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- AN-737: How ADIsimADC Models an ADC
- AN-742: Frequency Domain Response of Switched-Capacitor ADCs
- AN-756: Sampled Systems and the Effects of Clock Phase Noise and Jitter
- AN-803: Pin Compatible High Speed ADCs Simplify Design Tasks
- AN-807: Multicarrier WCDMA Feasibility
- AN-808: Multicarrier CDMA2000 Feasibility
- AN-827: A Resonant Approach to Interfacing Amplifiers to Switched-Capacitor ADCs
- AN-835: Understanding High Speed ADC Testing and Evaluation
- AN-878: High Speed ADC SPI Control Software
- AN-905: Visual Analog Converter Evaluation Tool Version 1.0 User Manual
- AN-935: Designing an ADC Transformer-Coupled Front End

Data Sheet

- AD9634: 12-Bit, 170 MSPS/210 MSPS/250 MSPS, 1.8 V Analog-to-Digital Converter Data Sheet

User Guides

- AD9634 Quick Start Guide
- UG-386: Evaluating the AD9642/AD9634/AD6672 Analog-to-Digital Converters

TOOLS AND SIMULATIONS

- Visual Analog
- AD9634 IBIS Model

REFERENCE MATERIALS

Technical Articles

- MS-2210: Designing Power Supplies for High Speed ADC

DESIGN RESOURCES

- AD9634 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints

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TABLE OF CONTENTS

Features	1	ADC Architecture	19
Applications	1	Analog Input Considerations	19
Functional Block Diagram	1	Voltage Reference	21
General Description	1	Clock Input Considerations	21
Product Highlights	1	Power Dissipation and Standby Mode	23
Revision History	2	Digital Outputs	23
Specifications	3	ADC Overrange (OR)	23
ADC DC Specifications	3	Serial Port Interface (SPI)	24
ADC AC Specifications	4	Configuration Using the SPI	24
Digital Specifications	6	Hardware Interface	24
Switching Specifications	7	SPI Accessible Features	25
Timing Specifications	8	Memory Map	26
Absolute Maximum Ratings	9	Reading the Memory Map Register Table	26
Thermal Characteristics	9	Memory Map Register Table	27
ESD Caution	9	Applications Information	29
Pin Configuration and Function Descriptions	10	Design Guidelines	29
Typical Performance Characteristics	12	Outline Dimensions	30
Equivalent Circuits	18	Ordering Guide	30
Theory of Operation	19		

REVISION HISTORY

12/14—Rev. A to Rev. B

Changes to Features Section	1
Changes to Reading the Memory Map Register Table Section	26
Changes to Table 13	28

7/14—Rev. 0 to Rev. A

Changes to Features Section	1
Changes to Full Power Bandwidth Parameter, Table 2	5
Deleted Noise Bandwidth Parameter, Table 2	5

7/11—Revision 0: Initial Version

SPECIFICATIONS

ADC DC SPECIFICATIONS

AVDD = 1.8 V, DRVDD = 1.8 V, maximum sample rate, VIN = −1.0 dBFS differential input, 1.75 V p-p full scale input range, DCS enabled, unless otherwise noted.

Table 1.

Parameter	Temperature	AD9634-170			AD9634-210			AD9634-250			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
RESOLUTION	Full	12			12			12			Bits
ACCURACY											
No Missing Codes	Full	Guaranteed			Guaranteed			Guaranteed			
Offset Error	Full			±11			±11			±11	mV
Gain Error	Full			+2/−11			+1/−8			+3/−7	%FSR
Differential Nonlinearity (DNL)	Full			±0.4			±0.4			±0.4	LSB
	25°C		±0.22			±0.22			±0.22		LSB
Integral Nonlinearity (INL) ¹	Full			±0.4			±0.4			±0.6	LSB
	25°C		±0.2			±0.2			±0.27		LSB
TEMPERATURE DRIFT											
Offset Error	Full		±7			±7			±7		ppm/°C
Gain Error	Full		±55			±58			±75		ppm/°C
INPUT REFERRED NOISE											
VREF = 1.0 V	25°C		0.531			0.391			0.407		LSB rms
ANALOG INPUT											
Input Span	Full		1.75			1.75			1.75		V p-p
Input Capacitance ²	Full		2.5			2.5			2.5		pF
Input Resistance ³	Full		20			20			20		kΩ
Input Common-Mode Voltage	Full		0.9			0.9			0.9		V
POWER SUPPLIES											
Supply Voltage											
AVDD	Full	1.7	1.8	1.9	1.7	1.8	1.9	1.7	1.8	1.9	V
DRVDD	Full	1.7	1.8	1.9	1.7	1.8	1.9	1.7	1.8	1.9	V
Supply Current											
I _{AVDD} ¹	Full		123	134		129	139		136	145	mA
I _{DRVDD} ¹	Full		50	54		56	60		64	68	mA
POWER CONSUMPTION											
Sine Wave Input (DRVDD = 1.8 V)	Full		311	340		333	360		360	385	mW
Standby Power ⁴	Full		50			50			50		mW
Power-Down Power	Full		5			5			5		mW

¹ Measured with a low input frequency, full-scale sine wave.

² Input capacitance refers to the effective capacitance between one differential input pin and its complement.

³ Input resistance refers to the effective resistance between one differential input pin and its complement.

⁴ Standby power is measured with a dc input and the CLK pin inactive (that is, set to AVDD or AGND).

ADC AC SPECIFICATIONS

AVDD = 1.8 V, DRVDD = 1.8 V, maximum sample rate, VIN = –1.0 dBFS differential input, 1.75 V p-p full-scale input range, unless otherwise noted.

Table 2.

Parameter ¹	Temperature	AD9634-170			AD9634-210			AD9634-250			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
SIGNAL-TO-NOISE RATIO (SNR)											
f _{IN} = 30 MHz	25°C		70.3			70.2			70.1		dBFS
f _{IN} = 90 MHz	25°C		70.1			70.1			70.0		dBFS
	Full	69.1			68.8						dBFS
f _{IN} = 140 MHz	25°C		69.9			70.0			69.9		dBFS
f _{IN} = 185 MHz	25°C		69.5			69.6			69.7		dBFS
	Full							67.8			dBFS
f _{IN} = 220 MHz	25°C		69.2			69.2			69.3		dBFS
SIGNAL-TO-NOISE AND DISTORTION (SINAD)											
f _{IN} = 30 MHz	25°C		69.4			69.2			69.2		dBFS
f _{IN} = 90 MHz	25°C		69.2			69.1			69.0		dBFS
	Full	68.1			67.8						dBFS
f _{IN} = 140 MHz	25°C		68.9			69.1			69.0		dBFS
f _{IN} = 185 MHz	25°C		68.5			68.7			68.7		dBFS
	Full							66.7			dBFS
f _{IN} = 220 MHz	25°C		68.3			68.3			68.4		dBFS
EFFECTIVE NUMBER OF BITS (ENOB)											
f _{IN} = 30 MHz	25°C		11.2			11.2			11.2		Bits
f _{IN} = 90 MHz	25°C		11.2			11.2			11.2		Bits
f _{IN} = 140 MHz	25°C		11.1			11.2			11.2		Bits
f _{IN} = 185 MHz	25°C		11.1			11.1			11.1		Bits
f _{IN} = 220 MHz	25°C		11.0			11.0			11.1		Bits
WORST SECOND OR THIRD HARMONIC											
f _{IN} = 30 MHz	25°C		–96			–96			–90		dBc
f _{IN} = 90 MHz	25°C		–95			–92			–89		dBc
	Full			–83			–80				dBc
f _{IN} = 140 MHz	25°C		–97			–94			–91		dBc
f _{IN} = 185 MHz	25°C		–86			–95			–87		dBc
	Full								–80		dBc
f _{IN} = 220 MHz	25°C		–84			–84			–93		dBc
SPURIOUS-FREE DYNAMIC RANGE (SFDR)											
f _{IN} = 30 MHz	25°C		96			96			90		dBc
f _{IN} = 90 MHz	25°C		95			92			89		dBc
	Full	83			80						dBc
f _{IN} = 140 MHz	25°C		97			94			91		dBc
f _{IN} = 185 MHz	25°C		86			95			87		dBc
	Full							80			dBc
f _{IN} = 220 MHz	25°C		84			84			93		dBc
WORST OTHER (HARMONIC OR SPUR)											
f _{IN} = 30 MHz	25°C		–98			–96			–95		dBc
f _{IN} = 90 MHz	25°C		–97			–95			–95		dBc
	Full			–87			–83				dBc
f _{IN} = 140 MHz	25°C		–98			–97			–96		dBc
f _{IN} = 185 MHz	25°C		–95			–95			–94		dBc
	Full								–81		dBc
f _{IN} = 220 MHz	25°C		–96			–95			–94		dBc

Parameter ¹	Temperature	AD9634-170			AD9634-210			AD9634-250			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
TWO-TONE SFDR $f_{IN} = 184.1 \text{ MHz}, 187.1 \text{ MHz} (-7 \text{ dBFS})$	25°C		87			89			88		dBc
FULL POWER BANDWIDTH	25°C		1000			1000			1000		MHz

¹ See the [AN-835 Application Note](#), *Understanding High Speed ADC Testing and Evaluation*, for a complete set of definitions.

DIGITAL SPECIFICATIONS

AVDD = 1.8 V, DRVDD = 1.8 V, maximum sample rate, VIN = –1.0 dBFS differential input, 1.0 V internal reference, DCS enabled, unless otherwise noted.

Table 3.

Parameter	Temperature	Min	Typ	Max	Unit
DIFFERENTIAL CLOCK INPUTS (CLK+, CLK–)					
Logic Compliance		CMOS/LVDS/LVPECL			
Internal Common-Mode Bias	Full		0.9		V
Differential Input Voltage	Full	0.3		3.6	V _{p-p}
Input Voltage Range	Full	AGND		AVDD	V
Input Common-Mode Range	Full	0.9		1.4	V
High Level Input Current	Full	10		22	μA
Low Level Input Current	Full	–22		–10	μA
Input Capacitance	Full		4		pF
Input Resistance	Full	12	15	18	kΩ
LOGIC INPUT (CSB) ¹					
High Level Input Voltage	Full	1.22		2.1	V
Low Level Input Voltage	Full	0		0.6	V
High Level Input Current	Full	50		71	μA
Low Level Input Current	Full	–5		+5	μA
Input Resistance	Full		26		kΩ
Input Capacitance	Full		2		pF
LOGIC INPUT (SCLK) ²					
High Level Input Voltage	Full	1.22		2.1	V
Low Level Input Voltage	Full	0		0.6	V
High Level Input Current	Full	45		70	μA
Low Level Input Current	Full	–5		+5	μA
Input Resistance	Full		26		kΩ
Input Capacitance	Full		2		pF
LOGIC INPUTS (SDIO) ¹					
High Level Input Voltage	Full	1.22		2.1	V
Low Level Input Voltage	Full	0		0.6	V
High Level Input Current	Full	45		70	μA
Low Level Input Current	Full	–5		+5	μA
Input Resistance	Full		26		kΩ
Input Capacitance	Full		5		pF
DIGITAL OUTPUTS					
LVDS Data and OR Outputs (OR+, OR–)					
Differential Output Voltage (V _{OD}), ANSI Mode	Full	250	350	450	mV
Output Offset Voltage (V _{OS}), ANSI Mode	Full	1.15	1.25	1.35	V
Differential Output Voltage (V _{OD}), Reduced Swing Mode	Full	150	200	280	mV
Output Offset Voltage (V _{OS}), Reduced Swing Mode	Full	1.15	1.25	1.35	V

¹ Pull-up.

² Pull-down.

SWITCHING SPECIFICATIONS

Table 4.

Parameter	Temperature	AD9634-170			AD9634-210			AD9634-250			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
CLOCK INPUT PARAMETERS ¹											
Input Clock Rate	Full			625			625			625	MHz
Conversion Rate ²											
DCS Enabled	Full	40		170	40		210	40		250	MSPS
DCS Disabled	Full	10		170	10		210	10		250	MSPS
CLK Period, Divide-by-1 Mode (t _{CLK})	Full	5.8			4.8			4			ns
CLK Pulse Width High (t _{CH})											
Divide-by-1 Mode, DCS Enabled	Full	2.61	2.9	3.19	2.16	2.4	2.64	1.8	2.0	2.2	ns
Divide-by-1 Mode, DCS Disabled	Full	2.76	2.9	3.05	2.28	2.4	2.52	1.9	2.0	2.1	ns
Divide-by-2 Mode Through Divide-by-8 Mode	Full	0.8			0.8			0.8			ns
Aperture Delay (t _A)	Full		1.0			1.0			1.0		ns
Aperture Uncertainty (Jitter, t _j)	Full		0.1			0.1			0.1		ps rms
DATA OUTPUT PARAMETERS ¹											
Data Propagation Delay (t _{PD})	Full	4.1	4.7	5.2	4.1	4.7	5.2	4.1	4.7	5.2	ns
DCO Propagation Delay (t _{DCO})	Full	4.7	5.3	5.8	4.7	5.3	5.8	4.7	5.3	5.8	ns
DCO to Data Skew (t _{SKEW})	Full	0.3	0.5	0.7	0.3	0.5	0.7	0.3	0.5	0.7	ns
Pipeline Delay (Latency)	Full		10			10			10		Cycles
Wake-Up Time (from Standby)	Full		10			10			10		μs
Wake-Up Time (from Power-Down)	Full		100			100			100		μs
Out-of-Range Recovery Time	Full		3			3			3		Cycles

¹ See Figure 2.² Conversion rate is the clock rate after the divider.

