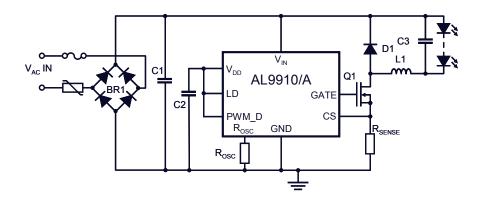


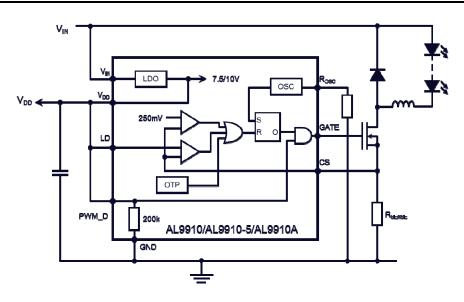
Typical Applications Circuit



Pin Descriptions

Pin	Pin N	umber	Europhien.	
Name	SO-8	SO-8EP	Function	
VIN	1	1	Input Voltage	
CS	2	2	Senses LED string and external MOSFET switch current	
GND	3	3	Device Ground	
Gate	4	4	Drives the gate of the external MOSFET switch.	
PWM_D	5	5	Low Frequency PWM Dimming pin, also Enable input. Internal 200k Ω pull-down to GND.	
V _{DD}	6	6	Internally regulated supply voltage. 7.5V nominal for AL9910 and AL9910-5 10V nominal for AL9910A. Can supply up to 1 mA for external circuitry. A sufficient storage capacitor is used to provide storage when the rectified AC input is near the zero crossing.	
LD	7	7	Linear Dimming Input. Changes the current limit threshold at current sense comparator and changes the average LED current.	
R _{osc}	8	8	Oscillator Control. A resistor connected between this pin and ground sets the PWM frequency. The devices can be switched into constant off time (PFM) mode by connecting the external oscillator resistor between R _{OSC} pin and the gate of the external MOSFET.	
EP PAD	N/A	EP	Exposed Pad (bottom). Connect to GND directly underneath the package.	

Functional Block Diagram





Symbol	Parameter	Ratings	Unit
V _{IN(MAX)}	Maximum Input Voltage, VIN, to GND	-0.5 to +520	V
Vcs	Maximum CS Input Pin Voltage Relative to GND	-0.3 to +0.45	V
V _{LD}	Maximum LD Input Pin Voltage Relative to GND	-0.3 to (V _{DD} +0.3)	V
V _{PWM_D}	Maximum PWM_D Input Pin Voltage Relative to GND	-0.3 to (V _{DD} +0.3)	V
VGATE	Maximum GATE Pin Voltage Relative to GND	-0.3 to (V _{DD} +0.3)	V
V _{DD(MAX)}	Maximum V _{DD} Pin Voltage Relative to GND	12	V
	Continuous Power Dissipation ($T_A = +25^{\circ}C$)		
	SO-8 (derate 6.3mW/°C above +25°C)	630	mW
	SO-8EP (derate at 22mW/°C above 25°C)	2200	mW
TJ	Junction Temperature Range	+150	°C
T _{ST}	Storage Temperature Range	-65 to +150	°C
ESD HBM	Human Body Model ESD Protection (Note 5)	1500	V
ESD MM	Machine Model ESD Protection (Note 5)	300	V

Absolute Maximum Ratings (Note 4) (@T_A = +25°C, unless otherwise specified.)

Notes: 4. Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those listed in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

All voltages are with respect to Ground. Currents are positive into, negative out of the specified terminal.

5. Semiconductor devices are ESD sensitive and may be damaged by exposure to ESD events. Suitable ESD precautions should be taken when handling and transporting these devices

Recommended Operating Conditions (@T_A = +25°C, unless otherwise specified.)

