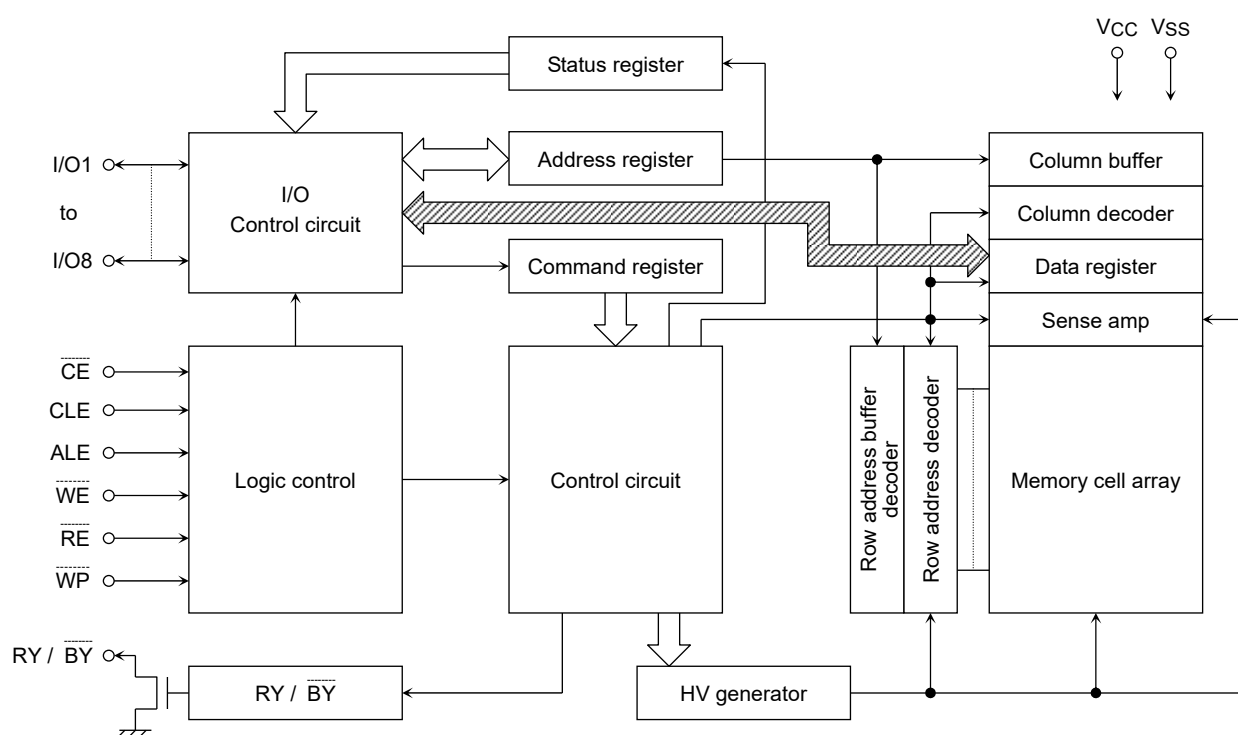


**PIN ASSIGNMENT (TOP VIEW)**

	1	2	3	4	5	6	7	8	9	10
A	NC	NC							NC	NC
B	NC								NC	NC
C			$\overline{\text{WP}}$	ALE	V <sub>SS</sub>	$\overline{\text{CE}}$	$\overline{\text{WE}}$	$\overline{\text{RY/BY}}$		
D			NC	$\overline{\text{RE}}$	CLE	NC	NC	NC		
E			NC	NC	NC	NC	NC	NC		
F			NC	NC	NC	NC	NC	NC		
G			NC	NC	NC	NC	NC	NC		
H			NC	I/O1	NC	NC	NC	V <sub>CC</sub>		
J			NC	I/O2	NC	V <sub>CC</sub>	I/O6	I/O8		
K			V <sub>SS</sub>	I/O3	I/O4	I/O5	I/O7	V <sub>SS</sub>		
L	NC	NC							NC	NC
M	NC	NC							NC	NC

**PIN NAMES**

I/O1 to I/O8	I/O port
$\overline{\text{CE}}$	Chip enable
$\overline{\text{WE}}$	Write enable
$\overline{\text{RE}}$	Read enable
CLE	Command latch enable
ALE	Address latch enable
$\overline{\text{WP}}$	Write protect
RY / $\overline{\text{BY}}$	Ready/Busy
V <sub>CC</sub>	Power supply
V <sub>SS</sub>	Ground
NC	No Connection

**BLOCK DIAGRAM****ABSOLUTE MAXIMUM RATINGS**

SYMBOL	RATING	VALUE	UNIT
V <sub>CC</sub>	Power Supply Voltage	-0.6 to 4.6	V
V <sub>IN</sub>	Input Voltage	-0.6 to 4.6	V
V <sub>I/O</sub>	Input / Output Voltage	-0.6 to V <sub>CC</sub> + 0.3 (≤ 4.6 V)	V
P <sub>D</sub>	Power Dissipation	0.3	W
T <sub>STG</sub>	Storage Temperature	-55 to 125	°C
T <sub>OPR</sub>	Operating Temperature	-40 to 85	°C

Note: Avoid locations where the device may be exposed to water (wet, rain, dew condensation, etc.)

**CAPACITANCE** \*(T<sub>a</sub> = 25°C, f = 1 MHz)

SYMBOL	PARAMETER	CONDITION	MIN	MAX	UNIT
C <sub>IN</sub>	Input	V <sub>IN</sub> = 0 V	—	10	pF
C <sub>OUT</sub>	Output	V <sub>OUT</sub> = 0 V	—	10	pF

\* This parameter is periodically sampled and is not tested for every device.

**VALID BLOCKS**

SYMBOL	PARAMETER	MIN	TYP.	MAX	UNIT
NvB	Number of Valid Blocks	2008	—	2048	Blocks

NOTE: The device occasionally contains unusable blocks. Refer to Application Note (13) toward the end of this document.  
The first block (Block 0) is guaranteed to be a valid block at the time of shipment.  
The specification for the minimum number of valid blocks is applicable over lifetime.

**DC OPERATING CONDITIONS**

SYMBOL	PARAMETER	MIN	TYP.	MAX	UNIT
V <sub>CC</sub>	Power Supply Voltage	2.7	—	3.6	V
V <sub>IH</sub>	High Level Input Voltage	V <sub>CC</sub> × 0.8	—	V <sub>CC</sub> + 0.3	V
V <sub>IL</sub>	Low Level Input Voltage	−0.3*	—	V <sub>CC</sub> × 0.2	V

\* −2 V (pulse width lower than 20 ns)

**DC CHARACTERISTICS (Ta = −40 to 85°C, Vcc = 2.7 to 3.6V)**

SYMBOL	PARAMETER	CONDITION	MIN	TYP.	MAX	UNIT
I <sub>IL</sub>	Input Leakage Current	V <sub>IN</sub> = 0 V to V <sub>CC</sub>	—	—	±10	μA
I <sub>LO</sub>	Output Leakage Current	V <sub>OUT</sub> = 0 V to V <sub>CC</sub>	—	—	±10	μA
I <sub>CCO1</sub>	Serial Read Current	$\overline{CE} = V_{IL}$ , I <sub>OUT</sub> = 0 mA, t <sub>RC</sub> = 25 ns	—	—	30	mA
I <sub>CCO2</sub>	Programming Current	—	—	—	30	mA
I <sub>CCO3</sub>	Erasing Current	—	—	—	30	mA
I <sub>CCS</sub>	Standby Current	$\overline{CE} = V_{CC} - 0.2\text{ V}$ , $\overline{WP} = 0\text{ V}/V_{CC}$	—	—	50	μA
V <sub>OH</sub>	High Level Output Voltage	I <sub>OH</sub> = −0.1 mA	V <sub>CC</sub> − 0.2	—	—	V
V <sub>OL</sub>	Low Level Output Voltage	I <sub>OL</sub> = 0.1 mA	—	—	0.2	V
I <sub>OL</sub> (RY / $\overline{BY}$ )	Output Current of RY / $\overline{BY}$ pin	V <sub>OL</sub> = 0.2 V	—	4	—	mA

**AC CHARACTERISTICS AND OPERATING CONDITIONS**

(Ta = -40 to 85°C, Vcc = 2.7 to 3.6V)

SYMBOL	PARAMETER	MIN	MAX	UNIT
tCLS	CLE Setup Time	12	—	ns
tCLH	CLE Hold Time	5	—	ns
tCS	CE Setup Time	20	—	ns
tCH	CE Hold Time	5	—	ns
tWP	Write Pulse Width	12	—	ns
tALS	ALE Setup Time	12	—	ns
tALH	ALE Hold Time	5	—	ns
tDS	Data Setup Time	12	—	ns
tDH	Data Hold Time	5	—	ns
tWC	Write Cycle Time	25	—	ns
tWH	WE High Hold Time	10	—	ns
tWW	WP High to WE Low	100	—	ns
tRR	Ready to RE Falling Edge	20	—	ns
tRW	Ready to WE Falling Edge	20	—	ns
tRP	Read Pulse Width	12	—	ns
tRC	Read Cycle Time	25	—	ns
tREA	RE Access Time	—	20	ns
tCEA	CE Access Time	—	25	ns
tCLR	CLE Low to RE Low	10	—	ns
tAR	ALE Low to RE Low	10	—	ns
tRHOH	RE High to Output Hold Time	25	—	ns
tRLOH	RE Low to Output Hold Time	5	—	ns
tRHZ	RE High to Output High Impedance	—	60	ns
tCHZ	CE High to Output High Impedance	—	20	ns
tCSD	CE High to ALE or CLE Don't Care	0	—	ns
tREH	RE High Hold Time	10	—	ns
tIR	Output-High-Impedance-to-RE Falling Edge	0	—	ns
tRHW	RE High to WE Low	30	—	ns
tWHC	WE High to CE Low	30	—	ns
tWHR	WE High to RE Low	60	—	ns
tWB	WE High to Busy	—	100	ns
tRST	Device Reset Time (Ready/Read/Program/Erase)	—	5/5/10/500	μs

\*1: tCLS and tALS can not be shorter than tWP

\*2: tCS should be longer than tWP + 8ns.

**AC TEST CONDITIONS**

PARAMETER	CONDITION
	V <sub>CC</sub> : 2.7 to 3.6V
Input level	V <sub>CC</sub> – 0.2 V, 0.2 V
Input pulse rise and fall time	3 ns
Input comparison level	V <sub>CC</sub> / 2
Output data comparison level	V <sub>CC</sub> / 2
Output load	C <sub>L</sub> (50 pF) + 1 TTL

Note: Busy to ready time depends on the pull-up resistor tied to the RY /  $\overline{\text{BY}}$  pin.  
(Refer to Application Note (9) toward the end of this document)

**PROGRAMMING / ERASING / READING CHARACTERISTICS**

(T<sub>a</sub> = -40 to 85°C, V<sub>CC</sub> = 2.7 to 3.6V)

SYMBOL	PARAMETER	MIN	TYP.	MAX	UNIT	NOTES
t <sub>PROG</sub>	Programming Time	—	300	700	μs	
t <sub>DCBSYW1</sub>	Data Cache Busy Time in Write Cache (following 11h)	—	—	10	μs	
t <sub>DCBSYW2</sub>	Data Cache Busy Time in Write Cache (following 15h)	—	—	700	μs	(2)
N	Number of Partial Program Cycles in the Same Page	—	—	4		(1)
t <sub>BERASE</sub>	Block Erasing Time	—	2.5	5	ms	
t <sub>R</sub>	Memory Cell Array to Starting Address	—	—	25	μs	
t <sub>DCBSYR1</sub>	Data Cache Busy in Read Cache (following 31h and 3Fh)	—	—	25	μs	
t <sub>DCBSYR2</sub>	Data Cache Busy in Page Copy (following 3Ah)	—	—	30	μs	

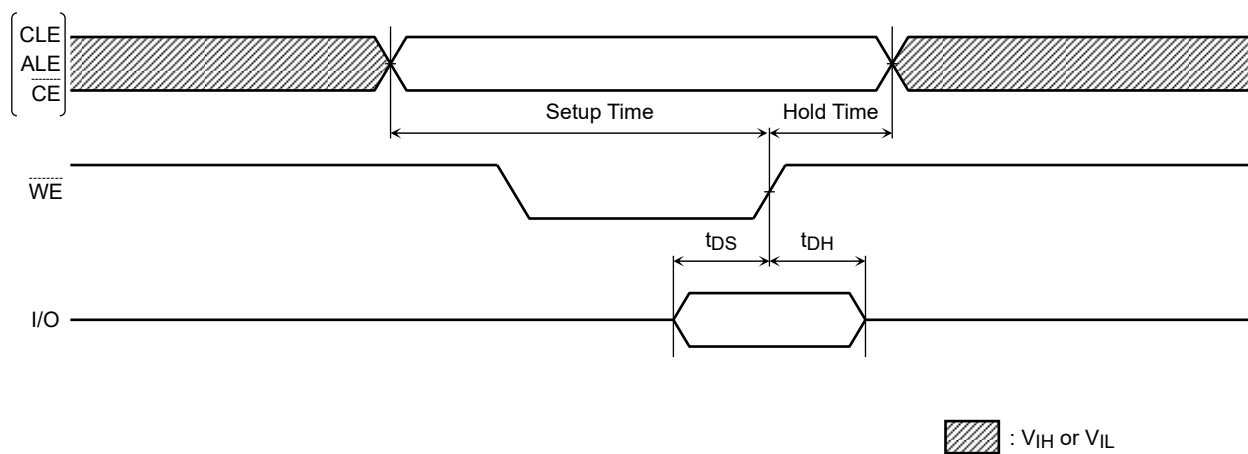
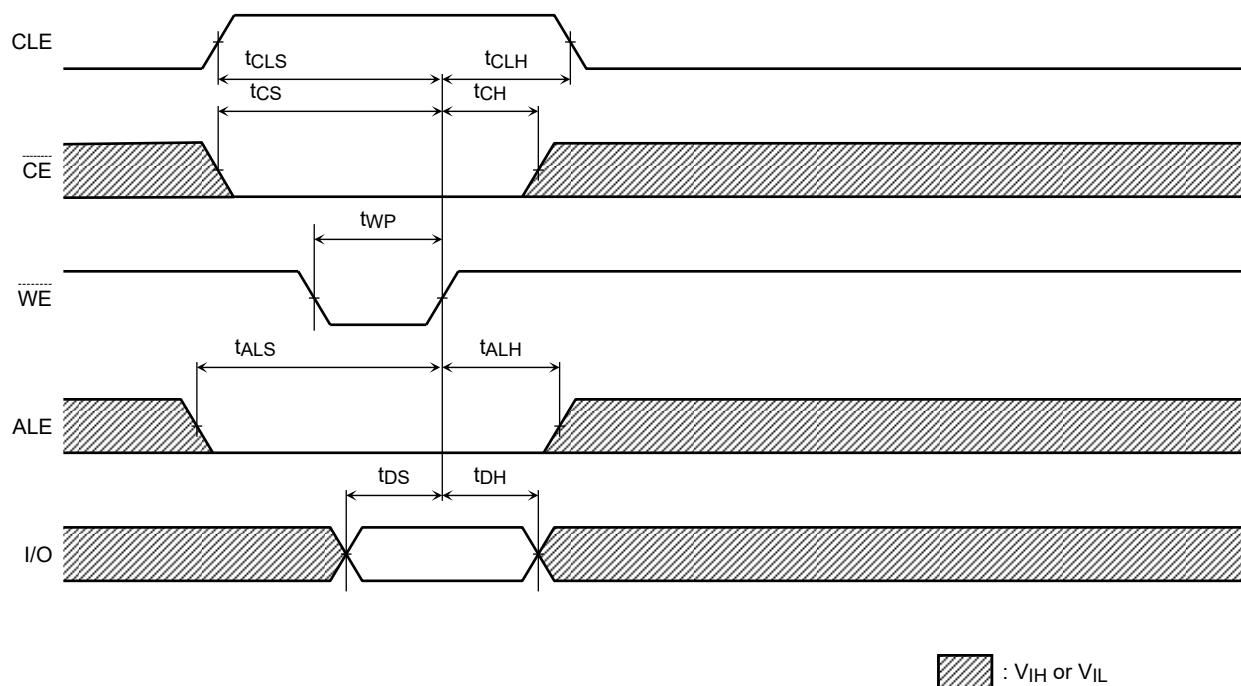
(1) Refer to Application Note (12) toward the end of this document.

(2) t<sub>DCBSYW2</sub> depends on the timing between internal programming time and data in time.

**Data Output**

When t<sub>REH</sub> is long, output buffers are disabled by /RE=High, and the hold time of data output depends on t<sub>RHOH</sub> (25ns MIN). Under this condition, the waveforms look like Normal Serial Read Mode.

When t<sub>REH</sub> is short, output buffers are not disabled by /RE=High, and the hold time of data output depends on t<sub>RLOH</sub> (5ns MIN). Under this condition, output buffers are disabled by the rising edge of CLE, ALE, /CE or the falling edge of /WE, and waveforms look like Extended Data Output Mode.

**TIMING DIAGRAMS****Latch Timing Diagram for Command/Address/Data****Command Input Cycle Timing Diagram**

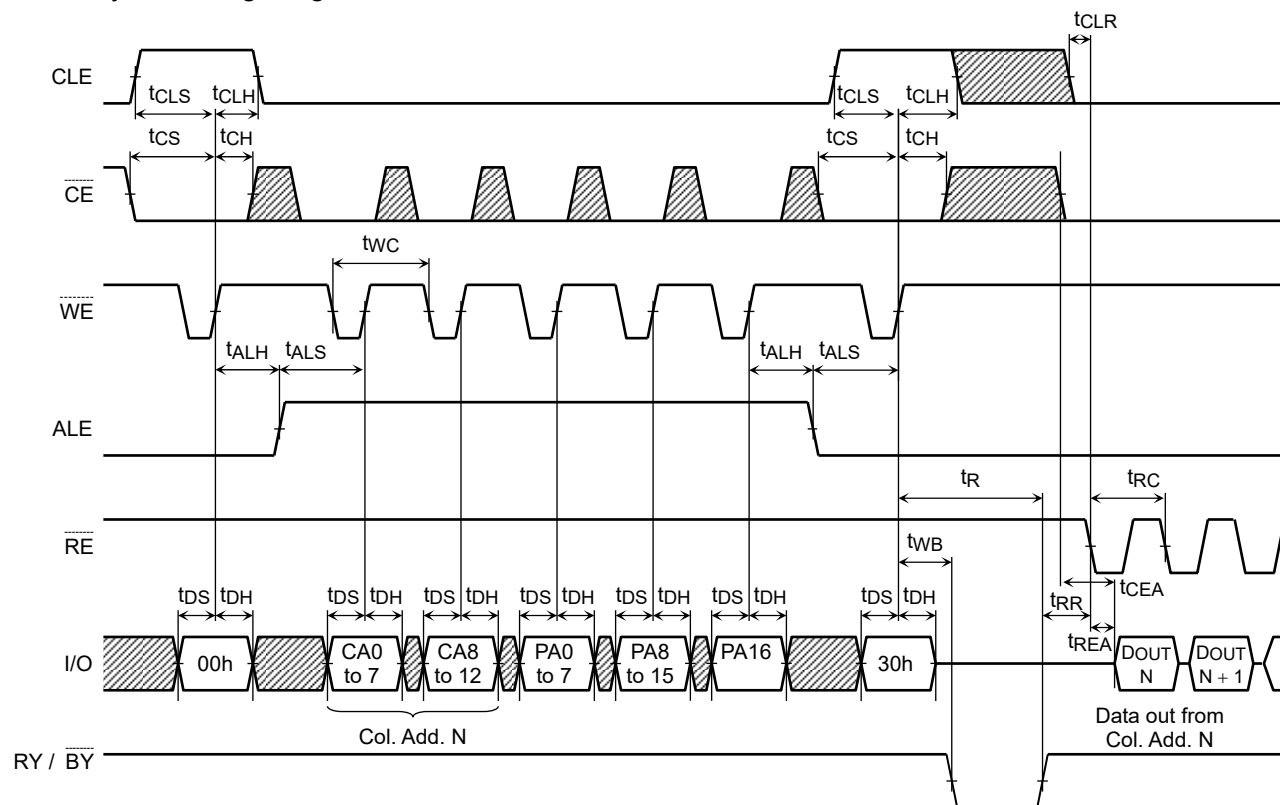
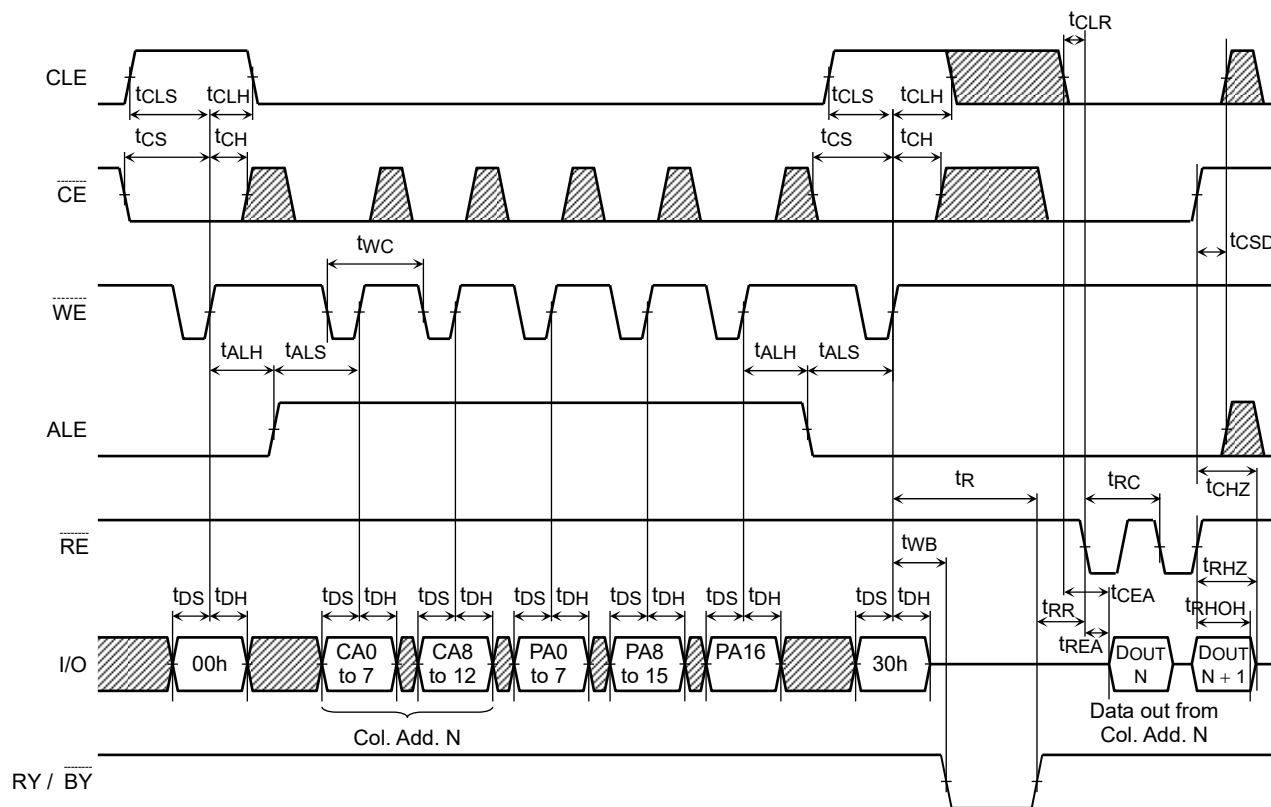


Timing diagram for the 70h/71h\* command sequence. The diagram shows the relationship between CLE, CE, WE, RE, I/O, and RY / BY signals. Key timing parameters are labeled:  $t_{CLS}$ ,  $t_{CLH}$ ,  $t_{CLR}$ ,  $t_{CS}$ ,  $t_{WP}$ ,  $t_{CH}$ ,  $t_{CEA}$ ,  $t_{WHC}$ ,  $t_{WHR}$ ,  $t_{CHZ}$ ,  $t_{DS}$ ,  $t_{DH}$ ,  $t_{IR}$ ,  $t_{REA}$ ,  $t_{RHZ}$ , and  $t_{RHOH}$ . The I/O signal shows a sequence of operations: 70h/71h\* (data read), a shaded area (data read), and Status output (data read). The RY / BY signal is active high.

