ABSOLUTE MAXIMUM RATINGS

VCC0.3V to +4.0V	Current Out of ROUT+, ROUT40mA
Voltage Range at SDA, SCL, CSEL,	Continuous Power Dissipation (TA = +70°C)
LOS, CAZ, RPMIN0.3V to (VCC + 0.3V)	16-Pin TQFN (derate 14.7mW/°C above +70°C)1.176W
Voltage Range at ROUT+, ROUT(VCC - 2V) to (VCC + 0.3V)	Operating Junction Temperature Range55°C to +150°C
Voltage Range at RIN+, RIN(VCC - 1.7V) to (VCC + 0.3V)	Storage Temperature Range65°C to +160°C
Current Range Into LOS1mA to +5mA	Lead Temperature (soldering, 10s)+300°C
Current Range Into SDA1mA to +1mA	Soldering Temperature (reflow)+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{CC} = 2.85 \text{V to } 3.63 \text{V}, \text{CML receiver output is AC-coupled to differential } 100\Omega \text{ load}, \text{C}_{CAZ} = 0.1 \mu\text{F}, \text{T}_{A} = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}.$ Registers are set to default values, unless otherwise noted. Typical values are at VCC = 3.3V, TA = +25 ^{\circ}\text{C}, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
POWER SUPPLY							
Power-Supply Current		Includes the CML output current, VDIFF_ROUT = 400mVp_p, RXDE_EN = 0, LOS1_EN = 1, LOS2_EN = 0		46.6	62	νο Λ	
	Icc	Includes the CML output current, VDIFF_ROUT = 400mVp-p, RXDE_EN = 0, LOS1_EN = 0, LOS2_EN = 1		39.4	52.5	mA	
Power-Supply Voltage	Vcc		2.85		3.63	V	
Power-Supply Noise		f < 10MHz			100	mV _{P-P}	
Fower-Supply Noise		10MHz < f < 20MHz			10	IIIVP-P	
GENERAL							
Input Data Rate			1.06	10.32	11.3	Gbps	
Input/Output SNR			14.1				
BER					10E-12		
POWER-ON RESET (POR)							
POR Deassert Threshold				2.55	2.75	V	
POR Assert Threshold			2.3	2.45		V	
INPUT SPECIFICATIONS							
Differential Input Resistance RIN+/RIN-	R _{IN_DIFF}		75	100	125	Ω	
Input Sensitivity	\/	RATE_SEL = 1, input transition time 25ps, 10.32Gbps, PRBS23-1 pattern		4	8	>/	
(Note 1)	VINMIN	RATE_SEL = 0, input transition time 260ps, 1.25Gbps, K28.5 pattern		1	2	mV _{P-P}	
Input Overload	VINMAX		1.2			V _{P-P}	
	00011	DUT is powered on, f ≤ 5GHz		10		-10	
	SDD11	DUT is powered on, f ≤ 16GHz		7		dB	
Input Return Loss	00011	DUT is powered on, 1GHz < f ≤ 5GHz		13		٩D	
	SCC11	DUT is powered on, 1GHz < f ≤ 16GHz		5		dB	
RPMIN Input-Current High	Ін	LOS1_EN = 0 and LOS2_EN = 1, VRPMIN = 2V		50		nA	

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = 2.85 \text{V to } 3.63 \text{V}, \text{CML receiver output is AC-coupled to differential } 100\Omega \text{ load}, \text{CCAZ} = 0.1 \mu\text{F}, \text{TA} = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}. \text{ Registers are set to default values, unless otherwise noted.}$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
External RPMIN Filter Capacitor			100			pF	
OUTPUT SPECIFICATIONS							
Differential Output Resistance ROUT+/ROUT-	Routdiff		75	100	125	Ω	
	CDDoo	DUT is powered on, f ≤ 5GHz		13			
Output Return Loss	SDD22	DUT is powered on, f ≤ 16GHz		7		dB	
	SCC22	DUT is powered on, 1GHz < f ≤ 5GHz		10			
	30022	DUT is powered on, 1GHz < f ≤ 16GHz		6			
Differential Output Voltage High		5mV _{P-P} ≤ V _{IN} ≤ 1200mV _{P-P} , RATE_SEL = 0, SET_CML[7:0] = 169d (decimal)	595	800	1005	m\/p p	
Differential Output-Voltage High		10mV _{P-P} ≤ V _{IN} ≤ 1200mV, RATE_SEL = 1, SET_CML[7:0] = 181d	595	800	1005	mVP-P	
Differential Output-Voltage Medium		10mV _{P-P} ≤ V _{IN} ≤ 1200mV _{P-P} , RATE_SEL = 1, SET_CML[7:0] = 91d	300	400	515	mV _{P-P}	
SET_CML DAC Range			60		255	Decimal	
Differential Output Signal When Squelched (Note 1)		Outputs AC-coupled, SET_CML[7:0] = 181d, at 8.5Gbps, SQ_EN = 1		6	15	mV _{P-P}	
Data Output Transition Time (20% to 80%) (Note 1)	Time t _R /t _F	$60\text{mV}_{P-P} \leq V_{IN} \leq 400\text{mV}_{P-P}$ at 10.32Gbps , RATE_SEL = 1, $V_{DIFF_ROUT} = 400\text{mV}_{P-P}$, RXDE_EN = 0, input transition time 25ps, pattern 11110000		26	35	ps	
		$10\text{mV}_{P-P} \le V_{IN} \le 1200\text{mV}_{P-P}$ at 1.25Gbps , RATE_SEL = 0, $V_{DIFF}_{ROUT} = 800\text{mV}_{P-P}$, input transition time 260ps, pattern 11110000		52	90		
TRANSFER CHARACTERISTICS	5				-		
		$\begin{array}{l} 10 \text{mVp-p} \leq \text{V}_{\text{IN}} \leq 1200 \text{mVp-p} \text{ at } 8.5 \text{Gbps}, \\ \text{RATE_SEL} = 1, \text{VDIFF_ROUT} = 400 \text{mVp-p}, \\ \text{RXDE_EN} = 0, \text{input transition time } 28 \text{ps} \end{array}$		4	8		
		$\label{eq:control_policy} \begin{array}{l} 60\text{mVp-p} \leq \text{V}_{\text{IN}} \leq 400\text{mVp-p} \text{ at } 10.32\text{Gbps}, \\ \text{RATE_SEL} = 1, \text{VDIFF_ROUT} = 400\text{mVp-p}, \\ \text{RXDE_EN} = 0, \text{ input transition time } 28\text{ps} \end{array}$		4	9		
Deterministic Jitter (Notes 1, 2)	DJ	$60 \text{mVP-P} \le \text{VIN} \le 400 \text{mVP-P}$ at 11.3Gbps, RATE_SEL = 1, VDIFF_ROUT = 400mVP-P , RXDE_EN = 0, input transition time 28ps		4	9	psp-p	
		$\label{eq:control_policy} \begin{array}{l} 10\text{mVp-p} \leq \text{V}_{\text{IN}} \leq 1200\text{mVp-p} \text{ at } 1.25\text{Gbps}, \\ \text{RATE_SEL} = 0, \text{BW1} = 0, \text{BW0} = 0, \\ \text{VDIFF_ROUT} = 800\text{mVp-p}, \text{input transition} \\ \text{time } 260\text{ps} \end{array}$		9	30		
		$\label{eq:control_policy} \begin{array}{l} 10\text{mVP-P} \leq \text{ViN} \leq 1200\text{mVP-P} \text{ at } 4.25\text{Gbps},\\ \text{RATE_SEL} = 0, \text{BW1} = 1, \text{BW0} = 1,\\ \text{VDIFF_ROUT} = 800\text{mVP-P}, \text{ input transition}\\ \text{time } 28\text{ps} \end{array}$		5	10		

