

## Absolute Maximum Ratings

Stresses beyond the limits listed below may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

$V_S$  ..... 0V to 6V

$V_{IN}$  .....  $-V_S - 0.5V$  to  $+V_S + 0.5V$

Continuous Output Current ..... -40mA to +40mA

## Operating Conditions

Supply Voltage Range ..... 2.5 to 5.5V

Operating Temperature Range ..... -40°C to 125°C

Junction Temperature ..... 150°C

Storage Temperature Range ..... -65°C to 150°C

Lead Temperature (Soldering, 10s) ..... 260°C

## Package Thermal Resistance

$\theta_{JA}$  (SOIC-8) ..... 150°C/W

$\theta_{JA}$  (MSOP-8) ..... 200°C/W

$\theta_{JA}$  (SOIC-14) ..... 90°C/W

$\theta_{JA}$  (TSSOP-14) ..... 100°C/W

Package thermal resistance ( $\theta_{JA}$ ), JEDEC standard, multi-layer test boards, still air.

## ESD Protection

CLC2011, CLC4011 (HBM) ..... 2kV

ESD Rating for HBM (Human Body Model).

**Electrical Characteristics at +2.7V**

$T_A = 25^\circ\text{C}$ ,  $V_S = +2.7\text{V}$ ,  $R_f = R_g = 5\text{k}\Omega$ ,  $R_L = 10\text{k}\Omega$  to  $V_S/2$ ;  $G = 2$ ; unless otherwise noted.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
Frequency Domain Response						
UGBW <sub>SS</sub>	Unity Gain -3dB Bandwidth	G = +1, V <sub>OUT</sub> = 0.02V <sub>pp</sub>		4.9		MHz
BW <sub>SS</sub>	-3dB Bandwidth	G = +2, V <sub>OUT</sub> = 0.2V <sub>pp</sub>		3.2		MHz
BW <sub>LS</sub>	Large Signal Bandwidth	G = +2, V <sub>OUT</sub> = 2V <sub>pp</sub>		1.4		MHz
GBWP	Gain Bandwidth Product	G = +11, V <sub>OUT</sub> = 0.2V <sub>pp</sub>		2.5		MHz
Time Domain Response						
t <sub>R</sub> , t <sub>F</sub>	Rise and Fall Time	V <sub>OUT</sub> = 1V step; (10% to 90%)		163		ns
t <sub>S</sub>	Settling Time to 0.1%	V <sub>OUT</sub> = 1V step		500		ns
OS	Overshoot	V <sub>OUT</sub> = 1V step		<1		%
SR	Slew Rate	1V step		5.3		V/μs
Distortion/Noise Response						
HD2	2nd Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		-72		dBc
HD3	3rd Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		-72		dBc
THD	Total Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		0.03		%
e <sub>n</sub>	Input Voltage Noise	>10kHz		21		nV/√Hz
X <sub>TALK</sub>	Crosstalk	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 10kHz		82		dB
		Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 50kHz		74		dB
DC Performance						
V <sub>IO</sub>	Input Offset Voltage			0.5		mV
d <sub>VIO</sub>	Average Drift			5		μV/°C
I <sub>B</sub>	Input Bias Current			90		nA
dI <sub>B</sub>	Average Drift			32		pA/°C
PSRR	Power Supply Rejection Ratio	DC	55	83		dB
A <sub>OL</sub>	Open Loop Gain	V <sub>OUT</sub> = V <sub>S</sub> / 2		90		dB
I <sub>S</sub>	Supply Current	per channel		136		μA
Input Characteristics						
R <sub>IN</sub>	Input Resistance	Non-inverting		12		MΩ
C <sub>IN</sub>	Input Capacitance			2		pF
CMIR	Common Mode Input Range			-0.25 to 2.95		V
CMRR	Common Mode Rejection Ratio	DC		81		dB
Output Characteristics						
V <sub>OUT</sub>	Output Voltage Swing	R <sub>L</sub> = 10kΩ to V <sub>S</sub> / 2		0.02 to 2.68		V
		R <sub>L</sub> = 1kΩ to V <sub>S</sub> / 2		0.05 to 2.63		V
		R <sub>L</sub> = 200Ω to V <sub>S</sub> / 2		0.11 to 2.52		V
I <sub>OUT</sub>	Output Current			±30		mA

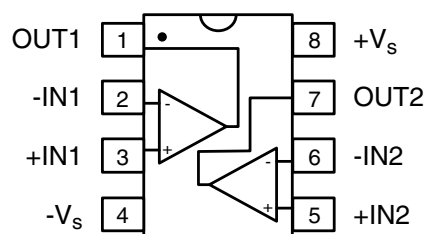
## Electrical Characteristics at +5V

$T_A = 25^\circ\text{C}$ ,  $V_S = +5\text{V}$ ,  $R_f = R_g = 5\text{k}\Omega$ ,  $R_L = 10\text{k}\Omega$  to  $V_S/2$ ;  $G = 2$ ; unless otherwise noted.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
Frequency Domain Response						
UGBW <sub>SS</sub>	Unity Gain -3dB Bandwidth	G = +1, V <sub>OUT</sub> = 0.02V <sub>pp</sub>		4.3		MHz
BW <sub>SS</sub>	-3dB Bandwidth	G = +2, V <sub>OUT</sub> = 0.2V <sub>pp</sub>		3.0		MHz
BW <sub>LS</sub>	Large Signal Bandwidth	G = +2, V <sub>OUT</sub> = 2V <sub>pp</sub>		2.3		MHz
GBWP	Gain Bandwidth Product	G = +11, V <sub>OUT</sub> = 0.2V <sub>pp</sub>		2.5		MHz
Time Domain Response						
t <sub>R</sub> , t <sub>F</sub>	Rise and Fall Time	V <sub>OUT</sub> = 1V step; (10% to 90%)		110		ns
t <sub>S</sub>	Settling Time to 0.1%	V <sub>OUT</sub> = 2V step		470		ns
OS	Overshoot	V <sub>OUT</sub> = 1V step		<1		%
SR	Slew Rate	2V step		9		V/μs
Distortion/Noise Response						
HD2	2nd Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		-73		dBc
HD3	3rd Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		-75		dBc
THD	Total Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		0.03		%
e <sub>n</sub>	Input Voltage Noise	>10kHz		22		nV/√Hz
X <sub>TALK</sub>	Crosstalk	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 10kHz		82		dB
		Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 50kHz		74		dB
DC Performance						
V <sub>IO</sub>	Input Offset Voltage		-8	1.5	8	mV
d <sub>VIO</sub>	Average Drift			15		μV/°C
I <sub>B</sub>	Input Bias Current			90	450	nA
dI <sub>B</sub>	Average Drift			40		pA/°C
PSRR	Power Supply Rejection Ratio	DC	55	85		dB
A <sub>OL</sub>	Open Loop Gain	V <sub>OUT</sub> = V <sub>S</sub> / 2		80		dB
I <sub>S</sub>	Supply Current	per channel		160	235	μA
Input Characteristics						
R <sub>IN</sub>	Input Resistance	Non-inverting		12		MΩ
C <sub>IN</sub>	Input Capacitance			2		pF
CMIR	Common Mode Input Range			-0.25 to 5.25		V
CMRR	Common Mode Rejection Ratio	DC	58	80		dB
Output Characteristics						
V <sub>OUT</sub>	Output Voltage Swing	R <sub>L</sub> = 10kΩ to V <sub>S</sub> / 2	0.08 to 4.92	0.04 to 4.96		V
		R <sub>L</sub> = 1kΩ to V <sub>S</sub> / 2		0.07 to 4.9		V
		R <sub>L</sub> = 200Ω to V <sub>S</sub> / 2		0.14 to 4.67		V
I <sub>OUT</sub>	Output Current			±35		mA

