ADM3485E* PRODUCT PAGE QUICK LINKS

Last Content Update: 02/23/2017

COMPARABLE PARTS -

View a parametric search of comparable parts.

EVALUATION KITS

 Standard RS-485 Half-Duplex Evaluation Board, EVAL-RS485HDEBZ

DOCUMENTATION

Application Notes

- AN-1161: EMC-Compliant RS-485 Communication Networks
- AN-1176: Component Footprints and Symbols in the Binary .Bxl File Format
- AN-960: RS-485/RS-422 Circuit Implementation Guide

Data Sheet

 ADM3485E: 15 kV ESD-Protected, 3.3 V,12 Mbps, EIA RS-485/RS-422 Transceiver Data Sheet

SOFTWARE AND SYSTEMS REQUIREMENTS 🖳

- ADI RS-485/RS-422 Cross Reference Guide
- RS-232 Transceivers Cross Reference Guide

TOOLS AND SIMULATIONS \Box

ADM3485E IBIS Model

REFERENCE DESIGNS 🖵

CN0313

REFERENCE MATERIALS 🖵

Solutions Bulletins & Brochures

- Emerging Energy Applications Solutions Bulletin, Volume 10, Issue 4
- Test & Instrumentation Solutions Bulletin, Volume 10, Issue 3

Technical Articles

 Safeguard Your RS485 Communication Networks from Harmful EMC Events

DESIGN RESOURCES 🖵

- ADM3485E Material Declaration
- PCN-PDN Information
- · Quality And Reliability
- Symbols and Footprints

DISCUSSIONS

View all ADM3485E EngineerZone Discussions.

SAMPLE AND BUY 🖳

Visit the product page to see pricing options.

TECHNICAL SUPPORT 🖳

Submit a technical question or find your regional support number.

DOCUMENT FEEDBACK 🖳

Submit feedback for this data sheet.

This page is dynamically generated by Analog Devices, Inc., and inserted into this data sheet. A dynamic change to the content on this page will not trigger a change to either the revision number or the content of the product data sheet. This dynamic page may be frequently modified.

TABLE OF CONTENTS

INDEE OF CONTENTS
Features
Applications
Functional Block Diagram
General Description
Revision History
Specifications
Timing Specifications
Absolute Maximum Ratings5
Thermal Resistance
ESD Caution5
Pin Configuration and Pin Function Descriptions6
REVISION HISTORY
8/10—Rev. C to Rev. D
Changes to Table 1, Driver, Logic Inputs 3
12/06—Rev. B to Rev. C
Updated FormatUniversal
Removed PDIP ModelUniversal
Changes to Features, Applications, and General Description 1
Changes to Specifications
Changes to Timing Specifications
Changes to Absolute Maximum Ratings
Reorganized Test Circuits and Switching
Characteristics Section
Replaced Figure 3 to Figure 11
Deleted Figure 12 to Figure 14
Changes to Figure 15 to Figure 20
Changes to Figure 21 and Figure 22
Changes to Table 9
Deleted Figure 24
Removed Fast Transient Burst Immunity
(IEC1000-4-4) Section
Updated Outline Dimensions
Changes to Ordering Guide
10/04—Rev. A to Rev. B
Updated FormatUniversal
Changes to Power-Supply Current, Table 1
Updated Outline Dimensions
Changes to Ordering Guide

Test Circuits and Switching Characteristics	7
Typical Performance Characteristics	9
Standards and Testing	11
ESD Testing	11
Applications Information	12
Differential Data Transmission	12
Cable and Data Rate	12
Receiver Open-Circuit Fail-Safe	12
Outline Dimensions	13
Ordering Guide	13

5/00—Rev. 0 to Rev. A

SPECIFICATIONS

 V_{CC} = +3.3 V \pm 0.3 V. All specifications T_{MIN} to $T_{\text{MAX}},$ unless otherwise noted.

Table 1.