MIXIM

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = 2.85 \text{V to } 3.63 \text{V}, \text{CML receiver output is AC-coupled to differential } 100\Omega \text{ load}, \text{CCAZ} = 0.1 \mu\text{F}, \text{TA} = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}. \text{ Registers are set to default values, unless otherwise noted.}$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Random Jitter (Note 1)	RJ	Input = 60mV _{P-P} at 10.32Gbps, RATE_SEL = 1, RXDE_EN = 0, input transition time 28ps, pattern 11110000, V _{DIFF_ROUT} = 800mV _{P-P}		0.28	0.51	psRMS	
Low-Frequency Cutoff		RATE_SEL = 0, C _{CAZ} = 0.1µF		2			
(Simulated Value)		RATE_SEL = 1, CCAZ = 0.1µF		0.7		kHz	
		RATE_SEL = 0, BW1 = 0, BW0 = 0		1.0			
Con all Cincard Davidus		RATE_SEL = 0, BW1 = 0, BW0 = 1		2.1			
Small-Signal Bandwidth (Simulated Value)	f _{3dB}	RATE_SEL = 0, BW1 = 1, BW0 = 0		2.5		GHz	
(Simulated Value)		RATE_SEL = 0, BW1 = 1, BW0 = 1		3.0			
		RATE_SEL = 1		9		1	
Rx INPUT-BASED LOS SPECIF	ICATIONS (L	OS1_EN = 1 and LOS2_EN = 0) (Note 1)				•	
LOS Assert Sensitivity Range		(Note 3)	14		77	mV _{P-P}	
SET_LOS DAC Range			7		63	Decimal	
LOS Hysteresis		10log(VDEASSERT/VASSERT)	1.25	2.1		dB	
LOS Assert/Deassert Time		(Note 4)	2.3	20	80	μs	
Low Assert Level		057 00[5 0] 7 (N 0)	8	11	14	\/	
Low Deassert Level		SET_LOS[5:0] = 7d (Note 3)	14	18	22	mV _{P-P}	
Medium Assert Level		057 0015 01 00 (A) 0)	39	49	58	\/	
Medium Deassert Level		SET_LOS[5:0] = 32d (Note 3)	65	82	95	mV _{P-P}	
High Assert Level		057 0055 01 00 (N 0)	77	96	112	\/	
High Deassert Level		SET_LOS[5:0] = 63d (Note 3)	127	158	182	mV _{P-P}	
LOS Output Masking Time Range		SET_LOSTIMER[6:0] = 0d for minimum and SET_LOSTIMER[6:0] = 127d for maximum	0		2920	μs	
LOS Output Masking DAC Resolution		SET_LOSTIMER[6:0] = 1d to 127d	23	35	50	μs	
RSSI MONITOR-BASED LOS S	PECIFICATIO	NS (LOS1_EN = 0 and LOS2_EN = 1) (Note	1)				
LOS Assert Sensitivity Range		(Note 5)	8.3		90	mV	
SET_LOS DAC Range			4		63	Decimal	
LOS Hysteresis		10log(VDEASSERT/VASSERT)	1.25	2.1		dB	
LOS Assert/Deassert Time		(Note 4)	2.3	20	80	μs	
Low Assert Level		057 + 0015 01 + 4 + (4) + 5	5.1	6.7	8.3	,,	
Low Deassert Level		SET_LOS[5:0] = 4d (Note 5)	9.0	10.8	12.7	mV	
Medium Assert Level		057 1 0015 01 00 1 (1) 1 5	45	50	55		
Medium Deassert Level		SET_LOS[5:0] = 32d (Note 5)	77	85	92	- mV	
High Assert Level		057 1 0015 01 00 1 (1) 1 5	90	98	106		
High Deassert Level		SET_LOS[5:0] = 63d (Note 5)	153	167	180	- mV	
LOS Output Masking Time Range		SET_LOSTIMER[6:0] = 0d for minimum and SET_LOSTIMER[6:0] = 127d for maximum	0		2920	μs	
LOS Output Masking DAC Resolution		SET_LOSTIMER[6:0] = 1d to 127d	23	35	50	μs	

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = 2.85 \text{V to } 3.63 \text{V}, \text{CML receiver output is AC-coupled to differential } 100\Omega \text{ load}, \text{CCAZ} = 0.1 \mu\text{F}, \text{TA} = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}. \text{ Registers are set to default values, unless otherwise noted.}$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
OUTPUT LEVEL VOLTAGE DAG	(SET_CML)					
		100 Ω differential resistive load, RXDE_EN = 0		1192		
Full-Scale Voltage	VFS	100 Ω differential resistive load, RATE_SEL = 1, RXDE_EN = 1, RXDE1 = 1, RXDE0 = 1 (maximum deemphasis)		828		mV _{P-P}
		100 Ω differential resistive load, RXDE_EN = 0		4.5		
Resolution		100Ω differential resistive load, RATE_SEL = 1, RXDE_EN = 1, RXDE1 = 1, RXDE0 = 1 (maximum deemphasis)		3.3		mV _{P-P}
Integral Nonlinearity	INL	SET_CML[7:0] > 60d		±0.9		LSB
LOS THRESHOLD VOLTAGE DA	AC (SET_LOS	5)				
Full-Scale Voltage	\/=0	LOS1_EN = 1, LOS2_EN = 0		96		mV _{P-P}
Full-Scale Voltage	VFS	LOS1_EN = 0, LOS2_EN = 1		98		mV
Resolution		LOS1_EN = 1, LOS2_EN = 0		1.52		mV _{P-P}
nesolution		LOS1_EN = 0, LOS2_EN = 1		1.56		mV
Integral Nonlinearity	INL	SET_LOS[5:0] > 3d		±0.7		LSB
CONTROL I/O SPECIFICATIONS	3					
LOS Output High Voltage	Voн	RLOS = 4.7 k Ω to 10 k Ω to VCC	VCC - 0.5		Vcc	V
LOS Output Low Voltage	VoL	$R_{LOS} = 4.7 k\Omega$ to $10 k\Omega$ to V_{CC}	0		0.4	V
3-WIRE DIGITAL I/O SPECIFICA	TIONS (SDA	, CSEL, SCL)				
Input High Voltage	VIH		2.0		Vcc	V
Input Low Voltage	VIL				0.8	V
Input Hysteresis	VHYST			0.082		V
Input Leakage Current	I _{IL,IH}	$V_{IN} = 0V$ or V_{CC} , internal pullup or pulldown (75k Ω typ)			85	μA
Output High Voltage	Voh	External pullup of 4.7kΩ to V _{CC}	Vcc - 0.5		Vcc	٧
Output Low Voltage	VoL	External pullup of 4.7kΩ to VCC	0		0.4	V
3-WIRE DIGITAL INTERFACE TI	MING CHAR	ACTERISTICS (see Figure 5)				
SCL Clock Frequency	fscl		0	400	1000	kHz
SCL Pulse-Width High	tCH		500			ns
SCL Pulse-Width Low	tcL		500			ns
SDA Setup Time	tDS			100		ns
SDA Hold Time	tDH			100		ns
SCL Rise to SDA Propagation Time	tD			5		ns
CSEL Pulse-Width Low	tcsw		500			ns
	•					



ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = 2.85V \text{ to } 3.63V, \text{CML receiver output is AC-coupled to differential } 100\Omega \text{ load, } C_{CAZ} = 0.1 \mu\text{F}, T_{A} = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}. \text{ Registers are set to default values, unless otherwise noted.})$

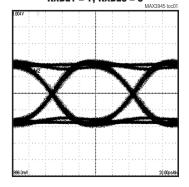
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CSEL Leading Time Before the First SCL Edge	t∟			500		ns
CSEL Trailing Time After the Last SCL Edge	t⊤			500		ns
SDA, SCL External Load	Св	Total bus capacitance on one line with 4.7k Ω to VCC			20	pF

- **Note 1:** Guaranteed by design and characterization, $T_A = -40$ °C to +95°C.
- **Note 2:** Deterministic jitter is measured with a repeating K28.5 pattern [00111110101100000101] for 1.25Gbps to 8.5Gbps data. At 10.32Gbps and 11.3Gbps, a repeating K28.5 plus 59 0s and K28.5 plus 59 1s pattern is used. Deterministic jitter is defined as the arithmetic sum of pulse-width distortion (PWD) and pattern-dependent jitter (PDJ).
- Note 3: LOS1_EN = 1, data rates of 1.25Gbps to 8.5Gbps with K28.5 pattern, and 6.4GHz input filter. For data rates of 10.32Gbps to 11.3Gbps, the input filter is 12.5GHz and the pattern is PRBS23-1.
- Note 4: Measurement includes an input AC-coupling capacitor of 100nF and C_{CAZ} of 100nF. The signal at the RIN or RPMIN input is switched between two amplitudes: Signal_ON and Signal_OFF.
 - 1) Receiver operates at sensitivity level plus 1dB power penalty
 - a) Signal_OFF = 0
 - Signal_ON = (+8dB) + 10log(min_assert_level)
 - b) Signal_ON = (+1dB) + 10log(max_deassert_level)
 - $Signal_OFF = 0$
 - 2) Receiver operates at overload
 - $Signal_OFF = 0$
 - Signal_ON = $1.2V_{P-P}$
 - max_deassert_level and min_assert_level are measured for one SET_LOS setting
- Note 5: LOS1_EN = 0, LOS2_EN = 1, DC voltage applied to the RPMIN input.

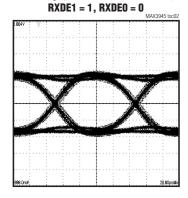
Typical Operating Characteristics

(VCC = 3.3V, TA = +25°C, unless otherwise noted. Registers are set to default values, unless otherwise noted, and the 3-wire interface is static during measurements.)

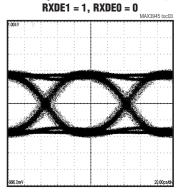
RECEIVE OUTPUT FROM OPTICAL SYSTEM, 10.32Gbps, OPTICAL INPUT -10dBm, RXDE1 = 1, RXDE0 = 0



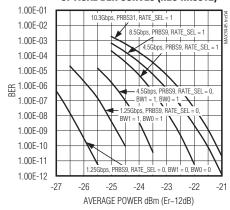
RECEIVE OUTPUT FROM OPTICAL SYSTEM, 10.32Gbps, OPTICAL INPUT -15dBm,



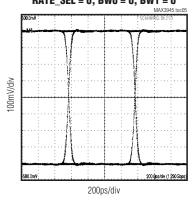
RECEIVE OUTPUT FROM OPTICAL SYSTEM, 10.32Gbps, OPTICAL INPUT -20dBm,



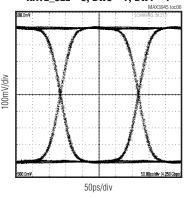
OPTICAL BER CURVES (NEC NR3312)



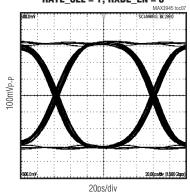
K28.5 PATTERN AT 1.25Gbps, SET_CML[7:0] = 169d, RATE_SEL = 0, BW0 = 0, BW1 = 0



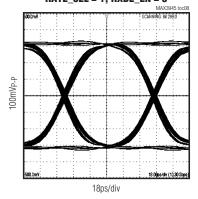
K28.5 PATTERN AT 4.25Gbps, SET_CML[7:0] = 169d, RATE_SEL = 0, BW0 = 1, BW1 = 1



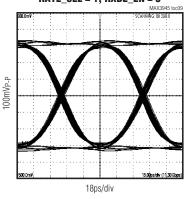
K28.5 PATTERN AT 8.5Gbps, SET_CML[7:0] = 148d, RATE_SEL = 1, RXDE_EN = 0



K28.5 PATTERN AT 10.3Gbps, SET_CML[7:0] = 148d, RATE_SEL = 1, RXDE_EN = 0

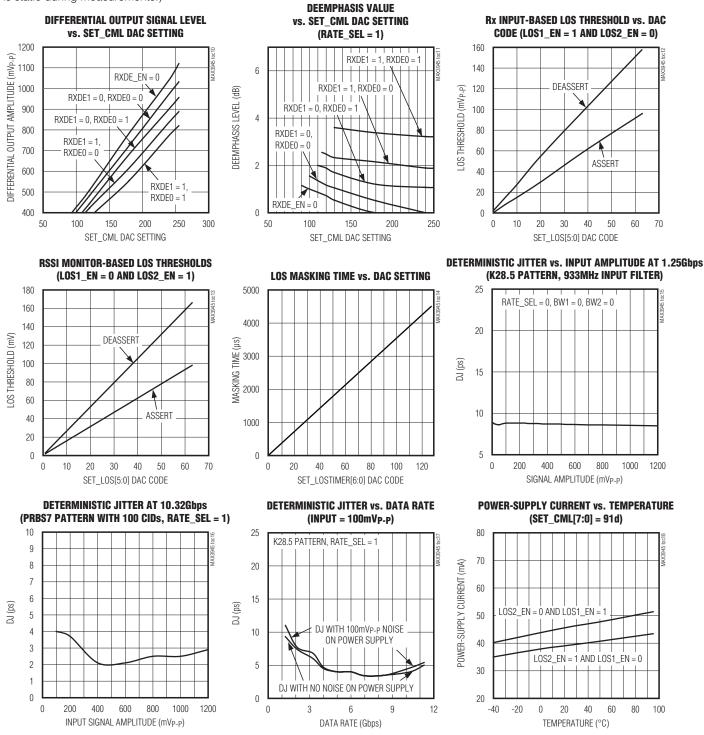


K28.5 PATTERN AT 11.3Gbps, SET_CML[7:0] = 148d, RATE_SEL = 1, RXDE_EN = 0



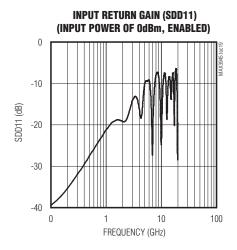
Typical Operating Characteristics (continued)

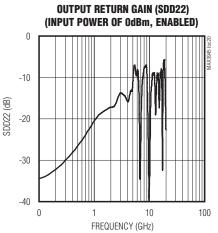
 $(V_{CC} = 3.3V, T_A = +25$ °C, unless otherwise noted. Registers are set to default values, unless otherwise noted, and the 3-wire interface is static during measurements.)

