

TABLE OF CONTENTS

Features	1	Insertion Loss, Return Loss, State Error, Step Error, and Relative Phase	8
Applications	1	Input Power Compression and Third-Order Intercept.....	12
Functional Block Diagram	1	Theory of Operation	13
General Description	1	Power Supply.....	13
Revision History	2	RF Input and Output	13
Specifications.....	3	Serial or Parallel Mode Selection	14
Electrical Specifications.....	3	Serial Mode Interface.....	14
Timing Specifications	5	Parallel Mode Interface.....	15
Absolute Maximum Ratings.....	6	Applications Information	16
Power Derating Curves.....	6	Evaluation Board	16
ESD Caution.....	6	Probe Matrix Board	18
Pin Configuration and Function Descriptions.....	7	Outline Dimensions	19
Interface Schematics.....	7	Ordering Guide	19
Typical Performance Characteristics	8		

REVISION HISTORY

3/2020—Rev. 0 Rev. A

Changes to RF Power Parameter, Table 1	5
Changes to Table 3.....	6
Changes to Power Supply Section	13
Added Power-Up State Section.....	13
Moved Serial or Parallel Mode Selection Section and Table 7;	
Renumbered Sequentially	14

7/2018—Revision 0: Initial Version

SPECIFICATIONS

ELECTRICAL SPECIFICATIONS

$V_{DD} = 3.3\text{ V}$, $V_{SS} = -3.3\text{ V}$, digital voltages = 0 V or V_{DD} , case temperature (T_{CASE}) = 25°C, and 50 Ω system, unless otherwise noted.

Table 1.

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
FREQUENCY RANGE		100		40,000	MHz
INSERTION LOSS (IL)					
With Impedance Match	See Figure 44				
	100 MHz to 10 GHz		1.6		dB
	10 GHz to 18 GHz		2.1		dB
	18 GHz to 26 GHz		2.9		dB
	26 GHz to 35 GHz		3.8		dB
	35 GHz to 40 GHz		4.8		dB
Without Impedance Match	See Figure 43				
	100 MHz to 10 GHz		1.6		dB
	10 GHz to 18 GHz		2.1		dB
	18 GHz to 26 GHz		2.7		dB
	26 GHz to 35 GHz		3.7		dB
	35 GHz to 40 GHz		5.2		dB
RETURN LOSS	ATTIN and ATTOUT, all attenuation states				
With Impedance Match	See Figure 44				
	100 MHz to 10 GHz		20		dB
	10 GHz to 18 GHz		19		dB
	18 GHz to 26 GHz		13		dB
	26 GHz to 35 GHz		11		dB
	35 GHz to 40 GHz		11		dB
Without Impedance Match	See Figure 43				
	100 MHz to 10 GHz		19		dB
	10 GHz to 18 GHz		18		dB
	18 GHz to 26 GHz		16		dB
	26 GHz to 35 GHz		13		dB
	35 GHz to 40 GHz		9		dB
ATTENUATION					
Range	Between minimum and maximum attenuation states		31.5		dB
Step Size	Between any successive attenuation states		0.5		dB
Accuracy	Referenced to insertion loss				
With Impedance Match	See Figure 44				
	100 MHz to 10 GHz		$\pm(0.10 + 0.6\% \text{ of state})$		dB
	10 GHz to 18 GHz		$\pm(0.10 + 1.0\% \text{ of state})$		dB
	18 GHz to 26 GHz		$\pm(0.15 + 0.8\% \text{ of state})$		dB
	26 GHz to 35 GHz		$\pm(0.20 + 2.0\% \text{ of state})$		dB
	35 GHz to 40 GHz		$\pm(0.35 + 2.5\% \text{ of state})$		dB
Without Impedance Match	See Figure 43				
	100 MHz to 10 GHz		$\pm(0.10 + 0.5\% \text{ of state})$		dB
	10 GHz to 18 GHz		$\pm(0.10 + 1.0\% \text{ of state})$		dB
	18 GHz to 26 GHz		$\pm(0.15 + 0.8\% \text{ of state})$		dB
	26 GHz to 35 GHz		$\pm(0.25 + 1.8\% \text{ of state})$		dB
	35 GHz to 40 GHz		$\pm(0.40 + 5.0\% \text{ of state})$		dB

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
Step Error	Between any successive state				
With Impedance Match	See Figure 44				
	100 MHz to 10 GHz		±0.11		dB
	10 GHz to 18 GHz		±0.18		dB
	18 GHz to 26 GHz		±0.23		dB
	26 GHz to 35 GHz		±0.3		dB
	35 GHz to 40 GHz		±0.51		dB
Without Impedance Match	See Figure 43				
	100 MHz to 10 GHz		±0.11		dB
	10 GHz to 18 GHz		±0.19		dB
	18 GHz to 26 GHz		±0.23		dB
	26 GHz to 35 GHz		±0.26		dB
	35 GHz to 40 GHz		±0.65		dB
RELATIVE PHASE	Referenced to insertion loss				
With Impedance Match	See Figure 44				
	10 GHz		15		Degrees
	18 GHz		30		Degrees
	26 GHz		50		Degrees
	35 GHz		75		Degrees
	40 GHz		100		Degrees
Without Impedance Match	See Figure 43				
	10 GHz		15		Degrees
	18 GHz		30		Degrees
	26 GHz		50		Degrees
	35 GHz		75		Degrees
	40 GHz		110		Degrees
SWITCHING CHARACTERISTICS	All attenuation states at input power = 10 dBm				
Rise and Fall Time (t_{RISE} and t_{FALL})	10% to 90% of RF output		35		ns
On and Off Time (t_{ON} and t_{OFF})	50% triggered control (CTL) to 90% of RF output		125		ns
RF Amplitude Settling Time					
0.1 dB	50% triggered CTL to 0.1 dB of final RF output		250		ns
0.05 dB	50% triggered CTL to 0.05 dB of final RF output		350		ns
Overshoot			1		dB
Undershoot			-2.5		dB
RF Phase Settling Time	$f = 5$ GHz				
5°	50% triggered CTL to 5° of final RF output		160		ns
1°	50% triggered CTL to 1° of final RF output		180		ns
INPUT LINEARITY ¹	100 MHz to 30 GHz				
0.1 dB Power Compression (P0.1dB)					
Insertion Loss State			30		dBm
Other Attenuation States			27		dBm
Third-Order Intercept (IP3)	Two-tone input power = 14 dBm per tone, $\Delta f = 1$ MHz, all attenuation states		50		dBm
DIGITAL CONTROL INPUTS	LE, PS, D0, D1, D2, D3/SEROUT ² , D4/SERIN, D5/CLK pins				
Voltage					
Low (V_{INL})		0		0.8	V
High (V_{INH})		1.2		3.3	V
Current					
Low (I_{INL})			<1		μA
High (I_{INH})	D0, D1, D2		33		μA
	LE, PS, D3/SEROUT ² , D4/SERIN, D5/CLK pins		<1		μA

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
DIGITAL CONTROL OUTPUT Voltage Low (V_{OUTL}) High (V_{OUTH}) Current (I_{OUTL} , I_{OUTH})	D3/SEROUT pin ²		0 ± 0.3 $V_{DD} \pm 0.3$	0.5	V V mA
SUPPLY CURRENT Positive Supply Current Negative Supply Current	VDD and VSS pins		117 -117		μ A μ A
RECOMMENDED OPERATING CONDITIONS Supply Voltage Positive (V_{DD}) Negative (V_{SS}) Digital Control Voltage		3.15 -3.45 0		3.45 -3.15 V_{DD}	V V V
RF Power ³ Input at ATTIN Input at ATTOUT Case Temperature (T_{CASE})	$f = 100 \text{ MHz to } 30 \text{ GHz}$, $T_{CASE} = 85^\circ\text{C}$, ⁴ all attenuation states Steady state average Steady state peak Hot switching average Hot switching peak Steady state average Steady state peak Hot switching average Hot switching peak			27 30 24 27 18 21 15 18	 dBm dBm dBm dBm dBm dBm dBm dBm $^\circ\text{C}$
		-40		+105	

¹ Input linearity performance degrades over frequency, see Figure 30 and Figure 31.

