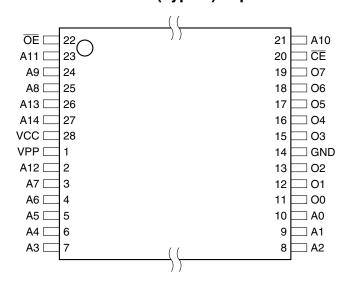
2. Pin Configurations

Pin Name	Function
A0 - A14	Addresses
00 - 07	Outputs
CE	Chip Enable
ŌĒ	Output Enable
NC	No Connect

2.1 28-lead SOIC Top View

VPP 🗔	1	28	
A12 🗔	2	27	🗌 A14
A7 🗔	3	26	🗌 A13
A6 🗔	4	25	🗆 A8
A5 🗔	5	24	🗆 A9
A4 🗔	6	23	🗌 A11
A3 🗔	7	22	
A2 🗔	8	21	🗌 A10
A1 🗔	9	20	
A0 🗔	10	19	07
O0 🗔	11	18	O6
01 🗔	12	17	O5
02 🗔	13	16	04
GND 🗔	14	15	O3

2.3 28-lead TSOP (Type 1) Top View



2.2 32-lead PLCC Top View

		A7	A12	VPP	Ŋ	VCC	A14	A13	
	~	\square							1
		4	С	N	-	32	9	8	L
A6 🗆	5				0			29	🗆 A8
A5 🗆	6							28	🗆 A9
A4 🗆	7							27	🗆 A11
A3 🗆	8							26	D NC
A2 🗆	9							25	
A1 🗆	1()						24	🗆 A10
A0 🗆	1	1						23	
NC 🗆	12	2						22	07
O0	1:	3 ⁴	15	16	17	18	19	ನ ²¹	06
		0 1	02 🗆	GND 🗆	NC	03	04 🗆	05 🗆	1

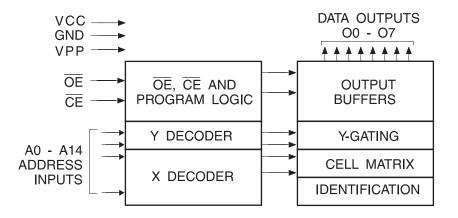
Note: 1. PLCC Package Pins 1 and 17 are Don't Connect.



3. System Considerations

Switching between active and standby conditions via the Chip Enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device non-conformance. At a minimum, a 0.1 μ F high frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the V_{CC} and Ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7 μ F bulk electrolytic capacitor should be utilized, again connected between the V_{CC} and Ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

4. Block Diagram



5. Absolute Maximum Ratings*

Temperature Under Bias	40°C to +85°C
Storage Temperature	65°C to +125°C
Voltage on Any Pin with Respect to Ground	2.0V to +7.0V ⁽¹⁾
Voltage on A9 with Respect to Ground	2.0V to +14.0V ⁽¹⁾
V _{PP} Supply Voltage with Respect to Ground	2.0V to +14.0V ⁽¹⁾

- *NOTICE: Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability
- Note: 1. Minimum voltage is -0.6V DC which may undershoot to -2.0V for pulses of less than 20 ns. Maximum output pin voltage is V_{CC} + 0.75V DC which may be exceeded if certain precautions are observed (consult application notes) and which may overshoot to +7.0V for pulses of less than 20 ns.





6. Operating Modes

Mode/Pin	CE	ŌĒ	Ai	V _{PP}	V _{cc}	Outputs
Read ⁽²⁾	V _{IL}	V _{IL}	Ai	V _{CC}	V _{cc}	D _{OUT}
Output Disable ⁽²⁾	V _{IL}	V _{IH}	X ⁽¹⁾	V _{CC}	V _{cc}	High Z
Standby ⁽²⁾	V _{IH}	X ⁽¹⁾	X ⁽¹⁾	V _{CC}	V _{cc}	High Z
Rapid Program ⁽³⁾	V _{IL}	V _{IH}	Ai	V _{PP}	V _{CC}	D _{IN}
PGM Verify ⁽³⁾	X ⁽¹⁾	V _{IL}	Ai	V _{PP}	V _{CC}	D _{OUT}
Optional PGM Verify ⁽³⁾	V _{IL}	V _{IL}	Ai	V _{cc}	V _{CC}	D _{OUT}
PGM Inhibit ⁽³⁾	V _{IH}	V _{IH}	X ⁽¹⁾	V _{PP}	V _{cc}	High Z
Product Identification ⁽³⁾⁽⁵⁾	V _{IL}	V _{IL}	$A9 = V_{H}^{(4)}$ $A0 = V_{IH} \text{ or } V_{IL}$ $A1 - A14 = V_{IL}$	V _{cc}	V _{cc}	Identification Code

