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#### **REVISION HISTORY**

10/08—Revision 0: Initial Version

### **SPECIFICATIONS**

#### **DC SPECIFICATIONS**

AVDD = 1.8 V, DRVDD = 1.8 V,  $T_{MIN} = -40^{\circ}C$ ,  $T_{MAX} = +85^{\circ}C$ ,  $f_{IN} = -1.0 dBFS$ , full scale = 1.25 V, DCS enabled, unless otherwise noted.

Parameter <sup>1</sup>	Temp	Min	Тур	Max	Unit
RESOLUTION			11		Bits
ACCURACY					
No Missing Codes	Full		Guarante	ed	
Offset Error	25°C		4.2		mV
	Full	-12		+12	mV
Gain Error	25°C		0.89		% FS
	Full	-2.2		+4.3	% FS
Differential Nonlinearity (DNL)	25°C		±0.15		LSB
	Full	-0.4		+0.4	LSB
Integral Nonlinearity (INL)	25°C		±0.5		LSB
	Full	-0.5		+0.5	LSB
TEMPERATURE DRIFT					
Offset Error	Full		±9		μV/°C
Gain Error	Full		0.019		%/°C
ANALOG INPUTS (VIN+, VIN–)					
Differential Input Voltage Range <sup>2</sup>	Full	0.98	1.25	1.5	V p-p
Input Common-Mode Voltage	Full		1.4		V
Input Resistance (Differential)	Full		4.3		kΩ
Input Capacitance	25°C		2		pF
POWER SUPPLY					
AVDD	Full	1.7	1.8	1.9	v
DRVDD	Full	1.7	1.8	1.9	V
Supply Currents					
I <sub>AVDD</sub> <sup>3</sup>	Full		152	164	mA
I <sub>DRVDD</sub> <sup>3</sup> /SDR Mode <sup>4</sup>	Full		55	58	mA
I <sub>DRVDD</sub> <sup>3</sup> /DDR Mode <sup>5</sup>	Full		36		mA
Power Dissipation <sup>3</sup>	Full				
SDR Mode <sup>4</sup>	Full		373	400	mW
DDR Mode⁵	Full		338		mW

<sup>1</sup> See the AN-835 Application Note, Understanding High Speed ADC Testing and Evaluation, for a complete set of definitions and an explanation of how these tests were completed.

<sup>2</sup> The input range is programmable through the SPI, and the range specified reflects the nominal values of each setting. See the Memory Map section. <sup>3</sup> I<sub>AVDD</sub> and I<sub>DRVDD</sub> are measured with a -1 dBFS, 10.3 MHz sine input at rated sample rate.

<sup>4</sup> Single data rate mode; this is the default mode of the AD9230-11.

<sup>5</sup> Double data rate mode; user-programmable feature. See the Memory Map section.

#### AC SPECIFICATIONS

AVDD = 1.8 V, DRVDD = 1.8 V,  $T_{MIN} = -40^{\circ}C$ ,  $T_{MAX} = +85^{\circ}C$ ,  $f_{IN} = -1.0 dBFS$ , full scale = 1.25 V, DCS enabled, unless otherwise noted.<sup>1</sup>

Table 2.	T	T			
Parameter <sup>2</sup>	Temp	Min	Тур	Max	Unit
SNR					
$f_{IN} = 10 \text{ MHz}$	25°C	62.4	62.9		dB
	Full	62.2			dB
$f_{IN} = 70 \text{ MHz}$	25°C	62.2	62.5		dB
	Full	62.0			dB
$f_{IN} = 170 \text{ MHz}$	25°C		61.8		dB
SINAD					
$f_{IN} = 10 \text{ MHz}$	25°C	62.3	62.8		dB
	Full	62.1			dB
$f_{IN} = 70 \text{ MHz}$	25°C	62.0	62.3		dB
	Full	61.8			dB
$f_{IN} = 170 \text{ MHz}$	25°C		61.5		dB
EFFECTIVE NUMBER OF BITS (ENOB)					
$f_{IN} = 10 \text{ MHz}$	25°C		10.3		Bits
$f_{IN} = 70 \text{ MHz}$	25°C		10.2		Bits
$f_{IN} = 170 \text{ MHz}$	25°C		10.1		Bits
WORST HARMONIC (SECOND OR THIRD)					
$f_{IN} = 10 \text{ MHz}$	25°C		-86	-77	dBc
	Full			-77	dBc
$f_{IN} = 70 \text{ MHz}$	25°C		-79	-77	dBc
	Full			-76	dBc
$f_{IN} = 170 \text{ MHz}$	25°C		-76		dBc
WORST OTHER (SFDR EXCLUDING SECOND AND THIRD)	1				
$f_{IN} = 10 \text{ MHz}$	25°C		-88	-84	dBc
	Full			-79	dBc
$f_{IN} = 70 \text{ MHz}$	25°C		-84	-82	dBc
	Full			-81	dBc
$f_{IN} = 170 \text{ MHz}$	25°C		-82		dBc
ANALOG INPUT BANDWIDTH	25°C		700		MHz

<sup>1</sup> All ac specifications tested by driving CLK+ and CLK– differentially.

<sup>2</sup> See the AN-835 Application Note, Understanding High Speed ADC Testing and Evaluation, for a complete set of definitions and an explanation of how these tests were completed.

#### **DIGITAL SPECIFICATIONS**

AVDD = 1.8 V, DRVDD = 1.8 V,  $T_{MIN} = -40^{\circ}C$ ,  $T_{MAX} = +85^{\circ}C$ ,  $f_{IN} = -1.0 dBFS$ , full scale = 1.25 V, DCS enabled, unless otherwise noted.

