ORDERING INFORMATION

Part Number	Package Markings	T _J Rating Package Description			
EN2342QI	EN2342QI	-40°C to +125°C 68-pin (8mm x 11mm x 3mm) QFN T			
EVB-EN2342QI	EN2342QI	QFN Evaluation Board			

Packing and Marking Information: https://www.inel.com/support/quality-and-reliability/packing.html

PIN FUNCTIONS

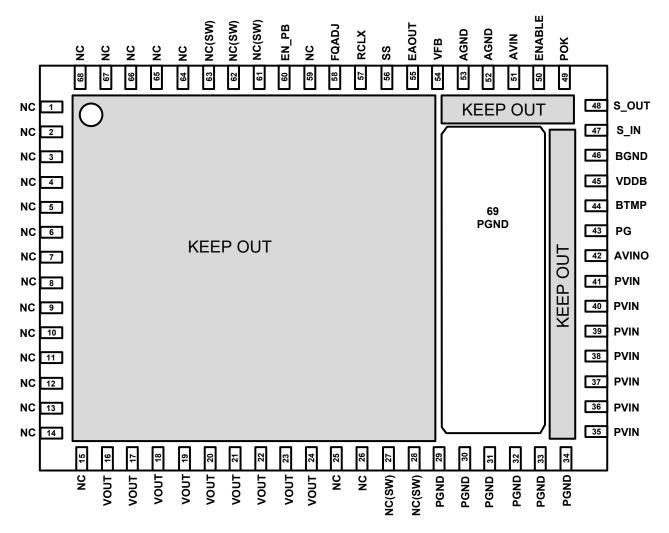


Figure 3. Pin Diagram (Top View)

NOTE A: NC pins are not to be electrically connected to each other or to any external signal, ground, or voltage. All pins including NC pins must be soldered to the PCB. Failure to follow this guideline may result in part malfunction or damage.

NOTE B: Shaded area highlights exposed metal below the package that is not to be mechanically or electrically connected to the PCB. Refer to Figure 12 for details.

NOTE C: White 'dot' on top left is pin 1 indicator on top of the device package.

PIN DESCRIPTIONS

PIN	NAME	TYPE	FUNCTION
1-15, 25-26, 59, 64- 68	NC	-	NO CONNECT – These pins may be internally connected. Do not connect them to each other or to any other electrical signal. Failure to follow this guideline may result in device damage.
16-24	VOUT	Power	Regulated converter output. Connect these pins to the load and place output capacitor between these pins and PGND pins 29-34.
27-28, 61-63	NC(SW)	-	NO CONNECT – These pins are internally connected to the common switching node of the internal MOSFETs. They are not to be electrically connected to any external signal, ground, or voltage. Failure to follow this guideline may result in damage to the device.
29-34	PGND	Ground	Input/output power ground. Connect these pins to the ground electrode of the input and output filter capacitors. See VOUT and PVIN pin descriptions for more details.
35-41	PVIN	Power	Input power supply. Connect to input power supply. Decouple with input capacitor to PGND pins 29-34.
42	AVINO	Power	Internal 3.3V linear regulator output. Connect this pin to AVIN (Pin 51) for applications where operation from a single input voltage (PVIN) is required. If AVINO is being used, place a $1\mu F$, X5R/X7R, capacitor between AVINO and AGND as close as possible to AVINO.
43	PG	Analog	PMOS gate. Place a 22nF, X5R/X7R, capacitor between this pin and BTMP. A 560Ω may be used between PVIN and PG to assist in filtering the input rail in noisy systems.
44	ВТМР	Analog	Bottom plate ground. See pin 43 description.
45	VDDB	Power	Internal regulated voltage used for the internal control circuitry. Place a 0.22µF, X5R/X7R, capacitor between this pin and BGND.
46	BGND	Ground	Ground for VDDB. See pin 45 description.
47	S_IN	Digital	Digital synchronization input. This pin accepts either an input clock to phase lock the internal switching frequency or a S_OUT signal from another EN2342QI. Leave this pin floating if not used.
48	S_OUT	Digital	Digital synchronization output. PWM signal is output on this pin. Leave this pin floating if not used.
49	РОК	Digital	Power OK is an open drain transistor (pulled up to AVIN or similar voltage) used for power system state indication. POK is logic high when VOUT is within -10% of VOUT nominal. Leave this pin floating if not used.
50	ENABLE	Analog	Output enable. Applying a logic high to this pin enables the output and initiates a soft-start. Applying a logic low disables the output. ENABLE logic cannot be higher than AVIN (refer to Absolute Maximum Ratings). Do not leave floating.
51	AVIN	Power	3.3V Input power supply for the controller. Place a $1\mu F$, X5R/X7R, capacitor between AVIN and AGND.

PIN	NAME	TYPE	FUNCTION
52, 53	AGND	Ground	Analog ground. This is the ground return for the controller. All AGND pins need to be connected to a quiet ground.
54	VFB	Analog	External feedback input. The feedback loop is closed through this pin. A voltage divider at VOUT is used to set the output voltage. The mid-point of the divider is connected to VFB. A phase lead network from this pin to VOUT is also required to stabilize the loop.
55	EAOUT	Analog	Optional error amplifier output. Allows for customization of the control loop.
56	SS	Analog	Soft-start node. The soft-start capacitor is connected between this pin and AGND. The value of this capacitor determines the startup time.
57	RCLX	Analog	Over-current protection. Placement of a resistor on this pin will adjust the over-current protection threshold. See Table 2 for the recommended RCLX Value to set OCP at the nominal value specified in the Electrical Characteristics table. No current limit protection when this pin is left floating.
58	FQADJ	Analog	Adding a resistor (R_{FS}) to this pin will adjust the switching frequency of the EN2342QI. See Table 1 for suggested resistor values on R_{FS} for various PVIN/VOUT combinations to maximize efficiency. Do not leave floating.
60	EN_PB	Analog	Enable pre-bias protection. Connect EN_PB directly to AVIN to enable the Pre-Bias Protection feature. Pull EN_PB directly to ground to disable the feature. Do not leave this pin floating. See Pre-Bias Operation for details.
69	PGND	Ground	Not a perimeter pin. Device thermal pad to be connected to the system GND plane for heat-sinking purposes.

