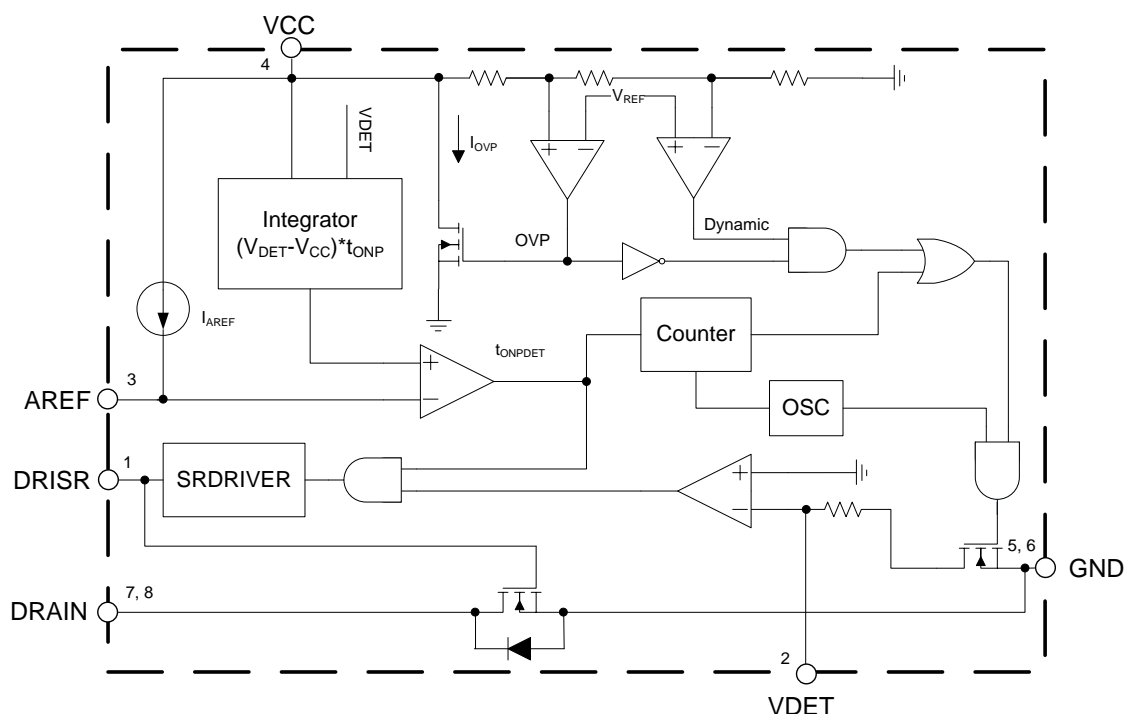


Pin Descriptions

Pin Number	Pin Name	Function
1	DRISR	Synchronous rectification MOSFET drive
2	VDET	Synchronous rectification sense input and dynamic function output, connected to DRAIN through a resistor
3	AREF	Program a voltage reference with a resistor from AREF to GND, to enable synchronous rectification MOSFET drive signal
4	VCC	Power supply, connected with system output
5, 6	GND	Source pin of internal MOSFET, connected to Ground
7, 8	DRAIN	Drain pin of internal MOSFET

Functional Block Diagram



Absolute Maximum Ratings (Note 4)

Symbol	Parameter	Value	Unit
V_{CC}	Supply Voltage	-0.3 to 7.5	V
V_{DET}, V_{DRAIN}	Voltage at VDET, DRAIN Pin	-2 to 50	V
V_{AREF}, V_{DRISR}	Voltage at AREF, DRISR Pin	-0.3 to 6	V
I_D	Continuous Drain Current	15	A
I_{DM}	Pulsed Drain Current	60	A
P_D	Power Dissipation at $T_A = +25^\circ\text{C}$	0.7	W
θ_{JA}	Thermal Resistance (Junction to Ambient) (Note 5)	170	$^\circ\text{C/W}$
θ_{JC}	Thermal Resistance (Junction to Case) (Note 5)	24	$^\circ\text{C/W}$
T_J	Operating Junction Temperature	+150	$^\circ\text{C}$
T_{STG}	Storage Temperature	-65 to +150	$^\circ\text{C}$
T_{LEAD}	Lead Temperature (Soldering, 10 sec)	+300	$^\circ\text{C}$

Notes: 4. Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "Recommended Operating Conditions" is not implied. Exposure to "Absolute Maximum Ratings" for extended periods may affect device reliability.