Parameter <sup>1</sup>	Temp	Min	Тур	Max	Unit
CLOCK INPUTS					
Logic Compliance	Full		CMOS/LVDS/	LVPECL	
Internal Common-Mode Bias	Full		1.2		V
Differential Input Voltage	Full	0.2		6	V p-р
Input Voltage Range	Full	AGND - 0.3		AVDD + 1.6	V
Input Common-Mode Range	Full	1.1		AVDD	V
High Level Input Voltage (V⊩)	Full	1.2		3.6	V
Low Level Input Voltage (V <sub>IL</sub> )	Full	0		0.8	V
High Level Input Current (I⊮)	Full	-10		+10	μA
Low Level Input Current (IIL)	Full	-10		+10	μA
Input Resistance (Differential)	Full	16	20	24	kΩ
Input Capacitance	Full		4		pF
LOGIC INPUTS					
Logic 1 Voltage	Full	$0.8 \times AVDD$			V
Logic 0 Voltage	Full			$0.2 \times AVDD$	V
Logic 1 Input Current (SDIO)	Full		0		μA
Logic 0 Input Current (SDIO)	Full		-60		μA
Logic 1 Input Current (SCLK, PWDN, CSB, RESET)	Full		55		μA
Logic 0 Input Current (SCLK, PWDN, CSB, RESET)	Full		0		μA
Input Capacitance	25°C		4		pF
LOGIC OUTPUTS <sup>2</sup>					
Vod Differential Output Voltage	Full	247		454	mV
Vos Output Offset Voltage	Full	1.125		1.375	V
Output Coding		Twos complen	nent, gray code,	or offset binary (defa	ult)

<sup>1</sup> See the AN-835 Application Note, Understanding High Speed ADC Testing and Evaluation, for a complete set of definitions and an explanation of how these tests were completed. <sup>2</sup> LVDS R<sub>TERMINATION</sub> = 100  $\Omega$ .

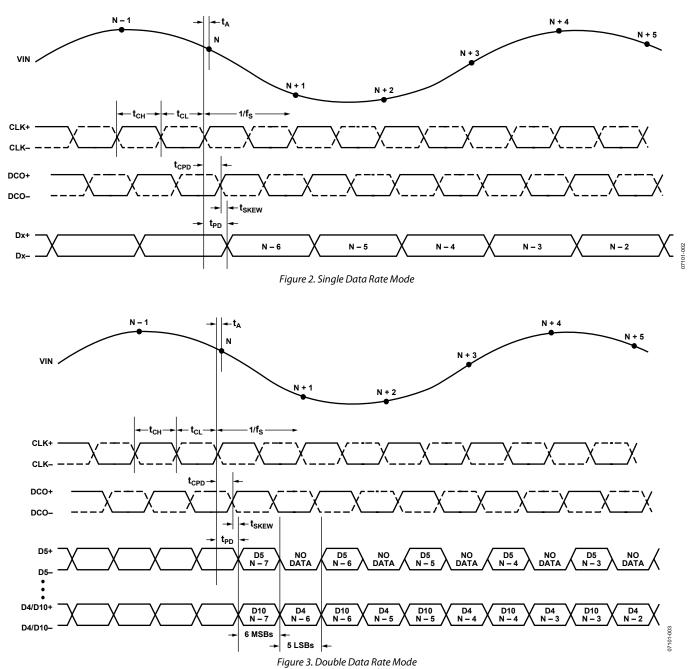
#### SWITCHING SPECIFICATIONS

AVDD = 1.8 V, DRVDD = 1.8 V,  $T_{MIN} = -40^{\circ}C$ ,  $T_{MAX} = +85^{\circ}C$ ,  $f_{IN} = -1.0 dBFS$ , full scale = 1.25 V, DCS enabled, unless otherwise noted.

Parameter	Temp	Min	Тур	Max	Unit
CONVERSION RATE					
Maximum Conversion Rate	Full	200			MSPS
Minimum Conversion Rate	Full			40	MSPS
PULSE WIDTH					
CLK+ Pulse Width High (t <sub>CH</sub> )	Full	2.25	2.5		ns
CLK+ Pulse Width Low (t <sub>CL</sub> )	Full	2.25	2.5		ns
OUTPUT (LVDS, SDR MODE) <sup>1</sup>					
Data Propagation Delay (tpd)	Full		3.8		ns
Rise Time (t <sub>R</sub> ) (20% to 80%)	25°C		0.2		ns
Fall Time ( $t_F$ ) (20% to 80%)	25°C		0.2		ns
DCO Propagation Delay (t <sub>CPD</sub> )	Full		3.9		ns
Data to DCO Skew (tskew)	Full	-0.3	0.1	0.5	ns
Latency	Full		6		Cycles
OUTPUT (LVDS, DDR MODE) <sup>2</sup>					
Data Propagation Delay (tpd)	Full		3.8		ns
Rise Time (t <sub>R</sub> ) (20% to 80%)	25°C		0.2		ns
Fall Time ( $t_F$ ) (20% to 80%)	25°C		0.2		ns
DCO Propagation Delay (t <sub>CPD</sub> )	Full		3.9		ns
Data to DCO Skew (tskew)	Full	-0.5	0.1	0.3	ns
Latency	Full		6		Cycles
APERTURE UNCERTAINTY (JITTER, t,)	25°C		0.2		ps rms

<sup>1</sup> See Figure 2. <sup>2</sup> See Figure 3.

#### **TIMING DIAGRAMS**



### **ABSOLUTE MAXIMUM RATINGS**

#### Table 5.

Parameter	Rating
Electrical	
AVDD to AGND	–0.3 V to +2.0 V
DRVDD to DRGND	–0.3 V to +2.0 V
AGND to DRGND	–0.3 V to +0.3 V
AVDD to DRVDD	-2.0 V to +2.0 V
D0+/D0– through D10+/D10– to DRGND	-0.3 V to DRVDD + 0.3 V
DCO+/DCO- to DRGND	-0.3 V to DRVDD + 0.3 V
OR+/OR- to DGND	-0.3 V to DRVDD + 0.3 V
CLK+ to AGND	–0.3 V to +3.9 V
CLK– to AGND	–0.3 V to +3.9 V
VIN+ to AGND	-0.3 V to AVDD + 0.2 V
VIN- to AGND	-0.3 V to AVDD + 0.2 V
SDIO/DCS to DGND	-0.3 V to DRVDD + 0.3 V
PWDN to AGND	–0.3 V to +3.9 V
CSB to AGND	–0.3 V to +3.9 V
SCLK/DFS to AGND	–0.3 V to +3.9 V
Environmental	
Storage Temperature Range	–65°C to +125°C
Operating Temperature Range	–40°C to +85°C
Lead Temperature (Soldering, 10 sec)	300°C
Junction Temperature	150°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### THERMAL RESISTANCE

The exposed paddle must be soldered to the ground plane for the LFCSP package. Soldering the exposed paddle to the customer board increases the reliability of the solder joints, maximizing the thermal capability of the package.

