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1 Overview

The STA321 is a single chip solution for digital audio processing applications of up to 4.0 channels.

The STA321 is part of the Sound Terminal™ family that together with the digital power stage provides full digital audio streaming to the speaker, offering cost effectiveness, low energy dissipation and sound enrichment.

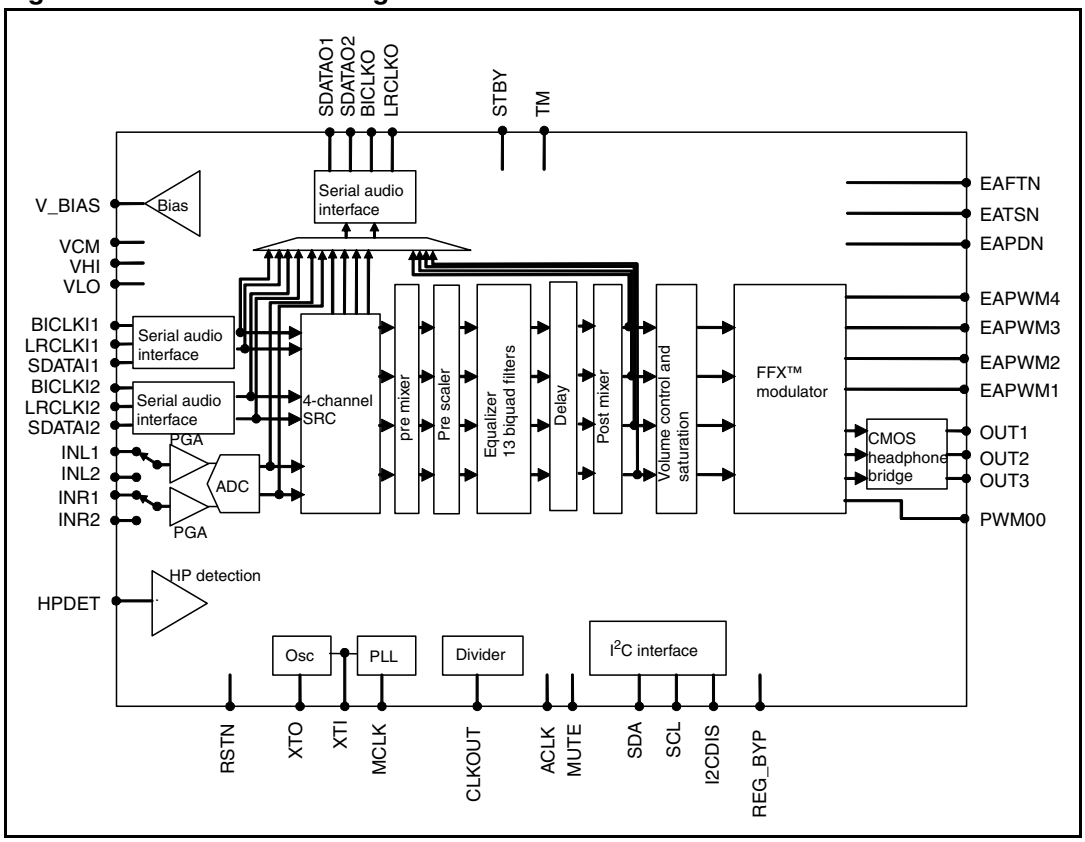
The STA321 input section consists of two multiplexed stereo analog inputs, a 16-bit ADC and two independent digital input interfaces. The serial audio data input interface accepts all possible formats, including the popular I^2S format. There is also a digital output interface fed by the ADC or by the digitally processed signals.

The device has a full assortment of digital processing features. This includes sample rate converter, pre and post mixing, up to 13 programmable 28-bit biquads (EQ) per channel, bass/treble tone control and DRC. The embedded headphone detector indicates when headphone jack is inserted.

The STA321 provides four independent channels of FFX™ output capabilities. In conjunction with a power device, it provides high-quality, high-efficiency, all digital amplification.

The embedded CMOS bridge supplies up to 0.5 W into an 8-Ω load and 70 mW into a 16-Ω load for the headphones output.

Figure 1. STA321 block diagram



2 Pin description

Figure 2. Pin out

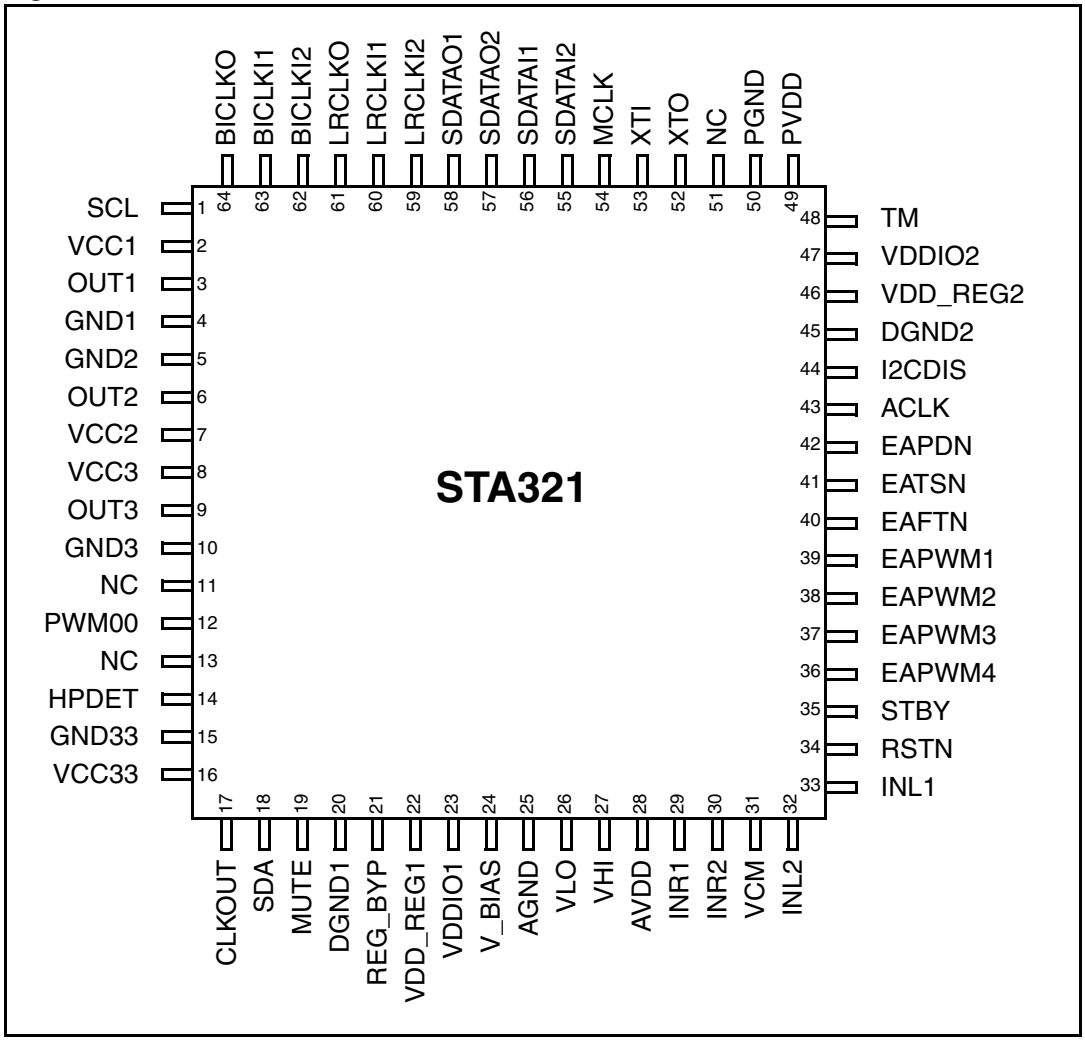


Table 2. Pin list

Pin	Pull	Name	Type	Description
1	-	SCL	In (digital), schmitt tr	I^2C serial clock, schmitt trigger input
3	-	OUT1	Out (analog)	HP/line-out PWM 1
6	-	OUT2	Out (analog)	HP/line-out PWM 2
9	-	OUT3	Out (analog)	HP/line-out PWM 3
11	-	NC	-	Not connected
12	-	PWM00	Out (digital)	Auxiliary PWM
13	-	NC	-	Not connected
14	-	HPDET	In (analog)	Headphone detection

Table 2. Pin list (continued)

Pin	Pull	Name	Type	Description
17	-	CLKOUT	Out (digital)	Buffered clock output
18	-	SDA	In/Out (digital)	I^2C serial data
19	H	MUTE	In (digital)	Mute (active high)
21	-	REG_BYPASS	In (analog)	DC regulator bypass: 0: normal operation, regulator enabled 1: regulator bypassed
24	-	BIAS	In/Out (analog)	ADC microphone bias voltage
26	-	VLO	In (analog)	ADC low reference voltage
27	-	VHI	In (analog)	ADC high reference voltage
29	-	INR1	In/Out (analog)	ADC right channel line input1
30	-	INR2	In/Out (analog)	ADC right channel line input2
31	-	VCM	In/Out (analog)	ADC common mode voltage
32	-	INL2	In (analog)	ADC left channel line input2 or microphone input2
33	-	INL1	In (analog)	ADC left channel line input1 or microphone input1
34	H	RSTN	In (digital)	Reset: 0: reset state 1: normal operation
35	-	STBY	In (digital)	Standby mode: 0: normal operation 1: power-down
36	-	EAPWM4	Out (digital)	External amplifier PWM 4B
37	-	EAPWM3	Out (digital)	External amplifier PWM 4A
38	-	EAPWM2	Out (digital)	External amplifier PWM 3B
39	-	EAPWM1	Out (digital)	External amplifier PWM 3A
40	H	EAFTN	Out (digital)	External power fault signal: 0: fault 1: normal operational mode
41	-	EATSN	Out (digital)	External amplifier control: 0: active 1: 3-state
42	-	EAPDN	Out (digital)	External amplifier powerdown (active low)
43	-	ACLK	In (digital), schmitt tr	Reserved pin, connect to ground
44	L	I2CDIS	In (digital)	I^2C disable: 0: I^2C enabled 1: I^2C disabled
48	L	TM	In (digital)	Test mode: 0: normal operation
51	-	NC	-	Not connected

Table 2. Pin list (continued)

Pin	Pull	Name	Type	Description
52	-	XTO	Out (digital), 1.8 V	Crystal output
53	-	XTI	In (digital), 1.8 V	Crystal input or master clock input
54	-	MCLK	In (digital), schmitt tr	Master clock input 3.3-V compatible, schmitt input
55	-	SDATAI2	In (digital)	Input serial audio interface data
56	-	SDATAI1	In (digital)	Input serial audio interface data
57	-	SDATAO2	Out (digital)	Output serial audio interface data
58	-	SDATAO1	Out (digital)	Output serial audio interface data
59	-	LRCLKI2	In/Out (digital)	Input serial audio interface L/R-clock
60	-	LRCLKI1	In/Out (digital)	Input serial audio interface L/R-clock
61	-	LRCLKO	In/Out (digital)	Output serial audio interface L/R-clock (volume DOWN when I2CDIS=1)
62	-	BICLKI2	In/Out (digital)	Input serial audio interface bit clock
63	-	BICLKI1	In/Out (digital)	Input serial audio interface bit clock
64	-	BICLKO	In/Out (digital)	Output serial audio interface bit clock (volume UP when I2CDIS=1)

Table 3. Power supply pin list

Number	Name	Type	Description
2	VCC1	Supply	CMOS bridge channel 1 supply
4	GND1	Ground	CMOS bridge channel 1 ground
5	GND2	Ground	CMOS bridge channel 2 ground
7	VCC2	Supply	CMOS bridge channel 2 supply
8	VCC3	Supply	CMOS bridge channel 3 supply
10	GND3	Ground	CMOS bridge channel 3 ground
15	GND33	Ground	CMOS bridge level shifter ground
16	VCC33	Supply	CMOS bridge level shifter supply
20	DGND1	Ground	Digital ground
22	VDD_REG1	Supply	DC regulator unit supply
23	VDDIO1	Supply	3.3-V IO supply
25	AGND	Ground	ADC analog ground
28	AVDD	Supply	ADC analog supply
45	DGND2	Ground	Digital ground
46	VDD_REG2	Supply	DC regulator unit supply
47	VDDIO2	Supply	3.3-V IO supply
49	PVDD	Supply	PLL analog supply
50	PGND	Ground	PLL analog ground

3 Electrical specifications

3.1 Absolute maximum ratings

Table 4. Absolute maximum ratings

Pin name/Symbol	Parameter	Negative	Positive	Unit
VDD_REG1, VDD_REG2	Digital supply voltage	-0.3	4.0	V
VDDIO1, VDDIO2	Digital IO supply voltage	-0.3	4.0	V
PVDD	PLL analog supply voltage	-0.3	4.0	V
AVDD	ADC analog supply voltage	-0.3	4.0	V
VCC1, VCC2, VCC3	CMOS bridge supply voltage	-0.3	4.0	V
VCC33	CMOS bridge level shifter power supply	-0.3	4.0	V
T_{STG}	Storage temperature	-40	150	°C
T_{OP}	Operating junction temperature	-20	125	°C

Note: All grounds must always be within 0.3 V of each other.

3.2 Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Min	Typ	Max	Unit
V_{VDD_REG1}, V_{VDD_REG2}	Digital supply voltage	2.5	3.3	3.6	V
V_{PVDD}	PLL analog supply voltage	2.5	3.3	3.6	V
V_{AVDD}	ADC analog supply voltage	1.8	3.3	3.6	V
V_{VCC1}, V_{VCC2}, V_{VCC3}	CMOS bridge supply voltage	1.55	-	3.3	V
V_{VCC33}	CMOS bridge level shifter power supply. Ensure that V_{VCC33} <= V_{VCCx} always	1.55	-	3.3	V
V_{VDDIO1}, V_{VDDIO2}	3.3-V IO supply	2.7	3.3	3.6	V
V_{IH}	High input voltage, 1.8-V pads	1.3	-	-	V
	High input voltage, 3.3-V pads	2.0	-	-	
V_{IL}	Low input voltage, 1.8-V pads	-	-	0.6	V
	Low input voltage, 3.3-V pads	-	-	0.8	
T_{amb}	Ambient temperature	0	-	70	°C

3.3 Electrical characteristics

Unless otherwise specified, the results in *Table 6* below are given for the operating conditions V_{CC} = 3.3 V, R_L = 32 Ω, f_{MCLK} = 12.288 MHz, Tamb = 25 °C and with the PLL set to default conditions.

Table 6. Electrical specifications

Symbol	Parameter	Test conditions	Min	Typ	Max	Unit
General						
V_{OH}	High output voltage, 1.8-V pads	-	1.4	-	-	V
	High output voltage, 3.3-V pads	-	V_{VDDIO} - 0.15	-	-	
V_{OL}	Low output voltage, 1.8-V pads	I_{OL} = 2 mA	-	-	0.15	V
	Low output voltage, 3.3-V pads	I_{OL} = 2 mA	-	-	0.15	
V_{hys}	Schmitt trigger hysteresis, 3.3-V IO	-	-	0.4	-	V
R_{UP}	Pull-up resistance	-	-	50	-	kΩ
R_{DN}	Pull-down resistance	-	-	50	-	kΩ
I_{STBYIO}	Standby current, pins VDDIO1,2	Pin STBY = 3.3 V CLKOUT disabled	-	450	-	µA
I_{DDIO}	Operating current, pins VDDIO1,2	-	-	3	-	mA
I_{STBYL0}	Standby current, pins VDD_REG1,2	Deep power-down, $V_{VDD\_REG1,2}$ = 3.3 V	-	450	-	µA
I_{STBYL1}	Standby current, pins VDD_REG1,2	Mild power-down, $V_{VDD\_REG1,2}$ = 3.3 V	-	2	-	mA
I_{DDL1}	Operating current, pins VDD_REG1,2	f_{MCLK} = 12.288 MHz, Play from SAI to CMOS bridge and EAPWM, f_{ADC} = 48 kHz on SAI_out, V_{AVDD} = 3.3 V, $V_{VDD\_REG1,2}$ = 3.3 V	-	45	-	mA
I_{STBYPD}	Pre-drive supply current in standby, pin VCC33	-	-	4.7	-	µA

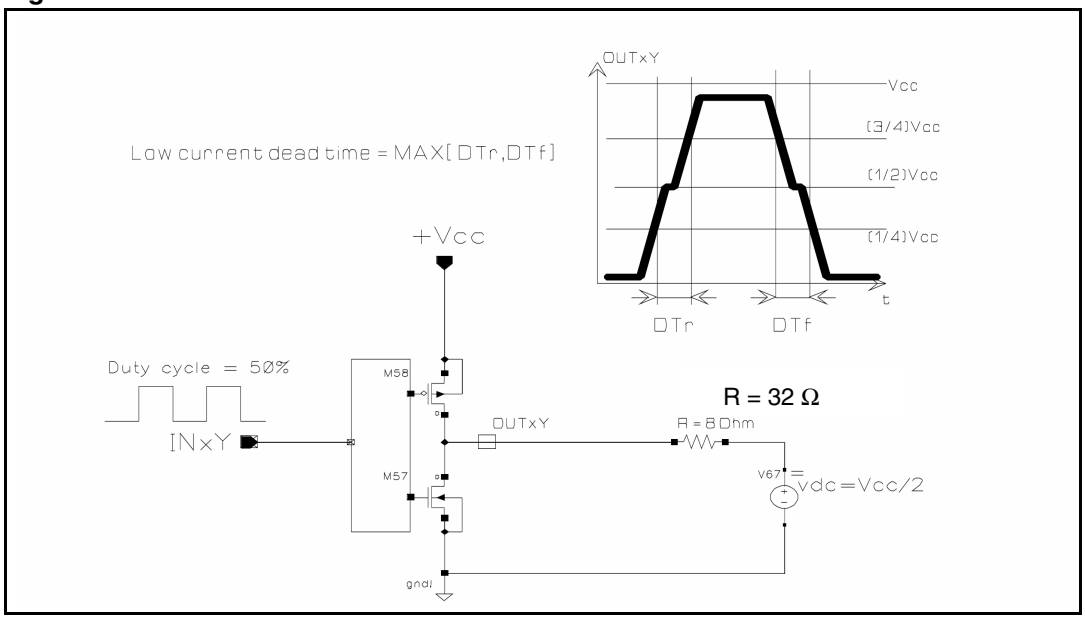
Table 6. Electrical specifications (continued)

Symbol	Parameter	Test conditions		Min	Typ	Max	Unit
Amplifier (CMOS bridge)							
η	Output power efficiency	-		-	90	-	%
P_{HPOUT}	Output power in HP mode with THD = 1%	3.3-V supply	R_L = 32 Ω	-	41	-	mW
	Output power in HP mode with THD = 10%	3.3-V supply	R_L = 32 Ω	-	53	-	
SNR	Signal to noise ratio	20 Hz to 20 kHz		-	75	-	dB
THD + N	Total harmonic distortion plus noise	RL = 32 Ω, HP mode	0 dBFs In	-	0.3	-	%
			-6 dBFs In	-	0.05	-	
DR	Dynamic range	A-weighted		-	80	-	dB
I_{STBYP}	Current in standby, pins VCCx	-		-	2	-	µA
I_{DDP}	Operating current, pins VCCx	No LC filter, no load, PWM at 50% duty-cycle		-	1	-	mA
I_{DDPD}	Pre-drive supply current in operation, pin VCC33	No load, PWM at 50% duty-cycle		-	250	350	µA
t_R	Driver rise time, pins OUT1-3	Resistive load, see *Figure 3*		-	5	-	ns
t_F	Driver fall time, pins OUT1-3	Resistive load, see *Figure 3*		-	5	-	ns
R_{DSON}	Headphone output stage N/P MOS on-resistance	-		-	500	700	mΩ
I_{OCH}	Over-current limit for OUT1-3 to VCCx short circuit	-		-	1.88	-	A
I_{OCL}	Over-current limit for OUT1-3 to ground short circuit	-		-	1.72	-	A
PLL							
$I_{STDBYPLL}$	PLL supply current in standby	-		-	20	-	µA
I_{DDPLL}	PLL supply current in operation	-		-	0.4	1.0	mA
f_{CLKIN_Range}	Input clock frequency range	-		2.048	-	49.152	MHz
$Duty_{CLKIN}$	Input clock duty cycle	-		40	-	60	%
t_{CLKIN_RF}	Input clock rise/fall time	-		-	-	0.2	ns
f_{F_INT}	PFD input clock frequency	PLL_FR_CTRL = 1		2.048	-	12.288	MHz
f_{VCO_Range}	Clock out range	-		65.536	-	98.304	MHz
$Duty_{VCO}$	Clock out duty cycle	-		35	-	65	%
T_{LOCK}	Lock time	-		-	-	200	µs

Table 6. Electrical specifications (continued)

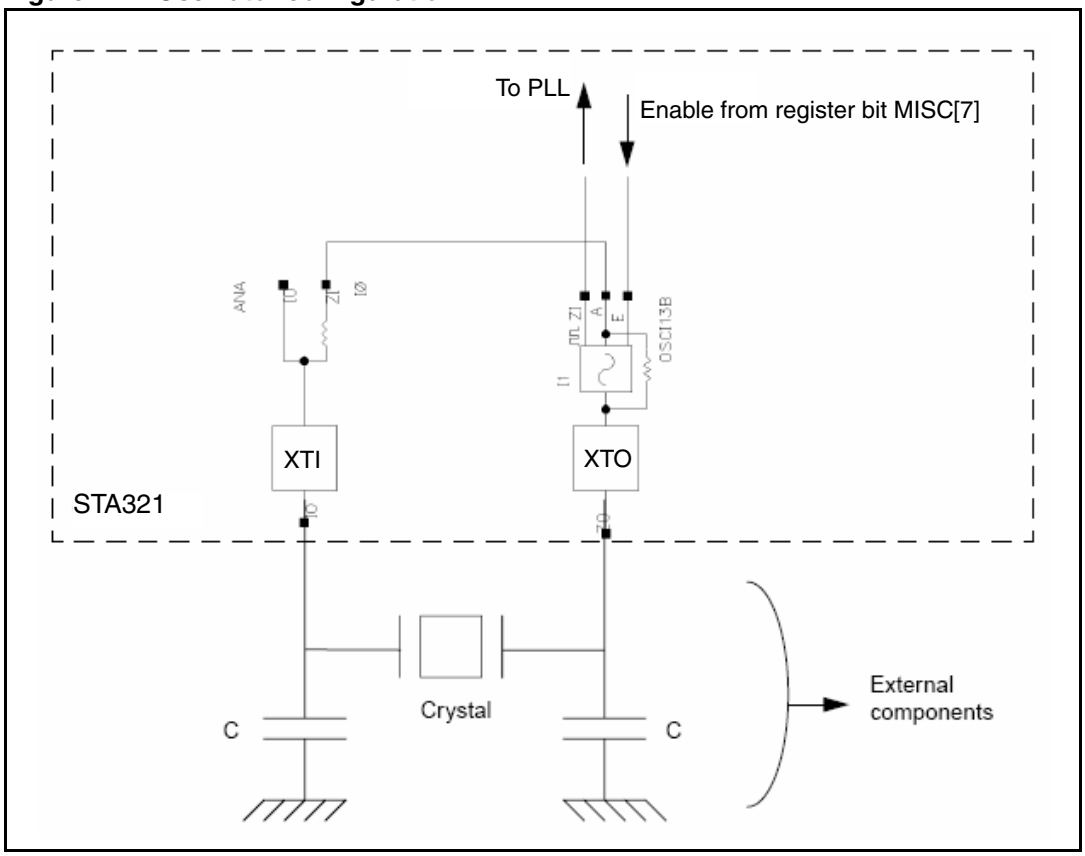
Symbol	Parameter	Test conditions	Min	Typ	Max	Unit
ADC						
I_{DDA}	Supply current in operating mode	V_{AVDD} = 3.3V	-	10	15	mA
I_{STDBYA}	AVDD supply current in standby	V_{AVDD} = 3.3V	-	2	-	µA
DR	Dynamic range	1 kHz, A-weigthed V_{AVDD} = 3.3 V	-	90	-	dB
SNR_{ADC}	Signal to noise ratio	1 kHz, A-weighted V_{AVDD} = 3.3 V	-	92	-	dB
THD_{ADC}	Total harmonic distortion	1 kHz, -1dB V_{AVDD} = 3.3 V	-	85	-	dB
CT	Channel cross talk	V_{AVDD} = 3.3 V	-	80	-	dB
-	Group delay	Fs mode (f_S = 32 kHz)	-	0.4	-	ms
		Fs_by_2 mode (f_S = 16 kHz)	-	0.7	-	
		Fs_by_4 mode (f_S = 8 kHz)	-	1.4	-	
-	Pass band	-	-	0.4535	-	Fs
-	Pass band ripple	Fs mode (f_S = 44.1 kHz)	-	0.08	-	dB
		Fs_by_2 mode (f_S = 22.05 kHz)	-	0.08	-	
		Fs_by_4 mode (f_S = 11.025 kHz)	-	0.08	-	
-	Stop band attenuation	Fs mode (f_S = 44.1 kHz)	-	45	-	dB
		Fs_by_2 mode (f_S = 22.05 kHz)	-	45	-	
		Fs_by_4 mode (f_S = 11.025 kHz)	-	45	-	
-	Frequency response	-3 dB	-	7	-	Hz
		-0.08 dB	-	50	-	Hz
-	Linear phase deviation	at 20 Hz	-	19.35	-	deg
-	Pass-band ripple	-	-	0.08	-	dB
Headphone detector threshold limits						
E_HP1	HP low threshold	-	-	2.34	-	V
	HP high threshold	-	-	2.52	-	
E_HP2	HP low threshold	-	-	0.7	-	V
	HP high threshold	-	-	0.9	-	

Figure 3. Test circuit



3.4 Embedded crystal oscillator

Figure 4. Oscillator configuration



The STA321 has an integrated oscillator between pins XTI and XTO.

The architecture is a single-stage oscillator with an inverter working as an amplifier. The oscillator stage is biased by an internal resistor (of about 500 kΩ), and requires an external PI network consisting of a crystal and two capacitors as shown in *Figure 4* below. An enable feature is provided in bit 7 of register MISC (address 0xC8) to stop the oscillator and thereby to reduce power consumption.

Not all crystals operate satisfactorily with the type of oscillator used in the STA321. To find out if a crystal is suitable for this device the following transconductance formula must be evaluated and compared to the critical transconductance for the embedded oscillator:

$$Gm = Rm * \omega^2 * (C + 2 * Co)^2 < Gm_{CRITICAL} / 3$$

where ω is the crystal operating frequency, C = CA = CB, Co and Rm are shown in *Figure 5* and $Gm_{CRITICAL}$ is given in *Table 7*.

Figure 5. Equivalent circuit of crystal and external components

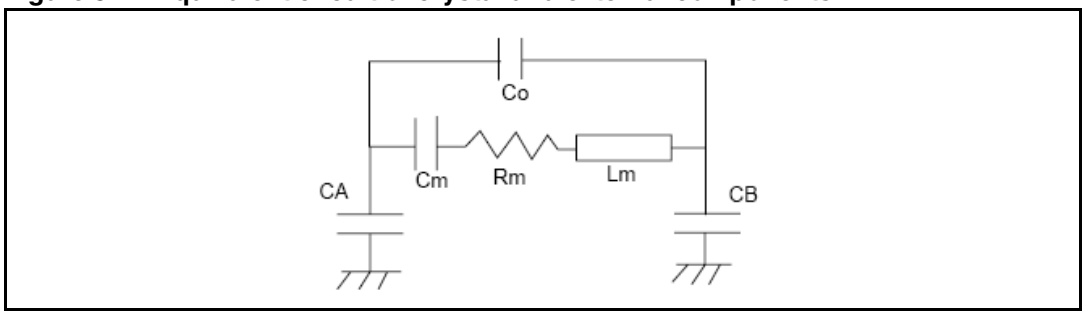


Table 7. Oscillator specifications

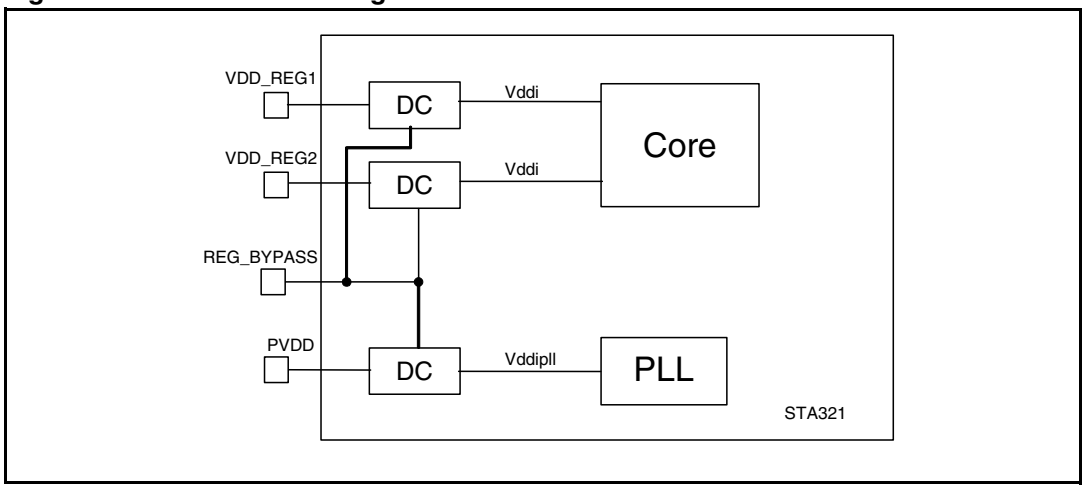
Symbol	Parameter	Min	Typ	Max	Unit
I_{OSC}	Oscillator power consumption with crystal connected (1)	-	-	215	µA
$Duty_{OSC}$	Duty cycle	46.9	47.8%	48.9	%
T_{UP}	Startup time	-	15 * τx	-	s (2)
$Gm_{CRITICAL}$	Oscillator transconductance	1060	-	-	µA/V

1. If no crystal is connected then the power consumption could be much higher.
2. τx is the time constant of the crystal and external components; a typical value is 44 µs.

3.5 Embedded DC regulator

The power supply to the digital STA321 core and PLL is provided via embedded linear DC regulators as shown below in *Figure 6*. When pin REG_BYPASS is tied to ground, the DC regulators are active so that a voltage in the range 2.5 V to 3.6 V applied to pins VDD_REGx or PVDD provides a regulated internal voltage to the core and the PLL. The voltages Vddi and Vddipll range from 1.55 V to 1.95 V depending on operating conditions.

Figure 6. Embedded DC regulator scheme



If the application allows multiple supplies or the power supply requirements are a fundamental constraint, pin REG_BYPASS can be tied high and a 1.8 V external supply can be applied directly to pins VDD_REGx and PVDD. In this case the operating range for such an external supply is 1.55 V to 1.95 V.

Embedded DC regulators imply also static power consumption that must be take into account when the power-down modes are active. The STA321 provides a deep powerdown mode where also the regulators are active but in a low power consumption mode (see *Section 4.3.2 on page 27*).

4 Power-up and power-down sequences

4.1 Device power-up

After providing the power supply to the device, it is necessary to wait until the DC regulator PWUP time has elapsed before the device can be set up and used for normal operations. (see *Figure 7*).

Figure 7. Startup sequence

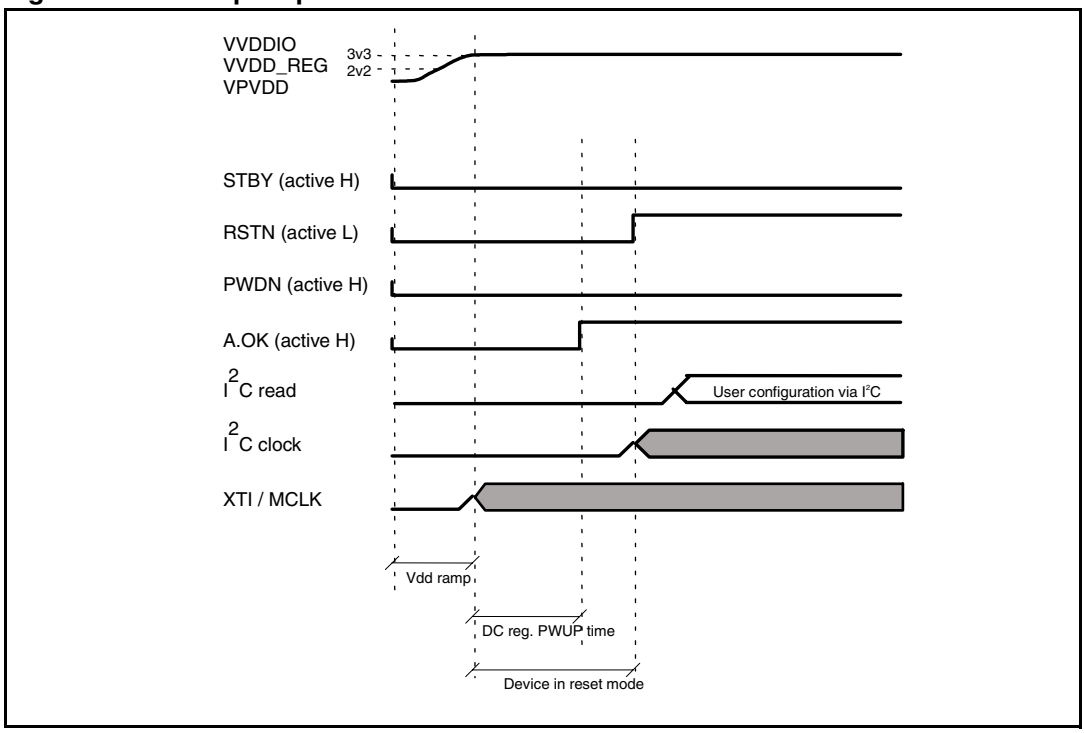


Table 8. Power-up signal description

Signal/pin	Type	Description
VDDIO	Supply	Power supply of the digital pads (= VDDIO1,2)
VDD_REG	Supply	Power supply of the system core (= VDD_REG1,2)
PVDD	Supply	Power supply of the PLL
STBY	In (digital)	External standby signal provided by the user
RSTN	In (digital)	External reset signal provided by the user
PWDN	Internal	Power-down of the DC regulator cell, controlled by the core
A. OK	Internal	DC regulator status, when active the 1.8 V is provided to the core
I^2C read	In (I^2C)	Configuration commands coming to the I^2C interface
I^2C clock	Internal	I^2C peripheral clock
XTI/MCLK	In (digital)	Clock input source

Table 9. Startup timings

Parameter	Description	Min	Typ	Max	Unit
DC reg. power-up time	Start up time of the DC Regulator after connecting the power	-	-	300	µs
Device in reset mode	Must be greater than (VDD time + DC reg. power-up time)	-	-	-	µs

Table 10. Configuration example

Register address	Value	Description
0xC9	0x00	Remove PLL bypass
0xCA	0x00	Headphone detection polarity = 0
0xB8	0x4A	Configure SAI output: SAI_out1 = SAI_in1, SAI_out2 = SAI_in2
0xB7	0x38	SRC source select: SRC1 = ADC, SRC2 = ADC
0xC6	0x02	ADC clock on
0xB2	0xF3	I^2S configuration
0xC8	0x21	Core clock on, SAI/ADC audio set to 32 kHz - 48 kHz range
0xB2	0xD3	SAI_out: output enabled
0xA0	0x00	Soft volume removed
0x00	0x00	Remove bridge 3-state

4.2 Software power-down mode

The software power-down is obtained by configuring the appropriate I^2C registers.

In order to obtain flexibility every peripheral has its independent, standby signal and several gating clock cells are available.

Obviously, the I^2C peripheral can not be turned off in this mode, otherwise the device can recover from the power-down state only via the reset pin.

In the table below EA is embedded amplifier and CB is CMOS bridge. For complete information this table must be used in conjunction with *Chapter 14: Register description on page 77*.

Table 11. Registers for power-down

Description	Register bit	Address
Put EA in standby	*FFXCFG1*[7]	*0x00 on page 81*
Put CB in standby	*FFXCFG1*[6]	*0x00*
Put PLL in standby	*PLLPFE*[5]	*0xC4 on page 132*
Put ADC in standby	*ADCCFG0*[3]	*0xC6 on page 133*
Turn core clock off	*MISC*[0]	*0xC8 on page 135*
Turn ADC clock off	*ADCCFG0*[1]	*0xC6*

Table 11. Registers for power-down (continued)

Description	Register bit	Address
Turn SRC clock off	*CKOCFG*[3]	*0xC7 on page 134*
Turn PROC clock off	*CKOCFG*[2]	*0xC7*
Turn FFX clock off	*CKOCFG*[4]	*0xC7*

4.2.1 Configuration example

This is an example of the register setup for power-down clock. It is assumed that every peripheral is already configured and working correctly.

