

# CY14B104NA

# Contents

Pinouts	3
Pin Definitions	4
Device Operation	5
SRAM Read	5
SRAM Write	5
AutoStore Operation	5
Hardware STORE Operation	5
Hardware RECALL (Power-Up)	6
Software STORE	
Software RECALL	
Preventing AutoStore	8
Data Protection	
Maximum Ratings	9
Operating Range	9
DC Electrical Characteristics	-
Data Retention and Endurance	10
Capacitance	
Thermal Resistance	10
AC Test Loads	11
AC Test Conditions	11
AC Switching Characteristics	
Switching Waveforms	13

AutoStore/Power-Up RECALL	. 16
Switching Waveforms –	
AutoStore/Power-up RECALL	.16
Software Controlled STORE/RECALL Cycle	. 17
Switching Waveforms –	
Software Controlled STORE/RECALL Cycle	. 17
Hardware STORE Cycle	.18
Switching Waveforms – Hardware STORE Cycle	
Truth Table For SRAM Operations	. 19
Ordering Information	. 20
Ordering Code Definitions	. 20
Package Diagrams	. 21
Acronyms	
Document Conventions	
Units of Measure	. 23
Document History Page	
Sales, Solutions, and Legal Information	
Worldwide Sales and Design Support	
Products	
PSoC®Solutions	
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### **Pinouts**

Figure 1. 48-ball FBGA	pinout						
48-ball FBGA (× 16) Top View (not to scale)							
1 2 3 4 5	6						
$\overline{BLE}$ $\overline{OE}$ $\overline{A_0}$ $\overline{A_1}$ $\overline{A_1}$							
$\boxed{\begin{array}{c} \overline{DQ_8} \\ \overline{BHE} \\ \overline{A_3} \\ \overline{A_4} \\ \overline{C} $							
$DQ_9 DQ_{10} A_5 A_6 DC$							
$V_{SS}$ $DQ_{11}$ $A_{17}$ $A_{7}$ $D0$							
$V_{CC}$ $DQ_{12}$ $V_{CAP}$ $A_{16}$ $DC$	N <sub>4</sub> V <sub>SS</sub> E						
$\left( \begin{array}{c} DQ_{14} \\ DQ_{13} \\ A_{14} \\ A_{15} \\ DQ_{13} \\ A_{15} \\ DQ_{13} \\ A_{15} \\ DQ_{15} \\ A_{15} \\ DQ_{15} \\ A_{15} \\ A_{15$	DQ <sub>6</sub> F						
	E DQ7 G						
$\mathbb{NC}^{[N]}$ $\mathbb{A}_{8}$ $\mathbb{A}_{9}$ $\mathbb{A}_{10}$ $\mathbb{A}_{10}$	1 NC H						
Figure 2. 44-pin TSOP	ll pinout						
(× 16) <sup>[3]</sup>							
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $						

 Notes

 1. Address expansion for 8-Mbit. NC pin not connected to die.

 2. Address expansion for 16-Mbit. NC pin not connected to die.

 3. HSB pin is not available in 44-pin TSOP II (x 16) package.



# **Pin Definitions**

Pin Name	I/O Type	Description
A <sub>0</sub> -A <sub>17</sub>	Input	Address inputs. Used to Select one of the 262,144 words of the nvSRAM.
DQ <sub>0</sub> -DQ <sub>15</sub>	Input/Output	Bidirectional data I/O lines. Used as input or output lines depending on operation.
WE	Input	Write Enable input, Active LOW. When selected LOW, data on the I/O pins is written to the specific address location.
CE	Input	Chip Enable input, Active LOW. When LOW, selects the chip. When HIGH, deselects the chip.
ŌĒ	Input	<b>Output Enable, Active LOW</b> . The active LOW OE input enables the data output buffers during read cycles. I/O pins are tristated on deasserting OE HIGH.
BHE	Input	Byte High Enable, Active LOW. Controls DQ <sub>15</sub> -DQ <sub>8</sub> .
BLE	Input	Byte Low Enable, Active LOW. Controls DQ7-DQ0.
V <sub>SS</sub>	Ground	Ground for the device. Must be connected to the ground of the system.
V <sub>CC</sub>	Power supply	Power supply inputs to the device.
HSB	Input/Output	Hardware STORE Busy (HSB). When LOW this output indicates that a Hardware STORE is in progress. When pulled LOW external to the chip it initiates a nonvolatile STORE operation. After each Hardware and Software STORE operation, HSB is driven HIGH for a short time (t <sub>HHHD</sub> ) with standard output high current, and then a weak internal pull-up resistor keeps this pin HIGH (external pull-up resistor connection optional).
V <sub>CAP</sub>	Power supply	AutoStore Capacitor. Supplies power to the nvSRAM during power loss to store data from SRAM to non-volatile elements.
NC	No connect	No Connect. This pin is not connected to the die.



### **Device Operation**

The CY14B104NA nvSRAM is made up of two functional components paired in the same physical cell. They are a SRAM memory cell and a nonvolatile QuantumTrap cell. The SRAM memory cell operates as a standard fast static RAM. Data in the SRAM is transferred to the nonvolatile cell (the STORE operation), or from the nonvolatile cell to the SRAM (the RECALL operation). Using this unique architecture, all cells are stored and recalled in parallel. During the STORE and RECALL operations, SRAM read and write operations are inhibited. The CY14B104NA supports infinite reads and writes similar to a typical SRAM. In addition, it provides infinite RECALL operations from the non-volatile cells. Refer to the Truth Table For SRAM Operations on page 19 for a complete description of read and write modes.

