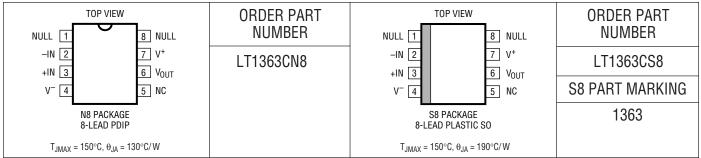
ABSOLUTE MAXIMUM RATINGS (Note 1)

Total Supply Voltage (V ⁺ to V ⁻)	36V
Differential Input Voltage	
(Transient Only) (Note 2)	±10V
Input Voltage	±Vs
Output Short-Circuit Duration (Note 3)	Indefinite

Operating Temperature Range (Note 8) – 40°C to 85°C
Specified Temperature Range (Note 9) – 40°C to 85°C
Maximum Junction Temperature (See Below)
Plastic Package150°C
Storage Temperature Range–65°C to 150°C
Lead Temperature (Soldering, 10 sec)

PACKAGE/ORDER INFORMATION



Consult factory for Industrial and Military grade parts.

ELECTRICAL CHARACTERISTICS $T_A = 25^{\circ}C$, $V_{CM} = 0V$ unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	V _{SUPPLY}	MIN	ТҮР	MAX	UNITS
V _{OS}	Input Offset Voltage	(Note 4)	±15V		0.5	1.5	mV
			±5V		0.5	1.5	mV
			±2.5V		0.7	1.8	mV
l _{os}	Input Offset Current		±2.5V to ±15V		120	350	nA
IB	Input Bias Current		±2.5V to ±15V		0.6	2.0	μΑ
e _n	Input Noise Voltage	f = 10kHz	±2.5V to ±15V		9		nV/√Hz
i _n	Input Noise Current	f = 10kHz	±2.5V to ±15V		1		pA/√Hz
R _{IN}	Input Resistance	$V_{CM} = \pm 12V$	±15V	12	50		MΩ
	Input Resistance	Differential	±15V		5		MΩ
CIN	Input Capacitance		±15V		3		pF
	Input Voltage Range+		±15V	12.0	13.4		V
			±5V	2.5	3.4		V
			±2.5V	0.5	1.1		V
	Input Voltage Range ⁻		±15V		-13.2	-12.0	V
			±5V		-3.2	-2.5	V
			±2.5V		-0.9	-0.5	V
CMRR	Common Mode Rejection Ratio	$V_{CM} = \pm 12V$	±15V	84	90		dB
		$V_{CM} = \pm 2.5 V$	±5V	76	81		dB
		$V_{CM} = \pm 0.5 V$	±2.5V	66	71		dB
PSRR	Power Supply Rejection Ratio	V _S = ±2.5V to ±15V		90	100		dB
A _{VOL}	Large-Signal Voltage Gain	$V_{OUT} = \pm 12V, R_L = 1k$	±15V	4.5	9.0		V/mV
		$V_{OUT} = \pm 10V, R_L = 500\Omega$	±15V	3.0	6.5		V/mV
		$V_{0UT} = \pm 7.5 V, R_{L} = 150 \Omega$	±15V	2.0	3.8		V/mV
		$V_{OUT} = \pm 2.5 V, R_L = 500 \Omega$	±5V	3.0	6.4		V/mV
		$V_{OUT} = \pm 2.5 V, R_{L} = 150 \Omega$	±5V	2.0	5.6		V/mV
		$V_{OUT} = \pm 1V, R_L = 500\Omega$	±2.5V	2.5	5.2		V/mV



