-X configuration, MDIB[0]+/- corresponds to BI_DB+/		
MDIB[0]+/-	Α	100BASE-TX: In MDI configuration, MDIB[0]+/- is used for the transmit pair, and in MDI-X configuration, MDIB[0]+/- is used for the receive pair.		
		10BASE-T : In MDI configuration, MDIB[0]+/- is used for the transmit pair, and in MDI-X configuration, MDIB[0]+/- is used for the receive pair.		
		Media Dependent Interface B [1].		
	А	1000BASE-T : In MDI configuration, MDIB[1]+/- corresponds to BI_DB+/-, and in MDI-X configuration, MDIB[1]+/- corresponds to BI_DA+/		
MDIB[1]+/-		100BASE-TX : In MDI configuration, MDIB[1]+/- is used for the receive pair, and in MDI-X configuration, MDIB[1]+/- is used for the transit pair.		
		10BASE-T : In MDI configuration, MDIB[1]+/- is used for the receive pair, and in MDI-X configuration, MDIB[1]+/- is used for the transit pair.		
	А	Media Dependent Interface B [2].		
MDIB[2]+/-		1000BASE-T : In MDI configuration, MDIB[2]+/- corresponds to BI_DC+/-, and in MDI-X configuration, MDIB[2]+/- corresponds to BI_DD+/		
		100BASE-TX: Unused.		
		10BASE-T: Unused.		
MDIB[3]+/-		Media Dependent Interface B [3].		
	А	1000BASE-T : In MDI configuration, MDIB[3]+/- corresponds to BI_DD+/-, and in MDI-X configuration, MDIB[3]+/- corresponds to BI_DC+/		
		100BASE-TX: Unused.		
		10BASE-T: Unused.		

3.7 Serializer / Deserializer Signals

Symbol	Туре	Name and Function		
RXA+/- RXB +/-	I	SERDES Receive Pairs A and B. These signals make the differential receive pair for the 1.25 GHz serial interface. If the SERDES interface is not used, these pins should not be connected.		
TXA+/- TXB +/-	0	SERDES Transmit Pairs A and B. These signals make the differential transmit pair for the 1.25 GHz serial interface. If the SERDES interface is not used, these pins should not be connected.		
SIG_ DETECT (A and B)	I	Signal Detects A and B. These pins indicate whether the SERDES signals (connected to the 1.25 GHz serial interface) have been detected by the optical transceivers. If the SERDES interface is not used, the SIG_DETECT inputs should connected to ground using pull-down resistors.		



3.8 JTAG Test Interface Signals

Symbol	Туре	Name and Function			
JTAG_TCK	I	JTAG Clock.			
JTAG_TDI	I	AG TDI.			
JTAG_TDO	0	JTAG TDO.			
JTAG_TMS	I	JTAG TMS.			
JTAG_ TRST#	I	JTAG Reset. This is an active low reset signal for JTAG. This signal should be terminated using a pull-down resistor to ground. It must not be left unconnected.			
CLK_VIEW	0	Clock View. The Clock View signal is an output of clock signals required for IEEE testing.			
TEST#	I	Factory Test Pin. This is an active low input and has an internal pull-up resistor. For normal operation, TEST# should be left unconnected.			

3.9 Power Supply Connections

3.9.1 Power Support Signals

Symbol	Туре	Name and Function		
CTRL_15	0	1.5 V Control. The 1.5 V Control signal is an output to an external power transistor. If regulators are used, it should be left unconnected.		
CTRL_25A	0	2.5 V Control. The 2.5 V Control signal is an output to an external power transistor. It regulators are used, it should be left unconnected.		
CTRL_25B	0	2.5 V Control. The 2.5 V Control signal is an output to an external power transistor. regulators are used, it should be left unconnected.		

3.9.2 Digital Supplies

Symbol	Туре	Name and Function	
VDDO	Р	3.3 V I/O Power Supply.	
DVDD	Р	1.5 V Digital Core Power Supply.	

3.9.3 Analog Supplies

Symbol	Туре	Name and Function	
AVDDH	Р	3.3 V Analog Power Supply.	
AVDDLA	Р	2.5 V Analog Power Supply to Port A.	
AVDDLB	Р	2.5 V Analog Power Supply to Port B.	



3.9.4 Ground and No Connects

Symbol	Туре	Name and Function			
GND	Р	Ground.			
NC	Р	No Connect. Do not connect any circuitry to these pins. Pull-up or pull-down resistors should not be connected to these pins.			
Reserved	R	Reserved. These pins are reserved for factory purposes and should be left unconnected. (However, the following pins should be pulled down to ground: A20, B18 and M5. In addition, the following pins should be pulled down to ground through a 1 Ks pull-down resistor: A6, E7 and R1.)			



4.0 Test Port Functionality

4.1 XOR Testing

A common board or system-level manufacturing test for proper electrical continuity between a silicon component and the board is some type of cascaded-XOR or NAND tree test. The 82546GB implements an XOR tree spanning most I/O signals. The component XOR tree consists of a series of cascaded XOR logic gates, each stage feeding in the electrical value from a unique pin. The output of the final stage of the tree is visible on an output pin from the component.



Figure 2. XOR Tree Concept

By connecting to a set of test-points or bed-of-nails fixture, a manufacturing test fixture can test connectivity to each of the component pins included in the tree by sequentially testing each pin, testing each pin when driven both high and low, and observing the output of the tree for the expected signal value and/or change.

4.1.1 XOR Tree Control and Operation

The following signals are required to place the 82546GB in XOR tree test mode:

Test Function/ Mode	Pin Name	TEST_DM_N	EWRAP	CLK_BYP_N	CLK_VIEW	SDP_B[7]
	Dual-Mode Name		TEST_ MODE[3]	TEST_ MODE[2]	TEST_ MODE[1]	TEST_ MODE[0]
XOR Tree Test		0	0	0	0	0



I/O pins with dual-mode function for XOR test:

Pin Name	Dual-Mode Name	Pin Function
FLSH_CE_N	XOR_OUT	Output of XOR tree.

