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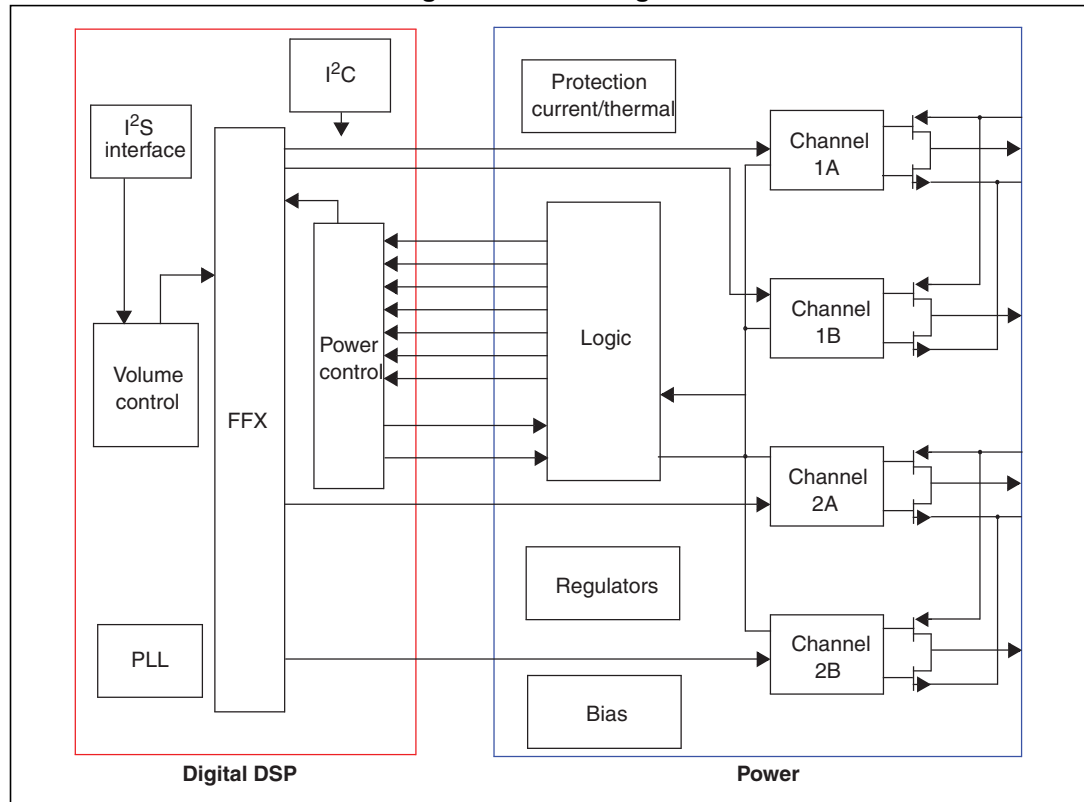
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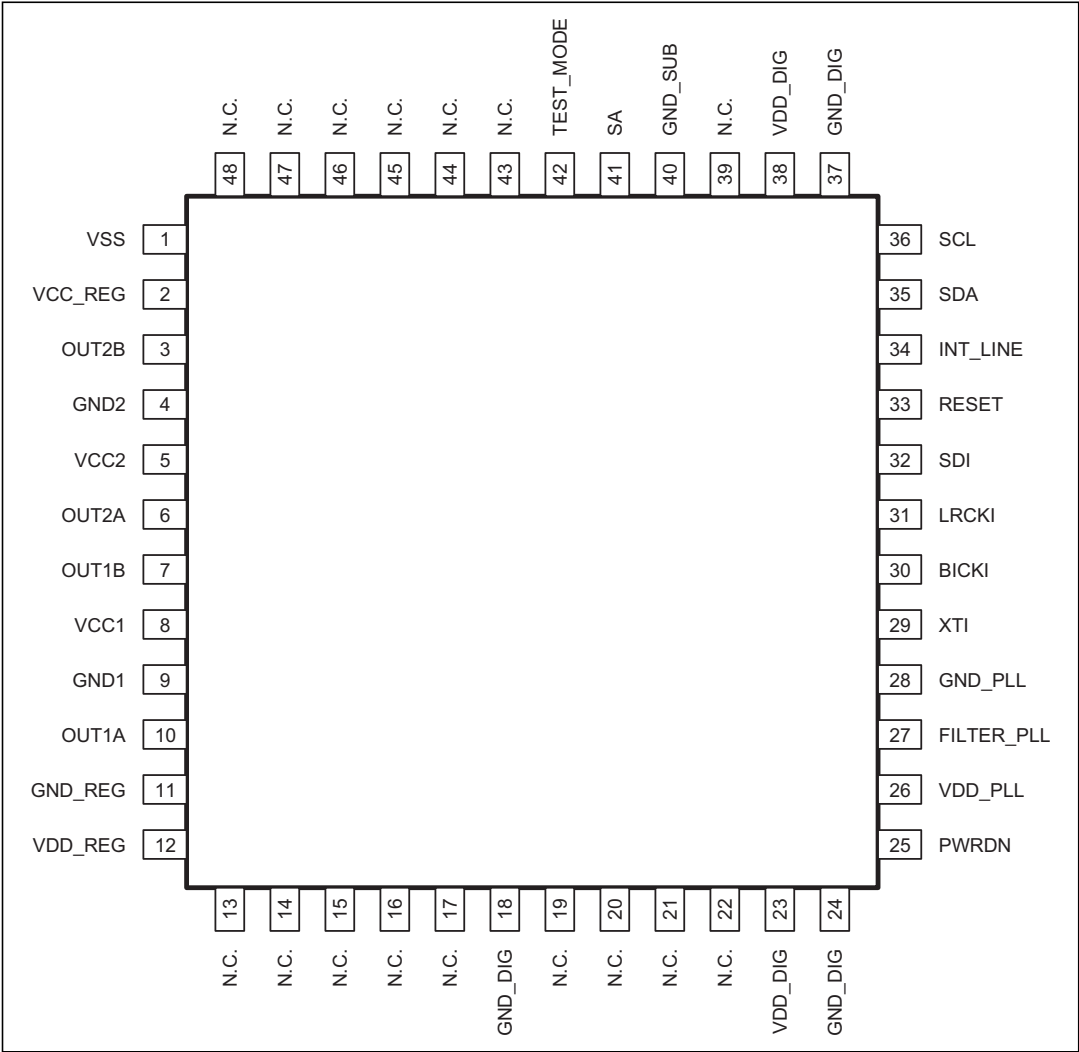
1 Block diagram

Figure 1. Block diagram

2 Pin description

2.1 Pinout

Figure 2. Pin connections (package top view)



2.2 Pin list

Table 2. Pin description

Number	Type	Name	Description
1	I/O	VSS	Internal reference at $V_{CC} - 3.3\text{ V}$
2	I/O	VCC_REG	Internal V_{CC} reference
3	O	OUT2B	Output half-bridge 2B
4	PWR	GND2	Power negative supply
5	PWR	VCC2	Power positive supply
6	O	OUT2A	Output half-bridge 2A
7	O	OUT1B	Output half-bridge 1B
8	PWR	VCC1	Power positive supply
9	PWR	GND1	Power negative supply
10	O	OUT1A	Output half-bridge 1A
11	PWR	GND_REG	Internal ground reference
12	PWR	VDD_REG	Internal 3.3-V reference voltage
13	-	N.C.	No internal connection
14	-	N.C.	No internal connection
15	-	N.C.	No internal connection
16	-	N.C.	No internal connection
17	-	N.C.	No internal connection
18	PWR	GND_DIG	Digital ground
19	-	N.C.	No internal connection
20	-	N.C.	No internal connection
21	-	N.C.	No internal connection
22	-	N.C.	No internal connection
23	PWR	VDD_DIG	Positive supply digital
24	PWR	GND_DIG	Digital ground
25	I	PWRDN	Power down: 0: power stage is switched off then the PLL is also switched off (this operation takes 13 million clock cycles) 1: normal operation
26	PWR	VDD_PLL	Positive supply for PLL
27	I	FILTER_PLL	Connection to PLL filter
28	PWR	GND_PLL	Negative supply for PLL
29	I	XTI	PLL input clock, $256 * f_S$, or $384 * f_S$
30	I	BICKI	I ² S serial clock
31	I	LRCKI	I ² S left/right clock

Table 2. Pin description (continued)

Number	Type	Name	Description
32	I	SDI	I ² S serial data channel
33	I	RESET	Reset: 0: reset state, power stage is switched off, all registers are set to default value 1: normal operation
34	O	INT_LINE	Fault interrupt
35	I/O	SDA	I ² C serial data
36	I	SCL	I ² C serial clock
37	PWR	GND_DIG	Digital ground
38	PWR	VDD_DIG	Digital supply
39	-	N.C.	No internal connection
40	PWR	GND_SUB	Substrate ground
41	I	SA	I ² C select address
42	I	TEST_MODE	This pin must be connected to ground
43	-	N.C.	No internal connection
44	-	N.C.	No internal connection
45	-	N.C.	No internal connection
46	-	N.C.	No internal connection
47	-	N.C.	No internal connection
48	-	N.C.	No internal connection
-	-	EP	Exposed pad for ground-plane heatsink, to be connected to GND

Note: To increase thermal dissipation, all N.C. (no internal connection) pins must be connected to GND.

3 Electrical specifications

3.1 Absolute maximum ratings

Table 3. Absolute maximum ratings

Symbol	Parameter	Min	Typ	Max	Unit
V _{CC}	Analog supply voltage (pins VCCx)	-	-	23	V
V _{DD}	Digital supply voltage (pins VDD_DIG)	-	-	4.0	V
I _L	Logic input interface	-0.3	-	4.0	V
T _{op}	Operating junction temperature	0	-	150	°C
T _{stg}	Storage temperature	-40	-	150	°C

Warning: Stresses beyond those listed in [Table 3: Absolute maximum ratings](#) may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in [Table 5: Recommended operating conditions](#) are not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability. In the real application, a power supply with nominal value rated within the limits of the recommended operating conditions, may rise beyond the maximum operating conditions for a short time when no or very low current is being sunk (amplifier in mute state). In this case the reliability of the device is guaranteed, provided that the absolute maximum ratings are not exceeded.

