

## Features

- **IN-SYSTEM PROGRAMMABLE**
  - IEEE 1149.1 Standard TAP Controller Port Programming
  - 4-Wire Serial Programming Interface
  - Minimum 10,000 Program/Erase Cycles
- **HIGH PERFORMANCE E<sup>2</sup>CMOS<sup>®</sup> TECHNOLOGY**
  - 4 ns Maximum Propagation Delay
  - F<sub>max</sub> = 250 MHz
  - 3 ns Maximum from Clock Input to Data Output
  - UltraMOS<sup>®</sup> Advanced CMOS Technology
- **3.3V LOW VOLTAGE 22V10 ARCHITECTURE**
  - JEDEC-Compatible 3.3V Interface Standard
  - 5V Tolerant Inputs and I/O
  - I/O Interfaces with Standard 5V TTL Devices
- **ACTIVE PULL-UPS ON ALL LOGIC INPUT AND I/O PINS**
- **COMPATIBLE WITH STANDARD 22LV10/22V10 DEVICES**
  - Function/Fuse-Map Compatible with 22LV10/22V10 Devices
  - Parametric Compatible with 22LV10
- **E<sup>2</sup> CELL TECHNOLOGY**
  - In-System Programmable Logic
  - 100% Tested/100% Yields
  - High Speed Electrical Erasure (<100ms)
  - 20 Year Data Retention
- **APPLICATIONS INCLUDE:**
  - DMA Control
  - State Machine Control
  - High Speed Graphics Processing
  - Software-Driven Hardware Configuration
- **ELECTRONIC SIGNATURE FOR IDENTIFICATION**

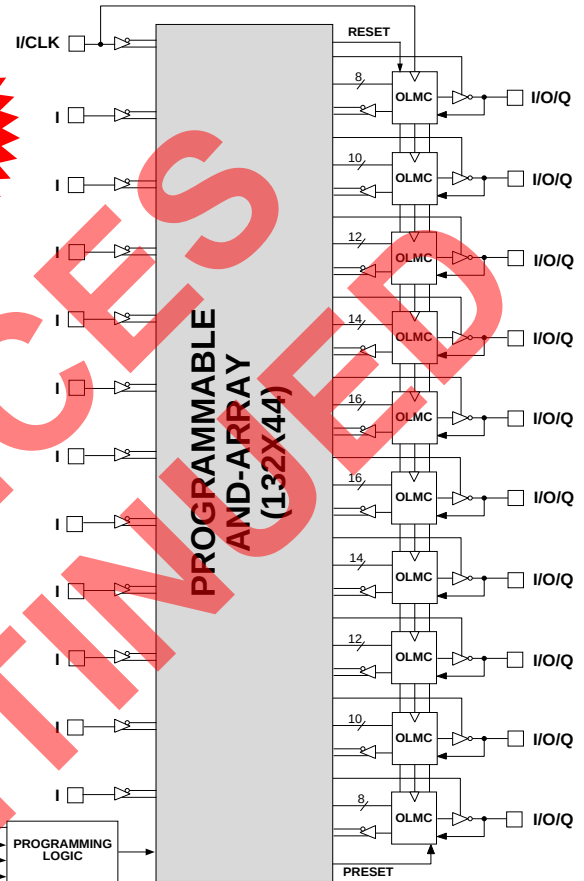
## Description

The ispGAL22LV10 is manufactured using Lattice Semiconductor's advanced 3.3V E<sup>2</sup>CMOS process, which combines CMOS with Electrically Erasable (E<sup>2</sup>) floating gate technology. The ispGAL22LV10 can interface with both 3.3V and 5V signal levels.

The ispGAL22LV10 is fully function/fuse map compatible with the GAL<sup>®</sup>22LV10 and GAL22V10. Further, the ispGAL22LV10 is parametric compatible with the GAL22LV10. The ispGAL22LV10 also shares the same 28-pin PLCC package pin-out as the GAL22LV10.

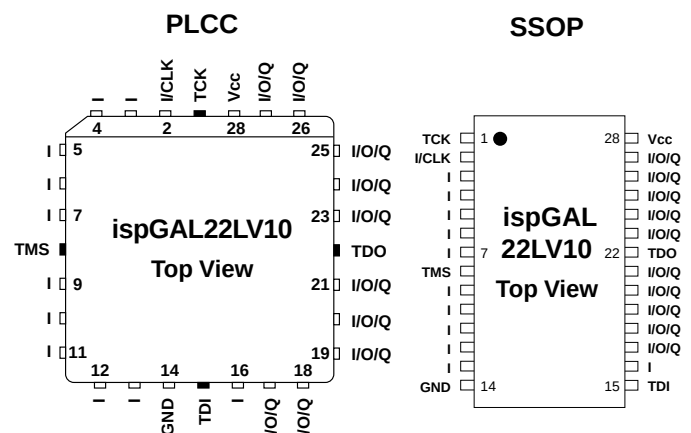
Unique test circuitry and reprogrammable cells allow complete AC, DC, and functional testing during manufacture. As a result, Lattice Semiconductor delivers 100% field programmability and functionality of all GAL products. In addition, 10,000 erase/write cycles and data retention in excess of 20 years are specified.

## Functional Block Diagram



**New  
4ns  
Speed  
Grade**

## Pin Configuration



Copyright © 1999 Lattice Semiconductor Corp. All brand or product names are trademarks or registered trademarks of their respective holders. The specifications and information herein are subject to change without notice.

LATTICE SEMICONDUCTOR CORP., 5555 Northeast Moore Ct., Hillsboro, Oregon 97124, U.S.A.  
Tel. (503) 268-8000; 1-800-LATTICE; FAX (503) 268-8556; <http://www.latticesemi.com>

