

CY7C68013A/CY7C68014A CY7C68015A/CY7C68016A

EZ-USB FX2LP USB Microcontroller High-Speed USB Peripheral Controller

Features

- USB 2.0 USB IF Hi-Speed certified (TID # 40460272)
- Single-chip integrated USB 2.0 transceiver, smart SIE, and enhanced 8051 microprocessor
- Fit-, form-, and function-compatible with the FX2
 - □ Pin-compatible0
 - □ Object-code-compatible
 - □ Functionally compatible (FX2LP is a superset)
- Ultra-low power: I_{CC} no more than 85 mA in any mode □ Ideal for bus- and battery-powered applications
- Software: 8051 code runs from:
 - □ Internal RAM, which is downloaded through USB
 - □ Internal RAM, which is loaded from EEPROM
 - □ External memory device (128-pin package)
- 16 KB of on-chip code/data RAM
- Four programmable BULK, INTERRUPT, and ISOCHRONOUS endpoints
 - □ Buffering options: Double, triple, and quad
- Additional programmable (BULK/INTERRUPT) 64-byte endpoint
- 8-bit or 16-bit external data interface
- Smart media standard ECC generation
- GPIF™ (general programmable interface)
 - □ Enables direct connection to most parallel interfaces
 - □ Programmable waveform descriptors and configuration registers to define waveforms
 - Supports multiple ready (RDY) inputs and control (CTL) outputs
- Integrated, industry-standard, enhanced 8051
 - □ 48-MHz, 24-MHz, or 12-MHz CPU operation
 - ☐ Four clocks per instruction cycle
 - □ Two USARTs
 - □ Three counter/timers
 - □ Expanded interrupt system
 - Two data pointers

- 3.3-V operation with 5-V tolerant inputs
- Vectored USB interrupts and GPIF/FIFO interrupts
- Separate data buffers for the setup and data portions of a CONTROL transfer
- Integrated I²C controller; runs at 100 or 400 kHz^[1]
- Four integrated FIFOs
 - □ Integrated glue logic and FIFOs lower system cost
 - ☐ Automatic conversion to and from 16-bit buses
 - □ Master or slave operation
 - Uses external clock or asynchronous strobes
 - □ Easy interface to ASIC and DSP ICs
- Available in commercial and industrial temperature grades (all packages except VFBGA)

Features (CY7C68013A/14A only)

- CY7C68014A: Ideal for battery-powered applications
 □ Suspend current: 100 µA (typ)
- CY7C68013A: Ideal for nonbattery-powered applications
 □ Suspend current: 300 μA (typ)
- Available in five Pb-free packages with up to 40 GPIOs
 □ 128-pin TQFP (40 GPIOs), 100-pin TQFP (40 GPIOs), 56-pin QFN (24 GPIOs), 56-pin SSOP (24 GPIOs), and 56-pin VFBGA (24 GPIOs)

Features (CY7C68015A/16A only)

- CY7C68016A: Ideal for battery-powered applications
 □ Suspend current: 100 μA (typ)
- CY7C68015A: Ideal for nonbattery-powered applications
 □ Suspend current: 300 μA (typ)
- Available in Pb-free 56-pin QFN package (26 GPIOs)
- Two more GPIOs than CY7C68013A/14A enabling additional features in the same footprint

Functional Description

For a complete list of related resources, click here.

Notes

1. The actual I²C clock frequency will be different. The measured I²C clock frequency when set for 100 kHz and 400 kHz is around 85 kHz and 300 kHz respectively.

2. For information on silicon errata, see "Errata" on page 68. Details include trigger conditions, devices affected, and proposed workaround.

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More Information

Cypress provides a wealth of data at www.cypress.com to help you to select the right device for your design, and to help you to quickly and effectively integrate the device into your design. For a comprehensive list of resources, see the application note AN65209 - Getting Started with FX2LP.

- Overview: USB Portfolio, USB Roadmap
- USB 2.0 Product Selectors: FX2LP, AT2LP, NX2LP-Flex, SX2
- Application notes: Cypress offers a large number of USB application notes covering a broad range of topics, from basic to advanced level. Recommended application notes for getting started with FX2LP are:
 - □ AN65209 Getting Started with FX2LP
 - □ AN15456 Guide to Successful EZ-USB® FX2LP™ and EZ-USB FX1™ Hardware Design and Debug
 - □ AN50963 EZ-USB® FX1™/FX2LP™ Boot Options
 - □ AN66806 EZ-USB® FX2LP™ GPIF Design Guide
- □ AN61345 Implementing an FX2LP™- FPGA Interface
- □ AN57322 Interfacing SRAM with FX2LP over GPIF
- □ AN4053 Streaming Data through Isochronous/Bulk Endpoints on EZ-USB® FX2 and EZUSB FX2LP
- ¬AN63787 EZ-USB® FX2LP™ GPIF and Slave FIFO Configuration Examples using 8-bit Asynchronous Interface

For complete list of Application notes, click here.

- Code Examples:
 - □ USB Hi-Speed
- Technical Reference Manual (TRM):
 □ EZ-USB FX2LP Technical Reference Manual
- Reference Designs:
 - □ CY4661 External USB Hard Disk Drives (HDD) with Fingerprint Authentication Security
 - ☐ FX2LP DMB-T/H TV Dongle reference design
- Models: IBIS

EZ-USB FX2LP Development Kit

The CY3684 EZ-USB FX2LP Development Kit is a complete development resource for FX2LP.

The CY3689 EZ-USB FX2LP Discovery Kit is a newly designed kit that helps beginners and experienced users to implement different applications using FX2LP

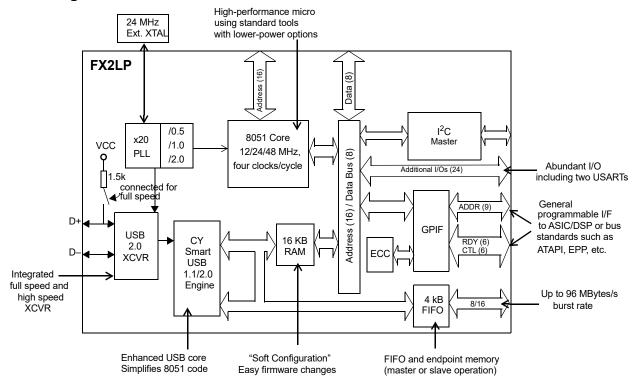
The development kit contains collateral materials for the firmware, hardware, and software aspects of a design using FX2LP.

GPIF™ Designer

FX2LP™ General Programmable Interface (GPIF) provides an independent hardware unit, which creates the data and control signals required by an external interface. FX2LP GPIF Designer allows users to create and modify GPIF waveform descriptors for EZ-USB FX2/ FX2LP family of chips using a graphical user interface. Extensive discussion of general GPIF discussion and programming using GPIF Designer is included in FX2LP Technical Reference Manual and GPIF Designer User Guide, distributed with GPIF Designer. AN66806 - Getting Started with EZ-USB® FX2LP™ GPIF can be a good starting point.



Logic Block Diagram



Cypress's EZ-USB[®] FX2LPTM (CY7C68013A/14A) is a low-power version of the EZ-USB FX2TM (CY7C68013), which is a highly integrated, low-power USB 2.0 microcontroller. By integrating the USB 2.0 transceiver, serial interface engine (SIE), enhanced 8051 microcontroller, and a programmable peripheral interface in a single chip, Cypress has created a cost-effective solution that provides superior time-to-market advantages with low power to enable bus-powered applications.

The ingenious architecture of FX2LP results in data transfer rates of over 53 Mbytes per second (the maximum allowable USB 2.0 bandwidth), while still using a low-cost 8051 microcontroller in a package as small as a 56 VFBGA (5 mm × 5 mm). Because it incorporates the USB 2.0 transceiver, the FX2LP is more economical, providing a smaller-footprint solution than a USB 2.0 SIE or external transceiver implementations.

With EZ-USB FX2LP, the Cypress Smart SIE handles most of the USB 1.1 and 2.0 protocol in hardware, freeing the embedded microcontroller for application-specific functions and decreasing the development time to ensure USB compatibility.

The general programmable interface (GPIF) and Master/Slave Endpoint FIFO (8-bit or 16-bit data bus) provide an easy and glueless interface to popular interfaces such as ATA, UTOPIA, EPP, PCMCIA, and most DSP/processors.

The FX2LP draws less current than the FX2 (CY7C68013), has double the on-chip code/data RAM, and is fit, form, and function compatible with the 56-, 100-, and 128-pin FX2.

Five packages are defined for the family: 56-ball VFBGA, 56-pin SSOP, 56-pin QFN, 100-pin TQFP, and 128-pin TQFP.

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Applications

- Portable video recorder
- MPEG/TV conversion
- DSL modems
- ATA interface
- Memory card readers
- Legacy conversion devices
- Cameras
- Scanners
- Wireless LAN
- MP3 players
- Networking

The "Reference Designs" section of the Cypress web site provides additional tools for typical USB 2.0 applications. Each reference design comes complete with firmware source and object code, schematics, and documentation. Visit www.cypress.com for more information.

Functional Overview

USB Signaling Speed

FX2LP operates at two of the three rates defined in the USB Specification Revision 2.0, dated April 27, 2000:

- Full speed, with a signaling bit rate of 12 Mbps
- High speed, with a signaling bit rate of 480 Mbps

FX2LP does not support the Low Speed signaling mode of 1.5 Mbps.

8051 Microprocessor

The 8051 microprocessor embedded in the FX2LP family has 256 bytes of register RAM, an expanded interrupt system, three timer/counters, and two USARTs.

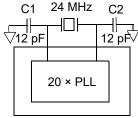
8051 Clock Frequency

FX2LP has an on-chip oscillator circuit that uses an external 24-MHz (±100 ppm) crystal with the following characteristics:

- Parallel resonant
- Fundamental mode
- 500-µW drive level
- 12-pF (5% tolerance) load capacitors

An on-chip PLL multiplies the 24-MHz oscillator up to 480 MHz, as required by the transceiver/PHY; internal counters divide it down for use as the 8051 clock. The default 8051 clock frequency is 12 MHz. The clock frequency of the 8051 can be changed by the 8051 through the CPUCS register, dynamically.

Figure 1. Crystal Configuration



12-pF capacitor values assume a trace capacitance of 3 pF per side on a four-layer FR4 PCA

The CLKOUT pin, which can be three-stated and inverted using internal control bits, outputs the 50% duty cycle 8051 clock, at the selected 8051 clock frequency: 48 MHz, 24 MHz, or 12 MHz.

USARTs

FX2LP contains two standard 8051 USARTs, addressed through Special Function Register (SFR) bits. The USART interface pins are available on separate I/O pins, and are not multiplexed with port pins.

UART0 and UART1 can operate using an internal clock at 230 KBaud with no more than 1% baud rate error. 230 KBaud operation is achieved by an internally derived clock source that generates overflow pulses at the appropriate time. The internal clock adjusts for the 8051 clock rate (48 MHz, 24 MHz, and 12 MHz) such that it always presents the correct frequency for the 230-KBaud operation^[3].

Special Function Registers

Certain 8051 SFR addresses are populated to provide fast access to critical FX2LP functions. These SFR additions are shown in Table 1 on page 6. Bold type indicates nonstandard, enhanced 8051 registers. The two SFR rows that end with "0" and "8" contain bit-addressable registers. The four I/O ports A to D use the SFR addresses used in the standard 8051 for ports 0 to 3, which are not implemented in FX2LP. Because of the faster and more efficient SFR addressing, the FX2LP I/O ports are not addressable in external RAM space (using the MOVX instruction).

I²C Bus

FX2LP supports the I²C bus as a master only at 100/400 kHz^[4]. SCL and SDA pins have open-drain outputs and hysteresis inputs. These signals must be pulled up to 3.3 V, even if no I²C device is connected.

Buses

All packages, 8-bit or 16-bit "FIFO" bidirectional data bus, multiplexed on I/O ports B and D. 128-pin package: adds 16-bit output-only 8051 address bus, 8-bit bidirectional data bus.

Notes

- 3. 115-KBaud operation is also possible by programming the 8051 SMOD0 or SMOD1 bits to a "1" for UART0, UART1, or both respectively.
- 4. The actual I²C clock frequency will be different. The measured I²C clock frequency when set for 100 kHz and 400 kHz is around 85 kHz and 300 kHz respectively.



Table 1. Special Function Registers

x	8x	9x	Ax	Bx	Сх	Dx	Ex	Fx
0	IOA	IOB	IOC	IOD	SCON1	PSW	ACC	В
1	SP	EXIF	INT2CLR	IOE	SBUF1	_	_	_
2	DPL0	MPAGE	INT4CLR	OEA	-	_	_	_
3	DPH0	_	_	OEB	-	_	_	_
4	DPL1	_	_	OEC	-	_	_	_
5	DPH1	_	_	OED	-	_	_	-
6	DPS	_	_	OEE	_	_	_	_
7	PCON	_	_	_	-	_	_	_
8	TCON	SCON0	ΙΕ	IP	T2CON	EICON	EIE	EIP
9	TMOD	SBUF0	_	_	-	_	_	_
Α	TL0	AUTOPTRH1	EP2468STAT	EP01STAT	RCAP2L	_	_	_
В	TL1	AUTOPTRL1	EP24FIFOFLGS	GPIFTRIG	RCAP2H	_	_	_
С	TH0	reserved	EP68FIFOFLGS		TL2	_	_	_
D	TH1	AUTOPTRH2	_	GPIFSGLDATH	TH2	_	_	_
Е	CKCON	AUTOPTRL2	_	GPIFSGLDATLX	_	_	_	_
F	_	reserved	AUTOPTRSET-UP	GPIFSGLDATLNOX	-	_	-	-

USB Boot Methods

During the power-up sequence, internal logic checks the I²C port for the connection of an EEPROM whose first byte is either 0xC0 or 0xC2. If found, it uses the VID/PID/DID values in the EEPROM in place of the internally stored values (0xC0), or it boot-loads the EEPROM contents into internal RAM (0xC2). If no EEPROM is detected, FX2LP enumerates using internally stored descriptors. The default ID values for FX2LP are VID/PID/DID (0x04B4, 0x8613, 0xAxxx where xxx = Chip revision)^[5].

Table 2. Default ID Values for FX2LP

Default VID/PID/DID			
Vendor ID	0x04B4	Cypress Semiconductor	
Product ID	0x8613	EZ-USB FX2LP	
Device release	0xAnnn	Depends on chip revision (nnn = chip revision where first silicon = 001)	

ReNumeration

Because the FX2LP's configuration is soft, one chip can take on the identities of multiple distinct USB devices.

When first plugged into USB, the FX2LP enumerates automatically and downloads firmware and USB descriptor tables over the USB cable. Next, the FX2LP enumerates again, this time as a device defined by the downloaded information. This patented two step process called ReNumeration **M* happens instantly when the device is plugged in, without a hint that the initial download step has occurred.

Two control bits in the USBCS (USB Control and Status) register control the ReNumeration process: DISCON and RENUM. To simulate a USB disconnect, the firmware sets DISCON to 1. To reconnect, the firmware clears DISCON to 0.

Before reconnecting, the firmware sets or clears the RENUM bit to indicate whether the firmware or the Default USB Device handles device requests over endpoint zero: if RENUM = 0, the Default USB Device handles device requests; if RENUM = 1, the firmware services the requests.

Bus-Powered Applications

The FX2LP fully supports bus-powered designs by enumerating with less than 100 mA as required by the USB 2.0 specification.

Interrupt System

INT2 Interrupt Request and Enable Registers

FX2LP implements an autovector feature for INT2 and INT4. There are 27 INT2 (USB) vectors, and 14 INT4 (FIFO/GPIF) vectors. See EZ-USB Technical Reference Manual (TRM) for more details.

USB Interrupt Autovectors

The main USB interrupt is shared by 27 interrupt sources. To save the code and processing time that is required to identify the individual USB interrupt source, the FX2LP provides a second level of interrupt vectoring, called Autovectoring. When a USB interrupt is asserted, the FX2LP pushes the program counter to its stack, and then jumps to the address 0x0043 where it expects to find a "jump" instruction to the USB interrupt service routine.

Note

5. The I²C bus SCL and SDA pins must be pulled up, even if an EEPROM is not connected. Otherwise this detection method does not work properly.

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The FX2LP jump instruction is encoded as follows:

Table 3. INT2 USB Interrupts

	USB INTERRUPT TABLE FOR INT2				
Priority	INT2VEC Value	Source	Notes		
1	00	SUDAV	Setup data available		
2	04	SOF	Start of frame (or microframe)		
3	08	SUTOK	Setup token received		
4	0C	SUSPEND	USB suspend request		
5	10	USB RESET	Bus reset		
6	14	HISPEED	Entered high speed operation		
7	18	EP0ACK	FX2LP ACK'd the CONTROL Handshake		
8	1C		reserved		
9	20	EP0-IN	EP0-IN ready to be loaded with data		
10	24	EP0-OUT	EP0-OUT has USB data		
11	28	EP1-IN	EP1-IN ready to be loaded with data		
12	2C	EP1-OUT	EP1-OUT has USB data		
13	30	EP2	IN: buffer available. OUT: buffer has data		
14	34	EP4	IN: buffer available. OUT: buffer has data		
15	38	EP6	IN: buffer available. OUT: buffer has data		
16	3C	EP8	IN: buffer available. OUT: buffer has data		
17	40	IBN	IN-Bulk-NAK (any IN endpoint)		
18	44		reserved		
19	48	EP0PING	EP0 OUT was pinged and it NAK'd		
20	4C	EP1PING	EP1 OUT was pinged and it NAK'd		
21	50	EP2PING	EP2 OUT was pinged and it NAK'd		
22	54	EP4PING	EP4 OUT was pinged and it NAK'd		
23	58	EP6PING	EP6 OUT was pinged and it NAK'd		
24	5C	EP8PING	EP8 OUT was pinged and it NAK'd		
25	60	ERRLIMIT	Bus errors exceeded the programmed limit		
26	64	_	-		
27	68	_	Reserved		
28	6C	_	Reserved		
29	70	EP2ISOERR	ISO EP2 OUT PID sequence error		
30	74	EP4ISOERR	ISO EP4 OUT PID sequence error		
31	78	EP6ISOERR	ISO EP6 OUT PID sequence error		
32	7C	EP8ISOERR	ISO EP8 OUT PID sequence error		

If Autovectoring is enabled (AV2EN = 1 in the INTSET-UP register), the FX2LP substitutes its INT2VEC byte. Therefore, if the high byte ("page") of a jump table address is preloaded at the location 0x0044, the automatically inserted INT2VEC byte at 0x0045 directs the jump to the correct address out of the 27 addresses within the page.

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FIFO/GPIF Interrupt (INT4)

Just as the USB Interrupt is shared among 27 individual USB interrupt sources, the FIFO/GPIF interrupt is shared among 14 individual FIFO/GPIF sources. The FIFO/GPIF Interrupt, similar to the USB Interrupt, can employ autovectoring.

Table 4 shows the priority and INT4VEC values for the 14 FIFO/GPIF interrupt sources.

Table 4. Individual FIFO/GPIF Interrupt Sources

Priority	INT4VEC Value	Source	Notes
1	80	EP2PF	Endpoint 2 programmable flag
2	84	EP4PF	Endpoint 4 programmable flag
3	88	EP6PF	Endpoint 6 programmable flag
4	8C	EP8PF	Endpoint 8 programmable flag
5	90	EP2EF	Endpoint 2 empty flag ^[6]
6	94	EP4EF	Endpoint 4 empty flag
7	98	EP6EF	Endpoint 6 empty flag
8	9C	EP8EF	Endpoint 8 empty flag
9	A0	EP2FF	Endpoint 2 full flag
10	A4	EP4FF	Endpoint 4 full flag
11	A8	EP6FF	Endpoint 6 full flag
12	AC	EP8FF	Endpoint 8 full flag
13	В0	GPIFDONE	GPIF operation complete
14	B4	GPIFWF	GPIF waveform

If Autovectoring is enabled (AV4EN = 1 in the INTSET-UP register), the FX 2LP substitutes its INT4VEC byte. Therefore, if the high byte ("page") of a jump-table address is preloaded at location 0x0054, the automatically inserted INT4VEC byte at 0x0055 directs the jump to the correct address out of the 14 addresses within the page. When the ISR occurs, the FX2LP pushes the program counter to its stack then jumps to address 0x0053, where it expects to find a "jump" instruction to the interrupt service routine (ISR).

Note

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^{6.} Errata: In Slave FIFO Asynchronous Word Wide mode, if a single word data is transferred from the USB host to EP2, configured as OUT Endpoint (EP) in the first transaction, then the Empty flag behaves incorrectly. This does not happen if the data size is more than one word in the first transaction. For more information, see the Errata on page 68.



Reset and Wakeup

Reset Pin

The input pin, RESET#, resets the FX2LP when asserted. This pin has hysteresis and is active LOW. When a crystal is used with the CY7C680xxA, the reset period must enable stabilization of the crystal and the PLL. This reset period must be approximately 5 ms after VCC reaches 3.0 V. If the crystal input pin is driven by a clock signal, the internal PLL stabilizes in 200 μs after VCC has reached 3.0 $V^{[7]}$.

Figure 2 shows a power-on reset condition and a reset applied during operation. A power-on reset is defined as the time reset that is asserted while power is being applied to the circuit. A powered reset is when the FX2LP is powered on and operating and the RESET# pin is asserted.

Cypress provides an application note which describes and recommends power-on reset implementation. For more information about reset implementation for the FX2 family of products, visit http://www.cypress.com.

Figure 2. Reset Timing Plots

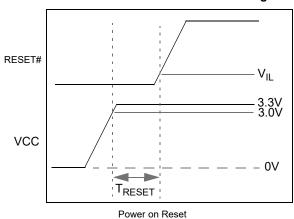
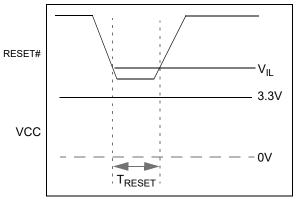


Table 5. Reset Timing Values

Condition	T _{RESET}
Power-on reset with crystal	5 ms
Power-on reset with external clock	200 μs + clock stability time
Powered reset	200 μs



Powered Reset

Wakeup Pins

The 8051 puts itself and the rest of the chip into a power-down mode by setting PCON.0 = 1. This stops the oscillator and PLL. When WAKEUP is asserted by external logic, the oscillator restarts after the PLL stabilizes, and the 8051 receives a wakeup interrupt. This applies irrespective of whether FX2LP is connected to the USB.

The FX2LP exits the power-down (USB suspend) state by using one of the following methods:

- USB bus activity (if D+/D- lines are left floating, noise on these lines may indicate activity to the FX2LP and initiate a wakeup)
- External logic asserts the WAKEUP pin
- External logic asserts the PA3/WU2 pin

The second wakeup pin, WU2, can also be configured as a general-purpose I/O pin. This enables a simple external R-C network to be used as a periodic wakeup source. WAKEUP is by default active LOW.

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Program/Data RAM

Size

The FX2LP has 16 KB of internal program/data RAM, where PSEN#/RD# signals are internally ORed to enable the 8051 to access it as both program and data memory. No USB control registers appears in this space.

Two memory maps are shown in the following diagrams:

Figure 3 shows the Internal Code Memory, EA = 0.

Figure 4 on page 11 shows the External Code Memory, EA = 1.

Internal Code Memory, EA = 0

This mode implements the internal 16 KB block of RAM (starting at 0) as combined code and data memory. When external RAM or ROM is added, the external read and write strobes are

suppressed for memory spaces that exist inside the chip. This enables the user to connect a 64 KB memory without requiring address decodes to keep clear of internal memory spaces.

Only the internal 16 KB and scratch pad 0.5 KB RAM spaces have the following access:

- USB download
- USB upload
- Setup data pointer
- I²C interface boot load

External Code Memory, EA = 1

The bottom 16 KB of program memory is external and therefore the bottom 16 KB of internal RAM is accessible only as a data memory.

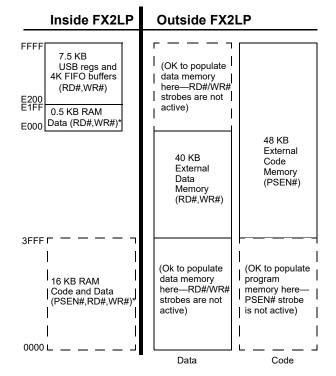


Figure 3. Internal Code Memory, EA = 0

Note

^{*}SUDPTR, USB upload/download, I²C interface boot access

^{7.} If the external clock is powered at the same time as the CY7C680xxA and has a stabilization wait period, it must be added to the 200 μ s.



