

# AD526\* PRODUCT PAGE QUICK LINKS

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- AN-245: Instrumentation Amplifiers Solve Unusual Design Problems
- AN-282: Fundamentals of Sampled Data Systems
- AN-589: Ways to Optimize the Performance of a Difference Amplifier
- AN-671: Reducing RFI Rectification Errors in In-Amp Circuits

### Data Sheet

- AD526 Military Data Sheet
- AD526: Software Programmable Gain Amplifier Data Sheet

### Technical Books

- A Designer's Guide to Instrumentation Amplifiers, 3rd Edition, 2006

## REFERENCE MATERIALS

### Technical Articles

- Auto-Zero Amplifiers
- High-performance Adder Uses Instrumentation Amplifiers
- Input Filter Prevents Instrumentation-amp RF-Rectification Errors
- The AD8221 - Setting a New Industry Standard for Instrumentation Amplifiers

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# AD526—SPECIFICATIONS (@ $V_S = \pm 15\text{ V}$ , $R_L = 2\text{ k}\Omega$ and $T_A = +25^\circ\text{C}$ unless otherwise noted)

Model	AD526J			AD526A			AD526B/S			AD526C			Units
	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
GAIN													
Gain Range (Digitally Programmable)	1, 2, 4, 8, 16			1, 2, 4, 8, 16			1, 2, 4, 8, 16			1, 2, 4, 8, 16			
Gain Error													
Gain = 1			0.05			0.02			0.01			0.01	%
Gain = 2			0.05			0.03			0.02			0.01	%
Gain = 4			0.10			0.03			0.02			0.01	%
Gain = 8			0.15			0.07			0.04			0.02	%
Gain = 16			0.15			0.07			0.04			0.02	%
Gain Error Drift													
Over Temperature													
G = 1		0.5	2.0		0.5	2.0		0.5	2.0		0.5	2.0	ppm/°C
G = 2		0.5	2.0		0.5	2.0		0.5	2.0		0.5	2.0	ppm/°C
G = 4		0.5	3.0		0.5	3.0		0.5	3.0		0.5	3.0	ppm/°C
G = 8		0.5	5.0		0.5	5.0		0.5	5.0		0.5	5.0	ppm/°C
G = 16		1.0	5.0		1.0	5.0		1.0	5.0		1.0	5.0	ppm/°C
Gain Error (T <sub>MIN</sub> to T <sub>MAX</sub> )													
Gain = 1			0.06			0.03			0.02			0.015	%
Gain = 2			0.06			0.04			0.03			0.015	%
Gain = 4			0.12			0.04			0.03			0.015	%
Gain = 8			0.17			0.08			0.05			0.03	%
Gain = 16			0.17			0.08			0.05			0.03	%
Nonlinearity													
Gain = 1			0.005			0.005			0.005			0.0035	% FSR
Gain = 2			0.001			0.001			0.001			0.001	% FSR
Gain = 4			0.001			0.001			0.001			0.001	% FSR
Gain = 8			0.001			0.001			0.001			0.001	% FSR
Gain = 16			0.001			0.001			0.001			0.001	% FSR
Nonlinearity (T <sub>MIN</sub> to T <sub>MAX</sub> )													
Gain = 1			0.01			0.01			0.01			0.007	% FSR
Gain = 2			0.001			0.001			0.001			0.001	% FSR
Gain = 4			0.001			0.001			0.001			0.001	% FSR
Gain = 8			0.001			0.001			0.001			0.001	% FSR
Gain = 16			0.001			0.001			0.001			0.001	% FSR
VOLTAGE OFFSET, ALL GAINS													
Input Offset Voltage		0.4	1.5		0.25	0.7		0.25	0.5		0.25	0.5	mV
Input Offset Voltage Drift Over Temperature		5	20		3	10		3	10		3	10	μV/°C
Input Offset Voltage T <sub>MIN</sub> to T <sub>MAX</sub>			2.0			1.0			0.8			0.8	mV
Input Offset Voltage vs. Supply (V <sub>S</sub> ± 10%)	80			80			84			90			dB
INPUT BIAS CURRENT													
Over Input Voltage Range ± 10 V		50	150		50	150		50	150		50	150	pA
ANALOG INPUT CHARACTERISTICS													
Voltage Range (Linear Operation)	±10	±12		±10	±12		±10	±12		±10	±12		V
Capacitance		5			5			5			5		pF
RATED OUTPUT													
Voltage	±10	±12		±10	±12		±10	±12		±10	±12		V
Current (V <sub>OUT</sub> = ±10 V)		±10		±5	±10		±5	±10		±5	±10		mA
Short-Circuit Current	15	30		15	30		15	30		15	30		mA
DC Output Resistance		0.002			0.002			0.002			0.002		Ω
Load Capacitance (For Stable Operation)		700			700			700			700		pF

Model	AD526J			AD526A			AD526B/S			AD526C			Units
	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
NOISE, ALL GAINS													
Voltage Noise, RTI 0.1 Hz to 10 Hz		3			3			3			3		μV p-p
Voltage Noise Density, RTI f = 10 Hz		70			70			70			70		nV√Hz
f = 100 Hz		60			60			60			60		nV√Hz
f = 1 kHz		30			30			30			30		nV√Hz
f = 10 kHz		25			25			25			35		nV√Hz
DYNAMIC RESPONSE													
−3 dB Bandwidth (Small Signal)													
G = 1		4.0			4.0			4.0			4.0		MHz
G = 2		2.0			2.0			2.0			2.0		MHz
G = 4		1.5			1.5			1.5			1.5		MHz
G = 8		0.65			0.65			0.65			0.65		MHz
G = 16		0.35			0.35			0.35			0.35		MHz
Signal Settling Time to 0.01% (ΔV <sub>OUT</sub> = ±10 V)													
G = 1		2.1	4		2.1	4		2.1	4		2.1	4	μs
G = 2		2.5	5		2.5	5		2.5	5		2.5	5	μs
G = 4		2.7	5		2.7	5		2.7	5		2.7	5	μs
G = 8		3.6	7		3.6	7		3.6	7		3.6	7	μs
G = 16		4.1	7		4.1	7		4.1	7		4.1	7	μs
Full Power Bandwidth													
G = 1, 2, 4		0.10			0.10			0.10			0.10		MHz
G = 8, 16		0.35			0.35			0.35			0.35		MHz
Slew Rate													
G = 1, 2, 4	4	6		4	6		4	6		4	6		V/μs
G = 8, 16	18	24		18	24		18	24		18	24		V/μs
DIGITAL INPUTS													
(T <sub>MIN</sub> to T <sub>MAX</sub> )													
Input Current (V <sub>H</sub> = 5 V)	60	100	140	60	100	140	60	100	140	60	100	140	μA
Logic “1”	2		6	2		6	2		6	2		6	V
Logic “0”	0		0.8	0		0.8	0		0.8	0		0.8	V
TIMING <sup>1</sup>													
(V <sub>L</sub> = 0.2 V, V <sub>H</sub> = 3.7 V)													
A0, A1, A2													
T <sub>C</sub>	50			50			50			50			ns
T <sub>S</sub>	30			30			30			30			ns
T <sub>H</sub>	30			30			30			30			ns
B													
T <sub>C</sub>	50			50			50			50			ns
T <sub>S</sub>	40			40			40			40			ns
T <sub>H</sub>	10			10			10			30			ns
TEMPERATURE RANGE													
Specified Performance	0		+70	−40		+85	−40/−55		+85/+125	−40		+85	°C
Storage	−65		+125	−65		+150	−65		+150	−65		+150	°C
POWER SUPPLY													
Operating Range	±4.5		±16.5	±4.5		±16.5	±4.5		±16.5	±4.5		±16.5	V
Positive Supply Current		10	14		10	14		10	14		10	14	mA
Negative Supply Current		10	13		10	13		10	13		10	13	mA
PACKAGE OPTIONS													
Plastic (N-16)	AD526JN			AD526AD			AD526BD AD526SD			AD526CD			
Ceramic DIP (D-16)							AD526SD/883B						

## NOTES

<sup>1</sup>Refer to Figure 25 for definitions. FSR = Full Scale Range = 20 V. RTI = Referred to Input.

