## **Ordering Information**

Part Number	Mark Code <sup>(1)</sup>	Junction Temperature Range	Package <sup>(2)</sup>	
MIC2860-2PYC6	<u>62</u> P	–40°C to +125°C	6-Pin SC-70	
MIC2860-2PYD6	<u>602</u> P	–40°C to +125°C	6-Pin Thin SOT-23	

### Notes:

- 1. Under bar symbol ( \_ ) may not be to scale.
- 2. Package is GREEN RoHS compliant. Lead finish is NiPdAu. Mold compound is halogen free.

# **Pin Configuration**



# **Pin Description**

Pin Number MIC2860-2P	Pin Name	Pin Function
1	EN	PWM Control Pin. This pin is used as a PWM input for dimming of WLEDs. Do not leave floating.
2	GND	Ground.
3	VIN	Voltage Input. Connect at least 1µF ceramic capacitor between VIN and GND.
4	D2	LED2 driver. Connect LED anode to VIN and cathode to this pin. Do not leave floating.
5	RSET	An internal 1.27V reference sets the nominal maximum WLED current. Example, apply a $9.53k\Omega$ resistor between RSET and GND to set LED current to $30.2mA$ at $100\%$ duty cycle.
6	D1	LED1 driver. Connect LED anode to VIN and cathode to this pin. Do not leave floating.

# Absolute Maximum Ratings<sup>(1)</sup>

Main Input Voltage (V <sub>IN</sub> )	0.3V to +6V
Enable Input Voltage (V <sub>EN</sub> )	
LED Driver Voltage (V <sub>D1, D2</sub> )	
Power Dissipation	
Lead Temperature (soldering, 10sec.)	
Storage Temperature (T <sub>s</sub> )	
ESD Rating	2KV

# Operating Ratings<sup>(2)</sup>

Supply Voltage (V <sub>IN</sub> )	+3.0V to +5.5V
Enable Input Voltage (V <sub>EN</sub> )	0V to V <sub>IN</sub>
LED Driver Voltage (V <sub>D1, D2</sub> )	0V to V <sub>IN</sub>
Junction Temperature (T <sub>J</sub> )	40°C to +125°C
Junction Thermal Resistance	
SC-70 (θ <sub>JA</sub> )	256 °C /W
SOT-23 (θ <sub>ΙΔ</sub> )	177 °C /W

## **Electrical Characteristics**

### **WLED Linear Drivers**

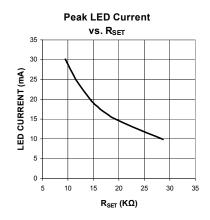
 $V_{IN} = V_{EN} = 3.6 V, \ C_{IN} = 1 \mu F, \ R_{SET} = 9.53 k \Omega; \ V_{D1, \ D2} = 0.6 V; \ T_{J} = 25 ^{\circ}C, \ \textbf{bold} \ \ \text{values indicate} \ -40 ^{\circ}C \leq T_{J} \leq 85 ^{\circ}C; \ unless \ noted.$ 

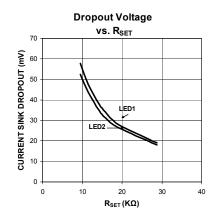
Parameter	Conditions	Min.	Тур.	Max.	Units
Current Accuracy <sup>(3)</sup>		27.18	30.2	33.22	mA
Matching <sup>(4)</sup>			±0.5	±3	%
Drop-Out (V <sub>D1,D2</sub> )	Where $I_{LED}$ = 90% of LED current seen at $V_{DROPNOM}$ = 0.6V, 100% brightness level		52	125	mV
Ground/Supply Bias Current	I <sub>OUT</sub> = 30.2mA		0.7	1.5	mA
Shutdown Current (current source leakage)	V <sub>EN</sub> = 0V		0.01	1	μA
PWM Dimming					
Enable Input Voltage (V )	Logic Low			0.4	V
Enable Input Voltage (V <sub>EN</sub> )	Logic High	1.4			V
Enable Input Current	V <sub>EN</sub> ≥1.4		0.01	1	μΑ
	Shutdown to On		32	80	
Current-Source Delay (50% levels)	Standby to On		1.5	4	μs
	On to Standby		0.3		
Current Source Transient Time (109/ 009/)	T <sub>RISE</sub>		0.7		
Current-Source Transient Time (10%–90%)	T <sub>FALL</sub>		0.2		μs
On-to-Shutdown Time	V <sub>EN</sub> = 0V	4	5.8	10	ms

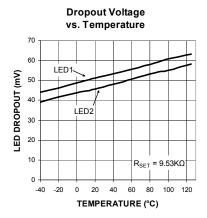
#### Notes:

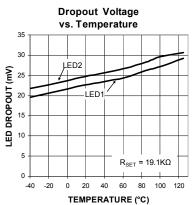
- 1. Exceeding the absolute maximum rating may damage the device.
- 2. The device is not guaranteed to function outside its operating rating.
- 3. As determined by average current of all channels in use and all channels loaded.
- 4. The current through each LED meets the stated limits from the average current of all LEDs.

