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4/2007—Revision 0: Initial Version

# **SPECIFICATIONS**

 $V_{\text{DD}}$  = 5.0 V;  $T_{\text{A}}$  = 25°C;  $R_{\text{L}}$  = 4  $\Omega,$  8  $\Omega;$  gain = 6 dB, unless otherwise noted.

Table 1.

Parameter	Symbol	Test Conditions/Comments	Min	Тур	Max	Unit
DEVICE CHARACTERISTICS						
Output Power	Po	$R_L = 4 \Omega$ , THD = 1%, f = 1 kHz, 20 kHz BW, $V_{DD} = 5.0 \text{ V}$		1.8		W
		$R_L = 8 \Omega$ , THD = 1%, f = 1 kHz, 20 kHz BW, $V_{DD} = 5.0 \text{ V}$		1.4		W
		$R_L = 4 \Omega$ , THD = 1%, f = 1 kHz, 20 kHz BW, $V_{DD} = 3.6 V$		0.9		W
		$R_L = 8 \Omega$ , THD = 1%, f = 1 kHz, 20 kHz BW, $V_{DD} = 3.6 V$		0.615		W
		$R_L = 4 \Omega$ , THD = 1%, f = 1 kHz, 20 kHz BW, $V_{DD} = 2.5 V$		0.35		W
		$R_L = 8 \Omega$ , THD = 1%, f = 1 kHz, 20 kHz BW, $V_{DD} = 2.5 V$		0.275		W
		$R_L = 4 \Omega$ , THD = 10%, f = 1 kHz, 20 kHz BW, $V_{DD} = 5.0 V$		2.4		W
		$R_L = 8 \Omega$ , THD = 10%, f = 1 kHz, 20 kHz BW, $V_{DD} = 5.0 V$		1.53		W
		$R_L = 4 \Omega$ , THD = 10%, f = 1 kHz, 20 kHz BW, $V_{DD} = 3.6 V$		1.1		W
		$R_L = 8 \Omega$ , THD = 10%, f = 1 kHz, 20 kHz BW, $V_{DD} = 3.6 V$		0.77		W
		$R_L = 4 \Omega$ , THD = 10%, f = 1 kHz, 20 kHz BW, $V_{DD} = 2.5 V$		0.45		W
		$R_L = 8 \Omega$ , THD = 10%, f = 1 kHz, 20 kHz BW, $V_{DD} = 2.5 V$		0.35		W
Efficiency	η	$P_{OUT} = 2 \text{ W}, 4 \Omega, V_{DD} = 5.0 \text{ V}$		75		%
		$P_{OUT} = 1.4 \text{ W}, 8 \Omega, V_{DD} = 5.0 \text{ V}$		85		%
Total Harmonic Distortion + Noise	THD + N	$P_0 = 2 \text{ W into } 4 \Omega \text{ each channel, } f = 1 \text{ kHz, } V_{DD} = 5.0 \text{ V}$		0.4		%
		$P_O = 1$ W into 8 $\Omega$ each channel, $f = 1$ kHz, $V_{DD} = 5.0$ V		0.02		%
Input Common-Mode Voltage Range	V <sub>CM</sub>		1.0		$V_{\text{DD}}-1$	٧
Common-Mode Rejection Ratio	CMRR <sub>GSM</sub>	$V_{CM} = 2.5 \text{ V} \pm 100 \text{ mV}$ at 217 Hz, $G = 18 \text{ dB}$ , input referred		70		dB
Channel Separation	X <sub>TALK</sub>	$P_0 = 100 \text{ mW}, f = 1 \text{ kHz}$		78		dB
Average Switching Frequency	$f_{\text{SW}}$			420		kHz
Differential Output Offset Voltage	Voos			2.0		mV
POWER SUPPLY						
Supply Voltage Range	$V_{\text{DD}}$	Guaranteed from PSRR test	2.5		5.0	V
Power Supply Rejection Ratio	PSRR	$V_{DD} = 2.5 \text{ V to } 5.0 \text{ V}$	70	85		dB
	PSRR <sub>GSM</sub>	$V_{RIPPLE}$ = 100 mV rms at 217 Hz, inputs ac GND, $C_{IN}$ = 0.1 $\mu$ F, input referred		75		dB
Supply Current	I <sub>SY</sub>	$V_{IN} = 0 \text{ V}$ , no load, $V_{DD} = 5.0 \text{ V}$		6.5		mA
		$V_{IN} = 0 \text{ V}$ , no load, $V_{DD} = 3.6 \text{ V}$		5.7		mA
		$V_{IN} = 0 \text{ V, no load, } V_{DD} = 2.5 \text{ V}$		5.1		mA
Shutdown Current	I <sub>SD</sub>	$\overline{SD} = GND$		20		nA
GAIN						
Closed-Loop Gain	Av	$R_{EXT} = 0$		18		dB
Differential Input Impedance	Z <sub>IN</sub>	$\overline{SD} = VDD$		43		kΩ
SHUTDOWN CONTROL						
Input Voltage High	V <sub>IH</sub>	$I_{SY} \ge 1 \text{ mA}$		1.2		V
Input Voltage Low	V <sub>IL</sub>	I <sub>SY</sub> ≤ 300 nA		0.5		V
Turn-On Time	tw∪	SD rising edge from GND to V <sub>DD</sub>		30		ms
Turn-Off Time	t <sub>SD</sub>	SD falling edge from V <sub>DD</sub> to GND		5		μs
Output Impedance	Оит	$\overline{SD} = GND$		>100		kΩ
NOISE PERFORMANCE	1		+			
Output Voltage Noise	e <sub>n</sub>	$V_{DD} = 3.6 \text{ V}$ , $f = 20 \text{ Hz}$ to 20 kHz, inputs are ac-grounded, $A_V = 18 \text{ dB}$ , $R_L = 4 \Omega$ , A weighting		44		μV
	1	J	1			1

