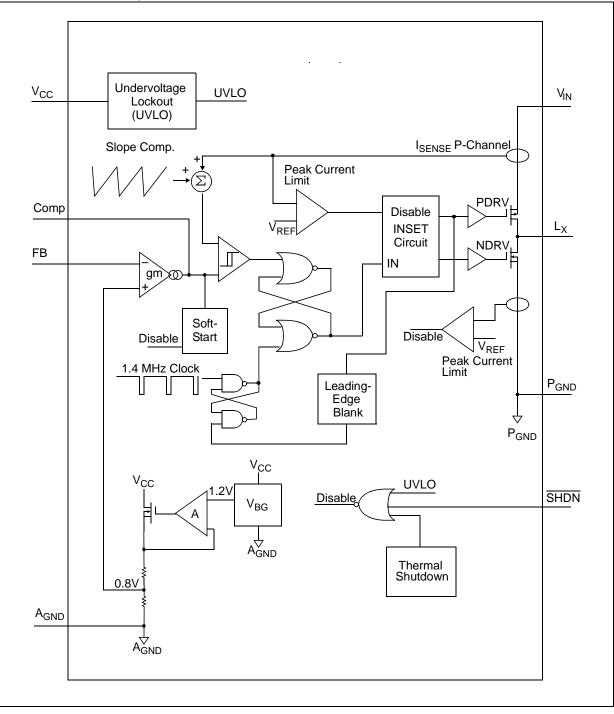
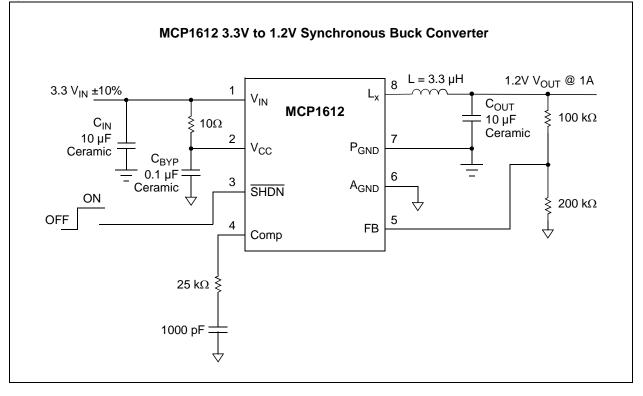
## **Functional Block Diagram**



DS21921C-page 2

## **Typical Application Circuit**



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## 1.0 ELECTRICAL CHARACTERISTICS

## Absolute Maximum Ratings †

V <sub>IN</sub> – A <sub>GND</sub>
$\overline{(SHDN}$ , FB, V <sub>CC</sub> , Comp (A <sub>GND</sub> – 0.3V) to (V <sub>IN</sub> + 0.3V)
$L_X$ to $P_{GND}$ -0.3V to $(V_{IN}$ + 0.3V)
$P_{GND}$ to $A_{GND}$ 0.3V to +0.3V
Output Short Circuit CurrentContinuous
Storage temperature65°C to +150°C
Ambient Temp. with Power Applied40°C to +85°C
Operating Junction Temperature40°C to +125°C
ESD protection on all pins (HBM) 4 kV
ESD protection on all pins (MM) 300V

**†** Notice: Stresses above those listed under "Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

## DC CHARACTERISTICS

**Electrical Specifications:** Unless otherwise noted,  $V_{IN} = V_{CC} = V_{\overline{SHDN}} = 3.3V$ ,  $V_{OUT} = 1.8V$ ,  $C_{IN} = C_{OUT} = 10 \ \mu\text{F}$ ,  $L = 3.3 \ \mu\text{H}$ ,  $I_{LOAD} = 100 \ \text{mA}$ ,  $T_A = +25^{\circ}\text{C}$ . **Boldface** specifications apply over the  $T_A$  range of -40°C to +85°C.

