

AD5663* PRODUCT PAGE QUICK LINKS

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EVALUATION KITS

- AD5663R Evaluation Board

DOCUMENTATION

Data Sheet

- AD5663: 2.7 V to 5.5 V, 250 μ A, Rail-to-Rail Output, Dual 16-Bit *nano*DAC Data Sheet

SOFTWARE AND SYSTEMS REQUIREMENTS

- AD5663 Evaluation Software (zip)

TOOLS AND SIMULATIONS

- AD5663R IBIS Model

REFERENCE MATERIALS

Solutions Bulletins & Brochures

- Digital to Analog Converters ICs Solutions Bulletin

DESIGN RESOURCES

- AD5663 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints

DISCUSSIONS

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REVISION HISTORY

11/2016—Rev. 0 to Rev. A

Changed ADSP-BF53x to ADSP-BF537	Throughout
Added Figure 4; Renumbered Sequentially	7
Changes to Table 6.....	7
Change to Figure 28	14
Changes to Software Reset Section	15
Changes to Figure 33.....	18
Updated Outline Dimensions	21
Changes to Ordering Guide	21

4/2006—Revision 0: Initial Version

SPECIFICATIONS

$V_{DD} = 2.7\text{ V to }5.5\text{ V}$; $R_L = 2\text{ k}\Omega$ to GND; $C_L = 200\text{ pF}$ to GND; $V_{REF} = V_{DD}$; all specifications T_{MIN} to T_{MAX} , unless otherwise noted.

Table 2.

Parameter	A Grade ¹			B Grade ¹			Unit	Conditions/Comments
	Min	Typ	Max	Min	Typ	Max		
STATIC PERFORMANCE ²								
AD5663								
Resolution	16			16			Bits	
Relative Accuracy		±8	±16		±6	±12	LSB	
Differential Nonlinearity			±1			±1	LSB	Guaranteed monotonic by design
Zero-Scale Error		+2	+10		+2	+10	mV	All 0s loaded to DAC register
Offset Error		±1	±10		±1	±10	mV	
Full-Scale Error		−0.15	±1		−0.15	±1	% of FSR	All 1s loaded to DAC register
Gain Error			±1.5			±1.5	% of FSR	
Zero-Scale Error Drift ³		±2			±2		μV/°C	
Gain Temperature Coefficient		±2.5			±2.5		ppm	Of FSR/°C
DC Power Supply Rejection Ratio		−100			−100		dB	DAC code = midscale, V _{DD} ± 10%
DC Crosstalk		10			10		μV	Due to full-scale output change R _L = 2 kΩ to GND or V _{DD}
		10			10		μV/mA	Due to load current change
		5			5		μV	Due to powering down (per channel)
OUTPUT CHARACTERISTICS ²								
Output Voltage Range	0		V _{DD}	0		V _{DD}	V	
Capacitive Load Stability		2			2		nF	R _L = ∞
		10			10		nF	R _L = 2 kΩ
DC Output Impedance		0.5			0.5		Ω	
Short-Circuit Current		30			30		mA	V _{DD} = 5 V
Power-Up Time		4			4		μs	Coming out of power-down mode; V _{DD} = 5 V
REFERENCE INPUTS								
Reference Current		170	200		170	200	μA	V _{REF} = V _{DD} = 5.5 V, 3.6 V
Reference Input Range	0.75		V _{DD}	0.75		V _{DD}	V	
Reference Input Impedance		26			26		kΩ	
LOGIC INPUTS ³								
Input Current			±2			±2	μA	All digital inputs
V _{INL} , Input Low Voltage			0.8			0.8	V	V _{DD} = 5 V, 3 V
V _{INH} , Input High Voltage	2			2			V	V _{DD} = 5 V, 3 V
Pin Capacitance		3			3		pF	DIN, SCLK, and SYNC
		19			19		pF	LDAC and CLR
POWER REQUIREMENTS								
V _{DD}	2.7		5.5	2.7		5.5	V	
I _{DD} (Normal Mode) ⁴								V _{IH} = V _{DD} and V _{IL} = GND
V _{DD} = 4.5 V to 5.5 V		250	450		250	450	μA	
V _{DD} = 2.7 V to 3.6 V		200	425		200	425	μA	
I _{DD} (All Power-Down Modes) ⁵								V _{IH} = V _{DD} , V _{IL} = GND
V _{DD} = 4.5 V to 5.5 V		0.48	1		0.48	1	μA	
V _{DD} = 2.7 V to 3.6 V		0.2	1		0.2	1	μA	

¹ Temperature range: A grade and B grade are both equal to -40°C to $+105^\circ\text{C}$.

² Linearity calculated using a reduced code range: AD5663 (Code 512 to Code 65024). Output unloaded.

³ Guaranteed by design and characterization, not production tested.

⁴ Interface inactive. All DACs active. DAC outputs unloaded.

⁵ Both DACs powered down.

AC CHARACTERISTICS

$V_{DD} = 2.7\text{ V to }5.5\text{ V}$; $R_L = 2\text{ k}\Omega$ to GND; $C_L = 200\text{ pF}$ to GND; $V_{REF} = V_{DD}$; all specifications T_{MIN} to T_{MAX} , unless otherwise noted.¹

Table 3.

Parameter ²	Min	Typ	Max	Unit	Conditions/Comments
Output Voltage Settling Time		4	7	μs	1/4 to 3/4 scale settling to ± 2 LSB
Slew Rate		1.8		$\text{V}/\mu\text{s}$	
Digital-to-Analog Glitch Impulse		10		$\text{nV}\cdot\text{s}$	1 LSB change around major carry
Digital Feedthrough		0.1		$\text{nV}\cdot\text{s}$	
Reference Feedthrough		-90		dBs	$V_{REF} = 2\text{ V} \pm 0.1\text{ V p-p}$, frequency 10 Hz to 20 MHz
Digital Crosstalk		0.1		$\text{nV}\cdot\text{s}$	
Analog Crosstalk		1		$\text{nV}\cdot\text{s}$	
DAC-to-DAC Crosstalk		1		$\text{nV}\cdot\text{s}$	
Multiplying Bandwidth		340		kHz	$V_{REF} = 2\text{ V} \pm 0.1\text{ V p-p}$
Total Harmonic Distortion		-80		dB	$V_{REF} = 2\text{ V} \pm 0.1\text{ V p-p}$; frequency = 10 kHz
Output Noise Spectral Density		120		$\text{nV}/\sqrt{\text{Hz}}$	DAC code = midscale, 1 kHz
		100		$\text{nV}/\sqrt{\text{Hz}}$	DAC code = midscale, 10 kHz
Output Noise		15		$\mu\text{V p-p}$	0.1 Hz to 10 Hz

¹ Guaranteed by design and characterization, not production tested.

² See the Terminology section.

TIMING CHARACTERISTICS

All input signals are specified with $t_R = t_F = 1 \text{ ns/V}$ (10% to 90% of V_{DD}) and timed from a voltage level of $(V_{IL} + V_{IH})/2$.
 $V_{DD} = 2.7 \text{ V}$ to 5.5 V ; all specifications T_{MIN} to T_{MAX} , unless otherwise noted.¹

Table 4.

Parameter	Limit at T_{MIN}, T_{MAX}	Unit	Conditions/Comments
	$V_{DD} = 2.7 \text{ V to } 5.5 \text{ V}$		
t_1^2	20	ns min	SCLK cycle time
t_2	9	ns min	SCLK high time
t_3	9	ns min	SCLK low time
t_4	13	ns min	$\overline{\text{SYNC}}$ to SCLK falling edge setup time
t_5	5	ns min	Data setup time
t_6	5	ns min	Data hold time
t_7	0	ns min	SCLK falling edge to $\overline{\text{SYNC}}$ rising edge
t_8	15	ns min	Minimum $\overline{\text{SYNC}}$ high time
t_9	13	ns min	$\overline{\text{SYNC}}$ rising edge to SCLK fall ignore
t_{10}	0	ns min	SCLK falling edge to $\overline{\text{SYNC}}$ fall ignore
t_{11}	10	ns min	$\overline{\text{LDAC}}$ pulse width low
t_{12}	15	ns min	SCLK falling edge to $\overline{\text{LDAC}}$ rising edge
t_{13}	5	ns min	$\overline{\text{CLR}}$ pulse width low
t_{14}	0	ns min	SCLK falling edge to $\overline{\text{LDAC}}$ falling edge
t_{15}	300	ns max	$\overline{\text{CLR}}$ pulse activation time

¹ Guaranteed by design and characterization; not production tested.

² Maximum SCLK frequency is 50 MHz at $V_{DD} = 2.7 \text{ V}$ to 5.5 V .