Notes: 1. X can be V_{IL} or V_{IH} .

2. Read, output disable, and standby modes require, 3.0V \leq V_{CC} \leq 3.6V, or 4.5V \leq V_{CC} \leq 5.5V.

3. Refer to Programming Characteristics. Programming modes require $V_{CC} = 6.5V$.

4. $V_{H} = 12.0 \pm 0.5 V.$

 Two identifier bytes may be selected. All Ai inputs are held low (V_{IL}), except A9 which is set to V_H and A0 which is toggled low (V_{IL}) to select the Manufacturer's Identification byte and high (V_{IH}) to select the Device Code byte.

7. DC and AC Operating Conditions for Read Operation

	AT27L	V256A
	-55	-90
Industrial Operating Temperature (Case)	-40°C - 85°C	-40°C - 85°C
M. Dawar Guash	3.0V to 3.6V	3.0V to 3.6V
V _{CC} Power Supply	5V ±10%	5V ±10%

AT27LV256A

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8. DC and Operating Characteristics for Read Operation

Symbol	Parameter	Condition	Min	Max	Units
V _{CC} = 3.0\	/ to 3.6V				
ILI	Input Load Current	$V_{IN} = 0V$ to V_{CC}		±1	μA
I _{LO}	Output Leakage Current	$V_{OUT} = 0V$ to V_{CC}		±5	μA
I _{PP1} ⁽²⁾	V _{PP} ⁽¹⁾ Read/Standby Current	V _{PP} = V _{CC}		10	μA
		I_{SB1} (CMOS), $\overline{CE} = V_{CC \pm} 0.3V$		20	μA
I _{SB} V _{CC} ⁽¹⁾ Standby Current	I_{SB2} (TTL), $\overline{CE} = 2.0$ to $V_{CC} + 0.5V$		100	μA	
I _{CC}	V _{CC} Active Current	f = 5 MHz, I_{OUT} = 0 mA, \overline{CE} = V_{IL}		8	mA
V _{IL}	Input Low Voltage		-0.6	0.8	V
V _{IH}	Input High Voltage		2.0	V _{CC} + 0.5	V
V _{OL}	Output Low Voltage	I _{OL} = 2.0 mA		0.4	V
V _{OH}	Output High Voltage	I _{OH} = -2.0 mA	2.4		V
V _{CC} = 4.5\	/ to 5.5V				
I _{LI}	Input Load Current	$V_{IN} = 0V$ to V_{CC}		±1	μA
I _{LO}	Output Leakage Current	$V_{OUT} = 0V$ to V_{CC}		±5	μA
I _{PP1} ⁽²⁾	V _{PP} ⁽¹⁾ Read/Standby Current	$V_{PP} = V_{CC}$		10	μA
	V (1) Standby Ourrent	I_{SB1} (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$		100	μA
I _{SB}	V _{CC} ⁽¹⁾ Standby Current	I_{SB2} (TTL), \overline{CE} = 2.0 to V_{CC} + 0.5V		1	mA
I _{CC}	V _{CC} Active Current	$f = 5 \text{ MHz}, I_{OUT} = 0 \text{ mA}, \overline{CE} = V_{IL}$		20	mA
V _{IL}	Input Low Voltage		-0.6	0.8	V
V _{IH}	Input High Voltage		2.0	V _{CC} + 0.5	V
V _{OL}	Output Low Voltage	I _{OL} = 2.1 mA		0.4	V
V _{OH}	Output High Voltage	I _{OH} = -400 μA	2.4		V

