

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

ABSOLUTE MAXIMUM RATINGS

V_{CC}, V_{CC2}-0.3V to +6V
 RS-0.3V to (V_{CC} + 0.3V)
 TXD, STBY, S, REF, RXD-0.3V to +6V
 CANH, CANL, SPLIT $\pm 80V$
 Continuous Power Dissipation (T_A = +70°C)
 8-Pin SO (derate 5.9mW/°C above +70°C)470mW

Operating Temperature Range-40°C to +125°C
 Junction Temperature+150°C
 Storage Temperature Range-65°C to +150°C
 Lead Temperature (soldering, 10s)+300°C
 Soldering Temperature (reflow)+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

(V_{CC} = +5V $\pm 5\%$, V_{CC2} = +3V to +3.6V, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at V_{CC} = +5V, V_{CC2} = +3.3V, R_L = 60 Ω , and T_A = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
V _{CC} Supply Current	I _{CC}	Dominant, R _L = 60 Ω			72	mA
		Recessive	MAX13050/MAX13052/ MAX13053		12.5	
					10	
V _{CC2} Supply Current	I _{CC2}	MAX13054, TXD = V _{CC2} or unconnected			15	μA
Standby Current	I _{STANDBY}	MAX13052			25	μA
		MAX13050/MAX13054			11	
Silent Mode	I _{SILENT}	MAX13053			12.5	mA
Thermal-Shutdown Threshold	T _{SH}			+165		°C
Thermal-Shutdown Hysteresis				13		°C
INPUT LEVELS (TXD, STBY, S)						
High-Level Input Voltage	V _{IH}		2			V
		TXD, STBY (MAX13054)	0.7 x			
Low-Level Input Voltage	V _{IL}			0.8		V
		TXD, STBY (MAX13054)		0.3 x		
High-Level Input Current	I _{IH}	V _{TXD} = V _{CC} , V _{TXD} = V _{CC2} (MAX13054)	-5		+5	μA
		V _{STBY} = V _{CC} , V _S = V _{CC} (MAX13053)	-5		+5	
Low-Level Input Current	I _{IL}	V _{TXD} = GND	-300		-100	μA
		V _{STBY} = GND, V _S = GND (MAX13053)	-10		-1	
Input Capacitance	C _{IN}			10		pF
CANH, CANL TRANSMITTER						
Recessive Bus Voltage	V _{CANH} , V _{CANL}	Normal mode, V _{TXD} = V _{CC} , no load	2		3	V
		Standby mode, no load	-100		+100	mV
Recessive Output Current	I _{CANH} , I _{CANL}	V _{CANH} , V _{CANL} = $\pm 76V$		± 3		mA
		-32V $\leq$ V _{CANH} , V _{CANL} $\leq$ +32V	-2.5		+2.5	
CANH Output Voltage	V _{CANH}	V _{TXD} = 0, dominant	3.0		4.25	V
CANL Output Voltage	V _{CANL}	V _{TXD} = 0, dominant	0.50		1.75	V
Matching Between CANH and CANL Output Voltage	Δ DOM	V _{TXD} = 0, dominant, T _A = +25°C, (V _{CANH} + V _{CANL}) - V _{CC}	-100		+150	mV

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

DC ELECTRICAL CHARACTERISTICS (continued)

($V_{CC} = +5V \pm 5\%$, $V_{CC2} = +3V$ to $+3.6V$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{CC} = +5V$, $V_{CC2} = +3.3V$, $R_L = 60\Omega$, and $T_A = +25^\circ C$.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Differential Output (V _{CANH} - V _{CANL})	V _{DIFF}	Dominant, V _{TXD} = 0, 45Ω ≤ R _L ≤ 60Ω	1.5		3.0	V
		Recessive, V _{TXD} = V _{CC} , no load	-50		+50	mV
CANH Short-Circuit Current	I _{CANHSC}	V _{CANH} = 0, V _{TXD} = 0	-100	-70	-45	mA
CANL Short-Circuit Current	I _{CANLSC}	V _{CANL} = 5V, V _{TXD} = 0	40	60	90	mA
		V _{CANL} = 40V, V _{TXD} = 0 (Note 2)	40	60	90	
		V _{CANL} = 76V, V _{TXD} = 0		63		
RXD OUTPUT LEVELS						
RXD High-Output-Voltage Level	V _{OH}	I = -100μA	0.8 x V _{CC}		V _{CC}	V
		I = -100μA (MAX13054)	0.8 x V _{CC2}		V _{CC2}	
RXD Low-Output-Voltage Level	V _{OL}	I = 5mA			0.4	V
COMMON-MODE STABILIZATION (SPLIT) and REF						
Output Voltage	V _{SPLIT}	Normal mode, -500μA ≤ I _{SPLIT} ≤ 500μA	0.3 x V _{CC}		0.7 x V _{CC}	V
Leakage Current	I _{LEAK}	Standby mode, -40V ≤ V _{SPLIT} ≤ +40V			20	μA
		Standby mode, -76V ≤ V _{SPLIT} ≤ +76V			50	
REF Output Voltage	V _{REF}	-50μA ≤ I _{REF} ≤ +50μA (MAX13053)	0.45 x V _{CC}		0.55 x V _{CC}	V
DC BUS RECEIVER (V _{TXD} = V _{CC} , CANH and CANL externally driven)						
Differential Input Voltage	V _{DIFF}	-12V ≤ V _{CM} ≤ +12V	0.5	0.7	0.9	V
		MAX13050/MAX13052/MAX13054 -12V ≤ V _{CM} ≤ +12V (standby mode)	0.50		1.15	
Differential Input Hysteresis	V _{DIFF(HYST)}	Normal mode, -12V ≤ V _{CM} ≤ +12V		70		mV
Common-Mode Input Resistance	R _{ICM}	Normal or standby mode, V _{CANH} = V _{CANL} = ±12V	15		35	kΩ
Matching Between CANH and CANL Common-Mode Input Resistance	R _{IC_MATCH}	V _{CANH} = V _{CANL}	-3		+3	%
Differential Input Resistance	R _{DIFF}	Normal or standby mode, V _{CANH} - V _{CANL} = 1V	25		75	kΩ
Common-Mode Input Capacitance	C _{IM}	V _{TXD} = V _{CC}		20		pF
Differential Input Capacitance		V _{TXD} = V _{CC}		10		pF
Input Leakage Current	I _{LI}	V _{CC} = 0, V _{CANH} = V _{CANL} = 5V	-5		+5	μA
SLOPE CONTROL RS (MAX13052)						
Input Voltage for High Speed	V _{IL_RS}				0.3 x V _{CC}	V

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

DC ELECTRICAL CHARACTERISTICS (continued)

($V_{CC} = +5V \pm 5\%$, $V_{CC2} = +3V$ to $+3.6V$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{CC} = +5V$, $V_{CC2} = +3.3V$, $R_L = 60\Omega$, and $T_A = +25^\circ C$.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Voltage for Standby	V_{IH_RS}		$0.75 \times V_{CC}$			V
Slope-Control Mode Voltage	V_{SLOPE}	$-200\mu A < I_{RS} < 10\mu A$	$0.4 \times V_{CC}$		$0.6 \times V_{CC}$	V
High-Speed Mode Current	I_{IL_RS}	$V_{RS} = 0$	-500			μA
ESD Protection		IEC 61000-4-2 Contact Discharge Method per IBEE test facility (Note 3)		± 8		kV

TIMING CHARACTERISTICS

($V_{CC} = +5V \pm 5\%$, $V_{CC2} = +3V$ to $+3.6V$, $R_L = 60\Omega$, $C_L = 100pF$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{CC} = +5V$, $V_{CC2} = +3.3V$, and $T_A = +25^\circ C$.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Delay TXD to Bus Active	t_{ONTXD}	Figure 1 (Note 4)			66	110	ns
Delay TXD to Bus Inactive	t_{OFFTXD}	Figure 1 (Note 4)	MAX13050/MAX13052/ MAX13053		61	95	ns
			MAX13054		70	110	
Delay Bus to Receiver Active	t_{ONRXD}	Figure 1 (Note 4)			54	115	ns
Delay Bus to Receiver Inactive	t_{OFFRXD}	Figure 1 (Note 4)			46	160	ns
Delay TXD to RXD Active (Dominant Loop Delay)	t_{ONLOOP}	Figure 1 (Note 4)			121	255	ns
Delay TXD to RXD Inactive (Recessive Loop Delay)	$t_{OFFLOOP}$	Figure 4 (Note 4)			108	255	ns
Delay TXD to RXD Active (Dominant Loop Delay) Slew-Rate Controlled	$t_{ONLOOP-S}$	MAX13052	$R_{RS} = 24k\Omega$ (500kbps)		280	450	ns
			$R_{RS} = 100k\Omega$ (125kbps)		0.82	1.6	μs
			$R_{RS} = 180k\Omega$ (62.5kbps)		1.37	5	
Delay TXD to RXD Inactive (Loop Delay) Slew-Rate Controlled	$t_{OFFLOOP-S}$	MAX13052	$R_{RS} = 24k\Omega$ (500kbps)		386	600	ns
			$R_{RS} = 100k\Omega$ (125kbps)		0.74	1.6	μs
			$R_{RS} = 180k\Omega$ (62.5kbps)		0.97	5	
Differential Output Slew Rate	ISRI	MAX13052	$R_{RS} = 24k\Omega$ (500kbps)		10		V/ μs
			$R_{RS} = 100k\Omega$ (125kbps)		2.7		
			$R_{RS} = 180k\Omega$ (62.5kbps)		1.6		