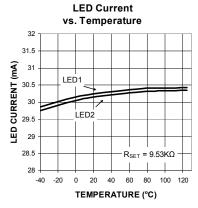
## **Typical Characteristics**

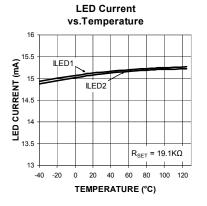


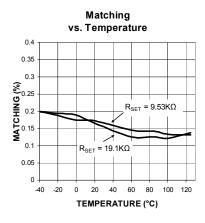




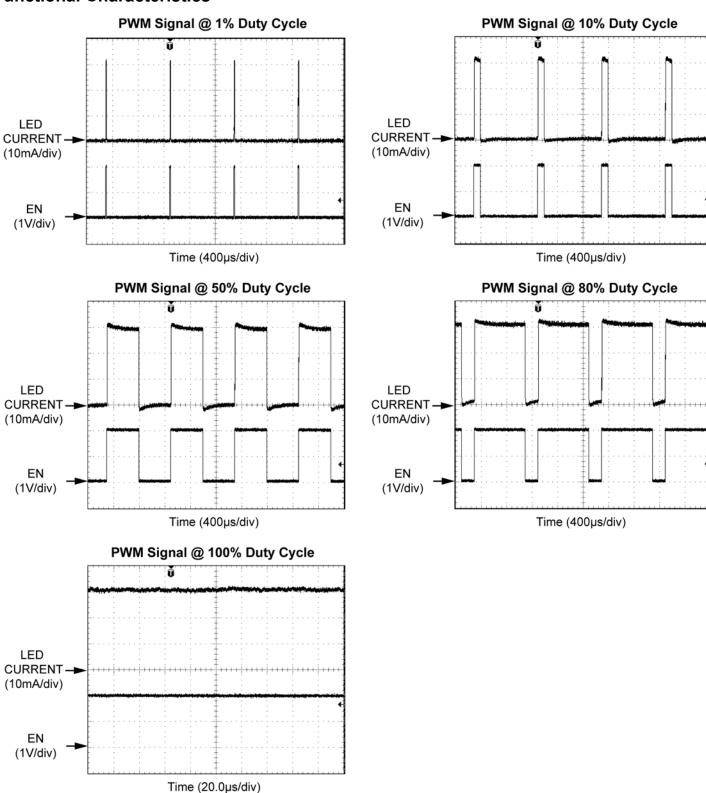




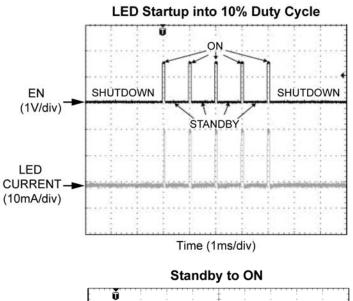


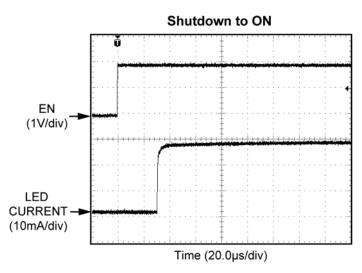


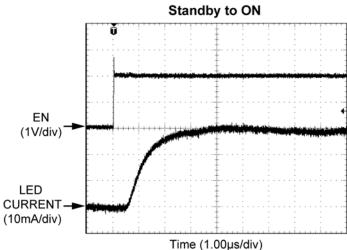
## **Functional Characteristics**

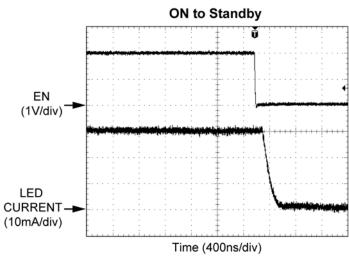


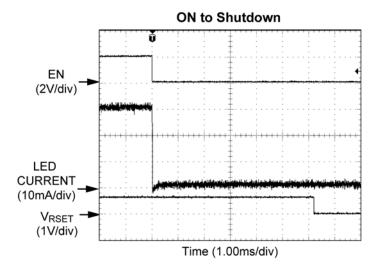
## **Functional Characteristics (Continued)**











