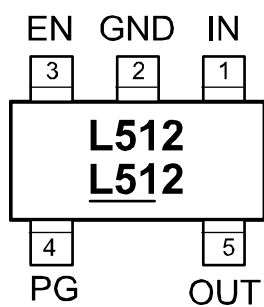


## Pin Configuration



MIC5268-x.x-BM5/YM5  
5-Pin SOT-23 (M5)

## Pin Description

Pin Number	Pin Name	Pin Function
1	IN	Supply Input
2	GND	Ground
3	EN	Enable/Shutdown (Input): CMOS compatible input. Logic high = enable; logic low = shutdown. Do not leave open.
4	PG	Power Good Output
5	OUT	Regulator Output

**Absolute Maximum Ratings<sup>(1)</sup>**

Supply Input Voltage ( $V_{IN}$ )	0V to +7V
Enable Input Voltage ( $V_{EN}$ )	0V to $V_{IN}$
Flag Output Voltage ( $V_{PG}$ )	0V to $V_{IN}$
Junction Temperature ( $T_J$ )	+150°C
Lead Temperature (soldering, 5sec.)	260°C
Storage Temperature ( $T_S$ )	–65°C to +150°C
EDS Rating <sup>(3)</sup>	

**Operating Ratings<sup>(2)</sup>**

Supply voltage ( $V_{IN}$ )	+2.7V to +6V
Enable Input Voltage ( $V_{EN}$ )	0V to $V_{IN}$
Flag Output Voltage ( $V_{PG}$ )	0V to $V_{IN}$
Junction Temperature ( $T_J$ )	–40°C to +125°C
Thermal Resistance	
SOT-23 ( $\theta_{JA}$ )	235°C/W

