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## REVISION HISTORY

### 8/15—Rev. A to Rev. B

|                            |    |
|----------------------------|----|
| Changes to Figure 51 ..... | 15 |
|----------------------------|----|

### 5/14—Rev. 0 to Rev. A

|                                  |   |
|----------------------------------|---|
| Change to Features Section ..... | 1 |
|----------------------------------|---|

### 11/12—Revision 0: Initial Version

## SPECIFICATIONS

$V_{IN} = 4.5\text{ V to }36\text{ V}$ ,  $T_J = -40^{\circ}\text{C to }+125^{\circ}\text{C}$ , unless otherwise noted.

Table 1.

| Parameter  | Symbol           | Test Conditions/Comments                            | Min   | Typ   | Max                 | Unit               |
|--|------------------|---|-------|-------|---------------------|--------------------|
| <b>POWER SUPPLY</b>  |                  |   |       |       |                     |                    |
| Input Voltage Range  | $V_{IN}$         |   | 4.5   |       | 36                  | V                  |
| Supply Current   | $I_{VIN}$        | $V_{EN} = 1.5\text{ V}$ not switching               |       | 1.7   | 2                   | mA                 |
| Shutdown Current   | $I_{SHDN}$       | $V_{EN} = \text{AGND}$                              |       | 10    | 15                  | $\mu\text{A}$      |
| UVLO   |                  |   |       |       |                     |                    |
| Threshold  | $V_{UVLO}$       | $V_{IN}$ falling                                    | 3.8   | 4     | 4.2                 | V                  |
| Hysteresis   |                  |   |       | 200   |                     | mV                 |
| <b>INTERNAL REGULATOR</b>                                      |                  |   |       |       |                     |                    |
| Regulator Output Voltage                                       | $V_{CC}$         | $V_{IN} = 5\text{ V to }36\text{ V}$                |       | 5     | 5.5                 | V                  |
| <b>OUTPUT</b>  |                  |   |       |       |                     |                    |
| Output Voltage Range   | $V_{OUT}$        |   | 0.6   |       | $0.9 \times V_{IN}$ | V                  |
| Maximum Output Current   | $I_{OUT}$        |   | 1     |       |                     | A                  |
| Feedback Regulation Voltage                                    | $V_{FB}$         | $T_J = -40^{\circ}\text{C to }+85^{\circ}\text{C}$  | 0.594 | 0.6   | 0.606               | V                  |
|  |                  | $T_J = -40^{\circ}\text{C to }+125^{\circ}\text{C}$ | 0.591 | 0.6   | 0.609               | V                  |
| Line Regulation  |                  |   |       | 0.005 |                     | %/V                |
| Load Regulation  |                  |   |       | 0.05  |                     | %/A                |
| <b>ERROR AMPLIFIER</b>   |                  |   |       |       |                     |                    |
| Feedback Bias Current  | $I_{FB\_BIAS}$   | $V_{FB} = 0.6\text{ V}$                             |       | 50    | 200                 | nA                 |
| Transconductance   | $g_m$            | $I_{COMP} = \pm 20\text{ }\mu\text{A}$              | 200   | 250   | 300                 | $\mu\text{A/V}$    |
| Open-Loop Voltage Gain <sup>1</sup>                            | $A_{VOL}$        |   |       | 65    |                     | dB                 |
| <b>MOSFETS</b>   |                  |   |       |       |                     |                    |
| High-Side Switch On Resistance <sup>2</sup>                    | $R_{DS\_H(ON)}$  | BST – SW = 5 V                                      |       | 170   | 270                 | m $\Omega$         |
| Low-Side Switch On Resistance <sup>2</sup>                     | $R_{DS\_L(ON)}$  | $V_{CC} = 5\text{ V}$                               |       | 120   | 180                 | m $\Omega$         |
| Leakage Current  | $I_{LKG}$        | $V_{EN} = \text{AGND}$                              |       | 1     | 25                  | $\mu\text{A}$      |
| Minimum On Time <sup>3</sup>                                   | $t_{ON\_MIN}$    | All switching frequencies                           |       | 50    | 65                  | ns                 |
| Minimum Off Time <sup>4</sup>                                  | $t_{OFF\_MIN}$   |   |       | 165   | 175                 | ns                 |
| <b>CURRENT SENSE</b>   |                  |   |       |       |                     |                    |
| Current Sense Amplifier Gain                                   | $G_{CS}$         |   | 1.6   | 2     | 2.4                 | A/V                |
| Hiccup Time  |                  | $f_{SW} = 300\text{ kHz to }1\text{ MHz}$           |       | 6     |                     | ms                 |
| Number of Cumulative Current-Limit Cycles to Enter Hiccup Mode |                  |   |       | 8     |                     | Events             |
| Peak Current Limit   | $I_{CL}$         |   | 1.4   | 1.6   | 1.8                 | A                  |
| <b>FREQUENCY</b>   |                  |   |       |       |                     |                    |
| Switching Frequency Range                                      | $f_{SW}$         |   | 300   |       | 1000                | kHz                |
| Frequency Set Accuracy   |                  | FREQ pin = 308 k $\Omega$                           | 270   | 300   | 330                 | kHz                |
|  |                  | FREQ pin = 92.5 k $\Omega$                          | 900   | 1000  | 1100                | kHz                |
| Frequency Synchronization Range                                |                  |   | 300   |       | 1000                | kHz                |
| <b>SOFT START</b>  |                  |   |       |       |                     |                    |
| Soft Start Time  | $t_{SS}$         |   |       | 2     |                     | ms                 |
| <b>PRECISION ENABLE</b>  |                  |   |       |       |                     |                    |
| Input Threshold  | $V_{EN(RISING)}$ |   | 1.15  | 1.20  | 1.25                | V                  |
| Hysteresis   | $V_{EN(HYST)}$   |   |       | 100   |                     | mV                 |
| Leakage Current  | $I_{IEN\_LEAK}$  | $V_{IN} = V_{EN}$                                   |       | 0.1   | 1                   | $\mu\text{A}$      |
| Thermal Shutdown   |                  |   |       |       |                     |                    |
| Rising   | $T_{SD}$         |   |       | 150   |                     | $^{\circ}\text{C}$ |
| Hysteresis   | $T_{SD(HYST)}$   |   |       | 25    |                     | $^{\circ}\text{C}$ |

| Parameter                                     | Symbol                  | Test Conditions/Comments           | Min | Typ | Max | Unit             |
|---|-------------------------|------------------------------------|-----|-----|-----|------------------|
| POWER GOOD                                    |                         |                                    |     |     |     |                  |
| PGOOD High, FB Rising Threshold <sup>5</sup>  |                         |                                    | 89  | 92  | 95  | %                |
| PGOOD Low, FB Rising Threshold <sup>5</sup>   |                         |                                    | 111 | 115 | 118 | %                |
| PGOOD High, FB Falling Threshold <sup>5</sup> |                         |                                    | 106 | 109 | 112 | %                |
| PGOOD Low, FB Falling Threshold <sup>5</sup>  |                         |                                    | 83  | 86  | 89  | %                |
| PGOOD   |                         |                                    |     |     |     |                  |
| Delay   | $t_{\text{PGOOD}}$      |                                    |     | 50  |     | $\mu\text{s}$    |
| High Leakage Current                          | $I_{\text{PGOOD(SRC)}}$ | $V_{\text{PGOOD}} = V_{\text{CC}}$ |     | 1   | 10  | $\mu\text{A}$    |
| Pull-Down Resistor                            | $I_{\text{PGOOD(SNK)}}$ | $\text{FB} = 0\text{ V}$           |     | 0.5 | 0.7 | $\text{k}\Omega$ |
| SYNC/MODE                                     |                         |                                    |     |     |     |                  |
| SYNC/MODE Input                               |                         |                                    |     |     |     |                  |
| Logic High                                    |                         |                                    | 2   |     |     | V                |
| Logic Low                                     |                         |                                    |     |     | 0.8 | V                |
| Pulse Width                                   |                         |                                    | 100 |     |     | ns               |

<sup>1</sup> Guaranteed by design.

<sup>2</sup> Measured between VIN and SW pins and includes bond wires and pin resistance.

<sup>3</sup> Based on bench characterization. Measured with  $V_{\text{IN}} = 12\text{ V}$ ,  $V_{\text{OUT}} = 1.2\text{ V}$ , load = 1 A,  $f_{\text{SW}} = 1\text{ MHz}$ , and the output in regulation. Measurement does not include dead time.

<sup>4</sup> Based on bench characterization. Measured with  $V_{\text{IN}} = 15\text{ V}$ ,  $V_{\text{OUT}} = 12\text{ V}$ , load = 1 A,  $f_{\text{SW}} = 600\text{ kHz}$ , and the output in regulation. Measurement does not include dead time.

<sup>5</sup> This threshold is expressed as a percentage of the nominal output voltage.

## ABSOLUTE MAXIMUM RATINGS

Table 2.

| Parameter                                   | Rating          |
|---|-----------------|
| VIN to PGND                                 | −0.3 V to +40 V |
| EN to AGND                                  | −0.3 V to +40 V |
| SW to PGND                                  | −0.3 V to +40 V |
| BST to PGND                                 | −0.3 V to +45 V |
| VCC to AGND                                 | −0.3 V to +6 V  |
| BST to SW                                   | −0.3 V to +6 V  |
| FREQ, PGOOD, SYNC/MODE, COMP,<br>FB to AGND | −0.3 V to +6 V  |
| PGND to AGND                                | ±0.3 V          |
| Operating Junction Temperature<br>Range     | −40°C to +125°C |
| Storage Temperature Range                   | −65°C to +150°C |
| Lead Temperature (Soldering, 10 sec)        | 260°C           |

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## THERMAL RESISTANCE

$\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages based on a 4-layer standard JEDEC board.

Table 3. Thermal Resistance

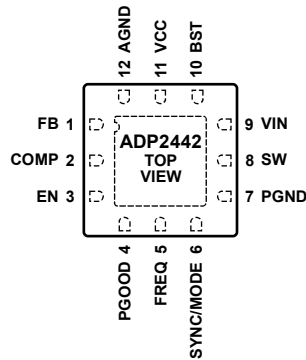
| Package Type  | $\theta_{JA}$ | $\theta_{JC}$ | Unit |
|---------------|---------------|---------------|------|
| 12-Lead LFCSP | 40            | 2.4           | °C/W |

## ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



NOTES  
1. THE EXPOSED PAD SHOULD BE CONNECTED TO THE SYSTEM AGND PLANE AND PGND PLANE.

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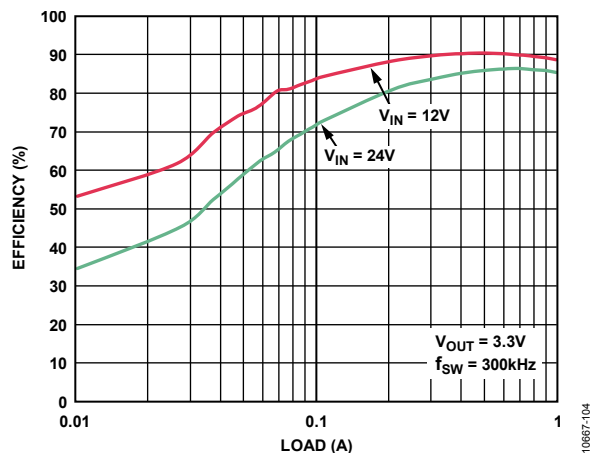
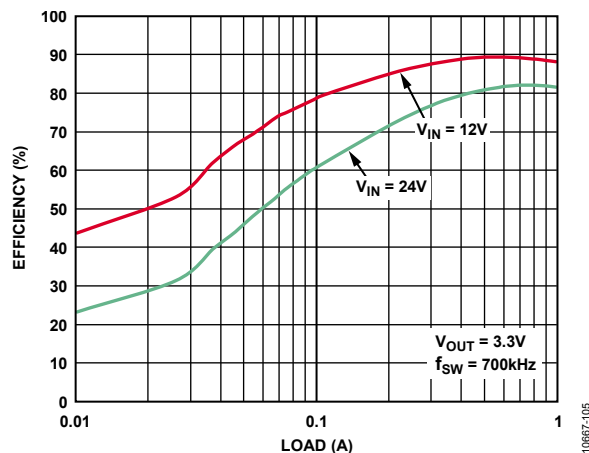
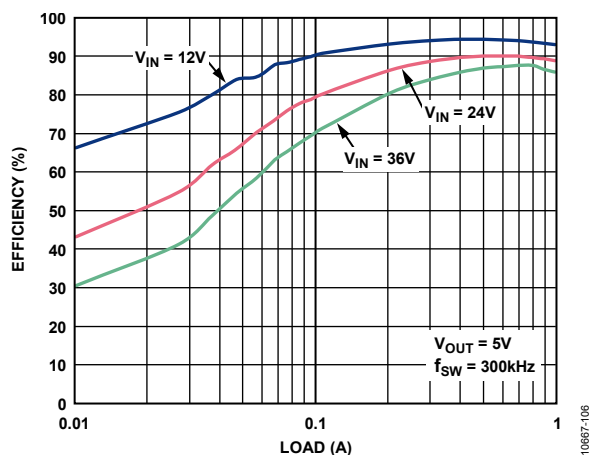
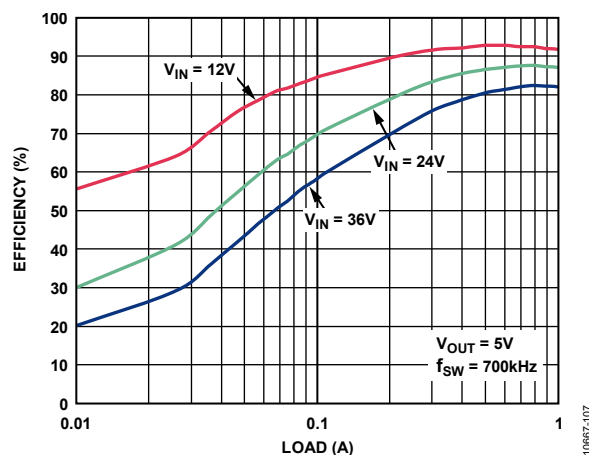
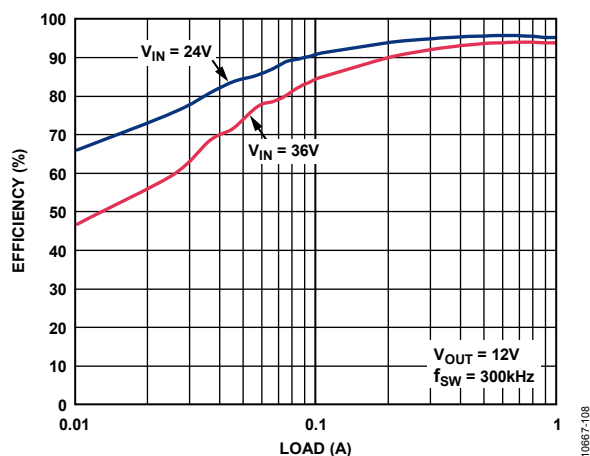
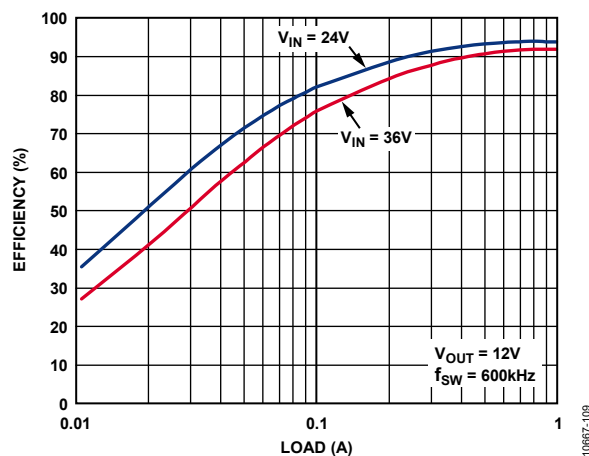
Figure 3. Pin Configuration, Top View

