ABSOLUTE MAXIMUM RATINGS

V חס to GND	0.2 // to 1.60 //
PV to GND	0.3V to +12.0V
All Other Pins to GND	0.3V to $(V_{DD} + 0.3V)$
Maximum Continuous Current into H,	L, and W
MAX5527	±0.5mA
MAX5528	±1.0mA
MAX5529	±2.0mA

Continuous Power Dissipation ($T_A = +70^{\circ}C$)
8-Pin µMAX (derate 4.5mW/°C above +70°C)
8-Pin TDFN (derate 18.2mW/°C above +70°C)1454.5mW
Operating Temperature Range40°C to +105°C
Junction Temperature+150°C
Storage Temperature Range65°C to +150°C
Lead Temperature (soldering, 10s)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{DD} = +2.7V \text{ to } +5.5V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +105^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5.0V, T_A = +25^{\circ}C.)$ (Note 1)

PARAMETER	SYMBOL	CONDITIONS	6	MIN	ТҮР	МАХ	UNITS	
DC PERFORMANCE	•			•				
Resolution				64			Taps	
		MAX5527		75	100	125		
End-to-End Resistance		MAX5528		37.5	50	62.5	kΩ	
		MAX5529		7.5	10	12.5		
End-to-End Resistance Temperature Coefficent	TCR				35		ppm/°C	
Resistance Ratio Temperature		MAX5527/MAX5528			5			
Coefficient		MAX5529			10		ppm/°C	
Integral Nonlinearity	INL	Potentiometer configuration, Figure 1	no load,		±0.025	±1	LSB	
Differential Nonlinearity	DNL	Potentiometer configuration, Figure 1	no load,		±0.01	±1	LSB	
Full-Scale Error		Potentiometer configuration, no load, Figure 1			-0.005	-1	LSB	
Zero-Scale Error		Potentiometer configuration, no load, Figure 1			+0.006	+1	LSB	
	Rw	$V_{DD} \ge 3V$			90	200	0	
Wiper Resistance (Note 2)		$V_{DD} < 3V$	125		125	650	Ω	
DYNAMIC CHARACTERISTICS		·						
		MAX5527			100			
Wiper -3dB Bandwidth (Note 3)		MAX5528			200		kHz	
		MAX5529			1000			
			MAX5527		-78			
Total Harmonic Distortion		f = 10kHz, midscale, 1V _{RMS} R _L = 100k Ω	MAX5528		-82		dB	
	112 - 100/22	MAX5529		-94				

2

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = +2.7V \text{ to } +5.5V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +105^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5.0V, T_A = +25^{\circ}C.)$ (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
DIGITAL INPUTS (CS, U/D)						
Input High Voltage	VIH		0.7 x V _{DD}			V
Input Low Voltage	VIL				0.3 x V _{DD}	V
Input Current	lin			±0.1	±1	μA
Input Capacitance	CIN			5		рF
TIMING CHARACTERISTICS (N	ote 4)					
U/\overline{D} Mode to \overline{CS} Setup Time	tcu	Figures 2 and 3	50			ns
U/\overline{D} Mode to \overline{CS} Hold Time	tCI	Figures 2 and 3	50			ns
$\overline{\text{CS}}$ to U/D Step Hold Time	tic	Figures 2 and 3	0			ns
U/D Step Low Time	tı∟	Figures 2 and 3	100			ns
U/D Step High Time	tıH	Figures 2 and 3	100			ns
Wiper Settling Time	tıw	$C_L = 0pF$, Figures 2 and 3 (Note 5)		400		ns
PV Rising Edge to $\overline{\text{CS}}$ Falling Edge	tPC	Figure 5	1			ms
CS Falling Edge to PV Falling Edge	tCP	Figure 5	5			ms
CS Step Low Time	tCL	Figure 5	5			ms
CS Step High Time	tсн	Figure 5	5			ms
PV Falling Edge to CS Rising Edge	tрн	Figure 5	1			ms
U/D Frequency	fu/dmax				5	MHz
Power-Up Time	tup	(Note 6)			1	ms
POWER SUPPLY	<u>.</u>					
Supply Voltage	V _{DD}		2.7		5.5	V
Static Supply Current	IDD	$\overline{CS} = U/\overline{D} = GND \text{ or } V_{DD}$			1.5	μA
		T _A < +50°C	10.45		11.55	V
Programming Voltage	PV	T _A ≥ +50°C	11.00		11.55	V
Programming Current	IPV	V _{PV} = 11V		4	5	mA

Note 1: All devices are production tested at $T_A = +25^{\circ}$ C, and are guaranteed by design for $T_A = -40^{\circ}$ C to $+105^{\circ}$ C.