Symbol	Parameter	Min	Max	Unit	
V _{INDC}	hand DO Ometa Malkana Basara	AL9910 AL9910-5	15.0	500	
	Input DC Supply Voltage Range	AL9910A Al9910A-5	20.0	500	V
T _A A	Ambient Temperature Denne (Nate C)	AL9910_S	-40	+85	°C
	Ambient Temperature Range (Note 6)	AL9910_SP	-40	+105	
		AL9910 AL9910-5		10	
V _{DD} M	Maximum Recommended Voltage Applied to V _{DD} Pin (Note 7)	AL9910A AL9910A-5		12	V
V _{EN(LO)}	Pin PWM_D Input Low Voltage	0	1	v	
V _{EN(HI)}	Pin PWM_D Input High Voltage	2.4	V _{DD}	v	

6. Maximum ambient temperature range is limited by allowable power dissipation. The Exposed pad SO-8EP with its lower thermal impedance allows Notes: the variants using this package to extend the allowable maximum ambient temperature range. 7. When using the AL9910 in isolated LED lamps an auxiliary winding might be used.



Symbol	Parameter	Conditions	Min	Тур	Max	Unit	
I _{INSD} S	Shut-Down Mode Supply Current	Pin PWM_D to GND,	AL9910 AL9910-5		0.50	1	mA
		$V_{IN} = V_{IN(MIN)}$ (Note 6)	AL9910A		0.65	1.2	
V _{DD}	Internally Regulated Voltage	V _{IN} = V _{IN(MIN)} ~500V, (Note 8)	AL9910 AL9910-5	7.0	7.5	8.0	v
		$I_{DD(ext)} = 0$, Gate pin open	AL9910A	9	10	11	
I _{DD(ext)}	V _{DD} Current Available for External Circuitry	$V_{IN} = V_{IN(MIN)}$ to 100V (Notes 8 &	k 9)			1.0	mA
UVLO	V _{DD} Under Voltage Lockout Threshold	V _{DD} rising	AL9910 AL9910-5	6.4	6.7	7	v
	-	-	AL9910A	8	9	10	
∆UVLO	V _{DD} Under Voltage Lockout Hysteresis	V _{DD} falling	AL9910 AL9910-5		500		mV
			AL9910A		750		
R _{PWM_D}	PWM_D Pull-Down Resistance	V _{PWM_D} = 5V	-	150	200	250	kΩ
V _{CS(HI)} Curren	Current Sense Threshold Voltage	Full ambient temperature range (Note 10)	AL9910	225	250	275	- mV
			AL9910A	230	255	280	
			AL9910A-5	242	255	267	
			AL9910-5	237.5	250	262.5	
V _{GATE(HI)}	GATE High Output Voltage	I _{OUT} = 10mA		V _{DD} -0.3		V _{DD}	V
VGATE(LO)	GATE Low Output Voltage	I _{OUT} = -10mA		0		0.3	V
4	Oppillator Fraguenov	R _{osc} = 1MΩ		20	25	30	kHz
fosc	Oscillator Frequency	$R_{OSC} = 226 k\Omega$		80	100	120	KIIZ
D _{MAXhf}	Maximum Oscillator PWM Duty Cycle	f _{PWMhf} = 25kHz, at GATE, CS to GND.				100	%
V _{LD}	Linear Dimming Pin Voltage Range	Full ambient temperature range V _{IN} = 20V	Full ambient temperature range (Note 10),		-	250	mV
t _{BLANK}	Current Sense Blanking Interval	$V_{CS} = 0.45V, V_{LD} = V_{DD}$		160	250	440	ns
t _{DELAY}	Delay From CS Trip to GATE lo	$V_{IN} = 20V, V_{LD} = 0.15,$ $V_{CS} = 0 \text{ to } 0.22V \text{ after } T_{BLANK}$				300	ns
t _{RISE}	GATE Output Rise Time	$C_{\text{GATE}} = 500\text{pF}$			30	50	ns
t _{FALL}	GATE Output Fall Time	C _{GATE} = 500pF			30	50	ns
T _{SD}	Thermal Shut Down	FOATE VVVP.			150		
T _{SDH}	Thermal Shut Down Hysteresis				50		°C
	Thermal Resistance Junction-to-	SO-8 (Note 11) SO-8EP (Note 12)			110		°C/W
θ_{JA}	Ambient				66		
0	Thermal Decistorias Institut to Con-	SO-8 (Note 11)			22		
θ _{JC} T	Thermal Resistance Junction-to-Case	SO-8EP (Note 12)		9		°C/W	