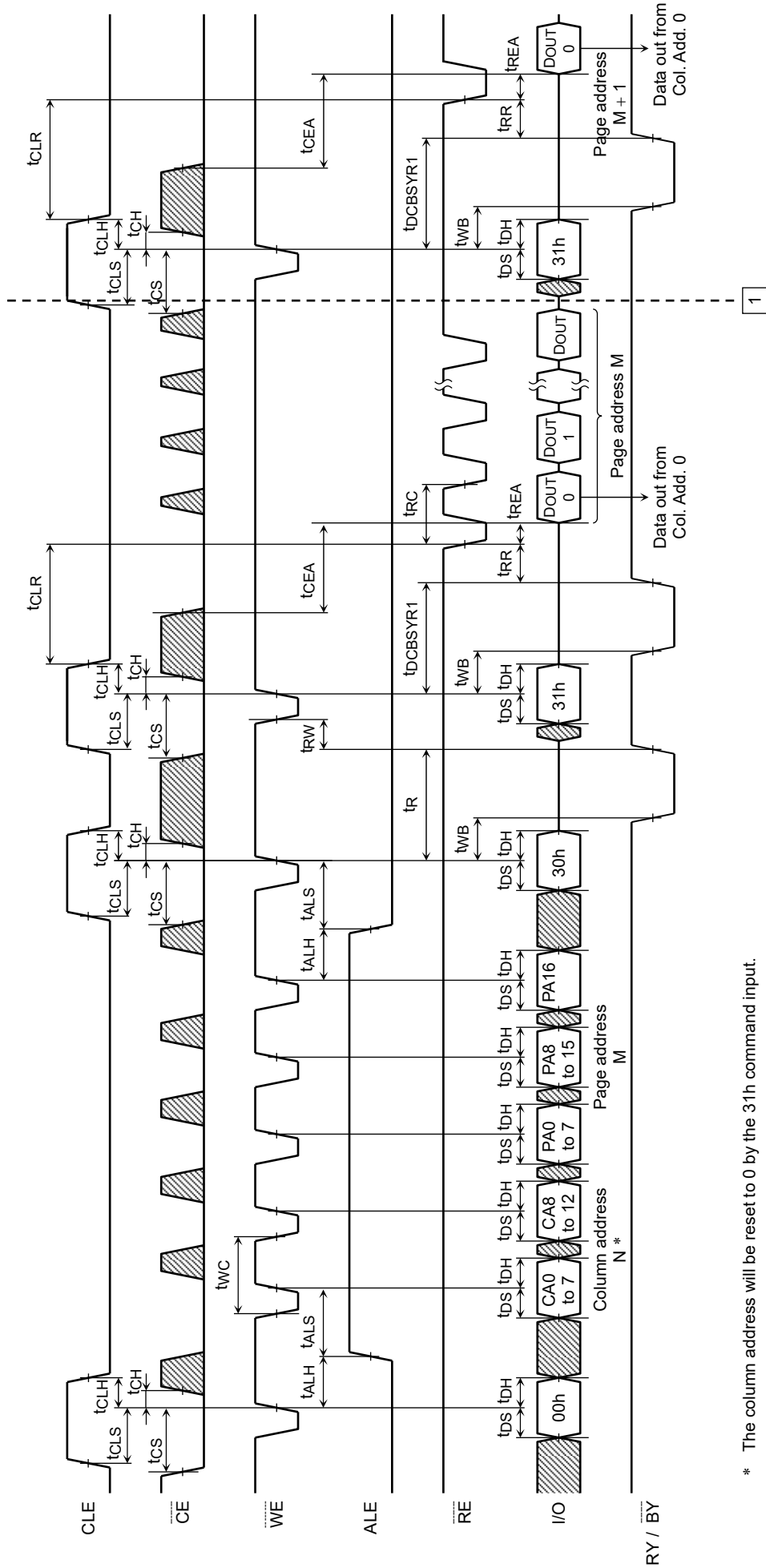
\*: 70h/71h represent the hexadecimal number



## Read Cycle Timing Diagram

Read Cycle Timing Diagram: When Interrupted by  $\overline{CE}$ 

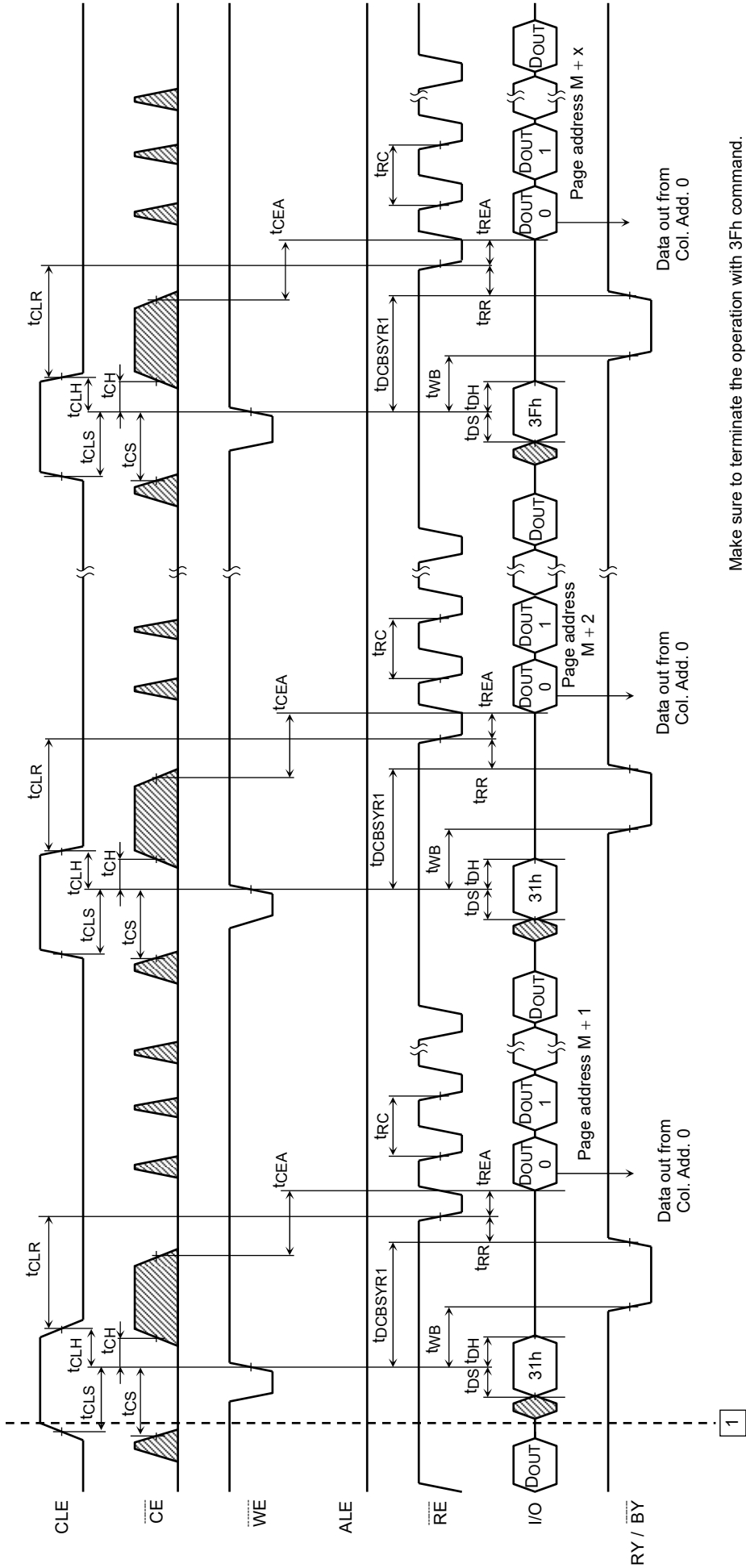
Read Cycle with Data Cache Timing Diagram (1/2)



Continues to 1 of next page

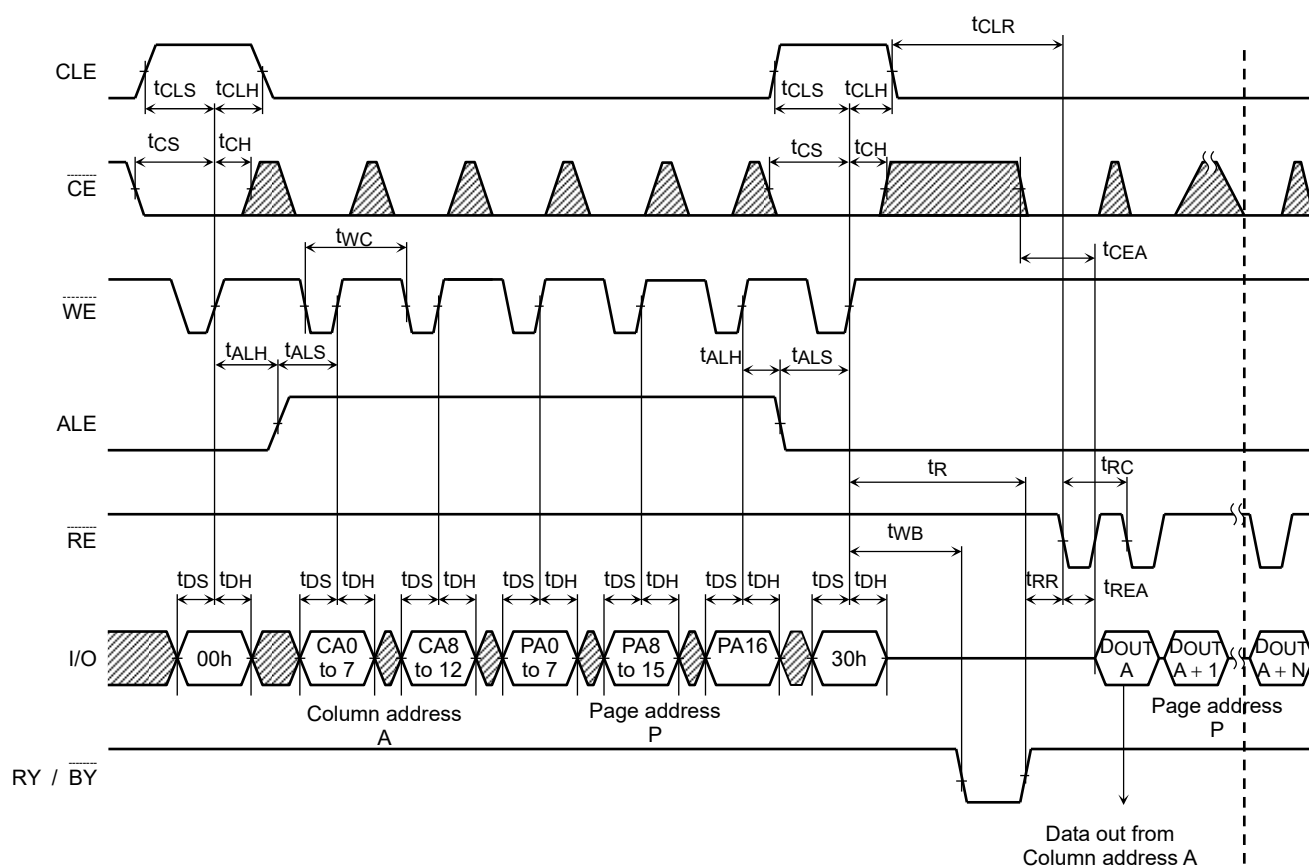
\* The column address will be reset to 0 by the 31h command input.

Read Cycle with Data Cache Timing Diagram (2/2)



Continues from 1 of previous page

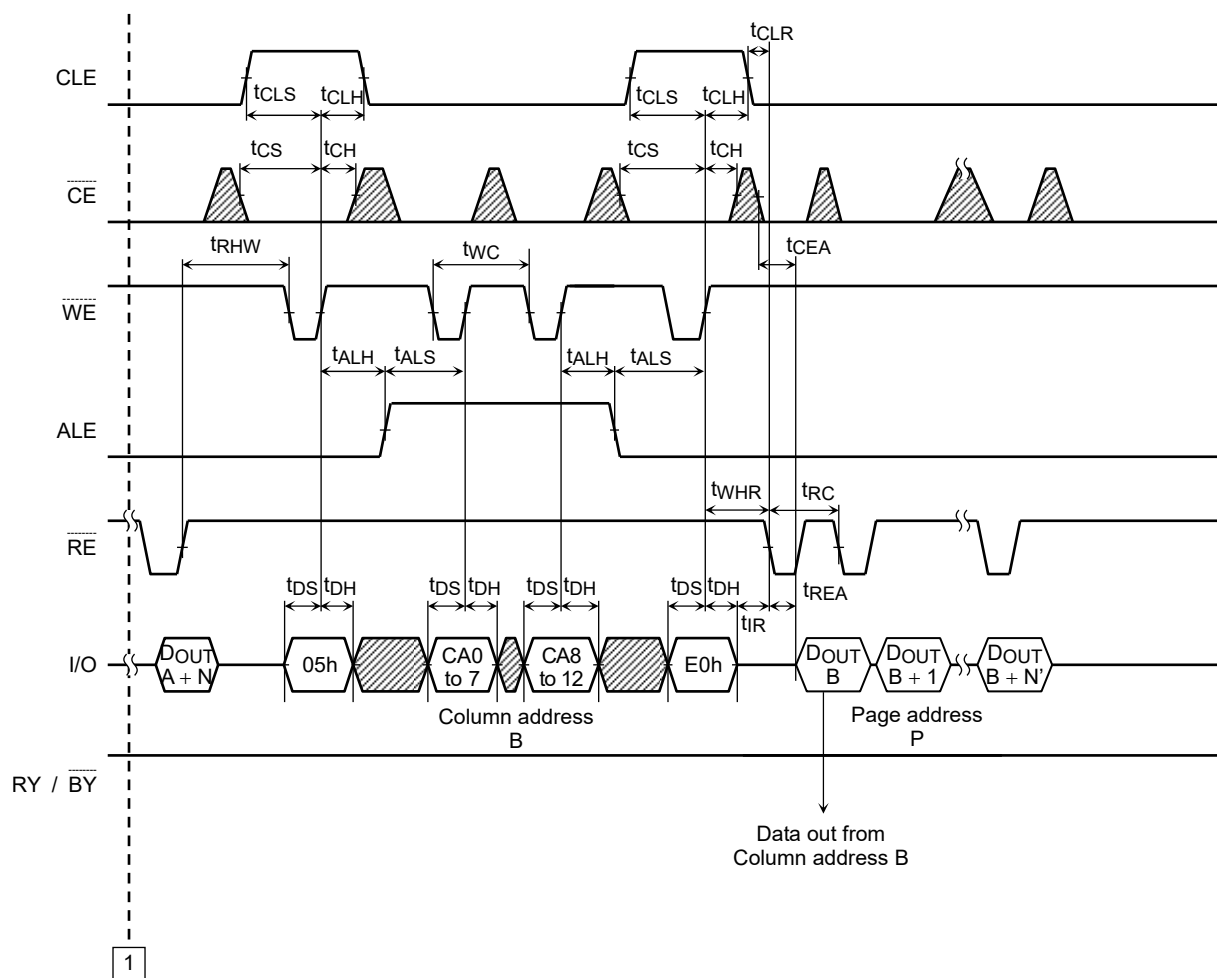
## Column Address Change in Read Cycle Timing Diagram (1/2)



1

Continues to 1 of next page

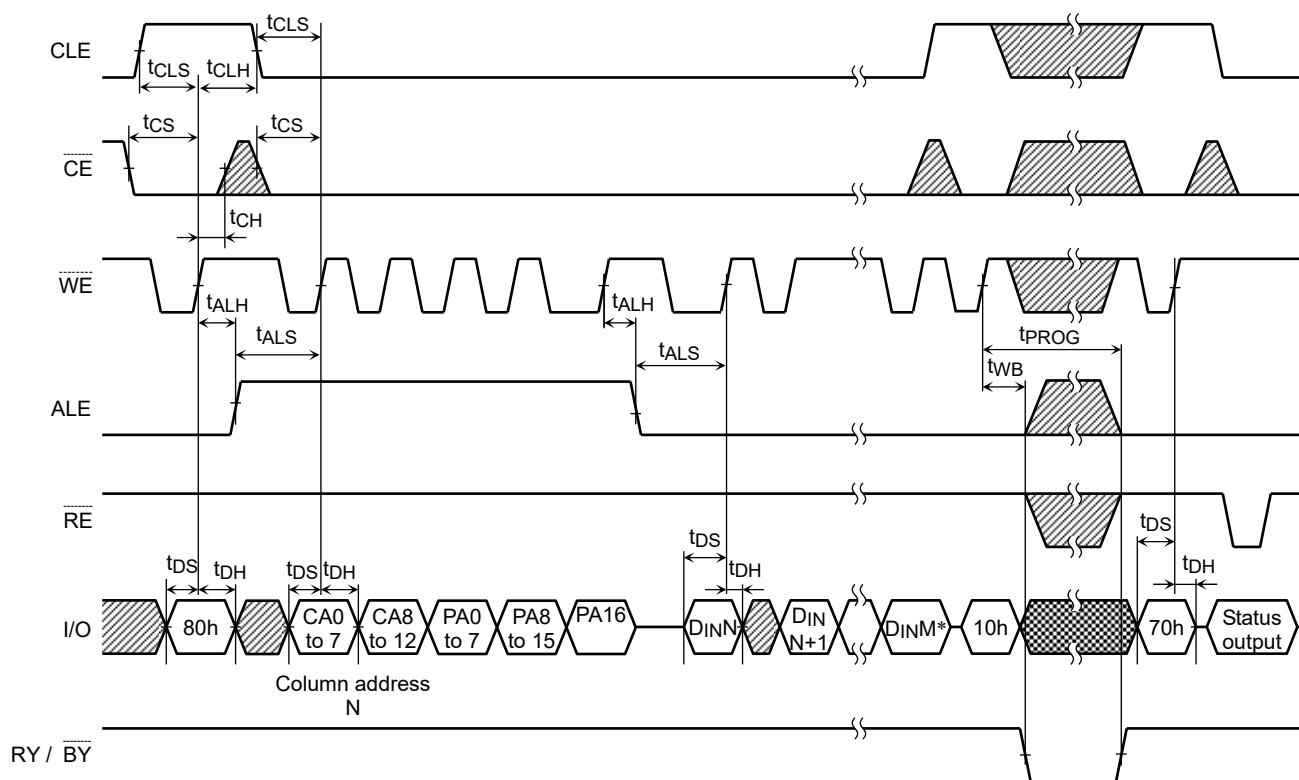
## Column Address Change in Read Cycle Timing Diagram (2/2)



Continues from 1 of previous page



## Auto-Program Operation Timing Diagram

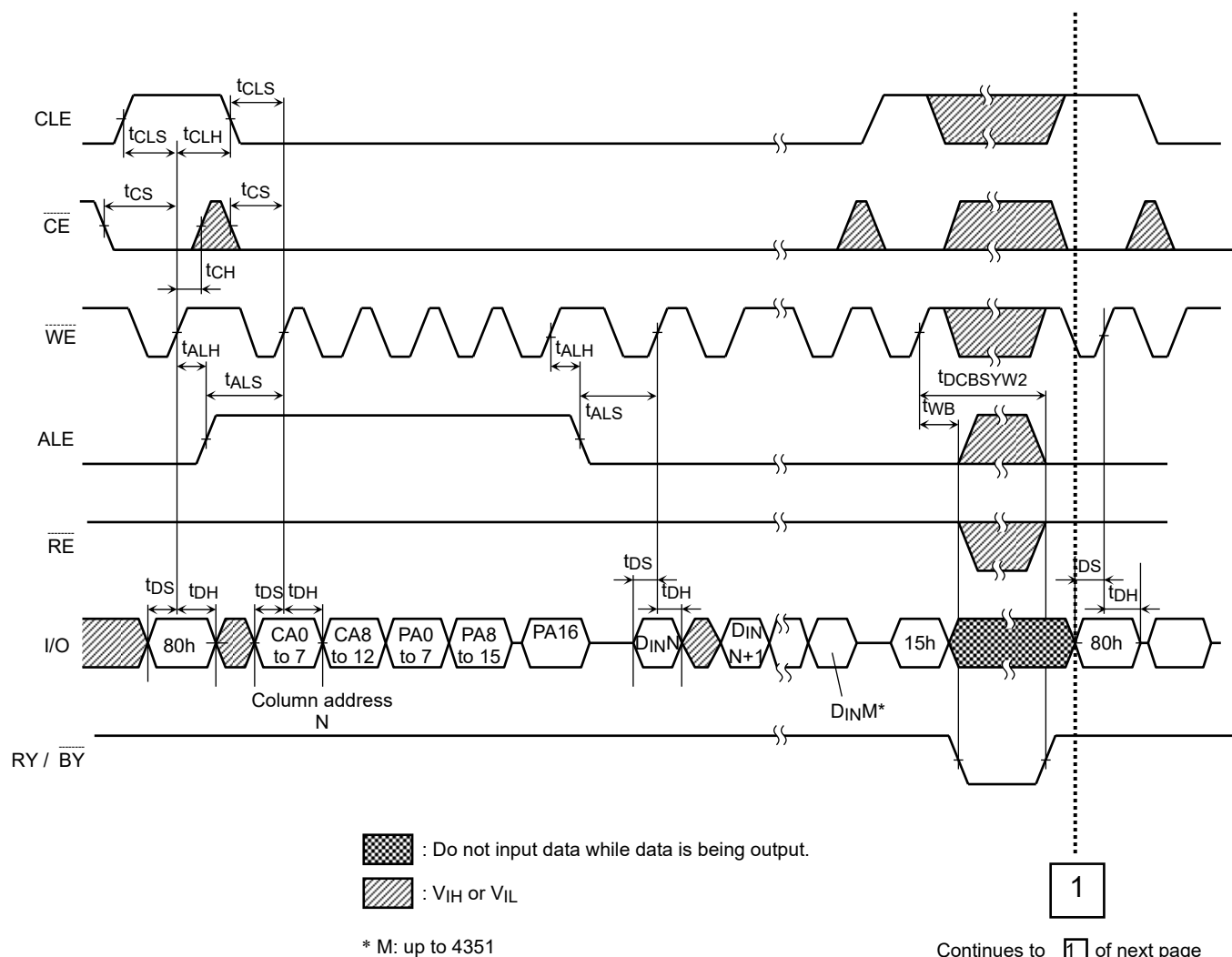


■ : Do not input data while data is being output.

▨ :  $V_{IH}$  or  $V_{IL}$

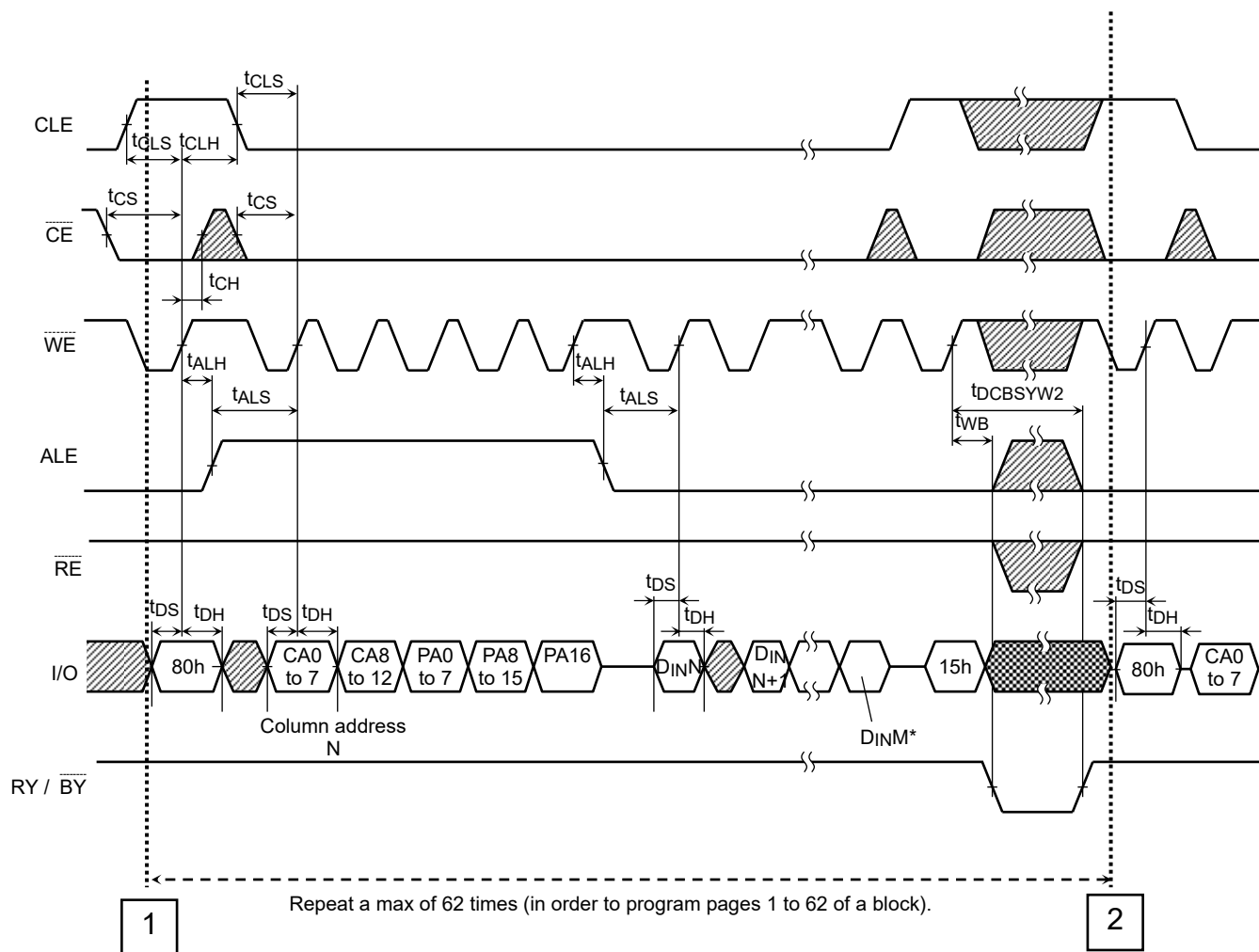
\* M: up to 4351

## Auto-Program Operation with Data Cache Timing Diagram (1/3)







## Auto-Program Operation with Data Cache Timing Diagram (2/3)



Continues from 1 of previous page

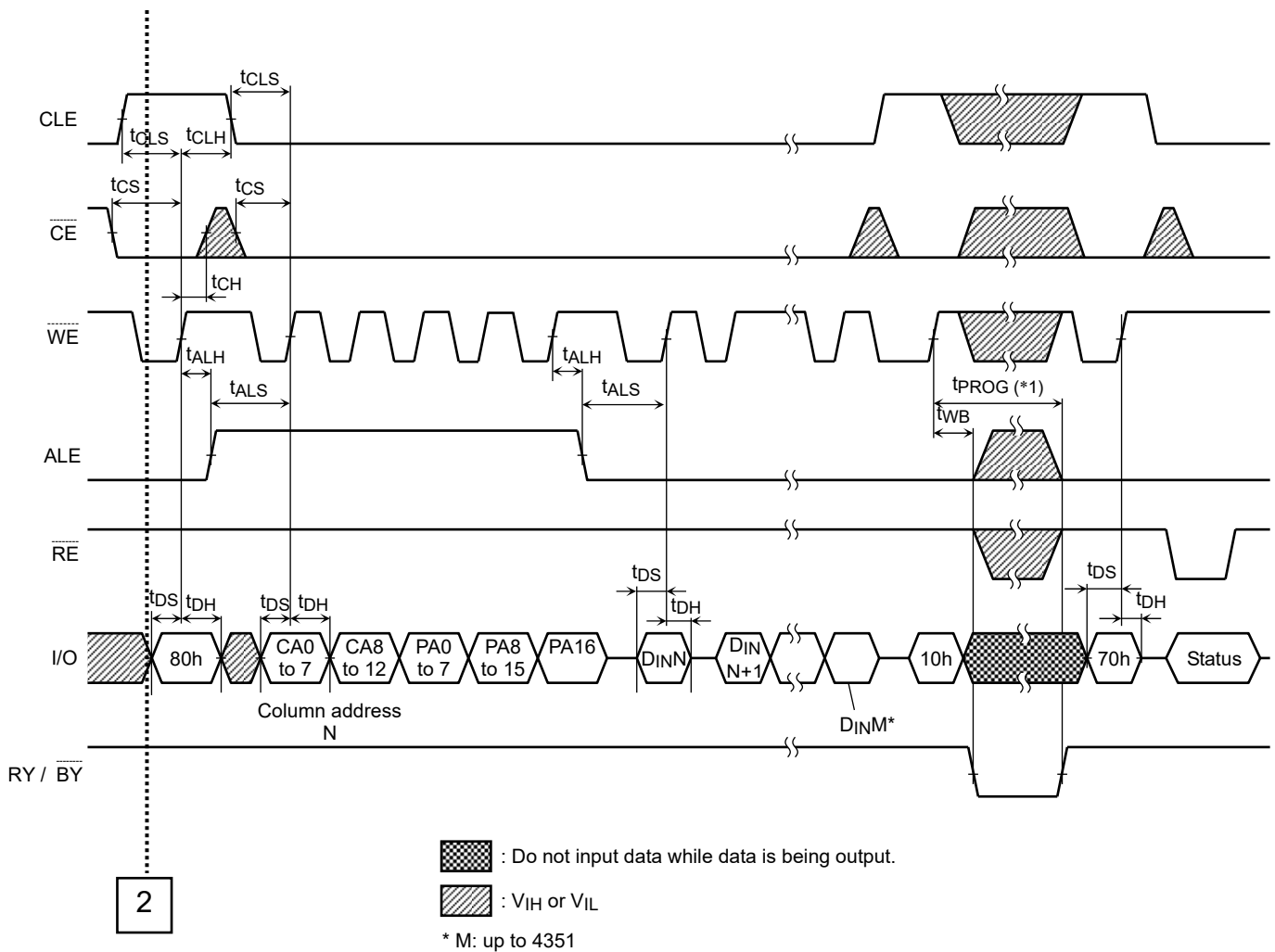
Continues to 2 of next page

 : Do not input data while data is being output.

