

# Contents

<b>1</b>	<b>Block diagram and pin description</b>	<b>5</b>
<b>2</b>	<b>Electrical specifications</b>	<b>7</b>
2.1	Absolute maximum ratings	7
2.2	Thermal data	8
2.3	Electrical characteristics	8
2.4	Waveforms	18
2.5	Electrical characteristics curves	21
<b>3</b>	<b>Application information</b>	<b>24</b>
3.1	GND protection network against reverse battery	24
3.1.1	Solution 1: resistor in the ground line (RGND only)	24
3.1.2	Solution 2: diode (D <sub>GND</sub> ) in the ground line	25
3.2	Load dump protection	25
3.3	MCU I/O protection	25
3.4	Current sense and diagnostic	25
3.4.1	Short to VCC and off-state open-load detection	26
3.5	Maximum demagnetization energy (VCC = 13.5V)	28
<b>4</b>	<b>Package and PCB thermal data</b>	<b>29</b>
4.1	SO-16L thermal data	29
<b>5</b>	<b>Package information</b>	<b>32</b>
5.1	ECOPACK® packages	32
5.2	Package mechanical data	32
5.3	Packing information	34
<b>6</b>	<b>Order codes</b>	<b>35</b>
<b>7</b>	<b>Revision history</b>	<b>36</b>

## List of tables

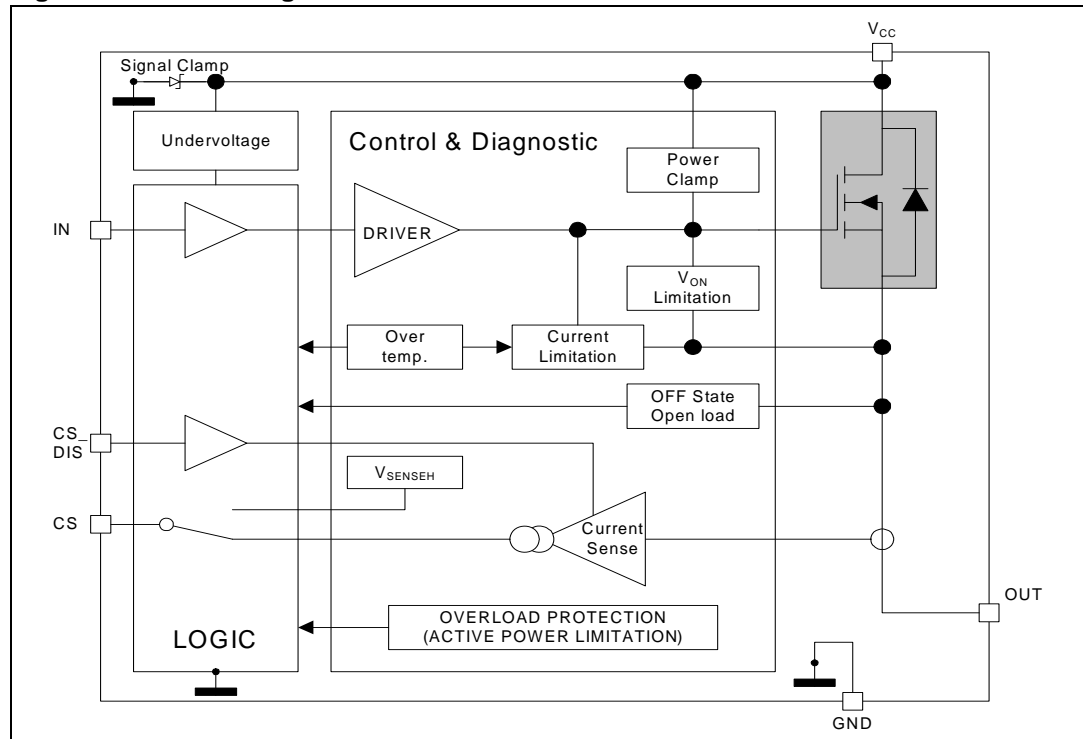
Table 1.	Pin function . . . . .	5
Table 2.	Suggested connections for unused and not connected pins . . . . .	6
Table 3.	Absolute maximum ratings . . . . .	7
Table 4.	Thermal data. . . . .	8
Table 5.	Power section . . . . .	8
Table 6.	Switching ( $V_{CC} = 13\text{ V}$ ; $T_j = 25\text{ °C}$ ) . . . . .	9
Table 7.	Logic inputs. . . . .	9
Table 8.	Protections and diagnostics . . . . .	10
Table 9.	Current sense ( $8\text{ V} < V_{CC} < 18\text{ V}$ ) . . . . .	10
Table 10.	Open-load detection ( $8\text{ V} < V_{CC} < 18\text{ V}$ ) . . . . .	12
Table 11.	Truth table. . . . .	16
Table 12.	Electrical transient requirements (part 1) . . . . .	17
Table 13.	Electrical transient requirements (part 2) . . . . .	17
Table 14.	Electrical transient requirements (part 3) . . . . .	17
Table 15.	Thermal parameter . . . . .	31
Table 16.	SO-16L mechanical data . . . . .	33
Table 17.	Device summary . . . . .	35
Table 18.	Document revision history . . . . .	36

## List of figures

Figure 1.	Block diagram . . . . .	5
Figure 2.	Configuration diagram (top view) . . . . .	6
Figure 3.	Current and voltage conventions . . . . .	7
Figure 4.	Current sense delay characteristics . . . . .	12
Figure 5.	Open-load off-state delay timing . . . . .	13
Figure 6.	Switching characteristics . . . . .	13
Figure 7.	Delay response time between rising edge of output current and rising edge of current sense (CS enabled) . . . . .	14
Figure 8.	Output voltage drop limitation . . . . .	14
Figure 9.	$I_{OUT}/I_{SENSE}$ vs $I_{OUT}$ . . . . .	15
Figure 10.	Maximum current sense ratio drift vs load current . . . . .	15
Figure 11.	Normal operation . . . . .	18
Figure 12.	Overload or short to GND . . . . .	18
Figure 13.	Intermittent overload . . . . .	19
Figure 14.	Off-state open-load with external circuitry . . . . .	19
Figure 15.	Short to $V_{CC}$ . . . . .	20
Figure 16.	$T_j$ evolution in over load or short to GND . . . . .	20
Figure 17.	Off-state output current . . . . .	21
Figure 18.	High level input current . . . . .	21
Figure 19.	Input clamp level . . . . .	21
Figure 20.	Input low level . . . . .	21
Figure 21.	Input high level . . . . .	21
Figure 22.	Input hysteresis voltage . . . . .	21
Figure 23.	On-state resistance vs $T_{case}$ . . . . .	22
Figure 24.	On-state resistance vs $V_{CC}$ . . . . .	22
Figure 25.	Undervoltage shutdown . . . . .	22
Figure 26.	Turn-On voltage slope . . . . .	22
Figure 27.	$I_{LIMH}$ vs $T_{case}$ . . . . .	22
Figure 28.	Turn-Off voltage slope . . . . .	22
Figure 29.	CS_DIS high level voltage . . . . .	23
Figure 30.	CS_DIS clamp voltage . . . . .	23
Figure 31.	CS_DIS low level voltage . . . . .	23
Figure 32.	Application schematic . . . . .	24
Figure 33.	Current sense and diagnostic . . . . .	26
Figure 34.	Maximum turn-Off current versus inductance . . . . .	28
Figure 35.	SO-16L PC board . . . . .	29
Figure 36.	$R_{thj-amb}$ vs PCB copper area in open box free air condition . . . . .	29
Figure 37.	SO-16L thermal impedance junction ambient single pulse . . . . .	30
Figure 38.	Thermal fitting model of a single channel HSD in SO-16L . . . . .	30
Figure 39.	SO-16L package dimensions . . . . .	32
Figure 40.	SO-16L tube shipment (no suffix) . . . . .	34
Figure 41.	SO-16L tape and reel shipment (suffix "TR") . . . . .	34

## 1 Block diagram and pin description

**Figure 1. Block diagram**



**Table 1. Pin function**

Name	Function
V <sub>CC</sub>	Battery connection.
OUTPUT	Power output.
GND	Ground connection. Must be reverse battery protected by an external diode/resistor network.
INPUT	Voltage controlled input pin with hysteresis, CMOS compatible; it controls output switch state.
CURRENT SENSE	Analog current sense pin; it delivers a current proportional to the load current.
CS_DIS	Active high CMOS compatible pin, to disable the current sense pin.

Figure 2. Configuration diagram (top view)

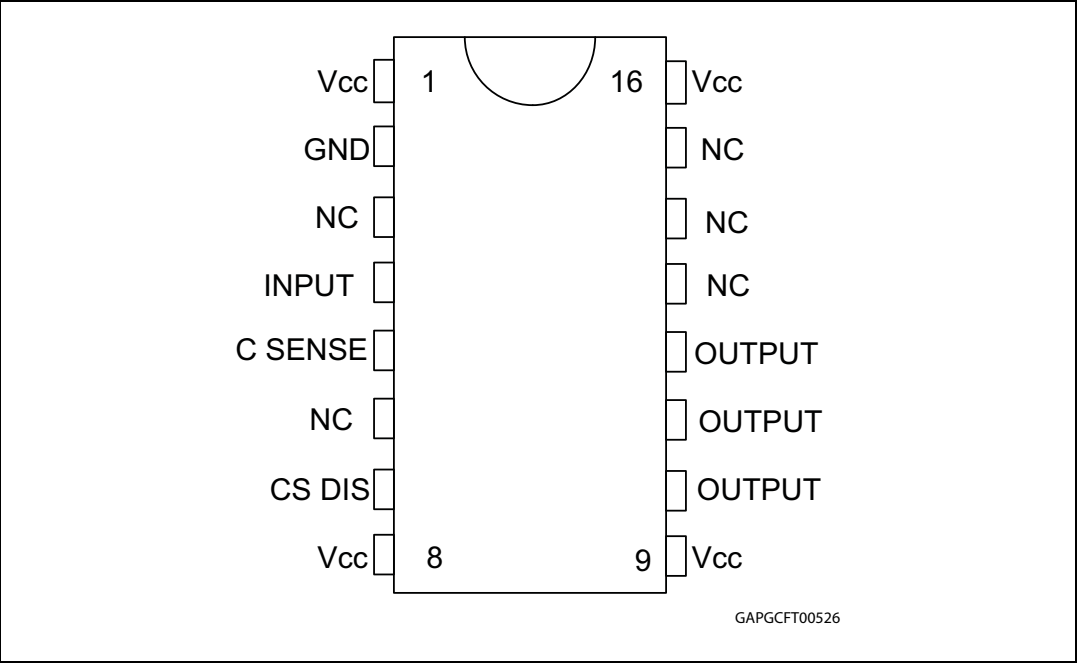
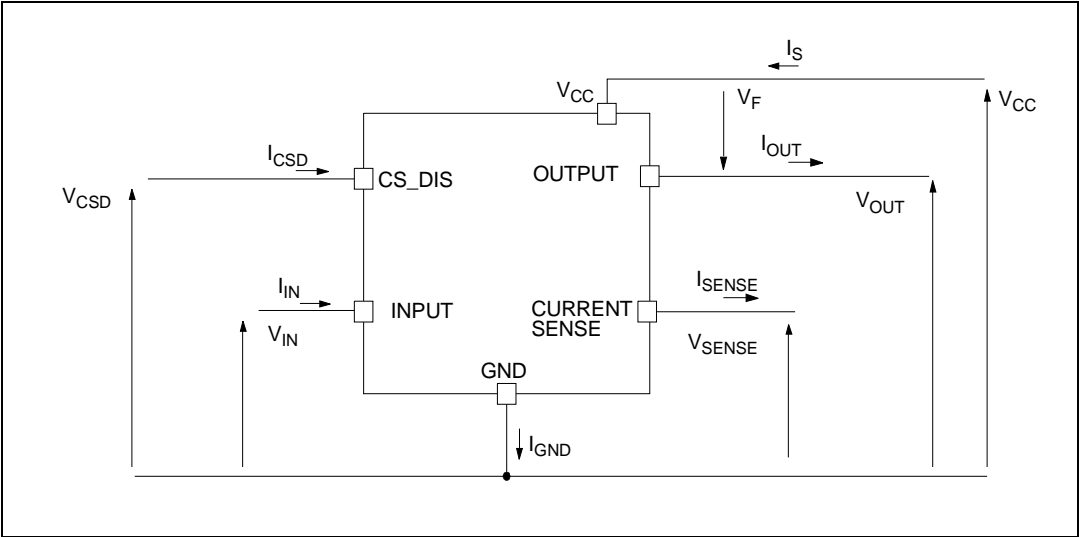


Table 2. Suggested connections for unused and not connected pins

Connection / pin	Current sense	N.C.	Output	Input	CS_DIS
Floating	Not allowed	X	X	X	X
To ground	Through 1 K $\Omega$ resistor	X	Through 22 K $\Omega$ resistor	Through 10 K $\Omega$ resistor	Through 10 K $\Omega$ resistor

# 2 Electrical specifications

Figure 3. Current and voltage conventions



Note:  $V_F = V_{OUT} - V_{CC}$  during reverse battery condition.

## 2.1 Absolute maximum ratings

Stressing the device above the rating listed in [Table 3](#) may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

Table 3. Absolute maximum ratings

Symbol	Parameter	Value	Unit
$V_{CC}$	DC supply voltage	41	V
$-V_{CC}$	Reverse DC supply voltage	0.3	V
$-I_{GND}$	DC reverse ground pin current	200	mA
$I_{OUT}$	DC output current	Internally limited	A
$-I_{OUT}$	Reverse DC output current	20	A
$I_{IN}$	DC input current	-1 to 10	mA
$I_{CSD}$	DC current sense disable input current	-1 to 10	mA
$-I_{CSENSE}$	DC reverse CS pin current	200	mA
$V_{CSENSE}$	Current sense maximum voltage	$V_{CC} - 41$ to $+V_{CC}$	V
$E_{MAX}$	Maximum switching energy (single pulse) $L = 3 \text{ mH}$ ; $R_L = 0 \Omega$ ; $V_{bat} = 13.5 \text{ V}$ ; $T_{jstart} = 150^\circ\text{C}$ ; $I_{OUT} = I_{limL} (Typ.)$	104	mJ

**Table 3. Absolute maximum ratings (continued)**

Symbol	Parameter	Value	Unit
V <sub>ESD</sub>	Electrostatic discharge (Human Body Model: R = 1.5 KΩ; C = 100 pF)		
	– INPUT	4000	V
	– CURRENT SENSE	2000	V
	– CS_DIS	4000	V
	– OUTPUT	5000	V
	– V <sub>CC</sub>	5000	V
V <sub>ESD</sub>	Charge device model (CDM-AEC-Q100-011)	750	V
T <sub>j</sub>	Junction operating temperature	-40 to 150	°C
T <sub>stg</sub>	Storage temperature	-55 to 150	°C

## 2.2 Thermal data

**Table 4. Thermal data**

Symbol	Parameter	Typ. value	Unit
R <sub>thj-pcb</sub>	Thermal resistance junction-pcb <sup>(1)</sup>	18.5	°C/W
R <sub>thj-amb</sub>	Thermal resistance junction - ambient on two layers pcb	See <a href="#">Figure 36</a>	°C/W
R <sub>thj-amb</sub>	Thermal resistance junction - ambient on two layers pcb <sup>(2)</sup>	34.5	°C/W

1. The measure is done in accordance with the JESD 51-8.

2. Four Layers PCB characteristics:

- Cu thickness: 70 μm outer layers, 35 μm inner layers
- Board finish thickness 1.6 mm +/- 10%
- Thermal vias separation 1.2 mm
- Thermal via diameter 0.3 mm +/- 0.08 mm
- Cu thickness on vias 0.025 mm
- Device soldered at about 2 cm from the PCB edge with two sqcm of exposed copper.