### **ABSOLUTE MAXIMUM RATINGS**

Absolute maximum ratings apply at 25°C, unless otherwise noted.

#### Table 2.

Parameter	Rating
Supply Voltage	6 V
Input Voltage	$V_{DD}$
Common-Mode Input Voltage	$V_{DD}$
ESD Susceptibility	4 kV
Storage Temperature Range	−65°C to +150°C
Operating Temperature Range	−40°C to +85°C
Junction Temperature Range	−65°C to +165°C
Lead Temperature (Soldering, 60 sec)	300°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

#### THERMAL RESISTANCE

 $\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

Table 3. Thermal Resistance

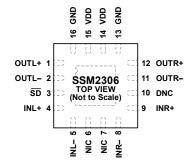
Package Type	θја	<b>Ө</b> лс	Unit
16-Lead, 3 mm × 3 mm LFCSP	44	31.5	°C/W

### **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

# PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



- NOTES
  1. NIC = NO INTERNAL CONNECTION.
  2. DNC = DO NOT CONNECT.
  3. CONNECT THE EXPOSED PAD TO THE GROUND PLANE OF THE PCB.

Figure 2. Pin Configuration

**Table 4. Pin Function Descriptions** 

Pin No.	Mnemonic	Description
1	OUTL+	Inverting Output for Left Channel.
2	OUTL-	Noninverting Output for Left Channel.
3	SD	Shutdown Input. Active low digital input.
4	INL+	Noninverting Input for Left Channel.
5	INL-	Inverting Input for Left Channel.
6, 7	NIC	No Internal Connection.
8	INR-	Inverting Input for Right Channel.
9	INR+	Noninverting Input for Right Channel.
10	DNC	Do Not Connect.
11	OUTR-	Noninverting Output for Right Channel.
12	OUTR+	Inverting Output for Right Channel.
13	GND	Ground for Output Amplifiers.
14	VDD	Power Supply for Output Amplifiers.
15	VDD	Power Supply for Output Amplifiers.
16	GND	Ground for Output Amplifiers.
0	EPAD	Exposed Pad. Connect the exposed pad to the ground plane of the PCB.