Electrical Characteristics (@T_A = +25°C, unless otherwise specified.)

Notes:

8. $V_{IN(MIN)}$ for the AL9910 is 15V and for the AL9910A it is 20V.

9. Also limited by package power dissipation limit, whichever is lower.

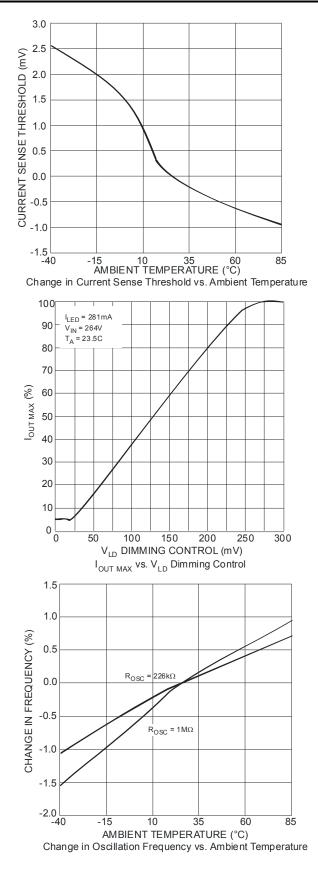
10. Full ambient temperature range for AL9910-5S, AL9910AS and AL9910S is -40 to +85°C; for AL9910-5SP, AL9910ASP and AL9910SP is -40°C to +105°C.

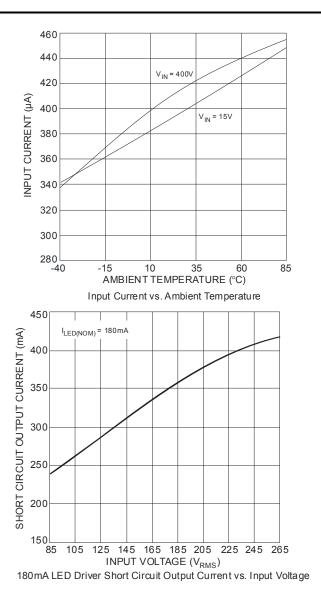
11. Device mounted on FR-4 PCB (25mm x 25mm 1oz copper, minimum recommended pad layout on top. For better thermal performance, larger copper pad for heat-sink is needed.

12. Device mounted on FR-4 PCB (51mm x 51mm 2oz copper, minimum recommended pad layout on top layer and thermal vias to bottom layer ground plane. For better thermal performance, larger copper pad for heat-sink is needed.