## 2.3 Electrical characteristics

Values specified in this section are for 8 V < V<sub>CC</sub> < 28 V; -40°C < T<sub>j</sub> < 150°C, unless otherwise stated.

**Table 5. Power section**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V <sub>CC</sub>	Operating supply voltage		4.5	13	28	V
V <sub>USD</sub>	Undervoltage shutdown			3.5	4.5	V
V <sub>USDhyst</sub>	Undervoltage shutdown hysteresis			0.5		V

**Table 5. Power section (continued)**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$R_{ON}$	On-state resistance	$I_{OUT} = 2\text{ A}; T_j = 25^\circ\text{C}$		50		m $\Omega$
		$I_{OUT} = 2\text{ A}; T_j = 150^\circ\text{C}$			100	m $\Omega$
		$I_{OUT} = 2\text{ A}; V_{CC} = 5\text{ V}; T_j = 25^\circ\text{C}$			65	m $\Omega$
$V_{clamp}$	Clamp voltage	$I_S = 20\text{ mA}$	41	46	52	V
$I_S$	Supply current	Off-state; $V_{CC} = 13\text{ V}; T_j = 25^\circ\text{C};$ $V_{IN} = V_{OUT} = V_{SENSE} = V_{CSD} = 0\text{ V}$		2 <sup>(1)</sup>	5 <sup>(1)</sup>	$\mu\text{A}$
		On-state; $V_{CC} = 13\text{ V}; V_{IN} = 5\text{ V};$ $I_{OUT} = 0\text{ A}$		1.5	3	mA
$I_{L(off1)}$	Off-state output current	$V_{IN} = V_{OUT} = 0\text{ V}; V_{CC} = 13\text{ V};$ $T_j = 25^\circ\text{C}$	0	0.01	3	$\mu\text{A}$
		$V_{IN} = V_{OUT} = 0\text{ V}; V_{CC} = 13\text{ V};$ $T_j = 125^\circ\text{C}$	0		5	$\mu\text{A}$
$V_F$	Output - $V_{CC}$ diode voltage	$-I_{OUT} = 2\text{ A}; T_j = 150^\circ\text{C}$			0.7	V

1. PowerMOS leakage included.

**Table 6. Switching ( $V_{CC} = 13\text{ V}; T_j = 25^\circ\text{C}$ )**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$t_{d(on)}$	Turn-on delay time	$R_L = 6.5\text{ }\Omega$ (see <a href="#">Figure 6</a> )	—	20	—	$\mu\text{s}$
$t_{d(off)}$	Turn-off delay time	$R_L = 6.5\text{ }\Omega$ (see <a href="#">Figure 6</a> )	—	40	—	$\mu\text{s}$
$(dV_{OUT}/dt)_{on}$	Turn-on voltage slope	$R_L = 6.5\text{ }\Omega$	—	See <a href="#">Figure 26</a>	—	V/ $\mu\text{s}$
$(dV_{OUT}/dt)_{off}$	Turn-off voltage slope	$R_L = 6.5\text{ }\Omega$	—	See <a href="#">Figure 28</a>	—	V/ $\mu\text{s}$
$W_{ON}$	Switching energy losses during $t_{on}$	$R_L = 6.5\text{ }\Omega$ (see <a href="#">Figure 6</a> )	—	0.20	—	mJ
$W_{OFF}$	Switching energy losses during $t_{off}$	$R_L = 6.5\text{ }\Omega$ (see <a href="#">Figure 6</a> )	—	0.3	—	mJ

**Table 7. Logic inputs**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{IL}$	Input low level voltage				0.9	V
$I_{IL}$	Low level input current	$V_{IN} = 0.9\text{ V}$	1			$\mu\text{A}$
$V_{IH}$	Input high level voltage		2.1			V
$I_{IH}$	High level input current	$V_{IN} = 2.1\text{ V}$			10	$\mu\text{A}$
$V_{I(hyst)}$	Input hysteresis voltage		0.25			V
$V_{ICL}$	Input clamp voltage	$I_{IN} = 1\text{ mA}$	5.5		7	V
		$I_{IN} = -1\text{ mA}$		-0.7		V

**Table 7. Logic inputs (continued)**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{CSDL}$	CS_DIS low level voltage				0.9	V
$I_{CSDL}$	Low level CS_DIS current	$V_{CSD} = 0.9\text{ V}$	1			$\mu\text{A}$
$V_{CSDH}$	CS_DIS high level voltage		2.1			V
$I_{CSDH}$	High level CS_DIS current	$V_{CSD} = 2.1\text{ V}$			10	$\mu\text{A}$
$V_{CSD(hyst)}$	CS_DIS hysteresis voltage		0.25			V
$V_{CSCL}$	CS_DIS clamp voltage	$I_{CSD} = 1\text{ mA}$	5.5		7	V
		$I_{CSD} = -1\text{ mA}$		-0.7		V

**Table 8. Protections and diagnostics <sup>(1)</sup>**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$I_{limH}$	DC short circuit current	$V_{CC} = 13\text{ V}$	19	27	38	A
		$5\text{ V} < V_{CC} < 28\text{ V}$			38	A
$I_{limL}$	Short circuit current during thermal cycling	$V_{CC} = 13\text{ V}; T_R < T_J < T_{TSD}$		7		A
$T_{TSD}$	Shutdown temperature		150	175	200	$^{\circ}\text{C}$
$T_R$	Reset temperature		$T_{RS} + 1$	$T_{RS} + 5$		$^{\circ}\text{C}$
$T_{RS}$	Thermal reset of status		135			$^{\circ}\text{C}$
$T_{HYST}$	Thermal hysteresis ( $T_{TSD} - T_R$ )			7		$^{\circ}\text{C}$
$V_{DEMAG}$	Turn- Off output voltage clamp	$I_{OUT} = 2\text{ A}; V_{IN} = 0;$ $L = 6\text{ mH}$	$V_{CC}-41$	$V_{CC}-46$	$V_{CC}-52$	V
$V_{ON}$	Output voltage drop limitation	$I_{OUT} = 0.1\text{ A};$ $T_J = -40^{\circ}\text{C}$ to $150^{\circ}\text{C}$ (see <a href="#">Figure 8</a> )		25		mV

1. To ensure long term reliability under heavy overload or short circuit conditions, protection and related diagnostic signals must be used together with a proper software strategy. If the device is subjected to abnormal conditions, this software must limit the duration and number of activation cycles.

**Table 9. Current sense ( $8\text{ V} < V_{CC} < 18\text{ V}$ )**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$K_0$	$I_{OUT}/I_{SENSE}$	$I_{OUT} = 0.05\text{ A}; V_{SENSE} = 0.5\text{ V};$ $V_{CSD} = 0\text{ V}; T_J = -40^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1170	2000	3090	
$K_1$	$I_{OUT}/I_{SENSE}$	$I_{OUT} = 1\text{ A}; V_{SENSE} = 4\text{ V};$ $V_{CSD} = 0\text{ V};$ $T_J = -40^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1575	2000	2750	
		$T_J = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1575	2000	2465	
$dK_1/K_1^{(1)}$	Current sense ratio drift	$I_{OUT} = 1\text{ A}; V_{SENSE} = 4\text{ V};$ $V_{CSD} = 0\text{ V};$ $T_J = -40^{\circ}\text{C}$ to $150^{\circ}\text{C}$	-10		10	%

Table 9. Current sense (8 V < V<sub>CC</sub> < 18 V) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
K <sub>2</sub>	I <sub>OUT</sub> /I <sub>SENSE</sub>	I <sub>OUT</sub> = 2 A; V <sub>SENSE</sub> = 4 V; V <sub>CSD</sub> = 0 V; T <sub>J</sub> = -40°C to 150°C T <sub>J</sub> = 25°C to 150°C	1765 1765	2000 2000	2315 2155	
dK <sub>2</sub> /K <sub>2</sub> <sup>(1)</sup>	Current sense ratio drift	I <sub>OUT</sub> = 2 A; V <sub>SENSE</sub> = 4 V; V <sub>CSD</sub> = 0 V; T <sub>J</sub> = -40 °C to 150 °C	-7		7	%
K <sub>3</sub>	I <sub>OUT</sub> /I <sub>SENSE</sub>	I <sub>OUT</sub> = 4 A; V <sub>SENSE</sub> = 4 V; V <sub>CSD</sub> = 0 V; T <sub>J</sub> = -40°C to 150°C T <sub>J</sub> = 25°C to 150°C	1840 1840	2000 2000	2135 2080	
dK <sub>3</sub> /K <sub>3</sub> <sup>(1)</sup>	Current sense ratio drift	I <sub>OUT</sub> = 4 A; V <sub>SENSE</sub> = 4 V; V <sub>CSD</sub> = 0 V; T <sub>J</sub> = -40 °C to 150 °C	-4		4	%
I <sub>SENSE0</sub>	Analog sense leakage current	I <sub>OUT</sub> = 0 A; V <sub>SENSE</sub> = 0 V; V <sub>CSD</sub> = 5 V; V <sub>IN</sub> = 0 V; T <sub>J</sub> = -40°C to 150°C	0		1	μA
		V <sub>CSD</sub> = 0 V; V <sub>IN</sub> = 5 V; T <sub>J</sub> = -40°C to 150°C	0		2	μA
		I <sub>OUT</sub> = 2 A; V <sub>SENSE</sub> = 0 V; V <sub>CSD</sub> = 5 V; V <sub>IN</sub> = 5 V; T <sub>J</sub> = -40°C to 150°C	0		1	μA
I <sub>OL</sub>	Open-load on-state current detection threshold	V <sub>IN</sub> = 5 V; 8 V < V <sub>CC</sub> < 18 V; I <sub>SENSE</sub> = 5 μA	4		20	mA
V <sub>SENSE</sub>	Max analog sense output voltage	I <sub>OUT</sub> = 4 A; V <sub>CSD</sub> = 0 V	5			V
V <sub>SENSEH</sub>	Analog sense output voltage in fault condition <sup>(2)</sup>	V <sub>CC</sub> = 13 V; R <sub>SENSE</sub> = 3.9 KΩ		8		V
I <sub>SENSEH</sub>	Analog sense output current in fault condition <sup>(2)</sup>	V <sub>CC</sub> = 13 V; V <sub>SENSE</sub> = 5 V		9		mA
t <sub>DSENSE1H</sub>	Delay response time from falling edge of CS_DIS pin	V <sub>SENSE</sub> < 4 V; 0.5 A < I <sub>OUT</sub> < 4 A; I <sub>SENSE</sub> = 90% of I <sub>SENSE max</sub> (see <a href="#">Figure 4</a> )		50	100	μs
t <sub>DSENSE1L</sub>	Delay response time from rising edge of CS_DIS pin	V <sub>SENSE</sub> < 4 V; 0.5 A < I <sub>OUT</sub> < 4 A; I <sub>SENSE</sub> = 10% of I <sub>SENSE max</sub> (see <a href="#">Figure 4</a> )		5	20	μs
t <sub>DSENSE2H</sub>	Delay response time from rising edge of INPUT pin	V <sub>SENSE</sub> < 4 V; 0.5 A < I <sub>OUT</sub> < 4 A; I <sub>SENSE</sub> = 90% of I <sub>SENSE max</sub> (see <a href="#">Figure 4</a> )		80	250	μs

**Table 9. Current sense (8 V < V<sub>CC</sub> < 18 V) (continued)**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$\Delta t_{\text{DSSENSE2H}}$	Delay response time between rising edge of output current and rising edge of current sense	$V_{\text{SENSE}} < 4 \text{ V}$ ; $I_{\text{SENSE}} = 90\%$ of $I_{\text{SENSEMAX}}$ ; $I_{\text{OUT}} = 90\%$ of $I_{\text{OUTMAX}}$ ; $I_{\text{OUTMAX}} = 2 \text{ A}$ (see <a href="#">Figure 7</a> )			40	$\mu\text{s}$
$t_{\text{DSSENSE2L}}$	Delay response time from falling edge of INPUT pin	$V_{\text{SENSE}} < 4 \text{ V}$ ; $0.5 \text{ A} < I_{\text{OUT}} < 4 \text{ A}$ ; $I_{\text{SENSE}} = 10\%$ of $I_{\text{SENSE max}}$ (see <a href="#">Figure 4</a> )		100	250	$\mu\text{s}$

- Parameter guaranteed by design; it is not tested.
- Fault condition includes: power limitation, overtemperature and open-load off-state detection.