Inside FX2LP **Outside FX2LP** FFFF 7.5 KB USB regs and 4K FIFO buffers (OK to populate data memory here—RD#/WR# strobes are not (RD#,WR#) E200 E1FF active) 0.5 KB RAM Data (RD#,WR#)* 40 KB External 64 KB Data External Memory (RD#,WR#) Code Memory (PSEN#) 3FFF □ (Ok to populate 16 KB data memory here—RD#/WR# RAM Data (RD#,WR#)* strobes are not active) 0000 Data Code

Figure 4. External Code Memory, EA = 1

*SUDPTR, USB upload/download, I²C interface boot access

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Register Addresses

FFFF	4 KB EP2-EP8 buffers (8 x 512)
F000 EFFF	
EFFF E800	2 KB RESERVED
E7FF E7C0	64 BEP1IN
E7BF E780	64 Bytes EP1OUT
E77F E740	64 Bytes EP0 IN/OUT
E73F E700	64 Bytes RESERVED
E6FF E500	8051 Addressable Registers (512)
E4FF E480	Reserved (128)
E47F E400	128 Bytes GPIF Waveforms
E3FF E200	Reserved (512)
E1FF	512 Bytes
E000	8051 xdata RAM

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Endpoint RAM

Size

■ 3 × 64 bytes (Endpoints 0 and 1)

■ 8 × 512 bytes (Endpoints 2, 4, 6, 8)

Organization

- EP0
- Bidirectional endpoint zero, 64-byte buffer
- EP1IN, EP1OUT
- 64 byte buffers, bulk or interrupt
- EP2, 4, 6, 8
- Eight 512-byte buffers, bulk, interrupt, or isochronous. EP4 and EP8 can be double buffered; EP2 and 6 can be either double, triple, or quad buffered. For Hi-Speed endpoint configuration options, see Figure 5.

Setup Data Buffer

A separate 8-byte buffer at 0xE6B8-0xE6BF holds the setup data from a CONTROL transfer.

Endpoint Configurations (Hi-Speed Mode)

Endpoints 0 and 1 are the same for every configuration. Endpoint 0 is the only CONTROL endpoint, and endpoint 1 can be either BULK or INTERRUPT.

The endpoint buffers can be configured in any 1 of the 12 configurations shown in the vertical columns. When operating in the Full-Speed BULK mode, only the first 64 bytes of each buffer are used. For example, in Hi-Speed mode, the max packet size is 512 bytes, but in Full-Speed mode, it is 64 bytes. Even though a buffer is configured to a 512-byte buffer, in Full-Speed mode, only the first 64 bytes are used. The unused endpoint buffer space is not available for other operations. An example endpoint configuration is the EP2–1024 double-buffered; EP6–512 quad-buffered (column 8).

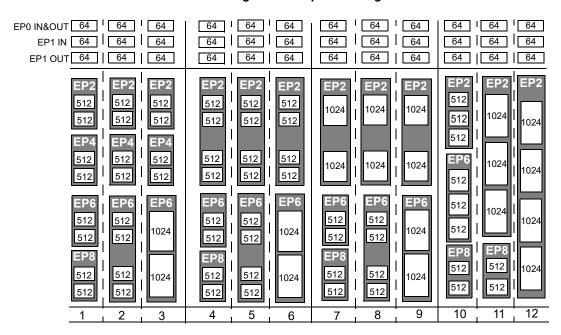


Figure 5. Endpoint Configuration



Default Full-Speed Alternate Settings

Table 6. Default Full Speed Alternate Settings [8, 9]

Alternate Setting	0	1	2	3
ep0	64	64	64	64
ep1out	0	64 bulk	64 int	64 int
ep1in	0	64 bulk	64 int	64 int
ep2	0	64 bulk out (2×)	64 int out (2×)	64 iso out (2×)
ep4	0	64 bulk out (2×)	64 bulk out (2×)	64 bulk out (2×)
ер6	0	64 bulk in (2×)	64 int in (2×)	64 iso in (2×)
ep8	0	64 bulk in (2×)	64 bulk in (2×)	64 bulk in (2×)

Default High Speed Alternate Settings

Table 7. Default Hi-Speed Alternate Settings^[8, 9]

Alternate Setting	0	1	2	3
ep0	64	64	64	64
ep1out	0	512 bulk ^[10]	64 int	64 int
ep1in	0	512 bulk ^[10]	64 int	64 int
ep2	0	512 bulk out (2×)	512 int out (2×)	512 iso out (2×)
ep4	0	512 bulk out (2×)	512 bulk out (2×)	512 bulk out (2×)
ер6	0	512 bulk in (2×)	512 int in (2×)	512 iso in (2×)
ер8	0	512 bulk in (2×)	512 bulk in (2×)	512 bulk in (2×)

Notes
8. "0" means "not implemented."
9. "2×" means "double buffered."

^{10.} Even though these buffers are 64 bytes, they are reported as 512 for USB 2.0 compliance. The user must never transfer packets larger than 64 bytes to EP1.



External FIFO Interface

Architecture

The FX2LP slave FIFO architecture has eight 512-byte blocks in the endpoint RAM that directly serve as FIFO memories and are controlled by FIFO control signals (such as IFCLK, SLCS#, SLRD, SLWR, SLOE, PKTEND, and flags).

In operation, some of the eight RAM blocks fill or empty from the SIE, while the others are connected to the I/O transfer logic. The transfer logic takes two forms: the GPIF for internally generated control signals and the slave FIFO interface for externally controlled transfers.

Master/Slave Control Signals

The FX2LP endpoint FIFOs are implemented as eight physically distinct 256×16 RAM blocks. The 8051/SIE can switch any of the RAM blocks between two domains, the USB (SIE) domain and the 8051-I/O Unit domain. This switching is done virtually instantaneously, giving essentially zero transfer time between "USB FIFOs" and "Slave FIFOs." Because they are physically the same memory, no bytes are actually transferred between buffers.

At any time, some RAM blocks are filling/emptying with the USB data under SIE control, while other RAM blocks are available to the 8051, the I/O control unit, or both. The RAM blocks operates as single-port in the USB domain, and dual-port in the 8051-I/O domain. The blocks can be configured as single-, double-, triple-, or quad-buffered as previously shown.

The I/O control unit implements either an internal master (M for Master) or external master (S for Slave) interface.

In Master (M) mode, the GPIF internally controls FIFOADR[1..0] to select a FIFO. The RDY pins (two in the 56-pin package, six in the 100-pin and 128-pin packages) can be used as flag inputs from an external FIFO or other logic if desired. The GPIF can be run from either an internally derived clock or externally supplied clock (IFCLK), at a rate that transfers data up to 96 MBytes/s (48 Hz IFCLK with 16-bit interface).

In the Slave (S) mode, FX2LP accepts either an internally derived clock or externally supplied clock (IFCLK, max frequency 48 MHz) and SLCS#, SLRD, SLWR, SLOE, PKTEND signals from external logic. When using an external IFCLK, the external clock must be present before switching to the external clock with the IFCLKSRC bit. Each endpoint can individually be selected for byte or word operation by an internal configuration bit and a Slave FIFO Output Enable signal (SLOE) that enables data of the selected width. External logic must ensure that the output enable signal is inactive when writing data to a slave FIFO. The slave interface can also operate asynchronously, where the SLRD and SLWR signals act directly as strobes, rather than a clock qualifier as in synchronous mode. The signals SLRD, SLWR, SLOE, and PKTEND are gated by the signal SLCS#.

GPIF and FIFO Clock Rates

An 8051 register bit selects one of two frequencies for the internally supplied interface clock: 30 MHz and 48 MHz.

Alternatively, an externally supplied clock of 5 MHz–48 MHz feeding the IFCLK pin can be used as the interface clock. IFCLK can be configured to function as an output clock when the GPIF and FIFOs are internally clocked. An output enable bit in the IFCONFIG register turns this clock output off, if desired. Another bit within the IFCONFIG register inverts the IFCLK signal whether internally or externally sourced.

GPIF

The GPIF is a flexible 8-bit or 16-bit parallel interface driven by a user-programmable finite state machine. It enables the CY7C68013A/15A to perform local bus mastering and can implement a wide variety of protocols such as ATA interface, printer parallel port, and Utopia.

The GPIF has six programmable control outputs (CTL), nine address outputs (GPIFADRx), and six general-purpose ready inputs (RDY). The data bus width can be 8 or 16 bits. Each GPIF vector defines the state of the control outputs, and determines what state a ready input (or multiple inputs) must be before proceeding. The GPIF vector can be programmed to advance a FIFO to the next data value, advance an address, etc. A sequence of the GPIF vectors make up a single waveform that is executed to perform the desired data move between the FX2LP and the external device.

Six Control OUT Signals

The 100-pin and 128-pin packages bring out all six Control Output pins (CTL0-CTL5). The 8051 programs the GPIF unit to define the CTL waveforms. The 56-pin package brings out three of these signals, CTL0-CTL2. CTLx waveform edges can be programmed to make transitions as fast as once per clock (20.8 ns using a 48-MHz clock).

Six Ready IN Signals

The 100-pin and 128-pin packages bring out all six Ready inputs (RDY0–RDY5). The 8051 programs the GPIF unit to test the RDY pins for GPIF branching. The 56-pin package brings out two of these signals, RDY0–1.

Nine GPIF Address OUT Signals

Nine GPIF address lines are available in the 100-pin and 128-pin packages, GPIFADR[8..0]. The GPIF address lines enable indexing through up to a 512-byte block of RAM. If more address lines are needed, then I/O port pins are used.

Long Transfer Mode

In the master mode, the 8051 appropriately sets GPIF transaction count registers (GPIFTCB3, GPIFTCB2, GPIFTCB1, or GPIFTCB0) for unattended transfers of up to 2^{32} transactions. The GPIF automatically throttles data flow to prevent under or overflow until the full number of requested transactions complete. The GPIF decrements the value in these registers to represent the current status of the transaction.

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ECC Generation

The EZ-USB can calculate ECCs (Error Correcting Codes)^[11] on data that passes across its GPIF or Slave FIFO interfaces. There are two ECC configurations: Two ECCs, each calculated over 256 bytes (SmartMedia Standard); and one ECC calculated over 512 bytes.

The ECC can correct any one-bit error or detect any two-bit error.

ECC Implementation

The two ECC configurations are selected by the ECCM bit:

ECCM = 0

Two 3-byte ECCs, each calculated over a 256-byte block of data. This configuration conforms to the SmartMedia Standard.

Write any value to ECCRESET, then pass data across the GPIF or Slave FIFO interface. The ECC for the first 256 bytes of data is calculated and stored in ECC1. The ECC for the next 256 bytes is stored in ECC2. After the second ECC is calculated, the values in the ECCx registers do not change until ECCRESET is written again, even if more data is subsequently passed across the interface.

ECCM = 1

One 3-byte ECC calculated over a 512-byte block of data.

Write any value to ECCRESET then pass data across the GPIF or Slave FIFO interface. The ECC for the first 512 bytes of data is calculated and stored in ECC1; ECC2 is unused. After the ECC is calculated, the values in ECC1 do not change even if more data is subsequently passed across the interface, till ECCRESET is written again.

USB Uploads and Downloads

The core has the ability to directly edit the data contents of the internal 16-KB RAM and of the internal 512-byte scratch pad RAM via a vendor-specific command. This capability is normally used when soft downloading the user code and is available only to and from the internal RAM, only when the 8051 is held in reset. The available RAM spaces are 16 KB from 0x0000–0x3FFF (code/data) and 512 bytes from 0xE000–0xE1FF (scratch pad data RAM)[12].

Autopointer Access

FX2LP provides two identical autopointers. They are similar to the internal 8051 data pointers but with an additional feature: they can optionally increment after every memory access. This capability is available to and from both internal and external RAM. Autopointers are available in external FX2LP registers

under the control of a mode bit (AUTOPTRSET-UP.0). Using the external FX2LP autopointer access (at 0xE67B–0xE67C) enables the autopointer to access all internal and external RAM to the part.

Also, autopointers can point to any FX2LP register or endpoint buffer space. When the autopointer access to external memory is enabled, locations 0xE67B and 0xE67C in XDATA and code space cannot be used.

I²C Controller

FX2LP has one I²C port that is driven by two internal controllers, the one that automatically operates at boot time to load VID/PID/DID and configuration information, and another that the 8051 uses when running to control external I²C devices. The I²C port operates in master mode only.

²C Port Pins

The I^2C pins SCL and SDA must have external 2.2-k Ω pull-up resistors even if no EEPROM is connected to the FX2LP. External EEPROM device address pins must be configured properly. See Table 8 for configuring the device address pins.

Table 8. Strap Boot EEPROM Address Lines to These Values

Bytes	Example EEPROM	A2	A1	A0
16	24LC00 ^[13]	N/A	N/A	N/A
128	24LC01	0	0	0
256	24LC02	0	0	0
4K	24LC32	0	0	1
8K	24LC64	0	0	1
16K	24LC128	0	0	1

²C Interface Boot Load Access

At power-on reset, the I²C interface boot loader loads the VID/PID/DID configuration bytes and up to 16 KB of program/data. The available RAM spaces are 16 KB from 0x0000–0x3FFF and 512 bytes from 0xE000–0xE1FF. The 8051 is in reset. I²C interface boot loads only occur after power-on reset.

PC Interface General-Purpose Access

The 8051 can control peripherals connected to the I²C bus using the I2CTL and I2DAT registers. FX2LP provides I²C master control only; it is never an I²C slave.

Notes

- 11. To use the ECC logic, the GPIF or Slave FIFO interface must be configured for byte-wide operation.
- 12. After the data is downloaded from the host, a "loader" can execute from internal RAM to transfer downloaded data to external memory.

13. This EEPROM does not have address pins.



Compatible with Previous Generation EZ-USB FX2

The EZ-USB FX2LP is form-, fit-, and with minor exceptions, functionally-compatible with its predecessor, the EZ-USB FX2. This makes for an easy transition for designers wanting to upgrade their systems from the FX2 to the FX2LP. The pinout and package selection are identical and a vast majority of firmware previously developed for the FX2 functions in the FX2LP.

For designers migrating from the FX2 to the FX2LP, a change in the bill of material and review of the memory allocation (due to increased internal memory) is required. For more information about migrating from EZ-USB FX2 to EZ-USB FX2LP, see the application note titled *Migrating from EZ-USB FX2 to EZ-USB FX2LP* available in the Cypress web site.

Table 9. Part Number Conversion Table

EZ-USB FX2 Part Number	EZ-USB FX2LP Part Number	Package Description
CY7C68013-56PVC	CY7C68013A-56PVXC or CY7C68014A-56PVXC	56-pin SSOP
CY7C68013-56PVCT	CY7C68013A-56PVXCT or CY7C68014A-56PVXCT	56-pin SSOP – Tape and Reel
CY7C68013-56LFC	CY7C68013A-56LFXC or CY7C68014A-56LFXC	56-pin QFN
CY7C68013-100AC	CY7C68013A-100AXC or CY7C68014A-100AXC	100-pin TQFP
CY7C68013-128AC	CY7C68013A-128AXC or CY7C68014A-128AXC	128-pin TQFP

CY7C68013A/14A and CY7C68015A/16A Differences

CY7C68013A is identical to CY7C68014A in form, fit, and functionality. CY7C68015A is identical to CY7C68016A in form, fit, and functionality. CY7C68014A and CY7C68016A have a lower suspend current than CY7C68013A and CY7C68015A respectively and are ideal for power-sensitive battery applications.

CY7C68015A and CY7C68016A are available in 56-pin QFN package only. Two additional GPIO signals are available on the CY7C68015A and CY7C68016A to provide more flexibility when neither IFCLK or CLKOUT are needed in the 56-pin package.

USB developers wanting to convert their FX2 56-pin application to a bus-powered system directly benefit from these additional signals. The two GPIOs give developers the signals they need for the power-control circuitry of their bus-powered application without pushing them to a high-pincount version of FX2LP.

The CY7C68015A is only available in the 56-pin QFN package

Table 10. CY7C68013A/14A and CY7C68015A/16A Pin Differences

CY7C68013A/CY7C68014A	CY7C68015A/CY7C68016A
IFCLK	PE0
CLKOUT	PE1

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Pin Assignments

Figure 6 on page 19 identifies all signals for the five package types. The following pages illustrate the individual pin diagrams, plus a combination diagram showing which of the full set of signals are available in the 128-pin, 100-pin, and 56-pin packages.

The signals on the left edge of the 56-pin package in Figure 6 on page 19 are common to all versions in the FX2LP family with the noted differences between the CY7C68013A/14A and the CY7C68015A/16A.

Three modes are available in all package versions: Port, GPIF master, and Slave FIFO. These modes define the signals on the right edge of the diagram. The 8051 selects the interface mode using the IFCONFIG[1:0] register bits. Port mode is the power on default configuration.

The 100-pin package adds functionality to the 56-pin package by adding these pins:

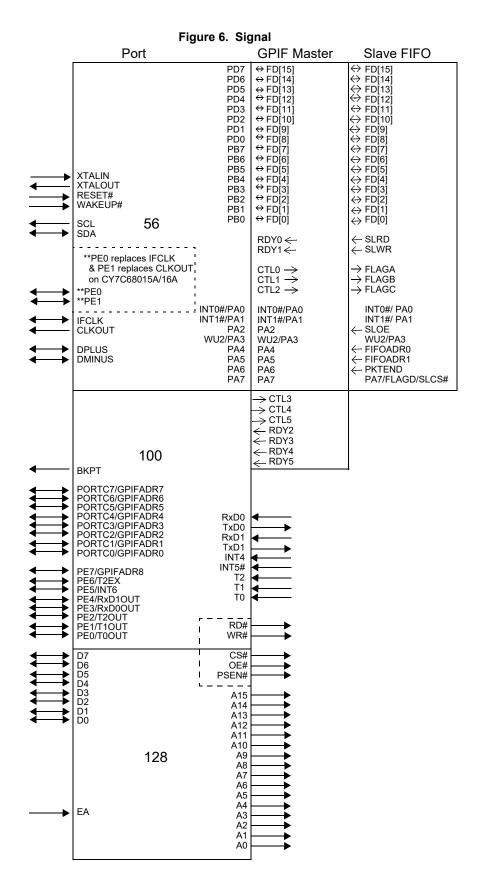
- PORTC or alternate GPIFADR[7:0] address signals
- PORTE or alternate GPIFADR[8] address signal and seven additional 8051 signals
- Three GPIF Control signals
- Four GPIF Ready signals
- Nine 8051 signals (two USARTs, three timer inputs, INT4, and INT5#)
- BKPT, RD#, WR#.

The 128-pin package adds the 8051 address and data buses plus control signals. Note that two of the required signals, RD# and WR#, are present in the 100-pin version.

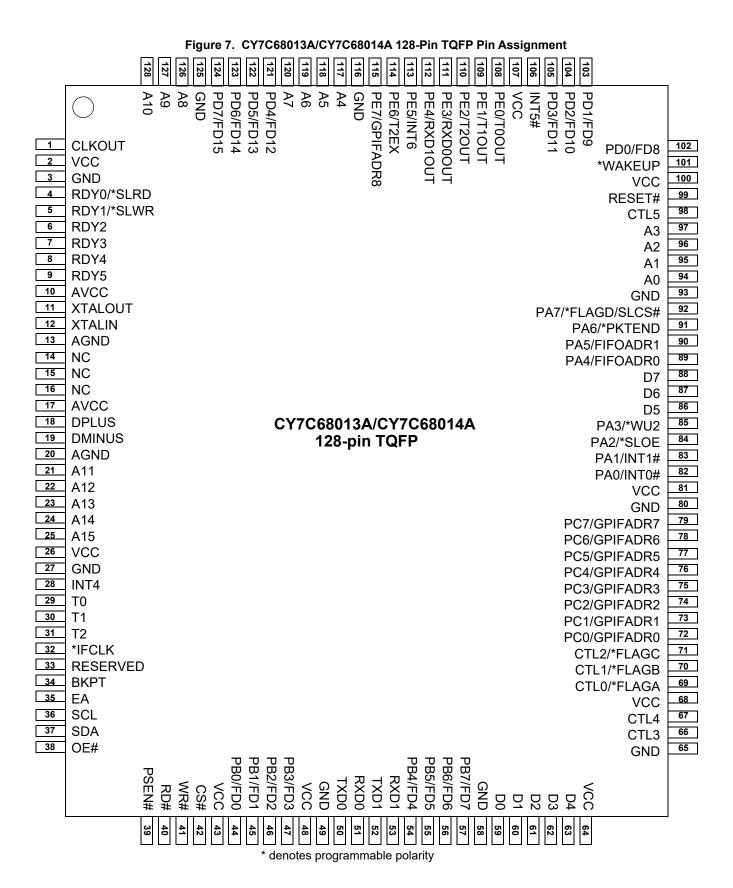
In the 100-pin and 128-pin versions, an 8051 control bit can be set to pulse the RD# and WR# pins when the 8051 reads from/writes to PORTC. This feature is enabled by setting the PORTCSTB bit in the CPUCS register.

PORTC Strobe Feature Timings on page 46 displays the timing diagram of the read and write strobing function on accessing PORTC.

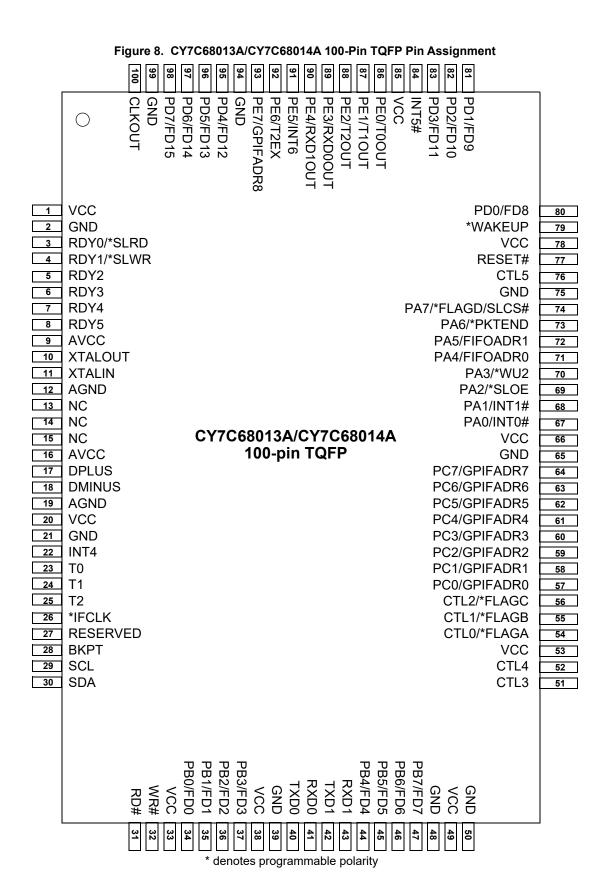












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Figure 9. CY7C68013A/CY7C68014A 56-Pin SSOP Pin Assignment

CY7C68013A/CY7C68014A 56-pin SSOP

	\cap		1
1	PD5/FD13	PD4/FD12	56
2	PD6/FD14	PD3/FD11	55
3	PD7/FD15	PD2/FD10	54
4	GND	PD1/FD9	53
5	CLKOUT	PD0/FD8	52
6	VCC	*WAKEUP	51
7	GND	VCC	50
8	RDY0/*SLRD	RESET#	49
9	RDY1/*SLWR	GND	48
10	AVCC	PA7/*FLAGD/SLCS#	47
11	XTALOUT	PA6/PKTEND	46
12	XTALIN	PA5/FIFOADR1	45
13	AGND	PA4/FIFOADR0	44
14	AVCC	PA3/*WU2	43
15	DPLUS	PA2/*SLOE	42
16	DMINUS	PA1/INT1#	41
17	AGND	PA0/INT0#	40
18	VCC	VCC	39
19	GND	CTL2/*FLAGC	38
20	*IFCLK	CTL1/*FLAGB	37
21	RESERVED	CTL0/*FLAGA	36
22	SCL	GND	35
23	SDA	VCC	34
24	VCC	GND	33
25	PB0/FD0	PB7/FD7	32
26	PB1/FD1	PB6/FD6	31
27	PB2/FD2	PB5/FD5	30
28	PB3/FD3	PB4/FD4	29

^{*} denotes programmable polarity

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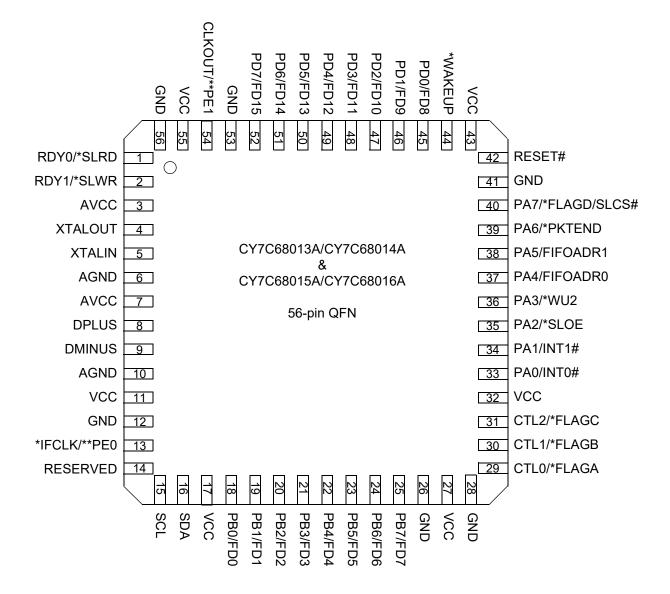