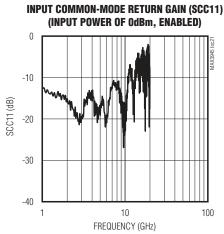


Typical Operating Characteristics (continued)

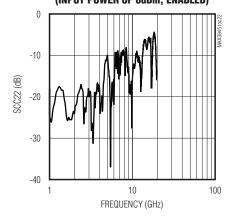
 $(V_{CC} = 3.3V, T_A = +25$ °C, unless otherwise noted. Registers are set to default values, unless otherwise noted, and the 3-wire interface is static during measurements.)



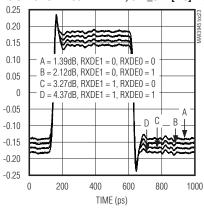




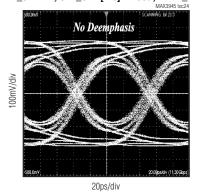
OUTPUT COMMON-MODE RETURN GAIN (SCC22) (INPUT POWER OF OdBm, ENABLED)



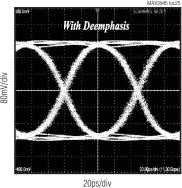
TRANSIENT RESPONSE (10.3Gbps, 10 ONES 10 ZEROS PATTERN, SET_CML[7:0] = 92d)



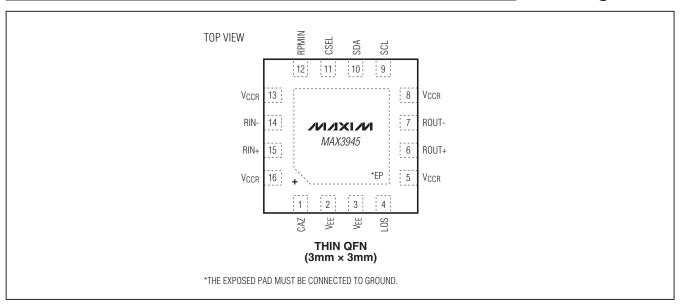
ELECTRICAL EYE DIAGRAM AFTER 6in OF FR4
AND 72in OF CABLE WITH NO DEEMPHASIS (11.3Gbps K28.5,
RATE_SEL = 1, SET_CML[7:0] = 160d, RXDE_EN = 0)



ELECTRICAL EYE DIAGRAM AFTER 6in OF FR4
AND 72in OF CABLE WITH DEEMPHASIS (11.3Gbps K28.5, RATE_SEL = 1,
SET_CML[7:0] = 160d, RXDE_EN = 1, RXDE0 = 1, RXDE1 = 1)



Pin Configuration



Pin Description

PIN	NAME	FUNCTION
1	CAZ	Offset-Correction Loop Capacitor. A capacitor connected between this pin and the adjacent VEE pin sets the time constant of the offset-correction loop. The offset correction can be disabled through the digital interface by setting bit AZ_EN = 0 and by connecting this pin to ground.
2, 3	VEE	Ground for Limiting Amplifier
4	LOS	Loss-of-Signal Output. This output is an open-drain output. LOS is asserted when the level of the input signal drops below the preset threshold set by SET_LOS[5:0]. LOS is deasserted when the signal level is above the threshold. The polarity of the LOS output can be inverted by setting LOS_POL = 0. The LOS circuitry can be disabled by setting LOS1_EN = 0 and LOS2_EN = 0. See Table 8.
5, 8, 13, 16	VCCR	Power Supply. Provides supply voltage to the limiting amplifier. All pins must be connected to the supply voltage.
6	ROUT+	Noninverted Output, CML. Back terminated for 50Ω load.
7	ROUT-	Inverted Output, CML. Back terminated for 50Ω load.
9	SCL	Serial-Clock Input, TTL/CMOS. This pin has a 75k Ω internal pulldown.
10	SDA	Serial-Data Bidirectional I/O. TTL/CMOS input and open-drain output. This pin has a $75k\Omega$ internal pullup, but it requires an external $4.7k\Omega$ pullup resistor to meet the 3-wire digital timing specification. (Data line collision protection is implemented.)
11	CSEL	Chip-Select Input, TTL/CMOS. Internally pulled down by a 75k Ω resistor. CSEL = 1 starts an SPI cycle, while CSEL = 0 ends the SPI cycle and resets the control state machine.
12	RPMIN	High-Impedance Receive Power-Monitor Input. Connect to ground when not used.
14	RIN-	Inverted Data Input, CML, with 50Ω Termination
15	RIN+	Noninverted Data Input, CML, with 50Ω Termination
_	EP	Exposed Pad. Must be soldered to circuit ground.

MIXIM

Detailed Description

The MAX3945 is designed to operate from 1.0625Gbps to 11.3Gbps. It consists of a dual-path limiter, offset-correction circuitry, CML output stage, and LOS circuitry. The characteristics of the MAX3945 can be controlled through the on-chip 3-wire interface. The registers that control the part's functionality are RXCTRL1, RXCTRL2, RXSTAT, SET_CML, SET_LOS, MODECTRL, and SET_LOSTIMER. The MAX3945 provides integrated DACs to allow the use of low-cost controller ICs. Figure 1 shows simplified input and output structures.

Dual-Path Limiter

The limiting amplifier features a low data-rate path (1.0625Gbps to 4.25Gbps) and a high data-rate path (up to 11.3Gbps), allowing for overall system optimization. Figure 2 shows the functional diagram. Data path selection is controlled by the RATE_SEL bit. The low data-rate path further features a programmable filter that provides optimization for 1.0625Gbps, 1.25Gbps, 2.125Gbps, and 4.25Gbps operation. It is important to tailor the bandwidth of the first stages to get the best receive sensitivity and to reduce the maximum receive

bandwidth for a given data rate. Table 1 summarizes the RATE_SEL, BW1, and BW0 control bit functions. The high data-rate mode (RATE_SEL = 1) is recommended for operation up to 11.3Gbps.

The polarity of ROUT+/ROUT- relative to RIN+/RIN- is programmed by the RX_POL bit, as shown in Table 2.

Offset-Correction Circuitry

The offset-correction circuitry is provided to remove PWD caused by intrinsic offset voltages within the differential amplifier stages. An external 0.1µF capacitor connected between the CAZ pin and ground sets the offset-correction loop cutoff frequency to approximately 2kHz when RATE_SEL = 0 and to approximately 0.7kHz when RATE_SEL = 1. The offset-correction loop can be disabled using the AZ_EN bit, as shown in Table 3.