**December 1999**

## Ordering Information

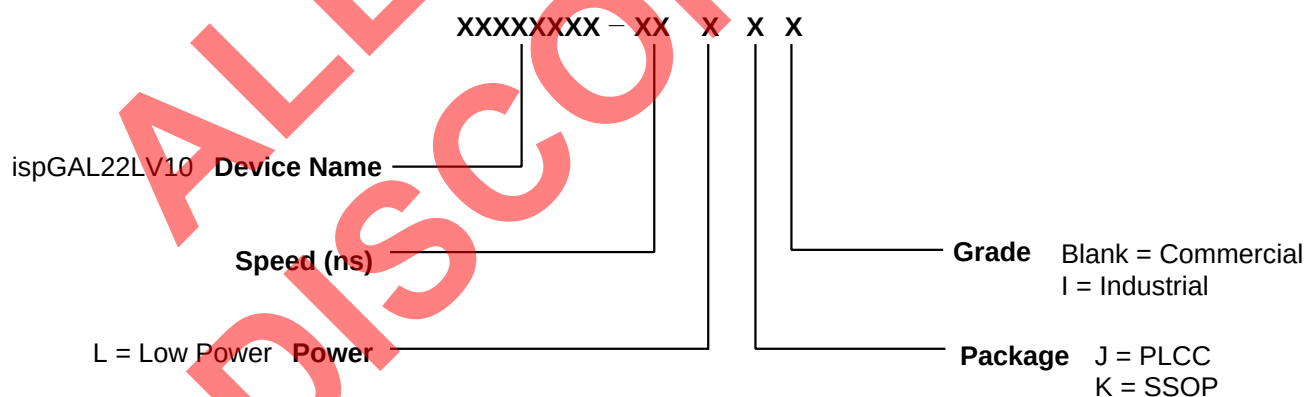
### Commercial Grade Specifications

| Tpd (ns) | Tsu (ns) | Tco (ns) | Icc (mA) | Ordering #        | Package      |
|----------|----------|----------|----------|-------------------|--------------|
| 4        | 3        | 3        | 130      | ispGAL22LV10-4LJ  | 28-Lead PLCC |
|          |          |          |          | ispGAL22LV10-4LK  | 28-Lead SSOP |
| 5        | 3.5      | 3.5      | 130      | ispGAL22LV10-5LJ  | 28-Lead PLCC |
|          |          |          |          | ispGAL22LV10-5LK  | 28-Lead SSOP |
| 7.5      | 5        | 5        | 130      | ispGAL22LV10-7LJ  | 28-Lead PLCC |
|          |          |          |          | ispGAL22LV10-7LK  | 28-Lead SSOP |
| 10       | 7        | 6.5      | 130      | ispGAL22LV10-10LJ | 28-Lead PLCC |
|          |          |          |          | ispGAL22LV10-10LK | 28-Lead SSOP |
| 15       | 10       | 8        | 130      | ispGAL22LV10-15LJ | 28-Lead PLCC |
|          |          |          |          | ispGAL22LV10-15LK | 28-Lead SSOP |

### Industrial Grade Specifications

| Tpd (ns) | Tsu (ns) | Tco (ns) | Icc (mA) | Ordering #         | Package      |
|----------|----------|----------|----------|--------------------|--------------|
| 7.5      | 5        | 5        | 160      | ispGAL22LV10-7LJI  | 28-Lead PLCC |
|          |          |          |          | ispGAL22LV10-7LKI  | 28-Lead SSOP |
| 10       | 7        | 6.5      | 160      | ispGAL22LV10-10LJI | 28-Lead PLCC |
|          |          |          |          | ispGAL22LV10-10LKI | 28-Lead SSOP |
| 15       | 10       | 8        | 160      | ispGAL22LV10-15LJI | 28-Lead PLCC |
|          |          |          |          | ispGAL22LV10-15LKI | 28-Lead SSOP |

## Part Number Description



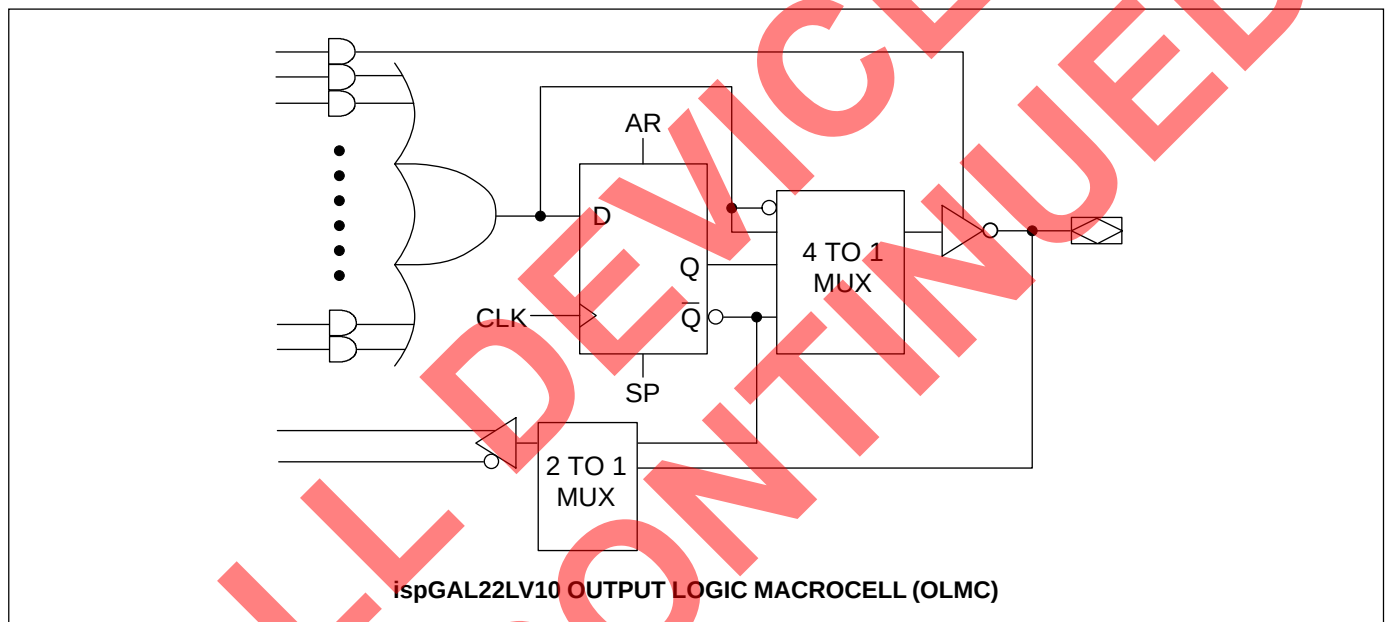
## Output Logic Macrocell (OLMC)

The ispGAL22LV10 has a variable number of product terms per OLMC. Of the ten available OLMCs, two OLMCs have access to eight product terms (pins 17 and 27), two have ten product terms (pins 18 and 26), two have twelve product terms (pins 19 and 25), two have fourteen product terms (pins 20 and 24), and two OLMCs have sixteen product terms (pins 21 and 23). In addition to the product terms available for logic, each OLMC has an additional product-term dedicated to output enable control.

The output polarity of each OLMC can be individually programmed to be true or inverting, in either combinatorial or registered mode. This allows each output to be individually configured as either active high or active low.

The ispGAL22LV10 has a product term for Asynchronous Reset (AR) and a product term for Synchronous Preset (SP). These two product terms are common to all registered OLMCs. The Asynchronous Reset sets all registers to zero any time this dedicated product term is asserted. The Synchronous Preset sets all registers to a logic one on the rising edge of the next clock pulse after this product term is asserted.

NOTE: The AR and SP product terms will force the Q output of the flip-flop into the same state regardless of the polarity of the output. Therefore, a reset operation, which sets the register output to a zero, may result in either a high or low at the output pin, depending on the pin polarity chosen.



## Output Logic Macrocell Configurations

Each of the Macrocells of the ispGAL22LV10 has two primary functional modes: registered, and combinatorial I/O. The modes and the output polarity are set by two bits (S0 and S1), which are normally controlled by the logic compiler. Each of these two primary modes, and the bit settings required to enable them, are described below and on the following page.

