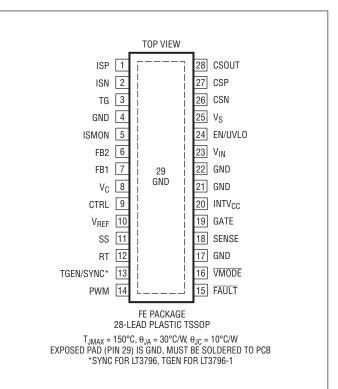
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### PIN CONFIGURATION



### **ORDER INFORMATION**

LEAD FREE FINISH	TAPE AND REEL	PART MARKING*	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LT3796EFE#PBF	LT3796EFE#TRPBF	LT3796FE	28-Lead Plastic TSSOP	-40°C to 125°C
LT3796IFE#PBF	LT3796IFE#TRPBF	LT3796FE	28-Lead Plastic TSSOP	-40°C to 125°C
LT3796HFE#PBF	LT3796HFE#TRPBF	LT3796FE	28-Lead Plastic TSSOP	-40°C to 150°C
LT3796EFE-1#PBF	LT3796EFE-1#TRPBF	LT3796FE-1	28-Lead Plastic TSSOP	-40°C to 125°C
LT3796IFE-1#PBF	LT3796IFE-1#TRPBF	LT3796FE-1	28-Lead Plastic TSSOP	-40°C to 125°C
LT3796HFE-1#PBF	LT3796HFE-1#TRPBF	LT3796FE-1	28-Lead Plastic TSSOP	-40°C to 150°C

Consult LTC Marketing for parts specified with wider operating temperature ranges. \*The temperature grade is identified by a label on the shipping container. Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/

For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/

**ELECTRICAL CHARACTERISTICS** The  $\bullet$  denotes the specifications which apply over the full operating temperature range, otherwise specifications are at T<sub>A</sub> = 25°C, V<sub>IN</sub> = 24V, EN/UVLO = 24V, CTRL = 2V, PWM = 5V, unless otherwise noted.

PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
V <sub>IN</sub> Minimum Operating Voltage	V <sub>IN</sub> Tied to INTV <sub>CC</sub>				6	V
$V_{IN}$ Shutdown IQ	EN/UVLO = 0V, PWM = 0V EN/UVLO = 1.15V, PWM = 0V				1 12	μΑ μΑ
V <sub>IN</sub> Operating I <sub>Q</sub> (Not Switching)	R <sub>T</sub> = 82.5k to GND, FB1 = 1.5V			2.5	3	mA
V <sub>REF</sub> Voltage	−100μA ≤ I <sub>REF</sub> ≤ 10μA	•	1.97	2.015	2.06	V
V <sub>REF</sub> Pin Line Regulation	6V < V <sub>IN</sub> < 100V			1.5		m%/V
V <sub>REF</sub> Pin Load Regulation	-100μA < I <sub>REF</sub> < 0μA			10		m%/µA
SENSE Current Limit Threshold			100	113	125	mV
SENSE Input Bias Current	Current Out of Pin			60		μA
SS Sourcing Current	SS = 0V			28		μA
SS Sinking Current	ISP – ISN = 1V, SS = 2V			2.8		μA
Error Amplifier						
Full Scale LED Current Sense Threshold (V <sub>(ISP-ISN)</sub> )	$\begin{split} \text{ISP} &= 48\text{V}, \text{CTRL} \geq 1.2\text{V} \\ \text{ISP} &= 0\text{V}, \text{CTRL} \geq 1.2\text{V} \end{split}$	•	243 243	250 250	257 257	mV mV
9/10th LED Current Sense Threshold (V <sub>(ISP-ISN)</sub> )	CTRL = 1V, ISP = 48V CTRL = 1V, ISP = 0V	•	220 220	225 225	230 230	mV mV
1/2 LED Current Sense Threshold (V <sub>(ISP-ISN)</sub> )	CTRL = 0.6V, ISP = 48V CTRL = 0.6V, ISP = 0V	•	119 119	125 125	131 131	mV mV
1/10th LED Current Sense Threshold (V <sub>(ISP-ISN)</sub> )	CTRL = 0.2V, ISP = 48V CTRL = 0.2V, ISP = 0V	•	16 16	25 25	32 32	mV mV
ISP/ISN Current Monitor Voltage (V <sub>ISMON</sub> )	$V_{(ISP-ISN)}$ = 250mV, ISP = 48V, –50 $\mu$ A < I_{ISMON} < 0 $\mu$ A $V_{(ISP-ISN)}$ = 250mV, ISP = 0V, –50 $\mu$ A < I_{ISMON} < 0 $\mu$ A	•	0.96 0.96	1 1	1.04 1.04	V V
$\begin{array}{l} \text{ISP/ISN Over Current Protection Threshold} \\ (V_{\text{(ISP-ISN)}}) \end{array}$	ISN = 48V ISN = 0V	•	360 360	375 375	390 390	mV mV
CTRL Input Bias Current	Current Out of Pin, CTRL = 1.2V			50	200	nA
ISP/ISN Current Sense Amplifier Input Common Mode Range			0		100	V
ISP/ISN Input Current Bias Current (Combined)	PWM = 5V (Active), ISP = 48V PWM = 0V (Standby), ISP = 48V			700 0	0.1	μΑ μΑ
ISP/ISN Current Sense Amplifier g <sub>m</sub>	$V_{(ISP-ISN)} = 250 mV$			400		μs
V <sub>C</sub> Output Impedance				2000		kΩ
V <sub>C</sub> Standby Input Bias Current	PWM = 0V		-20		20	nA
FB1, FB2 Regulation Voltage (V <sub>FB</sub> )	ISP = ISN = 48V ISP = ISN = 48V	•	1.230 1.238	1.250 1.250	1.270 1.264	V V
FB1 Amplifier g <sub>m</sub>			450	600	750	μS
FB2 Amplifier g <sub>m</sub>			130	170	210	μS
FB1, FB2 Pin Input Bias Current	$FB = V_{FB}$			100	200	nA
FB1 Open LED Threshold	VMODE Falling, ISP = ISN = 48V		V <sub>FB</sub> – 70mV	V <sub>FB</sub> – 60mV	V <sub>FB</sub> – 50mV	V
C/10 Comparator Threshold $(V_{(ISP-ISN)})$	<u>VMODE</u> Falling, FB1 = 1.25V, ISP = 48V VMODE Falling, FB1 = 1.25V, ISN = 0V			25 25		mV mV
FB1 Overvoltage Threshold	FAULT Falling		V <sub>FB</sub> + 35mV	V <sub>FB</sub> + 50mV	V <sub>FB</sub> + 60mV	V
FB2 Overvoltage Threshold	TG Rising		V <sub>FB</sub> + 35mV	V <sub>FB</sub> + 50mV	V <sub>FB</sub> + 60mV	V
V <sub>C</sub> Current Mode Gain ( $\Delta V_{VC}/\Delta V_{SENSE}$ )		1		4.2		V/V



**ELECTRICAL CHARACTERISTICS** The  $\bullet$  denotes the specifications which apply over the full operating temperature range, otherwise specifications are at T<sub>A</sub> = 25°C, V<sub>IN</sub> = 24V, EN/UVLO = 24V, CTRL = 2V, PWM = 5V, unless otherwise noted.

PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
Current Sense Amplifier (CSA)		I				
Power Supply Voltage Range (V <sub>S</sub> )			3		100	V
CSA Input Voltage Common Mode Range $(V_{CSP} \text{ and } V_{CSN})$		•	2.5		100	V
CSOUT Maximum Output Current					200	μA
Input Voltage Offset (V <sub>(CSP-CSN)</sub> )	V <sub>SNS</sub> = 100mV, V <sub>S</sub> = 48V (Note 5)		-3	0	3	mV
CSP, CSN Input Bias Current	$R_{IN1} = R_{IN2} = 1k$ (Note 5)			100		nA
CSP, CSN Input Current Offset	$R_{IN1} = R_{IN2} = 1k$ (Note 5)			0		nA
V <sub>S</sub> Supply Current	V <sub>S</sub> = 48V			80		μA
Input Step Response ( to 50% of Output Step)	$\Delta V_{\text{SENSE}} = 100 \text{mV}$ Step, $R_{\text{IN1}} = R_{\text{IN2}} = 1 \text{k}$ , $R_{\text{OUT}} = 5 \text{k}$			1		μs
Linear Regulator						
INTV <sub>CC</sub> Regulation Voltage			7.4	7.7	8	V
Dropout (V <sub>IN</sub> -INTV <sub>CC</sub> )	$I_{INTVCC} = -10$ mA, $V_{IN} = 6V$			400		mV
INTV <sub>CC</sub> Current Limit	$V_{IN} = 100V$ , INTV <sub>CC</sub> = 6V $V_{IN} = 12V$ , INTV <sub>CC</sub> = 6V		20 85			mA mA
INTV <sub>CC</sub> Shutdown Bias Current if Externally Driven to 7V	EN/UVLO = 0V, INTV <sub>CC</sub> = 7V			10		μA
INTV <sub>CC</sub> Undervoltage Lockout			3.8	4	4.1	V
INTV <sub>CC</sub> Undervoltage Lockout Hysteresis				150		mV
Oscillator						
Switching Frequency	$R_{T} = 82.5k$ $R_{T} = 19.6k$ $R_{T} = 6.65k$	•	85 340 900	105 400 1000	125 480 1150	kHz kHz kHz
Minimum Off-Time	(Note 6)			190		ns
Minimum On-Time	(Note 6)			210		ns
LOGIC Input/Outputs	1					1
PWM Input Threshold Rising			0.96	1	1.04	V
PWM Pin Bias Current				10		μA
EN/UVLO Threshold Voltage Falling		•	1.185	1.220	1.250	V
EN/UVLO Rising Hysteresis				20		mV
EN/UVLO Input Low Voltage	I <sub>VIN</sub> Drops Below 1µA		0.4			V
EN/UVLO Pin Bias Current Low	EN/UVLO = 1.15V		2.5	3	3.8	μA
EN/UVLO Pin Bias Current High	EN/UVLO = 1.30V			40	200	nA
VMODE OUTPUT Low	I <sub>VMODE</sub> = 0.5mA				300	mV
FAULT OUTPUT Low	I <sub>FAULT</sub> = 0.5mA				300	mV
SYNC Pin Resistance to GND	LT3796 Only			40		kΩ
SYNC Input Low Threshold	LT3796 Only		0.4			V
SYNC Input High Threshold	LT3796 Only				1.5	V
TGEN Pin Resistance to GND	LT3796-1 Only			40		kΩ
TGEN Input Low Threshold	LT3796-1 Only		0.4			V
TGEN Input High Threshold	LT3796-1 Only				1.5	V



**ELECTRICAL CHARACTERISTICS** The  $\bullet$  denotes the specifications which apply over the full operating temperature range, otherwise specifications are at T<sub>A</sub> = 25°C, V<sub>IN</sub> = 24V, EN/UVLO = 24V, CTRL = 2V, PWM = 5V, unless otherwise noted.

PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS
Gate Driver					<u>.</u>
t <sub>r</sub> NMOS GATE Driver Output Rise Time	C <sub>L</sub> = 3300pF, 10% to 90%		20		ns
t <sub>f</sub> NMOS GATE Driver Output Fall Time	C <sub>L</sub> = 3300pF, 10% to 90%		18		ns
NMOS GATE Output Low (V <sub>OL</sub> )				0.05	V
NMOS GATE Output High (V <sub>OH</sub> )		INTV <sub>CC</sub> – 0.05			V
t <sub>r</sub> Top GATE Driver Output Rise Time	C <sub>L</sub> = 300pF		50		ns
t <sub>f</sub> Top GATE Driver Output Fall Time	C <sub>L</sub> = 300pF		100		ns
Top Gate On Voltage (V <sub>ISP</sub> -V <sub>TG</sub> )	ISP = 48V		7	8	V
Top Gate Off Voltage ( $V_{ISP}$ - $V_{TG}$ )	PWM = 0V, ISP = 48V		0	0.3	V

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: Do not apply a positive or negative voltage source to TG and GATE pins, otherwise permanent damage may occur.

Note 3: Operating maximum for INTV<sub>CC</sub> is 8V.

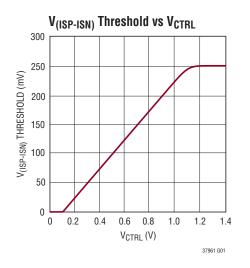
Note 4: The LT3796E and LT3796E-1 are guaranteed to meet specified performance from 0°C to 125°C. Specifications over the -40°C to 125°C operating temperature range are assured by design, characterization and correlation with statistical process controls. The LT3796I and LT3796I-1 are guaranteed to meet performance specifications over the -40°C to 125°C operating temperature range. The LT3796H and LT3796H-1 are guaranteed over the full -40°C to 150° C operating junction temperature range. High junction temperatures degrade operating lifetimes. Operating lifetime is derated at junction temperatures greater than 125°C.

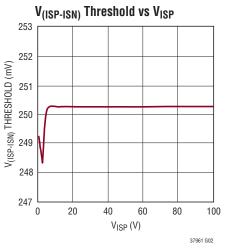
Note 5: Measured in servo. See Figure 9 for details.

**Note 6:** See Duty Cycle Considerations in the Applications Information section.



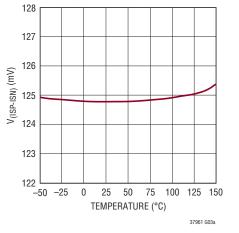
 $T_A = 25^{\circ}C$ , unless otherwise noted.

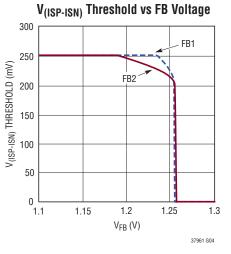




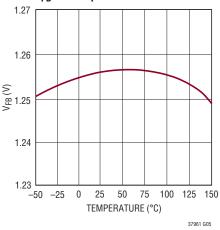
 $V_{\left(ISP\text{-}ISN\right)}$  Full-Scale Threshold vs Temperature 254 ISP = 48V CTRL = 2V 253 ISN) THRESHOLD (mV) 252 251 250 249 V(ISP-I 248 247 246 -25 25 50 75 100 -50 0 125 150 TEMPERATURE (°C) 37961 G03

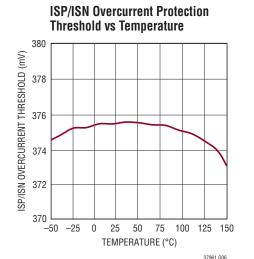
V<sub>(ISP-ISN)</sub> Threshold at CTRL = 0.6V vs Temperature



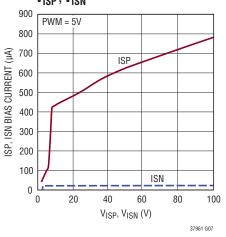


V<sub>FB</sub> vs Temperature

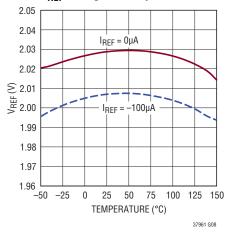




ISP/ISN Input Bias Current vs  $V_{ISP}$  ,  $V_{ISN}$ 



V<sub>REF</sub> Voltage vs Temperature

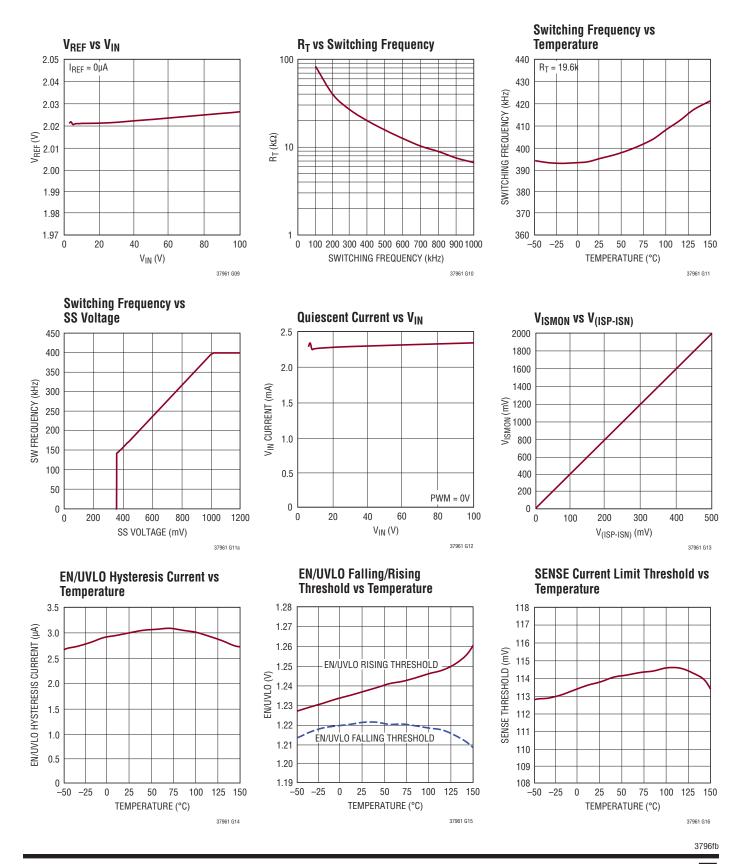






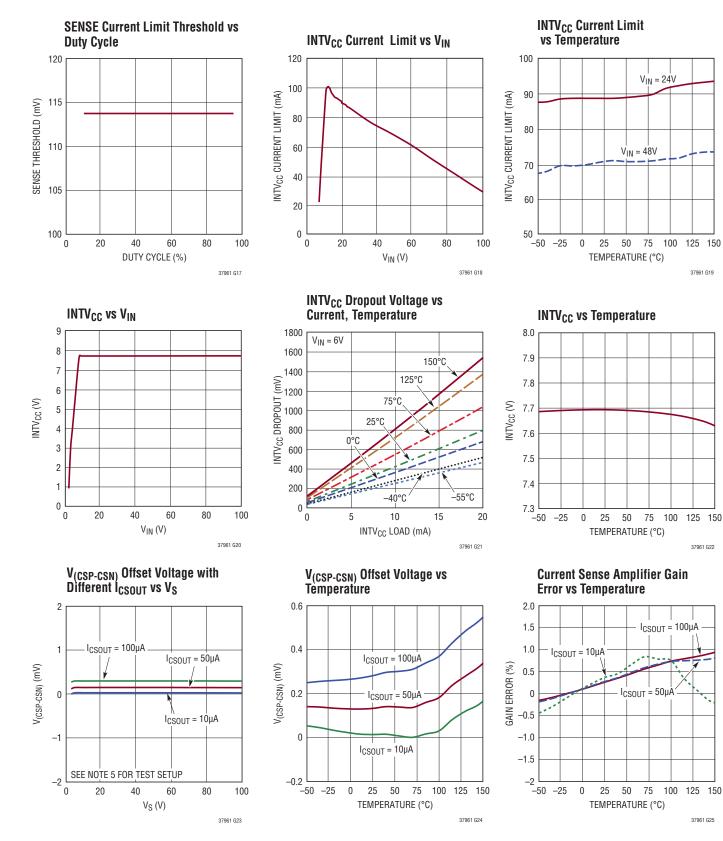


 $T_A = 25^{\circ}C$ , unless otherwise noted.



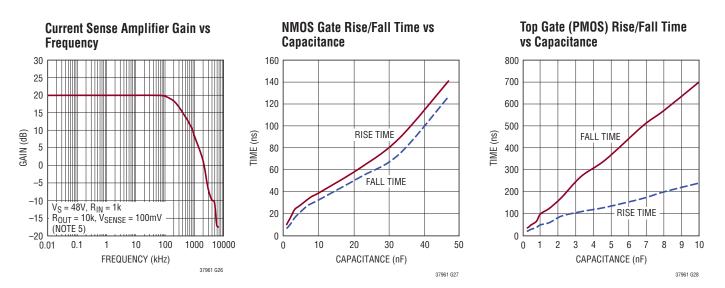


 $T_A = 25^{\circ}C$ , unless otherwise noted.

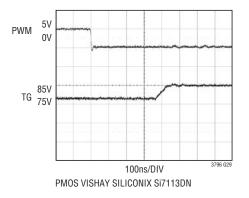




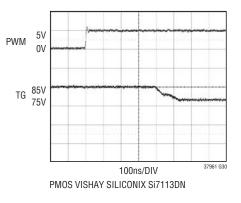
 $T_A = 25^{\circ}C$ , unless otherwise noted.



**Top Gate Driver Rising Edge** 



Top Gate Driver Falling Edge







### PIN FUNCTIONS

**ISP (Pin 1):** Connection Point for the Positive Terminal of the Current Feedback Resistor ( $R_{LED}$ ). Also serves as positive rail for TG pin driver.

**ISN (Pin 2):** Connection Point for the Negative Terminal of the Current Feedback Resistor (R<sub>LED</sub>).

**TG (Pin 3):** Top Gate Driver Output. An inverted PWM signal drives series PMOS device between  $V_{ISP}$  and  $(V_{ISP} - 7V)$  if  $V_{ISP} > 7V$ . An internal 7V clamp protects the PMOS gate by limiting VGS. Leave TG unconnected if not used.