TIMING DIAGRAM

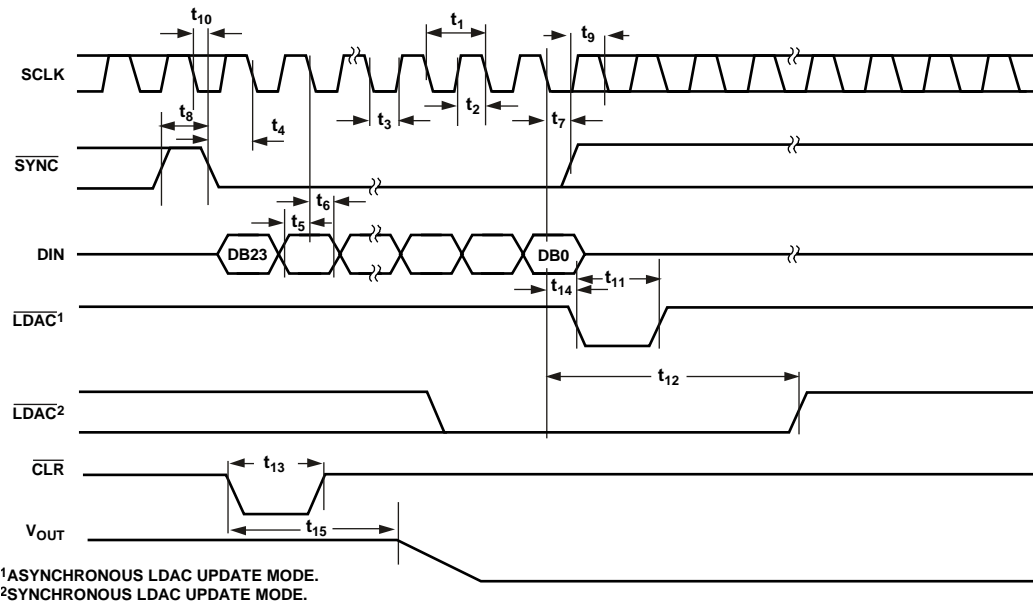


Figure 2. Serial Write Operation

039855-002

ABSOLUTE MAXIMUM RATINGS

$T_A = 25^\circ\text{C}$, unless otherwise noted.

Table 5.

Parameter	Rating
V_{DD} to GND	$-0.3\text{ V to }+7\text{ V}$
V_{OUT} to GND	$-0.3\text{ V to }V_{DD} + 0.3\text{ V}$
V_{REF} to GND	$-0.3\text{ V to }V_{DD} + 0.3\text{ V}$
Digital Input Voltage to GND	$-0.3\text{ V to }V_{DD} + 0.3\text{ V}$
Operating Temperature Range	
Industrial	$-40^\circ\text{C to }+105^\circ\text{C}$
Storage Temperature Range	$-65^\circ\text{C to }+150^\circ\text{C}$
Junction Temperature (T_J max)	150°C
Power Dissipation	$(T_J \text{ max} - T_A)/\theta_{JA}$
LFCSP_WD Package (4-Layer Board)	
θ_{JA} Thermal Impedance	61°C/W
MSOP Package (4-Layer Board)	
θ_{JA} Thermal Impedance	142°C/W
θ_{JC} Thermal Impedance	43.7°C/W
Reflow Soldering Peak Temperature	
Pb-Free	$260(+0/-5)^\circ\text{C}$

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND FUNCTION DESCRIPTION

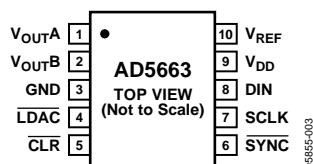
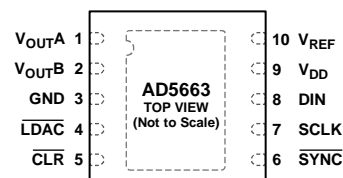


Figure 3. 10-Lead MSOP Pin Configuration



NOTES

1. EXPOSED PAD. THE EXPOSED PAD IS INTERNALLY FLOATING AND IS RECOMMENDED TO BE CONNECTED TO GROUND.

05665-100

Figure 4. 10-Lead LFCSP Pin Configuration

Table 6. Pin Function Descriptions

Pin No.		Mnemonic	Description
10-Lead MSOP	10-Lead LFCSP		
1	1	V _{OUTA}	Analog Output Voltage from DAC A. The output amplifier has rail-to-rail operation.
2	2	V _{OUTB}	Analog Output Voltage from DAC B. The output amplifier has rail-to-rail operation.
3	3	GND	Ground Reference Point for All Circuitry on the Device.
4	4	LDAC	Pulsing this pin low allows any or all DAC registers to be updated if the input registers have new data. This allows simultaneous update of all DAC outputs. Alternatively, this pin can be tied permanently low.
5	5	CLR	Asynchronous Clear Input. The CLR input is falling edge sensitive. While CLR is low, all LDAC pulses are ignored. When CLR is activated, zero scale is loaded to all input and DAC registers. This clears the output to 0 V. The device exits clear code mode on the 24th falling edge of the next write to the device. If CLR is activated during a write sequence, the write is aborted.
6	6	SYNC	Active Low Control Input. This is the frame synchronization signal for the input data. When SYNC goes low, it powers on the SCLK and DIN buffers and enables the input shift register. Data is transferred in on the falling edges of the next 24 clocks. If SYNC is taken high before the 24th falling edge, the rising edge of SYNC acts as an interrupt, and the write sequence is ignored by the device.
7	7	SCLK	Serial Clock Input. Data is clocked into the input shift register on the falling edge of the serial clock input. Data can be transferred at rates up to 50 MHz.
8	8	DIN	Serial Data Input. This device has a 24-bit shift register. Data is clocked into the register on the falling edge of the serial clock input.
9	9	V _{DD}	Power Supply Input. These devices can be operated from 2.7 V to 5.5 V, and the supply must be decoupled with a 10 μF capacitor in parallel with a 0.1 μF capacitor to GND.
10	10	V _{REF}	Reference Voltage Input.
N/A ¹		EPAD	Exposed Pad. The exposed pad is internally floating and is recommended to be connected to ground.

¹ N/A means not applicable.

TYPICAL PERFORMANCE CHARACTERISTICS

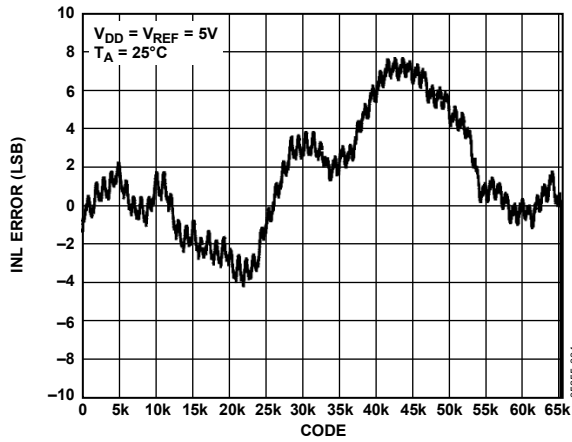


Figure 5. INL

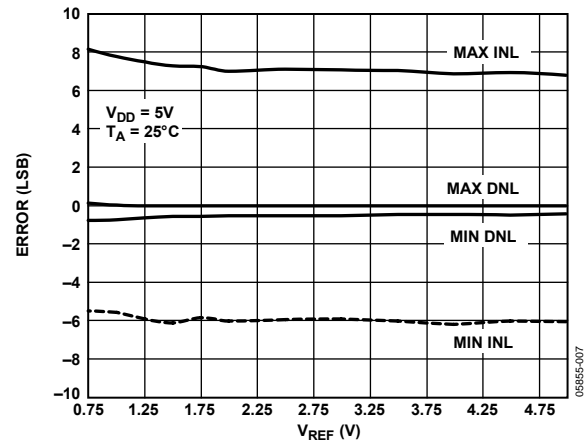
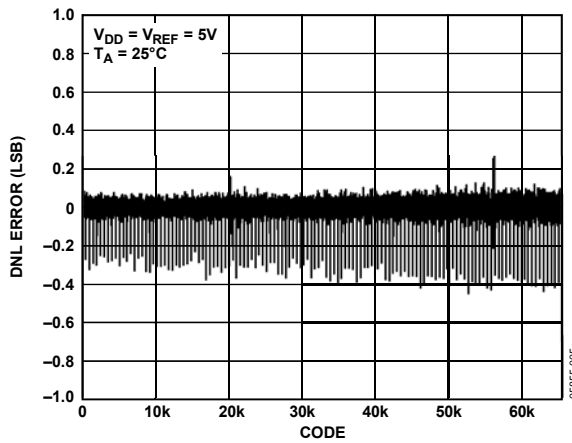
Figure 8. INL and DNL Error vs. V_{REF} 

