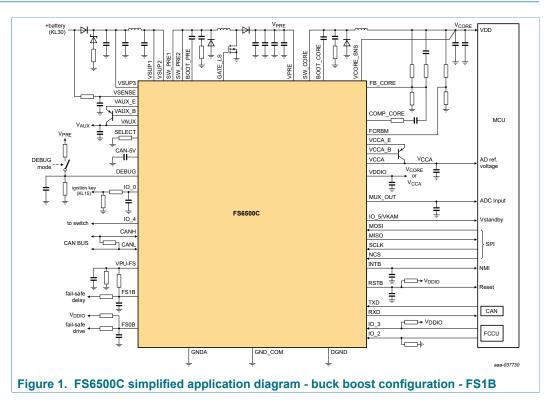
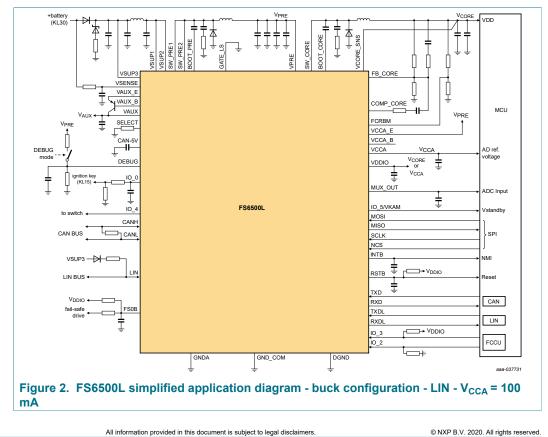
#### Safety power system basis chip with CAN FD and LIN transceivers

## 4 Simplified application diagrams

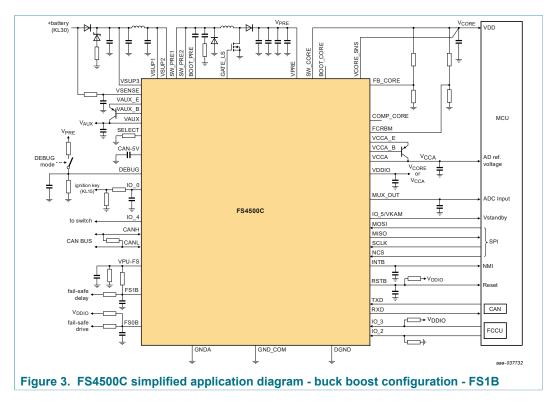




FS6500-FS4500SDS Product short data sheet

Rev. 7.0 — 11 November 2020

Safety power system basis chip with CAN FD and LIN transceivers



# 5 Ordering information

## 5.1 Part number definition

# MC33FS <u>c</u> 5 <u>x</u> <u>y</u> <u>z</u> AE/R2

#### Table 1. Part number breakdown

Code	Option	Variable	Description
С	4 series	V <sub>CORE</sub> type	Linear
	6 series		DC-DC
x	0	V <sub>CORE</sub> current	0.5 A or 0.8 A
	1 2		1.5 A
			2.2 A
У	0	Functions	None
	1		FS1B
	2		LDT
	3		FS1B, LDT
	4		LDT, VKAM ON by default

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# FS6500, FS4500

# Safety power system basis chip with CAN FD and LIN transceivers

Code	Option	Variable	Description
z	Ν	Physical interface	None
	С		CAN FD
	L		CAN FD and LIN

### 5.2 Part numbers list

#### Table 2. Orderable part variations

Part Number	Temperature (T <sub>A</sub> )	Package	FS1B	LDT	VCORE	VCORE type	VKAM on	CAN FD	LIN	Note
MC33FS4500CAE			0	0	0.5 A	Linear	by SPI	1	0	
MC33FS4500LAE			0	0	0.5 A	Linear	by SPI	1	1	
MC33FS4500NAE			0	0	0.5 A	Linear	by SPI	0	0	
MC33FS4501CAE			1	0	0.5 A	Linear	by SPI	1	0	
MC33FS4501NAE			1	0	0.5 A	Linear	by SPI	0	0	
MC33FS4502CAE			0	1	0.5 A	Linear	by SPI	1	0	
MC33FS4502LAE			0	1	0.5 A	Linear	by SPI	1	1	
MC33FS4502NAE			0	1	0.5 A	Linear	by SPI	0	0	
MC33FS4503CAE			1	1	0.5 A	Linear	by SPI	1	0	
MC33FS4503NAE			1	1	0.5 A	Linear	by SPI	0	0	
MC33FS6500CAE			0	0	0.8 A	DC-DC	by SPI	1	0	
MC33FS6500LAE	-		0	0	0.8 A	DC-DC	by SPI	1	1	-
MC33FS6500NAE			0	0	0.8 A	DC-DC	by SPI	0	0	
MC33FS6501CAE			1	0	0.8 A	DC-DC	by SPI	1	0	
MC33FS6501NAE	-	48-pin LQFP	1	0	0.8 A	DC-DC	by SPI	0	0	
MC33FS6502CAE	–40 °C		0	1	0.8 A	DC-DC	by SPI	1	0	
MC33FS6502LAE	to		0	1	0.8 A	DC-DC	by SPI	1	1	[1] [2
MC33FS6502NAE	125 °C	expected pad	0	1	0.8 A	DC-DC	by SPI	0	0	
MC33FS6503CAE			1	1	0.8 A	DC-DC	by SPI	1	0	
MC33FS6503NAE			1	1	0.8 A	DC-DC	by SPI	0	0	
MC33FS6504LAE			0	1	0.8 A	DC-DC	by default	1	1	
MC33FS6510CAE			0	0	1.5 A	DC-DC	by SPI	1	0	
MC33FS6510LAE	-		0	0	1.5 A	DC-DC	by SPI	1	1	
MC33FS6510NAE	1		0	0	1.5 A	DC-DC	by SPI	0	0	
MC33FS6511CAE			1	0	1.5 A	DC-DC	by SPI	1	0	
MC33FS6511NAE			1	0	1.5 A	DC-DC	by SPI	0	0	1
MC33FS6512CAE			0	1	1.5 A	DC-DC	by SPI	1	0	
MC33FS6512LAE			0	1	1.5 A	DC-DC	by SPI	1	1	1
MC33FS6512NAE			0	1	1.5 A	DC-DC	by SPI	0	0	
MC33FS6513CAE			1	1	1.5 A	DC-DC	by SPI	1	0	1
MC33FS6513NAE			1	1	1.5 A	DC-DC	by SPI	0	0	1
MC33FS6514LAE			0	1	1.5 A	DC-DC	by default	1	1	1
MC33FS6520CAE			0	0	2.2 A	DC-DC	by SPI	1	0	

