

MP Motion Sensor (AMN2, 3, 4)

TYPICAL APPLICATIONS

1. Home appliance market: Air conditioner, air purifier and fan heater

2. Construction equipment: lighting, automatic switches

3. Commercial equipment: vending machines, facilities for designated smoking areas
4. Anti-crime device market: crime prevention sensor, simple anti-crime devices, surveillance cameras

ORDERING INFORMATION

AMN

1

Output type

2: Analog output

3: Digital output

4: Low current consumption (digital output)

Detection performance

1: Standard detection type

2: Slight motion detection type

3: Spot detection type

4: 10m detection type

Feature

1: PC board mounting type

Operating voltage

1: 5V DC

2: 3V DC

Lens color

1: Black

2: White

PRODUCT TYPES

Detection performance	Output type	Digital output	Low current consumption type	Analog output
	Lens color		Digital output	
Standard detection type	Black	AMN31111	AMN41121	AMN21111
	White	AMN31112	AMN41122	AMN21112
Slight motion detection type	Black	AMN32111	AMN42121	AMN22111
	White	AMN32112	AMN42122	AMN22112
Spot detection type	Black	AMN33111	AMN43121	AMN23111
	White	AMN33112	AMN43122	AMN23112
10m detection type	Black	AMN34111	AMN44121	AMN24111
	White	AMN34112	AMN44122	AMN24112

Standard packing: Carton: 50 pcs.; Case: 1,000 pcs.

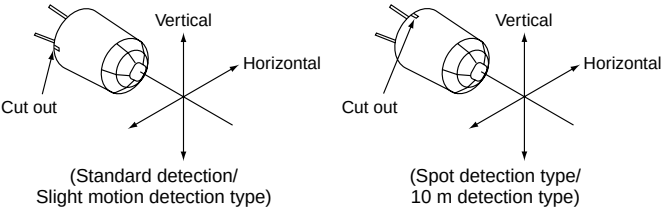
RATING

1. Detection performance

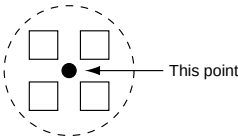
Items		Standard detection type	Slight motion detection type	Spot detection type	10m detection type	Conditions of objects to be detected
Rated detection distance Note 1)		Max. 5m 16.404ft	Max. 2m 6.562ft	Max. 5m 16.404ft	Max. 10m 32.808ft	
Detection range	Horizontal Note 2)	100°	91°	38°	110°	1. Detectable difference in temperature between the target and background is more than 4°C 7.2°F. 2. Movement speed 1) Digital output type • Standard detection type/Spot detection type/ 10m detection type: 0.8 to 1.2 m/s • Slight motion detection type: 0.5 m/s 2) Analog output and low current consumption types • Standard detection type/Spot detection type/ 10m detection type: 0.5 to 1.5 m/s • Slight motion detection type: 0.3 to 1.0 m/s 3. Detection object = human body (size is 700mm × 250mm 27.559inch × 9.843inch, but for the slight motion detection type the size is 200mm × 200mm 7.874inch × 7.874inch)
	Vertical Note 2)	82°	91°	22°	93°	
	Detection zone Note 3)	64 zones	104 zones	24 zones	80 zones	

Notes: 1. Depending on the difference in temperature between the background and detection target and the speed at which the target moves, these sensors may be capable of detection beyond the detection distances stated above. Nevertheless, they should be used within the prescribed detection distances. For further details, refer to the detection range diagram on page 24.

2.



This angle represents the center point of the detection zone created by the outermost lens.



3. Regarding of detection zone, please refer to "DETECTION PERFORMANCE" on page 24.

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2. Absolute maximum ratings (Measuring condition: ambient temperature = 25°C 77°F) (Common to All types)

Items	Absolute maximum ratings
Power supply voltage	−0.3 to 7 V DC
Usable ambient temperature	−20 to 60°C −4 to +140°F (No freezing and condensing at low temperature.)
Storage temperature	−20 to 70°C −4 to +158°F

3. Electrical characteristics (Common to All types)

1) Digital output

Items	Symbol	Electrical characteristics () is low current consumption type	Measured conditions () is low current consumption type
Rated operating voltage	Minimum	Vdd	3.0 V DC (2.2 V DC)
	Maximum		6.0 V DC (3.0 V DC)
Rated consumption current (Standby) Note	Typical	Iw	170 μA (46 μA)
	Maximum		300 μA (60 μA)
Output current (when detecting)	Maximum	Iout	100 μA
Output voltage (when detecting)	Minimum	Vout	Vdd −0.5
Circuit stability time	Typical	Twu	7 s
	Maximum		30 s

Note: The current which is consumed during detection consists of the standby consumed current plus the output current.

