

CT (ACT)

2. Specifications

Characteristics	Item		Specifications
Contact	Arrangement		1 Form C × 2, 1 Form C
	Contact resistance (Initial)		N.O.: Typ 7mΩ, N.C.: Typ 10mΩ (By voltage drop 6V DC 1A)
	Contact material		Ag alloy (Cadmium free)
Rating	Nominal switching capacity (resistive load)		N.O.: 20 A 14V DC, N.C.: 10 A 14V DC
	Max. carrying current (14V DC)*3		N.O.: 25 A for 1 hour, 35 A for 2 minutes at 20°C 68°F 20 A for 1 hour, 30 A for 2 minutes at 85°C 185°F
	Nominal operating power		800 mW
	Min. switching capacity (resistive load)*1		1 A 14V DC
Electrical characteristics	Insulation resistance (Initial)		Min. 100 MΩ (at 500V DC, Measurement at same location as "Breakdown voltage" section.)
	Breakdown voltage (Initial)	Between open contacts	500 Vrms for 1 min. (Detection current: 10mA)
		Between contacts and coil	500 Vrms for 1 min. (Detection current: 10mA)
	Operate time (at nominal voltage)		Max. 10ms (at 20°C 68°F, excluding contact bounce time) (Initial)
	Release time (at nominal voltage)		Max. 10ms (at 20°C 68°F, excluding contact bounce time) (Initial)
Mechanical characteristics	Shock resistance	Functional	Min. 100 m/s ² {10G} (Half-wave pulse of sine wave: 11ms; detection time: 10μs)
		Destructive	Min. 1,000 m/s ² {100G} (Half-wave pulse of sine wave: 6ms)
	Vibration resistance	Functional	10 Hz to 100 Hz, Min. 44.1 m/s ² {4.5G} (Detection time: 10μs)
		Destructive	10 Hz to 500 Hz, Min. 44.1 m/s ² {4.5G}, Time of vibration for each direction; X, Y direction: 2 hours, Z direction: 4 hours
Expected life	Mechanical		Min. 10 ⁷ (at 120 cpm)
	Electrical		<Resistive load> Min. 10 ⁵ (at nominal switching capacity, operating frequency: 1s ON, 9s OFF) <Motor load> N.O. side: Min. 2 × 10 ⁵ (at Inrush 25A, Steady 5A 14 V DC), Min. 10 ⁵ (at 25A 14 V DC motor lock condition) N.C. side: Min. 2 × 10 ⁵ (at brake current 20A 14 V DC) (operating frequency: 0.5s ON, 9.5s OFF)
Conditions	Conditions for operation, transport and storage*2		Ambient temperature: -40°C to +85°C -40°F to +185°F, Humidity: 5% R.H. to 85% R.H. (Not freezing and condensing at low temperature)
	Max. operating speed		6 cpm (at nominal switching capacity)
Mass			Twin type: approx. 8 g .28 oz, 1 Form C type: approx. 4 g .14 oz