### REGISTERED

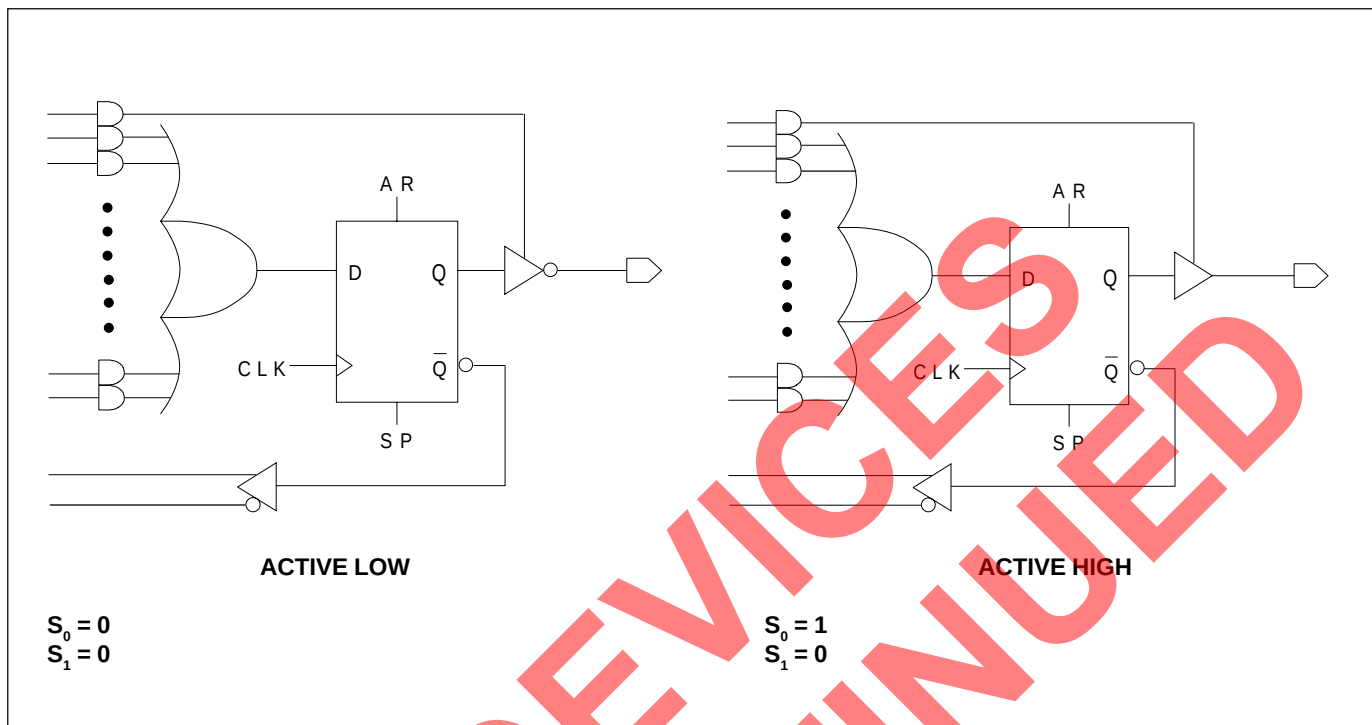
In registered mode the output pin associated with an individual OLMC is driven by the Q output of that OLMC's D-type flip-flop. Logic polarity of the output signal at the pin may be selected by specifying that the output buffer drive either true (active high) or inverted (active low). Output tri-state control is available as an individual product-term for each OLMC, and can therefore be defined by a logic equation. The D flip-flop's /Q output is fed back into the AND array, with both the true and complement of the feedback available as inputs to the AND array.

NOTE: In registered mode, the feedback is from the /Q output of the register, and not from the pin; therefore, a pin defined as registered is an output only, and cannot be used for dynamic I/O, as can the combinatorial pins.

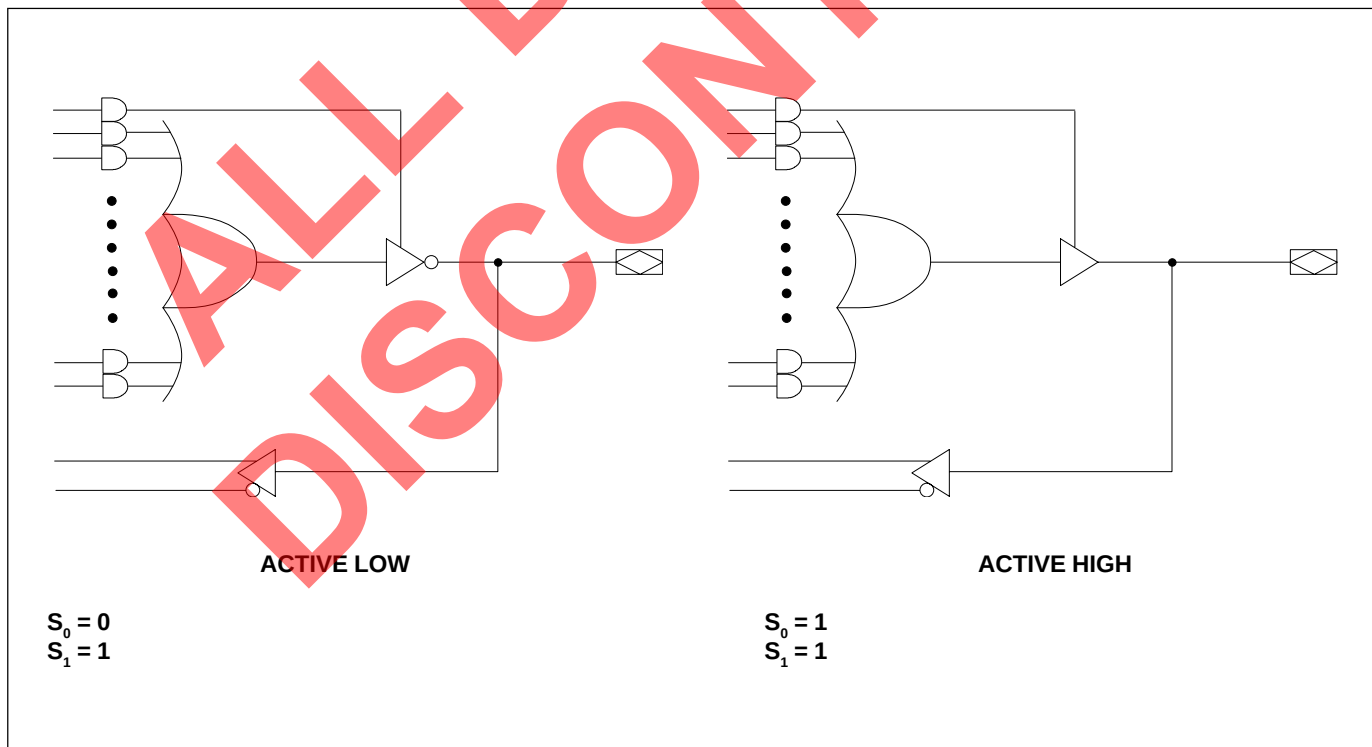
### COMBINATORIAL I/O

In combinatorial mode the pin associated with an individual OLMC is driven by the output of the sum term gate. Logic polarity of the output signal at the pin may be selected by specifying that the output buffer drive either true (active high) or inverted (active low). Output tri-state control is available as an individual product-term for each output, and may be individually set by the compiler as either "on" (dedicated output), "off" (dedicated input), or "product-term driven" (dynamic I/O). Feedback into the AND array is from the pin side of the output enable buffer. Both polarities (true and inverted) of the pin are fed back into the AND array.

