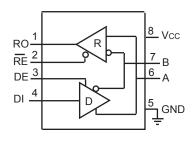
Pin Number	Pin Name	Pin Function
1	RO	Receiver Output. When $\overline{RE}$ is low and if $(A - B) \ge -40$ mV, RO is high. If $(A - B) \le -200$ mV, RO is low.
2	RE	Receiver Output Enable. When $\overline{RE}$ is low, RO is enabled. When $\overline{RE}$ is high, RO is high impedance. Drive $\overline{RE}$ high and DE low to enter shutdown mode.
3	DE	Driver Output Enable. When DE is high, outputs are enabled. When DE is low, outputs are high impedance. Drive DE low and RE high to enter shutdown mode.
4	DI	Driver Input. With DE high, a low level on DI forces non-inverting output low and inverting output high. A high level on DI forces non-inverting output high and inverting output low.
5	GND	Ground
6	А	Non-inverting Receiver Input and Non-inverting Driver Output
7	В	Inverting Receiver Input and Inverting Driver Output
8	Vcc	Positive Supply Vcc. Bypass to GND with a 0.1uF capacitor.

## **DEVICE ARCHITECTURE AND BLOCK DIAGRAM**



8-Pin Half Duplex

#### **ABSOLUTE MAXIMUM RATINGS**

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

## RECOMMENDED OPERATING CONDITIONS

Vcc=5V ±5%, T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted, Typical values are Vcc=5V and T<sub>A</sub>=25°C

Recommended Operating Conditions			Nom.	Max.	Unit
Supply Voltage, Vcc			5	5.5	V
Input Voltage on A and B pins				12	V
High-level input voltage (DI, DE or RE), Vін		2		Vcc	V
Low-level input voltage (DI, DE or RE), VIH		0		0.8	V
Output Current	Driver	-60		60	_
	Receiver	-8		8	mA
Operating Free Air Temperature, TA	Industrial Grade (E)	-40		85	°C

Note: The least positive (most negative) limit is designated as the maxium value.

### ELECTRICAL CHARACTERISTICS

				ECTRICA			
	PARAMETER		CONDITIONS	MIN	TYP	MAX	UNIT
Digital I	nput Signals: DI, DE, RE						
		High, V <sub>I</sub> н		2.0			
Logic inpu	t thresholds	Low, VIL				0.8	V
Logic Inpu	t Current	T <sub>A</sub> = 25°C, a	fter first transition			±1	μΑ
Input Hyst	eresis	TA = 25°C			100		mV
Driver							
Differentia	I Driver Output (Vob)	No Load				Vcc	V
Differentia	I Driver Output, Test 1	RL=100Ω (R	S-422)	2		Vcc	
Dillerentia	Driver Output, rest 1	RL=54Ω (RS	-485)	1.5	2.7	Vcc	V
Differentia	I Driver Output, Test 2	Vcm = -7 to -	+12V	1.5		Vcc	
	Magnitude of Differential Output Vod) (Note 1)	RL=54 or 10	0Ω			±0.2	V
Driver Cor	nmon Mode Output Voltage (Voc)	RL=54 or 10	0Ω	1		3	V
Change in (ΔVoc)	Common Mode Output Voltage	R <sub>L</sub> =54 or 100Ω				±0.2	٧
Driver Short Circuit Current Limit		-7V ≤ Vouт ≤ +12V				±250	mA
Output Leakage Current		DE=0,	Vout=12V			125	
		RE=0, Vcc=0 or 5.5V	Vout= -7V	-100			μA
Receive	r		•				
Receiver I	nput Resistance	-7V ≤ V <sub>CM</sub> ≤	12V	96			ΚΩ
		DE=0,	VIN= 12V			125	
Input Current (A, B pins)		RE=0, Vcc=0 or 5.5V	VIN= -7V	-100			μA
Receiver D	Differential Threshold (VA-VB)	-7V ≤ Vcм ≤ 12V		-200	-125	-40	mV
Receiver I	nput Hysteresis				25		mV
Receiver	Voн	Iоит = -8mA	VID = -40mV	Vcc-1.5			V
Output Voltage	Vol	IOUT = 8mA, VID = -200mV				0.4	
High-Z Re	ceiver Output Current	Vcc =5.5V, 0 ≤ Vouт ≤ Vcc				± 1	μA
Receiver Output Short Circuit Current		0V ≤ V <sub>RO</sub> ≤ V <sub>CC</sub>				± 95	mA
Supply	and Protection						
Supply	IQ, Active Mode	No load, DI=0 or Vcc			400	900	μA
Current	Shutdown Mode, Note 2	DE=0, RE=Vcc, DI=Vcc				1	μΑ
Thermal Shutdown Temperature		Junction temperature			165		- °C
Thermal S	hutdown Hysteresis				15		

#### Notes:

Notes.