5. FR-4 substrate PC board, 2oz copper, with 1 inch² pad layout.

Recommended Operating Conditions

Symbol	Parameter	Min	Max	Unit
V_{CC}	Supply Voltage	3.3	6	V
T_A	Ambient Temperature	-40	+85	$^\circ\text{C}$

Electrical Characteristics (@T_A = +25°C, V_{CC} = 5V, unless otherwise specified.)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Supply Voltage (VCC Pin)						
I _{STARTUP}	Startup Current	V _{CC} =V _{STARTUP} -0.1V	–	100	150	μA
I _{OP}	Operating Current	V _{DET} pin floating V _{CC} =V _{TRIGGER} +20mV	40	100	150	μA
V _{STARTUP}	Startup Voltage	–	2.6	3.1	3.4	V
–	UVLO	–	2.3	2.8	3.1	V
Dynamic Output Section/Oscillator Section						
V _{TRIGGER}	Internal Trigger Voltage	–	5.05	5.1	5.15	V
–	Duty Cycle	–	4	15	18	%
t _{OSC}	Oscillation Period	V _{CC} =5V	18	30	37.5	μs
I _{TRIGGER}	Internal Trigger Current	V _{CC} =V _{TRIGGER} , V _{CC} /V _{DET} pin is separately connected to a 20Ω resistor	30	60	80	mA
t _{DIS}	Minimum Period	–	18	30	37.5	ms
V _{DIS}	Discharge Voltage	–	5.17	5.25	5.33	V
I _{DIS}	Discharge Current	V _{CC} =V _{DIS} +0.1V	1.5	3	4.5	mA
V _{DIS} -V _{TRIGGER}	Trigger Discharger Gap	–	30	110	–	mV
V _{OVP}	Overshoot Voltage for Discharge	–	5.58	5.68	5.78	V
I _{OVP}	Overshoot Current for Discharge	V _{CC} =V _{OVP} +0.1V, V _{CC} pin is connected to a 20Ω resistor	40	–	100	mA
Synchronous Voltage Detect						
V _{THON}	Gate Turn On Threshold	–	0	–	1	V
V _{THOFF}	Gate Turn Off Threshold	–	-20	-12.5	-5	mV
t _{DON}	Turn On Delay Time	From V _{THON} to V _{DRISR} =1V	–	70	130	ns
t _{DOFF}	Turn Off Propagation Delay Time	From V _{THOFF} to V _{DRISR} =3V	–	100	150	ns
I _{AREF}	Reference Current	–	–	18	–	μA
t _{RG}	Gate Turn On Rising Time	From 1V to 3V, C _L =4.7nF	–	50	100	ns
t _{FG}	Gate Turn Off Falling Time	From 3V to 1V, C _L =4.7nF	–	50	100	ns
t _{LEB_S}	Minimum On Time	–	0.9	1.8	2.7	μs
t _{LEB_L}		–	–	–	6.5	
V _{DRISR_HIGH}	Drive Output Voltage	V _{CC} =5V	3.7	–	–	V
V _{S_MIN}	SR Minimum Operating Voltage (Note 6)	–	–	–	4.5	V
t _{OVP_LAST}	Added OVP Discharge Time	–	–	2.0	–	ms
K _{qs}	(Note 7)	(V _{DET} -V _{CC})*t _{ONP} = 25Vμs	0.325	–	0.515	mA*μs

Notes: 6. This item specifies the minimum SR operating voltage of V_{IN_DC}, V_{IN_DC} ≥ N_{PS}*V_{S_MIN}.

7. This item is used to specify the value of R_{AREF}.

Electrical Characteristics (@T_A = +25°C, unless otherwise specified. Cont.)