There are other configuration examples to help you get started please refer to other chapters and also to *Chapter 14: Register description on page 77* in order to get all the necessary and complementary details.

Turn off all the peripherals.

Note: The MCLK (or XTI) must be used as system clock (sys_clk) before setting the PLL to standby.

Table 12. Example configurations for power-down

Register bit	Address	Value	Description
EA_STBY CB_STBY	*0x00 on page 81*	0xC0	Set the embedded power amplifier and CMOS bridge to power-down
CLK_FFX_ON	*0xC7 on page 134*	0x0C	Turn off the FFX modulator clock
ADC_STBY	*0xC6 on page 133*	0x09	Set the ADC into standby mode
CLK_ADC_ON	*0xC6*	0x80	Turn the ADC clock off
CLK_PROC_ON	*0xC7*	0x08	Turn the processing clock off
CLK_SRC_ON	*0xC7*	0x00	Turn the sample rate converter clock to off
PLL_BYP_UNL	*0xC4 on page 132*	0x80	Bypass the PLL clock and use MCLK (or XTI) as source clock when the PLL is not locked (a safety operational mode)
PLL_PWDN	*0xC4*	0xA0	Put the PLL in standby
CLK_CORE_ON	*0xC8 on page 135*	0x00	Turning off the core clock

4.3 Hardware power-down mode

The hardware power-down is obtained by asserting pin STBY to high.

There are two power-down options available, namely mild mode and full (or deep) mode, that could be selected using the DC_STBY_EN signal in register STBY_MODES

Figure 8 summarizes the main power-down sequence. “Power on” is the normal operating status where all the startup procedures have already been executed. The rectangular boxes indicate the steps to be done by the user whilst the rounded boxes indicate the steps done by the device.

Figure 8. Hardware power-done sequence

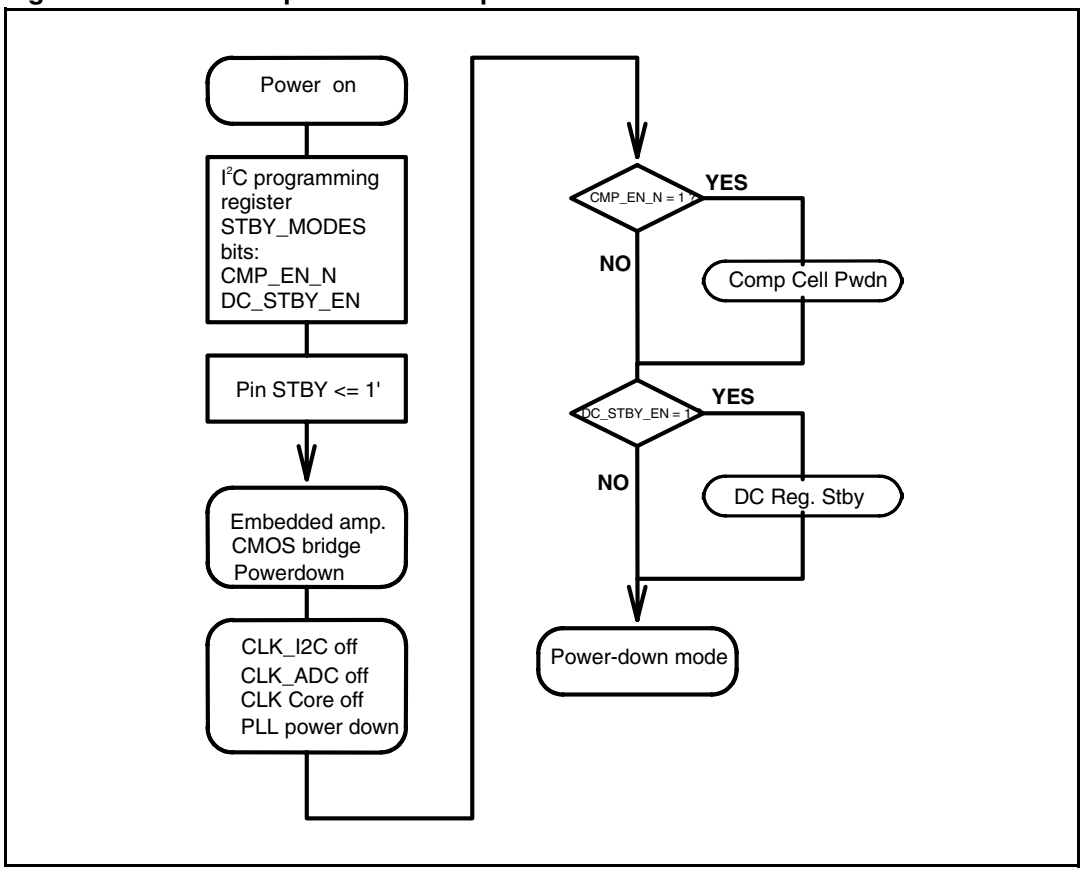


Table 13. Frequently used signals

Name	Description
STBY	Input pin *STBY on page 11*
PWDN DC regulator	Internal
A. OK DC regulator	Internal
CMP_EN_N	Bit 1, register *STBY_MODES on page 139*
EA_STBY CB_STBY	Bits 7:6, register *FFXCFG1 on page 81*
EA/CB volume	Internal
PLL_UNLOCK	Bit 7, register *PLLST on page 132*
PLL_PWDN	Bit 5, register *PLLPFE on page 132*
CLK_PROC_ON	Bit 2, register *CKOCFG on page 134*
CLK_PROC	Processing clock
CLK_FFX_ON	Bit 4, register *CKOCFG on page 134*
clk_ffx	FFX clock
CLK_ADC_ON	Bit 1, register *ADCCFG0 on page 133*
clk_adc	ADC clock
CLK_SRC_ON	Bit 3, register *CKOCFG on page 134*
clk_src	SRC clock
CMP_EN_N	Bit 1, register *STBY_MODES on page 139*
DC_STBY_EN	Bit 0, register *STBY_MODES on page 139*
FFX_ULCK_PLL	Bits 4:3, register *FFXCFG1 on page 81*

4.3.1 Mild power-down

In this case, the device is put into a mild power-down mode.

All the peripherals are set to standby and their clocks turned off.

The I^2C configuration is not required as the default values of the registers are sufficient.

- Initial conditions:

  FFX_ULCK_PLL = 10

  CMP_EN_N = 0

  DC_STBY_EN = 0

- Going into power-down:

  After the assertion of the pin STBY, the following actions are taken by the device:

1. Embedded amplifier (EA) and CMOS bridge (CB) volume are set to mute (the length of this step changes according to the fade-out ramp configuration).
2. EA and CB are put into power-down.

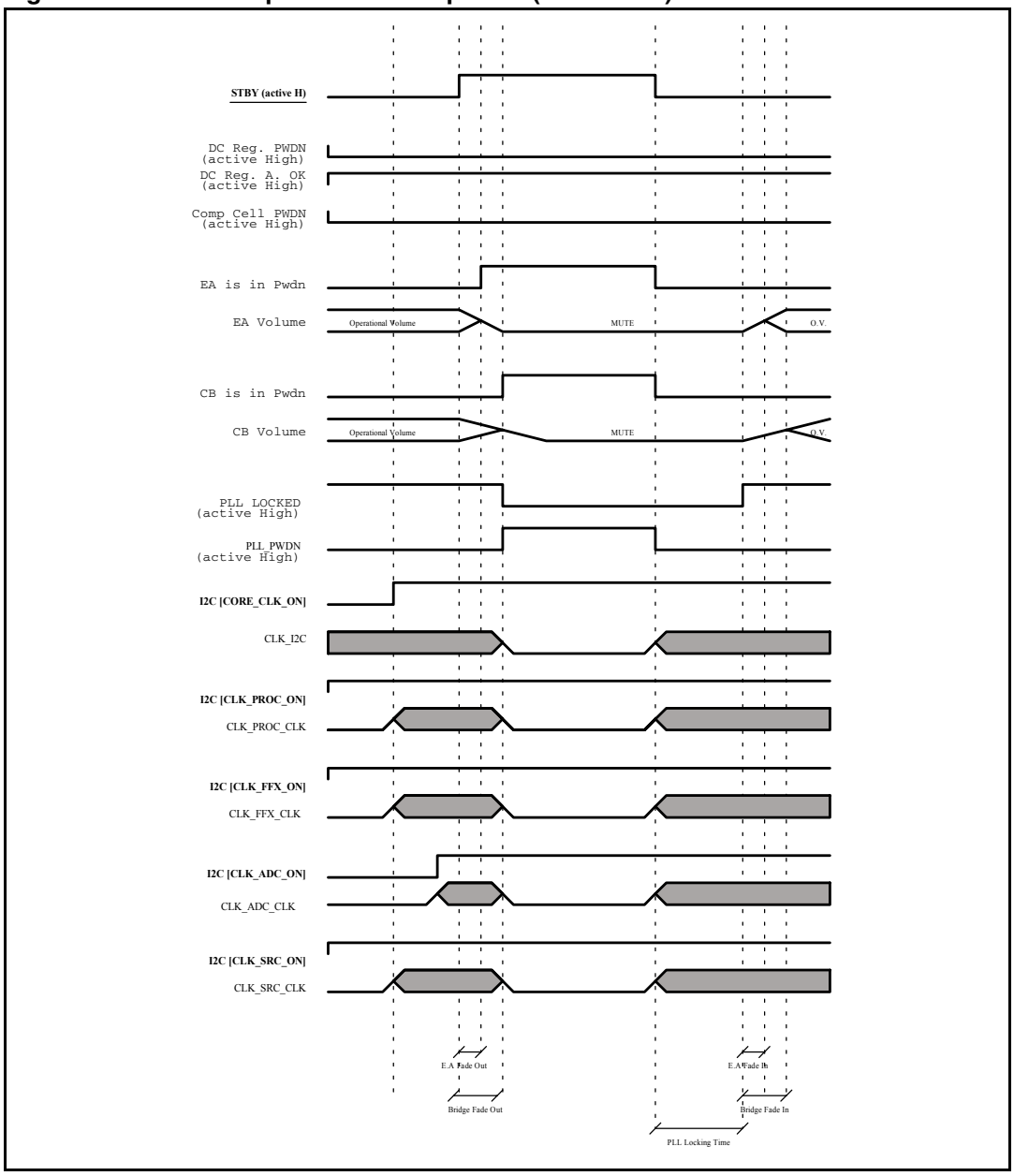
   After the previous operation is completed:
3. All peripherals are turned off (regardless the register settings).
4. The PLL clock is bypassed, the system clock (sys_clk in *Figure 11 on page 29*) is XTI.
5. All clocks are shut down.

- Returning to normal mode:

  After the release of the pin STBY, the power-up procedure takes place:

1. All clocks are turned on.
2. All peripherals are restored to their previous status (based on the last register settings).
3. If the PLL clock was the system clock it will be selected again after the locking time.
4. The EA and the CB execute the fade-in procedure before becoming ready to be used (the length of this step changes according to the fade-in ramp configuration).

Figure 9. Hardware powerdown sequence (mild mode)



4.3.2 Full power-down

In this case the device is put into a full power-down mode.

This implies lower power consumption than the mild mode, but has a drawback in that it takes longer to execute.

- Initial conditions

  FFX_ULCK_PLL = 10

  CMP_EN_N = 1

  DC_STBY_EN = 1

- Going into power-down:

  This mode differs from the previous one by an additional step at the end of the power-down procedure and at the beginning of the power-up:

1. Embedded amplifier (EA) and CMOS bridge (CB) volume are set to mute (the length of this step changes according to the fade-out ramp configuration).
2. EA and CB are put into power-down.

   After the acknowledge signals (EA is in power-down and CB is in power-down) are received:
3. All peripherals are turned off (regardless the register settings).
4. PLL clock is bypassed, the system clock (sys_clk in *Figure 11 on page 29*) is XTI.
5. All clocks are shut down.
6. DC regulator is put into standby mode. After this point the device is in a very low power consumption mode.

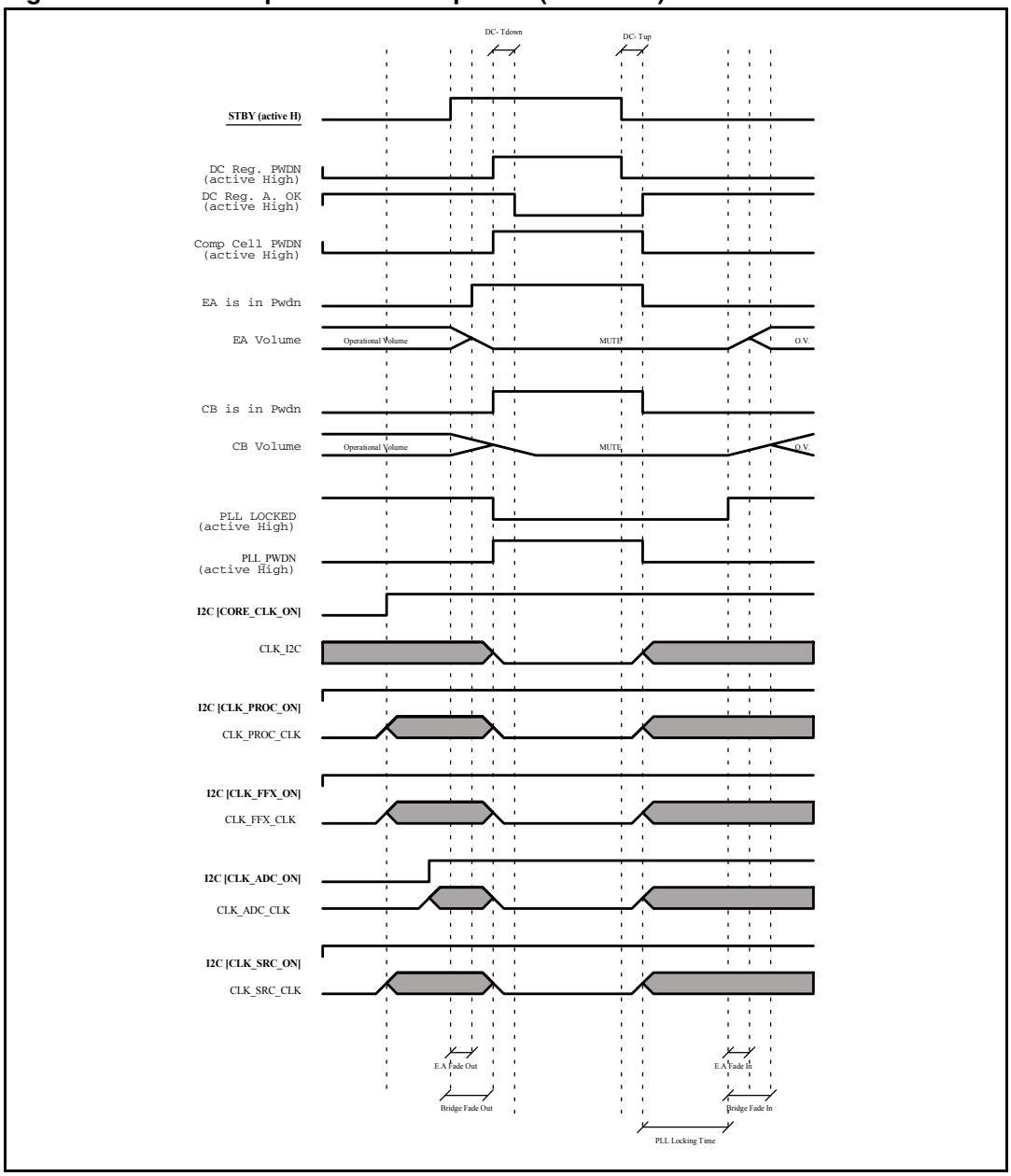
- Returning to normal mode:

  After the release of pin STBY, the power-up procedure will take place:

1. DC regulator is set to operational mode

   After the acknowledge signal (DCAOK) from the DC regulator is received:
2. All clocks are turned on.
3. All peripherals are restored to the status based on their relative register settings.
4. If the PLL clock was the system clock it is selected again after the locking time.
5. The EA and the CB execute the fade-in procedure before being ready to be used (the length of this step changes according to the fade-in ramp configuration).

Figure 10. Hardware power-down sequence (full mode)



5 Clock management

Figure 11. Clock management scheme

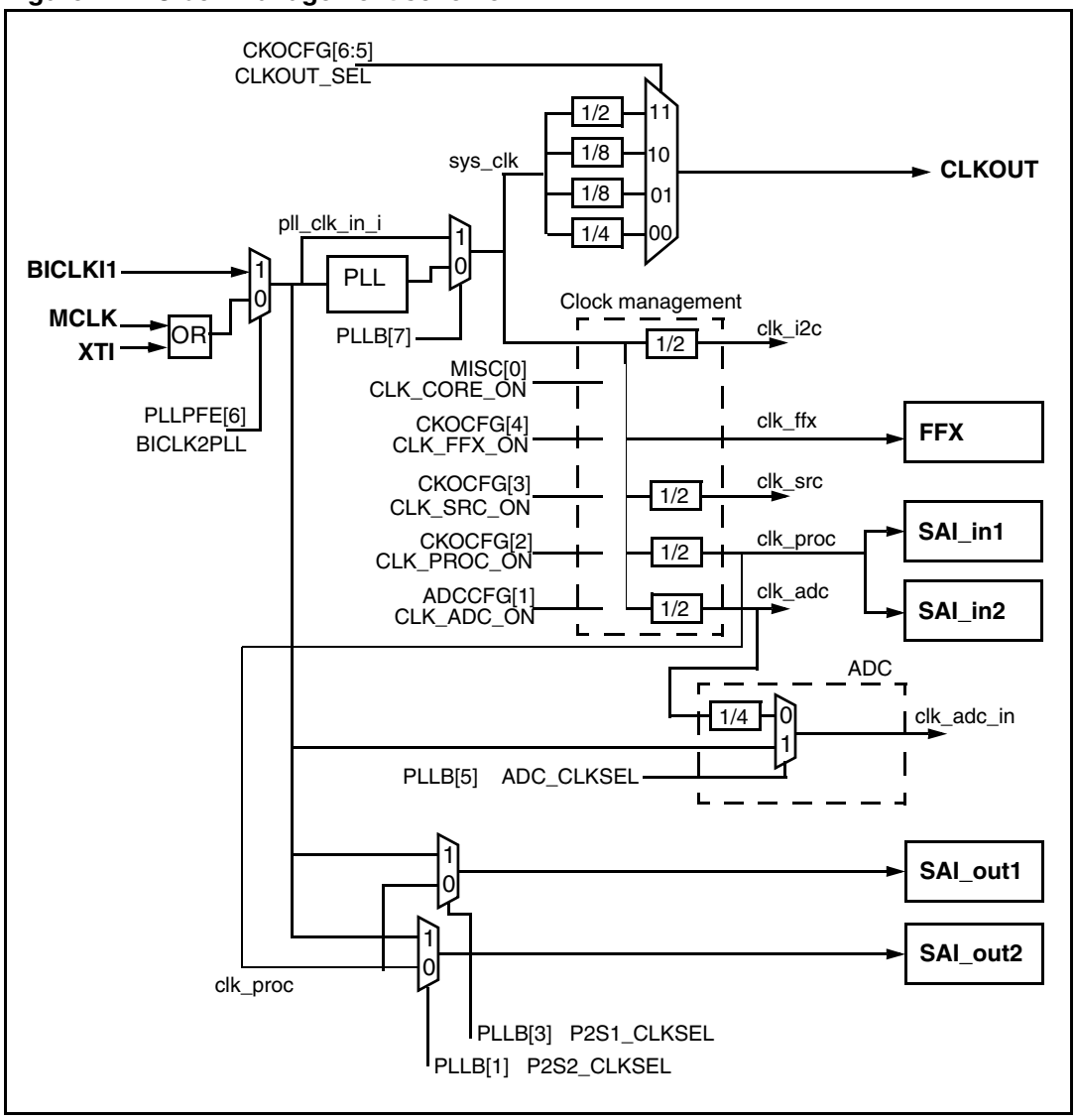


Table 14. Clock control registers

Register Name	Address
PLLB on page 136	0xC9
ADCCFG0 on page 133	0xC6
CKOCFG on page 134	0xC7

Table 15. Clock characteristics

Symbol	Parameter	Min	Typ	Max	Unit
f_{MCLK_Range}	Input clock frequency range	2.048	-	49.152	MHz
$Duty_{MCLK}$	Input clock duty cycle	40	-	60	%
t_{MCLK_RF}	Input clock rise/fall time	-	-	0.2	ns
f_{XTI_Range}	Input clock frequency range	2.048	-	49.152	MHz
$Duty_{XTI}$	Input clock duty cycle	40	-	60	%
t_{XTI_RF}	Input clock rise/fall time	-	-	0.2	ns
f_{BICLK1_Range}	Input clock frequency range	2.048	-	49.152	MHz
$Duty_{BICLK1}$	Input clock duty cycle	40	-	60	%
t_{BICLK1_RF}	Input clock rise/fall time	-	-	0.2	ns
f_{CLKOUT_Range}	Output clock frequency range	-	-	49.152	MHz

5.1 System clock

Figure 11 above shows the STA321 clock management scheme with all the major clocks. As can be seen, the system clock (sys_clk) is selected from one of three sources by using register *PLLB on page 136*:

- an external clock BICLKI1
- (default) an external clock XTI or MCLK (the unused one must, however, be set to 0)
- the internal PLL.

If the PLL is used there are some design constraints:

- pll_clk_in_i must be in the range: 2.048 MHz to 49.152 MHz
- pll_clk_out must be in the range: 65.536 MHz to 98.304 MHz.

The sys_clk is routed to the peripherals through the clock manager section.

5.1.1 Configuration example

This is an example of the PLL register setup. It is assumed that every peripheral is already configured and working correctly.

There are other configuration examples to help you get started please refer to other chapters and also to *Chapter 14: Register description on page 77* in order to get all the necessary and complementary details.

Starting with MCLK as system clock switching to PLL as source

Table 16. Register setup to provide sys_clk from MCLK to PLL

Register	Address	Value	Description
PLLPFE	0xC4	0x80	Safety operational mode: automatic use of MCLK (or XTI) as system clock if the PLL is not locked
PLLB	0xC9	0x00	Remove the PLL bypass and use its clock as system

5.2 Peripheral clock manager

This block manages the clocks of the core processing peripherals ADC, FFX, PROC (including memories and SAI interfaces) and SRC.

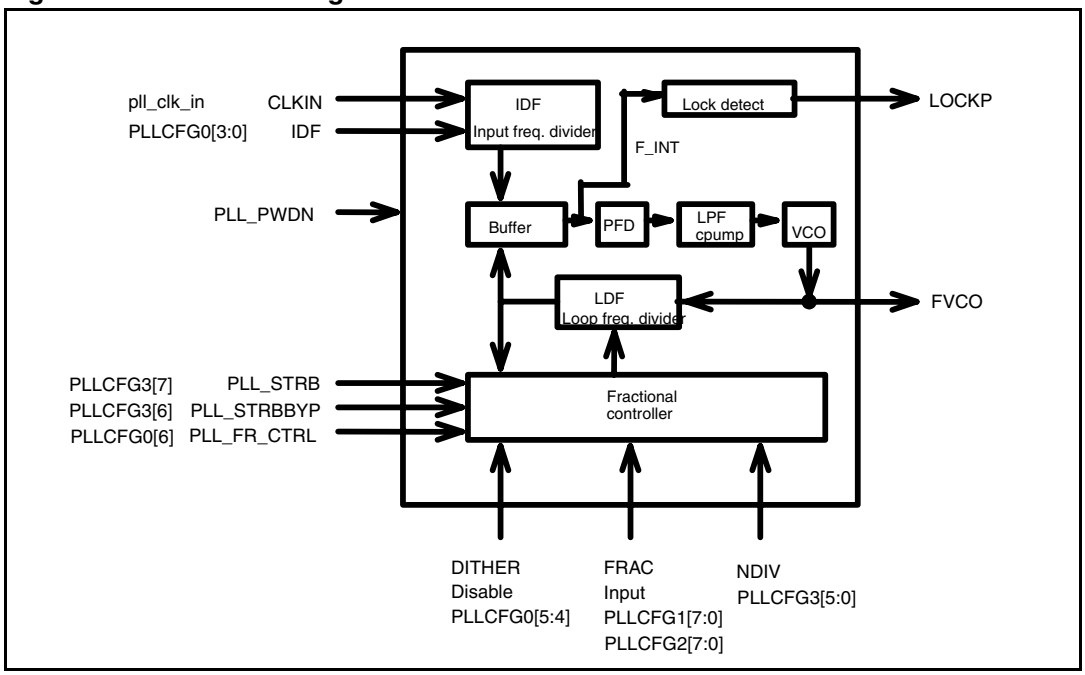
A clock divider (by 2) is attached before every block except the FFX.

Each block is attached to a global gating cell and to a dedicated one. This allows a flexible power-consumption management because it is possible to turn off either the whole processing chain or just a single block. The only exception is the I^2C peripheral clock which is disabled only when the device is in hardware power-down mode. In all the other cases this clock remains active.

5.3 Fractional PLL

The PLL specifications are given in *Table 6 on page 14*.

Figure 12. PLL block diagram



5.3.1 PLL block description

Phase/frequency detector (PFD)

This block compares the phase difference between the corresponding rising edges of the F_INT and the clock coming from the loop frequency divider.

It generates voltage pulses with widths proportional to the input phase error.

Charge pump and loop filter (LPF/CPUMP)

This block converts the voltage pulses from the phase/frequency detector to current pulses which charge the loop filter and generate the control voltage for the voltage controlled oscillator (VCO).

Voltage controlled oscillator (VCO)

This is the oscillator inside the PLL, which produces a frequency, f_{VCO}, on output FVCO proportional to the input control voltage.

Input frequency divider (IDF)

This frequency divider divides the PLL input clock CLKIN by the input division factor (IDF) to generate the PFD input frequency. IDF is programmed in register PLLCFG0[3:0].

Loop frequency divider (LDF)

This frequency divider is present within the PLL for dividing the VCO output by the loop division factor (LDF). LDF is programmed in register bits PLLCFG3[5:0].

Lock circuit

The output of this block, signal LOCKP, is asserted high when the PLL enters the state of coarse lock in which the output frequency is ±10% of the desired frequency. LOCKP is refreshed every 32 cycles of F_INT. The status bit PLL_UNLOCK is in register *PLLST on page 132*.

5.3.2 Output frequency computation

The input clock frequency of the phase/frequency detector (PFD) is

$$f_{F\_INT} = CLKIN / IDF$$

The VCO frequency depends on the value of register bit PLLCFG0.PLL_FR_CTRL such that

When PLL_FR_CTRL = 1

$$f_{VCO} = f_{F\_INT} * (LDF + FRAC / 2^{16} + 1 / 2^{17})$$

and when PLL_FR_CTRL = 0

$$f_{VCO} = f_{F\_INT} * LDF$$

Notes:

1. When dither is disabled (PLL_DDIS = 1), the factor $1 / 2^{17}$ is not used in the multiplication.

2. There are some limits to the input and output frequencies as given in *Table 17* and *Table 18* when selecting the values for IDF, LDF, and FRAC.

3. The LDF values of 5, 6 and 7 cannot be used when fractional synthesis mode is on, that is, when PLL_FR_CTRL = 1.

4. The fractional control bits (FRAC_INPUT) must be set to the required values before activating the fractional synthesis mode.

Table 17. Input division factor (IDF)

IDF[3]	IDF[2]	IDF[1]	IDF[0]	Input division factor (IDF)
0	0	0	0	1
0	0	0	1	1
0	0	1	0	2
…	…	…	…	…

Table 17. Input division factor (IDF) (continued)

IDF[3]	IDF[2]	IDF[1]	IDF[0]	Input division factor (IDF)
1	1	1	0	14
1	1	1	1	15

Table 18. Loop division factor (LDF)

NDIV[5]	NDIV[4]	NDIV[3]	NDIV[2]	NDIV[1]	NDIV[0]	Loop division factor (LDF)
0	0	0	0	x	x	NA
0	0	0	1	0	0	NA
0	0	0	1	0	1	5 (1)
0	0	0	1	1	0	6 (see note 3)
0	0	0	1	1	1	7 (see note 3)
0	0	1	0	0	0	8
…	…	…	…	…	…	…
1	1	0	1	1	0	54
1	1	0	1	1	1	55
1	1	1	x	x	x	NA

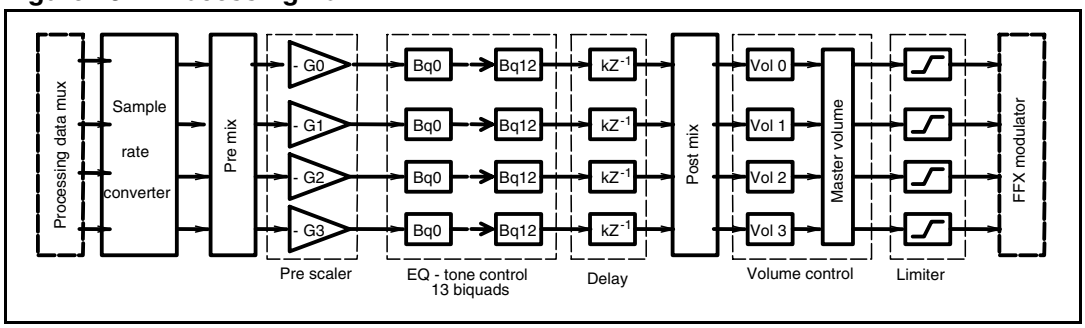
1. The LDF values of 5, 6 and 7 cannot be used when fractional synthesis mode is ON (PLL_FR_CTRL = 1)

6 Digital processing stage

6.1 Signal processing flow

The STA321 provides 4 channels of audio signal processing. The block diagram is shown in the following figure.

Figure 13. Processing flow



Left and right channels coming from the two serial audio interfaces and ADC (left and right channels) are fed into the selection multiplexer (controlled by register *SRCINSEL on page 128*), so that each channel can be connected to any desired processing chain. The four channels are then sample rate converted to the fixed internal sampling rate. Pre mix, EQ/tone processing, programmable delay, post mix, and volume/limiter make up the STA321 signal processing chain.

Figure 14. Processing data multiplexer

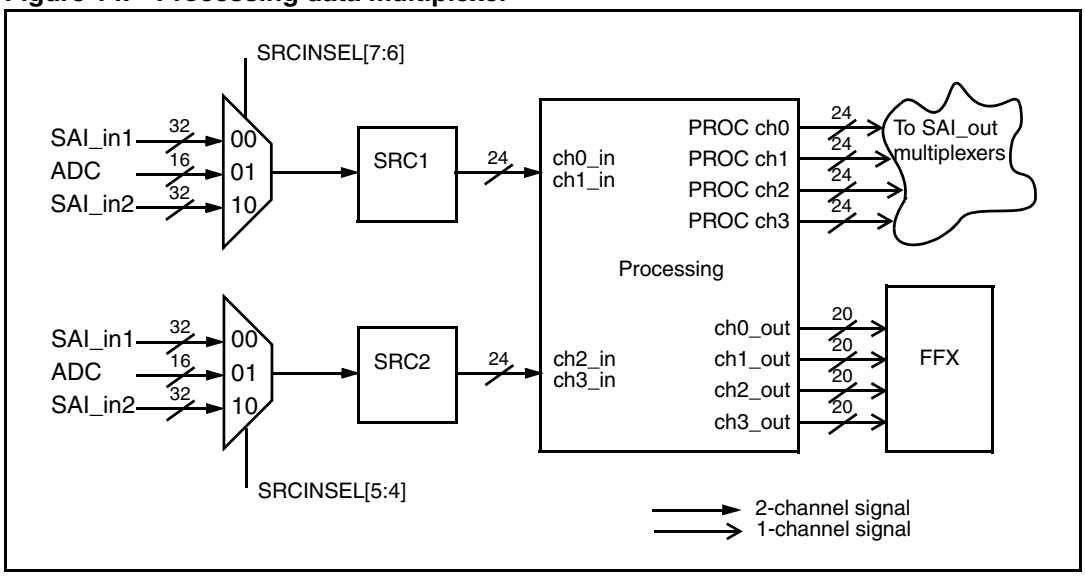
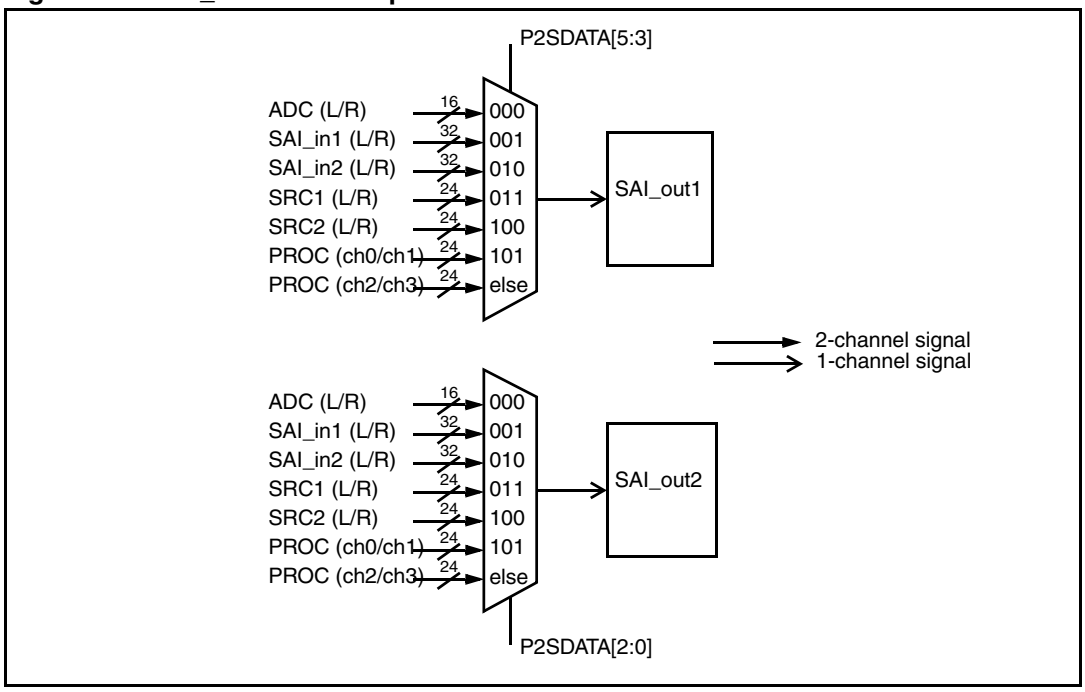


Figure 15. SAI_out data multiplexer



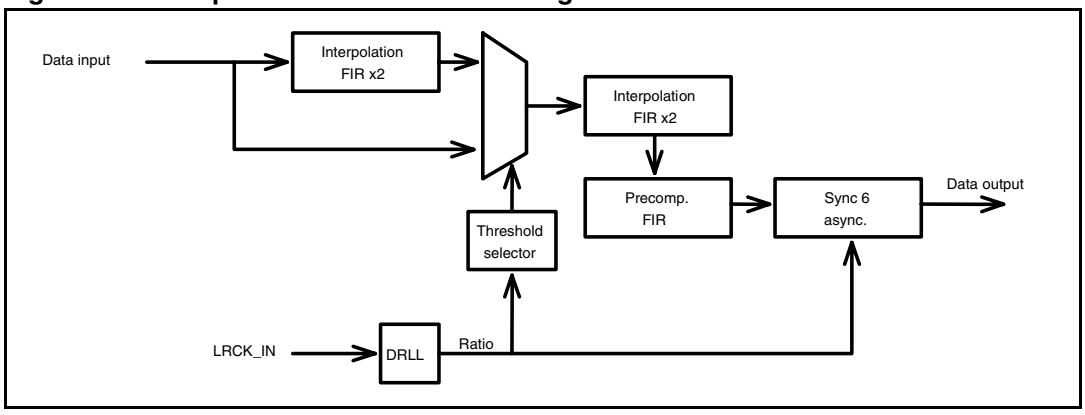
6.2 Sampling rate converter

The sample rate converter (SRC) re samples the input data source in order to send to the processing block an audio stream always with a fixed frequency:

sampling frequency, $f_S = f_{sys\_clk} / 1024$ where f_{sys_clk} is the system clock frequency.