## TYPICAL PERFORMANCE CHARACTERISTICS

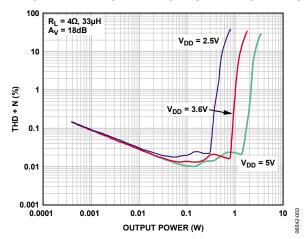


Figure 3. THD + N vs. Output Power into  $4 \Omega$ ,  $A_V = 18 dB$ 

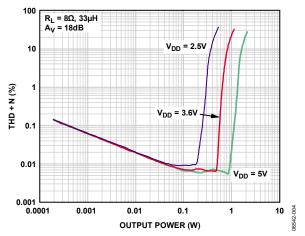


Figure 4. THD + N vs. Output Power into 8  $\Omega$ ,  $A_V = 18 \, dB$ 

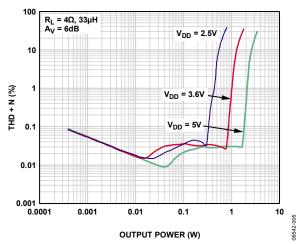


Figure 5. THD + N vs. Output Power into  $4 \Omega$ ,  $A_V = 6 dB$ 

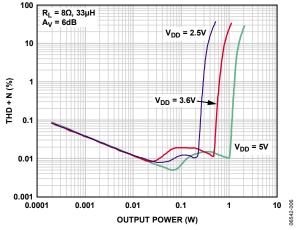


Figure 6. THD + N vs. Output Power into 8  $\Omega$ ,  $A_V = 6 dB$ 

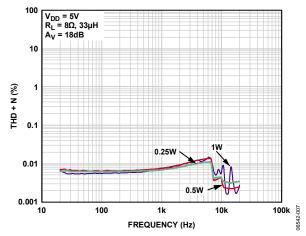


Figure 7. THD + N vs. Frequency,  $V_{DD} = 5 V$ ,  $R_L = 8 \Omega$ ,  $A_V = 18 dB$ 

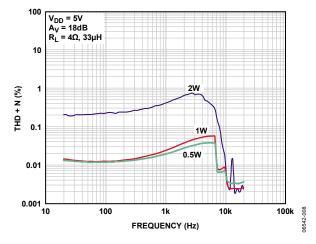


Figure 8. THD + N vs. Frequency,  $V_{DD}$  = 5 V,  $R_L$  = 4  $\Omega$ ,  $A_V$  = 18 dB

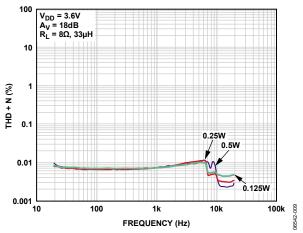


Figure 9. THD + N vs. Frequency,  $V_{DD} = 3.6 \text{ V}$ ,  $R_L = 8 \Omega$ ,  $A_V = 18 \text{ dB}$ 

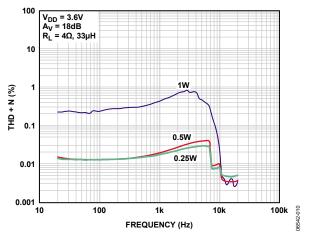


Figure 10. THD + N vs. Frequency,  $V_{DD} = 3.6 \text{ V}$ ,  $R_L = 4 \Omega$ ,  $A_V = 18 \text{ dB}$ 

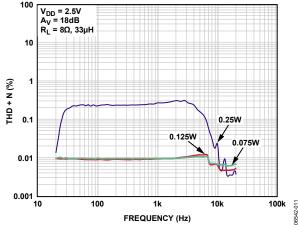


Figure 11. THD + N vs. Frequency,  $V_{DD} = 2.5 \text{ V}$ ,  $R_L = 8 \Omega$ ,  $A_V = 18 \text{ dB}$ 

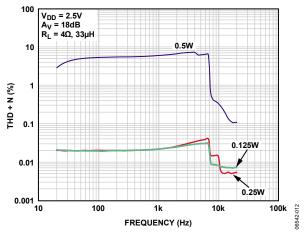


Figure 12. THD + N vs. Frequency,  $V_{DD}$  = 2.5 V,  $R_L$  = 4  $\Omega$ ,  $A_V$  = 18 dB