Specifications subject to change without notice.

Specifications shown in **boldface** are tested on all production units at final electrical test. All min and max specifications are guaranteed, although only those shown in boldface are tested on all production units.

# AD526—Typical Performance Characteristics

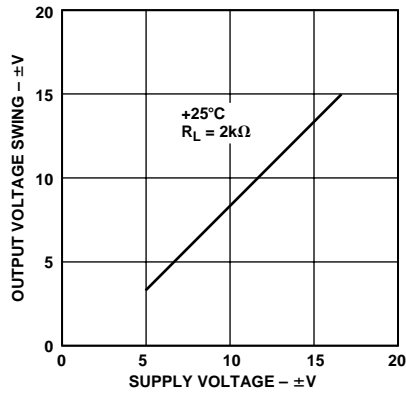


Figure 1. Output Voltage Swing vs. Supply Voltage,  $G = 16$

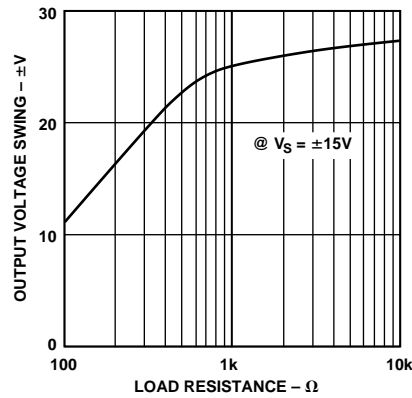


Figure 2. Output Voltage Swing vs. Load Resistance

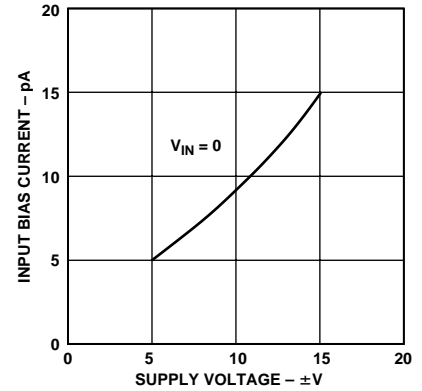


Figure 3. Input Bias Current vs. Supply Voltage

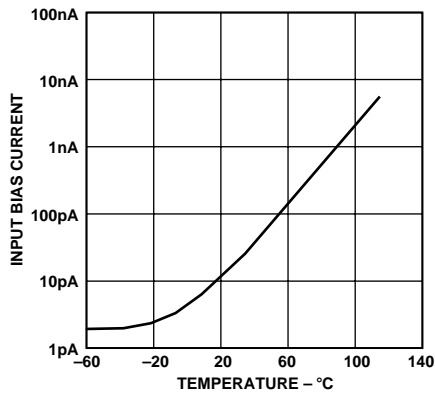


Figure 4. Input Bias Current vs. Temperature

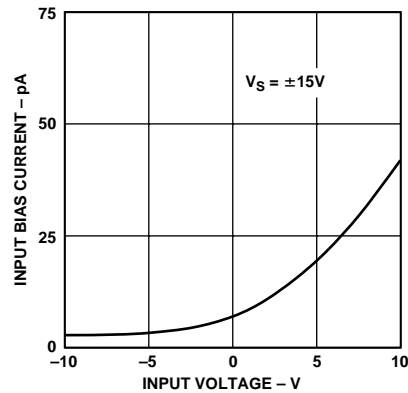


Figure 5. Input Bias Current vs. Input Voltage

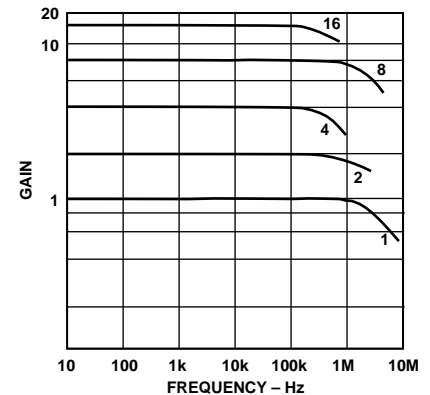


Figure 6. Gain vs. Frequency

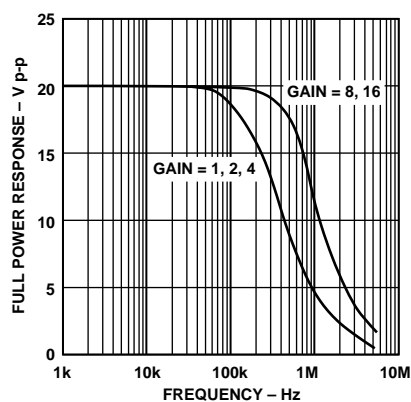


Figure 7. Large Signal Frequency Response

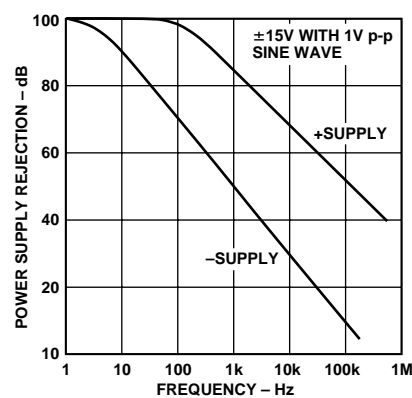


Figure 8. PSRR vs. Frequency

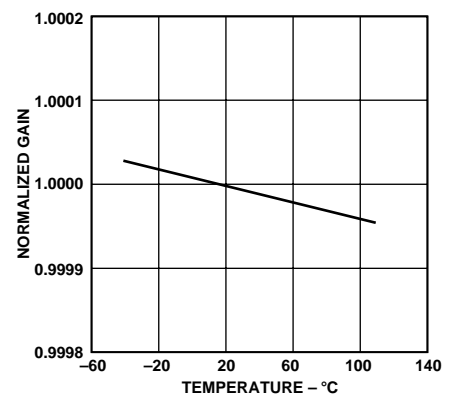


Figure 9. Normalized Gain vs. Temperature, Gain = 1

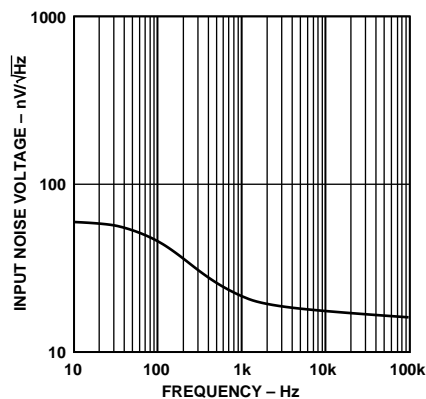


Figure 10. Noise Spectral Density

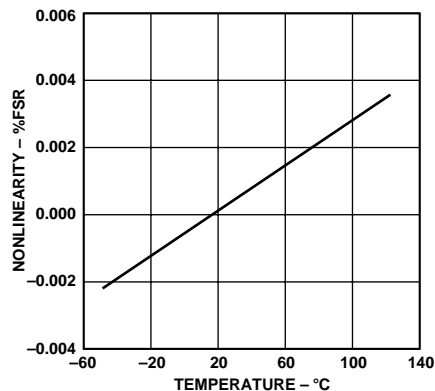


Figure 11. Nonlinearity vs. Temperature, Gain = 1

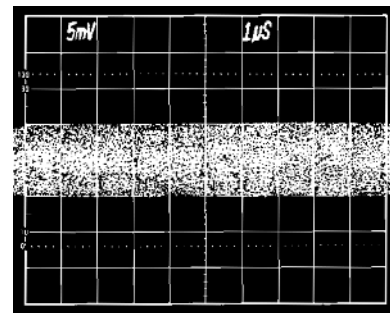


Figure 12. Wideband Output Noise, G = 16 (Amplified by 10)

