Absolute Maximum Ratings

V_{IN} to GND..-0.3V to 70V
EN/UVLO to GND...-0.3V to 70V
LX to GND ....-0.3V to V_{IN} + 0.3V
V_{CC}, FB/V_{OUT}, $\overline{RESET}$ to GND ....-0.3V to 6V
MODE to GND...-0.3V to V_{CC} + 0.3V
LX total RMS Current ....±800mA
Output Short-Circuit Duration ....Continuous

Continuous Power Dissipation (T_A = +70°C)
   8-Pin TDFN (derate 6.2mW/NC above +70°C) 496mW
Junction Temperature..+150°C
Storage Temperature Range .... -65°C to +150°C
Soldering Temperature (reflow) ....+260°C
Lead Temperature (soldering, 10s) ....+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Junction temperature greater than +125°C degrades operating lifetimes.

Package Thermal Characteristics(Note 1)

TDFN
   Junction-to-Ambient Thermal Resistance (θ_{JA}) ......+162°C/W
   Junction-to-Case Thermal Resistance (θ_{JC}) ....+20°C/W

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to **www.maximintegrated.com/thermal-tutorial**.

Electrical Characteristics

(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, LX = MODE = $\overline{RESET}$ = unconnected; T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
INPUT SUPPLY (VIN)						
Input Voltage Range	V_{IN}		4.5		60	V
Input Shutdown Current	I_{IN-SH}	$V_{EN/UVLO}$ = 0V, shutdown mode		2.2	4	µA
Input Supply Current	I_{Q-PFM}	MODE = unconnected, FB/V_{OUT} = 1.03 x FB/$V_{OUT-REG}$		95	160	µA
	I_{Q-PWM}	Normal switching mode, V_{IN} = 24V		2.5	4	mA
ENABLE/UVLO (EN/UVLO)						
EN/UVLO Threshold	V_{ENR}	$V_{EN/UVLO}$ rising	1.19	1.215	1.24	V
	V_{ENF}	$V_{EN/UVLO}$ falling	1.06	1.09	1.15	
	$V_{EN-TRUESD}$	$V_{EN/UVLO}$ falling, true shutdown		0.75		
EN/UVLO Input Leakage Current	$I_{EN/UVLO}$	$V_{EN/UVLO}$ = 60V, T_A = +25°C	-100		+100	nA
LDO (V_{CC})						
V_{CC} Output Voltage Range	V_{CC}	6V < V_{IN} < 60V, 0mA < I_{VCC} < 10mA	4.75	5	5.25	V
V_{CC} Current Limit	$I_{VCC-MAX}$	V_{CC} = 4.3V, V_{IN} = 12V	13	30	50	mA
V_{CC} Dropout	V_{CC-DO}	V_{IN} = 4.5V, I_{VCC} = 5mA		0.15	0.3	V
V_{CC} UVLO	V_{CC-UVR}	V_{CC} rising	4.05	4.18	4.3	V
	V_{CC-UVF}	V_{CC} falling	3.7	3.8	3.95	

Electrical Characteristics (continued)

(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, LX = MODE = $\overline{RESET}$ = unconnected; T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted.) (Note 2)

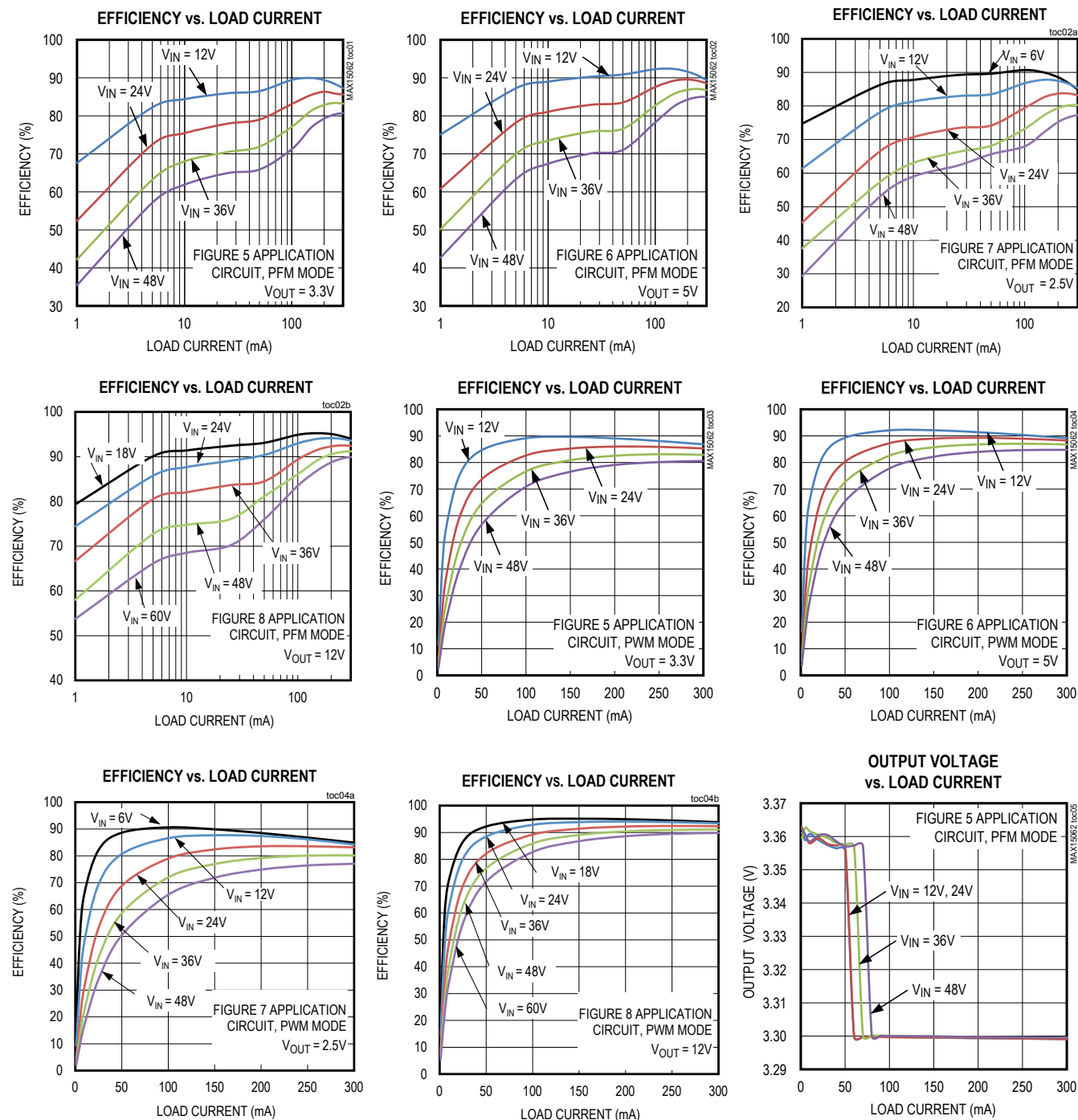| PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
POWER MOSFETs							
High-Side pMOS On-Resistance	R_{DS-ONH}	I_{LX} = 0.3A (sourcing)	T_A = +25°C		1.35	1.75	Ω
			T_A = T_J = +125°C			2.7	
Low-Side nMOS On-Resistance	R_{DS-ONL}	I_{LX} = 0.3A (sinking)	T_A = +25°C		0.45	0.55	Ω
			T_A = T_J = +125°C			0.9	
LX Leakage Current	I_{LX-LKG}	$V_{EN/UVLO}$ = 0V, V_{IN} = 60V, T_A = +25°C, V_{LX} = (V_{GND} + 1V) to (V_{IN} - 1V)		-1		+1	µA
SOFT-START (SS)							
Soft-Start Time	t_{SS}			3.8	4.1	4.4	ms
FEEDBACK (FB)							
FB Regulation Voltage	V_{FB-REG}	MODE = GND, MAX15062C		0.887	0.9	0.913	V
		MODE = unconnected, MAX15062C		0.887	0.915	0.936	
FB Leakage Current	I_{FB}	MAX15062C		-100	-25		nA
OUTPUT VOLTAGE (V_{OUT})							
V_{OUT} Regulation Voltage	$V_{OUT-REG}$	MODE = GND, MAX15062A		3.25	3.3	3.35	V
		MODE = unconnected, MAX15062A		3.25	3.35	3.42	
		MODE = GND, MAX15062B		4.93	5	5.07	
		MODE = unconnected, MAX15062B		4.93	5.08	5.18	
CURRENT LIMIT							
Peak Current-Limit Threshold	$I_{PEAK-LIMIT}$			0.49	0.56	0.62	A
Runaway Current-Limit Threshold	$I_{RUNAWAY-LIMIT}$			0.58	0.66	0.73	A
Negative Current-Limit Threshold	$I_{SINK-LIMIT}$	MODE = GND		0.25	0.3	0.35	A
					0.01		mA
PFM Current Level	I_{PFM}				0.13		A
TIMING							
Switching Frequency	f_{SW}			465	500	535	kHz
Events to Hiccup After Crossing Runaway Current Limit					1		Cycles
FB/V_{OUT} Undervoltage Trip Level to Cause Hiccup				62.5	64.5	66.5	%
Hiccup Timeout					131		ms
Minimum On-Time	t_{ON-MIN}				90	130	ns
Maximum Duty Cycle	D_{MAX}	FB/V_{OUT} = 0.98 x FB/$V_{OUT-REG}$		89	91.5	94	%

Electrical Characteristics (continued)

(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, LX = MODE = $\overline{RESET}$ = unconnected; T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
LX Dead Time				5		ns
$\overline{RESET}$						
FB/V_{OUT} Threshold for $\overline{RESET}$ Rising		FB/V_{OUT} rising	93.5	95.5	97.5	%
FB/V_{OUT} Threshold for $\overline{RESET}$ Falling		FB/V_{OUT} falling	90	92	94	%
$\overline{RESET}$ Delay After FB/V_{OUT} Reaches 95% Regulation				2		ms
$\overline{RESET}$ Output Level Low		$I_{\overline{RESET}}$ = 5mA			0.2	V
$\overline{RESET}$ Output Leakage Current		$V_{\overline{RESET}}$ = 5.5V, T_A = +25°C			0.1	µA
MODE						
MODE Internal Pullup Resistor				500		kΩ
THERMAL SHUTDOWN						
Thermal-Shutdown Threshold		Temperature rising		166		°C
Thermal-Shutdown Hysteresis				10		°C

