TO OUR VALUED CUSTOMERS

It is our intention to provide our valued customers with the best documentation possible to ensure successful use of your Microchip products. To this end, we will continue to improve our publications to better suit your needs. Our publications will be refined and enhanced as new volumes and updates are introduced.

If you have any questions or comments regarding this publication, please contact the Marketing Communications Department via E-mail at docerrors@microchip.com. We welcome your feedback.

Most Current Data Sheet

To obtain the most up-to-date version of this data sheet, please register at our Worldwide Web site at:

http://www.microchip.com

You can determine the version of a data sheet by examining its literature number found on the bottom outside corner of any page. The last character of the literature number is the version number, (e.g., DS3000000A is version A of document DS30000000).

Errata

An errata sheet, describing minor operational differences from the data sheet and recommended workarounds, may exist for current devices. As device/documentation issues become known to us, we will publish an errata sheet. The errata will specify the revision of silicon and revision of document to which it applies.

To determine if an errata sheet exists for a particular device, please check with one of the following:

- Microchip's Worldwide Web site; http://www.microchip.com
- Your local Microchip sales office (see last page)

When contacting a sales office, please specify which device, revision of silicon and data sheet (include -literature number) you are using.

Customer Notification System

Register on our web site at www.microchip.com to receive the most current information on all of our products.

Table of Contents

1.0 Introduction	4
	5
2.0 Pin Description and Configuration	5
4.0 Register Descriptions	4
5.0 Operational Characteristics	4
6 0 Electrical Characteristics	Б
7.0 Timing Diagrams	7
8.0 Reset Circuit	6
9.0 Reference Circuits — LED Strap-In Pins	7
10.0 Reference Clock - Connection and Selection5	
11.0 Magnetic - Connection and Selection	9
11.0 Magnetic - Connection and Selection	1
Appendix A: Data Sheet Revision History	2
The Microchip Web Site	3
Customer Change Notification Service	
Customer Support	3
Product Identification System	4

^{© 2018} Microchip Technology Inc.

1.0 INTRODUCTION

1.1 General Description

The KSZ8051 is an AEC-Q100 standard qualified single-supply 10BASE-T/100BASE-TX Ethernet physical-layer transceiver.

The KSZ8051 is a highly integrated PHY solution. It reduces board cost and simplifies board layout by using on-chip termination resistors for the differential pairs and by integrating a low-noise regulator to supply the 1.2V core.

The KSZ8051MNL offers the Media Independent Interface (MII) and the KSZ8051RNL offers the Reduced Media Independent Interface (RMII) for direct connection with MII-/RMII-compliant Ethernet MAC processors and switches.

A 25 MHz crystal is used to generate all required clocks, including the 50 MHz RMII reference clock output for the KSZ8051RNL.

The KSZ8051 provides diagnostic features to facilitate system bring-up and debugging in production testing and in product deployment. Parametric NAND tree support enables fault detection between KSZ8051 I/Os and the board. Microchip LinkMD[®] TDR-based cable diagnostics identify faulty copper cabling.

The KSZ8051MNL and KSZ8051RNL are available in 32-pin, lead-free QFN packages.

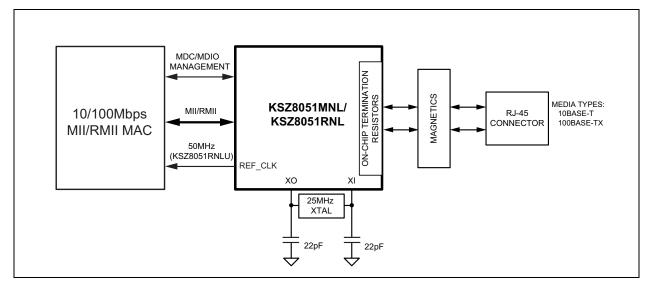


FIGURE 1-1: SYSTEM BLOCK DIAGRAM

2.0 PIN DESCRIPTION AND CONFIGURATION

FIGURE 2-1: 32-PIN 5 MM X 5 MM QFN ASSIGNMENT, KSZ8051MNL (TOP VIEW)

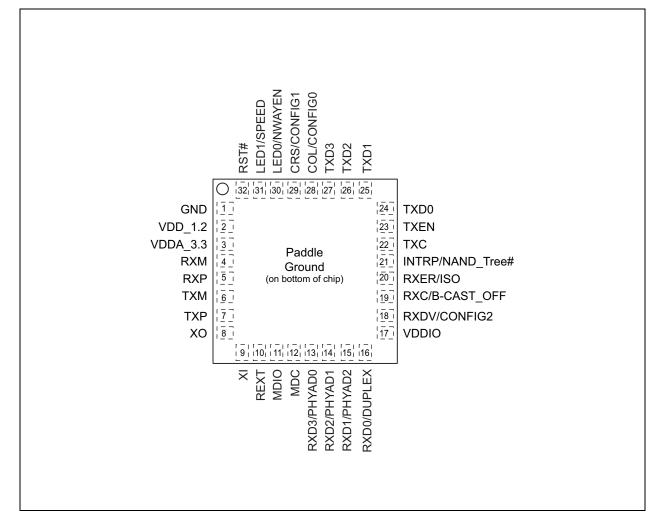


TABLE 2-1:SIGNALS - KSZ8051MNL

Pin Number	Pin Name	Type Note 2-1	Description	
1	GND	GND	Ground.	
2	VDD_1.2	Ρ	1.2V core V _{DD} (power supplied by KSZ8051MNL) Decouple with 2.2 μF and 0.1 μF capacitors to ground.	
3	VDDA_3.3	Р	3.3V analog V _{DD}	
4	RXM	I/O	Physical receive or transmit signal (– differential)	
5	RXP	I/O	Physical receive or transmit signal (+ differential)	
6	ТХМ	I/O	Physical transmit or receive signal (– differential)	

© 2018 Microchip Technology Inc.

TABLE 2-1: SIGNALS - KSZ8051MNL (CONTINUED)

Pin Number	Pin Name	Type Note 2-1	Description
7	TXP	I/O	Physical transmit or receive signal (+ differential)
8	ХО	0	Crystal feedback for 25 MHz crystal This pin is a no connect if an oscillator or external clock source is used.
9	ХІ	I	Crystal/Oscillator/External Clock input 25 MHz ±50 ppm
10	REXT	I	Set PHY transmit output current Connect a 6.49 k Ω resistor to ground on this pin.
11	MDIO	lpu/ Opu	Management Interface (MII) Data I/O This pin has a weak pull-up, is open-drain, and requires an external 1.0 k Ω pull-up resistor.
12	MDC	lpu	Management Interface (MII) Clock input This clock pin is synchronous to the MDIO data pin.
13	RXD3/ PHYAD0	lpu/O	MII mode: MII Receive Data Output[3] (Note 2-2) Config mode: The pull-up/pull-down value is latched as PHYADDR[0] at the de assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.
14	RXD2/ PHYAD1	lpd/O	MII mode: MII Receive Data Output[2] (Note 2-2) Config mode: The pull-up/pull-down value is latched as PHYADDR[1] at the deassertion of reset. See the Strap-In Options - KSZ8051MNL section for details.
15	RXD1/ PHYAD2	lpd/O	MII mode: MII Receive Data Output[1] (Note 2-2) Config mode: The pull-up/pull-down value is latched as PHYADDR[2] at the de assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.
16	RXD0/ DUPLEX	lpu/O	MII mode: MII Receive Data Output[0] (Note 2-2) Config mode: The pull-up/pull-down value is latched as DUPLEX at the de- assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.
17	VDDIO	Р	3.3V, 2.5V, or 1.8V digital V _{DD}
18	RXDV/ CONFIG2	lpd/O	MII mode: MII Receive Data Valid output Config mode: The pull-up/pull-down value is latched as CONFIG2 at the de- assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.
19	RXC/ B-CAST_OFF	lpd/O	MII mode: MII Receive Clock output Config mode: The pull-up/pull-down value is latched as B-CAST_OFF at the de assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.
20	RXER/ISO	lpd/O	MII mode: MII Receive Error output Config mode: The pull-up/pull-down value is latched as ISOLATE at the de- assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.

TABLE 2-1:	SIGNALS - KSZ8051MNL	(CONTINUED)	1
------------	----------------------	-------------	---

Pin Number	Pin Name	Type Note 2-1	Description				
21	INTRP/ NAND_Tree#	lpu/ Opu	Interrupt output: Programmable interrupt output This pin has a weak pull-up, is open-drain, and requires an external 1.0 kΩ pull-up resistor. Config mode: The pull-up/pull-down value is latched as NAND Tree# at the de-assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.				
22	тхс	I/O	MII mode: MII Transmit C MII back-to-back mode: I				
23	TXEN	I	MII mode: MII Transmit E	Enable input			
24	TXD0	I	MII mode: MII Transmit E	Data Input[0] (Note 2-3)			
25	TXD1	I	MII mode: MII Transmit E	Data Input[1] (Note 2-3)			
26	TXD2	I	MII mode: MII Transmit E	Data Input[2] (Note 2-3)			
27	TXD3	I	MII Mode: MII Transmit E	Data Input[3] (Note 2-3)			
28	COL/ CONFIG0	lpd/O	MII mode: MII Collision Detect output Config mode: The pull-up/pull-down value is latched as CONFIG0 at the de- assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.				
29	CRS/ CONFIG1	lpd/O	MII mode: MII Carrier Sense output Config mode: The pull-up/pull-down value is latched as CONFIG1 at the de- assertion of reset. See the Strap-In Options - KSZ8051MNL section for details.				
			de-assertion of reset. See the Strap-In Options	ole LED0 output auto-negotiation enable (F - KSZ8051MNL section fo mable using Register 1Fh	or details.		
			Link/Activity	Pin State	LED Definition		
			No Link	High	OFF		
30	LED0/ NWAYEN	lpu/O	Link	Low	ON		
			Activity	Toggle	Blinking		
			LED Mode = [01]	- 33			
			Link	Pin State	LED Definition		
			No Link	High	OFF		
			Link	Low	ON		
			LED Mode = [10], [11]: I	Reserved	I		

TABLE 2-1: SIGNALS - KSZ8051MNL (CONTINUED)

Pin Number	Pin Name	Type Note 2-1	Description			
		LED output: Programmable LED1 output Config mode: Latched as Speed (register 0h, bit [13]) at the de-assertion of reset. See the Strap-In Options - KSZ8051MNL section for details. The LED1 pin is programmable using register 1Fh bits [5:4], and is defined as follows.				
		LED mode = [00]				
			Speed	Pin State	LED Definition	
31	LED1/SPEED Ipu/O	lpu/O	10BASE-T	High	OFF	
			100BASE-TX	Low	ON	
			LED mode = [01]			
			Activity	Pin State	LED Definition	
			No activity	High	OFF	
			Activity	Toggle	Blinking	
			LED mode = [10], [11]: Reserved			
32	RST#	lpu	Chip reset (active low)			
PADDLE	GND	GND	Ground			

Note 2-1 P = power supply

GND = ground

I = input

O = output

I/O = bi-directional

Ipu = Input with internal pull-up (see Electrical Characteristics for value).

Ipu/O = Input with internal pull-up (see Electrical Characteristics for value) during power-up/reset; output pin otherwise.

Ipd/O = Input with internal pull-down (see Electrical Characteristics for value) during power-up/reset; output pin otherwise.

Ipu/Opu = Input with internal pull-up (see Electrical Characteristics for value) and output with internal pull-up (see Electrical Characteristics for value).

- **Note 2-2** MII RX Mode: The RXD[3:0] bits are synchronous with RXC. When RXDV is asserted, RXD[3:0] presents valid data to the MAC.
- **Note 2-3** MII TX Mode: The TXD[3:0] bits are synchronous with TXC. When TXEN is asserted, TXD[3:0] presents valid data from the MAC.

The strap-in pins are latched at the de-assertion of reset. In some systems, the MAC MII receive input pins may drive high/low during power-up or reset, and consequently cause the PHY strap-in pins on the MII signals to be latched to unintended high/low states. In this case, external pull-ups (4.7 k Ω) or pull-downs (1.0 k Ω) should be added on these PHY strap-in pins to ensure that the intended values are strapped-in correctly.

Pin Number	Pin Name	Type Note 2-4		Description		
15	PHYAD2	Ipd/O		latched at de-assertion of reset and is configurable to		
14	PHYAD1	Ipd/O	any value from 0 to 7 with PHY Address 1 as the default value.			
13	PHYAD0	lpu/O	address, but it ing the B-CAS 16h, bit [9].	PHY Address 0 is assigned by default as the broadcast PHY address, but it can be assigned as a unique PHY address after pull- ing the B-CAST_OFF strapping pin high or writing a '1' to Register 16h, bit [9]. PHY Address bits [4:3] are set to 00 by default.		
18	CONFIG2		The CONFIG[2 reset.	2:0] strap-in pins are latched at the de-assertion of		
			CONFIG[2:0]	Mode		
29	CONFIG1	Ipd/O	000	MII (default)		
			110	MII back-to-back		
28	CONFIG0		001 – 101, 111	Reserved, not used		
20	ISO	lpd/O	Isolate mode Pull-up = Enab Pull-down (def At the de-asse bit [10].			
31	SPEED	lpu/O	bit [13] as the s			
16	DUPLEX	lpu/O	Pull-down = Fu	t) = Half-duplex III-duplex rtion of reset, this pin value is latched into Register 0h		
30	NWAYEN	lpu/O	Pull-up (defaul Pull-down = Di	gotiation Enable: t) = Enable auto-negotiation sable auto-negotiation rtion of reset, this pin value is latched into Register 0h		
19	B-CAST_OFF	lpd/O	Broadcast Off – for PHY Address 0: Pull-up = PHY Address 0 is set as an unique PHY address Pull-down (default) = PHY Address 0 is set as a broadcast PHY address At the de-assertion of reset, this pin value is latched by the chip.			
21	NAND_Tree#	lpu/Opu	NAND Tree Mode: Pull-up (default) = Disable Pull-down = Enable At the de-assertion of reset, this pin value is latched by the chip.			

TABLE 2-2: STRAP-IN OPTIONS - KSZ8051MNL

Ipd/O = Input with internal pull-down during power-up/reset; output pin otherwise.

Ipu/Opu = Input with internal pull-up and output with internal pull-up.

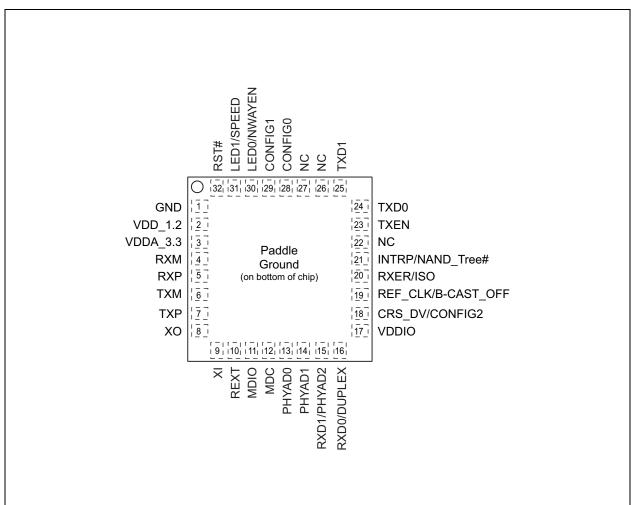


FIGURE 2-2: 32-PIN 5 MM X 5 MM QFN ASSIGNMENT, KSZ8051RNL (TOP VIEW)

TABLE 2-3: SIGNALS - KSZ8051RNL

Pin Number	Pin Name	Type Note 2-1	Description
1	GND	GND	Ground.
2	VDD_1.2	Р	1.2V core V_{DD} (power supplied by KSZ8091RNB) Decouple with 2.2 μ F and 0.1 μ F capacitors to ground.
3	VDDA_3.3	Р	3.3V analog V _{DD}
4	RXM	I/O	Physical receive or transmit signal (– differential)
5	RXP	I/O	Physical receive or transmit signal (+ differential)
6	TXM	I/O	Physical transmit or receive signal (– differential)
7	TXP	I/O	Physical transmit or receive signal (+ differential)
8	хо	0	Crystal feedback for 25 MHz crystal This pin is a no connect if an oscillator or external clock source is used.
9	XI	I	25 MHz Mode: 25 MHz ±50 ppm Crystal/Oscillator/External Clock Input 50 MHz Mode: 50 MHz ±50 ppm Oscillator/External Clock Input
10	REXT	I	Set PHY transmit output current Connect a 6.49 k Ω resistor to ground on this pin.