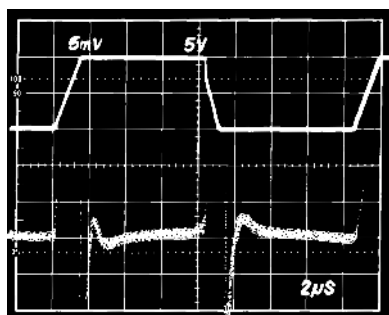


Figure 13. Large Signal Pulse Response and Settling Time,\* G = 1

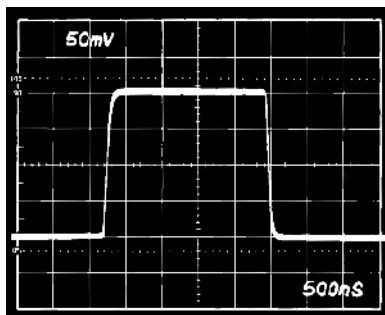


Figure 14. Small Signal Pulse Response, G = 1

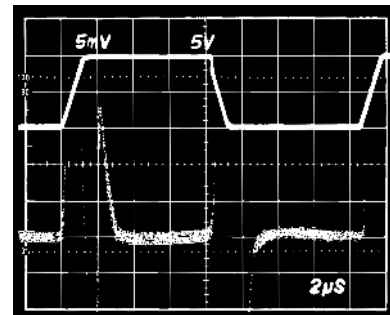


Figure 15. Large Signal Pulse Response and Settling Time,\* G = 2

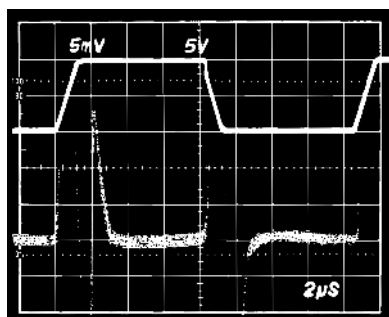


Figure 16. Small Signal Pulse Response, G = 2

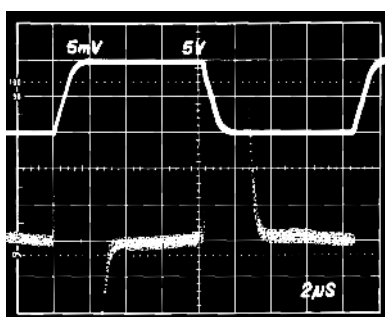


Figure 17. Large Signal Pulse Response and Settling Time,\* G = 4

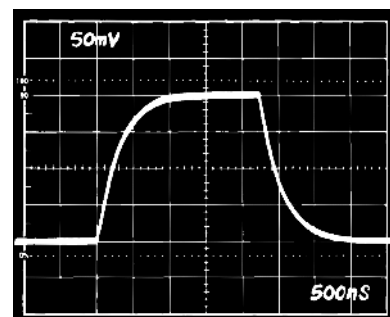


Figure 18. Small Signal Pulse Response, G = 4

\*For Settling Time Traces, 0.01% = 1/2 Vertical Division

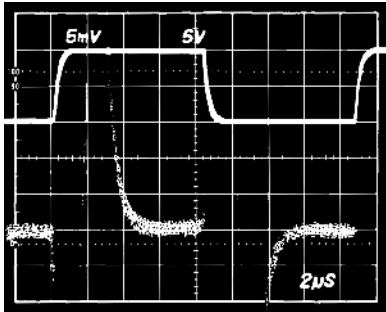


Figure 19. Large Signal Pulse Response and Settling Time,\*  $G = 8$

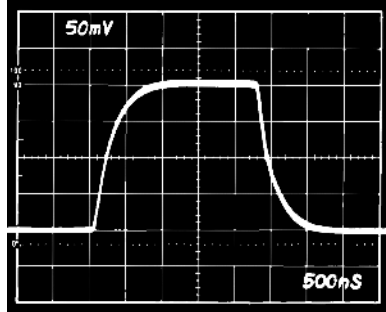


Figure 20. Small Signal Pulse Response,  $G = 8$

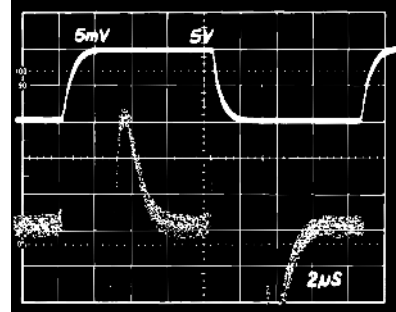


Figure 21. Large Signal Pulse Response and Settling Time,\*  $G = 16$

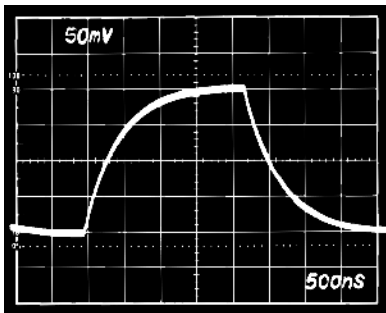


Figure 22. Small Signal Pulse Response, Gain = 16

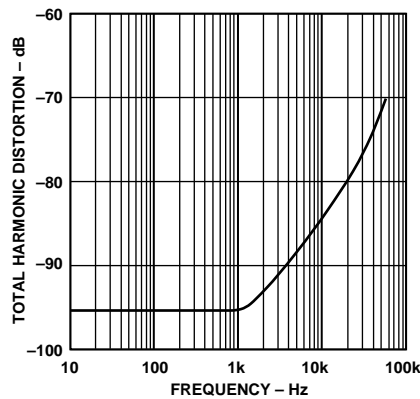


Figure 23. Total Harmonic Distortion vs. Frequency Gain = 16

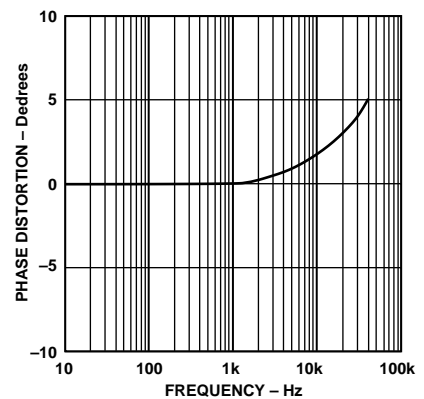


Figure 24. Phase Distortion vs. Frequency, Gain = 16

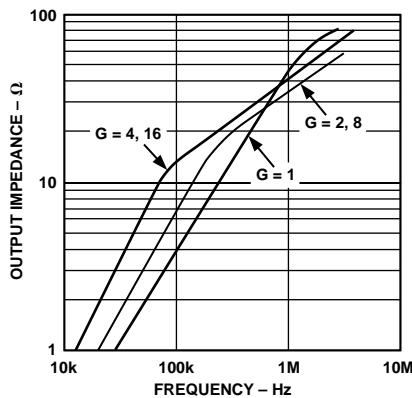


Figure 25. Output Impedance vs. Frequency

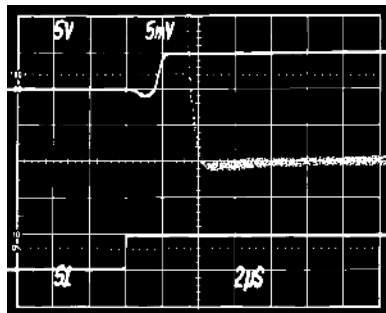


Figure 26. Gain Change Settling Time,\*\* Gain Change: 1 to 2

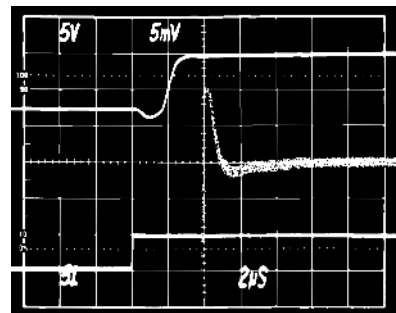


Figure 27. Gain Change Settling Time,\*\* Gain Change 1 to 4

\*For Settling Time Traces, 0.01% = 1/2 Vertical Division

\*\*Scope Traces are: Top: Output Transition; Middle: Output Settling; Bottom: Digital Input.

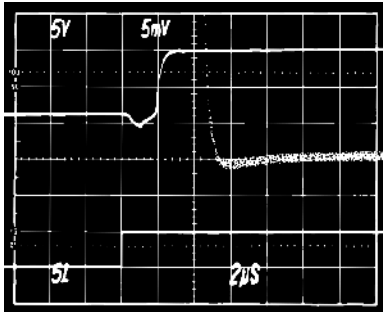


Figure 28. Gain Change Settling Time,\* Gain Change 1 to 8

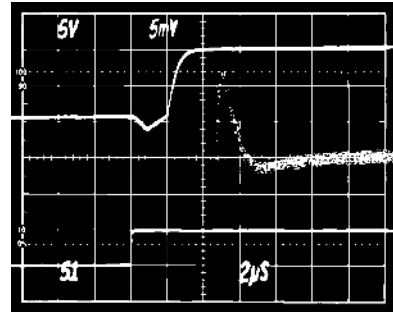


Figure 29. Gain Change Settling Time,\* Gain Change 1 to 16

