

Absolute Maximum Ratings

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

PV _{IN} , V _{IN}	-0.3V to 25V
V _{CC}	-0.3V to 6.0V
BST	-0.3V to 31V ⁽¹⁾
BST-SW	-0.3V to 6V
SW, I _{LIM}	-1V to 25V ^(1,2)
All other pins	-0.3V to V _{CC} +0.3V
Storage Temperature	-65°C to 150°C
Junction Temperature	150°C
Power Dissipation	Internally Limited
Lead Temperature (Soldering, 10 sec)	300°C
ESD Rating (HBM – Human Body Model)	2kV
ESD Rating (CDM – Charged Device Model)	1.5kV

Operating Ratings

PV _{IN}	3V to 22V
V _{IN}	4.5V to 22V
V _{CC}	4.5V to 5.5V
SW, I _{LIM}	-1V to 22V ⁽²⁾
PGOOD, V _{CC} , T _{ON} , SS, EN	-0.3V to 5.5V
Switching Frequency	200kHz-800kHz ⁽³⁾
Junction Temperature Range (T _J)	-40°C to 125°C
XR76108 Package Power Dissipation max at 25°C	3.8W
XR76112 Package Power Dissipation max at 25°C	4.1W
XR76108 JEDEC51 Package Thermal Resistance θ _{JA}	26°C/W
XR76112 JEDEC51 Package Thermal Resistance θ _{JA}	24°C/W

Note 1: No external voltage applied

Note 2: SW pin's DC range is -1V, transient is -5V for less than 50ns

Note 3: Recommended

Ordering Information⁽¹⁾

Part Number	Operating Temperature Range	Lead-Free	Package	Packing Method
XR76108EL-F	-40°C≤T _J ≤+125°C	Yes ⁽²⁾	5x5mm QFN	Bulk
XR76108ELMTR-F				Tape & Reel
XR76108ELTR-F				Tape & Reel
XR76112EL-F				Bulk
XR76112ELMTR-F				Tape & Reel
XR76112ELTR-F				Tape & Reel
XR76108EVB	XR76108 Evaluation Board			
XR76112EVB	XR76112 Evaluation Board			

NOTES:

1. Refer to www.exar.com/XR76108, www.exar.com/XR76112 for most up-to-date Ordering Information.
2. Visit www.exar.com for additional information on Environmental Rating.

Electrical Characteristics

Specifications are for Operating Junction Temperature of T_J = 25°C only; limits applying over the full Operating Junction Temperature range are denoted by a “•”. Typical values represent the most likely parametric norm at T_J = 25°C, and are provided for reference purposes only. Unless otherwise indicated, V_{IN}=12V

Parameter	Min.	Typ.	Max.	Units	Conditions
Power Supply Characteristics					
V _{IN} , Input Voltage Range	4.5	12	22	V	V _{CC} regulating or in dropout
	4.5	5.0	5.5		V _{CC} tied to V _{IN}
I _{VIN} , V _{IN} supply current		0.7	1.3	mA	• Not switching, V _{IN} =12V, V _{FB} =0.7V
I _{VCC} , V _{CC} Quiescent current		0.7	1.3	mA	• Not switching, V _{CC} =V _{IN} =5V, V _{FB} =0.7V

Parameter	Min.	Typ.	Max.	Units		Conditions
I _{VIN} , V _{IN} supply current (XR76112)		8		mA		f=300kHz, R _{ON} =107k, V _{FB} =0.58V
I _{VIN} , V _{IN} supply current (XR76108)		6		mA		f=300kHz, R _{ON} =107k, V _{FB} =0.58V
I _{OFF} , Shutdown current		0.5		μA		Enable=0V, V _{IN} =12V, V _{IN} =PV _{IN}
Enable and Under-Voltage Lock-Out UVLO						
V _{IH_EN} , EN Pin Rising Threshold	1.8	1.9	2.0	V	•	
V _{EN_HYS} , EN Pin Hysteresis		50		mV		
V _{IH_EN} , EN Pin Rising Threshold for DCM/CCM operation	2.8	3.0	3.1	V	•	
V _{EN_HYS} , EN Pin Hysteresis		100		mV		
V _{CC} UVLO start threshold, rising edge	4.00	4.25	4.40	V	•	
V _{CC} UVLO Hysteresis	150	230		mV	•	
Reference voltage						
V _{REF} , Reference voltage	0.597	0.600	0.603	V		V _{IN} =4.5V-22V → V _{CC} regulating or in dropout
	0.596	0.600	0.604	V		V _{IN} =4.5V-5.5V → V _{CC} tied to V _{IN}
	0.594	0.600	0.606	V	•	V _{IN} =4.5V-22V → V _{CC} regulating or in dropout, V _{IN} =4.5V-5.5V → V _{CC} tied to V _{IN}
DC load regulation		±0.25		%		CCM operation, closed loop, applies to any C _{OUT}
DC Line regulation		±0.1		%		
Parameter	Min.	Typ.	Max.	Units		Conditions
Programmable Constant On-Time						
On-Time 1	1.66	1.95	2.24	μs	•	R _{ON} =140kΩ, V _{IN} =22V
f corresponding to On-Time 1	243	280	329	kHz		V _{IN} =22V, V _{OUT} =12V
Minimum Programmable On-Time		109		ns		R _{ON} =6.98kΩ, V _{IN} =22V
On-Time 2	162	202	226	ns	•	R _{ON} =6.98kΩ, V _{IN} =12V
f corresponding to On-Time 2	1217	1361	1698	kHz		V _{OUT} =3.3V
f corresponding to On-Time 2	369	413	514	kHz		V _{OUT} =1.0V
On-Time 3	352	422	492	ns	•	R _{ON} =16.2kΩ, V _{IN} =12V
Minimum Off-Time		250	350	ns	•	
Diode Emulation Mode						
Zero crossing threshold		-2		mV		DC value measured during test
Soft-Start						
SS Charge current	-14	-10	-6	μA	•	
SS Discharge current	1	3		mA	•	Fault present
V _{CC} Linear Regulator						
V _{CC} Output Voltage	4.8	5.0	5.2	V	•	V _{IN} =6V to 22V, I _{load} =0 to 30mA
	4.3	4.37			•	V _{IN} =4.5V, R _{ON} =16.2kΩ, f _{sw} =678kHz, XR76112
Power Good Output						
Power Good Threshold	-10	-7.5	-5	%		
Power Good Hysteresis		2	4	%		
Power Good Sink Current	1	15		mA		
Protection: OCP, OTP, Short-Circuit						
Hiccup timeout		110		ms		
I _{LIM} pin source current	45	50	55	μA		
I _{LIM} current temperature coefficient		0.4		%/°C		
I _{LIM} comparator offset	-8	0	+8	mV	•	
Current limit blanking		100		ns		
Thermal shutdown threshold		150		°C		Rising temperature
Thermal Hysteresis		15		°C		

Parameter	Min.	Typ.	Max.	Units	Conditions
Feedback pin short-circuit threshold	50	60	70	%	• Percent of V_{REF} , short circuit is active After PGOOD is up
XR76108 Output Power Stage					
High-side MOSFET $R_{DS(on)}$		21	28	$m\Omega$	$V_{GS}=4.5V, I_{DS}=2A$
Low-side MOSFET $R_{DS(on)}$		7	10	$m\Omega$	$V_{GS}=4.5V, I_{DS}=2A$
Maximum Output Current	8			A	•
XR76112 Output Power Stage					
High-side MOSFET $R_{DS(on)}$		11	15.5	$m\Omega$	$V_{GS}=4.5V, I_{DS}=2A$
Low-side MOSFET $R_{DS(on)}$		5	9	$m\Omega$	$V_{GS}=4.5V, I_{DS}=2A$
Maximum Output Current	12			A	•

