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## REVISION HISTORY

3/2017—Revision 0: Initial Version

## SPECIFICATIONS

## ±5 V SUPPLY

$T_A = 25^\circ\text{C}$ , reference voltage ( $V_{REF}$ ) = 0 V, feedback resistor ( $R_F$ ) = gain resistor ( $R_G$ ) = 1 k $\Omega$  (see Figure 38), unless otherwise noted.

Table 1.

| Parameter                           | Test Conditions/Comments   | Min       | Typ       | Max | Unit                         |
|-------------------------------------|--|-----------|-----------|-----|------------------------------|
| DYNAMIC PERFORMANCE                 |  |           |           |     |                              |
| Gain Bandwidth                      | $R_{IN1} = 1\text{ k}\Omega$ , $R_{IN2} = 1\text{ k}\Omega$ (see Figure 38),<br>output voltage ( $V_{OUT}$ ) = 0.2 V p-p                     |           | 25        |     | MHz                          |
| Slew Rate                           | Gain = 1, $V_{OUT} = 2\text{ V}$ step  |           | 18        |     | V/ $\mu\text{s}$             |
| Channel Separation                  | 1 kHz to 10 kHz, input voltage ( $V_{IN}$ ) = 5 V p-p,<br>$R_L = 600\text{ }\Omega$ , 32 $\Omega$ , 16 $\Omega$                              |           | –140      |     | dB                           |
| DISTORTION PERFORMANCE              |  |           |           |     |                              |
| THD + N                             | 1 kHz, $V_{OUT} = 2\text{ V rms}$ , low-pass filter = 80 kHz,<br>$R_L = 600\text{ }\Omega$   |           | –122      |     | dB                           |
|                                     | 1 kHz, $V_{OUT} = 2\text{ V rms}$ , low-pass filter = 80 kHz,<br>$R_L = 32\text{ }\Omega$  |           | –121      |     | dB                           |
|                                     | 1 kHz, $V_{OUT} = 1.6\text{ V rms}$ , low-pass filter =<br>80 kHz, $R_L = 16\text{ }\Omega$  |           | –118      |     | dB                           |
|                                     | SMPTE two-tone, 4:1 (60 Hz and 7 kHz),<br>gain = 1, $V_{OUT} = 2\text{ V rms}$ , $R_L = 600\text{ }\Omega$ , 90 kHz<br>measurement bandwidth |           | –125      |     | dB                           |
|                                     | CCIF two-tone (19 kHz and 20 kHz), gain = 1,<br>$V_{OUT} = 2\text{ V rms}$ , $R_L = 600\text{ }\Omega$ , 90 kHz<br>measurement bandwidth     |           | –131      |     | dB                           |
| NOISE PERFORMANCE                   |  |           |           |     |                              |
| A-Weight Output Noise               | $f = 10\text{ Hz to }22\text{ kHz}$  |           | 1.8       |     | $\mu\text{V rms}$            |
| Input Voltage Noise                 | $f = 10\text{ Hz}$   |           | 5.2       |     | nV/ $\sqrt{\text{Hz}}$       |
|                                     | $f = 100\text{ kHz}$   |           | 3.6       |     | nV/ $\sqrt{\text{Hz}}$       |
| Input Current Noise                 | $f = 10\text{ Hz}$   |           | 10        |     | pA/ $\sqrt{\text{Hz}}$       |
|                                     | $f = 100\text{ kHz}$   |           | 1.2       |     | pA/ $\sqrt{\text{Hz}}$       |
| DC PERFORMANCE                      |  |           |           |     |                              |
| Output Offset Voltage               |  |           | 90        | 250 | $\mu\text{V}$                |
| Output Offset Voltage Drift         |  |           | 1.5       | 7.5 | $\mu\text{V}/^\circ\text{C}$ |
| Input Bias Current                  |  | –2.4      | –1.8      | –1  | $\mu\text{A}$                |
| Input Offset Current                |  |           | 60        | 320 | nA                           |
| Open-Loop Gain                      | $V_{OUT} = \pm 2.3\text{ V}$ , $R_L = 600\text{ }\Omega$   | 107       | 120       |     | dB                           |
| INPUT CHARACTERISTICS               |  |           |           |     |                              |
| Input Capacitance                   |  |           | 2         |     | pF                           |
| Input Common-Mode Voltage Range     | $I_{DIFF} = 3\text{ mA}$   |           | $\pm 1.5$ |     | V                            |
| Common-Mode Rejection               | $V_{CM} = \pm 1\text{ V}$  | 113       | 140       |     | dB                           |
| $V_{REF1}/V_{REF2}$                 |  |           |           |     |                              |
| Open Circuit Voltage                | Referenced to ground   |           | 1.45      |     | V                            |
| Output Current                      |  |           | 15        |     | $\mu\text{A}$                |
| OUTPUT CHARACTERISTICS              |  |           |           |     |                              |
| Output Voltage Swing<br>Each Output | $R_L = 600\text{ }\Omega$  | $\pm 3.3$ | $\pm 3.4$ |     | V                            |
|                                     | $R_L = 32\text{ }\Omega$   | $\pm 2.8$ | $\pm 2.9$ |     | V                            |
|                                     | $R_L = 16\text{ }\Omega$   | $\pm 2.0$ | $\pm 2.6$ |     | V                            |
| Output Current                      | $R_L = 16\text{ }\Omega$ , rms voltage ( $V_{RMS}$ ) = 1.6 V,<br>THD + N = –118 dB   |           | 100       |     | mA rms                       |
| Short-Circuit Current               | $R_L = 10\text{ }\Omega$ ; source/sink   |           | +240/–190 |     | mA                           |
| Closed-Loop Output Impedance        | 10 Hz to 20 kHz  |           | 0.04      |     | $\Omega$                     |

| Parameter                         | Test Conditions/Comments   | Min | Typ                  | Max  | Unit          |
|-----------------------------------|--|-----|----------------------|------|---------------|
| POWER SUPPLY                      |  |     |                      |      |               |
| Operating Range                   |  |     | $\pm 3.3$ to $\pm 6$ |      | V             |
| Quiescent Current                 | $V_{SD} = V_{SD2} = V_{CCx}$ , $V_{REF} = 0$ V, per channel<br>$-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ | 3   |                      | 3.35 | mA            |
|                                   |  | 3.1 |                      |      | mA            |
| Quiescent Current Power-Down Mode | $V_{SD} = 0$ V, $V_{SD2} = V_{CCx}$ , per channel  | 1.4 |                      |      | mA            |
|                                   | $V_{SD} = V_{SD2} = 0$ V, per channel  | 15  |                      |      | $\mu\text{A}$ |
| DC Power Supply Rejection Ratio   | Supply voltage ( $V_{SY}$ ) = 3.3 V to 5.5 V   | 115 | 140                  |      | dB            |
| AC Power Supply Rejection Ratio   | 20 kHz   |     | 87                   |      | dB            |
| POWER-DOWN INPUTS                 |  |     |                      |      |               |
| Logic High                        | Chip on, referenced to ground  |     | $>1.5$               |      | V             |
| Logic Low                         | Chip off, referenced to ground   |     | $<0.75$              |      | V             |

 **$\pm 3.3$  V SUPPLY**

$T_A = 25^{\circ}\text{C}$ ,  $V_{REF} = 0$  V,  $R_F = R_G = 1$  k $\Omega$  (see Figure 38), unless otherwise noted.

Table 2.

| Parameter                       | Test Conditions/Comments   | Min       | Typ        | Max | Unit                           |
|---------------------------------|--|-----------|------------|-----|--------------------------------|
| DYNAMIC PERFORMANCE             |  |           |            |     |                                |
| Gain Bandwidth                  | $R_{IN1} = 1$ k $\Omega$ , $R_{IN2} = 1$ k $\Omega$ (see Figure 38), $V_{OUT} = 0.2$ V p-p |           | 25         |     | MHz                            |
| Slew Rate                       | Gain = 1, $V_{OUT} = 2$ V step   |           | 14         |     | V/ $\mu\text{s}$               |
| Channel Separation              | 1 kHz to 10 kHz, $V_{IN} = 1$ V p-p, $R_L = 600$ $\Omega$ , 32 $\Omega$ , and 16 $\Omega$  |           | -140       |     | dB                             |
| DISTORTION PERFORMANCE          |  |           |            |     |                                |
| THD + N                         | 1 kHz, $V_{OUT} = 1$ V rms, low-pass filter = 80 kHz, $R_L = 600$ $\Omega$                 |           | -116       |     | dB                             |
|                                 | 1 kHz, $V_{OUT} = 1$ V rms, low-pass filter = 80 kHz, $R_L = 32$ $\Omega$                  |           | -116       |     | dB                             |
|                                 | 1 kHz, $V_{OUT} = 0.9$ V rms, low-pass filter = 80 kHz, $R_L = 16$ $\Omega$                |           | -111       |     | dB                             |
| NOISE PERFORMANCE               |  |           |            |     |                                |
| A-Weight Output Noise           | $f = 10$ Hz to 22 kHz  |           | 1.8        |     | $\mu\text{V rms}$              |
| Input Voltage Noise             | $f = 10$ Hz  |           | 5.2        |     | nV/ $\sqrt{\text{Hz}}$         |
|                                 | $f = 100$ kHz  |           | 3.6        |     | nV/ $\sqrt{\text{Hz}}$         |
| Input Current Noise             | $f = 10$ Hz  |           | 10         |     | pA/ $\sqrt{\text{Hz}}$         |
|                                 | $f = 100$ kHz  |           | 1.2        |     | pA/ $\sqrt{\text{Hz}}$         |
| DC PERFORMANCE                  |  |           |            |     |                                |
| Output Offset Voltage           |  |           | 90         | 250 | $\mu\text{V}$                  |
| Output Offset Voltage Drift     |  |           | 1.5        | 7.5 | $\mu\text{V}/^{\circ}\text{C}$ |
| Input Bias Current              |  | -2.4      | -1.8       | -1  | $\mu\text{A}$                  |
| Input Offset Current            |  |           | 60         | 300 | nA                             |
| Open-Loop Gain                  | $V_{OUT} = \pm 2.3$ V, $R_L = 600$ $\Omega$  | 106       | 120        |     | dB                             |
| INPUT CHARACTERISTICS           |  |           |            |     |                                |
| Input Capacitance               |  |           | 2          |     | pF                             |
| Input Common-Mode Voltage Range | Differential current ( $I_{DIFF}$ ) = 3 mA   |           | $\pm 0.3$  |     | V                              |
| Common-Mode Rejection           | Common-mode voltage ( $V_{CM}$ ) = $\pm 0.3$ V   | 109       | 135        |     | dB                             |
| $V_{REF1}/V_{REF2}$             |  |           |            |     | V                              |
| Open Circuit Voltage            | Referenced to ground   |           | 1.45       |     | V                              |
| Output Current                  |  |           | 15         |     | $\mu\text{A}$                  |
| OUTPUT CHARACTERISTICS          |  |           |            |     |                                |
| Output Voltage Swing            |  |           |            |     |                                |
| Each Output                     | $R_L = 600$ $\Omega$   | $\pm 1.6$ | $\pm 1.7$  |     | V                              |
|                                 | $R_L = 32$ $\Omega$  | $\pm 1.4$ | $\pm 1.45$ |     | V                              |
|                                 | $R_L = 16$ $\Omega$  | $\pm 1.2$ | $\pm 1.4$  |     | V                              |
| Output Current                  | $R_L = 16$ $\Omega$ , $V_{RMS} = 0.9$ V, THD + N = -111 dB                                 |           | 56         |     | mA rms                         |
| Short-Circuit Current           | $R_L = 10$ $\Omega$  |           | +115/-120  |     | mA                             |
| Closed-Loop Output Impedance    | 10 Hz to 20 kHz  |           | 0.04       |     | $\Omega$                       |