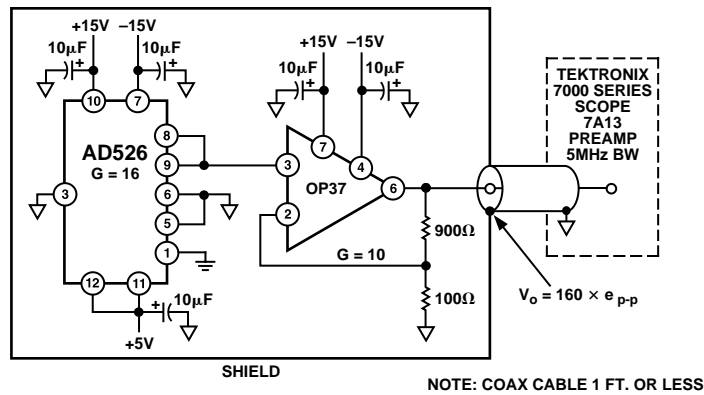


Figure 30. Wideband Noise Test Circuit

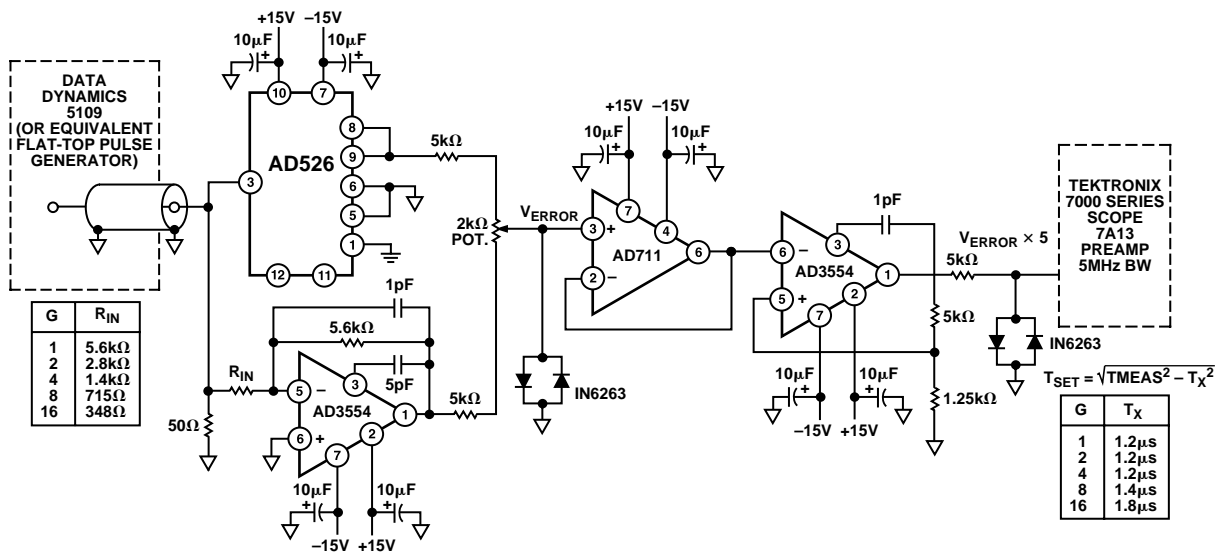


Figure 31. Settling Time Test Circuit

\*Scope Traces are:  
Top: Output Transition  
Middle: Output Settling  
Bottom: Digital Input

# AD526

## THEORY OF OPERATION

The AD526 is a complete software programmable gain amplifier (SPGA) implemented monolithically with a drift-trimmed BiFET amplifier, a laser wafer trimmed resistor network, JFET analog switches and TTL compatible gain code latches.

A particular gain is selected by applying the appropriate gain code (see Table I) to the control logic. The control logic turns on the JFET switch that connects the correct tap on the gain network to the inverting input of the amplifier; all unselected JFET gain switches are off (open). The "on" resistance of the gain switches causes negligible gain error since only the amplifier's input bias current, which is less than 150 pA, actually flows through these switches.

The AD526 is capable of storing the gain code, (latched mode), B, A0, A1, A2, under the direction of control inputs  $\overline{\text{CLK}}$  and  $\overline{\text{CS}}$ . Alternatively, the AD526 can respond directly to gain code changes if the control inputs are tied low (transparent mode).

For gains of 8 and 16, a fraction of the frequency compensation capacitance (C1 in Figure 32) is automatically switched out of the circuit. This increases the amplifier's bandwidth and improves its signal settling time and slew rate.

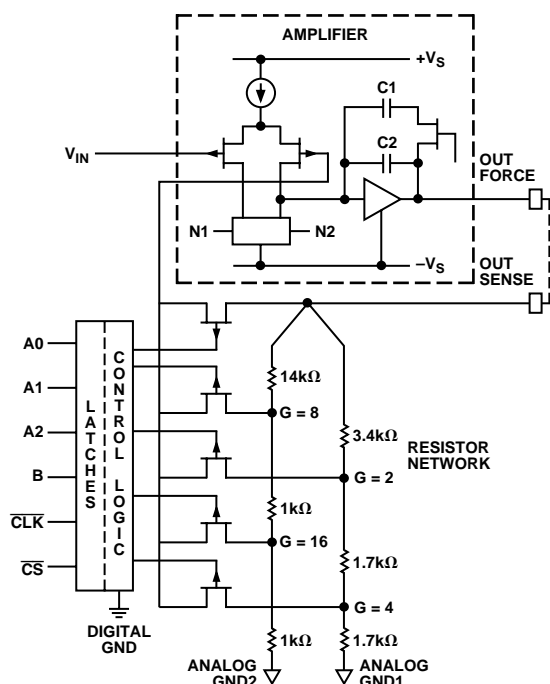


Figure 32. Simplified Schematic of the AD526

## TRANSPARENT MODE OF OPERATION

In the transparent mode of operation, the AD526 will respond directly to level changes at the gain code inputs (A0, A1, A2) if B is tied high and both  $\overline{\text{CS}}$  and  $\overline{\text{CLK}}$  are allowed to float low.