#### Table 6.

Package Type	θ」Α	οıc	Unit
56-Lead LFCSP (CP-56-2)	30.4	2.9	°C/W

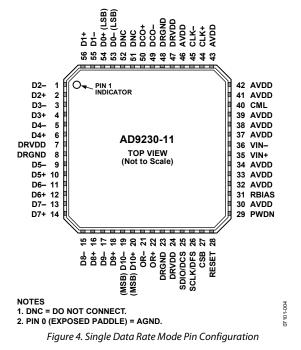
Typical  $\theta_{JA}$  and  $\theta_{JC}$  are specified for a 4-layer board in still air. Airflow increases heat dissipation, effectively reducing  $\theta_{JA}$ . In addition, metal that is in direct contact with the package leads reduces the  $\theta_{JA}$ .

#### **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

### PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS



#### Table 7. Single Data Rate Mode Pin Function Descriptions

Pin No.	Mnemonic	Description
30, 32 to 34, 37 to 39, 41 to	AVDD	1.8 V Analog Supply.
43, 46		
7, 24, 47	DRVDD	1.8 V Digital Output Supply.
0	AGND <sup>1</sup>	Analog Ground. The exposed paddle should be connected to the analog ground.
8, 23, 48	DRGND <sup>1</sup>	Digital Output Ground.
35	VIN+	Analog Input (True).
36	VIN-	Analog Input (Complement).
40	CML	Common-Mode Output Pin. Enabled through the SPI, this pin provides a reference for the optimized internal bias voltage for VIN+/VIN–.
44	CLK+	Clock Input (True).
45	CLK–	Clock Input (Complement).
31	RBIAS	Set Pin for Chip Bias Current. Place 1% 10 k $\Omega$ resistor terminated to ground. Nominally 0.5 V.
28	RESET	CMOS-Compatible Chip Reset (Active Low).
25	SDIO/DCS	Serial Port Interface (SPI) Data Input/Output (Serial Port Mode). Duty Cycle Stabilizer Select (External Pin Mode).
26	SCLK/DFS	Serial Port Interface Clock (Serial Port Mode). Data Format Select Pin (External Pin Mode).
27	CSB	Serial Port Chip Select (Active Low).
29	PWDN	Chip Power-Down.
49	DCO-	Data Clock Output (Complement).
50	DCO+	Data Clock Output Input (True).
51, 52	DNC	Do No Connect.
53	D0– (LSB)	D0 Complement Output Bit (LSB).
54	D0+ (LSB)	D0 True Output Bit (LSB).
55	D1–	D1 Complement Output Bit.
56	D1+	D1 True Output Bit.
1	D2-	D2 Complement Output Bit.
2	D2+	D2 True Output Bit.

Pin No.	Mnemonic	Description
3	D3-	D3 Complement Output Bit.
4	D3+	D3 True Output Bit.
5	D4-	D4 Complement Output Bit.
6	D4+	D4 True Output Bit.
9	D5-	D5 Complement Output Bit.
10	D5+	D5 True Output Bit.
11	D6-	D6 Complement Output Bit.
12	D6+	D6 True Output Bit.
13	D7–	D7 Complement Output Bit.
14	D7+	D77 True Output Bit.
15	D8-	D8 Complement Output Bit.
16	D8+	D8 True Output Bit.
17	D9-	D9 Complement Output Bit.
18	D9+	D9 True Output Bit.
19	D10– (MSB)	D10 Complement Output Bit (MSB).
20	D10+ (MSB)	D10 True Output Bit (MSB).
21	OR-	Overrange Complement Output Bit.
22	OR+	Overrange True Output Bit.

<sup>1</sup> AGND and DRGND should be tied to a common quiet ground plane.

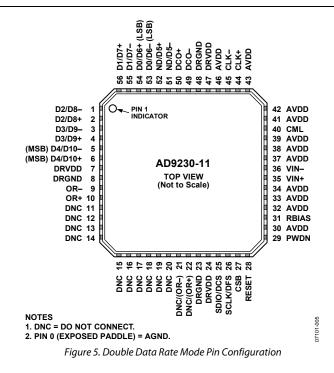


Table 8. Double Data Rate	Mode Pin	Function	Descriptions
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Pin No.	Mnemonic	Description
30, 32 to 34, 37 to 39,	AVDD	1.8 V Analog Supply.
41 to 43, 46		
7, 24, 47	DRVDD	1.8 V Digital Output Supply.
0	AGND <sup>1</sup>	Analog Ground. The exposed paddle should be connected to the analog ground.
8, 23, 48	DRGND <sup>1</sup>	Digital Output Ground.
35	VIN+	Analog Input Input (True).
36	VIN-	Analog Input (Complement).
40	CML	Common-Mode Output Pin. Enabled through the SPI, this pin provides a reference for the optimized internal bias voltage for VIN+/VIN–.
44	CLK+	Clock Input Input (True).
45	CLK–	Clock Input (Complement).
31	RBIAS	Set Pin for Chip Bias Current. Place 1% 10 k $\Omega$ resistor terminated to ground. Nominally 0.5 V.
28	RESET	CMOS-Compatible Chip Reset (Active Low).
25	SDIO/DCS	Serial Port Interface (SPI) Data Input/Output (Serial Port Mode).
		Duty Cycle Stabilizer Select (External Pin Mode).
26	SCLK/DFS	Serial Port Interface Clock (Serial Port Mode).
		Data Format Select Pin (External Pin Mode).
27	CSB	Serial Port Chip Select (Active Low).
29	PWDN	Chip Power-Down.
49	DCO-	Data Clock Output (Complement).
50	DCO+	Data Clock Output Input (True).
51	ND/D5-	ND/D5 Complement Output Bit.
52	ND/D5+	ND/D5 True Output Bit.
53	D0/D6- (LSB)	D0/D6 Complement Output Bit (LSB).
54	D0/D6+ (LSB)	D0/D6 True Output Bit (LSB).
55	D1/D7-	D1/D7 Complement Output Bit.
56	D1/D7+	D1/D7 True Output Bit.
1	D2/D8-	D2/D8 Complement Output Bit.
2	D2/D8+	D2/D8 True Output Bit.