When XOR tree test is selected, the following pin behavior(s) occur:

- Output drivers for the pins listed as tested are all placed in high-impedance (tri-state) state to ensure that the board/system test fixture can drive the tested inputs without contention
- The output driver for the XOR tree output on pin FLSH_CE_N is explicitly enabled.

4.1.2 Pins Tested

When performing XOR test, those pins tested by the XOR tree all function as inputs, regardless of the normal directionality of the pin. The following table(s) cites the pins tested and not-testable as inputs to the XOR tree. Table entries do not reflect the natural order of input into the XOR tree itself (nor need to, as the output of a multi-input XOR function is order-independent).

Pins included in XOR test tree are listed in Table 1:

Table 1. Tested Pins Included in XOR Tree

Pin Name	Pin Name	Pin Name
PCI_AD[63:0]	M66EN	RX_DATA[7:0]
PCI_CBE_N[7:0]	PCI_RST_N	RBC0/RX_CLK
PCI_PAR	LAN_PWR_GOOD	RBC1/MTX_CLK
PCI_PAR64	PCI_SERR_N	EE_DI
PCI_FRAME_N	PCI_PERR_N	EE_DO
PCI_IRDY_N	PCI_PME_N	EE_CS
PCI_TRDY_N	AUX_PWR	EE_SK
PCI_STOP_N	SMBCLK	FLSH_ADDR[18:0]
PCI_IDSEL	SMBDAT	FLSH_OE_N
PCI_DEVSEL_N	TX_DATA[9]/TX_ER	FLSH_WE_N
PCI_REQ64_N	TX_DATA[8]/TX_EN	FLSH_DATA[7:0]
PCI_ACK64_N	TX_DATA[7:0]	LED_A[3:0]
PCI_REQ_N	GTX_CLK	LED_B[3:0]
PCI_GNT_N	COL	SDP_A[7,6,1,0]
PCI_LOCK_N	CRS	SDP_B[6,1,0]
PCI_INTA_N	LINK/LOS	ALTCLK_125
PCI_INTB_N	RX_DATA[9]/RX_ER	
PCI_CLK	RX_DATA[8]/RX_DV	



Pins not included in XOR test tree:

- JTAG (TAP) interface: TRST_N, TCK, TDO, TMS, and TDO
- Test mode decode controls TEST_DM_N, EWRAP, CLK_BYP_N, CLK_VIEW, and SDP_B[7]
- Each internal PHY's analog signals including PHYREF, MDI +/-, and PHY_HSDACP/N
- PCI Impedance Compensation ZPCOMP and ZNCOMP
- Oscillator signals XTAL1 and XTAL2
- Test signals including PHY_TSTPT and each PHY's HSDACP/N
- Power-control pins CTRL_15, CTRL_25_A, and CTRL_25_B
- SMB_ALERT_N/PCI_PWR_GOOD

4.2 Tristate Mode

The 82546GB's tristate test mode is used to explicitly disable output drivers and place outputs in high-impedance (tristate) state. To more readily support XOR or NAND-tree like testing of other system components, the 82546GB decodes this test mode from the same signal pins used to exercise XOR tree testing. The 82546GB additionally supports a mechanism to enter tristate mode via the IEEE 802.3 JTAG (TAP) controller.

4.2.1 Tristate Mode Control and Operation

The following signals are required to place the 82546GB in tristate test mode:

Test Function/ Mode	Pin Name	TEST_DM_N	EWRAP	CLK_BYP_N	CLK_VIEW	SDP_B[7]
	Dual-Mode Name		TEST_ MODE[3]	TEST_ MODE[2]	TEST_ MODE[1]	TEST_ MODE[0]
Tristate Mode		0	0	1	0	1

When in tristate test mode:

- All output drivers for all digital signal pins are disabled (with the exception of the TDO pin).
- Analog signals such as MDI+/-, analog test points, and regulator controls are unaffected.

4.2.2 Tristate Mode Using JTAG (TAP)

The 82546GB can also be placed in tristate mode using the JTAG interface and the HIGHZ instruction.

The HIGHZ instruction is used to place the 82546GB in high-impedance (TRISTATE) mode, where all digital signal outputs are placed in high-impedance (tri-state) output state.



5.0 Voltage, Temperature, and Timing Specifications

Note: The specification values listed in this section are subject to change without notice. Verify with your local Intel sales office that you have the latest information before finalizing a design.

5.1 Targeted Absolute Maximum Ratings

Table 2. Absolute Maximum Ratings^a

Symbol	Parameter	Min	Max	Unit
VDD (3.3)	DC supply voltage on VDDD or AVDDH with respect to VSS	VSS - 0.5	4.6	V
VDD (2.5)	DC supply voltage on AVDDL with respect to VSS	VSS - 0.5	4.6 or VDD (2.5) + 0.5 ^b	V
VDD (1.5)	DC supply voltage on DVDD with respect to VSS	VSS - 0.5	4.6 or VDD (1.5) + 0.5 ^c	V
VDD	DC supply voltage	VSS - 0.5	4.6	V
VI / VO	LVTTL input voltage	VSS - 0.5	4.6	V
VI / VO	5 V compatible input voltage	VSS - 0.5	6.6	V
Ю	DC output current (by cell type): IOL = 3 mA IOL = 6 mA IOL - 12 mA		10 20 40	mA
TSTG	Storage temperature range	-40	125	С
	ESD per MIL_STD-883 Test Method 3015, Specification 2001V Latchup Over/Undershoot: 150 mA, 125 C		VDD overstress: VDD(3.3)(7.2 V)	V

a. Maximum ratings are referenced to ground (VSS). Permanent device damage is likely to occur if the ratings in this table are exceeded. These values should not be used as the limits for normal device operations.

5.2 Recommended Operating Conditions

Table 3. Recommended Operating Conditions^a

Symbol	Parameter	Min	Max	Unit
VDD (3.3)	DC supply voltage on VDDD or AVDDH ^b	3.0	3.6	V
VDD (2.5)	DC supply voltage on AVDDL ^c	2.38	2.62	V
VDD (1.5)	DC supply voltage on DVDD	1.43	1.57	V
VIO	PCI bus voltage reference	3.0	5.25	V

b. The maximum value is the lesser value of 4.6 V or VDD(2.5) + 0.5 V. This specification applies to biasing the device to a steady state for an indefinite duration.

c. The maximum value is the lesser value of 4.6 V or VDD(2.5) + 0.5 V.