Figure 10. CY7C68013A/14A/15A/16A 56-Pin QFN Pin Assignment

* denotes programmable polarity
** denotes CY7C68015A/CY7C68016A pinout

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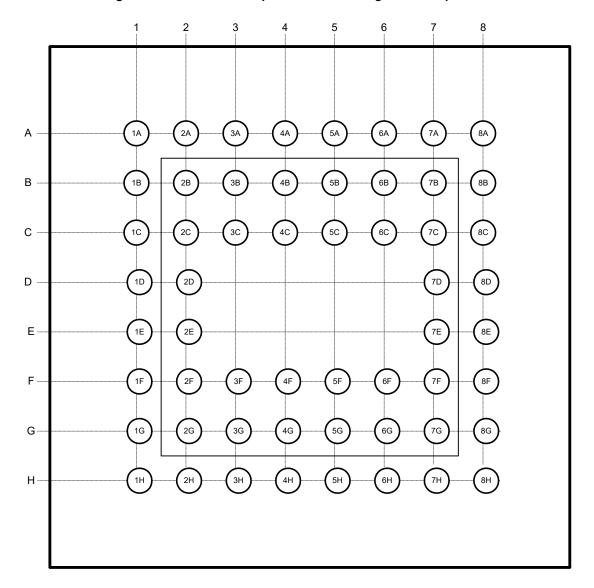


Figure 11. CY7C68013A 56-pin VFBGA Pin Assignment - Top View



CY7C68013A/15A Pin Descriptions

Table 11. FX2LP Pin Descriptions^[14]

128 TQFP	100 TQFP	56 SSOP	56 QFN	56 VFBGA	Name	Туре	Default	Reset ^[15]	Description					
10	9	10	3	2D	AVCC	Power	N/A	N/A	Analog VCC . Connect this pin to the 3.3 V power source. This signal provides power to the analog section of the chip.					
17	16	14	7	1D	AVCC	Power	N/A	N/A	Analog VCC . Connect this pin to the 3.3 V pow source. This signal provides power to the analog section of the chip.					
13	12	13	6	2F	AGND	Ground	N/A	N/A	Analog Ground . Connect to ground with as short a path as possible.					
20	19	17	10	1F	AGND	Ground	N/A	N/A	Analog Ground . Connect to ground with as short a path as possible.					
19	18	16	9	1E	DMINUS	I/O/Z	Z	N/A	USB D- Signal. Connect to the USB D- signal.					
18	17	15	8	2E	DPLUS	I/O/Z	Z	N/A	USB D+ Signal. Connect to the USB D+ signal.					
94	_	_	_	_	A0	Output	L	L						
95	_	_	_	_	A1	Output	L	L						
96	_	_	_	_	A2	Output	L	L						
97	_	_	_	_	A3	Output	L	L						
117	_	_	_	_	A4	Output	L	L						
118	_	_	_	_	A5	Output	L	L						
119	_	_	_	_	A6	Output	L	L						
120	_	_	_	_	A7	Output	L	L	8051 Address Bus. This bus is driven at all times.					
126	_	_	_	_	A8	Output	L	L	When the 8051 is addressing internal RAM it reflects the internal address.					
127	_	_	_	_	A9	Output	L	L						
128	_	_	_	_	A10	Output	L	L						
21	_	_	_	_	A11	Output	L	L						
22	_	_	_	_	A12	Output	L	L						
23	_	_	_	_	A13	Output	L	L						
24	_	_	_	_	A14	Output	L	L						
25	_	_	_	_	A15	Output	L	L						
59	_	_	_	_	D0	I/O/Z	Z	Z						
60	_	_	_	_	D1	I/O/Z	Z	Z						
61	_	_	_	_	D2	I/O/Z	Z	Z	8051 Data Bus . This bidirectional bus is high impedance when inactive, input for bus reads,					
62	_	_	_	_	D3	I/O/Z	Z	Z	and output for bus writes. The data bus is used for					
63	_	_	_	_	D4	I/O/Z	Z	Z	external 8051 program and data memory. The data					
86	-	-	-	_	D5	I/O/Z	Z	Z	bus is active only for external bus accesses, and is driven LOW in suspend.					
87	_	_	_	_	D6	I/O/Z	Z	Z						
88	_	_	_	_	D7	I/O/Z	Z	Z						
39	_	_	_	_	PSEN#	Output	Н	Н	Program Store Enable. This active LOW signal indicates an 8051 code fetch from external memory. It is active for program memory fetche from 0x4000–0xFFFF when the EA pin is LOW, from 0x0000–0xFFFF when the EA pin is HIGH					

Notes

14. Unused inputs must not be left floating. Tie either HIGH or LOW as appropriate. Outputs should only be pulled up or down to ensure signals at power up and in standby. Note also that no pins should be driven while the device is powered down.

15. The Reset column indicates the state of signals during reset (RESET# asserted) or during Power on Reset (POR).

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Table 11. FX2LP Pin Descriptions^[14] (continued)

			D 000.	- Puono	- (continueu)						
128 TQFP	100 TQFP	56 SSOP	56 QFN	56 VFBGA	Name	Type	Default	Reset ^[15]	Description		
34	28	ı	ı		ВКРТ	Output	L	L	Breakpoint. This pin goes active (HIGH) when the 8051 address bus matches the BPADDRH/L registers and breakpoints are enabled in the BREAKPT register (BPEN = 1). If the BPPULSE bit in the BREAKPT register is HIGH, this signal pulses HIGH for eight 12-/24-/48-MHz clocks. If the BPPULSE bit is LOW, the signal remains HIGH until the 8051 clears the BREAK bit (by writing 1 to it) in the BREAKPT register.		
99	77	49	42	8B	RESET#	Input	N/A	N/A	Active LOW Reset. Resets the entire chip. See section "Reset and Wakeup" on page 9 for more details.		
35	ı	1	ı	ı	EA	Input	N/A	N/A	External Access . This pin determines where the 8051 fetches code between addresses 0x0000 and 0x3FFF. If EA = 0 the 8051 fetches this code from its internal RAM. IF EA = 1 the 8051 fetches this code from external memory.		
12	11	12	5	1C	XTALIN	Input	N/A	N/A	Crystal Input. Connect this signal to a 24-MHz parallel-resonant, fundamental mode crystal and load capacitor to GND. It is also correct to drive XTALIN with an external 24-MHz square wave derived from another clock source. When driving from an external source, the driving signal should be a 3.3-V square wave.		
11	10	11	4	2C	XTALOUT	Output	N/A	N/A	Crystal Output. Connect this signal to a 24-MHz parallel-resonant, fundamental mode crystal and load capacitor to GND. If an external clock is used to drive XTALIN, leave this pin open.		
1	100	5	54	2B	CLKOUT on CY7C68013A and CY7C68014A	O/Z	12 MHz	Clock Driven	CLKOUT: 12-, 24- or 48-MHz clock, phase-locked to the 24-MHz input clock. The 8051 defaults to 12-MHz operation. The 8051 may three-state this output by setting CPUCS.1 = 1.		
					PE1 on CY7C68015A and CY7C68016A	- I/O/Z	I	Z	PE1 is a bidirectional I/O port pin.		
Port A	A										
82	67	40	33	8G	PA0 or INT0#	I/O/Z	I (PA0)	Z (PA0)	Multiplexed pin whose function is selected by PORTACFG.0 PA0 is a bidirectional I/O port pin. INT0# is the active-LOW 8051 INT0 interrupt input signal, which is either edge-triggered (IT0 = 1) or level-triggered (IT0 = 0).		
83	68	41	34	6G	PA1 or INT1#	I/O/Z	I (PA1)	Z (PA1)	Multiplexed pin whose function is selected by: PORTACFG.1 PA1 is a bidirectional I/O port pin. INT1# is the active-LOW 8051 INT1 interrupt input signal, which is either edge-triggered (IT1 = 1) or level-triggered (IT1 = 0).		



Table 11. FX2LP Pin Descriptions^[14] (continued)

128	100	56	56	56	Name	Туре	Default	Reset ^[15]	Description			
TQFP	TQFP	SSOP	QFN	VFBGA	INAIIIE	Type	Delault	1/626fr.ol	·			
84	69	42	35	8F	PA2 or SLOE	I/O/Z	I (PA2)	Z (PA2)	Multiplexed pin whose function is selected by two bits: IFCONFIG[1:0]. PA2 is a bidirectional I/O port pin. SLOE is an input-only output enable with programmable polarity (FIFOPINPOLAR.4) for the slave FIFOs connected to FD[70] or FD[150].			
85	70	43	36	7F	PA3 or WU2	I/O/Z	I (PA3)	Z (PA3)	Multiplexed pin whose function is selected by: WAKEUP.7 and OEA.3 PA3 is a bidirectional I/O port pin. WU2 is an alternate source for USB Wakeup, enabled by WU2EN bit (WAKEUP.1) and polarity set by WU2POL (WAKEUP.4). If the 8051 is in suspend and WU2EN = 1, a transition on this pin starts up the oscillator and interrupts the 8051 to enable it to exit the suspend mode. Asserting this pin inhibits the chip from suspending if WU2EN = 1.			
89	71	44	37	6F	PA4 or FIFOADR0	I/O/Z	I (PA4)	Z (PA4)	Multiplexed pin whose function is selected by: IFCONFIG[10]. PA4 is a bidirectional I/O port pin. FIFOADR0 is an input-only address select for the slave FIFOs connected to FD[70] or FD[150].			
90	72	45	38	8C	PA5 or FIFOADR1	I/O/Z	I (PA5)	Z (PA5)	Multiplexed pin whose function is selected by: IFCONFIG[10]. PA5 is a bidirectional I/O port pin. FIFOADR1 is an input-only address select for the slave FIFOs connected to FD[70] or FD[150].			
91	73	46	39	7C	PA6 or PKTEND	I/O/Z	I (PA6)	Z (PA6)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] bits. PA6 is a bidirectional I/O port pin. PKTEND is an input used to commit the FIFO packet data to the endpoint and whose polarity is programmable via FIFOPINPOLAR.5.			
92	74	47	40	6C	PA7 or FLAGD or SLCS#	I/O/Z	I (PA7)	Z (PA7)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and PORTACFG.7 bits. PA7 is a bidirectional I/O port pin. FLAGD is a programmable slave-FIFO output status flag signal. SLCS# gates all other slave FIFO enable/strobes			
Port	В			<u> </u>			1	·				
44	34	25	18	3H	PB0 or FD[0]	I/O/Z	(PB0)	Z (PB0)	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. PB0 is a bidirectional I/O port pin. FD[0] is the bidirectional FIFO/GPIF data bus.			
45	35	26	19	4F	PB1 or FD[1]	I/O/Z	I (PB1)	Z (PB1)	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. PB1 is a bidirectional I/O port pin. FD[1] is the bidirectional FIFO/GPIF data bus.			
46	36	27	20	4H	PB2 or FD[2]	I/O/Z	I (PB2)	Z (PB2)	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. PB2 is a bidirectional I/O port pin. FD[2] is the bidirectional FIFO/GPIF data bus.			



Table 11. FX2LP Pin Descriptions^[14] (continued)

128	100	56	56	56			Page #[15]	Description			
TQFP	TQFP	SSOP		VFBGA	Name	туре	Detauit	Reset	·		
47	37	28	21	4G	PB3 or FD[3]	I/O/Z	I (PB3)	Z (PB3)	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. PB3 is a bidirectional I/O port pin. FD[3] is the bidirectional FIFO/GPIF data bus.		
54	44	29	22	5H	PB4 or FD[4]	I/O/Z	I (PB4)	Z (PB4)	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. PB4 is a bidirectional I/O port pin. FD[4] is the bidirectional FIFO/GPIF data bus.		
55	45	30	23	5G	PB5 or FD[5]	I/O/Z	I (PB5)	Z (PB5)	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. PB5 is a bidirectional I/O port pin. FD[5] is the bidirectional FIFO/GPIF data bus.		
56	46	31	24	5F	PB6 or FD[6]	I/O/Z	I (PB6)	Z (PB6)	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. PB6 is a bidirectional I/O port pin. FD[6] is the bidirectional FIFO/GPIF data bus.		
57	47	32	25	6H	PB7 or FD[7]	I/O/Z	I (PB7)	Z (PB7)	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. PB7 is a bidirectional I/O port pin. FD[7] is the bidirectional FIFO/GPIF data bus.		
PORT	ГС										
72	57	-	-	-	PC0 or GPIFADR0	I/O/Z	I (PC0)	Z (PC0)	Multiplexed pin whose function is selected by PORTCCFG.0 PC0 is a bidirectional I/O port pin. GPIFADR0 is a GPIF address output pin.		
73	58	1	-	-	PC1 or GPIFADR1	I/O/Z	I (PC1)	Z (PC1)	Multiplexed pin whose function is selected by PORTCCFG.1 PC1 is a bidirectional I/O port pin. GPIFADR1 is a GPIF address output pin.		
74	59	-	-	-	PC2 or GPIFADR2	I/O/Z	I (PC2)	Z (PC2)	Multiplexed pin whose function is selected by PORTCCFG.2 PC2 is a bidirectional I/O port pin. GPIFADR2 is a GPIF address output pin.		
75	60	-	_	_	PC3 or GPIFADR3	I/O/Z	I (PC3)	Z (PC3)	Multiplexed pin whose function is selected by PORTCCFG.3 PC3 is a bidirectional I/O port pin. GPIFADR3 is a GPIF address output pin.		
76	61	ı	ı	-	PC4 or GPIFADR4	I/O/Z	I (PC4)	Z (PC4)	Multiplexed pin whose function is selected by PORTCCFG.4 PC4 is a bidirectional I/O port pin. GPIFADR4 is a GPIF address output pin.		
77	62	-	_	_	PC5 or GPIFADR5	I/O/Z	I (PC5)	Z (PC5)	Multiplexed pin whose function is selected by PORTCCFG.5 PC5 is a bidirectional I/O port pin. GPIFADR5 is a GPIF address output pin.		
78	63	-	-	-	PC6 or GPIFADR6	I/O/Z	I (PC6)	Z (PC6)	Multiplexed pin whose function is selected by PORTCCFG.6 PC6 is a bidirectional I/O port pin. GPIFADR6 is a GPIF address output pin.		
79	64	-	-	-	PC7 or GPIFADR7	I/O/Z	I (PC7)	Z (PC7)	Multiplexed pin whose function is selected by PORTCCFG.7 PC7 is a bidirectional I/O port pin. GPIFADR7 is a GPIF address output pin.		

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Table 11. FX2LP Pin Descriptions^[14] (continued)

				-	(continued)		1					
128 TQFP	100 TQFP	56 SSOP	56 QFN	56 VFBGA	Name	Type	Default	Reset ^[15]	Description			
POR	ΓD											
102	80	52	45	8A	PD0 or FD[8]	I/O/Z	I (PD0)	Z (PD0)	Multiplexed pin whose function is selected by the IFCONFIG[10] and EPxFIFOCFG.0 (wordwide) bits. FD[8] is the bidirectional FIFO/GPIF data bus.			
103	81	53	46	7A	PD1 or FD[9]	I/O/Z	I (PD1)	Z (PD1)	Multiplexed pin whose function is selected by the IFCONFIG[10] and EPxFIFOCFG.0 (wordwide) bits. FD[9] is the bidirectional FIFO/GPIF data bus.			
104	82	54	47	6B	PD2 or FD[10]	I/O/Z	I (PD2)	Z (PD2)	Multiplexed pin whose function is selected by the IFCONFIG[10] and EPxFIFOCFG.0 (wordwide) bits. FD[10] is the bidirectional FIFO/GPIF data bus.			
105	83	55	48	6A	PD3 or FD[11]	I/O/Z	I (PD3)	Z (PD3)	Multiplexed pin whose function is selected by the IFCONFIG[10] and EPxFIFOCFG.0 (wordwide) bits. FD[11] is the bidirectional FIFO/GPIF data bus.			
121	95	56	49	3B	PD4 or FD[12]	I/O/Z	I (PD4)	Z (PD4)	Multiplexed pin whose function is selected by the IFCONFIG[10] and EPxFIFOCFG.0 (wordwide) bits. FD[12] is the bidirectional FIFO/GPIF data bus.			
122	96	1	50	3A	PD5 or FD[13]	I/O/Z	I (PD5)	Z (PD5)	Multiplexed pin whose function is selected by the IFCONFIG[10] and EPxFIFOCFG.0 (wordwide) bits. FD[13] is the bidirectional FIFO/GPIF data bus.			
123	97	2	51	3C	PD6 or FD[14]	I/O/Z	I (PD6)	Z (PD6)	Multiplexed pin whose function is selected by the IFCONFIG[10] and EPxFIFOCFG.0 (wordwide) bits. FD[14] is the bidirectional FIFO/GPIF data bus.			
124	98	3	52	2A	PD7 or FD[15]	I/O/Z	I (PD7)	Z (PD7)	Multiplexed pin whose function is selected by the IFCONFIG[10] and EPxFIFOCFG.0 (wordwide) bits. FD[15] is the bidirectional FIFO/GPIF data bus.			
Port	E											
108	86	-	_	-	PE0 or T0OUT	I/O/Z	I (PE0)	Z (PE0)	Multiplexed pin whose function is selected by the PORTECFG.0 bit. PE0 is a bidirectional I/O port pin. T0OUT is an active-HIGH signal from 8051 Timer-counter0. T0OUT outputs a high level for one CLKOUT clock cycle when Timer0 overflows. If Timer0 is operated in Mode 3 (two separate timer/counters), T0OUT is active when the low byte timer/counter overflows.			
109	87	_	_	-	PE1 or T1OUT	I/O/Z	I (PE1)	Z (PE1)	Multiplexed pin whose function is selected by the PORTECFG.1 bit. PE1 is a bidirectional I/O port pin. T10UT is an active HIGH signal from 8051 Timer-counter1. T10UT outputs a high level for one CLKOUT clock cycle when Timer1 overflows. If Timer1 is operated in Mode 3 (two separate timer/counters), T10UT is active when the low byte timer/counter overflows.			



Table 11. FX2LP Pin Descriptions^[14] (continued)

128 TQFP	100 TQFP	56 SSOP	56 QFN	56 VFBGA	Name	Type	Default	Reset ^[15]	Description				
110	88	-	-	ı	PE2 or T2OUT	I/O/Z	l (PE2)	Z (PE2)	Multiplexed pin whose function is selected by the PORTECFG.2 bit. PE2 is a bidirectional I/O port pin. T2OUT is the active HIGH output signal from 8051 Timer2. T2OUT is active (HIGH) for one clock cycle when Timer/Counter 2 overflows.				
111	89	ı	ı	-	PE3 or RXD0OUT	I/O/Z	l (PE3)	Z (PE3)	Multiplexed pin whose function is selected by PORTECFG.3 bit. PE3 is a bidirectional I/O port pin. RXD0OUT is an active HIGH signal from 805 UART0. If RXD0OUT is selected and UART0 Mode 0, this pin provides the output data for UART0 only when it is in sync mode. Otherwis is a 1.				
112	90	ı	ı	ı	PE4 or RXD1OUT	I/O/Z	 (PE4)	Z (PE4)	Multiplexed pin whose function is selected by the PORTECFG.4 bit. PE4 is a bidirectional I/O port pin. RXD10UT is an active-HIGH output from 8051 UART1. When RXD10UT is selected and UART1 is in Mode 0, this pin provides the output data for UART1 only when it is in sync mode. In Modes 1, 2, and 3, this pin is HIGH.				
113	91	1	1	-	PE5 or INT6	I/O/Z	I (PE5)	Z (PE5)	Multiplexed pin whose function is selected by the PORTECFG.5 bit. PE5 is a bidirectional I/O port pin. INT6 is the 8051 INT6 interrupt request input signal. The INT6 pin is edge-sensitive, active HIGH.				
114	92	ı	ı	ı	PE6 or T2EX	I/O/Z	I (PE6)	Z (PE6)	Multiplexed pin whose function is selected by the PORTECFG.6 bit. PE6 is a bidirectional I/O port pin. T2EX is an active HIGH input signal to the 8051 Timer2. T2EX reloads timer 2 on its falling edge. T2EX is active only if the EXEN2 bit is set in T2CON.				
115	93	-	-	-	PE7 or GPIFADR8	I/O/Z	I (PE7)	Z (PE7)	Multiplexed pin whose function is selected by the PORTECFG.7 bit. PE7 is a bidirectional I/O port pin. GPIFADR8 is a GPIF address output pin.				
4	3	8	1	1A	RDY0 or SLRD	Input	N/A	N/A	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. RDY0 is a GPIF input signal. SLRD is the input-only read strobe with programmable polarity (FIFOPINPOLAR.3) for the slave FIFOs connected to FD[70] or FD[150].				
5	4	9	2	1B	RDY1 or SLWR	Input	N/A	N/A	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. RDY1 is a GPIF input signal. SLWR is the input-only write strobe with programmable polarity (FIFOPINPOLAR.2) for the slave FIFOs connected to FD[70] or FD[150].				
6	5	_	_		RDY2	Input	N/A	N/A	RDY2 is a GPIF input signal.				



Table 11. FX2LP Pin Descriptions^[14] (continued)

128	100	56	56	56	(continued)								
		SSOP	QFN	VFBGA	Name	Type	Default	Reset ^[15]	Description				
7	6	ı	-	_	RDY3	Input	N/A	N/A	RDY3 is a GPIF input signal.				
8	7	ı	-	_	RDY4	Input	N/A	N/A	RDY4 is a GPIF input signal.				
9	8	1	_	_	RDY5	Input	N/A	N/A	RDY5 is a GPIF input signal.				
69	54	36	29	7H	CTL0 or FLAGA	O/Z	н	L	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. CTL0 is a GPIF control output. FLAGA is a programmable slave-FIFO output status flag signal. Defaults to programmable for the FIFO selected to the FIFOADR[1:0] pins.				
70	55	37	30	7G	CTL1 or FLAGB	O/Z	Н	L	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. CTL1 is a GPIF control output. FLAGB is a programmable slave-FIFO output status flag signal. Defaults to FULL for the FIFO selected by the FIFOADR[1:0] pins.				
71	56	38	31	8H	CTL2 or FLAGC	O/Z	н	L	Multiplexed pin whose function is selected by the following bits: IFCONFIG[10]. CTL2 is a GPIF control output. FLAGC is a programmable slave-FIFO output status flag signal. Defaults to EMPTY for the FIFO selected by the FIFOADR[1:0] pins.				
66	51	_	_	_	CTL3	O/Z	Н	L	CTL3 is a GPIF control output.				
67	52	_	_	_	CTL4	Output	Н	L	CTL4 is a GPIF control output.				
98	76	_	_	_	CTL5	Output	Н	L	CTL5 is a GPIF control output.				
32	26	20	13	2G	IFCLK on CY7C68013A and CY7C68014A	I/O/Z	Z	Z	Interface Clock, used for synchronously clocking data into or out of the slave FIFOs. IFCLK also serves as a timing reference for all slave FIFO control signals and GPIF. When internal clocking is used (IFCONFIG.7 = 1) the IFCLK pin can be configured to output 30/48 MHz by bits IFCONFIG.5 and IFCONFIG.6. IFCLK may be inverted, whether internally or externally sourced, by setting the bit IFCONFIG.4 =1.				
					CY7C68015A and CY7C68016A	 /O/Z	I	Z	PE0 is a bidirectional I/O port pin.				
28	22	_	_	_	INT4	Input	N/A	N/A	INT4 is the 8051 INT4 interrupt request input signal. The INT4 pin is edge-sensitive, active HIGH.				
106	84	_	_	_	INT5#	Input	N/A	N/A	INT5# is the 8051 INT5 interrupt request input signal. The INT5 pin is edge-sensitive, active LOW.				
31	25	_	_	_	T2	Input	N/A	N/A	T2 is the active HIGH T2 input signal to 8051 Timer2, which provides the input to Timer2 when C/T2 = 1. When C/T2 = 0, Timer2 does not use this pin.				