ELECTRICAL CHARACTERISTICS $T_A = 25^{\circ}C$, $V_{CM} = 0V$ unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	VSUPPLY	MIN TYP MAX	UNITS
V _{OUT}	Output Swing	$ \begin{array}{l} {\sf R}_L = 1k, {\sf V}_{{\sf I}{\sf N}} = \pm 40m{\sf V} \\ {\sf R}_L = 500\Omega, {\sf V}_{{\sf I}{\sf N}} = \pm 40m{\sf V} \\ {\sf R}_L = 500\Omega, {\sf V}_{{\sf I}{\sf N}} = \pm 40m{\sf V} \\ {\sf R}_L = 150\Omega, {\sf V}_{{\sf I}{\sf N}} = \pm 40m{\sf V} \\ {\sf R}_L = 500\Omega, {\sf V}_{{\sf I}{\sf N}} = \pm 40m{\sf V} \end{array} $	±15V ±15V ±5V ±5V ±2.5V	13.5 14.0 13.0 13.7 3.5 4.1 3.4 3.8 1.3 1.7	V± V± V tV tV tV
I _{OUT}	Output Current	$V_{OUT} = \pm 7.5V$ $V_{OUT} = \pm 3.4V$	±15V ±5V	50 60 23 29	mA mA
I _{SC}	Short-Circuit Current	$V_{OUT} = 0V, V_{IN} = \pm 3V$	±15V	70 105	mA
SR	Slew Rate	A _V = -2, (Note 5)	±15V ±5V	750 1000 300 450	V/µs V/µs
	Full Power Bandwidth	10V Peak, (Note 6) 3V Peak, (Note 6)	±15V ±5V	15.9 23.9	MHz MHz
GBW	Gain Bandwidth	f = 1MHz	±15V ±5V ±2.5V	70 50 40	MHz MHz MHz
t _r , t _f	Rise Time, Fall Time	A _V = 1, 10%-90%, 0.1V	±15V ±5V	2.6 3.6	ns ns
	Overshoot	A _V = 1, 0.1V	±15V ±5V	36 23	% %
	Propagation Delay	50% V _{IN} to 50% V _{OUT} , 0.1V	±15V ±5V	4.6 5.6	ns ns
ts	Settling Time		±15V ±15V ±5V	50 80 55	ns ns ns
	Differential Gain	f = 3.58MHz, A_V = 2, R_L = 150Ω f = 3.58MHz, A_V = 2, R_L = 1k	±15V ±5V ±15V ±5V	0.03 0.06 0.01 0.01	% % % %
	Differential Phase	f = 3.58MHz, A_V = 2, R_L = 150Ω f = 3.58MHz, A_V = 2, R_L = 1k	±15V ±5V ±15V	0.10 0.04 0.05	Deg Deg Deg
Pa	Output Resistance	A _V = 1, f = 1MHz	±5V ±15V	0.25	Deg Ω
$\frac{R_0}{I_S}$	Supply Current		±15V ±15V	6.3 7.5	
18			±15V ±5V	6.0 7.2	mA

The \bullet denotes the specifications which apply over the temperature range $0^{\circ}C \leq T_A \leq 70^{\circ}C$, $V_{CM} = 0V$ unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	V _{SUPPLY}		MIN	ТҮР	MAX	UNITS
V _{OS}	Input Offset Voltage	(Note 4)	±15V				2.0	mV
			±5V				2.0	mV
			±2.5V				2.2	mV
	Input V _{OS} Drift	(Note 7)	±2.5V to ±15V			10	13	μV/°C
l _{os}	Input Offset Current		±2.5V to ±15V	٠			500	nA
Ι _Β	Input Bias Current		±2.5V to ±15V	٠			3	μΑ
CMRR	Common Mode Rejection Ratio	$V_{CM} = \pm 12V$	±15V		82			dB
		$V_{CM} = \pm 2.5 V$	±5V		74			dB
		$V_{CM} = \pm 0.5 V$	±2.5V		64			dB



ELECTRICAL CHARACTERISTICS $0^{\circ}C \le T_A \le 70^{\circ}C$, $V_{CM} = 0V$ unless otherwise noted.

