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- Practical Design Techniques for Sensor Signal Conditioning, 1999

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Reference Materials

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- Demystifying Auto-Zero Amplifiers Part 1
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REVISION HISTORY

10/11—Revision 0: Initial Version

SPECIFICATIONS

ELECTRICAL CHARACTERISTICS—30 V OPERATION

$V_S = 30\text{ V}$, $V_{CM} = V_{SY}/2\text{ V}$, $T_A = 25^\circ\text{C}$, unless otherwise specified.

Table 2.

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
INPUT CHARACTERISTICS						
Offset Voltage	V_{OS}	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; SOIC		0.5	4.5	μV
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; LFCSP			12.5	μV
Offset Voltage Drift	$\Delta V_{OS}/\Delta T$	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; SOIC			14.5	$\mu\text{V}/^\circ\text{C}$
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; LFCSP			0.08	$\mu\text{V}/^\circ\text{C}$
Input Bias Current	I_B			45	90	pA
Input Offset Current	I_{OS}	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			500	pA
				25	105	pA
Input Voltage Range		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			170	pA
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0\text{ V to } 27\text{ V}$	0		27	V
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	130	142		dB
Open-Loop Gain	A_{VO}	$R_L = 10\text{ k}\Omega$, $V_O = 1\text{ V to } 29\text{ V}$	130			dB
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	140	165		dB
Input Resistance, Common Mode	R_{INCM}		140			dB
Input Capacitance, Differential Mode	C_{INDM}			330		G Ω
Input Capacitance, Common Mode	C_{INCM}			4		pF
				9		pF
OUTPUT CHARACTERISTICS						
Output Voltage High	V_{OH}	$R_L = 10\text{ k}\Omega$ to V_{CM}	29.90	29.92		V
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	29.85			V
		$R_L = 2\text{ k}\Omega$ to V_{CM}	29.50	29.58		V
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	29.35			V
Output Voltage Low	V_{OL}	$R_L = 10\text{ k}\Omega$ to V_{CM}		50	60	mV
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			95	mV
		$R_L = 2\text{ k}\Omega$ to V_{CM}		235	270	mV
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			445	mV
Short-Circuit Current	I_{SC}			± 38		mA
Closed-Loop Output Impedance	Z_{OUT}	$f = 1\text{ MHz}$, $A_v = +1$		220		Ω
POWER SUPPLY						
Power Supply Rejection Ratio	PSRR	$V_S = 4.5\text{ V to } 30\text{ V}$	120	143		dB
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	120			dB
Supply Current/Amplifier	I_{SY}	$I_O = 0\text{ mA}$		0.85	1.05	mA
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			1.25	mA
DYNAMIC PERFORMANCE						
Slew Rate	SR	$R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_v = +1$		1.5		V/ μs
Overload Recovery Time		$R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_v = -100$		8		μs
Settling Time to 0.1%	t_s	$V_{IN} = 5\text{ V step}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_v = -1$		4		μs
Unity-Gain Crossover	UGC	$V_{IN} = 30\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_v = +1$		1.3		MHz
Phase Margin	Φ_M	$V_{IN} = 30\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_v = +1$		69		Degrees
Gain-Bandwidth Product	GBP	$V_{IN} = 30\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_v = +100$		1.5		MHz
-3 dB Closed-Loop Bandwidth	f_{-3dB}	$V_{IN} = 30\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_v = +1$		2.5		MHz
NOISE PERFORMANCE						
Voltage Noise	$e_n\text{ p-p}$	$f = 0.1\text{ Hz to } 10\text{ Hz}$		1.2		$\mu\text{V p-p}$
Voltage Noise Density	e_n	$f = 1\text{ kHz}$		66		nV/ $\sqrt{\text{Hz}}$
Current Noise Density	i_n	$f = 1\text{ kHz}$		0.1		pA/ $\sqrt{\text{Hz}}$

ELECTRICAL CHARACTERISTICS—10 V OPERATION

$V_S = 10\text{ V}$, $V_{CM} = V_{SY}/2\text{ V}$, $T_A = 25^\circ\text{C}$, unless otherwise specified.

Table 3.

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
INPUT CHARACTERISTICS						
Offset Voltage	V_{OS}	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; SOIC $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; LFCSP		0.1	4 9 12	μV μV μV
Offset Voltage Drift	$\Delta V_{OS}/\Delta T$	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; SOIC $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; LFCSP			0.05 0.08	$\mu\text{V}/^\circ\text{C}$ $\mu\text{V}/^\circ\text{C}$
Input Bias Current	I_B	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		20	50 250	pA pA
Input Offset Current	I_{OS}	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		20	80 140	pA pA
Input Voltage Range			0		7	V
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0\text{ V to }7\text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	130	155		dB dB
Open-Loop Gain	A_{VO}	$R_L = 10\text{ k}\Omega$, $V_O = 1\text{ V to }9\text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	130	160		dB dB
Input Resistance, Common Mode	R_{INCM}			250		G Ω
Input Capacitance, Differential Mode	C_{INDM}			4		pF
Input Capacitance, Common Mode	C_{INCM}			9		pF
OUTPUT CHARACTERISTICS						
Output Voltage High	V_{OH}	$R_L = 10\text{ k}\Omega$ to V_{CM} $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ $R_L = 2\text{ k}\Omega$ to V_{CM} $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	9.96 9.95 9.85 9.75	9.97		V V V V
Output Voltage Low	V_{OL}	$R_L = 10\text{ k}\Omega$ to V_{CM} $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ $R_L = 2\text{ k}\Omega$ to V_{CM} $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		20 80	25 40 90 145	mV mV mV mV
Short-Circuit Current	I_{SC}	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		± 22		mA
Closed-Loop Output Impedance	Z_{OUT}	$f = 1\text{ MHz}$, $A_V = +1$		300		Ω
POWER SUPPLY						
Power Supply Rejection Ratio	PSRR	$V_S = 4.5\text{ V to }30\text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	120 120	143		dB dB
Supply Current/Amplifier	I_{SY}	$I_O = 0\text{ mA}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		0.8	0.95 1.15	mA mA
DYNAMIC PERFORMANCE						
Slew Rate	SR	$R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +1$		1.5		V/ μs
Overload Recovery Time		$R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = -100$		14		μs
Settling Time to 0.1%	t_S	$V_{IN} = 2\text{ V step}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = -1$		3		μs
Unity-Gain Crossover	UGC	$V_{IN} = 30\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +1$		1.1		MHz
Phase Margin	Φ_M	$V_{IN} = 30\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +1$		67		Degrees
Gain Bandwidth Product	GBP	$V_{IN} = 30\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +100$		1.4		MHz
-3 dB Closed-Loop Bandwidth	f_{-3dB}	$V_{IN} = 30\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +1$		1.9		MHz
NOISE PERFORMANCE						
Voltage Noise	$e_n\text{ p-p}$	$f = 0.1\text{ Hz to }10\text{ Hz}$		1.2		$\mu\text{V p-p}$
Voltage Noise Density	e_n	$f = 1\text{ kHz}$		66		nV/ $\sqrt{\text{Hz}}$
Current Noise Density	i_n	$f = 1\text{ kHz}$		0.1		pA/ $\sqrt{\text{Hz}}$

ELECTRICAL CHARACTERISTICS—5 V OPERATION

$V_S = 5\text{ V}$, $V_{CM} = V_{SY}/2\text{ V}$, $T_A = 25^\circ\text{C}$, unless otherwise specified.

Table 4.

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
INPUT CHARACTERISTICS						
Offset Voltage	V_{OS}	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; SOIC		1	13	μV
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; LFCSP			18	μV
Offset Voltage Drift	$\Delta V_{OS}/\Delta T$	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; SOIC			21	$\mu\text{V}/^\circ\text{C}$
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$; LFCSP			0.05	$\mu\text{V}/^\circ\text{C}$
Input Bias Current	I_B	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		30	90	pA
Input Offset Current	I_{OS}	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		60	170	pA
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			200	pA
Input Voltage Range			0		3	V
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0\text{ V to } 3\text{ V}$	118	140		dB
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	118			dB
Open-Loop Gain	A_{VO}	$R_L = 10\text{ k}\Omega$, $V_O = 0.5\text{ V to } +4.5\text{ V}$	125	150		dB
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	125			dB
Input Resistance, Common Mode	R_{INCM}			75		$\text{G}\Omega$
Input Capacitance, Differential Mode	C_{INDM}			4		pF
Input Capacitance, Common Mode	C_{INCM}			9		pF
OUTPUT CHARACTERISTICS						
Output Voltage High	V_{OH}	$R_L = 10\text{ k}\Omega$ to V_{CM}	4.98	4.984		V
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	4.97			V
		$R_L = 2\text{ k}\Omega$ to V_{CM}	4.90	4.92		V
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	4.87			V
Output Voltage Low	V_{OL}	$R_L = 10\text{ k}\Omega$ to V_{CM}		7.5	10	mV
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			15	mV
		$R_L = 2\text{ k}\Omega$ to V_{CM}		37	45	mV
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			70	mV
Short-Circuit Current	I_{SC}			± 22		mA
Closed-Loop Output Impedance	Z_{OUT}	$f = 1\text{ MHz}$, $A_V = +1$		340		Ω
POWER SUPPLY						
Power Supply Rejection Ratio	PSRR	$V_S = 4.5\text{ V to } 30\text{ V}$	120	143		dB
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	120			dB
Supply Current/Amplifier	I_{SY}	$I_O = 0\text{ mA}$		0.8	0.95	mA
		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			1.15	mA
DYNAMIC PERFORMANCE						
Slew Rate	SR	$R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +1$		1.5		$\text{V}/\mu\text{s}$
Overload Recovery Time		$R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = -100$		22		μs
Settling Time to 0.1%	t_s	$V_{IN} = 1\text{ V step}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = -1$		3		μs
Unity-Gain Crossover	UGC	$V_{IN} = 20\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +1$		1.0		MHz
Phase Margin	Φ_M	$V_{IN} = 20\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +1$		64		Degrees
Gain Bandwidth Product	GBP	$V_{IN} = 20\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +100$		1.3		MHz
-3 dB Closed-Loop Bandwidth	$f_{-3\text{dB}}$	$V_{IN} = 20\text{ mV p-p}$, $R_L = 10\text{ k}\Omega$, $C_L = 20\text{ pF}$, $A_V = +1$		1.8		MHz
NOISE PERFORMANCE						
Voltage Noise	$e_n\text{ p-p}$	$f = 0.1\text{ Hz to } 10\text{ Hz}$		1.2		$\mu\text{V p-p}$
Voltage Noise Density	e_n	$f = 1\text{ kHz}$		70		$\text{nV}/\sqrt{\text{Hz}}$
Current Noise Density	i_n	$f = 1\text{ kHz}$		0.015		$\text{pA}/\sqrt{\text{Hz}}$

ABSOLUTE MAXIMUM RATINGS

Table 5.