Notes: 1. V_{CC} must be applied simultaneously with or before V_{PP} and removed simultaneously with or after V_{PP}

2. V_{PP} may be connected directly to V_{CC} , except during programming. The supply current would then be the sum of I_{CC} and I_{PP}



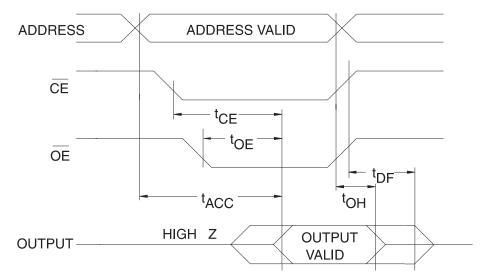


9. AC Characteristics for Read Operation

 V_{CC} = 3.0V to 3.6V and 4.5V to 5.5V

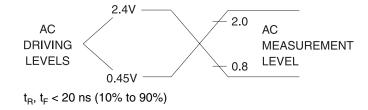
				AT27LV256A				
			-{	55	-9	90		
Symbol	Parameter	Condition	Max	Min	Min	Мах	Units	
t _{ACC} ⁽³⁾	Address to Output Delay	$\overline{CE} = \overline{OE} = V_{IL}$		55		90	ns	
t _{CE} ⁽²⁾	CE to Output Delay	$\overline{OE} = V_{IL}$		55		90	ns	
t _{OE} ⁽²⁾⁽³⁾	OE to Output Delay	$\overline{CE} = V_{IL}$		35		50	ns	
t _{DF} ⁽⁴⁾⁽⁵⁾	OE or CE High to Output Float, Whichever Occurred First			30		40	ns	
t _{OH}	Output Hold from Address, \overline{CE} or \overline{OE} , Whichever Occurred First		0		0		ns	

10. AC Waveforms for Read Operation⁽¹⁾

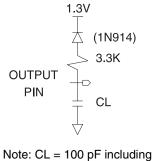


- Notes: 1. Timing measurement references are 0.8V and 2.0V. Input AC drive levels are 0.45V and 2.4V, unless otherwise specified.
 - 2. $\overline{\text{OE}}$ may be delayed up to t_{CE} t_{OE} after the falling edge of $\overline{\text{CE}}$ without impact on t_{CE} .
 - 3. \overline{OE} may be delayed up to t_{ACC} t_{OE} after the address is valid without impact on t_{ACC} .
 - 4. This parameter is only sampled and is not 100% tested.
 - 5. Output float is defined as the point when data is no longer driven.

11. Input Test Waveforms and Measurement Levels



12. Output Test Load



jig capacitance.

13. Pin Capacitance

f = 1 MHz, T = $25^{\circ}C^{(1)}$

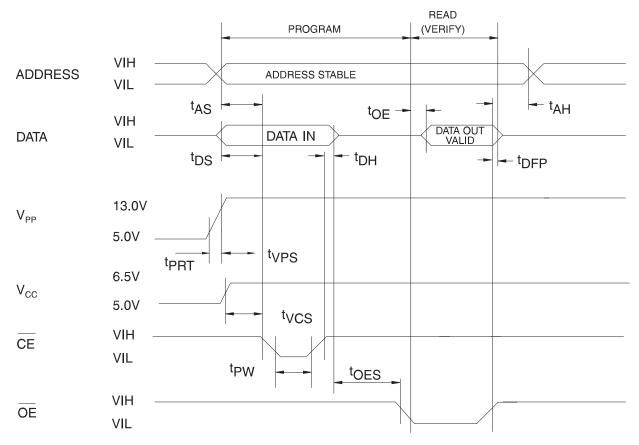
Symbol	Тур	Мах	Units	Conditions
C _{IN}	4	8	pF	$V_{IN} = 0V$
C _{OUT}	8	12	pF	$V_{OUT} = 0V$

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested.