Parameters	Sym	Min	Тур	Max	Units	Conditions	
Input Voltage							
Input Operating Voltage	V <sub>IN</sub>	2.7	—	5.5	V		
Input Shutdown Current	I(V <sub>IN</sub> )		0.01	1	μA	Shutdown mode ( $\overline{SHDN} = GND$ )	
Input Quiescent Current	I(V <sub>IN</sub> )	_	5	7	mA	$I_{LOAD} = 0 \text{ mA}$	
Oscillator Characteristics							
Internal Oscillator Frequency	F <sub>OSC</sub>	1.2	1.4	1.6	MHz		
Internal Power Swicthes							
R <sub>DSon</sub> P-Channel	R <sub>DSon-P</sub>	_	300	—	mΩ	I <sub>P</sub> = 250 mA	
R <sub>DSon</sub> N-Channel	R <sub>DSon-N</sub>	_	300	_	mΩ	I <sub>N</sub> = 250 mA	
L <sub>X</sub> Pin Leakage Current	I <sub>LX</sub>	-1	—	1	μA	$\overline{SHDN} = 0V, V_{IN} = 5.5V, L_X = 0V, L_X = 5.5V$	
Positive Current Limit Threshold	+I <sub>LX(MAX)</sub>	_	2.3	_	А		
Negative Current Limit Threshold	-I <sub>LX(MAX)</sub>	_	-1.4	_	А		
Feedback Characteristics							
Transconductance from FB to COMP	9 <sub>m</sub>	35	62	90	µA/V		
Output Voltage							
Output Voltage Range	V <sub>OUT</sub>	0.8	_	V <sub>IN</sub>	V		
Reference Feedback Voltage	V <sub>FB</sub>	0.78	0.8	0.82	V		
Feedback Input Bias Current	I <sub>VFB</sub>	_	1	_	nA		
Line Regulation	V <sub>LINE-REG</sub>	_	0.15	0.5	%/V	$V_{IN} = 2.7V$ to 5.5V, $I_{LOAD} = 100$ mA	
Load Regulation	V <sub>LOAD-REG</sub>		0.25	_	%	$V_{IN} = 4.2V, I_{LOAD} = 100 \text{ mA to } 1A$	

**Note 1:** The integrated MOSFET switches have an integral diode from the L<sub>X</sub> pin to V<sub>IN</sub> and from L<sub>X</sub> to P<sub>GND</sub>. In cases where these diodes are forward-biased, the package power dissipation limits must be adhered to. Thermal protection is not able to regulate the junction temperature for these cases.

2: UVLO is specified for a falling V<sub>IN</sub>. Once the UVLO is activated, the UVLO-<sub>HYS</sub> must be overcome before the device will return to operation.

## **DC CHARACTERISTICS (CONTINUED)**

Electrical Specifications: Unless $I_{LOAD} = 100 \text{ mA}, T_A = +25^{\circ}\text{C}$ . Bold						
Parameters	Sym	Min	Тур	Мах	Units	Conditions
Protection Features			•			
Undervoltage Lockout	UVLO	2.4	2.55	2.7	V	Note 2
Undervoltage Lockout Hysteresis	UVLO- <sub>HYS</sub>	_	200	_	mV	
Thermal Shutdown	T <sub>SHD</sub>	_	160	_	°C	Note 1
Thermal Shutdown Hysteresis	T <sub>SHD-HYS</sub>	_	9		°C	
Interface Signal (SHDN)						
Logic-High Input	V <sub>IN-HIGH</sub>	45	_	_	% of $\rm V_{\rm IN}$	
Logic-Low Input	V <sub>IN-LOW</sub>	_	_	15	% of $V_{\rm IN}$	

Note 1: The integrated MOSFET switches have an integral diode from the L<sub>X</sub> pin to V<sub>IN</sub> and from L<sub>X</sub> to P<sub>GND</sub>. In cases where these diodes are forward-biased, the package power dissipation limits must be adhered to. Thermal protection is not able to regulate the junction temperature for these cases.

2: UVLO is specified for a falling V<sub>IN</sub>. Once the UVLO is activated, the UVLO-<sub>HYS</sub> must be overcome before the device will return to operation.

## **TEMPERATURE SPECIFICATIONS**

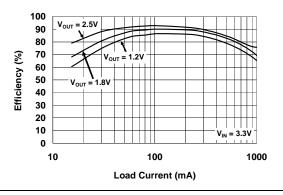
<b>Electrical Specifications:</b> $V_{IN}$ = 3.0V to 5.5V, $F_{OSC}$ = 1 MHz with 10% Duty Cycle, $C_{IN}$ = 0.1 µF. $T_A$ = -40°C to +125°C.								
Parameters	Sym	Min	Тур	Max	Units	Conditions		
Temperature Ranges								
Storage Temperature Range	T <sub>A</sub>	-65	—	+150	°C	Continuous		
Maximum Junction Temperature	Τ <sub>J</sub>	_	_	+150	°C	Transient Only		
Operating Junction Temperature Range	T <sub>A</sub>	- 40	_	+ 125	°C	Continuous Operation		
Thermal Package Resistances								
Thermal Resistance, 8L-MSOP	$\theta_{JA}$	—	208	—	°C/W	Typical 4-layer board interconnecting vias		
Thermal Resistance, 8L-DFN	$\theta_{JA}$	_	41	_	°C/W	Typical 4-layer board interconnecting vias		

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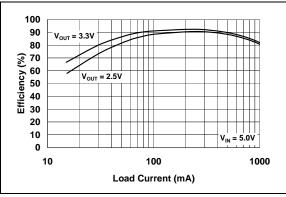
## 2.0 TYPICAL PERFORMANCE CURVES

**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

**Note:** Unless otherwise indicated,  $V_{IN} = V_{CC} = V_{\overline{SHDN}} = 3.3V$ ,  $C_{OUT} = C_{IN} = 10 \ \mu\text{F}$ ,  $L = 3.3 \ \mu\text{H}$ ,  $I_{LOAD} = 100 \ \text{mA}$ ,  $T_A = +25^{\circ}\text{C}$ . **Boldface** specifications apply over the  $T_A$  range of -40°C to +85°C.