**Electrical Characteristics**

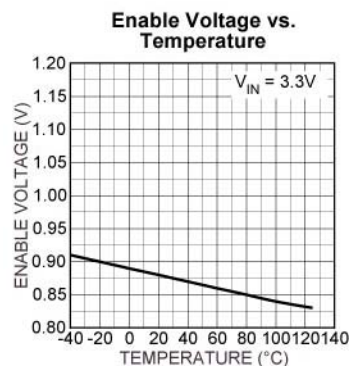
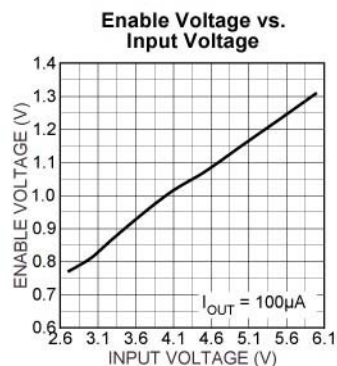
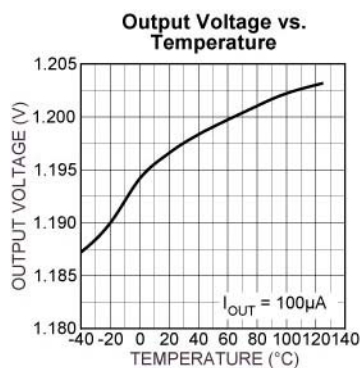
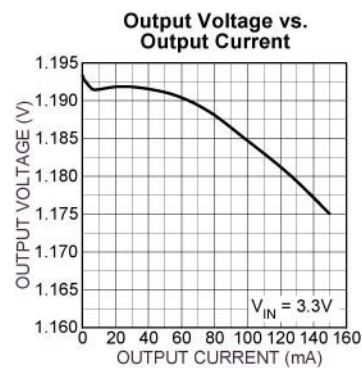
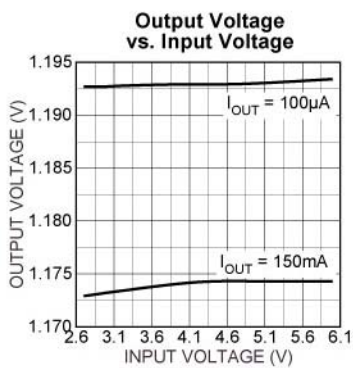
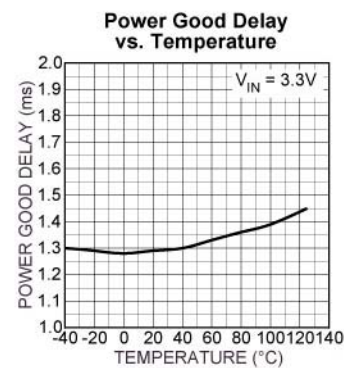
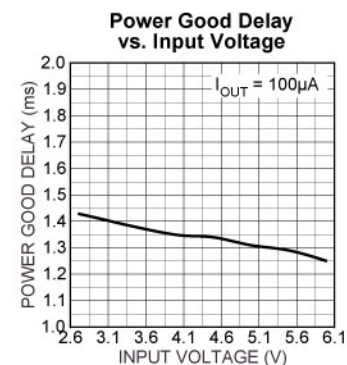
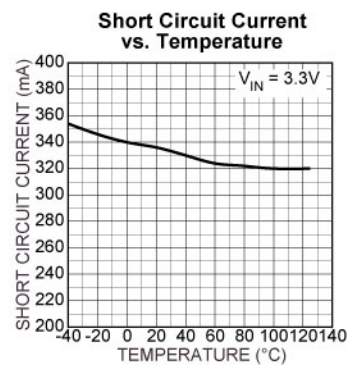
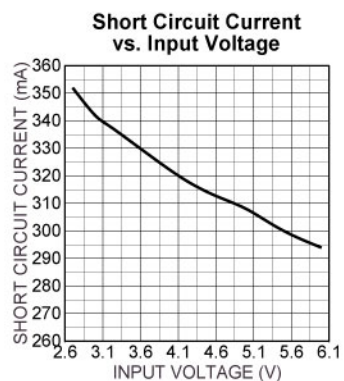
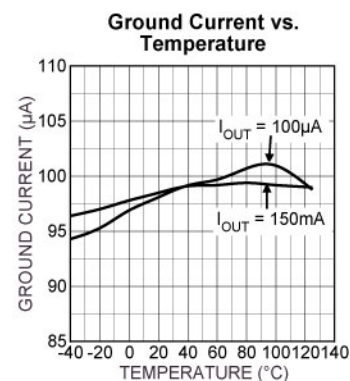
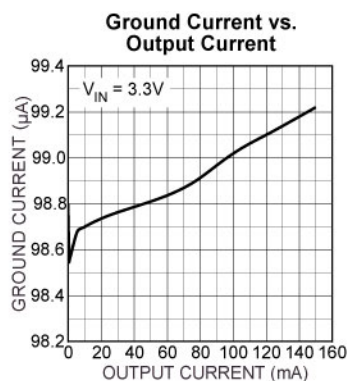
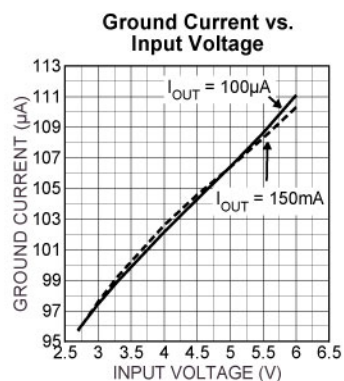
$V_{IN} = xx$ ;  $R_L = xx$ ;  $T_A = 25^\circ\text{C}$ , bold values indicate  $-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ , unless noted.