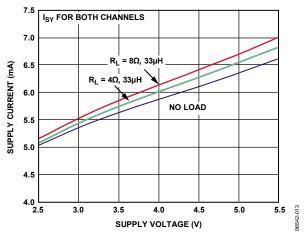


Figure 13. Supply Current vs. Supply Voltage, No Load

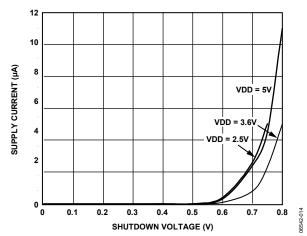


Figure 14. Supply Current vs. Shutdown Voltage

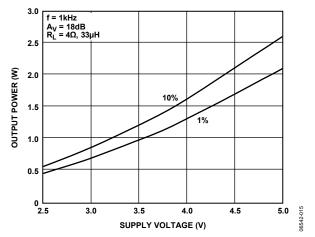


Figure 15. Maximum Output Power vs. Supply Voltage,  $R_L = 4 \Omega$ ,  $A_V = 18 dB$ 

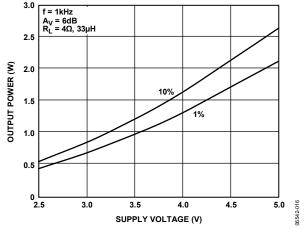


Figure 16.Maximum Output Power vs. Supply Voltage,  $R_L = 4 \Omega$ ,  $A_V = 6 dB$ 

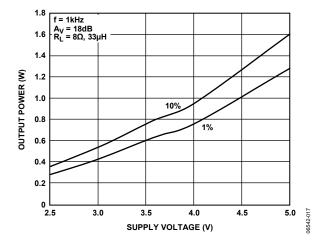


Figure 17. Maximum Output Power vs. Supply Voltage,  $R_L = 8 \Omega$ ,  $A_V = 18 dB$ 

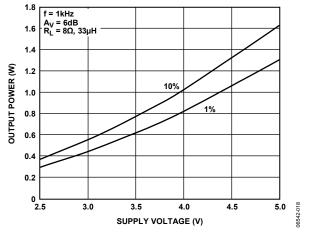


Figure 18. Maximum Output Power vs. Supply Voltage,  $R_L = 8 \Omega$ ,  $A_V = 6 dB$ 

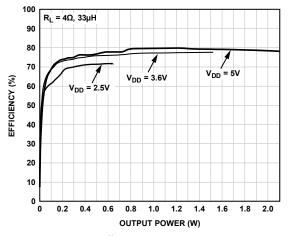


Figure 19. Efficiency vs. Output Power into 4  $\Omega$ 

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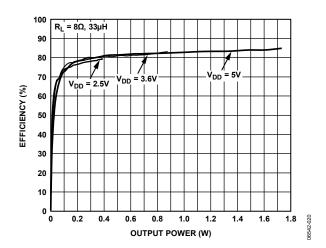


Figure 20. Efficiency vs. Output Power into 8  $\Omega$ 

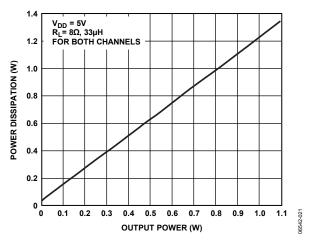


Figure 21. Power Dissipation vs. Output Power at  $V_{DD} = 5 \text{ V}$ ,  $R_L = 8 \Omega$ 

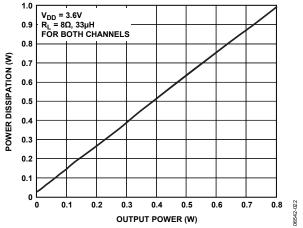


Figure 22. Power Dissipation vs. Output Power at  $V_{DD}$  = 3.6 V,  $R_L$  = 8  $\Omega$ 

