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Page/Date	**Subjects (major changes since last revision)**
2003-03-05	Rev. 1.0: First release of ADM7001
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2005-09-12	Rev. 1.07 when changed to the new Infineon format

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1 Product Overview

Features and Block Diagram.

1.1 Overview

The ADM7001 is a single chip one port 10/100M PHY, which is designed for today's low cost and low power dual speed application.

It supports auto sensing 10/100 Mbps ports with on-chip clock recovery and base line wander correction including integrated MLT-3 functionality for 100 Mbps operation, and also supports Manchester Code Converter with on chip clock recovery circuitry for 10 Mbps functionality. Meanwhile, it provides Medium Independent Interface (MII), Reduced Medium Independent Interface (RMII) and General Purpose Serial Interface (GPSI), three different interfaces in different applications.

For today's IA (Information Application), ADM7001 supports "Auto Cross Over Detection" function to eliminate the technical barrier between networking and end user. With the aid of this auto cross over detection function, Plug-n-Play feature can be easily applied to IA relative products.

The major design target for ADM7001 is to reduce the power consumption and system radiation for the whole system. With the aid of this low power consumption and low radiation chip, the fan and on-system power supply can be removed to save the total manufacture cost and make SOHO application achievable.

1.1.1 Package Information

Product Name	Product Type	Package	Ordering Number
ADM7001	ADM7001	LQFP-48-1	Q67801H 2A[1)]

1) contact Infineon for the updated ordering information

1.2 Features

Main features:

- IEEE 802.3 compatible 10Base-T and 100Base-T physical layer interface and ANSI X3.263 TP-PMD compatible transceiver.
- Single chip, integrated physical layer and transceivers for 10Base-T and 100BASE-TX function.
- Medium Independent Interface (MII), Reduced MII (RMII) and General Purpose Serial Interface (GPSI) for high port count switch.
- Built-in 10 Mbit transmit filter.
- 10 Mbit PLL, exceeding tolerances for both preamble and data jitter.
- 100 Mbit PLL, combined with the digital adaptive equalizer and performance up to 120 meters for UTP 5.
- 125 MHz Clock Generator and Timing Recovery.
- Integrated Base Line Wander Correction.
- Carrier Integrity Monitor function supported.
- Supports FEFI when Auto Negotiation disabled.
- Supports Auto MDIX function for Plug-and-Play
- IEEE 802.3u Clause 28 compliant auto negotiation for full 10 Mbit/s and 100 Mbit/s control.
- Supports programmable LED for different Switch Application and Power On LED Self Test.
- Supports Cable Length Indication both in MII Register and LED (Programmable)
- Supports PECL interface for fiber connection.
- Supports TP vs. FX Medium Converter function.
- Supports Fault Propagation function for medium converter.
- Supports 10K Bytes Jumbo Packet with Clock Skew 150 ppm.

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- Built-in Clock Generator and Power On Reset Signal to save system cost.
- 48 LQFP without regulator.
- Supports Power saving function.
- Supports Parallel LED output.

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1.3 Block Diagram

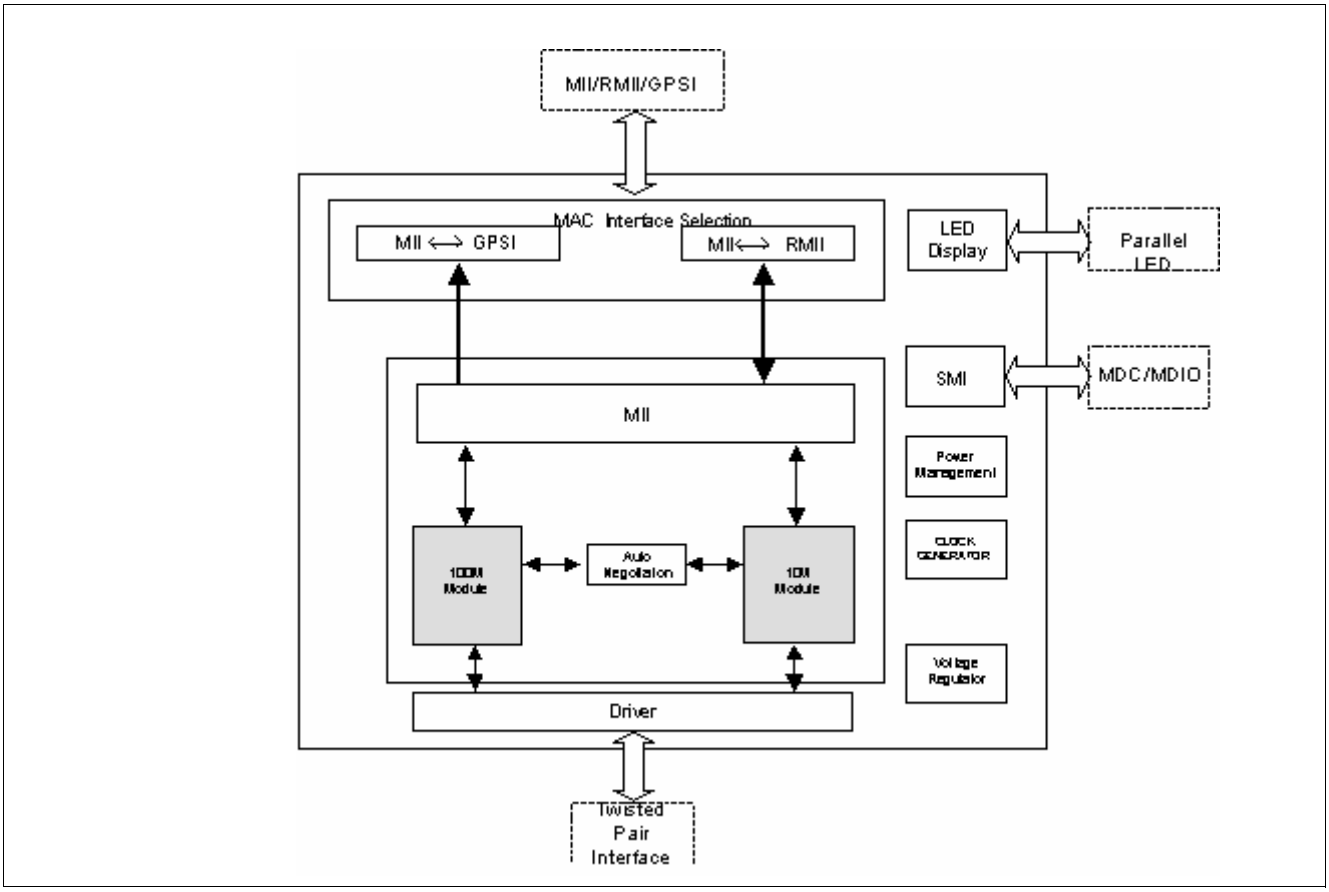

Figure 1 ADM7001 Block Diagram

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2 Interface Description

2.1 Pin Diagram

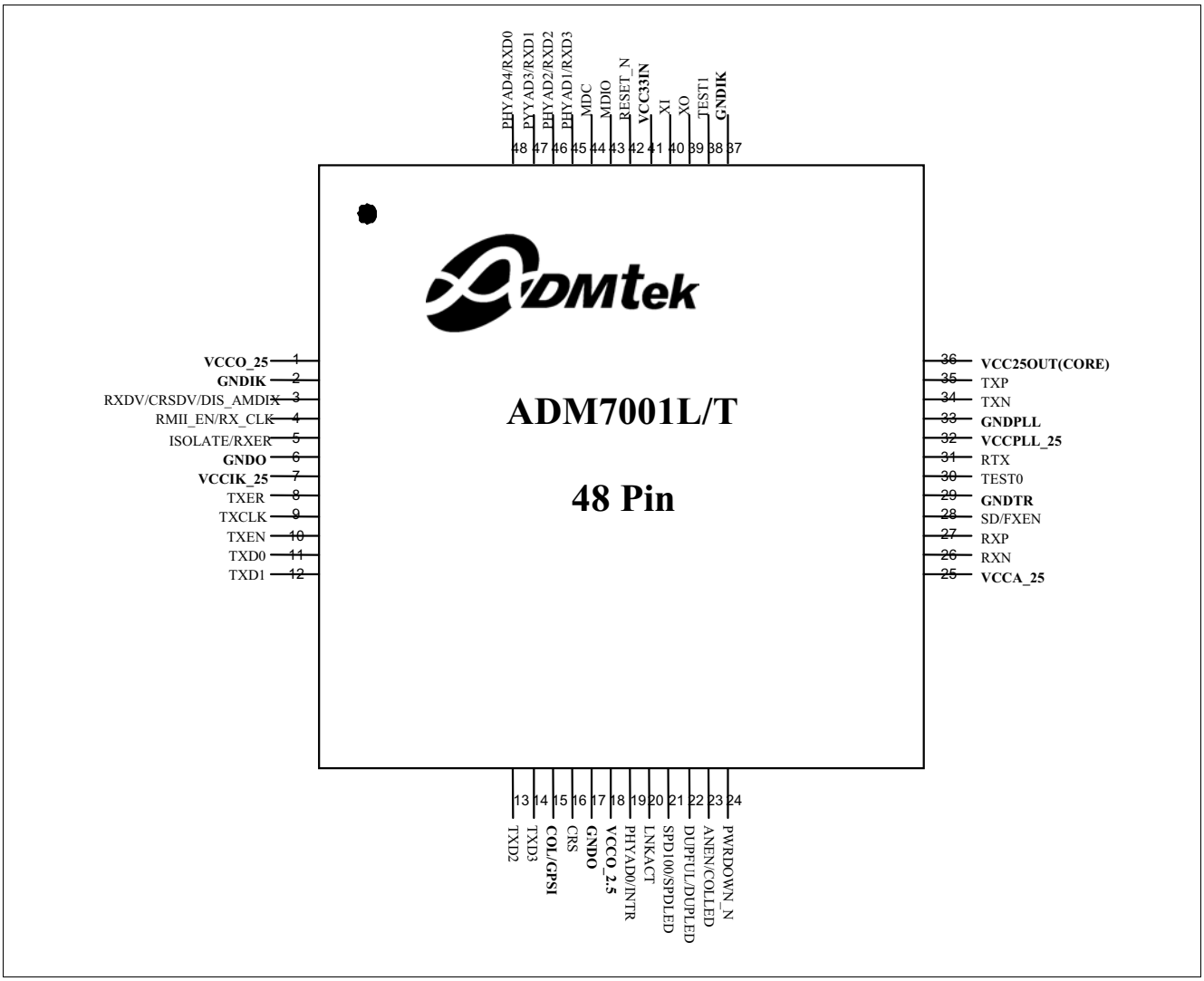

Figure 2 Pin Diagram

2.2 Pin Description

Note: For those pins, which have multiple functions, pin name is separated by slash ("/"). If not specified, all signals are default to digital signals. Please refer to ***Table 1****Pin Type Descriptions' for an explanation of pin abbreviations.*

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Table 1 Abbreviations for Pin Type

Abbreviations	Description
I	Standard input-only pin. Digital levels.
O	Output. Digital levels.
I/O	I/O is a bidirectional input/output signal.
AI	Input. Analog levels.
AO	Output. Analog levels.
AI/O	Input or Output. Analog levels.
PWR	Power
GND	Ground
MCL	Must be connected to Low (JEDEC Standard)
MCH	Must be connected to High (JEDEC Standard)
NU	Not Usable (JEDEC Standard)
NC	Not Connected (JEDEC Standard)

Table 2 Abbreviations for Buffer Type

Abbreviations	Description
Z	High impedance
PU1	Pull up, 10 kΩ
PD1	Pull down, 10 kΩ
PD2	Pull down, 20 kΩ
TS	Tristate capability: The corresponding pin has 3 operational states: Low, high and high-impedance.
OD	Open Drain. The corresponding pin has 2 operational states, active low and tristate, and allows multiple devices to share as a wire-OR. An external pull-up is required to sustain the inactive state until another agent drives it, and must be provided by the central resource.
OC	Open Collector
PP	Push-Pull. The corresponding pin has 2 operational states: Active-low and active-high (identical to output with no type attribute).
OD/PP	Open-Drain or Push-Pull. The corresponding pin can be configured either as an output with the OD attribute or as an output with the PP attribute.
ST	Schmitt-Trigger characteristics
TTL	TTL characteristics

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2.2.1 Twisted Pair Interface, 5 Pins

Table 3 Twisted Pair Interface, 5 Pins

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
35	TXP	AI/O		**Twisted Pair Transmit Output Positive**
34	TXN	AI/O		**Twisted Pair Transmit Output Negative**
27	RXP	AI/O		**Twisted Pair Receive Input Positive**
26	RXN	AI/O		**Twisted Pair Receive Input Negative**
28	Power On Setting FXEN	AI		**Fiber Enable** Value on this pin will be latched by ADM7001 during power on reset as fiber select signal. 0_B , Twisted Pair Mode 1_B , Fiber Optic Mode
	Fiber Mode SDP			**100BASE-FX Signal Detect.** After power on reset stage, this pin acts as signal detect signal from external fiber optic transceiver in case FXEN is detected as high during power on reset. 0_B , No signal detected 1_B , Signal

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2.2.2 Digital Ground/Power, 7 Pins

Table 4 Digital Ground/Power, 7 Pins

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
6, 17	GNDO	D,GND		**Ground used by 3.3 V I/O.**
2, 37	GNDIK	D,GND		**Ground used by Core.**
1, 18	VCCO_25	D,PWR		**2.5V Power used by Digital I/O Pad.**
7	VCCIK_25	D,PWR		**2.5 V Power used by Core**

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2.2.3 Ground and Power, 5 Pins

Table 5 Ground and Power, 5 Pins

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
41	VCC3IN	A,PWR		**3.3V Power input to ADM7001 and used by built-in 3.3 V to 2.5 V regulator.**
36	VCC25OUT	A,PWR		**2.5V Power output by ADM7001. Maximum Supply current from this pin is 200 mA**
29	GNDTR	A,GND		**Analog Ground Pad**
25	VCCA_25	A,PWR		**Analog 2.5 V Power**
32	VCCPLL_25	A,PWR		**Analog 2.5 V Power used by Clock Generator module.**

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2.2.4 Clock Input, 2 Pins

Table 6 Clock Input, 2 Pins

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
40	XI/OSCI	I	CTL	**Crystal/Oscillator input.** 25M Crystal/Oscillator Input in MII mode and 50M Clock input in RMII mode (Also called REFCLK in RMII Mode). *Note: CTL: Crystal*
39	XO	O	CTL	**Crystal output.** When 25M Oscillator is used, this pin should left unconnected. Capable of driving one XI input for multiple port application. *Note: CTL: Crystal*

2.2.5 MII/RMII/GPSI Interface, 16 pins

Table 7 MII/RMII/GPSI Interface, 16 pins

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
9	MII Mode TXCLK	O	16mA	**MII Transmit Clock.** 25M Clock output in 100BASE-X mode and 2.5M Clock output for 10BASE-T mode. This clock is continuously driven output and generated from XI. Before Speed is recognized, this pin drives out continuous 25M clock
	RMII Mode TXCLK			**N/A**
	GPSI Mode TXCLK			**GPSI Transmit Clock.** 10M Clock output in 10BASE-T mode.

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Table 7 MII/RMII/GPSI Interface, 16 pins (cont'd)

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
14, 13, 12, 11	MII Mode TXD[3:0]	I	TTL PD	**Transmit Data.** Nibble-wide transmit data stream in MII mode. These four bits are synchronous to the rising edge of TXCLK and TXD[3] is the most significant bit
	RMII Mode TXD[3:0]			**Di-bits Transmit Data.** TXD0 and TXD1 for the di-bits that are transmitted and are driven synchronously to REFCLK. TXD[1] is the MSB. Note that in 100Mb/s mode, TXD can change once per REFCLK cycle, whereas in 10Mb/s mode, TXD must be held steady for 10 consecutive REFCLK cycles. TXD[3] and TXD[2] are not used in RMII Mode, left unconnected or pull down externally for normal operation.
	GPSI Mode TXD[3:0]			**Serial Transmit Data.** TXD0 for the designated port inputs the data that is transmitted and is driven synchronously to TXCLK in 10Mb/s mode. When ADM7001 is programmed into GPSI mode, TXD[3:1] should be left unconnected or pull down externally for normal operation.
10	MII Mode TXEN	I	TTL PD	**Transmit Enable.** Transmit Enable to indicate that the data on TXD[3:0] is valid.
	RMII Mode TXEN			**Transmit Enable.** TXEN indicates that the di-bit on TXD is valid and it is driven synchronously to REFCLK.
	GPSI Mode TXEN			**Transmit Enable.** Transmit Enable to indicate that the data on TXD0 is valid.
8	MII Mode TXER	I	TTL PD	**Transmit Error.** Active high signal to indicate that there is error condition requested by MAC.
	RMII Mode TXER			**Transmit Error.** Active high signal to indicate that there is error condition requested by MAC.
	GPSI Mode LOW			Keep Low in GPSI Mode.

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Table 7 MII/RMII/GPSI Interface, 16 pins (cont'd)

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
4	Power On Setting RMII_EN	I	LVTTL PD	**RMII Enable.** Used to select MII or RMII operation. The default value during power on reset is 0 (Before RMII_EN and GPSI value is determined) *Note: LVTTL: Low Voltage TTL Level* 0_B , MII Mode 1_B , RMII Mode
	MII Mode RX_CLK	O	16mA	**MII Receive Clock.** 25M Clock output in 100BASE-X mode, 2.5M Clock output for 10BASE-T MII mode. This clock is recovered from the received data on the cable input. Due to recovered from incoming receive data, it is possible that RXCLK starts running yet RXDV keeps low for a while. During power on reset, there is no receiving clock driven by ADM7001
	RMII Mode CLKO50			**RMII 50M Clock Output.** This pin outputs continuous 50M clock in RMII mode. To reduce the BOM cost for system application, user can connect this pin directly to REFCLK to proper RMII operation.
	GPSI Mode RX_CLK			**GPSI Receive Clock.** 10M clock for 10BASE-T GPSI mode. This clock is recovered from the received data on the cable input. Due to recovered from incoming receive data, it is possible that RXCLK starts running yet CRS keeps low for a while. During power on reset, there is no receiving clock driven by ADM7001. *Note: That clock on this pin will not be active during power on reset due to power on setting.*

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Table 7 MII/RMII/GPSI Interface, 16 pins (cont'd)

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
3	Power On Setting DIS_AMDIX_EN	I	LVTTL PD	**Disable Auto Crossover Function** Value on this pin will be latched by ADM7001 to select Auto Cross-Over Function. *Note: LVTTL: Low Voltage TTL Level* 0_B , Enable Auto Crossover 1_B , Disable Auto Crossover
	MII Mode RXDV	O	8mA	**MII Receive Data Valid.** Active high signal to indicate that the data on RXD[3:0] is valid. Synchronous to the rising edge of RXCLK in MII mode.
	RMII Mode CRSDV			**RMII Carrier Sense/Receive Data Valid.** Represents Receive Carrier Sense and Data Valid in RMII mode. CRSDV asserts when the receive medium is non-idle. The assertion of CRSDV is asynchronous to REFCLK. At the de-assertion of carrier, CRSDV de-asserts synchronously to REFCLK only on the first di-bit of RXD. If there is still data in the FIFO not yet presented onto RXD, then on the second di-bit of RXD, CRSDV is asserted synchronously to REFCLK. The toggling of CRSDV_P on the first and second di-bit continues until all the data in the FIFO is presented onto RXD. CRSDV is asserted for the duration of carrier activity for a false carrier event.
	GPSI Mode LOW			**Keep Low in GPSI Mode.**
45, 46, 47, 48	Power On Setting PHYAD[1:4]	I	TTL PD	**PHY Address Select** Value on these 4 pins combined with PHYAD0 will be stored into ADM7001 as PHY physical address during power on reset. After power on reset, these 4 pins are output.
	MII Mode RXD[3:0]	O	8mA	**MII Receive Data.** Nibble-wide receive data stream in MII mode. These four bits are synchronous to the rising edge of RX_CLK and RXD[3] is the most significant bit.
	RMII Mode RXD[1:0]			**RMII Receive Data.** RXD0 and RXD1 for the di-bits that are received and are driven synchronously to REFCLK. RXD[1] is the MSB. Note that in 100Mb/s mode, RXD can change once per REFCLK cycle, whereas in 10Mb/s mode, RXD must be held steady for 10 consecutive REFCLK cycles. RXD[3:2] have not used in this mode.
	GPSI Mode RXD			**GPSI Receive Data.** RXD0 for the designated port inputs the data that is transmitted and is driven synchronously to RX_CLK in 10Mb/s mode. RXD[3:1] have not used in this mode.

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Table 7 MII/RMII/GPSI Interface, 16 pins (cont'd)

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
5	Power On Setting ISOLATE	I	TTL PD	**ISOLATE** Value on this pin will be latched by ADM7001 during power on reset. 0_B , Normal Operation 1_B , All MII outputs are tri-stated. All MII Inputs(TXD, TXEN, TXER) are ignored
	MII Mode RXER	O	4mA	**MII Receive Error.** Active high signal to indicate that there is error condition detected by ADM7001. When error is detected, RXER will be high and maintains high until RXDV is de-asserted.
	RMII Mode RXER			**RMII Receive Error.** Active high signal to indicate that there is error condition detected by ADM7001. When error is detected, RXER will be high and maintains high until CRSDV is de-asserted.
	GPSI Mode N/A			**No Operation in GPSI Mode.**
15	Power On Setting GPSI	I	PD	**GPSI Mode Select** Value on this pin will be sampled by ADM7001 during power on reset to form GPSI internal control signal. Together with RMII_EN, these two pins form three possible internal supported by ADM7001. RMII_EN GPSI Interface 0_B , 0_B MII 0_B , 1_B GPSI(1M8) 1_B , x RMII
	GPSI/MII Mode COL	O	8mA	**GPSI/MII Collision** In half duplex mode, active high to indicate that there is collision on the medium. In full duplex mode, this pin will keep low all the time.
	RMII Mode N/A			**Not Available**

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Table 7 MII/RMII/GPSI Interface, 16 pins (cont'd)

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
16	Power On Setting REPEATER	I	LVTTL PD	**Repeater Mode.** Value on this pin will be latched by ADM7001 during power on reset as repeater mode *Note: LVTTL: Low Voltage TTL Level* 0_B , SW/NIC mode, CRS will be asserted according to RX/TX in half duplex mode. 1_B , REPEATER mode. CRS will be asserted only in RX mode in half duplex operation.
	MII Mode CRS	O	8mA	**MII Carrier Sense.** This bit indicates that there is carrier sense presented on the medium. Note that in half duplex mode, this pin will also be asserted high by ADM7001 under transmit condition. This pin is asynchronous to RX_CLK.
	RMII Mode N/A			**Not Available.**
	GPSI Mode CRS			**GPSI Carrier Sense.** This bit indicates that there is carrier sense presented on the medium. Note that in half duplex mode, this pin will also be asserted high by ADM7001 under transmit condition. This pin is asynchronous to RX_CLK.

Note: LVTTL: Low Voltage TTL Level

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2.2.6 Reset Pin

Table 8 Reset Pin

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
42	RESET#	I	ST	**Reset Signal** Active low to bring ADM7001 into reset condition. Recommend keeping low for at least 200 ms to ensure the stability of the system after power on reset.