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

TIMING CHARACTERISTICS (continued)

($V_{CC} = +5V \pm 5\%$, $V_{CC2} = +3V$ to $+3.6V$, $R_L = 60\Omega$, $C_L = 100pF$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{CC} = +5V$, $V_{CC2} = +3.3V$, and $T_A = +25^\circ C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Dominant Time for Wake-Up with Bus	t_{WAKE}	Standby mode, $V_{DIFF} = +3V$, Figure 2	0.75	1.5	3.00	μs
Delay STBY to Normal Mode (DOMINANT)	$t_{STBY-NORM}$	$TXD = 0$ (MAX13050, MAX13054) FROM STBY falling to $CANH - CANL = 0.9V$	5		10	μs
TXD Dominant Timeout	t_{DOM}	$V_{TXD} = 0$	0.3	0.6	1.0	ms

Note 1: All currents into the device are positive, all currents out of the device are negative. All voltages are referenced to the device ground, unless otherwise noted.

Note 2: Guaranteed by design, not production tested.

Note 3: MAX13050 tested by IBEE test facility. Please contact factory for report. MAX13052/MAX13053/MAX13054 are pending ESD evaluation.

Note 4: For the MAX13052, $V_{RS} = 0$.

Timing Diagrams

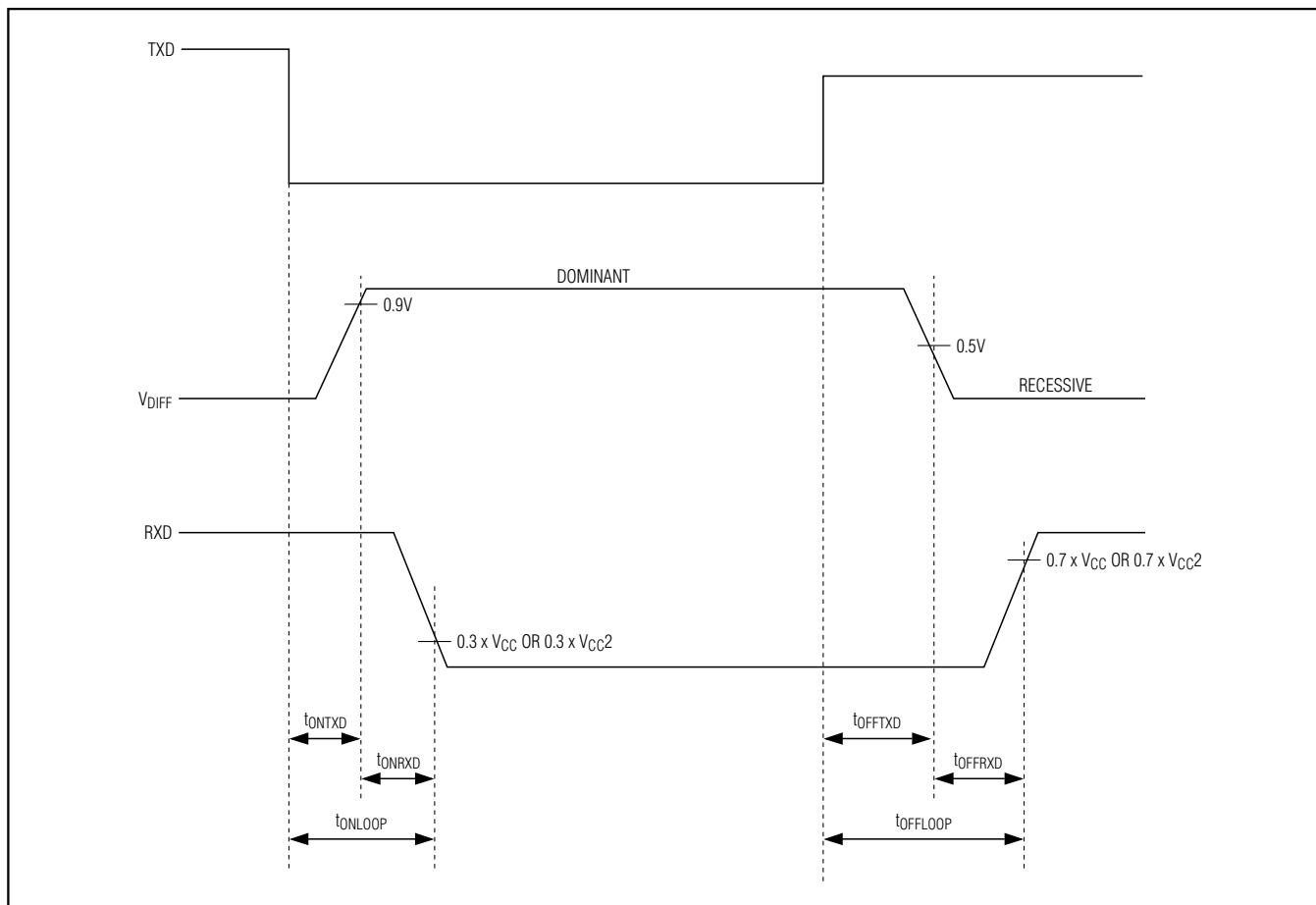


Figure 1. Timing Diagram

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

Timing Diagrams

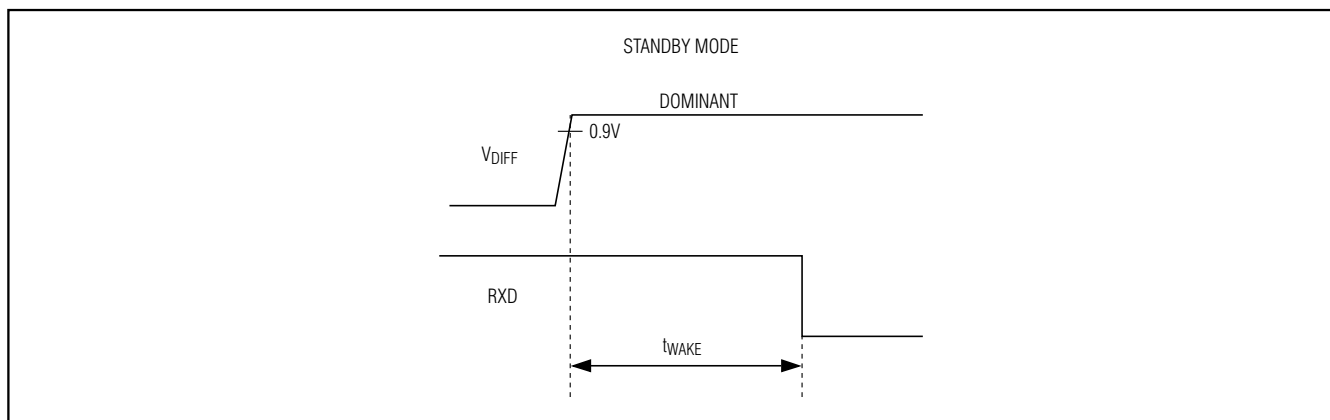
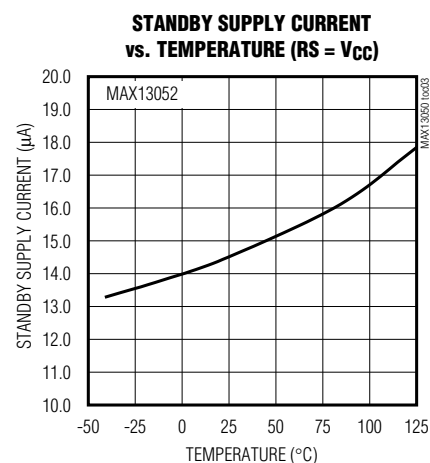
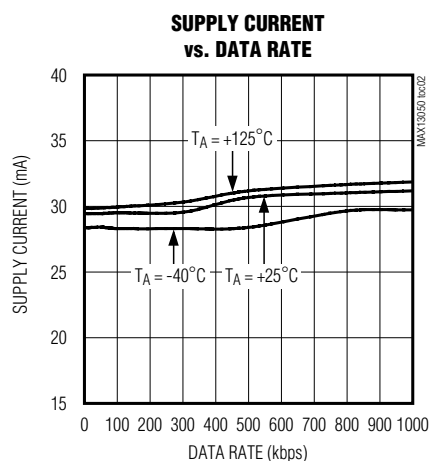
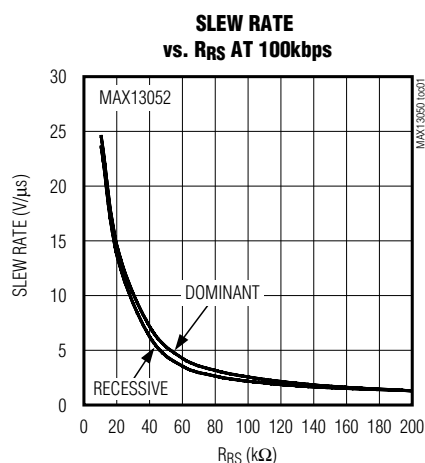


Figure 2. Timing Diagram for Standby and Wake-Up Signal

Typical Operating Characteristics

($V_{CC} = +5V$, $R_L = 60\Omega$, $C_L = 100pF$, $V_{CC2} = +3.3V$, and $T_A = +25^\circ C$, unless otherwise noted.)