### SRAM Read

The CY14<u>B104NA performs a read cycle when CE and OE are LOW and WE and HSB are HIGH. The address specified on pins A<sub>0-17</sub> determines which of the 262,144 words of 16 bits each are accessed. Byte enables (BHE, BLE) determine which bytes are enabled to the output, in the case of 16-bit words. When the read is initiated by an address transition, the outputs are valid after a delay of t<sub>AA</sub> (read cycle 1). If the read is initiated by CE or OE, the outputs are valid at t<sub>ACE</sub> or at t<sub>DOE</sub>, whichever is later (read cycle 2). The data output repeatedly responds to address changes within the t<sub>AA</sub> access time without the need for transitions on any control input pins. This remains valid until another address change or until CE or OE is brought HIGH, or WE or HSB is brought LOW.</u>

#### **SRAM Write**

A write cycle is performed when  $\overline{CE}$  and  $\overline{WE}$  are LOW and  $\overline{HSB}$  is HIGH. The address inputs must be stable before entering the write cycle and must remain stable until  $\overline{CE}$  or  $\overline{WE}$  goes HIGH at the end of the cycle. The data on the common I/O pins  $DQ_{0-15}$  are written into the memory if the data is valid ( $t_{SD}$  time) before the end of a  $\overline{WE}$  controlled write or before the end of an  $\overline{CE}$  controlled write. The Byte Enable inputs (BHE, BLE) determine which bytes are written, in the case of 16-bit words. It is recommended that  $\overline{OE}$  be kept HIGH during the entire write cycle to avoid data bus contention on common I/O lines. If  $\overline{OE}$  is left LOW, internal circuitry turns off the output buffers  $t_{HZWE}$  after  $\overline{WE}$  goes LOW.

#### **AutoStore Operation**

The CY14B104NA stores data to the nvSRAM using one of the following three storage operations: Hardware STORE activated by the HSB; Software STORE activated by an address sequence; AutoStore on device power-down. The AutoStore operation is a unique feature of QuantumTrap technology and is enabled by default on the CY14B104NA.

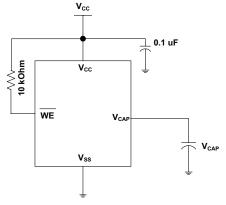
During a normal operation, the device draws current from V<sub>CC</sub> to charge a capacitor connected to the V<sub>CAP</sub> pin. This stored charge is used by the chip to perform a single STORE operation. If the voltage on the V<sub>CC</sub> pin drops below V<sub>SWITCH</sub>, the part automatically disconnects the V<sub>CAP</sub> pin from V<sub>CC</sub>. A STORE operation is initiated with power provided by the V<sub>CAP</sub> capacitor.

**Note** If the capacitor is not connected to  $V_{CAP}$  pin, AutoStore must be disabled using the soft sequence specified in Preventing

Figure 3 shows the proper connection of the storage capacitor ( $V_{CAP}$ ) for automatic store operation. Refer to DC Electrical Characteristics on page 9 for the size of  $V_{CAP}$ . The voltage on the  $V_{CAP}$  pin is driven to  $V_{CC}$  by a regulator on the chip. A pull-up should be placed on WE to hold it <u>inactive</u> during power-up. This pull-up is effective only if the WE signal is tristate during power-up. Many MPUs tristate their controls on power-up. This should be verified when using the pull-up. When the nvSRAM comes out of power-on-RECALL, the MPU must be active or the WE held inactive until the MPU comes out of reset.

To reduce unnecessary non-volatile stores, AutoStore and hardware STORE operations are ignored unless at least one write operation has taken place since the most recent STORE or RECALL cycle. Software initiated STORE cycles are performed regardless of whether a write operation has taken place. The HSB signal is monitored by the system to detect if an AutoStore cycle is in progress.

#### Figure 3. AutoStore Mode



#### Hardware STORE Operation

The CY14B104NA provides the HSB pin to control and acknowledge the STORE operations. The HSB pin is used to request a hardware STORE cycle. When the HSB pin is driven LOW, the CY14B104NA conditionally initiates a STORE operation after t<sub>DELAY</sub>. An actual STORE cycle only begins if a write to the SRAM has taken place since the last STORE or RECALL cycle. The HSB pin also acts as an open drain driver (internal 100 k $\Omega$  weak pull-up resistor) that is internally driven LOW to indicate a busy condition when the STORE (initiated by any means) is in progress.

**Note** After each Hardware and Software STORE operation HSB is driven HIGH for a short time ( $t_{HHHD}$ ) with standard output high current and then remains HIGH by internal 100 k $\Omega$  pull-up resistor.

SRAM write operations that are in progress when  $\overline{\text{HSB}}$  is driven LOW by any means are given time ( $t_{\text{DELAY}}$ ) to complete before the STORE operation is initiated. However, any SRAM write cycles requested after HSB goes LOW are in<u>hibited</u> until HSB returns HIGH. In case the write latch is not set, HSB is not driven LOW by the CY14B104NA. But any SRAM read and write cycles





are inhibited until  $\overline{\text{HSB}}$  is returned HIGH by MPU or other external source.

During any STORE operation, regardless of how it is initiated, the CY14B104NA continues to drive the HSB pin LOW, releasing it only when the STORE is complete. Upon completion of the STORE operation, the nvSRAM memory access is inhibited for  $t_{LZHSB}$  time after HSB pin returns HIGH. Leave the HSB unconnected if it is not used.

#### Hardware RECALL (Power-Up)

During power-up or after any low power condition  $(V_{CC} < V_{SWITCH})$ , an internal RECALL request is latched. When  $V_{CC}$  again exceeds the  $V_{SWITCH}$  on power up, a RECALL cycle is automatically initiated and takes  $t_{HRECALL}$  to complete. During this time, the HSB pin is driven LOW by the HSB driver and all reads and writes to nvSRAM are inhibited.

### Software STORE

Data is transferred from the SRAM to the non-volatile memory by a software address sequence. The CY14B104NA software STORE cycle is initiated by executing sequential CE or OE controlled read cycles from six specific address locations in exact order. During the STORE cycle an erase of the previous non-volatile data is first performed, followed by a program of the non-volatile elements. After a STORE cycle is initiated, further input and output are disabled until the cycle is completed.