# **Functional Diagram**

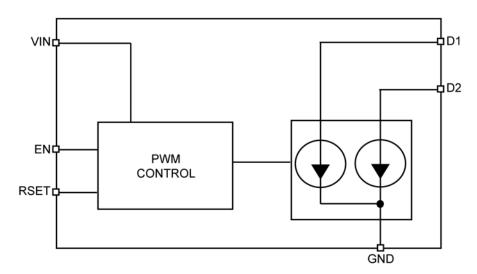


Figure 1. MIC2860-2P Functional Block Diagram

## **Functional Description**

The MIC2860-2P is a two channel WLED driver. The WLED driver is designed to maintain proper current regulation with LED current accuracy of 1% with a typical matching between the 2 channels of ±0.5%. The WLEDs are driven independently from the input supply and will maintain regulation with a dropout of 52mV at 30.2mA. The low dropout of the linear drivers allows the WLEDs to be driven directly from the battery voltage and eliminates the need for large and inefficient charge pumps. The peak WLED current for each channel is set via an external resistor. If dimming is desired the MIC2860-2P can dim via a PWM signal.

### **Block Diagram**

As shown in Figure 1, the MIC2860-2P consists of two current sinks with the peak current determined by  $R_{\text{SET}}.$  The linear drivers have a designated control block for enabling and dimming of the WLEDs. The MIC2860-2P is controlled by the PWM control block that receives PWM signals for dimming.

### VIN

The input supply  $(V_{IN})$  provides power to the linear drivers and the control circuitry. The  $V_{IN}$  operating range is 3V to 5.5V. Due to wire inductance a minimum bypass capacitor of  $1\mu F$  should be placed close to input (VIN) pin and the ground (GND) pin.

#### ΕN

The EN pin enables the linear drivers. It can also be used for dimming with a PWM signal. See the PWM Dimming Interface in the Application Information section for details. Do not leave floating.

### **R**SET

The  $R_{SET}$  pin is used by connecting a  $R_{SET}$  resistor to ground to set the peak current of the linear drivers. The maximum LED current (EN = 100% Duty Cycle) set by the  $R_{SET}$  resistor is shown in the table below:

R <sub>SET</sub> (kΩ)	I <sub>LED</sub> (mA)
9.53	30.2
11.5	25.0
14.3	20.1
15.8	18.2
19.1	15.1
28.7	10.0

Table 1. Maximum LED Current vs. R<sub>SET</sub> Resistor Values

A plot of I<sub>LED</sub> versus R<sub>SET</sub> is shown in Figure 2.

#### **Peak LED Current**

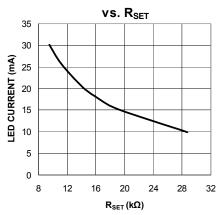


Figure 2. Peak LED Current vs. R<sub>SET</sub>

## D1, D2

The D1 and D2 pins are the linear driver inputs for WLED 1 and 2, respectively. Connect the anodes of the WLEDs to  $V_{\text{IN}}$  and each cathode of the WLEDs to D1 and D2. When operating with a single WLED, D1 and D2 should be connected to the WLED cathode to parallel the outputs for improved dropout performance. Paralleling these pins can also be done to drive a higher current through a single WLED. Do not leave these pins floating.

### **GND**

The ground pin is the ground path for the linear drivers. The current loop for the ground should be as small as possible. The ground of the input capacitor should be routed with low impedance traces to the GND pin and made as short as possible.

## **Application Information**

### **PWM Dimming Interface**

The MIC2860-2P can receive PWM signals from the EN pin for WLED dimming. Dimming is generated by pulsing the WLEDs on and off in synchronization with the PWM signal. The MIC2860-2P incorporates an internal shutdown delay to ensure that the internal control circuitry remains active during PWM dimming for optimum performance.

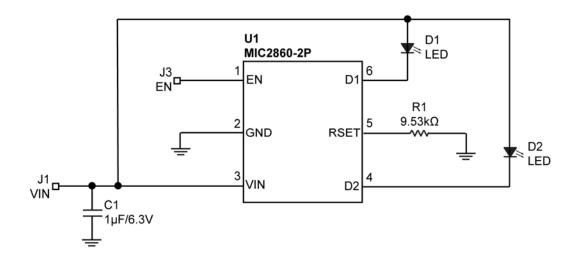
The lower PWM frequency range is recommended at 250Hz due to the minimum standby to shutdown time of 4ms. As the period of 250Hz is 4ms, a 1% duty cycle would have an on time of 40us and an off time of 3.96ms. To support operation down to 1% duty cycle, the maximum off time must not exceed 4ms or the drivers may go into the low Iq shutdown state.

