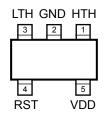
Ordering Information

Part Number				Output Polority	Acourcov	Tomporatura Bongo	Deekere	
Standard	Marking	Pb-Free	Marking	Output Polarity	Accuracy	Temperature Range	Package	
MIC2779H-2BM5	UPA2	MIC2779H-2YM5	<u>UP</u> A2	Active-High RST	2%	–40°C to +85°C	SOT-23-5	
MIC2779H-1BM5	UPA1	MIC2779H-1YM5	<u>UP</u> A1	Active-High RST	1%	–40°C to +85°C	SOT-23-5	
MIC2779L-2BM5	UPB2	MIC2779L-2YM5	<u>UP</u> B2	Active-Low /RST	2%	–40°C to +85°C	SOT-23-5	
MIC2779L-1BM5	UPB1	MIC2779L-1YM5	<u>UP</u> B1	Active-Low /RST	1%	–40°C to +85°C	SOT-23-5	

Pin Configuration



SOT-23-5 (M5) "H" Version

LTH	GND	HTH
	2	
4		5
/RS1	Г	VDD

SOT-23-5 (M5) "L" Version

Pin Description

Pin Number MIC2779H	Pin Number MIC2779L	Pin Name	Pin Function	
1	1	HTH	High-Voltage Theshold (Input): Analog input to a comparator. When the level on this pin initially rises above V _{REF} , the delay generator cycles and the /RST remains low or RST remains high for a minimum of 140ms.	
2	2	GND	Ground	
3	3	LTH	Low-Voltage Threshold (Input): Analog input to a comparator. This is the voltage monitor input assigned to detect a low voltage condition. When the level on this pin falls below V_{REF} , /RST or RST is asserted and the condition is latched until $V_{HTH} > V_{REF}$.	
4		RST	Reset (Output): Push-pull output. This output is asserted and latched when $V_{LTH} < V_{REF}$, indicating a low voltage condition. This state remains latched until $V_{HTH} > V_{REF}$. The polarity of this signal (active-high or low) is determined by the part number suffix. See ordering information.	
	4	/RST	Reset (Output): Push-pull output. This output is asserted and latched when $V_{LTH} < V_{REF}$, indicating a low voltage condition. This state remains latched until $V_{HTH} > V_{REF}$. The polarity of this signal (active-high or low) is determined by the part number suffix. See ordering information.	
5	5	VDD	Power Supply (Input): Independent supply input for internal circuitry.	

Supply Voltage (V _{DD})–0.3V to +7V	
Input Voltages (V _{LTH} , V _{HTH} , V _{/RST} , V _{RST})–0.3V to +7V	
/RST, RST Output Current (I _{/RST}), (I _{RST})	
Storage Temperature (T _S) –65°C to +150°C	
ESD Rating, Note 3	

Operating Ratings (Note 2)

Supply Voltage (V _{DD}) +1.5V to +5.5V
Input Voltages (V _{LTH} , V _{HTH} , V _{/RST} , V _{RST})–0.3V to +6.0V
Ambient Temperature Range (T _A) –40°C to +85°C
Package Thermal Resistance256°C/W

Electrical Characteristics

 $1.5V \le V_{DD} \le 5.5V$; T_A = +25°C, **bold** values indicate $-40^{\circ}C \le T_{A} \le +85^{\circ}C$; unless noted

Symbol	Parameter	Condition	Min	Тур	Max	Units
I _{DD}	Supply Current	/RST, RST not asserted		1	2	μA
I _{lth,} I _{hth}	Input Leakage Current			5		pА
					10	nA
V _{REF}	Reference Voltage			1.240		V
		MIC2779H/L-2	1.215		1.265	V
		MIC2779H/L-1	1.228		1.252	V
t _D	Propagation Delay	$V_{LTH} = V_{REF(max)} + 100mV$ to $V_{REF(min)} - 100mV$		5		μs
t _{RESET}	Reset Pulse Width		140		420	ms
V _{OL}	Reset Output Low Voltage	/RST asserted or RST not asserted, $I_{SINK} = 1.6mA, V_{DD} \ge 1.6V$			0.3	V
		/RST asserted or RST not asserted, $I_{SINK} = 100\mu A, V_{DD} \ge 1.2V,$			0.4	V
V _{OH}	Reset Output High Voltage	/RST not asserted or RST asserted, $I_{SOURCE} = 500 \mu A, V_{DD} \ge 1.6 V$	0.8V _{DD}			V
		/RST not asserted or RST asserted, $I_{SOURCE} = 50\mu A, V_{DD} \ge 1.2V,$	0.8V _{DD}			V

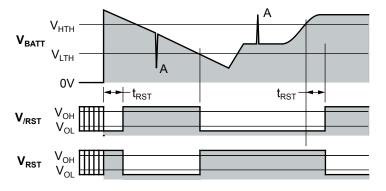
Exceeding the absolute maximum rating may damage the device. Note 1.

Note 2. The device is not guaranteed to function outside its operating rating.

Devices are ESD sensitive. Handling precautions recommended. Human body model, 1.5k in series with 100pF. Note 3.