Table 3. Recommended Operating Conditions^a

Symbol	Parameter	Min	Max	Unit
tR / tF	Input rise/fall time (normal input)	0	200	ns
tr/tf	input rise/fall time (Schmitt input)	0	10	ms
TA	Operating temperature range (ambient) ^d	0	55	С
TJ	Junction temperature		≤125	С

a. Sustained operation of the device at conditions exceeding these values, even if they are within the absolute maximum rating limits, might result in permanent damage.

b. It is recommended for VDDO to equal AVDDH (VDDO = AVDDH) during power-up and normal operation.

5.3 DC Specifications

Table 4. DC Characteristics

Symbol	Parameter	Min	Тур	Max	Units
VDD (3.3)	DC supply voltage on VDDO or AVDDH	3.00	3.3	3.60	V
VDD (2.5)	DC supply voltage on AVDDL	2.38	2.5	2.62	V
VDD (1.5)	DC supply voltage on DVDD	1.43	1.5	1.57	V

Table 5.a Power Supply Characteristics

	D0a (both ports)									
	Unplugge	ed/No Link	10 Mbps Operation 10		100 Mbps	100 Mbps Operation		1000 Mbps Operation		
	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)		
3.3 V	65	85	100	110	115	120	240	265		
2.5 V	60	65	80	80	130	135	310	335		
1.5 V	180	190	160	170	200	220	740	840		
Total Device Power	650 mW		800 mW		1.0 W		2.7 W	3.2 W		

c. It is recommended for both VDDO and AVDDH to be of a value greater than AVDDL, with a value greater than DVDD, during power-up (VDDO or AVDDH > AVDDL > DVDD).
d. A higher operating temperature of up to 70 C can be achieved using an appropriate thermal management device.



Table 5.b 82546GB Dual Port Ethernet Controller Only

		D3cold - Wake Up						
	Unplugge	ed/No Link	10 Mbps	Operation	100 Mbps	Operation	Disabled (both ports)	
	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)
3.3 V	65	75	100	110	95	120	65	75
2.5 V	65	70	65	70	125	140	60	65
1.5 V	50	50	60	70	105	130	20	40
Total Device Power	450 mW		600 mW		800 mW		400 mW	

Table 5.c 82546GB Dual Port Ethernet Controller Only

	Uninitialized/Disabled							
		nitialized GOOD = 0)	Disa (via Flash					
	Typ Icc (mA)			Max Icc (mA)				
3.3 V	75	80	50	55				
2.5 V	100	120	50	60				
1.5 V	360	385	20	25				
Total Device Power	1.0 W		325 mW					

Table 5.d Complete Subsystem (Including the 82546GB)

		Complete Subsystem (including 82546GB, Magnetics, LED, and Regulator Circuits)									
		D3cold / Wake disabled D3cold / Wake enabled at 10 Mbps at 100 Mbps					D0 at 10	00 Mbps			
	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)			
3.3 V	65	75	110	120	115	140	250	275			
2.5 V	60	65	85	90	175	190	500	525			
1.5 V	20	40	60	70	105	130	740	840			
Subsystem Total Power	mW	mW	mW	mW	mW	mW	mW	mW			



Table 5.e 82546GB SerDes Design

	82546GB Only						
	_	0a s active)	Wake D	cold visabled es off)			
	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)			
3.3 V	110	135	85	95			
2.5 V	120	125	leakage	leakage			
1.5 V	170	240	15	20			
Total Device Power	900 mW	1.2 W	300 mW	375 mW			

Table 5.f Complete Subsystem (SerDes Design - Includes the 82546GB)

	Complete Subsystem (SerDes design) Including LED and Regulator Circuits (no optics)						
	Wake D	cold Pisabled y power)	D0 SerDe (primary	es Active / power)			
	Typ Icc (mA)	Max Icc (mA)	Typ Icc (mA)	Max Icc (mA)			
3.3 V	85	95	110	135			
2.5	~0	~0	120	125			
1.5 V	15	20	170	240			
Subsystem 3.3 V Current		115 mA		500 mA			

Table 6. I/O Characteristics

Symbol	Parameter	Condition	Min	Тур	Max	Unit
V_{IL}	Voltage input LOW		-0.5		0.8	V
V_{IH}	Voltage input HIGH		2.0		V _{DD} +0.3	V
V _{OL}	Voltage output LOW				0.4	V
V _{OH}	Voltage output HIGH		2.4			V
V _{SH}	Schmitt Trigger Hysteresis		0.1			V
l _{OL} ^a	Output current LOW 3mA drivers (TTL3) 6mA drivers (TTL6) 12mA drivers (TTL12)	V _{OL} V _{OL} V _{OL}	3 6 12			mA mA mA



Table 6. I/O Characteristics

Symbol	Parameter	Condition	Min	Тур	Max	Unit
	Output current HIGH					
ı a	3mA drivers (TTL3)	V _{OH}	-3			mA
l _{OH} ^a	6mA drivers (TTL6)	V _{OH}	-6			mA
	12mA drivers (TTL12)	V _{OH}	-12			mA
	Input Current					
l	TTL inputs	$V_{IN} = V_{DD}$ or V_{SS}	-10	±1	10	μΑ
I _{IN}	Inputs with pull-down resistors	$V_{IN} = V_{DD}$	150		480	μΑ
	TTL inputs with pull-up resistors	$V_{IN} = V_{SS}$	-150		-480	μΑ
I _{OZ}	3-state output leakage current	$V_{OH} = V_{DD}$ or V_{SS}	-10	±1	10	μΑ
C _{IN}	Input capacitance	Any input and bidirectional buffer		2.5		pF
C _{OUT}	Output capacitance	Any output buffer		2.0		pF
C _{PUD}	Pull-up/down Resistor value		7.5		20	kΩ

a. TTL3 signals include: EE_DI, EE_SK, EE_CS, and JTAG_TDO.
TTL6 signals include: FL_CE#, CLK_VIEW, FL_DATA[7:0], FL_ADDR[18:0], FL_OE#, and FL_WE#.
TTL12 signals include: ACT_A#, ACT_B#, LINK_A#, LINK_B#, LEDA100#, LEDB100#, LEDA1000#, and LEDB1000#.