With PWM frequencies higher than 500Hz the  $T_{\text{RISE}}$  (0.7µs) and  $T_{\text{Fall}}$  (0.2µs) times will have a greater effect on the accuracy of the outputs. An upper frequency of 500Hz is recommended to maintain output accuracy with duty cycles down to 1%. For systems that do not require a duty cycle below 1%, the frequency of the PWM signal may be increased. For example, with a minimum duty cycle of 10% (3.02mA with  $R_{\text{SET}} = 9.53 k\Omega$ ) the PWM frequency can be increased to 10kHz and still maintain accuracy.

### **Input Capacitor**

The MIC2860-2P is a high performance, high bandwidth device. Stability can be maintained using a ceramic input capacitor of 1µF. Low-ESR ceramic capacitors provide optimal performance with a minimum amount of space. Additional high frequency capacitors, such as small valued NPO dielectric type capacitors, help filter out high-frequency noise and are good practice in any noise-sensitive circuit. X5R or X7R dielectrics are recommended for the input capacitor. Y5V dielectrics lose most of their capacitance over temperature and are therefore, not recommended.

## **MIC2860-2P Typical Application Circuit**



## **Bill of Materials**

Item	Part Number	Manufacturer	Description	Qty.
C1	C1608X5R0J105K	TDK <sup>(1)</sup>	1μF Ceramic Capacitor, 6.3V, X5R, Size 0603	1
R1	CRCW06032052FT1	Vishay <sup>(2)</sup>	9.53kΩ, 1%, Size 0603	1
U1	MIC2860-2PYC6 MIC2860-2PYD6	Micrel, Inc. <sup>(3)</sup>	2-Channel PWM Linear WLED Driver, SC-70 2-Channel PWM Linear WLED Driver, SOT-23	1

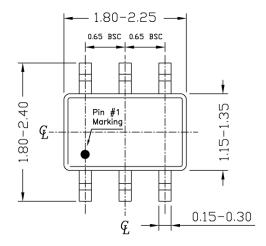
### Notes:

TDK: <u>www.tdk.com</u>.

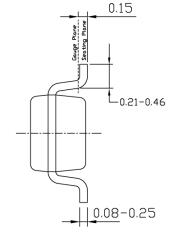
2. Vishay: www.vishay.com.

Micrel, Inc.: <u>www.micrel.com</u>.

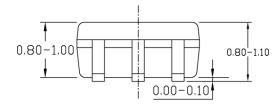
## **Package Information**



TOP VIEW



END VIEW



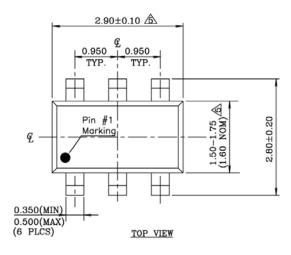
SIDE VIEW

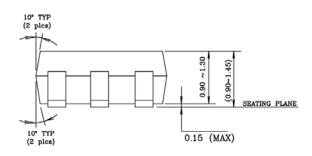
#### NDTE:

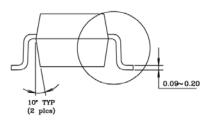
- 1. ALL DIMENSIONS ARE IN MILLIMETERS.
- 2. DIMENSIONS ARE INCLUSIVE OF PLATING.
- 3. DIMENSIONS ARE EXCLUSIVE OF MOLD FLASH & METAL BURR.

6-Pin SC-70 (C6)

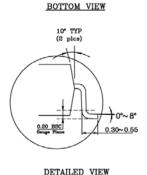
## **Package Information (Continued)**







SIDE VIEW



#### NOTE:

- Dimensions and tolerances are as per ANSI Y14.5M, 1982.
- 2. Package surface to be mirror finish.
- Die is facing up for mold. Die is facing down for trim/form, ie. reverse trim/form.
- 4. The footlength measuring is based on the gauge plane method.
- ⚠ Dimension are exclusive of mold flash & gate burr.

#### 6-Pin Thin SOT-23 (D6)

#### MICREL, INC. 2180 FORTUNE DRIVE SAN JOSE, CA 95131 USA

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