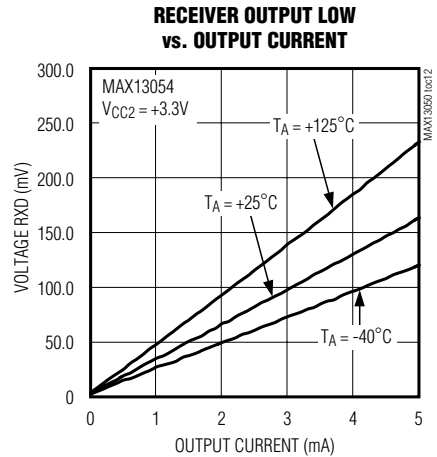
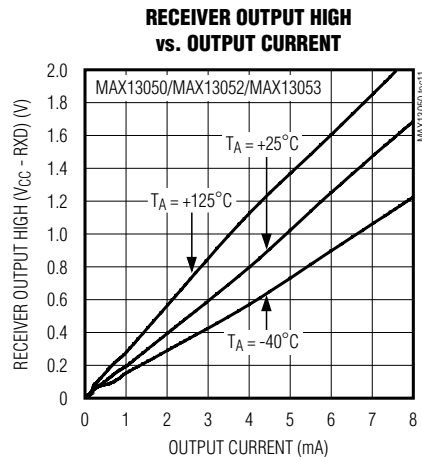
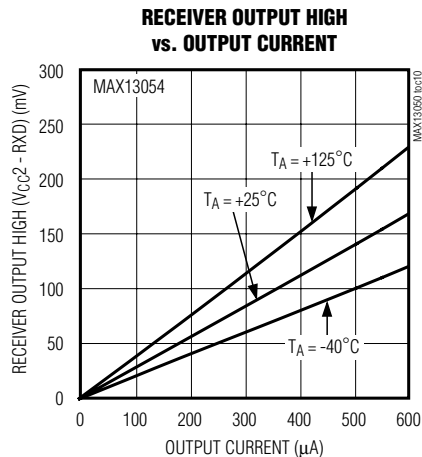
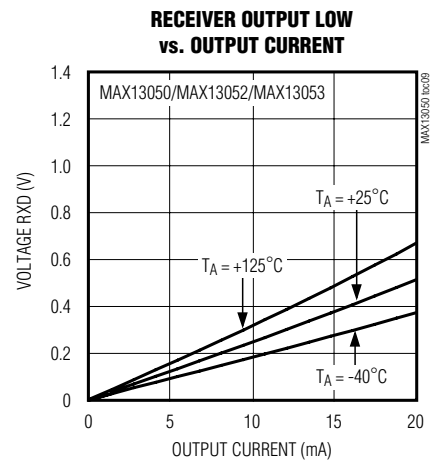
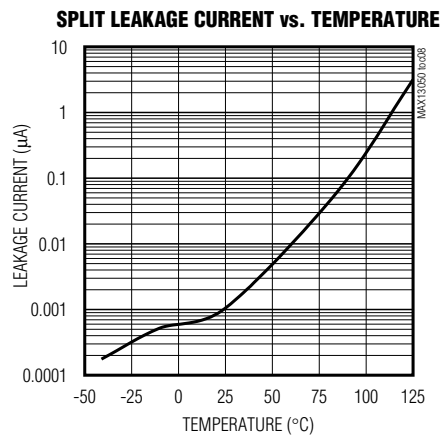
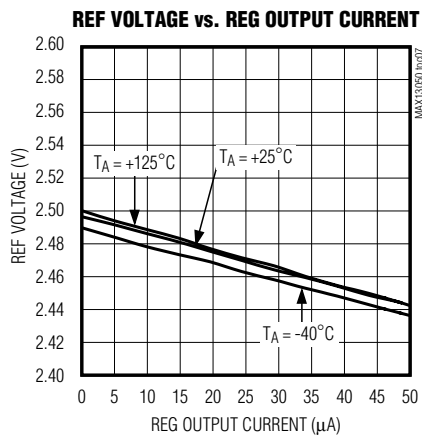
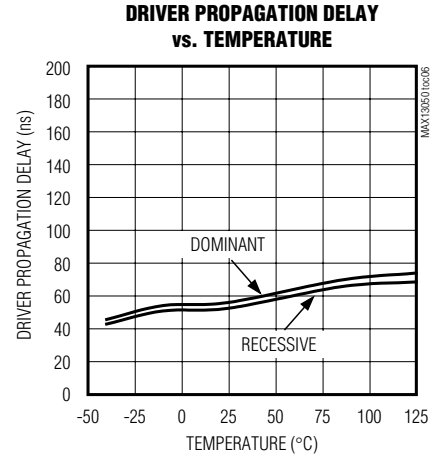
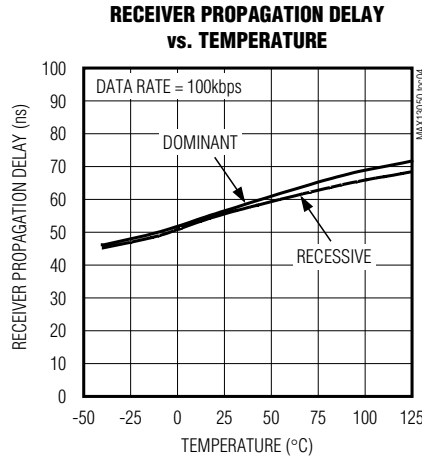
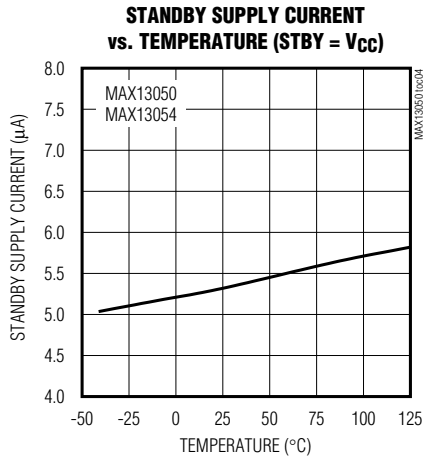


MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

Typical Operating Characteristics

($V_{CC} = +5V$, $R_L = 60\Omega$, $C_L = 100pF$, $V_{CC2} = +3.3V$, and $T_A = +25^\circ C$, unless otherwise noted.)