## Registered Mode

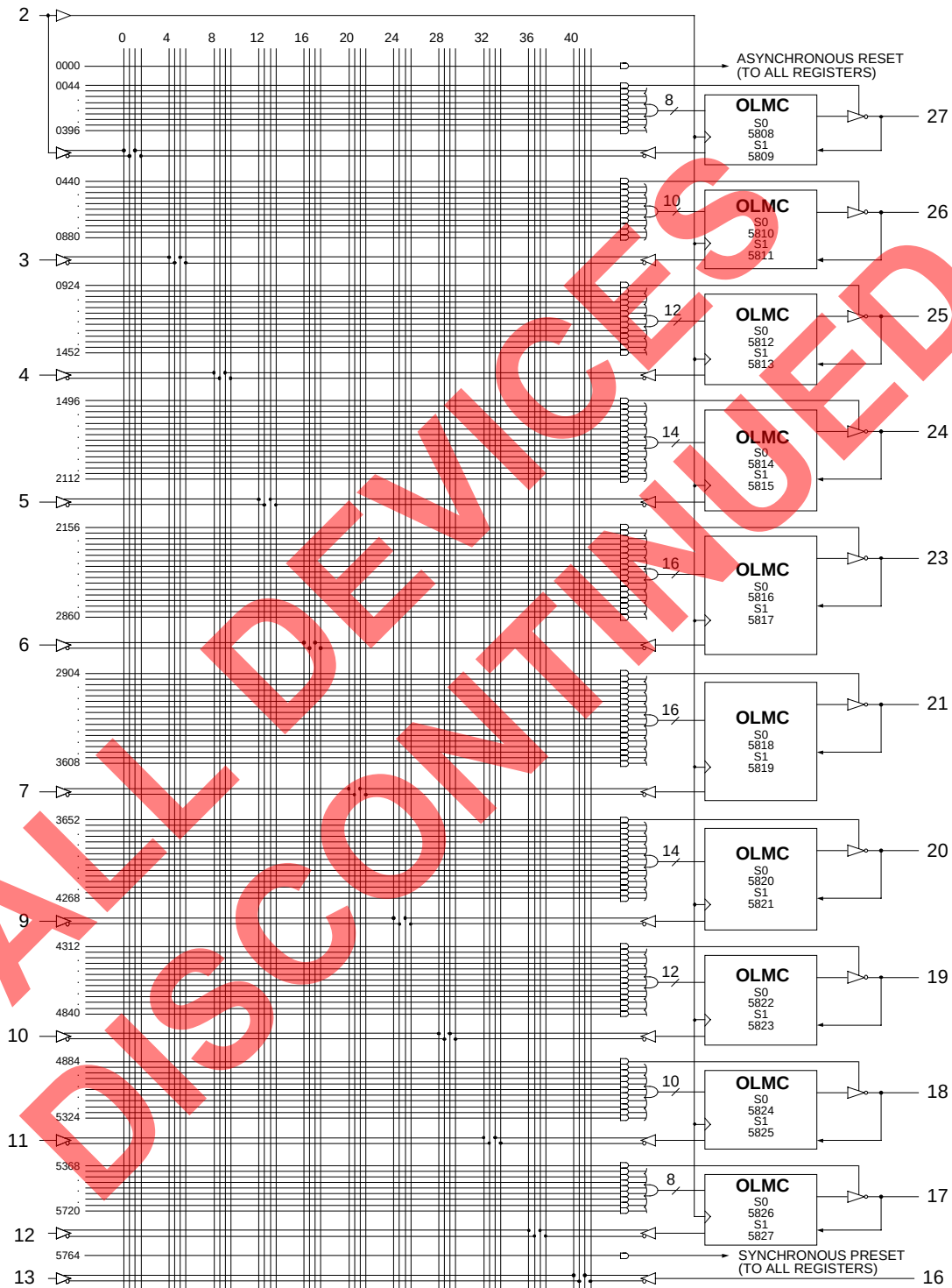


## Combinatorial Mode



**ispGAL22LV10 Logic Diagram/JEDEC Fuse Map**

**PLCC & SSOP Package Pinout**



|                                                    |        |        |        |        |        |        |
|----------------------------------------------------|--------|--------|--------|--------|--------|--------|
| 5828, 5829 ... Electronic Signature ... 5890, 5891 |        |        |        |        |        |        |
| Byte 7                                             | Byte 6 | Byte 5 | Byte 4 | Byte 3 | Byte 2 | Byte 1 |
| Byte 0                                             |        |        |        |        |        |        |
| M                                                  | L      |        |        |        |        |        |
| S                                                  | S      |        |        |        |        |        |
| B                                                  | B      |        |        |        |        |        |

## Absolute Maximum Ratings<sup>(1)</sup>

Supply voltage  $V_{CC}$  ..... -0.5 to +4.6V  
 Input and I/O voltage applied ..... -0.5 to +5.6V  
 Off-state output voltage applied ..... -0.5 to +4.6V  
 Storage Temperature ..... -65 to 150°C  
 Ambient Temperature with

Power Applied ..... -55 to 125°C

1. Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

## Recommended Operating Conditions

### Commercial Devices:

Ambient Temperature ( $T_A$ ) ..... 0 to 75°C

Supply voltage ( $V_{CC}$ )

with Respect to Ground ..... +3.0 to +3.6V

### Industrial Devices:

Ambient Temperature ( $T_A$ ) ..... -40 to 85°C

Supply voltage ( $V_{CC}$ )

with Respect to Ground ..... +3.0 to +3.6V

## DC Electrical Characteristics

Over Recommended Operating Conditions (Unless Otherwise Specified)

| SYMBOL       | PARAMETER                         | CONDITION                                                     | MIN.            | TYP. <sup>3</sup> | MAX. | UNITS   |
|--------------|-----------------------------------|---------------------------------------------------------------|-----------------|-------------------|------|---------|
| $V_{IL}$     | Input Low Voltage                 |                                                               | $V_{SS} - 0.3$  | —                 | 0.8  | V       |
| $V_{IH}$     | Input or I/O High Voltage         |                                                               | 2.0             | —                 | 5.25 | V       |
| $I_{IL}^1$   | Input or I/O Low Leakage Current  | $0V \leq V_{IN} \leq V_{IL} (MAX.)$                           | —               | —                 | -150 | $\mu A$ |
| $I_{IH}$     | Input or I/O High Leakage Current | $(V_{CC} - 0.2)V \leq V_{IN} \leq V_{CC}$                     | —               | —                 | 10   | $\mu A$ |
|              | Input or I/O High Leakage Current | $V_{CC} \leq V_{IN} \leq 5.25V$                               | —               | —                 | 2    | mA      |
| $V_{OL}$     | Output Low Voltage                | $I_{OL} = MAX. \quad V_{IN} = V_{IL} \text{ or } V_{IH}$      | —               | —                 | 0.4  | V       |
|              |                                   | $I_{OL} = 500\mu A \quad V_{IN} = V_{IL} \text{ or } V_{IH}$  | —               | —                 | 0.2  | V       |
| $V_{OH}$     | Output High Voltage               | $I_{OH} = MAX. \quad V_{IN} = V_{IL} \text{ or } V_{IH}$      | 2.4             | —                 | —    | V       |
|              |                                   | $I_{OH} = -100\mu A \quad V_{IN} = V_{IL} \text{ or } V_{IH}$ | $V_{CC} - 0.2V$ | —                 | —    | V       |
| $I_{OL}$     | Low Level Output Current          |                                                               | —               | —                 | 8    | mA      |
| $I_{OL-ISP}$ | Low Level Output Current TDO      |                                                               | —               | —                 | 4    | mA      |
| $I_{OH}$     | High Level Output Current         |                                                               | —               | —                 | -8   | mA      |
| $I_{OH-ISP}$ | High Level Output Current TDO     |                                                               | —               | —                 | -2   | mA      |
| $I_{OS}^2$   | Output Short Circuit Current      | $V_{CC} = 3.3V \quad V_{OUT} = 0.5V \quad T_A = 25^\circ C$   | -30             | —                 | -80  | mA      |