 :  $V_{IH}$  or  $V_{IL}$

\* M: up to 4351

Auto-Program Operation with Data Cache Timing Diagram (3/3)



Continues from **2** of previous page

(\*1)  $t_{PROG}$ : Since the last page's programming by 10h command is initiated after the previous cache program, the  $t_{PROG}$  during cache programming is given by the following equation.

$$t_{PROG} = t_{PROG} \text{ of the last page} + t_{PROG} \text{ of the previous page} - A$$

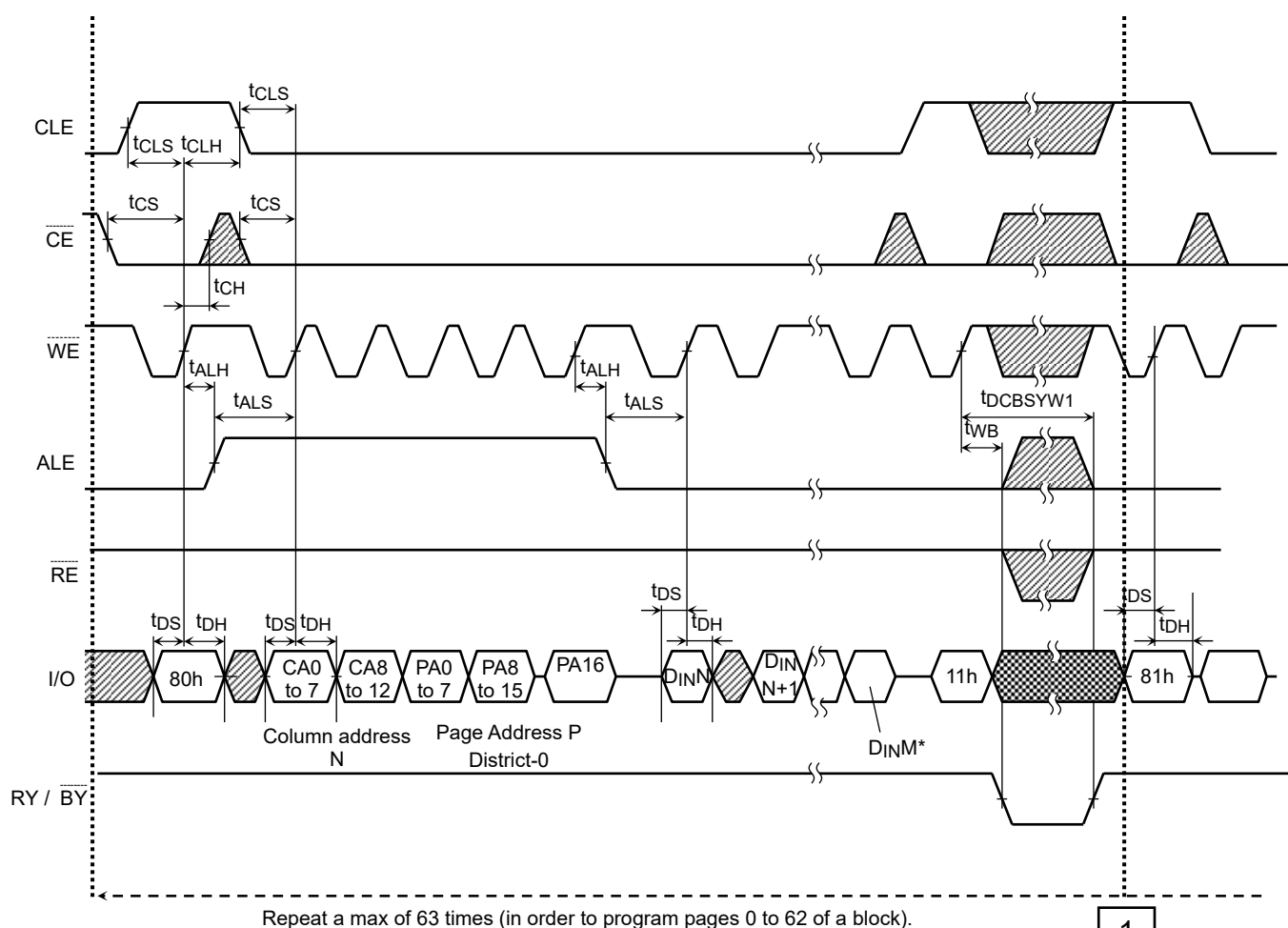
$$A = (\text{command input cycle} + \text{address input cycle} + \text{data input cycle time of the last page})$$

If "A" exceeds the  $t_{PROG}$  of previous page,  $t_{PROG}$  of the last page is  $t_{PROG} \text{ max}$ .


(Note) Make sure to terminate the operation with 80h-10h command sequence.


If the operation is terminated by 80h-15h command sequence, monitor I/O 6 (Ready / Busy) by issuing the Status Read command (70h) and make sure the previous page program operation is completed. If the page program operation is completed, issue FFh reset before the next operation.

## Multi-Page Program Operation with Data Cache Timing Diagram (1/4)



1

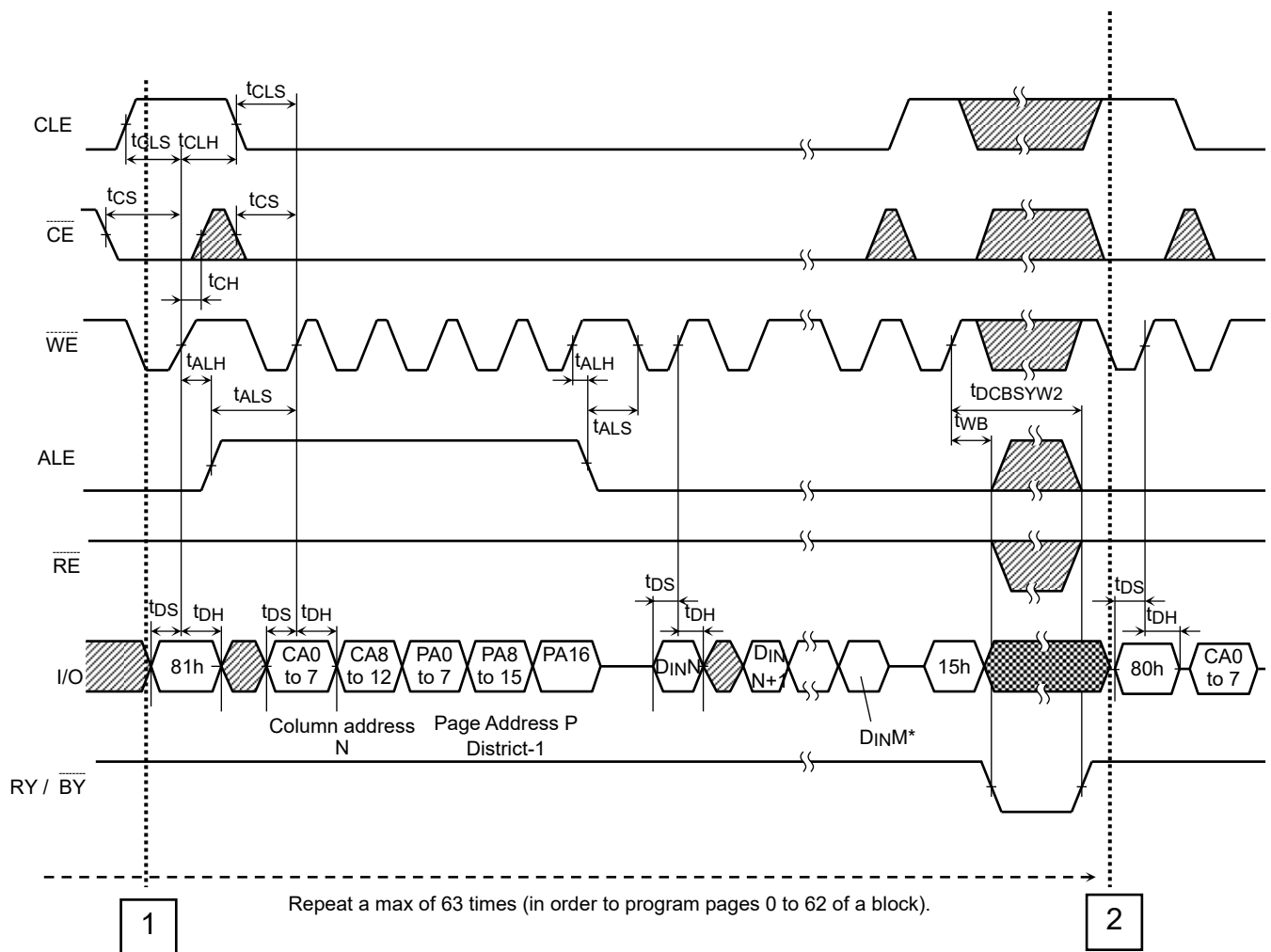
 : Do not input data while data is being output.

 :  $V_{IH}$  or  $V_{IL}$

\* M: up to 4351


Continues to 1 of next page


### Multi-Page Program Operation with Data Cache Timing Diagram (2/4)



Continues from 1 of previous page

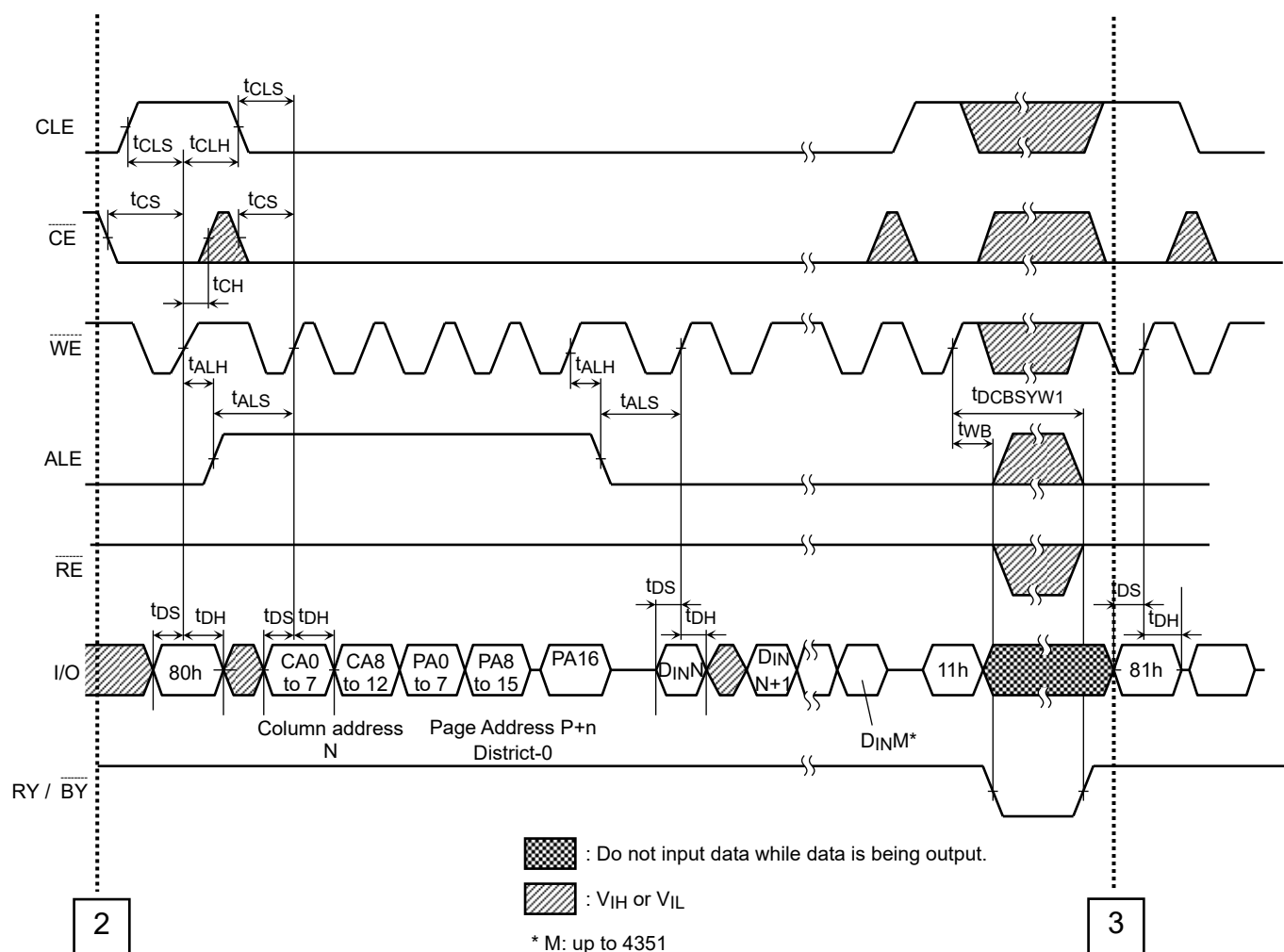
Continues to 2 of next page

 : Do not input data while data is being output.

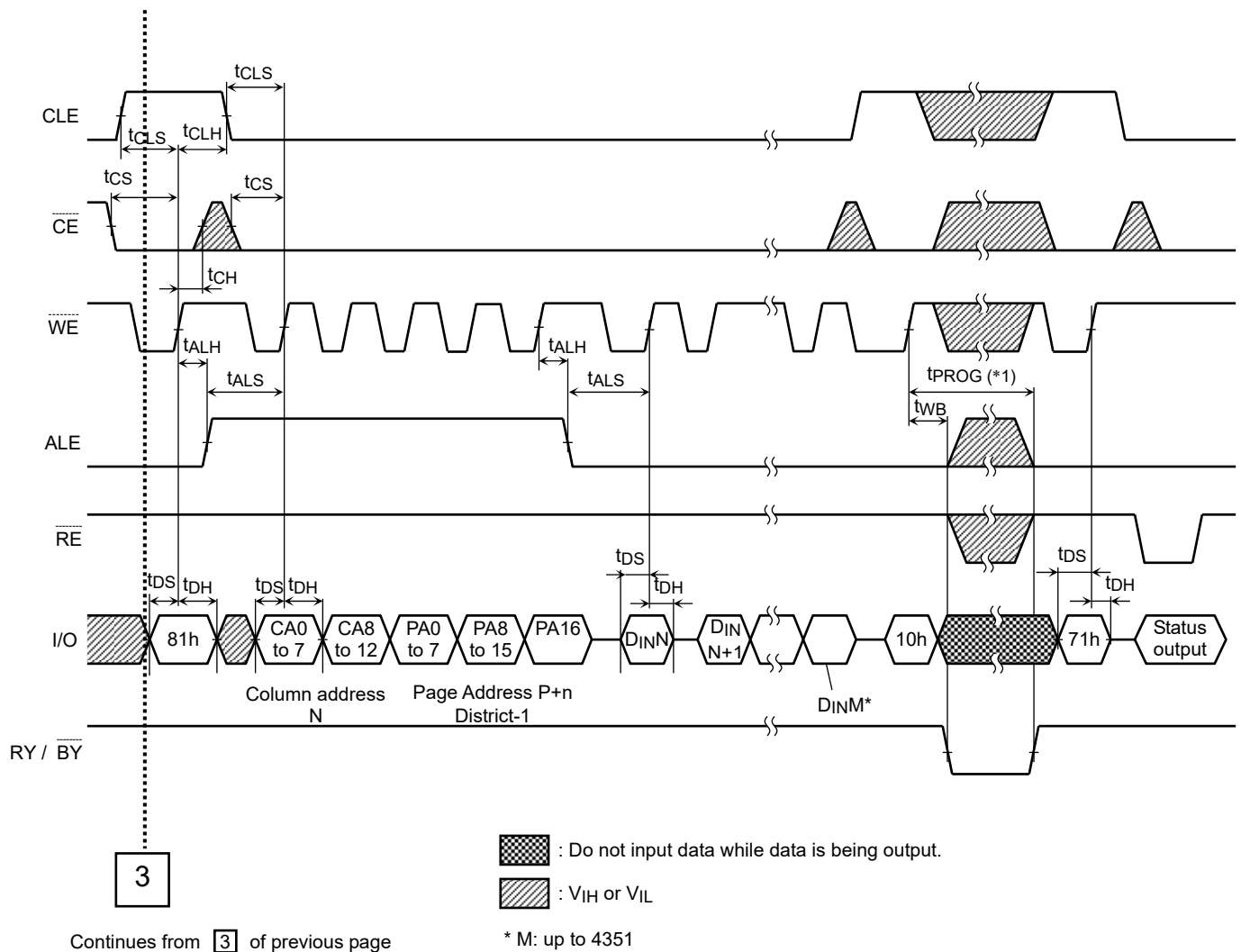
 :  $V_{IH}$  or  $V_{IL}$

\* M: up to 4351

## Multi-Page Program Operation with Data Cache Timing Diagram (3/4)



Multi-Page Program Operation with Data Cache Timing Diagram (4/4)



(\*1)  $t_{PROG}$ : Since the last page's programming by 10h command is initiated after the previous cache program, the  $t_{PROG}$  during cache programming is given by the following equation.

$$t_{PROG} = t_{PROG} \text{ of the last page} + t_{PROG} \text{ of the previous page} - A$$

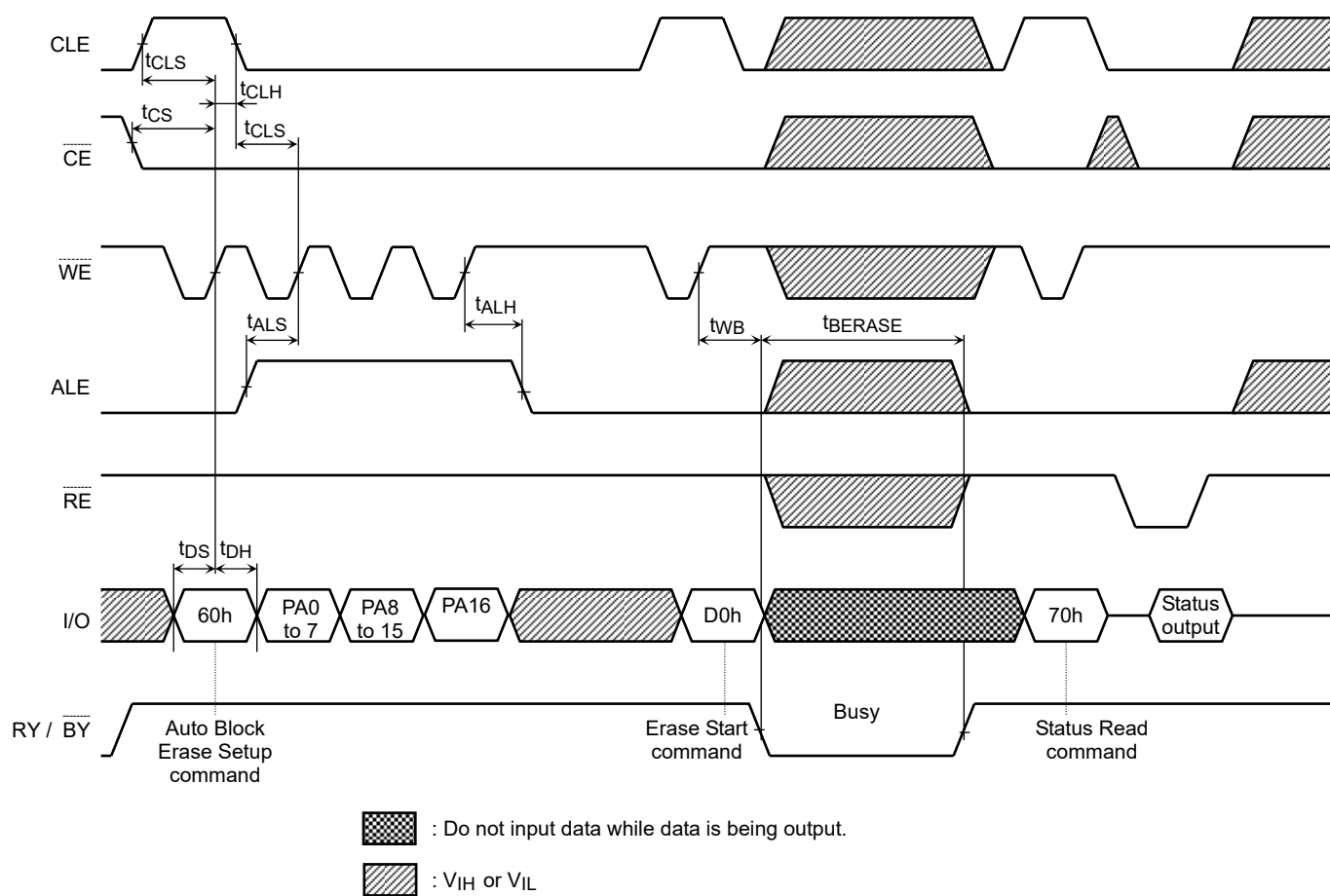
$$A = (\text{command input cycle} + \text{address input cycle} + \text{data input cycle time of the last page})$$

If "A" exceeds the  $t_{PROG}$  of previous page,  $t_{PROG}$  of the last page is  $t_{PROG} \text{ max}$ .

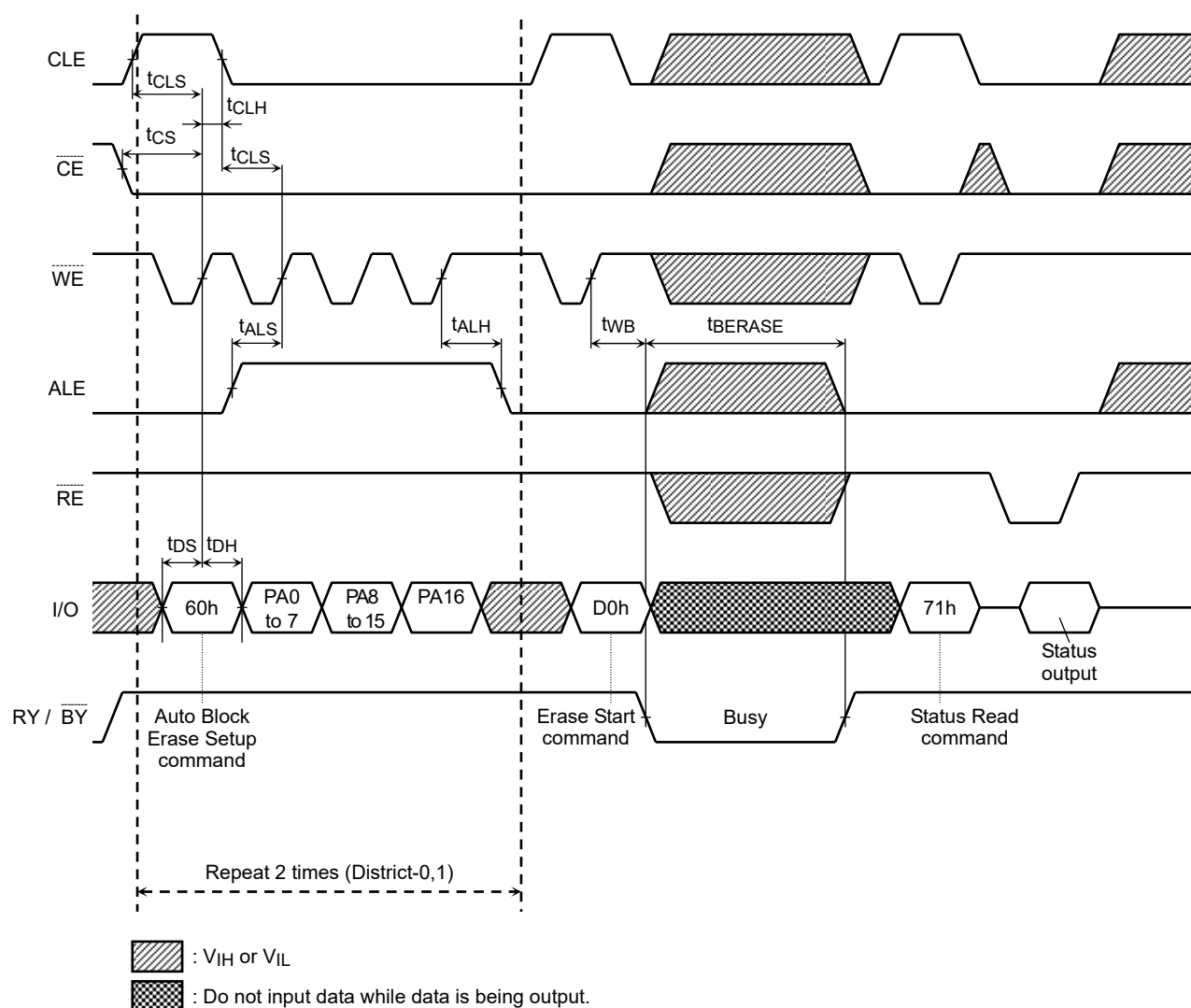
(Note) Make sure to terminate the operation with 81h-10h command sequence.