² The D3/SEROUT pin is an input in parallel control mode and an output in serial control mode. See Table 5 for the pin function descriptions.

³ For power derating over frequency, see Figure 2 to Figure 3. Applicable for all ATTIN and ATTOUT power specifications.

⁴ For 105°C operation, the power handling degrades from the $T_{CASE} = 85^\circ\text{C}$ specifications by 3 dB.

TIMING SPECIFICATIONS

See Figure 34, Figure 35, and Figure 36 for the timing diagrams.

Table 2.

Parameter	Description	Min	Typ	Max	Unit
t_{SCK}	Minimum serial period, see Figure 34	70			ns
t_{CS}	Control setup time, see Figure 34	15			ns
t_{CH}	Control hold time, see Figure 34		20		ns
t_{LN}	LE setup time, see Figure 34	15			ns
t_{LEW}	Minimum LE pulse width, see Figure 34 and Figure 36		10		ns
t_{LES}	Minimum LE pulse spacing, see Figure 34		630		ns
t_{CKN}	Serial clock hold time from LE, see Figure 34		0		ns
t_{PH}	Hold time, see Figure 36		10		ns
t_{PS}	Setup time, see Figure 36		2		ns
t_{CO}	Clock to output (SEROUT) time, see Figure 35		20		ns

ABSOLUTE MAXIMUM RATINGS

Table 3.

Parameter	Rating
Positive Supply Voltage	−0.3 V to +3.6 V
Negative Supply Voltage	−3.6 V to +0.3 V
Digital Control Inputs	
Voltage	−0.3 V to $V_{DD} + 0.3$ V
Current	3 mA
RF Power ¹ (f = 100 MHz to 30 GHz, T _{CASE} = 85°C ²)	
Input at ATTIN	
Steady State Average	28 dBm
Steady State Peak	31 dBm
Hot Switching Average	25 dBm
Hot Switching Peak	28 dBm
Input at ATTOUT	
Steady State Average	19 dBm
Steady State Peak	22 dBm
Hot Switching Average	16 dBm
Hot Switching Peak	19 dBm
RF Power Under Unbiased Condition (V _{DD} , V _{SS} = 0 V)	
Input at ATTIN	21 dBm
Input at ATTOUT	15 dBm
Temperature	
Junction (T _J)	135°C
Storage	−65°C to +150°C
Reflow	260°C
Continuous Power Dissipation (P _{DISS})	0.5 W
ESD Sensitivity	
Human Body Model (HBM)	
ATTIN and ATTOUT Pins	500 V
Digital Pins	2000 V
Charged Device Model (CDM)	1250 V

¹ For power derating over frequency, see Figure 2 and Figure 3. Applicable for all ATTIN and ATTOUT power specifications.

² For 105°C operation, the power handling degrades from the T_{CASE} = 85°C specifications by 3 dB.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

THERMAL RESISTANCE

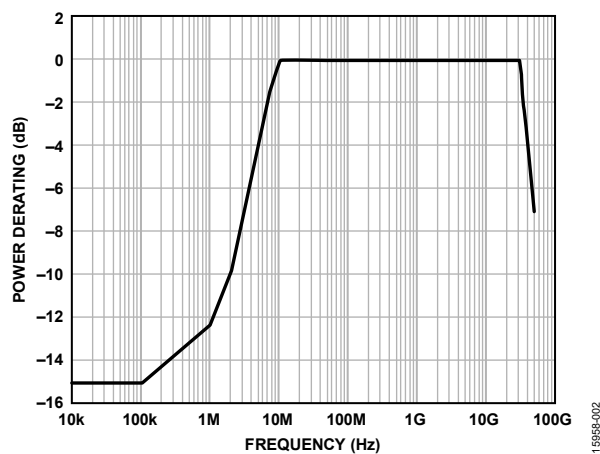
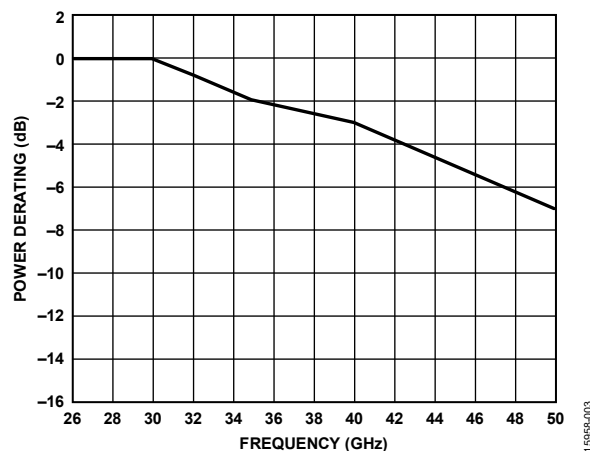
Thermal performance is directly linked to printed circuit board (PCB) design and operating environment. Careful attention to PCB thermal design is required.

θ_{JC} is the junction to case bottom (channel to package bottom) thermal resistance.

Table 4. Thermal Resistance

Package Type	θ_{JC}	Unit
CC-24-5	100	°C/W

POWER DERATING CURVES

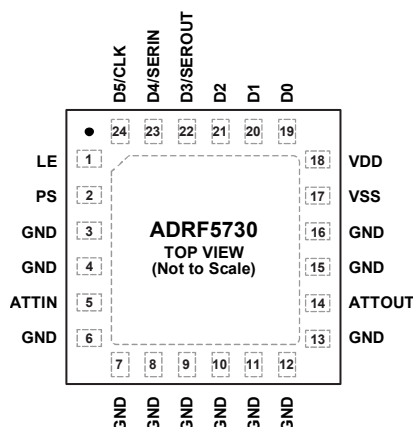
Figure 2. Power Derating vs. Frequency, Low Frequency Detail, T_{CASE} = 85°CFigure 3. Power Derating vs. Frequency, High Frequency Detail, T_{CASE} = 85°C

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



NOTES
1. THE EXPOSED PAD MUST BE CONNECTED TO THE RF AND DC GROUND OF THE PCB.

15958-004

Figure 4. Pin Configuration

Table 5. Pin Function Descriptions

Pin No.	Mnemonic	Description
1	LE	Latch Enable Input. See the Theory of Operation section for more information.
2	PS	Parallel or Serial Control Interface Selection Input. See the Theory of Operation section for more information.
3, 4, 6 to 13, 15, 16	GND	Ground. These pins must be connected to the RF and dc ground of the PCB.
5	ATTIN	Attenuator Input. This pin is dc-coupled to 0 V and ac matched to 50 Ω . No dc blocking capacitor is necessary when the RF line potential is equal to 0 V dc.
14	ATTOUT	Attenuator Output. This pin is dc-coupled to 0 V and ac matched to 50 Ω . No dc blocking capacitor is necessary when the RF line potential is equal to 0 V dc.
17	VSS	Negative Supply Input.
18	VDD	Positive Supply Input.
19	D0	Parallel Control Input for 0.5 dB Attenuator Bit. See the Theory of Operation section for more information.
20	D1	Parallel Control Input for 1 dB Attenuator Bit. See the Theory of Operation section for more information.
21	D2	Parallel Control Input for 2 dB Attenuator Bit. See the Theory of Operation section for more information.
22	D3/SEROUT	Parallel Control Input for 4 dB Attenuator Bit (D3). Serial Data Output (SEROUT). See the Theory of Operation section for more information.
23	D4/SERIN	Parallel Control Input for 8 dB Attenuator Bit (D4). Serial Data Input (SERIN). See the Theory of Operation section for more information.
24	D5/CLK	Parallel Control Input for 16 dB Attenuator Bit (D5). Serial Clock Input (CLK). See the Theory of Operation section for more information.
	EPAD	Exposed Pad. The exposed pad must be connected to the RF and dc ground of the PCB.