MOSFET Static Characteristics

Parameters	Symbol	Conditions	Min	Typ	Max	Unit
Drain to Source Breakdown Voltage	V _{DSS(BR)}	V _{GS} =0V, I _D =0.25mA	50	–	–	V
Gate Threshold Voltage	V _{GS(TH)}	V _{DS} =V _{GS} , I _D =0.25mA	0.5	0.9	2	V
Zero Gate Voltage Drain Current	I _{DSS}	V _{DS} =50V, V _{GS} =0V	–	–	1	μA
Gate to Source Leakage Current	I _{GSS}	V _{GS} =±10V, V _{DS} =0V	–	–	±10	μA
Drain to Source On-state Resistance	R _{DS(ON)}	V _{GS} =4.5V, I _D =15A	12	15	30	mΩ

MOSFET Dynamic Characteristics

Parameters	Symbol	Conditions	Min	Typ	Max	Unit
Input Capacitance	C _{iss}	V _{GS} =0V, V _{DS} =25V, f=1MHz	–	1316	–	pF
Output Capacitance	C _{oss}		–	97	–	
Reverse Transfer Capacitance	C _{rss}		–	85	–	
Gate to Source Charge	Q _{gs}	V _{GS} =0V to 10V, V _{DD} =25V, I _D =15A	–	3.2	–	nC
Gate to Drain Charge (Miller Charger)	Q _{gd}		–	5.7	–	
Total Gate Charge	Q _g		–	15.2	–	
Gate Resistance	R _g	–	–	0.85	–	Ω

NEW PRODUCT



When the V_{CC} falls below the power-off voltage (V_{OFF}), the APR3415C will shut down.

MOSFET Driver

In the process of drain current decreasing linearly toward zero, the drain-source voltage rises synchronically. When it rises over the turn off threshold voltage V_{THOFF} , APR3415C pulls the drive signal down after a turn off delay (t_{DOFF}).



Operation Description (Cont.)

Minimum On Time

When the controlled MOSFET gate is turned on, some ringing noise is generated. The minimum on-time timer blanks the V_{THOFF} comparator, keeping the controlled MOSFET on for at least the minimum on time. If V_{THOFF} falls below the threshold before minimum on time expires, the MOSFET will keep on until the end of the minimum on time.

The minimum on time is in direct proportion to the $(V_{DET}-V_{CC}) \cdot t_{ONP}$. When $(V_{DET}-V_{CC}) \cdot t_{ONP} = 5V \cdot 5\mu s$, the minimum on time is about $1.8\mu s$.

The Value and Meaning of AREF Resistor

As to DCM operation Flyback converter, after secondary rectifier stop conduction the primary MOSFET Drain-to-source ringing waveform is resulted from the resonant of primary inductance and equivalent switch device output capacitance. This ringing waveform probably leads to Synchronous Rectifier error conduction. To avoid this fault happening, APR3415C has a special function design by means of volt-second product detecting. From the sensed voltage of V_{DET} pin to see, the volt-second product of voltage above V_{CC} at primary switch on time is much higher than the volt-second product of each cycle ringing voltage above V_{CC} . Therefore, before every time Synchronous Rectifier turning on, APR3415C judges if the detected volt-second product of V_{DET} voltage above V_{CC} is higher than a threshold and then turn on synchronous Rectifier. The purpose of AREF resistor is to determine the volt-second product threshold. APR3415C has a parameter, K_{qs} , which converts R_{AREF} value to volt-second product,

$$Area2 = R_{AREF} \cdot K_{qs}$$

In general, Area1 and Area3 value depend on system design and are always fixed after system design frozen. As to Diodes Incorporated's PSR design, the Area1 value changes with primary peak current value and Area3 value generally keeps constant at all conditions. So the AREF resistor design should consider the worst case, the minimum primary peak current condition. Since of system design parameter distribution, Area1 and Area3 have moderate tolerance. So Area2 should be designed between the middle of Area1 and Area3 to keep enough design margin.