5.4 AC Characteristics

Table 7. AC Characteristics: 3.3 V Interfacing

Symbol	Parameter	Min	Тур	Max	Unit
fPCICLK	Clock frequency in PCI mode			66	MHz
fPCICLK	Clock frequency in PCI-X mode	66		133	MHz

Table 8. 25 MHz Clock Input Requirements

Symbol	Parameter ^a	Min	Тур	Max	Unit
fi_TX_CLK	TX_CLK_IN frequency	25 - 50 ppm	25	25 + 50 ppm	MHz

a. This parameter applies to an oscillator connected to the Crystal One (XTAL1) input. Alternatively, a crystal may be connected to XTAL1 and XTAL2 as the frequency source for the internal oscillator.

Table 9. Link Interface Clock Requirements

Symbol	Parameter	Min	Тур	Max	Unit
fGTX ^a	GTX ^a GTX_CLK frequency		125		MHz

a. $\ensuremath{\mathsf{GTX_CLK}}$ is used externally for test purposes only.



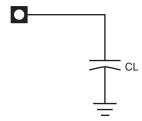
Table 10. EEPROM Interface Clock Requirements

Symbol	Parameter	Min	Тур	Max	Unit
fSK				1	MHz

Table 11. AC Test Loads for General Output Pins

Symbol	Signal Name	Value	Units
CL	TDO	10	pF
CL	APM_WAKEUP, PME#, SDP[7:6], SDP[1:0]	16	pF
CL	EE_DI, EE_SK, FL_ADDR[18:0], FL_CS#, FL_OE#, FL_WE#, FL_DATA[7:0]	18	pF
CL	RX_ACTIVITY, TX_ACTIVITY, LINK_UP	20	pF

Figure 3. AC Test Loads for General Output Pins



Serial Interface Specifications 5.5

Table 12. Driver Characteristics

Symbol	Parameter	Min	Тур	Max	Units
V _{OD}	Differential Output Voltage Swing ^a	875		1325	mV peak- peak
V _{OS}	Output Offset Voltage	1075		1325	mV
Delta V _{OD}	Change in V _{OD} between 0 and 1 ^b			25	mV
R _O	Differential Output Impedance	80		120	Ω
I _{SA} , I _{SB}	Output Current on Short to VSS			40	mA
I _{SAB}	Output Current when A and B are Shorted			12	mA

a. This is the maximum inside dimension of the eye pattern, measured on high and low data patterns with pre-emphasis present. Load = 100 Ω . b. This is defined as an absolute value of amplitude jitter.



Table 13. Receiver Characteristics

Symbol	Parameter	Min	Тур	Max	Units
V _{ID}	Differential Input Voltage Swing	100		2000	mV peak- peak
R _{IN}	Differential Input Impedance	80		120	Ω

Timing Specifications 5.6

5.6.1 **PCI/PCI-X Bus Interface**

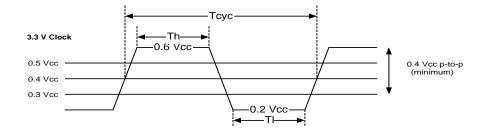
5.6.1.1 **PCI/PCI-X Bus Interface Clock**

Table 14. PCI/PCI-X Bus Interface Clock Parameters

Symbol	Parameter ^a	_	X 133 Hz	PCI-X	66 MHz	PCI 6	6MHz	PCI 3	3 MHz	Units
		Min	Max	Min	Max	Min	Max	Min	Max	
TCYC	CLK cycle time	7.5	20	15	20	15	30	30		ns
TH	CLK high time	3		6		6		11		ns
TL	CLK low time	3		6		6		11		ns
	CLK slew rate	1.5	4	1.5	4	1.5	4	1	4	V/ns
	RST# slew rate ^b	50		50		50		50		mV/ns

a. Rise and fall times are specified in terms of the edge rate measured in V/ns. This slew rate must be met across the minimum peak-to-peak portion of the clock waveform as shown.
 b. The minimum RST# slew rate applies only to the rising (de-assertion) edge of the reset signal and ensures that system noise

Figure 4. PCI/PCI-X Clock Timing



cannot render a monotonic signal to appear bouncing in the switching range.



5.6.1.2 **PCI/PCI-X Bus Interface Timing**

Table 15. PCI/PCI-X Bus Interface Timing Parameters

Symbol	Parameter		(133 Hz	PCI-X	66 MHz	PCI 6	6MHz	PCI 3	3 MHz	Units
		Min	Max	Min	Max	Min	Max	Min	Max	
TVAL	CLK to signal valid delay: bussed signals	0.7	3.8	0.7	3.8	2	6	2	11	ns
TVAL (ptp)	CLK to signal valid delay: point-to-point signals	0.7	3.8	0.7	3.8	2	6	2	12	ns
TON	Float to active delay	0		0		2		2		ns
TOFF	Active to float delay		7		7		14		28	ns
TSU	Input setup time to CLK: bussed signals	1.2		1.7		3		7		ns
TSU (ptp)	Input setup time to CLK: point-to-point signals	1.2		1.7		5		10, 12		ns
TH	Input hold time from CLK	0.5		0.5		0		0		ns
TRRSU	REQ64# to RST# setup time	10* TCYC		10* TCYC		10* TCYC		10* TCYC		ns
TRRH	RST# to REQ64# hold time	0		0		0		0		ns

NOTES:

- Output timing measurements are as shown.
 REQ# and GNT# signals are point-to-point and have different output valid delay and input setup times than bussed signals. GNT# has a setup of 10 ns; REQ# has a setup of 12 ns. All other signals are bussed.
- 3. Input timing measurements are as shown.