**Table 10. Open-load detection (8 V < V<sub>CC</sub> < 18 V)**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{\text{OL}}$	Open-load off-state voltage detection threshold	$V_{\text{IN}} = 0 \text{ V}$	2	See <a href="#">Figure 5</a>	4	V
$t_{\text{DSTKON}}$	Output short circuit to V <sub>CC</sub> detection delay at turn Off	See <a href="#">Figure 5</a>	180		1200	$\mu\text{s}$
$I_{\text{L(off2)r}}$	Off-state output current at $V_{\text{OUT}} = 4 \text{ V}$	$V_{\text{IN}} = 0 \text{ V}$ ; $V_{\text{SENSE}} = 0 \text{ V}$ ; $V_{\text{OUT}}$ rising from 0 V to 4 V	-120		0	$\mu\text{A}$
$I_{\text{L(off2)f}}$	Off-state output current at $V_{\text{OUT}} = 2 \text{ V}$	$V_{\text{IN}} = 0 \text{ V}$ ; $V_{\text{SENSE}} = V_{\text{SENSEH}}$ ; $V_{\text{OUT}}$ falling from V <sub>CC</sub> to 2 V	-50		90	$\mu\text{A}$
$t_{\text{d\_vol}}$	Delay response from output rising edge to V <sub>SENSE</sub> rising edge in open-load	$V_{\text{OUT}} = 4 \text{ V}$ ; $V_{\text{IN}} = 0 \text{ V}$ ; $V_{\text{SENSE}} = 90\%$ of $V_{\text{SENSEH}}$			20	$\mu\text{s}$

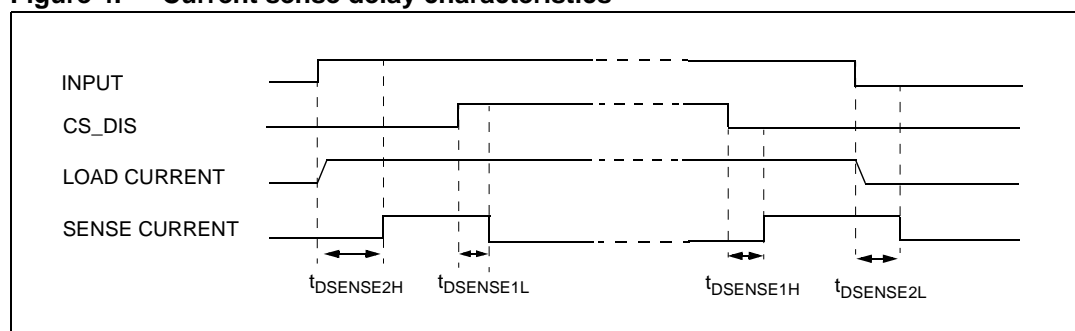
**Figure 4. Current sense delay characteristics**

Figure 5. Open-load off-state delay timing

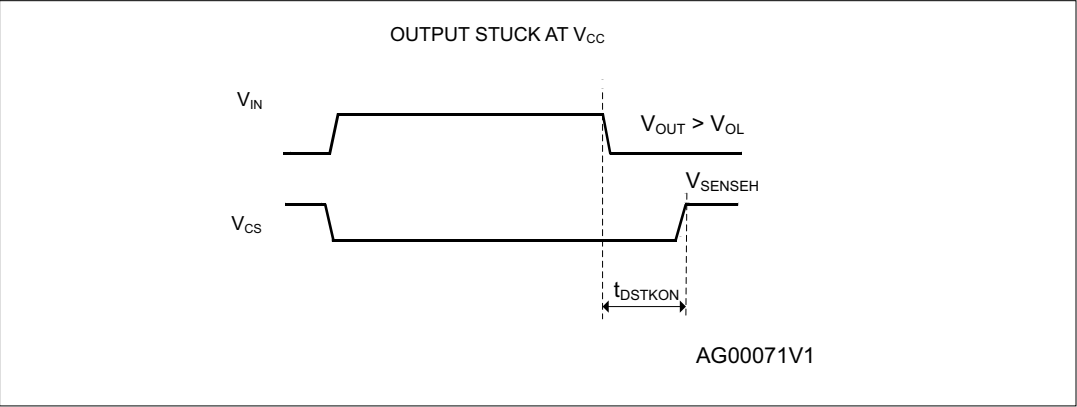


Figure 6. Switching characteristics

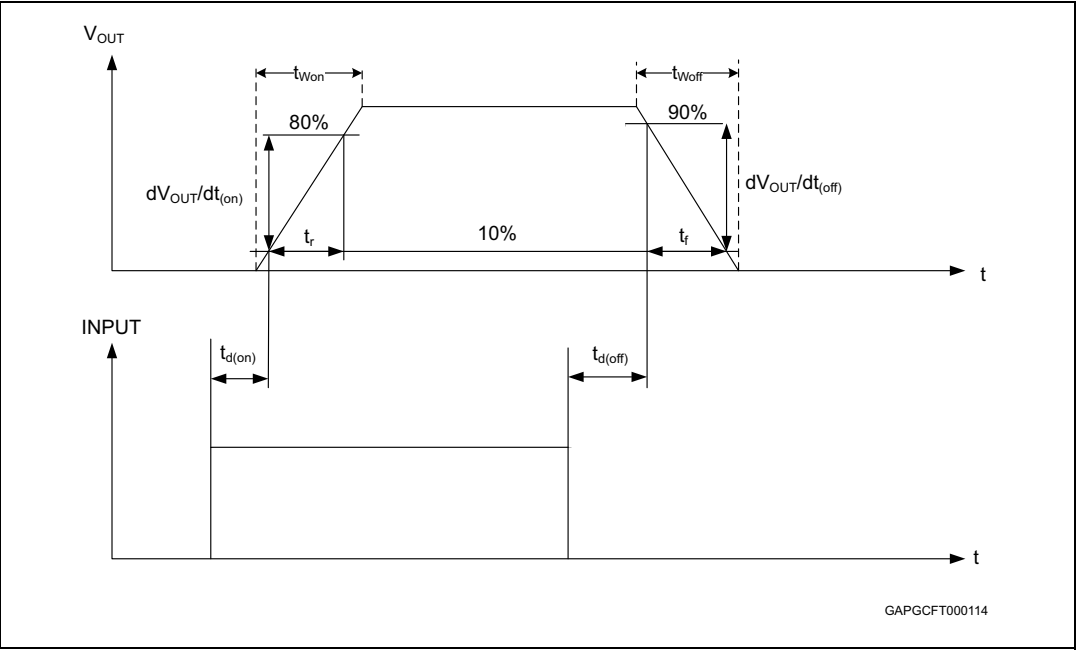


Figure 7. Delay response time between rising edge of output current and rising edge of current sense (CS enabled)

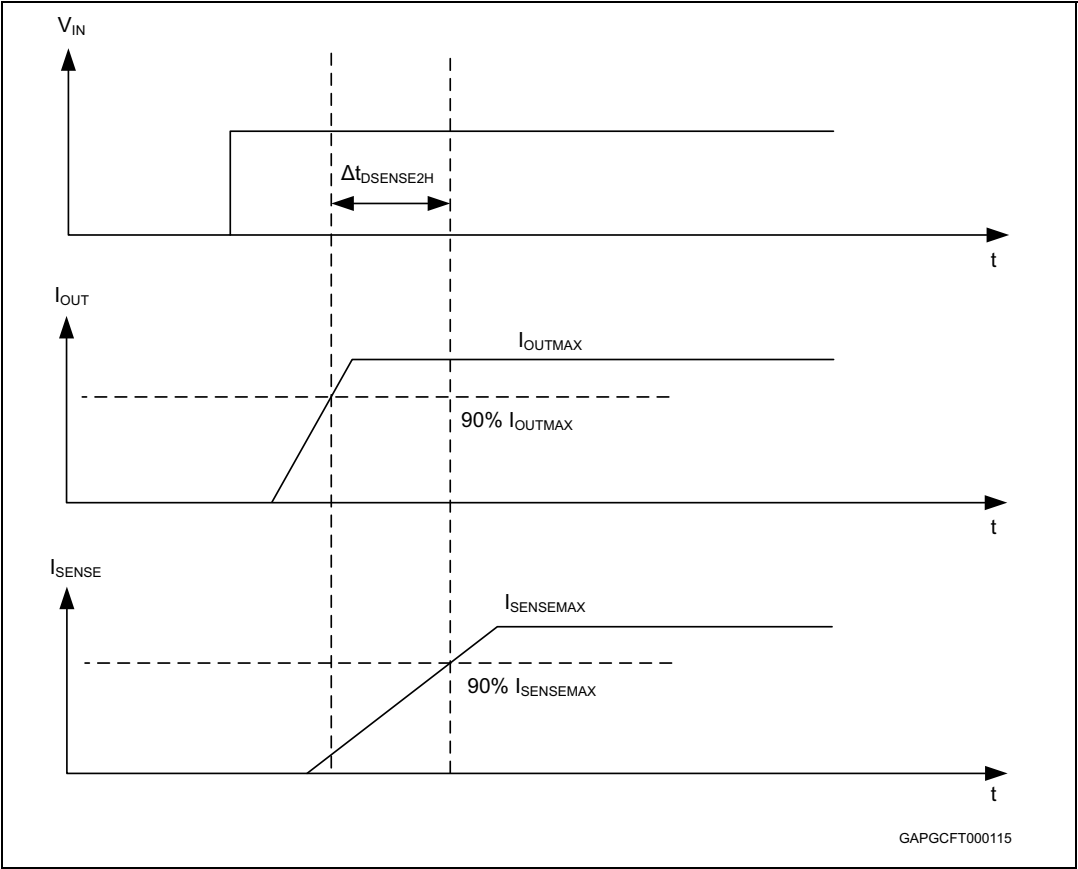


Figure 8. Output voltage drop limitation

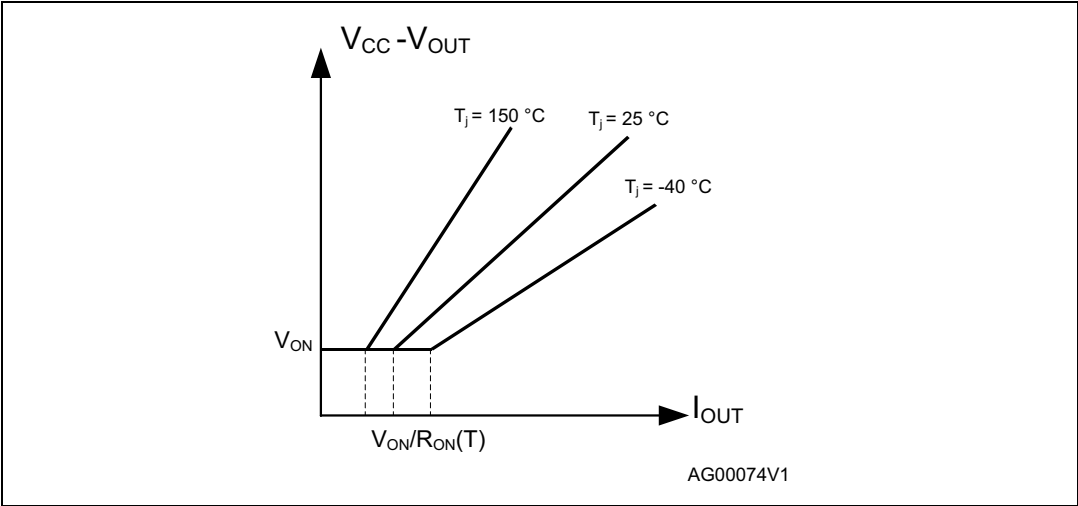


Figure 9.  $I_{OUT}/I_{SENSE}$  vs  $I_{OUT}$

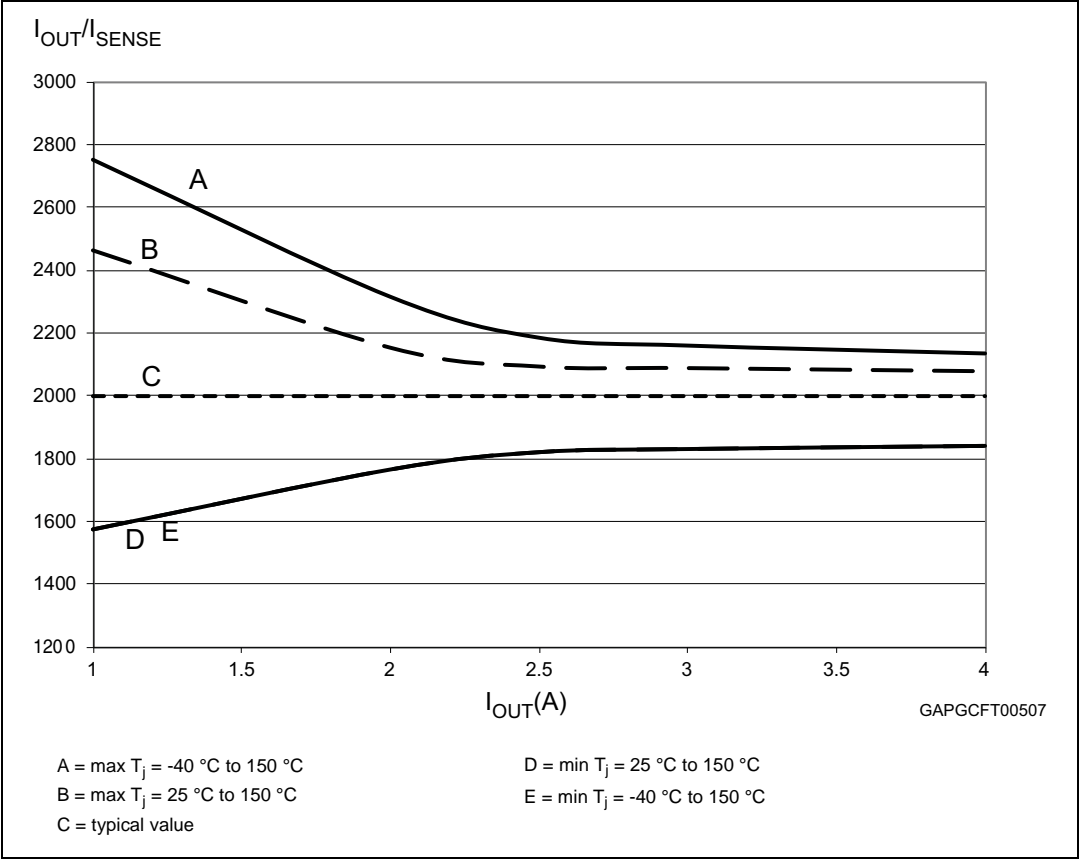
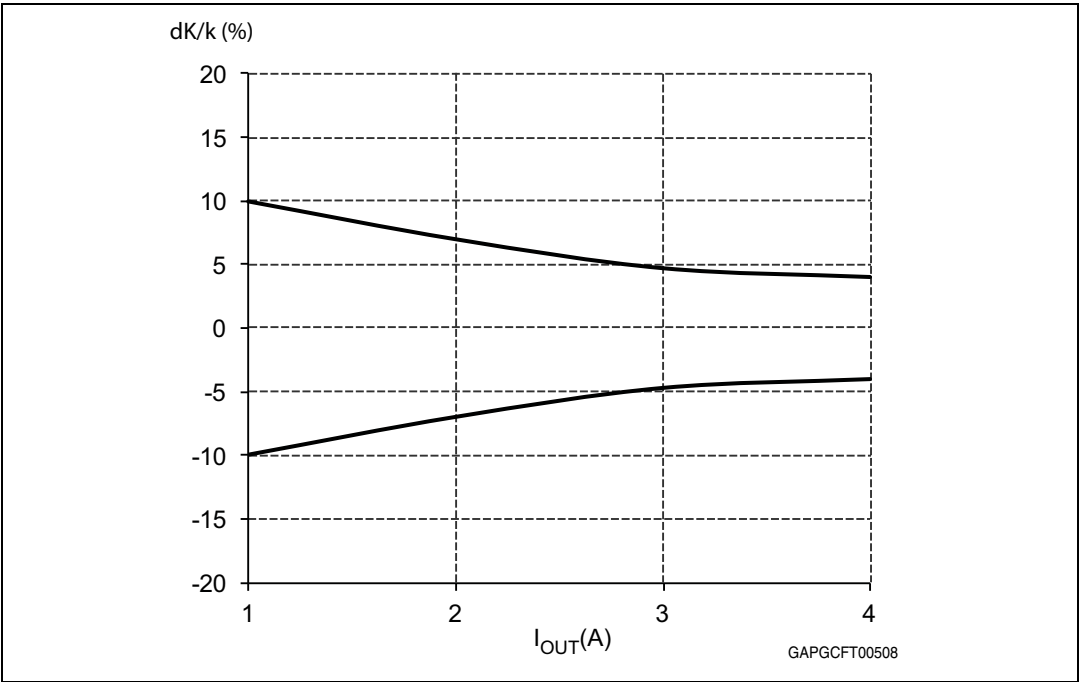


Figure 10. Maximum current sense ratio drift vs load current



Note: Parameter guaranteed by design; it is not tested.

