AD557—SPECIFICATIONS (@ $T_A = 25$ °C, $V_{CC} = 5$ V unless otherwise noted)

RESOLUTION				
			8	Bits
RELATIVE ACCURACY				
0°C to 70°C		±1/2	1	LSB
OUTPUT				
Ranges	0 to 2.56		56	V
Current Source	Internal Passive Pull-Down to Ground ²		mA	
Sink				
	10			
OUTPUT SETTLING TIME ³		0.8	1.5	μs
FULL-SCALE ACCURACY ⁴				
@ 25°C		±1.5	±2.5	LSB
T _{MIN} to T _{MAX}		±2.5	±4.0	LSB
ZERO ERROR				
@ 25°C			±1	LSB
T_{MIN} to T_{MAX}			±3	LSB
MONOTONICITY ⁵				
T_{MIN} to T_{MAX}	Guarant	eed But N	ot Tested	
DIGITAL INPUTS				
T_{MIN} to T_{MAX}				
Input Current			±100	μA
Data Inputs, Voltage				
Bit On—Logic "1"	2.0			V
Bit On—Logic "0"	0		0.8	V
Control Inputs, Voltage On—Logic "1"	2.0			V
On—Logic 1 On—Logic "0"	0		0.8	V
Input Capacitance	"	4	0.0	pF
TIMING ⁶		-		P-
t _w Strobe Pulsewidth	225			ne
T_{MIN} to T_{MAX}	300			ns ns
t _{DH} Data Hold Time	10			ns
T_{MIN} to T_{MAX}	10			ns
t _{DS} Data Setup Time	225			ns
T_{MIN} to T_{MAX}	300			ns
POWER SUPPLY				
Operating Voltage Range (V _{CC})				
2.56 Volt Range	4.5		5.5	V
Current (I _{CC})		15	25	mA
Rejection Ratio			0.03	%/%
POWER DISSIPATION, $V_{CC} = 5 \text{ V}$		75	125	mW
OPERATING TEMPERATURE RANGE	0		70	°C

NOTES

¹Relative Accuracy is defined as the deviation of the code transition points from the ideal transfer point on a straight line from the offset to the full scale of the device. See "Measuring Offset Error" on the AD558 data sheet.

Specifications shown in **boldface** are tested on all production units at electrical test. Specifications subject to change without notice.

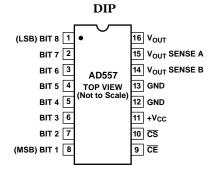
ORDERING GUIDE

Model	Temperature	Package	Package
	Range	Description	Option
		Plastic DIP Plastic Leaded Chip Carrier	N-16 P-20A

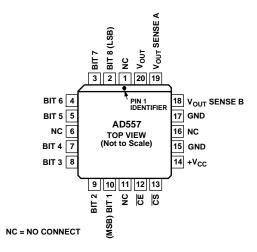
ABSOLUTE MAXIMUM RATINGS*

*Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

PIN CONFIGURATIONS



PLCC



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 $^{^2}Passive$ pull-down resistance is 2 k $\!\Omega.$

 $^{^3}$ Settling time is specified for a positive-going full-scale step to $\pm 1/2$ LSB. Negativegoing steps to zero are slower, but can be improved with an external pull-down. ⁴The full-scale output voltage is 2.55 V and is guaranteed with a 5 V supply.

 $^{^5}$ A monotonic converter has a maximum differential linearity error of ± 1 LSB.

⁶See Figure 7.

CIRCUIT DESCRIPTION

The AD557 consists of four major functional blocks fabricated on a single monolithic chip (see Figure 1). The main D/A converter section uses eight equally weighted laser-trimmed current sources switched into a silicon-chromium thin-film R/2R resistor ladder network to give a direct but unbuffered 0 mV to 400 mV output range. The transistors that form the DAC switches are PNPs; this allows direct positive-voltage logic interface and a zero-based output range.

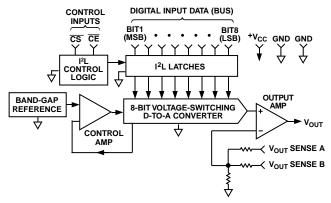


Figure 1. Functional Block Diagram

The high-speed output buffer amplifier is operated in the noninverting mode with gain determined by the user-connections at the output range select pin. The gain-setting application resistors are thin film laser trimmed to match and track the DAC resistors and to assure precise initial calibration of the output range, 0 V to 2.56 V. The amplifier output stage is an NPN transistor with passive pull-down for zero-based output capability with a single power supply.