The \bullet denotes the specifications which apply over the temperature range

SYMBOL	PARAMETER	CONDITIONS	VSUPPLY		MIN	ТҮР	MAX	UNITS
PSRR	Power Supply Rejection Ratio	V _S = ±2.5V to ±15V			88			dB
A _{VOL}	Large-Signal Voltage Gain	$\begin{array}{l} V_{0UT}=\pm 12V,R_{L}=1k\\ V_{0UT}=\pm 10V,R_{L}=500\Omega\\ V_{0UT}=\pm 2.5V,R_{L}=500\Omega\\ V_{0UT}=\pm 2.5V,R_{L}=150\Omega\\ V_{0UT}=\pm 1V,R_{L}=500\Omega \end{array}$	±15V ±15V ±5V ±5V ±2.5V	• • •	3.6 2.4 2.4 1.5 2.0			V/mV V/mV V/mV V/mV V/mV
V _{OUT}	Output Swing	$ \begin{array}{c} R_L = 1k, V_{IN} = \pm 40mV \\ R_L = 500\Omega, V_{IN} = \pm 40mV \\ R_L = 500\Omega, V_{IN} = \pm 40mV \\ R_L = 150\Omega, V_{IN} = \pm 40mV \\ R_L = 500\Omega, V_{IN} = \pm 40mV \end{array} $	±15V ±15V ±5V ±5V ±2.5V	• • •	13.4 12.8 3.4 3.3 1.2			±V ±V ±V ±V ±V
I _{OUT}	Output Current	$V_{OUT} = \pm 12.8V$ $V_{OUT} = \pm 3.3V$	±15V ±5V	•	25 22			mA mA
I _{SC}	Short-Circuit Current	$V_{OUT} = 0V, V_{IN} = \pm 3V$	±15V	•	55			mA
SR	Slew Rate	$A_V = -2$, (Note 5)	±15V ±5V	•	600 225			V/µs V/µs
Is	Supply Current		±15V ±5V	•			8.7 8.4	mA mA

The \bullet denotes the specifications which apply over the temperature range $-40^{\circ}C \le T_A \le 85^{\circ}C$, $V_{CM} = 0V$ unless otherwise noted. (Note 9)

SYMBOL	PARAMETER	CONDITIONS	VSUPPLY		MIN	ТҮР	MAX	UNITS
V _{OS}	Input Offset Voltage	(Note 4)	±15V	•			2.5	mV
			±5V	•			2.5	mV
			±2.5V				2.7	mV
	Input V _{OS} Drift	(Note 7)	±2.5V to ±15V	٠		10	13	μV/°C
l _{os}	Input Offset Current		±2.5V to ±15V	٠			600	nA
IB	Input Bias Current		±2.5V to ±15V				3.6	μA
CMRR	Common Mode Rejection Ratio	$V_{CM} = \pm 12V$	±15V		82			dB
		$V_{CM} = \pm 2.5 V$	±5V		74			dB
		$V_{CM} = \pm 0.5 V$	±2.5V		64			dB
PSRR	Power Supply Rejection Ratio	V _S = ±2.5V to ±15V			87			dB
A _{VOL}	Large-Signal Voltage Gain	$V_{OUT} = \pm 12V, R_L = 1k$	±15V	٠	2.5			V/mV
		$V_{OUT} = \pm 10V, R_L = 500\Omega$	±15V		1.5			V/mV
		$V_{0UT} = \pm 2.5 V, R_{L} = 500 \Omega$	±5V		1.5			V/mV
		$V_{OUT} = \pm 2.5 V, R_L = 150 \Omega$	±5V		1.0			V/mV
		$V_{OUT} = \pm 1 V, R_L = 500 \Omega$	±2.5V	٠	1.3			V/mV
V _{OUT}	Output Swing	$R_L = 1k\Omega$, $V_{IN} = \pm 40mV$	±15V		13.4			±V
		$R_L = 500\Omega$, $V_{IN} = \pm 40 mV$	±15V		12.7			±V
		$R_L = 500\Omega, V_{IN} = \pm 40 mV$	±5V		3.4			±V
		$R_L = 150\Omega$, $V_{IN} = \pm 40mV$	±5V		3.2			±V
		$R_L = 500\Omega, V_{IN} = \pm 40 mV$	±2.5V	•	1.2			±V
I _{OUT}	Output Current	$V_{OUT} = \pm 12.7 V$	±15V		25			mA
		$V_{OUT} = \pm 3.2 V$	±5V		21			mA
I _{SC}	Short-Circuit Current	$V_{OUT} = 0V, V_{IN} = \pm 3V$	±15V		50			mA
SR	Slew Rate	A _V = -2, (Note 5)	±15V		550			V/µs
			±5V		180			V/µs
I _S	Supply Current		±15V				9.0	mA
			±5V				8.7	mA