**FIGURE 2-1:** Efficiency vs. Load Current,  $V_{IN} = 3.3V$ .



**FIGURE 2-2:** Efficiency vs. Load Current,  $V_{IN} = 5.0V$ .

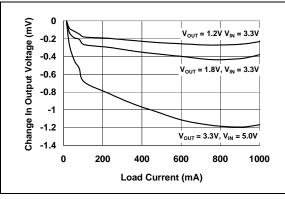
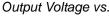
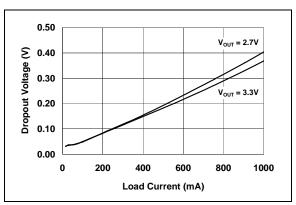


FIGURE 2-3: Load Current.







Dropout Voltage vs.

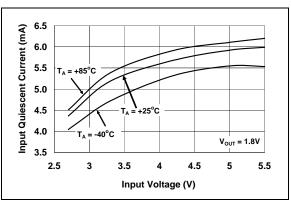


FIGURE 2-5: Input Quiescent Current vs. Input Voltage.

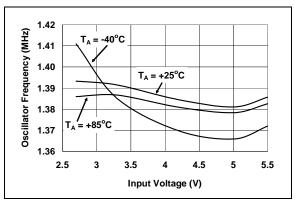


FIGURE 2-6: Input Voltage.

Oscillator Frequency vs.

## **TYPICAL PERFORMANCE CURVES (Continued)**

**Note:** Unless otherwise indicated,  $V_{IN} = V_{CC} = V_{\overline{SHDN}} = 3.3V$ ,  $C_{OUT} = C_{IN} = 10 \ \mu\text{F}$ ,  $L = 3.3 \ \mu\text{H}$ ,  $I_{LOAD} = 100 \ \text{mA}$ ,  $T_A = +25^{\circ}\text{C}$ . **Boldface** specifications apply over the  $T_A$  range of -40°C to +85°C.

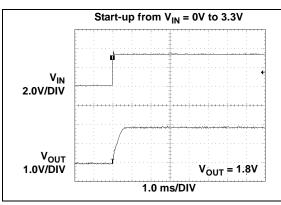


FIGURE 2-7: Power-Up from V<sub>IN</sub>.

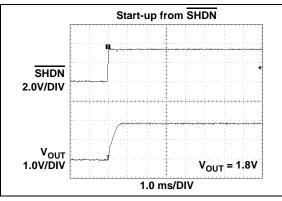


FIGURE 2-8:

Power-Up from Shutdown.

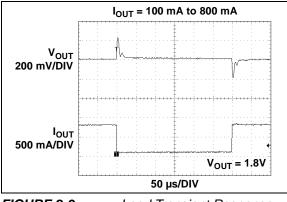


FIGURE 2-9:

Load Transient Response.

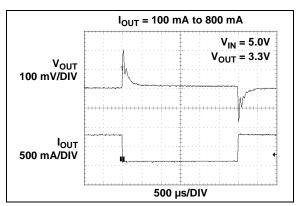


FIGURE 2-10: Load Transient Response.

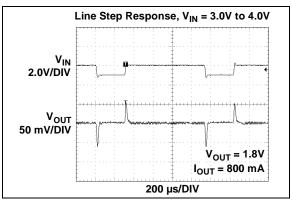


FIGURE 2-11: Line Transient Response.

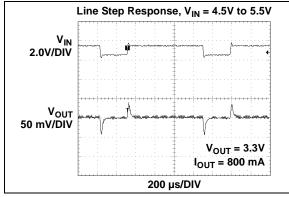


FIGURE 2-12: Line Transient Response.

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## **TYPICAL PERFORMANCE CURVES (Continued)**

**Note:** Unless otherwise indicated,  $V_{IN} = V_{CC} = V_{\overline{SHDN}} = 3.3V$ ,  $C_{OUT} = C_{IN} = 10 \ \mu\text{F}$ ,  $L = 3.3 \ \mu\text{H}$ ,  $I_{LOAD} = 100 \ \text{mA}$ ,  $T_A = +25^{\circ}\text{C}$ . **Boldface** specifications apply over the  $T_A$  range of -40°C to +85°C.

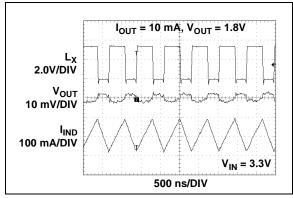
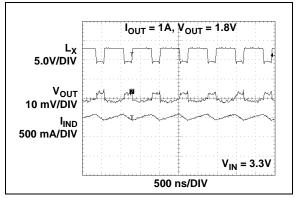


FIGURE 2-13: Low Load Current Switching Waveform.