Pin Number	Pin Name	Type Note 2-1	Description	
11	MDIO	lpu/Opu	Management Interface (MII) Data I/O This pin has a weak pull-up, is open-drain, and requires an external 1.0 k Ω pull-up resistor.	
12	MDC	lpu	Management Interface (MII) Clock input This clock pin is synchronous to the MDIO data pin.	
13	PHYAD0	lpu/O	The pull-up/pull-down value is latched as PHYADDR[0] at the de-assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	
14	PHYAD1	lpd/O	The pull-up/pull-down value is latched as PHYADDR[1] at the de-assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	
15	RXD1/ PHYAD2	lpd/O	RMII mode: RMII Receive Data Output[1] (Note 2-2) Config mode: The pull-up/pull-down value is latched as PHYADDR[2] at the de-assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	
16	RXD0/ DUPLEX	lpu/O	RMII mode: RMII Receive Data Output[0] (Note 2-2) Config mode: The pull-up/pull-down value is latched as DUPLEX at the de- assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	
17	VDDIO	Р	3.3V, 2.5V, or 1.8V digital V _{DD}	
18	CRS_DV/ CONFIG2	lpd/O	RMII mode: RMII Carrier Sense/Receive Data Valid output Config mode: The pull-up/pull-down value is latched as CONFIG2 at the de- assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	
19	REF_CLK/ B-CAST_OFF	lpd/O	RMII mode: 25 MHz mode: This pin provides the 50 MHz RMII reference clock output to the MAC. See also XI (pin 9). 50 MHz mode: This pin is a no connect. See also XI (pin 9). Config mode: The pull-up/pull-down value is latched as B-CAST_OFF at the de-assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	
20	RXER/ISO	lpd/O	RMII mode: RMII Receive Error output Config mode: The pull-up/pull-down value is latched as ISOLATE at the de- assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	
21	INTRP/ NAND_Tree#	lpu/Opu	Interrupt output: Programmable interrupt output This pin has a weak pull-up, is open-drain, and requires an external 1.0 k Ω pull-up resistor. Config mode: The pull-up/pull-down value is latched as NAND Tree# at the de-assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	
22	NC	_	No connect – This pin is not bonded and can be left floating.	
23	TXEN	I	RMII Transmit Enable input	
24	TXD0	I	RMII Transmit Data Input[0] (Note 2-3)	
25	TXD1	1	RMII Transmit Data Input[1] (Note 2-3)	
26	NC	NC	No connect – This pin is not bonded and can be left floating.	
27	NC	NC	No connect – This pin is not bonded and can be left floating.	
28	CONFIG0	lpd/O	The pull-up/pull-down value is latched as CONFIG0 at the de-assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.	

TABLE 2-3: SIGNALS - KSZ8051RNL (CONTINUED)

TABLE 2-3: SIGNALS - KSZ8051RNL (CONTINUED)

Pin Number	Pin Name	Type Note 2-1	Description				
29	CONFIG1	lpd/O	The pull-up/pull-down value is latched as CONFIG1 at the de-assertion of reset. See the Strap-In Options - KSZ8051RNL section for details.				
			de-assertion of reset. See the Strap-In Options The LED0 pin is program follows.	auto-negotiation ena	ble (Register 0h, bit [12]) at the on for details. 1Fh bits [5:4], and is defined as		
			LED Mode = [00]				
	LED0/		Link/Activity	Pin State	LED Definition		
30	NWAYEN	lpu/O	No Link	High	OFF		
			Link	Low	ON		
			Activity	Toggle	Blinking		
			LED Mode = [01]				
			Link	Pin State	LED Definition		
			No Link	High	OFF		
			Link	Low	ON		
			LED Mode = [10], [11]: Reserved				
			reset. See the Strap-In Options	SPEED (Register 0h - KSZ8051RNL secti	n, bit [13]) at the de-assertion of on for details. 1Fh bits [5:4], and is defined as		
			LED Mode = [00]				
24	LED1/	Invi/O	Speed	Pin State	LED Definition		
31	SPEED	lpu/O	10BASE-T	High	OFF		
			100BASE-TX	Low	ON		
			LED Mode = [01]				
			Activity	Pin State	LED Definition		
			No Activity	High	OFF		
			Activity	Toggle	Blinking		
			LED Mode = [10], [11]: F				
32	RST#	lpu	Chip reset (active low)				
PADDLE	GND	GND	Ground				
Note 2-1	D - Dower		I				

Note 2-1 P = Power supply.

GND = Ground.

I = Input.

O = Output.

I/O = Bi-directional.

Ipu = Input with internal pull-up (see Electrical Characteristics for value).

lpu/O = Input with internal pull-up (see Electrical Characteristics for value) during power-up/reset; output pin otherwise.

Ipd/O = Input with internal pull-down (see Electrical Characteristics for value) during power-up/reset; output pin otherwise.

Ipu/Opu = Input with internal pull-up (see Electrical Characteristics for value) and output with internal pull-up (see Electrical Characteristics for value).

NC = Pin is not bonded to the die.

- Note 2-2 RMII RX Mode: The RXD[1:0] bits are synchronous with the 50 MHz RMII Reference Clock. For each clock period in which CRS_DV is asserted, two bits of recovered data are sent by the PHY to the MAC.
- **Note 2-3** RMII TX Mode: The TXD[1:0] bits are synchronous with the 50 MHz RMII Reference Clock. For each clock period in which TXEN is asserted, two bits of data are received by the PHY from the MAC.

The strap-in pins are latched at the de-assertion of reset. In some systems, the MAC RMII receive input pins may drive high/low during power-up or reset, and consequently cause the PHY strap-in pins on the RMII signals to be latched to unintended high/low states. In this case, external pull-ups (4.7 k Ω) or pull-downs (1.0 k Ω) should be added on these PHY strap-in pins to ensure that the intended values are strapped-in correctly.

Pin Number	Pin Name	Type Note 2-4		Description	
15	PHYAD2	Ipd/O		latched at de-assertion of reset and is configurable to	
14	PHYAD1	Ipd/O		0 to 7 with PHY Address 1 as the default value.	
13	PHYAD0	lpu/O	address, but it ing the B-CAS ⁻ 16h, bit [9].	b is assigned by default as the broadcast PHY can be assigned as a unique PHY address after pull- Γ_OFF strapping pin high or writing a '1' to Register bits [4:3] are set to 00 by default.	
18	CONFIG2		The CONFIG[2 reset.	2:0] strap-in pins are latched at the de-assertion of	
29	CONFIG1		CONFIG[2:0]	Mode	
29	CONFIGT	Ipd/O	001	RMII (default)	
			101	RMII back-to-back	
28	CONFIG0		000, 010 – 100, 110, 111	Reserved, not used	
20	ISO	lpd/O	Isolate mode Pull-up = Enable Pull-down (default) = Disable At the de-assertion of reset, this pin value is latched into Regist bit [10].		
31	SPEED	lpu/O	Speed mode Pull-up (default) = 100 Mbps Pull-down = 10 Mbps At the de-assertion of reset, this pin value is latched into Regist bit [13] as the speed select, and also is latched into Register 4 (auto-negotiation advertisement) as the speed capability support		
16	DUPLEX	lpu/O	Pull-down = Fu	t) = Half-duplex III-duplex tion of reset, this pin value is latched into Register 0h,	
30	NWAYEN	lpu/O	Nway Auto-Negotiation Enable: Pull-up (default) = Enable auto-negotiation Pull-down = Disable auto-negotiation At the de-assertion of reset, this pin value is latched into Register Bit [12].		
19	B-CAST_OFF	lpd/O	Pull-up = PHY Pull-down (defa address	 for PHY Address 0: Address 0 is set as an unique PHY address ault) = PHY Address 0 is set as a broadcast PHY rtion of reset, this pin value is latched by the chip. 	

TABLE 2-4: STRAP-IN OPTIONS - KSZ8051RNL

© 2018 Microchip Technology Inc.

TABLE 2-4: STRAP-IN OPTIONS - KSZ8051RNL (CONTINUED)

Pin Number	Pin Name	Type Note 2-4	Description
21	NAND_Tree#	lpu/Opu	NAND Tree Mode: Pull-up (default) = Disable Pull-down = Enable At the de-assertion of reset, this pin value is latched by the chip.

Note 2-4 Ipu/O = Input with internal pull-up during power-up/reset; output pin otherwise. Ipd/O = Input with internal pull-down during power-up/reset; output pin otherwise. Ipu/Opu = Input with internal pull-up and output with internal pull-up.

3.0 FUNCTIONAL DESCRIPTION

The KSZ8051 is an integrated single 3.3V supply Fast Ethernet transceiver. It is fully compliant with the IEEE 802.3 Specification, and reduces board cost and simplifies board layout by using on-chip termination resistors for the two differential pairs and by integrating the regulator to supply the 1.2V core.

On the copper media side, the KSZ8051 supports 10Base-T and 100Base-TX for transmission and reception of data over a standard CAT-5 unshielded twisted pair (UTP) cable, and HP Auto MDI/MDI-X for reliable detection of and correction for straight-through and crossover cables.

On the MAC processor side, the KSZ8051MNL offers the Media Independent Interface (MII) and the KSZ8051RNL offers the Reduced Media Independent Interface (RMII) for direct connection with MII and RMII compliant Ethernet MAC processors and switches, respectively.

The MII management bus option gives the MAC processor complete access to the KSZ8051 control and status registers. Additionally, an interrupt pin eliminates the need for the processor to poll for PHY status change.

KSZ8051MNL/RNL is used in this data sheet to refer to both the KSZ8051MNL and the KSZ8051RNL devices.

3.1 10BASE-T/100BASE-TX Transceiver

3.1.1 100BASE-TX TRANSMIT

The 100Base-TX transmit function performs parallel-to-serial conversion, 4B/5B encoding, scrambling, NRZ-to-NRZI conversion, and MLT3 encoding and transmission.

The circuitry starts with a parallel-to-serial conversion, which converts the MII data from the MAC into a 125 MHz serial bit stream. The data and control stream is then converted into 4B/5B coding and followed by a scrambler. The serialized data is further converted from NRZ-to-NRZI format, and then transmitted in MLT3 current output. The output current is set by an external 6.49 k Ω 1% resistor for the 1:1 transformer ratio.

The output signal has a typical rise/fall time of 4ns and complies with the ANSI TP-PMD standard regarding amplitude balance, overshoot, and timing jitter. The wave-shaped 10Base-T output is also incorporated into the 100Base-TX transmitter.

3.1.2 100BASE-TX RECEIVE

The 100Base-TX receiver function performs adaptive equalization, DC restoration, MLT3-to-NRZI conversion, data and clock recovery, NRZI-to-NRZ conversion, de-scrambling, 4B/5B decoding, and serial-to-parallel conversion.

The receiving side starts with the equalization filter to compensate for inter-symbol interference (ISI) over the twisted pair cable. Because the amplitude loss and phase distortion is a function of the cable length, the equalizer must adjust its characteristics to optimize performance. In this design, the variable equalizer makes an initial estimation based on comparisons of incoming signal strength against some known cable characteristics, then tunes itself for optimization. This is an ongoing process and self-adjusts against environmental changes such as temperature variations.

Next, the equalized signal goes through a DC-restoration and data-conversion block. The DC-restoration circuit compensates for the effect of baseline wander and improves the dynamic range. The differential data-conversion circuit converts MLT3 format back to NRZI. The slicing threshold is also adaptive.

The clock-recovery circuit extracts the 125 MHz clock from the edges of the NRZI signal. This recovered clock is then used to convert the NRZI signal to NRZ format. This signal is sent through the de-scrambler, then the 4B/5B decoder. Finally, the NRZ serial data is converted to MII format and provided as the input data to the MAC.

3.1.3 SCRAMBLER/DE-SCRAMBLER (100BASE-TX ONLY)

The scrambler spreads the power spectrum of the transmitted signal to reduce electromagnetic interference (EMI) and baseline wander. The de-scrambler recovers the scrambled signal.

3.1.4 10BASE-T TRANSMIT

The 10Base-T drivers are incorporated with the 100Base-TX drivers to allow for transmission using the same magnetic. The drivers perform internal wave-shaping and pre-emphasis, and output 10Base-T signals with a typical amplitude of 2.5V peak. The 10Base-T signals have harmonic contents that are at least 27 dB below the fundamental frequency when driven by an all-ones Manchester-encoded signal.

^{© 2018} Microchip Technology Inc.

3.1.5 10BASE-T RECEIVE

On the receive side, input buffer and level detecting squelch circuits are used. A differential input receiver circuit and a phase-locked loop (PLL) performs the decoding function. The Manchester-encoded data stream is separated into clock signal and NRZ data. A squelch circuit rejects signals with levels less than 400 mV, or with short pulse widths, to prevent noise at the RXP and RXM inputs from falsely triggering the decoder. When the input exceeds the squelch limit, the PLL locks onto the incoming signal and the KSZ8051MNL/RNL decodes a data frame. The receive clock is kept active during idle periods between data receptions.

3.1.6 SQE AND JABBER FUNCTION (10BASE-T ONLY)

In 10Base-T operation, a short pulse is put out on the COL pin after each frame is transmitted. This SQE test is needed to test the 10Base-T transmit/receive path. If transmit enable (TXEN) is high for more than 20 ms (jabbering), the 10Base-T transmitter is disabled and COL is asserted high. If TXEN is then driven low for more than 250 ms, the 10Base-T transmitter is re-enabled and COL is de-asserted (returns to low).

3.1.7 PLL CLOCK SYNTHESIZER

The KSZ8051MNL/RNL generates all internal clocks and all external clocks for system timing from an external 25 MHz crystal, oscillator, or reference clock. For the KSZ8051RNL in RMII 50 MHz clock mode, these clocks are generated from an external 50 MHz oscillator or system clock.

3.1.8 AUTO-NEGOTIATION

The KSZ8051MNL/RNL conforms to the auto-negotiation protocol, defined in Clause 28 of the IEEE 802.3 specification.

Auto-negotiation allows unshielded twisted pair (UTP) link partners to select the highest common mode of operation.

During auto-negotiation, link partners advertise capabilities across the UTP link to each other and then compare their own capabilities with those they received from their link partners. The highest speed and duplex setting that is common to the two link partners is selected as the mode of operation.

The following list shows the speed and duplex operation mode from highest to lowest priority.

- Priority 1: 100BASE-TX, full-duplex
- Priority 2: 100BASE-TX, half-duplex
- Priority 3: 10BASE-T, full-duplex
- Priority 4: 10BASE-T, half-duplex

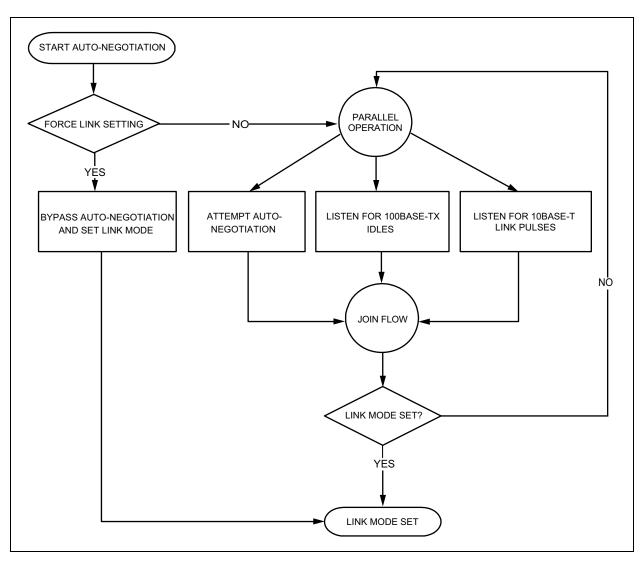
If auto-negotiation is not supported or the KSZ8051MNL/RNL link partner is forced to bypass auto-negotiation, then the KSZ8051MNL/RNL sets its operating mode by observing the signal at its receiver. This is known as parallel detection, which allows the KSZ8051MNL/RNL to establish a link by listening for a fixed signal protocol in the absence of the auto-negotiation advertisement protocol.

Auto-negotiation is enabled by either hardware pin strapping (NWAYEN, pin 30) or software (register 0h, bit [12]).

By default, auto-negotiation is enabled after power-up or hardware reset. After that, auto-negotiation can be enabled or disabled by register 0h, bit [12]. If auto-negotiation is disabled, the speed is set by register 0h, bit [13], and the duplex is set by register 0h, bit [8].

The auto-negotiation link-up process is shown in Figure 3-1.





3.2 MII Data Interface (KSZ8051MNL Only)

The Media Independent Interface (MII) is compliant with the IEEE 802.3 Specification. It provides a common interface between MII PHYs and MACs, and has the following key characteristics:

- Pin count is 15 pins (6 pins for data transmission, 7 pins for data reception, and 2 pins for carrier and collision indication).
- 10 Mbps and 100 Mbps data rates are supported at both half- and full-duplex.
- Data transmission and reception are independent and belong to separate signal groups.
- Transmit data and receive data are each 4 bits wide, a nibble.

By default, the KSZ8051MNL is configured to MII mode after it is powered up or hardware reset with the following:

- A 25 MHz crystal connected to XI, XO (pins 9, 8), or an external 25 MHz clock source (oscillator) connected to XI.
- The CONFIG[2:0] strapping pins (pins 18, 29, 28) set to 000 (default setting).

3.2.1 MII SIGNAL DEFINITION

Table 3-1 describes the MII signals. Refer to Clause 22 of the IEEE 802.3 Specification for detailed information.

MII Signal Name	Direction with Respect to PHY, KSZ8051MNL Signal	Direction with Respect to MAC	Description
тхс	Output	Input	Transmit Clock (2.5 MHz for 10 Mbps; 25 MHz for 100 Mbps)
TXEN	Input	Output	Transmit Enable
TXD[3:0]	Input	Output	Transmit Data[3:0]
RXC	Output	Input	Receive Clock (2.5 MHz for 10 Mbps; 25 MHz for 100 Mbps)
RXDV	Output	Input	Receive Data Valid
RXD[3:0]	Output	Input	Receive Data[3:0]
RXER	Output	Input or not required	Receive Error
CRS	Output	Input	Carrier Sense
COL	Output	Input	Collision Detection

TABLE 3-1: MII SIGNAL DEFINITION

3.2.1.1 Transmit Clock (TXC)

TXC is sourced by the PHY. It is a continuous clock that provides the timing reference for TXEN, TXD[3:0], and TXER. TXC is 2.5 MHz for 10 Mbps operation and 25 MHz for 100 Mbps operation.

3.2.1.2 Transmit Enable (TXEN)

TXEN indicates that the MAC is presenting nibbles on TXD[3:0] for transmission. It is asserted synchronously with the first nibble of the preamble and remains asserted while all nibbles to be transmitted are presented on the MII. It is negated before the first TXC following the final nibble of a frame.