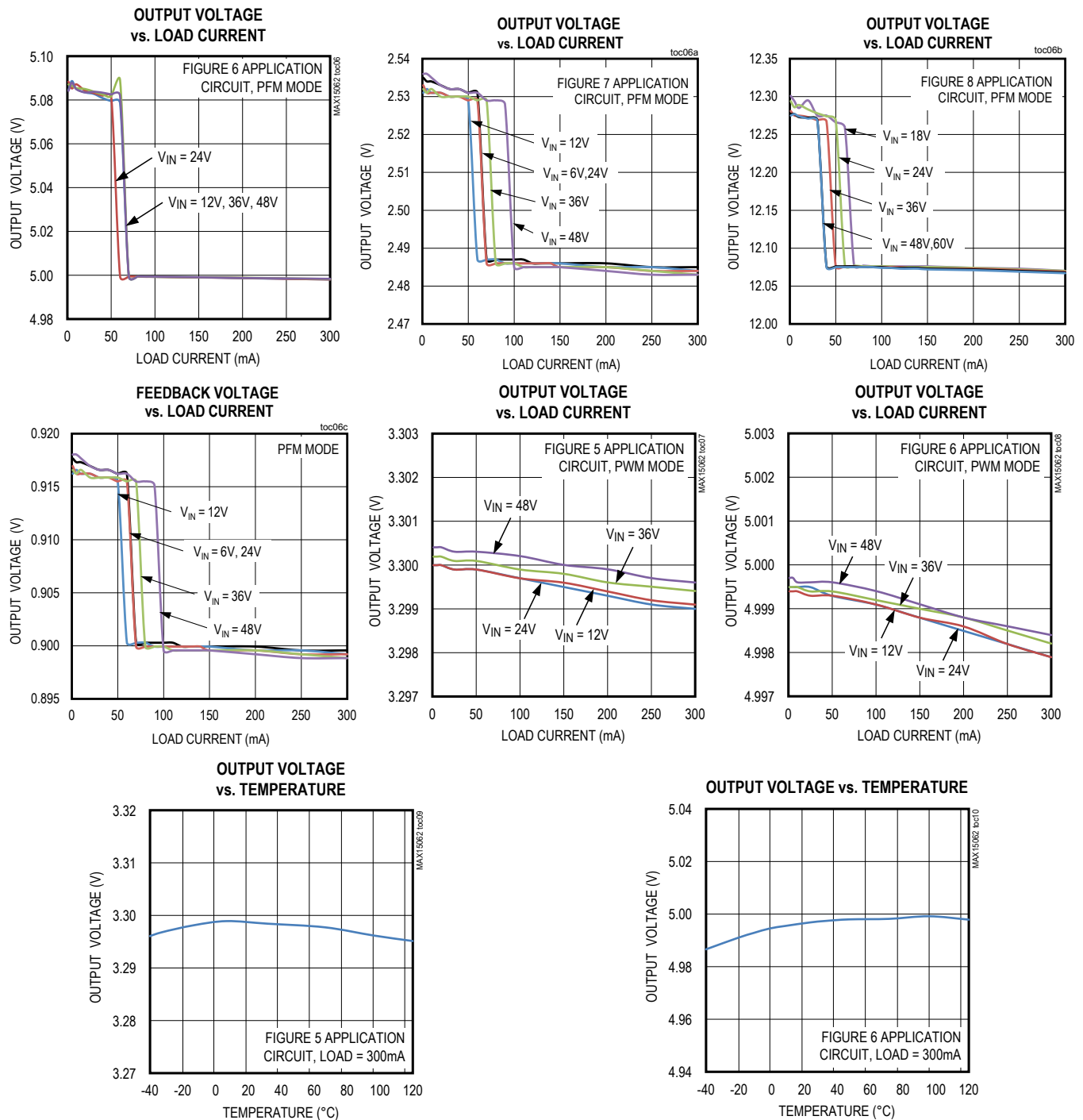**Note 2:** All the limits are 100% tested at T_A = +25°C. Limits over temperature are guaranteed by design.
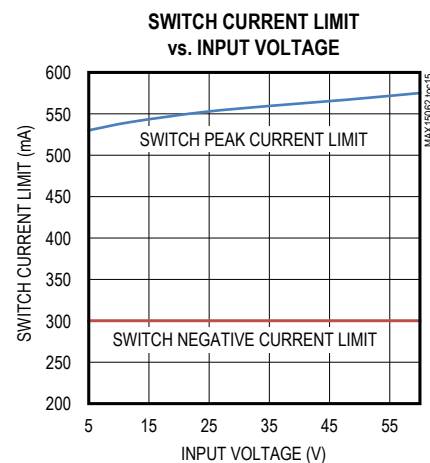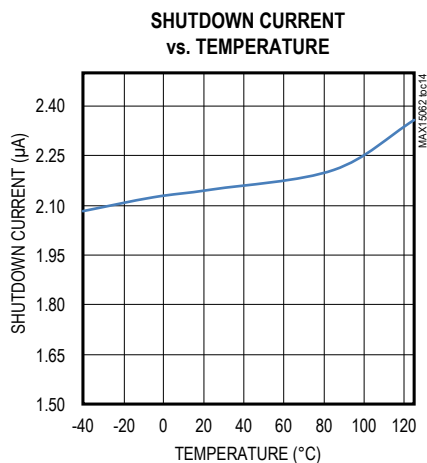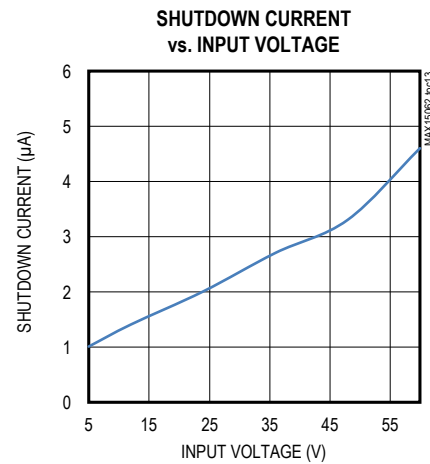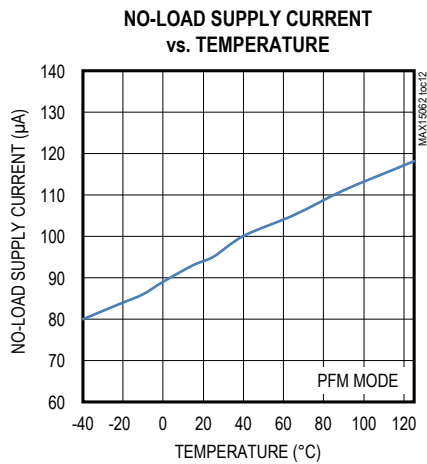
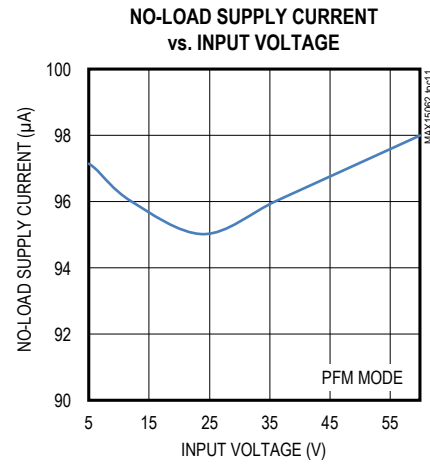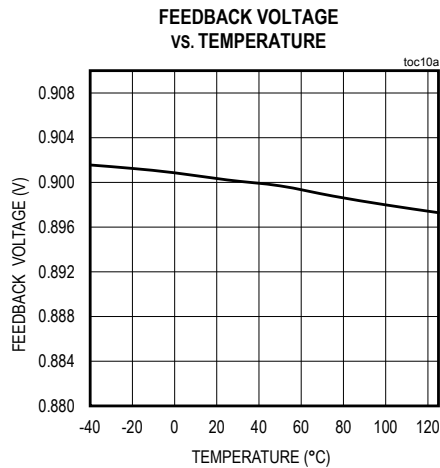## Typical Operating Characteristics

(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, T_A = +25°C, unless otherwise noted.)

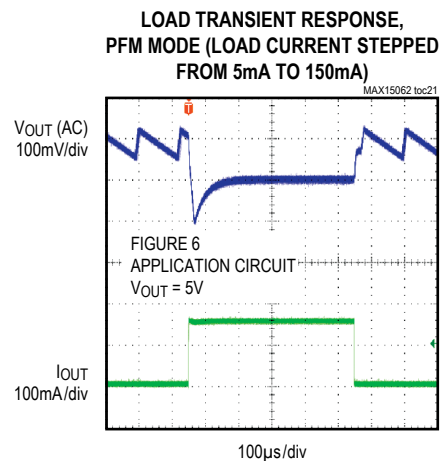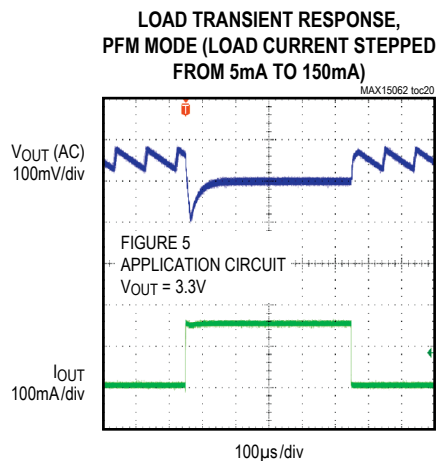EFFICIENCY vs. LOAD CURRENT