Parameter	Rating
Supply Voltage	33 V
Input Voltage ¹	$\pm V_{SY}$
Input Current	± 10 mA
Differential Input Voltage	$\pm V_{SY}$
Output Short-Circuit Duration to GND	Indefinite
Storage Temperature Range	–65°C to +150°C
Operating Temperature Range	–40°C to +125°C
Junction Temperature Range	–65°C to +150°C
Lead Temperature (Soldering, 60 sec)	300°C

¹ Input voltage should always be limited to less than 30 V.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

THERMAL RESISTANCE

θ_{JA} is specified for a device soldered on a 4-layer JEDEC standard board with zero airflow. For LFCSP packages, the exposed pad is soldered to the board.

Table 6. Thermal Resistance

Package Type	θ_{JA}	θ_{JC}	Unit
8-Lead SOIC	120	45	°C/W
8-Lead LFCSP	75	12	°C/W

ESD CAUTION



ESD (electrostatic discharge) sensitive device.

Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

TYPICAL PERFORMANCE CHARACTERISTICS

$T_A = 25^\circ\text{C}$, unless otherwise noted.

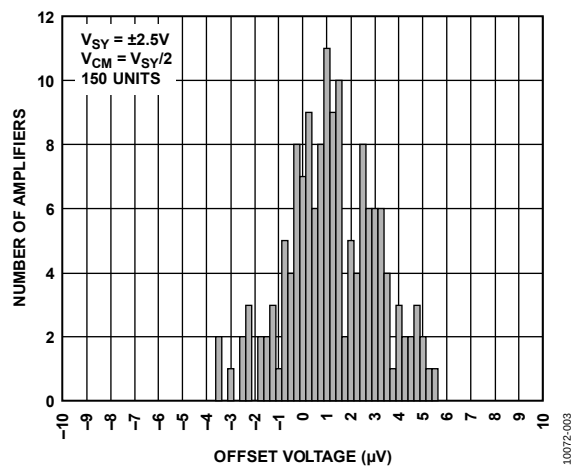


Figure 3. Input Offset Voltage Distribution

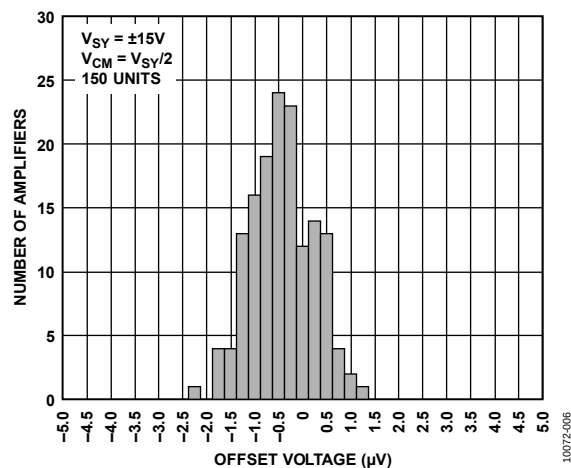


Figure 6. Input Offset Voltage Distribution

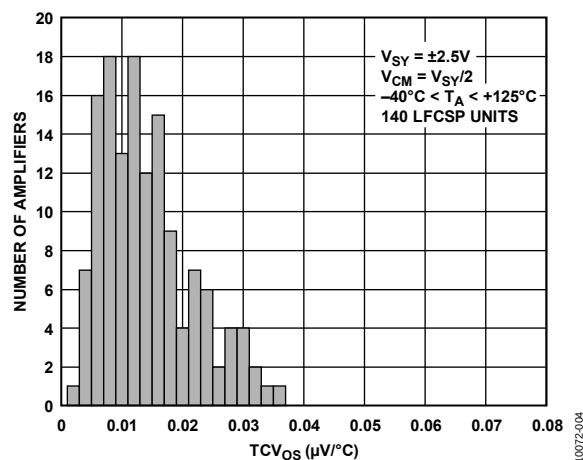


Figure 4. Input Offset Voltage Drift Distribution

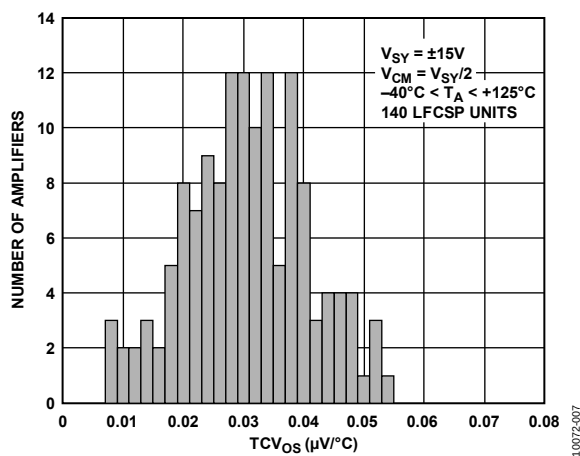


Figure 7. Input Offset Voltage Drift Distribution

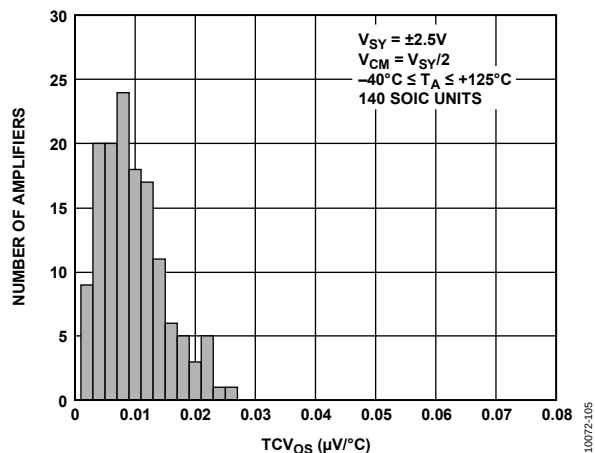