If the operation is terminated by 81h-15h command sequence, monitor I/O 6 (Ready / Busy) by issuing the Status Read command (70h) and make sure the previous page program operation is completed. If the page program operation is completed, issue FFh reset before the next operation.

## Auto Block Erase Timing Diagram

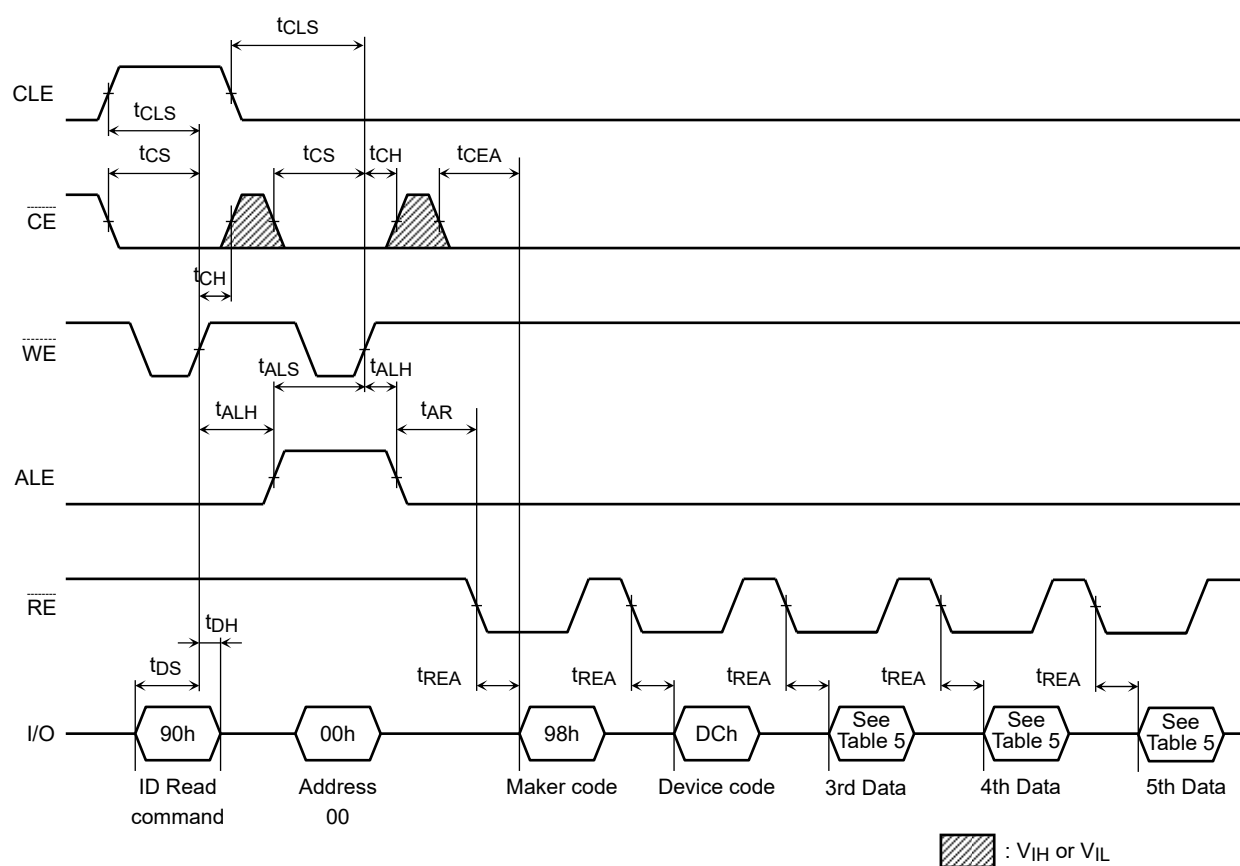


## Multi Block Erase Timing Diagram





## ID Read Operation Timing Diagram



## PIN FUNCTIONS

The device is a serial access memory which utilizes time-sharing input of address information.

### Command Latch Enable: CLE

The CLE input signal is used to control loading of the operation mode command into the internal command register. The command is latched into the command register from the I/O port on the rising edge of the  $\overline{WE}$  signal while CLE is High.

### Address Latch Enable: ALE

The ALE signal is used to control loading address information into the internal address register. Address information is latched into the address register from the I/O port on the rising edge of  $\overline{WE}$  while ALE is High.

### Chip Enable: $\overline{CE}$

The device goes into a low-power Standby mode when  $\overline{CE}$  goes High while the device is in Ready state. The  $\overline{CE}$  signal is ignored when the device is in Busy state ( $RY / \overline{BY} = L$ ), such as during a Program, Erase or Read operation, and will not enter Standby mode even if the  $\overline{CE}$  input goes High.

### Write Enable: $\overline{WE}$

The  $\overline{WE}$  signal is used to control the acquisition of data from the I/O port.

### Read Enable: $\overline{RE}$

The  $\overline{RE}$  signal controls serial data output. Data is available  $t_{REA}$  after the falling edge of  $\overline{RE}$ .

The internal column address counter is also incremented ( $Address = Address + 1$ ) on this falling edge.

### I/O Port: I/O1 to 8

The I/O1 to 8 pins are used as a port for transferring address, command and input/output data to and from the device.

### Write Protect: $\overline{WP}$

The  $\overline{WP}$  signal is used to protect the device from accidental programming or erasing. The internal voltage regulator is reset when  $\overline{WP}$  is Low. This signal is usually used to protect the data during the power-on/off sequence when input signals are invalid.

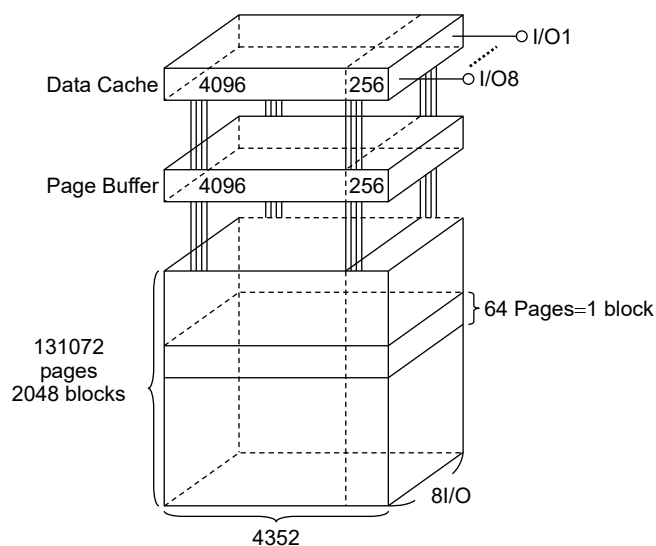
### Ready/Busy: $RY / \overline{BY}$

The  $RY / \overline{BY}$  output signal is used to indicate the operating condition of the device. The  $RY / \overline{BY}$  signal is in Busy state ( $RY / \overline{BY} = L$ ) during the Program, Erase and Read operations and will return to Ready state ( $RY / \overline{BY} = H$ ) after completion of the operation. The output buffer for this signal is an open drain and has to be pulled up to Vcc with an appropriate resistor.

If  $RY / \overline{BY}$  signal is not pulled up to Vcc ("Open" state), device operation cannot be guaranteed.

## Schematic Cell Layout and Address Assignment

The Program operation works on page units while the Erase operation works on block units.



A page consists of 4352 bytes in which 4096 bytes are used for main memory storage and 256 bytes are for redundancy or for other uses.

1 page = 4352 bytes

1 block = 4352 bytes × 64 pages = (256K + 16K) bytes

Capacity = 4352 bytes × 64 pages × 2048 blocks

An address is read in via the I/O port over five consecutive clock cycles, as shown in Table 1.

Table 1. Addressing





	I/O8	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1
First cycle	CA7	CA6	CA5	CA4	CA3	CA2	CA1	CA0
Second cycle	L	L	L	CA12	CA11	CA10	CA9	CA8
Third cycle	PA7	PA6	PA5	PA4	PA3	PA2	PA1	PA0
Fourth cycle	PA15	PA14	PA13	PA12	PA11	PA10	PA9	PA8
Fifth cycle	L	L	L	L	L	L	L	PA16

CA0 to CA12: Column address  
PA0 to PA5: Page address in block  
PA6 to PA16: Block address

Operation Mode: Logic and Command Tables

The operation modes such as Program, Erase, Read and Reset are controlled by command operations shown in Table 3. Address input, command input and data input/output are controlled by the CLE, ALE,  $\overline{\text{CE}}$ ,  $\overline{\text{WE}}$ ,  $\overline{\text{RE}}$  and  $\overline{\text{WP}}$  signals, as shown in Table 2.

Table 2. Logic Table

	CLE	ALE	$\overline{\text{CE}}$	$\overline{\text{WE}}$	$\overline{\text{RE}}$	$\overline{\text{WP}}^{*1}$
Command Input	H	L	L		H	*
Data Input	L	L	L		H	H
Address Input	L	H	L		H	*
Serial Data Output	L	L	L	H		*
During Program (Busy)	*	*	*	*	*	H
During Erase (Busy)	*	*	*	*	*	H
During Read (Busy)	*	*	H	*	*	*
	*	*	L	H (*2)	H (*2)	*
Program, Erase Inhibit	*	*	*	*	*	L
Standby	*	*	H	*	*	0 V/V <sub>CC</sub>

H: V<sub>IH</sub>, L: V<sub>IL</sub>, \*: V<sub>IH</sub> or V<sub>IL</sub>

\*1: When the  $\overline{\text{WP}}$  signal goes Low, Program or Erase operation is inhibited (Refer to Application Note (10) toward the end of this document).

\*2: If  $\overline{\text{CE}}$  is Low during Read Busy,  $\overline{\text{WE}}$  and  $\overline{\text{RE}}$  must be held High to avoid unintended command/address input to the device or read to the device. Reset or Status Read command can be input during Read Busy.

Table 3. Command table (HEX)

	First Cycle	Second Cycle	Acceptable while Busy
Serial Data Input	80	—	
Read	00	30	
Column Address Change in Serial Data Output	05	E0	
Read with Data Cache	31	—	
Read Start for Last Page in Read Cycle with Data Cache	3F	—	
Auto Page Program	80	10	
Column Address Change in Serial Data Input	85	—	
Auto Page Program with Data Cache	80	15	
Multi Page Program	80	11	
	81	15	
	81	10	
Read for Page Copy (2) with Data Out	00	3A	
Auto Program with Data Cache during Page Copy (2)	8C	15	
Auto Program for last page during Page Copy (2)	8C	10	
Auto Block Erase	60	D0	
ID Read	90	—	
Status Read	70	—	○
Status Read for Multi-Page Program or Multi Block Erase	71	—	○
Reset	FF	—	○

HEX data bit assignment  
(Example) Serial Data Input: 80h

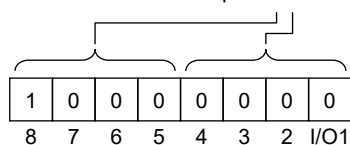


Table 4. Read mode operation states

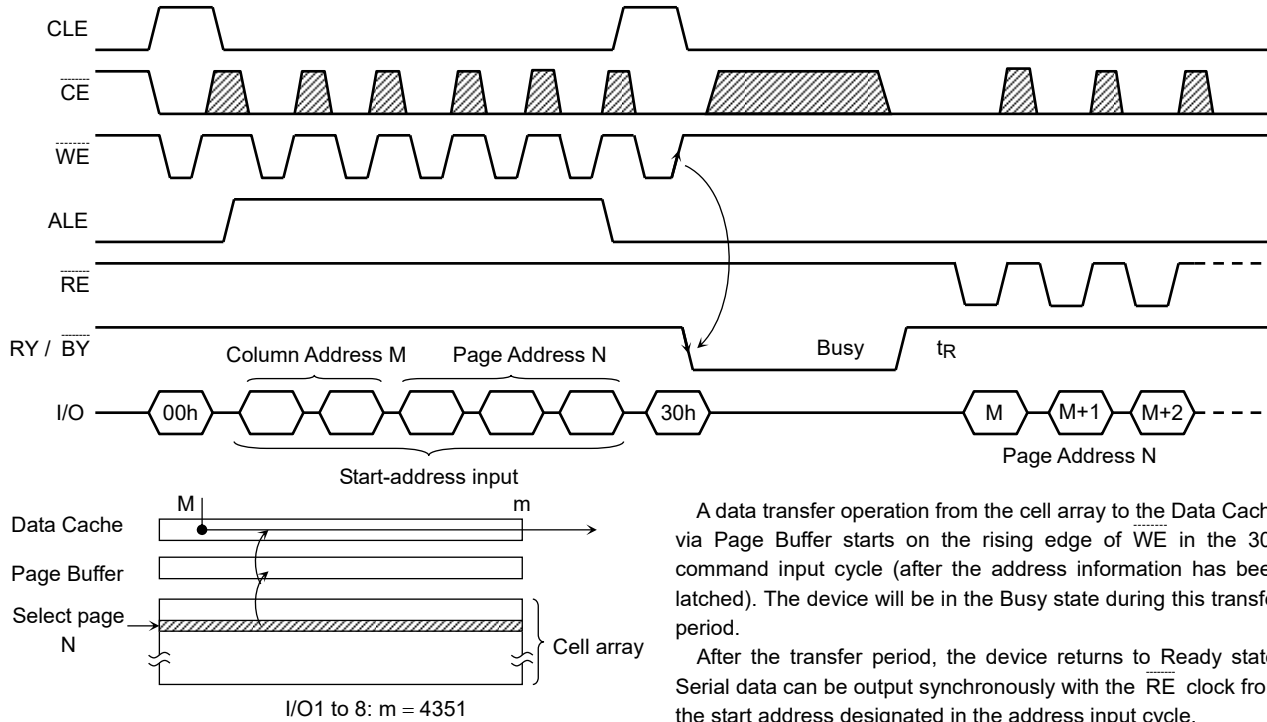
	CLE	ALE	$\overline{\text{CE}}$	$\overline{\text{WE}}$	$\overline{\text{RE}}$	I/O1 to I/O8	Power
Output select	L	L	L	H	L	Data output	Active
Output Deselect	L	L	L	H	H	High impedance	Active

H:  $V_{IH}$ , L:  $V_{IL}$

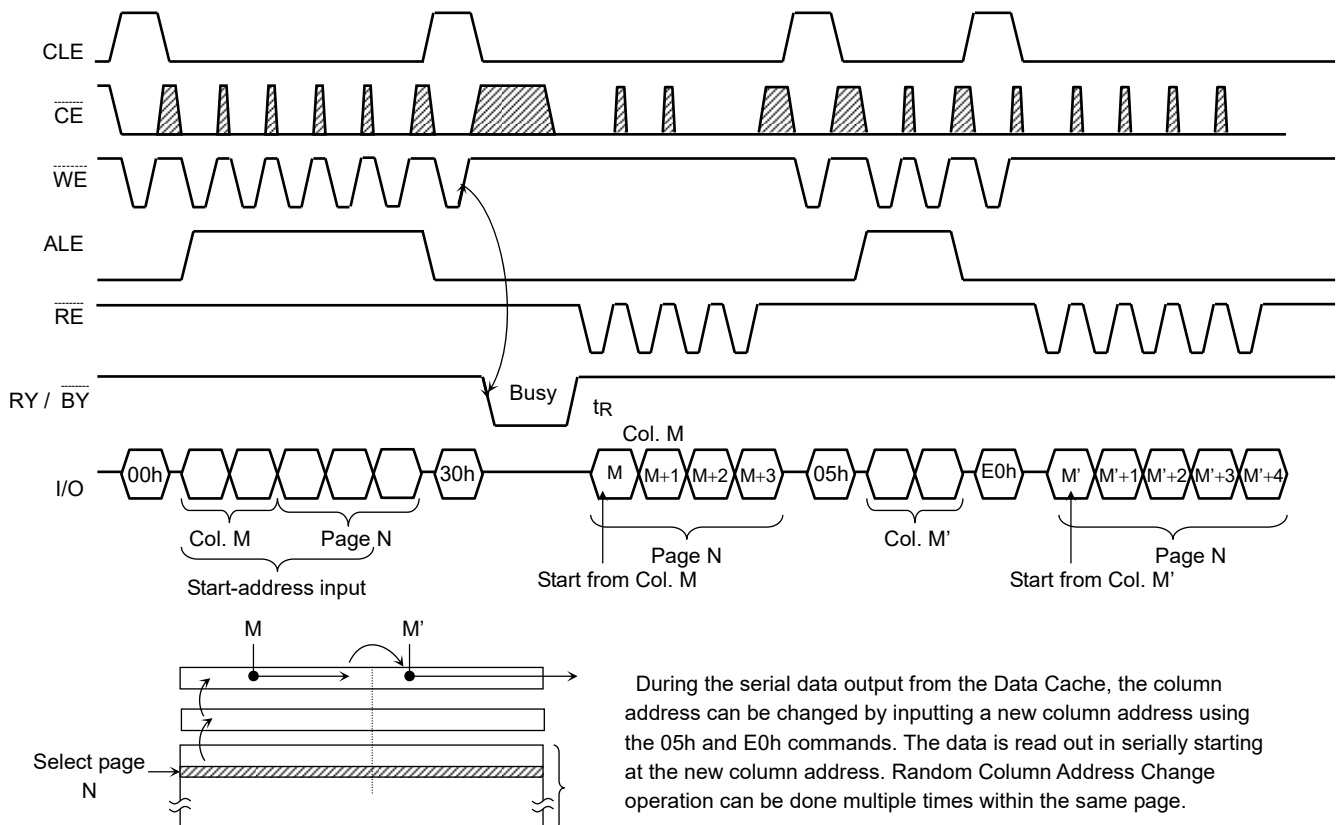
## DEVICE OPERATION

### Read Mode

Read mode is set when the "00h" and "30h" commands are issued to the Command register. Between the two commands, a start address for the Read mode needs to be issued. After the initial power on sequence, "00h" command is latched into the internal command register. Then the Read operation after the power on sequence is executed by the setting of only five address cycles and "30h" command. The sequence and the block diagram are shown below (Refer to the detailed timing chart).

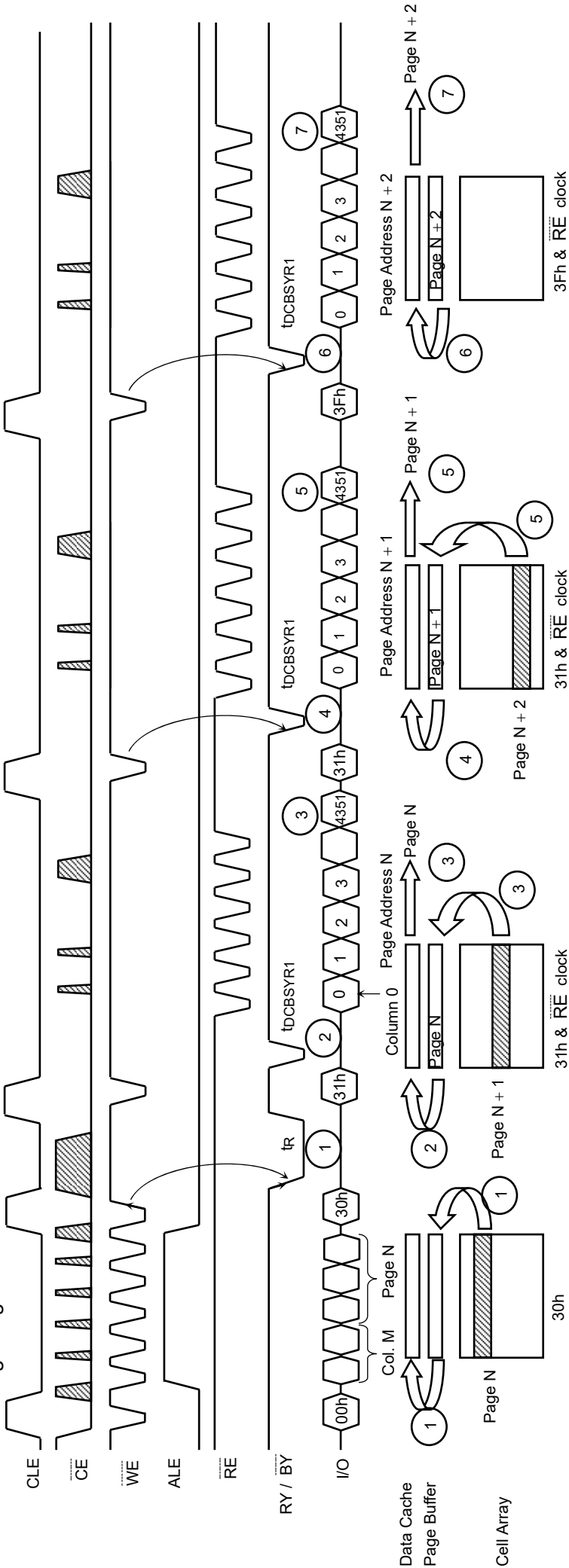


### Random Column Address Change in Read Cycle



### Read with Data Cache

The device has a Read with Data Cache that enables the high speed read operation shown below. When the block address changes, this sequence has to be started from the beginning.



If the 31h command is issued to the device, the data content of the next page is transferred to the Page Buffer during serial data out from the Data Cache, reducing the  $t_R$  (Data transfer from memory cell to data register).

1. Normal read. Data is transferred from Page N to Data Cache through Page Buffer. During this time period, the device outputs Busy state for  $t_R$  max.
2. After the Ready/Busy signal returns to Ready, 31h command is issued and data is transferred to Data Cache from Page Buffer again. This data transfer takes  $t_{DCBSYR1}$  max and the completion of this time period can be detected by Ready/Busy signal.
3. Data of Page N + 1 is transferred to Page Buffer from cell while the data of Page N in Data Cache can be read out by /RE clock simultaneously.
4. The 31h command makes data of Page N + 1 transfer to Data Cache from Page Buffer after the completion of the transfer from cell to Page Buffer. The device outputs Busy state for  $t_{DCBSYR1}$  max.. This Busy period depends on the combination of the internal data transfer time from cell to Page Buffer and the serial data out time.
5. Data of Page N + 2 is transferred to Page Buffer from cell while the data of Page N + 1 in Data Cache can be read out by /RE clock simultaneously.
6. The 3Fh command makes the data of Page N + 2 transfer to the Data Cache from the Page Buffer after the completion of the transfer from cell to Page Buffer. The device outputs Busy state for  $t_{DCBSYR1}$  max.. This Busy period depends on the combination of the internal data transfer time from cell to Page Buffer and the serial data out time.
7. Data of Page N + 2 in Data Cache can be read out, but since the 3Fh command does not transfer the data from the memory cell to Page Buffer, the device can accept new command input immediately after the completion of serial data out.

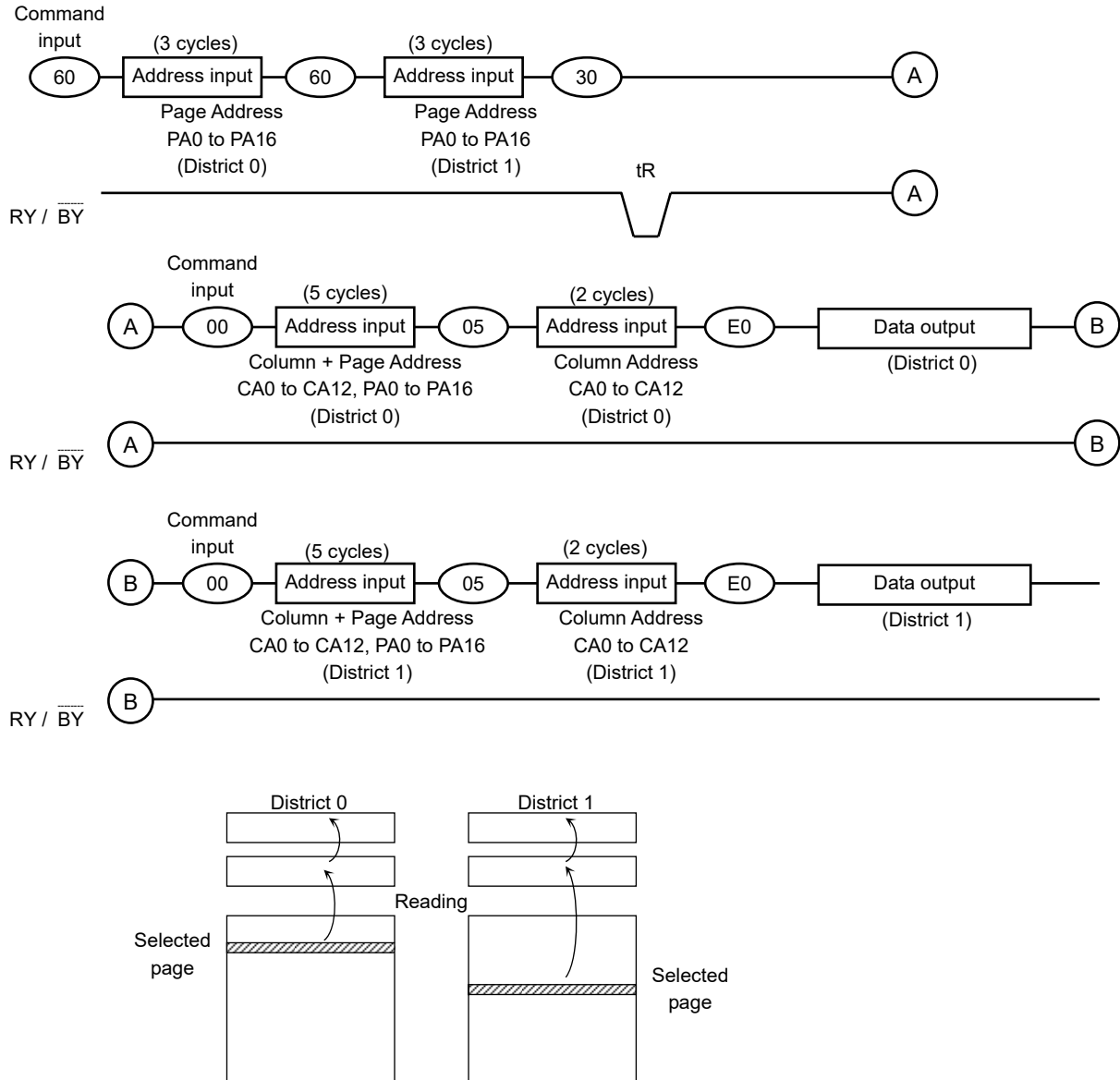
## Multi Page Read Operation

The device has a Multi Page Read operation and Multi Page Read with Data Cache operation.

