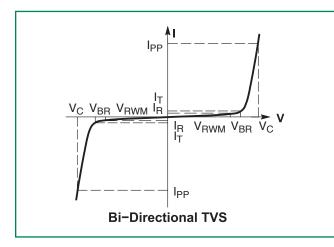


Surface Mount > 600W > 1SMB10CAT3G Series

I-V Curve Characteristics $(T_A = 25^{\circ}C \text{ unless otherwise noted})$



Symbol	Parameter
I _{PP}	Maximum Reverse Peak Pulse Current
V _c	Clamping Voltage @ I _{PP}
V _{RWM}	Working Peak Reverse Voltage
I _R	Maximum Reverse Leakage Current @V _{RWM}
V _{BR}	Breakdown Voltage @ I _T
I _T	Test Current



Surface Mount > 600W > 1SMB10CAT3G Series

Electrical Characteristics

	Device Marking		I _R @	Breakdown Voltage				V _C @ I _{PP} (Note 8)		- СТур.
Device*			V _{RWM}	V _{BR} @ I _T (V) (Note 7)			@ I _T	V _c	I _{PP} (Note \$	(Note 9)
		Volts	μA	MIN	NOM	MAX	mA	Volts	Amps	рF
1SMB10CAT3G	КХС	10	5.0	11.1	11.69	12.27	1.0	17.0	35.3	805
1SMB11CAT3G	KZC	11	5.0	12.2	12.84	13.5	1.0	18.2	33.0	740
1SMB12CAT3G	LEC	12	5.0	13.3	14.00	14.7	1.0	19.9	30.2	680
1SMB13CAT3G	LGC	13	5.0	14.4	15.16	15.9	1.0	21.5	27.9	630
1SMB14CAT3G	LKC	14	5.0	15.6	16.42	17.2	1.0	23.2	25.8	590
1SMB15CAT3G	LMC	15	5.0	16.7	17.58	18.5	1.0	24.4	24.0	555
1SMB16CAT3G	LPC	16	5.0	17.8	18.74	19.7	1.0	26.0	23.1	520
1SMB17CAT3G	LRC	17	5.0	18.9	19.90	20.9	1.0	27.6	21.7	490
1SMB18CAT3G	LTC	18	5.0	20.0	21.06	22.1	1.0	29.2	20.5	465
1SMB20CAT3G	LVC	20	5.0	22.2	23.37	24.5	1.0	32.4	18.5	425
1SMB22CAT3G	LXC	22	5.0	24.4	25.69	27.0	1.0	35.5	16.9	390
1SMB24CAT3G	LZC	24	5.0	26.7	28.11	29.5	1.0	38.9	15.4	366
1SMB26CAT3G	MEC	26	5.0	28.9	30.42	31.9	1.0	42.1	14.2	330
1SMB28CAT3G	MGC	28	5.0	31.1	32.74	34.4	1.0	45.4	13.2	310
1SMB30CAT3G	МКС	30	5.0	33.3	35.06	36.8	1.0	48.4	12.4	290
1SMB33CAT3G	MMC	33	5.0	36.7	38.63	40.6	1.0	53.3	11.3	265
1SMB36CAT3G	MPC	36	5.0	40.0	42.11	44.2	1.0	58.1	10.3	245
1SMB40CAT3G	MRC	40	5.0	44.4	46.74	49.1	1.0	64.5	9.3	220
1SMB43CAT3G	MTC	43	5.0	47.8	50.32	52.8	1.0	69.4	8.6	210
1SMB45CAT3G	MVC	45	5.0	50.0	52.63	55.3	1.0	72.2	8.3	200
1SMB48CAT3G	MXC	48	5.0	53.3	56.11	58.9	1.0	77.4	7.7	190
1SMB51CAT3G	MZC	51	5.0	56.7	59.69	62.7	1.0	82.4	7.3	175
1SMB54CAT3G	NEC	54	5.0	60.0	63.16	66.32	1.0	87.1	6.9	170
1SMB58CAT3G	NGC	58	5.0	64.4	67.79	71.18	1.0	93.6	6.4	155
1SMB60CAT3G	NKC	60	5.0	66.7	70.21	73.72	1.0	96.8	6.2	150
1SMB64CAT3G	NMC	64	5.0	71.1	74.84	78.58	1.0	103	5.8	145
1SMB75CAT3G	NRC	75	5.0	83.3	91.65	92.07	1.0	121	4.9	125

4. A transient suppressor is normally selected according to the working peak reverse voltage (V_{RWM}), which should be equal to or greater than the

DC or continuous peak operating voltage level.

5. $V_{_{\rm BR}}$ measured at pulse test current $I_{_{\rm T}}$ at an ambient temperature of 25°C.

6. Surge current waveform per Figure 2 and derate per Figure 3 of the General Data - 600 Watt at the beginning of this group.

7. Bias Voltage = 0 V, F = 1 MHz, T_{\downarrow} = 25°C



Surface Mount > 600W > 1SMB10CAT3G Series

Ratings and Characteristic Curves

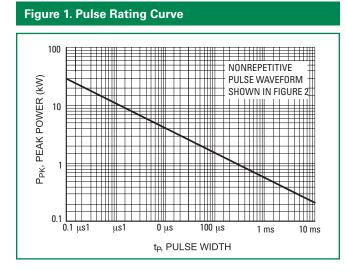
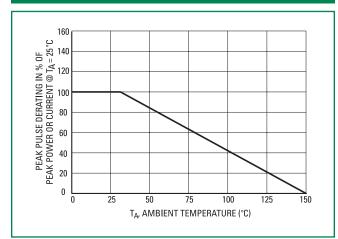