Figure 5. Input Offset Voltage Drift Distribution

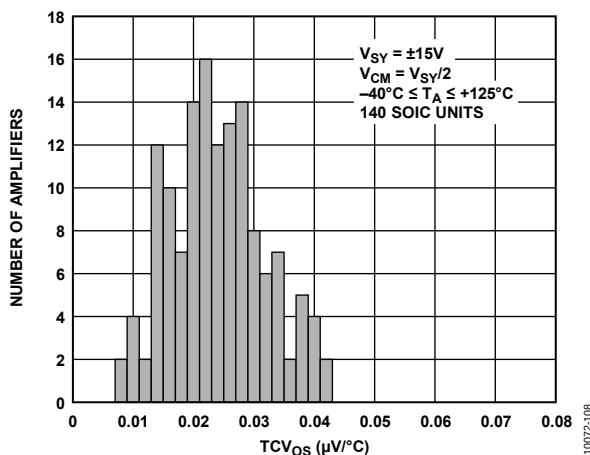


Figure 8. Input Offset Voltage Drift Distribution

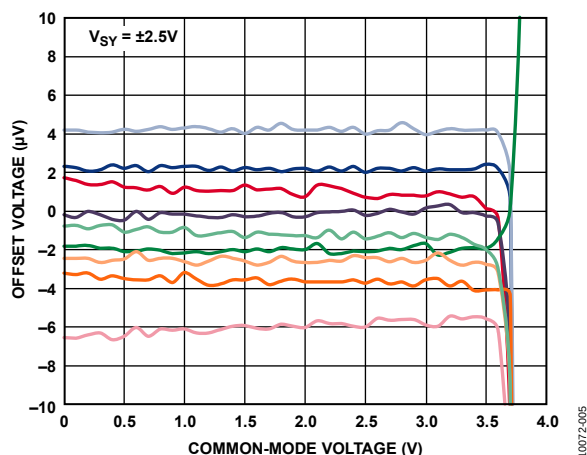


Figure 9. Input Offset Voltage vs. Common-Mode Voltage

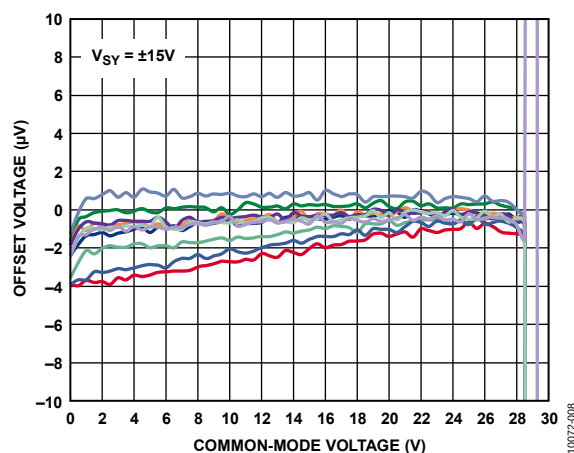


Figure 12. Input Offset Voltage vs. Common-Mode Voltage

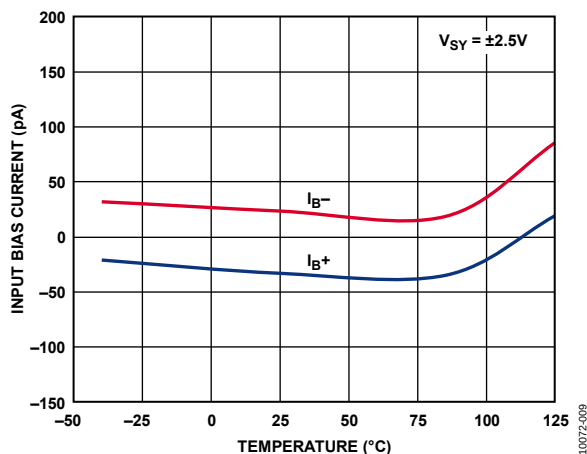


Figure 10. Input Bias Current vs. Temperature

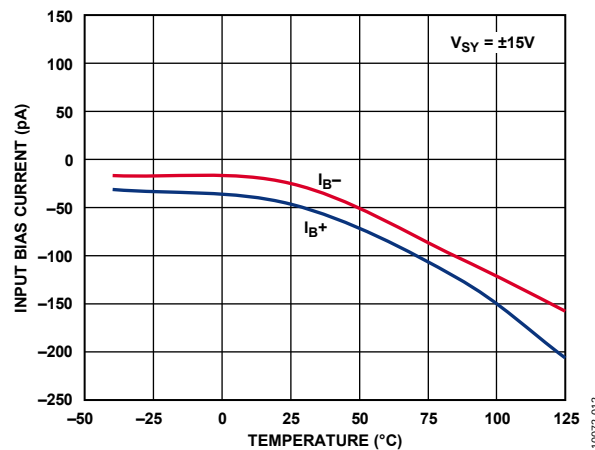


Figure 13. Input Bias Current vs. Temperature

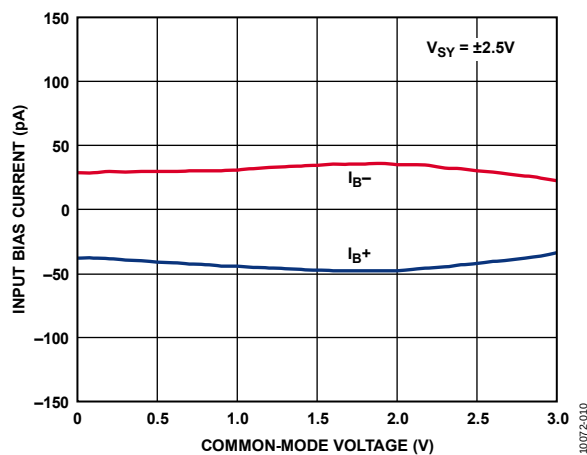


Figure 11. Input Bias Current vs. Common-Mode Voltage

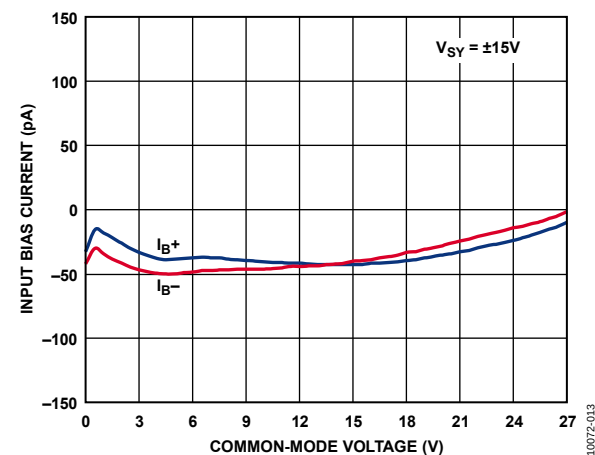
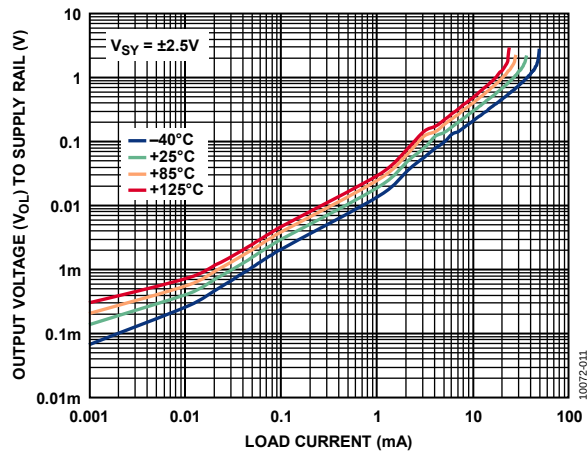
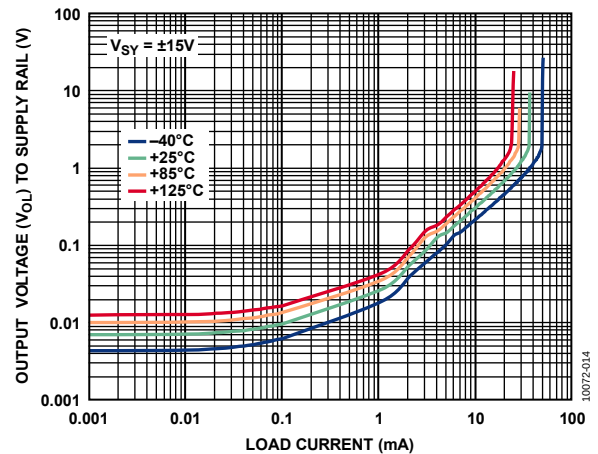
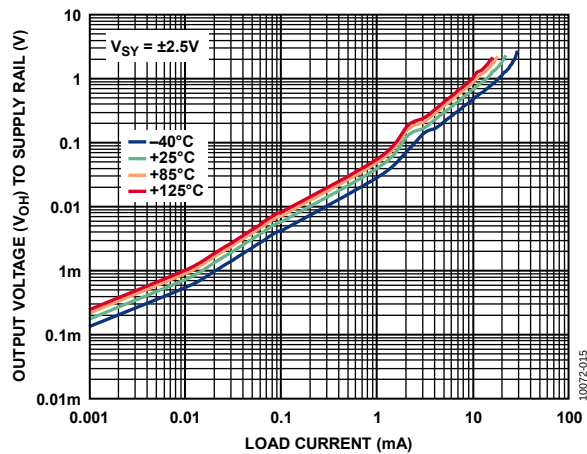
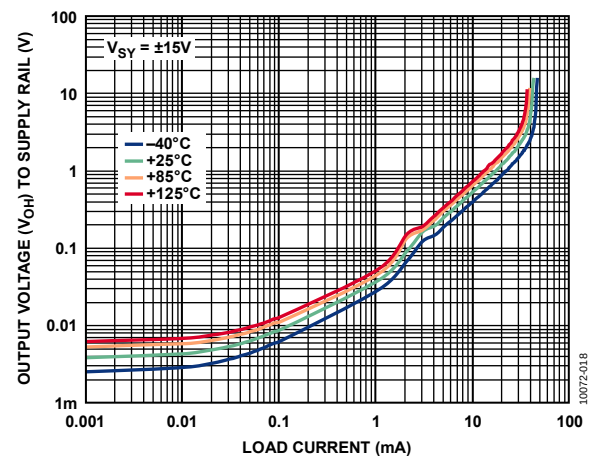
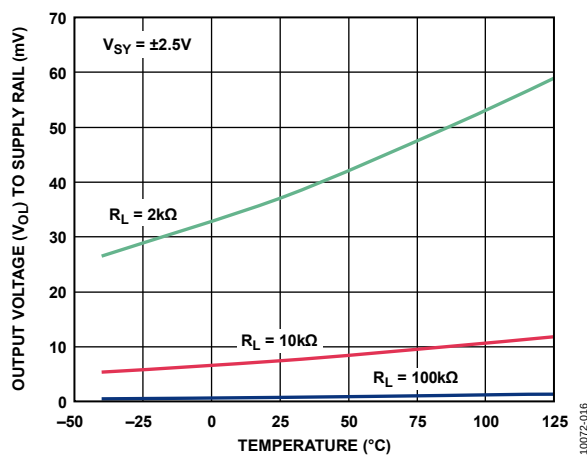
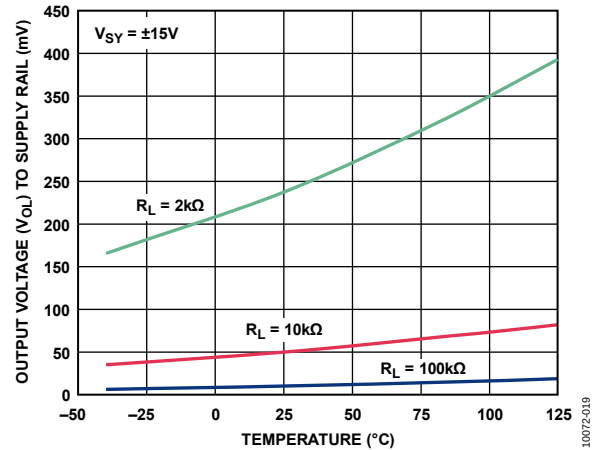


Figure 14. Input Bias Current vs. Common-Mode Voltage

Figure 15. Output Voltage (V_{OU}) to Supply Rail vs. Load CurrentFigure 18. Output Voltage (V_{OU}) to Supply Rail vs. Load CurrentFigure 16. Output Voltage (V_{OH}) to Supply Rail vs. Load CurrentFigure 19. Output Voltage (V_{OH}) to Supply Rail vs. Load CurrentFigure 17. Output Voltage (V_{OU}) to Supply Rail vs. TemperatureFigure 20. Output Voltage (V_{OU}) to Supply Rail vs. Temperature