Because a sequence of reads from specific addresses is used for STORE initiation, it is important that no other read or write accesses intervene in the sequence, or the sequence is aborted and no STORE or RECALL takes place.

To initiate the software STORE cycle, the following read sequence must be performed.

- 1. Read address 0x4E38 Valid READ
- 2. Read address 0xB1C7 Valid READ
- 3. Read address 0x83E0 Valid READ
- 4. Read address 0x7C1F Valid READ
- 5. Read address 0x703F Valid READ
- 6. Read address 0x8FC0 Initiate STORE cycle

The software sequence may be clocked with  $\overline{CE}$  controlled reads or  $\overline{OE}$  controlled reads, with  $\overline{WE}$  kept HIGH for all the six READ sequences. After the sixth address in the sequence is entered, the STORE cycle commences and the chip is disabled. HSB is driven LOW. After the t<sub>STORE</sub> cycle time is fulfilled, the SRAM is activated again for the read and write operation.

#### Software RECALL

Data is transferred from the non-volatile memory to the SRAM by a software address sequence. A software RECALL cycle is initiated with a sequence of read operations in a manner similar to the software STORE initiation. To initiate the RECALL cycle, perform the following sequence of CE or OE controlled read operations must be performed.

- 1. Read address 0x4E38 Valid READ
- 2. Read address 0xB1C7 Valid READ
- 3. Read address 0x83E0 Valid READ
- 4. Read address 0x7C1F Valid READ
- 5. Read address 0x703F Valid READ
- 6. Read address 0x4C63 Initiate RECALL cycle

Internally, RECALL is a two step procedure. First, the SRAM data is cleared; then, the non-volatile information is transferred into the SRAM cells. After the  $t_{RECALL}$  cycle time, the SRAM is again ready for read and write operations. The RECALL operation does not alter the data in the non-volatile elements.





#### Table 1. Mode Selection

CE	WE	OE	BHE, BLE	A <sub>15</sub> –A <sub>0</sub> <sup>[4]</sup>	Mode	I/O	Power
Н	Х	Х	Х	Х	Not selected	Output high Z	Standby
L	Н	L	L	Х	Read SRAM	Output data	Active
L	L	Х	L	Х	Write SRAM	Input data	Active
L	Н	L	Х	0x4E38 0xB1C7 0x83E0 0x7C1F 0x703F 0x8B45	Read SRAM Read SRAM Read SRAM Read SRAM Read SRAM AutoStore Disable	Output data Output data Output data Output data Output data Output data	Active <sup>[5]</sup>
L	Н	L	Х	0x4E38 0xB1C7 0x83E0 0x7C1F 0x703F 0x4B46	Read SRAM Read SRAM Read SRAM Read SRAM Read SRAM AutoStore Enable	Output data Output data Output data Output data Output data Output data	Active <sup>[6]</sup>
L	Н	L	Х	0x4E38 0xB1C7 0x83E0 0x7C1F 0x703F 0x8FC0	Read SRAM Read SRAM Read SRAM Read SRAM Read SRAM Non-volatile STORE	Output data Output data Output data Output data Output data Output high Z	Active I <sub>CC2</sub> <sup>[6]</sup>
L	Н	L	Х	0x4E38 0xB1C7 0x83E0 0x7C1F 0x703F 0x4C63	Read SRAM Read SRAM Read SRAM Read SRAM Read SRAM Non-volatile RECALL	Output data Output data Output data Output data Output data Output high Z	Active <sup>[6]</sup>

While there are 18 address lines on the CY14B104NA, only 13 address lines (A<sub>14</sub>-A<sub>2</sub>) are used to control software modes. The remaining address lines are don't care.
 The six consecutive address locations must be in the order listed. WE must be HIGH during all six cycles to enable a non-volatile cycle.
 The six consecutive address locations must be in the order listed. WE must be HIGH during all six cycles to enable a non-volatile cycle.



### **Preventing AutoStore**

The AutoStore function is disabled by initiating an AutoStore disable sequence. A sequence of read operations is performed in a manner similar to the software STORE initiation. To initiate the AutoStore disable sequence, the following sequence of  $\overrightarrow{CE}$  or  $\overrightarrow{OE}$  controlled read operations must be performed:

- 1. Read address 0x4E38 Valid READ
- 2. Read address 0xB1C7 Valid READ
- 3. Read address 0x83E0 Valid READ
- 4. Read address 0x7C1F Valid READ
- 5. Read address 0x703F Valid READ
- 6. Read address 0x8B45 AutoStore Disable

The AutoStore is re-enabled by initiating an AutoStore enable sequence. A sequence of read operations is performed in a manner similar to the software RECALL initiation. To initiate the AutoStore enable sequence, the following sequence of  $\overline{CE}$  or  $\overline{OE}$  controlled read operations must be performed:

- 1. Read address 0x4E38 Valid READ
- 2. Read address 0xB1C7 Valid READ
- 3. Read address 0x83E0 Valid READ
- 4. Read address 0x7C1F Valid READ
- 5. Read address 0x703F Valid READ
- 6. Read address 0x4B46 AutoStore Enable

If the AutoStore function is disabled or re-enabled, a manual STORE operation (hardware or software) must be issued to save the AutoStore state through subsequent power-down cycles. The part comes from the factory with AutoStore enabled and 0x00 written in all cells.

### **Data Protection**

The CY14B104NA protects data from corruption during low voltage conditions by inhibiting all externally initiated STORE and write operations. The low voltage condition is detected when  $V_{CC} \leq V_{SWITCH}$ . If the CY14B104NA is in a write mode (both CE and WE are LOW) at power-up, after a RECALL or STO<u>RE</u>, the write is inhibited until the SRAM is enabled after t<sub>LZHSB</sub> (HSB to output active). This protects against inadvertent writes during power-up or brown out conditions.