V_{IN} = 12V
V_{IN} = 24V
V_{IN} = 36V
V_{IN} = 48V
FIGURE 5 APPLICATION CIRCUIT, PFM MODE
V_{OUT} = 3.3V

EFFICIENCY vs. LOAD CURRENT

V_{IN} = 12V
V_{IN} = 24V
V_{IN} = 36V
V_{IN} = 48V
FIGURE 6 APPLICATION CIRCUIT, PFM MODE
V_{OUT} = 5V

EFFICIENCY vs. LOAD CURRENT

V_{IN} = 12V
V_{IN} = 6V
V_{IN} = 24V
V_{IN} = 36V
V_{IN} = 48V
FIGURE 7 APPLICATION CIRCUIT, PFM MODE
V_{OUT} = 2.5V

EFFICIENCY vs. LOAD CURRENT

V_{IN} = 24V
V_{IN} = 18V
V_{IN} = 36V
V_{IN} = 48V
V_{IN} = 60V
FIGURE 8 APPLICATION CIRCUIT, PFM MODE
V_{OUT} = 12V

EFFICIENCY vs. LOAD CURRENT

V_{IN} = 12V
V_{IN} = 24V
V_{IN} = 36V
V_{IN} = 48V
FIGURE 5 APPLICATION CIRCUIT, PWM MODE
V_{OUT} = 3.3V

EFFICIENCY vs. LOAD CURRENT

V_{IN} = 24V
V_{IN} = 12V
V_{IN} = 36V
V_{IN} = 48V
FIGURE 6 APPLICATION CIRCUIT, PWM MODE
V_{OUT} = 5V

EFFICIENCY vs. LOAD CURRENT

V_{IN} = 6V
V_{IN} = 12V
V_{IN} = 24V
V_{IN} = 36V
V_{IN} = 48V
FIGURE 7 APPLICATION CIRCUIT, PWM MODE
V_{OUT} = 2.5V

EFFICIENCY vs. LOAD CURRENT

V_{IN} = 18V
V_{IN} = 24V
V_{IN} = 36V
V_{IN} = 48V
V_{IN} = 60V
FIGURE 8 APPLICATION CIRCUIT, PWM MODE
V_{OUT} = 12V

OUTPUT VOLTAGE vs. LOAD CURRENT

FIGURE 5 APPLICATION CIRCUIT, PFM MODE
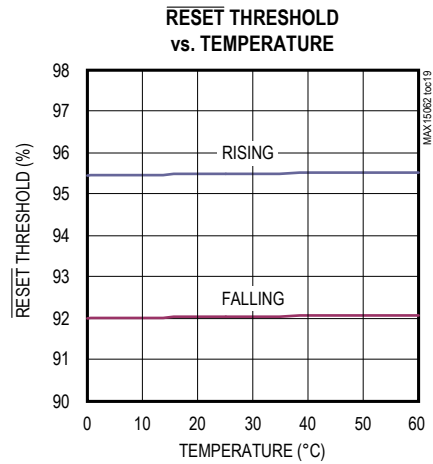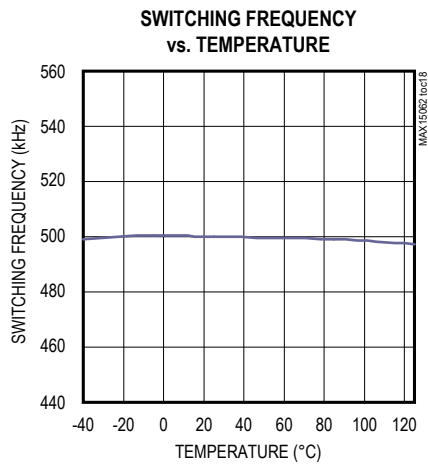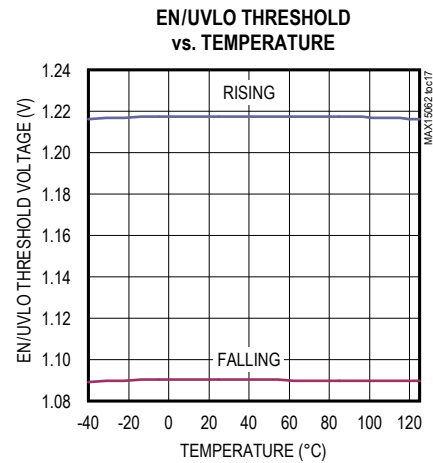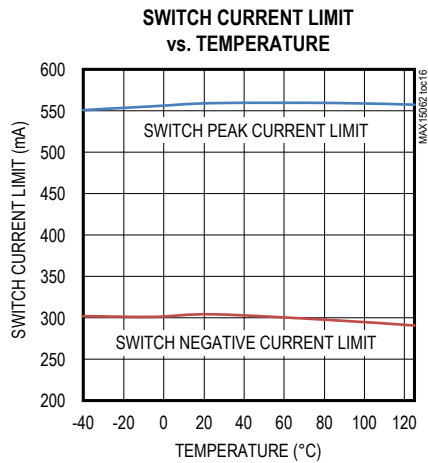V_{IN} = 12V, 24V
V_{IN} = 36V
V_{IN} = 48V

Typical Operating Characteristicsc (continued)

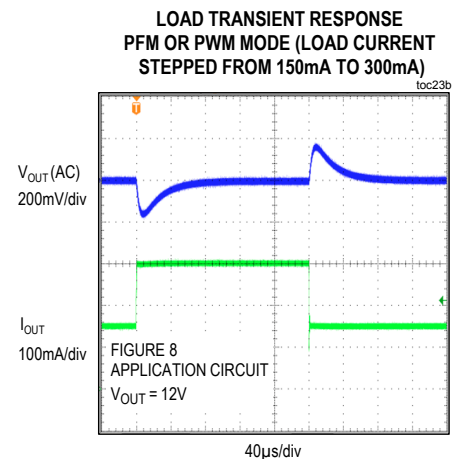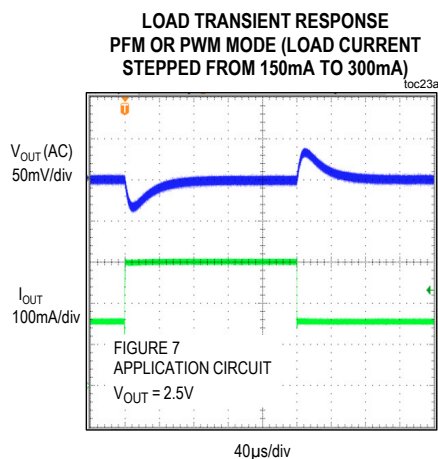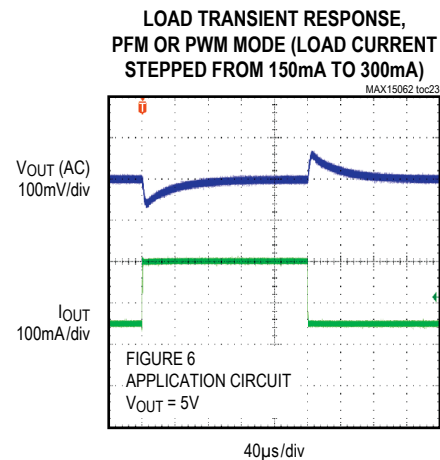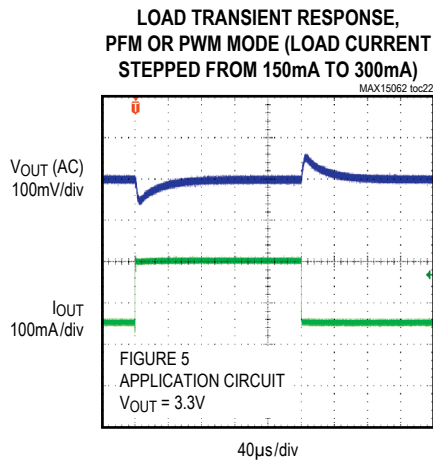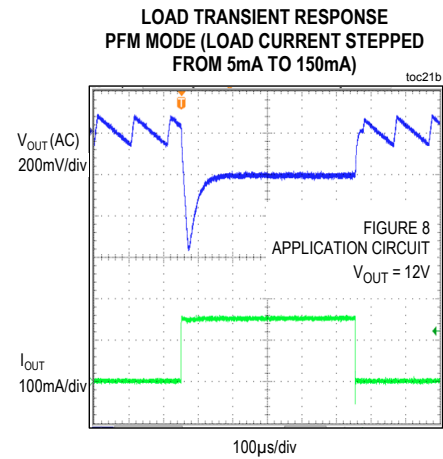(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, T_A = +25°C, unless otherwise noted.)

OUTPUT VOLTAGE vs. LOAD CURRENT

FIGURE 6 APPLICATION CIRCUIT, PFM MODE

V_{IN} = 24V

V_{IN} = 12V, 36V, 48V

OUTPUT VOLTAGE vs. LOAD CURRENT

FIGURE 7 APPLICATION CIRCUIT, PFM MODE

V_{IN} = 12V

V_{IN} = 6V, 24V

V_{IN} = 36V

V_{IN} = 48V

OUTPUT VOLTAGE vs. LOAD CURRENT

FIGURE 8 APPLICATION CIRCUIT, PFM MODE

V_{IN} = 18V

V_{IN} = 24V

V_{IN} = 36V

V_{IN} = 48V, 60V

FEEDBACK VOLTAGE vs. LOAD CURRENT

PFM MODE

V_{IN} = 12V

V_{IN} = 6V, 24V

V_{IN} = 36V

V_{IN} = 48V

OUTPUT VOLTAGE vs. LOAD CURRENT

FIGURE 5 APPLICATION CIRCUIT, PWM MODE

V_{IN} = 48V

V_{IN} = 36V

V_{IN} = 24V

V_{IN} = 12V

OUTPUT VOLTAGE vs. LOAD CURRENT

FIGURE 6 APPLICATION CIRCUIT, PWM MODE

V_{IN} = 48V

V_{IN} = 36V

V_{IN} = 12V

V_{IN} = 24V

OUTPUT VOLTAGE vs. TEMPERATURE

FIGURE 5 APPLICATION CIRCUIT, LOAD = 300mA

OUTPUT VOLTAGE vs. TEMPERATURE

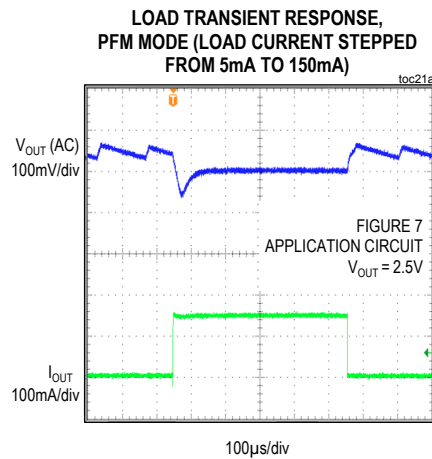FIGURE 6 APPLICATION CIRCUIT, LOAD = 300mA

Typical Operating Characteristicsc (continued)

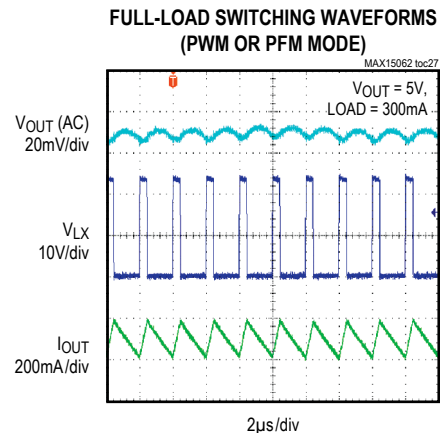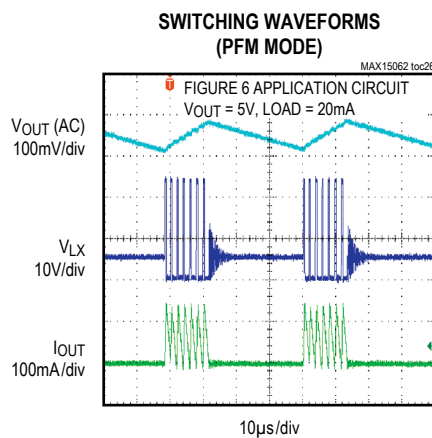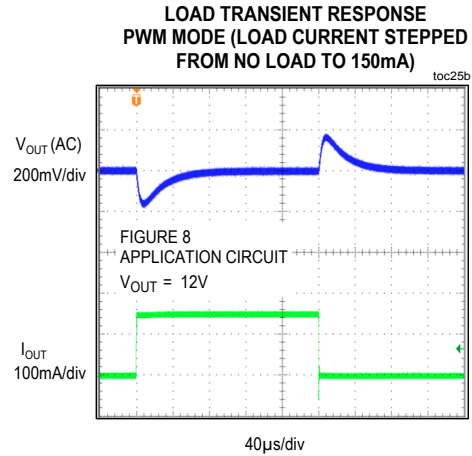(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, T_A = +25°C, unless otherwise noted.)