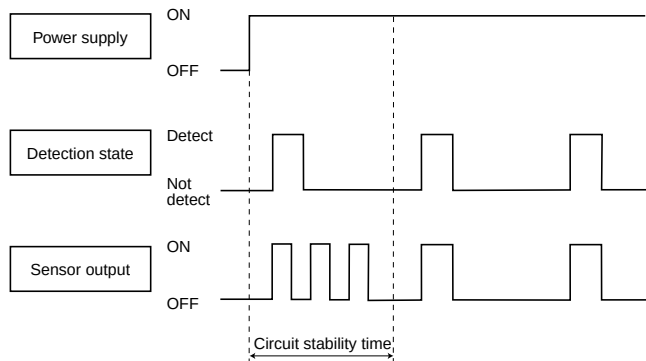
2) Analog output

Items	Symbol	Specified value	Measured conditions
Operating voltage	Minimum	Vdd	4.5 V DC
	Maximum		5.5 V DC
Consumption current	Typical	Iw	170 μA
	Maximum		300 μA
Output current	Maximum	Iout	50 μA
Output voltage range	Minimum	Vout	0 V
	Maximum		Vdd
Output offset average voltage	Minimum	Voff	2.3 V
	Typical		2.5 V
	Maximum		2.7 V
Steady-state noise	Typical	Vn	155 m Vp-p
	Maximum		300 m Vp-p
Detection sensitivity	Minimum	Vh or Vl	0.45 V
Circuit stability time	Maximum	Twu	45 s

Note: To set to the same detection performance as the digital output type, set the output voltage to the offset voltage (2.5V) ±0.45V (i.e. 2.95V or more and 2.05V or less).

TIMING CHART

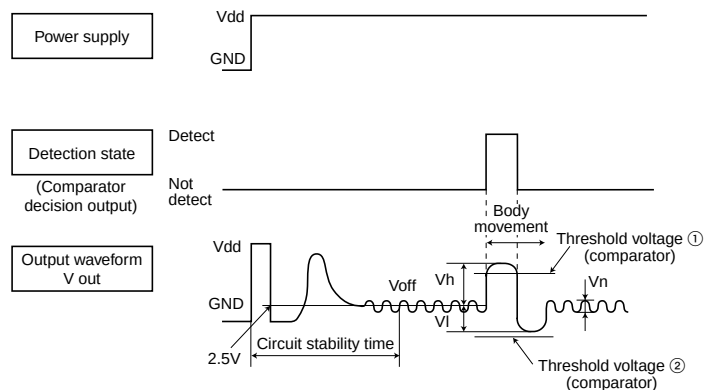
1. Digital output



Note: Circuit stability time: 30s max.

While the circuitry is stabilizing after the power is turned on, the sensor output is not fixed in the "on" state or "off" state. This is true regardless of whether or not the sensor has detected anything.