Table 4. Pin Function Descriptions

| Pin No. | Mnemonic   | Description   |
|---------|------------|---|
| 1       | FB         | Feedback. The FB regulation voltage is 0.6 V. Connect this pin to a resistor divider from the output of the dc-to-dc regulator.   |
| 2       | COMP       | Error Amplifier Compensation. Connect a resistor and a capacitor in series to ground.   |
| 3       | EN         | Precision Enable. This features offers $\pm 5\%$ accuracy when using a 1.25 V reference voltage. Pull this pin high to enable the regulator and pull it low to disable the regulator. Do not leave this pin floating.   |
| 4       | PGOOD      | Active High Power Good Output. This pin pulls low when the output is out of regulation.   |
| 5       | FREQ       | Switching Frequency. A resistor to AGND sets the switching frequency (see the Setting the Switching Frequency section). Do not leave this pin floating.   |
| 6       | SYNC/MODE  | External Clock Synchronization/Mode Pin. This pin can be used for external frequency synchronization and for setting forced fixed frequency mode or pulse skip mode. SYNC/MODE accepts an external clock signal, and when pulled high to 5 V, it sets the mode as forced fixed frequency mode. When this pin is tied to AGND, pulse skip mode enables. Do not leave the SYNC/MODE pin floating. |
| 7       | PGND       | Power Ground. Connect a decoupling ceramic capacitor as close as possible between the VIN pin and PGND. Connect this pin directly to the exposed pad.   |
| 8       | SW         | Switch. The midpoint for the drain of the low-side N-channel power MOSFET switch and the source for the high-side N-channel power MOSFET switch.  |
| 9       | VIN        | Power Supply Input. Connect this pin to the input power source, and connect a bypass ceramic capacitor directly from this pin to PGND, as close as possible to the IC. The operation voltage is 4.5 V to 36 V.  |
| 10      | BST        | Boost. Connect a 10 nF ceramic capacitor between the BST and SW pins as close to the IC as possible to form a floating supply for the high-side N-channel power MOSFET driver. This capacitor is required to drive the gate of the N-channel power MOSFET above the supply voltage.   |
| 11      | VCC        | Output of the Internal Low Dropout Regulator. This pin supplies power for the internal controller and driver circuitry. Connect a 1 $\mu$ F ceramic capacitor between VCC and AGND and a 1 $\mu$ F ceramic capacitor between VCC and PGND. The VCC output is active when the EN pin voltage is more than 0.7 V.   |
| 12      | AGND<br>EP | Analog Ground. This pin is the internal ground for the control functions. Connect this pin to the exposed pad. Exposed Pad. Connect the exposed pad to the system AGND plane and PGND plane.  |

## TYPICAL PERFORMANCE CHARACTERISTICS

## EFFICIENCY IN FORCED FIXED FREQUENCY MODE

Figure 4. Efficiency vs. Load Current,  $V_{OUT} = 3.3\text{ V}$ ,  $f_{SW} = 300\text{ kHz}$ Figure 7. Efficiency vs. Load Current,  $V_{OUT} = 3.3\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ Figure 5. Efficiency vs. Load Current,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 300\text{ kHz}$ Figure 8. Efficiency vs. Load Current,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ Figure 6. Efficiency vs. Load Current,  $V_{OUT} = 12\text{ V}$ ,  $f_{SW} = 300\text{ kHz}$ Figure 9. Efficiency vs. Load Current,  $V_{OUT} = 12\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$

## EFFICIENCY IN PULSE SKIP MODE

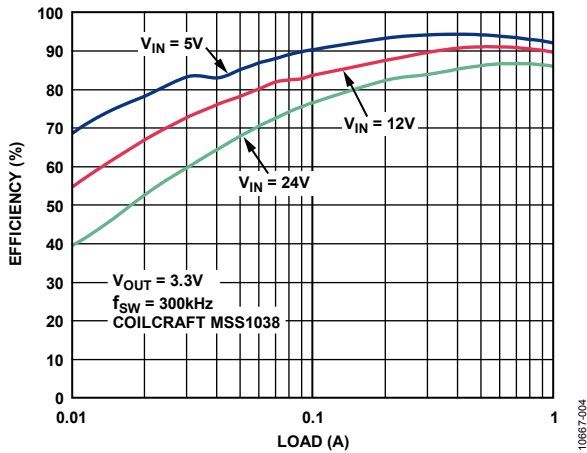


Figure 10. Efficiency vs. Load Current,  
 $V_{OUT} = 3.3V$ ,  $f_{SW} = 300kHz$

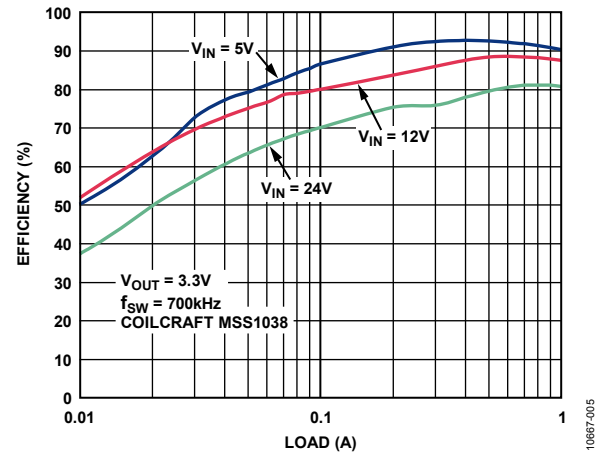


Figure 13. Efficiency vs. Load Current,  
 $V_{OUT} = 3.3V$ ,  $f_{SW} = 700kHz$

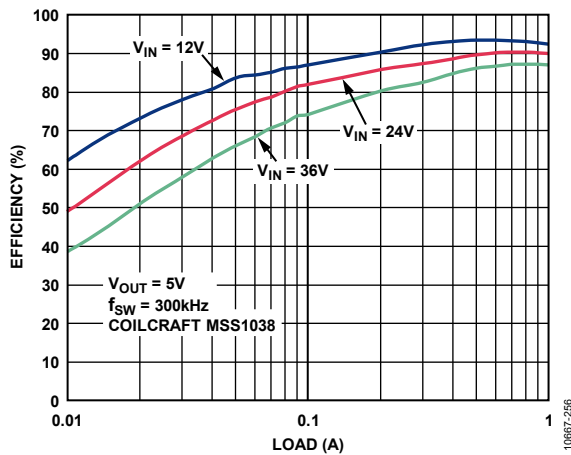


Figure 11. Efficiency vs. Load Current,  
 $V_{OUT} = 5V$ ,  $f_{SW} = 300kHz$

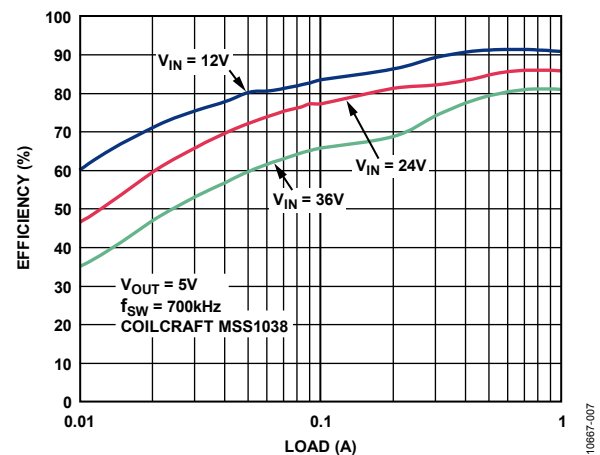


Figure 14. Efficiency vs. Load Current,  
 $V_{OUT} = 5V$ ,  $f_{SW} = 700kHz$

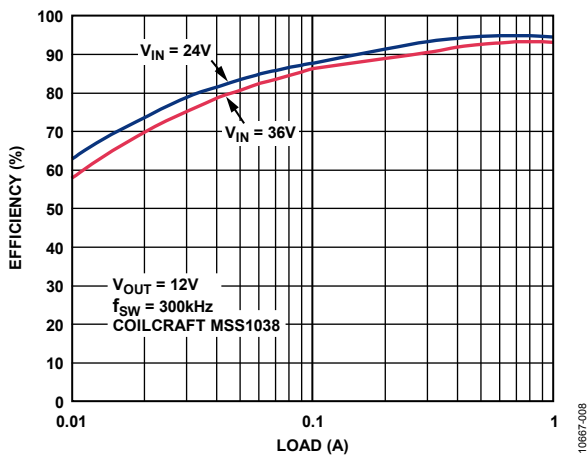


Figure 12. Efficiency vs. Load Current,  
 $V_{OUT} = 12V$ ,  $f_{SW} = 300kHz$

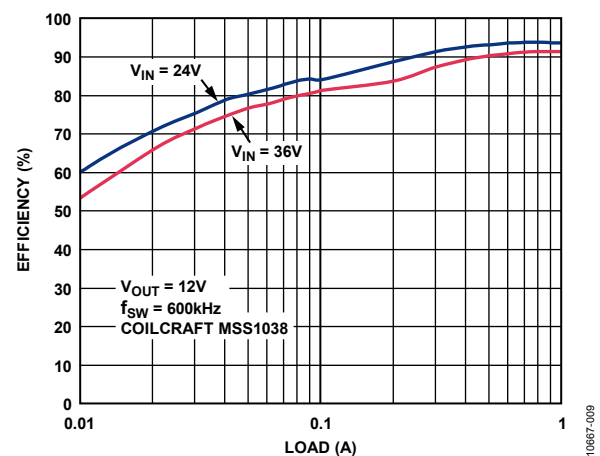


Figure 15. Efficiency vs. Load Current,  
 $V_{OUT} = 12V$ ,  $f_{SW} = 600kHz$

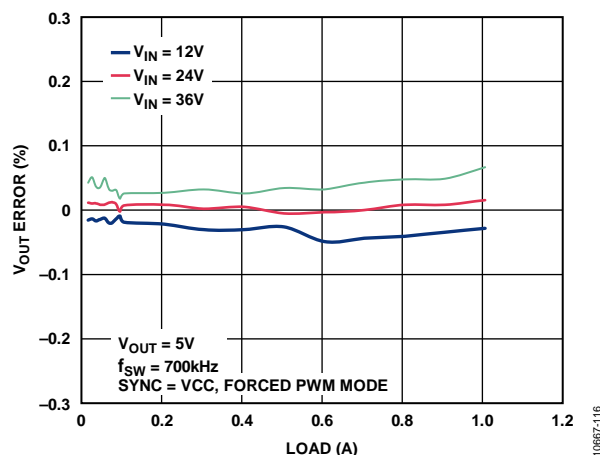


Figure 16. Load Regulation for Different Supplies

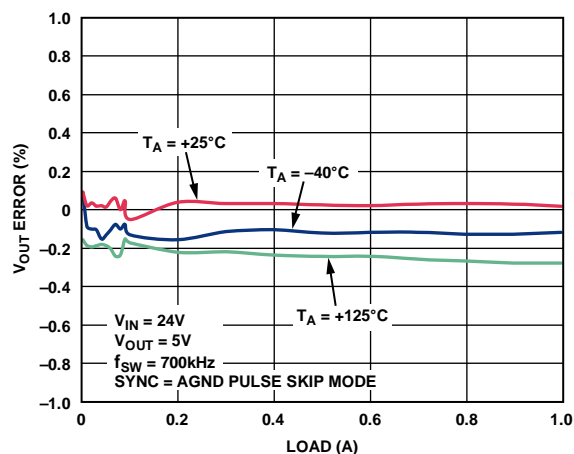
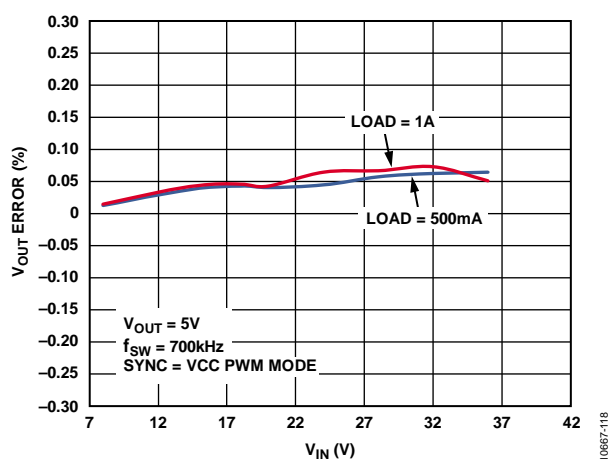
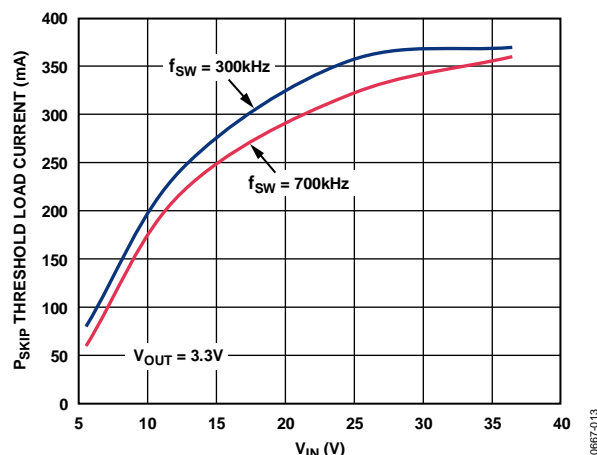
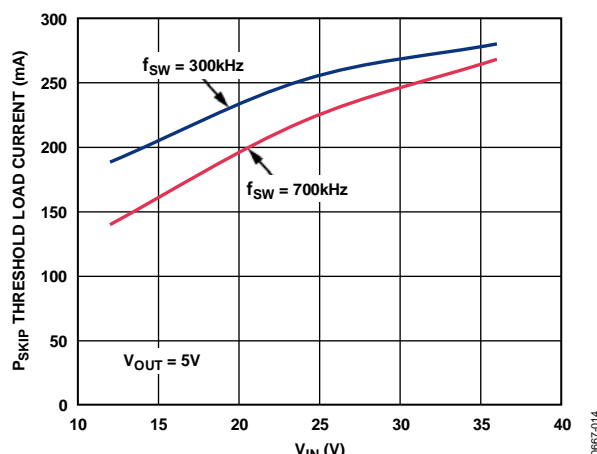
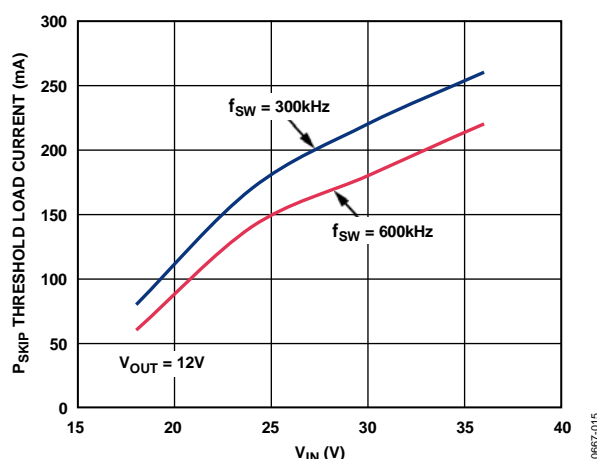


Figure 17. Load Regulation for Different Temperatures

Figure 18. Line Regulation,  $V_{OUT} = 5V$  for Different LoadsFigure 19. Pulse Skip ( $P_{SKIP}$ ) Threshold Load Current,  $V_{OUT} = 3.3V$ Figure 20. Pulse Skip Threshold Load Current,  $V_{OUT} = 5V$ Figure 21. Pulse Skip Threshold Load Current,  $V_{OUT} = 12V$