2.2.7 Clock Signals, 6 Pins

Table 9 Clock Signals, 6 pins

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
43	MDIO	I/O	LVTTL PU	**Management Data.** MDIO transfers management data in and out of the device synchronous to MDC. *Note: LVTTL: Low Voltage TTL Level*
44	MDC	I	LVTTL	**Management Data Reference Clock.** A non-continuous clock input for management usage. ADM7001 will use this clock to sample data input on MDIO and drive data onto MDIO according to rising edge of this clock. *Note: LVTTL: Low Voltage TTL Level*
19	Power On Setting PHYAD0	I	LVTTL PU	**PHY Address bit 0.** See RXD[3:0] description. *Note: LVTTL: Low Voltage TTL Level*
	MII/RMII/GPSI Mode INTR#			**Interrupt** Default active low signal to indicate that there is interrupt event in SMI register. Active value of interrupt signal can be configured by register 18.1. Only available when interrupt mode is selected. *Note: LVTTL: Low Voltage TTL Level*
24	PWRDOWN#	I	LVTTL PU	**Low Power Operation.** *Note: When RESET# is reset to 0 and PWRDOWN# is set to 0, whole ADM7001 blocks will be disabled.* 0_B , ADM7001 in low power mode operation. All blocks except the energy detection and crystal oscillator are de-activated. 1_B , ADM7001 in normal mode operation. *Note: LVTTL: Low Voltage TTL Level*
38, 30	TEST[1:0]	I	LVTTL PD	**Industrial Test Pin.** Keeps low for normal operation. *Note: LVTTL: Low Voltage TTL Level*

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2.2.8 LED Interface, 4 Pins

Table 10 LED Interface, 4 Pins

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
20	Reserved	I	TTL PU	**Reserved.**
	LNKACT	O	8mA	**Link/Activity LED.** Active low (Note) 100ms (blink 100ms) to indicate that there is transmit or receive activity after Link Up. Keeps high all the time when link is failed.
21	Power On Setting SPD100	I	TTL PU	**Recommend 100M Operation.** This bit is only available in TP mode. Together with ANEN to form speed mode select for ADM7001: ANEN SPD100 Mode 0_B , 0_B Force 10BASE-T Mode 0_B , 1_B Force 100BASE-TX Mode 1_B , 0_B 10M Capability 1_B , 1_B 10/100M Capability
	Normal Mode SPDLED	O	8mA	**Speed LED.(Note)** 0_B , 100M 1_B , 10M **Cable Length LED.** When FXEN is low and MII register 18.2 DIS_CABLEN_LED is set to 0, this pin together with COLLED and LNKACTLED form cable length information on twisted pair *Note: That the following indication assume recommend value on SPDLED, COLLED and LNKACTLED is high, when corresponding bit's power on setting bit is 0, polarity of corresponding bit will be inverted.* **SPDLED COLLED LNKACTLED Cable Length** *Note: When recommend value during power on is high, then this signal is active low; if the recommend value is low, then this signal is active high.* 110_B , >140 meters or Link Failed 110_B , 0 - 40 meters 100_B , 40 - 80 meters 000_B , 80 - 120 meters xxx_B , Flashed Reserved

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Table 10 LED Interface, 4 Pins (cont'd)

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
22	Power On Setting DUPFUL	I	TTL PU	**Duplex Control** This pin is only available when auto negotiation is disabled. ANEN DUPFUL Mode 0_B , 0_B Force to Half Duplex Mode 0_B , 1_B Force to Full Duplex Mode 1_B , 0_B Half Duplex Capability 1_B , 1_B Full/Half Duplex Capability
	Normal Mode DUPLED	O	8 mA	**Duplex LED.(Note)** *Note: When recommend value during power on is high, then this signal is active low; if the recommend value is low, then this signal is active high. This rule also applies to Cable Length indication* 0_B , Full Duplex 1_B , Half Duplex
23	Power On Setting ANEN	I	TTL PU	**Auto Negotiation Enable.** This bit is only available in TP mode. 0_B , Disable Auto Negotiation 1_B , Enable Auto Negotiation
	Normal Mode COLLED	O	8mA	**Collision LED.** Keep high (Note) when ADM7001 is in full duplex mode and will blink 100 ms when collision condition is detected in half duplex mode. *Note: When recommend value during power on is high, then this signal is active low; if the recommend value is low, then this signal is active high.*

2.2.9 Regulator Control

Table 11 Regulator Control

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
31	RTX	AI		**Constant Voltage Reference.** External 1.1kΩ +/- 1% resistor connection to ground.

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3 Function Description

ADM7001 integrates 100Base-X physical sub layer (PHY), 100Base-TX physical medium dependent (PMD) transceivers, and complete 10Base-T modules into a single chip for both 10 Mbps and 100 Mbps Ethernet operations. It also supports 100Base-FX operation through external fiber-optic transceivers. The device is capable of operating in either full-duplex mode or half-duplex mode in either 10 Mbps or 100 Mbps operation. Operational modes can be selected by hardware configuration pins, software settings of management registers, or determined by the on-chip auto negotiation logic.

The 10Base-T section of the device consists of the 10 Mbps transceiver module with filters and a Manchester ENDEC module.

ADM7001 consists of seven kinds of major blocks:

- 10/100M PHY Block
- MAC Interface
- LED Display
- SMI
- Power Management
- Clock Generator
- Voltage Regulator

Each 10/100M PHY block contains:

- 10M PHY block
- 100M PHY block
- Auto-negotiation
- Other Digital Control Blocks

3.1 10/100M PHY Block

The 100Base-X section of the device implements the following functional blocks:

- 100Base-X physical coding sub-layer (PCS)
- 100Base-X physical medium attachment (PMA)
- Twisted-pair PMD (TP-PMD) transceiver

The 100Base-X and 10Base-T sections share the following functional blocks:

- Clock synthesizer module
- MII Registers
- IEEE 802.3u auto negotiation

The interface used for communication between PHY block and switch core is MII interface.

3.1.1 100Base-X Module

ADM7001 implements 100Base-X compliant PCS and PMA, and 100Base-TX compliant TP-PMD as illustrated in **Figure 3**. Bypass options for each of the major functional blocks within the 100Base-X PCS provide flexibility for various applications. 100 Mbit/s PHY loop back is included for diagnostic purpose.

3.1.2 100Base-TX Receiver

For 100Base-TX operation, the on-chip twisted pair receiver that consists of a differential line receiver, an adaptive equalizer and a base-line wander compensation circuits detects the incoming signal.

ADM7001 uses an adaptive equalizer that changes filter frequency response in accordance with cable length. The cable length is estimated based on the incoming signal strength. The equalizer tunes itself automatically for any cable length to compensate for the amplitude and phase distortions incurred from the cable.

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The 100Base-X receiver consists of functional blocks required to recover and condition the 125 Mbps receive data stream. The ADM7001 implements the 100Base-X receiving state machine diagram as given in ANSI/IEEE Standard 802.3u, Clause 24. The 125 Mbps receive data stream may originate from the on-chip twisted-pair transceiver in a 100Base-TX application. Alternatively, the receive data stream may be generated by an external optical receiver as in a 100Base-FX application.

The receiver block consists of the following functional sub-blocks:

- A/D Converter
- Adaptive Equalizer and Timing Recovery Module
- NRZI/NRZ and Serial/Parallel Decoder
- De-scrambler
- Symbol Alignment Block
- Symbol Decoder
- Collision Detect Block
- Carrier Sense Block
- Stream Decoder Block

A/D Converter

High performance A/D converter with 125M sampling rate converts signals received on RXP/RXN pins to 6-bits data streams; besides it possess auto-gain-control capability that will further improve receive performance especially under long cable or harsh detrimental signal integrity. Due to high pass characteristic on transformer, built in base-line-wander correcting circuit will cancel it out and restore its DC level.

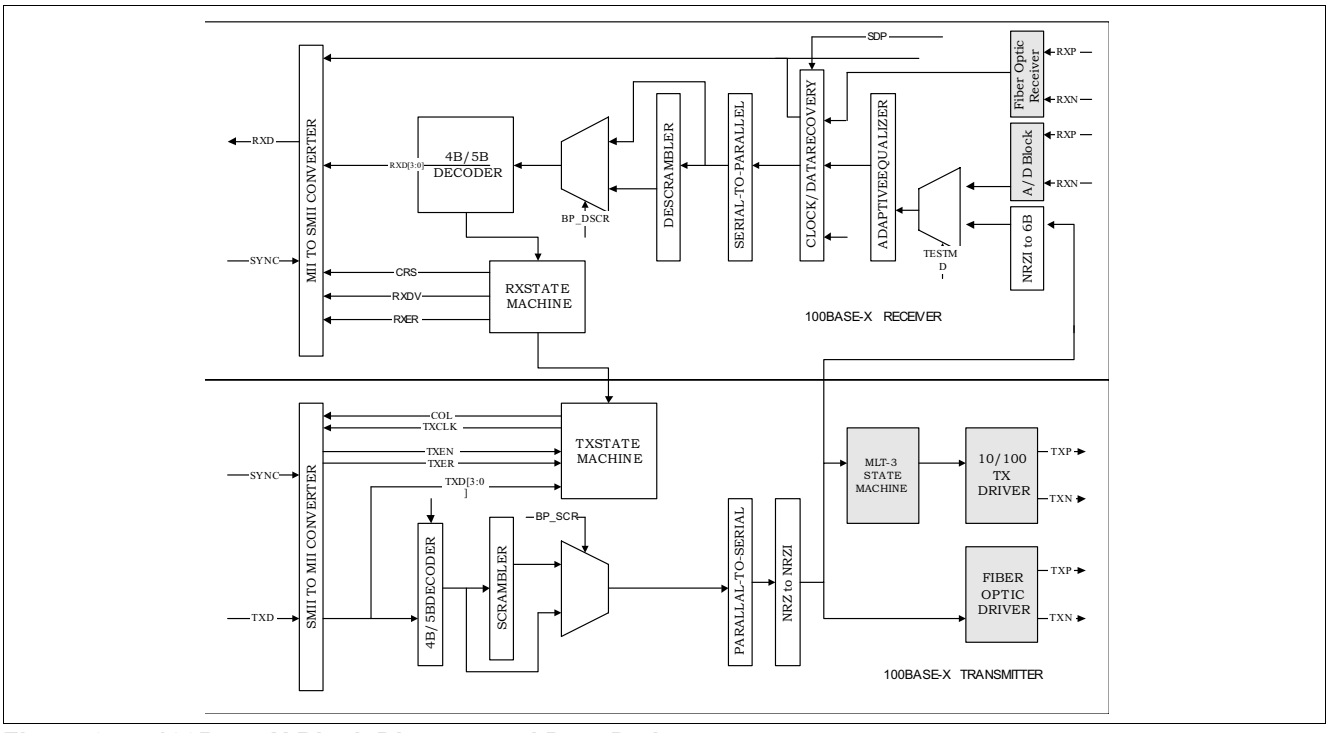

Figure 3 100Base-X Block Diagram and Data Path

Adaptive Equalizer and Timing Recovery Module

All digital design is especially immune from noise environments, and achieves better correlations between production and system testing. Baud rate Adaptive Equalizer/Timing Recovery compensates line loss induced from twisted pair and tracks far end clock at 125M samples per second. Adaptive Equalizer implemented with Feed

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forward and Decision Feedback techniques meets the requirement of BER less than 10-12 for transmission on CAT5 twisted pair cable ranging from 0 to 140 meters.

NRZI/NRZ and Serial/Parallel Decoder

The recovered data is converted from NRZI to NRZ. The data is not necessarily aligned to 4B/5B code group's boundary.

Data Descrambling

The descrambler acquires synchronization with the data stream by recognizing idle bursts of 40 or more bits and locking its deciphering Linear Feedback Shift Register (LFSR) to the state of the scrambling LFSR. Upon achieving synchronization, the incoming data is XORed by the deciphering LFSR and descrambled.

In order to maintain synchronization, the descrambler continuously monitors the validity of the unscrambled data that it generates. To ensure this, a link state monitor and a hold timer are used to constantly monitor the synchronization status. Upon synchronization of the descrambler the hold timer starts a 722 μs countdown. Upon detection of at least 6 idle symbols (30 consecutive 1) within the 722 μs period, the hold timer will reset and begin a new countdown. This monitoring operation will continue indefinitely to give a properly operating network connection with good signal integrity. If the link state monitor does not recognize at least 6 unscrambled idle symbols within 722 μs period, the descrambler will be forced out of the current state of synchronization and reset in order to re-acquire synchronization.

Symbol Alignment

The symbol alignment circuit in the ADM7001 determines code word alignment by recognizing the /J/K delimiter pair. This circuit operates on unaligned data from the descrambler. Once the /J/K symbol pair (11000 10001) is detected, subsequent data is aligned on a fixed boundary.

Symbol Decoding

The symbol decoder functions as a look-up table that translates incoming 5B symbols into 4B nibbles as shown in **Table 12**. The symbol decoder first detects the /J/K symbol pair preceded by idle symbols and replaces the symbol with MAC preamble. All subsequent 5B symbols are converted to the corresponding 4B nibbles for the duration of the entire packet. This conversion ceases upon the detection of the /T/R symbol pair denoting the end of stream delimiter (ESD). The translated data is presented on the internal RXD[3:0] signal lines with RXD[0] represents the least significant bit of the translated nibble.

Table 12 Look-up Table for Translating 5B Symbols into 4B Nibbles

PCS Code-Group[4:0]	Name	MII (TXD/RXD)<3:0>	Interpretation
11110	0	0000	Data 0
01001	1	0001	Data 1
10100	2	0010	Data 2
10101	3	0011	Data 3
01010	4	0100	Data 4
01011	5	0101	Data 5
01110	6	0110	Data 6
01111	7	0111	Data 7
10010	8	1000	Data 8
10011	9	1001	Data 9
10110	A	1010	Data A
10111	B	1011	Data B

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Table 12 Look-up Table for Translating 5B Symbols into 4B Nibbles (cont'd)

PCS Code-Group[4:0]	Name	MII (TXD/RXD)<3:0>	Interpretation
11010	C	1100	Data C
11011	D	1101	Data D
11100	E	1110	Data E
11101	F	1111	Data F
11111	I	Undefined	IDLEused as inter-stream fill code
11000	J	0101	Start-of-Stream Delimiter, Part 1 of 2; always used in pairs with K
10001	K	0101	Start-of-Stream Delimiter, Part 2 of 2; always used in pairs with J
01101	T	Undefined	Start-of-Stream Delimiter, Part 1 of 2; always used in pairs with R
0111	R	Undefined	Start-of-Stream Delimiter, Part 2 of 2; always used in pairs with T
00100	H	Undefined	Transmit Error; used to force signaling errors
00000	V	Undefined	Invalid code
00001	V	Undefined	Invalid code
00010	V	Undefined	Invalid code
00011	V	Undefined	Invalid code
00101	V	Undefined	Invalid code
00110	V	Undefined	Invalid code
01000	V	Undefined	Invalid code
01100	V	Undefined	Invalid code
10000	V	Undefined	Invalid code
11001	V	Undefined	Invalid code

Valid Data Signal

The valid data signal (RXDV) indicates that recovered and decoded nibbles are presented on the internal RXD[3:0] synchronous to receive clock, RXCLK. RXDV is asserted when the first nibble of translated /J/K is ready for transfer over the internal MII. It remains active until either the /T/R delimiter is recognized, link test indicates failure, or no signal is detected. On any of these conditions, RXDV is deasserted.

Receive Errors

The RXER signal is used to communicate with receiver error conditions. While the receiver is in a state of holding RXDV asserted, the RXER will be asserted for each code word which does not map to a valid code-group.

100Base-X Link Monitor

The 100Base-X link monitor function allows the receiver to ensure that reliable data is received. Without reliable data reception, the link monitor will halt both transmit and receive operations until a valid link is detected.

The ADM7001 performs the link integrity test as outlined in IEEE 100Base-X (Clause 24) link monitor state diagram. The link status is multiplexed with 10 Mbits/s link status to form the reportable link status bit in serial management register 1h, and driven to the LNKACT pin.

When persistent signal energy is detected on the network, the logic moves into a Link-Ready state after approximately 500 µs, and waits for an enable from the auto negotiation module. When receiving, the link-up state

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is entered, and the transmission and reception logic blocks become active. Should auto negotiation be disabled, the link integrity logic moves immediately to the link-up state after entering the link-ready state.

Carrier Sense

Carrier sense (CRS) for 100 Mbits/s operation is asserted upon the detection of two non contiguous zeros occurring within any 10-bit boundary of the received data stream.

The carrier sense function is independent of symbol alignment. In switch mode, CRS is asserted during either packet transmission or reception. For repeater mode, CRS is asserted only during packet reception. When the idle symbol pair is detected in the received data stream, CRS is deasserted. In repeater mode, CRS is only asserted due to receive activity. CRS is intended to encapsulate RXDV.

Bad SSD Detection

A bad start of stream delimiter (Bad SSD) is an error condition that occurs in the 100Base-X receiver if carrier is detected (CRS asserted) and a valid /J/K set of code-group (SSD) is not received.

If this condition is detected, the ADM7001 will assert RXER and present RXD[3:0] = 1110 to the internal MII for the cycles hat correspond to receive 5B code-groups until at least two idle code-groups are detected. Once at least two idle code groups are detected, RXER and CRS become deasserted.

Far-End Fault

Auto negotiation provides a mechanism for transferring information from the Local Station to the link Partner that a remote fault has occurred for 100Base-TX. As auto negotiation is not currently specified for operation over fiber, the far end fault indication function (FEFI) provides this capability for 100Base-FX applications.

A remote fault is an error in the link that one station can detect while the other cannot. An example of this is a disconnected wire at a station's transmitter. This station will receive valid data and detect that the link is good via the link integrity monitor, but will not be able to detect that its transmission is not propagating to the other station.

A 100Base-FX station that detects such a remote fault may modify its transmitted idle stream from all ones to a group of 84 ones followed by a single 0. This is referred to as the FEFI idle pattern.

The FEFI function is controlled by bit 3 of register 11_H. It is initialized to 1 (encoded) if the SELFX pin is at logic high level during power on reset. If the FEFI function is enabled the ADM7001 will halt all current operations and transmit the FEFI idle pattern when FOSD signal is de-asserted following a good link indication from the link integrity monitor. FOSD signal is generated internally from the internal signal detect circuit. Transmission of the FEFI idle pattern will continue until link up signal is asserted. If three or more FEFI idle patterns are detected by the ADM7001, bit 4 of the Basic mode status register (address 1h) is set to one until read by management. Additionally, upon detection of far end fault, all receive and transmit MII activities are disabled/ignored.

3.1.3 100Base-TX Transmitter

ADM7001 implements a TP-PMD compliant transceiver for 100Base-TX operation. The differential transmit driver is shared by the 10Base-T and 100Base-TX subsystems. This arrangement results in one device that uses the same external magnetics for both the 10Base-T and the 100Base-TX transmission with simple RC component connections. The individually wave-shaped 10Base-T and 100Base-TX transmit signals are multiplexed in the transmission output driver selection.

ADM7001 100Base-TX transmission driver implements MLT-3 translation and wave-shaping functions. The rise/fall time of the output signal is closely controlled to conform to the target range specified in the ANSI TP-PMD standard.

3.1.4 100Base-FX Receiver

Signal is received through PECL receiver inputs from fiber transceiver, and directly passed to clock recovery circuit for data/clock recovery. Scrambler/de-scrambler is bypassed in 100Base-FX.

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Automatic “Signal_Detect“ Function Block

When DIS_ANASDEN_N in register 18 is set to 0, ADM7001 doesn't support SDP detection in fiber mode, which is used to connect to fiber transceiver to indicate there is signal on the fiber. Instead, ADM7001 uses the data on RXP/RXN to detect consecutive 65 “1” on the receive data (Recovered from RXP/RXN) to determine whether “Signal” is detected or not. When the detect condition is true (Consecutive 65 bits “1”), internal signal detect signal will be asserted to inform receive relative blocks to be ready for coming receive activities.

3.1.5 100Base-FX Transmitter

In 100Base FX transmit, the serial data stream is driven out as NRZI PECL signals, which enter fiber transceiver in differential-pairs form. Fiber transceiver should be available working at 3.3 V environment.

3.1.6 10Base-T Module

The 10Base-T Transceiver Module is IEEE 802.3 compliant. It includes the receiver, transmitter, collision, heartbeat, loopback, jabber, waveshaper, and link integrity functions, as defined in the standard. **Figure 4** provides an overview for the 10Base-T module.

The ADM7001 10Base-T module is comprised of the following functional blocks:

- Manchester encoder and decoder
- Collision detector
- Link test function
- Transmit driver and receiver
- Serial and parallel interface
- Jabber and SQE test functions
- Polarity detection and correction

3.1.7 Operation Modes

The ADM7001 10Base-T module is capable of operating in either half-duplex mode or full-duplex mode. In half-duplex mode, the ADM7001 functions as an IEEE 802.3 compliant transceiver with fully integrated filtering. The COL signal is asserted during collisions or jabber events, and the CRS signal is asserted during transmitting and receiving. In full duplex mode the ADM7001 can simultaneously transmit and receive data.

3.1.8 Manchester Encoder/Decoder

Data encoding and transmission begin when the transmission enable input (TXEN) goes high and continues as long as the transceiver is in good link state. Transmission ends when the transmission enable input goes low. The last transition occurs at the center of the bit cell if the last bit is 1, or at the boundary of the bit cell if the last bit is 0.

A differential input receiver circuit accomplishes decoding and a phase-locked loop that separates the Manchester-encoded data stream into clock signals and NRZ data. The decoder detects the end of a frame when no more mid bit transitions are detected. Within one and half bit times after the last bit, carrier sense is deasserted.

3.1.9 Transmit Driver and Receiver

The ADM7001 integrates all the required signal conditioning functions in its 10Base-T block such that external filters are not required. Only one isolation transformer and impedance matching resistors are needed for the 10Base-T transmit and receive interface. The internal transmit filtering ensures that all the harmonics in the transmission signal are attenuated properly.

3.1.10 Smart Squelch

The smart squelch circuit is responsible for determining when valid data is present on the differential receives. The ADM7001 implements an intelligent receive squelch on the RXP/RXN differential inputs to ensure that impulse

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noise on the receive inputs will not be mistaken for a valid signal. The squelch circuitry employs a combination of amplitude and timing measurements (as specified in the IEEE 802.3 10Base-T standard) to determine the validity of data on the twisted-pair inputs.

The "analog squelch circuit" checks the signal at the start of the packet and any pulses not exceeding the squelch level (either positive or negative, depending upon polarity) will be rejected. Once this first squelch level is overcome correctly, the opposite squelch level must then be exceeded within 150ns. Finally, the signal must exceed the original squelch level within an additional 150ns to ensure that the input waveform will not be rejected.

Only after all these conditions have been satisfied will a control signal be generated to indicate to the remainder of the circuitry that valid data is present.

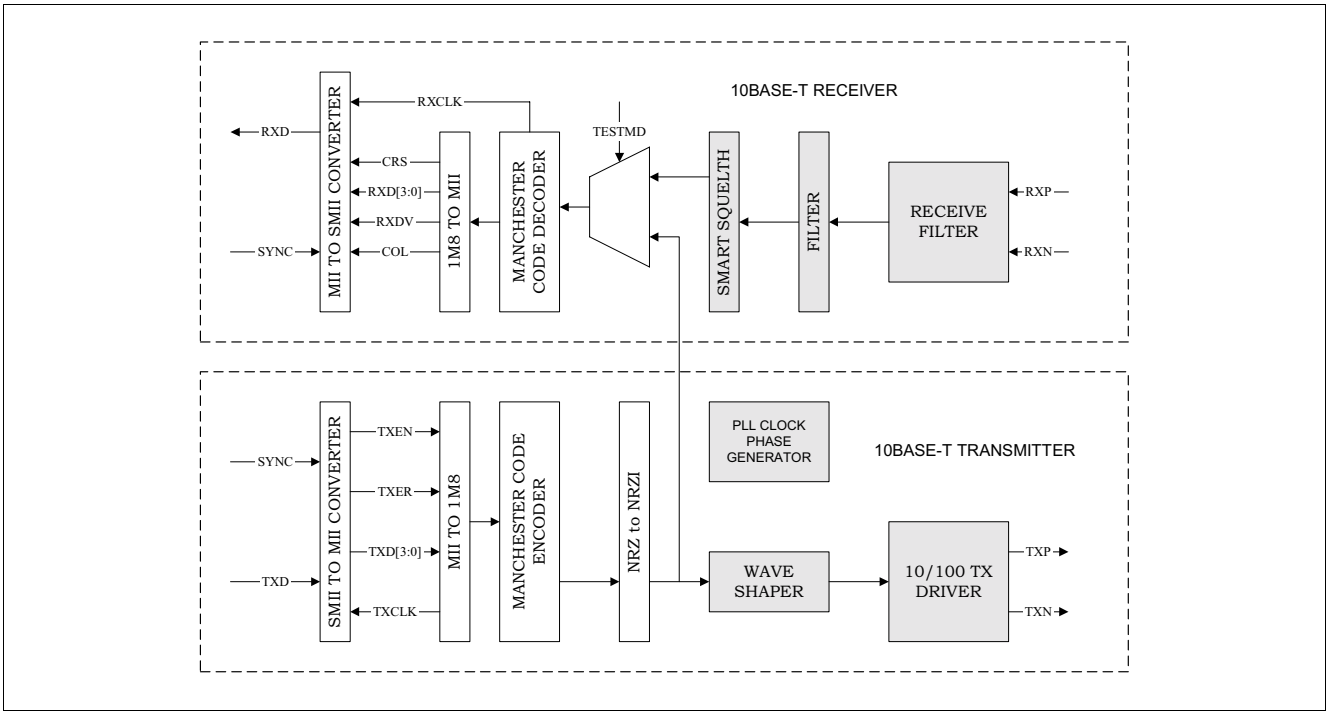

Figure 4 10Base-T Block Diagram and Data Path

Valid data is considered to be present until the squelch level has not been generated for a time longer than 200 ns, indicating end of packet. Once good data has been detected, the squelch levels are reduced to minimize the effect of noise, causing premature end-of-packet detection. The receive squelch threshold level can be lowered for use in longer cable applications. This is achieved by setting bit 7 of register address 10_H.