ELECTRICAL CHARACTERISTICS

Note 1: Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

Note 2: Differential inputs of ±10V are appropriate for transient operation only, such as during slewing. Large, sustained differential inputs will cause excessive power dissipation and may damage the part. See Input Considerations in the Applications Information section of this data sheet for more details.

Note 3: A heat sink may be required to keep the junction temperature below absolute maximum when the output is shorted indefinitely.

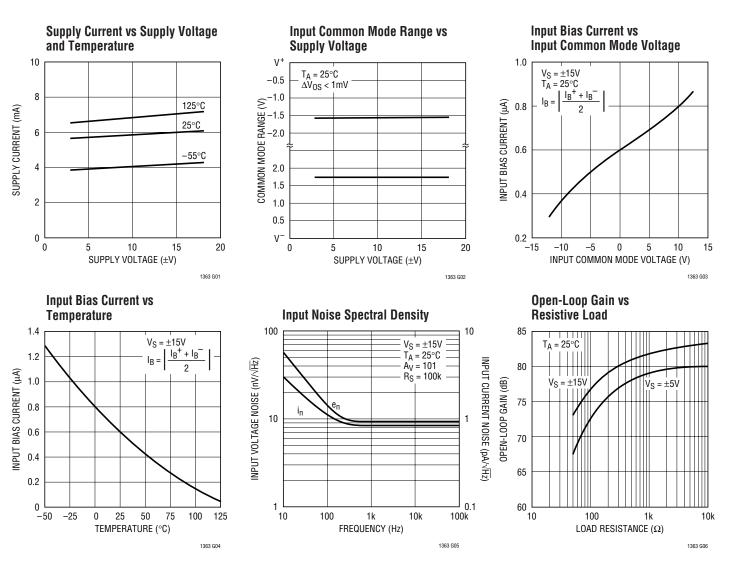
Note 4: Input offset voltage is pulse tested and is exclusive of warm-up drift. **Note 5:** Slew rate is measured between $\pm 10V$ on the output with $\pm 6V$ input for $\pm 15V$ supplies and $\pm 2V$ on the output with $\pm 1.75V$ input for $\pm 5V$ supplies. **Note 6:** Full power bandwidth is calculated from the slew rate measurement: FPBW = $SR/2\pi V_P$.

Note 7: This parameter is not 100% tested.