Block Diagram

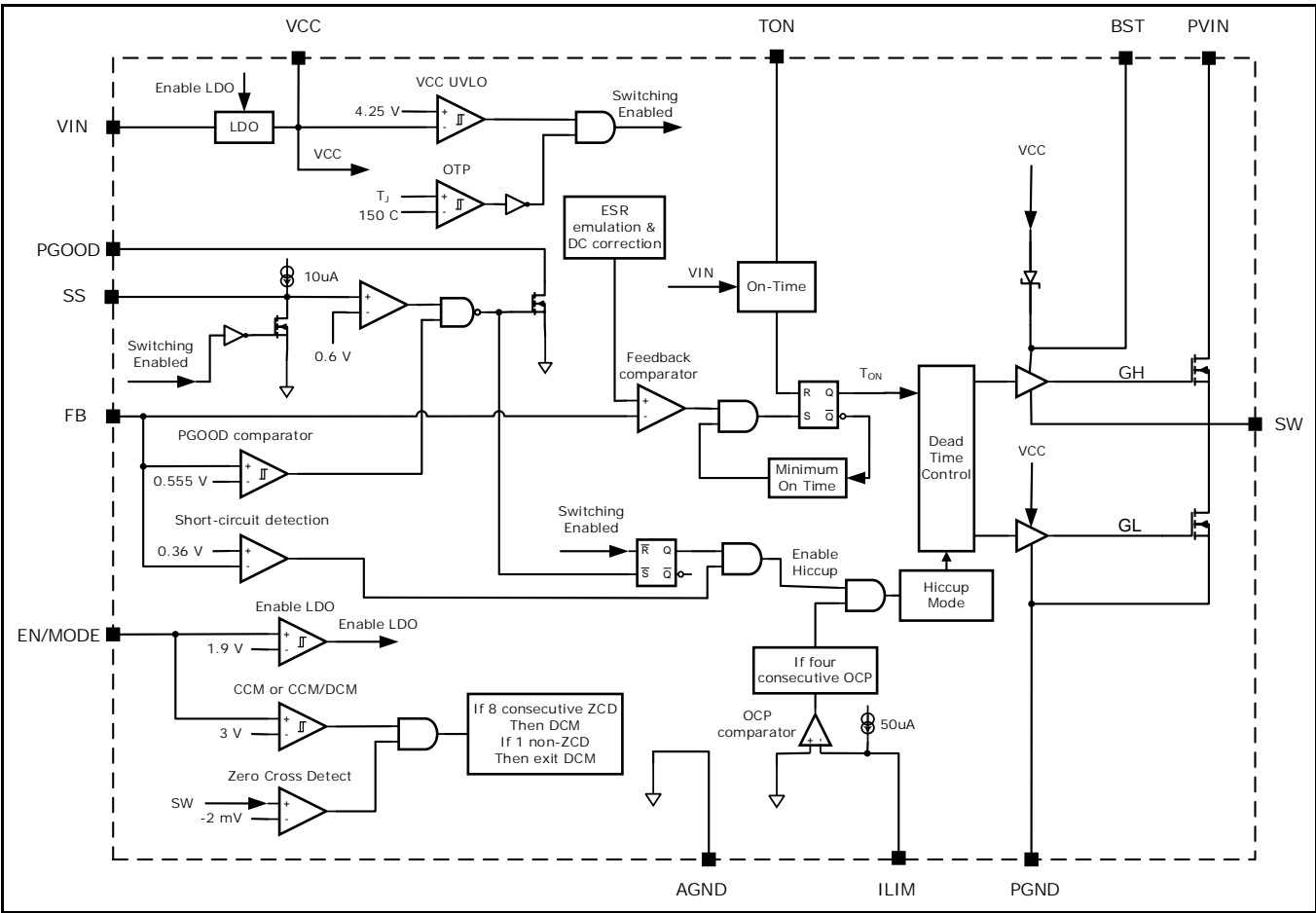


Figure 3: XR76108/12 Block Diagram

Pin Assignment

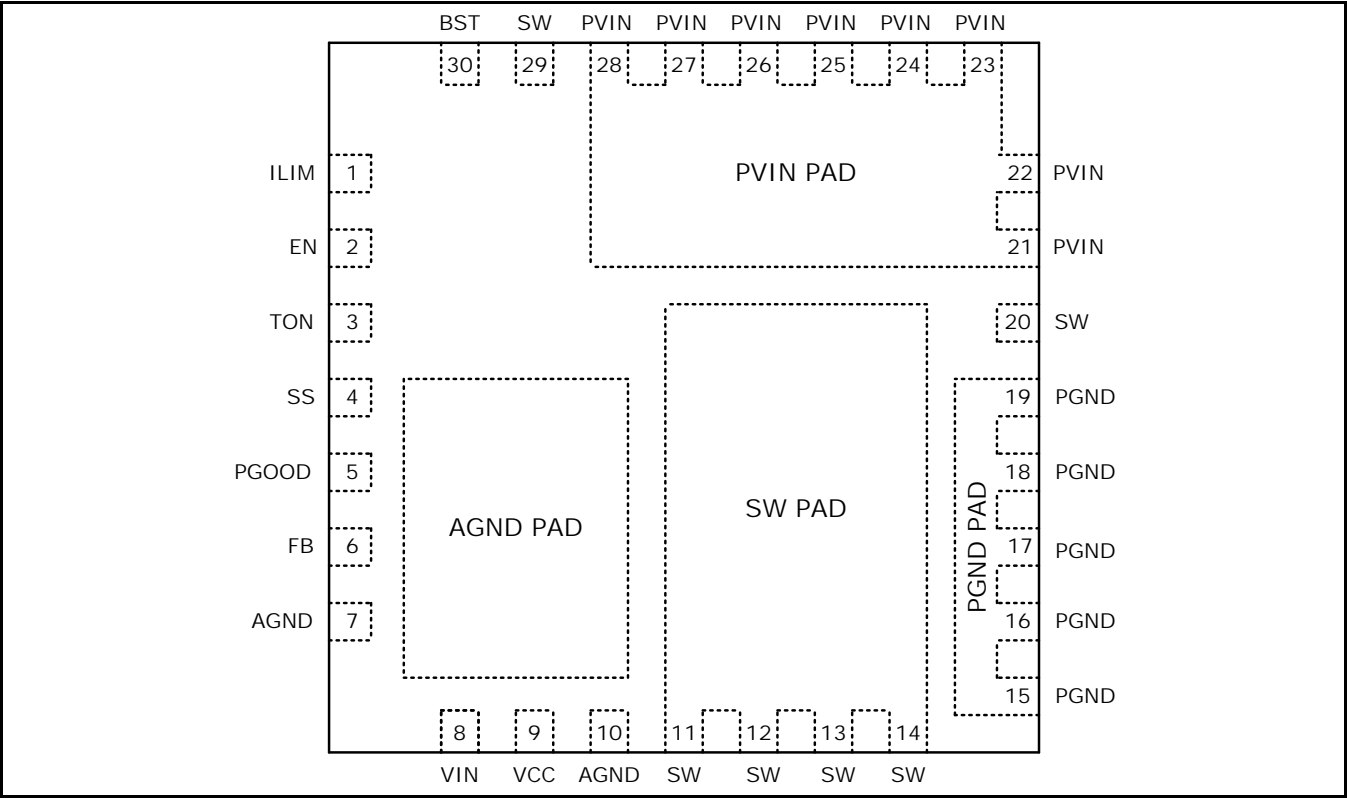


Figure 4: XR76108/12 Pin Assignment

Pin Description

Name	Pin Number	Description
ILIM	1	Over-current protection programming. Connect with a resistor to SW.
EN/MODE	2	Precision enable pin. Pulling this pin above 1.9V will turn the regulator on and it will operate in CCM. If the voltage is raised above 3.0V then the regulator will operate in DCM/CCM depending on load.
TON	3	Constant on-time programming pin. Connect with a resistor to AGND.
SS	4	Soft-Start pin. Connect an external capacitor between SS and AGND to program the soft-start rate based on the 10uA internal source current.
PGOOD	5	Power-good output. This open-drain output is pulled low when V_{OUT} is outside the regulation.
FB	6	Feedback input to feedback comparator. Connect with a set of resistors to V_{OUT} and AGND in order to program V_{OUT} .
AGND	7, 10, AGND Pad	Signal ground for control circuitry. Connect AGND Pad with a short trace to pins 7 and 10.
VIN	8	Supply input for the regulator's LDO. Normally it is connected to PVIN.
VCC	9	The output of regulator's LDO. For operation using a 5V rail, VCC should be shorted to VIN.
SW	11-14, 20, 29, SW Pad	Switch node. Drain of the low-side N-channel MOSFET. Source of the high-side MOSFET is wire-bonded to the SW Pad. Pins 20 and 29 are internally connected to SW pad.