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# FS6500, FS4500

## Safety power system basis chip with CAN FD and LIN transceivers

Part Number	Temperature (T <sub>A</sub> )	Package	FS1B	LDT	VCORE	VCORE type	VKAM on	CAN FD	LIN	Notes
MC33FS6520LAE			0	0	2.2 A	DC-DC	by SPI	1	1	
MC33FS6520NAE			0	0	2.2 A	DC-DC	by SPI	0	0	
MC33FS6521CAE	-		1	0	2.2 A	DC-DC	by SPI	1	0	
MC33FS6521NAE			1	0	2.2 A	DC-DC	by SPI	0	0	
MC33FS6522CAE	-		0	1	2.2 A	DC-DC	by SPI	1	0	
MC33FS6522LAE	-		0	1	2.2 A	DC-DC	by SPI	1	1	
MC33FS6522NAE			0	1	2.2 A	DC-DC	by SPI	0	0	
MC33FS6523CAE	1		1	1	2.2 A	DC-DC	by SPI	1	0	1
MC33FS6523NAE	1		1	1	2.2 A	DC-DC	by SPI	0	0	1

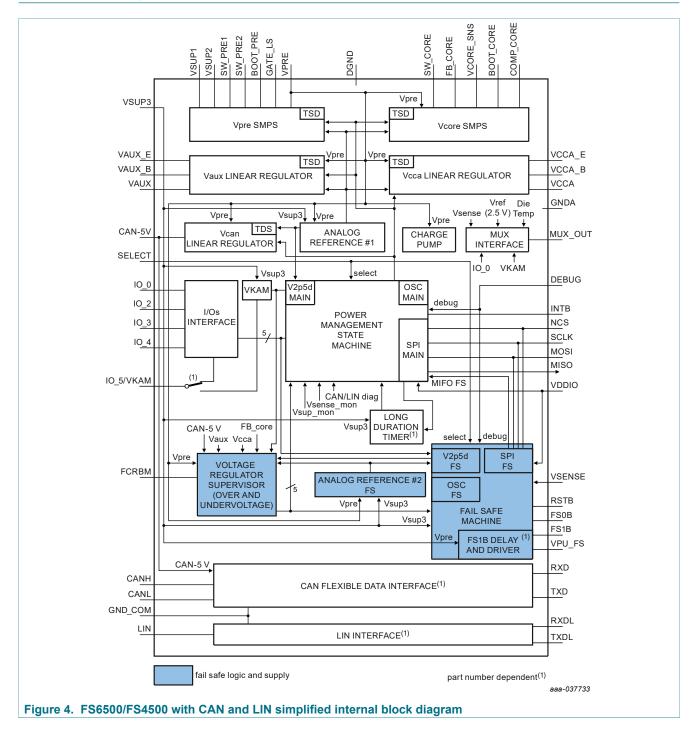
[1] To order parts in tape and reel, add the R2 suffix to the part number.

[2] LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, FS1B is not, and vice versa. VKAM on by default is available on certain part numbers only.

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#### Safety power system basis chip with CAN FD and LIN transceivers

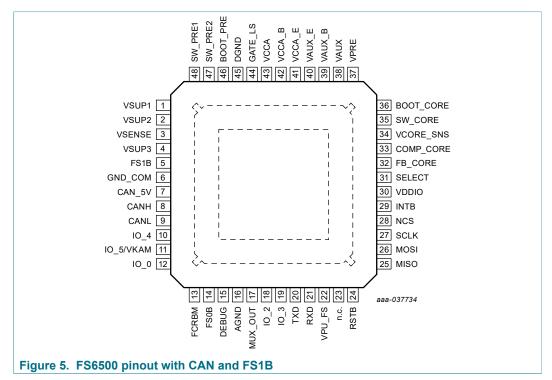
## 6 Block diagram

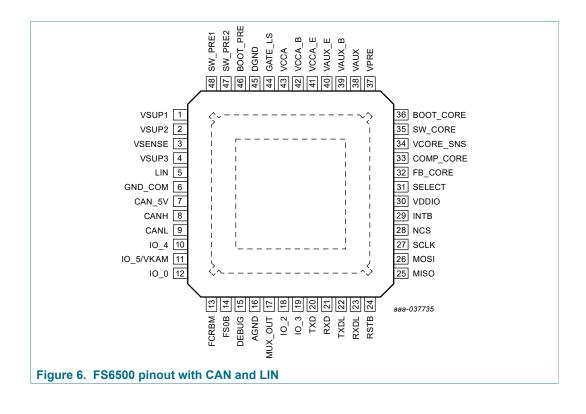


Safety power system basis chip with CAN FD and LIN transceivers

## 7 Pinning information

### 7.1 Pinning information

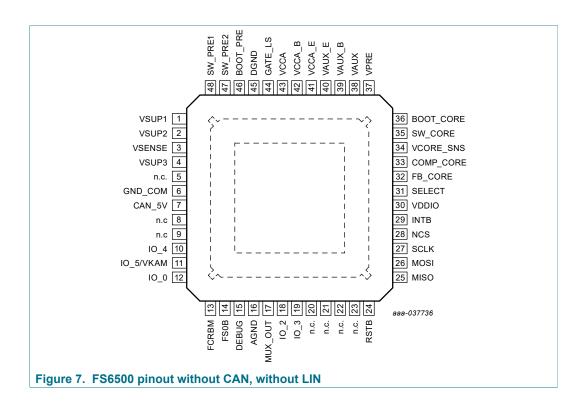


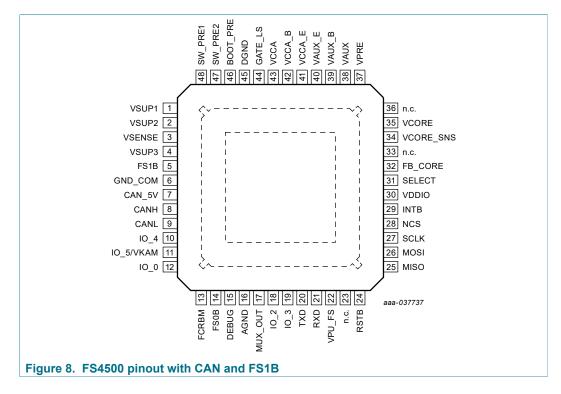


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# FS6500, FS4500

Safety power system basis chip with CAN FD and LIN transceivers





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## Safety power system basis chip with CAN FD and LIN transceivers

### 7.2 Pin description

A functional description of each pin can be found in the full data sheet.