TXEN transitions synchronously with respect to TXC.

3.2.1.3 Transmit Data[3:0] (TXD[3:0])

TXD[3:0] transitions synchronously with respect to TXC. When TXEN is asserted, TXD[3:0] are accepted by the PHY for transmission. TXD[3:0] is 00 to indicate idle when TXEN is de-asserted. Values other than 00 on TXD[3:0] while TXEN is de-asserted are ignored by the PHY.

3.2.1.4 Receive Clock (RXC)

RXC provides the timing reference for RXDV, RXD[3:0], and RXER.

In 10 Mbps mode, RXC is recovered from the line while the carrier is active. When the line is idle or the link is down, RXC is derived from the PHY's reference clock.

In 100 Mbps mode, RXC is continuously recovered from the line. If the link is down, RXC is derived from the PHY's reference clock.

RXC is 2.5 MHz for 10 Mbps operation and 25 MHz for 100 Mbps operation.

3.2.1.5 Receive Data Valid (RXDV)

RXDV is driven by the PHY to indicate that the PHY is presenting recovered and decoded nibbles on RXD[3:0].

In 10 Mbps mode, RXDV is asserted with the first nibble of the start-of-frame delimiter (SFD), 5D, and remains asserted until the end of the frame.

In 100 Mbps mode, RXDV is asserted from the first nibble of the preamble to the last nibble of the frame.

RXDV transitions synchronously with respect to RXC.

3.2.1.6 Receive Data[3:0] (RXD[3:0])

RXD[3:0] transitions synchronously with respect to RXC. For each clock period in which RXDV is asserted, RXD[3:0] transfers a nibble of recovered data from the PHY.

3.2.1.7 Receive Error (RXER)

RXER is asserted for one or more RXC periods to indicate that a symbol error (for example, a coding error that a PHY can detect that may otherwise be undetectable by the MAC sub-layer) was detected somewhere in the frame being transferred from the PHY.

RXER transitions synchronously with respect to RXC. While RXDV is de-asserted, RXER has no effect on the MAC.

3.2.1.8 Carrier Sense (CRS)

CRS is asserted and de-asserted as follows:

- In 10 Mbps mode, CRS assertion is based on the reception of valid preambles. CRS de-assertion is based on the reception of an end-of-frame (EOF) marker.
- In 100 Mbps mode, CRS is asserted when a start-of-stream delimiter or /J/K symbol pair is detected. CRS is deasserted when an end-of-stream delimiter or /T/R symbol pair is detected. Additionally, the PMA layer de-asserts CRS if IDLE symbols are received without /T/R.

3.2.1.9 Collision Detection (COL)

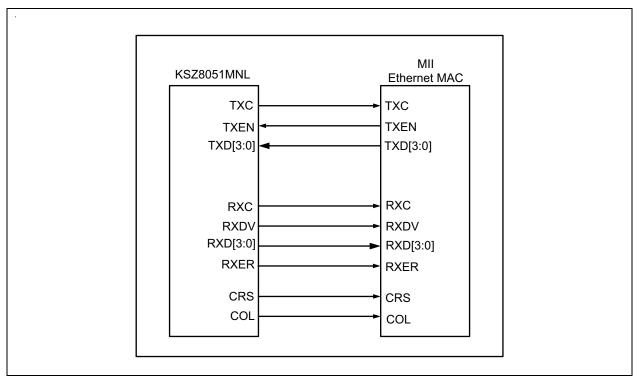
COL is asserted in half-duplex mode whenever the transmitter and receiver are simultaneously active on the line. This informs the MAC that a collision has occurred during its transmission to the PHY.

COL transitions asynchronously with respect to TXC and RXC.

3.2.2 MII SIGNAL DIAGRAM

The KSZ8051MNL MII pin connections to the MAC are shown in Figure 3-2.

FIGURE 3-2: KSZ8051MNL MII INTERFACE



^{© 2018} Microchip Technology Inc.

3.3 RMII Data Interface (KSZ8051RNL Only)

The Reduced Media Independent Interface (RMII) specifies a low pin count Media Independent Interface (MII). It provides a common interface between physical layer and MAC layer devices, and has the following key characteristics:

- Pin count is 8 pins (3 pins for data transmission, 4 pins for data reception, and 1 pin for the 50 MHz reference clock).
- 10 Mbps and 100 Mbps data rates are supported at both half- and full-duplex.
- Data transmission and reception are independent and belong to separate signal groups.
- Transmit data and receive data are each 2 bits wide, a dibit.

3.3.1 RMII - 25 MHZ CLOCK MODE

The KSZ8051RNL is configured to RMII - 25 MHz clock mode after it is powered up or hardware reset with the following:

- A 25 MHz crystal connected to XI, XO (pins 9, 8), or an external 25 MHz clock source (oscillator) connected to XI.
- The CONFIG[2:0] strap-in pins (pins 18, 29, 28) set to 001.
- Register 1Fh, bit [7] is set to 0 (default value) to select 25 MHz clock mode.

3.3.2 RMII - 50 MHZ CLOCK MODE

The KSZ8051RNL is configured to RMII - 50 MHz clock mode after it is powered up or hardware reset with the following:

- An external 50 MHz clock source (oscillator) connected to XI (pin 9).
- The CONFIG[2:0] strap-in pins (pins 18, 29, 28) set to 001.
- Register 1Fh, bit [7] is set to 1 to select 50 MHz clock mode.

3.3.3 RMII SIGNAL DEFINITION

Table 3-2 describes the RMII signals. Refer to RMII Specification v1.2 for detailed information.

RMII Signal Name	Direction with Respect to PHY KSZ8051RNL Signal	Direction with Respect to MAC	Description
REF_CLK	Output (25 MHz clock mode)/ <no connect=""> (50 MHz clock mode)</no>	Input/Input or <no connect=""></no>	Synchronous 50 MHz reference clock for receive, transmit, and control interface
TXEN	Input	Output	Transmit Enable
TXD[1:0]	Input	Output	Transmit Data[1:0]
CRS_DV	Output	Input	Carrier Sense/Receive Data Valid
RXD[1:0]	Output	Input	Receive Data[1:0]
RXER	Output	Input or not required	Receive Error

TABLE 3-2: RMII SIGNAL DEFINITION

3.3.4 REFERENCE CLOCK (REF_CLK)

REF_CLK is a continuous 50 MHz clock that provides the timing reference for TXEN, TXD[1:0], CRS_DV, RXD[1:0] and RX_ER.

For 25 MHz clock mode, the KSZ8051RNL generates and outputs the 50 MHz RMII REF_CLK to the MAC at REF_CLK (pin 19).

For 50 MHz clock mode, the KSZ8051RNL takes in the 50 MHz RMII REF_CLK from the MAC or system board at XI (pin 9) and leaves the REF_CLK (pin 19) as a no connect.

3.3.5 TRANSMIT ENABLE (TXEN)

TXEN indicates that the MAC is presenting dibits on TXD[1:0] for transmission. It is asserted synchronously with the first dibit of the preamble and remains asserted while all dibits to be transmitted are presented on the RMII. It is negated before the first REF_CLK following the final dibit of a frame.

TXEN transitions synchronously with respect to REF_CLK.

3.3.6 TRANSMIT DATA[1:0] (TXD[1:0])

TXD[1:0] transitions synchronously with respect to REF_CLK. When TXEN is asserted, the PHY accepts TXD[1:0] for transmission.

TXD[1:0] is 00 to indicate idle when TXEN is de-asserted. The PHY ignores values other than 00 on TXD[1:0] while TXEN is de-asserted.

3.3.7 CARRIER SENSE/RECEIVE DATA VALID (CRS_DV)

The PHY asserts CRS_DV when the receive medium is non-idle. It is asserted asynchronously when a carrier is detected. This happens when squelch is passed in 10 Mbps mode, and when two non-contiguous 0s in 10 bits are detected in 100 Mbps mode. Loss of carrier results in the de-assertion of CRS_DV.

While carrier detection criteria are met, CRS_DV remains asserted continuously from the first recovered dibit of the frame through the final recovered dibit. It is negated before the first REF_CLK that follows the final dibit. The data on RXD[1:0] is considered valid after CRS_DV is asserted. However, because the assertion of CRS_DV is asynchronous relative to REF_CLK, the data on RXD[1:0] is 00 until receive signals are properly decoded.

3.3.8 RECEIVE DATA[1:0] (RXD[1:0])

RXD[1:0] transitions synchronously with respect to REF_CLK. For each clock period in which CRS_DV is asserted, RXD[1:0] transfers two bits of recovered data from the PHY.

RXD[1:0] is 00 to indicate idle when CRS_DV is de-asserted. The MAC ignores values other than 00 on RXD[1:0] while CRS_DV is de-asserted.

3.3.9 RECEIVE ERROR (RXER)

RXER is asserted for one or more REF_CLK periods to indicate that a symbol error (for example, a coding error that a PHY can detect that may otherwise be undetectable by the MAC sub-layer) was detected somewhere in the frame being transferred from the PHY.

RXER transitions synchronously with respect to REF_CLK. While CRS_DV is de-asserted, RXER has no effect on the MAC.

3.3.10 COLLISION DETECTION (COL)

The MAC regenerates the COL signal of the MII from TXEN and CRS_DV.

3.3.11 RMII SIGNAL DIAGRAM

The KSZ8051RNL RMII pin connections to the MAC for 25 MHz clock mode are shown in Figure 3-3. The connections for 50 MHz clock mode are shown in Figure 3-4.

FIGURE 3-3: KSZ8051RNL RMII INTERFACE (25 MHZ CLOCK MODE)

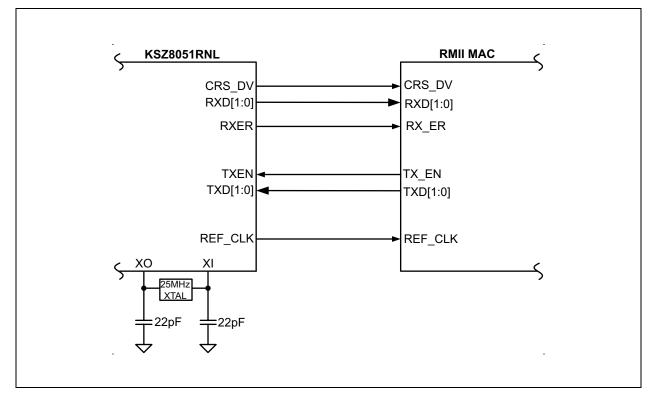
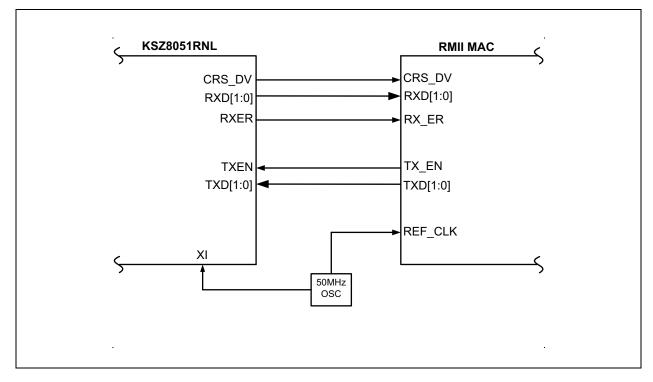


FIGURE 3-4: KSZ8051RNL RMII INTERFACE (50 MHZ CLOCK MODE)

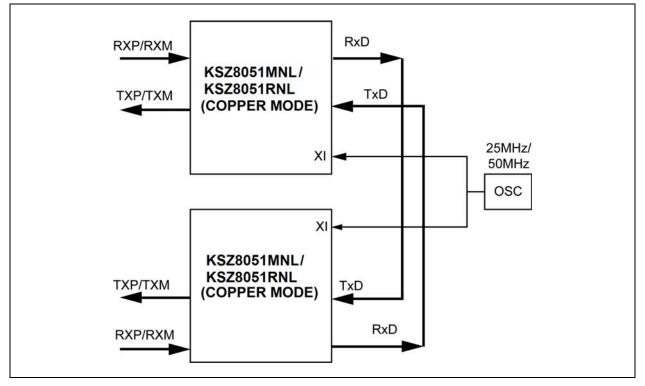


DS00002310B-page 22

3.4 Back-to-Back Mode – 100 Mbps Copper Repeater

Two KSZ8051MNL/RNL devices can be connected back-to-back to form a 100BASE-TX copper repeater.

FIGURE 3-5: KSZ8051MNL/RNL TO KSZ8051MNL/RNL BACK-TO-BACK COPPER REPEATER



3.4.1 MII BACK-TO-BACK MODE (KSZ8051MNL ONLY)

In MII back-to-back mode, a KSZ8051MNL interfaces with another KSZ8051MNL to provide a complete 100 Mbps copper repeater solution.

The KSZ8051MNL devices are configured to MII back-to-back mode after power-up or reset with the following:

- Strap-in pin CONFIG[2:0] (pins 18, 29, 28) set to 110.
- A common 25 MHz reference clock connected to XI (Pin 9) of both KSZ8051MNL devices.
- MII signals connected as shown in Table 3-3.

TABLE 3-3:MII SIGNAL CONNECTION FOR MII BACK-TO-BACK MODE (100BASE-TX COPPER
REPEATER)

KSZ805 ⁻	IMNL (100BASE-TX [Device 1]	Copper)	KSZ805 ⁷	1MNL (100BASE-TX [Device 2]	Copper)
Pin Name	Pin Number	Pin Type	Pin Name	Pin Number	Pin Type
RXDV	18	Output	TXEN	23	Input
RXD3	13	Output	TXD3	27	Input
RXD2	14	Output	TXD2	26	Input
RXD1	15	Output	TXD1	25	Input
RXD0	16	Output	TXD0	24	Input
TXEN	23	Input	RXDV	18	Output
TXD3	27	Input	RXD3	13	Output
TXD2	26	Input	RXD2	14	Output
TXD1	25	Input	RXD1	15	Output

© 2018 Microchip Technology Inc.

TABLE 3-3:MII SIGNAL CONNECTION FOR MII BACK-TO-BACK MODE (100BASE-TX COPPER
REPEATER) (CONTINUED)

KSZ8051MNL (100BASE-TX Copper) [Device 1]			KSZ8051MNL (100BASE-TX Copper) [Device 2]		
Pin Name	Pin Number Pin Type		Pin Name	Pin Number	Pin Type
TXD0	24	Input	RXD0	16	Output

3.4.2 RMII BACK-TO-BACK MODE (KSZ8051RNL ONLY)

In RMII back-to-back mode, a KSZ8051RNL interfaces with another KSZ8051RNL to provide a complete 100 Mbps copper repeater solution.

The KSZ8051RNL devices are configured to RMII back-to-back mode after power-up or reset with the following:

- Strap-in pin CONFIG[2:0] (pins 18, 29, 28) set to 101.
- A common 50 MHz reference clock connected to XI (pin 9) of both KSZ8051RNL devices.
- RMII signals connected as shown in Table 3-4.

TABLE 3-4:RMII SIGNAL CONNECTION FOR RMII BACK-TO-BACK MODE (100BASE-TX
COPPER REPEATER)

KSZ805 ²	1RNL (100BASE-TX [Device 1]	Copper)	KSZ805	1RNL (100BASE-TX [Device 2]	Copper)
Pin Name	Pin Number	Pin Type	Pin Name	Pin Number	Pin Type
CRSDV	18	Output	TXEN	23	Input
RXD1	15	Output	TXD1	25	Input
RXD0	16	Output	TXD0	24	Input
TXEN	23	Input	CRSDV	18	Output
TXD1	25	Input	RXD1	15	Output
TXD0	24	Input	RXD0	16	Output

3.5 MII Management (MIIM) Interface

The KSZ8051MNL/RNL supports the IEEE 802.3 MII management interface, also known as the Management Data Input/Output (MDIO) interface. This interface allows an upper-layer device, such as a MAC processor, to monitor and control the state of the KSZ8051MNL/RNL. An external device with MIIM capability is used to read the PHY status and/ or configure the PHY settings. More details about the MIIM interface can be found in Clause 22.2.4 of the IEEE 802.3 Specification.

The MIIM interface consists of the following:

- A physical connection that incorporates the clock line (MDC) and the data line (MDIO).
- A specific protocol that operates across the physical connection mentioned earlier, which allows the external controller to communicate with one or more PHY devices.
- A set of 16-bit MDIO registers. Registers [0:8] are standard registers, and their functions are defined in the IEEE 802.3 Specification. The additional registers are provided for expanded functionality. See the Register Descriptions section.

As the default, the KSZ8051MNL/RNL supports unique PHY addresses 1 to 7, and broadcast PHY address 0. The latter is defined in the IEEE 802.3 Specification, and can be used to read/write to a single KSZ8051MNL/RNL device, or write to multiple KSZ8051MNL/RNL devices simultaneously.

PHY address 0 can optionally be disabled as the broadcast address by either hardware pin strapping (B-CAST_OFF, pin 19) or software (Register 16h, bit [9]), and assigned as a unique PHY address.

The PHYAD[2:0] strap-in pins are used to assign a unique PHY address between 0 and 7 to each KSZ8051MNL/RNL device.

The MIIM interface can operates up to a maximum clock speed of 10 MHz MAC clock.

Table 3-5 shows the MII management frame format for the KSZ8051MNL/RNL.