Table 11. Truth table

Conditions	Input	Output	Sense ( $V_{CSD} = 0\text{ V}$ ) <sup>(1)</sup>
Normal operation	L	L	0
	H	H	Nominal
Overtemperature	L	L	0
	H	L	$V_{SENSEH}$
Undervoltage	L	L	0
	H	L	0
Overload	H	X (no power limitation)	Nominal
	H	Cycling (power limitation)	$V_{SENSEH}$
Short circuit to GND (power limitation)	L	L	0
	H	L	$V_{SENSEH}$
Open-load off-state (with external pull-up)	L	H	$V_{SENSEH}$
Short circuit to $V_{CC}$ (external pull-up disconnected)	L	H	$V_{SENSEH}$
	H	H	$V_{SENSEH}$ < Nominal
Negative output voltage clamp	L	L	0

1. If the  $V_{CSD}$  is high, the SENSE output is at a high impedance, its potential depends on leakage currents and external circuit.

**Table 12. Electrical transient requirements (part 1)**

ISO 7637-2: 2004(E) Test pulse	Test levels <sup>(1)</sup>		Number of pulses or test times	Burst cycle/pulse repetition time		Delays and Impedance
	III	IV		Min.	Max.	
1	-75V	-100V	5000 pulses	0.5s	5s	2 ms, 10Ω
2a	+37V	+50V	5000 pulses	0.2s	5s	50μs, 2Ω
3a	-100V	-150V	1h	90ms	100ms	0.1μs, 50Ω
3b	+75V	+100V	1h	90ms	100ms	0.1μs, 50Ω
4	-6V	-7V	1 pulse			100ms, 0.01Ω
5b <sup>(2)</sup>	+65V	+87V	1 pulse			400ms, 2Ω

1. The above test levels must be considered referred to  $V_{CC} = 13.5$  V except for pulse 5b.

2. Valid in case of external load dump clamp: 40 V maximum referred to ground.

**Table 13. Electrical transient requirements (part 2)**

ISO 7637-2: 2004E Test pulse	Test level results	
	III	VI
1	C	C
2a	C	C
3a	C	C
3b	C	C
4	C	C
5b <sup>(1)</sup>	C	C

1. Valid in case of external load dump clamp: 40V maximum referred to ground.

**Table 14. Electrical transient requirements (part 3)**

Class	Contents
C	All functions of the device performed as designed after exposure to disturbance.
E	One or more functions of the device did not perform as designed after exposure to disturbance and cannot be returned to proper operation without replacing the device.