Pin No.	Mnemonic	Description
3	D3/D9-	D3/D9 Complement Output Bit.
4	D3/D9+	D3/D9 True Output Bit.
5	D4/D10- (MSB)	D4/D10 Complement Output Bit (MSB).
6	D4/D10+ (MSB)	D4/D10 True Output Bit (MSB).
9	OR-	OR Complement Output Bit. This pin is disabled if Pin 21 is reconfigured through the SPI to be OR
10	OR+	OR True Output Bit. This pin is disabled if Pin 22 is reconfigured through the SPI to be OR+.
11 to 20	DNC	Do Not Connect.
21	DNC/(OR-)	Do Not Connect. This pin can be reconfigured as the Overrange Complement Output Bit through the serial port register.
22	DNC/(OR+)	Do Not Connect. This pin can be reconfigured as the Overrange True Output Bit through the serial port register.

<sup>1</sup> AGND and DRGND should be tied to a common quiet ground plane.

### **TYPICAL PERFORMANCE CHARACTERISTICS**

AVDD = 1.8 V, DRVDD = 1.8 V, rated sample rate, DCS enabled,  $T_A = 25^{\circ}C$ , 1.25 V p-p differential input, AIN = -1 dBFS, unless otherwise noted.

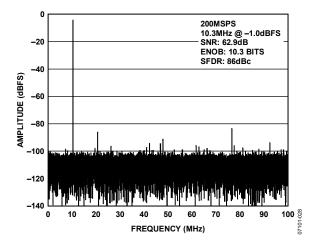
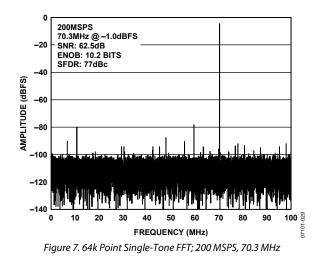


Figure 6. 64k Point Single-Tone FFT; 200 MSPS, 10.3 MHz



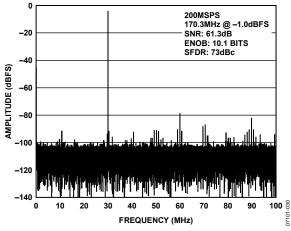


Figure 8. 64k Point Single-Tone FFT; 170 MSPS, 140.3 MHz

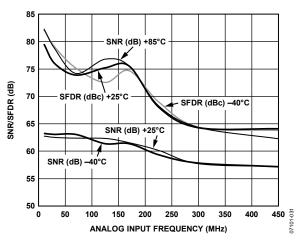
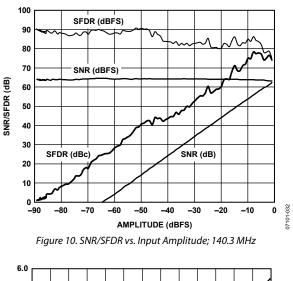
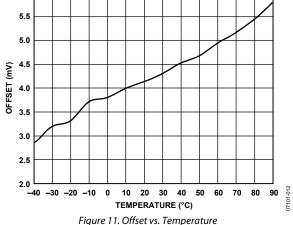
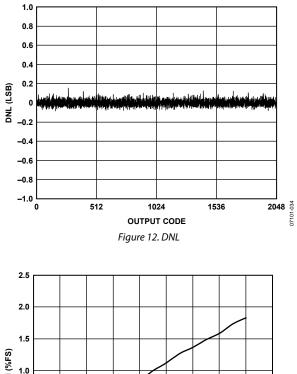
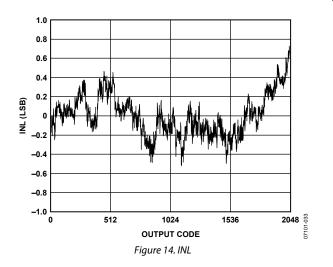


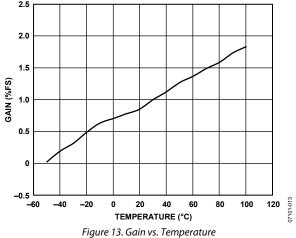
Figure 9. Single-Tone SNR/SFDR vs. Input Frequency (f<sub>IN</sub>) with 1.25 V p-p Full-Scale; 200 MSPS



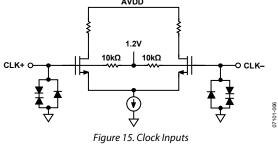


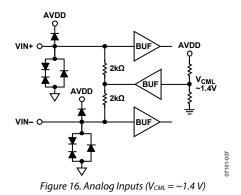






# EQUIVALENT CIRCUITS





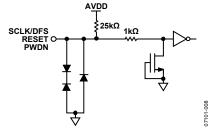


Figure 17. Equivalent SCLK/DFS, RESET, PWDN Input Circuit

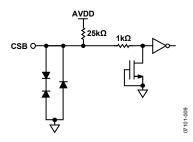


Figure 18. Equivalent CSB Input Circuit

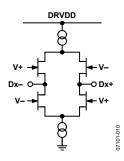


Figure 19. LVDS Outputs (Dx+, Dx-, OR+, OR-, DCO+, DCO-)

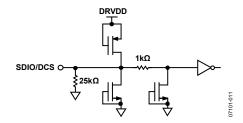


Figure 20. Equivalent SDIO/DCS Input Circuit

### THEORY OF OPERATION

The AD9230-11 architecture consists of a front-end sampleand-hold amplifier (SHA) followed by a pipelined switched capacitor ADC. The quantized outputs from each stage are combined into a final 11-bit result in the digital correction logic. The pipelined architecture permits the first stage to operate on a new input sample, while the remaining stages operate on preceding samples. Sampling occurs on the rising edge of the clock.

Each stage of the pipeline, excluding the last, consists of a low resolution flash ADC connected to a switched capacitor DAC and interstage residue amplifier (MDAC). The residue amplifier magnifies the difference between the reconstructed DAC output and the flash input for the next stage in the pipeline. One bit of redundancy is used in each stage to facilitate digital correction of flash errors. The last stage simply consists of a flash ADC.

The input stage contains a buffered differential SHA that can be ac- or dc-coupled. The output staging block aligns the data, carries out the error correction, and passes the data to the output buffers. The output buffers are powered from a separate supply, allowing adjustment of the output voltage swing. During power-down, the output buffers go into a high impedance state.