Parameter	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments
DRIVER						
Differential Outputs						
Differential Output Voltage	V_{OD}	2.0			V	$R_L = 100 \Omega$ (RS-422) (see Figure 3)
		1.5			V	$R_L = 54 \Omega$ (RS-485) (see Figure 3)
		1.5			V	$R_L = 60 \Omega$ (RS-485) (see Figure 4)
$\Delta V_{OD} $ for Complementary Output States ¹	ΔV_{OD}			0.2	V	$R_L = 54 \Omega$ or 100 Ω (see Figure 3)
Common-Mode Output Voltage	Voc			3	V	$R_L = 54 \Omega$ or 100 Ω (see Figure 3)
$\Delta V_{OC} $ for Complementary Output States ¹	ΔV_{OC}			0.2	V	$R_L = 54 \Omega$ or 100 Ω (see Figure 3)
Short-Circuit Output Current	losd	-250			mA	$V_{OUT} = -7 \text{ V}$
				250	mA	$V_{OUT} = 12 V$
Logic Inputs						
Input Low Voltage	V_{IL}			8.0	V	DE, DI, RE
Input High Voltage	V_{IH}	2.0			٧	DE, DI, RE
Logic Input Current	I _{IN1}			±2	μΑ	DE, DI, RE
RECEIVER						
Differential Inputs						
Differential Input Threshold Voltage	V_{TH}	-0.2		+0.2	V	$-7 \text{ V} < \text{V}_{CM} < +12 \text{ V}$
Input Voltage Hysteresis	ΔV_{TH}		50		mV	$V_{CM} = 0 V$
Input Resistance (A, B)	R _{IN}	12			kΩ	$-7 \text{ V} < \text{V}_{CM} < +12 \text{ V}$
Input Current (A, B)	I _{IN2}			1.0	mA	$DE = 0 \text{ V}, V_{CC} = 0 \text{ V or } 3.6 \text{ V}, V_{IN} = 12 \text{ V}$
		-0.8			mA	$DE = 0 \text{ V}, V_{CC} = 0 \text{ V or } 3.6 \text{ V}, V_{IN} = -7 \text{ V}$
RO Logic Output						
Output Voltage High	V _{OH}	V _{CC} – 0.4 V			V	$I_{OUT} = -1.5 \text{ mA, } V_{ID} = 200 \text{ mV (see Figure 5)}$
Output Voltage Low	V_{OL}			0.4	V	$I_{OUT} = 2.5 \text{ mA}, V_{ID} = 200 \text{ mV} \text{ (see Figure 5)}$
Short-Circuit Output Current	I _{OSR}	±8		±60	mA	$0 \text{ V} < V_{RO} < V_{CC}$
Tristate Output Leakage Current	lozr			±1	μΑ	$V_{CC} = 3.6 \text{ V}, 0 \text{ V} < V_{OUT} < V_{CC}$
POWER SUPPLY CURRENT						
Voltage Range	Vcc	3.0		3.6	V	
Supply Current	lcc		1.1	2.2	mA	No load, DI = 0 V or V_{CC} , DE = V_{CC} , \overline{RE} = 0 V or V_{CC}
			0.95	1.9	mA	$\frac{\text{No load, DI} = 0 \text{ V or V}_{CC}, \text{DE} = 0 \text{ V},}{\text{RE} = 0 \text{ V}}$
Shutdown Current	I _{SHDN}		0.002	1	μΑ	$DE = 0 \text{ V}, \overline{RE} = V_{CC}, DI = 0 \text{ V or } V_{CC}$
ESD PROTECTION						
A, B Pins			±15		kV	Human body model
All Pins Except A, B			±4		kV	Human body model

 $^{^1}$ $\Delta |V_{\text{OD}}|$ and $\Delta |V_{\text{OC}}|$ are the changes in V_{OD} and $V_{\text{OC}},$ respectively, when DI input changes state.

TIMING SPECIFICATIONS

 $V_{CC} = 3.3 \text{ V}, T_A = 25^{\circ}\text{C}.$

Table 2.