After the gain codes are changed, the AD526's output voltage typically requires 5.5  $\mu\text{s}$  to settle to within 0.01% of the final value. Figures 26 to 29 show the performance of the AD526 for positive gain code changes.

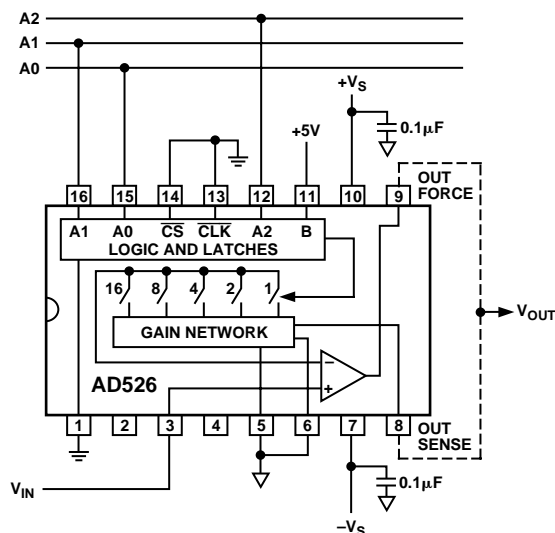


Figure 33. Transparent Mode

## LATCHED MODE OF OPERATION

The latched mode of operation is shown in Figure 34. When either  $\overline{\text{CS}}$  or  $\overline{\text{CLK}}$  go to a Logic "1," the gain code (A0, A1, A2, B) signals are latched into the registers and held until both  $\overline{\text{CS}}$  and  $\overline{\text{CLK}}$  return to "0." Unused  $\overline{\text{CS}}$  or  $\overline{\text{CLK}}$  inputs should be tied to ground. The  $\overline{\text{CS}}$  and  $\overline{\text{CLK}}$  inputs are functionally and electrically equivalent.

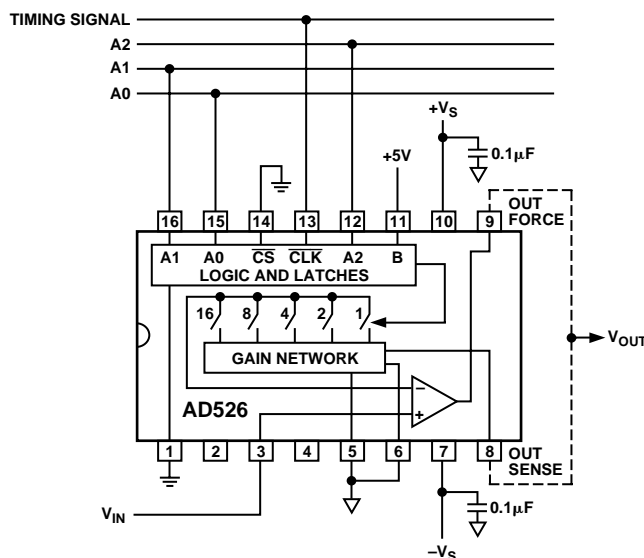


Figure 34. Latched Mode



## TIMING AND CONTROL

Table I. Logic Input Truth Table

Gain Code				Control	Condition	Condition
A2	A1	A0	B	$\overline{\text{CLK}}$ ( $\overline{\text{CS}} = 0$ )	Gain	
X	X	X	X	1	Previous State	Latched
0	0	0	1	0	1	Transparent
0	0	1	1	0	2	Transparent
0	1	0	1	0	4	Transparent
0	1	1	1	0	8	Transparent
1	X	X	1	0	16	Transparent
X	X	X	0	0	1	Transparent
X	X	X	0	1	1	Latched
0	0	0	1	1	1	Latched
0	0	1	1	1	2	Latched
0	1	0	1	1	4	Latched
0	1	1	1	1	8	Latched
1	X	X	1	1	16	Latched

NOTE: X = Don't Care.

The specifications on page 3, in combination with Figure 35, give the timing requirements for loading new gain codes.

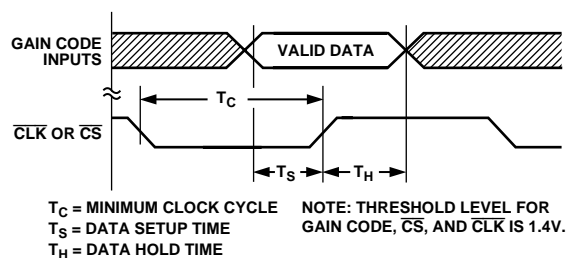


Figure 35. AD526 Timing

## DIGITAL FEEDTHROUGH

With either  $\overline{\text{CS}}$  or  $\overline{\text{CLK}}$  or both held high, the AD526 gain state will remain constant regardless of the transitions at the A0, A1, A2 or B inputs. However, high speed logic transitions will unavoidably feed through to the analog circuitry within the AD526 causing spikes to occur at the signal output.

This feedthrough effect can be completely eliminated by operating the AD526 in the transparent mode and latching the gain code in an external bank of latches (Figure 36).

To operate the AD526 using serial inputs, the configuration shown in Figure 36 can be used with the 74LS174 replaced by a serial-in/parallel-out latch, such as the 54LS594.

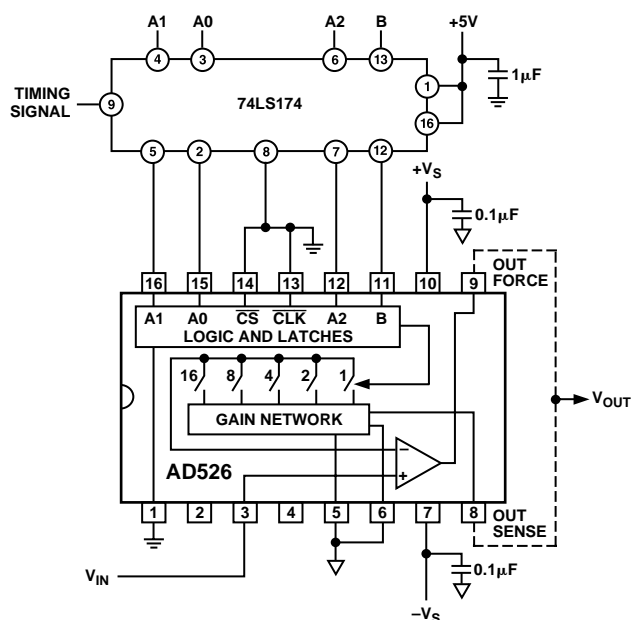


Figure 36. Using an External Latch to Minimize Digital Feedthrough

# AD526

## GROUNDING AND BYPASSING

Proper signal and grounding techniques must be applied in board layout so that specified performance levels of precision data acquisition components, such as the AD526, are not degraded.

As is shown in Figure 37, logic and signal grounds should be separate. By connecting the signal source ground locally to the AD526 analog ground Pins 5 and 6, gain accuracy of the AD526 is maintained. This ground connection should not be corrupted by currents associated with other elements within the system.