ABSOLUTE MAXIMUM RATINGS

CAUTION: Absolute Maximum ratings are stress ratings only. Functional operation beyond the recommended operating conditions is not implied. Stress beyond the absolute maximum ratings may impair device life. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

Absolute Maximum Pin Ratings

PARAMETER	SYMBOL	MIN	MAX	UNITS
PVIN, VOUT, PG		-0.5	15	V
ENABLE, POK, EN_PB		-0.3	AV _{IN} +0.3	V
Dual Supply PVIN Rising and Falling Slew Rate (1)			25	V/ms
Single Supply PVIN Rising and Falling Slew Rate (1)			10	V/ms
Pin Voltages – AVINO, AVIN, S_IN, S_OUT		3.0	6.0	V
Pin Voltages – VFB, SS, EAOUT, RCLX, FQADJ, VDDB, BTMP		-0.5	2.75	V

Absolute Maximum Thermal Ratings

PARAMETER	CONDITION	MIN	MAX	UNITS
Maximum Operating Junction Temperature			+150	°C
Storage Temperature Range		-65	+150	°C
Reflow Peak Body Temperature	(10 Sec) MSL3 JEDEC J-STD-020A		+260	°C

Absolute Maximum ESD Ratings

PARAMETER	CONDITION	MIN	MAX	UNITS
HBM (Human Body Model)		±2000		V
CDM (Charged Device Model)		±500		V

RECOMMENDED OPERATING CONDITIONS

PARAMETER	SYMBOL	MIN	MAX	UNITS
Input Voltage Range	PV _{IN}	4.5	14	V
AVIN: Controller Supply Voltage	AVIN	3.0	5.5	V
Output Voltage Range (2)	V _{OUT}	0.75	5	V
Output Current Range	I _{out}		4	Α
Operating Ambient Temperature Range	T _A	-40	+85	°C
Operating Junction Temperature	Τ _J	-40	+125	°C

THERMAL CHARACTERISTICS

PARAMETER	SYMBOL	TYPICAL	UNITS
Thermal Shutdown	T _{SD}	150	°C
Thermal Shutdown Hysteresis	T _{SDHYS}	35	°C
Thermal Resistance: Junction to Ambient (0 LFM) (3)	θ JA	18	°C/W
Thermal Resistance: Junction to Case (0 LFM)	θις	2	°C/W

⁽¹⁾ PVIN rising and falling slew rates cannot be outside of specification. After the device is powered, the input voltage transients should be kept under 1V peak-to-peak under all conditions. A noisy input rail will affect device performance. For accurate power up sequencing, use a fast ENABLE logic (>3V/100µs) after both AVIN and PVIN is high.

⁽²⁾ Dropout: Maximum $V_{OUT} \le V_{IN} - 2.5V$.

⁽³⁾ Based on 2oz. external copper layers and proper thermal design in line with EIJ/JEDEC JESD51-7 standard for high thermal conductivity boards.

ELECTRICAL CHARACTERISTICS

NOTE: V_{IN} = 12V, Minimum and Maximum values are over operating ambient temperature range (-40°C \leq T_A \leq +85°C) unless otherwise noted. Typical values are at T_A = 25°C.

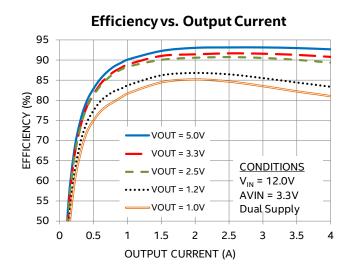
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNITS
Operating Input Voltage	PV_{IN}		4.5		14.0	V
Controller Input Voltage	AVIN		3.0		5.5	V
AVIN UVLO Rising	$AVIN_{UVLOR}$	UVLO is not asserted	2.5	2.75	3.0	V
AVIN UVLO Falling	AVIN _{OVLOF}	UVLO is asserted	2.1	2.35	2.6	V
AVIN UVLO Hysteresis	AVIN _{HYS}			400		mV
AVIN Pin Input Current	I _{AVIN}			7	15	mA
Internal LDO Output	AVINO			3.3		V
Shut-Down Supply	IPVIN _S	PVIN=12V, AVIN=3.3V, ENABLE=0V		2		mA
Current	IAVINs	PVIN=12V, AVIN=3.3V, ENABLE=0V		300		μΑ
Feedback Pin Voltage	V_{FB}	VIN = 12V, I _{LOAD} = 0, TA = 25°C Only	0.7425	0.750	0.7575	V
Feedback Pin Voltage (Load and Temperature)	V_{FB}	OA ≤ I _{LOAD} ≤ 4A Starting Date Code: X510 or greater	0.739	0.750	0.761	٧
Feedback Pin Voltage (Line, Load, Temperature)	V_{FB}	4.5V ≤ VIN ≤ 14V; 0A ≤ I _{LOAD} ≤ 4A	0.735	0.750	0.765	٧
Feedback Pin Input Leakage Current	I _{FB}	VFB pin input leakage current ⁽⁴⁾	-5		5	nA
V _{OUT} Rise Time	t _{RISE}	$C_{SS} = 47 nF^{(5)(6)}$		3.2		ms
Soft-Start Capacitor Range	C _{SS_RANGE}		10	47	68	nF
Output Current Range	I _{OUT}		0		4	Α
Over Current Trip Level	I _{OCP}	PVIN=12V, V _{OUT} =1.2V	4.15	6		Α
Short Circuit Average Input Current	I _{IN_AVG_OCP}	Short = $10m\Omega^{(7)}$		100		mA

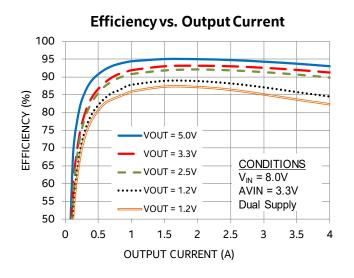
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNITS
Disable Threshold	$V_{DISABLE}$	ENABLE pin logic Low	0.0		0.95	V
ENABLE Threshold	V _{ENABLE}	ENABLE pin logic High	1.25		AVIN	V
ENABLE Hysteresis	EN _{HYS}			200		mV
ENABLE Lockout Time	T _{ENLOCKOUT}			8		ms
ENABLE Input Current	I _{ENABLE}	370k internal pull-down (4)		4		μА
Switching Frequency	F _{SW}	$R_{FS} = 3k\Omega$		1.0		MHz
External SYNC Clock Frequency Lock Range	F _{PLL_LOCK}	Range of SYNC clock frequency (See Table 1)	0.9		1.8	MHz
S_IN Threshold – Low	$V_{S_IN_LO}$	S_IN clock logic low level (4)			0.8	V
S_IN Threshold – High	V _{S_IN_HI}	S_IN clock logic high level (4)	1.8		2.5	V
S_OUT Threshold – Low	V _{S_OUT_LO}	S_OUT clock logic low level (4)			0.8	V
S_OUT Threshold – High	V _{S_OUT_HI}	S_OUT clock logic high level (4)	1.8		2.5	V
POK Lower Threshold	POK _{LT}	Vout / Vout_nom		90		%
POK Output low Voltage	V_{POKL}	With 4mA current sink into POK			0.4	V
POK Output Hi Voltage	V_{POKH}	PVIN range: 4.5V ≤ V _{IN} ≤ 14V			AVIN	V
POK V _{OH} Leakage Current	I _{POKL}	POK High ⁽⁴⁾			1	μΑ

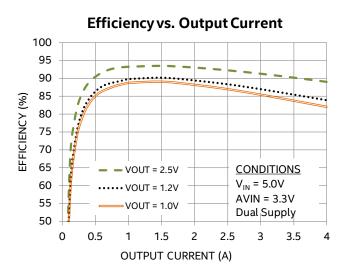
- (4) Parameter not production tested but is guaranteed by design.
- (5) Rise time calculation begins when AVIN > V_{UVLO} and ENABLE = HIGH.
- (6) V_{OUT} Rise Time Accuracy does not include soft-start capacitor tolerance.
- (7) Output short circuit condition was performed with load impedance that is greater than or equal to $10m\Omega$.