Pin	Pin name	00 pin definiti Type	Definition
number		.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
1	VSUP1	A_IN	Power supply of the device. An external reverse battery protection diode in series is mandatory
2	VSUP2	A_IN	Second power supply. Protected by the external reverse battery protection diode used for VSUP1. VSUP1 and VSUP2 must be connected together externally.
3	VSENSE	A_IN	Sensing of the battery voltage. Must be connected prior to the reverse battery protection diode.
4	VSUP3	A_IN	Third power supply dedicated to the device supply. Protected by the external reverse battery protection diode used for VSUP1. Must be connected between the reverse protection diode and the input PI filter.
5	LIN	A_IN/OUT	LIN single-wire bus transmitter and receiver.
	or FS1B	D_OUT	Second output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected, with a configurable delay or duration versus FS0B output terminal. Open drain structure.
			exclusive. The differentiation is made by part numbers. When LIN is available, FS1B ther LIN, nor FS1B functions are used, this pin must be left open.
6	GND_COM	GROUND	Dedicated ground for physical layers
7	CAN_5V	A_OUT	Output voltage for the embedded CAN FD interface
8	CANH	A_IN/OUT	CAN output high. If CAN function is not used, this pin must be left open.
9	CANL	A_IN/OUT	CAN output low. If CAN function is not used, this pin must be left open.
10	IO_4	D_IN A_OUT	Can be used as digital input (load dump proof) with wake-up capability or as an output gate driver <b>Digital input</b> : Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_5). <b>Wake-up capability:</b> Can be selectable to wake-up on edges or levels. <b>Output gate driver:</b> Can drive a logic level low-side NMOS transistor. Controlled by the SPI.
11	IO_5/VKAM	A_IN D_IN A_OUT	Can be used as digital input with wake-up capability or as an analog output providing keep alive memory supply in low-power mode. Analog input: Pin status can be read through the MUX output terminal Digital input: Pin status can be read through the SPI. Can be used to monitor error signals from another IC for safety purposes (when used with IO_4). Wake-up capability: Can be selectable to wake-up on edges or levels. Supply output: Provide keep alive memory supply in low-power mode
	VKAM can be	e enabled or di	sabled by default at power up. The differentiation is made by part numbers.
12	IO_0	A_IN D_IN	Can be used as analog or digital input (load dump proof) with wake-up capability (selectable) <b>Analog input</b> : Pin status can be read through the MUX output terminal <b>Digital input</b> : Pin status can be read through the SPI. <b>Wake-up capability:</b> Can be selectable to wake-up on edges or levels.