INTERFACE SCHEMATICS

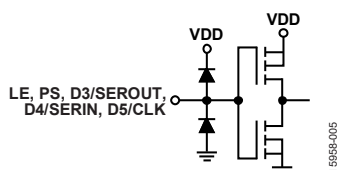


Figure 5. Digital Input Interface (LE, PS, D3/SEROUT, D4/SERIN, D5/CLK)

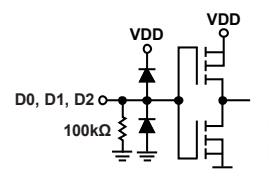


Figure 7. Digital Input Interface (D0, D1, D2)

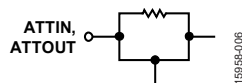


Figure 6. ATTIN and ATTOUT Interface

TYPICAL PERFORMANCE CHARACTERISTICS

INSERTION LOSS, RETURN LOSS, STATE ERROR, STEP ERROR, AND RELATIVE PHASE

$V_{DD} = 3.3$ V, $V_{SS} = -3.3$ V, digital voltages = 0 V or V_{DD} , $T_{CASE} = 25^{\circ}\text{C}$, and a $50\ \Omega$ system, unless otherwise noted. Measured on probe matrix board using ground signal ground (GSG) probes close to the RF pins. See the Applications Information section for details on evaluation and probe matrix boards.

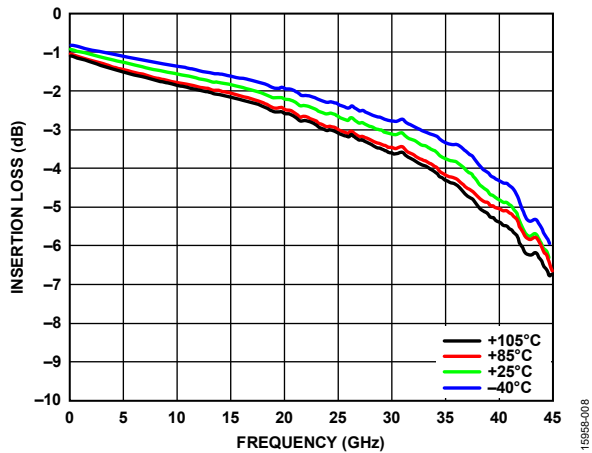


Figure 8. Insertion Loss vs. Frequency over Temperature with Impedance Match

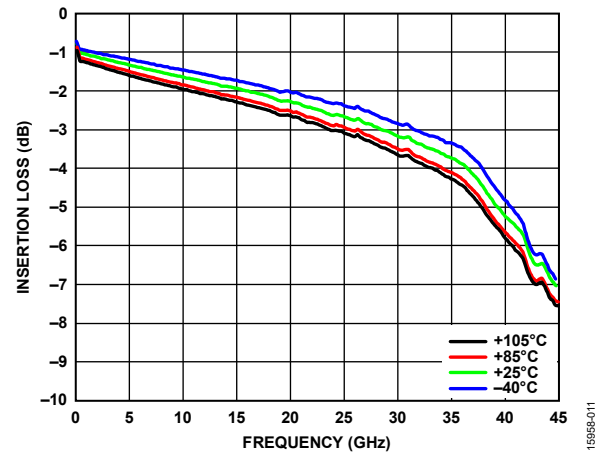


Figure 11. Insertion Loss vs. Frequency over Temperature Without Impedance Match

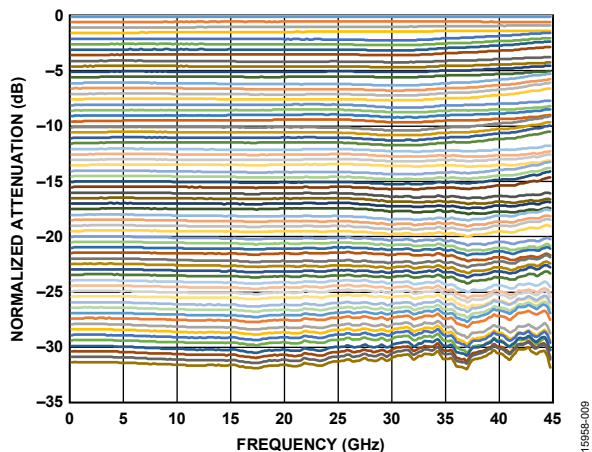


Figure 9. Normalized Attenuation vs. Frequency for All States at Room Temperature, with Impedance Match

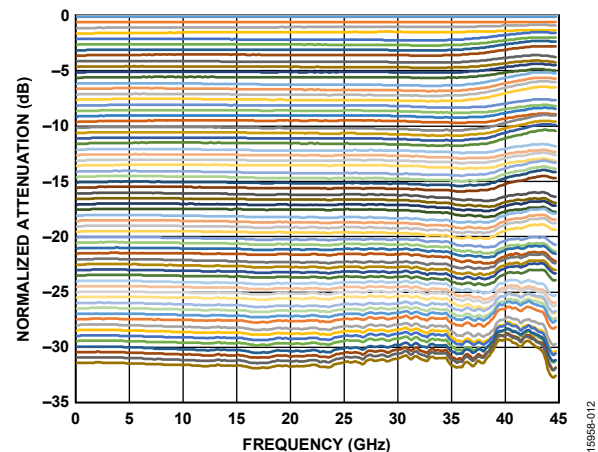


Figure 12. Normalized Attenuation vs. Frequency for All States at Room Temperature Without Impedance Match

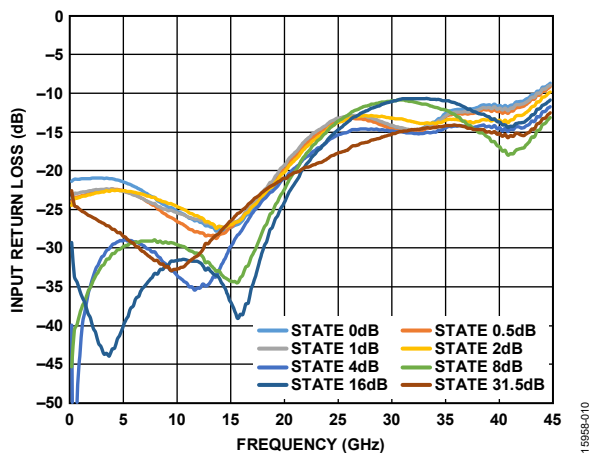


Figure 10. Input Return Loss vs. Frequency (Major States Only) with Impedance Match

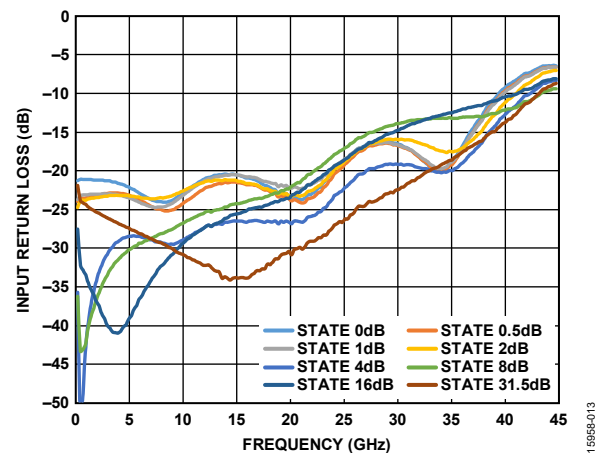


Figure 13. Input Return Loss vs. Frequency (Major States Only) Without Impedance Match

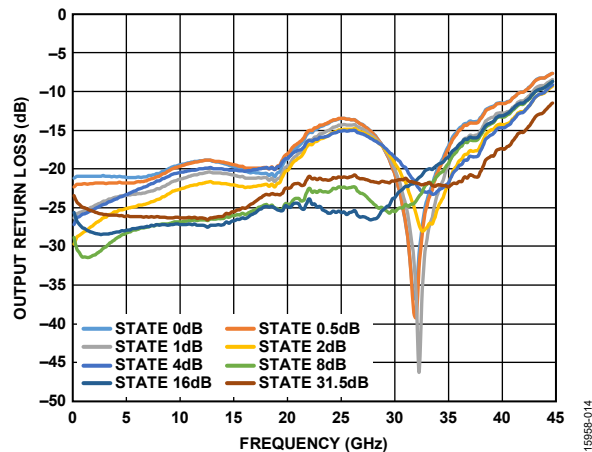


Figure 14. Output Return Loss vs. Frequency (Major States Only) with Impedance Match