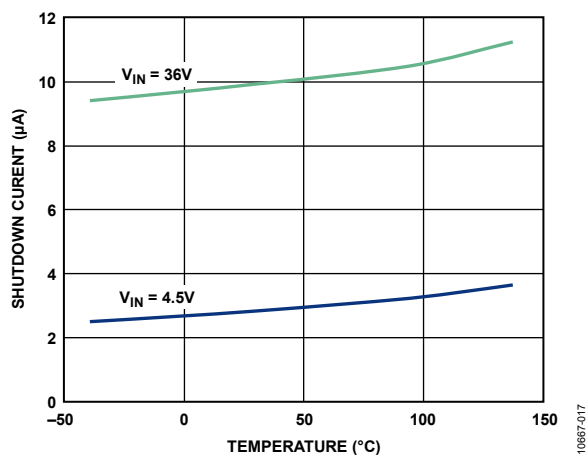


Figure 22. Shutdown Current vs. Temperature

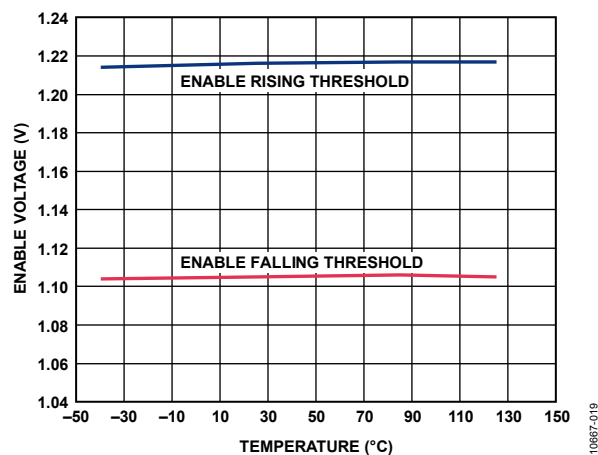


Figure 25. Enable Threshold vs. Temperature

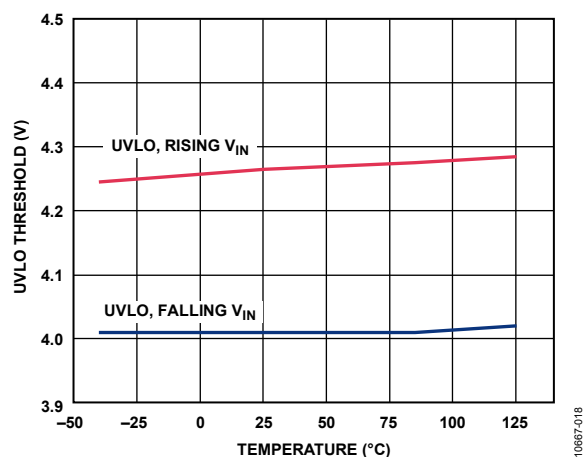


Figure 23. UVLO Threshold vs. Temperature

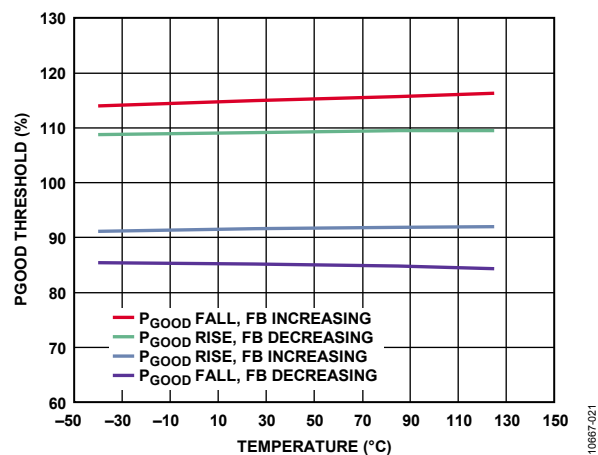


Figure 26. PGOOD Threshold vs. Temperature

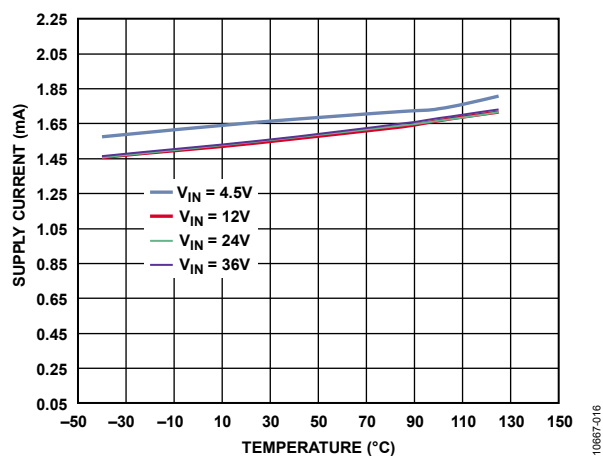


Figure 24. Supply Current vs. Temperature

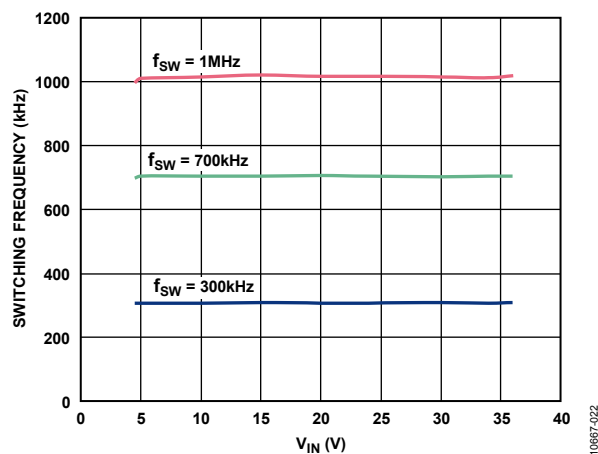


Figure 27. Switching Frequency vs. Supply

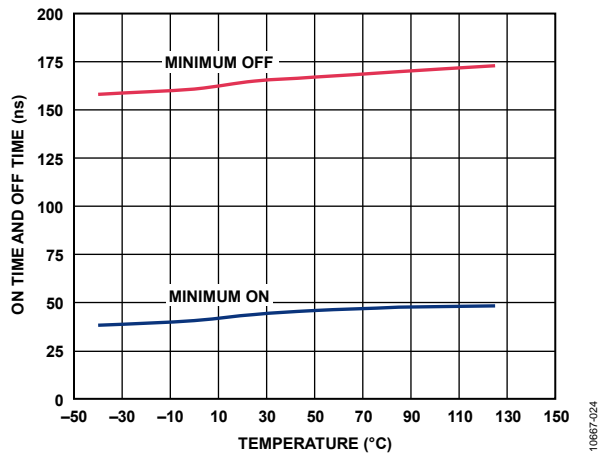


Figure 28. Minimum On Time and Minimum Off Time vs. Temperature

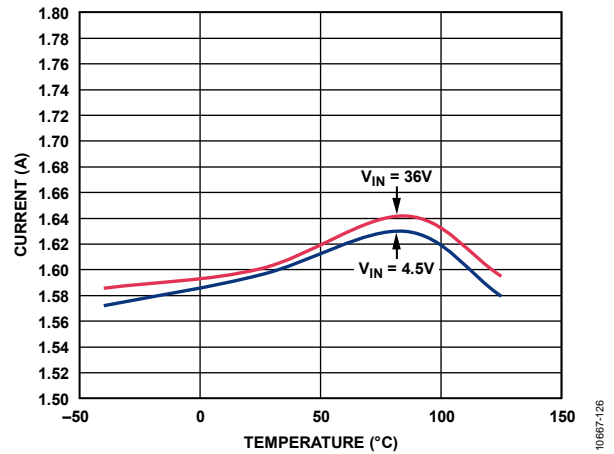


Figure 31. Current Limit vs. Temperature

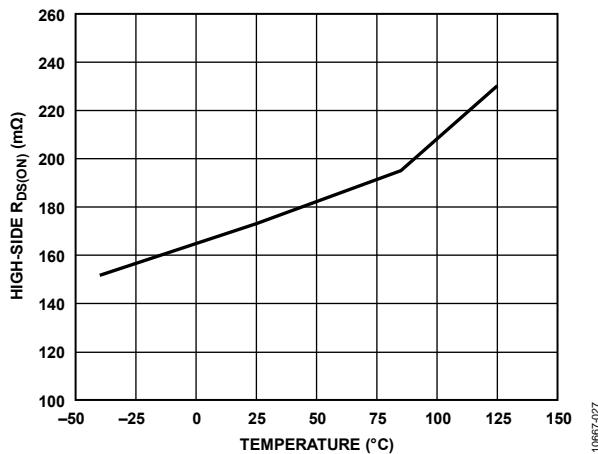
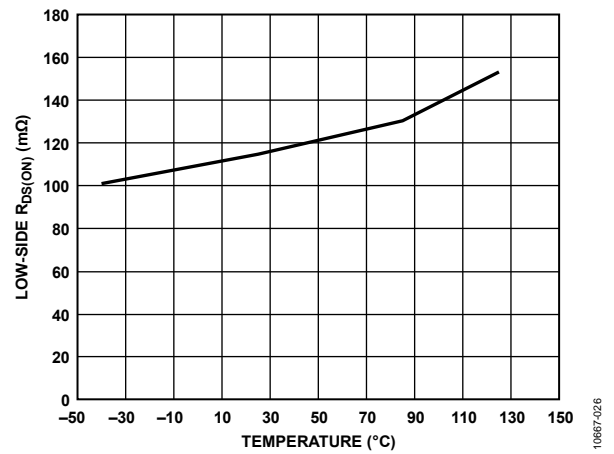
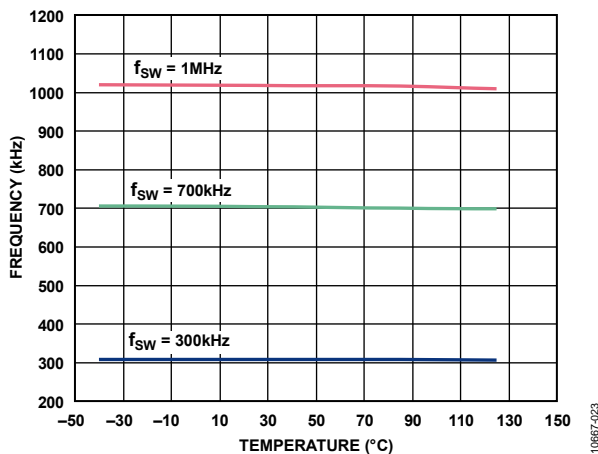
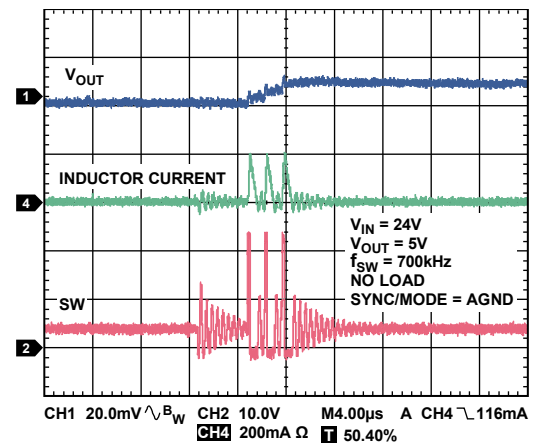
Figure 29. High-Side  $R_{DS(ON)}$  vs. TemperatureFigure 32. Low-Side  $R_{DS(ON)}$  vs. Temperature

Figure 30. Switching Frequency vs. Temperature

Figure 33. Pulse Skip Mode,  $V_{IN} = 24V$ ,  $V_{OUT} = 5V$ ,  $f_{SW} = 700kHz$ , No Load, SYNC/MODE = AGND

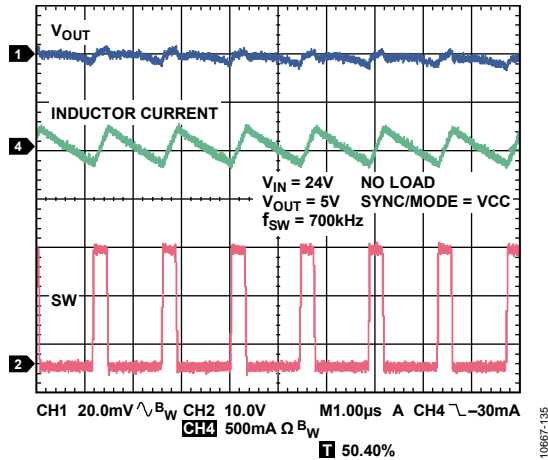


Figure 34. PWM Mode  
 $V_{IN} = 24V$ ,  $V_{OUT} = 5V$ ,  $f_{SW} = 700kHz$ , Load = No Load, SYNC/MODE = VCC

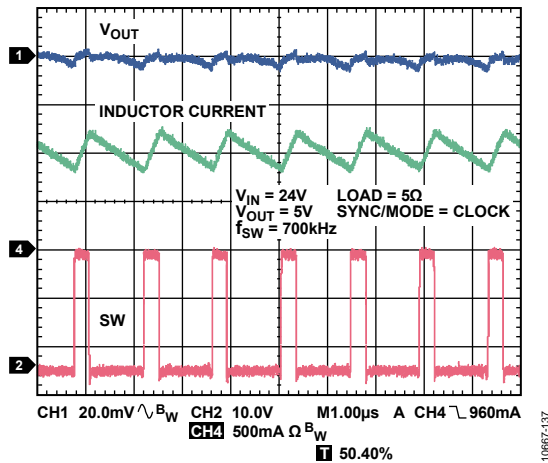


Figure 35. PWM Mode with External Clock,  $V_{IN} = 24V$ ,  $V_{OUT} = 5V$ ,  $f_{SW} = 700kHz$ , Load = 5Ω, SYNC/MODE = Clock

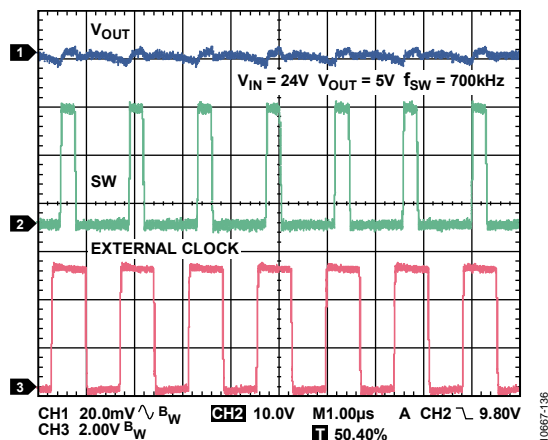


Figure 36. External Clock Synchronization,  
 $V_{IN} = 24V$ ,  $V_{OUT} = 5V$ ,  $f_{SW} = 700kHz$ , SYNC/MODE = Clock

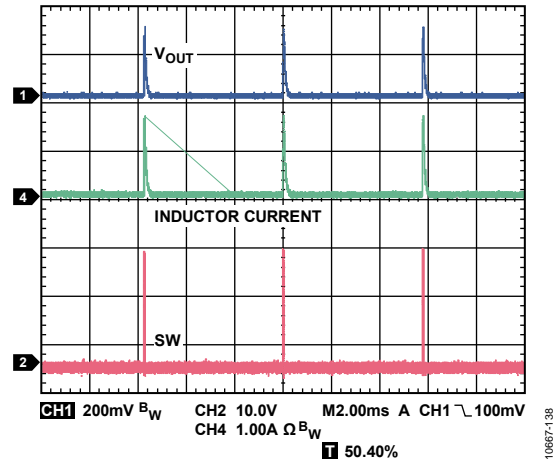


Figure 37. Hiccup Mode,  $V_{IN} = 24V$ ,  $V_{OUT} = 5V$ ,  $f_{SW} = 700kHz$ ,  
 Output Shorted to PGND

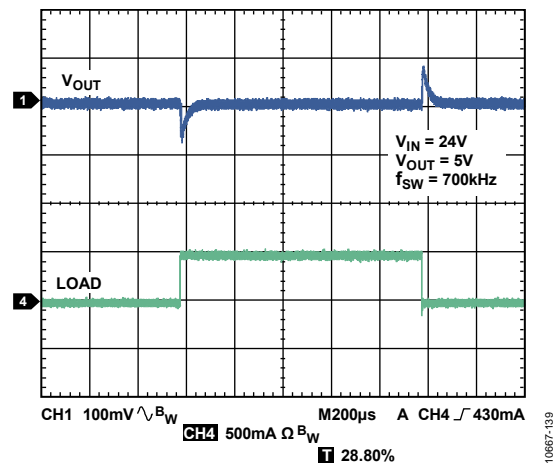


Figure 38. Load Transient Response,  $V_{IN} = 24V$ ,  $V_{OUT} = 5V$ ,  $f_{SW} = 700kHz$ ,  
 SYNC/MODE = Clock, Load Step = 500mA

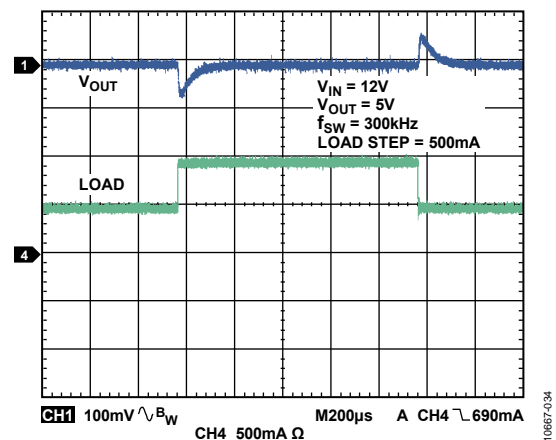


Figure 39. Load Transient Response,  
 $V_{IN} = 12V$ ,  $V_{OUT} = 5V$ ,  $f_{SW} = 300kHz$ , Load Step = 500mA

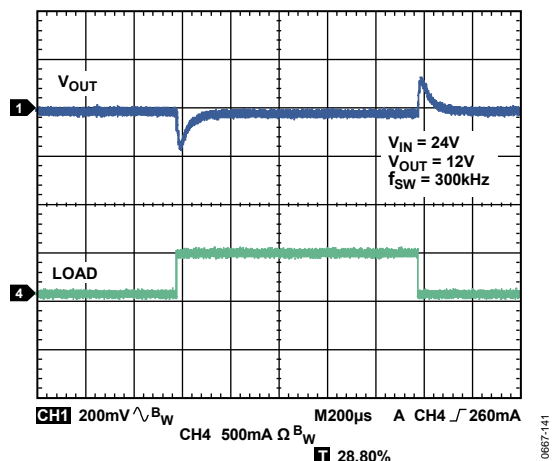


Figure 40. Load Transient Response,  $V_{IN} = 24\text{ V}$ ,  $V_{OUT} = 12\text{ V}$ ,  $f_{SW} = 300\text{ kHz}$ , SYNC/MODE = Clock, Load Step = 500 mA

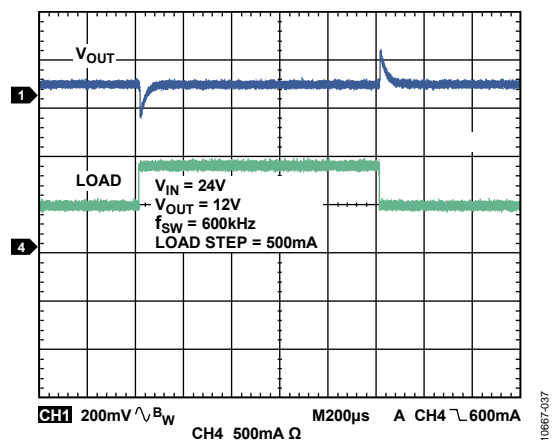


Figure 41. Load Transient Response,  $V_{IN} = 24\text{ V}$ ,  $V_{OUT} = 12\text{ V}$ ,  $f_{SW} = 600\text{ kHz}$ , Load Step = 500 mA

