

AD744—SPECIFICATIONS (@ +25°C and ±15 V dc, unless otherwise noted)

Model	Conditions	AD744J/A/S			AD744K/B/T			Unit
INPUT OFFSET VOLTAGE ¹	Initial Offset		0.3	1.0		0.25	0.5	mV
	Offset	T _{MIN} to T _{MAX}		2			1.0	mV
	vs. Temp.		5	20		5	10	μV/°C
	vs. Supply ²	82	95		88	100		dB
	vs. Supply	T _{MIN} to T _{MAX}	82		88			dB
Long-Term Stability			15			15		μV/month
INPUT BIAS CURRENT ³	Either Input	V _{CM} = 0 V	30	100		30	100	pA
	Either Input @ T _{MAX} =	V _{CM} = 0 V						
	J, K	70°C	0.7	2.3		0.7	2.3	nA
	A, B, C	85°C	1.9	6.4		1.9	6.4	nA
	S, T	125°C	31	102		31	102	nA
	Either Input	V _{CM} = +10 V	40	150		40	150	pA
	Offset Current	V _{CM} = 0 V	20	50		10	50	pA
	Offset Current @ T _{MAX} =	V _{CM} = 0 V						
	J, K	70°C	0.4	1.1		0.2	1.1	nA
	A, B, C	85°C	1.3	3.2		0.6	3.2	nA
	S, T	125°C	20	52		10	52	nA
FREQUENCY RESPONSE	Gain BW, Small Signal	G = -1	8	13		9	13	MHz
	Full Power Response	V _O = 20 V p-p		1.2			1.2	MHz
	Slew Rate, Unity Gain	G = -1	45	75		50	75	V/μs
	Settling Time to 0.01% ⁴	G = -1		0.5		0.5	0.75	μs
	Total Harmonic Distortion	f = 1 kHz R _I ≥ 2 kΩ V _O = 3 V rms		0.0003			0.0003	%
INPUT IMPEDANCE	Differential		3 × 10 ¹² 5.5			3 × 10 ¹² 5.5		Ω pF
	Common Mode		3 × 10 ¹² 5.5			3 × 10 ¹² 5.5		Ω pF
INPUT VOLTAGE RANGE	Differential ⁵		±20			±20		V
	Common-Mode Voltage		+14.5, -11.5			+14.5, -11.5		V
	Over Max Operating Range ⁶		-11	+13	-11	+13		V
	Common-Mode							
	Rejection Ratio	V _{CM} = ±10 V	78	88	82	88		dB
		T _{MIN} to T _{MAX}	76	84	80	84		dB
		V _{CM} = ±11 V	72	84	78	84		dB
		T _{MIN} to T _{MAX}	70	80	74	80		dB
INPUT VOLTAGE NOISE	0.1 to 10 Hz		2			2		μV p-p
	f = 10 Hz		45			45		nV/√Hz
	f = 100 Hz		22			22		nV/√Hz
	f = 1 kHz		18			18		nV/√Hz
	f = 10 kHz		16			16		nV/√Hz
INPUT CURRENT NOISE	f = 1 kHz		0.01			0.01		pA/√Hz
OPEN LOOP GAIN ⁷	V _O = ±10 V							
	R _{LOAD} ≥ 2 kΩ T _{MIN} to T _{MAX}	200 100	400		250 100	400		V/mV V/mV
OUTPUT CHARACTERISTICS	Voltage	R _{LOAD} ≥ 2 kΩ	+13, -12.5	+13.9, -13.3	+13, -12.5	+13.9, -13.3		V
		T _{MIN} to T _{MAX}	±12	+13.8, -13.1	±12	+13.8, -13.1		V
	Current	Short Circuit		25		25		mA
	Capacitive Load ⁸	Gain = -1		1000		1000		pF
POWER SUPPLY	Rated Performance			±15		±15		V
	Operating Range		±4.5	±18	±4.5	±18		V
	Quiescent Current			3.5		3.5	4.0	mA

NOTES

¹Input offset voltage specifications are guaranteed after 5 minutes of operation at T_A = +25°C.

²PSRR test conditions: +V_S = 15 V, -V_S = -12 V to -18 V and +V_S = +12 V to +18 V, -V_S = -15 V.

³Bias Current Specifications are guaranteed maximum at either input after 5 minutes of operation at T_A = +25°C. For higher temperature, the current doubles every 10°C.

⁴Gain = -1, R_I = 2 k, C_L = 10 pF, refer to Figure 25.

⁵Defined as voltage between inputs, such that neither exceeds ±10 V from ground.

⁶Typically exceeding -14.1 V negative common-mode voltage on either input results in an output phase reversal.

⁷Open-Loop Gain is specified with V_{OS} both nulled and unnulled.

⁸Capacitive load drive specified for C_{COMP} = 20 pF with the device connected as shown in Figure 32. Under these conditions, slew rate = 14 V/μs and 0.01% settling time = 1.5 μs typical.

Refer to Table II for optimum compensation while driving a capacitive load.

Specifications subject to change without notice. All min and max specifications are guaranteed.

ABSOLUTE MAXIMUM RATINGS¹

Supply Voltage	± 18 V
Internal Power Dissipation ²	500 mW
Input Voltage ³	± 18 V
Output Short Circuit Duration	Indefinite
Differential Input Voltage	$+V_S$ and $-V_S$
Storage Temperature Range (Q, H)	-65°C to $+150^{\circ}\text{C}$
Storage Temperature Range (N, R)	-65°C to $+125^{\circ}\text{C}$
Operating Temperature Range	
AD744J/K	0°C to $+70^{\circ}\text{C}$
AD744A/B	-40°C to $+85^{\circ}\text{C}$
AD744S/T	-55°C to $+125^{\circ}\text{C}$
Lead Temperature Range (Soldering 60 seconds)	300°C

NOTES

¹Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

²Thermal Characteristics

8-Lead Plastic Package: $\theta_{JA} = 100^{\circ}\text{C/Watt}$, $\theta_{JC} = 33^{\circ}\text{C/Watt}$

8-Lead Cerdip Package: $\theta_{JA} = 110^{\circ}\text{C/Watt}$, $\theta_{JC} = 22^{\circ}\text{C/Watt}$

8-Lead Metal Can Package: $\theta_{JA} = 150^{\circ}\text{C/Watt}$, $\theta_{JC} = 65^{\circ}\text{C/Watt}$