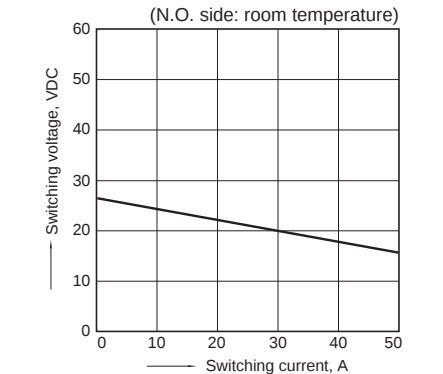
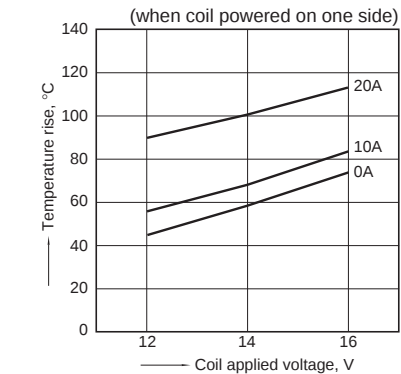
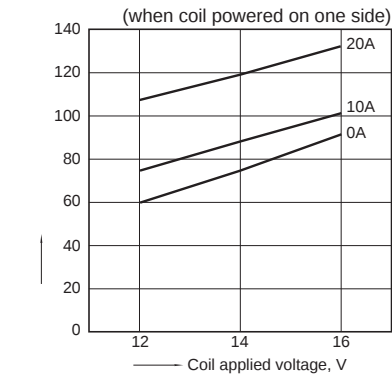
Notes:
*1. This value can change due to the switching frequency, environmental conditions, and desired reliability level, therefore it is recommended to check this with the actual load.
*2. The upper operation ambient temperature limit is the maximum temperature that can satisfy the coil temperature rise value. Refer to "6. Usage, Storage and Transport Conditions" in [AMBIENT ENVIRONMENT section in Relay Technical Information](#).
Please inquire if you will be using the relay in a high temperature atmosphere (110°C 230°F).
*3. Depends on connection conditions. Also, this does not guarantee repeated switching. We recommend that you confirm operation under actual conditions.
* If the relay is used continuously for long periods of time with coils on both sides in an energized condition, breakdown might occur due to abnormal heating depending on the carrying condition. Therefore, please inquire when using with a circuit that causes an energized condition on both sides simultaneously.

REFERENCE DATA

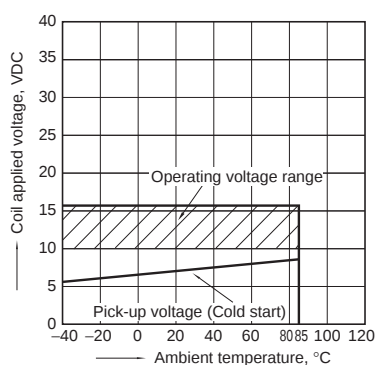
1-(1). Coil temperature rise (at room temperature)
Sample: ACT212, 3pcs.
Contact carrying current: 0A, 10A, 20A
Ambient temperature: Room temperature

1-(2). Coil temperature rise (at 85°C 185°F)
Sample: ACT212, 3pcs.
Contact carrying current: 0A, 10A, 20A
Ambient temperature: 85°C 185°F

2. Max. switching capability (Resistive load, initial)

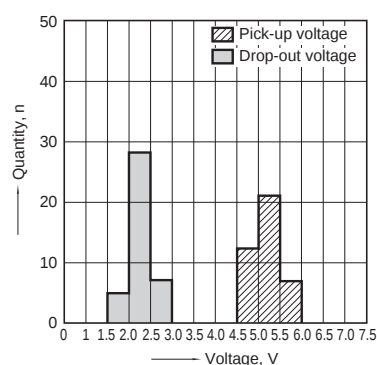


3. Ambient temperature and operating voltage range



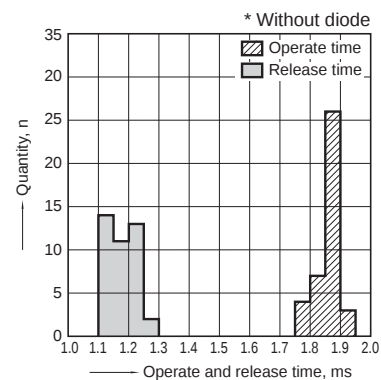
4. Distribution of pick-up and drop-out voltage

Sample: ACT212, 40pcs.



5. Distribution of operate and release time

Sample: ACT212, 40pcs.



6-(1). Electrical life test (Motor free)

Sample: ACT212, 3pcs.