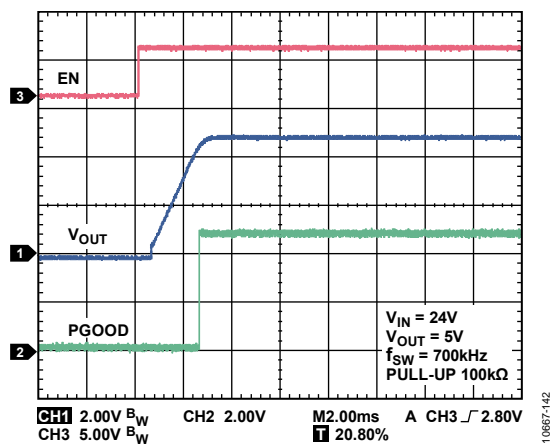


Figure 42. Power-Good Startup,  $V_{IN} = 24\text{ V}$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$

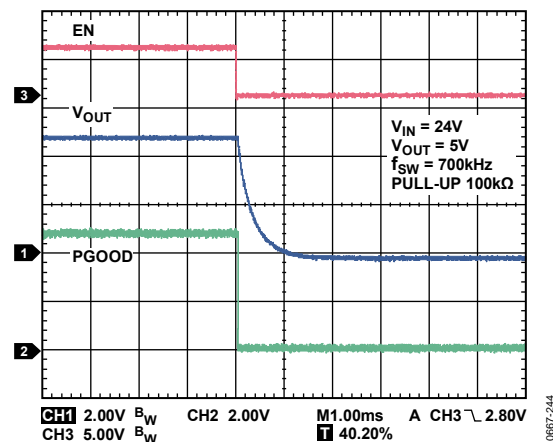


Figure 43. Power-Good Shutdown,  $V_{IN} = 24\text{ V}$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$

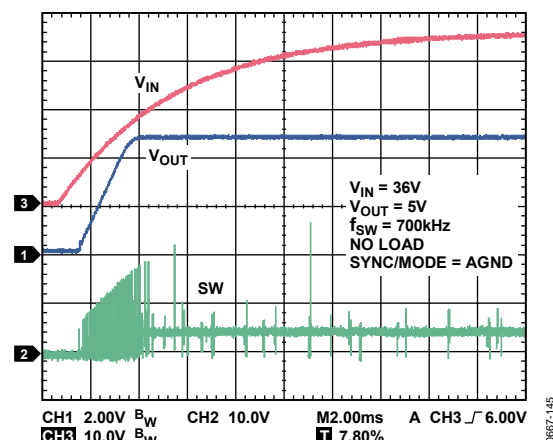


Figure 44. Startup with  $V_{IN}$ , Pulse Skip Mode,  $V_{IN} = 36\text{ V}$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ , No Load, SYNC/MODE = AGND

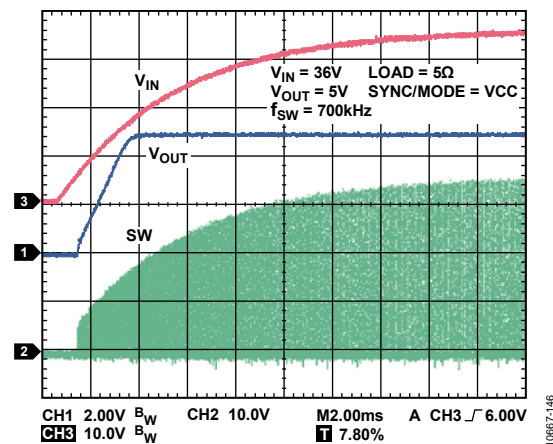


Figure 45. Startup with  $V_{IN}$ , PWM Mode,  $V_{IN} = 36\text{ V}$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ , Load = 5  $\Omega$ , SYNC/MODE = VCC

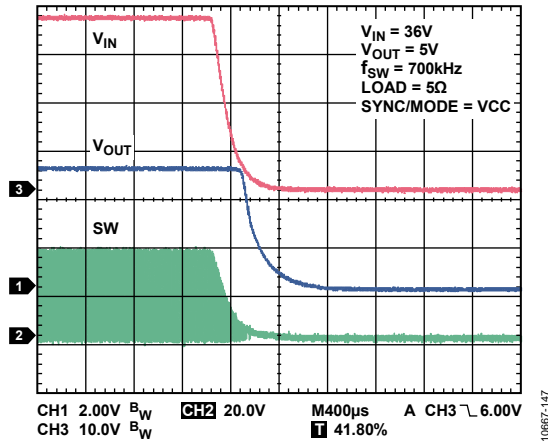


Figure 46. Shutdown with  $V_{IN}$ , PWM Mode,  $V_{IN} = 36\text{ V}$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ , Load =  $5\ \Omega$ , SYNC/MODE = VCC

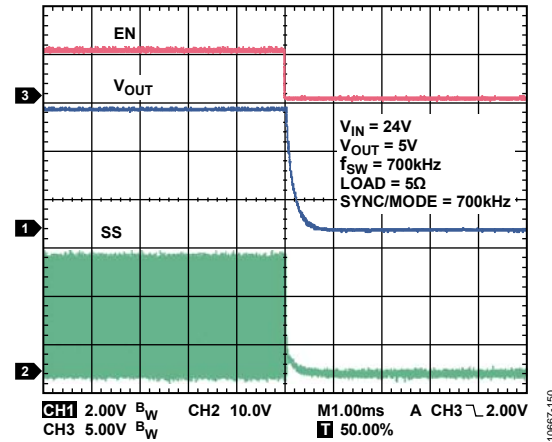


Figure 49. Shutdown with Precision Enable,  $V_{IN} = 24\text{ V}$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ , Load =  $5\ \Omega$ , SYNC/MODE =  $700\text{ kHz}$

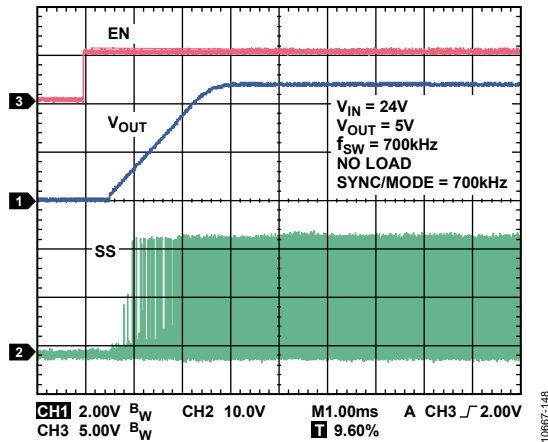


Figure 47. Startup with Precision Enable,  $V_{IN} = 24\text{ V}$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ , Load = No Load, SYNC/MODE =  $700\text{ kHz}$

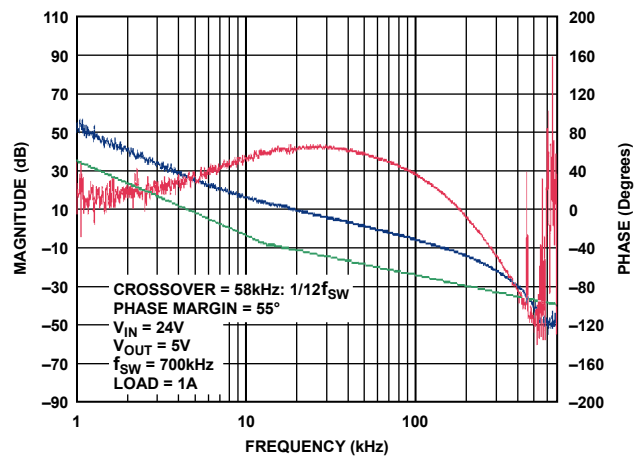


Figure 50. Magnitude and Phase vs. Frequency

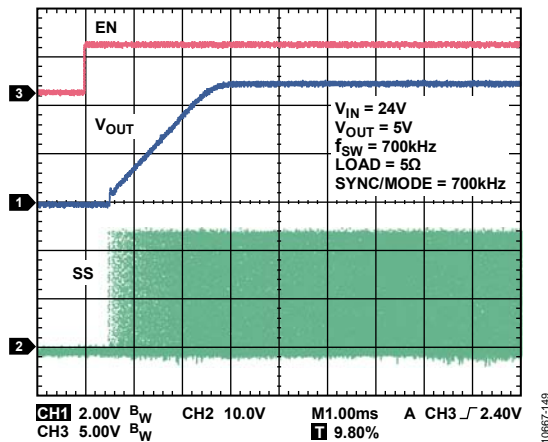


Figure 48. Startup with Precision Enable,  $V_{IN} = 24\text{ V}$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ , Load =  $5\ \Omega$ , SYNC/MODE =  $700\text{ kHz}$

## INTERNAL BLOCK DIAGRAM

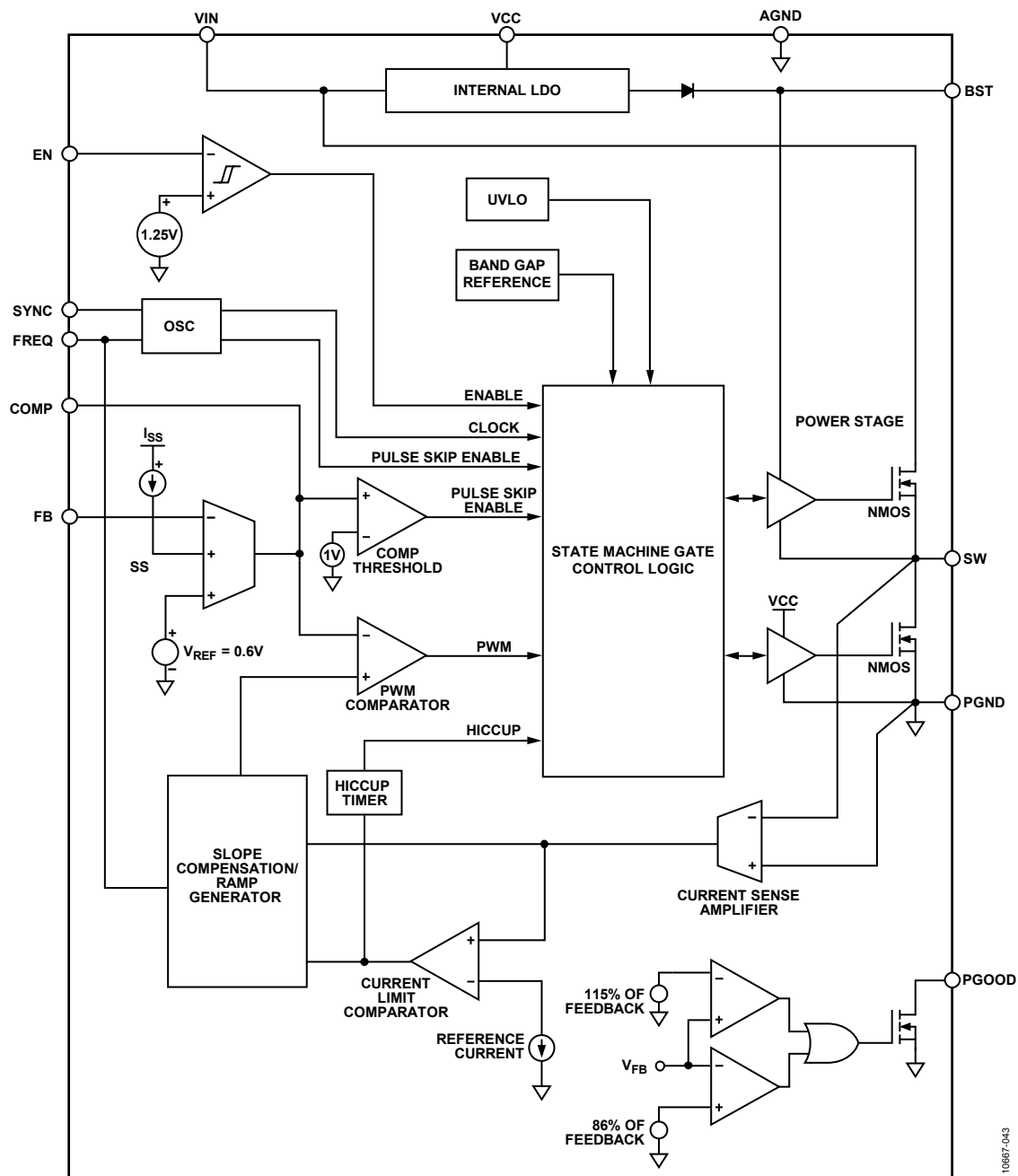


Figure 51. Internal Block Diagram

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## THEORY OF OPERATION

The [ADP2442](#) is a fixed frequency, current mode control, step-down, synchronous switching regulator that is capable of driving 1 A loads. The device operates with a wide input voltage range from 4.5 V to 36 V, and its output is adjustable from 0.6 V to  $0.9\text{ V} \times V_{\text{IN}}$ . The integrated high-side N-channel power MOSFET and the low-side N-channel power MOSFET yield high efficiency at medium to heavy loads. Pulse skip mode is available to improve efficiency at light loads.

The [ADP2442](#) includes programmable features, such as output voltage, switching frequency, and power good. These features are programmed externally via tiny resistors and capacitors. The [ADP2442](#) also includes protection features, such as UVLO with hysteresis, output short-circuit protection, and thermal shutdown.

## CONTROL ARCHITECTURE

The [ADP2442](#) is based on an emulated peak current mode control architecture. The [ADP2442](#) can operate in both fixed frequency and pulse skip modes.

### ***Fixed Frequency Mode***

A basic block diagram of the control architecture is shown in Figure 52. The [ADP2442](#) can be configured in fixed frequency mode. The output voltage,  $V_{OUT}$ , is sensed on the feedback pin, FB. An error amplifier integrates the error between the feedback voltage ( $V_{FB}$ ) and the reference voltage ( $V_{REF} = 0.6 \text{ V}$ ) to generate an error voltage at the COMP pin.

A current sense amplifier senses the valley inductor current ( $I_L$ ) during the off period when the low-side power MOSFET is on and the high-side power MOSFET is off. An internal oscillator initiates a pulse-width modulation (PWM) pulse to turn off the low-side power MOSFET and turn on the high-side power MOSFET at a fixed switching frequency.

When the high-side N-channel power MOSFET is enabled, the valley inductor-current information is added to an emulated ramp signal and the PWM comparator compares this value to the error voltage on the COMP pin. The output of the PWM comparator modulates the duty cycle by adjusting the trailing edge of the PWM pulse that turns off the high-side power MOSFET and turns on the low-side power MOSFET.

Slope compensation is programmed internally into the emulated ramp signal and is automatically selected, depending on the input voltage, output voltage, and switching frequency. This prevents subharmonic oscillations for near or greater than 50% duty cycle operation. The one restriction of this feature is that the inductor ripple current must be set between 0.2 A and 0.5 A to provide sufficient current information to the loop.

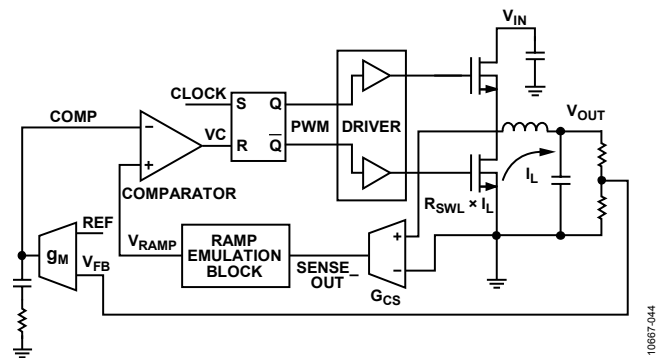


Figure 52. Control Architecture Block Diagram

### ***Pulse Skip Mode***

The [ADP2442](#) pulse skip mode is enabled by connecting the SYNC/MODE pin to AGND. In this mode, the pulse skip circuitry turns on during light loads, switching only as necessary to keep the output voltage within regulation. This mode allows the regulator to maintain high efficiency during operation with light loads by reducing switching losses. The pulse skip circuitry includes a comparator, which compares the COMP voltage to a fixed pulse skip threshold.

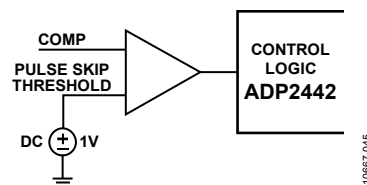


Figure 53. Pulse Skip Comparator

With light loads, the output voltage discharges at a very slow rate (load dependent). When the output voltage is within regulation, the device enters sleep mode and draws a very small quiescent current. As the output voltage drops below the regulation voltage, the COMP voltage rises above the pulse skip threshold. The device wakes up and begins switching until the output voltage is within regulation.

As the load increases, the settling value of the COMP voltage increases. At a particular load, COMP settles above the pulse skip threshold, and the device enters the fixed frequency mode. Therefore, the load current at which COMP exceeds the pulse skip threshold is defined as the pulse skip current threshold; the value varies with the duty cycle and the inductor ripple current.