## CLC2011 Pin Configurations

SOIC-8 / MSOP-8



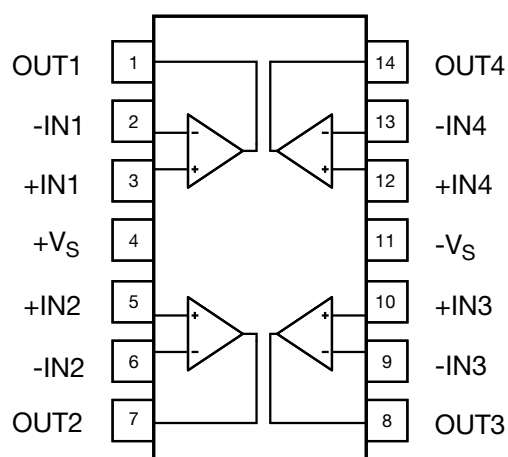
## CLC2011 Pin Assignments

SOIC-8 / MSOP-8

Pin No.	Pin Name	Description
1	OUT1	Output, channel 1
2	-IN1	Negative input, channel 1
3	+IN1	Positive input, channel 1
4	-Vs	Negative supply
5	+IN2	Positive input, channel 2
6	-IN2	Negative input, channel 2
7	OUT2	Output, channel 2
8	+Vs	Positive supply

## CLC4011 Pin Configuration

SOIC-14 / TSSOP-14



## CLC4011 Pin Assignments

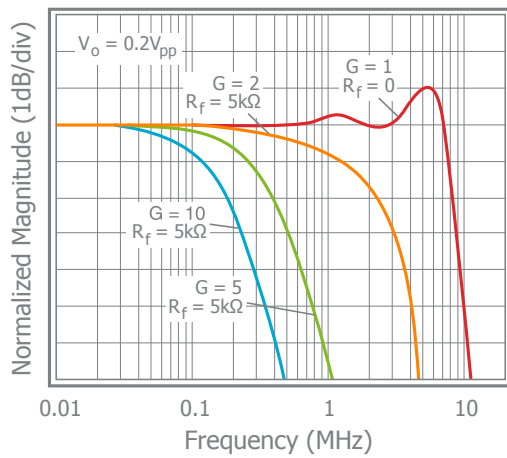
SOIC-14 / TSSOP-14

Pin No.	Pin Name	Description
1	OUT1	Output, channel 1
2	-IN1	Negative input, channel 1
3	+IN1	Positive input, channel 1
4	+Vs	Positive supply
5	+IN2	Positive input, channel 2
6	-IN2	Negative input, channel 2
7	OUT2	Output, channel 2
8	OUT3	Output, channel 3
9	-IN3	Negative input, channel 3
10	+IN3	Positive input, channel 3
11	-Vs	Negative supply
12	+IN4	Positive input, channel 4
13	-IN4	Negative input, channel 4
14	OUT4	Output, channel 4

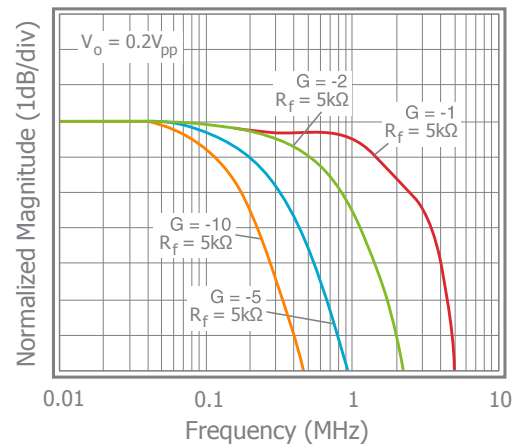
## Typical Performance Characteristics

$T_A = 25^\circ\text{C}$ ,  $V_S = +2.7\text{V}$ ,  $R_f = R_g = 5\text{k}\Omega$ ,  $R_L = 10\text{k}\Omega$  to  $V_S/2$ ;  $G = 2$ ; unless otherwise noted.

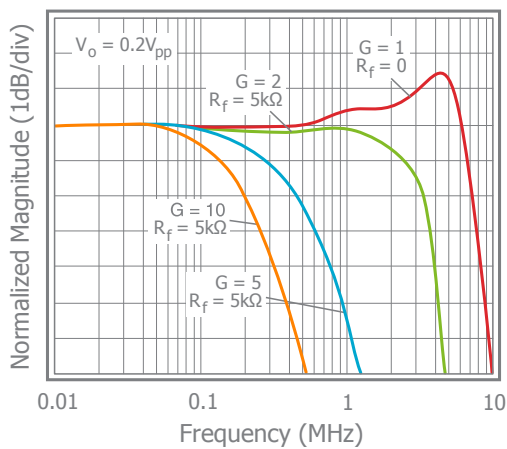
Non-Inverting Frequency Response at  $V_S = 5\text{V}$



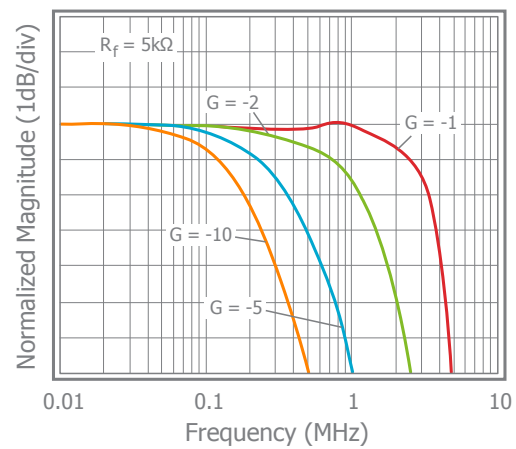
Inverting Frequency Response at  $V_S = 5\text{V}$



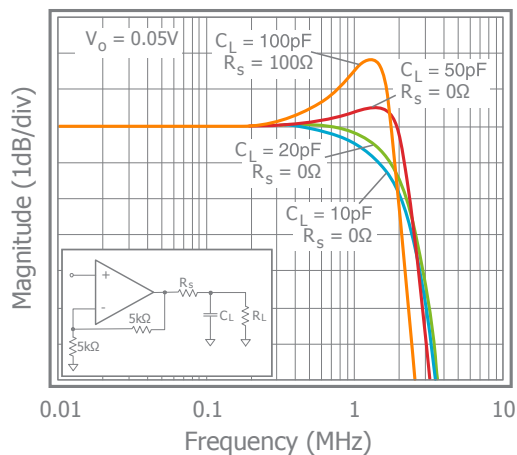
Non-Inverting Frequency Response at  $V_S = 2.7\text{V}$



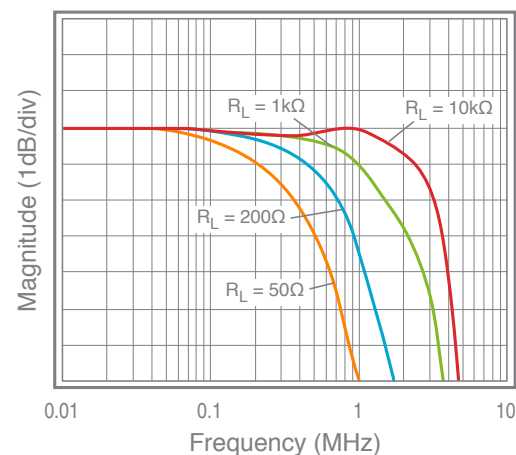
Inverting Frequency Response at  $V_S = 2.7\text{V}$