Typical Characteristics

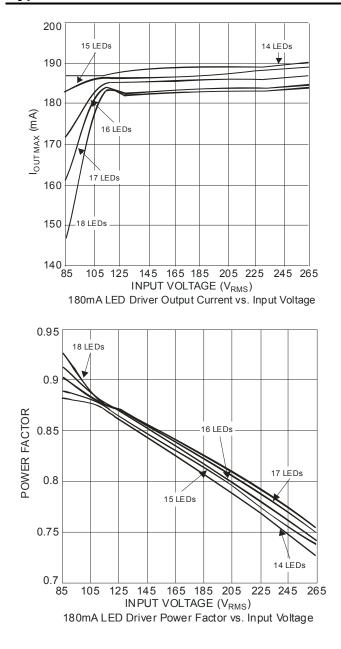


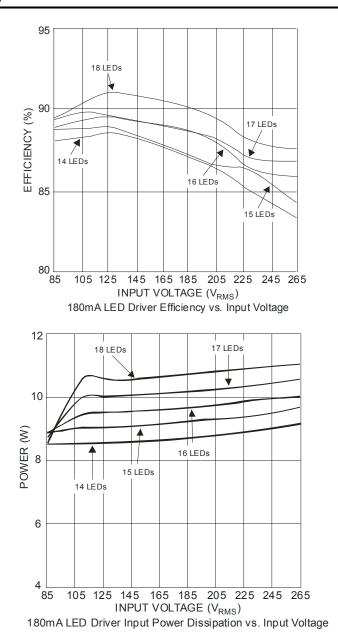


AL9910/ AL9910A/ AL9910-5/ AL9910A-5



Typical Characteristics (cont.) measured using AL9910EV4







Application Information

The AL9910 is very versatile and is capable of operating in isolated or non-isolated topologies. It can also be made to operate in continuous as well as discontinuous conduction mode.

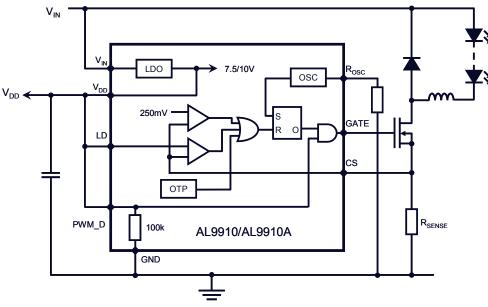


Figure 1 Functional Block Diagram

The AL9910 contains a high voltage LDO (see Figure 1) the output of the LDO provides a power rail to the internal circuitry including the gate driver. A UVLO on the output of the LDO prevents incorrect operation at low input voltage to the V_{IN} pin.

In a non-isolated Buck LED driver when the gate pin goes high the external power MOSFET Q1 is turned on causing current to flow through the LEDs, inductor (L1) and current sense resistor (R_{SENSE}). When the voltage across R_{SENSE} exceeds the current sense pin threshold the external MOSFET Q1 is turned off. The stored energy in the inductor causes the current to continue to flow through the LEDs via diode D1.

The AL9910's LDO provides all power to the rest of the IC including Gate drive this removes the need for large high power start-up resistors. This means that operate correctly it requires around 0.5mA from the high voltage power rail. The LDO can also be used to supply up to 1mA to external circuits.

The AL9910 operates and regulates by limiting the peak current of the external MOSFET; the peak current sense threshold is nominally set at 250mV.

The same basic operation is true for isolated topologies, however in these the energy stored in the transformer delivers energy to LEDs during the off-cycle of the external MOSFET.

Design Parameters

Setting the LED Current

In the non-isolated buck converter topology, figure 1, the average LED current is not the peak current divided by 2 - however, there is a certain error due to the difference between the peak and the average current in the inductor. The following equation accounts for this error:

$$R_{SENSE} = \frac{250mV}{\left(I_{LED} + (0.5 * I_{RIPPLE})\right)}$$



Setting Operating Frequency

The AL9910 is capable of operating over a 25 and 300 kHz switching frequency range. The switching frequency is programmed by connecting an external resistor between R_{OSC} pin and ground. The corresponding oscillator period is:

$$t_{OSC} = \frac{R_{OSC} + 22}{25} \ \mu s$$
 with R_{OSC} in $k\Omega$

The switching frequency is the reciprocal of the oscillator period. Typical values for R_{OSC} vary from 75k Ω to 1M Ω

When driving smaller numbers of LEDs, care should be taken to ensure that $t_{ON} > t_{BLANK}$. The simplest way to do this is to reduce/limit the switching frequency by increasing the R_{OSC} value. Reducing the switching frequency will also improve the efficiency.