| Parameter                         | Test Conditions/Comments   | Min | Typ        | Max  | Unit |
|-----------------------------------|--|-----|------------|------|------|
| POWER SUPPLY                      |  |     |            |      |      |
| Operating Range                   |  |     | ±3.3 to ±6 |      | V    |
| Quiescent Current                 | $V_{SD} = V_{SD2} = V_{CCx}$ , $V_{REF} = 0$ V, per channel<br>$-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ |     | 2.9        | 3.35 | mA   |
|                                   |  |     | 3.0        |      | mA   |
| Quiescent Current Power-Down Mode | $V_{SD} = 0$ V, $V_{SD2} = V_{CCx}$  |     | 1.3        |      | mA   |
|                                   | $V_{SD} = V_{SD2} = 0$ V   |     | 10         |      | μA   |
| DC Power Supply Rejection Ratio   | $V_{SY} = 3.3$ V to 5.5 V  | 115 | 140        |      | dB   |
| AC Power Supply Rejection Ratio   | 20 kHz   |     | 85         |      | dB   |
| POWER-DOWN INPUTS                 |  |     |            |      |      |
| Logic High                        | Chip on, referenced to ground  |     | >1.5       |      | V    |
| Logic Low                         | Chip off, referenced to ground   |     | <0.75      |      | V    |

## ABSOLUTE MAXIMUM RATINGS

Table 3.

| Parameter                           | Rating                     |
|-------------------------------------|----------------------------|
| Supply Voltage                      |                            |
| Single Supply                       | 12.6 V                     |
| Dual Supply                         | ±6.3 V                     |
| Exposed Pad Voltage                 | –V <sub>SY</sub> or ground |
| Storage Temperature Range           | –65°C to +125°C            |
| Operating Temperature Range         | –40°C to +85°C             |
| Lead Temperature (Soldering 10 sec) | 300°C                      |
| Junction Temperature                | 150°C                      |

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

### THERMAL RESISTANCE

Thermal performance is directly linked to PCB design and operating environment. Careful attention to PCB thermal design is required. The values in Table 4 were obtained per JEDEC standard JESD51-12.

Table 4. Thermal Resistance

| Package Type | θ <sub>JA</sub> | θ <sub>JC</sub> | Unit |
|--------------|-----------------|-----------------|------|
| CP-24-15     | 47              | 3.3             | °C/W |

Board layout impacts thermal characteristics, such as θ<sub>JA</sub>. When proper thermal management techniques are used, a better θ<sub>JA</sub> value can be achieved.

Although the exposed pad can be left floating, it must be connected to an external V– plane or ground plane for proper thermal management.

### Maximum Power Dissipation

The maximum safe power dissipation for the SSM6322 is limited by the associated rise in junction temperature (T<sub>J</sub>) on the die. At approximately 150°C, which is the glass transition temperature, the properties of the plastic change. Even temporarily exceeding this temperature limit may change the stresses that the package exerts on the die, permanently shifting the parametric performance of the SSM6322. Exceeding a junction temperature of 175°C for an extended period can result in changes in silicon devices, potentially causing degradation or loss of functionality. The power dissipated in the package (P<sub>D</sub>) is the sum of the quiescent power dissipation and the power dissipated in the die due to the SSM6322 drive at the output.

The quiescent power is the voltage between the supply pins (V<sub>S</sub>) times the quiescent current (I<sub>S</sub>).

$$P_D = \text{Quiescent Power} + (\text{Total Drive Power} - \text{Load Power})$$

$$P_D = (V_S \times I_S) + \left( \frac{V_S}{2} \times \frac{V_{OUT}}{R_L} \right) - \frac{V_{OUT}^2}{R_L}$$

Consider the rms output voltages. If R<sub>L</sub> is referenced to –V<sub>SY</sub>, as in single-supply operation, the total drive power is V<sub>SY</sub> × I<sub>OUT</sub>. If the rms signal levels are indeterminate, consider the worst case, when V<sub>OUT</sub> = V<sub>SY</sub>/4 for R<sub>L</sub> to midsupply.

$$P_D = (V_S \times I_S) + \frac{(V_S/4)^2}{R_L}$$

Airflow increases heat dissipation, effectively reducing θ<sub>JA</sub>. Also, more metal directly in contact with the package leads and exposed paddle from metal traces, through holes, ground, and power planes reduce θ<sub>JA</sub>.

Figure 2 shows the maximum safe power dissipation in the package vs. the ambient temperature for the 24-lead LFCSP package on a JEDEC standard 4-layer board.