Symbol	Parameter	Condition	Min	Typ	Max	Units
V <sub>O</sub>	Output Voltage Accuracy	I <sub>OUT</sub> = 100μA	–3 –4		3 4	% %
ΔV <sub>LNR</sub>	Line Regulation	V <sub>IN</sub> = 2.7V to 6V	–0.3		0.3	%/V
ΔV <sub>LNR</sub>	Load Regulation	I <sub>OUT</sub> = 0.1mA to 150mA, <b>Note 4</b>		3	5	%
I <sub>Q</sub>	Quiescent Current	V <sub>EN</sub> ≤ 0.4V (shutdown) PG = NC		0.45	1	μA
I <sub>GND</sub>	Ground Pin Current, <b>Note 5</b>	I <sub>OUT</sub> = 0mA; V <sub>IN</sub> = 6.0V		110	150	μA
		I <sub>OUT</sub> = 150mA; V <sub>IN</sub> = 6.0V		110	150	μA
I <sub>LIM</sub>	Current Limit	V <sub>OUT</sub> = 0V	160	350		mA
Enable Input						
V <sub>IL</sub>	Enable Input Logic-Low Voltage	V <sub>IN</sub> = 5.5V, regulator shutdown			0.4	V
V <sub>IH</sub>	Enable Input Logic-High Voltage	V <sub>IN</sub> = 5.5V, regulator enabled	1.6			V
I <sub>EN</sub>	Enable Input Current	V <sub>IL</sub> ≤ 0.4V; V <sub>IN</sub> = 5.5V		0.01		μA
		V <sub>IH</sub> ≥ 1.6V; V <sub>IN</sub> = 5.5V		0.01		μA
Thermal Protection						
	Thermal Shutdown Temperature			150		°C
	Thermal Shutdown Hysteresis			10		°C
Power Good, Note 6						
V <sub>PG</sub>	Low Threshold High Threshold	% of V <sub>OUT</sub> (PG ON) % of V <sub>OUT</sub> (PG OFF)	88		97	% %
V <sub>OL</sub>	PG Output Logic-Low Voltage	I <sub>L</sub> = 10mA		250	500	mV
I <sub>PG</sub>	Power Good Leakage Current	power good off, V <sub>PG</sub> = 5.5V		0.01		μA
V <sub>PG</sub> Delay	Delay time to Power Good	See Timing Diagram	1		5	ms