DS00002310B-page 24

	Preamble	Start of Frame	Read/ Write OP Code	PHY Address Bits[4:0]	REG Address Bits[4:0]	ТА	Data Bits[15:0]	ldle
Read	32 1's	01	10	00AAA	RRRRR	Z0	DDDDDDD_DDDDDDD	Z
Write	32 1's	01	01	00AAA	RRRRR	10	DDDDDDD_DDDDDDD	Ζ

TABLE 3-5: MII MANAGEMENT FRAME FORMAT FOR THE KSZ8051MNL/RNL

3.6 Interrupt (INTRP)

INTRP (pin 21) is an optional interrupt signal that is used to inform the external controller that there has been a status update to the KSZ8051MNL/RNL PHY Register. Bits [15:8] of Register 1Bh are the interrupt control bits to enable and disable the conditions for asserting the INTRP signal. Bits [7:0] of Register 1Bh are the interrupt status bits to indicate which interrupt conditions have occurred. The interrupt status bits are cleared after reading Register 1Bh.

Bit [9] of Register 1Fh sets the interrupt level to active high or active low. The default is active low.

The MII management bus option gives the MAC processor complete access to the KSZ8051MNL/RNL control and status registers. Additionally, an interrupt pin eliminates the need for the processor to poll the PHY for status change.

3.7 HP Auto MDI/MDI-X

HP Auto MDI/MDI-X configuration eliminates the need to decide whether to use a straight cable or a crossover cable between the KSZ8051MNL/RNL and its link partner. This feature allows the KSZ8051MNL/RNL to use either type of cable to connect with a link partner that is in either MDI or MDI-X mode. The auto-sense function detects transmit and receive pairs from the link partner and assigns transmit and receive pairs to the KSZ8051MNL/RNL accordingly.

HP Auto MDI/MDI-X is enabled by default. It is disabled by writing a '1' to Register 1Fh, bit [13]. MDI and MDI-X mode is selected by Register 1Fh, bit [14] if HP Auto MDI/MDI-X is disabled.

An isolation transformer with symmetrical transmit and receive data paths is recommended to support Auto MDI/MDI-X.

Table 3-6 shows how the IEEE 802.3 Standard defines MDI and MDI-X.

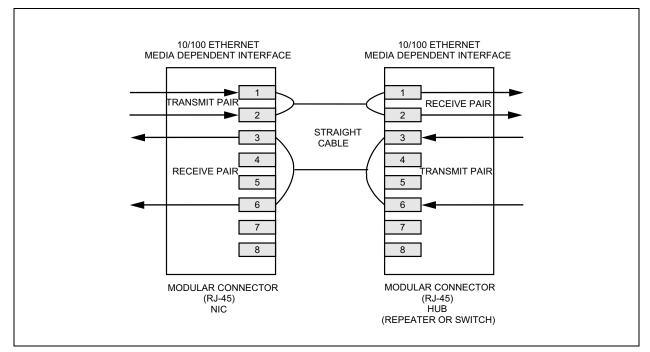
	MDI	ME	DI-X
RJ-45 Pin	Signal	RJ-45 Pin	Signal
1	TX+	1	RX+
2	TX–	2	RX–
3	RX+	3	TX+
6	RX–	6	TX–

TABLE 3-6: MDI/MDI-X PIN DESCRIPTION

3.7.1 STRAIGHT CABLE

A straight cable connects an MDI device to an MDI-X device, or an MDI-X device to an MDI device. Figure 3-6 shows a typical straight cable connection between a NIC card (MDI device) and a switch or hub (MDI-X device).

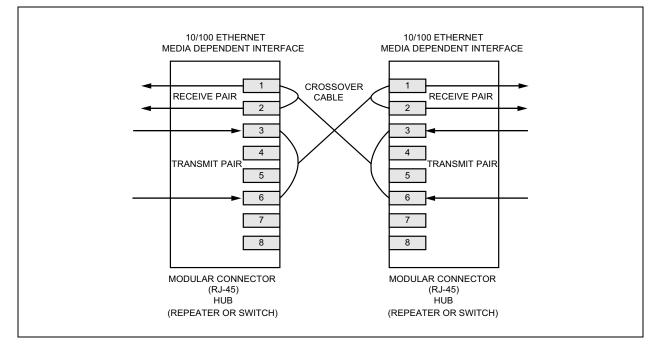
FIGURE 3-6: TYPICAL STRAIGHT CABLE CONNECTION



3.7.2 CROSSOVER CABLE

A crossover cable connects an MDI device to another MDI device, or an MDI-X device to another MDI-X device. Figure 3-7 shows a typical crossover cable connection between two switches or hubs (two MDI-X devices).





3.8 Loopback Mode

The KSZ8051MNL/RNL supports the following loopback operations to verify analog and/or digital data paths.

- Local (digital) loopback
- Remote (analog) loopback

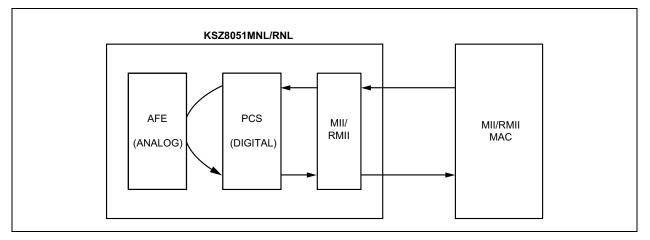
3.8.1 LOCAL (DIGITAL) LOOPBACK

This loopback mode checks the MII/RMII transmit and receive data paths between the KSZ8051MNL/RNL and the external MAC, and is supported for both speeds (10/100 Mbps) at full-duplex.

The loopback data path is shown in Figure 3-8.

- 1. The MII/RMII MAC transmits frames to the KSZ8051MNL/RNL.
- 2. Frames are wrapped around inside the KSZ8051MNL/RNL.
- 3. The KSZ8051MNL/RNL transmits frames back to the MII/RMII MAC.
- 4. Except the frames back to the RMII MAC, the transmit frames also go out from the copper port.

FIGURE 3-8: LOCAL (DIGITAL) LOOPBACK



The following programming action and register settings are used for local loopback mode:

For 10/100 Mbps loopback:

Set Register 0h,

- Bit [14] = 1 // Enable local loopback mode
- Bit [13] = 0/1 // Select 10 Mbps/100 Mbps speed
- Bit [12] = 0 // Disable auto-negotiation

Bit [8] = 1 // Select full-duplex mode

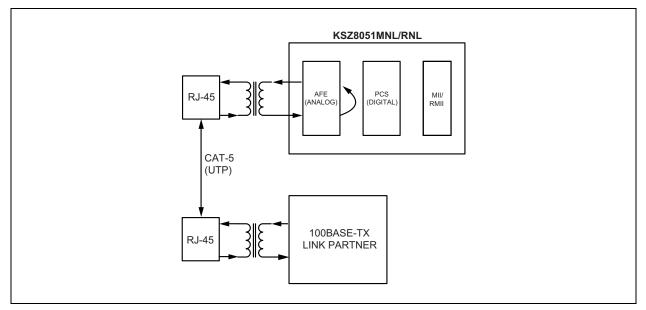
3.8.2 REMOTE (ANALOG) LOOPBACK

This loopback mode checks the line (differential pairs, transformer, RJ-45 connector, Ethernet cable) transmit and receive data paths between the KSZ8051MNL/RNL and its link partner, and is supported for 100BASE-TX full-duplex mode only.

The loopback data path is shown in Figure 3-9.

- 1. The Fast Ethernet (100BASE-TX) PHY link partner transmits frames to the KSZ8051MNL/RNL.
- 2. Frames are wrapped around inside the KSZ8051MNL/RNL.
- 3. The KSZ8051MNL/RNL transmits frames back to the Fast Ethernet (100BASE-TX) PHY link partner.

FIGURE 3-9: REMOTE (ANALOG) LOOPBACK



The following programming steps and register settings are used for remote loopback mode:

1. Set Register 0h,

Bits [13] = 1 // Select 100 Mbps speed

Bit [12] = 0 // Disable auto-negotiation

Bit [8] = 1 // Select full-duplex mode

Or just auto-negotiate and link up at 100BASE-TX full-duplex mode with the link partner.

2. Set Register 1Fh,

Bit [2] = 1 // Enable remote loopback mode

3.9 LinkMD[®] Cable Diagnostic

The LinkMD function uses time-domain reflectometry (TDR) to analyze the cabling plant for common cabling problems. These include open circuits, short circuits, and impedance mismatches.

LinkMD works by sending a pulse of known amplitude and duration down the MDI or MDI-X pair, then analyzing the shape of the reflected signal to determine the type of fault. The time duration for the reflected signal to return provides the approximate distance to the cabling fault. The LinkMD function processes this TDR information and presents it as a numerical value that can be translated to a cable distance.

LinkMD is initiated by accessing register 1Dh, the LinkMD Cable Diagnostic register, in conjunction with Register 1Fh, the PHY Control 2 Register. The latter register is used to disable Auto MDI/MDI-X and to select either MDI or MDI-X as the cable differential pair for testing.

3.9.1 USAGE

The following is a sample procedure for using LinkMD with Registers 1Dh and 1Fh:

- 1. Disable auto MDI/MDI-X by writing a '1' to Register 1Fh, bit [13].
- 2. Start cable diagnostic test by writing a '1' to Register 1Dh, bit [15]. This enable bit is self-clearing.
- 3. Wait (poll) for Register 1Dh, bit [15] to return a '0', and indicating cable diagnostic test is completed.
- 4. Read cable diagnostic test results in Register 1Dh, bits [14:13]. The results are as follows:
 - 00 = normal condition (valid test)
 - 01 = open condition detected in cable (valid test)
 - 10 = short condition detected in cable (valid test)

11 = cable diagnostic test failed (invalid test)

The '11' case, invalid test, occurs when the device is unable to shut down the link partner. In this instance, the test is not run because it would be impossible for the device to determine if the detected signal is a reflection of the signal generated or a signal from another source.

5. Get distance to fault by concatenating Register 1Dh, bits [8:0] and multiplying the result by a constant of 0.38. The distance to the cable fault can be determined by the following formula:

EQUATION 3-1:

 $D(Distance \text{ to cable fault in meters}) = 0.38 \times (Register 1Dh, bits[8:0])$

Concatenated value of Registers 1Dh bits [8:0] should be converted to decimal before multiplying by 0.38.

The constant (0.38) may be calibrated for different cabling conditions, including cables with a velocity of propagation that varies significantly from the norm.

3.10 NAND Tree Support

The KSZ8051MNL/RNL provides parametric NAND tree support for fault detection between chip I/Os and board. The NAND tree is a chain of nested NAND gates in which each KSZ8051MNL/RNL digital I/O (NAND tree input) pin is an input to one NAND gate along the chain. At the end of the chain, the CRS/CONFIG1 pin provides the output for the nested NAND gates.

The NAND tree test process includes:

- · Enabling NAND tree mode
- Pulling all NAND tree input pins high
- Driving each NAND tree input pin low, sequentially, according to the NAND tree pin order
- Checking the NAND tree output to make sure there is a toggle high-to-low or low-to-high for each NAND tree input
 driven low

Table 3-7 and Table 3-8 list the NAND tree pin orders for KSZ8051MNL and KSZ8051RNL, respectively.

Pin Number	Pin Name	NAND Tree Description
11	MDIO	Input
12	MDC	Input
13	RXD3	Input
14	RXD2	Input
15	RXD1	Input
16	RXD0	Input
18	RXDV	Input
19	RXC	Input
20	RXER	Input
21	INTRP	Input
22	TXC	Input
23	TXEN	Input
24	TXD0	Input
25	TXD1	Input
26	TXD2	Input
27	TXD3	Input

TABLE 3-7:NAND TREE TEST PIN ORDER FOR KSZ8051MNL

© 2018 Microchip Technology Inc.

Pin Number	Pin Name	NAND Tree Description
30	LED0	Input
31	LED1	Input
28	COL	Input
29	CRS	Output

TABLE 3-8:NAND TREE TEST PIN ORDER FOR KSZ8051RNL

Pin Number	Pin Name	NAND Tree Description
11	MDIO	Input
12	MDC	Input
13	PHYAD0	Input
14	PHYAD1	Input
15	RXD1	Input
16	RXD0	Input
18	CRS_DV	Input
19	REF_CLK	Input
20	RXER	Input
21	INTRP	Input
23	TXEN	Input
24	TXD0	Input
25	TXD1	Input
30	LED0	Input
31	LED1	Input
28	CONFIG0	Input
29	CONFIG1	Output

3.10.1 NAND TREE I/O TESTING

Use the following procedure to check for faults on the KSZ8051MNL/RNL digital I/O pin connections to the board:

- 1. Enable NAND tree mode using either a hardware strap-in pin (NAND_Tree#, Pin 21) or software (Register 16h, Bit [5]).
- 2. Use board logic to drive all KSZ8051MNL/RNL NAND tree input pins high.
- 3. Use board logic to drive each NAND tree input pin, in KSZ8051MNL/RNL NAND tree pin order, as follows:
 - a) Toggle the first pin (MDIO) from high to low, and verify that the CRS/CONFIG1 pin switches from high to low to indicate that the first pin is connected properly.
 - b) Leave the first pin (MDIO) low.
 - c) Toggle the second pin (MDC) from high to low, and verify that the CRS/CONFIG1 pin switches from low to high to indicate that the second pin is connected properly.
 - d) Leave the first pin (MDIO) and the second pin (MDC) low.
 - e) Toggle the third pin (RXD3/PHYAD0) from high to low, and verify that the CRS/CONFIG1 pin switches from high to low to indicate that the third pin is connected properly.
 - f) Continue with this sequence until all KSZ8051MNL/RNL NAND tree input pins have been toggled.

Each KSZ8051MNL/RNL NAND tree input pin must cause the CRS/CONFIG1 output pin to toggle high-to-low or lowto-high to indicate a good connection. If the CRS/CONFIG1 pin fails to toggle when the KSZ8051MNL/RNL input pin toggles from high to low, the input pin has a fault.

3.11 Power Management

The KSZ8051MNL/RNL incorporates a number of power-management modes and features that provide methods to consume less energy. These are discussed in the following sections.

3.11.1 POWER-SAVING MODE

Power-saving mode is used to reduce the transceiver power consumption when the cable is unplugged. It is enabled by writing a '1' to Register 1Fh, bit [10], and is in effect when auto-negotiation mode is enabled and the cable is disconnected (no link).

In this mode, the KSZ8051MNL/RNL shuts down all transceiver blocks, except for the transmitter, energy detect, and PLL circuits.

By default, power-saving mode is disabled after power-up.

3.11.2 ENERGY-DETECT POWER-DOWN MODE

Energy-detect power-down (EDPD) mode is used to further reduce transceiver power consumption when the cable is unplugged. It is enabled by writing a '0' to Register 18h, bit [11], and is in effect when auto-negotiation mode is enabled and the cable is disconnected (no link).

EDPD mode works with the PLL off (set by writing a '1' to Register 10h, bit [4] to automatically turn the PLL off in EDPD mode) to turn off all KSZ8051MNL/RNL transceiver blocks except the transmitter and energy-detect circuits.

Power can be reduced further by extending the time interval between transmissions of link pulses to check for the presence of a link partner. The periodic transmission of link pulses is needed to ensure the KSZ8051MNL/RNL and its link partner, when operating in the same low-power state and with Auto MDI/MDI-X disabled, can wake up when the cable is connected between them.

By default, energy-detect power-down mode is disabled after power-up.

3.11.3 POWER-DOWN MODE

Power-down mode is used to power down the KSZ8051MNL/RNL device when it is not in use after power-up. It is enabled by writing a '1' to Register 0h, bit [11].

In this mode, the KSZ8051MNL/RNL disables all internal functions except the MII management interface. The KSZ8051MNL/RNL exits (disables) power-down mode after Register 0h, bit [11] is set back to '0'.

3.11.4 SLOW-OSCILLATOR MODE

Slow-oscillator mode is used to disconnect the input reference crystal/clock on XI (pin 9) and select the on-chip slow oscillator when the KSZ8051MNL/RNL device is not in use after power-up. It is enabled by writing a '1' to Register 11h, bit [5].

Slow-oscillator mode works in conjunction with power-down mode to put the KSZ8051MNL/RNL device in the lowest power state, with all internal functions disabled except the MII management interface. To properly exit this mode and return to normal PHY operation, use the following programming sequence:

- 1. Disable slow-oscillator mode by writing a '0' to Register 11h, Bit [5].
- 2. Disable power-down mode by writing a '0' to Register 0h, Bit [11].
- 3. Initiate software reset by writing a '1' to Register 0h, Bit [15].

3.12 Reference Circuit for Power and Ground Connections

The KSZ8051MNL/RNL is a single 3.3V supply device with a built-in regulator to supply the 1.2V core. The power and ground connections are shown in Figure 3-10 and Table 3-9 for $3.3V V_{DDIO}$.

FIGURE 3-10: KSZ8051MNL/RNL POWER AND GROUND CONNECTIONS

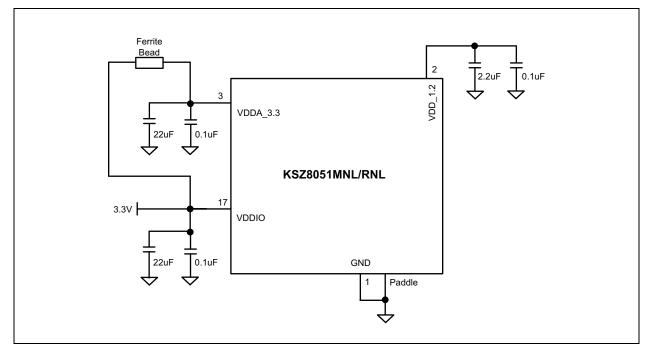


TABLE 3-9: KSZ8051MNL/RNL POWER PIN DESCRIPTION

Power Pin	Pin Number	Description
VDD_1.2	2	Decouple with 2.2 μ F and 0.1 μ F capacitors to ground.
VDDA_3.3	3	Connect to board's 3.3V supply through a ferrite bead. Decouple with 22 μ F and 0.1 μ F capacitors to ground.
VDDIO	17	Connect to board's 3.3V supply for 3.3V V _{DDIO} . Decouple with 22 μF and 0.1 μF capacitors to ground.