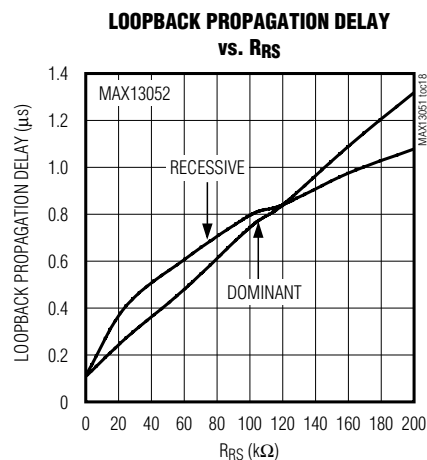
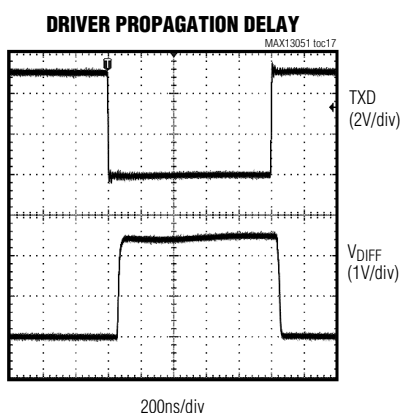
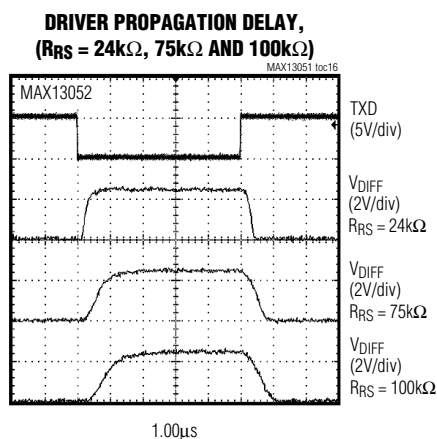
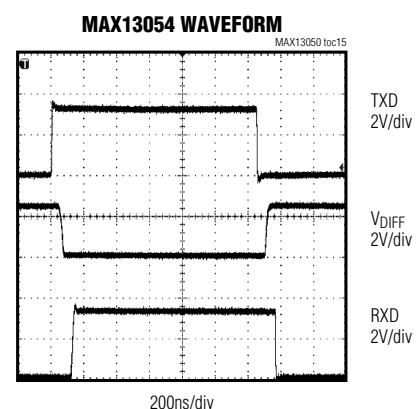
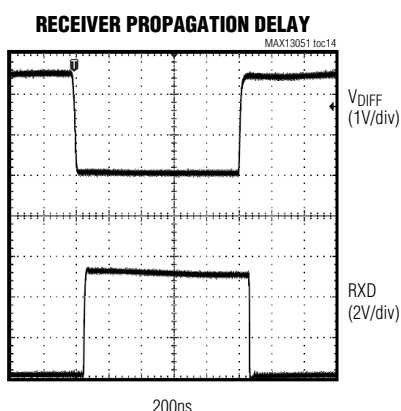
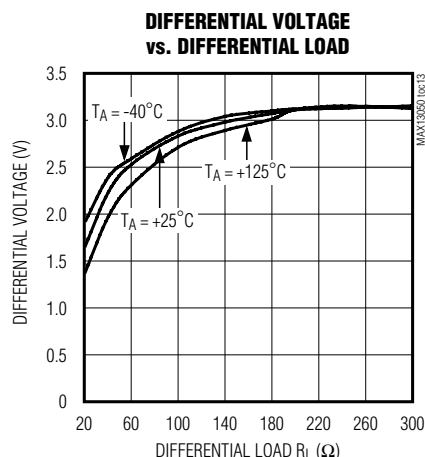


MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

Typical Operating Characteristics (continued)

($V_{CC} = +5V$, $R_L = 60\Omega$, $C_L = 100pF$, $V_{CC2} = +3.3V$, and $T_A = +25^\circ C$, unless otherwise noted.)



MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

Pin Description

PIN				NAME	FUNCTION
MAX13050	MAX13052	MAX13053	MAX13054		
1	1	1	1	TXD	Transmit Data Input. TXD is a CMOS/TTL-compatible input from a CAN controller with a $25k\Omega$ pullup to V_{CC} . For the MAX13054, TXD is pulled to V_{CC2} .
2	2	2	2	GND	Ground
3	3	3	3	V_{CC}	Supply Voltage. Bypass V_{CC} to GND with a $0.1\mu F$ capacitor.
4	4	4	4	RXD	Receive Data Output. RXD is a CMOS/TTL-compatible output from the physical bus lines CANH and CANL. For the MAX13054, RXD output voltage is referenced to the V_{CC2} supply voltage.
5	5	—	—	SPLIT	Common-Mode Stabilization Output. Output equaled to $0.5 \times V_{CC}$. SPLIT goes high impedance in standby mode.
6	6	6	6	CANL	CAN Bus-Line Low
7	7	7	7	CANH	CAN Bus-Line High
8	—	—	8	STBY	Standby Input. Drive STBY low for high-speed operation. Drive STBY high to place the device in low-current standby mode.
—	8	—	—	RS	Mode-Select Input. Drive RS low or connect to GND for high-speed operation. Connect a resistor between RS and GND to control output slope. Drive RS high to put into standby mode.
—	—	5	—	REF	Reference Output Voltage. Always on reference output voltage, set to $0.5 \times V_{CC}$.
—	—	8	—	S	Silent-Mode Input. Drive S low to enable TXD and to operate in high-speed mode. Drive S high to disable the transmitter.
—	—	—	5	V_{CC2}	Logic-Supply Input. V_{CC2} is the logic supply voltage for the input/output between the CAN transceiver and microprocessor. V_{CC2} allows fully compatible +3.3V logic on all digital lines. Bypass to GND with a $0.1\mu F$ capacitor. Connect V_{CC2} to V_{CC} for 5V logic compatibility.

Detailed Description

The MAX13050/MAX13052/MAX13053/MAX13054 $\pm 80V$ fault-protected CAN transceivers are ideal for industrial network applications where overvoltage protection is required. These devices provide a link between the CAN protocol controller and the physical wires of the bus lines in a control area network (CAN). These devices can be used for DeviceNet applications, requiring data rates up to 1Mbps.

The MAX13050/MAX13052/MAX13053/MAX13054 dominant timeout prevents the bus from being blocked

by a hungup microcontroller. If the TXD input is held low for greater than 1ms, the transmitter becomes disabled, driving the bus line to a recessive state. The MAX13054 +3.3V logic input allows the device to communicate with +3.3V logic, while operating from a +5V supply. The MAX13050 and MAX13052 provide a split DC-stabilized voltage. The MAX13053 has a reference output that can be used to bias the input of a CAN controller's differential comparator.

All devices can operate up to 1Mbps (high-speed mode). The MAX13052 slope-control feature allows the user to program the slew rate of the transmitter for data

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

rates of up to 500kbps. This reduces the effects of EMI, thus allowing the use of unshielded-twisted or parallel cable. The MAX13050/MAX13052 and MAX13054 standby mode shuts off the transmitter and switches the receiver to a low-current/low-speed state.

The MAX13050/MAX13052/MAX13053/MAX13054 input common-mode range is greater than $\pm 12V$, exceeding the ISO11898 specification of $-2V$ to $+7V$, and feature $\pm 8kV$ Contact Discharge protection, making these devices ideal for harsh industrial environments.

$\pm 80V$ Fault Protected

The MAX13050/MAX13052/MAX13053/MAX13054 feature $\pm 80V$ fault protection. This extended voltage range of CANH, CANL, and SPLIT allows use in high-voltage systems and communication with high-voltage buses.

Operating Modes

High-Speed Mode

The MAX13050/MAX13052/MAX13053/MAX13054 can achieve transmission rates of up to 1Mbps when operating in high-speed mode. Drive STBY low to operate the MAX13050 and MAX13054 in high-speed operation. Connect RS to ground to operate the MAX13052 in high-speed mode.

Slope-Control Mode (MAX13052)

Connect a resistor from RS to ground to select slope-control mode (Table 1). In slope-control mode, CANH and CANL slew rates are controlled by the resistor ($16k\Omega \leq R_{RS} \leq 200k\Omega$) connected between RS and GND. Controlling the rise and fall slopes reduces high-frequency EMI and allows the use of an unshielded-twisted pair or a parallel pair of wires as bus lines. The slew rate can be approximated using the formula below:

$$SR(V/\mu s) = \frac{250}{R_{RS}}$$

where, SR is the desired slew rate and R_{RS} is in $k\Omega$.

Standby Mode (MAX13050/MAX13052/MAX13054)

In standby mode (RS or STBY = high), the transmitter is switched off and the receiver is switched to a low-current/low-speed state. The supply current is reduced during standby mode. The bus line is monitored by a low-differential comparator to detect and recognize a wake-up event on the bus line. Once the comparator detects a dominant bus level greater than t_{WAKE} , RXD pulls low.

**Table 1. Mode Selection Truth Table
MAX13052**

CONDITION FORCED AT RS	MODE	RESULTING CURRENT AT RS
$V_{RS} \text{ or } \leq 0.3 \times V_{CC}$	High-Speed	$ I_{RS} \leq 500\mu A$
$0.4 \times V_{CC} \leq V_{RS} \leq 0.6 \times V_{CC}$	Slope Control	$10\mu A \leq I_{RS} \leq 200\mu A$
$V_{RS} \geq 0.75 \times V_{CC}$	Standby	$ I_{RS} \leq 10\mu A$

Drive STBY high for standby mode operation for the MAX13050 and MAX13054. Apply a logic-high to RS to enter a low-current standby mode for the MAX13052.

Silent Mode S (MAX13053)

Drive S high to place the MAX13053 in silent mode. When operating in silent mode, the transmitter is disabled regardless of the voltage level at TXD. RXD however, still monitors activity on the bus line.