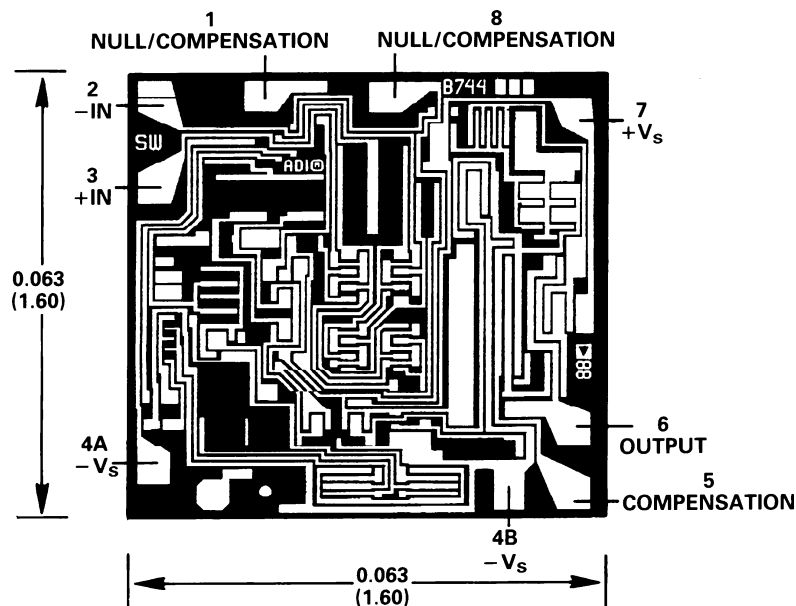
8-Lead SOIC Package: $\theta_{JA} = 160^{\circ}\text{C/Watt}$, $\theta_{JC} = 42^{\circ}\text{C/Watt}$

³For supply voltages less than ± 18 V, the absolute maximum input voltage is equal to the supply voltage.

METALIZATION PHOTOGRAPH

Contact factory for latest dimensions.

Dimensions shown in inches and (mm).



