ELECTRICAL CHARACTERISTICS (T_C = 25°C unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
OFF CHARACTERISTICS					
Collector−Emitter Sustaining Voltage (I_C = 100 mA, L = 25 mH)	$V_{CEO(sus)}$	400	–	–	Vdc
Collector Cutoff Current (V_{CE} = Rated V_{CEO}, I_B = 0)	I_{CEO}	–	–	100	μAdc
Collector Cutoff Current (V_{CE} = Rated V_{CES}, V_{EB} = 0) (T_C = 125°C)	I_{CES}	– –	– –	10 100	μAdc
Emitter Cutoff Current (V_{EB} = 9.0 Vdc, I_C = 0)	I_{EBO}	–	–	100	μAdc
ON CHARACTERISTICS					
Base−Emitter Saturation Voltage (I_C = 1.0 Adc, I_B = 0.2 Adc) (I_C = 2.0 Adc, I_B = 0.4 Adc)	$V_{BE(sat)}$	 – –	 0.84 0.89	 1.2 1.25	Vdc
Collector−Emitter Saturation Voltage (I_C = 1.0 Adc, I_B = 0.2 Adc) (T_C = 125°C)	$V_{CE(sat)}$	– –	0.175 0.150	0.25 –	Vdc
Collector−Emitter Saturation Voltage (I_C = 2.0 Adc, I_B = 0.4 Adc) (T_C = 125°C)	$V_{CE(sat)}$	– –	0.25 0.275	0.4 –	Vdc
DC Current Gain (I_C = 0.3 Adc, V_{CE} = 5.0 Vdc) (T_C = 125°C) (I_C = 2.0 Adc, V_{CE} = 1.0 Vdc) (T_C = 125°C) (I_C = 10 mAdc, V_{CE} = 5.0 Vdc)	h_{FE}	14 – 7.0 5.0 10	– 32 14 12 22	34 – – – –	–
DYNAMIC CHARACTERISTICS					
Current Gain Bandwidth (I_C = 0.5 Adc, V_{CE} = 10 Vdc, f = 1.0 MHz)	f_T	–	12	—	MHz
Output Capacitance (V_{CB} = 10 Vdc, I_E = 0, f = 1.0 MHz)	C_{ob}	–	50	75	pF
Input Capacitance (V_{EB} = 8.0 Vdc)	C_{ib}	–	920	1200	pF

Dynamic Saturation Voltage	Conditions	Time		Symbol	Min	Typ	Max	Unit
Dynamic Saturation Voltage: Determined 1.0 μs and 3.0 μs respectively after rising I_{B1} reaches 90% of final I_{B1} (see Figure 18)	(I_C = 1.0 Adc I_{B1} = 100 mAdc V_{CC} = 300 V)	1.0 μs	 (T_C = 125°C)	V_{CE} (Dyn sat)	– –	1.75 4.4	– –	Vdc
		3.0 μs	 (T_C = 125°C)		– –	0.5 1.0	– –	
	(I_C = 2.0 Adc I_{B1} = 400 mAdc V_{CC} = 300 V)	1.0 μs	 (T_C = 125°C)		– –	1.85 6.0	– –	
		3.0 μs	 (T_C = 125°C)		– –	0.5 1.0	– –	

SWITCHING CHARACTERISTICS: Resistive Load

Characteristic	Conditions	Symbol	Min	Typ	Max	Unit
Turn−On Time	(I_C = 2.0 Adc, I_{B1} = I_{B2} = 0.4 Adc Pulse Width = 20 μs, (T_C = 125°C)	t_{on}	– –	75 120	110 –	ns
Turn−Off Time	Duty Cycle < 20% V_{CC} = 300 V (T_C = 125°C)	t_{off}	– –	2.8 3.5	3.5 –	μs

SWITCHING CHARACTERISTICS: Inductive Load (V_{CC} = 15 Vdc, L_C = 200 μH, V_{clamp} = 300 Vdc)

Characteristic	Conditions	Symbol	Min	Typ	Max	Unit
Fall Time	(I_C = 2.0 Adc, I_{B1} = 0.4 Adc I_{B2} = 0.4 Adc) (T_C = 125°C)	t_{fi}	70 –	– 200	170 –	ns
Storage Time	(T_C = 125°C)	t_{si}	2.6 –	– 4.2	3.8 –	μs
Crossover Time	(T_C = 125°C)	t_c	– –	230 400	350 –	ns
Fall Time	(I_C = 1.0 Adc, I_{B1} = 100 mAdc I_{B2} = 0.5 Adc) (T_C = 125°C)	t_{fi}	– –	110 100	150 –	ns
Storage Time	(T_C = 125°C)	t_{si}	– –	1.1 1.5	1.7 –	μs
Crossover Time	(T_C = 125°C)	t_c	– –	170 170	250 –	ns
Fall Time	(I_C = 2.0 Adc, I_{B1} = 250 mAdc I_{B2} = 2.0 Adc) (T_C = 125°C)	t_{fi}	–	80	120	ns
Storage Time	(T_C = 125°C)	t_{si}	–	0.6	0.9	μs
Crossover Time	(T_C = 125°C)	t_c	–	175	300	ns