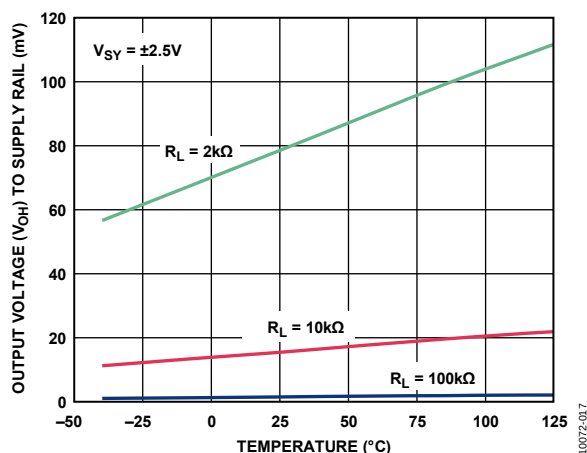


Figure 21. Output Voltage (V_{OH}) to Supply Rail vs. Temperature

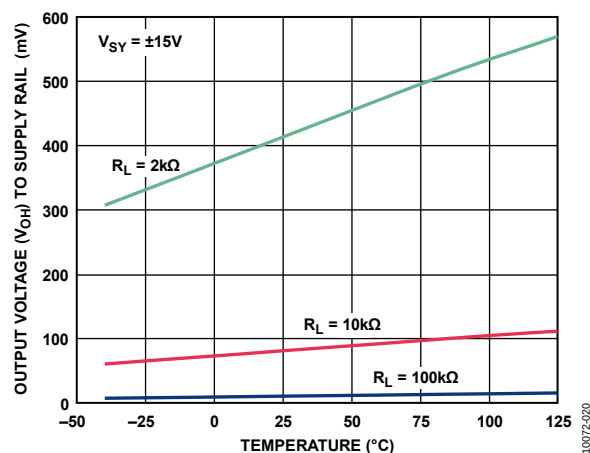


Figure 24. Output Voltage (V_{OH}) to Supply Rail vs. Temperature

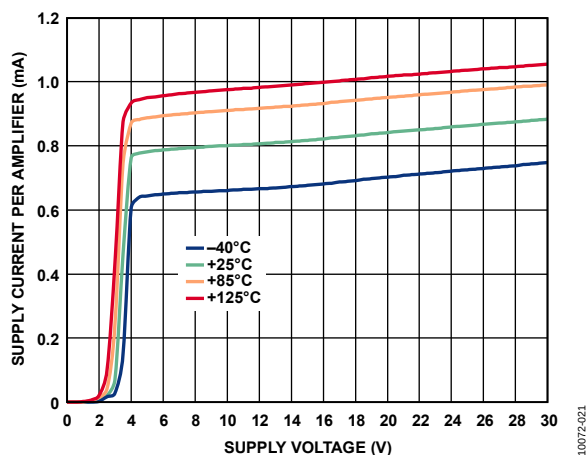


Figure 22. Supply Current vs. Supply Voltage

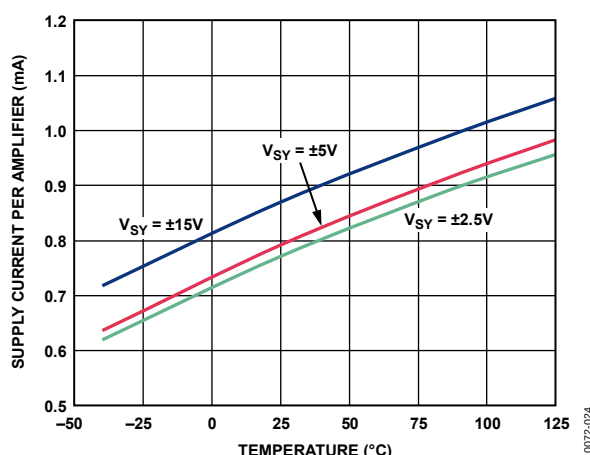


Figure 25. Supply Current vs. Temperature

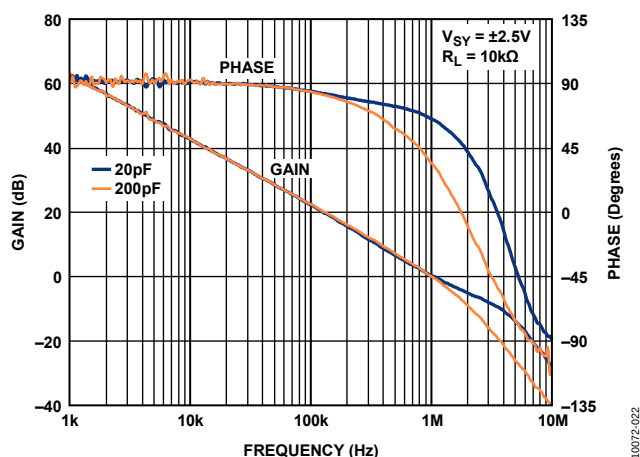


Figure 23. Open-Loop Gain and Phase vs. Frequency

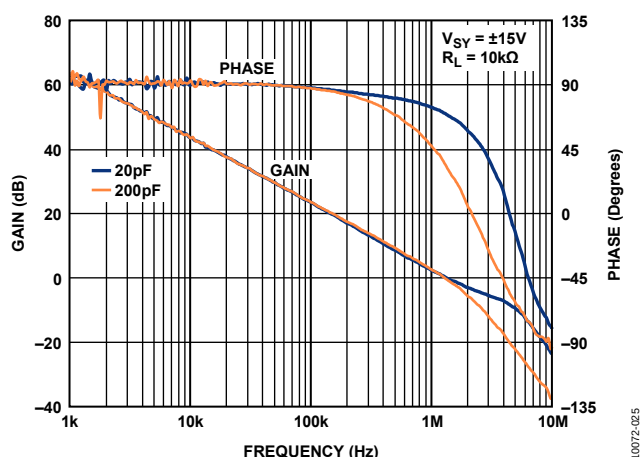


Figure 26. Open-Loop Gain and Phase vs. Frequency

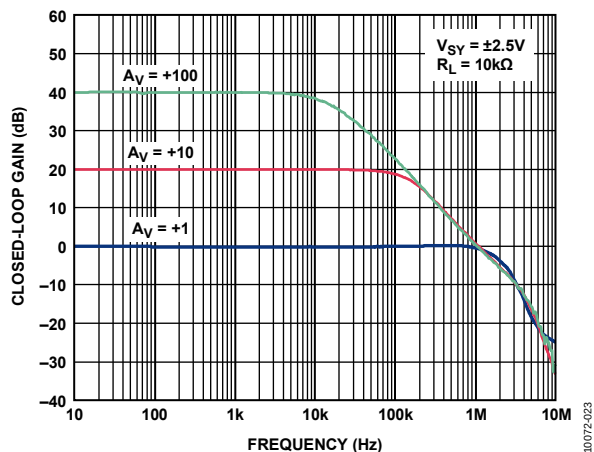


Figure 27. Closed-Loop Gain vs. Frequency

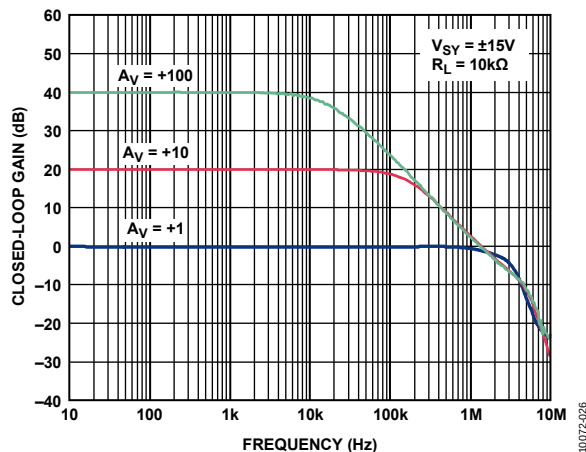


Figure 30. Closed-Loop Gain vs. Frequency

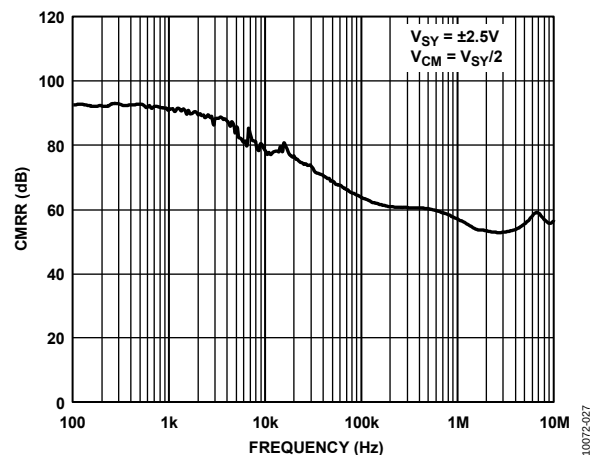


Figure 28. CMRR vs. Frequency

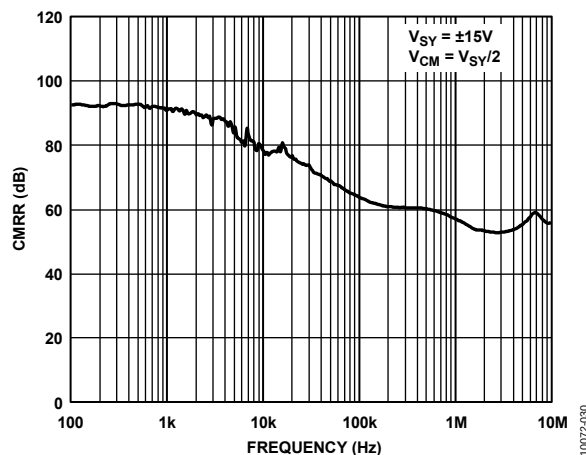


Figure 31. CMRR vs. Frequency

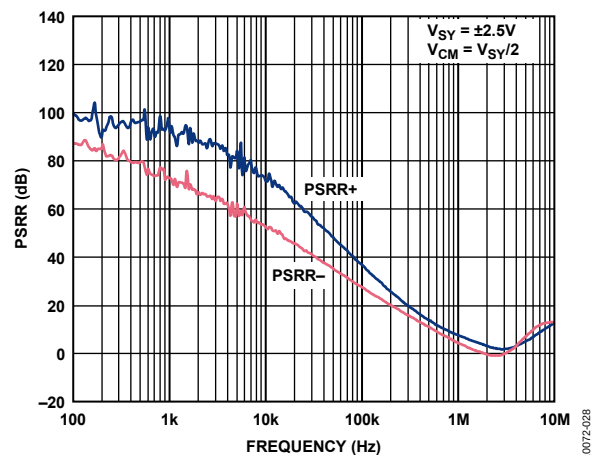


Figure 29. PSRR vs. Frequency

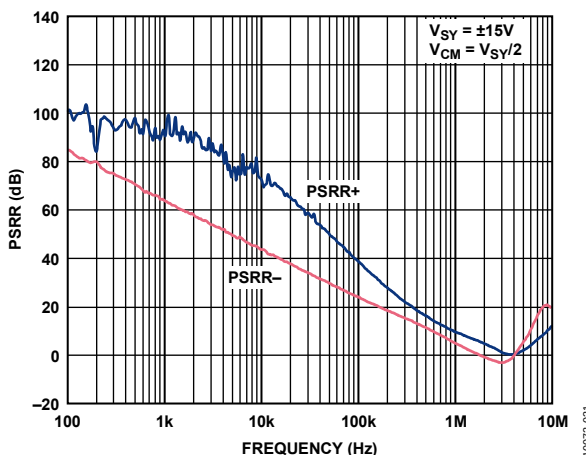


Figure 32. PSRR vs. Frequency

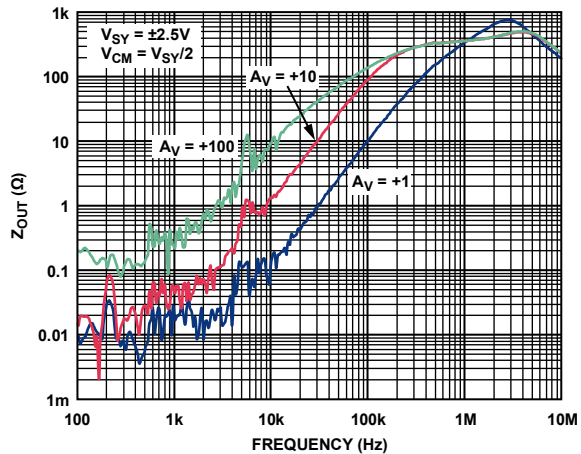


Figure 33. Closed-Loop Output Impedance vs. Frequency

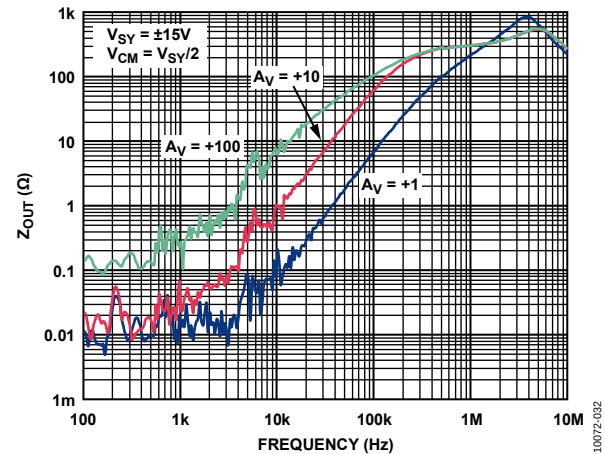


Figure 36. Closed-Loop Output Impedance vs. Frequency

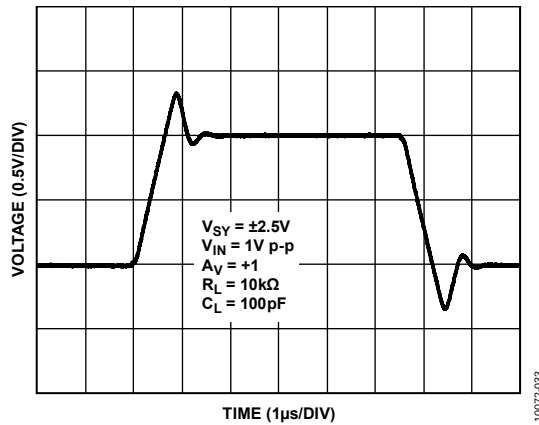


Figure 34. Large Signal Transient Response

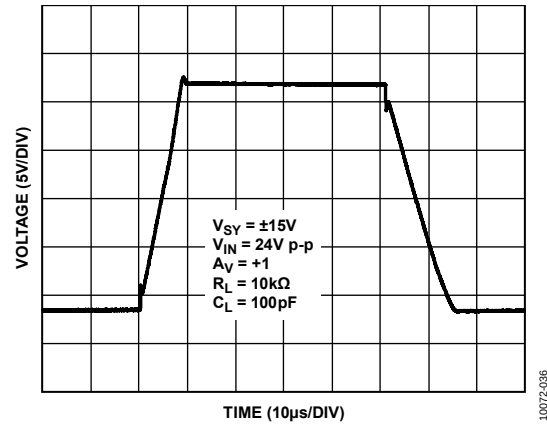


Figure 37. Large Signal Transient Response

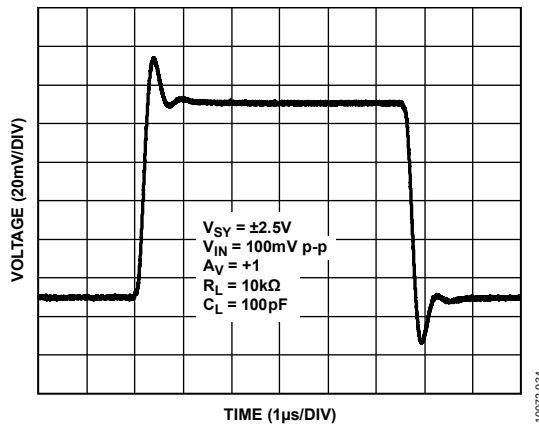


Figure 35. Small Signal Transient Response

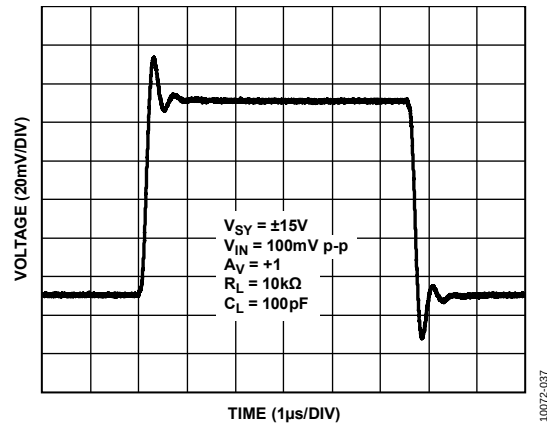


Figure 38. Small Signal Transient Response

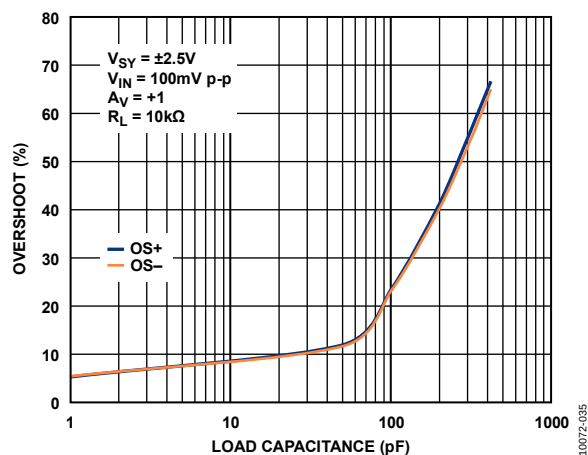


Figure 39. Small Signal Overshoot vs. Load Capacitance

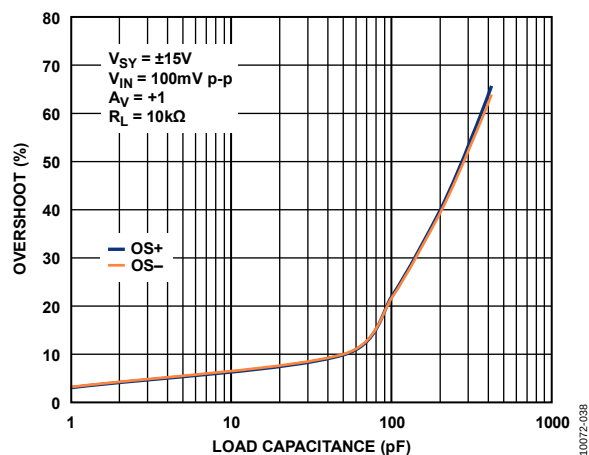


Figure 42. Small Signal Overshoot vs. Load Capacitance

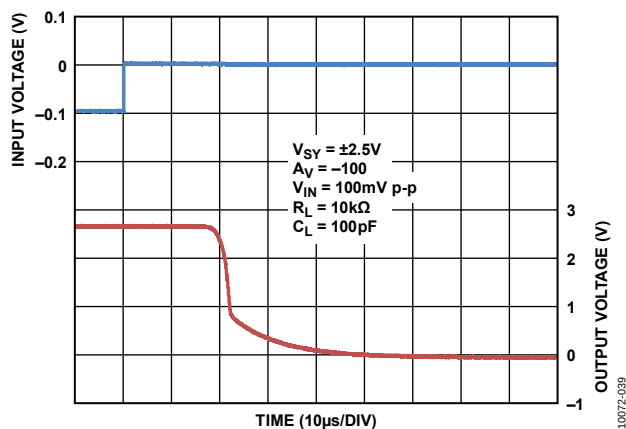


Figure 40. Positive Overload Recovery

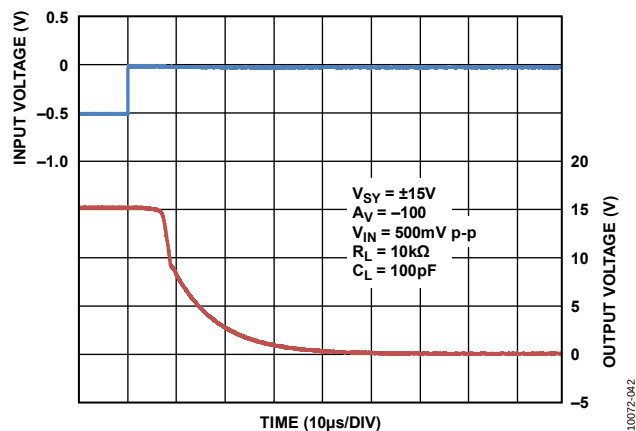


Figure 43. Positive Overload Recovery

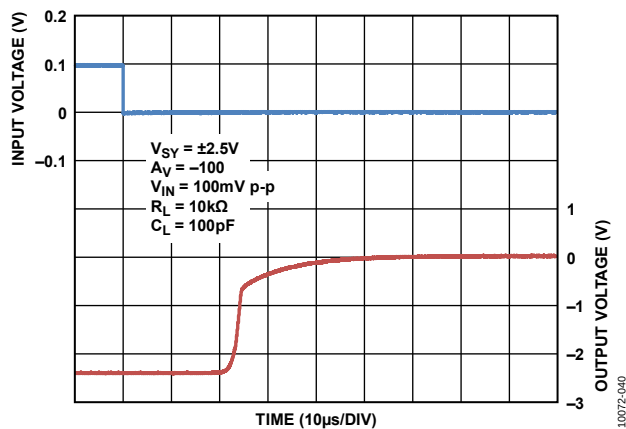


Figure 41. Negative Overload Recovery

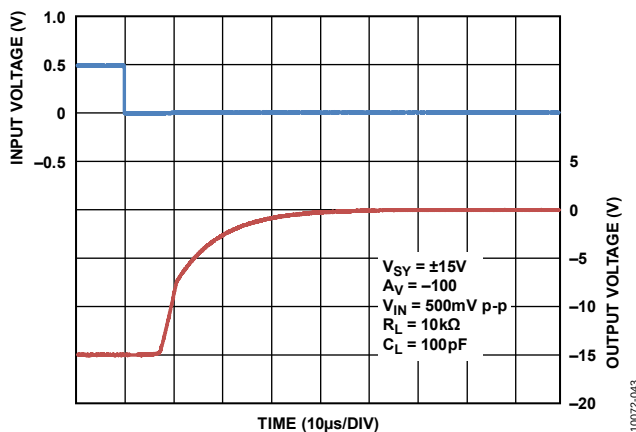