1. Change in Magnitude of Differential Output Voltage and Change in Magnitude of Common Mode Output Voltage are the changes in output voltage when DI input changes state.

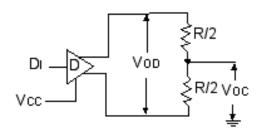
2. The transceivers are put into shutdown by bringing RE high and DE low. If the inputs are in this state for less than 50ns the device does not enter shutdown. If the enable inputs are held in this state for at teast 600ns the device is assured to be in shutdown. In this low power mode most circuitry is disabled and supply current is typically 1nA.

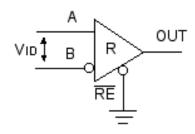
3. Characterized, not 100% tested.

## **\_TIMING CHARACTERISTICS**

Unless otherwise noted Vcc= +5.0±0.5V, ambient temperature TA from -40 to +85°C

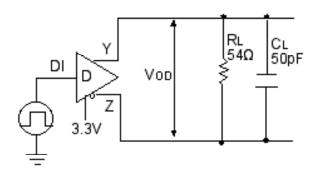
DRIVER CHARACTERISTICS:	Conditions	Min.	Тур.	Max.	Unit
Data Signaling Rate (1 / tu)	Duty Cycle 40 to 60%	115			Kbps
Driver Propagation Delay (tphl., tplh)	R <sub>L</sub> = 54Ω, C <sub>L</sub> = 50pF,			3500	ns
Driver Output Rise/Fall Time (t <sub>R</sub> , t <sub>F</sub> )	]	667	1200	2500	ns
Driver Differential Skew (tplh - tphl)				±500	ns
Driver Enable to Output High (tdzh)				3500	ns
Driver Enable to Output Low (tdz)				3500	ns
Driver Disable from Output High (tDHZ)				100	ns
Driver Disable from Output Low (tDLZ)				100	ns
Shutdown to Driver Output Valid (tdzv)				6000	ns
RECEIVER CHARACTERISTICS:	Conditions	Min.	Тур.	Max	Unit
Receiver Propagation Delay	C <sub>L</sub> = 15pF, V <sub>ID</sub> = ±2V			250	ns
Prop. Delay Skew (tplh – tphl)				±50	ns
Receiver Output Rise / Fall Time (t <sub>R</sub> , t <sub>F</sub> )	C <sub>L</sub> = 15pF			50	ns
Receiver Enable to Output High (tzн)				100	ns
Receiver Enable to Output Low (tzl.)				100	ns
Receiver Disable from Output High (t <sub>HZ</sub> )				100	ns
Receiver Disable from Output Low (t <sub>LZ</sub> )				100	ns
Shutdown to Receiver Output Valid (tROV)				3500	ns
Time to Shutdown (Note 2,3)		50		600	ns



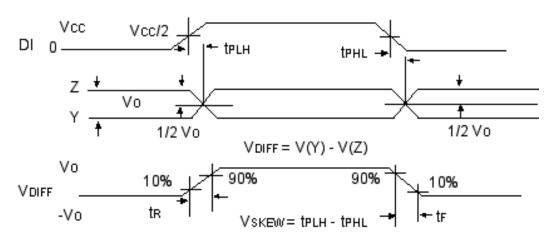


Driver DC Test Circuit

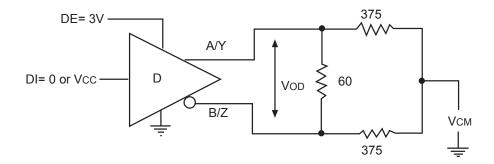
Receiver DC Test Circuit



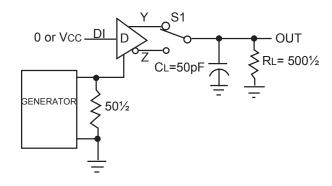
Driver Propagation Delay Time Test Circuit and Timing Diagram