Frequency Response vs  $C_L$



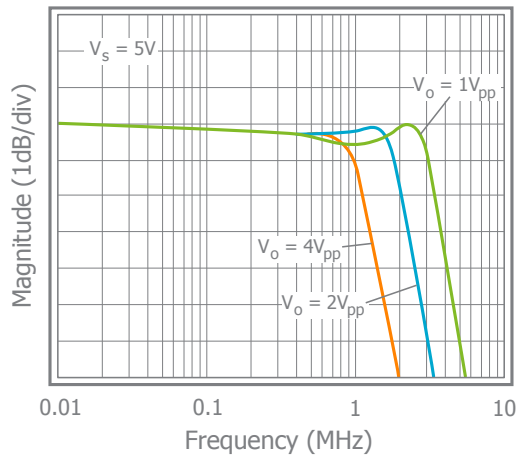
Frequency Response vs  $R_L$



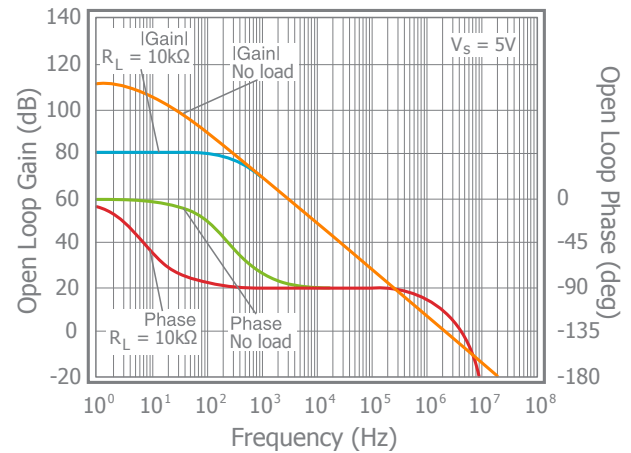
## Typical Performance Characteristics

$T_A = 25^\circ\text{C}$ ,  $V_S = +2.7\text{V}$ ,  $R_f = R_g = 5\text{k}\Omega$ ,  $R_L = 10\text{k}\Omega$  to  $V_S/2$ ;  $G = 2$ ; unless otherwise noted.

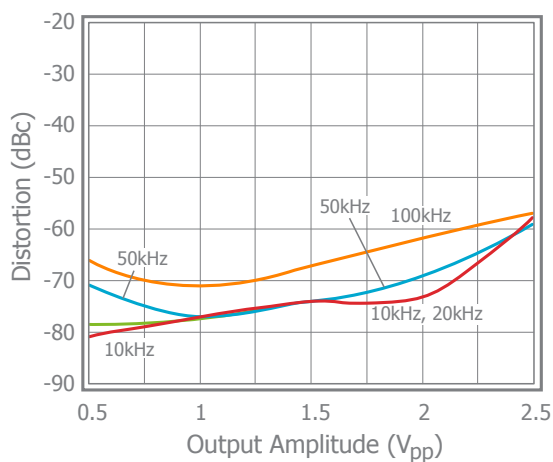
Frequency Response vs.  $V_{OUT}$



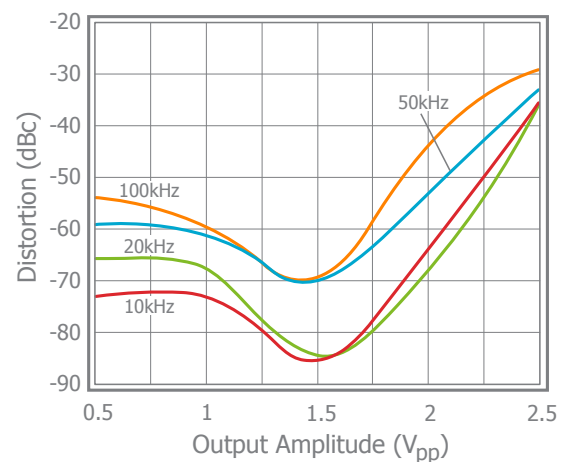
Open Loop Gain & Phase vs. Frequency



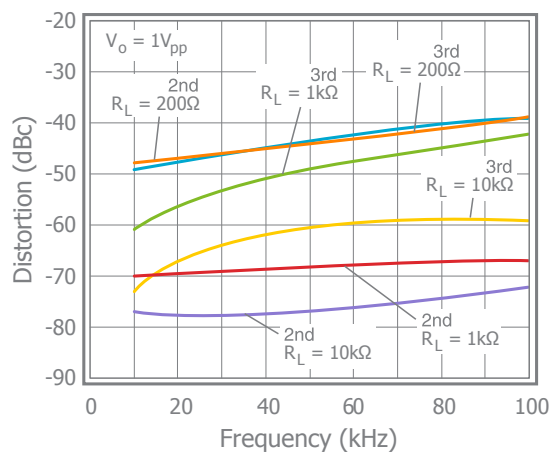
2nd Harmonic Distortion vs  $V_{OUT}$



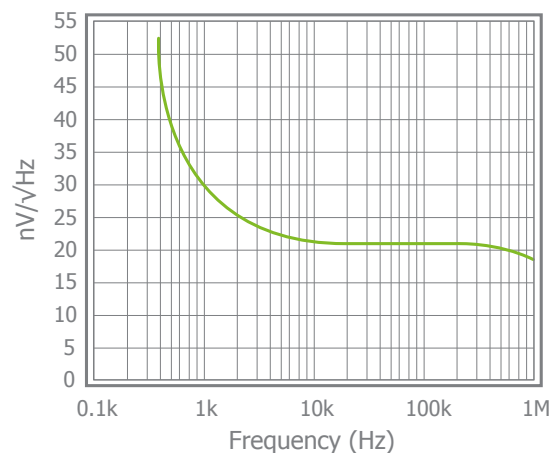
3rd Harmonic Distortion vs  $V_{OUT}$



2nd & 3rd Harmonic Distortion at  $V_S = 2.7\text{V}$



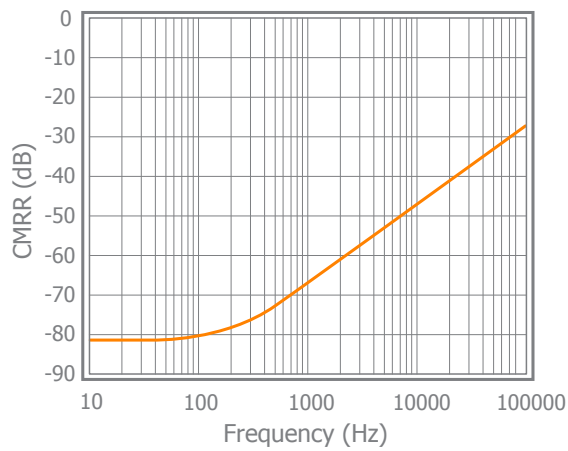
Input Voltage Noise



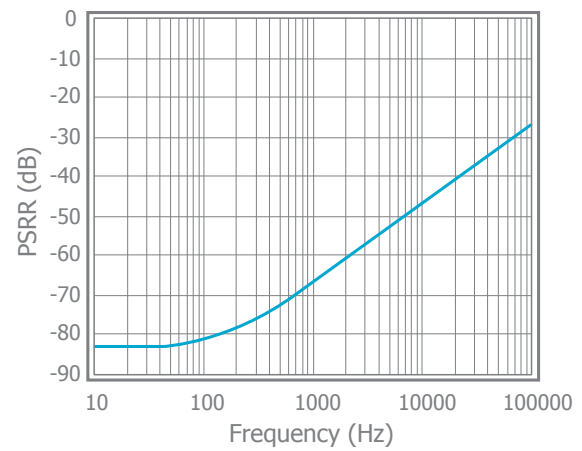
## Typical Performance Characteristics

$T_A = 25^\circ\text{C}$ ,  $V_S = +2.7\text{V}$ ,  $R_f = R_g = 5\text{k}\Omega$ ,  $R_L = 10\text{k}\Omega$  to  $V_S/2$ ;  $G = 2$ ; unless otherwise noted.