Table 11. FX2LP Pin Descriptions^[14] (continued)

128	100	56	56	56	Name	Туре	Default	Reset ^[15]	Description				
TQFP	TQFP	SSOP	QFN	VFBGA	Name	Туре	Delauit	IXCSC! 1	·				
30	24	I	I	_	T1	Input	N/A	N/A	T1 is the active HIGH T1 signal for 8051 Timer1, which provides the input to Timer1 when C/T1 is 1. When C/T1 is 0, Timer1 does not use this bit.				
29	23	1	1	_	ТО	Input	N/A	N/A	T0 is the active HIGH T0 signal for 8051 Timer which provides the input to Timer0 when C/T0 is When C/T0 is 0, Timer0 does not use this bit.				
53	43	ı	-	_	RXD1	Input	N/A	N/A	RXD1 is an active HIGH input signal for 8051 UART1, which provides data to the UART in all modes.				
52	42	1	-	_	TXD1	Output	Н	L	TXD1 is an active HIGH output pin from 8051 UART1, which provides the output clock in sync mode, and the output data in async mode.				
51	41	1	1	_	RXD0	Input	N/A	N/A	RXD0 is the active HIGH RXD0 input to 8051 UART0, which provides data to the UART in all modes.				
50	40	1	1	-	TXD0	Output	Н	L	TXD0 is the active HIGH TXD0 output from 8051 UART0, which provides the output clock in sync mode, and the output data in async mode.				
42		ı	-	_	CS#	Output	Н	Н	CS# is the active LOW chip select for external memory.				
41	32	-	_	_	WR#	Output	Н	Н	WR# is the active LOW write strobe output for external memory.				
40	31	-	_	_	RD#	Output	Н	Н	RD# is the active LOW read strobe output for external memory.				
38		_	_	_	OE#	Output	Н	Н	OE# is the active LOW output enable for external memory.				
33	27	21	14	2H	Reserved	Input	N/A	N/A	Reserved. Connect to ground.				
							I		_				
101	79	51	44	7B	WAKEUP	Input	N/A	N/A	USB Wakeup. If the 8051 is in suspend, asserting this pin starts up the oscillator and interrupts the 8051 to enable it to exit the suspend mode. Holding WAKEUP asserted inhibits the EZ-USB chip from suspending. This pin has programmable polarity (WAKEUP.4).				
36	29	22	15	3F	SCL	OD	Z	Z (if booting is done)	Clock for the I^2C interface. Connect to VCC with a 2.2-k Ω resistor, even if no I^2C peripheral is attached.				
37	30	23	16	3G	SDA	OD	Z	Z (if booting is done)	Data for I ² C compatible interface. Connect to VCC with a 2.2-kΩ resistor, even if no I ² C compatible peripheral is attached.				
2	1	6	55	5A	VCC	Power	N/A	N/A	VCC. Connect to the 3.3-V power source.				
26	20	18	11	1G	VCC	Power	N/A	N/A N/A	VCC. Connect to the 3.3-V power source.				
43	33	24	17	7E	VCC	Power	N/A	N/A	VCC. Connect to the 3.3-V power source.				
48	38	_	_	-	VCC	Power	N/A	N/A	VCC. Connect to 3.3-V power source.				
64	49	34	27	8E	VCC	Power	N/A	N/A	VCC. Connect to the 3.3-V power source.				
68	53	_	_	_	VCC	Power	N/A	N/A	VCC. Connect to the 3.3-V power source.				
81	66	39	32	5C	VCC	Power	N/A	N/A	VCC. Connect to the 3.3-V power source.				



Table 11. FX2LP Pin Descriptions^[14] (continued)

	11. 17.			•	,				
128 TQFP	100 TQFP	56 SSOP	56 QFN	56 VFBGA	Name	Туре	Default	Reset ^[15]	Description
100	78	50	43	5B	VCC	Power	N/A	N/A	VCC. Connect to the 3.3-V power source.
107	85	_	_	_	VCC	Power	N/A	N/A	VCC. Connect to the 3.3-V power source.
3	2	7	56	4B	GND	Ground	N/A	N/A	Ground
27	21	19	12	1H	GND	Ground	N/A	N/A	Ground
49	39	-	-	-	GND	Ground	N/A	N/A	Ground
58	48	33	26	7D	GND	Ground	N/A	N/A	Ground
65	50	35	28	8D	GND	Ground	N/A	N/A	Ground
80	65	_	_	_	GND	Ground	N/A	N/A	Ground
93	75	48	41	4C	GND	Ground	N/A	N/A	Ground
116	94	_	_	_	GND	Ground	N/A	N/A	Ground
125	99	4	53	4A	GND	Ground	N/A	N/A	Ground
	<u> </u>	U U							
14	13	-	_	_	NC	N/A	N/A	N/A	No Connect. This pin must be left open.
15	14	-	-	_	NC	N/A	N/A	N/A	No Connect. This pin must be left open.
16	15	-	_	_	NC	N/A	N/A	N/A	No Connect. This pin must be left open.

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Register Summary

FX2LP register bit definitions are described in the FX2LP TRM in greater detail.

Table 12. FX2LP Register Summary

Hex	Size	Name	Description	b7	b6	b5	b4	b3	b2	b1	b0	Default	Access
		GPIF Waveform Memo	ories										
E400	128	WAVEDATA	GPIF Waveform Descriptor 0, 1, 2, 3 data	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXX	RW
E480	128	reserved											
		GENERAL CONFIGU											
E50D		GPCR2	General Purpose Configuration Register 2	reserved	reserved	reserved	FULL SPEED_ON- LY	reserved	reserved	reserved	reserved	00000000	R
E600	1	CPUCS	CPU Control & Status	0	0	PORTCSTB	CLKSPD1	CLKSPD0	CLKINV	CLKOE	8051RES	00000010	rrbbbbbr
E601	1	IFCONFIG	Interface Configuration (Ports, GPIF, slave FIFOs)	IFCLKSRC	3048MHZ	IFCLKOE	IFCLKPOL	ASYNC	GSTATE	IFCFG1	IFCFG0	10000000	RW
E602	1	PINFLAGSAB ^[16]	Slave FIFO FLAGA and FLAGB Pin Configuration	FLAGB3	FLAGB2	FLAGB1	FLAGB0	FLAGA3	FLAGA2	FLAGA1	FLAGA0	00000000	RW
E603	1	PINFLAGSCD ^[16]	Slave FIFO FLAGC and FLAGD Pin Configuration	FLAGD3	FLAGD2	FLAGD1	FLAGD0	FLAGC3	FLAGC2	FLAGC1	FLAGC0	00000000	RW
E604	1	FIFORESET ^[16]	Restore FIFOS to default state	NAKALL	0	0	0	EP3	EP2	EP1	EP0	xxxxxxx	W
E605	1	BREAKPT	Breakpoint Control	0	0	0	0	BREAK	BPPULSE	BPEN	0	00000000	rrrrbbbr
E606	1	BPADDRH	Breakpoint Address H	A15	A14	A13	A12	A11	A10	A9	A8	XXXXXXX	RW
E607	1	BPADDRL	Breakpoint Address L	A7	A6	A5	A4	A3	A2	A1	A0	XXXXXXX	RW
E608	1	UART230	230 Kbaud internally generated ref. clock	0	0	0	0	0	0	230UART1	230UART0	00000000	rrrrrbb
E609	1	FIFOPINPOLAR ^[16]	Slave FIFO Interface pins polarity	0	0	PKTEND	SLOE	SLRD	SLWR	EF	FF	00000000	rrbbbbbb
E60A	1	REVID	Chip Revision	rv7	rv6	rv5	rv4	rv3	rv2	rv1	rv0	RevA 00000001	R
E60B	1	REVCTL ^[16] UDMA	Chip Revision Control	0	0	0	0	0	0	dyn_out	enh_pkt	00000000	rrrrrbb
E60C	1	GPIFHOLDAMOUNT	MSTB Hold Time (for UDMA)	0	0	0	0	0	0	HOLDTIME1	HOLDTIME0	00000000	rrrrrbb
	3	reserved	,										
		ENDPOINT CONFIGU	JRATION										
E610	1	EP10UTCFG	Endpoint 1-OUT Configuration	VALID	0	TYPE1	TYPE0	0	0	0	0	10100000	brbbrrrr
E611	1	EP1INCFG	Endpoint 1-IN Configuration	VALID	0	TYPE1	TYPE0	0	0	0	0	10100000	brbbrrrr
E612	1	EP2CFG	Endpoint 2 Configuration	VALID	DIR	TYPE1	TYPE0	SIZE	0	BUF1	BUF0	10100010	bbbbbrbb
E613	1	EP4CFG	Endpoint 4 Configuration	VALID	DIR	TYPE1	TYPE0	0	0	0	0	10100000	bbbbrrrr
E614	1	EP6CFG	Endpoint 6 Configuration	VALID	DIR	TYPE1	TYPE0	SIZE	0	BUF1	BUF0	11100010	bbbbbrbb
E615	1	EP8CFG	Endpoint 8 Configuration	VALID	DIR	TYPE1	TYPE0	0	0	0	0	11100000	bbbbrrrr
	2	reserved											
E618	1	EP2FIFOCFG ^[16]	Endpoint 2 / slave FIFO configuration	0	INFM1	OEP1	AUTOOUT	AUTOIN	ZEROLENIN	0	WORDWIDE	00000101	rbbbbbrb
E619	1	EP4FIFOCFG ^[16]	Endpoint 4 / slave FIFO configuration	0	INFM1	OEP1	AUTOOUT	AUTOIN	ZEROLENIN	0	WORDWIDE	00000101	rbbbbbrb
E61A	1	EP6FIFOCFG ^[16]	Endpoint 6 / slave FIFO configuration	0	INFM1	OEP1	AUTOOUT	AUTOIN	ZEROLENIN	0	WORDWIDE	00000101	rbbbbbrb
E61B	1	EP8FIFOCFG ^[16]	Endpoint 8 / slave FIFO configuration	0	INFM1	OEP1	AUTOOUT	AUTOIN	ZEROLENIN	0	WORDWIDE	00000101	rbbbbbrb
E61C	4	reserved											
E620	1	EP2AUTOINLENH ^{[16}	Endpoint 2 AUTOIN Packet Length H	0	0	0	0	0	PL10	PL9	PL8	00000010	rrrrrbbb
E621	1	EP2AUTOINLENL ^[16]	Endpoint 2 AUTOIN Packet Length L	PL7	PL6	PL5	PL4	PL3	PL2	PL1	PL0	00000000	RW
E622	1	EP4AUTOINLENH ^[16]	Endpoint 4 AUTOIN Packet Length H	0	0	0	0	0	0	PL9	PL8	00000010	rrrrrbb
E623	1	EP4AUTOINLENL ^[16]	Endpoint 4 AUTOIN Packet Length L	PL7	PL6	PL5	PL4	PL3	PL2	PL1	PL0	00000000	RW
E624	1	EP6AUTOINLENH ^[16]	Endpoint 6 AUTOIN Packet Length H	0	0	0	0	0	PL10	PL9	PL8	00000010	rrrrrbbb
E625	1	EP6AUTOINLENL ^[16]	Endpoint 6 AUTOIN Packet Length L	PL7	PL6	PL5	PL4	PL3	PL2	PL1	PL0	00000000	RW
E626	1	EP8AUTOINLENH ^[16]	Endpoint 8 AUTOIN Packet Length H	0	0	0	0	0	0	PL9	PL8	00000010	rrrrrbb
E627	1	EP8AUTOINLENL ^[16]	Endpoint 8 AUTOIN Packet Length L	PL7	PL6	PL5	PL4	PL3	PL2	PL1	PL0	00000000	RW
E628	1	ECCCFG	ECC Configuration	0	0	0	0	0	0	0	ECCM	00000000	rrrrrrb
E629	1	ECCRESET	ECC Reset	х	х	х	х	х	х	х	х	00000000	W
	1	ECC1B0	ECC1 Byte 0 Address	LINE15	LINE14	LINE13	LINE12	LINE11	LINE10	LINE9	LINE8	00000000	ь

Note

16. Read and writes to these registers may require synchronization delay; see Technical Reference Manual for "Synchronization Delay."

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Table 12. FX2LP Register Summary (continued)

EGG CCT ECT By E Address NET	Hex	Size	Name	Description	b7	b6	b5	b4	b3	b2	b1	b0	Default	Access
ESSECT ECCUSES ECCUS		1												
EEGO I COCOBI COCO Per Address NR 15 NR 14 NR 15 NR 14 NR 15 NR 16 NR 10000000 PC COCOBI COCO		1		,										
EGGS CO28		1		, ,										R
COCARD C		1												F -
Exercise Experiment Endower Zeleve Fire Color Prof. Prof		1		·										
	E630 H.S.	1		Endpoint 2 / slave FIFO			IN:PKTS[2]	IN:PKTS[1]			-	1-		
1.5 Paper	E630 F.S.	1	EP2FIFOPFH ^[17]	Endpoint 2 / slave FIFO	DECIS	PKTSTAT	OUT:PFC12	OUT:PFC11		0	PFC9	IN:PKTS[2] OUT:PFC8	10001000	bbbbbrbb
Section Programmable Flag Courseror Course Cour	E631 H.S.	1	EP2FIFOPFL ^[17]		PFC7	PFC6	PFC5	PFC4	PFC3	PFC2	PFC1	PFC0	00000000	RW
1.5 Popision of James Programmable Flag	E631 F.S	1		Programmable Flag L	OUT:PFC7	OUT:PFC6	PFC5							
Programmable Flag F	H.S.	1		Programmable Flag H			_	OUT:PFC10	OUT:PFC9					
1.5 Poperpoper Poper P	F.S	1		Programmable Flag H										
Programmable Flag L	H.S.	1		Programmable Flag L										
Fig. Programmable Flag H Programmable	F.S	1		Programmable Flag L	OUT:PFC7	OUT:PFC6								
Position Programmable Flag	H.S.	1		Programmable Flag H				OUT:PFC11	OUT:PFC10					
H.S. Programmable Flag L Programmable	F.S			Programmable Flag H										
Programmable Flag Programmable Flag Court-Price Programmable Flag Court-Price Programmable Flag Flag PRISTAT O IN-PKTS(I) OUT-PFC9	H.S.	1		Programmable Flag L										
H.S. Programmable Flag H Ep8FIFOPPH ^[17] Ep8FIFOPPH [[]	F.S	1		Programmable Flag L	OUT:PFC7	OUT:PFC6								
Fig.	H.S.	1		Programmable Flag H			_	OUT:PFC10	OUT:PFC9	0				
H.S.	F.S	1		Programmable Flag H						0				
Second Programmable Flag L OUT-PFC9' OUT-PFC9'	H.S.			Programmable Flag L										
EP2 SOINPKTS	F.S				IN: PKTS[1] OUT:PFC7	IN: PKTS[0] OUT:PFC6	PFC5	PFC4	PFC3	PFC2	PFC1	PFC0	00000000	RW
Frame (1-3)														
				framè (1-3)			0	0	0					
Fame (1-3)				frame (1-3)			_	Ŭ	0					
Frame (1-3)				frame (1-3)			_		0					
E648 1 NPKTEND Force N Packet End Skip 0 0 0 EP3 EP2 EP1 EP0 XXXXXXXX W		1			AADJ	0	0	0	0	0	INPPF1	INPPF0	00000001	brrrrrr
E649 7 OUTPKTEND ^[17] Force OUT Packet End Skip 0 0 0 0 EP3 EP2 EP1 EP0 XXXXXXXX W E650 1 EP2FIFOIE ^[17] Endpoint 2 slave FIFO Flag 0 0 0 0 EDGEPF FF EF FF O0000000 RW E652 1 EP2FIFOIRQ ^[17,18] Endpoint 2 slave FIFO Flag 0 0 0 0 0 EDGEPF EF FF O0000000 RW E652 1 EP4FIFOIRQ ^[17,18] Endpoint 4 slave FIFO Flag 0 0 0 0 0 EDGEPF EF FF O0000000 RW E653 1 EP4FIFOIRQ ^[17,18] Endpoint 4 slave FIFO Flag 0 0 0 0 0 EDGEPF EF FF O0000000 RW E655 1 EP6FIFOIRQ ^[17,18] Endpoint 4 slave FIFO Flag 0 0 0 0 EDGEPF EF FF O0000000 RW E655 1 EP6FIFOIRQ ^[17,18] Endpoint 6 slave FIFO Flag 0 0 0 0 EDGEPF EF FF EF FF EF EF EF		4										<u> </u>		
INTERRUPTS		1			<u> </u>		-	-						
EP2FIFOIRQ Endpoint 2 slave FIFO Flag 0 0 0 0 0 0 0 0 0	E649	1		Force OUT Packet End	Skip	U	U	U	EP3	EP2	EP1	EP0	XXXXXXXX	VV
EP2FIFOIRQ ^[17,18]	E650	1			0	0	0	0	EDGEPF	PF	EF	FF	00000000	RW
EP4FIFOIE ^[17]	E651	1	EP2FIFOIRQ ^[17,18]	Endpoint 2 slave FIFO Flag	0	0	0	0	0	PF	EF	FF	00000000	rrrrrbbb
EP4FIFOIRQ EP4FIFOIRQ Endpoint Slave FIFO Flag O O O O O O EDGEPF FF EF FF EF EF EF EF	E652	1	EP4FIFOIE ^[17]	Endpoint 4 slave FIFO Flag	0	0	0	0	EDGEPF	PF	EF	FF	00000000	RW
EP6FIFOIE ^[17]	E653	1	EP4FIFOIRQ ^[17,18]	Endpoint 4 slave FIFO Flag	0	0	0	0	0	PF	EF	FF	00000000	rrrrrbbb
EP6FIFOIRQ 17.18 Endpoint 6 slave FIFO Flag 0 0 0 0 0 0 0 0 0	E654	1	EP6FIFOIE ^[17]	Endpoint 6 slave FIFO Flag	0	0	0	0	EDGEPF	PF	EF	FF	00000000	RW
E656 1 EP8FIFOIE ^[17] Endpoint & slave FIFO Flag on the rupt Enable 0 0 0 0 EDGEPF PF EF FF 000000000 RW E657 1 EP8FIFOIRQ ^[17,18] Endpoint & slave FIFO Flag on the rupt Request 0 0 0 0 PF EF FF 000000000 rrrrrrbbb E658 1 IBNIE IN-BULK-NAK Interrupt Enable 0 0 EP8 EP6 EP4 EP2 EP1 EP0 000000000 RW E659 1 IBNIRQ ^[18] IN-BULK-NAK interrupt Enable 0 0 EP8 EP6 EP4 EP2 EP1 EP0 00xxxxxxx rrbbbbbb E659 1 IBNIRQ ^[18] IN-BULK-NAK interrupt Enable 0 0 EP8 EP6 EP4 EP2 EP1 EP0 00xxxxxxx rrbbbbbb E659 1 INAKIE Endpoint Ping-NAK / IBN Interrupt Enable EP6 EP4 EP2 EP1 EP0 0 IBN	E655	1	EP6FIFOIRQ ^[17,18]	Endpoint 6 slave FIFO Flag	0	0	0	0	0	PF	EF	FF	00000000	rrrrrbbb
E657 1 EP8FIFOIRQ ^[17,18] Endpoint & slave FIFO Flag 0 0 0 0 0 PF EF FF 00000000 rrrrrbbb E658 1 IBNIE IN-BULK-NAK Interrupt 0 0 EP8 EP6 EP4 EP2 EP1 EP0 00000000 RW E659 1 IBNIRQ ^[18] IN-BULK-NAK interrupt 0 0 EP8 EP6 EP4 EP2 EP1 EP0 00xxxxxxx rrbbbbbb E659 1 NAKIE Endpoint Ping-NAK / IBN EP8 EP6 EP4 EP2 EP1 EP0 0 IBN 00000000 RW E65B 1 NAKIRQ ^[18] Endpoint Ping-NAK / IBN EP8 EP6 EP4 EP2 EP1 EP0 0 IBN xxxxxxxx0x bbbbbbrb	E656	1	EP8FIFOIE ^[17]	Endpoint 8 slave FIFO Flag	0	0	0	0	EDGEPF	PF	EF	FF	00000000	RW
E658 1 IBNIE IN-BULK-NAK Interrupt Enable 0 0 EP8 EP6 EP4 EP2 EP1 EP0 000000000 RW E659 1 IBNIRQ[18] IN-BULK-NAK interrupt equest 0 0 EP8 EP6 EP4 EP2 EP1 EP0 00xxxxxxx rrbbbbbb E65A 1 NAKIE Endpoint Ping-NAK / IBN Interrupt Enable EP8 EP6 EP4 EP2 EP1 EP0 0 IBN 00000000 RW E65B 1 NAKIRQ ^[18] Endpoint Ping-NAK / IBN Interrupt Request EP8 EP6 EP4 EP2 EP1 EP0 0 IBN xxxxxxxx0x bbbbbbbrb	E657	1	EP8FIFOIRQ[17,18]	Endpoint 8 slave FIFO Flag	0	0	0	0	0	PF	EF	FF	00000000	rrrrrbbb
E659 1 IBNIRQ ^[18] IN-BULK-NAK interrupt Request 0 0 EP8 EP6 EP4 EP2 EP1 EP0 00xxxxxxx rrbbbbbb E65A 1 NAKIE Endpoint Ping-NAK / IBN Interrupt Enable EP6 EP4 EP2 EP1 EP0 0 IBN 000000000 RW E65B 1 NAKIRQ ^[18] Endpoint Ping-NAK / IBN Interrupt Request EP6 EP4 EP2 EP1 EP0 0 IBN xxxxxxxx0x bbbbbbrb	E658	1	IBNIE	IN-BULK-NAK Interrupt	0	0	EP8	EP6	EP4	EP2	EP1	EP0	00000000	RW
E65A 1 NAKIE Endpoint Ping-NAK / IBN Interrupt Enable EP8 EP6 EP4 EP2 EP1 EP0 0 IBN 00000000 RW E65B 1 NAKIRQ ^[18] Endpoint Ping-NAK / IBN Interrupt Request EP8 EP6 EP4 EP2 EP1 EP0 0 IBN xxxxxxxx0x bbbbbbrb	E659	1	IBNIRQ ^[18]	IN-BULK-NAK interrupt	0	0	EP8	EP6	EP4	EP2	EP1	EP0	00xxxxxx	rrbbbbbb
E65B 1 NAKIRQ ^[18] Endpoint Ping-NAK / IBN EP8 EP6 EP4 EP2 EP1 EP0 0 IBN xxxxxx0x bbbbbbrb	E65A	1	NAKIE	Endpoint Ping-NAK / IBN	EP8	EP6	EP4	EP2	EP1	EP0	0	IBN	00000000	RW
E65C 1 USBIE USB Int Enables 0 EP0ACK HSGRANT URES SUSP SUTOK SOF SUDAV 000000000 RW	E65B	1	NAKIRQ ^[18]	Endpoint Ping-NAK / IBN	EP8	EP6	EP4	EP2	EP1	EP0	0	IBN	xxxxxx0x	bbbbbbrb
	E65C	1	USBIE	USB Int Enables	0	EP0ACK	HSGRANT	URES	SUSP	SUTOK	SOF	SUDAV	00000000	RW

^{17.} Read and writes to these registers may require synchronization delay; see Technical Reference Manual for "Synchronization Delay".