When operating in buck mode the designer must keep in mind that the input voltage must be maintained higher than 2 times the forward voltage drop across the LEDs. This limitation is related to the output current instability that may develop when the AL9910 operates at a duty cycle greater than 0.5. This instability reveals itself as an oscillation of the output current at a sub-harmonic (SBO) of the switching frequency.

The best solution is to adopt the so-called constant off-time operation as shown in Figure 2. The resistor (R_{OSC}) is, connected to ground by default, to set operating frequency. To force the AL9910 to enter constant OFF time mode R_{OSC} is connected to the gate of the external MOSFET. This will decrease the duty cycle from 50% by increasing the total period, $t_{OFF} + t_{ON}$.

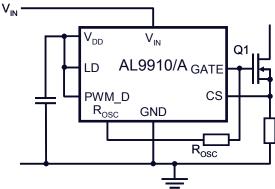


Figure 2. Constant Off-Time Configuration

The oscillator period equation above now defines the AL9910 off time, t_{OFF}.

When using this mode the nominal switching frequency is chosen and from the nominal input and output voltages the off-time can be calculated:

$$t_{OFF} = \left(1 - \frac{V_{OUT(nom)}}{V_{IN(nom)}}\right) * \frac{1}{f_{OSC}}$$

From this the timing resistor, R_{OSC}, can be calculated: $R_{OSC} = (t_{OFF}(\mu s) * 25) - 22(k\Omega)$

Inductor Selection

The non-isolated buck circuit, Figure 1, is usually selected and it has two operation modes: continuous and discontinuous conduction modes. A buck power stage can be designed to operate in continuous mode for load current above a certain level usually 15% to 30% of full load. Usually, the input voltage range, the output voltage and load current are defined by the power stage specification. This leaves the inductor value as the only design parameter to maintain continuous conduction mode. The minimum value of inductor to maintain continuous conduction mode can be determined by the following example.

The required inductor value is determined from the desired peak-to-peak LED ripple current in the inductor; typically around 30% of the nominal LED current.

$$L = \frac{(V_{IN} - V_{LEDs}) \times D}{(0.3 \times I_{LED}) \times f_{OSC}}$$
 Where D is duty cycle

The next step is determining the total voltage drop across the LED string. For example, when the string consists of 10 High-Brightness LEDs and each diode has a forward voltage drop of 3.0V at its nominal current; the total LED voltage V_{LEDS} is 30V.



Dimming

The LED brightness can be dimmed either linearly (using the LD pin) or via pulse width modulation (using the PWM-D pin); or a combination of both - depending on the application. Pulling the PWM_D pin to ground will turn off the AL9910. When disabled, the AL9910's quiescent current is typically 0.5mA (0.65 for AL9910A). Reducing the LD voltage will reduce the LED current but it will not entirely turn off the external power transistor and hence the LED current – this is due to the finite blanking period. Only the PWM_D pin will turn off the power transistor.

Linear dimming is accomplished by applying a 45mV to 250mV analog signal to the LD pin. This overrides the default 250mV threshold level of the CS pin and reduces the output current. If an input voltage greater than 250mV is applied to the LD then the output current will not change.

The LD pin also provides a simple cost effective solution to soft start; by connecting a capacitor to the LD pin down to ground at initial power up the LD pin will be held low causing the sense threshold to be low. As the capacitor charges up the current sense threshold will increase thereby causing the average LED current to increase.

PWM dimming is achieved by applying an external PWM signal to the PWM_D pin. The LED current is proportional to the PWM duty cycle and the light output can be adjusted between zero and 100%. The PWM signal enables and disables the AL9910 - modulating the LED current. The ultimate accuracy of the PWM dimming method is limited only by the minimum gate pulse width, which is a fraction of a percentage of the low frequency duty cycle. PWM dimming of the LED light can be achieved by turning on and off the converter with low frequency 50Hz to 1000Hz TTL logic level signal.