Figure 6. DNL

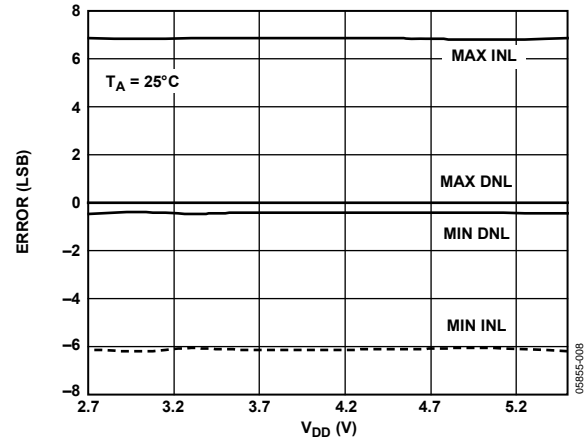


Figure 9. INL and DNL Error vs. Supply

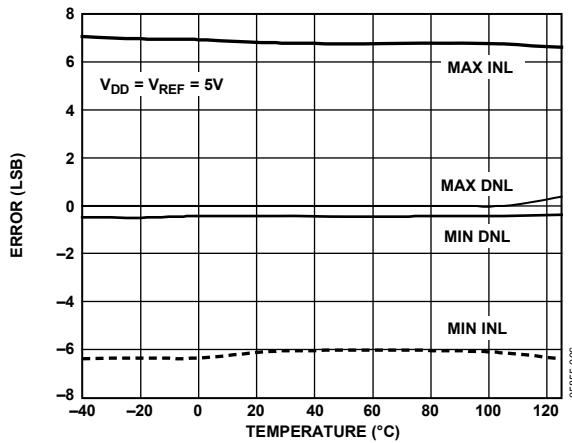


Figure 7. INL Error and DNL Error vs. Temperature

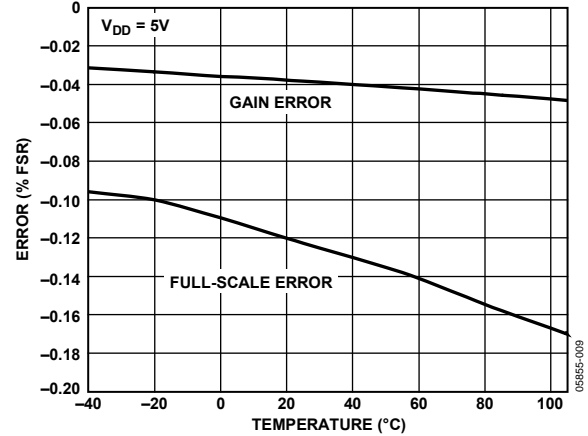


Figure 10. Gain Error and Full-Scale Error vs. Temperature

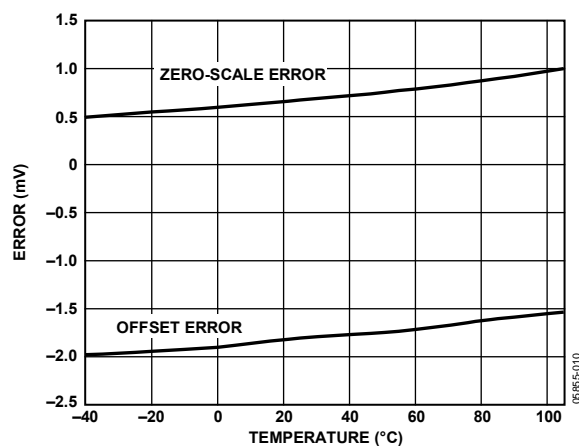


Figure 11. Zero-Scale and Offset Error vs. Temperature

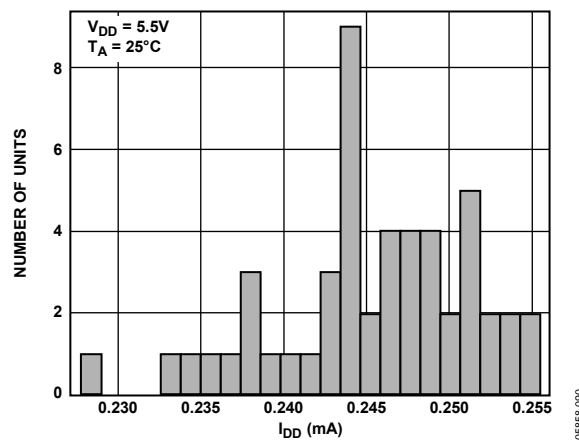
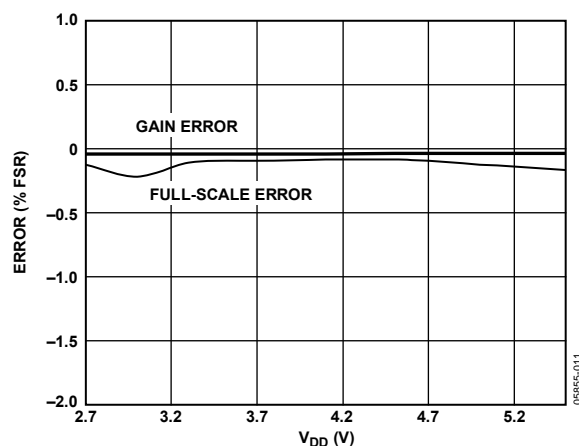
Figure 14. I_{DD} Histogram with $V_{DD} = 5.5 V$ 

Figure 12. Gain Error and Full-Scale Error vs. Supply

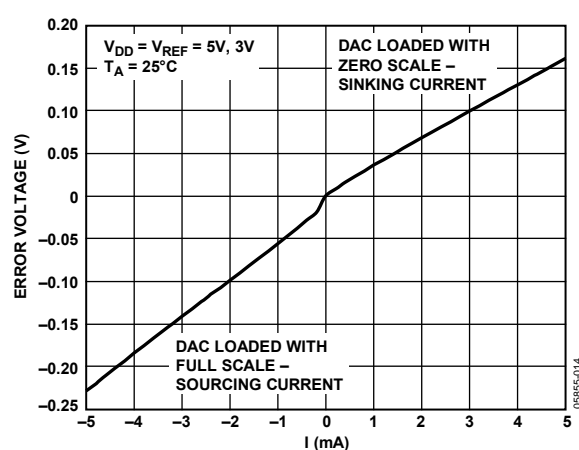


Figure 15. Headroom at Rails vs. Source and Sink Current

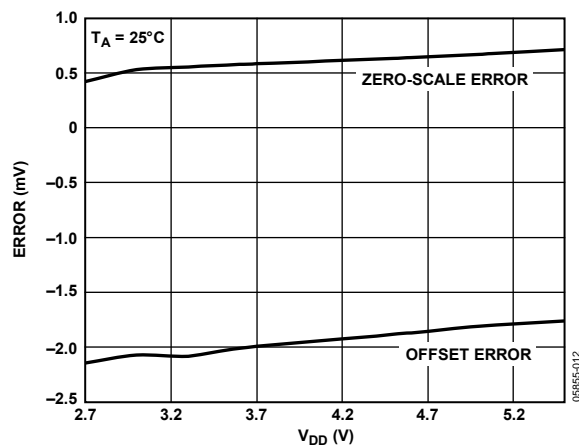


Figure 13. Zero-Scale and Offset Error vs. Supply

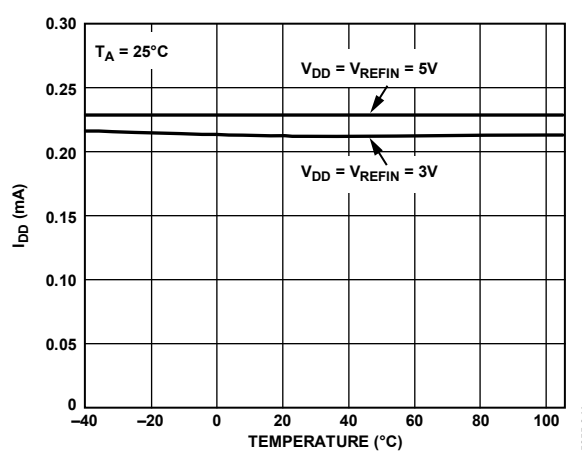


Figure 16. Supply Current vs. Temperature

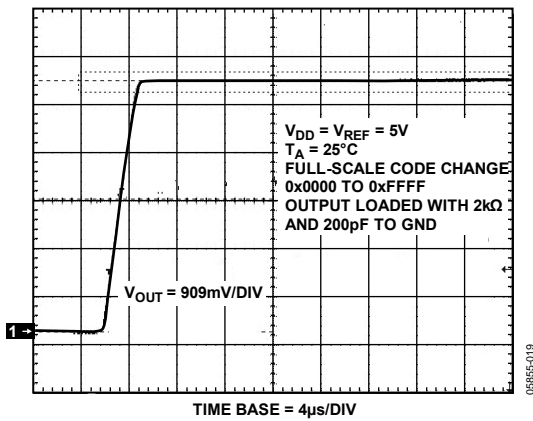


Figure 17. Full-Scale Settling Time, 5 V

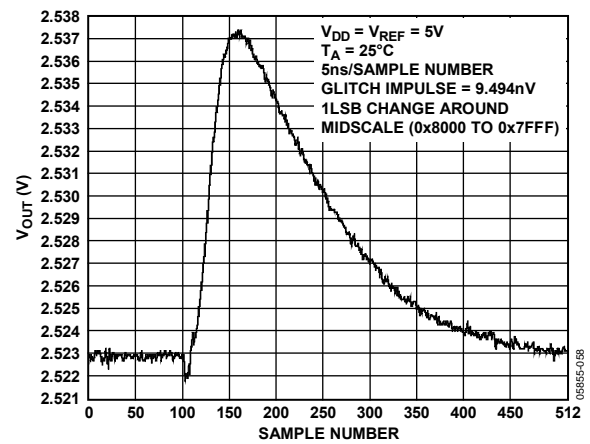


Figure 20. Digital-to-Analog Glitch Impulse (Negative)