2. Analog output



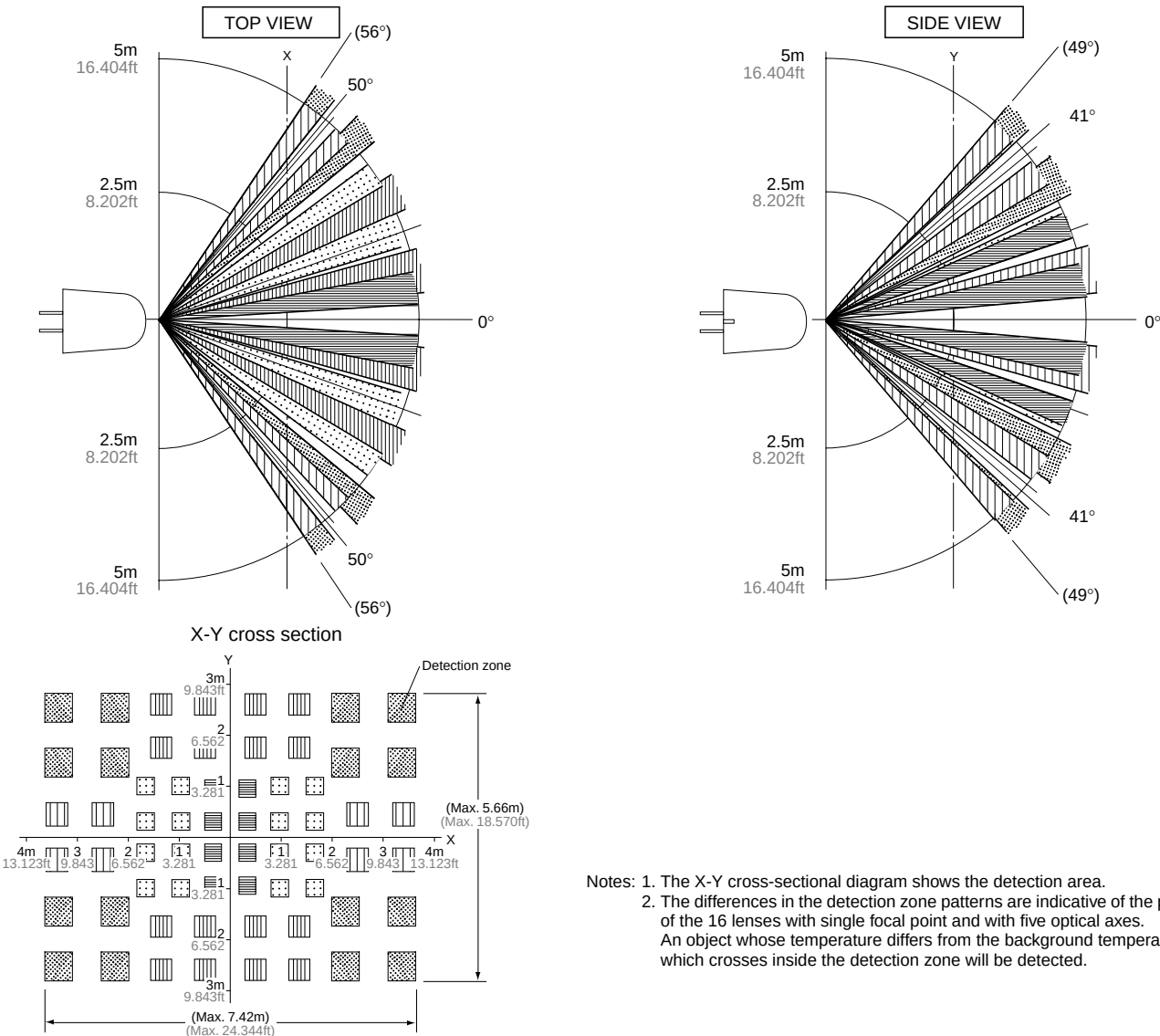
Note: Circuit stability time: 45s max.

While the circuitry is stabilizing after the power is turned on, the sensor output is not fixed in the "on" state or "off" state. This is true regardless of whether or not the sensor has detected anything.

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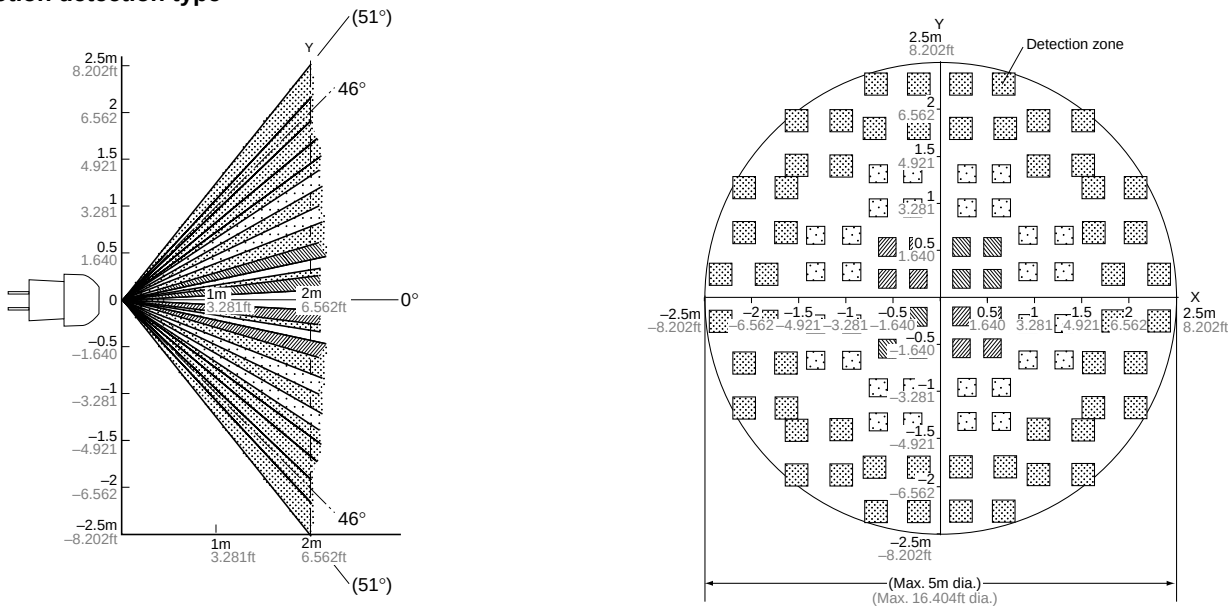
DETECTION PERFORMANCE

