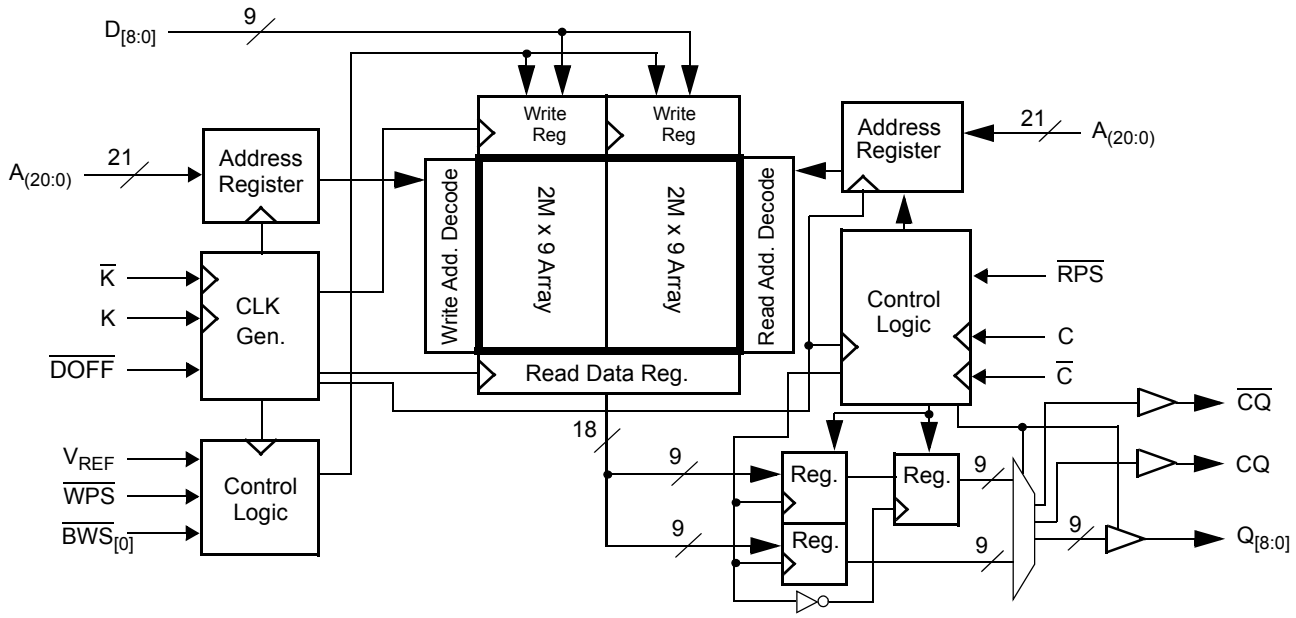
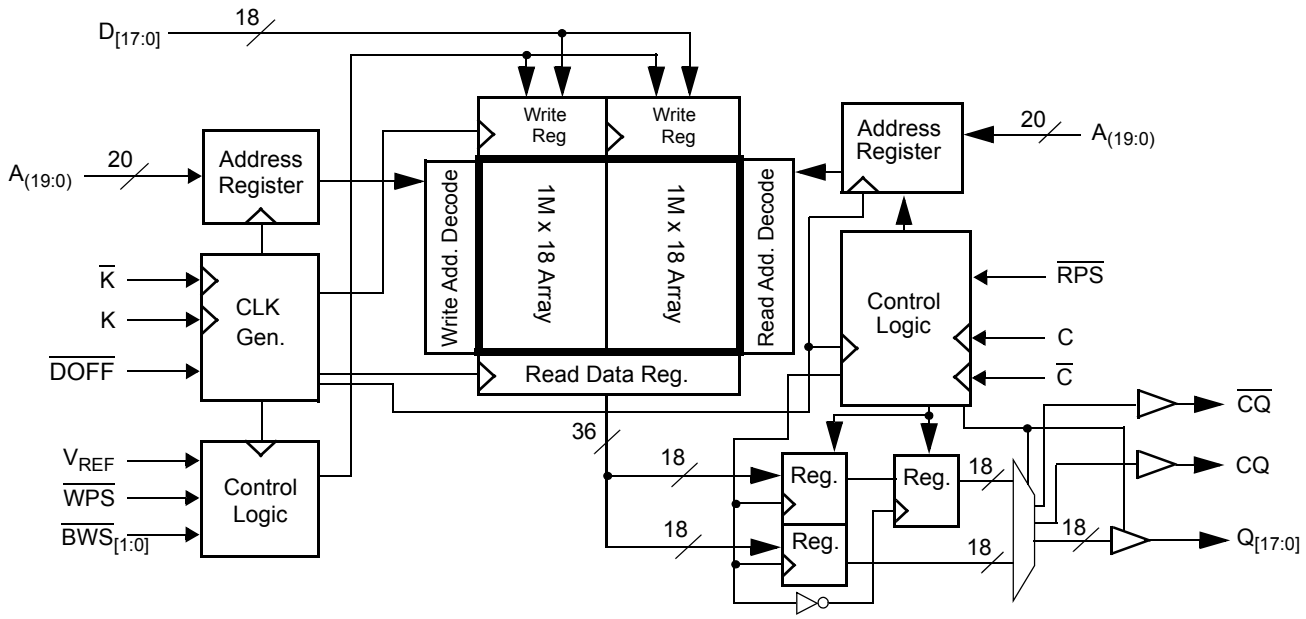
Logic Block Diagram – CY7C1425KV18

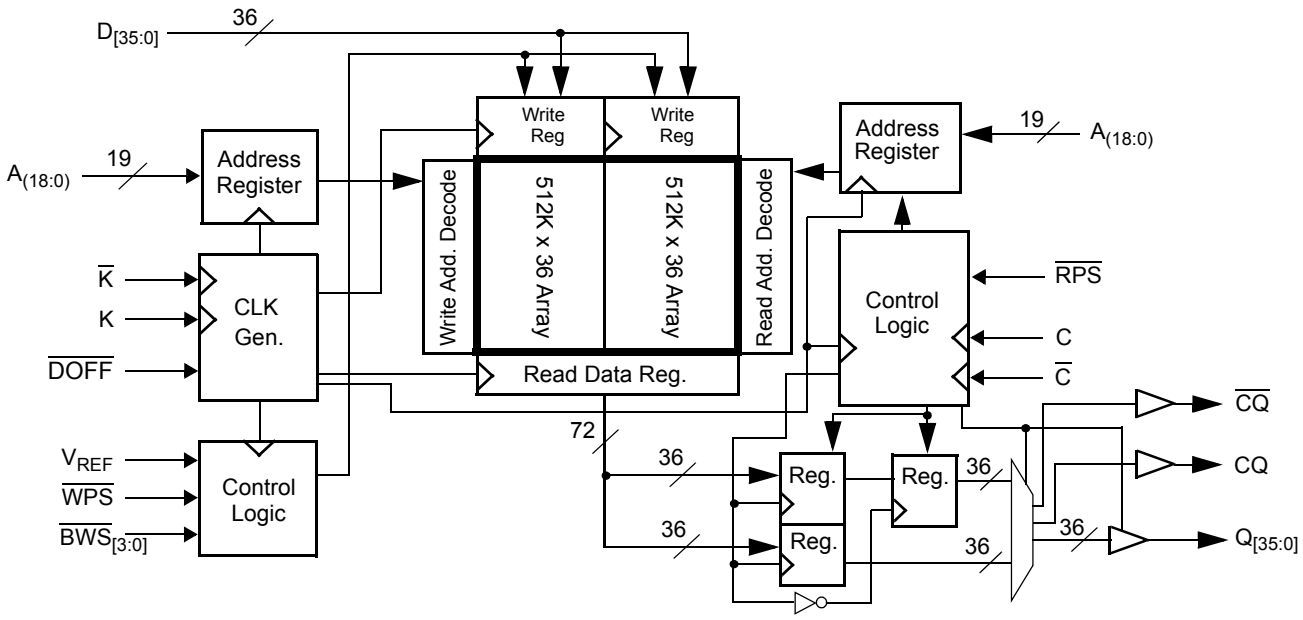


Logic Block Diagram – CY7C1412KV18



Downloaded from Arrow.com.

Logic Block Diagram – CY7C1414KV18



Downloaded from Arrow.com.

Contents

Pin Configurations **5**
Pin Definitions **7**
Functional Overview **8**
Read Operations 8
Write Operations 9
Byte Write Operations 9
Concurrent Transactions 9
Depth Expansion 9
Programmable Impedance 9
Echo Clocks 9
PLL 9
Application Example **10**
Truth Table **11**
Write Cycle Descriptions **11**
Write Cycle Descriptions **12**
Write Cycle Descriptions **12**
IEEE 1149.1 Serial Boundary Scan (JTAG) **13**
Disabling the JTAG Feature 13
Test Access Port 13
Performing a TAP Reset 13
TAP Registers 13
TAP Instruction Set 13
TAP Controller State Diagram **15**
TAP Controller Block Diagram **16**
TAP Electrical Characteristics **16**
TAP AC Switching Characteristics **17**
TAP Timing and Test Conditions **18**
Identification Register Definitions **19**
Scan Register Sizes **19**
Instruction Codes **19**
Boundary Scan Order **20**
Power Up Sequence in QDR II SRAM **21**
Power Up Sequence 21
PLL Constraints 21
Maximum Ratings **22**
Operating Range **22**
Neutron Soft Error Immunity **22**
Electrical Characteristics **22**
DC Electrical Characteristics 22
AC Electrical Characteristics 24
Capacitance **24**
Thermal Resistance **24**
AC Test Loads and Waveforms **24**
Switching Characteristics **25**
Switching Waveforms **27**
Ordering Information **28**
Ordering Code Definitions 28
Package Diagram **29**
Acronyms **30**
Document Conventions **30**
Units of Measure 30
Document History Page **31**
Sales, Solutions, and Legal Information **33**
Worldwide Sales and Design Support 33
Products 33
PSoC® Solutions 33
Cypress Developer Community 33
Technical Support 33

Downloaded from Arrow.com.

Pin Configurations

The pin configurations for CY7C1425KV18, CY7C1412KV18, and CY7C1414KV18 follow. [1]

Figure 1. 165-ball FBGA (13 × 15 × 1.4 mm) pinout

CY7C1425KV18 (4M × 9)

	1	2	3	4	5	6	7	8	9	10	11
A	$\overline{CQ}$	NC/72M	A	$\overline{WPS}$	NC	$\overline{K}$	NC/144M	$\overline{RPS}$	A	A	CQ
B	NC	NC	NC	A	NC/288M	K	$\overline{BWS_0}$	A	NC	NC	Q4
C	NC	NC	NC	V_{SS}	A	A	A	V_{SS}	NC	NC	D4
D	NC	D5	NC	V_{SS}	V_{SS}	V_{SS}	V_{SS}	V_{SS}	NC	NC	NC
E	NC	NC	Q5	V_{DDQ}	V_{SS}	V_{SS}	V_{SS}	V_{DDQ}	NC	D3	Q3
F	NC	NC	NC	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	NC	NC
G	NC	D6	Q6	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	NC	NC
H	$\overline{DOFF}$	V_{REF}	V_{DDQ}	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	V_{DDQ}	V_{REF}	ZQ
J	NC	NC	NC	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	Q2	D2
K	NC	NC	NC	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	NC	NC
L	NC	Q7	D7	V_{DDQ}	V_{SS}	V_{SS}	V_{SS}	V_{DDQ}	NC	NC	Q1
M	NC	NC	NC	V_{SS}	V_{SS}	V_{SS}	V_{SS}	V_{SS}	NC	NC	D1
N	NC	D8	NC	V_{SS}	A	A	A	V_{SS}	NC	NC	NC
P	NC	NC	Q8	A	A	C	A	A	NC	D0	Q0
R	TDO	TCK	A	A	A	$\overline{C}$	A	A	A	TMS	TDI

Note
1. NC/72M, NC/144M and NC/288M are not connected to the die and can be tied to any voltage level.

Downloaded from Arrow.com.