Figure 44. Negative Overload Recovery

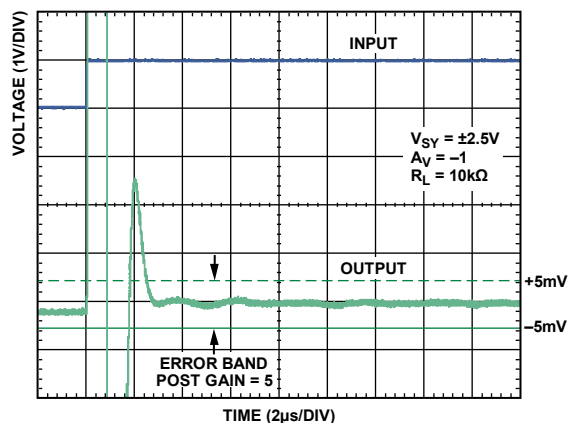


Figure 45. Positive Settling Time to 0.1%

10072-041

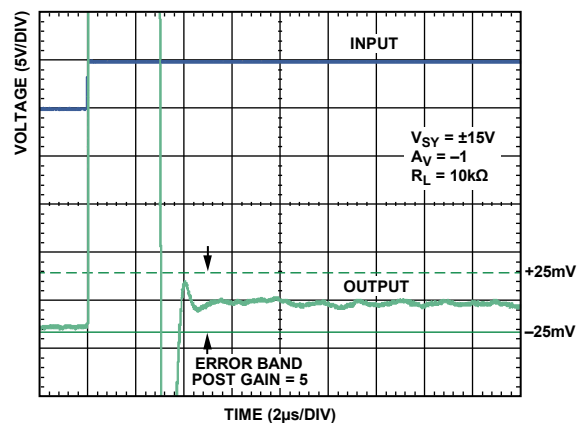


Figure 48. Positive Settling Time to 0.1%

10072-044

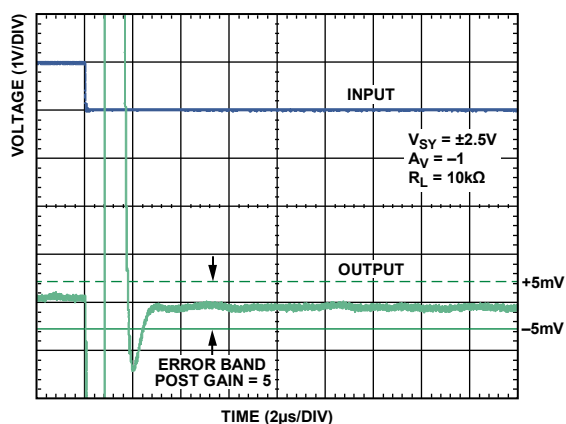


Figure 46. Negative Settling Time to 0.1%

10072-045

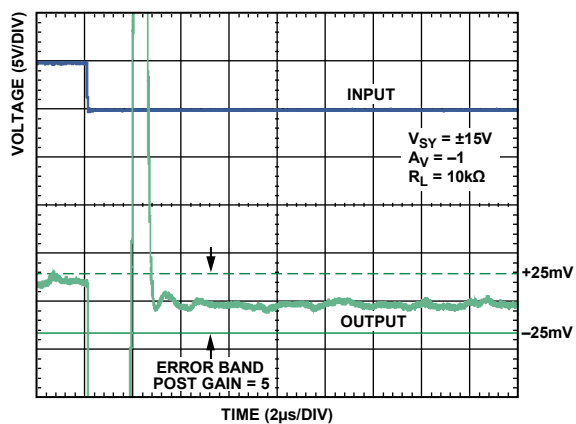


Figure 49. Negative Settling Time to 0.1%

10072-048

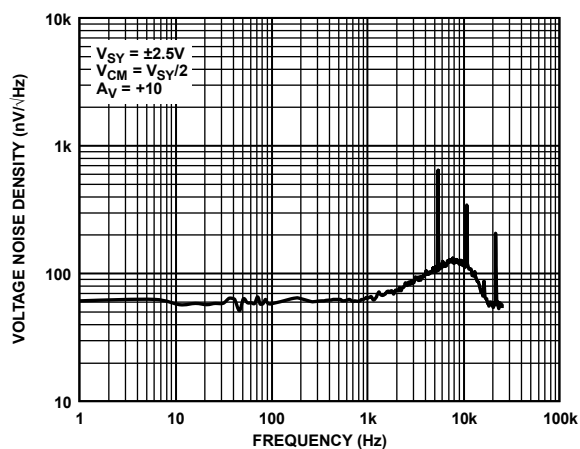


Figure 47. Voltage Noise Density vs. Frequency

10072-049

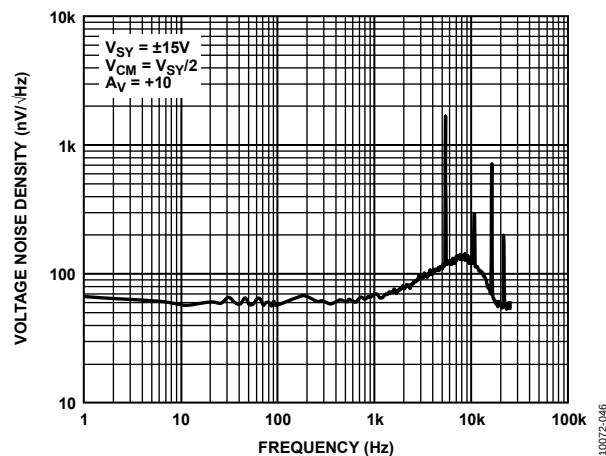


Figure 50. Voltage Noise Density vs. Frequency

10072-046

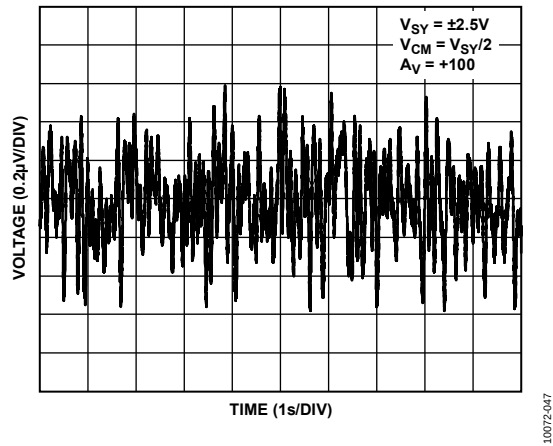


Figure 51. 0.1 Hz to 10 Hz Noise

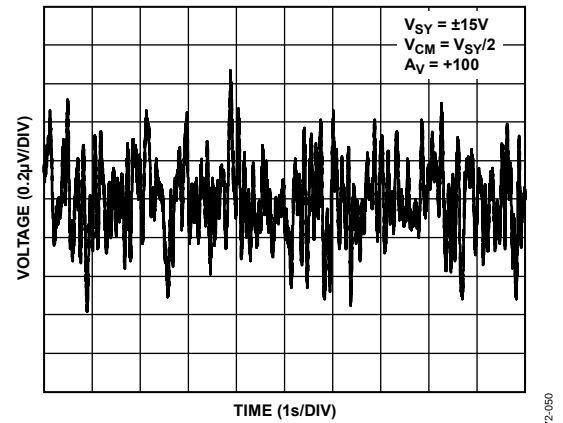


Figure 54. 0.1 Hz to 10 Hz Noise

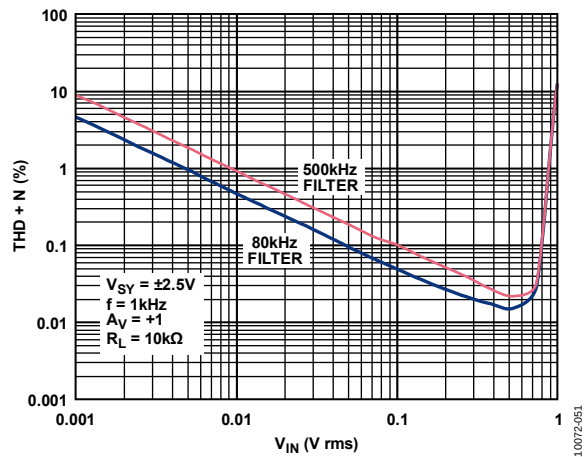


Figure 52. THD + N vs. Amplitude

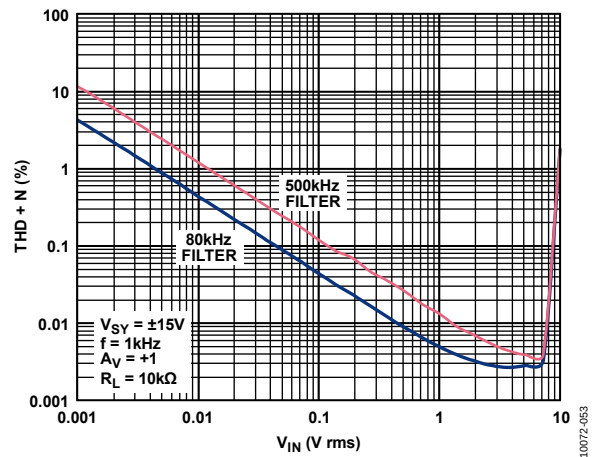


Figure 55. THD + N vs. Amplitude

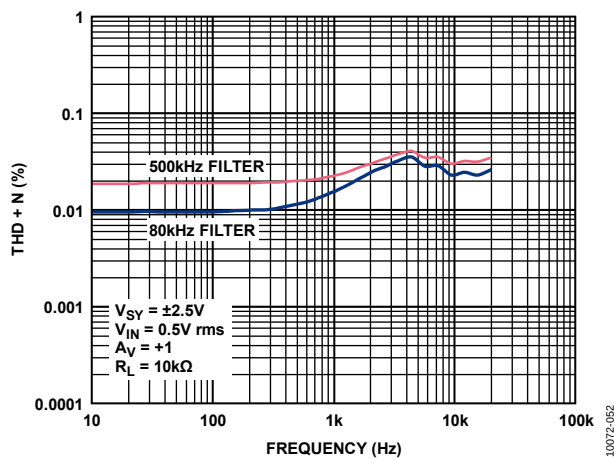


Figure 53. THD + N vs. Frequency

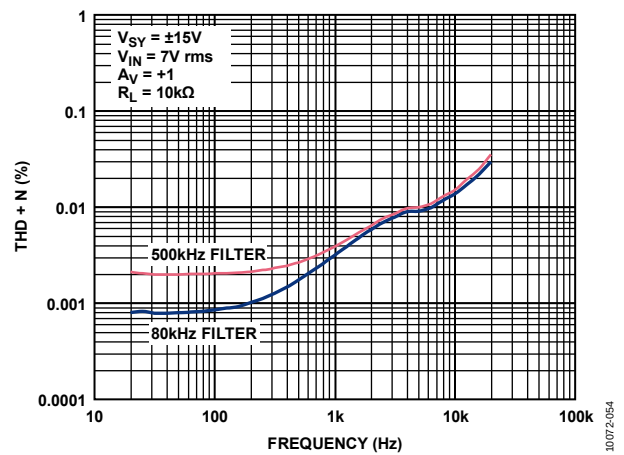


Figure 56. THD + N vs. Frequency

APPLICATIONS INFORMATION

The [ADA4638-1](#), with its wide supply voltage range of 4.5 V to 30 V, is a precision, rail-to-rail output, zero-drift operational amplifier that features a patented combination of auto-zeroing and chopping technique. This unique topology allows the [ADA4638-1](#) to maintain its low offset voltage over a wide temperature range and over its operating lifetime. This amplifier offers ultralow input offset voltage of 4.5 μ V maximum and an input offset voltage drift of 80 nV/ $^{\circ}$ C maximum. Offset voltage errors due to common-mode voltage swings and power supply variations are also corrected by the auto-zeroing and chopping technique, resulting in a superb typical CMRR figure of 142 dB and a PSRR figure of 143 dB at a $\pm$ 15 V supply voltage. With ultrahigh dc accuracy and no 1/f noise component, the [ADA4638-1](#) is ideal for high gain amplification of low level signals in dc or low frequency applications without the risk of excessive output voltage errors.