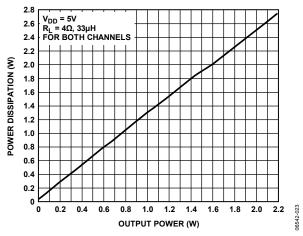


Figure 23. Power Dissipation vs. Output Power at  $V_{DD} = 5 \text{ V}$ ,  $R_L = 4 \Omega$ 

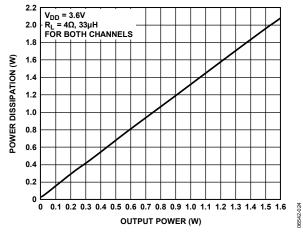


Figure 24. Power Dissipation vs. Output Power at  $V_{DD} = 3.6 \text{ V}$ ,  $R_L = 4 \Omega$ 

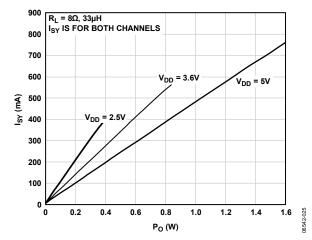


Figure 25. Supply Current vs. Output Power into 8  $\Omega$ 

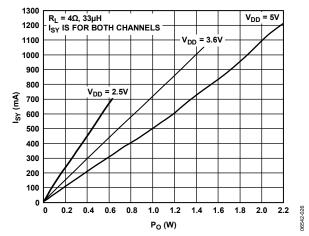


Figure 26. Supply Current vs. Output Power into 4  $\Omega$ 

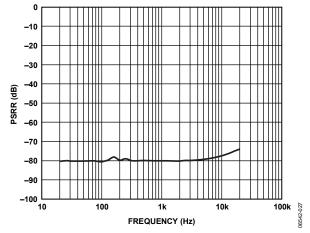


Figure 27. PSRR vs. Frequency

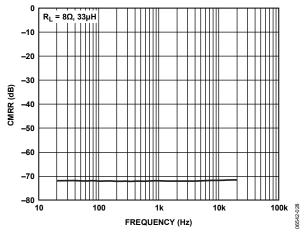


Figure 28. CMRR vs. Frequency

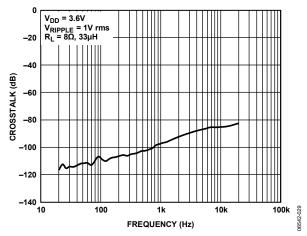


Figure 29. Crosstalk vs. Frequency

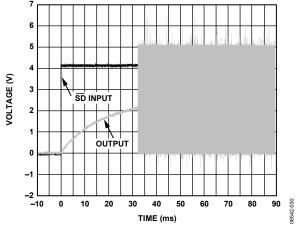


Figure 30. Turn-On Response

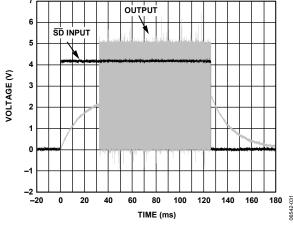


Figure 31. Turn-Off Response

### TYPICAL APPLICATION CIRCUITS

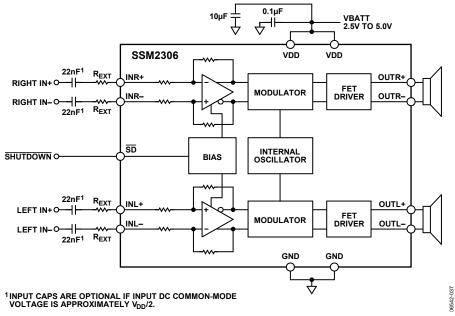


Figure 32. Stereo Differential Input Configuration

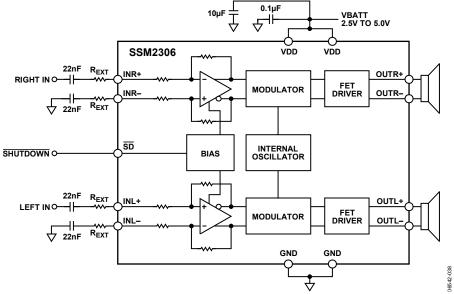


Figure 33. Stereo Single-Ended Input Configuration

### **APPLICATION NOTES**

#### **OVERVIEW**

The SSM2306 stereo, Class-D, audio amplifier features a filterless modulation scheme that greatly reduces the external components count, conserving board space and, thus, reducing systems cost. The SSM2306 does not require an output filter; instead, it relies on the inherent inductance of the speaker coil and the natural filtering capacity of the speaker and human ear to fully recover the audio component of the square wave output.