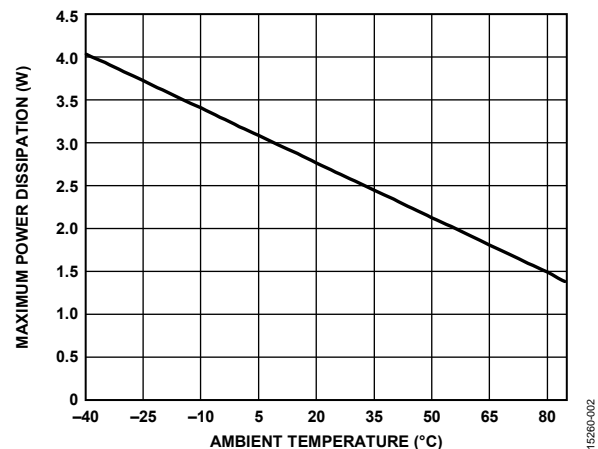


Figure 2. Maximum Power Dissipation vs. Ambient Temperature for a 4-Layer Board

### ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

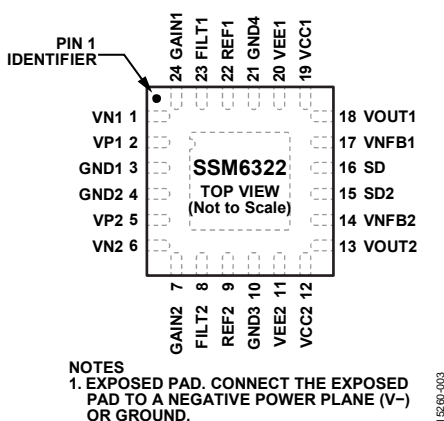
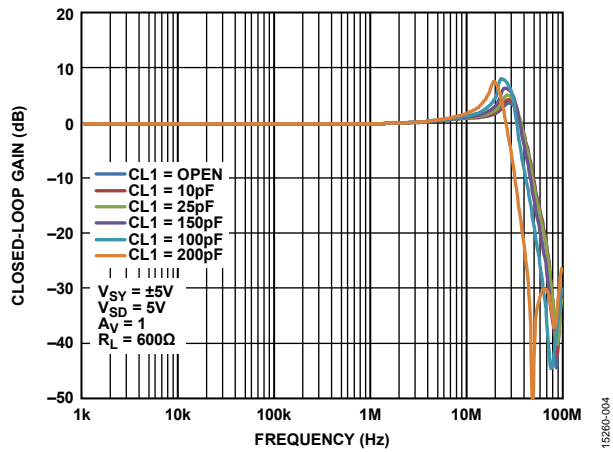
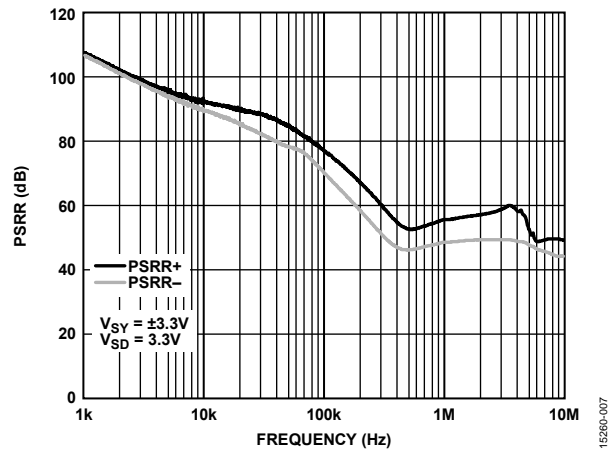
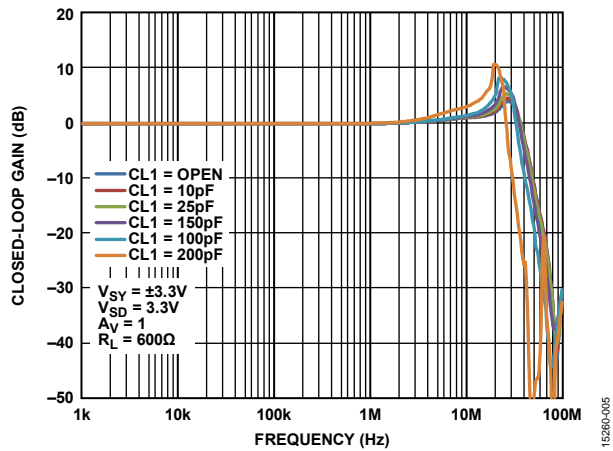
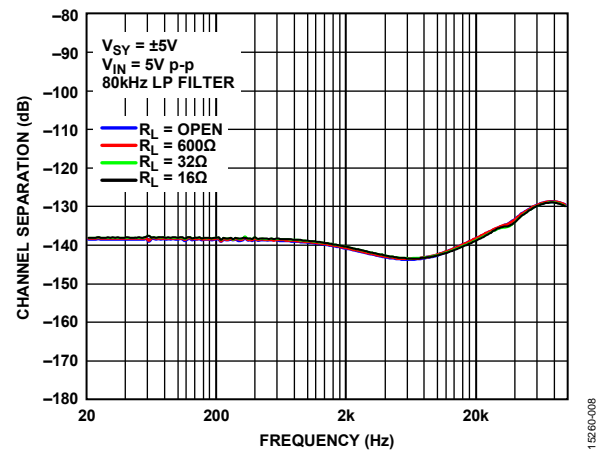
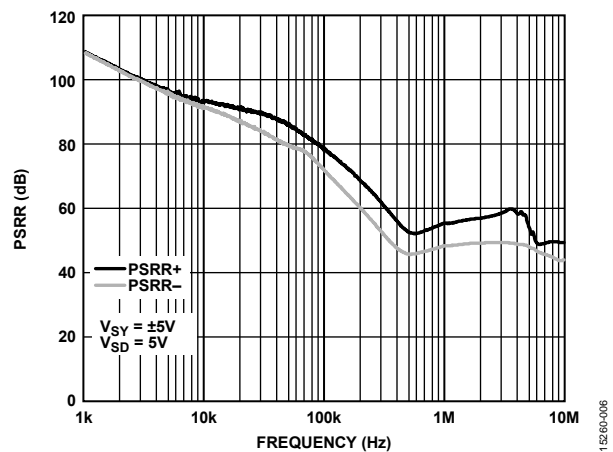
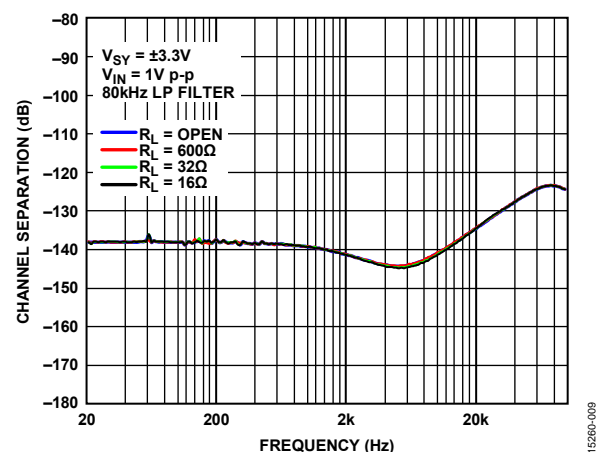
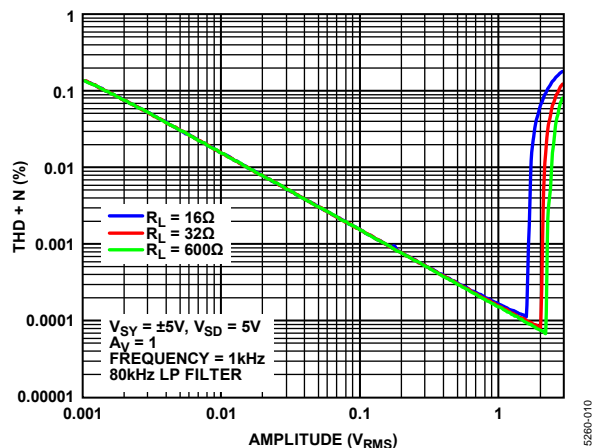
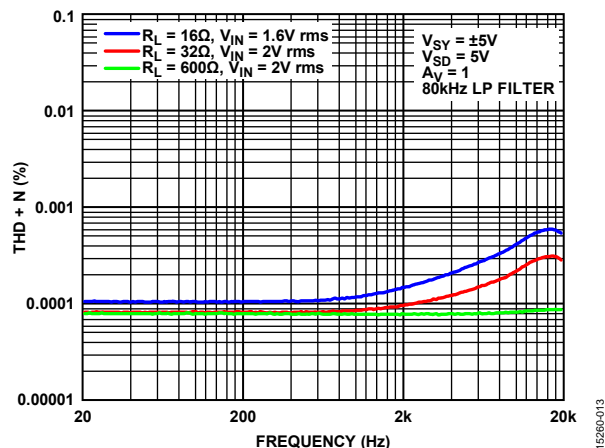
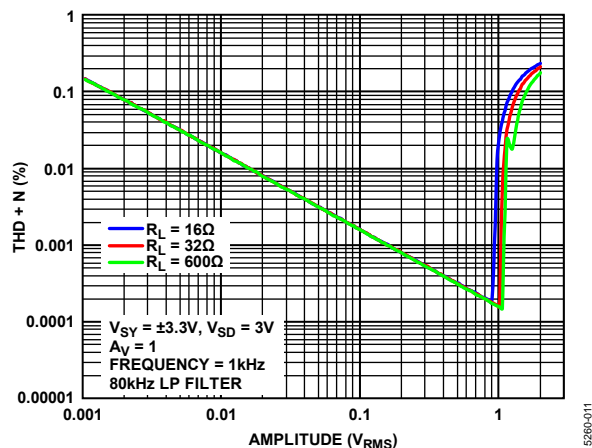
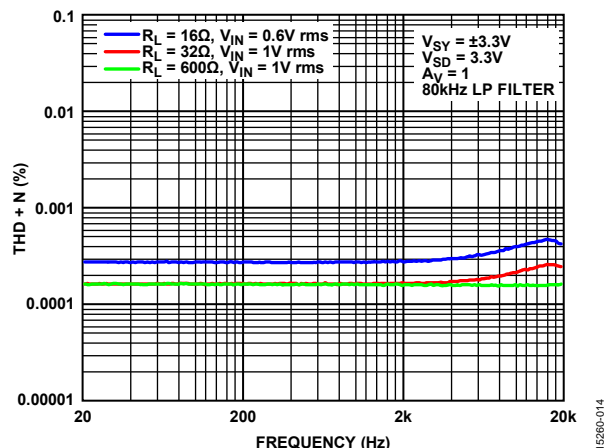
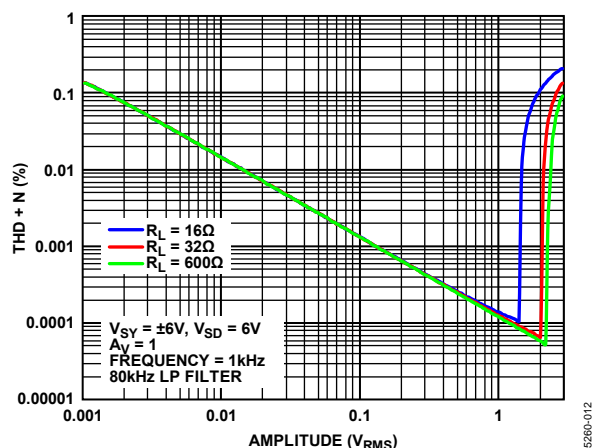
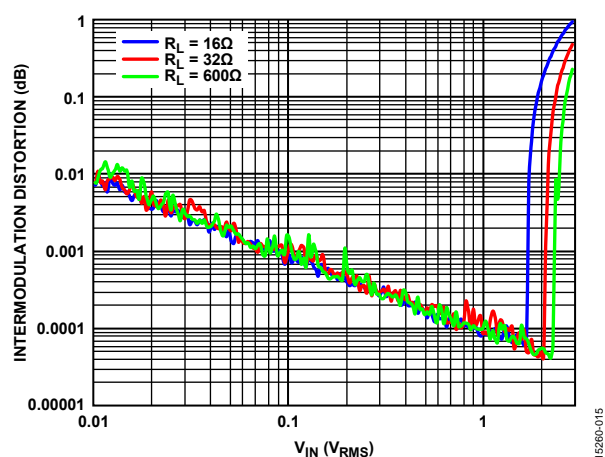