# **Maximum Ratings**

Exceeding maximum ratings may impair the useful life of the device. These user guidelines are not tested.

Storage temperature65 °C to +150 °C
Maximum accumulated storage time
At 150 °C ambient temperature 1000 h
At 85 °C ambient temperature 20 Years
At 125 °C ambient temperature 1 Year
Ambient temperature with power applied55 °C to +150 °C
Supply voltage on $V_{CC}$ relative to $V_{SS}$ –0.5 V to 4.1 V
Voltage applied to outputs in high Z state0.5 V to V_{CC} + 0.5 V
Input voltage0.5 V to Vcc + 0.5 V

# **DC Electrical Characteristics**

### Over the Operating Range

Transient voltage (< 20 ns) on any pin to ground potential–2.0 V to V <sub>CC</sub> + 2.0 V
Package power dissipation capability (T <sub>A</sub> = 25 °C)1.0 W
Surface mount Pb soldering temperature (3 Seconds)+260 °C
DC output current (1 output at a time, 1s duration) 15 mA
Static discharge voltage (per MIL-STD-883, Method 3015)> 2001 V
Latch up current> 200 mA
Operating Pange

### **Operating Range**

Range	Ambient Temperature	V <sub>CC</sub>
Automotive-A	–40 °C to +85 °C	2.7 V to 3.6 V
Automotive-E	–40 °C to +125 °C	3.0 V to 3.6 V

Parameter	Description Test Conditions				<b>Typ</b> <sup>[7]</sup>	Max	Unit
V <sub>CC</sub>	Power supply		Automotive-A	2.7	3.0	3.6	V
			Automotive-E	3.0	3.3	3.6	V
I <sub>CC1</sub>	Average V <sub>CC</sub> current	t <sub>RC</sub> = 25 ns	Automotive-A	_	_	70	mA
		RC III III	Automotive-A	-	-	52	mA
		Values obtained without output loads $(I_{OUT} = 0 \text{ mA})$	Automotive-E	-	-	65	mA
I <sub>CC2</sub>	Average V <sub>CC</sub> current during	All inputs don't care,	Automotive-A	-	-	10	mA
002	STORE	V <sub>CC</sub> = Max Average current for duration <sup>t</sup> STORE	Automotive-E	_	-	15	mA
I <sub>CC3</sub>	Average V <sub>CC</sub> current at t <sub>RC</sub> = 200 ns, V <sub>CC(Typ)</sub> , 25 °C	All inputs cycling at CMOS levels. Values obtained without output loads (I <sub>OUT</sub> = 0 mA).		_	35	_	mA
I <sub>CC4</sub> <sup>[8]</sup>	Average V <sub>CAP</sub> current during	All inputs don't care. Average	Automotive-A	_	-	5	mA
	AutoStore cycle	current for duration t <sub>STORE</sub>	Automotive-E	_	-	10	mA
I <sub>SB</sub>	V <sub>CC</sub> standby current		Automotive-A	_	-	5	mA
			Automotive-E	_	-	10	mA
I <sub>IX</sub> <sup>[9]</sup>	Input leakage current (except	$V_{CC} = Max, V_{SS} \le V_{IN} \le V_{CC}$	Automotive-A	-1	-	+1	μΑ
	HSB)		Automotive-E	-5	-	+5	μΑ
	Input leakage current (for HSB)	$V_{CC} = Max, V_{SS} \le V_{IN} \le V_{CC}$	Automotive-A	-100	-	+1	μA
			Automotive-E	-100	-	+5	μΑ
I <sub>OZ</sub>	Off-state output leakage current	$V_{CC} = Max, V_{SS} \le V_{OUT} \le V_{CC},$	Automotive-A	-1	-	+1	μA
		$\overline{CE}$ or $\overline{OE} \ge V_{IH}$ or	Automotive-E	-5	-	+5	μΑ
		$\overline{BHE}/\overline{BLE} \ge V_{IH} \text{ or } \overline{WE} \le V_{IL}$					

Notes

Typical values are at 25 °C, V<sub>CC</sub> = V<sub>CC(Typ)</sub>. Not 100% tested.
 This <u>parameter</u> is guaranteed by design but not tested.
 The HSB pin has I<sub>OUT</sub> = -2 μA for V<sub>OH</sub> of 2.4 V when both active HIGH and LOW drivers are disabled. When they are enabled standard V<sub>OH</sub> and V<sub>OL</sub> are valid. This parameter is characterized but not tested.



# DC Electrical Characteristics (continued)

### Over the Operating Range

Parameter	Description	Test Conditions		Min	<b>Typ</b> <sup>[7]</sup>	Max	Unit
V <sub>IH</sub>	Input HIGH voltage		Automotive-A	2.0	-	$V_{CC}$ + 0.5	V
			Automotive-E	2.2	-	$V_{CC} + 0.5$	V
V <sub>IL</sub>	Input LOW voltage			$V_{ss} - 0.5$	-	0.8	V
V <sub>OH</sub>	Output HIGH voltage	$I_{OUT} = -2 \text{ mA}$		2.4	_	-	V
V <sub>OL</sub>	Output LOW voltage	I <sub>OUT</sub> = 4 mA		-	-	0.4	V
V <sub>CAP</sub> <sup>[10]</sup>	Storage capacitor	Between $V_{\mbox{CAP}}$ pin and $V_{\mbox{SS}},$ 5 $V$	/ rated	61	68	180	μF

### **Data Retention and Endurance**

### Over the Operating Range

Parameter	Description			Unit
DATA <sub>R</sub>	Data retention	Automotive-A	20	Years
		Automotive-E	1	
NV <sub>C</sub>	Non-volatile STORE operations	Automotive-A	1,000	К
		Automotive-E	100	