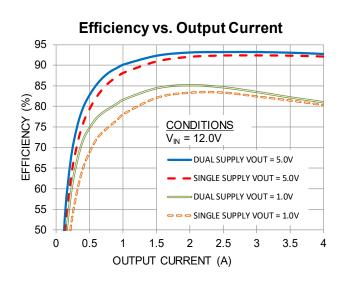
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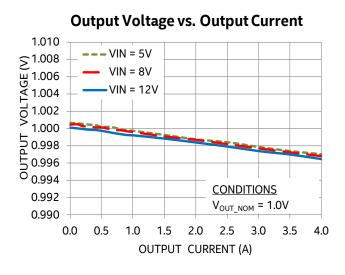
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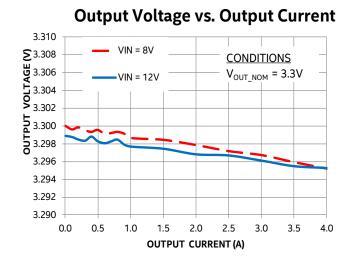




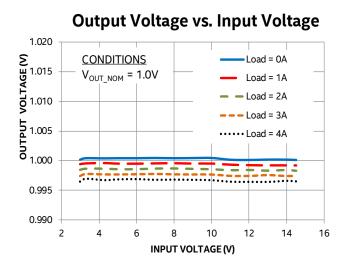


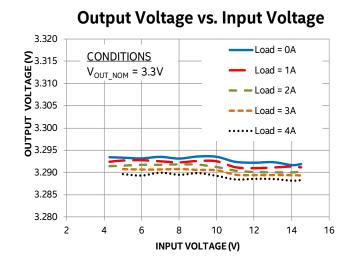


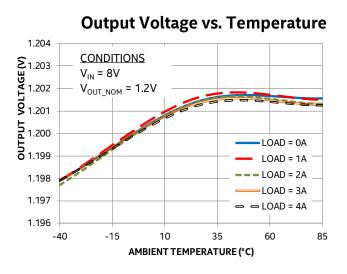


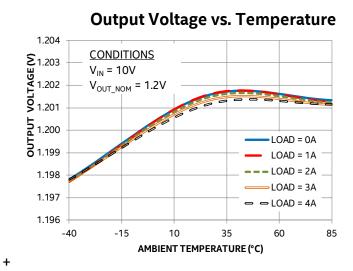


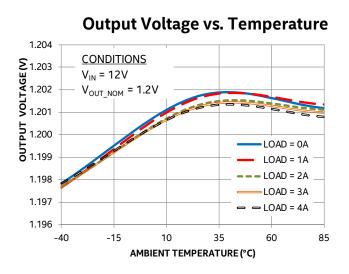
TYPICAL PERFORMANCE CURVES (CONTINUED)

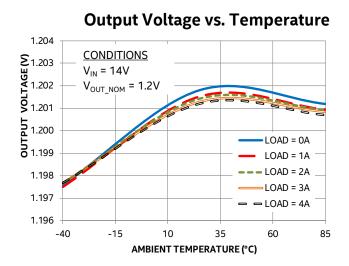




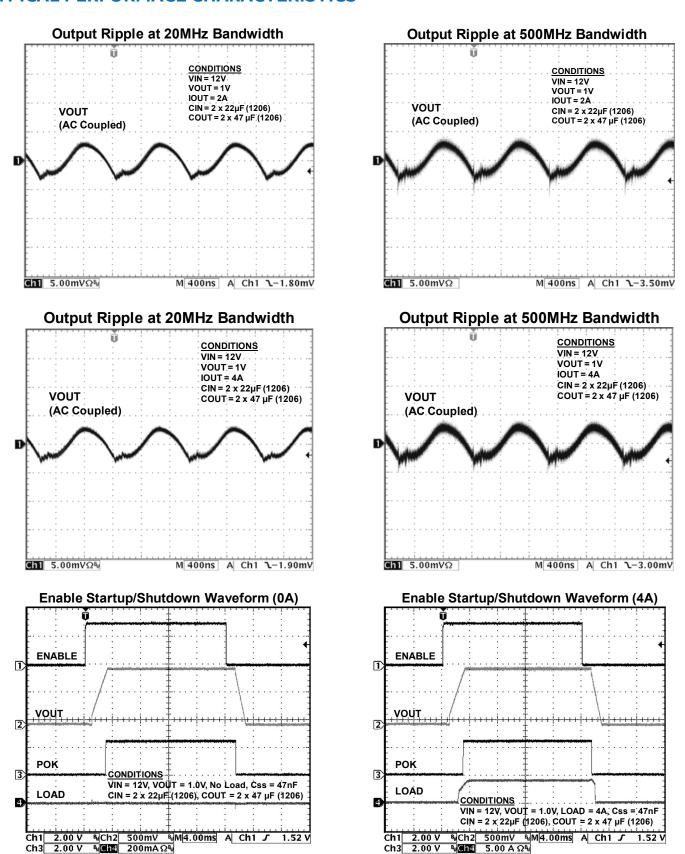




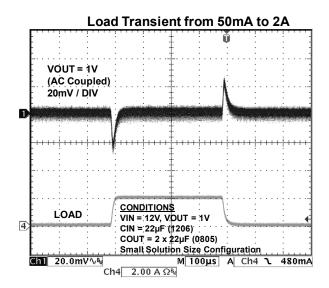


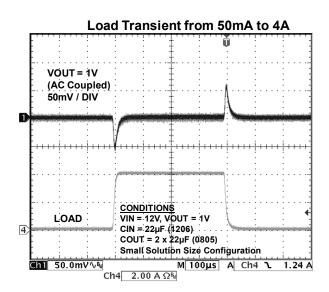


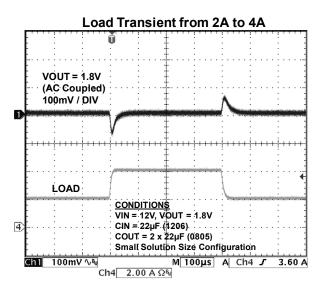
TYPICAL PERFORMACE CHARACTERISTICS

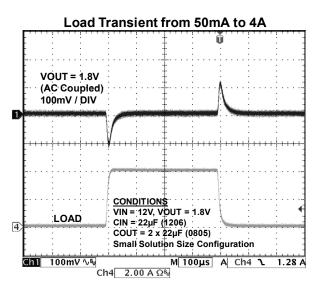


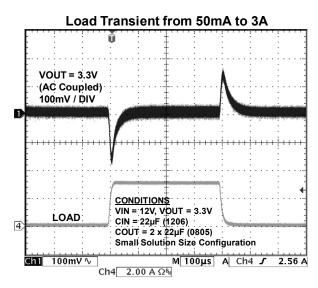
TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)

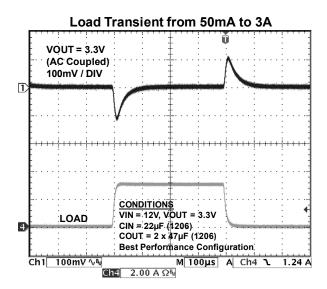






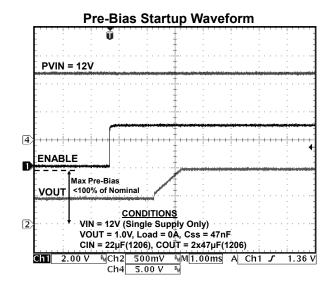


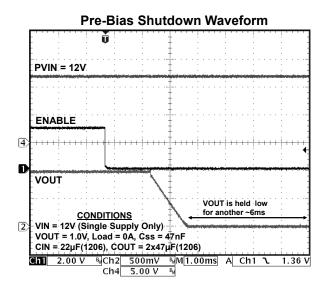




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TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)