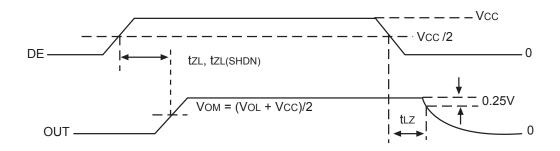


# Driver Differential Output Test Circuit

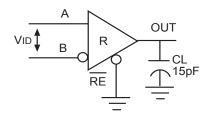


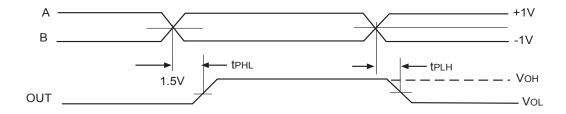
# Driver Enable and Disable Times Test Circuit and Timing Diagram



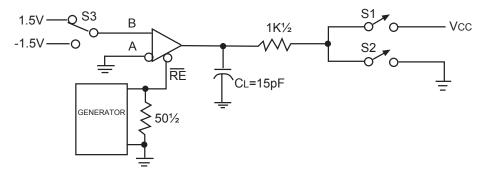


# Receiver Propagation Delay Test Circuit and Timing Diagram

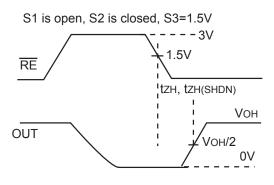


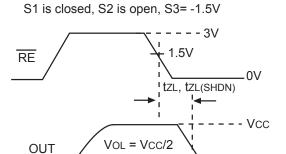


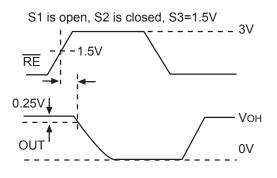
## Receiver Enable and Disable Times Test Circuit

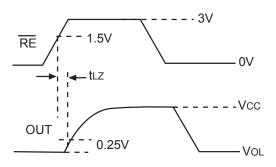


## Receiver Enable and DisableTiming Diagram









S1 is closed, S2 is open, S3= -1.5V

-Vol

Transmitting							
Inputs Outputs							
RE	DE	DI	Α	В			
Х	1	1	1	0			
Х	1	0	0	1			
0	0	Х	Hig	h-Z			
1	0	X	Shute	down			

Receiving					
	Output				
RE	DE	V <sub>A</sub> - V <sub>B</sub>	RO		
0	X	≥ -40mV	1		
0	Х	≤-200mV	0		
0	X	Open/shorted	1		
1	1	X	High-Z		
1	0	Х	Shutdown		

Note: Receiver inputs -200mV < VA - VB  $\,\,$  < -40mV, should be considered indeterminate

#### **DETAILED DESCRIPTION**

The SP4082E is a 5V half-duplex RS-485 transceiver.

The SP4082E contains one driver and one receiver. These devices feature fail-safe circuitry that will guarantee a logic-high receiver output when the receiver inputs are open or shorted.

The SP4082E features reduced slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, allowing error-free data transmission up to 115kbps.

It operates from a single 5.0V supply. Drivers are output short-circuit current limited. Thermal-shutdown circuitry protects drivers against excessive power dissipation. When activated, the thermal-shutdown circuitry places the driver outputs into a high-impedance state.

### **Receiver FAILSAFE**

Ordinary RS-485 differential receivers will be in an indeterminate state whenever A - B is less than ±200mV. This situation can occur whenever the data bus is not being actively driven. The Failsafe feature guarantees a logic-high receiver output if the receiver's differential inputs are shorted or open-circuit.

The receiver thresholds of the SP4082E are very precise and offset by at least a 40mV noise margin from ground. This results in a logic-high receiver output at zero volts input differential while maintaining compliance with the EIA/TIA-485 standard of ±200mV.

### ±15KV ESD PROTECTION

ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver output and receiver inputs have extra protection against static electricity. Sipex uses state of the art structures to protect these pins against ESD of ±15kV without damage. The ESD structures withstand high ESD in all states: normal operation, shutdown, and powered down. After an ESD event, the SP4082E keeps working without latch-up or damage.

ESD protection can be tested in various ways. The transmitter outputs and receiver inputs of

the SP4082E is characterized for protection to the following limits:

±15kV using the Human Body Model

#### **ESD TEST CONDITIONS**

ESD performance depends on a variety of conditions. Contact Sipex for a reliability report that documents test setup, methodology and results.

#### MACHINE MODEL

The machine model for ESD tests all pins using a 200pF storage capacitor and zero discharge resistance. The objective is to emulate the stress caused when I/O pins are contacted by handling equipment during test and assembly.