### (1) Multi Page Read without Data Cache

The sequence of command and address input is shown below.

Same page address (PA0 to PA5) within each District has to be selected.



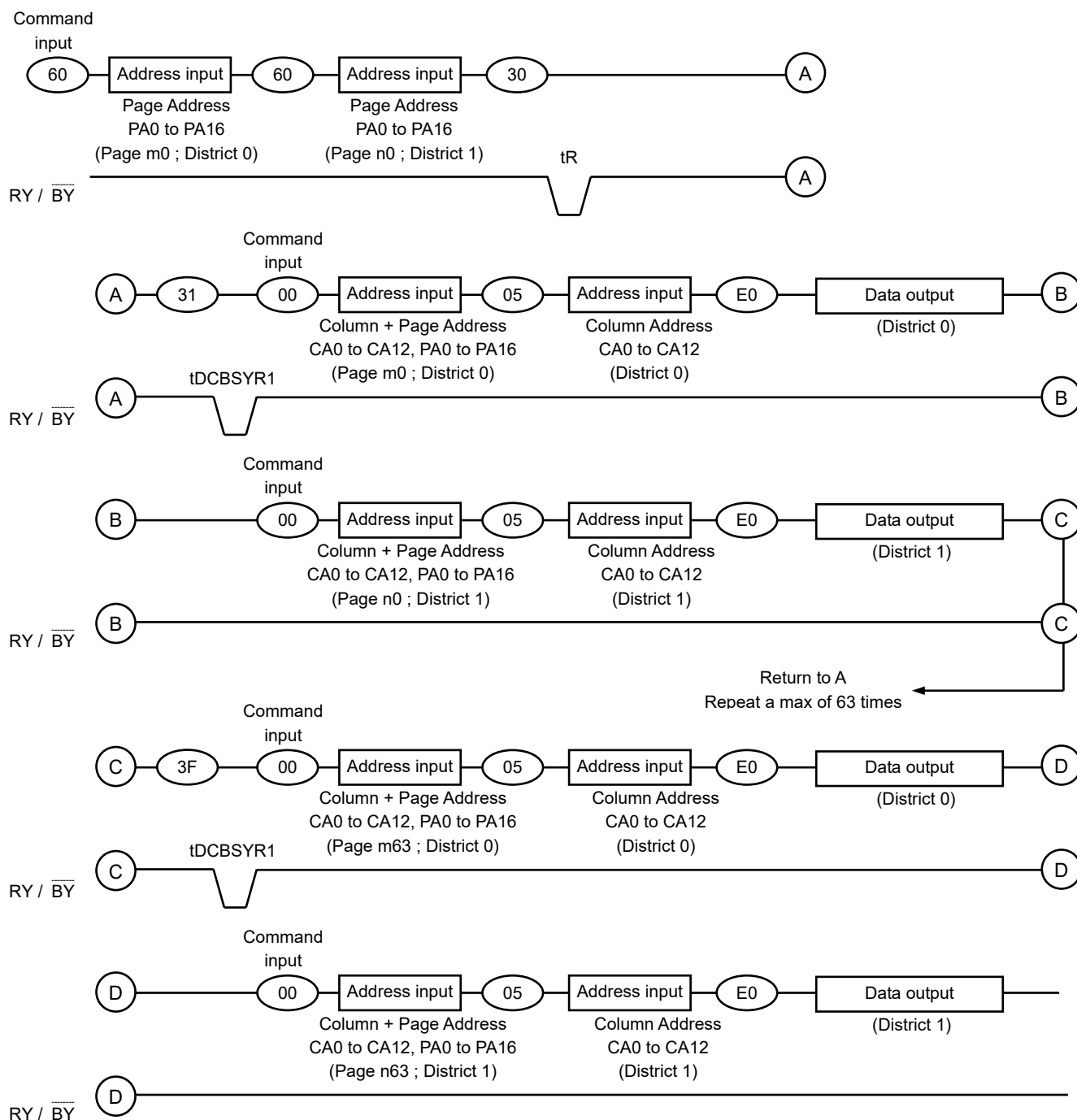
The data transfer operation from the cell array to the Data Cache via Page Buffer starts on the rising edge of WE in the 30h command input cycle (after the 2 Districts' address information has been latched). The device will be in the Busy state during this transfer period.

After the transfer period, the device returns to Ready state. Serial data can be output synchronously with the RE clock from the start address designated in the address input cycle.



## (2) Multi Page Read with Data Cache

When the block address changes (increments) this sequence has to be started from the beginning.  
The sequence of command and address input is shown below.  
Same page address (PA0 to PA5) within each District has to be selected.



## (3) Notes

## (a) Internal addressing in relation to the Districts

To use the Multi Page Read operation, the internal addressing should be considered in relation to the District.

- The device consists of 2 Districts.
- Each District consists of 1024 erase blocks.
- The allocation rule is as follows:  
 District 0: Block 0, Block 2, Block 4, Block 6, ..., Block 2046  
 District 1: Block 1, Block 3, Block 5, Block 7, ..., Block 2047

## (b) Address input restriction for the Multi Page Read operation

There are the following restrictions in using Multi Page Read:

## (Restriction)

Maximum one block should be selected from each District.

Same page address (PA0 to PA5) within two Districts has to be selected.

For example:

(60) [District 0, Page Address 0x00000] (60) [District 1, Page Address 0x00040] (30)  
 (60) [District 0, Page Address 0x00001] (60) [District 1, Page Address 0x00041] (30)

## (Acceptance)

There is no order limitation of the District for the address input.

For example, the following operation is accepted:

(60) [District 0] (60) [District 1] (30)  
 (60) [District 1] (60) [District 0] (30)

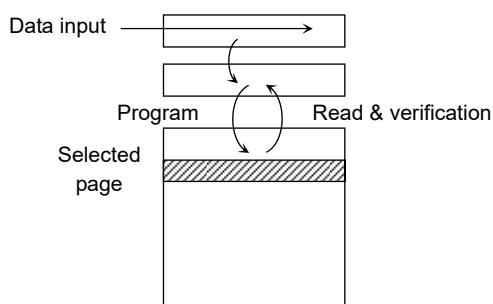
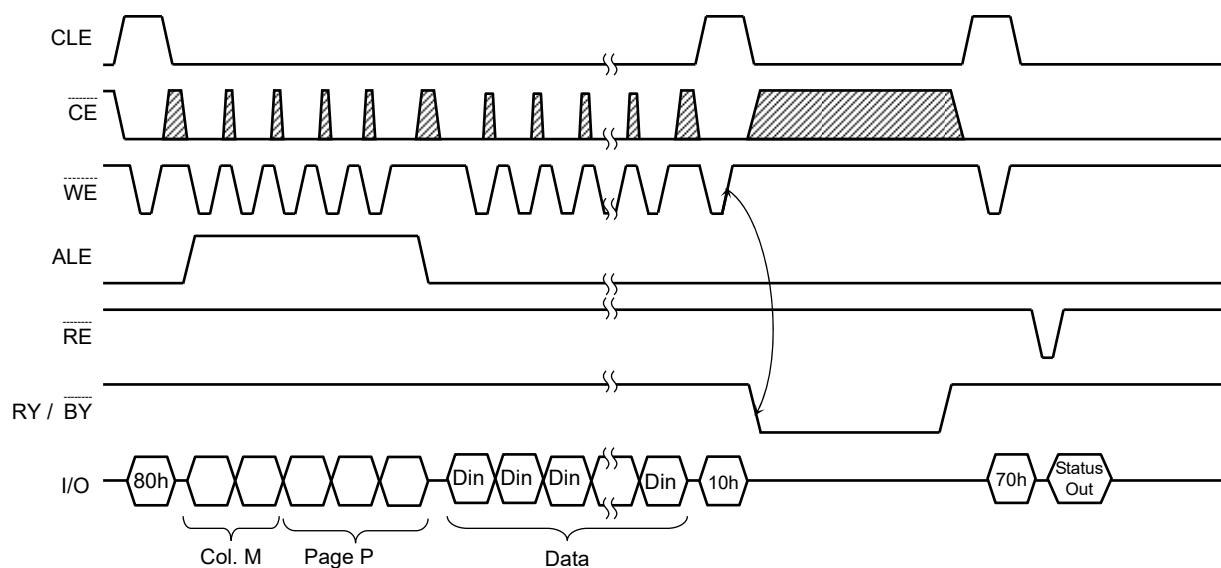
It requires no mutual address relation between the selected blocks from each District.

(c)  $\overline{WP}$  signal

Make sure  $\overline{WP}$  is held to High when the Multi Page Read operation is performed.

## Auto Page Program Operation

The device carries out an Auto Page Program operation when it receives a "10h" Program command after the address and data have been input. The sequence of command, address and data input is shown below (Refer to the detailed timing chart).

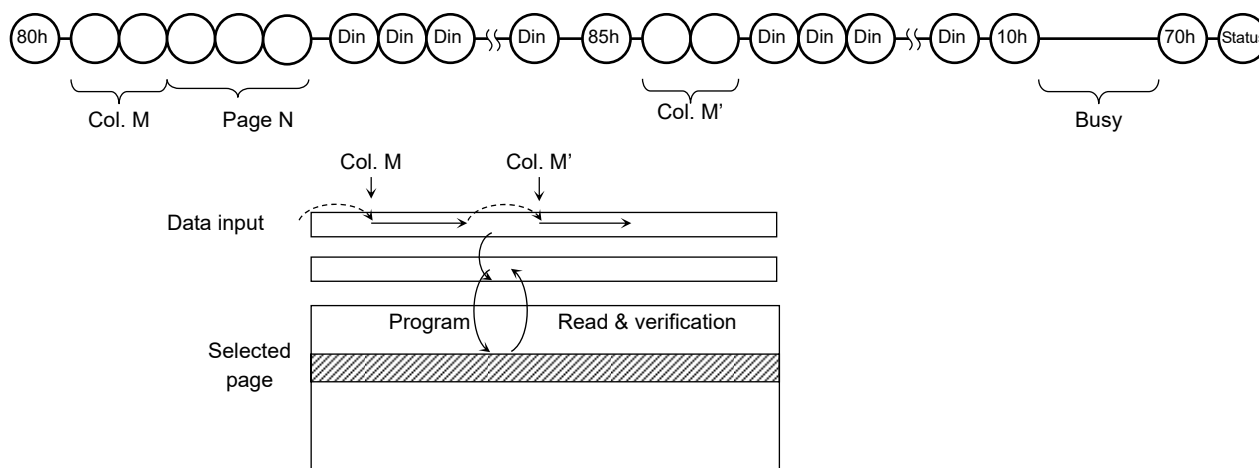


The data is transferred (programmed) from the Data Cache via the Page Buffer to the selected page on the rising edge of WE following input of the "10h" command. After programming, the programmed data is transferred back to the Page Buffer to be automatically verified by the device. If the programming does not succeed, the Program/Verify operation is repeated by the device until success is achieved or until the maximum loop number set in the device is reached.

## Random Column Address Change in Auto Page Program Operation

The column address can be changed by the 85h command during the data input sequence of the Auto Page Program operation.

Two address input cycles after the 85h command are recognized as a new column address for the data input. After the new data is input to the new column address, the 10h command initiates the actual data program into the selected page automatically. The Random Column Address Change operation can be repeated multiple times within the same page.

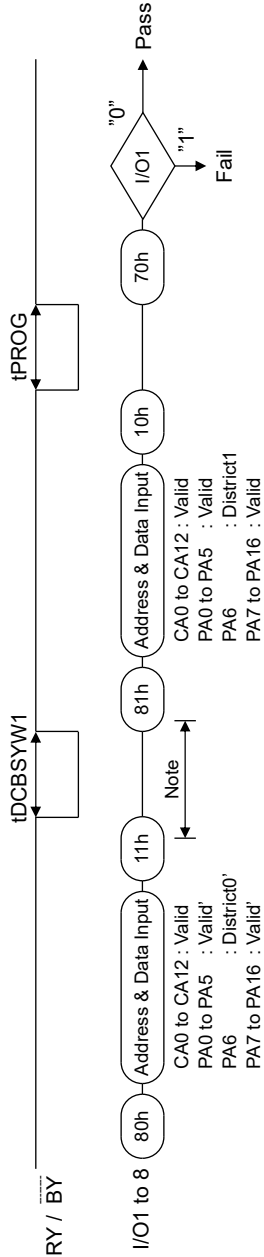


Multi Page Program

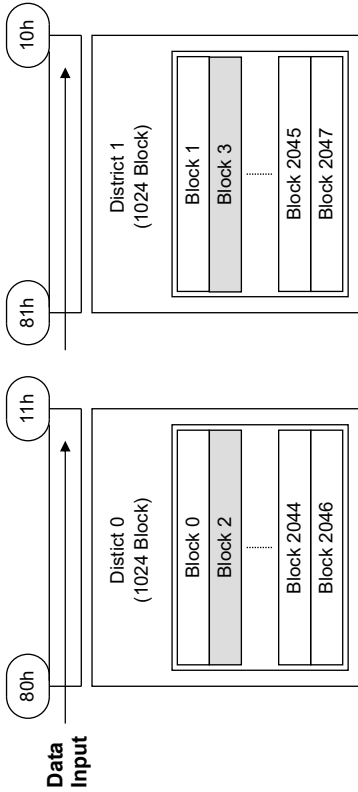
The device has a Multi Page Program, which enables even higher speed program operation compared to Auto Page Program. The sequence of command, address and data input is shown below. (Refer to the detailed timing chart.)

Although two Districts are programmed simultaneously, Pass/Fail is not available for each page by "70h" command when the program operation completes. The status bit of I/O 1 is set to "1" when any of the pages fail. Limitation in addressing with Multi Page Program is shown below.

Multi Page Program

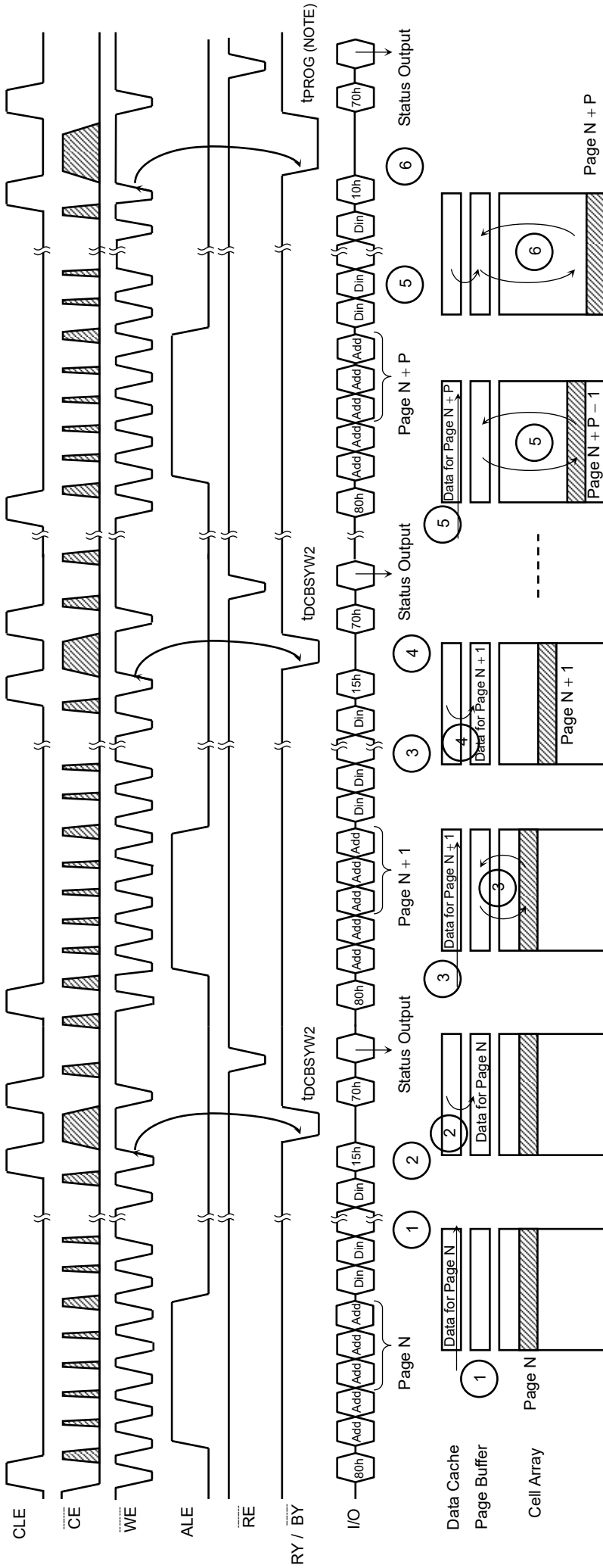


NOTE: Any command between 11h and 81h is prohibited except 70h and FFh.



### Auto Page Program Operation with Data Cache

The device has an Auto Page Program with Data Cache operation enabling the high speed program operation shown below. When the block address changes, this sequence has to be started from the beginning.



Issuing the 15h command to the device after serial data input initiates the program operation with Data Cache.

1. Data for Page N is input to Data Cache.
2. Data is transferred to the Page Buffer by the 15h command. During the transfer the Ready/Busy signal outputs Busy state (tDCBSYW2).
3. Data is programmed to the selected page while the data for Page N + 1 is input to the Data Cache.
4. By the 15h command, the data in the Data Cache is transferred to the Page Buffer after the programming of Page N and serial data input for Page N + 1 (tDCBSYW2) becomes empty. The duration of this period depends on timing between the internal programming of Page N + P - 1 is being programmed.
5. Data for Page N + P is input to the Data Cache while the data of the Page N + P - 1 is being programmed.
6. The programming with Data Cache is terminated by the 10h command. When the device becomes Ready state, it shows that the internal programming of the Page N + P is completed.

NOTE: Since the last page's programming by the 10h command is initiated after the previous cache program, the tPROG during cache programming is given by the following:

$$tPROG = tPROG \text{ for the last page} + tPROG \text{ of the previous page} - (\text{command input cycle} + \text{data input cycle time of the last page})$$

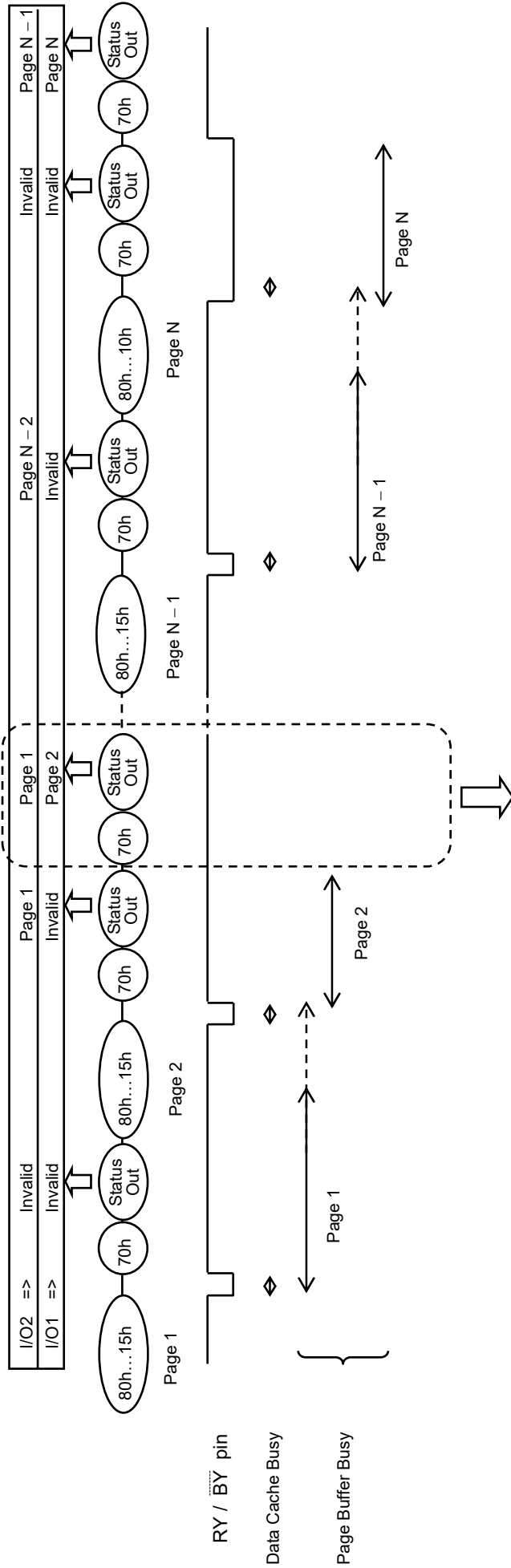
Pass/Fail status for each page programmed by the Auto Page Program with Data Cache operation can be detected by the Status Read operation.

- I/O1: Pass/Fail of the current page program operation.
- I/O2: Pass/Fail of the previous page program operation.

The Pass/Fail status on I/O1 and I/O2 are valid under the following conditions.

- Status on I/O1: Page Buffer Ready/Busy is Ready.  
The Page Buffer Ready/Busy is output on I/O6 by Status Read operation or RY /  $\overline{\text{BY}}$  pin after the 10h command.
- Status on I/O2: Data Cache Read/Busy is Ready.  
The Data Cache Ready/Busy is output on I/O7 by Status Read operation or RY /  $\overline{\text{BY}}$  pin after the 15h command.

Example)

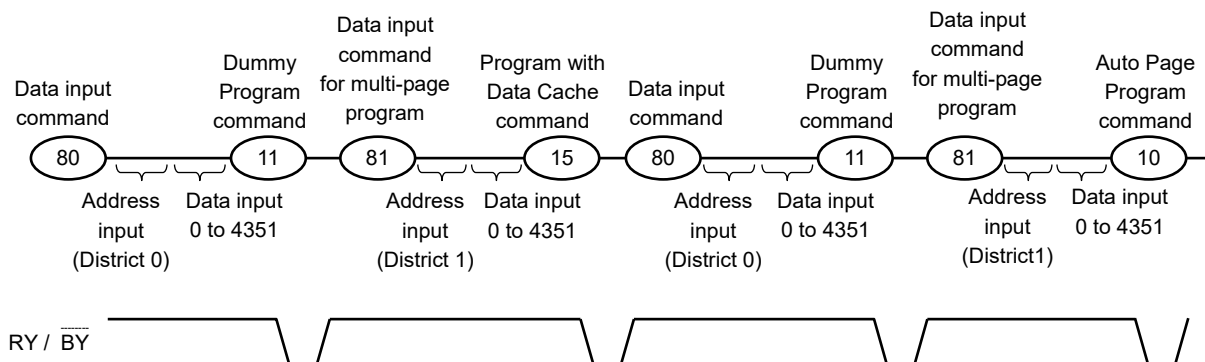


If the Page Buffer Busy returns to Ready before the next 80h command input and Status Read is done during this Ready period, the Status Read provides the Pass/Fail result for Page 2 on I/O1 and the Pass/Fail result for Page 1 on I/O2.

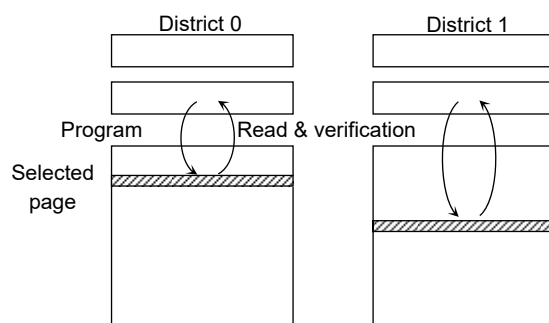
### Multi Page Program with Data Cache

The device has a Multi Page Program with Data Cache operation, which enables an even higher speed program operation compared to Auto Page Program with Data Cache as shown below. When the block address changes (increments) this sequence has to be started from the beginning.

The sequence of command, address and data input is shown below (Refer to the detailed timing chart).



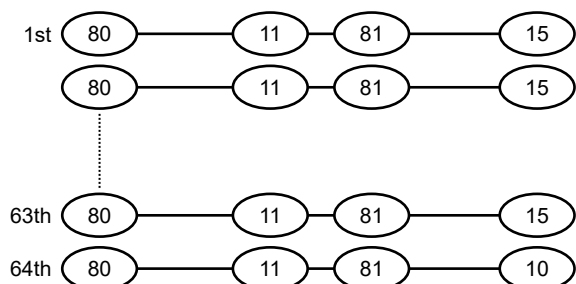
After either “15h” or “10h” Program command is input to the device, physical programming starts as follows. For details about Auto Page Program with Data Cache, refer to “Auto Page Program Operation with Data Cache”.