3.2 Thermal data

Table 4. Thermal data

Symbol	Parameter	Min	Typ	Max	Unit
R _{Th(j-case)}	Thermal resistance junction to case (thermal pad)	-	-	1.5	°C/W
T _{sd}	Thermal-shutdown junction temperature	140	150	160	°C
T _w	Thermal-warning temperature	-	130	-	°C
T _{hsd}	Thermal-shutdown hysteresis	18	20	22	°C

3.3 Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Min	Typ	Max	Unit
V_{CC}	Analog supply voltage (VCCx)	4.5	-	20.0	V
V_{DD}	Digital supply voltage (VDD_DIG)	2.7	3.3	3.6	V
I_L	Logic input interface	2.7	3.3	3.6	V
T_{amb}	Ambient temperature	0	-	70	°C

3.4 Electrical specifications - digital section

Table 6. Electrical characteristics for digital section

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{il}	Input current, no pull-up or pull-down resistor	$V_i = 0$ V	-	-	± 10	μ A
I_{ih}		$V_i = V_{DD} = 3.6$ V	-	-	± 10	μ A
V_{il}	Low-level input voltage	-	-	-	$0.2 * V_{DD}$	V
V_{ih}	High-level input voltage	-	$0.8 * V_{DD}$	-	-	V
V_{ol}	Low-level output voltage	$I_{ol} = 2$ mA	-	-	$0.4 * V_{DD}$	V
V_{oh}	High-level output voltage	$I_{oh} = 2$ mA	$0.8 * V_{DD}$	-	-	V
I_{pu}	Pull-up current	-	25	66	125	μ A
R_{pu}	Equivalent pull-up resistance	-	-	50	-	k Ω

3.5 Electrical specifications - power section

The specifications in [Table 7](#) below are given for the conditions $V_{CC} = 18$ V, $V_{DD} = 3.3$ V, $f_{SW} = 384$ kHz, $T_{amb} = 25$ °C and $R_L = 8$ Ω , unless otherwise specified.

Table 7. Electrical specifications for power section

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
P_o	Output power BTL	THD = 1%	-	16	-	W
		THD = 10%	-	20	-	
R_{dsON}	Power P-channel/N-channel MOSFET (total bridge)	$I_d = 1$ A	-	180	250	m Ω
I_{dss}	Power P-channel/N-channel leakage	$V_{CC} = 18$ V	-	-	10	μ A

Table 7. Electrical specifications for power section (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
gP	Power P-channel R_{dsON} matching	$I_d = 1\text{ A}$	95	-	-	%
gN	Power N-channel R_{dsON} matching	$I_d = 1\text{ A}$	95	-	-	%
I_{LDT}	Low-current dead time (static)	Resistive load, refer to Figure 5	-	5	10	ns
I_{HDT}	High-current dead time (dynamic)	Refer to Figure 6	-	10	20	ns
t_r	Rise time	Resistive load, refer to Figure 5	-	8	10	ns
t_f	Fall time	Resistive load, refer to Figure 5	-	8	10	ns
V_{CC}	Supply voltage	-	4.5	-	20	V
I_{VCC}	Supply current from V_{CC} in power down	PWRDN = 0	30	60	200	μA
	Supply current from V_{CC} in operation	PCM input signal = -60 dBfs Switching frequency = 384 kHz No LC filters	-	30	50	mA
I_{VDD_DIG}	Supply current for FFX processing (reference only)	Internal clock = 49.152 MHz	10	30	50	mA
	Supply current in standby	-	8	11	25	mA
I_{LIM}	Overcurrent limit	Non-linear output ⁽¹⁾	2.2	3.5	4.3	A
I_{SCP}	Short-circuit protection	High-impedance output ⁽²⁾	2.7	3.8	5.0	A
V_{OVP}	Overvoltage protection threshold			22.9		V
V_{UVP}	Undervoltage protection threshold	-	-	3.5	4.3	V
t_{min}	Output minimum pulse width	No load	20	30	60	ns
THD+N	Total harmonic distortion and noise	FFX stereo mode, $P_o = 1\text{ W}$, $f = 1\text{ kHz}$	-	0.05	0.2	%
DR	Dynamic range	-	-	100	-	dB
SNR	Signal-to-noise ratio in ternary mode	A-weighted	-	100	-	dB
	Signal-to-noise ratio in binary mode	A-weighted	-	90	-	
PSRR	Power supply rejection ratio	FFX stereo mode, < 5 kHz, $V_{RIPPLE} = 1\text{ V RMS}$ audio input = dither only	-	80	-	dB

Table 7. Electrical specifications for power section (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
X_{TALK}	Crosstalk	FFX stereo mode, < 5 kHz, One channel driven at 1 W the other channel measured	-	80	-	dB
η	Peak efficiency in FFX mode	$P_o = 2 \times 20 \text{ W}$ into 8Ω	-	90	-	%

1. The I_{LIM} data is for 1 channel of BTL configuration, thus, $2 * I_{LIM}$ drives the 2-channel BTL configuration. The current limit is active when $OCRB = 0$ (see [Table 23: Overcurrent warning detect adjustment bypass on page 29](#)). When $OCRB = 1$ then I_{SC} applies.
2. The I_{SCP} current limit data is for 1 channel of BTL configuration, thus, $2 * I_{SCP}$ drives the 2-channel BTL configuration. The short-circuit current is applicable when $OCRB = 1$ (see [Table 23: Overcurrent warning detect adjustment bypass on page 29](#)).

3.6 Power-on/off sequences

The power-on/off sequences shown in *Figure 3* and *Figure 4* below ensure a pop-free turn-on and turn-off.

Figure 3. Power-on sequence

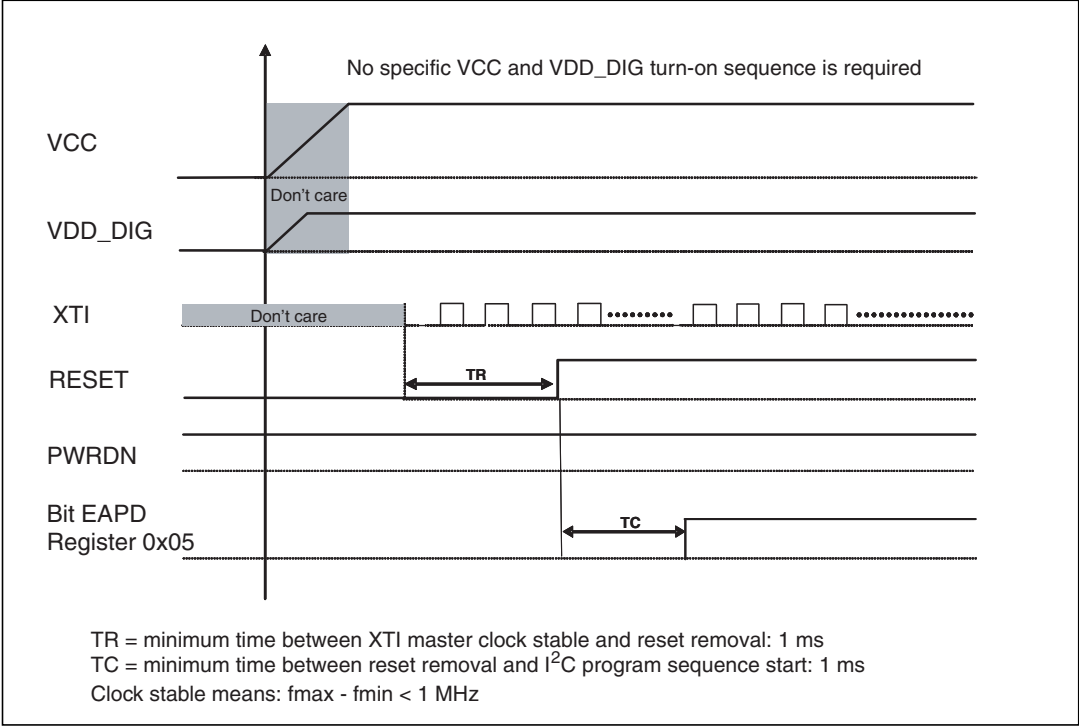
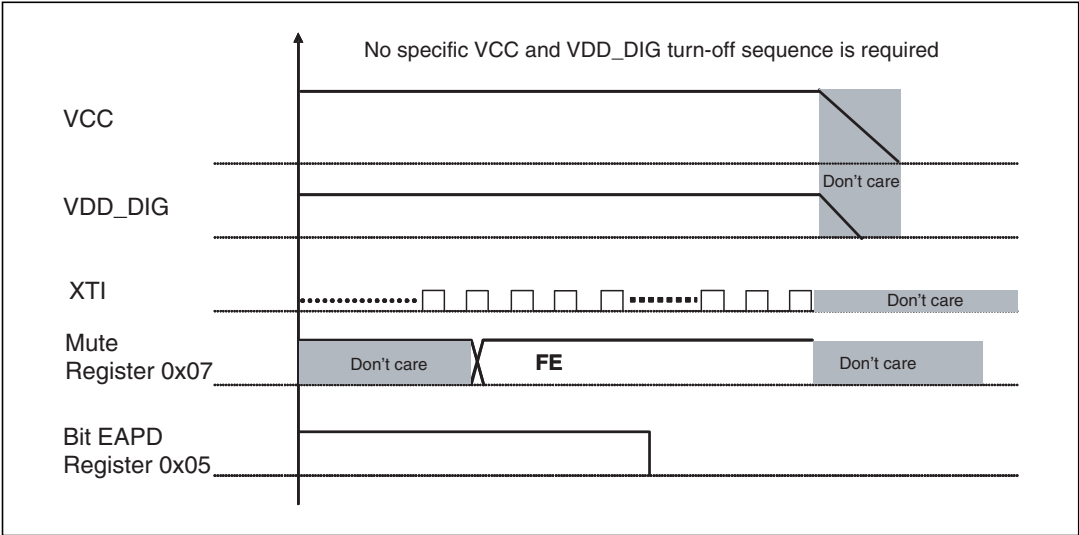