Parameter	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments
DRIVER						
Maximum Data Rate		12	15			
Differential Output Delay	t _{DD}	1	22	35	ns	$R_L = 60 \Omega$, $C_{L1} = C_{L2} = 15 \text{ pF (see Figure 6)}$
Differential Output Transition Time	t _{TD}	3	11	25	ns	$R_L = 60 \Omega$, $C_{L1} = C_{L2} = 15 pF$ (see Figure 6)
Propagation Delay						
From Low to High Level	t _{PLH}	7	23	35	ns	$R_L = 27 \Omega$ (see Figure 7)
From High to Low Level	t _{PHL}	7	23	35	ns	$R_L = 27 \Omega$ (see Figure 7)
$ t_{PLH} - t_{PHL} $ Propagation Delay Skew	t _{PDS}		-1.4	±8	ns	$R_L = 27 \Omega$ (see Figure 7)
Enable/Disable Timing						
Enable Time to Low Level	t _{PZL}		42	90	ns	$R_L = 110 \Omega$ (see Figure 9)
Enable Time to High Level	t _{PZH}		42	90	ns	$R_L = 110 \Omega$ (see Figure 8)
Disable Time from Low Level	t _{PLZ}		35	80	ns	$R_L = 110 \Omega$ (see Figure 9)
Disable Time from High Level	t _{PHZ}		35	80	ns	$R_L = 110 \Omega$ (see Figure 8)
Enable Time from Shutdown to Low Level	t _{PSL}		650	900	ns	$R_L = 110 \Omega$ (see Figure 9)
Enable Time from Shutdown to High Level	t _{PSH}		650	900	ns	$R_L = 110 \Omega$ (see Figure 8)
RECEIVER						
Propagation Delay						
From Low to High Level	t _{RPLH}	25	62	90	ns	$V_{ID} = 0 \text{ V to } 3.0 \text{ V, } C_{L} = 15 \text{ pF (see Figure 10)}$
From High to Low Level	t _{RPHL}	25	62	90	ns	$V_{ID} = 0 \text{ V to } 3.0 \text{ V, } C_L = 15 \text{ pF (see Figure 10)}$
t _{RPLH} - t _{RPHL} Propagation Delay Skew	t _{RPDS}		6	±10	ns	$V_{ID} = 0 \text{ V to } 3.0 \text{ V, } C_L = 15 \text{ pF (see Figure 10)}$
Enable/Disable Timing						
Enable Time to Low Level	t _{RPZL}		25	50	ns	$C_L = 15 \text{ pF (see Figure 11)}$
Enable Time to High Level	t _{RPZH}		25	50	ns	$C_L = 15 \text{ pF (see Figure 11)}$
Disable Time from Low Level	t _{RPLZ}		25	45	ns	$C_L = 15 \text{ pF (see Figure 11)}$
Disable Time from High Level	t _{RPHZ}		25	45	ns	$C_L = 15 \text{ pF (see Figure 11)}$
Enable Time from Shutdown to Low Level	t _{RPSL}		720	1400	ns	$C_L = 15 \text{ pF (see Figure 11)}$
Enable Time from Shutdown to High Level	t _{RPSH}		720	1400	ns	$C_L = 15 \text{ pF (see Figure 11)}$
Time to Shutdown ¹	t _{SHDN}	80	190	300	ns	

¹ The transceivers are put into shutdown mode by bringing the RE high and the DE low. If the inputs are in this state for less than 80 ns, the parts are guaranteed not to enter shutdown. If the parts are in this state for 300 ns or more, the parts are guaranteed to enter shutdown.

ABSOLUTE MAXIMUM RATINGS

 $T_A = 25$ °C, unless otherwise noted.

Table 3.

1 autc 3.	
Parameter	Values
V _{cc} to GND	-0.3 V to +6 V
Digital Input/Output Voltage (DE, $\overline{\text{RE}}$, DI)	-0.3 V to +6 V
Receiver Output Voltage (RO)	$-0.3 \text{ V to } (V_{CC} + 0.3 \text{ V})$
Driver Output (A, B)/	
Receiver Input (A, B) Voltage	−8 V to +13 V
Driver Output Current	±250 mA
Power Dissipation (8-Lead SOIC_N)	650 mW
Operating Temperature Range	-40°C to +85°C
Storage Temperature Range	−65°C to +150°C
Lead Temperature, Soldering (10 sec)	300°C
Vapor Phase (60 sec)	215°C
Infrared (15 sec)	220°C
ESD Rating	
Human Body Model (A, B)	±15 kV