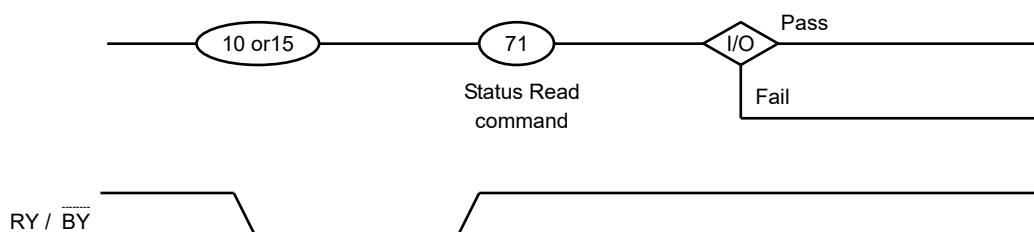
The data is transferred (programmed) from the page buffer to the selected page on the rising edge of /WE following input of the “15h” or “10h” command. After programming, the programmed data is transferred back to the register to be automatically verified by the device. If the programming does not succeed, the Program/Verify operation is repeated by the device until success is achieved or until the maximum loop number set in the device is reached.

By starting the above operation from the 1st page of the selected erase blocks, repeating total of 64 times while incrementing the page address in the blocks, and then inputting the last page data of the blocks, "10h" command executes the final programming. Make sure to terminate with 81h-10h command sequence.

In this full sequence, the command sequence is following.



After the "15h" or "10h" command, the results of the above operation is shown through the "71h" Status Read command.



The 71h command Status description is as below.

	STATUS	OUTPUT	
I/O1	Chip Status1 : Pass/Fail	Pass: 0	Fail: 1
I/O2	District 0 Chip Status1 : Pass/Fail	Pass: 0	Fail: 1
I/O3	District 1 Chip Status1 : Pass/Fail	Pass: 0	Fail: 1
I/O4	District 0 Chip Status2 : Pass/Fail	Pass: 0	Fail: 1
I/O5	District 1 Chip Status2 : Pass/Fail	Pass: 0	Fail: 1
I/O6	Ready/Busy	Ready: 1	Busy: 0
I/O7	Data Cache Ready/Busy	Ready: 1	Busy: 0
I/O8	Write Protect	Protect: 0	Not Protect: 1

I/O1 describes the Pass/Fail condition of District 0 and 1(OR data of I/O2 and I/O3). If one of the Districts fails during Multi Page Program operation, it shows "Fail".

I/O2 to 5 show the Pass/Fail condition of each District. For details on "Chip Status1" and "Chip Status2", refer to section "Status Read".



Internal addressing in relation to the Districts

To use the Multi Page Program operation, the internal addressing should be considered in relation to the District.

- The device consists of 2 Districts.
- Each District consists of 1024 erase blocks.
- The allocation rule is as follows:  
 District 0: Block 0, Block 2, Block 4, Block 6, ..., Block 2046  
 District 1: Block 1, Block 3, Block 5, Block 7, ..., Block 2047

Address input restriction for the Multi Page Program with Data Cache operation

There are the following restrictions in using Multi Page Program with Data Cache:

(Restriction)

Maximum one block should be selected from each District.

Same page address (PA0 to PA5) within two Districts has to be selected.

For example:

(80) [District 0, Page Address 0x00000] (11)    (81) [District 1, Page Address 0x00040] (15 or 10)  
 (80) [District 0, Page Address 0x00001] (11)    (81) [District 1, Page Address 0x00041] (15 or 10)

(Acceptance)

There is no order limitation of the District for the address input.

For example, the following operation is accepted:

(80) [District 0] (11)    (81) [District 1] (15 or 10)  
 (80) [District 1] (11)    (81) [District 0] (15 or 10)

It requires no mutual address relation between the selected blocks from each District.

Operating restriction during the Multi Page Program with Data Cache operation

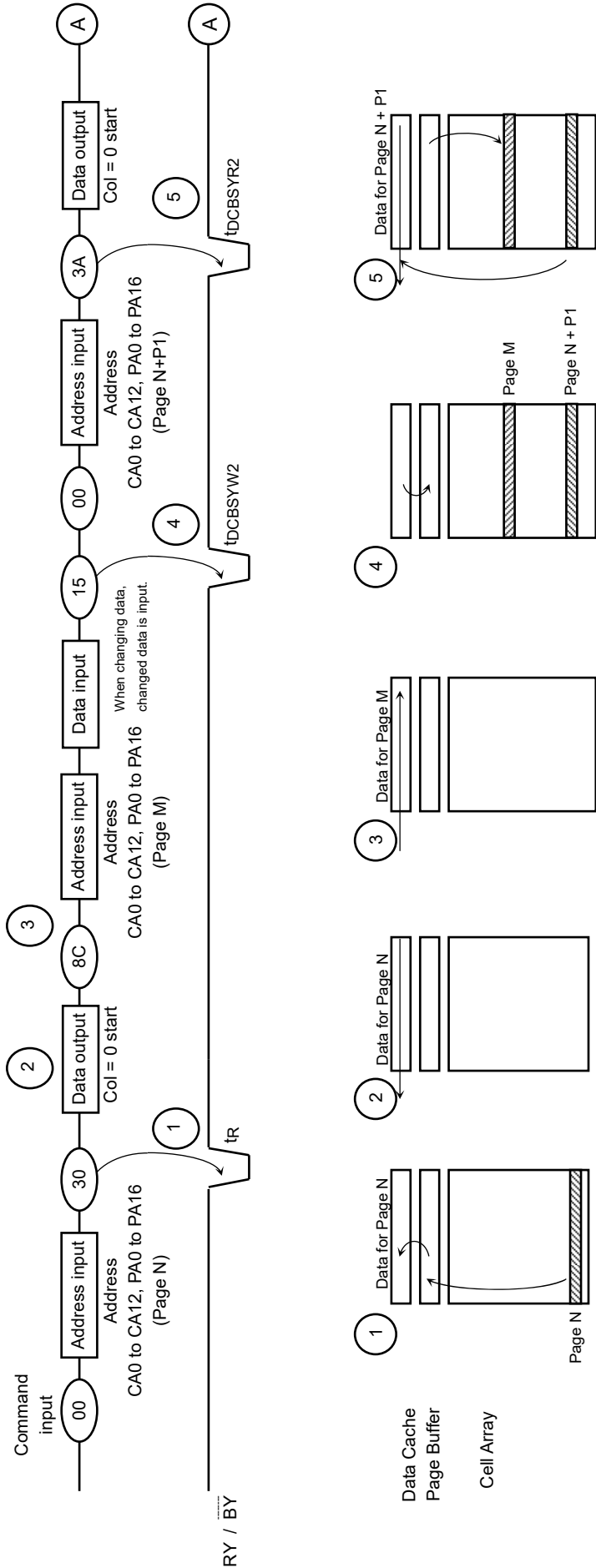
(Restriction)

The operation must be terminated with "10h" command.

Once the operation has started, no commands other than the commands shown in the timing diagram are allowed to be input except for Status Read command and Reset command.

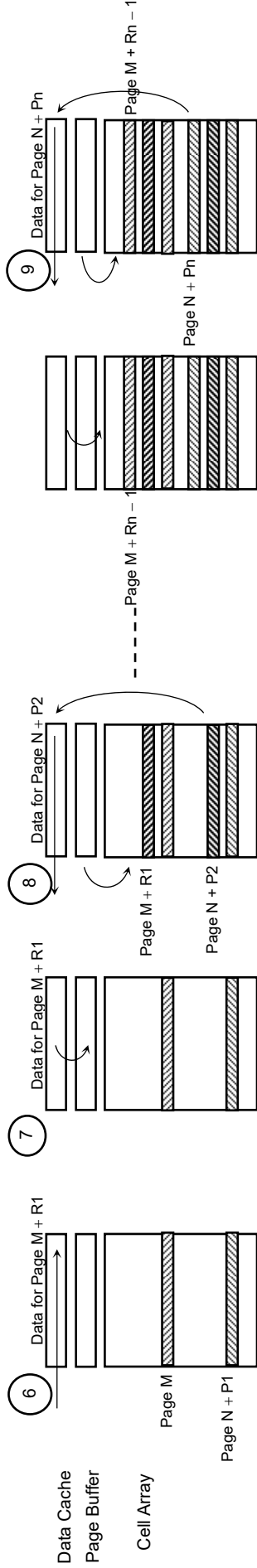
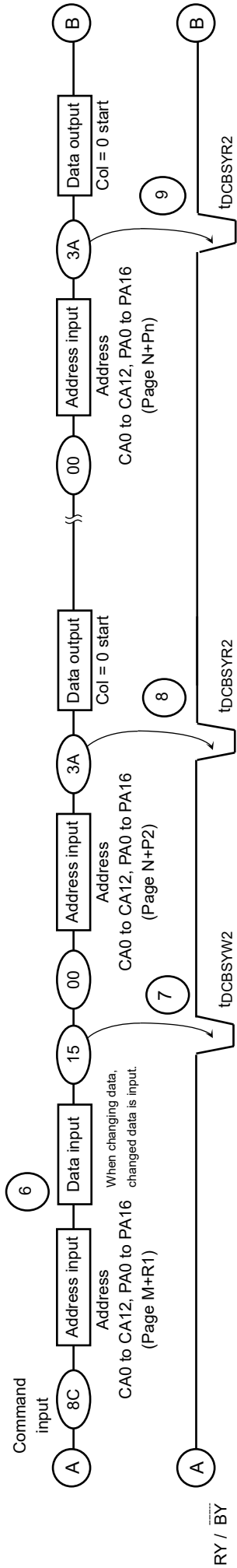
Page Copy (2)

By using Page Copy (2), data in a page can be copied to another page after the data has been read out. When the block address changes (increments) this sequence has to be started from the beginning.

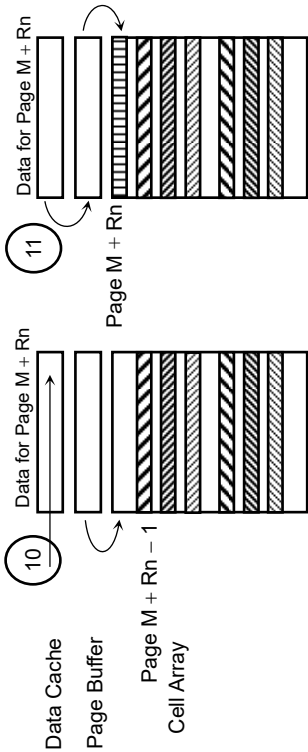
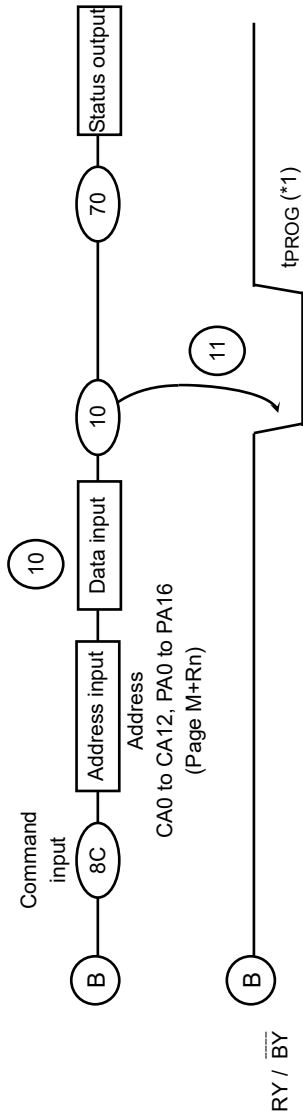


Page Copy (2) operation is as follows.

1. Data for Page N is transferred to the Data Cache.
2. Data for Page N is read out.
3. Address for Page M is input. If the data needs to be changed, changed data is input.
4. Data Cache for Page M is transferred to the Page Buffer.
5. After the Ready state, Data for Page N + P1 is output from the Data Cache while the data of Page M is being programmed.



6. Address for Page (M + R1) is input. If the data needs to be changed, changed data is input.
7. After programming of page M is completed, Data Cache for Page M + R1 is transferred to the Page Buffer.
8. By the 15h command, the data in the Page Buffer is programmed to Page M + R1. Data for Page N + P2 is transferred to the Data cache.
9. The data in the Page Buffer is programmed to Page M + Rn - 1. Data for Page N + Pn is transferred to the Data Cache.



- 10. Address for Page (M + Rn) is input. If the data needs to be changed, changed data is input.
- 11. By issuing the 10h command, the data in the Page Buffer is programmed to Page M + Rn.

(\*1) Since the last page's programming by the 10h command is initiated after the previous cache program, the tPROG here will be expected as the following:  
tPROG = tPROG of the last page + tPROG of the previous page - (command input cycle + data output/input cycle time of the last page)

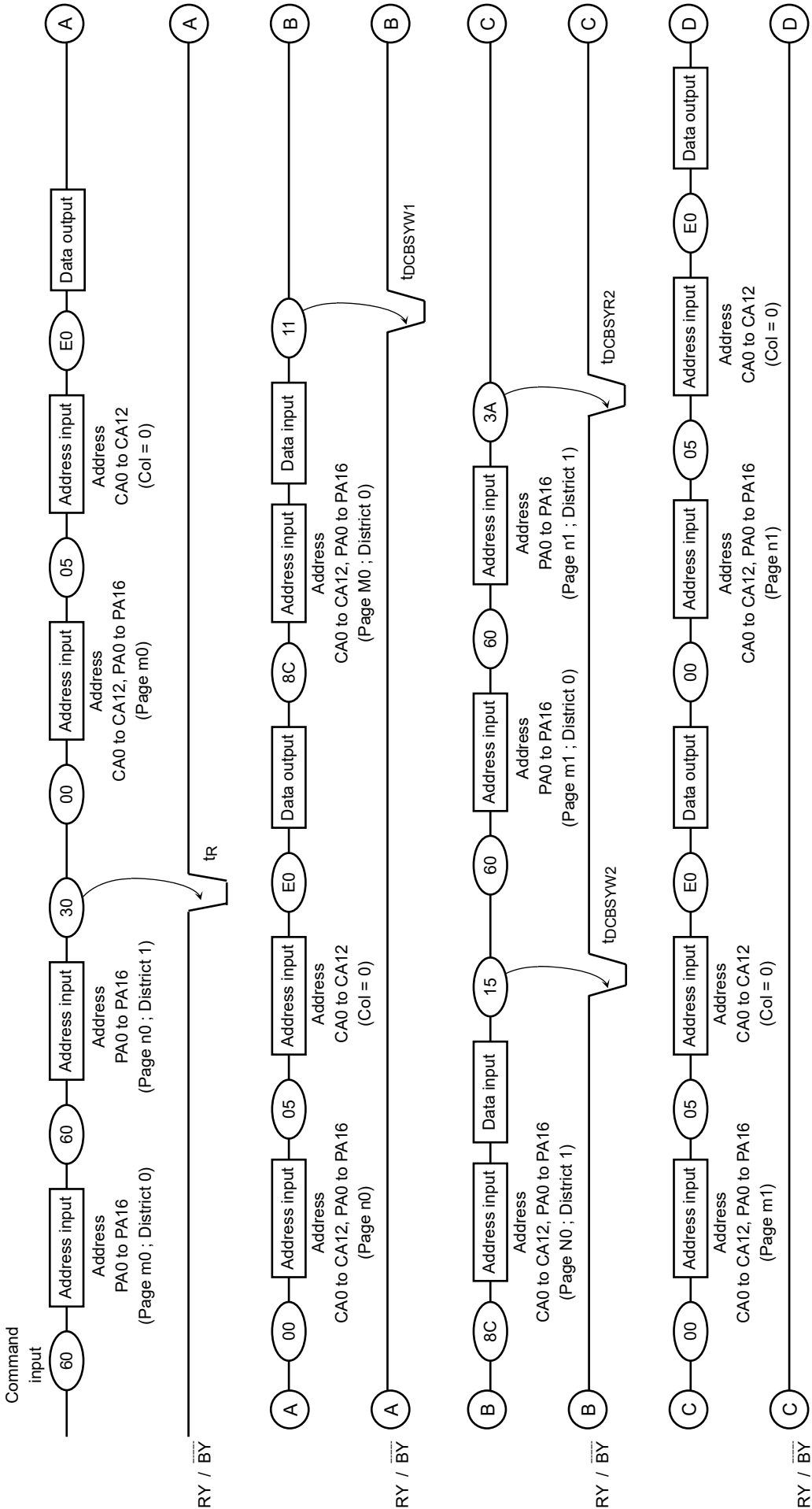
NOTE) This operation needs to be executed within District-0 or District-1.

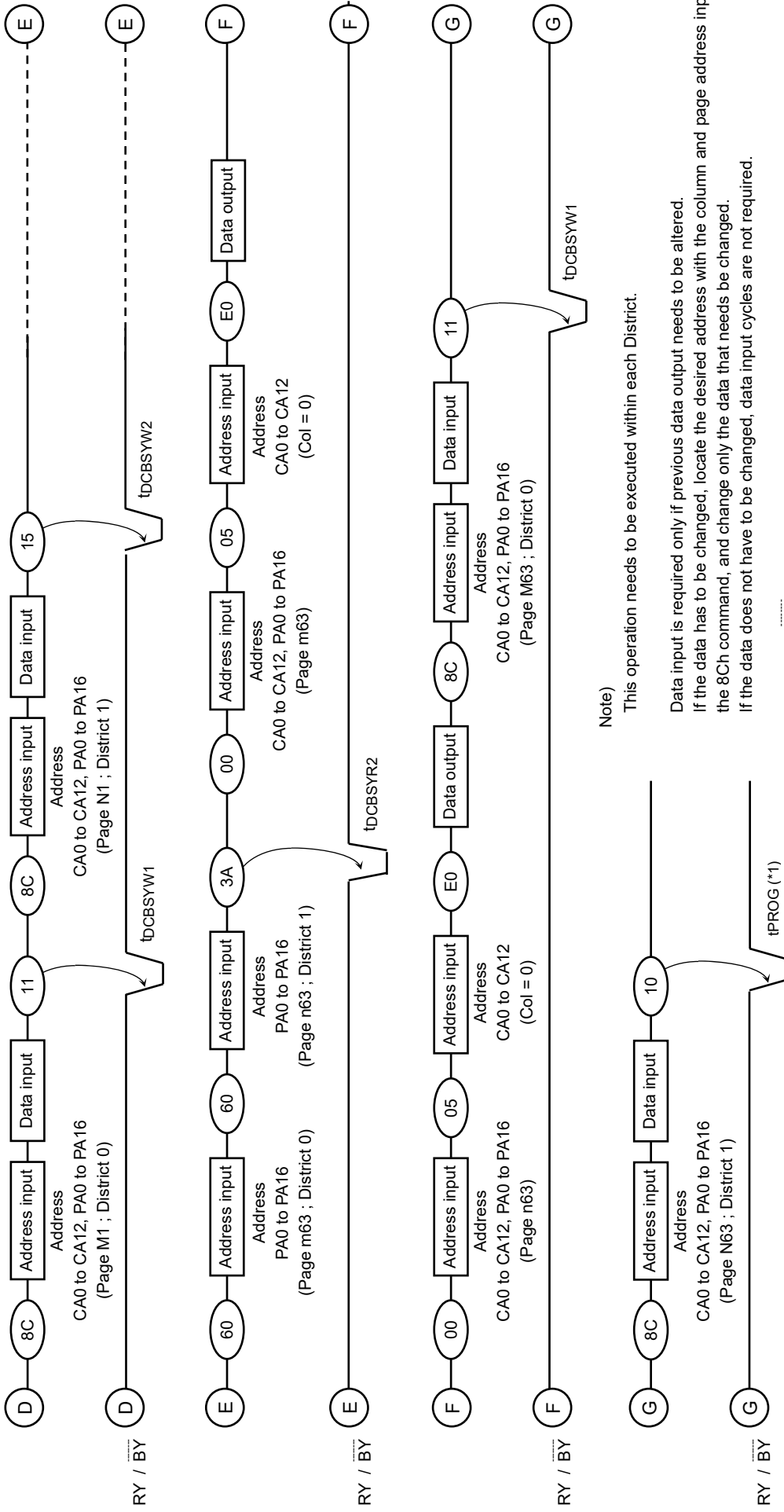
Data input is required only if previous data output needs to be altered.  
If the data has to be changed, locate the desired address with the column and page address input after the 8Ch command, and change only the data that needs be changed.  
If the data does not have to be changed, data input cycles are not required.

Make sure WP is held to High when the Page Copy (2) operation is performed.  
Also make sure the Page Copy operation is terminated with 8Ch-10h command sequence.

Multi Page Copy (2)

By using Multi Page Copy (2), data in two pages can be copied to other pages after the data has been read out. When each block address changes (increments) this sequence has to be started from the beginning. Same page address (PA0 to PA5) within two Districts has to be selected.





(\*)1 tPROG: Since the last page's programming by 10h command is initiated after the previous cache programming, the tPROG during cache programming is given by the following equation.

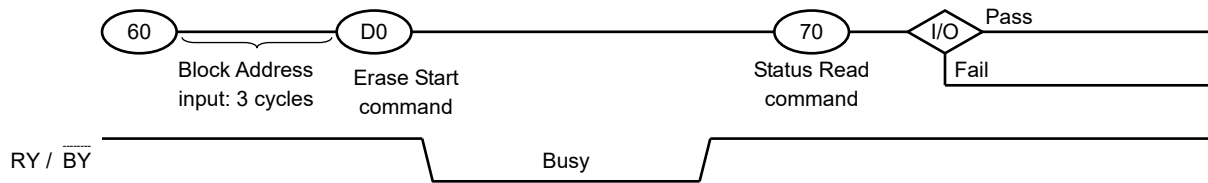
tPROG = tPROG of the last page + tPROG of the previous page-A

A = (Command input cycle + address input cycle + data output/input cycle time of the last page)

If "A" exceeds the tPROG of previous page, tPROG of the last page is tPROG max.

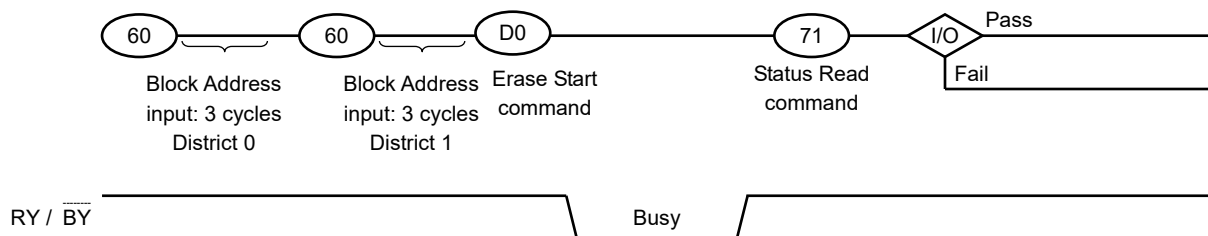
### Auto Block Erase

The Auto Block Erase operation starts on the rising edge of  $\overline{WE}$  after the Erase Start command “D0h” which follows the Erase Setup command “60h”. This two-cycle process for Erase operations acts as an extra layer of protection from accidental erasure of data due to external noise. The device automatically executes the Erase and Verify operations.



### Multi Block Erase

The Multi Block Erase operation starts by selecting two block addresses before D0h command as in the below diagram. The device automatically executes the Erase and Verify operations and the result can be monitored by checking the status with 71h status read command. For details on 71h status read command, refer to section “Multi Page Program with Data Cache”.



### Internal addressing in relation to the Districts

To use the Multi Block Erase operation, the internal addressing should be considered in relation to the District.

- The device consists of 2 Districts.
- Each District consists of 1024 erase blocks.
- The allocation rule is as follows:  
 District 0: Block 0, Block 2, Block 4, Block 6, ..., Block 2046  
 District 1: Block 1, Block 3, Block 5, Block 7, ..., Block 2047

### Address input restriction for the Multi Block Erase

There are the following restrictions in using Multi Block Erase:

(Restriction)

Maximum one block should be selected from each District.

For example:

(60) [District 0] (60) [District 1] (D0)

(Acceptance)

There is no order limitation of the District for the address input.

For example, the following operation is accepted:

(60) [District 1] (60) [District 0] (D0)

It requires no mutual address relation between the selected blocks from each District.

Make sure to terminate the operation with D0h command. If the operation needs to be terminated before D0h command input, input the FFh reset command to terminate the operation.

## ID Read

The device contains ID codes which can be used to identify the device type, the manufacturer, and features of the device. The ID codes can be read out under the following timing conditions:

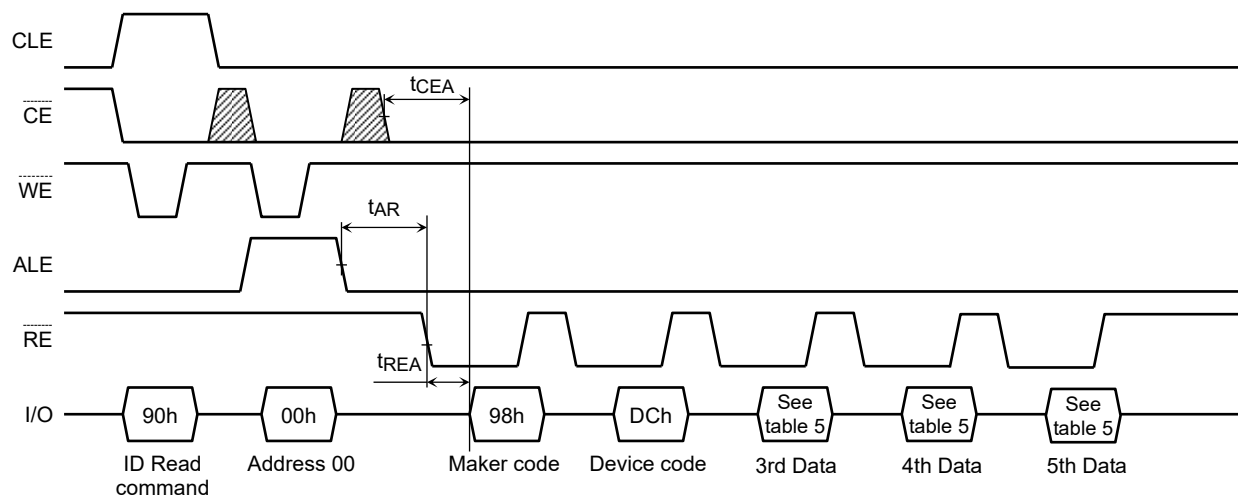


Table 5. Code table

	Description	I/O8	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1	Hex Data
1st Data	Maker Code	1	0	0	1	1	0	0	0	98h
2nd Data	Device Code	1	1	0	1	1	1	0	0	DCh
3rd Data	Chip Number, Cell Type	1	0	0	1	0	0	0	0	90h
4th Data	Page Size, Block Size, I/O Width	0	0	1	0	0	1	1	0	26h
5th Data	District Number	0	1	1	1	0	1	1	0	76h

3rd Data

	Description	I/O8	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1
Internal Chip Number	1							0	0
	2							0	1
	4							1	0
	8							1	1
Cell Type	2 level cell					0	0		
	4 level cell					0	1		
	8 level cell					1	0		
	16 level cell					1	1		
Reserved		1	0	0	1				



4th Data

	Description	I/O8	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1
Page Size (without redundant area)	1 KB							0	0
	2 KB							0	1
	4 KB							1	0
	8 KB							1	1
Block Size (without redundant area)	64 KB			0	0				
	128 KB			0	1				
	256 KB			1	0				
	512 KB			1	1				
I/O Width	x8		0						
	x16		1						
Reserved		0				0	1		

5th Data

	Description	I/O8	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1
District Number	1 District					0	0		
	2 Districts					0	1		
	4 Districts					1	0		
	8 Districts					1	1		
Reserved		0	1	1	1			1	0

## Status Read

The device automatically implements the execution and verification of the Program and Erase operations. The Status Read function is used to monitor the Ready/Busy status of the device, determine the result (pass /fail) of a Program or Erase operation, and determine whether the device is in Protect mode. The device status is output via the I/O port using  $\overline{RE}$  after a "70h" command input. The Status Read command can also be used during a Read operation to monitor the Ready/Busy status.