FUNCTIONAL BLOCK DIAGRAM

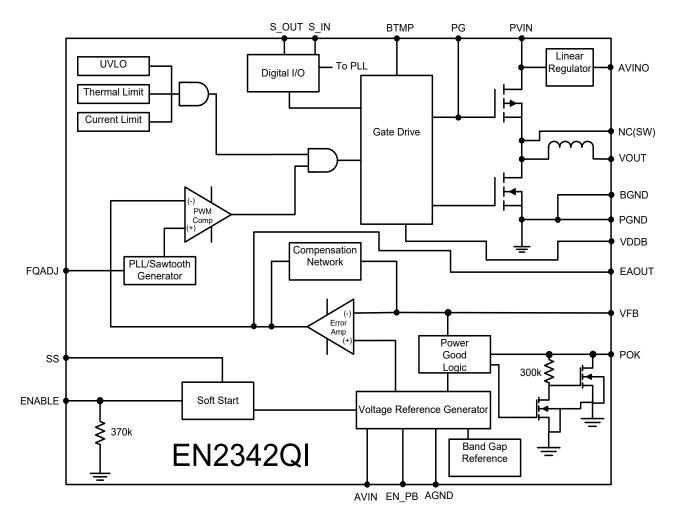


Figure 4. Functional Block Diagram

FUNCTIONAL DESCRIPTION

Synchronous DC-DC Step-Down PowerSoC

The EN2342QI is a highly integrated synchronous, buck converter with integrated controller, power MOSFET switches and inductor. The nominal input voltage (PVIN) range is 4.5V to 14V and can support up to 4A of continuous output current. The output voltage is programmed using an external resistor divider network. The control loop utilizes a Type IV Voltage-Mode compensation network and maximizes on a low-noise PWM topology. Much of the compensation circuitry is internal to the device. However, a phase lead capacitor is required along with the output voltage feedback resistor divider to complete the Type IV compensation network.. The high switching frequency of the EN2342QI enables the use of small size input and output filter capacitors, as well as a wide loop bandwidth within a small foot print.

The power supply has the following protection features:

- Pre-Bias Protection.
- Over-Current and Short Circuit Protection.
- Thermal Soft-Shutdown with Hysteresis.
- Under-Voltage Lockout Protection.
- Switching Frequency Synchronization.
- Programmable Soft-Start.
- Power OK Output Monitoring.

Modes of Operation

The EN2342QI is designed to be powered by either a single input supply (PVIN) or two separate supplies: one for PVIN and the other for AVIN. The EN2342QI is not "hot pluggable." Refer to the PVIN Slew Rate specification on page 6.

Single Input Supply Application (PVIN Only):

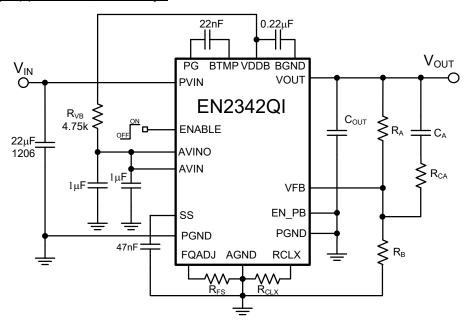


Figure 5. Single Input Supply Schematic

In single input supply mode, the EN2342QI only requires one input voltage rail (typically 12V). The EN2342QI has an internal linear regulator that converts PVIN to 3.3V. The output of the linear regulator is provided on the AVINO pin once the device is enabled. AVINO should be connected to AVIN. Also, in this single supply application, place a resistor (R_{VB}) between VDDB and AVIN, as shown in Figure 5. Intel Enpirion recommends R_{VB} =4.75k Ω .

Dual Input Supply Application (PVIN and AVIN):

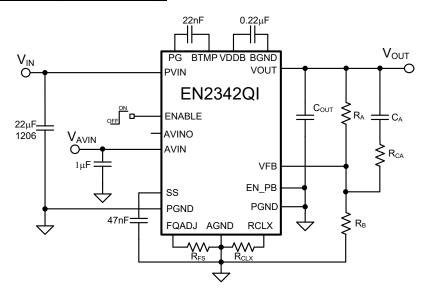


Figure 6. Dual Input Supply Schematic

In dual input supply mode, two input voltage rails are required (typically 12V for PVIN and 3.3V for AVIN). Refer to Figure 6 for the recommended schematic for a dual input supply application. Since AVINO is not used, it can be left open.

Enable Operation

The ENABLE pin provides a means to enable normal operation or to shut down the device. A logic high will enable the converter into normal operation. When the ENABLE pin is asserted (high) the device will undergo a normal soft-start. A logic low will disable the converter. A logic low will power down the device in a controlled manner and the device is subsequently shut down. The ENABLE signal has to be low for at least the ENABLE Lockout Time (8ms) in order for the device to be re-enabled. To ensure accurate startup sequencing the ENABLE/DISABLE signal should be faster than 1V/100µs. A slower ENABLE/DISABLE signal may result in a delayed startup and shutdown response. Do not leave ENABLE floating.

Pre-Bias Operation

The EN2342QI has a Pre-Bias feature which will allow the regulator to startup into a pre-charged output. The pre-biased output voltage must be below the nominal regulation voltage; otherwise, damage may occur during startup and shutdown. To use this feature, the EN2342QI must be configured to Single Supply mode, set to standalone operation (no parallel operation) and follow the instructions below:

- The EN_PB pin must be pulled high to AVIN.
- A resistor divider must be connected from PVIN to ENABLE to Ground (10k on top, 4.02k on the bottom) to ensure proper shutdown. The resistor divider will disable the device when PVIN falls below approximately 4.5V. The resistor divider values may be adjusted accordingly to meet PVIN requirements. See Figure 7.
- PVIN rail should be in regulation (>4.5V) prior to being enabled.
- Since the ENABLE pin is tied to the resistor divider to PVIN, an open drain (such as the POK signal of another regulator or Sequencer) should be tied to ENABLE in order to keep the device disabled while the PVIN rail rises into regulation.
- Once the PVIN rail is in regulation, the ENABLE may be pulled high through the resistor divider.
- The ENABLE rise time must be faster than 3V/100μs.

The output will start up from the Pre-Bias voltage into regulation monotonically if the instructions are followed; otherwise, the Pre-Bias Protection feature may not function properly. Starting up into a Pre-Bias voltage without the Pre-Bias Protection feature enabled can lead to device damage. When using the Pre-Bias feature, the device must be disabled using the ENABLE pin prior to PVIN falling out of regulation (<4.5V), otherwise damage may occur during shutdown. To disable the Pre-Bias feature pull the EN_PB pin directly to ground. Do not leave the EN_PB pin floating. See Typical Performance Characteristics for an example of Pre-Bias Protection. See Figure 7 for a typical schematic with Pre-Bias Protection enabled.