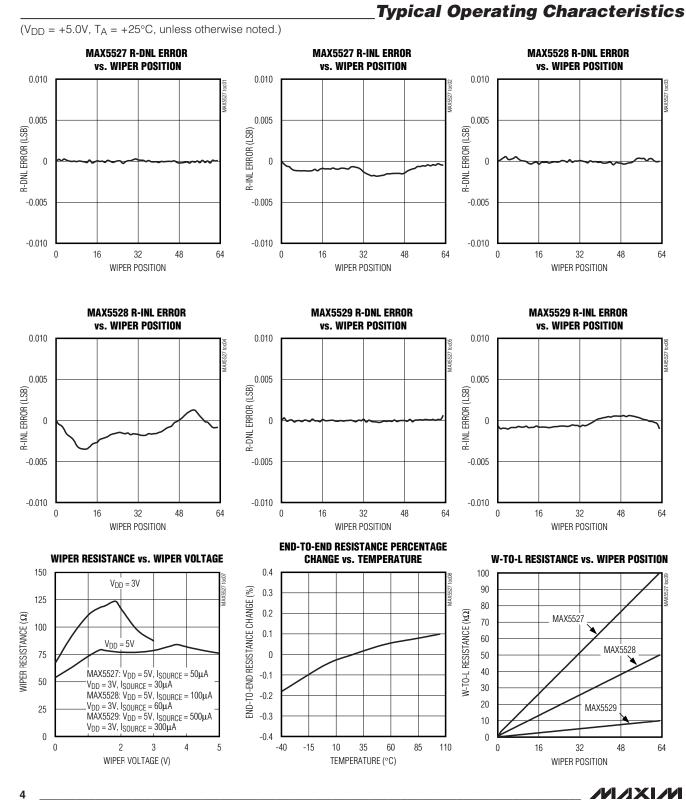
Note 2: The wiper resistance is measured by driving the wiper terminal with a source of 20µA for the MAX5527, 40µA for the MAX5528, and 200µA for the MAX5529.

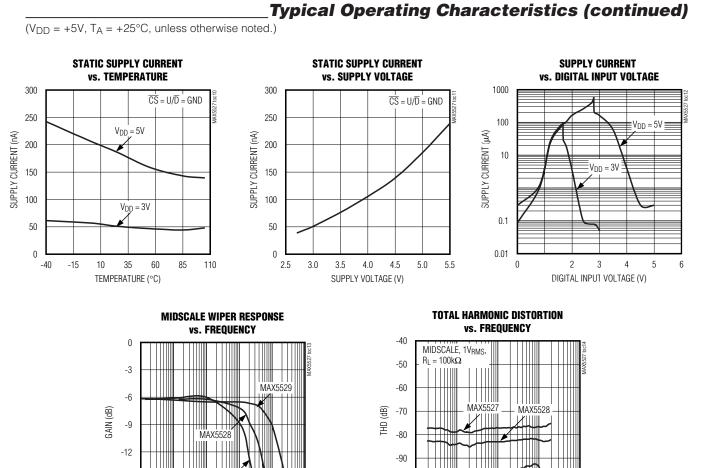
Note 3: Wiper at midscale with a 10pF load.

Note 4: Digital timing is guaranteed by design, not production tested.

Note 5: Wiper setting time is measured for a single step from U/D transition until wiper voltage reaches 90% of final value.

Note 6: Power-up time is the period of time from when the power supply is applied, until the serial interface is ready for writing.