AD744—Typical Characteristics

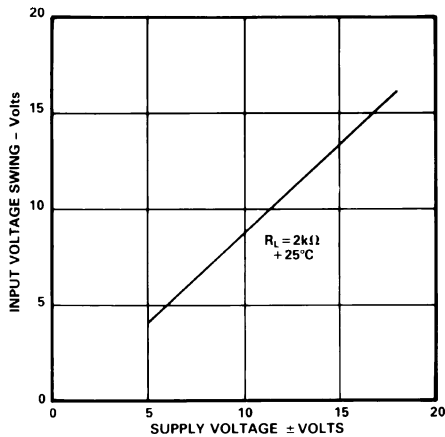


Figure 1. Input Voltage Swing vs. Supply Voltage

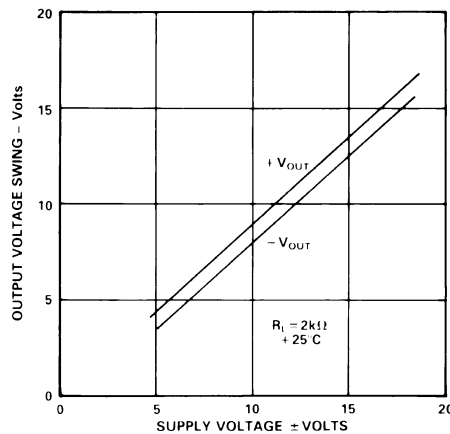


Figure 2. Output Voltage Swing vs. Supply Voltage

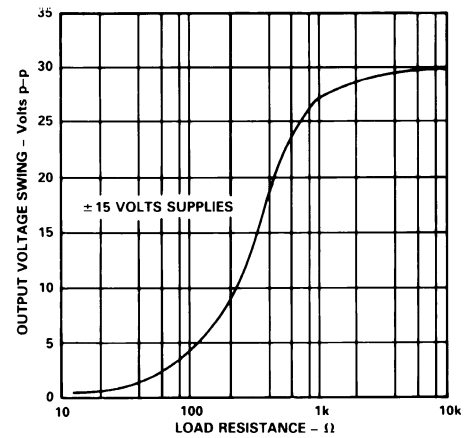


Figure 3. Output Voltage Swing vs. Load Resistance

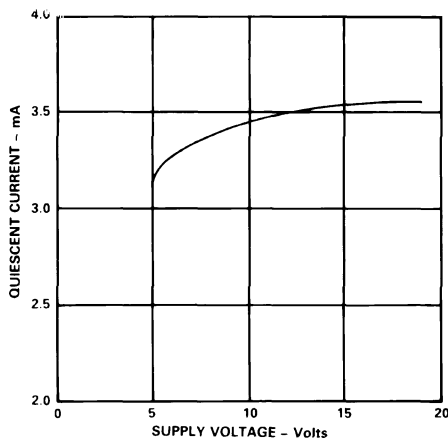


Figure 4. Quiescent Current vs. Supply Voltage

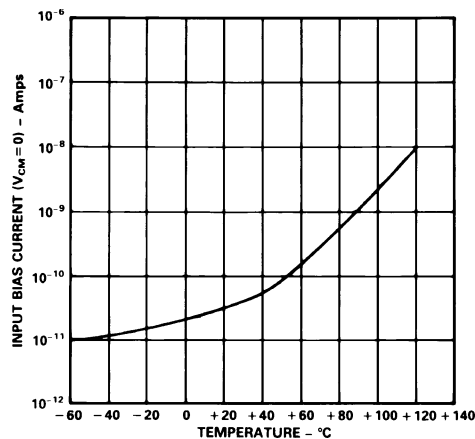


Figure 5. Input Bias Current vs. Temperature

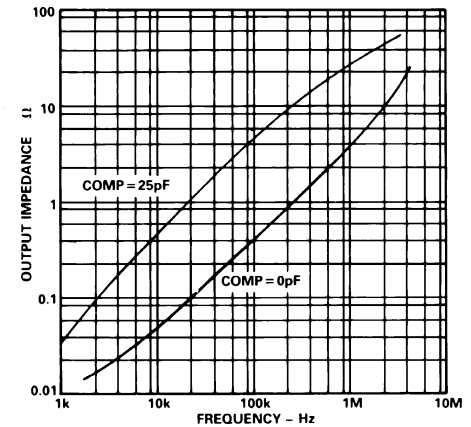


Figure 6. Output Impedance vs. Frequency

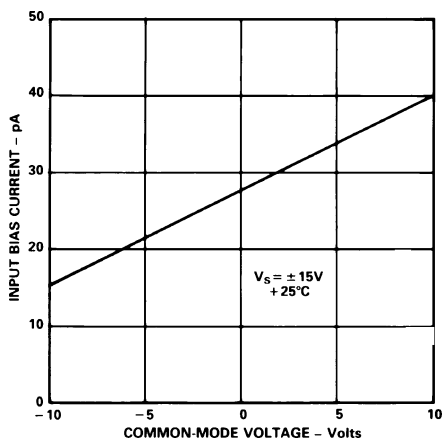


Figure 7. Input Bias Current vs. Common-Mode Voltage

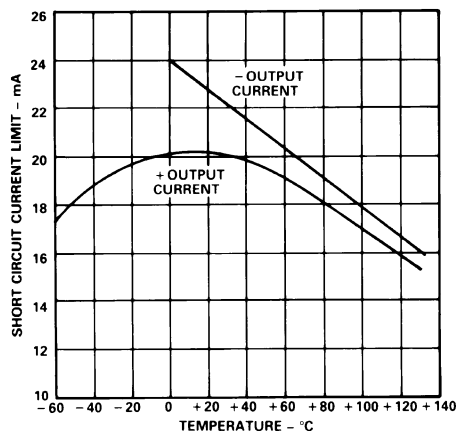


Figure 8. Short Circuit Current Limit vs. Temperature

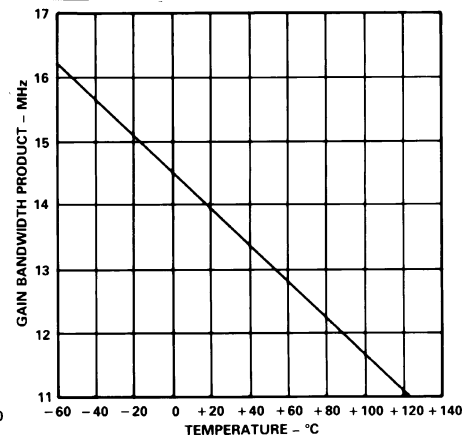


Figure 9. Gain Bandwidth Product vs. Temperature

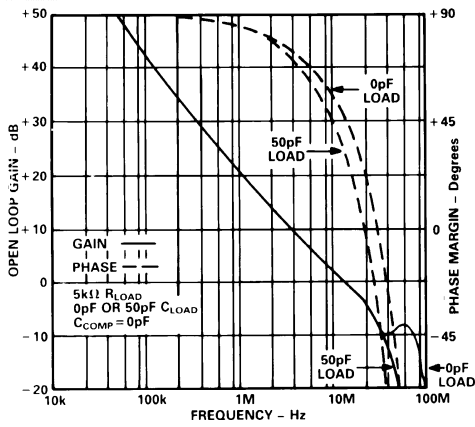


Figure 10. Open-Loop Gain and Phase Margin vs. Frequency
 $C_{COMP} = 0 \text{ pF}$

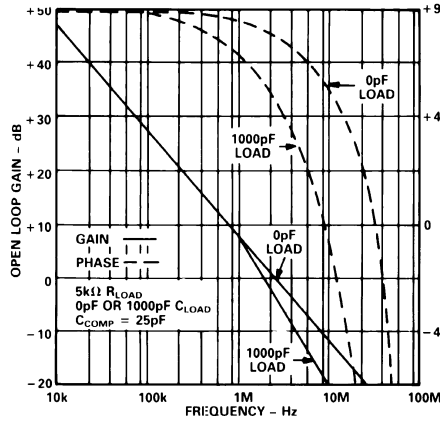


Figure 11. Open Loop Gain and Phase Margin vs. Frequency
 $C_{COMP} = 25 \text{ pF}$

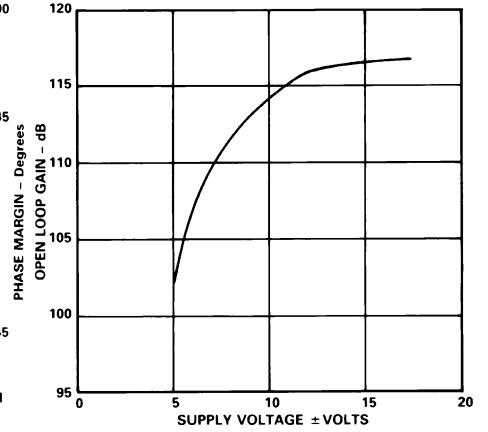


Figure 12. Open-Loop Gain vs. Supply Voltage

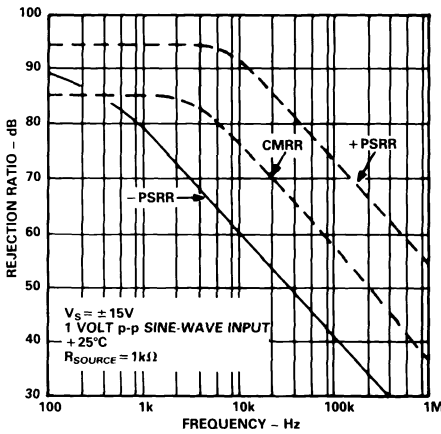


Figure 13. Common-Mode and Power Supply Rejection vs. Frequency

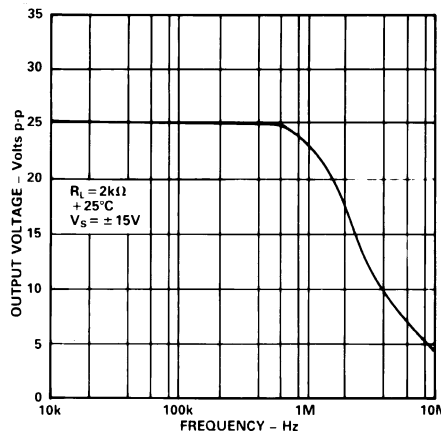


Figure 14. Large Signal Frequency Response

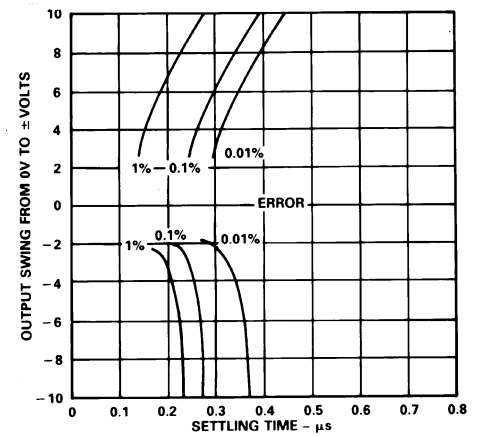


Figure 15. Output Swing and Error vs. Settling Time

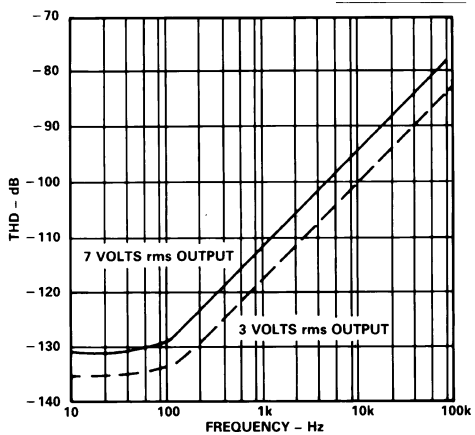


Figure 16. Total Harmonic Distortion vs. Frequency, Circuit of Figure 20
($G = 10$)