Pin Configurations *(continued)*

The pin configurations for CY7C1425KV18, CY7C1412KV18, and CY7C1414KV18 follow. [1]

Figure 1. 165-ball FBGA (13 × 15 × 1.4 mm) pinout

CY7C1412KV18 (2M × 18)

	1	2	3	4	5	6	7	8	9	10	11
A	$\overline{CQ}$	NC/144M	A	$\overline{WPS}$	$\overline{BWS_1}$	$\overline{K}$	NC/288M	$\overline{RPS}$	A	NC/72M	CQ
B	NC	Q9	D9	A	NC	K	$\overline{BWS_0}$	A	NC	NC	Q8
C	NC	NC	D10	V_{SS}	A	A	A	V_{SS}	NC	Q7	D8
D	NC	D11	Q10	V_{SS}	V_{SS}	V_{SS}	V_{SS}	V_{SS}	NC	NC	D7
E	NC	NC	Q11	V_{DDQ}	V_{SS}	V_{SS}	V_{SS}	V_{DDQ}	NC	D6	Q6
F	NC	Q12	D12	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	NC	Q5
G	NC	D13	Q13	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	NC	D5
H	$\overline{DOFF}$	V_{REF}	V_{DDQ}	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	V_{DDQ}	V_{REF}	ZQ
J	NC	NC	D14	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	Q4	D4
K	NC	NC	Q14	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	D3	Q3
L	NC	Q15	D15	V_{DDQ}	V_{SS}	V_{SS}	V_{SS}	V_{DDQ}	NC	NC	Q2
M	NC	NC	D16	V_{SS}	V_{SS}	V_{SS}	V_{SS}	V_{SS}	NC	Q1	D2
N	NC	D17	Q16	V_{SS}	A	A	A	V_{SS}	NC	NC	D1
P	NC	NC	Q17	A	A	C	A	A	NC	D0	Q0
R	TDO	TCK	A	A	A	$\overline{C}$	A	A	A	TMS	TDI

CY7C1414KV18 (1M × 36)

	1	2	3	4	5	6	7	8	9	10	11
A	$\overline{CQ}$	NC/288M	NC/72M	$\overline{WPS}$	$\overline{BWS_2}$	$\overline{K}$	$\overline{BWS_1}$	$\overline{RPS}$	A	NC/144M	CQ
B	Q27	Q18	D18	A	$\overline{BWS_3}$	K	$\overline{BWS_0}$	A	D17	Q17	Q8
C	D27	Q28	D19	V_{SS}	A	A	A	V_{SS}	D16	Q7	D8
D	D28	D20	Q19	V_{SS}	V_{SS}	V_{SS}	V_{SS}	V_{SS}	Q16	D15	D7
E	Q29	D29	Q20	V_{DDQ}	V_{SS}	V_{SS}	V_{SS}	V_{DDQ}	Q15	D6	Q6
F	Q30	Q21	D21	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	D14	Q14	Q5
G	D30	D22	Q22	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	Q13	D13	D5
H	$\overline{DOFF}$	V_{REF}	V_{DDQ}	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	V_{DDQ}	V_{REF}	ZQ
J	D31	Q31	D23	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	D12	Q4	D4
K	Q32	D32	Q23	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	Q12	D3	Q3
L	Q33	Q24	D24	V_{DDQ}	V_{SS}	V_{SS}	V_{SS}	V_{DDQ}	D11	Q11	Q2
M	D33	Q34	D25	V_{SS}	V_{SS}	V_{SS}	V_{SS}	V_{SS}	D10	Q1	D2
N	D34	D26	Q25	V_{SS}	A	A	A	V_{SS}	Q10	D9	D1
P	Q35	D35	Q26	A	A	C	A	A	Q9	D0	Q0
R	TDO	TCK	A	A	A	$\overline{C}$	A	A	A	TMS	TDI

Downloaded from Arrow.com.

Pin Definitions

Pin Name	I/O	Pin Description
$D_{[x:0]}$	Input-synchronous	**Data input signals**. Sampled on the rising edge of K and $\overline{K}$ clocks during valid write operations. CY7C1425KV18 – $D_{[8:0]}$ CY7C1412KV18 – $D_{[17:0]}$ CY7C1414KV18 – $D_{[35:0]}$
$\overline{WPS}$	Input-synchronous	**Write port select** – **active LOW**. Sampled on the rising edge of the K clock. When asserted active, a write operation is initiated. Deasserting deselects the write port. Deselecting the write port ignores $D_{[x:0]}$.
$\overline{BWS_0}$, $\overline{BWS_1}$, $\overline{BWS_2}$, $\overline{BWS_3}$	Input-synchronous	**Byte write select 0, 1, 2, and 3** – **active LOW**. Sampled on the rising edge of the K and $\overline{K}$ clocks during write operations. Used to select which byte is written into the device during the current portion of the write operations. Bytes not written remain unaltered. CY7C1425KV18 – $\overline{BWS_0}$ controls $D_{[8:0]}$. CY7C1412KV18 – $\overline{BWS_0}$ controls $D_{[8:0]}$ and $\overline{BWS_1}$ controls $D_{[17:9]}$. CY7C1414KV18 – $\overline{BWS_0}$ controls $D_{[8:0]}$, $\overline{BWS_1}$ controls $D_{[17:9]}$, $\overline{BWS_2}$ controls $D_{[26:18]}$ and $\overline{BWS_3}$ controls $D_{[35:27]}$. All the byte write selects are sampled on the same edge as the data. Deselecting a byte write select ignores the corresponding byte of data and it is not written into the device.
A	Input-synchronous	**Address inputs**. Sampled on the rising edge of the K (read address) and $\overline{K}$ (write address) clocks during active read and write operations. These address inputs are multiplexed for both read and write operations. Internally, the device is organized as 4M × 9 (2 arrays each of 2M × 9) for CY7C1425KV18, 2M × 18 (2 arrays each of 1M × 18) for CY7C1412KV18, and 1M × 36 (2 arrays each of 512K × 36) for CY7C1414KV18. Therefore, only 21 address inputs are needed to access the entire memory array of CY7C1425KV18, 20 address inputs for CY7C1412KV18, and 19 address inputs for CY7C1414KV18. These inputs are ignored when the appropriate port is deselected.
$Q_{[x:0]}$	Output-synchronous	**Data output signals**. These pins drive out the requested data during a read operation. Valid data is driven out on the rising edge of the C and $\overline{C}$ clocks during read operations, or K and $\overline{K}$ when in single clock mode. When the read port is deselected, $Q_{[x:0]}$ are automatically tristated. CY7C1425KV18 – $Q_{[8:0]}$ CY7C1412KV18 – $Q_{[17:0]}$ CY7C1414KV18 – $Q_{[35:0]}$
$\overline{RPS}$	Input-synchronous	**Read port select** – **active LOW**. Sampled on the rising edge of positive input clock (K). When active, a read operation is initiated. Deasserting deselects the read port. When deselected, the pending access is allowed to complete and the output drivers are automatically tristated following the next rising edge of the C clock. Each read access consists of a burst of two sequential transfers.
C	Input clock	**Positive input clock for output data**. C is used in conjunction with $\overline{C}$ to clock out the read data from the device. Use C and $\overline{C}$ together to deskew the flight times of various devices on the board back to the controller. See Application Example on page 10 for further details.
$\overline{C}$	Input clock	**Negative input clock for output data**. $\overline{C}$ is used in conjunction with C to clock out the read data from the device. Use C and $\overline{C}$ together to deskew the flight times of various devices on the board back to the controller. See Application Example on page 10 for further details.
K	Input clock	**Positive input clock input**. The rising edge of K is used to capture synchronous inputs to the device and to drive out data through $Q_{[x:0]}$ when in single clock mode. All accesses are initiated on the rising edge of K.
$\overline{K}$	Input clock	**Negative input clock input**. $\overline{K}$ is used to capture synchronous inputs being presented to the device and to drive out data through $Q_{[x:0]}$ when in single clock mode.
CQ	Echo clock	**CQ referenced with respect to C**. This is a free running clock and is synchronized to the input clock for output data (C) of the QDR II. In single clock mode, CQ is generated with respect to K. The timing for the echo clocks is shown in Switching Characteristics on page 25.
$\overline{CQ}$	Echo clock	**$\overline{CQ}$ referenced with respect to $\overline{C}$**. This is a free running clock and is synchronized to the input clock for output data ($\overline{C}$) of the QDR II. In single clock mode, $\overline{CQ}$ is generated with respect to $\overline{K}$. The timing for the echo clocks is shown in the Switching Characteristics on page 25.

Downloaded from Arrow.com.

Pin Definitions *(continued)*

Pin Name	I/O	Pin Description
ZQ	Input	**Output impedance matching input**. This input is used to tune the device outputs to the system data bus impedance. CQ, $\overline{CQ}$, and $Q_{[x:0]}$ output impedance are set to 0.2 × RQ, where RQ is a resistor connected between ZQ and ground. Alternatively, connect this pin directly to V_{DDQ}, which enables the minimum impedance mode. This pin cannot be connected directly to GND or left unconnected.
$\overline{DOFF}$	Input	**PLL turn off** – **active LOW**. Connecting this pin to ground turns off the PLL inside the device. The timing in the operation with the PLL turned off differs from those listed in this data sheet. For normal operation, connect this pin to a pull up through a 10 KΩ or less pull-up resistor. The device behaves in QDR I mode when the PLL is turned off. In this mode, the device can be operated at a frequency of up to 167 MHz with QDR I timing.
TDO	Output	**TDO pin for JTAG**.
TCK	Input	**TCK pin for JTAG**.
TDI	Input	**TDI pin for JTAG**.
TMS	Input	**TMS pin for JTAG**.
NC	N/A	**Not connected to the die**. Can be tied to any voltage level.
NC/72M	Input	**Not connected to the die**. Can be tied to any voltage level.
NC/144M	Input	**Not connected to the die**. Can be tied to any voltage level.
NC/288M	Input	**Not connected to the die**. Can be tied to any voltage level.
V_{REF}	Input-reference	**Reference voltage input**. Static input used to set the reference level for HSTL inputs, outputs, and AC measurement points.
V_{DD}	Power supply	**Power supply inputs to the core of the device**.
V_{SS}	Ground	**Ground for the device**.
V_{DDQ}	Power supply	**Power supply inputs for the outputs of the device**.

Functional Overview

The CY7C1425KV18, CY7C1412KV18, and CY7C1414KV18 are synchronous pipelined burst SRAMs with a read port and a write port. The read port is dedicated to read operations and the write port is dedicated to write operations. Data flows into the SRAM through the write port and flows out through the read port. These devices multiplex the address inputs to minimize the number of address pins required. By having separate read and write ports, the QDR II completely eliminates the need to turn around the data bus and avoids any possible data contention, thereby simplifying system design. Each access consists of two 9-bit data transfers in the case of CY7C1425KV18, two 18-bit data transfers in the case of CY7C1412KV18, and two 36-bit data transfers in the case of CY7C1414KV18 in one clock cycle.

This device operates with a read latency of one and half cycles when $\overline{DOFF}$ pin is tied HIGH. When $\overline{DOFF}$ pin is set LOW or connected to V_{SS} then the device behaves in QDR I mode with a read latency of one clock cycle.

Accesses for both ports are initiated on the rising edge of the positive input clock (K). All synchronous input timing is referenced from the rising edge of the input clocks (K and $\overline{K}$) and all output timing is referenced to the output clocks (C and $\overline{C}$, or K and $\overline{K}$ when in single clock mode).

All synchronous data inputs ($D_{[x:0]}$) pass through input registers controlled by the input clocks (K and $\overline{K}$). All synchronous data outputs ($Q_{[x:0]}$) pass through output registers controlled by the rising edge of the output clocks (C and $\overline{C}$, or K and $\overline{K}$ when in single clock mode).

All synchronous control ($\overline{RPS}$, $\overline{WPS}$, $\overline{BWS}_{[x:0]}$) inputs pass through input registers controlled by the rising edge of the input clocks (K and $\overline{K}$).

CY7C1412KV18 is described in the following sections. The same basic descriptions apply to CY7C1425KV18, and CY7C1414KV18.

Read Operations

The CY7C1412KV18 is organized internally as two arrays of 1M × 18. Accesses are completed in a burst of two sequential 18-bit data words. Read operations are initiated by asserting $\overline{RPS}$ active at the rising edge of the positive input clock (K). The address is latched on the rising edge of the K clock. The address presented to the address inputs is stored in the read address register. Following the next K clock rise, the corresponding lowest order 18-bit word of data is driven onto the $Q_{[17:0]}$ using $\overline{C}$ as the output timing reference. On the subsequent rising edge of C, the next 18-bit data word is driven onto the $Q_{[17:0]}$. The requested data is valid 0.45 ns from the rising edge of the output clock (C and $\overline{C}$ or K and $\overline{K}$ when in single clock mode).