PGND	15-19, PGND Pad	Ground of the power stage. Should be connected to the system's power ground plane. Source of the low-side MOSFET is wire-bonded to PGND Pad.
PVIN	21-28, PVIN Pad	Input voltage for power stage. Drain of the high-side N-channel MOSFET.
BST	30	High-side driver supply pin. Connect a bootstrap capacitor between BST and pin 29.

Typical Performance Characteristics

All data taken at $V_{IN}=12V$, $V_{OUT}=1.2V$, $f=600kHz$, $T_A=25^{\circ}C$, No Air flow, Forced CCM, unless otherwise specified. Schematic and BOM from Applications Circuit section of this datasheet.

REGULATION

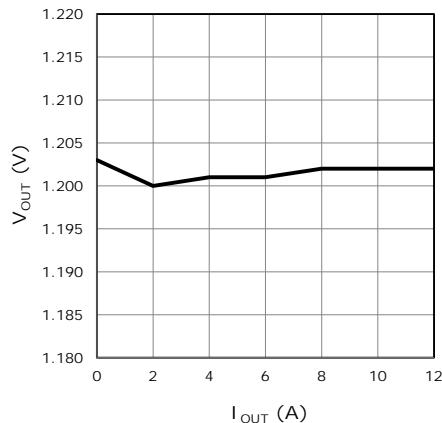


Figure 5: XR76112 Load regulation, $V_{IN}=12V$

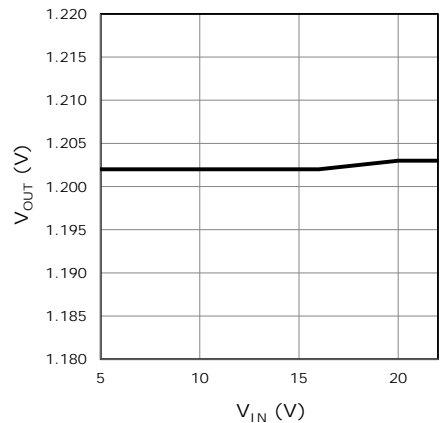


Figure 6: XR76112 Line regulation, $I_{OUT}=12A$

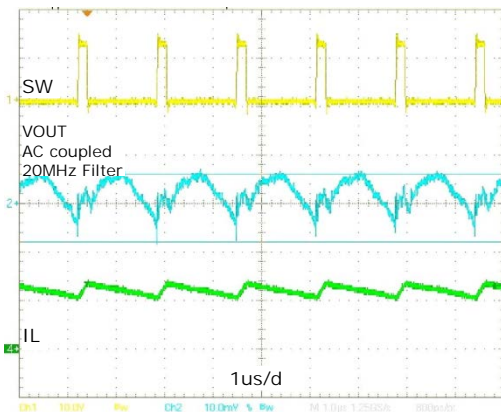


Figure 7: XR76112 V_{OUT} ripple is 14mV at 12A

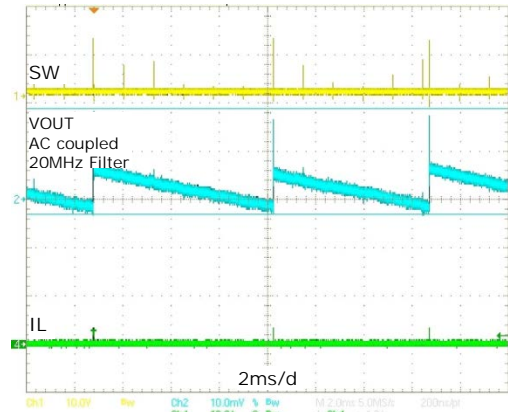


Figure 8: XR76112 V_{OUT} ripple is 22mV at 0A, DCM

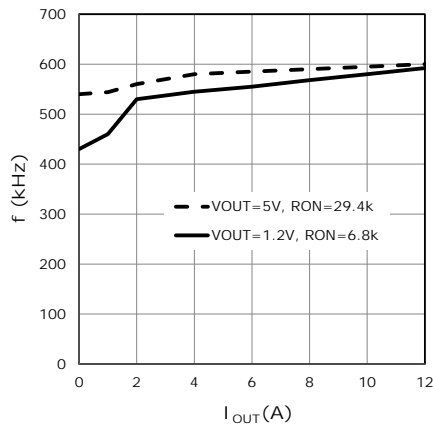


Figure 9: XR76112 Frequency vs. I_{OUT} , Forced CCM

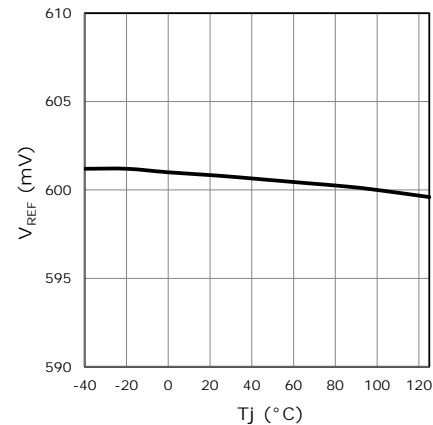


Figure 10: V_{REF} vs. temperature

Typical Performance Characteristics

All data taken at $V_{IN}=12V$, $V_{OUT}=1.2V$, $f=600kHz$, $T_A=25^{\circ}C$, No Air flow, Forced CCM, unless otherwise specified. Schematic and BOM from Applications Circuit section of this datasheet.