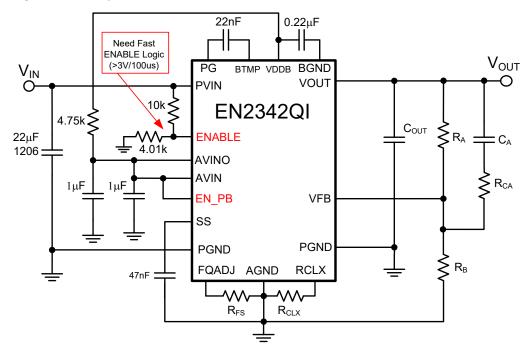


Figure 7. Pre-Bias Application Circuit

Frequency Synchronization

The switching frequency of the EN2342QI can be phase-locked to an external clock source to move unwanted beat frequencies out of band. The internal switching clock of the EN2342QI can be phase locked to a clock signal applied to the S_IN pin. An activity detector recognizes the presence of an external clock signal and automatically phase-locks the internal oscillator to this external clock. Phase-lock will occur as long as the input clock frequency is in the range of 0.9MHz to 1.8MHz. The external clock frequency must be within $\pm 10\%$ of the nominal switching frequency set by the R_{FS} resistor. It is recommended to use a synchronized clock frequency close to the typical frequency recommendations in Table 1. A 3.01k Ω resistor from FQADJ to ground is recommended for clock frequencies within $\pm 10\%$ of 1MHz. When multiple devices are connected to a single external clock, use a clock frequency normally used by the highest output voltage device (the highest frequency). When no clock is present, the device reverts to the free running frequency of the internal oscillator set by the R_{FS} resistor.

The efficiency performance of the EN2342QI for various PVIN/VOUT combinations can be optimized by adjusting the switching frequency. Table 1 shows recommended R_{FS} values for various PVIN/VOUT combinations in order to optimize performance of the EN2342QI. It is recommended to use R_{FS} values that are at least equal to or higher than Table 1, never lower.

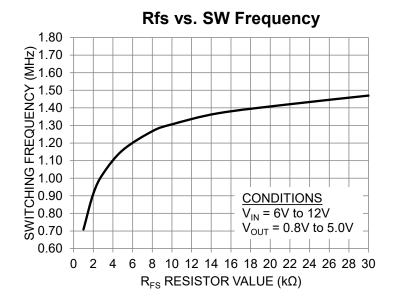


Figure 8. Typical R_{FS} vs. Switching Frequency

Table 1. Recommended R _{FS} Values

PVIN	VOUT	R_{FS}	Typical Fsw
	5.0V	30k	1.48 MHz
	3.3V	22k	1.42 MHz
4.5V	2.5V	10k	1.3 MHz
to	1.8V	4.87k	1.15 MHz
14V	1.5V	3.01k	1.0 MHz
	1.2V	3.01k	1.0 MHz
	<1.0V	3.01k	1.0 MHz

Soft-Start Operation

Soft start is a means to ramp the output voltage gradually upon start-up. The output voltage rise time is controlled by the choice of soft-start capacitor, which is placed between the SS pin (pin 56) and the AGND pin (pin 52). During start-up of the converter, the reference voltage to the error amplifier is linearly increased to its final level by an internal current source of approximately 10µA. The soft-start time is measured from when $V_{IN} > V_{UVLOR}$ and ENABLE pin voltage crosses its logic high threshold to when V_{OUT} reaches its programmed value. The total soft-start time can be calculated by:

Soft Start Time (ms): $T_{SS} \approx C_{ss}$ [nF] x 0.067

Typical soft-start time is approximately 3.2ms with SS capacitor value of 47nF.

POK Operation

The POK signal is an open drain signal (requires a pull up resistor to AVIN or similar voltage) from the converter indicating the output voltage is within the specified range. Typically, a $100k\Omega$ or lower resistance is used as the pull-up resistor. The POK signal will be logic high (AVIN) when the output voltage is above 90% of the programmed voltage level. If the output voltage is below this point, the POK signal will be a logic low. The POK signal can be used to sequence down-stream converters by tying to their enable pins.

Over-Current Protection (OCP)

The current limit function is achieved by sensing the current flowing through a high-side sense PFET. If the current exceeds the OCP threshold, the switching cycle is terminated and an OCP counter is incremented. If the counter value reaches 32 OCP cycles, the device will shut down as described below. If there are 8 consecutive cycles that do not exceed the OCP threshold, the counter will reset. Once the OCP counter has reached 32 cycles, the MOSFET switches will tri-state and the soft start capacitor will be discharged. After approximately 32ms the device will attempt a restart. If the OCP condition persists, the device will enter a hiccup mode until the OCP condition is removed. The OCP trip point depends on PVIN, VOUT, RCLX, RFS and is meant to protect the device from damage. OCP is not an adjustable threshold. For a list of RCLX values, see Table 2.

PVIN VOUT R_{CLX} Res 5.0V 68.1k 30k 3.3V 61.9k 22k 2.5V 56.2k 10k 4.5V 54.9k to 1.8V 4.87k 14V 1.5V 53.6k 3.01k 1.2V 46.4k 3.01k <1.0V 38.3k 3.01k

Table 2. Recommended R_{CLX} Values

Note: Do not leave RCLX floating.

Thermal Overload Protection

Thermal shutdown circuit will disable device operation when the junction temperature exceeds approximately 150°C. The device will go through a soft-shutdown and allow the output to discharge in a controlled manner. This prevents excessive output ringing in the event of a thermal fault condition. After a thermal shutdown event, when the junction temperature drops by approximately 35°C, the converter will re-start with a normal soft-start.

Input Under-Voltage Lock-out (UVLO)

Internal circuits ensure that the converter will not start switching until the AVIN input voltage is above the specified minimum voltage. Hysteresis, input de-glitch and output leading edge blanking ensures high noise immunity and prevents false UVLO triggers.

APPLICATION INFORMATION

Output Voltage Programming and Loop Compensation

The EN2342QI uses a Type IV Voltage Mode compensation network. Type IV Voltage Mode control is a proprietary Intel Enpirion control scheme that maximizes control loop bandwidth to deliver excellent load transient responses and maintain output regulation with pin point accuracy. For ease of use, most of this network has been customized and is integrated within the device package.

The EN2342QI output voltage is programmed using a simple resistor divider network (R_A and R_B). The feedback voltage at VFB is nominally 0.75V. R_A depends on Table 6 and R_B can be calculated based on Figure 9. The values recommended for C_{OUT} , C_A , and R_{CA} make up the external compensation of the EN2342QI. It will vary with each PVIN and VOUT combination to optimize on performance. The EN2342QI solution can be optimized for either smallest size or highest performance. Please see Table 6 for a list of recommended R_A , R_{CA} , and R_{COUT} values for each solution. Since VFB is a sensitive node, do not touch the VFB node while the device is in operation as doing so may introduce parasitic capacitance into the control loop that causes the device to behave abnormally and damage may occur. Be sure to use the recommended switching frequency for each output voltage.

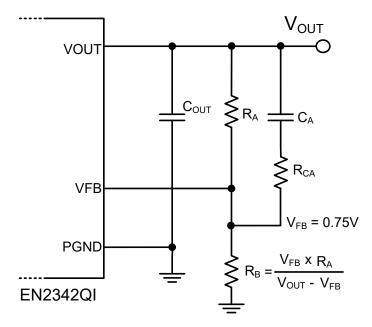


Figure 9. V_{OUT} Resistor Divider & Compensation Components. See Table 6 for details

Input Capacitor Selection

The EN2342QI requires a $22\mu\text{F}/1206$ input capacitor. Low-cost, low-ESR ceramic capacitors should be used as input capacitors for this converter. The dielectric must be X5R or X7R rated. Y5V or equivalent dielectric formulations must not be used as these lose too much capacitance with frequency, temperature and bias voltage. In some applications, lower value capacitors are needed in parallel with the larger, capacitors in order to provide high frequency decoupling. Table 3 contains a list of recommended input capacitors.