*FIGURE 2-14:* High Load Current Switching Waveform.

## 3.0 MCP1612 PIN DESCRIPTIONS

The descriptions of the pins are listed in Table 3-1.

TABLE 0 1.		
Pin No.	Name	Function
1	V <sub>IN</sub>	Input Voltage Pin
2	V <sub>CC</sub>	Analog Input Voltage Pin
3	SHDN	Shutdown Control Input Pin
4	COMP	Transconductance Amplifier Output Pin
5	FB	Feedback Input Pin
6	A <sub>GND</sub>	Analog Ground Pin
7	P <sub>GND</sub>	Power Ground Pin
8	L <sub>X</sub>	Buck Inductor Output Pin

#### TABLE 3-1: PIN FUNCTION TABLE

## 3.1 Input Voltage Pin (VIN)

Connect the input voltage source to V<sub>IN</sub>. For normal operation, the voltage on V<sub>IN</sub> should be between +2.7V and +5.5V. A 10  $\mu$ F bypass capacitor should be connected between V<sub>IN</sub> and P<sub>GND</sub>.

## 3.2 Analog Input Voltage Pin (V<sub>CC</sub>)

 $V_{CC}$  provides bias for internal analog functions. This voltage is derived by filtering the  $V_{\rm IN}$  supply.

## 3.3 Shutdown Input Pin (SHDN)

Connect SHDN to a logic-level input in order to turn the regulator on or off. A logic-high (>45% of V<sub>IN</sub>) will enable the regulator. A logic-low (<15% of V<sub>IN</sub>) will force the regulator into Shutdown mode. When in shutdown, both the P-channel and N-channel switches are turned off.

## 3.4 Compensation Pin (COMP)

COMP is the internal transconductance amplifier output pin. External compensation is connected to COMP for control-loop stabilization.

## 3.5 Feedback Pin (FB)

Connect the output voltage of the buck converter through an external resistor divider to FB to regulate the output voltage. The nominal voltage compared to this input for pulse termination is 0.8V.

## 3.6 Analog Ground Pin (A<sub>GND</sub>)

Tie all small-signal ground returns to  $A_{GND}.$  Noise on  $A_{GND}$  can effect the sensitive internal analog measurements.

## 3.7 Power Ground Pin (P<sub>GND</sub>)

Connect all large-signal ground returns to  $P_{GND}$ . These large-signal traces should have a small loop area and length to prevent coupling of switching noise to sensitive traces.

## 3.8 Buck Inductor Output Pin (L<sub>X</sub>)

Connect  $L_X$  directly to the buck inductor. This pin carries large signal-level currents; all connections should be made as short as possible.

## 4.0 DETAILED DESCRIPTION

#### 4.1 Device Overview

The MCP1612 is a 1A synchronous buck converter switching at 1.4 MHz to minimize external component size and cost. While utilizing a fixed-frequency Current mode architecture, the MCP1612 provides fast response to sudden load changes, as well as overcurrent protection in the event of a shorted load. The input voltage range is 2.7V to 5.5V, while the output voltage is adjustable by properly setting an external resistor divider and can range from 0.8V to  $V_{\rm IN}$ . Integrated soft-start, UVLO and overtemperature protection minimize external circuitry and component count.

### 4.2 Current Mode Control Scheme

The MCP1612 incorporates a Peak Current mode control scheme. Peak Current mode is used to obtain high gain in the PWM control loop for very fast response to dynamic line and load conditions. With both the P-channel and N-channel MOSFETs turned off, the beginning of a cycle occurs on the negative edge of the internal 1.4 MHz oscillator, the P-channel MOSFET turns on and current ramps up into the buck inductor. The inductor current is sensed and tied to one input of a high-speed comparator. The other input of the high-speed comparator is the error amplifier output. This is the amplified difference between the internal 0.8V reference and the divided-down  $V_{\mbox{OUT}}$  signal at the FB pin of the MCP1612. When the sensed inductor current ramps up to the point that is equal to the amplified error signal, the high-speed comparator output switches states and the P-channel MOSFET is turned off until the beginning of the next clock cycle and the N-channel is turned on. The width of the pulse (or duty cycle) is ideally determined by the V<sub>OUT</sub>/V<sub>IN</sub> ratio of the DC/DC converter. The actual duty cycle is slightly larger to account for the non-ideal losses of the integrated MOSFET switches and the losses in the external inductor.

## 4.3 Low-Dropout Operation

The MCP1612 is capable of operating over a wide range of input voltages. The PWM architecture allows for the P-channel MOSFET to achieve 100% duty cycle operation for applications that have minimal input voltage headroom. During 100% Duty Cycle mode, the output voltage ( $V_{OUT}$ ) is equal to the Output Current ( $I_{OUT}$ ) x Resistance (P-channel R<sub>DSON</sub> + R<sub>INDUCTOR</sub>).