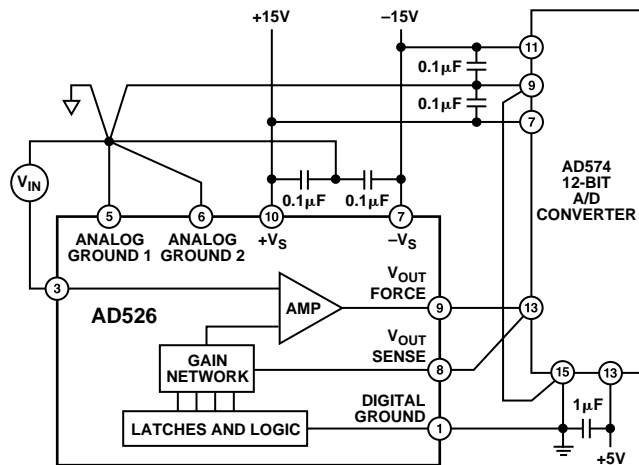


Figure 37. Grounding and Bypassing

Utilizing the force and sense outputs of the AD526, as shown in Figure 38, avoids signal drops along etch runs to low impedance loads.

Table II. Logic Table for Figure 38

$V_{OUT}/V_{IN}$	A2	A1	A0
1	0	0	0
2	0	0	1
4	0	1	0
8	0	1	1
16	1	0	0
32	1	0	1
64	1	1	0
128	1	1	1

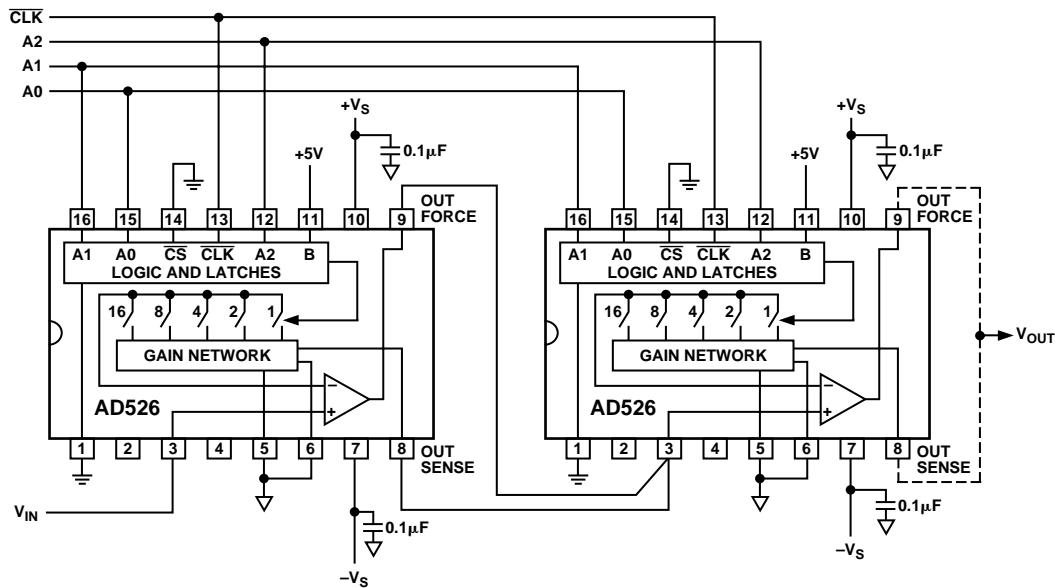


Figure 38. Cascaded Operation

### OFFSET NULLING

Input voltage offset nulling of the AD526 is best accomplished at a gain of 16, since the referred-to-input (RTI) offset is amplified the most at this gain and therefore is most easily trimmed. The resulting trimmed value of RTI voltage offset typically varies less than  $3\ \mu\text{V}$  across all gain ranges.

Note that the low input current of the AD526 minimizes RTI voltage offsets due to source resistance.

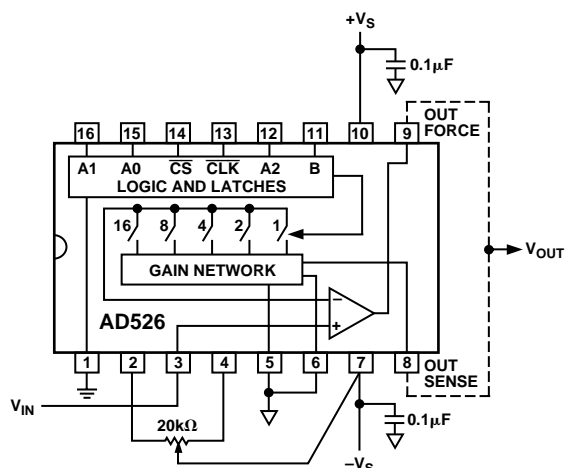


Figure 39. Offset Voltage Null Circuit

### OUTPUT CURRENT BOOSTER

The AD526 is rated for a full  $\pm 10\text{ V}$  output voltage swing into  $2\text{ k}\Omega$ . In some applications, the need exists to drive more current into heavier loads. As shown in Figure 40, a high current booster may be connected “inside the loop” of the SPGA to provide the required current boost without significantly degrading overall performance. Nonlinearities, offset and gain inaccuracies of the buffer are minimized by the loop gain of the AD526 output amplifier.

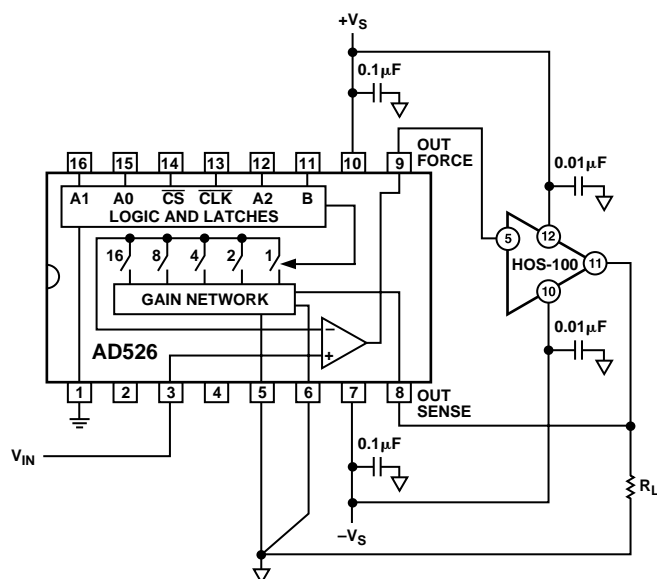


Figure 40. Current Output Boosting

### CASCADED OPERATION

A cascade of two AD526s can be used to achieve binarily weighted gains from 1 to 256. If gains from 1 to 128 are needed, no additional components are required. This is accomplished by using the B pin as shown in Figure 38. When the B pin is low, the AD526 is held in a unity gain stage independent of the other gain code values.

### OFFSET NULLING WITH A D/A CONVERTER

Figure 41 shows the AD526 with offset nulling accomplished with an 8-bit D/A converter (AD7524) circuit instead of the potentiometer shown in Figure 39. The calibration procedure is the same as before except that instead of adjusting the potentiometer, the D/A converter corrects for the offset error. This calibration circuit has a number of benefits in addition to eliminating the trimpot. The most significant benefit is that calibration can be under the control of a microprocessor and therefore can be implemented as part of an autocalibration scheme. Secondly, dip switches or RAM can be used to hold the 8-bit word after its value has been determined. In Figure 42 the offset null sensitivity, at a gain of 16, is  $80\ \mu\text{V}$  per LSB of adjustment, which guarantees dc accuracy to the 16-bit performance level.