With both modes of dimming it is not possible to achieve average brightness levels higher than the one set by the current sense threshold level of the AL9910. If a greater LED current is required then a smaller sense resistor should be used

Output Open Circuit Protection

The non-isolated buck LED driver topology provides inherent protection against an open circuit condition in the LED string due to the LEDs being connected in series with the inductor. Should the LED string become open circuit then no switching occurs and the circuit can be permanently left in this state with damage to the rest of the circuit.

AC/DC Off-Line LED Driver

The AL9910 is a cost-effective off-line buck LED driver-controller specifically designed for driving LED strings. It is suitable for being used with either rectified AC line or any DC voltage between 15V to 500V. See Figure 3 for typical circuit.

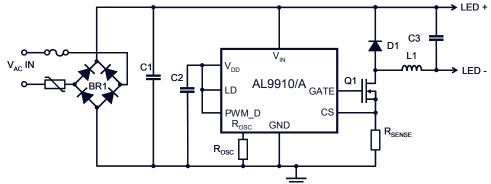


Figure 3. Typical Application Circuit (without PFC)

Buck Design Equations:

$$\begin{split} D &= \frac{V_{LEDs}}{V_{IN}} \\ t_{ON} &= \frac{D}{f_{osc}} \\ L &\geq \frac{(V_{IN} - V_{LEDs}) \times t_{ON}}{0.3 \times I_{LED}} \\ R_{SENSE} &= \frac{0.25}{I_{LED} + (0.5 \times (I_{LED} \times 0.3))} \text{ where } I_{LED} \times 0.3 = I_{RIPPLE} \end{split}$$



Design Example

For an AC line voltage of 120V the nominal rectified input voltage $V_{IN} = 120V^*1.41 = 169V$. From this and the LED chain voltage the duty cycle can be determined:

D = V_{LEDs} /V_{IN} = 30/169 = 0.177

From the switching frequency, for example f_{OSC} = 50kHz, the required on-time of the external MOSFET can be calculated:

 $t_{ON} = D/f_{OSC} = 3.5 \ \mu s$

The value of the inductor for an LED current of 350mA is determined as follows:

 $L = (V_{IN} - V_{LEDs}) * t_{ON} / (0.3 * I_{LED}) = 4.6 mH$

Input Bulk Capacitor

For Offline lamps an input bulk capacitor is required to ensure that the rectified AC voltage is held above twice the LED string voltage throughout the AC line cycle. The value can be calculated from:

$$C_{IN} \geq \frac{P_{IN} \times (1 - D_{CH})}{\sqrt{2} \times V_{LINE - MIN} \times 2f_L \times \Delta V_{DC - MAX}}$$

Where

D_{ch}: Capacity charge work period, generally about 0.2 to 0.25

f_I: Input frequency for full range (85 to 265V_{RMS})

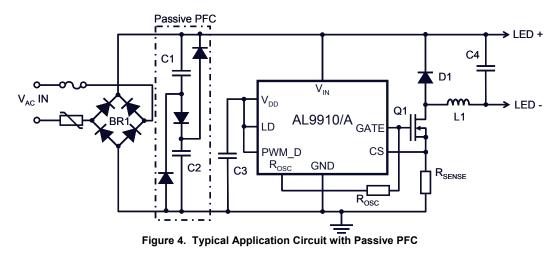
 ΔV_{DC} MAX Should be set 10 to15% of $\sqrt{2}V_{LINE}$ MIN

If the capacitor has a 15% voltage ripple then a simplified formula for the minimum value of the bulk input capacitor approximates to:

$$C_{MIN} = \frac{I_{LED} \times V_{LEDs} \times 0.06}{V_{IN}^2}$$

Power Factor Correction

If power factor improvement is required then for the input power less than 25W, a simple passive power factor correction circuit can be added to the AL9910 typical application circuit. Figure 4 shows that passive PFC circuitry (3 current steering diodes and 2 identical capacitors) does not significantly affect the rest of the circuit. Simple passive PFC improves the line current harmonic distortion and achieves a power factor greater than 0.85.