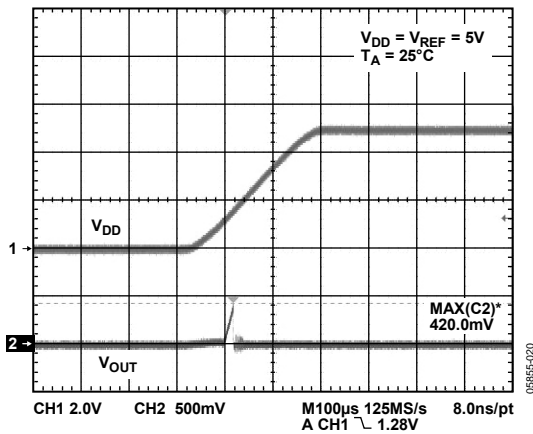


Figure 18. Power-On Reset to 0 V

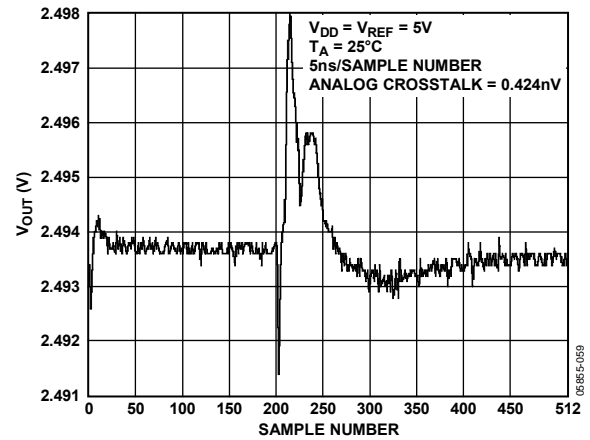


Figure 21. Analog Crosstalk

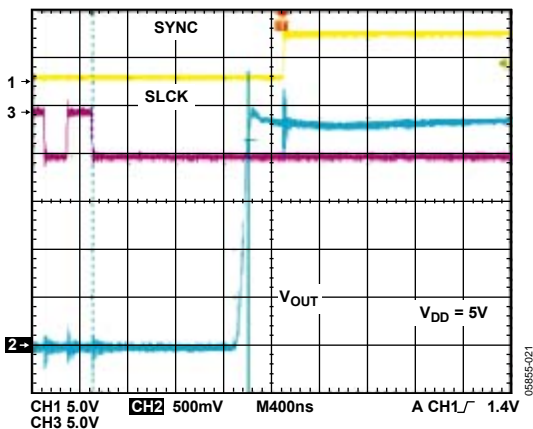


Figure 19. Exiting Power-Down to Midscale

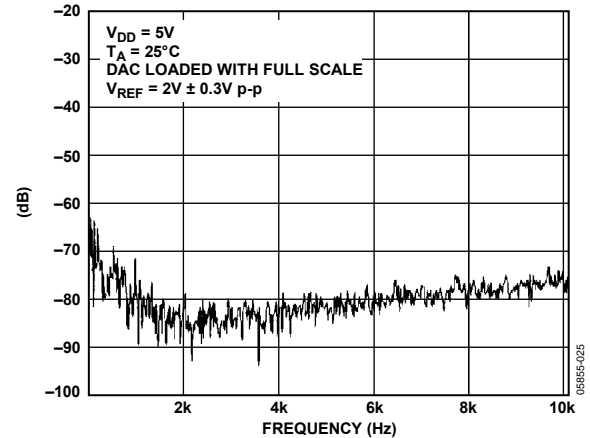


Figure 22. Total Harmonic Distortion

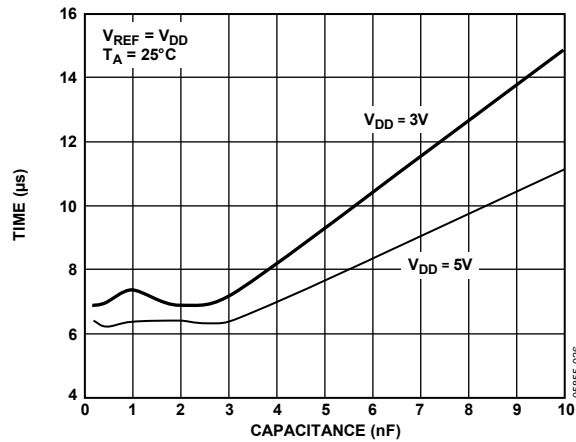


Figure 23. Settling Time vs. Capacitive Load

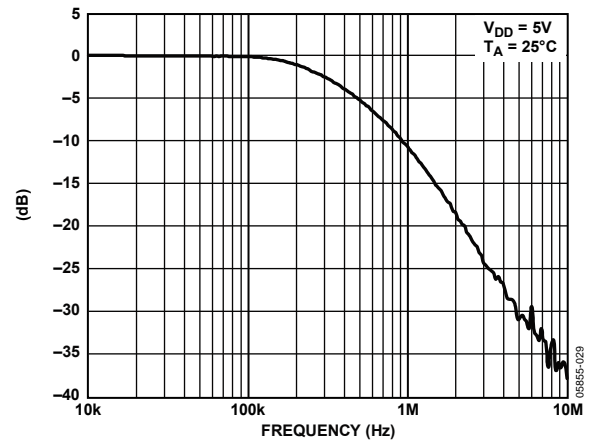


Figure 26. Multiplying Bandwidth

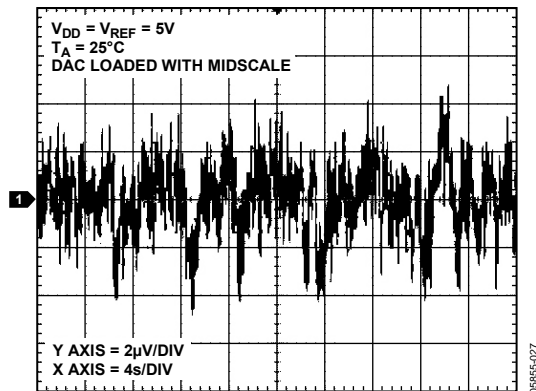


Figure 24. 0.1 Hz to 10 Hz Output Noise Plot

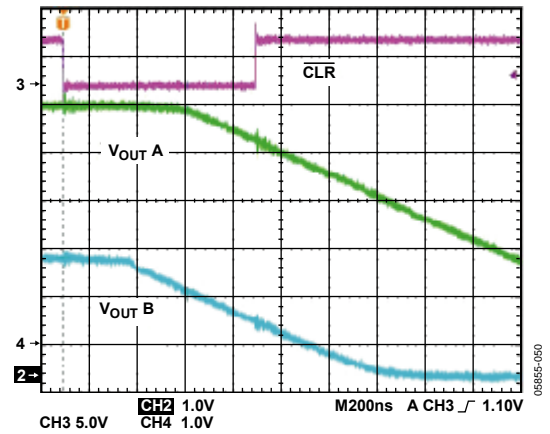


Figure 27. CLR Pulse Activation Time

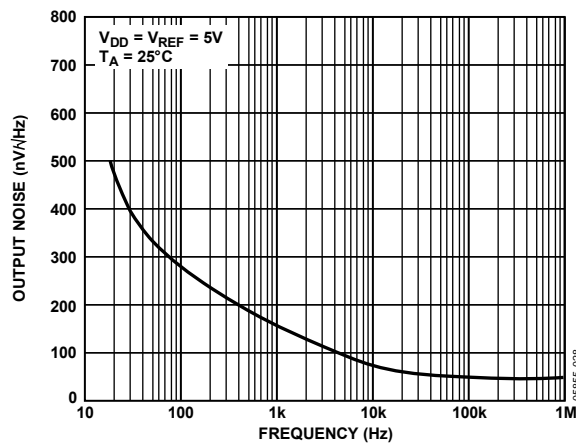


Figure 25. Noise Spectral Density

TERMINOLOGY

Relative Accuracy or Integral Nonlinearity (INL)

For the DAC, relative accuracy or integral nonlinearity is a measurement of the maximum deviation, in LSBs, from a straight line passing through the endpoints of the DAC transfer function. A typical INL vs. code plot is shown in Figure 5.

Differential Nonlinearity (DNL)

Differential nonlinearity is the difference between the measured change and the ideal 1 LSB change between any two adjacent codes. A specified differential nonlinearity of ± 1 LSB maximum ensures monotonicity. This DAC is guaranteed monotonic by design. A typical DNL vs. code plot is shown in Figure 6.

Zero-Scale Error

Zero-scale error is a measurement of the output error when zero code (0x0000) is loaded to the DAC register. Ideally, the output should be 0 V. The zero-scale error is always positive in the AD5663 because the output of the DAC cannot go below 0 V. It is due to a combination of the offset errors in the DAC and the output amplifier. Zero-scale error is expressed in mV. A plot of zero-scale error vs. temperature is shown in Figure 11.