Common-Mode Stabilization (SPLIT)

SPLIT provides a DC common-mode stabilization voltage of $0.5 \times V_{CC}$ when operating in normal mode. SPLIT stabilizes the recessive voltage to $0.5 \times V_{CC}$ for conditions when the recessive bus voltage is lowered, caused by an unsupplied transceiver in the network with a significant leakage current from the bus lines to ground. Use SPLIT to stabilize the recessive common-mode voltage by connecting SPLIT to the center tap of the split termination, see the *Typical Operating Circuit*. In standby mode or when $V_{CC} = 0$, SPLIT becomes high impedance.

Reference Output (MAX13053)

MAX13053 has a reference voltage output (REF) set to $0.5 \times V_{CC}$. REF can be utilized to bias the input of a CAN controller's differential comparator, and to provide power to external circuitry.

Transmitter

The transmitter converts a single-ended input (TXD) from the CAN controller to differential outputs for the bus lines (CANH, CANL). The truth table for the transmitter and receiver is given in Table 2.

TXD Dominant Timeout

The CAN transceivers provide a transmitter dominant timeout function that prevents erroneous CAN controllers from clamping the bus to a dominant level by a continuous low TXD signal. When the TXD remains low for the 1ms maximum timeout period, the transmitter becomes disabled, thus driving the bus line to a recessive state

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

Table 2. Transmitter and Receiver Truth Table (MAX13052)

TXD	RS	CANH	CANL	BUS STATE	RXD
Low	$V_{RS} \leq 0.75 \times V_{CC}$	High	Low	Dominant	Low
High or Open	$V_{RS} \leq 0.75 \times V_{CC}$	$V_{CC} / 2$	$V_{CC} / 2$	Recessive	High
X	$V_{RS} \geq 0.75 \times V_{CC}$	R _{ICM} to GND	R _{ICM} to GND	Recessive	High

Table 3. Transmitter and Receiver Truth Table (MAX13053)

TXD	RS	CANH	CANL	BUS STATE	RXD
Low	$V_S < 0.8V$	High	Low	Dominant	Low
High or Open	$V_S < 0.8V$	$V_{CC} / 2$	$V_{CC} / 2$	Recessive	High
X	$V_S > 2V$	$V_{CC} / 2$	$V_{CC} / 2$	Recessive	High

(MAX13050/MAX13054)

TXD	STBY	CANH	CANL	BUS STATE	RXD
Low	$V_{STBY} \leq 0.8V$ $*V_{STBY} \leq 0.3 \times V_{CC2}$	High	Low	Dominant	Low
High or Open	$V_{STBY} \leq 0.8V$ $*V_{STBY} \leq 0.3 \times V_{CC2}$	$V_{CC} / 2$	$V_{CC} / 2$	Recessive	High
X	$V_{STBY} \geq 2V$ $*V_{STBY} \geq 0.7 \times V_{CC2}$	R _{ICM} to GND	R _{ICM} to GND	Recessive	High

*For the MAX13054

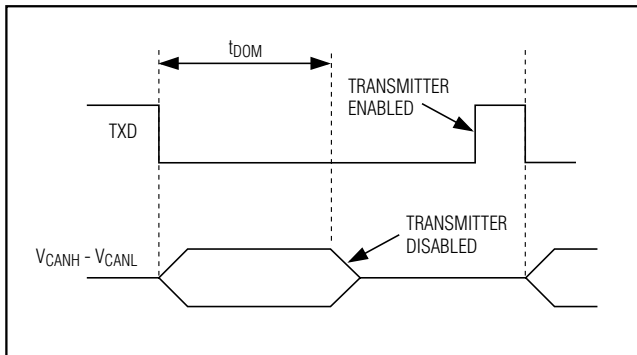


Figure 3. Transmitter Dominant Timeout Timing Diagram

(Figure 3). The transmitter becomes enabled upon detecting a rising edge at TXD.

Receiver

The receiver reads differential inputs from the bus lines (CANH, CANL) and transfers this data as a single-ended output (RXD) to the CAN controller. It consists of a comparator that senses the difference $V_{DIFF} = (CANH - CANL)$ with respect to an internal threshold of 0.7V. If this difference is positive (i.e., $V_{DIFF} > 0.7$), a logic-low is present at RXD. If negative (i.e., $V_{DIFF} < 0.7V$), a logic-high is present.

The CANH and CANL common-mode range is greater than $\pm 12V$. RXD is logic-high when CANH and CANL are shorted or terminated and undriven.

+3.3V Logic Compatibility (MAX13054)

A separate input, V_{CC2} , allows the MAX13054 to communicate with +3.3V logic systems while operating from a +5V supply. This provides a reduced input voltage threshold to the TXD and STBY inputs, and provides a logic-high output at RXD compatible with the microcontroller's system voltage. The logic compatibility eliminates longer propagation delay due to level shifting. Connect V_{CC2} to V_{CC} to operate the MAX13054 with +5V logic systems.

Driver Output Protection

The current-limiting feature protects the transmitter output stage against a short circuit to a positive and negative battery voltage. Although the power dissipation increases during this fault condition, current-limit protection prevents destruction of the transmitter output stage. Upon removal of a short, the CAN transceiver resumes normal operation.

Thermal Shutdown

If the junction temperature exceeds $+165^{\circ}C$, the driver is switched off. The hysteresis is approximately $13^{\circ}C$,

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

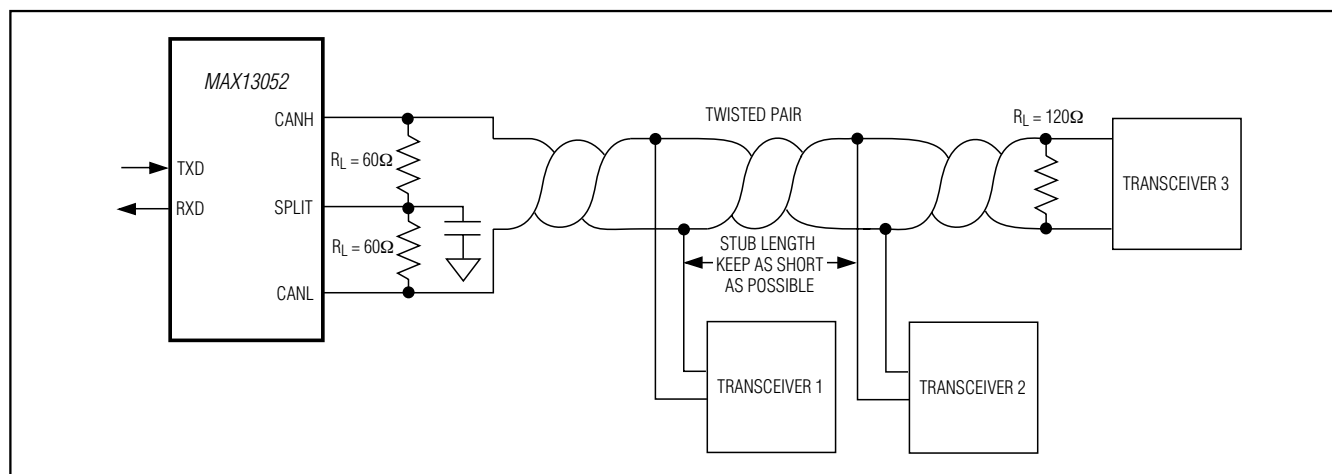


Figure 4. Multiple Receivers Connected to CAN Bus

disabling thermal shutdown once the temperature drops below $+152^{\circ}\text{C}$. In thermal shutdown, CANH and CANL go recessive. After a thermal-shutdown event, the IC resumes normal operation when the junction temperature drops below the thermal-shutdown hysteresis, and upon the CAN transceiver detecting a rising edge at TXD.

Applications Information

Reduced EMI and Reflections

In slope-control mode, the MAX13052's CANH and CANL outputs are slew-rate limited, minimizing EMI and reducing reflections caused by improperly terminated cables.

In multidrop CAN applications, it is important to maintain a direct point-to-point wiring scheme. A single pair of wires should connect each element of the CAN bus, and the two ends of the bus should be terminated with 120Ω resistors, see Figure 4. A star configuration should never be used.

Any deviation from the point-to-point wiring scheme creates a stub. The high-speed edge of the CAN data on a stub can create reflections back down the bus. These reflections can cause data errors by eroding the noise margin of the system.

Although stubs are unavoidable in a multidrop system, care should be taken to keep these stubs as small as possible, especially in high-speed mode. In slope-control mode, the requirements are not as rigorous, but stub length should still be minimized.