### Table 3. FS6500/FS4500 pin definition

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# FS6500, FS4500

# Safety power system basis chip with CAN FD and LIN transceivers

Image: Second	Pin number	Pin name	Туре	Definition
When a fault condition is detected. Open drain structure.           15         DEBUG         D_IN         Debug mode entry input           16         AGND         GROUND         Analog ground connection           17         MUX_OUT         A_OUT         Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI.           18         IO_2:3         D_IN         Digital input pin with wake-up capability (logic level compatible)           19         D_2:3         D_IN         Digital input pin with wake-up capability (logic level compatible)           19         D_2:3         D_IN         Transceiver input from the MCU which controls the state of the CAN-bus. Internal pull-up to VDDIO.           20         TXD         D_OUT         Receiver output which reports the state of the CAN-bus to the MCU if CAN function is not used, this pin must be left open.           21         RXD         D_OUT         Receiver output which reports the state of the LIN bus. Internal pull-to VDDIO.           22         TXDL         D_IN         Transceiver input from the MCU controlling the state of the LIN bus. Internal pull-to VDDIO.           23         RXDL         D_OUT         Receiver output which reports the state of the LIN bus. Internal pull-to VDDIO.           24         MSO         D_OUT         Receiver output the STS function.           25	13	FCRBM	A_IN	parallel to the one used to set the V <sub>CORE</sub> voltage). If not used, this pin must be
16       AGND       GROUND       Analog ground connection         17       MUX_OUT       A_OUT       Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI.         18       IO_2:3       D_IN       Digital input pin with wake-up capability (logic level compatible)         19       Digital input pin with wake-up capability: Can be selectable to wake-up on edges or levels.         20       TXD       D_IN       Transceiver input from the MCU which controls the state of the CAN-bus. Interna pull-up to VDDIO.         21       RXD       D_OUT       Transceiver output which reports the state of the CAN-bus to the MCU if CAN function is not used, this pin must be left open.         22       TXDL       D_IN       Transceiver output from the MCU controlling the state of the LIN bus. Internal pull-to VDDIO.         21       RXD       D_OUT       Receiver output for the MCU controlling the state of the LIN bus. Internal pull-to VDIO.         22       TXDL       D_IN       Transceiver output for the MCU controlling the state of the LIN bus. Internal pull-to VDIO.         23       RXDL       D_OUT       Pull-up output for FS1B function.         24       RSTB       D_OUT       Receiver output reporting the state of the LIN bus to the MCU.         25       MISO       D_OUT       Receiver output reporting the state of the LIN bus to the MCU.	14	FS0B	D_OUT	First output of the safety block (active low). The pin is asserted low at start-up and when a fault condition is detected. Open drain structure.
17       MUX_OUT       A_OUT       Multiplexed output to be connected to a MCU ADC. Selection of the analog parameter is available at MUX-OUT through the SPI.         18       IO_2:3       D_IN       Digital input pin with wake-up capability (logic level compatible) Digital input pin status can be read through the SPI. Can be used to monitor FCCU error signals from MCU for safety purposes. Wake-up or edges or levels.         20       TXD       D_IN       Transceiver input from the MCU which controls the state of the CAN-bus. Interna pull-up to VDDIO. If CAN function is not used, this pin must be left open.         21       RXD       D_OUT       Receiver output which reports the state of the CAN-bus to the MCU if CAN function is not used, this pin must be left open.         22       TXDL       D_IN       Transceiver input from the MCU controlling the state of the LIN bus. Internal pull-to VDDIO. or VPU_FS         23       TXDL       D_IN       Transceiver input for the MCU controlling the state of the LIN bus. Internal pull-to VDDIO.         24       MO       D_OUT       Receiver output which reports the state of the LIN bus. Internal pull-to VDDIO.         25       A_OUT       Pull-up output for FS1B function.         26       NCN or FS1B functions are used, this pin must be left open.         27       RSDL       D_OUT       Receiver output reporting the state of the LIN bus to the MCU. If LIN function is not used, this pin must be left open.         28       MCD	15	DEBUG	D_IN	Debug mode entry input
Image: Section of the sectin sectin section of the section of the section of the	16	AGND	GROUND	Analog ground connection
19     Image: Second Seco	17	MUX_OUT	A_OUT	
pull-up to VDDIO. If CAN function is not used, this pin must be left open.21RXDD_OUTReceiver output which reports the state of the CAN-bus to the MCU If CAN function is not used, this pin must be left open.22XZDLD_INTransceiver input from the MCU controlling the state of the LIN bus. Internal pull- to VDU_FSA_OUTPull-up output for FS1B function.LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, FS 		IO_2:3	D_IN	<b>Digital input</b> : Pin status can be read through the SPI. Can be used to monitor FCCU error signals from MCU for safety purposes.
Image: Constraint of the constra	20	TXD	D_IN	
or VPU_FSA_OUTPull-up output for FS1B function.LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, FS is not, and vice versa.23RXDLD_OUTRSTBD_OUTReceiver output reporting the state of the LIN bus to the MCU. If LIN function is not used, this pin must be left open.24RSTBD_OUTThis output is asserted low when the safety block reports a failure. The main function is to reset the MCU. Reset input voltage is also monitored in order to det external reset and fault condition. Open drain structure.25MISOD_OUTSPI bus. Master output slave output26MOSID_INSPI bus. Serial clock27SCLKD_INSPI Bus. Serial clock28NCSD_INNot chip select (active low)29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage feedback. Input of the error amplifier.31SELECTD_INVCORE voltage feedback. Input of the error amplifier.32COMP_ COREA_INVCORE input voltage sense	21	RXD	D_OUT	
LIN and FS1B functions are exclusive. The differentiation is made by part numbers. When LIN is available, FS is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open.23RXDLD_OUTReceiver output reporting the state of the LIN bus to the MCU. If LIN function is not used, this pin must be left open.24RSTBD_OUTThis output is asserted low when the safety block reports a failure. The main function is to reset the MCU. Reset input voltage is also monitored in order to det external reset and fault condition. Open drain structure.25MISOD_OUTSPI bus. Master input slave output26MOSID_INSPI bus. Master output slave input27SCLKD_INSPI Bus. Serial clock28NCSD_INNot chip select (active low)29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier. For FS4500 series, this pin must be left open (NC).34VCORE_A_INVCORE input voltage sense	22	TXDL	D_IN	Transceiver input from the MCU controlling the state of the LIN bus. Internal pull-up to VDDIO.
is not, and vice versa. If neither LIN, nor FS1B functions are used, this pin must be left open.23RXDLD_OUTReceiver output reporting the state of the LIN bus to the MCU. If LIN function is not used, this pin must be left open.24RSTBD_OUTThis output is asserted low when the safety block reports a failure. The main function is to reset the MCU. Reset input voltage is also monitored in order to det external reset and fault condition. Open drain structure.25MISOD_OUTSPI bus. Master input slave output26MOSID_INSPI bus. Master output slave input27SCLKD_INSPI Bus. Serial clock28NCSD_INNot chip select (active low)29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier.33COMP_ COREA_INVCORE input voltage sense		or VPU_FS	A_OUT	Pull-up output for FS1B function.
If LIN function is not used, this pin must be left open.24RSTBD_OUTThis output is asserted low when the safety block reports a failure. The main function is to reset the MCU. Reset input voltage is also monitored in order to det external reset and fault condition. Open drain structure.25MISOD_OUTSPI bus. Master input slave output26MOSID_INSPI bus. Master output slave input27SCLKD_INSPI Bus. Serial clock28NCSD_INNot chip select (active low)29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier.33COMP_ COREA_INVCORE input voltage sense		is not, and vi	ce versa.	
Image: Section is to reset the MCU. Reset input voltage is also monitored in order to det external reset and fault condition. Open drain structure.25MISOD_OUTSPI bus. Master input slave output26MOSID_INSPI bus. Master output slave input27SCLKD_INSPI Bus. Serial clock28NCSD_INNot chip select (active low)29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INVCORE voltage feedback. Input of the error amplifier.33COMP_ COREA_OUTCompensation network. Output of the error amplifier.34VCORE_A_INVCORE input voltage sense	23	RXDL	D_OUT	
26MOSID_INSPI bus. Master output slave input27SCLKD_INSPI Bus. Serial clock28NCSD_INNot chip select (active low)29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier.33COMP_ COREA_OUTCompensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).34VCORE_A_INVCORE input voltage sense	24	RSTB	D_OUT	function is to reset the MCU. Reset input voltage is also monitored in order to detect
27SCLKD_INSPI Bus. Serial clock28NCSD_INNot chip select (active low)29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier.33COMP_COREA_OUTCompensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).34VCORE_A_INVCORE input voltage sense	25	MISO	D_OUT	SPI bus. Master input slave output
NCSD_INNot chip select (active low)29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier.33COMP_ COREA_OUTCompensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).34VCORE_A_INVCORE input voltage sense	26	MOSI	D_IN	SPI bus. Master output slave input
29INTBD_OUTThis output pin generates a low pulse when an Interrupt condition occurs. Pulse duration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier.33COMP_ COREA_OUTCompensation network. Output of the error amplifier.34VCORE_A_INVCORE input voltage sense	27	SCLK	D_IN	SPI Bus. Serial clock
andandandduration is configurable. Internal pull-up to VDDIO.30VDDIOA_INInput voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier.33COMP_COREA_OUTCompensation network. Output of the error amplifier.34VCORE_A_INVCORE input voltage sense	28	NCS	D_IN	Not chip select (active low)
31SELECTD_INHardware selection pin for VAUX and VCCA output voltages32FB_COREA_INVCORE voltage feedback. Input of the error amplifier.33COMP_COREA_OUTCompensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).34VCORE_A_INVCORE input voltage sense	29	INTB	D_OUT	
32       FB_CORE       A_IN       VCORE voltage feedback. Input of the error amplifier.         33       COMP_ CORE       A_OUT       Compensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).         34       VCORE_       A_IN       VCORE input voltage sense	30	VDDIO	A_IN	Input voltage for MISO output buffer. Allows voltage compatibility with MCU I/Os.
33COMP_ COREA_OUTCompensation network. Output of the error amplifier. For FS4500 series, this pin must be left open (NC).34VCORE_A_INVCORE input voltage sense	31	SELECT	D_IN	Hardware selection pin for VAUX and VCCA output voltages
CORE     For FS4500 series, this pin must be left open (NC).       34     VCORE_     A_IN     VCORE input voltage sense	32	FB_CORE	A_IN	VCORE voltage feedback. Input of the error amplifier.
	33		A_OUT	
303	34	VCORE_ SNS	A_IN	VCORE input voltage sense