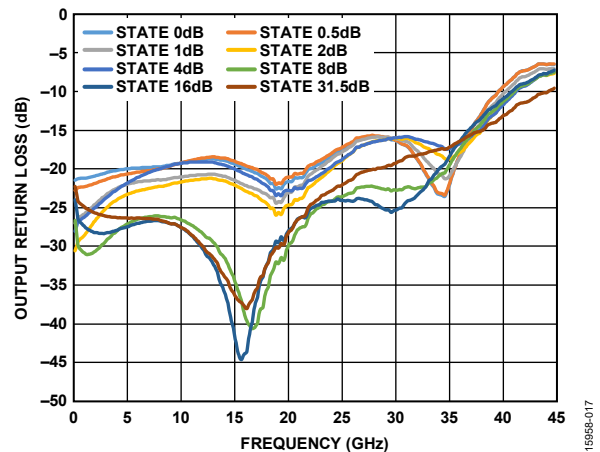


Figure 17. Output Return Loss vs. Frequency (Major States Only) Without Impedance Match

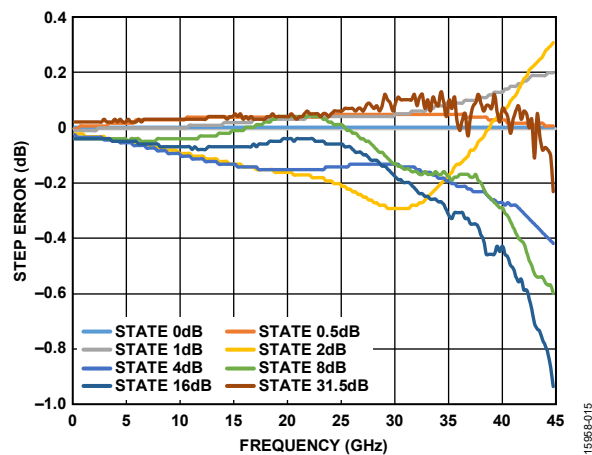


Figure 15. Step Error vs. Frequency (Major States Only) with Impedance Match

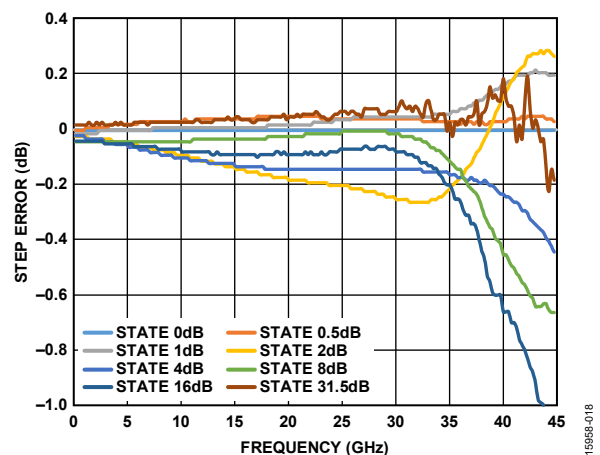


Figure 18. Step Error vs. Frequency (Major States Only) Without Impedance Match

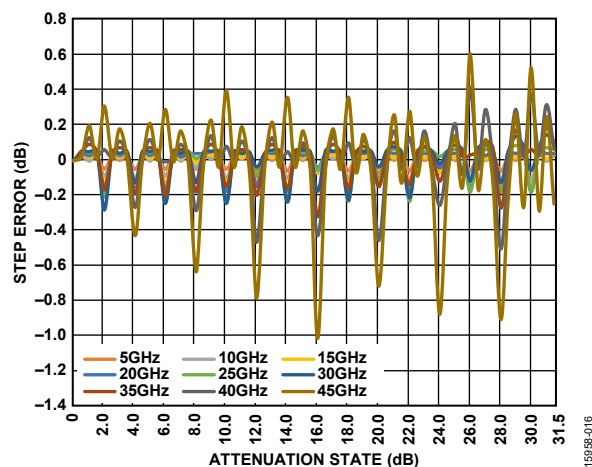


Figure 16. Step Error vs. Attenuation State over Frequency with Impedance Match

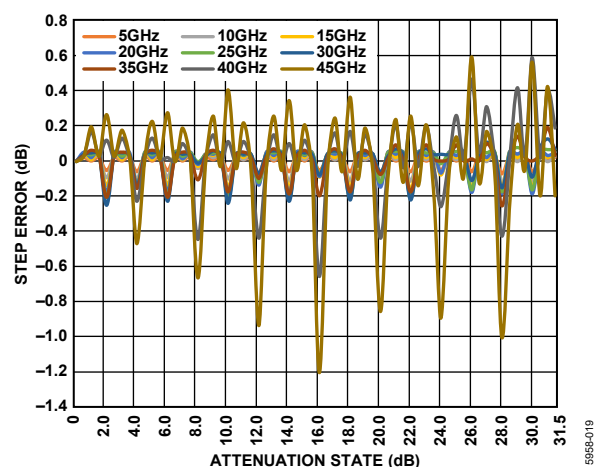


Figure 19. Step Error vs. Attenuation State over Frequency Without Impedance Match

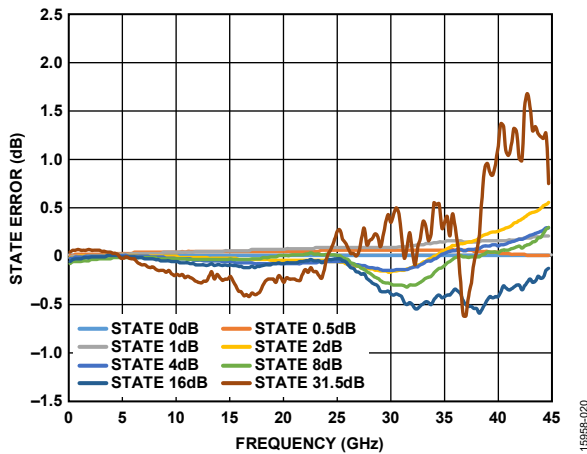


Figure 20. State Error vs. Frequency (Major States Only) with Impedance Match

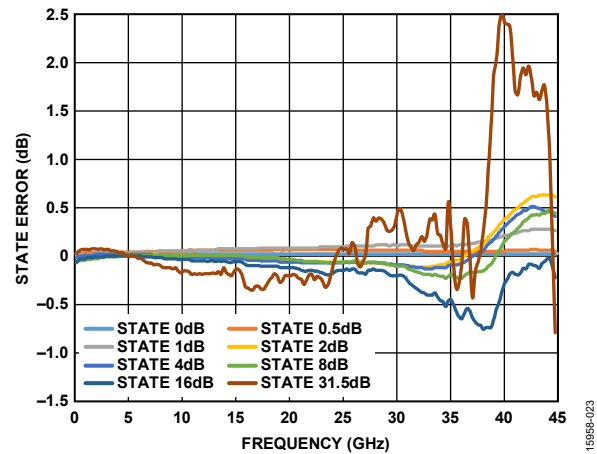


Figure 23. State Error vs. Frequency (Major States Only) Without Impedance Match

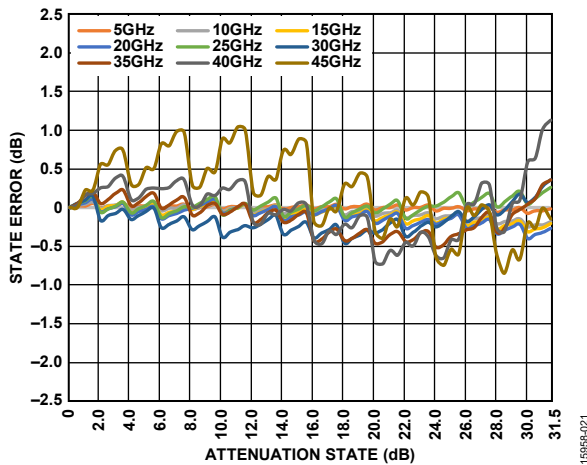


Figure 21. State Error vs. Attenuation State over Frequency with Impedance Match

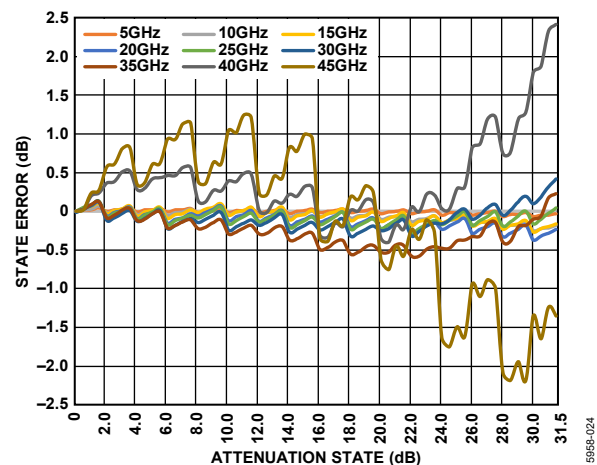


Figure 24. State Error vs. Attenuation State over Frequency Without Impedance Match