Layout Consideration

CANH and CANL are differential signals and steps should be taken to insure equivalent parasitic capaci-

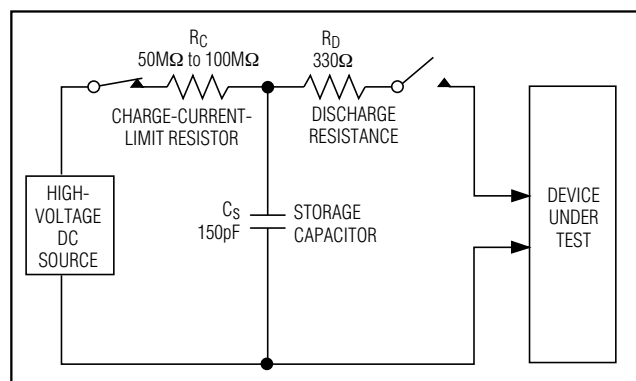


Figure 5. IEC 61000-4-2 Contact Discharge ESD Test Model

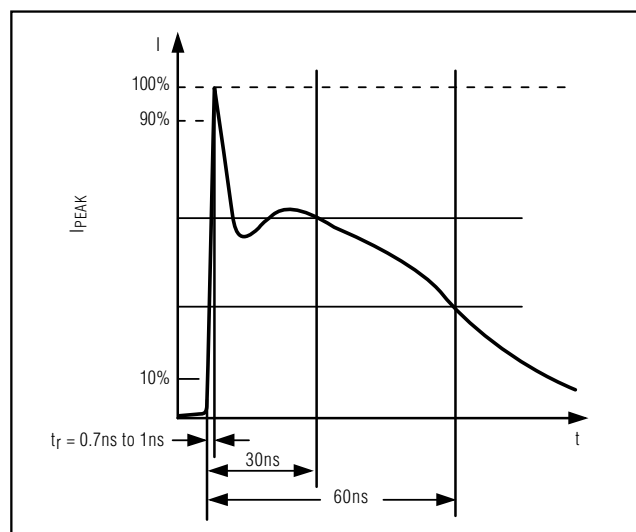


Figure 6. IEC 61000-4-2 ESD Test Model Current Waveform

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

tance. Place the resistor at RS as close as possible to the MAX13052 to minimize any possible noise coupling at the input.

Power Supply and Bypassing

The MAX13050/MAX13052/MAX13053/MAX13054 require no special layout considerations beyond common practices. Bypass VCC and VCC2 to GND with a 0.1 μ F ceramic capacitor mounted close to the IC with short lead lengths and wide trace widths.

ESD Protection

ESD-protection structures are incorporated on CANH and CANL to protect against ESD encountered during handling and assembly. CANH and CANL inputs have extra protection to protect against static electricity found in normal operation. Maxim's engineers have developed state-of-the-art structures to protect these pins against $\pm 8kV$ ESD Contact Discharge without damage. After an ESD event, the MAX13050/MAX13052/MAX13053/

MAX13054 continue working without latchup. ESD protection can be tested in several ways. The CANH and CANL inputs are characterized for protection to $\pm 8kV$ using the IEC 61000-4-2 Contact Discharge Method per IBEE Test facility.

ESD Test Conditions

ESD performance depends on a number of conditions. Contact Maxim for a reliability report that documents test setup, methodology, and results.

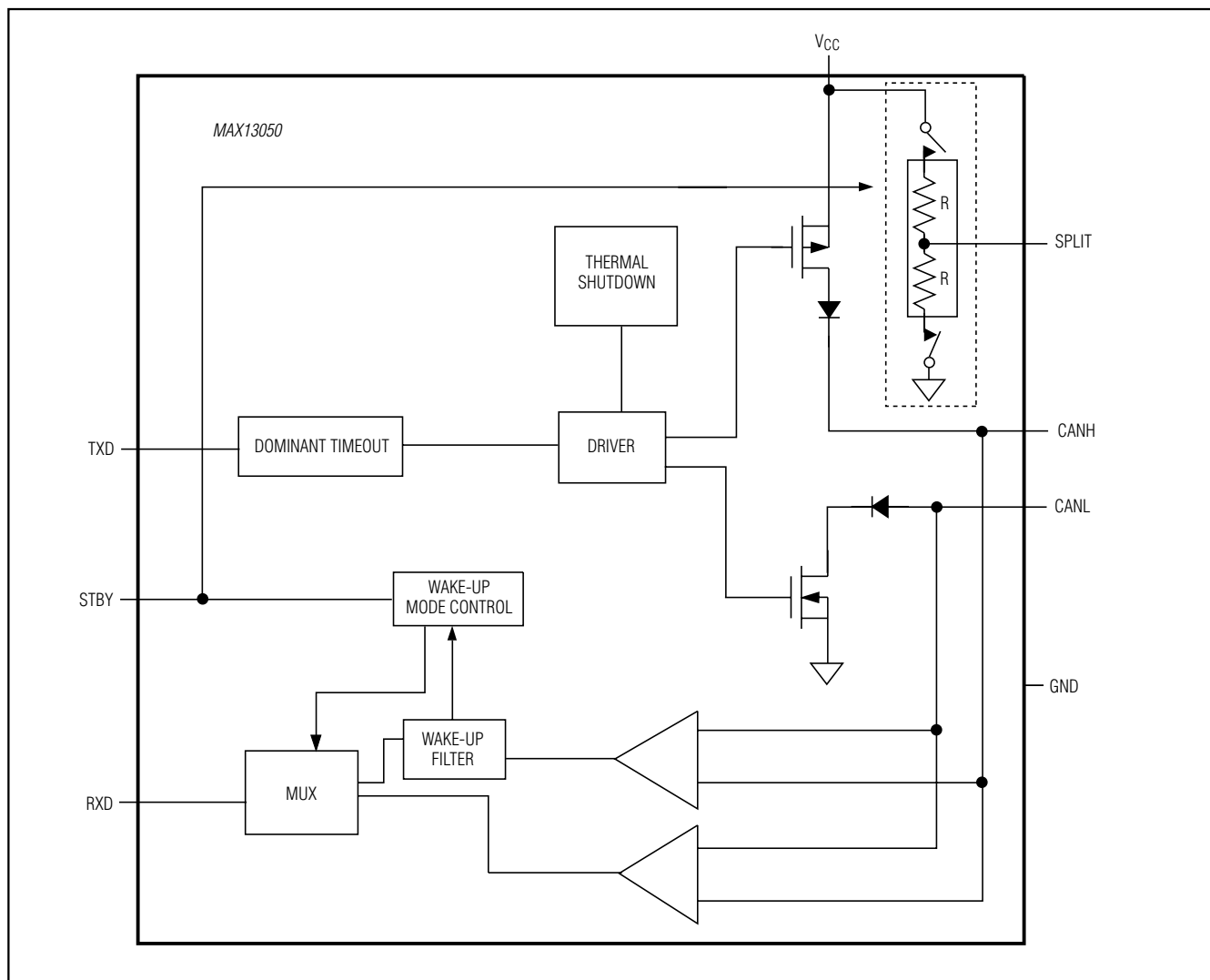
Human Body Model

Figure 5 shows the IEC 61000-4-2 Contact Discharge Model, and Figure 6 shows the current waveform it generates when discharged into a low impedance. This model consists of a 100pF capacitor charged to the ESD voltage of interest, which is then discharged into the device through a 1.5k Ω resistor.