Full-Scale Error

Full-scale error is a measurement of the output error when full-scale code (0xFFFF) is loaded to the DAC register. Ideally, the output should be $V_{DD} - 1$ LSB. Full-scale error is expressed in percent of full-scale range. A plot of full-scale error vs. temperature is shown in Figure 10.

Gain Error

Gain error is a measure of the span error of the DAC. It is the deviation in slope of the DAC transfer characteristic from ideal expressed as a percent of the full-scale range.

Zero-Scale Error Drift

Zero-scale error drift is a measurement of the change in zero-scale error with a change in temperature. It is expressed in $\mu\text{V}/^\circ\text{C}$.

Gain Temperature Coefficient

Gain temperature coefficient is a measurement of the change in gain error with changes in temperature. It is expressed in (ppm of full-scale range)/ $^\circ\text{C}$.

Offset Error

Offset error is a measure of the difference between V_{OUT} (actual) and V_{OUT} (ideal) expressed in mV in the linear region of the transfer function. Offset error is measured on the AD5663 with Code 512 loaded in the DAC register. It can be negative or positive.

DC Power Supply Rejection Ratio (PSRR)

PSRR indicates how the output of the DAC is affected by changes in the supply voltage. PSRR is the ratio of the change in V_{OUT} to a change in V_{DD} for full-scale output of the DAC. It is measured in dB. V_{REF} is held at 2 V, and V_{DD} is varied by $\pm 10\%$.

Output Voltage Settling Time

Output voltage settling time is the amount of time it takes for the output of a DAC to settle to a specified level for a 1/4 to 3/4 full-scale input change and is measured from the 24th falling edge of SCLK.

Digital-to-Analog Glitch Impulse

Digital-to-analog glitch impulse is the impulse injected into the analog output when the input code in the DAC register changes state. It is normally specified as the area of the glitch in nV-s, and is measured when the digital input code is changed by 1 LSB at the major carry transition (0x7FFF to 0x8000). See Figure 20.

Digital Feedthrough

Digital feedthrough is a measure of the impulse injected into the analog output of the DAC from the digital inputs of the DAC, but it is measured when the DAC output is not updated. It is specified in nV-s and measured with a full-scale code change on the data bus, that is, from all 0s to all 1s and vice versa.

Total Harmonic Distortion (THD)

Total harmonic distortion is the difference between an ideal sine wave and its attenuated version using the DAC. The sine wave is used as the reference for the DAC, and the THD is a measurement of the harmonics present on the DAC output. It is measured in dB.

Noise Spectral Density

Noise spectral density is a measurement of the internally generated random noise. Random noise is characterized as a spectral density (voltage per $\sqrt{\text{Hz}}$). It is measured by loading the DAC to midscale and measuring noise at the output. It is measured in $\text{nV}/\sqrt{\text{Hz}}$. Figure 25 shows a plot of noise spectral density.

DC Crosstalk

DC crosstalk is the dc change in the output level of one DAC in response to a change in the output of another DAC. It is measured with a full-scale output change on one DAC (or soft power-down and power-up) while monitoring another DAC kept at midscale. It is expressed in μV .

DC crosstalk due to load current change is a measure of the impact that a change in load current on one DAC has to another DAC kept at midscale. It is expressed in $\mu\text{V}/\text{mA}$.

Digital Crosstalk

Digital crosstalk is the glitch impulse transferred to the output of one DAC at midscale in response to a full-scale code change (all 0s to all 1s and vice versa) in the input register of another DAC. It is measured in standalone mode and is expressed in nV-s.

Analog Crosstalk

Analog crosstalk is the glitch impulse transferred to the output of one DAC due to a change in the output of another DAC. It is measured by loading one of the input registers with a full-scale code change (all 0s to all 1s and vice versa) while keeping $\overline{\text{LDAC}}$ high. Then pulse $\overline{\text{LDAC}}$ low and monitor the output of the DAC whose digital code was not changed. The area of the glitch is expressed in nV-s.

DAC-to-DAC Crosstalk

DAC-to-DAC crosstalk is the glitch impulse transferred to the output of one DAC due to a digital code change and subsequent output change of another DAC. This includes both digital and analog crosstalk. It is measured by loading one of the DACs with a full-scale code change (all 0s to all 1s and vice versa) with $\overline{\text{LDAC}}$ low and monitoring the output of another DAC. The energy of the glitch is expressed in nV-s.

Multiplying Bandwidth

The amplifiers within the DAC have a finite bandwidth. The multiplying bandwidth is a measure of this. A sine wave on the reference (with full-scale code loaded to the DAC) appears on the output. The multiplying bandwidth is the frequency at which the output amplitude falls to 3 dB below the input.

THEORY OF OPERATION

D/A SECTION

The AD5663 DAC is fabricated on a CMOS process. The architecture consists of a string DAC followed by an output buffer amplifier. Figure 28 shows a block diagram of the DAC architecture.

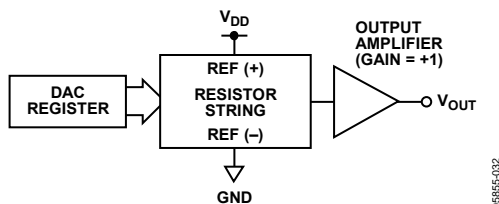


Figure 28. DAC Architecture

Because the input coding to the DAC is straight binary, the ideal output voltage is given by

$$V_{OUT} = V_{REF} \times \left(\frac{D}{65,536} \right)$$

where D is the decimal equivalent of the binary code that is loaded to the DAC register. It can range from 0 to 65,535.

RESISTOR STRING

The resistor string section is shown in Figure 29. It is a string of resistors, each of Value R . The code loaded to the DAC register determines at which node on the string the voltage is tapped off to be fed into the output amplifier. The voltage is tapped off by closing one of the switches connecting the string to the amplifier. Because it is a string of resistors, it is guaranteed monotonic.

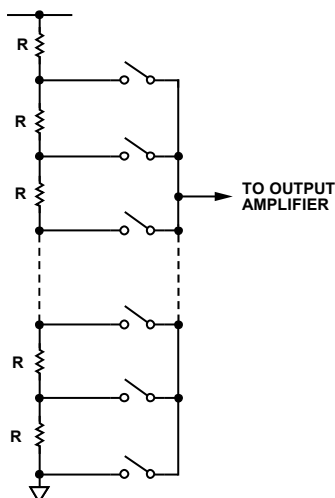


Figure 29. Resistor String

OUTPUT AMPLIFIER

The output buffer amplifier can generate rail-to-rail voltages on its output, which gives an output range of 0 V to V_{DD} . It can drive a load of 2 k Ω in parallel with 1000 pF to GND.

The source and sink capabilities of the output amplifier can be seen in Figure 15. The slew rate is 1.8 V/ μ s with a 1/4 to 3/4 full-scale settling time of 10 μ s.

SERIAL INTERFACE

The AD5663 has a 3-wire serial interface ($\overline{\text{SYNC}}$, SCLK, and DIN) that is compatible with SPI, QSPI, and MICROWIRE interface standards, as well as with most DSPs. See Figure 2 for a timing diagram of a typical write sequence.

The write sequence begins by bringing the $\overline{\text{SYNC}}$ line low. Data from the DIN line is clocked into the 24-bit shift register on the falling edge of SCLK. The serial clock frequency can be as high as 50 MHz, making the AD5663 compatible with high speed DSPs. On the 24th falling clock edge, the last data bit is clocked in and the programmed function is executed; that is, there is a change in DAC register contents and/or a change in the mode of operation. At this stage, the $\overline{\text{SYNC}}$ line can be kept low or be brought high. In either case, it must be brought high for a minimum of 15 ns before the next write sequence so that a falling edge of $\overline{\text{SYNC}}$ can initiate the next write sequence. Because the $\overline{\text{SYNC}}$ buffer draws more current when $V_{IN} = 2.0$ V than it does when $V_{IN} = 0.10$ V, $\overline{\text{SYNC}}$ should be idled low between write sequences for even lower power operation. As mentioned previously, however, it must be brought high again just before the next write sequence.

INPUT SHIFT REGISTER

The input shift register is 24 bits wide (see Figure 30). The first two bits are don't cares. The next three are the Command Bit C2 to Command Bit C0 (see Table 7), followed by the 3-bit DAC Address A2 to DAC Address A0 (see Table 8), and, finally, the 16-bit data-word. These are transferred to the DAC register on the 24th falling edge of SCLK.

Table 7. Command Definition

C2	C1	C0	Command
0	0	0	Write to input register n
0	0	1	Update DAC register n
0	1	0	Write to input register n , update all (software LDAC)
0	1	1	Write to and update DAC channel n
1	0	0	Power down DAC (power up)
1	0	1	Reset
1	1	0	$\overline{\text{LDAC}}$ register setup
1	1	1	Reserved

Table 8. Address Command

A2	A1	A0	ADDRESS (n)
0	0	0	DAC A
0	0	1	DAC B
0	1	0	Reserved
0	1	1	Reserved
1	1	1	All DACs

SYNC INTERRUPT

In a normal write sequence, the $\overline{\text{SYNC}}$ line is kept low for at least 24 falling edges of SCLK, and the DAC is updated on the 24th falling edge. However, if $\overline{\text{SYNC}}$ is brought high before the 24th falling edge, this acts as an interrupt to the write sequence. The shift register is reset and the write sequence is seen as invalid. Neither an update of the DAC register contents nor a change in the operating mode occurs (see Figure 31).