### Capacitance

Parameter <sup>[11]</sup>	Description	Test Conditions	Мах	Unit
C <sub>IN</sub>	Input capacitance (except BHE,	$T_A = 25 \text{ °C}, f = 1 \text{ MHz}, V_{CC} = V_{CC(Typ)}$	7	pF
	BLE and HSB)			
	Input capacitance (for BHE, BLE		8	pF
	and HSB)			
C <sub>OUT</sub>	Output capacitance (except HSB)		7	pF
	Output capacitance (for HSB)		8	pF

### **Thermal Resistance**

Parameter <sup>[11]</sup>	Description	Test Conditions	48-pin FBGA	44-pin TSOP II	Unit
JA		Test conditions follow standard test methods and procedures for measuring thermal impedance, in		43.3	°C/W
$\Theta_{JC}$	Thermal resistance (junction to case)	accordance with EIA/JESD51.	7.84	5.56	°C/W

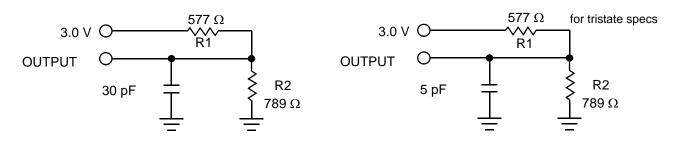
Notes

Min V<sub>CAP</sub> value guarantees that there is a sufficient charge available to complete a successful AutoStore operation. Max V<sub>CAP</sub> value guarantees that the capacitor on V<sub>CAP</sub> is charged to a minimum voltage during a Power-Up RECALL cycle so that an immediate power-down cycle can complete a successful AutoStore. Therefore it is always recommended to use a capacitor within the specified min and max limits. Refer application note AN43593 for more details on V<sub>CAP</sub> options.
 These parameters are guaranteed by design but not tested.



### **AC Test Loads**

Figure 4. AC Test Loads



# **AC Test Conditions**

Input pulse levels0 V to 3 V	
Input rise and fall times (10%–90%) $\leq$ 3 ns	
Input and output timing reference levels 1.5 V	



# **AC Switching Characteristics**

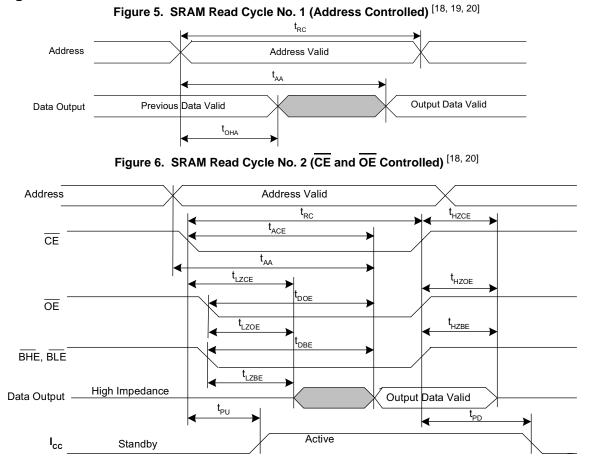
### Over the Operating Range

Parameters <sup>[12]</sup>			25	ins	45 ns		
Cypress Parameter	Alt Parameter	Description	Min	Max	Min	Max	Unit
SRAM Read C	ycle						
t <sub>ACE</sub>	t <sub>ACS</sub>	Chip enable access time	-	25	-	45	ns
t <sub>RC</sub> <sup>[13]</sup>	t <sub>RC</sub>	Read cycle time	25	-	45	-	ns
t <sub>AA</sub> <sup>[14]</sup>	t <sub>AA</sub>	Address access time	-	25	-	45	ns
t <sub>DOE</sub>	t <sub>OE</sub>	Output enable to data valid	-	12	-	20	ns
t <sub>OHA</sub> <sup>[14]</sup>	t <sub>OH</sub>	Output hold after address change	3	-	3	-	ns
t <sub>LZCE</sub> <sup>[15, 16]</sup>	t <sub>LZ</sub>	Chip enable to output active	3	-	3	-	ns
t <sub>HZCE</sub> <sup>[15, 16]</sup>	t <sub>HZ</sub>	Chip disable to output inactive	-	10	-	15	ns
t <sub>LZOE</sub> <sup>[15, 16]</sup>	t <sub>OLZ</sub>	Output enable to output active	0	-	0	-	ns
t <sub>HZOE</sub> <sup>[15, 16]</sup>	t <sub>OHZ</sub>	Output disable to output inactive	-	10	-	15	ns
t <sub>PU</sub> <sup>[15]</sup>	t <sub>PA</sub>	Chip enable to power active	0	-	0	-	ns
t <sub>PD</sub> <sup>[15]</sup>	t <sub>PS</sub>	Chip disable to power standby	-	25	-	45	ns
t <sub>DBE</sub>	-	Byte enable to data valid	-	12	-	20	ns
t <sub>LZBE</sub> <sup>[15]</sup>	-	Byte enable to output active	0	-	0	-	ns
t <sub>HZBE</sub> <sup>[15]</sup>	-	Byte disable to output inactive	-	10	-	15	ns
SRAM Write C	ycle		·				
t <sub>WC</sub>	t <sub>WC</sub>	Write cycle time	25	-	45	-	ns
t <sub>PWE</sub>	t <sub>WP</sub>	Write pulse width	20	-	30	-	ns
t <sub>SCE</sub>	t <sub>CW</sub>	Chip enable to end of write	20	-	30	-	ns
t <sub>SD</sub>	t <sub>DW</sub>	Data setup to end of write	10	-	15	-	ns
t <sub>HD</sub>	t <sub>DH</sub>	Data hold after end of write	0	-	0	-	ns
t <sub>AW</sub>	t <sub>AW</sub>	Address setup to end of write	20	-	30	-	ns
t <sub>SA</sub>	t <sub>AS</sub>	Address setup to start of write	0	_	0	-	ns
t <sub>HA</sub>	t <sub>WR</sub>	Address hold after end of write	0	-	0	-	ns
t <sub>HZWE</sub> [15, 16, 17]	t <sub>WZ</sub>	Write enable to output disable	-	10	-	15	ns
t <sub>LZWE</sub> <sup>[15, 16]</sup>	t <sub>OW</sub>	Output active after end of write	3	-	3	-	ns
t <sub>BW</sub>	-	Byte enable to end of write	20	_	30	-	ns