### COMMERCIAL

|          |                                |                                                                                                 |   |    |     |    |
|----------|--------------------------------|-------------------------------------------------------------------------------------------------|---|----|-----|----|
| $I_{CC}$ | Operating Power Supply Current | $V_{IL} = 0V \quad V_{IH} = 3.0V$ Unused Inputs at $V_{IL}$<br>$f_{toggle} = 1MHz$ Outputs Open | — | 90 | 130 | mA |
|----------|--------------------------------|-------------------------------------------------------------------------------------------------|---|----|-----|----|

### INDUSTRIAL

|          |                                |                                                                                                 |   |    |     |    |
|----------|--------------------------------|-------------------------------------------------------------------------------------------------|---|----|-----|----|
| $I_{CC}$ | Operating Power Supply Current | $V_{IL} = 0V \quad V_{IH} = 3.0V$ Unused Inputs at $V_{IL}$<br>$f_{toggle} = 1MHz$ Outputs Open | — | 90 | 160 | mA |
|----------|--------------------------------|-------------------------------------------------------------------------------------------------|---|----|-----|----|

1) The leakage current is due to the internal pull-up resistor on all pins. See **Input Buffer** section for more information.

2) One output at a time for a maximum duration of one second.  $V_{out} = 0.5V$  was selected to avoid test problems caused by tester ground degradation. Characterized but not 100% tested.

3) Typical values are at  $V_{CC} = 3.3V$  and  $T_A = 25^\circ C$

## AC Switching Characteristics

Over Recommended Operating Conditions

|                               |                          |                                                               | COM  |      | COM  |      | COM/IND |      | COM/IND |      | COM/IND |      |       |
|-------------------------------|--------------------------|---------------------------------------------------------------|------|------|------|------|---------|------|---------|------|---------|------|-------|
| PARAM.                        | TEST COND <sup>1</sup> . | DESCRIPTION                                                   | -4   |      | -5   |      | -7      |      | -10     |      | -15     |      | UNITS |
|                               |                          |                                                               | MIN. | MAX. | MIN. | MAX. | MIN.    | MAX. | MIN.    | MAX. | MIN.    | MAX. |       |
| t <sub>pd</sub> <sup>2</sup>  | A                        | Input or I/O to Comb. Output                                  | 1    | 4    | 1    | 5    | 1       | 7.5  | 1       | 10   | 1       | 15   | ns    |
| t <sub>co</sub> <sup>2</sup>  | A                        | Clock to Output Delay                                         | 1    | 3    | 1    | 3.5  | 1       | 5    | 1       | 6.5  | —       | 8    | ns    |
| t <sub>cf</sub> <sup>3</sup>  | —                        | Clock to Feedback Delay                                       | —    | 2.5  | —    | 2.5  | —       | 2.5  | —       | 2.5  | —       | 2.5  | ns    |
| t <sub>su</sub>               | —                        | Setup Time, Input or Fdbk before Clk↑                         | 3    | —    | 3.5  | —    | 5       | —    | 7       | —    | 10      | —    | ns    |
| t <sub>h</sub>                | —                        | Hold Time, Input or Fdbk after Clk↑                           | 0    | —    | 0    | —    | 0       | —    | 0       | —    | 0       | —    | ns    |
| f <sub>max</sub> <sup>4</sup> | A                        | Maximum Clock Frequency with External Feedback, 1/(tsu + tco) | 167  | —    | 143  | —    | 100     | —    | 74      | —    | 55.5    | —    | MHz   |
|                               | A                        | Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf) | 182  | —    | 166  | —    | 133     | —    | 105     | —    | 80      | —    | MHz   |
|                               | A                        | Maximum Clock Frequency with No Feedback                      | 250  | —    | 200  | —    | 166     | —    | 111     | —    | 83.3    | —    | MHz   |
| t <sub>wh</sub> <sup>4</sup>  | —                        | Clock Pulse Duration, High                                    | 2    | —    | 2.5  | —    | 3       | —    | 4       | —    | 6       | —    | ns    |
| t <sub>wl</sub> <sup>4</sup>  | —                        | Clock Pulse Duration, Low                                     | 2    | —    | 2.5  | —    | 3       | —    | 4       | —    | 6       | —    | ns    |
| t <sub>en</sub>               | B                        | Input or I/O to Output Enabled                                | 1    | 5    | 1    | 6    | 1       | 7.5  | 1       | 10   | —       | 15   | ns    |
| t <sub>dis</sub>              | C                        | Input or I/O to Output Disabled                               | 1    | 5    | 1    | 6    | 1       | 7.5  | 1       | 10   | —       | 15   | ns    |
| t <sub>ar</sub>               | A                        | Input or I/O to Asynch. Reset of Reg.                         | 1    | 4.5  | 1    | 5.5  | 1       | 9    | 1       | 13   | —       | 20   | ns    |
| t <sub>arw</sub>              | —                        | Asynchronous Reset Pulse Duration                             | 4.5  | —    | 5.5  | —    | 7       | —    | 8       | —    | 15      | —    | ns    |
| t <sub>arr</sub>              | —                        | Asynch. Reset to Clk↑ Recovery Time                           | 3.5  | —    | 4    | —    | 5       | —    | 8       | —    | 10      | —    | ns    |
| t <sub>spr</sub>              | —                        | Synch. Preset to Clk↑ Recovery Time                           | 3.5  | —    | 4    | —    | 5       | —    | 10      | —    | 10      | —    | ns    |

1) Refer to **Switching Test Conditions** section.

2) Minimum values for **t<sub>pd</sub>** and **t<sub>co</sub>** are not 100% tested but established by characterization.

3) Calculated from **f<sub>max</sub>** with internal feedback. Refer to **f<sub>max</sub> Descriptions** section.

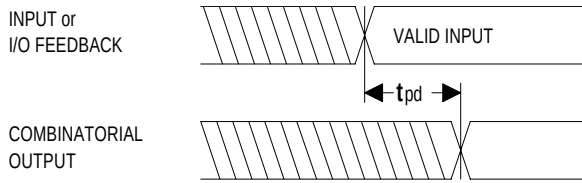
4) Refer to **f<sub>max</sub> Descriptions** section. Characterized but not 100% tested.

Note: Maximum clock input rise and fall time between 10% to 90% of V<sub>out</sub> = 2ns.