TYPICAL STATIC CHARACTERISTICS

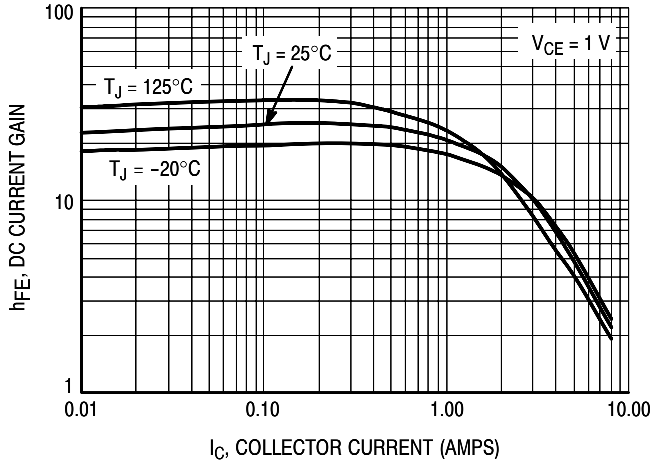


Figure 1. DC Current Gain @ 1 Volt

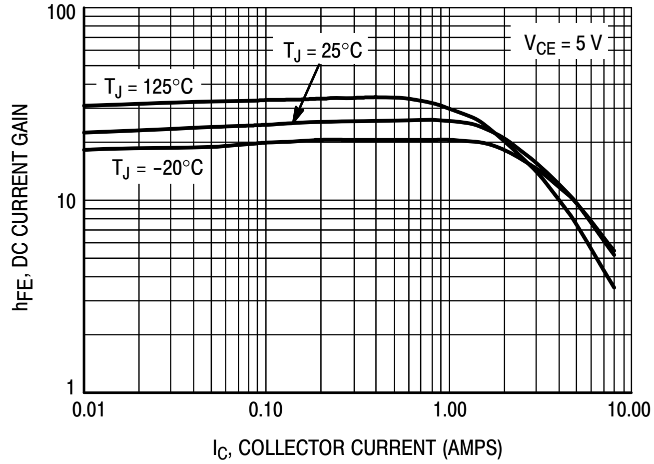


Figure 2. DC Current Gain at @ 5 Volts

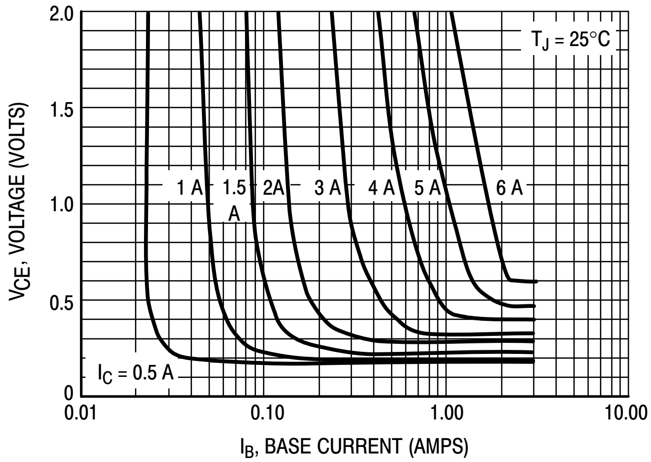


Figure 3. Collector−Emitter Saturation Region

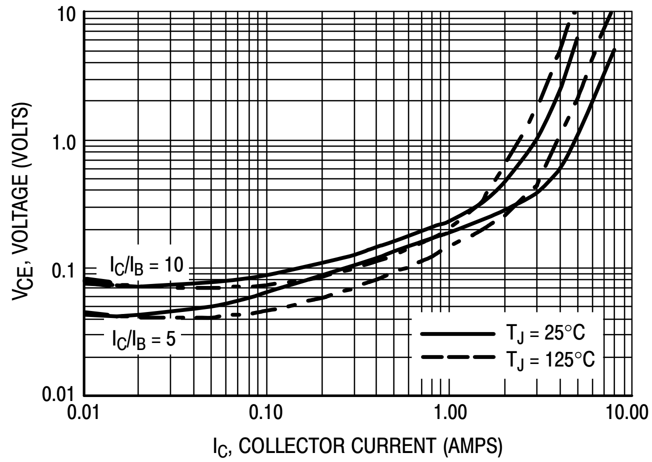


Figure 4. Collector−Emitter Saturation Voltage

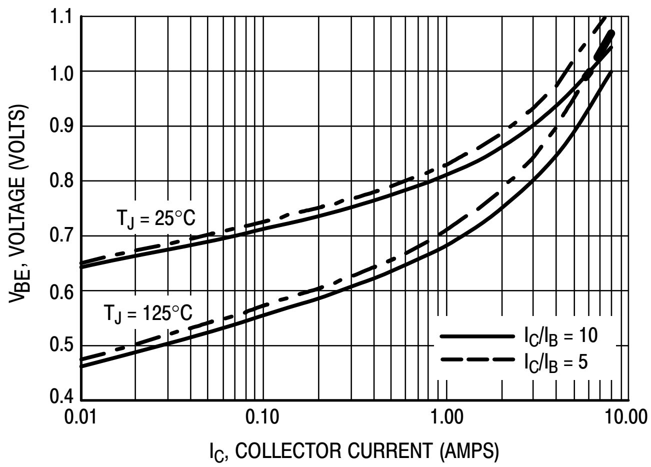


Figure 5. Base−Emitter Saturation Region

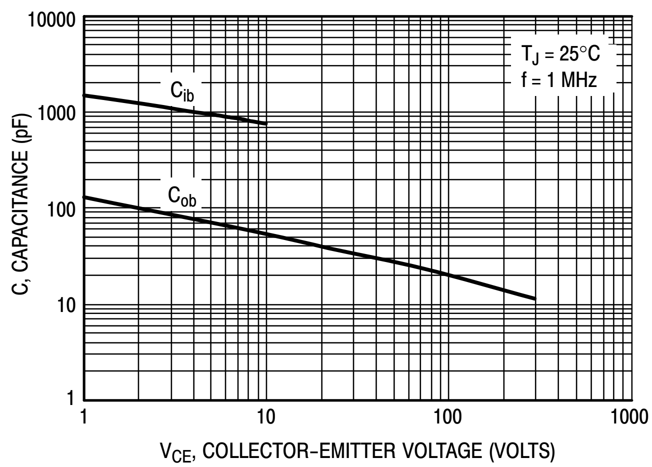


Figure 6. Capacitance

TYPICAL SWITCHING CHARACTERISTICS
($I_{B2} = I_C/2$ for all switching)