DIFFERENTIATION

Traditionally, zero-drift amplifiers are designed using either the auto-zeroing or chopping technique. Each technique has its benefits and drawbacks. Auto-zeroing usually results in low noise energy at the auto-zeroing frequency, at the expense of higher low frequency noise due to aliasing of wideband noise into the auto-zeroed frequency band. Chopping results in lower low frequency noise at the expense of larger noise energy at the chopping frequency. The [ADA4638-1](#) uses both auto-zeroing and chopping in a patented ping-pong arrangement to obtain lower low frequency noise together with lower energy at the chopping and auto-zeroing frequencies, maximizing the signal-to-noise ratio for the majority of applications. The relatively high chopping frequency of 16 kHz and auto-zeroing frequency of 8 kHz simplifies filter requirements for a wide, useful bandwidth.

THEORY OF OPERATION

Figure 57 shows the ADA4638-1 amplifier block diagram. The noninverting and inverting amplifier inputs are +IN and -IN, respectively. The transconductance amplifiers, A1 and A2, are the two input gain stages; the A3 and A4 transconductance amplifiers are the nulling amplifiers used to correct the offsets of A1 and A2, and A_{OUT} is the output amplifier. A four-phase cycle ($\phi 1$ to $\phi 4$) controls the switches. In Phase 1 ($\phi 1$), A1 is auto-zeroed where both the inputs of A1 are connected to +IN. A1 produces a differential output current of $V_{OS1} \times gm_1$, where V_{OS1} is the input offset voltage of A1, and gm_1 is the differential transconductance of A1. The outputs of A1 are then connected to the inputs and outputs of A3. A3 is designed to have an equivalent resistance of $1/gm_3$, where gm_3 is the transconductance of A3. The amplified version of V_{OS1} , which is $V_{OS1} \times gm_1/gm_3$, is stored on Capacitors C1 and C2. These capacitors, together with A3, are used to null out the offset of A1 when A1 amplifies the signal during the $\phi 3$ and $\phi 4$ phases.