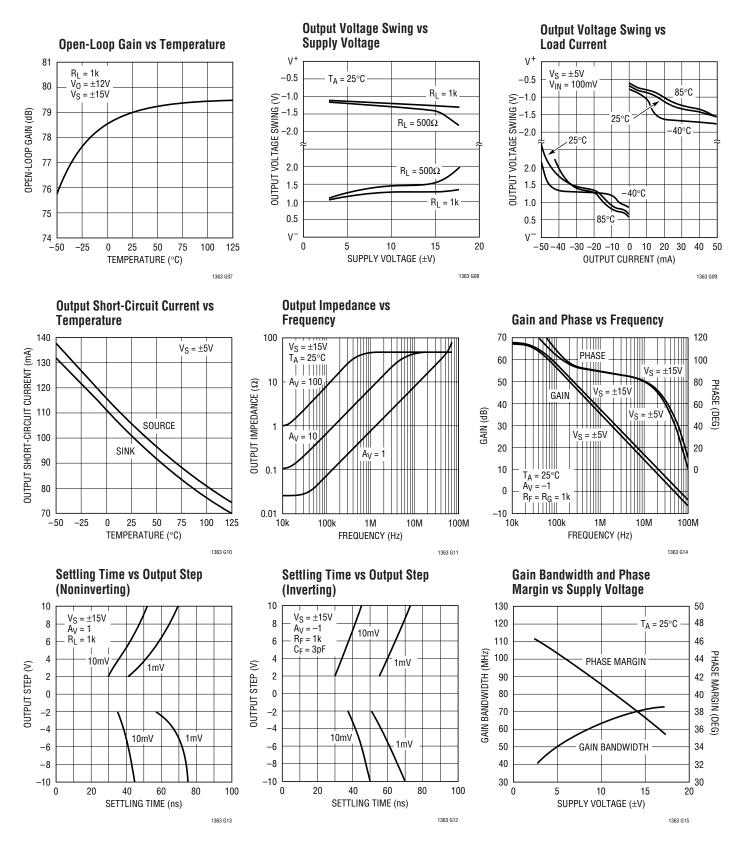
Note 8: The LT1363C is guaranteed functional over the operating temperature range of -40° C to 85° C.

Note 9: The LT1363C is guaranteed to meet specified performance from 0°C to 70°C. The LT1363C is designed, characterized and expected to meet specified performance from -40°C to 85°C, but is not tested or QA sampled at these temperatures. For guaranteed I-grade parts, consult the factory.