Table 13. PCI Bus Interface Timing Measurement Conditions

Symbol	Parameter	PCI-X	PCI 66 MHz 3.3 v	Unit
VTH	Input measurement test voltage (high)	0.6*VCC	0.6*VCC	V
VTL	Input measurement test voltage (low)	0.25*VCC	0.2*VCC	V
VTEST	Output measurement test voltage	0.4*VCC	0.4*VCC	V
	Input signal slew rate	1.5	1.5	V/ns



Figure 5. PCI Bus Interface Output Timing Measurement

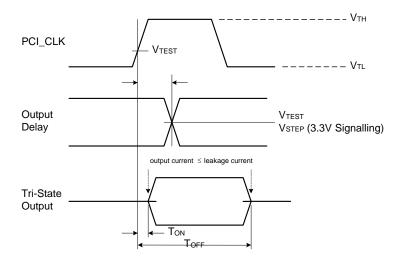


Figure 6. PCI Bus Interface Input Timing Measurement Conditions

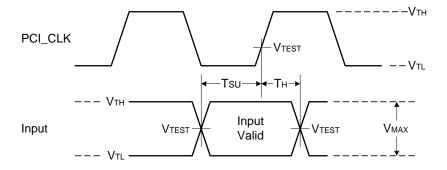


Figure 7. TVAL (max) Rising Edge Test Load

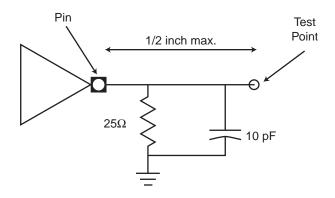
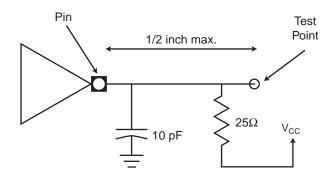




Figure 8. TVAL (max) Falling Edge Test Load



5.6.2 Link Interface Timing

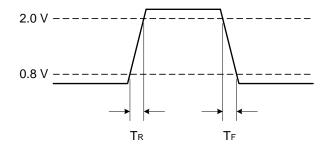
5.6.2.1 Link Interface Rise and Fall Time

Table 16. Rise and Fall Times

Symbol	Parameter	Condition	Min	Max	Unit
TR	Clock rise time	0.8 V to 2.0 V	0.7		ns
TF	Clock fall time	2.0 V to 0.8 V	0.7		ns
TR	Data rise time	0.8 to 2.0 V	0.7		ns
TF	Data fall time	2.0 V to 0.8 V	0.7		ns



Figure 9. Link Interface Rise/Fall Timing



5.6.2.2 Link Interface Transmit Timing

Figure 10. Transmit Interface Timing

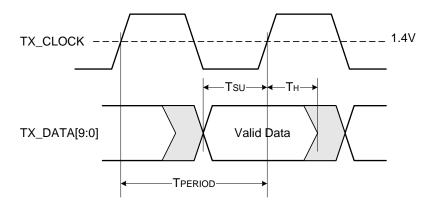


Table 17. Transmit Interface Timing

Symbol	Parameter	Min	Тур	Max	Unit
TPERIOD	GTX_CLK period ^a TBI mode (1000 Mbps)		8		ns
TSETUP	Data setup to rising GTX_CLK		2.5		ns
THOLD	Data hold from rising GRX_CLK		1.0		ns
TDUTY	GTX_CLK duty cycle	40		60	%

a. GTX_CLK should have a 100 ppm tolerance.



5.6.2.3 Link Interface Receive Timing

Figure 11. Receive Interface Timing

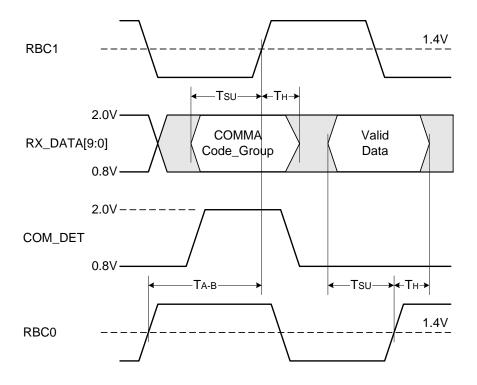


Table 18. Receive Interface Timing

Symbol	Parameter	Min	Тур	Max	Unit
TREQ	RBC0/RBC1 frequency TBI mode (1000 Mbps)		62.5		MHz
TSETUP	Data setup before rising RBC0/RBC1		2.5		ns
THOLD	Data hold after rising RBC0/RBC1		1		ns
TDUTY	RBC0/RBC1 duty cycle	40		60	%
ТА-В	RBC0/RBC1 skew	7.5		8.5	ns



5.6.3 Flash Interface

Figure 12. Flash Read Timing

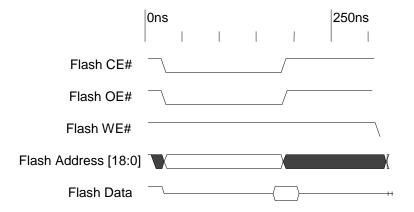


Table 19. Flash Read Operation Timing

Symbol	Parameter	Min	Тур	Max	Unit
TCE	Flash CE# or OE# to read data delay			160	ns
TACC	Flash address setup time			160	ns
THOLD	Data hold time	0			ns

Figure 13. Flash Write Timing

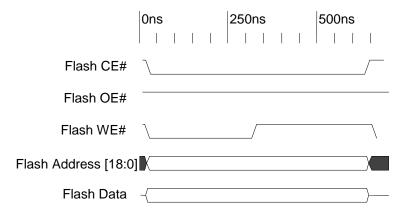




Table 20. Flash Write Operation Timing

Symbol	Parameter	Min	Тур	Max	Unit
TWE	Flash write pulse width (WE#)		160		ns
TAH	Flash address hold time	0			ns
TDS	Flash data setup time	160			ns

5.6.4 EEPROM Interface

Table 21. Link Interface Clock Requirements

Symbol	Parameter	Min	Тур	Max	Unit
TPW	EE_SK pulse width		TPERIOD*128		ns

Table 22. Link Interface Clock Requirements

Symbol	Parameter ^a	Min	Тур	Max	Unit
TDOS	EE_DO setup time	TCYC*2			ns
TDOH	EE_DO hold time	0			ns

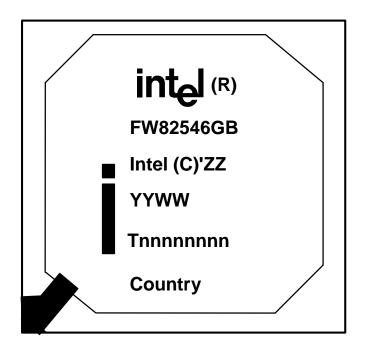
a. The EE_DO setup and hold time is a function of the CLK cycle time but is referenced to O_EE_SK .