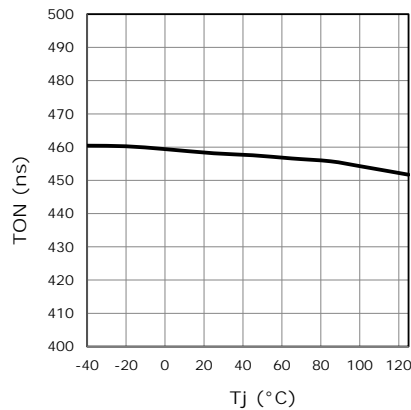


Figure 11: On-Time vs. temperature

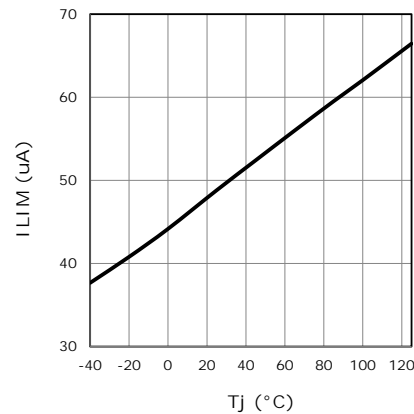


Figure 12: I_{LIM} vs. temperature

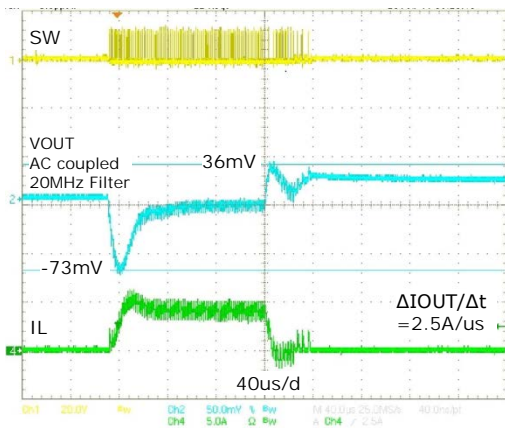


Figure 13: XR76108 load step, DCM/CCM, 0A-4A-0A

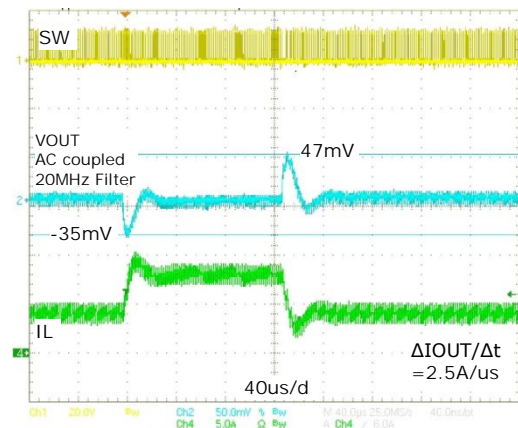


Figure 14: XR76108 load step, Forced CCM, 4A-8-4A

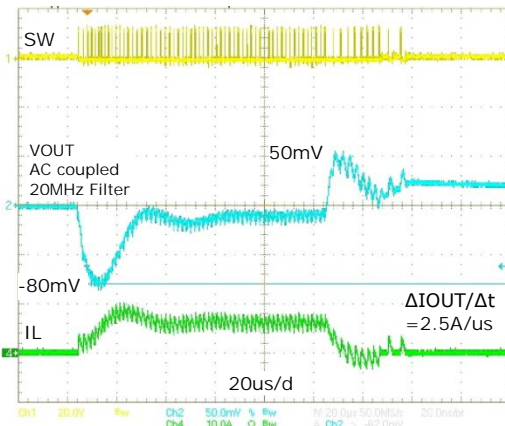


Figure 15: XR76112 load step, DCM/CCM, 0A-6A-0A

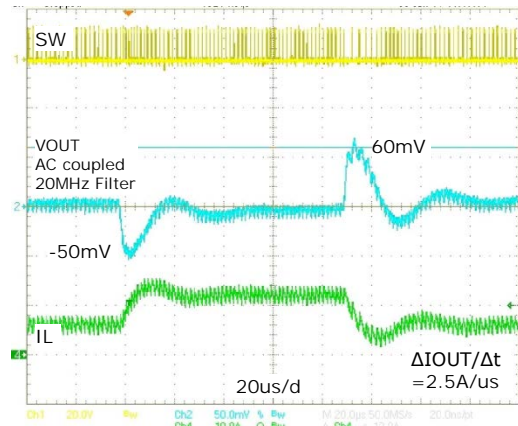


Figure 16: XR76112 load step, Forced CCM, 6A-12A-6A

Powerup

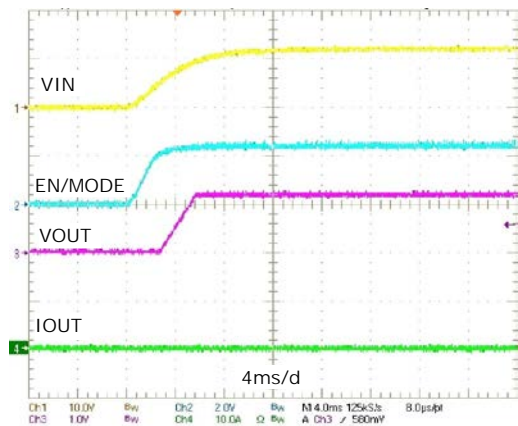


Figure 17: XR76112 Powerup, Forced CCM, $I_{OUT}=0A$

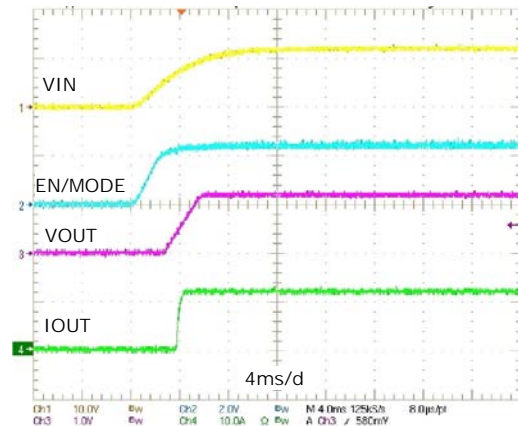


Figure 18: XR76112 Powerup, Forced CCM, $I_{OUT}=12A$

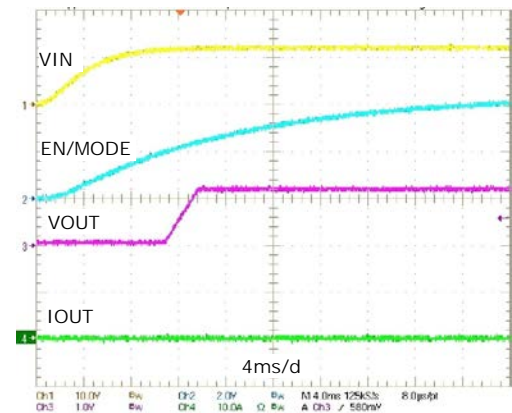


Figure 19: XR76112 Powerup, DCM/CCM, $I_{OUT}=0A$

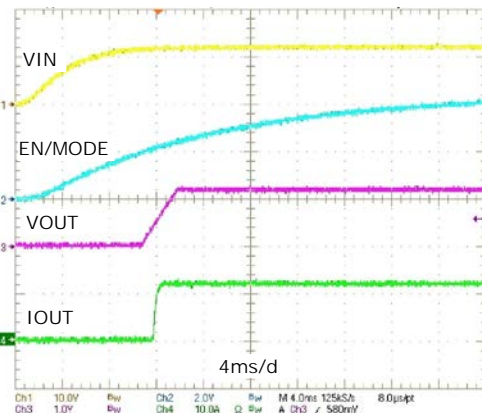


Figure 20: XR76112 Powerup, DCM/CCM, $I_{OUT}=12A$

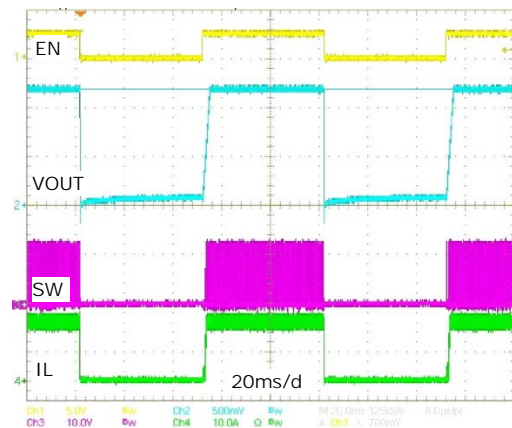


Figure 21: XR76112 Enable turn on/turn off, $1.2V_{OUT}$, 12A

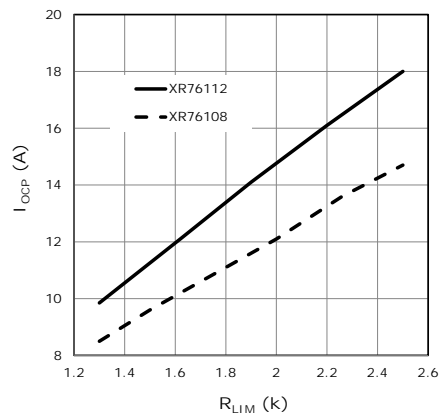


Figure 22: Typical I_{OCP} versus R_{LIM}

Efficiency – XR76108/ XR76112

$T_{\text{AMBIENT}} = 25^{\circ}\text{C}$, No Air flow, Inductor losses are included.