TYPICAL PERFORMANCE CHARACTERISTICS

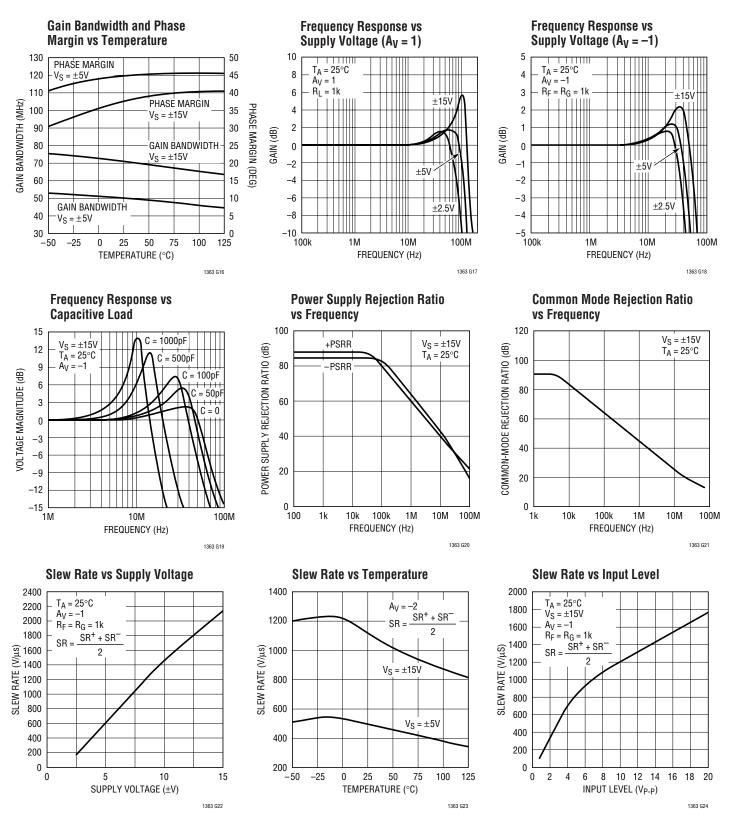






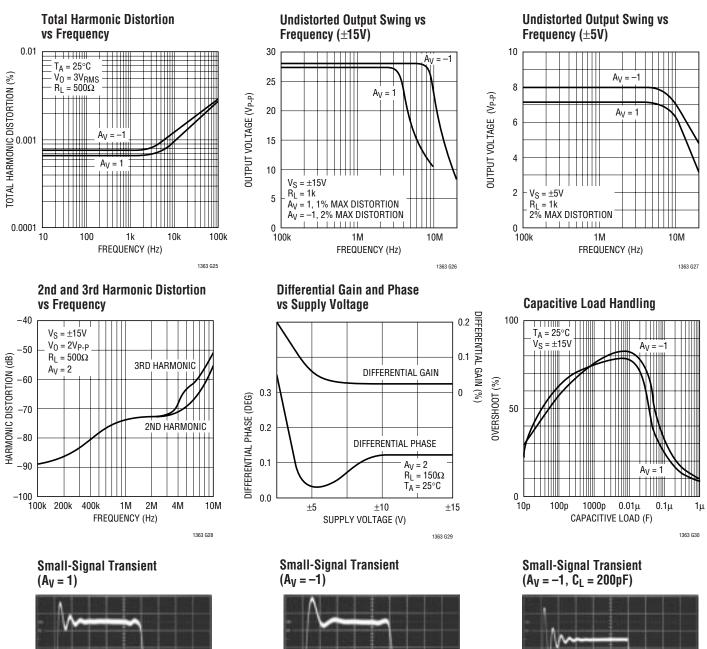


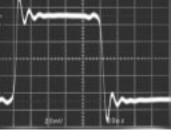
6 Downloaded from Arrow.com.



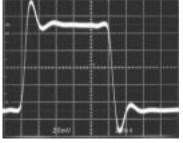


7



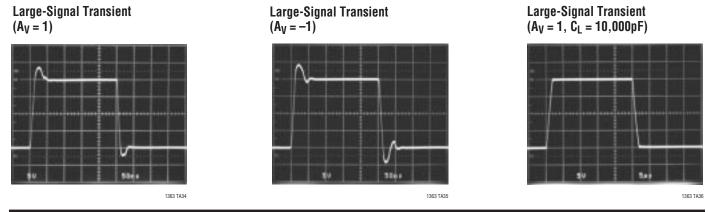


1363 TA31



1363 TA32

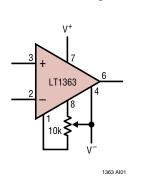
1363 TA33



APPLICATIONS INFORMATION

The LT1363 may be inserted directly into AD817, AD847, EL2020, EL2044, and LM6361 applications improving both DC and AC performance, provided that the nulling circuitry is removed. The suggested nulling circuit for the LT1363 is shown below.

Offset Nulling



Layout and Passive Components

The LT1363 amplifier is easy to apply and tolerant of less than ideal layouts. For maximum performance (for example fast settling time) use a ground plane, short lead lengths, and RF-quality bypass capacitors (0.01μ F to 0.1μ F). For high drive current applications use low ESR bypass capacitors (1μ F to 10μ F tantalum). Sockets should be avoided when maximum frequency performance is required, although low profile sockets can provide reasonable performance up to 50MHz. For more details see Design Note 50.

The parallel combination of the feedback resistor and gain setting resistor on the inverting input can combine with the input capacitance to form a pole which can cause peaking or oscillations. For feedback resistors greater than $5k\Omega$, a parallel capacitor of value

$$C_F > R_G \times C_{IN}/R_F$$

should be used to cancel the input pole and optimize dynamic performance. For unity-gain applications where a large feedback resistor is used, C_F should be greater than or equal to C_{IN} .

Capacitive Loading

The LT1363 is stable with any capacitive load. This is accomplished by sensing the load induced output pole and adding compensation at the amplifier gain node. As the capacitive load increases, both the bandwidth and phase margin decrease so there will be peaking in the frequency domain and in the transient response as shown in the typical performance curves. The photo of the small-signal response with 200pF load shows 62% peaking. The largesignal response with a 10,000pF load shows the output slew rate being limited to 10V/µs by the short-circuit current. Coaxial cable can be driven directly, but for best pulse fidelity a resistor of value equal to the characteristic impedance of the cable (i.e., 75Ω) should be placed in series with the output. The other end of the cable should be terminated with the same value resistor to ground. The response of a cable driver in a gain of 2 driving a 75Ω cable is shown on the front page of the data sheet.