14. Programming Waveforms⁽¹⁾



- Notes: 1. The Input Timing Reference is 0.8V for $V_{\rm IL}$ and 2.0V for $V_{\rm IH}.$
 - 2. t_{OE} and t_{DFP} are characteristics of the device but must be accommodated by the programmer.
 - 3. When programming the AT27LV256A a 0.1 μ F capacitor is required across V_{PP} and ground to suppress spurious voltage transients.

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15. DC Programming Characteristics

 $T_{A} = 25 \pm 5^{\circ}C, \, V_{CC} = 6.5 \pm 0.25V, \, V_{PP} = 13.0 \pm 0.25V$

			Lir	Limits			
Symbol	Parameter	Test Conditions	Min	Max	Units		
ILI	Input Load Current	$V_{IN} = V_{IL}, V_{IH}$		±10	μA		
V _{IL}	Input Low Level		-0.6	0.8	V		
V _{IH}	Input High Level		2.0	V _{cc} + 0.5	V		
V _{OL}	Output Low Voltage	I _{OL} = 2.1 mA		0.4	V		
V _{OH}	Output High Voltage	I _{OH} = -400 μA	2.4		V		
I _{CC2}	V_{CC} Supply Current (Program and Verify)			25	mA		
I _{PP2}	V _{PP} Current	$\overline{CE} = V_{IL}$		25	mA		
V _{ID}	A9 Product Identification Voltage		11.5	12.5	V		

16. AC Programming Characteristics

 $T_{A} = 25 \pm 5^{\circ}C, \ V_{CC} = 6.5 \pm 0.25V, \ V_{PP} = 13.0 \pm 0.25V$

			Lir		
Symbol Parameter		Test Conditions ⁽¹⁾	Min	Max	Units
t _{AS}	Address Setup Time		2		μs
t _{OES}	OE Setup Time	Input Rise and Fall Times:	2		μs
t _{DS}	Data Setup Time	(10% to 90%) 20 ns	2		μs
t _{AH}	Address Hold Time		0		μs
t _{DH}	Data Hold Time	Input Pulse Levels: 0.45V to 2.4V	2		μs
t _{DFP}	OE High to Output Float Delay ⁽²⁾		0	130	ns
t _{VPS}	V _{PP} Setup Time	Input Timing Reference Level:	2		μs
t _{VCS}	V _{CC} Setup Time	0.8V to 2.0V	2		μs
t _{PW}	CE Program Pulse Width ⁽³⁾	Output Timing Reference Level:	95	105	μs
t _{OE}	Data Valid from $\overline{OE}^{(2)}$	0.8V to 2.0V		150	ns
t _{PRT}	V _{PP} Pulse Rise Time During Programming		50		ns

Notes: 1. V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP}

2. This parameter is only sampled and is not 100% tested. Output Float is defined as the point where data is no longer driven – see timing diagram.

3. Program Pulse width tolerance is 100 $\,\mu\text{sec}\pm5\%.$

17. Atmel's AT27LV256A Integrated Product Identification Code⁽¹⁾

		Pins							Hex	
Codes	A0	07	O 6	O5	04	O3	02	01	00	Data
Manufacturer	0	0	0	0	1	1	1	1	0	1E
Device Type	1	1	0	0	0	1	1	0	0	8C

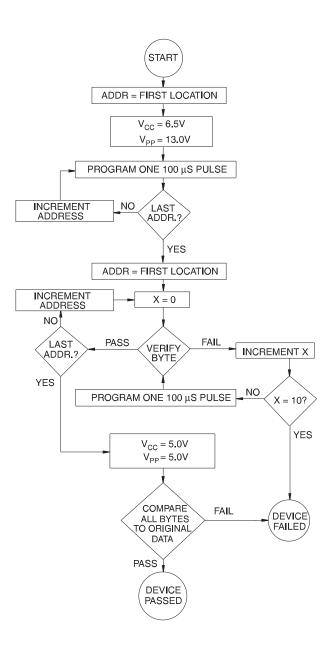
Note: 1. The AT27LV256A has the same Product Identification Code as the AT27C256R. Both are programming compatible.