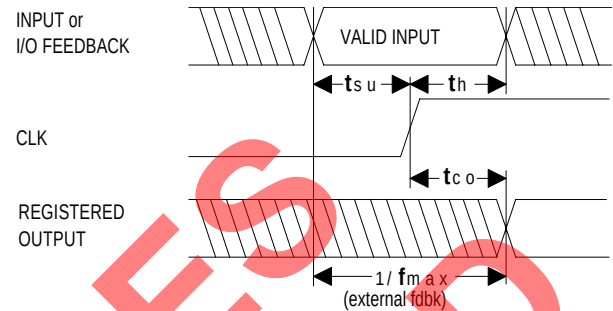
## Capacitance (TA = 25°C, f = 1.0 MHz)

| SYMBOL           | PARAMETER         | TYPICAL | UNITS | TEST CONDITIONS                               |
|------------------|-------------------|---------|-------|-----------------------------------------------|
| C <sub>I</sub>   | Input Capacitance | 4       | pF    | V <sub>CC</sub> = 3.3V, V <sub>I</sub> = 0V   |
| C <sub>I/O</sub> | I/O Capacitance   | 5       | pF    | V <sub>CC</sub> = 3.3V, V <sub>I/O</sub> = 0V |

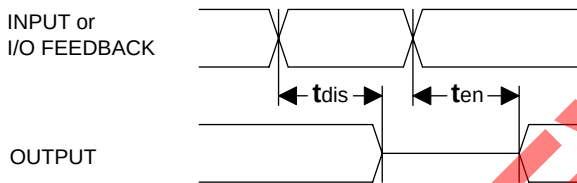
## Switching Waveforms



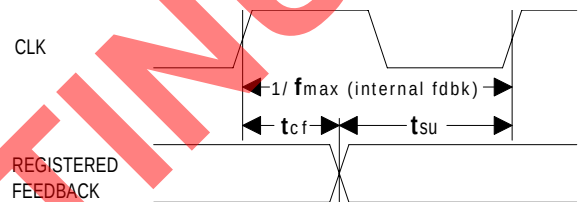
**Combinatorial Output**



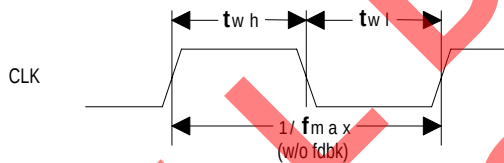
**Registered Output**



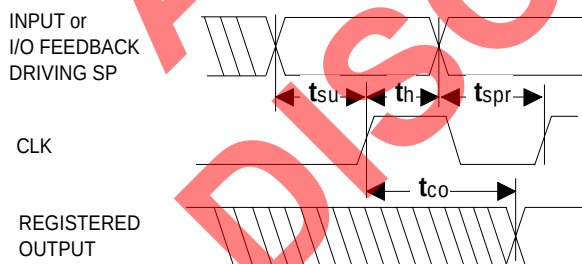
**Input or I/O to Output Enable/Disable**



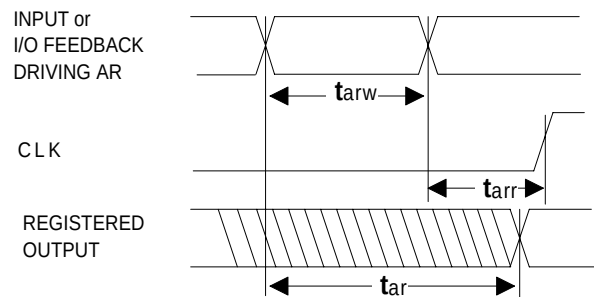
**$f_{max}$  with Feedback**



**Clock Width**



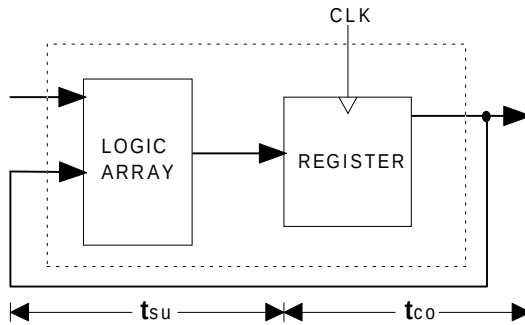
**Synchronous Preset**



**Asynchronous Reset**

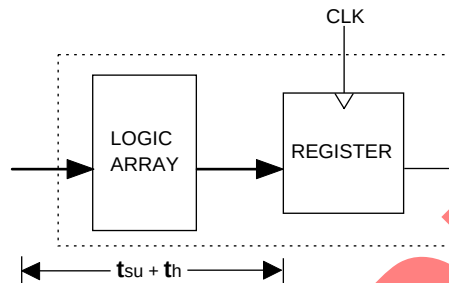


## f<sub>max</sub> Descriptions



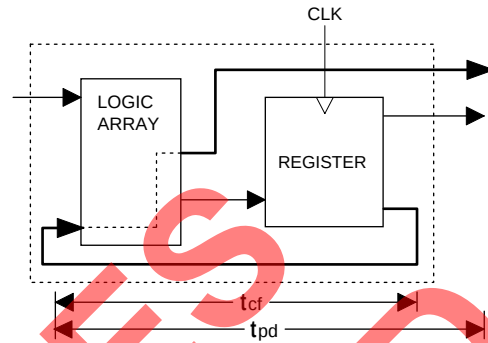
### f<sub>max</sub> with External Feedback $1/(t_{su}+t_{co})$

**Note:** f<sub>max</sub> with external feedback is calculated from measured t<sub>su</sub> and t<sub>co</sub>.



### f<sub>max</sub> with No Feedback

**Note:** f<sub>max</sub> with no feedback may be less than  $1/t_{wh} + t_{wl}$ . This is to allow for a clock duty cycle of other than 50%.



### f<sub>max</sub> with Internal Feedback $1/(t_{su}+t_{cf})$

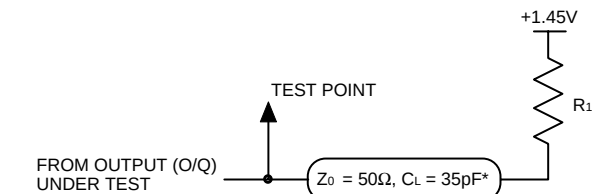
**Note:** t<sub>cf</sub> is a calculated value, derived by subtracting t<sub>su</sub> from the period of f<sub>max</sub> w/internal feedback ( $t_{cf} = 1/f_{max} - t_{su}$ ). The value of t<sub>cf</sub> is used primarily when calculating the delay from clocking a register to a combinatorial output (through registered feedback), as shown above. For example, the timing from clock to a combinatorial output is equal to t<sub>cf</sub> + t<sub>pd</sub>.

## Switching Test Conditions

|                                |                 |
|--------------------------------|-----------------|
| Input Pulse Levels             | GND to 3.0V     |
| Input Rise and Fall Times      | 1.5ns 10% – 90% |
| Input Timing Reference Levels  | 1.5V            |
| Output Timing Reference Levels | 1.5V            |
| Output Load                    | See Figure      |

### Output Load Conditions (see figure)

| Test Condition | R <sub>1</sub> | C <sub>L</sub> |
|----------------|----------------|----------------|
| A              | 50Ω            | 35pF           |
| B              | 50Ω            | 35pF           |
| B              | 50Ω            | 35pF           |
| C              | 50Ω            | 35pF           |
| C              | 50Ω            | 35pF           |



\*C<sub>L</sub> includes test fixture and probe capacitance.