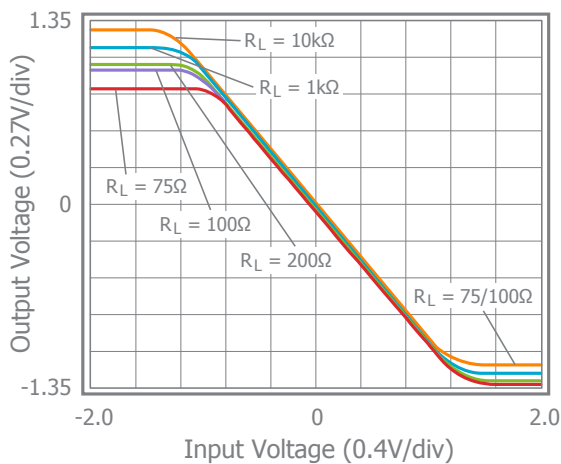
### CMRR



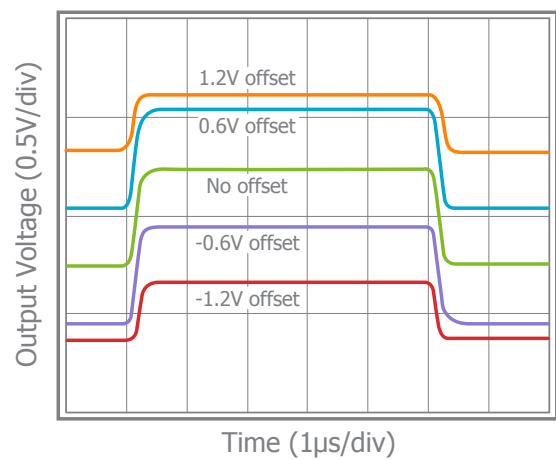
### PSRR



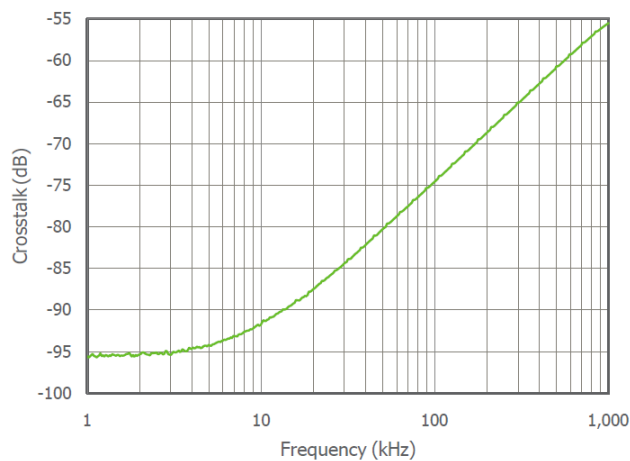
### Output Swing vs. Load



### Pulse Response vs. Common Mode Voltage



### Crosstalk vs. Frequency



## Application Information

### General Description

The CLCx011 family of amplifiers are single supply, general purpose, voltage-feedback amplifiers. They are fabricated on a complimentary bipolar process, feature a rail-to-rail input and output, and are unity gain stable.

### Basic Operation

Figures 1, 2, and 3 illustrate typical circuit configurations for non-inverting, inverting, and unity gain topologies for dual supply applications. They show the recommended bypass capacitor values and overall closed loop gain equations. Figure 4 shows the typical non-inverting gain circuit for single supply applications.

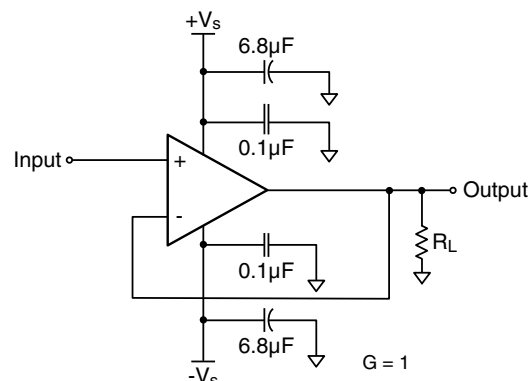


Figure 3: Unity Gain Circuit

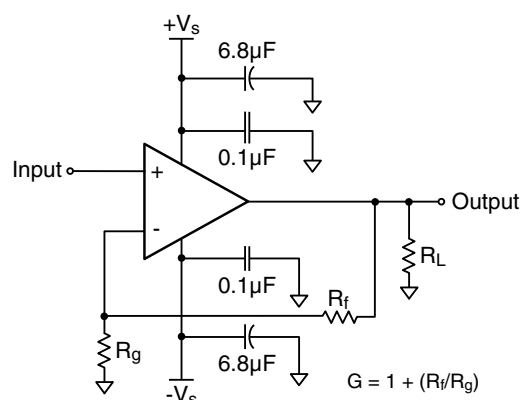


Figure 1: Typical Non-Inverting Gain Circuit

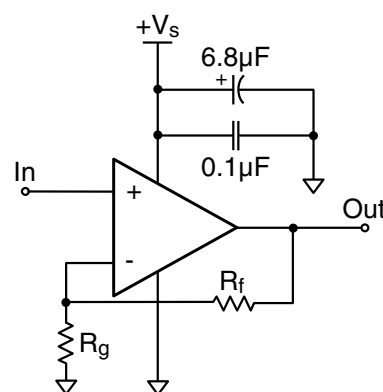


Figure 4: Single Supply Non-Inverting Gain Circuit

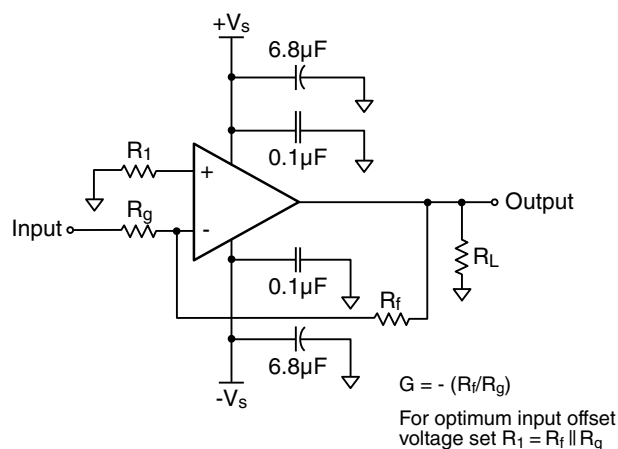


Figure 2: Typical Inverting Gain Circuit

### Power Dissipation

Power dissipation should not be a factor when operating under the stated 10kΩ load condition. However, applications with low impedance, DC coupled loads should be analyzed to ensure that maximum allowed junction temperature is not exceeded. Guidelines listed below can be used to verify that the particular application will not cause the device to operate beyond its intended operating range.

Maximum power levels are set by the absolute maximum junction rating of 150°C. To calculate the junction temperature, the package thermal resistance value  $\theta_{JA}$  ( $\theta_{JA}$ ) is used along with the total die power dissipation.

$$T_{\text{Junction}} = T_{\text{Ambient}} + (\theta_{JA} \times P_D)$$

Where  $T_{\text{Ambient}}$  is the temperature of the working environment.