CML Output Stage

CML Output Enable and Squelch

The CML output stage is optimized for differential 100Ω loads. The output stage is controlled by a combination of the RX_EN and SQ_EN bits and the internal LOS status. See Table 4.

Table 1. Rate Select and Bandwidth Control

	RXCTRL1[3:1]		OPERATION MODE DESCRIPTION			
BW1	BW0	RATE_SEL	DATA RATE (Gbps)	FILTER BANDWIDTH (MHz)	RISE/FALL TIME (ps)	
0	0	0	1.0625 to 1.25	1000	52	
0	1	0	2.125	2100	52	
1	0	0	2.125	2500	52	
1	1	0	4.25	3000	52	
X	X	1	11.3	9000	26	

Table 2. Signal Polarity Control

RX_POL	OPERATION MODE DESCRIPTION
0	Inversed polarity of the differential signal path
1	Normal polarity of the differential signal path

Table 3. Offset-Correction Enable/Disable Control

AZ_EN	OPERATION MODE DESCRIPTION
0	Autozero loop is disabled
1	Autozero loop is enabled

Table 4. CML Output Stage Operation Modes

RX_EN	SQ_EN	LOS STATUS	OPERATION MODE DESCRIPTION
0	X	X	CML output disabled
1	0	X	CML output enabled
1	1	0	CML output enabled
1	1	1	CML output disabled

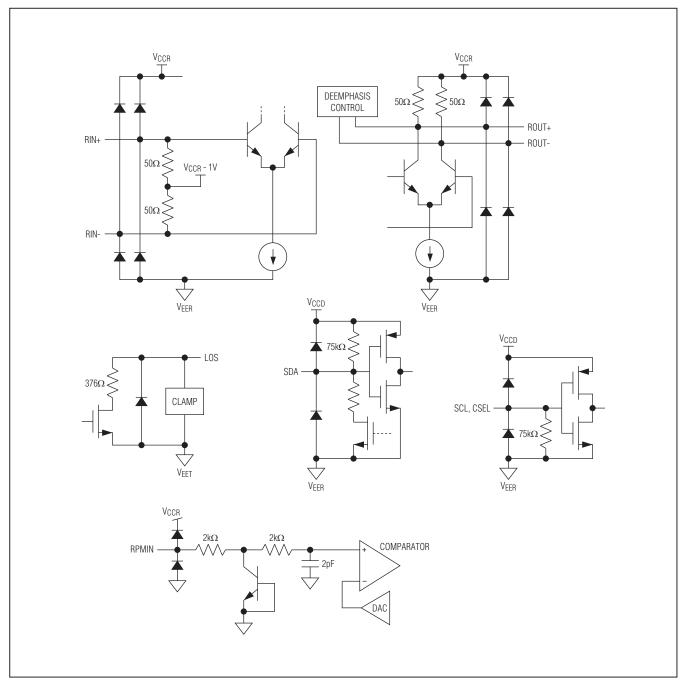


Figure 1. Simplified Input/Output Structures

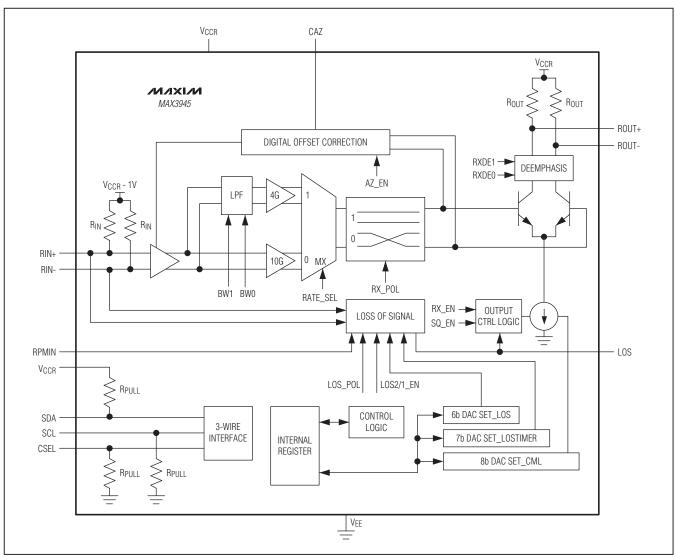


Figure 2. Functional Diagram

CML Output Deemphasis

The CML output stage is optimized for differential 100Ω transmission lines on a standard FR4 board. The RXDE1 and RXDE0 bits add programmable analog output deemphasis to compensate for FR4 board losses and SFP connector losses. Table 5 describes the deemphasis control settings.

Programmable CML Output Amplitude

The 8-bit SET_CML register controls the amplitude of the CML output stage. The maximum programmable output level depends on the operational mode of the MAX3945. These output levels (which assume an ideal 100Ω differential load) and their corresponding control bits are described in Table 6. Table 7 shows the output DAC resolution dependency.

Table 5. Output Signal Deemphasis Control

RXCTRL2[1]	RXCTRL1[7:6]		OPERATION MODE DESCRIPTION		
RXDE_EN	RXDE1	RXDE0	MODE	DEEMPHASIS (dB)	
0	Х	Х	Deemphasis block is disabled	0	
1	0	0	Deemphasis block is enabled Level 1	0.3	
1	0	1	Deemphasis block is enabled Level 2	1.1	
1	1	0	Deemphasis block is enabled Level 3	2.1	
1	1	1	Deemphasis block is enabled Level 4	4.3	

Table 6. CML Output Amplitude Range (Typical)

RXCTRL1[1]	RXCTRL2[1]	RXCTI	RL1[7:6]	MODE	OUTPUT AMPLITUDE
RATE_SEL	RXDE_EN	RXDE1	RXDE0	MODE	(mV _{P-P})
0	X	X	X	Low data-rate path	400 to 1192
1	0	X	X	High data-rate path	400 to 1147
1	1	0	0	High data-rate path with deemphasis	400 to 1041
1	1	0	1	High data-rate path with deemphasis	400 to 987
1	1	1	0	High data-rate path with deemphasis	400 to 908
1	1	1	1	High data-rate path with deemphasis	400 to 828

Table 7. CML Output DAC Resolution (Typical)

	•				
RXCTRL1[1]	RXCTRL2[1]	RXCT	RL1[7:6]	MODE	RESOLUTION
RATE_SEL	RXDE_EN	RXDE1	RXDE0	MODE	(mV _{P-P})
0	X	Х	X	Low data-rate path	4.5
1	0	X	X	High data-rate path	4.5
1	1	0	0	High data-rate path with deemphasis	4.1
1	1	0	1	High data-rate path with deemphasis	3.9
1	1	1	0 High data-rate path with deemphasis		3.6
1	1	1	1	High data-rate path with deemphasis	3.3

Table 8. LOS Control

LOS2_EN	LOS1_EN	OPERATION MODE DESCRIPTION
0	0	LOS circuitry is disabled and powered down
X	1	LOS circuitry is enabled and Rx input amplitude is detected
1	0	LOS circuitry is enabled and RPMIN input amplitude is detected

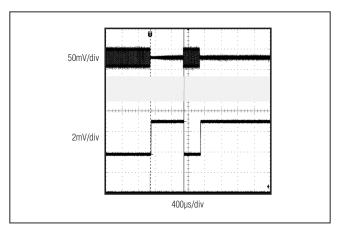


Figure 3. LOS Response to a Short Burst of Input Signal

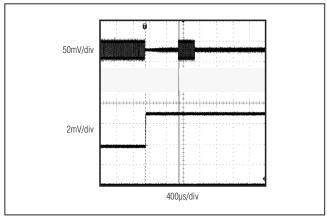


Figure 4. LOS Response to a Short Burst of Input Signal (Any changes in LOS are masked until the end of the LOS masking period.)