3.1.11 Carrier Sense

Carrier Sense (CRS) is asserted due to receive activity once valid data is detected via the smart squelch function. For 10 Mbit/s half duplex operation, CRS is asserted during either packet transmission or reception. For 10 Mbit/s full duplex and repeater mode operations, the CRS is asserted only due to receive activity.

3.1.12 Collision Detection

Collision is detected internal to the MAC, which is generated by an AND function of TXEN and RXDV derived from internal timing recovery circuitry. Note should be taken that due to TXEN and RXDV are asynchronous to each other, COL signal outputted by ADM7001 is irrelevant to either TXCLK or RXCLK.

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3.1.13 Jabber Function

The jabber function monitors the ADM7001 output and disables the transmitter if it attempts to transmit a longer than legal sized packet. If TXEN is high for greater than 24ms, the 10Base-T transmitter will be disabled. Once disabled by the jabber function, the transmitter stays disable for the entire time that the TXEN signal is asserted. This signal has to be de-asserted for approximately 408 ms (The un-jab time) before the jabber function re-enables the transmit outputs. The jabber function can be disabled by programming bit 0 of register address 10_H to high.

3.1.14 Link Test Function

A link pulse is used to check the integrity of the connection with the remote end. If valid link pulses are not received, the link detector disables the 10Base-T twisted-pair transmitter, receiver, and collision detection functions.

The link pulse generator produces pulses as defined in IEEE 802.3 10Base-T standard. Each link pulse is nominally 100 ns in duration and is transmitted every 16 ms, in the absence of transmit data. Setting bit 10 of register 10_H to high can disable link pulse check function.

3.1.15 Automatic Link Polarity Detection

ADM7001's 10Base-T transceiver module incorporates an “automatic link polarity detection circuit”. The inverted polarity is determined when seven consecutive link pulses of inverted polarity or three consecutive packets are received with inverted end-of-packet pulses. If the input polarity is reversed, the error condition will be automatically corrected and reported in bit 13 of register 11_H.

3.1.16 Clock Synthesizer

The ADM7001 implements a clock synthesizer that generates all the reference clocks needed from a single external frequency source. The clock source must be a TTL level signal at 25 MHz $\pm$ 50ppm.

3.1.17 Auto Negotiation

The Auto Negotiation function provides a mechanism for exchanging configuration information between two ends of a link segment and automatically selecting the highest performance mode of operation supported by both devices. Fast Link Pulse (FLP) Bursts provides the signaling used to communicate auto negotiation abilities between two devices at each end of a link segment. For further detail regarding auto negotiation, refer to Clause 28 of the IEEE 802.3u specification. The ADM7001 supports four different Ethernet protocols, so the inclusion of auto negotiation ensures that the highest performance protocol will be selected based on the ability of the link partner.

The auto negotiation function within the ADM7001 can be controlled either by internal register access or by the use of configuration pins are sampled. If disabled, auto negotiation will not occur until software enables bit 12 in register 0. If auto negotiation is enabled, the negotiation process will commence immediately.

When auto negotiation is enabled, the ADM7001 transmits the abilities programmed into the auto negotiation advertisement register at address 04_H via FLP bursts. Any combination of 10 Mbps, 100 Mbps, half duplex and full duplex modes may be selected. Auto negotiation controls the exchange of configuration information. Upon successfully auto negotiation, the abilities reported by the link partner are stored in the auto negotiation link partner ability register at address 05_H.

The contents of the “auto negotiation link partner ability register” are used to automatically configure to the highest performance protocol between the local and far-end nodes. Software can determine which mode has been configured by auto negotiation by comparing the contents of register 04_H and 05_H and then selecting the technology whose bit is set in both registers of highest priority relative to the following list.

- 100Base-TX full duplex (highest priority)
- 100Base-TX half duplex
- 10Base-T full duplex

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- 10Base-T half duplex (lowest priority)

The basic mode control register at address 0_H provides control of enabling, disabling, and restarting of the auto negotiation function. When auto negotiation is disabled, the speed selection bit (bit 13) controls switching between 10 Mbps or 100 Mbps operation, while the duplex mode bit (bit 8) controls switching between full duplex operation and half duplex operation. The speed selection and duplex mode bits have no effect on the mode of operation when the auto negotiation enable bit (bit 12) is set.

The basic mode status register (BMSR) at address 1_H indicates the set of available abilities for technology types (bit 15 to bit 11), auto negotiation ability (bit 3), and extended register capability (bit 0). These bits are hardwired to indicate the full functionality of the ADM7001. The BMSR also provides status on:

- Whether auto negotiation is complete (bit 5)
- Whether the Link Partner is advertising that a remote fault has occurred (bit 4)
- Whether a valid link has been established (bit 2)

The auto negotiation advertisement register at address 4_H indicates the auto negotiation abilities to be advertised by the ADM7001. All available abilities are transmitted by default, but writing to this register or configuring external pins can suppress any ability.

The auto negotiation link partner ability register at address 05_H indicates the abilities of the Link Partner as indicated by auto negotiation communication. The contents of this register are considered valid when the auto negotiation complete bits (bit 5, register address 1_H and bit 4, register 17_H) are set.

3.1.18 Auto Negotiation and Speed Configuration

The twelve sets of four pins listed in **Table 13** configure the speed capability of each channel of ADM7001. The logic state of these pins is latched into the advertisement register (register address 4_H) for auto negotiation purpose. These pins are also used for evaluating the default value in the base mode control register (register 0_H) according to **Table 13** Channel Configuration.

3.2 MAC Interface

The ADM7001 interfaces to 10/100 Media Access Controllers (MAC) via the RMII, MII, or GPSI Interface.

3.2.1 Reduced Media Independent Interface (RMII)

The reduced media Independent interface (RMII) is compliant to the RMII consortium's RMII Rev. 1.2 specification. The REFCLK pin that supplies the 50 MHz reference clock to the ADM7001 is used as the RMII REFCLK signal. All RMII signals with the exception of the assertion of CRSDV_P are synchronous to REFCLK. See **Figure 5**

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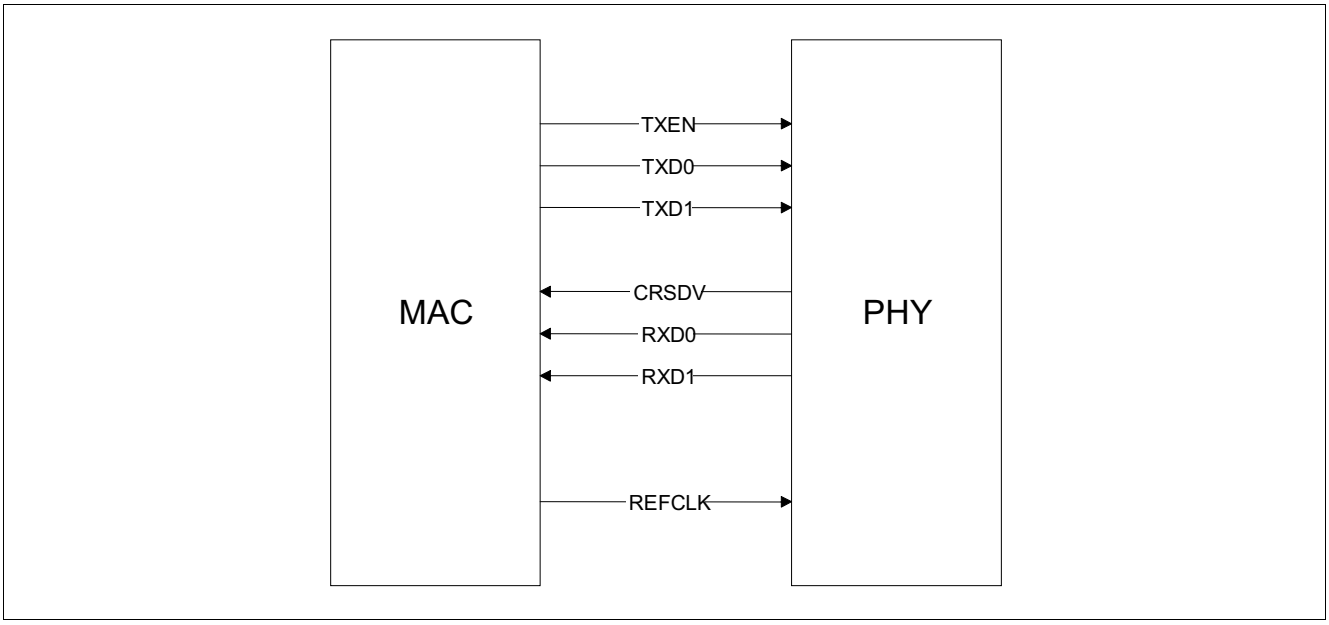

Figure 5 RMII Signal Diagram

3.2.2 Receive Path for 100M

Figure 6 shows the relationship among REFCLK, CRSDV, RXD and RXER while receiving a valid packet. Carrier sense is detected, which causes CRSDV to assert asynchronously to REFCLK. The received data is then placed into the FIFO for resynchronization. After a minimum of 12 bits are placed into the FIFO, the received data is presented onto RXD[1:0] synchronously to REFCLK. Note that while the FIFO is filling up RXD[1:0] is set to 00 until the first received di-bit of preamble (01) is presented onto RXD[1:0]. When carrier sense is de-asserted at the end of a packet, CRSDV is de-asserted when the first di-bit of a nibble is presented onto RXD[1:0] synchronously to REFCLK. If there is still data in the FIFO that has not yet been presented onto RXD[1:0], then on the second di-bit of a nibble, CRSDV reasserts. This pattern of assertion and de-assertion continues until all received data in the FIFO has been presented onto RXD[1:0]. RXER is inactive for the duration of the received valid packet.

Figure 7 shows the relationship among REFCLK, CRSDV and RXD[1:0] during a received false carrier event. CRSDV is asserted asynchronously to REFCLK as in the valid receive case shown in . However, once false carrier is detected, RXD[1:0] is changed to (10) (11) (Value 1110 in MII) and RXER is asserted. Both RXD[1:0] and RXER transition synchronously to REFCLK. After carrier sense is de-asserted, CRSDV is de-asserted synchronously to REFCLK.

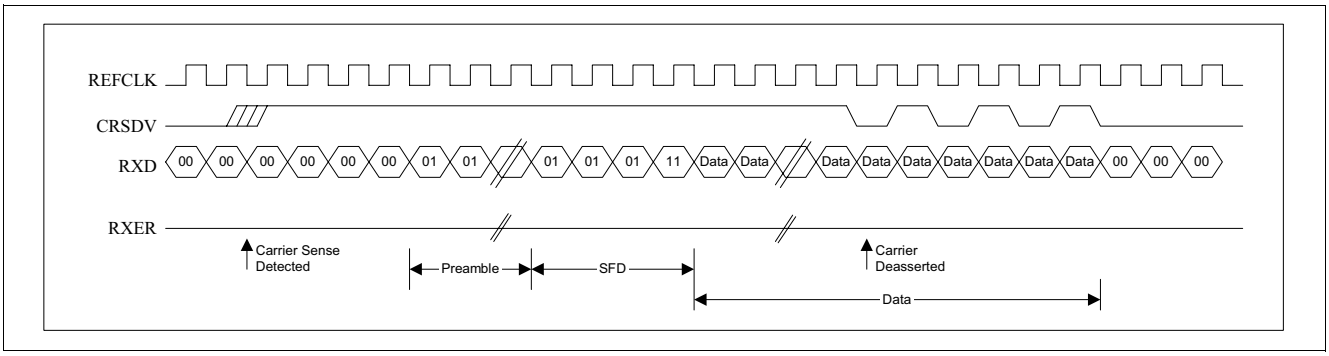

Figure 6 RMII Reception Without Error

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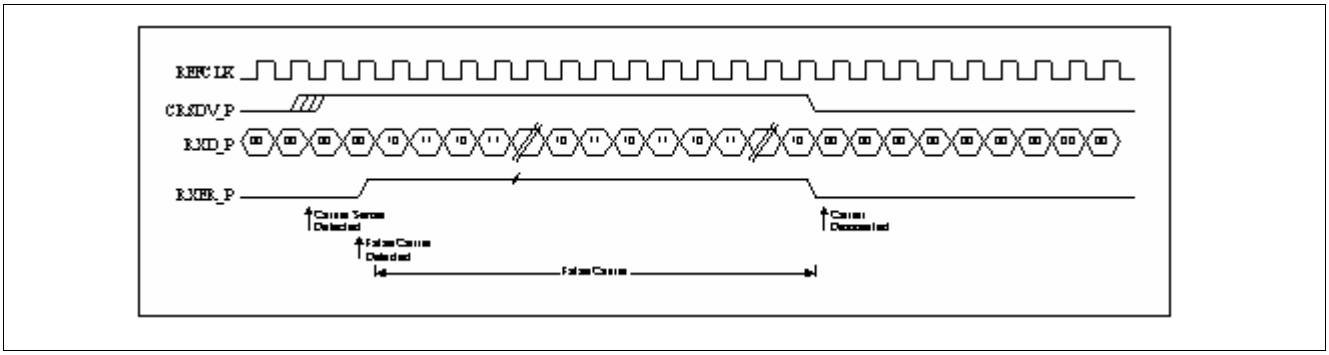

Figure 7 RMII Reception with False Carrier (100M Only)

A receive symbol error event is shown in **Figure 8**. The packet with the symbol error is treated as if it were a valid packet with the exception that all di-bits are substituted with the (01) pattern.

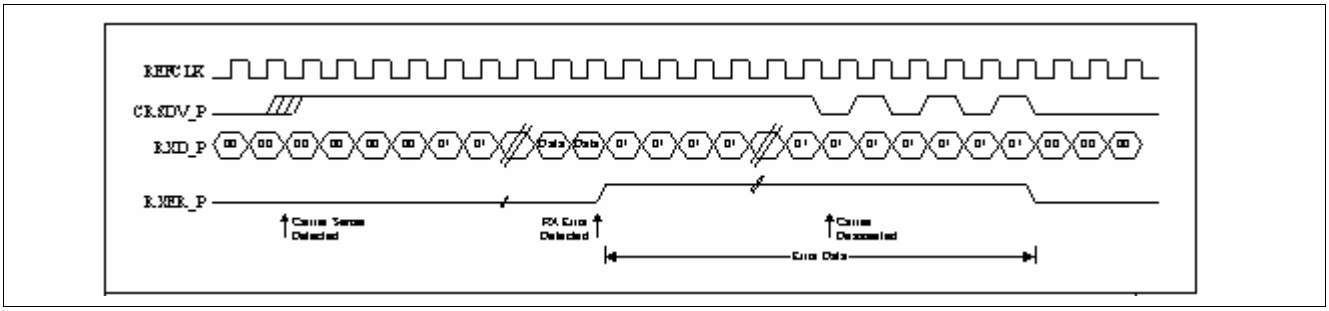

Figure 8 RMII Reception with Symbol Error

3.2.3 Receive Path for 10M

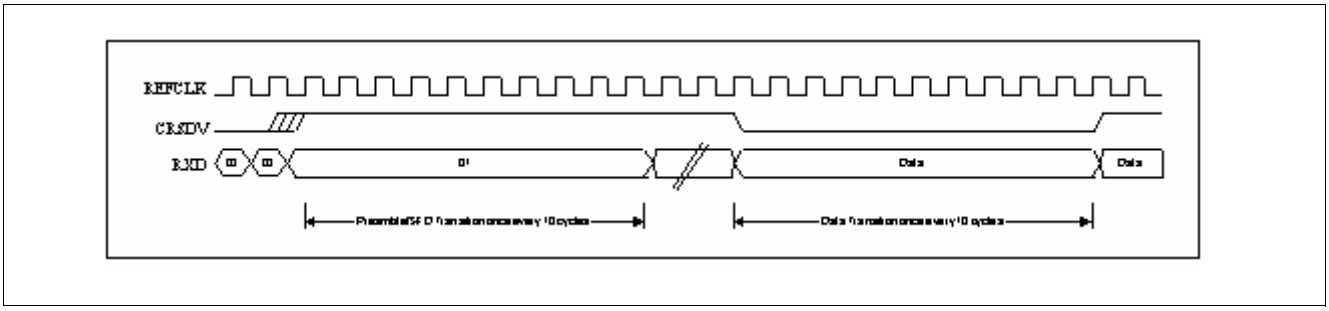

Figure 9 10M RMII Receive Diagram

In 10M Mode, RXER will maintain low all the time due to False Carrier and symbol error is not supported by 10M Mode. Different from 100M mode, RXD and CRSDV can transit once per 10 REFCLK cycles. After carrier sense is de-asserted yet the FIFO data is not fully presented onto RXD, the CRSDV de-assertion and re-assertion also follow this rule.

3.2.4 Transmit Path for 100M

Figure 10 shows the relationship among REFCLK, TXEN and TXD[1:0] during a transmit event. TXEN and TXD[1:0] are synchronous to REFCLK. When TXEN is asserted, it indicates that TXD[1:0] contains valid data to be transmitted. When TXEN is de-asserted, value on TXD[1:0] should be ignored. If an odd number of di-bits are presented onto TXD[1:0] and TXEN, the final di-bit will be discarded by ADM7001.

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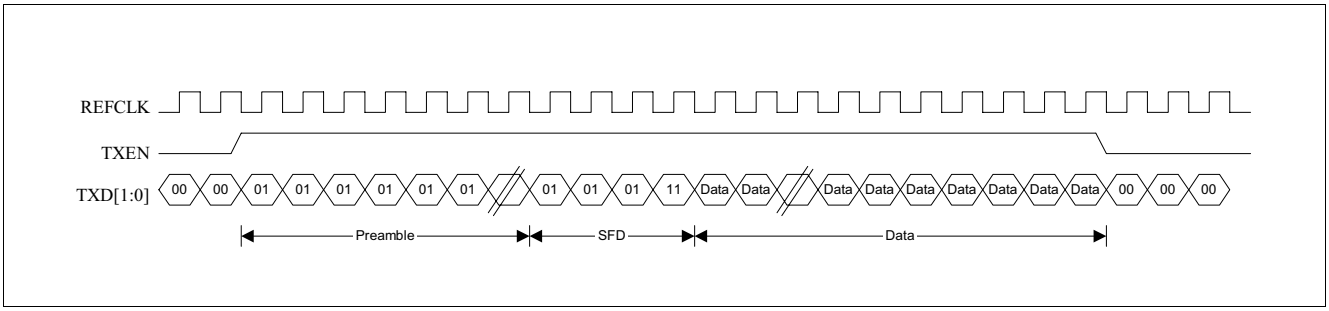

Figure 10 100M RMII Transmit Diagram

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3.2.5 Transmit Path for 10M

In 10MBSE-T mode, each di-bit must be repeated 10 times by the MAC, TXEN and TXD[1:0] should be synchronous to REFCLK. When TXEN is asserted, it indicates that data on TXD[1:0] is valid for transmission.

In 10Base-T mode, it is possible that the number of preamble bits and the number of frame bits received are not integer nibbles. The preamble is always padded up such that the SFD appears on the RMII aligned to the nibble boundary. Extra bits at the end of the frame that do not complete a nibble are truncated by AD7001. **Figure 11** shows the timing diagram for 10M Transmission.

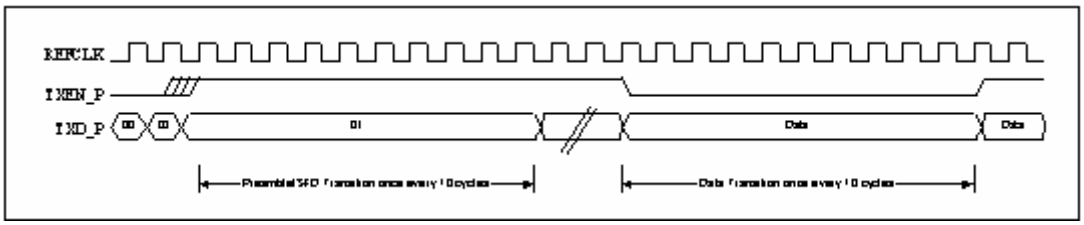

Figure 11 10M RMII Transmit Diagram

Table 13 Channel Configuration

Recommend Value			Auto Negotiation		Capability			
ANENDIS	REC_10M	TP_FULL DUPLEX	Enable	Disable	100 Full	100 Half	10 Full	10 Half
1	1	1	√		√	√	√	√
1	1	0	√			√		√
1	0	1	√				√	√
1	0	0	√					√
0	1	1		√	√			
0	1	0		√		√		
0	0	1		√			√	
0	0	0		√				√

3.2.6 Media Independent Interface (MII)

Signal Diagram for MII interface is shown in **Figure 12**.

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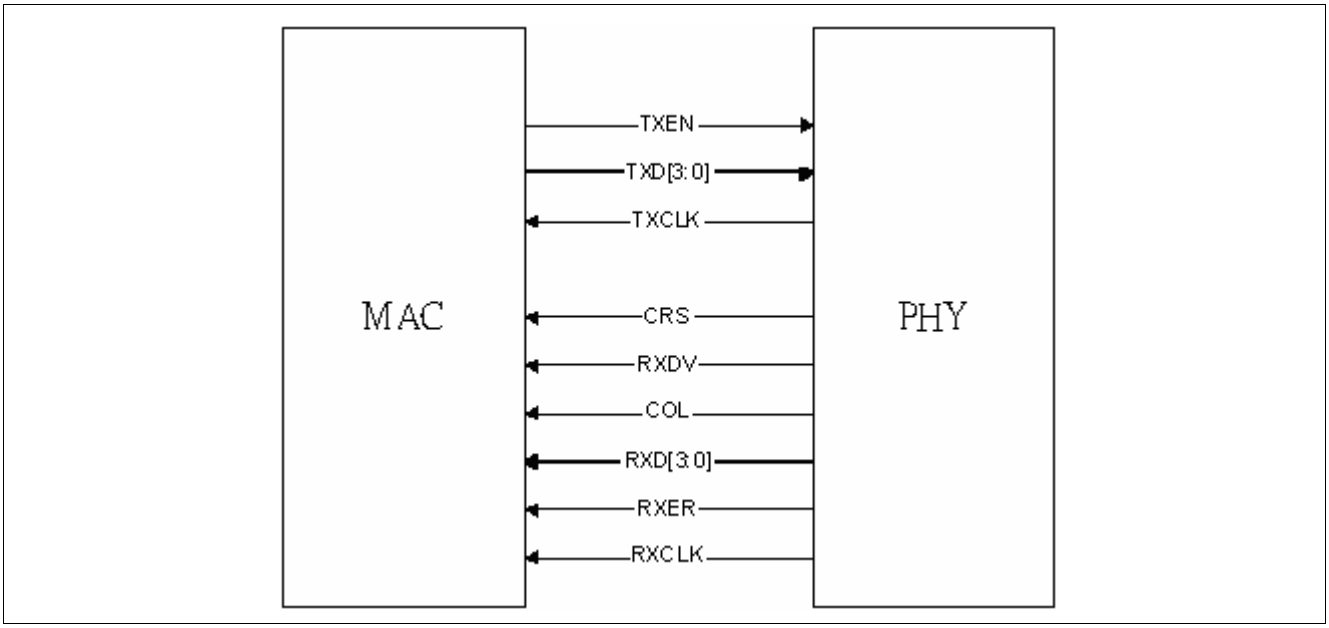

Figure 12 MII Signal Diagram

3.2.7 Receive Path for MII

Figure 13 shows the relationship among RXCLK, RXDV, RXD and CRS during a reception of valid packet. Carrier sense is detected and asserted asynchronously to RXCLK by ADM7001. When ADM7001 detects there is valid data, RXDV and the received data are presented onto RXD[3:0] synchronously to RX_CLK. Whenever received data is not valid anymore, RXDV will be de-asserted by ADM7001 and "0" will be put on RXD[3:0].