In all the examples given here, f_S = 96 kHz.

Figure 16. Sample rate converter block diagram



The selection between x2 FIR interpolation and direct input data is made automatically by the threshold selector block. If the input sampling frequency (measured by the DRLL) is higher than the SRC threshold (that is, more than 81 kHz) the direct connection is selected (first filter bypassed), otherwise the first x2 filter is added to the data path.

A 3-kHz hysteresis is fixed around the SRC threshold nominal value in order to prevent unstable oscillations.

6.3 Pre-EQ mix 1 and post-EQ mix

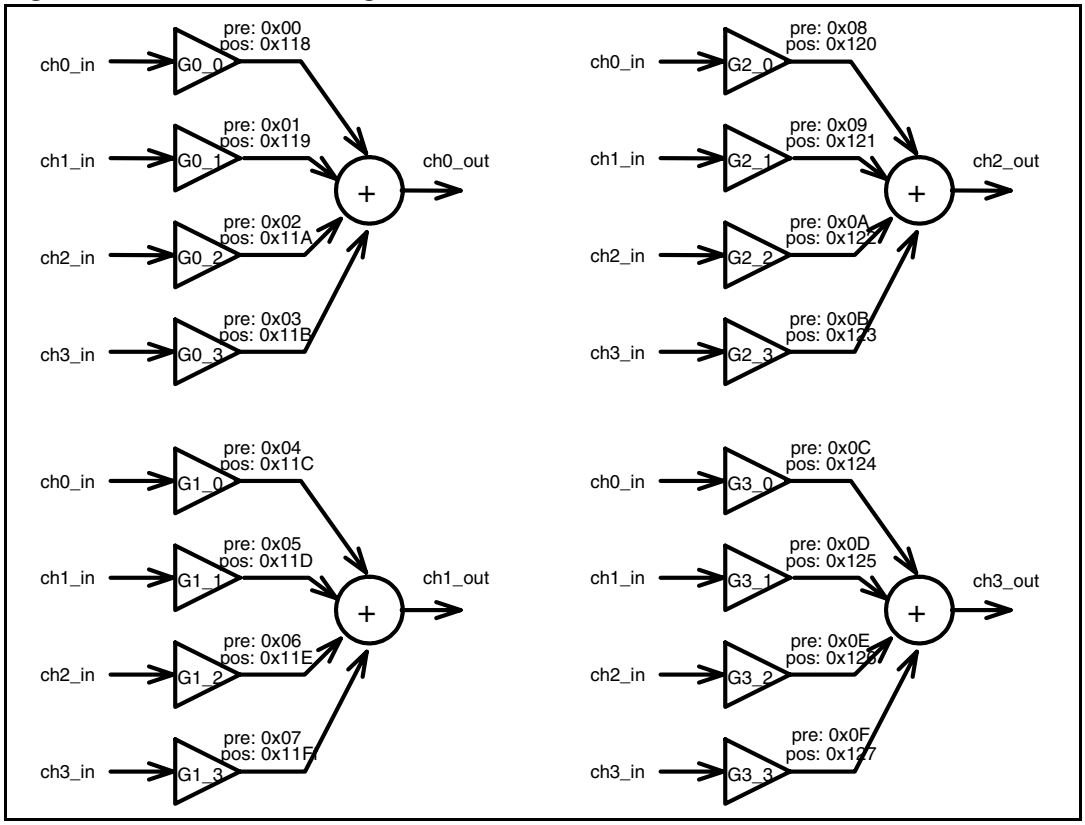
The four-channel data, received from the sample rate converters, is sent to Mix1 block to produce the four mixed-channel data for processing. All this data can be mapped to any internal processing channel through the appropriate configuration of the RAM memory locations.

Table 19. Channel mapping

Function	Channel	Memory location (RAM)
Pre mixer	Ch0	from 0x00
	Ch1	from 0x04
	Ch2	from 0x08
	Ch3	from 0x0c
Post mixer	Ch0	from 0x118
	Ch1	from 0x11c
	Ch2	from 0x120
	Ch3	from 0x124

The post-EQ mixer acts in a similar way for the output channels from the processing and directed to the FFX. It is placed after the delay block which provides a full 4-channel input mix on every channel.

Figure 17. Mixers block diagram



6.3.1 Presets

By default, each mixer output is connected to its corresponding input without any attenuation and without any mixing with the other channels:

ch0_out = ch0_in, ch1_out = ch1_in, ch2_out = ch2_in, ch3_out = ch3_in.

6.4 Pre scaler

The pre scale block, which precedes the first biquad, could be used to attenuate the input signal when the filters of the processing chain have a gain that could reach the clamping value.

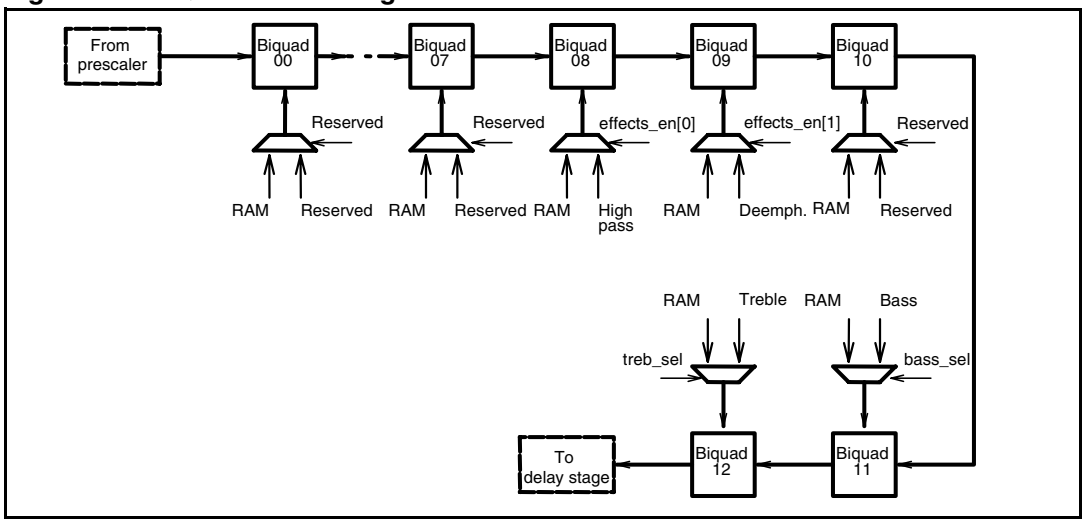
Each channel has a dedicated 24-bit signed multiplier in the range -1 (0x800000) to almost +1 (0x7FFFFF).

6.4.1 Presets

By default, all pre-scale factors are set to 0x7FFFFF

6.5 Equalization, tone control and effects

Figure 18. EQ/tone block diagram



Four channels of input data are fed to the EQ processing block which provides 13 user-programmable biquad filters per channel as shown in *Figure 18* above.

A description of the biquad programming is given in *Section 6.14 on page 44*.

Some filter coefficients are pre-programmed and stored in the non-volatile memory in order to supply particular EQ effects (see *Figure 19* and *Table 20 on page 38*).

The selection of RAM, ROM bass/treble or ROM effects is made using registers EFFS_EN_CHn *on page 109* for the effects and BASS_SELn_R *on page 111* and TREB_SELn_R *on page 113* for the bass/treble. Each biquad can be configured independently.

Figure 19. Biquad coefficient selection

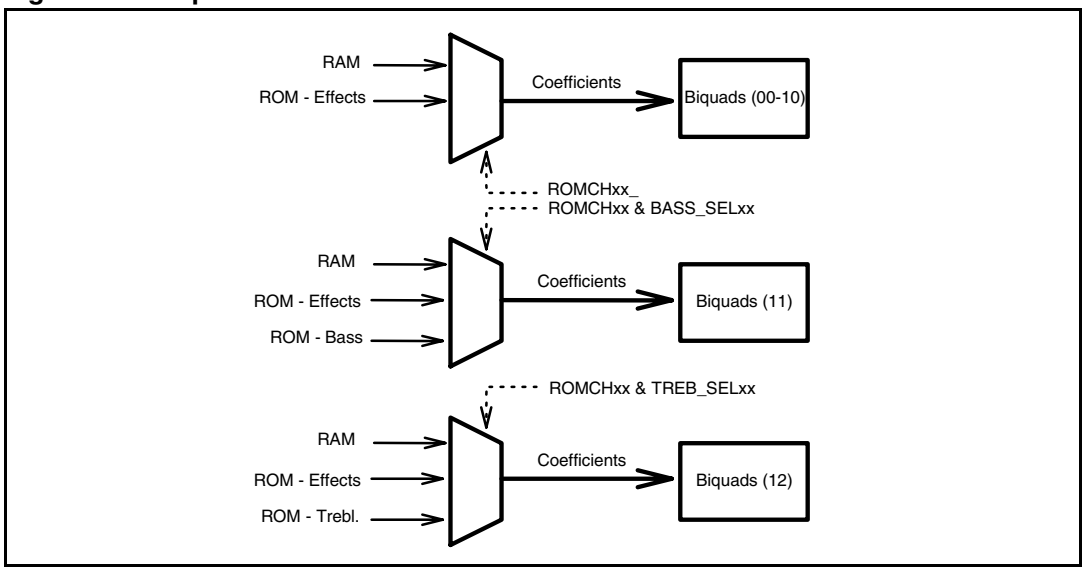


Table 20. EQ control signals

Signal name	Description	Channel	Register addr
effects_en[1]	1: enable deemphasysa filter	Ch0	0x71
		Ch1	0x73
		Ch2	0x73
		Ch3	0x77
bass_sel[5]	1: enable bass tone control	Ch0	0x78
		Ch1	0X79
		Ch2	0X7A
		Ch3	0X7B
treb_sel[5]	1: enable treble tone control	Ch0	0X7C
		Ch1	0X7D
		Ch2	0X7E
		Ch3	0X7F

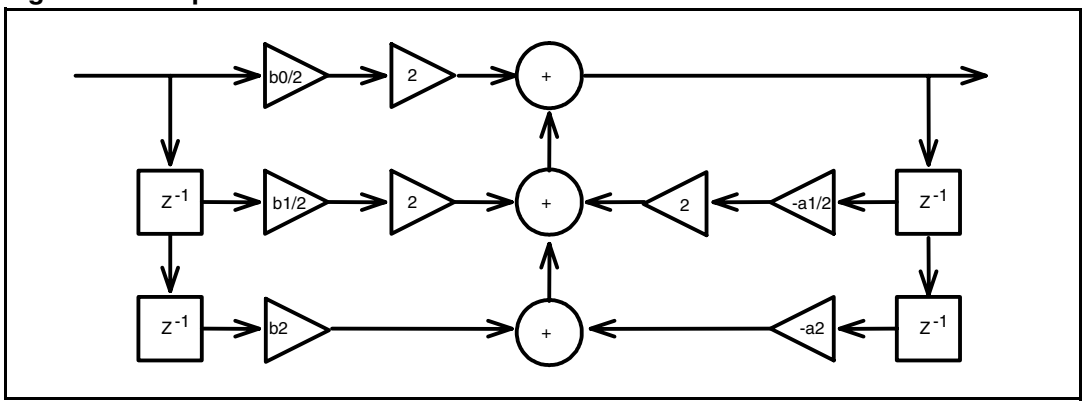
6.6 Biquads

The biquads are based on the following equation and is shown diagramatically in *Figure 20*.

Y[n] = b0 * X[n] + b1 * X[n-1] + b2 * X[n-2] - a1 * Y[n-1] - a2 * Y[n-2]

where Y[n] represents the output and X[n] represents the input. Fractional multipliers are 24-bit signed with coefficient values in the range -1 (0xFFFFFF) to +1 (0x7FFFFF).

Figure 20. Biquad filter



6.6.1 Presets

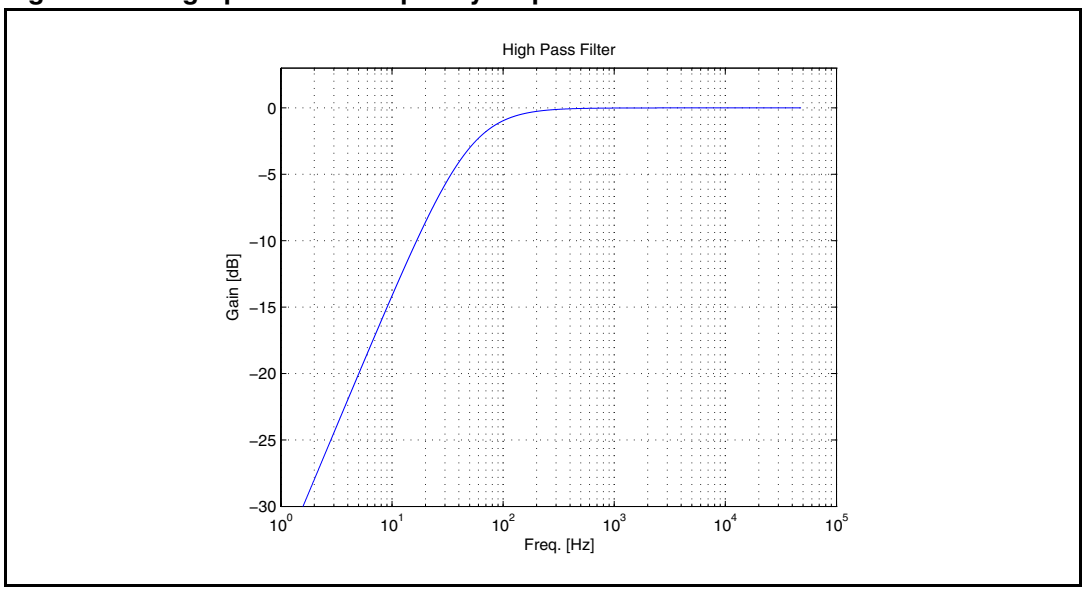
By default all the biquads values in RAM are set to give a bypass function; in actual fact, the signal passes through unchanged. The coefficients for this are:

a1 / 2 = 0, a2 / 2 = 0, b0 / 2 = 0.5 (0x400000), b1 / 2 = 0, b2 / 2 = 0.

6.7 High-pass filter

The standard high-pass filter is provided by the STA321

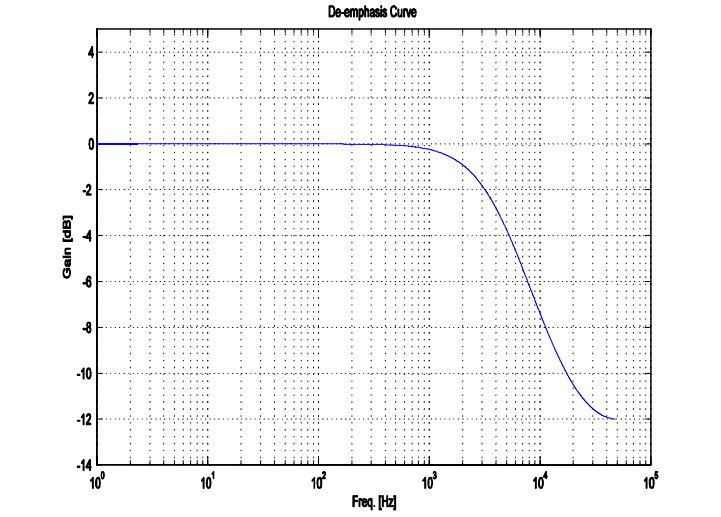
Figure 21. High-pass filter frequency response



6.8 Deemphasis filter

The standard deemphasis filter is provided by the STA321.

Figure 22. Deemphasis filter frequency response



6.9 Bass and treble control

Preset values for the 11th and 12th biquads of every channel are stored in ROM in order to achieve a bass and treble tone control.

They are channel independent and have 24 curves ranging from -12 to +12 dB gain with 1 dB steps. Their selection (and enable) is via registers BASS_SELx_R and TREB_SELx_R where x is the number of the channel to be equalized.

The EQ curve and filter cut-off frequencies are shown in *Figure 23* and *Figure 24*.

With a sampling frequency of 96 kHz (inside the processing block), the cut-off frequencies are 3 kHz for treble curves and 150 Hz for bass curves.

Figure 23. Frequency responses of treble control at 1-dB gain steps

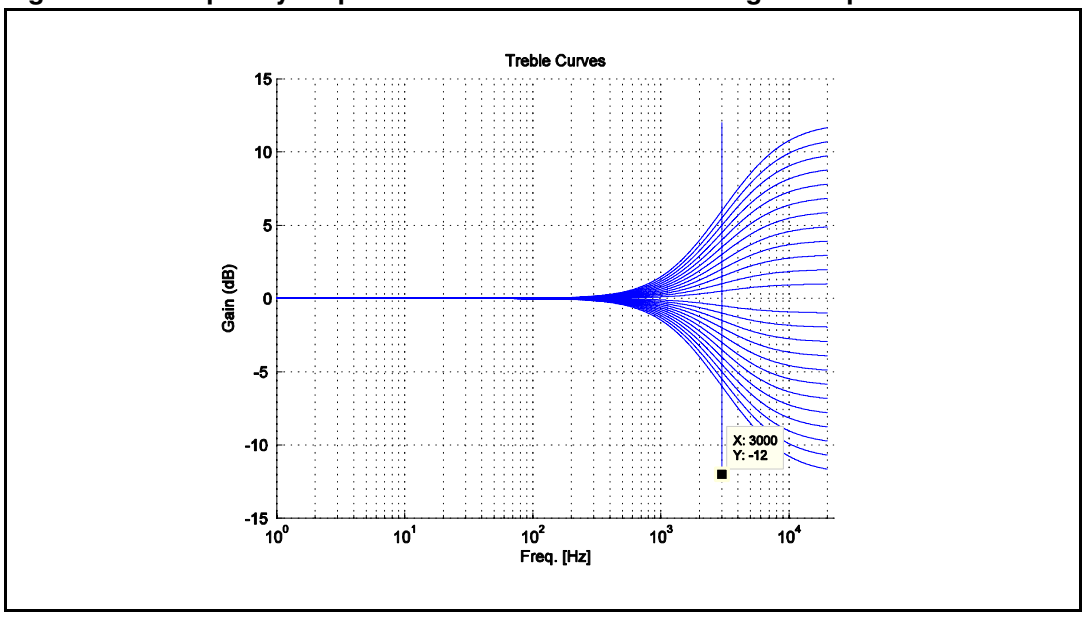
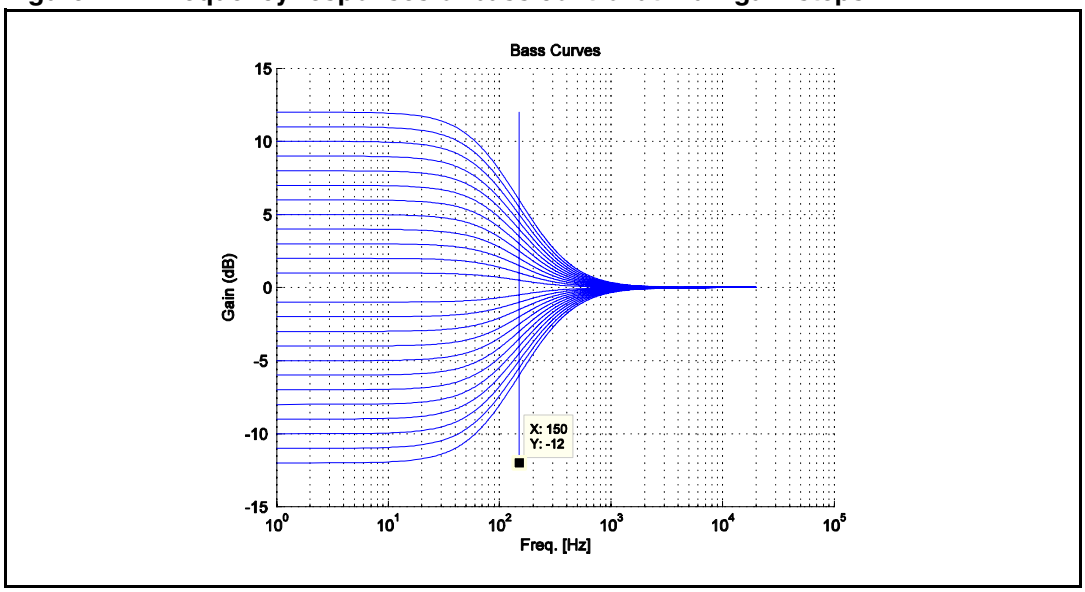


Figure 24. Frequency responses of bass control at 1-dB gain steps



6.9.1 Configuration example

This is an example of the tone control register setup. It is assumed that every peripheral is already configured and working correctly.

Table 21 gives the register values to obtain +12 dB of bass on all channels and -10 dB of treble on channels 0 and 1.

Table 21. Selecting EQ curves

Register - Address	Programmed value	Description
BASS_SEL0_R	0x38	CH0 +12 dB bass
BASS_SEL1_R	0x38	CH1 +12 dB bass
BASS_SEL2_R	0x38	CH2 +12 dB bass
BASS_SEL3_R	0x38	CH3 +12 dB bass
TREB_SEL0_R	0x22	CH0 -10 dB treble
TREB_SEL1_R	0xx22	CH1 - 10 dB treble

6.10 Programmable delay

Every channel, just after the biquads stage, is connected to a dedicated delay block.

The length of the delay is stored in RAM at location 0x128 and can vary from 0 to 35 samples. The corresponding time delay depends on the processing sampling frequency.

6.10.1 Presets

The delay of every channel is set to 0.

6.11 Volume and mute control

The STA321 provides a flexible volume and mute control stage. Using the registers *VOLCH0* to *VOLCH3 on page 122* it is possible to set the volume for each channel individually from +36 dB to -105 dB with 0.5-dB steps.

There is a master volume control, register *MVOL on page 120*, as well. The master volume adds an offset to all the individual volume settings.

The mute function offers the possibility to turn off the sound by reducing the volume setting to -127.5 dB. It could be activated in two ways:

- register *FFXCFG0 on page 82* provides a dedicated mute control for each channel.
- pin MUTE, driven by an external signal, puts all four channels into mute mode.

Register *VOLCFG on page 120* provides some flexibility to set how the mute and volume change procedures are applied. If bit SVOL_ONx is activated the volume of channel x is changed gradually (soft volume or soft mute); using a ramp it starts from the current value and goes down to the target value or to -127.5 dB for mute. The slope of the ramp is set with with the value TIM_SVOL which represents how many samples are needed to achieve a 0.5-dB step.

$$t_{STEP} = 2^{TIM\_SVOL} / f_S$$

The ramp procedure ends when the target volume or mute level is reached. The time for the volume change is calculated as:

$$t_{CHANGE} = (volume_{CURRENT} - volume_{TARGET}) / 0.5 * t_{STEP}$$

If SVOL_ONx is not used, the volume and mute are set instantaneously.

The STA321 also has the possibility to put the FFX into mute in the event of bad input data using register FFXCFG0. If bit BAD_CKS_M is set to 1 the FFX is muted when BICLK and LRCLK do not meet the specifications. If MIS_BICK_M is set to 1 the FFX is muted when BICLK is missing. The mute can be applied gradually or abruptly via bit BAD_IN_M.

6.12 Limiter (clamping)

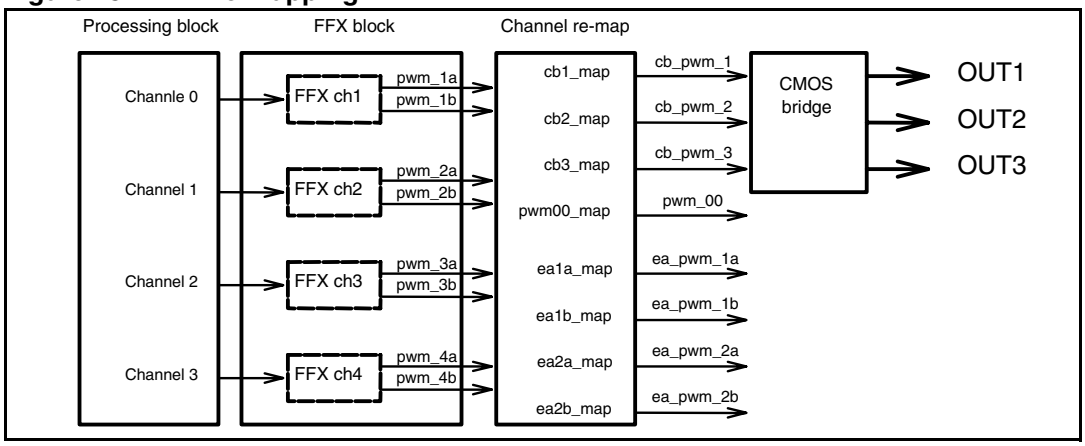
The saturation stage provides an individual or a global limitation on the output signal amplitude such that if the signal is above the limiting value then it is truncated (clamped).

A 23-bit saturation value made up using registers SATCHxCFG1, SATCHxCFG2 and SATCHxCFG3 can be set for each channel x.

However, if bit 7 of register *SATCH0CFG1 on page 116* is set to 1, all the channels take the saturation value of channel 0 and ignore the individual settings.

6.13 FFX channel re-mapping

Figure 25. FFX re-mapping



The channels are re-mapped through registers *PWMMAP1*, *PWMMAP2* and *PWMMAP3 on page 86*. The default configuration routes the channels directly to their respective CB/EA signals:

pwm_1a -> cb_pwm_1
pwm_1b -> cb_pwm_2
pwm_2a -> cb_pwm_3
pwm_2b -> pwm_00 (PWM00)
pwm_3a -> ea_pwm_1 (EAPWM1)
pwm_3b -> ea_pwm_2 (EAPWM2)
pwm_4a -> ea_pwm_3 (EAPWM3)
pwm_4b -> ea_pwm_4 (EAPWM4)

6.14 Memory programming

Table 22 on page 47 shows the RAM mapping for the programmable functions in the signal processing stage. Changing or reading this data is done through the I^2C interface in either single-word mode or in multi-word mode. Register *PROCCTRL on page 107* sets the desired mode and whether to read or write:

- 1-word mode:
  this is for write only; the address of the memory location must be specified in registers *START_ADDR2* and *START_ADDR1 on page 108* and the value of the parameter must be written into registers *I2CB0_TOP*, *I2CB0_MID* and *I2CB0_BOT on page 102*.
- 5-word mode:
  in this case it is possible to write/read 5 contiguous locations. Only the address of the first one must be specified in registers START_ADD1-2, all the others are generated automatically. The values of the parameters must be placed in (or taken from) registers *I2CB0_TOP*-BOT, *I2CB1_TOP*-BOT, *I2CB2_TOP*-BOT, *I2CA1_TOP*-BOT, *I2CA2_TOP*-BOT.

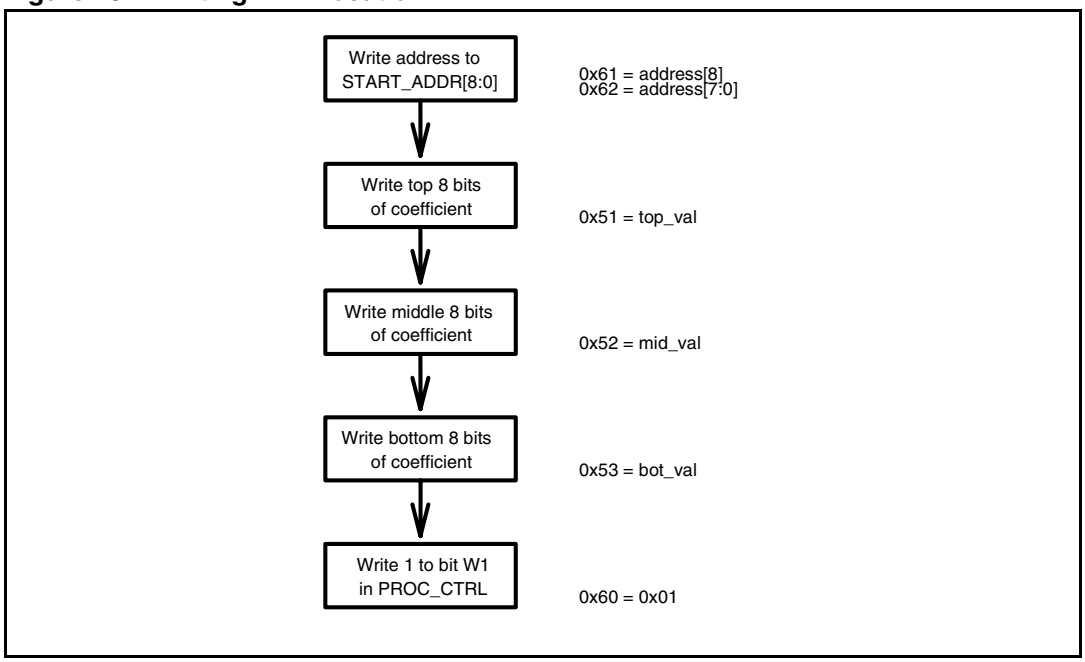
The 5-word mode is particular useful during the biquad programming when a set of five coefficients needs to be updated. Not only is it more efficient to change all of them at the same time but it avoids the generation of possible unpleasant acoustical side-effects.

The following sections explain how to implement this programming using the I^2C interface.

6.14.1 Writing one coefficient/location to RAM

- Write RAM address to registers *START_ADDR2* and *START_ADDR1*
- (b0) Write 8 MSBs of coefficient in register *I2CB0_TOP*
- Write 8 middle bits of coefficient in register *I2CB0_MID*
- Write 8 LSBs of coefficient in register *I2CB0_BOT*
- Write 1 to bit W1 in register *PROCCTRL*.

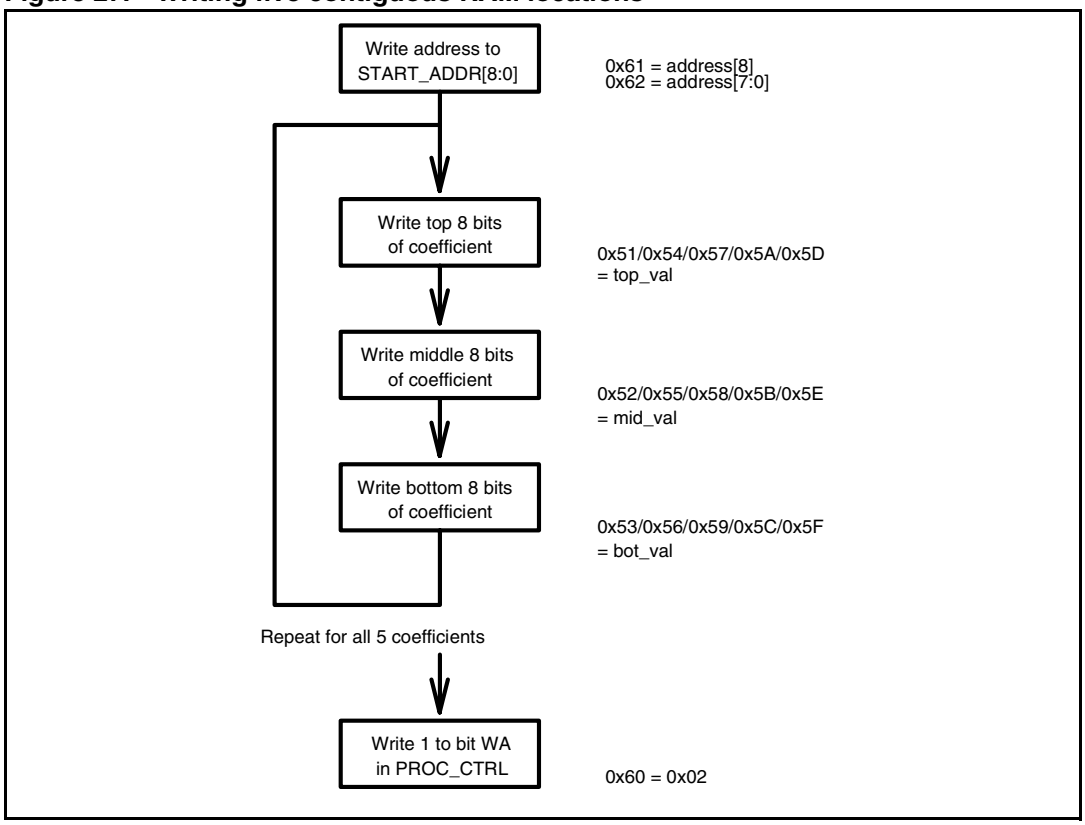
Figure 26. Writing RAM location



6.14.2 Writing a set of five coefficients/locations to RAM

- Write RAM address of b0 to registers *START_ADDR2* and *START_ADDR1*
- (b0) Write 8 MSBs of coefficient in register *I2CB0_TOP*
- Write 8 middle bits of coefficient in register *I2CB0_MID*
- Write 8 LSBs of coefficient in register *I2CB0_BOT*
- (b1) Write 8 MSBs of coefficient in register *I2CB1_TOP*
- Write 8 middle bits of coefficient in register *I2CB1_MID*
- Write 8 LSBs of coefficient in register *I2CB1_BOT*
- (b2) Write 8 MSBs of coefficient in register *I2CB2_TOP*
- Write 8 middle bits of coefficient in register *I2CB2_MID*
- Write 8 LSBs of coefficient in register *I2CB2_BOT*
- (a1) Write 8 MSBs of coefficient in register *I2CA1_TOP*
- Write 8 middle bits of coefficient in register *I2CA1_MID*
- Write 8 LSBs of coefficient in register *I2CA1_BOT*
- (a2) Write 8 MSBs of coefficient in register *I2CA2_TOP*
- Write 8 middle bits of coefficient in register *I2CA2_MID*
- Write 8 LSBs of coefficient in register *I2CA2_BOT*
- Write 1 to bit WA in register *PROCCTRL*.