Timing Diagram

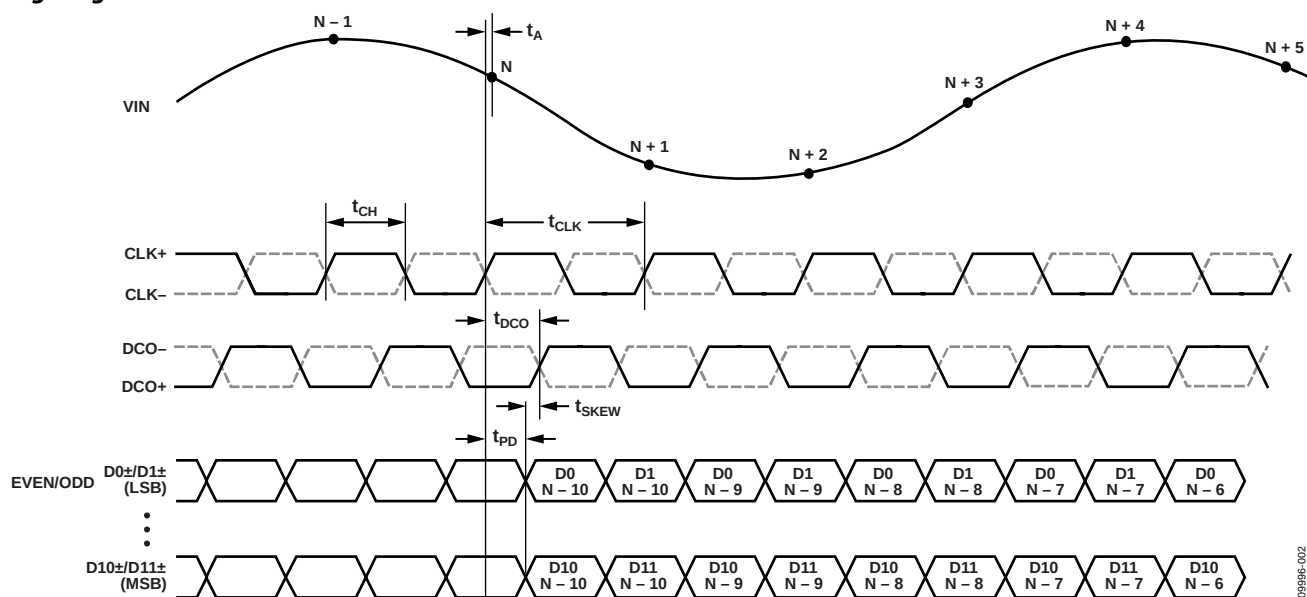


Figure 2. Even/Odd LVDS Mode Data Output Timing

TIMING SPECIFICATIONS

Table 5.

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
SPI TIMING REQUIREMENTS	See Figure 58 for the SPI timing diagram				
t_{DS}	Setup time between the data and the rising edge of SCLK	2			ns
t_{DH}	Hold time between the data and the rising edge of SCLK	2			ns
t_{CLK}	Period of the SCLK	40			ns
t_S	Setup time between CSB and SCLK	2			ns
t_H	Hold time between CSB and SCLK	2			ns
t_{HIGH}	Minimum period that SCLK should be in a logic high state	10			ns
t_{LOW}	Minimum period that SCLK should be in a logic low state	10			ns
t_{EN_SDIO}	Time required for the SDIO pin to switch from an input to an output relative to the SCLK falling edge (not shown in Figure 58)	10			ns
t_{DIS_SDIO}	Time required for the SDIO pin to switch from an output to an input relative to the SCLK rising edge (not shown in Figure 58)	10			ns

ABSOLUTE MAXIMUM RATINGS

Table 6.

Parameter	Rating
Electrical	
AVDD to AGND	−0.3 V to +2.0 V
DRVDD to AGND	−0.3 V to +2.0 V
VIN+, VIN− to AGND	−0.3 V to AVDD + 0.2 V
CLK+, CLK− to AGND	−0.3 V to AVDD + 0.2 V
VCM to AGND	−0.3 V to AVDD + 0.2 V
CSB to AGND	−0.3 V to DRVDD + 0.3 V
SCLK to AGND	−0.3 V to DRVDD + 0.3 V
SDIO to AGND	−0.3 V to DRVDD + 0.3 V
D0±/D1± through D10±/D11± to AGND	−0.3 V to DRVDD + 0.3 V
DCO+/DCO− to AGND	−0.3 V to DRVDD + 0.3 V
OR+/OR− to AGND	−0.3 V to DRVDD + 0.3 V
Environmental	
Operating Temperature Range (Ambient)	−40°C to +85°C
Maximum Junction Temperature Under Bias	150°C
Storage Temperature Range (Ambient)	−65°C to +125°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

THERMAL CHARACTERISTICS

The exposed paddle must be soldered to the ground plane for the LFCSP package. Soldering the exposed paddle to the customer board increases the reliability of the solder joints, maximizing the thermal capability of the package.

Table 7. Thermal Resistance

Package Type	Airflow Velocity (m/sec)	$\theta_{JA}^{1,2}$	$\theta_{JC}^{1,3}$	$\theta_{JB}^{1,4}$	Unit
32-Lead LFCSP 5 mm × 5 mm (CP-32-12)	0	37.1	3.1	20.7	°C/W
	1.0	32.4			°C/W
	2.0	29.1			°C/W

¹ Per JEDEC 51-7, plus JEDEC 25-5 252P test board.

² Per JEDEC JESD51-2 (still air) or JEDEC JESD51-6 (moving air).

³ Per MIL-Std 883, Method 1012.1.

⁴ Per JEDEC JESD51-8 (still air).

Typical θ_{JA} is specified for a 4-layer PCB with solid ground plane. As shown in Table 7, airflow increases heat dissipation, which reduces θ_{JA} . In addition, metal in direct contact with the package leads from metal traces, through holes, ground, and power planes reduces the θ_{JA} .

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

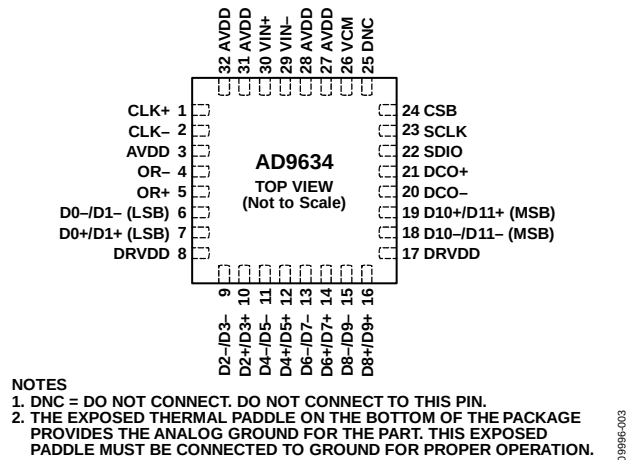


Figure 3. Pin Configuration

Table 8. Pin Function Descriptions

Pin No.	Mnemonic	Type	Description
ADC Power Supplies			
8, 17	DRVDD	Supply	Digital Output Driver Supply (1.8 V Nominal).
3, 27, 28, 31, 32	AVDD	Supply	Analog Power Supply (1.8 V Nominal).
0	AGND, Exposed Paddle	Ground	Analog Ground. The exposed thermal paddle on the bottom of the package provides the analog ground for the part. This exposed paddle must be connected to ground for proper operation.
25	DNC		Do No Connect. Do not connect to this pin.
ADC Analog			
30	VIN+	Input	Differential Analog Input Pin (+).
29	VIN–	Input	Differential Analog Input Pin (–).
26	VCM	Output	Common-Mode Level Bias Output for Analog Inputs. This pin should be decoupled to ground using a 0.1 μ F capacitor.
1	CLK+	Input	ADC Clock Input—True.
2	CLK–	Input	ADC Clock Input—Complement.
Digital Outputs			
5	OR+	Output	Overrange—True.
4	OR–	Output	Overrange—Complement.
7	D0+/D1+ (LSB)	Output	DDR LVDS Output Data 0/Data 1—True (LSB).
6	D0–/D1– (LSB)	Output	DDR LVDS Output Data 0/Data 1—Complement (LSB).
10	D2+/D3+	Output	DDR LVDS Output Data 2/Data 3—True.
9	D2–/D3–	Output	DDR LVDS Output Data 2/Data 3—Complement.
12	D4+/D5+	Output	DDR LVDS Output Data 4/Data 5—True.
11	D4–/D5–	Output	DDR LVDS Output Data 4/Data 5—Complement.
14	D6+/D7+	Output	DDR LVDS Output Data 6/Data 7—True.
13	D6–/D7–	Output	DDR LVDS Output Data 6/Data 7—Complement.
16	D8+/D9+	Output	DDR LVDS Output Data 8/Data 9—True.
15	D8–/D9–	Output	DDR LVDS Output Data 8/Data 9—Complement.
19	D10+/D11+ (MSB)	Output	DDR LVDS Output Data 10/Data 11—True (MSB).
18	D10–/D11– (MSB)	Output	DDR LVDS Output Data 10/Data 11—Complement (MSB).
21	DCO+	Output	LVDS Data Clock Output—True.
20	DCO–	Output	LVDS Data Clock Output—Complement.

Pin No.	Mnemonic	Type	Description
SPI Control			
23	SCLK	Input	SPI Serial Clock.
22	SDIO	Input/Output	SPI Serial Data I/O.
24	CSB	Input	SPI Chip Select (Active Low).

TYPICAL PERFORMANCE CHARACTERISTICS

AVDD = 1.8 V, DRVDD = 1.8 V, sample rate = maximum sample rate per speed grade, DCS enabled, 1.75 V p-p differential input, VIN = -1.0 dBFS, 32k sample, TA = 25°C, unless otherwise noted.