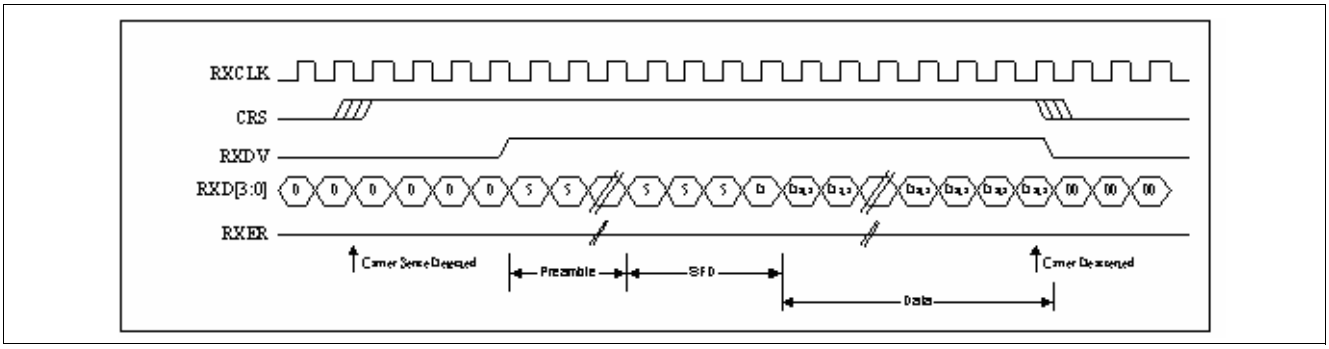

Figure 13 MII Receive Without Error

Figure 14 shows the relationship among RXCLK, RXDV and RXD[3:0] during a received false carrier event. CRS is asserted asynchronously to RXCLK as in the valid receive case shown in **Figure 15**. However, once false carrier is detected, RXD[3:0] is changed to (1110) and RXER is asserted. Both RXD[3:0] and RXER transit synchronously to RXCLK.

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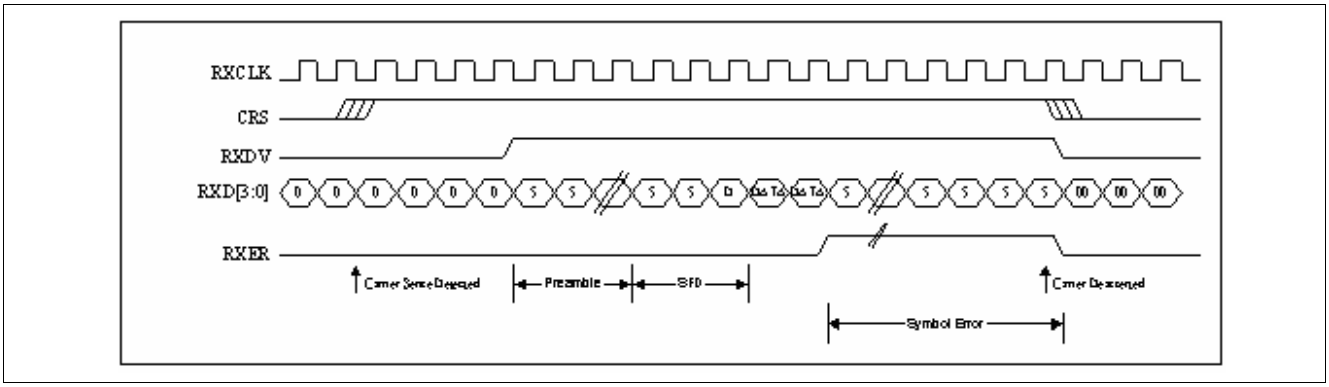

Figure 14 MII Receive With False Carrier

A receive symbol error event is shown in **Figure 15**. The packet with the symbol error is treated as if it were a valid packet with the exception that all bits are substituted with the (0101) pattern. RXER will keep low in 10M Operation.

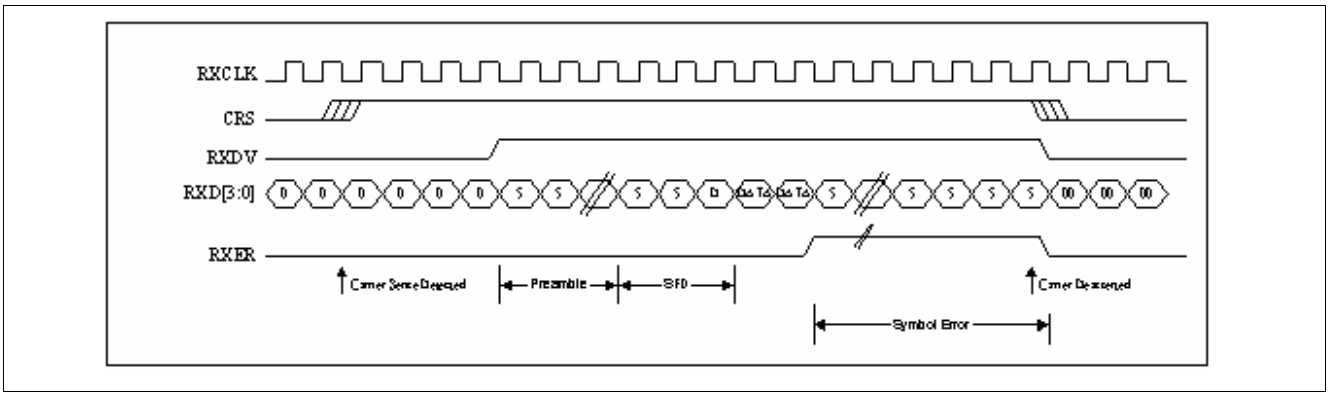

Figure 15 MII Receive With Symbol Error(100M Only)

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3.2.8 Transmit Path for MII

Figure 16 shows the relationship among TXCLK, TXEN and TXD[3:0] during a transmit event. TXEN and TXD[3:0] are synchronous to TXCLK, which is generated by MAC. TXCLK is running at 25M in 100M mode and 2.5M in 10M mode. When TXEN is asserted, it indicates that TXD[3:0] contains valid data to be transmitted. When TXEN is de-asserted, value on TXD[1:0] should be ignored.

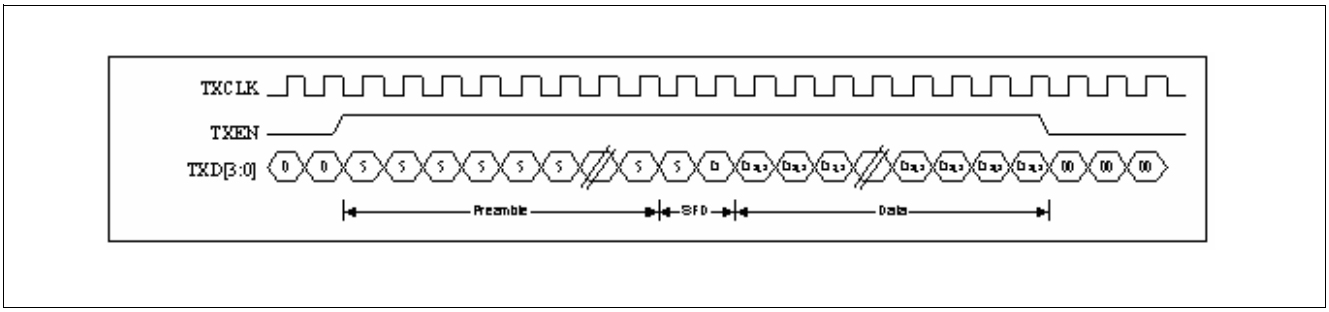

Figure 16 MII Transmission

When ADM7001 operates in half duplex mode, either 10M or 100M, it will assert COL signal whenever it detects there is collision on the medium. Figure 17 shows the timing diagram for MII Collision.

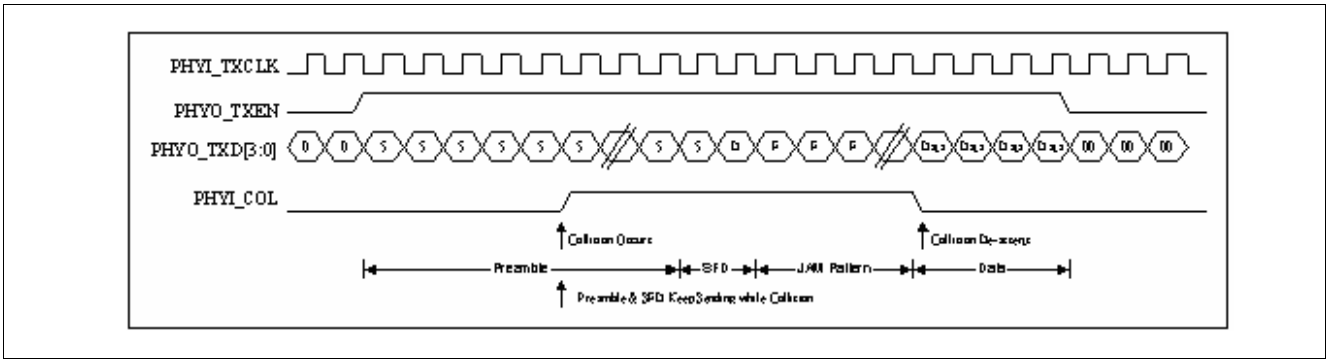

Figure 17 MII Transmit with Collision (Half Duplex Only)

3.2.9 General Purpose Serial Interface (GPSI)

Signal Diagram for MII interface is shown in Figure 18.

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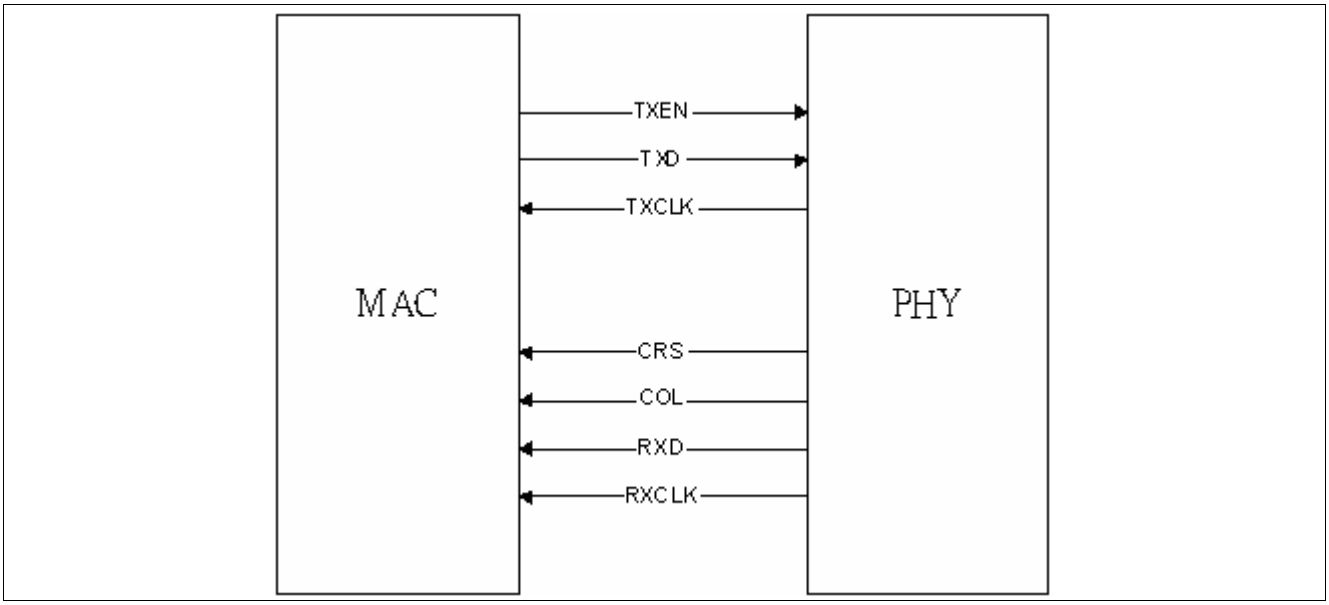

Figure 18 GPSI Signal Diagram

3.2.10 Receive Path for GPSI

Figure 19 shows the relationship among RXCLK, RXD and CRS during a receive of valid packet. Carrier sense is detected and asserted asynchronously to RXCLK by ADM7001. When ADM7001 detects there is valid data, received data is presented onto RXD synchronously to RXCLK. Whenever received data is not valid anymore, CRS will be de-asserted by ADM7001 and "0" will be put on RXD.

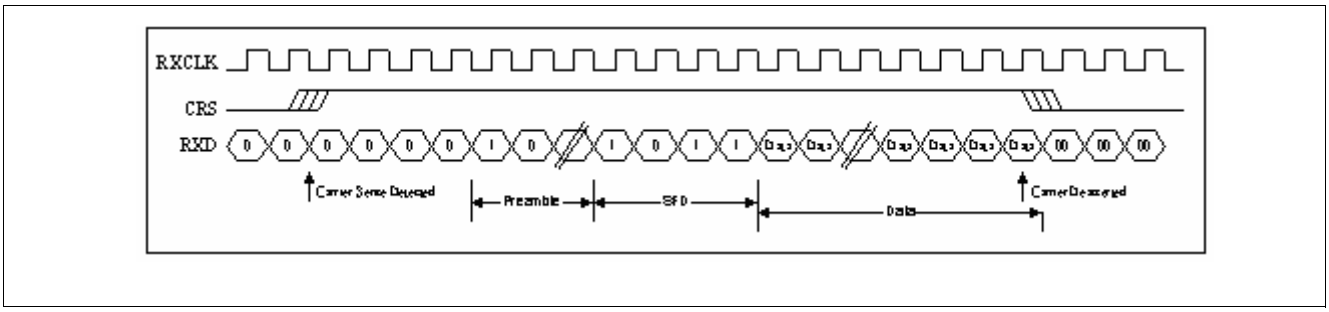

Figure 19 GPSI Receive Diagram

3.2.11 Transmit Path for GPSI

Figure 20 shows the relationship among TXCLK, TXEN and TXD during a transmit event. TXEN and TXD are synchronous to TXCLK, which is generated by MAC. TXCLK is running at 10M in 10M mode. When TXEN is asserted, it indicates that TXD contains valid data to be transmitted. When TXEN is de-asserted, value on TXD should be ignored.

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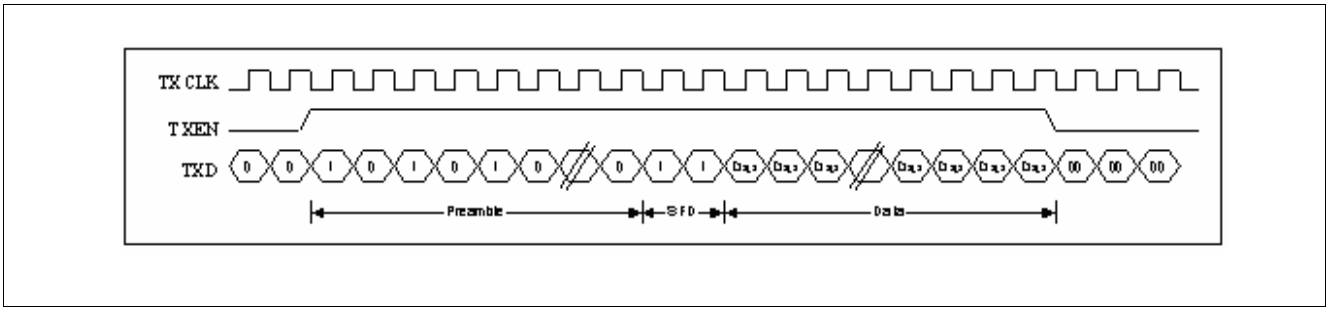

Figure 20 GPSI Transmit Diagram

3.3 LED Display

Register 19 is used for different mode led display. ADM7001 provides power on LED self test to minimize and ease the system test cost.

All LEDs will be Off during power on reset (Output value same as recommend value on LED pins). After power on reset, all internal parallel LEDs will be On for 2 seconds to ease manufacture overhead

There are three types of LED supported by ADM7001 internally. The first is LNKACT, which represents the status of Link and Transmit/Receive Activity, the second is LDSPD, which indicates the speed status, and the last is DUPCOL, which shows pure duplex status in full duplex and duplex/collision combined status in half duplex. All these three LED can be controlled by Register 19 to change display contents.

After LED self test, **Table 14**, **Table 15**,**Table 16** show the On/Off polarity according to different recommended value setting for LDSPD, DUPCOL and LNKACT. When the recommend value is high, ADM7001 will drive LED LOW; ADM7001 will drive the LED HIGH when the recommend value is low, instead.

Table 14 Speed LED Display

SPEED	SPDLED
10M	0
100M	1
LINK FAIL	1

Table 15 Duplex LED Display

DUPLEX	DUPCOL	
	HALF	FULL
LINK UP	Blink (HIGH) When Collision	LOW All the Time
LINK FAIL	HIGH All the Time	HIGH All the Time

Table 16 Activity/Link LED Display

SPEED	Link/Activity	
	Link	Activity
LINK UP	LOW	Blink (HIGH) When RX/TX
LINK FAIL	HIGH All the Time	HIGH All the Time

Besides duplex, speed, link and activity status, ADM7001 also provides cable information that can be shown on LEDs when register 19 is programmed to distance LED display (see **Table 17**)

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Table 17 Cable Distance LED Display

LNKACT	DUPCOL	LEDSPD	Cable Distance
1	1	0	0 to 40 meters
1	0	0	40 to 80 meters
0	0	0	80 to 120 meters
1	1	1	Reserved

3.4 Management Register Access

The SMI consists of two pins, management data clock (MDC) and management data input/output (MDIO). The ADM7001 is designed to support an MDC frequency specified in the IEEE specification of up to 2.5 MHz. The MDIO line is bi-directional and may be shared by up to 32 devices.

The MDIO pin requires a 1.5 KΩ pull-up which, during idle and turnaround periods, will pull MDIO to a logic one state. Each MII management data frame is 64 bits long. The first 32 bits are preamble consisting of 32 contiguous logic one bits on MDIO and 32 corresponding cycles on MDC. Following preamble is the start-of-frame field indicated by a <01> pattern. The next field signals the operation code (OP): <10> indicates read from MII management register operation, and <01> indicates write to MII management register operation. The next two fields are PHY device address and MII management register address. Both of them are 5 bits wide and the most significant bit is transferred first.

During Read operation, a 2-bit turn around (TA) time spacing between the register address field and data field is provided for the MDIO to avoid contention. Following the turnaround time, a 16-bit data stream is read from or written into the MII management registers of the ADM7001

3.4.1 Preamble Suppression

The ADM7001 supports a preamble suppression mode as indicated by an 1 in bit 6 of the basic mode status register (Register 1h). If the station management entity (i.e. MAC or other management controller) determines that all PHYs in the system support preamble suppression by reading a 1 in this bit, then the station management entity needs not to generate preamble for each management transaction. The ADM7001 requires a single initialization sequence of 32 bits of preamble following powerup/hardware reset. This requirement is generally met by pulling-up the resistor of MDIO. While the ADM7001 will respond to management accesses without preamble, a minimum of one idle bit between management transactions is required as specified in IEEE 802.3u.

When ADM7001 detects that there is physical address match, then it will enable Read/Write capability for external access. When neither physical address nor register address is matched, then ADM7001 will tristate the MDIO pin.

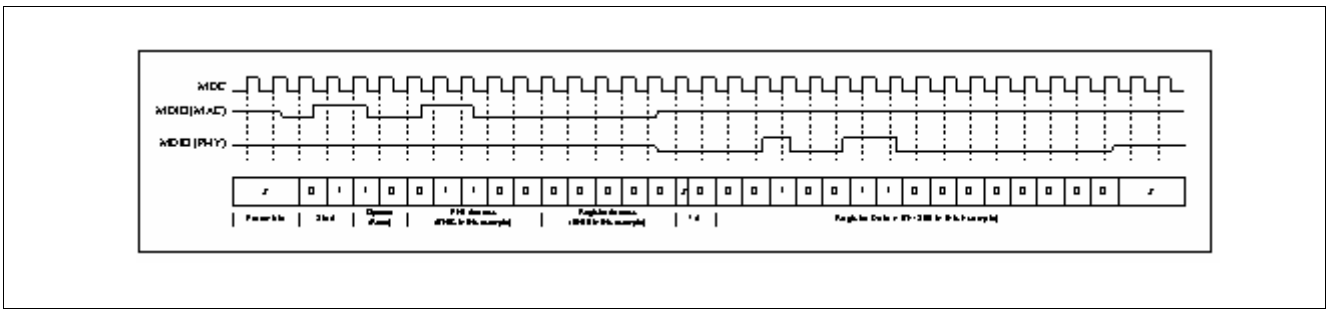

Figure 21 SMII Read Operation

3.4.2 Reset Operation

The ADM7001 can be reset either by hardware or software. A hardware reset is accomplished by applying a negative pulse, with duration of at least 200 ms to the RC pin of the ADM7001 during normal operation to

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guarantee internal Power On Reset Circuit is reset well. Setting the reset bit in the Basic Mode Control activates software reset

Register (bit 15, register 0_H). This bit is self-clearing and, when set, will return a value of 1 until the software reset operation has completed, please note that internal SRAM will not be reset during software reset.

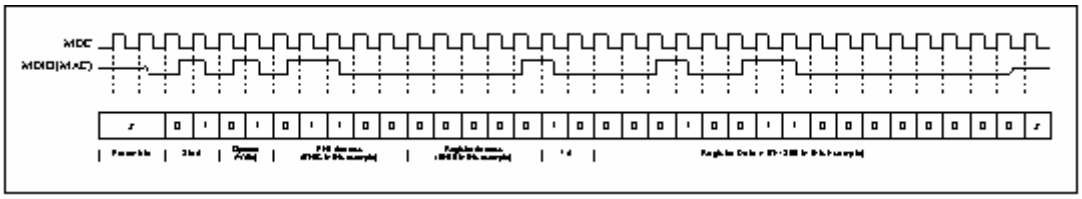

Figure 22 SMII Write Operation

Hardware reset operation samples the pins and initializes all registers to their default values. This process includes re-evaluation of all hardware configurable registers.

A software reset will reset an individual PHY and it does not latch the external pins nor reset the registers to their respective default value.

Logic levels on several I/O pins are detected during a hardware reset to determine the initial functionality of ADM7001. Some of these pins are used as output ports after reset operation.

Care must be taken to ensure that the configuration setup will not interfere with normal operation. Dedicated configuration pins can be tied to VCC or Ground directly. Configuration pins multiplexed with logic level output functions should be either weakly pulled up or weakly pulled down through resistors.

3.5 Power Management

An analog block is designed for carrier sense detecting. When there is no carrier sense presented on medium (cable not attached), then "SIGNAL DETECT" will not be ON. Whenever cable is attached to ADM7001 and the voltage threshold is above +/- 50mV, then SD will be asserted HIGH to indicate that there is cable attached to ADM7001. All internal blocks except Management block will be disabled (reset) before SD is asserted.