2.4 Waveforms

Figure 11. Normal operation

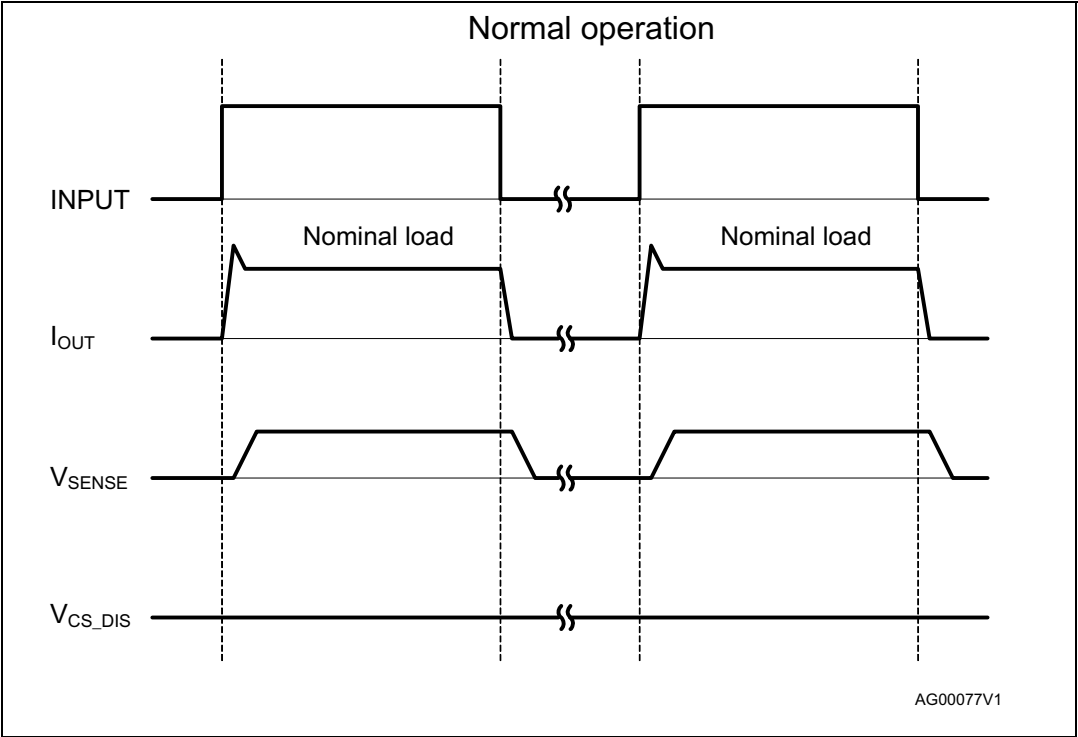


Figure 12. Overload or short to GND

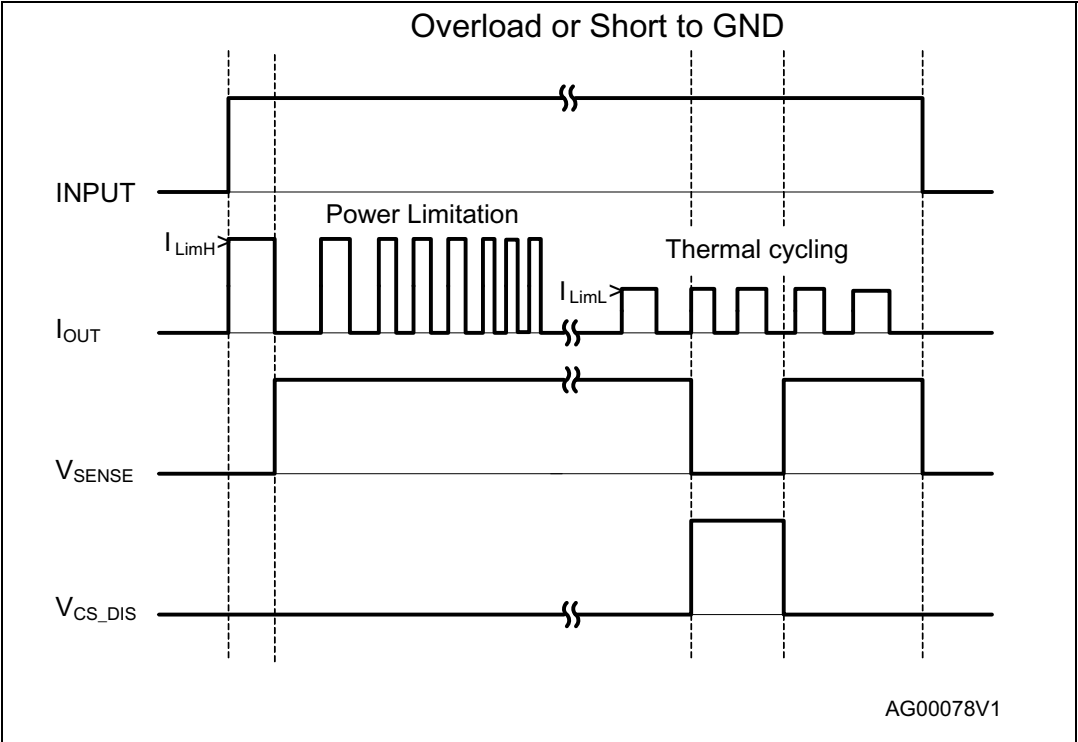


Figure 13. Intermittent overload

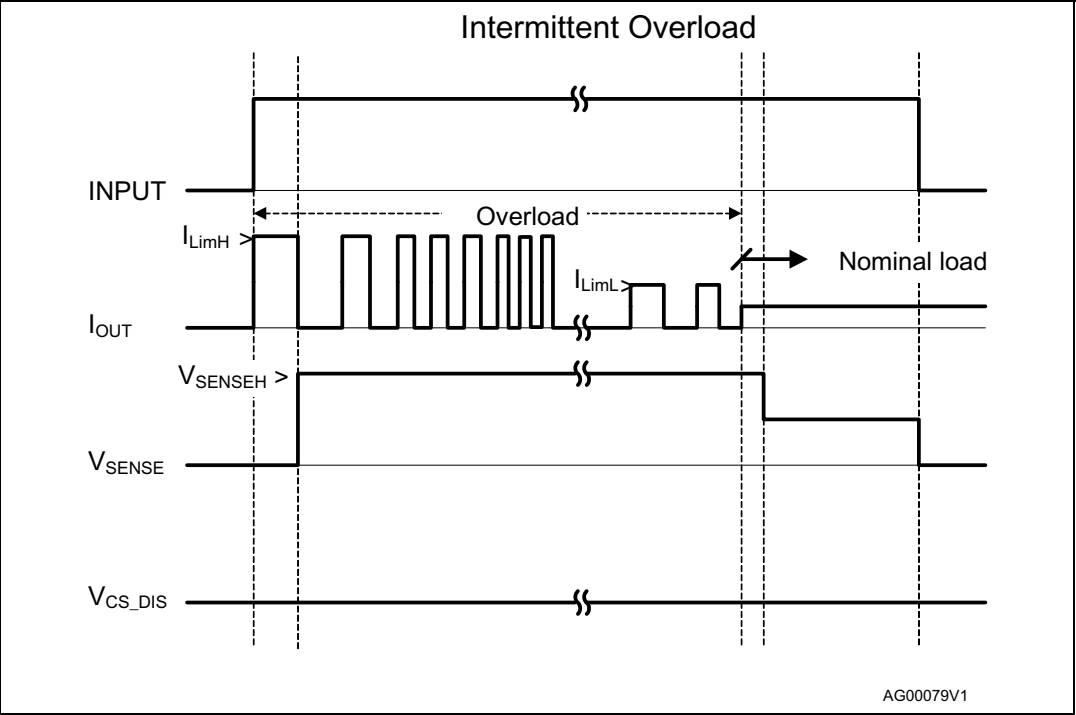


Figure 14. Off-state open-load with external circuitry

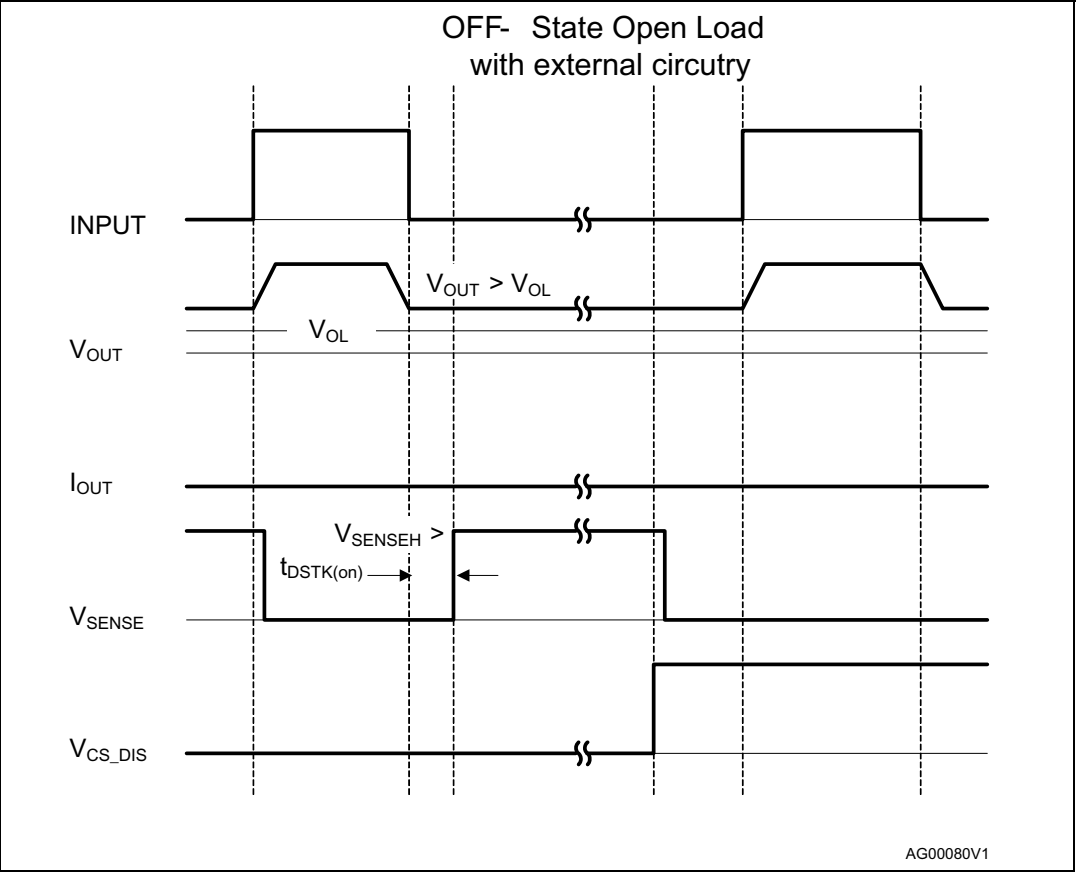


Figure 15. Short to  $V_{CC}$

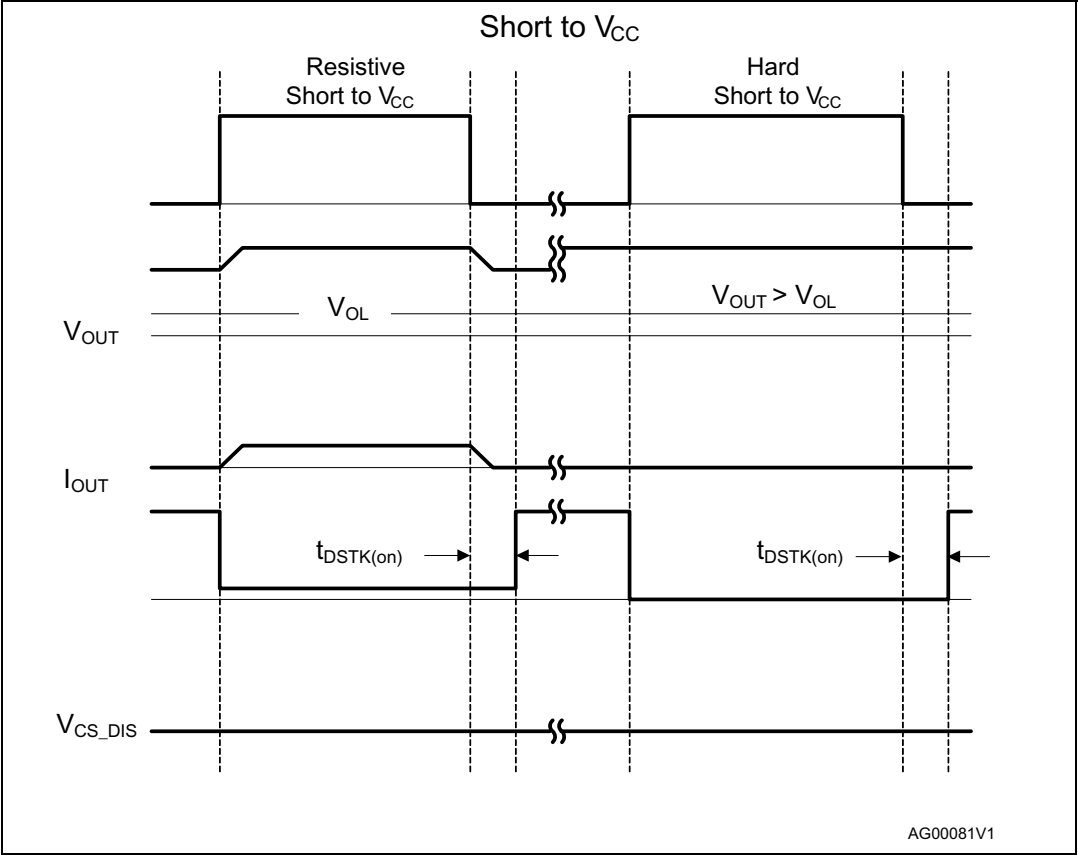
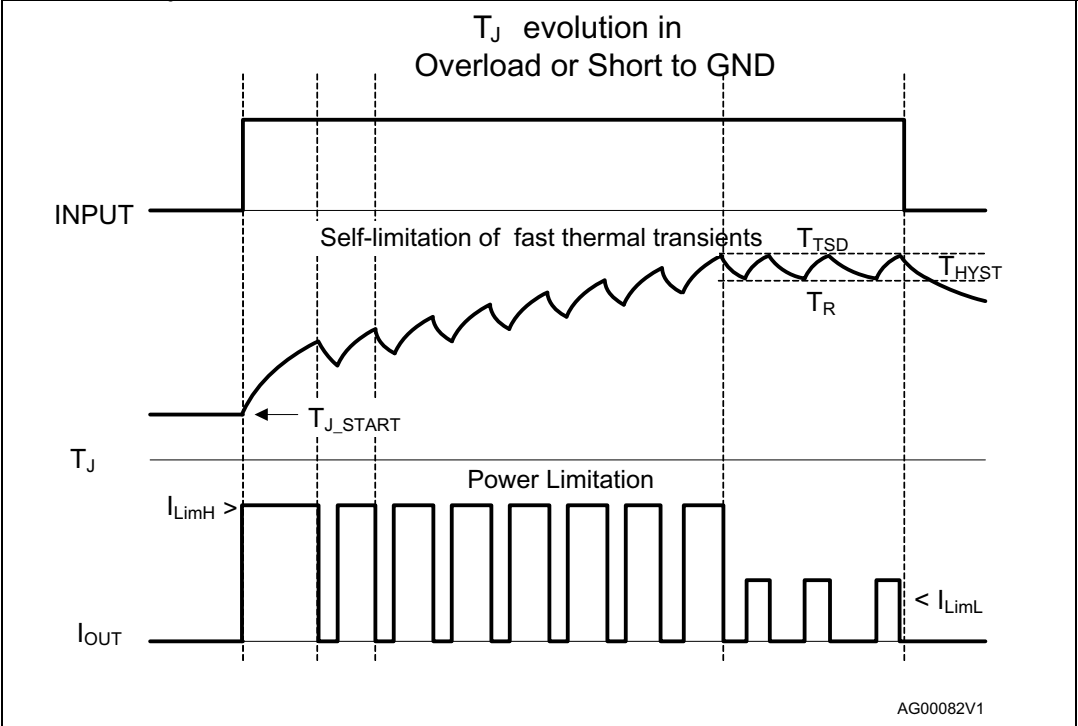