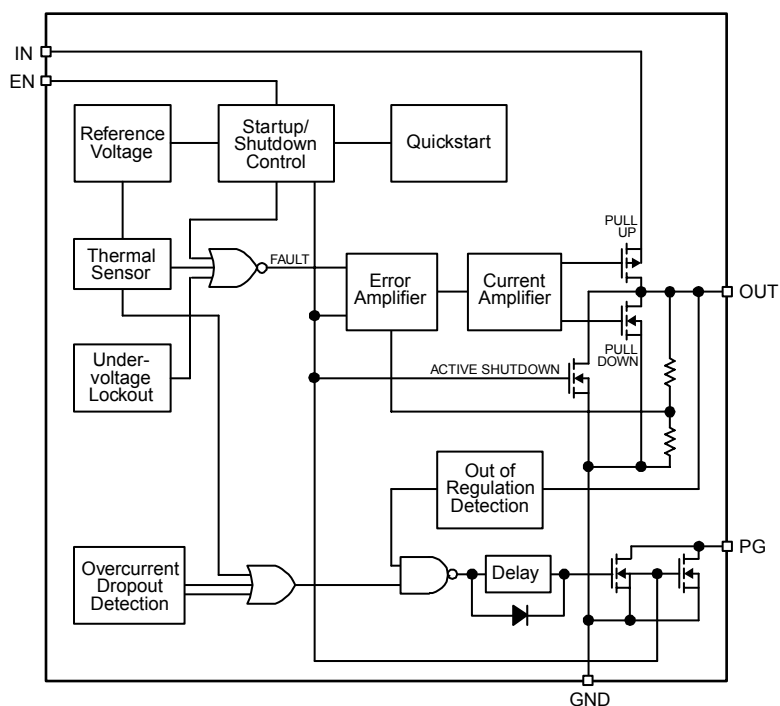
**Notes:**

- Exceeding the absolute maximum rating may damage the device.
- The device is not guaranteed to function outside its operating rating.
- Devices are ESD sensitive. Handling precautions recommended.
- Regulation is measured at constant junction temperature using low duty cycle pulse testing. Parts are tested for load regulation in the load range from 0.1mA to 150mA. Changes in output voltage due to heating effects are covered by the thermal regulation specification.
- Ground pin current is the regulator quiescent current. The total current drawn from the supply is the sum of the load current plus the ground pin current.
- The power good is a function of the output voltage being 5% low and the detection of one of the following: overcurrent, overtemperature or dropout. See "Applications Information" section for additional information.

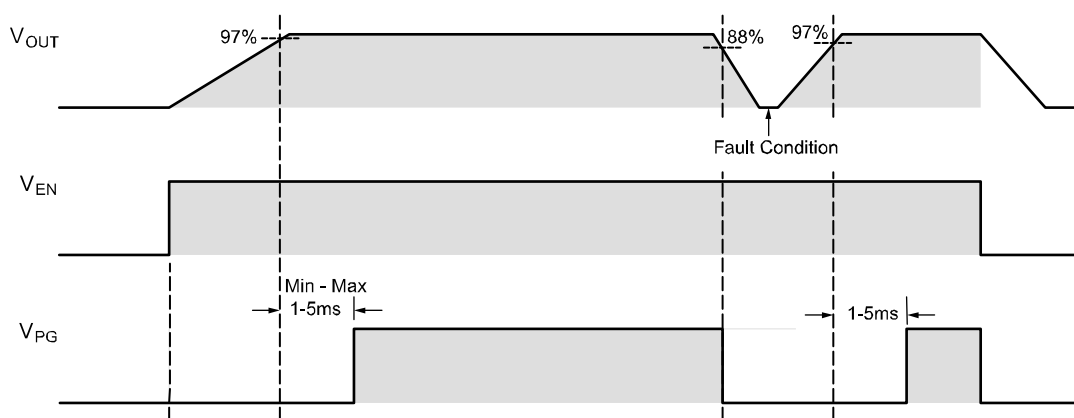
## Typical Characteristics



## Block Diagram



## Timing Diagram



## Application Information

### Enable/Shutdown

The MIC5268 comes with an active-high enable pin that allows the regulator to be disabled. Forcing the enable pin low disables the regulator and sends it into a “zero” off-mode-current state. In this state, current consumed by the regulator goes nearly to zero. Forcing the enable pin high enables the output voltage. This part is CMOS and the enable pin cannot be left floating; a floating enable pin may cause an indeterminate state on the output.

### Input Capacitor

An input capacitor is not required for stability. A 1 $\mu$ F input capacitor is recommended when the bulk ac supply capacitance is more than 10 inches away from the device, or when the supply is a battery.

### Output Capacitor

The MIC5268 requires an output capacitor for stability. The design requires 1 $\mu$ F or greater on the output to maintain stability. The capacitor can be a low-ESR ceramic chip capacitor. The MIC5268 has been designed to work specifically with the low-cost, small chip capacitors. Tantalum capacitors can also be used for improved capacitance overtemperature. The value of the capacitor can be increased without bound.

X7R dielectric ceramic capacitors are recommended because of their temperature performance. X7R-type capacitors change capacitance by 15% over their operating temperature range and are the most stable type of ceramic capacitors. Z5U and Y5V dielectric capacitors change value by as much 50% and 60% respectively over their operating temperature ranges. To use a ceramic chip capacitor with Y5V dielectric, the value must be much higher than an X7R ceramic or a tantalum capacitor to ensure the same minimum capacitance value over the operating temperature range. Tantalum capacitors have a very stable dielectric (10% over their operating temperature range) and can also be used with this device.