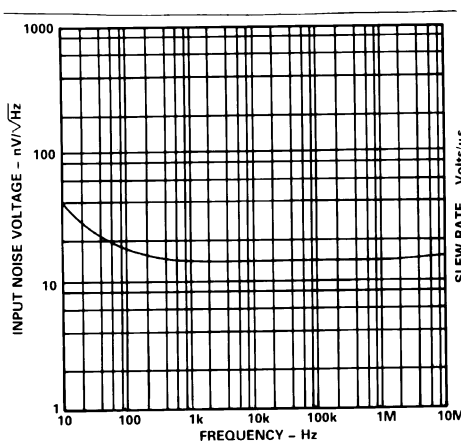


Figure 17. Input Noise Voltage Spectral Density

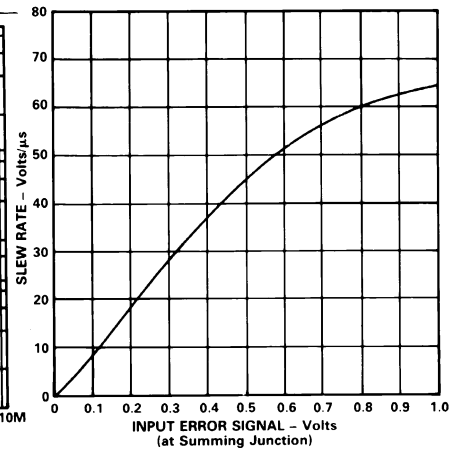


Figure 18. Slew Rate vs. Input Error Signal

AD744—Typical Characteristics

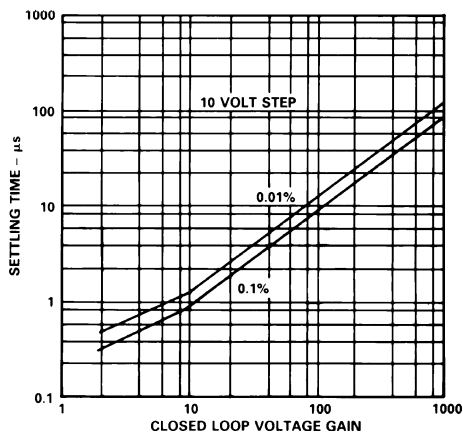


Figure 19. Settling Time vs. Closed Loop Voltage Gain

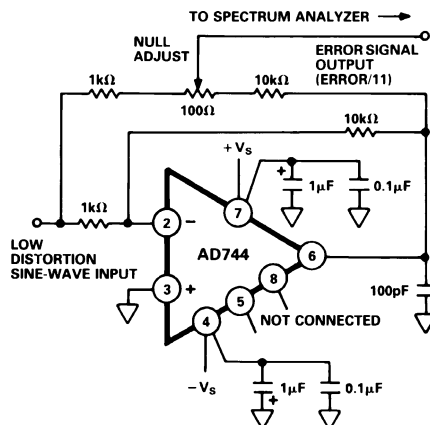


Figure 20. THD Test Circuit

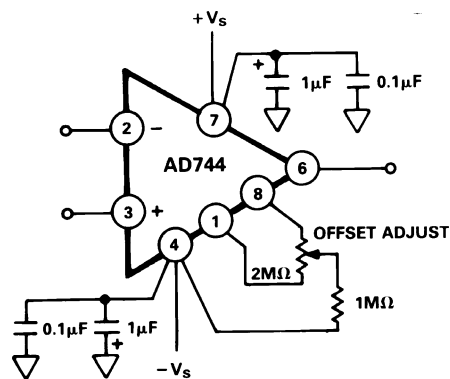


Figure 21. Offset Null Configuration

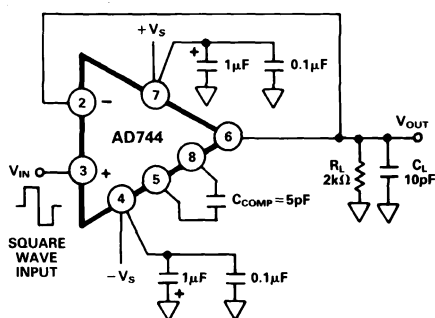


Figure 22a. Unity-Gain Follower

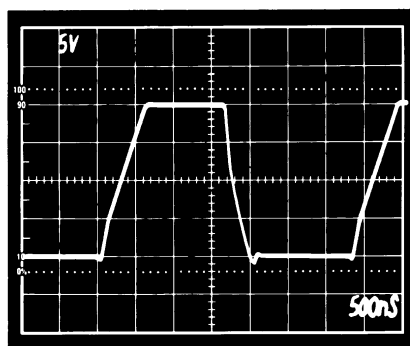


Figure 22b. Unity-Gain Follower Large Signal Pulse Response, $C_{COMP} = 5 \text{ pF}$

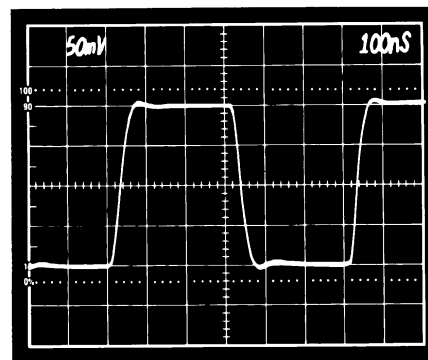


Figure 22c. Unity-Gain Follower Small Signal Pulse Response, $C_{COMP} = 5 \text{ pF}$

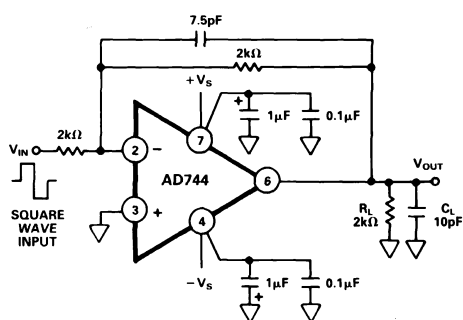


Figure 23a. Unity-Gain Inverter

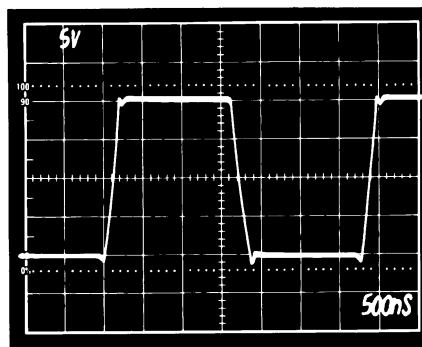


Figure 23b. Unity-Gain Inverter Large Signal Pulse Response, $C_{COMP} = 5 \text{ pF}$

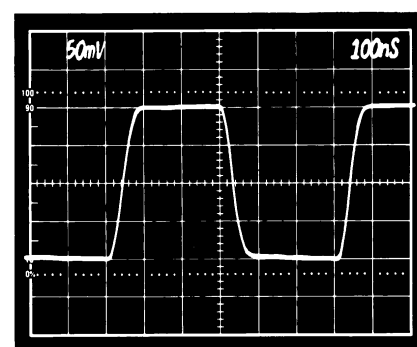


Figure 23c. Unity-Gain Inverter Small Signal Pulse Response, $C_{COMP} = 0 \text{ pF}$

The power supply connections to the AD744 must maintain a low impedance to ground over a bandwidth of 10 MHz or more. This is especially important when driving a significant resistive or capacitive load, since all current delivered to the load comes from the power supplies. Multiple high quality bypass capacitors are recommended for each power supply line in any critical application. A 0.1 μF ceramic and a 1 μF electrolytic capacitor as shown in Figure 24 placed as close as possible to the amplifier (with short lead lengths to power supply common) will assure adequate high frequency bypassing, in most applications. A minimum bypass capacitance of 0.1 μF should be used for any application.