	<u> </u>	•		
Description	MFG	P/N		
22μF, 16V, X5R, 10%, 1206	Murata	GRM31CR61C226ME15		
22μF, 16V, X5R, 20%, 1206	Taiyo Yuden	EMK316ABJ226ML-T		

Table 3. Recommended Input Capacitors

Output Capacitor Selection

As seen from Table 6, EN2342QI has been optimized for use with either two $47\mu F/1206$ or two $22\mu F/0805$ output capacitors. Low ESR ceramic capacitors are required with X5R or X7R rated dielectric formulation. Y5V or equivalent dielectric formulations must not be used as these lose too much capacitance with frequency, temperature and bias voltage. Table 5 contains a list of recommended output capacitors. In some applications, extra bulk capacitance is required at the load. Extra bulk capacitors may be used to improve load transient response at the load. The maximum output capacitance allowed on EN2342QI depends on the output voltage. Table 4 shows the maximum output capacitance based on output voltage. The maximum output capacitance includes all capacitors connected from the output power plain to ground (including those at the load).

VOUT	R _{FS}	COUT_MAX	Compensation
5.0V	30k	150μF	
3.3V	22k	500μF	
2.5V	10k	600μF	C _A = 100pF
1.8V	4.87k	700μF	R _A = 250kΩ
1.5V	3.01k	800µF	$R_{CA} = 5k\Omega$
1.2V	3.01k	900μF	
≤1.0V	3.01k	1000μF	

Table 4. Vout vs. Maximum Cout

Note that when bulk capacitors are used the converter must work harder during startup in order to raise the output voltage from zero volts into regulation. If there is too much output capacitance, the device can hit current limit before it is able to raise the output into regulation. If current limit is reached the device stops switching, the output will be discharged and the cycle repeats itself indefinitely. The equation below can be used to estimate the maximum output capacitance allowed based on current limit. Since the maximum output capacitance in the calculation does not account for temperature or part to part variations, it is always good to add margin by using a value that is 80% of the calculated output capacitance value.

 $C_{OUT\ MAX} = I_{TOTAL} * dt / dv * 0.8$

C_{OUT_MAX} = Maximum allowable output capacitance

 I_{TOTAL} = Max output current of device minus the load during startup

dv = Change in voltage (which is 0 to V_{OUT})

dt = Soft-start time (ms) $\approx C_{ss}$ [nF] x 0.067

The output capacitance can also influence the output ripple. Output ripple voltage is determined by the aggregate output capacitor impedance.

Capacitor impedance, denoted as Z, is comprised of capacitive reactance, effective series resistance, ESR, and effective series inductance, ESL reactance.

Placing output capacitors in parallel reduces the impedance and will hence result in lower ripple voltage.

$$\frac{1}{Z_{Total}} = \frac{1}{Z_1} + \frac{1}{Z_2} + \dots + \frac{1}{Z_n}$$

Table 5. Recommended Output Capacitors

Description	MFG	P/N		
47μF, 6.3V, X5R, 20%, 1206	Murata	GRM31CR60J476ME19L		
47μF, 10V, X5R, 20%, 1206	Taiyo Yuden	LMK316BJ476ML-T		
22μF, 10V, X5R, 20%, 0805	Panasonic	ECJ-2FB1A226M		
22μF, 10V, X5R, 20%, 0805	Taiyo Yuden	LMK212BJ226MG-T		

Table 6. RA, CA, and RCA Values for Various PVIN/VOUT Combinations: Low Vout Ripple vs. Smallest Solution Size.

			Low V	_{оит} Ripple			Small	est Soluti	on Size	
			$C_{IN} = 1 x$	22μF/120	9					
			C _{OUT} = 2	x 47μF/120	96		C _{IN} =	1 x 22μF	/1206	
			R _A = 180	/(Vout ^{0.5}) k	Ω		Cout	= 2 x 22µl	F/0805	
			R_{CA}	Nominal	Nominal			D.	Nominal	Nominal
PVIN	V _{OUT}	C _A (pF)	κ _{cA} (kΩ)	Ripple	Deviation	R_A (k Ω)	C _A (pF)	R _{CA} (kΩ)	Ripple	Deviation
			(K12)	(mV)	(mV)			(K12)	(mV)	(mV)
	≤1.0V	10	30	≤5	≤47	75	27	0.1	≤10	≤34
	1.2V	12	27	6	48	43	39	0.1	13	33
	1.5V	15	27	5	53	56	39	0.1	15	38
14V	1.8V	22	27	6	54	56	39	0.1	18	41
	2.5V	27	24	8	55	51	39	0.1	26	59
	3.3V	39	18	11	63	51	33	0.1	35	63
	5.0V	47	8.2	18	97	75	22	5.1	42	115
	≤1.0V	18	22	≤4	≤48	27	47	0.1	≤10	≤35
	1.2V	22	22	5	49	75	47	0.1	13	37
	1.5V	27	20	5	53	75	47	0.1	15	38
12V	1.8V	33	20	6	54	75	47	0.1	17	44
	2.5V	47	18	7	54	56	47	0.1	25	59
	3.3V	56	15	10	66	51	39	0.1	32	63
	5.0V	56	10	16	99	75	22	5.1	39	128
	≤1.0V	33	18	≤3	≤45	27	82	0.1	≤9	≤35
	1.2V	39	18	4	46	30	100	0.1	13	39
	1.5V	47	18	5	54	30	100	0.1	14	43
10V	1.8V	56	16	6	56	30	100	0.1	17	50
	2.5V	68	12	7	57	75	56	0.1	26	70
	3.3V	82	10	9	68	56	47	0.1	30	83
	5.0V	100	4.3	14	98	75	33	5.1	33	140
	≤1.0V	100	8.2	≤3	≤51	100	100	0.1	≤10	≤41
	1.2V	100	8.2	4	51	100	100	0.1	12	43
	1.5V	100	8.2	4	54	100	100	0.1	14	46
8.0V	1.8V	100	8.2	5	57	100	100	0.1	16	53
	2.5V	100	8.2	6	64	91	82	0.1	23	71
	3.3V	100	8.2	8	70	75	56	0.1	25	85
	5.0V	100	8.2	10	110	75	56	5.1	30	127
	≤1.0V	100	8.2	≤3	≤60	100	100	0.1	≤9	≤46
	1.2V	100	8.2	4	63	100	100	0.1	12	51
6.6V	1.5V	100	8.2	4	65	100	100	0.1	14	56
	1.8V	100	8.2	5	68	100	100	0.1	16	61
	2.5V	100	8.2	5	75	100	100	0.1	19	83
	3.3V	100	8.2	6	85	91	82	0.1	22	106
	≤1.0V	100	8.2	≤3	≤73	100	100	0.1	≤9	≤56
	1.2V	100	8.2	3	75	100	100	0.1	11	63
5V	1.5V	100	8.2	4	76	100	100	0.1	13	70
	1.8V	100	8.2	4	80	100	100	0.1	13	78
	2.5V	100	8.2	4	88	100	100	0.1	14	98

Note: See Figure 8. Use the equation in Figure 8 to calculate R_B (for low V_{OUT} ripple option). Output Ripple is measured at no load and Nominal Deviation is for a 2A load transient step in one direction. For compensation values of output voltage in between the specified output voltages, choose compensation values of the lower output voltage setting.