Each of these identical capacitors should be rated for half of the input voltage and have twice as much capacitance as the calculated C_{MIN} of the buck converter circuit without passive PFC (see above section on bulk capacitor calculation).

For further design information please see AN75 from the Diodes website.



DC-DC Buck LED Driver

The design procedure for an ac input buck LED driver outlined in the previous chapters equally applies DC input LED drivers.

When driving long LED chains care should be taken not to induce SBO – maximum LED chain voltage should be less half of V_{IN}. So either maximum duty cycle should be kept below 50% or use of constant off-time removes this issue.

DC-DC Boost LED Driver

Due to the topology of the AL9910 LED driver-controller it is capable of being used in boost configurations – at reduced accuracy. The accuracy can be improved by measuring the LED current with an op amp and use the op amp's output to drive the LD pin.

A Boost LED driver is used when the forward voltage drop of the LED string is higher than the input supply voltage. For example, the Boost topology can be appropriate when input voltage is supplied by a 48V power supply and the LED string consists of twenty HB LEDs, as the case may be for a street light.

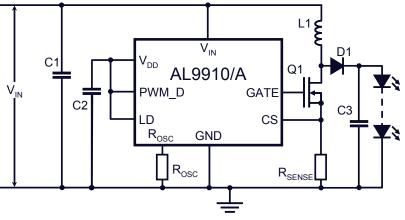


Figure 5. Boost LED Driver

In a Boost converter, when the external MOSFET is ON the energy is stored in the inductor which is then delivered to the output when the external MOSFET switches OFF. If the energy stored in the inductor is not fully depleted by the next switching cycle (continuous conduction mode) the DC conversion between input and output voltage is given by:

$$V_{OUT} = \frac{V_{IN}}{1-D} \Rightarrow D = \frac{V_{OUT} - V_{IN}}{V_{OUT}}$$

From the switching frequency, $f_{\mbox{OSC}},$ the on-time of the MOSFET can be calculated:

$$t_{ON} = \frac{D}{f_{OSC}}$$

From this the required inductor value can be determined by:

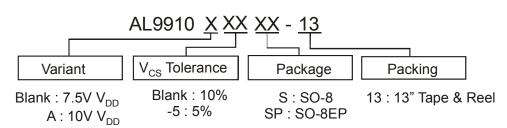
$$L = \frac{V_{IN} * t_{ON}}{0.3 * I_{LED}}$$

The Boost topology LED driver requires an output capacitor to deliver current to the LED string during the time that the external MOSFET is on.

In boost LED driver topologies if the LEDs should become open circuit damage may occur to the power switch and so some form of detection should be present to provide Over-voltage detection/protection.



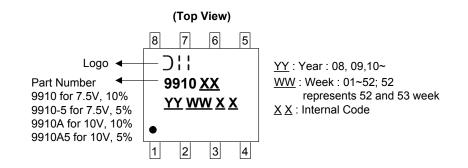
Ordering Information



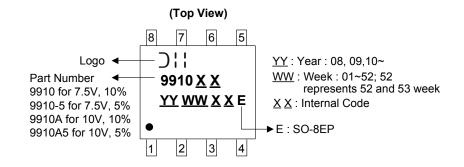
Part Number	V Televenee	Package Code	Deekesins	13" Tape and Reel		
Part Number	V _{CS} Tolerance		Packaging	Quantity	Part Number Suffix	
AL9910-5S-13	±5%	S	SO-8	2500/Tape & Reel	-13	
AL9910-5SP-13	±5%	SP	SO-8EP	2500/Tape & Reel	-13	
AL9910A-5S-13	±5%	S	SO-8	2500/Tape & Reel	-13	
AL9910A-5SP-13	±5%	SP	SO-8EP	2500/Tape & Reel	-13	
AL9910AS-13	±10%	S	SO-8	2500/Tape & Reel	-13	
AL9910ASP-13	±10%	SP	SO-8EP	2500/Tape & Reel	-13	
AL9910S-13	±10%	S	SO-8	2500/Tape & Reel	-13	
AL9910SP-13	±10%	SP	SO-8EP	2500/Tape & Reel	-13	