#### ANALOG INPUT AND VOLTAGE REFERENCE

The analog input to the AD9230-11 is a differential buffer. For best dynamic performance, the source impedances driving VIN+ and VIN- should be matched such that common-mode settling errors are symmetrical. The analog input is optimized to provide superior wideband performance and requires that the analog inputs be driven differentially. SNR and SINAD performance degrades significantly if the analog input is driven with a single-ended signal.

A wideband transformer, such as Mini-Circuits<sup>®</sup> ADT1-1WT, can provide the differential analog inputs for applications that require a single-ended-to-differential conversion. Both analog inputs are selfbiased by an on-chip resistor divider to a nominal 1.4 V. An internal differential voltage reference creates positive and negative reference voltages that define the 1.25 V p-p fixed span of the ADC core. This internal voltage reference can be adjusted by means of SPI control. See the Configuration Using the SPI section.

#### **Differential Input Configurations**

Optimum performance is achieved while driving the AD9230-11 in a differential input configuration. For baseband applications, the AD8138 differential driver provides excellent performance and a flexible interface to the ADC. The output common-mode voltage of the AD8138 is easily set to AVDD/2 + 0.5 V, and the driver can be configured in a Sallen-Key filter topology to provide band limiting of the input signal.

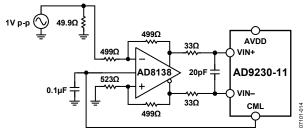


Figure 21. Differential Input Configuration Using the AD8138

At input frequencies in the second Nyquist zone and above, the performance of most amplifiers may not be adequate to achieve the true performance of the AD9230-11. This is especially true in IF undersampling applications where frequencies in the 70 MHz to 100 MHz range are being sampled. For these applications, differential transformer coupling is the recommended input configuration. The signal characteristics must be considered when selecting a transformer. Most RF transformers saturate at frequencies below a few megahertz and excessive signal power can also cause core saturation, leading to distortion. In any configuration, the value of the shunt capacitor, C, is dependent on the input frequency and may need to be reduced or removed.

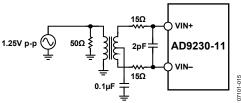


Figure 22. Differential Transformer—Coupled Configuration

As an alternative to using a transformer-coupled input at frequencies in the second Nyquist zone, the AD8352 differential driver can be used (see Figure 23).

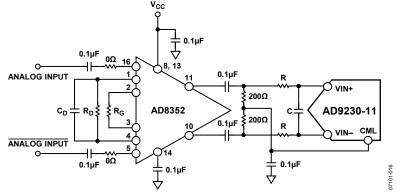


Figure 23. Differential Input Configuration Using the AD8352

#### **CLOCK INPUT CONSIDERATIONS**

For optimum performance, the AD9230-11 sample clock inputs (CLK+ and CLK-) should be clocked with a differential signal. This signal is typically ac-coupled into the CLK+ pin and the CLK- pin via a transformer or capacitors. These pins are biased internally and require no additional bias.

Figure 24 shows a preferred method for clocking the AD9230-11. The low jitter clock source is converted from single-ended to differential using an RF transformer. The back-to-back Schottky diodes across the secondary transformer limit clock excursions into the AD9230-11 to approximately 0.8 V p-p differential. This helps prevent the large voltage swings of the clock from feeding through to other portions of the AD9230-11 and preserves the fast rise and fall times of the signal, which are critical to low jitter performance.

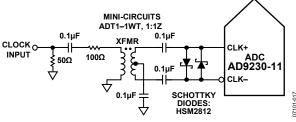


Figure 24. Transformer-Coupled Differential Clock

If a low jitter clock is available, another option is to ac couple a differential PECL signal to the sample clock input pins as shown in Figure 25. The AD9510/AD9511/AD9512/AD9513/ AD9514/AD9515 family of clock drivers offers excellent jitter performance.

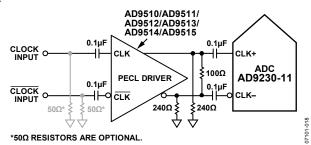


Figure 25. Differential PECL Sample Clock

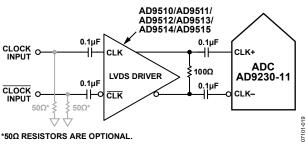
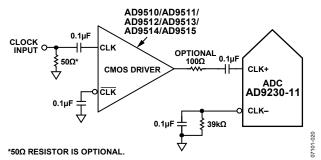
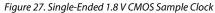
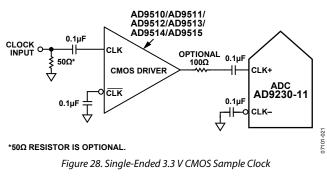


Figure 26. Differential LVDS Sample Clock

In some applications, it is acceptable to drive the sample clock inputs with a single-ended CMOS signal. In such applications, CLK+ should be directly driven from a CMOS gate, and the CLK– pin should be bypassed to ground with a 0.1  $\mu$ F capacitor in parallel with a 39 k $\Omega$  resistor (see Figure 27). Although the CLK+ input circuit supply is AVDD (1.8 V), this input is designed to withstand input voltages up to 3.3 V (as shown in Figure 28), making the selection of the drive logic voltage very flexible.







#### **Clock Duty Cycle Considerations**

Typical high speed ADCs use both clock edges to generate a variety of internal timing signals. As a result, these ADCs may be sensitive to clock duty cycle. Commonly, a 5% tolerance is required on the clock duty cycle to maintain dynamic performance characteristics. The AD9230-11 contains a duty cycle stabilizer (DCS) that retimes the nonsampling edge, providing an internal clock signal with a nominal 50% duty cycle. This allows a wide range of clock input duty cycles without affecting the performance of the AD9230-11. When the DCS is on, noise and distortion performance are nearly flat for a wide range of duty cycles. However, some applications may require the DCS function to be off. If so, keep in mind that the dynamic range performance can be affected when operated in this mode. See the Configuration Using the SPI section for more details on using this feature.

The duty cycle stabilizer uses a delay-locked loop (DLL) to create the nonsampling edge. As a result, any changes to the sampling frequency require approximately eight clock cycles to allow the DLL to acquire and lock to the new rate.