Notes
12. Test conditions assume signal transition time of 3 ns or less, timing reference levels of V<sub>CC</sub>/2, input pulse levels of 0 to V<sub>CC(typ)</sub>, and output loading of the specified load/load capacitance shown in Figure 4 on page 11.
13. WE must be HIGH during SRAM read cycles.
14. Device is continuously selected with CE, OE and BHE / BLE LOW.
15. These parameters are guaranteed by design but not tested.
16. Measured ±200 mV from steady state output voltage.
17. If WE is LOW when CE goes LOW, the outputs remain in the high impedance state.



### **Switching Waveforms**

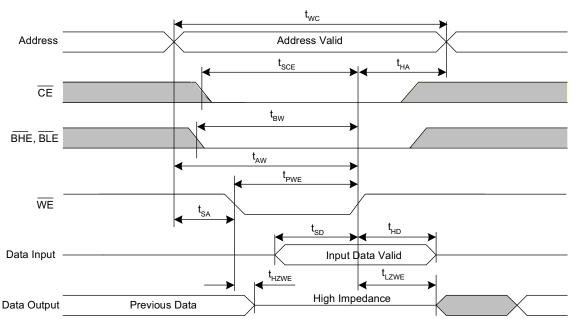


Notes

- WES
   WE must be HIGH during SRAM read cycles.
   <u>Device</u> is continuously selected with CE, OE and BHE / BLE LOW.
   HSB must remain HIGH during read and write cycles.



### Switching Waveforms (continued)



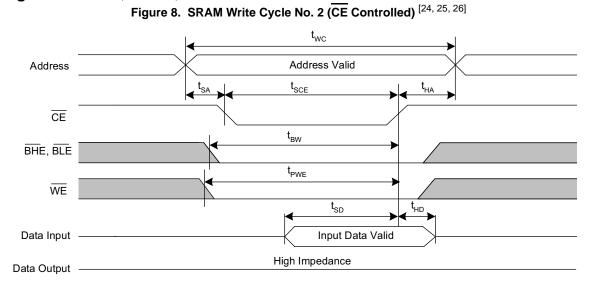


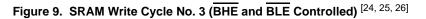
Notes

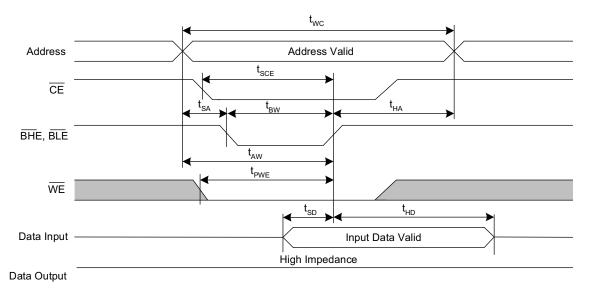
21. HSB must remain HIGH during read and write cycles. 22. If WE is LOW when CE goes LOW, the outputs remain in the high impedance state. 23. CE or WE must be ≥ $V_{\rm IH}$  during address transitions.



### Switching Waveforms (continued)







Notes

24. If  $\overline{WE}$  is LOW when  $\overline{CE}$  goes LOW, the outputs remain in the high impedance state. 25.  $\overline{HSB}$  must remain HIGH during read and write cycles. 26.  $\overline{CE}$  or  $\overline{WE}$  must be ≥V<sub>IH</sub> during address transitions.



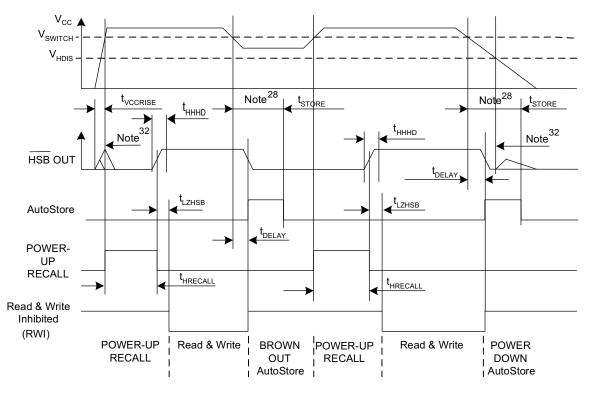
# AutoStore/Power-Up RECALL

### Over the Operating Range

Paramotor	Parameter Description		25	ns	45	ns	Unit
	Description	Min	Max	Min	Max	Unit	
t <sub>HRECALL</sub> <sup>[27]</sup>	Power-Up RECALL duration	-	20	_	20	ms	
t <sub>STORE</sub> <sup>[28]</sup>	STORE cycle duration	-	8	_	8	ms	
t <sub>DELAY</sub> <sup>[29]</sup>	Time allowed to complete SRAM write cy	-	25	_	25	ns	
V <sub>SWITCH</sub>	Low voltage trigger level	Automotive-A	-	2.65	_	2.65	V
		Automotive-E	-	-	_	2.95	V
t <sub>VCCRISE</sub> <sup>[30]</sup>	V <sub>CC</sub> rise time	150	-	150	-	μS	
V <sub>HDIS</sub> <sup>[30]</sup>	HSB output disable voltage	-	1.9	_	1.9	V	
t <sub>LZHSB</sub> <sup>[30]</sup>	HSB to output active time	-	5	_	5	μS	
t <sub>HHHD</sub> <sup>[30]</sup>	HSB high active time		_	500	_	500	ns

# Switching Waveforms – AutoStore/Power-up RECALL

Figure 10. AutoStore or Power-Up RECALL <sup>[31]</sup>



#### Notes

- 27.  $t_{\mbox{HRECALL}}$  starts from the time  $V_{\mbox{CC}}$  rises above  $V_{\mbox{SWITCH}}.$
- If an SRAM write has not taken place since the last non-volatile cycle, no AutoStore or Hardware STORE takes place.
   On a Hardware STORE and AutoStore initiation, SRAM write operation continues to be enabled for time t<sub>DELAY</sub>.
- 30. These parameters are guaranteed by design but not tested.
- Read and write cycles are ignored during STORE, RECALL, and while V<sub>CC</sub> is below V<sub>SWITCH</sub>.
   During power-up and power-down, HSB glitches when HSB pin is pulled up through an external resistor.