3.13 Typical Current/Power Consumption

Table 3-10, Table 3-11, and Table 3-12 show typical values for current consumption by the transceiver (VDDA_3.3) and digital I/O (VDDIO) power pins, and typical values for power consumption by the KSZ8051MNL/RNL device for the indicated nominal operating voltages. These current and power consumption values include the transmit driver current and on-chip regulator current for the 1.2V core.

TABLE 3-10:	TYPICAL CURRENT/POWER CONSUMPTION (VDDA_3.3 = 3.3V, VDDIO = 3.3V)	

	•	_ /	,
Condition	3.3V Transceiver (VDDA_3.3)	3.3V Digital I/Os (VDDIO)	Total Chip Power
100BASE-TX Link-up (no traffic)	34 mA	12 mA	152 mW
100BASE-TX Full-duplex @ 100% utilization	34 mA	13 mA	155 mW
10BASE-T Link-up (no traffic)	14 mA	11 mA	82.5 mW
10BASE-T Full-duplex @ 100% utilization	30 mA	11 mA	135 mW
Power-saving mode (Reg. 1Fh, Bit [10] = 1)	14 mA	10 mA	79.2 mW
EDPD mode (Reg. 18h, Bit [11] = 0)	10 mA	10 mA	66 mW
EDPD mode (Reg. 18h, Bit [11] = 0) and PLL off (Reg. 10h, Bit [4] = 1)	3.77 mA	1.54 mA	17.5 mW
Software power-down mode (Reg. 0h, Bit [11] =1)	2.59 mA	1.51 mA	13.5 mW

TABLE 3-10 :	TYPICAL CURRENT/POWER CONSUMPTION (VDDA_3.3 = 3.3V, VDDIO = 3.3V)
---------------------	-------------------------------------------------------------------

Condition	3.3V Transceiver (VDDA_3.3)	3.3V Digital I/Os (VDDIO)	Total Chip Power
Software power-down mode (Reg. 0h, Bit [11] =1) and slow-oscillator mode (Reg. 11h, Bit [5] =1)	1.36 mA	0.45 mA	5.97 mW

TABLE 3-11: TYPICAL CURRENT/POWER CONSUMPTION (VDDA_3.3 = 3.3V, VDDIO = 2.5V)

Condition	3.3V Transceiver (VDDA_3.3)	2.5V Digital I/Os (VDDIO)	Total Chip Power
100BASE-TX Link-up (no traffic)	34 mA	11 mA	140 mW
100BASE-TX Full-duplex @ 100% utilization	34 mA	12 mA	142 mW
10BASE-T Link-up (no traffic)	15 mA	10 mA	74.5 mW
10BASE-T Full-duplex @ 100% utilization	27 mA	10 mA	114 mW
Power-saving mode (Reg. 1Fh, Bit [10] = 1)	15 mA	10 mA	74.5 mW
EDPD mode (Reg. 18h, Bit [11] = 0)	11 mA	10 mA	61.3 mW
EDPD mode (Reg. 18h, Bit [11] = 0) and PLL off (Reg. 10h, Bit [4] = 1)	3.55 mA	1.35 mA	15.1 mW
Software power-down mode (Reg. 0h, Bit [11] =1)	2.29 mA	1.34 mA	10.9 mW
Software power-down mode (Reg. 0h, Bit [11] =1) and slow-oscillator mode (Reg. 11h, Bit [5] =1)	1.15 mA	0.29 mA	4.52 mW

TABLE 3-12: TYPICAL CURRENT/POWER CONSUMPTION (VDDA_3.3 = 3.3V, VDDIO = 1.8V)

Condition	3.3V Transceiver (VDDA_3.3)	1.8V Digital I/Os (VDDIO)	Total Chip Power
100BASE-TX Link-up (no traffic)	34 mA	11 mA	132 mW
100BASE-TX Full-duplex @ 100% utilization	34 mA	12 mA	134 mW
10BASE-T Link-up (no traffic)	15 mA	9 mA	65.7 mW
10BASE-T Full-duplex @ 100% utilization	27 mA	9 mA	105 mW
Power-saving mode (Reg. 1Fh, Bit [10] = 1)	15 mA	9 mA	65.7 mW
EDPD mode (Reg. 18h, Bit [11] = 0)	11 mA	9 mA	52.5 mW
EDPD mode (Reg. 18h, Bit [11] = 0) and PLL off (Reg. 10h, Bit [4] = 1)	4.05 mA	1.21 mA	15.5 mW
Software power-down mode (Reg. 0h, Bit [11] =1)	2.79 mA	1.21 mA	11.4 mW
Software power-down mode (Reg. 0h, Bit [11] =1) and slow-oscillator mode (Reg. 11h, Bit [5] =1)	1.65 mA	0.19 mA	5.79 mW

4.0 **REGISTER DESCRIPTIONS**

4.1 Register Map

TABLE 4-1: REGISTERS SUPPORTED BY KSZ8051MNL/RNL

Register Number (hex)	Description
0h	Basic Control
1h	Basic Status
2h	PHY Identifier 1
3h	PHY Identifier 2
4h	Auto-Negotiation Advertisement
5h	Auto-Negotiation Link Partner Ability
6h	Auto-Negotiation Expansion
7h	Auto-Negotiation Next Page
8h	Auto-Negotiation Link Partner Next Page Ability
9h	Reserved
10h	Digital Reserved Control
11h	AFE Control 1
12h - 14h	Reserved
15h	RXER Counter
16h	Operation Mode Strap Override
17h	Operation Mode Strap Status
18h	Expanded Control
19h - 1Ah	Reserved
1Bh	Interrupt Control/Status
1Ch	Reserved
1Dh	LinkMD Control/Status
1Eh	PHY Control 1
1Fh	PHY Control 2

4.2 Register Descriptions

Address	Name	Description	Mode Note 4-1	Default
Register 0h	- Basic Contro	bl		
0.15	Reset	1 = Software reset 0 = Normal operation This bit is self-cleared after a '1' is written to it.	RW/SC	0
0.14	Loopback	1 = Loopback mode 0 = Normal operation	RW	0
0.13	Speed Select	1 = 100 Mbps 0 = 10 Mbps This bit is ignored if auto-negotiation is enabled (Register 0.12 = 1).	RW	Set by the SPEED strap-in pin. See the Strap-In Options - KSZ8051MNL section for details.
0.12	Auto-Negoti- ation Enable	1 = Enable auto-negotiation process 0 = Disable auto-negotiation process If enabled, the auto-negotiation result overrides the settings in Registers 0.13 and 0.8.	RW	Set by the NWAYEN strap-in pin. See the Strap-In Options - KSZ8051MNL section for details.
0.11	Power-Down	1 = Power-down mode 0 = Normal operation If software reset (Register 0.15) is used to exit power-down mode (Register 0.11 = 1), two soft- ware reset writes (Register 0.15 = 1) are required. The first write clears power-down mode; the sec- ond write resets the chip and re-latches the pin strapping pin values.	RW	0
0.10	Isolate	1 = Electrical isolation of PHY from MII/RMII 0 = Normal operation	RW	Set by the ISO strap- in pin. See the Strap-In Options - KSZ8051MNL section for details.
0.9	Restart Auto- Negotiation	 1 = Restart auto-negotiation process 0 = Normal operation. This bit is self-cleared after a '1' is written to it. 	RW/SC	0
0.8	Duplex Mode	1 = Full-duplex 0 = Half-duplex	RW	The inverse of the DUPLEX strap-in pin value. See the Strap-In Options - KSZ8051MNL section for details.
0.7	Collision Test	1 = Enable COL test 0 = Disable COL test	RW	0
0.6:0	Reserved	Reserved	RO	000_0000
Register 1h	- Basic Status	·		•
1.15	100BASE-T4	1 = T4 capable 0 = Not T4 capable	RO	0
1.14	100BASE-TX Full-Duplex	1 = Capable of 100 Mbps full-duplex 0 = Not capable of 100 Mbps full-duplex	RO	1

TABLE 4-2:	REGISTER	DESCRIP	TIONS
------------	----------	---------	-------

© 2018 Microchip Technology Inc.

TABLE 4-2: Address	Name	R DESCRIPTIONS (CONTINUED) Description	Mode Note 4-1	Default
1.13	100BASE-TX		RO	1
1.10	Half-Duplex	0 = Not capable of 100 Mbps half-duplex		·
1.12	10BASE-T Full-Duplex	1 = Capable of 10 Mbps full-duplex 0 = Not capable of 10 Mbps full-duplex	RO	1
1.11	10BASE-T Half-Duplex	1 = Capable of 10 Mbps half-duplex 0 = Not capable of 10 Mbps half-duplex	RO	1
1.10:7	Reserved	Reserved	RO	000_0
1.6	No Preamble	1 = Preamble suppression 0 = Normal preamble	RO	1
1.5	Auto-Negoti- ation Com- plete	1 = Auto-negotiation process completed 0 = Auto-negotiation process not completed	RO	0
1.4	Remote Fault	1 = Remote fault 0 = No remote fault	RO/LH	0
1.3	Auto-Negoti- ation Ability	1 = Can perform auto-negotiation0 = Cannot perform auto-negotiation	RO	1
1.2	Link Status	1 = Link is up 0 = Link is down	RO/LL	0
1.1	Jabber Detect	1 = Jabber detected 0 = Jabber not detected (default is low)	RO/LH	0
1.0	Extended Capability	1 = Supports extended capability registers	RO	1
Register 2h	- PHY Identifie	r 1		
2.15:0	PHY ID Number	Assigned to the 3rd through 18th bits of the Organi- zationally Unique Identifier (OUI). KENDIN Com- munication's OUI is 0010A1 (hex).	RO	0022h
Register 3h	- PHY Identifie	r 2		
3.15:10	PHY ID Num- ber	Assigned to the 19th through 24th bits of the Orga- nizationally Unique Identifier (OUI). KENDIN Com- munication's OUI is 0010A1 (hex).	RO	0001_01
3.9:4	Model Num- ber	Six-bit manufacturer's model number	RO	01_0110
3.3:0	Revision Number	Four-bit manufacturer's revision number	RO	Indicates silicon revision.
Register 4h	- Auto-Negotia	tion Advertisement		
4.15	Next Page	1 = Next page capable 0 = No next page capability	RW	0
4.14	Reserved	Reserved	RO	0
4.13	Remote Fault	1 = Remote fault supported 0 = No remote fault	RW	0
4.12	Reserved	Reserved	RO	0
4.11:10	Pause	[00] = No pause [10] = Asymmetric pause [01] = Symmetric pause [11] = Asymmetric and symmetric pause	RW	00
4.9	100BASE-T4	1 = T4 capable 0 = No T4 capability	RO	0

TABLE 4-2: REGISTER DESCRIPTIONS (CONTINUED)

Address	Name	Description	Mode Note 4-1	Default
4.8	100BASE-TX Full-Duplex	1 = 100 Mbps full-duplex capable 0 = No 100 Mbps full-duplex capability	RW	Set by the SPEED strap-in pin. See the Strap-In Options - KSZ8051MNL section for details.
4.7	100BASE-TX Half-Duplex	1 = 100 Mbps half-duplex capable 0 = No 100 Mbps half-duplex capability	RW	Set by the SPEED strap-in pin. See the Strap-In Options - KSZ8051MNL section for details.
4.6	10BASE-T Full-Duplex	1 = 10 Mbps full-duplex capable 0 = No 10 Mbps full-duplex capability	RW	1
4.5	10BASE-T Half-Duplex	1 = 10 Mbps half-duplex capable 0 = No 10 Mbps half-duplex capability	RW	1
4.4:0	Selector Field	[00001] = IEEE 802.3	RW	0_0001
Register 5h	- Auto-Negotia	tion Link Partner Ability		
5.15	Next Page	1 = Next page capable 0 = No next page capability	RO	0
5.14	Acknowledge	1 = Link code word received from partner0 = Link code word not yet received	RO	0
5.13	Remote Fault	1 = Remote fault detected 0 = No remote fault	RO	0
5.12	Reserved	Reserved	RO	0
5.11:10	Pause	[00] = No pause [10] = Asymmetric pause [01] = Symmetric pause [11] = Asymmetric and symmetric pause	RO	00
5.9	100BASE-T4	1 = T4 capable 0 = No T4 capability	RO	0
5.8	100BASE-TX Full-Duplex	1 = 100 Mbps full-duplex capable 0 = No 100 Mbps full-duplex capability	RO	0
5.7	100BASE-TX Half-Duplex	1 = 100 Mbps half-duplex capable 0 = No 100 Mbps half-duplex capability	RO	0
5.6	10BASE-T Full-Duplex	1 = 10 Mbps full-duplex capable 0 = No 10 Mbps full-duplex capability	RO	0
5.5	10BASE-T Half-Duplex	1 = 10 Mbps half-duplex capable 0 = No 10 Mbps half-duplex capability	RO	0
5.4:0	Selector Field	[00001] = 802.3 after AN completes.	RO	0_0000
Register 6h	- Auto-Negotia	tion Expansion	•	•
6.15:5	Reserved	Reserved	RO	0000_0000_000
6.4	Parallel Detection Fault	1 = Fault detected by parallel detection 0 = No fault detected by parallel detection	RO/LH	0
6.3	Link Partner Next Page Able	1 = Link partner has next page capability 0 = Link partner does not have next page capability	RO	0

TABLE 4-2:	REGISTER DESCRIPTIONS ((CONTINUED)
------------	-------------------------	-------------

© 2018 Microchip Technology Inc.

Mode Address Name Description Default Note 4-1 1 = Local device has next page capability Next Page 0 = Local device does not have next page capabil-6.2 RO 1 Able ity Page 1 = New page received 0 6.1 RO/LH Received 0 = New page not received yet Link Partner 1 = Link partner has auto-negotiation capability 6.0 Auto-Negoti-0 = Link partner does not have auto-negotiation RO 0 ation Able capability **Register 7h - Auto-Negotiation Next Page** 1 = Additional next pages will follow 7.15 Next Page RW 0 0 = Last page 7.14 Reserved Reserved RO 0 Message 1 = Message page 7.13 RW 1 Page 0 = Unformatted page 1 = Will comply with message Acknowl-7.12 RW 0 edge2 0 = Cannot comply with message 1 = Previous value of the transmitted link code 7.11 Toggle word equaled logic 1 RO 0 0 = Logic 0Message 7.10:0 RW 000 0000 0001 11-bit wide field to encode 2048 messages Field **Register 8h - Link Partner Next Page Ability** 1 = Additional next pages will follow 8.15 RO 0 Next Page 0 = Last page 1 = Successful receipt of link word RO 0 8.14 Acknowledge 0 = No successful receipt of link word Message 1 = Message page 8.13 RO 0 0 = Unformatted page Page 1 = Can act on the information Acknowl-0 8.12 RO edge2 0 = Cannot act on the information 1 = Previous value of transmitted link code word equal to logic 0 8.11 RO 0 Toggle 0 = Previous value of transmitted link code word equal to logic 1 Message 8.10:0 RO 000 0000 0000 11-bit wide field to encode 2048 messages Field Register 10h - Digital Reserved Control RW 0000 0000 000 10.15:5 Reserved Reserved 1 = Turn PLL off automatically in EDPD mode 10.4 PLL Off 0 = Keep PLL on in EDPD mode. RW 0 See also Register 18h, Bit [11] for EDPD mode 10.3:0 Reserved Reserved 0000 RW Register 11h – AFE Control 1 RW 11.15:6 Reserved Reserved 0000 0000 00

TABLE 4-2: REGISTER DESCRIPTIONS (CONTINUED)

Address	Name	Description	Mode Note 4-1	Default		
11.5	Slow-oscillator mode is used to disconnect the input reference crystal/clock on the XI pin and select the on-chip slow oscillator when the KSZ8051MNL/RNL device is not in use after power-up. Enable 1 = Enable 0 = Disable This bit automatically sets software power-down to the analog side when enabled.		RW	0		
11.4:0	Reserved	Reserved	RW	0_000		
Register 15	h – RXER Coui	nter				
15.15:0	RXER Counter	Receive error counter for symbol error frames	RO/SC	0000h		
Register 16	h – Operation I	Mode Strap Override				
16.15:11	Reserved	Reserved	RW	0000_0		
16.10	Reserved	Reserved	RO	0		
16.9	B- CAST_OFF Override	1 = Override strap-in for B-CAST_OFF If bit is '1', PHY Address 0 is non-broadcast.	RW	0		
16.8	Reserved	Reserved	RW	0		
16.7	MII B-to-B Override	1 = Override strap-in for MII back-to-back mode (also set bit 0 of this register to '1') This bit applies only to KSZ8051MNL.	RW	0		
16.6	RMII B-to-B Override	1 = Override strap-in for RMII back-to-back mode (also set bit 1 of this register to '1') This bit applies only to KSZ8051RNL.	RW	0		
16.5	NAND Tree Override	1 = Override strap-in for NAND tree mode	RW	0		
16.4:2	Reserved	Reserved	RW	0_00		
16.1	RMII Override	1 = Override strap-in for RMII mode This bit applies only to KSZ8051RNL.	RW	0		
16.0	MII Override	1 = Override strap-in for MII mode This bit applies only to KSZ8051MNL.	RW	1		
Register 17	h - Operation N	Node Strap Status				
17.15:13	PHYAD[2:0] Strap-In Sta- tus	[000] = Strap to PHY Address 0 [001] = Strap to PHY Address 1 [010] = Strap to PHY Address 2 [011] = Strap to PHY Address 3 [100] = Strap to PHY Address 4 [101] = Strap to PHY Address 5 [110] = Strap to PHY Address 6 [111] = Strap to PHY Address 7	RO	_		
17.12:10	Reserved	Reserved	RO	_		
17.9	B- CAST_OFF Strap-In Status	1 = Strap to B-CAST_OFF If bit is '1', PHY Address 0 is non-broadcast.	RO			
17.8	Reserved	Reserved	RO			

TABLE 4-2:	REGISTER DESCRIPTIONS	(CONTINUED))
	REGIOTER DEGORIT HONO		

^{© 2018} Microchip Technology Inc.