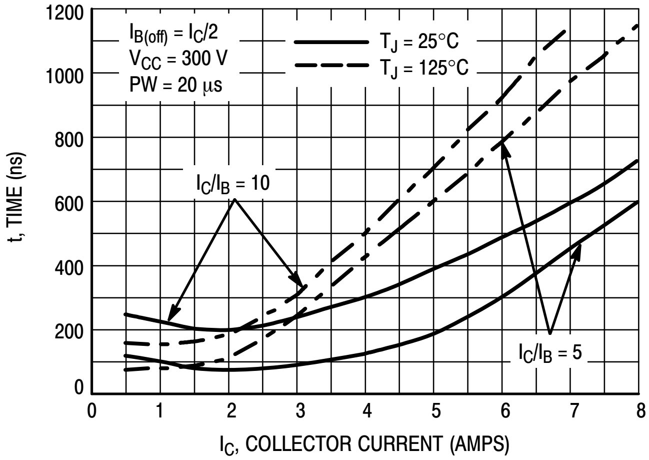


Figure 7. Resistive Switching, t_{on}

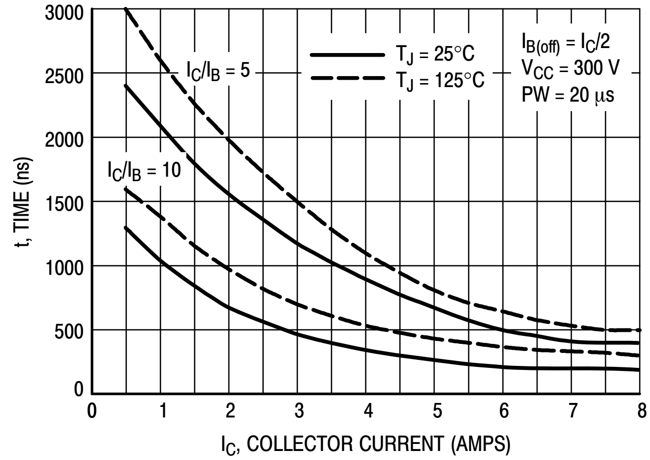


Figure 8. Resistive Switching, t_{off}

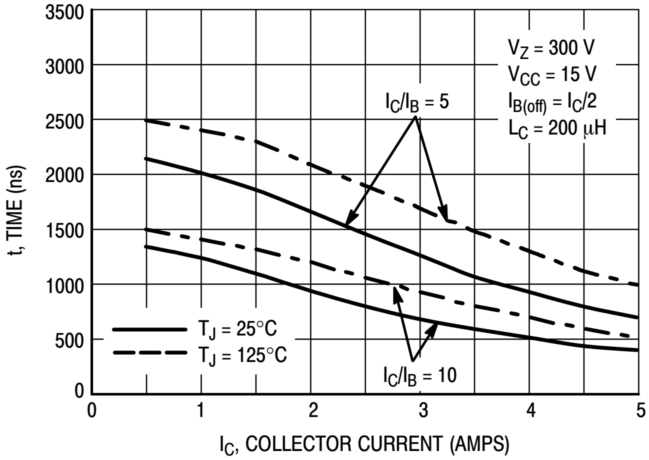


Figure 9. Inductive Storage Time, t_{si}

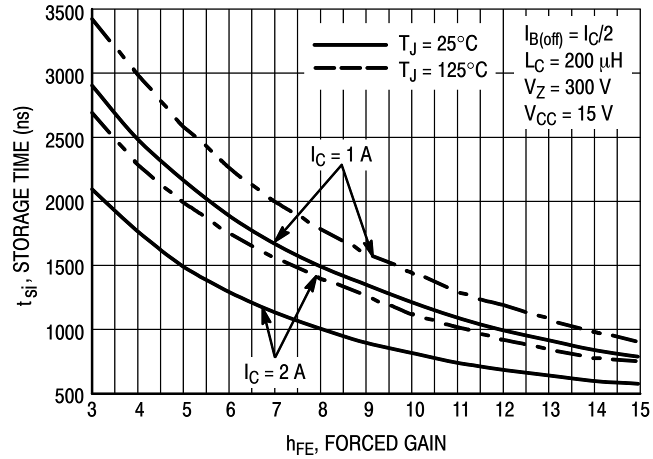