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

THERMAL RESISTANCE

 θ_{JA} is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

Table 4. Thermal Resistance

Package Type	θја	Unit
8-Lead SOIC_N	158	°C/W

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND PIN FUNCTION DESCRIPTIONS



Figure 2. SOIC_N Pin Configuration (R-8)

Table 5. Pin Function Descriptions

Mnemonic	Pin Number	Description
	Number	Description
RO	1	Receiver Output. When enabled, if $A > B$ by 200 mV, then $RO = high$. If $A < B$ by 200 mV, then $RO = high$.
RE	2	Receiver Output Enable. With RE low, the receiver output (RO) is enabled. With RE high, the output goes into a high impedance state. If RE is high and DE is low, the ADM3485E enters a shutdown state.
DE	3	Driver Output Enable. A high level enables the driver differential outputs A and B. A low level places it in a high impedance state.
DI	4	Driver Input. When the driver is enabled, a logic low on DI forces A low and B high, while a logic high on DI forces A high and B low.
GND	5	Ground Connection, 0 V.
Α	6	Noninverting Receiver Input A/Driver Output A.
В	7	Inverting Receiver Input B/Driver Output B.
Vcc	8	Power Supply, $3.3 \text{ V} \pm 0.3 \text{ V}$.

TEST CIRCUITS AND SWITCHING CHARACTERISTICS

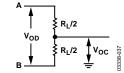


Figure 3. Driver Differential Output Voltage and Common-Mode Output Voltage

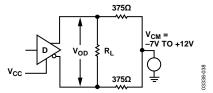


Figure 4. Driver Differential Output Voltage with Varying Common-Mode Voltage

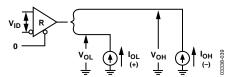
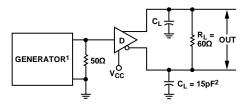


Figure 5. Receiver Output Voltage High and Output Voltage Low



 ^{1}PPR = 250kHz, 50% DUTY CYCLE, t_{R} \leq 6.0ns, $\rm Z_{O}$ = 50 $\!\Omega$. $^{2}\rm C_{L}$ INCLUDES PROBE AND STRAY CAPACITANCE.

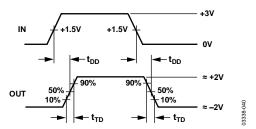
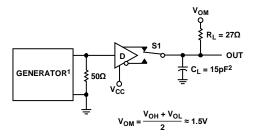


Figure 6. Driver Differential Output Delay and Transition Times



 ^{1}PPR = 250kHz, 50% DUTY CYCLE, t_{R} \leq 6.0ns, $\rm Z_{O}$ = 50 $\!\Omega$. $^{2}\rm C_{L}$ INCLUDES PROBE AND STRAY CAPACITANCE.

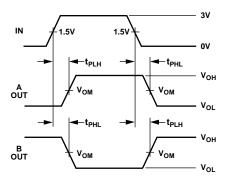
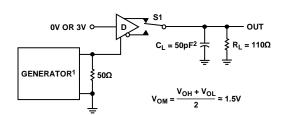


Figure 7. Driver Propagation Delays



 ^{1}PPR = 250kHz, 50% DUTY CYCLE, t_{R} \leq 6.0ns, Z_{O} = 50 $\!\Omega$. $^{2}C_{L}$ INCLUDES PROBE AND STRAY CAPACITANCE.

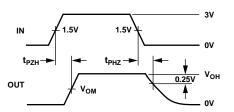
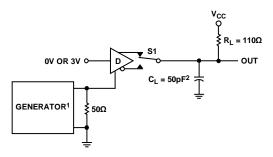


Figure 8. Driver Enable and Disable Times (tpzh, tpsh, tphz)



 ^{1}PPR = 250kHz, 50% DUTY CYCLE, $t_{R} \leq 6.0\text{ns},$ Z_{O} = 50 $\Omega.$ $^{2}\text{C}_{L}$ INCLUDES PROBE AND STRAY CAPACITANCE.