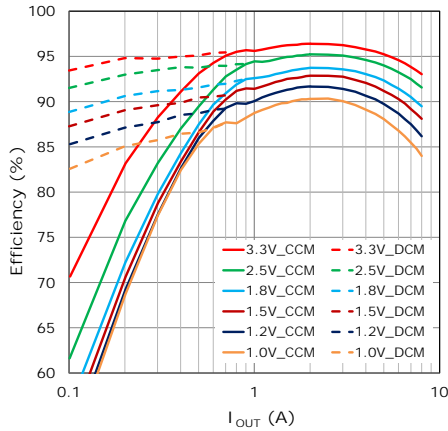


Figure 23: XR76108, 5V_{IN}, 600kHz, 1uH

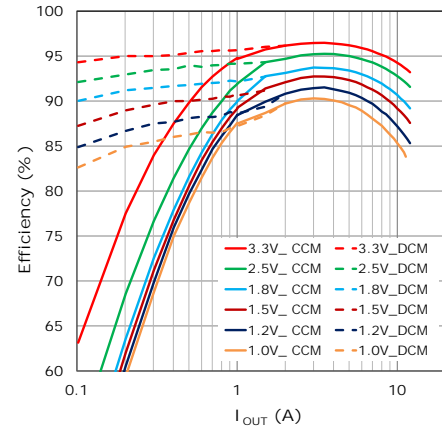


Figure 24: XR76112, 5V_{IN}, 600kHz, 0.56uH

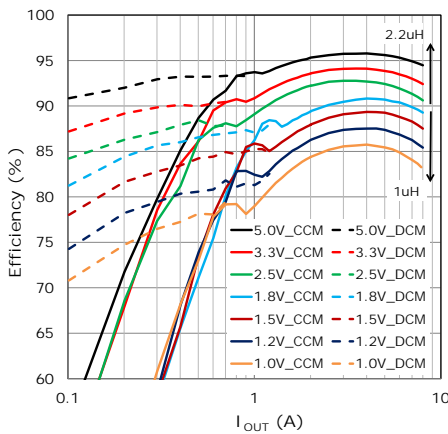


Figure 25: XR76108, 12V_{IN}, 600kHz

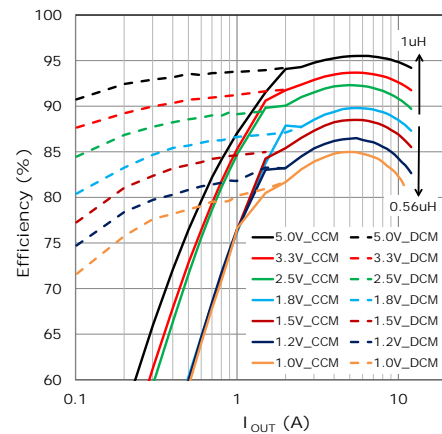


Figure 26: XR76112, 12V_{IN}, 600kHz

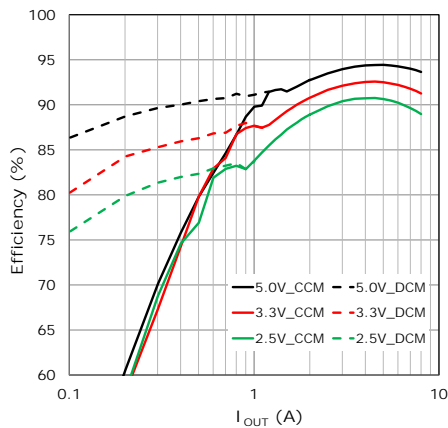


Figure 27: XR76108, 22V_{IN}, 400kHz, 3.3uH

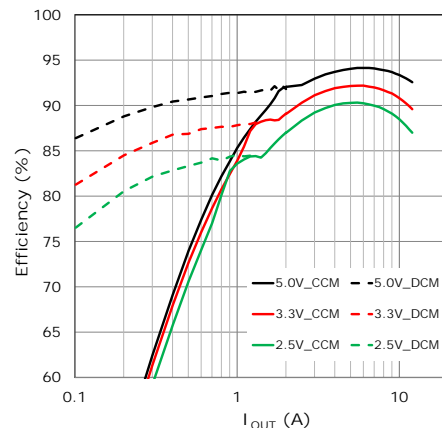


Figure 28: XR76112, 22V_{IN}, 400kHz, 2.2uH

Thermal Characteristics

No Air flow, $f=600\text{kHz}$

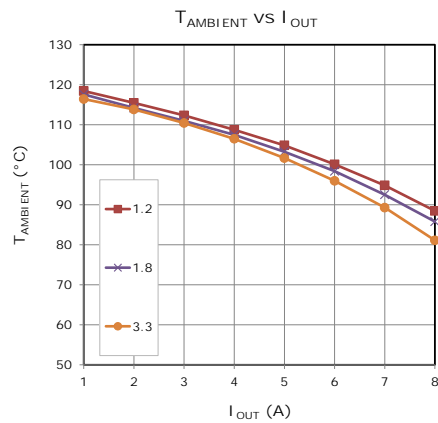


Figure 29: XR76108 Package Thermal Derating, 12VIN

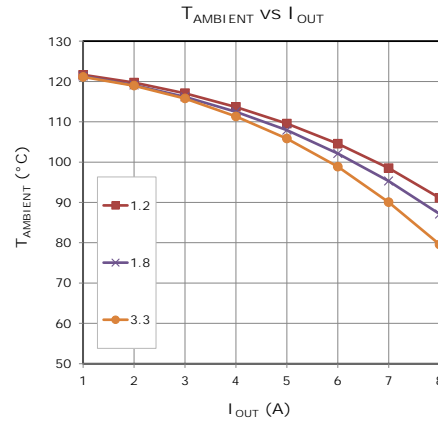


Figure 30: XR76108 Package Thermal Derating, 5VIN

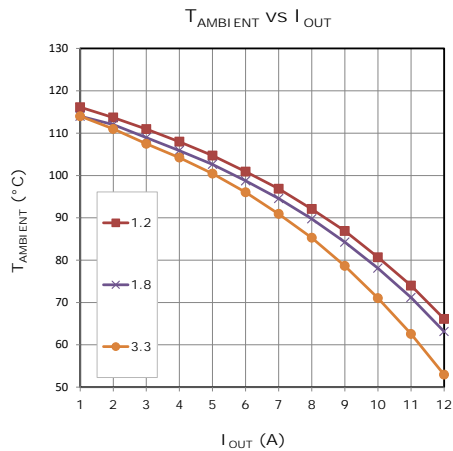


Figure 31: XR76112 Package Thermal Derating, 12V_{IN}

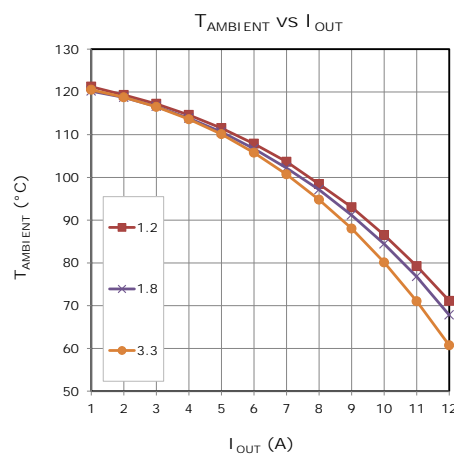


Figure 32: XR76112 Package Thermal Derating, 5V_{IN}

Detailed Operation

The XR76108/12 uses a synchronous step-down proprietary emulated current-mode Constant On-Time (COT) control scheme. The on-time, which is programmed via R_{ON} , is inversely proportional to V_{IN} and maintains a nearly constant frequency. The emulated current-mode control allows the use of ceramic output capacitors.

Each switching cycle begins with the high-side (switching) FET turning on for a preprogrammed time. At the end of the on-time, the high-side FET is turned off and the low-side (synchronous) FET is turned on for a preset minimum time (250ns nominal). This parameter is termed the Minimum Off-Time. After the minimum off-time the voltage at the feedback pin FB is compared to an internal voltage ramp at the feedback comparator. When V_{FB} drops below the ramp voltage, the high-side FET is turned on and the cycle repeats. This voltage ramp constitutes an emulated current ramp and allows for the use of ceramic capacitors, in addition to other capacitor types, for output filtering.

Enable/Mode

The EN/MODE pin accepts a tri-level signal that is used to control turn-on and turn-off. It also selects between two modes of operation: 'Forced CCM' and 'DCM/CCM'. If EN is pulled below 1.8V the regulator shuts down. A voltage between 2.0V and 2.8V selects the Forced CCM mode, which will run the converter in continuous conduction for all load currents. A voltage higher than 3.1V selects the DCM/CCM mode, which will run the converter in discontinuous conduction mode at light loads.