### Power Good

The power good output is an open-drain output. It is designed essentially to work as a power-on reset generator once the regulated voltage was up and/or a fault condition. The output of the power good drives low when a fault condition AND an undervoltage detection occurs. The power good output comes back up once the output has reached 97% of its nominal value and a 1ms to 5ms delay has passed. See *Timing Diagram*.

The MIC5268's internal circuit intelligently monitors overcurrent, overtemperature and dropout conditions and ORs these outputs together indicate some fault condition. This output is fed into an on-board delay circuitry that drives the open drain transistor to indicate a fault.

## Transient Response

The MIC5268 implements a unique output stage to dramatically improve transient response recovery time. The output is a totem-pole configuration with a P-channel MOSFET pass device and an N-channel MOSFET clamp. The N-channel clamp is a significantly smaller device that prevents the output voltage from overshooting when a heavy load is removed. This feature helps to speed up the transient response by significantly decreasing transient response recovery time during the transition from heavy load (100mA) to light load (100 $\mu$ A).

### Active Shutdown

The MIC5268 also features an active shutdown clamp, which is an N-channel MOSFET that turns on when the device is disabled. This allows the output capacitor and load to discharge, de-energizing the load.

### Thermal Considerations

The MIC5268 is designed to provide 150mA of continuous current in a very small package. Maximum power dissipation can be calculated based on the output current and the voltage drop across the part. To determine the maximum power dissipation of the package, use the junction-to-ambient thermal resistance of the device and the following basic equation:

$$P_{D(max)} = \left( \frac{T_{J(max)} - T_A}{\theta_{JA}} \right)$$

$T_{J(max)}$  is the maximum junction temperature of the die, 125°C, and  $T_A$  is the ambient operating temperature.  $\theta_{JA}$  is layout dependent; Table 1 shows examples of junction-to-ambient thermal resistance for the MIC5268.

Package	$\theta_{JA}$ Recommended Minimum Footprint	$\theta_{JA}$ 1" Square Copper Clad	$\theta_{JC}$
SOT-23-5 (M5)	235°C/W	185°C/W	145°C/W

Table 1. Thermal Resistance

The actual power dissipation of the regulator circuit can be determined using the equation:

$$P_D = (V_{IN} - V_{OUT}) I_{OUT} + V_{IN} I_{GND}$$

Substituting  $P_{D(max)}$  for  $P_D$  and solving for the operating conditions that are critical to the application will give the maximum operating conditions for the regulator circuit. For example, when operating the MIC5268-1.2BM5 at 50°C with a minimum footprint layout, the maximum input voltage for a set output current can be determined as follows:

$$P_{D(max)} = \left( \frac{125^\circ\text{C} - 50^\circ\text{C}}{235^\circ\text{C}} \right)$$

$$P_{D(max)} = 315\text{mW}$$

The junction-to-ambient thermal resistance for the minimum footprint is 235°C/W, from Table 1. The maximum power dissipation must not be exceeded for proper operation. Using the output voltage of 1.2V and an output current of 150mA, the maximum input voltage can be determined. Because this device is CMOS and the ground current is typically 100µA over the load range, the power dissipation contributed by the ground current is < 1% and can be ignored for this calculation.