In order to determine  $P_D$ , the power dissipated in the load needs to be subtracted from the total power delivered by the supplies.

$$P_D = P_{\text{supply}} - P_{\text{load}}$$

Supply power is calculated by the standard power equation.

$$P_{\text{supply}} = V_{\text{supply}} \times I_{\text{RMSsupply}}$$

$$V_{\text{supply}} = V_{S+} - V_{S-}$$

Power delivered to a purely resistive load is:

$$P_{\text{load}} = ((V_{\text{load}})_{\text{RMS}})^2 / R_{\text{load eff}}$$

The effective load resistor ( $R_{\text{load eff}}$ ) will need to include the effect of the feedback network. For instance,  $R_{\text{load eff}}$  in Figure 3 would be calculated as:

$$R_L \parallel (R_f + R_g)$$

These measurements are basic and are relatively easy to perform with standard lab equipment. For design purposes however, prior knowledge of actual signal levels and load impedance is needed to determine the dissipated power. Here,  $P_D$  can be found from

$$P_D = P_{\text{Quiescent}} + P_{\text{Dynamic}} - P_{\text{load}}$$

Quiescent power can be derived from the specified  $I_S$  values along with known supply voltage,  $V_{\text{supply}}$ . Load power can be calculated as above with the desired signal amplitudes using:

$$(V_{\text{load}})_{\text{RMS}} = V_{\text{peak}} / \sqrt{2}$$

$$(I_{\text{load}})_{\text{RMS}} = (V_{\text{load}})_{\text{RMS}} / R_{\text{load eff}}$$

The dynamic power is focused primarily within the output stage driving the load. This value can be calculated as:

$$P_{\text{Dynamic}} = (V_{S+} - V_{\text{load}})_{\text{RMS}} \times (I_{\text{load}})_{\text{RMS}}$$

Assuming the load is referenced in the middle of the power rails or  $V_{\text{supply}}/2$ .

The CLC2011 is short circuit protected. However, this may not guarantee that the maximum junction temperature ( $+150^\circ\text{C}$ ) is not exceeded under all conditions. Figure 5 shows the maximum safe power dissipation in the package vs. the ambient temperature for the packages available.

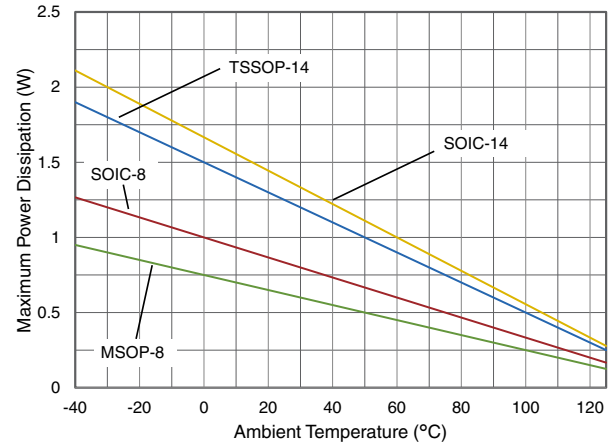


Figure 5. Maximum Power Derating

### Input Common Mode Voltage

The common mode input range extends to 250mV below ground and to 250mV above  $V_S$ , in single supply operation. Exceeding these values will not cause phase reversal. However, if the input voltage exceeds the rails by more than 0.5V, the input ESD devices will begin to conduct. The output will stay at the rail during this overdrive condition. If the absolute maximum input voltage (700mV beyond either rail) is exceeded, externally limit the input current to  $\pm 5\text{mA}$  as shown in Figure 6.

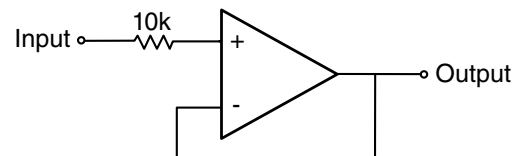


Figure 6. Circuit for Input Current Protection

### Driving Capacitive Loads

Increased phase delay at the output due to capacitive loading can cause ringing, peaking in the frequency response, and possible unstable behavior. Use a series resistance,  $R_S$ , between the amplifier and the load to help improve stability and settling performance. Refer to Figure 7.

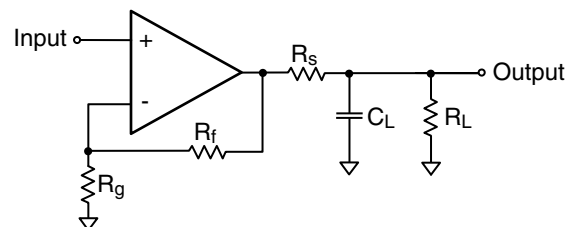


Figure 7. Addition of  $R_S$  for Driving Capacitive Loads

Table 1 provides the recommended  $R_S$  for various capacitive loads. The recommended  $R_S$  values result in approximately <1dB peaking in the frequency response. The Frequency Response vs. CL plot, on page 6, illustrates the response of the CLCx011.

$C_L$ (pF)	$R_S$ ( $\Omega$ )	-3dB BW (MHz)
10pF	0	2.2
20pF	0	2.4
50pF	0	2.5
100pF	100	2

Table 1: Recommended  $R_S$  vs.  $C_L$

For a given load capacitance, adjust  $R_S$  to optimize the tradeoff between settling time and bandwidth. In general, reducing  $R_S$  will increase bandwidth at the expense of additional overshoot and ringing.

### Overdrive Recovery

An overdrive condition is defined as the point when either one of the inputs or the output exceed their specified voltage range. Overdrive recovery is the time needed for the amplifier to return to its normal or linear operating point. The recovery time varies, based on whether the input or output is overdriven and by how much the range is exceeded. The CLCx011 will typically recover in less than 50ns from an overdrive condition. Figure 8 shows the CLC2011 in an overdriven condition.

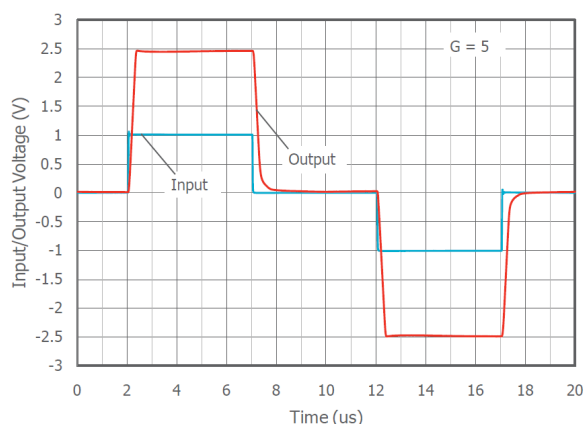


Figure 8: Overdrive Recovery

### Layout Considerations

General layout and supply bypassing play major roles in high frequency performance. Resurgent has evaluation boards to use as a guide for high frequency layout and as an aid in device testing and characterization. Follow the steps below as a basis for high frequency layout:

- Include 6.8 $\mu$ F and 0.1 $\mu$ F ceramic capacitors for power supply decoupling
- Place the 6.8 $\mu$ F capacitor within 0.75 inches of the power pin
- Place the 0.1 $\mu$ F capacitor within 0.1 inches of the power pin
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance
- Minimize all trace lengths to reduce series inductances

Refer to the evaluation board layouts below for more information.

### Evaluation Board Information

The following evaluation boards are available to aid in the testing and layout of these devices:

Evaluation Board #	Products
CEB006	CLC2011 in SOIC
CEB010	CLC2011 in MSOP
CEB019	CLC4011 in TSSOP
CEB018	CLC4011 in SOIC

### Evaluation Board Schematics

Evaluation board schematics and layouts are shown in Figures 9-16. These evaluation boards are built for dual-supply operation. Follow these steps to use the board in a single-supply application:

1. Short  $-V_S$  to ground.
2. Use C3 and C4, if the  $-V_S$  pin of the amplifier is not directly connected to the ground plane.