Figure 4. Power-off sequence



3.7 Testing

Figure 5. Test circuit

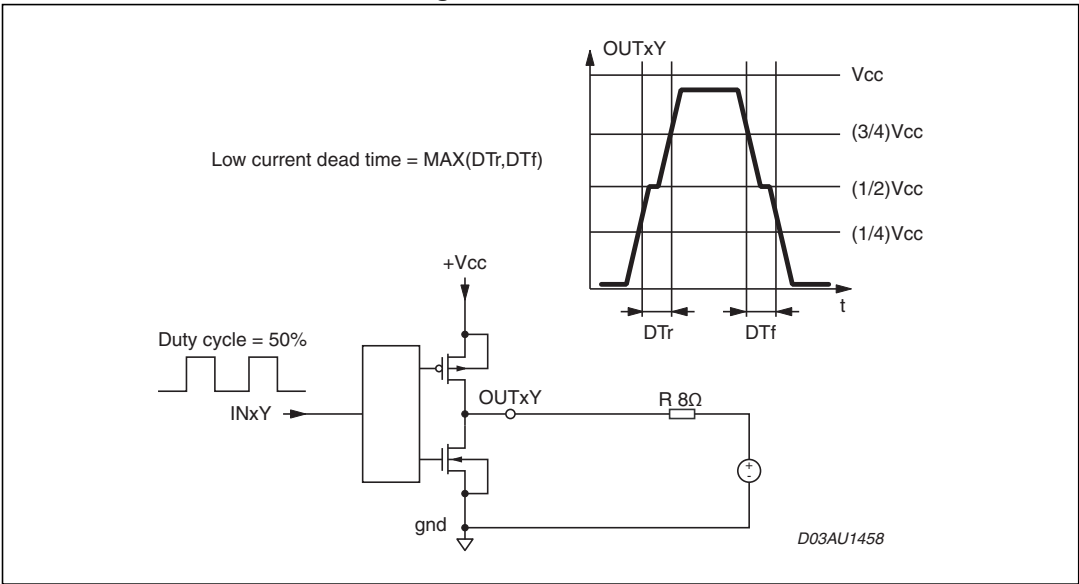
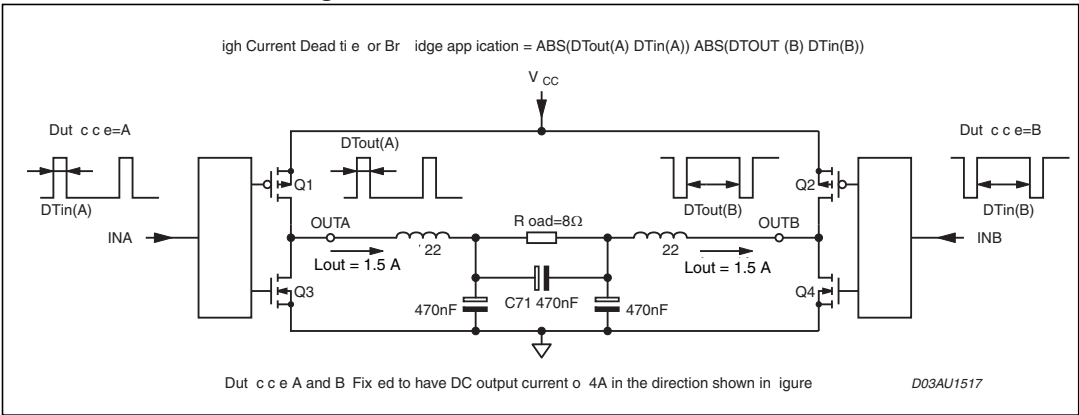


Figure 6. Current dead-time test circuit



4 Functional description

4.1 Functional pins

4.1.1 Power-down function

Pin PWRDN (23) is used to power down the STA380WS.

PWRDN = 0 (0 V): power-down state

PWRDN = 1 (V_{DD}): normal operation

During the power-down sequence the output begins to mute. After the mute condition is reached, the power stage is switched off and the output becomes high impedance. Then the master clock to all internal hardware blocks is gated off. The PLL is also switched off. The complete power-down sequence takes 13 million cycles.

4.1.2 Reset function

Pin RESET (31) is used to reset the STA380WS.

RESET = 0 (0 V): reset state

RESET = 1 (V_{DD}): normal operation

When pin RESET is forced to 0, the power stage is switched off (with high-impedance output) and the master clock to all internal hardware blocks is gated off.

Note: Reset has a higher priority than power-down.

4.2 Serial audio interface description

4.2.1 Serial audio interface protocols

The STA380WS serial audio input was designed to interface with standard digital audio components and to accept serial data formats. The STA380WS always acts as a slave when receiving audio input from standard digital audio components. Serial data for two channels is provided using 3 input pins: left/right clock LRCLKI (pin 29), serial clock BICKI (pin 28), and serial data SDI (pin 30).

The available formats are shown in [Table 7](#) and [Table 8](#), and set through [Configuration register B \(addr 0x01\) on page 25](#).

Figure 7. I²S

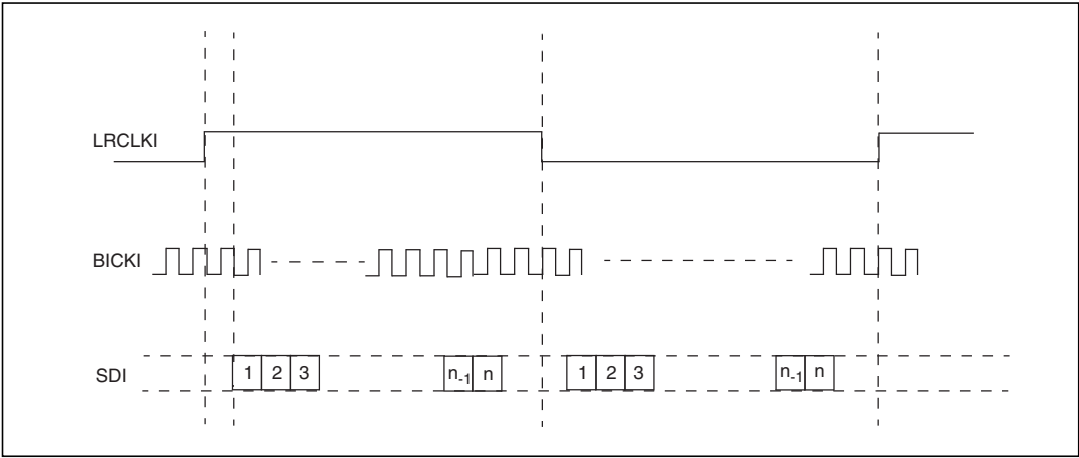
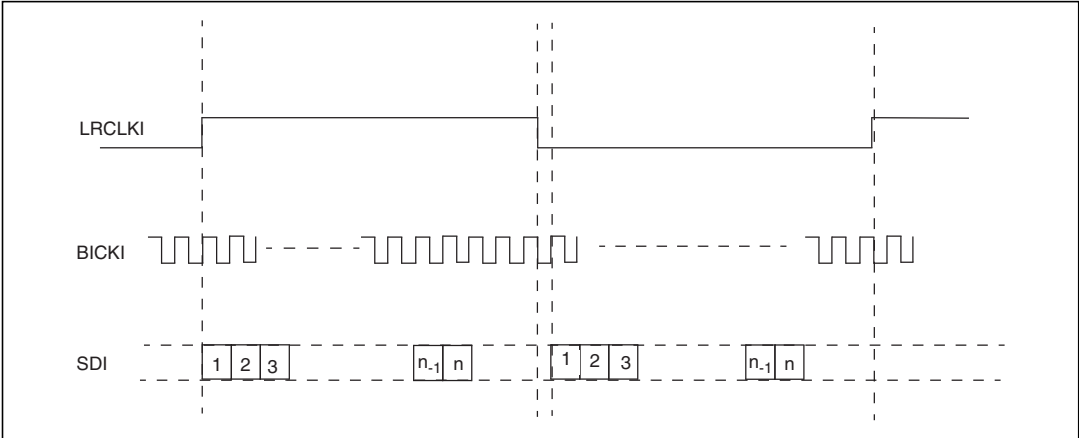


Figure 8. Left justified



5 I²C bus specification

The STA380WS supports the I²C protocol via the input ports SCL and SDA. This protocol defines any device that sends data to the bus as a transmitter and any device that reads the data as a receiver. The device that controls the data transfer is known as the master and the other as the slave. The master always starts the transfer and provides the serial clock for synchronization. The STA380WS is always a slave device in all of its communications. It supports up to 400 kb/s (fast-mode bit rate).

5.1 Communication protocol

5.1.1 Data transition or change

Data changes on the SDA line must only occur when the SCL clock is low. An SDA transition while the clock is high is used to identify a START or STOP condition.

5.1.2 Start condition

START is identified by a high to low transition of the data bus SDA signal while the clock signal SCL is stable in the high state. A START condition must precede any command for data transfer.

5.1.3 Stop condition

STOP is identified by low to high transition of the data bus SDA signal while the clock signal SCL is stable in the high state. A STOP condition terminates communication between the STA380WS and the bus master.

5.1.4 Data input

During the data input the STA380WS samples the SDA signal on the rising edge of clock SCL. For correct device operation the SDA signal must be stable during the rising edge of the clock and the data can change only when the SCL line is low.

5.2 Device addressing

To start communication between the master and the STA380WS, the master must initiate a start condition. Following this, the master sends to the SDA line 8 bits (MSB first) corresponding to the device-select address and read or write mode.

The 7 most significant bits are the device address identifiers, corresponding to the I²C bus definition. In the STA380WS the I²C interface has two device addresses depending on the SA port configuration, 0x38 when SA = 0, and 0x3A when SA = 1.

The 8th bit (LSB) identifies read or write operation RW, this bit is set to 1 for read mode and 0 for write mode. After a START condition the STA380WS identifies the device address on the SDA bus and if a match is found, acknowledges the identification during the 9th bit time. The byte following the device identification byte is the internal space address.

5.3 Write operation

Following the START condition the master sends a device select code with the RW bit set to 0. The STA380WS acknowledges this and then waits for the byte of internal address. After receiving the internal byte address the STA380WS again responds with an acknowledgement.

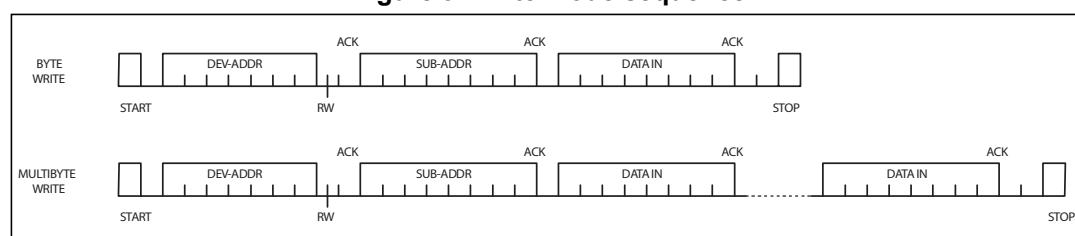
5.3.1 Byte write

In the byte write mode the master sends one data byte which is acknowledged by the STA380WS. The master then terminates the transfer by generating a STOP condition.

5.3.2 Multi-byte write

The multi-byte write modes can start from any internal address. The master generating a STOP condition terminates the transfer.

Figure 9. Write mode sequence



5.4 Read operation

5.4.1 Current address byte read

Following the START condition the master sends a device select code with the RW bit set to 1. The STA380WS acknowledges this and then responds by sending one byte of data. The master then terminates the transfer by generating a STOP condition.

5.4.2 Current address multi-byte read

The multi-byte read modes can start from any internal address. Sequential data bytes are read from sequential addresses within the STA380WS. The master acknowledges each data byte read and then generates a STOP condition terminating the transfer.