The measured value of pulse skip threshold over  $V_{IN}$  is shown in Figure 19, Figure 20, and Figure 21.

## ADJUSTABLE FREQUENCY

The ADP2442 features a programmable oscillator frequency with a resistor connected between the FREQ and AGND pins.

At power-up, the FREQ pin is forced to 1.2 V and current flows from the FREQ pin to AGND; the current value is based on the resistor value on the FREQ pin. Next, the same current replicates in the oscillator to set the switching frequency. Note that the resistor connected to the FREQ pin must be placed as close as possible to the FREQ pin (see the Applications Information section for more information).

## POWER GOOD

The PGOOD pin is an open-drain output that indicates the status of the output voltage. When the voltage of the FB pin is between 92% and 109% of the internal reference voltage, the PGOOD output pulls high, provided there is a pull-up resistor connected to the pin. When the voltage of the FB pin is not within this range, the PGOOD output pulls low to AGND. The PGOOD threshold is shown in Figure 54.

Likewise, the PGOOD pin is pulled low to AGND when

- The input voltage is below the internal UVLO threshold.
- The EN pin is low.
- A thermal shutdown event has occurred.

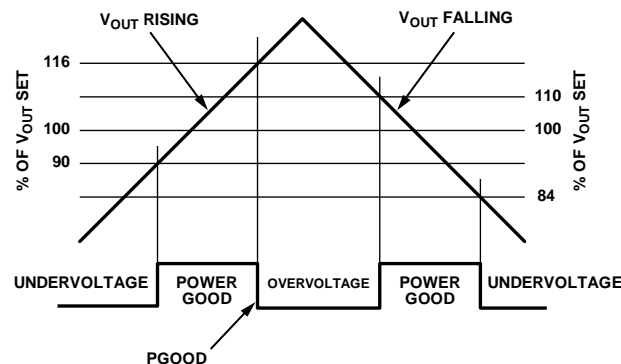


Figure 54. PGOOD Threshold

In a typical application, a pull-up resistor connected between the PGOOD pin and an external supply is used to generate a logic signal. This pull-up resistor must range in value from 30 kΩ to 100 kΩ, and the external supply must be less than 5.5 V.

## MODE OF OPERATION

The SYNC/MODE pin is a multifunctional pin. The fixed frequency mode is enabled when SYNC/MODE is connected to VCC or a high logic. When SYNC/MODE connects to AGND, pulse skip mode enables. The external clock can be applied for synchronization.

Table 5. SYNC/MODE Pin Mode of Operation

| SYNC/MODE Pin | Mode of Operation           |
|---------------|-----------------------------|
| Low           | Pulse skip mode             |
| High          | Forced fixed frequency mode |
| Clock Signal  | Forced fixed frequency mode |

## EXTERNAL SYNCHRONIZATION

The external synchronization feature allows the switching frequency of the device to be synchronized to an external clock. The SYNC/MODE input accepts a logic level clock input ranging from 300 kHz to 1 MHz (minimum pulse width = 100 ns) and has high input impedance. For best practices, it is recommended that the set frequency (set by the resistor at the FREQ pin) be within  $\pm 30\%$  of the expected clock frequency to ensure stable, reliable, and seamless operation with or without an external SYNC/MODE clock. When the ADP2442 is synchronized to an external clock, the regulator switching frequency changes to the external clock frequency.

## SOFT START

The ADP2442 has an internal soft start feature that allows the output voltage to ramp up in a controlled manner, limiting the inrush current during startup. The ADP2442 internal soft start time is 2 ms.

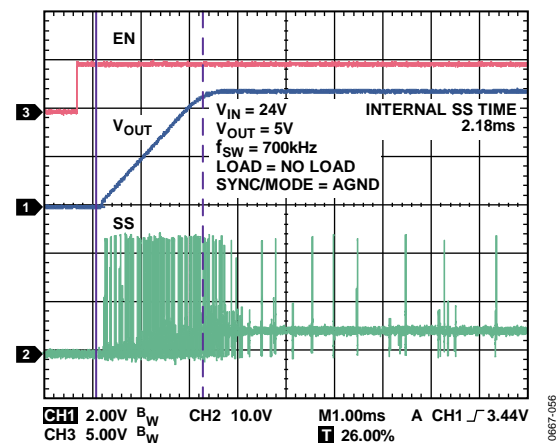


Figure 55. Internal Soft Start

## UNDERVOLTAGE LOCKOUT

The undervoltage lockout (UVLO) function prevents the IC from turning on when the input voltage is below the specified operating range to avoid an undesired operating mode. If the input voltage drops below the specified range, the UVLO function shuts off the device. The rising input voltage threshold for the UVLO function is 4.2 V with 200 mV hysteresis. The 200 mV of hysteresis prevents the regulator from turning on and off repeatedly when there is a slow voltage ramp on the VIN pin.

## PRECISION ENABLE/SHUTDOWN

The ADP2442 features a precision enable pin (EN) to enable or shutdown the device. The  $\pm 5\%$  accuracy lends itself to using a resistor divider from the VIN pin (or another external supply) to program a desired UVLO threshold that is higher than the fixed internal UVLO of 4.2 V. The hysteresis is 100 mV.

If a resistor divider is not used, apply a logic signal instead. A logic high enables the device, and a logic low forces the device into shutdown mode.



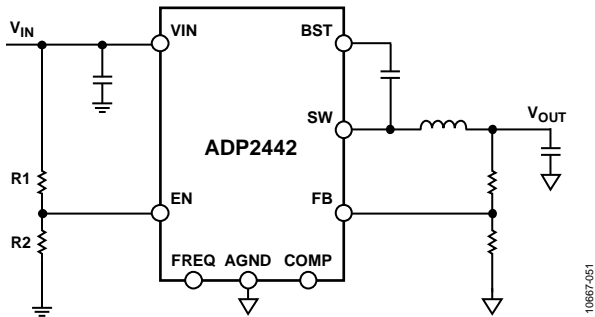


Figure 56. Precision Enable Used as a Programmable UVLO

## CURRENT-LIMIT AND SHORT-CIRCUIT PROTECTION

The ADP2442 has a current-limit comparator that compares the current sensed across the low-side power MOSFET to the internally set reference current. If the sensed current exceeds the reference current, the high-side power MOSFET does not turn on in the next cycle and the low-side power MOSFET stays on until the inductor current ramps down below the current-limit level.

If the output is overloaded and the peak inductor current exceeds the preset current limit for more than eight consecutive clock cycles, the hiccup mode current-limit condition occurs. The output goes to sleep for 6 ms, during which time the output discharges, the average power dissipation reduces, and the device wakes up with a soft start period. If the current-limit condition is triggered again, the output goes to sleep and wakes up after 6 ms. Figure 37 shows the current-limit hiccup mode when the output is shorted to ground.

## THERMAL SHUTDOWN

If the ADP2442 junction temperature rises above 150°C, the thermal shutdown circuit turns off the switching regulator. Extreme junction temperatures can be the result of high current operation, poor circuit board design, or high ambient temperature. A 25°C hysteresis is included so that when a thermal shutdown occurs, the ADP2442 does not return to normal operation until the junction temperature drops below 125°C. Soft start is active upon each restart cycle.

## APPLICATIONS INFORMATION

### ADIsimPOWER DESIGN TOOL

The ADP2442 is supported by the ADIsimPower design tool set. ADIsimPower is a collection of tools that produce complete power designs optimized to a specific design goal. These tools allow the user to generate a full schematic, bill of materials, and calculate performance in minutes. ADIsimPower can optimize designs for cost, area, efficiency, and device count while taking into consideration the operating conditions and limitations of the IC and all real external components. Find the ADIsimPower tool at [www.analog.com/adisimpower](http://www.analog.com/adisimpower) and the user can request an unpopulated board through the tool.

### SELECTING THE OUTPUT VOLTAGE

The output voltage is set using a resistor divider connected between the output voltage and the FB pin (see Figure 57). The resistor divider divides down the output voltage to the 0.6 V FB regulation voltage. The output voltage can be set to as low as 0.6 V and as high as 90% of the power input voltage.

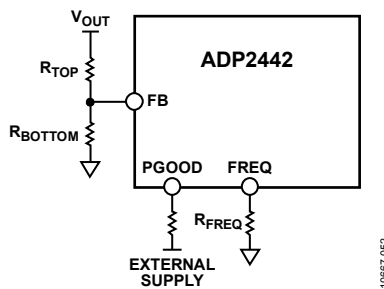


Figure 57. Voltage Divider

The ratio of the resistive voltage divider sets the output voltage, and the absolute value of the resistors sets the divider string current. When calculating the resistor values for lower divider string currents, take into account the small 50 nA (0.1 μA maximum) FB bias current. The FB bias current can be ignored for a higher divider string current; however, using small feedback resistors degrades efficiency at very light loads.

To limit degradation of the output voltage accuracy due to FB bias current to less than 0.005% (0.5% maximum), ensure that the divider string current is greater than 20 μA. To calculate the desired resistor values, first determine the value of the bottom resistor,  $R_{BOTTOM}$ , as follows:

$$R_{BOTTOM} = \frac{V_{REF}}{I_{STRING}} \quad (1)$$

where:

$V_{REF}$  is the internal reference and equals 0.6 V.

$I_{STRING}$  is the resistor divider string current.

Next, calculate the value of the top resistor,  $R_{TOP}$ , as follows:

$$R_{TOP} = R_{BOTTOM} \times \left( \frac{V_{OUT} - V_{REF}}{V_{REF}} \right) \quad (2)$$

Table 6. Output Voltage Selection

| Voltage (V) | $R_{TOP}$ (kΩ) | $R_{BOTTOM}$ (kΩ) |
|-------------|----------------|-------------------|
| 12          | 190            | 10                |
| 5           | 73             | 10                |
| 3.3         | 45             | 10                |
| 1.2         | 10             | 10                |

### SETTING THE SWITCHING FREQUENCY

The choice of the switching frequency depends on the required dc-to-dc conversion ratio and is limited by the minimum and maximum controllable duty cycle, as shown in Figure 58. This limitation is due to the requirement of minimum on time and minimum off time for current sensing and robust operation. However, the choice is also influenced by whether there is a need for small external components. For example, higher switching frequencies are required for small, area limited power solutions.

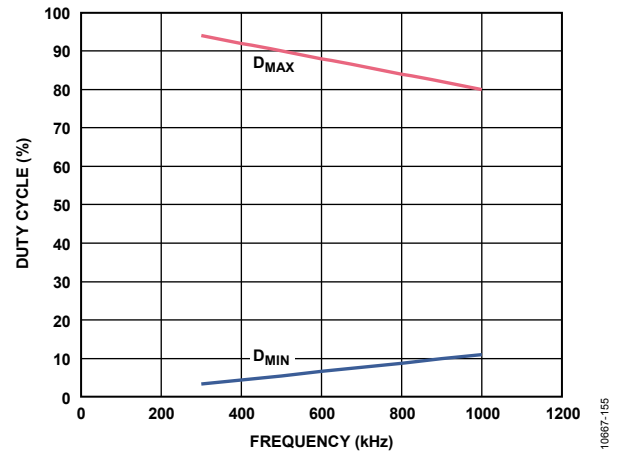


Figure 58. Duty Cycle vs. Switching Frequency

Calculate the value of the frequency resistor by using the following equation:

$$R_{FREQ} = \frac{92,500}{f_{SW}} \quad (3)$$

where  $R_{FREQ}$  is in kΩ and  $f_{SW}$  is in kHz.

Table 7 and Figure 59 provide examples of frequency resistor values that are based on the switching frequency.

Table 7. Frequency Resistor Selection

| $R_{FREQ}$ | Frequency |
|------------|-----------|
| 308 kΩ     | 300 kHz   |
| 132 kΩ     | 700 kHz   |
| 92.5 kΩ    | 1 MHz     |

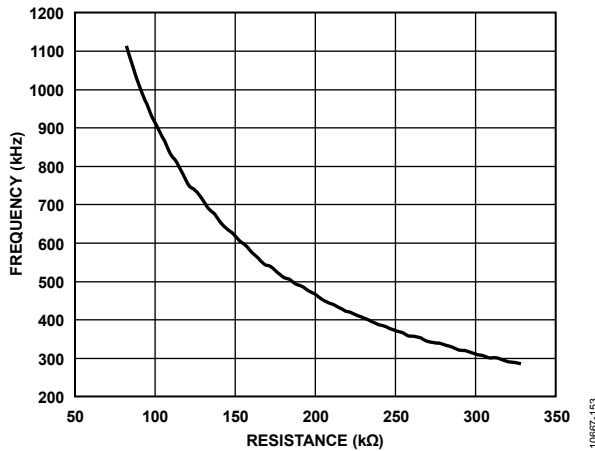


Figure 59. Frequency vs. Resistor

## EXTERNAL COMPONENT SELECTION

### Input Capacitor Selection

The input current to a buck regulator is pulsating in nature. The current is zero when the high-side switch is off and is approximately equal to the load current when the switch is on. Because switching occurs at reasonably high frequencies (300 kHz to 1 MHz), the input bypass capacitor usually supplies most of the high frequency current (ripple current), allowing the input power source to supply only the average (dc) current. The input capacitor needs a sufficient ripple current rating to handle the input ripple and needs an ESR that is low enough to mitigate the input voltage ripple. In many cases, different types of capacitors are placed in parallel to minimize the effective ESR and ESL.

The minimum input capacitance required for a particular load is

$$C_{IN\_MIN} = \frac{I_{OUT} \times D \times (1 - D)}{(V_{PP} - I_{OUT} \times D \times R_{ESR}) f_{SW}} \quad (4)$$

where:

$V_{PP}$  is the desired input ripple voltage.

$R_{ESR}$  is the equivalent series resistance of the capacitor.

$I_{OUT}$  is the maximum load current.

$D$  is the duty cycle.

$f_{SW}$  is the switching frequency.

For best practice, use a ceramic bypass capacitor because the ESR associated with this type of capacitor is near zero, simplifying the equation to

$$C_{IN\_MIN} = \frac{I_{OUT} \times D \times (1 - D)}{V_{PP} \times f_{SW}} \quad (5)$$

In addition, use a ceramic capacitor with a voltage rating that is 1.5 times the input voltage with X5R and X7R dielectrics. Using Y5V and Z5U dielectrics is not recommended because of their poor temperature and dc bias characteristics. Table 10 shows a list of recommended MLCC capacitors.

For large step load transients, add more bulk capacitance by using electrolytic or polymer capacitors. Ensure that the ripple current rating of the bulk capacitor exceeds the minimum input ripple current of a particular design.

### Inductor Selection

The high switching frequency of the ADP2442 allows for minimal output voltage ripple even when small inductors are used. Selecting the size of the inductor involves considering the trade-off between efficiency and transient response. A smaller inductor results in larger inductor current ripple, which provides excellent transient response; however, it degrades efficiency. Because of the high switching frequency of the ADP2442, use shielded ferrite core inductors for their low core losses and low EMI.

The inductor ripple current also affects the stability of the loop because the ADP2442 uses the emulated peak current mode architecture. In the traditional approach of slope compensation, the user sets the inductor ripple current and then sets the slope compensation using an external ramp resistor. In most cases, the inductor ripple current is typically set to be 1/3 of the maximum load current for optimal transient response and efficiency. The ADP2442 has internal slope compensation, which assumes that the inductor ripple current is set to 0.3 A (30% of the maximum load of 1 A), eliminating the need for an external ramp resistor.

For the ADP2442, choose an inductor such that the peak-to-peak ripple current of the inductor is between 0.2 A and 0.5 A for stable operation. Calculate the inductor value as follows:

$$\Delta I_L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times f_{SW} \times L} \quad (6)$$

$$0.2 \text{ A} \leq \Delta I_L \leq 0.5 \text{ A}$$

$$\frac{2 \times V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times f_{SW}} \leq L \leq \frac{5 \times V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times f_{SW}}$$

$$L_{IDEAL} = \frac{3.3 \times V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times f_{SW}} \quad (7)$$

where:

$V_{IN}$  is the input voltage.

$V_{OUT}$  is the desired output voltage.

$f_{SW}$  is the regulator switching frequency.

$L$  is the inductor value.

$\Delta I_L$  is the peak-to-peak inductor ripple current.

$L_{IDEAL}$  is the ideal calculated inductor value.

For applications with a wide input ( $V_{IN}$ ) range, choose the inductor based on the geometric mean ( $V_{IN(GEOMETRIC)}$ ) of the input voltage extremes.

$$V_{IN(GEOMETRIC)} = \sqrt{V_{IN\_MAX} \times V_{IN\_MIN}} \quad (8)$$

where:

$V_{IN\_MAX}$  is the maximum input voltage.

$V_{IN\_MIN}$  is the minimum input voltage.