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### Safety power system basis chip with CAN FD and LIN transceivers

Pin number	Pin name	Туре	Definition
35	SW_CORE	A_OUT	VCORE output switching point for FS6500 series
	or VCORE	A_OUT	VCORE output voltage for FS4500 series
36	BOOT_ CORE	A_IN/OUT	Bootstrap capacitor for VCORE internal NMOS gate drive For FS4500 series, this pin must be left open (NC).
37	VPRE	A_IN	VPRE input voltage sense
38	VAUX	A_OUT	VAUX output voltage. External PNP ballast transistor. Collector connection
39	VAUX_B	A_OUT	VAUX voltage regulator. External PNP ballast transistor. Base connection
40	VAUX_E	A_OUT	VAUX voltage regulator. External PNP ballast transistor. Emitter connection
41	VCCA_E	A_OUT	VCCA voltage regulator. External PNP ballast transistor. Emitter connection
42	VCCA_B	A_OUT	VCCA voltage regulator. External PNP ballast transistor. Base connection
43	VCCA	A_OUT	VCCA output voltage. External PNP ballast transistor. Collector connection
44	GATE_LS	A_OUT	Low-side MOSFET gate drive for non-inverting buck-boost configuration
45	DGND	GROUND	Digital ground connection
46	BOOT_PRE	A_IN/OUT	Bootstrap capacitor for the VPRE internal NMOS gate drive
47	SW_PRE2	A_OUT	Second pre-regulator output switching point
48	SW_PRE1	A_OUT	First pre-regulator output switching point

# 8 Maximum ratings

#### Table 4. Maximum ratings

All voltages are with respect to ground, unless otherwise specified. Exceeding these ratings may cause a malfunction or permanent damage to the device.

Symbol	Ratings	Value	Unit	Notes
Electrical rati	ngs	l.	1	J
V <sub>SUP1/2/3</sub>	DC voltage at power supply pins	-1.0 to 40	V	[1]
V <sub>SENSE</sub>	DC voltage at battery sense pin (with ext R in series mandatory)	-14 to 40	V	
V <sub>SW1,2</sub>	DC voltage at SW_PRE1 and SW_PRE2 Pins	-1.0 to 40	V	
V <sub>PRE</sub>	DC voltage at VPRE Pin	-0.3 to 8	V	
V <sub>GATE_LS</sub>	DC voltage at Gate_LS pin	–0.3 to 8	V	
V <sub>BOOT_PRE</sub>	DC voltage at BOOT_PRE pin	-1.0 to 50	V	
V <sub>SW_CORE</sub>	DC voltage at SW_CORE pin	-1.0 to 8	V	
V <sub>CORE_SNS</sub>	DC voltage at VCORE_SNS pin	0.0 to 8	V	
V <sub>BOOT_CORE</sub>	DC voltage at BOOT_CORE pin	0.0 to 15	V	
V <sub>FB_CORE</sub>	DC voltage at FB_CORE pin	-0.3 to 2.5	V	
V <sub>COMP_CORE</sub>	DC voltage at COMP_CORE pin	-0.3 to 2.5	V	
V <sub>FCRBM</sub>	DC voltage at FCRBM pin	–0.3 to 8	V	
V <sub>AUX_B,E</sub>	DC voltage at VAUX_B, VAUX_E pins	-0.3 to 40	V	
V <sub>AUX</sub>	DC voltage at VAUX pin	-2.0 to 40	V	
V <sub>CCA_B,E</sub>	DC voltage at VCCA_B, VCCA_E pins	–0.3 to 8	V	