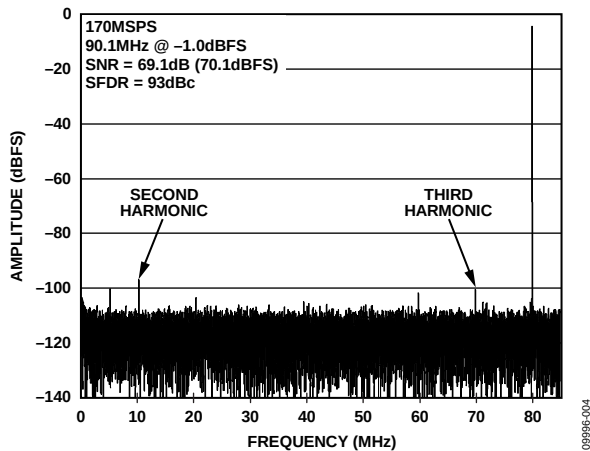


Figure 4. AD9634-170 Single-Tone FFT with $f_{IN} = 90.1$ MHz

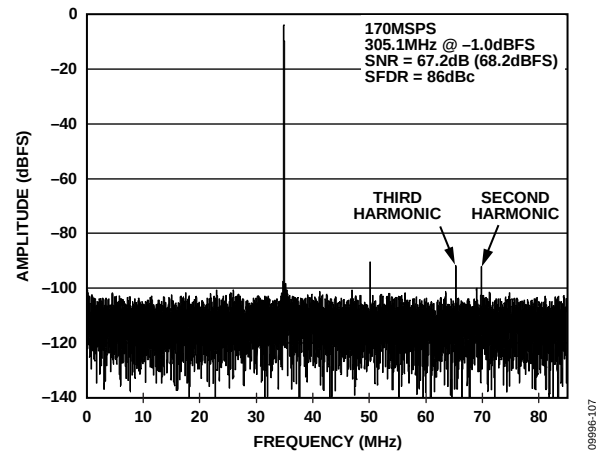


Figure 7. AD9634-170 Single-Tone FFT with $f_{IN} = 305.1$ MHz

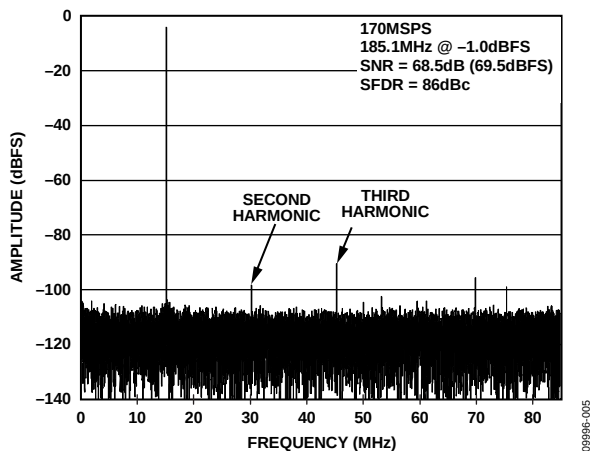


Figure 5. AD9634-170 Single-Tone FFT with $f_{IN} = 185.1$ MHz

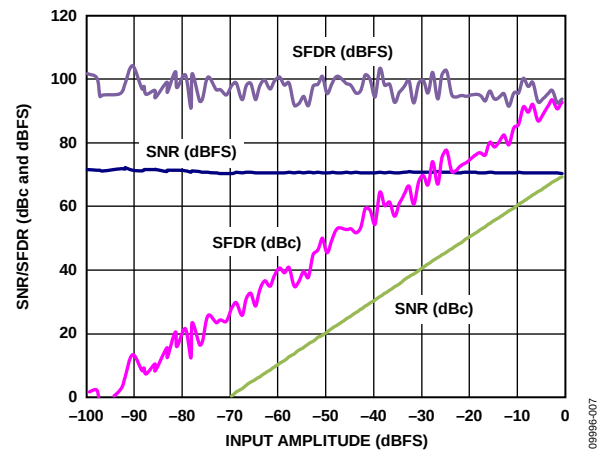


Figure 8. AD9634-170 Single-Tone SNR/SFDR vs. Input Amplitude (A_{IN}) with $f_{IN} = 90.1$ MHz, $f_s = 170$ MSPS

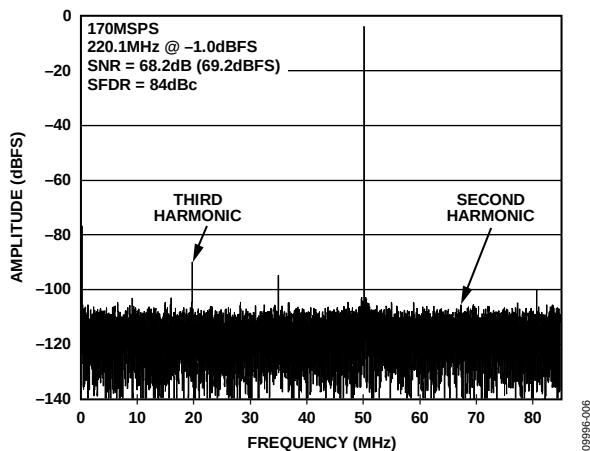


Figure 6. AD9634-170 Single-Tone FFT with $f_{IN} = 220.1$ MHz

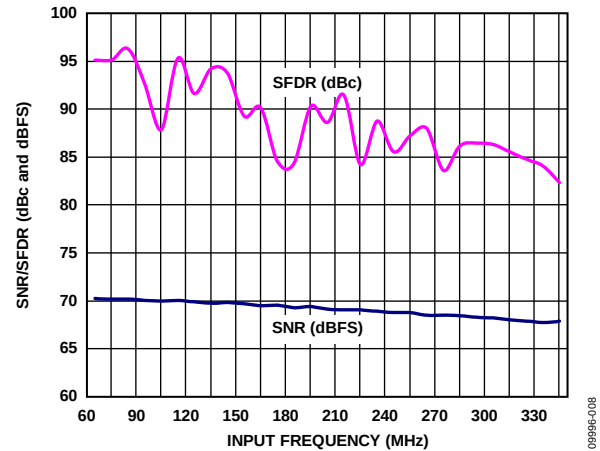


Figure 9. AD9634-170 Single-Tone SNR/SFDR vs. Input Frequency (f_{IN}), $f_s = 170$ MSPS

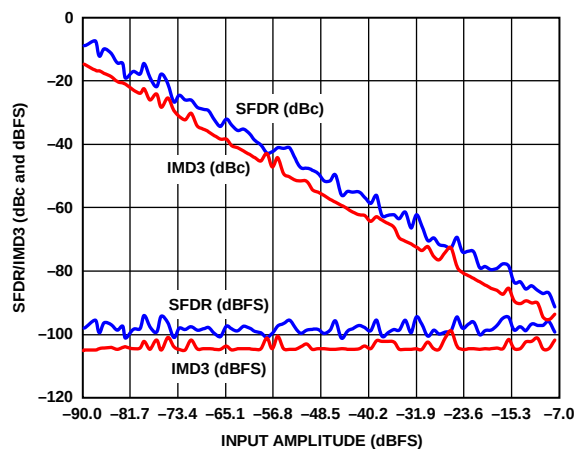


Figure 10. AD9634-170 Two-Tone SFDR/IMD3 vs. Input Amplitude (A_{IN}) with $f_{IN1} = 89.12$ MHz, $f_{IN2} = 92.12$ MHz, $f_s = 170$ MSPS

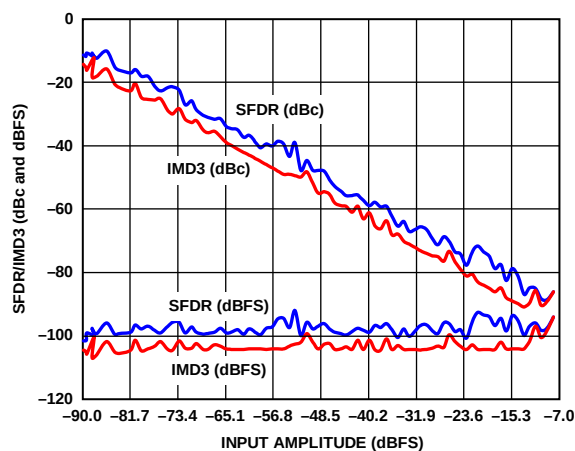


Figure 11. AD9634-170 Two-Tone SFDR/IMD3 vs. Input Amplitude (A_{IN}) with $f_{IN1} = 184.12$ MHz, $f_{IN2} = 187.12$ MHz, $f_s = 170$ MSPS

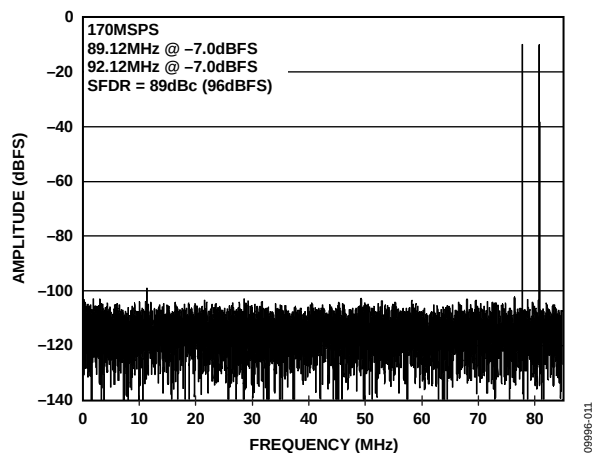


Figure 12. AD9634-170 Two-Tone FFT with $f_{IN1} = 89.12$ MHz, $f_{IN2} = 92.12$ MHz

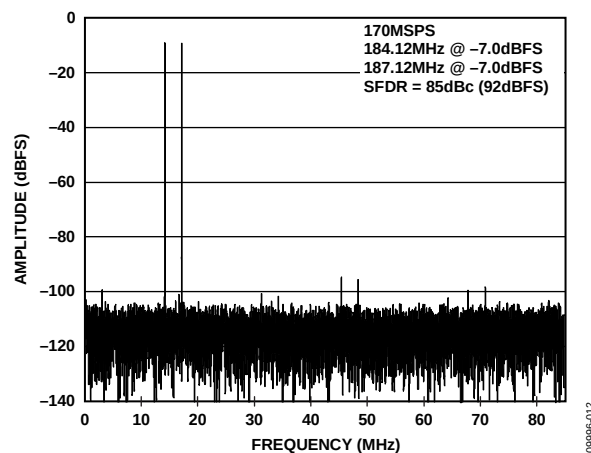


Figure 13. AD9634-170 Two-Tone FFT with $f_{IN1} = 184.12$ MHz, $f_{IN2} = 187.12$ MHz

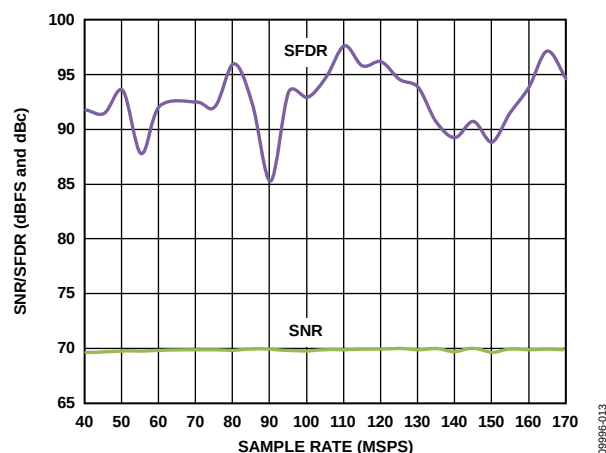


Figure 14. AD9634-170 Single-Tone SNR/SFDR vs. Sample Rate (f_s) with $f_{IN} = 90$ MHz