**FEEDBACK VOLTAGE
vs. TEMPERATURE**

**NO-LOAD SUPPLY CURRENT
vs. INPUT VOLTAGE**

**NO-LOAD SUPPLY CURRENT
vs. TEMPERATURE**

**SHUTDOWN CURRENT
vs. INPUT VOLTAGE**

**SHUTDOWN CURRENT
vs. TEMPERATURE**

**SWITCH CURRENT LIMIT
vs. INPUT VOLTAGE**
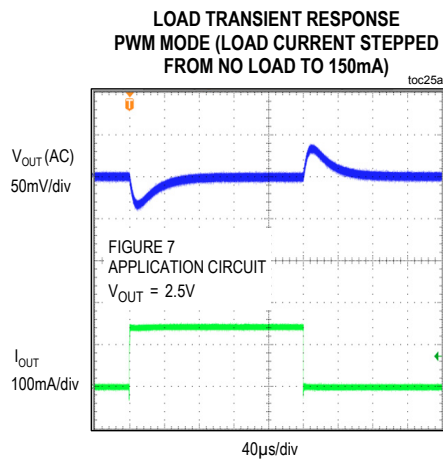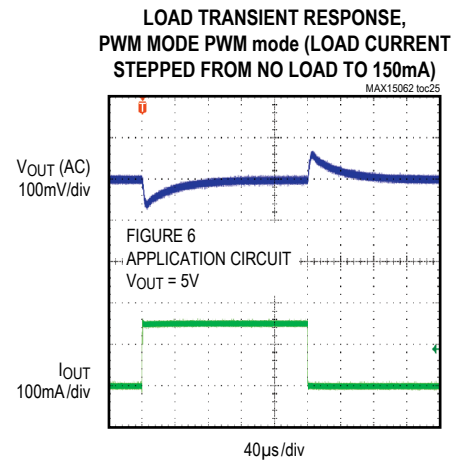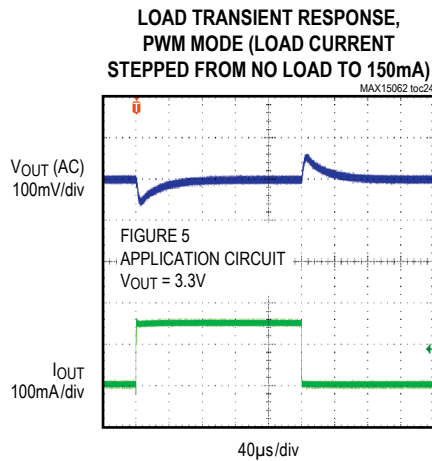
SWITCH PEAK CURRENT LIMIT

SWITCH NEGATIVE CURRENT LIMIT

Typical Operating Characteristicsc (continued)

(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, T_A = +25°C, unless otherwise noted.)

**SWITCH CURRENT LIMIT
vs. TEMPERATURE**

**EN/UVLO THRESHOLD
vs. TEMPERATURE**

**SWITCHING FREQUENCY
vs. TEMPERATURE**

**RESET THRESHOLD
vs. TEMPERATURE**

**LOAD TRANSIENT RESPONSE,
PFM MODE (LOAD CURRENT STEPPED
FROM 5mA TO 150mA)**

FIGURE 5
APPLICATION CIRCUIT
V_{OUT} = 3.3V

**LOAD TRANSIENT RESPONSE,
PFM MODE (LOAD CURRENT STEPPED
FROM 5mA TO 150mA)**

FIGURE 6
APPLICATION CIRCUIT
V_{OUT} = 5V

Typical Operating Characteristicsc (continued)

(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, T_A = +25°C, unless otherwise noted.)

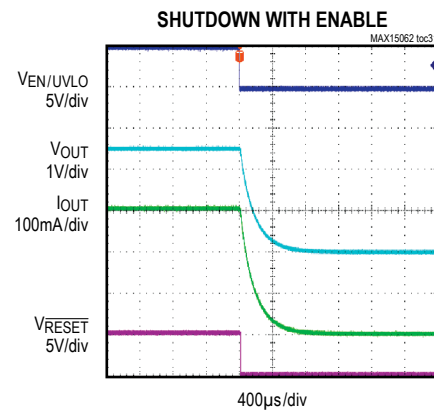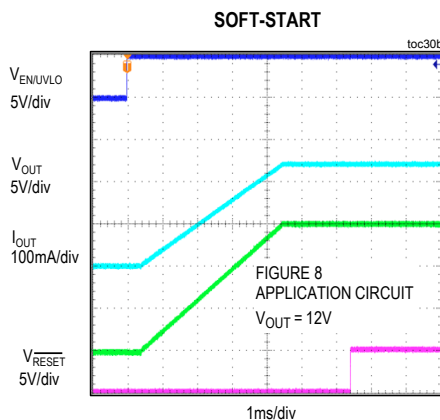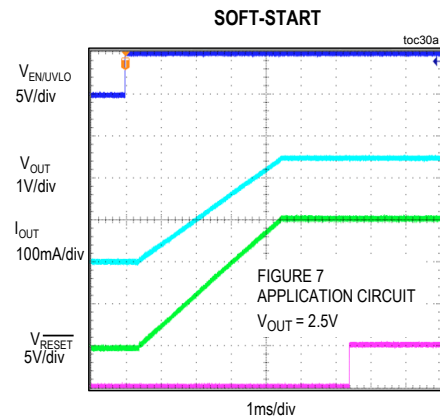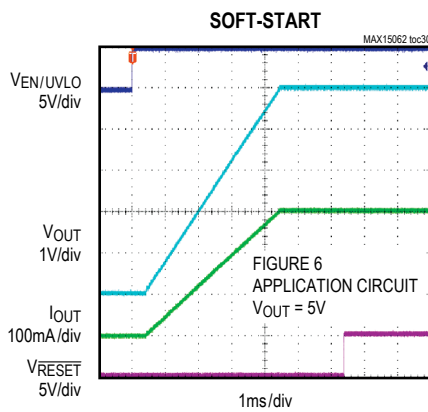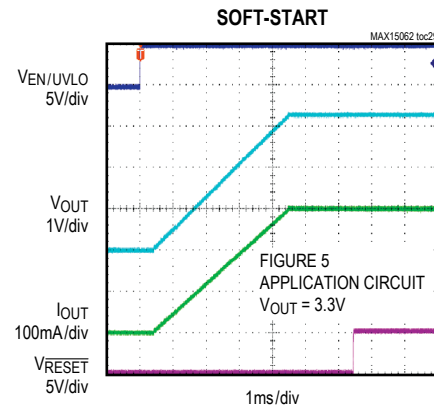LOAD TRANSIENT RESPONSE,
PFM MODE (LOAD CURRENT STEPPED
FROM 5mA TO 150mA)

toc21a

V_{OUT} (AC)
100mV/div

FIGURE 7
APPLICATION CIRCUIT
V_{OUT} = 2.5V

I_{OUT}
100mA/div

100µs/div

LOAD TRANSIENT RESPONSE
PFM MODE (LOAD CURRENT STEPPED
FROM 5mA TO 150mA)

toc21b

V_{OUT} (AC)
200mV/div

FIGURE 8
APPLICATION CIRCUIT
V_{OUT} = 12V

I_{OUT}
100mA/div

100µs/div

LOAD TRANSIENT RESPONSE,
PFM OR PWM MODE (LOAD CURRENT
STEPPED FROM 150mA TO 300mA)

MAX15062 toc22

V_{OUT} (AC)
100mV/div

I_{OUT}
100mA/div

FIGURE 5
APPLICATION CIRCUIT
V_{OUT} = 3.3V

40µs/div

LOAD TRANSIENT RESPONSE,
PFM OR PWM MODE (LOAD CURRENT
STEPPED FROM 150mA TO 300mA)

MAX15062 toc23

V_{OUT} (AC)
100mV/div

I_{OUT}
100mA/div

FIGURE 6
APPLICATION CIRCUIT
V_{OUT} = 5V

40µs/div

LOAD TRANSIENT RESPONSE
PFM OR PWM MODE (LOAD CURRENT
STEPPED FROM 150mA TO 300mA)

toc23a

V_{OUT} (AC)
50mV/div

I_{OUT}
100mA/div

FIGURE 7
APPLICATION CIRCUIT
V_{OUT} = 2.5V

40µs/div

LOAD TRANSIENT RESPONSE
PFM OR PWM MODE (LOAD CURRENT
STEPPED FROM 150mA TO 300mA)

toc23b

V_{OUT} (AC)
200mV/div

I_{OUT}
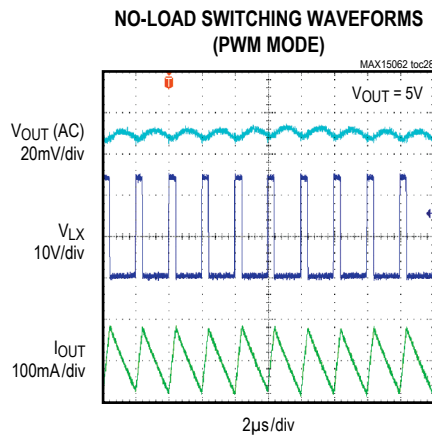100mA/div

FIGURE 8
APPLICATION CIRCUIT
V_{OUT} = 12V

40µs/div

Typical Operating Characteristicsc (continued)