18. Rapid Programming Algorithm

A 100 μ s \overline{CE} pulse width is used to program. The address is set to the first location. V_{CC} is raised to 6.5V and V_{PP} is raised to 13.0V. Each address is first programmed with one 100 μ s \overline{CE} pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a byte fails to pass verification, up to 10 successive 100 μ s pulses are applied with a verification after each pulse. If the byte fails to verify after 10 pulses have been applied, the part is considered failed. After the byte verifies properly, the next address is selected until all have been checked. V_{PP} is then lowered to 5.0V and V_{CC} to 5.0V. All bytes are read again and compared with the original data to determine if the device passes or fails.



10 **AT27LV256A**

19. Ordering Information

19.1 Standard Package

t _{ACC}	I _{CC} (mA)				
(ns)	Active	Standby	Ordering Code	Package	Operation Range
55	8	0.02	AT27LV256A-55JI	32J	Industrial
			AT27LV256A-55RI	28R ⁽¹⁾	(-40° C to 85° C)
			AT27LV256A-55TI	28T	
90	8	0.02	AT27LV256A-90JI	32J	Industrial
			AT27LV256A-90RI	28R ⁽¹⁾	(-40° C to 85° C)
			AT27LV256A-90TI	28T	

Note:

Not recommended for new designs. Use Green package option.

19.2 Green Package Option (Pb/Halide-free)

t _{acc} (ns)	I _{CC} (mA)				
	Active	Standby	Ordering Code	Package	Operation Range
55	8	0.02	AT27LV256A-55JU	32J	Industrial
			AT27LV256A-55RU	28R ⁽¹⁾	(-40° C to 85° C)
			AT27LV256A-55TU	28T	
90	8	0.02	AT27LV256A-90JU	32J	Industrial
			AT27LV256A-90RU	28R ⁽¹⁾	(-40° C to 85° C)
			AT27LV256A-90TU	28T	

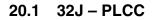
Note: 1. The 28-pin SOIC package is not recommended for new designs.

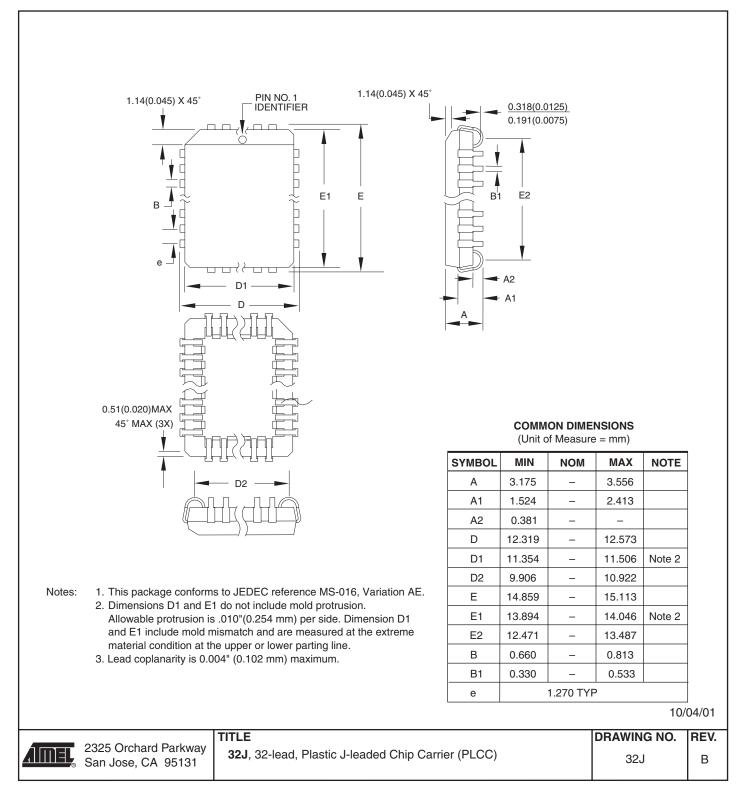
Package Type				
32J	32-lead, Plastic J-leaded Chip Carrier (PLCC)			
28R	28-lead, 0.330" Wide, Plastic Gull Wing Small Outline (SOIC)			
28T	28-lead, Thin Small Outline Package (TSOP)			