18. The register can only be reset; it cannot be set.



Table 12. FX2LP Register Summary (continued)

	٥.											D ()	
Hex E65D	Size	Name USBIRQ ^[19]	Description USB Interrupt Requests	b7	b6 EP0ACK	b5 HSGRANT	b4 URES	b3 SUSP	b2 SUTOK	b1 SOF	b0 SUDAV	Default 0xxxxxxx	Access rbbbbbbb
	1	EPIE	Endpoint Interrupt	EP8	EP0ACK EP6	EP4	EP2	EP10UT	EP1IN	EP0OUT	EP0IN	00000000	
			Enables										
E65F	1	EPIRQ ^[19]	Endpoint Interrupt Requests	EP8	EP6	EP4	EP2	EP1OUT	EP1IN	EP0OUT	EP0IN	0	RW
E660	1	GPIFIE ^[20]	GPIF Interrupt Enable	0	0	0	0	0	0	GPIFWF	GPIFDONE	00000000	RW
E661	1	GPIFIRQ ^[20]	GPIF Interrupt Request	0	0	0	0	0	0	GPIFWF	GPIFDONE	000000xx	RW
E662	1	USBERRIE	USB Error Interrupt Enables	ISOEP8	ISOEP6	ISOEP4	ISOEP2	0	0	0	ERRLIMIT	00000000	RW
E663	1	USBERRIRQ ^[19]	USB Error Interrupt Requests	ISOEP8	ISOEP6	ISOEP4	ISOEP2	0	0	0	ERRLIMIT	0000000x	bbbbrrrb
E664	1	ERRCNTLIM	USB Error counter and limit	EC3	EC2	EC1	EC0	LIMIT3	LIMIT2	LIMIT1	LIMIT0	xxxx0100	rrrrbbbb
E665	1	CLRERRCNT	Clear Error Counter EC3:0	x	х	х	Х	х	х	х	х	XXXXXXX	W
	1	INT2IVEC	Interrupt 2 (USB) Autovector	0	12V4	12V3	I2V2	I2V1	12V0	0	0	00000000	
E667	1	INT4IVEC	Interrupt 4 (slave FIFO & GPIF) Autovector	1	0	14V3	14V2	I4V1	I4V0	0	0	10000000	R
E668	1	INTSET-UP	Interrupt 2&4 setup	0	0	0	0	AV2EN	0	INT4SRC	AV4EN	00000000	RW
E669	7	reserved											
		INPUT / OUTPUT	lua nanni i			_							
E670	1	PORTACFG	I/O PORTA Alternate Configuration	FLAGD	SLCS	0	0	0	0	INT1	INT0	00000000	
E671	1	PORTCCFG	I/O PORTC Alternate Configuration	GPIFA7	GPIFA6	GPIFA5	GPIFA4	GPIFA3	GPIFA2	GPIFA1	GPIFA0	00000000	
E672	1	PORTECFG	I/O PORTE Alternate Configuration	GPIFA8	T2EX	INT6	RXD10UT	RXD0OUT	T2OUT	T1OUT	T0OUT	00000000	RW
E673	4	reserved											
E677	1	reserved											
E678	1	I ² CS	I ² C Bus Control & Status	START	STOP	LASTRD	ID1	ID0	BERR	ACK	DONE	000xx000	bbbrrrrr
E679	1	I2DAT	I ² C Bus Data	d7	d6	d5	d4	d3	d2	d1	d0	xxxxxxx	RW
E67A	1	I ² CTL	I ² C Bus Control	0	0	0	0	0	0	STOPIE	400KHZ	00000000	RW
E67B	1	XAUTODAT1	Autoptr1 MOVX access, when APTREN=1	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXX	RW
E67C	1	XAUTODAT2	Autoptr2 MOVX access, when APTREN=1	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXX	RW
		UDMA CRC											
E67D	1	UDMACRCH ^[20]	UDMA CRC MSB	CRC15	CRC14	CRC13	CRC12	CRC11	CRC10	CRC9	CRC8	01001010	
E67E	1	UDMACRCL ^[20]	UDMA CRC LSB	CRC7	CRC6	CRC5	CRC4	CRC3	CRC2	CRC1	CRC0	10111010	RW
E67F	1	UDMACRC- QUALIFIER	UDMA CRC Qualifier	QENABLE	0	0	0	QSTATE	QSIGNAL2	QSIGNAL1	QSIGNAL0	00000000	brrrbbbb
		USB CONTROL											
_000	1	USBCS	USB Control & Status	HSM	0	0	0	DISCON	NOSYNSOF	RENUM	SIGRSUME	x0000000	
E681	1	SUSPEND	Put chip into suspend	x	Х	х	Х	х	х	Х	x	XXXXXXX	W
E682	1	WAKEUPCS		WU2	WU	WU2POL	WUPOL	0	DPEN	WU2EN	WUEN	xx000101	bbbbrbbb
E683	1	TOGCTL	Toggle Control	Q	S	R n	1/0	EP3	EP2	EP1	EP0	x0000000	
E684 E685	1	USBFRAMEH USBFRAMEL	USB Frame count H USB Frame count L	0 FC7	0 FC6	FC5	0 FC4	FC3	FC10 FC2	FC9 FC1	FC8 FC0	00000xxx	R
E686	1	MICROFRAME	Microframe count 0-7	0	0	0	0	0	MF2	MF1	MF0	00000xxx	R
E687	1	FNADDR	USB Function address	0	FA6	FA5	FA4	FA3	FA2	FA1	FA0	0xxxxxxx	R
E688	2	reserved	OOD 1 unouon address		1710	1710	174	17.0	1712	1711	17.0	OXXXXX	
		ENDPOINTS											
E68A		EP0BCH ^[20]	Endpoint 0 Byte Count H	(BC15)	(BC14)	(BC13)	(BC12)	(BC11)	(BC10)	(BC9)	(BC8)	XXXXXXXX	RW
E68B		EP0BCL ^[20]	Endpoint 0 Byte Count L	(BC7)	BC6	BC5	BC4	BC3	BC2	BC1	BC0	XXXXXXXX	RW
E68C		reserved	, , , , , , , , , , , , , , , , , , , ,	,									
E68D	1	EP1OUTBC	Endpoint 1 OUT Byte Count	0	BC6	BC5	BC4	BC3	BC2	BC1	BC0	0xxxxxxx	RW
E68E	1	reserved									1		
E68F	1	EP1INBC	Endpoint 1 IN Byte Count	0	BC6	BC5	BC4	BC3	BC2	BC1	BC0	0xxxxxxx	RW
E690	1	EP2BCH ^[20]	p j	0	0	0	0	0	BC10	BC9	BC8	00000xxx	RW
E691	1	EP2BCL ^[20]	Endpoint 2 Byte Count L	BC7/SKIP	BC6	BC5	BC4	BC3	BC2	BC1	BC0	xxxxxxx	RW
E692	2	reserved	-										
E694	1	EP4BCH ^[20]	, , .	0	0	0	0	0	0	BC9	BC8	000000xx	
E695	1	EP4BCL ^[20]	Endpoint 4 Byte Count L	BC7/SKIP	BC6	BC5	BC4	BC3	BC2	BC1	BC0	XXXXXXX	RW
E696	2	reserved EP6BCH ^[20]	Endnaint 6 Date County	0	0		0	0	DC10	DC0	DC0	00000:	DW
E698	1	EP6BCH ^[20]	Endpoint 6 Byte Count H	0 BC7/SKIP	0	0	0 PC4	U DC2	BC10	BC9	BC8	00000xxx	
E699	I	ELORCTing	Endpoint 6 Byte Count L	DC//SKIP	BC6	BC5	BC4	BC3	BC2	BC1	BC0	XXXXXXX	RW

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^{19.} The register can only be reset; it cannot be set.
20. Read and writes to these registers may require synchronization delay; see Technical Reference Manual for "Synchronization Delay".



Table 12. FX2LP Register Summary (continued)

Max Size Name Description b7 b6 b5 b4 b3 b2 b1 b0	Default Acc	bbbbbri bbbbbri
ERBSC_MIT ERBSC_MIT Endpoint 8 Byte Count H 0	0000000 bbbb 0000000 bbbb 0000000 bbbb 00101000 rrrrrr	bbbbbri bbbbbri
E666 E700	10000000 bbbbb 00000000 bbbbb 00101000 rrrrrrr	bbbbbrl bbbbbrl
EGGE POCS Endpoint Ocntrol and Sta- NRNAK 0 0 0 0 0 0 0 0 0	10000000 bbbbb 00000000 bbbbb 00101000 rrrrrrr	bbbbbri
EPA1 EP10UTCS Endpoint 1 OUT Control 0 0 0 0 0 0 0 0 0	00000000 bbbb 00000000 bbbb 00101000 rrrrrr	bbbbbri
BPTINCS Endpoint IN Control and 0 0 0 0 0 0 0 0 0 0	00000000 bbbb 00101000 rrrrrr	bbbbbrl
Status Park Park	00101000 rrrrrr	
BPACS	00101000 rrrrrr	rrrrrb
Lus		
Lis	00000100 rrrrrr	rrrrrb
Lis	<u> </u>	rrrrrb
Flags	00000100 rrrrrr	rrrrrb
Flags	00000010 R	
Flags	00000010 R	
Flags	00000110 R	
Second S	00000110 R	
Setable Seta	00000000 R	
E6AE EP4FIFOBCL	00000000 R	
E6AF 1 EP6FIFOBCH Endpoint 6 slave FIFO total byte count H 0 0 0 0 BC11 BC10 BC9 BC8 E6B0 1 EP6FIFOBCL Endpoint 6 slave FIFO total byte count L BC7 BC6 BC5 BC4 BC3 BC2 BC1 BC0 E6B1 1 EP8FIFOBCH Endpoint 8 slave FIFO total byte count H 0 0 0 0 0 BC3 BC2 BC1 BC9 BC8 E6B2 1 EP8FIFOBCL Endpoint 8 slave FIFO total byte count L BC7 BC6 BC5 BC4 BC3 BC2 BC1 BC0 E6B2 1 EP8FIFOBCL Endpoint 8 slave FIFO total byte count L BC7 BC6 BC5 BC4 BC3 BC2 BC1 BC0 E6B3 1 SUDPTRH Setup Data Pointer high address byte A14 A13 A12 A11 A10 A9 A8 E6B4 1 SUDPTRL Setup Data Pointer low address byte A6 A5 </td <td>00000000 R</td> <td></td>	00000000 R	
E6AF 1 EP6FIFOBCH Endpoint 6 slave FIFO total byte count H 0 0 0 0 BC11 BC10 BC9 BC8 E6B0 1 EP6FIFOBCL Endpoint 8 slave FIFO total byte count L BC7 BC6 BC5 BC4 BC3 BC2 BC1 BC0 E6B1 1 EP8FIFOBCH Endpoint 8 slave FIFO total byte count H 0 0 0 0 0 BC3 BC2 BC1 BC8 E6B2 1 EP8FIFOBCL Endpoint 8 slave FIFO total byte count L BC7 BC6 BC5 BC4 BC3 BC2 BC1 BC0 E6B2 1 EP8FIFOBCL Endpoint 8 slave FIFO total byte count L BC7 BC6 BC5 BC4 BC3 BC2 BC1 BC0 E6B3 1 SUDPTRH Setup Data Pointer high address byte A14 A13 A12 A11 A10 A9 A8 E6B4 1 SUDPTRL Setup Data Pointer Auto Mode 0 0 0	00000000 R	
total byte count L E6B1 1 EP8FIFOBCH Endpoint 8 slave FIFO 10 10 10 10 10 10 10 1	00000000 R	
total byte count H	00000000 R	
total byte count L Setup Data Pointer high address byte A15 A14 A13 A12 A11 A10 A9 A8	00000000 R	
Address byte	00000000 R	
	xxxxxxxx RW	.W
Mode	xxxxxxx0 bbbb	bbbbbb
E6B8 8 SET-UPDAT 8 bytes of setup data D7 D6 D5 D4 D3 D2 D1 D0 SET-UPDAT[0] = bmRequestType SET-UPDAT[1] = bmRequest SET-UPDAT[2:3] = wValue SET-UPDAT[3:3] = wValue <	00000001 RW	W
SET-UPDAT[0] =		
bmRequestType	xxxxxxxx R	
bmRequest SET-UPDAT[2:3] = wValue		
SET-UPDAT[2:3] = wValue		
SET-HPDATI4:51 = wIndex	1	
52. 0. 5/11[10] 1111(0.)		
SET-UPDAT[6:7] =		
WLength GPIF		
E6C0 1 GPIFWFSELECT Waveform Selector SINGLEWR1 SINGLEWR0 SINGLERD1 SINGLERD0 FIFOWR0 FIFORD1 FIFORD0	11100100 RW	٠/٨/
GPIFIDLECS	10000000 RW	
E6C2 1 GPIFIDLECTL Inactive Bus, CTL states 0 0 CTL5 CTL4 CTL3 CTL2 CTL1 CTL0	11111111 RW	W
E6C3 1 GPIFCTLCFG CTL Drive Type TRICTL 0 CTL5 CTL4 CTL3 CTL2 CTL1 CTL0	00000000 RW	.W
E6C4 1 GPIFADRH ^[21] GPIF Address H 0 0 0 0 0 0 0 0 GPIFA8	00000000 RW	
E6C5 1 GPIFADRL ^[21] GPIF Address L GPIFA7 GPIFA6 GPIFA5 GPIFA4 GPIFA3 GPIFA2 GPIFA1 GPIFA0	00000000 RW	.W
FLOWSTATE		
E6C6 1 FLOWSTATE Flowstate Enable and FSE 0 0 0 0 FS2 FS1 FS0	00000000 brrrrt	
E6C7 1 FLOWLOGIC Flowstate Logic LFUNC1 LFUNC0 TERMA2 TERMA1 TERMA0 TERMB2 TERMB1 TERMB0	00000000 RW	
E6C8 1 FLOWEQ0CTL CTL-Pin States in Flowstate (when Logic = 0) CTL0E3 CTL0E2 CTL0E1/ CTL5 CTL1 CTL0 CTL1 CTL1 CTL1 CTL1 CTL1 CTL1 CTL1 CTL1	00000000 RW	.W

Note

21. Read and writes to these registers may require synchronization delay; see Technical Reference Manual for "Synchronization Delay".

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Table 12. FX2LP Register Summary (continued)

Have	Cina	Nama	Description	L-7	L.C	h.F	h.4	h2	L 2	L4	L 60	Default	Access
	Size 1	Name FLOWEQ1CTL	Description CTL-Pin States in Flow-	b7 CTL0E3	b6 CTL0E2	b5 CTL0E1/	b4 CTL0E0/	b3 CTL3	b2 CTL2	b1 CTL1	b0 CTL0	Default 00000000	
E0C9	1	FLOWEQICIL	state (when Logic = 1)	CILUES	CILUEZ	CTL5	CTL0E0/	CILS	CILZ	CILI	CILU	00000000	KVV
E6CA	1	FLOWHOLDOFF	Holdoff Configuration	HOPERIOD3	HOPERIOD2	HOPERIOD1	HOPERIOD0	HOSTATE	HOCTL2	HOCTL1	HOCTL0	00010010	RW
E6CB	1	FLOWSTB	Flowstate Strobe	SLAVE	RDYASYNC	CTLTOGL	SUSTAIN	0	MSTB2	MSTB1	MSTB0	00100000	RW
			Configuration										
E6CC	1	FLOWSTBEDGE	Flowstate Rising/Falling Edge Configuration	0	0	0	0	0	0	FALLING	RISING	00000001	rrrrrbb
E6CD	1	FLOWSTBPERIOD	Master-Strobe Half-Period	D7	D6	D5	D4	D3	D2	D1	D0	00000010	RW/
E6CE		GPIFTCB3 ^[22]	GPIF Transaction Count	TC31	TC30	TC29	TC28	TC27	TC26	TC25	TC24	00000000	
LOOL		01111000	Byte 3	1001	1000	1020	1020	1021	1020	1020	1024	0000000	
E6CF	1	GPIFTCB2 ^[22]	GPIF Transaction Count	TC23	TC22	TC21	TC20	TC19	TC18	TC17	TC16	00000000	RW
E000	,	0.015700.4[22]	Byte 2	T045	T011	T010	T040	T044	T040	T00	T00	0000000	DIM
E6D0	1	GPIFTCB1 ^[22]	GPIF Transaction Count Byte 1	TC15	TC14	TC13	TC12	TC11	TC10	TC9	TC8	00000000	RVV
E6D1	1	GPIFTCB0 ^[22]	GPIF Transaction Count	TC7	TC6	TC5	TC4	TC3	TC2	TC1	TC0	00000001	RW
			Byte 0										
		reserved										00000000	RW
		reserved											
FODO		reserved	E		•		0	•	•	F0.4	500	0000000	DIA.
E6D2	1	EP2GPIFFLGSEL ^[22]	Endpoint 2 GPIF Flag select	0	0	0	0	0	0	FS1	FS0	00000000	RW
E6D3	1	EP2GPIFPFSTOP	Endpoint 2 GPIF stop	0	0	0	0	0	0	0	FIFO2FLAG	00000000	RW
			transaction on prog. flag										
E6D4		EP2GPIFTRIG ^[22]	Endpoint 2 GPIF Trigger	х	X	х	х	х	х	х	Х	XXXXXXX	W
	3	reserved											
		reserved											
E0D 4		reserved	E		•		0	•	•	F0.4	500	0000000	DIA.
E6DA	1	EP4GPIFFLGSEL ^[22]	Endpoint 4 GPIF Flag select	0	0	0	0	0	0	FS1	FS0	00000000	RW
E6DB	1	EP4GPIFPFSTOP		0	0	0	0	0	0	0	FIFO4FLAG	00000000	RW
			transaction on GPIF Flag										
E6DC	1	EP4GPIFTRIG ^[22]	Endpoint 4 GPIF Trigger	x	x	x	x	х	x	x	x	XXXXXXX	W
	3	reserved											
		reserved											
		reserved			•								
E6E2	1	EP6GPIFFLGSEL ^[22]	Endpoint 6 GPIF Flag select	0	0	0	0	0	0	FS1	FS0	00000000	RW
E6E3	1	EP6GPIFPFSTOP	Endpoint 6 GPIF stop	0	0	0	0	0	0	0	FIFO6FLAG	00000000	RW
	-		transaction on prog. flag										
E6E4	1	EP6GPIFTRIG ^[22]	Endpoint 6 GPIF Trigger	x	Х	x	х	Х	Х	Х	х	XXXXXXX	W
	3	reserved											
		reserved											
		reserved											
E6EA	1	EP8GPIFFLGSEL ^[22]	Endpoint 8 GPIF Flag select	0	0	0	0	0	0	FS1	FS0	00000000	RW
E6EB	1	EP8GPIFPFSTOP	Endpoint 8 GPIF stop	0	0	0	0	0	0	0	FIFO8FLAG	00000000	RW
LULD		21 001 11 1 0 101	transaction on prog. flag		0			·	·	·	111 001 210	0000000	
E6EC	1	EP8GPIFTRIG ^[22]	Endpoint 8 GPIF Trigger	х	Х	х	х	х	х	х	х	XXXXXXX	W
	3	reserved											
E6F0	1	XGPIFSGLDATH	GPIF Data H	D15	D14	D13	D12	D11	D10	D9	D8	XXXXXXX	RW
E6F1	1	XGPIFSGLDATLX	(16-bit mode only) Read/Write GPIF Data L &	D7	D6	D5	D4	D3	D2	D1	D0	xxxxxxxx	RW
LOII		AGFII GGLDATLA	trigger transaction	D1	Бо	D3	D4	D3	D2	D1	Бо	^^^^	IXVV
E6F2	1	XGPIFSGLDATLNOX	Read GPIF Data L, no	D7	D6	D5	D4	D3	D2	D1	D0	xxxxxxx	R
			transaction trigger								ļ		
E6F3	1	GPIFREADYCFG	Internal RDY, Sync/Async, RDY pin states	INTRDY	SAS	TCXRDY5	0	0	0	0	0	00000000	bbbrrrrr
			TOT pin states								1		L
E6F4	1	GPIFREADYSTAT	GPIF Ready Status	0	0	RDY5	RDY4	RDY3	RDY2	RDY1	RDY0	00xxxxxx	R
E6F5		GPIFABORT	Abort GPIF Waveforms	x	X	x	x	X	x	X	x	XXXXXXXX	W
E6F6	2	reserved											
		ENDPOINT BUFFERS	3										
E740	64	EP0BUF	EP0-IN/-OUT buffer	D7	D6	D5	D4	D3	D2	D1	D0	xxxxxxx	RW
E780	64	EP10UTBUF	EP1-OUT buffer	D7	D6	D5	D4	D3	D2	D1	D0	xxxxxxx	RW
E7C0	64	EP1INBUF	EP1-IN buffer	D7	D6	D5	D4	D3	D2	D1	D0	xxxxxxx	RW
E800		reserved											RW
F000	1024	EP2FIFOBUF	512/1024 byte EP 2 / slave	D7	D6	D5	D4	D3	D2	D1	D0	xxxxxxx	RW
F400	512	EP4FIFOBUF	FIFO buffer (IN or OUT) 512 byte EP 4 / slave FIFO	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXXX	RW
1.400	312	LF4FIFUDUF	buffer (IN or OUT)	וט	טם	טט	D4	טט	DZ	וטו	D0	^XXXXXXX	IXVV
F600	512	reserved	,										

Note

22. Read and writes to these registers may require synchronization delay; see Technical Reference Manual for "Synchronization Delay".

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Table 12. FX2LP Register Summary (continued)

F800	Size	Name	Description	b7	b6	b5	b4	b3	b2	b1	b0	Default	Access
	1024	EP6FIFOBUF	512/1024 byte EP 6 / slave	D7	D6	D5	D4	D3	D2	D1	D0	xxxxxxx	RW
FC00	512	EP8FIFOBUF	FIFO buffer (IN or OUT) 512 byte EP 8 / slave FIFO buffer (IN or OUT)	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXXX	RW
FE00	512	reserved	buller (IIV or OOT)						+			+	
XXXX	OIL	I ² C Configuration Byte	<u> </u>	0	DISCON	0	0	0	0	0	400KHZ	xxxxxxxx [23]	n/a
		Special Function Regi	. '										
80	1	IOA ^[24]	Port A (bit addressable)	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXX	RW
81	1	SP	Stack Pointer	D7	D6	D5	D4	D3	D2	D1	D0	00000111	RW
82	1	DPL0	Data Pointer 0 L	A7	A6	A5	A4	A3	A2	A1	A0	00000000	RW
83	1	DPH0	Data Pointer 0 H	A15	A14	A13	A12	A11	A10	A9	A8		
84	1	DPL1 ^[24]	Data Pointer 1 L	A7	A6	A5	A4	A3	A2	A1	A0	00000000	
85	1	DPH1 ^[24]	Data Pointer 1 H	A15	A14	A13	A12	A11	A10	A9	A8	00000000	
86	1	DPS ^[24]	Data Pointer 0/1 select	0	0	0	0	0	0	0	SEL	00000000	
87	1	PCON	Power Control	SMOD0	х	1	1	x	х	х	IDLE	00110000	
88	1	TCON	Timer/Counter Control (bit addressable)	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0	00000000	
89	1	TMOD	Timer/Counter Mode Control	GATE	СТ	M1	M0	GATE	СТ	M1	M0	00000000	
8A	1	TL0	Timer 0 reload L	D7	D6	D5	D4	D3	D2	D1	D0	00000000	
8B	1	TL1	Timer 1 reload L	D7	D6	D5	D4	D3	D2	D1	D0	00000000	
8C	1	TH0	Timer 0 reload H	D15	D14	D13	D12	D11	D10	D9	D8	00000000	RW
8D	1	TH1 CKCON ^[24]	Timer 1 reload H	D15	D14	D13	D12	D11	D10	D9	D8	00000000	RW
8E	1		Clock Control	х	х	T2M	T1M	TOM	MD2	MD1	MD0	00000001	RW
8F	1	reserved IOB ^[24]	Doub D (bit oddooooble)	D.7	DO	Dr	D4	Do	DO.	D4	DO		D)A/
90 91	1	EXIF ^[24]	Port B (bit addressable)	D7 IE5	D6 IE4	D5	D4 USBNT	D3	D2	D1	D0 0	00001000	RW
92	1	MPAGE ^[24]	External Interrupt Flag(s) Upper Addr Byte of MOVX using @R0 / @R1		A14	I ² CINT A13	A12	A11	A10	0 A9	A8	0000000	
93	5	reserved	doing (girto / (girt)										
98	1	SCON0	Serial Port 0 Control (bit addressable)	SM0_0	SM1_0	SM2_0	REN_0	TB8_0	RB8_0	TI_0	RI_0	00000000	RW
99	1	SBUF0	Serial Port 0 Data Buffer	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
9A	1	AUTOPTRH1 ^[24]	Autopointer 1 Address H	A15	A14	A13	A12	A11	A10	A9	A8	00000000	RW
9B	1	AUTOPTRL1 ^[24]	Autopointer 1 Address L	A7	A6	A5	A4	A3	A2	A1	A0	00000000	RW
9C	1	reserved											
9D	1	AUTOPTRH2 ^[24]	Autopointer 2 Address H	A15	A14	A13	A12	A11	A10	A9	A8	00000000	RW
9E	1	AUTOPTRL2 ^[24]	Autopointer 2 Address L	A7	A6	A5	A4	A3	A2	A1	A0	00000000	RW
9F	1	reserved											
A0	1	IOC ^[24]	Port C (bit addressable)	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXX	RW
A1	1	INT2CLR ^[24]	Interrupt 2 clear	x	Х	х	Х	х	х	х	Х	XXXXXXX	W
A2	1	INT4CLR ^[24]	Interrupt 4 clear	x	х	х	x	х	х	х	х	XXXXXXX	W
	5	reserved											
A8	1	IE .	Interrupt Enable (bit addressable)	EA	ES1	ET2	ES0	ET1	EX1	ET0	EX0	00000000	RW
A9	1	reserved	E 1 : 10 10 0 11	FDOF	EDOE	EDOE	EDOE	ED.45	ED 4E	EDOE	EDOE	04044040	_
	1	EP2468STAT ^[24]	Endpoint 2,4,6,8 status flags	EP8F	EP8E	EP6F	EP6E	EP4F	EP4E	EP2F	EP2E	01011010	
AB	1	EP24FIFOFLGS [24]	Endpoint 2,4 slave FIFO status flags	0	EP4PF EP8PF	EP4EF EP8EF	EP4FF EP8FF	0	EP2PF EP6PF	EP2EF EP6EF	EP2FF EP6FF	00100010	
AC	1	EP68FIFOFLGS	Endpoint 6,8 slave FIFO status flags	U	EP8PF	EP8EF	EP8FF	0	EPOPF	EPOEF	EPOFF	01100110	K
AD AF	2	reserved AUTOPTRSETUP ^[24]	Autopointer 1&2 setup	0	0	0	0	0	APTR2INC	APTR1INC	APTREN	00000110	D\A/
B0	1	IOD ^[24]		D7	D6	D5	D4	D3	D2	D1	D0		RW
B1	1	IOE ^[24]	, ,	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXXX	
B2	1	OEA ^[24]	,	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
	1	OEB ^[24]	Port B Output Enable	D7	D6	D5	D4	D3	D2	D1	D0	00000000	
33	1	OEC ^[24]	Port C Output Enable	D7	D6	D5	D4	D3	D2	D1	D0	00000000	
B3 B4		OED ^[24]	Port D Output Enable	D7	D6	D5	D4	D3	D2	D1	D0	00000000	
B4	1				1								
B4 B5	1	OEE ^[24]	Port E Output Enable	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
	1 1 1	OEE ^[24]		D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
B4 B5 B6	1 1 1			D7	D6 PS1	D5 PT2	D4 PS0	D3 PT1	D2 PX1	D1 PT0	D0 PX0	10000000	

23. If no EEPROM is detected by the SIE then the default is 00000000. 24. SFRs not part of the standard 8051 architecture.