The photos of Figures 26 and 27 show the dynamic response of the AD744 while operating in the settling time test circuit of Figure 25. The input of the settling time fixture is driven by a flat-top pulse generator. The error signal output from the false summing node of A1, the AD744 under test, is clamped, amplified by op amp A2 and then clamped again.

Downloaded from Arrow.com.

AD744

EXTERNAL FREQUENCY COMPENSATION

Even though the AD744 is useable without compensation in most applications, it may be externally compensated for even more flexibility. This is accomplished by connecting a capacitor between Pins 5 and 8. Figure 28, a simplified schematic of the AD744, shows where this capacitor is connected. This feature is useful because it allows the AD744 to be used as a unity gain voltage follower. It also enables the amplifier to drive capacitive loads up to 2000 pF and greater.

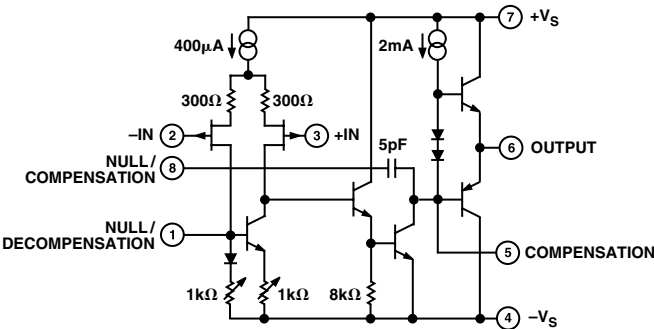


Figure 28. AD744 Simplified Schematic

The slew rate and gain bandwidth product of the AD744 are inversely proportional to the value of the compensation capacitor, C_{COMP} . Therefore, when trying to maximize the speed of the amplifier, the value of C_{COMP} should be minimized. C_{COMP} can also be used to slow the amplifier to a point where the slew rate is perfectly symmetrical and well controlled. Figure 29 summarizes the effect of external compensation on slew rate and bandwidth.

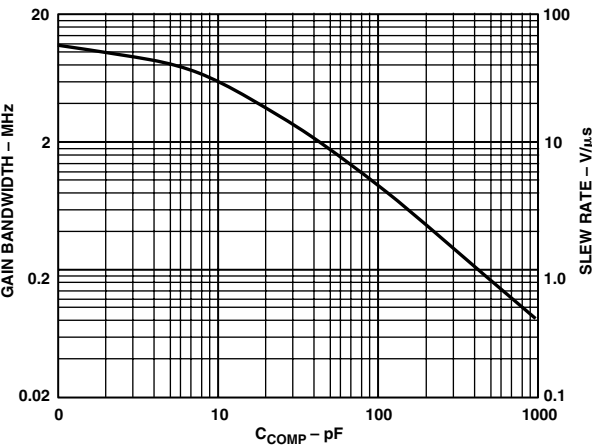


Figure 29. Gain Bandwidth and Slew Rate vs. C_{COMP}

The following section provides tables to show what C_{COMP} values will provide the necessary compensation for given circuit configurations and capacitive loads. In each case, the recommended C_{COMP} is a minimum value. A larger C_{COMP} can always be used, but slew rate and bandwidth performance will be degraded.

Figure 30 shows the AD744 configured as a unity gain voltage follower. In this case, a minimum compensation capacitor of 5 pF is necessary for stable operation. Larger compensation capacitors can be used for driving larger capacitive loads. Table I outlines recommended minimum values for C_{COMP} based on the desired capacitive load. It also gives the slew rate and bandwidth that will be achieved for each case.

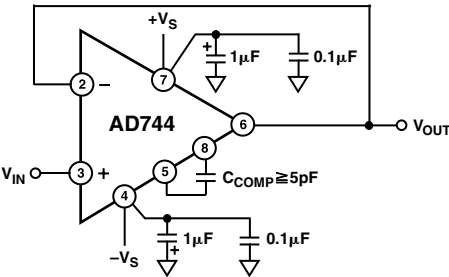


Figure 30. AD744 Connected as a Unity Gain Voltage Follower

Table I. Recommended Values of C_{COMP} vs. Various Capacitive Loads

Gain	Max C_{LOAD} (pF)	C_{COMP} (pF)	Slew Rate (V/µs)	-3 dB Bandwidth (MHz)
1	50	5	37	6.5
1	150	10	25	4.3
1	2000	25	12.5	2.0

Figures 31 and 32 show the AD744 as a voltage follower with gain and as an inverting amplifier. In these cases, external compensation is not necessary for stable operation. However, compensation may be applied to drive capacitive loads above 50 pF. Table II gives recommended C_{COMP} values, along with expected slew rates and bandwidths for a variety of load conditions and gains for the circuits in Figures 31 and 32.

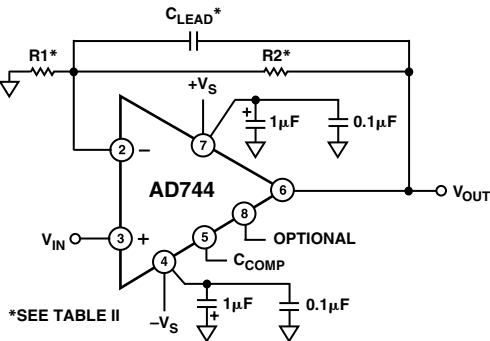


Figure 31. AD744 Connected as a Voltage Follower Operating at Gains of 2 or Greater

Table II. Recommended Values of C_{COMP} vs. Various Load Conditions for the Circuits of Figures 31 and 32.

R1 (Ω)	R2 (Ω)	Gain Follower	Gain Inverter	Max C_{LOAD} (pF)	C_{COMP} (pF)	C_{LEAD} (pF)	Slew Rate (V/ μ s)	-3 dB Bandwidth (MHz)
4.99 k	4.99 k	2	1	50	0	7	75	2.5 ¹
4.99 k	4.99 k	2	1	150	5	7	37	2.3 ¹
4.99 k	4.99 k	2	1	1000	20	—	14	1.2
4.99 k	4.99 k	2	1	>2000	25	—	12.5 ²	1.0
499 Ω	4.99 k	11	10	270	0	—	75	1.2
499 Ω	4.99 k	11	10	390	2	—	50	0.85
499 Ω	4.99 k	11	10	1000	5	—	37 ²	0.60

NOTES

¹Bandwidth with C_{LEAD} adjusted for minimum settling time.

²Into large capacitive loads the AD744's 25 mA output current limit sets the slew rate of the amplifier, in V/ μ s, equal to 0.025 amps divided by the value of C_{LOAD} in μ F. Slew rate is specified into rated max C_{LOAD} except for cases marked ², which are specified with a 50 pF load.