## 4.4 Current Limit

Cycle-by-cycle current limit is used to protect the MCP1612 from being damaged when an external short circuit is applied. The typical peak current limit is 2.3A. If the sensed inductor current reaches the 2.3A limit, the P-channel MOSFET is turned off, even if the output voltage is not in regulation.

## 4.5 Soft-Start

During normal power-up, as  $V_{IN}$  rises above the UVLO protection setting (or, in the case of a logic-low to logic-high transition on the shutdown pin), the rise time of the MCP1612 output voltage is controlled by the soft-start feature. This is accomplished by allowing the output of the error amplifier to slowly rise. This feature prevents the output voltage from overshooting the desired value and the sudden inrush of current, depleting the input capacitors and causing a large dip in input voltage. This large dip in the input voltage can trip the UVLO threshold, causing the converter to shut down prior to reaching steady-state operation.

## 4.6 Undervoltage Lockout (UVLO)

The UVLO feature uses a comparator to sense the input voltage level (V<sub>IN</sub>). If the input voltage is lower than the voltage necessary to properly operate the MCP1612, the UVLO feature will hold the converter off. When V<sub>IN</sub> rises above the necessary input voltage, the UVLO is released and soft-start begins. For the MCP1612, the UVLO protection threshold is at a maximum of 2.7V. Hysteresis is built into the UVLO circuit to compensate for input impedance. For example, if there is any resistance between the input voltage source and the converter (once it starts), there will be a voltage drop at the converter input equal to I<sub>IN</sub> x R<sub>IN</sub>. The typical hysteresis for the MCP1612 is 200 mV.

## 4.7 **Overtemperature Protection**

The MCP1612 has an integrated overtemperature protection circuit that monitors the device junction temperature and shuts the device off if the junction temperature exceeds the typical 160°C threshold. If the overtemperature threshold is reached, the soft-start is reset so that, when the junction temperature cools to approximately 151°C, the device will automatically restart and the output voltage will not overshoot.

## 4.8 Shutdown Input Operation

The SHDN pin is used to turn the MCP1612 on and off. When the SHDN pin is tied low, the MCP1612 is off. When tied high, the MCP1612 will be enabled and begin operation as long as the input voltage is not below the UVLO threshold.

## 5.0 APPLICATION CIRCUITS/INFORMATION

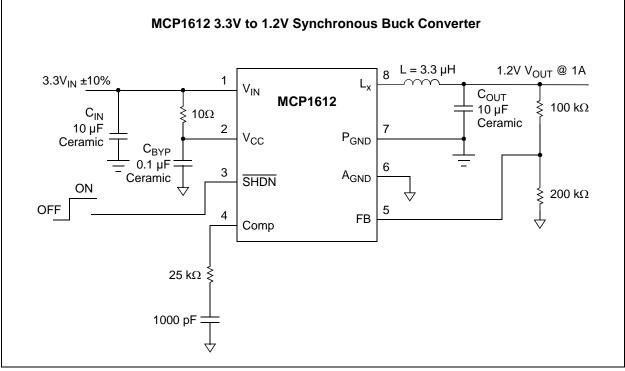


FIGURE 5-1: Typical Application Circuit.

## 5.1 Typical Applications

The MCP1612 buck controller can be used in several different applications where a voltage that is lower than the supply voltage is required. Its small size, low cost and high efficiency make the MCP1612 a good choice for densely-packaged applications. The input voltage range, low-dropout voltage and low shutdown current make this part perfectly suited for battery-powered applications.

## 5.2 Design Example

The step-by-step design of a buck converter with the following parameters is presented to illustrate how easy the MCP1612 is to use.

Input voltage = 3.3V Output voltage = 1.2V Output current = 0A to 1A Switching frequency = 1.4 MHz

#### 5.2.1 SETTING OUTPUT VOLTAGE

The output voltage of the MCP1612 is set by using an external resistor-divider network. The voltage present at FB is internally compared to a 0.8V reference voltage. A 200 k $\Omega$  resistor is recommended for R<sub>2</sub>, the lower-end of the voltage divider. Using higher-value

resistors will make the circuit more susceptible to noise on the FB pin. Lower-value resistors can be used, if necessary.

Equation 5-1, used to calculate the output voltage, is shown below.

**EQUATION 5-1:** 

$$R_1 = R_2 \times \left(\frac{V_{OUT}}{V_{FR}} - I\right)$$

Where:

V<sub>OUT</sub> = desired output voltage

- V<sub>FB</sub> = MCP1612 internal reference voltage
  - $R_1 = top resistor value$
  - $R_2$  = bottom resistor value

For this example:

$$V_{OUT} = 1.2V$$

$$V_{FB} = 0.8V$$

$$R_2 = 200 k\Omega$$

$$R_1 = 100 k\Omega$$

The MCP1612 is capable of a 15% duty cycle. Instability may result when the duty cycle is below 15%. If less than 15% duty cycle operation is needed, care must be taken to ensure stable operation.