1

FREQUENCY (kHz)

10

100

MAX5529

U/D 2V/div

GND

OUTPUT W 50mV/div

0.1

-100

-110

TAP-TO-TAP SWITCHING TRANSIENT

400ns

0.01

MAX5527

FREQUENCY (kHz)

100

10

10,000

1000

-15

-18

0.1

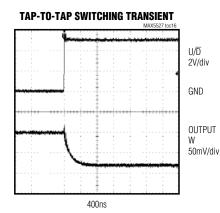
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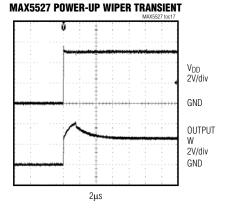
M/X/M

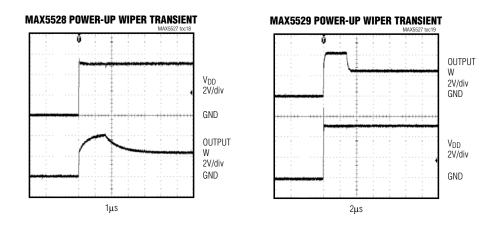


Typical Operating Characteristics (continued)

 $(V_{DD} = +5V, T_A = +25^{\circ}C, unless otherwise noted.)$







M/X/M

Pin Description

PIN	NAME	FUNCTION
1	W	Wiper Connection
2	CS	Chip-Select Input. A high-to-low \overline{CS} transition determines the increment/decrement mode. Increment if U/\overline{D} is high, or decrement if U/\overline{D} is low. \overline{CS} is also used for one-time programming. See the <i>PV One-Time Programming</i> section.
3	V _{DD}	Supply Voltage. Bypass with a 0.1µF capacitor to GND.
4	GND	Ground
5	PV	One-Time Programming Voltage. Connect PV to an 11V supply at the time the device is programmed/locked, and bypass with a 22μ F capacitor to GND. For normal operation, connect to GND or leave floating.
6	U/D	Up/Down Control Input. When \overline{CS} is low, a low-to-high transition at U/ \overline{D} increments or decrements the wiper position. See the <i>Digital Interface Operation</i> section.
7	L	Resistor Low Terminal
8	Н	Resistor High Terminal
_	EP	Exposed Pad (TDFN Only). Internally connected to GND. Connect to a large ground plane to maximize thermal dissipation.

Detailed Description

The MAX5527/MAX5528/MAX5529 100k Ω /50k Ω /10k Ω end-to-end resistance digitally-controlled potentiometers offer 64 wiper tap positions accessible along the resistor array between H and L. These devices function as potentiometers or variable resistors (see Figure 1).

The wiper (W) position is adjusted sequentially through the tap positions using a simple 2-wire up/down interface. These digital potentiometers provide an optional one-time programmable feature that sets and locks the power-on reset position of the wiper (see the *PV One-Time Programming* section). Once the desired wiper position is programmed, the 2-wire interface can be disabled to prevent unwanted adjustment.

Digital Interface Operation

The MAX5527/MAX5528/MAX5529 provide two modes of operation when the serial interface is active: increment mode or decrement mode. The serial interface is only active when $\overline{\text{CS}}$ is low.

The \overline{CS} and U/D inputs control the position of the wiper along the resistor array. Set U/D high to increment the MAX5527/MAX5528/MAX5529 when \overline{CS} transitions from high to low (Figure 2). Set U/D low to decrement the MAX5527/MAX5528/MAX5529 when \overline{CS} transitions high to low (Figure 3). Once \overline{CS} is held low, each lowto-high transition at U/D increments or decrements the wiper one position. Once the increment or decrement

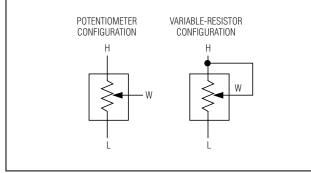


Figure 1. Potentiometer/Variable-Resistor Configuration

mode is set, the device remains in that mode until $\overline{\text{CS}}$ goes high.

Idle U/ \overline{D} high for normal operation. If U/ \overline{D} is low when \overline{CS} transitions low to high, the wiper moves one additional tap in its present direction. The wiper remains in the same position when U/ \overline{D} is high and \overline{CS} transitions low to high. After \overline{CS} returns high, the wiper position remains the same (Figure 4).

Additional increments do not change the wiper position when the wiper is at the maximum end of the resistor array. Additional decrements do not change the wiper position when the wiper is at the minimum end of the resistor array.