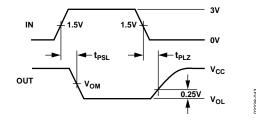
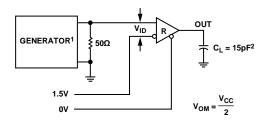


Figure 9. Driver Enable and Disable Times (tpzl, tpsl, tplz)



 ^{1}PPR = 250kHz, 50% DUTY CYCLE, t_{R} \leq 6.0ns, $\rm Z_{O}$ = 50 $\!\Omega$. $^{2}\rm C_{L}$ INCLUDES PROBE AND STRAY CAPACITANCE.

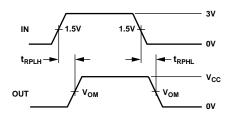
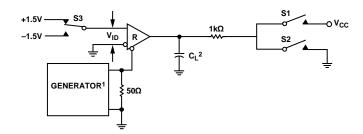


Figure 10. Receiver Propagation Delays



 ^{1}PPR = 250kHz, 50% DUTY CYCLE, $t_{R} \leq 6.0\text{ns},$ Z_{O} = 50 $\Omega.$ $^{2}\text{C}_{L}$ INCLUDES PROBE AND STRAY CAPACITANCE.

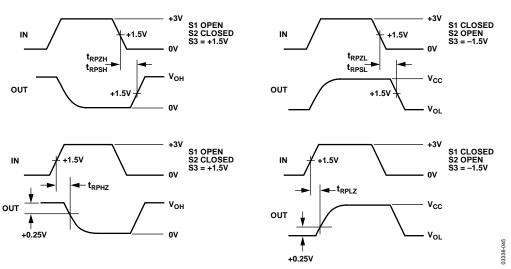


Figure 11. Receiver Enable and Disable Times

TYPICAL PERFORMANCE CHARACTERISTICS

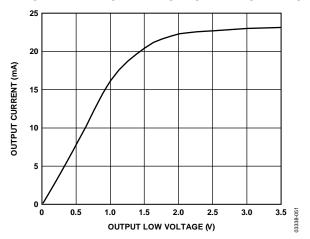


Figure 12. Output Current vs. Receiver Output Low Voltage

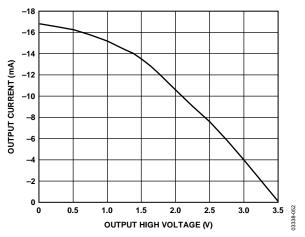


Figure 13. Output Current vs. Receiver Output High Voltage

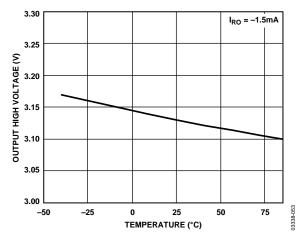


Figure 14. Receiver Output High Voltage vs. Temperature

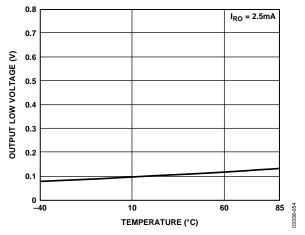


Figure 15. Receiver Output Low Voltage vs. Temperature

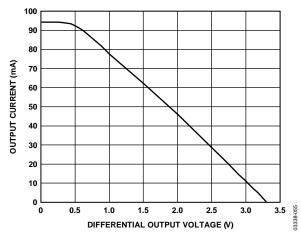


Figure 16. Driver Output Current vs. Differential Output Voltage

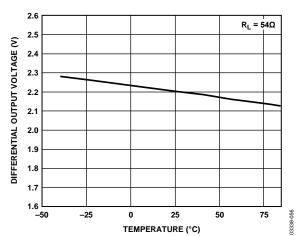


Figure 17. Driver Differential Output Voltage vs. Temperature

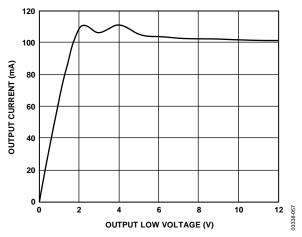


Figure 18. Output Current vs. Driver Output Low Voltage

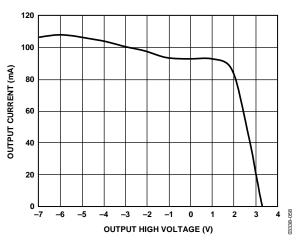


Figure 19. Output Current vs. Driver Output High Voltage

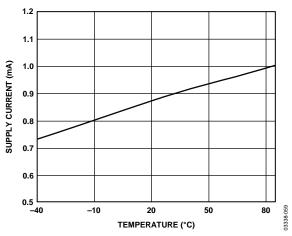


Figure 20. Supply Current vs. Temperature

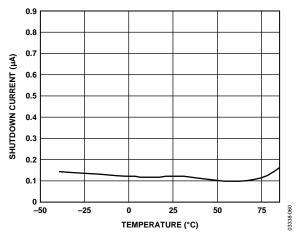


Figure 21. Shutdown Current vs. Temperature

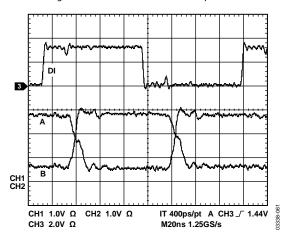


Figure 22. Driver Propagation Delay

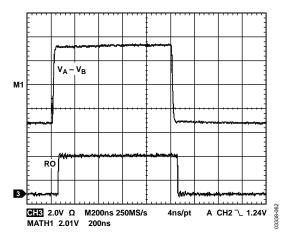


Figure 23. Receiver Propagation Delay, Driven by External RS-485 Device

STANDARDS AND TESTING

Table 6 compares RS-422 and RS-485 interface standards, and Table 7 and Table 8 show transmitting and receiving truth tables.

Table 6.

Specification	RS-422	RS-485
Transmission Type	Differential	Differential
Maximum Data Rate	10 Mbps	10 Mbps
Maximum Cable Length	4000 ft	4000 ft
Minimum Driver Output Voltage	±2 V	±1.5 V
Driver Load Impedance	100 Ω	54 Ω
Receiver Input Resistance	4 kΩ min	12 kΩ min
Receiver Input Sensitivity	±200 mV	±200 mV