While A1 is being auto-zeroed, A2 (nulled by A4, C3, and C4) is used for signal amplification. The ADA4638-1 differs from traditional auto-zero amplifiers in that the input offset voltage is also chopped during signal amplification. During $\phi 1$, +IN and -IN are applied to the noninverting and inverting inputs, respectively, of A2. However, during $\phi 2$, both the inputs and outputs of A2 are inverted, and the input offset voltage of A2 is chopped.

The combination of auto-zeroing and chopping offers two major benefits. First, any residual offset following the auto-zeroing process is reduced. During $\phi 1$, the output offset voltage of A2 is $+V_{OSA22}$ and during $\phi 2$, it is $-V_{OSA22}$, producing a theoretical average of zero. Second, the aliased noise spectrum density at dc due to auto-zeroing is modulated up to the chopping frequency, and the prechopped noise spectrum density at the chopping frequency is modulated down to dc. This noise transformation lowers the noise spectrum density at dc, thus making zero-drift amplifiers ideal for low frequency signal amplification.

During $\phi 3$ and $\phi 4$, the roles of A1 and A2 are reversed. A2 offset is nulled, and the input signal is chopped and amplified using A1.

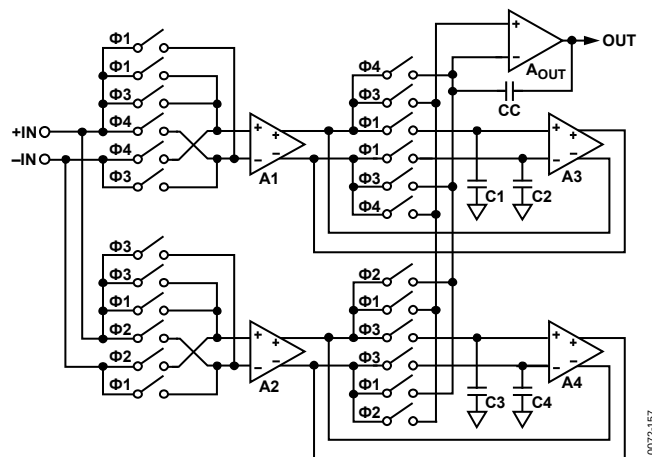


Figure 57. ADA4638-1 Amplifier Block Diagram

INPUT PROTECTION

The ADA4638-1 has internal ESD protection diodes that are connected between the inputs and each supply rail. These diodes protect the input transistors in the event of electrostatic discharge and are reverse-biased during normal operation. However, if either input exceeds one of the supply rails, these ESD diodes become forward-biased and large amounts of current begin to flow through them. Without current limiting, this excessive fault current causes permanent damage to the device. If the inputs are expected to be subject to overvoltage conditions, insert a resistor in series with each input to limit the input current to 10 mA maximum. However, consider the resistor thermal noise effect on the entire circuit.

NO OUTPUT PHASE REVERSAL

An undesired phenomenon, phase reversal (also known as phase inversion) occurs in many amplifiers when one or both of the inputs are driven beyond the specified input common-mode voltage range, in effect reversing the polarity of the output. In some cases, phase reversal can induce lockups and cause equipment damage as well as self destruction.

The ADA4638-1 has been carefully designed to prevent any output phase reversal, provided that both inputs are maintained within the supply voltages. If either one or both inputs may exceed either supply voltage, place resistors in series with the inputs to limit the current to less than 10 mA.

The ADA4638-1 features rail-to-rail output with a supply voltage from 4.5 V to 30 V. Figure 58 shows the input and output waveforms of the ADA4638-1 configured as a unity-gain buffer with a supply voltage of ± 15 V and a resistive load of 10 k Ω . The ADA4638-1 does not exhibit phase reversal.

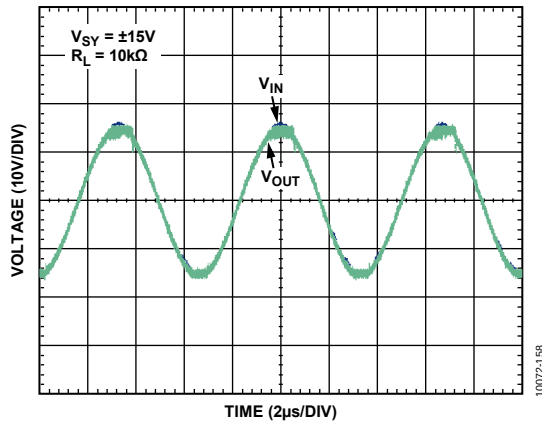


Figure 58. No Phase Reversal

NOISE CONSIDERATIONS

1/f Noise

1/f noise, also known as pink noise or flicker noise, is inherent in semiconductor devices and increases as frequency decreases. At low frequency, 1/f noise is a major noise contributor and causes a significant output voltage offset when amplified by the noise gain of the circuit. However, the ADA4638-1 eliminates the 1/f noise internally, thus making it an excellent choice for dc or low frequency high precision applications. The 0.1 Hz to 10 Hz voltage noise is only 1.2 μ V p-p at ± 15 V of supply voltage.

The low frequency 1/f noise appears as a slow varying offset to the ADA4638-1 and is greatly reduced by the combination of auto-zeroing and chopping technique. This allows the ADA4638-1 to have a much lower noise at dc and low frequency in comparison to standard low noise amplifiers that are susceptible to 1/f noise. Figure 47 and Figure 50 show the voltage noise density of the ADA4638-1 with no 1/f noise.

COMPARATOR OPERATION

Op amps are designed to operate in a closed-loop configuration with feedback from its output to its inverting input. Figure 59 shows the ADA4638-1 configured as a voltage follower with an input voltage, which is kept at midpoint of the power supplies. A1 and A2 indicate the placement of ammeters to measure supply currents. I_{SY+} refers to the current flowing into the positive supply pin of the op amp, and I_{SY-} refers to the current flowing out of the negative supply pin of the op amp. From Figure 60, as expected in normal operating condition, the current flowing into the op amp is equivalent to the current flowing out of the op amp, where $I_{SY+} = I_{SY-}$.

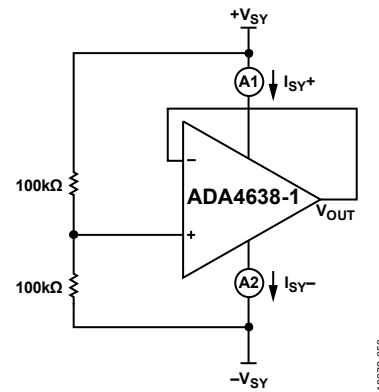


Figure 59. Voltage Follower

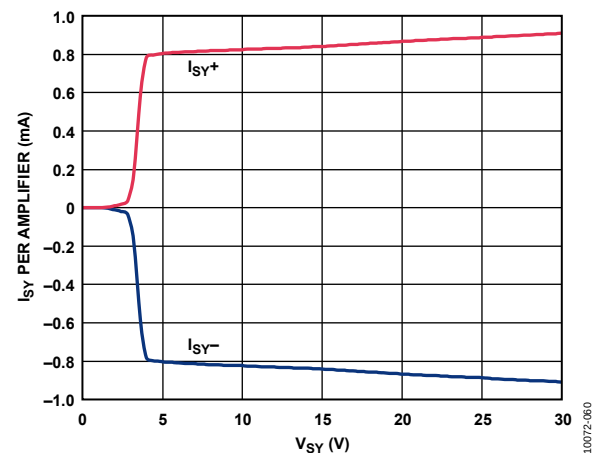


Figure 60. Supply Current vs. Supply Voltage (Voltage Follower)

In contrast to op amps, comparators are designed to work in an open-loop configuration and to drive logic circuits. Although op amps are different from comparators, occasionally an unused section of a dual op amp is used as a comparator to save board space and cost; however, this is not recommended.

Figure 61 and Figure 62 show the ADA4638-1 configured as a comparator, with resistors R_{IN1} and R_{IN2} in series with the input pins.

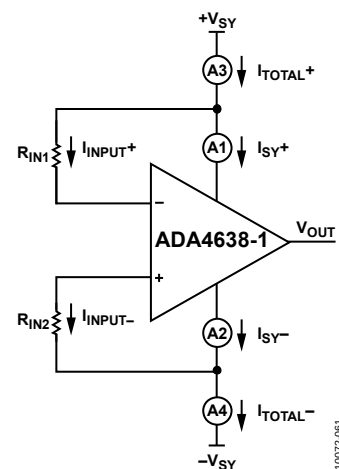


Figure 61. Comparator A

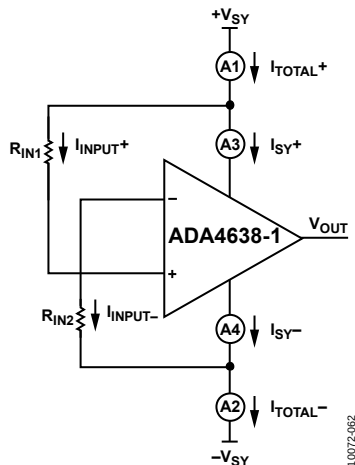


Figure 62. Comparator B

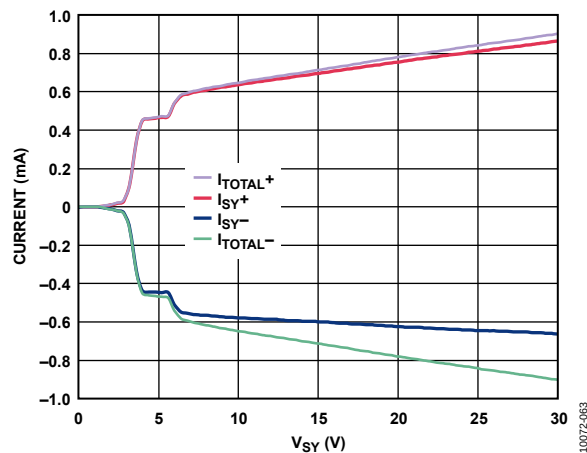
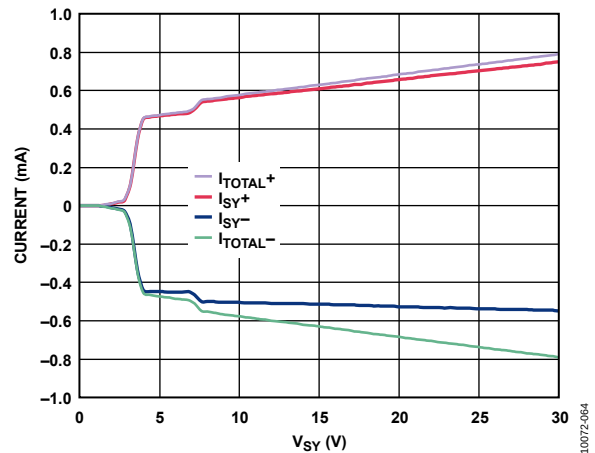
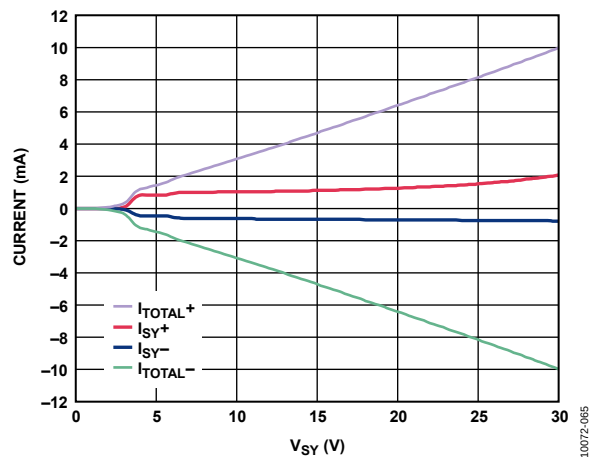
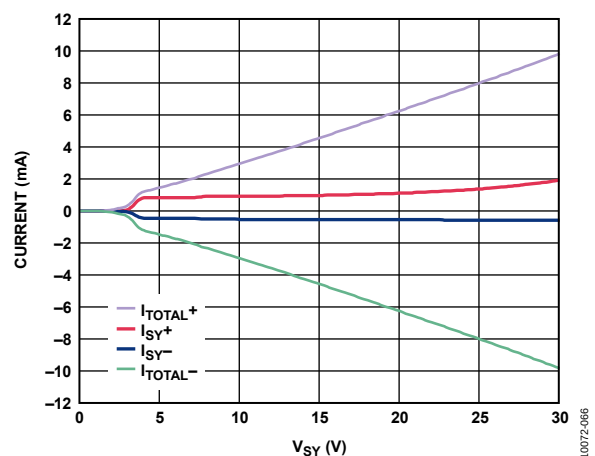
Figure 63 and Figure 64 show the total supply current of the system, I_{TOTAL} , and the actual currents, I_{SY} , that flow into and out of the supply pins of the ADA4638-1. With $R_{IN1} = R_{IN2} = 100\text{ k}\Omega$ and supply voltage of 30 V, the total supply current of the system is 800 μA to 900 μA .