Mode Address Name Description Default Note 4-1 MII B-to-B 1 = Strap to MII back-to-back mode RO 17.7 Strap-In This bit applies only to KSZ8051MNL. Status RMII B-to-B 1 = Strap to RMII back-to-back mode 17.6 RO Strap-In This bit applies only to KSZ8051RNL. Status NAND Tree 17.5 Strap-In 1 = Strap to NAND tree mode RO Status 17.4:2 Reserved RO Reserved RMII Strap-In 1 = Strap to RMII mode 17.1 RO Status This bit applies only to KSZ8051RNL. MII Strap-In 1 = Strap to MII mode 17.0 RO Status This bit applies only to KSZ8051MNL. **Register 18h - Expanded Control** 18.15:12 Reserved Reserved RW 0000 Energy-detect power-down mode EDPD 1 = Disable 18.11 RW 1 Disabled 0 = Enable See also Register 10h, Bit [4] for PLL off. 1 = MII output is random latency 0 = MII output is fixed latency 100BASE-TX For both settings, all bytes of received preamble 18.10 RW 0 Latency are passed to the MII output. This bit applies only to the KSZ8051MNL. 18.9:7 Reserved RW 00 0 Reserved 1 = Restore received preamble to MII output 10BASE-T 0 = Remove all seven bytes of preamble before 18.6 Preamble RW 0 sending frame (starting with SFD) to MII output Restore This bit applies only to the KSZ8051MNL 18.5:0 Reserved RW 00 0001 Reserved Register 1Bh - Interrupt Control/Status Jabber Inter-1 = Enable jabber interrupt 0 1B.15 RW rupt Enable 0 = Disable jabber interrupt Receive 1 = Enable receive error interrupt 1B.14 Error Inter-RW 0 0 = Disable receive error interrupt rupt Enable Page Received 1 = Enable page received interrupt 1B.13 RW 0 Interrupt 0 = Disable page received interrupt Enable Parallel Detect Fault 1 = Enable parallel detect fault interrupt 1B.12 RW 0 Interrupt 0 = Disable parallel detect fault interrupt Enable Link Partner 1 = Enable link partner acknowledge interrupt Acknowl-1B.11 RW 0 edge Inter-0 = Disable link partner acknowledge interrupt rupt Enable

TABLE 4-2: REGISTER DESCRIPTIONS (CONTINUED)

TABLE 4-2: REGISTER DESCRIPTIONS (CONTINUED)								
Address	Name	Description	Mode Note 4-1	Default				
1B.10	Link-Down Interrupt Enable	1= Enable link-down interrupt 0 = Disable link-down interrupt	RW	0				
1B.9	Remote Fault Interrupt Enable	1 = Enable remote fault interrupt 0 = Disable remote fault interrupt	RW	0				
1B.8	Link-Up Interrupt Enable	1 = Enable link-up interrupt 0 = Disable link-up interrupt	RW	0				
1B.7	Jabber Interrupt	1 = Jabber occurred 0 = Jabber did not occur	RO/SC	0				
1B.6	Receive Error Interrupt	1 = Receive error occurred 0 = Receive error did not occur	RO/SC	0				
1B.5	Page Receive Interrupt	1 = Page receive occurred 0 = Page receive did not occur	RO/SC	0				
1B.4	Parallel Detect Fault Interrupt	1 = Parallel detect fault occurred 0 = Parallel detect fault did not occur	RO/SC	0				
1B.3	Link Partner Acknowl- edge Inter- rupt	1 = Link partner acknowledge occurred0 = Link partner acknowledge did not occur	RO/SC	0				
1B.2	Link-Down Interrupt	1 = Link-down occurred 0 = Link-down did not occur	RO/SC	0				
1B.1	Remote Fault Interrupt	1 = Remote fault occurred0 = Remote fault did not occur	RO/SC	0				
1B.0	Link-Up Interrupt	1 = Link-up occurred 0 = Link-up did not occur	RO/SC	0				
Register 1D	h – LinkMD Co	ontrol/Status						
1D.15	Cable Diag- nostic Test Enable	 1 = Enable cable diagnostic test. After test has completed, this bit is self-cleared. 0 = Indicates cable diagnostic test (if enabled) has completed and the status information is valid for read. 	RW/SC	0				
1D.14:13	Cable Diag- nostic Test Result	 [00] = Normal condition [01] = Open condition has been detected in cable [10] = Short condition has been detected in cable [11] = Cable diagnostic test has failed 	RO	00				
1D.12	Short Cable Indicator	1 = Short cable (<10 meter) has been detected by LinkMD	RO	0				
1D.11:9	Reserved	Reserved RW 000		000				
1D.8:0	Cable Fault Counter	Distance to fault	RO	0_0000_0000				
Register 1E	h – PHY Contro	ol 1						
1E.15:10	Reserved	Reserved	RO	0000_00				
1E.9	Enable Pause (Flow Control)	1 = Flow control capable 0 = No flow control capability	RO	0				

TABLE 4-2: REGISTER DESCRIPTIONS (CONTINUED)

© 2018 Microchip Technology Inc.

Address	Name	Description	Mode Note 4-1	Default	
1E.8	Link Status	1 = Link is up 0 = Link is down	RO	0	
1E.7	Polarity Status	1 = Polarity is reversed 0 = Polarity is not reversed	RO	_	
1E.6	Reserved	Reserved	RO	0	
1E.5	MDI/MDI-X State	1 = MDI-X 0 = MDI	RO	_	
1E.4	Energy Detect	1 = Signal present on receive differential pair0 = No signal detected on receive differential pair	RO	0	
1E.3	PHY Isolate	1 = PHY in isolate mode 0 = PHY in normal operation	RW	0	
1E.2:0	Operation Mode Indication	[000] = Still in auto-negotiation [001] = 10BASE-T half-duplex [010] = 100BASE-TX half-duplex [011] = Reserved [100] = Reserved [101] = 10BASE-T full-duplex [110] = 100BASE-TX full-duplex [111] = Reserved	RO	000	
Register 1F	h – PHY Contr	ol 2			
1F.15	HP_MDIX	1 = HP Auto MDI/MDI-X mode 0 = Microchip Auto MDI/MDI-X mode	RW	1	
1F.14	MDI/MDI-X Select	When Auto MDI/MDI-X is disabled, 1 = MDI-X mode Transmit on RXP, RXM (Pins 5, 4) and Receive on TXP, TXM (Pins 7, 6) 0 = MDI mode Transmit on TXP, TXM (Pins 7, 6) and Receive on RXP, RXM (Pins 5, 4)	RW	0	
1F.13	Pair Swap Disable	1 = Disable Auto MDI/MDI-X 0 = Enable Auto MDI/MDI-X	RW	0	
1F.12	Reserved	Reserved	RW	0	
1F.11	Force Link	 1 = Force link pass 0 = Normal link operation This bit bypasses the control logic and allows the transmitter to send a pattern even if there is no link. 	RW	0	
1F.10	Power Saving	1 = Enable power saving 0 = Disable power saving	RW	0	
1F.9	Interrupt Level	1 = Interrupt pin active high 0 = Interrupt pin active low	RW	0	
1F.8	Enable Jabber	1 = Enable jabber counter0 = Disable jabber counter	RW	1	
1F.7	RMII Refer- ence Clock Select	 1 = RMII 50 MHz clock mode; clock input to XI (pin 9) is 50 MHz 0 = RMII 25 MHz clock mode; clock input to XI (pin 9) is 25 MHz This bit applies only to KSZ8051RNL. 	RW	0	
1F.6	Reserved	Reserved	RW	0	

TABLE 4-2: REGISTER DESCRIPTIONS (CONTINUED)

Address	dress Name Description		Mode Note 4-1	Default
1F.5:4	LED Mode	[00] = LED1: Speed LED0: Link/Activity [01] = LED1: Activity LED0: Link [10], [11] = Reserved	RW	00
1F.3	Disable Transmitter	1 = Disable transmitter 0 = Enable transmitter	RW	0
1F.2	Remote Loopback	1 = Remote (analog) loopback is enabled 0 = Normal mode	RW	0
1F.1	Enable SQE Test	1 = Enable SQE test 0 = Disable SQE test	RW	0
1F.0	Disable Data Scrambling	1 = Disable scrambler 0 = Enable scrambler	RW	0

TABLE 4-2: REGISTER DESCRIPTIONS (CONTINUED)

Note 4-1 RW = Read/Write; RO = Read Only; SC = Self-Cleared; LH = Latch High; LL = Latch Low.

^{© 2018} Microchip Technology Inc.

5.0 OPERATIONAL CHARACTERISTICS

5.1 Absolute Maximum Ratings*

–0.5V to +1.8V
–0.5V to +5.0V
–0.5V to +5.0V
–0.5V to +5.0V
+260°C
–55°C to +150°C

*Exceeding the absolute maximum rating may damage the device. Stresses greater than the absolute maximum rating may cause permanent damage to the device. Operation of the device at these or any other conditions above those specified in the operating sections of this specification is not implied. Maximum conditions for extended periods may affect reliability.

5.2 Operating Ratings**

Supply	Voltage
--------	---------

(V _{DDIO_3.3} , V _{DDA_3.3})	+3.135V to +3.465V
(V _{DDIO_2.5})	+2.375V to +2.625V
(V _{DDIO_1.8})	+1.710V to +1.890V
Ambient Temperature (T _A)	
(U Temperature Grade)	–40°C to +85°C
(V Temperature Grade)	–40°C to +105°C
Maximum Junction Temperature (T _J max.)	+125°C
Thermal Resistance (O _{JA})	+34°C/W
Thermal Resistance (O _{JC})	+6°C/W
**The device is not guaranteed to function outside its operating ratings.	

Note: Do not drive input signals without power supplied to the device.

6.0 ELECTRICAL CHARACTERISTICS

 $T_A = 25^{\circ}C$. Specification is for packaged product only.

Parameters	Symbol	Min.	Тур.	Max.	Units	Note
Supply Current (V _{DDIO} , V _{DI}	_{DA 3.3} = 3.3V	'), Note 6	-1	•	•	L
10BASE-T	I _{DD1_3.3V}	—	41	—	mA	Full-duplex traffic @ 100% utilization
100BASE-TX	I _{DD2_3.3V}	_	47	_	mA	Full-duplex traffic @ 100% utilization
EDPD Mode	I _{DD3_3.3V}	_	20	_	mA	Ethernet cable disconnected (Reg. 18h.11 = 0)
Power-Down Mode	I _{DD4_3.3V}		4	_	mA	Software power-down (Reg. 0h.11 = 1)
CMOS Level Inputs						
		2.0	_	_	V	V _{DDIO} = 3.3V
Input High Voltage	V _{IH}	1.8	_	—	V	V _{DDIO} = 2.5V
		1.3	_	—	V	V _{DDIO} = 1.8V
				0.8	V	V _{DDIO} = 3.3V
Input Low Voltage	V _{IL}	_	—	0.7	V	V _{DDIO} = 2.5V
			_	0.5	V	V _{DDIO} = 1.8V
Input Current	I _{IN}	—		10	μA	$V_{IN} = GND \sim V_{DDIO}$
CMOS Level Outputs						
		2.4	_	—	V	V _{DDIO} = 3.3V
Output High Voltage	V _{OH}	2.0	_	—	V	V _{DDIO} = 2.5V
		1.5	—	—	V	V _{DDIO} = 1.8V
			_	0.4	V	V _{DDIO} = 3.3V
Output Low Voltage	V _{OL}		_	0.4	V	V _{DDIO} = 2.5V
		_	—	0.3	V	V _{DDIO} = 1.8V
Output Tri-State Leakage	I _{oz}		_	10	μA	_
LED Output						
Output Drive Current	I _{LED}	_	8	—	mA	Each LED pin (LED0, LED1)
All Pull-Up/Pull-Down Pins	(including	Strap-In	Pins)			
		30	45	73	kΩ	V _{DDIO} = 3.3V
Internal Pull-Up Resistance	pu	39	61	102	kΩ	V _{DDIO} = 2.5V
		48	99	178	kΩ	V _{DDIO} = 1.8V
laters of Dull Davis		26	43	79	kΩ	V _{DDIO} = 3.3V
Internal Pull-Down Resistance	pd	34	59	113	kΩ	V _{DDIO} = 2.5V
resistance		53	99	200	kΩ	V _{DDIO} = 1.8V
100BASE-TX Transmit (me	asured diffe	rentially	after 1:1	l transfo	rmer)	
Peak Differential Output Voltage	Vo	0.95	_	1.05	V	100Ω termination across differential output
Output Voltage Imbalance	V _{IMB}	_	_	2	%	100Ω termination across differential output
Rise/Fall Time	t _r /t _f	3		5	ns	—
Rise/Fall Time Imbalance		0		0.5	ns	
Duty Cycle Distortion	_			±0.25	ns	—
Overshoot	_	_		5	%	—
Output Jitter	_	_	0.7	_	ns	Peak-to-peak

TABLE 6-1: ELECTRICAL CHARACTERISTICS

 $\ensuremath{\textcircled{}^{\odot}}$ 2018 Microchip Technology Inc.

Parameters	Symbol	Min.	Тур.	Max.	Units	Note
10BASE-T Transmit (meas	ured differe	ntially af	ter 1:1 tr	ansform	er)	<u> </u>
Peak Differential Output Voltage	V _P	2.2	_	2.8	V	100Ω termination across differential output
Jitter Added	—	_	_	3.5	ns	Peak-to-peak
Rise/Fall Time	t _r /t _f		25	—	ns	_
10BASE-T Receive						
Squelch Threshold	V _{SQ}		400	—	mV	5 MHz square wave
Transmitter - Drive Setting						
Reference Voltage of I _{SET}	V _{SET}		0.65	—	V	R(I _{SET}) = 6.49 kΩ
REF_CLK Output						
50 Mhz RMII Clock Output Jitter	_	_	300	—	ps	Peak-to-peak (Applies only to KSZ8051RNL in RMII - 25 MHz Clock Mode)
100 Mbps Mode - Industria	I Applicatio	ns Paran	neters			
Clock Phase Delay – XI Input to MII TXC Output	_	15	20	25	ns	XI (25 MHz clock input) to MII TXC (25 MHz clock output) delay, refer- enced to rising edges of both clocks (Applies only to KSZ8051MNL in MII mode)
Link Loss Reaction (Indication) Time	tıır		4.4		μs	 Link loss detected at receive differential inputs to PHY signal indication time for each of the following: 1. For LED mode 00, Speed LED out put changes from low (100 Mbps) to high (10 Mbps, default state for link-down). 2. For LED mode 01, Link LED output changes from low (link-up) to high (link-down). 3. INTRP pin asserts for link-down status change.

TABLE 6-1: ELECTRICAL CHARACTERISTICS (CONTINUED)

Note 6-1 Current consumption is for the single 3.3V supply KSZ8051MNL/RNL device only, and includes the transmit driver current and the 1.2V supply voltage (V_{DD_1.2}) that are supplied by the KSZ8051MNL/ RNL.

7.0 TIMING DIAGRAMS

7.1 MII SQE Timing (10BASE-T)



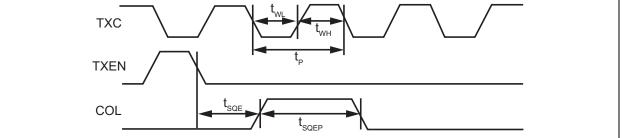


TABLE 7-1: MII SQE TIMING (10BASE-T) PARAMETERS

Parameter	Description	Min.	Тур.	Max.	Units
t _P	TXC period	_	400	-	ns
t _{WL}	TXC pulse width low	_	200		ns
t _{WH}	TXC pulse width high	_	200	-	ns
t _{SQE}	COL (SQE) delay after TXEN de-asserted	_	2.2	-	μs
t _{SQEP}	COL (SQE) pulse duration		1.0		μs

^{© 2018} Microchip Technology Inc.