APPLICATIONS INFORMATION

Input Considerations

Each of the LT1363 inputs is the base of an NPN and a PNP transistor whose base currents are of opposite polarity and provide first-order bias current cancellation. Because of variation in the matching of NPN and PNP beta, the polarity of the input bias current can be positive or negative. The offset current does not depend on NPN/PNP beta matching and is well controlled. The use of balanced source resistance at each input is recommended for applications where DC accuracy must be maximized.

The inputs can withstand transient differential input voltages up to 10V without damage and need no clamping or source resistance for protection. Differential inputs, however, generate large supply currents (tens of mA) as required for high slew rates. If the device is used with sustained differential inputs, the average supply current will increase, excessive power dissipation will result and the part may be damaged. The part should not be used as a comparator, peak detector or other open-loop application with large, sustained differential inputs. Under normal, closed-loop operation, an increase of power dissipation is only noticeable in applications with large slewing outputs and is proportional to the magnitude of the differential input voltage and the percent of the time that the inputs are apart. Measure the average supply current for the application in order to calculate the power dissipation.

Single Supply Operation

The LT1363 is specified at $\pm 15V$, $\pm 5V$, and $\pm 2.5V$ supplies, but it is also well suited to single supply operation down to a single 5V supply. The symmetrical input Ccmmon mode range and output swing make the device well suited for applications with a single supply if the the input and output swing ranges are centered (i.e., a DC bias of 2.5V on the input and the output). For 5V video applications with an assymetrical swing, an offset of 2V on the input works best.

Power Dissipation

The LT1363 combines high speed and large output drive in a small package. Because of the wide supply voltage range, it is possible to exceed the maximum junction LT1363CN8: $T_J = T_A + (P_D \times 130^{\circ}C/W)$ LT1363CS8: $T_J = T_A + (P_D \times 190^{\circ}C/W)$

Worst case power dissipation occurs at the maximum supply current and when the output voltage is at 1/2 of either supply voltage (or the maximum swing if less than 1/2 supply voltage). Therefore P_{DMAX} is:

 $P_{DMAX} = (V^+ - V^-)(I_{SMAX}) + (V^+/2)^2/R_L$

Example: LT1363CS8 at 70°C, V_S = $\pm 15V$, R_L = 390 Ω

 $\mathsf{P}_{\mathsf{DMAX}} = (30\mathsf{V})(8.7\mathsf{mA}) + (7.5\mathsf{V})^2/390\Omega = 405\mathsf{mW}$

 $T_{JMAX} = 70^{\circ}C + (405mW)(190^{\circ}C/W) = 147^{\circ}C$

Circuit Operation

The LT1363 circuit topology is a true voltage feedback amplifier that has the slewing behavior of a current feedback amplifier. The operation of the circuit can be understood by referring to the simplified schematic. The inputs are buffered by complementary NPN and PNP emitter followers which drive a 500 Ω resistor. The input voltage appears across the resistor generating currents which are mirrored into the high impedance node. Complementary followers form an output stage which buffers the gain node from the load. The bandwidth is set by the input resistor and the capacitance on the high impedance node. The slew rate is determined by the current available to charge the gain node capacitance. This current is the differential input voltage divided by R1, so the slew rate is proportional to the input. Highest slew rates are therefore seen in the lowest gain configurations. For example, a 10V output step in a gain of 10 has only a 1V input step, whereas the same output step in unity gain has a 10 times greater input step. The curve of Slew Rate vs Input Level illustrates this relationship. The LT1363 is tested for slew rate in a gain of -2 so higher slew rates can be expected in gains of 1 and -1, and lower slew rates in higher gain configurations.