## Electronic Signature

An electronic signature (ES) is provided in every ispGAL22LV10 device. It contains 64 bits of reprogrammable memory that can contain user-defined data. Some uses include user ID codes, revision numbers, or inventory control. The signature data is always available to the user independent of the state of the security cell.

The electronic signature is an additional feature not present in other manufacturers' 22V10 devices. To use the extra feature of the user-programmable electronic signature it is necessary to choose a Lattice Semiconductor 22V10 device type when compiling a set of logic equations. In addition, many device programmers have two separate selections for the device, typically an ispGAL22LV10 and a ispGAL22LV10-UES (UES = User Electronic Signature) or ispGAL22LV10-ES. This allows users to maintain compatibility with existing 22V10 designs, while still having the option to use the GAL device's extra feature.

The JEDEC map for the ispGAL22LV10 contains the 64 extra fuses for the electronic signature, for a total of 5892 fuses. However, the ispGAL22LV10 device can still be programmed with a standard 22V10 JEDEC map (5828 fuses) with any qualified device programmer.

## Security Cell

A security cell is provided in every ispGAL22LV10 device to prevent unauthorized copying of the array patterns. Once programmed, this cell prevents further read access to the functional bits in the device. This cell can only be erased by re-programming the device, so the original configuration can never be examined once this cell is programmed. The Electronic Signature is always available to the user, regardless of the state of this control cell.

## Latch-Up Protection

ispGAL22LV10 devices are designed with an on-board charge pump to negatively bias the substrate. The negative bias is of sufficient magnitude to prevent input undershoots from causing the circuitry to latch.

## Device Programming

The ispGAL22LV10 device uses a standard 22V10 JEDEC fusemap file to describe the device programming information. Any third party logic compiler can produce the JEDEC file for this device.

## In-System Programmability

The ispGAL22LV10 device features In-System Programmable technology. By integrating all the high voltage programming circuitry on-chip, programming can be accomplished by simply shifting data into the device. Once the function is programmed, the non-volatile E<sup>2</sup>CMOS cells will not lose the pattern even when the power is turned off.

All necessary programming is done via four TTL level logic interface signals. These four signals are fed into the on-chip programming circuitry where a state machine controls the programming. The interface signals are Test Data In (TDI), Test Data Out (TDO), Test Clock (TCK) and Test Mode Select (TMS) control. For details on the operation of the internal state machine and programming of ispGAL22LV10 devices please refer to the ISP Architecture and Programming section in this Data Book.

## Output Register Preload

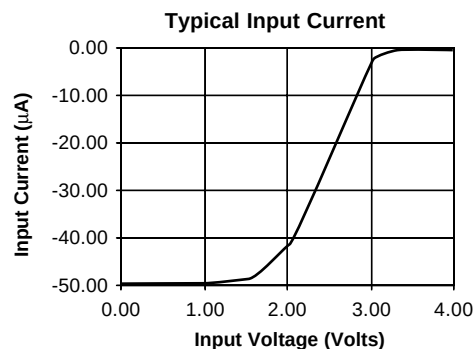
When testing state machine designs, all possible states and state transitions must be verified in the design, not just those required in the normal machine operations. This is because certain events may occur during system operation that throw the logic into an illegal state (power-up, line voltage glitches, brown-outs, etc.). To test a design for proper treatment of these conditions, a way must be provided to break the feedback paths, and force any desired (i.e., illegal) state into the registers. Then the machine can be sequenced and the outputs tested for correct next state conditions.

The ispGAL22LV10 device includes circuitry that allows each registered output to be synchronously set either high or low. Thus, any present state condition can be forced for test sequencing. If necessary, approved GAL programmers capable of executing test vectors perform output register preload automatically.

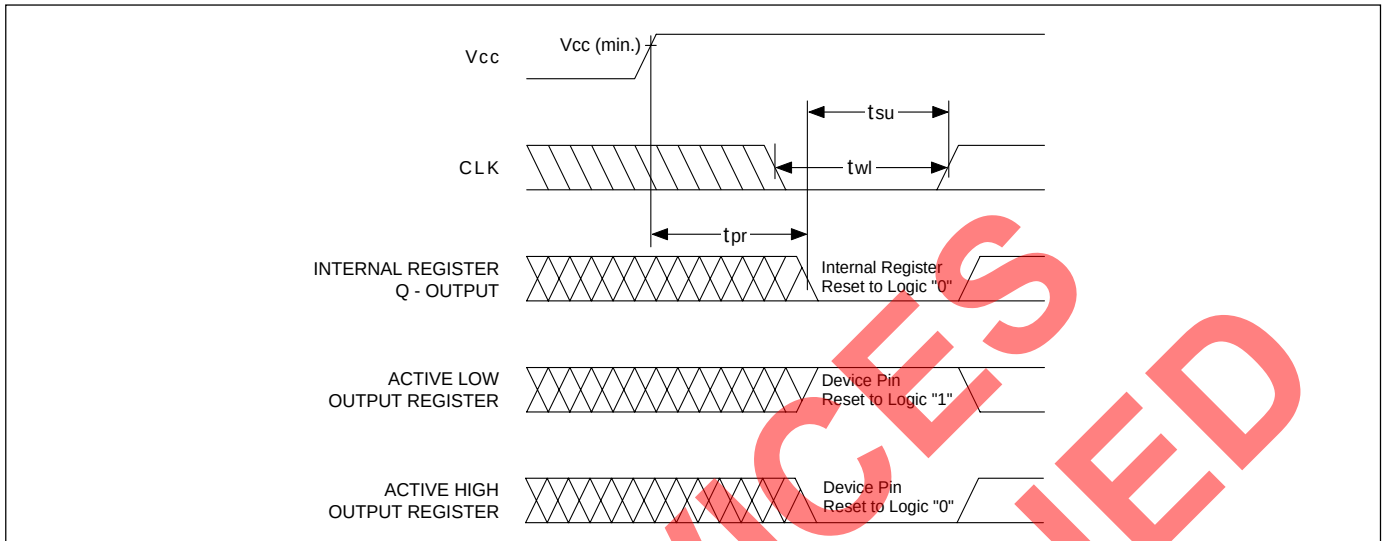
## Input Buffers

ispGAL22LV10 devices are designed with TTL level compatible input buffers. These buffers have a characteristically high impedance, and present a much lighter load to the driving logic than bipolar TTL devices.

All input and I/O pins also have built-in active pull-ups. As a result, floating inputs will float to a TTL high (logic 1). However, Lattice Semiconductor recommends that all unused inputs and tri-stated I/O pins be connected to an adjacent active input, Vcc, or ground. Doing so will tend to improve noise immunity and reduce Icc for the device. (See equivalent input and I/O schematics on the following page.)