Figure 16.  $T_J$  evolution in over load or short to GND



2.5 Electrical characteristics curves

Figure 17. Off-state output current

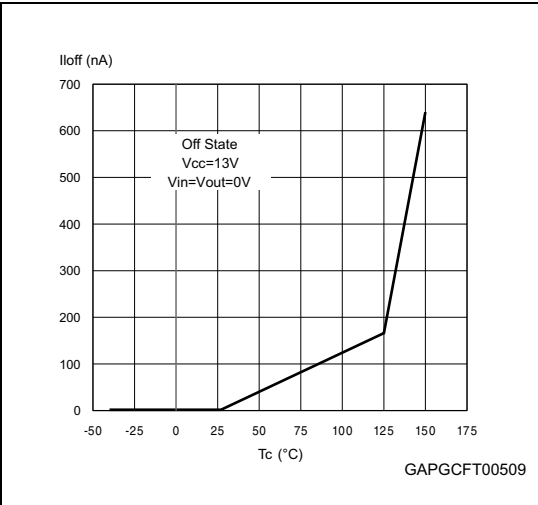


Figure 18. High level input current

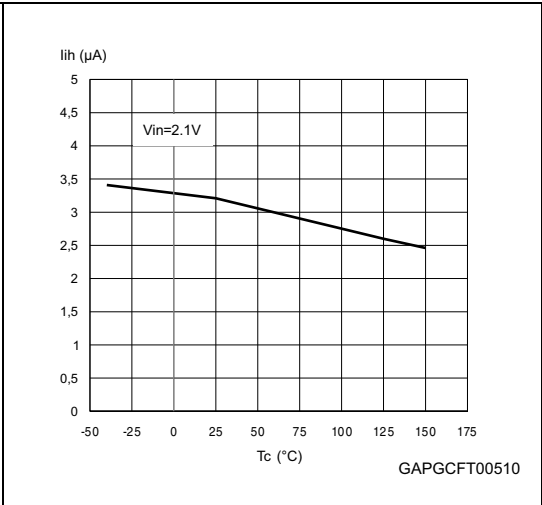


Figure 19. Input clamp level

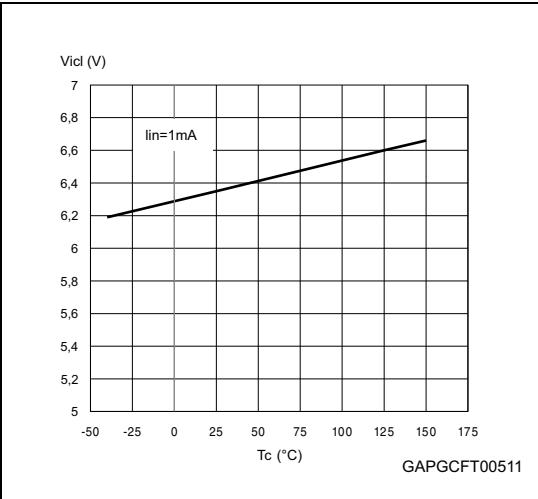


Figure 20. Input low level

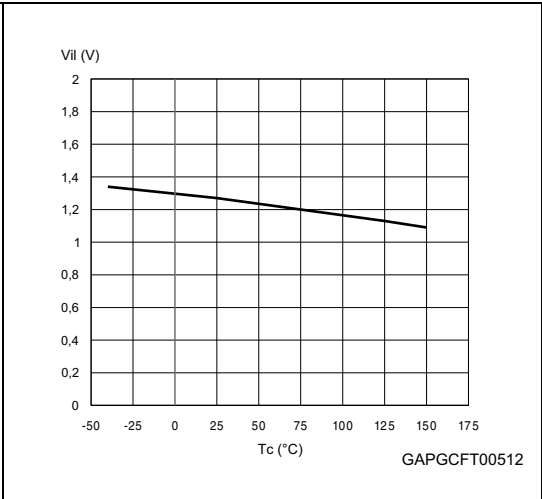


Figure 21. Input high level

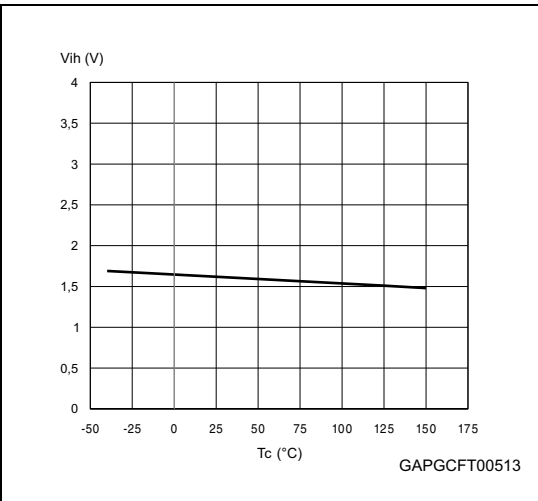


Figure 22. Input hysteresis voltage

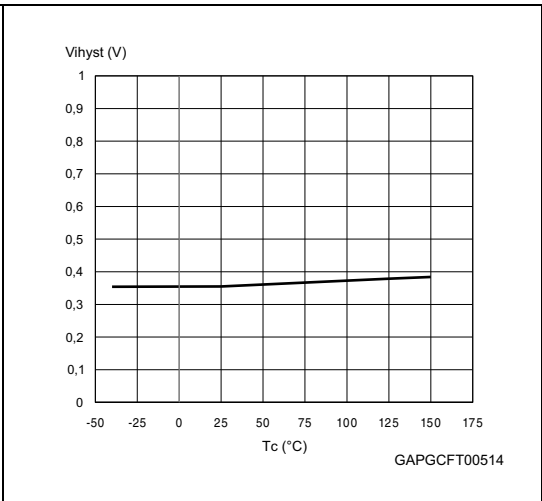


Figure 23. On-state resistance vs  $T_{case}$

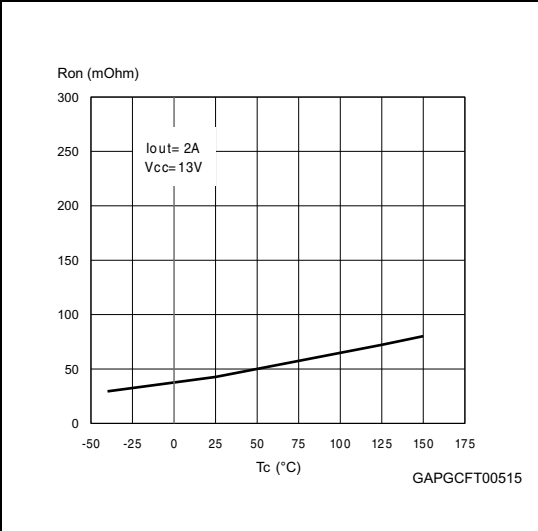


Figure 24. On-state resistance vs  $V_{cc}$

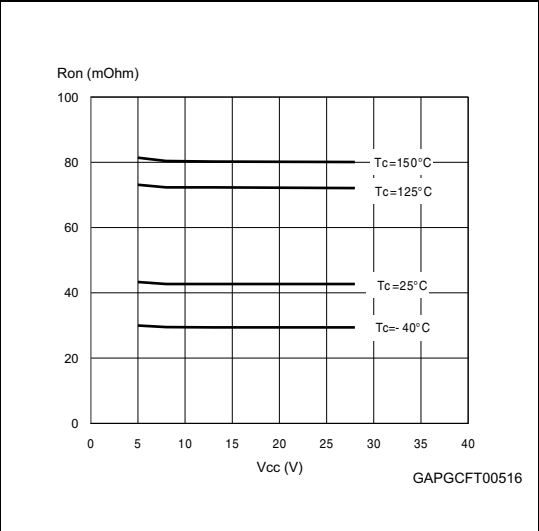


Figure 25. Undervoltage shutdown

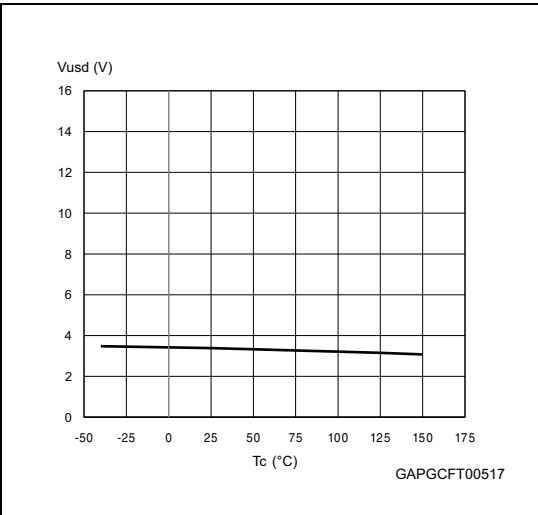


Figure 26. Turn-On voltage slope

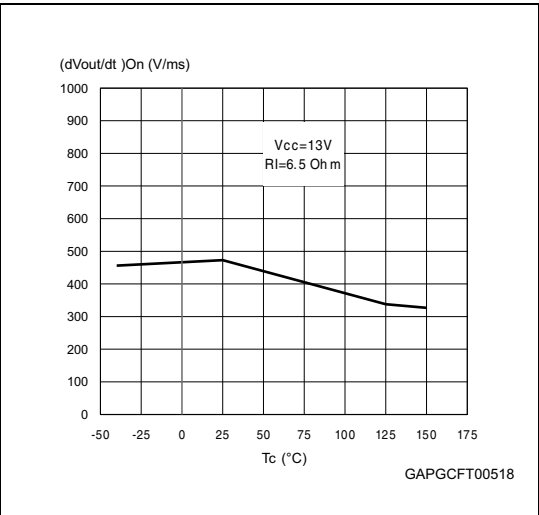


Figure 27.  $I_{limH}$  vs  $T_{case}$

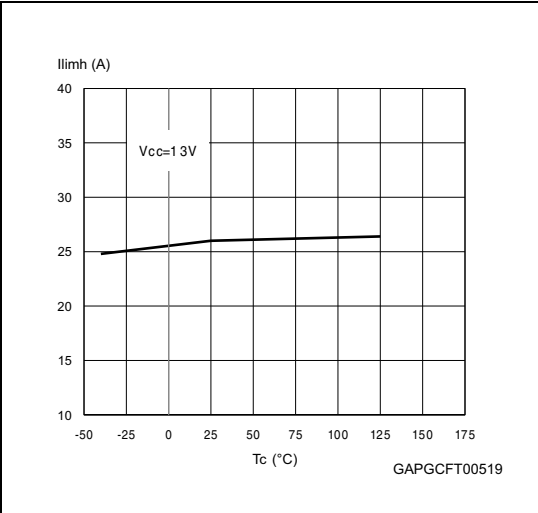


Figure 28. Turn-Off voltage slope

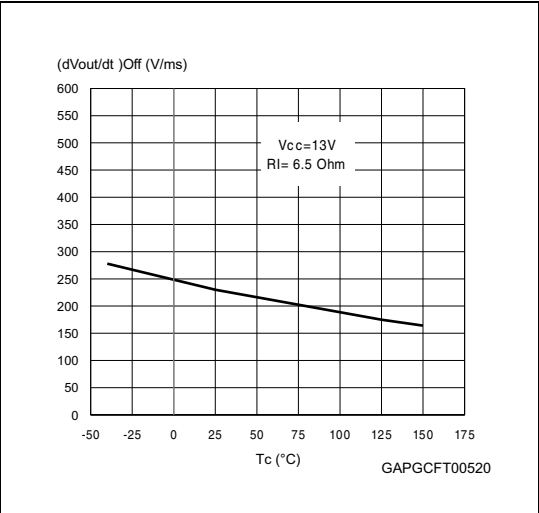


Figure 29. CS\_DIS high level voltage

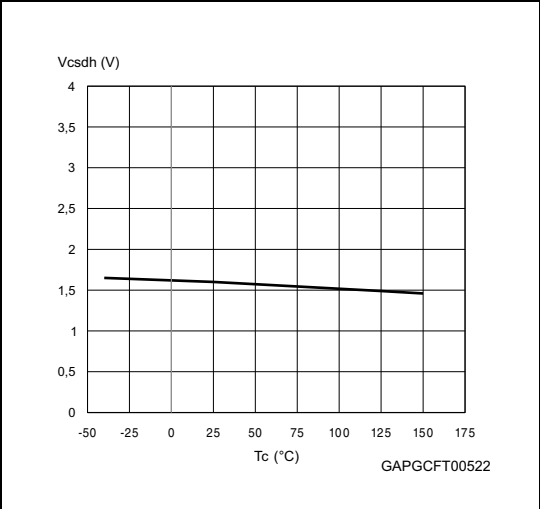


Figure 30. CS\_DIS clamp voltage

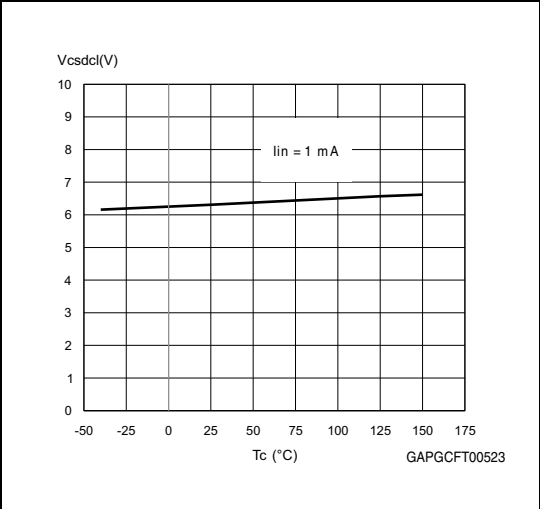
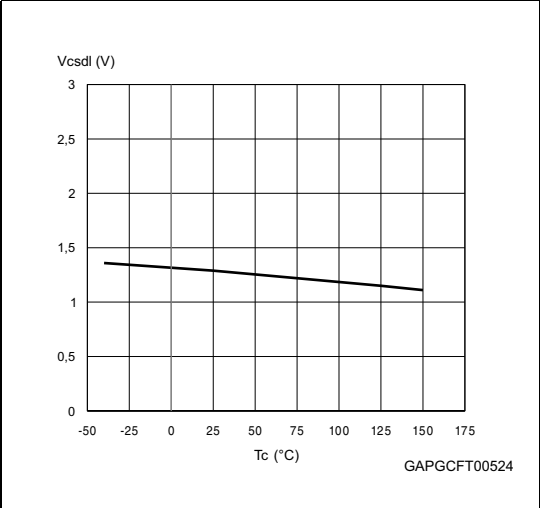
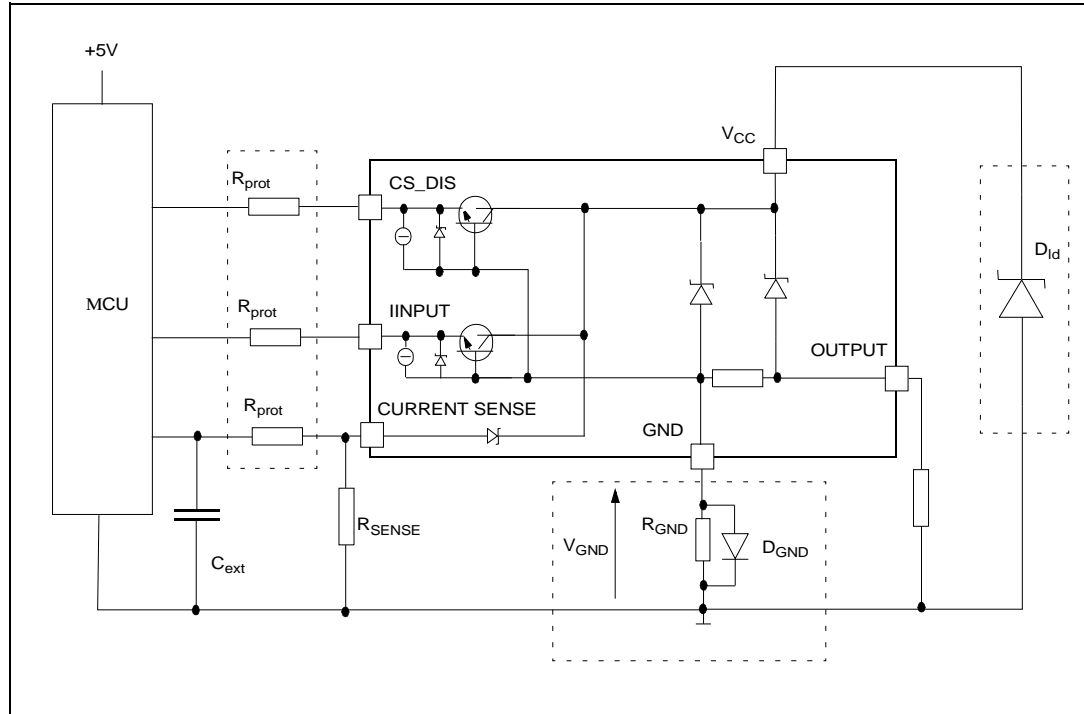


Figure 31. CS\_DIS low level voltage



# 3

**Figure 32. Application schematic**



### 3.1

This section provides two solutions to implement a ground protection network against reverse battery.

### 3.1.1

This can be used with any type of load.

The following description shows how to select the  $R_{GND}$  resistor:

1.  $R_{GND} \leq 600 \text{ mV} / (I_{S(on)max})$
2.  $R_{GND} \geq (-V_{CC}) / (-I_{GND})$

where  $-I_{\text{GND}}$  is the DC reverse ground pin current and can be found in the absolute maximum rating section of the device datasheet.

Power dissipation in  $R_{GND}$  (when  $V_{CC} < 0$  during reverse battery situations) is:

$$P_D = (-V_{CC})^2/R_{GND}$$

This resistor can be shared amongst several different HSDs. Please note that the value of this resistor should be calculated with formula (1) where  $I_{S(on)max}$  becomes the sum of the maximum on-state currents of the different devices.

Please note that, if the microprocessor ground is not shared by the device ground, then the  $R_{GND}$  produces a shift  $(I_{S(on)max} * R_{GND})$  in the input thresholds and in the status output

values. This shift varies depending on how many devices are ON in case of several high side drivers sharing the same  $R_{GND}$ .

If the calculated power dissipation requires the use of a large resistor, or several devices have to share the same resistor, then ST suggests to utilize [Section 3.1.2: Solution 2: diode \( \$D\_{GND}\$ \) in the ground line](#).

### 3.1.2 Solution 2: diode ( $D_{GND}$ ) in the ground line

Note that a resistor ( $R_{GND} = 1\text{ k}\Omega$ ) should be inserted in parallel to  $D_{GND}$  if the device drives an inductive load.

This small signal diode can be safely shared amongst several different HSDs. Also in this case, the presence of the ground network will produce a shift ( $\approx 600\text{ mV}$ ) in the input threshold and in the status output values if the microprocessor ground is not common to the device ground. This shift will not vary if more than one HSD shares the same diode/resistor network.

## 3.2 Load dump protection

$D_{ld}$  is necessary (Voltage Transient Suppressor) if the load dump peak voltage exceeds the  $V_{CC}$  maximum DC rating. The same applies if the device is subject to transients on the  $V_{CC}$  line which are greater than the ones shown in the ISO 7637-2: 2004(E) table.

## 3.3 MCU I/O protection

If a ground protection network is used and negative transients are present on the  $V_{CC}$  line, the control pins are pulled negative. ST suggests to insert a resistor ( $R_{prot}$ ) in line to prevent the microcontroller I/O pins from latching up.

The value of these resistors is a compromise between the leakage current of microcontroller and the current required by the HSD I/Os (Input levels compatibility) with the latch-up limit of microcontroller I/Os:

$$-V_{CCpeak}/I_{latchup} \leq R_{prot} \leq (V_{OH\mu C} - V_{IH} - V_{GND}) / I_{IHmax}$$

Calculation example:

For  $V_{CCpeak} = -100\text{ V}$  and  $I_{latchup} \geq 20\text{ mA}$ ;  $V_{OH\mu C} \geq 4.5\text{ V}$

$$5\text{ k}\Omega \leq R_{prot} \leq 180\text{ k}\Omega$$

Recommended values:  $R_{prot} = 10\text{ k}\Omega$ ,  $C_{EXT} = 10\text{ nF}$ .

## 3.4 Current sense and diagnostic

The current sense pin performs a double function (see [Figure 33: Current sense and diagnostic](#)):

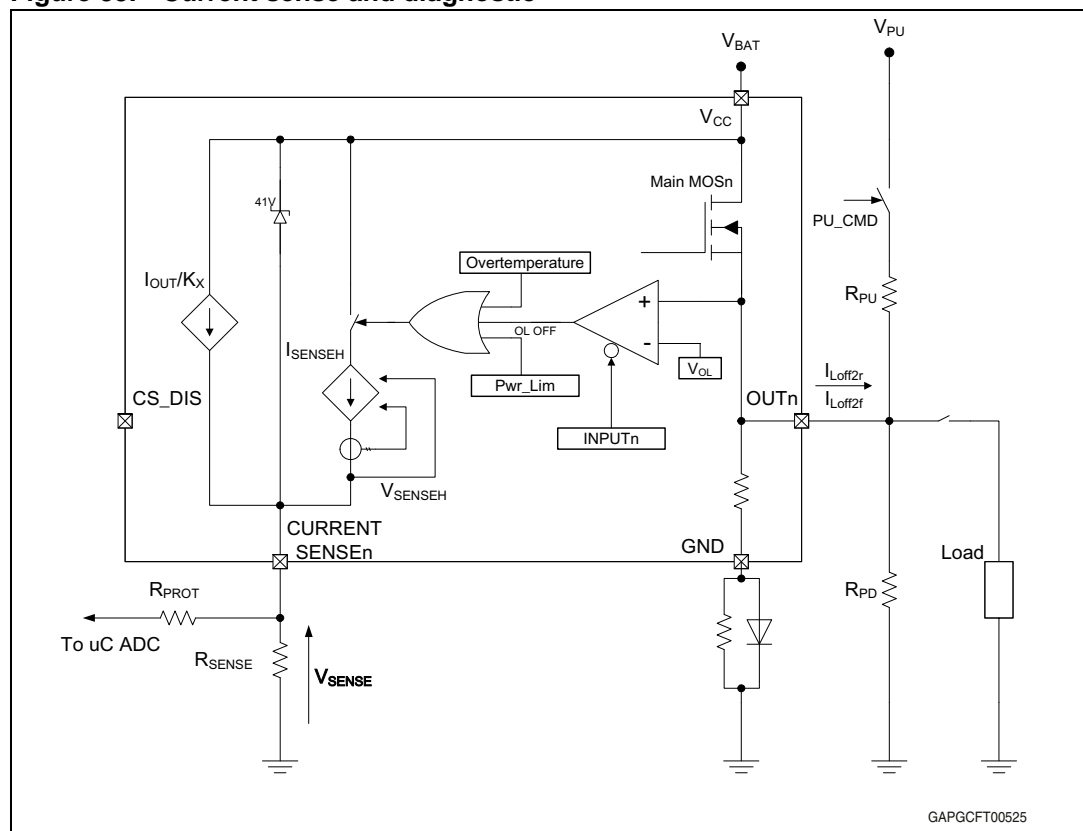
- **Current mirror of the load current in normal operation**, delivering a current proportional to the load current according to a known ratio  $K_X$ .  
The current  $I_{SENSE}$  can be easily converted to a voltage  $V_{SENSE}$  by means of an external resistor  $R_{SENSE}$ . Linearity between  $I_{OUT}$  and  $V_{SENSE}$  is ensured up to 5V minimum (see parameter  $V_{SENSE}$  in [Table 9: Current sense \(8 V < VCC < 18 V\)](#)). The

current sense accuracy depends on the output current (refer to current sense electrical characteristics [Table 9: Current sense \(8 V < VCC < 18 V\)](#)).

- **Diagnostic flag in fault conditions**, delivering a fixed voltage  $V_{SENSEH}$  up to a maximum current  $I_{SENSEH}$  in case of the following fault conditions (refer to [Table 11: Truth table](#)):
  - Power limitation activation
  - Overtemperature
  - Short to  $V_{CC}$  in off-state
  - Open-load in off-state with additional external components.

A logic level high the CS\_DIS pin simultaneously sets all the current sense pins of the device in a high impedance state, thus disabling the current monitoring and diagnostic detection. This feature allows multiplexing of the microcontroller analog inputs by sharing the sense resistance and ADC line among different devices.