**GND (Pins 4, 17, 21, 22, Exposed Pad Pin 29):** Ground. These pins also serve as current sense input for control loop, sensing negative terminal of current sense resistor in the source of the N-channel MOSFET. Solder the exposed pad directly to ground plane.

**ISMON (Pin 5):** ISP/ISN Current Report Pin. The LED current sensed by ISP/ISN inputs is reported as  $V_{ISMON} = I_{LED} \bullet R_{LED} \bullet 4$ . Leave ISMON pin unconnected if not used. When PWM is low, ISMON is driven to ground. Bypass with a 47nF capacitor or higher if needed.

**FB2 (Pin 6):** Voltage Loop Feedback 2 Pin. This pin is connected to the internal transconductance amplifier positive input node. The internal transconductance amplifier with output  $V_C$  regulates FB2 to 1.25V through the DC/DC converter. On LT3796 only, the FB2 has an additional feature. If FB2 is driven above 1.3V, the TG pin is pulled high to turn off the external PMOS and GATE pin is driven to GND to turn off the external N-channel MOSFET. Connect to GND if not used.

**FB1 (Pin 7):** Voltage Loop Feedback 1 Pin. FB1 is intended for constant-voltage regulation or for LED protection/open LED detection. The internal transconductance amplifier with output V<sub>C</sub> regulates FB1 to 1.25V (nominal) through the DC/DC converter. If the FB1 input is regulating the loop and V<sub>(ISP-ISN)</sub> is less than 25mV (normal), the VMODE pull-down is asserted. This action may signal an open LED fault. If FB1 is driven above the 1.3V (by an external power supply spike, for example), the FAULT pull-down is asserted, the GATE pin is pulled low to turn off the external N-channel MOSFET and the TG pin is driven high to protect the LEDs from an overcurrent event. Do not leave the FB1 pin open. If not used, connect FB1 to GND.  $V_C$  (Pin 8): Transconductance Error Amplifier Output Pin. Used to stabilize the control loop with an RC network. This pin is high impedance when PWM is low, a feature that stores the demand current state variable for the next PWM high transition. Connect a capacitor between this pin and GND; a resistor in series with the capacitor is recommended for fast transient response. Do not leave this pin open.

**CTRL (Pin 9):** Current Sense Threshold Adjustment Pin. Regulating threshold  $V_{(ISP-ISN)}$  is  $0.25 \cdot V_{CTRL}$  plus an offset for  $0.1V < V_{CTRL} < 1V$ . For  $V_{CTRL} > 1.2V$  the current sense threshold is constant at the full-scale value of 250mV. For  $1V < V_{CTRL} < 1.2V$ , the dependence of the current sense threshold upon  $V_{CTRL}$  transitions from a linear function to a constant value, reaching 98% of full-scale value by  $V_{CTRL} = 1.1V$ . Connect CTRL to  $V_{REF}$  for the 250mV default current threshold. Do not leave this pin open. Pull CTRL pin to GND for zero LED current.

 $V_{REF}$  (Pin 10): Voltage Reference Output Pin. Typically 2.015V. This pin drives a resistor divider for the CTRL pin, either for analog dimming or for temperature limit/ compensation of LED load. It can supply up to 100µA.

**SS (Pin 11):** Soft-Start Pin. This pin modulates oscillator frequency and compensation pin voltage ( $V_C$ ) clamp. The soft-start interval is set with an external capacitor. The pin has a 28µA (typical) pull-up current source to an internal 2.5V rail. This pin can be used as fault timer. Provided the SS pin has exceeded 1.7V, the pull-up current source is disabled and a 2.8µA pull-down current enabled when any one of the following fault conditions happen:

- 1. LED overcurrent
- 2. INTV<sub>CC</sub> undervoltage
- 3. Thermal limit

The SS pin must be discharged below 0.2V to reinitiate a soft-start cycle. Switching is disabled until SS is recharged.

**RT (Pin 12):** Switching Frequency Adjustment Pin. Set the frequency using a resistor to GND (for resistor values, see the Typical Performance curve or Table 2). Do not leave the RT pin open.



## PIN FUNCTIONS

**SYNC (Pin 13) LT3796:** The SYNC pin is used to synchronize the internal oscillator to an external logic level signal. If SYNC is used, the  $R_T$  resistor should be chosen to program an internal switching frequency 20% slower than the SYNC pulse frequency. Gate turn-on occurs a fixed delay after the rising edge of SYNC. Use a 50% duty cycle waveform to drive this pin. If not used, tie this pin to GND.

**TGEN (Pin 13) LT3796-1:** Top Gate Driver Enable Pin. TGEN signal low causes the TG pin to transition high and turn off a PMOS switch, independent of the PWM input. Unlike PWM, TGEN low does not put the switching regulator in an idle state. TGEN can be used in combination with TG and a PMOS switch to deactivate one of two output current regulation loops. Tie the TGEN pin to 1.5V or higher if its function is not used. There is an equivalent 90k resistor from TGEN to ground internally.

**PWM (Pin 14):** PWM Input Signal Pin. A signal low turns off switching, idles the oscillator, disconnects the  $V_C$  pin from all internal loads, and makes the TG pin high. There is an equivalent 500k resistor from PWM pin to GND internally. If not used, tie this pin to  $V_{REF}$ .

**FAULT (Pin 15):** An open-collector pull-down on FAULT asserts when any of the following conditions happen: 1. FB1 overvoltage ( $V_{FB1} > 1.3V$ ), 2. INTV<sub>CC</sub> undervoltage, 3. LED overcurrent ( $V_{(ISP-ISN)} > 375mV$ ), or 4. Thermal shutdown. If all faults are removed, FAULT flag returns high. Fault status is only updated during PWM high state and latched during PWM low state. FAULT remains asserted until the SS pin is discharged below 0.2V for cases 2, 3 and 4 above.

**WMODE** (Pin 16): An open-collector pull-down on VMODE asserts if the FB1 input is above 1.19V (typical), and  $V_{(ISP-ISN)}$  is less than 25mV (typical). To function, the pin requires an external pull-up resistor. VMODE status is updated only during PWM high state and latched during PWM low state.

**SENSE (Pin 18):** The current sense input for the control loop. Kelvin connect this pin to the positive terminal of the switch current sense resistor,  $R_{SENSE}$ , in the source of the N-channel MOSFET. The negative terminal of the

current sense resistor should be Kelvin connected to the GND plane of the IC.

**GATE (Pin 19):** N-Channel MOSFET Gate Driver Output. Switches between  $INTV_{CC}$  and GND. It is driven to GND during shutdown, fault or idle states.

**INTV<sub>CC</sub> (Pin 20):** Regulated Supply for Internal Loads, GATE Driver and Top Gate (PMOS) Driver. Supplied from V<sub>IN</sub> and regulates to 7.7V (typical). INTV<sub>CC</sub> must be bypassed with a 4.7 $\mu$ F capacitor placed close to the pin. Connect INTV<sub>CC</sub> directly to V<sub>IN</sub> if V<sub>IN</sub> is always less than or equal to 7V.

 $V_{IN}$  (Pin 23): Input Supply Pin. Must be locally bypassed with a 0.22µF (or larger) capacitor placed close to the IC.

**EN/UVLO (Pin 24):** Enable and Undervoltage Lockout Pin. An accurate 1.22V falling threshold with externally programmable hysteresis detects when power is OK to enable switching. Rising hysteresis is generated by the external resistor divider and an accurate internal  $3\mu$ A pull-down current. Above the threshold (but below 6V), EN/UVLO input bias current is sub- $\mu$ A. Below the falling threshold, a  $3\mu$ A pull-down current is enabled so the user can define the hysteresis with the external resistor selection. An undervoltage condition resets soft-start. Tie to 0.4V, or less, to disable the device and reduce V<sub>IN</sub> quiescent current below 1 $\mu$ A.

**V<sub>S</sub> (Pin 25):** Current Sense Amplifier Power Supply Pin. This pin supply current to the current sense amplifier and can operate from 3V to 100V.

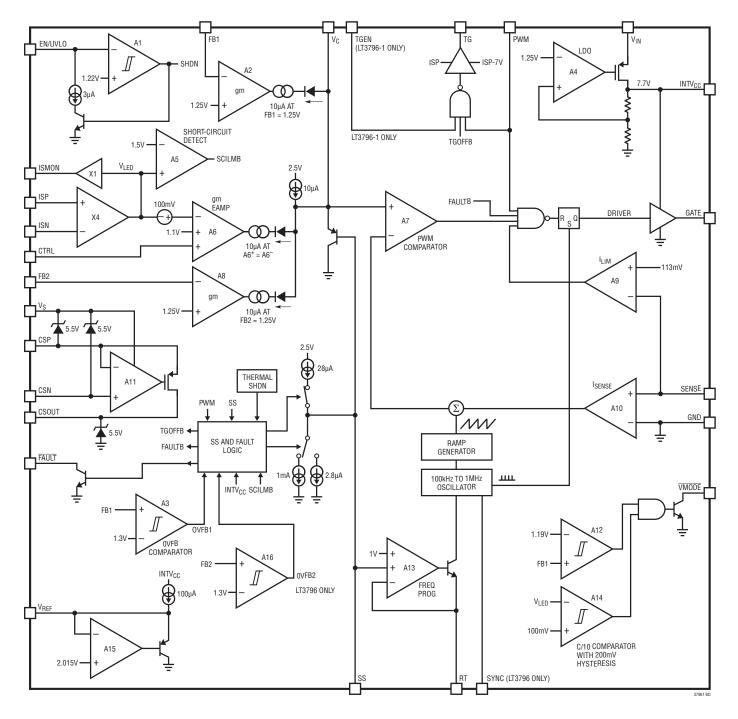
**CSN (Pin 26):** Negative Current Sense Input Terminal. CSN remains functional for voltages up to 100V. Typically connected to  $V_S$  and CSP as shown in Figure 9.

**CSP (Pin 27):** Positive Current Sense Input Terminal. The internal sense amplifier sinks current from CSP to regulate it to the same potential as CSN. A resistor ( $R_{IN1}$ ) tied from  $V_{IN}$  to CSP sets the output current  $I_{CSOUT} = V_{SNS}/R_{IN1}$ .  $V_{SNS}$  is the voltage developed across  $R_{SNS}$ . See Figure 9.

**CSOUT (Pin 28):** Current Sense Amplifier Output. CSOUT pin sources the current that is drawn from CSP. Typically is output to an external resistor to GND.