Figure 10. Inductive Storage Time, $t_{si}(h_{FE})$

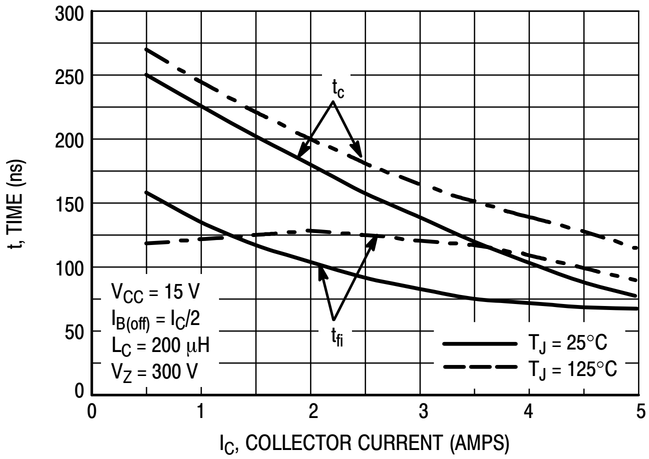


Figure 11. Inductive Switching, t_c & t_{fi}, $I_C/I_B = 5$

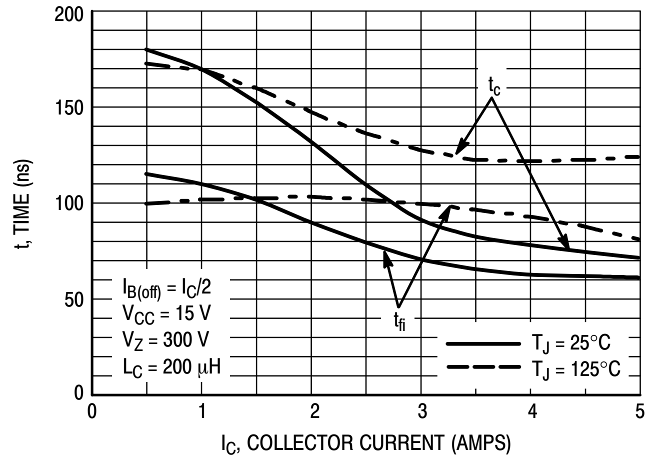


Figure 12. Inductive Switching, t_c & t_{fi}, $I_C/I_B = 10$

TYPICAL SWITCHING CHARACTERISTICS
($I_{B2} = I_C/2$ for all switching)