When SD is asserted, internal Auto Negotiation block will be turned on and the 10M transmit driver will also be turned on for auto negotiation process. Auto negotiation will issue control signals to control 10M receive and 100M A/D block according to different state in arbitration block diagram. During auto negotiation, all digital blocks except management and link monitor blocks will be disabled to reduce power consumption.

Whenever operating speed is determined (Either auto negotiation is On or Off), the non-active speed relative circuit will be disabled all the time to save more power. For example, when corresponding port is operating on 10M, then 100M relative blocks will be disabled and 10M relative blocks will be disabled whenever corresponding port is in 100M mode. Auto negotiation block will be reset when SD signal goes from high to low. See **Figure 23** for the state diagram for this algorithm.

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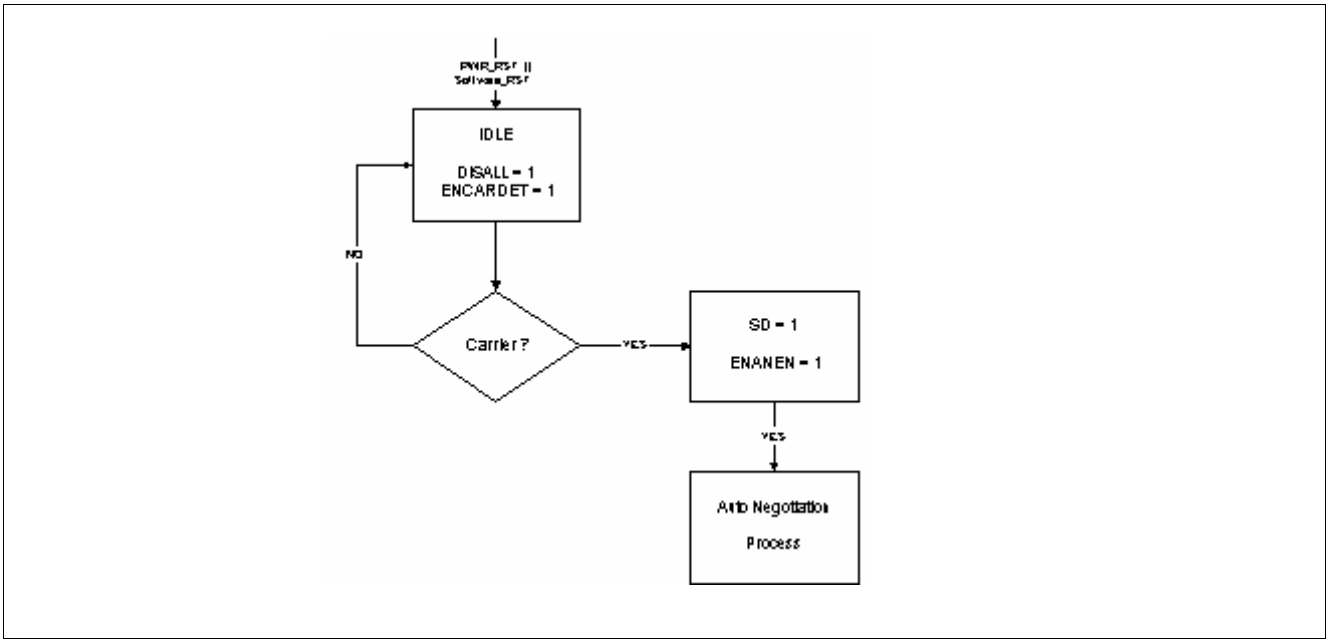

Figure 23 Medium Detect Power Management Flow Chart

Another way to reduce instant power is to separate the LED display period. All 4 LEDs will be divided into 4 time frame and each time frame occupies 1 us. One and only one LED will be driven at each time frame to reduce instant current consumed from LED.

3.6 Voltage Regulator

ADM7001 requires two different levels, 3.3 V and 2.5 V, of voltage supply to provide the power to different parts of circuitry inside the chip. ADM7001 has a build-in voltage regulator circuitry to generate the 2.5 V voltage (VCC25OUT) from 3.3 V power source (VCC3IN). External Application Circuitry is shown in **Figure 24**.

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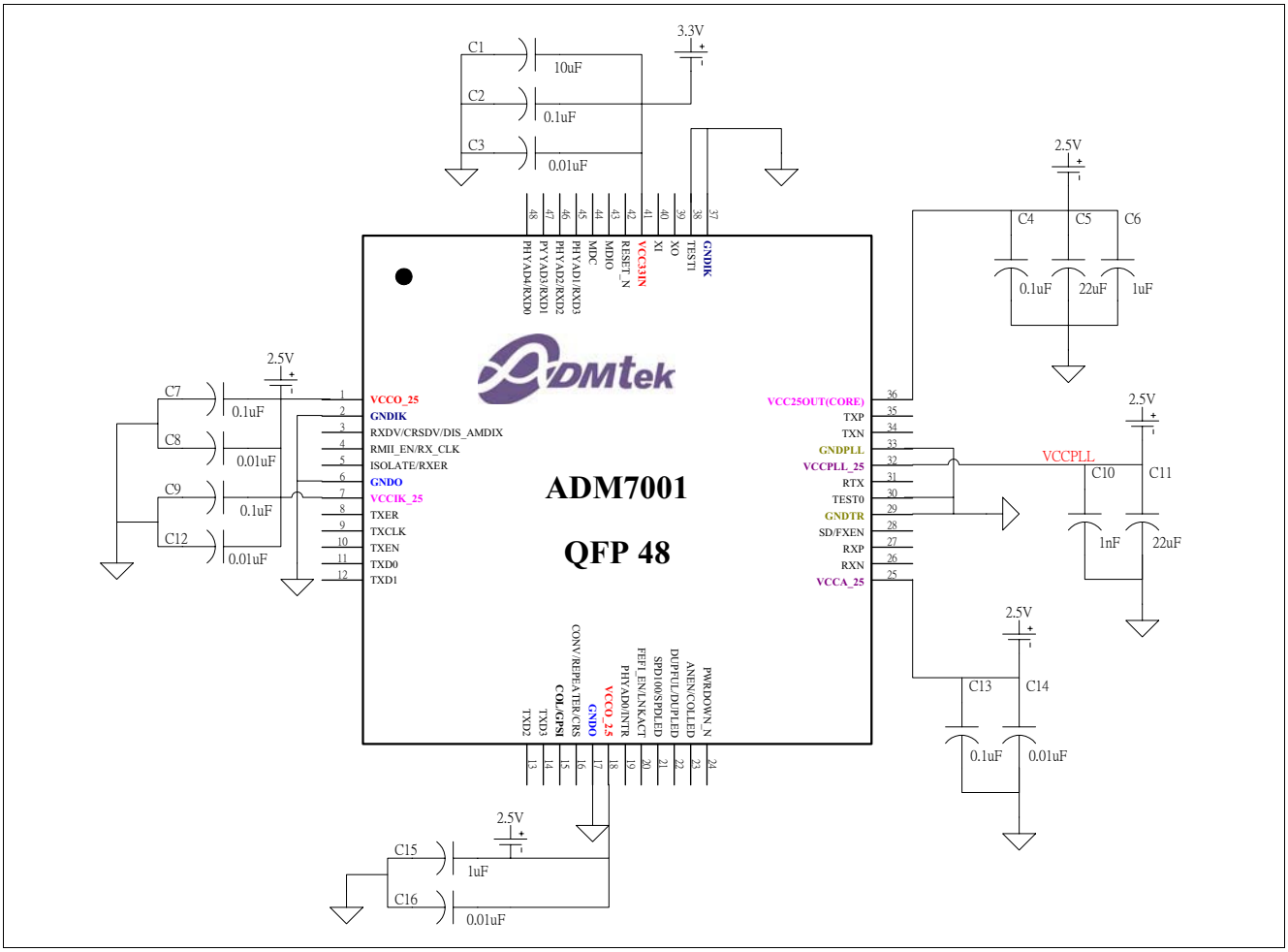

Figure 24 Power and Ground Filtering

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4 Registers Description

Table 18 Registers Address Space

Module	Base Address	End Address	Note
PHY	00_H	$1F_H$	

Table 19 Registers Overview

Register Short Name	Register Long Name	Offset Address	Page Number
CR	Control Register	00_H	49
SR	Status Register	01_H	51
PHY_IR0	PHY Identifier Register 0	02_H	54
PHY_IR1	PHY Identifier Register 1	03_H	54
Advertisement	Auto Negotiation Advertisement Register	04_H	55
ANLPA	Auto Negotiation Link Partner Ability	05_H	56
ANER	Auto Negotiation Expansion Register	06_H	57
Res0	Reserved 0	07_H	58
GPCR	Generic PHY Control/Configuration Register	10_H	59
P10_MCR	PHY 10M Module Configuration Register	11_H	61
P100_MCR	PHY 100M Module Control Register	12_H	63
LCR	LED Configuration Register	13_H	64
IER	Interrupt Enable Register	14_H	66
PGSR	PHY Generic Status Register	16_H	67
PSSR	PHY Specific Status Register	17_H	68
PRVSR	PHY Recommend Value Status Register	18_H	69
ISR	Interrupt Status Register	19_H	70
RECR	Receive Error Counter Register	$1D_H$	71
CIR	Chip ID Register	$1F_H$	72

The register is addressed wordwise.

Table 20 Registers Access Types

Mode	Symbol	Description Hardware (HW)	Description Software (SW)
read/write	rw	Register is used as input for the HW	Register is read and writable by SW
read	r	Register is written by HW (register between input and output -> one cycle delay)	Value written by software is ignored by hardware; that is, software may write any value to this field without affecting hardware behavior (= Target for development.)
write	w		Register is writable by SW
read/write hardware affected	rwh	Register can be modified by HW	Register can be modified by HW, but the priority SW versus HW has to be specified
	rwv		

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Table 20 Registers Access Types (cont'd)

Mode	Symbol	Description Hardware (HW)	Description Software (SW)
Read only	ro	Register is set by HW (register between input and output -> one cycle delay)	SW can only read this register
Read virtual	rv	Physically, there is no new register, the input of the signal is connected directly to the address multiplexer.	SW can only read this register
Latch high, self clearing	lhsc	Latch high signal at high level, clear on read	SW can read the register
Latch low, self clearing	llsc	Latch high signal at low-level, clear on read	SW can read the register
Latch high, mask clearing	lhmk	Latch high signal at high level, register cleared with written mask	SW can read the register, with write mask the register can be cleared (1 clears)
Latch low, mask clearing	llmk	Latch high signal at low-level, register cleared on read	SW can read the register, with write mask the register can be cleared (1 clears)
Interrupt high, self clearing	ihsc	Differentiate the input signal (low->high) register cleared on read	SW can read the register
Interrupt low, self clearing	ilsc	Differentiate the input signal (high->low) register cleared on read	SW can read the register
Interrupt high, mask clearing	ihmk	Differentiate the input signal (high->low) register cleared with written mask	SW can read the register, with write mask the register can be cleared
Interrupt low, mask clearing	ilmk	Differentiate the input signal (low->high) register cleared with written mask	SW can read the register, with write mask the register can be cleared
Interrupt enable register	ien	Enables the interrupt source for interrupt generation	SW can read and write this register
latch_on_reset	lor	rw register, value is latched after first clock cycle after reset	Register is read and writable by SW
Read/write self clearing	rwsc	Register is used as input for the hw, the register will be cleared due to a HW mechanism.	Writing to the register generates a strobe signal for the HW (1 pdi clock cycle) Register is read and writable by SW.

Table 21 Registers Clock Domains

Clock Short Name	Description

4.1 Register Description

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Control Register

CR	Offset	Reset Value
Control Register	00_H	3000_H

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RST	LPBK	SSL	ANEN	PDN	ISO	RAN	DPLX	CT	SSM	Res					
rwsc	rw	rw	rw	rw	rw	rwsc	rw	rw	ro	ro					

Field	Bits	Type	Description
RST	15	rwsc	**RESET** Setting this bit initiates the software reset function that resets the selected port, except for the phase-locked loop circuit. It will re-latch in all hardware configuration pin values. The software reset process takes 25us to complete. This bit, which is self-clearing, returns a value of 1 until the reset process is complete. 0_B **RST_0**, Normal operation 1_B **RST_1**, PHY Reset
LPBK	14	rw	**Back Enable** This bit controls the PHY loop back operation that isolates the network transmitter outputs (TXP and TXN) and routes the MII transmit data to the MII receive data path. This function should only be used when auto negotiation is disabled (bit12 = 0). The specific PHY (10Base-T or 100Base-X) used for this operation is determined by bits 12 and 13. 0_B **LPBK_0**, Disable Loop back mode 1_B **LPBK_1**, Enable loop back mode
SSL	13	rw	**Speed Selection LSB** SPEED_LSB 0.60.13 Link speed is selected by this bit or by auto negotiation if bit 12 of this register is set (in which case, the value of this bit is ignored). 00_B **10M**, 10 Mbit/s 01_B **100M**, 100 Mbit/s 10_B **1000M**, 1000 Mbit/s 11_B **Res**, Reserved
ANEN	12	rw	**Auto Negotiation Enable** This bit determines whether the link speed should set up by the auto negotiation process or not. It is set at power up or reset if the PI_RECANEN pin detects a logic 1 input level in Twisted-Pair Mode. 0_B **ANEN_0**, Disable Auto negotiation process 1_B **ANEN_1**, Enable auto negotiation process

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Field	Bits	Type	Description
PDN	11	rw	**Power Down Enable** Ored result with PI_PWRDN pin. Setting this bit high or asserting the PI_PWRDN puts the PHY841F into power down mode. During the power down mode, TXP/TXN and all LED outputs are tristated and the MII/RMII interfaces are isolated. 0_B **PDN_0**, Normal Operation 1_B **PDN_1**, Power Down
ISO	10	rw	**Isolate PHY841F from Network** Setting this control bit isolates the part from the RMII/MII, with the exception of the serial management interface. When this bit is asserted, the PHY841F does not respond to TXD, TXEN and TXER inputs, and it presents a high impedance on its TXC, RXC, CRSDV, RXER, RXD, COL and CRS outputs. 0_B **ISO_0**, Normal Operation 1_B **ISO_1**, Isolate PHY from MII/RMII
RAN	9	rwsc	**Restart Auto Negotiation** ANEN_RST. Setting this bit while auto negotiation is enabled forces a new auto negotiation process to start. This bit is self-clearing and returns to 0 after the auto negotiation process has commenced. 0_B **RAN_0**, Normal Operation 1_B **RAN_1**, Restart Auto Negotiation Process
DPLX	8	rw	**Duplex Mode** If auto negotiation is disabled, this bit determines the duplex mode for the link. 0_B **DPLX_0**, Half Duplex mode 1_B **DPLX_1**, Full Duplex mode
CT	7	rw	**Collision Test** When set, this bit will cause the COL signal of MII interface to be asserted in response to the assertion of TXEN. 0_B **CT_0**, Disable COL signal test 1_B **CT_1**, Enable COL signal test
SSM	6	ro	**Speed Selection MSB** SPEED_MSB. Set to 0 all the time indicate that the PHY841F does not support 1000 Mbit/s function.
Res	5:0	ro	**Reserved** Not Applicable

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Status Register

SR	Offset	Reset Value
Status Register	01_H	7849_H

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
T4	**TXF**	**TXH**	**TF**	**TH**	**T2**	Res			**SUPR**	**AN_C**	**RFD**	**ANEG**	**LINK**	**JAB**	**XTND**
ro	ro	ro	ro	ro	ro	ro			ro	ro	ro	ro	ro, ll	ro, lh	ro

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Field	Bits	Type	Description
T4	15	ro	**100Base-T4 Capable** Set to 0 all the time to indicate that the PHY841F does not support 100Base-T4.
TXF	14		**100Base-X Full Duplex Capable** Set to 1 all the time to indicate that the PHY841F does support Full Duplex mode.
TXH	13		**100Base-X Half Duplex Capable** Set to 1 all the time to indicate that the PHY841F does support Half Duplex mode
TF	12		**10M Full Duplex Capable** TP: Set to 1 all the time to indicate that the PHY841F does support 10M Full Duplex mode. FX: Set to 0 all the time to indicate that the PHY841F does not support 10M Full Duplex mode
TH	11		**10M Half Duplex Capable** TP: Set to 1 all the time to indicate that the PHY841F does support 10M Half Duplex mode. FX: Set to 0 all the time to indicate that the PHY841F does not support 10M Half Duplex mode
T2	10		**100Base-T2 Capable** Set to 0 all the time to indicate that the PHY841F does not support 100Base-T2.
Res	9:7		**Reserved** Not Applicable
SUPR	6		**MF Preamble Suppression Capable** This bit is hardwired to 1 indicating that the PHY841F accepts management frame without preamble. Minimum 32 preamble bits are required following power-on or hardware reset. One idle bit is required between any two management transactions as per IEEE 802.3u specification.
AN_C	5		**Auto Negotiation Complete** If auto negotiation is enabled, this bit indicates whether the auto negotiation process has been completed or not. Set to 0 all the time when Fiber Mode is selected. 0_B **AN_C_0**, Auto Negotiation process not completed 1_B **AN_C_1**, Auto Negotiation process completed

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Field	Bits	Type	Description
RFD	4	ro	**Remote Fault Detect** This bit is latched to 1 if the RF bit in the auto negotiation link partner ability register (bit 13, register address 05h) is set or the receive channel meets the far end fault indication function criteria. It is unlatched when this register is read. 0_B **RFD_0**, Remote Fault not detected 1_B **RFD_1**, Remote Fault detected
ANEG	3		**Auto Negotiation Ability** TP: This bit is set to 1 all the time, indicating that PHY841F is capable of auto negotiation. FX: This bit is set to 0 all the time, indicating that PHY841F is not capable of auto negotiation in Fiber Mode. 0_B **ANEG_0**, Not capable of auto negotiation 1_B **ANEG_1**, Capable of auto negotiation
LINK	2	ro, llsc	**Link Status** This bit reflects the current state of the link -test-fail state machine. Loss of a valid link causes a 0 latched into this bit. It remains 0 until this register is read by the serial management interface. Whenever Linkup, this bit should be read twice to get link up status 0_B **LINK_0**, Link is down 1_B **LINK_1**, Link is up
JAB	1	ro, lhsc	**Jabber Detect** 0_B **JAB_0**, Jabber condition not detected 1_B **JAB_1**, Jabber condition detected
XTND	0	ro	**Extended Capability** This bit defaults to 1, indicating that the PHY841F implements extended registers. 0_B **XTND_0**, No extended register set 1_B **XTND_1**, Extended register set

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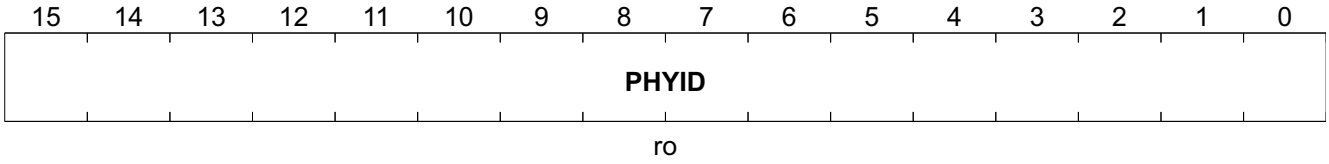
PHY Identifier

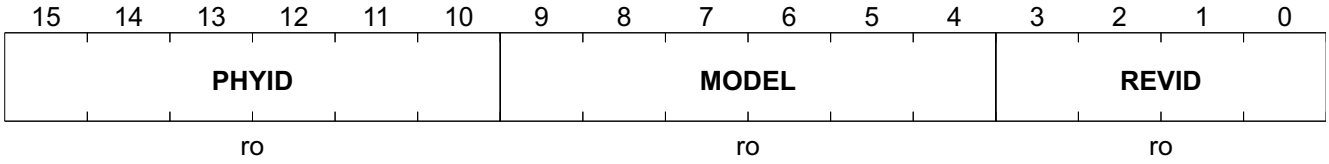
PHY_IR0	Offset	Reset Value
PHY Identifier Register 0	02_H	$002E_H$



Field	Bits	Type	Description
PHYID	15:0	ro	**PHY-ID** IEEE Address

PHY Identifier Register 1

PHY_IR1	Offset	Reset Value
PHY Identifier Register 1	03_H	$CC62_H$



Field	Bits	Type	Description
PHYID	15:10	ro	**PHY-ID 15:0** IEEE Address/Model No./Rev. No.
MODEL	9:4		**MODEL 5:0** ADMTEK PHY Revision ID.
REVID	3:0		**REV-ID 3:0** ADMTEK PHY Revision ID.

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Advertisement	Offset	Reset Value
Auto Negotiation Advertisement Register	04_H	$01E1_H$

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
NP	Res	**RF**	Res	**APD**	**PSE**	**T4**	**TXF**	**TXD**	**TF**	**TD**	**Sel**				
rw	ro	rw	ro	rw	rw	ro	rw	rw	rw	rw	ro				

Field	Bits	Type	Description
NP	15	rw	**Next Page** This bit is defaults to 1, indicating that PHY841F is next page capable.
Res	14	ro	**Reserved** Not Applicable
RF	13	rw	**Remote Fault** This bit is written by serial management interface for the purpose of communicating the remote fault condition to the auto negotiation link partner. 0_B **NRFD**, No remote fault has been detected 1_B **RFD**, Remote Fault has been detected
Res	12	ro	**Reserved** Not Applicable
APD	11	rw	**Asymmetric Pause Direction** Bit[11:10] Capability 00_B **NP**, No Pause 01_B **SP**, Symmetric PAUSE 10_B **AP**, Asymmetric PAUSE toward Link Partner 11_B **BSP**, Both Symmetric PAUSE and Asymmetric PAUSE toward local device
PSE	10	rw	**Pause Operation for Full Duplex** Value on PAUREC will be stored in this bit during power on reset.
T4	9	ro	**Technology Ability for 100Base-T4** Defaults to 0.

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Field	Bits	Type	Description
TXF	8	rw	**100Base-TX Full Duplex** 0_B **NCFDO**, Not capable of 100M Full duplex operation 1_B **CFDO**, Capable of 100M Full duplex operation
TXD	7		**100Base-TX Half Duplex** 0_B **TXD_0**, Not capable of 100M operation 1_B **TXD_1**, Capable of 100M operation
TF	6		**10Base-T Full Duplex** 0_B **TF_0**, Not capable of 10M full duplex operation 1_B **TF_1**, Capable of 10M Full Duplex operation
TD	5		**10Base-T Half Duplex** 0_B **TD_0**, Not capable of 10M operation 1_B **TD_1**, Capable of 10M operation
Sel	4:0	ro	**Selector Field** These 5 bits are hardwired to 00001_B, indicating that the PHY841F supports IEEE 802.3 CSMA/CD.