LOS Circuitry

The LOS circuitry has two operational modes controlled by the LOS1_EN and LOS2_EN bits (see Table 8). In the first mode, the LOS block detects the differential amplitude of the input signal and compares it against a preset threshold controlled by the 6-bit SET_LOS register. In the second mode, the LOS block compares the voltage at the RPMIN pin to a preset threshold also controlled by the 6-bit SET_LOS register. The second mode enables low-power LOS detection based on average photodiode current.

The LOS assert threshold is approximately 1.5mVP-P x SET_LOS[5:0]. The LOS deassert level is approximately 1.6 times the assert level to avoid LOS chatter. LOS polarity, squelch, and LOS masking time are unaffected by the selection of LOS1_EN or LOS2_EN.

Programmable LOS Output Masking Time

This feature masks false input signals that can occur after a loss-of-light event in a fiber optic link. These false input signals, caused by some transimpedance amplifier implementations, can corrupt the LOS output and cause system-level link diagnostic errors.

The LOS output masking time can be programmed from 0 to 4500µs in 35µs steps using the 7-bit SET_LOSTIMER[6:0] register. The output mask timer is initiated on the first transition of the LOS signal and prevents any further changes in the LOS output signal until the end of the programmed LOS timing period. The LOS output masking time should be carefully chosen to extend beyond any expected input glitch. Figure 3 shows the LOS signal changing after approximately 800µs to a change in the input signal where the LOS output masking time function is not used. Figure 4 shows masking of the LOS signal by the LOS output masking time function to a change in the input signal.

Table 9. Digital Communication Word Structure

	BIT														
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Register Address							RWN			Data	that is w	ritten or	read.		

Table 10. Register Descriptions and Addresses

ADDRESS	NAME	FUNCTION
H0x00	RXCTRL1	Receiver Control Register 1
H0x01	RXCTRL2	Receiver Control Register 2
H0x02	RXSTAT	Receiver Status Register
H0x03	SET_CML	CML Output Level Setting Register
H0x04	SET_LOS	LOS Threshold Assert Level Setting Register
H0x0E	MODECTRL	General Control Register
H0x12	SET_LOSTIMER	LOS Timer Setting Register

3-Wire Digital Communication

General

The MAX3945 implements a proprietary 3-wire digital interface. An external controller generates the clock. The 3-wire interface consists of an SDA bidirectional data line, an SCL clock signal input, and a CSEL chip-select input (active high). The external master initiates a data transfer by asserting the CSEL pin. The master starts to generate a clock signal after the CSEL has been set to 1. All data transfers are most significant bit (MSB) first.

Protocol

Each operation consists of 16-bit transfers (15-bit address/data, 1-bit RWN). The bus master generates 16 clock cycles to SCL. All operations transfer 8 bits to the MAX3945. The RWN bit determines if the cycle is read or write. See Table 9.

Register Addresses

The MAX3945 contains seven registers available for programming. Table 10 shows the registers and addresses.

Write Mode (RWN = 0)

The master generates 16 total clock cycles at SCL. The master outputs a total of 16 bits (MSB first) to the SDA

line at falling edge of the clock. The master closes the transmission by setting CSEL to 0. Figure 5 shows the interface timing, and Table 11 defines the various timing parameters.

Read Mode (RWN = 1)

The master generates 16 total clock cycles at SCL. The master outputs a total of 8 bits (MSB first) to the SDA line at falling edge of the clock. The SDA line is released after the RWN bit has been transmitted. The slave outputs 8 bits of data (MSB first) at rising edge of the clock. The master closes the transmission by setting CSEL to 0. Figure 5 shows the interface timing.

Mode Control

Normal mode allows read-only instruction for all registers except MODECTRL. Normal mode is the default mode.

Setup mode allows the master to write unrestricted data into any register except the RXSTAT register. To enter setup mode, the MODECTRL register (address = H0x0E) must be set to H0x12. After the MODECTRL register has been set to H0x12, the next operation is unrestricted. The setup mode is automatically exited after the next operation is finished. This sequence must be repeated if further unrestricted settings are necessary.

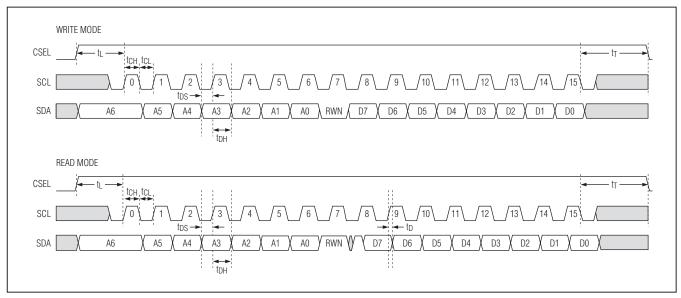


Figure 5. Timing for the 3-Wire Digital Interface

Table 11. Interface Timing Parameters

SYMBOL	DEFINITION
t∟	CSEL leading time before the first SCL edge
tCH	SCL pulse-width high
tCL	SCL pulse-width low
t _D	SCL rise to SDA propagation time
tDS	SDA setup time
tDH	SDA hold time
t⊤	CSEL trailing time after last SCL edge

Register Descriptions Receiver Control Register 1 (RXCTRL1)

Bit #
Name
Default Value

7	6	5	4	3	2	1	0	ADDRESS	
RXDE1	RXDE0	X*	SOFTRES	BW1	BW0	RATE_SEL	Χ*	Hoyoo	
0	0	1	0	1	1	1	1	H0x00	

^{*}Do not change default setting.

Bits 7 and 6: RXDE[1:0]. These 2 bits are used to control deemphasis of the output waveform. See Table 5 for the bit settings and corresponding deemphasis levels.

Bit 4: SOFTRES. When this bit is set to 1 during a 3-wire interface write operation, all registers are set to the default state when CSEL goes low.

Bits 3 and 2: BW[1:0]. When RATE_SEL = 0, these 2 bits control the bandwidth of the limiting amplifier. See Table 1 for the settings and corresponding filter selection.

Bit 1: RATE_SEL. RATE_SEL selects between the low bandwidth data path (1.0625Gbps to 4.25Gbps) and the high bandwidth data path (4.25Gbps to 11.3Gbps). When RATE_SEL is set to 1, the high bandwidth path is chosen. When RATE_SEL is set to 0, the low bandwidth path is chosen.