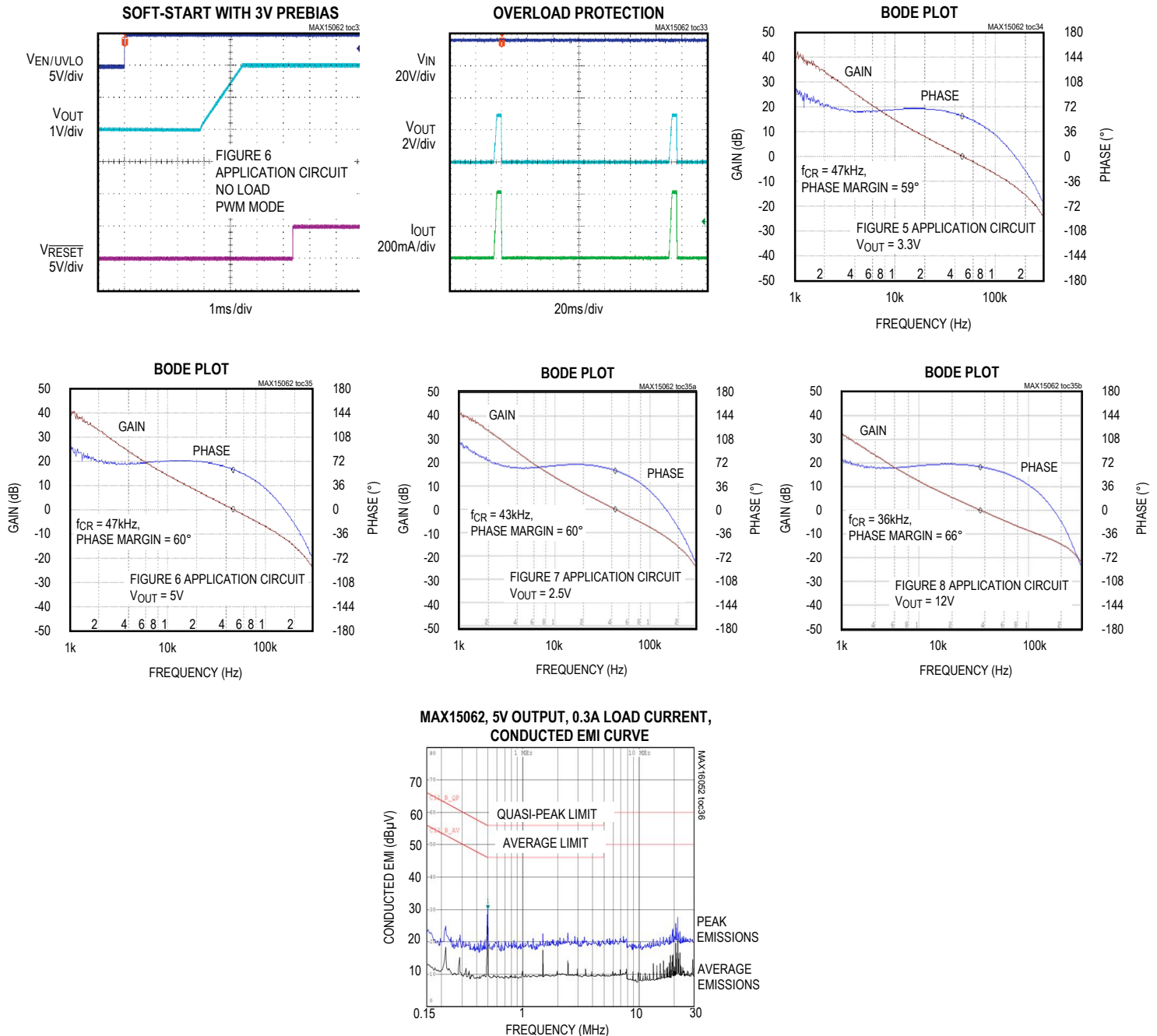(V_IN = 24V, V_GND = 0V, C_IN = C_VCC = 1µF, V_EN/UVLO = 1.5V, T_A = +25°C, unless otherwise noted.)

LOAD TRANSIENT RESPONSE,
PWM MODE (LOAD CURRENT
STEPPED FROM NO LOAD TO 150mA)

MAX15062 toc24

V_OUT (AC)
100mV/div

FIGURE 5
APPLICATION CIRCUIT
V_OUT = 3.3V

I_OUT
100mA/div

40µs/div

LOAD TRANSIENT RESPONSE,
PWM MODE PWM mode (LOAD CURRENT
STEPPED FROM NO LOAD TO 150mA)

MAX15062 toc25

V_OUT (AC)
100mV/div

FIGURE 6
APPLICATION CIRCUIT
V_OUT = 5V

I_OUT
100mA/div

40µs/div

LOAD TRANSIENT RESPONSE
PWM MODE (LOAD CURRENT STEPPED
FROM NO LOAD TO 150mA)

toc25a

V_OUT (AC)
50mV/div

FIGURE 7
APPLICATION CIRCUIT
V_OUT = 2.5V

I_OUT
100mA/div

40µs/div

LOAD TRANSIENT RESPONSE
PWM MODE (LOAD CURRENT STEPPED
FROM NO LOAD TO 150mA)

toc25b

V_OUT (AC)
200mV/div

FIGURE 8
APPLICATION CIRCUIT
V_OUT = 12V

I_OUT
100mA/div

40µs/div

SWITCHING WAVEFORMS
(PFM MODE)

MAX15062 toc26

FIGURE 6 APPLICATION CIRCUIT
V_OUT = 5V, LOAD = 20mA

V_OUT (AC)
100mV/div

V_LX
10V/div

I_OUT
100mA/div

10µs/div

FULL-LOAD SWITCHING WAVEFORMS
(PWM OR PFM MODE)

MAX15062 toc27

V_OUT = 5V,
LOAD = 300mA

V_OUT (AC)
20mV/div

V_LX
10V/div

I_OUT
200mA/div

2µs/div

Typical Operating Characteristicsc (continued)

(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, T_A = +25°C, unless otherwise noted.)

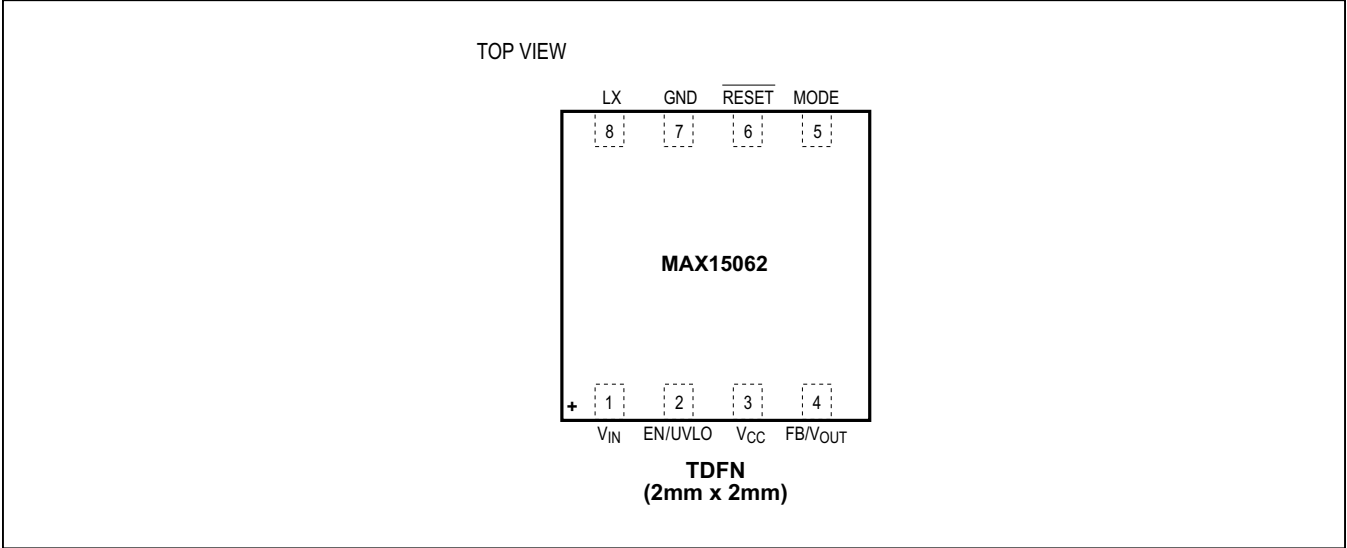**NO-LOAD SWITCHING WAVEFORMS (PWM MODE)**

SOFT-START

FIGURE 5
APPLICATION CIRCUIT
V_{OUT} = 3.3V

SOFT-START

FIGURE 6
APPLICATION CIRCUIT
V_{OUT} = 5V

SOFT-START

FIGURE 7
APPLICATION CIRCUIT
V_{OUT} = 2.5V

SOFT-START

FIGURE 8
APPLICATION CIRCUIT
V_{OUT} = 12V

SHUTDOWN WITH ENABLE

Typical Operating Characteristicsc (continued)

(V_{IN} = 24V, V_{GND} = 0V, C_{IN} = C_{VCC} = 1µF, $V_{EN/UVLO}$ = 1.5V, T_A = +25°C, unless otherwise noted.)

SOFT-START WITH 3V PREBIAS

$V_{EN/UVLO}$
5V/div

V_{OUT}
1V/div

FIGURE 6
APPLICATION CIRCUIT
NO LOAD
PWM MODE

$V_{\overline{RESET}}$
5V/div

1ms/div

OVERLOAD PROTECTION

V_{IN}
20V/div

V_{OUT}
2V/div

I_{OUT}
200mA/div

20ms/div

BODE PLOT

GAIN

PHASE

f_{CR} = 47kHz,
PHASE MARGIN = 59°

FIGURE 5 APPLICATION CIRCUIT
V_{OUT} = 3.3V

BODE PLOT

GAIN

PHASE

f_{CR} = 47kHz,
PHASE MARGIN = 60°

FIGURE 6 APPLICATION CIRCUIT
V_{OUT} = 5V

BODE PLOT

GAIN

PHASE

f_{CR} = 43kHz,
PHASE MARGIN = 60°

FIGURE 7 APPLICATION CIRCUIT
V_{OUT} = 2.5V

BODE PLOT

GAIN

PHASE

f_{CR} = 36kHz,
PHASE MARGIN = 66°

FIGURE 8 APPLICATION CIRCUIT
V_{OUT} = 12V

MAX15062, 5V OUTPUT, 0.3A LOAD CURRENT, CONDUCTED EMI CURVE

QUASI-PEAK LIMIT

AVERAGE LIMIT

PEAK EMISSIONS

AVERAGE EMISSIONS

Measured on the MAX15062BEVKIT with Input Filter–
C_{IN} = 4.7µF, L_{IN} = 10µH

Pin Configuration

TOP VIEW

```
         LX    GND  RESET  MODE

        │ 8 │ │ 7 │ │ 6 │ │ 5 │

                MAX15062

    +   │ 1 │ │ 2 │ │ 3 │ │ 4 │

         V_IN  EN/UVLO  V_CC  FB/V_OUT
```

TDFN
(2mm x 2mm)

Pin Description

PIN	NAME	FUNCTION
1	V_{IN}	Switching Regulator Power Input. Connect a X7R 1µF ceramic capacitor from V_{IN} to GND for bypassing.
2	EN/UVLO	Active-High, Enable/Undervoltage-Detection Input. Pull EN/UVLO to GND to disable the regulator output. Connect EN/UVLO to V_{IN} for always-on operation. Connect a resistor-divider between V_{IN} and EN/UVLO to GND to program the input voltage at which the device is enabled and turns on.
3	V_{CC}	Internal LDO Power Output. Bypass V_{CC} to GND with a minimum 1µF capacitor.
4	FB/V_{OUT}	Feedback Input. For fixed output voltage versions, connect FB/V_{OUT} directly to the output. For the adjustable output voltage version, connect FB/V_{OUT} to a resistor-divider between V_{OUT} and GND to adjust the output voltage from 0.9V to 0.89 x V_{IN}.
5	MODE	PFM/PWM Mode Selection Input. Connect MODE to GND to enable the fixed-frequency PWM operation. Leave unconnected for light-load PFM operation.
6	$\overline{RESET}$	Open-Drain Reset Output. Pull up $\overline{RESET}$ to an external power supply with an external resistor. $\overline{RESET}$ goes low when the output voltage drops below 92% of the set nominal regulated voltage. $\overline{RESET}$ goes high impedance 2ms after the output voltage rises above 95% of its regulation value. See the *Electrical Characteristics* table for threshold values.
7	GND	Ground. Connect GND to the power ground plane. Connect all the circuit ground connections together at a single point. See the *PCB Layout Guidelines* section.
8	LX	Inductor Connection. Connect LX to the switching side of the inductor. LX is high impedance when the device is in shutdown.