1. Standard detection type



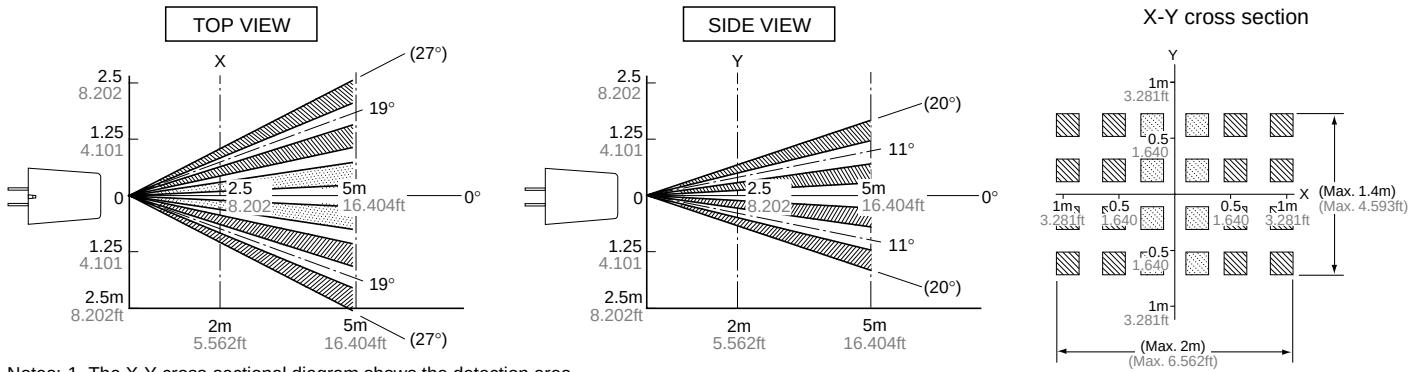
Notes: 1. The X-Y cross-sectional diagram shows the detection area.
2. The differences in the detection zone patterns are indicative of the projections of the 16 lenses with single focal point and with five optical axes. An object whose temperature differs from the background temperature and which crosses inside the detection zone will be detected.