Load: Inrush 25A, steady 5A

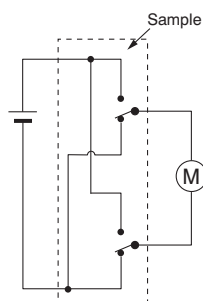
Brake current: 13A 14V DC,

Power window motor actual load (free condition)

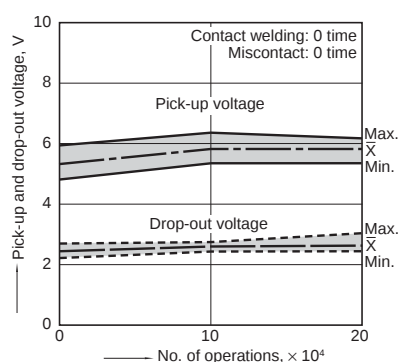
Operating frequency: ON 0.5s, OFF 9.5s

Ambient temperature: Room temperature

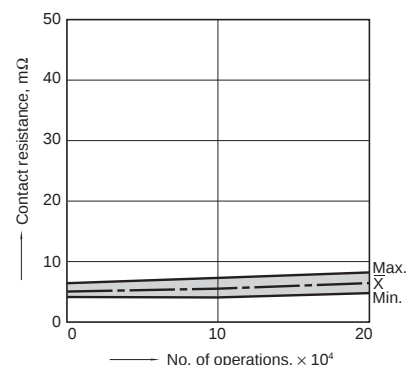
Circuit:



Change of pick-up and drop-out voltage



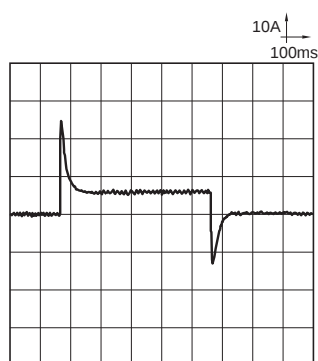
Change of contact resistance



Load current waveform

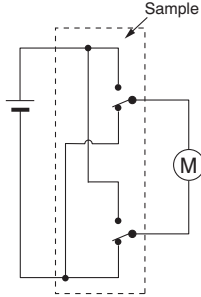
Inrush current: 25A, Steady current: 6A

Brake current: 13A

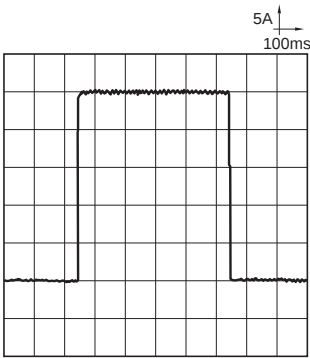


CT (ACT)

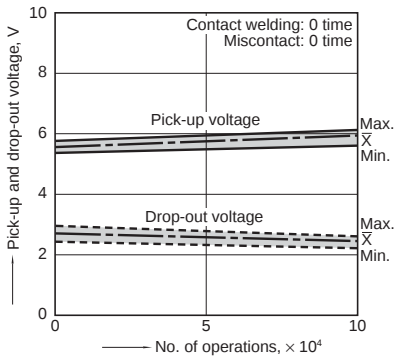
6-(2). Electrical life test (Motor lock)
Sample: ACT212, 3pcs.
Load: 25A 14V DC
Power window motor actual load (lock condition)
Switching frequency: ON 0.5s, OFF 9.5s
Ambient temperature: Room temperature
Circuit:



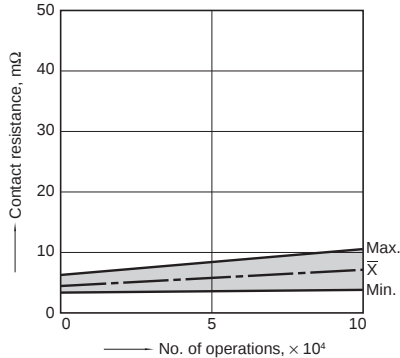
Load current waveform



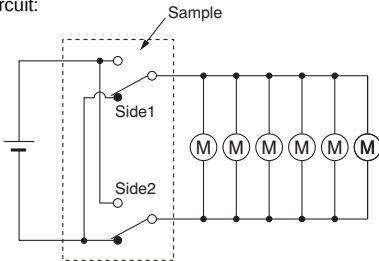
Change of pick-up and drop-out voltage



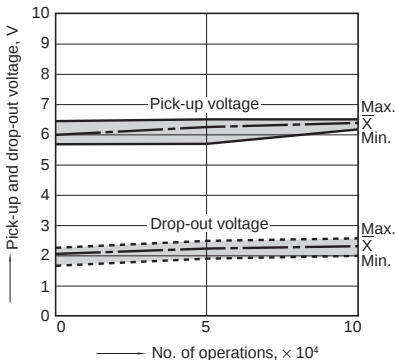
Change of contact resistance



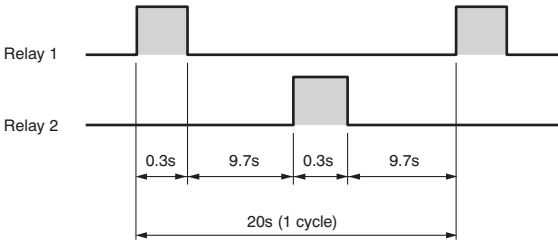
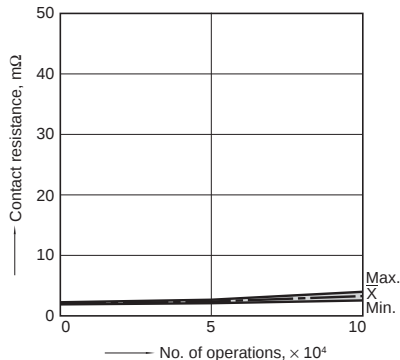
6-(3). Electrical life test (Motor lock)
Sample: ACT212, 3pcs.
Load: 20A 14V DC,
door lock motor actual load (Lock condition)
Switching frequency: ON 0.3s, OFF 19.7s
Ambient temperature: Room temperature
Circuit:



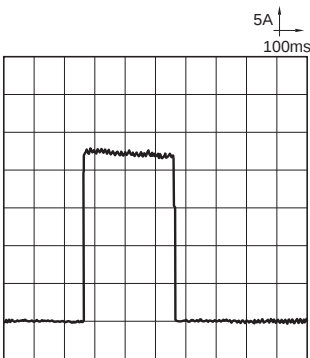
Change of pick-up and drop-out voltage



Change of contact resistance



Load current waveform



DIMENSIONS (mm inch)

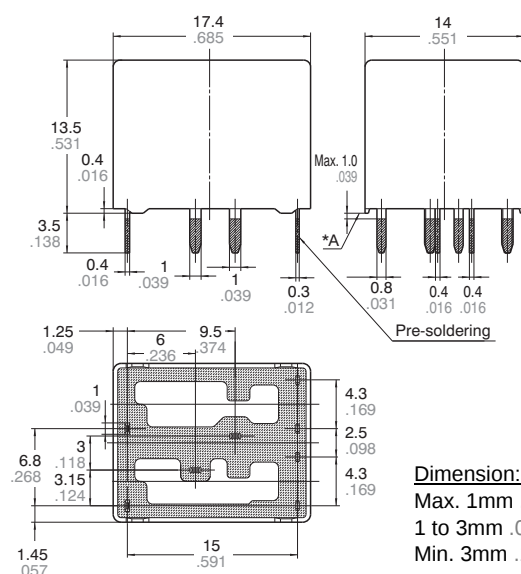
Download **CAD Data** from our Web site.

1. Twin type (8 terminals)

CAD Data

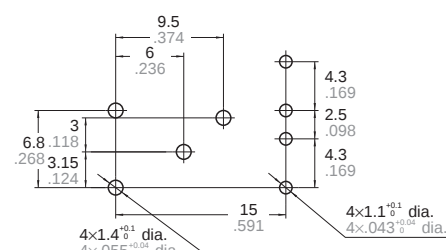


External dimensions



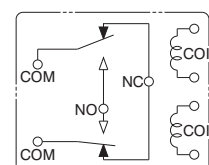
* Dimensions (thickness and width) of terminal is measured before pre-soldering. Intervals between terminals is measured at A surface level.