Synchronous internal circuitry automatically tristates the outputs following the next rising edge of the output clocks (C/$\overline{C}$). This enables for a seamless transition between devices without the insertion of wait states in a depth expanded memory.

Downloaded from Arrow.com.

Write Operations

Write operations are initiated by asserting $\overline{WPS}$ active at the rising edge of the positive input clock (K). On the same K clock rise the data presented to $D_{[17:0]}$ is latched and stored into the lower 18-bit write data register, provided $\overline{BWS}_{[1:0]}$ are both asserted active. On the subsequent rising edge of the negative input clock ($\overline{K}$), the address is latched and the information presented to $D_{[17:0]}$ is also stored into the write data register, provided $\overline{BWS}_{[1:0]}$ are both asserted active. The 36 bits of data are then written into the memory array at the specified location.

When deselected, the write port ignores all inputs after the pending write operations are completed.

Byte Write Operations

Byte write operations are supported by the CY7C1412KV18. A write operation is initiated as described in the Write Operations section. The bytes that are written are determined by $\overline{BWS}_0$ and $\overline{BWS}_1$, which are sampled with each set of 18-bit data words. Asserting the appropriate byte write select input during the data portion of a write latches the data being presented and writes it into the device. Deasserting the byte write select input during the data portion of a write enables the data stored in the device for that byte to remain unaltered. This feature is used to simplify read, modify, or write operations to a byte write operation.

Concurrent Transactions

The read and write ports on the CY7C1412KV18 operate completely independently of one another. As each port latches the address inputs on different clock edges, the user can read or write to any location, regardless of the transaction on the other port. The user can start reads and writes in the same clock cycle. If the ports access the same location at the same time, the SRAM delivers the most recent information associated with the specified address location. This includes forwarding data from a write cycle that was initiated on the previous K clock rise.

Depth Expansion

The CY7C1412KV18 has a port select input for each port. This enables for easy depth expansion. Both port selects are sampled on the rising edge of the positive input clock only (K). Each port select input can deselect the specified port. Deselecting a port does not affect the other port. All pending transactions (read and write) are completed before the device is deselected.

Programmable Impedance

An external resistor, RQ, must be connected between the ZQ pin on the SRAM and V_{SS} to enable the SRAM to adjust its output driver impedance. The value of RQ must be 5X the value of the intended line impedance driven by the SRAM. The allowable range of RQ to guarantee impedance matching with a tolerance of ±15% is between 175 Ω and 350 Ω, with V_{DDQ} = 1.5 V. The output impedance is adjusted every 1024 cycles upon power-up to account for drifts in supply voltage and temperature.

Echo Clocks

Echo clocks are provided on the QDR II to simplify data capture on high speed systems. Two echo clocks are generated by the QDR II. CQ is referenced with respect to C and $\overline{CQ}$ is referenced with respect to $\overline{C}$. These are free running clocks and are synchronized to the output clock of the QDR II. In the single clock mode, CQ is generated with respect to K and $\overline{CQ}$ is generated with respect to $\overline{K}$. The timing for the echo clocks is shown in Switching Characteristics on page 25.

PLL

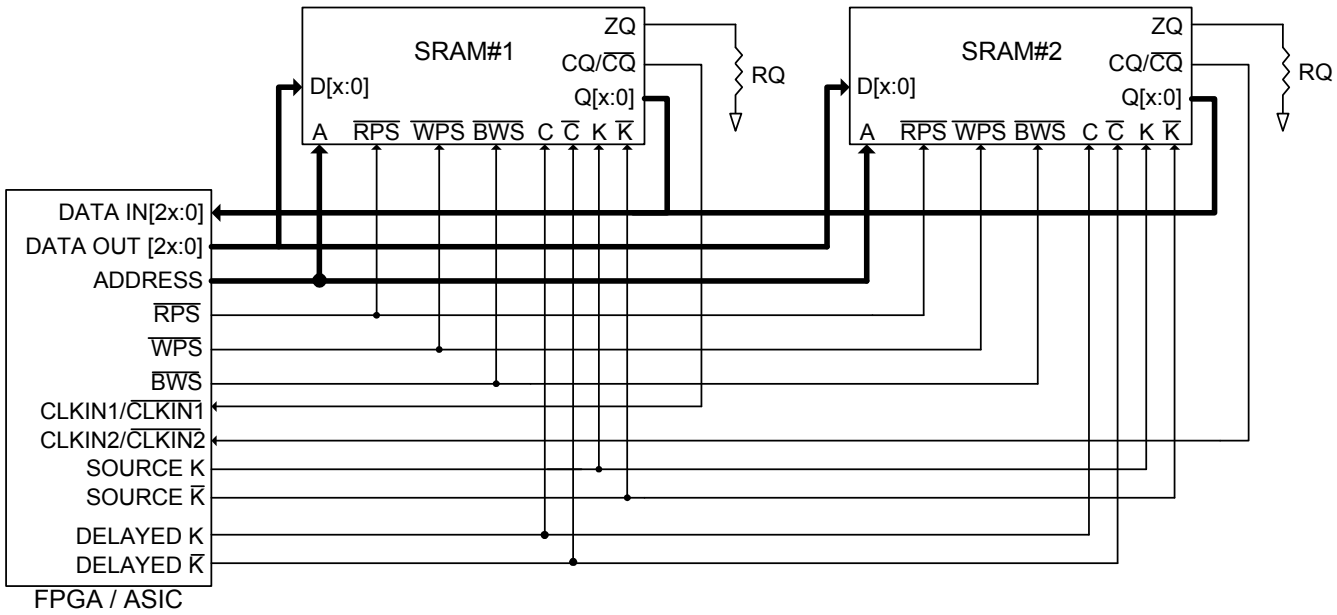
These chips use a PLL which is designed to function between 120 MHz and the specified maximum clock frequency. During power up, when the $\overline{DOFF}$ is tied HIGH, the PLL is locked after 20 µs of stable clock. The PLL can also be reset by slowing or stopping the input clocks K and $\overline{K}$ for a minimum of 30 ns. However, it is not necessary to reset the PLL to lock to the desired frequency. The PLL automatically locks 20 µs after a stable clock is presented. The PLL may be disabled by applying ground to the $\overline{DOFF}$ pin. When the PLL is turned off, the device behaves in QDR I mode (with one cycle latency and a longer access time).

Downloaded from Arrow.com.

Application Example

Figure 2 shows two QDR II used in an application.

Figure 2. Application Example (Width Expansion)



Downloaded from Arrow.com.

Truth Table

The truth table for CY7C1425KV18, CY7C1412KV18, and CY7C1414KV18 follow. [2, 3, 4, 5, 6, 7]

Operation	K	$\overline{RPS}$	$\overline{WPS}$	DQ	DQ
Write cycle: Load address on the rising edge of $\overline{K}$; input write data on K and $\overline{K}$ rising edges.	L–H	X	L	D(A + 0) at K(t) ↑	D(A + 1) at $\overline{K}$(t) ↑
Read cycle: Load address on the rising edge of K; wait one and a half cycle; read data on $\overline{C}$ and C rising edges.	L–H	L	X	Q(A + 0) at $\overline{C}$(t + 1) ↑	Q(A + 1) at C(t + 2) ↑
NOP: No operation	L–H	H	H	D = X Q = high Z	D = X Q = high Z
Standby: Clock stopped	Stopped	X	X	Previous state	Previous state

Write Cycle Descriptions

The write cycle description table for CY7C1412KV18 follow. [2, 8]

$\overline{BWS_0}$	$\overline{BWS_1}$	K	$\overline{K}$	Comments
L	L	L–H	–	During the data portion of a write sequence: CY7C1412KV18 – both bytes ($D_{[17:0]}$) are written into the device.
L	L	–	L–H	During the data portion of a write sequence: CY7C1412KV18 – both bytes ($D_{[17:0]}$) are written into the device.
L	H	L–H	–	During the data portion of a write sequence: CY7C1412KV18 – only the lower byte ($D_{[8:0]}$) is written into the device, $D_{[17:9]}$ remains unaltered.
L	H	–	L–H	During the data portion of a write sequence: CY7C1412KV18 – only the lower byte ($D_{[8:0]}$) is written into the device, $D_{[17:9]}$ remains unaltered.
H	L	L–H	–	During the data portion of a write sequence: CY7C1412KV18 – only the upper byte ($D_{[17:9]}$) is written into the device, $D_{[8:0]}$ remains unaltered.
H	L	–	L–H	During the data portion of a write sequence: CY7C1412KV18 – only the upper byte ($D_{[17:9]}$) is written into the device, $D_{[8:0]}$ remains unaltered.
H	H	L–H	–	No data is written into the devices during this portion of a write operation.
H	H	–	L–H	No data is written into the devices during this portion of a write operation.

Notes
2. X = “Don't Care,” H = Logic HIGH, L = Logic LOW, ↑ represents rising edge.
3. Device powers up deselected with the outputs in a tristate condition.
4. “A” represents address location latched by the devices when transaction was initiated. A + 0, A + 1 represents the internal address sequence in the burst.
5. “t” represents the cycle at which a read/write operation is started. t + 1, and t + 2 are the first, and second clock cycles respectively succeeding the “t” clock cycle.
6. Data inputs are registered at K and $\overline{K}$ rising edges. Data outputs are delivered on C and $\overline{C}$ rising edges, except when in single clock mode.
7. Ensure that when the clock is stopped K = K and C = C = HIGH. This is not essential, but permits most rapid restart by overcoming transmission line charging symmetrically.
8. Is based on a write cycle that was initiated in accordance with the Truth Table. $\overline{BWS_0}$, $\overline{BWS_1}$, $\overline{BWS_2}$, and $\overline{BWS_3}$ can be altered on different portions of a write cycle, as long as the setup and hold requirements are achieved.

Downloaded from Arrow.com.

Write Cycle Descriptions

The write cycle description table for CY7C1425KV18 follow. [9, 10]

$\overline{BWS_0}$	K	$\overline{K}$	Comments
L	L–H	–	During the data portion of a write sequence, the single byte ($D_{[8:0]}$) is written into the device.
L	–	L–H	During the data portion of a write sequence, the single byte ($D_{[8:0]}$) is written into the device.
H	L–H	–	No data is written into the device during this portion of a write operation.
H	–	L–H	No data is written into the device during this portion of a write operation.

Write Cycle Descriptions

The write cycle description table for CY7C1414KV18 follow. [9, 10]

$\overline{BWS_0}$	$\overline{BWS_1}$	$\overline{BWS_2}$	$\overline{BWS_3}$	K	$\overline{K}$	Comments
L	L	L	L	L–H	–	During the data portion of a write sequence, all four bytes ($D_{[35:0]}$) are written into the device.
L	L	L	L	–	L–H	During the data portion of a write sequence, all four bytes ($D_{[35:0]}$) are written into the device.
L	H	H	H	L–H	–	During the data portion of a write sequence, only the lower byte ($D_{[8:0]}$) is written into the device. $D_{[35:9]}$ remains unaltered.
L	H	H	H	–	L–H	During the data portion of a write sequence, only the lower byte ($D_{[8:0]}$) is written into the device. $D_{[35:9]}$ remains unaltered.
H	L	H	H	L–H	–	During the data portion of a write sequence, only the byte ($D_{[17:9]}$) is written into the device. $D_{[8:0]}$ and $D_{[35:18]}$ remains unaltered.
H	L	H	H	–	L–H	During the data portion of a write sequence, only the byte ($D_{[17:9]}$) is written into the device. $D_{[8:0]}$ and $D_{[35:18]}$ remains unaltered.
H	H	L	H	L–H	–	During the data portion of a write sequence, only the byte ($D_{[26:18]}$) is written into the device. $D_{[17:0]}$ and $D_{[35:27]}$ remains unaltered.
H	H	L	H	–	L–H	During the data portion of a write sequence, only the byte ($D_{[26:18]}$) is written into the device. $D_{[17:0]}$ and $D_{[35:27]}$ remains unaltered.
H	H	H	L	L–H	–	During the data portion of a write sequence, only the byte ($D_{[35:27]}$) is written into the device. $D_{[26:0]}$ remains unaltered.
H	H	H	L	–	L–H	During the data portion of a write sequence, only the byte ($D_{[35:27]}$) is written into the device. $D_{[26:0]}$ remains unaltered.
H	H	H	H	L–H	–	No data is written into the device during this portion of a write operation.
H	H	H	H	–	L–H	No data is written into the device during this portion of a write operation.