Auto Negotiation Link Partner Ability

ANLPA	Offset	Reset Value
Auto Negotiation Link Partner Ability	**05_H**	**$01E1_H$**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
NPG	**ACK**	**RF**	Res	**LPAP**	**LPP**	**LPTA**	**TXF**	**TXD**	**TF**	**TD**	**Sel**				
ro	ro	ro	ro	ro	ro	ro	ro	ro	ro	ro			ro		

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Field	Bits	Type	Description
NPG	15	ro	**Next Page** 0_B **NPG_0**, Not capable of next page function 1_B **NPG_1**, Capable of next page function
ACK	14		**Acknowledge** 0_B **ACK_0**, Not acknowledged 1_B **ACK_1**, Link Partner acknowledges reception of the ability data word
RF	13		**Remote Fault** 0_B **RF_0**, No remote fault has been detected 1_B **RF_1**, Remote Fault has been detected
Res	12		**Reserved** Not Applicable
LPAP	11		**Link Partner Asymmetric Pause Direction**
LPP	10		**Link Partner Pause Capability** Value on PAUREC will be stored in this bit during power on reset.
LPTA	9		**Link Partner Technology Ability for 100Base-T4** Defaults to 0.
TXF	8		**100Base-TX Full Duplex** 0_B **TXF_0**, Not capable of 100M Full duplex operation 1_B **TXF_1**, Capable of 100M Full duplex operation
TXD	7		**100Base-TX Half Duplex** 1_B **TXD_1**, Capable of 100M operation 0_B **TXD_2**, Not capable of 100M operation
TF	6		**10Base-T Full Duplex** 1_B **TF_1**, Capable of 10M Full Duplex operation 0_B **TF_0**, Not capable of 10M full duplex operation
TD	5		**10Base-T Half Duplex** 1_B **TD_1**, Capable of 10M operation 0_B **TD_0**, Not capable of 10M operation
Sel	4:0		**Encoding Definitions**

Auto Negotiation Expansion Register

ANER	**Offset**	**Reset Value**
Auto Negotiation Expansion Register	**06_H**	**0000_H**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Res											**PFLT**	**LPNP**	**NXPG**	**PRCV**	**LPAN**
ro											ro, lh	ro	ro	ro, lh	ro

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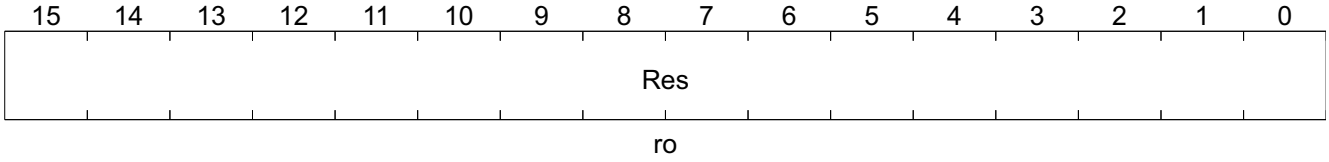
Field	Bits	Type	Description
Res	15:5	ro	**Reserved** Not Applicable
PFLT	4	ro, lhsc	**Parallel Detection Fault** 0_B **PFLT_0**, No Fault Detect 1_B **PFLT_1**, Fault has been detected
LPNP	3	ro	**Link Partner Next Page Able** 0_B **LPNP_0**, Link Partner is not next page capable 1_B **LPNP_1**, Link Partner is next page capable
NXPG	2		**Next Page Able** 1_B **NXPG_1**, Next page Enable. 0_B **NXPG_0**, Next page Disable
PRCV	1	ro, lhsc	**Page Received** 0_B **PRCV_0**, No new page has been received 1_B **PRCV_1**, A new page has been received
LPAN	0	ro	**Link Partner Auto Negotiation Able** 0_B **LPAN_0**, Link Partner is not auto negotiable 1_B **LPAN_1**, Link Partner is auto negotiable

Reserved 0

Res0 **Offset** **Reset Value**

Reserved 0 **07_H** **Reserved$_H$**



Field	Bits	Type	Description
Res	15:0	ro	**Reserved** Not Applicable

Table 22 Reserved Registers

Register Short Name	Register Long Name	Offset Address
Res1	Reserved 1	08_H
Res2	Reserved 2	09_H
Res3	Reserved 3	$0A_H$
Res4	Reserved 4	$0B_H$
Res5	Reserved 5	$0C_H$
Res6	Reserved 6	$0D_H$

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Table 22 Reserved Registers (cont'd)

Register Short Name	Register Long Name	Offset Address
Res7	Reserved 7	$0E_H$
Res8	Reserved 8	$0F_H$
Res9	Reserved 9	15_H
Res10	Reserved 10	$1A_H$
Res11	Reserved 11	$1B_H$
Res12	Reserved 12	$1C_H$
Res 13	Reserved 13	$1E_H$

Generic PHY Control/Configuration Register

Note: PHY Control/Configuration Registers start from address 16 to 21.

GPCR	Offset	Reset Value
Generic PHY Control/Configuration Register	**10_H**	**1000_H**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
IFSEL		**LBKMD**		Res		**FLT**	**Conv**	Res			**XOVEN**	Res		**En8**	**DPMG**
ro		rw		ro		rw	rw	ro			rw	rw		rw	rw

Field	Bits	Type	Description
IFSEL	15:14	ro	**Interface Select.** Value on RMII_EN and GPSI will be stored in IFSEL[1] and IFSEL[0], respectively 00_B , MII 01_B , GPSI $1x_B$, RMII
LBKMD	13:12	rw	**Loop Back Mode Select.** When 0.14 LPBK is set to 1, these two bits are set to 01 by default. Value on these two bits can be modified through MDC/MDIO. When 0.14 LPBK is set to 0, these two bits are reset to 00 and can't be updated by MDC/MDIO. *Note: Both 10M and 100M loopback should be covered by AD2106.* 00_B , Disable Loop back 01_B , PCS Layer Loop back mode 10_B , PMA Layer Loop back mode 11_B , PMD layer loop back mode
Res	11:10	ro	**Reserved** Not Applicable
FLT	9	rw	**Enable called output remote fault status** 0_B **FLT_0**, Disable. 1_B **FLT_1**, Enable.

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Field	Bits	Type	Description
Conv	8	rw	**Converter mode (only valid in rmii mode)** 0_B **Conv_0**, Normal Mode 1_B **Conv_1**, converter mode
Res	7:5	ro	**Reserved** Not Applicable
XOVEN	4	rw	**Cross Over Auto Detect Enable** 0_B **XOVEN_0**, Disable. 1_B **XOVEN_1**, Enable.
Res	3:2	rw	**ADMtek reserved bits.** Writing value other than 0 to these two bits may cause abnormal operation.
En8	1	rw	**Enable Register 8 to Store Next Page Information.** 0_B **En8_0**, Store Next Page in Register 5. 1_B **En8_1**, Store Next Page in Register 8
DPMG	0	rw	**Disable Power Management Feature** 0_B **DPMG_0**, Enable. Enable Medium Detect Function. 1_B **DPMG_1**, Disable. Medium_On is high all the time.

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PHY 10M Module Configuration Register

P10_MCR	Offset	Reset Value
PHY 10M Module Configuration Register	11_H	0008_H

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Res	**SMS**	Res	Res		**ITCE**	Res	Res			Res	**APD**	**RJM**	**TJD**	**NTH**	**FRL**
ro	rw	rw	rw		rw	rw	rw			rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
Res	15	ro	**Reserved** Not Applicable

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Field	Bits	Type	Description
SMS	14	rw	**10BASE-T Serial Mode Select.** Only available when AD2106 works in 10M mode. 0_B **SMS_0**, 10M MII or RMII mode (According to RMII_EN) 1_B **SMS_1**, 10M Serial Mode (Seven Wire Mode)
Res	13		**ADMtek reserved bits.** Writing value other than 1 to this bit may cause abnormal operation.
Res	12:11		**ADMtek reserved bits.** Writing value other than 0 to these two bits may cause abnormal operation.
ITCE	10		**Polarity Interval Timer Check Enable.** 0_B **ITCE_0**, Disable 1_B **ITCE_1**, Enable
Res	9		**ADMtek reserved bits.** Writing value other than 1 to this bit may cause abnormal operation.
Res	8:6		**ADMtek reserved bits.** Writing value other than 5 to these three bits may cause abnormal operation.
Res	5		**ADMtek reserved bits.** Writing value other than 1 to this bit may cause abnormal operation.
APD	4		**Auto Polarity Disable** 0_B **APD_0**, Normal 1_B **APD_1**, Disable
RJM	3		**Enable Receive Jabber Monitor** 0_B **RJM_0**, Disable 1_B **RJM_1**, Enable
TJD	2		**Disable Transmit Jabber** 0_B **TJD_0**, Enable Transmit Jabber Function 1_B **TJD_1**, Disable Transmit Jabber Function
NTH	1		**Normal Threshold** 0_B **NTH_0**, Lower 10BASE-T Receive threshold 1_B **NTH_1**, Normal 10BASE-T Receive threshold
FRL	0		**Force 10M Receive Good Link.** 0_B **FRL_0**, Normal Operation 1_B **FRL_1**, Force Good Link

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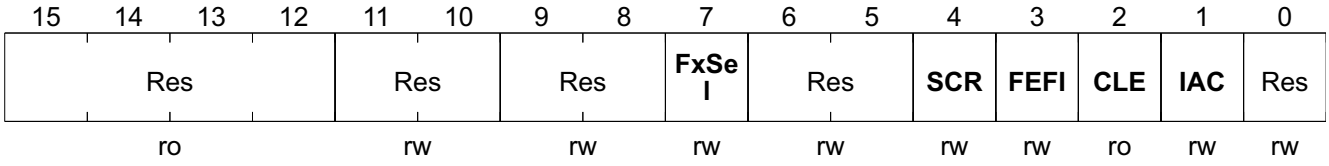
PHY 100M Module Control Register

P100_MCR	Offset	Reset Value
PHY 100M Module Control Register	12_H	0022_H



Field	Bits	Type	Description
Res	15:12	ro	**Reserved** Not Applicable
Res	11:10	rw	**ADMtek reserved bits.** Writing value other than 0 to these two bits may cause abnormal operation.
Res	9:8		**ADMtek reserved bits.** Writing value other than 0 to these two bits may cause abnormal operation.
FxSel	7		**Fiber Select.** 0_B **SelFX_0**, TP Mode 1_B **SelFX_1**, Fiber Mode
Res	6:5		**ADMtek reserved bits.** Writing value other than 0 to these two bits may cause abnormal operation.
SCR	4		**Disable Scrambler** When set to fiber mode, this bit will be forced to 1 automatically. Write 0 to this bit in Fiber Mode has no effect. 0_B **SCR_0**, Enable 1_B **SCR_1**, Disable
FEFI	3		**Enable FEFI** 0_B **FEFI_0**, Disable 1_B **FEFI_1**, Enable
CLE	2	ro	**Disable cable length led indication** When this bit is set to 0, SPDLED, COLLED and LNKACTLED are used to represent twisted pair cable length. See SPDLED description for more detail 0_B **CLE_0**, Enable cable length led 1_B **CLE_1**, Disable cable length led
IAC	1	rw	**Interrupt active value control** 0_B **IAC_0**, Active low 1_B **IAC_1**, Active high
Res	0		**ADMtek reserved bits.** Writing value other than 0 to this bit may cause abnormal operation.

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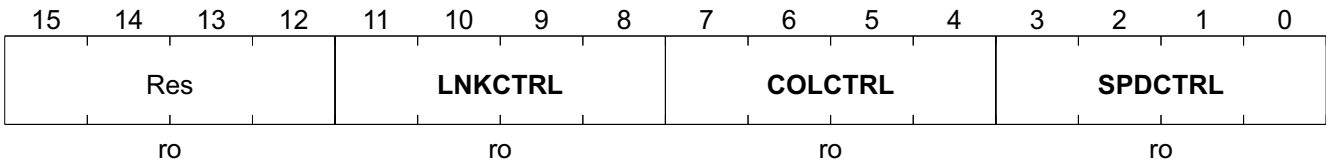
LED Configuration Register

LCR	Offset	Reset Value
LED Configuration Register	13_H	$0A34_H$



Field	Bits	Type	Description
Res	15:12	ro	**Reserved** Not Applicable
LNKCTRL	11:8	ro	**Link/Act LED Control** 0000_B, Collision 0001_B, All Errors 0010_B, Duplex 0011_B, Duplex/Collision 0100_B, Speed 0101_B, Link 0110_B, Transmit Activity 0111_B, Receive Activity 1000_B, TX/RX Activity 1001_B, Link/Receive Activity 1010_B, Link and TX/RX Activity 1011_B, 100M False Carrier Error/10M Receive Jabber 1100_B, 100M Error End of Stream/10M Transmit Jabber 1101_B, Reserved 1110_B, Distance (See LED Description for more detail)
COLCTRL	7:4	ro	**COLLISION LED Control** 0000_B, Collision 0001_B, All Errors 0010_B, Duplex 0011_B, Duplex/Collision 0100_B, Speed 0101_B, Link 0110_B, Transmit Activity 0111_B, Receive Activity 1000_B, TX/RX Activity 1001_B, Link/Receive Activity 1010_B, Link and TX/RX Activity 1011_B, 100M False Carrier Error/10M Receive Jabber 1100_B, 100M Error End of Stream/10M Transmit Jabber 1101_B, Reserved 1110_B, Distance (See LED Description for more detail)

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Field	Bits	Type	Description
SPDCTRL	3:0	ro	**Speed LED Control** 0000_B, Collision 0001_B, All Errors 0010_B, Duplex 0011_B, Duplex/Collision 0100_B, Speed 0101_B, Link 0110_B, Transmit Activity 0111_B, Receive Activity 1000_B, TX/RX Activity 1001_B, Link/Receive Activity 1010_B, Link and TX/RX Activity 1011_B, 100M False Carrier Error/10M Receive Jabber 1100_B, 100M Error End of Stream/10M Transmit Jabber 1101_B, Reserved 1110_B, Distance (See LED Description for more detail)

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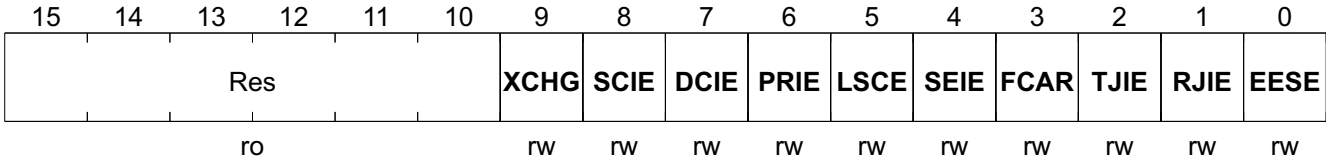
Interrupt Enable Register

IER	Offset	Reset Value
Interrupt Enable Register	14_H	$03FF_H$



Field	Bits	Type	Description
Res	15:10	ro	**Reserved** Not Applicable
XCHG	9	rw	**Cross Over mode Changed Interrupt Enable** 0_B **XCHG_0**, Interrupt Disable 1_B **XCHG_1**, Interrupt Enable
SCIE	8		**Speed Changed Interrupt Enable** 0_B **SCIE_0**, Interrupt Disable 1_B **SCIE_1**, Interrupt Enable
DCIE	7		**Duplex Changed Interrupt Enable** 0_B **DCIE_0**, Interrupt Disable 1_B **DCIE_1**, Interrupt Enable
PRIE	6		**Page Received Interrupt Enable** 0_B **PRIE_0**, Interrupt Disable 1_B **PRIE_1**, Interrupt Enable
LSCE	5		**Link Status Changed Interrupt Enable** 0_B **LSCE_0**, Interrupt Disable 1_B **LSCE_1**, Interrupt Enable
SEIE	4		**Symbol Error Interrupt Enable** 0_B **SEIE_0**, Interrupt Disable 1_B **SEIE_1**, Interrupt Enable
FCAR	3		**False Carrier Interrupt Enable** 0_B **FCAR_0**, Interrupt Disable 1_B **FCAR_1**, Interrupt Enable
TJIE	2		**Transmit Jabber Interrupt Enable** 0_B **TJIE_0**, Interrupt Disable 1_B **TJIE_1**, Interrupt Enable
RJIE	1		**Receive Jabber Interrupt Enable** 0_B **RJIE_0**, Interrupt Disable 1_B **RJIE_1**, Interrupt Enable
EESE	0		**Error End of Stream Enable** 0_B **EESE_0**, Interrupt Disable 1_B **EESE_1**, Interrupt Enable

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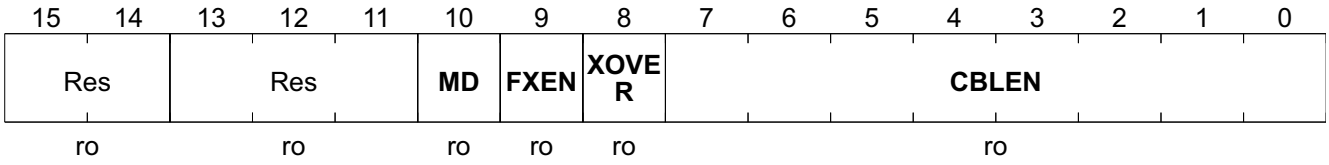
PHY Generic Status Register

Note: PHY Status Registers start from 22 to 28 (29 to 30 reserves for further use)

PGSR	Offset	Reset Value
PHY Generic Status Register	16_H	0000_H



Field	Bits	Type	Description
Res	15:14	ro	**Reserved** Not Applicable
Res	13:11		**Reserved** Not Applicable
MD	10		**Medium Detect** Real Time Status for Medium Detect Signal. 0_B **MD_0**, Medium_Detect Fail 1_B **MD_1**, Medium_Detect Pass
FXEN	9		**Fiber Enable** Only Changed when PHY Reset. OR'ed result of PI_SELFX and 17.9 (SELFX) 0_B **FXEN_0**, TX mode 1_B **FXEN_1**, FX mode
XOVER	8		**Cross Over Status** 0_B **XOVS_0**, MDI mode 1_B **XOVS_1**, MDIX mode
CBLEN	7:0		**Cable Length.** Only valid for 100M MSB is IC0 $1a_H$, 40 meters 22_H , 60 meters 94_H , 80 meters $9a_H$, 100 meters $a2_H$, 120 meters ab_H , 140 meters

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PHY Specific Status Register

PSSR	Offset	Reset Value
PHY Specific Status Register	17_H	0060_H

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Res				JRX	JTX	POL	POUT	PIN	DUP	SPD	LINK	RPAU	RDUP	RSPD	RANV
ro				ro	ro	ro	ro	ro	ro	ro	ro	ro	ro	ro	ro

Field	Bits	Type	Description
Res	15:12	ro	**Reserved** Not Applicable
JRX	11		**Real Time 10M Receive Jabber Status** 0_B **JRX_0**, No jabber 1_B **JRX_1**, Jabber
JTX	10		**Real Time 10M Transmit Jabber Status** 0_B **JTX_0**, No Jabber 1_B **JTX_1**, Jabber
POL	9		**Polarity** Only available in 10M. 0_B **POL_0**, Normal Polarity 1_B **POL_1**, Polarity Reversed
POUT	8		**Pause Out Capability** Disabled when Half Duplex. 0_B **POUT_0**, Lack of Pause Out capability 1_B **POUT_1**, Has Pause Out capability
PIN	7		**Pause In Capability** Disabled when Half Duplex. 0_B **PIN_0**, Has Pause In capability 1_B **PIN_1**, Lack of Pause In capability
DUP	6		**Operating Duplex** 0_B **DUP_0**, Half Duplex 1_B **DUP_1**, Full Duplex
SPD	5		**Operating Speed** 0_B **SPD_0**, 10Mb/s 1_B **SPD_1**, 100Mb/s
LINK	4		**Real Time Link Status** 0_B **LINK_0**, Link Down 1_B **LINK_1**, Link Up
RPAU	3		**Pause Recommend Value** Only Changed when PHY Reset. This bit is disabled automatically when RDUP is 0. 0_B **RPAU_0**, Pause Disable 1_B **RPAU_1**, Pause Enable

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Field	Bits	Type	Description
RDUP	2	ro	**Duplex Recommended Value** Only Changed when PHY Reset. 0_B **RDUP_0**, Half Duplex 1_B **RDUP_1**, Full Duplex
RSPD	1		**Speed Recommend Value** Only Changed when PHY Reset. 0_B **RSPD_0**, 10M 1_B **RSPD_1**, 100M
RANV	0		**Recommended Auto Negotiation Value** Only Changed when PHY Reset.

PHY Recommend Value Status Register

PRVSR	Offset	Reset Value
PHY Recommend Value Status Register	**18_H**	**0000_H**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Res	**RANV**	**FSEL**	**RSPD**	**RDUP**	**PREC**	**FEFD**	**XOVR**	**XOVS**	**RSII**	**RM**	**PHYA**				
ro	ro	ro	ro	ro	ro	ro	ro	ro	ro	ro	ro				

Field	Bits	Type	Description
Res	15	ro	**Reserved** Not Applicable
RANV	14		**Auto Negotiation Recommend Value**
FSEL	13		**Fiber Select Recommend Value**
RSPD	12		**Speed Recommend Value** 0_B **RSPD_1**, 10M 1_B **RSPD_0**, 100M
RDUP	11		**Duplex Recommend Value** 0_B **RDUP_0**, Half Duplex 1_B **RDUP_1**, Full Duplex
PREC	10		**Pause Capability Recommend Value** 0_B **PREC_0**, Pause Disable 1_B **PREC_1**, Pause Enable
FEFD	9		**Far End Fault Disable** 0_B **FEFD_0**, Enable 1_B **FEFD_1**, Disable
XOVR	8		**Cross Over Capability Recommend Value** 0_B **XOVR_0**, Disable 1_B **XOVR_1**, Enable
XOVS	7		**Cross Over Status** 0_B **XOVS_0**, Non-Cross Over 1_B **XOVS_1**, Cross Over

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Field	Bits	Type	Description
RSII	6	ro	**RMII_SMII Interface** 0_B **RSII_0**, Non RMII_SMII Interface 1_B **RSII_1**, RMII or SMII Interface used
RM	5		**Repeater Mode Recommend Value** 0_B **RM_0**, NIC/SW 1_B **RM_1**, Repeater
PHYA	4:0		**PHY Address**

Interrupt Status Register

ISR	Offset	Reset Value
Interrupt Status Register	**19_H**	**0000_H**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Res						**XOVC**	**SPDC**	**DUPC**	**PREC**	**LNKC**	**SERR**	**FCAR**	**TJAB**	**RJAB**	**STRE**
cor						cor	cor	cor	cor	cor	cor	cor	cor	cor	cor

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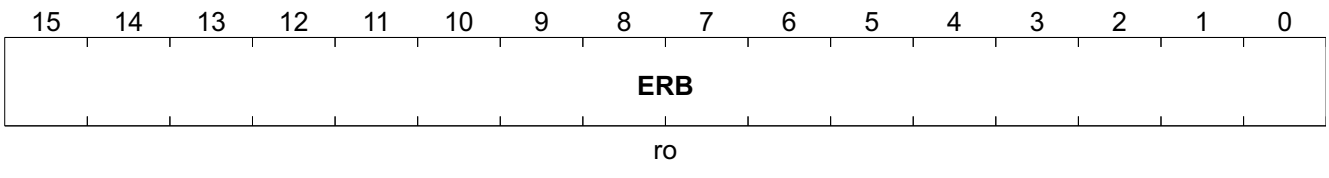
Field	Bits	Type	Description
Res	15:10	cor	**Reserved** Not Applicable
XOVC	9		**Cross Over mode Changed** 0_B **XOVC_0**, Cross Over mode Not Changed 1_B **XOVC_1**, Cross Over mode Changed
SPDC	8		**Speed Changed** 0_B **SPDC_0**, Speed Not Changed 1_B **SPDC_1**, Speed Changed
DUPC	7		**Duplex Changed** 0_B **DUPC_0**, Duplex not changed 1_B **DUPC_1**, Duplex Changed
PREC	6		**Page Received** 0_B **PREC_0**, Page not received 1_B **PREC_1**, Page Received
LNKC	5		**Link Status Changed** 0_B **LNKC_0**, Link Status not Changed 1_B **LNKC_1**, Link Status Changed
SERR	4		**Symbol Error** 0_B **SERR_0**, No symbol Error 1_B **SERR_1**, Symbol Error
FCAR	3		**False Carrier** *Note: High whenever Link is Failed* 0_B **FCAR_0**, No false carrier 1_B **FCAR_1**, False Carrier
TJAB	2		**Transmit Jabber** 0_B **TJAB_0**, No Jabber 1_B **TJAB_1**, Jabber
RJAB	1		**Receive Jabber** 0_B **RJAB_0**, No Jabber 1_B **RJAB_1**, Jabber
STRE	0		**Error End of Stream** 0_B **STRE_0**, No ESD Error 1_B **STRE_1**, ESD Error