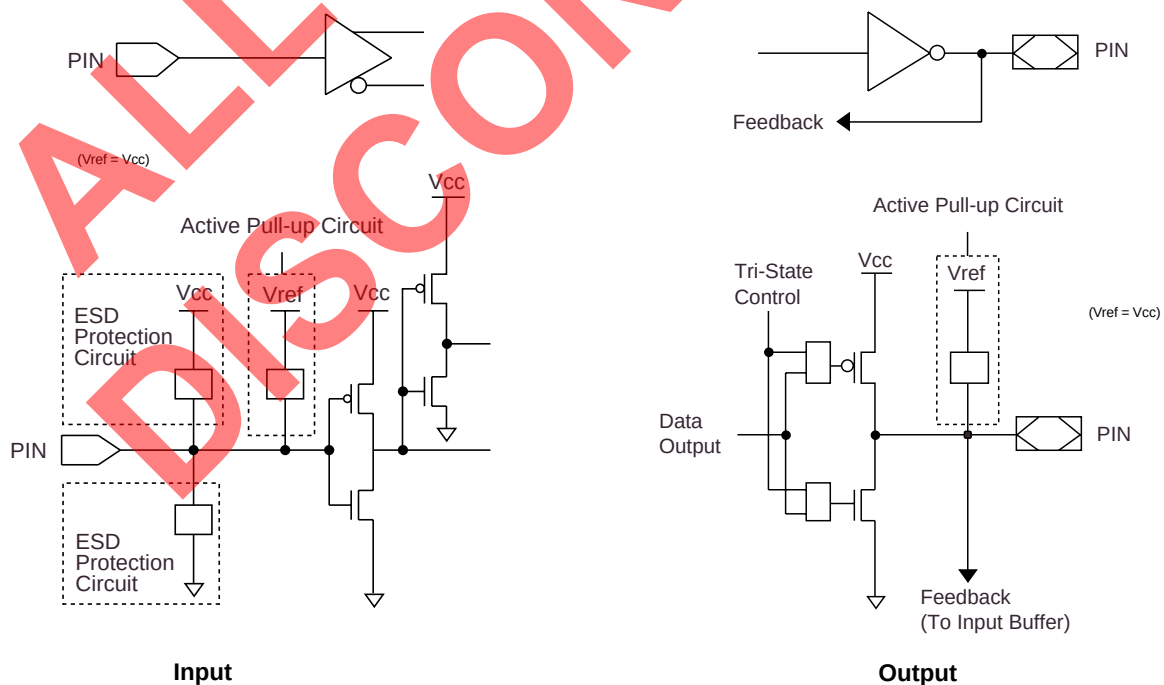
## Power-Up Reset



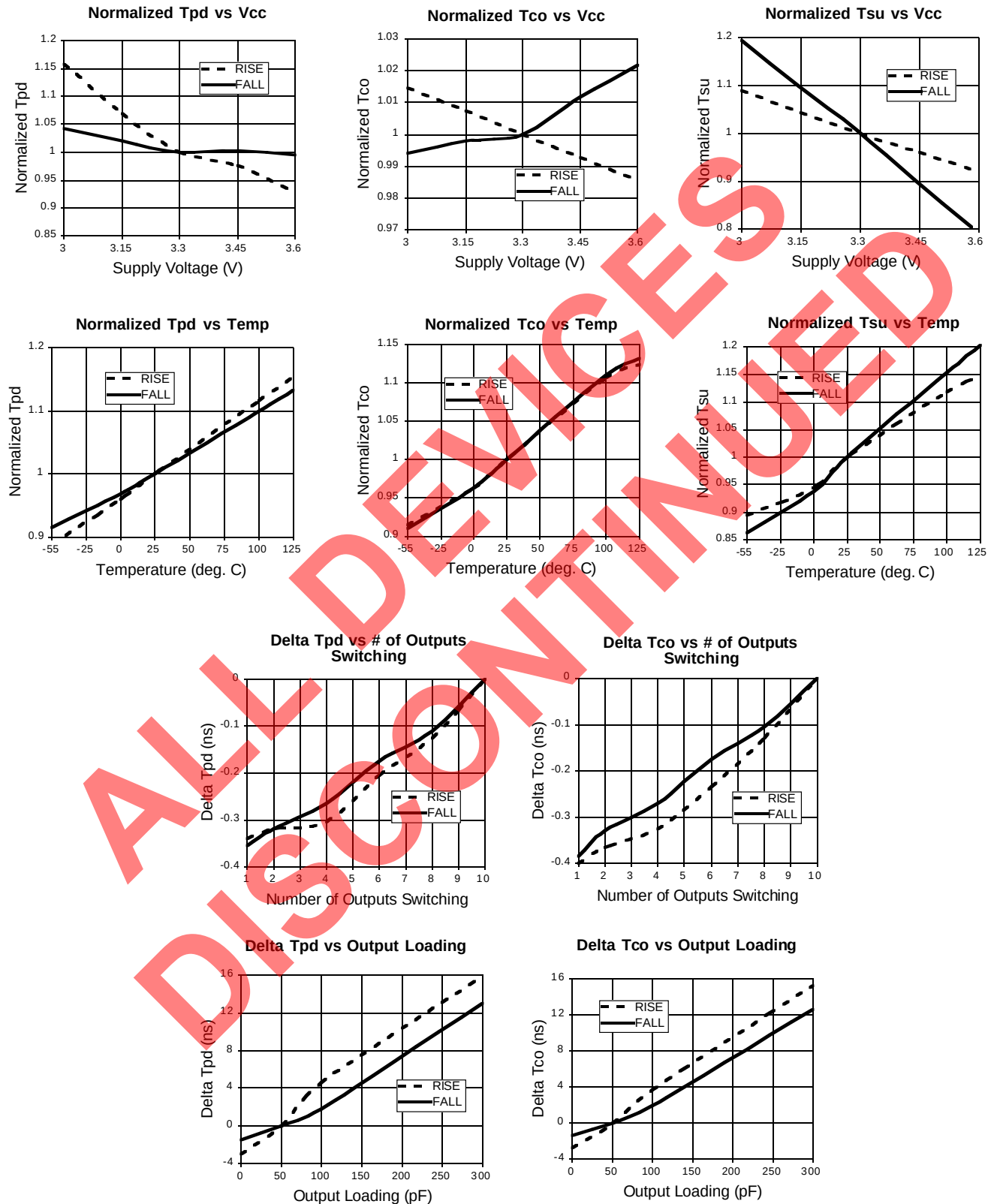
Circuitry within the ispGAL22LV10 provides a reset signal to all registers during power-up. All internal registers will have their Q outputs set low after a specified time ( $t_{pr}$ , 1 $\mu$ s MAX). As a result, the state on the registered output pins (if they are enabled) will be either high or low on power-up, depending on the programmed polarity of the output pins. This feature can greatly simplify state machine design by providing a known state on power-up. The timing diagram for power-up is shown above. Because of the asynchronous nature of system power-

up, some conditions must be met to provide a valid power-up reset of the ispGAL22LV10. First, the  $V_{CC}$  rise must be monotonic. Second, the clock input must be at static TTL level as shown in the diagram during power up. The registers will reset within a maximum of  $t_{pr}$  time. As in normal system operation, avoid clocking the device until all input and feedback path setup times have been met. The clock must also meet the minimum pulse width requirements.

## Input/Output Equivalent Schematics



**ispGAL22LV10: Typical AC and DC Characteristic Diagrams**



**ispGAL22LV10: Typical AC and DC Characteristic Diagrams**