### **BLOCK DIAGRAM**



LT3796/LT3796-1 Block Diagram

### OPERATION

The LT3796/LT3796-1 are constant-frequency, current mode controllers with a low side NMOS gate driver. The operation of the LT3796/LT3796-1 is best understood by referring to the Block Diagram. In normal operation, with the PWM pin low, the GATE pin is driven to GND, the TG pin is pulled high to ISP to turn off the PMOS disconnect switch, the V<sub>C</sub> pin goes high impedance to store the previous switching state on the external compensation capacitor, and the ISP and ISN pin bias currents are reduced to leakage levels. When the PWM pin transitions high, the TG pin transitions low after a short delay. At the same time, the internal oscillator wakes up and generates a pulse to set the PWM latch, turning on the external power N-channel MOSFET switch (GATE goes high). A voltage input proportional to the switch current, sensed by an external current sense resistor between the SENSE and GND input pins, is added to a stabilizing slope compensation ramp and the resulting switch current sense signal is fed into the negative terminal of the PWM comparator. The current in the external inductor increases steadily during the time the switch is on. When the switch current sense voltage exceeds the output of the error amplifier, labeled V<sub>C</sub>, the latch is reset and the switch is turned off. During the switch off phase, the inductor current decreases. At the completion of each oscillator cycle, internal signals such as slope compensation return to their starting points and a new cycle begins with the set pulse from the oscillator. Through this repetitive action, the PWM control algorithm establishes a switch duty cycle to regulate a current or voltage in the load. The  $V_{\rm C}$  signal is integrated over many switching cycles and is an amplified version of the difference between the LED current sense voltage, measured between ISP and ISN, and the target difference voltage set by the CTRL pin. In this manner, the error amplifier sets the correct peak switch current level to keep the LED current in regulation. If the error amplifier output increases, more current is demanded in the switch; if it decreases, less current is demanded. The switch current is monitored during the on phase and the voltage across the SENSE pin is not allowed to exceed the current limit threshold of 113mV (typical). If the SENSE pin exceeds the current limit threshold, the SR latch is reset regardless of the output state of the PWM comparator. Likewise, any fault condition, i.e. FB1 overvoltage ( $V_{FB1} > 1.3V$ ), LED over current, or INTV<sub>CC</sub> undervoltage (INTV<sub>CC</sub> < 4V), the GATE pin is pulled down to GND immediately.

In voltage feedback mode, the operation is similar to that described above, except the voltage at the V<sub>C</sub> pin is set by the amplified difference of the internal reference of 1.25V (nominal) and the FB1 and FB2 pins. If FB1 and FB2 are both lower than the reference voltage, the switch current increases; if FB1 or FB2 is higher than the reference voltage, the switch demand current decreases. The LED current sense feedback interacts with the voltage feedback so that neither FB1 or FB2 exceeds the internal reference and the voltage between ISP and ISN does not exceed the threshold set by the CTRL pin. For accurate current or voltage regulation, it is necessary to be sure that under normal operating conditions, the appropriate loop is dominant. To deactivate the voltage loop entirely, FB1 and FB2 can be connected to GND. To deactivate the LED current loop entirely, the ISP and ISN should be tied together and the CTRL input tied to V<sub>RFF</sub>.

Two LED specific functions featured on the LT3796/LT3796-1 are controlled by the voltage feedback FB1 pin. First, when the FB1 pin exceeds a voltage 60mV lower (-5%) than the FB1 regulation voltage and  $V_{(ISP-ISN)}$  is less than 25mV (typical), the pull-down driver on the VMODE pin is activated. This function provides a status indicator that the load may be disconnected and the constant-voltage feedback loop is taking control of the switching regulator. When the FB1 pin exceeds the FB1 regulation voltage by 50mV (4% typical), the FAULT pin is activated.

LT3796/LT3796-1 feature a PMOS disconnect switch driver. The PMOS disconnect switch can be used to improve the PWM dimming ratio, and operate as fault protection as well. Once a fault condition is detected, the TG pin is pulled high to turnoff the PMOS switch. The action isolates the LED array from the power path, preventing excessive current from damaging the LEDs.

A standalone current sense amplifier is integrated in the LT3796/LT3796-1. It can work as input current limit or open LED protection. The detailed information can be found in the Application Information section.



#### $\ensuremath{\mathsf{INTV}_{\mathsf{CC}}}$ Regulator Bypassing and Operation

The INTV<sub>CC</sub> pin requires a capacitor for stable operation and to store the charge for the large GATE switching currents. Choose a 10V rated low ESR, X7R or X5R ceramic capacitor for best performance. A 4.7 $\mu$ F ceramic capacitor is adequate for many applications. Place the capacitor close to the IC to minimize the trace length to the INTV<sub>CC</sub> pin and also to the IC ground.

An internal current limit on the  $INTV_{CC}$  output protects the LT3796/LT3796-1 from excessive on-chip power dissipation. The minimum value of this current limit should be considered when choosing the switching N-channel MOSFET and the operating frequency.  $I_{INTVCC}$  can be calculated from the following equation:

 $I_{INTVCC} = Q_G \bullet f_{OSC}$ 

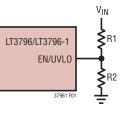
Careful choice of a lower Q<sub>G</sub> MOSFET allows higher switching frequencies, leading to smaller magnetics. The INTV<sub>CC</sub> pin has its own undervoltage disable (UVLO) set to 4V (typical) to protect the external FETs from excessive power dissipation caused by not being fully enhanced. If the INTV<sub>CC</sub> pin drops below the UVLO threshold, the GATE pin is forced to OV, TG pin is pulled high and the soft-start pin will be reset. If the input voltage, VIN, will not exceed 7V, then the  $INTV_{CC}$  pin should be connected to the input supply. Be aware that a small current (typically 10 $\mu$ A) loads the INTV<sub>CC</sub> in shutdown. If V<sub>IN</sub> is normally above, but occasionally drops below the INTV<sub>CC</sub> regulation voltage, then the minimum operating V<sub>IN</sub> is close to 6V. This value is determined by the dropout voltage of the linear regulator and the 4V INTV<sub>CC</sub> undervoltage lockout threshold mentioned above.

# Programming the Turn-On and Turn-Off Thresholds with the EN/UVLO Pin

The falling UVLO value can be accurately set by the resistor divider. A small  $3\mu$ A pull-down current is active when EN/UVLO is below the threshold. The purpose of this current

is to allow the user to program the rising hysteresis. The following equations should be used to determine the values of the resistors:

$$V_{IN(FALLING)} = 1.22 \bullet \frac{R1 + R2}{R2}$$
$$V_{IN(RISING)} = V_{IN(FALLING)} + 3\mu A \bullet R1$$





#### LED Current Programming

The LED current is programmed by placing an appropriate value current sense resistor  $R_{LED}$  between the ISP and ISN pins. Typically, sensing of the current should be done at the top of the LED string. If this option is not available, then the current may be sensed at the bottom of the string. The CTRL pin should be tied to a voltage higher than 1.2V to get the full-scale 250mV (typical) threshold across the sense resistor. The CTRL pin can also be used to dim the LED current to zero, although relative accuracy decreases with the decreasing voltage sense threshold. When the CTRL pin voltage is less than 1V, the LED current is:

$$I_{LED} = \frac{V_{CTRL} - 100mV}{R_{LED} \bullet 4}$$
,  $0.1V < V_{CTRL} \le 1V$ 

$$I_{LED} = 0, V_{CTRL} = 0V$$

When the CTRL pin voltage is between 1V and 1.2V, the LED current varies with CTRL, but departs from the previous equation by an increasing amount as the CTRL voltage increases. Ultimately above 1.2V, the LED current no



longer varies with CTRL. The typical  $V_{(\text{ISP-ISN})}$  threshold vs CTRL is listed in the Table 1.

V <sub>CTRL</sub> (V)	V <sub>(ISP-ISN)</sub> (mV)			
1	225			
1.05	236			
1.1	244.5			
1.15	248.5			
1.2	250			

Table 1. V<sub>(ISP-ISN)</sub> Threshold vs CTRL

When CTRL is higher than 1.2V, the LED current is regulated to:

$$I_{LED} = \frac{250 \text{mV}}{\text{R}_{LED}}$$

The CTRL pin should not be left open (tie to  $V_{REF}$  if not used). The CTRL pin can also be used in conjunction with a thermistor to provide overtemperature protection for the LED load, or with a resistor divider to  $V_{IN}$  to reduce output power and switching current when  $V_{IN}$  is low. The presence of a time varying differential voltage signal (ripple) across ISP and ISN at the switching frequency is expected. The amplitude of this signal is increased by high LED load current, low switching frequency and/or a smaller value output filter capacitor.

# Programming Output Voltage (Constant-Voltage Regulation) or Open LED/Overvoltage Threshold

The LT3796/LT3796-1 have two voltage feedback pins, FB1 and FB2. Either one can be used for a boost or SEPIC application. The difference between these two pins is FB1 has a comparator that senses when FB1 exceeds  $V_{FB} - 60mV$  (VMODE threshold) and asserts the VMODE output if  $V_{(ISP-ISN)}$  is less than 25mV. This indicates that the output is in voltage regulation mode and not current

regulation. FB2 does not have this extra comparator. The output voltage can be set by selecting the values of R3 and R4 (see Figure 2) according to the following equation:

$$V_{OUT} = 1.25 \bullet \frac{R3 + R4}{R4}$$

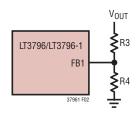


Figure 2. Feedback Resistor Connections for Boost and SEPIC Applications

For a boost type LED driver, set the resistor from the output to the FB1 pin such that the expected  $V_{FB1}$  during normal operation does not exceed 1.15V. For an LED driver of buck mode or a buck-boost mode configuration, the FB voltage is typically level shifted to a signal with respect to GND as illustrated in Figure 3. The output can be expressed as:

$$V_{OUT} = 1.25 \bullet \frac{R5}{R8} \bullet \frac{R6 + R7}{R6}$$
 for Figure 3a  
or  $V_{OUT} = 1.25 \bullet \frac{R9}{R10} + V_{BE(Q1)}$  for Figure 3b

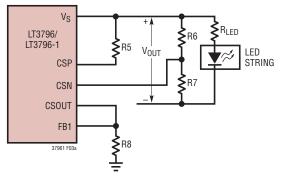


Figure 3a. Feedback Resistor Connection for Buck Mode or Buck-Boost Mode LED Driver



3796fl

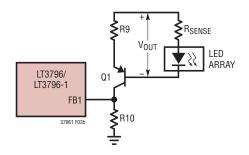


Figure 3b. Feedback Resistor Connection for Buck Mode or Buck-Boost Mode LED Driver Using External PNP

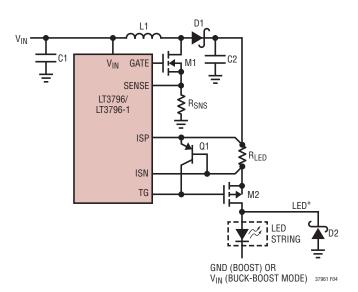
#### **Open LED Detection**

The LT3796/LT3796-1 provide an open-collector status pin, VMODE, that pulls low when the FB1 pin is above 1.19V and  $V_{(ISP-ISN)}$  is less than 25mV. If the open LED clamp voltage is programmed correctly using the resistor divider, then the FB1 pin should never exceed 1.15V when LEDs are connected, therefore, the only way for the FB1 pin to be within 60mV of the 1.25V regulation voltage is for an open LED event to have occurred.