Notes
9. X = "Don't Care," H = Logic HIGH, L = Logic LOW, ↑represents rising edge.
10. Is based on a write cycle that was initiated in accordance with the Truth Table on page 11. $\overline{BWS_0}$, $\overline{BWS_1}$, $\overline{BWS_2}$, and $\overline{BWS_3}$ can be altered on different portions of a write cycle, as long as the setup and hold requirements are achieved.

Downloaded from Arrow.com.

IEEE 1149.1 Serial Boundary Scan (JTAG)

These SRAMs incorporate a serial boundary scan test access port (TAP) in the FBGA package. This part is fully compliant with IEEE Standard #1149.1-2001. The TAP operates using JEDEC standard 1.8 V I/O logic levels.

Disabling the JTAG Feature

It is possible to operate the SRAM without using the JTAG feature. To disable the TAP controller, TCK must be tied LOW (V_{SS}) to prevent clocking of the device. TDI and TMS are internally pulled up and may be unconnected. They may alternatively be connected to V_{DD} through a pull-up resistor. TDO must be left unconnected. Upon power-up, the device comes up in a reset state, which does not interfere with the operation of the device.

Test Access Port

Test Clock

The test clock is used only with the TAP controller. All inputs are captured on the rising edge of TCK. All outputs are driven from the falling edge of TCK.

Test Mode Select (TMS)

The TMS input is used to give commands to the TAP controller and is sampled on the rising edge of TCK. This pin may be left unconnected if the TAP is not used. The pin is pulled up internally, resulting in a logic HIGH level.

Test Data-In (TDI)

The TDI pin is used to serially input information into the registers and can be connected to the input of any of the registers. The register between TDI and TDO is chosen by the instruction that is loaded into the TAP instruction register. For information about loading the instruction register, see the TAP Controller State Diagram on page 15. TDI is internally pulled up and can be unconnected if the TAP is unused in an application. TDI is connected to the most significant bit (MSB) on any register.

Test Data-Out (TDO)

The TDO output pin is used to serially clock data out from the registers. The output is active, depending upon the current state of the TAP state machine (see Instruction Codes on page 19). The output changes on the falling edge of TCK. TDO is connected to the least significant bit (LSB) of any register.

Performing a TAP Reset

A Reset is performed by forcing TMS HIGH (V_{DD}) for five rising edges of TCK. This Reset does not affect the operation of the SRAM and is performed when the SRAM is operating. At power up, the TAP is reset internally to ensure that TDO comes up in a high Z state.

TAP Registers

Registers are connected between the TDI and TDO pins to scan the data in and out of the SRAM test circuitry. Only one register can be selected at a time through the instruction registers. Data is serially loaded into the TDI pin on the rising edge of TCK. Data is output on the TDO pin on the falling edge of TCK.

Instruction Register

Three-bit instructions are serially loaded into the instruction register. This register is loaded when it is placed between the TDI and TDO pins, as shown in TAP Controller Block Diagram on page 16. Upon power-up, the instruction register is loaded with the IDCODE instruction. It is also loaded with the IDCODE instruction if the controller is placed in a reset state, as described in the previous section.

When the TAP controller is in the Capture-IR state, the two least significant bits are loaded with a binary “01” pattern to enable fault isolation of the board level serial test path.

Bypass Register

To save time when serially shifting data through registers, it is sometimes advantageous to skip certain chips. The bypass register is a single-bit register that can be placed between TDI and TDO pins. This enables shifting of data through the SRAM with minimal delay. The bypass register is set LOW (V_{SS}) when the BYPASS instruction is executed.

Boundary Scan Register

The boundary scan register is connected to all of the input and output pins on the SRAM. Several No Connect (NC) pins are also included in the scan register to reserve pins for higher density devices.

The boundary scan register is loaded with the contents of the RAM input and output ring when the TAP controller is in the Capture-DR state and is then placed between the TDI and TDO pins when the controller is moved to the Shift-DR state. The EXTEST, SAMPLE/PRELOAD, and SAMPLE Z instructions are used to capture the contents of the input and output ring.

The Boundary Scan Order on page 20 shows the order in which the bits are connected. Each bit corresponds to one of the bumps on the SRAM package. The MSB of the register is connected to TDI, and the LSB is connected to TDO.

Identification (ID) Register

The ID register is loaded with a vendor-specific, 32-bit code during the Capture-DR state when the IDCODE command is loaded in the instruction register. The IDCODE is hardwired into the SRAM and can be shifted out when the TAP controller is in the Shift-DR state. The ID register has a vendor code and other information described in Identification Register Definitions on page 19.

TAP Instruction Set

Eight different instructions are possible with the three-bit instruction register. All combinations are listed in Instruction Codes on page 19. Three of these instructions are listed as RESERVED and must not be used. The other five instructions are described in this section in detail.

Instructions are loaded into the TAP controller during the Shift-IR state when the instruction register is placed between TDI and TDO. During this state, instructions are shifted through the instruction register through the TDI and TDO pins. To execute the instruction after it is shifted in, the TAP controller must be moved into the Update-IR state.

Downloaded from Arrow.com.

IDCODE

The IDCODE instruction loads a vendor-specific, 32-bit code into the instruction register. It also places the instruction register between the TDI and TDO pins and shifts the IDCODE out of the device when the TAP controller enters the Shift-DR state. The IDCODE instruction is loaded into the instruction register at power up or whenever the TAP controller is supplied a Test-Logic-Reset state.

SAMPLE Z

The SAMPLE Z instruction connects the boundary scan register between the TDI and TDO pins when the TAP controller is in a Shift-DR state. The SAMPLE Z command puts the output bus into a high Z state until the next command is supplied during the Update IR state.

SAMPLE/PRELOAD

SAMPLE/PRELOAD is a 1149.1 mandatory instruction. When the SAMPLE/PRELOAD instructions are loaded into the instruction register and the TAP controller is in the Capture-DR state, a snapshot of data on the input and output pins is captured in the boundary scan register.

The TAP controller clock can only operate at a frequency up to 20 MHz, while the SRAM clock operates more than an order of magnitude faster. Because there is a large difference in the clock frequencies, it is possible that during the Capture-DR state, an input or output undergoes a transition. The TAP may then try to capture a signal while in transition (metastable state). This does not harm the device, but there is no guarantee as to the value that is captured. Repeatable results may not be possible.

To guarantee that the boundary scan register captures the correct value of a signal, the SRAM signal must be stabilized long enough to meet the TAP controller's capture setup plus hold times (t_{CS} and t_{CH}). The SRAM clock input might not be captured correctly if there is no way in a design to stop (or slow) the clock during a SAMPLE/PRELOAD instruction. If this is an issue, it is still possible to capture all other signals and simply ignore the value of the CK and $\overline{CK}$ captured in the boundary scan register.

After the data is captured, it is possible to shift out the data by putting the TAP into the Shift-DR state. This places the boundary scan register between the TDI and TDO pins.

PRELOAD places an initial data pattern at the latched parallel outputs of the boundary scan register cells before the selection of another boundary scan test operation.

The shifting of data for the SAMPLE and PRELOAD phases can occur concurrently when required, that is, while the data captured is shifted out, the preloaded data can be shifted in.

BYPASS

When the BYPASS instruction is loaded in the instruction register and the TAP is placed in a Shift-DR state, the bypass register is placed between the TDI and TDO pins. The advantage of the BYPASS instruction is that it shortens the boundary scan path when multiple devices are connected together on a board.

EXTEST

The EXTEST instruction drives the preloaded data out through the system output pins. This instruction also connects the boundary scan register for serial access between the TDI and TDO in the Shift-DR controller state.

EXTEST OUTPUT BUS TRISTATE

IEEE Standard 1149.1 mandates that the TAP controller be able to put the output bus into a tristate mode.

The boundary scan register has a special bit located at bit #108. When this scan cell, called the "extest output bus tristate," is latched into the preload register during the Update-DR state in the TAP controller, it directly controls the state of the output (Q-bus) pins, when the EXTEST is entered as the current instruction. When HIGH, it enables the output buffers to drive the output bus. When LOW, this bit places the output bus into a high Z condition.

This bit is set by entering the SAMPLE/PRELOAD or EXTEST command, and then shifting the desired bit into that cell, during the Shift-DR state. During Update-DR, the value loaded into that shift-register cell latches into the preload register. When the EXTEST instruction is entered, this bit directly controls the output Q-bus pins. Note that this bit is pre-set LOW to enable the output when the device is powered up, and also when the TAP controller is in the Test-Logic-Reset state.

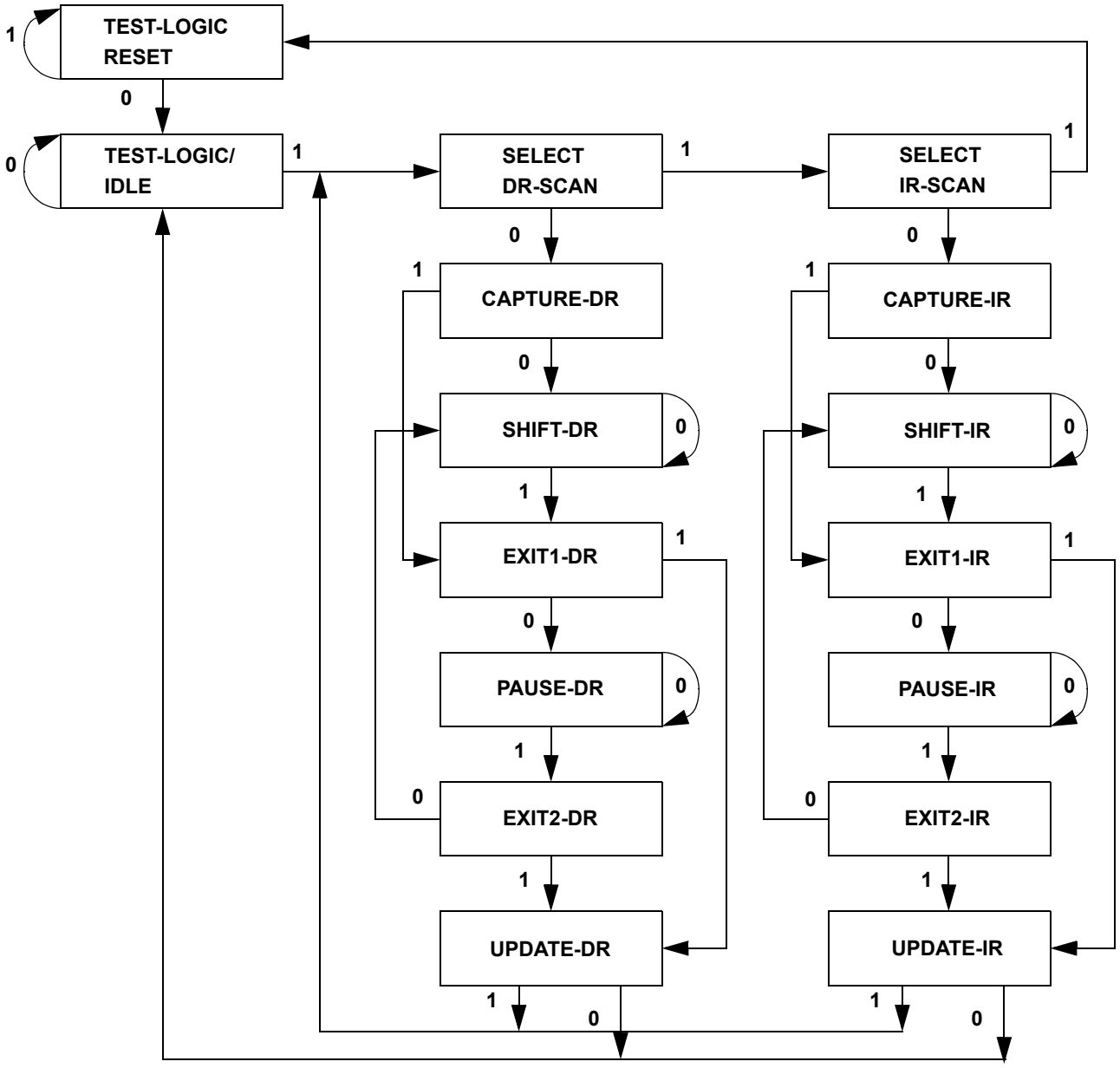
Reserved

These instructions are not implemented but are reserved for future use. Do not use these instructions.