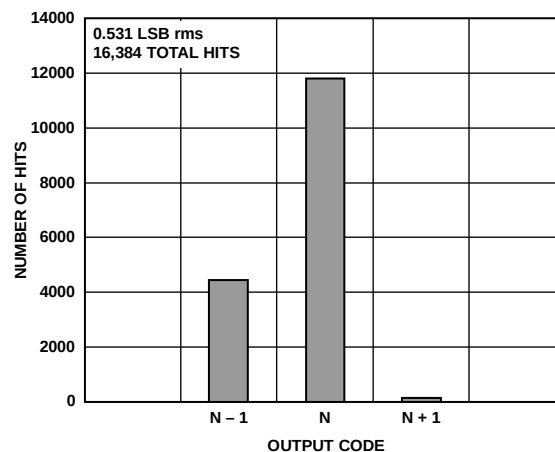
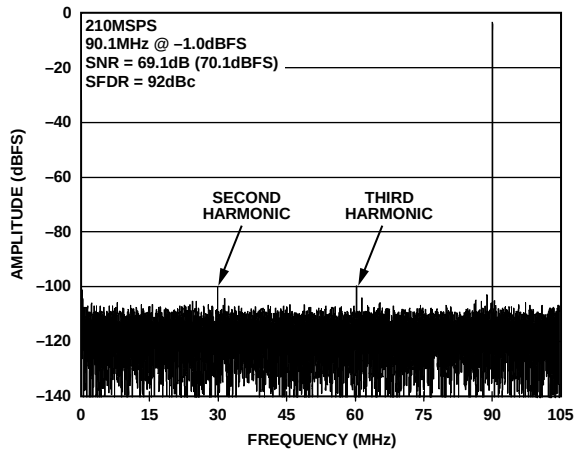
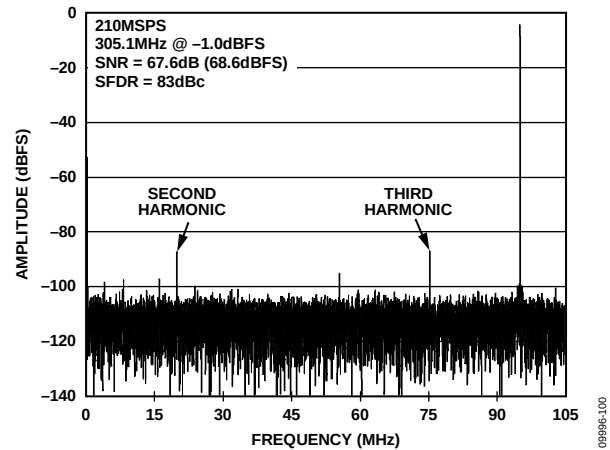
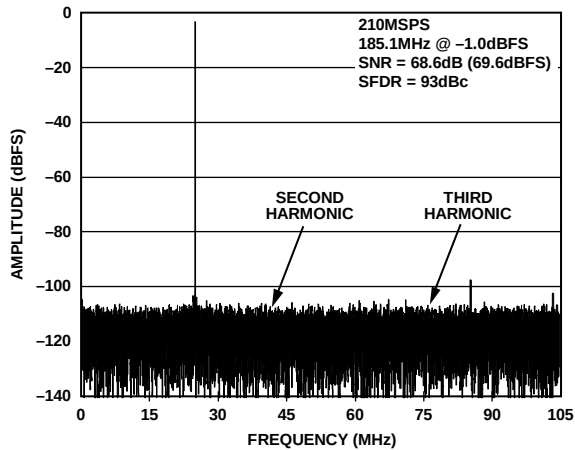
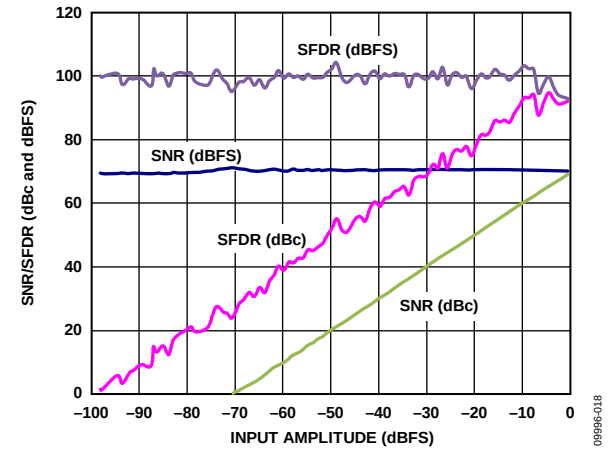
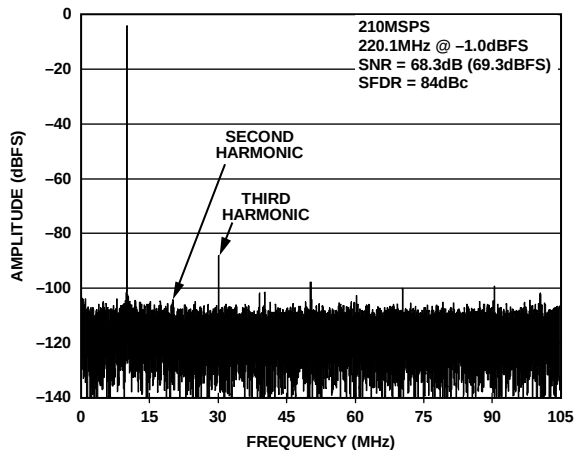
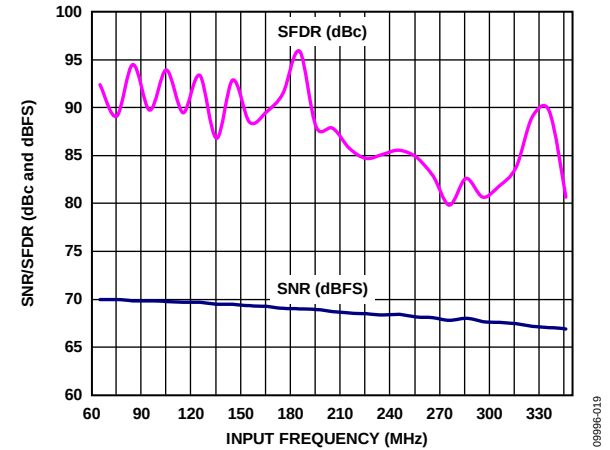


Figure 15. AD9634-170 Grounded Input Histogram, $f_s = 170$ MSPS

Figure 16. AD9634-210 Single-Tone FFT with $f_{IN} = 90.1$ MHzFigure 19. AD9634-210 Single-Tone FFT with $f_{IN} = 305.1$ MHzFigure 17. AD9634-210 Single-Tone FFT with $f_{IN} = 185.1$ MHzFigure 20. AD9634-210 Single-Tone SNR/SFDR vs. Input Amplitude (A_{IN}) with $f_{IN} = 90.1$ MHz, $f_s = 210$ MSPSFigure 18. AD9634-210 Single-Tone FFT with $f_{IN} = 220.1$ MHzFigure 21. AD9634-210 Single-Tone SNR/SFDR vs. Input Frequency (f_{IN}), $f_s = 210$ MSPS

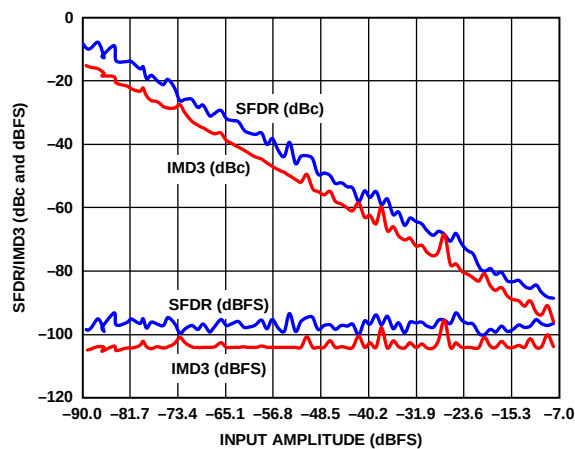


Figure 22. AD9634-210 Two-Tone SFDR/IMD3 vs. Input Amplitude (A_{IN}) with $f_{IN1} = 89.12$ MHz, $f_{IN2} = 92.12$ MHz, $f_s = 210$ MSPS

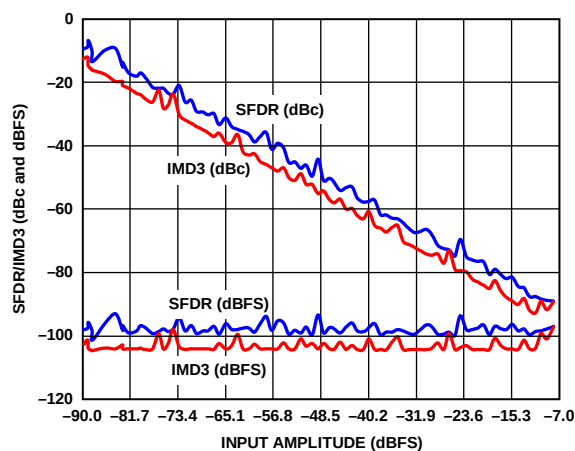


Figure 23. AD9634-210 Two-Tone SFDR/IMD3 vs. Input Amplitude (A_{IN}) with $f_{IN1} = 184.12$ MHz, $f_{IN2} = 187.12$ MHz, $f_s = 210$ MSPS

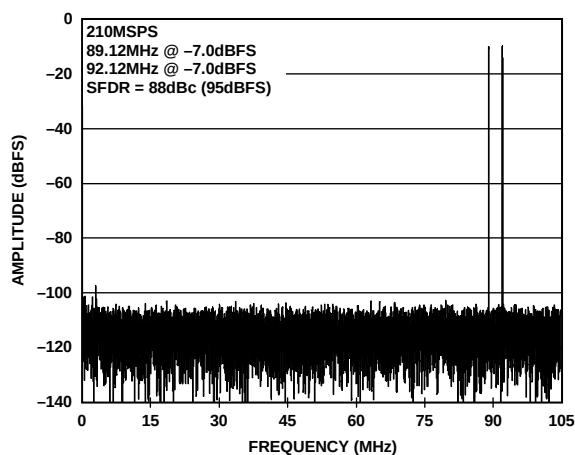


Figure 24. AD9634-210 Two-Tone FFT with $f_{IN1} = 89.12$ MHz, $f_{IN2} = 92.12$ MHz

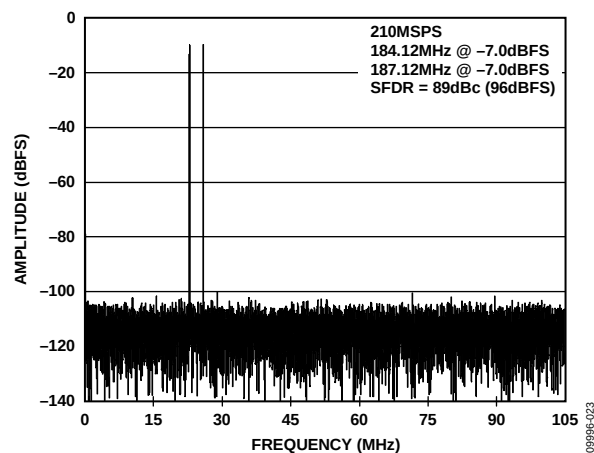


Figure 25. AD9634-210 Two Tone FFT with $f_{IN1} = 184.12$ MHz, $f_{IN2} = 187.12$ MHz

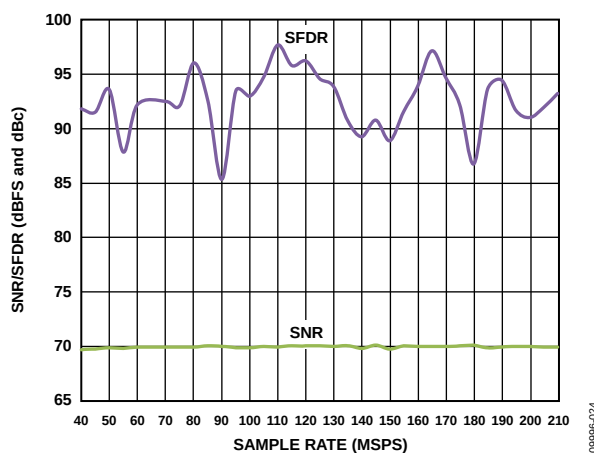


Figure 26. AD9634-210 Single-Tone SNR/SFDR vs. Sample Rate (f_s) with $f_{IN} = 90$ MHz

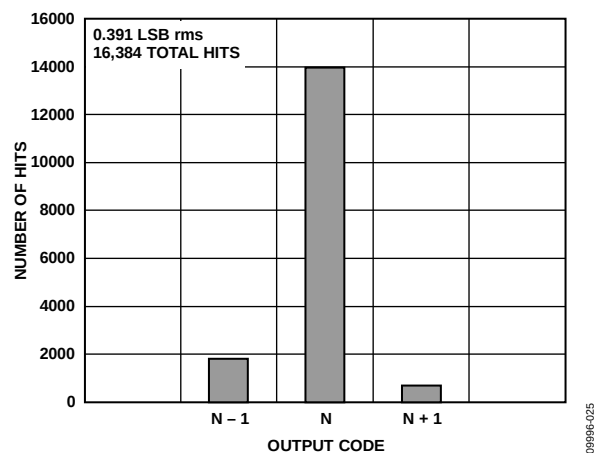
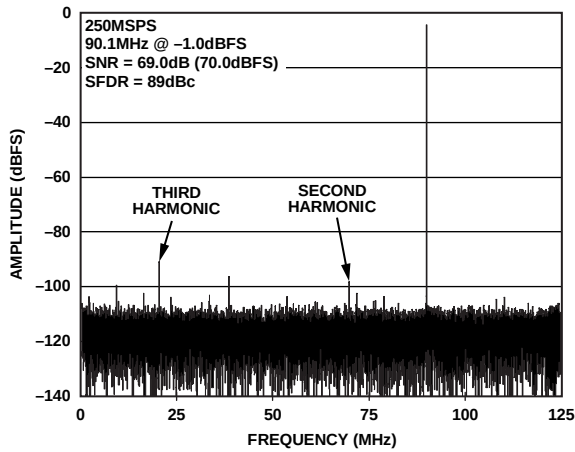
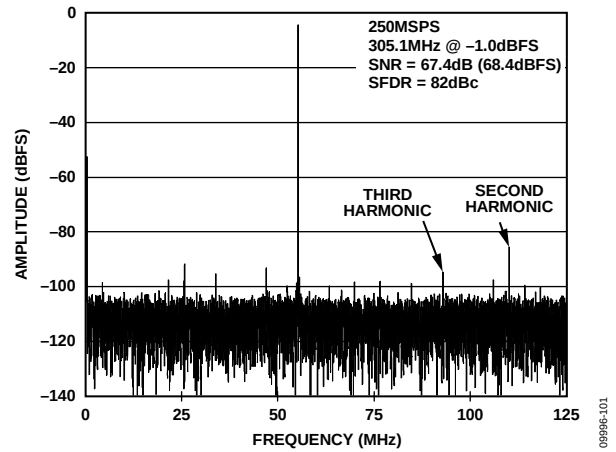
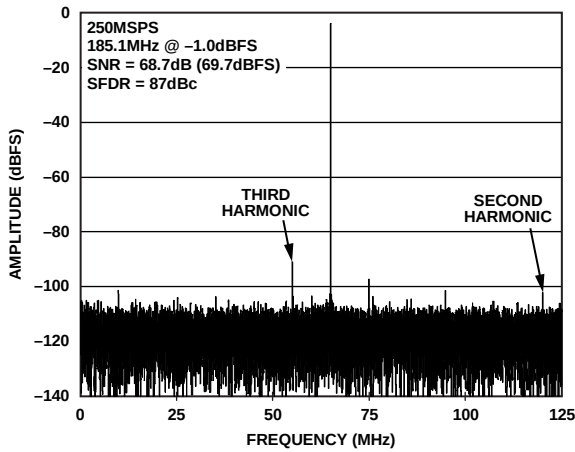
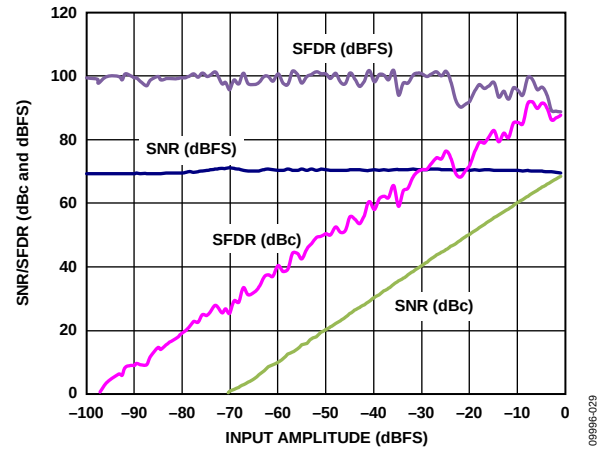
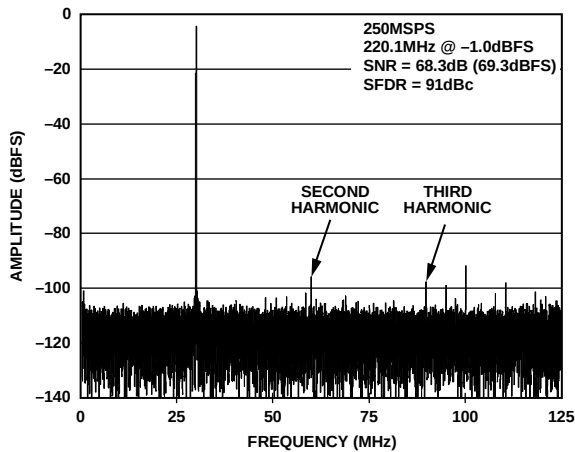
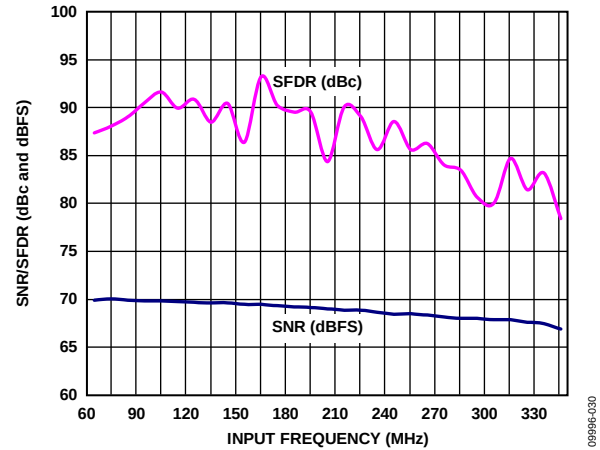