The internal precision voltage reference is of the patented band-gap type. This design produces a reference voltage of 1.2 V and thus, unlike 6.3 V temperature-compensated Zeners, may be operated from a single, low-voltage logic power supply. The microprocessor interface logic consists of an 8-bit data latch and control circuitry. Low power, small geometry and high speed are advantages of the I^2L design as applied to this section. I^2L is bipolar process compatible so that the performance of the analog sections need not be compromised to provide on-chip logic capabilities. The control logic allows the latches to be operated from a decoded microprocessor address and write signal. If the application does not involve a μP or data bus, wiring \overline{CS} and \overline{CE} to ground renders the latches "transparent" for direct DAC access.

	Output		
Binary	Hexadecimal	Decimal	Voltage
0000 0000	00	0	0
0000 0001	01	1	0.010 V
0000 0010	02	2	0.020 V
0000 1111	0F	15	0.150 V
0001 0000	10	16	0.160 V
0111 1111	7F	127	1.270 V
1000 0000	80	128	1.280 V
1100 0000	C0	192	1.920 V
1111 1111	FF	255	2.55 V

CONNECTING THE AD557

The AD557 has been configured for low cost and ease of application. All reference, output amplifier and logic connections are made internally. In addition, all calibration trims are performed at the factory assuring specified accuracy without user trims. The only connection decision to be made by the user is whether the output range desired is unipolar or bipolar. Clean circuit board layout is facilitated by isolating all digital bit inputs on one side of the package; analog outputs are on the opposite side.

UNIPOLAR 0 V TO 2.56 V OUTPUT RANGE

Figure 2 shows the configuration for the 0 V to 2.56 V full-scale output range. Because of its precise factory calibration, the AD557 is intended to be operated without user trims for gain and offset; therefore, no provisions have been made for such user trims. If a small increase in scale is required, however, it may be accomplished by slightly altering the effective gain of the output buffer. A resistor in series with V_{OUT} SENSE will increase the output range. Note that decreasing the scale by putting a resistor in series with GND will not work properly due to the codedependent currents in GND. Adjusting offset by injecting dc at GND is not recommended for the same reason.

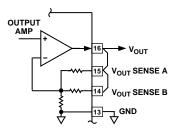


Figure 2. 0 V to 2.56 V Output Range

BIPOLAR -1.28 V TO +1.28 V OUTPUT RANGE

The AD557 was designed for operation from a single power supply and is thus capable of providing only a unipolar 0 V to 2.56 V output range. If a negative supply is available, bipolar output ranges may be achieved by suitable output offsetting and scaling. Figure 3 shows how a ± 1.28 V output range may be achieved when a -5 V power supply is available. The offset is provided by the AD589 precision 1.2 V reference which will operate from a 5 V supply. The AD711 output amplifier can provide the necessary ± 1.28 V output swing from ± 5 V supplies. Coding is complementary offset binary.

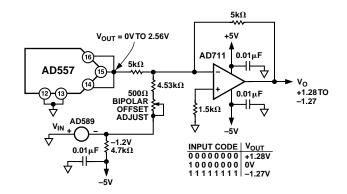


Figure 3. Bipolar Operation of AD557 from ±5 V Supplies

AD557

APPLICATIONS

Grounding and Bypassing

All precision converter products require careful application of good grounding practices to maintain full rated performance. Because the AD557 is intended for application in microcomputer systems where digital noise is prevalent, special care must be taken to assure that its inherent precision is realized.

The AD557 has two ground (common) pins; this minimizes ground drops and noise in the analog signal path. Figure 4 shows how the ground connections should be made.

It is often advisable to maintain separate analog and digital grounds throughout a complete system, tying them common in one place only. If the common tie-point is remote and accidental disconnection of that one common tie-point occurs due to card removal with power on, a large differential voltage between the two commons could develop. To protect devices that interface to both digital and analog parts of the system, such as the AD557, it is recommended that common ground tie-points should be provided at *each* such device. If only one system ground can be connected directly to the AD557, it is recommended that analog common be selected.