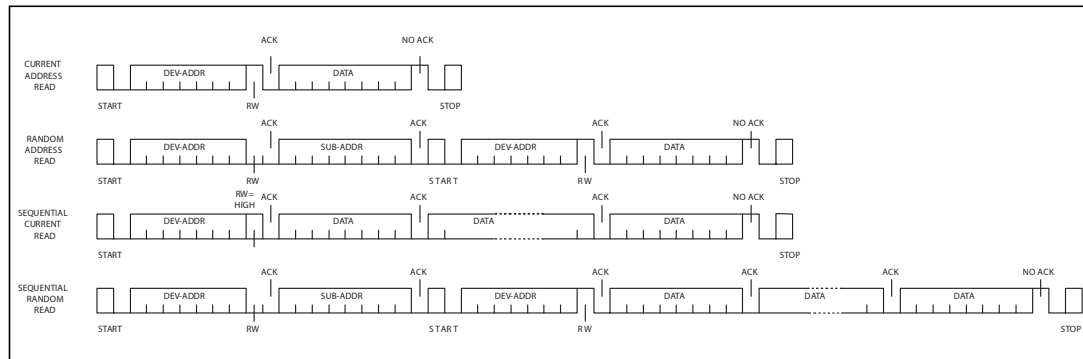
5.4.3 Random address byte read

Following the START condition the master sends a device select code with the RW bit set to 0. The STA380WS acknowledges this and then the master writes the internal address byte. After receiving the internal byte address, the STA380WS again responds with an acknowledgement. The master then initiates another START condition and sends the device select code with the RW bit set to 1. The STA380WS acknowledges this and then responds by sending one byte of data. The master then terminates the transfer by generating a STOP condition.

5.4.4 Random address multi-byte read

The multi-byte read modes could start from any internal address. Sequential data bytes are read from sequential addresses within the STA380WS. The master acknowledges each data byte read and then generates a STOP condition to terminate the transfer.

Figure 10. Read mode sequence



6 Register description

Table 8. Register summary

Addr	Name	D7	D6	D5	D4	D3	D2	D1	D0
0x00	CONFA	FDRB	TWAB	TWRB	IR1	IR0	MCS2	MCS1	MCS0
0x01	CONFB	C2IM	C1IM	Reserved	SAIFB	SAI3	SAI2	SAI1	SAI0
0x02	CONFC	OCRB	Reserved	CSZ3	CSZ2	CSZ1	CSZ0	OM1	OM0
0x03	CONFD	Reserved	ZDE	Reserved					
0x04	CONFE	SVE	ZCE	DCCV	PWMS	AME	NSBW	MPC	MPCV
0x05	CONFF	EAPD	PWDN	ECLE	LDTE	BCLE	IDE	Reserved	
0x06	MUTE	Reserved					C2M	C1M	MMUTE
0x07	MVOL	MV7	MV6	MV5	MV4	MV3	MV2	MV1	MV0
0x08	C1VOL	C1V7	C1V6	C1V5	C1V4	C1V3	C1V2	C1V1	C1V0
0x09	C2VOL	C2V7	C2V6	C2V5	C2V4	C2V3	C2V2	C2V1	C2V0
0x0C	AUTO	Reserved				AMAM2	AMAM1	AMAM0	AMAME
0x0E	C1CFG	Reserved					C1VBP	Reserved	
0x0F	C2CFG	Reserved					C2VBP	Reserved	
0x27	MPCC1	MPCC15	MPCC14	MPCC13	MPCC12	MPCC11	MPCC10	MPCC9	MPCC8
0x28	MPCC2	MPCC7	MPCC6	MPCC5	MPCC4	MPCC3	MPCC2	MPCC1	MPCC0
0x29	DCC1	DCC15	DCC14	DCC13	DCC12	DCC11	DCC10	DCC9	DCC8
0x2A	DCC2	DCC7	DCC6	DCC5	DCC4	DCC3	DCC2	DCC1	DCC0
0x2B	FDRC1	FDRC15	FDRC14	FDRC13	FDRC12	FDRC11	FDRC10	FDRC9	FDRC8
0x2C	FDRC2	FDRC7	FDRC6	FDRC5	FDRC4	FDRC3	FDRC2	FDRC1	FDRC0
0x2D	STATUS	PLLUL	FAULT	UVFAULT	Reserved	OCFAULT	OCWARN	TFAULT	TWARN
0x2E	BIST1	Reserved		RO1BACT	R5BACT	R4BACT	R3BACT	R2BACT	R1BACT
0x2F	BIST2	Reserved		RO1BEND	R5BEND	R4BEND	R3BEND	R2BEND	R1BEND
0x30	BIST3	Reserved			R5BBAD	R4BBAD	R3BBAD	R1BBAD	R1BBAD
0x31	TSTCTL	Reserved							
0x32	C1PS	C1PS7	C1PS6	C1PS5	C1PS4	C1PS3	C1PS2	C1PS1	C1PS0
0x33	C2PS	C2PS7	C2PS6	C2PS5	C2PS4	C2PS3	C2PS2	C2PS1	C2PS0
0x34	OLIM	OLIM7	OLIM6	OLIM5	OLIM4	OLIM3	OLIM2	OLIM1	OLIM0

6.1 Configuration registers (addr 0x00 to 0x05)

6.1.1 Configuration register A (addr 0x00)

D7	D6	D5	D4	D3	D2	D1	D0
FDRB	TWAB	TWRB	IR1	IR0	MCS2	MCS1	MCS0
0	1	1	0	0	0	1	1

Master clock select

Table 9. Master clock select

Bit	R/W	RST	Name	Description
0	R/W	1	MCS0	Master clock select: Selects the ratio between the input I ² S sample frequency and the input clock.
1	R/W	1	MCS1	
2	R/W	0	MCS2	

The STA380WS supports sample rates of 32 kHz, 44.1 kHz, 48 kHz, 88.2 kHz, 96 kHz, 176.4 kHz, and 192 kHz. Therefore the internal clock is:

- 32.768 MHz for 32 kHz
- 45.1584 MHz for 44.1 kHz, 88.2 kHz, and 176.4 kHz
- 49.152 MHz for 48 kHz, 96 kHz, and 192 kHz

The external clock frequency provided to the XTI pin must be a multiple of the input sample frequency (f_S).

The relationship between the input clock and the input sample rate is determined by both the MCSx and the IR (input rate) register bits. The MCSx bits determine the PLL factor generating the internal clock and the IR bit determines the oversampling ratio used internally.

Table 10. MCS bits

Input sample rate f_S (kHz)	IR	MCS[2:0]					
		101	100	011	010	001	000
32, 44.1, 48	00	$576 * f_S$	$128 * f_S$	$256 * f_S$	$384 * f_S$	$512 * f_S$	$768 * f_S$
88.2, 96	01	NA	$64 * f_S$	$128 * f_S$	$192 * f_S$	$256 * f_S$	$384 * f_S$
176.4, 192	1X	NA	$32 * f_S$	$64 * f_S$	$96 * f_S$	$128 * f_S$	$192 * f_S$

Interpolation ratio select

Table 11. Interpolation ratio select

Bit	R/W	RST	Name	Description
4:3	R/W	00	IR [1:0]	Interpolation ratio select: Selects internal interpolation ratio based on input I ² S sample frequency.

The STA380WS has variable interpolation (oversampling) settings such that internal processing and FFX output rates remain consistent. The first processing block interpolates by either 2 times or 1 time (pass-through) or provides a 2-times downsample. The oversampling ratio of this interpolation is determined by the IR bits.

Table 12. IR bit settings as a function of input sample rate

Input sample rate f_s (kHz)	IR	1 st stage interpolation ratio
32	00	2-times oversampling
44.1	00	2-times oversampling
48	00	2-times oversampling
88.2	01	Pass-through
96	01	Pass-through
176.2	10	2-times downsampling
192	10	2-times downsampling

Thermal warning recovery bypass

Table 13. Thermal warning recovery

Bit	R/W	RST	Name	Description
5	R/W	1	TWRB	Thermal warning recovery bypass: 0: thermal warning recovery enabled 1: thermal warning recovery disabled

If the thermal warning adjustment is enabled (TWAB = 0), then the thermal warning recovery determines if the -3 dB output limit is removed when the thermal warning is negative.

If TWRB = 0 and TWAB = 0, then when a thermal warning disappears, the -3 dB output limit is removed and the gain is added back to the system. If TWRB = 1 and TWAB = 0, then when a thermal warning disappears, the -3 dB output limit remains until TWRB is changed to zero or the device is reset.

Thermal warning adjustment bypass

Table 14. Thermal warning adjustment

Bit	R/W	RST	Name	Description
6	R/W	1	TWAB	Thermal warning adjustment bypass: 0: thermal warning adjustment enabled 1: thermal warning adjustment disabled

The on-chip STA380WS power output block provides feedback to the digital controller using inputs to the power control block. The TWARN input is used to indicate a thermal warning condition. When TWARN is asserted (set to 0) for a period of time greater than 400 ms, the power control block will force a -3 dB output limit (determined by TWOCL in coefficient RAM) to the modulation limit in an attempt to eliminate the thermal warning condition. Once the thermal warning output limit adjustment is applied, it remains in this state until reset, unless FDRB = 0.

Fault detect recovery bypass

Table 15. Fault detect recovery

Bit	R/W	RST	Name	Description
7	R/W	0	FDRB	Fault detect recovery bypass: 0: fault detect recovery enabled 1: fault detect recovery disabled

The on-chip STA380WS power output block provides feedback to the digital controller using inputs to the power control block. The FAULT input is used to indicate a fault condition (either overcurrent or thermal). When FAULT is asserted (set to 0), the power control block attempts a recovery from the fault by asserting the 3-state output (setting it to 0 which directs the power output block to begin recovery), holding it at 0 for period of time in the range of 0.1 ms to 1 second as defined by the fault detect recovery constant register (FDRC registers 0x2B, 0x2C), then toggling it back to 1. This sequence is repeated as long as the fault indication exists. This feature is enabled by default but can be bypassed by setting the FDRB control bit to 1.

6.1.2 Configuration register B (addr 0x01)

D7	D6	D5	D4	D3	D2	D1	D0
C2IM	C1IM	Reserved	SAIFB	SAI3	SAI2	SAI1	SAI0
1	0	0	0	0	0	0	0

Serial audio input interface format

Table 16. Serial audio input interface format

Bit	R/W	RST	Name	Description
0	R/W	0	SAI0	Determines the interface format of the input serial digital audio interface.
1	R/W	0	SAI1	
2	R/W	0	SAI2	
3	R/W	0	SAI3	

Serial data interface

The STA380WS audio serial input interfaces with standard digital audio components and accepts a number of serial data formats. STA380WS always acts a slave when receiving audio input from standard digital audio components. Serial data for two channels is provided using three inputs: left/right clock LRCKI, serial clock BICKI, and serial data SDI.

Bits SAI and bit SAIFB are used to specify the serial data format. The default serial data format is I²S, MSB first. Available formats are shown in the tables and figure that follow.