Downloaded from Arrow.com.

TAP Controller State Diagram

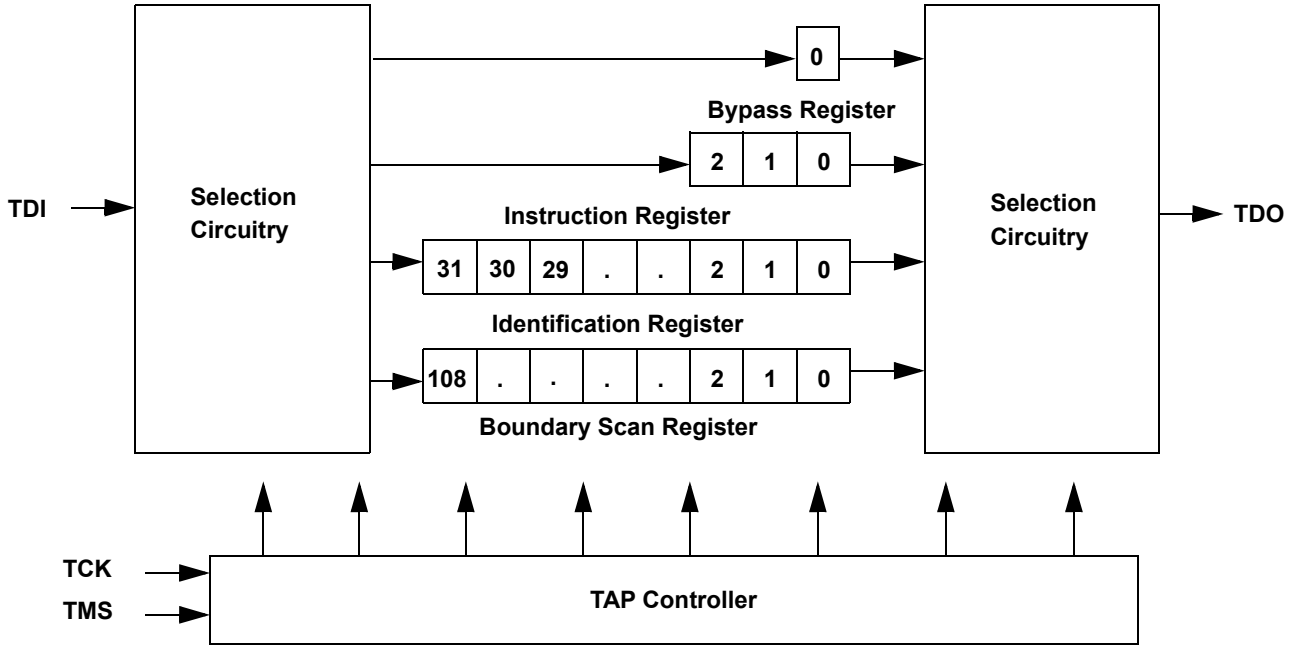
The state diagram for the TAP controller follows. [11]



Note
11. The 0/1 next to each state represents the value at TMS at the rising edge of TCK.

Downloaded from Arrow.com.

TAP Controller Block Diagram



TAP Electrical Characteristics

Over the Operating Range

Parameter [12, 13, 14]	Description	Test Conditions	Min	Max	Unit
V_{OH1}	Output HIGH voltage	I_{OH} = –2.0 mA	1.4	–	V
V_{OH2}	Output HIGH voltage	I_{OH} = –100 µA	1.6	–	V
V_{OL1}	Output LOW voltage	I_{OL} = 2.0 mA	–	0.4	V
V_{OL2}	Output LOW voltage	I_{OL} = 100 µA	–	0.2	V
V_{IH}	Input HIGH voltage		0.65 × V_{DD}	V_{DD} + 0.3	V
V_{IL}	Input LOW voltage		–0.3	0.35 × V_{DD}	V
I_X	Input and output load current	GND ≤ V_I ≤ V_{DD}	–5	5	µA

Notes
12. These characteristics pertain to the TAP inputs (TMS, TCK, TDI and TDO). Parallel load levels are specified in the Electrical Characteristics on page 22.
13. Overshoot: $V_{IH(AC)}$ < V_{DDQ} + 0.85 V (Pulse width less than $t_{CYC}/2$), Undershoot: $V_{IL(AC)}$ > –1.5 V (Pulse width less than $t_{CYC}/2$).
14. All voltage referenced to Ground.

Downloaded from Arrow.com.

TAP AC Switching Characteristics

Over the Operating Range

Parameter [15, 16]	Description	Min	Max	Unit
t_{TCYC}	TCK clock cycle time	50	–	ns
t_{TF}	TCK clock frequency	–	20	MHz
t_{TH}	TCK clock HIGH	20	–	ns
t_{TL}	TCK clock LOW	20	–	ns
Setup Times				
t_{TMSS}	TMS setup to TCK clock rise	5	–	ns
t_{TDIS}	TDI setup to TCK clock rise	5	–	ns
t_{CS}	Capture setup to TCK rise	5	–	ns
Hold Times				
t_{TMSH}	TMS hold after TCK clock rise	5	–	ns
t_{TDIH}	TDI hold after clock rise	5	–	ns
t_{CH}	Capture hold after clock rise	5	–	ns
Output Times				
t_{TDOV}	TCK clock LOW to TDO valid	–	10	ns
t_{TDOX}	TCK clock LOW to TDO invalid	0	–	ns

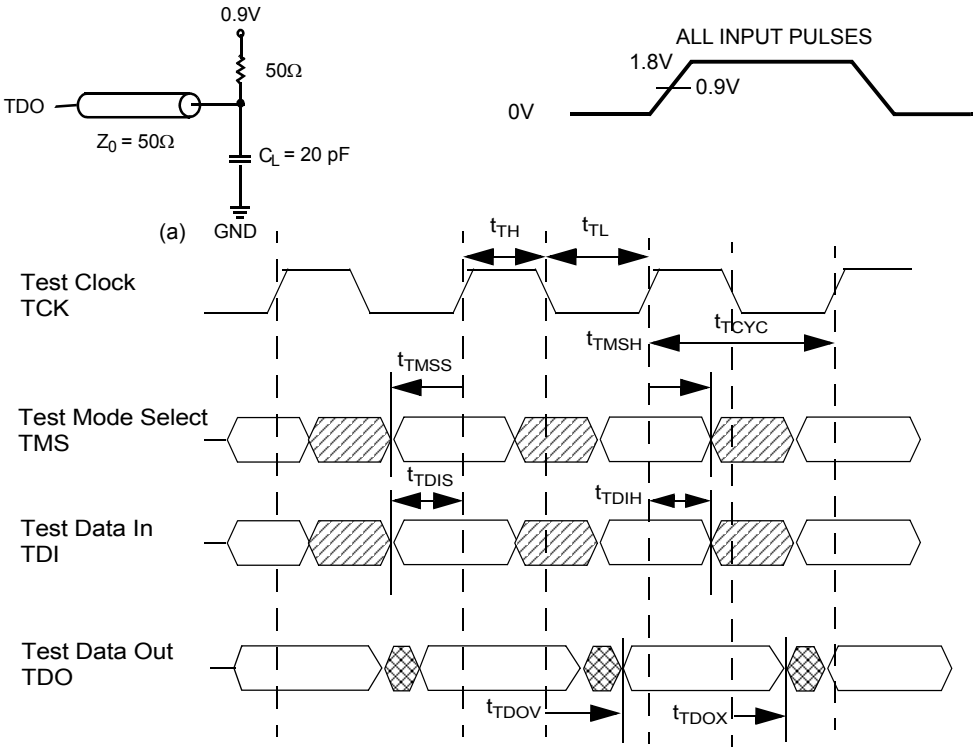
Notes
15. t_{CS} and t_{CH} refer to the setup and hold time requirements of latching data from the boundary scan register.
16. Test conditions are specified using the load in TAP AC Test Conditions. t_R/t_F = 1 ns.

Downloaded from Arrow.com.

TAP Timing and Test Conditions

Figure 3 shows the TAP timing and test conditions. [17]

Figure 3. TAP Timing and Test Conditions



Note
17. Test conditions are specified using the load in TAP AC Test Conditions. t_R/t_F = 1 ns.

Downloaded from Arrow.com.

Identification Register Definitions

Instruction Field	Value			Description
	CY7C1425KV18	CY7C1412KV18	CY7C1414KV18	
Revision number (31:29)	000	000	000	Version number.
Cypress device ID (28:12)	11010011010001111	11010011010010111	11010011010100111	Defines the type of SRAM.
Cypress JEDEC ID (11:1)	00000110100	00000110100	00000110100	Allows unique identification of SRAM vendor.
ID register presence (0)	1	1	1	Indicates the presence of an ID register.

Scan Register Sizes

Register Name	Bit Size
Instruction	3
Bypass	1
ID	32
Boundary scan	109

Instruction Codes

Instruction	Code	Description
EXTEST	000	Captures the input and output ring contents.
IDCODE	001	Loads the ID register with the vendor ID code and places the register between TDI and TDO. This operation does not affect SRAM operation.
SAMPLE Z	010	Captures the input and output contents. Places the boundary scan register between TDI and TDO. Forces all SRAM output drivers to a high Z state.
RESERVED	011	Do Not Use: This instruction is reserved for future use.
SAMPLE/PRELOAD	100	Captures the input and output contents. Places the boundary scan register between TDI and TDO. Does not affect the SRAM operation.
RESERVED	101	Do Not Use: This instruction is reserved for future use.
RESERVED	110	Do Not Use: This instruction is reserved for future use.
BYPASS	111	Places the bypass register between TDI and TDO. This operation does not affect SRAM operation.

Downloaded from Arrow.com.

Boundary Scan Order

Bit #	Bump ID
0	6R
1	6P
2	6N
3	7P
4	7N
5	7R
6	8R
7	8P
8	9R
9	11P
10	10P
11	10N
12	9P
13	10M
14	11N
15	9M
16	9N
17	11L
18	11M
19	9L
20	10L
21	11K
22	10K
23	9J
24	9K
25	10J
26	11J
27	11H

Bit #	Bump ID
28	10G
29	9G
30	11F
31	11G
32	9F
33	10F
34	11E
35	10E
36	10D
37	9E
38	10C
39	11D
40	9C
41	9D
42	11B
43	11C
44	9B
45	10B
46	11A
47	10A
48	9A
49	8B
50	7C
51	6C
52	8A
53	7A
54	7B
55	6B

Bit #	Bump ID
56	6A
57	5B
58	5A
59	4A
60	5C
61	4B
62	3A
63	2A
64	1A
65	2B
66	3B
67	1C
68	1B
69	3D
70	3C
71	1D
72	2C
73	3E
74	2D
75	2E
76	1E
77	2F
78	3F
79	1G
80	1F
81	3G
82	2G
83	1H

Bit #	Bump ID
84	1J
85	2J
86	3K
87	3J
88	2K
89	1K
90	2L
91	3L
92	1M
93	1L
94	3N
95	3M
96	1N
97	2M
98	3P
99	2N
100	2P
101	1P
102	3R
103	4R
104	4P
105	5P
106	5N
107	5R
108	Internal

Downloaded from Arrow.com.

Power Up Sequence in QDR II SRAM

QDR II SRAMs must be powered up and initialized in a predefined manner to prevent undefined operations.