Figure 27. AD9634-210 Grounded Input Histogram, $f_s = 210$ MSPS

Figure 28. AD9634-250 Single-Tone FFT with $f_{IN} = 90.1$ MHzFigure 31. AD9634-250 Single-Tone FFT with $f_{IN} = 305.1$ MHzFigure 29. AD9634-250 Single-Tone FFT with $f_{IN} = 185.1$ MHzFigure 32. AD9634-250 Single-Tone SNR/SFDR vs. Input Amplitude (A_{IN}) with $f_{IN} = 90.1$ MHz, $f_s = 250$ MSPSFigure 30. AD9634-250 Single-Tone FFT with $f_{IN} = 220.1$ MHzFigure 33. AD9634-250 Single-Tone SNR/SFDR vs. Input Frequency (f_{IN}), $f_s = 250$ MSPS

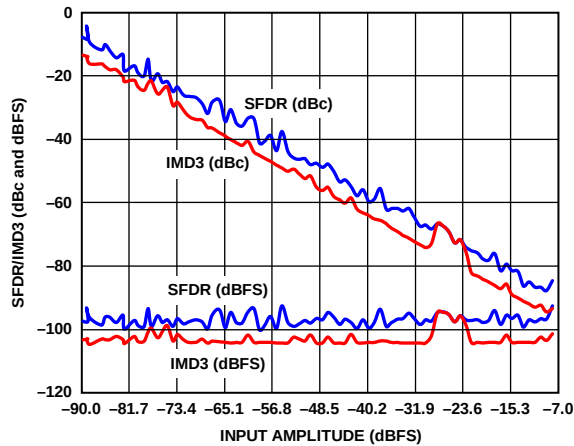


Figure 34. AD9634-250 Two-Tone SFDR/IMD3 vs. Input Amplitude (A_{IN}) with $f_{IN1} = 89.12$ MHz, $f_{IN2} = 92.12$ MHz, $f_s = 250$ MSPS

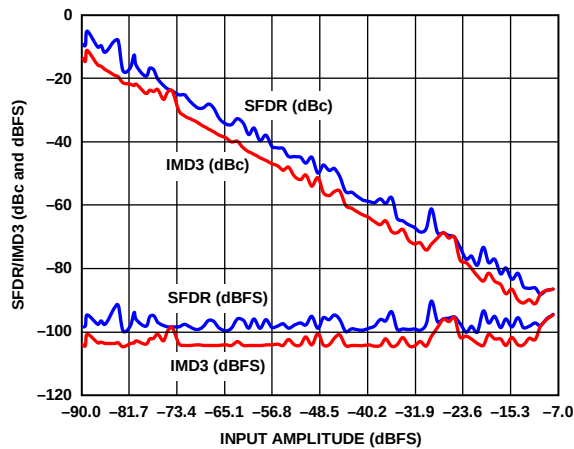


Figure 35. AD9634-250 Two-Tone SFDR/IMD3 vs. Input Amplitude (A_{IN}) with $f_{IN1} = 184.12$ MHz, $f_{IN2} = 187.12$ MHz, $f_s = 250$ MSPS

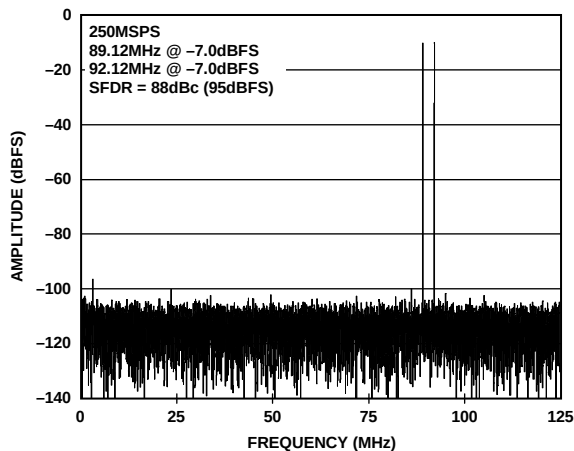


Figure 36. AD9634-250 Two-Tone FFT with $f_{IN1} = 89.12$ MHz, $f_{IN2} = 92.12$ MHz

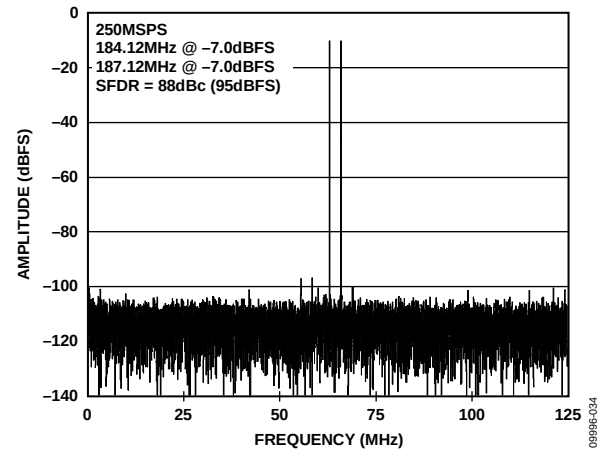


Figure 37. AD9634-250 Two-Tone FFT with $f_{IN1} = 184.12$ MHz, $f_{IN2} = 187.12$ MHz

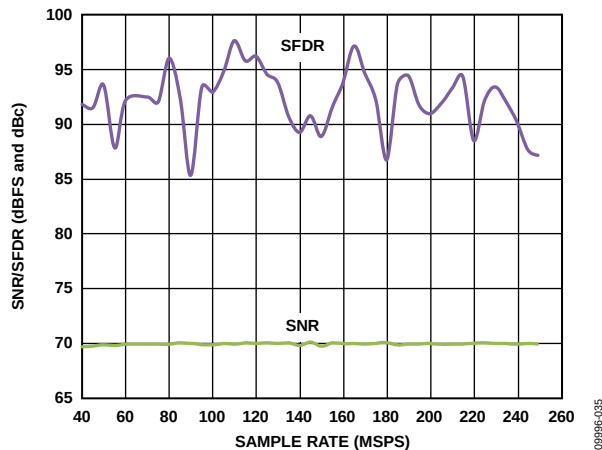


Figure 38. AD9634-250 Single-Tone SNR/SFDR vs. Sample Rate (f_s) with $f_{IN} = 90$ MHz

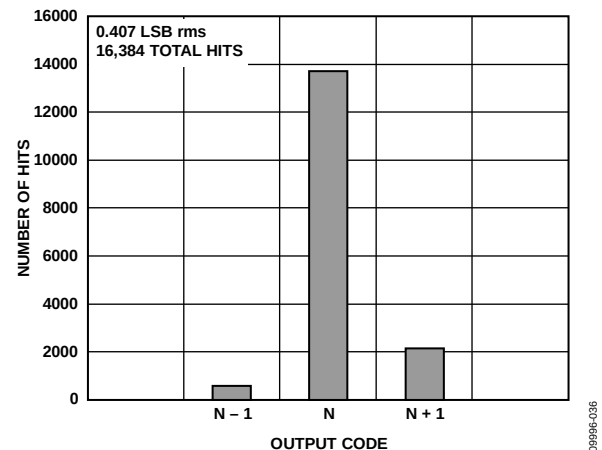


Figure 39. AD9634-250 Grounded Input Histogram, $f_s = 250$ MSPS

EQUIVALENT CIRCUITS

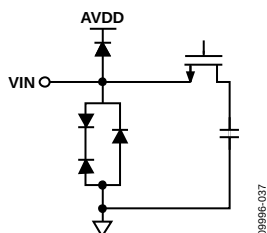


Figure 40. Equivalent Analog Input Circuit

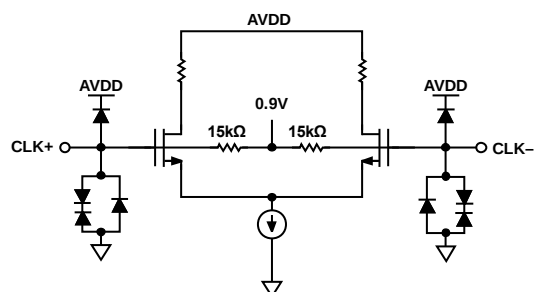


Figure 41. Equivalent Clock Input Circuit

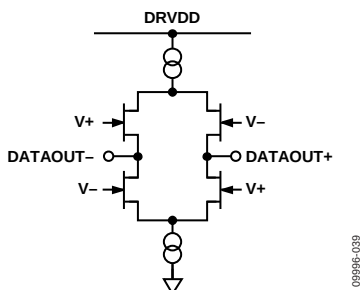


Figure 42. Equivalent LVDS Output Circuit

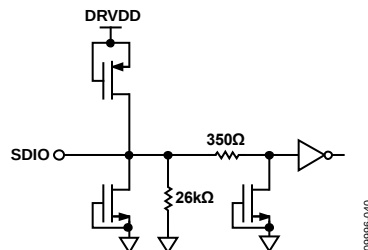


Figure 43. Equivalent SDIO Circuit

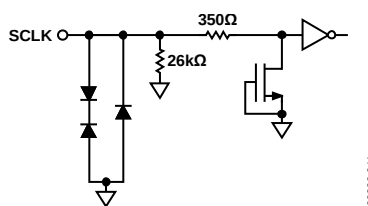


Figure 44. Equivalent SCLK Input Circuit

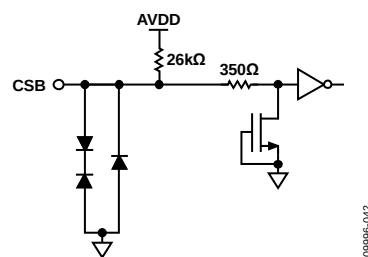


Figure 45. Equivalent CSB Input Circuit

THEORY OF OPERATION

The AD9634 can sample any $f_s/2$ frequency segment from dc to 250 MHz using appropriate low-pass or band-pass filtering at the ADC inputs with little loss in ADC performance.