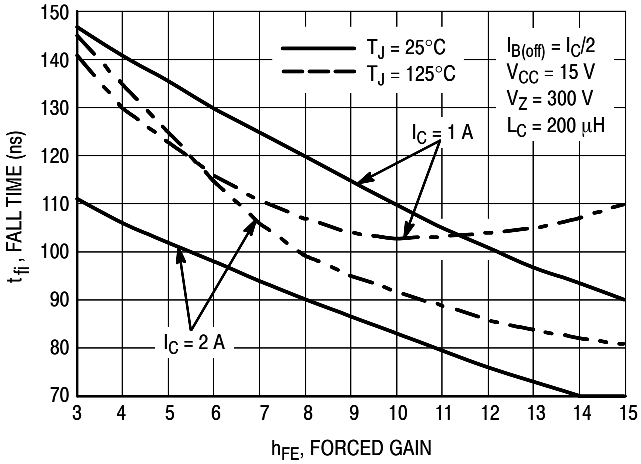


Figure 13. Inductive Fall Time, $t_{fi}(h_{FE})$

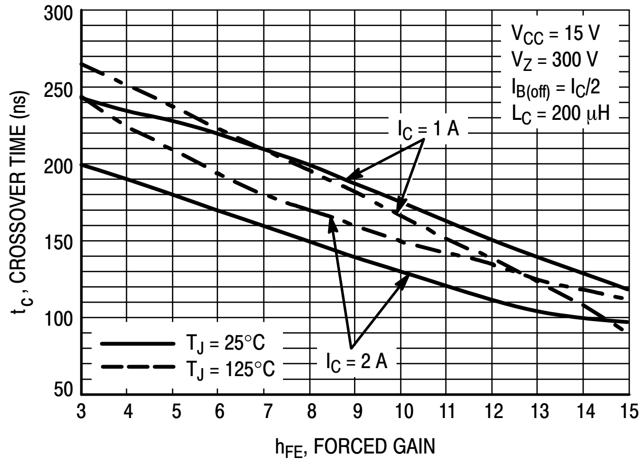


Figure 14. Crossover Time

GUARANTEED SAFE OPERATING AREA INFORMATION

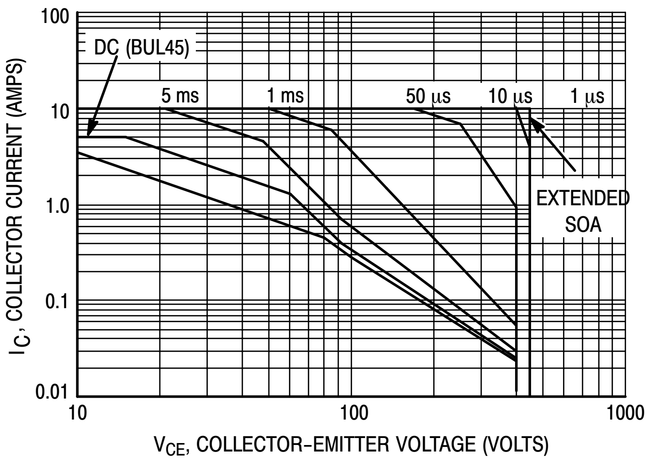


Figure 15. Forward Bias Safe Operating Area

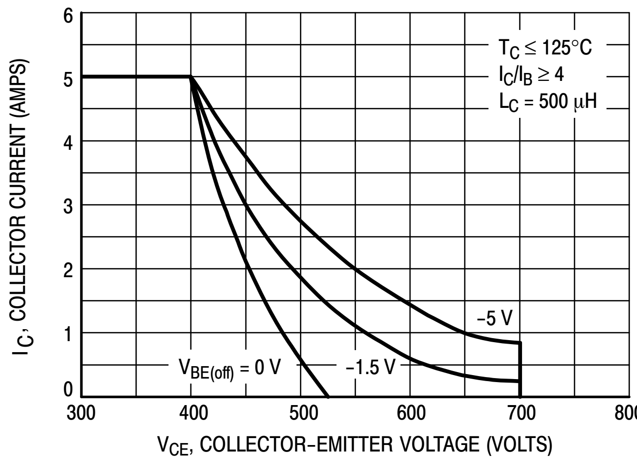


Figure 16. Reverse Bias Switching Safe Operating Area

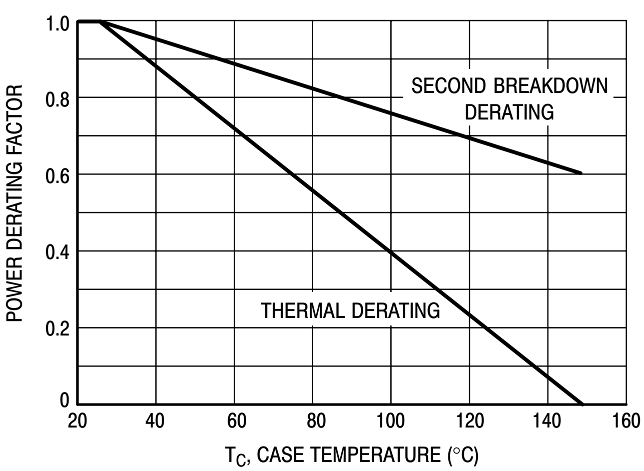


Figure 17. Forward Bias Power Derating

There are two limitations on the power handling ability of a transistor: average junction temperature and second breakdown. Safe operating area curves indicate $I_C - V_{CE}$ limits of the transistor that must be observed for reliable operation; i.e., the transistor must not be subjected to greater dissipation than the curves indicate. The data of Figure 15 is based on T_C = 25°C; $T_{J(pk)}$ is variable depending on power level. Second breakdown pulse limits are valid for duty cycles to 10% but must be derated when $T_C \ge$ 25°C. Second breakdown limitations do not derate the same as thermal limitations. Allowable current at the voltages shown in Figure 15 may be found at any case temperature by using the appropriate curve on Figure 17. $T_{J(pk)}$ may be calculated from the data in Figures 20. At any case temperatures, thermal limitations will reduce the power that can be handled to values less than the limitations imposed by second breakdown. For inductive loads, high voltage and current must be sustained simultaneously during turn−off with the base−to−emitter junction reverse−biased. The safe level is specified as a reverse−biased safe operating area (Figure 16). This rating is verified under clamped conditions so that the device is never subjected to an avalanche mode.

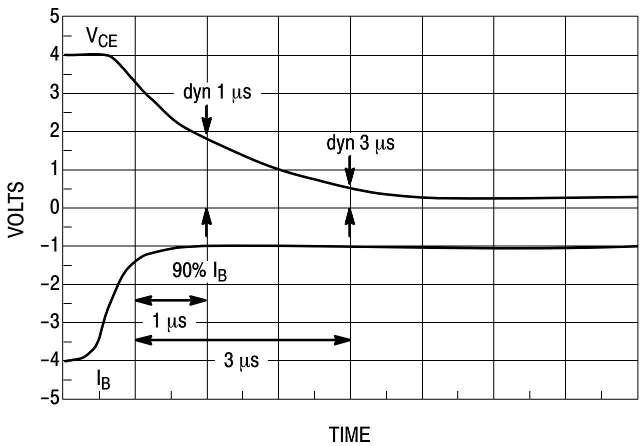


Figure 18. Dynamic Saturation Voltage Measurements

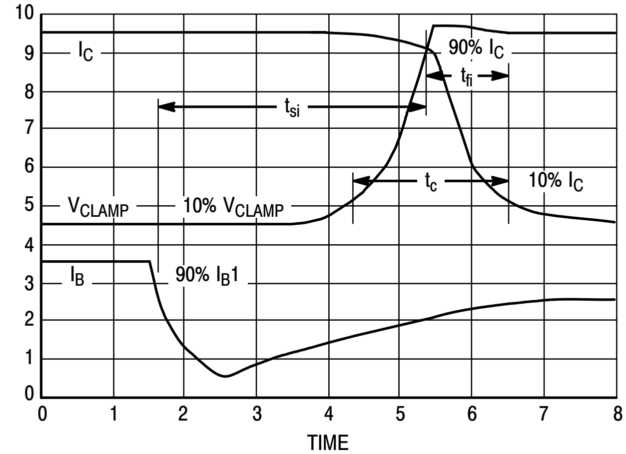
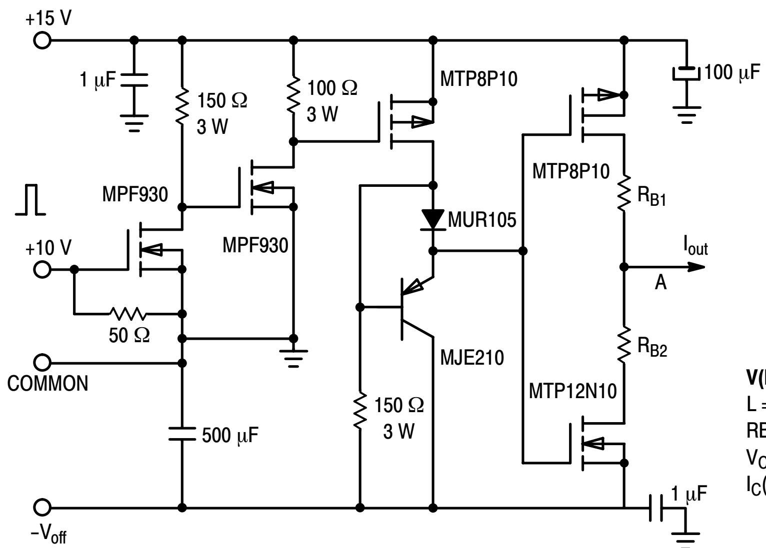
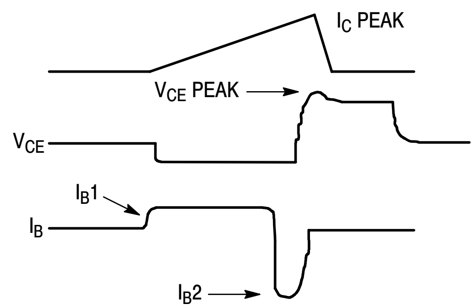