Table 5. Pin Function Descriptions

| Pin No. | Mnemonic | Description  |
|---------|----------|--|
| 1       | VN1      | Negative Input of Channel 1 Input Stage.                                       |
| 2       | VP1      | Positive Input of Channel 1 Input Stage.                                       |
| 3       | GND1     | Ground 1.  |
| 4       | GND2     | Ground 2.  |
| 5       | VP2      | Positive Input of Channel 2 Input Stage.                                       |
| 6       | VN2      | Negative Input of Channel 2 Input Stage.                                       |
| 7       | GAIN2    | Output of Channel 2 Input Stage.   |
| 9       | FILT2    | Positive Input of Channel 2 Output Stage.                                      |
| 9       | REF2     | Input Common-Mode Voltage of Channel 2 Input Stage.                            |
| 10      | GND3     | Ground 3.  |
| 11      | VEE2     | Negative Supply 2. This pin is internally shorted to Pin 20.                   |
| 12      | VCC2     | Positive Supply 2. This pin is internally shorted to Pin 19.                   |
| 13      | VOUT2    | Output of Channel 2 Output Stage.  |
| 14      | VNFB2    | Negative Feedback of Channel 2 Output Stage.                                   |
| 15      | SD2      | Shuts Down Power for the Entire Device. This pin is referenced to ground.      |
| 16      | SD       | Shuts Down Power for the Output Stage. This pin is referenced to ground.       |
| 17      | VNFB1    | Negative Feedback of Channel 1 Output Stage.                                   |
| 18      | VOUT1    | Output of Channel 1 Output Stage.  |
| 19      | VCC1     | Positive Supply 1. This pin is internally shorted to Pin 12.                   |
| 20      | VEE1     | Negative Supply 1. This pin is internally shorted to Pin 11.                   |
| 21      | GND4     | Ground 4.  |
| 22      | REF1     | Input Common-Mode Voltage of Channel 1 Input Stage.                            |
| 23      | FILT1    | Positive Input of Channel 1 Output Stage.                                      |
| 24      | GAIN1    | Output of Channel 1 Input Stage.   |
|         | EPAD     | Exposed Pad. Connect the exposed pad to a negative power plane (V-) or ground. |

## TYPICAL PERFORMANCE CHARACTERISTICS

Figure 4. Frequency Response for Various Capacitive Loads,  $V_{SV} = \pm 5\text{ V}$ Figure 7. PSRR vs. Frequency,  $V_{SV} = \pm 3.3\text{ V}$ Figure 5. Frequency Response for Various Capacitive Loads,  $V_{SV} = \pm 3.3\text{ V}$ Figure 8. Channel Separation vs. Frequency,  $V_{SV} = \pm 5\text{ V}$ Figure 6. PSRR vs. Frequency,  $V_{SV} = \pm 5\text{ V}$ Figure 9. Channel Separation vs. Frequency,  $V_{SV} = \pm 3.3\text{ V}$

Figure 10. THD + N vs. Amplitude,  $V_{SY} = \pm 5 V$ Figure 13. THD + N vs. Frequency,  $V_{SY} = \pm 5 V$ Figure 11. THD + N vs. Amplitude,  $V_{SY} = \pm 3.3 V$ Figure 14. THD + N vs. Frequency,  $V_{SY} = \pm 3.3 V$ Figure 12. THD + N vs. Amplitude,  $V_{SY} = \pm 6 V$ Figure 15. SMPTE vs. Input Voltage ( $V_{IN}$ ),  $V_{SY} = \pm 5 V$



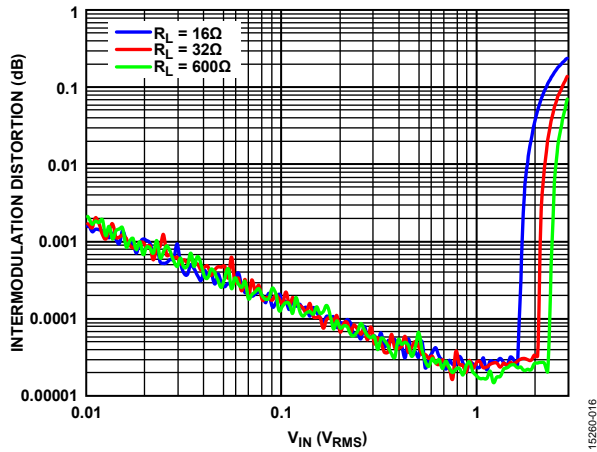
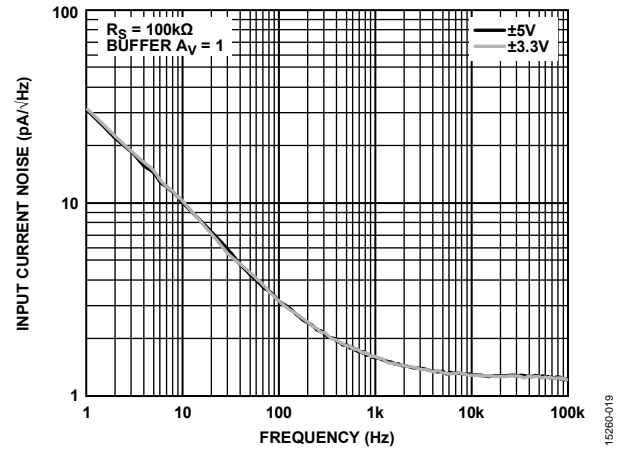
Figure 16. CCIF vs. Input Voltage ( $V_{IN}$ ),  $V_{SY} = \pm 5V$ 