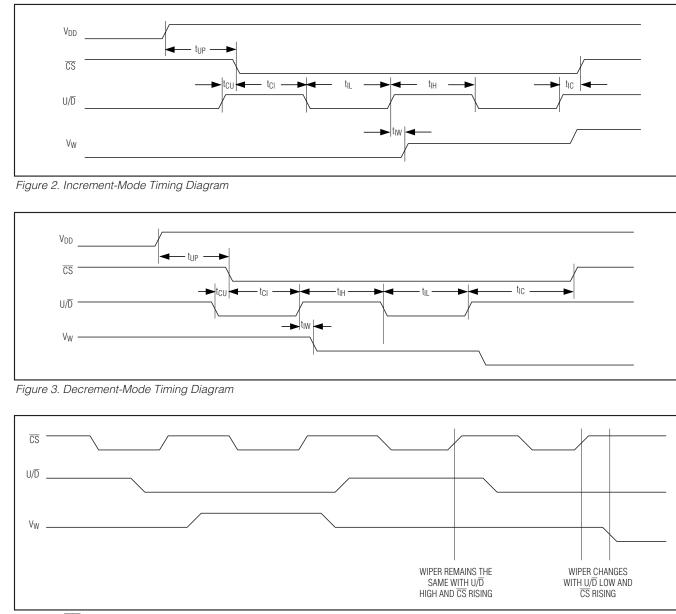


Figure 4. CS Low-to-High Transition Timing Diagram

PV One-Time Programming

The MAX5527/MAX5528/MAX5529 power up and function after power-up with the wiper position set in one of three ways:

- 1) Factory default power-up position, midscale, adjustable wiper
- 2) A newly programmed power-up position, adjustable wiper

3) A new programmed power-up position, locked wiper

The wiper is set to the factory default position at powerup (midscale, tap 31). Connect PV to GND or leave floating to continue powering up the wiper position at midscale. See Table 1 for the default and one-time programming options.







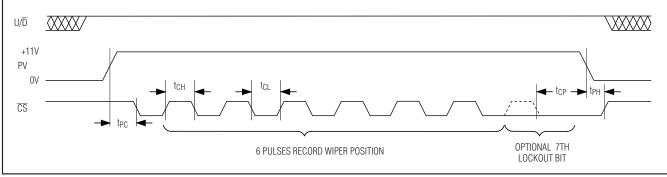


Figure 5. One-Time Program Mode, Serial-Interface Timing Diagram

MODE	POWER-ON RESET WIPER POSITION	ADJUSTABLE WIPER	
Factory Default (Unprogrammed)	Tap 31	Yes	
Programmed by Six CS Pulses	Programmed position	Yes	
Programmed by Seven CS Pulses	Programmed position	No	

Table 1. One-Time Programming Options

Change the wiper's power-up position using the PV one-time programming sequence after power-up (see Figure 5). After setting the wiper to the desired power-up position, perform the following six-step sequence:

- 1) Set U/\overline{D} and \overline{CS} high.
- 2) Connect an external voltage source at PV in the range of +11V to +11.55V.
- 3) Pull \overline{CS} low.
- 4a) Pulse CS high for six cycles, consisting of CS starting low and going high for at least t_{CH}, and then low for at least t_{CL}, to change the wiper power-up position. The wiper remains adjustable.
- 4b) Pulse CS high for seven cycles, consisting of CS starting low and going high for at least t_{CH} and then low for at least t_{CL}, to change the wiper power-up position and lock the wiper in that same position. The seventh CS pulse is labeled the optional lock-out bit in Figure 5.
- 5) Connect PV to GND or release the voltage source, leaving PV floating.
- 6) Pull $\overline{\text{CS}}$ high.

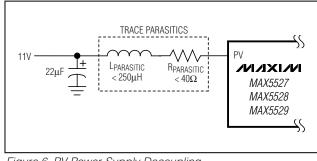


Figure 6. PV Power-Supply Decoupling

Pulse \overline{CS} high for six cycles to change the wiper powerup position. The wiper position returns to this programmed position on power-up, but remains adjustable.