2. Slight motion detection type



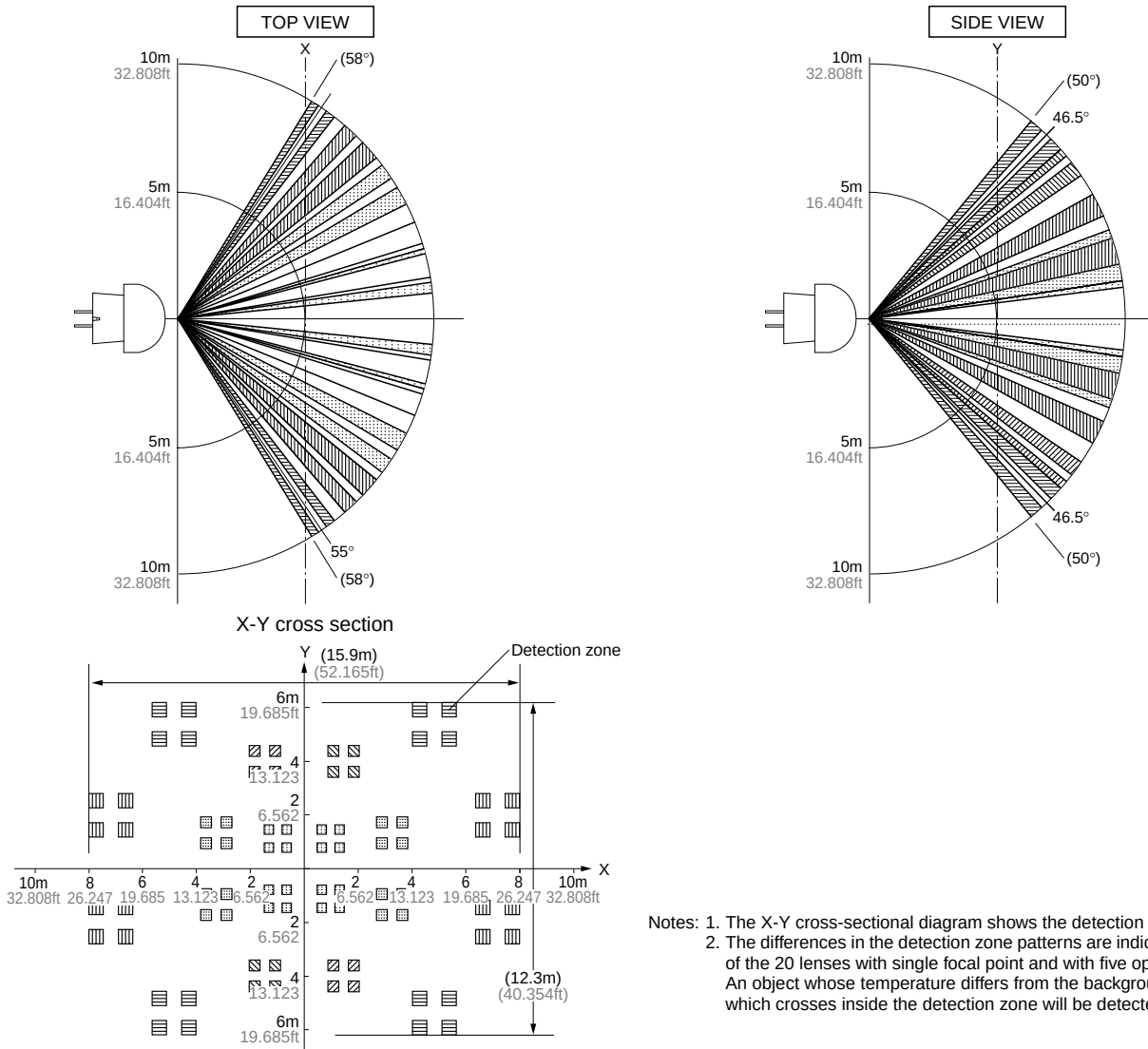
Notes: 1. The X-Y cross-sectional diagram shows the detection area.
2. The differences in the detection zone patterns are indicative of the projections of the 26 lenses with single focal point and with three optical axes. An object whose temperature differs from the background temperature and which crosses inside the detection zone will be detected.

3. Spot detection type



Notes: 1. The X-Y cross-sectional diagram shows the detection area.
 2. The differences in the detection zone patterns are indicative of the projections of the 6 lenses with single focal point and with two optical axes.
 An object whose temperature differs from the background temperature and which crosses inside the detection zone will be detected.

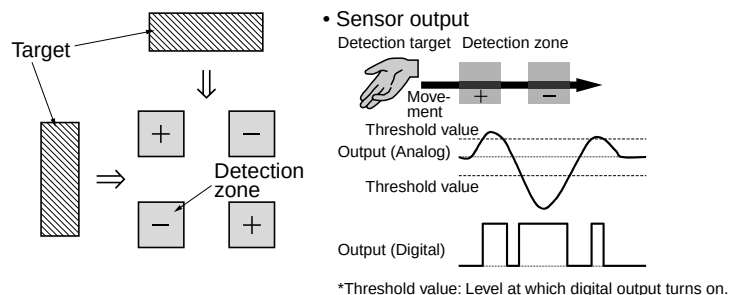
4. 10m detection type



Notes: 1. The X-Y cross-sectional diagram shows the detection area.
 2. The differences in the detection zone patterns are indicative of the projections of the 20 lenses with single focal point and with five optical axes.
 An object whose temperature differs from the background temperature and which crosses inside the detection zone will be detected.

5. Notes regarding the detection zone

The detection zone has the polarity shown in the diagram on the right.
 When targets enter both the + and - zones with the same timing, the signals are cancelled each other, thus in this case there is a possibility that the object cannot be detected at the maximum specified detection distance.