Note 4. V_{DD} operating range is 1.5V to 5.5V. Output is guaranteed to be held low down to V_{DD} = 1.2V.

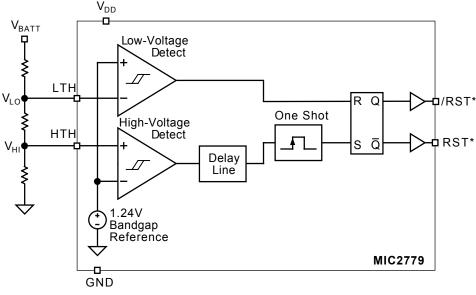
Timing Diagram



Propagation delays not shown for clarity.

Note A. The MIC2779 ignores very brief transients. See "Applications Information" for details.

Functional Diagram



* Pinout and polarity vary by device type. See ordering information table.

Functional Description

The MIC2779 monitors the voltage of a battery and detects when it is discharged below a programmed level. Upon being replaced, or being recharged above a second higher programmed trip point, the output remains low (MIC2779L) or high (MIC2779H) for a minimum of 140ms and then sends a reset signal to a microprocessor or other downstream component. See "Timing Diagram."

/RST, RST Low Output

The output is a push-pull logic signal which is asserted when the MIC2779 detects a low input voltage. The MIC2779L's /RST output is active-low; the MIC2779H's RST output is active-high.

Trip Points

Battery voltage is monitored by a comparator via a voltage divider network. The divided voltage is compared to an internal reference voltage. When the voltage at the LTH input pin drops below the internal reference voltage, the output is asserted. At this point, the voltage at HTH is assumed to be below the reference voltage.

Delay

At power-on or when the battery is replaced or recharged, and the voltage at HTH exceeds the reference voltage, the output is deasserted after a minimum delay of 140ms.

Applications Information

Programming the Thresholds

The low-voltage threshold is calculated using:

$$V_{BAT(lo)} = V_{REF} \left(\frac{R1 + R2 + R3}{R2 + R3} \right)$$

The high-voltage threshold is calculated using:

$$V_{BAT(hi)} = V_{REF} \left(\frac{R1 + R2 + R3}{R3} \right)$$

where, for both equations:

V_{REF} = 1.240V

In order to provide the additional criteria needed to solve for the resistor values, the resistors can be selected such that they have a given total value, that is, R1 + R2 + R3 = R_{TOTAL} . A value such as 1M Ω for R_{TOTAL} is a reasonable value because it draws minimum battery current but has no measurable effect on accuracy.

When working with large resistors, a small amount of leakage current can cause voltage offsets that degrade system accuracy. The maximum recommended total resistance from V_{BAT} to ground is 3M Ω .

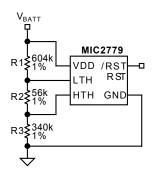


Figure 1. Example Circuit

Once the desired trip points are determined, set the $\mathrm{V}_{\mathrm{BAT}(\mathrm{hi})}$ threshold first.

For example, use a total of $1M\Omega = R1 + R2 + R3$. For a typical single-cell lithium ion battery, 3.6V is a good "high threshold" because at 3.6V the battery is moderately charged. Solving for R3:

$$V_{BAT(hi)} = 1.24 \left(\frac{1M\Omega}{R3}\right)$$

R3 = 344kΩ

Once R3 is determined, the equation for $V_{BAT(lo)}$ can be used to determine R2. A single lithium-ion cell should not be discharged below 2.5V. Many applications limit the drain to 3.1V. Using 3.1V for the $V_{BAT(lo)}$ threshold allows calculation of the two remaining resistor values.

$$V_{BAT(lo)} = 3.1V = 1.24 \left(\frac{1M\Omega}{R2 + 344k} \right)$$

R2 = 56kΩ
R1 = 1MΩ - R2 - R3
R1 = 600kΩ

The accuracy of the resistors can be chosen based upon the accuracy required by the system.

Input Transients

The MIC2779 is inherently immune to very short negativegoing "glitches." Very brief transients may exceed the $\rm V_{BAT(lo)}$ threshold without tripping the output.

As shown in Figure 2, the narrower the transient, the deeper the threshold overdrive that will be ignored by the MIC2779. The graph represents the typical allowable transient duration for a given amount of threshold overdrive that will not generate a reset.

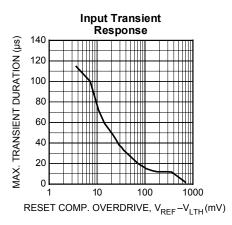
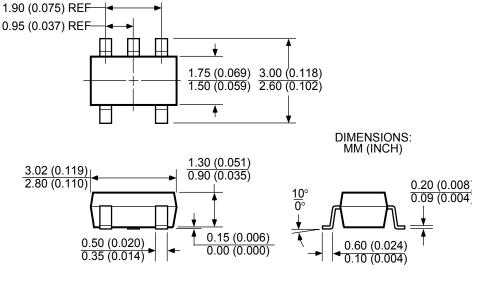


Figure 2. Input Transient Response

Package Information



5-Pin SOT-23 (M5)

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