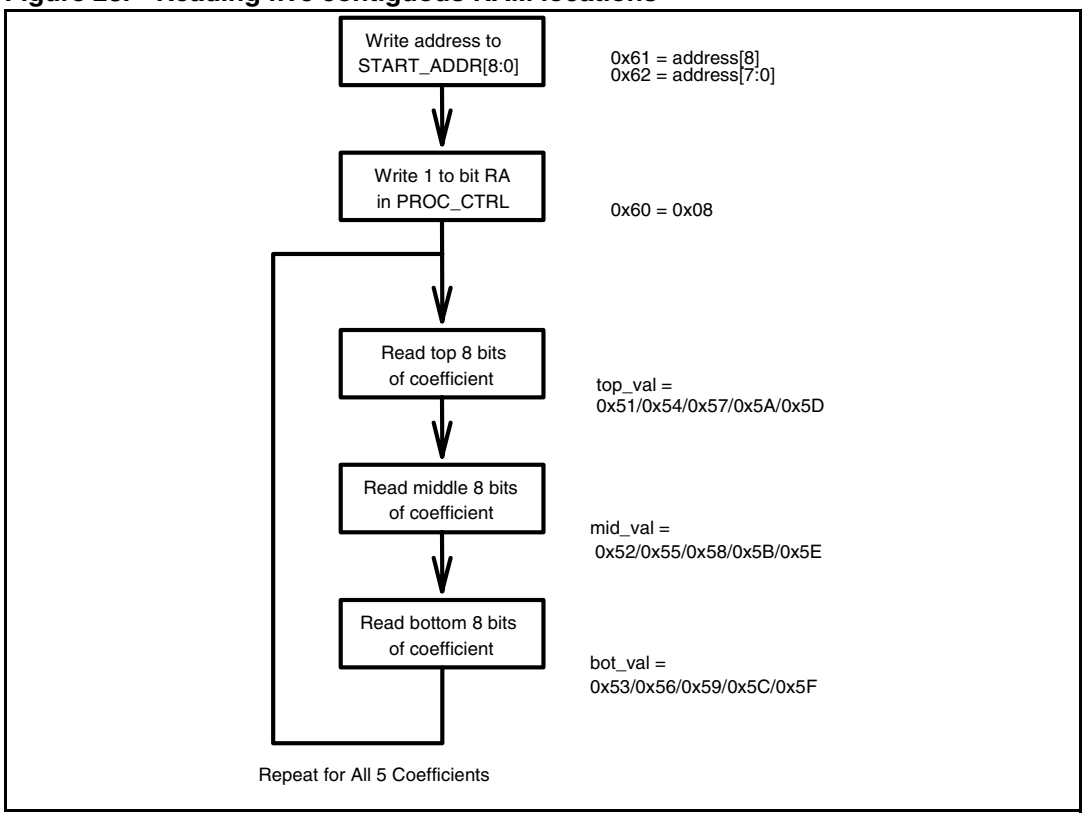
Figure 27. Writing five contiguous RAM locations



6.14.3 Reading a set of five coefficients/locations from RAM

- Write RAM address of b0 to registers *START_ADDR2* and *START_ADDR1*
- Write 1 to bit RA in register *PROCCTRL*
- (b0) Read 8 MSBs of coefficient in register *I2CB0_TOP*
- Read 8 middle bits of coefficient in register *I2CB0_MID*
- Read 8 LSBs of coefficient in register *I2CB0_BOT*
- (b1) Read 8 MSBs of coefficient in register *I2CB1_TOP*
- Read 8 middle bits of coefficient in register *I2CB1_MID*
- Read 8 LSBs of coefficient in register *I2CB1_BOT*
- (b2) Read 8 MSBs of coefficient in register *I2CB2_TOP*
- Read 8 middle bits of coefficient in register *I2CB2_MID*
- Read 8 LSBs of coefficient in register *I2CB2_BOT*
- (a1) Read 8 MSBs of coefficient in register *I2CA1_TOP*
- Read 8 middle bits of coefficient in register *I2CA1_MID*
- Read 8 LSBs of coefficient in register *I2CA1_BOT*
- (a2) Read 8 MSBs of coefficient in register *I2CA2_TOP*
- Read 8 middle bits of coefficient in register *I2CA2_MID*
- Read 8 LSBs of coefficient in register *I2CA2_BOT*

Figure 28. Reading five contiguous RAM locations



6.14.4 RAM mapping

Table 22. RAM mapping for processing stage

Addr	Descr.	Default	Block		Addr	Descr.	Default	Block
0x000	ch0i	0x7FFFFF	Pre mix: ch0		0x021	#2 a2	0x000000	(Ch0-biquad)
0x001	ch1i	0x000000			0x022	#2 a1	0x000000	
0x002	ch2i	0x000000			0x023	#3 b0	0x400000	
0x003	ch3i	0x000000			0x024	#3 b1	0x000000	
0x004	ch0i	0x000000	Pre mix: ch1		0x025	#3 b2	0x000000	
0x005	ch1i	0x7FFFFF			0x026	#3 a2	0x000000	
0x006	ch2i	0x000000			0x027	#3 a1	0x000000	
0x007	ch3i	0x000000			0x028	#3 b0	0x400000	
0x008	ch0i	0x000000	Pre mix: ch2		0x029	#4 b1	0x000000	
0x009	ch1i	0x000000			0x02A	#4 b2	0x000000	
0x00A	ch2i	0x7FFFFF			0x02B	#4 a2	0x000000	
0x00B	ch3i	0x000000			0x02C	#4 a1	0x000000	
0x00C	ch0i	0x000000	Pre mix: ch3		0x02D	#5 b0	0x400000	
0x00D	ch1i	0x000000			0x02E	#5 b1	0x000000	
0x00E	ch2i	0x000000			0x02F	#5 b2	0x000000	
0x00F	ch3i	0x7FFFFF			0x030	#5 a2	0x000000	
0x010	ch0	0x7FFFFF	Pre scaler		0x031	#5 a1	0x000000	
0x011	ch1	0x7FFFFF			0x032	#6 b0	0x400000	
0x012	ch2	0x7FFFFF			0x033	#6 b1	0x000000	
0x013	ch3	0x7FFFFF			0x034	#6 b2	0x000000	
0x014	#0 b0	0x400000	Ch0-biquad		0x035	#6 a2	0x000000	
0x015	#0 b1	0x000000			0x036	#6 a1	0x000000	
0x016	#0 b2	0x000000			0x037	#7 b0	0x400000	
0x017	#0 a2	0x000000			0x038	#7 b1	0x000000	
0x018	#0 a1	0x000000			0x039	#7 b2	0x000000	
0x019	#1 b0	0x400000			0x03A	#7 a2	0x000000	
0x01A	#1 b1	0x000000			0x03B	#7 a1	0x000000	
0x01B	#1 b2	0x000000			0x03C	#8 b0	0x400000	
0x01C	#1 a2	0x000000			0x03D	#8 b1	0x000000	
0x01D	#1 a1	0x000000			0x03E	#8 b2	0x000000	
0x01E	#2 b0	0x400000			0x03F	#8 a2	0x000000	
0x01F	#2 b1	0x000000			0x040	#8 a1	0x000000	
0x020	#2 b2	0x000000			0x041	#9 b0	0x400000	

Table 22. RAM mapping for processing stage (continued)

Addr	Descr.	Default	Block		Addr	Descr.	Default	Block
0x042	#9 b1	0x000000			0x065	#3 b1	0x000000	
0x043	#9 b2	0x000000			0x066	#3 b2	0x000000	
0x044	#9 a2	0x000000			0x067	#3 a2	0x000000	
0x045	#9 a1	0x000000			0x068	#3 a1	0x000000	
0x046	#10 b0	0x400000			0x069	#3 b0	0x400000	
0x047	#10 b1	0x000000			0x06A	#4 b1	0x000000	
0x048	#10 b2	0x000000			0x06B	#4 b2	0x000000	
0x049	#10 a2	0x000000			0x06C	#4 a2	0x000000	
0x04A	#10 a1	0x000000			0x06D	#4 a1	0x000000	
0x04B	#11 b0	0x400000	(Ch0-biquad)		0x06E	#5 b0	0x400000	
0x04C	#11 b1	0x000000			0x06F	#5 b1	0x000000	
0x04D	#11 b2	0x000000			0x070	#5 b2	0x000000	
0x04E	#11 a2	0x000000			0x071	#5 a2	0x000000	
0x04F	#11 a1	0x000000			0x072	#5 a1	0x000000	
0x050	#12 b0	0x400000			0x073	#6 b0	0x400000	
0x051	#12 b1	0x000000			0x074	#6 b1	0x000000	
0x052	#12 b2	0x000000			0x075	#6 b2	0x000000	
0x053	#12 a2	0x000000			0x076	#6 a2	0x000000	(Ch1-biquad)
0x054	#12 a1	0x000000			0x077	#6 a1	0x000000	
0x055	#0 b0	0x400000			0x078	#7 b0	0x400000	
0x056	#0 b1	0x000000			0x079	#7 b1	0x000000	
0x057	#0 b2	0x000000			0x07A	#7 b2	0x000000	
0x058	#0 a2	0x000000			0x07B	#7 a2	0x000000	
0x059	#0 a1	0x000000			0x07C	#7 a1	0x000000	
0x05A	#1 b0	0x400000			0x07D	#8 b0	0x400000	
0x05B	#1 b1	0x000000			0x07E	#8 b1	0x000000	
0x05C	#1 b2	0x000000			0x07F	#8 b2	0x000000	
0x05D	#1 a2	0x000000	Ch1-biquad		0x080	#8 a2	0x000000	
0x05E	#1 a1	0x000000			0x081	#8 a1	0x000000	
0x05F	#2 b0	0x400000			0x082	#9 b0	0x400000	
0x060	#2 b1	0x000000			0x083	#9 b1	0x000000	
0x061	#2 b2	0x000000			0x084	#9 b2	0x000000	
0x062	#2 a2	0x000000			0x085	#9 a2	0x000000	
0x063	#2 a1	0x000000			0x086	#9 a1	0x000000	
0x064	#3 b0	0x400000			0x087	#10 b0	0x400000	

Table 22. RAM mapping for processing stage (continued)

Addr	Descr.	Default	Block		Addr	Descr.	Default	Block
0x088	#10 b1	0x000000	(Ch1-biquad)		0x0AB	#4 b1	0x000000	(Ch2-biquad)
0x089	#10 b2	0x000000			0x0AC	#4 b2	0x000000	
0x08A	#10 a2	0x000000			0x0AD	#4 a2	0x000000	
0x08B	#10 a1	0x000000			0x0AE	#4 a1	0x000000	
0x08C	#11 b0	0x400000			0x0AF	#5 b0	0x400000	
0x08D	#11 b1	0x000000			0x0B0	#5 b1	0x000000	
0x08E	#11 b2	0x000000			0x0B1	#5 b2	0x000000	
0x08F	#11 a2	0x000000			0x0B2	#5 a2	0x000000	
0x090	#11 a1	0x000000			0x0B3	#5 a1	0x000000	
0x091	#12 b0	0x400000			0x0B4	#6 b0	0x400000	
0x092	#12 b1	0x000000			0x0B5	#6 b1	0x000000	
0x093	#12 b2	0x000000			0x0B6	#6 b2	0x000000	
0x094	#12 a2	0x000000			0x0B7	#6 a2	0x000000	
0x095	#12 a1	0x000000			0x0B8	#6 a1	0x000000	
0x096	#0 b0	0x400000	Ch2-biquad		0x0B9	#7 b0	0x400000	
0x097	#0 b1	0x000000			0x0BA	#7 b1	0x000000	
0x098	#0 b2	0x000000			0x0BB	#7 b2	0x000000	
0x099	#0 a2	0x000000			0x0BC	#7 a2	0x000000	
0x09A	#0 a1	0x000000			0x0BD	#7 a1	0x000000	
0x09B	#1 b0	0x400000			0x0BE	#8 b0	0x400000	
0x09C	#1 b1	0x000000			0x0BF	#8 b1	0x000000	
0x09D	#1 b2	0x000000			0x0C0	#8 b2	0x000000	
0x09E	#1 a2	0x000000			0x0C1	#8 a2	0x000000	
0x09F	#1 a1	0x000000			0x0C2	#8 a1	0x000000	
0x0A0	#2 b0	0x400000			0x0C3	#9 b0	0x400000	
0x0A1	#2 b1	0x000000			0x0C4	#9 b1	0x000000	
0x0A2	#2 b2	0x000000			0x0C5	#9 b2	0x000000	
0x0A3	#2 a2	0x000000			0x0C6	#9 a2	0x000000	
0x0A4	#2 a1	0x000000			0x0C7	#9 a1	0x000000	
0x0A5	#3 b0	0x400000			0x0C8	#10 b0	0x400000	
0x0A6	#3 b1	0x000000			0x0C9	#10 b1	0x000000	
0x0A7	#3 b2	0x000000			0x0CA	#10 b2	0x000000	
0x0A8	#3 a2	0x000000			0x0CB	#10 a2	0x000000	
0x0A9	#3 a1	0x000000			0x0CC	#10 a1	0x000000	
0x0AA	#3 b0	0x400000			0x0CD	#11 b0	0x400000	

Table 22. RAM mapping for processing stage (continued)

Addr	Descr.	Default	Block		Addr	Descr.	Default	Block
0x0CE	#11 b1	0x000000			0x0F1	#5 b1	0x000000	
0x0CF	#11 b2	0x000000			0x0F2	#5 b2	0x000000	
0x0D0	#11 a2	0x000000			0x0F3	#5 a2	0x000000	
0x0D1	#11 a1	0x000000			0x0F4	#5 a1	0x000000	
0x0D2	#12 b0	0x400000	(Ch2-biquad)		0x0F5	#6 b0	0x400000	
0x0D3	#12 b1	0x000000			0x0F6	#6 b1	0x000000	
0x0D4	#12 b2	0x000000			0x0F7	#6 b2	0x000000	
0x0D5	#12 a2	0x000000			0x0F8	#6 a2	0x000000	
0x0D6	#12 a1	0x000000			0x0F9	#6 a1	0x000000	
0x0D7	#0 b0	0x400000			0x0FA	#7 b0	0x400000	
0x0D8	#0 b1	0x000000			0x0FB	#7 b1	0x000000	
0x0D9	#0 b2	0x000000			0x0FC	#7 b2	0x000000	
0x0DA	#0 a2	0x000000			0x0FD	#7 a2	0x000000	
0x0DB	#0 a1	0x000000			0x0FE	#7 a1	0x000000	
0x0DC	#1 b0	0x400000			0x0FF	#8 b0	0x400000	
0x0DD	#1 b1	0x000000			0x100	#8 b1	0x000000	
0x0DE	#1 b2	0x000000			0x101	#8 b2	0x000000	
0x0DF	#1 a2	0x000000			0x102	#8 a2	0x000000	(Ch3-biquad)
0x0E0	#1 a1	0x000000			0x103	#8 a1	0x000000	
0x0E1	#2 b0	0x400000			0x104	#9 b0	0x400000	
0x0E2	#2 b1	0x000000			0x105	#9 b1	0x000000	
0x0E3	#2 b2	0x000000			0x106	#9 b2	0x000000	
0x0E4	#2 a2	0x000000	Ch3-biquad		0x107	#9 a2	0x000000	
0x0E5	#2 a1	0x000000			0x108	#9 a1	0x000000	
0x0E6	#3 b0	0x400000			0x109	#10 b0	0x400000	
0x0E7	#3 b1	0x000000			0x10A	#10 b1	0x000000	
0x0E8	#3 b2	0x000000			0x10B	#10 b2	0x000000	
0x0E9	#3 a2	0x000000			0x10C	#10 a2	0x000000	
0x0EA	#3 a1	0x000000			0x10D	#10 a1	0x000000	
0x0EB	#3 b0	0x400000			0x10E	#11 b0	0x400000	
0x0EC	#4 b1	0x000000			0x10F	#11 b1	0x000000	
0x0ED	#4 b2	0x000000			0x110	#11 b2	0x000000	
0x0EE	#4 a2	0x000000			0x111	#11 a2	0x000000	
0x0EF	#4 a1	0x000000			0x112	#11 a1	0x000000	
0x0F0	#5 b0	0x400000			0x113	#12 b0	0x400000	

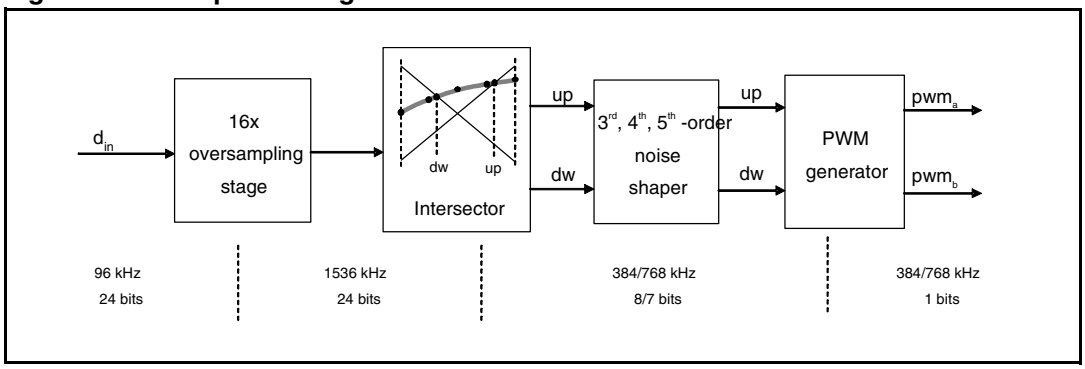
Table 22. RAM mapping for processing stage (continued)

Addr	Descr.	Default	Block		Addr	Descr.	Default	Block
0x114	#12 b1	0x000000	(Ch3-biquad)		0x120	ch0i	0x000000	Post mix: ch2
0x115	#12 b2	0x000000			0x121	ch1i	0x000000	
0x116	#12 a2	0x000000			0x122	ch2i	0x7FFFFF	
0x117	#12 a1	0x000000			0x123	ch3i	0x000000	
0x118	ch0i	0x7FFFFF	Post mix: ch0		0x124	ch0i	0x000000	Post mix: ch3
0x119	ch1i	0x000000			0x125	ch1i	0x000000	
0x11A	ch2i	0x000000			0x126	ch2i	0x000000	
0x11B	ch3i	0x000000			0x127	ch3i	0x7FFFFF	
0x11C	ch0i	0x000000	Post mix: ch1		0x128	delay	0x000000	Delay
0x11D	ch1i	0x7FFFFF			-	-	-	-
0x11E	ch2i	0x000000			-	-	-	-
0x11F	ch3i	0x000000			-	-	-	-

7 FFX

7.1 Functional description

Figure 29. FFX processing schematic



The FFX modulator is a digital low-distortion low-noise PCM-to-PWM converter, based on a pseudo-natural sampling technique, which converts the 4 by 24-bit digital inputs into differential pulse-width modulated outputs at a frequency of either 384 or 768 kHz (selected by register *FFXCFG2*, bit PWM_FREQ) and with a time resolution of 98.304 MHz. This gives a dynamic range that is approaching 100 dB.

The signal is compared with two different carrier signals (rising and falling sawtooth waveforms at the PWM frequency), to get a double edge modulation and to have the possibility to drive a differential (full bridge) power stage.

The order of the noise shaper can be modified by the user, via register bit *FFXCFG2*.NS_ORD, depending on the acceptable amount of noise out of the audio band, that is, noise above 20 kHz. The higher the noise shaper order, the better is the SNR but the higher is the out of band noise.

The PWM generator block converts the amplitude quantization into time quantization to generate a PWM signal.

7.2 Modulation schemes

It is possible to use each of the two intersections with up-carrier and down-carrier to force a rising or a falling edge on each of the two PWM outputs (A and B). This flexibility is achieved through programming registers PWMOnCFG1-2 (where n is the number, 1 to 4, of the output) beginning *on page 91*.

PWM output A can be modulated in one of, or a hybrid of, two basic ways via bits PM_nA:

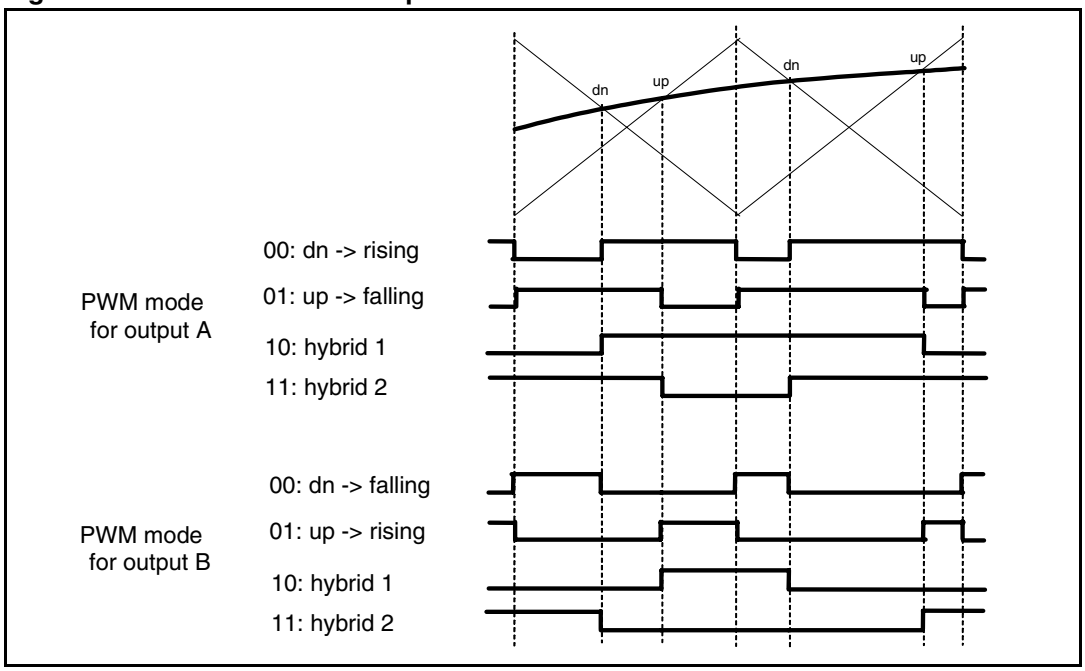
- with the wave starting from level 0 at the beginning of the period, and rising to level 1 when the audio signal intersects the down-carrier
- with the wave starting from level 1 at the beginning of the period, and falling to level 0 when the audio signal intersects the up-carrier;

PWM output B can be similarly modulated via bits PM_nB:

- with the wave starting from level 1 at the beginning of the period, and falling to level 0 when the audio signal intersects the down-carrier;
- with the wave starting from level 0 at the beginning of the period, and rising to level 1 when the audio signal intersects the up-carrier;

The hybrid mode is the toggling between the two methods of modulation for each PWM period.

Figure 30. PWM modes for outputs A and B



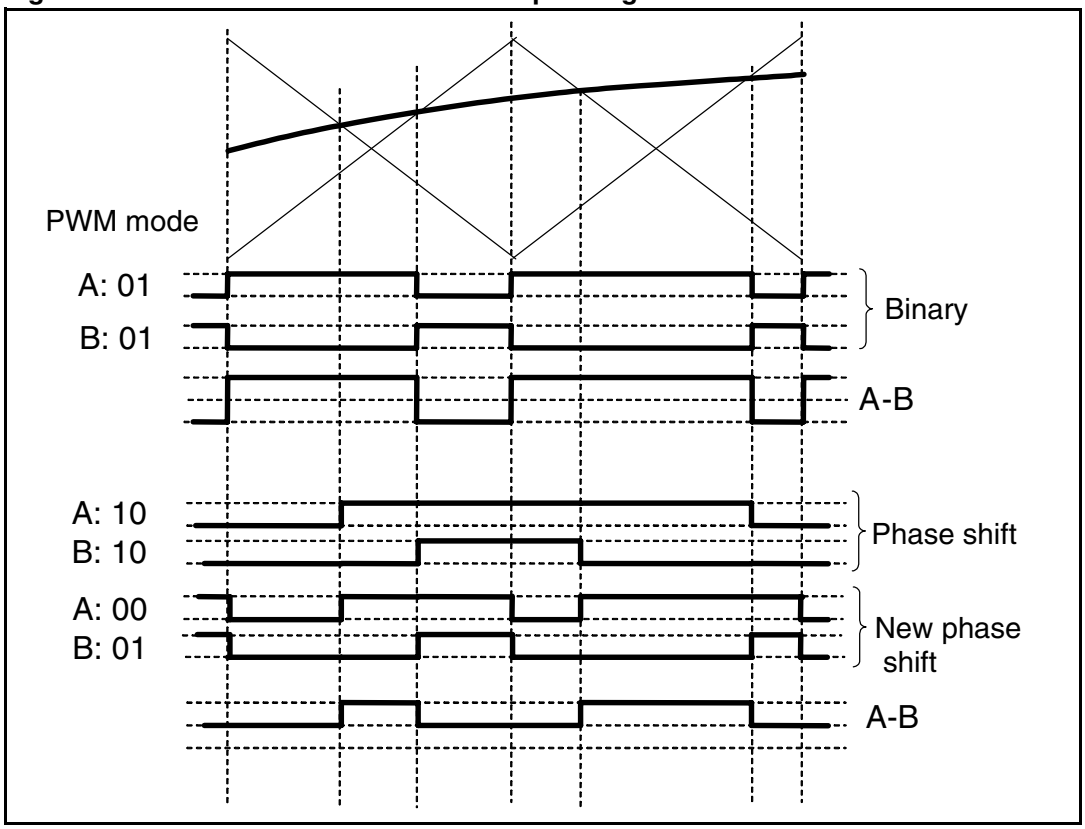
The various single output modulation schemes can be combined together on the two outputs to get the desired differential modulation schemes.

In particular, for the traditional schemes (binary, phase shift), and the new one (new phase shift modulation) the mode bits must be set according to *Table 23* below.

Table 23. Modulation type with register programming

Register bit PWMOnCFG1.PM_nA	Register bit PWMOnCFG2.PM_nB	Resulting modulation
00	00	binary
01	01	
10	10	phase shift
11	11	
00	01	new phase shift
01	00	

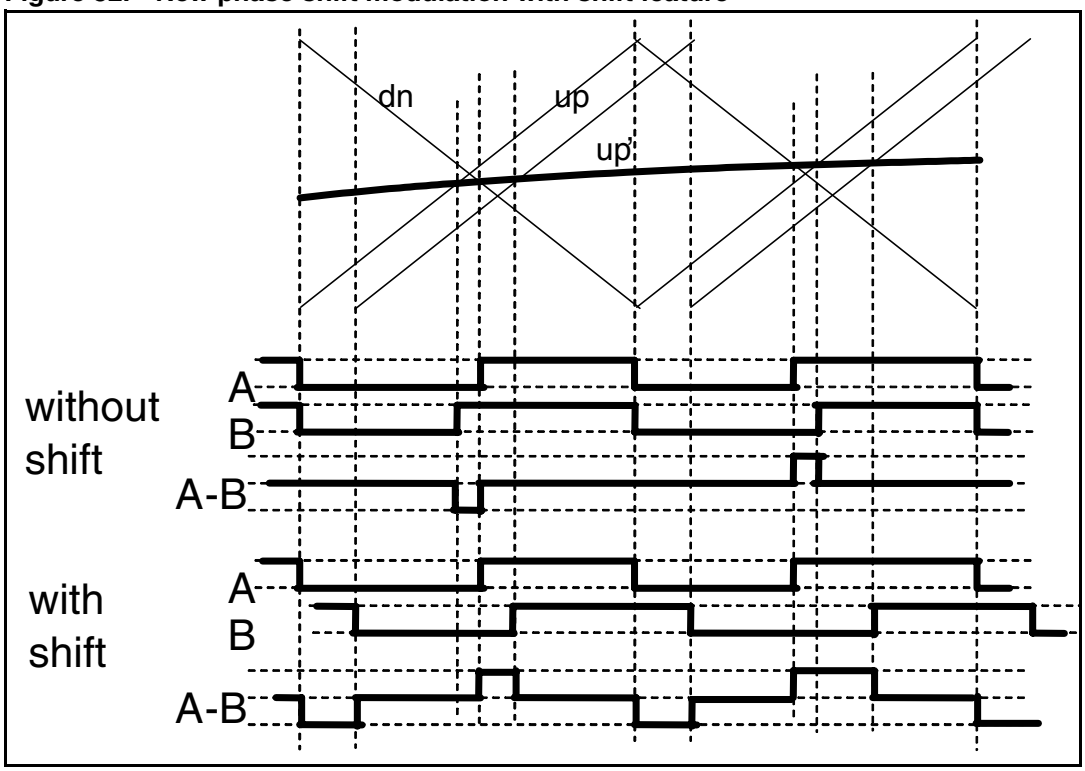
Figure 31. Modulation waveforms corresponding to *Table 23*



7.3 PWM shift feature

In new phase shift modulation it is possible to shift one output with respect to the other one. This can reduce the noise generated by the simultaneous switching of two or more outputs. The shift is performed through by programming bits PS_nA and PS_nB in registers PWMOnCFG1-2 (where n is the number, 1 to 4, of the output) beginning *on page 91*.

Figure 32. New phase shift modulation with shift feature

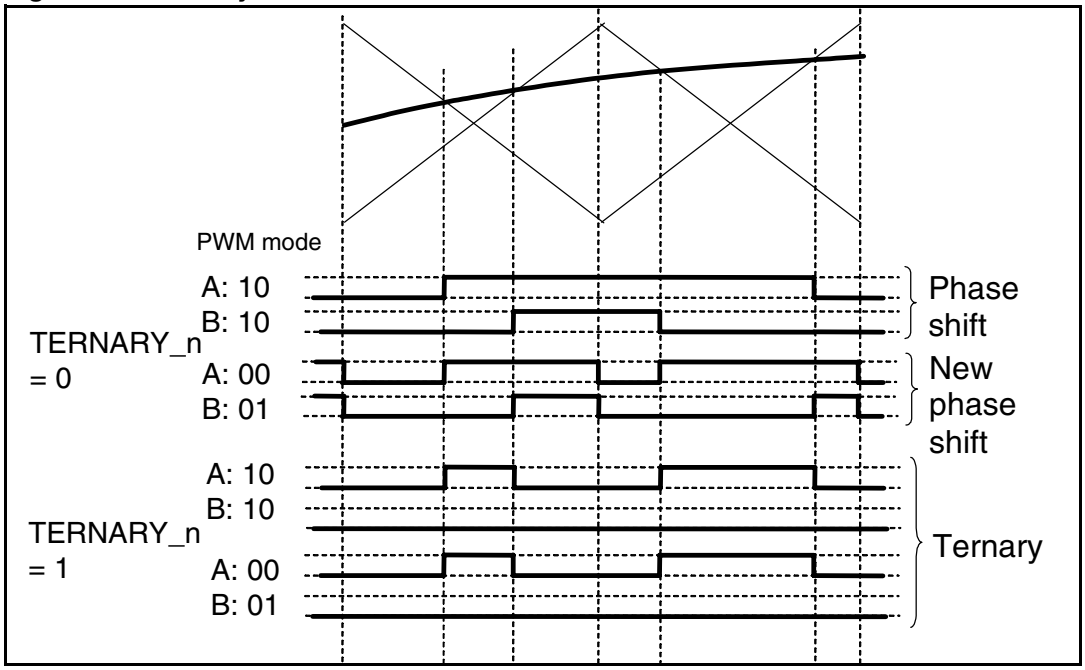


7.4 Ternary mode

The ternary mode feature is also available. It is activated by bits TERNARY_n in registers PWMOnCFG0 beginning *on page 91* (where n is the number, 1 to 4, of the output).

This feature overrides the PWM mode bits settings PM_nA and PM_nB.

Figure 33. Ternary modulation



7.5 Minimum pulse limitation

The FFX modulator has a minimum pulse limitation feature which has a double purpose:

- to limit the maximum/minimum duty cycle when the audio signal is near to full scale;
- to have the commutations on the same channel outputs A and B separated by a minimum pulse distance.

The first feature is always enabled.

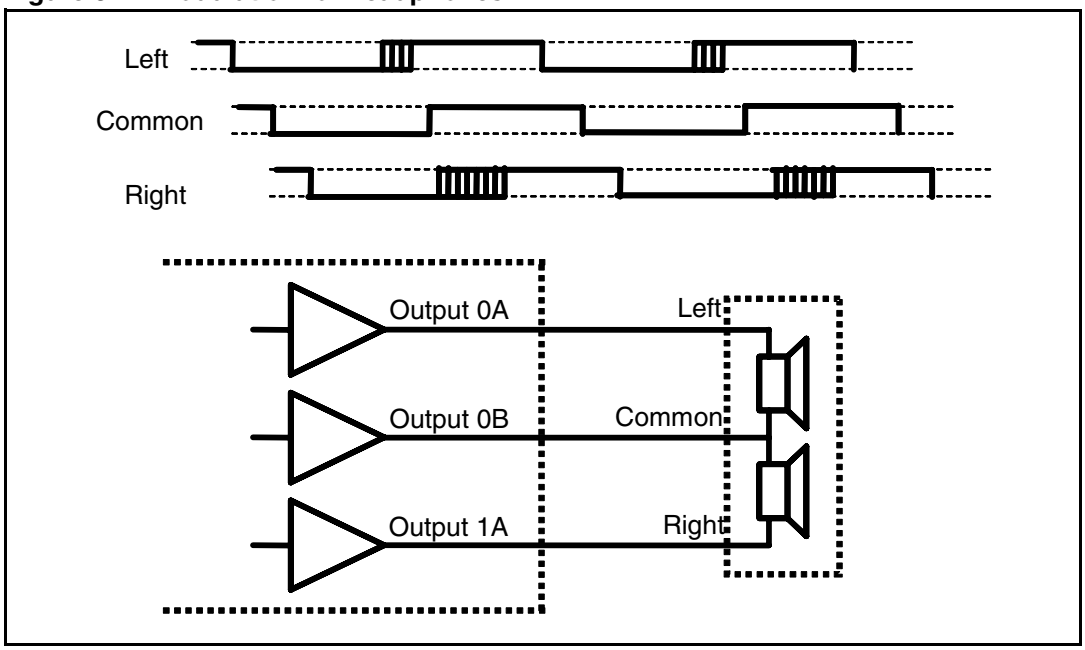
The second feature is enabled with register bit PWMOnCFG0.MP_ZERO_n, where n is the output 1 to 4. It is possible to prevent the commutations on outputs A and B to happen exactly at the same time using bit AZPLS_n. The minimum pulse size is determined by the number of system clock (98.304 MHz) periods programmed in bits MIN_PLS_n[3:0].

7.6 Headphone modulation

The FFX modulator can be used for driving a headphone load with the common terminal available, together with left and right terminals.

In this case it is possible to drive the common terminal with a 50% fixed duty cycle square wave coming from output B of the modulator, by setting bit HALFB_n to 1, and the left and right terminals from the output A of two different channels. For the three outputs used in this way bits PM_nA and PM_nB can be 00 or 01.

Figure 34. Modulation for headphones



7.7 pfStart™ operation

In order to avoid pop noise the bypass capacitor, situated between the filtered amplifier output and the load in single-ended applications, needs to be pre-charged to half of the power supply voltage. This is usually done by connecting a resistive partition to the output and then disconnecting it at the end of the charging phase (see the analog pop free description in section 9).

In the STA321 the FFX digital pop-free feature allows the digital pre-charging of the bypass capacitor using the amplifier instead of a resistive partition. This active pre-charge is also faster than the resistive partition method. The digital pop-free function can be independently set on both power stages, that is, the CMOS bridge stage using bit CB_PFDIG and the embedded amplifier stage using bit EA_PFDIG in register *FFXCFG2 on page 83*.

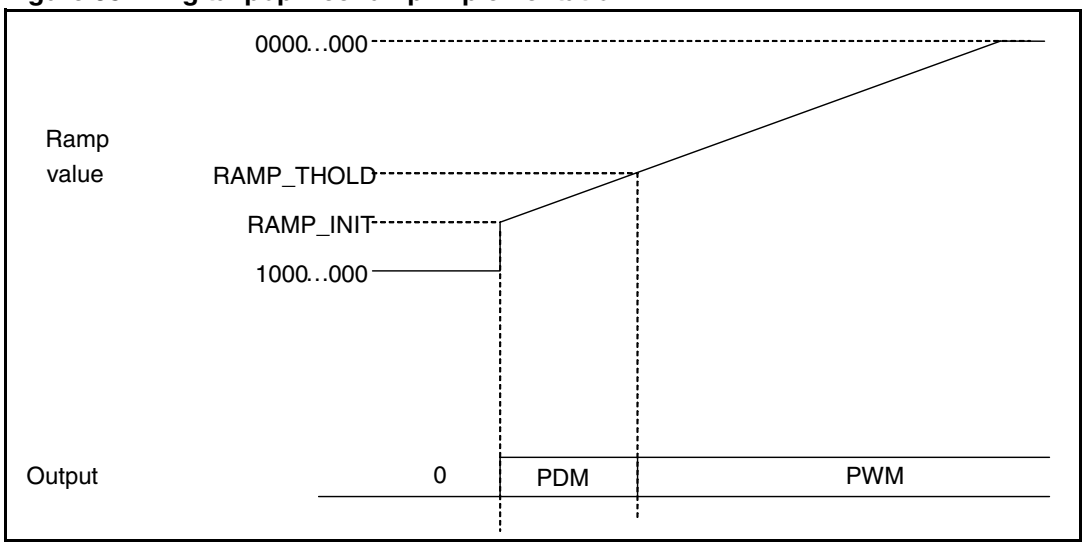
Registers CB_PFRAMP1-6 beginning *on page 97* and EA_PFRAMP1-6 beginning *on page 99* control the charging function. The register usage is given in the following description.

The capacitor is charged from zero to half the supply voltage with the PWM signal. By applying a suitable ramp to the input of the modulator the PWM signal begins from near 0% duty cycle to 50% duty cycle.

The method is based on a slow ramp signal (from ground to V_{CC} / 2), implemented using both pulse density modulation (PDM) and pulse width modulation (PWM). At the beginning of the ramp PDM is used starting from an initial value set by bits CBRMPINI and EARMPINI, and then switching to PWM when reaching a threshold value set by bits CBRMPTH and EARMPTH.

The total ramp time can be modified via bits EATIM_RMP and CBTIM_RMP.

Figure 35. Digital pop-free ramp implementation



The PDM is realized with a noise shaper circuit, where the sampling time (Td) of the noise shaper is equal to the minimum pulse size set by bits CBRMP_MP and EARMP_MP.

7.8 PWM00 output

Pin PWM00 is an additional output with a maximum driving capability of 2 mA to control an external bridge or external operational amplifier.

By default, PWM00 is tied to logical 0. When register bit CKOCFG[0] is set to 1 then any FFX PWM channel output can be mapped to it.

When the CMOS bridge is in standby the output PWM00 is, by default, turned off. However, it is possible to have the FFX signal PWM3A as the PWM00 output by using bit 3 of register *FFXCFG0 on page 82*, and this whatever the status of power-down or the 3-state signals of both bridges, even if they are different from the normal operating mode where the output is 0 when in power-down or 3-state mode.