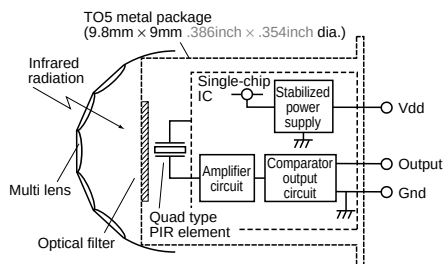


MP Motion Sensor (AMN2, 3, 4)

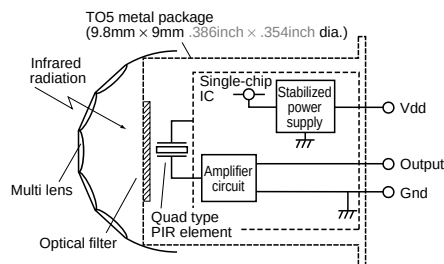
HOW TO USE

1. Block diagram output circuit

1) Block diagram of the digital output circuit

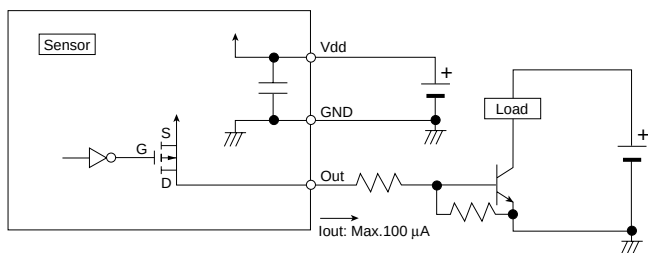


2) Block diagram of the analog output circuit



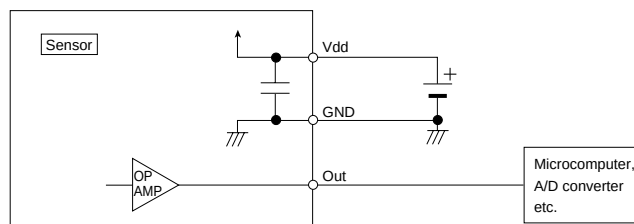
2. Wiring diagram

1) Digital output



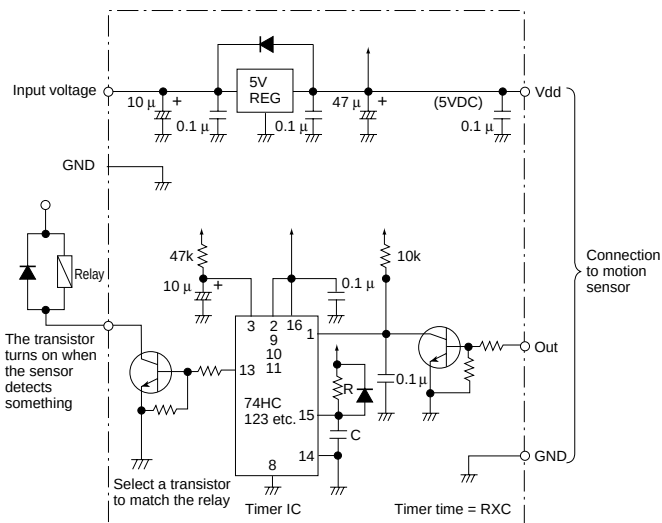
Vdd: Input power source (DC)
GND: GND
Out: Output (Comparator)