Serial data first bit

Table 17. Serial data first bit

SAIFB	Format
0	MSB-first
1	LSB-first

Table 18. Support serial audio input formats for MSB first (SAIFB = 0)

BICKI	SAI [3:0]	SAIFB	Interface format
32 * f _S	0000	0	I ² S 15-bit data
	0001	0	Left/right justified 16-bit data
48* f _S	0000	0	I ² S 16- to 23-bit data
	0001	0	Left-justified 16- to 24-bit data
	0010	0	Right-justified 24-bit data
	0110	0	Right-justified 20-bit data
	1010	0	Right-justified 18-bit data
	1110	0	Right-justified 16-bit data
64* f _S	0000	0	I ² S 16- to 24-bit data
	0001	0	Left-justified 16- to 24-bit data
	0010	0	Right-justified 24-bit data
	0110	0	Right-justified 20-bit data
	1010	0	Right-justified 18-bit data
	1110	0	Right-justified 16-bit data

Table 19. Supported serial audio input formats for LSB-first (SAIFB = 1)

BICKI	SAI[3:0]	SAIFB	Interface format
32* f _S	1100	1	I ² S 15-bit data
	1110	1	Left/right justified 16-bit data
48* f _S	0100	1	I ² S 23-bit data
	0100	1	I ² S 20-bit data
	1000	1	I ² S 18-bit data
	1100	1	LSB-first I ² S 16-bit data
	0001	1	Left-justified 24-bit data
	0101	1	Left-justified 20-bit data
	1001	1	Left-justified 18-bit data
	1101	1	Left-justified 16-bit data
	0010	1	Right-justified 24-bit data
48* f _S	0110	1	Right-justified 20-bit data
	1010	1	Right-justified 18-bit data
	1110	1	Right-justified 16-bit data
64* f _S	0000	1	I ² S 24-bit data
	0100	1	I ² S 20-bit data
	1000	1	I ² S 18-bit data
	1100	1	LSB-first I ² S 16-bit data
	0001	1	Left-justified 24-bit data
	0101	1	Left-justified 20-bit data
	1001	1	Left-justified 18-bit data
	1101	1	Left-justified 16-bit data
	0010	1	Right-justified 24-bit data
	0110	1	Right-justified 20-bit data
	1010	1	Right-justified 18-bit data
	1110	1	Right-justified 16-bit data

Channel input mapping

Table 20. Channel input mapping

Bit	R/W	RST	Name	Description
6	R/W	0	C1IM	0: processing channel 1 receives left I ² S input 1: processing channel 1 receives right I ² S input
7	R/W	0	C2IM	0: processing channel 2 receives left I ² S input 1: processing channel 2 receives right I ² S input

Each channel received via I²S can be mapped to any internal processing channel via the channel input mapping registers. This allows for flexibility in processing. The default settings of these registers map each I²S input channel to its corresponding processing channel.

6.1.3 Configuration register C (addr 0x02)

D7	D6	D5	D4	D3	D2	D1	D0
OCRB	Reserved	CSZ3	CSZ2	CSZ1	CSZ0	OM1	OM0
1	0	0	1	0	1	1	1

FFX power output mode

Table 21. FFX power output mode

Bit	R/W	RST	Name	Description
0	R/W	1	OM0	The FFX power output mode selects the configuration of the FFX output: 00: drop compensation 01: discrete output stage: tapered compensation 10: full-power mode 11: variable drop compensation (CSZx bits)
1	R/W	1	OM1	

FFX compensation pulse size register

Table 22. FFX compensating pulse size

Bit	R/W	RST	Name	Description
2	R/W	1	CSZ0	When OM[1:0] = 11, this register determines the size of the FFX compensating pulse from 0 to 15 clock periods: 0000: 0 ns (0 ticks) compensating pulse size 0001: 20 ns (1 tick) clock period compensating pulse size 1111: 300 ns (15 ticks) clock period compensating pulse size
3	R/W	0	CSZ1	
4	R/W	1	CSZ2	
5	R/W	0	CSZ3	

Overcurrent warning detect adjustment bypass

Table 23. Overcurrent warning detect adjustment bypass

Bit	R/W	RST	Name	Description
7	R/W	1	OCRB	0: overcurrent warning adjustment enabled 1: overcurrent warning adjustment disabled

The status bit OCWARN warns that an overcurrent condition is present. When OCWARN is asserted (set to 0), the power control block forces an adjustment to the modulation limit (default -3 dB) in an attempt to eliminate the overcurrent warning condition. Once the overcurrent warning volume adjustment is applied, it remains applied until the device is reset. The overcurrent limit can be changed via register OLIM (*Output limit register (addr 0x34) on page 39*).

6.1.4 Configuration register D (addr 0x03)

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	ZDE	Reserved					
0	1	0	0	0	0	0	0

Zero-detect mute enable

Table 24. Zero detect mute enable

Bit	R/W	RST	Name	Description
6	R/W	1	ZDE	1: enable the automatic zero-detect mute

Setting the ZDE bit enables the zero-detect automatic mute. The zero-detect circuit looks at the data for each processing channel at the output of the crossover (bass management) filter. If any channel receives 2048 consecutive zero value samples (regardless of f_s), then that individual channel is muted if this function is enabled.

6.1.5 Configuration register E (addr 0x04)

D7	D6	D5	D4	D3	D2	D1	D0
SVE	ZCE	DCCV	PWMS	AME	NSBW	MPC	MPCV
1	1	0	0	0	0	1	0

Max power correction variable

Table 25. Max power correction variable

Bit	R/W	RST	Name	Description
0	R/W	0	MPCV	0: use standard MPC coefficient 1: use MPCC bits for MPC coefficient

Max power correction**Table 26. Max power correction**

Bit	R/W	RST	Name	Description
1	R/W	1	MPC	1: enable power bridge correction for THD reduction near maximum power output.

Setting the MPC bit turns on special processing that corrects the STA380WS power device at high power. This mode lowers the THD+N of a full FFX system at maximum power output and slightly below. If enabled, MPC is operational in all output modes except tapered (OM[1:0] = 01) and binary. When OCFG = 00, MPC does not affect channels 3 and 4, the line-out channels.

Noise-shaper bandwidth selection**Table 27. Noise-shaper bandwidth selection**

Bit	R/W	RST	Name	Description
2	R/W	0	NSBW	1: 3 rd order NS 0: 4 th order NS

AM mode enable**Table 28. AM mode enable**

Bit	R/W	RST	Name	Description
3	R/W	0	AME	0: normal FFX operation 1: AM reduction mode FFX operation

The STA380WS features an FFX processing mode that minimizes the amount of noise generated in the frequency range of AM radio. This mode is intended for use when FFX is operating in a device with an active AM tuner. The SNR of the FFX processing is reduced to approximately 83 dB in this mode, which is still greater than the SNR of AM radio.

PWM speed mode**Table 29. PWM speed mode**

Bit	R/W	RST	Name	Description
4	R/W	0	PWMS	0: normal speed (384 kHz) all channels 1: odd speed (341.3 kHz) all channels

Distortion compensation variable enable**Table 30. Distortion compensation variable enable**

Bit	R/W	RST	Name	Description
5	R/W	0	DCCV	0: uses preset DC coefficient 1: uses DCC coefficient

Zero-crossing volume enable**Table 31. Zero-crossing volume enable**

Bit	R/W	RST	Name	Description
6	R/W	1	ZCE	1: volume adjustments will only occur at digital zero-crossings 0: volume adjustments will occur immediately

The ZCE bit enables zero-crossing volume adjustments. When volume is adjusted on digital zero-crossings, no clicks will be audible.

Soft volume update enable**Table 32. Soft volume update enable**

Bit	R/W	RST	Name	Description
7	R/W	1	SVE	1: volume adjustments ramp according to SVR settings 0: volume adjustments will occur immediately

6.1.6 Configuration register F (addr 0x05)

D7	D6	D5	D4	D3	D2	D1	D0
EAPD	PWDN	ECLE	LDTE	BCLE	IDE	Reserved	
0	1	0	1	1	1	0	0

Invalid input detect mute enable**Table 33. Invalid input detect mute enable**

Bit	R/W	RST	Name	Description
2	R/W	1	IDE	1: enables the automatic invalid input detect mute

Setting the IDE bit enables this function, which looks at the input I²S data and will automatically mute if the signals are perceived as invalid.

Binary output mode clock loss detection**Table 34. Binary output mode clock loss detection**

Bit	R/W	RST	Name	Description
3	R/W	1	BCLE	Binary output mode clock loss detection enable

Detects loss of input MCLK in binary mode and outputs 50% of the duty cycle.

LRCK double trigger protection**Table 35. LRCK double trigger protection**

Bit	R/W	RST	Name	Description
4	R/W	1	LDTE	LRCLK double trigger protection enable

Actively prevents double triggering of LRCLK.

Auto EAPD on clock loss**Table 36. Auto EAPD on clock loss**

Bit	R/W	RST	Name	Description
5	R/W	0	ECLE	Auto EAPD on clock loss

When active, will issue a power stage device power-down signal (EAPD) on clock loss detection.

IC power-down**Table 37. Power-down**

Bit	R/W	RST	Name	Description
6	R/W	1	PWDN	0: power-down, low-power condition 1: normal operation

The PWDN register is used to put the IC in a low-power state. When PWDN is 0, the output begins a soft-mute. After the mute condition is reached, EAPD is asserted to power down the power stage, then the master clock to all internal hardware except the I²C block is gated. This puts the IC in a very low power consumption state.

External amplifier power-down**Table 38. External amplifier power-down**

Bit	R/W	RST	Name	Description
7	R/W	1	EAPD	0: external power stage power-down active 1: normal operation

The EAPD register directly disables/enables the internal power circuitry.

When EAPD = 0, the internal power section is placed in a low-power state (disabled).

6.2 Volume control registers (addr 0x06 to 0x09)

6.2.1 Mute/line output configuration register (addr 0x06)

D7	D6	D5	D4	D3	D2	D1	D0
Reserved					C2M	C1M	MMUTE
0	0	0	0	0	0	0	0

Master mute

Table 39. Master mute

Bit	R/W	RST	Name	Description
0	R/W	0	MMUTE	0: normal operation 1: all channels are in mute condition

Channel mute

Table 40. Channel mute

Bit	R/W	RST	Name	Description
1	R/W	0	C1M	Channel 1 mute: 0: not muted, it is possible to set the channel volume 1: hardware muted
2	R/W	0	C2M	Channel 2 mute: 0: not muted, it is possible to set the channel volume 1: hardware muted

6.2.2 Master volume register (addr 0x07)

D7	D6	D5	D4	D3	D2	D1	D0
MV7	MV6	MV5	MV4	MV3	MV2	MV1	MV0
1	1	1	1	1	1	1	1

6.2.3 Channel volume (addr 0x08, 0x09)

D7	D6	D5	D4	D3	D2	D1	D0
C1V7	C1V6	C1V5	C1V4	C1V3	C1V2	C1V1	C1V0
0	1	1	0	0	0	0	0

D7	D6	D5	D4	D3	D2	D1	D0
C2V7	C2V6	C2V5	C2V4	C2V3	C2V2	C2V1	C2V0
0	1	1	0	0	0	0	0

Volume setting

The volume structure of the STA380WS consists of individual volume registers for each channel and a master volume register that provides an offset to each channel's volume setting. The individual channel volumes are adjustable in 0.5-dB steps from +48 dB to -80 dB. As an example, if C2V = 0x00 or +48 dB and MV = 0x18 or -12 dB, then the total gain for channel 2 = +36 dB.