Receiver Input Voltage Range	−7 V to +7 V	−7 V to +12 V
Number of Drivers/Receivers per Line	1/10	32/32

Table 7. Transmitting Truth Table

Tr	ansmitting	Inputs	Transm	nitting Outputs
RE	DE	DI	В	Α
X ¹	1	1	0	1
X^1	1	0	1	0
0	0	X ¹	High-Z ² High-Z ²	High-Z ² High-Z ²
1	0	X ¹	High-Z ²	High-Z ²

¹ X = don't care.

Table 8. Receiving Truth Table

	Receiving Inputs	Receiving Outputs		
RE	DE	A – B	RO	
0	X ¹	>+0.2 V	1	
0	X ¹	<-0.2 V	0	
0	X ¹	Inputs open	1	
1	X ¹	X ¹	High-Z ²	

¹ X = don't care.

ESD TESTING

Two coupling methods are used for ESD testing, contact discharge and air-gap discharge. Contact discharge calls for a direct connection to the unit being tested. Air-gap discharge uses a higher test voltage but does not make direct contact with the unit under test. With air-gap discharge, the discharge gun is moved toward the unit under test, developing an arc across the air gap, hence the term air-gap discharge. This method is

influenced by humidity, temperature, barometric pressure, distance, and rate of closure of the discharge gun. The contact discharge method, while less realistic, is more repeatable and is gaining acceptance and preference over the air-gap method.

Although very little energy is contained within an ESD pulse, the extremely fast rise time, coupled with high voltages, can cause failures in unprotected semiconductors. Catastrophic destruction can occur immediately as a result of arcing or heating. Even if catastrophic failure does not occur immediately, the device can suffer from parametric degradation, which can result in degraded performance. The cumulative effects of continuous exposure can eventually lead to complete failure.

I/O lines are particularly vulnerable to ESD damage. Simply touching or plugging in an I/O cable can result in a static discharge that can damage or completely destroy the interface product connected to the I/O port. It is extremely important, therefore, to have high levels of ESD protection on the I/O lines.

The ESD discharge could induce latch-up in the device under test, so it is important that ESD testing on the I/O pins be carried out while device power is applied. This type of testing is more representative of a real-world I/O discharge, where the equipment is operating normally when the discharge occurs.