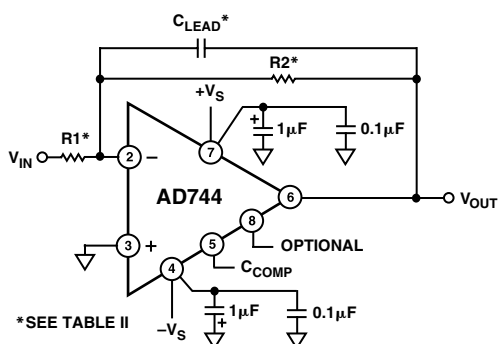


Figure 32. AD744 Connected as an Inverting Amplifier Operating at Gains of 1 or Greater

Using Decompensation to Extend the Gain Bandwidth Product

When the AD744 is used in applications where the closed-loop gain is greater than 10, gain bandwidth product may be enhanced by connecting a small capacitor between Pins 1 and 5 (Figure 33). At low frequencies, this capacitor cancels the effects of the chip's internal compensation capacitor, C_{COMP} , effectively decompensating the amplifier.

Due to manufacturing variations in the value of the internal C_{COMP} , it is recommended that the amplifier's response be optimized for the desired gain by using a 2 to 10 pF trimmer capacitor rather than using a fixed value.

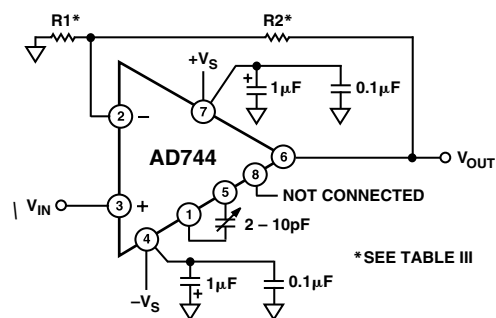


Figure 33. Using the Decompensation Connection to Extend Gain Bandwidth

Table III. Performance Summary for the Circuit of Figure 33

R1 (Ω)	R2 (Ω)	Gain Follower	Gain Inverter	-3 dB Bandwidth	Gain/BW Product
1 k	10 k	11	10	2.5 MHz	25 MHz
100	10 k	101	100	760 kHz	76 MHz
100	100 k	1001	1000	225 kHz	225 MHz

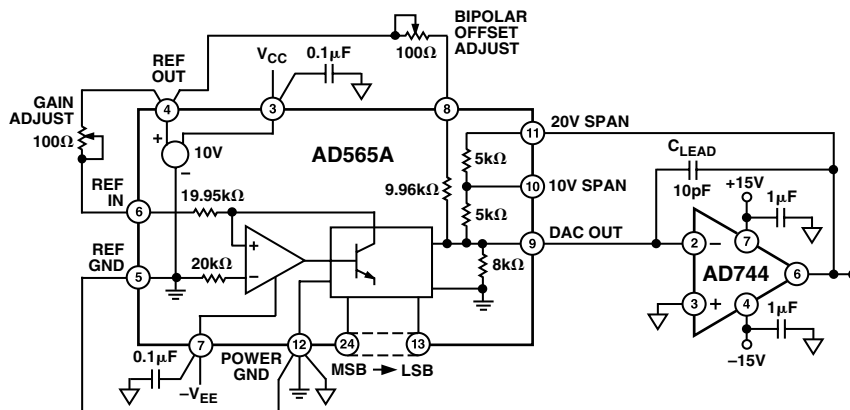


Figure 34. ± 10 V Voltage Output Bipolar DAC Using the AD744 as an Output Buffer

HIGH-SPEED OP AMP APPLICATIONS AND TECHNIQUES

DAC Buffers (I-to-V Converters)

Digital-to-analog converters which use bipolar transistors to switch currents into (or out of) their outputs can achieve very fast settling times. The AD565A, for example, is specified to settle to 12 bits in less than 250 ns, with a current output. However, in many applications, a voltage output is desirable, and it would be useful – perhaps essential – that this I-to-V conversion be accomplished without increasing the settling time or without degrading the accuracy of the DAC.

Figure 34 is a schematic of an AD565A DAC using an AD744 output buffer. The 10 pF C_{LEAD} capacitor compensates for the DAC's output capacitance, plus the 5.5 pF amplifier input capacitance.

Figure 35 is an oscilloscope photo of the AD744's output voltage with a +10 V to 0 V step applied; this corresponds to an all "1s" to all "0s" code change on the DAC. Since the DAC is

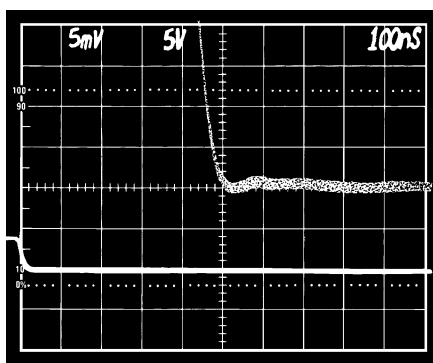


Figure 35. Upper Trace: AD744 Output Voltage for a +10 V to 0 V Step, Scale: 5 mV/div.

Lower Trace: Logic Input Signal, Scale: 5 V/div.

connected in the 20 V span mode, 1 LSB is equal to 4.88 mV. Output settling time for the AD565/AD744 combination is less than 500 ns to within a 2.44 mV, 1/2 LSB error band.

A HIGH-SPEED, 3 OP AMP INSTRUMENTATION AMPLIFIER CIRCUIT

The instrumentation amplifier circuit shown in Figure 36 can provide a range of gains from unity up to 1000 and higher. The circuit bandwidth is 4 MHz at a gain of 1 and 750 kHz at a gain of 10; settling time for the entire circuit is less than 2 μ s to within 0.01% for a 10 V step, ($G = 10$).

While the AD744 is not stable with 100% negative feedback (as when connected as a standard voltage follower), phase margin and therefore stability at unity gain may be increased to an acceptable level by placing the parallel combination of a resistor and a small lead capacitor between each amplifier's output and its inverting input terminal.

The only penalty associated with this method is a small bandwidth reduction at low gains. The optimum value for C_{LEAD} may be determined from the graph of Figure 41. This technique can be used in the circuit of Figure 36 to achieve stable operation at gains from unity to over 1000.