Table 12. FX2LP Register Summary (continued)

Hex	Size	Name	Description	b7	b6	b5	b4	b3	b2	b1	b0	Default	Access
ВА	1	EP01STAT ^[25]	Endpoint 0&1 Status	0	0	0	0	0	EP1INBSY	EP10UTBSY	EP0BSY	00000000	R
	1	GPIFTRIG ^[25, 26]	Endpoint 2,4,6,8 GPIF slave FIFO Trigger	DONE	0	0	0	0	RW	EP1	EP0	10000xxx	brrrrbbb
BC	1	reserved											
	1	GPIFSGLDATH ^[25]	GPIF Data H (16-bit mode only)		D14	D13	D12	D11	D10	D9	D8	XXXXXXX	RW
BE	1	GPIFSGLDATLX ^[25]		D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXX	RW
BF		GPIFSGLDATL- NOX ^[25]	GPIF Data L w/ No Trigger	D7	D6	D5	D4	D3	D2	D1	D0	XXXXXXXX	R
C0		SCON1 ^[25]	Serial Port 1 Control (bit addressable)	SM0_1	SM1_1	SM2_1	REN_1	TB8_1	RB8_1	TI_1	RI_1	00000000	RW
C1	1	SBUF1 ^[25]	Serial Port 1 Data Buffer	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
C2	6	reserved											
C8	1	T2CON	Timer/Counter 2 Control (bit addressable)	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	CT2	CPRL2	00000000	RW
C9	1	reserved											
CA	1	RCAP2L	Capture for Timer 2, auto-reload, up-counter	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
СВ	1	RCAP2H	Capture for Timer 2, auto-reload, up-counter	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
CC	1	TL2	Timer 2 reload L	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
CD	1	TH2	Timer 2 reload H	D15	D14	D13	D12	D11	D10	D9	D8	00000000	RW
CE	2	reserved											
D0	1	PSW	Program Status Word (bit addressable)	CY	AC	F0	RS1	RS0	OV	F1	Р	00000000	RW
D1	7	reserved											
D8	1	EICON ^[25]	External Interrupt Control	SMOD1	1	ERESI	RESI	INT6	0	0	0	01000000	RW
D9	7	reserved											
E0	1	ACC	Accumulator (bit address- able)	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
E1	7	reserved											
E8	1	EIE ^[25]	External Interrupt En- able(s)	1	1	1	EX6	EX5	EX4	El ² C	EUSB	11100000	RW
E9	7	reserved											
F0	1	В	B (bit addressable)	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
F1	7	reserved											
F8	1	EIP ^[25]	External Interrupt Priority Control	1	1	1	PX6	PX5	PX4	PI ² C	PUSB	11100000	RW
F9	7	reserved											

R = all bits read-only W = all bits write-only

r = read-only bit

w = write-only bit

b = both read/write bit

25. SFRs not part of the standard 8051 architecture.
26. Read and writes to these registers may require synchronization delay; see Technical Reference Manual for "Synchronization Delay".

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Absolute Maximum Ratings

Exceeding maximum ratings may shorten the useful life of the device. User guidelines are not tested. Storage temperature-65 °C to +150 °C Ambient temperature with power supplied (Commercial)...... 0 °C to +70 °C Ambient temperature with power supplied (Industrial)-40 °C to +105 °C Supply voltage to ground potential-0.5 V to +4.0 V DC input voltage to any input pin^[27]5.25 V DC voltage applied to outputs in high Z state -0.5 V to V_{CC} + 0.5 V Static discharge voltage>2000 V Max output current, per I/O port10 mA Max output current, all five I/O ports (128-pin and 100-pin packages) 50 mA

Operating Conditions

T _A (ambient temperature under bias) Commercial	0 °C to +70 °C
T _A (ambient temperature under bias) Industrial	–40 °C to +105 °C
Supply voltage	+3.00 V to +3.60 V
Ground voltage	0 V
F _{OSC} (oscillator or crystal frequency)	24 MHz ± 100 ppm, parallel resonant

Thermal Characteristics

Maximum junction temperature 125 °C

The following table displays the thermal characteristics of various packages:

Table 13. Thermal Characteristics

Package	Ambient Temperature (°C)	⊕Jc Junction to Case Thermal Resistance (°C/W)	θJa Junction to Ambient Thermal Resistance (°C/W)
56 SSOP	70	24.4	47.7
100 TQFP	70	11.9	45.9
128 TQFP	70	15.5	43.2
56 QFN	70	10.6	25.2
56 VFBGA	70	30.9	58.6

The junction temperature θ_i , can be calculated using the following equation: $\theta_i = P^*\theta_{Ja} + \theta_a$ Where,

P = Power

 θ_{Ja} = Junction to ambient temperature (θ_{Jc} + θ_{Ca})

 θ_a = Ambient temperature (70 °C)

The case temperature θ_c , can be calculated using the following equation: $\theta_c = P^*\theta_{Ca} + \theta_a$ where,

P = Power

 θ_{Ca} = Case to ambient temperature

θ_a = Ambient temperature (70 °C)

27. Do not power I/O with the chip power OFF.



DC Electrical Characteristics

Table 14. DC Characteristics

Parameter	Description	Conditions	Min	Тур	Max	Unit
VCC	Supply voltage	-	3.00	3.3	3.60	V
VCC Ramp Up	0 to 3.3 V	-	200	_	-	μS
V _{IH}	Input HIGH voltage	-	2	_	5.25	V
V _{IL}	Input LOW voltage	-	-0.5	_	0.8	V
V _{IH_X}	Crystal input HIGH voltage	_	2	_	5.25	V
V_{IL_X}	Crystal input LOW voltage	-	-0.5	_	0.8	V
I _I	Input leakage current	0< V _{IN} < V _{CC}	-	_	±10	μΑ
V _{OH}	Output voltage HIGH	I _{OUT} = 4 mA	2.4	_	_	V
V _{OL}	Output LOW voltage	I _{OUT} = –4 mA	-	_	0.4	V
I _{OH}	Output current HIGH	_	-	_	4	mA
I _{OL}	Output current LOW	_	_	_	4	mA
C	Input pin capacitance	Except D+/D-	-	_	10	pF
C _{IN}	Imput pin capacitance	D+/D-	-	_	15	pF
	Suspend current	Connected	-	300	380 ^[28]	μΑ
	CY7C68014/CY7C68016	Disconnected	_	100	150 ^[28]	μΑ
ISUSP	Suspend current	Connected	-	0.5	1.2 ^[28]	mA
	CY7C68013/CY7C68015	Disconnected	_	0.3	1.0 ^[28]	mA
1	Supply ourrent	8051 running, connected to USB HS	_	50	85	mA
I _{CC}	Supply current	8051 running, connected to USB FS	_	35	65	mA
т	Reset time after valid power	\/ min = 2.0.\/	5.0	_	_	ms
T _{RESET}	Pin reset after powered on		200	_	-	μS

USB Transceiver

USB 2.0 compliant in Full Speed and Hi-Speed modes.

Note

28. Measured at Max $\rm V_{CC},\,25~^{\circ}C.$



AC Electrical Characteristics

USB Transceiver

USB 2.0 compliant in Full-Speed and Hi-Speed modes.

Program Memory Read

Figure 12. Program Memory Read Timing Diagram

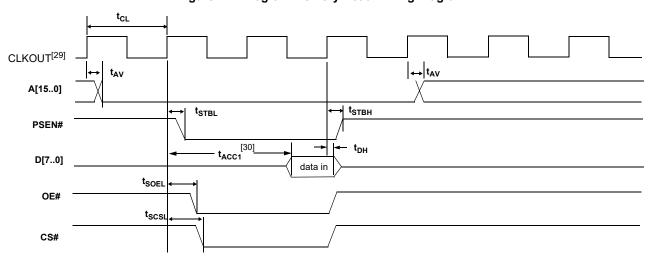


Table 15. Program Memory Read Parameters

Parameter	Description	Min	Тур	Max	Unit	Notes
		_	20.83	-	ns	48 MHz
t _{CL}	1/CLKOUT frequency	_	41.66	-	ns	24 MHz
		_	83.2	-	ns	12 MHz
t _{AV}	Delay from clock to valid address	0	_	10.7	ns	-
t _{STBL}	Clock to PSEN LOW	0	_	8	ns	_
t _{STBH}	Clock to PSEN HIGH	0	_	8	ns	_
t _{SOEL}	Clock to OE LOW	_	_	11.1	ns	_
t _{SCSL}	Clock to CS LOW	_	_	13	ns	_
t _{DSU}	Data setup to clock	9.6	_	-	ns	-
t _{DH}	Data hold time	0	_	-	ns	-

Notes

29. CLKOUT is shown with positive polarity.

30. t_{ACC1} is computed from these parameters as follows: t_{ACC1}(24 MHz) = 3*t_{CL} - t_{AV} - t_{DSU} = 106 ns. t_{ACC1}(48 MHz) = 3*t_{CL} - t_{AV} - t_{DSU} = 43 ns.

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Data Memory Read^[31]

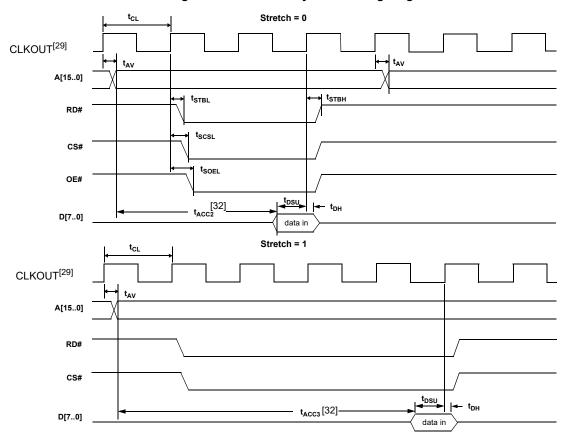


Figure 13. Data Memory Read Timing Diagram

Table 16. Data Memory Read Parameters

Parameter	Description	Min	Тур	Max	Unit	Notes
t _{CL}	1/CLKOUT frequency	_	20.83	_	ns	48 MHz
		_	41.66	_	ns	24 MHz
		_	83.2	_	ns	12 MHz
t _{AV}	Delay from clock to valid address	_	_	10.7	ns	-
t _{STBL}	Clock to RD LOW	_	_	11	ns	_
t _{STBH}	Clock to RD HIGH	_	_	11	ns	_
t _{SCSL}	Clock to CS LOW	_	_	13	ns	-
t _{SOEL}	Clock to OE LOW	_	_	11.1	ns	_
t _{DSU}	Data setup to clock	9.6	_	_	ns	-
t _{DH}	Data hold time	0	_	_	ns	_

When using the AUTPOPTR1 or AUTOPTR2 to address external memory, the address of AUTOPTR1 is only active while either RD# or WR# is active. The address of AUTOPTR2 is active throughout the cycle and meets the address valid time for which is based on the stretch value.

^{31.} The stretch memory cycle feature enables EZ-USB firmware to adjust the speed of data memory accesses not the program memory accesses. Details including typical strobe width timings can be found in the section 12.1.2 of the Technical Reference Manual. The address cycle width can be interpreted from these.

^{32.} t_{ACC2} and t_{ACC3} are computed from these parameters as follows: $t_{ACC2}(24 \text{ MHz}) = 3^*t_{CL} - t_{AV} - t_{DSU} = 106 \text{ ns}$ $t_{ACC3}(24 \text{ MHz}) = 3^*t_{CL} - t_{AV} - t_{DSU} = 43 \text{ ns}$ $t_{ACC3}(24 \text{ MHz}) = 5^*t_{CL} - t_{AV} - t_{DSU} = 190 \text{ ns}$ $t_{ACC3}(48 \text{ MHz}) = 5^*t_{CL} - t_{AV} - t_{DSU} = 86 \text{ ns}.$



Data Memory Write^[33]

Figure 14. Data Memory Write Timing Diagram

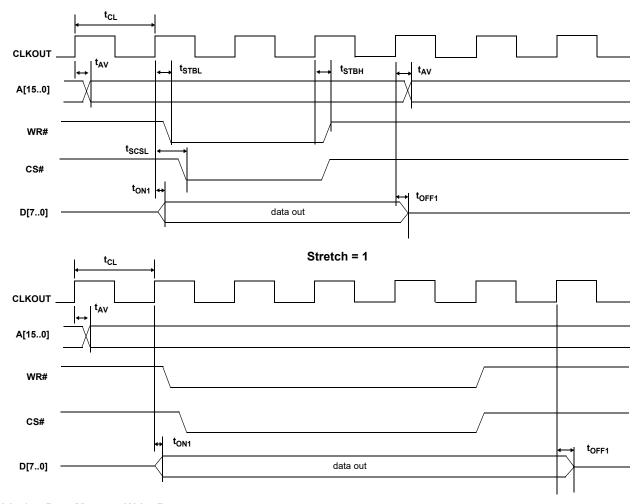


Table 17. Data Memory Write Parameters

Parameter	Description	Min	Max	Unit	Notes
t _{AV}	Delay from clock to valid address	0	10.7	ns	_
t _{STBL}	Clock to WR pulse LOW	0	11.2	ns	_
t _{STBH}	Clock to WR pulse HIGH	0	11.2	ns	_
t _{SCSL}	Clock to CS pulse LOW	_	13.0	ns	_
t _{ON1}	Clock to data turn-on	0	13.1	ns	_
t _{OFF1}	Clock to data hold time	0	13.1	ns	_

When using the AUTPOPTR1 or AUTOPTR2 to address external memory, the address of AUTOPTR1 is only active while either RD# or WR# are active. The address of AUTOPTR2 is active throughout the cycle and meets the address valid time for which is based on the stretch value.

Note

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^{33.} The stretch memory cycle feature enables EZ-USB firmware to adjust the speed of data memory accesses not the program memory accesses. Details including typical strobe width timings can be found in the section 12.1.2 of the Technical Reference Manual. The address cycle width can be interpreted from these.



PORTC Strobe Feature Timings

The RD# and WR# are present in the 100-pin version and the 128-pin package. In these 100-pin and 128-pin versions, an 8051 control bit can be set to pulse the RD# and WR# pins when the 8051 reads from or writes to PORTC. This feature is enabled by setting PORTCSTB bit in CPUCS register.

The RD# and WR# strobes are asserted for two CLKOUT cycles when PORTC is accessed.

The WR# strobe is asserted two clock cycles after PORTC is updated and is active for two clock cycles after that, as shown in Figure 16.

As for read, the value of PORTC three clock cycles before the assertion of RD# is the value that the 8051 reads in. The RD# is pulsed for two clock cycles after three clock cycles from the point when the 8051 has performed a read function on PORTC.

The RD# signal prompts the external logic to prepare the next data byte. Nothing gets sampled internally on assertion of the RD# signal itself; it is just a prefetch type signal to get the next data byte prepared. So, using it with that in mind easily meets the setup time to the next read.

The purpose of this pulsing of RD# is to allow the external peripheral to know that the 8051 is done reading PORTC and the data was latched into PORTC three CLKOUT cycles before asserting the RD# signal. After the RD# is pulsed, the external logic can update the data on PORTC.

Following is the timing diagram of the read and write strobing function on accessing PORTC. Refer to Data Memory Read^[31] on page 44 and Data Memory Write^[33] on page 45 for details on propagation delay of RD# and WR# signals.

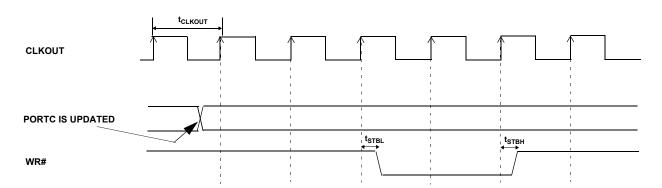
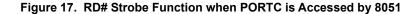
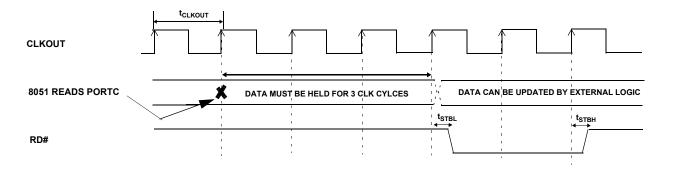


Figure 16. WR# Strobe Function when PORTC is Accessed by 8051





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GPIF Synchronous Signals

Figure 18. GPIF Synchronous Signals Timing Diagram^[34]

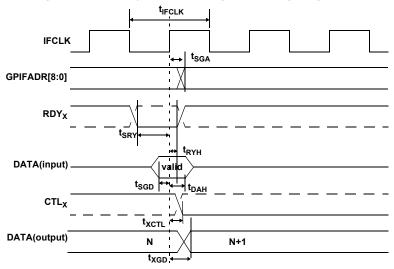


Table 18. GPIF Synchronous Signals Parameters with Internally Sourced IFCLK $^{[34,\,35]}$

Parameter	Description	Min	Max	Ty	/p	Unit
Parameter	Description	IVIIII	IVIAX	Min	Max	Ullit
t _{IFCLK}	IFCLK Period	20.83	_	-	_	ns
t _{SRY}	RDY _X to clock setup time	8.9	_	_	_	ns
t _{RYH}	RDY _X Hold Time	0	_	_	_	ns
t _{SGD}	GPIF data to clock setup time	9.2	_	_	_	ns
t _{DAH}	GPIF data hold time	0	_	_	_	ns
t _{SGA}	Clock to GPIF address propagation delay	_	7.5	_	_	ns
t _{XGD}	Clock to GPIF data output propagation delay	_	10	-	_	ns
t _{XCTL}	Clock to CTL _X output propagation delay	_	6.7	-	_	ns
t _{IFCLKR}	IFCLK rise time	_	_	_	900	ps
t _{IFCLKF}	IFCLK fall time	_	_	_	900	ps
t _{IFCLKOD}	IFCLK output duty cycle	_	_	49	51	%
t _{IFCLKJ}	IFCLK jitter peak to peak	_	_	_	300	ps

Table 19. GPIF Synchronous Signals Parameters with Externally Sourced IFCLK^[35]

Parameter	Description	Min	Max	Unit
t _{IFCLK}	IFCLK period ^[36]	20.83	200	ns
t _{SRY}	RDY _X to clock setup time	2.9	_	ns
t _{RYH}	RDY _X Hold Time	3.7	_	ns
t _{SGD}	GPIF data to clock setup time	3.2	_	ns
t _{DAH}	GPIF data hold time	4.5	_	ns
t _{SGA}	Clock to GPIF address propagation delay	_	11.5	ns
t _{XGD}	Clock to GPIF data output propagation delay	_	15	ns
t _{XCTL}	Clock to CTL _X output propagation delay	_	10.7	ns

Notes

34. Dashed lines denote signals with programmable polarity.
35. GPIF asynchronous RDY_x signals have a minimum setup time of 50 ns when using the internal 48-MHz IFCLK.

36. IFCLK must not exceed 48 MHz.



Slave FIFO Synchronous Read

Figure 19. Slave FIFO Synchronous Read Timing Diagram [37]

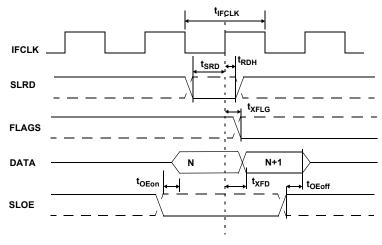


Table 20. Slave FIFO Synchronous Read Parameters with Internally Sourced IFCLK^[38]

Parameter	Description	Min	Max	Ty	/p	Unit
i di dilletei	Description	IVIIII	IVIAX	Min	Max	Unit
t _{IFCLK}	IFCLK period	20.83	-	-	_	ns
t _{SRD}	SLRD to clock setup time	18.7	_	_	_	ns
t _{RDH}	Clock to SLRD hold time	0	-	-	_	ns
t _{OEon}	SLOE turn on to FIFO data valid	-	10.5	_	_	ns
t _{OEoff}	SLOE turn off to FIFO data hold	_	10.5	_	_	ns
t _{XFLG}	Clock to FLAGS output propagation delay	-	9.5	_	_	ns
t _{XFD}	Clock to FIFO data output propagation delay	_	11	_	_	ns
t _{IFCLKR}	IFCLK rise time	_	_	_	900	ps
t _{IFCLKF}	IFCLK fall time	_	_	_	900	ps
t _{IFCLKOD}	IFCLK output duty cycle	-	_	49	51	%
t _{IFCLKJ}	IFCLK jitter peak to peak	_	_	_	300	ps

Table 21. Slave FIFO Synchronous Read Parameters with Externally Sourced IFCLK $^{[38]}$

Parameter	Description	Min	Max	Unit
t _{IFCLK}	IFCLK period	20.83	200	ns
t _{SRD}	SLRD to clock setup time	12.7	_	ns
t _{RDH}	Clock to SLRD hold time	3.7	_	ns
t _{OEon}	SLOE turn on to FIFO data valid	_	10.5	ns
t _{OEoff}	SLOE turn off to FIFO data hold	_	10.5	ns
t _{XFLG}	Clock to FLAGS output propagation delay	-	13.5	ns
t _{XFD}	Clock to FIFO data output propagation delay	-	15	ns

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^{37.} Dashed lines denote signals with programmable polarity.
38. GPIF asynchronous RDY_x signals have a minimum setup time of 50 ns when using the internal 48-MHz IFCLK.



Slave FIFO Asynchronous Read

Figure 20. Slave FIFO Asynchronous Read Timing Diagram [39]

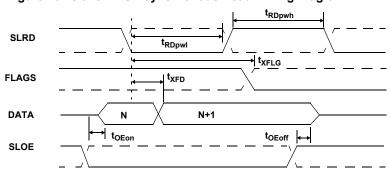


Table 22. Slave FIFO Asynchronous Read Parameters $^{[40]}$

Parameter	Description	Min	Max	Unit
t _{RDpwl}	SLRD pulse width LOW	50	-	ns
t _{RDpwh}	SLRD pulse width HIGH	50	_	ns
t _{XFLG}	SLRD to FLAGS output propagation delay	_	70	ns
t _{XFD}	SLRD to FIFO data output propagation delay	_	15	ns
t _{OEon}	SLOE turn-on to FIFO data valid	_	10.5	ns
t _{OEoff}	SLOE turn-off to FIFO data hold	_	10.5	ns

Notes
39. Dashed lines denote signals with programmable polarity.
40. Slave FIFO asynchronous parameter values use internal IFCLK setting at 48 MHz.



Slave FIFO Synchronous Write

Figure 21. Slave FIFO Synchronous Write Timing Diagram [41]

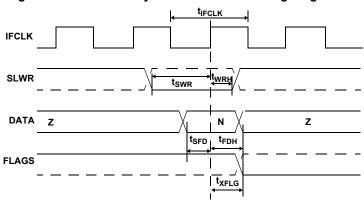


Table 23. Slave FIFO Synchronous Write Parameters with Internally Sourced IFCLK^[42]

Parameter	Description	Min	Max	Unit
t _{IFCLK}	IFCLK period	20.83	_	ns
t _{SWR}	SLWR to clock setup time	10.4	_	ns
t _{WRH}	Clock to SLWR hold time	0	_	ns
t _{SFD}	FIFO data to clock setup time	9.2	_	ns
t _{FDH}	Clock to FIFO data hold time	0	_	ns
t _{XFLG}	Clock to FLAGS output propagation time	-	9.5	ns

Table 24. Slave FIFO Synchronous Write Parameters with Externally Sourced IFCLK^[42]

Parameter	Description	Min	Max	Unit
t _{IFCLK}	IFCLK Period	20.83	200	ns
t _{SWR}	SLWR to clock setup time	12.1	_	ns
t _{WRH}	Clock to SLWR hold time	3.6	_	ns
t _{SFD}	FIFO data to clock setup time	3.2	_	ns
t _{FDH}	Clock to FIFO data hold time	4.5	-	ns
t _{XFLG}	Clock to FLAGS output propagation time	_	13.5	ns

Notes

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^{41.} Dashed lines denote signals with programmable polarity.