Figure 19. Input Current Noise vs. Frequency

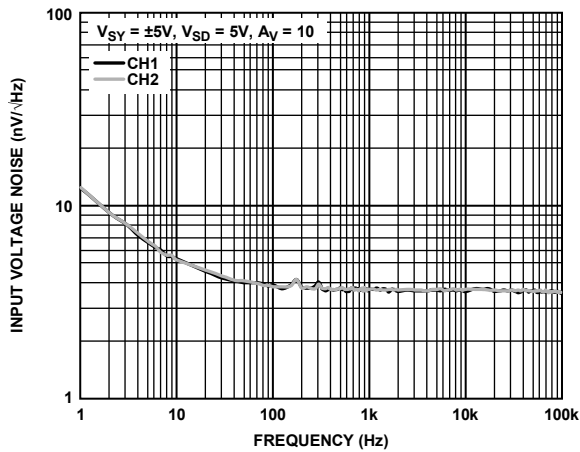
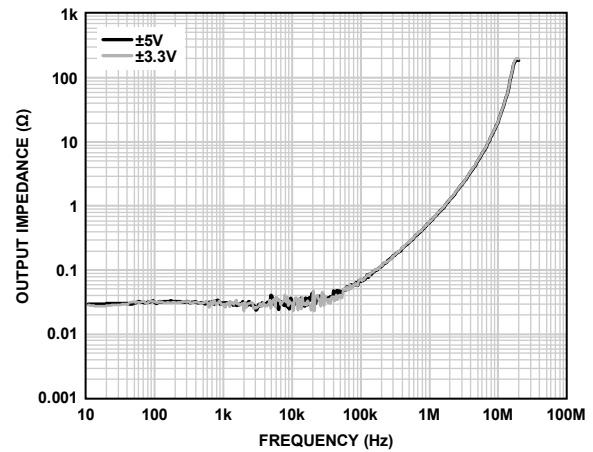
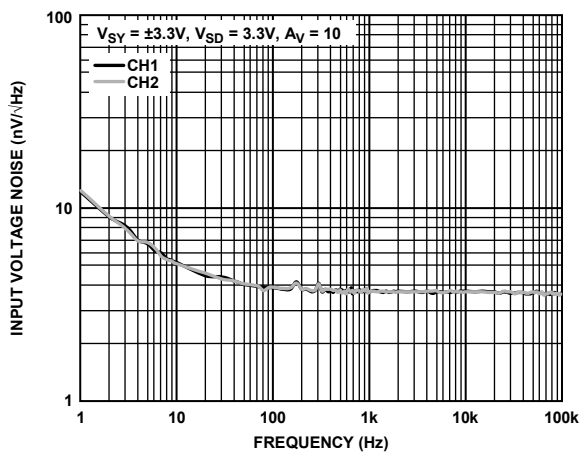
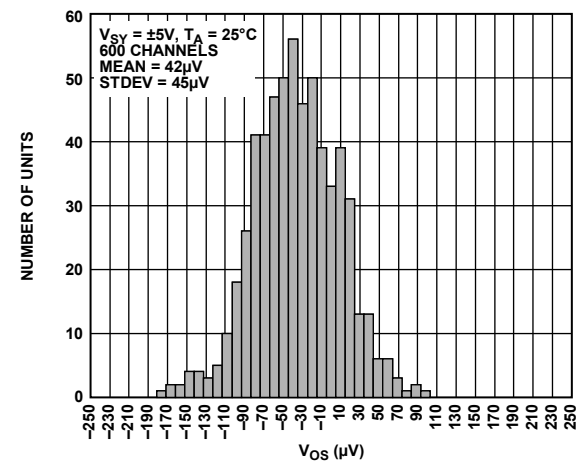
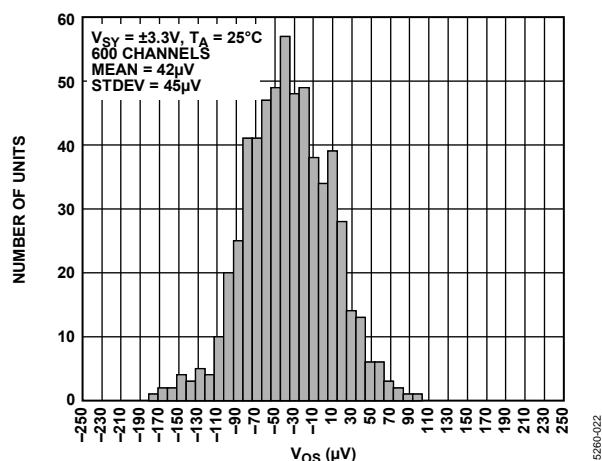
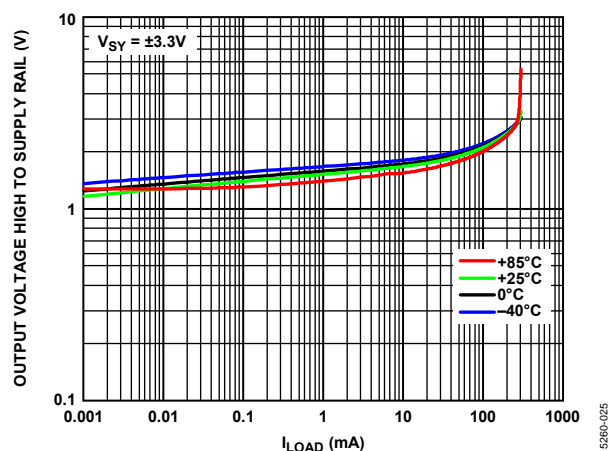
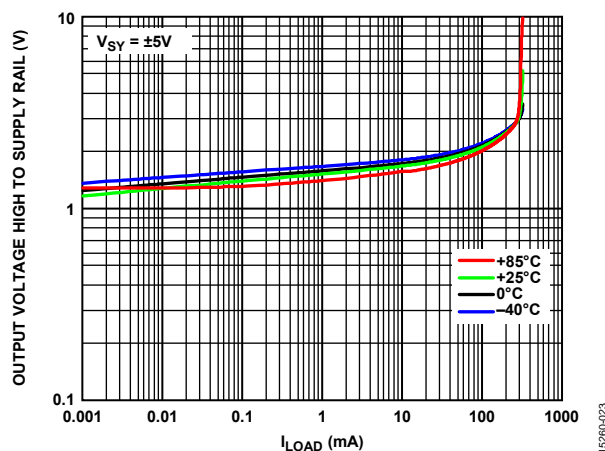
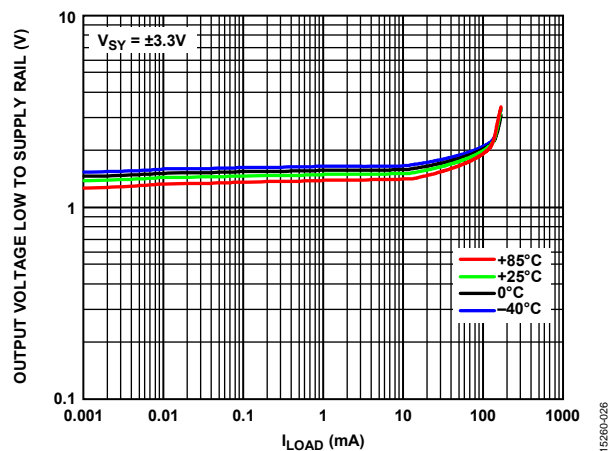
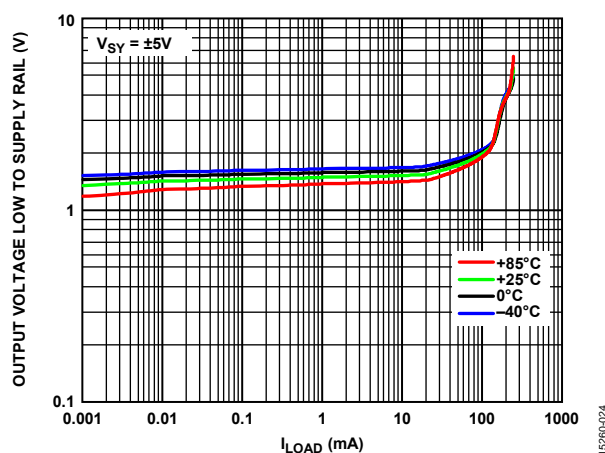
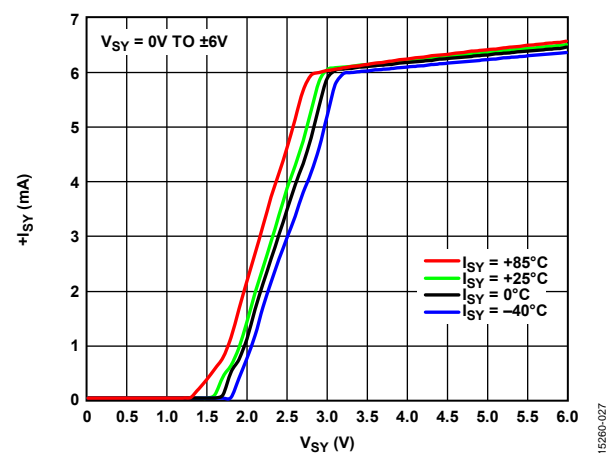
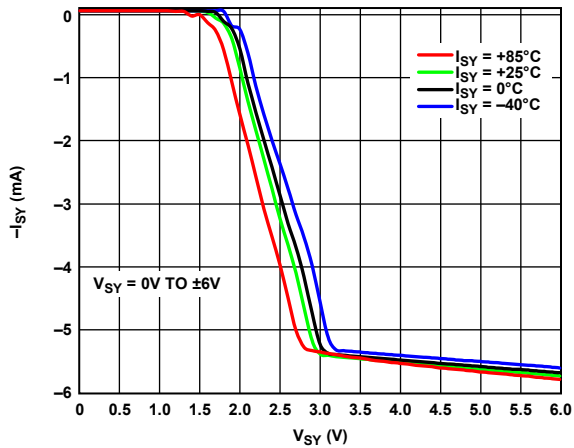
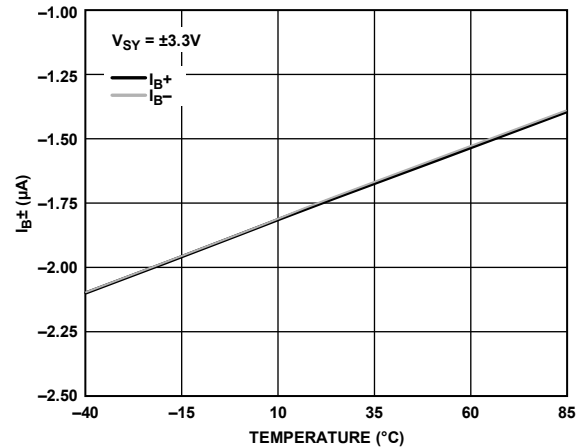
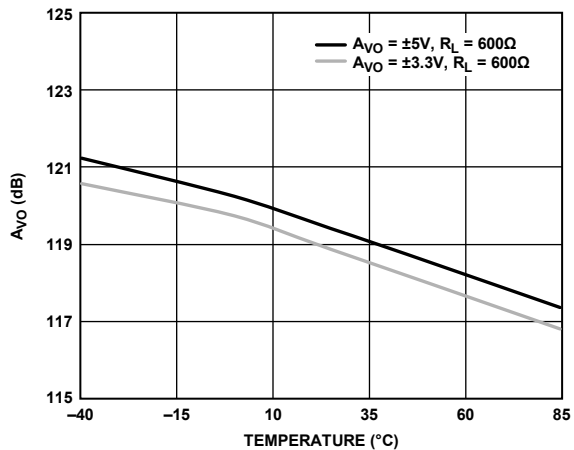
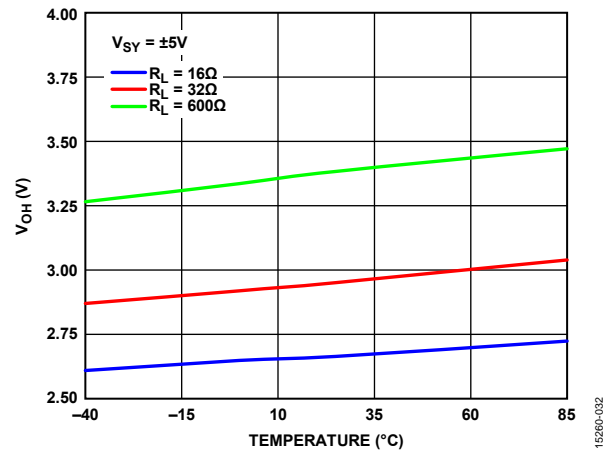
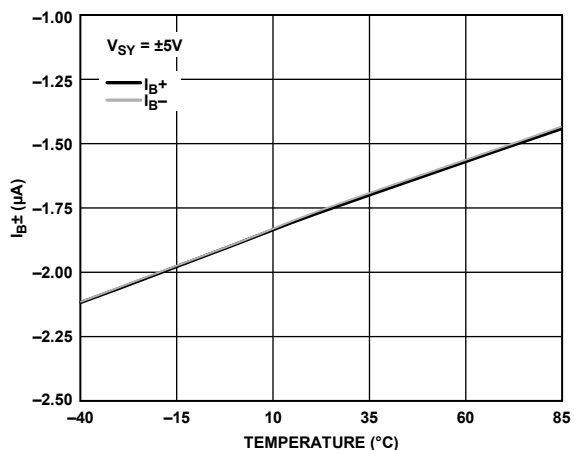
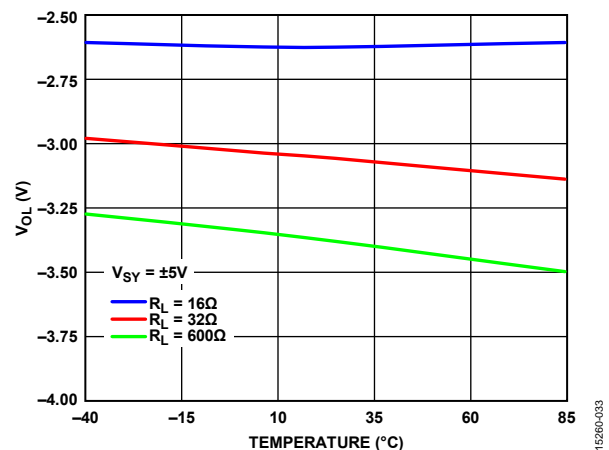
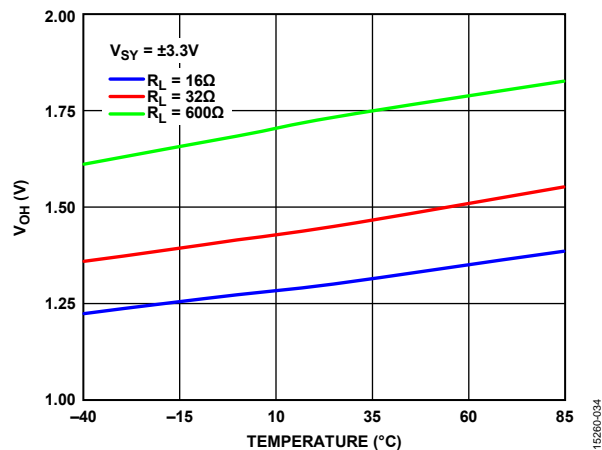
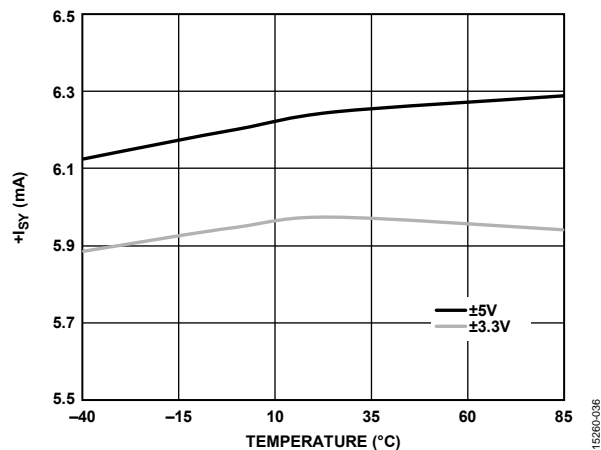
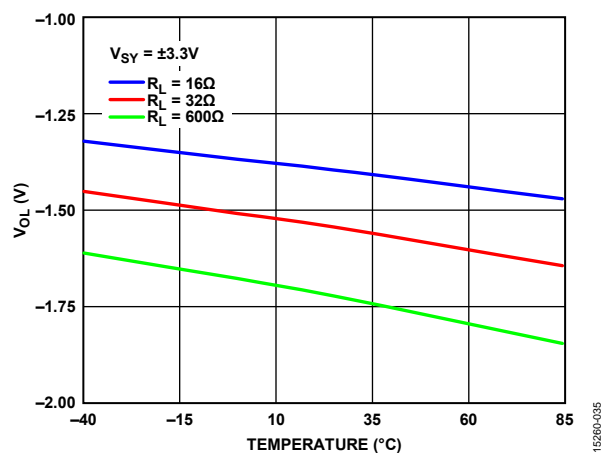
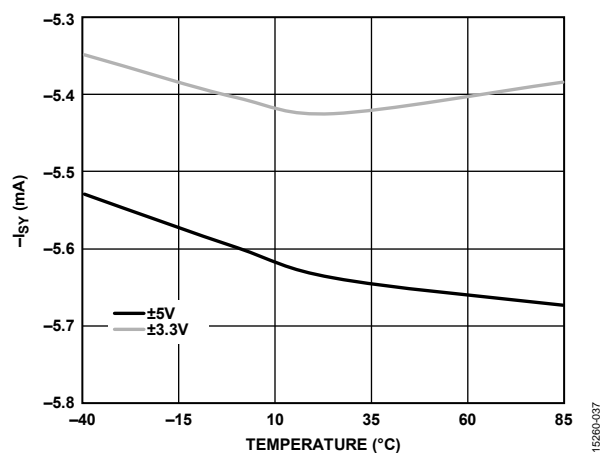
Figure 17. Input Voltage Noise vs. Frequency,  $V_{SY} = \pm 5V$ 