POWER-ON RESET

The AD5663 family contains a power-on reset circuit that controls the output voltage during power-up. The AD5663 DAC outputs power up to 0 V, the AD5663BRMZ-1 powers up to midscale, and the output remains there until a valid write sequence is made to the DAC. This is useful in applications where it is important to know the state of the output of the DAC while it is in the process of powering up. Any events on $\overline{\text{LDAC}}$ or $\overline{\text{CLR}}$ during power-on reset are ignored.

SOFTWARE RESET

The AD5663 contains a software reset function. Command 101 is reserved for the software reset function (see Table 7). The software reset command contains two reset modes that are software-programmable by setting Bit DB0 in the control register.

Table 9 shows how the state of the bit corresponds to the mode of operation of the device. Table 10 shows the contents of the input shift register during the software reset mode of operation.

After a full software reset (DB0 = 1), there must be a short time delay, approximately 5 μs , to complete the reset. During the reset, a low pulse can be observed on the $\overline{\text{CLR}}$ line. If the next SPI transaction commences before the $\overline{\text{CLR}}$ line returns high, that SPI transaction is ignored.

Table 9. Software Reset Modes for the AD5663

DB0	Registers Reset to 0
0	DAC register Input register
1 (Power-On Reset)	DAC register Input register $\overline{\text{LDAC}}$ register Power-down register

Table 10. 24-Bit Input Shift Register Contents for Software Reset Command

MSB								LSB	
DB23 to DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15 to DB1	DB0	
x	1	0	1	x	x	x	x	1/0	
Don't care	Command bits (C2 to C0)			Address bits (A2 to A0)			Don't care	Determines software reset mode	

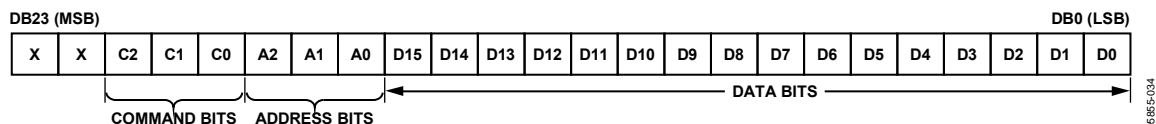
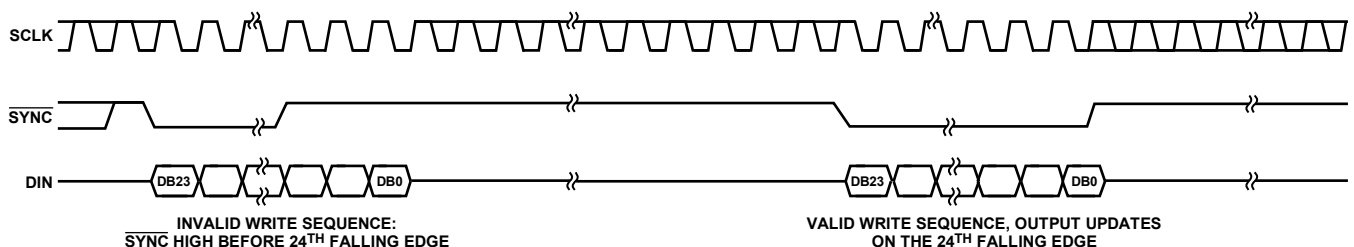


Figure 30. Input Register Contents

Figure 31. $\overline{\text{SYNC}}$ Interrupt Facility

POWER-DOWN MODES

The AD5663 contains four separate modes of operation. Command 100 is reserved for the power-down function (see Table 7). These modes are software-programmable by setting Bit DB5 and Bit DB4 in the control register. Table 11 shows how the state of the bits corresponds to the mode of operation of the device. Any or all DACs (DAC B and DAC A) can be powered down to the selected mode by setting the corresponding two bits (Bit DB1 and Bit DB0) to 1. By executing the same Command 100, any combination of DACs can be powered up by setting Bit DB5 and Bit DB4 to normal operation mode. Again, to select which combination of DAC channels to power up, set the corresponding two bits (Bit DB1 and Bit DB0) to 1. See Table 12 for contents of the input shift register during power-down/power-up operation.

The DAC output powers up to the value in the input register while $\overline{\text{LDAC}}$ is low. If $\overline{\text{LDAC}}$ is high, the DAC output powers up to the value held in the DAC register before power-down.

When both bits are set to 0, the part works normally with its normal power consumption of 500 μA at 5 V. However, for the three power-down modes, the supply current falls to 480 nA at 5 V (100 nA at 3 V). Not only does the supply current fall, but the output stage is also internally switched from the output of the amplifier to a resistor network of known values. This has the advantage that the output impedance of the part is known while the part is in power-down mode. The outputs can either be connected internally to GND through a 1 k Ω or 100 k Ω register or left open-circuited (three-state) (see Figure 32).

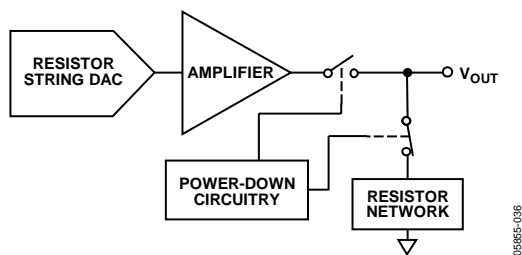


Figure 32. Output Stage During Power-Down

The bias generator, the output amplifier, the resistor string, and other associated linear circuitry are shut down when power-down mode is activated. However, the contents of the DAC register are unaffected when in power-down.

Table 12. 24-Bit Input Shift Register Contents of Power-Up/Power-Down Function

MSB								LSB					
DB23 to DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15 to DB6	DB5	DB4	DB3	DB2	DB1	DB0
x	1	0	0	x	x	x	x	PD1	PD0	x	x	DAC B	DAC A
Don't care	Command bits (C2 to C0)			Address bits (A2 to A0); don't care			Don't care	Power-down mode		Don't care		Power down/Power up channel selection; set bit to 1 to select channel	

The time required to exit power-down is typically 4 μs for $V_{\text{DD}} = 5\text{ V}$ and for $V_{\text{DD}} = 3\text{ V}$ (see Figure 19).

Table 11. Power-Down Modes of Operation for the AD5663

DB5	DB4	Operating Mode
0	0	Normal operation
		Power-Down Modes
0	1	1 k Ω to GND
1	0	100 k Ω to GND
1	1	Three-state

LDAC FUNCTION

The AD5663 DAC has double-buffered interfaces consisting of two banks of registers: input registers and DAC registers. The input registers are connected directly to the input shift register and the digital code is transferred to the relevant input register on completion of a valid write sequence. The DAC registers contain the digital code used by the resistor strings.

Access to the DAC registers is controlled by the $\overline{\text{LDAC}}$ pin. When the $\overline{\text{LDAC}}$ pin is high, the DAC registers are latched and the input registers can change state without affecting the contents of the DAC registers. When $\overline{\text{LDAC}}$ is brought low, however, the DAC registers become transparent and the contents of the input registers are transferred to them. The double-buffered interface is useful if the user requires simultaneous updating of all DAC outputs. The user can write to one of the input registers individually and then, by bringing $\overline{\text{LDAC}}$ low when writing to the other DAC input register, all outputs update simultaneously.

These parts each contain an extra feature whereby a DAC register is not updated unless its input register has been updated since the last time $\overline{\text{LDAC}}$ was brought low. Normally, when $\overline{\text{LDAC}}$ is brought low, the DAC registers are filled with the contents of the input registers. In the case of the AD5663, the DAC register updates only if the input register has changed since the last time the DAC register was updated, thereby removing unnecessary digital crosstalk.

The outputs of all DACs can be updated simultaneously using the hardware $\overline{\text{LDAC}}$ pin.

Synchronous $\overline{\text{LDAC}}$: The DAC registers are updated after new data is read in on the falling edge of the 24th SCLK pulse. $\overline{\text{LDAC}}$ can be permanently low or pulsed, as shown in Figure 2.

Asynchronous $\overline{\text{LDAC}}$: The outputs are not updated at the same time that the input registers are written to. When $\overline{\text{LDAC}}$ goes low, the DAC registers are updated with the contents of the input register.

The $\overline{\text{LDAC}}$ register gives the user full flexibility and control over the hardware $\overline{\text{LDAC}}$ pin. This register allows the user to select which combination of channels to simultaneously update when the hardware $\overline{\text{LDAC}}$ pin is executed. Setting the $\overline{\text{LDAC}}$ bit register to 0 for a DAC channel means that the update of this channel is controlled by the $\overline{\text{LDAC}}$ pin. If this bit is set to 1, this channel synchronously updates; that is, the DAC register is updated after new data is read in, regardless of the state of the $\overline{\text{LDAC}}$ pin. It effectively sees the $\overline{\text{LDAC}}$ pin as being pulled low. See Table 13 for the $\overline{\text{LDAC}}$ register mode of operation.