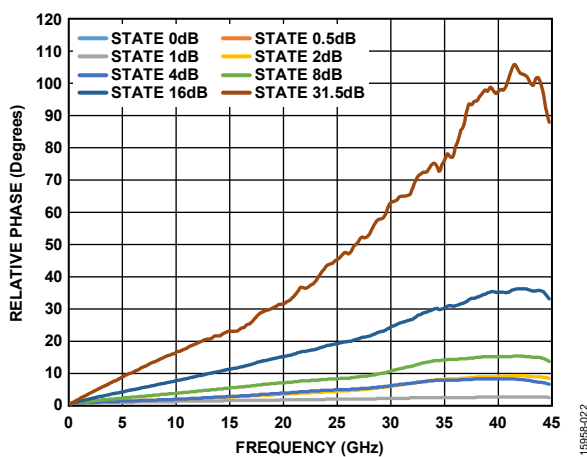


Figure 22. Relative Phase vs. Frequency (Major States Only) with Impedance Match

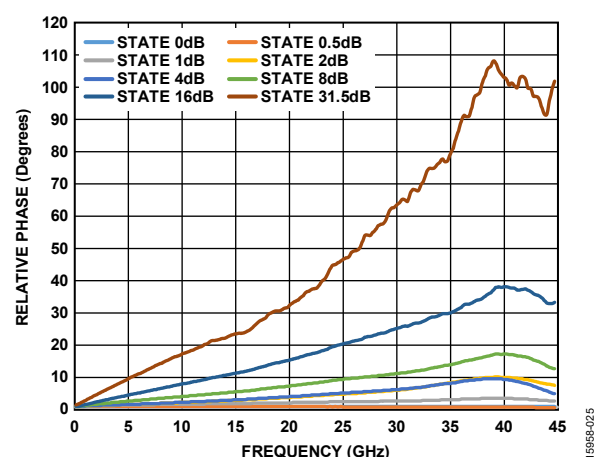


Figure 25. Relative Phase vs. Frequency (Major States Only) Without Impedance Match

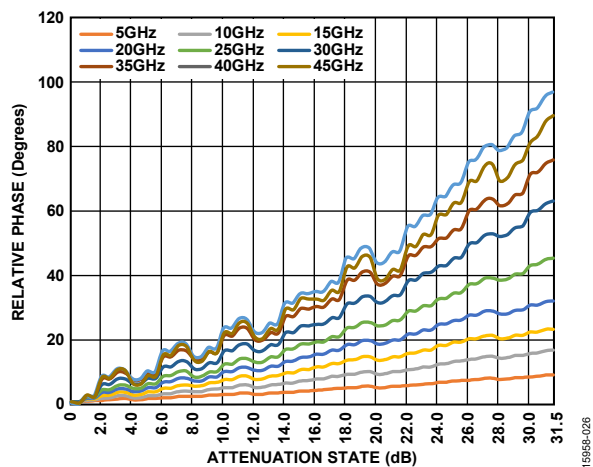


Figure 26. Relative Phase vs. Attenuation State over Frequency with Impedance Match

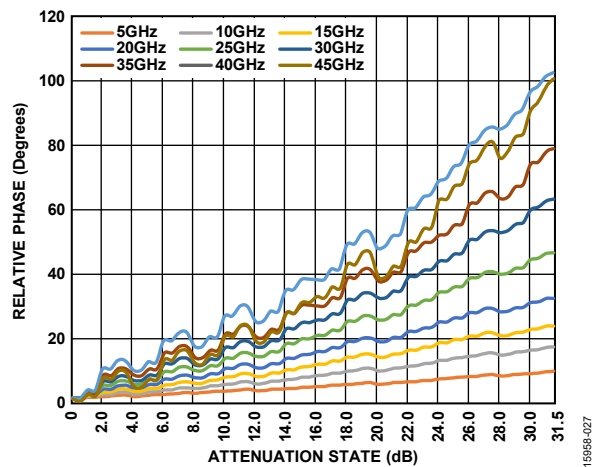


Figure 27. Relative Phase vs. Attenuation State over Frequency Without Impedance Match

INPUT POWER COMPRESSION AND THIRD-ORDER INTERCEPT

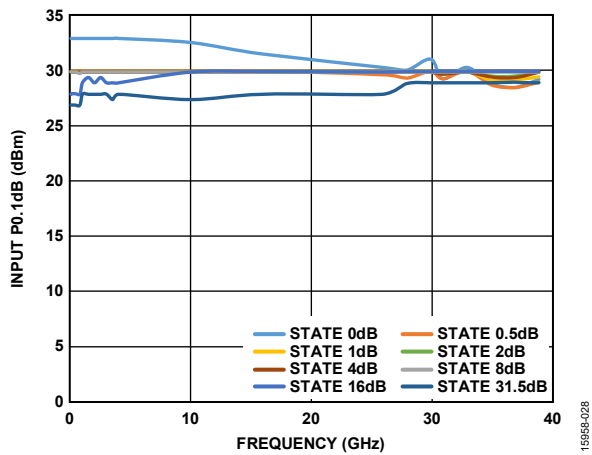


Figure 28. Input P0.1dB vs. Frequency (Major States Only)

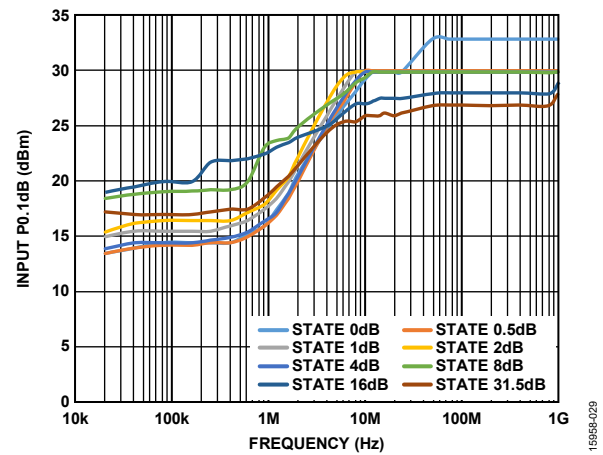


Figure 30. Input P0.1dB vs. Frequency (Major States Only), Low Frequency Detail

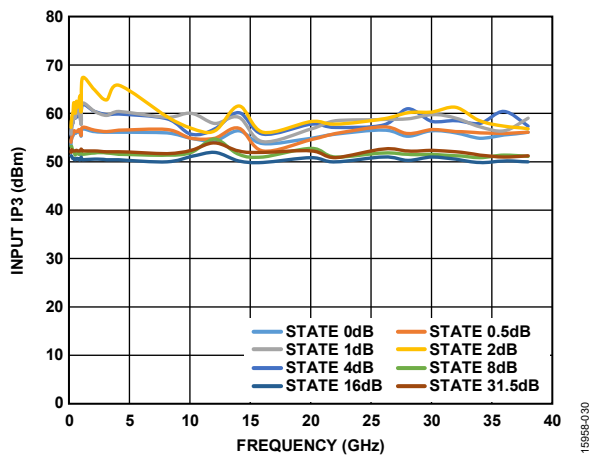


Figure 29. Input IP3 vs. Frequency (Major States Only)

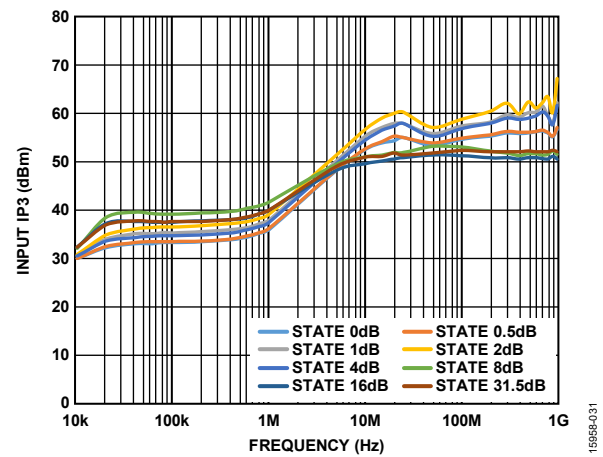


Figure 31. Input IP3 vs. Frequency (Major States Only), Low Frequency Detail

THEORY OF OPERATION

The ADRF5730 incorporates a 6-bit fixed attenuator array that offers an attenuation range of 31.5 dB in 0.5 dB steps. An integrated driver provides both serial and parallel mode control of the attenuator array (see Figure 32).