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#### 5.2.2 BUCK INDUCTOR

There are many requirements that need to be satisfied when selecting the buck inductor. The application, physical size, current rating, resistance, mounting method, supplier, temperature range, minimum inductance and cost all need to be considered.

Many suppliers specify the maximum peak current that an inductor can handle before magnetic saturation occurs. The peak current is equal to the maximum DC output current, plus one-half the peak-to-peak AC ripple current.

When the P-channel MOSFET is on, the current in the buck inductor is ramped up. The voltage across the inductor, the inductance and the MOSFET on-time are required to determine the peak-to-peak ripple current.

When operating in Continuous Current mode, the ontime of the P-channel MOSFET is determined by multiplying the duty cycle by the switching period. The following equation can be used to determine the duty cycle.

#### **EQUATION 5-2:**

$$DutyCycle = \frac{V_{OUT}}{V_{IN}}$$

The on-time is then defined as follows.

#### EQUATION 5-3:

$$T_{ON} = DutyCycle \times \frac{1}{F_{SW}}$$

Where:

F<sub>SW</sub> = switching frequency

The AC ripple current in the inductor can be calculated by the following relationship.

#### **EQUATION 5-4:**

$$V_L = L \times \frac{\Delta I_L}{\Delta t}$$

Solving for  $\Delta I_L$  yields:

#### EQUATION 5-5:

$$\Delta I_L = \frac{V_L}{L} \times \Delta t$$

Where:

$$V_L$$
 = voltage across the inductor  
( $V_{IN} - V_{OUT}$ )  
 $\Delta t$  = on-time of the P-channel MOSFET

The value of the buck inductor is chosen to be  $3.3 \,\mu$ H. The AC ripple current is controlled by the size of the buck inductor. The value of the inductor will therefore need to be raised so that the converter operates in Continuous Conduction mode. Calculation of the buck inductor current rating follows.

$$\begin{array}{rcl} V_{IN} &=& 3.3V \\ V_{OUT} &=& 1.2V \\ F_{SW} &=& 1.4 \ \text{MHz} \\ I_{OUT(MAX)} &=& 1A \\ T_{ON} &=& (1.2V/3.3V) \ x \ (1/1.4 \ \text{MHz}) \\ T_{ON} &=& 260 \ \text{ns} \\ V_L &=& (3.3V-1.2V) = 2.1V \\ \Delta I_L &=& (2.1V/3.3 \ \mu\text{H}) \ x \ 260 \ \text{ns} \\ \Delta I_L &=& 165 \ \text{mA} \\ I_{L(PEAK)} &=& I_{OUT(MAX)} + 1/2 \ \Delta I_L \\ I_{L(PEAK)} &=& 1A + (165 \ \text{mA})/2 \\ I_{L(PEAK)} &=& 1.08A \end{array}$$

The inductor selected must have an inductance of  $3.3 \,\mu\text{H}$  at a peak current rating of 1.08A. The DC resistance of the inductor should be as low as is feasibly possible. Extremely low DC resistance inductors are available, though a trade-off between size and cost should be considered.

## 5.2.3 OUTPUT CAPACITOR

The output capacitor is used to filter the inductor AC ripple current and provide storage for load transients. The size and Equivalent Series Resistance (ESR) of the output capacitor determines the amount of ripple voltage present at the output of the converter. When selecting the output capacitor, a design trade-off has to be made between the acceptable ripple voltage and the size/cost of the output capacitor. Ceramic capacitors have very low ESR, but increase in cost with higher values. Tantalum and electrolytic capacitors are relatively inexpensive in higher values, but they also have a much higher ESR.

The amount of capacitance needed to obtain the desired ripple voltage is calculated by using the following relationship.

#### **EQUATION 5-6:**

$$I_C = C \times \frac{\Delta V_C}{\Delta t}$$

Solving for C:

$$C = I_C \times \frac{\Delta}{\Delta V}$$

Where:

$$\Delta t$$
 = on-time of P-channel MOSFET

 $\Delta V_{C}$  = output ripple voltage

There will also be some ripple voltage caused by the ESR of the capacitor. The ripple is defined as follows.

#### EQUATION 5-7:

 $V_{ESRRIPPLE} = ESR \times I_C$ 

For this example:

۱ <sub>C</sub>	=	165 mA
С	=	4.7 μF
$\Delta t$	=	260 ns
ESR	=	8 mΩ
$\Delta V_{C}$	=	(260 ns x 165 mA)/4.7 µF
$\Delta V_{C}$	=	9.13 mV
V <sub>ESRRIPPLE</sub>	=	8 mΩ x 165 mA
V <sub>ESRRIPPLE</sub>	=	1.32 mV
$\Delta V_{OUT}$	=	$\Delta V_{C}$ + $V_{ESRRIPPLE}$
$\Delta V_{OUT}$	=	9.13 mV + 1.32 mV
$\Delta V_{OUT}$	=	10.45 mV

## 5.2.4 INPUT CAPACITOR

For the buck topology, the input current is pulled from the source and the input capacitor in pulses. The size of the input capacitor will determine the amount of current pulled from the source. For most applications, a 10  $\mu$ F ceramic capacitor connected between the MCP1612's V<sub>IN</sub> and P<sub>GND</sub> is recommended to filter the current pulses. Less capacitance can be used for applications that have low source impedance. The ripple current rating for ceramic capacitors are typically very high due to their low loss characteristics. Low-cost electrolytic capacitors can be used, but their ripple current rating should not be exceeded.