The inductor value is based on  $V_{IN(GEOMETRIC)}$  as follows:

$$L_{IDEAL} = \frac{3.3 \times V_{OUT} \times (V_{IN(GEOMETRIC)} - V_{OUT})}{V_{IN(GEOMETRIC)} \times f_{SW}} \quad (9)$$

**Table 8. Inductor Values for Various  $V_{IN}$ ,  $V_{OUT}$ , and  $f_{SW}$  Combinations**

| $f_{SW}$ (kHz) | $V_{IN}$ (V) | $V_{OUT}$ (V) | Inductor Values |                |
|----------------|--------------|---------------|-----------------|----------------|
|                |              |               | Min ( $\mu$ H)  | Max ( $\mu$ H) |
| 300            | 12           | 3.3           | 22              | 27             |
| 300            | 12           | 5             | 27              | 33             |
| 300            | 24           | 3.3           | 27              | 33             |
| 300            | 24           | 5             | 39              | 47             |
| 300            | 24           | 12            | 56              | 68             |
| 300            | 36           | 3.3           | 27              | 33             |
| 300            | 36           | 5             | 39              | 47             |
| 300            | 36           | 12            | 68              | 82             |
| 600            | 12           | 3.3           | 12              | 15             |
| 600            | 12           | 5             | 15              | 18             |
| 600            | 24           | 3.3           | 15              | 18             |
| 600            | 24           | 5             | 18              | 22             |
| 600            | 24           | 12            | 27              | 33             |
| 600            | 36           | 3.3           | 15              | 18             |
| 600            | 36           | 5             | 22              | 27             |
| 1000           | 12           | 5             | 6.8             | 10             |
| 1000           | 24           | 5             | 10              | 12             |
| 1000           | 24           | 12            | 18              | 22             |
| 1000           | 36           | 5             | 12              | 15             |

To avoid inductor saturation and ensure proper operation, choose the inductor value so that neither the saturation current nor the maximum temperature rated current ratings are exceeded. Inductor manufacturers specify both of these ratings in data sheets, or the rating can be calculated as follows:

$$I_{L\_PEAK} = I_{LOAD(MAX)} + \frac{\Delta I_L}{2} \quad (10)$$

where:

$I_{LOAD(MAX)}$  is the maximum dc load current.

$\Delta I_L$  is the peak-to-peak inductor ripple current.

$I_{L\_PEAK}$  is the peak inductor current.

**Table 9. Recommended Inductors**

| Value ( $\mu$ H) | Small Inductors<br>( $<10\text{ mm} \times 10\text{ mm}$ ) | Large Inductors<br>( $>10\text{ mm} \times 10\text{ mm}$ ) |
|------------------|--|--|
| 10               | XAL4040-103ME  | MSS1260  |
| 18               | LPS6235-183ML  | MSS1260  |
| 33               | LPS6235-33ML   | MSS1260  |
| 15               | XAL4040-153ME  | MSS1260  |

### Output Capacitor Selection

The output capacitor selection affects both the output voltage ripple and the loop dynamics of the regulator. The ADP2442 is designed to operate with small ceramic output capacitors that have low ESR and ESL; therefore, the device easily meets tight output voltage ripple specifications. For best performance, use X5R or X7R dielectric capacitors with a voltage rating that is 1.5 times the output voltage and avoid using Y5V and Z5U dielectric capacitors, which have poor temperature and dc bias characteristics. Table 10 lists recommended capacitors from Murata and Taiyo Yuden.

**Table 10. Recommended Output Capacitors**

| Capacitor        | Vendor             |                  |
|------------------|--------------------|------------------|
|                  | Murata             | Taiyo Yuden      |
| 10 $\mu$ F/25 V  | GRM32DR71E106KA12L | TMK325B7106KN-TR |
| 22 $\mu$ F/25 V  | GRM32ER71E226KE15L | TMK325B7226MM-TR |
| 47 $\mu$ F/6.3 V | GCM32ER70J476KE19L | JMK325B7476MM-TR |
| 4.7 $\mu$ F/50 V | GRM31CR71H475KA12L | UMK325B7475MMT   |

For acceptable maximum output voltage ripple, determine the minimum output capacitance,  $C_{OUT(MIN)}$ , as follows:

$$\Delta V_{RIPPLE} \cong \Delta I_L \times \left( ESR + \frac{1}{8 \times f_{SW} \times C_{OUT(MIN)}} \right) \quad (11)$$

Therefore,

$$C_{OUT(MIN)} \cong \frac{\Delta I_L}{8 \times f_{SW} \times (\Delta V_{RIPPLE} - \Delta I_L \times ESR)} \quad (12)$$

where:

$\Delta V_{RIPPLE}$  is the allowable peak-to-peak output voltage ripple.

$\Delta I_L$  is the inductor ripple current.

$ESR$  is the equivalent series resistance of the capacitor.

$f_{SW}$  is the switching frequency of the regulator.

When there is a step load requirement, choose the output capacitor value based on the value of the step load. Use the following equation to determine the maximum acceptable output voltage droop/overshoot caused by the step load:

$$C_{OUT(MIN)} \cong \Delta I_{OUT(STEP)} \times \left( \frac{3}{f_{SW} \times \Delta V_{DROOP}} \right) \quad (13)$$

where:

$\Delta I_{OUT(STEP)}$  is the load step.

$f_{SW}$  is the switching frequency of the regulator.

$\Delta V_{DROOP}$  is the maximum allowable output voltage droop/overshoot.

Select the larger of the output capacitances derived from Equation 12 and Equation 13. When choosing the type of ceramic capacitor for the output filter of the regulator, select a capacitor with a nominal capacitance that is 20% to 30% larger than the calculated value because the effective capacitance degrades with dc voltage and temperature. Figure 60 shows the capacitance loss resulting from the dc bias voltage for two capacitors (X7R MLCC capacitors from Murata are shown in Figure 60).

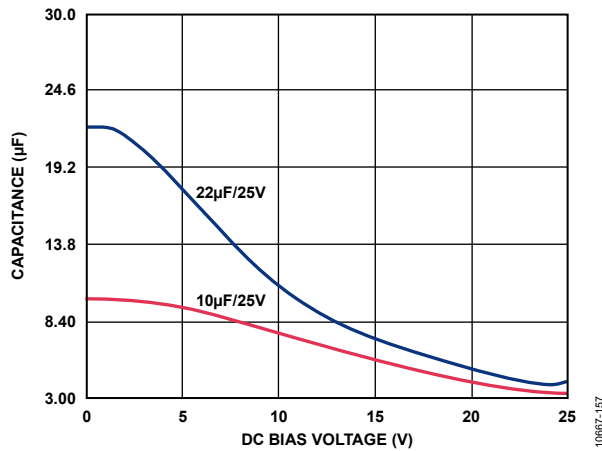


Figure 60. Capacitance vs. DC Voltage

For example, to attain 20  $\mu\text{F}$  of output capacitance with an output voltage of 5 V while providing some margin for temperature variation, use a 22  $\mu\text{F}$  capacitor with a voltage rating of 25 V and a 10  $\mu\text{F}$  capacitor with a voltage rating of 25 V in parallel. This configuration ensures that the output capacitance is sufficient under all conditions and, therefore, that the device exhibits stable behavior.

### BOOST CAPACITOR

The boost pin (BST) is used to power up the internal driver for the high-side power MOSFET. In the ADP2442, the high-side power MOSFET is an N-channel device to achieve high efficiency in mid and high duty cycle applications. To power up the high-side driver, a capacitor is required between the BST and SW pins. The size of this boost capacitor is critical because it affects the light load functionality and efficiency of the device. Therefore, choose a boost ceramic capacitor with a value between 10 nF and 22 nF with a voltage rating of 50 V, placing the capacitor as close as possible to the IC. It is recommended to use a boost capacitor within this range because a capacitor beyond 22 nF can cause the LDO to reach the current-limit threshold.

### VCC CAPACITOR

The ADP2442 has an internal regulator to power up the internal controller and the low-side driver. The VCC pin is the output of the internal regulator. The internal regulator provides the pulse current when the low-side driver turns on. Therefore, it is recommended to place a 1  $\mu\text{F}$  ceramic capacitor between the VCC and PGND pins as close as possible to the IC and place a 1  $\mu\text{F}$  ceramic capacitor between the VCC and AGND pins.

## LOOP COMPENSATION

The ADP2442 uses a peak current mode control architecture for excellent load and line transient response. This control architecture has two loops: an inner current loop and an external voltage loop.

The inner current loop senses the current in the low-side switch and controls the duty cycle to maintain the average inductor current. To ensure stable operation when the duty cycle is above 50%, slope compensation is added to the inner current loop.

The external voltage loop senses the output voltage and adjusts the duty cycle to regulate the output voltage to the desired value. A transconductance amplifier with an external series RC network connected to the COMP pin compensates for the external voltage loop, as shown in Figure 61.

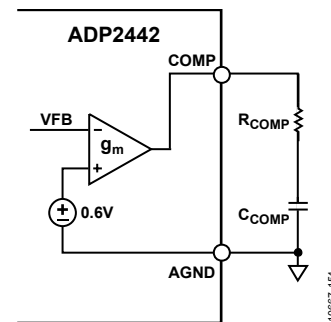


Figure 61. RC Compensation Network

## LARGE SIGNAL ANALYSIS OF THE LOOP COMPENSATION

The control loop can be broken down into the following three sections:

- $V_{\text{OUT}}$  to  $V_{\text{COMP}}$
- $V_{\text{COMP}}$  to  $I_L$
- $I_L$  to  $V_{\text{OUT}}$

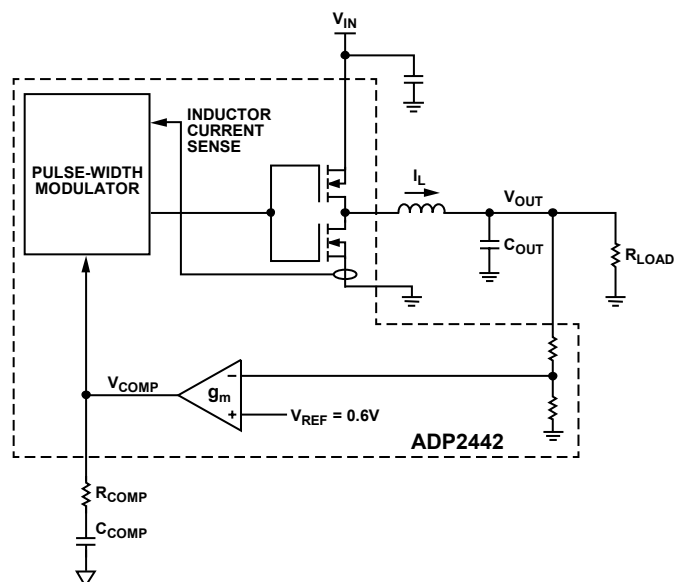


Figure 62. Large Signal Model

Correspondingly, there are three transfer functions:

$$\frac{V_{COMP}(s)}{V_{OUT}(s)} = \frac{V_{REF}}{V_{OUT}} \times g_m \times Z_{COMP}(s) \quad (14)$$

$$\frac{I_L(s)}{V_{COMP}(s)} = G_{CS} \quad (15)$$

$$\frac{V_{OUT}(s)}{I_L(s)} = Z_{FILT}(s) \quad (16)$$

where:

$V_{COMP}$  is the comparator voltage.

$I_L$  is the inductor current.

$g_m$  is the transconductance of the error amplifier and equals 250  $\mu\text{A/V}$ .

$G_{CS}$  is the current sense gain and equals 2 A/V.

$V_{OUT}$  is the output voltage of the regulator.

$V_{REF}$  is the internal reference voltage and equals 0.6 V.

$Z_{COMP}(s)$  is the impedance of the RC compensation network that forms a pole at the origin and a zero, as expressed in Equation 17.

$$Z_{COMP}(s) = \frac{1 + s \times R_{COMP} \times C_{COMP}}{s \times C_{COMP}} \quad (17)$$

$Z_{FILT}(s)$  is the impedance of the output filter and is expressed as

$$Z_{FILT}(s) = \frac{R_{LOAD}}{1 + s \times R_{LOAD} \times C_{OUT}} \quad (18)$$

where  $s$  is the angular frequency, which can be written as  $s = 2\pi f$ .

Obtain the overall loop gain,  $H(s)$ , by multiplying the three transfer functions previously mentioned as follows:

$$H(s) = g_m \times G_{CS} \times \frac{V_{REF}}{V_{OUT}} \times Z_{COMP}(s) \times Z_{FILT}(s) \quad (19)$$

When the switching frequency ( $f_{sw}$ ), output voltage ( $V_{OUT}$ ), output inductor ( $L$ ), and output capacitor ( $C_{OUT}$ ) values are selected, the unity crossover frequency can be set to 1/12 of the switching frequency.

At the crossover frequency, the gain of the open-loop transfer function is unity.

$$H(f_{CROSSOVER}) = 1 \quad (20)$$

This yields Equation 21 for the RC compensation network impedance at the crossover frequency.

$$Z_{COMP}(f_{CROSSOVER}) = \frac{2 \times \pi \times f_{CROSSOVER} \times C_{OUT}}{g_m \times G_{CS}} \times \frac{V_{OUT}}{V_{REF}} \quad (21)$$

Placing  $s = f_{CROSSOVER}$  in Equation 17,

$$Z_{COMP}(f_{CROSSOVER}) = \frac{1 + 2 \times \pi \times f_{CROSSOVER} \times R_{COMP} \times C_{COMP}}{2 \times \pi \times f_{CROSSOVER} \times C_{COMP}} \quad (22)$$

To ensure that there is sufficient phase margin at the crossover frequency, place the compensator zero at 1/8 of the crossover frequency, as shown in the following equation:

$$f_{ZERO} = \frac{1}{2 \times \pi \times R_{COMP} \times C_{COMP}} \approx \frac{f_{CROSSOVER}}{8} \quad (23)$$

Solving Equation 21, Equation 22, and Equation 23 yields the values for the resistor and capacitor in the RC compensation network, as shown in Equation 24 and Equation 25.

$$R_{COMP} = 0.9 \times \frac{2 \times \pi \times f_{CROSSOVER}}{g_m \times G_{CS}} \times \frac{C_{OUT} \times V_{OUT}}{V_{REF}} \quad (24)$$

$$C_{COMP} = \frac{1}{2 \times \pi \times f_{ZERO} \times R_{COMP}} \quad (25)$$

Using these equations allows calculating the compensations for the voltage loop.

## DESIGN EXAMPLE

Consider an application with the following specifications:

- $V_{IN}$ : 24 V  $\pm$  10%
- $V_{OUT}$ : 5 V  $\pm$  1%
- Switching frequency: 700 kHz
- Load: 800 mA typical
- Maximum load current: 1 A
- Overshoot  $\leq$  2% under all load transient conditions

## CONFIGURATION AND COMPONENTS SELECTION

### Resistor Divider

The first step in selecting the external components is to calculate the resistance of the resistor divider that sets the output voltage.

Using Equation 1 and Equation 2,

$$R_{BOTTOM} = \frac{V_{REF}}{I_{STRING}} = \frac{0.6}{60 \mu A} = 10 \text{ k}\Omega$$

$$R_{TOP} = R_{BOTTOM} \times \left( \frac{V_{OUT} - V_{REF}}{V_{REF}} \right)$$

$$R_{TOP} = 10 \text{ k}\Omega \times \left( \frac{5 \text{ V} - 0.6 \text{ V}}{0.6 \text{ V}} \right) = 73.3 \text{ k}\Omega$$

### Switching Frequency

Choosing the switching frequency involves consideration of the trade-off between efficiency and component size. Low frequency improves the efficiency by reducing the gate losses but requires a large inductor. The choice of high frequency is limited by the minimum and maximum duty cycle.

Table 11. Duty Cycle

| $V_{IN}$                     | Duty Cycle             |
|------------------------------|------------------------|
| 24 V (Nominal)               | $D_{NOMINAL} = 20.8\%$ |
| 26 V (10% Above Nominal)     | $D_{MIN} = 19\%$       |
| 22 V (10% Less than Nominal) | $D_{MAX} = 23\%$       |

Based on the estimated duty cycle range, choose the switching frequency according to the minimum and maximum duty cycle limitations, as shown in Figure 58. For example, a 700 kHz, frequency is well within the maximum and minimum duty cycle limitations.

Using Equation 3,

$$R_{FREQ} = \frac{92,500}{f_{SW}}$$

$$R_{FREQ} = 132 \text{ k}\Omega$$

### Inductor Selection

Select the inductor by using Equation 7.

$$L_{IDEAL} = \frac{3.3 \times V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times f_{SW}}$$

$$L_{IDEAL} = \frac{3.3 \times 5 \text{ V} \times (24 - 5) \text{ V}}{24 \text{ V} \times 700 \text{ kHz}} = 18.66 \mu\text{H} \approx 18.3 \mu\text{H}$$

In Equation 7,  $V_{IN} = 24 \text{ V}$ ,  $V_{OUT} = 5 \text{ V}$ ,  $I_{LOAD(MAX)} = 1 \text{ A}$ , and  $f_{SW} = 700 \text{ kHz}$ , which results in  $L = 18.66 \mu\text{H}$ . When  $L = 18 \mu\text{H}$  (the closest standard value) in Equation 6,  $\Delta I_L = 0.314 \text{ A}$ . Although the maximum output current that is required is 1 A, the maximum peak current is 1.6 A. Therefore, the inductor must be rated for higher than 1.6 A current.