THERMAL CONSIDERATIONS

Thermal considerations are important power supply design facts that cannot be avoided in the real world. Whenever there are power losses in a system, the heat that is generated by the power dissipation needs to be accounted for. Intel Enpirion PowerSoC helps alleviate some of those concerns.

Intel Enpirion EN2342QI DC-DC converter is packaged in an 8x11x3mm 68-pin QFN package. The QFN package is constructed with copper lead frames that have exposed thermal pads. The exposed thermal pad on the package should be soldered directly on to a copper ground pad on the printed circuit board (PCB) to act as a heat sink. The recommended maximum junction temperature for continuous operation is 125°C. Continuous operation above 125°C may reduce long-term reliability. The device has a thermal overload protection circuit designed to turn off the device at an approximate junction temperature value of 150°C.

The EN2342QI is guaranteed to support the full 4A output current up to 85°C ambient temperature. The following example and calculations illustrate the thermal performance of the EN2342QI.

Example:

 $V_{IN} = 12V$

 $V_{OUT} = 3.3V$

 $I_{OUT} = 4A$

First calculate the output power.

 $P_{OUT} = 3.3V \times 4A = 13.2W$

Next, determine the input power based on the efficiency (η) shown in Figure 9.

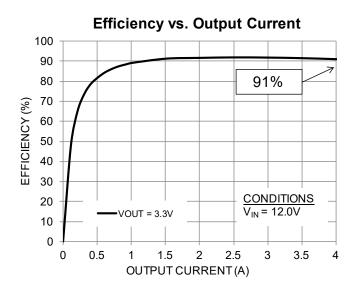


Figure 10. Efficiency vs. Output Current

For $V_{IN} = 12V$, $V_{OUT} = 3.3V$ at 4A, $\eta \approx 91\%$

 $\eta = P_{OUT} / P_{IN} = 91\% = 0.91$

 $P_{IN} = P_{OUT} / \eta$

 $P_{IN} \approx 13.2 \text{W} / 0.9 \approx 14.51 \text{W}$

The power dissipation (PD) is the power loss in the system and can be calculated by subtracting the output power from the input power.

$$P_D = P_{IN} - P_{OUT}$$

 $\approx 14.51W - 13.2W \approx 1.31W$

With the power dissipation known, the temperature rise in the device may be estimated based on the theta JA value (θ_{JA}). The θ_{JA} parameter estimates how much the temperature will rise in the device for every watt of power dissipation. The EN2342QI has a θ_{JA} value of 18 ${}^{\circ}$ C/W without airflow.

Determine the change in temperature (ΔT) based on P_D and θ_{JA} .

$$\Delta T = P_D x \theta_{JA}$$

$$\Delta T \approx 1.31 \text{W} \times 18^{\circ} \text{C/W} = 23.5^{\circ} \text{C} \approx 24^{\circ} \text{C}$$

The junction temperature (T_J) of the device is approximately the ambient temperature (T_A) plus the change in temperature. We assume the initial ambient temperature to be 25°C.

$$T_J = T_A + \Delta T$$

$$T_J \approx 25^{\circ}\text{C} + 24^{\circ}\text{C} \approx 49^{\circ}\text{C}$$

The maximum operating junction temperature (T_{JMAX}) of the device is 125°C, so the device can operate at a higher ambient temperature. The maximum ambient temperature (T_{AMAX}) allowed can be calculated.

$$T_{AMAX} = T_{JMAX} - P_D \times \theta_{JA}$$

 $\approx 125^{\circ}C - 24^{\circ}C \approx 101^{\circ}C$

The maximum ambient temperature the device can reach is 101°C given the input and output conditions. Note that the efficiency will be slightly lower at higher temperatures and this calculation is an estimate.

ENGINEERING SCHEMATIC

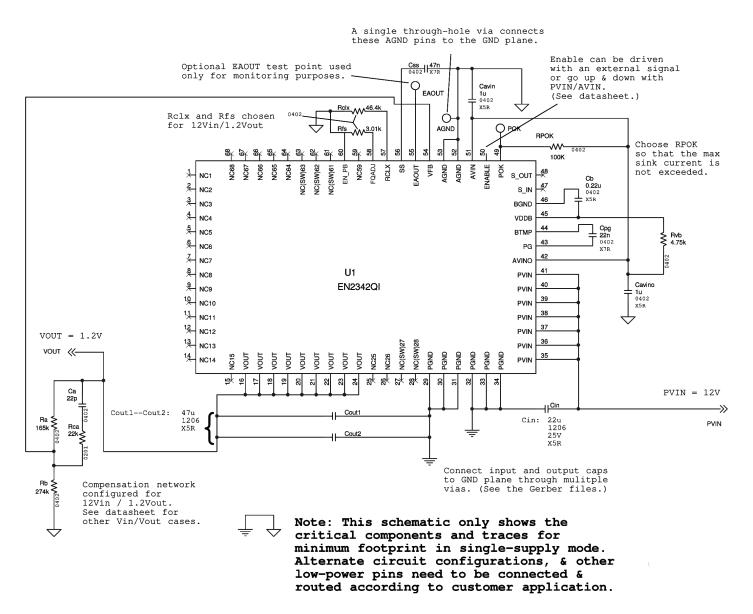


Figure 11. Engineering Schematic with Engineering Notes

LAYOUT RECOMMENDATIONS

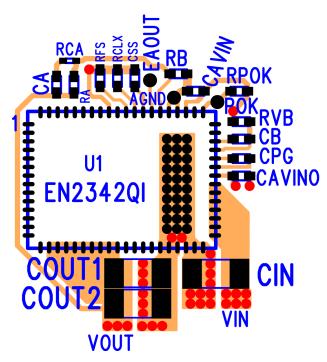


Figure 12. Top Layout with Critical Components Only (Top View)

This layout only shows the critical components and top layer traces for minimum footprint in single-supply mode. Alternate circuit configurations & other low-power pins need to be connected and routed according to customer application. Please see the Gerber files at http://www.intel.com/enpirion for details on all layers.

Recommendation 1: Input and output filter capacitors should be placed on the same side of the PCB, and as close to the EN2342QI package as possible. They should be connected to the device with very short and wide traces. Do not use thermal reliefs or spokes when connecting the capacitor pads to the respective nodes. The +V and GND traces between the capacitors and the EN2342QI should be as close to each other as possible so that the gap between the two nodes is minimized, even under the capacitors.

Recommendation 2: The PGND connections for the input and output capacitors on layer 1 need to have a slit between them in order to provide some separation between input and output current loops.

Recommendation 3: The system ground plane should be the first layer immediately below the surface layer. This ground plane should be continuous and un-interrupted below the converter and the input/output capacitors.