Marking Information

(1) SO-8



(2) SO8-EP

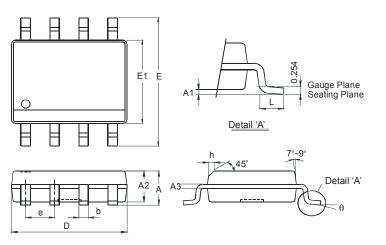




Package Outline Dimensions (All dimensions in mm.)

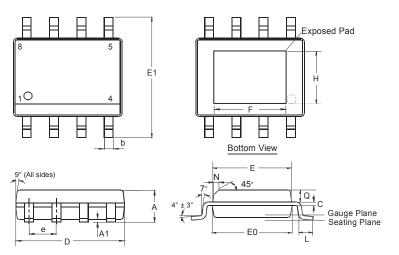
Please see AP02002 at http://www.diodes.com/datasheets/ap02002.pdf for latest version.

(1) SO-8



	SO-8				
Dim	Min	Max			
Α	-	1.75			
A1	0.10	0.20			
A2	1.30	1.50			
A3	0.15	0.25			
b	0.3	0.5			
D	4.85	4.95			
Е	5.90	6.10			
E1	3.85	3.95			
е	1.27	Тур			
h	-	0.35			
L	0.62	0.82			
θ	0°	8°			
All Di	All Dimensions in mm				

(2) SO-8EP



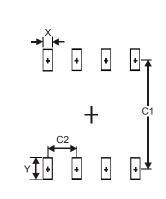
SO-8EP (SOP-8L-EP)					
Dim	Min	Max	Тур		
Α	1.40	1.50	1.45		
A1	0.00	0.13	-		
b	0.30	0.50	0.40		
С	0.15	0.25	0.20		
D	4.85	4.95	4.90		
Е	3.80	3.90	3.85		
E0	3.85 3.95		3.90		
E1	5.90	6.10	6.00		
е	I	1	1.27		
F	2.75	3.35	3.05		
Н	2.11	2.71	2.41		
L	0.62	0.82	0.72		
Ν	-	-	0.35		
Q	0.60	0.70	0.65		
All Dimensions in mm					



Suggested Pad Layout

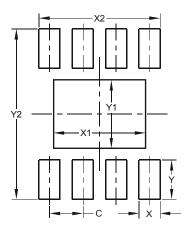
Please see AP02001 at http://www.diodes.com/datasheets/ap02001.pdf for the latest version.

(1) SO-8



Dimensions	Value (in mm)
Х	0.60
Y	1.55
C1	5.4
C2	1.27

(2) SO-8EP



Dimensions	Value (in mm)
С	1.270
Х	0.802
X1	3.502
X2	4.612
Y	1.505
Y1	2.613
Y2	6.500



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- A. Life support devices or systems are devices or systems which:
 - 1. are intended to implant into the body, or
 - 2. support or sustain life and whose failure to perform when properly used in accordance with instructions for use provided in the labeling can be reasonably expected to result in significant injury to the user.
- B. A critical component is any component in a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or to affect its safety or effectiveness.

Customers represent that they have all necessary expertise in the safety and regulatory ramifications of their life support devices or systems, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of Diodes Incorporated products in such safety-critical, life support devices or systems, notwithstanding any devices- or systems-related information or support that may be provided by Diodes Incorporated. Further, Customers must fully indemnify Diodes Incorporated and its representatives against any damages arising out of the use of Diodes Incorporated products in such safety-critical, life support devices or systems.

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