## **256 TRANSCEIVERS ON THE BUS**

The standard RS-485 receiver input impedance is  $12k\Omega$  (1 unit load). A standard driver can drive up to 32 unit loads. The SP4032E has only a 1/8th unit load receiver input impedance (96k $\Omega$ ), thereby allowing eight times as many, up to 256, transceivers to be connected in parallel on a communication line. Any combination of these devices and other RS-485 transceivers up to a total of 32 unit loads may be connected to the line.

#### LOW POWER SHUTDOWN MODE

Low-power shutdown mode is initiated by bringing both  $\overline{RE}$  high and DE low simultaneously. While in shutdown devices typically draw only 50nA of supply current. DE and  $\overline{RE}$  may be tied together and driven by a single control signal. Devices are guaranteed not to enter shutdown if  $\overline{RE}$  is high and DE is low for less than 50ns. If the inputs are in this state for at least 600ns, the parts are shutdown.

Enable times tzH and tzL apply when the part is not in low-power shutdown state. Enable times  $tzH(\overline{SHDN})$  and  $tzL(\overline{SHDN})$  apply when the parts are shut down. The drivers and receivers take longer to become enabled from low power shutdown mode  $tzL(\overline{SHDN})$  and  $tzL(\overline{SHDN})$  than from driver/receiver-disable mode (tzH, tzL).

#### DRIVER OUTPUT PROTECTION

Two mechanisms prevent excessive output current and power dissipation caused by faults or by bus contention. First, a driver current limit on the output stage provides immediate protec-

11

tion against short circuits over the whole common-mode voltage range. Second, a thermalshutdown circuit forces the driver outputs into a high-impedance state if junction temperature becomes excessive.

## LINE LENGTH, EMI, AND REFLECTIONS

It features controlled slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables.

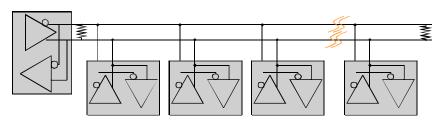
Driver rise and fall times are limited to no faster than 667ns, allowing error-free data transmission up to 115kbps.

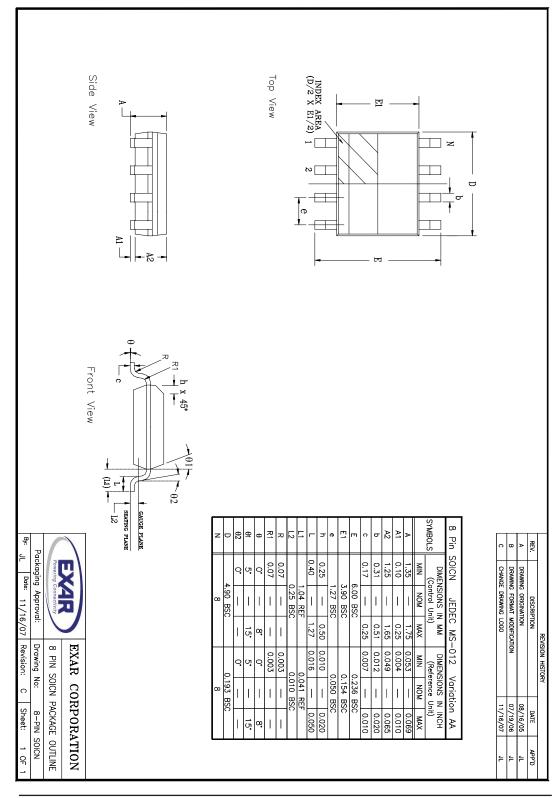
The RS-485/RS-422 standard covers line lengths up to 4,000ft. Maximum achievable line length is a function of signal attenuation and noise. Use of slew-controlled drivers may help to reduce crosstalk interference and permit communication over longer transmission lines.

Termination prevents reflections by eliminating the impedance mismatches on a transmission line. Line termination is typically used if rise and fall times are shorter than the round-trip signal propagation time. Slew-limited drivers may reduce or eliminate the need for cable termination in many applications.

### **TYPICAL APPLICATIONS:**

## Half-Duplex Network





Part number	LEAD FREE	Tape & Reel	Temperature range	Package Type
SP4082EEN	-L	/TR	From -40 to +85°C	8 pin nSOIC

All packages are available as lead free (RoHS compliant). To order add "-L" suffix to part number. For Tape and Reel add "/TR". Reel quantity is 2,500 for NSOIC.

Example: SP4082EEN-L/TR = lead free and Tape and Reel. SP4082EEN/TR = standard with Tape and Reel.

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