Figure 3. Pulse Derating Curve



Typical Protection Circuit

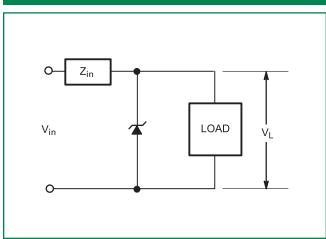


Figure 2. Pulse Waveform

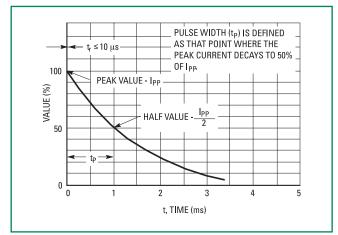
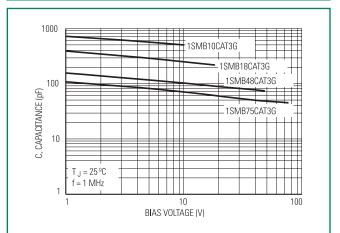


Figure 4. Typical Junction Capacitance vs. Bias Voltage





Application Notes

ResponseTime

In most applications, the transient suppressor device is placed in parallel with the equipment or component to be protected. In this situation, there is a time delay associated with the capacitance of the device and an overshoot condition associated with the inductance of the device and the inductance of the connection method. The capacitive effect is of minor importance in the parallel protection scheme because it only produces a time delay in the transition from the operating voltage to the clamp voltage as shown in Figure 5.

The inductive effects in the device are due to actual turn-on time (time required for the device to go from zero current to full current) and lead inductance. This inductive effect produces an overshoot in the voltage across the equipment or component being protected as shown in Figure 6. Minimizing this overshoot is very important in the application, since the main purpose for adding a transient suppressor is to clamp voltage spikes. The SMB series have a very good response time, typically < 1 ns and negligible inductance. However, external inductive effects could produce unacceptable overshoot. Proper circuit layout minimum lead lengths and placing the suppressor device as close as possible to the equipment or components to be protected will minimize this overshoot.

Some input impedance represented by Zin is essential to prevent overstress of the protection device. This impedance should be as high as possible, without restricting the circuit operation.

Duty Cycle Derating

The data of Figure 1 applies for non-repetitive conditions and at a lead temperature of 25°C. If the duty cycle increases, the peak power must be reduced as indicated by the curves of Figure 7. Average power must be derated as the lead or ambient temperature rises above 25°C. The average power derating curve normally given on data sheets may be normalized and used for this purpose.

At first glance the derating curves of Figure 7 appear to be in error as the 10 ms pulse has a higher derating factor than the 10 s pulse. However, when the derating factor for a given pulse of Figure 7 is multiplied by the peak power value of Figure 1 for the same pulse, the results follow the expected trend.

Figure 5.

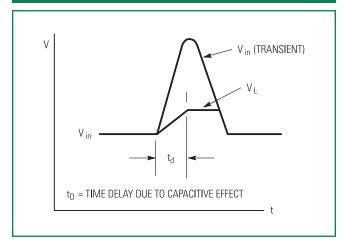


Figure 6.

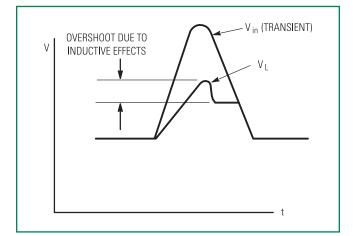
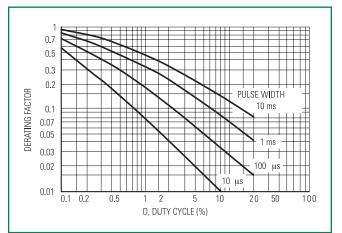


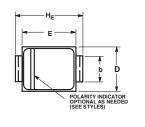
Figure 7. Typical Derating Factor for Duty Cycle

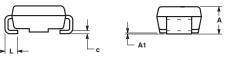




Surface Mount > 600W > 1SMB10CAT3G Series

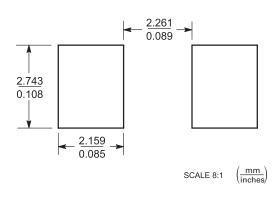
Dimensions





Dim		Inches		Millimeters			
DIIII	Min	Nom	Max	Min	Nom	Max	
А	0.075	0.087	0.090	1.90	2.20	2.28	
A1	0.002	0.004	0.007	0.05	0.10	0.19	
b	0.077	0.080	0.087	1.96	2.03	2.20	
С	0.006	0.009	0.012	0.15	0.23	0.31	
D	0.130	0.140	0.156	3.30	3.56	3.95	
E	0.160	0.170	0.181	4.06	4.32	4.60	
H _E	0.205	0.214	0.220	5.21	5.44	5.60	
L	0.030	0.040	0.063	0.76	1.02	1.60	
L1	0.020 REF				0.51 REF		

Soldering Footrpint



ORDERING INFORMATION

Device	Package	Shipping
1SMBxxCAT3G	SMB (Pb–Free)	2,500 / Tape & Reel

Flow/Wave Soldering (Solder Dipping)

Peak Temperature :	260 °C
Dipping Time :	10 seconds

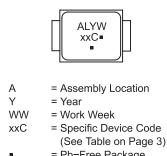
NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

2. CONTROLLING DIMENSION: INCH.

3. D DIMENSION SHALL BE MEASURED WITHIN DIMENSION P.

Part Marking System



= Pb-Free Package

(Note: Microdot may be in either location)

Physical Specifications

Case	Void-free, transfer-molded, thermosetting plastic
Polarity	Cathode indicated by polarity band
Mounting Position	Any
Finish	All external surfaces are corrosion resistant and leads are readily solderable
Leads	Modified L–Bend providing more contact area to bond pads

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