2) Analog output

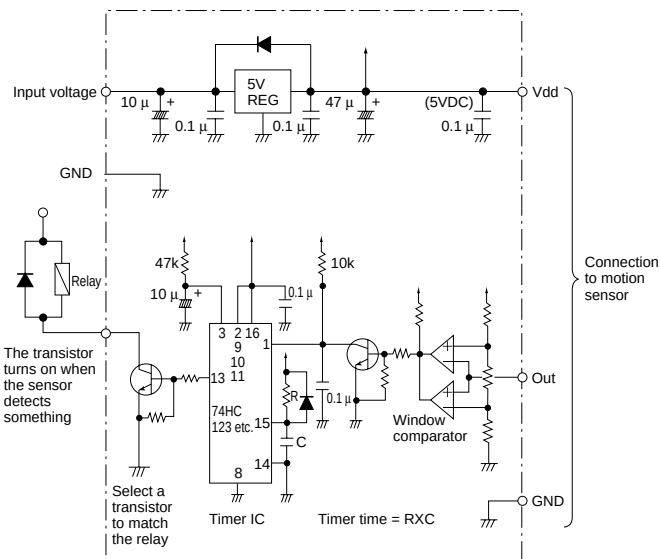


3. Timer circuit example

1) Digital output



2) Analog output

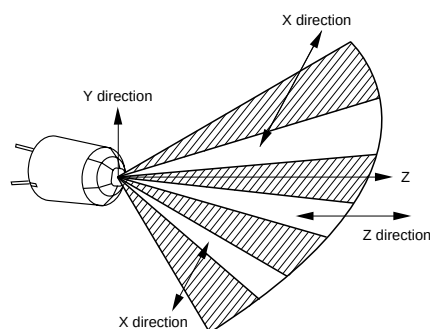


Note: This is the reference circuit which drives the MP motion sensor. Install a noise filter for applications requiring enhanced detection reliability and noise withstanding capability.
Differences in the specifications of electronic components to which the units are connected sometimes affect their correct operation; please check the units' performance and reliability for each application.
Panasonic Corporation accepts no responsibility for damages resulting from the use of this circuit.

4. Installation

Install the sensor so that people will be entering from the X direction shown below.

(If persons approach the sensor from the Z direction, detection distance will be shortened.)



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DIMENSIONS (mm inch)

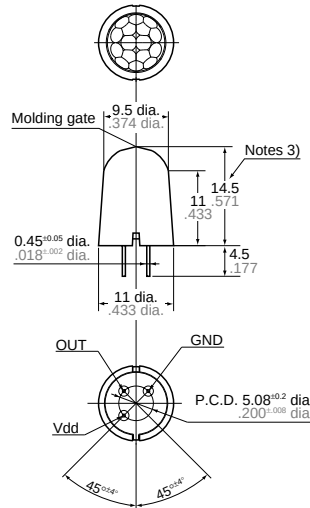
The CAD data of the products with a **CAD Data** mark can be downloaded from: <http://industrial.panasonic.com/ac/e>

1. Standard detection type

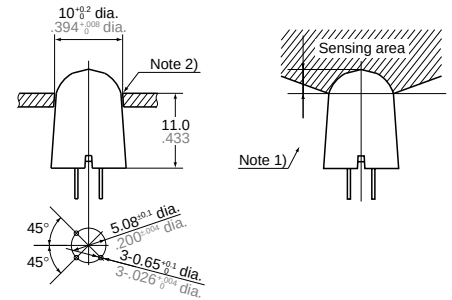
CAD Data



General tolerance $\pm 0.5 \pm .020$



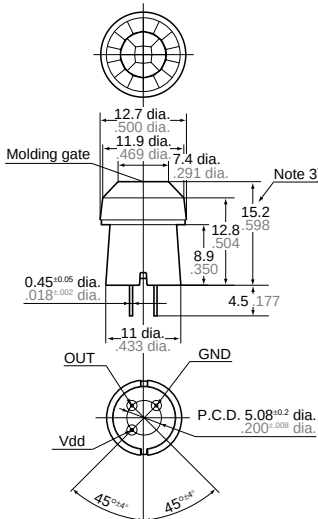
Recommended panel mounting hole



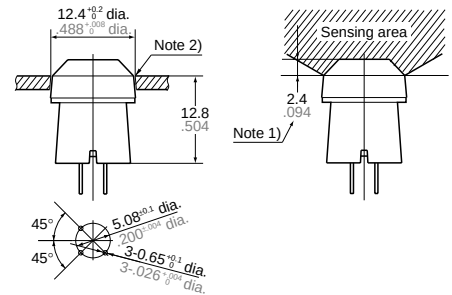
- Notes: 1. In order to ensure proper detection, install it with the lens exposed at least 3.5mm .138inch.
2. As for panel mounting hole, tapering or making a large size hole should be done.
3. The height dimension does not include the remaining molding gate.

2. Slight motion detection type

CAD Data



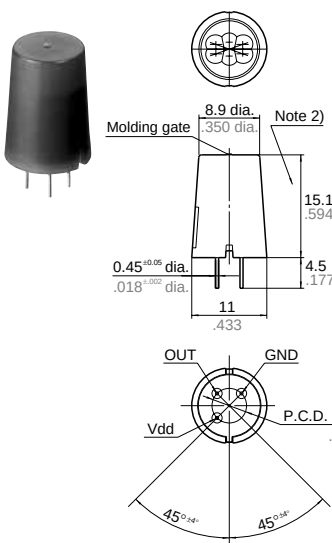
Recommended panel mounting hole



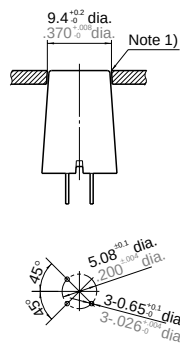
- Notes: 1. In order to ensure proper detection, install it with the lens exposed at least 2.4mm .094inch.
2. As for panel mounting hole, tapering or making a large size hole should be done.
3. The height dimension does not include the remaining molding gate.