## 5.2.5 V<sub>CC</sub> INPUT

The  $V_{CC}$  input is used to bias the internal MCP1612 circuitry. A  $10\Omega$  resistor is recommended between the unregulated inputs  $V_{IN}$  and  $V_{CC}$ , along with a 0.1  $\mu F$  capacitor to ground to help isolate the  $V_{CC}$  pin from the switching noise.

## 5.2.6 COMPENSATION COMPONENTS

An internal transconductance error amplifier is used to compensate the buck converter. An external resistor ( $R_C$ ) and capacitor ( $C_C$ ), connected between COMP and GND, are all that is needed to provide a high-bandwidth loop.

Table 5-1 identifies values for  $R_C$  and  $C_C$  for standard buck inductor (L) and output capacitor ( $C_{OUT}$ ) values.

L	C <sub>OUT</sub>	R <sub>C</sub>	Cc
3.3 µH	10.0 µF	25 kΩ	1000 pF
2.2 µH	4.7 µF	10 kΩ	1000 pF

## 5.3 Printed Circuit Board (PCB) Layout

The MCP1612 is capable of switching over 1A at 1.4 MHz. As with all high-frequency switching power supplies, good PCB layout techniques are essential to prevent noise generated by the switching power-train from interfering with the sensing circuitry.

There are two ground pins ( $P_{GND}$  and  $A_{GND}$ ) on the MCP1612 to separate the large-signal ground current from the small-signal circuit ground. These two grounds should be kept separate, only connecting near the input bulk capacitor.

Care must also be taken to minimize the length and loop area of the large signal connections. Components connected to this loop consist of the input bulk capacitor,  $V_{IN}$ ,  $P_{GND}$  and  $L_X$  pins of the MCP1612, the buck inductor and the output filter capacitor.

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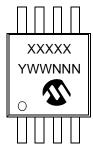
## 6.0 PACKAGING INFORMATION

## 6.1 Package Marking Information

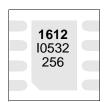
8-Lead DFN (3mm x 3mm)



8-Lead MSOP



Example:

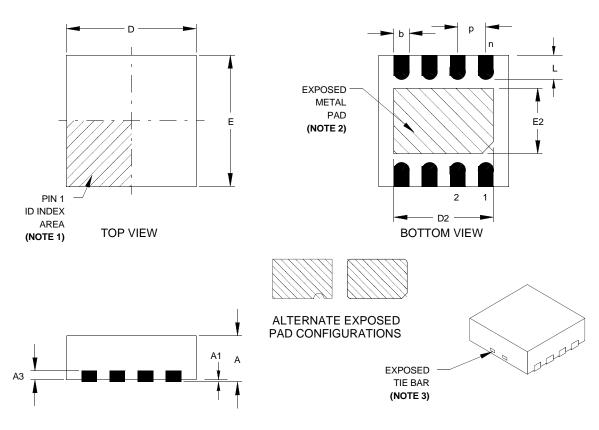




Legei	nd: XXX Y YY WW NNN (e3) *	Customer-specific information Year code (last digit of calendar year) Year code (last 2 digits of calendar year) Week code (week of January 1 is week '01') Alphanumeric traceability code Pb-free JEDEC designator for Matte Tin (Sn) This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.
Note:	be carrie	nt the full Microchip part number cannot be marked on one line, it will d over to the next line, thus limiting the number of available s for customer-specific information.

#### 8-Lead Plastic Dual-Flat, No-Lead Package (MF) 3x3x0.9 mm Body (DFN) - Saw Singulated

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	INCHES			MILLIMETERS*		
Dimension	Limits	MIN	MIN NOM MAX		MIN	NOM	MAX
Number of Pins	n		8			8	
Pitch	р		.026 BSC			0.65 BSC	
Overall Height	А	.031	.035	.039	0.80	0.90	1.00
Standoff	A1	.000	.001	.002	0.00	0.02	0.05
Contact Thickness	A3		.008 REF.		0.20 REF.		
Overall Length	E		.118 BSC		3.00 BSC		
Exposed Pad Width	E2	.043	.061	.063	1.09	1.55	1.60
Overall Width	D		.118 BSC		3.00 BSC		
Exposed Pad Length	D2	.059	.092	.096	1.50	2.37	2.45
Contact Width	b	.009	.012	.015	0.23	0.30	0.37
Contact Length	L	.008	.016	.020	0.20	0.40	0.50

\* Controlling Parameter

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

- 2. Exposed pad varies according to die attach paddle size.
- 3. Package may have one or more exposed tie bars at ends.