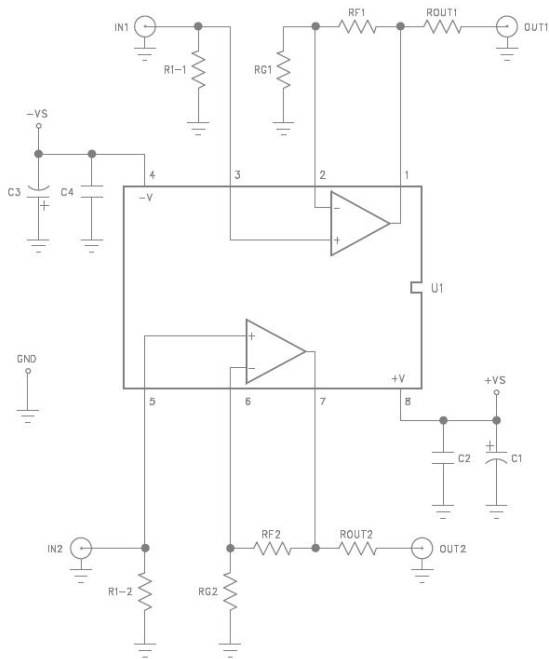


Figure 9. CEB006 &amp; CEB010 Schematic

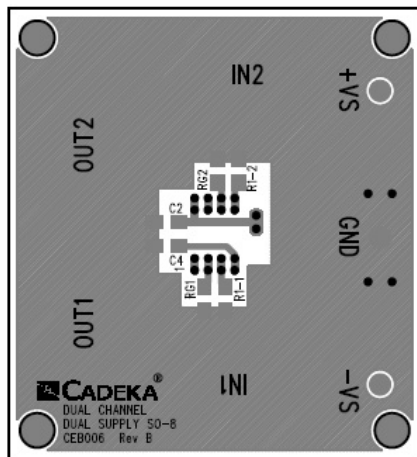


Figure 10. CEB006 Top View

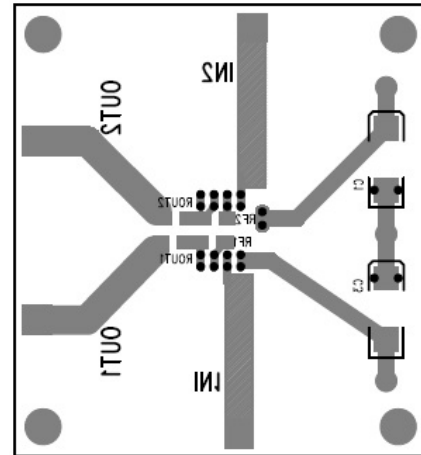


Figure 11. CEB006 Bottom View

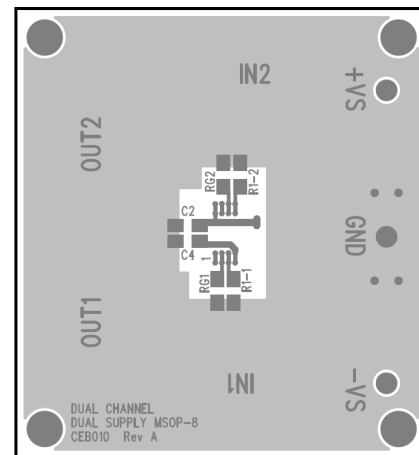


Figure 12. CEB010 Top View

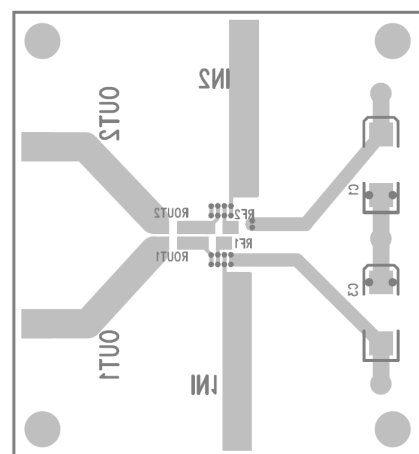


Figure 13. CEB010 Bottom View

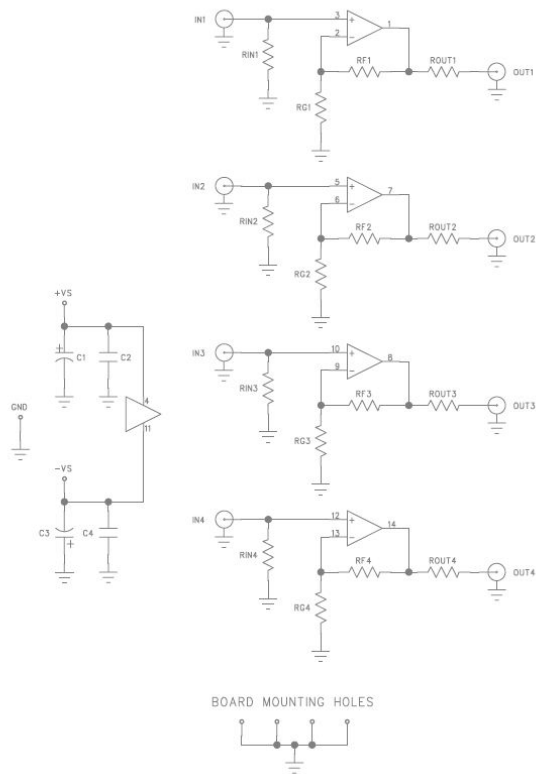


Figure 14. CEB018 Schematic

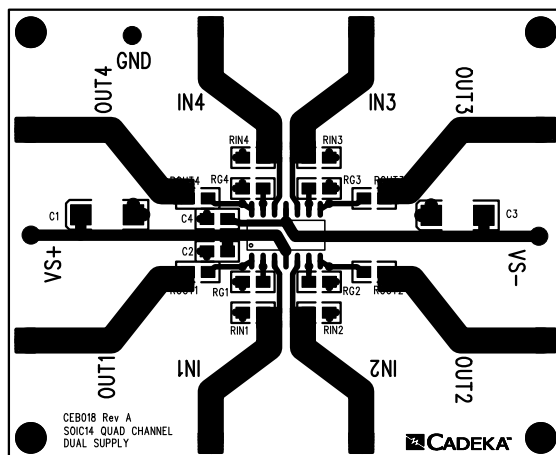


Figure 15. CEB018 Top View

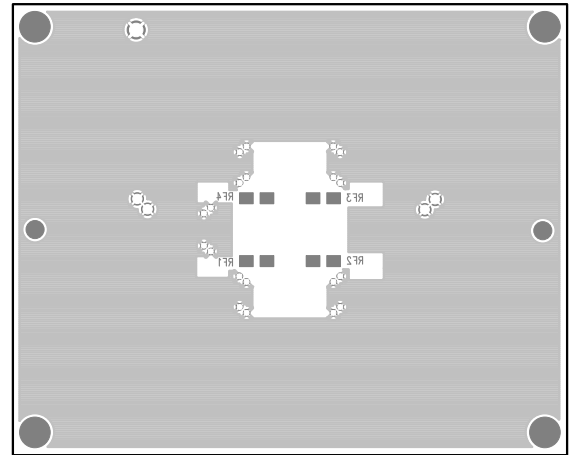
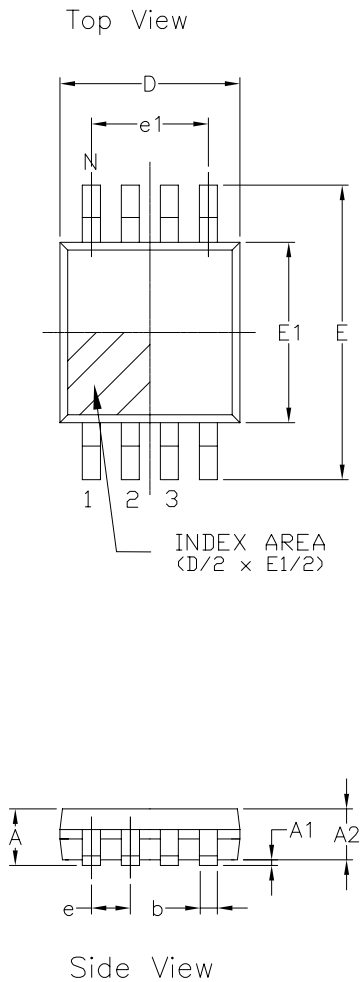