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

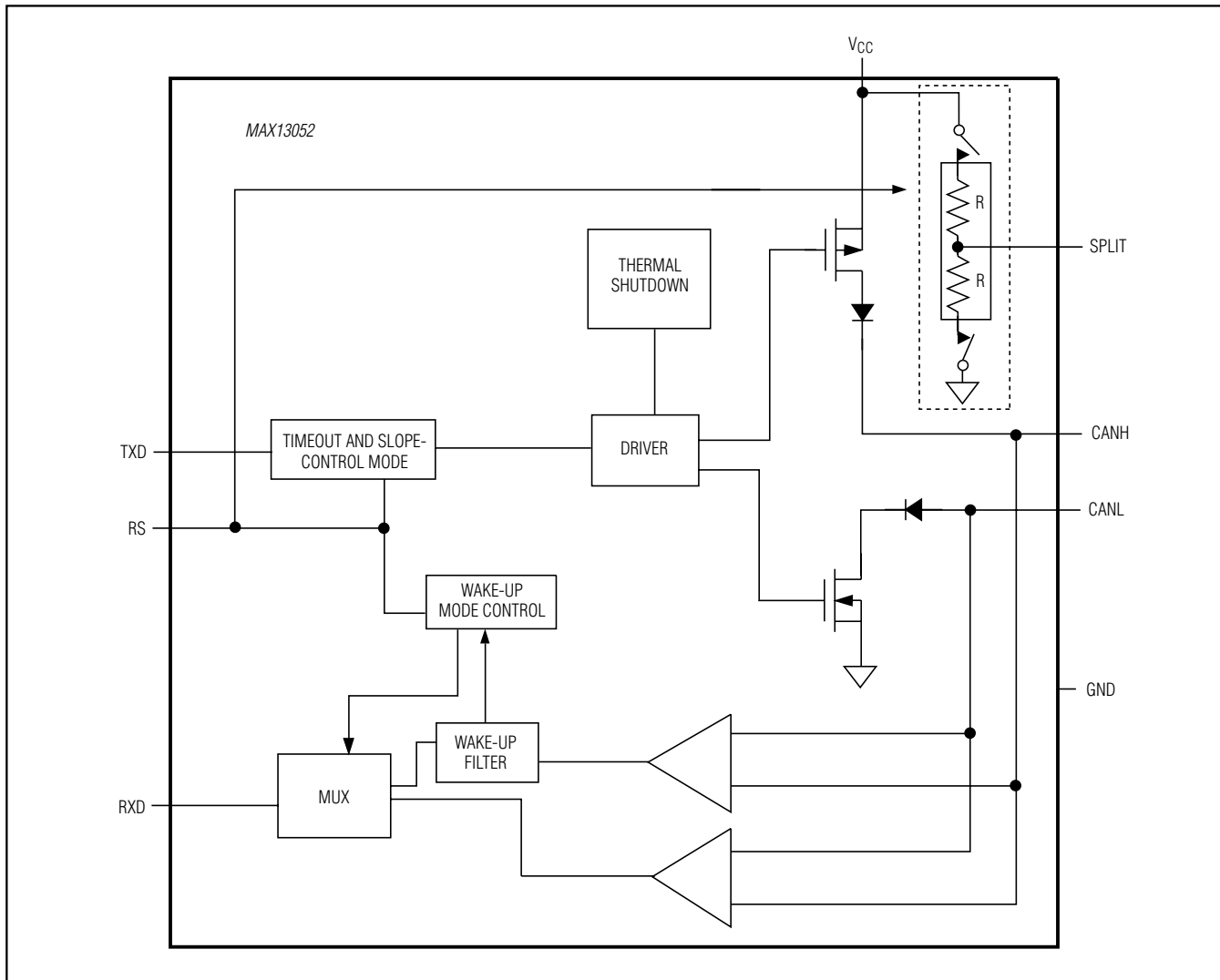
Functional Diagrams



MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

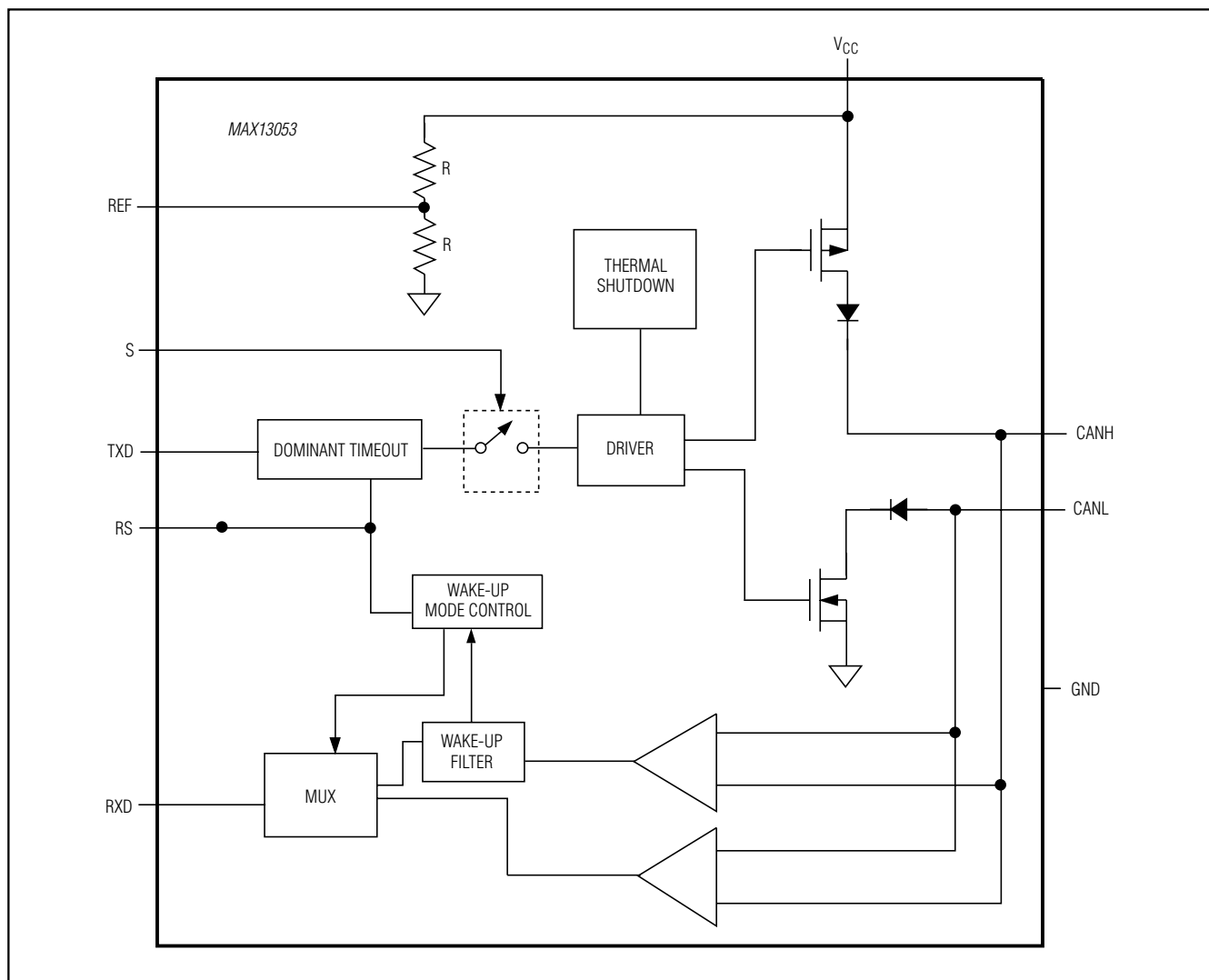
Functional Diagrams (continued)



MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

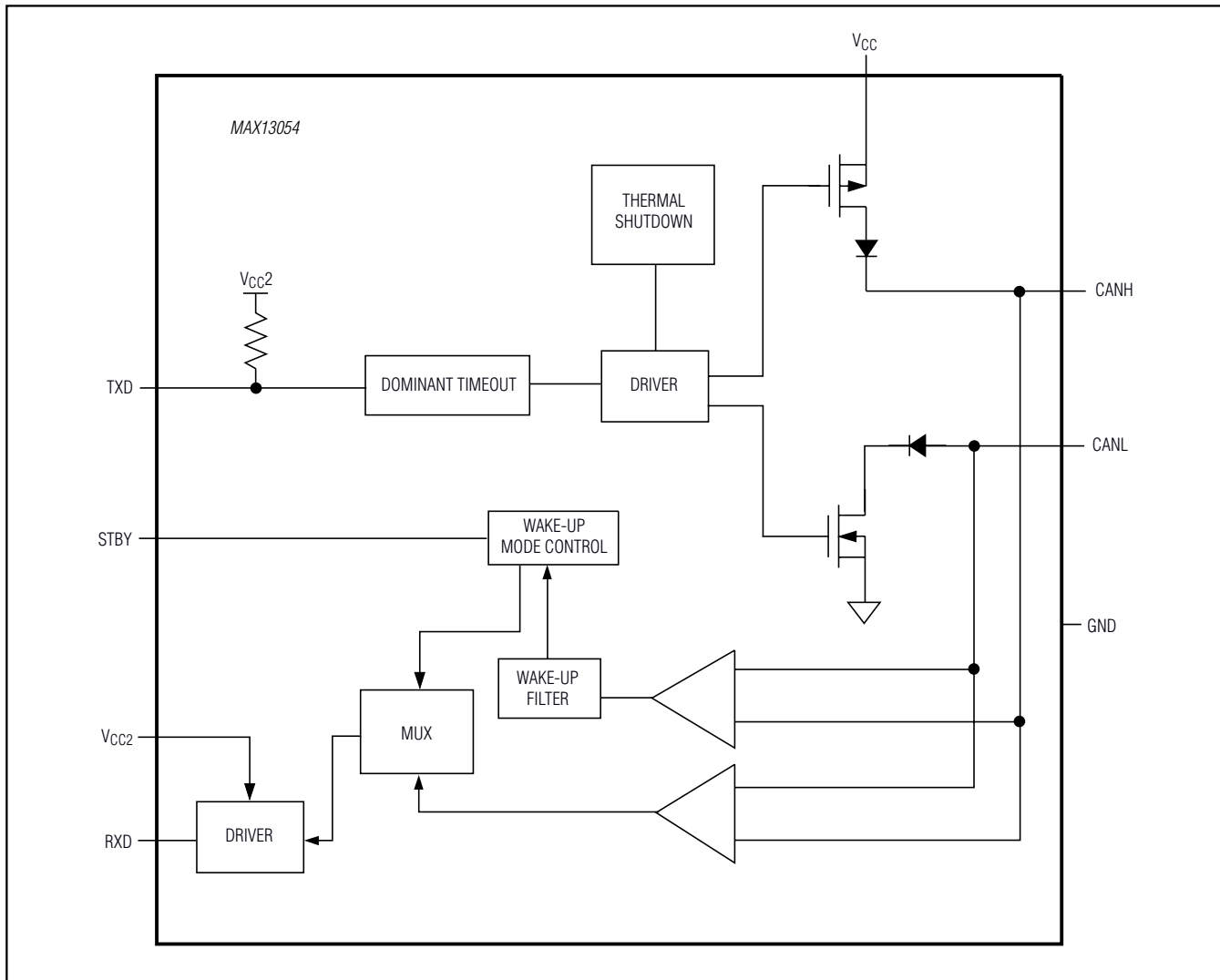
Functional Diagrams (continued)



MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

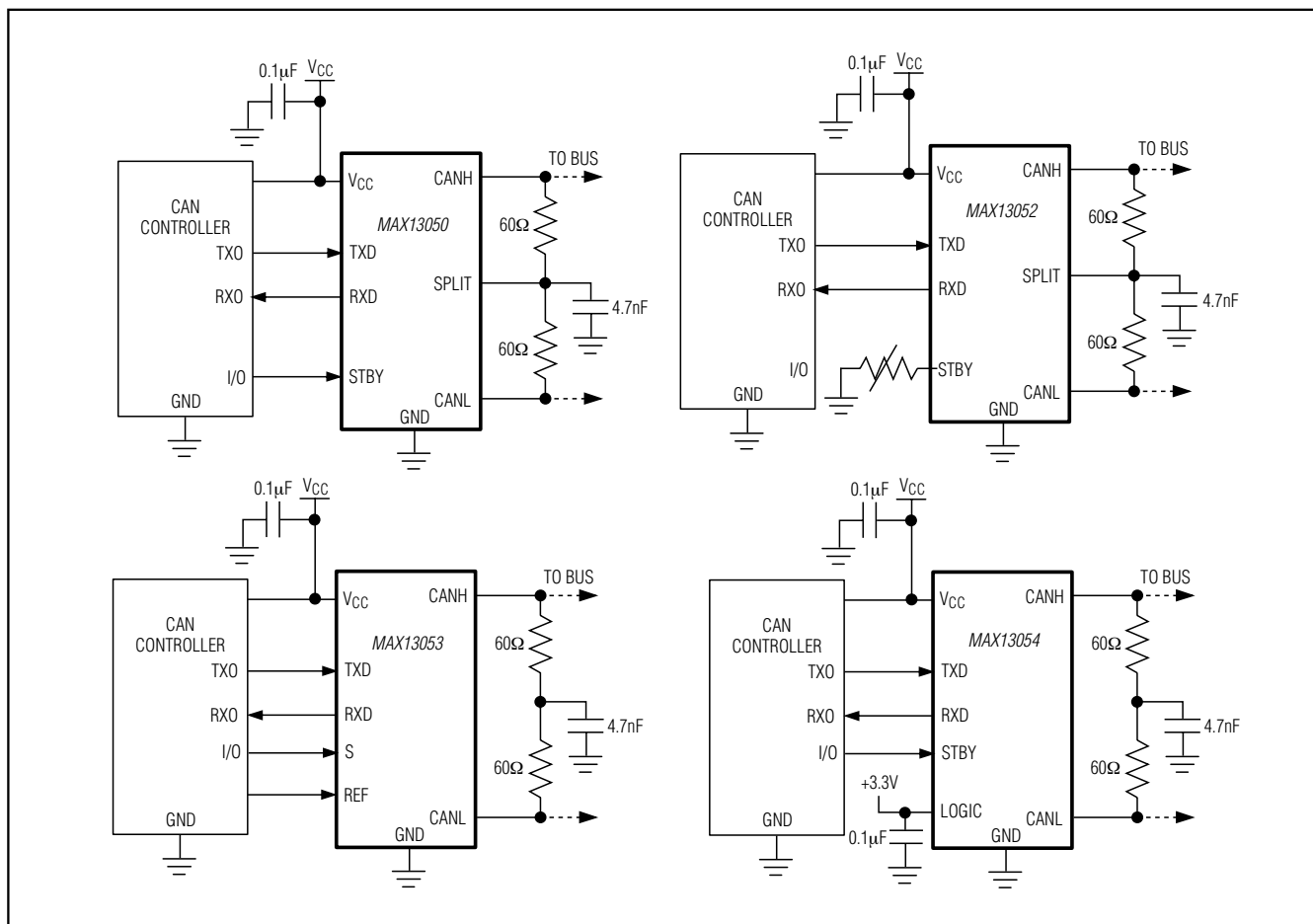
Functional Diagrams (continued)



MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

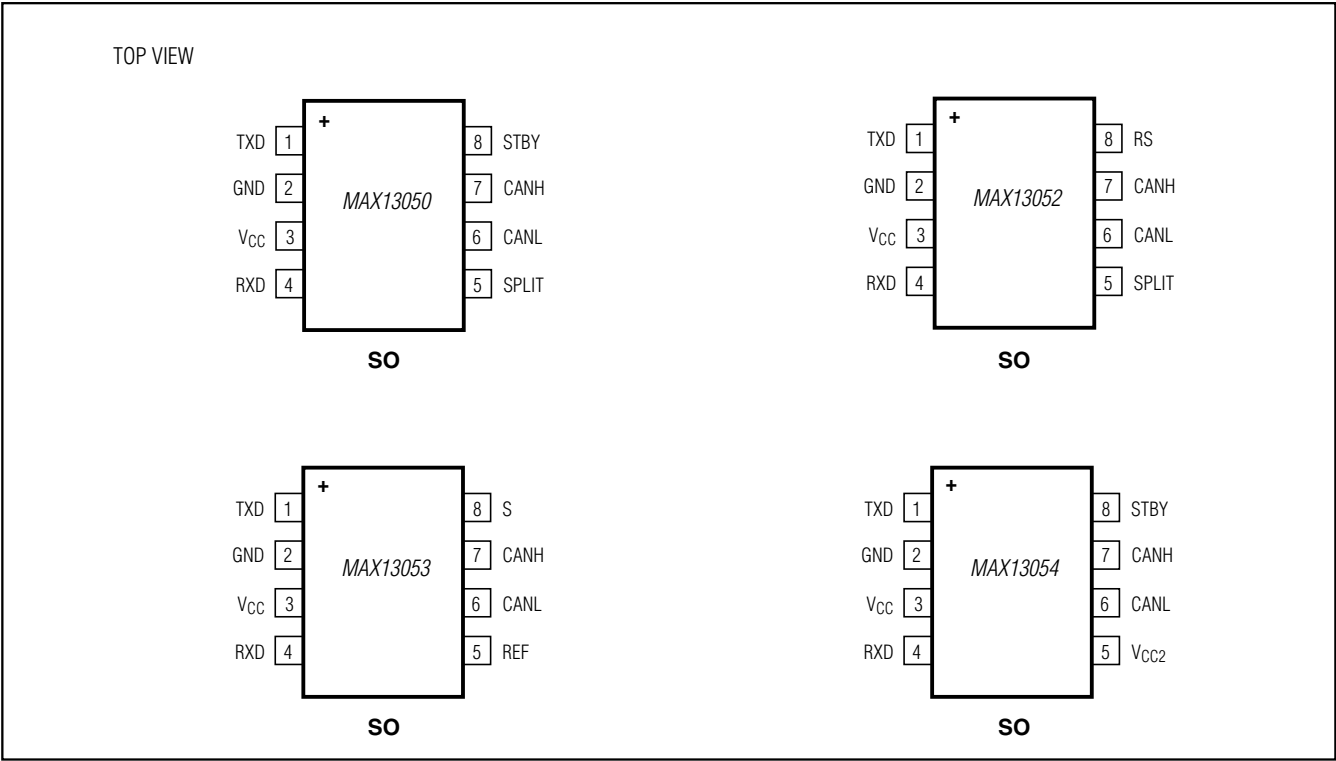
Typical Operating Circuits



MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

Pin Configurations



Chip Information

PROCESS: BiCMOS

Package Information

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
8 SO	S8M+5	21-0041	90-0096

MAX13050/MAX13052/MAX13053/MAX13054

Industry-Standard High-Speed CAN Transceivers with $\pm 80V$ Fault Protection

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	2/05	Initial release	—
1	2/13	Removed automotive part information and references throughout data sheet	1, 9–12, 19



Maxim Integrated cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim Integrated product. No circuit patent licenses are implied. Maxim Integrated reserves the right to change the circuitry and specifications without notice at any time. The parametric values (min and max limits) shown in the Electrical Characteristics table are guaranteed. Other parametric values quoted in this data sheet are provided for guidance.