3. Spot detection type

CAD Data



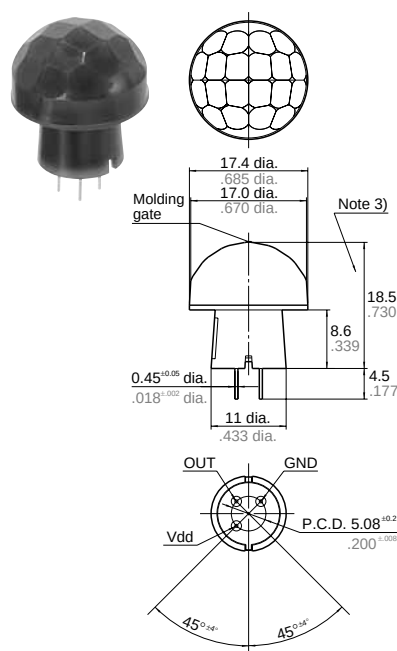
Recommended panel mounting hole



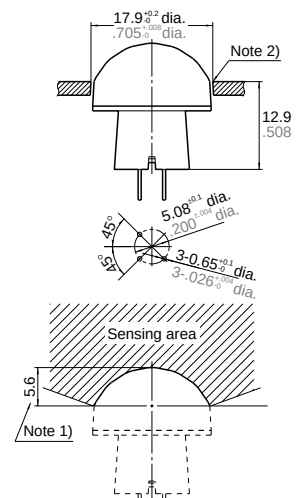
- Notes: 1. As for panel mounting hole, tapering or making a large size hole should be done.
2. The height dimension does not include the remaining molding gate.

4. 10m detection type

CAD Data



Recommended panel mounting hole



- Notes: 1. In order to ensure proper detection, install it with the lens exposed at least 5.6mm .220inch.
2. As for panel mounting hole, tapering or making a large size hole should be done.
3. The height dimension does not include the remaining molding gate.

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NOTES

1. Checkpoints relating to principle of operation

MP motion sensors are passive infrared sensors which detect changes in the infrared rays. They may fail to detect successfully if a heat source other than a human being is detected or if there are no temperature changes in or movement of a heat source. Care must generally be taken in the following cases. The performance and reliability of the sensors must be checked out under conditions of actual use.

1) Cases where a heat source other than a human being is detected.

- (1) When a small animal enters the detection range.
- (2) When the sensor is directly exposed to sunlight, a vehicle's headlights, an incandescent light or some other source of far infrared rays.
- (3) When the temperature inside the detection range has changed suddenly due to the entry of cold or warm air from an air-conditioning or heating unit, water vapor from a humidifier, etc.

2) Cases where it is difficult to detect the heat source

- (1) When an object made of glass, acrylic or other subject which far infrared rays have difficulty passing through is located between the sensor and what is to be detected.
- (2) When the heat source inside the detection range hardly moves or when it moves at high speed; for details on the movement speed, refer to the section on the performance ratings.

2. When the detection area becomes larger

When the difference between the ambient temperature and body temperature is large (more than 20°C 68°F), detection may occur in isolated areas outside the specified detection range.

3. Other handling cautions

- 1) Be careful not to allow dust or dirt to accumulate on the lens as this will adversely affect the detection sensitivity.
- 2) The lens is made of a soft material (polyethylene).
Avoid applying a load or impact since this will deform or scratch the lens, making proper operation impossible and causing a deterioration in its performance.
- 3) The sensor may be damaged if it is exposed to static with a voltage exceeding $\pm 200\text{V}$. Therefore, do not touch its terminals directly, and exercise adequate care in the handling of the sensor.
- 4) When the leads are to be soldered, solder them by hand for less than 3 seconds at a temperature of less than 350°C 662°F at the tip of the soldering iron. Avoid using a solder bath since this will cause a deterioration in the sensor's performance.
- 5) Do not attempt to clean the sensor. Cleaning fluid may enter inside the lens area causing a deterioration in performance.
- 6) When using the sensors with cables, it is recommended that cables which are shielded and as short as possible be used in order to safeguard against the effects of noise.

For Cautions for Use.