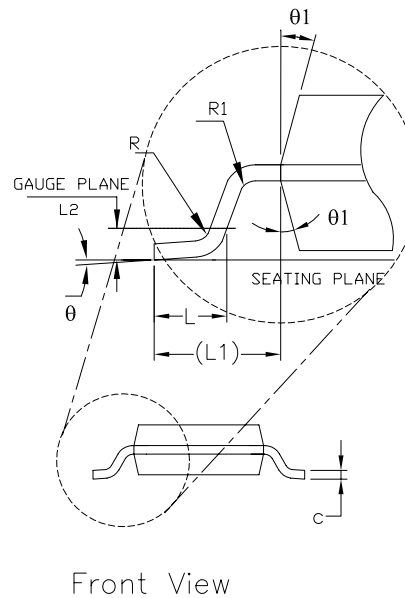
Figure 16. CEB018 Bottom View

## Mechanical Dimensions

## MSOP-8

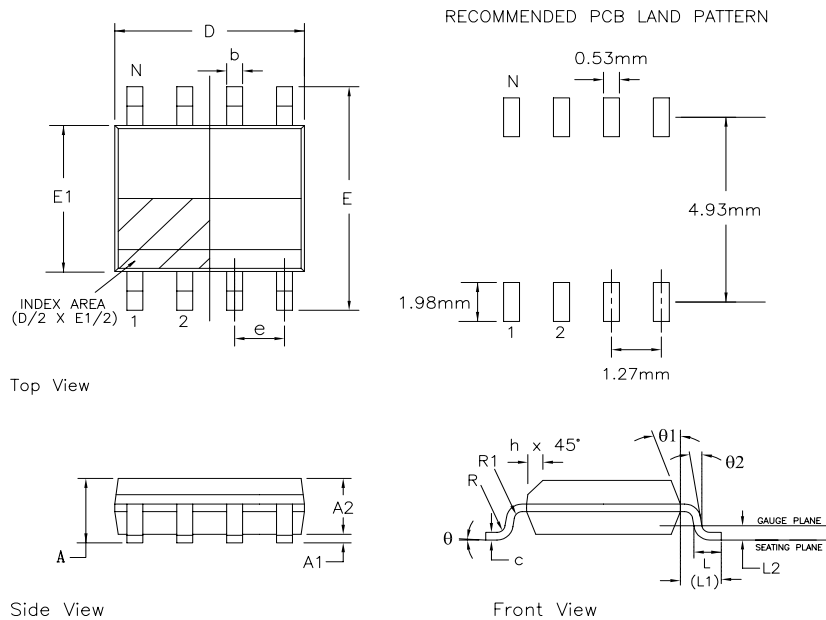


8 Pin MSOP JEDEC MO-187 Variation AA						
SYMBOLS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	—	—	1.10	—	—	0.043
A1	0.00	—	0.15	0.000	—	0.006
A2	0.75	0.85	0.95	0.030	0.033	0.037
b	0.22	—	0.38	0.009	—	0.015
c	0.08	—	0.23	0.003	—	0.009
E	4.90 BSC			0.193 BSC		
E1	3.00 BSC			0.118 BSC		
e	0.65 BSC			0.026 BSC		
e1	1.95 BSC			0.077 BSC		
L	0.40	0.60	0.80	0.016	0.024	0.031
L1	0.95 REF			0.037 REF		
L2	0.25 BSC			0.010 BSC		
R	0.07	—	—	0.003	—	—
R1	0.07	—	—	0.003	—	—
θ	0°	—	8°	0°	—	8°
θ1	5°	—	15°	5°	—	15°
D	3.00 BSC			0.118 BSC		
N	8			8		



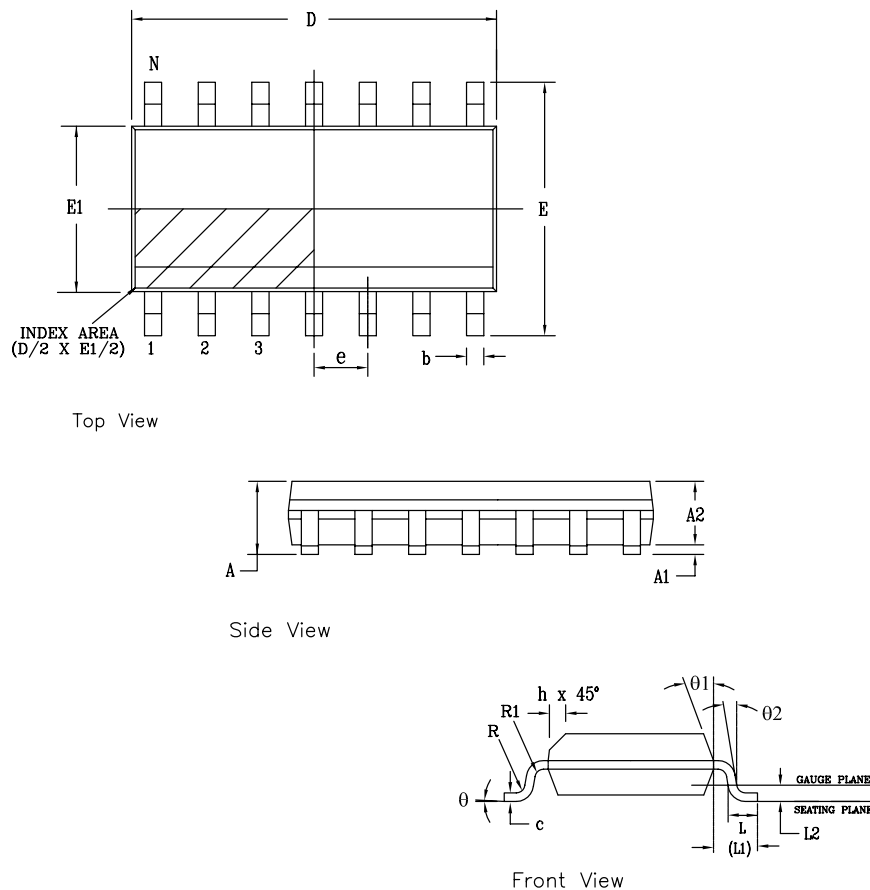
## Mechanical Dimensions

## SOIC-8 Package



8 Pin SOICN JEDEC MS-012 Variation AA						
SYMBOLS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	1.35	—	1.75	0.053	—	0.069
A1	0.10	—	0.25	0.004	—	0.010
A2	1.25	—	1.65	0.049	—	0.065
b	0.31	—	0.51	0.012	—	0.020
c	0.17	—	0.25	0.007	—	0.010
E	6.00 BSC			0.236 BSC		
E1	3.90 BSC			0.154 BSC		
e	1.27 BSC			0.050 BSC		
h	0.25	—	0.50	0.010	—	0.020
L	0.40	—	1.27	0.016	—	0.050
L1	1.04 REF			0.041 REF		
L2	0.25 BSC			0.010 BSC		
R	0.07	—	—	0.003	—	—
R1	0.07	—	—	0.003	—	—
θ	0°	—	8°	0°	—	8°
θ1	5°	—	15°	5°	—	15°
θ2	0°	—	—	0°	—	—
D	4.90 BSC			0.193 BSC		
N	8			8		