Receive Error Counter Register

RECR	Offset	Reset Value
Receive Error Counter Register	**$1D_H$**	**0000_H**



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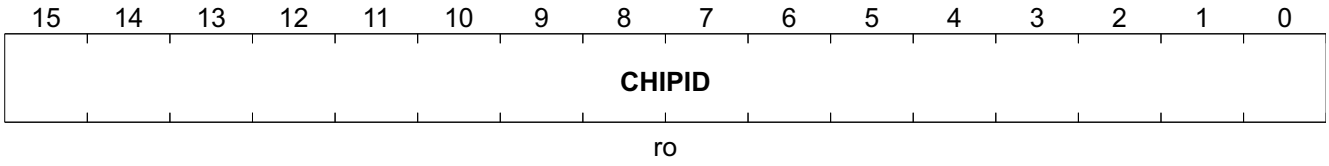
Field	Bits	Type	Description
ERB	15:0	ro	**Error Counter** Includes. 1_H **100MFC**, 100M False Carrier 2_H **100MSE**, 100M Symbol Error 3_H **10MTJ**, 10M Transmit Jabber 4_H **10MRJ**, 10M Receive Jabber 5_H **ESS**, Error Start of Stream 6_H **EES**, Error End of Stream

Chip ID Register

CIR	Offset	Reset Value
Chip ID Register	**$1F_H$**	**8125_H**



Field	Bits	Type	Description
CHIPID	15:0	ro	**CHIPID 15:0**

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5 Electrical Characteristics

5.1 DC Characterization

5.1.1 Absolute Maximum Rating

Table 23 Absolute Maximum Rating

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
3.3 V Power Supply	V_{CC33}	3.0	–	3.6	V	–
2.5 V Power Supply	V_{CC25}	2.25	–	2.75	V	–
Input Voltage	V_{IN}	-0.3	–	V_{CC33} + 0.3	V	–
Output Voltage	V_{OUT}	-0.25	–	V_{CC25} + 0.25	V	–
Storage Temperature	T_{STG}	-55	–	155	°C	–
Power Consumption	P_C	–	–	0.5	W	–
ESD Rating	V_{ESD}	–	–	2000	V	–

5.1.2 Recommended Operating Conditions

Table 24 Recommended Operating Conditions

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Power Supply	V_{CC33}	3.135	3.3	3.465	V	–
Input Voltage	V_{IN}	0	–	V_{cc33}	V	–
Junction Operating Temperature	T_j	0	25	115	°C	–

5.1.2.1 DC Characteristics for 2.5 V Operation

Under V_{cc} = 3.0 V ~3.6 V, T_j = 0°C ~ 115 °C

Table 25 DC Characteristics for 2.5 V Operation

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Input Low Voltage	V_{IL}	–	–	0.3 * V_{cc}	V	CMOS
Input High Voltage	V_{IH}	0.7 * V_{cc}	v	–	V	CMOS
Output Low Voltage	V_{OL}	–	–	0.4	V	CMOS
Output High Voltage	V_{OH}	2.0	–	–	V	CMOS
Input Pull-up/down Resistance	R_I	–	75	–	KΩ	V_{IL} = 0 V or V_{IH} = V_{cc33}

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5.2 AC Characteristics

5.2.1 XI/OSCI (Crystal/Oscillator) Timing (In MII Mode)

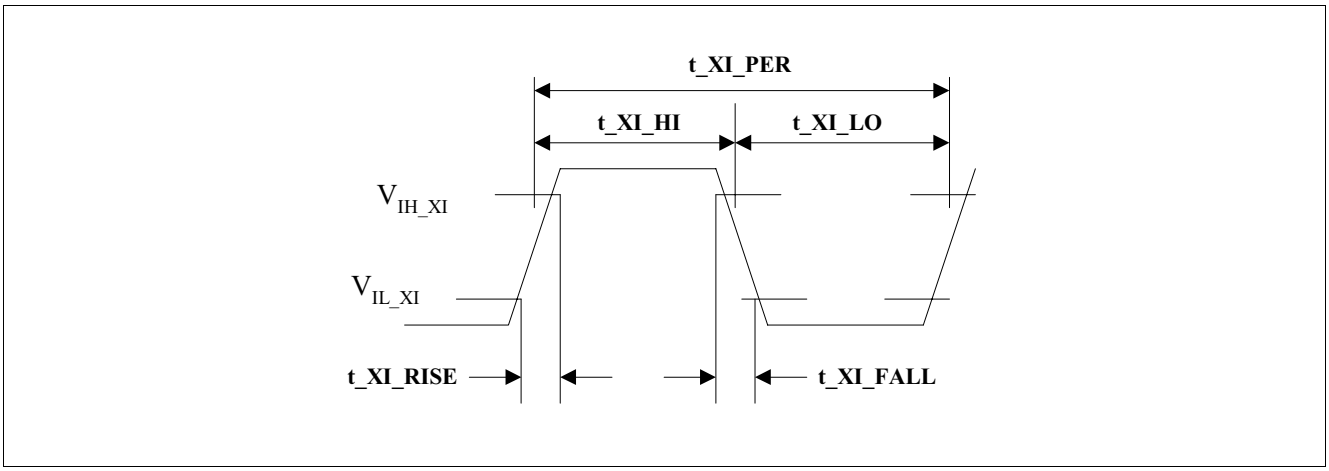

Figure 25 Crystal/Oscillator Timing

Table 26 Crystal/Oscillator Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
XI/OSCI Clock Period[1)]	t_{XI_PER}	40.0 - 50 ppm	40.0	40.0 + 50 ppm	ns	–
XI/OSCI Clock High	t_{XI_HI}	14	20.0	–	ns	–
XI/OSCI Clock Low	TX_ILO	14	20.0	–	ns	–
XI/OSCI Clock Rise Time, V_{IL} (max) to V_{IH} (min.)	t_{XI_RISE}	–	–	4	ns	–
XI/OSCI Clock Fall Time, V_{IH} (min.) to V_{IL} (max)	t_{XI_FALL}	–	–	4	ns	–

1) Clock period less then 40ns - 50ppm or greater than 40ns + 50ppm may introduce peer receive CRC due to insufficient receive FIFO depth. Check peer receive FIFO description to confirm.

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5.3 RMII Timing

5.3.1 REFCLK Input Timing (XI in RMII Mode)

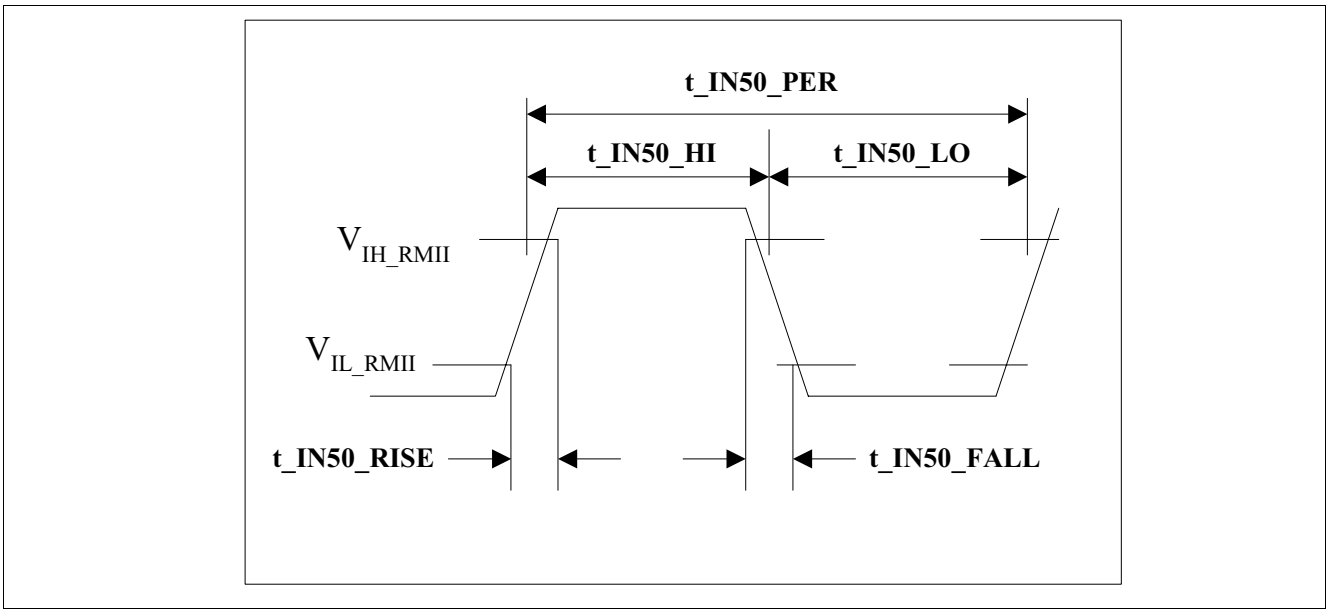

Figure 26 REFCLK Input Timing

Table 27 REFCLK Input Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
REFCLK Clock Period	t_{IN50_PER}	20.0 - 50 ppm	20.0	20.0 + 50 ppm	ns	–
REFCLK Clock High	t_{IN50_HI}	8	10.0	–	ns	–
REFCLK Clock Low	t_{IN50_LO}	8	10.0	–	ns	–
REFCLK Clock Rise Time, V_{IL} (max) to V_{IH} (min.)	t_{IN50_RISE}	–	–	2	ns	–
REFCLK Clock Fall Time, V_{IH} (min.) to V_{IL} (max)	t_{IN50_FALL}	–	–	2	ns	–

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5.3.2 REFCLK Output Timing (CLKO50 in RMII Mode)

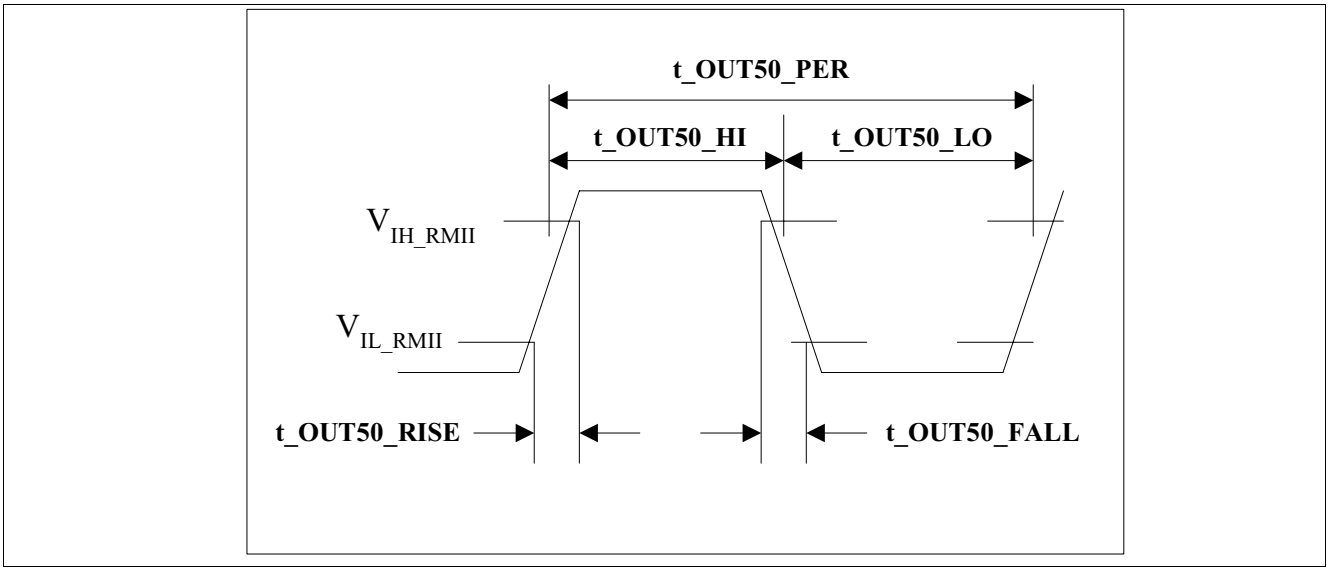

Figure 27 REFCLK Output Timing

Table 28 REFCLK Output Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
REFCLK Clock Period	t_{OUT50_PER}	20.0 - 50 ppm	20.0	20.0 + 50 ppm	ns	–
REFCLK Clock High	t_{OUT50_HI}	8	10.0	12	ns	–
REFCLK Clock Low	t_{OUT50_LO}	8	10.0	12	ns	–
REFCLK Clock Rise Time, V_{IL} (max) to V_{IH} (min.)	t_{OUT50_RISE}	–	–	2	ns	–
REFCLK Clock Fall Time, V_{IH} (min.) to V_{IL} (max)	t_{OUT50_FALL}	–	–	2	ns	–
REFCLK Clock Jittering (p-p)	t_{OUT50_JIT}	–	0.15	–	ns	v

5.3.3 RMII Transmit Timing

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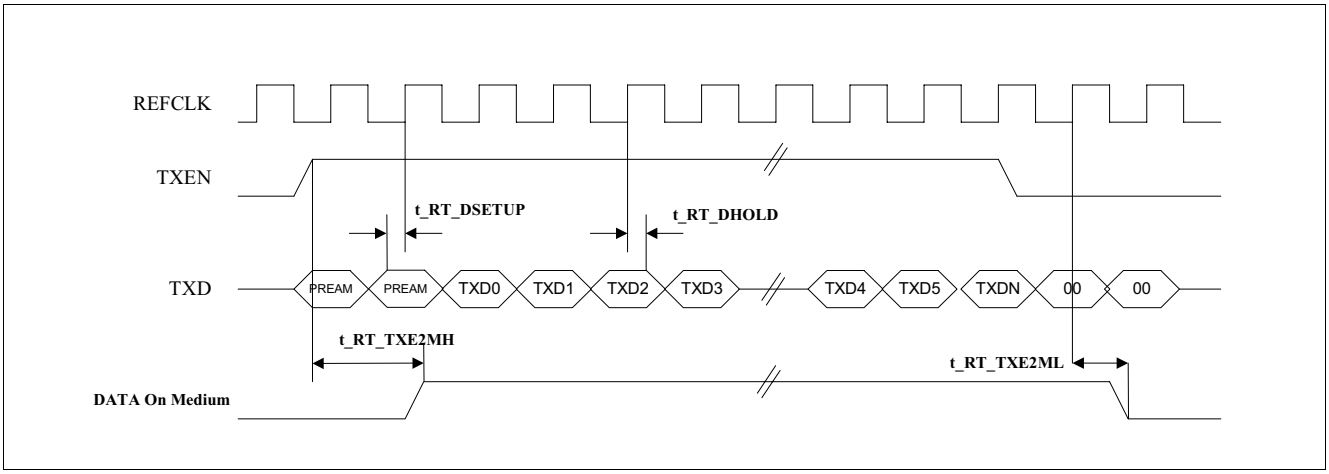

Figure 28 RMII Transmit Timing

Table 29 RMII Transmit Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
TXD to REFCLK Rising Setup Time	t_{RT_DSETUP}	2	–	–	ns	–
TXD to REFCLK Rising Hold Time	t_{RT_DHOLD}	2	–	–	ns	–
TXEN asserts to data transmit to medium	$t_{RT_TXE2MH100}$	–	–	235	ns	–
TXEN asserts to data transmit to medium	$t_{RT_TXE2MH10}$	–	–	1550	ns	–
TXEN de-asserts to finish transmitting	$t_{RT_TXE2ML100}$	–	–	260	ns	–
TXEN de-asserts to finish transmitting	$t_{RT_TXE2ML10}$	–	–	1250	ns	–

5.3.4 RMII Receive Timing

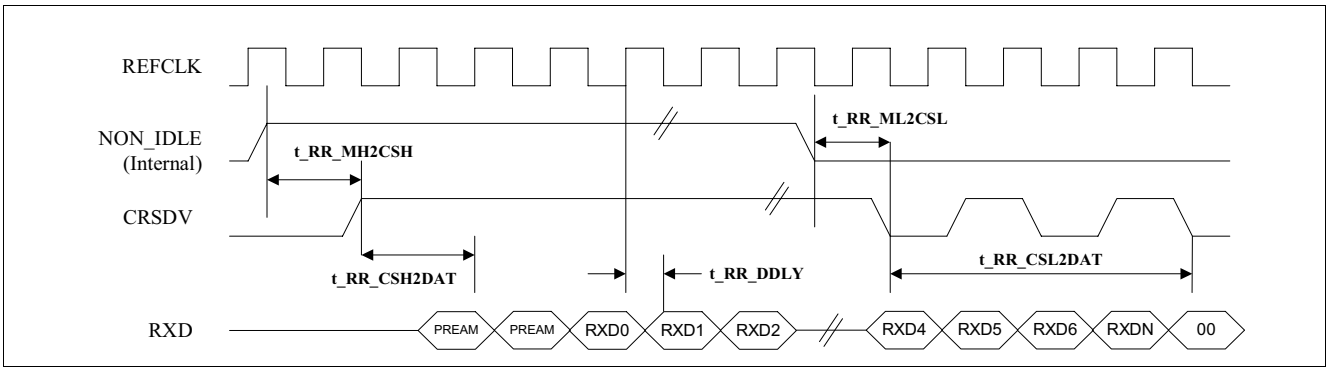

Figure 29 RMII Receive Timing

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Table 30 RMII Receive Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Signal Detected on Medium to CRSDV High	$t_{RR_MH2CSH100}$	–	–	265	ns	–
Signal Detected on Medium to CRSDV High	$t_{RR_MH2CSH10}$	–	–	1000	ns	–
IDLE Detected on Medium to CRSDV low	$t_{RR_ML2CSL100}$	–	–	260	ns	–
IDLE Detected on Medium to CRSDV low	$t_{RR_ML2CSL10}$	–	–	570	ns	–
CRSDV High to Receive Data on RXD	$t_{RR_CSH2DAT100}$	–	–	160	ns	–
CRSDV High to Receive Data on RXD	$t_{RR_CSH2DAT10}$	–	–	1600	ns	–
CRSDV Toggle to End of Data Receiving	$t_{RR_CSL2DAT100}$	–	160	–	ns	–
CRSDV Toggle to End of Data Receiving	$t_{RR_CSL2DAT10}$	–	1600	–	ns	–
REFCLK Rising to RXD/CRSDV Delay Time	t_{RR_DDLY}	–	–	5	ns	–

5.4 MII Timing

5.4.1 RXCLK Clock Timing

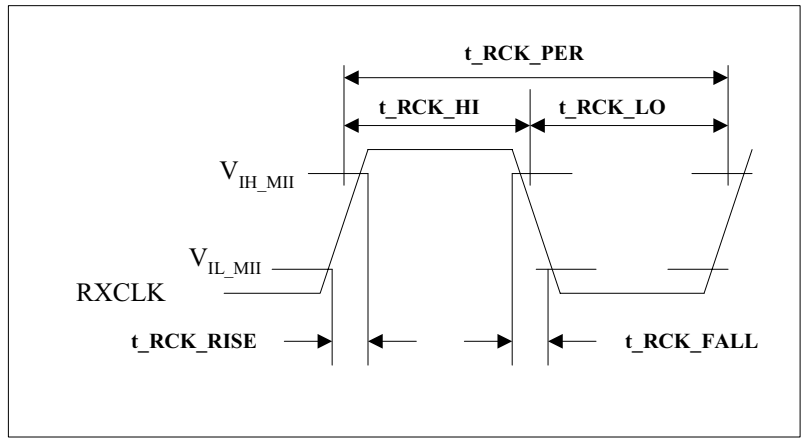

Figure 30 RXCLK Output Timing

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Table 31 REFCLK Input Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
RXCLK Clock Period(100M) Note[1]	t_{RCK_PER100}	40.0 - 50 ppm	40.0	40.0 + 50 ppm	ns	–
RXCLK Clock Period(10M) Note[2]	t_{RCK_PER10}	400.0 - 50 ppm	400.0	400.0 + 50 ppm	ns	–
RXCLK Clock High (100M)	t_{RCK_HI100}	16	–	24		–
RXCLK Clock High (10M)	t_{RCK_HI10}	–	200	–		–
RXCLK Clock Low (100M)	t_{RCK_LO100}	16	–	24	ns	–
RXCLK Clock Low (10M)	t_{RCK_LO10}	–	200	–		–
RXCLK Clock Rise Time, V_{IL} (max) to V_{IH} (min.)	t_{RCK_RISE}	–	–	2	ns	–
RXCLK Clock Fall Time, V_{IH} (min.) to V_{IL} (max)	t_{RCK_FALL}	–	–	2	ns	–
REFCLK Clock Jittering (p-p)	t_{RCK_JIT}	–	0.15	–	ns	–

1) Clock period ppm value is highly depended upon peer transmitter clock source skew.

2) Clock period ppm value is highly depended upon peer transmitter clock source skew.