### Input Capacitor Selection

The input filter consists of a small 0.1  $\mu\text{F}$  ceramic capacitor placed as close as possible to the IC.

The minimum input capacitance required for a particular load is

$$C_{IN\_MIN} = \frac{I_{OUT} \times D \times (1 - D)}{V_{PP} \times f_{SW}}$$

where:

$$V_{PP} = 50 \text{ mV.}$$

$$I_{OUT} = 1 \text{ A.}$$

$$D = 0.23.$$

$$f_{SW} = 700 \text{ kHz.}$$

Therefore,

$$C_{IN\_MIN} = \frac{1 \text{ A} \times 0.22 \times (1 - 0.22)}{0.05 \text{ V} \times 700 \text{ kHz}} \approx 4.9 \mu\text{F}$$

Choosing an input capacitor of 10  $\mu\text{F}$  with a voltage rating of 50 V ensures sufficient capacitance over voltage and temperature.

### Output Capacitor Selection

Select the output capacitor by using Equation 12 and Equation 13

$$C_{OUT(MIN)} \cong \frac{\Delta I_L}{8 \times f_{SW} \times (\Delta V_{RIPPLE} - \Delta I_L \times ESR)}$$

Equation 12 is based on the output voltage ripple ( $\Delta V_{RIPPLE}$ ), which is 1% of the output voltage.

$$C_{OUT(MIN)} \cong \Delta I_{OUT(STEP)} \left( \frac{3}{f_{SW} \times \Delta V_{DROOP}} \right)$$

Equation 13 calculates the capacitor selection based on the transient load performance requirement of 2%. Perform these calculations, then use the equation that yields the larger capacitor size to select a capacitor.



In this example, the values listed in Table 12 are substituted for the variables in Equation 12 and Equation 13.

**Table 12. Requirements**

| Parameter                           | Test Conditions/Comments       | Value   |
|-------------------------------------|--------------------------------|---------|
| Ripple Current                      | Fixed at 0.3 A for the ADP2442 | 0.3 A   |
| Voltage Ripple                      | 1% of $V_{OUT}$                | 50 mV   |
| Voltage Droop Due to Load Transient | 2% of $V_{OUT}$                | 100 mV  |
| ESR                                 |                                | 5 mΩ    |
| $f_{SW}$                            |                                | 700 kHz |

The calculation based on the output voltage ripple (see Equation 12) dictates that the minimum output capacitance is

$$C_{OUT(MIN)} \cong \frac{0.3 \text{ A}}{8 \times 700 \text{ kHz} \times (50 \text{ mV} - 0.3 \text{ A} \times 5 \text{ m}\Omega)} = 1.1 \mu\text{F}$$

Whereas the calculation based on the transient load (see Equation 13) dictates that the minimum output capacitance is

$$C_{OUT(MIN)} \cong 0.5 \times \frac{3}{700 \text{ kHz} \times 0.1 \text{ V}} \approx 22 \mu\text{F}$$

To meet both requirements, use the value determined by the latter equation. As shown in Figure 60, capacitance degrades with dc bias; therefore, choose a capacitor that is 1.5 times the calculated value.

$$C_{OUT} = 1.5 \times 22 \mu\text{F} = 32 \mu\text{F}$$

### Compensation Selection

Calculate the compensation component values for the feedback loop using the following equations:

$$R_{COMP} = 0.9 \times \frac{2 \times \pi \times f_{CROSSOVER}}{g_m \times G_{CS}} \times \frac{C_{OUT} \times V_{OUT}}{V_{REF}}$$

$$C_{COMP} = \frac{1}{2 \times \pi \times f_{ZERO} \times R_{COMP}}$$

Selecting the crossover frequency to be 1/12 of the switching frequency and placing the zero frequency at 1/8 of the crossover frequency ensures that there is adequate phase margin in the system.

**Table 13. Calculated Parameter Value**

| Parameter       | Test Conditions/Comments            | Value               |
|-----------------|-------------------------------------|---------------------|
| $f_{CROSSOVER}$ | 1/12 of $f_{SW}$                    | 58.3 kHz            |
| $f_{ZERO}$      | 1/8 of $f_{CROSSOVER}$              | 7.3 kHz             |
| $V_{REF}$       | Fixed reference                     | 0.6 V               |
| $g_m$           | Transconductance of error amplifier | 250 $\mu\text{A/V}$ |
| $G_{CS}$        | Current sense gain                  | 2 A/V               |
| $C_{OUT}$       | Output capacitor                    | 22 $\mu\text{F}$    |
| $V_{OUT}$       | Output voltage                      | 5 V                 |

Based on the values listed in Table 13, calculate the compensation value:

$$R_{COMP} = 0.9 \times \frac{2 \times \pi \times 58.3}{250 \times 2} \times \frac{22 \times 5}{0.6} \approx 121 \text{ k}\Omega$$

The closest standard resistor value is 118 kΩ. Therefore,

$$C_{COMP} = \frac{1}{2 \times \pi \times 7.3 \times 118} = 185 \text{ pF} \approx 180 \text{ pF}$$

### SYSTEM CONFIGURATION

Configure the system as follows; though the steps are not sequential, they all must be completed:

- Connect a capacitor of 1  $\mu\text{F}$  between the VCC and PGND pins and another capacitor of 1  $\mu\text{F}$  between the VCC and AGND pins. For best performance, use ceramic X5R or X7R capacitors with a 25 V voltage rating.
- Connect a ceramic capacitor of 10 nF with a 50 V voltage rating between the BST and SW pins.
- Connect a resistor between the FREQ and AGND pins as close as possible to the IC.
- If using the power-good feature, connect a 50 kΩ pull-up resistor to a 5 V external supply.
- For synchronization, connect an external clock with a frequency of 700 kHz to the SYNC/MODE pin. Connect the external clock to AGND to activate pulse skip mode or connect it to VCC for forced fixed frequency mode.

See Figure 63 for a schematic of this design example and Table 14 for the calculated component values.



## TYPICAL APPLICATION CIRCUITS

## DESIGN EXAMPLE

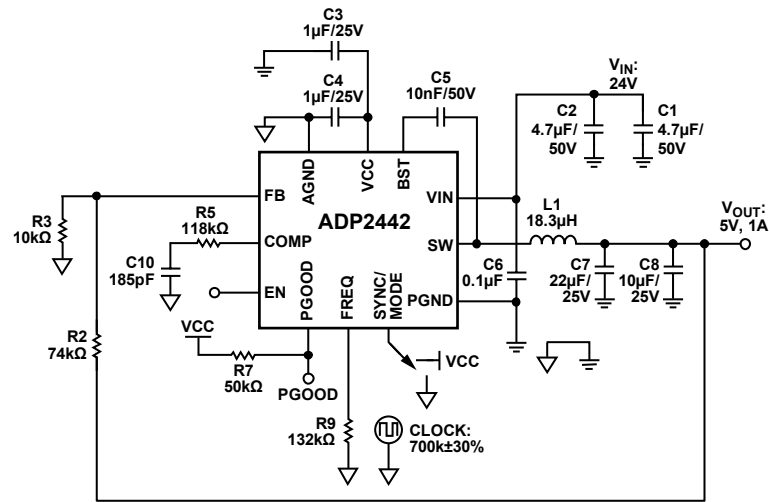
Figure 63. Typical Application Circuit,  $V_{IN} = 24\text{ V} \pm 10\%$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$ 

Table 14. Calculated Component Values for Figure 63

| Quantity | Reference | Value   | Description                                   | Part Number               |
|----------|-----------|---------|---|---------------------------|
| 2        | C1, C2    | 4.7 µF  | Capacitor ceramic, X7R, 50 V                  | GRM31CR71H475KA12L        |
| 2        | C3, C4    | 1 µF    | Capacitor ceramic, 1 µF, 25 V, X7R, 10%, 0603 | GRM188R71E105KA12D        |
| 2        | C5        | 10 nF   | Capacitor ceramic, 10 nF, 50 V, 10%, X7R, 603 | ECJ-1VB1H103K             |
| 1        | C7        | 22 µF   | Capacitor ceramic, 22 µF, 25 V, X7R, 1210     | GRM32ER71E226K            |
| 1        | C8        | 10 µF   | Capacitor ceramic, 10 µF, 25 V, X7R, 1210     | GRM32DR71E106KA12L        |
| 1        | L1        | 18.3 µH | Inductor                                      | CoilCraft MSS1260T-183NLB |
| 1        | C6        | 0.1 µF  | Capacitor ceramic, 0.1 µF, 50 V, X7R, 0805    | ECJ-2FB1H104K             |
| 1        | C10       | 185 pF  | Capacitor ceramic, 50 V                       | Determined by user        |
| 1        | R9        | 132 kΩ  | Resistor, 1/10 W, 1%, 0603, SMD               | Determined by user        |
| 1        | R5        | 118 kΩ  | Resistor, 1/10 W, 1%, 0603, SMD               | Determined by user        |
| 1        | R2        | 74 kΩ   | Resistor, 1/10 W, 1%, 0603, SMD               | Determined by user        |
| 2        | R3        | 10 kΩ   | Resistor, 1/10 W, 1%, 0603, SMD               | Determined by user        |
| 1        | R7        | 50 kΩ   | Resistor, 1/10 W, 1%, 0603, SMD               | Determined by user        |

## OTHER TYPICAL CIRCUIT CONFIGURATIONS

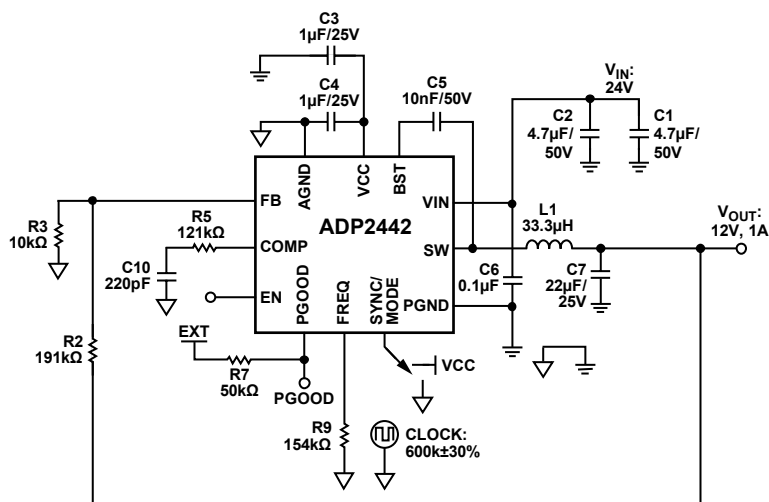
Figure 64. Typical Application Circuit,  $V_{IN} = 24V \pm 10\%$ ,  $V_{OUT} = 12V$ ,  $f_{SW} = 600kHz$ 

Table 15. Calculated Component Values for Figure 64

| Quantity | Reference | Value            | Description                                       | Part Number             |
|----------|-----------|------------------|---|-------------------------|
| 2        | C1, C2    | 4.7 μF           | Capacitor ceramic, X7R, 50 V                      | GRM31CR71H475KA12L      |
| 2        | C3, C4    | 1 μF             | Capacitor ceramic, 1 μF, 25 V, X7R, 10%, 0603     | GRM188R71E105KA12D      |
| 2        | C5        | 10 nF            | Capacitor ceramic, 10000 pF, 50 V, 10%, X7R, 0603 | ECJ-1VB1H103K           |
| 1        | C7        | 22 μF            | Capacitor ceramic, 22 μF, 25 V, X7R, 1210         | GRM32ER71E226K          |
| 1        | C8        | N/A <sup>1</sup> | N/A <sup>1</sup>                                  | N/A <sup>1</sup>        |
| 1        | L1        | 33.3 μH          | Inductor  | CoilCraft MSS1038-333ML |
| 1        | C6        | 0.1 μF           | Capacitor ceramic, 0.1 μF, 50 V, X7R, 0805        | ECJ-2FB1H104K           |
| 1        | C10       | 220 pF           | Capacitor ceramic, 50 V                           | Determined by user      |
| 1        | R9        | 154 kΩ           | Resistor, 1/10 W, 1%, 0603, SMD                   | Determined by user      |
| 1        | R5        | 121 kΩ           | Resistor, 1/10 W, 1%, 0603, SMD                   | Determined by user      |
| 1        | R2        | 191 kΩ           | Resistor, 1/10 W, 1%, 0603, SMD                   | Determined by user      |
| 2        | R3        | 10 kΩ            | Resistor, 1/10 W, 1%, 0603, SMD                   | Determined by user      |
| 1        | R7        | 50 kΩ            | Resistor, 1/10 W, 1%, 0603, SMD                   | Determined by user      |

<sup>1</sup> N/A means not applicable.

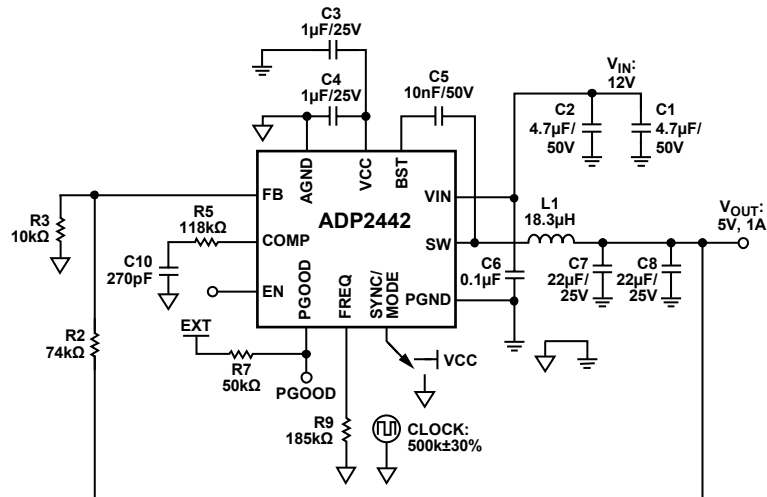


Figure 65. Typical Application Circuit,  $V_{IN} = 12\text{ V} \pm 10\%$ ,  $V_{OUT} = 5\text{ V}$ ,  $f_{SW} = 500\text{ kHz}$

Table 16. Calculated Component Values for Figure 65

| Quantity | Reference | Value              | Description   | Part Number             |
|----------|-----------|--------------------|---|-------------------------|
| 2        | C1, C2    | 4.7 $\mu\text{F}$  | Capacitor ceramic, X7R, 50 V                              | GRM31CR71H475KA12L      |
| 2        | C3, C4    | 1 $\mu\text{F}$    | Capacitor ceramic, 1 $\mu\text{F}$ , 25 V, X7R, 10%, 0603 | GRM188R71E105KA12D      |
| 2        | C5        | 10 nF              | Capacitor ceramic, 10 nF, 50 V, 10%, X7R, 0603            | ECJ-1VB1H103K           |
| 1        | C7        | 22 $\mu\text{F}$   | Capacitor ceramic, 22 $\mu\text{F}$ , 25 V, X7R, 1210     | GRM32ER71E226K          |
| 1        | C8        | 22 $\mu\text{F}$   | Capacitor ceramic, 22 $\mu\text{F}$ , 25 V, X7R, 1210     | Determined by user      |
| 1        | L1        | 18.3 $\mu\text{H}$ | Inductor  | CoilCraft MSS1038-183ML |
| 1        | C6        | 0.1 $\mu\text{F}$  | Capacitor ceramic, 0.1 $\mu\text{F}$ , 50 V, X7R, 0805    | ECJ-2FB1H104K           |
| 1        | C10       | 270 pF             | Capacitor ceramic, 50 V                                   | Determined by user      |
| 1        | R9        | 185 k $\Omega$     | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user      |
| 1        | R5        | 118 k $\Omega$     | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user      |
| 1        | R2        | 74 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user      |
| 1        | R3        | 10 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user      |
| 1        | R7        | 50 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user      |

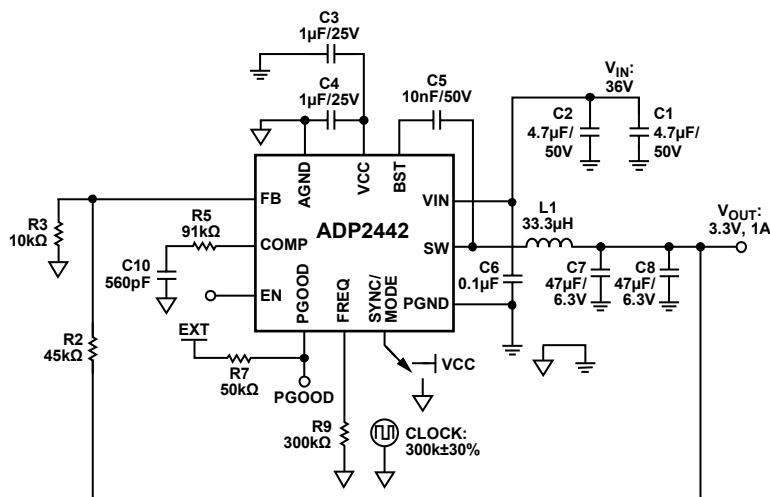


Figure 66. Typical Application Circuit,  $V_{IN} = 36\text{ V} \pm 10\%$ ,  $V_{OUT} = 3.3\text{ V}$ ,  $f_{SW} = 300\text{ kHz}$