6.0 Package and Pinout Information

6.1 Device Identification

Figure 14. 82546GB Device Identification Markings



82546GB Product Name
FW82546GB Intel Product Number

(c)'ZZ Copyright Information
YYWW Date Code

Tnnnnnnn Lot Trace Code

Country Country of Origin Assembly

NOTE: The black mark in the lower left corner indicates the location of pin 1.



6.2 Package Information

The 82546GB device is a 364-lead ball grid array (BGA) measuring 21 mm². The package dimensions are detailed in the figures below. The nominal ball pitch is 1 mm.

Figure 15. 82546GB 364-Lead BGA Ball Pad Dimensions

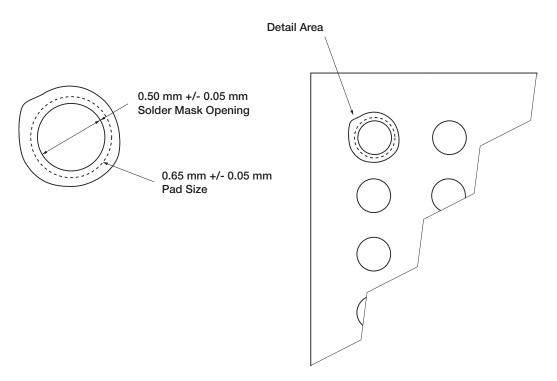




Figure 16. 82546GB Mechanical Specifications

Symbol dimension in mm dimension in inch	MIN NOM MAX	A 2.03 2.23 2.43 0.080 0.088 0.096	A1 0.40 0.50 0.60 0.016 0.020 0.024	A2 1.12 1.17 1.22 0.044 0.046 0.048	b 0.50 0.60 0.70 0.020 0.024 0.028	C 0.51 0.56 0.61 0.020 0.022 0.024	D 20.80 21.00 21.20 0.819 0.827 0.835	D1 19.00 BSC 0.748 BSC	D2 18.80 19.00 19.20 0.740 0.748 0.756	D3 — 15.00 — 0.591 —	E 20.80 21.00 21.20 0.819 0.827 0.835	E1 19.00 BSC 0.748 BSC	18.80	E3 — 15.00 — 0.591 —	e 1.0 BASIC 0.039 BASIC	aaa 0.20 0.008	bbb 0.25 0.010	ddd 0.15 0.006	eee 0.25 0.010	fff 0.10 0.004	⊝ 30° TYP 30° TYP	TROLLING DIMENSION: MILLIME MARY DATUM CAND SEATING PL THE SPHERICAL CROWNS OF TI- ENSION D IS MEASURED AT THE IALL DIAMETER, PARALLEL TO PRIN RE SHALL BE A MINIMUM CLEAR? TWEEN THE EDGE OF THE SOLDS IDY EDGE.
		eee	(S)				_	√ √		_			DETAIL B									
		• •							000	D3			C		000							Part Pa



6.3 Thermal Specifications

The 82546GB Gigabit Ethernet controller is specified for operation when the ambient temperature (TA) is within the range of 0° C to 55° C. The maximum permitted junction temperature is 125° C.

TC (case temperature) is calculated using the equation:

$$TC = TA + P(\theta_{JA} - \theta_{JC})$$

TJ (junction temperature) is calculated using the equation:

$$TJ = TA + P \theta_{JA}$$

The power consumption (P) is calculated by using the typical ICC and nominal VCC. The thermal resistances are shown in Table 23.

Table 23. Thermal Characteristics

Symbol	Parameter	Val	Value at specified airflow (m/s)							
Symbol	r didiffetei	0	1	2	3	Units				
θ_{JA}	Thermal resistance, junction-to- ambient	17.7	15.6	14.8	14.0	C/Watt				
θ _{JC}	Thermal resistance, junction-to-case	6.8	6.8	6.8	6.8	C/Watt				

Thermal resistances are determined empirically with test devices mounted on standard thermal test boards. Real system designs may have different characteristics due to board thickness, arrangement of ground planes, and proximity of other components. The case temperature measurements should be used to assure that the 82546GB Gigabit Ethernet controller is operating under recommended conditions.

The use of a heat sink device can enhance the overall θ_{JA} of the solution in situations where tolerance of higher overall ambient air temperatures is desired. Intel does not qualify or recommend any specific heat sink device for use with the 82546GB Gigabit Ethernet controller but can provide a thermal report modeling a generic heat sink device and the θ_{JA} that might be achieved with the use of a heat sink device. Refer to the 82546EB/GB Gigabit Ethernet Controller Thermal Properties with External Heat Sink Application Note for more information.



6.4 Ball Mapping Diagram

Note: The 82546GB device uses five categories of VDD connections: VDDO (3.3 V), AVDDH (Analog 3.3 V), AVDDL (Analog 2.5 V), and DVDD (1.5 V).