Figure 19. Inductive Switching Measurements





V(BR)CEO(sus)	**INDUCTIVE SWITCHING**	**RBSOA**
L = 10 mH	L = 200 µH	L = 500 µH
RB2 = ∞	RB2 = 0	RB2 = 0
V_{CC} = 20 VOLTS	V_{CC} = 15 VOLTS	V_{CC} = 15 VOLTS
I_C(pk) = 100 mA	RB1 SELECTED FOR DESIRED I_B1	RB1 SELECTED FOR DESIRED I_B1

Table 1. Inductive Load Switching Drive Circuit

TYPICAL THERMAL RESPONSE

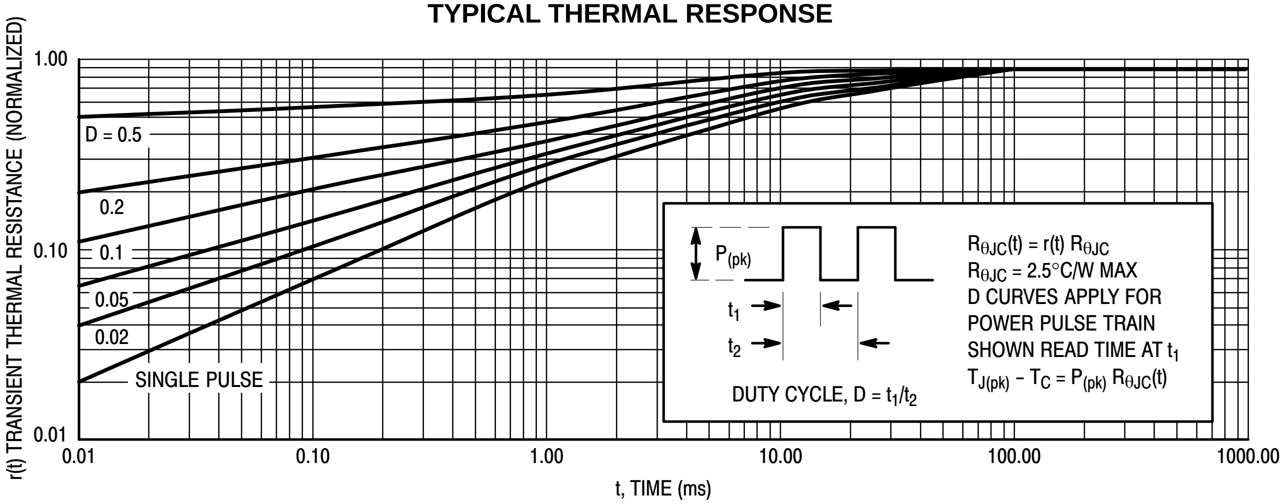
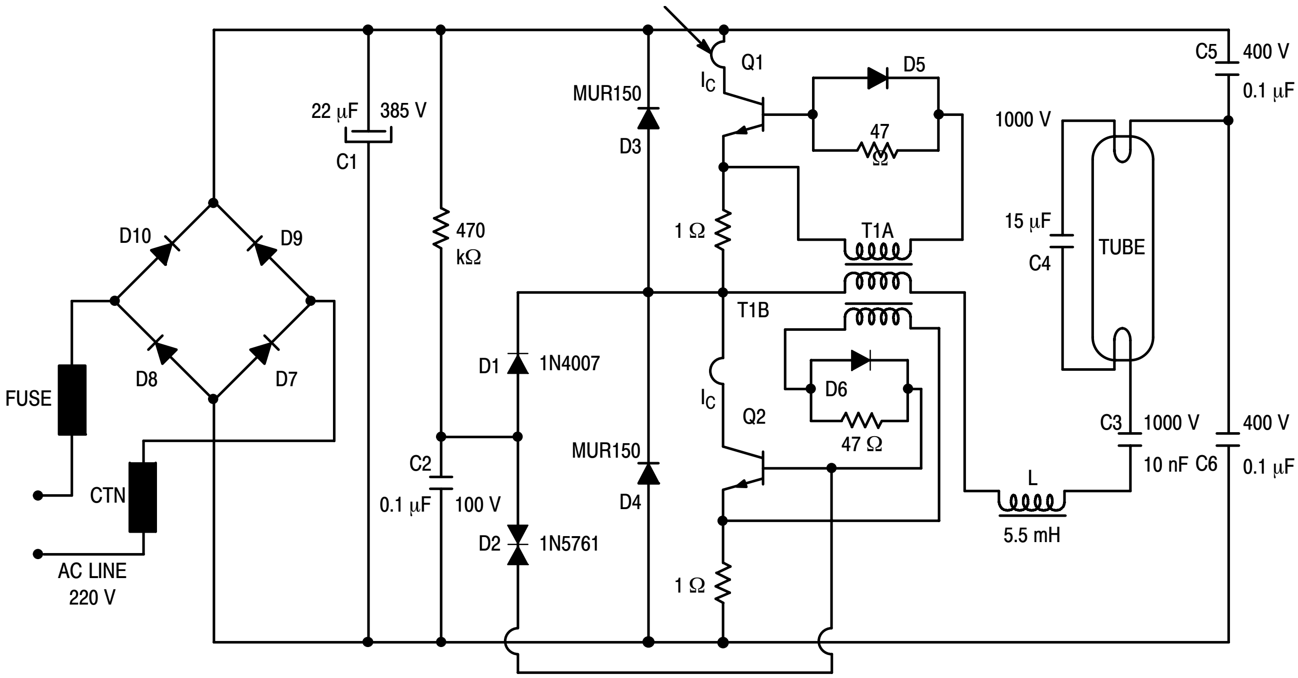