Figure 20. Enabled Output Impedance vs. Frequency

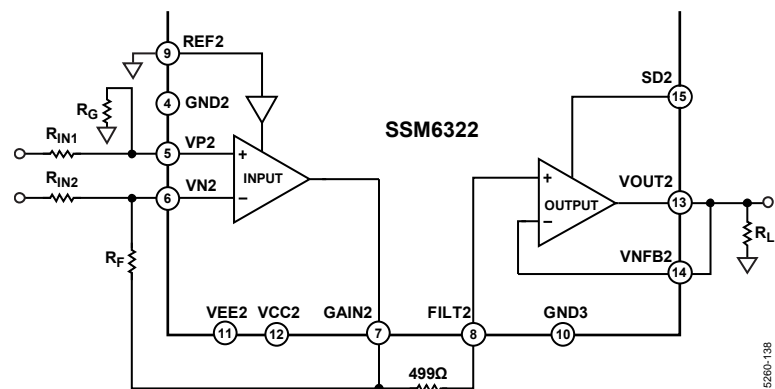
Figure 18. Input Voltage Noise vs. Frequency,  $V_{SY} = \pm 3.3V$ Figure 21. Input Offset Voltage ( $V_{OS}$ ) Distribution,  $V_{SY} = \pm 5V$

Figure 22. Input Offset Voltage ( $V_{OS}$ ) Distribution,  $V_{SY} = \pm 3.3\text{ V}$ Figure 25. Output Voltage High ( $V_{OH}$ ) to Supply Rail vs. Load Current ( $I_{LOAD}$ ),  $V_{SY} = \pm 3.3\text{ V}$ Figure 23. Output Voltage High ( $V_{OH}$ ) to Supply Rail vs. Load Current ( $I_{LOAD}$ ),  $V_{SY} = \pm 5\text{ V}$ Figure 26. Output Voltage Low ( $V_{OL}$ ) to Supply Rail vs. Load Current ( $I_{LOAD}$ ),  $V_{SY} = \pm 3.3\text{ V}$ Figure 24. Output Voltage Low ( $V_{OL}$ ) to Supply Rail vs. Load Current ( $I_{LOAD}$ ),  $V_{SY} = \pm 5\text{ V}$ Figure 27. Positive Supply Current ( $+I_{SY}$ ) vs. Supply Voltage ( $V_{SY}$ )

Figure 28. Supply Current ( $-I_{SY}$ ) vs. Supply Voltage ( $V_{SY}$ )Figure 31. Input Bias Current ( $I_{B\pm}$ ) vs. Temperature,  $V_{SY} = \pm 3.3V$ Figure 29. Open-Loop Gain ( $A_{VO}$ ) vs. TemperatureFigure 32. Output Voltage High ( $V_{OH}$ ) vs. Temperature,  $V_{SY} = \pm 5V$ Figure 30. Input Bias Current ( $I_{B\pm}$ ) vs. Temperature,  $V_{SY} = \pm 5V$ Figure 33. Output Voltage Low ( $V_{OL}$ ) vs. Temperature,  $V_{SY} = \pm 5V$

Figure 34. Output Voltage High ( $V_{OH}$ ) vs. Temperature,  $V_{SY} = \pm 3.3\text{ V}$ Figure 36. Supply Current ( $+I_{SY}$ ) vs. TemperatureFigure 35. Output Voltage Low ( $V_{OL}$ ) vs. Temperature,  $V_{SY} = \pm 3.3\text{ V}$ Figure 37. Supply Current ( $-I_{SY}$ ) vs. Temperature

TEST CIRCUIT



## THEORY OF OPERATION

The [SSM6322](#) is designed using Analog Devices, Inc., proprietary extra fast complementary bipolar (XFCB) process. The device features exceptionally low 1/f noise, low power, and load drive capability. The device combines a classic difference amplifier configuration with a common-mode loop that maintains a fixed common-mode input level, regardless of the differential or common-mode currents going into the device. This combination results in the DAC operating in optimal conditions to reach the THD specifications. This configuration of a common-mode loop and a difference amplifier also has much lower noise and power consumption than other solutions by eliminating two additional amplifiers from the signal path.

The output driver has many features including heavy load drive, multiplexing, and pop click suppression. In both shutdown conditions, the output is high impedance in the audio band when the applied external signal is between the supply rails. An additional shutdown pin is included to power up the input difference amplifier so that it can settle before any unwanted signals are applied to the driver. The output driver is capable of delivering –120 dB THD with a 100 mA peak output current and a 2 V rms signal.

### REF1 and REF2 Pin Voltage

REF1 and REF2 set the input common-mode signal. Internally, there is a 15  $\mu$ A current source; by externally adding a resistor, 15  $\mu$ A of current flows through the resistor to generate a common-mode voltage. For example, a 51 k $\Omega$  resistor and 15  $\mu$ A current results in a common-mode voltage of 0.765 V.

### Shutdown Control

The [SSM6322](#) features two shutdown pins to control different sections of the device. When SD and SD2 are Logic 1, the entire device is enabled. When SD is Logic 0 and SD2 is Logic 1, the input stage is enabled, and the output buffer is disabled. When SD2 is Logic 0, the entire device is disabled with a quiescent current of only 15  $\mu$ A (see Table 6).

**Table 6. Disabled Mode and Enabled Mode**

| Logic Level of the Shutdown Pins | Device Status   |
|----------------------------------|---|
| SD and SD2 = 1                   | Entire device is enabled.   |
| SD = 0 and SD2 = 1               | Input stage is enabled, and the output buffer is disabled.        |
| SD2 = 0                          | Entire device is disabled with a quiescent current of 15 $\mu$ A. |

## APPLICATIONS INFORMATION

### HEADPHONE DRIVERS IN MOBILE PHONES

In a headphone driver application, some high performance audio DACs can be configured as a voltage output or a current output. Typically, the current output configuration results in the best THD + N performance.

For a current output configuration, implement an current to voltage (I to V) circuit to convert the differential current signal from the R channel and the L channel to the differential voltage signal, followed by a difference amplifier circuit (see Figure 41).

For a voltage output configuration, the conditioning circuit is a difference amplifier circuit, which converts the differential signal from the R channel or L channel to a single-ended signal (see Figure 39).