Selecting the Forced CCM Mode

In order to set the controller to operate in Forced CCM a voltage between 2.0V and 2.8V must be applied to EN/MODE. This can be achieved with an external control signal that meets the above voltage requirement. The EN/MODE can be derived from V_{IN} where an external control is not available. If V_{IN} is well regulated, use a resistor divider and set the voltage to 2.45V. If V_{IN} varies over a wide range, the circuit shown in figure 33 can be used to generate the required voltage.

Selecting the DCM/CCM Mode

In order to set the controller operation to DCM/CCM a voltage between 3.1V and 5.5V must be applied to EN/MODE pin and be sequenced with respect to V_{OUT} such that $2.0 \leq V_{EN} \leq 2.8V$ when V_{OUT} finishes softstart.

If an external 5V control signal is available use a low-pass RC and set the time constant to $RC = 5.5 \times t_{ss}$ where t_{ss} is the softstart time. R should be in the 50k-100k range. Time t_1 can be approximated from $t_1 = 2.8 \times t_{ss}$. The timing circuit and diagram are shown in figure 34.

If an external 3.3V control signal is available, use a low-pass RC and set the time constant to $RC = 2.1 \times t_{ss}$. R should be in the 50k-100k range. Time t_1 can be approximated from $t_1 = 1.9 \times t_{ss}$ (figure 34).

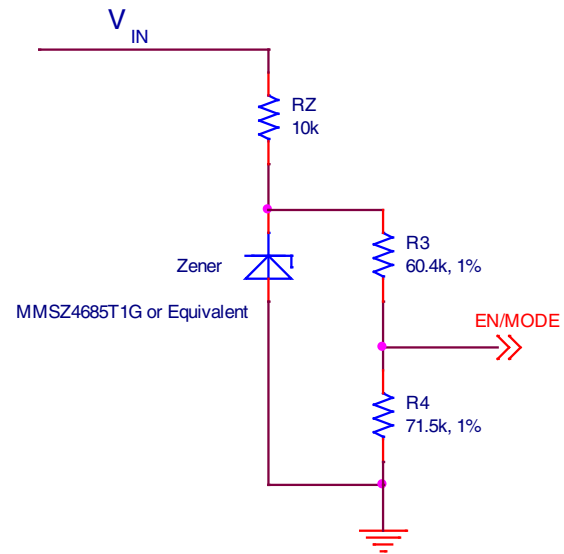


Figure 33: Selecting Forced CCM by deriving EN/MODE from V_{IN}

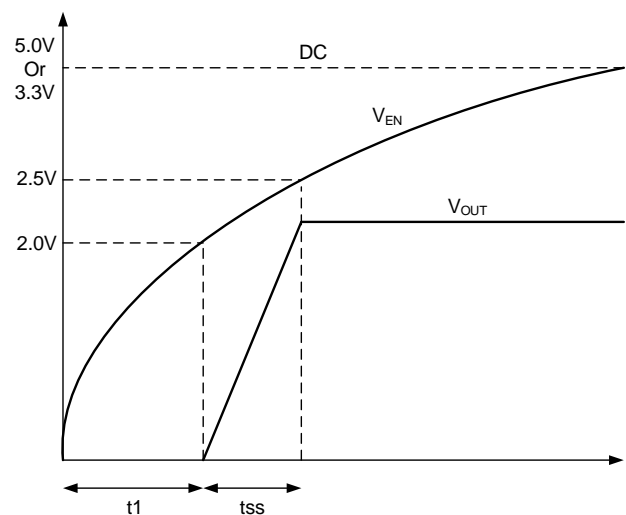
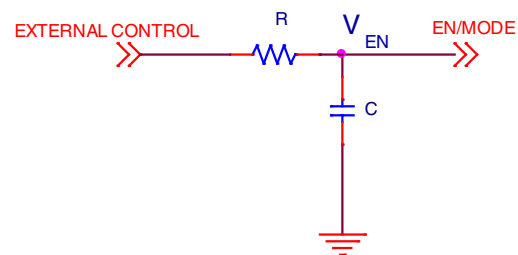


Figure 34: Timing circuit and diagram for selecting DCM/CCM by using an external enable signal

EN/MODE input must be derived from V_{IN} in applications where an external control is not available. The timing circuit and diagram are shown in figure 35. Calculate the time constant from $RC=4.7 \times t_{ss}$. The value of R3 should be between 50k and 100k. t_1 can be approximated from $t_1=2.7 \times t_{ss}$. The R3 and C in figure 35 correspond to 2.8ms typical softstart of the application circuit.