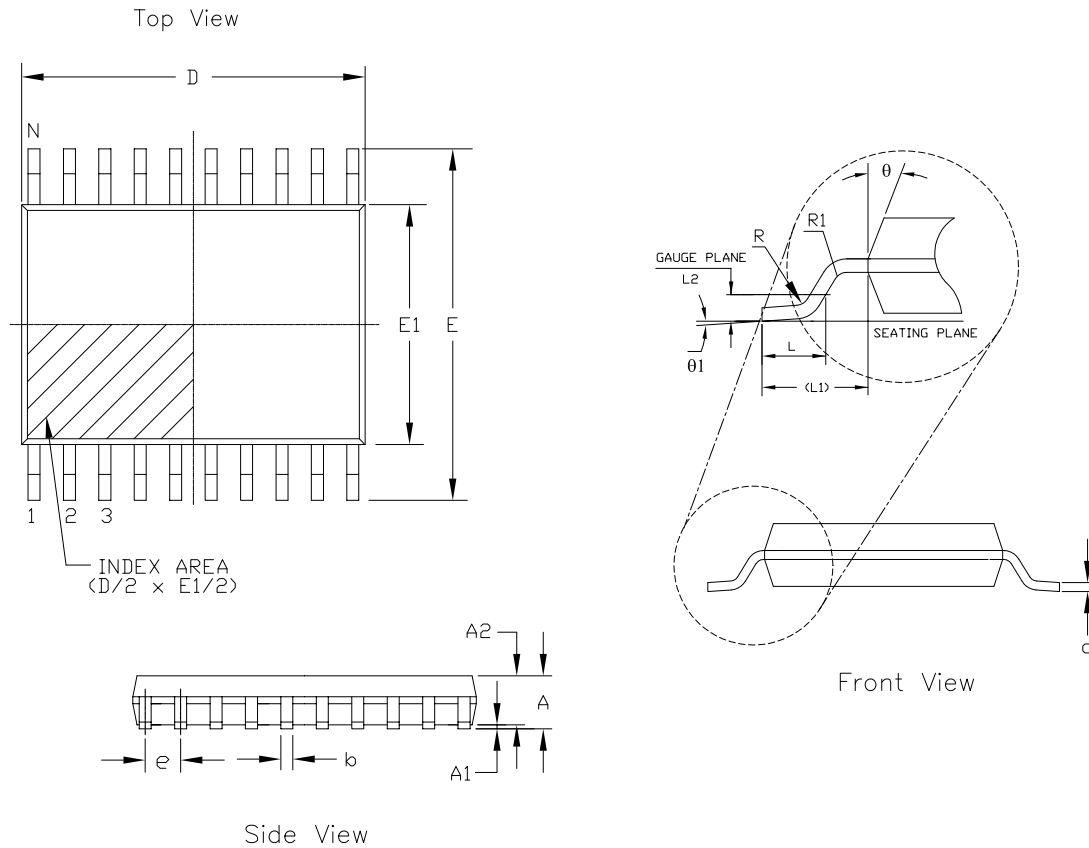
## SOIC-14 Package



PACKAGE OUTLINE NSOIC .150" BODY JEDEC MS-012						
SYMBOLS	COMMON DIMENSIONS IN MM (Control Unit)			COMMON DIMENSIONS IN INCH (Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	1.35	—	1.75	0.053	—	0.069
A1	0.10	—	0.25	0.004	—	0.010
A2	1.25	—	1.65	0.049	—	0.065
b	0.31	—	0.51	0.012	—	0.020
c	0.17	—	0.25	0.007	—	0.010
E	6.00 BSC			0.236 BSC		
E1	3.90 BSC			0.154 BSC		
e	1.27 BSC			0.050 BSC		
h	0.25	—	0.50	0.010	—	0.020
L	0.40	—	1.27	0.016	—	0.050
L1	1.04 REF			0.041 REF		
L2	0.25 BSC			0.010 BSC		
R	0.07	—	—	0.003	—	—
R1	0.07	—	—	0.003	—	—
θ	0°	—	8°	0°	—	8°
θ1	5°	—	15°	5°	—	15°
θ2	0°	—	—	0°	—	—
D	SEE VARIATIONS					
N	SEE VARIATIONS					

VARIATION D						
SYMBOLS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
AA	4.90 BSC			0.193 BSC		
AB	8.65 BSC			0.341 BSC		
AC	9.90 BSC			0.390 BSC		

## TSSOP-14 Package



14 Pin TSSOP JEDEC MO-153 Variation AB-1						
SYMBOLS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
A	—	—	1.20	—	—	0.047
A1	0.05	—	0.15	0.002	—	0.006
A2	0.80	1.00	1.05	0.031	0.039	0.041
b	0.19	—	0.30	0.007	—	0.012
c	0.09	—	0.20	0.004	—	0.008
E	6.40 BSC			0.252 BSC		
E1	4.30	4.40	4.50	0.169	0.173	0.177
e	0.65 BSC			0.026 BSC		
L	0.45	0.60	0.75	0.018	0.024	0.030
L1	1.00 REF			0.039 REF		
L2	0.25 BSC			0.010 BSC		
R	0.09	—	—	0.035	—	—
R1	0.09	—	—	0.035	—	—
$\theta$	12° REF			12° REF		
$\theta1$	0°	—	8°	0°	—	8°
D	4.90	5.00	5.10	0.193	0.197	0.200
N	14			14		

## Ordering Information

Part Number	Package	Green	Operating Temperature Range	Packaging
CLC2011 Ordering Information				
CLC2011ISO8X	SOIC-8	Yes	-40°C to +125°C	Tape & Reel
CLC2011ISO8MTR	SOIC-8	Yes	-40°C to +125°C	Mini Tape & Reel
CLC2011ISO8EVB	Evaluation Board	N/A	N/A	N/A
CLC2011IMP8X	MSOP-8	Yes	-40°C to +125°C	Tape & Reel
CLC2011IMP8MTR	MSOP-8	Yes	-40°C to +125°C	Mini Tape & Reel
CLC2011IMP8EVB	Evaluation Board	N/A	N/A	N/A
CLC4011 Ordering Information				
CLC4011ISO14X	SOIC-14	Yes	-40°C to +125°C	Tape & Reel
CLC4011ISO14MTR	SOIC-14	Yes	-40°C to +125°C	Mini Tape & Reel
CLC4011ISO14EVB	Evaluation Board	N/A	N/A	N/A
CLC4011ITP14X	TSSOP-14	Yes	-40°C to +125°C	Tape & Reel
CLC4011ITP14MTR	TSSOP-14	Yes	-40°C to +125°C	Mini Tape & Reel
CLC4011ITP14EVB	Evaluation Board	N/A	N/A	N/A

Moisture sensitivity level for all parts is MSL-1. Mini tape and reel quantity is 250.

## Revision History

Revision	Date	Description
1D (ECN 1504-01)	January 19, 2015	Reformat into Exar data sheet template. Updated PODs and thermal resistance numbers. Updated ordering information table to include MTR and EVB part numbers. Increased operating temperature to +125°C.
1D.R	July 2018	Updated to Resurgent Semiconductor.

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