Although most Class-D amplifiers use some variation of pulsewidth modulation (PWM), the SSM2306 uses sigma-delta ( $\Sigma$ - $\Delta$ ) modulation to determine the switching pattern of the output devices. This provides a number of important benefits.  $\Sigma$ - $\Delta$  modulators do not produce a sharp peak with many harmonics in the AM frequency band, as pulse-width modulators often do.  $\Sigma$ - $\Delta$  modulation provides the benefits of reducing the amplitude of spectral components at high frequencies; that is, reducing EMI emission that might otherwise radiate by the use of speakers and long cable traces. The SSM2306 also offers protection circuits for overcurrent and overtemperature protection.

#### **GAIN SELECTION**

The SSM2306 has a pair of internal resistors that set an 18 dB default gain for the amplifier. It is possible to adjust the SSM2306 gain by using external resistors at the input. To set a gain lower than 18 dB, refer to Figure 32 for the differential input configuration and Figure 33 for the single-ended configuration. Calculate the external gain configuration as

External Gain Settings =  $344 \text{ k}\Omega/(43 \text{ k}\Omega + R_{EXT})$ 

### **POP-AND-CLICK SUPPRESSION**

Voltage transients at the output of audio amplifiers can occur with the activation or deactivation of shutdown. Furthermore, voltage transients as low as 10 mV are audible as an audio pop in the speaker. Likewise, clicks and pops are classified as undesirable audible transients generated by the amplifier system, and as such, as not coming from the system input signal. These types of transients generate when the amplifier system changes its operating mode. For example, the following can be sources of audible transients:

- System power-up/power-down
- Mute/unmute
- Input source change
- Sample rate change

The SSM2306 has a pop-and-click suppression architecture that reduces these output transients, resulting in noiseless activation and deactivation.

#### **EMI NOISE**

The SSM2306 uses a proprietary modulation and spread-spectrum technology to minimize EMI emissions from the device. Figure 34 shows the SSM2306 EMI emission starting from 100 kHz to 30 MHz. Figure 35 shows the SSM2306 EMI emission from 30 kHz to 2 GHz. These figures clearly depict the SSM2306 EMI behavior as being well below the FCC regulation values, starting from 100 kHz and passing beyond 1 GHz of frequency. Although the overall EMI noise floor is slightly higher, frequency spurs from the SSM2306 are greatly reduced.

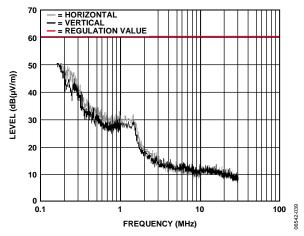


Figure 34. EMI Emissions from the SSM2306

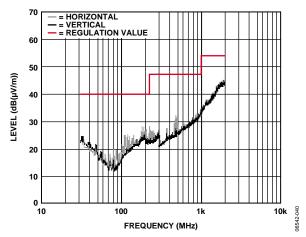


Figure 35. EMI Emissions from the SSM2306

The measurements for Figure 34 and Figure 35 were taken with a 1 kHz input signal, producing 0.5 W output power into an 8  $\Omega$  load from a 3.6 V supply. Cable length was approximately 5 cm. To detect EMI, a magnetic probe was used touching the 2-inch output trace to the load.