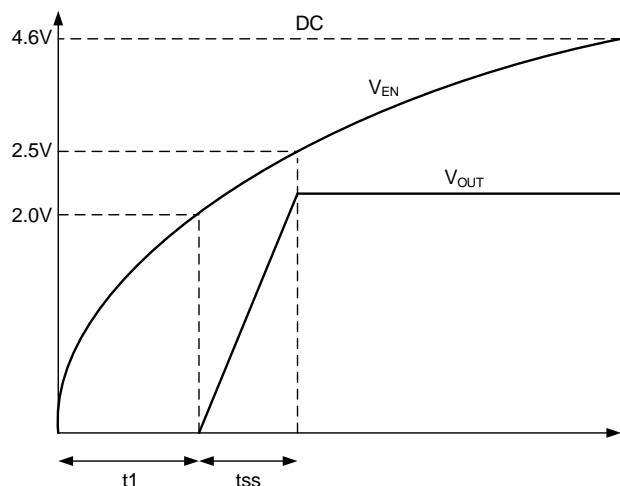
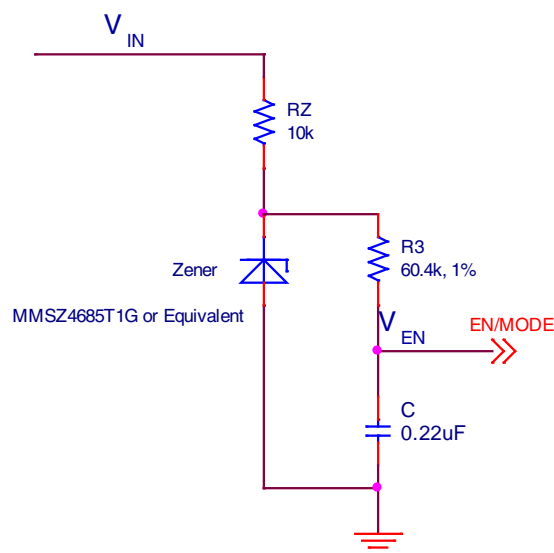


Figure 35: Timing circuit and diagram for selecting DCM/CCM by deriving EN/MODE from V_{IN}

Programming the On-Time

The on-time T_{ON} is programmed via resistor R_{ON} according to following equation:

$$R_{ON} = \frac{V_{IN} \times [T_{ON} - (3 \times 10^{-8})]}{2.9 \times 10^{-10}}$$

Where T_{ON} is calculated from:

$$T_{ON} = \frac{V_{OUT}}{V_{IN} \times f \times Eff.}$$

Where:

f is the desired switching frequency at nominal I_{OUT}

Eff. is the converter efficiency corresponding to nominal I_{OUT}

Substituting for T_{ON} in the first equation we get:

$$R_{ON} = \frac{\left(\frac{V_{OUT}}{f \times Eff.}\right) - [(3 \times 10^{-8}) \times V_{IN}]}{(2.9 \times 10^{-10})}$$

At $V_{IN}=12V$, $f=600kHz$, $I_{OUT}=8A$ and using the efficiency numbers from figure 25 we get the following R_{ON} for XR76108:

V_{OUT} (V)	R_{ON} (k Ω)
5.0	29.3
3.3	19.4
2.5	14.5
1.8	10.4
1.5	8.67
1.2	6.87
1.0	5.68

Figure 36: XR76108 R_{ON} for common output voltages, $V_{IN}=12V$, $I_{OUT}=8A$, $f=600kHz$

Over-Current Protection (OCP)

If the load current exceeds the programmed over-current I_{OCP} for four consecutive switching cycles, then the regulator enters the hiccup mode of operation. In hiccup mode the MOSFET gates are turned off for 110ms (hiccup timeout). Following the hiccup timeout a soft-start is attempted. If OCP persists, hiccup timeout will repeat. The regulator will remain in hiccup mode until load current is reduced below the programmed I_{OCP} . In order to program over-current protection use the following equation:

$$R_{LIM} = \frac{(I_{OCP} \times R_{DS(on)}) + 8mV}{I_{LIM}}$$

where:

R_{LIM} is resistor value for programming I_{OCP}

I_{OCP} is the over-current value to be programmed

$R_{DS(on)}=10m\Omega$ (XR76108)

$R_{DS(on)}=9m\Omega$ (XR76112)

8mV is the OCP comparator offset

I_{LIM} is the internal current that generates the necessary OCP comparator threshold (45 μ A)

Note that I_{LIM} has a positive temperature coefficient of 0.4%/°C. This is meant to approximately match and compensate for positive temperature coefficient of the synchronous FET's $R_{DS(on)}$.

The above equation is for worst-case analysis and safeguards against premature OCP. Actual value of I_{OCP} , for a given R_{LIM} , will be higher than that predicted by the above equation. Typical I_{OCP} versus R_{LIM} is shown in Figure 22.

Short-Circuit Protection (SCP)

If the output voltage drops below 60% of its programmed value, the regulator will enter hiccup mode. Hiccup mode will persist until the short-circuit is removed. The SCP circuit becomes active after PGOOD asserts high.

Over-Temperature Protection (OTP)

OTP triggers at a nominal controller temperature of 150°C. The gates of the switching FET and the synchronous FET are turned off. When controller temperature cools down to 135°C, soft-start is initiated and operation resumes.

Programming the Output Voltage

Use an external voltage divider as shown in Figure 1 to program the output voltage V_{OUT} .

$$R1 = R2 \times \left(\frac{V_{OUT}}{0.6} - 1 \right)$$

The recommended value for $R2$ is 2k Ω .

Programming the Soft-start

Place a capacitor C_{SS} between the SS and GND pins to program the soft-start. In order to program a soft-start time of T_{SS} , calculate the required capacitance C_{SS} from the following equation:

$$C_{SS} = T_{SS} \times \frac{10\mu A}{0.6V}$$

Feed-Forward Capacitor C_{FF}

The voltage divider $R1$ - $R2$ attenuates the output voltage ripple ($V_{OUT, RIPPLE}$) that is fed back to controller's FB pin. The steady-state voltage ripple at FB ($V_{FB, RIPPLE}$) must not exceed 50mV in order for the controller to function correctly. If $V_{FB, RIPPLE}$ is larger than 50mV, a C_{FF} should not be used. C_{OUT} should be increased as necessary in order to keep the $V_{FB, RIPPLE}$ below 50mV.