$$315\text{mW} = (V_{\text{IN}} - 1.2\text{V}) 150\text{mA}$$

$$315\text{mW} = V_{\text{IN}} \cdot 150\text{mA} - 195\text{mW}$$

$$510\text{mW} = V_{\text{IN}} \cdot 150\text{mA}$$

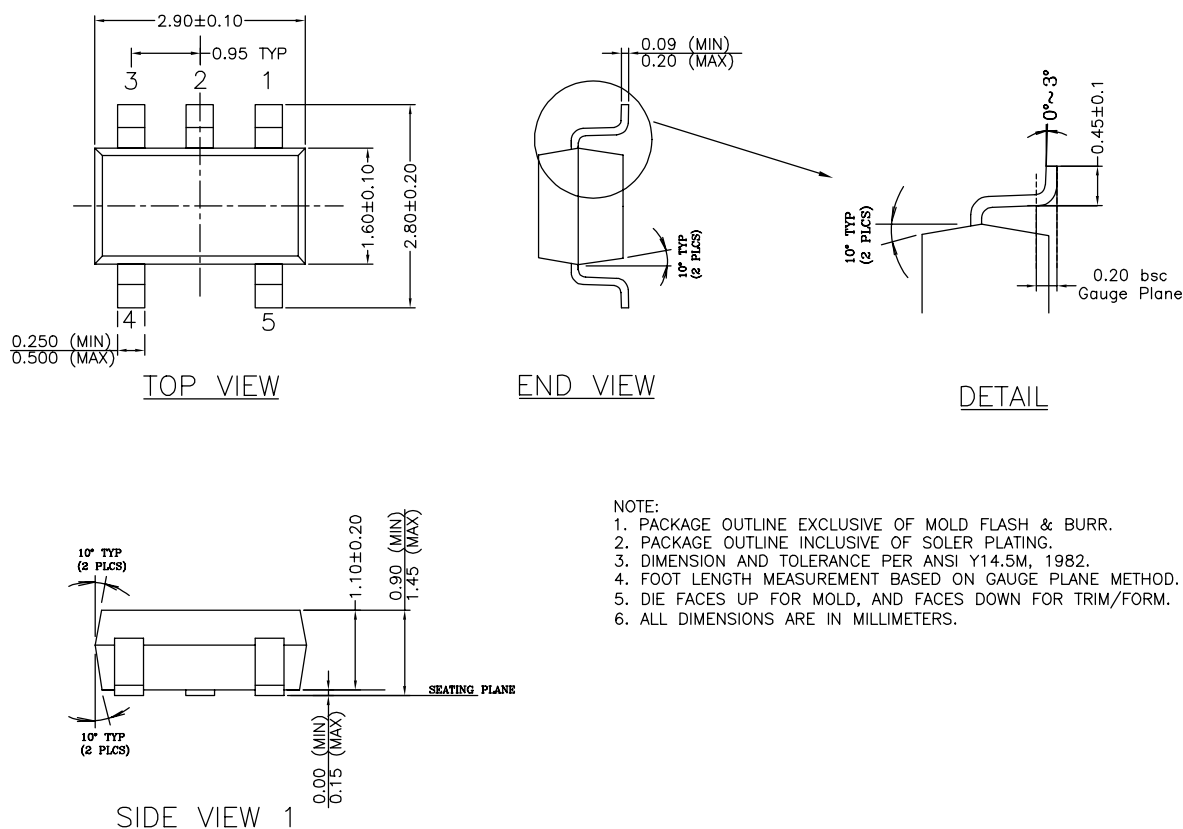
$$V_{\text{IN}} (\text{max}) = 3.4\text{V}$$

Therefore, a 1.2V application at 150mA of output current can accept a maximum input voltage of 3.4V in a SOT-23-5 package. For a full discussion of heat sinking and thermal effects on voltage regulators, refer to the Regulator Thermals section of Micrel's *Designing with Low-Dropout Voltage Regulators* handbook.

### Dual-Supply Operation

When used in dual supply systems where the regulator load is returned to a negative supply, the output voltage must be diode clamped to ground.

## Package Information



NOTE:

1. PACKAGE OUTLINE EXCLUSIVE OF MOLD FLASH & BURR.
2. PACKAGE OUTLINE INCLUSIVE OF SOLDER PLATING.
3. DIMENSION AND TOLERANCE PER ANSI Y14.5M, 1982.
4. FOOT LENGTH MEASUREMENT BASED ON GAUGE PLANE METHOD.
5. DIE FACES UP FOR MOLD, AND FACES DOWN FOR TRIM/FORM.
6. ALL DIMENSIONS ARE IN MILLIMETERS.

**5-Pin SOT-23 (M5)**

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