#### **Clock Jitter Considerations**

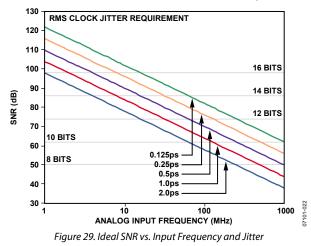
High speed, high resolution ADCs are sensitive to the quality of the clock input. The degradation in SNR at a given input frequency  $(f_A)$  due only to aperture jitter  $(t_I)$  can be calculated by

*SNR Degradation* =  $20 \times \log_{10}[1/2 \times \pi \times f_A \times t_J]$ 

In this equation, the rms aperture jitter represents the root mean square of all jitter sources, including the clock input, analog input signal, and ADC aperture jitter specifications. IF undersampling applications are particularly sensitive to jitter (see Figure 29).

Treat the clock as an analog signal in cases where aperture jitter may affect the dynamic range of the AD9230-11. Power supplies for clock drivers should be separated from the ADC output driver supplies to avoid modulating the clock signal with digital noise. Low jitter, crystal-controlled oscillators make the best clock sources. If the clock is generated from another type of source (by gating, dividing, or other methods), it should be retimed by the original clock at the last step.

Refer to the AN-501 Application Note and the AN-756 Application Note for more in-depth information about jitter performance as it relates to ADCs (visit www.analog.com).



#### POWER DISSIPATION AND POWER-DOWN MODE

The power dissipated by the AD9230-11 is proportional to its sample rate. The digital power dissipation does not vary much because it is determined primarily by the DRVDD supply and bias current of the LVDS output drivers.

By asserting PWDN (Pin 29) high, the AD9230-11 is placed in standby mode or full power-down mode, as determined by the contents of Register 0x08. Reasserting the PWDN pin low returns the AD9230-11 to its normal operational mode.

An additional standby mode is supported by means of varying the clock input. When the clock rate falls below 20 MHz, the AD9230-11 assumes a standby state. In this case, the biasing network and internal reference remain on, but digital circuitry is powered down. Upon reactivating the clock, the AD9230-11 resumes normal operation after allowing for the pipeline latency.

#### **DIGITAL OUTPUTS**

#### **Digital Outputs and Timing**

The AD9230-11 differential outputs conform to the ANSI-644 LVDS standard on default power-up. This can be changed to a low power, reduced signal option similar to the IEEE 1596.3 standard using the SPI. This LVDS standard can further reduce the overall power dissipation of the device, which reduces the power by ~39 mW. See the Memory Map section for more information. The LVDS driver current is derived on-chip and sets the output current at each output equal to a nominal 3.5 mA. A 100  $\Omega$  differential termination resistor placed at the LVDS receiver inputs results in a nominal 350 mV swing at the receiver.

The AD9230-11 LVDS outputs facilitate interfacing with LVDS receivers in custom ASICs and FPGAs that have LVDS capability for superior switching performance in noisy environments. Single point-to-point net topologies are recommended with a 100  $\Omega$  termination resistor placed as close to the receiver as possible. No far-end receiver termination and poor differential trace routing may result in timing errors. It is recommended that the trace length is no longer than 24 inches and that the differential output traces are kept close together and at equal lengths.

An example of the LVDS output using the ANSI standard (default) data eye and a time interval error (TIE) jitter histogram with trace lengths less than 24 inches on regular FR-4 material is shown in Figure 30. Figure 31 shows an example of when the trace lengths exceed 24 inches on regular FR-4 material. Notice that the TIE jitter histogram reflects the decrease of the data eye opening as the edge deviates from the ideal position. It is up to the user to determine if the waveforms meet the timing budget of the design when the trace lengths exceed 24 inches.

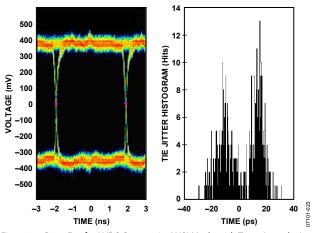


Figure 30. Data Eye for LVDS Outputs in ANSI Mode with Trace Lengths Less than 24 Inches on Standard FR-4

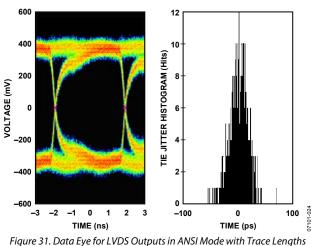


Figure 31. Data Eye for LVDS Outputs in ANSI Mode with Trace Lengths Greater than 24 Inches on Standard FR-4

The format of the output data is offset binary by default. An example of the output coding format can be found in Table 12. If it is desired to change the output data format to twos complement, see the Configuration Using the SPI section.

An output clock signal is provided to assist in capturing data from the AD9230-11. The DCO is used to clock the output data and is equal to the sampling clock (CLK) rate. In single data rate mode (SDR), data is clocked out of the AD9230-11 and must be captured on the rising edge of the DCO. In double data rate mode (DDR), data is clocked out of the AD9230-11 and must be captured on the rising and falling edges of the DCO See the timing diagrams shown in Figure 2 and Figure 3 for more information.

#### **Output Data Rate and Pinout Configuration**

The output data of the AD9230-11 can be configured to drive 12 pairs of LVDS outputs at the same rate as the input clock signal (single data rate, or SDR, mode), or six pairs of LVDS outputs at 2× the rate of the input clock signal (double data rate, or DDR, mode). SDR is the default mode; the device can be reconfigured for DDR by setting Bit 3 in Register 14 (see Table 13).

#### Out-of-Range (OR)

An out-of-range condition exists when the analog input voltage is beyond the input range of the ADC. OR is a digital output that is updated along with the data output corresponding to the particular sampled input voltage. Thus, OR has the same pipeline latency as the digital data. OR is low when the analog input voltage is within the analog input range and high when the analog input voltage exceeds the input range, as shown in Figure 32. OR remains high until the analog input returns to within the input range and another conversion is completed. By logically AND-ing OR with the MSB and its complement, overrange high or underrange low conditions can be detected.

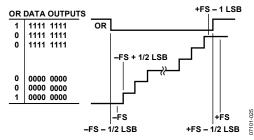


Figure 32. OR Relation to Input Voltage and Output Data

#### TIMING

The AD9230-11 provides latched data outputs with a pipeline delay of seven clock cycles. Data outputs are available one propagation delay ( $t_{\rm PD}$ ) after the rising edge of the clock signal.