Receiver Control Register 2 (RXCTRL2)

Bit # Name Default Value

	7	6	5	4	3	2	1	0	ADDRESS	
LOS	52_EN	LOS1_EN	LOS_POL	RX_POL	SQ_EN	RX_EN	RXDE_EN	AZ_EN	LIOVO1	
	0	1	1	1	0	1	0	1	H0x01	

Bit 7: LOS2_EN. Enables or disables the RSSI monitor-based LOS circuitry, in combination with the LOS1_EN bit. The below table shows when the RSSI monitor-based LOS is disabled and enabled.

LOS2_EN	LOS1_EN	RX_EN	Rx INPUT-BASED LOS	RSSI MONITOR-BASED LOS
0	0	X	Disabled and powered down	Disabled and powered down
0	1	1	Enabled	Disabled and powered down
Χ	1	0	Disabled and powered down	Disabled and powered down
1	1	1	Enabled	Disabled and powered down
1	0	0	Disabled and powered down	Enabled
1	0	1	Disabled and powered down	Enabled

Bit 6: LOS1_EN. Controls the Rx input-based LOS circuitry. When RX_EN is set to 0, the LOS detector is also disabled.

0 = disabled

1 = enabled

Bit 5: LOS POL. Controls the polarity of the LOS pin.

0 = inverse

1 = normal

Bit 4: RX_POL. Controls the polarity of the CML output.

0 = inverse

1 = normal

Bit 3: SQ_EN. When SQ_EN = 1, the CML output is squelched when LOS is asserted.

0 = disabled

1 = enabled

Bit 2: RX_EN. Enables or disables the receive circuitry.

0 = disabled

1 = enabled

Bit 1: RXDE_EN. Enables or disables the deemphasis on the CML output.

0 = disabled

1 = enabled

Bit 0: AZ_EN. Enables or disables the autozero circuitry.

0 = disabled

1 = enabled

Receiver Status Register (RXSTAT)

Bit #	7	6	5	4	3	2	1 (STICKY)	0 (STICKY)	ADDRESS
Name	Х	Х	Χ	Х	Χ	X	POR_2d	LOS_2d	H0x02
Default Value	Х	Х	Χ	Χ	Χ	Х	Χ	Χ	HUXUZ

Bit 1: POR_2d. When the V_{CC} supply voltage is below 2.3V, the POR circuitry sets POR_2d high. When the supply voltage is above 2.75V, the POR circuitry deasserts, but the POR_2d bit remains high until it is read.

Bit 0: LOS_2d. Copy of the LOS status. This is a sticky bit, which means that it is cleared on a read. The first 0-to-1 transition is latched until the bit is read by the master or POR occurs.

CML Output Level Setting Register (SET_CML)

Bit #	7	6	5	4	3	2	1	0	ADDRESS
Name	SET_CML[7] (MSB)	SET_CML[6]	SET_CML[5]	SET_CML[4]	SET_CML[3]	SET_CML[2]	SET_CML[1]	SET_CML[0] (LSB)	H0x03
Default Value	0	1	0	1	1	1	0	0	

Bits 7 to 0: SET_CML[7:0]. The SET_CML register is an 8-bit register that can be set up to 255 for maximum CML output amplitude. See Table 13 for equations to determine CML output level vs. SET_CML.

LOS Threshold Assert Level Setting Register (SET_LOS)

Bit #	7	6	5	4	3	2	1	0	ADDRESS
Name	X	X	SET_LOS[5] (MSB)	SET_LOS[4]	SET_LOS[3]	SET_LOS[2]	SET_LOS[1]	SET_LOS[0] (LSB)	H0x04
Default Value	Χ	Х	0	0	1	1	0	0	

Bits 5 to 0: SET_LOS[5:0]. The SET_LOS register is a 6-bit register used to program the LOS threshold. See the *Typical Operating Characteristics* section for a typical LOS threshold voltage vs. DAC code for both the Rx input-based LOS and the RSSI monitor-based LOS.

General Control Register (MODECTRL)

Bit #
Name
Default
Value

7	6	5	4	3	2	1	0	ADDRESS
MODECTRL[7] (MSB)	MODECTRL[6]	MODECTRL[5]	MODECTRL[4]	MODECTRL[3]	MODECTRL[2]	MODECTRL[1]	MODECTRL[0] (LSB)	H0x0E
0	0	0	0	0	0	0	0	TIOXOE

Bits 7 to 0: MODECTRL[7:0]. The MODECTRL register enables a switch between normal and setup modes. The setup mode is achieved by setting this register to H0x12. MODECTRL must be updated before each write operation.

LOS Timer Setting Register (SET_LOSTIMER)

Bit #
Name

Default Value

7	6	5	4	3	2	1	0	ADDRESS
X	SET_ LOSTIMER[6] (MSB)	SET_ LOSTIMER[5]	SET_ LOSTIMER[4]	SET_ LOSTIMER[3]	SET_ LOSTIMER[2]	SET_ LOSTIMER[1]	SET_ LOSTIMER[0] (LSB)	H0x12
Χ	0	0	0	0	0	0	0	

Bits 6 to 0: SET_LOSTIMER[6:0]. The SET_LOSTIMER register is a 7-bit register that can be set from 0 to 127. See the *Typical Operating Characteristics* section for a typical timer period vs. DAC code.

Table 12. Register Map

REGISTER FUNCTION/ ADDRESS	REGISTER NAME	NORMAL MODE	SETUP MODE	BIT NUMBER/ TYPE	BIT NAME	DEFAULT VALUE	NOTES
		R	RW	7	RXDE1	0	Rx deemphasis MSB control with RXDE_EN = 1
	R	RW	6	RXDE0	0	Rx deemphasis LSB control with RXDE_EN = 1	
	R	RW	5	Χ	1	Must be set to 1	
Receiver		R	RW	4	SOFTRES	0	Soft reset control bit
Control Register 1 Address = H0x00	RXCTRL1	R	RW	3	BW1	1	Input bandwidth control with RATE_SEL = 0: 00: 1GHz 01: 2.1GHz 10: 2.5GHz 11: 3GHz
		R	RW	2	BW0	1	
		R	RW	1	RATE_SEL	1	Rate-select control 0: 1G/4G mode 1: fast mode
		R	RW	0	Χ	1	Must be set to 1

Table 12. Register Map (continued)

REGISTER FUNCTION/ ADDRESS	REGISTER NAME	NORMAL MODE	SETUP MODE	BIT NUMBER/ TYPE	BIT NAME	DEFAULT VALUE	NOTES	
Receiver Control Register 2 Address =		R	RW	7	LOS2_EN	0	RSSI monitor- based LOS 0: disabled 1: enabled when LOS1_EN = 0	
		R	RW	6	LOS1_EN	1	Rx input-based LOS 0: disabled 1: enabled	
		R	RW	5	LOS_POL	1	LOS polarity 0: inverse 1: normal	
	RXCTRL2	R	RW	4	RX_POL	1	Rx polarity 0: inverse 1: normal	
H0x01			R	RW	3	SQ_EN	0	Squelch 0: disabled 1: enabled
		R	RW	2	RX_EN	1	Rx control 0: disabled 1: enabled	
		R	RW	1	RXDE_EN	0	Rx deemphasis 0: disabled 1: enabled	
		R	RW	0	AZ_EN	1	Rx autozero control 0: disabled 1: enabled	
Receiver Status Register	RXSTAT	R	R	1 (sticky)	POR_2d	Х	POR -> V _{CC} low limit violation	
Address = H0x02		R	R	0 (sticky)	LOS_2d	X	Copy of LOS status	