^{42.} GPIF asynchronous RDY_x signals have a minimum setup time of 50 ns when using the internal 48-MHz IFCLK.



Slave FIFO Asynchronous Write

Figure 22. Slave FIFO Asynchronous Write Timing Diagram [43]

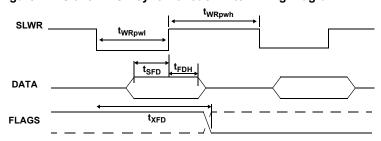


Table 25. Slave FIFO Asynchronous Write Parameters with Internally Sourced IFCLK $^{[44]}$

Parameter	Description	Min	Max	Unit
t _{WRpwl}	SLWR pulse LOW	50	_	ns
t _{WRpwh}	SLWR pulse HIGH	70	_	ns
t _{SFD}	SLWR to FIFO DATA setup time	10	_	ns
t _{FDH}	FIFO DATA to SLWR hold time	10	_	ns
t _{XFD}	SLWR to FLAGS output propagation delay	_	70	ns

^{43.} Dashed lines denote signals with programmable polarity.
44. Slave FIFO asynchronous parameter values use internal IFCLK setting at 48 MHz.



Slave FIFO Synchronous Packet End Strobe

Figure 23. Slave FIFO Synchronous Packet End Strobe Timing Diagram [45]

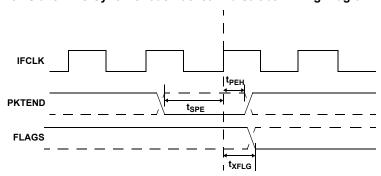


Table 26. Slave FIFO Synchronous Packet End Strobe Parameters with Internally Sourced IFCLK^[46]

Parameter	Description	Min	Max	Unit
t _{IFCLK}	IFCLK period	20.83	_	ns
t _{SPE}	PKTEND to clock setup time	14.6	_	ns
t _{PEH}	Clock to PKTEND hold time	0	_	ns
t _{XFLG}	Clock to FLAGS output propagation delay	1	9.5	ns

Table 27. Slave FIFO Synchronous Packet End Strobe Parameters with Externally Sourced IFCLK^[46]

Parameter	Description	Min	Max	Unit
t _{IFCLK}	IFCLK period	20.83	200	ns
t _{SPE}	PKTEND to clock setup time	8.6	_	ns
t _{PEH}	Clock to PKTEND hold time	2.5	_	ns
t _{XFLG}	Clock to FLAGS output propagation delay	-	13.5	ns

Notes
45. Dashed lines denote signals with programmable polarity.
46. GPIF asynchronous RDY_x signals have a minimum setup time of 50 ns when using the internal 48-MHz IFCLK.



There is no specific timing requirement that should be met for asserting the PKTEND pin to asserting SLWR. PKTEND can be asserted with the last data value clocked into the FIFOs or thereafter. The setup time $t_{\mbox{\footnotesize SPE}}$ and the hold time $t_{\mbox{\footnotesize PEH}}$ must be met.

Although there are no specific timing requirements for PKTEND assertion, there is a specific corner-case condition that needs attention while using the PKTEND pin to commit a one byte or word packet. There is an additional timing requirement that needs to be met when the FIFO is configured to operate in auto mode and it is required to send two packets back to back: a full packet (full defined as the number of bytes in the FIFO meeting the level set in AUTOINLEN register) committed automatically followed by a short one byte or word packet committed manually using the PKTEND pin. In this scenario, the user must ensure to assert PKTEND, at least one clock cycle after the rising edge that

caused the last byte or word to be clocked into the previous auto committed packet. Figure 24 shows this scenario. X is the value the AUTOINLEN register is set to when the IN endpoint is configured to be in auto mode.

Figure 24 shows a scenario where two packets are committed. The first packet gets committed automatically when the number of bytes in the FIFO reaches X (value set in AUTOINLEN register) and the second one byte/word short packet being committed manually using PKTEND.

Note that there is at least one IFCLK cycle timing between the assertion of PKTEND and clocking of the last byte of the previous packet (causing the packet to be committed automatically). Failing to adhere to this timing results in the FX2 failing to send the one byte or word short packet.

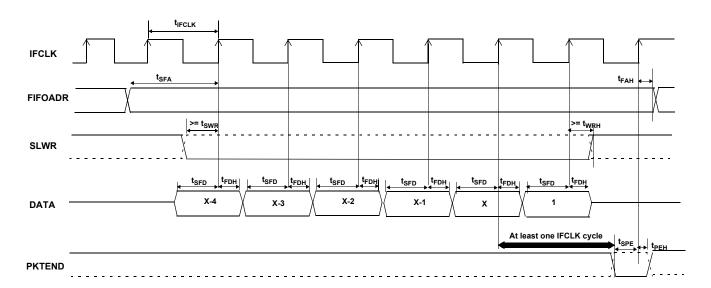


Figure 24. Slave FIFO Synchronous Write Sequence and Timing Diagram^[47]

Note

47. Dashed lines denote signals with programmable polarity.

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Slave FIFO Asynchronous Packet End Strobe

Figure 25. Slave FIFO Asynchronous Packet End Strobe Timing Diagram^[48]

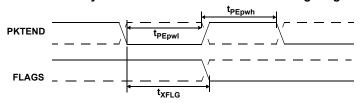


Table 28. Slave FIFO Asynchronous Packet End Strobe Parameters^[49]

Parameter	Description	Min	Max	Unit
t _{PEpwl}	PKTEND pulse width LOW	50	_	ns
t _{PWpwh}	PKTEND pulse width HIGH	50	_	ns
t _{XFLG}	PKTEND to FLAGS output propagation delay	_	115	ns

Slave FIFO Output Enable

Figure 26. Slave FIFO Output Enable Timing Diagram^[48]

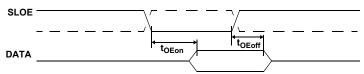


Table 29. Slave FIFO Output Enable Parameters

Parameter	Description	Min	Max	Unit
t _{OEon}	SLOE assert to FIFO DATA output	-	10.5	ns
t _{OEoff}	SLOE deassert to FIFO DATA hold	1	10.5	ns

Slave FIFO Address to Flags/Data

Figure 27. Slave FIFO Address to Flags/Data Timing Diagram^[48]

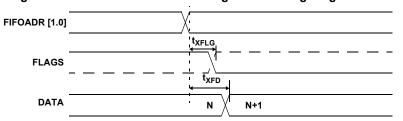


Table 30. Slave FIFO Address to Flags/Data Parameters

Parameter	Description	Min	Max	Unit
t _{XFLG}	FIFOADR[1:0] to FLAGS output propagation delay	_	10.7	ns
t_{XFD}	FIFOADR[1:0] to FIFODATA output propagation delay	_	14.3	ns

Notes

48. Dashed lines denote signals with programmable polarity.
49. Slave FIFO asynchronous parameter values use internal IFCLK setting at 48 MHz.



Slave FIFO Synchronous Address

Figure 28. Slave FIFO Synchronous Address Timing Diagram^[50]

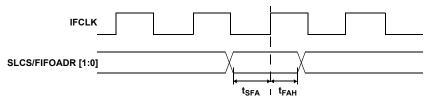


Table 31. Slave FIFO Synchronous Address Parameters^[51]

Parameter	Description	Min	Max	Unit
t _{IFCLK}	Interface clock period	20.83	200	ns
t _{SFA}	FIFOADR[1:0] to clock setup time	25	_	ns
t _{FAH}	Clock to FIFOADR[1:0] hold time	10	_	ns

Slave FIFO Asynchronous Address

Figure 29. Slave FIFO Asynchronous Address Timing Diagram [50]

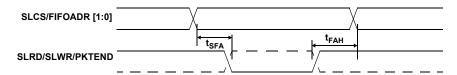


Table 32. Slave FIFO Asynchronous Address Parameters^[52]

Parameter	Description	Min	Max	Unit
t _{SFA}	FIFOADR[1:0] to SLRD/SLWR/PKTEND setup time	10	_	ns
t _{FAH}	RD/WR/PKTEND to FIFOADR[1:0] hold time	10	-	ns

Note

- 50. Dashed lines denote signals with programmable polarity.
- 51. GPIF asynchronous RDY_x signals have a minimum setup time of 50 ns when using the internal 48-MHz IFCLK.
- 52. Slave FIFO asynchronous parameter values use internal IFCLK setting at 48 MHz.



Sequence Diagram

Single and Burst Synchronous Read Example

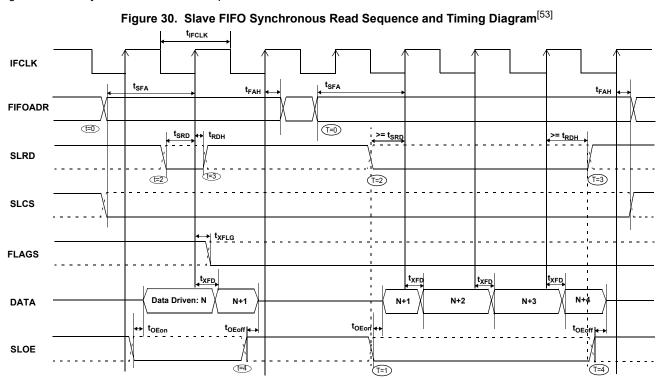


Figure 31. Slave FIFO Synchronous Sequence of Events Diagram

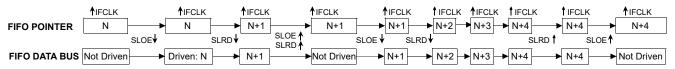


Figure 30 shows the timing relationship of the SLAVE FIFO signals during a synchronous FIFO read using IFCLK as the synchronizing clock. The diagram illustrates a single read followed by a burst read.

(E1)

- At t = 0, the FIFO address is stable and the signal SLCS is asserted (SLCS may be tied LOW in some applications). Note that t_{SFA} has a minimum of 25 ns. This means that when IFCLK is running at 48 MHz, the FIFO address setup time is more than one IFCLK cycle.
- At t = 1, SLOE is asserted. SLOE is an output enable only, whose sole function is to drive the data bus. The data that is driven on the bus is the data that the internal FIFO pointer is currently pointing to. In this example it is the first data value in the FIFO. Note: the data is prefetched and is driven on the bus when SLOE is asserted.
- At t = 2, SLRD is asserted. SLRD must meet the setup time of t_{SRD} (time from asserting the SLRD signal to the rising edge of the IFCLK) and maintain a minimum hold time of t_{RDH} (time from the IFCLK edge to the deassertion of the SLRD signal).

If the SLCS signal is used, it must be asserted before SLRD is

53. Dashed lines denote signals with programmable polarity.

asserted (The SLCS and SLRD signals must both be asserted to start a valid read condition).

■ The FIFO pointer is updated on the rising edge of the IFCLK, while SLRD is asserted. This starts the propagation of data from the newly addressed location to the data bus. After a propagation delay of tXFD (measured from the rising edge of IFCLK) the new data value is present. N is the first data value read from the FIFO. To have data on the FIFO data bus, SLOE MUST also be asserted.

The same sequence of events are shown for a burst read and are marked with the time indicators of T = 0 through 5.

Note For the burst mode, the SLRD and SLOE are left asserted during the entire duration of the read. In the burst read mode, when SLOE is asserted, data indexed by the FIFO pointer is on the data bus. During the first read cycle, on the rising edge of the clock, the FIFO pointer is updated and incremented to point to address N+1. For each subsequent rising edge of IFCLK, while the SLRD is asserted, the FIFO pointer is incremented and the next data value is placed on the data bus.



Figure 32. Slave FIFO Synchronous Write Sequence and Timing Diagram^[54] **IFCLK** t_{SFA} t_{SFA} t_{FAH} t_{FAH} **FIFOADR** t_{SWF} (T=0) t_{WRH} >= t_{SWE} SLWR (T=2) (T=5) (E2) (=3) SLCS t_{XFLG} **FLAGS** t_{FDH} t_{FDH} t_{SFD} t_{FDH} tSFD tSFD N+1 N N+2 N+3 DATA (T=3) (T=4) (t=1) (T=1) t_{SPE} t_{PFH} **PKTEND**

Single and Burst Synchronous Write

Figure 32 shows the timing relationship of the SLAVE FIFO signals during a synchronous write using IFCLK as the synchronizing clock. The diagram illustrates a single write followed by burst write of three bytes and committing all four bytes as a short packet using the PKTEND pin.

- At t = 0 the FIFO address is stable and the signal SLCS is asserted. (SLCS may be tied LOW in some applications) Note that t_{SFA} has a minimum of 25 ns. This means when IFCLK is running at 48 MHz, the FIFO address setup time is more than one IFCLK cycle.
- At t = 1, the external master/peripheral must outputs the data value onto the data bus with a minimum set up time of t_{SFD} before the rising edge of IFCLK.
- At t = 2, SLWR is asserted. The SLWR must meet the setup time of t_{SWR} (time from asserting the SLWR signal to the rising edge of IFCLK) and maintain a minimum hold time of twent (time from the IFCLK edge to the deassertion of the SLWR signal). If the SLCS signal is used, it must be asserted with SLWR or before SLWR is asserted (The SLCS and SLWR signals must both be asserted to start a valid write condition).
- While the SLWR is asserted, data is written to the FIFO and on the rising edge of the IFCLK, the FIFO pointer is incremented. The FIFO flag is also updated after a delay of t_{XFI G} from the rising edge of the clock.

The same sequence of events are also shown for a burst write and are marked with the time indicators of T = 0 through 5.

Note For the burst mode, SLWR and SLCS are left asserted for the entire duration of writing all the required data values. In this burst write mode, after the SLWR is asserted, the data on the

54. Dashed lines denote signals with programmable polarity.

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FIFO data bus is written to the FIFO on every rising edge of IFCLK. The FIFO pointer is updated on each rising edge of IFCLK. In Figure 32, after the four bytes are written to the FIFO, SLWR is deasserted. The short 4 byte packet can be committed to the host by asserting the PKTEND signal.

There is no specific timing requirement that should be met for asserting PKTEND signal with regards to asserting the SLWR signal. PKTEND can be asserted with the last data value or thereafter. The only requirement is that the setup time t_{SPE} and the hold time t_{PFH} must be met. In the scenario of Figure 32, the number of data values committed includes the last value written to the FIFO. In this example, both the data value and the PKTEND signal are clocked on the same rising edge of IFCLK. PKTEND can also be asserted in subsequent clock cycles. The FIFOADDR lines should be held constant during the PKTEND assertion.

Although there are no specific timing requirement for the PKTEND assertion, there is a specific corner-case condition that needs attention while using the PKTEND to commit a one byte/word packet. Additional timing requirements exist when the FIFO is configured to operate in auto mode and it is desired to send two packets: a full packet ('full' defined as the number of bytes in the FIFO meeting the level set in the AUTOINLEN register) committed automatically followed by a short one byte or word packet committed manually using the PKTEND pin.

In this case, the external master must ensure to assert the PKTEND pin at least one clock cycle after the rising edge that caused the last byte or word that needs to be clocked into the previous auto committed packet (the packet with the number of bytes equal to what is set in the AUTOINLEN register). Refer to Figure 24 on page 53 for further details on this timing.



Sequence Diagram of a Single and Burst Asynchronous Read

t_{FAH} tSFA t_{FAH} **FIFOADR** T=0t_{RDpwh} t_{RDpwh} t_{RDpw} t_{RDpwl} t_{RDp}v t_{RDpwl} t_{RDpwl} SLRD (f=3) (T=5) **SLCS** t_{XFI G} FLAGS t_{XFD} txFD t_{XFD} Data (X) DATA Ν N+1 N+2 N+3 Driven t_{OFof} SLOE (T=1) (T=7) (E1)

Figure 33. Slave FIFO Asynchronous Read Sequence and Timing Diagram^[55]

Figure 34. Slave FIFO Asynchronous Read Sequence of Events Diagram

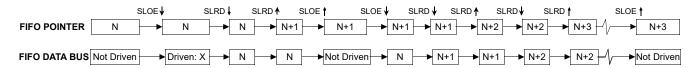


Figure 33 shows the timing relationship of the SLAVE FIFO signals during an asynchronous FIFO read. It shows a single read followed by a burst read.

- At t = 0, the FIFO address is stable and the SLCS signal is asserted.
- At t = 1, SLOE is asserted. This results in the data bus being driven. The data that is driven on to the bus is the previous data, the data that was in the FIFO from an earlier read cycle.
- At t = 2, SLRD is asserted. The SLRD must meet the minimum active pulse of t_{RDpwl} and minimum de-active pulse width of t_{RDpwh}. If SLCS is used, then SLCS must be asserted before SLRD is asserted (The SLCS and SLRD signals must both be asserted to start a valid read condition.)

■ The data that is driven, after asserting SLRD, is the updated data from the FIFO. This data is valid after a propagation delay of t_{XFD} from the activating edge of SLRD. In Figure 33, data N is the first valid data read from the FIFO. For data to appear on the data bus during the read cycle (SLRD is asserted), SLOE must be in an asserted state. SLRD and SLOE can also be tied together.

The same sequence of events is also shown for a burst read marked with T = 0 through 5.

Note In the burst read mode, during SLOE is asserted, the data bus is in a driven state and outputs the previous data. After SLRD is asserted, the data from the FIFO is driven on the data bus (SLOE must also be asserted) and then the FIFO pointer is incremented.

Note

55. Dashed lines denote signals with programmable polarity.

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Sequence Diagram of a Single and Burst Asynchronous Write

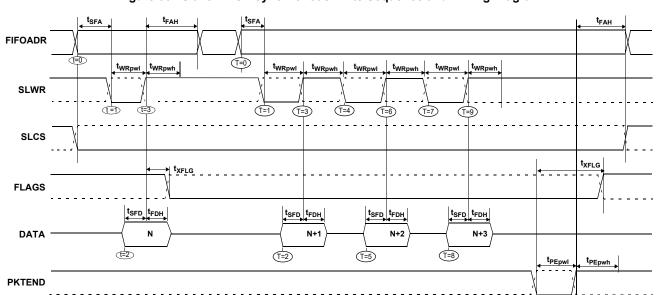


Figure 35. Slave FIFO Asynchronous Write Sequence and Timing Diagram^[56]

Figure 35 shows the timing relationship of the SLAVE FIFO write in an asynchronous mode. The diagram shows a single write followed by a burst write of 3 bytes and committing the 4byte short packet using PKTEND.

- At t = 0 the FIFO address is applied, ensuring that it meets the setup time of t_{SFA}. If SLCS is used, it must also be asserted (SLCS may be tied LOW in some applications).
- At t = 1 SLWR is asserted. SLWR must meet the minimum active pulse of t_{WRpwl} and minimum de-active pulse width of t_{WRpwh}. If the SLCS is used, it must be asserted with SLWR or before SLWR is asserted.
- At t = 2, data must be present on the bus t_{SFD} before the deasserting edge of SLWR.
- At t = 3, deasserting SLWR causes the data to be written from the data bus to the FIFO and then increments the FIFO pointer.

The FIFO flag is also updated after t_{XFLG} from the deasserting edge of SLWR.

The same sequence of events is shown for a burst write and is indicated by the timing marks of T=0 through 5.

Note In the burst write mode, after SLWR is deasserted, the data is written to the FIFO and then the FIFO pointer is incremented to the next byte in the FIFO. The FIFO pointer is post incremented.

In Figure 35, after the four bytes are written to the FIFO and SLWR is deasserted, the short 4-byte packet can be committed to the host using PKTEND. The external device should be designed to not assert SLWR and the PKTEND signal at the same time. It should be designed to assert the PKTEND after SLWR is deasserted and met the minimum deasserted pulse width. The FIFOADDR lines have to held constant during the PKTEND assertion.

Note

56. Dashed lines denote signals with programmable polarity.

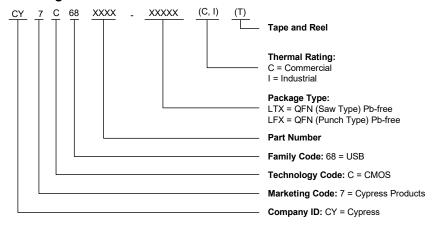


Ordering Information

Table 33. Ordering Information

Ordering Code	Package Type	RAM Size	# Prog I/Os	8051 Address /Data Bus	Serial Debug ^[57]
Ideal for Battery Powered Ap	plications	•	•		
CY7C68014A-128AXC	128 TQFP – Pb-free	16K	40	16-/8-bit	Y
CY7C68014A-100AXC	100 TQFP – Pb-free	16K	40	_	Y
CY7C68014A-56PVXC	56 SSOP – Pb-free	16K	24	_	N
CY7C68014A-56LTXC	56 QFN - Pb-free	16K	24	_	N
CY7C68016A-56LTXC	56 QFN - Pb-free	16K	26	_	N
CY7C68016A-56LTXCT	56 QFN - Pb-free	16K	26	_	N
Ideal for Non Battery Powere	ed Applications	•	•		
CY7C68013A-128AXC	128 TQFP – Pb-free	16K	40	16-/8-bit	Y
CY7C68013A-128AXI	128 TQFP – Pb-free (Industrial)	16K	40	16-/8-bit	Y
CY7C68013A-100AXC	100 TQFP – Pb-free	16K	40	_	Y
CY7C68013A-100AXI	100 TQFP – Pb-free (Industrial)	16K	40	_	Y
CY7C68013A-56PVXC	56 SSOP – Pb-free	16K	24	_	N
CY7C68013A-56PVXCT	56 SSOP – Pb-free	16K	24	_	N
CY7C68013A-56PVXI	56 SSOP – Pb-free (Industrial)	16K	24	_	N
CY7C68013A-56BAXC	56 VFBGA – Pb-free	16K	24	_	N
CY7C68013A-56BAXCT	56 VFBGA – Pb-free	16K	24	_	N
CY7C68013A-56LTXC	56 QFN – Pb-free	16K	24	_	N
CY7C68013A-56LTXCT	56 QFN – Pb-free	16K	24	_	N
CY7C68013A-56LTXI	56 QFN – Pb-free (Industrial)	16K	24	_	N
CY7C68015A-56LTXC	56 QFN – Pb-free	16K	26	_	N
Development Tool Kit		•	•		
CY3684	EZ-USB FX2LP development kit				
CY3689	EZ-USB FX2LP Discovery Kit				
Reference Design Kit					
CY4611B	USB 2.0 to ATA/ATAPI reference	design using	EZ-USB FX2L	.P	

Ordering Code Definitions



Note

57. As UART is not available in the 56-pin package of CY7C68013A, serial port debugging using Keil Monitor is not possible.