8 CMOS power stage

The CMOS half-bridge circuit of *Figure 36* is a single channel analog output power stage. There are three such output stages in the STA321, one for each of the outputs OUT1-3.

The switching mode is regulated by the logic circuit which ensures that the MOSFETs are switched in such a way as to avoid (or minimize) conditions where both the PMOS and the NMOS are conducting at the same time.

The input is a 1.8-V to 3.3-V level shifter followed by some combinational logic.

Figure 36. CMOS half bridge block diagram

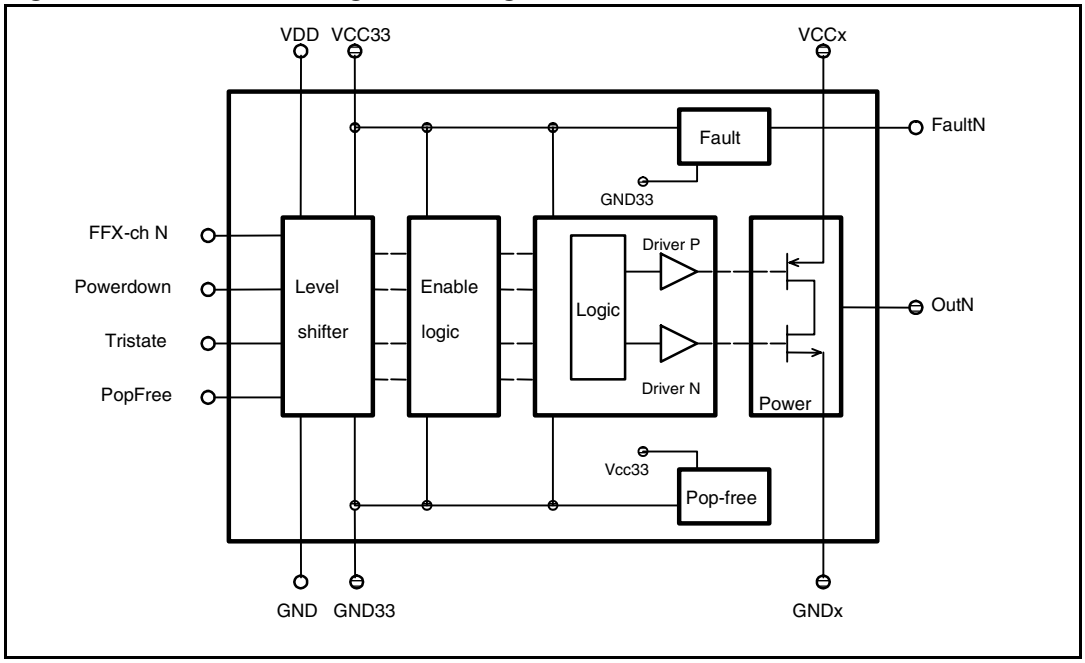


Table 24. CMOS bridge signal descriptions

Pin Name	Direction	Description
FFX-ch	In	Digital audio signal coming from FFX block
Powerdown	In	Powerdown signal coming from the FFX block
Tristate	In	3-state signal from the FFX block
PopFree	In	Pop-free signal from the FFX block
Fault	Out	Short-circuit fault output feedback signal to digital core (active low)
Out	Out	Channel half-bridge analog output
VCC33/GND33	Supply	Pre-driver analog supply
VDD/GND	Supply	Digital core supply generated by internal regulator
VCCx/GNDx	Supply	Half-bridge power supply

The CMOS bridge power rating can be calculated using the following formulas:

$P\ (<1\%) = (R_L / 2) * (M * VCC / 2 / (R_L + 2 * R_{DS}))^2$ for BTL

$P\ (<1\%) = (R_L / 2) * (M * VCC / 2 / (R_L + R_{DS}))^2$ for single ended

$P\ (10\%) = 1.28 * P(<1\%)$

where R_{DS} is composed of the MOST R_{DSON} and the board and connector parasitic resistances (including power supplies and coils) and M is the modulation index obtained from

$M = 1 - 2 * (MIN\_PLS\_n + 1) / f_{clk\_ffx} / \tau_S$

where MIN_PLS_n is the value in register PWMOnCFG0 for channel n, f_{clk_ffx} is the frequency of the FFX clock and τ_S is the PWM clock period (384 kHz or 768 kHz selected by register bit *FFXCFG2*.PWM_FREQ).

For the CMOS bridge, MIN_PLS_n can be set to 0; this gives M = 0.9922.

Table 25. Power output (at 1% THD) in headphone mode

Load, R_L in Ω	Power, P in mW (for 3.3-V supply)
16	70
32	32

The analog pop_free function is available in the CMOS bridge circuit by setting the appropriate bridge start-up as per *Table 26*. The CMOS bridge enable and pop-free signals are generated from the three signals Powerdown, Tristate and PopFree provided by the digital core and controlled/configured through register bits *FFXCFG1*.CB_STBY, *FFXCFG1*.CB_TRISTn and *PFEFAULT*.PFEn for the three outputs, n = 1 to 3.

Figure 37. Analog pop-free schematic

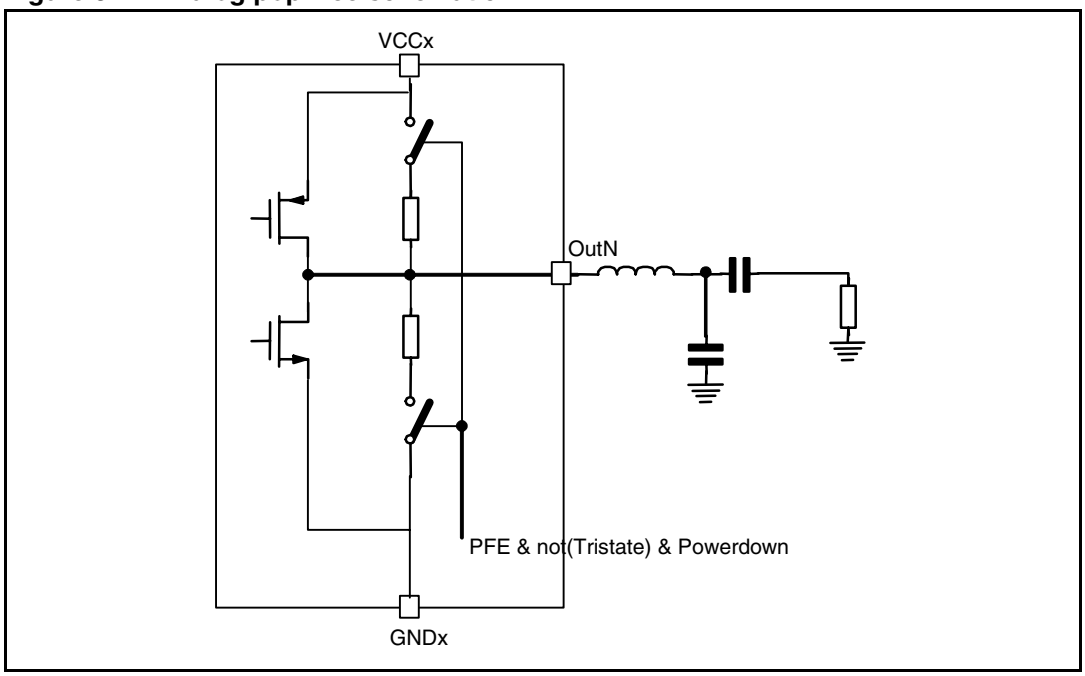


Table 26. Logic circuit at bridge input

Powerdown	Tristate	PopFree	Pop-free resistors	Bridge status
0	0	0	Disconnected	3-state
0	0	1	Disconnected	3-state
1	0	1	Connected	3-state
1	1	1	Disconnected	On
1	1	0	Disconnected	On

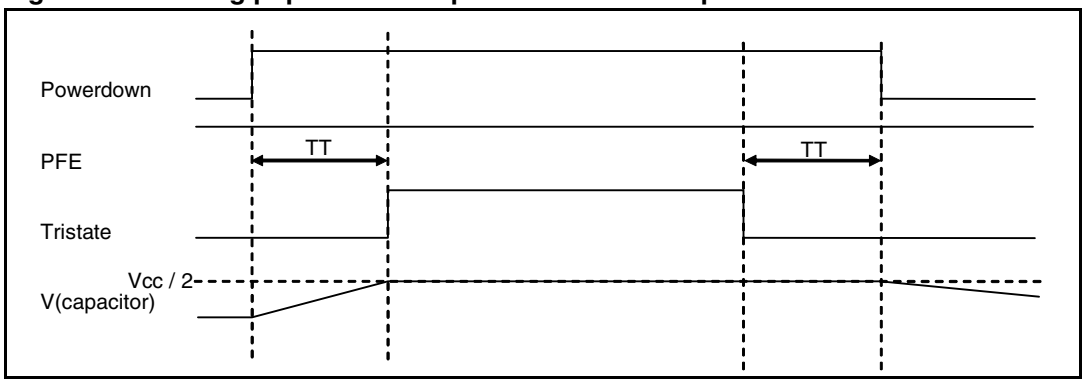
At the appropriate time the two pop-free resistors allow the bypass capacitor to be charged to V_{CCx} / 2. The STA321 generates automatically the bridge start-up and switch-off sequence to provide the correct charging. The time TT in *Figure 38* below is set using registers CBTTF0-1 and CBTTP0-1. TT must be chosen for the specific application depending on the decoupling capacitor, load and power supply.

After powerdown is applied again the decoupling capacitor discharges slowly due to capacitor leakage.

The analog pop-free implementation cannot be used with the digital pfStart implementation

Both analog and digital pop-free features must be disabled if binary headphone modulation is used.

Figure 38. Analog pop-free start-up and switch-off sequence



The CMOS bridge circuit includes over-current protection. The FAULT signal indicates to the output the status of the over-current condition due to a short circuit. The over-current thresholds detected by the CMOS bridge are fixed at 1.8 A.

9 Fault detection and recovery

9.1 External amplifier

When Fault is reported on pin EAFTN and bit EA_TSFT_ON of register *FFXCFG2 on page 83* is active, then pin EATSN is reset to 0 and the embedded bridge outputs are put in the high-impedance state. When the fault signal disappears (that is, goes to 1) the embedded bridge is kept in 3-state for a time defined in register EATTF0-1 *on page 86*, after which time the outputs recover.

9.2 CMOS bridge

When Fault is reported to the digital core and CB_TSFT_ON of register *FFXCFG2 on page 83* is active then the tristate is activated thus putting the STA321 OUTn outputs in the high-impedance state. When the fault signal disappears, the CMOS bridge is kept in 3-state status for a time defined in register CBTTF0-1 *on page 88*, after which time the outputs recover.

10 ADC

10.1 Description

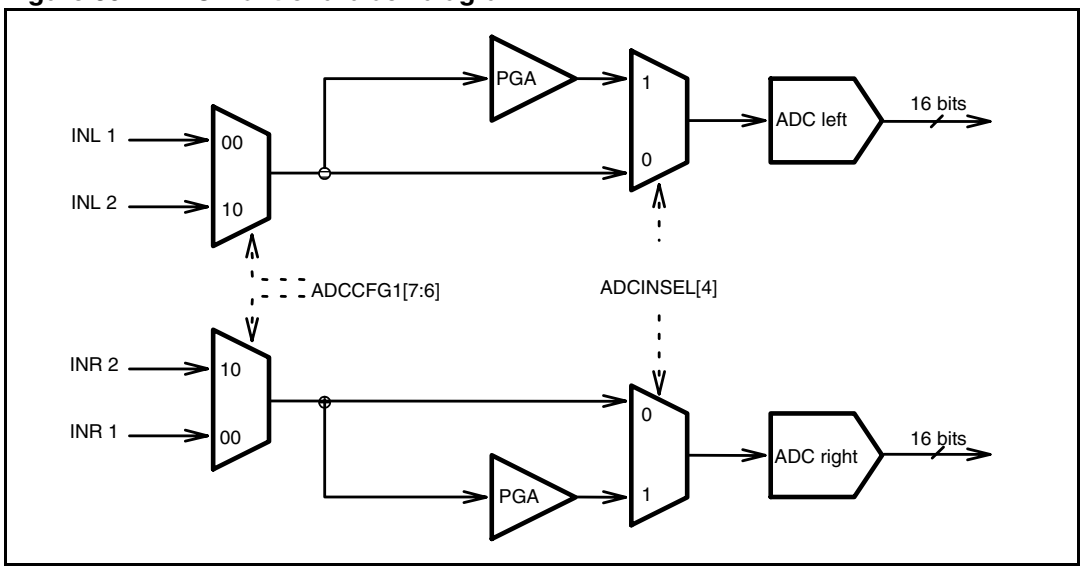
The STA321 analog input is provided through a low-power, low-voltage complete low-cost analog-to-digital converter front end designed for stereo audio applications. It includes programmable gain amplifier, anti-aliasing filter, low-noise microphone biasing circuit, a third order MASH2-1 delta-sigma modulator, a digital decimating filter and a 1st-order DC-removal filter.

The ADC works with either a microphone input or a line input, selected using bit ADC_INSEL in register *ADCCFG0 on page 133*.

A programmable gain amplifier (PGA) is available in microphone-in mode giving the possibility to amplify the signal from 0 to 42 dB in steps of 6 dB using register bit *ADCCFG0*.ADC_PGA.

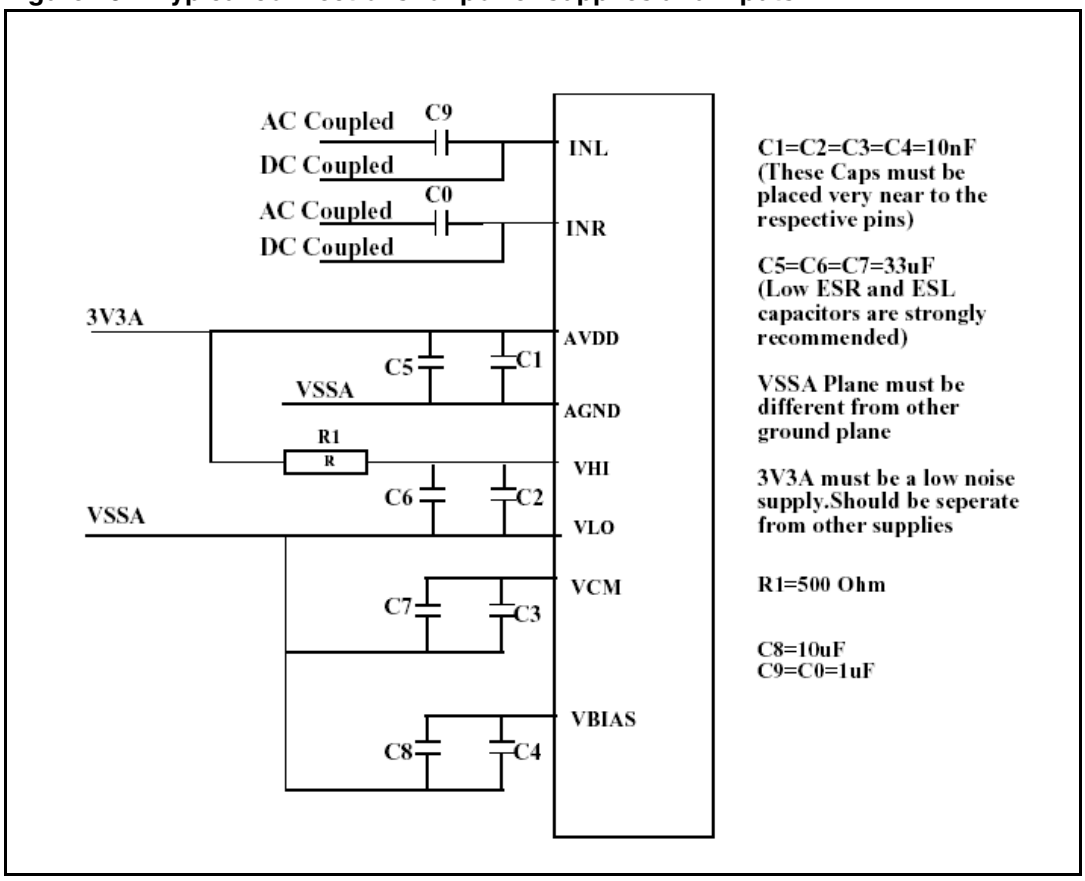
The ADC specifications are given in *Table 6 on page 14*.

Figure 39. ADC front-end block diagram



10.2 Application schematic

Figure 40. Typical connections for power supplies and inputs



10.2.1 Configuration example

This is an example of the register setup for the ADC inputs. It is assumed that every peripheral is already configured and working correctly.

There are other configuration examples to help you get started please refer to other chapters and also to *Chapter 14: Register description on page 77* in order to get all the necessary and complementary details.

Table 27 shows the register settings for selecting INL2 and INR2 as input source for SRC and SAI_out1 and using the PGA with a 12-dB gain.

Table 27. Example register settings for ADC

Register	Value	Description
ADCCFG1	0x40	Selecting INL2 and INR2 as sources
ADCCFG0	0x52	PGA Gain = +12 dB, PGA enabled, ADC clock on
P2SDATA	0x40	ADC Data routed also to the SAI_out

11 Serial audio interface

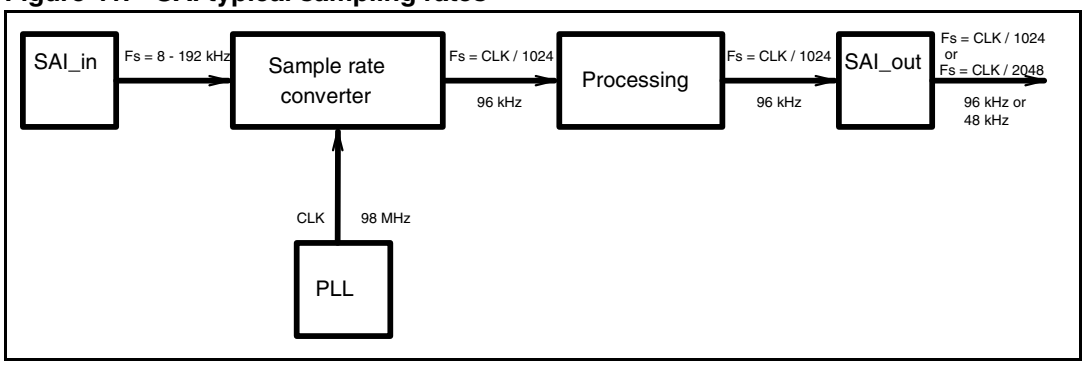
The data on pins SDATAI, SDATAO, LRCLKI and LRCLKO are always synchronous with the bit clock. The data on these pins changes with the BICLK active (or clocking) edge.

The BICLK strobe edge latches the data SDATAI, SDATAO, LRCLKI, LRCLKO; thus this data should be stable near the BICLK strobe edges. The slave device uses the strobe edges to latch the serial data internally.

The active and strobe edges can be selected to be the rising edge or the falling edge by appropriately programming register bits *SAI_IN1_CFG0*[7], *SAI_OUT_CFG0*[7] and *SAI_IN2_CFG0*[7].

The serial-to-parallel interface and the parallel-to-serial interface can have different sampling rates. *Figure 41* shows a typical setup.

Figure 41. SAI typical sampling rates



11.1 Master mode

In this mode BICLKI/BICLKO and LRCLKI/LRCLKO are configured as outputs and are generated by the core.

Figure 42. Timing diagram for master mode

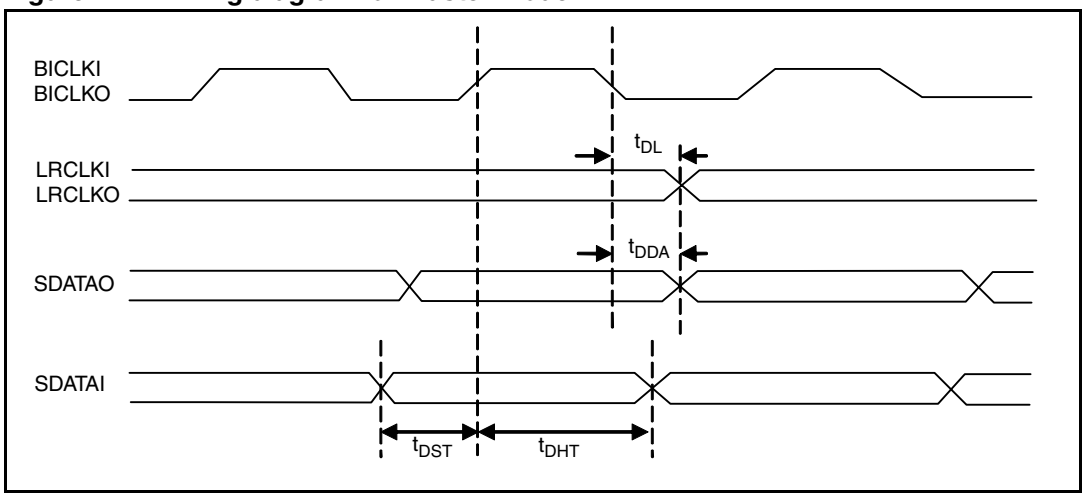


Table 28. Timing parameters for master mode

Symbol	Parameter	Min	Typ	Max	Unit
t_{DL}	LRCLKI/LRCLKO propagation delay from BICLK active edge	0	-	10	ns
t_{DDA}	SDATAI propagation delay from BICLKI/O active edge	0	-	15	ns
t_{DST}	SDATAO setup time to BICLKI/O strobing edge	10	-	-	ns
t_{DHT}	SDATAO hold time from BICLKI/O strobing edge	10	-	-	ns

11.2 Slave mode

In this mode BICLKI/O and LRCLKI/O are configured as inputs and supplied by the external peripheral.

Figure 43. Timing diagram for slave mode

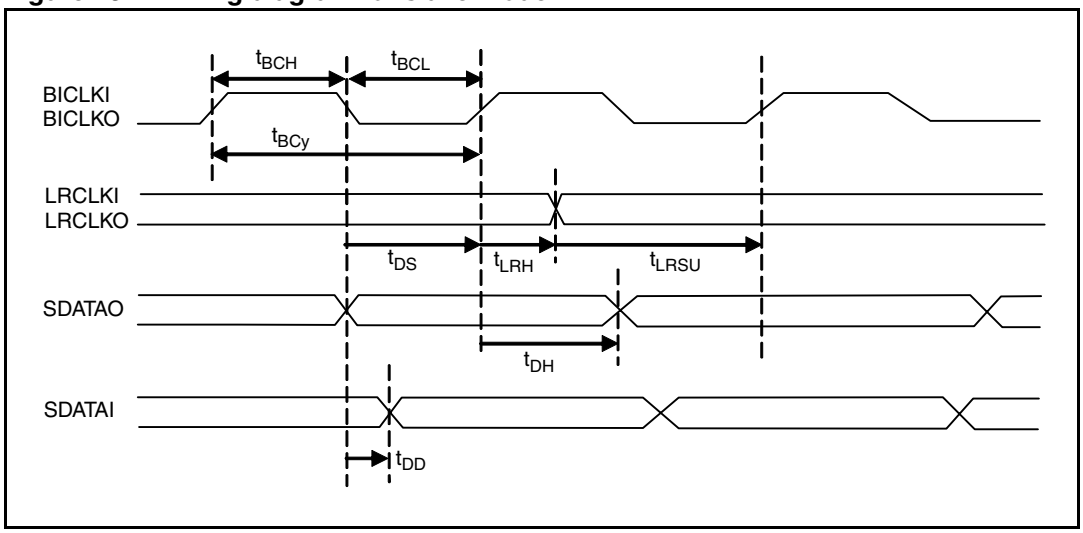


Table 29. Timing parameters for slave mode

Symbol	Parameter	Min	Typ	Max	Unit
t_{BCy}	BICLK cycle time	50	-	-	ns
t_{BCH}	BICLK pulse width high	20	-	-	ns
t_{BCL}	BICLK pulse width low	20	-	-	ns
t_{LRSU}	LRCLKI/LRCLKO setup time to BICLK strobing edge	10	-	-	ns
t_{LRH}	LRCLKI/LRCLKO hold time to BICLK strobing edge	10	-	-	ns
t_{DS}	SDATAO setup time to BICLK strobing edge	10	-	-	ns
t_{DH}	SDATAO hold time to BICLK strobing edge	10	-	-	ns
t_{DD}	SDATAI propagation delay from BICLK active edge	0	-	10	ns

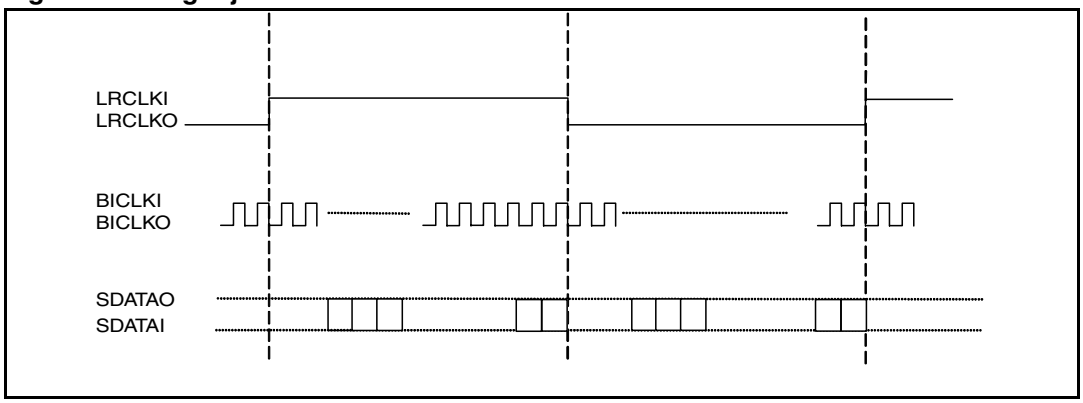
11.3 Serial formats

Different audio formats are supported in both master and slave modes. Clock and data configurations can be customized to match most of the serial audio protocols available on the market.

Data length can be customized for 8, 16, 24 or 32 bits.

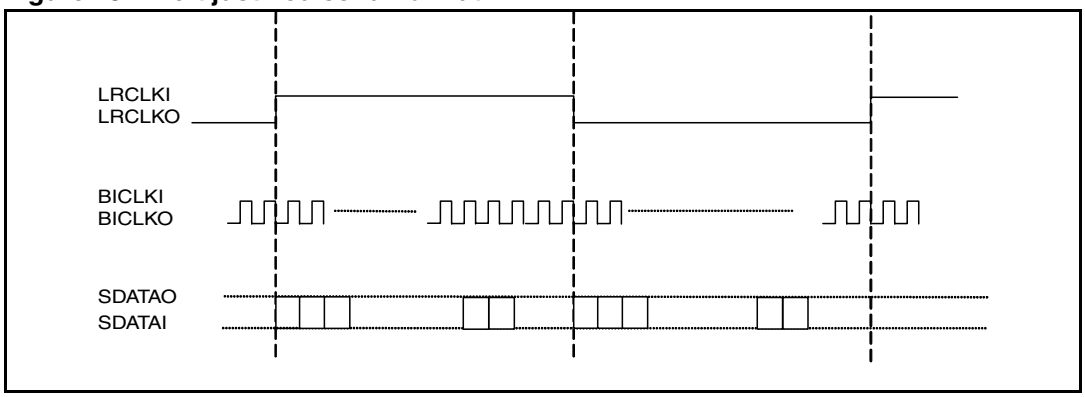
11.3.1 Right justified

Figure 44. Right justified serial format



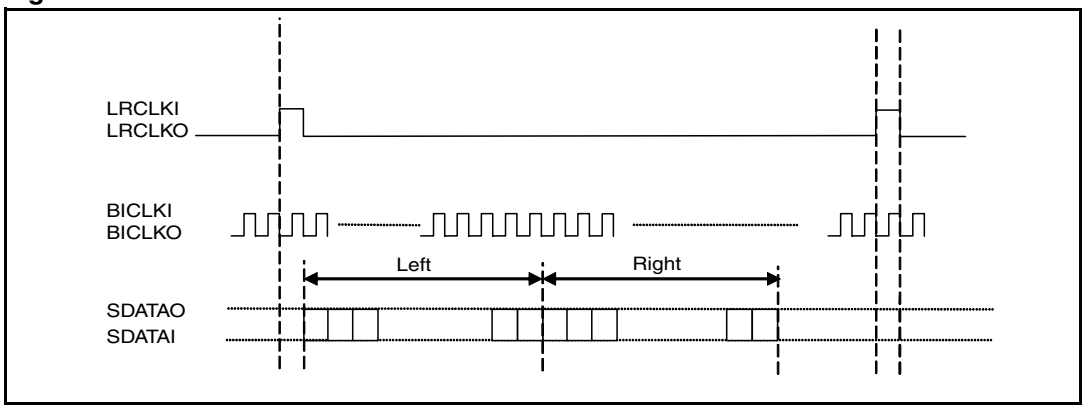
11.3.2 Left justified

Figure 45. Left justified serial format



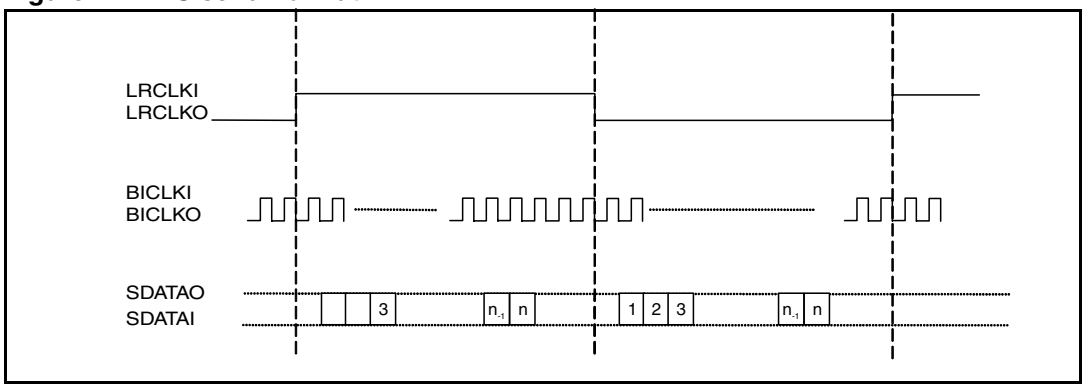
11.3.3 DSP

Figure 46. DSP serial format



11.3.4 I²S

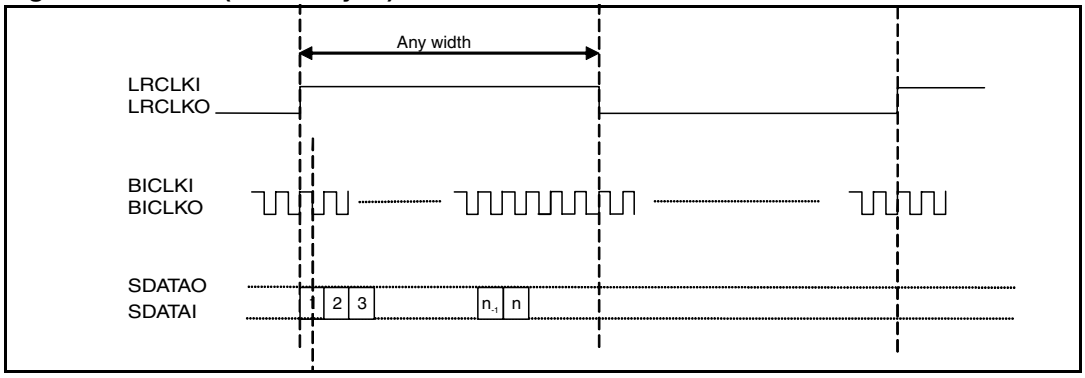
Figure 47. I²S serial format



11.3.5 PCM/IF (non-delayed mode)

- MSB first
- 16-bit data.

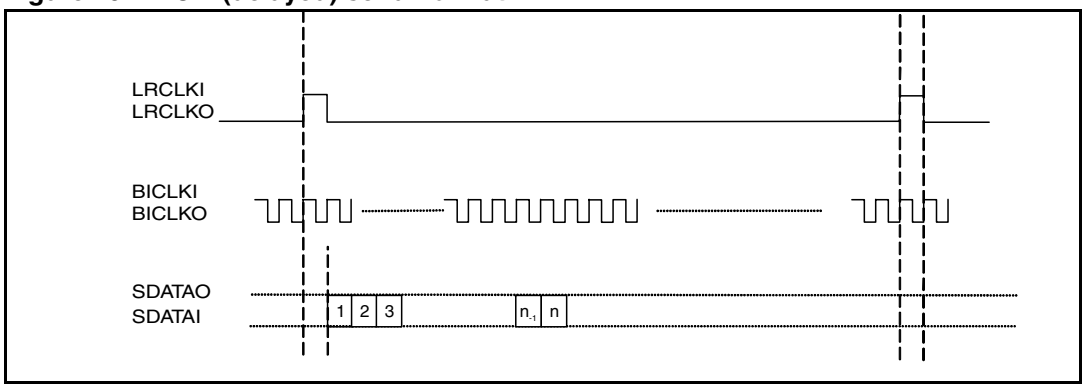
Figure 48. PCM (non-delayed) serial format



11.3.6 PCM/IF (delayed mode)

- MSB first
- 16-bit data.

Figure 49. PCM (delayed) serial format



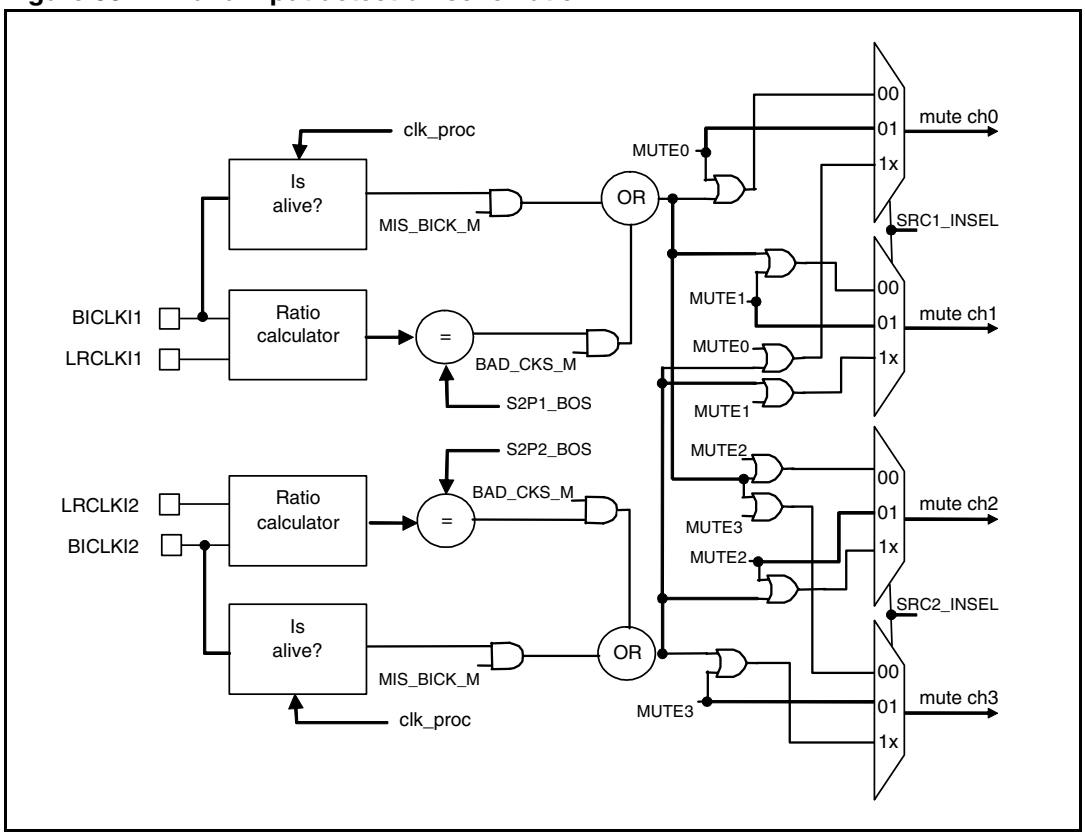
11.4 Invalid detection

STA321 has an invalid input detection feature that can detect an invalid serial interface bit clock or frame clock and then mute the processing channels to avoid any speaker or headphone damage and, moreover, to avoid loud audible transients which may be discomforting to the listener. The control is active only for the SAI input. The configuration programmed in bits 0, 1 and 2 of register *FFXCFG0 on page 82* is applicable to both SAI1 and SAI2 whilst the checks are independent for each interface. The mute on the processing channel is asserted depending on the input interface mapping.