7.2 MII Transmit Timing (10BASE-T)

FIGURE 7-2: MII TRANSMIT TIMING (10BASE-T)

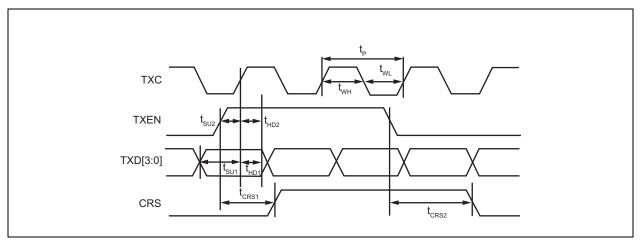


TABLE 7-2: MII TRANSMIT TIMING (10BASE-T) PARAMETERS

Parameter	Description	Min.	Тур.	Max.	Units
t _P	TXC period	_	400		ns
t _{WL}	TXC pulse width low	—	200	_	ns
t _{WH}	TXC pulse width high	—	200	_	ns
t _{SU1}	TXD[3:0] setup to rising edge of TXC	120	—	—	ns
t _{SU2}	TXEN setup to rising edge of TXC	120	_	_	ns
t _{HD1}	TXD[3:0] hold from rising edge of TXC	0	_	_	ns
t _{HD2}	TXEN hold from rising edge of TXC	0	—	—	ns
t _{CRS1}	TXEN high to CRS asserted latency	_	600		ns
t _{CRS2}	TXEN low to CRS de-asserted latency	_	1.0		μs

7.3 MII Receive Timing (10BASE-T)



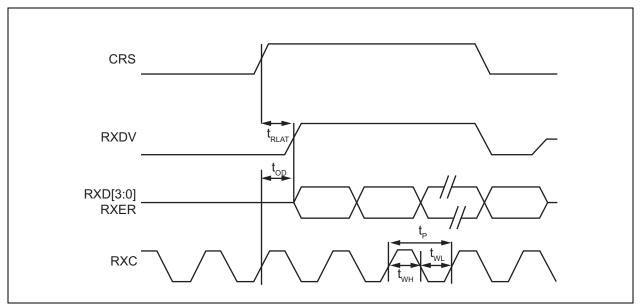


TABLE 7-3: MII RECEIVE TIMING (10BASE-T) PARAMETERS

Parameter	Description	Min.	Тур.	Max.	Units
t _P	RXC period	—	400	—	ns
t _{WL}	RXC pulse width low	—	200	—	ns
t _{WH}	RXC pulse width high	—	200	—	ns
t _{OD}	(RXDV, RXD[3:0], RXER) output delay from rising edge of RXC	_	205	_	ns
t _{RLAT}	CRS to (RXDV, RXD[3:0]) latency	—	7.2	—	μs

^{© 2018} Microchip Technology Inc.

7.4 MII Transmit Timing (100BASE-TX)

FIGURE 7-4: MII TRANSMIT TIMING (100BASE-TX)

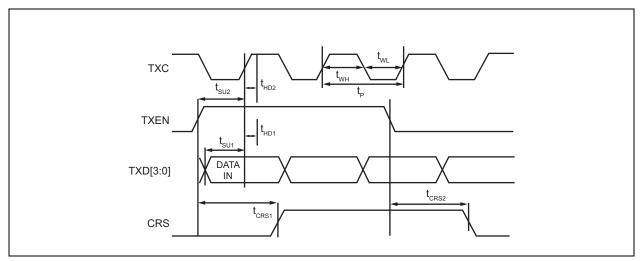


TABLE 7-4: MII TRANSMIT TIMING (100BASE-TX) PARAMETERS

Parameter	Description	Min.	Тур.	Max.	Units
t _P	TXC period	_	40		ns
t _{WL}	TXC pulse width low	—	20		ns
t _{WH}	TXC pulse width high	—	20	_	ns
t _{SU1}	TXD[3:0] setup to rising edge of TXC	10	—	_	ns
t _{SU2}	TXEN setup to rising edge of TXC	10	—		ns
t _{HD1}	TXD[3:0] hold from rising edge of TXC	0	—	_	ns
t _{HD2}	TXEN hold from rising edge of TXC	0	—		ns
t _{CRS1}	TXEN high to CRS asserted latency	—	72		ns
t _{CRS2}	TXEN low to CRS de-asserted latency	—	72		ns

7.5 MII Receive Timing (100BASE-TX)

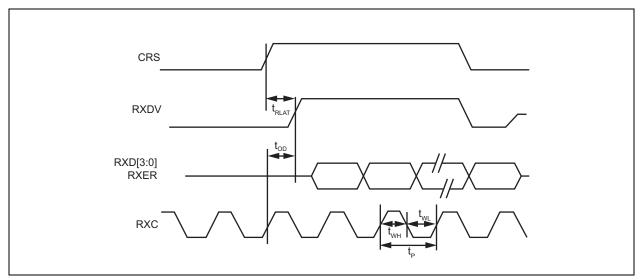


FIGURE 7-5: MII RECEIVE TIMING (100BASE-TX)

TABLE 7-5: MII RECEIVE TIMING (10BASE-T) PARAMETERS

Parameter	Description	Min.	Тур.	Max.	Units
t _P	RXC period	_	40		ns
t _{WL}	RXC pulse width low	_	20	_	ns
t _{WH}	RXC pulse width high	—	20		ns
t _{OD}	(RXDV, RXD[3:0], RXER) output delay from rising edge of RXC	—	25	—	ns
t _{RLAT}	CRS to (RXDV, RXD[3:0]) latency	_	170	_	ns

7.6 RMII Timing

FIGURE 7-6: RMII TIMING - DATA RECEIVED FROM RMII

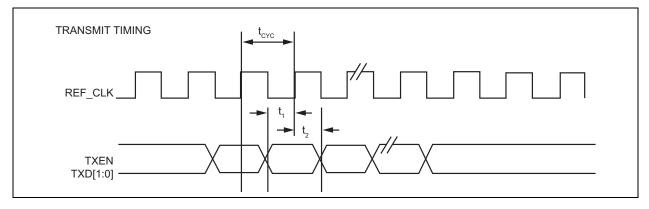


FIGURE 7-7: RMII TIMING - DATA INPUT TO RMII

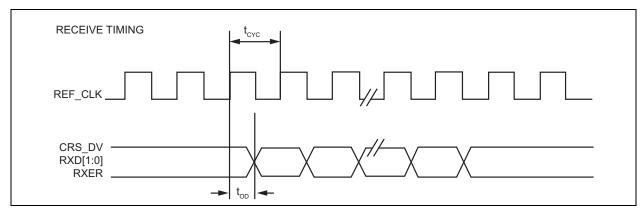


TABLE 7-6: RMII TIMING PARAMETERS - KSZ8051RNL (Note 7-1)

Timing Parameter	Description	Min.	Тур.	Max.	Units
t _{CYC}	Clock cycle		20	_	ns
t ₁	Setup time	4	_	_	ns
t ₂	Hold time	2	—	—	ns
t _{OD}	Output delay	7	10	13	ns

Note 7-1 25 MHz input to XI pin, 50 MHz output from REF_CLK pin.

TABLE 7-7: RMII TIMING PARAMETERS - KSZ8051RNL (Note 7-1)

Description	Min.	Тур.	Max.	Units
Clock cycle	—	20	_	ns
Setup time	4	_	_	ns
Hold time	2		_	ns
Output delay	8	11	13	ns
-	Clock cycle Setup time Hold time	Clock cycle — Setup time 4 Hold time 2	Clock cycle—20Setup time4—Hold time2—	Clock cycle 20 Setup time 4 Hold time 2

Note 7-1 50 MHz input to XI pin.

7.7 Auto-Negotiation Timing

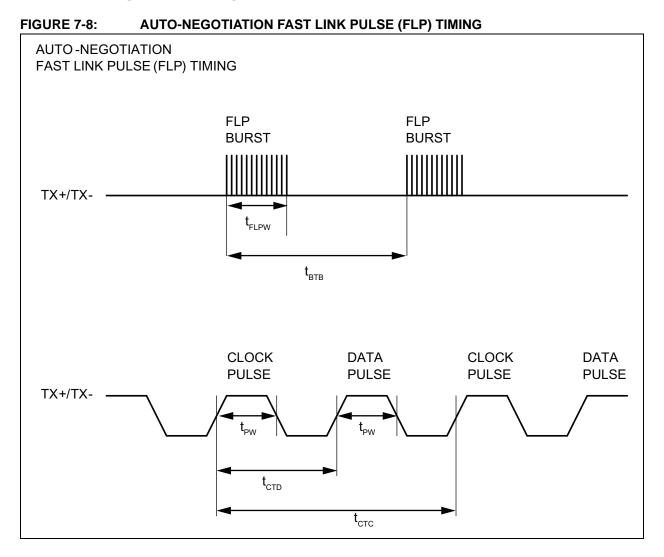


TABLE 7-8: AUTO-NEGOTIATION FAST LINK PULSE TIMING PARAMETERS

Parameter	Description	Min.	Тур.	Max.	Units
t _{BTB}	FLP burst to FLP burst	8	16	24	ms
t _{FLPW}	FLP burst width	—	2	—	ms
t _{PW}	Clock/Data pulse width	—	100	—	ns
t _{CTD}	Clock pulse to data pulse	55.5	64	69.5	μs
t _{CTC}	Clock pulse to clock pulse	111	128	139	μs
—	Number of clock/data pulses per FLP burst	17	_	33	

^{© 2018} Microchip Technology Inc.

7.8 MDC/MDIO Timing

FIGURE 7-9: MDC/MDIO TIMING

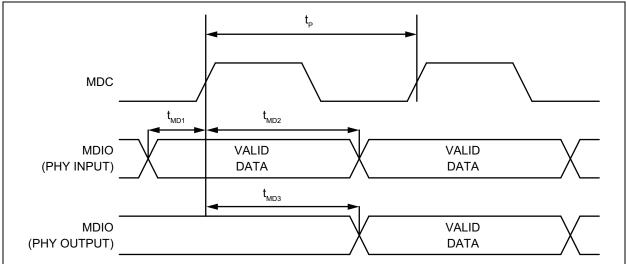


TABLE 7-9: MDC/MDIO TIMING PARAMETERS

Parameter	Description	Min.	Тур.	Max.	Units
t _P	MDC period	_	400	—	ns
t _{MD1}	MDIO (PHY input) setup to rising edge of MDC	10	—	—	ns
t _{MD2}	MDIO (PHY input) hold from rising edge of MDC	4	—	—	ns
t _{MD3}	MDIO (PHY output) delay from rising edge of MDC	5	—	—	ns

7.9 Power-Up/Reset Timing

The KSZ8051MNL/RNL reset timing requirement is summarized in Figure 7-10 and Table 7-10.



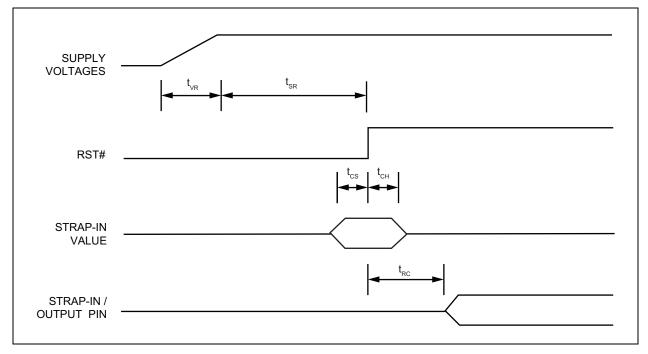


	TABLE 7-10:	POWER-UP/RESET TIMING PARAMETERS
--	-------------	-----------------------------------------

Parameter	Description	Min.	Тур.	Max.	Units
t _{VR}	Supply voltage (V _{DDIO} , V _{DDA_3.3}) rise time	300	—	_	μs
t _{SR}	Stable supply voltage (V_{DDIO} , $V_{DDA_{3.3}}$) to reset high	10	_	-	ms
t _{CS}	Configuration setup time	5	—	_	ns
t _{CH}	Configuration hold time	5	—	—	ns
t _{RC}	Reset to strap-in pin output	6	—	_	ns

The supply voltage (V_{DDIO} and $V_{DDA_3.3}$) power-up waveform should be monotonic. The 300 µs minimum rise time is from 10% to 90%.

For warm reset, the reset (RST#) pin should be asserted low for a minimum of 500 μ s. The strap-in pin values are read and updated at the de-assertion of reset.

After the de-assertion of reset, wait a minimum of 100 μ s before starting programming on the MIIM (MDC/MDIO) interface.

If the clock source to XI is something other than a crystal, the clock must be present for a minimum of 1 ms prior to the rising edge of RST#.

8.0 RESET CIRCUIT

Figure 8-1 shows a reset circuit recommended for powering up the KSZ8051MNL/RNL if reset is triggered by the power supply.

FIGURE 8-1: RECOMMENDED RESET CIRCUIT

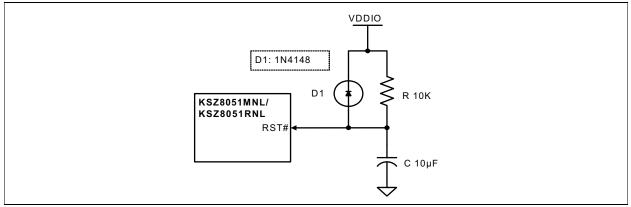
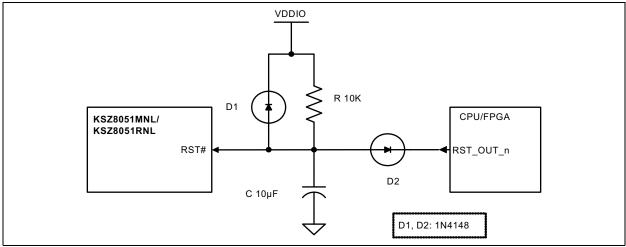


Figure 8-2 shows a reset circuit recommended for applications where reset is driven by another device (for example, the CPU or an FPGA). At power-on-reset, R, C, and D1 provide the necessary ramp rise time to reset the KSZ8051MNL/ RNL device. The RST_OUT_N from the CPU/FPGA provides the warm reset after power-up.

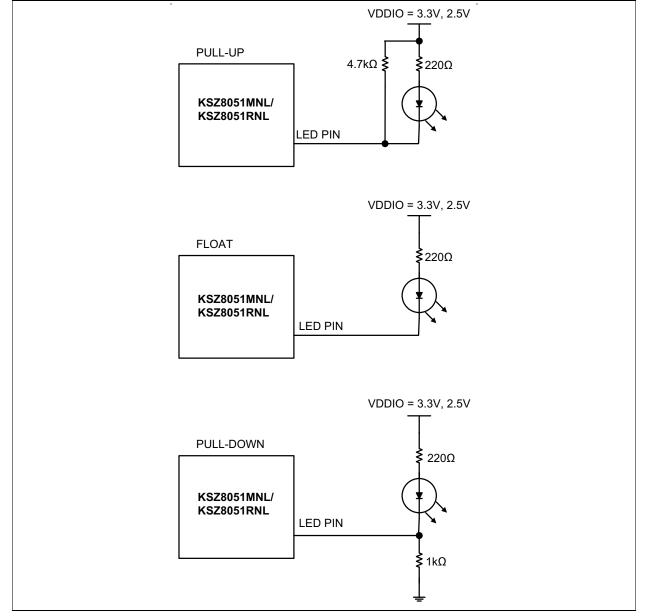
FIGURE 8-2: RECOMMENDED RESET CIRCUIT FOR CPU/FPGA RESET OUTPUT



9.0 REFERENCE CIRCUITS — LED STRAP-IN PINS

The pull-up, float, and pull-down reference circuits for the LED1/SPEED and LED0/NWAYEN strap-in pins are shown in Figure 9-1 for 3.3V and 2.5V VDDIO.





For 1.8V VDDIO, LED indication support is not recommended due to the low voltage. Without the LED indicator, the SPEED and NWAYEN strapping pins are functional with a 4.7 k Ω pull-up to 1.8V VDDIO or float for a value of '1', and with a 1.0 k Ω pull-down to ground for a value of '0'.

^{© 2018} Microchip Technology Inc.

10.0 REFERENCE CLOCK - CONNECTION AND SELECTION

A crystal or external clock source, such as an oscillator, is used to provide the reference clock for the KSZ8051MNL/ RNL. For the KSZ8051MNL in all operating modes and for the KSZ8051RNL in RMII – 25 MHz Clock Mode, the reference clock is 25 MHz. The reference clock connections to XI (pin 9) and XO (pin 8), and the reference clock selection criteria, are provided in Figure 10-1 and Table 10-1.

FIGURE 10-1: 25 MHZ CRYSTAL/OSCILLATOR REFERENCE CLOCK CONNECTION

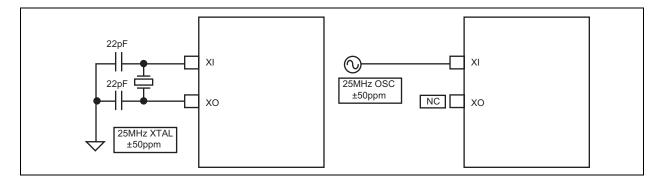


TABLE 10-1: 25 MHZ CRYSTAL/REFERENCE CLOCK SELECTION CRITERIA

Characteristics	Value
Frequency	25 MHz
Frequency Tolerance (max.)	±50 ppm

For the KSZ8051RNL in RMII - 50 MHz Clock Mode, the reference clock is 50 MHz. The reference clock connections to XI (Pin 9), and the reference clock selection criteria are provided in Figure 10-2 and Table 10-2.

FIGURE 10-2: 50 MHZ OSCILLATOR REFERENCE CLOCK CONNECTION

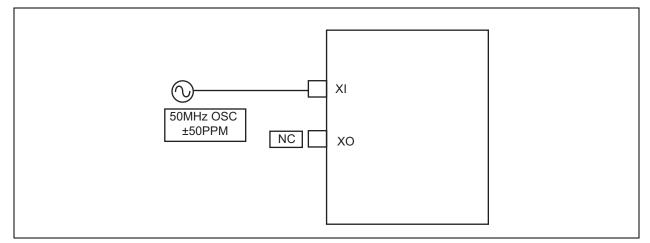


TABLE 10-2: 50 MHZ OSCILLATOR/REFERENCE CLOCK SELECTION CRITERIA

Characteristics	Value
Frequency	50 MHz
Frequency Tolerance (max.)	±50 ppm

11.0 MAGNETIC - CONNECTION AND SELECTION

A 1:1 isolation transformer is required at the line interface. Use one with integrated common-mode chokes for designs exceeding FCC requirements.