Pulse \overline{CS} high for seven cycles to lock the MAX5527/ MAX5528/MAX5529 to a specific wiper position with no further adjustments allowed. This effectively converts the potentiometer to a fixed resistor-divider. The seventh pulse locks the wiper position and disables the up/down interface. Once locked, connect U/D and \overline{CS} high, low, or leave them floating without increasing the supply current (see Table 1).

If six clock pulses are used, the interface is enabled and the device can be put into program mode again. However, the part uses one-time programmable (OTP) memory and should be programmed only once. If the part is programmed more than once, all applied values are ORed together. Thus, if 010101 is programmed the first time and 101010 is programmed the second time, the result will be 111111.

The external PV power supply must source at least 5mA and have a good transient response. Decouple the PV power supply with a 22µF capacitor to GND. Ensure that no more than 250µH of inductance and/or 40 Ω of parasitic resistance exists between the capacitor and the device (see Figure 6).





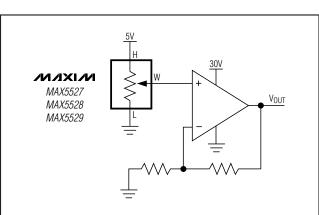


Figure 7. Positive LCD Bias Control Using a Voltage-Divider

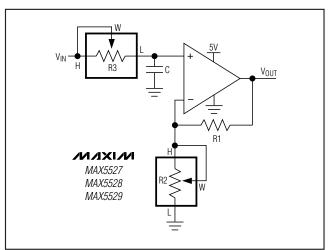


Figure 9. Programmable Filter

Applications Information

Use the MAX5527/MAX5528/MAX5529 in applications requiring digitally controlled adjustable resistance, such as LCD contrast control where voltage biasing adjusts the display contrast, or for programmable filters with adjustable gain and/or cutoff frequency.

Positive LCD Bias Control

Figures 7 and 8 show an application where the voltagedivider or variable resistor is used to make an adjustable, positive LCD bias voltage. The op-amp provides buffering and gain to the resistor-divider network made by the potentiometer (Figure 7), or to a fixed resistor and a variable resistor (Figure 8).

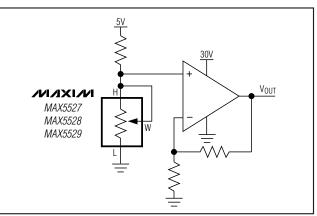


Figure 8. Positive LCD Bias Control Using a Variable Resistor

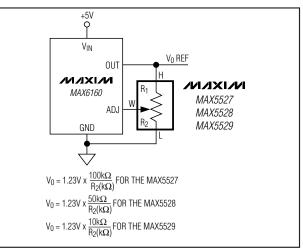


Figure 10. Adjustable Voltage Reference

Programmable Filter

Figure 9 shows the configuration for a 1st-order programmable filter. The gain of the filter is adjusted by R2, and the cutoff frequency is adjusted by R3. Use the following equations to calculate the gain (G), and the -3dB cutoff frequency (fc), only up to frequencies one decade below the wiper -3dB bandwidth.

$$G = 1 + \frac{R1}{R2}$$
$$f_{C} = \frac{1}{2\pi \times R3 \times C}$$

Adjustable Voltage Reference

Figure 10 shows the MAX5527/MAX5528/MAX5529 used as the feedback resistors in an adjustable-voltage reference application.



Layout and Power-Supply Considerations

Proper layout and power-supply bypassing can affect device performance. Bypass V_{DD} with a 0.1µF capacitor as close to the device as possible. When programming the wiper position, bypass PV with a 22µF capacitor as close to the device as possible. For a V_{DD} power supply with a slew rate greater than 1V/µs or in applications where power-supply overshoot is prevalent, connect a 10 Ω resistor in series to V_{DD} and bypass V_{DD} with an additional 4.7µF capacitor to ground.

Chip Information

TRANSISTOR COUNT: 3420 PROCESS: BICMOS

Package Information

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.
8 TDFN-EP	T833+2	<u>21-0137</u>
8 µMAX	U8+1	<u>21-0036</u>



Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	
0	5/05	Initial release	—
1	7/09	Added lead-free note to the Ordering Information. Added exposed pad information to the Pin Description. Added text to PV One-Time Programming section.	

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12

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