### Figure 33. Current sense and diagnostic



### 3.4.1 Short to $V_{CC}$ and off-state open-load detection

### Short to $V_{CC}$

A short circuit between  $V_{CC}$  and output is indicated by the relevant current sense pin set to  $V_{SENSEH}$  during the device off-state. Little or no current is delivered by the current sense during the on-state depending on the nature of the short circuit.

**Off-state open-load with external circuitry**

Detection of an open-load in off mode requires an external pull-up resistor ( $R_{PU}$ ) connecting the output to a positive supply voltage ( $V_{PU}$ ).

It is preferable that  $V_{PU}$  is switched off during the module standby mode to avoid an increase in overall standby current consumption in normal conditions, that is, when the load is connected.

An external pull-down resistor ( $R_{PD}$ ) connected between output and GND is mandatory to avoid misdetection in case of floating outputs in off-state (see [Figure 33: Current sense and diagnostic](#)).

$R_{PD}$  must be selected in order to ensure  $V_{OUT} < V_{OLmin}$  unless pulled up by the external circuitry:

$$V_{OUT}|_{Pull-up\_OFF} = R_{PD} \cdot I_{L(off)2f} < V_{OLmin} = 2V$$

$R_{PD} \leq 22 \text{ K}\Omega$  is recommended.

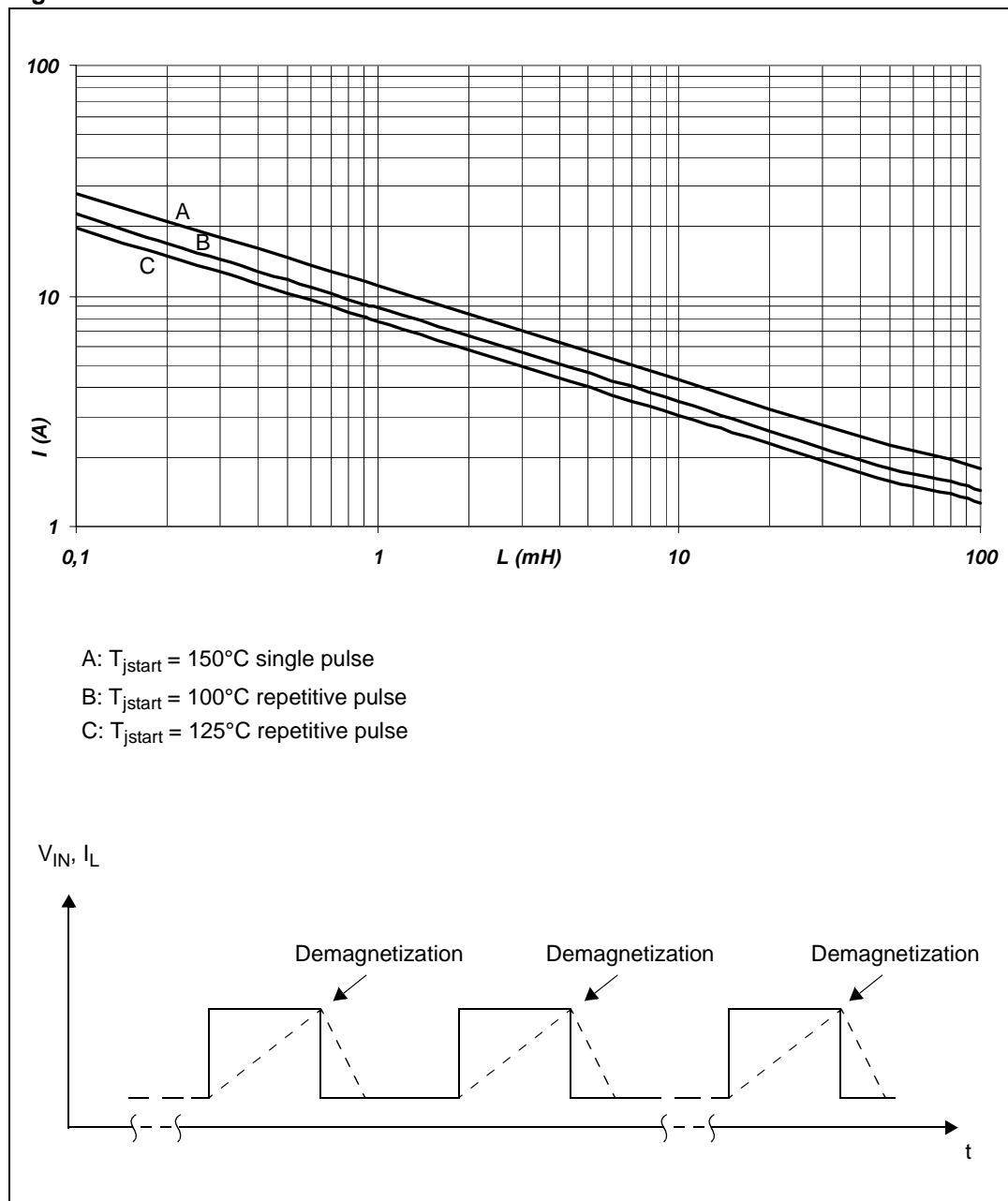
For proper open-load detection in off-state, the external pull-up resistor must be selected according to the following formula:

$$V_{OUT}|_{Pull-up\_ON} = \frac{R_{PD} \cdot V_{PU} - R_{PU} \cdot R_{PD} \cdot I_{L(off)2r}}{R_{PU} + R_{PD}} > V_{OLmax} = 4V$$

For the values of  $V_{OLmin}$ ,  $V_{OLmax}$ ,  $I_{L(off)2r}$  and  $I_{L(off)2f}$  see [Table 10: Open-load detection \(8 V < VCC < 18 V\)](#).

### 3.5 Maximum demagnetization energy ( $V_{CC} = 13.5V$ )

Figure 34. Maximum turn-Off current versus inductance

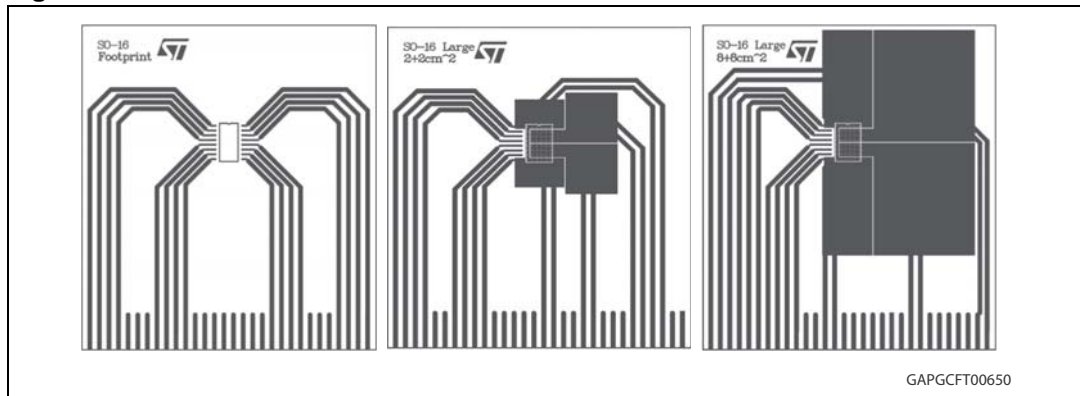


**Note:** Values are generated with  $R_L = 0 \Omega$ . In case of repetitive pulses,  $T_{jstart}$  (at the beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves A and B.

## 4 Package and PCB thermal data

### 4.1 SO-16L thermal data

Figure 35. SO-16L PC board



Note: Layout condition of  $R_{th}$  and  $Z_{th}$  measurements (PCB: Double layer, Thermal Vias, FR4 area = 77 mm x 86 mm, PCB thickness = 1.6 mm, Cu thickness = 70  $\mu$ m (front and back side), Copper areas: from minimum pad lay-out to 8 cm<sup>2</sup>).

Figure 36.  $R_{thj-amb}$  vs PCB copper area in open box free air condition

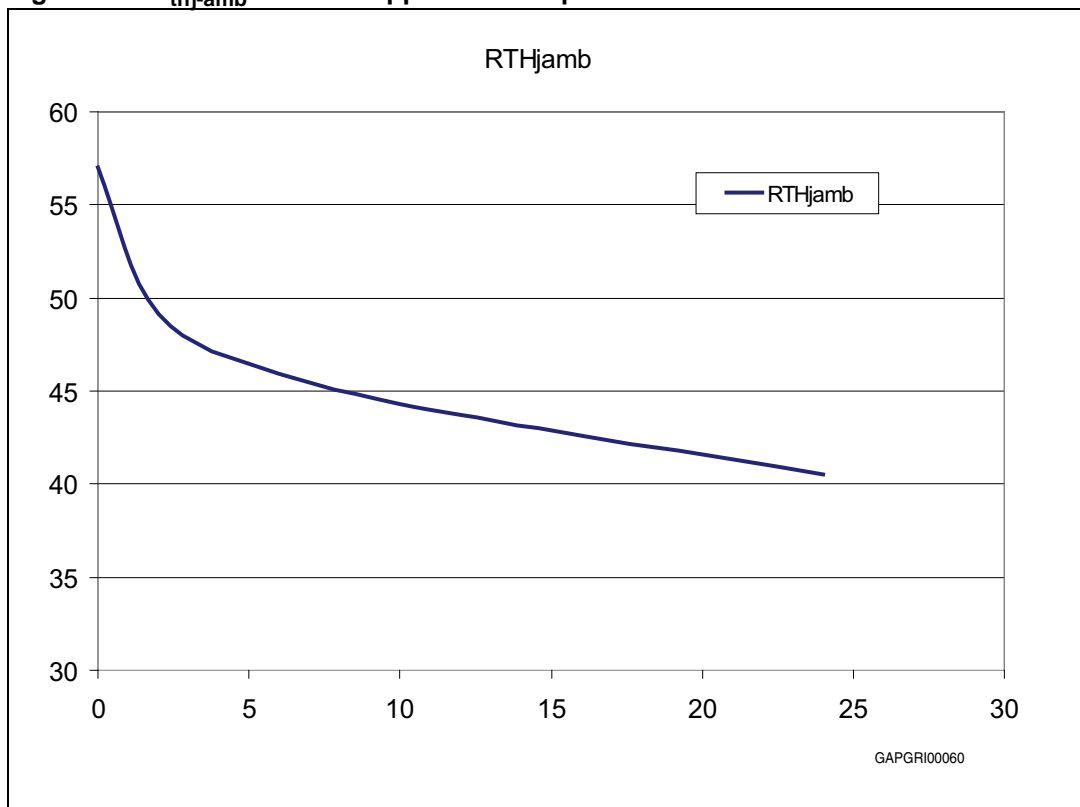
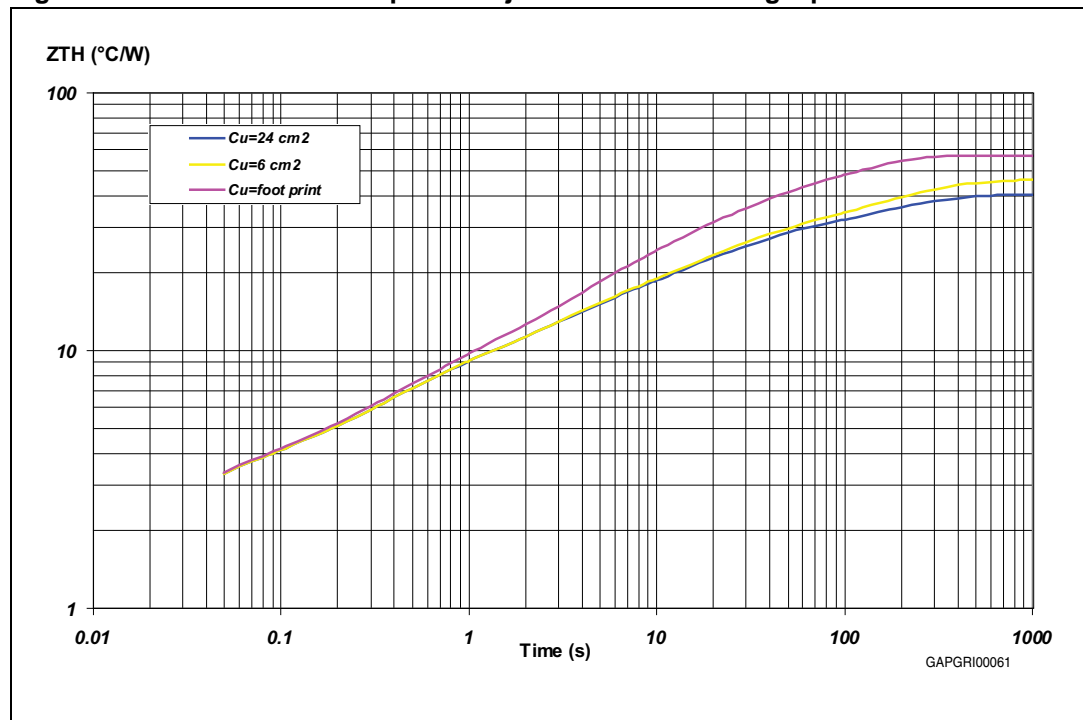


Figure 37. SO-16L thermal impedance junction ambient single pulse

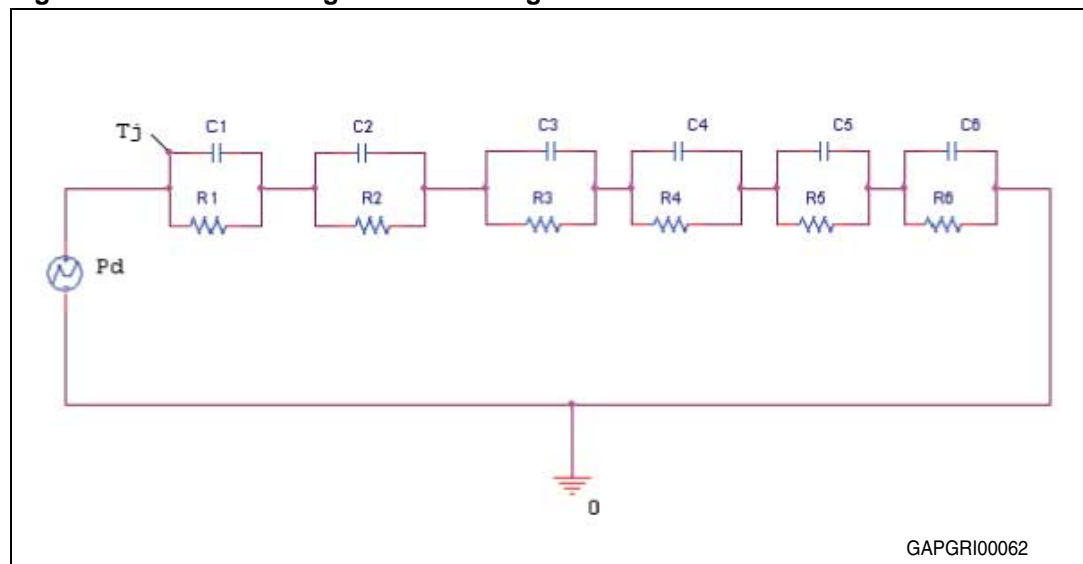


Equation 1: pulse calculation formula

$$Z_{TH\delta} = R_{TH} \cdot \delta + Z_{THtp}(1 - \delta)$$

where  $\delta = t_p/T$

Figure 38. Thermal fitting model of a single channel HSD in SO-16L (a)



- a. The fitting model is a simplified thermal tool and is valid for transient evolutions where the embedded protections (power limitation or thermal cycling during thermal shutdown) are not triggered.