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
A	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
В	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
С	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
D	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
E	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
F	0	0	0	0	0											0	0	0	0	0
G	0	0	0	0	0		0	0	0	0	0	0	0	0		0	0	0	0	0
н	0	0	0	0	0		0	0	0	Ο	0	0	0	0		0	0	0	0	0
J	0	0	0	0	0		0	0	0	Ο	0	0	0	0		0	0	0	0	0
ĸ	0	0	0	0	0		0_	0	0	0	0	0	0	0		0	0	0	0	0
L	0	0	0	0	0		0	0	0	0	0	0	0	0		0	0	0	0	0
М	0	0	0	0	0		0	0	0	Ο	0	0	0	0		0	0	0	0	0
N	0	0	0	0	0		0	Ο	0	Ο	0	0	0	0		0	0	0	0	0
P	0	0	0	0	0		0	0	0	0	0	0	0	0		0	0	0	0	0
R	0	0	0	0	0											0	0	0	0	0
т	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
υ	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
v	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
W	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Y	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0



6.5 Pinout Information

Table 24. PCI Address, Data, and Control Signals

Signal	Pin	Signal	Pin	Signal	Pin
PCI_AD[0]	T14	PCI_AD[28]	Y3	PCI_AD[56]	T17
PCI_AD[1]	V14	PCI_AD[29]	U4	PCI_AD[57]	U18
PCI_AD[2]	Y15	PCI_AD[30]	V3	PCI_AD[58]	V18
PCI_AD[3]	W14	PCI_AD[31]	V1	PCI_AD[59]	U16
PCI_AD[4]	T13	PCI_AD[32]	L16	PCI_AD[60]	V17
PCI_AD[5]	V13	PCI_AD[33]	M20	PCI_AD[61]	W18
PCI_AD[6]	Y14	PCI_AD[34]	M19	PCI_AD[62]	Y19
PCI_AD[7]	U12	PCI_AD[35]	M16	PCI_AD[63]	T16
PCI_AD[8]	V12	PCI_AD[36]	M18	CBE[0]#	Y13
PCI_AD[9]	T12	PCI_AD[37]	M17	CBE[1]#	V10
PCI_AD[10]	W12	PCI_AD[38]	N20	CBE[2]#	T8
PCI_AD[11]	Y12	PCI_AD[39]	N16	CBE[3]#	Y4
PCI_AD[12]	V11	PCI_AD[40]	P20	CBE[4]#	V16
PCI_AD[13]	T11	PCI_AD[41]	N18	CBE[5]#	Y18
PCI_AD[14]	Y11	PCI_AD[42]	P19	CBE[6]#	Y17
PCI_AD[15]	W10	PCI_AD[43]	P16	CBE[7]#	T15
PCI_AD[16]	U8	PCI_AD[44]	R20	PAR	U10
PCI_AD[17]	Y7	PCI_AD[45]	P18	PAR64	V15
PCI_AD[18]	Y6	PCI_AD[46]	P17	FRAME#	V8
PCI_AD[19]	V7	PCI_AD[47]	T20	IRDY#	W8
PCI_AD[20]	T7	PCI_AD[48]	R16	TRDY#	Y8
PCI_AD[21]	W6	PCI_AD[49]	U20	STOP#	V9
PCI_AD[22]	Y5	PCI_AD[50]	R18	IDSEL	T6
PCI_AD[23]	V6	PCI_AD[51]	T19	DEVSEL#	Т9
PCI_AD[24]	U6	PCI_AD[52]	V20	VIO	Y1
PCI_AD[25]	V5	PCI_AD[53]	T18	VIO	Y20
PCI_AD[26]	W4	PCI_AD[54]	W20		
PCI_AD[27]	V4	PCI_AD[55]	V19		

Table 25. PCI Arbitration Signals

Signal	Pin	Signal	Pin	Signal	Pin
REQ64#	U14	REQ#	W2	LOCK#	Y9
ACK64#	W16	GNT#	T3		



Table 26. Interrupt Signals

Signal	Pin	Signal	Pin
INTA#	Y2	INTB#	T1

Table 27. System Signals

Signal	Pin	Signal	Pin
PCICLK	U2	PCIRST#	T5
M66EN	Y16	LAN_PWR_GOOD	A17

Table 28. Error Reporting Signals

Signal	Pin	Signal	Pin
SERR#	T10	PERR#	Y10

Table 29. Power Management Signals

Signal	Pin	Signal	Pin
PME#	T4	AUX_PWR	R3

Table 30. Impedance Compensation Signals

Signal	Pin	Signal	Pin
ZN_COMP	T2	ZP_COMP	R5

Table 31. SMB Signals

Signal	Pin	Signal	Pin	Signal	Pin
SMBCLK	A14	SMBDATA	A15	SMBALRT#	A16

Table 32. EEPROM Interface Signals

Signal	Pin	Signal	Pin
EE_DI	C19	EE_CS	C20
EE_DO	B20	EE_SK	D20



Table 33. Flash Interface Signals

Signal	Pin	Signal	Pin	Signal	Pin
FL_ADDR[0]	F16	FL_ADDR[10]	G17	FL_OE#	K18
FL_ADDR[1]	E18	FL_ADDR[11]	G16	FL_WE#	C17
FL_ADDR[2]	E16	FL_ADDR[12]	B15	FL_DATA[0] / LAN_A_DISABLE	H16
FL_ADDR[3]	E15	FL_ADDR[13]	D19	FL_DATA[1] / LAN_B_DISABLE	G18
FL_ADDR[4]	E14	FL_ADDR[14]	D18	FL_DATA[2]	J16
FL_ADDR[5]	E13	FL_ADDR[15]	C15	FL_DATA[3]	H18
FL_ADDR[6]	D15	FL_ADDR[16]	D16	FL_DATA[4]	J17
FL_ADDR[7]	B16	FL_ADDR[17]	C18	FL_DATA[5]	J18
FL_ADDR[8]	F17	FL_ADDR[18]	D17	FL_DATA[6]	K17
FL_ADDR[9]	F18	FL_CS#	H20	FL_DATA[7]	K16

Table 34. LED Signals

Signal	Pin	Signal	Pin	Signal	Pin
ACT_A#	N1	LINKA1000#	N3	LINKB100#	C14
LINK_A#	M1	ACT_B#	B13	LINKB1000#	C13
LINKA100#	N4	LINK_B#	A13		

Table 35. Software Definable Signals

Signal	Pin	Signal	Pin
SDPA[0]	G4	SDPB[0]	D13
SDPA[1]	G5	SDPB[1]	B12
SDPA[6]	E12	SDPB[6]	C12
SDPA[7]	E11	SDPB[7]	D12