The resulting information is outlined in Table 6.

Table 6. Status output table

	Definition	Page Program Block Erase	Cache Program	Read Cache Read
I/O1	Chip Status1 Pass: 0      Fail: 1	Pass/Fail	Pass/Fail	Invalid
I/O2	Chip Status 2 Pass: 0      Fail: 1	Invalid	Pass/Fail	Invalid
I/O3	Not Used	0	0	0
I/O4	Not Used	0	0	0
I/O5	Not Used	0	0	0
I/O6	Page Buffer Ready/Busy Ready: 1      Busy: 0	Ready/Busy	Ready/Busy	Ready/Busy
I/O7	Data Cache Ready/Busy Ready: 1      Busy: 0	Ready/Busy	Ready/Busy	Ready/Busy
I/O8	Write Protect Not Protected :1    Protected: 0	Not Protected/Protected	Not Protected/Protected	Not Protected/Protected

The Pass/Fail status on I/O1 and I/O2 is only valid during a Program/Erase operation when the device is in the Ready state.

### Chip Status 1:

During an Auto Page Program or Auto Block Erase operation this bit indicates the Pass/Fail result.

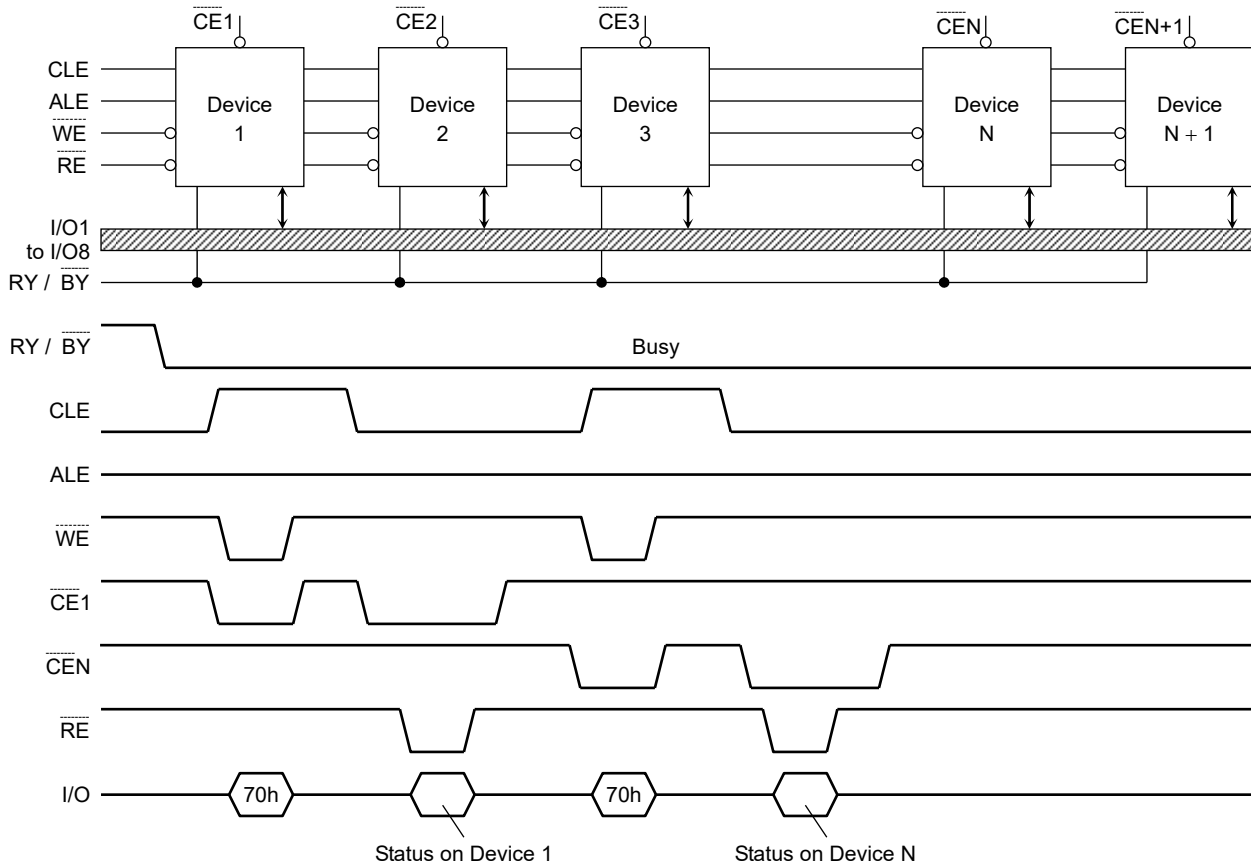
During an Auto Page Program with Data Cache operation, this bit shows the Pass/Fail results of the current page program operation and therefore this bit is only valid when I/O6 shows the Ready state.

### Chip Status 2:

This bit shows the Pass/Fail result of the previous page program operation during Auto Page Program with Data Cache. This status is valid when I/O7 shows the Ready State.

The status output on I/O6 is the same as that of I/O7 if the command input just before 70h is not 15h or 31h.

An application example with multiple devices is shown in the figure below.



#### System Design Note:

If the RY / BY pin signals from multiple devices are wired together as shown in the diagram, the Status Read function can be used to determine the status of each individual device.

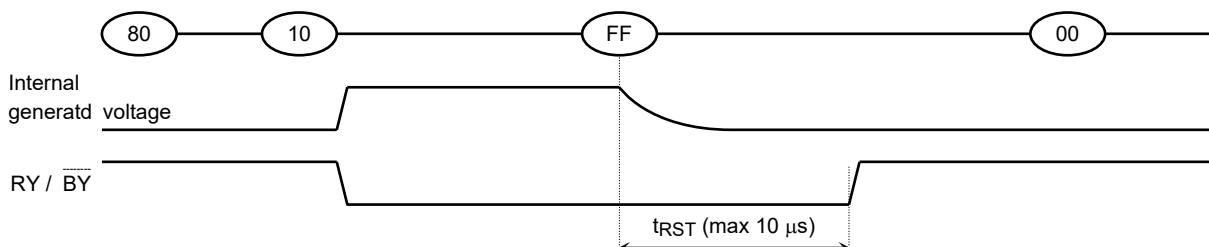
#### Reset

The Reset mode stops all operations. For example, in case of a Program or Erase operation, the internally generated voltage is discharged to 0 volts and the device enters the Wait state.

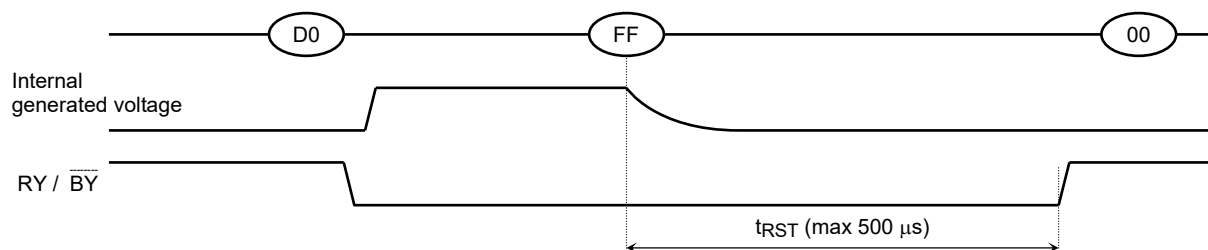
Reset during a Cache Program/Page Copy may not just stop the most recent page program but it may also stop the previous program at a page depending on when the FF reset is input.

The response to a "FFh" Reset command input during the various device operations is as follows:

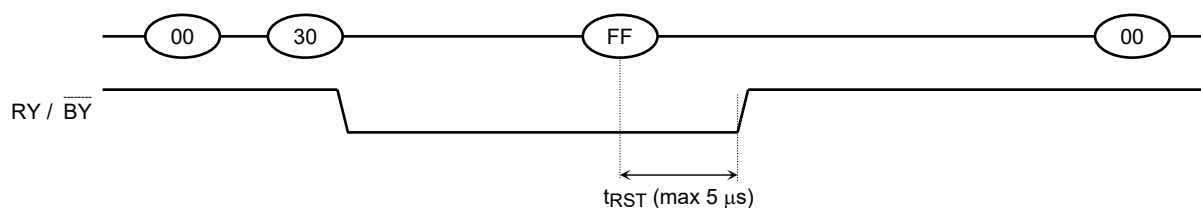
#### When a Reset (FFh) command is input during Program operation



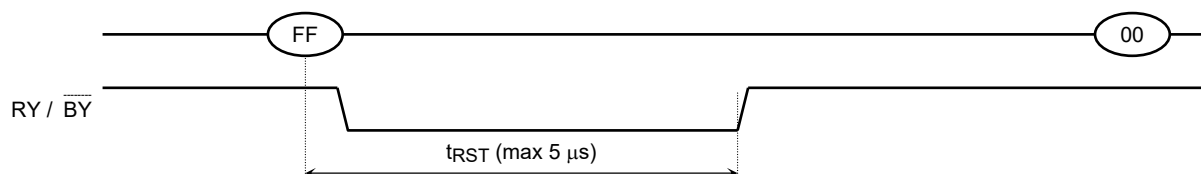
### When a Reset (FFh) command is input during Erase operation



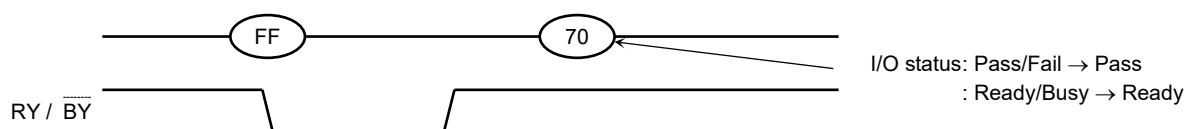
### When a Reset (FFh) command is input during Read operation



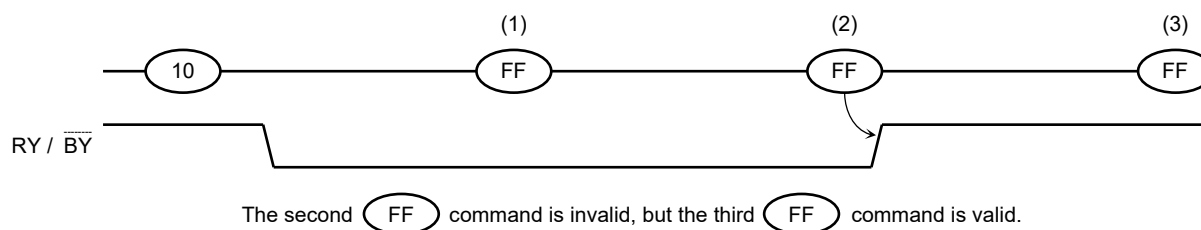
### When a Reset (FFh) command is input during Ready



### When a Status Read command (70h) is input after a Reset



### When two or more Reset commands are input in succession

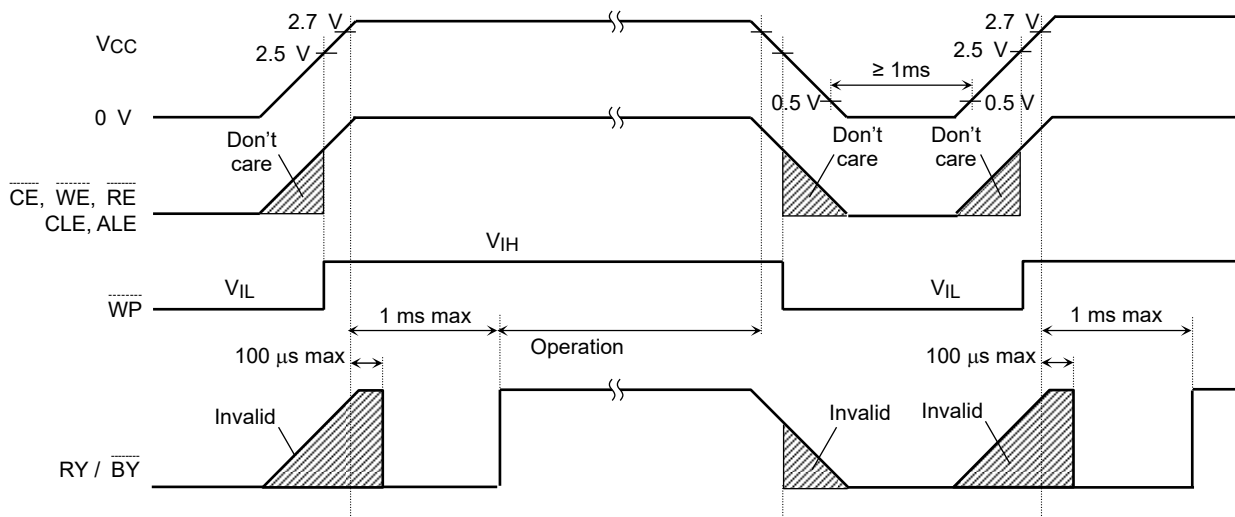


**APPLICATION NOTES AND COMMENTS****(1) Power-on/off sequence**

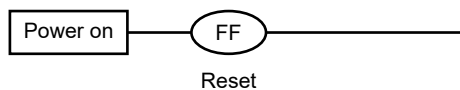
The timing sequence shown in the figure below is necessary for the power-on/off sequence.

The device's internal initialization starts after the power supply reaches an appropriate level during the power-on sequence. During the initialization the device Ready/Busy signal indicates the Busy state as shown in the figure below. In this time period, the acceptable commands are FFh or 70h.

The  $\overline{WP}$  signal is useful for protecting against data corruption at power-on/off.

**(2) Power-on Reset**

The following sequence is necessary because some input signals may not be stable at power-on.

**(3) Prohibition of unspecified commands**

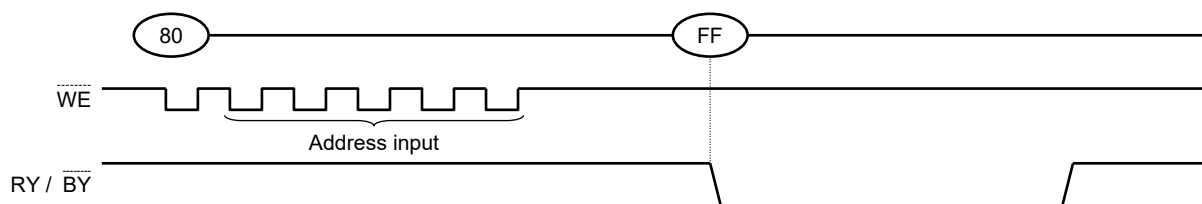
The operation commands are listed in Table 3. Input of a command other than those specified in Table 3 is prohibited. Stored data may be corrupted if an unknown command is entered during the command cycle.

**(4) Restriction of commands while in the Busy state**

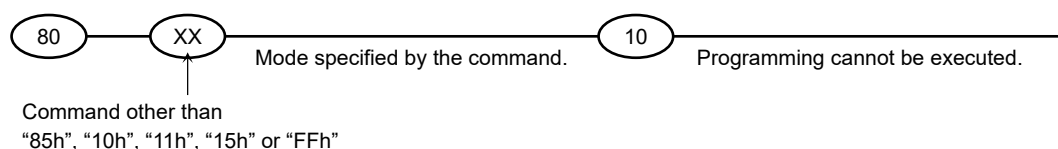
During the Busy state, do not input any command except 70h, 71h and FFh.

## (5) Acceptable commands after Serial Data Input command "80h"

Once the Serial Data Input command "80h" has been input, do not input any command other than the Column Address Change in Serial Data Input command "85h", Auto Page Program command "10h", Multi Page Program command "11h", Auto Page Program with Data Cache Command "15h", or the Reset command "FFh".



If a command other than "85h", "10h", "11h", "15h" or "FFh" is input, the Program operation is not performed and the device operation is set to the mode that the input command specifies.

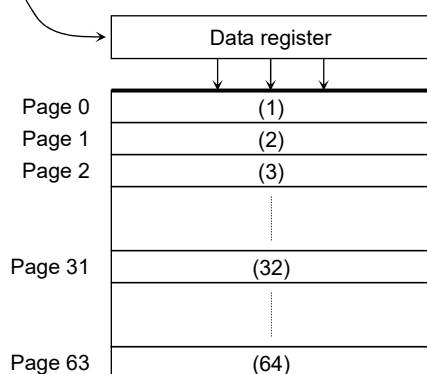


## (6) Addressing for program operation

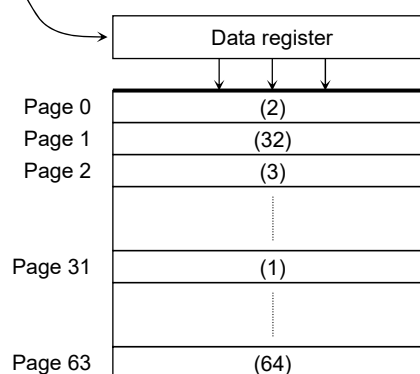
Within a block, the pages must be programmed consecutively from the LSB (least significant bit) page of the block to the MSB (most significant bit) page of the block. Random page address programming is prohibited.

From the LSB page to MSB page

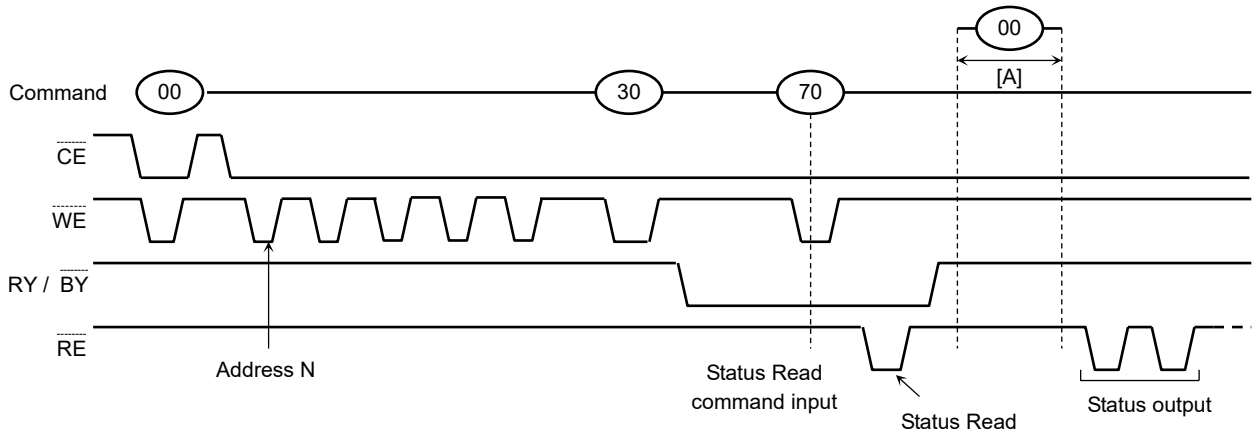
DATA IN: Data (1) → Data (64)

e.g.) Random page program (Prohibition)

DATA IN: Data (1) → Data (64)

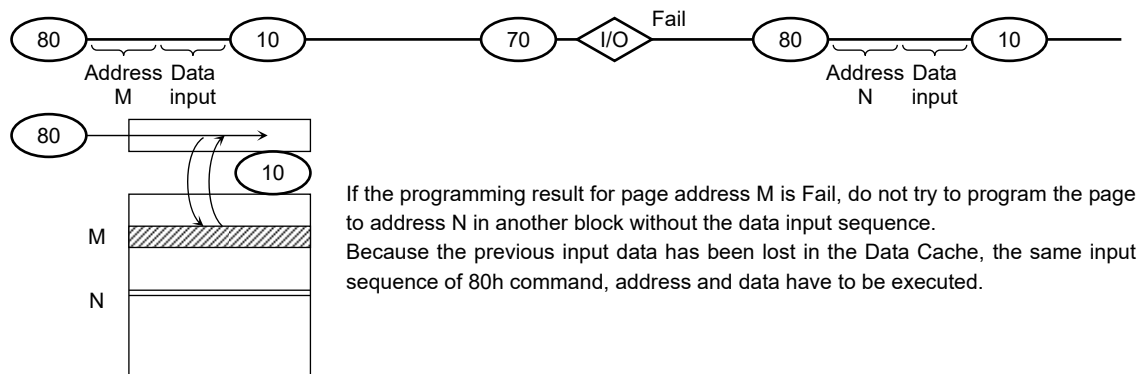


(7) Status Read during a Read operation



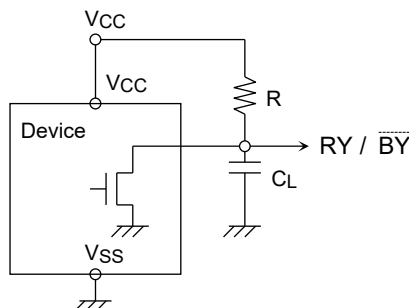
The device status can be read out by inputting the Status Read command “70h” in Read mode. Once the device has been set to Status Read mode by a “70h” command, the device will not return to Read mode unless the Read command “00h” is input during [A]. If the Read command “00h” is input during [A], Status Read mode is reset, and the device returns to Read mode. In this case, data output starts automatically from address N and address input is unnecessary

(8) Auto programming failure

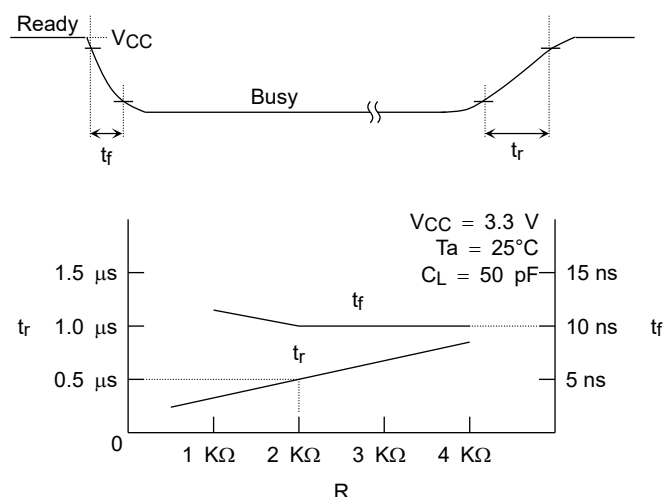


(9) RY / BY: termination for the Ready/Busy pin (RY / BY)

A pull-up resistor needs to be used for termination because the RY / BY buffer consists of an open drain circuit.

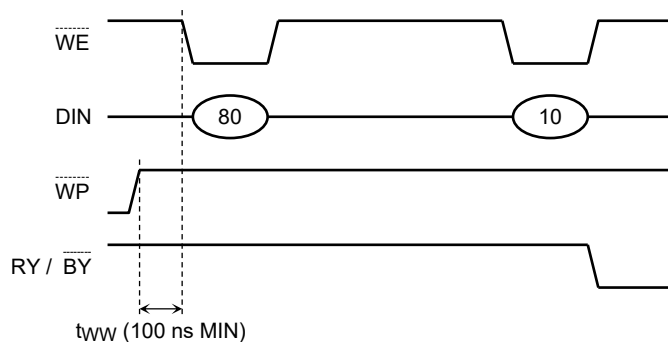
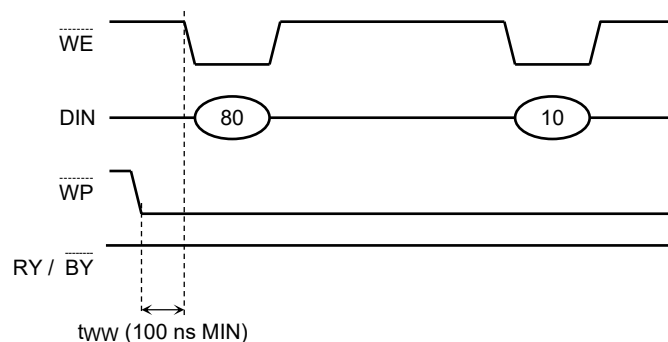
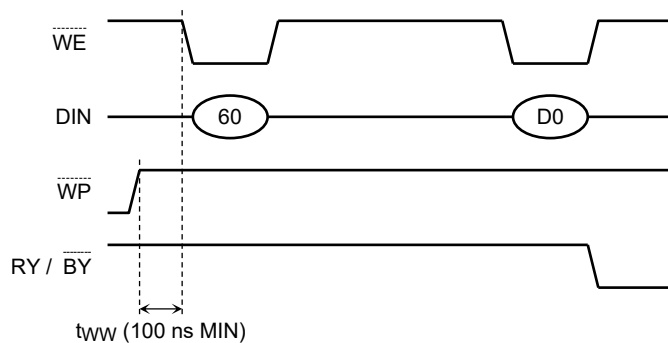
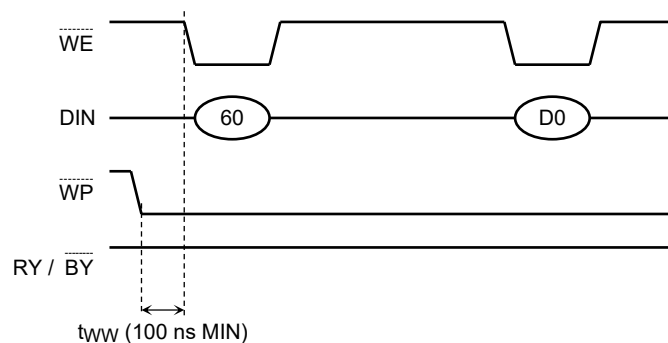


This data may vary from device to device.  
We recommend to use this data as a reference for selecting a resistor value.