Programming and control of the AD9634 are accomplished using a 3-pin, SPI-compatible serial interface.

ADC ARCHITECTURE

The AD9634 architecture consists of a front-end sample-and-hold circuit, followed by a pipelined, switched-capacitor ADC. The quantized outputs from each stage are combined into a final 12-bit result in the digital correction logic. The pipelined architecture permits the first stage to operate on a new input sample and the remaining stages to operate on the preceding samples. Sampling occurs on the rising edge of the clock.

Each stage of the pipeline, excluding the last, consists of a low resolution flash ADC connected to a switched-capacitor digital-to-analog converter (DAC) and an interstage residue amplifier (MDAC). The MDAC magnifies the difference between the reconstructed DAC output and the flash input for the next stage in the pipeline. One bit of redundancy is used in each stage to facilitate digital correction of flash errors. The last stage simply consists of a flash ADC.

The input stage contains a differential sampling circuit that can be ac- or dc-coupled in differential or single-ended modes. The output staging block aligns the data, corrects errors, and passes the data to the output buffers. The output buffers are powered from a separate supply, allowing digital output noise to be separated from the analog core. During power-down, the output buffers go into a high impedance state.

ANALOG INPUT CONSIDERATIONS

The analog input to the AD9634 is a differential switched-capacitor circuit that has been designed to attain optimum performance when processing a differential input signal.

The clock signal alternatively switches the input between sample mode and hold mode (see the configuration shown in Figure 46). When the input is switched into sample mode, the signal source must be capable of charging the sampling capacitors and settling within $\frac{1}{2}$ clock cycle.

A small resistor in series with each input can help reduce the peak transient current required from the output stage of the driving source. A shunt capacitor can be placed across the inputs to provide dynamic charging currents. This passive network creates a low-pass filter at the ADC input; therefore, the precise values are dependent on the application.

In intermediate frequency (IF) undersampling applications, reduce the shunt capacitors. In combination with the driving source impedance, the shunt capacitors limit the input bandwidth. Refer to the [AN-742 Application Note, Frequency Domain Response of Switched-Capacitor ADCs](#); the [AN-827 Application Note, A Resonant Approach to Interfacing Amplifiers to Switched-Capacitor ADCs](#); and the [Analog Dialogue](#) article, “[Transformer-Coupled Front-End for Wideband A/D Converters](#)” for more information on this subject.

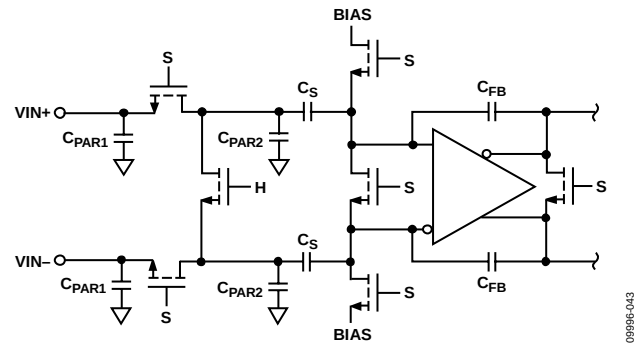


Figure 46. Switched-Capacitor Input

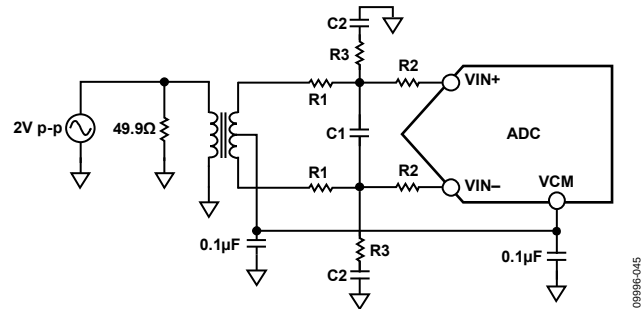
For best dynamic performance, match the source impedances driving VIN+ and VIN- and differentially balance the inputs.

Input Common Mode

The analog inputs of the AD9634 are not internally dc biased. In ac-coupled applications, the user must provide this bias externally. Setting the device so that $V_{CM} = 0.5 \times AVDD$ (or 0.9 V) is recommended for optimum performance. An on-board common-mode voltage reference is included in the design and is available from the VCM pin. Using the VCM output to set the input common mode is recommended. Optimum performance is achieved when the common-mode voltage of the analog input is set by the VCM pin voltage (typically $0.5 \times AVDD$). The VCM pin must be decoupled to ground by a 0.1 μF capacitor, as described in the Applications Information section. Place this decoupling capacitor close to the pin to minimize the series resistance and inductance between the part and this capacitor.

Optimum performance can be achieved when driving the [AD9634](#) in a differential input configuration. For baseband applications, the [AD8138](#), [ADA4937-1](#), and [ADA4930-1](#) differential drivers provide excellent performance and a flexible interface to the ADC.

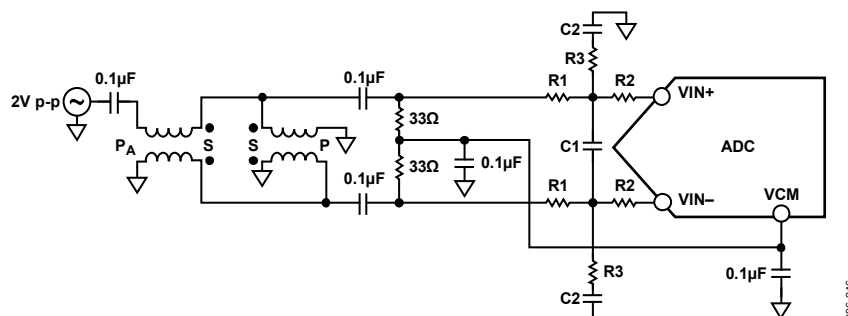
For baseband applications where SNR is a key parameter, differential transformer coupling is the recommended input configuration. An example is shown in Figure 48. To bias the analog input, connect the VCM voltage to the center tap of the secondary winding of the transformer.



The signal characteristics must be considered when selecting a transformer. Most RF transformers saturate at frequencies below a few megahertz. Excessive signal power can also cause core saturation, which leads to distortion.

In the double balun and transformer configurations, the value of the input capacitors and resistors is dependent on the input frequency and source impedance. Based on these parameters the value of the input resistors and capacitors may need to be adjusted, or some components may need to be removed. Table 9 displays recommended values to set the RC network for different input frequency ranges. However, these values are dependent on the input signal and bandwidth and should be used only as a starting guide. Note that the values given in Table 9 are for the R1, R2, R3, C1, and C2 components shown in Figure 49.

Frequency Range (MHz)	R1 Series (Ω)	C1 Differential (pF)	R2 Series (Ω)	C2 Shunt (pF)	R3 Shunt (Ω)
0 to 100	33	8.2	0	15	49.9
100 to 300	15	3.9	0	8.2	49.9



Rev. B | Page 20 of 30

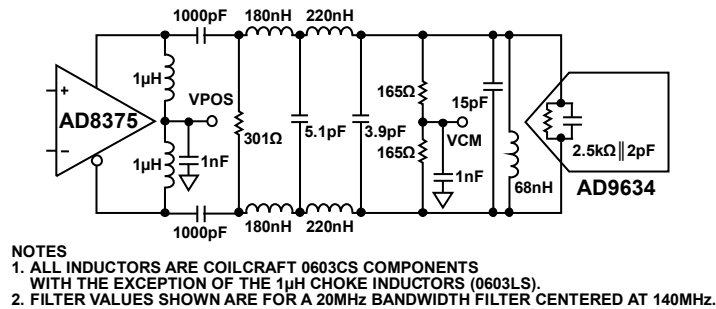


Figure 50. Differential Input Configuration Using the AD8375

An alternative to using a transformer-coupled input at frequencies in the second Nyquist zone is to use an amplifier with variable gain. The AD8375 digital variable gain amplifier (DVGA) provides good performance for driving the AD9634. Figure 50 shows an example of the AD8375 driving the AD9634 through a band-pass antialiasing filter.

VOLTAGE REFERENCE

A stable and accurate voltage reference is built into the AD9634. The full-scale input range can be adjusted by varying the reference voltage via SPI. The input span of the ADC tracks reference voltage changes linearly.

CLOCK INPUT CONSIDERATIONS

For optimum performance, the AD9634 sample clock inputs, CLK+ and CLK–, should be clocked with a differential signal. The signal is typically ac-coupled into the CLK+ and CLK– pins by means of a transformer or a passive component configuration. These pins are biased internally (see Figure 51) and require no external bias. If the inputs are floated, the CLK– pin is pulled low to prevent spurious clocking.

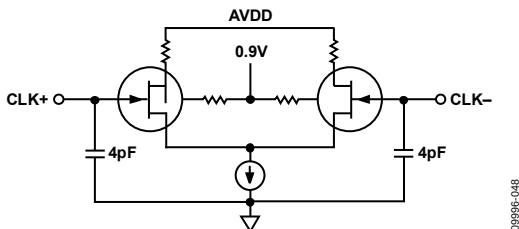


Figure 51. Equivalent Clock Input Circuit

Clock Input Options

The AD9634 has a very flexible clock input structure. Clock input can be a CMOS, LVDS, LVPECL, or sine wave signal. Regardless of the type of signal being used, clock source jitter is of the most concern, as described in the Jitter Considerations section.

Figure 52 and Figure 53 show two preferable methods for clocking the AD9634 (at clock rates of up to 625 MHz). A low jitter clock source is converted from a single-ended signal to a differential signal using an RF balun or RF transformer.

The RF balun configuration is recommended for clock frequencies between 125 MHz and 625 MHz, and the RF transformer is recommended for clock frequencies from 10 MHz to 200 MHz. The back-to-back Schottky diodes across the secondary windings of the transformer limit clock excursions into the AD9634 to approximately 0.8 V p-p differential. This limit helps prevent the large voltage swings of the clock from feeding through to other portions of the AD9634, while preserving the fast rise and fall times of the signal, which are critical for low jitter performance.

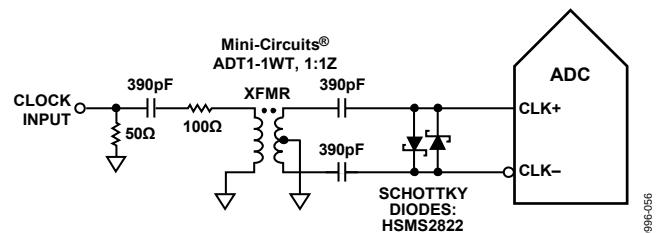


Figure 52. Transformer Coupled Differential Clock (Up to 200 MHz)

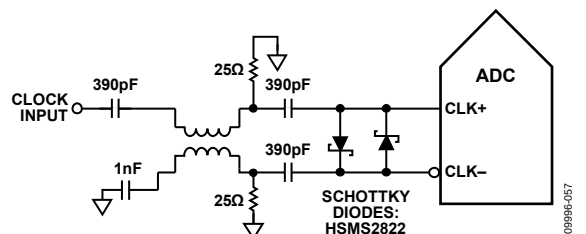


Figure 53. Balun-Coupled Differential Clock (Up to 625 MHz)

If a low jitter clock source is not available, another option is to ac couple a differential PECL signal to the sample clock input pins as shown in Figure 54. The AD9510, AD9511, AD9512, AD9513, AD9514, AD9515, AD9516, AD9517, AD9518, AD9520, AD9522, AD9523, AD9524, ADCLK905, ADCLK907, and ADCLK925 clock drivers offer excellent jitter performance.

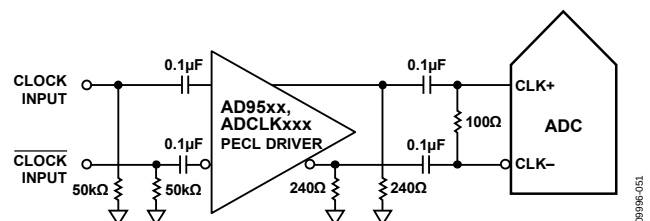


Figure 54. Differential PECL Sample Clock (Up to 625 MHz)

A third option is to ac couple a differential LVDS signal to the sample clock input pins, as shown in Figure 55. The [AD9510](#), [AD9511](#), [AD9512](#), [AD9513](#), [AD9514](#), [AD9515](#), [AD9516](#), [AD9517](#), [AD9518](#), [AD9520](#), [AD9522](#), [AD9523](#), [AD9524](#) clock drivers offer excellent jitter performance.