The length of the output data lines and loads placed on them should be minimized to reduce transients within the AD9230-11. These transients can degrade the dynamic performance of the converter. The AD9230-11 also provides data clock output (DCO) intended for capturing the data in an external register. The data outputs are valid on the rising edge of DCO.

The lowest typical conversion rate of the AD9230-11 is 40 MSPS. At clock rates below 1 MSPS, the AD9230-11 assumes the standby mode.

#### RBIAS

The AD9230-11 requires the user to place a 10 k $\Omega$  resistor between the RBIAS pin and ground. This resister should have a 1% tolerance and is used to set the master current reference of the ADC core.

#### **CONFIGURATION USING THE SPI**

The AD9230-11 SPI allows the user to configure the converter for specific functions or operations through a structured register space inside the ADC. This gives the user added flexibility to customize device operation depending on the application. Addresses are accessed (programmed or readback) serially in 1-byte words. Each byte may be further divided down into fields, which are documented in the Memory Map section.

There are three pins that define the serial port interface (SPI) to this particular ADC. They are the SCLK/DFS, SDIO/DCS, and CSB pins. The SCLK/DFS (serial clock) is used to synchronize the read and write data presented to the ADC. The SDIO/DCS (serial data input/output) is a dual-purpose pin that allows data to be sent and read from the internal ADC memory map registers. The CSB pin is an active low control that enables or disables the read and write cycles (see Table 9).

#### Table 9. Serial Port Interface Pins

Mnemonic	Function
SCLK	SCLK (serial clock) is the serial shift clock in. SCLK is used to synchronize serial interface reads and writes.
SDIO	SDIO (serial data input/output) is a dual-purpose pin. The typical role for this pin is an input and output depending on the instruction being sent and the relative position in the timing frame.
CSB	CSB (chip select bar) is an active low control that gates the read and write cycles.
RESET	Master Device Reset. When asserted, device assumes default settings. Active low.

The falling edge of CSB, in conjunction with the rising edge of the SCLK, determines the start of the framing. An example of the serial timing and its definitions can be found in Figure 33 and Table 11.

During an instruction phase, a 16-bit instruction is transmitted. Data then follows the instruction phase and is determined by the W0 and W1 bits, which is 1 or more bytes of data. All data is composed of 8-bit words. The first bit of each individual byte of serial data indicates whether this is a read or write command. This allows the serial data input/output (SDIO) pin to change direction from an input to an output.

Data can be sent in MSB or in LSB first mode. MSB first is default on power-up and can be changed by changing the configuration register. For more information about this feature and others, see the AN-877 Application Note, *Interfacing to High Speed ADCs via SPI*, at www.analog.com.

#### HARDWARE INTERFACE

The pins described in Table 9 comprise the physical interface between the user's programming device and the serial port of the AD9230-11. All serial pins are inputs, which is an open-drain output and should be tied to an external pull-up or pull-down resistor (suggested value of 10 k $\Omega$ ).

This interface is flexible enough to be controlled by either PROMS or PIC microcontrollers as well. This provides the user with an alternate method to program the ADC other than using an SPI controller.

If the user chooses not to use the SPI interface, some pins serve a dual function and are associated with a specific function when strapped externally to AVDD or ground during device power on. The Configuration Without the SPI section describes the strappable functions supported on the AD9230-11.

#### **CONFIGURATION WITHOUT THE SPI**

In applications that do not interface to the SPI control registers, the SDIO/DCS and SCLK/DFS pins can alternately serve as standalone CMOS-compatible control pins. When the device is powered up, it is assumed that the user intends to use the pins as static control lines for the duty cycle stabilizer. In this mode, the CSB pin should be connected to AVDD, which disables the serial port interface.

#### Table 10. Mode Selection

Mnemonic	External Voltage	Configuration
SDIO/DCS	AVDD	Duty cycle stabilizer enabled
	AGND	Duty cycle stabilizer disabled
SCLK/DFS	AVDD	Twos complement enabled
	AGND	Offset binary enabled

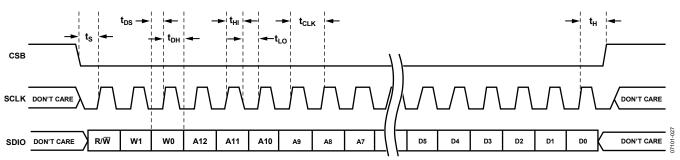


Figure 33. Serial Port Interface Timing Diagram

#### Table 11. Serial Timing Definitions

Parameter	Timing (minimum, ns)	Description
t <sub>DS</sub>	5	Setup time between the data and the rising edge of SCLK
t <sub>DH</sub>	2	Hold time between the data and the rising edge of SCLK
<b>t</b> <sub>CLK</sub>	40	Period of the clock
ts	5	Setup time between CSB and SCLK
tн	2	Hold time between CSB and SCLK
t <sub>HI</sub>	16	Minimum period that SCLK should be in a logic high state
t <sub>LO</sub>	16	Minimum period that SCLK should be in a logic low state
t <sub>en_sdio</sub>	1	Minimum time for the SDIO pin to switch from an input to an output relative to the SCLK falling edge (not shown in Figure 33)
t <sub>DIS_SDIO</sub>	5	Minimum time for the SDIO pin to switch from an output to an input relative to the SCLK rising edge (not shown in Figure 33)

#### Table 12. Output Data Format

		Offset Binary Output Mode	Twos Complement Mode	
Input (V)	Condition (V)	D10 to D0	D10 to D0	OR
VIN+-VIN-	< 0.62	0000 0000 000	1000 0000 000	1
VIN + - VIN -	= 0.62	0000 0000 000	1000 0000 000	0
VIN+-VIN-	= 0	0000 0000 000	0000 0000 000	0
VIN+-VIN-	= 0.62	1111 1111 111	0111 1111 111	0
VIN + - VIN -	> 0.62 + 0.5 LSB	1111 1111 111	0111 1111 111	1

### MEMORY MAP reading the memory map table

Each row in the memory map table has eight address locations. The memory map is roughly divided into three sections: chip configuration register map (Address 0x00 to Address 0x02), transfer register map (Address 0xFF), and ADC functions map (Address 0x08 to Address 0x2A).