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5.4.2 MII Receive Timing

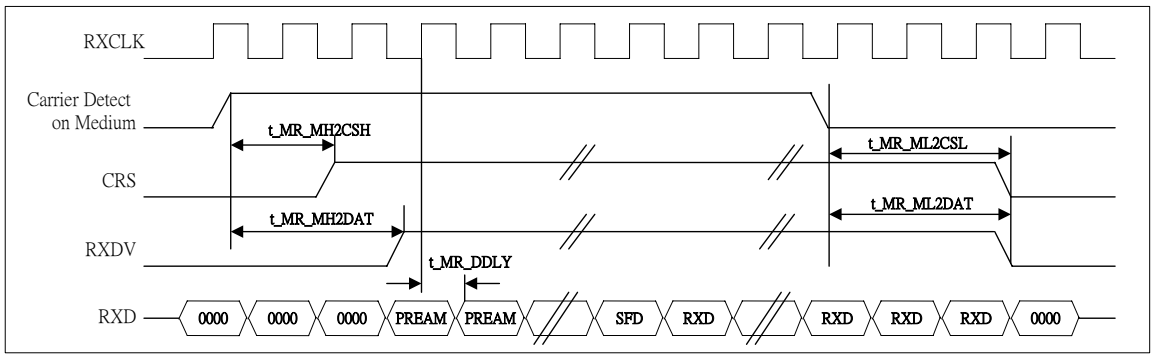

Figure 31 MII Receive Timing

Table 32 MII Receive Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Signal Detected on Medium to CRS High	$t_{MR_MH2CSH100}$	–	–	140	ns	–
Signal Detected on Medium to CRS High	$t_{MR_MH2CSH10}$	–	–	1450	ns	–
Signal Detected on Medium to RXDV High	$t_{MR_MH2DAT100}$	–	–	150	ns	–
Signal Detected on Medium to RXDV High	$t_{MR_MH2DAT10}$	–	–	2300	ns	–
RXCLK rising to Data Valid Delay Time	$t_{MR_DDLY100}$	10	–	25	ns	–
RXCLK rising to Data Valid Delay Time	t_{MR_DDLY10}	10	–	25	ns	–
IDLE Detected on Medium to CRS Low	$t_{MR_ML2CSL100}$	–	–	120	ns	–
DLE Detected on Medium to CRS Low	$t_{MR_ML2CSL10}$	–	–	235	ns	–
DLE Detected on Medium to RXDV Low	$t_{MR_ML2DAT100}$	–	–	150	ns	–
DLE Detected on Medium to RXDV Low	$t_{MR_ML2DAT10}$	–	–	1450	ns	–

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5.4.3 TXCLK Output Timing

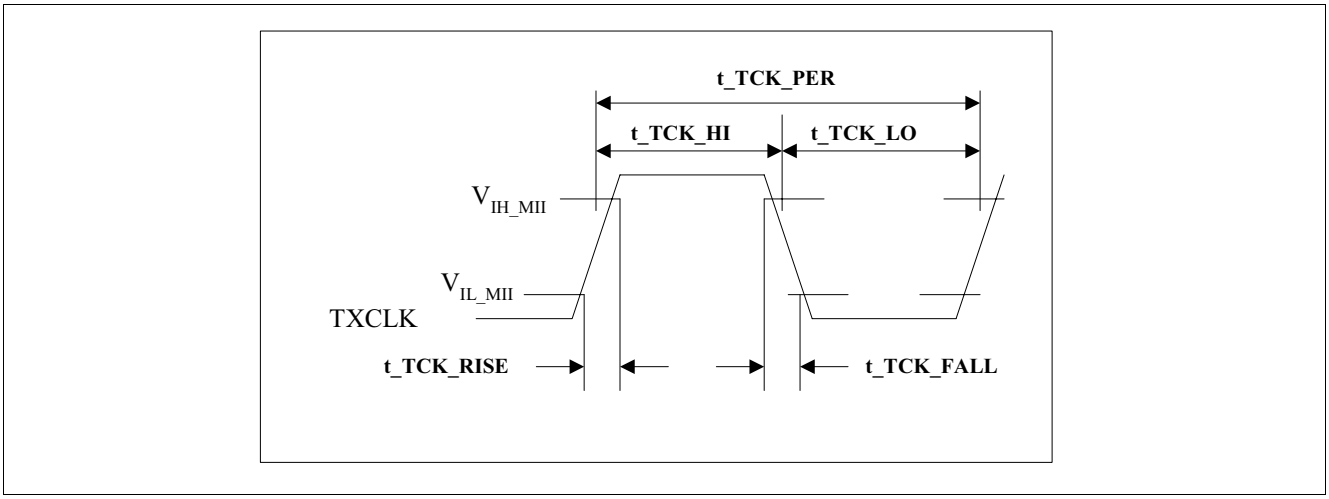

Figure 32 TXCLK Output Timing

Table 33 TXCLK Output Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
TXCLK Clock Period (100M)	t_{TCK_PER100}	40.0 - 50 ppm	40.0	40.0 + 50 ppm	ns	–
TXCLK Clock Period (10M)	t_{TCK_PER10}	40.0 - 50 ppm	40.0	40.0 + 50 ppm	ns	–
TXCLK Clock High (100M)	t_{TCK_HI100}	16	–	24	ns	–
TXCLK Clock High (10M)	t_{TCK_HI10}	160	–	240	ns	–
TXCLK Clock Low(100M)	t_{TCK_LO100}	16	–	24	ns	–
TXCLK Clock High (10M)	t_{TCK_LO10}	160	–	240	ns	–
TXCLK Clock Rise Time, VIL (max) to VIH (min)	t_{TCK_RISE}	–	–	2	ns	–
TXCLK Clock Fall Time, VIH (min) to VIL (max)	t_{TCK_FALL}	–	–	2	ns	–
TXCLK Clock Jittering (p-p)	t_{TCK_JIT}	–	0.15	–	ns	–

5.4.4 MII Transmit Timing

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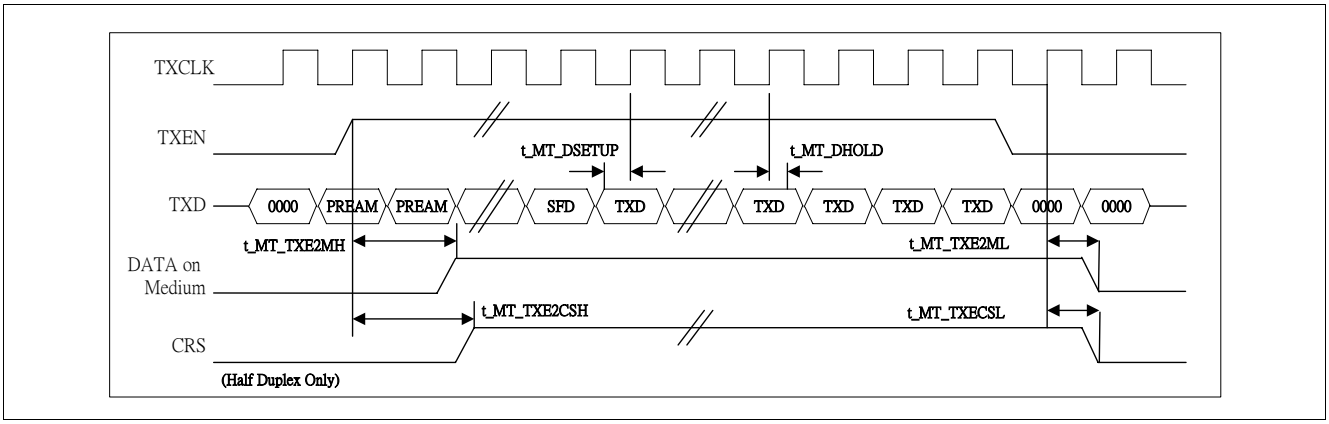

Figure 33 MII Transmit Timing

Table 34 MII Transmit Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
TXD to TXCLK Rising Setup Time	t_{MT_DSETUP}	10	–	25	ns	–
TXD to TXCLK Rising Hold Time	t_{MT_DHOLD}	10	–	25	ns	–
TXEN asserts to data transmit to medium (100M)	$t_{MT_TXE2MH100}$	–	–	75	ns	–
TXEN asserts to data transmit to medium (10M)	$t_{MT_TXE2MH10}$	–	–	350	ns	–
TXEN asserts to CRS Assert (100M Half)	$t_{MT_TXE2CSH100}$	–	–	15	ns	–
TXEN asserts to CRS Assert (10M Half)	$t_{MT_TXE2CSH10}$	–	–	200	ns	–
TXEN de-asserts to finish transmitting (100M)	$t_{MT_TXE2ML100}$	–	–	95	ns	–
TXEN de-asserts to finish transmitting (10M)	$t_{MT_TXE2ML10}$	–	–	660	ns	–
TXEN de-asserts to CRS de-asserts (100M)	$t_{MT_TXE2CSL100}$	–	–	15	ns	–
TXEN de-asserts to CRS de-asserts (10M)	$t_{MT_TXE2CSL10}$	–	–	190	ns	–

5.5 GPSI Timing

5.5.1 GPSI Receive Timing

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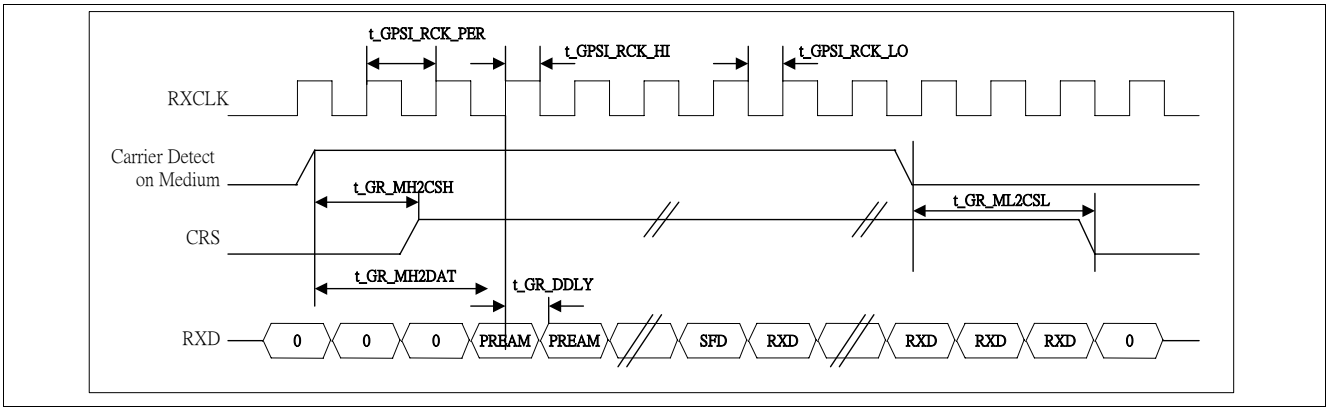

Figure 34 GPSI Receive Timing

Table 35 GPSI Receive Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
10M Receive Clock Period	$t_{GPSI_RCK_PER}$	100.0 - 50 ppm	100.0	100.0 + 50 ppm	ns	–
10M Receive Clock High	$t_{GSPI_RCK_HI}$	40	–	–	ns	–
10M Receive Clock Low	$t_{GSPI_RCK_LO}$	40	–	–	ns	–
Signal Detected on Medium to CRS High	t_{GR_MH2CSH}	–	–	1500	ns	–
Signal Detected on Medium to Data Valid	t_{GR_MH2DAT}	–	–	1600	ns	–
RXCLK rising to Data Valid Delay Time	t_{GR_DDLY}	40	–	60	ns	–
IDLE Detected on Medium to CRS Low	t_{GR_ML2CSL}	–	–	230	ns	–

5.5.2 GPSI Transmit Timing

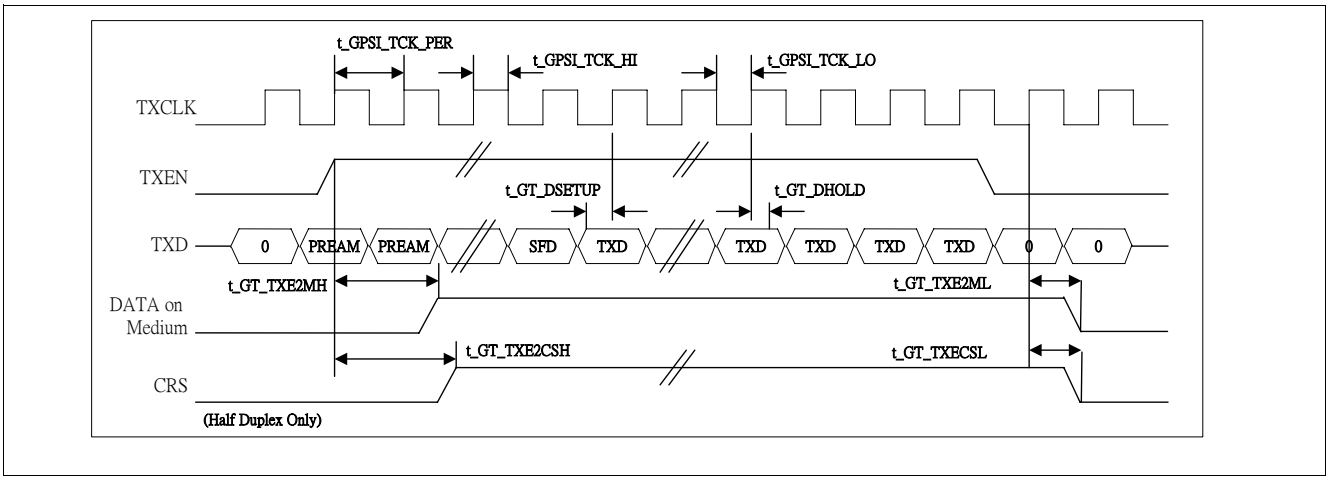

Figure 35 GPSI Transmit Timing

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Table 36 GPSI Transmit Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
10M Transmit Clock Period	$t_{GPSI_TCK_PER}$	100.0 - 50 ppm	100.0	100.0 + 50 ppm	ns	–
10M Transmit Clock High	$t_{GSPI_TCK_HI}$	40	–	–	ns	–
10M Transmit Clock Low	$t_{GSPI_TCK_LO}$	40	–	–	ns	–
TXD to TXCLK Rising Setup Time	t_{GT_DSETUP}	40	–	–	ns	–
TXD to TXCLK Rising Hold Time	t_{GT_DHOLD}	40	–	–	ns	–
TXEN asserts to data transmit to medium	t_{GT_TXE2MH}	–	–	150	ns	–
TXEN asserts to CRS Assert (Half)	$t_{GT_TXE2CSH}$	–	–	10	ns	–
TXEN de-asserts to finish transmitting	t_{GT_TXE2ML}	–	–	900	ns	–
TXEN de-asserts to CRS de-asserts	t_{GT_TXECSL}	–	–	10	ns	–

5.6 Serial Management Interface (MDC/MDIO) Timing

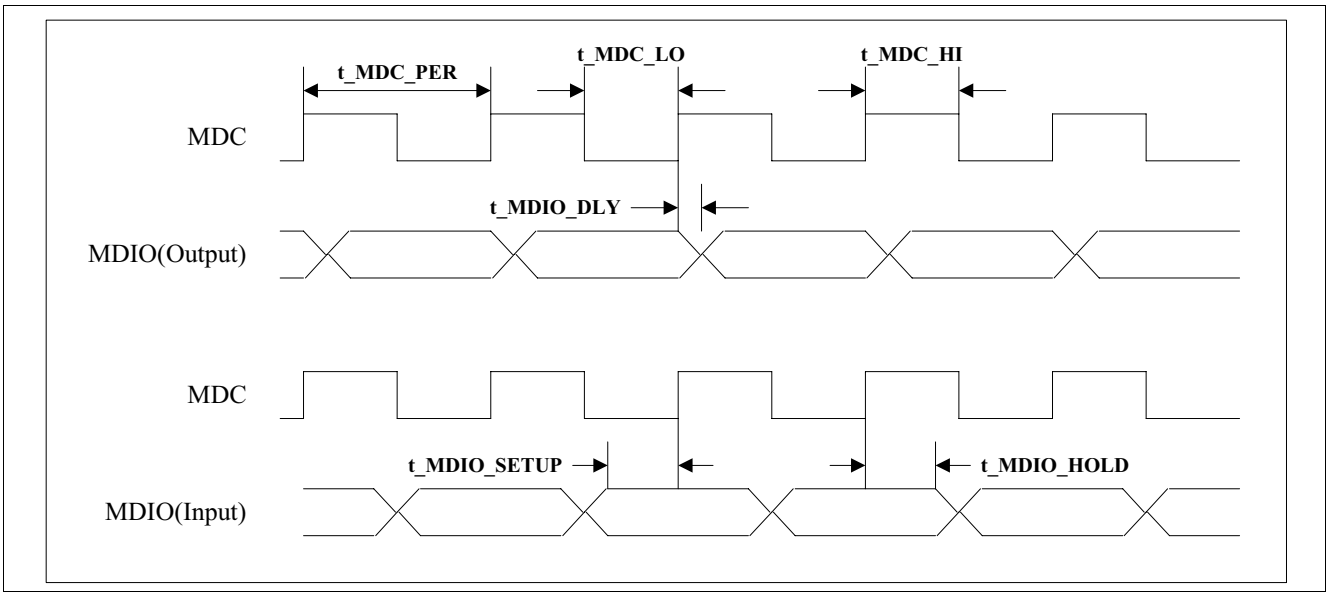

Figure 36 Serial Management Interface (MDC/MDIO) Timing

Table 37 Serial Management Interface (MDC/MDIO) Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
MDC Period	t_{MDC_PER}	100	–	–	ns	–
MDC High	t_{MDC_HI}	40	–	–	ns	–

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Table 37 Serial Management Interface (MDC/MDIO) Timing (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
MDC Low	t_{MDC_LO}	40	–	–	ns	–
MDC to MDIO Delay Time	t_{MDIO_DLY}	–	–	20	ns	–
MDIO Input to MDC Setup Time	t_{MDIO_SETUP}	10	–	–	ns	–
MDIO Input to MDC Hold Time	t_{MDIO_HOLD}	10	–	–	ns	–

5.7 Power On Configuration Timing

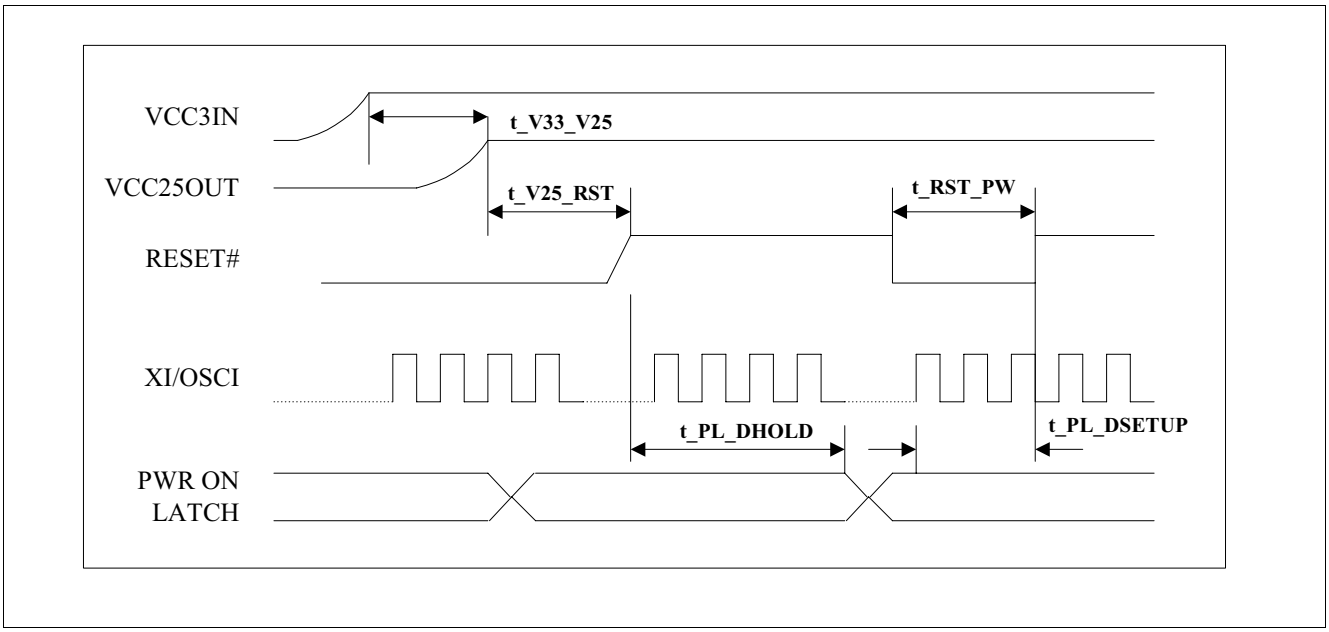

Figure 37 Power On Configuration Timing

Table 38 Power On Configuration Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
3.3V Power Good to 2.5 V Power Good	t_{V33_V25}	TBD	–	–	ms	–
Hardware Reset With Device Powered up	t_{V25_RST}	200	–	–	ms	–
Hardware Reset With Clock Running	t_{RST_PW}	800	–	–	ns	–
Reset High to Configuration Setup Time	t_{PL_DSETUP}	200	–	–	ns	–
Reset High to Configuration Hold Time	t_{PL_DHOLD}	0	–	–	ns	–

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6 Packaging

ADM7001,Low Profile Quad Flat Package (LQFP) 48 Pin

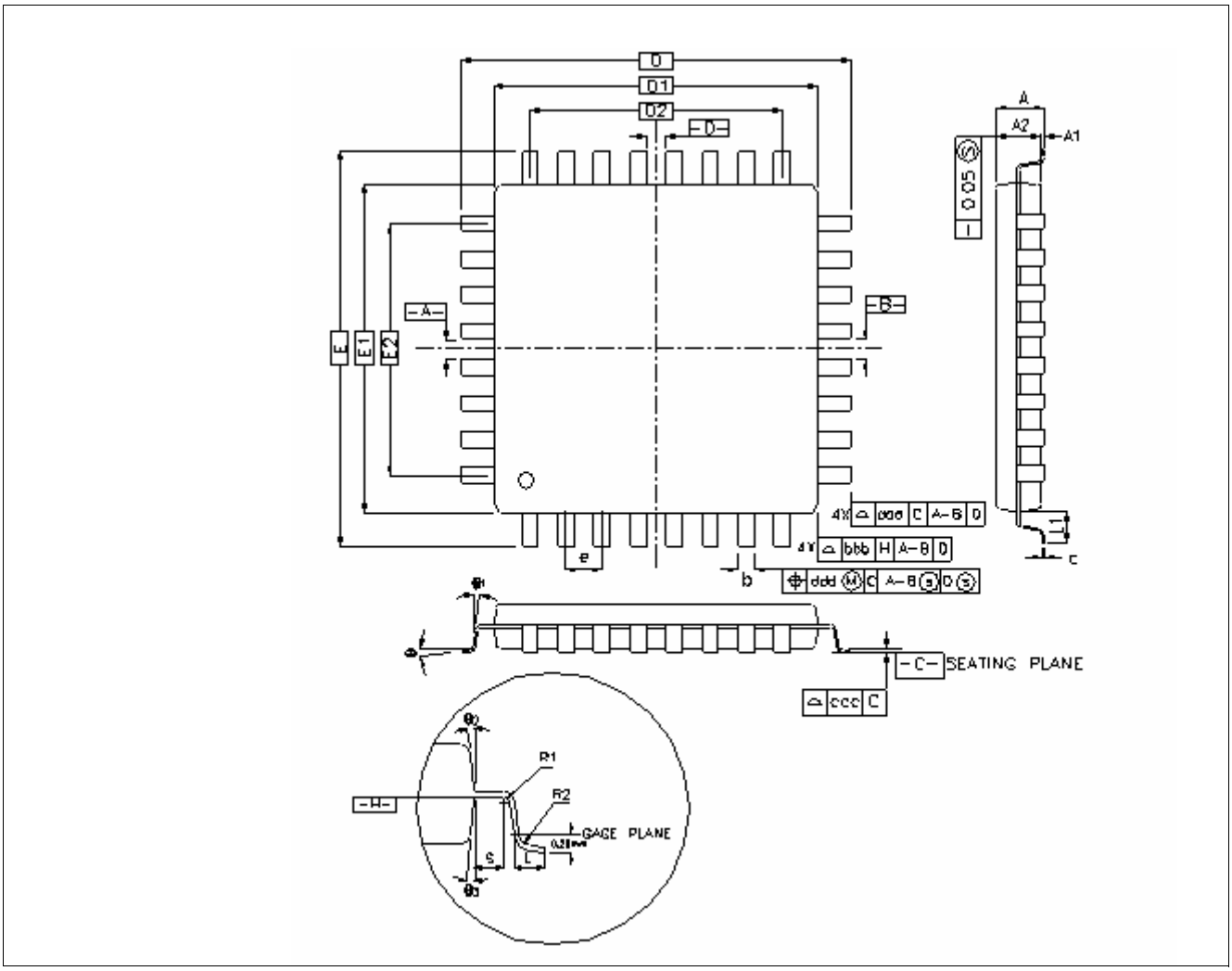

Figure 38 ADM7001,Low Profile Quad Flat Package (LQFP)

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Table 39 Dimensions for 100 Pin LQFP Package

Symbol	Millimeter (mm)			Inch		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	–	–	1.60	–	–	0.063
A_1	0.05	–	0.15	0.002	–	0.006
A_2	1.35	1.40	1.45	0.053	0.005	0.057
D		9.00 BSC.			0.354 BSC.	
D_1		7.00 BSC			0.276 BSC.	
E		9.00 BSC			0.354 BSC.	
E_1		7.00 BSC			0.276 BSC.	
R_2	0.08	–	0.20	0.003	–	0.008
R_1	0.08	–	–	0.003	–	–
Θ	0°	3.5°	7°	0°	3.5°	7°
$Θ_1$	0°	–	–	0°	–	–
$Θ_2$	11°	12°	13°	11°	12°	13°
$Θ_3$	11°	12°	13°	11°	12°	13°
c	0.09	–	0.20	0.004	–	0.008
L	0.45	0.60	0.75	0.018	0.024	0.030
L_1		1.00 Ref.			0.039 Ref.	
S	0.20	–	–	0.008	–	–
			32L			
b	0.30	0.35	0.45	0.012	0.014	0.018
e		0.80 BSC.			0.031 BSC.	
D_2		5.60			0.220	
E_2		5.60			0.220	
			Tolerance of Form and Position			
aaa		0.20			0.008	
bbb		0.20			0.008	
ccc		0.10			0.003	
ddd		0.20			0.008	
			44L			
b	0.17	0.20	0.27	0.007	0.008	0.011
e		0.50 BSC.			0.020 BSC.	
D_2		5.00			0197	
E_2		5.00			0.197	
			Tolerance of Form and Position			
aaa		0.20			0.008	
bbb		0.20			0.008	
ccc		0.08			0.003	
ddd		0.08			0.003	
			48L			
b	0.17	0.20	0.27	0.007	0.008	0.011

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Table 39 Dimensions for 100 Pin LQFP Package (cont'd)

Symbol	Millimeter (mm)	Inch
e	0.50 BSC.	0.020 BSC.
D_2	5.50	0.217
E_2	5.50	0.217
Tolerance of Form and Position		
aaa	0.20	0.008
bbb	0.20	0.008
ccc	0.08	0.003
ddd	0.08	0.003

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References

[1]

[2]

[3]

[4]

[5]

[6]

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Predefined Names

Name	Note

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Terminology

A

B

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