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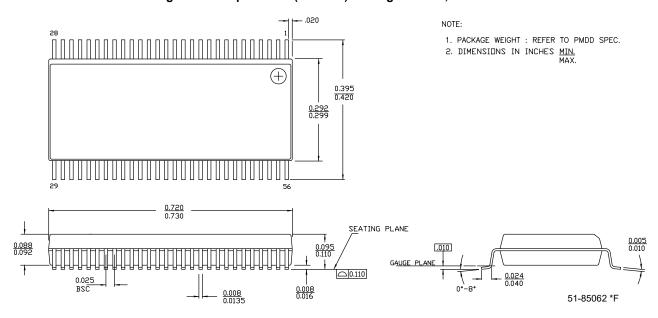


Package Diagrams

The FX2LP is available in five packages:

- 56-pin SSOP
- 56-pin QFN
- 100-pin TQFP
- 128-pin TQFP
- 56-ball VFBGA

Figure 36. 56-pin SSOP (300 Mils) Package Outline, 51-85062



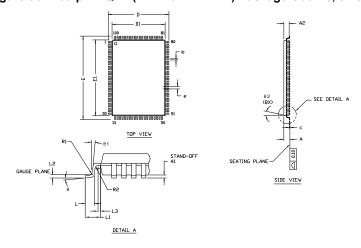
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TOP VIEW BOTTOM VIEW SIDE VIEW -0.900±0.100 8.00±0.10 - 0.200 REF. 43 56 42 000000000 PIN 1 DOT 8.00±0.10 14 29 <u>nahanananahan</u> 0.0 +0.05 28 SEATING PLANE NOTES: 0.40±0.10 1. \bowtie HATCH AREA IS SOLDERABLE EXPOSED METAL. 4.50±0.10 2. REFERENCE JEDEC#: MO-220 3. PACKAGE WEIGHT: $162 \pm 16 \text{ mg}$ 001-53450 *E

Figure 37. 56-pin QFN ((8 × 8 × 1 mm) 4.5 × 5.2 E-Pad (Sawn)) Package Outline, 001-53450

Figure 38. 100-pin TQFP (14 × 20 × 1.4 mm) Package Outline, 51-85050



SYMBOL	DIMENSIONS		ONS	NOTE:
STWIDOL	MIN.	NOM.	MAX.	1 ALL DIMENSIONS ARE IN MILLIMETERS
Α	I —	_	1.60	2 BODY LENGTH DIMENSION DOES NOT
A1	0.05	_	0.15	
A2	1.35	1.40	1.45	INCLUDE MOLD PROTRUSION/END FLASH.
D	15.80	16.00	16.20	MOLD PROTRUSION/END FLASH SHALL
D1	13.90	14.00	14.10	NOT EXCEED 0.0098 in (0.25 mm) PER SIDE.
E	21.80	22.00	22.20	BODY LENGTH DIMENSIONS ARE MAX PLAST
E1	19.90	20.00	20.10	BODY SIZE INCLUDING MOLD MISMATCH.
R1	0.08	_	0.20	3. JEDEC SPECIFICATION NO. REF: MS-026.
R2	0.08	_	0.20	
θ	0°	_	7°	
θ1	0°	_	_	
θ2	11°	12°	13°	
С	_	_	0.20	
b	0.22	0.30	0.38	

1.00 REF

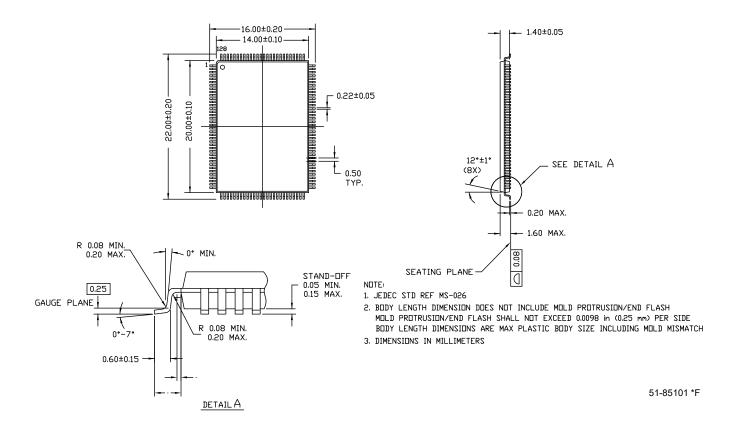
51-85050 *G

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4. ALL DIMENSIONS ARE IN MILLIMETERS



Figure 39. 128-pin TQFP (14 × 20 × 1.4 mm) Package Outline, 51-85101

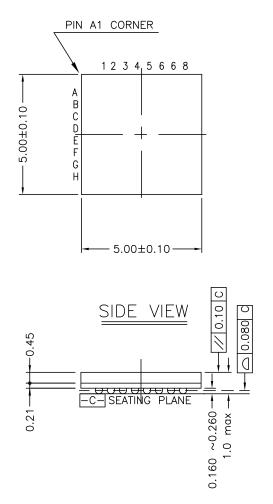


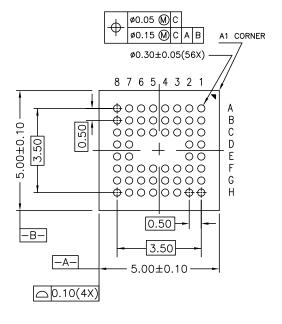
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Figure 40. 56-ball VFBGA (5 × 5 × 1.0 mm) 0.50 Pitch, 0.30 Ball Package Outline, 001-03901

TOP VIEW





BOTTOM VIEW

REFERENCE JEDEC: MO-195C PACKAGE WEIGHT: 0.02 grams

001-03901 *F

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PCB Layout Recommendations

Follow these recommendations to ensure reliable high-performance operation: $\ensuremath{^{[58]}}$

- Four-layer, impedance-controlled boards are required to maintain signal quality.
- Specify impedance targets (ask your board vendor what they can achieve).
- To control impedance, maintain trace widths and trace spacing.
- Minimize stubs to minimize reflected signals.
- Connections between the USB connector shell and signal ground must be near the USB connector.

- Bypass and flyback caps on VBUS, near connector, are recommended.
- DPLUS and DMINUS trace lengths should be kept to within 2 mm of each other in length, with preferred length of 20 to 30 mm.
- Maintain a solid ground plane under the DPLUS and DMINUS traces. Do not allow the plane to split under these traces.
- Do not place vias on the DPLUS or DMINUS trace routing.
- Isolate the DPLUS and DMINUS traces from all other signal traces by no less than 10 mm.

Note

58. Source for recommendations: EZ-USB FX2™PCB Design Recommendations, http://www.cypress.com and High Speed USB Platform Design Guidelines, http://www.usb.org/developers/docs/hs_usb_pdg_r1_0.pdf.



Quad Flat Package No Leads (QFN) Package Design Notes

Electrical contact of the part to the PCB is made by soldering the leads on the bottom surface of the package to the PCB. Therefore, special attention is required to the heat transfer area below the package to provide a good thermal bond to the circuit board. Design a copper (Cu) fill in the PCB as a thermal pad under the package. Heat is transferred from the FX2LP through the device's metal paddle on the bottom side of the package. Heat from here is conducted to the PCB at the thermal pad. It is then conducted from the thermal pad to the PCB inner ground plane by a 5 × 5 array of via. A via is a plated-through hole in the PCB with a finished diameter of 13 mil. The QFN's metal die paddle must be soldered to the PCB's thermal pad. Solder mask is placed on the board top side over each via to resist solder flow into the via. The mask on the top side also minimizes outgassing during the solder reflow process.

For further information on this package design, refer to application notes for Surface Mount Assembly of Amkor's MicroLeadFrame (MLF) Packages. You can find this on Amkor's website http://www.amkor.com.

This application note provides detailed information about board mounting guidelines, soldering flow, rework process, etc.

Figure 41 shows a cross-sectional area underneath the package. The cross section is of only one via. The solder paste template should be designed to allow at least 50% solder coverage. The thickness of the solder paste template should be 5 mil. Use the No Clean type 3 solder paste for mounting the part. Nitrogen purge is recommended during reflow.

Figure 42 is a plot of the solder mask pattern and Figure 43 displays an X-Ray image of the assembly (darker areas indicate solder).

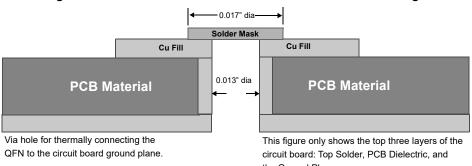


Figure 41. Cross-section of the Area Underneath the QFN Package

Figure 42. Plot of the Solder Mask (White Area)

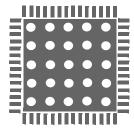
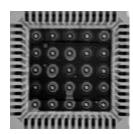


Figure 43. X-ray Image of the Assembly



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Acronyms

Table 34. Acronyms Used in this Document

Acronym	Description
ASIC	application-specific integrated circuit
ATA	advanced technology attachment
DID	device identifier
DSL	digital service line
DSP	digital signal processor
ECC	error correction code
EEPROM	electrically erasable programmable read only memory
EPP	enhanced parallel port
FIFO	first in first out
GPIF	general programmable interface
GPIO	general purpose input output
I/O	input output
LAN	local area network
MPEG	moving picture experts group
PCMCIA	personal computer memory card international association
PID	product identifier
PLL	phase locked loop
QFN	quad flat no leads
RAM	random access memory
SIE	serial interface engine
SOF	start of frame
SSOP	super small outline package
TQFP	thin quad flat pack
USART	universal serial asynchronous receiver/transmitter
USB	universal serial bus
UTOPIA	universal test and operations physical-layer interface
VFBGA	very fine ball grid array
VID	vendor identifier

Document Conventions

Units of Measure

Table 35. Units of Measure

Symbol	Unit of Measure		
kHz	kilohertz		
mA	milliamperes		
Mbps	megabits per second		
MBPs	megabytes per second		
MHz	megahertz		
uA	microamperes		
V	volts		

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Errata

This section describes the errata for the EZ-USB[®] FX2LP™ CY7C68013A/14A/15A/16A Rev. B silicon. Details include errata trigger conditions, scope of impact, available workaround, and silicon revision applicability.

Contact your local Cypress Sales Representative if you have questions.

Part Numbers Affected

Part Number	Package Type	Operating Range
CY7C68013A	All	Commercial
CY7C68014A	All	Commercial
CY7C68015A	All	Commercial
CY7C68016A	All	Commercial

CY7C68013A/14A/15A/16A Qualification Status

In production

CY7C68013A/14A/15A/16A Errata Summary

This table defines the errata for available CY7C68013A/14A/15A/16A family devices. An "X" indicates that the errata pertain to the selected device.

Items	CY7C68013A/14A/15A/16A	Silicon Revision	Fix Status
[1.]. Empty Flag Assertion	X	В	No silicon fix planned currently. Use the workaround.

1. Empty Flag Assertion

■ Problem Definition

In Slave FIFO Asynchronous Word Wide mode, if a single word data is transferred from the USB host to EP2, configured as OUT Endpoint (EP) in the first transaction, then the Empty flag behaves incorrectly. This does not happen if the data size is more than one word in the first transaction.

■ Parameters Affected

NA

■ Trigger Condition(S)

In Slave FIFO Asynchronous Word Wide Mode, after firmware boot and initialization, EP2 OUT endpoint empty flag indicates the status as 'Empty'. When data is received in EP2, the status changes to 'Not-Empty'. However, if data transferred to EP2 is a single word, then asserting SLRD with FIFOADR pointing to any other endpoint changes 'Not-Empty' status to 'Empty' for EP2 even though there is a word data (or it is untouched). This is noticed only when the single word is sent as the first transaction and not if it follows a multi-word packet as the first transaction.

■ Scope of Impact

External interface does not see data available in EP2 OUT endpoint and can end up waiting for data to be read.

■ Workaround

One of the following workarounds can be used:

- Send a pulse signal to the SLWR pin, with FIFOADR pins pointing to an endpoint other than EP2, after firmware initialization and before or after transferring the data to EP2 from the host
- Set the length of the first data to EP2 to be more than a word
- Prioritize EP2 read from the Master for multiple OUT EPs and single word write to EP2
- · Write to an IN EP, if any, from the Master before reading from other OUT EPs (other than EP2) from the Master.

■ Fix Status

There is no silicon fix planned for this currently; use the workarounds provided.

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Document History Page

Document Title: CY7C68013A/CY7C68014A/CY7C68015A/CY7C68016A, EZ-USB FX2LP USB Microcontroller High-Speed USB Peripheral Controller Document Number: 38-08032

Devi	ECN No.	Submission	Department of Change
Rev.	ECN NO.	Date	Description of Change
**	124316	03/17/2003	New data sheet (Advance Information).
*A	128461	09/02/2003	Updated Document Title to read as "CYTC68013A/CY7C68015A, EZ-USB FX2LP™ USB Microcontroller High-Speed USB Peripheral Controller". Changed status from Advance Information to Final. Added CY7C68015A part related information in all instances across the document. Replaced I²C-compatible with I²C in all instances across the document. Updated Logic Block Diagram (Added ECC block and fixed errors). Updated Functional Overview: Updated 8051 Microprocessor: Updated 8051 Clock Frequency: Added Figure 1. Updated Reset and Wakeup: Updated Reset Pin: Updated Reset Pin: Updated Register Addresses: Updated figure below the heading. Updated Endpoint RAM: Updated Endpoint Configurations (Hi-Speed Mode): Updated Figure 5 (for clarity). Added ECC Generation. Updated I²C Controller: Added "I²C Software Reset". Updated Compatible with Previous Generation EZ-USB FX2: Updated Register Summary: Updated Register Summary: Updated Register Summary: Updated Table 12. Updated Table 12. Updated Pokage Diagrams: spec 51-85144 - Changed revision from *B to *D. Minor grammatical edits across the document.
*B	130335	10/09/2003	Changed status from Final to Preliminary.
*C	131673	02/12/2004	Updated Functional Overview: Updated Reset and Wakeup: Updated Reset Pin: Updated description; added Note 7 and referred the same note at the end of sentence "If the crystal input pin is driven by a clock signal the internal PLL stabilizes in 200 µs after V _{CC} has reached 3.0 Volts" Updated Endpoint RAM: Updated Endpoint Configurations (Hi-Speed Mode): Updated description (Replaced column 9 with column 8 in last paragraph). Updated ECC Generation: Updated description. Removed "ECC Features". Updated description. Updated description. Updated Register Summary: Updated Register Summary: Updated Table 12.
*C (cont.)	131673	02/12/2004	Updated DC Electrical Characteristics: Updated Table 14: Added V _{IH, X} , V _{IL, X} parameters and their corresponding details. Updated USB Transceiver: Replaced "certified" with "compliant". Updated AC Electrical Characteristics: Updated USB Transceiver: Replaced "certified" with "compliant". Updated Data Memory Write ^[33] : Updated Data Memory Write ^[33] : Updated Figure 14. Added Sequence Diagram. Updated Ordering Information: Updated Table 33: Updated part numbers.
*D	230713	06/09/2004	Updated Ordering Information: Updated Table 33: Updated part numbers (Changed Lead free MPNs as per spec change in 28-00054).

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Document Title: CY7C68013A/CY7C68014A/CY7C68015A/CY7C68016A, EZ-USB FX2LP USB Microcontroller High-Speed USB Peripheral Controller

Document Number: 38-08032

Document	Oocument Number: 38-08032					
Rev.	ECN No.	Submission Date	Description of Change			
*E	242398	07/13/2004	Minor Change: Post to external web,			
*F	271169	10/07/2004	Updated Features: Added "USB 2.0–USB-IF high speed certified (TID # 40440111)". Added Features (CY7C68013A/14A only). Added Features (CY7C68015A/16A only). Updated Logic Block Diagram (Added USB 2.0 logo). Updated Absolute Maximum Ratings: Replaced TBD with values for "Power Dissipation". Updated DC Electrical Characteristics: Updated Table 14: Updated minimum and maximum values of V _{CC} parameter. Replaced TBD with values for V _{IH, X} , V _{IL, X} , I _{SUSP} , I _{CC} parameters. Updated AC Electrical Characteristics: Updated AC Electrical Characteristics: Updated Slave FIFO Asynchronous Packet End Strobe: Updated Table 28: Changed maximum value of t _{XFLG} parameter from 70 ns to 115 ns. Updated Table 33: Updated part numbers.			
*G	316313	02/04/2005	Updated Document Title to read as "CY7C68013A/CY7C68014A/CY7C68015A/CY7C68016A, EZ-USB FX2LP™ USB Microcontroller High-Speed USB Peripheral Controller". Changed status from Preliminary to Final. Added CY7C68014A, CY7C68016A part related information in all instances across the document. Updated DC Electrical Characteristics: Updated Table 14: Added V _{CC} Ramp Up parameter and its corresponding details. Updated AC Electrical Characteristics: Updated AC Electrical Characteristics: Updated Slave FIFO Synchronous Packet End Strobe: Added description; and also added Figure 24. Updated Ordering Information: Updated Table 33: Updated part numbers.			
*H	338901	04/18/2005	Updated Register Summary: Updated Table 12. Updated AC Electrical Characteristics: Updated Data Memory Read ^[31] : Added description. Updated Data Memory Write ^[33] : Added description. Updated Slave FIFO Synchronous Read: Updated Table 20: Replaced TBD with "-" under "Min" column corresponding to t _{XFD} parameter. Updated Ordering Information: Updated Table 33: Updated part numbers.			
*	371097	06/09/2005	Updated AC Electrical Characteristics: Added PORTC Strobe Feature Timings.			
*J	397239	09/19/2005	Added 56-pin VFBGA Package related information in all instances across the document. Updated Register Summary: Updated Table 12. Updated DC Electrical Characteristics: Updated Table 14: Updated minimum and maximum values of V _{CC} parameter. Updated Ordering Information: Updated Table 33: Updated part numbers. Updated Package Diagrams: Added spec 001-03901 *B.			

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Document Title: CY7C68013A/CY7C68014A/CY7C68015A/CY7C68016A, EZ-USB FX2LP USB Microcontroller High-Speed USB Peripheral Controller Document Number: 38-08032

Documer	Document Number: 38-08032						
Rev.	ECN No.	Submission Date	Description of Change				
*K	420505	02/09/2006	Updated Pin Assignments: Updated description (Replaced "four package types" with "five package types"). Updated Absolute Maximum Ratings: Added "Ambient Temperature with Power Supplied (Industrial)" and its corresponding details. Added Thermal Characteristics. Updated AC Electrical Characteristics: Updated Slave FIFO Asynchronous Write: Updated Figure 22 (Remove SLCS). Updated Sequence Diagram: Updated Sequence Diagram: Updated Single and Burst Synchronous Write: Updated description. Updated Sequence Diagram of a Single and Burst Asynchronous Read: Updated description. Updated to new template.				
*L	2064406	02/04/2008	Updated Features: Replaced "TID # 40440111" with "TID # 40460272". Updated Functional Overview: Updated CY7C68013A/14A and CY7C68015A/16A Differences: Updated Table 10 (Removed T0OUT and T1OUT in "CY7C68015A/CY7C68016A" column). Updated AC Electrical Characteristics: Updated Slave FIFO Synchronous Write: Updated Table 23 (Updated minimum value of t _{SWR} parameter). Updated Package Diagrams: spec 51-85144 – Changed revision from *D to *G.				
*M	2710327	05/22/2009	Updated Operating Conditions: Changed value of F _{OSC} (oscillator or crystal frequency) from "24 MHz ± 100 ppm, Parallel Resonant" to "24 MHz ± 10 ppm, Parallel Resonant". Updated Ordering Information: Updated Table 33: Updated part numbers. Updated Package Diagrams: Added spec 51-85187 *C.				
*N	2727334	07/01/2009	Updated Package Diagrams: spec 51-85187 – Changed revision from *C to *D. Fixed Typo in Document History Page (Removed sentence on E-Pad size change from *F revision).				
*0	2756202	08/26/2009	Updated Ordering Information: Updated Table 33: No change in part numbers. Added a column "Serial Debug" and added details under the column. Added Note 57 and referred the same note in "Serial Debug".				
*P	2785207	10/12/2009	Updated Ordering Information: Updated Table 33: No change in part numbers. Updated details in "Package Type" column (Added information on Pb-free parts).				
*Q	2811890	11/20/2009	Updated Ordering Information: Updated Table 33: Updated part numbers. Updated details under "# Program I/Os" column for CY7C68016A-56LTXC and CY7C68016A-56LTXCT MPNs.				
*R	2896281	03/19/2010	Updated Ordering Information: Updated Table 33: Updated part numbers. Updated Package Diagrams: spec 51-85062 – Changed revision from *C to *D. spec 51-85144 – Changed revision from *G to *H. spec 51-85187 – Changed revision from *D to *E. spec 51-85050 – Changed revision from *B to *C. spec 51-85101 – Changed revision from *C to *D. Updated to new template.				

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Document Title: CY7C68013A/CY7C68014A/CY7C68015A/CY7C68016A, EZ-USB FX2LP USB Microcontroller High-Speed USB Peripheral Controller

Document Number: 38-08032

ov E			
ev. E	CN No.	Submission Date	Description of Change
*S 3(8035980	09/22/2010	Updated Operating Conditions: Changed value of F _{OSC} (oscillator or crystal frequency) from "24 MHz ± 10 ppm, Parallel Resonant" to "24 MHz ± 100 ppm, Parallel Resonant". Updated Ordering Information: Updated Table 33: No change in part numbers. Added Ordering Code Definitions. Added Acronyms and Units of Measure. Updated to new template.
*T 3	3161410	02/03/2011	Updated Package Diagrams: Removed spec 51-85144 *H. Added spec 001-12921 *A. Removed spec 51-85187 *E. Added spec 001-53450 *B. spec 51-85050 — Changed revision from *C to *D. spec 51-85101 — Changed revision from *D to *E. Completing Sunset Review.
*U 3:	195232	03/14/2011	Updated table numbering. Updated Thermal Characteristics: Updated Table 13 (Removed column "0Ca Case to Ambient Temperature (°C/W)"). Updated AC Electrical Characteristics: Updated GPIF Synchronous Signals: Updated Table 18 (Added a column "Typ" and added values in that column). Updated Slave FIFO Synchronous Read: Updated Table 20 (Added a column "Typ" and added values in that column). Updated Package Diagrams: spec 001-12921 – Changed revision from *A to *B. spec 001-03901 – Changed revision from *C to *D.
*V 3:	3512313	02/01/2012	Updated Ordering Information: Updated Table 33: Updated part numbers. Updated Package Diagrams: spec 51-85062 - Changed revision from *D to *E. Removed spec 001-12921 *B. spec 001-03901 - Changed revision from *D to *E. Completing Sunset Review.
W 39	998554	07/19/2013	Added Errata footnote (Note 6). Updated Functional Overview: Updated Interrupt System: Updated FIFO/GPIF Interrupt (INT4): Added Note 6 and referred the same note in "Endpoint 2 empty flag" in Table 4. Updated Package Diagrams: spec 51-85062 – Changed revision from *E to *F. spec 001-53450 – Changed revision from *B to *C. Added Errata. Updated to new template.
*X 41	9617527	01/15/2015	Added More Information. Updated Pin Assignments: Updated CY7C68013A/15A Pin Descriptions: Updated Table 11 (Added a column "Reset" and added details in that column). Updated AC Electrical Characteristics: Updated Data Memory Read[31]: Added Note 31 and referred the same note in heading. Updated Figure 13. Updated Data Memory Write[33]: Added Note 31 and referred the same note in heading. Updated Package Diagrams: spec 001-53450 – Changed revision from *C to *D. spec 51-85050 – Changed revision from *D to *E. spec 51-85101 – Changed revision from *E to *F. Updated to new template. Completing Sunset Review.
'Y 5	317277	06/28/2016	Updated to new template.
W 39	3998554	07/19/2013	Updated Table 13 (Removed column "6Ca Case to Ambient Temperature (°C/W)"). Updated AC Electrical Characteristics: Updated GPIF Synchronous Signals: Updated Table 18 (Added a column "Typ" and added values in that column). Updated Slave FIFO Synchronous Read: Updated Table 20 (Added a column "Typ" and added values in that column). Updated Package Diagrams: spec 001-12921 - Changed revision from *A to *B. spec 001-03901 - Changed revision from *C to *D. Updated Ordering Information: Updated Table 33: Updated part numbers. Updated Package Diagrams: spec 51-85062 - Changed revision from *D to *E. Removed spec 001-12921 *B. spec 001-03901 - Changed revision from *D to *E. Completing Sunset Review. Added Errata footnote (Note 6). Updated Finctional Overview: Updated Finctional Overview: Updated Finctional Overview: Updated Finctional Overview: Updated Package Diagrams: spec 51-85062 - Changed revision from *E to *F. spec 001-53450 - Changed revision from *B to *C. Added Errata. Updated Package Diagrams: spec 51-85062 - Changed revision from *B to *C. Added Errata. Updated Pin Assignments: Updated Pin Assignments: Updated Pin Assignments: Updated Table 11 (Added a column "Reset" and added details in that column). Updated AC Electrical Characteristics: Updated Data Memory Read ⁽³¹⁾ : Added Note 31 and referred the same note in heading. Updated Figure 13. Updated Package Diagrams: spec 51-85450 - Changed revision from *C to *D.



Document Title: CY7C68013A/CY7C68014A/CY7C68015A/CY7C68016A, EZ-USB FX2LP USB Microcontroller High-Speed USB Peripheral Controller Document Number: 38-08032

Rev. ECN No. Submission Date Description of Change

200	ocument Number: 00-00002				
Rev.	ECN No.	Submission Date	Description of Change		
*Z	5713641	04/26/2017	Updated Package Diagrams: spec 51-85050 – Changed revision from *E to *G. Updated to new template.		
AA	5930426	11/09/2017	Updated AC Electrical Characteristics: Updated GPIF Synchronous Signals: Updated Table 18. Updated Table 19.		
AB	6403695	12/06/2018	Updated Features: Added Note 1 and referred the note at the end in "Integrated I ² C controller; runs at 100 or 400 kHz". Updated Functional Overview: Updated I ² C Bus: Added Note 4 and referred the note at the end in "FX2LP supports the I ² C bus as a master only at 100/400 kHz". Updated Thermal Characteristics: Added "Maximum junction temperature" and its corresponding details. Updated Package Diagrams: spec 001-53450 — Changed revision from *D to *E. Updated to new template. Completing Sunset Review.		
AC	6637530	07/26/2019	Updated to new template.		
AD	7113265	04/30/2021	Updated EZ-USB FX2LP Development Kit in More Information. Added "CY3689" in Ordering Information.		

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