#### **LED Over Current Protection Feature**

The ISP and ISN pins have a short-circuit protection feature independent of the LED current sense feature. This feature prevents the development of excessive switching currents and protects the power components. The short-circuit protection threshold (375mV, typ) is designed to be 50% higher than the default LED current sense threshold. Once the LED over current is detected, the GATE pin is driven to GND to stop switching, and TG pin is pulled high to disconnect the LED array from the power path.

A typical LED short-circuit protection scheme for boost or buck-boost mode converter is shown in Figure 4. The Schottky diode D2 should be put close to the drain of M2 on the board. It protects the LED<sup>+</sup> node from swinging well below ground when being shorted to ground through a long cable. Usually, the internal protection loop takes about 1µs to respond. Including PNP helper Q1 is recommended to limit the transient short-circuit current. With the PNP helper, the short-circuit current can be limited to 2A, whereas the short-circuit current can reach to 20A without the PNP helper as shown in Figure 5 and Figure 6 respectively. Refer to boost LED driver with output short-circuit protection and LED current monitor for the test schematic. Note that the impedance of the short-circuit cable affects the peak current.





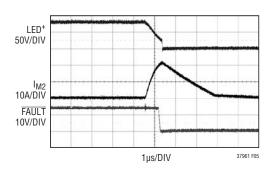


Figure 5. Short-circuit Current without PNP Helper



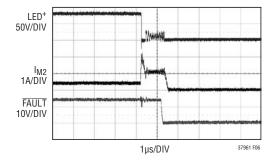


Figure 6. Short-circuit Current with PNP Helper

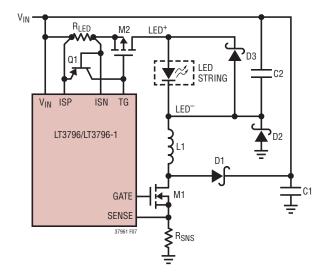


Figure 7. The Simplified LED Short-Circuit Protection Schematic for Buck Mode Converter

Similar to boost, Schottky diodes D2, D3 and PNP transistor Q1 are recommended to protect short-circuit event in the buck mode.

#### **PWM Dimming Control for Brightness**

There are two methods to control the LED current for dimming using the LT3796/LT3796-1. One method uses the CTRL pin to adjust the current regulated in the LEDs.

A second method uses the PWM pin to modulate the LED current between zero and full current to achieve a precisely programmed average current, without the possibility of color shift that occurs at low current in LEDs. To make PWM dimming more accurate, the switch demand current is stored on the V<sub>C</sub> node during the quiescent phase when PWM is low. This feature minimizes recovery time when the PWM signal goes high. To further improve the recovery time, a disconnect switch should be used in the LED current path to prevent the output capacitor from discharging during the PWM signal low phase. The minimum PWM on or off time depends on the choice of operating frequency through the RT input. For best current accuracy, the minimum PWM high time should be at least three switching cycles (3µs for f<sub>SW</sub> = 1MHz).

A low duty cycle PWM signal can cause excessive start-up times if it were allowed to interrupt the soft-start sequence. Therefore, once start-up is initiated by PWM > 1V, it will ignore a logical disable by the external PWM input signal. The device will continue to soft-start with switching and TG enabled until either the voltage at SS reaches the 1.0V level, or the output current reaches one-fourth of the full-scale current. At this point the device will begin following the dimming control as designated by PWM. If at any time an output overcurrent is detected, GATE and TG will be disabled even as SS continues to charge.

#### **Programming the Switching Frequency**

The RT frequency adjust pin allows the user to program the switching frequency from 100kHz to 1MHz to optimize efficiency/performance or external component size. Higher frequency operation yields smaller component size but increases switching losses and gate driving current, and may not allow sufficiently high or low duty cycle operation. Lower frequency operation gives better performance at the cost of larger external component size. For an appropriate



 $R_T$  resistor value see Table 2. An external resistor from the RT pin to GND is required—do not leave this pin open.

f <sub>osc</sub> (kHz)	R <sub>T</sub> (kΩ)		
1000	6.65		
900	7.50		
800	8.87		
700	10.2		
600	12.4		
500	15.4		
400	19.6		
300	26.1		
200	39.2		
100	82.5		
	*		

 Table 2. Typical Switching Frequency vs R<sub>T</sub> Value (1% Resistor)

#### **Frequency Synchronization**

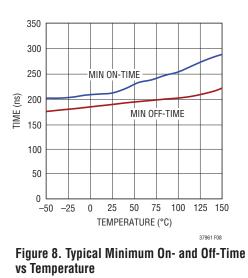
The LT3796 switching frequency can be synchronized to an external clock using the SYNC pin. For proper operation, the  $R_T$  resistor should be chosen for a switching frequency 20% lower than the external clock frequency. The SYNC pin is disabled during the soft-start period. Observation of the following guidelines about the SYNC waveform will ensure proper operation of this feature. Driving SYNC with a 50% duty cycle waveform is always a good choice, otherwise, maintain the duty cycle between 20% and 60%. When using both PWM and SYNC features, the PWM signal rising edge must have the aligned rising edges to achieve the optimized high PWM dimming ratio. If the SYNC pin is not used, it should be connected to GND.

#### **Duty Cycle Considerations**

Switching duty cycle is a key variable defining converter operation, therefore, its limits must be considered when programming the switching frequency for a particular application. The fixed minimum on-time and minimum off-time (see Figure 8) and the switching frequency define the minimum and maximum duty cycle of the switch, respectively. The following equations express the minimum/ maximum duty cycle:

Min Duty Cycle = minimum on-time • switching frequency

Max Duty Cycle = 1 - minimum off-time • switching frequency



When calculating the operating limits, the typical values for on/off-time in the data sheet should be increased by at least 100ns to allow margin for PWM control latitude, GATE rise/fall times and SW node rise/fall times.

#### Setting Input Current Limit

The LT3796/LT3796-1 have a standalone current sense amplifier. It can be used to limit the input current. As shown in Figure 9, the input current signal is converted to voltage output at CSOUT pin. When the CSOUT voltage exceeds FB2 regulation voltage, the GATE is pulled low, and the converter stops switching. The input current limit is calculated as follows:

$$I_{\rm IN} = 1.25 \bullet \frac{R_{\rm IN1}}{R_{\rm OUT} \bullet R_{\rm SNS}}$$



For buck applications, filter components,  $R_{IN2(OPT)}$  and  $C_{OPT}$ , are recommended to be placed close to LT3796/LT3796-1 to suppress the substantial transient signal or noise at across CSN and CSP pins. For boost and buckboost applications,  $R_{IN2(OPT)}$  and  $C_{OPT}$  are not required.

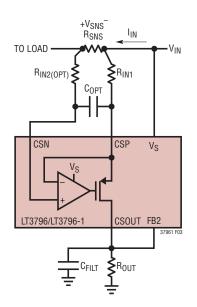


Figure 9. Setting Input Current Limit

#### **Thermal Considerations**

The LT3796/LT3796-1 are rated to a maximum input voltage of 100V. Careful attention must be paid to the internal power dissipation of the IC at higher input voltages to ensure that a junction temperature of 150°C is not exceeded. This junction limit is especially important when operating at high ambient temperatures. The majority of the power dissipation in the IC comes from the supply current needed to drive the gate capacitance of the external power N-channel MOSFET. This gate drive current can be calculated as:

$$I_{GATE} = f_{SW} \bullet Q_G$$

A low  $Q_G$  power MOSFET should always be used when operating at high input voltages, and the switching frequency should also be chosen carefully to ensure that the IC does not exceed a safe junction temperature. The internal junction temperature,  $T_J$  of the IC can be estimated by:

where T<sub>A</sub> is the ambient temperature, I<sub>Q</sub> is the V<sub>IN</sub> operating current of the part (2.5mA typical) and  $\theta_{JA}$  is the package thermal impedance (30°C/W for the TSSOP package). For example, an application with T<sub>A(MAX)</sub> = 85°C, V<sub>IN(MAX)</sub> = 60V, f<sub>SW</sub> = 400kHz, and having a N-channel MOSFET with Q<sub>G</sub> = 20nC, the maximum IC junction temperature will be approximately:

$$T_J = 85^{\circ}C + [60V \bullet (2.5mA + 400kHz \bullet 20nC) \bullet 30^{\circ}C/W]$$

≈ 104°C

The exposed pad on the bottom of the package must be soldered to a ground plane. This ground should then be connected to an internal copper ground plane with thermal vias placed directly under the package to spread out the heat dissipated by the IC.

It is best if the copper plane is extended on either the top or bottom layer of the PCB to have the maximum exposure to air. Internal ground layers do not dissipate thermals as much as top and bottom layer copper does. See recommended layout as an example.

#### **Input Capacitor Selection**

The input capacitor supplies the transient input current for the power inductor of the converter and must be placed and sized according to the transient current requirements. The switching frequency, output current and tolerable input voltage ripple are key inputs to estimating the capacitor value. An X7R type ceramic capacitor is usually the best choice since it has the least variation with temperature and DC bias. Typically, boost and SEPIC converters



require a lower value capacitor than a buck mode converter. Assuming that a 100mV input voltage ripple is acceptable, the required capacitor value for a boost converter can be estimated as follows ( $T_{SW} = 1/f_{OSC}$ ):

$$C_{IN}(\mu F) = I_{LED}(A) \bullet \frac{V_{LED}}{V_{IN}} \bullet T_{SW}(\mu s) \bullet \frac{1\mu F}{A \bullet \mu s \bullet 2.8}$$

Therefore, a  $2.2\mu$ F capacitor is an appropriate selection for a 400kHz boost regulator with 12V input, 48V output and 500mA load.

With the same  $V_{\text{IN}}$  voltage ripple of less than 100mV, the input capacitor for a buck converter can be estimated as follows:

$$C_{IN}(\mu F) = I_{LED}(A) \bullet \frac{V_{LED}(V_{IN} - V_{LED})}{V_{IN}^2} \bullet T_{SW}(\mu s) \bullet \frac{10\mu F}{A \bullet \mu s}$$

A  $10\mu$ F input capacitor is an appropriate selection for a 400kHz buck mode converter with 24V input, 12V output and 1A load.