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# FS6500, FS4500

# Safety power system basis chip with CAN FD and LIN transceivers

Symbol	Ratings	Value	Unit	Notes
V <sub>CCA</sub>	DC voltage at VCCA pin	–0.3 to 8	V	
V <sub>DDIO</sub>	DC voltage at VDDIO pin	-0.3 to 8	V	
V <sub>CAN_5V</sub>	DC voltage on CAN_5V pin	-0.3 to 8	V	
V <sub>PU_FS</sub>	DC voltage at VPU_FS pin	-0.3 to 8	V	
V <sub>FSxB</sub>	DC voltage at FS0B, FS1B pins (with ext R in series mandatory)	-0.3 to 40	V	
V <sub>DEBUG</sub>	DC voltage at DEBUG pin	-0.3 to 40	V	
V <sub>IO_0,4</sub>	DC voltage at IO_0, IO_4 pins (with ext R in series mandatory)	-0.3 to 40	V	
V <sub>IO_5</sub>	DC voltage at IO_5 pin	-0.3 to 20	V	
V <sub>KAM</sub>	DC voltage at VKAM pin	-0.3 to 8	V	
V <sub>DIG</sub>	DC voltage at INTB, RSTB, MISO, MOSI, NCS, SCLK, MUX_OUT, RXD, TXD, RXDL, TXDL, IO_2, IO_3 pins	-0.3 to 8	V	
V <sub>SELECT</sub>	DC voltage at SELECT pin	-0.3 to 8	V	
V <sub>BUS_CAN</sub>	DC voltage on CANL, CANH pins	-27 to 40	V	
V <sub>BUS_LIN</sub>	DC voltage on LIN pin	-18 to 40	V	
I_lsense	V <sub>SENSE</sub> maximum current capability	-5.0 to 5.0	mA	
I_IO <sub>0, 4, 5</sub>	IOs maximum current capability (IO_0, IO_4, IO_5)	-5.0 to 5.0	mA	
ESD voltage		`	2	
Human body	model (JESD22/A114) <sup>(20)</sup> – 100 pF, 1.5 kΩ			
V <sub>ESD-HBM1</sub>	All pins	±2.0	kV	[2]
V <sub>ESD-HBM2</sub>	<ul> <li>VSUP1, 2, 3, VSENSE, VAUX, IO_0,4, FS0B, FS1B, DEBUG</li> </ul>	±4.0	kV	
V <sub>ESD-HBM3</sub>	CANH, CANL	±6.0	kV	
V <sub>ESD-HBM4</sub>	• LIN	±8.0	kV	
Charge devic	ce model (JESD22/C101) <sup>(21)</sup> :			
V <sub>ESD-CDM1</sub>	All pins	±500	V	
V <sub>ESD-CDM2</sub>	Corner pins	±750	V	
System level	ESD (gun test)			
	<ul> <li>VSUP1, 2, 3, VSENSE, VAUX, IO_0, 4, 5, FS0B, FS1B</li> </ul>			
V <sub>ESD-GUN1</sub>	330 $\Omega$ /150 pF unpowered according to IEC 61000-4-2: <sup>(17)</sup>	±8.0	kV	
V <sub>ESD-GUN2</sub>	330 $\Omega$ /150 pF unpowered according to OEM LIN, CAN, FlexRay Conformance	±8.0	kV	
V <sub>ESD-GUN3</sub>	2.0 k $\Omega$ /150 pF unpowered according to ISO 10605 <sup>(16)</sup>	±8.0	kV	
V <sub>ESD-GUN4</sub>	2.0 k $\Omega$ /330 pF powered according to ISO 10605 <sup>(16)</sup>	±8.0	kV	
	CANH, CANL			
V <sub>ESD-GUN5</sub>	330 $\Omega$ /150 pF unpowered according to IEC 61000-4-2:(17)	±15.0	kV	
V <sub>ESD-GUN6</sub>	330 $\Omega$ /150 pF unpowered according to OEM LIN, CAN, FlexRay Conformance	±12.0	kV	
V <sub>ESD-GUN7</sub>	2.0 k $\Omega$ /150 pF unpowered according to ISO 10605 <sup>(16)</sup>	±15.0	kV	
V <sub>ESD-GUN8</sub>	2.0 kΩ/330 pF powered according to ISO 10605 <sup>(16)</sup>	±12.0	kV	
	• LIN			
V <sub>ESD-GUN9</sub>	330 $\Omega$ /150 pF unpowered according to IEC 61000-4-2: <sup>(17)</sup>	±12.0	kV	
V <sub>ESD-GUN10</sub>	330 Ω/150 pF unpowered according to OEM LIN, CAN, FlexRay conformance	±12.0	kV	

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### Safety power system basis chip with CAN FD and LIN transceivers

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Symbol	Ratings	Value	Unit	Notes
V <sub>ESD-GUN11</sub>	2.0 k $\Omega$ /150 pF unpowered according to ISO 10605 <sup>(16)</sup>	±12.0	kV	
V <sub>ESD-GUN12</sub>	2.0 k $\Omega$ /330 pF powered according to ISO 10605 <sup>(16)</sup>	±12.0	kV	
Thermal ratin	gs		1	
T <sub>A</sub>	Ambient temperature	-40 to 125	°C	
TJ	Junction temperature	-40 to 150	°C	
T <sub>STG</sub>	Storage temperature	–55 to 150	°C	
Thermal resis	stance	l		
R <sub>0JA</sub>	Thermal resistance junction to ambient	30	°C/W	[3]
R <sub>0JCTOP</sub>	Thermal resistance junction to case top	23.8	°C/W	[4]
R <sub>0JCBOTTOM</sub>	Thermal resistance junction to case bottom	0.9	°C/W	[5]

All  $V_{SUPS}$  ( $V_{SUP1/2/3}$ ) must be connected to the same supply (Figure 1). Compared to AGND. [1]

[2] [3]

Per JEDEC JESD51- $6^{(18)}$  with the board (JESD51-7)<sup>(19)</sup> horizontal.

[4] Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC - 883 Method 1012.1)<sup>(22)</sup>

[5] Thermal resistance between the die and the solder pad on the bottom of the packaged based on simulation without any interface resistance.

#### Packaging 9

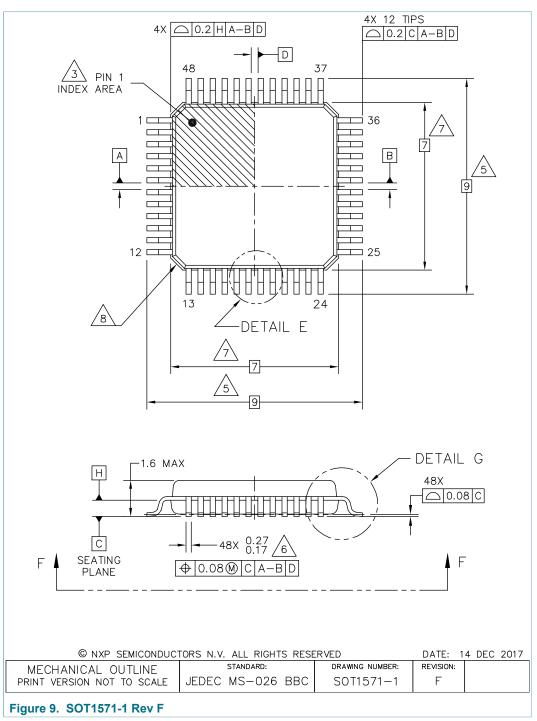
#### 9.1 Package mechanical dimensions

Package dimensions are provided in package drawings. To find the most current package outline drawing, go to www.nxp.com and perform a keyword search for the drawing's document number.