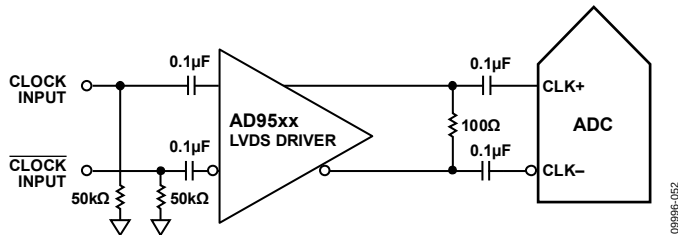


Figure 55. Differential LVDS Sample Clock (Up to 625 MHz)

Input Clock Divider

The [AD9634](#) contains an input clock divider with the ability to divide the input clock by integer values between 1 and 8. For divide ratios other than 1, the DCS is enabled by default on power-up.

Clock Duty Cycle

Typical high speed ADCs use both clock edges to generate a variety of internal timing signals and, as a result, may be sensitive to clock duty cycle. Commonly, a $\pm 5\%$ tolerance is required on the clock duty cycle to maintain dynamic performance characteristics.

The [AD9634](#) contains a DCS that retimes the nonsampling (falling) edge, providing an internal clock signal with a nominal 50% duty cycle. This allows the user to provide a wide range of clock input duty cycles without affecting the performance of the [AD9634](#).

Jitter on the rising edge of the input clock is still of paramount concern and is not reduced by the duty cycle stabilizer. The duty cycle control loop does not function for clock rates less than 40 MHz nominally. The loop has a time constant associated with it that must be considered when the clock rate may change dynamically. A wait time of 1.5 μs to 5 μs is required after a dynamic clock frequency increase or decrease before the DCS loop is relocked to the input signal. During the time that the loop is not locked, the DCS loop is bypassed, and internal device timing is dependent on the duty cycle of the input clock signal. In such applications, it may be appropriate to disable the duty cycle stabilizer. In all other applications, enabling the DCS circuit is recommended to maximize ac performance.

Jitter Considerations

High speed, high resolution ADCs are sensitive to the quality of the clock input. The degradation in SNR at a given input frequency (f_{IN}) due to jitter (t_j) can be calculated by

$$SNR_{HF} = -10 \log[(2\pi \times f_{IN} \times t_{jRMS})^2 + 10^{(-SNR_{LF}/10)}]$$

In the equation, the rms aperture jitter represents the root-mean-square of all jitter sources, which include the clock input, the analog input signal, and the ADC aperture jitter specification. IF undersampling applications are particularly sensitive to jitter, as shown in Figure 56.

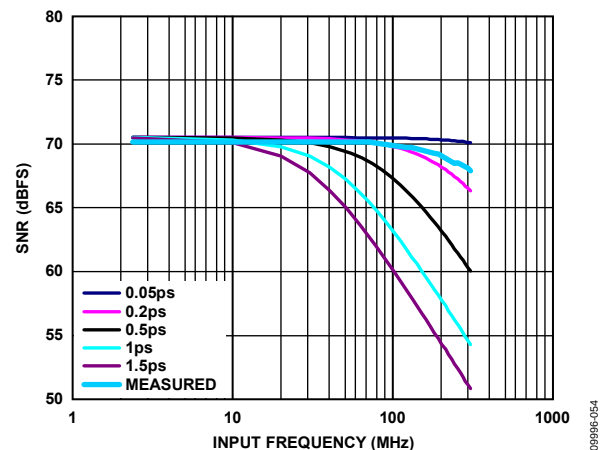


Figure 56. [AD9634-250](#) SNR vs. Input Frequency and Jitter

In cases where aperture jitter may affect the dynamic range of the [AD9634](#), treat the clock input as an analog signal. In addition, use separate power supplies for the clock drivers and the ADC output driver to avoid modulating the clock signal with digital noise. Low jitter, crystal controlled oscillators provide the best clock sources. If the clock is generated from another type of source (by gating, dividing, or another method), it should be retimed by the original clock during the last step.

Refer to [AN-501 Application Note, Aperture Uncertainty and ADC System Performance](#), and [AN-756 Application Note, Sampled Systems and the Effects of Clock Phase Noise and Jitter](#), for more information about jitter performance as it relates to ADCs.

POWER DISSIPATION AND STANDBY MODE

As shown in Figure 57, the power dissipated by the AD9634 is proportional to its sample rate. The data in Figure 57 was taken using the same operating conditions as those used for the Typical Performance Characteristics section.

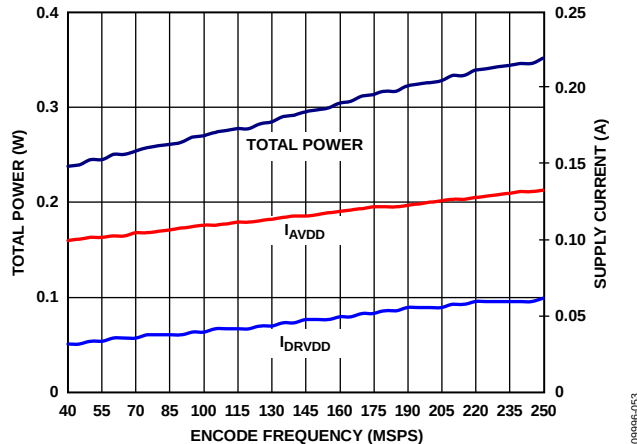


Figure 57. AD9634-250 Power and Current vs. Sample Rate

By setting the internal power-down mode bits (Bits[1:0]) in the power modes register (Address 0x08) to 01, the AD9634 is placed in power-down mode. In this state, the ADC typically dissipates 5 mW. During power-down, the output drivers are placed in a high impedance state.

Low power dissipation in power-down mode is achieved by shutting down the reference, reference buffer, biasing networks, and clock. Internal capacitors are discharged when entering power-down mode and then must be recharged when returning to normal operation. As a result, wake-up time is related to the time spent in power-down mode, and shorter power-down cycles result in proportionally shorter wake-up times.

When using the SPI port interface, the user can place the ADC in power-down mode or standby mode. Standby mode allows the user to keep the internal reference circuitry powered when faster wake-up times are required. To put the part into standby mode, set the internal power-down mode bits (Bits[1:0]) in the power modes register (Address 0x08) to 10. See the Memory Map section and [AN-877 Application Note, Interfacing to High Speed ADCs via SPI](#) for additional details.

DIGITAL OUTPUTS

The AD9634 output drivers can be configured for either ANSI LVDS or reduced swing LVDS using a 1.8 V DRVDD supply.

As detailed in the [AN-877 Application Note, Interfacing to High Speed ADCs via SPI](#), the data format can be selected for offset binary, twos complement, or gray code when using the SPI control.

Digital Output Enable Function (OEB)

The AD9634 has a flexible three-state ability for the digital output pins. The three-state mode is enabled using the SPI interface. The data outputs can be three-stated by using the output enable bar bit (Bit 4) in Register 0x14. This OEB function is not intended for rapid access to the data bus.

Timing

The AD9634 provides latched data with a pipeline delay of 10 input sample clock cycles. Data outputs are available one propagation delay (t_{PD}) after the rising edge of the clock signal.

Minimize the length of the output data lines as well as the loads placed on these lines to reduce transients within the AD9634. These transients may degrade converter dynamic performance.

The lowest typical conversion rate of the AD9634 is 40 MSPS. At clock rates below 40 MSPS, dynamic performance can degrade.

Data Clock Output (DCO)

The AD9634 also provides the data clock output (DCO) intended for capturing the data in an external register. Figure 2 shows timing diagram of the AD9634 output modes.

ADC OVERRANGE (OR)

The ADC overrange indicator is asserted when an overrange is detected on the input of the ADC. The overrange condition is determined at the output of the ADC pipeline and, therefore, is subject to a latency of 10 ADC clock cycles. An overrange at the input is indicated by this bit 10 clock cycles after it occurs.

Table 10. Output Data Format

Input (V)	VIN+ – VIN–, Input Span = 1.75 V p-p (V)	Offset Binary Output Mode	Twos Complement Mode (Default)	OR
VIN+ – VIN–	< –0.875	0000 0000 0000	1000 0000 0000	1
VIN+ – VIN–	= –0.875	0000 0000 0000	1000 0000 0000	0
VIN+ – VIN–	= 0	1000 0000 0000	0000 0000 0000	0
VIN+ – VIN–	= +0.875	1111 1111 1111	0111 1111 1111	0
VIN+ – VIN–	> +0.875	1111 1111 1111	0111 1111 1111	1

SERIAL PORT INTERFACE (SPI)

The [AD9634](#) serial port interface (SPI) allows the user to configure the converter for specific functions or operations through a structured register space provided inside the ADC. The SPI offers added flexibility and customization, depending on the application. Addresses are accessed via the serial port and can be written to or read from via the port. Memory is organized into bytes that can be further divided into fields. These fields are documented in the Memory Map section. For detailed operational information, see the [AN-877 Application Note, Interfacing to High Speed ADCs via SPI](#).

CONFIGURATION USING THE SPI

Three pins define the SPI of this ADC: the SCLK pin, the SDIO pin, and the CSB pin (see Table 11). The SCLK (serial clock) pin is used to synchronize the read and write data presented from and to the ADC. The SDIO (serial data input/output) pin is a dual-purpose pin that allows data to be sent and read from the internal ADC memory map registers. The CSB (chip select bar) pin is an active-low control that enables or disables the read and write cycles.

Table 11. Serial Port Interface Pins

Pin	Function
SCLK	Serial clock. The serial shift clock input, which is used to synchronize serial interface reads and writes.
SDIO	Serial data input/output. A dual-purpose pin that typically serves as an input or an output, depending on the instruction being sent and the relative position in the timing frame.
CSB	Chip select bar. An active-low control that gates the read and write cycles.

The falling edge of CSB, in conjunction with the rising edge of SCLK, determines the start of the framing. An example of the serial timing and its definitions can be found in Figure 58 and Table 5.

Other modes involving the CSB are available. The CSB can be held low indefinitely, which permanently enables the device; this is called streaming. The CSB can stall high between bytes to allow for additional external timing. When CSB is tied high, SPI functions are placed in a high impedance mode. This mode turns on any SPI pin secondary functions.

During an instruction phase, a 16-bit instruction is transmitted. Data follows the instruction phase, and its length is determined by the W0 and W1 bits.

All data is composed of 8-bit words. The first bit of each individual byte of serial data indicates whether a read or write command is issued. This allows the serial data input/output (SDIO) pin to change direction from an input to an output.

In addition to word length, the instruction phase determines whether the serial frame is a read or write operation, allowing the serial port to be used both to program the chip and to read the contents of the on-chip memory. If the instruction is a readback operation, performing a readback causes the serial data input/output (SDIO) pin to change direction from an input to an output at the appropriate point in the serial frame.

Data can be sent in MSB-first mode or in LSB-first mode. MSB-first mode is the default on power-up and can be changed via the SPI port configuration register. For more information about this and other features, see the [AN-877 Application Note, Interfacing to High Speed ADCs via SPI](#).

HARDWARE INTERFACE

The pins described in Table 11 comprise the physical interface between the user programming device and the serial port of the [AD9634](#). The SCLK pin and the CSB pin function as inputs when using the SPI interface. The SDIO pin is bidirectional, functioning as an input during write phases and as an output during readback.

The SPI interface is flexible enough to be controlled by either FPGAs or microcontrollers. One method for SPI configuration is described in detail in the [AN-812 Application Note, Microcontroller-Based Serial Port Interface \(SPI\) Boot Circuit](#).

The SPI port should not be active during periods when the full dynamic performance of the converter is required. Because the SCLK signal, the CSB signal, and the SDIO signal are typically asynchronous to the ADC clock, noise from these signals can degrade converter performance. If the on-board SPI bus is used for other devices, it may be necessary to provide buffers between this bus and the [AD9634](#) to prevent these signals from transitioning at the converter inputs during critical sampling periods.

SPI ACCESSIBLE FEATURES

Table 12 provides a brief description of the general features that are accessible via the SPI. These features are described in detail in [AN-877 Application Note, Interfacing to High Speed ADCs via SPI](#).