### **LAYOUT**

As output power continues to increase, careful layout is needed for proper placement of PCB traces and wires between the amplifier, load, and power supply. A good practice is to use short, wide PCB tracks to decrease voltage drops and minimize inductance. Make track widths at least 200 mil for every inch of track length for lowest DCR, and use 1 oz. or 2 oz. of copper PCB traces to further reduce IR drops and inductance. Poor layout increases voltage drops, consequently affecting efficiency. Use large traces for the power supply inputs and amplifier outputs to minimize losses due to parasitic trace resistance. Proper grounding guidelines help to improve audio performance, minimize crosstalk between channels, and prevent switching noise from coupling into the audio signal.

To maintain high output swing and high peak output power, the PCB traces that connect the output pins to the load and supply pins should be as wide as possible to maintain the minimum trace resistances. It is also recommended to use a large area ground plane for minimum impedances.

Good PCB layouts isolate critical analog paths from sources of high interference; furthermore, separate high frequency circuits (analog and digital) from low frequency ones. Properly designed multilayer printed circuit boards can reduce EMI emission and increase immunity to RF field by a factor of 10 or more compared with double-sided boards. A multilayer board allows a complete layer to be used for the ground plane, whereas the ground plane side of a double-sided board is often disrupted with signal crossover. If the system has separate analog and digital ground and power planes, the analog ground plane should be underneath the analog power plane, and, similarly, the digital ground plane should be underneath the digital power plane. There should be no overlap between analog and digital ground planes or analog and digital power planes.

#### INPUT CAPACITOR SELECTION

The SSM2306 does not require input coupling capacitors if the input signal is biased from 1.0 V to  $V_{\rm DD}-1.0$  V. Input capacitors are required if the input signal is not biased within this recommended input dc common-mode voltage range, if high-pass filtering is needed (see Figure 32), or if using a single-ended source (see Figure 33). If high-pass filtering is needed at the input, the input capacitor together with the input resistor of the SSM2306 form a high-pass filter whose corner frequency is determined by the following equation:

$$f_C = 1/(2\pi \times R_{IN} \times C_{IN})$$

Input capacitors can have very important effects on the circuit performance. Not using input capacitors degrades the output offset of the amplifier as well as the PSRR performance.

### PROPER POWER SUPPLY DECOUPLING

To ensure high efficiency, low total harmonic distortion (THD), and high PSRR, proper power supply decoupling is necessary. Noise transients on the power supply lines are short duration voltage spikes. Although the actual switching frequency can range from 10 kHz to 100 kHz, these spikes can contain frequency components that extend into the hundreds of megahertz. The power supply input needs to be decoupled with a good quality, low ESL and low ESR capacitor, usually around 4.7  $\mu F$ . This capacitor bypasses low frequency noises to the ground plane. For high frequency transients noises, use a 0.1  $\mu F$  capacitor as close as possible to the VDD pin of the device. Placing the decoupling capacitor as close as possible to the SSM2306 helps maintain efficiency performance.

### **OUTLINE DIMENSIONS**

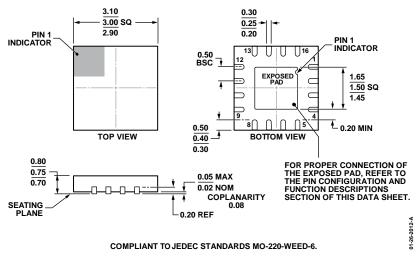


Figure 36. 16-Lead Lead Frame Chip Scale Package [LFCSP] 3 mm × 3 mm Body and 0.75 mm Package Height (CP-16-27) Dimensions shown in millimeters

### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Package Option	Branding
SSM2306CPZ-R2	-40°C to +85°C	16-Lead Lead Frame Chip Scale Package [LFCSP]	CP-16-27	A1R
SSM2306CPZ-REEL	-40°C to +85°C	16-Lead Lead Frame Chip Scale Package [LFCSP]	CP-16-27	A1R
SSM2306CPZ-REEL7	-40°C to +85°C	16-Lead Lead Frame Chip Scale Package [LFCSP]	CP-16-27	A1R

<sup>&</sup>lt;sup>1</sup> Z = RoHS Compliant Part.

# **NOTES**

**NOTES** 