Table 15. Thermal parameter

Area/island (cm <sup>2</sup> )	Footprint	2	8
R1 (°C/W)	0.7		
R2 (°C/W)	2.3		
R3 (°C/W)	4		
R4 (°C/W)	8	6	6
R5 (°C/W)	14	13	13
R6 (°C/W)	28	20	14.5
C1 (W.s/°C)	0.001		
C2 (W.s/°C)	0.01		
C3 (W.s/°C)	0.1		
C4 (W.s/°C)	0.5		
C5 (W.s/°C)	1	1.5	1.5
C6 (W.s/°C)	3	9	12

## 5 Package information

### 5.1 ECOPACK® packages

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com).

ECOPACK® is an ST trademark.

### 5.2 Package mechanical data

Figure 39. SO-16L package dimensions

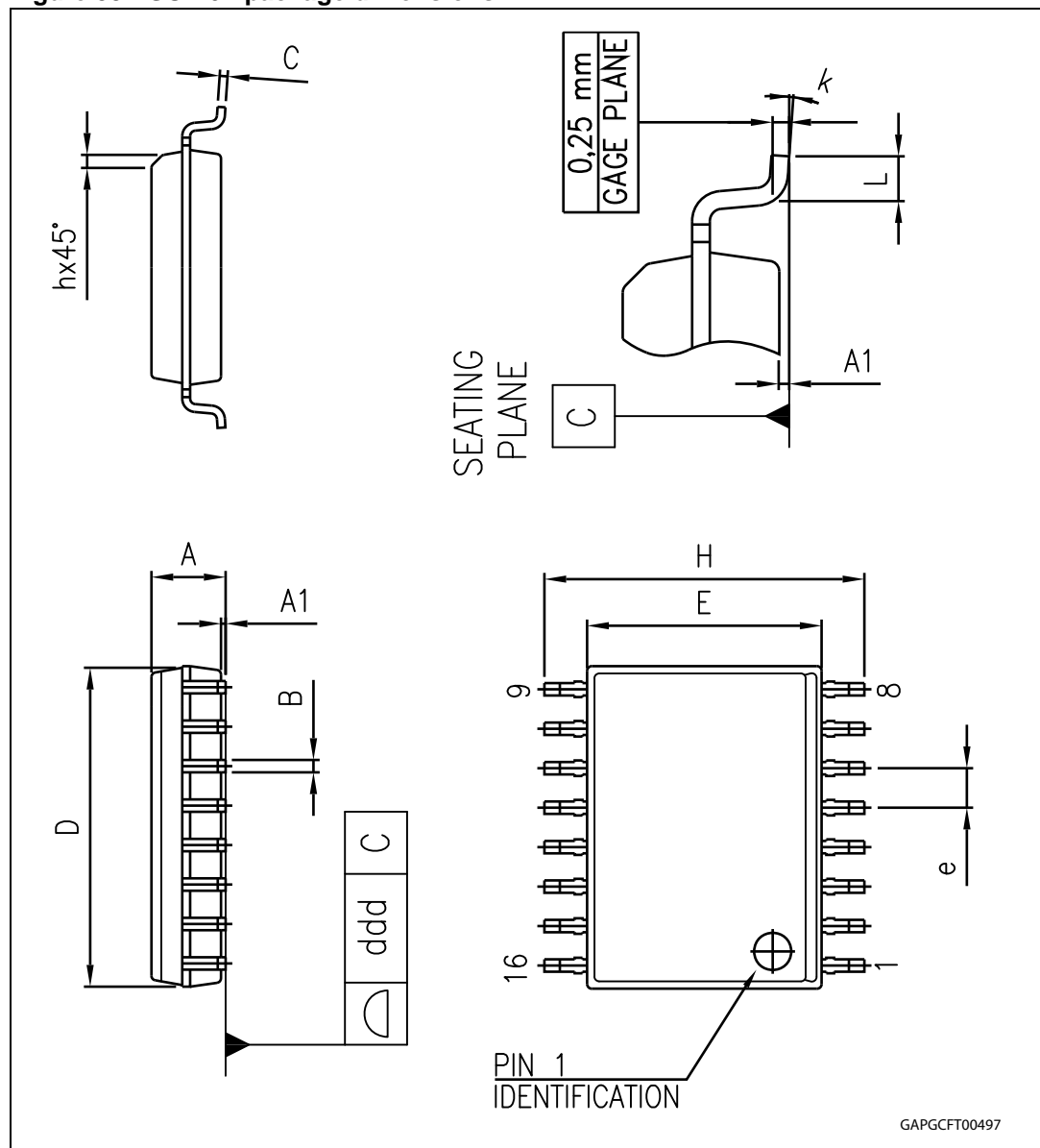


Table 16. SO-16L mechanical data

Symbol	Millimeters		
	Min	Typ	Max
A	2.35		2.65
A1	0.10		0.30
B	0.33		0.51
C	0.23		0.32
D	10.10		10.50
E	7.40		7.60
e		1.27	
H	10.00		10.65
h	0.25		0.75
L	0.40		1.27
k	0°		8°
ddd			0.10

## 5.3 Packing information

Figure 40. SO-16L tube shipment (no suffix)

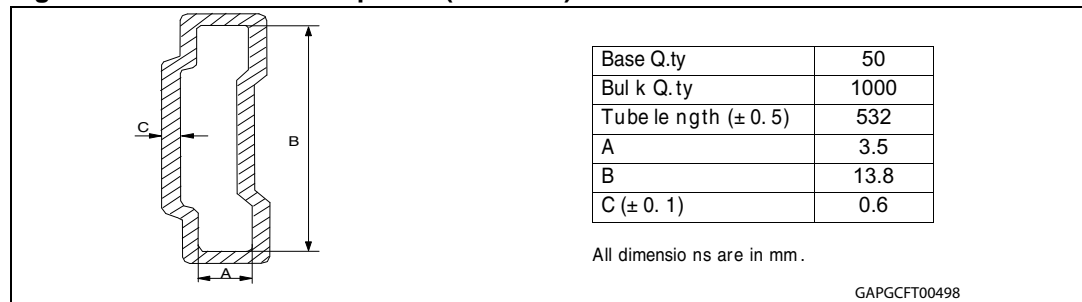
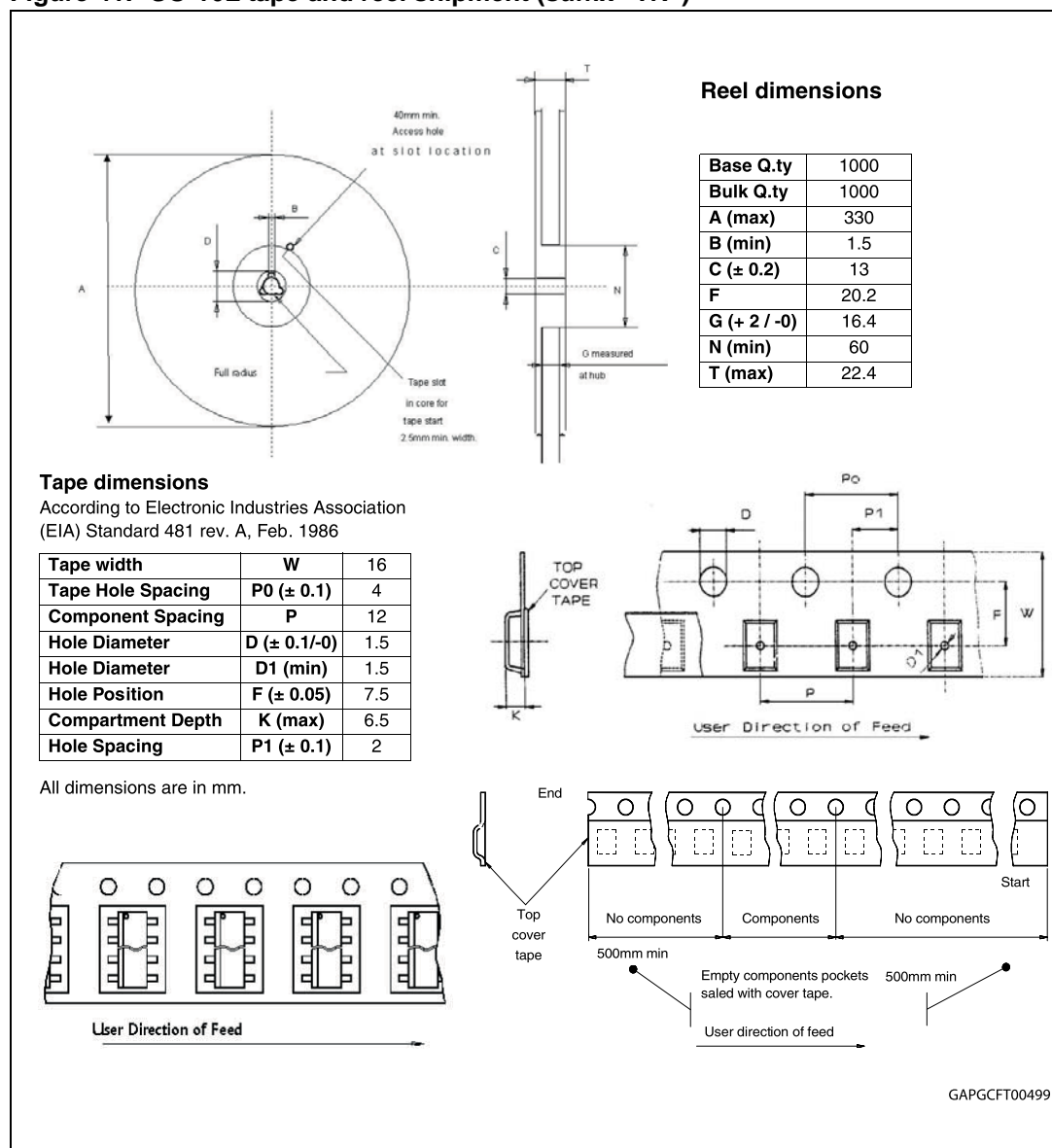


Figure 41. SO-16L tape and reel shipment (suffix "TR")



## 6 Order codes

Table 17. Device summary

Package	Order codes	
	Tube	Tape and reel
SO-16L	VN5E050ASO-E	VN5E050ASOTR-E

## 7 Revision history

**Table 18. Document revision history**

Date	Revision	Changes
14-Dec-2011	1	Initial release
16-Mar-2012	2	Added <a href="#">Section 4: Package and PCB thermal data</a> and update <a href="#">Table 5</a> .
25-June-2012	3	Update <a href="#">Table 4</a> .
18-Sep-2012	4	Update <a href="#">Table 4</a> .
18-Sep-2013	5	Updated disclaimer.

**Please Read Carefully:**

Information in this document is provided solely in connection with ST products. STMicroelectronics NV and its subsidiaries ("ST") reserve the right to make changes, corrections, modifications or improvements, to this document, and the products and services described herein at any time, without notice.

All ST products are sold pursuant to ST's terms and conditions of sale.

Purchasers are solely responsible for the choice, selection and use of the ST products and services described herein, and ST assumes no liability whatsoever relating to the choice, selection or use of the ST products and services described herein.

No license, express or implied, by estoppel or otherwise, to any intellectual property rights is granted under this document. If any part of this document refers to any third party products or services it shall not be deemed a license grant by ST for the use of such third party products or services, or any intellectual property contained therein or considered as a warranty covering the use in any manner whatsoever of such third party products or services or any intellectual property contained therein.

**UNLESS OTHERWISE SET FORTH IN ST'S TERMS AND CONDITIONS OF SALE ST DISCLAIMS ANY EXPRESS OR IMPLIED WARRANTY WITH RESPECT TO THE USE AND/OR SALE OF ST PRODUCTS INCLUDING WITHOUT LIMITATION IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE (AND THEIR EQUIVALENTS UNDER THE LAWS OF ANY JURISDICTION), OR INFRINGEMENT OF ANY PATENT, COPYRIGHT OR OTHER INTELLECTUAL PROPERTY RIGHT.**

**ST PRODUCTS ARE NOT DESIGNED OR AUTHORIZED FOR USE IN: (A) SAFETY CRITICAL APPLICATIONS SUCH AS LIFE SUPPORTING, ACTIVE IMPLANTED DEVICES OR SYSTEMS WITH PRODUCT FUNCTIONAL SAFETY REQUIREMENTS; (B) AERONAUTIC APPLICATIONS; (C) AUTOMOTIVE APPLICATIONS OR ENVIRONMENTS, AND/OR (D) AEROSPACE APPLICATIONS OR ENVIRONMENTS. WHERE ST PRODUCTS ARE NOT DESIGNED FOR SUCH USE, THE PURCHASER SHALL USE PRODUCTS AT PURCHASER'S SOLE RISK, EVEN IF ST HAS BEEN INFORMED IN WRITING OF SUCH USAGE, UNLESS A PRODUCT IS EXPRESSLY DESIGNATED BY ST AS BEING INTENDED FOR "AUTOMOTIVE, AUTOMOTIVE SAFETY OR MEDICAL" INDUSTRY DOMAINS ACCORDING TO ST PRODUCT DESIGN SPECIFICATIONS. PRODUCTS FORMALLY ESCC, QML OR JAN QUALIFIED ARE DEEMED SUITABLE FOR USE IN AEROSPACE BY THE CORRESPONDING GOVERNMENTAL AGENCY.**

Resale of ST products with provisions different from the statements and/or technical features set forth in this document shall immediately void any warranty granted by ST for the ST product or service described herein and shall not create or extend in any manner whatsoever, any liability of ST.

ST and the ST logo are trademarks or registered trademarks of ST in various countries.

Information in this document supersedes and replaces all information previously supplied.

The ST logo is a registered trademark of STMicroelectronics. All other names are the property of their respective owners.

© 2013 STMicroelectronics - All rights reserved

STMicroelectronics group of companies

Australia - Belgium - Brazil - Canada - China - Czech Republic - Finland - France - Germany - Hong Kong - India - Israel - Italy - Japan - Malaysia - Malta - Morocco - Philippines - Singapore - Spain - Sweden - Switzerland - United Kingdom - United States of America

[www.st.com](http://www.st.com)