$$Area3 < R_{AREF} \cdot K_{qs} < Area1$$

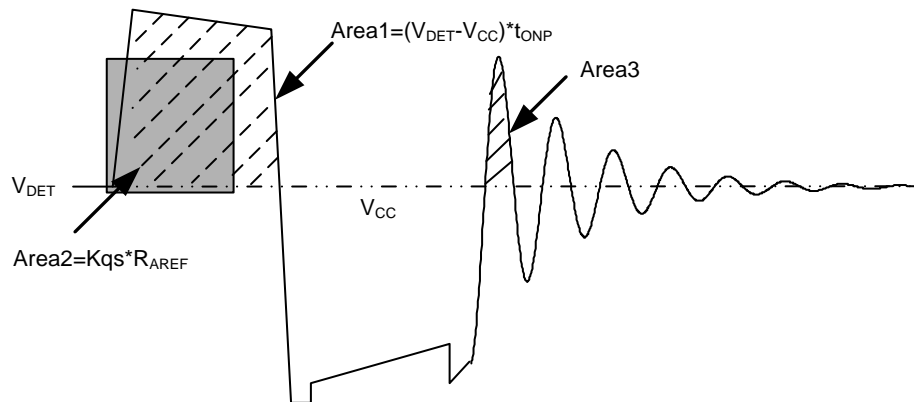


Figure 3. AREF Function

SR Minimum Operating Voltage

APR3415C sets a minimum SR operating voltage by comparing the difference between V_{DET} and output voltage (V_{CC}). The value of $V_{DET}-V_{CC}$ must be higher than its internal reference, then APR3415C will begin to integrate the area of $(V_{DET}-V_{CC}) \cdot t_{ONP}$. If not, the area integrating will not begin and the SR driver will be disabled.

SR Turning off Timing Impact on PSR CV Sampling

As to synchronous rectification on Flyback power system, SR MOSFET need to turn off in advance of secondary side current decreasing to zero to avoid current flowing reversely. When SR turns off in advance, the secondary current will flow through the body diode. The SR turning off time is determined by the V_{THOFF} at a fixed system. When V_{THOFF} is more close to zero, the SR turning on time gets longer and body diode conduction time gets shorter. Since of the different voltage drop between SR MOSFET and body diode, the PSR feedback signal V_{FB} appears a voltage jump at the time of SR MOSFET turning off. If the PSR CV sampling time t_{SAMPLE} is close to even behind this voltage jump time, there will be system unstable operation issue or the lower output voltage issue.

Operation Description (Cont.)

To ensure stable operating of system, it must be met:

$$t_{\text{BODYDIODE}} < t_{\text{ONS}} - t_{\text{SAMPLE}}$$

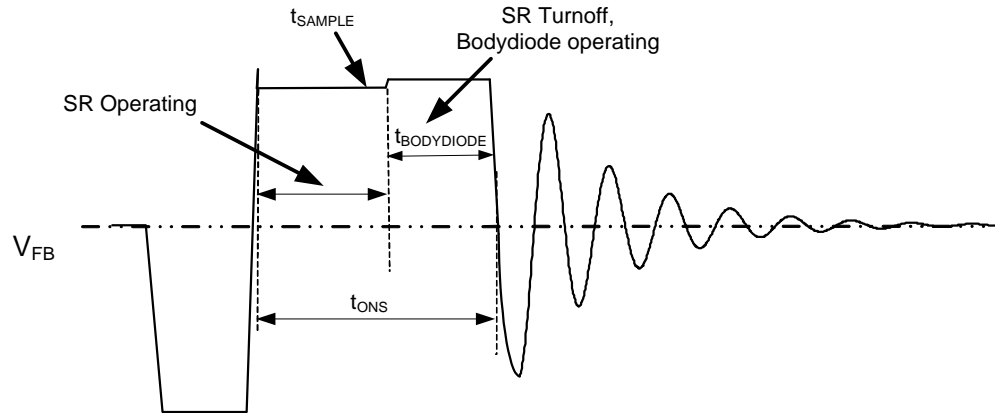


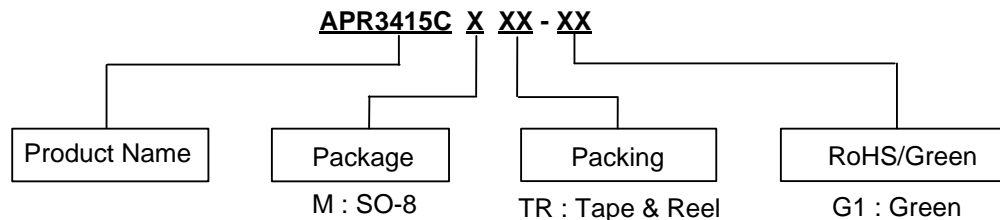
Figure 4. SR Turning off Timing Impact on PSR CV Sampling

Recommended Application Circuit Parameters

The two resistors R23 and R24 are used to pass ESD test. The value of R23 and R24 should be over 20Ω and below 47Ω respectively because of the undershoot performance. The package of R23 and R24 should be at least 0805 and there isn't any trace under these two resistors.

C_{AREF} is suggested to parallel with AREF resistor to keep the volt-second product threshold stable. And the recommended value of C_{AREF} is 20nF. The recommended value of C24 is 100nF.

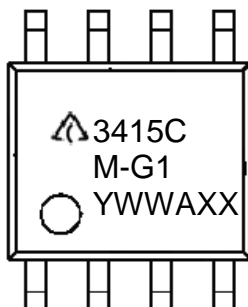
Ordering Information



Package	Temperature Range	Part Number	Marking ID	Packing
SO-8	-40 to +85°C	APR3415CMTR-G1	3415CM-G1	4000/Tape & Reel

Marking Information

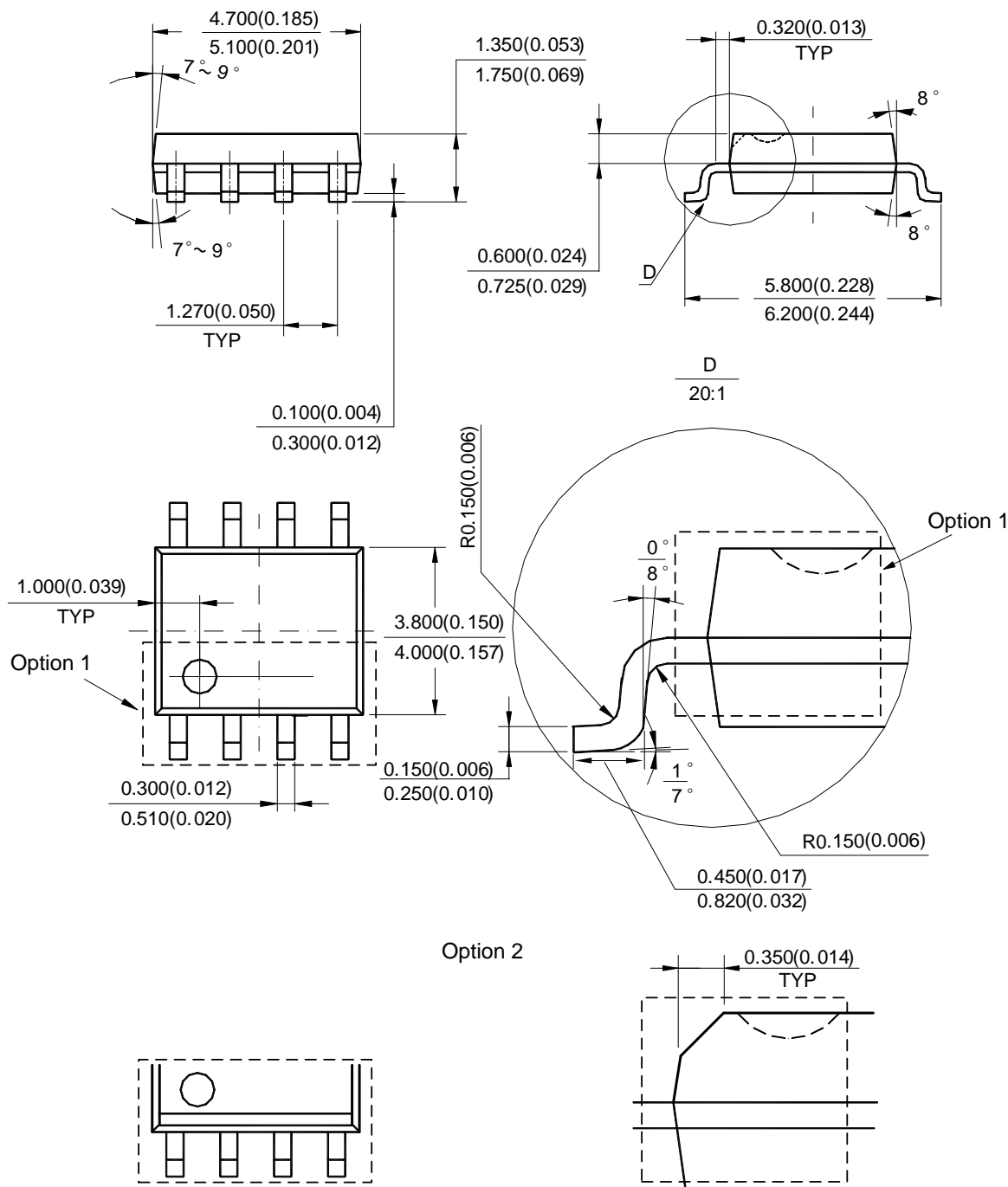
(Top View)