Block Diagram

Detailed Description

The MAX15062 high-efficiency, high-voltage, synchronous step-down DC-DC converter with integrated MOSFETs operates over a wide 4.5V to 60V input voltage range. The converter delivers output current up to 300mA at 3.3V (MAX15062A), 5V (MAX15062B), and adjustable output voltages (MAX15062C). When EN/UVLO and V_{CC} UVLO are satisfied, an internal power-up sequence soft-starts the error-amplifier reference, resulting in a clean monotonic output-voltage soft-start independent of the load current. The FB/V_{OUT} pin monitors the output voltage through a resistor-divider. $\overline{RESET}$ transitions to a high-impedance state 2ms after the output voltage reaches 95% of regulation. The device selects either PFM or forced-PWM mode depending on the state of the MODE pin at power-up. By pulling the EN/UVLO pin to low, the device enters the shutdown mode and consumes only 2.2µA (typ) of standby current.

DC-DC Switching Regulator

The device uses an internally compensated, fixed-frequency, current-mode control scheme (see the *Block Diagram*). On the rising edge of an internal clock, the high-side pMOSFET turns on. An internal error amplifier compares the feedback voltage to a fixed internal reference voltage and generates an error voltage. The error voltage is compared to a sum of the current-sense voltage and a slope-compensation voltage by a PWM comparator to set the on-time. During the on-time of the pMOSFET, the inductor current ramps up. For the remainder of the switching period (off-time), the pMOSFET is kept off and the low-side nMOSFET turns on. During the off-time, the inductor releases the stored energy as the inductor current ramps down, providing current to the output. Under overload conditions, the cycle-by-cycle current-limit feature limits the inductor peak current by turning off the high-side pMOSFET and turning on the low-side nMOSFET.

Mode Selection (MODE)

The logic state of the MODE pin is latched after V_{CC} and EN/UVLO voltages exceed respective UVLO rising thresholds and all internal voltages are ready to allow LX switching. If the MODE pin is unconnected at power-up, the part operates in PFM mode at light loads. If the MODE pin is grounded at power-up, the part operates in constant-frequency PWM mode at all loads. State changes on the MODE pin are ignored during normal operation.

PWM Mode Operation

In PWM mode, the inductor current is allowed to go negative. PWM operation is useful in frequency sensitive applications and provides fixed switching frequency at all loads. However, the PWM mode of operation gives lower efficiency at light loads compared to PFM mode of operation.

PFM Mode Operation

PFM mode operation disables negative inductor current and additionally skips pulses at light loads for high efficiency. In PFM mode, the inductor current is forced to a fixed peak of 130mA every clock cycle until the output rises to 102.3% of the nominal voltage. Once the output reaches 102.3% of the nominal voltage, both high-side and low-side FETs are turned off and the part enters hibernate operation until the load discharges the output to 101.1% of the nominal voltage. Most of the internal blocks are turned off in hibernate operation to save quiescent current. After the output falls below 101.1% of the nominal voltage, the device comes out of hibernate operation, turns on all internal blocks, and again commences the process of delivering pulses of energy to the output until it reaches 102.3% of the nominal output voltage. The device naturally exits PFM mode when the load current exceeds 55mA (typ). The advantage of the PFM mode is higher efficiency at light loads because of lower quiescent current drawn from supply.

Internal 5V Linear Regulator

An internal regulator provides a 5V nominal supply to power the internal functions and to drive the power MOSFETs. The output of the linear regulator (V_{CC}) should be bypassed with a 1µF capacitor to GND. The V_{CC} regulator dropout voltage is typically 150mV. An undervoltage-lockout circuit that disables the regulator when V_{CC} falls below 3.8V (typ). The 400mV V_{CC} UVLO hysteresis prevents chattering on power-up and power-down.

Enable Input (EN/UVLO), Soft-Start

When EN/UVLO voltage is above 1.21V (typ), the device's internal error-amplifier reference voltage starts to ramp up. The duration of the soft-start ramp is 4.1ms, allowing a smooth increase of the output voltage. Driving EN/UVLO low disables both power MOSFETs, as well as other internal circuitry, and reduces V_{IN} quiescent current to below 2.2µA. EN/UVLO can be used as an input-voltage UVLO adjustment input. An external voltage-divider between V_{IN} and EN/UVLO to GND adjusts the input voltage at which the device turns on or turns off. If input UVLO programming is not desired, connect EN/UVLO to V_{IN} (see the *Electrical Characteristics* table for EN/UVLO rising and falling threshold voltages).

Reset Output ($\overline{RESET}$)

The device includes an open-drain $\overline{RESET}$ output to monitor the output voltage. $\overline{RESET}$ goes high impedance 2ms after the output rises above 95% of its nominal set value and pulls low when the output voltage falls below 92% of the set nominal regulated voltage. $\overline{RESET}$ asserts low during the hiccup timeout period.

Startup into a Prebiased Output

The device is capable of soft-start into a prebiased output, without discharging the output capacitor in both the PFM and forced-PWM modes. Such a feature is useful in applications where digital integrated circuits with multiple rails are powered.

Operating Input Voltage Range

The maximum operating input voltage is determined by the minimum controllable on-time and the minimum operating input voltage is determined by the maximum duty cycle and circuit voltage drops. The minimum and maximum operating input voltages for a given output voltage should be calculated as follows:

$$V_{INMIN} = \frac{V_{OUT} + (I_{OUT} \times (R_{DCR} + 0.5))}{D_{MAX}} + (I_{OUT} \times 1.0)$$

$$V_{INMAX} = \frac{V_{OUT}}{t_{ONMIN} \times f_{SW}}$$

where V_{OUT} is the steady-state output voltage, I_{OUT} is the maximum load current, R_{DCR} is the DC resistance of the inductor, f_{SW} is the switching frequency (max), D_{MAX} is maximum duty cycle (0.89), and t_{ONMIN} is the worst-case minimum controllable switch on-time (130ns).

Overcurrent Protection/Hiccup Mode

The device is provided with a robust overcurrent protection scheme that protects the device under overload and output short-circuit conditions. A cycle-by-cycle peak current limit turns off the high-side MOSFET whenever the high-side switch current exceeds an internal limit of 0.56A (typ). A runaway current limit on the high-side switch current at 0.66A (typ) protects the device under high input voltage, and short-circuit conditions when there is insufficient output voltage available to restore the inductor current that was built up during the on period of the step-down converter. One occurrence of the runaway current limit triggers a hiccup mode. In addition, if due

to a fault condition, output voltage drops to 65% (typ) of its nominal value any time after soft-start is complete, hiccup mode is triggered. In hiccup mode, the converter is protected by suspending switching for a hiccup timeout period of 131ms. Once the hiccup timeout period expires, soft-start is attempted again. Hiccup mode of operation ensures low power dissipation under output short-circuit conditions.

Care should be taken in board layout and system wiring to prevent violation of the absolute maximum rating of the FB/V_{OUT} pin under short-circuit conditions. Under such conditions, it is possible for the ceramic output capacitor to oscillate with the board or wiring inductance between the output capacitor or short-circuited load, thereby causing the absolute maximum rating of FB/V_{OUT} (-0.3V) to be exceeded. The parasitic board or wiring inductance should be minimized and the output voltage waveform under short-circuit operation should be verified to ensure the absolute maximum rating of FB/V_{OUT} is not exceeded.

Thermal Overload Protection

Thermal overload protection limits the total power dissipation in the device. When the junction temperature exceeds +166°C, an on-chip thermal sensor shuts down the device, turns off the internal power MOSFETs, allowing the device to cool down. The thermal sensor turns the device on after the junction temperature cools by 10°C.

Applications Information

Inductor Selection

A low-loss inductor having the lowest possible DC resistance that fits in the allotted dimensions should be selected. The saturation current (I_{SAT}) must be high enough to ensure that saturation cannot occur below the maximum current-limit value. The required inductance for a given application can be determined from the following equation:

$$L = 9.3 \times V_{OUT}$$

where L is inductance in µH and V_{OUT} is output voltage. Once the L value is known, the next step is to select the right core material. Ferrite and powdered iron are commonly available core materials. Ferrite cores have low core losses and are preferred for high-efficiency designs. Powdered iron cores have more core losses and are relatively cheaper than ferrite cores. See Table 1 to select the inductors for typical applications.