#### Table 5. Package mechanical dimensions

Package	Suffix	Package outline drawing number
7.0 × 7.0, 48–Pin LQFP exposed pad, with 0.5 mm pitch, and a 4.5 × 4.5 exposed pad	AE	98ASA00173D

### Safety power system basis chip with CAN FD and LIN transceivers

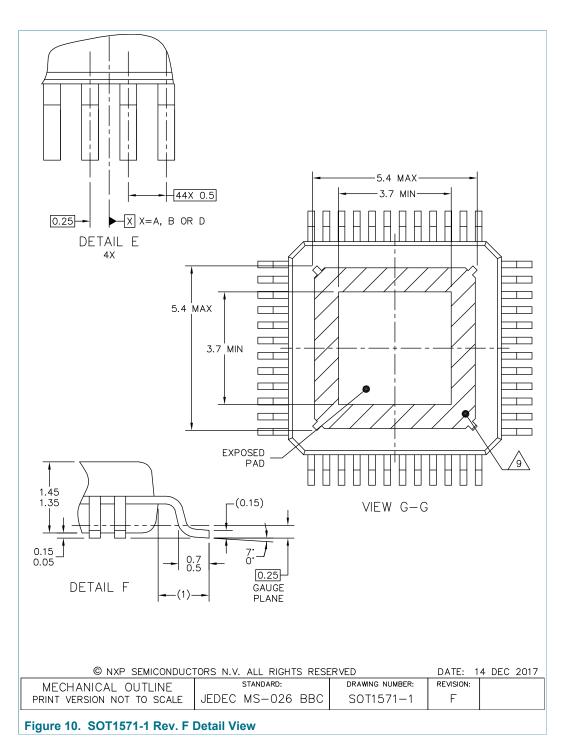


## 9.2 Package outline

FS6500-FS4500SDS

# FS6500, FS4500

Safety power system basis chip with CAN FD and LIN transceivers



#### Safety power system basis chip with CAN FD and LIN transceivers

NOTES:

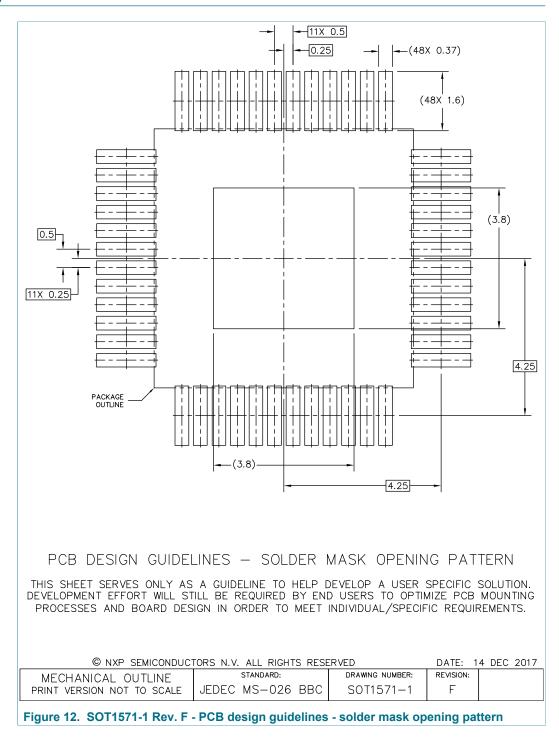
- 1. DIMENSIONS ARE IN MILLIMETERS.
- 2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
- $\sqrt{3}$ , PIN 1 FEATURE SHAPE, SIZE AND LOCATION MAY VARY.
- 4. DATUMS A, B AND D TO BE DETERMINED AT DATUM PLANE H.
- 5. DIMENSION TO BE DETERMINED AT SEATING PLANE C.
- THIS DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE UPPER LIMIT BY MORE THAN 0.08MM AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD SHALL NOT BE LESS THAN 0.07MM.
- A THIS DIMENSION DOES NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25MM PER SIDE. THIS DIMENSION IS MAXIMUM PLASTIC BODY SIZE DIMENSION INCLUDING MOLD MISMATCH.
- 8. EXACT SHAPE OF EACH CORNER IS OPTIONAL.
- A HATCHED AREA TO BE KEEP OUT ZONE FOR PCB ROUTING.

© NXP SEMICONDUCT	DATE: 1	4 DEC 2017		
MECHANICAL OUTLINE	STANDARD:	DRAWING NUMBER:	REVISION:	
PRINT VERSION NOT TO SCALE	JEDEC MS-026 BBC	SOT1571-1	F	

Figure 11. SOT1571-1 Rev F Notes

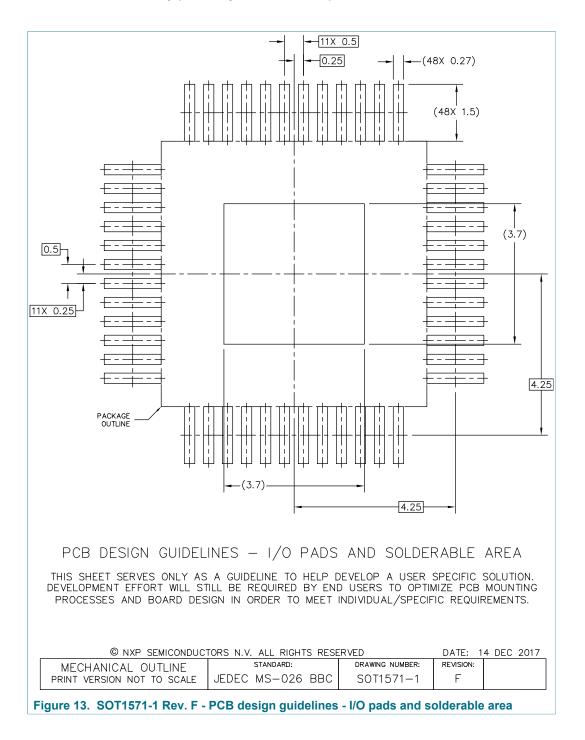
#### Safety power system basis chip with CAN FD and LIN transceivers

# **10 Soldering**



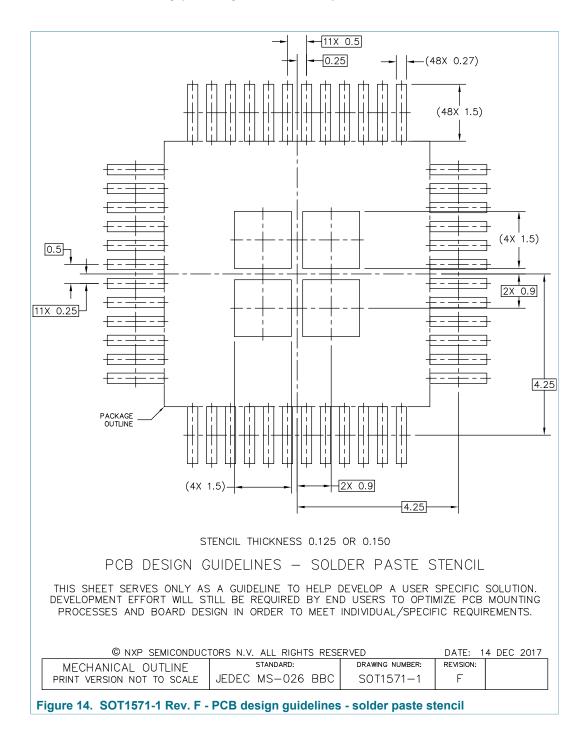
# FS6500, FS4500

#### Safety power system basis chip with CAN FD and LIN transceivers



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#### Safety power system basis chip with CAN FD and LIN transceivers



#### Safety power system basis chip with CAN FD and LIN transceivers

## **11 References**

Obtain additional information on related NXP products and application solutions through the documents and URLs listed below.