The master mute, when set to 1, will mute all channels at once, whereas the individual channel mutes (CxM) mute only that channel. Both the master mute and the channel mutes provide a "soft mute" with the volume ramping down to mute in 4096 samples from the maximum volume setting at the internal processing rate (about 96 kHz). A hard mute can be obtained by commanding a value of all 1's (255) to any channel volume register or the master volume register. When volume offsets are provided via the master volume register, any channel that whose total volume is less than -80 dB is muted.

All changes in volume take place at zero-crossings when ZCE = 1 (configuration register F) on a per-channel basis as this creates the smoothest possible volume transitions. When ZCE = 0, volume updates will occur immediately.

Table 41. Master volume offset as a function of MV

MV[7:0]	Volume offset from channel value
00000000 (0x00)	0 dB
00000001 (0x01)	-0.5 dB
00000010 (0x02)	-1 dB
...	...
01001100 (0x4C)	-38 dB
...	...
11111110 (0xFE)	-127.5 dB
11111111 (0xFF)	Hard master mute

Table 42. Channel volume as a function of CxV

CxV[7:0]	Volume
00000000 (0x00)	+48 dB
00000001 (0x01)	+47.5 dB
00000010 (0x02)	+47 dB
...	...
01011111 (0x5F)	+0.5 dB
01100000 (0x60)	0 dB
01100001 (0x61)	-0.5 dB
...	...
11010111 (0xD7)	-59.5 dB
11011000 (0xD8)	-60 dB
11011001 (0xD9)	-61 dB
11011010 (0xDA)	-62 dB
...	...
11101100 (0xEC)	-80 dB
11101101 (0xED)	Hard channel mute
...	...
11111111 (0xFF)	Hard channel mute

6.3 Automode register (0x0C)

D7	D6	D5	D4	D3	D2	D1	D0
Reserved				AMAM2	AMAM1	AMAM0	AMAME
0	0	0	0	0	0	0	0

AM interference frequency switching

Table 43. AM interference frequency switching

Bit	R/W	RST	Name	Description
0	R/W	0	AMAME	0: switching frequency determined by PWMS setting 1: switching frequency determined by AMAM setting

AMAM bits

Table 44. Automode AM switching frequency selection

AMAM[2:0]	48 kHz / 96 kHz input f_s	44.1 kHz / 88.2 kHz input f_s
000	0.535 MHz - 0.720 MHz	0.535 MHz - 0.670 MHz
001	0.721 MHz - 0.900 MHz	0.671 MHz - 0.800 MHz
010	0.901 MHz - 1.100 MHz	0.801 MHz - 1.000 MHz
011	1.101 MHz - 1.300 MHz	1.001 MHz - 1.180 MHz
100	1.301 MHz - 1.480 MHz	1.181 MHz - 1.340 MHz
101	1.481 MHz - 1.600 MHz	1.341 MHz - 1.500 MHz
110	1.601 MHz - 1.700 MHz	1.501 MHz - 1.700 MHz

6.4 Channel configuration registers (addr 0x0E, 0x0F)

D7	D6	D5	D4	D3	D2	D1	D0
Reserved					C1VBP	Reserved	
0	0	0	0	0	0	0	0

D7	D6	D5	D4	D3	D2	D1	D0
Reserved					C2VBP	Reserved	
0	0	0	0	0	0	0	0

Volume bypass

Each channel contains an individual channel volume bypass. If a particular channel has volume bypassed via the CxVBP = 1 register, then only the channel volume setting for that particular channel affects the volume setting. The master volume setting will not affect that channel.

6.5 Variable max power correction registers (addr 0x27, 0x28)

The MPCC bits determine the 16 MSBs of the MPC compensation coefficient. This coefficient is used in place of the default coefficient when MPCV = 1.

D7	D6	D5	D4	D3	D2	D1	D0
MPCC15	MPCC14	MPCC13	MPCC12	MPCC11	MPCC10	MPCC9	MPCC8
0	0	0	1	1	0	1	0

D7	D6	D5	D4	D3	D2	D1	D0
MPCC7	MPCC6	MPCC5	MPCC4	MPCC3	MPCC2	MPCC1	MPCC0
1	1	0	0	0	0	0	0

6.6 Variable distortion compensation registers (addr 0x29, 0x2A)

D7	D6	D5	D4	D3	D2	D1	D0
DCC15	DCC14	DCC13	DCC12	DCC11	DCC10	DCC9	DCC8
1	1	1	1	0	0	1	1

D7	D6	D5	D4	D3	D2	D1	D0
DCC7	DCC6	DCC5	DCC4	DCC3	DCC2	DCC1	DCC0
0	0	1	1	0	0	1	1

The DCC bits determine the 16 MSBs of the distortion compensation coefficient. This coefficient is used in place of the default coefficient when DCCV = 1.

6.7 Fault detect recovery constant registers (addr 0x2B, 0x2C)

D7	D6	D5	D4	D3	D2	D1	D0
FDRC15	FDRC14	FDRC13	FDRC12	FDRC11	FDRC10	FDRC9	FDRC8
0	0	0	0	0	0	0	0

D7	D6	D5	D4	D3	D2	D1	D0
FDRC7	FDRC6	FDRC5	FDRC4	FDRC3	FDRC2	FDRC1	FDRC0
0	0	0	0	1	1	0	0

The FDRC bits specify the 16-bit fault detect recovery time delay. When status register bit FAULT is asserted, the tristate output is immediately asserted low and held low for the time period specified by this constant. A value of 0x0001 in this register is approximately 0.083 ms. The default value of 0x000C gives approximately 0.1 ms.

Note: 0x0000 is a reserved value for this register pair. This value must not be used.

6.8 Device status register (addr 0x2D)

D7	D6	D5	D4	D3	D2	D1	D0
PLLUL	FAULT	UVFAULT	Reserved	OCFAULT	OCWARN	TFAULT	TWARN

This read-only register provides the fault, warning and PLL status from the power control block.

Table 45. Status bits description

Bit	R/W	RST	Name	Description
0	RO	-	TWARN	Thermal warning: 0: junction temperature is close to the fault condition 1: normal operation
1	RO	-	TFAULT	Thermal fault: 0: junction temperature limit detection 1: normal operation
2	RO	-	OCWARN	Overcurrent warning: 0: warning 1: normal operation
3	RO	-	OCFAULT	Overcurrent fault: 0: fault detected 1: normal operation
4	-	-	-	Reserved
5	RO	-	UVFAULT	Undervoltage warning: 0: VCCx below lower voltage threshold 1: normal operation
6	RO	-	FAULT	Power bridge fault: 0: fault detected 1: normal operation
7	RO	-	PLLUL	PLL lock: 0: locked 1: not locked

6.9 Reserved registers (addr 0x2E, 0x2F, 0x30, 0x31)

These registers are not to be used.

6.10 Postscale registers (addr 0x32, 0x33)

D7	D6	D5	D4	D3	D2	D1	D0
C1PS7	C1PS6	C1PS5	C1PS4	C1PS3	C1PS2	C1PS1	C1PS0
0	1	1	1	1	1	1	1

D7	D6	D5	D4	D3	D2	D1	D0
C2PS7	C2PS6	C2PS5	C2PS4	C2PS3	C2PS2	C2PS1	C2PS0
0	1	1	1	1	1	1	1

Postscale

The STA380WS provides one additional multiplication after the last interpolation stage and the distortion compensation on each channel, which can be used to limit the maximum modulation index and therefore the peak current through the power device. The register values represent an 8-bit signed fractional number. This number is extended to a 24-bit number, by adding zeros to the right, and then directly multiplied by the data on that

channel. An independent postscale is provided for each channel but all channels can use channel 1 postscale factor by setting the postscale link bit. By default, all postscale factors are set to 0x7F (pass-through).

6.11 Output limit register (addr 0x34)

6.11.1 Thermal and overcurrent warning output limit register

D7	D6	D5	D4	D3	D2	D1	D0
OLIM7	OLIM6	OLIM5	OLIM4	OLIM3	OLIM2	OLIM1	OLIM0
0	1	0	1	1	0	1	0

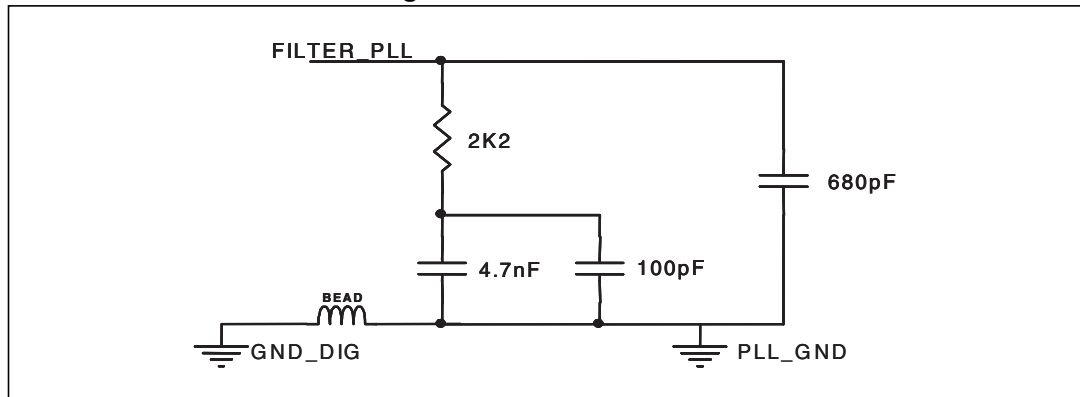
The STA380WS provides a simple mechanism for reacting to a thermal or overcurrent warning in the power device. When the TWARN or OCWARN status bit is asserted, the output is limited to the OLIM setting. The limit can be adjusted by modifying the thermal warning/overcurrent output limit value. As for the normal postscale, the register value represents an 8-bit signed fractional number. This number is extended to a 24-bit number, by adding zeros to the right, and then directly multiplied by the data on both channels. The scaling value range is from 0x80 = -1 to 0x7F = 0.992. To avoid phase changes in the output signal, only the positive range is used (0x00 to 0x7F). The default setting of 0x5A provides a -3-dB limit.