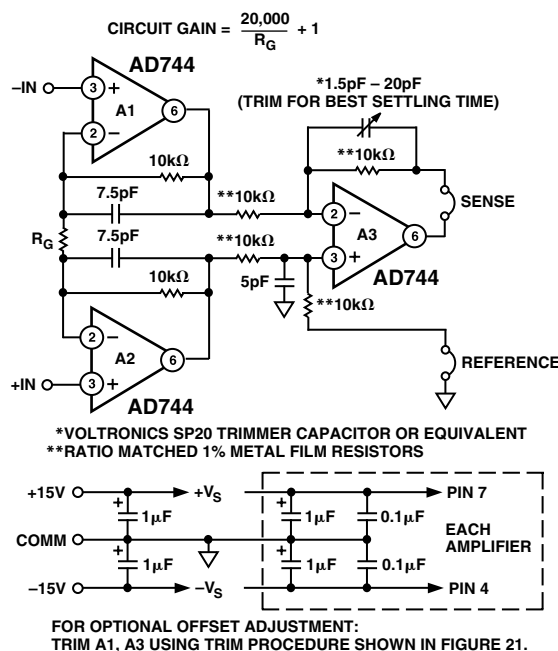


Figure 36. A High Performance, 3 Op Amp Instrumentation Amplifier Circuit

Table IV. Performance Summary for the 3 Op Amp Instrumentation Amplifier Circuit

Gain	RG	Bandwidth	T Settle (0.01%)
1	NC	3.5 MHz	1.5 μ s
2	20 k Ω	2.5 MHz	1.0 μ s
10	2.22 k Ω	1 MHz	2 μ s
100	202 Ω	290 kHz	5 μ s

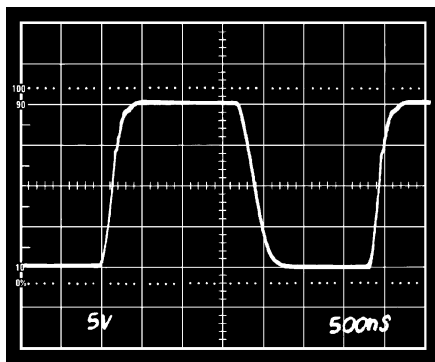


Figure 37. The Pulse Response of the 3 Op Amp Instrumentation Amplifier. Gain = 1, Horizontal Scale: 0.5 μ V/div., Vertical Scale: 5 V/div. (Gain= 10)

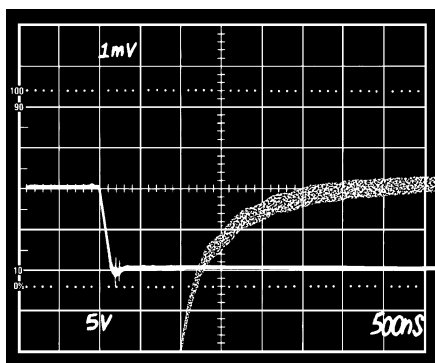


Figure 38. Settling Time of the 3 Op Amp Instrumentation Amplifier. Horizontal Scale: 500 ns/div., Vertical Scale, Pulse Input: 5 V/div., Output Settling: 1 mV/div.

Minimizing Settling Time in Real-World Applications

An amplifier with a “single pole” or “ideal” integrator open-loop frequency response will achieve the minimum possible settling time for any given unity-gain bandwidth. However, when this “ideal” amplifier is used in a practical circuit, the actual settling time is increased above the minimum value because of added time constants which are introduced due to additional capacitance on the amplifier’s summing junction. The following discussion will explain how to minimize this increase in settling time by the selection of the proper value for feedback capacitor, C_L .

If an op amp is modeled as an ideal integrator with a unity gain crossover frequency, f_O , Equation 1 will accurately describe the small signal behavior of the circuit of Figure 39. This circuit models an op amp connected as an I-to-V converter.

Equation 1 would completely describe the output of the system if not for the op amp’s finite slew rate and other nonlinear effects. Even considering these effects, the fine scale settling to <0.1% will be determined by the op amp’s small signal behavior. Equation 1.

$$\frac{V_O}{I_{IN}} = \frac{-R}{\frac{R(C_L + C_X)}{2\pi F_O} s^2 + \left(\frac{G_N}{2\pi F_O} + RC_L \right) s + 1}$$

Where F_O = the op amp’s unity gain crossover frequency

$$G_N = \text{the “noise” gain of the circuit} \left(1 + \frac{R}{R_O} \right)$$

This Equation May Then Be Solved for C_L :

Equation 2.

$$C_L = \frac{2 - G_N}{R 2\pi F_O} + \frac{2\sqrt{RC_X 2\pi F_O + (1 - G_N)}}{R 2\pi F_O}$$

In these equations, capacitance C_X is the total capacitance appearing at the inverting terminal of the op amp. When modeling an I-to-V converter application, the Norton equivalent circuit of Figure 39 can be used directly. Capacitance C_X is the total capacitance of the output of the current source plus the input capacitance of the op amp, which includes any stray capacitance at the op amp’s input.

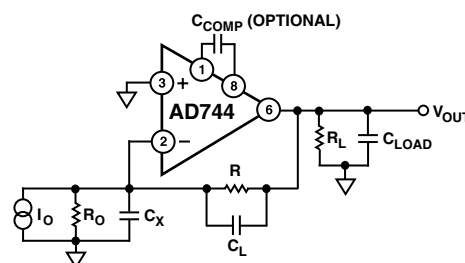


Figure 39. A Simplified Model of the AD744 Used as a Current-to-Voltage Converter

When R_O and I_O are replaced with their Thevenin V_{IN} and R_{IN} equivalents, the general purpose inverting amplifier model of Figure 40 is created. Here capacitor C_X represents the input capacitance of the AD744 (5.5 pF) plus any stray capacitance due to wiring and the type of IC package employed.

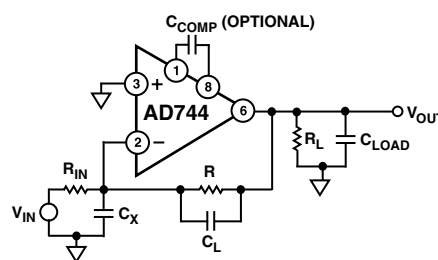


Figure 40. A Simplified Model of the AD744 Used as an Inverting Amplifier

AD744

In either case, the capacitance C_X causes the system to go from a one-pole to a two-pole response; this additional pole increases settling time by introducing peaking or ringing in the op amp's output. If the value of C_X can be estimated with reasonable accuracy, Equation 2 can be used to choose the correct value for a small capacitor, C_L , which will optimize amplifier response. If the value of C_X is not known, C_L should be a variable capacitor.

As an aid to the designer, the optimum value of C_L for one specific amplifier connection can be determined from the graph of Figure 41. This graph has been produced for the case where the AD744 is connected as in Figures 39 and 40 with a practical minimum value for C_{STRAY} of 2 pF and a total C_X value of 7.5 pF.

The approximate value of C_L can be determined for almost any application by solving Equation 2. For example, the AD565/AD744 circuit of Figure 34 constrains all the variables of Equation 2 ($G_N = 3.25$, $R = 10 \text{ k}\Omega$, $F_O = 13 \text{ MHz}$, and $C_X = 32.5 \text{ pF}$). Therefore, under these conditions, $C_L = 10.5 \text{ pF}$.