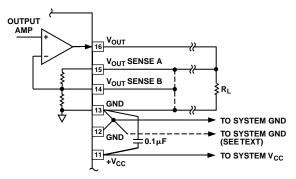


Figure 4. Recommended Grounding and Bypassing

Using a "False" Ground

Many applications, such as disk drives, require servo control voltages that swing on either side of a "false" ground. This ground is usually created by dividing the 12 V supply equally and calling the midpoint voltage "ground."

Figure 5 shows an easy and inexpensive way to implement this. The AD586 is used to provide a stable 5 V reference from the system's 12 V supply. The op amp shown likewise operates from a single (12 V) supply available in the system. The resulting output at the V_{OUT} node is ± 2.5 V around the "false" ground point of 5 V. AD557 input code vs. V_{OUT} is shown in Figure 6.

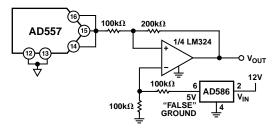


Figure 5. Level Shifting the AD557 Output Around a "False" Ground

Timing and Control

The AD557 has data input latches that simplify interface to 8-and 16-bit data buses. These latches are controlled by Chip Enable (\overline{CE}) and Chip Select (\overline{CS}) inputs. \overline{CE} and \overline{CS} are internally "NORed" so that the latches transmit input data to the DAC section when both \overline{CE} and \overline{CS} are at Logic "0." If the application does not involve a data bus, a "00" condition allows for direct operation of the DAC. When either \overline{CE} or \overline{CS} go to Logic "1," the input data is latched into the registers and held until both \overline{CE} and \overline{CS} return to "0." (Unused \overline{CE} or \overline{CS} inputs should be tied to ground.) The truth table is given in Table I. The logic function is also shown in Figure 6.

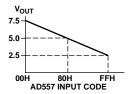


Figure 6. AD557 Input Code vs. Level Shifted Output in a "False" Ground Configuration

Table I. AD557 Control Logic Truth Table

Input Data	CE	CS	DAC Data	Latch Condition
0	0	0	0	"Transparent"
1	0	0	1	"Transparent"
0	-	0	0	Latching
1	.	0	1	Latching
0	0	₹	0	Latching
1	0	.	1	Latching
X	1	X	Previous Data	Latched
X	X	1	Previous Data	Latched

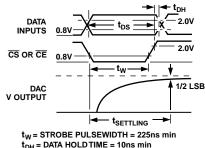
NOTES

X = Does not matter

I = Logic Threshold at Positive-Going Transition

In a level-triggered latch such as that used in the AD557, there is an interaction between the data setup and hold times and the width of the enable pulse. In an effort to reduce the time required to test all possible combinations in production, the AD557 is tested with $t_{DS} = t_W = 225~\text{ns}$ at 25°C and 300 ns at T_{MIN} and T_{MAX} , with $t_{DH} = 10~\text{ns}$ at all temperatures. Failure to comply with these specifications may result in data not being latched properly.

Figure 7 shows the timing for the data and control signals, \overline{CE} and \overline{CS} are identical in timing as well as in function.



 $t_{\rm B}$ = 51KOBE POLSEWITH = 22518 MIN $t_{\rm DH}$ = DATA HOLD TIME = 10ns min $t_{\rm DS}$ = DATA SETUP TIME = 225ns min $t_{\rm SETTLING}$ = DAC SETTLING TIME TO \pm 1/2 LSB

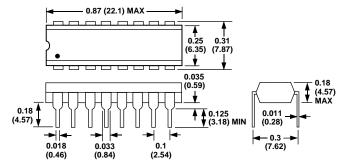
Figure 7. AD557 Timing

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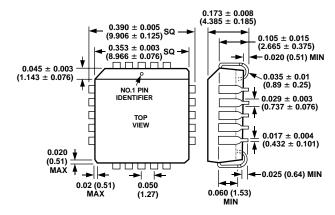
OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).

N-16 (Plastic) Package



P-20A (PLCC) Package



REV. B -5-

AD557–Revision History

Location	Page
Data sheet changed from REV. A to REV. B.	
Changes to MONOTONICITY section of spec. page	2