Table 17. Calculated Component Values for Figure 66

| Quantity | Reference | Value              | Description   | Part Number              |
|----------|-----------|--------------------|---|--------------------------|
| 2        | C1, C2    | 4.7 $\mu\text{F}$  | Capacitor ceramic, X7R, 50 V                              | GRM31CR71H475KA12L       |
| 2        | C3, C4    | 1 $\mu\text{F}$    | Capacitor ceramic, 1 $\mu\text{F}$ , 25 V, X7R, 10%, 0603 | GRM188R71E105KA12D       |
| 2        | C5        | 10 nF              | Capacitor ceramic, 10 nF, 50 V, 10%, X7R, 0603            | ECJ-1VB1H103K            |
| 1        | C7        | 47 $\mu\text{F}$   | Capacitor ceramic, 47 $\mu\text{F}$ , 6.3 V, X7R, 1210    | GRM32ER70J476KE20L       |
| 1        | C8        | 47 $\mu\text{F}$   | Capacitor ceramic, 47 $\mu\text{F}$ , 6.3 V, X7R, 1210    | GRM32ER70J476KE20L       |
| 1        | L1        | 33.3 $\mu\text{H}$ | Inductor  | CoilCraft MSS1038T-333ML |
| 1        | C6        | 0.1 $\mu\text{F}$  | Capacitor ceramic, 0.1 $\mu\text{F}$ , 50 V, X7R, 0805    | ECJ-2FB1H104K            |
| 1        | C10       | 560 pF             | Capacitor ceramic, 50 V                                   | Determined by user       |
| 1        | R9        | 300 k $\Omega$     | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |
| 1        | R5        | 91 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |
| 1        | R2        | 45 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |
| 1        | R3        | 10 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |
| 1        | R7        | 50 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |

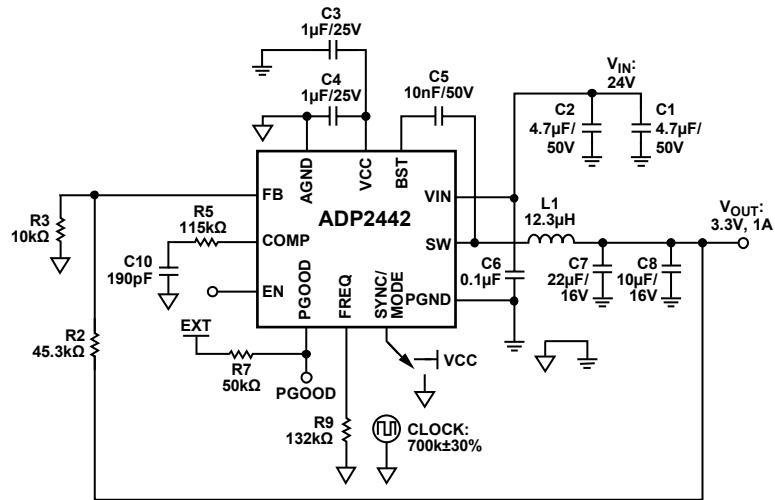


Figure 67. Typical Application Circuit,  $V_{IN} = 24\text{ V} \pm 10\%$ ,  $V_{OUT} = 3.3\text{ V}$ ,  $f_{SW} = 700\text{ kHz}$

Table 18. Calculated Component Values for Figure 67

| Quantity | Reference | Value              | Description   | Part Number              |
|----------|-----------|--------------------|---|--------------------------|
| 2        | C1, C2    | 4.7 $\mu\text{F}$  | Capacitor ceramic, X7R, 50 V                              | GRM31CR71H475KA12L       |
| 2        | C3, C4    | 1 $\mu\text{F}$    | Capacitor ceramic, 1 $\mu\text{F}$ , 25 V, X7R, 10%, 0603 | GRM188R71E105KA12D       |
| 2        | C5        | 10 nF              | Capacitor ceramic, 10 nF, 50 V, 10%, X7R, 0603            | ECJ-1VB1H103K            |
| 1        | C7        | 22 $\mu\text{F}$   | Capacitor ceramic, 22 $\mu\text{F}$ , 16 V, X7R, 1210     | GRM32ER71C226KEA8L       |
| 1        | C8        | 10 $\mu\text{F}$   | Capacitor ceramic, 10 $\mu\text{F}$ , 25 V, X7R, 1210     | GRM32DR71E106KA12L       |
| 1        | L1        | 12.3 $\mu\text{H}$ | Inductor  | CoilCraft MSS1038T-123ML |
| 1        | C6        | 0.1 $\mu\text{F}$  | Capacitor ceramic, 0.1 $\mu\text{F}$ , 50 V, X7R, 0805    | ECJ-2FB1H104K            |
| 1        | C10       | 190 pF             | Capacitor ceramic, 50 V                                   | Determined by user       |
| 1        | R9        | 132 k $\Omega$     | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |
| 1        | R5        | 115 k $\Omega$     | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |
| 1        | R2        | 45.3 k $\Omega$    | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |
| 1        | R3        | 10 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |
| 1        | R7        | 50 k $\Omega$      | Resistor, 1/10 W, 1%, 0603, SMD                           | Determined by user       |

## POWER DISSIPATION AND THERMAL CONSIDERATIONS

### POWER DISSIPATION

The efficiency of a dc-to-dc regulator is

$$\text{Efficiency} = \frac{P_{OUT}}{P_{IN}} \times 100\% \quad (26)$$

where:

$P_{IN}$  is the input power.

$P_{OUT}$  is the output power.

The power loss of a dc-to-dc regulator is

$$P_{LOSS} = P_{IN} - P_{OUT}$$

There are four main sources of power loss in a dc-to-dc regulator

- Inductor losses
- Power switch conduction losses
- Switching losses
- Transition losses

#### Inductor Losses

Inductor conduction losses are caused by the flow of current through the inductor DCR (internal resistance). The inductor power loss (excluding core loss) is

$$P_L = I_{OUT}^2 \times DCR_L \quad (27)$$

#### Power Switch Conduction Losses

Power switch conduction losses are caused by the output current,  $I_{OUT}$ , flowing through the N-channel MOSFET power switches that have internal resistance,  $R_{DS(ON)}$ . The amount of power loss can be approximated as follows:

$$P_{COND} = [R_{DS(ON) - HIGH\ SIDE} \times D + R_{DS(ON) - LOW\ SIDE} \times (1 - D)] \times I_{OUT}^2 \quad (28)$$

#### Switching Losses

Switching losses are associated with the current drawn by the driver to turn the power devices on and off at the switching frequency. Each time a power device gate is turned on and off, the driver transfers a charge ( $\Delta Q$ ) from the input supply to the gate and then from the gate to ground.

The amount of switching loss can be calculated as follows:

$$P_{SW} = Q_{G\_TOTAL} \times V_{IN} \times f_{SW} \quad (29)$$

where:

$Q_{G\_TOTAL}$  is the total gate charge of both the high-side and low-side devices and is approximately 18 nC.  $f_{SW}$  is the switching frequency.

#### Transition Losses

Transition losses occur because the N-channel MOSFET power switch cannot turn on or off instantaneously. During a switch node transition, the power switch provides all of the inductor current, and the source-to-drain voltage of the power switch is half the input, resulting in power loss. Transition losses increase as the load current and input voltage increase; these losses occur twice for each switching cycle.

The transition losses can be calculated as follows:

$$P_{TRANS} = \frac{V_{IN}}{2} \times I_{OUT} \times (t_{ON} + t_{OFF}) f_{SW} \quad (30)$$

where  $t_{ON}$  and  $t_{OFF}$  are the rise time and fall time of the switch node and are each approximately 10 ns for a 24 V input.

### THERMAL CONSIDERATIONS

The power dissipated by the regulator increases the die junction temperature,  $T_J$ , above the ambient temperature,  $T_A$ , as follows:

$$T_J = T_A + T_R \quad (31)$$

where the temperature rise,  $T_R$ , is proportional to the power dissipation,  $P_D$ , in the package.

The proportionality coefficient is defined as the thermal resistance from the junction temperature of the die to the ambient temperature, as follows:

$$T_R = \theta_{JA} + P_D \quad (32)$$

where  $\theta_{JA}$  is the junction-to-ambient thermal resistance and equals 40°C/W for the JEDEC board (see Table 3).

When designing an application for a particular ambient temperature range, calculate the expected ADP2442 power dissipation (PD) due to the conduction, switching, and transition losses using Equation 28, Equation 29, and Equation 30, and then estimate the temperature rise using Equation 31 and Equation 32. Improved thermal performance can be achieved by good board layout.

For example, on the ADP2442 evaluation board (ADP2442-EVALZ), the measured  $\theta_{JA}$  is <30°C/W. Thermal performance of the ADP2442-EVALZ evaluation board is shown in Figure 68 and Figure 69.

EVALUATION BOARD THERMAL PERFORMANCE

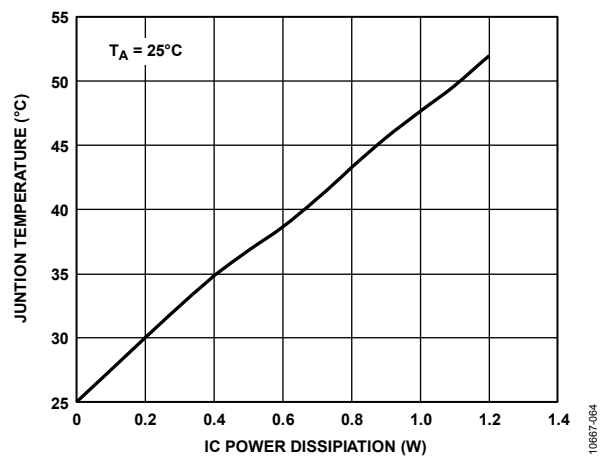


Figure 68. Junction Temperature vs. Power Dissipation Based on ADP2442-EVALZ

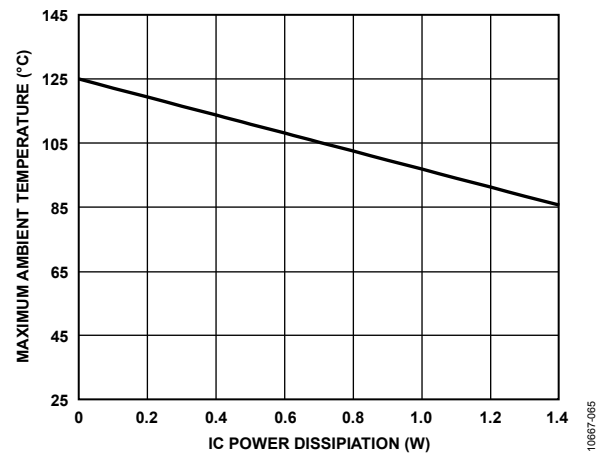


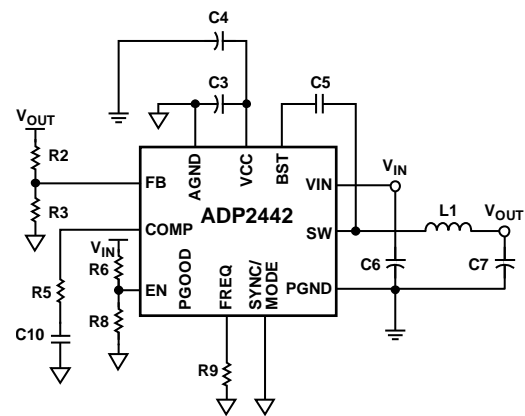
Figure 69. Maximum Ambient Temperature vs. Power Dissipation Based on ADP2442-EVALZ

## CIRCUIT BOARD LAYOUT RECOMMENDATIONS

Good printed circuit board (PCB) layout is essential for obtaining optimum performance. Poor PCB layout degrades the output voltage ripple; the load, line, and feedback regulation; and the EMI and electromagnetic compatibility performance. For optimum layout, refer to the following guidelines:

- Use separate analog and power ground planes. Connect the ground reference of sensitive analog circuitry, such as the output voltage divider component and the compensation and frequency resistor, to analog ground. In addition, connect the ground references of power components, such as input and output capacitors, to power ground. Connect both ground planes to the exposed pad of the [ADP2442](#).
- Place one end of the input capacitor as close as possible to the VIN pin, and connect the other end to the closest power ground plane.
- Place a high frequency filter capacitor between the VIN and PGND pins, as close as possible to the PGND pin.
- VCC is the internal regulator output. Place a 1  $\mu$ F capacitor between the VCC and AGND pins and another 1  $\mu$ F capacitor between the VCC and PGND pins. Place the capacitors as close as possible to the pins.
- Ensure that the high current loop traces are as short and wide as possible. Make the high current path from C<sub>IN</sub> through L, C<sub>OUT</sub>, and the power ground plane back to C<sub>IN</sub> as short as possible. To accomplish this, ensure that the input and output capacitors share a common power ground plane.
- Make the high current path from the PGND pin through L and C<sub>OUT</sub> back to the power ground plane as short as possible. To do this, ensure that the PGND pin is tied to the PGND plane as close as possible to the input and output capacitors (see Figure 70).
- Connect the [ADP2442](#) exposed pad to a large copper plane to maximize its power dissipation capability.
- Place the feedback resistor divider network as close as possible to the FB pin to prevent noise pickup. Keep the length of the trace connecting the top of the feedback resistor divider to the output as short as possible and, to avoid noise pickup, also keep it away from the high current traces and switch node. Place an analog ground plane on either side of the FB trace, further reducing noise pickup.

- The placement and routing of the compensation components are critical for optimum performance of [ADP2442](#). Place the compensation components as close as possible to the COMP pin. Use 0402 sized compensation components to allow closer placement, which in turn reduces parasitic noise.
- Surround the compensation components with AGND to prevent noise pickup.
- The FREQ pin is sensitive to noise; therefore, place the frequency resistor as close as possible to the FREQ pin and route it with minimal trace length.
- Ground the small signal components to the analog ground path.



NOTES  
1. THICK LINE INDICATES HIGH CURRENT TRACE.

Figure 70. High Current Trace

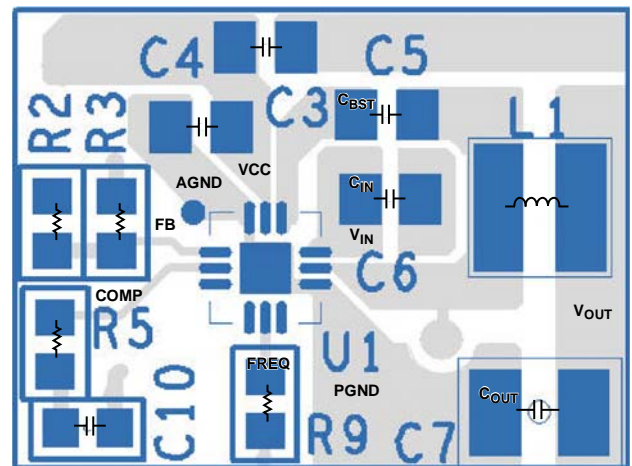
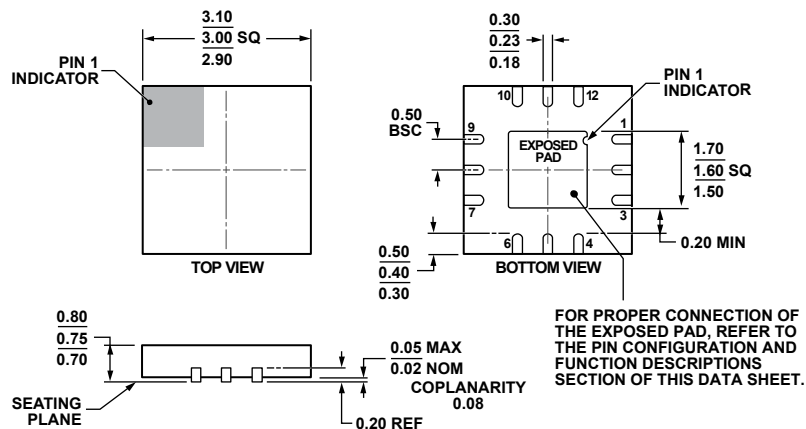


Figure 71. PCB Top Layer Placement



OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-229-WEED-4.

Figure 72. 12-Lead Lead Frame Chip Scale Package [LFCSP\_WQ]  
3 mm × 3 mm Body, Very Very Thin Quad  
(CP-12-6)  
Dimensions shown in millimeters

ORDERING GUIDE

| Model <sup>1</sup> | Output Voltage | Temperature Range | Package Description                              | Package Option | Branding |
|--------------------|----------------|-------------------|--|----------------|----------|
| ADP2442ACPZ-R7     | Adjustable     | −40°C to +125°C   | 12-Lead Lead Frame Chip Scale Package [LFCSP_WQ] | CP-12-6        | LK5      |
| ADP2442-EVALZ      |                |                   | Evaluation Board (Preset to 5 V)                 |                |          |

<sup>1</sup> Z = RoHS Compliant Part.

## NOTES

**NOTES**