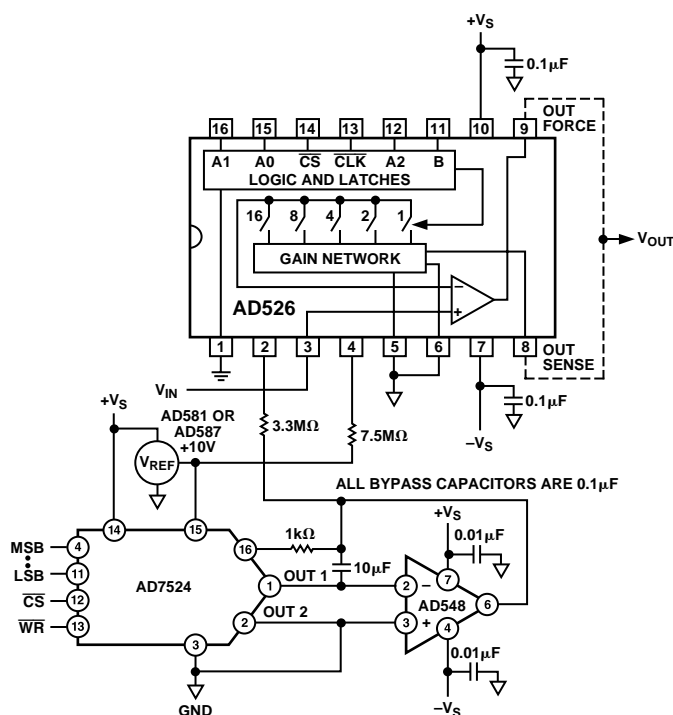


Figure 41. Offset Nulling Using a DAC

# AD526

## FLOATING-POINT CONVERSION

High resolution converters are used in systems to obtain high accuracy, improve system resolution or increase dynamic range. There are a number of high resolution converters available with throughput rates of 66.6 kHz that can be purchased as a single component solution; however in order to achieve higher throughput rates, alternative conversion techniques must be employed. A floating point A/D converter can improve both throughput rate and dynamic range of a system.

In a floating point A/D converter (Figure 42), the output data is presented as a 16-bit word, the lower 12 bits from the A/D converter form the mantissa and the upper 4 bits from the digital signal used to set the gain form the exponent. The AD526 programmable gain amplifier in conjunction with the comparator circuit scales the input signal to a range between half scale and full scale for the maximum usable resolution.

The A/D converter diagrammed in Figure 42 consists of a pair of AD585 sample/hold amplifiers, a flash converter, a five-range programmable gain amplifier (the AD526) and a fast 12-bit A/D converter (the AD7572). The floating-point A/D converter achieves its high throughput rate of 125 kHz by overlapping the acquisition time of the first sample/hold amplifier and the settling time of the AD526 with the conversion time of the A/D converter. The first sample/hold amplifier holds the signal for the flash autoranger, which determines which binary quantum

the input falls within, relative to full scale. Once the AD526 has settled to the appropriate level, then the second sample/hold amplifier can be put into hold which holds the amplified signal while the AD7572 perform its conversion routine. The acquisition time for the AD585 is 3  $\mu$ s, and the conversion time for the AD7572 is 5  $\mu$ s for a total of 8  $\mu$ s, or 125 kHz. This performance relies on the fast settling characteristics of the AD526 after the flash autoranging (comparator) circuit quantizes the input signal. A 16-bit register holds the 3-bit output from the flash autoranger and the 12-bit output of the AD7572.

The A/D converter in Figure 42 has a dynamic range of 96 dB. The dynamic range of a converter is the ratio of the full-scale input range to the LSB value. With a floating-point A/D converter the smallest value LSB corresponds to the LSB of the monolithic converter divided by the maximum gain of the PGA. The floating point A/D converter has a full-scale range of 5 V, a maximum gain of 16 V/V from the AD526 and a 12-bit A/D converter; this produces:

$$\text{LSB} = ([\text{FSR}/2^N]/\text{Gain}) = ([5 \text{ V}/4096]/16) = 76 \mu\text{V}.$$
 The dynamic range in dBs is based on the log of the ratio of the full-scale input range to the LSB;  $\text{dynamic range} = 20 \log (5 \text{ V}/76 \mu\text{V}) = 96 \text{ dB}.$