(10) Note regarding the  $\overline{WP}$  signal

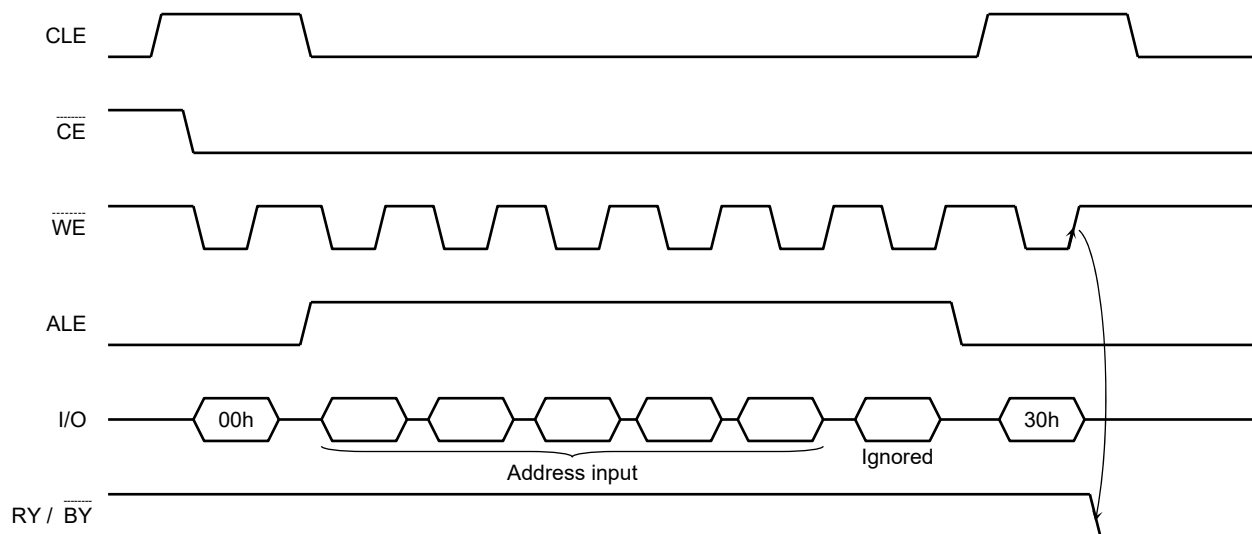
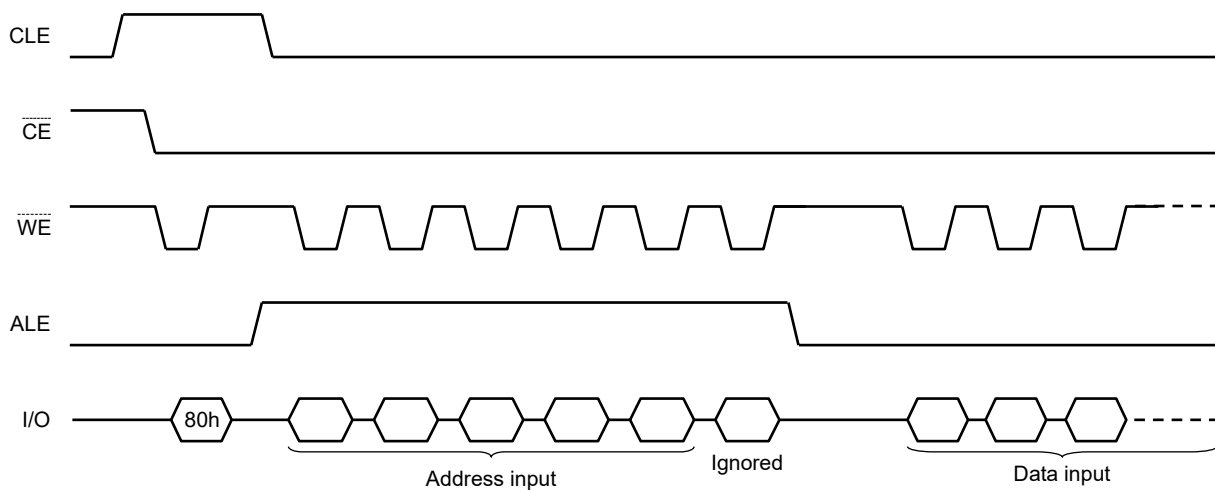
The Erase and Program operations are automatically reset when  $\overline{WP}$  goes Low. The operations are enabled and disabled as follows:

Enable ProgrammingDisable ProgrammingEnable ErasingDisable Erasing



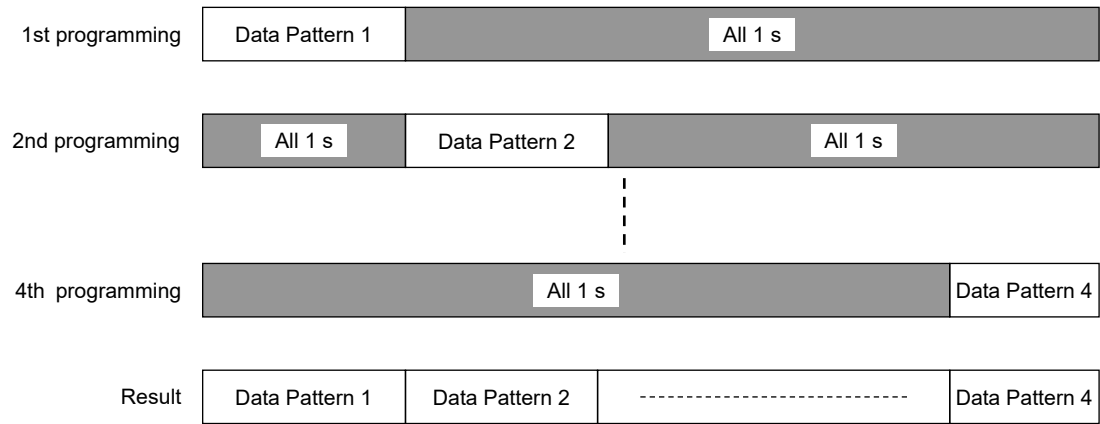
## (11) When six address cycles are input

Although the device may read in a sixth address, it is ignored inside the chip.

Read operationProgram operation

(12) Several programming cycles on the same page (Partial Page Program)

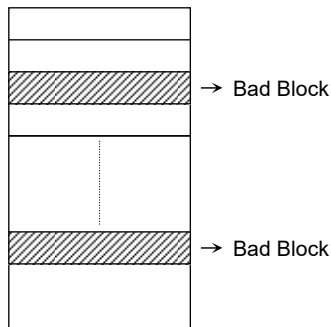
Each segment can be programmed individually as follows:



Number of partial program cycles in the same page must not exceed 4.

## (13) Invalid blocks (bad blocks)

The device occasionally contains unusable blocks. Therefore, the following issues must be recognized:



Please do not perform an erase operation to bad blocks. It may be impossible to recover the bad block's information if the information is erased.

Check if the device has any bad blocks after installation into the system. Refer to the test flow for bad block detection. Bad blocks which are detected by the test flow must be managed as unusable blocks by the system.

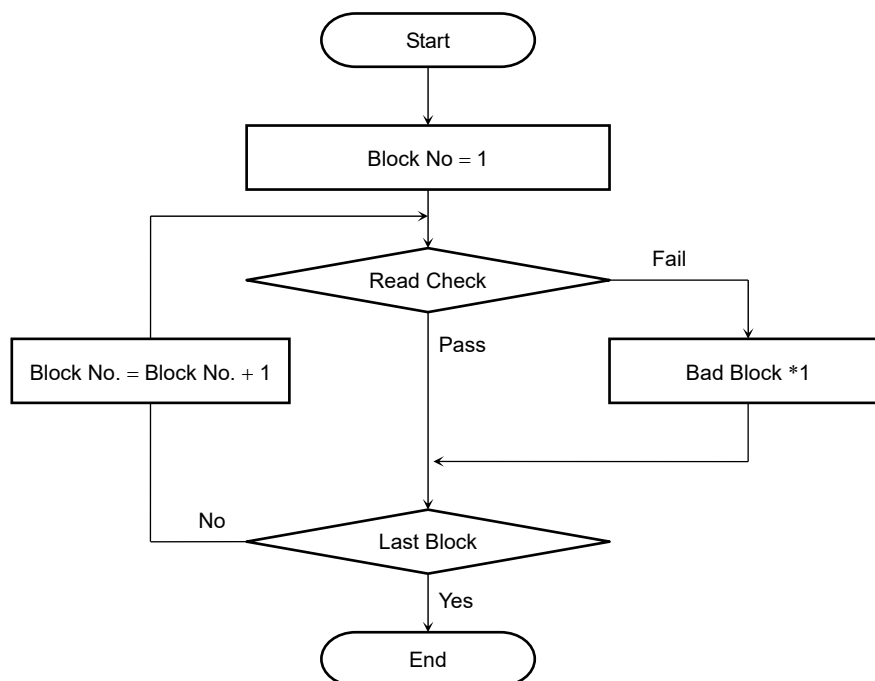
A bad block does not affect the performance of good blocks because it is isolated from the bit lines by select gates.

The number of valid blocks over the device lifetime is as follows:

	MIN	TYP.	MAX	UNIT
Valid (Good) Block Number	2008	—	2048	Blocks

### Bad Block Test Flow

Regarding invalid blocks, bad block mark is in whole pages. Please read one column of any page in each block. If the data of the column is 00(Hex), define the block as a bad block.



\*1: No erase operation is allowed to detected bad blocks

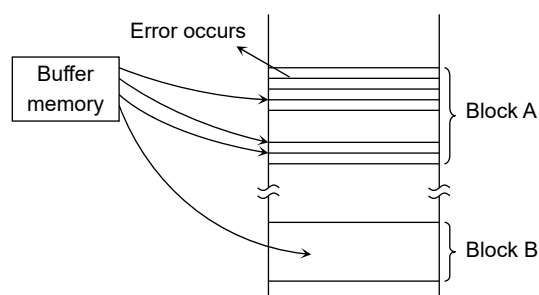
## (14) Failure phenomena for Program, Erase and Read operations

The device may fail during a Program or Erase operation.

The following possible failure modes should be considered when implementing a highly reliable system.

FAILURE MODE		DETECTION AND COUNTERMEASURE SEQUENCE
Block	Erase Failure	Status Read after Erase → Block Replacement
Page	Programming Failure	Status Read after Program → Block Replacement
Read	Bit Error	Check the ECC status at host controller and take appropriate measure such as rewrite in consideration of Wear Leveling before uncorrectable ECC error occurs.

- ECC: Error Correction Code. 8 bit correction per 512 Bytes is necessary.
- Block Replacement

Program

When an error happens in Block A, try to reprogram the data into another Block (Block B) by loading from an external buffer. Then, prevent further system accesses to Block A ( by creating a bad block table or by using another appropriate scheme).

Erase

When an error occurs during an Erase operation, prevent future accesses to this bad block (by creating a table within the system or by using another appropriate scheme).

- (15) Do not turn off the power before the Write/Erase operation is complete. Avoid using the device when the battery is low. Power shortage and/or power failure before the Write/Erase operation is complete will cause loss of data and/or damage to data.
- (16) Please refer to KIOXIA soldering temperature profile for details.

## (17) Reliability Guidance

This reliability guidance is intended to provide some guidance related to using NAND Flash with 8 bit ECC for each 512 bytes. NAND Flash memory cells are gradually worn out and the reliability level of memory cells is degraded by repeating Write and Erase operation of '0' data in each block. For detailed reliability data, please refer to the reliability note for each product.

Although random bit errors may occur during use, it does not necessarily mean that a block is bad.

Generally, a block should be marked as bad when a program status failure or erase status failure is detected.

The reliability of NAND Flash memory cells during the actual usage on system level depends on the usage and environmental conditions. KIOXIA adopts the checker pattern data, 0x55 & 0xAA for alternative Write/Erase cycles, for the reliability test.

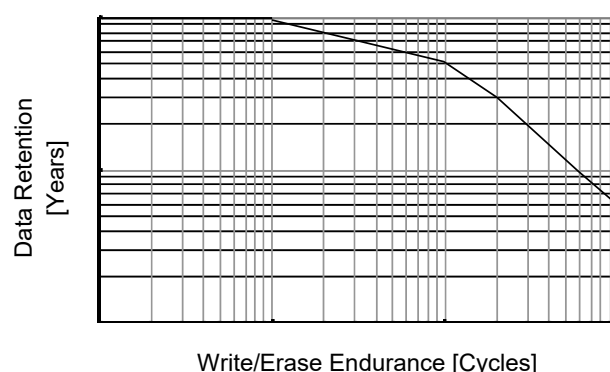
**Write/Erase Endurance**

Write/Erase endurance failures may occur in a cell, page, or block, and are detected by doing a Status Read after either an Auto Page Program or Auto Block Erase operation. The cumulative bad block count will increase along with the number of Write/Erase cycles.

**Data Retention**

The data in NAND Flash memory may change after a certain amount of storage time. This is due to charge loss or charge gain. After block erasure and reprogramming, the block may become usable again. Data Retention time is generally influenced by the number of Write/Erase cycles and temperature.

Here is a graph plotting the relationship between Write/Erase Endurance and Data Retention.

**Read Disturb**

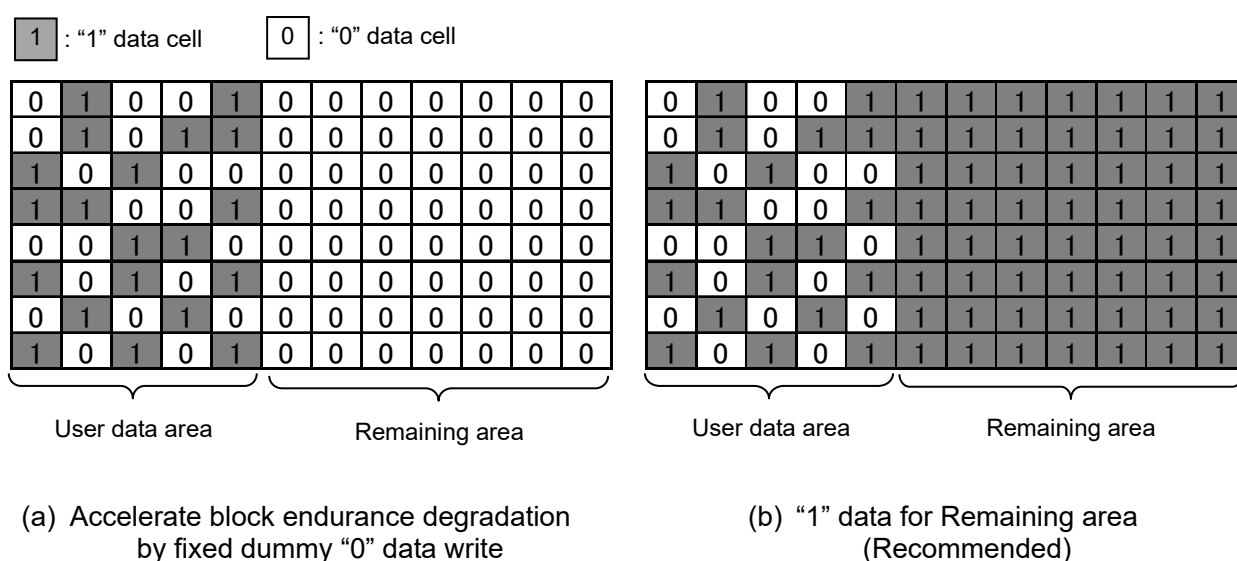
A Read operation may disturb the data in NAND Flash memory. The data may change due to charge gain. Usually, bit errors occur on other pages in the block, not the page being read. After a large number of read cycles (between block erases), a tiny charge may build up and can cause a cell to be soft programmed to another state. After block erasure and reprogramming, the block may become usable again. Read Disturb capability is generally influenced by the number of Write/Erase cycles.

## (18) NAND Management

NAND Management such as Bad Block Management, ECC treatment and Wear Leveling, but not limited to these treatments, should be recognized and incorporated in the system design.

ECC treatment for read data is mandatory against random bit errors, and host should monitor ECC status to take appropriate measures such as rewrite in consideration of Wear Leveling before uncorrectable Error occurs. To realize robust system design generally it is necessary to prevent the concentration of Write/Erase cycles at the specific blocks by adopting Wear Leveling which manages to distribute Write/Erase cycles evenly among NAND Flash memory. And also it is necessary to avoid dummy '0' data write, e.g. '0' data padding, which accelerate block endurance degradation.

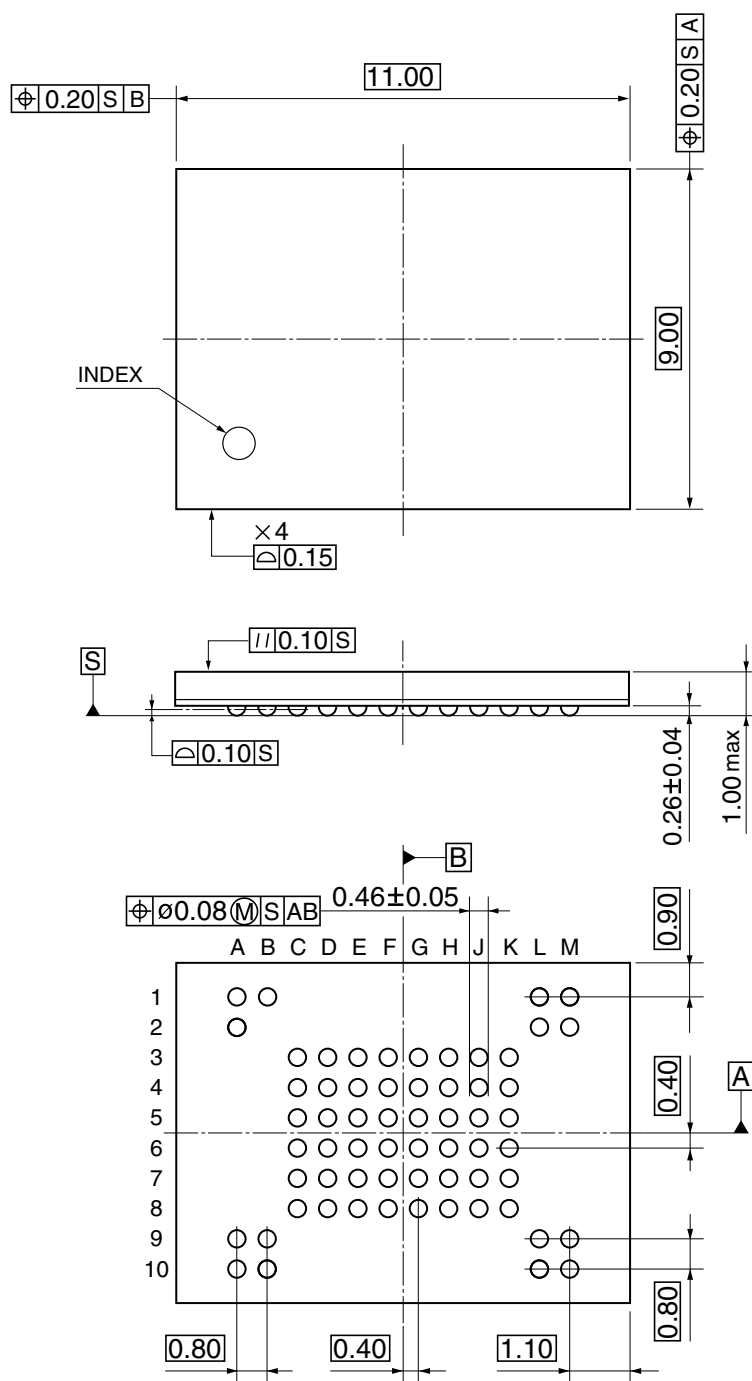
Continuous Write and Erase cycling with high percentage of '0' bits in data pattern can lead to faster block endurance degradation.

Example: NAND cell array with '0' data padding

### Package Dimensions

P-TFBGA63-0911-0.80CZ

Unit: mm



Weight: 0.15 g (typ.)

**Revision History**

Date	Rev.	Description
2013-03-15	0.10	Initial Release
2013-07-05	1.00	Deleted TENTATIVE notation. Clarification for the Package Weight.
2018-12-14	1.10	Corrected typo and described some notes. Removed Soldering Temperature and added note in ABSOLUTE MAXIMUM RATINGS, and added comments in APPLICATION NOTES AND COMMENTS. Removed the word "Recommended" from the title of DC OPERATING CONDITIONS and AC CHARACTERISTICS AND OPERATING CONDITIONS. Renewed Reliability Guidance and added NAND Management. Changed "RESTRICTIONS ON PRODUCT USE".
2019-10-01	2.00	Rebrand as "KIOXIA"



## RESTRICTIONS ON PRODUCT USE

KIOXIA Corporation and its subsidiaries and affiliates are collectively referred to as "KIOXIA". Hardware, software and systems described in this document are collectively referred to as "Product".

- KIOXIA reserves the right to make changes to the information in this document and related Product without notice.
- This document and any information herein may not be reproduced without prior written permission from KIOXIA. Even with KIOXIA's written permission, reproduction is permissible only if reproduction is without alteration/omission.
- Though KIOXIA works continually to improve Product's quality and reliability, Product can malfunction or fail. Customers are responsible for complying with safety standards and for providing adequate designs and safeguards for their hardware, software and systems which minimize risk and avoid situations in which a malfunction or failure of Product could cause loss of human life, bodily injury or damage to property, including data loss or corruption. Before customers use the Product, create designs including the Product, or incorporate the Product into their own applications, customers must also refer to and comply with (a) the latest versions of all relevant KIOXIA information, including without limitation, this document, the specifications, the data sheets and application notes for Product and the precautions and conditions set forth in the "Reliability Information" in KIOXIA Corporation's website and (b) the instructions for the application with which the Product will be used with or for. Customers are solely responsible for all aspects of their own product design or applications, including but not limited to (a) determining the appropriateness of the use of this Product in such design or applications; (b) evaluating and determining the applicability of any information contained in this document, or in charts, diagrams, programs, algorithms, sample application circuits, or any other referenced documents; and (c) validating all operating parameters for such designs and applications. **KIOXIA ASSUMES NO LIABILITY FOR CUSTOMERS' PRODUCT DESIGN OR APPLICATIONS.**
- **PRODUCT IS NEITHER INTENDED NOR WARRANTED FOR USE IN EQUIPMENTS OR SYSTEMS THAT REQUIRE EXTRAORDINARILY HIGH LEVELS OF QUALITY AND/OR RELIABILITY, AND/OR A MALFUNCTION OR FAILURE OF WHICH MAY CAUSE LOSS OF HUMAN LIFE, BODILY INJURY, SERIOUS PROPERTY DAMAGE AND/OR SERIOUS PUBLIC IMPACT ("UNINTENDED USE").** Except for specific applications as expressly stated in this document, Unintended Use includes, without limitation, equipment used in nuclear facilities, equipment used in the aerospace industry, lifesaving and/or life supporting medical equipment, equipment used for automobiles, trains, ships and other transportation, traffic signaling equipment, equipment used to control combustions or explosions, safety devices, elevators and escalators, and devices related to power plant. **IF YOU USE PRODUCT FOR UNINTENDED USE, KIOXIA ASSUMES NO LIABILITY FOR PRODUCT.** For details, please contact your KIOXIA sales representative or contact us via our website.
- Do not disassemble, analyze, reverse-engineer, alter, modify, translate or copy Product, whether in whole or in part.
- Product shall not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable laws or regulations.
- The information contained herein is presented only as guidance for Product use. No responsibility is assumed by KIOXIA for any infringement of patents or any other intellectual property rights of third parties that may result from the use of Product. No license to any intellectual property right is granted by this document, whether express or implied, by estoppel or otherwise.
- **ABSENT A WRITTEN SIGNED AGREEMENT, EXCEPT AS PROVIDED IN THE RELEVANT TERMS AND CONDITIONS OF SALE FOR PRODUCT, AND TO THE MAXIMUM EXTENT ALLOWABLE BY LAW, KIOXIA (1) ASSUMES NO LIABILITY WHATSOEVER, INCLUDING WITHOUT LIMITATION, INDIRECT, CONSEQUENTIAL, SPECIAL, OR INCIDENTAL DAMAGES OR LOSS, INCLUDING WITHOUT LIMITATION, LOSS OF PROFITS, LOSS OF OPPORTUNITIES, BUSINESS INTERRUPTION AND LOSS OF DATA, AND (2) DISCLAIMS ANY AND ALL EXPRESS OR IMPLIED WARRANTIES AND CONDITIONS RELATED TO SALE, USE OF PRODUCT, OR INFORMATION, INCLUDING WARRANTIES OR CONDITIONS OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, ACCURACY OF INFORMATION, OR NONINFRINGEMENT.**
- Do not use or otherwise make available Product or related software or technology for any military purposes, including without limitation, for the design, development, use, stockpiling or manufacturing of nuclear, chemical, or biological weapons or missile technology products (mass destruction weapons). Product and related software and technology may be controlled under the applicable export laws and regulations including, without limitation, the Japanese Foreign Exchange and Foreign Trade Law and the U.S. Export Administration Regulations. Export and re-export of Product or related software or technology are strictly prohibited except in compliance with all applicable export laws and regulations.
- Please contact your KIOXIA sales representative for details as to environmental matters such as the RoHS compatibility of Product. Please use Product in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. **KIOXIA ASSUMES NO LIABILITY FOR DAMAGES OR LOSSES OCCURRING AS A RESULT OF NONCOMPLIANCE WITH APPLICABLE LAWS AND REGULATIONS.**