If the cause of the limiting is a thermal warning, the output limiting is removed when the thermal warning situation disappears. If the cause of the limiting is an overcurrent warning, output limiting remains in effect until the device is reset.

Table 46. Output limit values for thermal and overcurrent warnings

OLIM [7:0]	Attenuation (dB)
0x7F	0.06
0x7E	0.13
....
0x5A	3.0
....
0x40	6.0
....
0x28	10
....
0x01	42
0x00	Inf

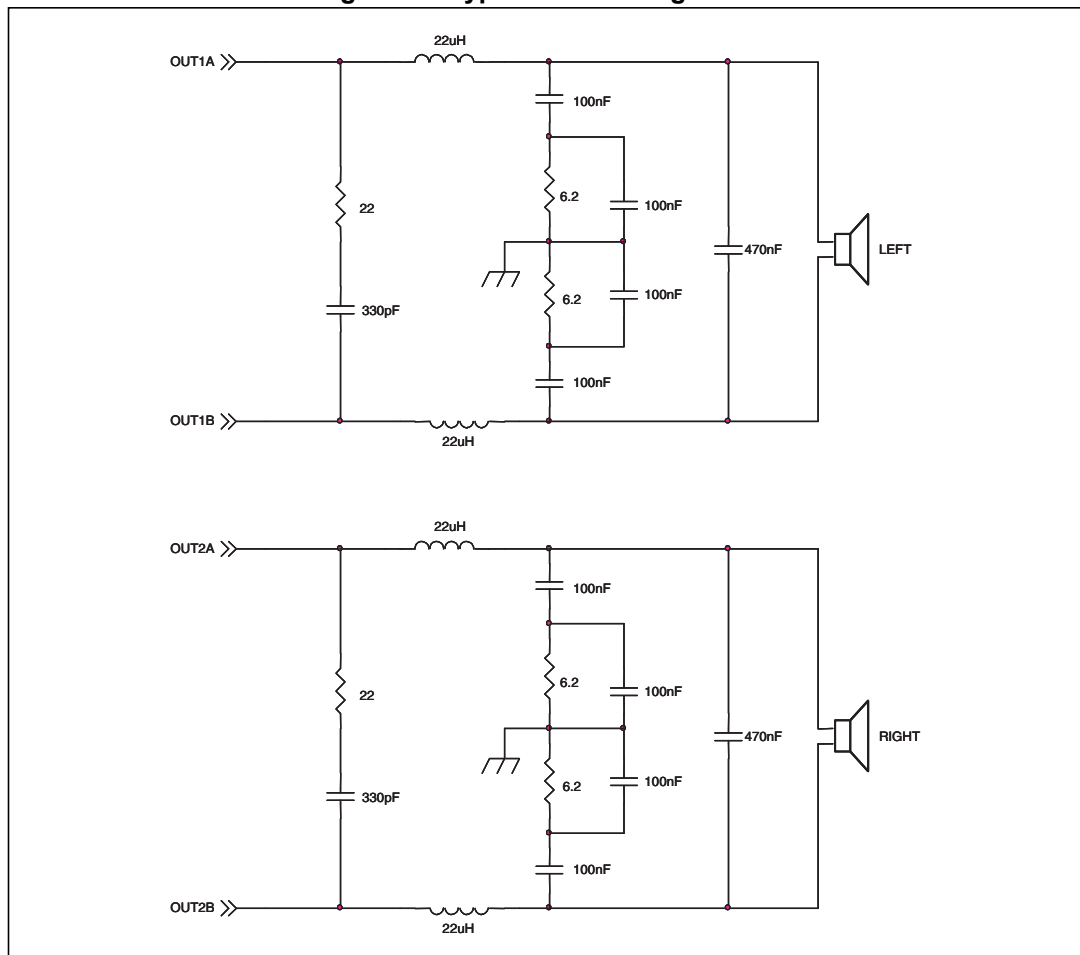
Figure 12. PLL filter circuit



7.3 Typical output configuration

Figure 13 below shows a typical output configuration used for BTL stereo mode.

Figure 13. Typical BTL configuration



8 Characterization data

The following characterizations were made with $R_L = 8\ \Omega$ and $f = 1\ \text{kHz}$ unless otherwise stated.

Figure 14. Output power vs. supply voltage (THD = 1%)

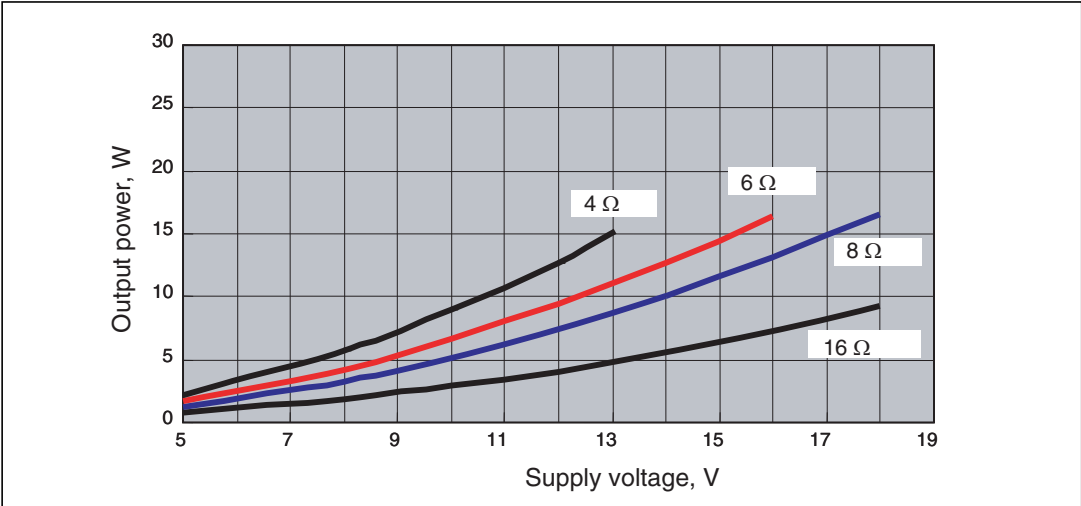


Figure 15. FFT 0 dBfs ($V_{CC} = 12\ \text{V}$)

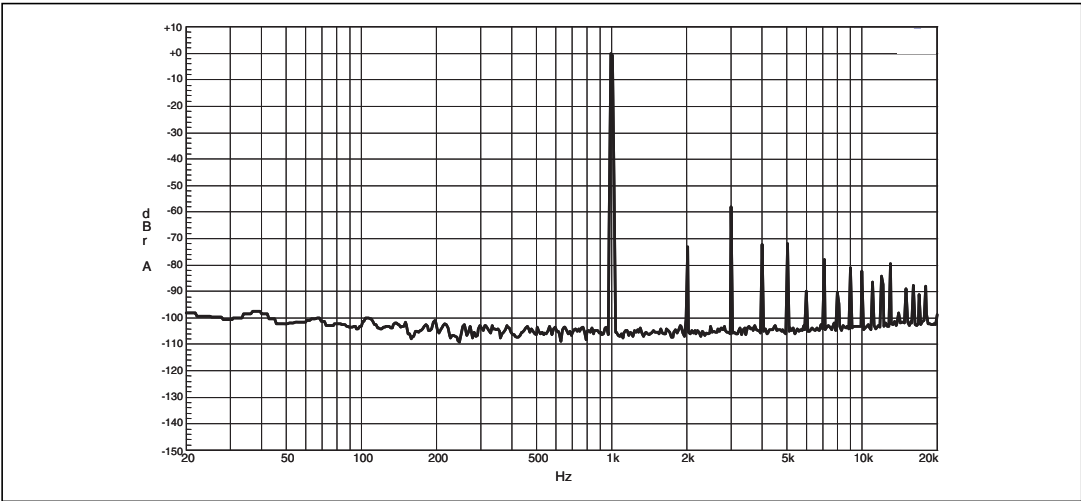


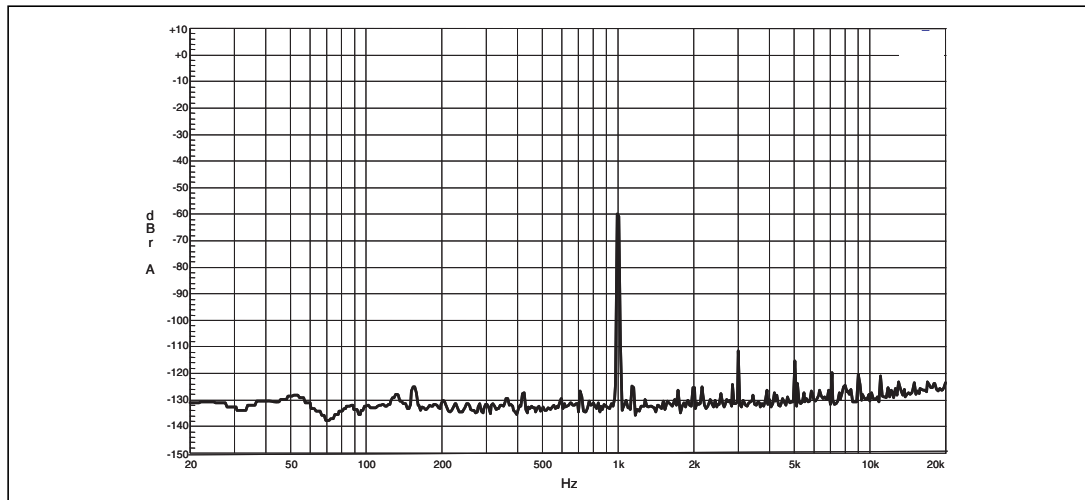
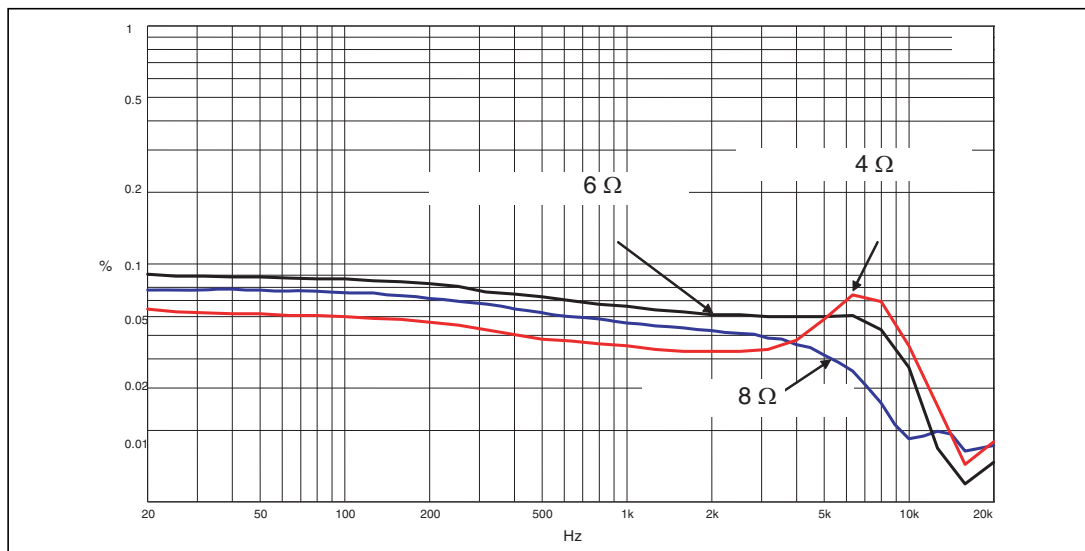
Figure 16. FFT -60 dBfs ($V_{CC} = 12\text{ V}$)Figure 17. THD vs. frequency ($V_{CC} = 12\text{ V}$, $P_o = 1\text{ W}$)