The KSZ8051MNL/RNL design incorporates voltage-mode transmit drivers and on-chip terminations.

With the voltage-mode implementation, the transmit drivers supply the common-mode voltages to the two differential pairs. Therefore, the two transformer center tap pins on the KSZ8051MNL/RNL side should not be connected to any power supply source on the board; instead, the center tap pins should be separated from one another and connected through separate 0.1 µF common-mode capacitors to ground. Separation is required because the common-mode voltage is different between transmitting and receiving differential pairs.

Figure 11-1 shows the typical magnetic interface circuit for the KSZ8051MNL/RNL.

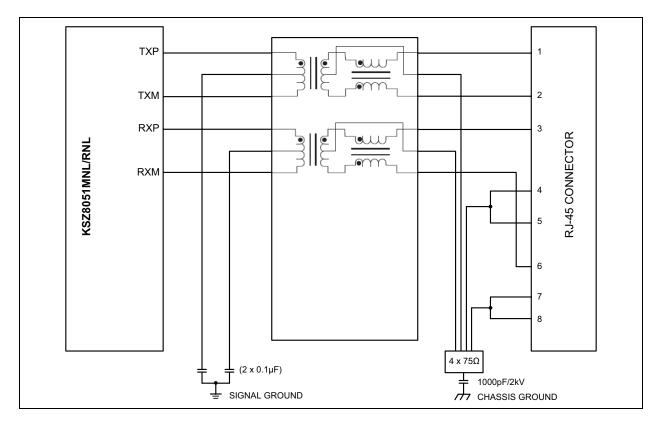


FIGURE 11-1: TYPICAL MAGNETIC INTERFACE CIRCUIT

Table 11-1 lists recommended magnetic characteristics.

TABLE 11-1: MAGNETICS SELECTION CRITERIA

Parameter	Value	Test Conditions
Turns Ratio	1 CT : 1 CT	—
Open-Circuit Inductance (min.)	350 µH	100 mV, 100 kHz, 8 mA
Insertion Loss (max.)	–1.1 dB	100 kHz to 100 MHz
HIPOT (min.)	1500 V _{RMS}	—

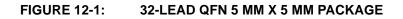
^{© 2018} Microchip Technology Inc.

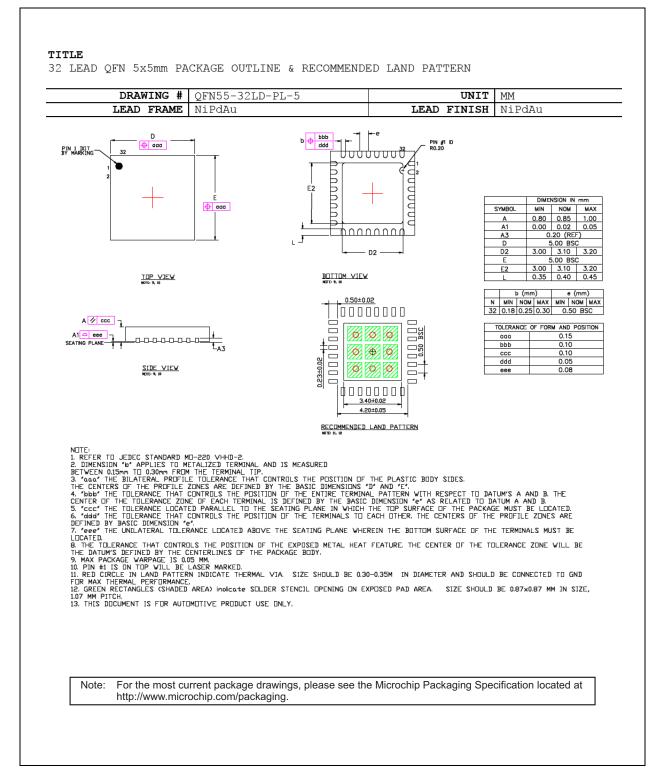
Table 11-2 is a list of compatible single-port magnetics with separated transformer center tap pins on the PHY chip side that can be used with the KSZ8051MNL/RNL.

Manufacturer	Part Number	Temperature Range	Magnetic + RJ-45
Bel Fuse	S558-5999-U7	0°C to 70°C	No
Bel Fuse	SI-46001-F	0°C to 70°C	Yes
Bel Fuse	SI-50170-F	0°C to 70°C	Yes
Delta	LF8505	0°C to 70°C	No
HALO	HFJ11-2450E	0°C to 70°C	Yes
HALO	TG110-E055N5	-40°C to 85°C	No
LANKom	LF-H41S-1	0°C to 70°C	No
Pulse	H1102	0°C to 70°C	No
Pulse	H1260	0°C to 70°C	No
Pulse	HX1188	–40°C to 85°C	No
Pulse	J00-0014	0°C to 70°C	Yes
Pulse	JX0011D21NL	-40°C to 85°C	Yes
TDK	TLA-6T718A	0°C to 70°C	Yes
Transpower	HB726	0°C to 70°C	No
Wurth/Midcom	000-7090-37R-LF1	–40°C to 85°C	No

TABLE 11-2: COMPATIBLE SINGLE-PORT 10/100 MAGNETICS

12.0 PACKAGE OUTLINE





© 2018 Microchip Technology Inc.

APPENDIX A: DATA SHEET REVISION HISTORY

TABLE A-1: REVISION HISTORY

Revision	Section/Figure/Entry	Correction
DS00002310A (11-15-16)	_	Converted Micrel data sheet KSZ8051MNL/RNL to Microchip DS00002310A. Minor text changes throughout. This document combines Micrel's auto- motive-qualified KSZ8051MNLU/RNLU and KSZ8051MNLV/RNLV data sheets. It also replaces the non-automotive KSZ8051MNL/RNL, which has been EoL.
	Table 3-3	Removed references to TXC and RXC pins.
	LinkMD® Cable Diagnostic	Added usage example.
DS00002310B (3-19-18)	Table 2-4	Corrected CONFIG[2:0] values to reflect the original data sheet.

THE MICROCHIP WEB SITE

Microchip provides online support via our WWW site at www.microchip.com. This web site is used as a means to make files and information easily available to customers. Accessible by using your favorite Internet browser, the web site contains the following information:

- **Product Support** Data sheets and errata, application notes and sample programs, design resources, user's guides and hardware support documents, latest software releases and archived software
- General Technical Support Frequently Asked Questions (FAQ), technical support requests, online discussion groups, Microchip consultant program member listing
- Business of Microchip Product selector and ordering guides, latest Microchip press releases, listing of seminars and events, listings of Microchip sales offices, distributors and factory representatives

CUSTOMER CHANGE NOTIFICATION SERVICE

Microchip's customer notification service helps keep customers current on Microchip products. Subscribers will receive e-mail notification whenever there are changes, updates, revisions or errata related to a specified product family or development tool of interest.

To register, access the Microchip web site at www.microchip.com. Under "Support", click on "Customer Change Notification" and follow the registration instructions.

CUSTOMER SUPPORT

Users of Microchip products can receive assistance through several channels:

- Distributor or Representative
- Local Sales Office
- Field Application Engineer (FAE)
- Technical Support

Customers should contact their distributor, representative or field application engineer (FAE) for support. Local sales offices are also available to help customers. A listing of sales offices and locations is included in the back of this document.

Technical support is available through the web site at: http://microchip.com/support

^{© 2018} Microchip Technology Inc.

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<sz8051 M = MII R = RMII N = 32-pin QFN</sz8051 	Automotive Grade 3 Temperature Tray b) KSZ8051MNLV MII Interface 32-pin QFN
R = RMII	MII Interface 32-pin QFN
N = 32 pin OEN	Single 3.3V Supply Automotive Grade 2 Temperature
ν – 52-μπ αι τν	Tray c) KSZ8051RNLUB-VAO (Note 1) RMII Interface
_ = Single 3.3V Supply	32-pin QFN Single 3.3V Supply Automotive Grade 3 Temperature Tray, Automotive Option
$J = -40^{\circ}C \text{ to } +85^{\circ}C \text{ (Automotive Grade 3)}$ $JB = -40^{\circ}C \text{ to } +85^{\circ}C \text{ (Automotive Grade 3)}$ $V = -40^{\circ}C \text{ to } +105^{\circ}C \text{ (Automotive Grade 2)}$	d) KSZ8051RNLU (Note 1) RMII Interface 32-pin QFN Single 3.3V Supply
olank = Tray TR = Tape & Reel	Automotive Grade 3 Temperature Tray e) KSZ8051MNLU-TR MII Interface
/AO = Automotive Option	32-pin QFN Single 3.3V Supply Automotive Grade 3 Temperature Tape & Reel
1RNLUB corrects an erratum in the KSZ8051RNLU (see #1 in the KSZ8051 Errata document). KSZ8051RNLUB is ended for all new designs and is a 100% functional and pin ent replacement for KSZ8051RNLU.	f) KSZ8051MNLV-TR MII Interface
	RMII Interface 32-pin QFN Single 3.3V Supply Automotive Grade 3 Temperature Tape & Reel, Automotive Option
	h) KSZ8051RNLU-TR (Note 1) RMII Interface 32-pin QFN Single 3.3V Supply Automotive Grade 3 Temperature Tape & Reel
	J = -40°C to +85°C (Automotive Grade 3) JB = -40°C to +85°C (Automotive Grade 3) / = -40°C to +105°C (Automotive Grade 2) blank = Tray TR = Tape & Reel /AO = Automotive Option 1RNLUB corrects an erratum in the KSZ8051RNLU (see #1 in the KSZ8051 Errata document). KSZ8051RNLUB is ended for all new designs and is a 100% functional and pin

Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as "unbreakable."

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip's code protection feature may be a violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

Information contained in this publication regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION, QUALITY, PERFORMANCE, MERCHANTABILITY OR FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights unless otherwise stated.

Trademarks

The Microchip name and logo, the Microchip logo, AnyRate, AVR, AVR logo, AVR Freaks, BeaconThings, BitCloud, CryptoMemory, CryptoRF, dsPIC, FlashFlex, flexPWR, Heldo, JukeBlox, KEELOQ, KEELOQ logo, Kleer, LANCheck, LINK MD, maXStylus, maXTouch, MediaLB, megaAVR, MOST, MOST logo, MPLAB, OptoLyzer, PIC, picoPower, PICSTART, PIC32 logo, Prochip Designer, QTouch, RightTouch, SAM-BA, SpyNIC, SST, SST Logo, SuperFlash, tinyAVR, UNI/O, and XMEGA are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

ClockWorks, The Embedded Control Solutions Company, EtherSynch, Hyper Speed Control, HyperLight Load, IntelliMOS, mTouch, Precision Edge, and Quiet-Wire are registered trademarks of Microchip Technology Incorporated in the U.S.A.

Adjacent Key Suppression, AKS, Analog-for-the-Digital Age, Any Capacitor, AnyIn, AnyOut, BodyCom, chipKIT, chipKIT logo, CodeGuard, CryptoAuthentication, CryptoCompanion, CryptoController, dsPICDEM, dsPICDEM.net, Dynamic Average Matching, DAM, ECAN, EtherGREEN, In-Circuit Serial Programming, ICSP, Inter-Chip Connectivity, JitterBlocker, KleerNet, KleerNet logo, Mindi, MiWi, motorBench, MPASM, MPF, MPLAB Certified logo, MPLIB, MPLINK, MultiTRAK, NetDetach, Omniscient Code Generation, PICDEM, PICDEM.net, PICkit, PICtail, PureSilicon, QMatrix, RightTouch logo, REAL ICE, Ripple Blocker, SAM-ICE, Serial Quad I/O, SMART-I.S., SQI, SuperSwitcher, SuperSwitcher II, Total Endurance, TSHARC, USBCheck, VariSense, ViewSpan, WiperLock, Wireless DNA, and ZENA are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

SQTP is a service mark of Microchip Technology Incorporated in the U.S.A.

Silicon Storage Technology is a registered trademark of Microchip Technology Inc. in other countries.

GestIC is a registered trademark of Microchip Technology Germany II GmbH & Co. KG, a subsidiary of Microchip Technology Inc., in other countries.

All other trademarks mentioned herein are property of their respective companies.

© 2018, Microchip Technology Incorporated, All Rights Reserved.

ISBN: 978-1-5224-2811-4

QUALITY MANAGEMENT SYSTEM CERTIFIED BY DNV = ISO/TS 16949=

Microchip received ISO/TS-16949:2009 certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona; Gresham, Oregon and design centers in California and India. The Company's quality system processes and procedures are for its PIC® MCUs and dsPIC® DSCs, KEELOQ® code hopping devices, Serial EEPROMs, microperipherals, nonvolatile memory and analog products. In addition, Microchip's quality system for the design and mulfacture of development systems is ISO 9001:2000 certified.

© 2018 Microchip Technology Inc.



Worldwide Sales and Service

AMERICAS

Corporate Office 2355 West Chandler Blvd. Chandler, AZ 85224-6199 Tel: 480-792-7200 Fax: 480-792-7277 Technical Support: http://www.microchip.com/ support

Web Address: www.microchip.com

Atlanta Duluth, GA Tel: 678-957-9614 Fax: 678-957-1455

Austin, TX Tel: 512-257-3370

Boston Westborough, MA Tel: 774-760-0087 Fax: 774-760-0088

Chicago Itasca, IL Tel: 630-285-0071 Fax: 630-285-0075

Dallas Addison, TX Tel: 972-818-7423 Fax: 972-818-2924

Detroit Novi, MI Tel: 248-848-4000

Houston, TX Tel: 281-894-5983

Indianapolis Noblesville, IN Tel: 317-773-8323 Fax: 317-773-5453 Tel: 317-536-2380

Los Angeles Mission Viejo, CA Tel: 949-462-9523 Fax: 949-462-9608 Tel: 951-273-7800

Raleigh, NC Tel: 919-844-7510

New York, NY Tel: 631-435-6000

San Jose, CA Tel: 408-735-9110 Tel: 408-436-4270

Canada - Toronto Tel: 905-695-1980 Fax: 905-695-2078

DS00002310B-page 66

ASIA/PACIFIC

Australia - Sydney Tel: 61-2-9868-6733

China - Beijing Tel: 86-10-8569-7000 China - Chengdu

Tel: 86-28-8665-5511 China - Chongqing Tel: 86-23-8980-9588

China - Dongguan Tel: 86-769-8702-9880

China - Guangzhou Tel: 86-20-8755-8029

China - Hangzhou Tel: 86-571-8792-8115

China - Hong Kong SAR Tel: 852-2943-5100

China - Nanjing Tel: 86-25-8473-2460

China - Qingdao Tel: 86-532-8502-7355

China - Shanghai Tel: 86-21-3326-8000

China - Shenyang Tel: 86-24-2334-2829

China - Shenzhen Tel: 86-755-8864-2200

China - Suzhou Tel: 86-186-6233-1526

China - Wuhan Tel: 86-27-5980-5300

China - Xian Tel: 86-29-8833-7252

China - Xiamen Tel: 86-592-2388138 China - Zhuhai

Tel: 86-756-3210040

ASIA/PACIFIC

India - Bangalore Tel: 91-80-3090-4444

India - New Delhi Tel: 91-11-4160-8631 India - Pune

Tel: 91-20-4121-0141 Japan - Osaka

Tel: 81-6-6152-7160

Japan - Tokyo Tel: 81-3-6880- 3770 Korea - Daegu

Tel: 82-53-744-4301

Korea - Seoul Tel: 82-2-554-7200

Malaysia - Kuala Lumpur Tel: 60-3-7651-7906

Malaysia - Penang Tel: 60-4-227-8870

Philippines - Manila Tel: 63-2-634-9065

Singapore Tel: 65-6334-8870

Taiwan - Hsin Chu Tel: 886-3-577-8366

Taiwan - Kaohsiung Tel: 886-7-213-7830

Taiwan - Taipei Tel: 886-2-2508-8600

Thailand - Bangkok Tel: 66-2-694-1351

Vietnam - Ho Chi Minh Tel: 84-28-5448-2100

Tel: 31-416-690399 Fax: 31-416-690340

EUROPE

Austria - Wels

Tel: 43-7242-2244-39

Tel: 45-4450-2828

Fax: 45-4485-2829

Tel: 358-9-4520-820

Tel: 33-1-69-53-63-20

Fax: 33-1-69-30-90-79

Germany - Garching

Tel: 49-2129-3766400

Germany - Heilbronn

Germany - Karlsruhe

Tel: 49-721-625370

Germany - Munich

Tel: 49-89-627-144-0

Fax: 49-89-627-144-44

Germany - Rosenheim

Tel: 49-8031-354-560

Israel - Ra'anana

Italy - Milan

Italy - Padova

Tel: 972-9-744-7705

Tel: 39-0331-742611

Fax: 39-0331-466781

Tel: 39-049-7625286

Netherlands - Drunen

Tel: 49-7131-67-3636

Tel: 49-8931-9700

Germany - Haan

Finland - Espoo

France - Paris

Fax: 43-7242-2244-393

Denmark - Copenhagen

Norway - Trondheim Tel: 47-7289-7561

Poland - Warsaw Tel: 48-22-3325737

Romania - Bucharest Tel: 40-21-407-87-50

Spain - Madrid Tel: 34-91-708-08-90 Fax: 34-91-708-08-91

Sweden - Gothenberg Tel: 46-31-704-60-40

Sweden - Stockholm Tel: 46-8-5090-4654

UK - Wokingham Tel: 44-118-921-5800 Fax: 44-118-921-5820

© 2018 Microchip Technology Inc. 10/25/17