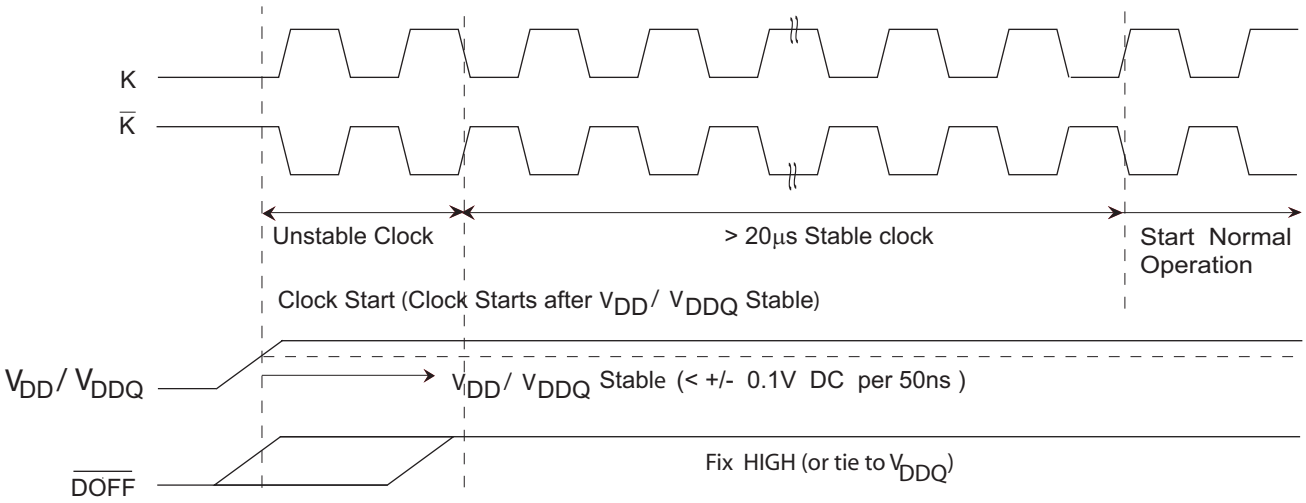
Power Up Sequence

- Apply power and drive $\overline{DOFF}$ either HIGH or LOW (All other inputs can be HIGH or LOW).
  - Apply V_{DD} before V_{DDQ}.
  - Apply V_{DDQ} before V_{REF} or at the same time as V_{REF}.
  - Drive $\overline{DOFF}$ HIGH.
- Provide stable $\overline{DOFF}$ (HIGH), power and clock (K, $\overline{K}$) for 20 µs to lock the PLL.

PLL Constraints

- PLL uses K clock as its synchronizing input. The input must have low phase jitter, which is specified as $t_{KC\ Var}$.
- The PLL functions at frequencies down to 120 MHz.
- If the input clock is unstable and the PLL is enabled, then the PLL may lock onto an incorrect frequency, causing unstable SRAM behavior. To avoid this, provide 20 µs of stable clock to relock to the desired clock frequency.

Figure 4. Power Up Waveforms



Downloaded from Arrow.com.

Maximum Ratings

Exceeding maximum ratings may impair the useful life of the device. These user guidelines are not tested.

Storage temperature ..... –65 °C to +150 °C

Ambient temperature with power applied ..... –55 °C to +125 °C

Supply voltage on V_{DD} relative to GND .....–0.5 V to +2.9 V

Supply voltage on V_{DDQ} relative to GND ..... –0.5 V to +V_{DD}

DC applied to outputs in high Z .....–0.5 V to V_{DDQ} + 0.5 V

DC input voltage [18] .....–0.5 V to V_{DD} + 0.5 V

Current into outputs (LOW) ..... 20 mA

Static discharge voltage (MIL-STD-883, M. 3015) ..... > 2001 V

Latch-up current ..... > 200 mA

Operating Range

Range	Ambient Temperature (T_A)	V_{DD}[19]	V_{DDQ}[19]
Commercial	0 °C to +70 °C	1.8 ± 0.1 V	1.4 V to V_{DD}
Industrial	–40 °C to +85 °C		

Neutron Soft Error Immunity

Parameter	Description	Test Conditions	Typ	Max*	Unit
LSBU	Logical single-bit upsets	25 °C	197	216	FIT/Mb
LMBU	Logical Multi-Bit upsets	25 °C	0	0.01	FIT/Mb
SEL	Single event latchup	85 °C	0	0.1	FIT/Dev

* *No LMBU or SEL events occurred during testing*; this column represents a statistical χ^2, 95% confidence limit calculation. For more details refer to Application Note AN54908 "Accelerated Neutron SER Testing and Calculation of Terrestrial Failure Rates".

Electrical Characteristics

Over the Operating Range

DC Electrical Characteristics

Over the Operating Range

Parameter [20]	Description	Test Conditions	Min	Typ	Max	Unit
V_{DD}	Power supply voltage		1.7	1.8	1.9	V
V_{DDQ}	I/O supply voltage		1.4	1.5	V_{DD}	V
V_{OH}	Output HIGH voltage	Note 21	$V_{DDQ}/2 - 0.12$	–	$V_{DDQ}/2 + 0.12$	V
V_{OL}	Output LOW voltage	Note 22	$V_{DDQ}/2 - 0.12$	–	$V_{DDQ}/2 + 0.12$	V
$V_{OH(LOW)}$	Output HIGH voltage	I_{OH} = –0.1 mA, nominal impedance	$V_{DDQ} - 0.2$	–	V_{DDQ}	V
$V_{OL(LOW)}$	Output LOW voltage	I_{OL} = 0.1 mA, nominal impedance	V_{SS}	–	0.2	V
V_{IH}	Input HIGH voltage		$V_{REF} + 0.1$	–	$V_{DDQ} + 0.3$	V
V_{IL}	Input LOW voltage		–0.3	–	$V_{REF} - 0.1$	V
I_X	Input leakage current	$GND \le V_I \le V_{DDQ}$	–5	–	5	µA
I_{OZ}	Output leakage current	$GND \le V_I \le V_{DDQ}$, output disabled	–5	–	5	µA
V_{REF}	Input reference voltage [23]	Typical value = 0.75 V	0.68	0.75	0.95	V

Notes

18. Overshoot: $V_{IH(AC)} < V_{DDQ} + 0.85$ V (Pulse width less than $t_{CYC}/2$), Undershoot: $V_{IL(AC)} > -1.5$ V (Pulse width less than $t_{CYC}/2$).
19. Power-up: Assumes a linear ramp from 0 V to $V_{DD(min)}$ within 200 ms. During this time $V_{IH} < V_{DD}$ and $V_{DDQ} \le V_{DD}$.
20. All voltage referenced to Ground.
21. Output are impedance controlled. $I_{OH} = -(V_{DDQ}/2)/(RQ/5)$ for values of $175\ \Omega \le RQ \le 350\ \Omega$.
22. Output are impedance controlled. $I_{OL} = (V_{DDQ}/2)/(RQ/5)$ for values of $175\ \Omega \le RQ \le 350\ \Omega$.
23. $V_{REF(min)}$ = 0.68 V or 0.46 V_{DDQ}, whichever is larger, $V_{REF(max)}$ = 0.95 V or 0.54 V_{DDQ}, whichever is smaller.

Downloaded from Arrow.com.

Electrical Characteristics *(continued)*

Over the Operating Range

DC Electrical Characteristics *(continued)*

Over the Operating Range

Parameter [20]	Description	Test Conditions			Min	Typ	Max	Unit
I_{DD} [24]	V_{DD} operating supply	V_{DD} = Max, I_{OUT} = 0 mA, f = f_{MAX} = 1/t_{CYC}	333 MHz	(× 9)	–	–	730	mA
				(× 18)	–	–	750	
				(× 36)	–	–	910	
			300 MHz	(× 9)	–	–	680	mA
				(× 18)	–	–	700	
				(× 36)	–	–	850	
			250 MHz	(× 9)	–	–	590	mA
				(× 18)	–	–	610	
				(× 36)	–	–	730	
I_{SB1}	Automatic power-down current	Max V_{DD}, both ports deselected, $V_{IN} \geq V_{IH}$ or $V_{IN} \leq V_{IL}$ f = f_{MAX} = 1/t_{CYC}, Inputs Static	333 MHz	(× 9)	–	–	280	mA
				(× 18)	–	–	280	
				(× 36)	–	–	280	
			300 MHz	(× 9)	–	–	270	mA
				(× 18)	–	–	270	
				(× 36)	–	–	270	
			250 MHz	(× 9)	–	–	260	mA
				(× 18)	–	–	260	
				(× 36)	–	–	260	

Note
24. The operation current is calculated with 50% read cycle and 50% write cycle.

Downloaded from Arrow.com.

AC Electrical Characteristics

Over the Operating Range

Parameter [25]	Description	Test Conditions	Min	Typ	Max	Unit
V_{IH}	Input HIGH voltage		V_{REF} + 0.2	–	–	V
V_{IL}	Input LOW voltage		–	–	V_{REF} – 0.2	V

Capacitance

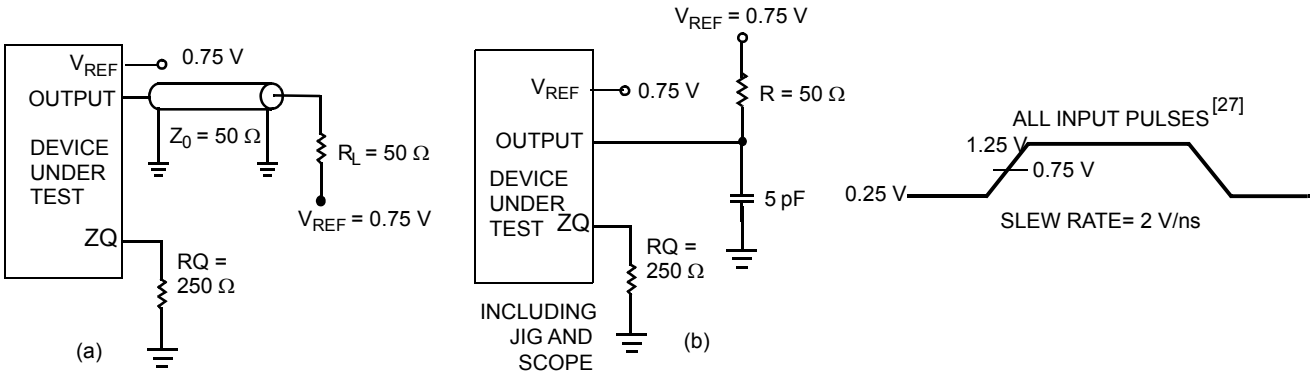
Parameter [26]	Description	Test Conditions	Max	Unit
C_{IN}	Input capacitance	T_A = 25 °C, f = 1 MHz, V_{DD} = 1.8 V, V_{DDQ} = 1.5 V	4	pF
C_O	Output capacitance		4	pF

Thermal Resistance

Parameter [26]	Description	Test Conditions	165-ball FBGA Package	Unit
Θ_{JA} (0 m/s)	Thermal resistance (junction to ambient)	Socketed on a 170 × 220 × 2.35 mm, eight-layer printed circuit board	16.72	°C/W
Θ_{JA} (1 m/s)			15.67	°C/W
Θ_{JA} (3 m/s)			14.92	°C/W
Θ_{JB}	Thermal resistance (junction to board)		13.67	°C/W
Θ_{JC}	Thermal resistance (junction to case)		4.54	°C/W

AC Test Loads and Waveforms

Figure 5. AC Test Loads and Waveforms



Notes

25. Overshoot: $V_{IH(AC)} < V_{DDQ}$ + 0.85 V (Pulse width less than $t_{CYC}/2$), Undershoot: $V_{IL(AC)} > -1.5$ V (Pulse width less than $t_{CYC}/2$).
26. Tested initially and after any design or process change that may affect these parameters.
27. Unless otherwise noted, test conditions are based on signal transition time of 2 V/ns, timing reference levels of 0.75 V, Vref = 0.75 V, RQ = 250 Ω, V_{DDQ} = 1.5 V, input pulse levels of 0.25 V to 1.25 V, and output loading of the specified I_{OL}/I_{OH} and load capacitance shown in (a) of Figure 5.

Downloaded from Arrow.com.