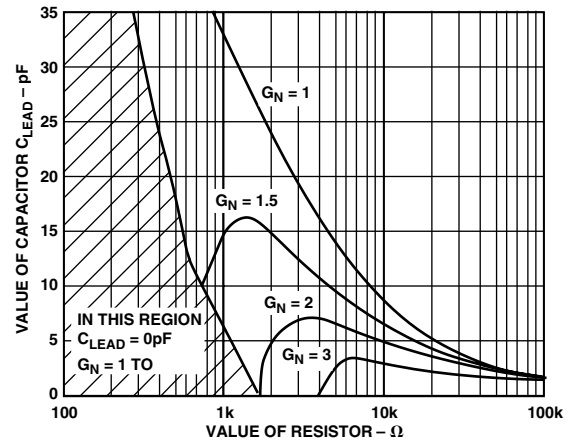
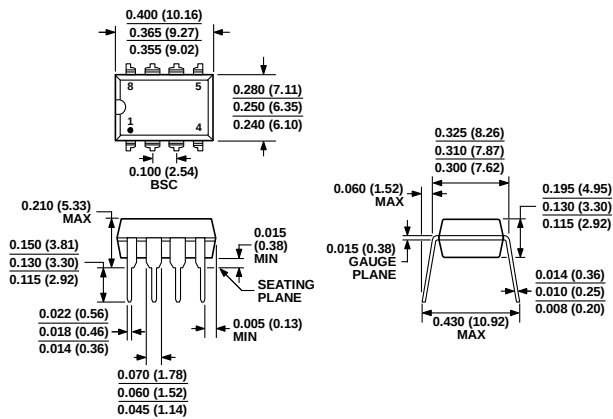


Figure 41. Practical Values of C_L vs. Resistance of R for Various Amplifier Noise Gains

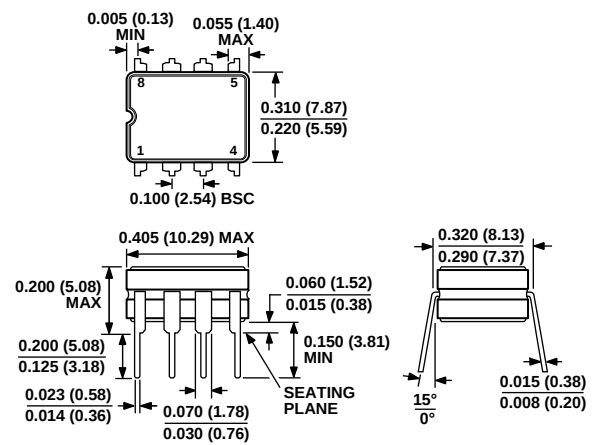
OUTLINE DIMENSION



COMPLIANT TO JEDEC STANDARDS MS-001

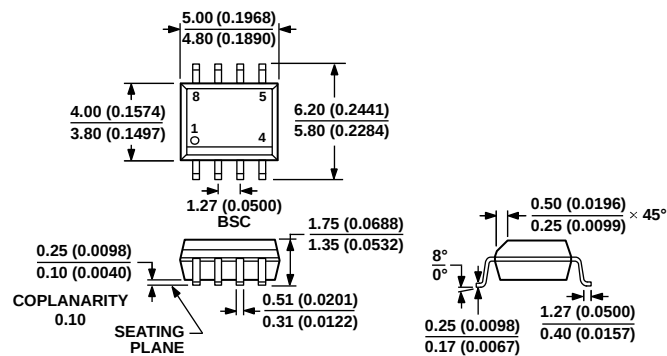
CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN. CORNER LEADS MAY BE CONFIGURED AS WHOLE OR HALF LEADS.

Figure 42. 8-Lead Plastic Dual In-Line Package [PDIP]
Narrow Body
(N-8)
Dimensions shown in inches and (millimeters)



CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

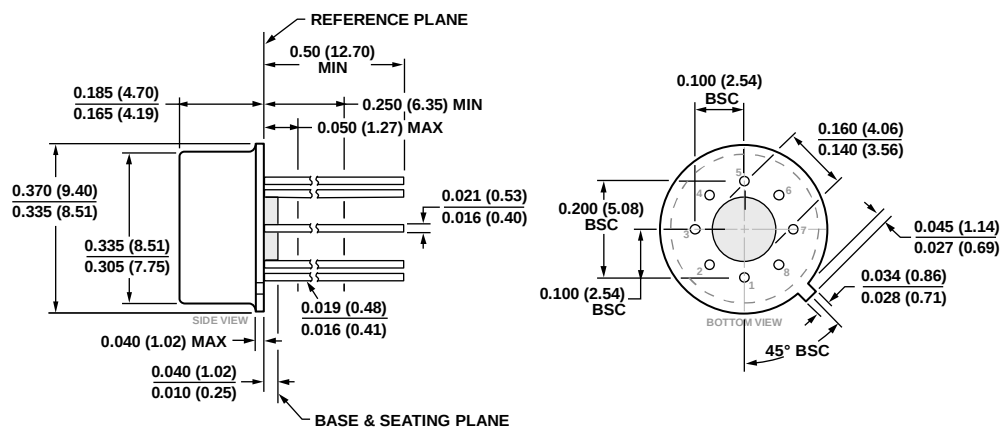
Figure 43. 8-Lead Ceramic Dual In-Line Package [CERDIP]
(Q-8)
Dimensions shown in inches and (millimeters)



COMPLIANT TO JEDEC STANDARDS MS-012-AA

CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 44. 8-Lead Standard Small Outline Package [SOIC_N]
Narrow Body
(R-8)
Dimensions shown in inches and (millimeters)



COMPLIANT TO JEDEC STANDARDS MO-002-AK
CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS
(IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR
REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 45. 8-Pin Metal Header [TO_99]
(H-08)

Dimensions shown in inches and (millimeters)

01-15-2015-B

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option
AD744JR	0°C to +70°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
AD744JRZ	0°C to +70°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
AD744JR-REEL	0°C to +70°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
AD744KRZ	0°C to +70°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
AD744KRZ-REEL	0°C to +70°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
AD744KRZ-REEL7	0°C to +70°C	8-Lead Standard Small Outline Package [SOIC_N]	R-8
AD744AQ	-40°C to +85°C	8-Lead Ceramic Dual In-Line Package [CERDIP]	Q-8
AD744BQ	-40°C to +85°C	8-Lead Ceramic Dual In-Line Package [CERDIP]	Q-8
AD744JNZ	-40°C to +85°C	8-Lead Plastic Dual In-Line Package [PDIP]	N-8
AD744KNZ	-40°C to +85°C	8-Lead Plastic Dual In-Line Package [PDIP]	N-8
AD744JCHIPS	0°C to +70°C		Die
AD744TH/883B	-55°C to +125°C	8-Pin Metal Header [TO-99]	H-08

¹ Z = RoHS Compliant Part.

REVISION HISTORY**10/2017—Rev. C to Rev. D**

Updated Outline Dimensions	14
Changes to Ordering Guide	14

7/2000—Rev. B to Rev. C