PC board pattern (Bottom view)



Tolerance: $\pm 0.1 \pm .004$

Schematic (Bottom view)

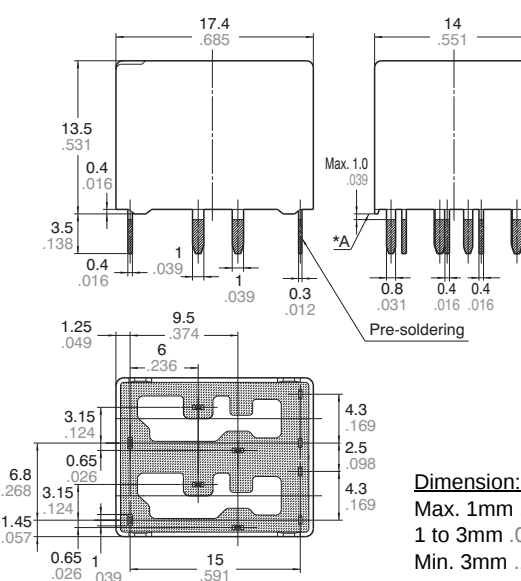


2. Twin type (10 terminals)

CAD Data

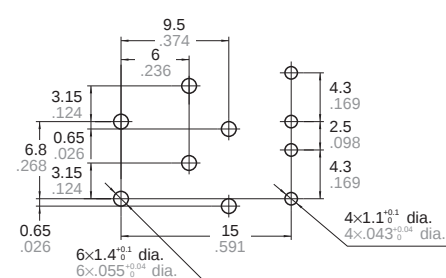


External dimensions



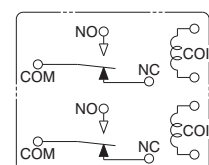
* Dimensions (thickness and width) of terminal is measured before pre-soldering. Intervals between terminals is measured at A surface level.

PC board pattern (Bottom view)



Tolerance: $\pm 0.1 \pm .004$

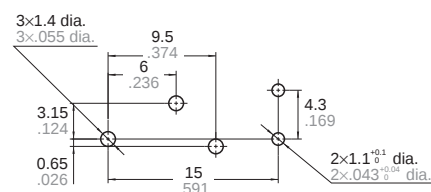
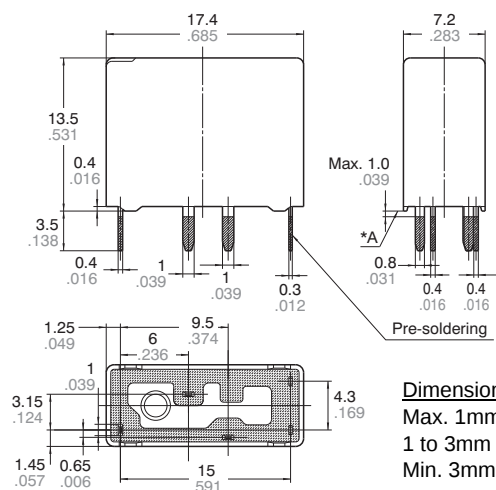
Schematic (Bottom view)



CAD Data

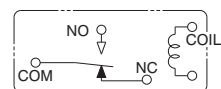


PC board pattern (Bottom view)



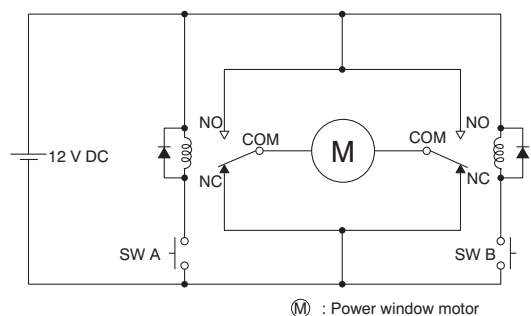
Tolerance: $\pm 0.1 \pm .004$

Schematic (Bottom view)



* Dimensions (thickness and width) of terminal is measured before pre-soldering. Intervals between terminals is measured at A surface level.

Forward/reverse control circuits of DC motor for power windows



For Cautions for Use, see [Relay Technical Information](#).