Table 9. ESD Test Results

ESD Test Method	I/O Pins
Human Body Model	±15 kV

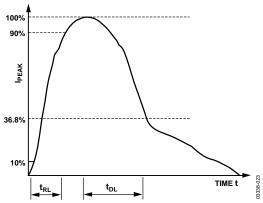


Figure 24. Human Body Model Current Waveform

² High-Z = high impedance.

² High-Z = high impedance.

APPLICATIONS INFORMATION DIFFERENTIAL DATA TRANSMISSION

Differential data transmission is used to reliably transmit data at high rates over long distances and through noisy environments. Differential transmission nullifies the effects of ground shifts and noise signals that appear as common-mode voltages on the line.

Two main standards that specify the electrical characteristics of transceivers used in differential data transmission are approved by the Electronics Industries Association (EIA). The RS-422 standard specifies data rates up to 10 Mbps and line lengths up to 4000 feet. A single driver can drive a transmission line with up to 10 receivers. The RS-485 standard was defined to cater to true multipoint communications. This standard meets or exceeds all the requirements of RS-422 but also allows multiple drivers and receivers to be connected to a single bus. An extended common-mode range of -7 V to +12 V is defined.

The most significant difference between RS-422 and RS-485 is the fact that under the RS-485 standard the drivers may be disabled, thereby allowing more than one to be connected to a single line. Only one driver should be enabled at a time, but the RS-485 standard contains additional specifications to guarantee device safety in the event of line contention.

CABLE AND DATA RATE

The transmission line of choice for RS-485 communications is a twisted pair. Twisted-pair cable tends to cancel common-mode noise and also causes cancellation of the magnetic fields generated by the current flowing through each wire, thereby reducing the effective inductance of the pair.

The ADM3485E is designed for bidirectional data communications on multipoint transmission lines. A typical application showing a multipoint transmission network is illustrated in Figure 25. Only one driver can transmit at a particular time, but multiple receivers may be enabled simultaneously.

As with any transmission line, it is important that reflections are minimized. This can be achieved by terminating the extreme ends of the line using resistors equal to the characteristic impedance of the line. Stub lengths off the main line must also be kept as short as possible. A properly terminated transmission line appears purely resistive to the driver.

RECEIVER OPEN-CIRCUIT FAIL-SAFE

The receiver input includes a fail-safe feature that guarantees a logic high on the receiver when the inputs are open circuit or floating.

Table 10. RS-422 and RS-485 Interface Standards

Specification	RS-422	RS-485
Transmission Type	Differential	Differential
Maximum Cable Length	4000 ft	4000 ft
Minimum Driver Output Voltage	±2 V	±1.5 V
Driver Load Impedance	100 Ω	54 Ω
Receiver Input Resistance	4 kΩ min	12 kΩ min
Receiver Input Sensitivity	±200 mV	±200 mV
Receiver Input Voltage Range	−7 V to +7 V	−7 V to +12 V

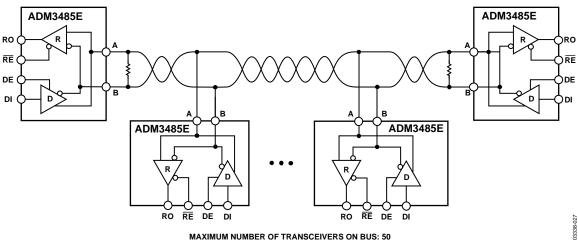
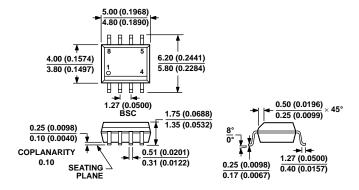


Figure 25. Multipoint Transmission Network

OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-012-AA
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS
(IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR
REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 26. 8-Lead Standard Small Outline Package [SOIC_N]
Narrow Body
(P. 9)

Dimensions shown in millimeters and (inches)

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option
ADM3485EAR	−40°C to +85°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
ADM3485EAR-REEL7	-40°C to +85°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
ADM3485EAR-REEL	-40°C to +85°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
ADM3485EARZ	-40°C to +85°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
ADM3485EARZ-REEL7	-40°C to +85°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
ADM3485EARZ-REEL	-40°C to +85°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8

¹ Z = RoHS Compliant Part.

NOTES

NOTES

ADM3485E

NOTES