In the buck mode configuration, the input capacitor has large pulsed currents due to the current returned through the Schottky diode when the switch is off. It is important to place the capacitor as close as possible to the Schottky diode and to the GND return of the switch (i.e., the sense resistor). It is also important to consider the ripple current rating of the capacitor. For best reliability, this capacitor should have low ESR and ESL and have an adequate ripple current rating. The RMS input current for a buck mode LED driver is:

$$I_{IN(RMS)} = I_{LED} \bullet \sqrt{(1-D)D}$$
  
 $D = \frac{V_{LED}}{V_{IN}}$ 

where D is the switch duty cycle.

MANUFACTURER	WEB
TDK	www.tdk.com
Kemet	www.kemet.com
Murata	www.murata.com
Taiyo Yuden	www.t-yuden.com
AVX	www.avx.com

#### **Output Capacitor Selection**

The selection of the output capacitor depends on the load and converter configuration, i.e., step-up or step-down and the operating frequency. For LED applications, the equivalent resistance of the LED is typically low and the output filter capacitor should be sized to attenuate the current ripple. Use of an X7R type ceramic capacitor is recommended.

To achieve the same LED ripple current, the required filter capacitor is larger in the boost and buck-boost mode applications than that in the buck mode applications. Lower operating frequencies will require proportionately higher capacitor values.

#### **Power MOSFET Selection**

For applications operating at high input or output voltages, the power N-channel MOSFET switch is typically chosen for drain voltage  $V_{DS}$  rating and low gate charge  $Q_G$ . Consideration of switch on-resistance,  $R_{DS(ON)}$ , is usually secondary because switching losses dominate power loss. The INTV<sub>CC</sub> regulator on the LT3796/LT3796-1 has a fixed current limit to protect the IC from excessive power dissipation at high  $V_{IN}$ , so the MOSFET should be chosen so that the product of  $Q_G$  at 7.7V and switching frequency does not exceed the INTV<sub>CC</sub> current limit. For driving LEDs be careful to choose a switch with a  $V_{DS}$  rating that exceeds the threshold set by the FB pin in case of an open load fault. Several MOSFET vendors are listed





in Table 4. The MOSFETs used in the application circuits in this data sheet have been found to work well with the LT3796/LT3796-1. Consult factory applications for other recommended MOSFETs.

VENDOR	WEB
Vishay Siliconix	www.vishay.com
Fairchild	www.fairchildsemi.com
International Rectifier	www.irf.com
Infineon	www.infineon.com

#### High Side PMOS Disconnect Switch Selection

A high side PMOS disconnect switch with a minimum  $V_{TH}$  of –1V to –2V is recommended in most LT3796/LT3796-1 applications to optimize or maximize the PWM dimming ratio and protect the LED string from excessive heating during fault conditions as well. The PMOS disconnect switch is typically selected for drain-source voltage  $V_{DS}$ , and continuous drain current  $I_D$ . For proper operations,  $V_{DS}$  rating must exceed the open LED regulation voltage set by the FB1 pin, and  $I_D$  rating should be above  $I_{LED}$ .

#### Schottky Rectifier Selection

The power Schottky diode conducts current during the interval when the switch is turned off. Select a diode rated for the maximum SW voltage. If using the PWM feature for dimming, it is important to consider diode leakage, which increases with the temperature, from the output during the PWM low interval. Therefore, choose the Schottky diode with sufficiently low leakage current. Table 5 has some recommended component vendors.

#### Table 5. Schottky Rectifier Manufacturers

VENDOR	WEB		
On Semiconductor	www.onsemi.com		
Diodes, Inc	www.diodes.com		
Central Semiconductor	www.centralsemi.com		
Rohm Semiconductor	www.rohm.com		

#### **Sense Resistor Selection**

The resistor, R<sub>SENSE</sub>, between the source of the external N-channel MOSFET and GND should be selected to provide adequate switch current to drive the application without exceeding the 113mV (typical) current limit threshold on the SENSE pin of LT3796/LT3796-1. For buck mode applications, select a resistor that gives a switch current at least 30% greater than the required LED current. For buck mode, select a resistor according to:

$$R_{\text{SENSE(BUCK)}} \leq \frac{0.07V}{I_{\text{LED}}}$$

For buck-boost mode, select a resistor according to:

$$R_{SENSE(BUCK-BOOST)} \leq \frac{V_{IN} \bullet 0.07V}{(V_{IN} + V_{LED})I_{LED}}$$

For boost, select a resistor according to:

$$R_{\text{SENSE(BOOST)}} \leq \frac{V_{\text{IN}} \bullet 0.07V}{V_{\text{LED}} \bullet I_{\text{LED}}}$$

The placement of  $R_{SENSE}$  should be close to the source of the NMOS FET and GND of the LT3796/LT3796-1. The SENSE input to LT3796/LT3796-1 should be a Kelvin connection to the positive terminal of  $R_{SENSE}$ .

70mV is used in the equations above to give some margin below the 113mV (typical) sense current limit threshold.

#### **Inductor Selection**

The inductor used with the LT3796/LT3796-1 should have a saturation current rating appropriate to the maximum switch current selected with the R<sub>SENSE</sub> resistor. Choose an inductor value based on operating frequency, input and output voltage to provide a current mode signal on SENSE



of approximately 20mV magnitude. The following equations are useful to estimate the inductor value ( $T_{SW} = 1/f_{OSC}$ ):

$$L_{BUCK} = \frac{T_{SW} \bullet R_{SENSE} \bullet V_{LED}(V_{IN} - V_{LED})}{V_{IN} \bullet 0.02V}$$
$$L_{BUCK, BOOST} = \frac{T_{SW} \bullet R_{SENSE} \bullet V_{LED} \bullet V_{IN}}{(V_{LED} + V_{IN}) \bullet 0.02V}$$

$$L_{BOOST} = \frac{T_{SW} \bullet R_{SENSE} \bullet V_{IN} (V_{LED} - V_{IN})}{V_{LED} \bullet 0.02V}$$

Table 6 provides some recommended inductor vendors.

VENDOR	WEB
Sumida	www.sumida.com
Würth Elektronik	www.we-online.com
Coiltronics	www.cooperet.com
Vishay	www.vishay.com
Coilcraft	www.coilcraft.com

#### Loop Compensation

The LT3796/LT3796-1 use an internal transconductance error amplifier whose  $V_C$  output compensates the control loop. The external inductor, output capacitor and the compensation resistor and capacitor determine the loop stability. The inductor and output capacitor are chosen based on performance, size and cost. The compensation resistor and capacitor at  $V_C$  are selected to optimize control loop response and stability. For typical LED applications, a 22nF compensation capacitor at  $V_C$  is adequate, and a series resistor should always be used to increase the slew rate on the  $V_C$  pin to maintain tighter regulation of LED current during fast transients on the input supply to the converter.

#### Soft-Start Capacitor Selection

For many applications, it is important to minimize the inrush current at start-up. The built-in soft-start circuit significantly reduces the start-up current spike and output voltage overshoot. The soft-start interval is set by the soft-start capacitor selection according to the equation:

$$T_{SS} = C_{SS} \bullet \frac{2V}{28\mu A}$$

A typical value for the soft-start capacitor is  $0.1\mu$ F. The soft-start pin reduces the oscillator frequency and the maximum current in the switch. Soft-start also operates as fault protection, which forces the converter into hiccup or latchoff mode. Detailed information is provided in the Fault Protection: Hiccup Mode and Latchoff Mode section.

#### Fault Protection: Hiccup Mode and Latchoff Mode

If an LED overcurrent condition,  $INTV_{CC}$  undervoltage, or thermal limit happens, an open-drain pull-down on FAULT asserts. The TG pin is pulled high to disconnect the LED array from the power path, and the GATE pin is driven low. If the soft-start pin is charging and still below 1.7V, then it will continue to do so with a 28µA source. Once above 1.7V, the pull-up source is disabled and a 2.8µA pull-down is activated. While the SS pin is discharging, the GATE is forced low. When SS pin is discharged below 0.2V, a new cycle is initiated. This is referred as hiccup mode operation. If the fault still exists when SS crosses below 0.2V, then a full SS charge/discharge cycle has to complete before switching is enabled and the FAULT flag is deasserted.

If a resistor is placed between  $V_{REF}$  pin and SS pin to hold SS pin higher than 0.2V during a fault, then the LT3796/ LT3796-1 will enter latchoff mode with GATE pin low, TG pin high and FAULT pin low. To exit latchoff mode, the EN/ UVLO pin must be toggled low to high.

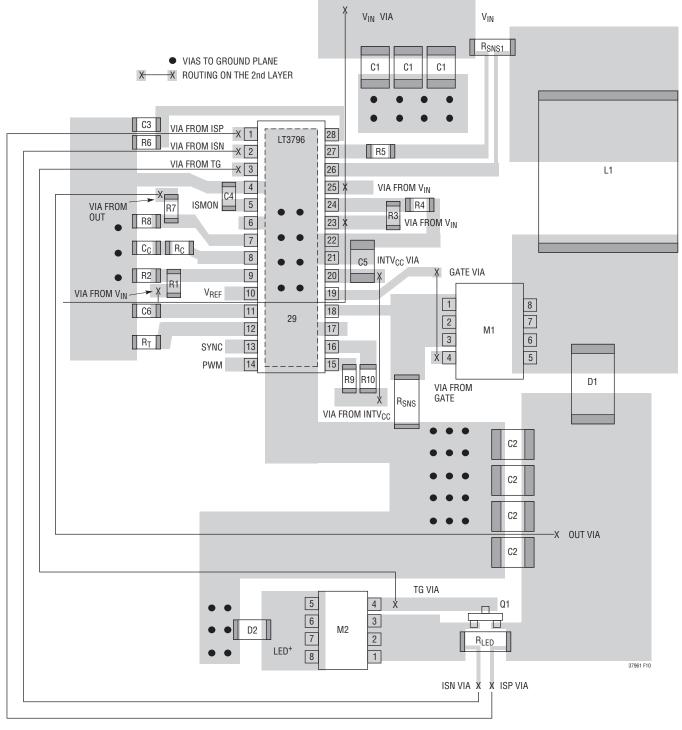


#### **Board Layout**

The high speed operation of the LT3796/LT3796-1 demands careful attention to board layout and component placement. The exposed pad of the package is the GND terminal of the IC and is also important for thermal management of the IC. It is crucial to achieve a good electrical and thermal contact between the exposed pad and the ground plane of the board. To reduce electromagnetic interference (EMI), it is important to minimize the area of the high dV/dt switching node between the inductor, switch drain and anode of the Schottky rectifier. Use a ground plane under the switching node to eliminate interplane coupling to sensitive signals. The lengths of the high dl/dt traces: 1) from the switch node through the switch and sense resistor to GND, and 2) from the switch node through the Schottky rectifier and filter capacitor to GND should be minimized. The ground points of these two switching current traces should come to a common point then connect to the ground plane under the LT3796/LT3796-1. Likewise, the ground terminal of the bypass capacitor for the INTV<sub>CC</sub> regulator should be placed near the GND of the switching path. Typically, this requirement results in the external switch being closest to the IC, along with the INTV<sub>CC</sub> bypass capacitor. The ground for the compensation network and other DC control signals should be star connected to the underside of the IC. Do not extensively route high impedance signals such as FB1, FB2, RT and V<sub>C</sub>, as they may pick up switching noise. Since there is a small variable DC input bias current to the ISN and ISP inputs, resistance in series with these pins should be minimized to avoid creating an offset in the current sense threshold. Likewise, minimize resistance in series with the SENSE input to avoid changes (most likely reduction) to the switch current limit threshold.