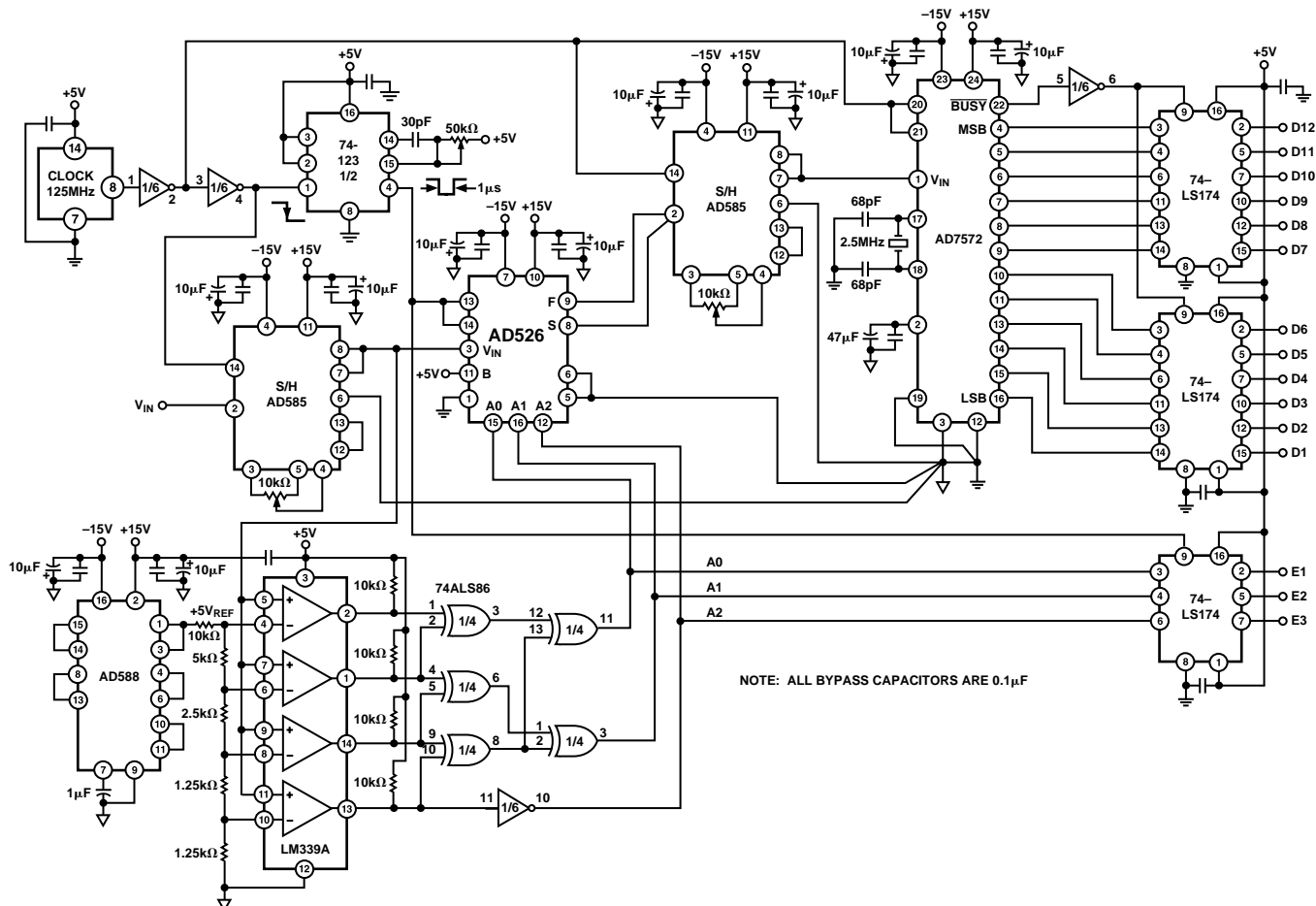


Figure 42. Floating-Point A/D Converter

### HIGH ACCURACY A/D CONVERTERS

Very high accuracy and high resolution floating-point A/D converters can be achieved by the incorporation of offset and gain calibration routines. There are two techniques commonly used for calibration, a hardware circuit as shown in Figure 43 and/or a software routine. In this application the microprocessor is functioning as the autoranging circuit, requiring software overhead; therefore, a hardware calibration technique was applied which reduces the software burden. The software is used to set the gain of the AD526. In operation the signal is converted, and if the MSB of the AD574 is not equal to a Logical 1, the gain is increased by binary steps, up to the maximum gain. This maximizes the full-scale range of the conversion process and insures a wide dynamic range.

The calibration technique uses two point correction, offset and gain. The hardware is simplified by the use of programmable magnitude comparators, the 74ALS528s, which can be "burned" for a particular code. In order to prevent under or over range

hunting during the calibration process, the reference offset and gain codes should be different from the endpoint codes. A calibration cycle consists of selecting whether gain or offset is to be calibrated then selecting the appropriate multiplexer channel to apply the reference voltage to the signal channel. Once the operation has been initiated, the counter, a 74ALS869, drives the D/A converter in a linear fashion providing a small correction voltage to either the gain or offset trim point of the AD574. The output of the A/D converter is then compared to the value preset in the 74ALS528 to determine a match. Once a match is detected, the 74ALS528 produces a low going pulse which stops the counter. The code at the D/A converter is latched until the next calibration cycle. Calibration cycles are under the control of the microprocessor in this application and should be implemented only during periods of converter inactivity.

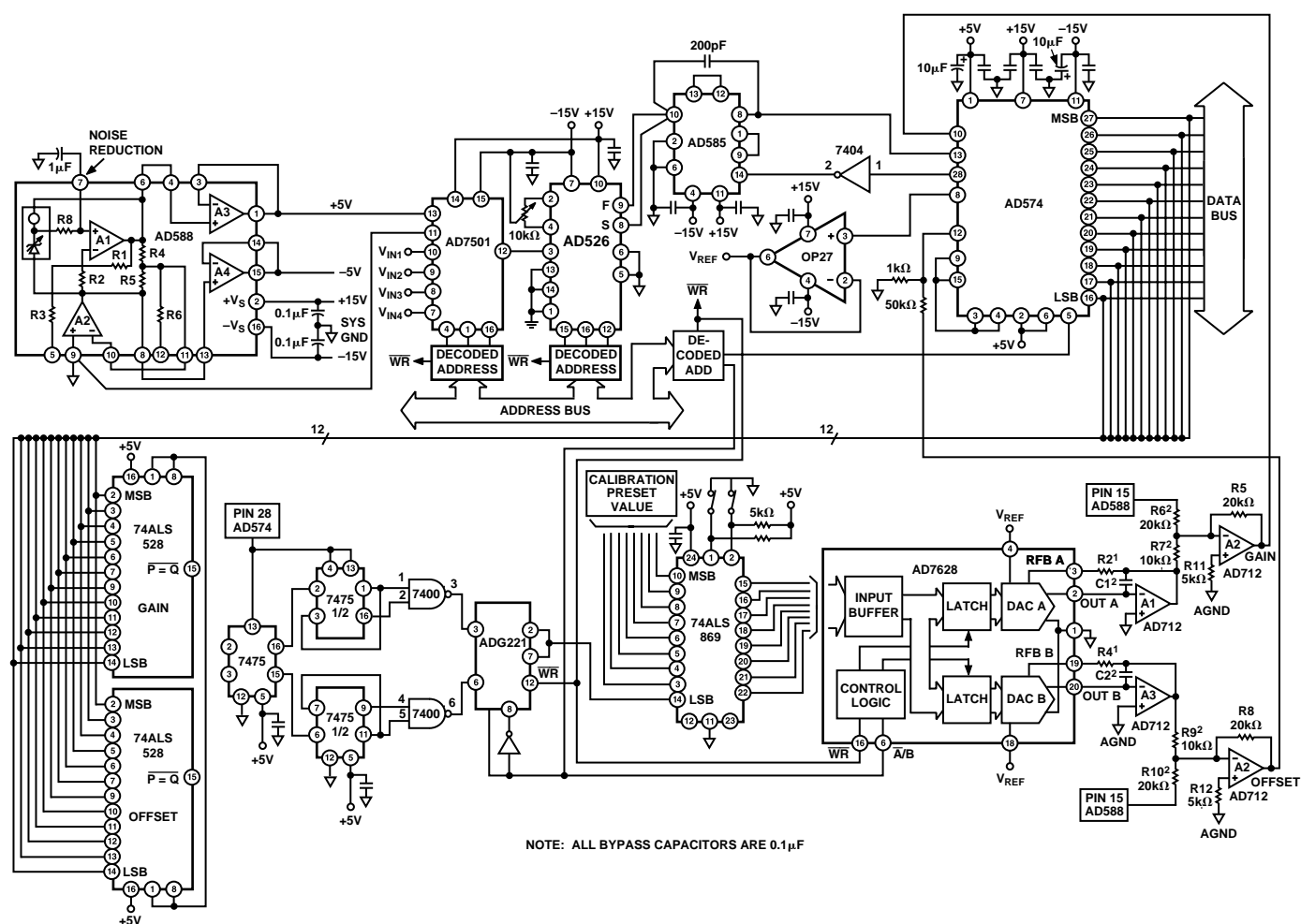
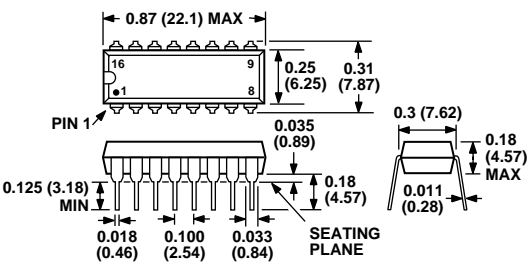


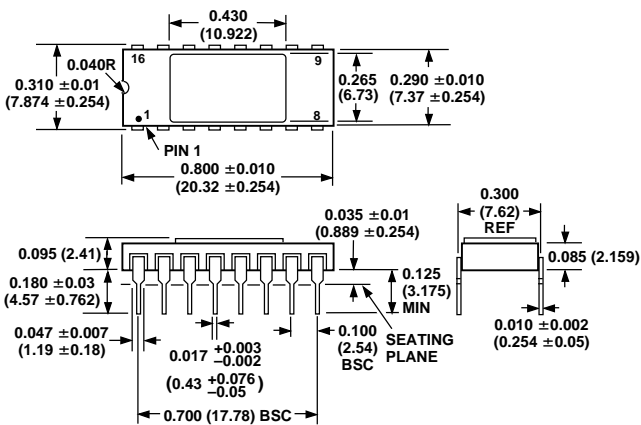
Figure 43. High Accuracy A/D Converter

OUTLINE DIMENSIONS  
Dimensions shown in inches and (mm).

16-Lead Plastic  
DIP Package (N-16)



16-Lead Sided-Brazed  
Ceramic Package (D-16)



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