Table 1. Inductor Selection

INPUT VOLTAGE RANGE V_{IN} (V)	V_{OUT} (V)	I_{OUT} (mA)	L (µH)	RECOMMENDED PART NO.
4.5 to 60	3.3 (Fixed)	300	33	Coilcraft LPS4018-333ML
6 to 60	5 (Fixed)	300	47	Coilcraft LPS4018-473ML
4.5 to 60	1.8 or 2.5	300	22	Coilcraft LPS4018-223ML
14 to 60	12	300	100	Wurth 74408943101
17 to 60	15	300	150	TDK VLC6045T-151M

Table 2. Output Capacitor Selection

INPUT VOLTAGE RANGE V_{IN} (V)	V_{OUT} (V)	I_{OUT} (mA)	C_{OUT} (µF)	RECOMMENDED PART NO.
4.5 to 60	3.3 (Fixed)	300	10µF/1206/X7R/6.3V	Murata GRM31CR70J106K
6 to 60	5 (Fixed)	300	10µF/1206/X7R/6.3V	Murata GRM31CR70J106K
4.5 to 60	1.8 or 2.5	300	22µF/1206/X7R/6.3V	Murata GRM31CR70J226K
14 to 60	12	300	4.7µF/1206/X7R/16V	Murata GRM31CR71C475K
17 to 60	15	300	4.7µF/1206/X7R/25V	Murata GRM31CR71E475K
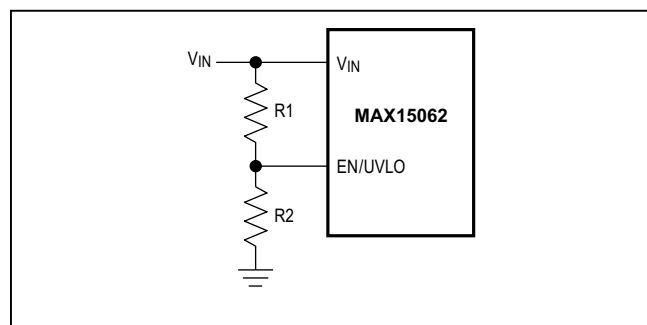
Figure 1. Adjustable EN/UVLO Network

Input Capacitor

The input filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple on the input caused by the circuit's switching. The input capacitor RMS current requirement (I_{RMS}) is defined by the following equation:

$$I_{RMS} = I_{OUT(MAX)} \times \frac{\sqrt{(V_{OUT} \times (V_{IN} - V_{OUT})}}{V_{IN}}$$

where, $I_{OUT(MAX)}$ is the maximum load current. I_{RMS} has a maximum value when the input voltage equals twice the output voltage ($V_{IN} = 2 \times V_{OUT}$), so $I_{RMS(MAX)} = I_{OUT(MAX)}/2$.

Choose an input capacitor that exhibits less than +10°C temperature rise at the RMS input current for optimal long-term reliability. Use low-ESR ceramic capacitors with high-ripple-current capability at the input. X7R capacitors are recommended in industrial applications for their temperature stability. Calculate the input capacitance using the following equation:

$$C_{IN} = I_{OUT(MAX)} \times D \times \frac{(1 - D)}{\eta \times f_{SW} \times \Delta V_{IN}}$$

where $D = V_{OUT}/V_{IN}$ is the duty ratio of the converter, f_{SW} is the switching frequency, ΔV_{IN} is the allowable input voltage ripple, and η is the efficiency.

In applications where the source is located distant from the device input, an electrolytic capacitor should be added in parallel to the ceramic capacitor to provide necessary damping for potential oscillations caused by the inductance of the longer input power path and input ceramic capacitor.

Output Capacitor

Small ceramic X7R-grade capacitors are sufficient and recommended for the device. The output capacitor has two functions. It filters the square wave generated by the device along with the output inductor. It stores sufficient energy to support the output voltage under load transient conditions and stabilizes the device's internal control loop. Usually the output capacitor is sized to support a step load of 50% of the maximum output current in the application, such that the output-voltage deviation is less than 3%. Required output capacitance can be calculated from the following equation:

$$C_{OUT} = \frac{30}{V_{OUT}}$$

where C_{OUT} is the output capacitance in µF and V_{OUT} is the output voltage. Derating of ceramic capacitors with DC-voltage must be considered while selecting the output capacitor. Derating curves are available from all major ceramic capacitor vendors. See Table 2 to select the output capacitor for typical applications.

Setting the Input Undervoltage-Lockout Level

The devices offer an adjustable input undervoltage-lockout level. Set the voltage at which the device turns on with a resistive voltage-divider connected from V_{IN} to GND (see Figure 1). Connect the center node of the divider to EN/UVLO.

Choose R1 to be 3.3MΩ max, and then calculate R2 as follows:

$$R2 = \frac{R1 \times 1.215}{(V_{INU} - 1.215)}$$

where V_{INU} is the voltage at which the device is required to turn on.

If the EN/UVLO pin is driven from an external signal source, a series resistance of minimum 1kΩ is recommended to be placed between the signal source output and the EN/UVLO pin, to reduce voltage ringing on the line.

Adjusting the Output Voltage

The MAX15062C output voltage can be programmed from 0.9V to 0.89 x V_{IN}. Set the output voltage by connecting a resistor-divider from output to FB to GND (see Figure 2).

For the output voltages less than 6V, choose R2 in the 50kΩ to 150kΩ range. For the output voltages greater than 6V, choose R2 in the 25kΩ to 75kΩ range and calculate R1 with the following equation:

$$R1 = R2 \times \left[\frac{V_{OUT}}{0.9} - 1 \right]$$

Power Dissipation

At a particular operating condition, the power losses that lead to temperature rise of the part are estimated as follows:

$$P_{LOSS} = \left(P_{OUT} \times \left(\frac{1}{\eta} - 1 \right) \right) - (I_{OUT}{}^2 \times R_{DCR})$$

$$P_{OUT} = V_{OUT} \times I_{OUT}$$

where P_{OUT} is the output power, η is the efficiency of power conversion, and R_{DCR} is the DC resistance of the output inductor. See the *Typical Operating Characteristics* for the power-conversion efficiency or measure the efficiency to determine the total power dissipation.

The junction temperature (T_J) of the device can be estimated at any ambient temperature (T_A) from the following equation:

$$T_J = T_A + (\theta_{JA} \times P_{LOSS})$$

where θ_{JA} is the junction-to-ambient thermal impedance of the package.

Junction temperature greater than +125°C degrades operating lifetimes.

PCB Layout Guidelines

Careful PCB layout is critical to achieve clean and stable operation. The switching power stage requires particular attention. Follow the guidelines below for good PCB layout.

● Place the input ceramic capacitor as close as possible to the V_{IN} and GND pins.

● Connect the negative terminal of the V_{CC} bypass capacitor to the GND pin with shortest possible trace or ground plane.

● Minimize the area formed by the LX pin and the inductor connection to reduce the radiated EMI.

● Place the V_{CC} decoupling capacitor as close as possible to the V_{CC} pin.

● Ensure that all feedback connections are short and direct.

● Route the high-speed switching node (LX) away from the FB/V_{OUT}, $\overline{RESET}$, and MODE pins.

For a sample PCB layout that ensures the first-pass success, refer to the MAX15062 evaluation kit layouts available at **www.maximintegrated.com**.
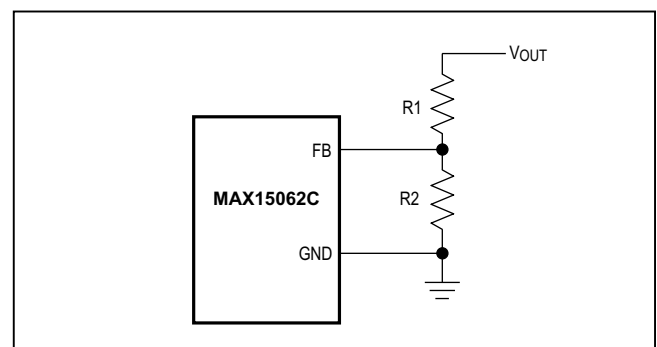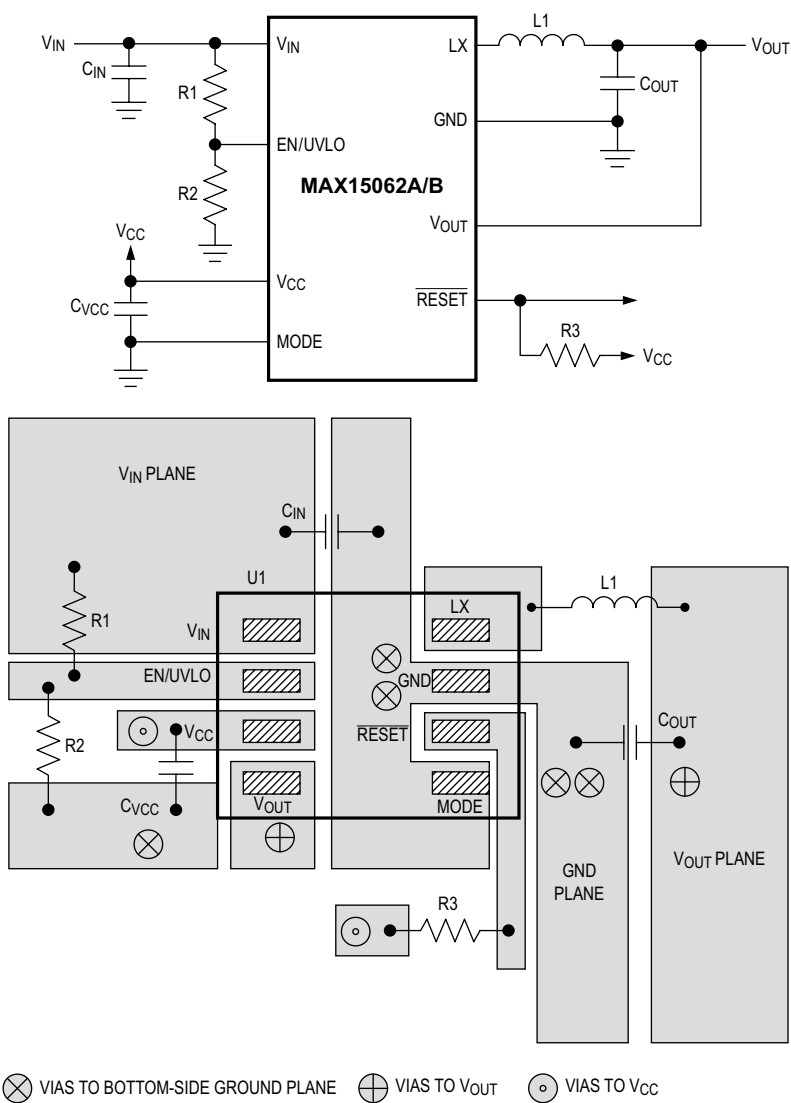