Note that when referring to a single function of a multifunction pin in this section, only the portion of the pin name that is relevant is mentioned. For full pin names of the multifunction pins, refer to the Pin Configuration and Function Descriptions section.

POWER SUPPLY

Bypassing capacitors are recommended on the positive supply voltage line (VDD) and negative supply line (VSS) to filter high frequency noise.

The power-up sequence is as follows:

1. Connect GND.
2. Power up the VDD and VSS voltages. Power up VSS after VDD to avoid current transients on VDD during ramp-up.
3. Power up the digital control inputs. The order of the digital control inputs is not important. However, powering the digital control inputs before the VDD voltage supply may inadvertently forward bias and damage the internal ESD structures. To avoid this damage, use a series 1 k Ω resistor to limit the current flowing in to the control pin. Use pull-up or pull-down resistors if the controller output is in a

high impedance state after the VDD voltage is powered up and the control pins are not driven to a valid logic state.

4. Apply an RF input signal to ATTIN or ATTOUT.

The power-down sequence is the reverse order of the power-up sequence.

Power-Up State

The ADRF5730 has internal power-on reset circuitry. This circuitry sets the attenuator to the maximum attenuation state (31.5 dB) when the VDD and VSS voltages are applied and LE is set to low.

RF INPUT AND OUTPUT

Both RF ports (ATTIN and ATTOUT) are dc-coupled to 0 V. No dc blocking is required at the RF ports when the RF line potential is equal to 0 V.

The RF ports are internally matched to 50 Ω . Therefore, external matching components are not required. For wideband applications, use impedance matching to improve insertion loss, return loss, and attenuation accuracy performance at high frequencies. See the Impedance Matching section.

The ADRF5730 supports bidirectional operation at a lower power level. The power handling of the ATTIN and ATTOUT ports are different. Therefore, the bidirectional power handling is defined by the ATTOUT port. Refer to the RF input power specifications in Table 1.

Table 6. Truth Table

Digital Control Input ¹						Attenuation State (dB)
D5	D4	D3	D2	D1	D0	
Low	Low	Low	Low	Low	Low	0 (reference)
Low	Low	Low	Low	Low	High	0.5
Low	Low	Low	Low	High	Low	1.0
Low	Low	Low	High	Low	Low	2.0
Low	Low	High	Low	Low	Low	4.0
Low	High	Low	Low	Low	Low	8.0
High	Low	Low	Low	Low	Low	16.0
High	High	High	High	High	High	31.5

¹ Any combination of the control voltage input states shown in Table 6 provides an attenuation equal to the sum of the bits selected.

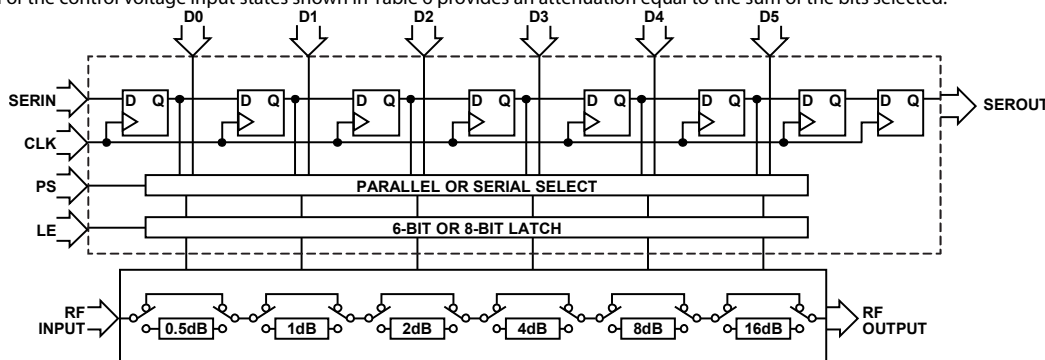


Figure 32. Simplified Circuit Diagram

SERIAL OR PARALLEL MODE SELECTION

The ADRF5730 can be controlled in either serial or parallel mode by setting the PS pin to high or low, respectively (see Table 7).

Table 7. Mode Selection

PS	Control Mode
Low	Parallel
High	Serial

SERIAL MODE INTERFACE

The ADRF5730 supports a 3-wire SPI: serial data input (SERIN), clock (CLK), and latch enable (LE). The serial control interface is activated when PS is set to high.

The ADRF5730 attenuation states can be controlled using 6-bit or 8-bit SERIN data. If an 8-bit word is used to control the state of the attenuator, the first two bits, D7 and D6, are don't care bits. It does not matter if these two bits are held low or high, or if they are omitted altogether. Only Bits[D0:D5] set the state of the attenuator.

In serial mode, the SERIN data is clocked most significant bit (MSB) first on the rising CLK edges into the shift register. Then, LE must be toggled high to latch the new attenuation state into the device. LE must be set to low to clock new SERIN data into the shift register as CLK is masked to prevent the attenuator value from changing if LE is kept high. See Figure 34 in conjunction with Table 2 and Table 6.

Using SEROUT

The ADRF5730 also features a serial data output, SEROUT. SEROUT outputs the serial input data at the 8th clock cycle, and can control a cascaded attenuator using a single SPI bus. Figure 35 shows the serial out timing diagram.

When using the attenuator in a daisy-chain operation, 8-bit SERIN data must be used due to the 8 clock cycle delay between SERIN and SEROUT.

It is optional to use a 1 kΩ resistor between SEROUT on the first attenuator and SERIN of the next attenuator to filter the signal (see Figure 33).