Current output audio DACs are typically used to achieve the best THD + N performance (see Figure 41). Six amplifiers and many passive components are required to perform current mode signal conditioning, which consumes more PCB area and more power. Area consumption and power consumption are important considerations in mobile phone applications.

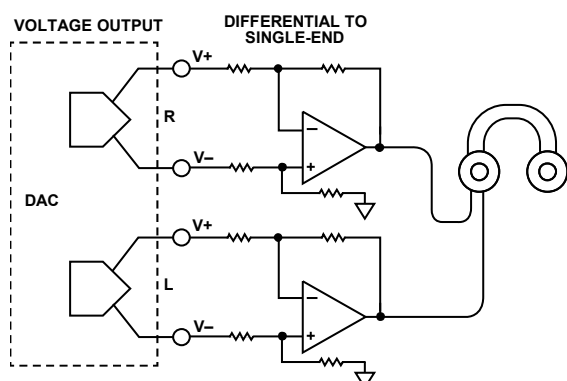


Figure 39. Voltage Output DAC Configuration

The SSM6322 is an integrated solution for mobile phone applications requiring low distortion and noise performance while directly driving a low impedance load. The device also saves more PCB area and power than the current discrete solution.

The SSM6322 contains an additional buffer to support high current drive capabilities. The buffer is also capable of being configured in true high-Z mode in the audio band, which is desirable in some portable applications for the multiplexing of other signals on the same output port.

### COMMON-MODE CONTROL CIRCUIT

The differential output stage of the DAC can be modeled as two voltage sources, which both have the same amplitude and a 180° phase difference.  $R_{S1}$  and  $R_{S2}$  are the source resistors of the voltage source (see Figure 40).

In a typical current output DAC signal chain (see Figure 41), four amplifiers are configured as an I to V circuit. The non-inverting inputs are connected to a dc voltage that is the output common-mode level of the DAC, making the voltage at the I+/I- terminals a dc signal. This signal makes the voltage drop at two internal source resistors of the DAC ( $R_{S1}$  and  $R_{S2}$ ) the same, which makes the DAC achieve the best distortion performance.

In the SSM6322, the input difference amplifier performs the I to V conversion.

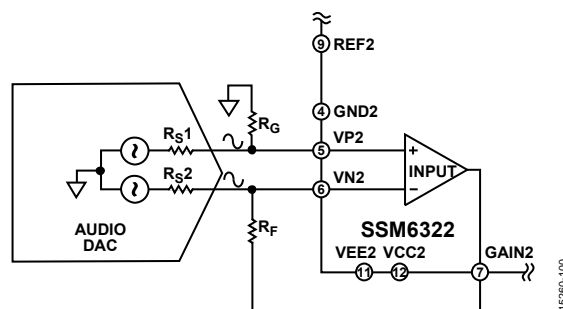


Figure 40. Common-Mode Circuit Without Common-Mode Control

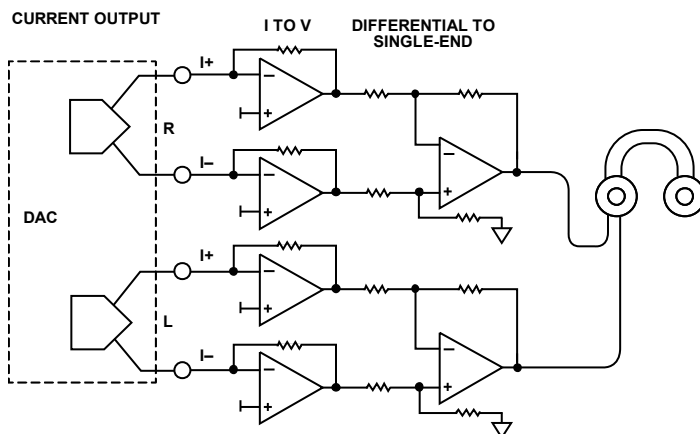


Figure 41. Current Output DAC Configuration

Assuming there is no common-mode control (see Figure 40), the signals at the input terminals (VP2/VN2) are ac signals that have the same amplitude and phase. In addition, the internal voltage source of the DAC is differential, which makes the voltage drop at  $R_{S1}$  and  $R_{S2}$  different values. This difference degrades the performance of the DAC. Simultaneously, from the amplifier, the ac common-mode signal at two input terminals (VP2 and VN2) generates additional error signal at the output by its limited ac common-mode rejection ratio (CMRR) performance.

After a common-mode control circuit (indicated by the dashed outline shown in Figure 42) is included, the signal at the input terminals (VP2 and VN2) is a dc signal set by the voltage at the REF2 pin (typically this voltage is the same as the dc common-mode voltage of the DAC). The voltage drop at  $R_{S1}$  and  $R_{S2}$  in the DAC is the same. Additionally, the high dc CMRR performance of the amplifier renders the CMRR error negligible. Both the DAC and the amplifier have the best performance in this configuration. The SSM6322 implements the circuit shown in Figure 42.

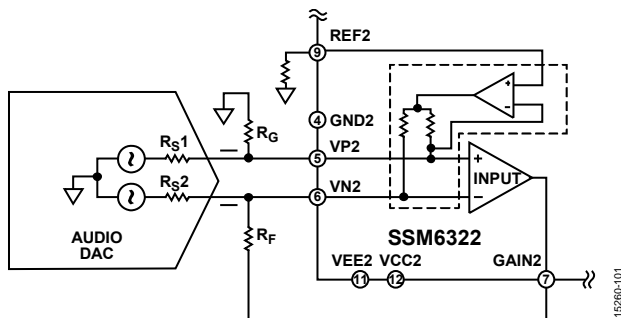


Figure 42. Common-Mode Circuit with Common-Mode Control

## CAPACITIVE LOAD DRIVE

Figure 43 shows the schematic of the output stage for driving capacitive loads. Figure 44 and Figure 45 show the frequency response for a gain of 1 at the  $\pm 5$  V and  $\pm 3.3$  V power supply voltages, respectively. The peaking is high with a small capacitive load. With a 2.2 nF capacitive load ( $C_L$ ), the frequency response is flat and without peaking.

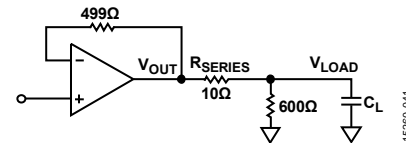


Figure 43. Schematic for Driving Capacitive Loads

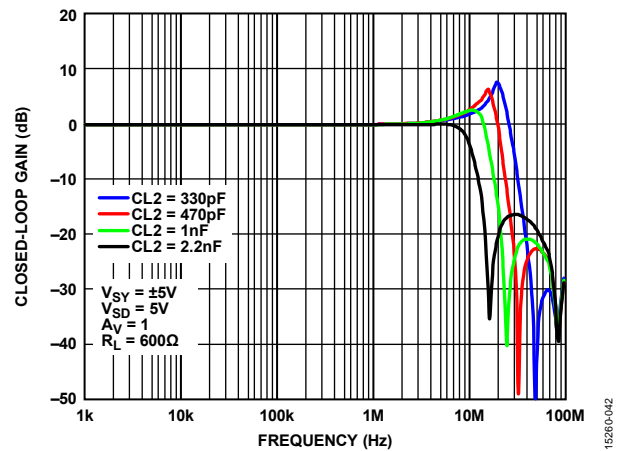


Figure 44. Frequency Response for Driving Capacitive Loads,  $V_{SY} = \pm 5$  V

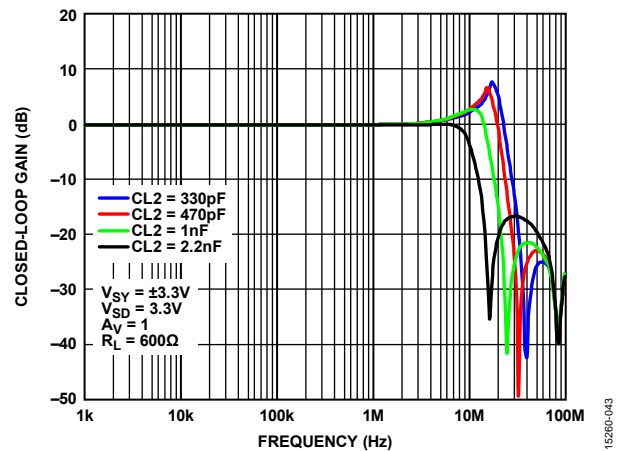


Figure 45. Frequency Response for Driving Capacitive Loads,  $V_{SY} = \pm 3.3$  V



## SSM6322 IN A HEADPHONE DRIVER APPLICATION

### SSM6322 Circuit with Current Output DAC

For an audio DAC with a differential current output, two gain resistors convert the current to voltage (see Figure 46). The resistor value is determined by the DAC output full-scale current and the input stage output range (the output range is  $\pm 3$  V at a  $\pm 5$  V supply). Assuming that the DAC single-ended output current is  $\pm 1.5$  mA, and that the differential current is  $\pm 3$  mA, the output of the input stage is  $\pm 3$  V when using two  $1$  k $\Omega$  gain resistors. The feedback capacitors, in parallel with the gain resistors, form a single-pole, low-pass filter. The SSM6322 can handle up to a  $1$  k $\Omega$  and  $2.2$  nF resistor capacitor combination.

Typically, audio DACs generate a dc offset current, which is converted to an input common-mode voltage at the input of the SSM6322. The REF1 and REF2 pins of the SSM6322 set the input common-mode voltage of each channel. The voltage at the REF1 and REF2 pins is achieved by an internal  $15$   $\mu$ A current source and an external resistor; a  $51$  k $\Omega$  resistor is suggested to achieve a  $0.765$  V voltage. A  $1$   $\mu$ F capacitor can be used in parallel with the resistor to remove noise.