Figure 10 is a suggested two sided layout for a boost converter. Note that the 4-layer layout is recommended for best performance. Please contact the factory for the reference layout design.

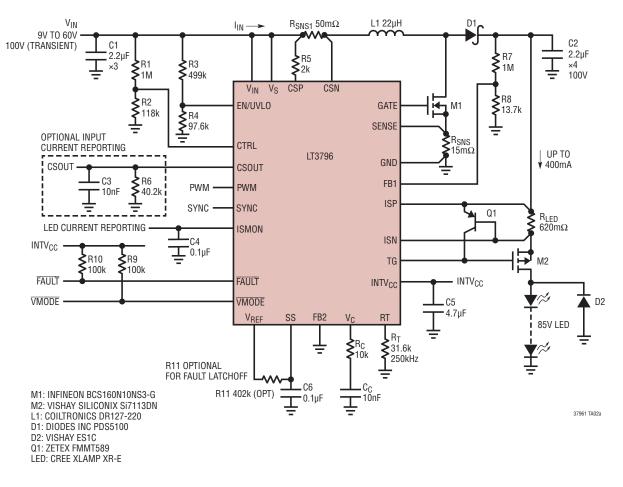




COMPONENT DESIGNATIONS REFER TO BOOST LED DRIVER WITH OUTPUT SHORT CIRCUIT PROTECTION AND LED CURRENT MONITOR

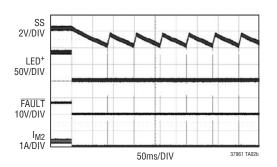
Figure 10. Boost Converter Suggested Layout



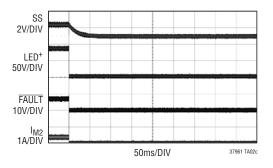


Boost LED Driver with Output Short Circuit Protection and LED Current Monitor

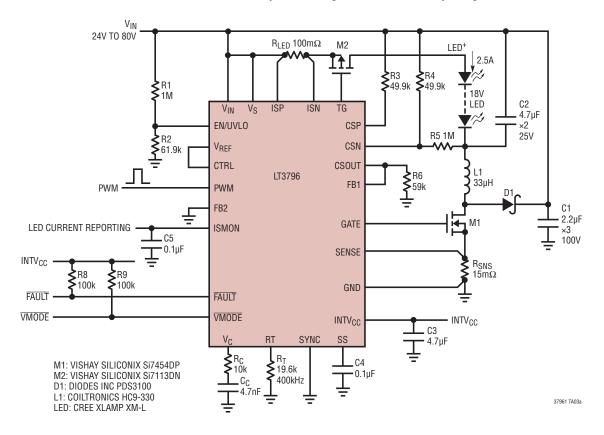
#### Fault (Short LED) Protection without R11: Hiccup Mode



Fault (Short LED) Protection with R11: Latchoff Mode

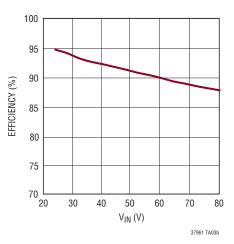






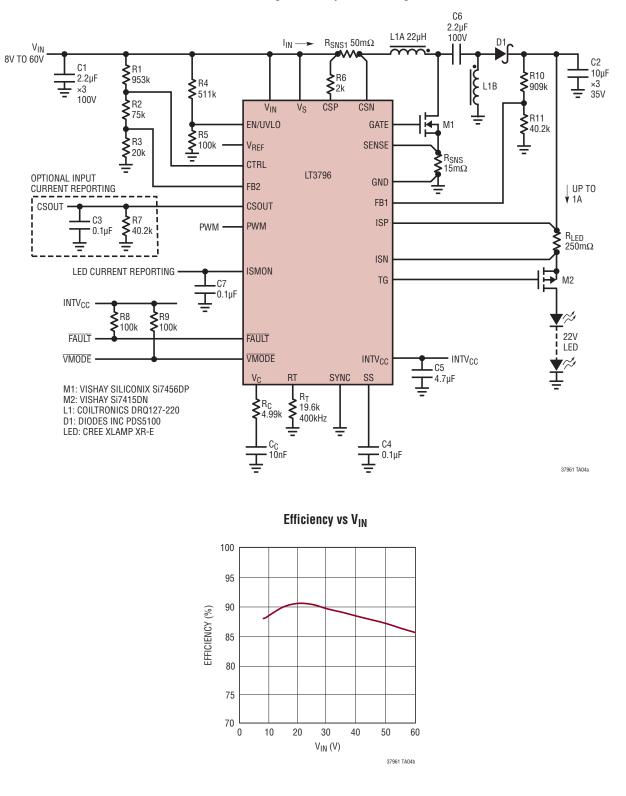
Buck Mode LED Driver with Open LED Flag and LED Current Reporting

Efficiency vs V<sub>IN</sub>



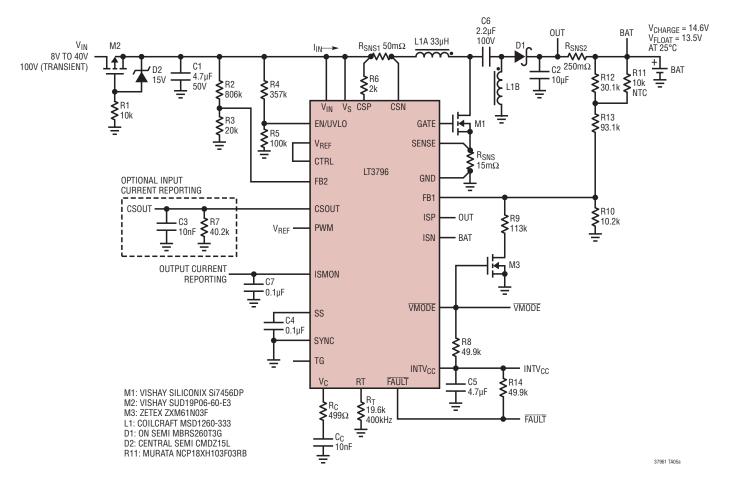






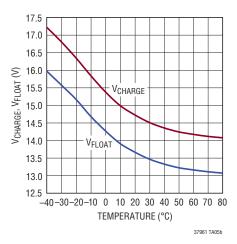
SEPIC LED Driver Using FB2 for Input Overvoltage Protection





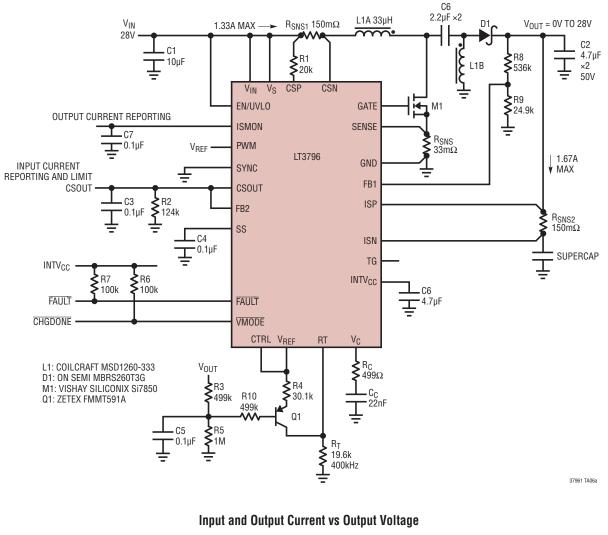
#### SEPIC Sealed Lead Acid (SLA) Battery Charger

 $V_{CHARGE}$ ,  $V_{FLOAT}$  vs Temperature

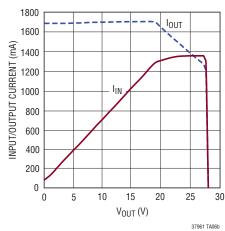






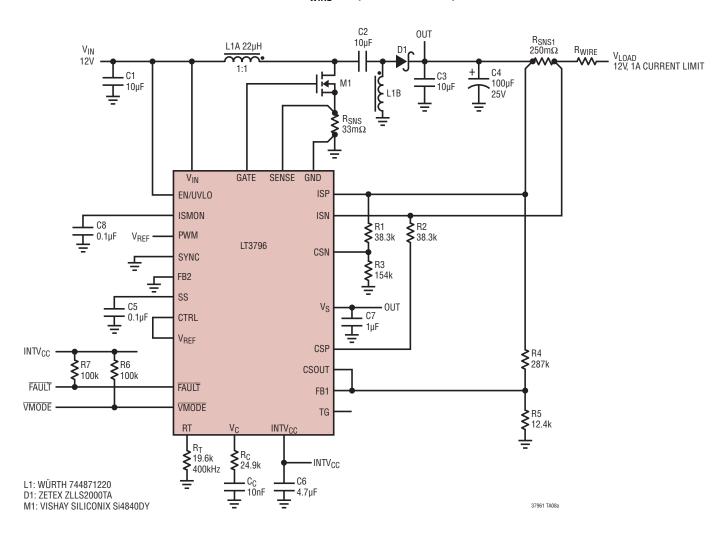


 $28V_{IN}$  to 28V SuperCap Charger with Input Current Limit and Charge Done Flag



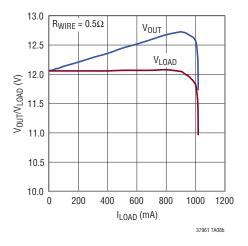




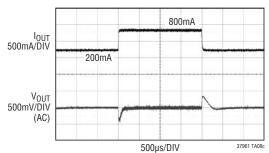


SEPIC Converter with  $\mathbf{R}_{\text{WIRE}}$  Compensation and Output Current Limit