With smaller input series resistors, total supply current of the system increases much more. Figure 65 and Figure 66 show the supply currents with $R_{IN1} = R_{IN2} = 0\text{ }\Omega$. The total current of the system increases to 10 mA.

$$I_{TOTAL} = I_{SY} + I_{INPUT}$$

Note that, at 30 V of supply voltage, 8 mA to 9 mA of current flows through the input pins. This is undesirable. The ADA4638-1 is not recommended to be used as a comparator. If absolutely necessary, place resistors in series with the inputs of the amplifier to limit input current to less than 10 mA.

For more details on op amps as comparators, refer to the AN-849 Application Note, *Using Op Amps as Comparators*.

Figure 63. Supply Current vs. Supply Voltage
(Comparator A, $R_{IN1} = R_{IN2} = 100\text{ k}\Omega$)Figure 64. Supply Current vs. Supply Voltage
(Comparator B, $R_{IN1} = R_{IN2} = 100\text{ k}\Omega$)Figure 65. Supply Current vs. Supply Voltage
(Comparator A, $R_{IN1} = R_{IN2} = 0\text{ k}\Omega$)Figure 66. Supply Current vs. Supply Voltage
(Comparator B, $R_{IN1} = R_{IN2} = 0\text{ k}\Omega$)

PRECISION LOW-SIDE CURRENT SHUNT SENSOR

Many applications require the sensing of signals near the positive or negative rails. Current shunt sensors are one such application and are mostly used for feedback control systems. They are also used in a variety of other applications, including power metering, battery fuel gauging and feedback controls in electrical power steering. In such application, it is desirable to use a shunt with very low resistance to minimize series voltage drop. This not only minimizes wasted power, but also allows the measurement of high currents while saving power. A typical shunt may be 100 mΩ. At a measured current of 1 A, the voltage produced from the shunt is 100 mV, and the amplifier error sources are not critical. However, at low measured current in the 1 mA range, the 100 μV generated across the shunt demands a very low offset voltage and drift amplifier to maintain absolute accuracy. The unique attributes of a zero-drift amplifier provides a solution. The ADA4638-1, with its input common-mode voltage that includes the lower supply rail, can be used for implementing low-side current shunt sensors.

Figure 67 shows a low-side current sensing circuit using the ADA4638-1. The ADA4638-1 is configured as a difference amplifier with a gain of 1000. Although the ADA4638-1 has high common-mode rejection, the CMR of the system is limited by the external resistors. Therefore, the key to high CMR for the system are resistors that are well matched from both the resistive ratio and relative drift, where $R1/R2 = R3/R4$. The resistors are important in determining the performance over manufacturing tolerances, time, and temperature.

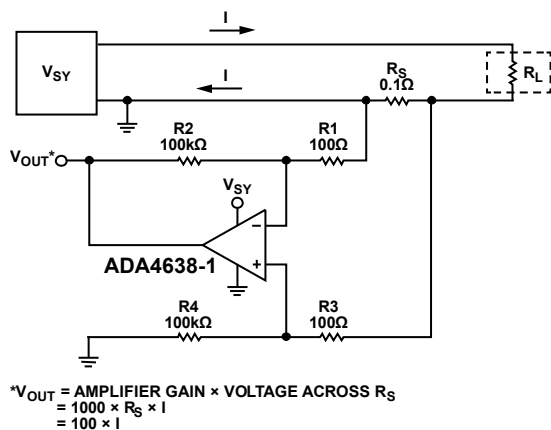


Figure 67. Low-Side Current Sensing Circuit

PRINTED CIRCUIT BOARD LAYOUT

The ADA4638-1 is a high precision device with ultralow offset voltage and offset voltage drift. Therefore, care must be taken in the design of the printed circuit board (PCB) layout to achieve optimum performance of the ADA4638-1 at board level.

To avoid leakage currents, keep the surface of the board clean and free of moisture. Coating the board surface creates a barrier to moisture accumulation and reduces parasitic resistance on the board.

Properly bypassing the power supplies and keeping the supply traces short minimizes power supply disturbances caused by output current variation. Connect bypass capacitors as close as possible to the device supply pins. Stray capacitances are a concern at the outputs and the inputs of the amplifier. It is recommended that signal traces be kept at a distance of at least 5 mm from supply lines to minimize coupling.

A potential source of offset error is the Seebeck voltage on the circuit board. The Seebeck voltage occurs at the junction of two dissimilar metals and is a function of the temperature of the junction. The most common metallic junctions on a circuit board are solder-to-board trace and solder-to-component lead. Figure 68 shows a cross section of a surface-mount component soldered to a PCB. A variation in temperature across the board (where $T_{A1} \neq T_{A2}$) causes a mismatch in the Seebeck voltages at the solder joints thereby resulting in thermal voltage errors that degrade the performance of the ultralow offset voltage of the ADA4638-1.

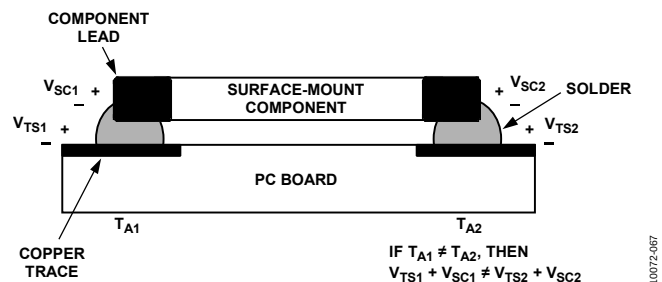
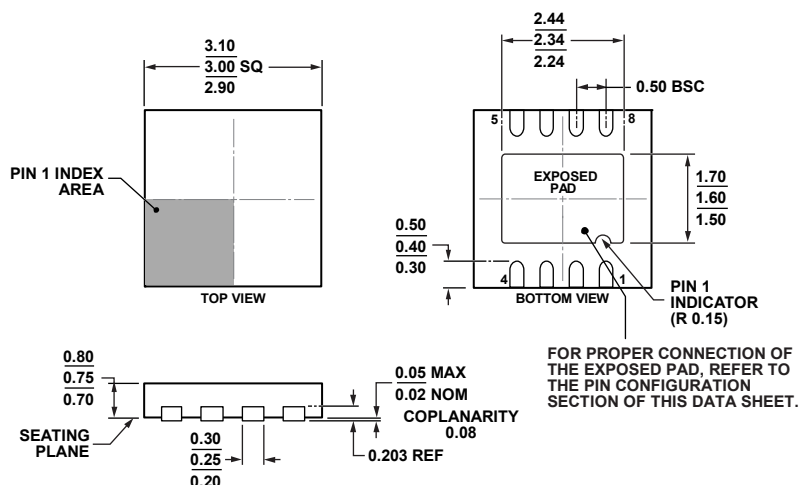


Figure 68. Mismatch in Seebeck Voltages Causes Seebeck Voltage Error

To minimize these thermocouple effects, orient resistors so that heat sources warm both ends equally. Where possible, the input signal paths should contain matching numbers and types of components to match the number and type of thermocouple junctions. For example, dummy components, such as zero value resistors, can be used to match the thermoelectric error source (real resistors in the opposite input path). Place matching components in close proximity and orient them in the same manner to ensure equal Seebeck voltages, thus cancelling thermal errors. Additionally, use leads that are of equal length to keep thermal conduction in equilibrium. Keep heat sources on the PCB as far away from amplifier input circuitry as is practical.

It is highly recommended to use a ground plane. A ground plane helps distribute heat throughout the board, maintains a constant temperature across the board, and reduces EMI noise pickup.

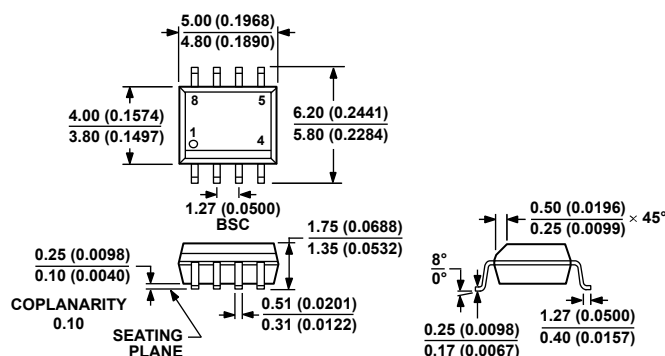
OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-229-WEED

Figure 69. 8-Lead Lead Frame Chip Scale Package [LFCSP_WD]
3 mm × 3 mm Body, Very Very Thin, Dual Lead
(CP-8-11)

Dimensions shown in millimeters



COMPLIANT TO JEDEC STANDARDS MS-012-AA

CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS
(IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR
REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 70. 8-Lead Standard Small Outline Package [SOIC_N]
Narrow Body
(R-8)

Dimensions shown in millimeters and (inches)

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option	Branding
ADA4638-1ACPZ-R7	−40°C to +125°C	8-Lead Lead Frame Chip Scale Package [LFCSP_WD]	CP-8-11	A2W
ADA4638-1ACPZ-RL	−40°C to +125°C	8-Lead Lead Frame Chip Scale Package [LFCSP_WD]	CP-8-11	A2W
ADA4638-1ARZ	−40°C to +125°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8	
ADA4638-1ARZ-R7	−40°C to +125°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8	
ADA4638-1ARZ-RL	−40°C to +125°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8	

¹ Z = RoHS Compliant Part.

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