A  $499$   $\Omega$  resistor and  $1$  nF capacitor can be added between the input stage and output stage for a second single-pole, low-pass filter, as shown in Figure 46.

For better gain matching and better distortion performance, all  $1$  k $\Omega$  and  $499$   $\Omega$  resistors must be of  $0.1\%$  tolerance and a

$25$  ppm/ $^{\circ}$ C temperature coefficient. The  $1$  nF capacitors must be NP0 capacitors. There are no specific requirements for the  $51$  k $\Omega$  resistor and the  $1$   $\mu$ F capacitor at REF1 and REF2.

### SSM6322 Circuit with Voltage Output DAC

For audio DACs that output a differential voltage, four gain resistors convert the differential voltage to single-ended voltage (see Figure 47). The feedback capacitors must be in parallel with the gain resistors to form the single-pole, low-pass filter. As shown in Figure 47, four  $1$  k $\Omega$  resistors and two  $1$  nF capacitors are used to achieve a gain of  $1$  and a first-order,  $159$  kHz cutoff frequency low-pass filter.

For REF1 and REF2, refer to the DAC data sheet for the common-mode voltage; then, calculate the resistor value at REF1 and REF2. As shown in Figure 47, a  $51$  k $\Omega$  resistor is suggested to obtain a  $0.765$  V voltage.

A  $499$   $\Omega$  resistor and  $1$  nF capacitor can be added between the input stage and output stage for a second single-pole, low-pass filter, as shown in Figure 47.

For better gain matching and better distortion performance, all  $1$  k $\Omega$  and  $499$   $\Omega$  resistors must be of a  $0.1\%$  tolerance and  $25$  ppm/ $^{\circ}$ C temperature coefficient; the  $1$  nF capacitor must be NP0 capacitor.

There are no specific requirement for the  $51$  k $\Omega$  resistor and  $1$   $\mu$ F capacitor at REF1 and REF2.

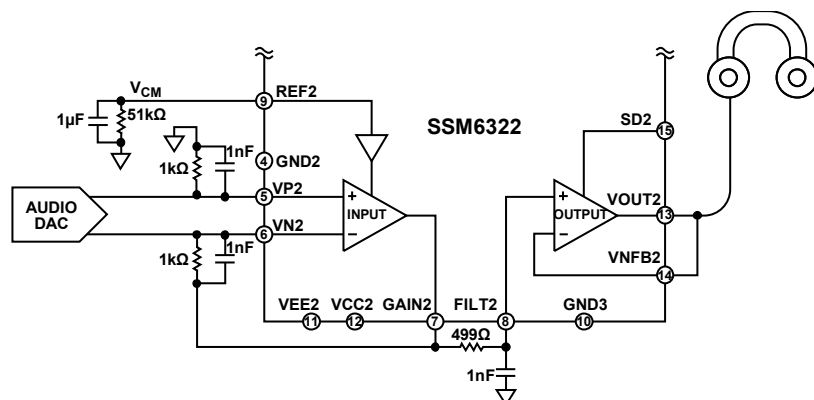


Figure 46. SSM6322 Circuit with Current Output DAC

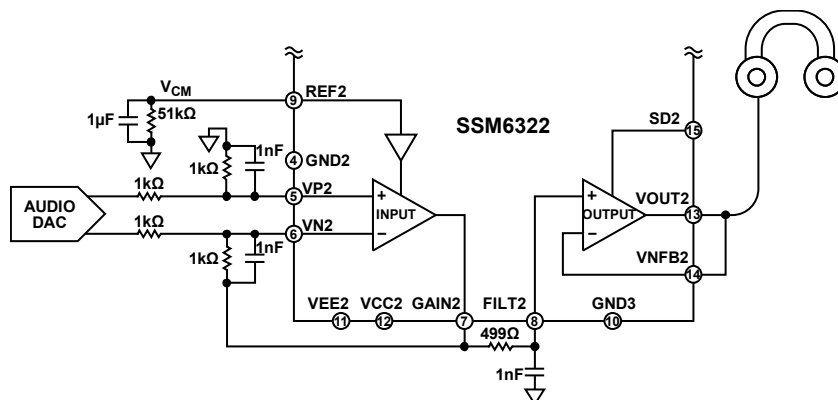


Figure 47. SSM6322 Circuit with Voltage Output DAC

## DESIGN GUIDELINES

The performance of the SSM6322 is such that any minor external interference can destroy the circuit. When using this device, consider the following:

- The sensing ground of the input stage is sensitive to external interference. In the PCB layout, it is recommended to refer the sensing ground to the output interface ground (in high fidelity headphone driver applications, the output interface is the jack). As shown in Figure 48, the dashed outline enclosed ground is the input stage sensing ground, which must be routed directly to the ground of the jack. Note that Figure 48 only shows one channel; for the other channel, route the sensing ground to the jack ground separately.
- The SSM6322 circuit is different with a typical current output DAC signal chain (see Figure 41); there is only one op amp that performs the differential I to V conversion. The power across the noninverting grounded resistor is fixed, but the power across the feedback resistor varies with the output signal. This variability creates a mismatch between the two resistors, as well as distortion if the heat cannot be well dissipated. Low drift (25 ppm/°C) metal film or thin film resistors are suggested to avoid this situation (see Figure 46).
- If there is a resistor between the final output and the headphone, the resistor must be low drift (25 ppm/°C) and metal film or thin film to avoid distortion when driving heavy loads.
- Use a low dropout regulator (LDO) as the power supply. Place the decoupling capacitors (0.1  $\mu$ F and 4.7  $\mu$ F) near the amplifier power pins. If there is switching power on the board, keep the switching power circuit and return path far away from the SSM6322 circuit.
- For better heat dissipation, solder the exposed pad of the LFCSP package to the board pad and, using vias, connect the exposed pad to a large, solid copper plane at the opposite side of the board. The copper plane can be connected to the negative supply plane or ground plane.
- Shielding is important in mobile phone applications. To reach  $<-100$  dB THD + N specifications, even small interferences can degrade THD + N performance, particularly when listening to music and browsing the internet simultaneously. Metal shielding helps prevent performance degradation.
- The maximum input filter capacitor values are 2.2 nF.

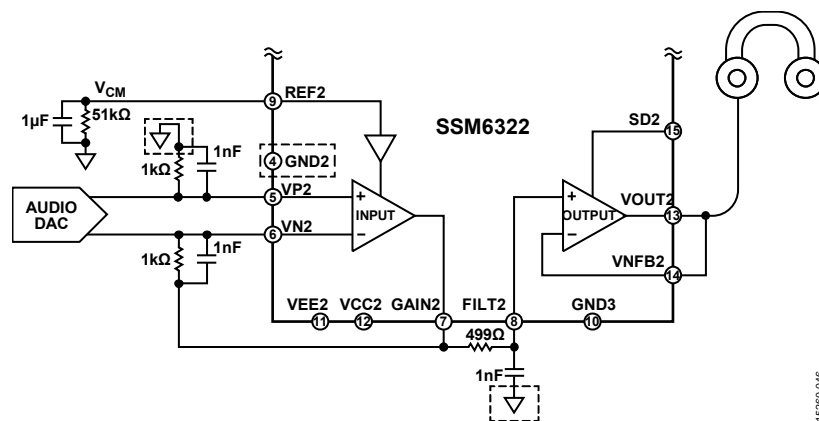


Figure 48. Sensing Ground of Input Stage

## OUTLINE DIMENSIONS

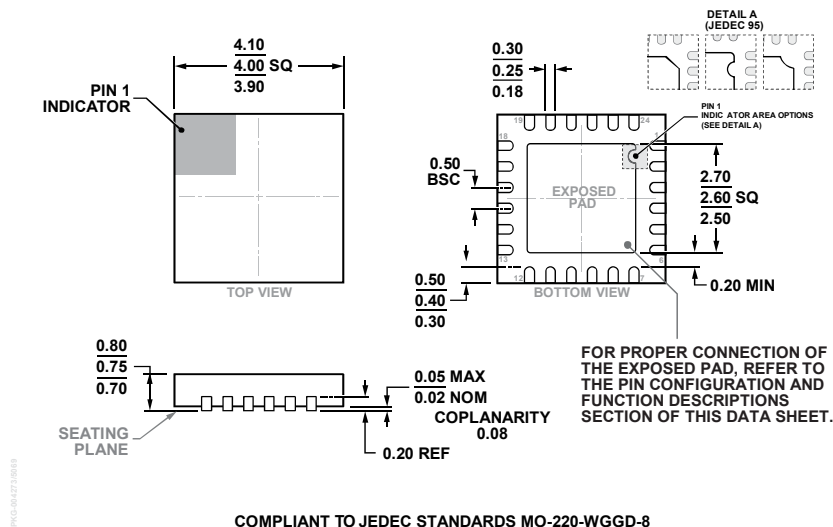


Figure 49. 24-Lead Lead Frame Chip Scale Package [LFCSP]  
4 mm × 4 mm Body and 0.75 mm Package Height  
(CP-24-15)  
Dimensions shown in millimeters

## ORDERING GUIDE

| Model <sup>1</sup> | Temperature Package | Package Description                           | Package Option | Branding |
|--------------------|---------------------|---|----------------|----------|
| SSM6322ACPZ-R2     | −40°C to +85°C      | 24-Lead Lead Frame Chip Scale Package [LFCSP] | CP-24-15       | 6322A    |
| SSM6322ACPZ-R7     | −40°C to +85°C      | 24-Lead Lead Frame Chip Scale Package [LFCSP] | CP-24-15       | 6322A    |
| SSM6322ACPZ-RL     | −40°C to +85°C      | 24-Lead Lead Frame Chip Scale Package [LFCSP] | CP-24-15       | 6322A    |
| SSM6322CP-EBZ      |                     | Evaluation Board                              |                |          |

<sup>1</sup> Z = RoHS Compliant Part.