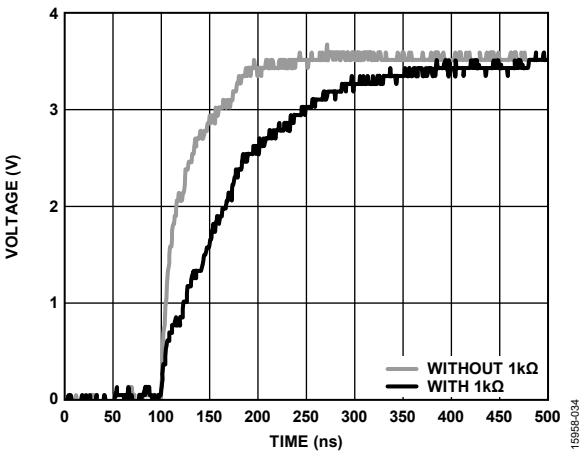


Figure 33. Using a Resistor on SEROUT

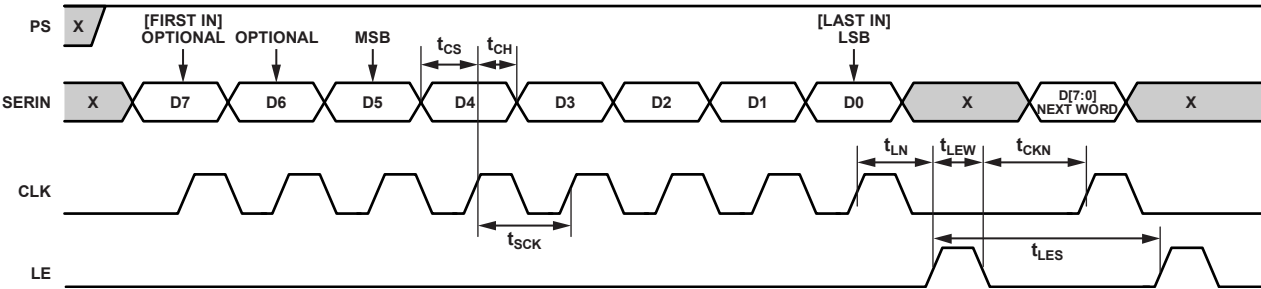


Figure 34. Serial Control Timing Diagram

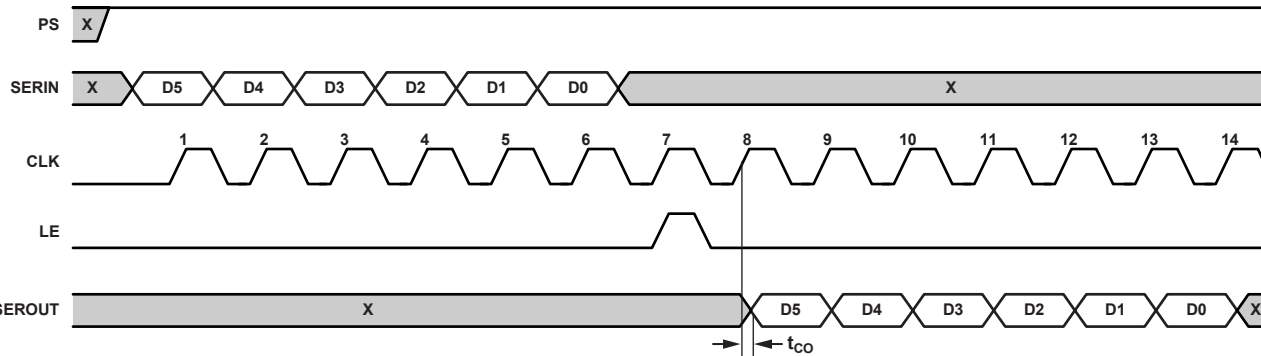


Figure 35. Serial Output Timing Diagram

PARALLEL MODE INTERFACE

The ADRF5730 has six digital control inputs, D0 (LSB) to D5 (MSB), to select the desired attenuation state in parallel mode, as shown in Table 6. The parallel control interface is activated when PS is set to low.

There are two modes of parallel operation: direct parallel and latched parallel.

Direct Parallel Mode

To enable direct parallel mode, the LE pin must be kept high. The attenuation state is changed by the control voltage inputs (D0 to D5) directly. This mode is ideal for manual control of the attenuator.

Latched Parallel Mode

To enable latched parallel mode, the LE pin must be kept low when changing the control voltage inputs (D0 to D5) to set the attenuation state. When the desired state is set, LE must be toggled high to transfer the 6-bit data to the bypass switches of the attenuator array, and then toggled low to latch the change into the device until the next desired attenuation change (see Figure 36 in conjunction with Table 2).

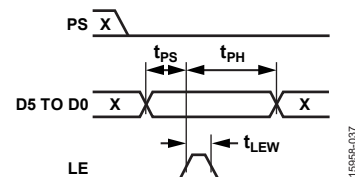


Figure 36. Latched Parallel Mode Timing Diagram

APPLICATIONS INFORMATION

EVALUATION BOARD

The [ADRF5730-EVALZ](#) is a 4-layer evaluation board. The top and bottom copper layer are 0.5 oz (0.7 mil) plated to 1.5 oz (2.2 mil) and are separated by dielectric materials. The stackup for this evaluation board is shown in Figure 37.

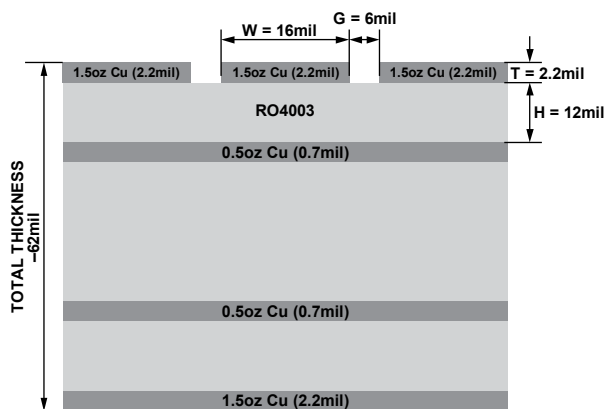


Figure 37. Evaluation Board Stackup

All RF and dc traces are routed on the top copper layer, whereas the inner and bottom layers are grounded planes that provide a solid ground for the RF transmission lines. The top dielectric material is 12 mil Rogers RO4003, offering optimal high frequency performance. The middle and bottom dielectric materials provide mechanical strength. The overall board thickness is 62 mil, which allows 2.4 mm RF launchers to be connected at the board edges.

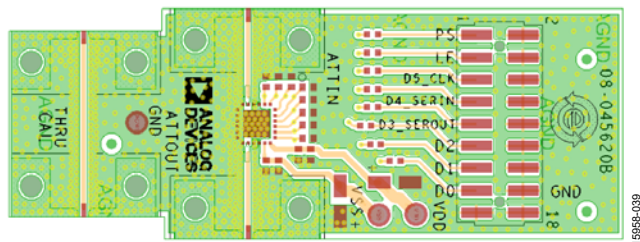


Figure 38. Evaluation Board, Top View

The RF transmission lines are designed using a coplanar waveguide (CPWG) model, with a trace width of 16 mil and ground clearance of 6 mil to have a characteristic impedance of 50 Ω . For optimal RF and thermal grounding, as many through vias as possible are arranged around transmission lines and under the exposed pad of the package.

The [ADRF5730-EVALZ](#) does not have high frequency impedance matching implemented on the RF transmission lines. For more details on the impedance matched circuit, refer to the Impedance Matching portion of the Probe Matrix Board section.

Thru calibration can be used to calibrate out the board loss effects from the [ADRF5730-EVALZ](#) evaluation board measurements to determine the device performance at the pins of the IC. Figure 39 shows the typical board loss for the [ADRF5730-EVALZ](#) evaluation board at room temperature, the embedded insertion loss, and the de-embedded insertion loss for the ADRF5730.

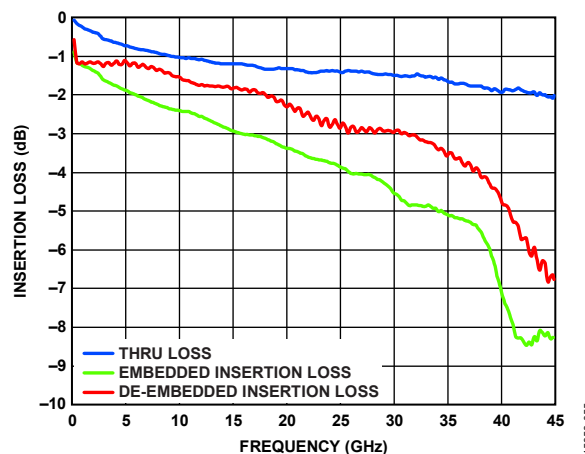


Figure 39. Insertion Loss vs. Frequency

Figure 38 shows the actual ADRF5730 evaluation board with component placement.

Two power supply ports are connected to the VDD and VSS test points, TP1 and TP2, and the ground reference is connected to the GND test point, TP4. On the supply traces, VDD and VSS, a 100 pF bypass capacitor is used to filter high frequency noise. Additionally, unpopulated components positions are available for applying extra bypass capacitors.

All the digital control pins are connected through digital signal traces to the 2 $\times$ 9-pin header, P1. There are provisions for a resistor capacitor (RC) filter that helps eliminate dc-coupled noise. The ADRF5730 was evaluated without an external RC filter, the series resistors are 0 Ω , and shunt capacitors are unpopulated on the evaluation board.

The RF input and output ports (ATTIN and ATTOUT) are connected through 50 Ω transmission lines to the 2.4 mm RF launchers, J1 and J2, respectively. These high frequency RF launchers are connected by contact and are not soldered onto the board.