This flexibility is useful in applications where the user wants to simultaneously update select channels while the rest of the channels are synchronously updating

Writing to the DAC using Command 110 loads the 2-bit $\overline{\text{LDAC}}$ register [DB1:DB0]. The default for each channel is 0; that is, the $\overline{\text{LDAC}}$ pin works normally. Setting the bits to 1 means the DAC register is updated regardless of the state of the $\overline{\text{LDAC}}$ pin. See Table 14 for contents of the input shift register during the $\overline{\text{LDAC}}$ register setup command.

Table 13. $\overline{\text{LDAC}}$ Register Mode of Operation

$\overline{\text{LDAC}}$ Bits (DB1 to DB0)	$\overline{\text{LDAC}}$ Pin	$\overline{\text{LDAC}}$ Operation
0	1/0	Determined by $\overline{\text{LDAC}}$ pin
1	x = don't care	The DAC registers are updated after new data is read in on the falling edge of the 24th SCLK pulse

Table 14. 24-Bit Input Shift Register Contents for $\overline{\text{LDAC}}$ Register Setup Command

MSB								LSB	
DB23 to DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15 to DB2	DB1	DB0
x	1	1	0	x	x	x	x	DAC B	DAC A
Don't care	Command bits (C2 to C0)			Address bits (A3 to A0); Don't care			Don't care	Set DAC to 0 or 1 for required mode of operation	

MICROPROCESSOR INTERFACING

AD5663 to Blackfin ADSP-BF537 Interface

Figure 33 shows a serial interface between the AD5663 and the Blackfin ADSP-BF537 microprocessor. The ADSP-BF537 incorporates two dual-channel synchronous serial ports, SPORT1 and SPORT0, for serial and multiprocessor communications. When using SPORT0 to connect to the AD5663, the setup for the interface is as follows:

- DT0PRI drives the DIN pin of the AD5663.
- TSCLK0 drives the SCLK of the device.
- The $\overline{\text{SYNC}}$ pin is driven from TFS0.

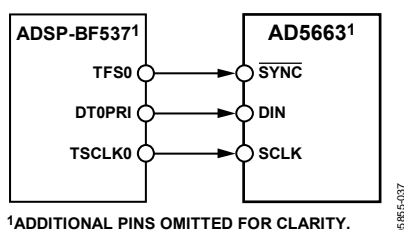


Figure 33. AD5663 to Blackfin ADSP-BF537 Interface

AD5663 to 68HC11/68L11 Interface

Figure 34 shows a serial interface between the AD5663 and the 68HC11/68L11 microcontroller. SCK of the 68HC11/68L11 drives the SCLK of the AD5663, and the MOSI output drives the serial data line of the DAC.

The $\overline{\text{SYNC}}$ signal is derived from a port line (PC7). The setup conditions for correct operation of this interface are as follows:

- The 68HC11/68L11 is configured with its CPOL bit as 0.
- The 68HC11/68L11 is configured with its CPHA bit as 1.

When data is being transmitted to the DAC, the $\overline{\text{SYNC}}$ line is taken low (PC7). When the 68HC11/68L11 is configured as previously described, data appearing on the MOSI output is valid on the falling edge of SCK. Serial data from the 68HC11/68L11 is transmitted in 10-bit bytes with only eight falling clock edges occurring in the transmit cycle. Data is transmitted MSB first. To load data to the AD5663, PC7 is left low after the first eight bits are transferred, and a second serial write operation is performed to the DAC. PC7 is taken high at the end of this procedure.

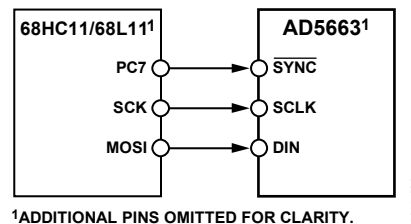


Figure 34. AD5663 to 68HC11/68L11 Interface

AD5663 to 80C51/80L51 Interface

Figure 35 shows a serial interface between the AD5663 and the 80C51/80L51 microcontroller. The setup for the interface is as follows:

- TxD of the 80C51/80L51 drives SCLK of the AD5663.
- RxD drives the serial data line of the part.

The $\overline{\text{SYNC}}$ signal is again derived from a bit-programmable pin on the port. In this case, Port Line P3.3 is used. When data is to be transmitted to the AD5663, P3.3 is taken low. The 80C51/80L51 transmits data in 10-bit bytes only; thus only eight falling clock edges occur in the transmit cycle. To load data to the DAC, P3.3 is left low after the first eight bits are transmitted, and a second write cycle is initiated to transmit the second byte of data. P3.3 is taken high following the completion of this cycle. The 80C51/80L51 outputs the serial data in a format that has the LSB first. The AD5663 must receive data with the MSB first. The 80C51/80L51 transmit routine should take this into account.

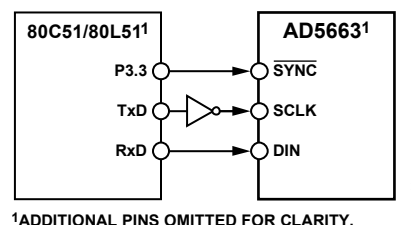


Figure 35. AD5663 to 80C51/80L51 Interface

AD5663 to MICROWIRE Interface

Figure 36 shows an interface between the AD5663 and any MICROWIRE-compatible device. Serial data is shifted out on the falling edge of the serial clock and is clocked into the AD5663 on the rising edge of the SK.

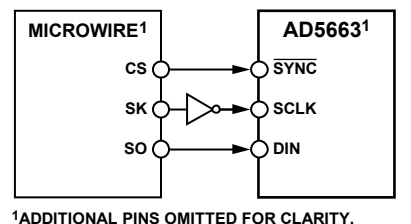


Figure 36. AD5663 to MICROWIRE Interface

APPLICATIONS

CHOOSING A REFERENCE FOR THE AD5663

To achieve the optimum performance from the AD5663, thought should be given to the choice of a precision voltage reference. The AD5663 has only one reference input, V_{REF} . The voltage on the reference input is used to supply the positive input to the DAC. Therefore, any error in the reference is reflected in the DAC.

When choosing a voltage reference for high accuracy applications, the sources of error are initial accuracy, ppm drift, long-term drift, and output voltage noise. Initial accuracy on the output voltage of the DAC leads to a full-scale error in the DAC. To minimize these errors, a reference with high initial accuracy is preferred. Also, choosing a reference with an output trim adjustment, such as the ADR423, allows a system designer to trim system errors out by setting a reference voltage to a voltage other than the nominal. The trim adjustment can also be used at temperature to trim out any error.

Long-term drift is a measurement of how much the reference drifts over time. A reference with a tight long-term drift specification ensures that the overall solution remains relatively stable during its entire lifetime.

The temperature coefficient of a reference's output voltage affects INL, DNL, and TUE. A reference with a tight temperature coefficient specification should be chosen to reduce temperature dependence of the DAC output voltage in ambient conditions.

In high accuracy applications, which have a relatively low noise budget, reference output voltage noise needs to be considered. It is important to choose a reference with as low an output noise voltage as practical for the system noise resolution required. Precision voltage references, such as the ADR425, produce low output noise in the 0.1 Hz to 10 Hz range. Examples of recommended precision references for use as supplies to the AD5663 are shown in the Table 15.

USING A REFERENCE AS A POWER SUPPLY FOR THE AD5663

Because the supply current required by the AD5663 is extremely low, an alternative option is to use a voltage reference to supply the required voltage to the part (see Figure 37). This is especially useful if the power supply is quite noisy, or if the system supply voltages are at some value other than 5 V or 3 V (for example, 15 V). The voltage reference outputs a steady supply voltage for the AD5663; see Table 15 for a suitable reference. If the low drop-out REF195 is used, it must supply 250 μ A of current to the AD5663, with no load on the output of the DAC. When the DAC output is loaded, the REF195 also needs to supply the current to the load. The total current required (with a 5 k Ω load on the DAC output) is

$$250 \mu\text{A} + (5 \text{ V} / 5 \text{ k}\Omega) = 1.25 \text{ mA}$$

The load regulation of the REF195 is typically 2 ppm/mA, which results in a 2.5 ppm (12.5 μ V) error for the 1.25 mA current drawn from it. This corresponds to a 0.164 LSB error.