Figure 50 shows the invalid detection schematic. Here, two different checks are available. The first one is enabled by register bit *FFXCFG0*.BAD_CKS_M and evaluates the ratio of BICLK and LRCLK. The resulting number must be the same as that written in bits S2Pn_BOS (for example, 32 * f_S or 64 * f_S) in registers *SAI_IN1_CFG1 on page 123* and *SAI_IN2_CFG1*, otherwise the channels are muted.

The second check is enabled by register bit *FFXCFG0*.MIS_BICK_M and is related to the presence of BICLK. Basically, a 8-bit watchdog counter decrements, starting from 0xFF, with each edge of clk_proc. The counter is reset to 0xFF at each BICLK edge; so, if the watchdog counter ever reaches 0x00, a missing bit clock error is signalled and the mute command is issued.

Figure 50. Invalid input detection schematic



12 Headphone detection

The headphone detector circuit, shown in *Figure 51*, is made with two schmitt-trigger comparators (with different thresholds) which sense the value of the HPDECT input voltage and modifies the HP_DET1 or the HP_DET2 level as given in *Table 30* and *Table 31* below. The comparators are enabled or disabled with bits E_HP1 and E_HP2 in register *HPDET2 on page 138*

Table 30. Headphone 1 detector

E_HP1 (register HPDET2)	HP-jack status	HP_DET voltage	HP_DET1	Status register bit HPDST.HP_DET_FILT
1	Unplugged	Low	0	-
1	Plugged	High	1	-
0	X	X	1	-

Table 31. Headphone 2 detector

E_HP2 (register HPDET2)	HP-jack status	HP_DET voltage	HP_DET2	Status register bit HPDST.HP_DET_FILT
1	Unplugged	Low	1	-
1	Plugged	High	0	-
0	X	X	1	-

The comparator output status is provided via bits 1 and 0 of register *HPDET2 on page 138*. One of the comparator outputs is then selected with register bit *HPDET1*.HPD_SEL, and that signal is passed through a digital debouncing filter and supplied to the FFX modulator. The PWM outputs are then modified depending on the settings of register bits *HPDST*.HP_DET_FILT and *HPDET1*.HPD_ACT_MODE.

12.1 Applications circuits

Two applications circuits are given here, one for the binary single-ended application and one for the binary headphone application.

Figure 51. Headphone detection circuit for single-ended configuration

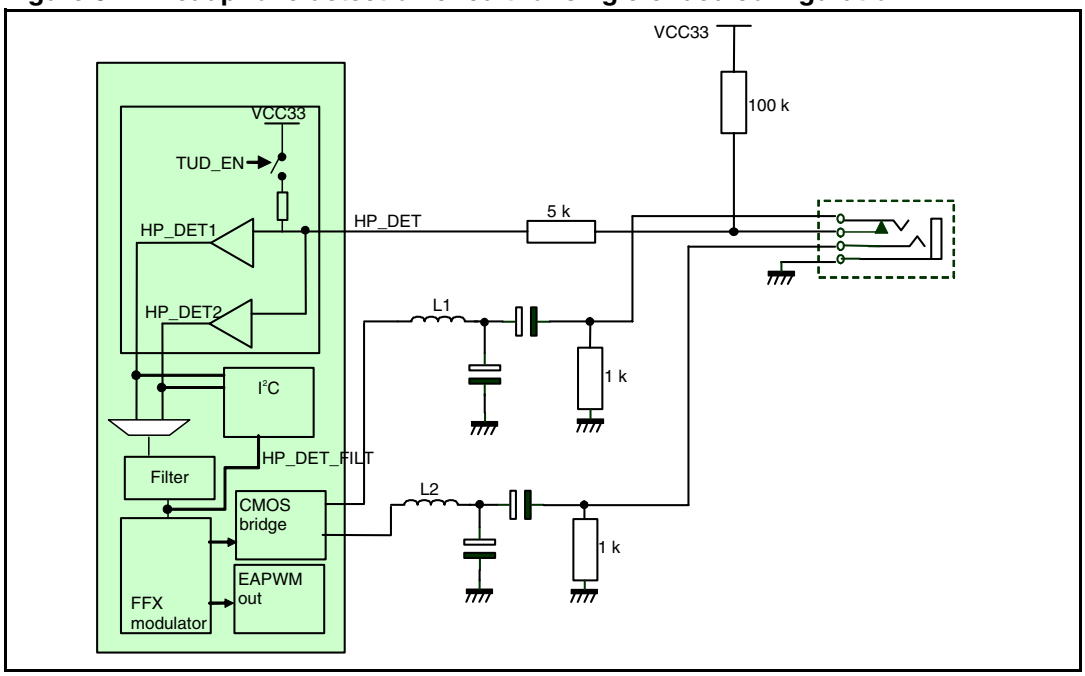
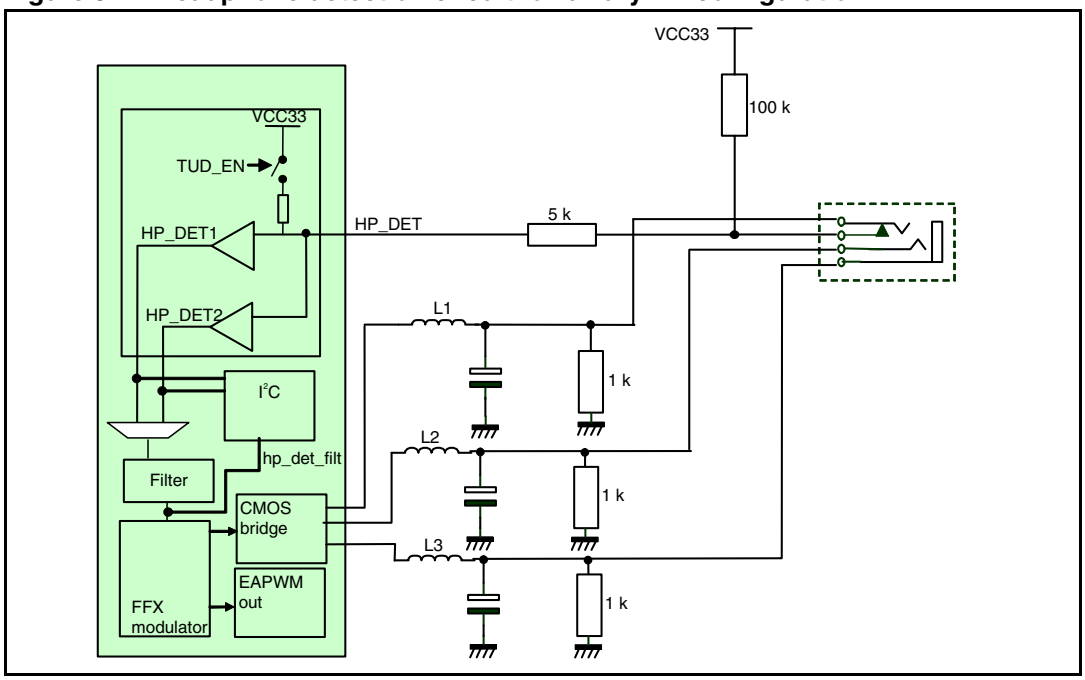


Figure 52. Headphone detection circuit for binary HP configuration



12.2 Configuration example

This is an example of the register setup for headphones detection. It is assumed that every peripheral is already configured and working correctly.

There are other configuration examples to help you get started please refer to other chapters and also to *Chapter 14: Register description on page 77* in order to get all the necessary and complementary details.

Table 32 and *Table 33* below give a possible setup for the headphones detection configurations shown in *Figure 51* and *Figure 52*, respectively.

Table 32. Headphone detection configuration sequence for binary SE

Register	Value	Description
MISC on page 135	0x21	Enable core clock
PLLB on page 136	0x00	Use PLL clock
User FFX and CMOS bridge configuration		
HPDET2 on page 138	0x80	Disable the HP_DET pull-up
HPDET1 on page 137	0x57	Use HP1 for hpdet filter; polarity = high; action = mute; mod = binary SE; average time 170 ms.
HPDET2 on page 138	0x80	Select E_HP1 comparator
FFXCFG1 on page 81	0x00	Remove the tristate from the bridges

Table 33. Headphone detection configuration sequence for binary headphone

Register	Value	Description
MISC on page 135	0x21	Enable core clock
PLLB on page 136	0x00	Use PLL clock
User FFX and CMOS bridge configuration		
HPDET2 on page 138	0x80	Disable the HP_DET pull-up
HPDET1 on page 137	0x5F	Use HP1 for hpdet filter; polarity = high; action = mute; mod = binary HP; average time 170 ms.
HPDET2 on page 138	0x80	Select E_HP1 comparator
FFXCFG1 on page 81	0x00	Remove the tristate from the bridges

Note: The pullup on HPDET pad must always be disabled before using the HPDET function.

Note: Comparator 1 and comparator 2 cannot be enabled simultaneously.

13 I²C interface

13.1 Communication protocol

13.1.1 Data transition and change

Data changes on the SDA line must only occur when the SCL clock is low. SDA transition while the clock is high is used to identify a START or STOP condition.

13.1.2 Start condition

START is identified by a high to low transition of the SDA bus while the clock signal, SCL, is stable in the high state. A START condition must precede any command for data transfer.

13.1.3 Stop condition

STOP is identified by a low to high transition on the SDA bus while the clock signal, SCL, is stable in the high state. A STOP condition terminates communication between STA321 and the bus master.

13.1.4 Data input

During the data input the STA321 samples the SDA signal on the rising edge of clock SCL. For correct device operation the SDA signal must be stable during the rising edge of the clock and the data can change only when the SCL line is low.

13.1.5 Device addressing

To start communication between the master and the STA321, the master initiates with a start condition. Following this, the master sends 8 bits (MSB first) on the SDA line which corresponds to the device select address and read or write mode.

The 7 MSBs are the device address identifiers, corresponding to the I²C bus definition. In the STA321 the I²C interface has the device address 0x30.

After a START condition the STA321 identifies the device address and if a match is found, acknowledges the identification on SDA bus during the 9th bit time. The byte following the device identification byte is the internal space address.

13.1.6 Write operation

Following the START condition the master sends a device select code with the RW bit set to 0. After the STA321 acknowledge, the master sends the byte of internal address. On receiving the internal byte address the STA321 responds with acknowledge.

Byte write

In the byte write mode the master sends one data byte, this is acknowledged by the STA321. The master then terminates the transfer by generating a STOP condition.

Multi-byte write

The multi-byte write mode starts from any internal address. The master generates a STOP condition to terminate the transfer.

13.1.7 Read operation

Current address byte read

Following the START condition the master sends a device select code with the RW bit set to 1. The STA321 acknowledges and then responds by sending one byte of data. The master then terminates the transfer by generating a STOP condition.

Current address multi-byte read

The multi-byte read mode start from any internal address. Data bytes are read from sequential addresses within the STA321. The master acknowledges each data byte read and then generates a STOP condition to terminate the transfer.

Random address byte read

Following the START condition the master sends a device select code with the RW bit set to 0. The STA321 acknowledges and then the master writes the internal address byte. After receiving, the internal byte address the STA321 again responds with an acknowledge. The master then initiates another START condition and sends the device select code with the RW bit set to 1. The STA321 acknowledges this and then responds by sending one byte of data. The master then terminates the transfer by generating a STOP condition.

Random address multi-byte read

The multi-byte read modes start from any internal address. Data bytes are read from sequential addresses within the STA321. The master acknowledges each data byte read and then generates a STOP condition to terminate the transfer.

Figure 53. I²C write operations

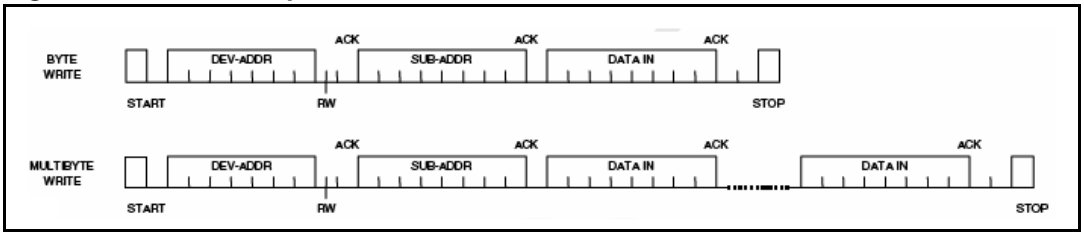
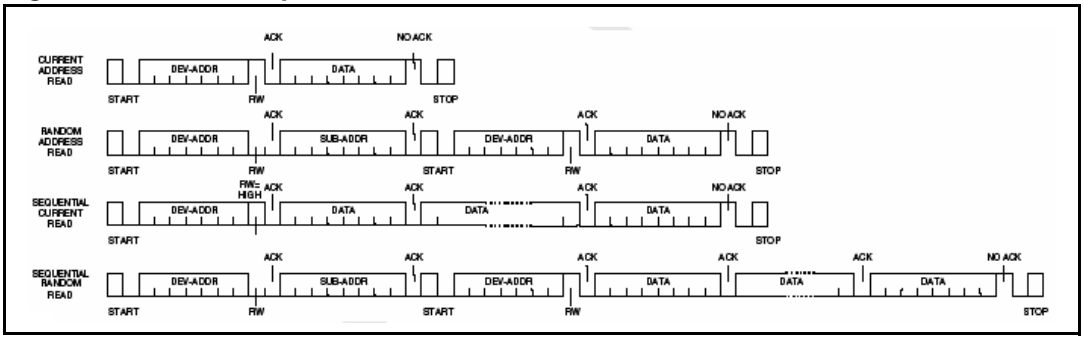


Figure 54. I²C read operations



14 Register description

Table 34. Register summary

Register	Addr	7	6	5	4	3	2	1	0
FFXCFG1	0x00	EA_STBY	CB_STBY	EA_TRIST	FFX_ULCK_PLL		CB_TRIST2	CB_TRIST1	CB_TRIST0
FFXCFG0	0x01	MUTE3	MUTE2	MUTE1	MUTE0	PWM00_3A	BAD_IN_M	BAD_CKS_M	MIS_BICK_M
FFXCFG2	0x02	RESET _NOISH	PWM_FREQ	NS_ORD[1:0]		EA_TSFT_ON	CB_TSFT_ON	EA_PFDIG	CB_PFDIG
PWMMAP1	0x03	CB1_MAP[2:0]			CB2_MAP[2:0]			CB3_MAP[2:1]	
PWMMAP2	0x04	CB3_MAP[0]	PWM00_MAP[2:0]			EA1A_MAP[2:0]			EA1B_MAP[2]
PWMMAP3	0x05	EA1B_MAP[1:0]		EA2A_MAP[2:0]			EA2B_MAP[2:0]		
EATTF0	0x06	EATTF[7:0]							
EATTF1	0x07	EATTF[7:0]							
EATTP0	0x08	EATTP[15:8]							
EATTP1	0x09	EATTP[7:0]							
CBTTF0	0x0A	CBTTF[15:8]							
CBTTF1	0x0B	CBTTF[7:0]							
CBTTP0	0x0C	CBTTP[15:8]							
CBTTP1	0x0D	CBTTP[7:0]							
FFXST	0x0E	EA_MPWM	CB_MPWM	EARMP_ST[1:0]		CBRMP_ST[1:0]		EABINSS_AC	CBBINSS_AC
POWST	0x0F	Reserved				EA_TW	EA_PD	EA_FT	EA_TS
POWST1	0x10	Reserved	CB_PD	CB_FT[2:0]			CB_TS[2:0]		
PWMO1CFG0	0x11	AZPLS_1	TERNARY_1	HALFB_1	MP_ZERO_1	MIN_PLS_1[3:0]			
PWMO1CFG1	0x12	PM_1A[1:0]		PS_1A[5:0]					
PWMO1CFG2	0x13	PM_1B[1:0]		PS_1B[5:0]					
PWMO2CFG0	0x14	AZPLS_2	TERNARY_2	HALFB_2	MP_ZERO_2	MIN_PLS_2[3:0]			
PWMO2CFG1	0x15	PM_2A[1:0]		PS_2A[5:0]					
PWMO2CFG2	0x16	PM_2B[1:0]		PS_2B[5:0]					
PWMO3CFG0	0x17	AZPLS_3	TERNARY_3	HALFB_3	MP_ZERO_3	MIN_PLS_3[3:0]			
PWMO3CFG1	0x18	PM_3A[1:0]		PS_3A[5:0]					
PWMO3CFG2	0x19	PM_3B[1:0]		PS_3B[5:0]					
PWMO4CFG0	0x1A	AZPLS_4	TERNARY_4	HALFB_4	MP_ZERO_4	MIN_PLS_4[3:0]			
PWMO4CFG1	0x1B	PM_4A[1:0]		PS_4A[5:0]					
PWMO4CFG2	0x1C	PM_4B[1:0]		PS_4B[5:0]					
CB_PFRAMP1	0x20	CBRMP_MP[5:0]						Reserved	
CB_PFRAMP2	0x21	CBRMPINI[15:8]							
CB_PFRAMP3	0x22	CBRMPINI[7:0]							
CB_PFRAMP4	0x23	CBTIM_RMP[3:0]				Reserved			
CB_PFRAMP5	0x24	CBRMPTH[15:8]							
CB_PFRAMP6	0x25	CBRMPTH[7:0]							
EA_PFRAMP1	0x26	EARMP_MP[5:0]						Reserved	
EA_PFRAMP2	0x27	EARMPINI[15:8]							

Table 34. Register summary (continued)

Register	Addr	7	6	5	4	3	2	1	0
EA_PFRAMP3	0x28	EARMPINI[7:0]							
EA_PFRAMP4	0x29	EATIM_RMP[3:0]				Reserved			
EA_PFRAMP5	0x2A	EARMPTH[15:8]							
EA_PFRAMP6	0x2B	EARMPTH[7:0]							
SRC1STATE	0x30	SRC1_BYP[1:0]		SRC_1_LOCK	SRC1_FISFO[4:0]				
SRC2STATE	0x31	SRC1_BYP[1:0]		SRC_1_LOCK	SRC1_FISFO[4:0]				
I2CB0_TOP	0x51	I2CB0[23:16]							
I2CB0_MID	0x52	I2CB0[15:8]							
I2CB0_BOT	0x53	I2CB0[7:0]							
I2CB1_TOP	0x54	I2CB1[23:16]							
I2CB1_MID	0x55	I2CB1[15:8]							
I2CB1_BOT	0x56	I2CB1[7:0]							
I2CB2_TOP	0x57	I2CB2[23:16]							
I2CB2_MID	0x58	I2CB2[15:8]							
I2CB2_BOT	0x59	I2CB2[7:0]							
I2CA1_TOP	0x5A	I2CA1[23:16]							
I2CA1_MID	0x5B	I2CA1[15:8]							
I2CA1_BOT	0x5C	I2CA1[7:0]							
I2CA2_TOP	0x5D	I2CA2[23:16]							
I2CA2_MID	0x5E	I2CA2[15:8]							
I2CA2_BOT	0x5F	I2CA2[7:0]							
PROCCTRL	0x60	Reserved				RA	Reserved	WA	W1
START_ADD2	0x61	Reserved							I2CSTART_A8
START_ADD	0x62	I2CSTART_A7_A0							
ROM_REMAP	0x6F	Reserved	ENAB_PRE3	ENAB_PRE2	ENAB_PRE1	ENAB_PRE0	ENAB_POST	ENAB_PRMIX	ENAB_DELAY
BYP_EN_CH0	0x70	Reserved							
EFFS_EN_CH0	0x71	Reserved						EROM09	EROM08
BYP_EN_CH1	0x72	Reserved							
EFFS_EN_CH1	0x73	Reserved						EROM19	Reserved
BYP_EN_CH2	0x74	Reserved							
EFFS_EN_CH2	0x75	Reserved						EROM29	EROM28
BYP_EN_CH3	0x76	Reserved							
EFFS_EN_CH3	0x77	Reserved						EROM39	Reserved
BASS_SEL0_R	0x78	Reserved		BASS_EN0	BASS_SEL0				
BASS_SEL1_R	0x79	Reserved		BASS_EN1	BASS_SEL1				
BASS_SEL2_R	0x7A	Reserved		BASS_EN2	BASS_SEL2				
BASS_SEL3_R	0x7B	Reserved		BASS_EN3	BASS_SEL3				
TREB_SEL0_R	0x7C	Reserved		TREB_EN0	TREB_SEL0				
TREB_SEL1_R	0x7D	Reserved		TREB_EN1	TREB_SEL1				
TREB_SEL2_R	0x7E	Reserved		TREB_EN2	TREB_SEL2				

Table 34. Register summary (continued)

Register	Addr	7	6	5	4	3	2	1	0
TREB_SEL3_R	0x7F	Reserved		TREB_EN3	TREB_SEL3				
SATCH0CFG1	0x90	SAT_EQ	SAT_CH0[22:16]						
SATCH0CFG2	0x91	SAT_CH0[15:8]							
SATCH0CFG3	0x92	SAT_CH0[7:0]							
SATCH1CFG1	0x93	Reserved	SAT_CH1[22:16]						
SATCH1CFG2	0x94	SAT_CH1[15:8]							
SATCH1CFG3	0x95	SAT_CH1[7:0]							
SATCH2CFG1	0x96	Reserved	SAT_CH2[22:16]						
SATCH2CFG2	0x97	SAT_CH2[15:8]							
SATCH2CFG3	0x98	SAT_CH2[7:0]							
SATCH3CFG1	0x99	Reserved	SAT_CH3[22:16]						
SATCH3CFG2	0x9A	SAT_CH3[15:8]							
SATCH3CFG3	0x9B	SAT_CH3[7:0]							
VOLCFG	0xA0	SVOL_ON3	SVOL_ON2	SVOL_ON1	SVOL_ON0	TIM_SVOL			
MVOL	0xA1	MVOL							
VOLCH0	0xA2	CVOL0							
VOLCH1	0xA3	CVOL1							
VOLCH2	0xA4	CVOL2							
VOLCH3	0xA5	CVOL3							
SAI_IN1_CFG0	0xB0	S2P1_B_STR	S2P1_LR_L	Reserved	S2P1_MSB	S2P1_DFM			S2P1_MMD
SAI_IN1_CFG1	0xB1	S2P1_DLEN		S2P1_BOS		S2P1_MAP_L		S2P1_MAP_R	
SAI_OUT_CFG0	0xB2	P2S_B_STR	P2S_LR_L	SDATAO_ACT	P2S_MSB	P2S_DFM			P2S_MMD
SAI_OUT_CFG1	0xB3	P2S_DLEN		P2S_BOS		P2S_MAP_L		P2S_MAP_R	
SAI_IN2_CFG0	0xB4	S2P2_B_STR	S2P2_LR_L	Reserved	S2P2_MSB	S2P2_DFM			S2P2_MMD
SAI_IN2_CFG1	0xB5	S2P2_DLEN		S2P2_BOS		S2P2_MAP_L		S2P2_MAP_R	
AUIFSHARE	0xB6	Reserved						SHARE_BILR	
SRCINSEL	0xB7	SRC1_INSEL		SRC2_INSEL		MUTE_SRCU	Reserved		
P2SDATA	0xB8	Reserved	P2S_HFS	P2S1_DSEL			P2S2_DSEL		
PLLCFG0	0xC0	PLL_DPROG	PLL_FR _CTRL	PLL_DDIS		PLL_IDF			
PLLCFG1	0xC1	PLL_FRAC[15:8]							
PLLCFG2	0xC2	PLL_FRAC[7:0]							
PLLCFG3	0xC3	PLL_STRB	PLL _STRBBYP	PLL_NDIV					
PLLPFE	0xC4	PLL_BYP _UNL	BICLK2PLL	PLL_PWDN	PLL _NOPDDIV	Reserved			
PLLST	0xC5	PLL_UNLOCK	PLL_PWD_ST	PLL_BYP_ST	Reserved				
ADCCFG0	0xC6	ADC_PGA			ADC_INSEL	ADC_STBY	ADC_BYPCAL	CLK_ADC_ON	Reserved
CKOCFG	0xC7	CLKOUT_DIS	CLKOUT_SEL		CLK_FFX_ON	CLK_SRC_ON	CLK_PROC _ON	EAPWM_DIS	PWM00ACT
MISC	0xC8	OSC_DIS	S2P_FS_RNG			ADC_FS_RNG		P2P_IN_ADC	CLKCORE _ON

Table 34. Register summary (continued)

Register	Addr	7	6	5	4	3	2	1	0
PLLB	0xC9	PLL_BYP	Reserved	ADC_CLKSEL	Reserved	P2S1 _CLKSEL	Reserved	P2S2 _CLKSEL	Reserved
HPDET1	0xCA	HPD_SEL	HPD_POL	HPD_ACT_MODE		HPD_HPMOD	HPD_TIM_F		
HPDET2	0xCB	E_HP2	E_HP1	TUD_EN	Reserved			E_HPDET1	E_HPDET2
HPDST	0xCC	HPD_DET _FILT	Reserved						
STBY_MODES	0xCD	PAD_PULLDIS	Reserved					CMP_EN_N	DC_STBY _EN_N
ADCCFG1	0xCE	ADC_ANA_SEL		Reserved					
PFEFAULT	0xCF	Reserved			PFE1	PFE2	PFE3	RESET_EA _FT	RESET_CB _FT
BISTRUN0	0xD0	SF1_BRUN	SF2_BRUN	SS1_BRUN	SS2_BRUN	CF_BRUN	PR_BRUN	CF_ROM _BRUN	Reserved
BISTRUN1	0xD1	OS_BRUN	DB_BRUN	Reserved					
BISTST0	0xD2	SF1_BEND	SF1_BBAD	SF1_BFAIL	SF2_BEND	SF2_BBAD	SF2_BFAIL	SS1_BEND	SS1_BBAD
BISTST1	0xD3	SS1_BFAIL	SS2_BEND	SS2_BBAD	SS2_BFAIL	CF_BEND	CF_BBAD	CF_BFAIL	PR_BEND
BISTST2	0xD4	PR_BBAD	PR_BFAIL	OS_BEND	OS_BBAD	OS_BFAIL	DB_BEND	DB_BBAD	DB_BFAIL
BISTST3	0xD5	CF_ROM _BEND	Reserved						
ROMSIGN0	0xD6	CF_ROMS[7:0]							
ROMSIGN1	0xD7	CF_ROMS[15:8]							
ROMSIGN2	0xD8	CF_ROMS[23:16]							
DEBUG0	0xD9	DBGCKO_ON	DBGCKO_VAL						
PADST0	0xF0	PAD_RSTN	Reserved	PAD_SCL	PAD_SDA	PAD_I2CDIS	Reserved		PAD_STBY
PADST1	0xF1	PAD_MUTE	PAD_BICLKI	PAD_LRCLKI	PAD_SDATAI	PAD_BICLKO	PAD_LRCLKO	Reserved	

FFXCFG1

7	6	5	4 3	2	1	0
EA_STBY	CB_STBY	EA_TRIST	FFX_ULCK_PLL	CB_TRIST2	CB_TRIST1	CB_TRIST0

Address: 0x00

Type: RW

Reset: 0xD0

Description:

[7] EA_STBY
0: the external bridge is active
1: the external bridge is in standby mode

[6] CB_STBY
0: the bridge is active
1: the bridge is in standby mode

[5] EA_TRIST
0: normal behaviour
1: the external bridge is put in 3-state mode

[4:3] FFX_ULCK_PLL: behavior of the FFX modulator in the event of the PLL losing lock:
00: do nothing
01: FFX hard mute (equivalent to using pin MUTE)
10: FFX standby
11: FFX hard mute and noise-shaper reset

[2] CB_TRIST2
0: the bridge is active
1: force CMOS bridge OUT3 to 3-state

[1] CB_TRIST1
0: the bridge is active
1: force CMOS bridge OUT2 to 3-state

[0] CB_TRIST0
0: normal behaviour
1: force CMOS bridge OUT1 to 3-state

FFXCFG0

7	6	5	4	3	2	1	0
MUTE3	MUTE2	MUTE1	MUTE0	PWM00_3A	BAD_IN_M	BAD_CKS_M	MIS_BICK_M

Address: 0x01

Type: RW

Reset: 0x07

Description:

[7] MUTE3
0: normal behaviour
1: force the mute in the channel 3

[6] MUTE2
0: normal behaviour
1: force the mute in the channel 2

[5] MUTE1
0: normal behaviour
1: force the mute in the channel 1

[4] MUTE0
0: normal behaviour
1: force the mute in the channel 0

[3] PWM00_3A
0: output PWM00 is driven by FFX (default)
1: output PWM00 comes from FFX output PWM3A and is not sensitive to bridge power-down or 3-state states

[2] BAD_IN_M
Depending on the bit 0 and bit 1 settings
0: mute with a ramp
1: mute instantaneously

[1] BAD_CKS_M
0: FFX not muted
1: FFX muted if biclk and lrclk do not meet the specification

[0] MIS_BICK_M
0: FFX not muted
1: FFX will be muted if biclk is missing

FFXCFG2

7	6	5 4	3	2	1	0
RESET_NOISH	PWM_FREQ	NS_ORD[1:0]	EA_TSFT_ON	CB_TSFT_ON	EA_PFDIG	CB_PFDIG

Address: 0x02

Type: RW

Reset: 0x2D

Description:

[7] **RESET_NOISH**
1: a reset is forced to the noise-shaper block

[6] PWM_FREQ
0: 4 f_S (4*96 kHz = 384 kHz)
1: 8 fS (8*96 kHz = 768 kHz)

[5:4] NS_ORD[1:0]
Noise shape order
00: 3rd. order
01: 4th. order
10: 5th. order

[3] EA_TSFT_ON
1: if there is a fault on the external bridge, it will be put in 3-state

[2] CB_TSFT_ON
1: if there is a fault on the CMOS bridge, it will be put in 3-state

[1] EA_PFDIG
1: enable the pop-free ramp of EA

[0] **CB_PFDIG**
1: enable the pop-free ramp of CB

Note: Particular care must be taken when bits NS_ORD and PWM_FREQ are changed. To avoid any audible artifacts, these bits must be modified only with the following procedure:

1. Mute STA321 processing.
2. Change PWM_FREQ and/or NS_ORD and set RESET_NOISH = 1.
3. Configure RESET_NOISH = 0.
4. Unmute STA321 processing.

PWMMAP1 Processing to PWM out mapping

7	6	5	4	3	2	1	0
CB1_MAP[2:0]			CB2_MAP[2:0]			CB3_MAP[2:1]	

Address: 0x03

Type: RW

Reset: 0x08

Description:

[7:5] CB1_MAP[2:0]

CB_PWM_1 channel mapping:

000: Ch0-A	001: Ch0-B
010: Ch1-A	011: Ch1-B
100: Ch2-A	101: Ch2-B
110: Ch3-A	111: Ch3-B

[4:2] CB2_MAP[2:0]

CB_PWM_2 channel mapping

000: Ch0-A	001: Ch0-B
010: Ch1-A	011: Ch1-B
100: Ch2-A	101: Ch2-B
110: Ch3-A	111: Ch3-B

[1:0] CB3_MAP[2:1]

CB_PWM_3 channel mapping (for bit 0 see register *PWMMAP2*):

000: Ch0-A	001: Ch0-B
010: Ch1-A	011: Ch1-B
100: Ch2-A	101: Ch2-B
110: Ch3-A	111: Ch3-B

PWMMAP2

7	6	5	4	3	2	1	0
CB3_MAP[0]	PWM00_MAP[2:0]			EA1A_MAP[2:0]			EA1B_MAP[2]

Address: 0x04

Type: RW

Reset: 0xB9

Description:

[7] **CB3_MAP[0]**
CB_PWM_3 channel mapping (for bits 1 and 2 see register *PWMMAP1*)

[6:4] PWM00_MAP[2:0]
PWM00 channel mapping:

000: Ch0-A	001: Ch0-B
010: Ch1-A	011: Ch1-B
100: Ch2-A	101: Ch2-B
110: Ch3-A	111: Ch3-B

[3:1] EA1A_MAP[2:0]
EA_PWM_1A channel mapping:

000: Ch0-A	001: Ch0-B
010: Ch1-A	011: Ch1-B
100: Ch2-A	101: Ch2-B
110: Ch3-A	111: Ch3-B

[0] **EA1B_MAP[2]**
EA_PWM_1B channel mapping (for bits 1and 0 see register *PWMMAP3*)

000: Ch0-A	001: Ch0-B
010: Ch1-A	011: Ch1-B
100: Ch2-A	101: Ch2-B
110: Ch3-A	111: Ch3-B

PWMMAP3

7	6	5	4	3	2	1	0
EA1B_MAP[1:0]		EA2A_MAP[2:0]			EA2B_MAP[2:0]		

Address: 0x05

Type: RW

Reset: 0x77

Description:

[7:6] **EA1B_MAP[1:0]**
EA_PWM_1B channel mapping (for bit 2 see register *PWMMAP2*)

[5:3] EA2A_MAP[2:0]
EA_PWM_2A channel mapping:

000: Ch0-A	001: Ch0-B
010: Ch1-A	011: Ch1-B
100: Ch2-A	101: Ch2-B
110: Ch3-A	111: Ch3-B

[2:0] EA2B_MAP[2:0]
EA_PWM_2B channel mapping:

000: Ch0-A	001: Ch0-B
010: Ch1-A	011: Ch1-B
100: Ch2-A	101: Ch2-B
110: Ch3-A	111: Ch3-B

EATTF0 External bridge tristate time from fault

7	6	5	4	3	2	1	0
EATTF[15:8]							

Address: 0x06

Type: RW

Reset: 0x00

Description: The tristate time is the time between fault deasserted and 3-state removed for the external bridge. It is calculated as EATTF[15:0] * 41.66 µs

[7:0] EATTF[15:8]
MSBs of the EA tristate time factor

EATTF1 External bridge tristate time from fault

7	6	5	4	3	2	1	0
EATTF[7:0]							

Address: 0x07

Type: RW

Reset: 0x03

Description: See also register *EATTF0*

[7:0] EATTF[7:0]
LSBs of EA tristate time factor

EATTP0 External bridge tristate time from powerdown

7	6	5	4	3	2	1	0
EATTP[15:8]							

Address: 0x08

Type: RW

Reset: 0x00

Description: This tristate time is the time between bridge powerdown removed and 3-state removed for the external bridge. It is calculated as EATTP[15:0] * 41.66 µs

[7:0] **EATTP[15:8]**
MSBs of EA 3-state time after power-up factor

EATTP1 External bridge tristate time from powerdown

7	6	5	4	3	2	1	0
EATTP[7:0]							

Address: 0x09

Type: RW

Reset: 0x03

Description: See also register *EATTP0*

[7:0] **EATTP[7:0]**
LSBs of EA 3-state time after power-up factor

CBTTF0 CMOS bridge tristate time from fault

7	6	5	4	3	2	1	0
CBTTF[15:8]							

Address: 0x0A

Type: RW

Reset: 0x00

Description: The tristate time is the time between fault deasserted and 3-state removed for the CMOS bridge. It is calculated as CBTTF[15:0] * 41.66 µs

[7:0] **CBTTF[15:8]**
MSBs of CB 3-state time factor

CBTTF1 CMOS bridge tristate time from fault

7	6	5	4	3	2	1	0
CBTTF[7:0]							

Address: 0x0B

Type: RW

Reset: 0x02

Description: See also register *CBTTF0*

[7:0] **CBTTF[7:0]**
LSBs of CB 3-state time factor

CBTTP0 CMOS bridge tristate time from powerdown

7	6	5	4	3	2	1	0
CBTTP[15:8]							

Address: 0x0C

Type: RW

Reset: 0x00

Description: This tristate time is the time between bridge powerdown removed and 3-state removed for the CMOS bridge. It is calculated as CBTTP[15:0] * 41.66 µs

[7:0] **CBTTP[15:8]**
MSBs of CB 3-state time after power-up factor

CBTTP1 CMOS bridge tristate time from powerdown

7	6	5	4	3	2	1	0
CBTTP[7:0]							

Address: 0x0D

Type: RW

Reset: 0x02

Description: See also register *CBTTP0*

[7:0] **CBTTP[7:0]**
LSBs of CB 3-state time after power-up factor

FFXST

7	6	5	4	3	2	1	0
EA_MPWM	CB_MPWM	EARMP_ST[1:0]		CBRMP_ST[1:0]		EABINSS_AC	CBBINSS_AC

Address: 0x0E

Type: RO

Reset: 0xC0

Description:

[7] **EA_MPWM**
1: EA is in mute

[6] CB_MPWM
1: CB is in mute

[5:4] **EARMP_ST[1:0]**: pop free ramp status
00: parked
11: ready
10: going to park
01: going to ready

[3:2] CBRMP_ST[1:0]: pop free ramp status
00: parked
11: ready
10: going to park
01: going to ready

[1] EABINSS_AC
1: ramp active (going to park or ready)

[0] **CBBINSS_AC**
1: ramp active (going to park or ready)

POWST Status register for external amplifier

7	6	5	4	3	2	1	0
Reserved				EA_TW	EA_PD	EA_FT	EA_TS

Address: 0x0F

Type: RO

Reset: 0x05

Description:

[7:4] **Reserved**

[3] EA_TW
1: EA thermal warning

[2] EA_PD
1: EA power-down

[1] EA_FT
1: EA is in fault

[0] **EA_TS**
1: EA is in 3-state

POWST1 Status register for CMOS bridge

7	6	5	4	3	2	1	0
Reserved	CB_PD	CB_FT[2:0]			CB_TS[2:0]		

Address: 0x10

Type: RO

Reset: 0x47

Description:

[7] **Reserved**

[6] CB_PD
1: CMOS bridge is in power-down

[5:3] CB_FT[2:0]
xx1: CMOS bridge channel 1 is in fault
x1x: CMOS bridge channel 2 is in fault
1xx: CMOS bridge channel 3 is in fault

[2:0] CB_TS[2:0]
xx1: CMOS bridge channel 1 is in 3-state
x1x: CMOS bridge channel 2 is in 3-state
1xx: CMOS bridge channel 3 is in 3-state

PWMO1CFG0

7	6	5	4	3	2	1	0
AZPLS_1	TERNARY_1	HALFB_1	MP_ZERO_1	MIN_PLS_1[3:0]			

Address: 0x11

Type: RW

Reset: 0x20

Description:

[7] AZPLS_1
1: avoid zero pulse

[6] TERNARY_1
1: ternary modulation

[5] HALFB_1
1: 1B is modulated as null signal

[4] MP_ZERO_1
1: apply the minimum pulse settings also for values near 0

[3:0] MIN_PLS_1[3:0]
minimum pulse length = clock period * (MIN_PLS_1 + 1)

PWMO1CFG1

7	6	5	4	3	2	1	0
PM_1A[1:0]		PS_1A[5:0]					

Address: 0x12

Type: RW

Reset: 0x00

Description: Configuration for PWM-A

[7:6] **PM_1A[1:0]:** PWM mode
00: generate a rising edge using a down carrier
01: generate a falling edge using an up carrier
10: hybrid mode: alternation of modes 00 and 01
11: hybrid mode: alternation of modes 01 and 00

[5:0] PS_1A[5:0]: PWM shift
The PWM waveform could be shifted by (PS_1A * clock period / 64)

PWMO1CFG2

7	6	5	4	3	2	1	0
PM_1B[1:0]		PS_1B[5:0]					

Address: 0x13

Type: RW

Reset: 0x48

Description: Configuration for PWM-B

[7:6] PM_1B[1:0]: PWM mode
00: generate a rising edge using a down carrier
01: generate a falling edge using an up carrier
10: ibrid mode: alternation of modes 00 and 01
11: ibrid mode: alternation of modes 01 and 00

[5:0] PS_1B[5:0]: PWM shift
The PWM waveform could be shifted by (PS_1B * clock period / 64)

PWMO2CFG0

7	6	5	4	3	2	1	0
AZPLS_2	TERNARY_2	HALFB_2	MP_ZERO_2	MIN_PLS_2[3:0]			

Address: 0x14

Type: RW

Reset: 0x20

Description:

[7] AZPLS_2
1: avoid zero pulse

[6] TERNARY_2
1: ternary modulation

[5] HALFB_2
1: 2B is modulated as null signal

[4] MP_ZERO_2
1: apply the minimum pulse settings also for values near 0

[3:0] MIN_PLS_2[3:0]
Minimum pulse length = clock period * (MIN_PLS_2 + 1)

PWMO2CFG1

7	6	5	4	3	2	1	0
PM_2A[1:0]		PS_2A[5:0]					

Address: 0x15

Type: RW

Reset: 0x10

Description:

[7:6] **PM_2A[1:0]:** PWM mode
00: generate a rising edge using a down carrier
01: generate a falling edge using an up carrier
10: hybrid mode: alternation of modes 00 and 01
11: hybrid mode: alternation of modes 01 and 00

[5:0] PS_2A[5:0]: PWM shift
The PWM waveform could be shifted by (PS_2A * clock period / 64)

PWMO2CFG2

7	6	5	4	3	2	1	0
PM_2B[1:0]		PS_2B[5:0]					

Address: 0x16

Type: RW

Reset: 0x58

Description:

[7:6] **PM_2B[1:0]:** PWM mode
00: generate a rising edge using a down carrier
01: generate a falling edge using an up carrier
10: hybrid mode: alternation of modes 00 and 01
11: hybrid mode: alternation of modes 01 and 00

[5:0] PS_2B[5:0]: PWM shift
The PWM waveform could be shifted by (PS_2B * clock period / 64)

PWMO3CFG0

7	6	5	4	3	2	1	0
AZPLS_3	TERNARY_3	HALFB_3	MP_ZERO_3	MIN_PLS_3[3:0]			

Address: 0x17

Type: RW

Reset: 0x00

Description:

[7] AZPLS_3
1: avoid zero pulse

[6] TERNARY_3
1: ternary modulation

[5] HALFB_3
1: 3B is modulated as null signal

[4] MP_ZERO_3
1: apply the minimum pulse settings also for values near 0

[3:0] MIN_PLS_3[3:0]
Minimum pulse length = clock period * (MIN_PLS_3 + 1)

PWMO3CFG1

7	6	5	4	3	2	1	0
PM_3A[1:0]		PS_3A[5:0]					

Address: 0x18

Type: RW

Reset: 0x20

Description:

[7:6] **PM_3A[1:0]:** PWM mode
00: generate a rising edge using a down carrier
01: generate a falling edge using an up carrier
10: hybrid mode: alternation of modes 00 and 01
11: hybrid mode: alternation of modes 01 and 00

[5:0] PS_3A[5:0]: PWM shift
The PWM waveform could be shifted by (PS_3A * clock period / 64)

PWMO3CFG2

7	6	5	4	3	2	1	0
PM_3B[1:0]		PS_3B[5:0]					

Address: 0x19

Type: RW

Reset: 0x68

Description:

[7:6] **PM_3B[1:0]:** PWM mode
00: generate a rising edge using a down carrier
01: generate a falling edge using an up carrier
10: hybrid mode: alternation of modes 00 and 01
11: hybrid mode: alternation of modes 01 and 00

[5:0] PS_3B[5:0]: PWM shift
The PWM waveform could be shifted by (PS_3B * clock period / 64)

PWMO4CFG0

7	6	5	4	3	2	1	0
AZPLS_4	TERNARY_4	HALFB_4	MP_ZERO_4	MIN_PLS_4[3:0]			

Address: 0x1A

Type: RW

Reset: 0x00

Description:

[7] AZPLS_4
1: avoid zero pulse

[6] TERNARY_4
1: ternary modulation

[5] HALFB_4
1: 4B is modulated as null signal

[4] MP_ZERO_4
1: apply the minimum pulse settings also for values near 0

[3:0] MIN_PLS_4[3:0]
Minimum pulse length = clock period * (MIN_PLS_4 + 1)

PWMO4CFG1

7	6	5	4	3	2	1	0
PM_4A[1:0]		PS_4A[5:0]					

Address: 0x1B

Type: RW

Reset: 0x30

Description:

[7:6] **PM_4A[1:0]:** PWM mode
00: generate a rising edge using a down carrier
01: generate a falling edge using an up carrier
10: hybrid mode: alternation of modes 00 and 01
11: hybrid mode: alternation of modes 01 and 00

[5:0] PS_4A[5:0]: PWM shift
The PWM waveform could be shifted by (PS_4A * clock period / 64)

PWMO4CFG2

7	6	5	4	3	2	1	0
PM_4B[1:0]		PS_4B[5:0]					

Address: 0x1C

Type: RW

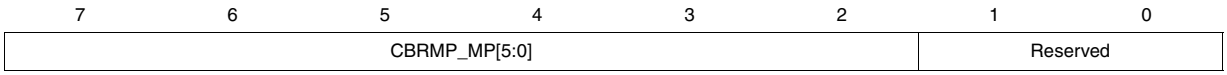
Reset: 0x78

Description:

[7:6] **PM_4B[1:0]:** PWM mode
00: generate a rising edge using a down carrier
01: generate a falling edge using an up carrier
10: hybrid mode: alternation of modes 00 and 01
11: hybrid mode: alternation of modes 01 and 00

[5:0] PS_4B[5:0]: PWM shift
The PWM waveform could be shifted by (PS_4B * clock period / 64)

CB_PFRAMP1



Address: 0x20

Type: RW

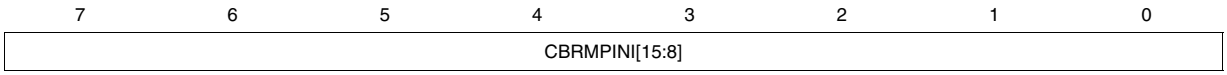
Reset: 0x14

Description:

[7:2] CBRMP_MP[5:0]
Minimum pulse width of the PDM signal

[1:0] Reserved

CB_PFRAMP2



Address: 0x21

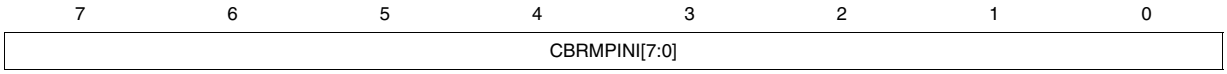
Type: RW

Reset: 0x80

Description: Initial value of the ramp signal

[7:0] CBRMPINI[15:8]
MSBs of CB ramp init

CB_PFRAMP3



Address: 0x22

Type: RW

Reset: 0x3C

Description:

[7:0] CBRMPINI[7:0]
LSBs of CB ramp init

CB_PFRAMP4

7	6	5	4	3	2	1	0
CBTIM_RMP[3:0]				Reserved			

Address: 0x23

Type: RW

Reset: 0x10

Description:

[7:4] CBTIM_RMP[3:0]
EA timing duration of the ramp (= slope)

[3:0] Reserved

CB_PFRAMP5

7	6	5	4	3	2	1	0
CBRMPTH[15:8]							

Address: 0x24

Type: RW

Reset: 0x14

Description: During the ramp, if the signal is below the threshold, the signal is modulated with PDM, otherwise with PWM

[7:0] CBRMPTH[15:8]
MSBs of CB ramp threshold

CB_PFRAMP6

7	6	5	4	3	2	1	0
CBRMPTH[7:0]							

Address: 0x25

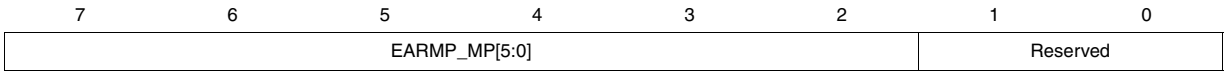
Type: RW

Reset: 0x00

Description: During the ramp, if the signal is below the threshold, the signal is modulated with PDM, otherwise with PWM

[7:0] CBRMPTH[7:0]
LSBs of CB ramp threshold

EA_PFRAMP1



Address: 0x26

Type: RW

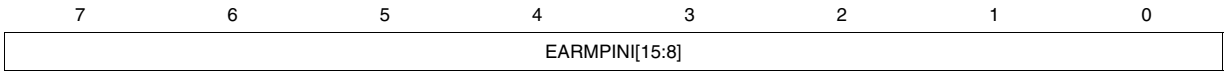
Reset: 0x1C

Description:

[7:2] EARMP_MP[5:0]
Minimum pulse width of the PDM signal

[1:0] Reserved

EA_PFRAMP2



Address: 0x27

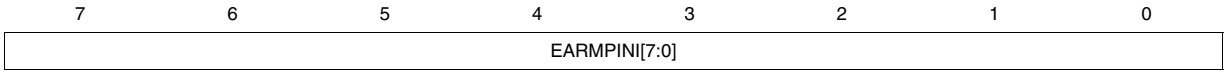
Type: RW

Reset: 0x80

Description: Initial value of the ramp signal

[7:0] EARMPINI[15:8]
MSBs of EA ramp init

EA_PFRAMP3



Address: 0x28

Type: RW

Reset: 0x60

Description:

[7:0] EARMPINI[7:0]
LSBs of EA ramp init

EA_PFRAMP4

7	6	5	4	3	2	1	0
EATIM_RMP[3:0]				Reserved			

Address: 0x29

Type: RW

Reset: 0x10

Description:

[7:4] EATIM_RMP[3:0]
EA timing duration of the ramp (= slope)

[3:0] Reserved

EA_PFRAMP5

7	6	5	4	3	2	1	0
EARMPTH[15:8]							

Address: 0x2A

Type: RW

Reset: 0x80

Description: During the ramp, if the signal is below the threshold, the signal is modulated with PDM, otherwise with PWM

[7:0] EARMPTH[15:8]
MSBs of EA ramp threshold

EA_PFRAMP6

7	6	5	4	3	2	1	0
EARMPTH[7:0]							

Address: 0x2B

Type: RW

Reset: 0x60

Description: During the ramp, if the signal is below the threshold, the signal is modulated with PDM, otherwise with PWM

[7:0] EARMPTH[7:0]
LSBs of EA ramp threshold

SRC1STATE

7	6	5	4	3	2	1	0
SRC1_BYP[1:0]		SRC_1_LOCK	SRC1_FISFO[4:0]				

Address: 0x30

Type: RO

Reset: 0x8F

Description: Values of f_S based on the 96 kHz as output frequency

[7:6] SRC1_BYP[1:0]
00: input signal has f_S < 78 kHz
10: input signal has f_S > 81 kHz

[5] SRC_1_LOCK
0: SRC target frequency not reached
1: SRC1 target frequency reached

[4:0] SRC1_FISFO[4:0]
MSB Fs_input / Fs_output

SRC2STATE

7	6	5	4	3	2	1	0
SRC1_BYP[1:0]		SRC_1_LOCK	SRC1_FISFO[4:0]				

Address: 0x31

Type: RO

Reset: 0x8F

Description:

[7:6] SRC2_BYP[1:0]
00: Input Signal has f_S < 78 kHz
10: Input Signal has f_S > 81 kHz

[5] SRC_2_LOCK
0: SRC target frequency not reached
1: SRC1 target frequency reached

[4:0] SRC2_FISFO[4:0]
MSB Fs_input / Fs_output

I2CB0_TOP

7	6	5	4	3	2	1	0
I2CB0[23:16]							

Address: 0x51

Type: RW

Reset: 0x00

Description:

[7:0] I2CB0[23:16]
MSBs of coefficient b0

I2CB0_MID

7	6	5	4	3	2	1	0
I2CB0[15:8]							

Address: 0x52

Type: RW

Reset: 0x00

Description:

[7:0] I2CB0[15:8]
Middle bits of coefficient b0

I2CB0_BOT

7	6	5	4	3	2	1	0
I2CB0[7:0]							

Address: 0x53

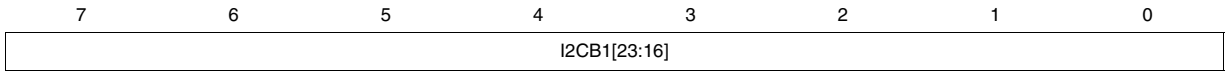
Type: RW

Reset: 0x00

Description:

[7:0] I2CB0[7:0]
LSBs of coefficient b0

I2CB1_TOP



Address: 0x54

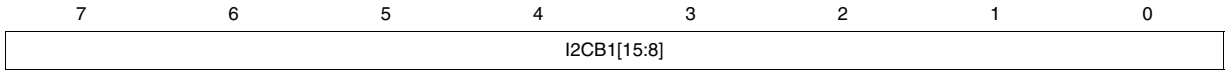
Type: RW

Reset: 0x00

Description:

[7:0] I2CB1[23:16]
MSBs of coefficient b1

I2CB1_MID



Address: 0x55

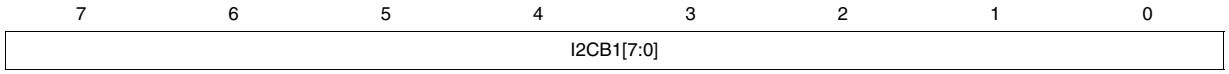
Type: RW

Reset: 0x00

Description:

[7:0] I2CB1[15:8]
Middle bits of coefficient b1

I2CB1_BOT



Address: 0x56

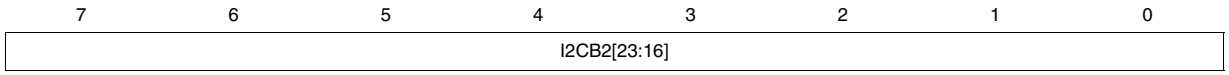
Type: RW

Reset: 0x00

Description:

[7:0] I2CB1[7:0]
LSBs of coefficient b1

I2CB2_TOP



Address: 0x57

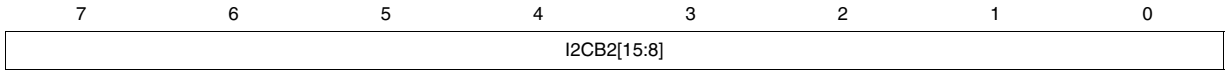
Type: RW

Reset: 0x00

Description:

[7:0] I2CB2[23:16]
MSBs of coefficient b2

I2CB2_MID



Address: 0x58

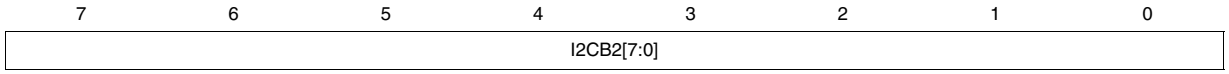
Type: RW

Reset: 0x00

Description:

[7:0] I2CB2[15:8]
Middle bits of coefficient b2

I2CB2_BOT



Address: 0x59

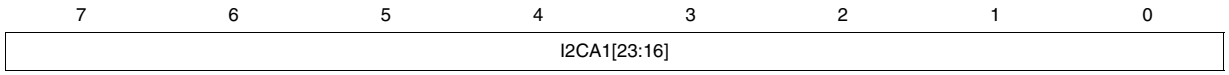
Type: RW

Reset: 0x00

Description:

[7:0] I2CB2[7:0]
LSBs of coefficient b2

I2CA1_TOP



Address: 0x5A

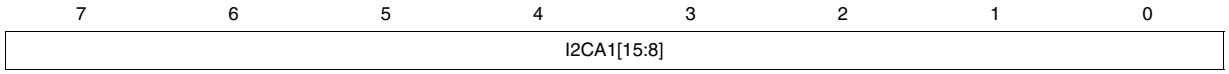
Type: RW

Reset: 0x00

Description:

[7:0] I2CA1[23:16]
MSBs of coefficient a1

I2CA1_MID



Address: 0x5B

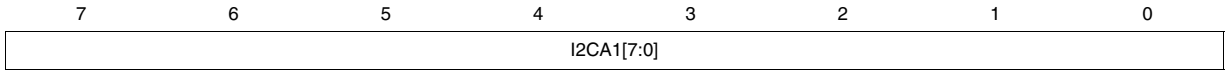
Type: RW

Reset: 0x00

Description:

[7:0] I2CA1[15:8]
Middle bits of coefficient a1

I2CA1_BOT



Address: 0x5C

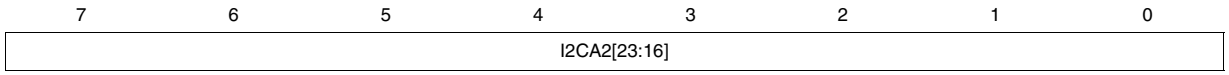
Type: RW

Reset: 0x00

Description:

[7:0] I2CA1[7:0]
LSBs of coefficient a1

I2CA2_TOP



Address: 0x5D

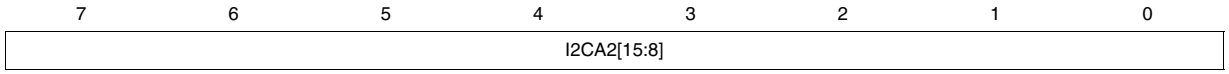
Type: RW

Reset: 0x00

Description:

[7:0] I2CA2[23:16]
MSBs of coefficient a2

I2CA2_MID



Address: 0x5E

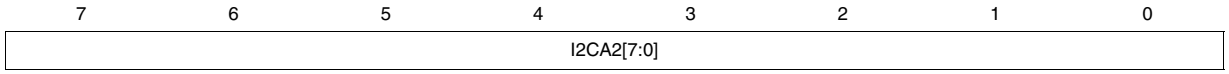
Type: RW

Reset: 0x00

Description:

[7:0] I2CA2[15:8]
Middle bits of coefficient a2

I2CA2_BOT



Address: 0x5F

Type: RW

Reset: 0x00

Description:

[7:0] I2CA2[7:0]
LSBs of coefficient a2

PROCCTRL

7	6	5	4	3	2	1	0
Reserved				RA	Reserved	WA	W1

Address: 0x60

Type: RO

Reset: 0x00

Description:

[7:4] **Reserved**

[3] RA
1: read all the biquad coefficients

[2] Reserved

[1] WA
1: write/update all the biquad coefficients

[0] W1
1: write/update the b0 coefficient

START_ADDR2

7	6	5	4	3	2	1	0
Reserved							I2CSTART_A8

Address: 0x61

Type: RW

Reset: 0x00

Description:

[7:1] Reserved

[0] I2CSTART_A8
Base address of the biquadratic to be updated (= address of coefficient b0)

START_ADDR1

7	6	5	4	3	2	1	0
I2CSTART_A7_A0							

Address: 0x62

Type: RW

Reset: 0x00

Description:

[7:0] I2CSTART_A7_A0
Base address of the biquadratic to be updated (= address of the b0 coefficient)

ROM_REMAP

7	6	5	4	3	2	1	0
Reserved	ENAB_PRE3	ENAB_PRE2	ENAB_PRE1	ENAB_PRE0	ENAB_POST	ENAB_PRMIX	ENAB_DELAY

Address: 0x6F

Type: RW

Reset: 0x00

Description:

[7] **Reserved**

[6] ENAB_PRE3
0: pre scale value of channel 3 taken from RAM
1: pre scale value of channel 3 taken from ROM

[5] ENAB_PRE2
0: pre scale value of channel 2 taken from RAM
1: pre scale value of channel 2 taken from ROM

[4] ENAB_PRE1
0: pre scale value of channel 1 taken from RAM
1: pre scale value of channel 1 taken from ROM

[3] ENAB_PRE0
0: pre scale value of channel 0 taken from RAM
1: pre scale value of channel 0 taken from ROM

[2] ENAB_POST
0: post mix values taken from RAM
1: post mix values taken from ROM

[1] ENAB_PRMIX
0: pre mix values taken from RAM
1: pre mix values taken from ROM

[0] ENAB_DELAY
0: Delay values taken from RAM
1: Delay values taken from ROM

BYP_EN_CH0

7	6	5	4	3	2	1	0
Reserved							

Address: 0x70

Type: RW

Reset: 0x00

Description:

[7:0] **Reserved**

EFFS_EN_CH0

7	6	5	4	3	2	1	0
Reserved						EROM09	EROM08

Address: 0x71

Type: RW

Reset: 0x00

Description:

[7:2] **Reserved**

[1] EROM09
1: enable de-emphasis EQ on channel 0

[0] EROM08
1: enable high-pass filter on channel 0

BYP_EN_CH1

7	6	5	4	3	2	1	0
Reserved							

Address: 0x72

Type: RW

Reset: 0x00

Description:

[7:0] **Reserved**

EFFS_EN_CH1

7	6	5	4	3	2	1	0
Reserved						EROM19	Reserved

Address: 0x73

Type: RW

Reset: 0x00

Description:

[7:2] **Reserved**

[1] EROM19
1: enable de-emphasis EQ on channel 1

[0] Reserved

BYP_EN_CH2

7	6	5	4	3	2	1	0
Reserved							

Address: 0x74

Type: RW

Reset: 0x00

Description:

[7:0] Reserved

EFFS_EN_CH2

7	6	5	4	3	2	1	0
Reserved						EROM29	EROM28

Address: 0x75

Type: RW

Reset: 0x00

Description:

[7:2] **Reserved**

[1] EROM29
1: enable de-emphasis EQ on channel 2

[0] EROM28
1: enable high-pass filter on channel 2

BYP_EN_CH3

7	6	5	4	3	2	1	0
Reserved							

Address: 0x76

Type: RW

Reset: 0x00

Description:

[7:0] **Reserved**

EFFS_EN_CH3

7	6	5	4	3	2	1	0
Reserved						EROM39	Reserved

Address: 0x77

Type: RW

Reset: 0x00

Description:

[7:2] **Reserved**

[1] EROM39
1: enable de-emphasis EQ on channel 3

[0] Reserved

BASS_SEL0_R

7	6	5	4	3	2	1	0
Reserved		BASS_EN0	BASS_SEL0				

Address: 0x78

Type: RW

Reset: 0x00

Description:

[7:6] Reserved

[5] BASS_EN0
0: Bass EQ of channel 0 is not active
1: Bass EQ of channel 0 is active

[4:0] BASS_SEL0
Select the gain of the bass filter from -12 dB (00000) to +12 dB using *Table 35* below

BASS_SEL1_R

7	6	5	4	3	2	1	0
Reserved		BASS_EN1	BASS_SEL1				

Address: 0x79

Type: RW

Reset: 0x00

Description:

[7:6] Reserved

[5] BASS_EN1
0: Bass EQ of channel 1 is not active
1: Bass EQ of channel 1 is active

[4:0] BASS_SEL1
Select the gain of the bass filter from -12 dB (00000) to +12 dB using *Table 35* below

BASS_SEL2_R

7	6	5	4	3	2	1	0
Reserved		BASS_EN2	BASS_SEL2				

Address: 0x7A

Type: RW

Reset: 0x00

Description:

[7:6] Reserved

[5] BASS_EN2
0: Bass EQ of channel 2 is not active
1: Bass EQ of channel 2 is active

[4:0] BASS_SEL2
Select the gain of the bass filter from -12 dB (00000) to +12 dB using *Table 35* below

BASS_SEL3_R

7	6	5	4	3	2	1	0
Reserved		BASS_EN3	BASS_SEL3				

Address: 0x7B

Type: RW

Reset: 0x00

Description:

[7:6] Reserved

[5] BASS_EN3
0: Bass EQ of channel 3 is not active
1: Bass EQ of channel 3 is active

[4:0] BASS_SEL3
Select the gain of the bass filter from -12 dB (00000) to +12 dB using *Table 35* below

TREB_SEL0_R

7	6	5	4	3	2	1	0
Reserved		TREB_EN0	TREB_SEL0				

Address: 0x7C

Type: RW

Reset: 0x00

Description:

[7:6] Reserved

[5] TREB_EN0
0: Treble EQ of channel 0 is not active
1: Treble EQ of channel 0 is active

[4:0] TREB_SEL0
Select the gain of the treble filter from -12 dB (00000) to +12 dB using *Table 35* below

TREB_SEL1_R

7	6	5	4	3	2	1	0
Reserved		TREB_EN1	TREB_SEL1				

Address: 0x7D

Type: RW

Reset: 0x00

Description:

[7:6] Reserved

[5] TREB_EN1
0: Treble EQ of channel 1 is not active
1: Treble EQ of channel 1 is active

[4:0] TREB_SEL1
Select the gain of the treble filter from -12 dB (00000) to +12 dB using *Table 35* below

TREB_SEL2_R

7	6	5	4	3	2	1	0
Reserved		TREB_EN2	TREB_SEL2				

Address: 0x7E

Type: RW

Reset: 0x00

Description:

[7:6] Reserved

[5] TREB_EN2
0: Treble EQ of channel 2 is not active
1: Treble EQ of channel 2 is active

[4:0] TREB_SEL2
Select the gain of the treble filter from -12 dB (00000) to +12 dB using *Table 35* below

TREB_SEL3_R

7	6	5	4	3	2	1	0
Reserved		TREB_EN3	TREB_SEL3				

Address: 0x7F

Type: RW

Reset: 0x00

Description:

[7:6] Reserved

[5] TREB_EN3
0: Treble EQ of channel 3 is not active
1: Treble EQ of channel 3 is active

[4:0] TREB_SEL3
Select the gain of the treble filter from -12 dB (00000) to +12 dB using *Table 35* below

Table 35. Bass/treble filter gains used in register addresses 0x78 - 0x7F

BASS_SELx TREBLE_SELx	Gain	BASS_SELx TREBLE_SELx	Gain
11000	+12	-	-
10111	+11	01011	-01
10110	+10	01010	-02
10101	+09	01001	-03
10100	+08	01000	-04
10011	+07	00111	-05
10010	+06	00110	-06
10001	+05	00101	-07
10000	+04	00100	-08
01111	+03	00011	-09
01110	+02	00010	-10
01101	+01	00001	-11
01100	+00	00000	-12

SATCH0CFG1

7	6	5	4	3	2	1	0
SAT_EQ	SAT_CH0[22:16]						

Address: 0x90

Type: RW

Reset: 0xFF

Description:

[7] SAT_EQ
0: saturation value of every channel is independent
1: all the channels take the saturation value of channel 0

[6:0] SAT_CH0[22:16]
MSBs of the absolute saturation value for channel 0.
If the signal is above SAT_CH0[22:0] then it is truncated

SATCH0CFG2

7	6	5	4	3	2	1	0
SAT_CH0[15:8]							

Address: 0x91

Type: RW

Reset: 0xFF

Description:

[7:0] SAT_CH0[15:8]
Middle bits of the saturation value for channel 0
If the signal is above SAT_CH0[22:0] then it is truncated

SATCH0CFG3

7	6	5	4	3	2	1	0
SAT_CH0[7:0]							

Address: 0x92

Type: RW

Reset: 0xFF

Description:

[7:0] SAT_CH0[7:0]
LSBs of the saturation value for channel 0
If the signal is above SAT_CH0[22:0] then it is truncated

SATCH1CFG1

7	6	5	4	3	2	1	0
Reserved	SAT_CH1[22:16]						

Address: 0x93

Type: RW

Reset: 0x00

Description:

[7] Reserved

[6:0] SAT_CH1[22:16]
MSBs of the absolute saturation value for channel 1.
If the signal is above SAT_CH1[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

SATCH1CFG2

7	6	5	4	3	2	1	0
SAT_CH1[15:8]							

Address: 0x94

Type: RW

Reset: 0x00

Description:

[7:0] SAT_CH1[15:8]
Middle bits of the saturation value for channel 1
If the signal is above SAT_CH1[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

SATCH1CFG3

7	6	5	4	3	2	1	0
SAT_CH1[7:0]							

Address: 0x95

Type: RW

Reset: 0x00

Description:

[7:0] SAT_CH1[7:0]
LSBs of the saturation value for channel 1
If the signal is above SAT_CH1[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

SATCH2CFG1

7	6	5	4	3	2	1	0
Reserved	SAT_CH2[22:16]						

Address: 0x96

Type: RW

Reset: 0x00

Description:

[7] Reserved

[6:0] SAT_CH2[22:16]
MSBs of the absolute saturation value for channel 2.
If the signal is above SAT_CH2[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

SATCH2CFG2

7	6	5	4	3	2	1	0
SAT_CH2[15:8]							

Address: 0x97

Type: RW

Reset: 0x00

Description:

[7:0] SAT_CH2[15:8]
Middle bits of the saturation value for channel 2
If the signal is above SAT_CH2[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

SATCH2CFG3

7	6	5	4	3	2	1	0
SAT_CH2[7:0]							

Address: 0x98

Type: RW

Reset: 0x00

Description:

[7:0] SAT_CH2[7:0]
LSBs of the saturation value for channel 2
If the signal is above SAT_CH2[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

SATCH3CFG1

7	6	5	4	3	2	1	0
Reserved	SAT_CH3[22:16]						

Address: 0x99

Type: RW

Reset: 0x00

Description:

[7] Reserved

[6:0] SAT_CH3[22:16]
MSBs of the absolute saturation value for channel 3.
If the signal is above SAT_CH3[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

SATCH3CFG2

7	6	5	4	3	2	1	0
SAT_CH3[15:8]							

Address: 0x9A

Type: RW

Reset: 0x00

Description:

[7:0] SAT_CH3[15:8]
Middle bits of the saturation value for channel 3
If the signal is above SAT_CH3[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

SATCH3CFG3

7	6	5	4	3	2	1	0
SAT_CH3[7:0]							

Address: 0x9B

Type: RW

Reset: 0x00

Description:

[7:0] SAT_CH3[7:0]
LSBs of the saturation value for channel 3
If the signal is above SAT_CH3[22:0] then it is truncated, see also register bit *SATCH0CFG1*[7]

VOLCFG

7	6	5	4	3	2	1	0
SVOL_ON3	SVOL_ON2	SVOL_ON1	SVOL_ON0	TIM_SVOL			

Address: 0xA0

Type: RW

Reset: 0xF5

Description: The register sets up the soft volume control

[7] SVOL_ON3
0: volume on channel 3 is updated immediately
1: volume on channel 3 is updated gradually with a ramp

[6] SVOL_ON2
0: volume on channel 2 is updated immediately
1: volume on channel 2 is updated gradually with a ramp

[5] SVOL_ON1
0: volume on channel 1 is updated immediately
1: volume on channel 1 is updated gradually with a ramp

[4] SVOL_ON0
0: volume on channel 0 is updated immediately
1: volume on channel 0 is updated gradually with a ramp

[3:0] TIM_SVOL
Set the volume ramp; each volume step (0.5 dB) takes (2^{TIM_SVOL} / f_S) s

MVOL Master volume control

7	6	5	4	3	2	1	0
MVOL							

Address: 0xA1

Type: RW

Reset: 0x00

Description:

[7:0] MVOL
Master volume from 0 dB to -127.5 dB in 0.5 dB steps (volume = MVOL * 0.5 dB)

VOLCH0 Channel 0 volume control

7	6	5	4	3	2	1	0
CVOL0							

Address: 0xA2

Type: RW

Reset: 0x48

Description:

[7:0] CVOL0
Channel 0 volume 36 dB to -91.5 dB in 0.5 dB steps

VOLCH1 Channel 1 volume control

7	6	5	4	3	2	1	0
CVOL1							

Address: 0xA3

Type: RW

Reset: 0x48

Description:

[7:0] CVOL1
Channel 1 volume 36 dB to -91.5 dB in 0.5 dB steps

VOLCH2 Channel 2 volume control

7	6	5	4	3	2	1	0
CVOL2							

Address: 0xA4

Type: RW

Reset: 0x48

Description:

[7:0] CVOL2
Channel 2 volume 36 dB to -91.5 dB in 0.5 dB steps

VOLCH3 Channel 3 volume control

7	6	5	4	3	2	1	0
CVOL3							

Address: 0xA5

Type: RW

Reset: 0x48

Description:

[7:0] CVOL3
Channel 3 volume 36 dB to -91.5 dB in 0.5 dB steps

SAI_IN1_CFG0

7	6	5	4	3	2	1	0
S2P1_B_STR	S2P1_LR_L	Reserved	S2P1_MSB	S2P1_DFM			S2P1_MMD

Address: 0xB0

Type: RW

Reset: 0xD2

Description:

[7] S2P1_B_STR
BICLK strobe
0: active_edge = rising, strb_edge = falling
1: active_edge = falling, strb_edge = rising

[6] S2P1_LR_L
LRCLK strobe
0: left = 0, right = 1
1: left = 1, right = 0

[5] Reserved

[4] S2P1_MSB
MSB first

[3:1] S2P1_DFM[2:0]
Data format
000: left justified
001: I^2S
010: right justified
100: PCM no-delay
101: PCM delay
111: DSP

[0] S2P1_MMD
Master mode

SAI_IN1_CFG1

7	6	5	4	3	2	1	0
S2P1_DLEN		S2P1_BOS		S2P1_MAP_L		S2P1_MAP_R	

Address: 0xB1

Type: RW

Reset: 0x91

Description:

[7:6] S2P1_DLEN
Data length
00: 8 bits
01: 16 bits
10: 24 bits
11: 32 bits

[5:4] S2P1_BOS
BICLK_OS
00: BICLK = 32 * f_S
01: BICLK = 64 * f_S
10: BICLK = 128 * f_S
11: BICLK = 256 * f_S

[3:2] S2P1_MAP_L
Map left
00: slot 0
01: slot 1
10: slot 2
11: slot 3

[1:0] S2P1_MAP_R
Map right
00: slot 0
01: slot 1
10: slot 2
11: slot 3

SAI_OUT_CFG0

7	6	5	4	3	2	1	0
P2S_B_STR	P2S_LR_L	SDATAO_ACT	P2S_MSB	P2S_DFM			P2S_MMD

Address: 0xB2

Type: RW

Reset: 0xD3

Description:

[7] P2S_B_STR
BICLK strobe
0: active_edge = rising, strb_edge = falling
1: active_edge = falling, strb_edge = rising

[6] P2S_LR_L
LRCLK strobe
0: left = 0, right = 1
1: left = 1, right = 0

[5] SDATA0_ACT
0: normal behavior
1: SDATAO is disabled

[4] P2S_MSB
MSB first

[3:1] P2S_DFM[2:0]
Data format
000: left justified
001: I^2S
010: right justified
100: PCM no-delay
101: PCM delay
111: DSP

[0] P2S_MMD
Master mode

SAI_OUT_CFG1

7	6	5	4	3	2	1	0
P2S_DLEN		P2S_BOS		P2S_MAP_L		P2S_MAP_R	

Address: 0xB3

Type: RW

Reset: 0x91

Description:

[7:6] P2S_DLEN
Data length
00: 08 bits
01: 16 bits
10: 24 bits
11: 32 bits

[5:4] P2S_BOS
BICLK_OS
00: BICLK = 32 * f_S
01: BICLK = 64 * f_S
10: BICLK = 128 * f_S
11: BICLK = 256 * f_S

[3:2] P2S_MAP_L
Map left
00: slot 0
01: slot 1
10: slot 2
11: slot 3

[1:0] P2S_MAP_R
Map right
00: slot 0
01: slot 1
10: slot 2
11: slot 3

SAI_IN2_CFG0

7	6	5	4	3	2	1	0
S2P2_B_STR	S2P2_LR_L	Reserved	S2P2_MSB	S2P2_DFM			S2P2_MMD

Address: 0xB4

Type: RW

Reset: 0xD2

Description:

[7] S2P2_B_STR
BICLK strobe
0: active_edge = rising, strb_edge = falling
1: active_edge = falling, strb_edge = rising

[6] S2P2_LR_L
LRCLK strobe
0: left = 0, right = 1
1: left = 1, right = 0

[5] Reserved

[4] S2P2_MSB
MSB first

[3:1] S2P2_DFM[2:0]
Data format
000: left justified
001: I^2S
010: right justified
100: PCM no-delay
101: PCM delay
111: DSP

[0] S2P2_MMD
Master mode

SAI_IN2_CFG1

7	6	5	4	3	2	1	0
S2P2_DLEN		S2P2_BOS		S2P2_MAP_L		S2P2_MAP_R	

Address: 0xB5

Type: RW

Reset: 0x91

Description:

[7:6] S2P2_DLEN
Data length
00: 8 bits
01: 16 bits
10: 24 bits
11: 32 bits

[5:4] S2P2_BOS
BICLK_OS
00: BICLK = 32 * f_S
01: BICLK = 64 * f_S
10: BICLK = 128 * f_S
11: BICLK = 256 * f_S

[3:2] S2P2_MAP_L
Map left
00: slot 0
01: slot 1
10: slot 2
11: slot 3

[1:0] S2P2_MAP_R
Map right
00: slot 0
01: slot 1
10: slot 2
11: slot 3

AUIFSHARE

7	6	5	4	3	2	1	0
Reserved						SHARE_BILR	

Address: 0xB6

Type: RW

Reset: 0x00

Description:

[7:2] Reserved

[1:0] SHARE_BILR

00: no clock sharing

01: SAI_in1, SAI_in2 share the clocks: BICLKI1 and LRCLKI1 (others are not used)
SAI1: can be master/slave (see config)
SAI2: always slave

10: SAI_in1, SAI_in2, SAI_out share the clocks: BICLKI1 and LRCLKI1 (others arenot used)
SAI_out: can be master/slave (see config)
SAI1 and SAI2: always slave

11: no clock sharing

SRCINSEL

7	6	5	4	3	2	1	0
SRC1_INSEL		SRC2_INSEL		MUTE_SRCU	Reserved		

Address: 0xB7

Type: RW

Reset: 0x28

Description:

[7:6] SRC1_INSEL

Sample rate converter IN channels 0 and 1:

00: serial audio interface IN 1

01: ADC

1x: serial audio interface IN 2

[5:4] SRC2_INSEL

Sample rate converter IN channels 2 and 3:

00: serial audio interface IN 1

01: ADC

1x: serial audio interface IN 2

[3] MUTE_SRCU0:

1: The device will be put in mute if the SRC is not locked at the 96 kHz sample frequency

[2:0] Reserved

P2SDATA

7	6	5	4	3	2	1	0
Reserved	P2S_HFS	P2S1_DSEL			P2S2_DSEL		

Address: 0xB8

Type: RW

Reset: 0x00

Description:

[7] Reserved

[6] P2S_HFS
SAI OUT:
0: 96 kHz
1: half processing frequency (48 kHz)

[5:3] P2S1_DSEL
SAI OUT 1
000: ADC
001: SAI IN 1
010: SAI IN 2
011: SRC channels 0-1
100: SRC channels 2-3
101: processing channels 0 - 1
110: processing channels 2 - 3

[2:0] P2S2_DSEL
SAI OUT 2
000: ADC
001: SAI IN 1
010: SAI IN 2
011: SRC channels 0-1
100: SRC channels 2-3
101: processing channels 0 - 1
110: processing channels 2 - 3

PLLCFG0

7	6	5	4	3	2	1	0
PLL_DPROG	PLL_FR_CTRL	PLL_DDIS		PLL_IDF			

Address: 0xC0

Type: RW

Reset: 0x00

Description:

[7] 0: PLL takes the internal settings
1: PLL takes the register settings

[6] PLL_FR_CTRL
0: fractional frequency synthesis disabled
1: fractional frequency synthesis enabled

[5:4] PLL_DDIS
PLL dither disable
x0: triangular PDF dither input enabled
x1: triangular PDF dither input disabled
0x: rectangular PDF dither input enabled
1x: rectrangular PDF dither input disabled

[3:0] PLL_IDF
Set the input division factor of the PLL (see *Section 5.3: Fractional PLL on page 31*)

PLLCFG1

7	6	5	4	3	2	1	0
PLL_FRAC[15:8]							

Address: 0xC1

Type: RW

Reset: 0x00

Description: See also *Section 5.3: Fractional PLL on page 31*

[7:0] PLL_FRAC[15:8]
The MSBs of PLL_FRAC[15:0] which is used to set the PLL multiplication factor

PLLCFG2

7	6	5	4	3	2	1	0
PLL_FRAC[7:0]							

Address: 0xC2

Type: RW

Reset: 0x00

Description: See also *Section 5.3: Fractional PLL on page 31*

[7:0] PLL_FRAC[7:0]
The LSBs of PLL_FRAC[15:0] which is used to set the PLL multiplication factor

PLLCFG3

7	6	5	4	3	2	1	0
PLL_STRB	PLL_STRBBYP	PLL_NDIV					

Address: 0xC3

Type: RW

Reset: 0x00

Description: See also *Section 5.3: Fractional PLL on page 31*

[7] PLL_STRB
0: normal behaviour
1: asynchronous strobe input, a new configuration input is loaded into the fraction controller

[6] PLL_STRBBYP
0: normal behaviour
1: bypass the strobe signal

[5:0] PLL_NDIV
Set the PLL multiplication factor (integral part), loop division factor (LDF)

PLLPFE

7	6	5	4	3	2	1	0
PLL_BYP_UNL	BICLK2PLL	PLL_PWDN	PLL_NOPDDIV	Reserved			

Address: 0xC4

Type: RW

Reset: 0x80

Description:

[7] PLL_BYP_UNL
0: PLL clock is not bypassed if it is unlock
1: PLL clock is bypassed if it is unlock, the external clock is used as system clock

[6] BICLK2PLL
PLL clock in selection
0: normal behaviour
1: BICLKI1 is used as PLL clock source

[5] PLL_PWDN
0: normal behaviour
1: PLL goes into power-down mode

[4] PLL_NOPDDIV
0: PLL goes to power-down when the divider settings are changed
1: PLL remains active when the divider settings are changed

[3:0] Reserved

PLLST PLL status

7	6	5	4	3	2	1	0
PLL_UNLOCK	PLL_PWD_ST	PLL_BYP_ST	Reserved				

Address: 0xC5

Type: RO

Reset: 0x00

Description:

[7] PLL_UNLOCK
0: normal behaviour
1: PLL is not locked

[6] PLL_PWD_ST
0: normal behaviour
1: PLL is in power-down mode

[5] PLL_BYP_ST
0: PLL is selected
1: PLL is bypassed

[4:0] Reserved

ADCCFG0

7	6	5	4	3	2	1	0
ADC_PGA			ADC_INSEL	ADC_STBY	ADC_BYPCAL	CLK_ADC_ON	Reserved

Address: 0xC6

Type: RW

Reset: 0x00

Description:

[7:5] ADC_PGA
Programmable gain amplifier:
000: 0 dB
001: +6 dB
010: +12 dB
011: +18 dB
100: +24 dB
101: +30 dB
110: +36 dB
111: +42 dB

[4] ADC_INSEL
0: line input mode selected
1: mike input mode selected

[3] ADC_STBY
0: ADC normal mode
1: ADC standby mode for power reduction

[2] ADC_BYPCAL
0: DC-removal block enabled
1: bypass DC-removal block

[1] CLK_ADC_ON
0: ADC clock disabled
1: ADC clock active

[0] Reserved

CKOCFG

7	6 5	4	3	2	1	0
CLKOUT_DIS	CLKOUT_SEL	CLK_FFX_ON	CLK_SRC_ON	CLK_PROC_ON	EAPWM_DIS	PWM00ACT

Address: 0xC7

Type: RW

Reset: 0x1C

Description:

[7] CLKOUT_DIS
0: CLKOUT is enabled
1: CLKOUT is disabled

[6:5] CLKOUT_SEL
00: system clock / 4
01: system clock / 2
10: system clock / 4
11: system clock / 8

[4] CLK_FFX_ON
0: FFX clock disabled
1: FFX clock active

[3] CLK_SRC_ON
0: sample rate converter clock disabled
1: sample rate converter clock active

[2] CLK_PROC_ON
0: process block clock disabled
1: process block clock active

[1] EAPWM_DIS
0: EA PWM output is enable
1: EA PWM output is disabled

[0] PWM00ACT
0: output PWM00 is at logical 0
1: Output PWM00 is active

MISC

7	6	5	4	3	2	1	0
OSC_DIS	S2P_FS_RNG			ADC_FS_RNG		Reserved	CLK_CORE_ON

Address: 0xC8

Type: RW

Reset: 0x20

Description:

[7] OSC_DIS
0: normal behaviour
1: XT oscillator is disabled

[6:4] S2P_FS_RNG
Serial audio interface sampling frequency, f_S, range:
000: 8 - 12 kHz (very low)
001: 16 - 24 kHz (low)
010: 32 - 48 kHz (normal)
011: 64 - 96 kHz (high)
100: 128 - 192 kHz (very high)

[3:2] ADC_FS_RNG
ADC sampling frequency, f_S, range:
00: 32 - 48 kHz (normal)
01: 16 - 24 kHz (low)
1x: 8 - 12 kHz (very low)

[1] Reserved

[0] CLK_CORE_ON
0: core clock disabled
1: core clock active

PLLB

7	6	5	4	3	2	1	0
PLL_BYP	Reserved	ADC_CLKSEL	Reserved	P2S1_CLKSEL	Reserved	P2S2_CLKSEL	Reserved

Address: 0xC9

Type: RW

Reset: 0x80

Description: See also *Figure 11: Clock management scheme on page 29*

[7] PLL_BYP
0: PLL not bypassed
1: PLL bypassed

[6] Reserved

[5] ADC_CLKSEL
0: clk_adc / 4
1: pll_clk_in

[4] Reserved

[3] P2S1_CLKSEL
0: processing clock
1: pll_clk_in

[2] Reserved

[1] P2S2_CLKSEL
0: processing clock
1: pll_clk_in

[0] Reserved

HPDET1

7	6	5 4	3	2 1 0
HPD_SEL	HPD_POL	HPD_ACT_MODE	HPD_HPMOD	HPD_TIM_F

Address: 0xCA

Type: RW

Reset: 0x40

Description:

[7] HPD_SEL
Select the headphone detection threshold
0: HP1
1: HP2

[6] HPD_POL
Polarity of the detection signal

[5:4] HPD_ACT_MODE
Action to be done in case of detection:
00: inactive
01: mute EA and un-mute CB
10: 3-state EA and un-3-state CB
11: power-down EA and power-up CB

[3] HPD_HPMOD
0: normal behaviour
1: FFX is in headphone modulation mode

[2:0] HPD_TIM_F
000: 1.33 ms
001: 2.66 ms
010: 5.33 ms
011: 10.66 ms
100: 21.33 ms
101: 42.66 ms
110: 85.33 ms
111: 170.67 ms

HPDET2

7	6	5	4	3	2	1	0
E_HP2	E_HP1	TUD_EN	Reserved			E_HPDET1	E_HPDET2

Address: 0xCB

Type: RW

Reset: 0xC0

Description:

[7] E_HP2
0: headphone detection 2 is disabled
1: headphone detection 2 is enabled

[6] E_HP1
0: headphone detection 1 is disabled
1: headphone detection 1 is enabled

[5] TUD_EN
1: disable the pull-up resistor of the headphones detector

[4:2] Reserved

[1] E_HPDET1
Headphone 1 detector line (not filtered)

[0] E_HPDET2
Headphone 2 detector line (not filtered)

HPDST Headphone detection status

7	6	5	4	3	2	1	0
HPD_DET_FILT	Reserved						

Address: 0xCC

Type: RO

Reset: 0x00

Description:

[7] HPD_DET_FILT
0: no headphones
1: headphones detected

[6:0] Reserved

STBY_MODES

7	6	5	4	3	2	1	0
PAD_PULLDIS	Reserved					CMP_EN_N	DC_STBY_EN_N

Address: 0xCD

Type: RW

Reset: 0x00

Description:

[7] PAD_PULLDIS
0: Enable the pull (up/down) of the pads
1: Disable the pull (up/down) of the pads

[6:2] Reserved

[1] CMP_EN_N
0: compensation cell is active
1: compensation cell goes into power-down mode when pin STBY is asserted

[0] DC_STBY_EN_N
0: DC regulators are active
1: DC regulators go into power-down mode when pin STBY is asserted

ADCCFG1 ADC analog input selection

7	6	5	4	3	2	1	0
ADC_ANA_SEL		Reserved					

Address: 0xCE

Type: RW

Reset: 0x00

Description:

[7:6] ADC_ANA_SEL
00: INL1, INR1
01: INL2, INR2
1x: reserved

[5:0] Reserved

PFEFAULT

7	6	5	4	3	2	1	0
Reserved			PFE1	PFE2	PFE3	RESET_EA_FT	RESET_CB_FT

Address: 0xCF

Type: RW

Reset: 0x00

Description:

[7:5] Reserved

[4] PFE1
0: analog pop free disabled on bridge output 1
1: analog pop free enabled bridge output 1

[3] PFE2
0: analog pop free disabled on bridge output 2
1: analog pop free enabled bridge output 2

[2] PFE3
0: analog pop free disabled on bridge output 3
1: analog pop free enabled bridge output 3

[1] RESET_EA_FT
0: normal operation
1: reset register bit *POWST*[1]

[0] RESET_CB_FT
0: normal operation
1: reset register bits *POWST1*[5:3]

BISTRUN0 BIST control

7	6	5	4	3	2	1	0
SF1_BRUN	SF2_BRUN	SS1_BRUN	SS2_BRUN	CF_BRUN	PR_BRUN	CF_ROM_BRUN	Reserved

Address: 0xD0

Type: RW

Reset: 0x00

Description:

[7] SF1_BRUN
SRC1 RAM
0: normal functional mode
1: start the BIST

[6] SF2_BRUN
SRC2 RAM
0: normal functional mode
1: start the BIST

[5] SS1_BRUN
SRC1 RAM
0: normal functional mode
1: start the BIST

[4] SS2_BRUN
SRC2 RAM
0: normal functional mode
1: start the BIST

[3] CF_BRUN
PROC RAM (coefficients)
0: normal functional mode
1: start the BIST

[2] PR_BRUN
PROC RAM (program)
0: normal functional mode
1: start the BIST

[1] CF_ROM_BRUN
PROC RAM (coefficients)
0: normal functional mode
1: start the BIST

[0] Reserved

BISTRUN1

7	6	5	4	3	2	1	0
OS_BRUN	DB_BRUN	Reserved					

Address: 0xD1

Type: RW

Reset: 0x00

Description:

[7] OS_BRUN
FFX RAM
0: normal functional mode
1: start the BIST

[6] DB_BRUN
FFX RAM
0: normal functional mode
1: start the BIST

[5:0] Reserved

BISTST0 BIST status register 0

7	6	5	4	3	2	1	0
SF1_BEND	SF1_BBAD	SF1_BFAIL	SF2_BEND	SF2_BBAD	SF2_BFAIL	SS1_BEND	SS1_BBAD

Address: 0xD2

Type: RO

Reset: 0x00

Description:

[7] SF1_BEND:
For SRC1 RAM BIST
0: normal functional mode
1: BIST is finished

[6] SF1_BBAD
For SRC1 RAM BIST
0: no faults detected
1: at least one fault detected

[5] SF1_BFAIL
For SRC1 RAM BIST
0: no faults detected in the current location
1: at least one fault detected in the current location

[4] SF2_BEND
For SRC2 RAM BIST
0: normal functional mode
1: BIST is finished

[3] SF2_BBAD
For SRC2 RAM BIST
0: no faults detected
1: at least one fault detected

[2] SF2_BFAIL
For SRC2 RAM BIST
0: no faults detected in the current location
1: at least one fault detected in the current location

[1] SS1_BEND
For SRC1 RAM BIST
0: normal functional mode
1: BIST is finished

[0] SS1_BBAD
For SRC1 RAM BIST
0: no faults detected
1: at least one fault detected

BISTST1 BIST status register 1

7	6	5	4	3	2	1	0
SS1_BFAIL	SS2_BEND	SS2_BBAD	SS2_BFAIL	CF_BEND	CF_BBAD	CF_BFAIL	PR_BEND

Address: 0xD3

Type: RO

Reset: 0x00

Description:

[7] SS1_BFAIL
For SRC1 RAM BIST
0: no faults detected in the current location
1: at least one fault detected in the current location

[6] SS2_BEND:
For SRC2 RAM BIST
0: normal functional mode
1: BIST is finished

[5] SS2_BBAD
For SRC2 RAM BIST
0: no faults detected
1: at least one fault detected

[4] SS2_BFAIL
For SRC2 RAM BIST
0: no faults detected in the current location
1: at least one fault detected in the current location

[3] CF_BEND:
For PROC RAM BIST
0: normal functional mode
1: BIST is finished

[2] CF_BBAD
For PROC RAM BIST
0: no faults detected
1: at least one fault detected

[1] CF_BFAIL
For PROC RAM BIST
0: no faults detected in the current location
1: at least one fault detected in the current location

[0] PR_BEND:
For PROC RAM BIST
0: normal functional mode
1: BIST is finished

BISTST2 BIST status register 2

7	6	5	4	3	2	1	0
PR_BBAD	PR_BFAIL	OS_BEND	OS_BBAD	OS_BFAIL	DB_BEND	DB_BBAD	DB_BFAIL

Address: 0xD4

Type: RO

Reset: 0x00

Description:

[7] PR_BBAD
For PROC RAM BIST
0: no faults detected
1: at least one fault detected

[6] PR_BFAIL
For PROC RAM BIST
0: no faults detected in the current location
1: at least one fault detected in the current location

[5] OS_BEND:
For FFX RAM BIST
0: normal functional mode
1: BIST is finished

[4] OS_BBAD
For FFX RAM BIST
0: no faults detected
1: at least one fault detected

[3] OS_BFAIL
For FFX RAM BIST
0: no faults detected in the current location
1: at least one fault detected in the current location

[2] DB_BEND:
For FFX RAM BIST
0: normal functional mode
1: BIST is finished

[1] DB_BBAD
For FFX RAM BIST
0: no faults detected
1: at least one fault detected

[0] DB_BFAIL
For FFX RAM BIST
0: no faults detected in the current location
1: at least one fault detected in the current location

BISTST3 BIST status register 3

7	6	5	4	3	2	1	0
CF_ROM_BEND	Reserved						

Address: 0xD5

Type: RO

Reset: 0x00

Description:

[7] CF_ROM_BEND
ROM BIST computation is finished

[6:0] Reserved

ROMSIGN0 ROM BIST signature (LSBs)

7	6	5	4	3	2	1	0
CF_ROMS[7:0]							

Address: 0xD6

Type: RO

Reset: 0x00

Description:

[7:0] CF_ROMS[7:0]
LSBs of ROM BIST signature CF_ROMS[23:0]

ROMSIGN1 ROM BIST signature (middle bits)

7	6	5	4	3	2	1	0
CF_ROMS[15:8]							

Address: 0xD7

Type: RO

Reset: 0x00

Description:

[7:0] CF_ROMS[15:8]
Middle bits of ROM BIST signature CF_ROMS[23:0]

ROMSIGN2 ROM BIST signature (MSBs)

7	6	5	4	3	2	1	0
CF_ROMS[23:16]							

Address: 0xD8

Type: RO

Reset: 0x00

Description:

[7:0] CF_ROMS[23:16]
MSBs of ROM BIST signature CF_ROMS[23:0]

DEBUG0

7	6	5	4	3	2	1	0
DBGCKO_ON	DBGCKO_VAL						

Address: 0xD9

Type: RW

Reset: 0x00

Description:

[7] DBGCKO_ON
0: normal behaviour
1: CLKOUT exports internal clocks as defined by bits DBGCKO_VAL

[6:0] DBGCKO_VAL
0x00: invalid_inp_fbk
0x01: mute_int_fbk
0x02: binss_fbk
0x21: debug_start
0x22: debug_data_end
0x23: debug_data_ok
0x24: debug_lrclk_old
0x25: debug_biclk
0x40: clk_proc
0x41: clk_src
0x42: clk_ffx
0x50: src_1_lock
0x51: src_2_lock
0x52: src_1_bypass_state[0]
0x53: src_1_bypass_state[1]
0x54: src_2_bypass_state[0]
0x55: src_2_bypass_state[1]
0x56: pwm_sync
0x57: s2p_1_bad_clocks
0x58: s2p_2_bad_clocks
0x59: s2p_1_missing_biclk
all other values: no clock exported

PADST0 Pad status 0

7	6	5	4	3	2	1	0
PAD_RSTN	Reserved	PAD_SCL	PAD_SDA	PAD_I2CDIS	Reserved		PAD_STBY

Address: 0xF0

Type: RO

Reset: 0xA0

Description:

[7] PAD_RSTN

[6] Reserved

[5] PAD_SCL

[4] PAD_SDA

[3] PAD_I2CDIS

[2:1] Reserved

[0] PAD_STBY

PADST1

7	6	5	4	3	2	1	0
PAD_MUTE	PAD_BICLKI	PAD_LRCLKI	PAD_SDATAI	PAD_BICLKO	PAD_LRCLKO	Reserved	

Address: 0xF1

Type: RW

Reset: 0x74

Description:

[7] PAD_MUTE

[6] PAD_BICLKI

[5] PAD_LRCLKI

[4] PAD_SDATAI

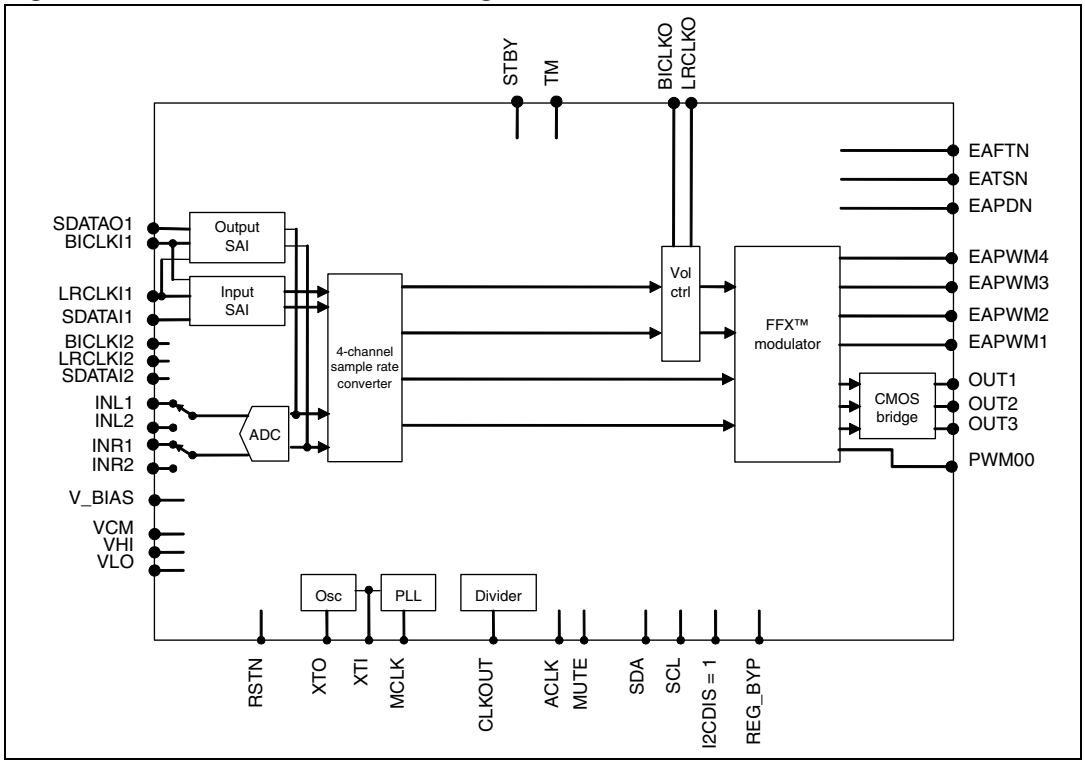
[3] PAD_BICLKO

[2] PAD_LRCLKO

[1:0] Reserved

15 I²C disabled (microless) mode

Figure 55. Microless mode block diagram



In microless mode (I2CDIS = 1) the I²C interface is inhibited and SDA and SCL are used as static inputs. The device is working in the configuration shown in *Figure 55* with the ADC connected to input line 1 and to SAI out. The processing chain uses the inputs from SAI input 1. The working modes are selected via the logical levels on the inputs SDA, SCL as follows:

- SCL = 0 : CMOS bridge outputs come from digital input serial audio interface;
  SCL = 1 : CMOS bridge outputs come from analog ADC input.
- SDA = 0 : external amplifier outputs come from digital input serial audio interface;
  SDA = 1 : external amplifier outputs come from analog ADC input.

At power-up the channel volume is set to -60 dB. The volume is controlled by pulsing the inputs LRCLKO and BICLKO as follows:

- when pulsing LRCLKO = 1 and BICLKO = 1 simultaneously the channel volume is set to 0 dB.
- Any LRCLKO = 1 pulse causes a channel volume decrease of 0.5 dB.
- Any BICLKO = 1 pulse causes a channel volume increase of 0.5 dB.

The channel volume change applies only to the external amplifier.

The digital output serial audio interface is always fed with the result of the ADC conversion with no volume control (line-out mode). It is in master mode when SCL = 1 and SDA = 1 otherwise it is in slave mode. It is configured in I²S format.

The LRCLK and BICLK signals are shared between input and output SAI.

The input sampling frequency must be between 32 kHz and 48 kHz and the master clock input (MCLK or XTI) must be 256 * f_S.

The CMOS bridge FFX output is configured in line-out mode:

- left channel binary on OUT1
- right channel binary on OUT2
- zero signal binary (duty cycle 50%) on OUT3
- pop-free digital ramp active
- volume control not effective (always 0 dB)
- switching frequency 384 kHz.

The external amplifier FFX output is configured in BTL mode:

- left channel BTL (new ternary modulation) on EAPWM1 and EAPWM2
- right channel BTL (new ternary modulation) on EAPWM1 and EAPWM2
- volume control is effective
- switching frequency 384 kHz.

The headphone detection is disabled.

The CLKOUT pad is active at the PLL frequency of 2048 * f_S.

16 Package mechanical data

The STA321 comes in a 64-pin, 10 mm x 10 mm, LQFP, exposed pad down (EPD) package. The reference number is JEDEC MS-026-BCD-HD.

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: *www.st.com*. ECOPACK® is an ST trademark.

Figure 56. LQFP-64L EPD outline drawing

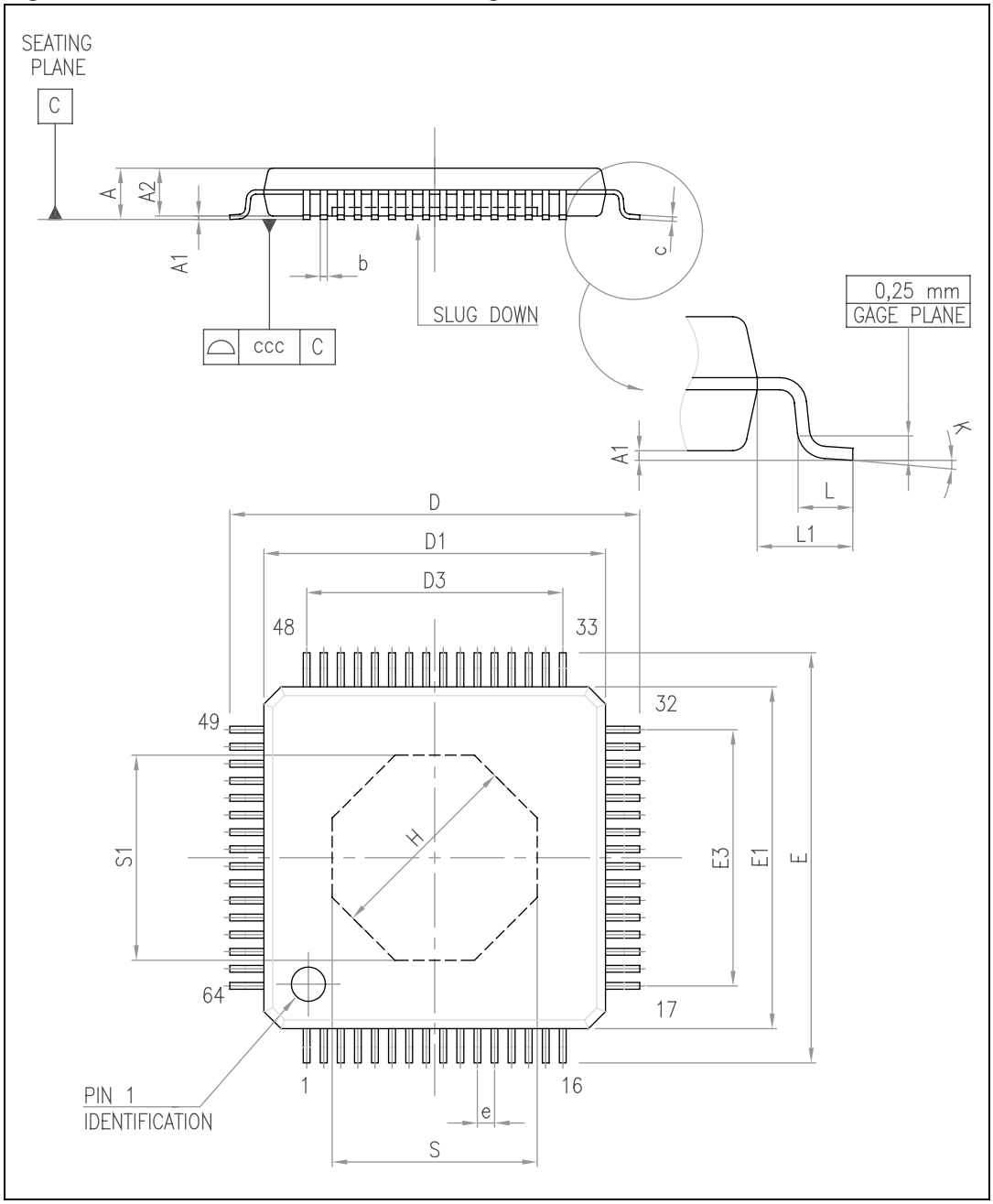


Table 36. LQFP-64L EPD dimensions

Symbol	Dimensions in mm			Dimensions in inches			Notes
	Min	Typ	Max	Min	Typ	Max	
A	-	-	1.60	-	-	0.063	-
A1	0.05	-	0.15	0.002	-	0.006	-
A2	1.35	1.40	1.45	0.053	0.055	0.057	-
b	0.17	0.22	0.27	0.007	0.009	0.011	-
c	0.09	-	0.20	0.004	-	0.008	-
D	11.80	12.00	12.20	0.465	0.472	0.480	-
D1	9.80	10.00	10.20	0.386	0.394	0.402	-
D3	-	7.50	-	-	0.295	-	-
E	11.80	12.00	12.20	0.465	0.472	0.480	-
E1	9.80	10.00	10.20	0.386	0.394	0.402	-
E3	-	7.50	-	-	0.295	-	-
e	-	0.50	-	-	0.020	-	-
H	-	5.89	-	-	0.232	-	-
L	0.45	0.60	0.75	0.018	0.024	0.030	-
L1	-	1.00	-	-	0.039	-	-
S	6.00	-	-	0.236	-	-	Exposed pad
S1	6.00	-	-	0.236	-	-	Exposed pad
ccc	-	-	0.08	-	-	0.003	-
k	0	3.5	7.0	0	3.5	7.0	Degrees

17 Glossary

Total harmonic distortion + noise (THDN)

The ratio of the RMS value of all the spectral components in the specified band (20 Hz - 20 kHz) to the RMS values of the signal fundamental component. THDN is measured at 0 dBfs input at a frequency of 1 kHz.

Signal to noise plus distortion ratio (SNDR)

Ratio between power of signal fundamental component and “noise+distortion”. It is measured at different input levels: 0 dBfs, -3 dBfs, -6 dBfs, -10 dBfs, -20 dBfs, -40 dBfs, -60 dBfs. When the signal amplitude is less than 0 dBfs, that much dB is added to obtain the final SNR. For example, if SNDR is 87 dB with -6dBfs signal, then SNR = 87 + 6 = 93 dB.

Dynamic range (DR)

Dynamic range is measured using SNDR at -60 dBfs, 1 kHz signal and adding 60 dB. For example, if SNDR with -60 dBfs is 38 dB then the dynamic range is 38 + 60 = 98 dB.

Crosstalk

Crosstalk is the measure of the inter-channel isolation between the left and right channels of a stereo system. It is measured at each output with zero input to the channel under test and a full-scale input applied to the other channel.

Deviation from linear phase

Measurement bandwidth 20 Hz to 20 kHz, f_S = 48 kHz. The measurement takes into account the combined digital and analog filter characteristics.

Pass band, pass-band ripple, stop band, stop-band attenuation

These parameters take into account both analog and digital filter characteristics. Stop-band attenuation should be measured between 0.55 * f_S and 3.45 * f_S.

18 Trademarks and other acknowledgements

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19 Revision history

Table 37. Document revision history

Date	Revision	Changes
27-Mar-2009	1	Initial release.
11-May-2009	2	Updated *Table 1: Device summary on page 1* Added ambient temperature to *Table 5: Recommended operating conditions on page 13* Updated *Table 6: Electrical specifications on page 14* Updated resistor to 32 Ω in *Figure 3: Test circuit on page 17* Updated and moved Headphone detector threshold limits table from *Chapter 12 on page 72* and merged into *Table 6: Electrical specifications on page 14* Updated HPDET2 bitfield in *Table 34: Register summary on page 77* Updated description of register *HPDET2 on page 138*
30-Oct-2009	3	Updates to feature list *on page 1* Updated *Chapter 1: Overview on page 9* Updated *Chapter 16: Package mechanical data on page 152*

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