The Addr. (Hex) column of the memory map indicates the register address in hexadecimal, and the Default Value (Hex) column shows the default hexadecimal value that is already written into the register. The Bit 7 (MSB) column is the start of the default hexadecimal value given. For example, Hexadecimal Address 0x09, the clock register, has a hexadecimal default value of 0x01. This means Bit 7 = 0, Bit 6 = 0, Bit 5 = 0, Bit 4 = 0, Bit 3 = 0, Bit 2 = 0, Bit 1 = 0, and Bit 0 = 1, or 0000 0001 in binary. The default value enables the duty cycle stabilizer. Overwriting this default so that Bit 0 = 0 disables the duty cycle stabilizer. For more information on this and other functions, consult the AN-877 Application Note, *Interfacing to High Speed ADCs via SPI*, at www.analog.com.

#### **RESERVED LOCATIONS**

Undefined memory locations should not be written to other than their default values suggested in this data sheet. Addresses that have values marked as 0 should be considered reserved and have a 0 written into their registers during power-up.

#### **DEFAULT VALUES**

Coming out of reset, critical registers are preloaded with default values. These values are indicated in Table 13. Other registers do not have default values and retain the previous value when exiting reset.

#### LOGIC LEVELS

An explanation of logic level terminology follows: "bit is set" is synonymous with "bit is set to Logic 1" or "writing Logic 1 for the bit." Similarly, "clear a bit" is synonymous with "bit is set to Logic 0" or "writing Logic 0 for the bit."

#### **TRANSFER REGISTER MAP**

Address 0x08 to Address 0x18 are shadowed. Writes to these addresses do not affect part operation until a transfer command is issued by writing 0x01 to Address 0xFF, setting the transfer bit. This allows these registers to be updated internally and simultaneously when the transfer bit is set. The internal update takes place when the transfer bit is set, and the bit autoclears.

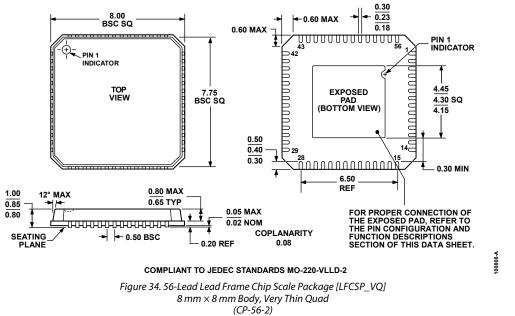
Addr. (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default Value (Hex)	Notes/ Comments
Chip Co	onfiguration Registe	ers								1	•
0x00	chip_port_config	0 LSB Soft 1 1 Soft reset 0							0x18	The nibbles should be mirrored by the user so that LSB-or MSB-first mode registers correctly, regardless of shift mode.	
0x01	chip_id		8-bit chip ID, Bits[7:0] AD9230-11 = 0x0C							Read- only	Default is unique chip ID, different for each device. This is a read-only register.
0x02	chip_grade	0	0	0	Speed grade: X X X   11 = 200 MSPS X X X				Read- only	Child ID used to differentiate graded devices.	
Transfe	er Register										
0xFF	device_update	0	0	0	0	0	0	0	SW transfer	0x00	Synchronously transfers data from the master shift register to the slave.

#### Table 13. Memory Map Register

Addr. (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default Value (Hex)	Notes/ Comments
	unctions	(1100)	Dire	DIED	DICT	Ditto	5112	Ditt	(200)	(110,7)	connents
0x08	modes	0	0	PWDN: 0 = full (default) 1 = standby	0	0	Internal power-down mode: 000 = normal (power-up, default) 001 = full power-down 010 = standby 011 = normal (power-up) Note: external PWDN pin overrides this setting			0x00	Determines various generic modes of chip operation.
0x09	clock	0	0	0	0	0	0	0	Duty cycle stabilizer: 0 = disabled 1 = enabled (default)	0x01	
0x0D	test_io	0	0	Reset PN23 gen: 1 = on 0 = off (default)	Reset PN9 gen: 1 = on 0 = off (default)	0000 0011 0010 0111 0100 0101 0111 1000 1001 1010 1011 1100	it test mode: = off (default) = midscale short = +FS short = -FS short = checker board output = PN 23 sequence = PN 9 = one/zero word toggle = unused = unused			0x00	When this register is set, the test data is placed on the output pins in place of normal data.
0x0F	ain_config	0	0	0	0	0	Analog input disable: 1 = on 0 = off (default)	CML enable: 1 = on 0 = off (default)	0	0x00	
0x14	output_mode	0	0	0	Output enable: 0 = enable (default) 1 = disable	DDR: 1 = enabled 0 = disabled (default)	Output invert: 1 = on 0 = off (default)	Data format select: 00 = offset binary (default) 01 = twos		0x00	
0x15	output_adjust	0	0	0	0	LVDS course adjust: 0 = 3.5 mA (default) 1 = 2.0 mA		LVDS fine adjust: 001 = 3.50 mA 010 = 3.25 mA 011 = 3.00 mA 100 = 2.75 mA 101 = 2.50 mA 110 = 2.25 mA 111 = 2.00 mA			
16	output_phase	Output clock polarity 1 = inverted 0 = normal (default)	0	0	0	0	0	0		0x03	

Addr. (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default Value (Hex)	Notes/ Comments
0x17	flex_output_delay	Output delay enable: 0 = enable 1 = disable	0	0		o	0				
0x18	flex_vref	0	0	0		11111 = 3.2 ns Input voltage range setting: 10000 = 0.98 V 10001 = 1.00 V 10010 = 1.02 V 10011 = 1.04 V  11111 = 1.23 V 00000 = 1.25 V 00001 = 1.27 V  01110 = 1.48 V					
0x2A	ovr_config	0	0	0	0	0	0	OR position (DDR mode only): 0 = Pin 9, Pin 10 1 = Pin 21, Pin 22	OR enable: 1 = on (default) 0 = off	0x01	

### **OUTLINE DIMENSIONS**



(CP-56-2) Dimensions shown in millimeters

#### **ORDERING GUIDE**

Model	Temperature Range	Package Description	Package Option		
AD9230BCPZ11-2001	-40°C to +85°C	56-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-56-2		
AD923011-200EBZ1		LVDS Evaluation Board			

 $^{1}$  Z = RoHS Compliant Part.

### NOTES

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