20. Packaging Information

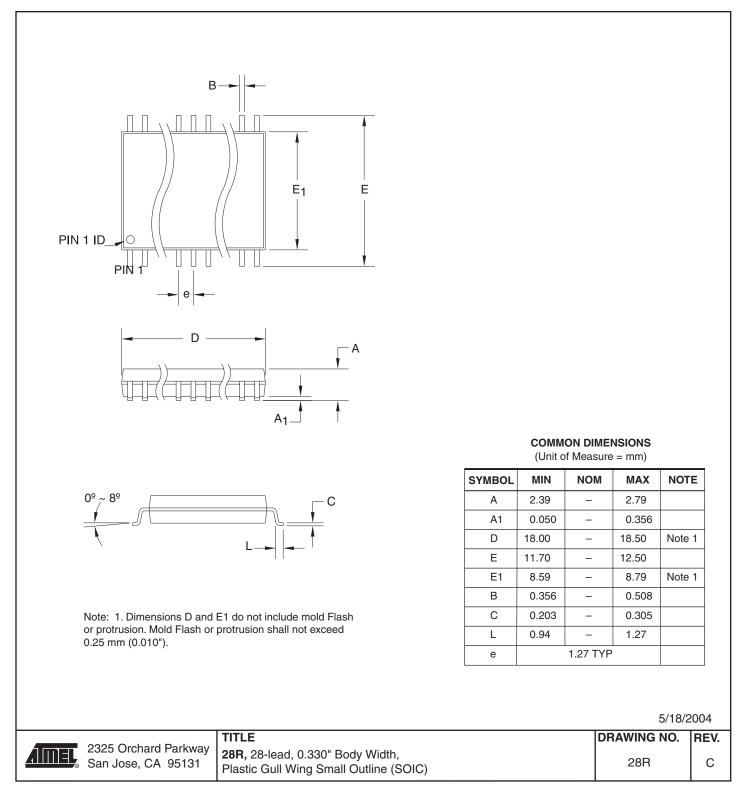




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AT27LV256A

20.2 28R - SOIC

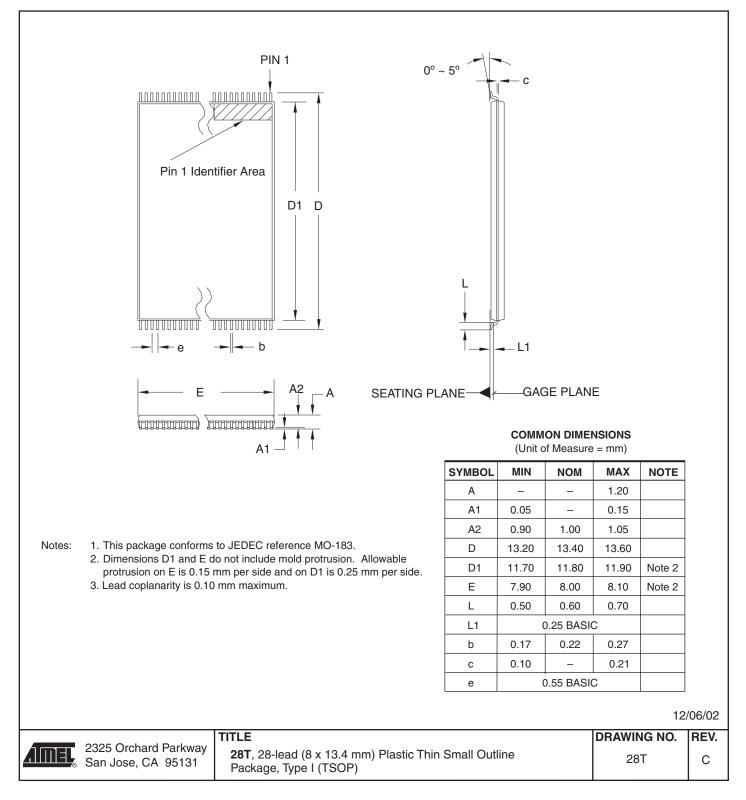




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20.3 28T - TSOP





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