First and Second Lines: Logo and Marking ID
 Third Line: Date Code
 Y: Year
 WW: Work Week of Molding
 A: Assembly House Code
 XX: 7th and 8th Digits of Batch No.

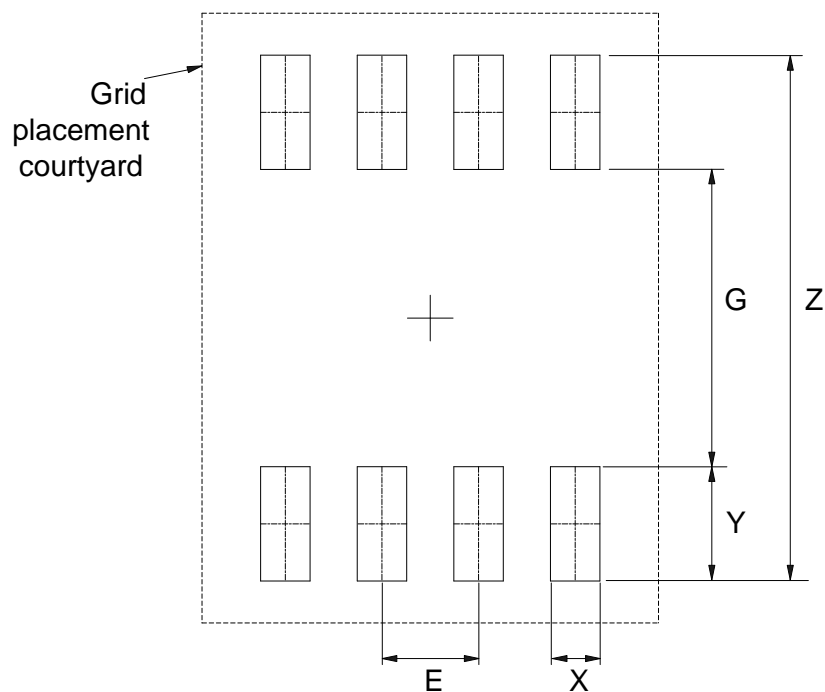
Package Outline Dimensions (All dimensions in mm(inch).)

(1) Package Type: SO-8



Suggested Pad Layout

(1) Package Type: SO-8



Dimensions	Z (mm)/(inch)	G (mm)/(inch)	X (mm)/(inch)	Y (mm)/(inch)	E (mm)/(inch)
Value	6.900/0.272	3.900/0.154	0.650/0.026	1.500/0.059	1.270/0.050

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