- (1) AN5238 FS6500 and FS4500 Safe System Basis Chip Hardware Design and Product Guidelines Application Note <u>https://www.nxp.com/AN5238-DOWNLOAD</u>
- (2) AN4388 Quad Flat Package (QFP) https://www.nxp.com/files/analog/doc/app\_note/AN4388.pdf
- (3) **FS6500-FS4500PDTCALC** Power dissipation tool (Excel File) <u>https://www.nxp.com/files/analog/software\_tools/FS6500-FS4500-power-dissipation-calculator.xlsx</u>
- (4) **V**<sub>CORE</sub> compensation network simulation tool (CNC)<sup>[1]</sup>
- (5) **FMEDA** FS6500/FS4500 FMEDA<sup>[1]</sup>
- (6) **FS6500-FS4500SMUG** FS6500/FS4500 Safety manual user guide https://www.docstore.nxp.com/products/product-hierarchy?query=Sm5509
- (7) KITFS6522LAEEVM FS6522, System Basis Chip, DC-DC 2.2 A Vcore LDT, CAN, LIN <u>http://www.nxp.com/KITFS6522LAEEVM</u>
- (8) KITFS6523CAEEVM FS6523, System Basis Chip, DC-DC 2.2A Vcore FS1B LDT CAN https://www.nxp.com/KITFS6523CAEEVM
- (9) **KITFS4503CAEEVM** FS4503, System Basis Chip, Linear 0.5 A Vcore, FS1b, LDT, CAN https://www.nxp.com/KITFS4503CAEEVM
- (10) FS6500 product summary page https://www.nxp.com/FS6500
- (11) FS4500 product summary page https://www.nxp.com/FS4500
- (12) Analog power management homepage https://www.nxp.com/products/power-management
- (13) **ISO 11898-2:2003** Road vehicles Controller area network (CAN) Part 2: High-speed medium access unit https://www.iso.org/standard/33423.html
- (14) **ISO 11898-5:2007** Road vehicles Controller area network (CAN) Part 5: High-speed medium access unit with low-power mode
  - https://www.iso.org/contents/data/standard/04/12/41284.html
- (15) ISO 7637-2:2011 Road vehicles Electrical disturbances from conduction and coupling Part 2: Electrical transient conduction along supply lines only <u>https://www.iso.org/standard/50925.html</u>
- (16) **ISO 10605:2008** Road vehicles Test methods for electrical disturbances from electrostatic discharge <u>https://www.iso.org/standard/41937.html</u>
- (17) IEC 61000-4-2:2008 Electromagnetic compatibility (EMC) Part 4-2: Testing and measurement techniques -Electrostatic discharge immunity test https://webstore.iec.ch/publication/4189
- (18) **JESD51-6** INTEGRATED CIRCUIT THERMAL TEST METHOD ENVIRONMENTAL CONDITIONS FORCED CONVECTION (MOVING AIR)
- (19) **JESD51-7** HIGH EFFECTIVE THERMAL CONDUCTIVITY TEST BOARD FOR LEADED SURFACE MOUNT PACKAGES
- (20) JESD22-A114F ELECTROSTATIC DISCHARGE (ESD) SENSITIVITY TESTING HUMAN BODY MODEL (HBM)

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#### Safety power system basis chip with CAN FD and LIN transceivers

- (21) **JESD22-C101F** FIELD-INDUCED CHARGED-DEVICE MODEL TEST METHOD FOR ELECTROSTATIC DISCHARGE WITHSTAND THRESHOLDS OF MICROELECTRONIC COMPONENTS
- (22) MIL-STD-883-1, Method 1012.1 TEST METHOD STANDARD MICROCIRCUITS
- (23) LIN Specification Package Revision 2.1:2006 https://www.lin-cia.org/fileadmin/microsites/lin-cia.org/resources/documents/LIN-Spec\_Pac2\_1.pdf
- (24) LIN Specification Package Revision 2.2A:2010 https://www.lin-cia.org/fileadmin/microsites/lin-cia.org/resources/documents/LIN\_2.2A.pdf
- (25) SAE J2602-2:201211 LIN Network for Vehicle Applications Conformance Test https://www.sae.org/standards/content/j2602/2\_201211/
- [1] Available upon request.

## **12 Revision history**

#### Table 6. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
FS6500-FS4500SDS v.7.0	20201111	Product data sheet	-	FS6500- FS4500SDS v.1.0
Modifications	<ul> <li>guidelines of NX company name</li> <li>Updated short de revision number</li> <li>Changed produce</li> <li>Global: Performe throughout the de</li> <li>Revised all image</li> <li><u>Section 1</u>, addee</li> <li><u>Section 2</u>, remove</li> <li><u>Section 9.2</u>, upd each drawing in</li> <li><u>Section 10</u>, addee</li> <li><u>Section 11</u>, Updae</li> </ul>	s data sheet has been redes P Semiconductors, N.V. Leg where appropriate. ata sheet revision number fr of the full data sheet. et status from "Advance infor ed minor grammar, punctuat ocument. les in Figures 1 through 7. d new paragraph beginning v ved the feature "36 V maxim ated the package outline ima Figure 9, Figure 10, and Fig ed new Soldering section an ated reference to FS6500-FS uide and added industry stat	yal texts have been a om v.1.0 to v.7.0 to mation" to "Product ion, and typographic with "High temperatu um input operating v ages and created se <u>ure 11</u> d <u>Figure 12</u> , <u>Figure</u> S4500SMUG - FS65	adapted to the new align with the short data sheet". cal changes ure capability" voltage". eparate figures for 13, and Figure 14. 500/FS4500 Safety
FS6500-FS4500SDS v.1.0	20171214	Data sheet: advance information	_	-
Modifications	Initial release			

#### Safety power system basis chip with CAN FD and LIN transceivers

# **13 Legal information**

### 13.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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