Recommendation 4: The thermal pad underneath the component must be connected to the system ground plane through as many vias as possible. The drill diameter of the vias should be 0.33mm, and the vias must have at least 1 oz. copper plating on the inside wall, making the finished hole size around 0.20-0.26mm. Do not use thermal reliefs or spokes to connect the vias to the ground plane. This connection provides the path for heat dissipation from the converter.

Recommendation 5: Multiple small vias (the same size as the thermal vias discussed in recommendation 4) should be used to connect ground terminal of the input capacitor and output capacitors to the system ground plane. It is preferred to put these vias along the edge of the GND copper closest to the +V copper. These vias connect the input/output filter capacitors to the GND plane, and help reduce parasitic inductances in the input and output current loops. If vias cannot be placed under the capacitors, then place them on both sides of the slit in the top layer PGND copper.

Recommendation 6: AVIN is the power supply for the small-signal control circuits. AVINO powers AVIN in single supply mode. AVIN and AVINO should have a decoupling capacitor close to each of their pins. Refer to Figure 12.

Recommendation 7: The layer 1 metal under the device must not be more than shown in Figure 12. Refer to the section regarding Exposed Metal on Bottom of Package. As with any switch-mode DC-DC converter, try not to run sensitive signal or control lines underneath the converter package on other layers.

Recommendation 8: The V_{OUT} sense point should be just after the last output filter capacitor. Keep the sense trace short in order to avoid noise coupling into the node. Contact Intel MySupport for any remote sensing applications.

Recommendation 9: Keep R_A , C_A , R_B , and R_{CA} close to the VFB pin (Refer to Figure 12). The VFB pin is a high-impedance, sensitive node. Keep the trace to this pin as short as possible. Whenever possible, connect R_B directly to the AGND pins 52 and 53 instead of going through the GND plane.

Recommendation 10: Follow all the layout recommendations as close as possible to optimize performance. Intel provides schematic and layout reviews for all customer designs.

DESIGN CONSIDERATIONS FOR LEAD-FRAME BASED MODULES

Exposed Metal on Bottom of Package

Lead-frames offer many advantages in thermal performance, in reduced electrical lead resistance, and in overall foot print. However, they do require some special considerations.

In the assembly process lead frame construction requires that, for mechanical support, some of the lead-frame cantilevers be exposed at the point where wire-bond or internal passives are attached. This results in several small pads being exposed on the bottom of the package, as shown in Figure 13.

Only the thermal pad and the perimeter pads are to be mechanically or electrically connected to the PC board. The PCB top layer under the EN2342QI should be clear of any metal (copper pours, traces, or vias) except for the thermal pad. The "shaded-out" area in Figure 12 represents the area that should be clear of any metal on the top layer of the PCB. Any layer 1 metal under the shaded-out area runs the risk of undesirable shorted connections even if it is covered by soldermask.

The solder stencil aperture should be smaller than the PCB ground pad. This will prevent excess solder from causing bridging between adjacent pins or other exposed metal under the package. Please consult the Enpirion Manufacturing Application Note for more details and recommendations.

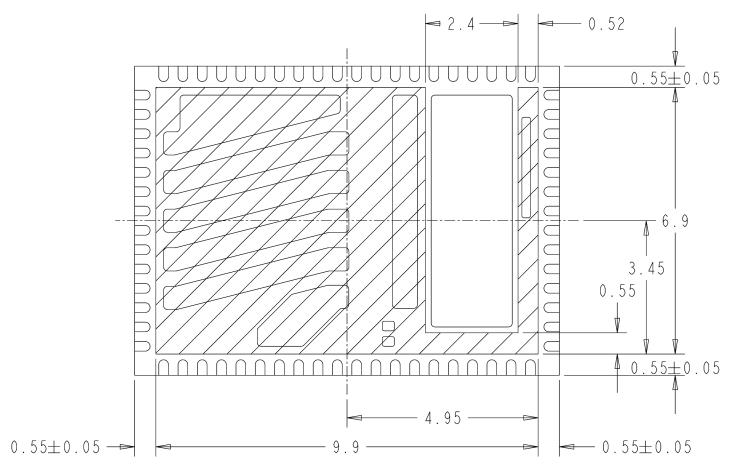


Figure 13. Lead-Frame exposed metal (Bottom View)

Shaded area highlights exposed metal that is not to be mechanically or electrically connected to the PCB.

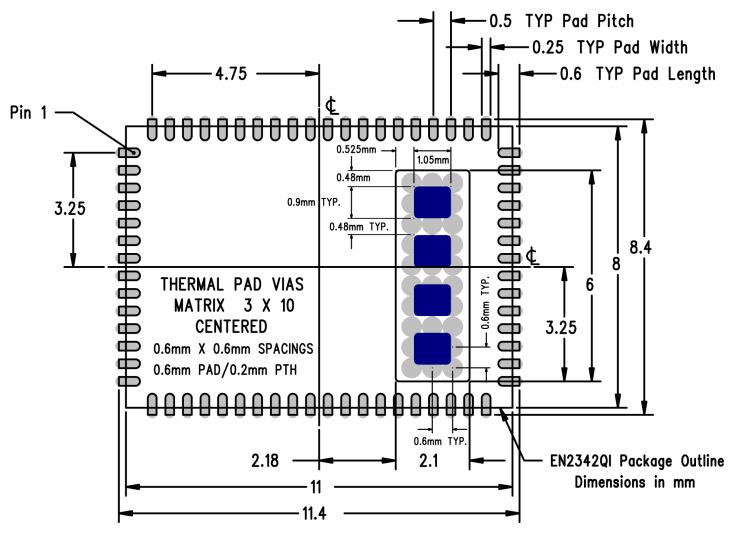


Figure 14. EN2342QI PCB Footprint (Top View)

The solder stencil aperture for the thermal pad is shown in blue and is based on Enpirion power product manufacturing specifications.

PACKAGE DIMENSIONS

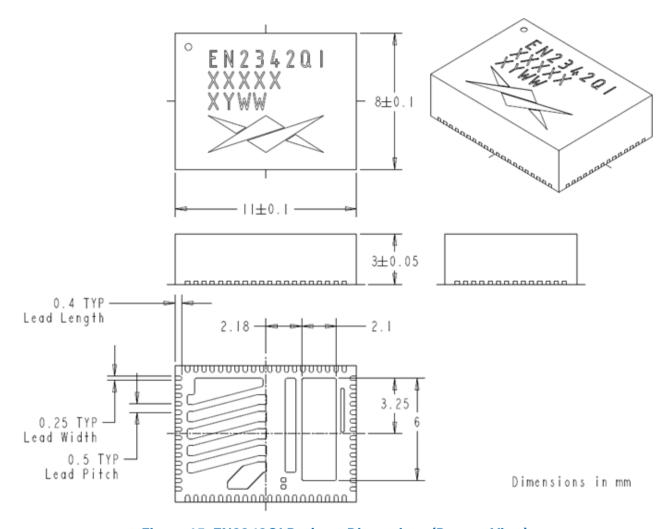


Figure 15. EN2342QI Package Dimensions (Bottom View)

Packing and Marking Information: https://www.intel.com/support/quality-and-reliability/packing.html

REVISION HISTORY

Rev	Date	Change(s)
G	July 2019	Changed datasheet into Intel format

WHERE TO GET MORE INFORMATION

For more information about Intel® and Enpirion® PowerSoCs, visit:

www.intel.com/enpirion

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