Figure 18. FFT 0 dBfs ($V_{CC} = 18\text{ V}$)

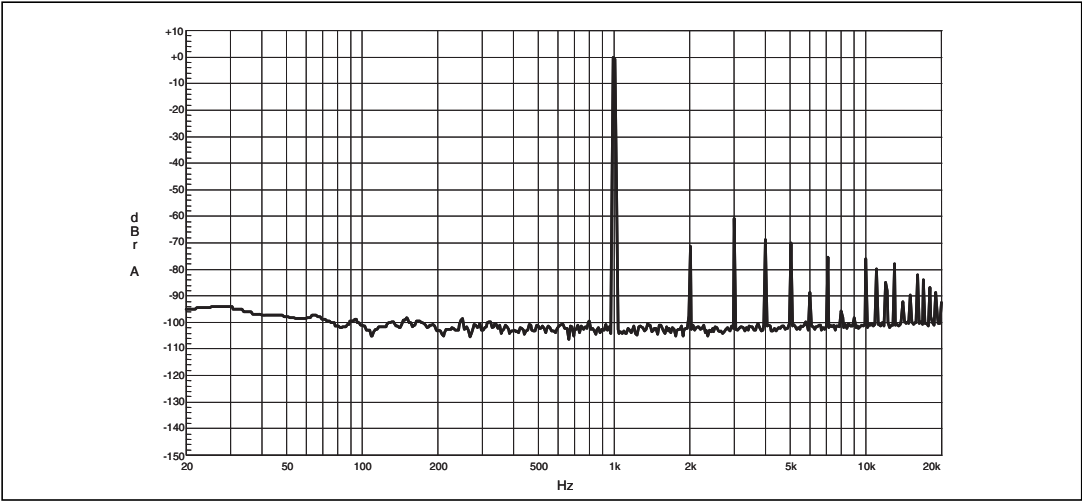


Figure 19. FFT -60 dBfs ($V_{CC} = 18\text{ V}$)

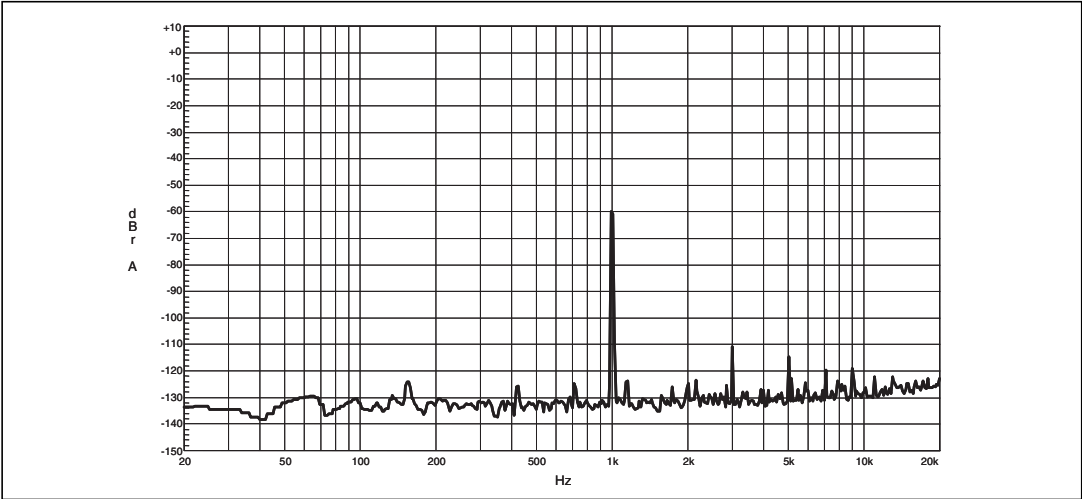
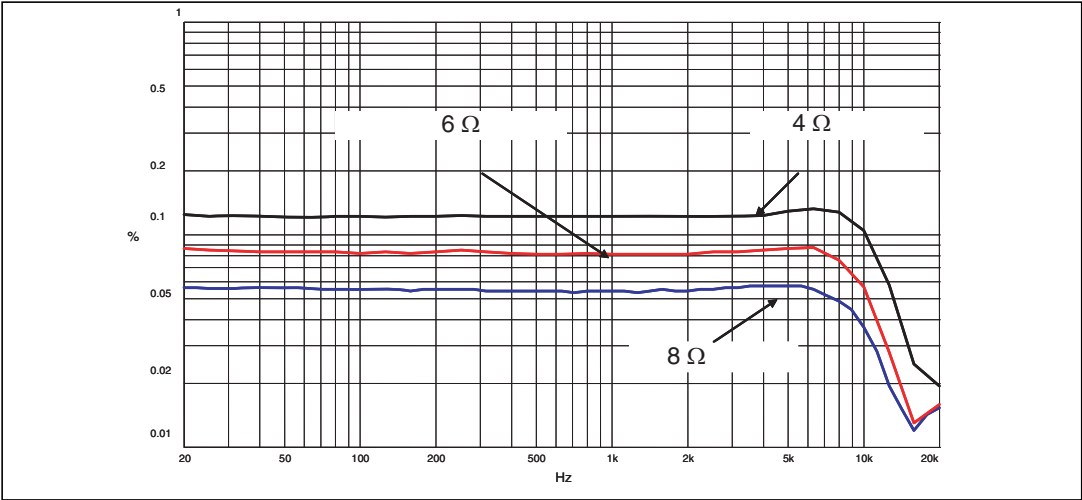


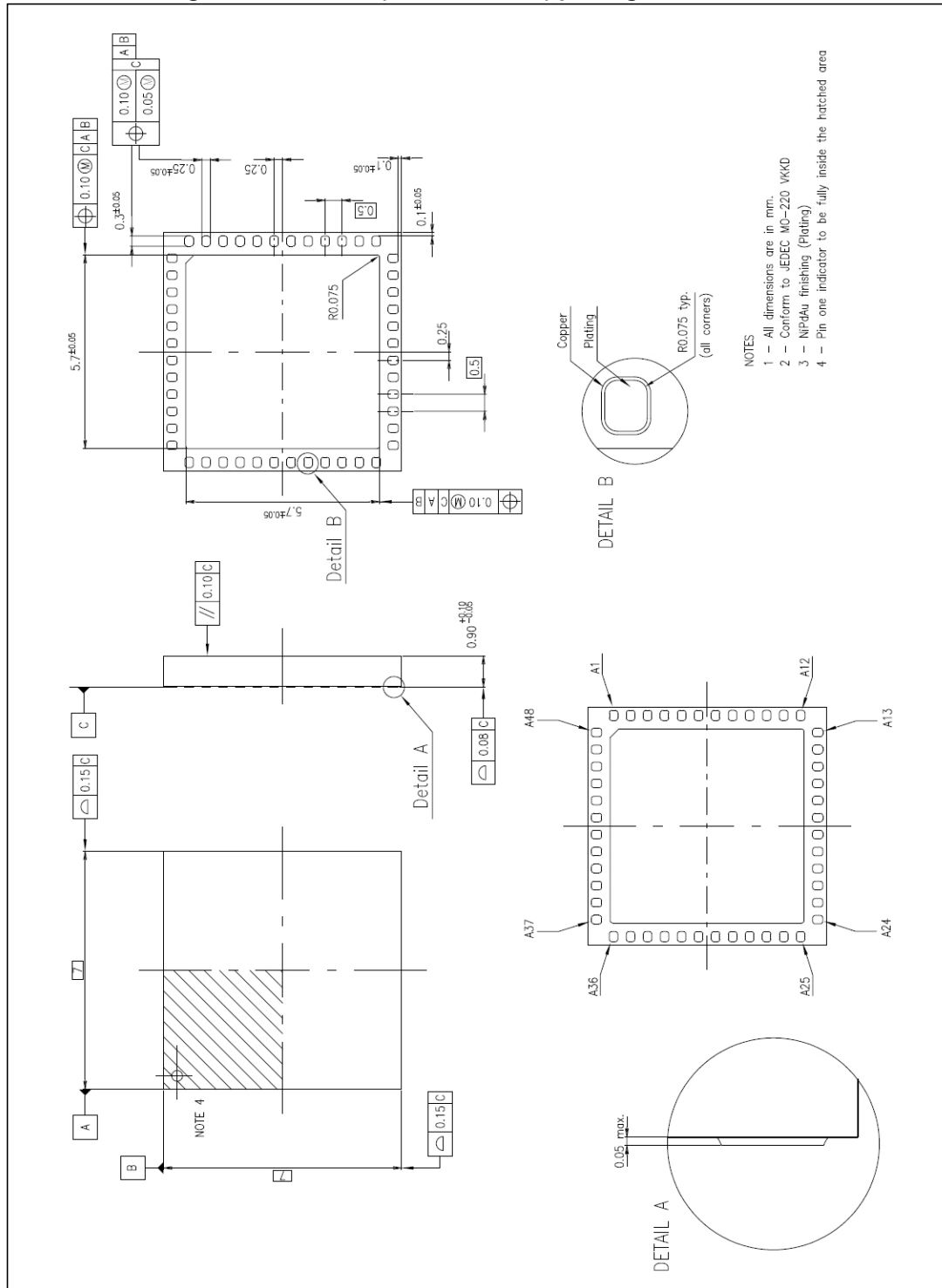
Figure 20. THD vs. frequency ($V_{CC} = 18\text{ V}$, $P_o = 1\text{ W}$)



9 Package mechanical data

The STA380WS comes in a 48-pin VQFN package with exposed pad down (EPD).

Figure 21. VQFN48 (7 x 7 x 0.9 mm) package dimensions



In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status are available at: www.st.com. ECOPACK[®] is an ST trademark.

10 **Revision history**

Table 47. Document revision history

Date	Revision	Changes
03-Apr-2013	1	Initial release.

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