 $\ensuremath{\mathsf{BSC}}$  : Basic Dimension. Theoretically exact value shown without tolerances.

- See ASME Y14.5M
- REF: Reference Dimension, usually without tolerance, for information purposes only. See ASME Y14.5M

JEDEC equivalent: M0-229

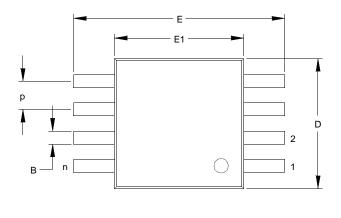
Drawing No. C04-062

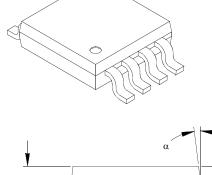
Revised 07-20-05

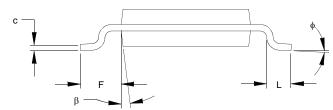
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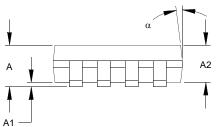
## 8-Lead Plastic Micro Small Outline Package (MS) (MSOP)

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging









Units			INCHES		MILLIMETERS*		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		8			8	
Pitch	р		.026 BSC			0.65 BSC	
Overall Height	Α	-	-	.043	-	-	1.10
Molded Package Thickness	A2	.030	.033	.037	0.75	0.85	0.95
Standoff	A1	.000	-	.006	0.00	-	0.15
Overall Width	Е		.193 BSC		4.90 BSC		
Molded Package Width	E1		.118 BSC		3.00 BSC		
Overall Length	D		.118 BSC		3.00 BSC		
Foot Length	L	.016	.024	.031	0.40	0.60	0.80
Footprint (Reference)	F		.037 REF		0.95 REF		
Foot Angle	φ	0°	-	8°	0°	-	8°
Lead Thickness	с	.003	.006	.009	0.08	-	0.23
Lead Width	В	.009	.012	.016	0.22	-	0.40
Mold Draft Angle Top	α	5°	-	15°	5°	-	15°
Mold Draft Angle Bottom	β	5°	-	15°	5°	-	15°

\* Controlling Parameter

#### Notes:

Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

See ASME Y14.5M

REF: Reference Dimension, usually without tolerance, for information purposes only.

See ASME Y14.5M

JEDEC Equivalent: MO-187

Drawing No. C04-111

Revised 07-21-05

## APPENDIX A: REVISION HISTORY

## **Revision C (January 2013)**

Added a note to each package outline drawing.

## **Revision B (September 2005)**

The following is the list of modifications:

- 1. Changed pin 6 in Package Types diagram on front page.
- 2. Removed device qualification note in Package Marking section.
- 3. Removed device qualification note in Package Outline drawing.
- 4. Removed device qualification note in Package Identification System section
- 5. Replaced MSOP and QFN package diagrams.

## **Revision A (December 2004)**

• Original Release of this Document.

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# **MCP1612**

NOTES:

## **PRODUCT IDENTIFICATION SYSTEM**

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<u>× /xx</u>	E	xamples:	
erature Package	a)	MCP1612-ADJI/MS:	Industrial Temperature, 8LD MSOP package.
nge	b)	MCP1612T-ADJI/MS:	Tape and Reel Industrial Temperature, 8LD MSOP package.
MCP1612: Synchronous Buck Regulator MCP1612T: Synchronous Buck Regulator	c)	MCP1612-ADJI/MF:	Industrial Temperature, 8LD DFN package.
(Tape and Reel)	d)	MCP1612T-ADJI/MF:	Tape and Reel Industrial Temperature, 8LD DFN package.
$I = -40^{\circ}C \text{ to } +85^{\circ}C$			012 2 paolago.
MF = Dual Flat, No Lead (3x3mm Body), 8-lead MS = Plastic MSOP, 8-lead			
	MCP1612: Synchronous Buck Regulator MCP1612T: Synchronous Buck Regulator (Tape and Reel) I = -40°C to +85°C MF = Dual Flat, No Lead (3x3mm Body), 8-lead	M       Package       a)         perature       Package       b)         MCP1612:       Synchronous Buck Regulator       c)         MCP1612T:       Synchronous Buck Regulator       d)         I       = -40°C to +85°C       d)         MF       = Dual Flat, No Lead (3x3mm Body), 8-lead       slaad	merature       Package         a)       MCP1612-ADJI/MS:         b)       MCP1612T-ADJI/MS:         b)       MCP1612T-ADJI/MS:         MCP1612T:       Synchronous Buck Regulator (Tape and Reel)         I       = -40°C to +85°C         MF       = Dual Flat, No Lead (3x3mm Body), 8-lead

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# MCP1612

NOTES:

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