Table 12. Features Accessible Using the SPI

Feature Name	Description
Mode	Allows the user to set either power-down mode or standby mode
Clock	Allows the user to access the DCS via the SPI
Offset	Allows the user to digitally adjust the converter offset
Test I/O	Allows the user to set test modes to have known data on output bits
Output Mode	Allows the user to set up outputs
Output Phase	Allows the user to set the output clock polarity
Output Delay	Allows the user to vary the DCO delay
VREF	Allows the user to set the reference voltage
Digital Processing	Allows the user to enable the synchronization features

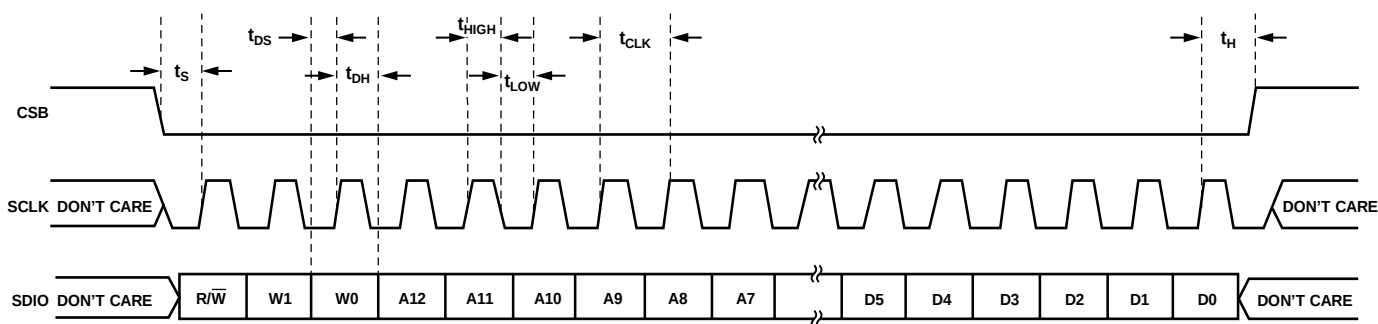


Figure 58. Serial Port Interface Timing Diagram

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MEMORY MAP

READING THE MEMORY MAP REGISTER TABLE

Each row in the memory map register table has eight bit locations. The memory map is roughly divided into three sections: the chip configuration registers (Address 0x00 to Address 0x02), the transfer register (Address 0xFF), and the ADC functions registers (Address 0x08 to Address 0x20), including setup, control, and test.

The memory map register table (Table 13) documents the default hexadecimal value for each hexadecimal address shown. The Bit 7 (MSB) column is the start of the default hexadecimal value given. For example, Address 0x14, the output mode register, has a hexadecimal default value of 0x01. This means that Bit 0 = 1 and the remaining bits are 0s. This setting is the default output format value, which is twos complement. For more information on this function and others, see the [AN-877 Application Note, Interfacing to High Speed ADCs via SPI](#). This document details the functions controlled by Register 0x00 to Register 0x20.

Open Locations

All address and bit locations that are not included in Table 13 are not currently supported for this device. Write 0s to unused bits of a valid address location. Writing to these locations is required only when part of an address location is open (for example, Address 0x18). If the entire address location is open (for example, Address 0x13), do not write to this address location.

Default Values

After the [AD9634](#) is reset, critical registers are loaded with default values. The default values for the registers are given in the memory map register table (see Table 13).

Logic Levels

An explanation of logic level terminology follows:

- “Bit is set” is synonymous with “bit is set to Logic 1” or “writing Logic 1 for the bit.”
- “Clear a bit” is synonymous with “bit is set to Logic 0” or “writing Logic 0 for the bit.”

Transfer Register Map

Address 0x08 to Address 0x20 are shadowed. Writes to these addresses do not affect part operation until a transfer command is issued by writing 0x01 to Address 0xFF, setting the transfer bit. This allows these registers to be updated internally and simultaneously when the transfer bit is set. The internal update takes place when the transfer bit is set, and then the bit autoclears.

MEMORY MAP REGISTER TABLE

All address and bit locations that are not included in Table 13 are not currently supported for this device.

Table 13. Memory Map Registers

Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default Value (Hex)	Default Notes/ Comments
Chip Configuration Registers											
0x00	SPI port configuration	0	LSB first	Soft reset	1	1	Soft reset	LSB first	0	0x18	Nibbles are mirrored so that LSB-first mode or MSB-first mode is set correctly, regardless of shift mode.
0x01	Chip ID	8-bit chip ID[7:0], AD9634 = 0x87 (default)								0x87	Read only.
0x02	Chip grade	Open	Open	Speed grade ID; 00 = 250 MSPS 01 = 210 MSPS 11 = 170 MSPS		Open	Open	Open	Open		Speed grade ID used to differentiate devices; read only.
Transfer Register											
0xFF	Transfer	Open	Open	Open	Open	Open	Open	Open	Transfer	0x00	Synchronously transfers data from the master shift register to the slave.
ADC Function Registers											
0x08	Power modes	Open	Open	Open	Open	Open	Open	Internal power-down mode 00 = normal operation 01 = full power-down 10 = standby 11 = reserved		0x00	Determines various generic modes of chip operation.
0x09	Global clock	Open	Open	Open	Open	Open	Open	Open	Duty cycle stabilizer (default)	0x01	
0x0B	Clock divide	Open	Open	Input clock divider phase adjust 000 = no delay 001 = 1 input clock cycle 010 = 2 input clock cycles 011 = 3 input clock cycles 100 = 4 input clock cycles 101 = 5 input clock cycles 110 = 6 input clock cycles 111 = 7 input clock cycles			Clock divide ratio 000 = divide by 1 001 = divide by 2 010 = divide by 3 011 = divide by 4 100 = divide by 5 101 = divide by 6 110 = divide by 7 111 = divide by 8		0x00	Clock divide values other than 000 automatically cause the duty cycle stabilizer to become active.	
0x0D	Test mode	Test mode 0 = continuous/ repeat pattern 1 = single pattern then zeros	Open	Reset PN long gen	Reset PN short gen	Output test mode 0000 = off (default) 0001 = midscale short 0010 = positive FS 0011 = negative FS 0100 = alternating checkerboard 0101 = PN long sequence 0110 = PN short sequence 0111 = one/zero word toggle 1000 = user test mode 1001 to 1110 = unused 1111 = ramp output				0x00	When this register is set, the test data is placed on the output pins in place of normal data.
0x10	Offset adjust	Open	Open	Offset adjust in LSBs from +31 to −32 (twos complement format)						0x00	

Addr (Hex)	Register Name	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)	Default Value (Hex)	Default Notes/ Comments
0x14	Output mode	Open	Open	Open	Output enable bar 0 = on (default) 1 = off	Open	Output invert 0 = normal (default) 1 = inverted	Output format 00 = offset binary 01 = twos complement (default) 10 = gray code 11 = reserved		0x01	Configures the outputs and the format of the data.
0x15	Output adjust	Open	Open	Open	Open	LVDS output drive current adjust 0000 = 3.72 mA output drive current 0001 = 3.5 mA output drive current (default) 0010 = 3.30 mA output drive current 0011 = 2.96 mA output drive current 0100 = 2.82 mA output drive current 0101 = 2.57 mA output drive current 0110 = 2.27 mA output drive current 0111 = 2.0 mA output drive current (reduced range) 1000 to 1111 = reserved				0x01	
0x16	Clock phase control	Invert DCO clock	Open	Open	Open	Open	Open	Open	Open	0x00	
0x17	DCO output delay	Enable DCO clock delay	Open	Open	DCO clock delay [delay = (3100 ps × register value/31 + 100)] 00000 = 100 ps 00001 = 200 ps 00010 = 300 ps ... 11110 = 3100 ps 11111 = 3200 ps					0x00	
0x18	Input span select	Open	Open	Open	Full-scale input voltage selection 01111 = 2.087 V p-p ... 00001 = 1.772 V p-p 00000 = 1.75 V p-p (default) 11111 = 1.727 V p-p ... 10000 = 1.383 V p-p					0x00	Full-scale input adjustment in 0.022 V steps.
0x19	User Test Pattern 1 LSB	User Test Pattern 1[7:0]								0x00	
0x1A	User Test Pattern 1 MSB	User Test Pattern 1[15:8]								0x00	
0x1B	User Test Pattern 2 LSB	User Test Pattern 2[7:0]								0x00	
0x1C	User Test Pattern 2 MSB	User Test Pattern 2[15:8]								0x00	
0x1D	User Test Pattern 3 LSB	User Test Pattern 3[7:0]								0x00	
0x1E	User Test Pattern 3 MSB	User Test Pattern 3[15:8]								0x00	
0x1F	User Test Pattern 4 LSB	User Test Pattern 4[7:0]								0x00	
0x20	User Test Pattern 4 MSB	User Test Pattern 4[15:8]								0x00	

APPLICATIONS INFORMATION

DESIGN GUIDELINES

Before starting system-level design and layout of the [AD9634](#), it is recommended that the designer become familiar with these guidelines, which describe the special circuit connections and layout requirements needed for certain pins.

Power and Ground Recommendations

When connecting power to the [AD9634](#), it is recommended that two separate 1.8 V supplies be used: use one supply for analog (AVDD) and a separate supply for digital outputs (DRVDD). The designer can employ several different decoupling capacitors to cover both high and low frequencies. Locate these capacitors close to the point of entry at the PC board level and close to the pins of the part with minimal trace length.

A single PCB ground plane should be sufficient when using the [AD9634](#). With proper decoupling and smart partitioning of the PCB analog, digital, and clock sections, optimum performance can be easily achieved.

Exposed Paddle Thermal Heat Slug Recommendations

It is mandatory that the exposed paddle on the underside of the ADC be connected to analog ground (AGND) to achieve the best electrical and thermal performance. A continuous, exposed (no solder mask) copper plane on the PCB should be connected to the [AD9634](#) exposed paddle, Pin 0.

The copper plane should have several vias to achieve the lowest possible resistive thermal path for heat dissipation to flow through the bottom of the PCB. These vias should be filled or plugged with nonconductive epoxy.

To maximize the coverage and adhesion between the ADC and the PCB, overlay a silkscreen to partition the continuous plane on the PCB into several uniform sections. This provides several tie points between the ADC and the PCB during the reflow process. Using one continuous plane with no partitions guarantees only one tie point between the ADC and the PCB. See the evaluation board for a PCB layout example. For detailed information about the packaging and PCB layout of chip scale packages, refer to the [AN-772 Application Note, A Design and Manufacturing Guide for the Lead Frame Chip Scale Package \(LFCS\)](#).

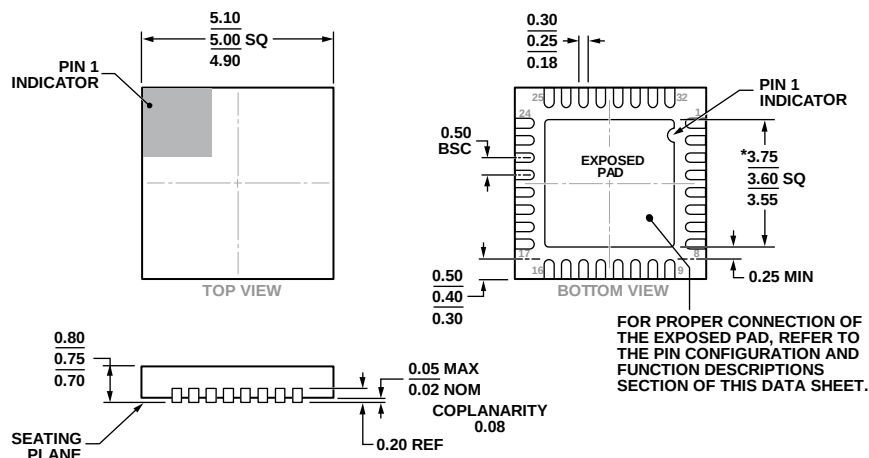
VCM

Decouple the VCM pin to ground with a 0.1 μ F capacitor, as shown in Figure 48.

SPI Port

The SPI port should not be active during periods when the full dynamic performance of the converter is required. Because the SCLK, CSB, and SDIO signals are typically asynchronous to the ADC clock, noise from these signals can degrade converter performance. If the on-board SPI bus is used for other devices, it may be necessary to provide buffers between this bus and the [AD9634](#) to keep these signals from transitioning at the converter input pins during critical sampling periods.

OUTLINE DIMENSIONS



*COMPLIANT TO JEDEC STANDARDS MO-220-WHHD-5
WITH THE EXCEPTION OF THE EXPOSED PAD DIMENSION.

Figure 59. 32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]
5 mm × 5 mm Body, Very Very Thin Quad
(CP-32-12)
Dimensions shown in millimeters

08-16-2010-B

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option
AD9634BCPZ-250	−40°C to +85°C	32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-32-12
AD9634BCPZRL7-250	−40°C to +85°C	32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-32-12
AD9634BCPZ-210	−40°C to +85°C	32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-32-12
AD9634BCPZRL7-210	−40°C to +85°C	32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-32-12
AD9634BCPZ-170	−40°C to +85°C	32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-32-12
AD9634BCPZRL7-170	−40°C to +85°C	32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-32-12
AD9634-170EBZ		Evaluation Board with AD9634 and Software	
AD9634-210EBZ		Evaluation Board with AD9634 and Software	
AD9634-250EBZ		Evaluation Board with AD9634 and Software	

¹ Z = RoHS Compliant Part.