Switching Characteristics

Over the Operating Range

Parameters [28, 29]		Description	333 MHz		300 MHz		250 MHz		Unit
Cypress Parameter	Consortium Parameter		Min	Max	Min	Max	Min	Max	
t_{POWER}		V_{DD}(typical) to the first access [30]	1	–	1	–	1	–	ms
t_{CYC}	t_{KHKH}	K clock and C clock cycle time	3.0	8.4	3.3	8.4	4.0	8.4	ns
t_{KH}	t_{KHKL}	Input clock (K/$\overline{K}$; C/$\overline{C}$) HIGH	1.20	–	1.32	–	1.6	–	ns
t_{KL}	t_{KLKH}	Input clock (K/$\overline{K}$; C/$\overline{C}$) LOW	1.20	–	1.32	–	1.6	–	ns
$t_{KH\overline{K}H}$	$t_{KH\overline{K}H}$	K clock rise to $\overline{K}$ clock rise and C to $\overline{C}$ rise (rising edge to rising edge)	1.35	–	1.49	–	1.8	–	ns
t_{KHCH}	t_{KHCH}	K/$\overline{K}$ clock rise to C/$\overline{C}$ clock rise (rising edge to rising edge)	0	1.30	0	1.45	0	1.8	ns
Setup Times									
t_{SA}	t_{AVKH}	Address set-up to K clock rise	0.3	–	0.3	–	0.35	–	ns
t_{SC}	t_{IVKH}	Control set-up to K clock rise ($\overline{RPS}$, $\overline{WPS}$)	0.3	–	0.3	–	0.35	–	ns
t_{SCDDR}	t_{IVKH}	DDR control set-up to clock (K/$\overline{K}$) rise ($\overline{BWS_0}$, $\overline{BWS_1}$, $\overline{BWS_2}$, $\overline{BWS_3}$)	0.3	–	0.3	–	0.35	–	ns
t_{SD}	t_{DVKH}	$D_{[X:0]}$ set-up to clock (K/$\overline{K}$) rise	0.3	–	0.3	–	0.35	–	ns
Hold Times									
t_{HA}	t_{KHAX}	Address hold after K clock rise	0.3	–	0.3	–	0.35	–	ns
t_{HC}	t_{KHIX}	Control hold after K clock rise ($\overline{RPS}$, $\overline{WPS}$)	0.3	–	0.3	–	0.35	–	ns
t_{HCDDR}	t_{KHIX}	DDR control hold after clock (K/$\overline{K}$) rise ($\overline{BWS_0}$, $\overline{BWS_1}$, $\overline{BWS_2}$, $\overline{BWS_3}$)	0.3	–	0.3	–	0.35	–	ns
t_{HD}	t_{KHDX}	$D_{[X:0]}$ hold after clock (K/$\overline{K}$) rise	0.3	–	0.3	–	0.35	–	ns

Notes

28. Unless otherwise noted, test conditions are based on signal transition time of 2 V/ns, timing reference levels of 0.75 V, Vref = 0.75 V, RQ = 250 Ω, V_{DDQ} = 1.5 V, input pulse levels of 0.25 V to 1.25 V, and output loading of the specified I_{OL}/I_{OH} and load capacitance shown in (a) of Figure 5 on page 24.
29. When a part with a maximum frequency above 250 MHz is operating at a lower clock frequency, it requires the input timings of the frequency range in which it is operated and outputs data with the output timings of that frequency range.
30. This part has a voltage regulator internally; t_{POWER} is the time that the power must be supplied above $V_{DD(minimum)}$ initially before initiating a read or write operation.

Downloaded from Arrow.com.

Switching Characteristics *(continued)*

Over the Operating Range

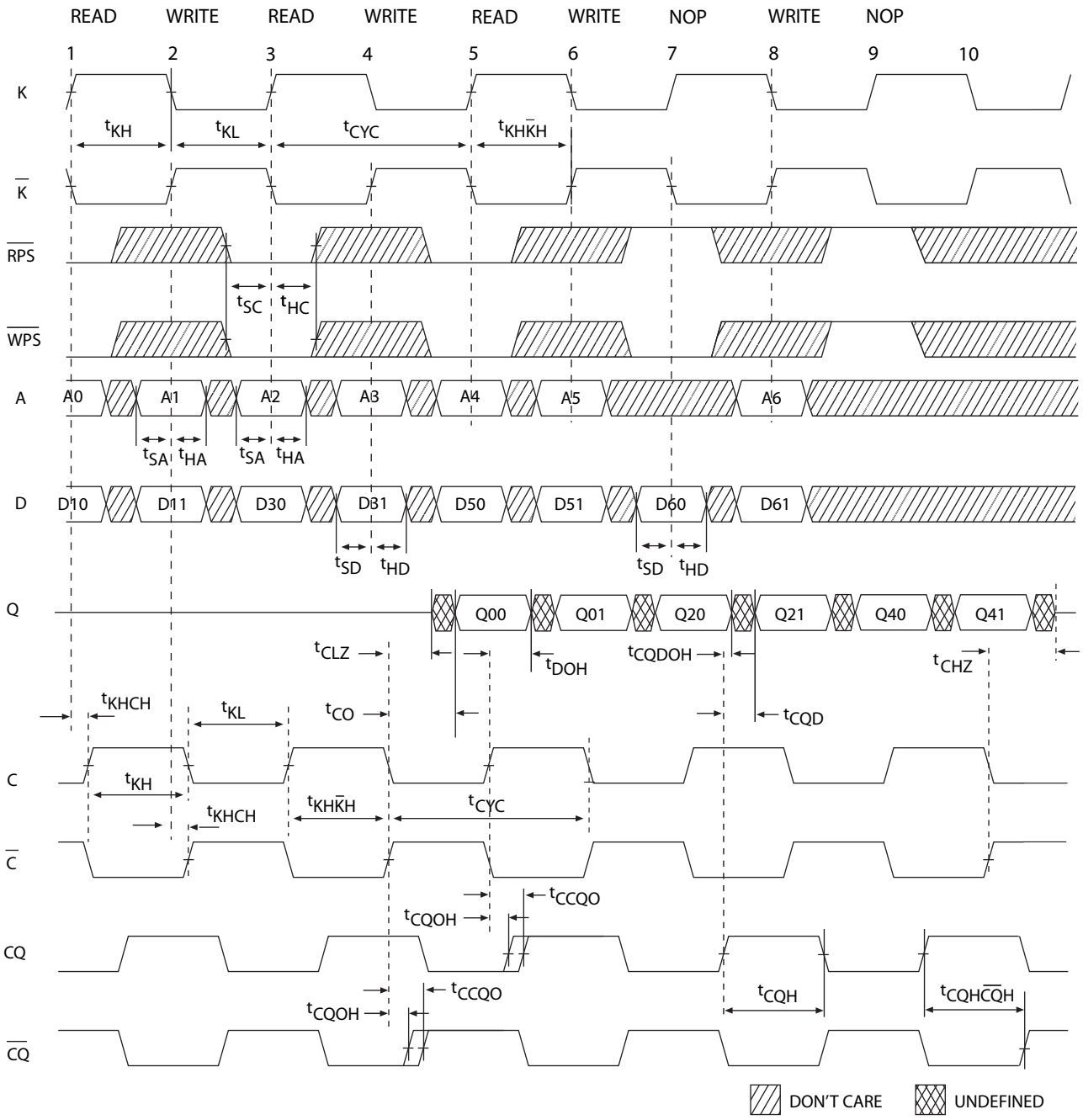
Parameters [28, 29]		Description	333 MHz		300 MHz		250 MHz		Unit
Cypress Parameter	Consortium Parameter		Min	Max	Min	Max	Min	Max	
Output Times									
t_{CO}	t_{CHQV}	C/$\overline{C}$ clock rise (or K/$\overline{K}$ in single clock mode) to data valid	–	0.45	–	0.45	–	0.45	ns
t_{DOH}	t_{CHQX}	Data output hold after output C/$\overline{C}$ clock rise (active to active)	–0.45	–	–0.45	–	–0.45	–	ns
t_{CCQO}	t_{CHCQV}	C/$\overline{C}$ clock rise to echo clock valid	–	0.45	–	0.45	–	0.45	ns
t_{CQOH}	t_{CHCQX}	Echo clock hold after C/$\overline{C}$ clock rise	–0.45	–	–0.45	–	–0.45	–	ns
t_{CQD}	t_{CQHQV}	Echo clock high to data valid		0.25		0.27	–	0.30	ns
t_{CQDOH}	t_{CQHQX}	Echo clock high to data invalid	–0.25	–	–0.27	–	–0.30	–	ns
t_{CQH}	t_{CQHCQL}	Output clock (CQ/$\overline{CQ}$) HIGH [31]	1.25	–	1.40	–	1.75	–	ns
$t_{CQH\overline{CQ}H}$	$t_{CQH\overline{CQ}H}$	CQ clock rise to $\overline{CQ}$ clock rise (rising edge to rising edge) [31]	1.25	–	1.40	–	1.75	–	ns
t_{CHZ}	t_{CHQZ}	Clock (C/$\overline{C}$) rise to high Z (active to high Z) [32, 33]	–	0.45	–	0.45	–	0.45	ns
t_{CLZ}	t_{CHQX1}	Clock (C/$\overline{C}$) rise to low Z [32, 33]	–0.45	–	–0.45	–	–0.45	–	ns
PLL Timing									
$t_{KC\ Var}$	$t_{KC\ Var}$	Clock phase jitter	–	0.20	–	0.20	–	0.20	ns
$t_{KC\ lock}$	$t_{KC\ lock}$	PLL lock time (K, C) [34]	20	–	20	–	20	–	µs
$t_{KC\ Reset}$	$t_{KC\ Reset}$	K static to PLL reset	30	–	30	–	30	–	ns

Notes
31. These parameters are extrapolated from the input timing parameters ($t_{CYC}/2$ – 250 ps, where 250 ps is the internal jitter). These parameters are only guaranteed by design and are not tested in production.
32. t_{CHZ}, t_{CLZ}, are specified with a load capacitance of 5 pF as in part (b) of Figure 5 on page 24. Transition is measured ± 100 mV from steady state voltage.
33. At any voltage and temperature t_{CHZ} is less than t_{CLZ} and t_{CHZ} less than t_{CO}.
34. For frequencies 300 MHz or below, the Cypress QDR II devices surpass the QDR consortium specification for PLL lock time (tKC lock) of 20 µs (min. spec.) and will lock after 1024 clock cycles (min. spec.), after a stable clock is presented, per the previous 90 nm version.

Downloaded from Arrow.com.

Switching Waveforms

Figure 6. Read/Write/Deselect Sequence [35, 36, 37]



Notes
35. Q00 refers to output from address A0. Q01 refers to output from the next internal burst address following A0, that is, A0 + 1.
36. Outputs are disabled (high Z) one clock cycle after a NOP.
37. In this example, if address A0 = A1, then data Q00 = D10 and Q01 = D11. Write data is forwarded immediately as read results. This note applies to the whole diagram.

Downloaded from Arrow.com.

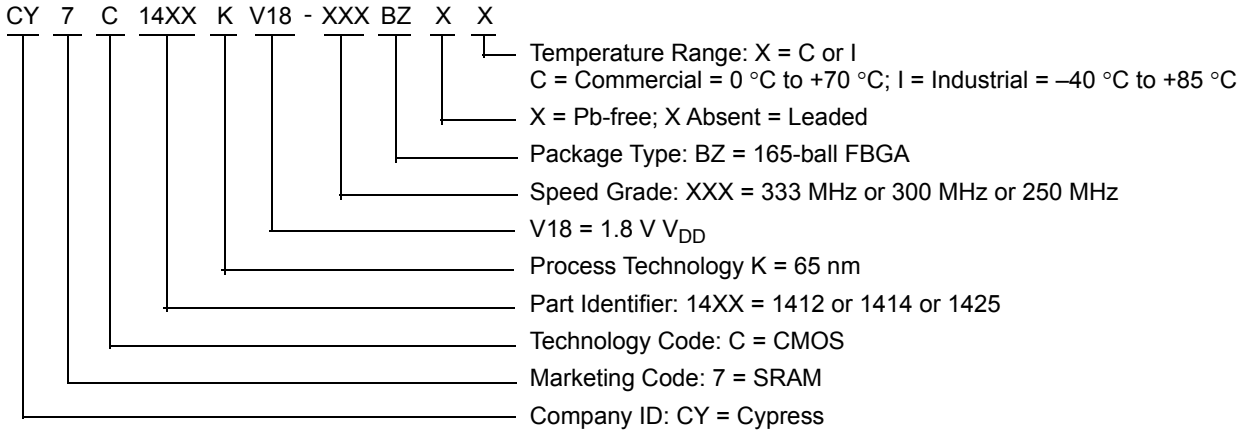
Ordering Information

The following table contains only the parts that are currently available. If you do not see what you are looking for, contact your local sales representative. For more information, visit the Cypress website at www.cypress.com and refer to the product summary page at http://www.cypress.com/products

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives and distributors. To find the office closest to you, visit us at http://www.cypress.com/go/datasheet/offices.