Table 36. Crystal Signals

Signal	Pin	Signal	Pin
XTAL1	А3	XTAL2	A4

Table 37. PHY Signals

Signal	Pin	Signal	Pin	Signal	Pin
REF_A	E3	MDIA2-	D1	MDIB1-	L1
REF_B	L4	MDIA2+	D2	MDIB1+	K1
MDIA0-	B1	MDIA3-	E1	MDIB2-	J2



Table 37. PHY Signals

Signal	Pin	Signal	Pin	Signal	Pin
MDIA0+	B2	MDIA3+	E2	MDIB2+	J1
MDIA1-	C1	MDIB0-	L3	MDIB3-	НЗ
MDIA1+	C2	MDIB0+	K3	MDIB3+	J3

Table 38. Serializer / Deserializer Signals

Signal	Pin	Signal	Pin	Signal	Pin
RXA+	G19	TXA+	F19	SIG_DETECT_A	E20
RXA-	G20	TXA-	F20	SIG_DETECT_B	L20
RXB+	J19	TXB+	K19		
RXB-	J20	TXB-	K20		

Table 39. JTAG Test Interface Signals

Signal	Pin	Signal	Pin	Signal	Pin
JTAG_TCK	P1	JTAG_TMS	P5	CLK_VIEW	P3
JTAG_TDI	P4	JTAG_RST#	N5	TEST#	A8
JTAG_TDO	P2				

Table 40. Power Support Signals

Signal	Pin	Signal	Pin	Signal	Pin
CTRL_15	A18	CTRL_25A	F2	CTRL_B	H5



Table 41. Digital Power Signals

Signal	Pin	Signal	Pin	Signal	Pin
VDDO (3.3V)	В8	VDDO (3.3V)	U7	DVDD (1.5V)	H13
VDDO (3.3V)	B14	VDDO (3.3V) - PLL	U11	DVDD (1.5V)	H14
VDDO (3.3V)	B19	VDDO (3.3V)	U15	DVDD (1.5V)	J7
VDDO (3.3V)	C10	VDDO (3.3V)	U19	DVDD (1.5V)	J14
VDDO (3.3V)	C16	VDDO (3.3V)	W1	DVDD (1.5V)	M7
VDDO (3.3V)	D6	VDDO (3.3V)	W5	DVDD (1.5V)	M14
VDDO (3.3V)	D11	VDDO (3.3V)	W9	DVDD (1.5V)	N7
VDDO (3.3V)	E17	VDDO (3.3V)	W13	DVDD (1.5V)	N8
VDDO (3.3V) - PHY B	H4	VDDO (3.3V)	W17	DVDD (1.5V)	N13
VDDO (3.3V)	H19	DVDD (1.5V)	G7	DVDD (1.5V)	N14
VDDO (3.3V)	L17	DVDD (1.5V)	G8	DVDD (1.5V)	P7
VDDO (3.3V)	M2	DVDD (1.5V)	G9	DVDD (1.5V)	P8
VDDO (3.3V)	N19	DVDD (1.5V)	G12	DVDD (1.5V)	P9
VDDO (3.3V)	R4	DVDD (1.5V)	G13	DVDD (1.5V)	P12
VDDO (3.3V)	R17	DVDD (1.5V)	G14	DVDD (1.5V)	P13
VDDO (3.3V)	U1	DVDD (1.5V)	H7	DVDD (1.5V)	P14
VDDO (3.3V)	U3	DVDD (1.5V)	H8		

Table 42. Analog Power Signals

Signal	Pin	Signal	Pin	Signal	Pin
AVDDH (3.3 V)	B4	AVDDLA (2.5 V)	G1	AVDDLB (2.5 V)	L2
AVDDH (3.3 V) - PHY A	F1	AVDDLA (2.5 V)	G2	AVDDLB (2.5 V)	L5
AVDDLA (2.5 V)	A19	AVDDLA (2.5 V)	G3	AVDDLB (2.5 V)	L18



Table 43. Grounds and No Connect Signals

Signal	Pin	Signal	Pin	Signal	Pin
GND	A1	GND	K2	GND	N10
GND	A2	GND	K4	GND	N11
GND	A5	GND	K5	GND	N12
GND	A10	GND	K7	GND	N17
GND	В3	GND	K8	GND	P10
GND	В6	GND	K9	GND	P11
GND	B11	GND	K10	GND	R2
GND	B17	GND	K11	GND	R19
GND	С3	GND	K12	GND	U5
GND	D3	GND	K13	GND	U9
GND	D8	GND	K14	GND	U13
GND	D14	GND	L7	GND	U17
GND	E19	GND	L8	GND	V2
GND	F3	GND	L9	GND	W3
GND	G10	GND	L10	GND	W7
GND	G11	GND	L11	GND	W11
GND	H2	GND	L12	GND	W15
GND	H9	GND	L13	GND	W19
GND	H10	GND	L14	NC	A11
GND	H11	GND	L19	NC	A12
GND	H12	GND	M4	NC	F4
GND	H17	GND	M8	NC	F5
GND	J8	GND	M9	NC	H1
GND	J9	GND	M10	NC	J4
GND	J10	GND	M11	NC	J5
GND	J11	GND	M12	NC	МЗ
GND	J12	GND	M13	NC	N2
GND	J13	GND	N9		



Table 44. Reserved Signals

Signal	Pin	Signal	Pin	Signal	Pin
Reserved[0]	D4	Reserved[10]	E10	Reserved[20]	A9
Reserved[1]	D5	Reserved[11]	B7	Reserved[21]	C11
Reserved[2]	C4	Reserved[12]	A7	Reserved[22]	B10
Reserved[3]	E4	Reserved[13]	C8	Reserved[23]	C6
Reserved[4]	C5	Reserved[14]	E8	Reserved[24]	A20
Reserved[5]	E5	Reserved[15]	E9	Reserved[25]	B18
Reserved[6]	B5	Reserved[16]	D9	Reserved[26]	M5
Reserved[7]	E6	Reserved[17]	C9	Reserved[27]	E7
Reserved[8]	D7	Reserved[18]	B9	Reserved[28]	A6
Reserved[9]	C7	Reserved[19]	D10	Reserved[29]	R1



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