Table 12. Register Map (continued)

REGISTER FUNCTION/ ADDRESS	REGISTER NAME	NORMAL MODE	SETUP MODE	BIT NUMBER/ TYPE	BIT NAME	DEFAULT VALUE	NOTES
		R	RW	7	SET_CML[7]	0	MSB output level DAC
CML Output		R	RW	6	SET_CML[6]	1	
Level		R	RW	5	SET_CML[5]	0	
Setting	CET CM	R	RW	4	SET_CML[4]	1	
Register	SET_CML	R	RW	3	SET_CML[3]	1	
Address =		R	RW	2	SET_CML[2]	1	
H0x03		R	RW	1	SET_CML[1]	0	
		R	RW	0	SET_CML[0]	0	LSB output level DAC
LOS		R	RW	5	SET_LOS[5]	0	MSB LOS thresh- old DAC
Threshold		R	RW	4	SET_LOS[4]	0	
Assert Level	057.1.00	R	RW	3	SET_LOS[3]	1	
Setting Register	SET_LOS	R	RW	2	SET_LOS[2]	1	
Address =		R	RW	1	SET_LOS[1]	0	
H0x04		R	RW	0	SET_LOS[0]	0	LSB LOS thresh- old DAC
		RW	RW	7	MODECTRL[7]	0	MSB mode control
		RW	RW	6	MODECTRL[6]	0	
General		RW	RW	5	MODECTRL[5]	0	
Control	MODECTRI	RW	RW	4	MODECTRL[4]	0	
Register Address =	MODECTRL	RW	RW	3	MODECTRL[3]	0	
H0x0E		RW	RW	2	MODECTRL[2]	0	
		RW	RW	1	MODECTRL[1]	0	
		RW	RW	0	MODECTRL[0]	0	LSB mode con- trol
		R	RW	6	SET_LOSTIMER[6]	0	MSB LOS timer
LOS Timer		R	RW	5	SET_LOSTIMER[5]	0	
Setting		R	RW	4	SET_LOSTIMER[4]	0	
Register	SET_LOSTIMER	R	RW	3	SET_LOSTIMER[3]	0	
Address =		R	RW	2	SET_LOSTIMER[2]	0	
H0x12		R	RW	1	SET_LOSTIMER[1]	0	
		R	RW	0	SET_LOSTIMER[0]	0	LSB LOS timer

Design Procedure

Programming CML Output Levels

See Tables 13 and 14. For each value of the bits RXDE1 and RXDE0 in Table 13, the value of deemphasis does vary with the SET_CML[7:0] setting. In Table 13, the values of deemphasis are given for the setting SET_CML[7:0] = 120d. The variation of deemphasis for other values of SET_CML[7:0] is shown in the *Typical Operating Characteristics* (see the Deemphasis Value vs. SET_CML DAC Setting (RATE_SEL = 1) graph). Note that even though RXDE_EN = 0, there is still some deemphasis for RATE_SEL = 1 for values of amplitude control below SET_CML[7:0] = 170d.

Select the Coupling Capacitor

For AC-coupling, the coupling capacitors C_{IN} and C_{OUT} should be selected to minimize the receiver's deterministic jitter. Jitter is decreased as the input low frequency cutoff (f_{IN}) is decreased: f_{IN} = $1/[2\pi(50)(C_{IN})]$. The recommended value of C_{IN} and C_{OUT} is $0.1\mu F$ for the MAX3945.

Select the Offset-Correction Capacitor

The capacitor between CAZ and ground determines the time constant of the signal path DC-offset cancellation loop. A $0.1\mu F$ capacitor between CAZ and ground is recommended for the MAX3945.

Applications Information

Layout Considerations

Use good, high-frequency layout techniques and multiple-layer boards with uninterrupted ground planes to minimize EMI and crosstalk.

Exposed-Pad Package

The exposed pad on the 16-pin TQFN provides a very low-thermal resistance path for heat removal from the IC. The pad is also electrical ground on the MAX3945 and must be soldered to the circuit board ground for proper thermal and electrical performance. Refer to Application Note 862: HFAN-08.1: Thermal Considerations of QFN and Other Exposed-Paddle Packages for additional information.

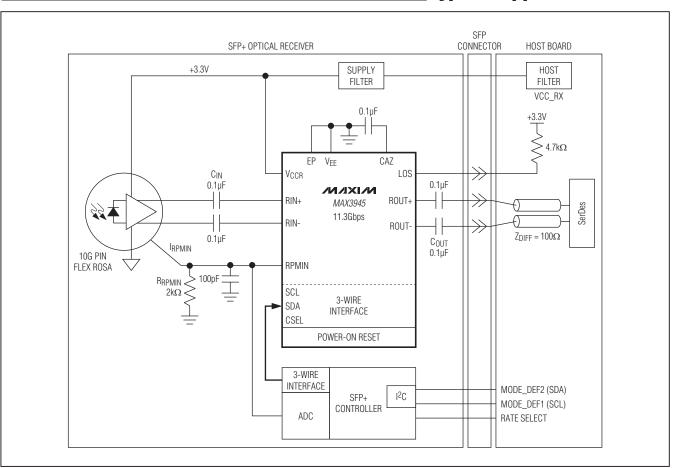
Table 13. CML Output Amplitude Equations (Typical)

RXCTRL1[1]	RXCTRL2[1]	RXCTRL1[7:6]		DEEMPHASIS (dB)	EQUATION FOR (VROUT+ - VROUT-)	
RATE_SEL	RXDE_EN	RXDE1	RXDE0	(SET_CML[7:0] = 120d)	EGOATION FOR (VROUT+ - VROUT-)	
0	X	Χ	Χ	0	45mV _{P-P} + 4.5mV _{P-P} x SET_CML	
1	0	Χ	Χ	0.72	4.5mV _{P-P} x SET_CML	
1	1	0	0	1.17	-4mV _{P-P} + 4.1mV _{P-P} x SET_CML	
1	1	0	1	1.89	-7mVp-p + 3.9mVp-p x SET_CML	
1	1	1	0	2.48	-10mV _{P-P} + 3.6mV _{P-P} x SET_CML	
1	1	1	1	3.86	-13mV _{P-P} + 3.3mV _{P-P} x SET_CML	

Table 14. SET_CML DAC Codes for 400mVp-p and 800mVp-p Output Levels

RXCTRL1[1]	RXCTRL2[1]	RXCT	RL1[7:6]	SET_CML DAC CODE		
RATE_SEL	RXDE_EN	RXDE1	RXDE0	400mV _{P-P}	800mV _{P-P}	
0	Х	X	X	80	169	
1	0	X	X	91	181	
1	1	0	0	98	194	
1	1	0	1	106	208	
1	1	1	0	115	225	
1	1	1	1	126	245	

Typical Application Circuit



Package Information

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.
16 TQFN-EP	T1633+5	<u>21-0136</u>

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