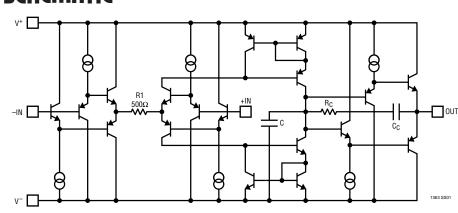


APPLICATIONS INFORMATION

The RC network across the output stage is bootstrapped when the amplifier is driving a light or moderate load and has no effect under normal operation. When driving a capacitive load (or a low value resistive load) the network is incompletely bootstrapped and adds to the compensation at the high impedance node. The added capacitance slows down the amplifier which improves the phase margin by moving the unity-gain frequency away from the pole formed by the output impedance and the capacitive load. The zero created by the RC combination adds phase to ensure that even for very large load capacitances, the total phase lag can never exceed 180 degrees (zero phase margin) and the amplifier remains stable.

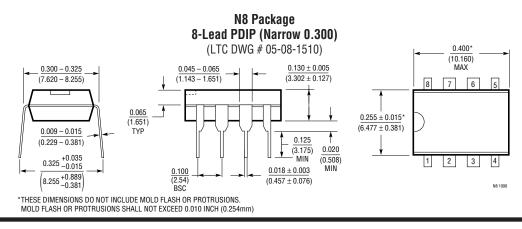
Comparison to Current Feedback Amplifiers

The LT1363 enjoys the high slew rates of Current Feedback Amplifiers (CFAs) while maintaining the characteristics of a true voltage feedback amplifier. The primary differences are that the LT1363 has two high impedance inputs and its closed loop bandwidth decreases as the gain increases. CFAs have a low impedance inverting input and maintain relatively constant bandwidth with increasing gain. The LT1363 can be used in all traditional op amp configurations including integrators and applications such as photodiode amplifiers and I-to-V converters where there may be significant capacitance on the inverting input. The frequency compensation is internal and not dependent on the value of the feedback resistor. For CFAs, the feedback resistance is fixed for a given bandwidth and capacitance on the inverting input can cause peaking or oscillations. The slew rate of the LT1363 in noninverting gain configurations is also superior in most cases.



PACKAGE DESCRIPTION

Dimension in inches (millimeters) unless otherwise noted.



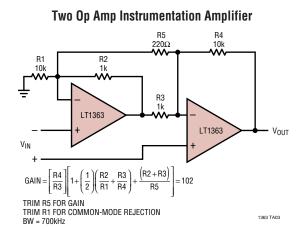
Information furnished by Linear Technology Corporation is believed to be accurate and reliable. However, no responsibility is assumed for its use. Linear Technology Corporation makes no representation that the interconnection of its circuits as described herein will not infringe on existing patent rights.

SIMPLIFIED SCHEMATIC

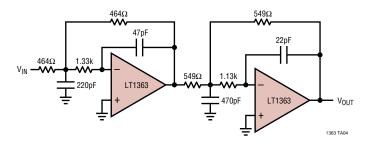


11

TYPICAL APPLICATIONS



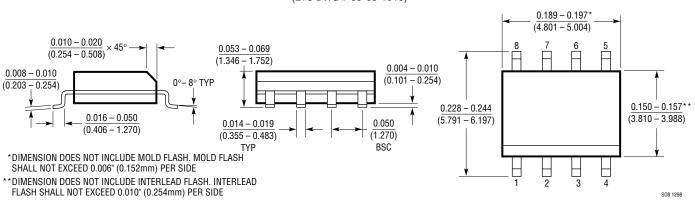
2MHz, 4th Order Butterworth Filter



PACKAGE DESCRIPTION

Dimension in inches (millimeters) unless otherwise noted.





RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LT1364/LT1365	Dual and Quad 70MHz, 1000V/µs Op Amps	Dual and Quad Versions of LT1363
LT1360	50MHz, 800V/µs Op Amp	Lower Power Version of LT1363, V_{OS} = 1mV, I_{S} = 4mA
LT1357	25MHz, 600V/μs Op Amp	Lower Power Version of LT1363, V_{OS} = 0.6mV, I_S = 2mA
LT1812	100MHz, 750V/µs Ор Атр	Low Voltage, Low Power LT1363, V_{OS} = 1.5mV, I_S = 3mA