Speed (MHz)	Ordering Code	Package Diagram	Package Type	Operating Range
333	CY7C1412KV18-333BZC	51-85180	165-ball FBGA (13 × 15 × 1.4 mm)	Commercial
	CY7C1414KV18-333BZC			
	CY7C1425KV18-333BZXC		165-ball FBGA (13 × 15 × 1.4 mm) Pb-free	
	CY7C1412KV18-333BZXI			Industrial
	CY7C1414KV18-333BZXI			
300	CY7C1414KV18-300BZC	51-85180	165-ball FBGA (13 × 15 × 1.4 mm)	Commercial
	CY7C1425KV18-300BZXC		165-ball FBGA (13 × 15 × 1.4 mm) Pb-free	
	CY7C1412KV18-300BZXC			
	CY7C1414KV18-300BZXC			
	CY7C1414KV18-300BZXI		165-ball FBGA (13 × 15 × 1.4 mm) Pb-free	Industrial
250	CY7C1425KV18-250BZC	51-85180	165-ball FBGA (13 × 15 × 1.4 mm)	Commercial
	CY7C1412KV18-250BZC			
	CY7C1414KV18-250BZC			
	CY7C1425KV18-250BZXC		165-ball FBGA (13 × 15 × 1.4 mm) Pb-free	
	CY7C1412KV18-250BZXC			
	CY7C1414KV18-250BZXC			
	CY7C1425KV18-250BZI		165-ball FBGA (13 × 15 × 1.4 mm)	Industrial
	CY7C1412KV18-250BZI			
	CY7C1414KV18-250BZI			
	CY7C1425KV18-250BZXI		165-ball FBGA (13 × 15 × 1.4 mm) Pb-free	
	CY7C1412KV18-250BZXI			
	CY7C1414KV18-250BZXI			

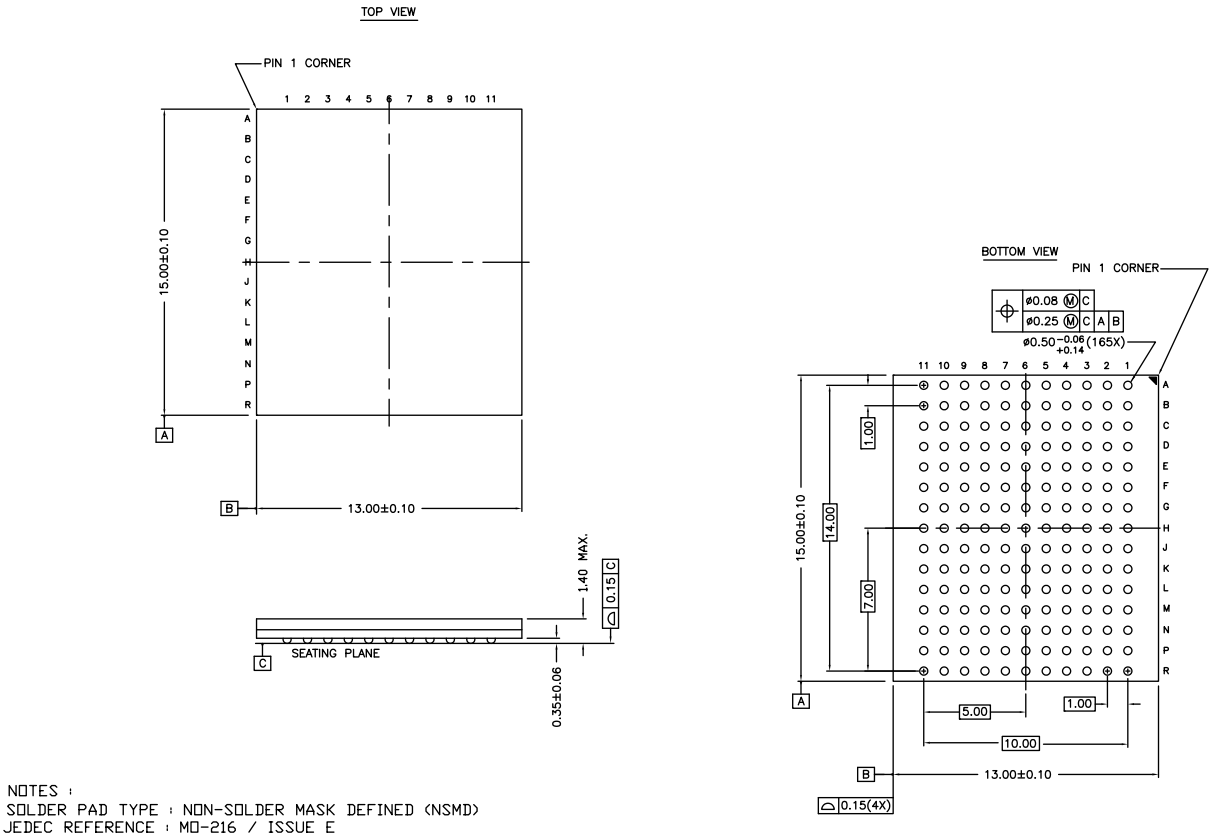
Ordering Code Definitions



Downloaded from Arrow.com.

Package Diagram

Figure 7. 165-ball FBGA (13 × 15 × 1.4 mm) BB165D/BW165D (0.5 Ball Diameter) Package Outline, 51-85180



NOTES :
SOLDER PAD TYPE : NON-SOLDER MASK DEFINED (NSMD)
JEDEC REFERENCE : MO-216 / ISSUE E
PACKAGE CODE : BB0AC/BW0AC
PACKAGE WEIGHT : SEE CYPRESS PACKAGE MATERIAL DECLARATION DATASHEET (PMDD) POSTED ON THE CYPRESS WEB.

51-85180 *G

Downloaded from Arrow.com.

Acronyms

Acronym	Description
DDR	Double Data Rate
FBGA	Fine-Pitch Ball Grid Array
HSTL	High-Speed Transceiver Logic
I/O	Input/Output
JTAG	Joint Test Action Group
LSB	Least Significant Bit
MSB	Most Significant Bit
PLL	Phase Locked Loop
QDR	Quad Data Rate
SRAM	Static Random Access Memory
TAP	Test Access Port
TCK	Test Clock
TDI	Test Data-In
TDO	Test Data-Out
TMS	Test Mode Select

Document Conventions

Units of Measure

Symbol	Unit of Measure
°C	degree Celsius
MHz	megahertz
µA	microampere
µs	microsecond
mA	milliampere
mm	millimeter
ms	millisecond
ns	nanosecond
Ω	ohm
%	percent
pF	picofarad
V	volt
W	watt

Downloaded from Arrow.com.

Document History Page

Document Title: CY7C1425KV18/CY7C1412KV18/CY7C1414KV18, 36-Mbit QDR® II SRAM Two-Word Burst Architecture Document Number: 001-57825				
Rev.	**ECN No.**	**Orig. of Change**	**Submission Date**	**Description of Change**
**	2816620	VKN / AESA	11/27/2009	New data sheet.
*A	2884865	VKN	02/26/2010	Updated Switching Characteristics (Changed the minimum value of t_{SA} and t_{SC} parameters from 0.7 ns to 0.5 ns for 167 MHz, from 0.6 ns to 0.4 ns for 200 MHz, from 0.5 ns to 0.35 ns for 250 MHz, and from 0.4 ns to 0.3 ns for 333 MHz and 300 MHz).
*B	3018546	NJY	10/21/2010	Changed status from Preliminary to Final. Added Ordering Code Definitions. Minor edits. Updated to new template.
*C	3155124	VIDB	01/27/2011	Updated Switching Characteristics: Added Note 34 and referred the same note in description of $t_{KC\ lock}$ parameter.
*D	3165654	NJY	02/08/2011	Updated Switching Characteristics: Updated Note 34. Updated Ordering Information (Updated part numbers). Added Acronyms and Units of Measure.
*E	3436284	PRIT	11/11/2011	Updated Ordering Information (Updated part numbers).
*F	3549927	PRIT	03/13/2012	Updated Features (Removed CY7C1410KV18 part related information). Updated Configurations (Removed CY7C1410KV18 part related information). Updated Functional Description (Removed CY7C1410KV18 part related information). Updated Selection Guide (Removed 167 MHz and 200 MHz frequencies related information). Removed Logic Block Diagram – CY7C1410KV18. Updated Pin Configurations (Removed CY7C1410KV18 part related information). Updated Pin Definitions (Removed CY7C1410KV18 part related information). Updated Functional Overview (Removed CY7C1410KV18 part related information). Updated Truth Table (Removed CY7C1410KV18 part related information). Updated Write Cycle Descriptions (Removed CY7C1410KV18 part related information). Updated Identification Register Definitions (Removed CY7C1410KV18 part related information). Updated Electrical Characteristics (Updated DC Electrical Characteristics (Removed 167 MHz and 200 MHz frequencies related information)). Updated Switching Characteristics (Removed 167 MHz and 200 MHz frequencies related information, updated Note 29). Updated Ordering Information (Updated part numbers). Updated Package Diagram.
*G	3789642	PRIT	10/22/2012	Updated Package Diagram (spec 51-85180 (Changed revision from *E to *F)).
*H	3860026	PRIT	01/10/2013	Updated Ordering Information (Updated part numbers).
*I	3905088	PRIT	03/20/2013	Updated Ordering Information: Updated part numbers.
*J	4373734	PRIT	05/08/2014	Updated Application Example: Updated Figure 2. Updated Thermal Resistance: Updated values of Θ_{JA} parameter. Included Θ_{JB} parameter and its details. Updated to new template.

Downloaded from Arrow.com.

Document History Page *(continued)*

Document Title: CY7C1425KV18/CY7C1412KV18/CY7C1414KV18, 36-Mbit QDR® II SRAM Two-Word Burst Architecture Document Number: 001-57825				
Rev.	**ECN No.**	**Orig. of Change**	**Submission Date**	**Description of Change**
*K	4567876	PRIT	11/12/2014	Updated Functional Description: Added “For a complete list of related documentation, click here.” at the end. Updated Ordering Information: Updated part numbers.
*L	4621838	PRIT	01/13/2015	Updated Ordering Information (Updated part numbers).
*M	5060318	PRIT	12/22/2015	Updated Package Diagram: spec 51-85180 – Changed revision from *F to *G. Updated to new template. Completing Sunset Review.
*N	5522985	PRIT	11/16/2016	Updated Ordering Information: Updated part numbers. Updated to new template. Completing Sunset Review.
*O	6012085	AESATP12	01/03/2018	Updated logo and copyright.

Downloaded from Arrow.com.

Sales, Solutions, and Legal Information

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at Cypress Locations.

Products

Arm® Cortex® Microcontrollers	cypress.com/arm
Automotive	cypress.com/automotive
Clocks & Buffers	cypress.com/clocks
Interface	cypress.com/interface
Internet of Things	cypress.com/iot
Memory	cypress.com/memory
Microcontrollers	cypress.com/mcu
PSoC	cypress.com/psoc
Power Management ICs	cypress.com/pmic
Touch Sensing	cypress.com/touch
USB Controllers	cypress.com/usb
Wireless Connectivity	cypress.com/wireless

PSoC® Solutions

PSoC 1 | PSoC 3 | PSoC 4 | PSoC 5LP | PSoC 6 MCU

Cypress Developer Community

Community | Projects | Video | Blogs | Training | Components

Technical Support

cypress.com/support

© Cypress Semiconductor Corporation, 2009-2018. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. No computing device can be absolutely secure. Therefore, despite security measures implemented in Cypress hardware or software products, Cypress does not assume any liability arising out of any security breach, such as unauthorized access to or use of a Cypress product. In addition, the products described in these materials may contain design defects or errors known as errata which may cause the product to deviate from published specifications. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably expected to cause the failure of the device or system, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.

Downloaded from Arrow.com.