It is recommended to use a feed-forward capacitor (C_{FF}) if output voltage ripple ($V_{OUT, RIPPLE}$) is less than 50mV. C_{FF} provides a low-impedance/high-frequency path for the $V_{OUT, RIPPLE}$ to be transmitted to FB. It also helps get an optimum transient load response. Calculate C_{FF} from:

$$C_{FF} = \frac{1}{2 \times \pi \times f \times 0.1 \times R1}$$

A load step test should be performed and if necessary C_{FF} can be adjusted in order to get a critically damped transient load response.

Feed-Forward Resistor R_{FF}

Fast Turn on and turn off of power FETs gives rise to switching noise that may be coupled to the feedback pin. Excessive switching noise at FB will result in poor load regulation. A resistor R_{FF} , in series with C_{FF} , helps decouple noise and restore good load regulation. Maximum value of R_{FF} should not exceed $0.02 \times R1$.

Thermal Design

Proper thermal design is critical in controlling device temperatures and in achieving robust designs. There are a number of factors that affect the thermal performance. One key factor is the temperature rise of the devices in the package, which is a function of the thermal resistances of the devices inside the package and the power being dissipated.

The thermal resistances of the XR76108/12 are specified in the "Operating Ratings" section of this datasheet. The JEDEC θ_{JA} thermal resistance provided is based on tests that comply with the JESD51-2A "Integrated Circuit Thermal Test Method Environmental Conditions – Natural Convection" standard. JESD51-xx are a group of standards whose intent is to provide comparative data based on a standard test condition which includes a defined board construction. Since the actual board design in the final application will be different from the board defined in the standard, the thermal resistances in the final design may be different from those shown.

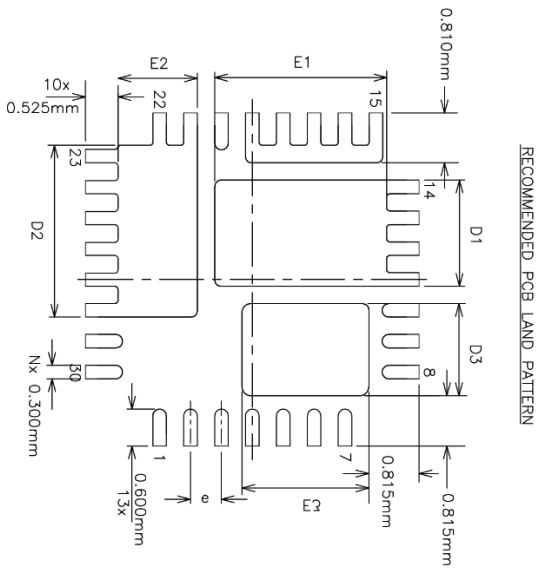
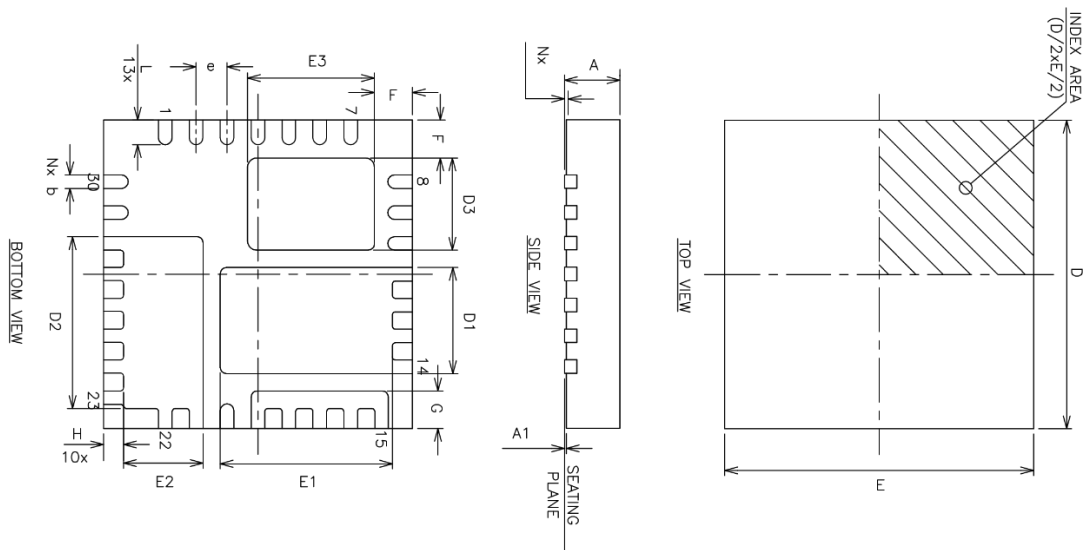
The package thermal derating curves for the XR76108 are shown in Figures 29 and 30. These correspond to input voltage of 12V and 5V respectively. The package thermal derating curves for the XR76112 are shown in Figures 31 and 32.

Operation at $V_{IN} < 6V$

As V_{IN} falls below approximately 5V, the V_{CC} regulator will start to operate in dropout. This means it is no longer regulating the output of V_{CC} . V_{CC} is designed with a UVLO function to ensure all internal circuitry has sufficient voltage to operate to meet datasheet specifications and properly drive the internal MOSFETs. The UVLO is set to allow the chip to start operating once V_{CC} reaches 4.25V and will disable the chip if the voltage falls below 4.00V.

When V_{IN} is 4.5V and the part is not switching, the output of the V_{CC} regulator will be close to V_{IN} and be high enough to ensure it is above the V_{CC} UVLO. Although once switching starts the output of V_{CC} may fall as low as 4.3V, the UVLO shutdown threshold is guaranteed to be less than 4.25V.

Mechanical Dimensions



SYMBOLS	30LD 5x5mm QFN 0.50 PITCH			DIMENSIONS IN INCH		
	DIMENSIONS IN MM (Control Unit)			(Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	0.800	0.900	1.000	0.031	0.035	0.039
A1	0.000	0.020	0.050	0.000	0.001	0.002
b	0.180	0.250	0.300	0.007	0.010	0.012
D	5.000 BSC			0.200 BSC		
E	5.000 BSC			0.200 BSC		
e	0.500 BSC			0.020 BSC		
F	0.615 REF			0.024 REF		
G	0.610 REF			0.024 REF		
H	0.325 REF			0.013 REF		
D1	1.570	1.720	1.820	0.062	0.068	0.072
E1	2.635	2.785	2.885	0.104	0.110	0.113
D2	2.635	2.785	2.885	0.104	0.110	0.113
E2	1.135	1.285	1.385	0.045	0.050	0.054
D3	1.345	1.495	1.595	0.053	0.059	0.063
E3	1.903	2.053	2.153	0.075	0.081	0.085
L	0.300	0.400	0.500	0.012	0.016	0.020
N	30			30		

Drawing No: POD-00000018
Revision: A

Revision History

Revision	Date	Description
1A	March 2014	Initial release: ECN 1413-13 03-26-14
2A	August 2014	Changed figure 1, 3, 17-20, 33-38. Extend input operating range down to 4.5V. Changed V_{CC} dropout conditions. Changed V_{CC} UVLO specification. Added applications information for operating $V_{IN} < 6V$. Added ESD CDM Rating. Added to SW and BST pin definition. Removed Diode emulation write up. Added selecting the CCM mode and selecting the DCM/CCM mode applications information. Changed CFF and RFF write up and equations. Changed programming the TON write up and equations. On page 1 in the general description and Features section changed minimum VIN range from 5.0V to 4.5V.
2B	June 2018	Updated to MaxLinear logo. Updated format and Ordering Information table.

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