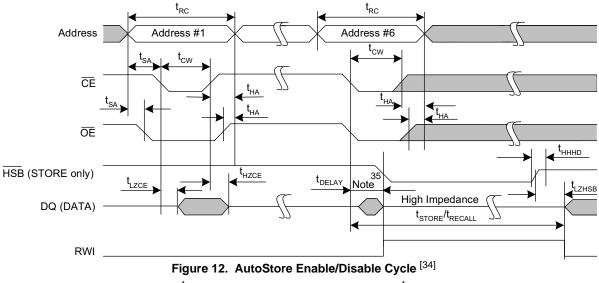
# Software Controlled STORE/RECALL Cycle

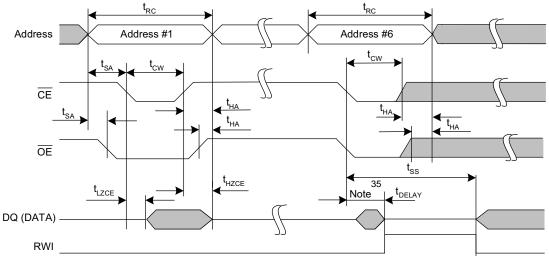
#### Over the Operating Range

Parameter [33, 34]	Description	25	ns	45 ns		Unit
Farameter	Description	Min	Max	Min	Max	Unit
t <sub>RC</sub>	STORE/RECALL initiation cycle time	25	-	45	_	ns
t <sub>SA</sub>	Address setup time	0	-	0	-	ns
t <sub>CW</sub>	Clock pulse width	20	-	30	-	ns
t <sub>HA</sub>	Address hold time	0	-	0	-	ns
t <sub>RECALL</sub>	RECALL duration	_	200	_	200	μS

# Switching Waveforms – Software Controlled STORE/RECALL Cycle

Figure 11. CE and OE Controlled Software STORE/RECALL Cycle [34]





#### Notes

33. The software sequence is clocked with  $\overline{CE}$  controlled or  $\overline{OE}$  controlled reads.

34. The six consecutive addresses must be read in the order listed in Table 1 on page 7. WE must be HIGH during all six consecutive cycles.
 35. DQ output data at the sixth read may be invalid since the output is disabled at t<sub>DELAY</sub> time.

Document Number: 001-54469 Rev. \*H



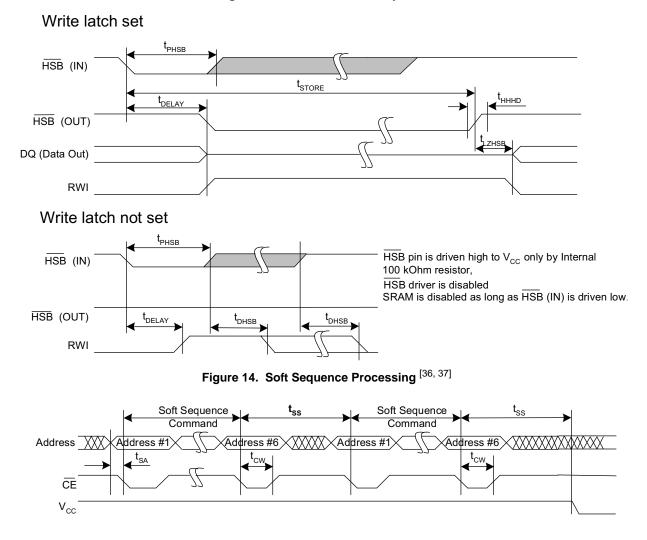
# Hardware STORE Cycle

### Over the Operating Range

Parameter	Description	25	ns	45 ns		Unit
Farameter	Description		Max	Min	Max	Unit
t <sub>DHSB</sub>	HSB to output active time when write latch not set	-	25	-	25	ns
t <sub>PHSB</sub>	Hardware STORE pulse width	15	-	15	-	ns
t <sub>SS</sub> <sup>[36, 37]</sup>	Soft sequence processing time	-	100	_	100	μS

### Switching Waveforms – Hardware STORE Cycle

Figure 13. Hardware STORE Cycle <sup>[38]</sup>



#### Notes

36. This is the amount of time it takes to take action on a soft sequence command. V<sub>CC</sub> power must remain HIGH to effectively register command.
 37. Commands such as STORE and RECALL lock out I/O until operation is complete which further increases this time. See the specific command.
 38. If an SRAM write has not taken place since the last non-volatile cycle, no AutoStore or Hardware STORE takes place.





# **Truth Table For SRAM Operations**

HSB should remain HIGH for SRAM Operations.