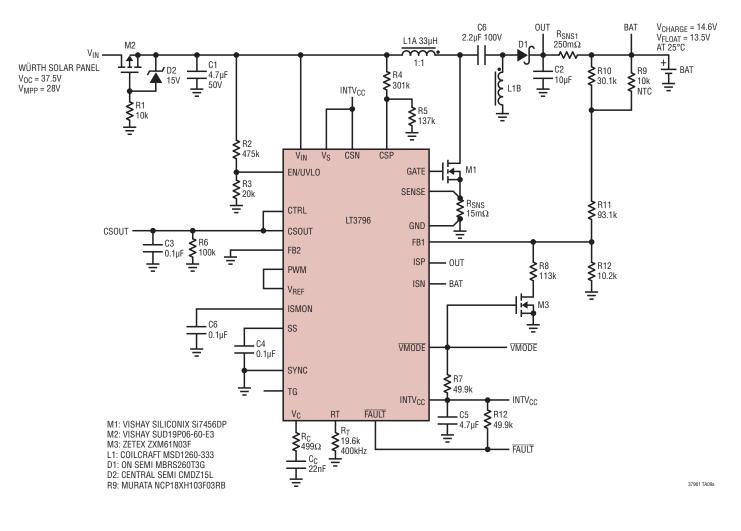
Line Impedance Compensation



#### Load Step Response

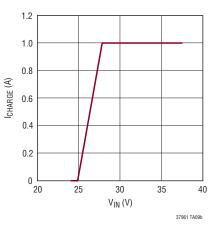




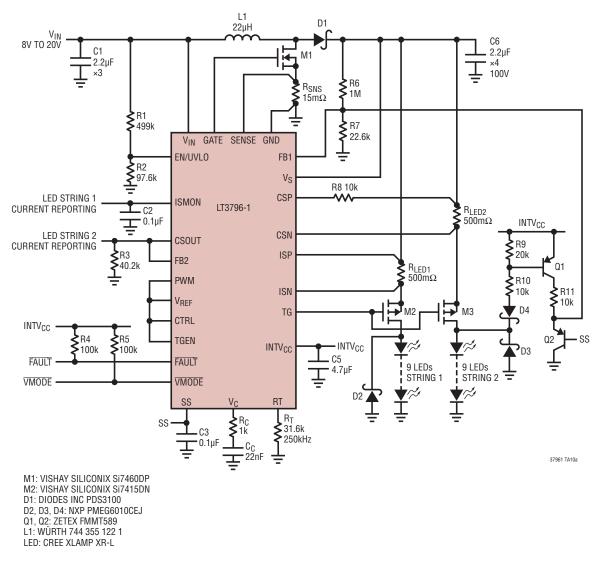


Solar Panel Driven SLA Battery Charger with Maximum Power Point Tracking

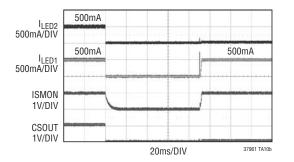






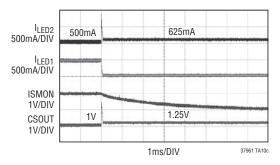


Boost LED Driver for Twin LEDs with Detection and Protection for Faulty LED

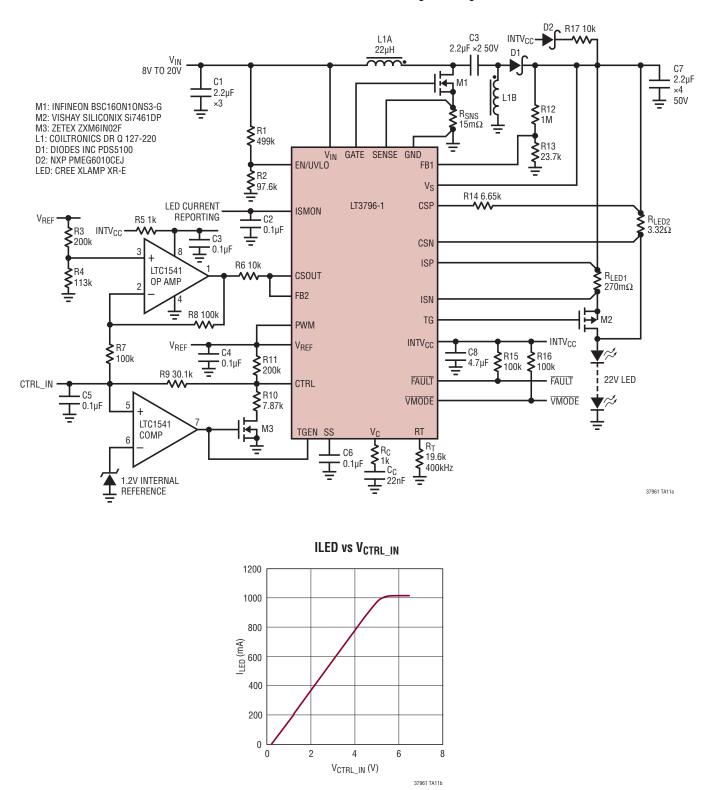


Short One LED from String 1

#### Short One LED from String 2





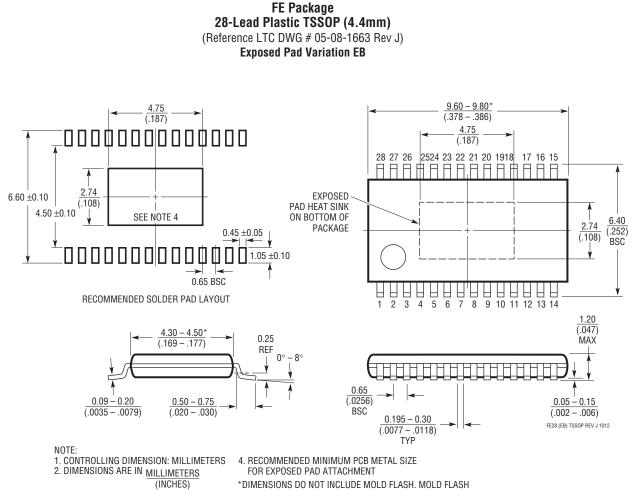


SEPIC LED Driver with 100:1 Analog Dimming



### PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.



3. DRAWING NOT TO SCALE

SHALL NOT EXCEED 0.150mm (.006") PER SIDE



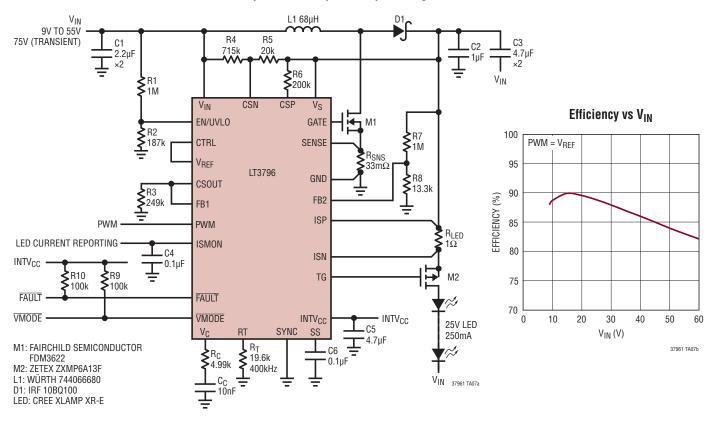


### **REVISION HISTORY**

REV	DATE	DESCRIPTION	PAGE NUMBER
Α	1/13	Added LT3796-1 option	1 to 36
В	3/14	Clarified Schematic	33



Buck-Boost Mode LED Driver with Open LED Clamp and Output Voltage Limit



### **RELATED PARTS**

PART NUMBER	DESCRIPTION	COMMENTS	
LT3755/LT3755-1 LT3755-2	High Side 60V, 1MHz LED Controller with True Color 3,000:1 PWM Dimming	$V_{IN}$ : 4.5V to 40V, $V_{OUT}$ Range: 5V to 60V, True Color PWM, Analog = 3000:1, $I_{SD}$ < 1µA, 3mm × 3mm QFN-16, MSOP-16E Packages	
LT3756/LT3756-1 LT3756-2	High Side 100V, 1MHz LED Controller with True Color 3,000:1 PWM Dimming	V <sub>IN</sub> : 6V to 100V, V <sub>OUT</sub> Range: 5V to 100V, True Color PWM, Analog = 3000:1, I <sub>SD</sub> < 1μA, 3mm × 3mm QFN-16, MSOP-16E Packages	
LT3743	Synchronous Step-Down 20A LED Driver with Three-State LED Current Control	$V_{\text{IN}}$ : 5.5V to 36V, $V_{\text{OUT}}$ Range: 5.5V to 35V, True Color PWM, Analog = 3000:1, $I_{\text{SD}}$ < 1µA, 4mm × 5mm QFN-28, TSSOP-28E Packages	
LT3791	60V, Synchronous Buck-Boost LED Driver Controller	r V <sub>IN</sub> : 4.7V to 60V, V <sub>OUT</sub> Range: 1.2V to 60V, True Color PWM, Analog, I <sub>SD</sub> < 1μA, TSSOP-38E Package	
LT3791-1	60V, Synchronous Buck-Boost Controller	V <sub>IN</sub> : 4.7V to 60V, V <sub>OUT</sub> Range: 1.2V to 60V, I <sub>SD</sub> < 1µA, TSSOP-38E Package	
LT3517	1.3A, 2.5MHz High Current LED Driver with 3,000:1 Dimming	V <sub>IN</sub> : 3V to 30V, True Color PWM, Analog = 3000:1, I <sub>SD</sub> < 1µA, 4mm × 4mm QFN-16 Package	
LT3518	2.3A, 2.5MHz High Current LED Driver with 3,000:1 Dimming	$V_{\text{IN}}$ : 3V to 30V, True Color PWM, Analog = 3000:1, $I_{\text{SD}}$ < 1µA, 4mm × 4mm QFN-16 Package	
LT3474/LT3474-1	36V, 1A (ILED), 2MHz, Step-Down LED Driver	V <sub>IN</sub> : 4V to 36V, V <sub>OUT</sub> Range = 13.5V, True Color PWM = 400:1, I <sub>SD</sub> < 1µA, TSSOP-16E Package	
LT3475/LT3475-1	Dual 1.5A(ILED), 36V, 2MHz, Step-Down LED Driver	V <sub>IN</sub> : 4V to 36V, V <sub>OUT</sub> Range = 13.5V, True Color PWM, Analog = 3000:1, I <sub>SD</sub> < 1µA, TSSOP-20E Package	

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