Figure 2. Setting the Output Voltage

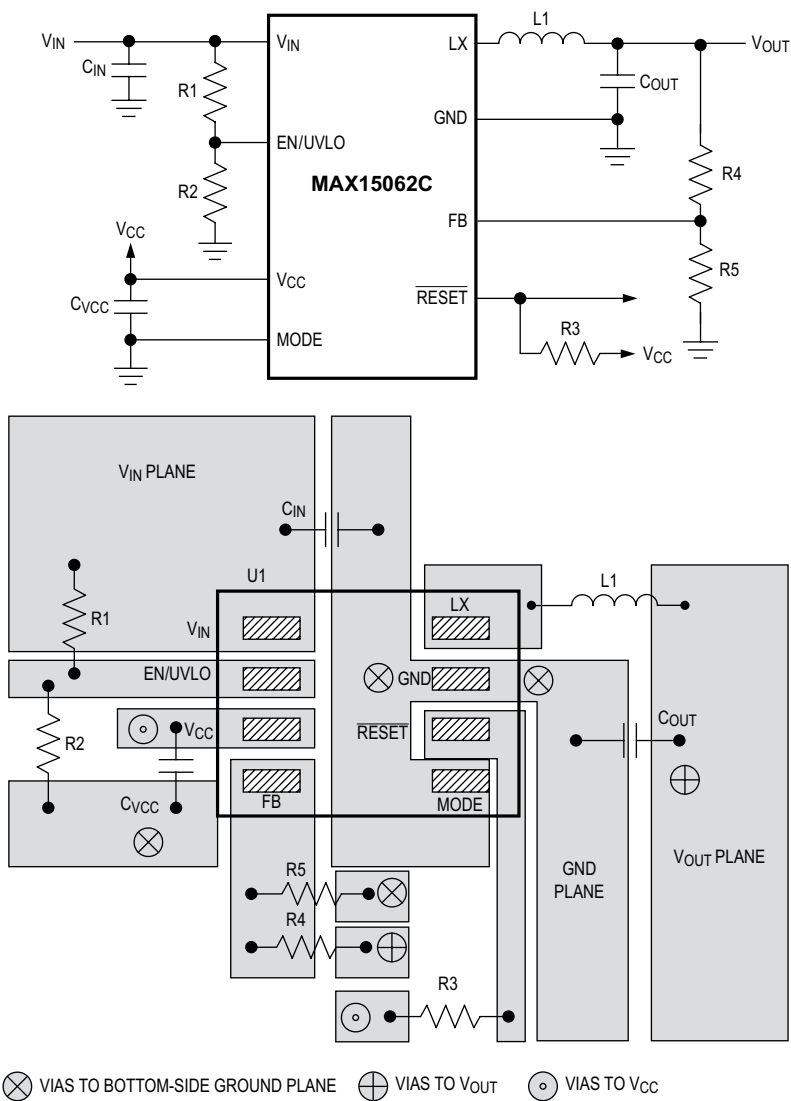*Figure 3. Layout Guidelines for MAX15062A and MAX15062B*

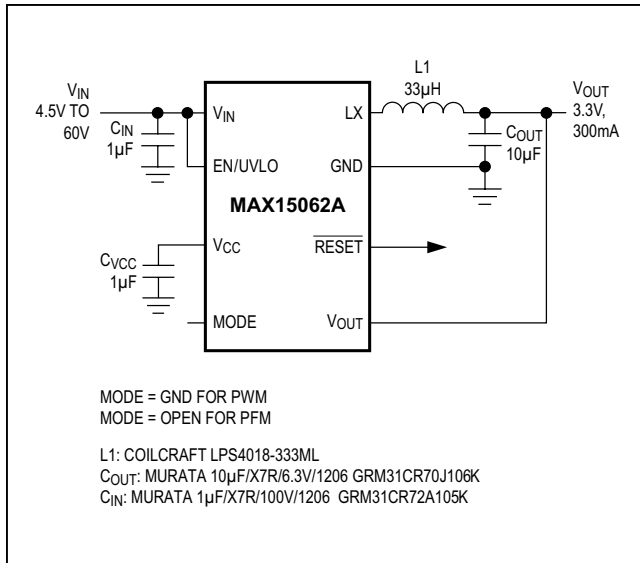*Figure 4. Layout Guidelines for MAX15062C*
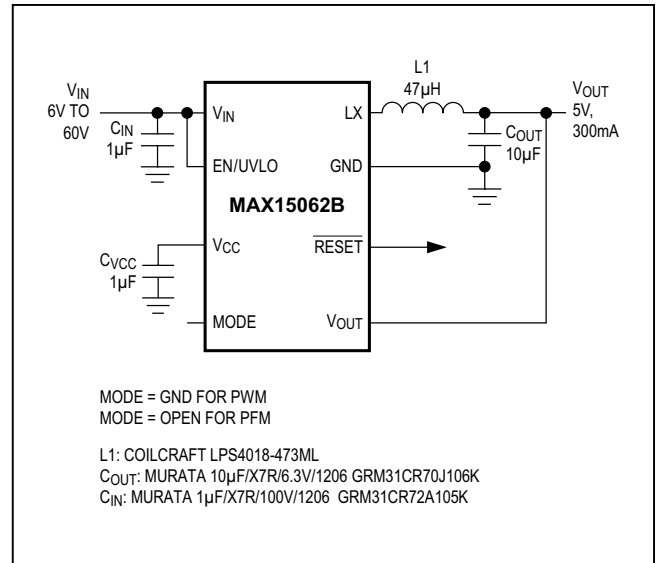
Figure 5. 3.3V, 300mA Step-Down Regulator

Figure 6. 5V, 300mA Step-Down Regulator
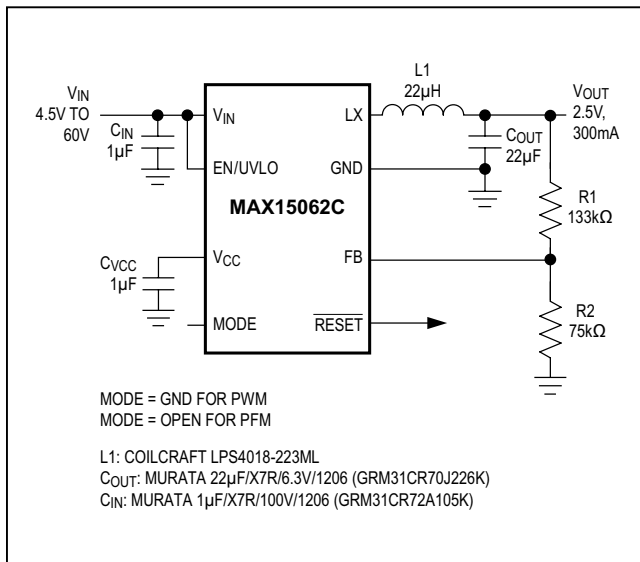
Figure 7. 2.5V, 300mA Step-Down Regulator

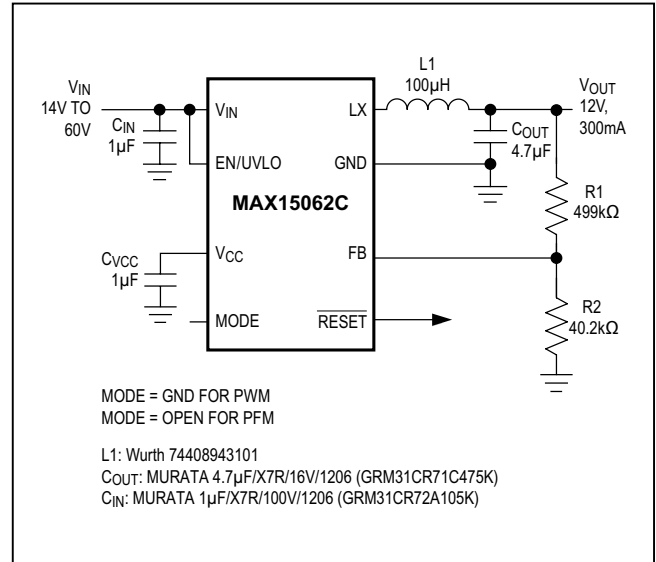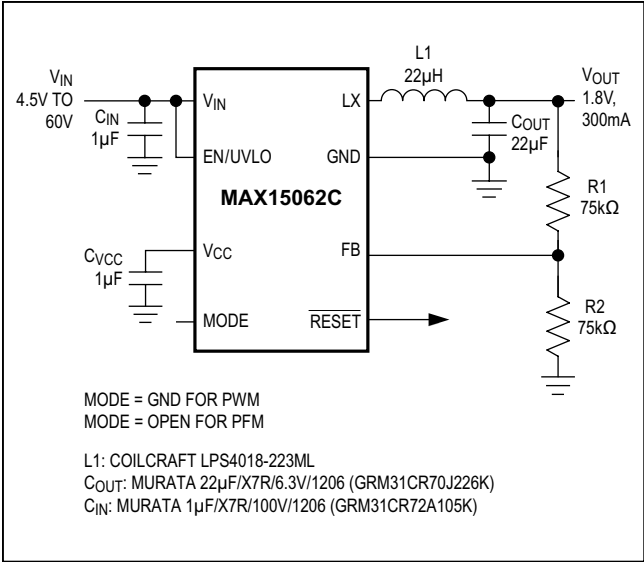Figure 8. 12V, 300mA Step-Down Regulator

Figure 9. 1.8V, 300mA Step-Down Regulator
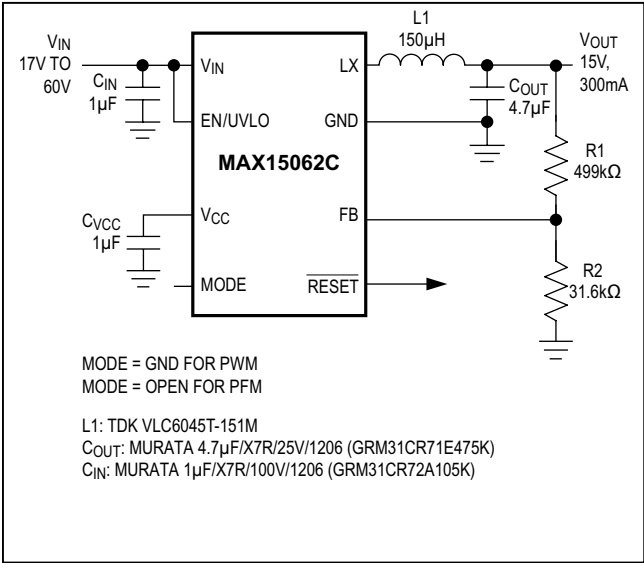
Figure 10. 15V, 300mA Step-Down Regulator

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	V_{OUT}
MAX15062AATA+	-40°C to +125°C	8 TDFN	3.3V
MAX15062BATA+	-40°C to +125°C	8 TDFN	5V
MAX15062CATA+	-40°C to +125°C	8 TDFN	Adj

+Denotes a lead(Pb)-free/RoHS-compliant package.

Chip Information

PROCESS: BiCMOS

Package Information

For the latest package outline information and land patterns (footprints), go to **www.maximintegrated.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
8 TDFN	T822CN+1	**21-0487**	**90-0349**

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	6/13	Initial release	—
1	10/13	Added MAX15062C, added figures, updated tables and figures throughout	1–17
2	7/16	Operating and Junction temperature value update, additional TOC and text.	1–4, 12, 16–18

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at www.maximintegrated.com.