CE	WE	OE	BHE	BLE	Inputs/Outputs	Mode	Power
Н	Х	Х	Х	Х	High Z	Deselect/Power-down	Standby
L	Х	Х	Н	н	High Z	Output disabled	Active
L	Н	L	L	L	Data out (DQ <sub>0</sub> –DQ <sub>15</sub> )	Read	Active
L	Н	L	Н	L	Data out (DQ <sub>0</sub> –DQ <sub>7</sub> ); DQ <sub>8</sub> –DQ <sub>15</sub> in High Z	Read	Active
L	Н	L	L	Н	Data out (DQ <sub>8</sub> –DQ <sub>15</sub> ); DQ <sub>0</sub> –DQ <sub>7</sub> in High Z	Read	Active
L	н	Н	L	L	High Z	Output disabled	Active
L	Н	Н	Н	L	High Z	Output disabled	Active
L	Н	Н	L	н	High Z	Output disabled	Active
L	L	Х	L	L	Data in (DQ <sub>0</sub> –DQ <sub>15</sub> )	Write	Active
L	L	Х	Н	L	Data in (DQ <sub>0</sub> –DQ <sub>7</sub> ); DQ <sub>8</sub> –DQ <sub>15</sub> in High Z	Write	Active
L	L	Х	L	Н	Data in (DQ <sub>8</sub> –DQ <sub>15</sub> ); DQ <sub>0</sub> –DQ <sub>7</sub> in High Z	Write	Active

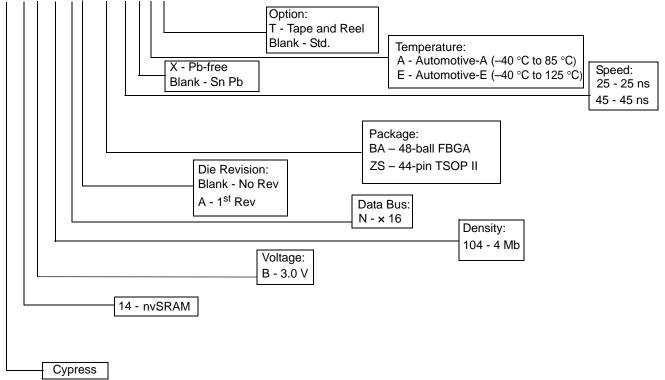


# **Ordering Information**

Speed (ns)	Ordering Code	Package Diagram	Package Type	Operating Range
25	CY14B104NA-ZS25XE	51-85087	44-pin TSOP II (Pb-free)	Automotive-E
	CY14B104NA-ZS25XET			
45	CY14B104NA-BA45XE	51-85128	48-ball FBGA (Pb-free)	
	CY14B104NA-BA45XET			
	CY14B104NA-ZS45XE	51-85087	44-pin TSOP II (Pb-free)	
	CY14B104NA-ZS45XET			

### **Ordering Code Definitions**

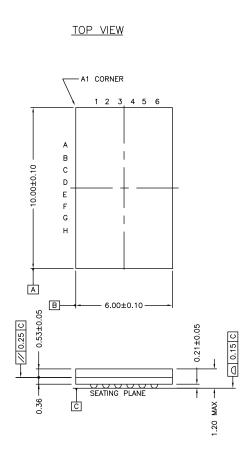
### CY 14 B 104 N A - BA 45 X E T

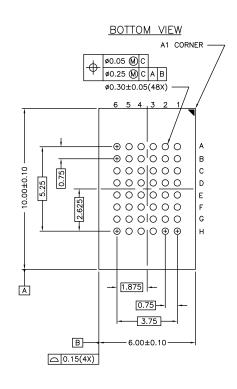




# **Package Diagrams**

Figure 15. 48-ball FBGA (6 × 10 × 1.2 mm) Package Outline, 51-85128





51-85128 \*G



# Package Diagrams (continued)

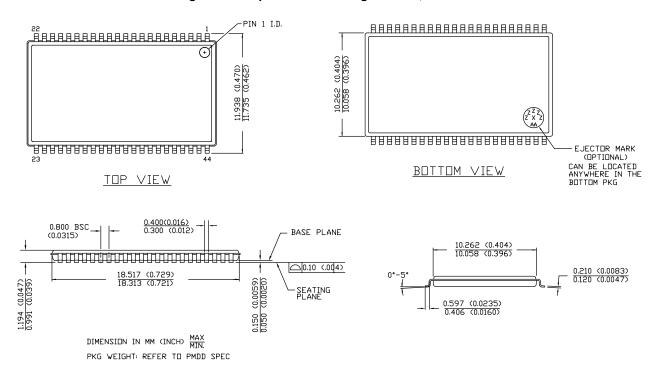


Figure 16. 44-pin TSOP II Package Outline, 51-85087

51-85087 \*E





# Acronyms

Acronym	Description
BHE	Byte High Enable
BLE	Byte Low Enable
CE	Chip Enable
CMOS	Complementary Metal Oxide Semiconductor
EIA	Electronic Industries Alliance
FBGA	Fine-Pitch Ball Grid Array
HSB	Hardware Store Busy
I/O	Input/Output
nvSRAM	nonvolatile Static Random Access Memory
OE	Output Enable
RoHS	Restriction of Hazardous Substances
RWI	Read and Write Inhibited
SRAM	Static Random Access Memory
WE	Write Enable

# **Document Conventions**

### **Units of Measure**

Symbol	Unit of Measure
°C	degree Celsius
Hz	hertz
kHz	kilohertz
kΩ	kilohm
MHz	megahertz
μΑ	microampere
μF	microfarad
μS	microsecond
mA	milliampere
ms	millisecond
ns	nanosecond
Ω	ohm
%	percent
pF	picofarad
V	volt
W	watt



# **Document History Page**

	Document Title: CY14B104NA, 4-Mbit (256K × 16) Automotive nvSRAM Document Number: 001-54469						
Rev.	ECN	Orig. of Change	Submission Date	Description of Change			
*F	5157487	GVCH	03/03/2016	Changed status from Preliminary to Final.			
*G	5349257	GVCH	07/13/2016	Added 44-pin TSOP II package related information in all instances across the document. Updated Ordering Information: Updated part numbers. Updated Ordering Code Definitions. Updated Package Diagrams: Added spec 51-85087 *E. Updated to new template.			
*H	5583673	GVCH	01/12/2017	Updated Ordering Information: Updated part numbers. Updated to new template.			



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