A thru calibration line connects the unpopulated J3 and J4 launchers. This transmission line is used to estimate the loss of the PCB over the environmental conditions being evaluated.

The schematic of the [ADRF5730-EVALZ](#) evaluation board is shown in Figure 40.

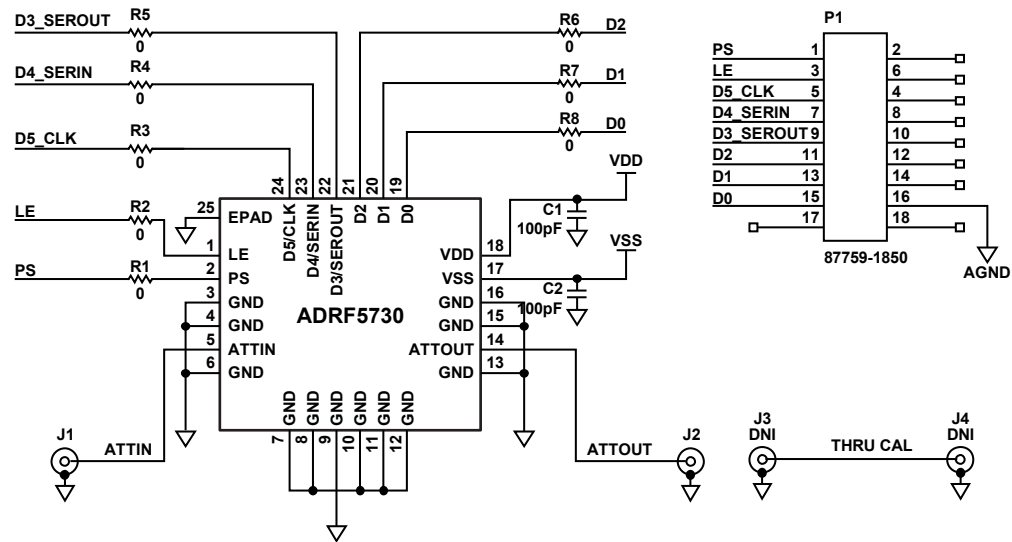


Figure 40. Evaluation Board Schematic

15959-042

Table 8. Evaluation Board Components

Component	Default Value	Description
C1, C2	100 pF	Capacitor, C0402 package
J1 to J4	Not applicable	2.4 mm end launch connector (Southwest Microwave: 1492-04A-5)
P1	Not applicable	2 × 9-pin header
R1 to R11	0 Ω	Resistor, 0402 package
TP1, TP2, TP4	Not applicable	Through-hole mount test point
U1	ADRF5730	ADRF5730 digital attenuator, Analog Devices, Inc.

PROBE MATRIX BOARD

The probe matrix board is a 4-layer board. Similar to the evaluation board, the probe matrix board also uses a 12 mil Rogers RO4003 dielectric. The top and bottom copper layers are 0.5 oz (0.7 mil) plated to 1.5 oz (2.2 mil). The RF transmission lines are designed using a CPWG model with a width of 16 mil and ground spacing of 6 mil to have a characteristic impedance of 50 Ω .

Figure 41 and Figure 42 show the cross sectional view and the top view of the board, respectively. Measurements are made using GSG probes at close proximity to the RF pins. Unlike the evaluation board, probing reduces reflections caused by mismatch arising from connectors, cables, and board layout, resulting in a more accurate measurement of the device performance.



Figure 41. Probe Matrix Board Stackup

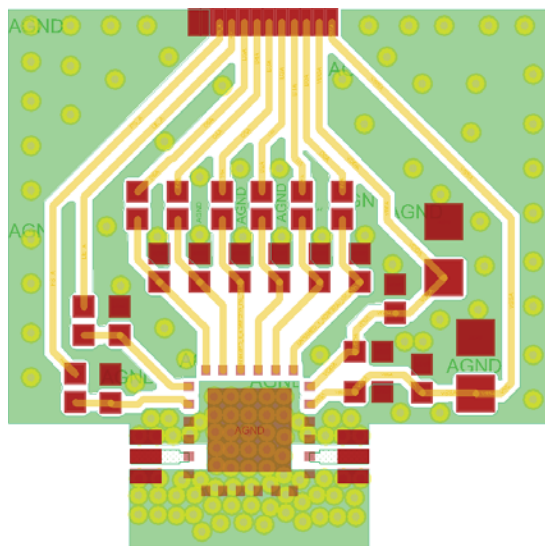


Figure 42. Probe Matrix Board Top View

The probe matrix board includes a thru reflect line (TRL) calibration kit, allowing board loss de-embedding. The actual board duplicates the same layout in matrix form to assemble multiple devices at one time. All S-parameters were measured on this board.

Impedance Matching

Impedance matching at the RF pins can improve insertion loss, return loss, and attenuation accuracy at high frequencies. Figure 43 and Figure 44 show the difference in the transmission lines at the ATTIN and ATTOUT pins.

The dimensions of the 50 Ω lines are 16 mil trace width and 6 mil gap. To implement this impedance matched circuit, the pad length is extended by 5 mil (from 17 mil to 22 mil). The calibration reference kit does not include the 5 mil matching line and, therefore, the measured insertion loss includes the losses of the matching circuit.

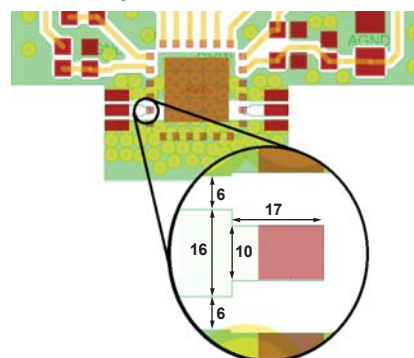


Figure 43. Without Impedance Match

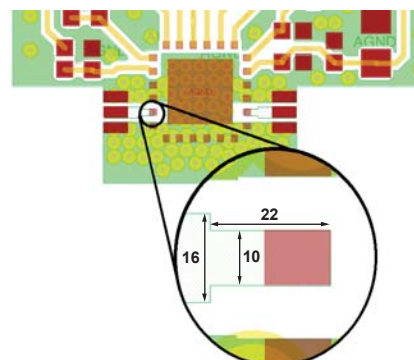


Figure 44. With Impedance Match

OUTLINE DIMENSIONS

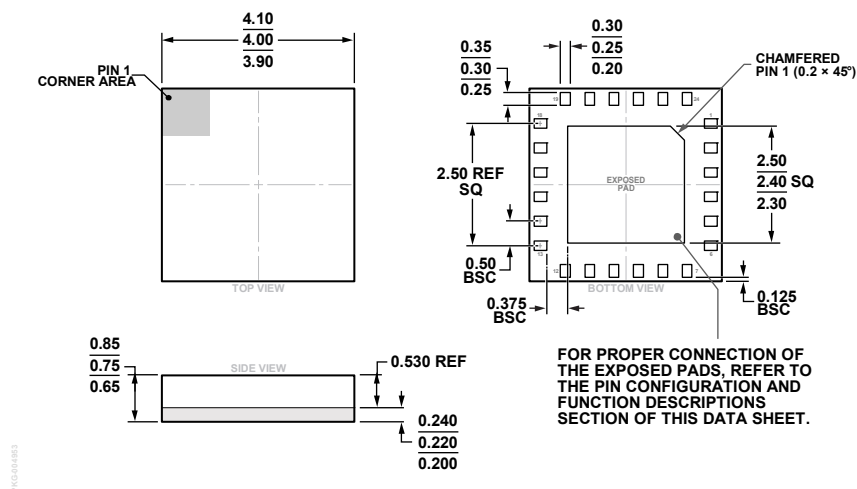


Figure 45. 24-Terminal Land Grid Array [LGA]
4 mm × 4 mm Body and 0.75 mm Package Height
(CC-24-5)
Dimensions shown in millimeters

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option
ADRF5730BCCZN	−40°C to +105°C	24-Terminal Land Grid Array [LGA]	CC-24-5
ADRF5730BCCZN-R7	−40°C to +105°C	24-Terminal Land Grid Array [LGA]	CC-24-5
ADRF5730-EVALZ		Evaluation Board	

¹ Z = RoHS Compliant Part.