Figure 20. Typical Thermal Response ($Z_{\theta JC}(t)$) for BUL45

The BUL45 Bipolar Power Transistors were specially designed for use in electronic lamp ballasts. A circuit designed by ON Semiconductor applications was built to demonstrate how well these devices operate. The circuit and detailed component list are provided below.



Components Lists

Q1 = Q2 = BUL45 Transistor
D1 = 1N4007 Rectifier
D2 = 1N5761 Rectifier
D3 = D4 = MUR150
D5 = D6 = MUR105
D7 = D8 = D9 = D10 = 1N400
CTN = 47 Ω @ 25°C
L = RM10 core, A1 = 400, B51 (LCC) 75 turns, wire ∅ = 0.6 mm
T1 = FT10 toroid, T4A (LCC)
Primary: 4 turns
Secondaries: T1A: 4 turns
T1B: 4 turns

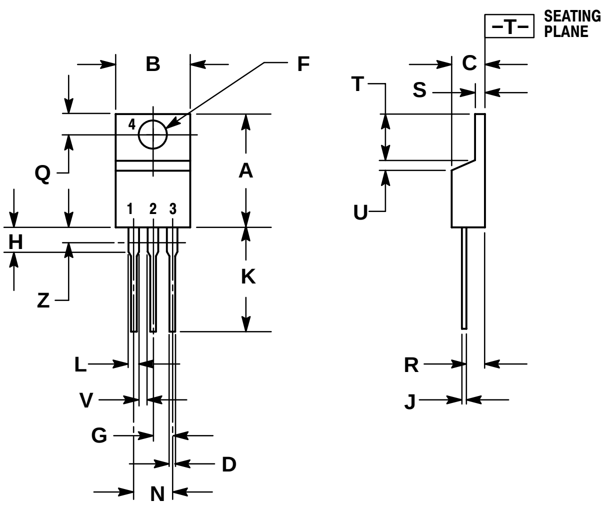
All resistors are 1/4 Watt, ±5%
R1 = 470 kΩ
R2 = R3 = 47 Ω
R4 = R5 = 1 Ω (these resistors are optional, and might be replaced by a short circuit)
C1 = 22 µF/385 V
C2 = 0.1 µF
C3 = 10 nF/1000 V
C4 = 15 nF/1000 V
C5 = C6 = 0.1 µF/400 V

NOTES:
1. Since this design does not include the line input filter, it cannot be used “as−is” in a practical industrial circuit.
2. The windings are given for a 55 Watt load. For proper operation they must be re−calculated with any other loads.

Figure 21. Application Example

PACKAGE DIMENSIONS

TO−220AB
CASE 221A−09
ISSUE AA



NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION Z DEFINES A ZONE WHERE ALL BODY AND LEAD IRREGULARITIES ARE ALLOWED.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.570	0.620	14.48	15.75
B	0.380	0.405	9.66	10.28
C	0.160	0.190	4.07	4.82
D	0.025	0.035	0.64	0.88
F	0.142	0.147	3.61	3.73
G	0.095	0.105	2.42	2.66
H	0.110	0.155	2.80	3.93
J	0.018	0.025	0.46	0.64
K	0.500	0.562	12.70	14.27
L	0.045	0.060	1.15	1.52
N	0.190	0.210	4.83	5.33
Q	0.100	0.120	2.54	3.04
R	0.080	0.110	2.04	2.79
S	0.045	0.055	1.15	1.39
T	0.235	0.255	5.97	6.47
U	0.000	0.050	0.00	1.27
V	0.045	---	1.15	---
Z	---	0.080	---	2.04

STYLE 1:
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