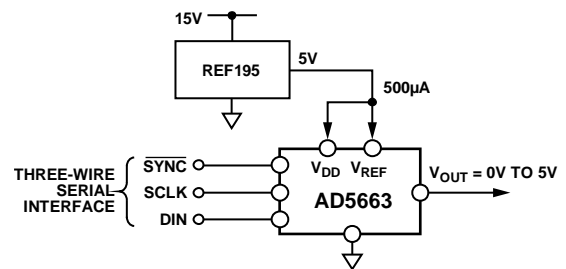


Figure 37. REF195 as Power Supply to the AD5663

Table 15. Partial List of Precision References for Use with the AD5663

Part No.	Initial Accuracy (mV Max)	Temperature Drift (ppm/°C Max)	0.1 Hz to 10 Hz Noise (μ V p-p Typ)	V_{OUT} (V)
ADR425	± 2	3	3.4	5
ADR395	± 6	25	5	5
REF195	± 2	5	50	5
AD780	± 2	3	4	2.5/3
ADR423	± 2	3	3.4	3

BIPOLAR OPERATION USING THE AD5663

The AD5663 has been designed for single-supply operation, but a bipolar output range is also possible using the circuit in Figure 38. The circuit gives an output voltage range of ± 5 V. Rail-to-rail operation at the amplifier output is achievable using an AD820 or an OP295 as the output amplifier.

The output voltage for any input code can be calculated as

$$V_O = \left[V_{DD} \times \left(\frac{D}{65,536} \right) \times \left(\frac{R1 + R2}{R1} \right) - V_{DD} \times \left(\frac{R2}{R1} \right) \right]$$

where D represents the input code in decimal (0 to 65,535).

With $V_{DD} = 5$ V, $R1 = R2 = 10$ k Ω

$$V_O = \left(\frac{10 \times D}{65,536} \right) - 5 \text{ V}$$

This is an output voltage range of ± 5 V, with 0x0000 corresponding to a -5 V output, and 0xFFFF corresponding to a $+5$ V output.

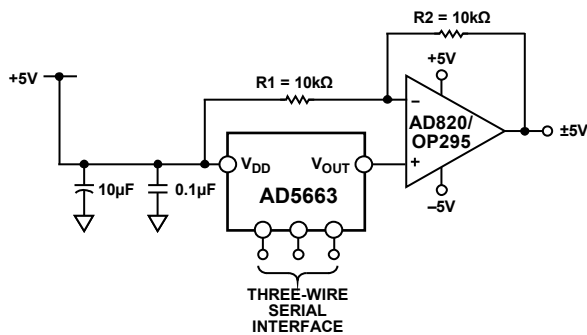


Figure 38. Bipolar Operation with the AD5663

USING THE AD5663 WITH A GALVANICALLY ISOLATED INTERFACE

In process control applications in industrial environments, it is often necessary to use a galvanically isolated interface to protect and isolate the controlling circuitry from any hazardous common-mode voltages that can occur in the area where the DAC is functioning. *iCoupler*® provides isolation in excess of 2.5 kV. The AD5663 use a 3-wire serial logic interface, so the ADuM1300 three-channel digital isolator provides the required isolation (see Figure 39). The power supply to the part also needs to be isolated, which is done by using a transformer. On the DAC side of the transformer, a 5 V regulator provides the 5 V supply required for the AD5663.

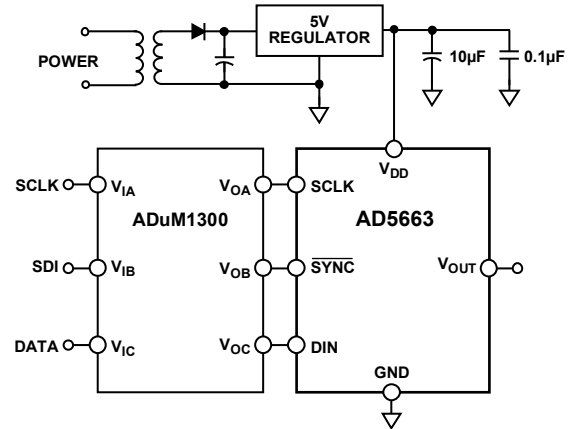


Figure 39. AD5663 with a Galvanically Isolated Interface

POWER SUPPLY BYPASSING AND GROUNDING

When accuracy is important in a circuit, it is helpful to carefully consider the power supply and ground return layout on the board. The printed circuit board containing the AD5663 should have separate analog and digital sections, each having its own area of the board. If the AD5663 is in a system where other devices require an AGND-to-DGND connection, the connection should be made at one point only. This ground point should be as close as possible to the AD5663.

The power supply to the AD5663 should be bypassed with 10 μ F and 0.1 μ F capacitors. The capacitors should be located as close as possible to the device, with the 0.1 μ F capacitor ideally right up against the device. The 10 μ F capacitors are of the tantalum bead type. It is important that the 0.1 μ F capacitor have low effective series resistance (ESR) and effective series inductance (ESI) as in, for example, common ceramic types of capacitors. This 0.1 μ F capacitor provides a low impedance path to ground for high frequencies caused by transient currents due to internal logic switching.

The power supply line itself should have as large a trace as possible to provide a low impedance path and to reduce glitch effects on the supply line. Clocks and other fast switching digital signals should be shielded from other parts of the board by digital ground. Avoid crossover of digital and analog signals if possible. When traces cross on opposite sides of the board, ensure that they run at right angles to each other to reduce feedthrough effects through the board. The best board layout technique is the microstrip technique, where the component side of the board is dedicated to the ground plane only, and the signal traces are placed on the solder side. However, this is not always possible with a 2-layer board.

OUTLINE DIMENSIONS

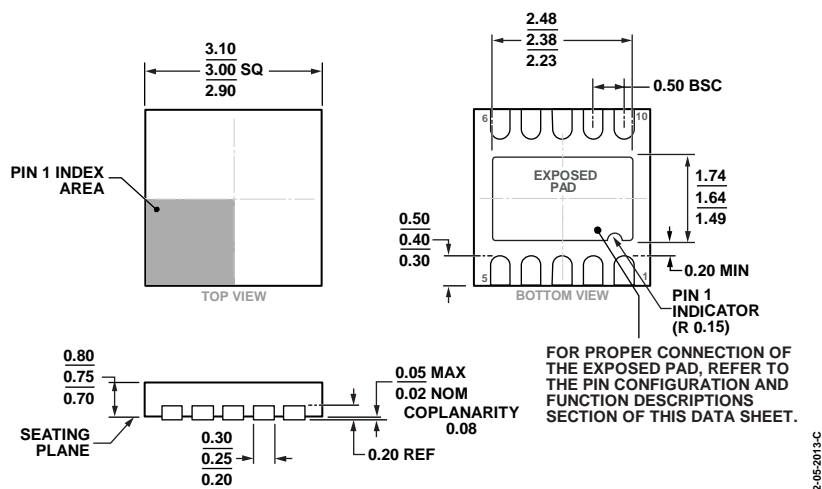
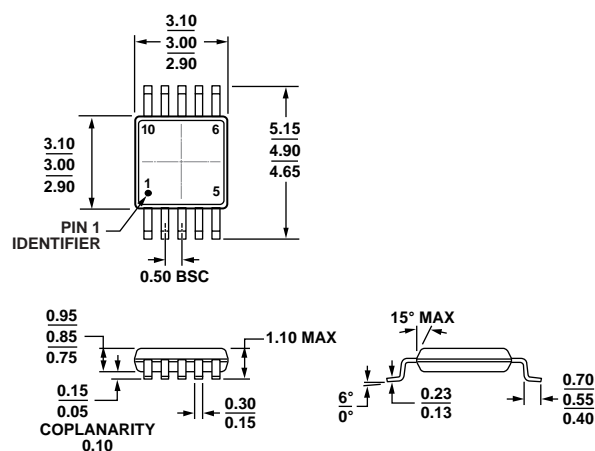


Figure 40. 10-Lead Lead Frame Chip Scale Package [LFCSP_WD]
3 mm × 3 mm Body, Very Very Thin, Dual Lead
(CP-10-9)

Dimensions shown in millimeters



COMPLIANT TO JEDEC STANDARDS MO-187-BA

Figure 41. 10-Lead Mini Small Outline Package [MSOP]
(RM-10)

Dimensions shown in millimeters

ORDERING GUIDE

Model ¹	Temperature Range	Power-On Reset Code	Accuracy	Package Description	Package Option	Branding
AD5663ARMZ	−40°C to +105°C	Zero	±16 LSB INL	10-Lead MSOP	RM-10	D80
AD5663ARMZ-REEL7	−40°C to +105°C	Zero	±16 LSB INL	10-Lead MSOP	RM-10	D80
AD5663BRMZ	−40°C to +105°C	Zero	±12 LSB INL	10-Lead MSOP	RM-10	D8C
AD5663BRMZ-REEL7	−40°C to +105°C	Zero	±12 LSB INL	10-Lead MSOP	RM-10	D8C
AD5663BRMZ-1	−40°C to +105°C	Midscale	±12 LSB INL	10-Lead MSOP	RM-10	D7J
AD5663BRMZ-1REEL7	−40°C to +105°C	Midscale	±12 LSB INL	10-Lead MSOP	RM-10	D7J
AD5663BCPZ-R2	−40°C to +105°C	Zero	±12 LSB INL	10-Lead LFCSP_WD	CP-10-9	D8C
AD5663BCPZ-REEL7	−40°C to +105°C	Zero	±12 LSB INL	10-Lead LFCSP_WD	CP-10-9	D8C

¹ Z = RoHS Compliant Part.

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